

Multivariate Optimization of Production Systems--
The Time Dimension

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Abstract

Traditional analysis of oil and gas production systems treats individual nodes one at a time. This only calculates a feasible solution which is not necessarily optimal. Multivariate optimization is able to determine the most profitable configuration, including all variables simultaneously. The optimization can also find the optimal recovery over a period of time, rather than just at a single instant as in traditional methods. This report describes the development of multivariate optimization for situations in which the decision variables may change as a function of time. For example, instead of estimating a tubing size which is optimal over the life of the project, this approach determines a series of optimal tubing sizes which may change from year to year. Examples show that under an optimal strategy, tubing size can be changed only infrequently while still increasing profitability of a project. The methods used in this work considered the special requirements of objectives which are not smooth functions of their decision variables. The physical problems considered included artificial lift production systems.

1. Introduction

1.1 Production Optimization

When a new well is drilled, the production engineer is given the task of designing the "best" completion for the well. Usually the engineer will use nodal analysis to find the "best" size of tubing, the "best" operating pressure for the production separator, etc. (decision variables) Any type of optimization is limited to varying the decision variables on a trial and error basis to find a suitable combination of the variables.

Nodal analysis is not an optimization technique. It is a method to find the stabilized flow rate for a given set of conditions (decision variables). Further, nodal analysis does not have a time dimension. The solution is for an instant in time.

There are numerical algorithms that are designed to find the minimum or maximum of nonlinear functions. These algorithms can be used to optimize production from a single completion. To accomplish the optimization an objective function has to be chosen along with the decision variables -- they are the variables that the engineer chooses to optimize. These optimization algorithms simultaneously vary all the decision variables, and proceed to find the extreme point without the use of a trial and error procedure.

Carroll [1990] was one of the first to apply nonlinear optimization algorithms to production systems. Others have used linear programming, integer programming, dynamic programming and other techniques to optimization problems in petroleum engineering. However, Carroll [1990] focused on optimization of well production. The reader is referred to the work of Carroll [1990] for a history of optimization studies in petroleum engineering.

In this study a model of the reservoir is coupled to a model of the tubing, and a model of a two stage separator. These models are then coupled with the nonlinear optimization algorithms and the objective function. The goal of the optimization study was to find the optimum values of the decision variables that gave the maximum value of the objective function -- in this case the present value of the hydrocarbon production. The production model included a time dimension; the oil and gas rates are given as a function of time.

The well performance was modeled using a tank model for the reservoir, and several multiphase correlations for the flow through the tubing string. The sequence of production separators was modeled using a two phase flash process and an equation of state. The well performance model was used to generate a production profile for oil and gas from the reservoir. This production profile was used to generate the present value for

the production. The present value of the oil and gas produced was used as the objective function for the nonlinear optimization algorithms.

Chapter 2 of this report describes the reservoir model used, Chapter 3 the vertical multiphase flow correlations used and Chapter 4 the separator model developed. Chapter 5 describes the nonlinear optimization algorithms used and Chapter 6 the results of the study.

Carroll [1990] studied the optimization of decision variables that were fixed with time. This particular study concentrates on the optimization of decision variables that change with time, i.e., variables that are optimized for a single or group of time steps.

2 Reservoir Model

2.1 Introduction

The behavior of the petroleum reservoir and the inflow performance relationship was simulated by using a model developed by Borthne [1986] at the Norwegian Institute of Technology. This chapter is a summary of the detailed analysis that appears in Borthne's thesis. Readers are referred to his thesis and that of Carroll [1990] for further details.

Developed for use in production optimization of a recently discovered reservoir, the model requires only very basic field parameters, and is able to compute a production forecast very rapidly.

Based on a material balance equation, which is coupled with a pseudopressure based inflow relationship, the model assumes that the reservoir is a "tank." The production from the reservoir is constrained by a minimum flowing wellhead pressure, and both, maximum and minimum flow rates of the preferred phase (oil).

A series of simplifying assumptions are made in deriving the model. They are:

- The reservoir is homogenous, isotropic, horizontal, cylindrical, and of uniform thickness.
- The reservoir is a single cell with no-flow boundaries.
- The reservoir is saturated with a single hydrocarbon phase, and an immobile connate water phase.
- The drive mechanism for the oil reservoir is solution-drive.
- During a time step, production occurs under pseudosteady state conditions, at a constant rate.
- Capillary pressure, gravity effects, and coning forces are negligible, and are therefore ignored.
- All wells are assumed to be equivalent, and are assumed to produce at the same average reservoir conditions, and the same inflow performance relationships.

2.2 Reservoir Material Balance

The mass conservation equation for flow in a porous medium can be written as:

$$\frac{\partial m_p}{\partial t} + \tilde{q}_p = -\nabla \left(\frac{k\rho\nabla p}{\mu} \right) V_b \quad (2.1)$$

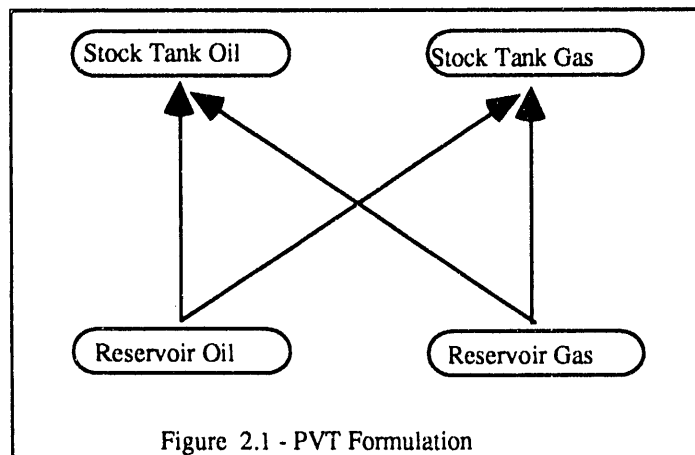
Where

- p = pressure
- k = permeability
- ρ = density
- μ = viscosity
- V_b = reservoir bulk volume
- \tilde{q}_b = mass production rate from reservoir
- m_b = mass of oil and gas in reservoir
- t = time

If the reservoir is considered to be a single cell, then there is no mass flux across the boundaries and the right hand side of Equation 2.1 is zero. Discretizing the equation gives the following:

$$\Delta m_p + \tilde{q}_p \Delta t = 0 \quad (2.2)$$

In order to use a realistic pressure behavior in the production system, the black oil model assumptions were assumed. The black oil model for phase behavior assumes that the reservoir oil will produce both oil and gas at the surface. Similarly, the reservoir gas is assumed to produce gas, as well as oil at the surface. The black oil PVT formulation is shown schematically below.



The following definitions are used in the derivation of the material balance equations.

$$B_o = \frac{V_o^R}{V_{oo}^S} \quad (2.3)$$

$$B_g = \frac{V_g^R}{V_{gg}^S} \quad (2.4)$$

$$R_s = \frac{V_{go}^S}{V_{oo}^S} \quad (2.5)$$

$$r_s = \frac{V_{og}^S}{V_{gg}^S} \quad (2.6)$$

where

- B_o = formation volume factor for oil
- B_g = formation volume factor for gas
- R_s = solution gas / oil ratio in reservoir oil
- r_s = solution oil / gas ratio in reservoir gas
- V_o^R = volume of reservoir oil
- V_g^R = volume of reservoir gas
- V_{oo}^S = stock tank oil volume from flash separation of reservoir oil
- V_{og}^S = stock tank oil volume from flash separation of reservoir gas
- V_{gg}^S = stock tank gas volume from flash separation of reservoir gas
- V_{go}^S = stock tank gas volume from flash separation of reservoir oil

If all the oil and gas in the reservoir is separated at stock tank conditions (STC), the mass of oil will be m_o , and the mass of gas m_g . As all this oil and gas originates from the reservoir, the total oil and gas mass may be expressed as follows:

$$m_o = m_{oo} + m_{og} \quad (2.7)$$

and

$$m_g = m_{gg} + m_{go} \quad (2.8)$$

where

- m_g = total mass of gas at stock tank conditions
- m_o = total mass of oil at stock tank conditions
- m_{oo} = mass of oil at STC from separation of reservoir oil
- m_{og} = mass of oil at STC from separation of reservoir gas
- m_{gg} = mass of gas at STC from separation of reservoir gas
- m_{go} = mass of gas at STC from separation of reservoir oil

These masses can be expressed in terms of reservoir variables and fluid properties.

$$m_{oo} = \frac{\phi S_o \rho_{oo}^s}{B_o} V_b \quad (2.9)$$

$$m_{og} = \frac{\phi S_g r_s \rho_{og}^s}{B_g} V_b \quad (2.10)$$

$$m_{gg} = \frac{\phi S_g \rho_{gg}^s}{B_g} V_b \quad (2.11)$$

$$m_{go} = \frac{\phi S_o R_s \rho_{go}^s}{B_o} V_b \quad (2.12)$$

where S_x = saturation of the appropriate phase
 ρ_{xx}^s = density of the appropriate phase at STC
 ϕ = porosity

The oil production mass flux (mass per unit time) can be defined as follows.

$$\tilde{q}_o = \tilde{q}_{oo} + \tilde{q}_{og} \quad (2.13)$$

where \tilde{q}_o = total mass flux of oil at the surface
 \tilde{q}_{oo} = mass flux of oil originating from reservoir oil
 \tilde{q}_{og} = mass flux of oil originating from solution in reservoir gas

In terms of volumetric flow rates and solubility,

$$\tilde{q}_{oo} = q_{oo} \rho_{oo}^s \quad (2.14)$$

$$\tilde{q}_{og} = q_{gg} r_s \rho_{og}^s \quad (2.15)$$

where q_{oo} = oil production rate from the reservoir oil, at standard conditions
 q_{gg} = gas production rate from the reservoir gas, at standard conditions.

Equivalent equations can be written for the gas production rates. The total mass flux equation for gas production is:

$$\tilde{q}_g = \tilde{q}_{gg} + \tilde{q}_{go} \quad (2.16)$$

where \bar{q}_o = total mass flux of gas at the surface
 \bar{q}_{gg} = mass flux of gas originating from reservoir gas
 \bar{q}_{go} = mass flux of gas originating from solution in reservoir oil.

Substituting the appropriate equations and the PVT formulations into Equation 2.2, four mass balance equations can be derived.

$$\Delta \left(\frac{\phi S_o \rho_{oo}^s}{B_o} \right) + q_{oo}'' \rho_{oo}^s \Delta t = 0 \quad (2.17)$$

$$\Delta \left(\frac{\phi S_g r_s \rho_{og}^s}{B_g} \right) + q_{gg}'' r_s \rho_{og}^s \Delta t = 0 \quad (2.18)$$

$$\Delta \left(\frac{\phi S_g \rho_{gg}^s}{B_g} \right) + q_{gg}'' \rho_{gg}^s \Delta t = 0 \quad (2.19)$$

$$\Delta \left(\frac{\phi S_g R_s \rho_{go}^s}{B_o} \right) + q_{oo}'' R_s \rho_{go}^s \Delta t = 0 \quad (2.20)$$

where the double quote (") indicates that the variable has been divided by the reservoir bulk volume. For example, $q'' = q / V_b$.

Summing the two oil equations (2.17 and 2.18) and rearranging we obtain the following expression for oil production at the surface.

$$\Delta \left[\phi \left(\frac{S_o}{B_o} + \frac{S_g r_s \rho_{og}^s}{B_g \rho_{oo}^s} \right) \right] + q_{oo}'' \Delta t + q_{gg}'' \Delta t r_s \frac{\rho_{og}^s}{\rho_{oo}^s} = 0 \quad (2.21)$$

Similarly, rearranging Equations 2.19 and 2.20, we obtain the following expression for gas production at the surface.

$$\Delta \left[\phi \left(\frac{S_g}{B_g} + \frac{S_o R_s \rho_{go}^s}{B_o \rho_{gg}^s} \right) \right] + q_{gg}'' \Delta t + q_{oo}'' \Delta t R_s \frac{\rho_{go}^s}{\rho_{gg}^s} = 0 \quad (2.22)$$

In Equations 2.21 and 2.22 the oil and gas rates appear. Using Darcy's law the oil and gas rates can be written as:

$$q_{gg}'' B_g = C_1 \frac{k_{rg}}{\mu_g} \quad (2.23)$$

$$q_{\infty}'' B_o = C_2 \frac{k_{ro}}{\mu_o} \quad (2.24)$$

where C_1 and C_2 are constants. The two constants are equal, if the capillary pressure is zero. Taking the gas - oil ratio (dividing Equation 2.23 by 2.24) and multiplying the result by Δt gives the following equation.

$$\frac{\Delta G_p''}{\Delta N_p''} = \frac{k_{rg} \mu_o B_o}{k_{ro} \mu_g B_g} \quad (2.25)$$

where $\Delta G_p'' = q_{gg}'' \Delta t$ which is the incremental gas produced during the last time step from reservoir gas, per unit volume of the reservoir.

and $\Delta N_p'' = q_{oo}'' \Delta t$ which is the incremental oil produced during the last time step from reservoir oil, per unit volume of the reservoir.

Substituting Equation 2.25 into Equations 2.21 and 2.22 gives the following,

$$\Delta \left[\phi \left(\frac{S_o}{B_o} + \frac{S_g r_s}{B_g} \frac{\rho_{og}^s}{\rho_{oo}^s} \right) \right] + \Delta N_p'' \left[1 + r_s \left(\frac{\rho_{og}^s}{\rho_{oo}^s} \right) \frac{k_{rg} \mu_o B_o}{k_{ro} \mu_g B_g} \right] = 0 \quad (2.26)$$

$$\Delta \left[\phi \left(\frac{S_g}{B_g} + \frac{S_o R_s}{B_o} \frac{\rho_{go}^s}{\rho_{gg}^s} \right) \right] + \Delta N_p'' \left[\frac{k_{rg} \mu_o B_o}{k_{ro} \mu_g B_g} + R_s \frac{\rho_{go}^s}{\rho_{gg}^s} \right] = 0 \quad (2.27)$$

For a given time step Δt , Equations 2.26 and 2.27 can be solved using trial and error procedure to find the incremental oil produced during the time step.

2.3 Solution Procedure

1. Specify the oil rate q_o and time step length Δt .
2. Calculate incremental total oil production $\Delta N_p''$.
3. Assume average reservoir pressure, and calculate the pressure dependent properties - formation volume factors, solution gas ratios, viscosities and densities.
4. Calculate oil saturation from Equation 2.26. The term beginning with ϕ in Equation 2.26 is calculated using the properties calculated at the previous time step.

5. Calculate the gas saturation.
6. Calculate the relative permeability ratio as a function of gas saturation from the input table.
7. Calculate incremental oil and gas production.
8. Calculate the material balance error.
9. If the material balance is not satisfied then go to step 3 and try a new estimate for the average pressure.

2.4 Inflow Performance Relationship

An inflow performance relationship is used to calculate the flowing bottomhole pressure (FBHP) for the well. The calculations are based on equations which relate the average reservoir pressure, and fluid properties with the FBHP.

Darcy's law can be written as

$$q_{oo} = \frac{2\pi r h k k_{ro}}{\mu_o B_o} \frac{\partial p}{\partial r} \quad (2.28)$$

separating and integrating Equation 2.28 gives:

$$q_{oo} = \frac{2\pi k h}{\ln(r_e/r_w)} \int_{p_w}^{p_i} \frac{k_{ro}}{\mu_o B_o} dp \quad (2.29)$$

where

- k = absolute permeability
- k_{ro} = relative permeability to oil
- r_e = radius of the reservoir
- r_w = radius of the well
- h = height of the reservoir
- p_e = pressure at the external boundary of the reservoir
- p_{wf} = flowing bottomhole pressure
- q_{oo} = oil production rate from reservoir oil

Including the skin factor and assuming pseudosteady state flow conditions, Equation 2.28 can be written in terms of pseudopressure ($m(p)$) as:

$$q_{oo} = \frac{2\pi k h}{\ln(r_e/r_w) - 0.75 + S + Dq_{oo}} [m(p_r) - m(p_{wf})] \quad (2.30)$$

where S = skin

D = rate dependent skin

$$\text{and} \quad m(p) = \int_0^p \frac{k_{ro}}{\mu_o B_o} dp \quad (2.31)$$

By redefining the pseudopressure, Equation 2.30 can be expressed in terms of the oil production measured at the surface q_o :

$$q_o = \frac{2\pi kh}{\ln(r_e/r_w) - 0.75 + S + Dq_o} [m(p_r) - m(p_{wf})] \quad (2.32)$$

$$\text{where} \quad m(p) = \int_0^p \left(\frac{k_{ro}}{\mu_o B_o} + \frac{k_{rg} r_s}{\mu_g B_g} \right) dp \quad (2.33)$$

A similar equation can be written for gas production.

$$q_g = \frac{2\pi kh}{\ln(r_e/r_w) - 0.75 + S + Dq_g} [m(p_r) - m(p_{wf})] \quad (2.34)$$

$$\text{where} \quad m(p) = \int_0^p \left(\frac{k_{rg}}{\mu_g B_g} + \frac{k_{ro} R_s}{\mu_o B_o} \right) dp \quad (2.35)$$

The derivation above relates the flow equations to the pseudopressure functions. The pseudopressure is a function of both pressure and saturations. Assuming a constant producing gas - oil ratio, we can derive a relationship between saturation and pressure. During the discussion of the reservoir material balance equations, the producing gas - oil ratio R_p was approximated by:

$$R_p = \frac{\Delta G_p}{\Delta N_p} \quad (2.36)$$

Using the material balance equations to substitute for ΔN_p and ΔG_p , Equation 2.36 can be written as

$$R_p = \frac{\Delta N_{oo}'' \left(M + R_s \frac{\rho_{go}^s}{\rho_{gg}^s} \right)}{\Delta N_{oo}'' \left(1 + r_s \frac{\rho_{og}^s}{\rho_{oo}^s} M \right)} \quad (2.37)$$

where M is the mobility ratio. Solving for M gives

$$M = \frac{R_p - R_s \frac{\rho_{go}^s}{\rho_{og}^s}}{1 - R_p r_s \frac{\rho_{og}^s}{\rho_{oo}^s}} \quad (2.38)$$

The mobility ratio is calculated from the material balance equations. For the mobility ratio, we can calculate the relative permeability ratio. As the permeability ratio is a function of saturation, we can calculate the phase saturation as a function of pressure for each time step. With the phase saturation, we can calculate the relative permeability of each phase, and use it in the calculation of the pseudopressure function.

The deliverability Equation (2.31), in terms of pseudopressure can be written as

$$\int_{p_{wf}}^{p_r} \left(\frac{k_{ro}}{\mu_o B_o} + \frac{k_{rg} r_s}{\mu_g B_g} \right) dp = q_o \frac{\ln(r_e/r_w) - 0.75 - S + Dq_o}{2\pi kh} \quad (2.39)$$

In this equation, the right hand side is a constant during a time step. The above equation is solved to find the FBHP (p_{wf}), which gives the value for the integral, equal to the value of the constant on the right hand side of the equation.

3 Tubing Model

3.1 Introduction

The flow of fluids from the reservoir to the wellhead through the completion string is modeled using the vertical multiphase flow correlations. For a more complete analysis of multiphase vertical flow the readers are referred to Brown [1977], Govier and Aziz [1972] and to Beggs [1992].

The law of conservation of energy is used as the theoretical basis for most flow correlations. For a steady state system, the energy balance equation may be written as

$$U_1 + p_1V_1 + \frac{mv_1^2}{2g_c} + \frac{mgZ_1}{g_c} + q' + W_s = U_2 + p_2V_2 + \frac{mv_2^2}{2g_c} + \frac{mgZ_2}{g_c} \quad (3.1)$$

where

- U = internal energy
- pV = energy of expansion or compression
- q' = heat energy added to the system
- W_s = work done by the fluid
- mv² = kinetic energy
- mgZ = potential energy

Equation 3.1 can be modified to a pressure gradient form by using thermodynamic relations. For a fluid flowing in a pipe, the law of conservation of energy can be written as

$$\frac{dp}{dL} = \frac{g}{g_c} \rho \sin \theta + \frac{\rho v dv}{g_c dL} + \left(\frac{dp}{dL} \right)_f \quad (3.2)$$

where

- ρ = density of the fluid
- θ = the angle of inclination from the horizontal
- g = gravitational acceleration
- g_c = gravitational constant
- v = fluid velocity
- L = length of the pipe
- $\left(\frac{dp}{dL} \right)_f$ is the pressure loss due to friction

As Equation 3.2 indicates, the total pressure drop can be thought of as composed of three distinct components - hydrostatic component, kinetic energy component, and a component due to friction. Symbolically this can be expressed as

$$\left(\frac{dp}{dL}\right)_{total} = \left(\frac{dp}{dL}\right)_{hydrostatic} + \left(\frac{dp}{dL}\right)_{kinetic} + \left(\frac{dp}{dL}\right)_{friction} \quad (3.3)$$

3.2 Two Phase Flow

When considering multiphase flow, the introduction of another phase into the flow stream complicates the analysis of the pressure gradient equation. The pressure gradient is changed by the presence of different phases, which in turn change the fluid properties such as densities, viscosities, surface tensions and flow velocities. To take into account these changes a set of variables are defined. A brief description of these variables follow.

Liquid Holdup H_L , defined as the fraction of the pipe element that is occupied by liquid

$$H_L = \frac{\text{Volume of Liquid in a Pipe Element}}{\text{Volume of the Pipe Element}} \quad (3.4)$$

The gas holdup is defined as

$$H_G = 1 - H_L \quad (3.5)$$

No-Slip Liquid Holdup λ_L , is defined as the ratio of the volume of the liquid in a pipe element that would exist if the gas and liquid traveled at the same velocity (no slippage) divided by the volume of the pipe element. It can be calculated from the gas and liquid velocities as

$$\lambda_L = \frac{q_L}{q_L + q_G} \quad (3.6)$$

Similarly, the no slip gas holdup factor is defined as

$$\lambda_G = 1 - \lambda_L \quad (3.7)$$

Density ρ_m , is used in calculating the kinetic and potential energy changes. Several different equations have been used to calculate the appropriate fluid density. The most commonly used equation is

$$\rho_m = \rho_L H_L + \rho_G H_G \quad (3.8)$$

in this case ρ_L is defined to be

$$\rho_L = \rho_o f_o + \rho_w f_w \quad (3.9)$$

where f_x represents the fractional flow of water or oil.

Velocity Many of the two phase flow correlations are based on the superficial velocity of a phase. The superficial velocity is defined as the velocity of the phase, if the phase was flowing through the total cross sectional area of the pipe. The superficial velocity of gas is defined as

$$v_{SG} = \frac{q_G}{A} \quad (3.10)$$

where

- v_{SG} = superficial velocity of gas
- A = cross sectional area of the pipe
- q_G = flowrate of gas

The actual gas velocity is calculated from

$$v_G = \frac{q_G}{AH_G} \quad (3.11)$$

Similar definitions can be applied to calculate the superficial velocity, and the actual velocity of the liquid phase.

The viscosity and surface tension of the fluid is calculated in a similar manner to the density calculation - (Equation 3.8), with the density terms replaced by the appropriate viscosity or surface tension terms.

There are many empirical multiphase correlations that have been developed to predict the pressure drop due to two phase flow in pipes. Most of these correlations use liquid holdup to accurately predict the pressure loss due to the potential energy term. This is accomplished by using flow regime maps. Depending on the superficial velocity of gas and liquid, distinct flow patterns are observed. Each of these flow patterns provides a different pressure drop associated with the potential energy and friction energy terms. The flow regimes are based on the fluid distribution in the pipe.

Descriptions of the major flow regimes are as follows:

Bubble Flow - The pipe is almost completely filled with liquid and the free gas phase is present as small bubbles. The bubbles flow at different velocities, and except for the density, have little effect on the pressure gradient.

Slug Flow - The gas phase is more pronounced. The gas bubbles coalesce and form plugs or slugs which almost fill the pipe cross section. The gas bubble velocity is greater than the liquid velocity. Both phases have a significant effect on the pressure drop.

Transitional Flow - Change from liquid phase to a continuous gas phase occurs. Gas bubbles join together, and the liquid may be entrained in the bubbles. Although the liquid phase effects are significant, the gas phase effects are dominant.

Mist Flow - The gas phase is continuous, and the liquid is entrained as droplets in the gas phase. Gas phase controls the pressure gradient.

3.3 Hagedorn and Brown Correlation

Hagedorn and Brown [1964] proposed a generalized correlation for multiphase vertical flow. This correlation was generated using data measured for a wide range of gas-liquid ratios, tubing sizes, and differing fluid properties.

The pressure drop equation can be written as

$$144 \frac{\Delta p}{\Delta h} = \frac{g}{g_c} [\rho_L H_L + \rho_g (1 - H_L)] \left\{ 1 + \frac{f(v_{SL} + v_{SG})^2}{2g_c d} + \Delta \left[\frac{(v_{SL} + v_{SG})^2}{2g} \right] \right\} \quad (3.12)$$

where Δh = depth increment
 d = pipe diameter
 f = Moody friction factor

This correlation does not take into account the different flow regimes. In this case, the liquid hold up is used as a correlating parameter, in the calculation of the total pressure drop for an incremental length of pipe.

The calculation procedure for the Hagedorn and Brown [1964] correlation is described below.

1. An incremental pipe length Δh , is chosen.
2. Starting with a point at which the pressure is known, the incremental pressure is assumed and the arithmetic average pressure is calculated.
3. Specific gravity of the oil and gas are calculated.

4. The mass associated with one barrel of stock tank liquid is calculated as.

$$m = 350\gamma_o \left(\frac{1}{1+WOR} \right) + 350\gamma_w \left(\frac{WOR}{1+WOR} \right) + 0.0764\gamma_g GLR \quad (3.13)$$

where WOR = water-oil ratio
GLR = gas-liquid ratio
 γ_x = specific gravity

5. Calculate the mass flow rate.
6. Calculate the density, viscosity and surface tension of the liquid and gas phases.
7. Calculate the liquid viscosity number, N_L

$$N_L = 0.15726\mu_L \left(\frac{1}{\rho_L\sigma_L^3} \right)^{1/4} \quad (3.14)$$

Interpolating from Table 3.1, Graph 1, calculate CN_L

8. Calculate the liquid velocity number, N_{LV}

$$N_{LV} = 1.938v_{SL} \left(\frac{\rho_L}{\sigma_L} \right)^{1/4} \quad (3.15)$$

9. Calculate the gas velocity number, N_{GV}

$$N_{GV} = 1.938v_{SG} \left(\frac{\rho_L}{\sigma_L} \right)^{1/4} \quad (3.16)$$

9. Calculate the pipe diameter number, N_D

$$N_D = 120.872 d \sqrt{\rho_L/\sigma_L} \quad (3.17)$$

10. Calculate the correlating parameter, Φ_α as in Graph 2 of Table 3.1. Interpolating Graph 2 find the value of ψ .

$$\text{where } \Phi_\alpha = \frac{N_{LV}N_L^{0.38}}{N_D^{2.14}} \quad (3.18)$$

11. Calculate the correlating parameter Φ_β , as in Graph 3 of Table 3.1, and then interpolate to find the value of H_L/ψ , and hence the value of the liquid holdup, H_L .

$$\text{where } \Phi_\beta = \left(\frac{N_{LV}}{N_{GV}^{0.575}} \right) \left(\frac{p}{p_{sc}} \right)^{0.1} \left(\frac{CN_L}{N_D} \right) \quad (3.19)$$

| Table 3.1: Correlating Functions of Hagedorn and Brown [1964] from Carroll [1990] | | | | | |
|-----------------------------------------------------------------------------------|--------|---------------|--------|--------------|------------|
| GRAPH 1 | | GRAPH 2 | | GRAPH 3 | |
| N_L | CN_L | Φ_α | ψ | Φ_β | H_L/ψ |
| 0.002 | 0.0019 | 0.010 | 1.00 | 0.20 | 0.04 |
| 0.005 | 0.0022 | 0.020 | 1.10 | 0.50 | 0.09 |
| 0.010 | 0.0024 | 0.025 | 1.23 | 1.00 | 0.15 |
| 0.020 | 0.0028 | 0.030 | 1.40 | 2.00 | 0.18 |
| 0.030 | 0.0033 | 0.035 | 1.53 | 5.00 | 0.25 |
| 0.060 | 0.0047 | 0.040 | 1.60 | 10.00 | 0.34 |
| 0.100 | 0.0064 | 0.045 | 1.65 | 20.00 | 0.44 |
| 0.150 | 0.0080 | 0.050 | 1.68 | 50.00 | 0.65 |
| 0.200 | 0.0090 | 0.060 | 1.74 | 100.00 | 0.82 |
| 0.400 | 0.0115 | 0.070 | 1.78 | 200.00 | 0.92 |
| | | 0.080 | 1.80 | 300.00 | 0.96 |
| | | 0.090 | 1.83 | 1000.00 | 1.00 |

12. Calculate the Reynolds number N_{Re} , and the friction factor f .

$$N_{Re} = \frac{2.2 \times 10^{-2} q_o m}{(\mu_L^{H_L})(\mu_L^{(1-H_L)})d} \quad (3.20)$$

$$\text{and } \frac{1}{\sqrt{f}} = 1.74 - 2 \log \left(\frac{2\varepsilon}{d} + \frac{18.7}{N_{Re} \sqrt{f}} \right) \quad (3.21)$$

where ε = roughness of the pipe

Equation 3.21 has to be solved using a trial and error procedure. Then using Equation 3.12 the value of Δh can be calculated.

The correlation implemented contains a modified form of the Hagedorn and Brown [1964] correlation. If the flow regime is found to be in bubble flow, the Griffith and Wallis [1961] correlation is used. The procedure followed is as follows.

1. Calculate the values of A and B.

$$A = 1.071 - \left[0.2218(v_{SL} + v_{SG})^2 \right] / d \quad (3.22)$$

$$B = \frac{v_{SG}}{v_{SL} + v_{SG}} \quad (3.23)$$

If B is greater than or equal to A, then continue with Hagedorn and Brown correlation. If A is greater than B, the flow is in the bubble flow regime and the Griffith and Wallis [1961] correlation is used.

2. Griffith and Wallis [1961] used the following equation to calculate the gas holdup H_G

$$H_G = \frac{1}{2} \left[1 + \frac{q_L}{v_s A} - \sqrt{\left(1 + \frac{q_L}{v_s A} \right)^2 - \frac{4q_G}{v_s A}} \right] \quad (3.24)$$

where v_s = is the slip velocity, average value of 0.8 ft/sec.

With this value of gas holdup computed the rest of the computations are carried on in the same manner as in the Hagedorn and Brown correlation.

3.4 Aziz, Govier and Fogarasi Correlation

Aziz, Govier and Fogarasi [1972] proposed a method which was flow regime dependent. The flow regimes are defined using the following variables.

$$N_x = v_{SG} \left(\frac{\rho_G}{0.0764} \right)^{1/3} \left(\frac{72 \rho_L}{62.4 \sigma_L} \right)^{1/4} \quad (3.25)$$

$$N_y = v_{SL} \left(\frac{72 \rho_L}{62.4 \sigma_L} \right)^{1/4} \quad (3.26)$$

$$N_1 = 0.51(100N_y)^{0.172} \quad (3.27)$$

$$N_2 = 8.6 + 3.8N_y \quad (3.28)$$

$$N_3 = 70(100N_y)^{-0.152} \quad (3.29)$$

Bubble Flow - the case when

$$N_x < N_1$$

then the liquid holdup is calculated from

$$H_L = 1 - \frac{v_{SG}}{v_{bf}} \quad (3.30)$$

where v_{bf} = the bubble rise velocity in the flowing stream

$$v_{bf} = 1.2v_m + v_{bs} \quad (3.31)$$

and
$$v_{bs} = 1.41 \left[\frac{\sigma_L g (\rho_L - \rho_G)}{\rho_L^2} \right]^{1/4} \quad (3.32)$$

$$v_m = v_{SG} + v_{SL} \quad (3.33)$$

The hydrostatic head is then calculated by

$$\left(\frac{dp}{dL} \right)_{hs} = \frac{g}{g_c} \rho_m \quad (3.34)$$

The friction pressure drop is calculated as

$$\left(\frac{dp}{dL} \right)_f = \frac{f \rho_m v_m^2}{2 g_c d} \quad (3.35)$$

In bubble flow the acceleration term is considered to be negligible. The summation of the friction pressure drop and the hydrostatic pressure drop gives the total pressure drop.

Slug Flow - The limits for this flow regime is defined as follows,

$$N_1 < N_x < N_2 \quad \text{for } N_y < 4$$

$$\text{and } N_1 < N_x < 26.5 \quad \text{for } N_y \geq 4$$

The liquid holdup is calculated as in Equation 3.30, and the bubble rise velocity as in Equation 3.31. In this case v_{bs} is defined as

$$v_{bs} = C \left[\frac{gd(\rho_L - \rho_G)}{\rho_L} \right]^{1/2} \quad (3.36)$$

$$\text{and } C = 0.345 \left[1 - \text{EXP}(-0.029N_v) \right] \left[1 - \text{EXP}\left(\frac{3.37 - N_E}{m}\right) \right] \quad (3.37)$$

$$\text{where } N_E = \frac{gd^2(\rho_L - \rho_G)}{\sigma_L} \quad (3.38)$$

$$N_v = \frac{[d^3g(\rho_L - \rho_G)]^{1/2}}{\mu_L} \quad (3.39)$$

In the slug flow regime the acceleration pressure drop is considered to be negligible. The total hydrostatic pressure drop is calculated as in Equation 3.34 and the friction pressure drop as

$$\left(\frac{dp}{dL} \right)_f = \frac{f\rho_L H_L v_m^2}{2g_c d} \quad (3.40)$$

Summation of the hydrostatic and friction pressure losses provides the total pressure loss.

Transition Flow - This flow regime exists when

$$N_2 < N_x < N_3 \quad \text{for } N_y < 4$$

When the flow regime fall in this transition zone, the total pressure drop is obtained by interpolating between the total pressure drops in the slug flow regime and the mist flow regime. The pressure drop can be expressed as

$$\left(\frac{dp}{dL}\right)_{Total} = A\left(\frac{dp}{dL}\right)_{Slug} + B\left(\frac{dp}{dL}\right)_{Mist} \quad (3.41)$$

where A and B represent weighting factors.

Mist Flow - This flow regime is encountered when

$$N_x > N_3 \quad \text{For } N_y < 4$$

$$\text{and } N_x > 26.5 \quad \text{For } N_y > 4$$

Aziz, Govier and Fogarasi [1972] use the procedure of Duns and Ros [1963]. Duns and Ros [1963] assumed that with high gas flow rates in this region, that the slip velocity would be zero. The mixture density is calculated from the no-slip velocities as

$$\rho_m = \rho_L \lambda_L + \rho_G \lambda_G \quad (3.42)$$

The hydrostatic head is calculated from Equation 3.34 with the density of the mixture from Equation 3.42.

The frictional pressure drop is calculated from

$$\left(\frac{dp}{dZ}\right)_f = \frac{f \rho_G v_{SG}^2}{2g_c d} \quad (3.43)$$

The friction factor is a function of the Reynolds number of the gas, which can be expressed as

$$N_{Re} = \frac{\rho_G v_{SG} d}{\mu_G} \quad (3.44)$$

Duns and Ros [1963] also accounted for the increase in roughness of the wall due to the presence of the liquid film. The ripples of liquid on the wall causes a drag on the gas. These processes is governed by the Weber number N_{We} and the liquid viscosity number N_μ .

$$N_{We} = \frac{\rho_G v_{SG}^2 \varepsilon}{\sigma_L} \quad (3.45)$$

$$N_{\mu} = \frac{\mu_L^2}{\rho_L \sigma_L \varepsilon} \quad (3.46)$$

The following equations provide the corrected values for the pipe roughness. For values of $N_{w\epsilon} N_{\mu} \leq 0.05$

$$\frac{\varepsilon}{d} = \frac{0.0749 \sigma_L}{\rho_G v_{SG}^2 d} \quad (3.47)$$

For values of $N_{w\epsilon} N_{\mu} > 0.05$

$$\frac{\varepsilon}{d} = \frac{0.3713 \sigma_L}{\rho_G v_{SG}^2 d} (N_{w\epsilon} N_{\mu})^{0.302} \quad (3.48)$$

Using the above relations the frictional pressure drop can be calculated.

The pressure drop due to acceleration can be included by defining an acceleration term E_K as

$$E_K = \frac{v_m v_{SG} \rho_{ns}}{g_c P} \quad (3.49)$$

The total pressure drop can be calculated as

$$\left(\frac{dp}{dL}\right)_{\text{total}} = \frac{\left(\frac{dp}{dL}\right)_{\text{hydrostatic}} + \left(\frac{dp}{dL}\right)_{\text{friction}}}{1 - E_K} \quad (3.50)$$

4. Separator Model

4.1 Introduction

Produced reservoir fluids are complex mixtures of hydrocarbons with different physical characteristics. The produced fluids separate into two phases - oil and gas. The separation of the oil from the gas at the surface is accomplished by conventional stage separation.

Stage separation is the process by which gaseous and liquid hydrocarbons are flashed (separated) into vapor and liquid streams by using two or many separators. As Figure 4.1 illustrates, the separation process can use as many separators as is desired. As the number of stages increases, the pressure of the separators is dropped slowly and the flashing process mimics differential liberation. Differential liberation is the "best" separation process as it leaves the maximum quantity of the valuable liquid phase.

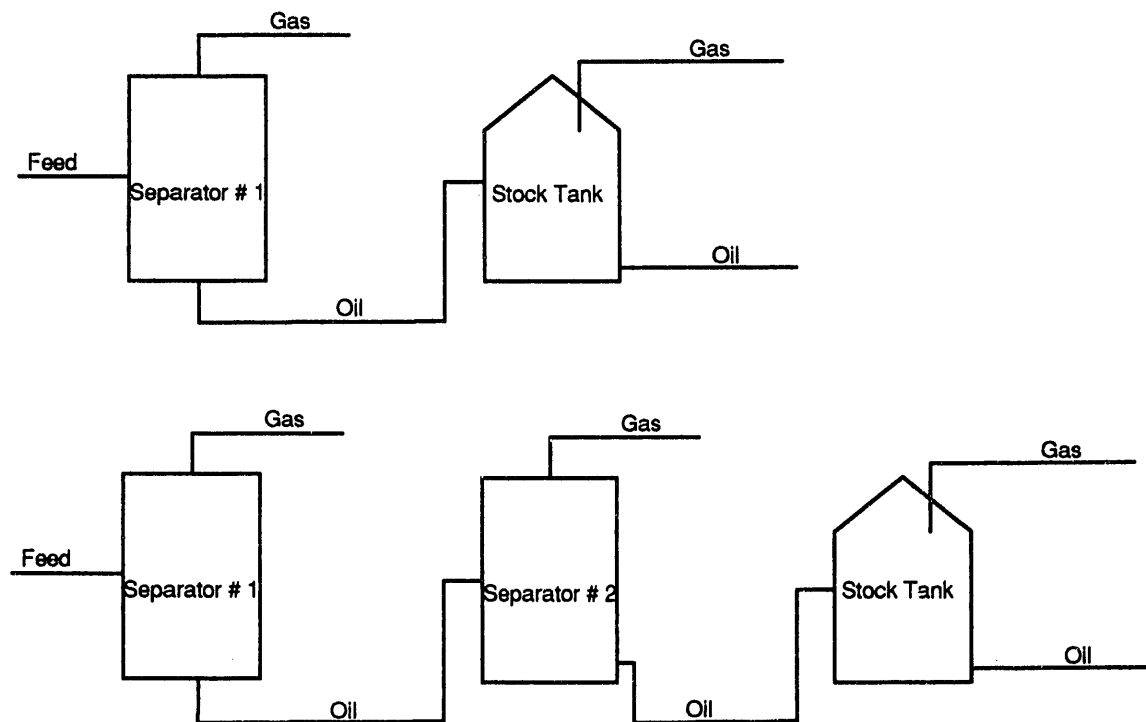


Figure 4.1: Schematic illustration of a two and three stage separation process (Ahmed [1989])

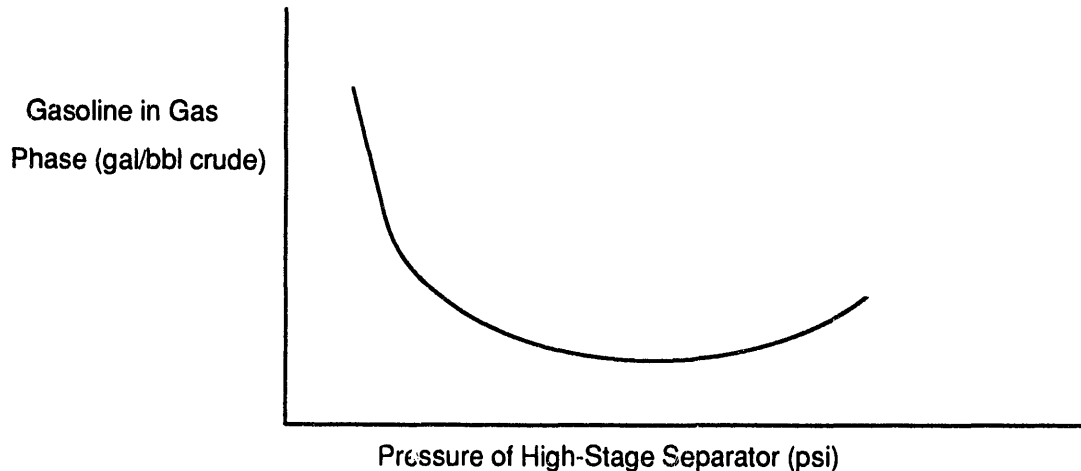


Figure 4.2: Gasoline Content of Gas Phase as a Function of High Stage Separator Pressure

Figure 4.2 shows the gasoline that is retained in the vapor phase as a function of separator pressure. The goal in stage separation is to flash the feed stream at that pressure which results in the least loss of gasoline and other valuable hydrocarbons to the gas phase (Chilingarian, Robertson and Kumar [1987]). The separation process is modeled by using a flash calculation. This chapter describes the flash process that was implemented in this study.

4.2 Flash Calculation

The oil and gas mixture that flows into a separator has a fixed overall composition. In the separator it is flashed at a fixed temperature and pressure. The flash calculation mimics this phase behavior and is used to determine the new composition of the oil and gas streams.

The following procedure from Orr [1991] is used to determine the phase compositions.

1. For a flash of a given overall composition, pressure and temperature, guess the resulting composition of the liquid stream x_i and the gas stream y_i
2. Calculate the equation of state parameters
3. Solve the equation of state and determine the molar volumes of the gas and liquid phases.
4. Calculate the partial fugacities of the liquid and gas phases.

5. Check if the partial fugacities of all the phases are equal. If the partial fugacities are equal, then the equilibrium composition of the output streams have been calculated.
6. If the fugacities are not equal, then improve the estimates of the composition of the phases and return to step 2.

A detailed description of each of the steps described above appears in Section 4.3 through to Section 4.8.

4.3 Initial Estimation of the Compositions

As a first guess, the Wilson and Deal [1962] equation is used to estimate the value of the equilibrium ratio k_i .

$$k_i = \frac{y_i}{x_i} = \frac{\exp\left[5.37(1 + \omega_i)\left(1 - \frac{1}{T_{ri}}\right)\right]}{P_{ri}} \quad (4.1)$$

where ω_i = acentric factor, available from the literature
 T_{ri} = Reduced Temperature (= $T/T_{critical}$)
 P_{ri} = Reduced Pressure (= $p/P_{critical}$)

A material balance on component i gives

$$z_i = Lx_i + (1 - L)y_i \quad (4.2)$$

where L = liquid mole fraction

Using the definition for the equilibrium ratio from Equation 4.1, Equation 4.2 can be rewritten as

$$x_i = \frac{z_i}{L + (1 - L)k_i} \quad (4.3)$$

and
$$y_i = \frac{k_i z_i}{L + (1 - L)k_i} \quad (4.4)$$

The solutions to Equations 4.3 and 4.4 are constrained by the following relation

$$\sum_i x_i - \sum_i y_i = 0 \quad (4.5)$$

Therefore, a solution to the following equation must be found

$$F(L) = \sum_i \frac{z_i(1-k_i)}{k_i + (1-k_i)L} \quad (4.6)$$

This equation can be solved to find the value of L using a Newton-Raphson iteration scheme.

$$L^{k+1} = L^k - \frac{F(L^k)}{\left. \frac{dF}{dL} \right|_{L^k}} \quad (4.7)$$

Convergence is assumed when both of the following conditions are met.

$$|L^{k+1} - L^k| < \varepsilon$$

and $F(L^{k+1}) < \varepsilon$

where $\varepsilon =$ a small number, say 10^{-6}

4.4 Calculation of Equation of State (EOS) Parameters

The Soave-Redlich-Kwong (SRK) equation of state is used in this study. The SRK equation of state can be written as

$$p = \frac{RT}{V - b_i} - \frac{a_i \alpha_i}{V(V - b_i)} \quad (4.9)$$

This equation can be written in cubic form as

$$V^3 - \left[\frac{RT}{p} \right] V^2 + \left[\frac{(a\alpha)_m}{p} - \frac{b_m RT}{p} - b_m^2 \right] V - \left[\frac{(a\alpha)_m b_m}{p} \right] = 0 \quad (4.10)$$

where $V =$ Molar volume
 $R =$ Universal gas constant

and $a_i = 0.42747 \frac{R^2 T_c^2}{p_c}$ (4.11)

$$b_i = \frac{0.08664 RT_c}{p_c} \quad (4.12)$$

$$\alpha_i = \left[1 + (0.480 + 1.574\omega_i - 0.176\omega_i^2)(1 - T_i^{0.5}) \right]^2 \quad (4.13)$$

$$(a\alpha)_m = \sum_i \sum_j \left[x_i x_j (a_i a_j \alpha_i \alpha_j)^{0.5} (K_{ij} - 1) \right] \quad (4.14)$$

$$b_m = \sum_i x_i b_i \quad (4.15)$$

K_{ij} is an empirically determined correction factor known as a binary interaction parameter, characterizing the binary formed by component i and j in the hydrocarbon mixture. The binary interaction parameters are used to model the intermolecular interaction through empirical adjustment.

4.5 Calculation of Liquid and Vapor Molar Volumes

The cubic form of the SRK equation of state (Equation 4.10) must be solved to find the molar volumes of the liquid and vapor. The roots can be calculated analytically or numerically using a Newton-Raphson iteration scheme. The analytical solution method is implemented in this study. Detailed explanation of the technique can be found in the notes of Orr [1991], and in the thesis by Carroll [1990].

4.6 Determining the Partial Fugacities

The partial fugacity \hat{f}_i , of a component can be calculated from the following relation

$$\hat{f}_i = p \text{ EXP} \left[\int_0^p \left(\frac{Z-1}{p} \right) dp \right] \quad (4.16)$$

For the SRK equation of state the partial fugacity \hat{f}_i , of component i may be calculated from

$$\hat{f}_i = p \exp \left[\left(\frac{V}{V-b_m} \right) + \frac{b_i}{V-b_m} + \frac{2 \sum x_i a_i a_j}{RT b_m} \ln \left(\frac{V+b_m}{V} \right) + \frac{(a\alpha)_m b_i}{RT b_m^2} \left(\ln \left(\frac{V+b}{V} \right) - \frac{b_m}{V+b_m} \right) - \ln \left(\frac{pV}{x_i RT} \right) \right] \quad (4.17)$$

4.7 Convergence Checks

The phase compositions and the molar volumes are found when the partial fugacities of each the components are the same, for all of the phases present. In this case, convergence is assumed when

$$\left| \frac{\hat{f}_i^V}{\hat{f}_i^L} - 1 \right| \leq \varepsilon \quad (4.18)$$

4.8 Modification of the Phase Compositions

The new values for the equilibrium ratios are found by a substitution scheme described below. Readers are referred to the work of Orr[1991] and that of Carroll [1990] for further detail.

$$k_i^{k+1} = \frac{\hat{f}_i^L}{\hat{f}_i^V} k_i^k \quad (4.19)$$

With the new values for the phase compositions the procedure is restarted (Section 4.3).

Nonlinear Optimization Algorithms

5.1 Introduction

Nonlinear optimization is concerned with finding the minimum or maximum of nonlinear functions. For example, when designing an aircraft an engineer may try to minimize the fuel consumption. This is known as the objective, and the mathematical statement which describes the behavior of the objective as a function of the chosen variables is known as the objective function. In this case, the fuel consumption is a function of many of the aircraft design variables such as wing span, size of the fuselage, size of engines used etc., which are known as the decision variables.

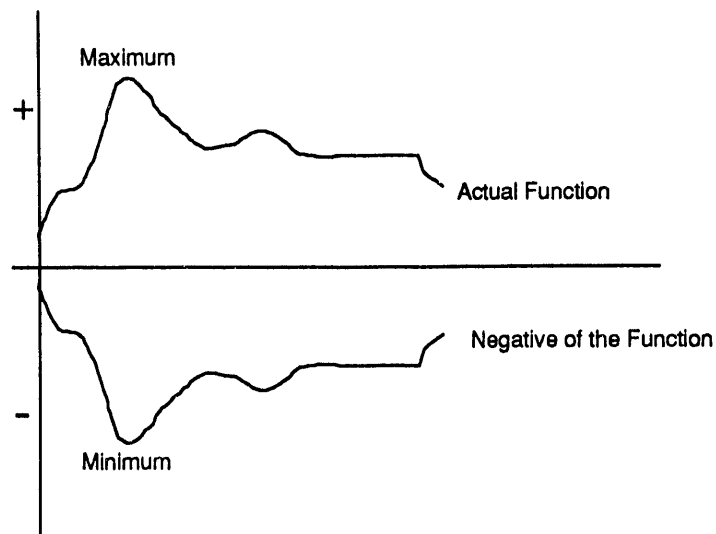


Figure 5.1 - Shows how the actual function and its negative can be used to find the minimum and the maximum of the function

As Figure 5.1 illustrates, maximization can be thought of as the minimization of the negative of the objective function. Nonlinear optimization algorithms are designed to find the minimum of objective functions. Therefore, in the rest of this discussion concentrates on the minimization of objective functions.

Nonlinear optimization algorithms can be separated in to two major classes. One, the algorithms based on gradients of the objective function such as those based Newton's method. Second, the algorithms based on function value comparisons such as the polytope algorithm and other searching techniques.

Readers are referred to Gill, Murray and Wright [1981] and to Scales [1985] for a comprehensive treatment of nonlinear optimization.

There are many techniques available to minimize an arbitrary function $F(\bar{x})$ of n independent variables. Before describing these techniques, let me define some commonly used notation.

The objective function $F(x_1, x_2, x_3, x_4, \dots, x_n)$ will be denoted by $F(\bar{x})$ where the variables are gathered together in a vector \bar{x}

$$\bar{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \text{and} \quad \bar{p} = \begin{bmatrix} p_1 \\ p_2 \\ \vdots \\ p_n \end{bmatrix} \quad (5.1)$$

All methods used to find the extrema of nonlinear functions are iterative. At the start of the k -th iteration, the current estimate of the minimum will be denoted by \bar{x}_k . The k -th iteration then consists of computing the search vector \bar{p}_k , from which the new estimate for the minimum \bar{x}_{k+1} is found according to the equation

$$\bar{x}_{k+1} = \bar{x}_k + \alpha_k \bar{p}_k \quad (5.2)$$

where α_k is a scalar, and is obtained by a line search or is based on the theory of the method being used. It is the method of determining \bar{p}_k that largely distinguishes one method from another.

5.2 Method of Steepest Descent

Gradient methods involve searching along the vector \bar{p}_k from the current point \bar{x}_k . The requirement is that α_k be chosen so that

$$F_{k+1} < F_k \quad \text{where} \quad F_k = F(\bar{x}_k) \quad (5.3)$$

It is not always possible to find a vector \bar{p}_k which satisfies Equation 5.3. The basic idea in gradient based algorithms is to find the descent direction. The descent direction is given by the vector \bar{p}_k . With the descent direction known, a very small, positive value of α_k . will satisfy Equation 5.3.

Most of the techniques used to find the extrema of the functions use the first and second derivatives of the functions to compute \bar{p}_k . The derivatives may be calculated analytically or approximated by using finite difference algorithms.

Using a Taylor series expansion F_{k+1} , can be written as

$$F_{k+1} = F(\tilde{x}_k + \alpha_k \tilde{p}_k) \approx F_k + \frac{1}{2} \alpha_k^2 \tilde{p}_k^T G_k \tilde{p}_k \quad (5.4)$$

In this case all the terms of order three or more have been ignored. The form indicated in Equation 5.4 is the quadratic approximation to the real function.

The term G_k is the Hessian Matrix of the function $F(\tilde{x})$ at the k-th iteration, and can be written as

$$G_k = \begin{bmatrix} \frac{\partial^2 F}{\partial \alpha_1^2} & \dots & \dots & \frac{\partial^2 F}{\partial \alpha_n \partial \alpha_1} \\ \vdots & & & \vdots \\ \vdots & & & \vdots \\ \frac{\partial^2 F}{\partial \alpha_n \partial \alpha_1} & \dots & \dots & \frac{\partial^2 F}{\partial \alpha_n^2} \end{bmatrix} \quad (5.5)$$

In order to satisfy Equation 5.3, \tilde{p}_k must be chosen such that

$$\tilde{p}_k^T G_k \tilde{p}_k < 0 \quad (5.6)$$

The calculation of the first and second derivatives of the objective function $F(\tilde{x})$ may be carried out either analytically or numerically. The numerical, finite difference techniques used to approximate the values of the derivatives are based on Taylor series expansions. Readers are referred to Abramowitz and Stegun [1965] for a detailed description of the available numerical approximations.

Equation 5.4 is a second order approximation to the function $F(\tilde{x})$ at \tilde{x}_k . A first order approximation can be written as

$$F_{k+1} = F(\tilde{x}_k + \alpha_k \tilde{p}_k) \approx F_k + \alpha_k \tilde{g}_k^T \tilde{p}_k \quad (5.7)$$

If the condition in Equation 5.3 is to be satisfied

$$\tilde{g}_k^T \tilde{p}_k < 0 \quad (5.8)$$

where $\tilde{g}_k = \begin{bmatrix} \frac{\partial F}{\partial \alpha_1} \\ \frac{\partial F}{\partial \alpha_2} \\ \vdots \\ \frac{\partial F}{\partial \alpha_n} \end{bmatrix}$ (5.9)

Equation 5.7 can be written in the form

$$F_{k+1} - F_k \approx \alpha_k \|\tilde{g}_k\| \|\tilde{p}_k\| \cos \theta \quad (5.10)$$

Now if all values in the right hand side of this equation are held constant, and only the angle θ is allowed to change, the equation will be most negative (< 0) when $\theta = \pi$. Thus, for a small value of α_k , the largest reduction in the value of the function will be in the direction

$$\tilde{p}_k = -\tilde{g}_k \quad (5.11)$$

This direction is known as *steepest descent direction*, and gives rise to the method of *steepest descent*.

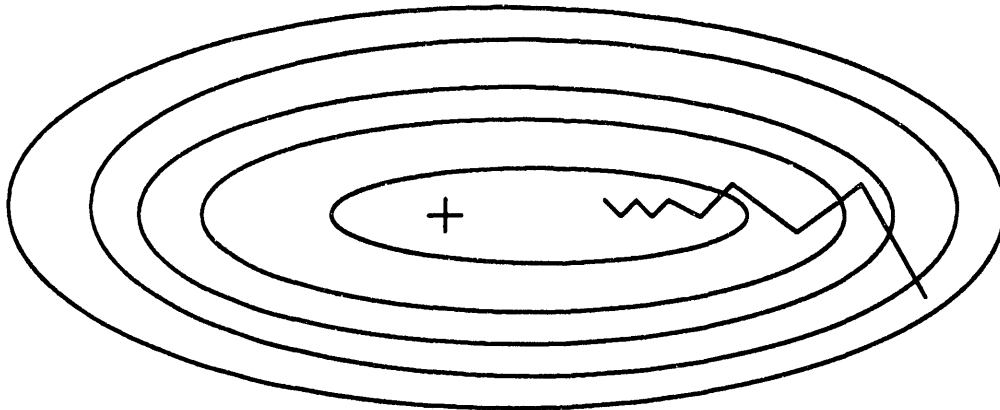


Figure 5.2: The steepest decent method showing the zig-zag progress.

In the case of this algorithm, the successive search directions are orthogonal, and as a result the iterations generate a sequence of points which follow a zig-zag path to the minimum. This results in very small steps being taken, which results in very slow convergence to the minimum.

The *Steepest decent* algorithm is very stable, and is theoretically simple. However, due to the slow rate of convergence, it is not used in optimization, but is the fundamental component of more elaborate techniques.

5.3 Newton's Method

Newton's method is designed to achieve quadratic termination with a positive definite Hessian matrix. Mathematically, *Newton's method* can be represented as follows. The minimum of a function occurs when

$$\nabla F = 0 \quad \text{and} \quad \nabla^2 F = 0 \quad (5.12)$$

The gradient of the function can be written as

$$\nabla F = \tilde{g}_{k+1} = \tilde{g}(\tilde{x}_k + \tilde{p}_k) = \tilde{g}_k + G_k \tilde{p}_k \quad (5.13)$$

This is the Taylor series expansion for the gradient of the quadratic function at \tilde{x}_{k+1} . The terms of order greater than two are neglected. If \tilde{x}_{k+1} is the minimum of the function, then \tilde{g}_{k+1} is equal to zero, and therefore

$$\tilde{p}_k = -G_k^{-1} \tilde{g}_k \quad (5.14)$$

For non-quadratic functions, $\tilde{x}_k + \tilde{p}_k$ will be in general an approximation to the minimum, and so an iterative process is required to find the minimum of the function. Note that in *Newton's method* α_k , the step length, is unity.

The key to finding the minimum of the function is the Hessian matrix G_k . If the function has a minimum, the Hessian matrix must be positive definite¹. Problems arise with *Newton's method* when the calculated Hessian matrix is indefinite. This implies that the quadratic model for the actual function is neither bounded from above or below. There are a series of methods developed, known as *modified Newton methods* which overcome this problem. These methods are all based on constructing a new positive definite matrix \bar{G}_k , which is based on the Hessian matrix and is used to replace G_k in Equation 5.14.

The Hessian matrix can be decomposed, and written as the product of three matrices as shown in Equation 5.15. This particular decomposition technique is known as spectral decomposition.

$$G_k = U \Lambda U^T = \sum_{i=1}^n u_i \lambda_i u_i^T \quad (5.15)$$

where

- u_i = the eigenvectors of G_k
- λ_i = the eigenvalues of G_k
- U = the matrix composed of the eigenvectors of G_k
- Λ = the matrix composed of the eigenvalues of G_k on the diagonal, and zero's elsewhere.

¹ If all the eigenvalues of a symmetric matrix are strictly positive, then the matrix is said to be *positive definite*. Further, if A is a *positive definite* matrix, then for any non-zero vector x ,

$$\tilde{x}^T A \tilde{x} > 0$$

There is a corresponding definition for a *negative definite* matrix.

One of the methods of ensuring positive definiteness is to add a small quantity, μ_k to each eigenvalue, ensuring that all the new eigenvalues are positive. This technique, and modification to it, were the work of Marquardt [1963], Goldfeld, Quandt, and Trotter [1966], and Greenstadt [1967]. This process can be represented in matrix notation as

$$\bar{G}_k = G_k + \mu_k I \quad (5.16)$$

The modified Hessian matrix is used in an iterative process, solving Equation 5.14 to find the minimum of the function under consideration.

The method of Gill and Murray [1974] uses the *Cholesky factorization* of G_k to modify *Newton's method*. The *Cholesky factorization* can be represented as

$$G_k = L_k D_k L_k^T \quad (5.17)$$

In this case D_k is a diagonal matrix and L_k is a lower triangular matrix with diagonal elements equal to one. The values of D_k (elements d_{ij}) and L_k (elements l_{ij}) can be calculated using the following expressions (g_{ij} are elements of G_k)

$$d_{jj} = g_{jj} - \sum_{q=1}^{j-1} d_{jq} l_{jq}^2 \quad (5.18)$$

$$l_{ij} = \left(g_{ij} - \sum_{q=1}^{j-1} d_{jq} l_{iq} l_{jq} \right) / d_{jj} \quad \text{for } i = j+1, n \quad (5.19)$$

Equation 5.14 can be written in terms of the *Cholesky factorization* as two systems of linear equations, which can easily be solved.

$$t_k = -\bar{g}_k L_k^T \quad (5.20)$$

$$L_k^T p_k = D_k^{-1} t_k \quad (5.21)$$

In the Gill-Murray [1974] process, if any of the values of d_{ij} are less than a small positive constant δ , then a positive quantity r_{jj} is added to g_{ij} , and the *Cholesky factorization* is continued. The resulting matrices are then used in the minimization scheme as defined in Equations 5.20 and 5.21.

5.4 Quasi-Newton Methods

There are some nonlinear optimization algorithms which have the property of quadratic termination but do not use the second derivatives of the function. These methods sacrifice the speed of convergence, but save on the expense associated with calculating a new Hessian matrix for each iteration. During each iteration the Hessian

matrix is updated, and this new approximation to the Hessian is used to find the estimate to the minimum value.

The Newton iteration equation (Equation 5.14) can be written as

$$\bar{p}_k = -H_k \bar{g}_k \quad (H_k \approx G_k^{-1}) \quad (5.22)$$

During each iteration H_k is updated by

$$H_{k+1} = H_k + Q_k^H \quad (5.23)$$

where Q_k^H is a updating matrix. Q_k^H is chosen such that the *quasi Newton* condition is satisfied. The *quasi Newton* condition can be stated as

$$H_{k+1}(\bar{g}_{k+1} - \bar{g}_k) = \rho_k(\bar{x}_{k+1} - \bar{x}_k) \quad (5.24)$$

where ρ_k is a scalar.

Combining Equation 5.23 and 5.24 results in the following equation

$$Q_k^H \Delta \bar{g}_k = \rho_k \Delta \bar{x}_k - H_k \Delta \bar{g}_k \quad (5.25)$$

The solution to this equation can be written as

$$Q_k^H = \rho_k \frac{\Delta \bar{x}_k \bar{y}_k^T}{\bar{y}_k^T \Delta \bar{g}_k} - \frac{H_k \Delta \bar{g}_k \bar{z}_k^T}{\bar{z}_k^T \Delta \bar{g}_k} \quad (5.26)$$

In this case z_k and y_k are arbitrary vectors. If the following conditions are set

$$\rho_k = 1$$

$$\bar{y}_k = \Delta \bar{x}_k$$

and $\bar{z}_k = H_k \Delta \bar{g}_k$

then the updating equation for the new Hessian, Equation 5.23 can be written as

$$H_{k+1} = H_k + \frac{\Delta \bar{x}_k \Delta \bar{x}_k^T}{\Delta \bar{x}_k^T \Delta \bar{g}_k} - \frac{H_k \Delta \bar{g}_k \Delta \bar{g}_k^T H_k}{\Delta \bar{g}_k^T H_k \Delta \bar{g}_k} \quad (5.27)$$

This is known as the Davidon-Fletcher-Powell (DFP) formula (Davidon [1959], Fletcher and Powell [1963]). This was the first form of the *quasi Newton* method used widely in function minimization.

Another formulation widely used today is the BFGS formula. This was first suggested by Broyden [1970], Fletcher [1970], Goldfarb [1970] and Shanno [1970]. It can be expressed as

$$H_{k+1} = \left[I - \frac{\Delta \tilde{x}_k \Delta \tilde{g}_k^T}{\Delta \tilde{x}_k^T \Delta \tilde{g}_k} \right] H_k \left[I - \frac{\Delta \tilde{x}_k \Delta \tilde{g}_k^T}{\Delta \tilde{x}_k^T \Delta \tilde{g}_k} \right]^T + \frac{\Delta \tilde{x}_k \Delta \tilde{x}_k^T}{\Delta \tilde{x}_k^T \Delta \tilde{g}_k} \quad (5.28)$$

where I is the identity matrix.

The convergence rate when using the *quasi Newton* algorithms is between linear and quadratic. The advantage of the method is the reduction in computation required to generate the new Hessian matrix for each iteration. It is expected that the reduction in the efficiency of convergence is offset by the more efficient computation of the Hessian matrix, and hence the overall efficiency of the method is greater than that of *Newton's method*.

5.5 Polytope Algorithm

The *polytope* method, also known in the literature as the simplex method, is based on function comparison techniques. It does not require the use of function gradients, and can be used on both smooth and non smooth functions.

The *polytope* algorithm (Gill, [1983]) is a fairly robust function comparison algorithm. For a problem of n decision variables, a polytope of $n+1$ points is created. The objective function is evaluated at each of the $n+1$ points. The point with the highest function value (known as the worst point) is chosen, and a new point is generated to replace this point. The method of choosing the new point is as follows.

Using the best n points (excluding the point with the highest function value), a centroid c is generated.

$$c = \frac{1}{n} \sum_{i=1}^n \tilde{x}_i \quad (5.29)$$

The centroid is then used to generate the reflected point.

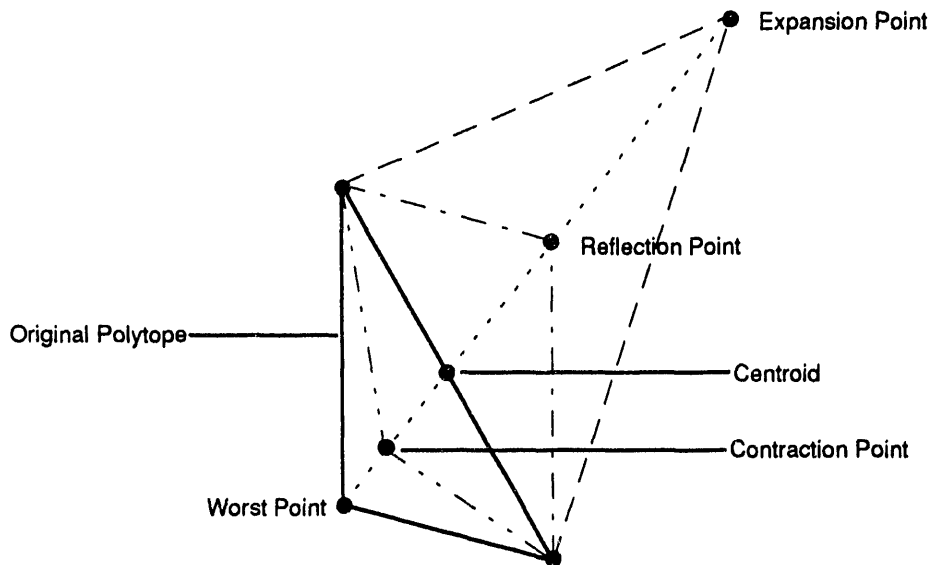


Figure 5.3: Two dimensional Polytope with the reflection, Expansion and Contraction Points. After Carroll [1990] and Gill, Murray and Wright [1981].

The reflected point is generated from the equation

$$x_r = c + \beta(c - x_{n+1})$$

where x_r = reflected point
 x_{n+1} = Worst point
 c = Centroid
 β = reflection coefficient

The function is evaluated at x_r , and there are three cases to consider.

1. The function value falls within the set of existing n function values, (i.e. the new point is neither the best or the worst point). In this case x_r replaces x_{n+1} and the next iteration is begun.
2. The function value is the new best point. In this case, the assumption that the direction of reflection is "good" is made, and the polytope is expanded in this direction - a reflection coefficient of greater than one is used. If the new expanded point is "better" than the reflected point, the expanded point is accepted as the new best point, and the next iteration is started. If however the expanded point is not "good", the original reflected point is accepted and a new iteration is started.
3. If the reflected function value is greater than all the existing points, then the polytope is thought to be too large, and a contraction is made by setting the reflection coefficient to less than one. If the contraction succeeds, the new value is accepted and a new iteration is started. Otherwise another contraction is carried out.

After several cycles of reflection the existing polytope is discarded and a new polytope is constructed using the best two points. The other points of the polytope are spaced on a regular grid using the distance between the two points as the spacing between points.

One of the main difficulties with the *polytope* method is to decide when a minimum point has been reached, as opposed to when the polytope is undergoing temporary difficulty. Nelder and Mead [1965] suggested the following two criteria for convergence to a minimum point of a objective function. Convergence is assumed when either one of the two criteria is satisfied.

1. $|F_1 - F_{n+1}| \leq \varepsilon(1 + |F_1|)$

$$2. \quad \sum_{i=1}^{n+1} \left(F_i - \frac{\sum_{j=1}^{n+1} F_j}{n+1} \right)^2 \leq \varepsilon$$

The above description of the *polytope* algorithm (also known as the simplex algorithm) is based on the discussion in Gill, Murray and Wright [1981], Carroll [1990] and Press, Flannery, Teukolsky and Vetterling [1986].

6. Optimization of Production Systems

6.1 Introduction

The purpose of this study was to investigate the ability of the nonlinear optimization algorithms to find optimum values for decision variables that vary with time. For example to maximize the Present Value of oil and gas production from a single completion. The completion string -- tubing diameter -- is assumed to change with time. The optimization would produce the "best" tubing diameter for a given time interval, for example for each year, or two years, or five years of production.

The previous chapters have described in detail the theory used in developing each of the components of the production model used for this optimization study. This chapter will concentrate initially on how the nonlinear optimization algorithms were coupled to the model of the production system and the objective function, and next, describe the results obtained from several time dependent optimizations of a tubing string and a simple gas lift scheme.

6.2 Production Model

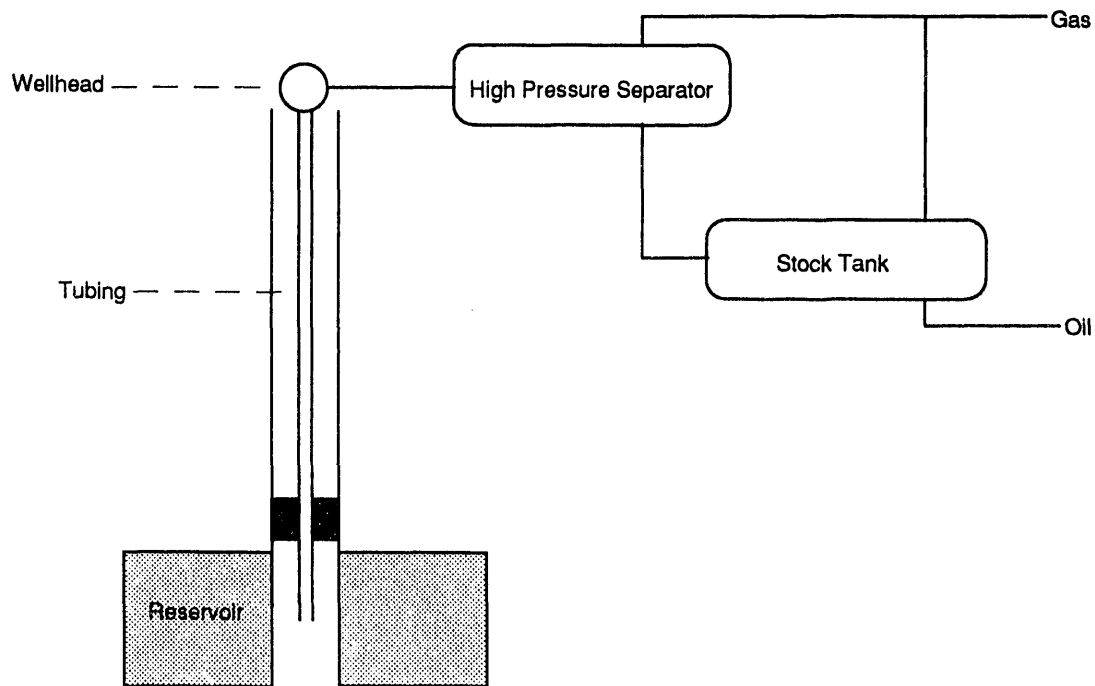


Figure 6.1: Schematic diagram of the Production Model

Figure 6.1 shows a schematic diagram of the production model used in this study. Note that in this case there is no horizontal flowline between the wellhead and the high pressure separator. The flowing wellhead pressure is the operating pressure of the high pressure separator. The decision variables chosen for studying are the tubing diameter and the high pressure separator pressure. Later in the study a gas lift system was implemented providing an additional decision variable, the gas injection rate.

6.3 Optimization Scheme and Algorithm

Figure 6.2 shows schematically how the nonlinear optimization algorithms are coupled with the objective function and production model. The iterative procedure for optimization is as follows.

1. The nonlinear optimization algorithm sends values for the decision variables to the production model.
2. Using the values for the decision variables the production model generates the production forecast.
3. Based on the production forecast the objective function generates the Present Value.
4. The nonlinear optimization algorithms use the Present Value to refine the estimate for the maximum, and sends the new estimates for the decision variables to the production model.

Iteration around the loop (in an anti-clockwise direction) as indicated in Figure 6.2 is continued until the maximum Present Value² is found, along with the associated values for the decision variables.

The IMSL mathematics library functions were used for optimization. Specifically DUMINF -- a quasi Newton algorithm that uses the BFGS formulation, and DUMPOL -- an implementation of the polytope algorithm. For a detailed explanation of these algorithms the reader is referred to Chapter 5 of this work.

The polytope algorithm always converged to the maximum point or to a point very close to the maximum point. The quasi Newton method did not always converge, specially when the time dependent variables were included in the optimization scheme. The "best" results were obtained by using a composite method, where the polytope algorithm was combined with the quasi Newton method. The technique employed was to

² In fact the algorithm finds the minimum of the negative of the objective function. This is equivalent to finding the maximum of the objective function. See Chapter 5 for further details.

use the polytope algorithm first to find the vicinity of the global maximum. Then the quasi Newton technique was used to locate the maximum point.

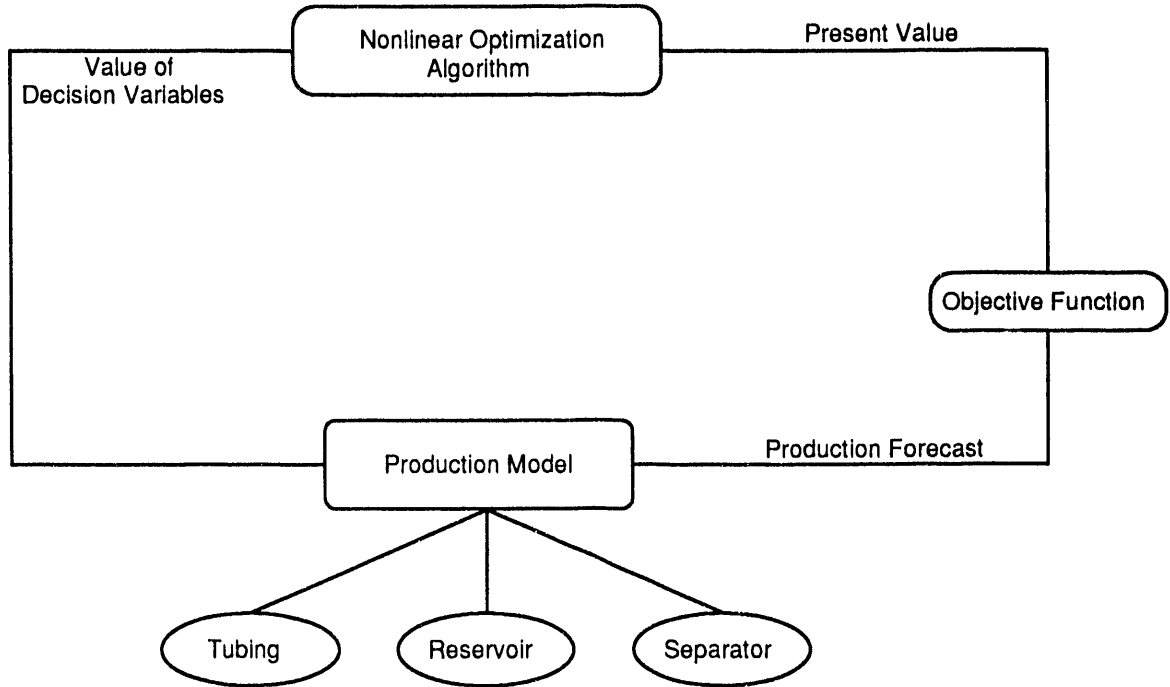


Figure 6.2: Schematic of the Iteration Process for Optimization

6.4 Objective Criteria

For the purpose of this study the objective criteria chosen was the Present Value of the oil and gas produced from the completion. The Present Value is a widely used method in project economics. The idea behind using Present Value is the concept of the "time value of money." The future income is discounted to reflect its worth in today's dollars.

The Present Value for a future income at time T , FI_T , can be represented mathematically as

$$PV_T = \frac{FI_T}{(1 + R)^{T-1/2}} \quad (6.1)$$

where R = the discount rate, and reflects the cost of capital to the company.

FI_T = Price of Oil * Oil Produced + Price of Gas * Gas Produced

It is assumed that the price of oil and gas will increase with time, and therefore the price is escalated at a inflation rate i . Equation 6.1 can be modified to

$$PV = \sum_{T=1}^n \left[\frac{FI_T}{\left(\frac{1+R}{1+i} \right)^{T-\frac{1}{2}}} \right] \quad (6.2)$$

The objective function can easily be modified to a net Present Value (NPV) form

$$NPV = \sum_{T=1}^n \left[\frac{FI_T - Cost_T}{\left(\frac{1+R}{1+i} \right)^{T-\frac{1}{2}}} \right] \quad (6.3)$$

where $Cost_T =$ Capital cost, tax payments, royalties, operating cost etc.

6.5 Tubing Diameter Optimization

The first sets of optimizations were carried out to obtain the optimum tubing diameters for a given well. This process finds the "best" tubing diameter for a producing time interval. The best in this case refers to the tubing size(s) that maximizes the Present Value. It mimics the real life case where a workover is performed to change out the tubing.

Figure 6.3 and 6.4 shows the Present Value surface for the case where a single tubing size and separator pressure are used for the entire life of the well. Figure 6.3 is based on the Aziz, Govier and Fogarasi [1972] and Figure 6.4 uses the Hagedorn and Brown correlation [1964]. As these figures indicate, the surface is rough (nonsmooth) and shows the presence of several local maxima.

The following time dependent tubing diameter optimization runs were made.

1. Tubing diameter changed after every 10 years of production.
2. Tubing diameter changed after every 5 years of production.
3. Tubing diameter changed every year of production.

The results from the optimizations are shown in numerical form in Tables 6.1 through to Table 6.4. The tubing sizes, production rates and pressures are plotted as a function of time for the Aziz, Govier and Fogarasi [1972] correlation in Figure 6.5 to Figure 6.7.

| Table 6.1: Single Tubing Diameter Optimization Results | | |
|--------------------------------------------------------|---------------------------|--------------------|
| | Flow Correlation | |
| | Aziz, Govier and Fogarasi | Hagedorn and Brown |
| Separator Pressure (psi) | 1113.77 | 1045.53 |
| Tubing Diameter (inches) | 9.27 | 13.44 |
| Present Value (\$ million) | 305.76 | 311.44 |

| Table 6.2: Optimization Results for Case When Tubing Diameter is Changed Every 10 Years. | | |
|------------------------------------------------------------------------------------------|---------------------------|--------------------|
| | Flow Correlation | |
| | Aziz, Govier and Fogarasi | Hagedorn and Brown |
| Separator Pressure (psi) | 1113.13 | 1029.71 |
| Tubing Diameter (inches) | | |
| (Year 0 - 10) | 9.16 | 18.97 |
| (Year 11 - 20) | 11.17 | 11.36 |
| Present Value (\$ million) | 306.64 | 313.02 |

| Table 6.3: Optimization Results for Case When Tubing Diameter is Changed Every 5 Years. | | |
|-----------------------------------------------------------------------------------------|---------------------------|--------------------|
| | Flow Correlation | |
| | Aziz, Govier and Fogarasi | Hagedorn and Brown |
| Separator Pressure (psi) | 1115.43 | 1029.4 |
| Tubing Diameter (inches) | | |
| (Year 0 - 5) | 9.11 | 22.36 |
| (Year 6 - 10) | 9.26 | 21.17 |
| (Year 11 - 15) | 11.10 | 10.66 |
| (Year 16 - 20) | 12.78 | 9.78 |
| Present Value (\$ million) | 306.80 | 314.19 |

| Table 6.4: Optimization Results for Case When Tubing Diameter is Changed Every Year. | |
|--------------------------------------------------------------------------------------|---------------------------|
| | Flow Correlation |
| | Aziz, Govier and Fogarasi |
| Separator Pressure (psi) | 1089.8 |
| Tubing Diameter (inches) | |
| (Year 1) | 9.78 |
| (Year 2) | 9.55 |
| (Year 3) | 9.34 |
| (Year 4) | 9.25 |
| (Year 5) | 9.30 |
| (Year 6) | 9.47 |

| | |
|----------------------------|--------|
| (Year 7) | 9.54 |
| (Year 8) | 10.03 |
| (Year 9) | 10.11 |
| (Year 10) | 10.80 |
| (Year 11) | 11.31 |
| (Year 12) | 11.73 |
| (Year 13) | 12.19 |
| (Year 14) | 12.57 |
| (Year 15) | 12.92 |
| (Year 16) | 13.03 |
| (Year 17) | 15.04 |
| (Year 18) | 11.77 |
| (Year 19) | 12.60 |
| (Year 20) | 13.38 |
| Present Value (\$ million) | 354.07 |

6.6 Gas Lift Optimization

A simple gas lift model was developed to investigate the ability of the nonlinear optimization algorithms to optimize the gas injection rate with time (Brown [1977]).

The model assumed that the gas was injected at the bottom of the completion string (tubing) at a specified rate. The net effect of the gas injection is to decrease the apparent density of the fluid flowing in the tubing. As the wellhead pressure is held constant, the reduction in density, reduces the pressure drop between the wellhead and the perforations, decreasing the flowing bottomhole pressure, increasing the flowrate of oil and gas. Except for the injection of gas, the production model and the objective function used is identical to the model described in Section 6.2

The model also assumes that there is an endless supply of gas for injection, and as the objective function was formulated in terms of Present Value there is no cost associated with the injection of gas.

Initially, the tubing diameter, separator pressure, and the gas injection rate were used as the decision variables for optimization. This problem did not appear to have an optimum. As Figures 6.8, 6.9, and 6.10 show the Present Value of the production seems to increase slowly in the direction of increasing tubing diameter and increasing gas injection rate. This problem can be overcome in one of two ways, to apply a cost to the injection gas, or to fix the tubing diameter. To investigate the time dependence of the optimum gas injection rate, the tubing diameter was fixed at 5.90 inches (15.0 cm).

Figure 6.11 shows the Present Value surface for the gas injection scheme with the tubing diameter fixed at 5.90 inches (15 cm). Figures 6.12 and 6.13 show the same surface for a fixed tubing diameter of 3.93 inches (10 cm) and 7.87 inches (20 cm) respectively.

The results of the optimizations are presented in Table 6.5 through to Table 6.7. Figure 6.14 shows the optimum injection rates as a function of time, and Figure 6.15 the production rates for oil and gas. Figure 6.16 shows the accompanying pressure profiles.

| Table 6.5: Single Gas Injection Rate Optimization Results | |
|-----------------------------------------------------------|-----------------------------------------------|
| | Flow Correlation Aziz, Govier and Fogarasi |
| Separator Pressure (psi) | 1217.20 |
| Tubing Diameter (inches) | 5.90 (fixed) |
| Injection Rate (mmscf/d) | 9.78 |
| Present Value (\$ million) | 341.35 |

| Table 6.6: Optimization Results for Case When Gas Injection Rate is Changed Every 10 Years. | |
|---------------------------------------------------------------------------------------------|-----------------------------------------------|
| | Flow Correlation Aziz, Govier and Fogarasi |
| Separator Pressure (psi) | 1215.89 |
| Tubing Diameter (inches) | 5.90 (fixed) |
| Injection Rate (mmscf/d) | |
| (Year 0 - 10) | 10.78 |
| (Year 11 - 20) | 0.13 |
| Present Value (\$ million) | 343.20 |

| Table 6.7: Optimization Results for Case When Gas Injection Rate is Changed Every 5 Years. | |
|--------------------------------------------------------------------------------------------|-----------------------------------------------|
| | Flow Correlation Aziz, Govier and Fogarasi |
| Separator Pressure (psi) | 1240.2 |
| Tubing Diameter (inches) | 5.90 (fixed) |
| Injection Rate (mmscf/d) | |
| (Year 0 - 5) | 17.75 |
| (Year 6 - 10) | 16.82 |
| (Year 11 - 15) | 4.87 |
| (Year 16 - 20) | 0.13 |
| Present Value (\$ million) | 344.19 |

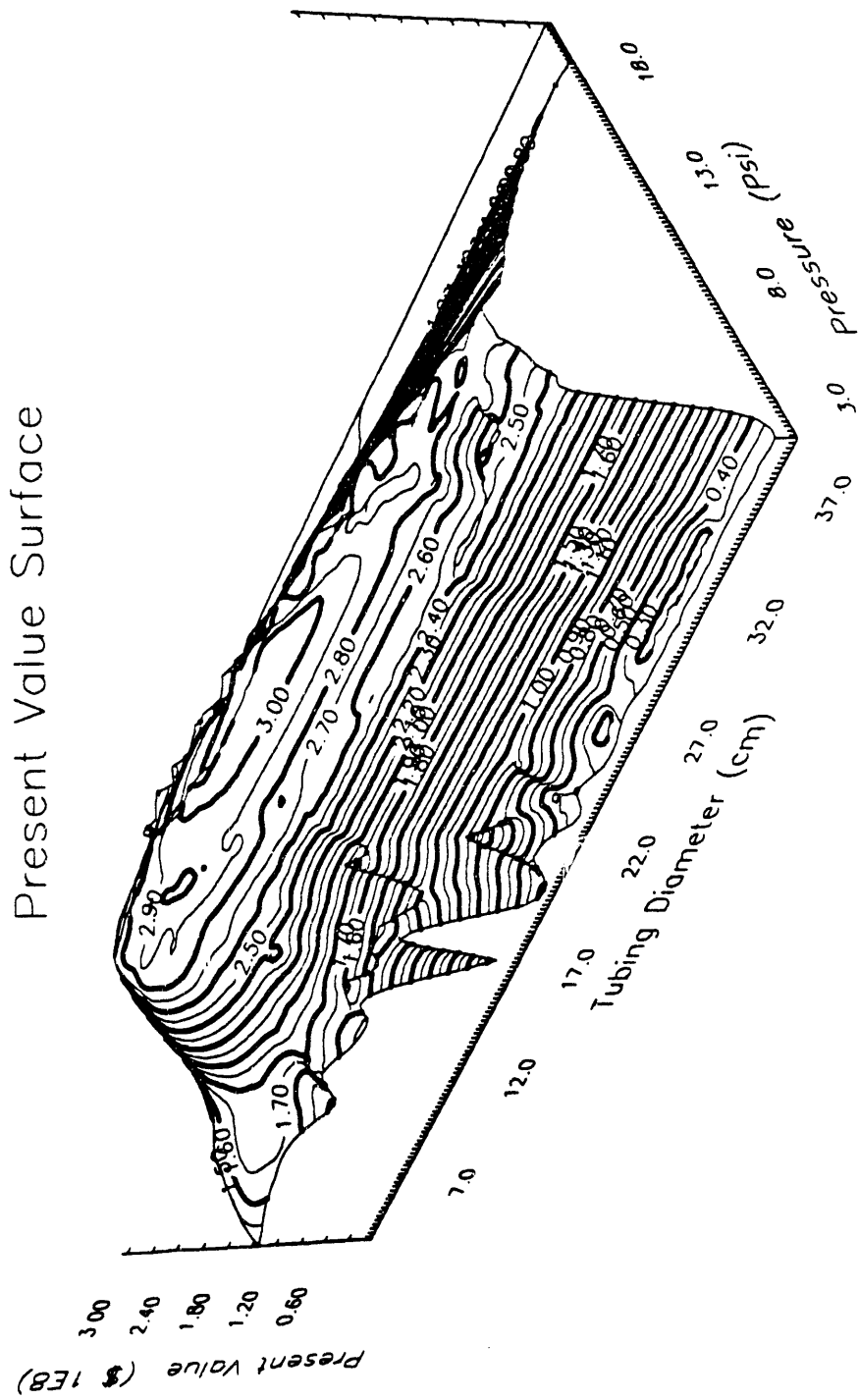


Figure 6.3: Present Value Surface for the Aziz, Govier and Fogarasi [1972] Correlation

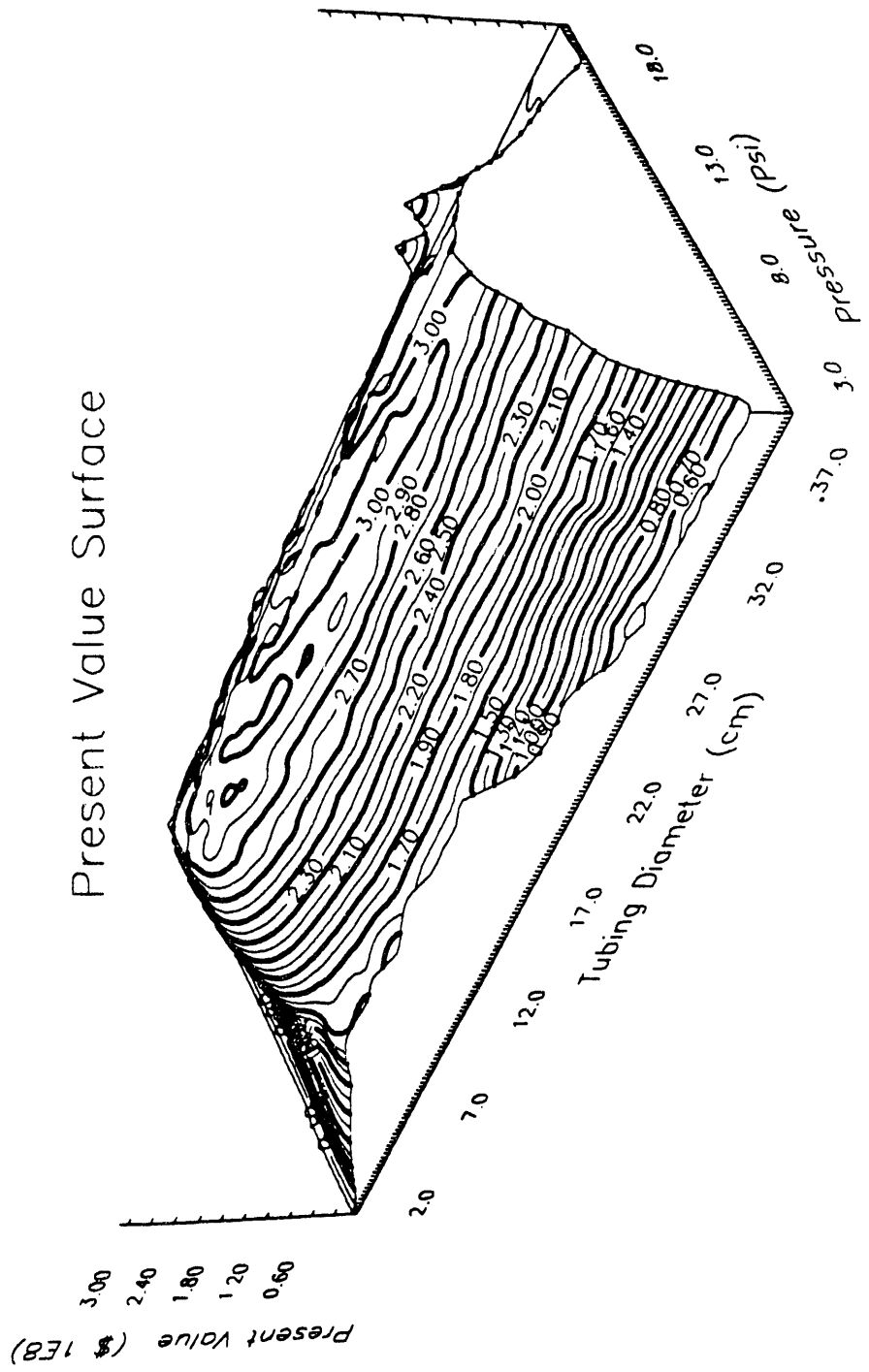


Figure 6.4: Present Value Surface for the Hagedorn and Brown [1964] Correlation

Optimum Tubing Diameters

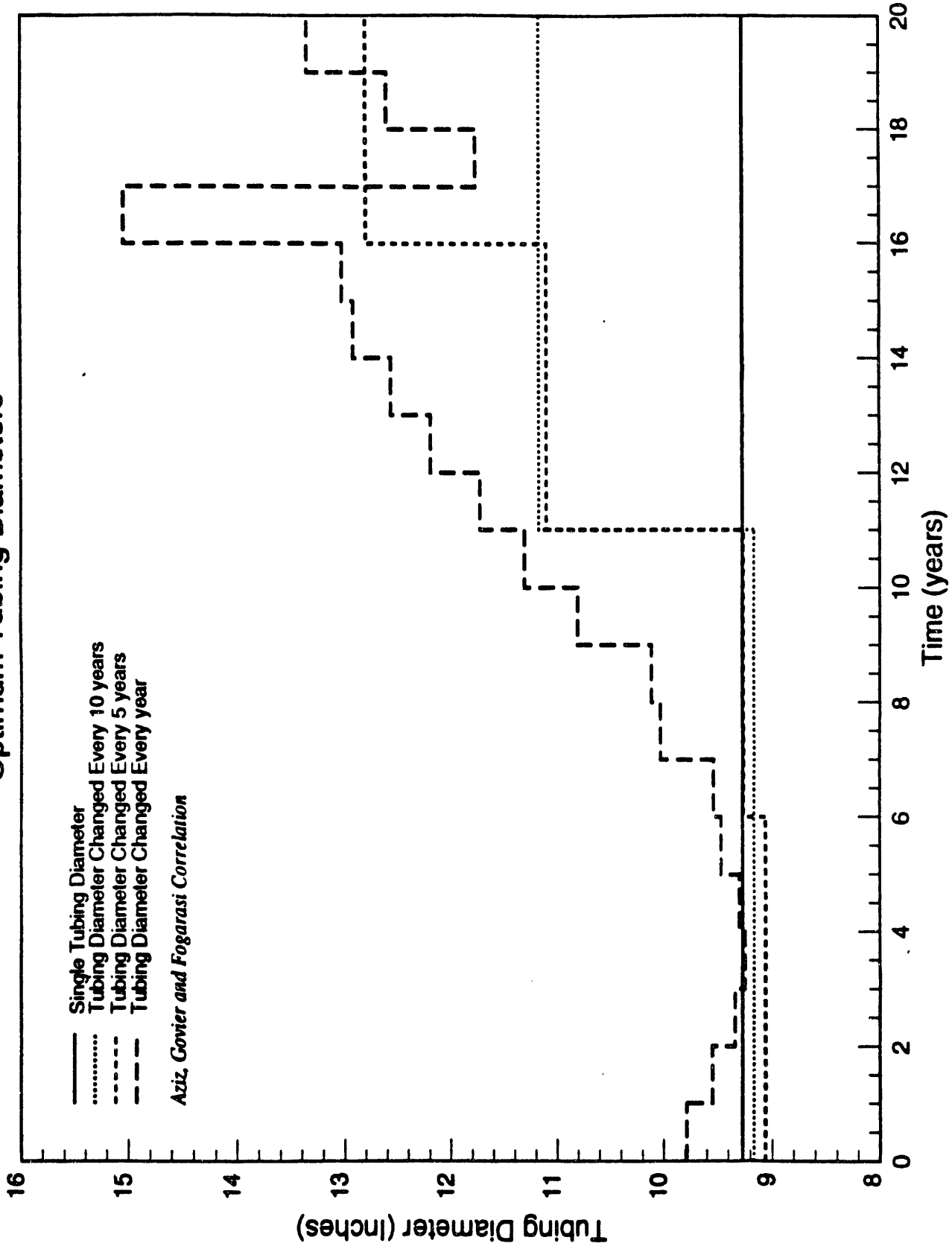


Figure 6.5 Optimum Tubing Diameters as a Function of Time

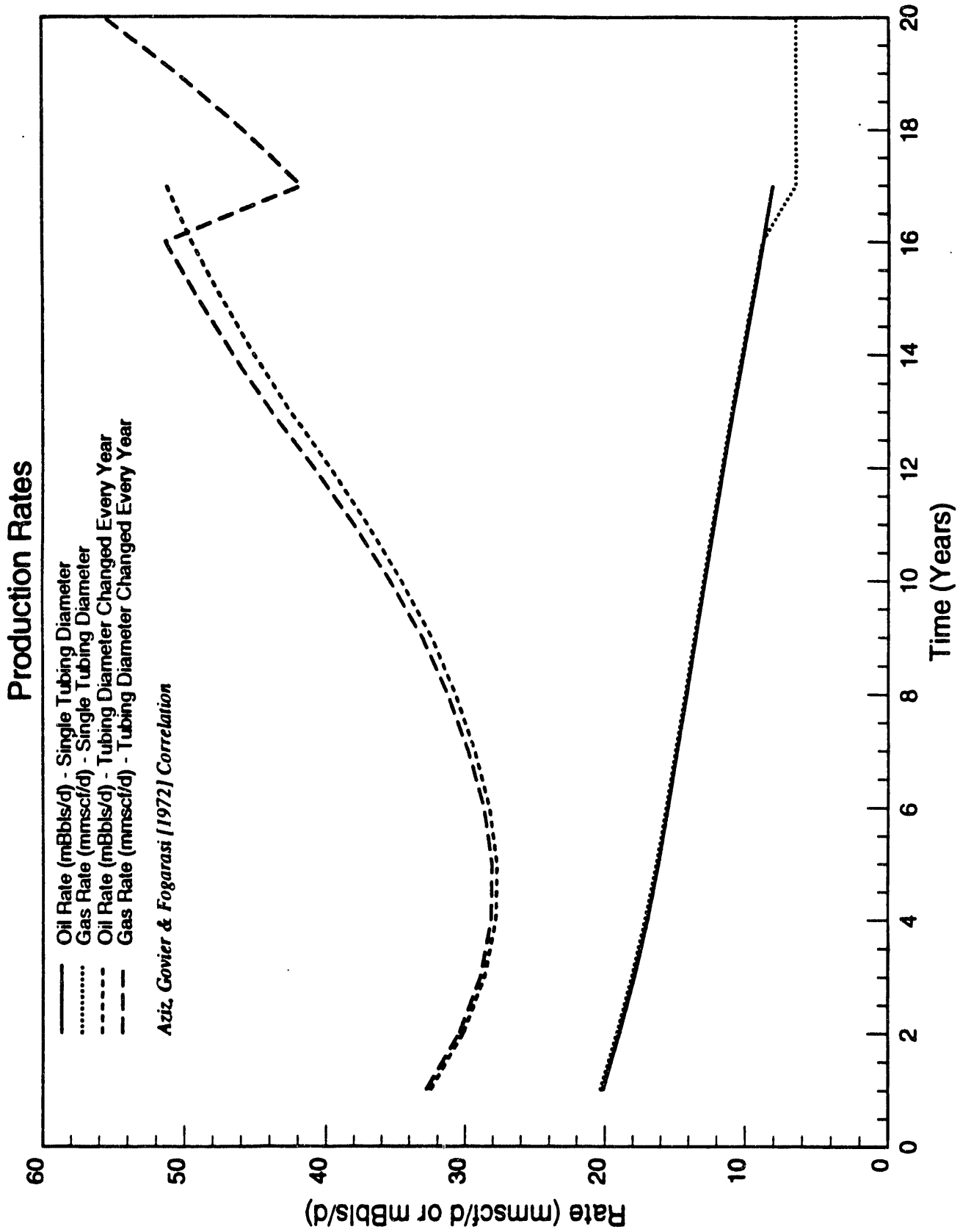


Figure 6.6 Production Rates of Oil & Gas for Tubing Optimizations

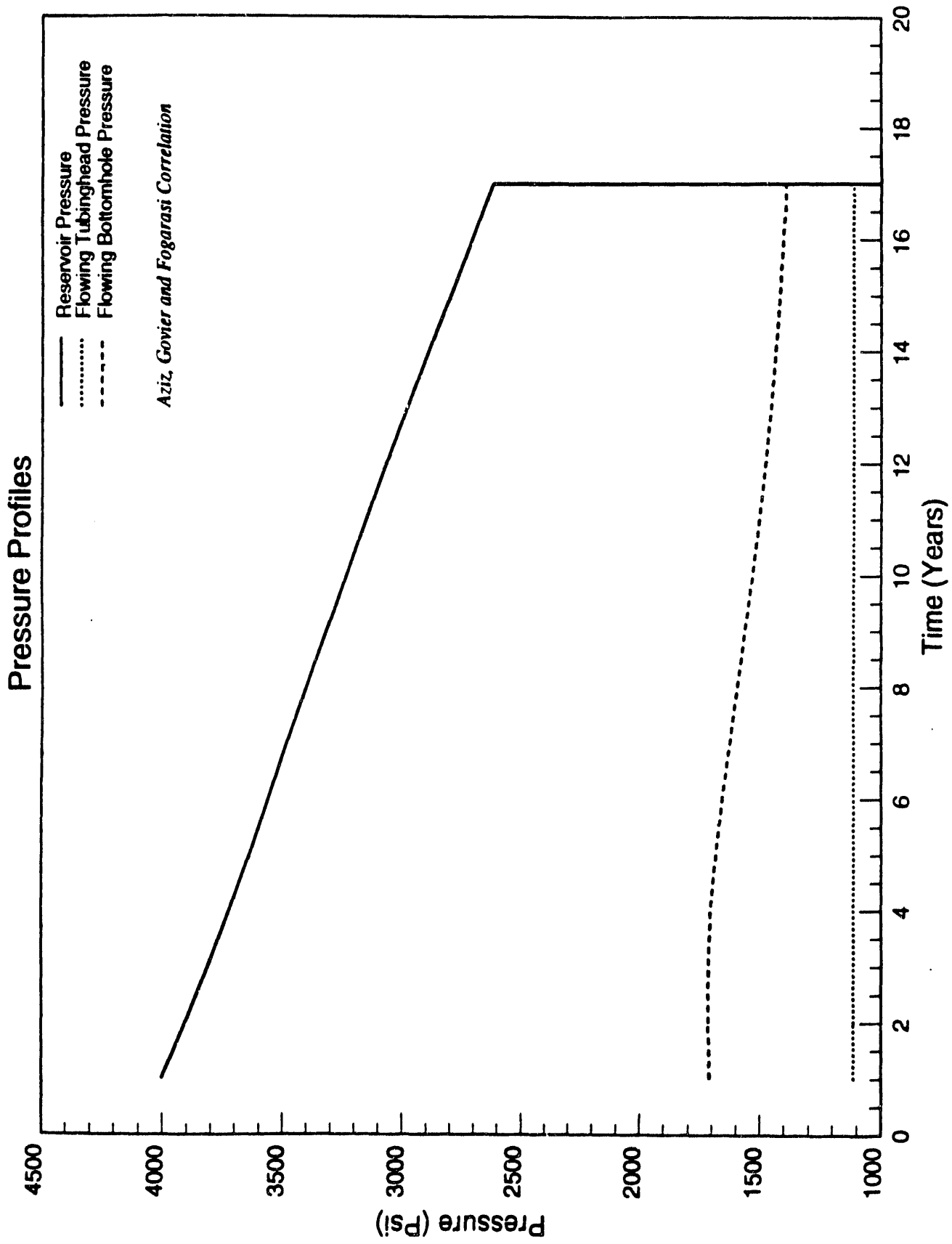


Figure 6.7 Pressure Profile For Single Tubing Diameter Optimization

Pressure = 9000 KPa

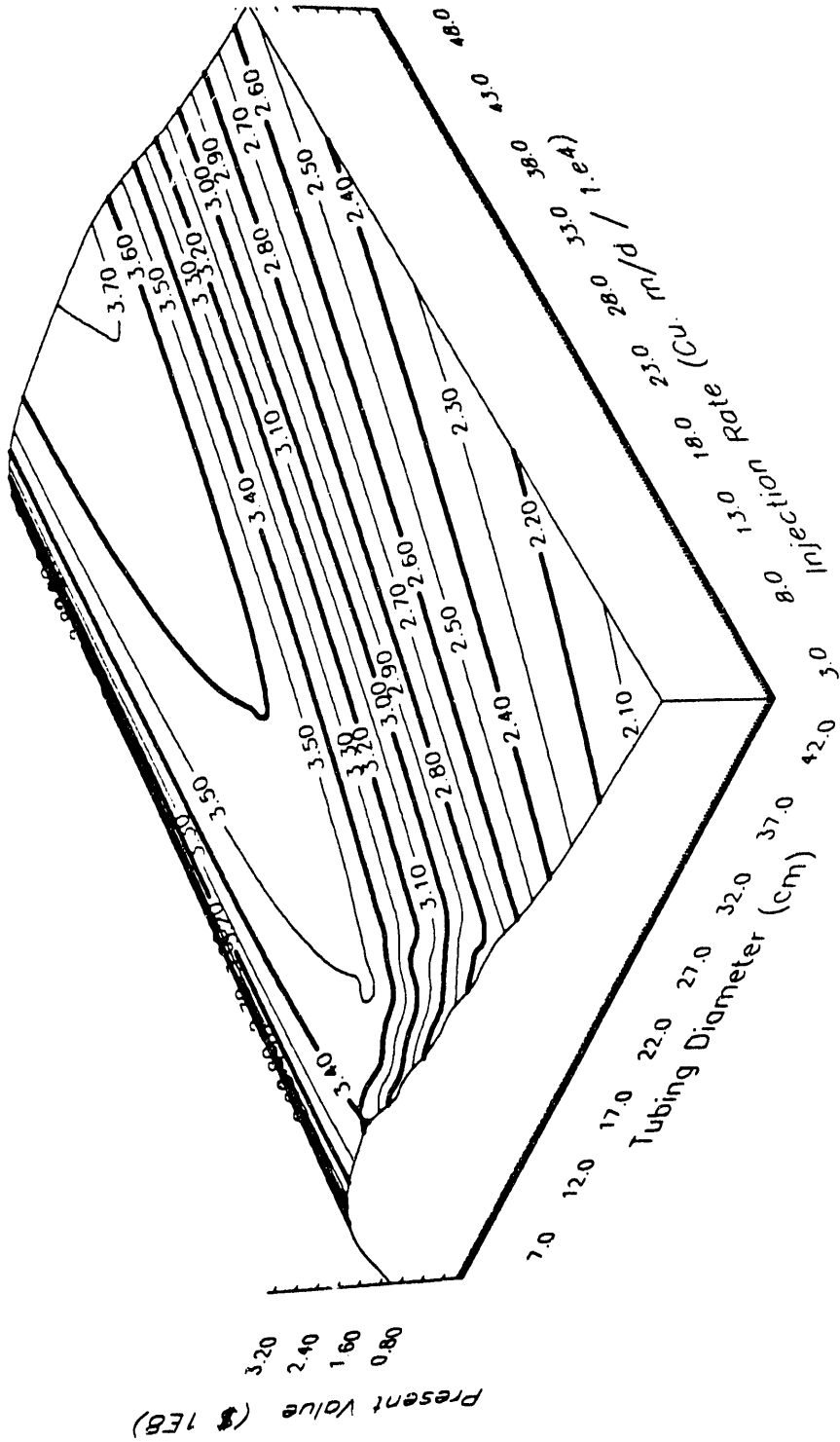


Figure 6.9 Present Value Surface for Gas Injection with the Wellhead Pressure Fixed at 9000 KPa

Pressure = 11000 KPa

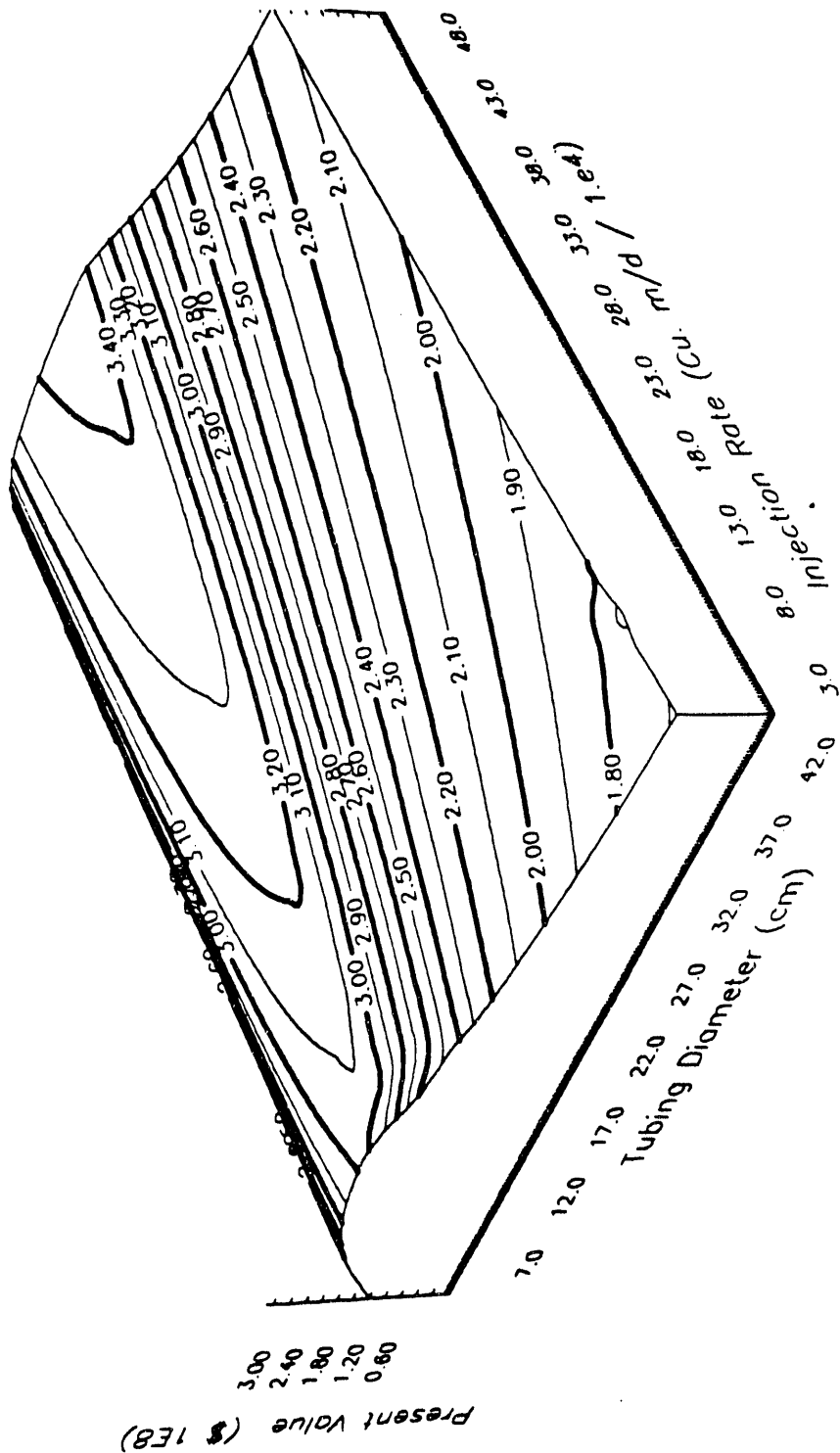


Figure 6.10 Present Value Surface for Gas Injection with the Wellhead Pressure Fixed at 11000 KPa

Tubing Diameter = 15.0 cm.

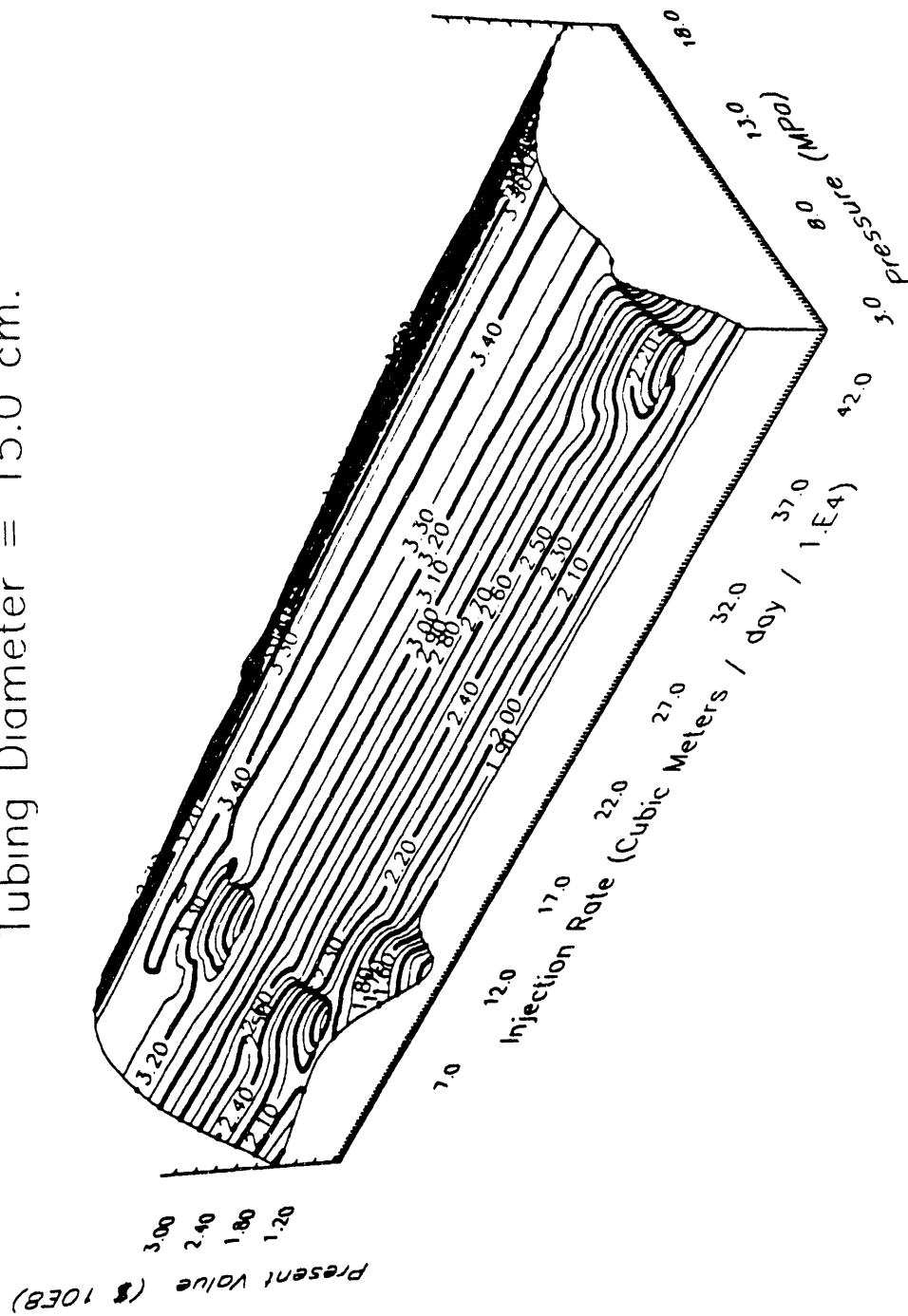


Figure 6.1.1 Present Value Surface for Gas Injection with the Tubing Diameter Fixed at 5.9 inches.

Tubing Diameter = 10.0 cm.

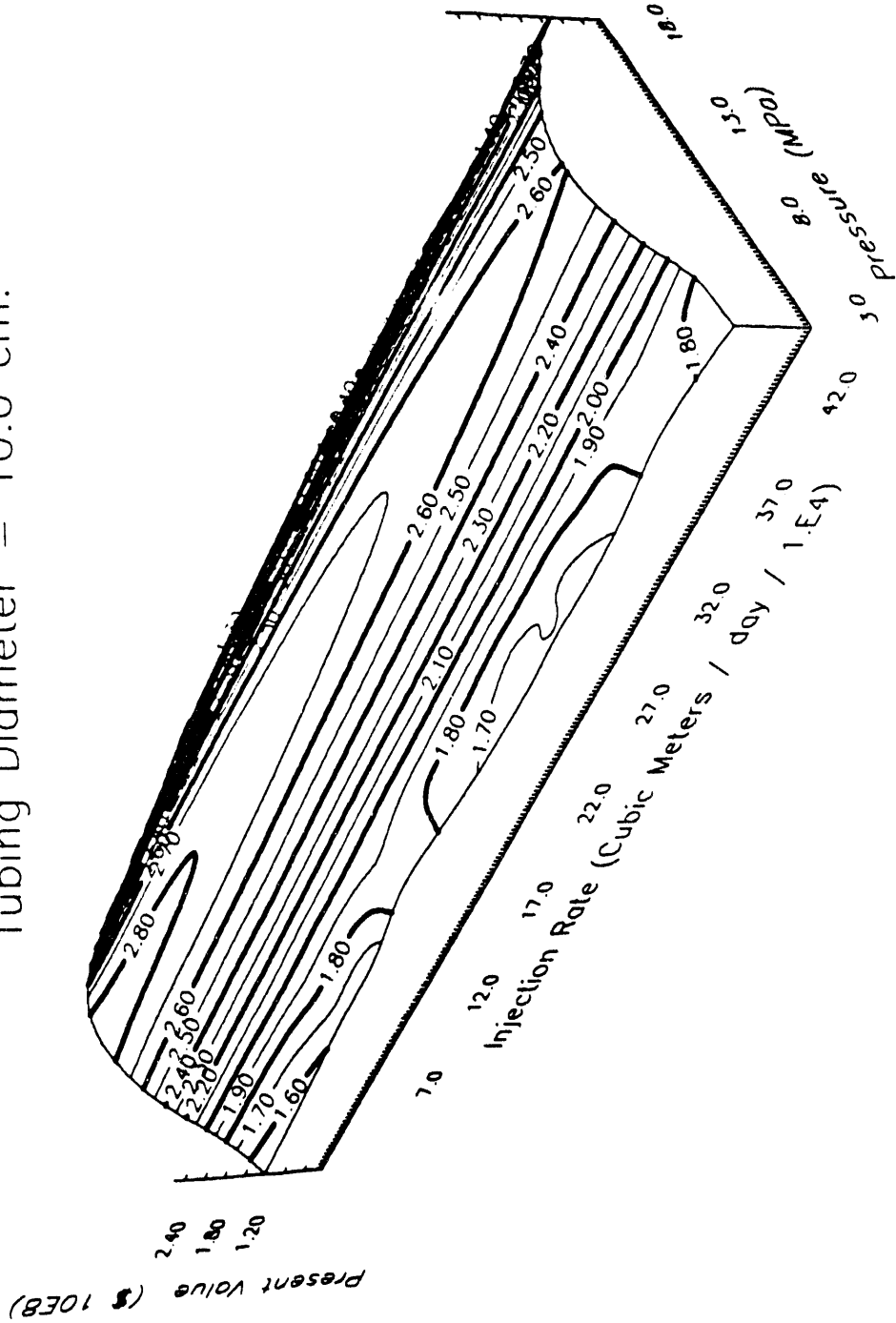


Figure 6.12 Present Value Surface for Gas Injection with the Tubing Diameter Fixed at 3.9 inches

Tubing Diameter = 20.0 cm.

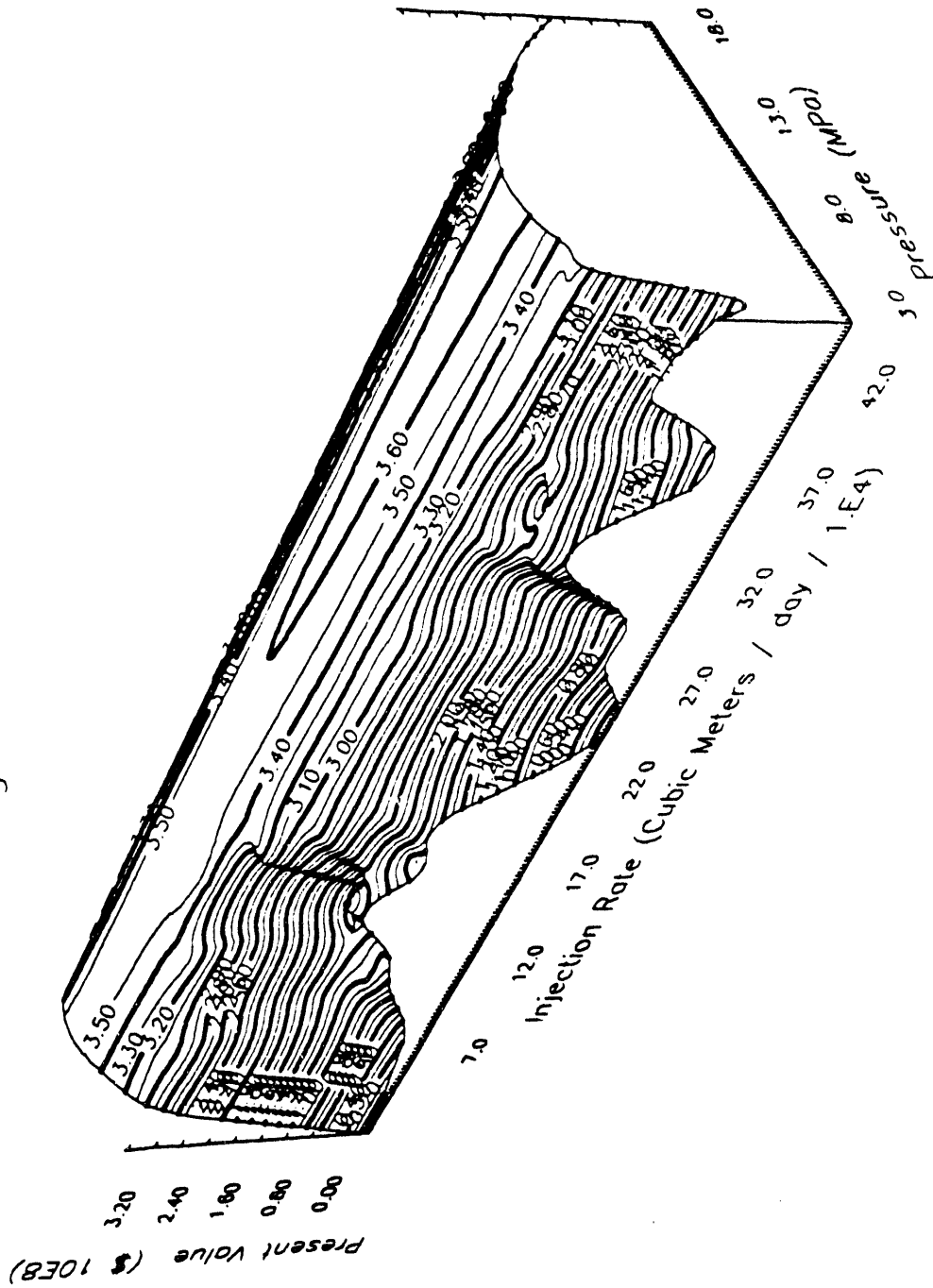


Figure 6.13 Present Value Surface for Gas Injection with the Tubing Diameter Fixed at 7.87 inches

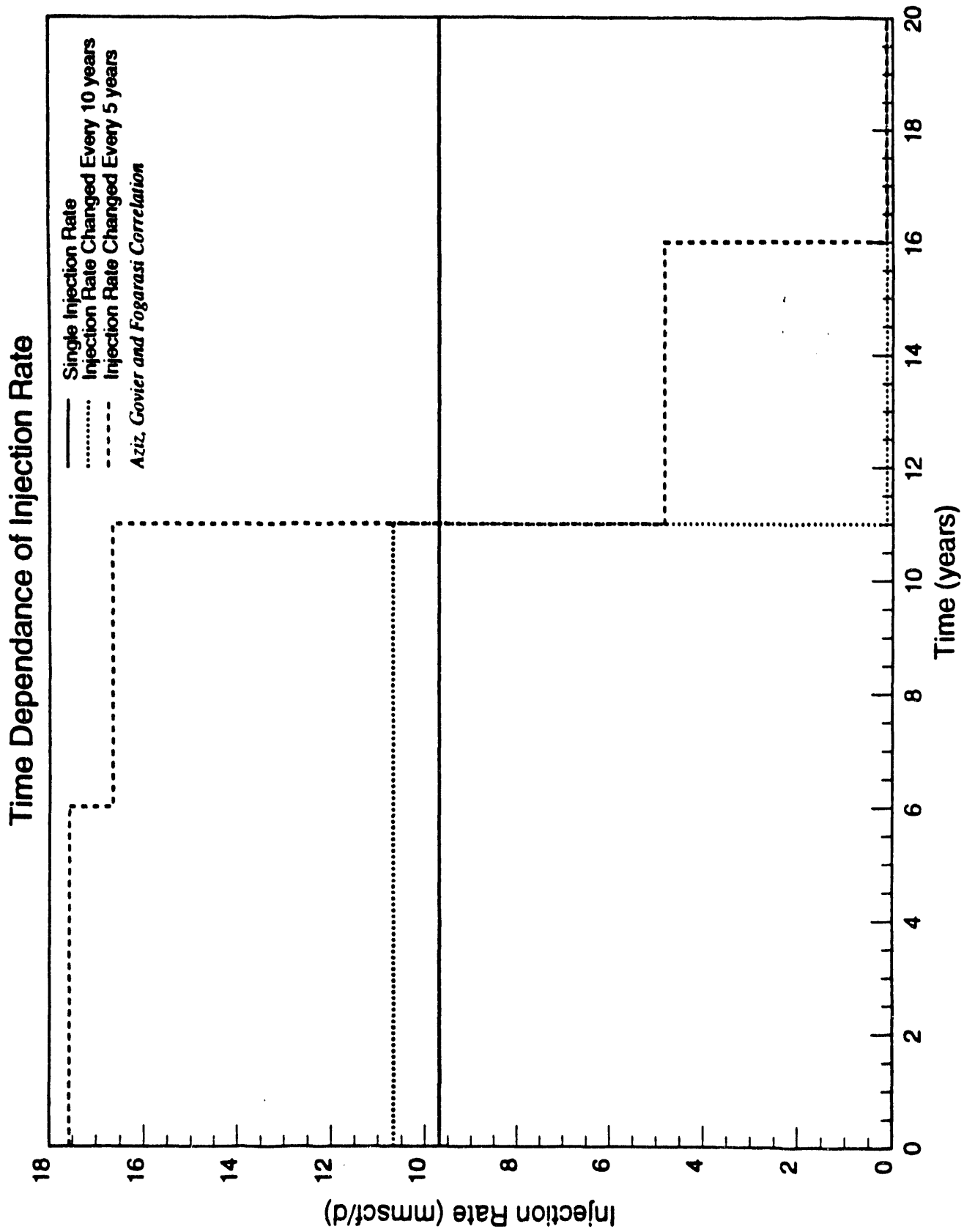


Figure 6.14 Optimum Gas Injection Rates as a Function of Time

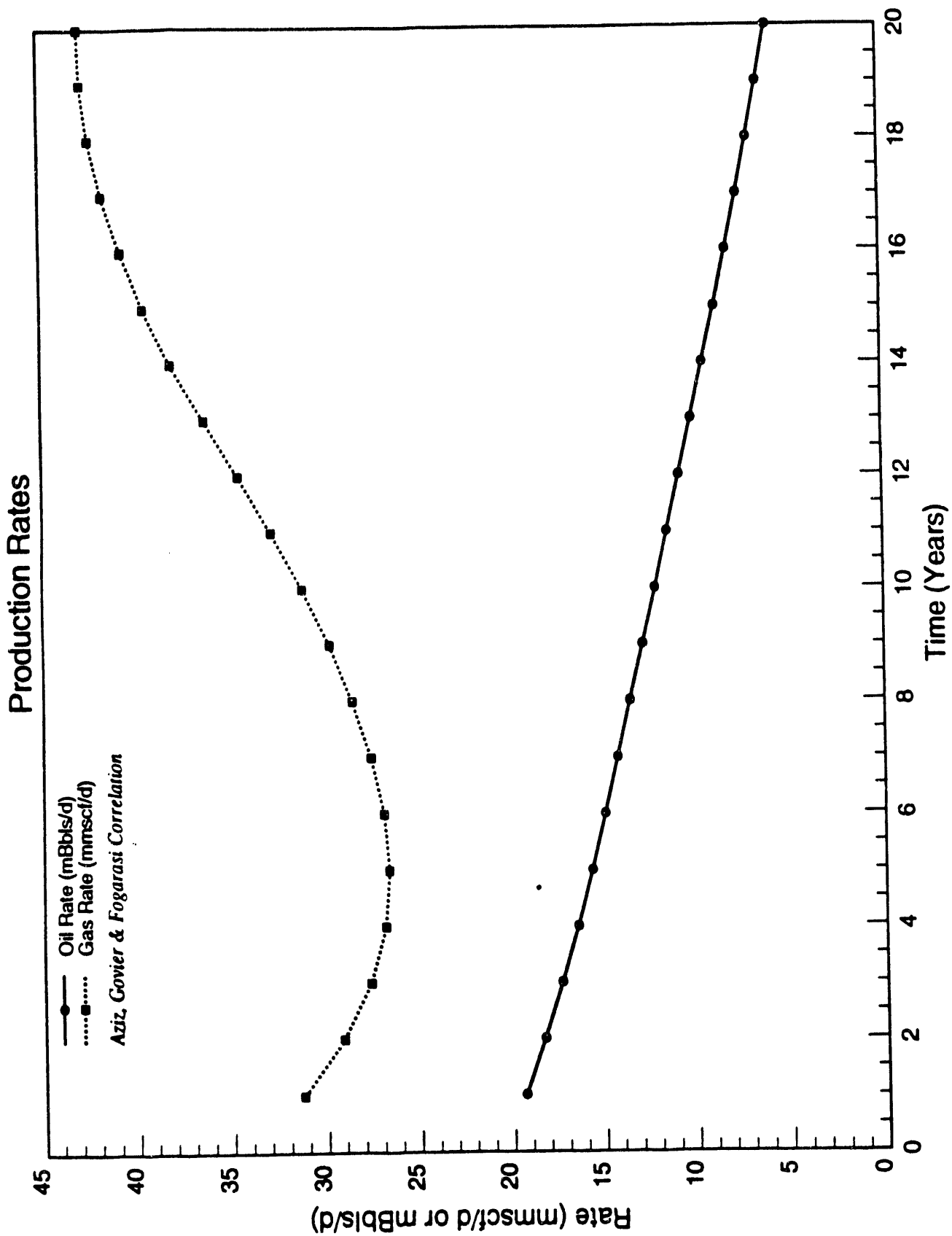


Figure 6.15 Oil and Gas Production Rates for Gas Injection Case

Pressure Profiles - Single Injection Rate

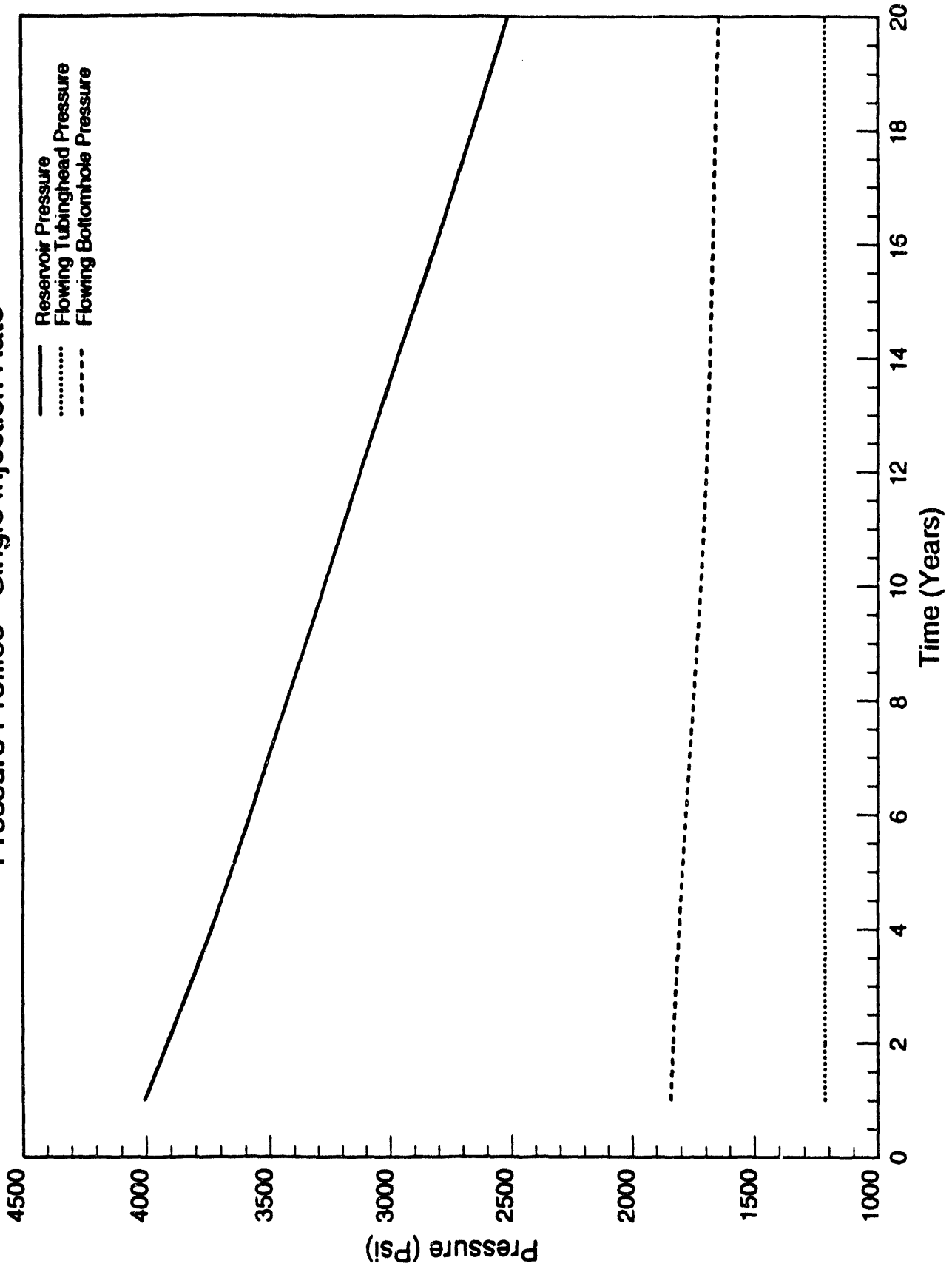


Figure 6.16 Pressure Profiles for Single Gas Injection Rate Optimization

7. Conclusions and Ideas for Future Projects

7.1 Conclusions

This study has demonstrated that nonlinear optimization techniques can be successfully applied to hydrocarbon production systems.

Specifically this study shows that

- The nonlinear optimization techniques can be applied to production systems with decision variables that change with time.
- The present value surfaces are nonsmooth functions of the decision variables (tubing diameter, separator pressure, gas injection rate). The nonlinear optimization algorithms that do not use gradients of the objective functions like the polytope method are the more suitable algorithms.
- The best strategy for optimization of the production system was found to be to use the polytope algorithm to find the local area of the maximum point, and then to use a Newton based technique such as the BFGS algorithm (Broyden [1970], Fletcher [1970], Goldfarb [1970] and Shanno [1970]) to find the "exact" location of the maximum.
- The sensitivity of the decision variables to the objective function is a cause for concern, specially for problems with time dependent variables. For example, in this study the objective function -- the Present Value -- is weighted towards production in early years. The result is that production towards the end of the life of the reservoir has very little effect on the total present value. The objective surface is relatively flat, and therefore false convergence may be assumed by the algorithm away from the actual maximum point.

7.2 Future Work

Genetic algorithms and simulated annealing algorithms are being increasingly used in various engineering fields for optimization. Goldberg [1989], Holland [1975] and Katragadda [1991] have used genetic algorithms to optimize different problems. Readers are referred to Goldberg [1989] for a very good introduction to genetic algorithms. Katragadda [1991] used genetic algorithms to optimize a highly nonlinear problem -- the trajectory of a spacecraft on a mission from Earth to Mars.

Including the cost of production into the economic analysis by switching the objective function to use net present value (NPV), is highly desirable. For example when

considering the gas lift system, the use of NPV would provide a very different objective surface. The optimization would then be able to include the tubing diameter as one of the decision variable.

Another very interesting problem to which the nonlinear optimization algorithms can be applied to is a plunger lift system. Plunger lift is being used increasingly in industry as a method of dewatering gas wells, and as an artificial lift system for high gas - oil ratio wells that are unable to flow to the surface. The optimization of the plunger cycle time, as well as the tubing diameters, and other various decision variables would pose a challenging problem.

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APPENDIX

Source Code For the Well Model

Wellmodel.For

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```

*****
**** Program Simplex
**** Authors Niranjana Ravindran, James Carroll and Gunnar Botthne
**** Date June, 1990
**** Function Driver for Well Model. Set for Time Dependant
**** Optimization of Tubing Diameters and Gas Injection
*****

```

```

Program Simplex
Integer N, IDO, P
Parameter (N=5)
Integer MAXFCN, K, IPARAM(7)
Real*8 FTOL, FVALUE, S, X(N), XGUESS(N)
Real*8 RPARAM(7), XSCALE(N), CPU1, CPU2, CPU
Real*8 A(N), B(N), SS(N), F
Character*100 ZIN, ZINI, ZOUT1, ZOUT2, ZOUT3, ZOUT4
External FCN,DUMPOL,DUMINF,DU4INF

```

```

*----- Start Execution

Print *, 'Name of file for input data - GMS?'
Read 5100, ZIN
Print *, 'Name of file for input Start Point?'
Read 5100, ZINI
Print *, 'Name of file for general output data?'
Read 5100, ZOUT1
Print *, 'Name of file for graph output data?'
Read 5100, ZOUT2
Print *, 'Name of file for triag output data?'
Read 5100, ZOUT3
Print *, 'Name of file for Plot output data?'
Read 5100, ZOUT4

Open (Unit=2,File=ZIN)
Open (Unit=1,File=ZINI)
Open (Unit=3,File=ZOUT1)
Open (Unit=4,File=ZOUT2)
Open (Unit=5,File=ZOUT3)
Open (Unit=8,File=ZOUT4)

```

```

C----- Unit 20, File Nspace is reserved for writing N-dimensional
C----- results.
C----- Unit 25, is reserved for reading *in* the top corner, and
C----- bottom corner of the N-space.
C----- Read the Initial guess, and the step size for the Polytope.

```

```

do I=1,N
  read(1,*) XGUESS(I)
  X(I) = XGUESS(I)
enddo
SO=5
Call GMSINP
Call GMSECHO

```

```

C----- Time Taken For Calculations.
      Call GetCpu(Cpu1)
C----- Convergence Tollerance.
      FTOL = 9.999999999999E-13

```

```

C----- Max No of Calls to GMSBODY
      MAXFCN = 1000000
C----- Goto 10
C----- Goto 20
C----- Call Polytope Algorithm. form IMSL
      Call DUMPOL(FCN,N,XGUESS,S,FTOL,MAXFCN,X,FVALUE)
      Call FCN(N,X,F)
      Write(6,*) 'Optimum - Simplex1', (X(K),K=1,N),-F
      Write(5,*) 'Optimum - Simplex1', (X(K),K=1,N),-F
      Write(8,*) 'Optimum - Simplex1', (X(K),K=1,N),-F
C----- Goto 30
C----- Set up for Newton Algorithm.
10    do K=1,N
      XGUESS(K) = X(K)
      XSCALE(K) = 1.0d0
    enddo
      FSCALE = 1.0
      Call DU4INF(IPARAM,RPARAM)
      IPARAM(3) = 1000.
      IPARAM(4) = 4000.
      IPARAM(5) = 4000.
      RPARAM(1) = RPARAM(4)
      RPARAM(2) = RPARAM(4)
      RPARAM(3) = RPARAM(4)
      RPARAM(5) = RPARAM(4)
      Write(5,*) (IPARAM(K),K=1,7)
      Write(5,*) (RPARAM(K),K=1,7)
C----- Call Modified Newton Algorithm
      Call DUMINF(FCN, N, XGUESS, XSCALE, FSCALE, IPARAM,
      * RPARAM, X, FVALUE)
      Call FCN(N,X,F)
      Write(6,*) 'Optimum Modnewt', (X(K),K=1,N),-F
      Write(5,*) 'Optimum Modnewt', (X(K),K=1,N),-F
      Write(8,*) 'Optimum Modnewt', (X(K),K=1,N),-F
C----- Goto 30
C----- Call DGGUES, the Point Generator.
      DATA IDO /0/
20    Open (Unit=25, File='Points')
      Open (Unit=20, File='Nspace')
      Do I=1,N

```

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```
Read(25,*)A(I),B(I)
End do
Read(25,*)P
Close (Unit=25)

Do I=1,F
  Call DGGUES(N, A, B, P, IDO, SS)
  Call FCN(N, SS, F)
  F = F / 1.0d08
  Write(20,*)SS(1)/1000.0, SS(2)/1000.0, -F
Enddo
Close (Unit=20)
Goto 40

C----- Calculate Time Taken
30 Call PLOTOUT(Cpu)

  Call Getcpu(Cpu2)
  Cpu = Cpu2 - Cpu1

  Write(6,*)'Time',Cpu
  Write(5,*)'Time',Cpu
  Write(8,*)'Time',Cpu

5100 Format (A)

40 Close (Unit=2)
   Close (Unit=3)
   Close (Unit=4)
   Close (Unit=5)
   Close (Unit=8)

Stop
End

.....

Subroutine FCN (N,X,F)
Integer N
Parameter (N3=5)
Double Precision Pass(N3), Pass4
Real*8 X(N),F
Common /Pass/ Pass, Pass4

Do I = 1, N
  Pass(I) = X(I)
  Pass(I) = Pass(I) / 1.00d5
End do
Pass(N3) = X(N3)

Pass(1-4) tubing diameter1.
Pass(3) Pressure
do I=1,N
  If(X(i)-1e-0.0) then
    F=0.0
  Return
Endif
Enddo

C Write(6,*)'FCN1',(Pass(I),I=1,N),-Pass4/1.0e8
Call GMSBODY
Write(6,*)'FCN2',(Pass(I),I=1,N),-Pass4/1.0e8
Write(8,*)'FCN2',(Pass(I)/1000.,I=1,N),-Pass4/1.0e8

F = Pass4
Return
End

.....
Subroutine GMSECON
.....
  Author James Carroll
  Date November, 1990
  Function This subroutine determines the objective criterion of
  the well model. The objective criterion is the
  present value of the production stream.
  Subroutine GMSECON(I)
.....
----- VARIABLES AND CONSTANTS
Implicit Double Precision (A-Z)

Integer N1, N2, IVNMEL, NWELLS, IERR, IEXE, IHC, IPRT, IUNIN,
  IWCTR, K, NWELL, NMT, NSTEP, I
Character ZJOBID*60, ZC(8)*6
Parameter (N1 = 100, N2 = 500)

Dimension TPMMIN(N1), TRTEFM(N1), TRTEFT(N1), TSKN(N1), TTIM(N1),
  VGASPI(0:N2), VGOR(0:N2), VOILP(0:N2), VPRSR(0:N2),
  VPRSMF(0:N2), VPRSMH(0:N2), VRTEG(0:N2), VRTEO(0:N2),
  VTIME(0:N2), IVNMEL(0:N2), NWELLS(N1), NPV1(0:N2),
  Common /TRANS1/ TTIM, NWELLS, TRTEFM, TRTEFT, TPMMIN, TSKN, RADM,
  DELTIM, XMXTIM, HCPV, IHC, IUNIN, IPRT, IEXE, NMT, IERR, NSTEP
Common /TRANS2/ CI, C2, C3, C4, C5, C6, C7, C8, C9
Common /TRANS3/ ZC, ZJOBID
Common /TRANS4/ VGASF, VGOR, VOILP, VPRSR, VPRSMF, VPRSMH, VRTEG,
  VRTEO, VTIME, IWCTR, NWELL, OILTI, GASTI, IVNMEL, K
Common /FINANCE/ INFRATE, DISRATE, OILPRIC, GASPRIC
Common /RESULTS/ NPV, NPV1

IF(I.EQ.1)THEN
  NSTEP = IDINT(DNINT(XMXTIM/DELTIM))
  NPV = 0.
  DFEFF = (1+DISRATE) ** (DELTIM/365)
  DFEFF = (1+DISRATE) ** (DELTIM/2/365)
  IFEFF = (1+INFRATE) ** (DELTIM/365)
  IFACTOR = (1+INFRATE) ** (DELTIM/2/365)
ENDIF

Do 10 I = 1, NSTEP
  GASPRO = VRTEG(I) * IVNMEL(I) * DELTIM
  GASREV = GASPRO * GASPRIC * IFACTOR
  OILPRO = VRTEO(I) * IVNMEL(I) * DELTIM
  OILREV = OILPRO * OILPRIC * IFACTOR
  TOTREV = GASREV + OILREV
  NPV = NPV + TOTREV / DFACTOR
  NPV1(I) = NPV
  IFACTOR = IFACTOR * IFEFF
  DFACTOR = DFACTOR * DFEFF
  10 Continue
-----
Return
End
```

Wellmodel.For

```

.....
**** Subroutine GMSINP
**** Author Gunnar Borthme (expanded by James Carroll)
**** Date April, 1986
**** Function This subroutine reads the input file of the well model.
**** Subroutine GMSINP
.....

```

DESCRIPTION OF INPUT DATA

```

-----
**** FORMAT : TEXT STRING (1 LINE)
1. JOBID : JOB IDENTIFICATION

-----
**** FORMAT : 4 INTEGERS (1 LINE)
1. IHC : HYDROCARBON TYPE
      = 0 : GAS CONDENSATE
      = 1 : OIL

2. IUNIN : UNITS IDENTIFIER FOR INPUT DATA
      = 0 : METRIC UNITS
      = 1 : OIL FIELD UNITS

3. IPRT : PRINT OPTION
      = 0 : TABLES OF RESULTS ONLY
      = 1 : * ECHO OF INPUT DATA
      = 2 : * ITERATION REPORT
      = 3 : * RESULTS PRINTED EACH TIMESTEP
      = 4 : * A MESSAGE FROM EACH ROUTINE

4. IEXE : EXECUTION MODE
      = 0 : MATERIAL BALANCE ONLY
      = 1 : MATERIAL BALANCE AND IPR
      = 2 : MATERIAL BALANCE, IPR AND TUBING

```

```

**** NOTE : USE ONLY THE UNIT SYSTEM
          CHOSEN WITH IUNIN

```

```

-----
**** FORMAT : 6 DOUBLEPRECISION VARIABLES (1 LINE)
1. DELTIM : TIMESTEP LENGTH ..... YEARS YEARS
2. XHATIM : LENGTH OF SIMULATION ..... YEARS YEARS
3. HCPV : HYDROCARBON PORE VOLUME ..... M3 BBL
4. PORI : INITIAL POROSITY ..... (FRACTION)
5. SATWI : INITIAL WATER SATURATION ..... (FRACTION)
6. CHFF : FORMATION COMPRESSIBILITY ..... 1/KPA 1/PSI

```

```

-----
**** FORMAT : 6 DOUBLEPRECISION VARIABLES (1 LINE)
1. PRM : PERMEABILITY ..... UM2 MD
2. THK : RESERVOIR THICKNESS ..... M FT
3. RADW : WELLBORE RADIUS ..... M FT
4. DSKN : NON-DARCY FLOW COEFFICIENT
      (RATE DEPENDENT SKIN TERM)
      ** IF IHC=0 (GAS) ..... D/SM3 D/SCF
      ** IF IHC=1 (OIL) ..... D/SM3 D/STB
5. DPINT : PRESSURE INCREMENT IN STIMPSON-
      INTEGRATION, IPR ROUTINE ..... KPA PSI

```

```

-----
**** FORMAT : 5 DOUBLEPRECISION VARIABLES (1 LINE)
1. API : SPECIFIC GRAVITY OF OIL ..... DEGREES
2. GRVG : SPECIFIC GRAVITY OF GAS ..... FRACTION
3. THF : TEMPERATURE AT BOTTOMHOLE ..... C F
4. TWH : TEMPERATURE AT WELLHEAD ..... C F
5. SIGMAO : OIL/GAS INTERFACIAL TENSION ..... N/M 10m/s2

-----
**** FORMAT : 4 DOUBLEPRECISION VARIABLES (1 LINE)
1. CORR : CORRELATION NUMBER ..... INTEGER
2. DIAM : DIAMETER OF TUBING ..... M FT

```

```

3. LENGTH : LENGTH OF VERTICAL TUBING ..... M FT
4. AROUHF : RELATIVE ROUGHNESS OF TUBING ..... M FT

```

```

-----
**** FORMAT : 4 DOUBLEPRECISION VARIABLES (1 LINE)
1. INFRATE : INFLATION RATE ..... FRACTION
2. DISRATE : DISCOUNT RATE ..... FRACTION
3. OILPRIC : PRICE OF OIL ..... $/M3 $/BBL
4. GASPRIC : PRICE OF GAS ..... $/M3 $/MMSCF

```

```

-----
**** FORMAT : 4 DOUBLEPRECISION VARIABLES (1 LINE)
1. N2 : GAS FRACTION OF NITROGEN ..... FRACTION
2. CO2 : GAS FRACTION OF CARBON-DIOXIDE ..... FRACTION
3. H2S : GAS FRACTION OF HYDROGEN-SULFIDE ..... FRACTION
4. RSI : INITIAL SOLUTION GAS-OIL RATIO ..... M3/M3 SCF/BBL

```

```

-----
**** TABLE OF WELL CONTROL SPECIFICATIONS
**** FORMAT : 1 DOUBLEPRECISION + 1 INTEGER + 4 DOUBLEPRECISION
          ON EACH LINE
          (REPEAT LINES, END WITH -1)

```

```

1. TTIM : TIME FOR WELL CONTROL ..... YEARS YEARS
2. NMELLS : NUMBER OF WELLS ..... YEARS
   ** IF IHC=0 (GAS) ..... SM3/D SCF/D
   ** IF IHC=1 (OIL) ..... SM3/D STB/D
3. TRTEFT : FIELD TARGET PRODUCTION RATE
   ** IF IHC=0 (GAS) ..... SM3/D SCF/D
   ** IF IHC=1 (OIL) ..... SM3/D STB/D
4. TDMIN : MINIMUM WELLHEAD PRESSURE ..... KPA PSIA
5. TSKN : TOTAL SKIN (EXCEPT RATE DEPENDENT) ..... DIMENSIONLESS
** NOTE : - TTIM MUST INCREASE DOWN THE COLUMN.
          - TO END THE TABLE, PUT: -1 ON THE NEXT LINE.

```

```

-----
**** TABLE OF PVT DATA FOR THE OIL PHASE
**** FORMAT : 5 DOUBLEPRECISION VARIABLES ON EACH LINE
          (REPEAT LINES, END WITH -1)

```

```

1. TPRS : PRESSURE FOR PVT DATA ..... KPA PSIA
2. TVISO : OIL VISCOSITY ..... PA S CP
3. TGOBS : SOLUTION GAS/OIL RATIO,
          IN OIL PHASE ..... SM3/SM3 SCF/BBL
4. TDENRO : DENSITY RATIO (GRAVITY RATIO),
          OIL-FROM-GAS / OIL-FROM-OIL ..... DIMENSIONLESS
5. TFFPO : OIL FORMATION VOLUME FACTOR ..... (RES.VOL/STD.VOL)
** NOTE : - TPRS MUST INCREASE DOWN THE COLUMN.
          - TO END THE TABLE, PUT: -1 ON THE NEXT LINE.

```

```

-----
**** TABLE OF PVT DATA FOR THE GAS PHASE
**** FORMAT : 4 DOUBLEPRECISION VARIABLES ON EACH LINE
          (REPEAT LINES, END WITH -1)

```

```

** NOTE : SAME PRESSURES AS ABOVE
1. TVISG : GAS VISCOSITY ..... PA S CP
2. TUGRS : SOLUTION OIL/GAS RATIO,
          IN GAS PHASE ..... SM3/SM3 STB/MMSCF
3. TDENRG : DENSITY RATIO (GRAVITY RATIO),
          GAS-FROM-OIL / GAS-FROM-GAS ..... DIMENSIONLESS
4. TFFVG : GAS FORMATION VOLUME FACTOR ..... (RES.VOL/STD.VOL)
** NOTE : TO END THE TABLE, PUT: -1 ON THE NEXT LINE

```

```

-----
**** TABLE OF RELATIVE PERMEABILITY VS. SATURATION
**** FORMAT : 1 DOUBLEPRECISION VARIABLES ON EACH LINE
          (REPEAT LINES, END WITH -1)
1. TSATG : GAS SATURATION ..... (FRACTION)
2. TFRMO : RELATIVE PERMEABILITY TO OIL ..... (FRACTION)

```


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```
Call SKIP(2)
Read (2,*) PRM, THK, RADW, DSKN, DPINT
If (IUNIN.EQ.1) Then
  PRM = PRM * C5
  THK = THK * C3
  RADW = RADW * C3
If (IHC.EQ.0) DSKN = DSKN / C8
If (IHC.EQ.1) DSKN = DSKN / C6
DPINT = DPINT * C4
End If
Call TEST(PRM,0D+0,1000D+0,'PRM',IERR)
Call TEST(THK,0D+0,1000D+0,'THK',IERR)
Call TEST(RADW,0D+0,3D+1,'RADW',IERR)
Call TEST(DPINT,10D+0,1000D+0,'DPINT',IERR)
*----- READ DATA LINE 5, 6, 7, & 8
Call SKIP(2)
Read (2,*) API, GRVG, TMF, TMH, SIGMAO
Call TEST(API,1D+0,1D+2,'API',IERR)
Call TEST(GRVG,0.5D+0,1D+1,'GRVG',IERR)
Call TEST(TMf,0D+0,0.25D+0,'TMF',IERR)
Call TEST(TMh,0D+0,0.25D+0,'TMH',IERR)
Call TEST(SIGMAO,0D+0,1D+4,'SIGMA',IERR)
If (IUNIN.EQ.1) Then
  TMF = TMF * C9
  TMH = TMH * C9
  SIGMAO = SIGMAO * 14.60956181
End If
Call SKIP(2)
Read (2,*) CORR, DIAM, LENGTH, AROUGH, TSEP, PSEP
If (IUNIN.EQ.1) Then
  AROUGH = AROUGH * C3
  DIAM = DIAM * C3
  LENGTH = LENGTH * C3
  TSEP = TSEP * C9
  PSEP = PSEP * C4
End If
Call ITTEST(CORR,1,3,'CORR',IERR)
Call TEST(DIAM,0D+0,0.5D+0,'DIAM',IERR)
Call TEST(LENGTH,0.1D+01,0.1D+05,'LENGTH',IERR)
Call TEST(AROUGH,0D+0,1D+0,'AROUGH',IERR)
Call TEST(TSEP,0D+0,1D+3,'TSEP',IERR)
Call TEST(PSEP,0D+0,1D+5,'PSEP',IERR)
Call SKIP(2)
Read (2,*) INFRATE, DISRATE, OILPRIC, GASPRIC
Call TEST(INFRATE,0D+0,1D+0,'INFRATE',IERR)
Call TEST(DISRATE,0D+0,1D+0,'DISRATE',IERR)
Call TEST(OILPRIC,0D+0,1D+3,'OILPRIC',IERR)
Call TEST(GASPRIC,0D+0,1D+5,'GASPRIC',IERR)
If (IUNIN.EQ.1) THEN
  OILPRIC = OILPRIC * C4
  GASPRIC = GASPRIC / (C8 * 1000000.)
else
  GASPRIC = GASPRIC / 1D6
endif
Call SKIP(2)
Read (2,*) NITRO, CO2, H2S, RSI
Call TEST(NITRO,0D+0,1D+0,'NITRO',IERR)
Call TEST(CO2,0D+0,1D+0,'CO2',IERR)
Call TEST(H2S,0D+0,1D+0,'H2S',IERR)
Call TEST(RSI,0D+0,1D+3,'RSI',IERR)
If (IUNIN.EQ.1) Then
  RSI = RSI / 5.615
*----- READ AND TEST DATA TABLE 1
I = 0
10 Continue
I = I + 1
Call SKIP(2)
Read (2,*) X0
If (X0.GE.0.) Then
  Backspace (2)
Read (2,*) TTIM(I), NWELLS(I), TRTEFM(I), TRTEFT(I), TPCMIN(I),
  * TSKN(I)
  Note: Input time in years, internal time in days.
  TTIM(I) = TTIM(I) * 365
  NWT = I
  X1 = C8
  If (IHC.EQ.1) X1 = C6
  If (IUNIN.EQ.1) Then
    TRTEFM(I) = TRTEFM(I) * X1
    TRTEFT(I) = TRTEFT(I) * X1
    TPCMIN(I) = TPCMIN(I) * C4
  End If
  Call TEST(TTIM(I)/365,0D+0,400D+0,'TTIM',IERR)
  If (I.GT.1) Call TESTGE(TTIM(I-1)/365,'TTIM',IERR)
  Call ITTEST(NWELLS(I),1,500,'NWELLS',IERR)
  Call TEST(TRTEFM(I),0D+0,1D+7,'TRTEFM',IERR)
  Call TEST(TRTEFT(I),0D+0,2D+9,'TRTEFT',IERR)
  Call TEST(TPCMIN(I),0D+0,1D+5,'TPCMIN',IERR)
  Call TEST(TSKN(I),-1D+2,1D+2,'TSKN',IERR)
  Go To 10
End If
Call TEST(TTIM(I)/365,0D+0,0D+0,'TTIM(I)',IERR)
Call ITTEST(NWT,1,N1-1,'NWT' >= N1,'IERR)
*----- READ AND TEST DATA TABLE 2
I = 0
20 Continue
I = I + 1
Call SKIP(2)
Read (2,*) X0
If (X0.GE.0.) Then
  Backspace (2)
Read (2,*) TPRS(I), TVISO(I), TGOORS(I), TDENRO(I), TFWFO(I)
  NPVT = I
  If (IUNIN.EQ.1) Then
    TPRS(I) = TPRS(I) * C4
    TVISO(I) = TVISO(I) * C1
    TGOORS(I) = TGOORS(I) / C7
  End If
  Call TEST(TPRS(I),0D+0,5D+5,'TPRS',IERR)
  If (I.GT.1) Call TESTGE(TPRS(I-1),TPRS(I),'TPRS',IERR)
  Call TEST(TVISO(I),0D+0,1D+0,'TVISO',IERR)
  Call TEST(TGOORS(I),0D+0,5D+3,'TGOORS',IERR)
  Call TEST(TDENRO(I),0D+0,10D+0,'TDENRO',IERR)
  Call TEST(TFWFO(I),0D+0,10D+0,'TFWFO',IERR)
  Go To 20
End If
*----- READ AND TEST DATA TABLE 3
I = 0
```

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30 Continue
  I = I + 1
  Call SKIP(2)
  Read (2,*) X0
  If (X0.GE.0.) Then
    Backspace (2)
    Read (2,*) TVISG(I), TVGRS(I), TDENRG(I), TFVFG(I)
    TFVFG(I) = I / TFVFG(I)
    If (IUNIN.EQ.1) Then
      TVISG(I) = TVISG(I) * C1
      TVGRS(I) = TVGRS(I) * C7 / ID*6
    End If
    Call TEST(TVISG(I),0D+0,0D+0,'TVISG',IERR)
    Call TEST(TVGRS(I),0D+0,1D+0,'TVGRS',IERR)
    Call TEST(TDENRG(I),0D+0,10D+0,'TDENRG',IERR)
    Call TEST(TFVFG(I),0D+0,2D+0,'TFVFG',IERR)
    Go To 30
  End If
  Call ITEST(NPVT,1,1,1,'NPVT TABLES DIFFERENT LENGTH',IERR)
  Call ITEST(NPVT,2,NI,'NPVT',IERR)

* ... READ AND TEST DATA TABLE 4

  I = 0
40 Continue
  I = I + 1
  Call SKIP(2)
  Read (2,*) X0
  If (X0.GE.0.) Then
    Backspace (2)
    Read (2,*) TSATG(I), TPRMRO(I), TPRMRG(I)
    Write(6,*)TSATG(I)
    NRP = I
    Call TEST(TSATG(I),0D+0,1D+0,'TSATG',IERR)
    If (I.GT.1) Call TESTGE(TSATG(I-1),TSATG(I),'TSATG',IERR)
    Call TEST(TPRMRO(I),0D+0,1D+0,'TPRMRO',IERR)
    Call TEST(TPRMRG(I),0D+0,1D+0,'TPRMRG',IERR)
    Go To 40
  End If
  Call ITEST(NRP,2,NI,'NRP',IERR)
  Call TEST(TSATG(I),0D+0,0D+0,'TSATG, FIRST VALUE',IERR)
  Call TEST(TSATG(NRP),1D+0-SATWI,1D+0,'TSATG, LAST VALUE',IERR)

Close (2)
TTIM(NMT*1) = XMXTIM

Return
Format (A)
End

* ... Subroutine GMSECHO
* Author Gunnar Borlthne (expanded by James Carroll)
* Date April, 1986
* Function This subroutine echoes the input data of the well model.
* Subroutine GMSECHO

* ... VARIABLES AND CONSTANTS
Implicit Double Precision (A-Z)

Integer NI, N2, MWELLS, I, IERR, IEXE, IHC, IPRT, IUNIN, NMT,
* CORR, NPVT, NRP, IC, IT, NSTEP
Character ZJOBID*60, ZC(8)*6

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Parameter (NI = 100,N2 = 500)

Dimension TPRMIN(NI), TRTEFM(NI), TRTEFT(NI), TSKN(NI), TTIM(NI),
* TDENRG(100), TDENRO(100), TFVFG(100), TFVFGX(100),
* TFVFO(100), TFOORS(100), TFOGRS(100), TPRMRG(100), TPRMRO(100),
* PRMLC(100), TPRS(100), TSATG(100), TVISG(100), TVISO(100),
* MWELLS(NI), IC(8), IT(8)

* ... COMMON BLOCKS

Common /CONTAM/ NITRO, CO2, H2S, NACL, RSI
Common /TBG/ API, GRVG, AROUCH, DIAM, LENGTH, TWF, TWH, SIGMAO,
* CORR
Common /PROP/ TDENRG, TDENRO, TFVFG, TFVFGX, TFOORS, TFOGRS,
* TPRMRG, TPRMRO, PRMLCO, TPRS, TSATG, TVISG, TVISO, NPVT, NRP
Common /MBAL1/ AGI, AO1, CMPF, DTIM, PORI, PRSI, RGI, ROI, SATWI,
* VOLBW
Common /MBAL2/ AO2, AG2, RO2, RG2, RGAV
Common /MBAL3/ DENRG, DENRO, FVFG, FVFO, GORS, OGRS, POR, PRIMCO,
* SATGI, SATOI, VISC, VISO, XMBALI
Common /IPRI/ DPINT, DSKN, PRM, RADEQ, SKN, THK
Common /ICQUFT/ IC, IT
Common /FINANCE/ INFRATE, DISRATE, OILPRIC, GASPRIC
Common /TRANS1/ TTIM, MWELLS, TRTEFM, TRTEFT, TPRMIN, TSKN, RADW,
* DELTIM, XMXTIM, HCPV, IHC, IUNIN, IPRT, IEXE, NMT, IERR, NSTEP
Common /TRANS2/ C1, C2, C3, C4, C5, C6, C7, C8, C9
Common /TRANS3/ ZC, ZJOBID

* ... WRITE INPUT DATA,
* (BOTH METRIC UNITS AND OIL FIELD UNITS)

Write (3,5000)
If (IPRT.NE.0) Then
  Print *, 'Writing Input Data....'
  Print *
  Write (*,4)
  Write (4,4)
  format (4x,'Iter',7x,'Dtblg',12x,'Peep',9x,'Obj Var',8x,'Side',
* 7x,'Conv?')
  Write (3,5400) 'REVIEW OF INPUT DATA'
  Write (3,*) '-----'

* ... WRITE DATA LINE 1 AND 2

Write (3,5500) ZJOBID, IHC, IUNIN
Write (3,5600) IPRT, IEXE
Write (3,5700) NMT, NPVT, NRP
X1 = DELTIM / 365.

* ... WRITE DATA LINE 3

X2 = XMXTIM / 365.
X3 = HCPV / C6
X4 = CMPF * C4
Write (3,5800) X1, X2, HCPV, X3, PORI, SATWI, CMPF, X4

* ... WRITE DATA LINE 4

X1 = PRM / C5
X2 = THK / C3
X3 = RADW / C3
X4 = DSKN * C8
X5 = DSKN * C6
X6 = DPINT / C4

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. 15/1X,'NPVT' : NUMBER OF PVT DATA INPUT LINES ..... : ,15
. /1X,'HRP' : NUMBER OF REL. PERM. DATA INPUT LINES ... : ,15)
5800 Format (1X,'DELTIM : TIMESTEP LENGTH (YEARS) ..... : ,
. G12.5/1X,
. 'AMXTIM : LENGTH OF SIMULATION (YEARS) ..... : ,G12.5/1
. X,'H*PV : HYDROCARBON PORE VOLUME (M3) ..... : ,G12.5/
1X,
. /1X,'PORI : INITIAL POROSITY (FRACTION) ..... : ,G12.5
.5/1X,'SATWI : INITIAL WATER SATURATION (FRACTION) ..... : ,G12
. 'CMFF : FORMATION COMPRESSIBILITY (1/KPA) ..... : ,G12.5/1
. X,
5900 Format (/1X,
. 'PRM : PERMEABILITY (UM2) ..... : ,G12.5/1
. X,
. /1X,'THK : RESERVOIR THICKNESS (M) ..... : ,G12.5/
. /1X,'RADW : WELLBORE RADIUS (M) ..... : ,G12.5
.5/1X,
. 'DSKN : NON-DARCY FLOW COEFFICIENT (D/M3) ..... : ,G12.5/1
. /1X,
. /1X,'DPINT : PRESSURE INCREMENT IN SIMPSON- /1X,
. X,
6000 Format (/1X,'JOB IDENTIFICATION : ',A60//1X,
6100 Format (1X,2(A15.1X,G15.5,1X))
6200 Format (1X,A15.1X,15.1X,A30)
6300 Format (/1X,'JOB IDENTIFICATION : ',A60//1X,
. 'PRESSURE-DEPENDENT PROPERTIES, OIL'/1X,100('')/1X,
. 'PRESSURE
. SOLUTION GAS/OIL RATIO SPECIFIC OIL FVF '/1X,
. GRAVITY
. 'NO. KPA PSIA PSIA CP
. SM3/SM3 SCF/BBL RATIO,OIL RES/STD VOL'/1X,
. '
6400 Format (1X,13,F12.0,F12.1,6G12.5)
6500 Format (/1X,'JOB IDENTIFICATION : ',A60//1X,
. 'PRESSURE-DEPENDENT PROPERTIES, GAS'/1X,100('')/1X,
. 'PRESSURE
. SOLUTION OIL/GAS RATIO SPECIFIC GAS FVF '/1X,
. GRAVITY
. 'NO. KPA PSIA PSIA CP
. SM3/SM3 BBL/HMSCF RATIO,GAS RES/STD VOL'/1X,
. '
6600 Format (1X,13,F12.0,F12.1,6G12.5)
6700 Format (/1X,'JOB IDENTIFICATION : ',A60//1X,
. 'RELATIVE PERMEABILITIES AS FUNCTIONS OF GAS SATURATION'/1X,39
. ('')/1X,
. 'NO. SATURATION REL-PERM OIL REL-PERM '/1X,
. '
6800 Format (1X,13,9G12.5)
6900 Format (/1X,'JOB IDENTIFICATION : ',A60//1X,'WELL CONTROL'/1X,126(
. ')/1X,
. 'FIELD MINIMUM FIELD TARGET
. MINIMUM WELLHEAD SKIN FACTOR'/1X,
. '
. 'GAS PRODUCTION RATE GAS PRODUCTION RATE
. 'PRESSURE

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. 'NO. D SCF/D SM3/D SCF/D
. 'KPA PSIA DIM-LESS '/1X,
. '
7000 Format (/1X,'JOB IDENTIFICATION : ',A60//1X,'WELL CONTROL'/1X,126(
. ')/1X,
. 'FIELD MINIMUM FIELD TARGET
. MINIMUM WELLHEAD SKIN FACTOR'/1X,
. '
. 'OIL PRODUCTION RATE OIL PRODUCTION RATE
. 'PRESSURE OF
. '
. 'NO. D STB/D SM3/D STB/D
. 'KPA PSIA DIM-LESS '/1X,
. '
7100 Format (1X,13,F8.1,'F7.1,F7.2,'F6.2,I6,1X,4G12.5,F12.0,F12
.1,F12.2)
. End
. Subroutine GMSBODY
. Author Gunnar Borthne (modified by James Carroll)
. Date April, 1986
. Function This program is a material balance and inflow
. performance simulation model for oil and gas-condensate
. reservoirs. The GMS formulations can utilize PVT data from the
. general PVT formulation which is based on flash separation of the
. oil and gas, separately, to stock-tank conditions (STC). (For
. these data, flash has been done from each pressure step in a
. differential-liberation or constant-volume depletion process. The
. gas/oil ratio in oil, oil/gas ratio in gas, and densities at STC
. are functions of the feed pressure to the flash process.)
. The inflow-performance procedure utilizes the pseudopressure
. concept with numerical integration of a pressure function.
. (Simpson's integration method is used.)
. A field with multiple wells can be simulated. The field
. target and minimum production rates, minimum bottomhole or
. wellhead pressure, and the number of wells should be specified on
. the input as functions of time. All the wells are considered to be
. "equivalent" and produce at the same average reservoir conditions
. and have the same inflow-performance relationship. Calculations
. are performed on a well-basis and multiplied by the number of
. wells to get field quantities.
. For more information, see diploma theses by
. 1) Gunnar Borthne, MTH, 1986;
. 2) James Carroll, Stanford, 1990.
. Subroutine GMSBODY
.----- VARIABLES AND CONSTANTS
Implicit Double Precision (A-Z)
Integer N1, N2, IVNWEI, NWEI, I, IERR, IEKE, IHC, IPRT, IUNIN,

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* IWCTR, J, K, MWELL, MWT, CORR, NPVT, NRP, IC, IT, NSTEP
Character ZJOBID*60, ZC(8)*6
Logical QMCTR, QSTOP, ICRIT
Parameter NI = 100, N2 = 500, N3 = 5

Dimension TPWMIN(N1), TRTEFM(N1), TRTEFT(N1), TSKN(N1), TTIM(N1),
  VGRASP(0:N2), VGOR(0:N2), VOILP(0:N2), VPRSR(0:N2),
  VPRSMF(0:N2), VPRSMH(0:N2), VRTEG(0:N2), VRTEO(0:N2), AN(8),
  VTIME(0:N2), TDENRG(100), TDENRO(100), TFFVFG(100),
  TFFVFX(100), TFFVOI(100), TGOGRS(100), TGOGRS(100), TPRMRG(100),
  TPRMRO(100), PRLMGO(100), TPRS(100), TSATG(100), TVISSG(100),
  TVISO(100), IVMWEL(0:N2), NMWELLS(N1), IC(8), IT(8)
Dimension Pass(N3), VRTEO1(0:N2), VRTEG1(0:N2), NPV1(0:N2)

COMMON BLOCKS
Common /PASS/ Pass, Pass4
Common /CONTAM/ NITRO, CO2, H2S, NACL, RSI
Common /TBG/ API, GRVG, AROUGH, DIAM, LENGTH, TWF, TMH, SIGMAO,
  CORR
Common /PROP/ TDENRG, TDENRO, TFFVFG, TFFVFX, TFFVOI, TGOGRS, TGOGRS,
  TPRMRG, TPRMRO, PRLMGO, TPRS, TSATG, TVISSG, TVISO, NPVT, NRP
Common /MBAL1/ AG1, AO1, CHPF, DTIM, PORI, PRSI, RGI, ROI, SATWI,
  VOLB
Common /MBAL2/ AO2, AG2, RO2, RG2, RGV
Common /MBAL3/ DENRG, DENRO, FVFG, FVFO, GORS, OGRS, POR, PRMGO,
  SATG1, SATO1, VISG, VISO, XMBAL1
Common /FPI/ DPINT, DSKN, PRM, RADEQ, SKN, THK
Common /ICOUNT/ IC, IT
Common /FINANCE/ INFRATE, DISRATE, OILPRIC, GASPRIC
Common /TRANS1/ TTIM, NMWELLS, TRTEFM, TRTEFT, TPWMIN, TSKN, RADW,
  DELTIM, XMXTIM, HCPV, IHC, IHCN, IUNIN, IPRT, IEKE, NMT, IERR, NSTEF
Common /TRANS2/ C1, C2, C3, C4, C5, C6, C7, C8, C9
Common /TRANS3/ ZC, ZJOBID
Common /TRANS4/ VGASP, VOILP, VPRSR, VPRSMF, VPRSMH, VRTEG,
  VRTEO, VTIME, IWCTR, MWELL, NMWEL, OILTI, GASTI, IVMWEL, K
Common /RESULTS/ NEV, NPV1
Common /FLOW/ ICRIT
Common /SEP/ TSEP, PSEP
Common /BHRATE/ VRTEO1, VRTEG1

*----- INITIALIZE ARRAYS
Do I=0, N2
  VTIME(I) = 0.000d0
  VPRSR(I) = 0.000d0
  VPRSMF(I) = 0.000d0
  VPRSMH(I) = 0.000d0
  VGOR(I) = 0.000d0
  VGASP(I) = 0.000d0
  VOILP(I) = 0.000d0
  VRTEO(I) = 0.0d0
  VRTEG(I) = 0.0d0
  VRTEO1(I) = 0.0d0
  VRTEG1(I) = 0.0d0
  NPV1(I) = 0.0d0
End do

*----- INITIALIZE VARIABLES
DIAM=Pass(1)
PSEP=Pass(N3)

Do I=1, N1
  TPWMIN(I)=PSEP

*----- INITIALIZE PRECALCULATED ARRAY OF LOG10 (REL.PERM. RATIO)
ICRIT = .FALSE.
K = 0
IWCTR = 1
QMCTR = .TRUE.
QSTOP = .FALSE.
PI = 3.141592654
NMWELLS(NMT+1) = 0
PVTMIN = MIN(TPRS(1), TPRS(NPVT))
PVTMAX = MAX(TPRS(1), TPRS(NPVT))
PRSI = PVTMAX
VOLB = HCPV / PORI / (1-SATWI)
AREA = VOLB / THK
RADE = SQRT(AREA/PI+RADW*RADEW)

*----- INITIALIZE PRECALCULATED ARRAY OF LOG10 (REL.PERM. RATIO)
Do I = 1, NRP
  If (TPMRO(I).LE.1D-15) Then
    PRLMGO(I) = 15.
  Else If (TPMRG(I).EQ.0.) Then
    PRLMGO(I) = -15.
  Else
    PRLMGO(I) = LOG10(TPMRG(I)/TPMRO(I))
  End If
  If (PRLMGO(I).GT.15.) PRLMGO(I) = 15.
10 Continue

*----- INITIALIZE VARIABLES TO BE USED BY MBAL
Write(6,*)Init 1102.
Do I=1,NRP
  Write(6,*)TSATG(I)
Enddo

Call INTPI(TPRS, TGOGRS, PRSI, 1, NPVT, GORSI, FRAC, J)
FVFOI = TR-FOI(J) + FRAC * (TEVFO(J+1)-TEVFO(J))
VISOI = TVISO(J) + FRAC * (TVISO(J+1)-TVISO(J))
OGRSI = TGOGRS(J) + FRAC * (TGOGRS(J+1)-TGOGRS(J))
VISGI = TVISSG(J) + FRAC * (TVISSG(J+1)-TVISSG(J))
DENROI = TDENRO(J) + FRAC * (TDENRO(J+1)-TDENRO(J))
DENRGI = TDENRG(J) + FRAC * (TDENRG(J+1)-TDENRG(J))

*----- INTERPOLATE IN PRECALCULATED ARRAY OF RECIPROCAL OF FVFG
FVFGI = 1 / (TEVFG(J)+FRAC*(TEVFG(J+1)-TEVFG(J)))

If (IHC.EQ.0) SATOI = 0.
If (IHC.EQ.1) SATOI = 1 - SATMI
SATGI = 1 - SATMI - SATOI
Call INTPL(TSATG, PRLMGO, SATGI, 1, NRP, Y, FRAC, J)
PRMGOI = (1D+1)**Y
XMOBR = PRMGOI * VISOI / VISGI
AOI = PORI * (SATI/I/FVFOI+SATGI*OGRSI+DENROI/FVFGI)
AGI = PORI * (SATGI/FVFGI+SATOI*GORSI+DENRGI/FVFOI)
ROI = (1.+OGRSI*DENROI+XMOBR*FVFOI/FVFGI)
RGI = GORSI * DENRGI + XMOBR * FVFOI / FVFGI

*----- CALCULATE INITIAL GAS AND OIL IN PLACE
GASTI = 0.
OILTI = C.
If (IHC.EQ.0) GASTI = HCPV / FVFGI
If (IHC.EQ.1) OILTI = HCPV / FVFOI
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*----- INITIALIZE REPORT ARRAYS
VTIME(0) = 0.
VTIME(1) = DELTIM
VPRSR(0) = PRSI
VPRSWF(0) = 0.
VPRSWH(0) = 0.
VGOR(0) = 0.
VGASP(0) = 0.
VOILP(0) = 0.

*----- INITIALIZE ITERATION COUNTERS
Do 20 I = 1, 8
  IC(I) = 0
  IT(I) = 0
  AN(I) = 0.
20 Continue

*----- WRITE RESULTS
  Write (3,5400)
  Write (3,*) 'CALCULATED RESULTS'
  Write (3,*) '-----'
  If (IHC.EQ.0) Then
    X1 = PRSI / C4
    X2 = GASTI / C8
  Write (3,5700) PRSI, X1, GASTI, X2
  Else If (IHC.EQ.1) Then
    X1 = PRSI / C4
    X2 = OILTI / C6
  Write (3,5800) PRSI, X1, OILTI, X2
  End If
  X1 = VOLB / C
  X2 = AREA / C2
  X3 = RADE / C3
  Write (3,5900) SATOI, SATGI, VOLB, X1, AREA / 1000., X2, RADE, X3

*----- START TIMESTEP LOOP
  Print *, 'Processing timestep : '
  Print *
  30 Continue
  K = K + 1
  Print 5300, K
  C---- DIAM=Pass(K)

  If (K.LE.5) Then
    DIAM=Pass(1)
    Goto 32
  Endif

  If (K.LE.10) Then
    DIAM=Pass(2)
    Goto 32
  Endif

  If (K.LE.15) Then
    DIAM=Pass(3)
    Goto 32
  Endif

  If (K.LE.20) Then
    DIAM=Pass(4)
    Endif

    If (K.LT.N2) Then
      *----- WELL CONTROL
      If (OMCTR) Then
        NMELL = NMELLS(IMCTR)
        If (NMELL.EQ.0) Then
          * (It's time to stop execution)
          Go To 50
        End If
        RTELO = TRTEFM(IMCTR) / NMELL
        RTEMAX = TRTEFT(IMCTR) / NMELL
        RTEW = RTEMAX
        RTECRIT = RTEMAX
        EPSRTE = RTEW * 0.0005
        EPSPRS = 0.5
        VOLBW = VOLB / NMELL
        RADEQ = RADE / RADW
        FMHMIN = FMHMIN(IMCTR)
        SKN = TSKN(IMCTR)
        IMCTR = IMCTR + 1
        OMCTR = .FALSE.
      End If

      *----- TIME CONTROL
      If (VTIME(K).GT.TTIM(IMCTR)) Then
        OMCTR = .TRUE.
        VTIME(K+1) = VTIME(K)
      Else If (VTIME(K).EQ.TTIM(IMCTR)) Then
        OMCTR = .TRUE.
        VTIME(K+1) = VTIME(K) + DELTIM
      Else
        VTIME(K+1) = VTIME(K) + DELTIM
      End If
      DTIH = VTIME(K) - VTIME(K-1)

      *----- Assume that the average reservoir pressure and the rate will not
      * increase from one timestep to another unless well control is
      * changed. Since XMBAL usually is not identically zero after a time-
      * step, PRSHI is set > VPRSR(K-1) to avoid problems when the rate
      * is zero. Shrink the rate interval which will be used for
      * calculations.
      PRSHI = MIN(VPRSR(K-1)*1.0001,PVTMAX)
      40 RTEHI = MIN(RTEW*1.0001,RTEMAX,RTECRIT)

      *----- CALCULATE RATE, RESERVOIR PRESSURE, BOTTOMHOLE PRESSURE AND
      * WELLHEAD PRESSURE
      Call RATE(PRSHI, PVTMIN, FMHMIN, RTEHI, RTELO, EPSPRS, EPSRTE, K, IPRT,
      * IEHE, IHC, PRS, PRSWF, PRSWH, RTEW, DGASP, DOILP, DGORP, QSTOP)
      If (ICRIT) Then
        RTECRIT = RTECRIT * 0.95
        ICRIT = .FALSE.
        Go To 40
      End If
      If (.NOT.QSTOP) Then

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* X, (SCF) ..... ,G12.5/
* 5900 Format (/1X, 'PRSI : INITIAL PRESSURE IS ASSUMED TO BE EQUAL
* /1X, ' TO MAX. INPUT PVT-DATA PRESSURE (KPA) ... ' ,F11
*      (PSIA) ..... ' ,
*      .0/1X, '
*      F12.1/1X, '
*      'OILTI : OIL VOLUME INITIALLY IN PLACE (SM3) ..... ,G12.5/1
*      (STB) ..... ,G12.5/
*      X, '
* 5900 Format (/1X,
*      'SATOI : INITIAL OIL SATURATION (FRACTION) ..... ,G12.5/1
*      X, 'SATGI : INITIAL GAS SATURATION (FRACTION) ..... ,G12.5/
*      1X, 'VOLB : BULK VOLUME OF RESERVOIR (M3) ..... ,G12.5/
*      (BBL) ..... ,G12.5/
*      .5/1X, 'AREA : TOTAL RESERVOIR AREA, FOR UNIFORM /1X,
*      THICKNESS (1E+3 M2) ..... ,G12.5/1
*      (ACRES) ..... ,G12.5/
*      X, 'RADE : RESERVOIR RADIUS, FOR CIRCULAR SHAPE (M) : ,G12.5/
*      /1X, '
*      .5)
*      End
* .....
* Subroutine GMSOUT
* Author Gunnar Borthne (modified by James Carroll)
* Date April, 1986
* Function This subroutine outputs the results of the well model.
* .....
* Subroutine GMSOUT

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*----- VARIABLES AND CONSTANTS
Implicit Double Precision (A-Z)
Integer N1, N2, IVNMEL, NWEELLS, I, IERR, IEKE, IHC, IPRT, IUNIN,
* IWCTR, K, NSTEP, NWEEL, NMT, CORR, NPVT, NRP, IC, IT
Character ZJOBID*60, ZC(8)*6
Parameter (N1 = 100, N2 = 500)
Dimension TPRMIN(N1), TRTEFM(N1), TRTEFT(N1), TSKN(N1), TTIM(N1),
* VGASP(0:N2), VGOR(0:N2), VOILP(0:N2), VPRSR(0:N2),
* VPRSMF(0:N2), VPRSHH(0:N2), VRTEG(0:N2), VRTEO(0:N2), AN(8),
* VTIME(0:N2), TDENRG(100), TDENRO(100), TFVFG(100),
* TFVFGX(100), TFVFO(100), TGOORS(100), TGOGRS(100), TPRMRG(100),
* TPRMRO(100), PRMLGO(100), TPRS(100), TSATG(100), TVISG(100),
* TVISO(100), IVNMEL(0:N2), NWEELLS(N1), IC(8), IT(8)

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*----- COMMON BLOCKS
Common /CONTAM/ NITRO, CO2, H2S, NAACL, RSI
Common /TBC/ API, CRVG, AROUGH, DIAM, LENGTH, TWF, TWH, SIGMAO,
* CORR
Common /PROP/ TDENRG, TDENRO, TFVFG, TFVFGX, TFVFO, TGOORS, TGOGRS,
* TPRMRG, TPRMRO, PRMLGO, TPRS, TSATG, TVISG, TVISO, NPVT, NRP
Common /MBAL1/ AG1, AO1, CMPF, DTIM, POR1, PRSI, RGI, ROI, SATM1,
* VOLBW
Common /MBAL2/ AO2, AG2, RO2, RG2, RGAU
Common /MBAL3/ DENRG, DENRO, FVFG, FVFO, GORS, OGRS, POR, PRMGO,
* SATC1, SATOI, VISG, VISO, XMBAL1
Common /ICOUNT/ IC, IT
Common /FINANCE/ INFRATE, DISRATE, OILPRIC, GASPRIC
Common /TRANS1/ TTIM, NWEELLS, TRTEFM, TRTEFT, TFMIN, TSKN, RADW,
* DELTIM, AXHTIM, HCPV, IHC, IUNIN, IPRT, IEKE, NMT, IERR, NSTEP
Common /TRANS2/ C1, C2, C3, C4, C5, C6, C7, C8, C9
Common /TRANS3/ ZC, ZJOBID
Common /TRANS4/ VGASP, VGOR, VOILP, VPRSR, VPRSMF, VPRSHH, VRTEG,

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* VRTEO, VTIME, IWCTR, NWEEL, NWEEL, OILTI, GASTI, IVNMEL, K
*----- WRITE RESULTS
Print *
Print *, 'Writing results...'
NSTEP = K - 1
*----- WRITE TABLE OF CUMULATIVE PRODUCTION
Write (3,5300) ZJOBID
Do 10 I = 1, NSTEP
  X1 = VTIME(I) / 365.
  X2 = VGASP(I) / 1D+6
  X3 = VGASP(I) / C8 / 1D+6
  X4 = VOILP(I) / 1D+3
  X5 = VOILP(I) / C6 / 1D+3
  X6 = 0.
  If (X4.NE.0.) X6 = X2 / X4
  X7 = 0.
  If (X5.NE.0.) X7 = X3 / X5
  If (IHC.EQ.0) X8 = VGASP(I) / GASTI
  If (IHC.EQ.1) X8 = VOILP(I) / OILTI
  Write (3,5400) I, VTIME(I), X1, X2, X3, X4, X5, X6, X7, X8
10 Continue
Write (3,5000)
*----- WRITE TABLE OF PRESSURES AND PRODUCING GOR
Write (3,5500) ZJOBID
Do 20 I = 1, NSTEP
  X1 = VTIME(I-1) / 365.
  X2 = VPRSR(I) / C4
  X3 = VPRSMF(I) / C4
  X4 = VPRSHH(I) / C4
  X5 = VGOR(I) / 1D+3
  X6 = VGOR(I) * C7 / 1D+3
  Write (3,5600) I, VTIME(I), X1, VPRSR(I), X2, VPRSMF(I), X3,
* VPRSHH(I), X4, X5, X6
20 Continue
Write (3,5100)
*----- WRITE TABLE OF PRODUCTION RATES
Write (3,5700) ZJOBID
Write (3,5800)
Do 30 I = 1, NSTEP
  X1 = VTIME(I-1) / 365.
  X2 = VTIME(I) / 365.
  X3 = VRTEG(I) / 1D+3
  X4 = VRTEG(I) / C8 / 1D+6
  X5 = X3 * IVNMEL(I)
  X6 = X4 * IVNMEL(I)
  X7 = VRTEO(I)
  X8 = VRTEO(I) / C6
  X9 = X7 * IVNMEL(I)
  X10 = X8 * IVNMEL(I)
  Write (3,5900) I, VTIME(I-1), VTIME(I), X1, X2, IVNMEL(I), X3,
* X4, X5, X6, X7, X8, X9, X10
30 Continue
Write (3,5200)
*----- WRITE TABLE OF REVENUES

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Write (3.6000) ZJOBID
Write (3.6100)
NPV = 0.
DDEF = (1+DISRATE) ** (DELTIM/365)
DFACTOR = (1+DISRATE) ** (DELTIM/2/365)
IFEFF = (1+INFRATE) ** (DELTIM/365)
DO 40 I = 1, NSTEP
  GASPRO = VRTE5(I) / C8 / ID+6 * IVNMEL(I) * DELTIM
  GASREV = GASPRO * GASPRIC * DFACTOR
  OILPRO = VRTEO(I) / C6 * IVNMEL(I) * DELTIM
  OILREV = OILPRO * OILPRIC * DFACTOR
  TOTREV = GASREV + OILREV
  NPV = NPV + TOTREV / DFACTOR
  Write (3.6200) I, VTIME(I-1) / 365, VTIME(I) / 365, GASPRO,
  * GASPRIC * DFACTOR, GASREV, OILPRO, OILPRIC * DFACTOR,
  * OILREV, TOTREV, NPV
  DFACTOR = DFACTOR * DDEF
  DFEFF = DDEF * DDEF
  Write (3.5200)
40 Continue
Write (3.5200)
*----- CALCULATE AND WRITE ITERATION REPORT
If (IPRT.GE.2) Then
  Do 50 I = 1, 3
  XI = IC(I+1) - IC(I) + IT(I)
  If (IT(I).NE.0) AN(I) = XI / IT(I)
  Continue
50
XI = IC(5)
If (XI.EQ.0.) XI = 1.
AN(5) = IC(6) / XI
Write (3.6300)
Do 60 I = 1, 8
  Write (3.6400) ZC(I), IC(I), IT(I), AN(I)
60 Continue
Write (3.6500)
End If
Return
*----- FORMAT STATEMENTS
5000 Format (1X,108('-'))
5100 Format (1X,120('-'))
5200 Format (1X,132('-'))
5300 Format (//1X,'JOB IDENTIFICATION : ',A60//1X,'SIMULATION RESULTS'/1
  * X,108('-')/1X,
  * FIELD CUMULATIVE FIELD CUMULATIVE
  * RECOVERY OF/1X,
  * GAS PRODUCTION GAS PRODUCTION
  * OIL PRODUCTION GAS/OIL RATIO
  * PREF. PHASE/1X.
  *-----/1X,
  * NO. D YEARS 1E+6 SM3 MMSCF
  * 1E+3 SM3 MSTB 1E+3 SM3/SM3 MMSCF/MSTB
  * FRACTION /1X,
  *-----/1X,
  * IN-CALLS = NUMBER OF CALLS TO THIS SUBROUTINE/1X,
  * SOLVE = HOW MANY TIMES DID THE SUBROUTINE HAVE TO START/1
  * A SOLUTION PROCEDURE WITH ITERATIONS/1X,
  * X,
5400 Format (1X,13,F12.1,F9.2,2G12.5,F12.5)
5500 Format (//1X,'JOB IDENTIFICATION : ',A60//1X,'SIMULATION RESULTS'/1
  * X,120('-')/1X,
  * AVERAGE RESERVOIR WELLHEAD
  * BOTTOMHOLE PRODUCING /1X,
  * PRESSURE PRESSURE
  * PRESSURE PRESSURE
  * GAS/OIL RATIO /1X,
  *-----/1X,
  * NO. D YEARS KPA PSIA KPA PSIA
  * 1E+3 SM3/SM3 MMSCF/MSTB/1X,
  *-----/1X,
  *-----)
5600 Format (1X,13,F12.1,F9.2,3(F12.0,F12.1),2G12.5)
5700 Format (//1X,'JOB IDENTIFICATION : ',A60//1X,'SIMULATION RESULTS'/1
  * X,132('-')/1X,
  * GAS PRODUCTION RATE NUM. /1X,
  * OIL PRODUCTION RATE /1X,
  *-----/1X,
  * TIME BER FIELD FIELD
  * WELL WELL OF /1X,
  *-----/1X,
  * NO. D YEARS WELLS
  * 1E+3 SM3/D MMSCF/D 1E+3 SM3/D MMSCF/D
  * SM3/D SM3/D STB/D STB/D /1X,
  *-----/1X,
  *-----)
5900 Format (1X,13,F8.1,'-',F7.1,F7.2,'-',F6.2,I5,1X,2G11.5,3(G12.5,
  * G11.5))
6000 Format (//1X,'JOB IDENTIFICATION : ',A60//1X,'SIMULATION RESULTS'/1
  * X,96('-')/1X,
  * GAS /1X,
  * OIL /1X,
  *-----/1X,
  *-----)
6100 Format (//1X,
  * PRODUCTION PRICE REVENUE TOTAL
  * REVENUE REVENUE PRICE REVENUE
  * YEARS YEARS $ $ /1X,
  * MMSCF/D $/MMSCF $ /1X,
  * STB/D $/STB $ $ /1X,
  *-----/1X,
  *-----)
6200 Format (1X,13,F7.2,'-',F6.2,1X,F11.1,1X,F9.2,1X,F11.0,1X,F11.1,1
  * X,F7.2,2(1X,F11.0),1X,F20.0)
6300 Format (//1X,
  * ITERATION REPORT/1X,
  *-----/1X,
  * IN-CALLS SOLVE IT/SOLVE /1X,
  *-----/1X,
  *-----)
6400 Format (1X,A11,I10,4X,I8,2X,F10.1)
6500 Format (//1X,'NAME = NAME OF SUBROUTINE'/1X,
  * IN-CALLS = NUMBER OF CALLS TO THIS SUBROUTINE/1X,
  * SOLVE = HOW MANY TIMES DID THE SUBROUTINE HAVE TO START/1
  * A SOLUTION PROCEDURE WITH ITERATIONS/1X,
  * X,

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* 'IT/SOLVE = (1) AVERAGE NUMBER OF ITERATIONS EACH TIME A /IX,
* SOLUTION PROCEDURE WAS NECESSARY, OR (2) AVERAGE /
* NUMBER OF INTEGRATION STEPS PER INTEGRATION (IP
* R) )
* End
.....
*.... INPUT VARIABLES
Double Precision DCORP, P2
Integer IHC, IPRT
*----- OUTPUT VARIABLES
Double Precision F, XPRMGO
*----- COMMON BLOCKS
Double Precision TDENRG(100), TDENRO(100), TEFVFG(100),
* TEFVFX(100), TEFVO(100), TCGORS(100), TCGRS(100), TPRMRG(100),
* TPRMRO(100), PRMLGO(100), TPRS(100), TSATG(100), TVISSG(100),
* TVISO(100)
Common /PROP/ TDENRG, TDENRO, TEFVFG, TEFVFX, TEFVO, TCGORS, TCGRS,
* TPRMRG, TPRMRO, PRMLGO, TPRS, TSATG, TVISSG, TVISO, NPVT, NRP
Integer NPVT, NRP
Common /ICOUNT/ IC, IT
Integer IC(8), IT(8)
*----- LOCAL VARIABLES
Double Precision XSATG, XGORPF, GORS, FVFG, VISO, OGRS, FVFG,
* VISSG, DENRO, DENRG, PMRO, PMRG, XPRML, FRAC
Integer J
*----- START EXECUTION
IC(6) = IC(6) + 1
*----- CALCULATE PRESSURE-DEPENDENT PROPERTIES
Call INTPL(TPRS,TCORS,P2,1,NPVT,GORS,FRAC,J)
FVFO = TEFVO(J) + FRAC * (TEFVO(J+1)-TEFVO(J))
VISO = TVISO(J) + FRAC * (TVISO(J+1)-TVISO(J))
OGRS = TCGRS(J) + FRAC * (TCGRS(J+1)-TCGRS(J))
VISSG = TVISSG(J) + FRAC * (TVISSG(J+1)-TVISSG(J))
DENRO = TDENRO(J) + FRAC * (TDENRO(J+1)-TDENRO(J))
DENRG = TDENRG(J) + FRAC * (TDENRG(J+1)-TDENRG(J))
FVFG = 1 / (TEVFX(J)+FRAC*(TEVFX(J+1)-TEVFX(J)))
*----- CALCULATE RELATIVE PERMEABILITY RATIO
XGORPF = (DCORP-GORS*DENRG) / (1-DCORP*OGRS*DENRO)
XPRMGO = XGORPF * VISSG * FVFG / VISO / FVFO

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If (XPRMGO.LT.0..AND.IPRT.GE.4) Then
Write (3,*) 'FNPRS.'
Write (3,*) 'MESSAGE.'
Write (3,*) 'NEGATIVE RELATIVE PERMEABILITY RATIO (KRG/KRO)'
Write (3,*) 'ENCOUNTERED DURING PSEUDOPRESSURE CALCULATIONS.'
Write (3,*) 'KRG/KRO = ', XPRMGO
Write (3,*) 'PRESSURE = ', P2
Write (3,*) 'THIS IS NOT AN ERROR IF THE PRESSURE IS DIFFERENT'
Write (3,*) 'FROM THE BOTTOMHOLE PRESSURE SOUGHT BY *IPR*'
Write (3,*) 'KRG/KRO IS SET EQUAL TO 1E-15, AND CALCULATIONS'
Write (3,*) 'CONTINUE. TRY SMALLER DELTIN OR DEINT.'
Write (3,*)
End If
If (XPRMGO.LE.0.) Then
XPRML = -15
Else
XPRML = LOG10(XPRMGO)
End If
*----- CALCULATE GAS SATURATION
Call INTPL(PRMLGO,TSATG,XPRML,1,NRP,XSATG,FRAC,J)
*----- CALCULATE RELATIVE PERMEABILITIES
Call INTPL(TSATG,TPRMRG,XSATG,1,NRP,PRMRO,FRAC,J)
PRMRG = TPRMRG(J) + FRAC * (TPRMRG(J+1)-TPRMRG(J))
*----- CALCULATE THE PRESSURE FUNCTION
If (IHC.EQ.0) Then
F = PRMRG / VISSG / FVFG + PRMRO * GORS / VISO / FVFO
Else If (IHC.EQ.1) Then
F = PRMRO / VISO / FVFO + PRMRG * OGRS / VISSG / FVFG
End If
Return
End
*----- INPUT VARIABLES
*.... TITLE .....: INTPL
*.... AUTHOR .....: GUNNAR BORTHNE
*.... DATE .....: APRIL 1986
*.... IN-CALLS .....: GMS, MATBAL, FNPRS
*.... OUT-CALLS .....: NONE
*.... FUNCTION .....: Linear X - Linear Y interpolation.
Subroutine INTPL(TABX,TABY,X,I,MAX,Y,FRAC,J)
*----- INPUT VARIABLES
Double Precision TABX(100), TABY(100), X
Integer I, MAX, M
*----- OUTPUT VARIABLES
Double Precision Y, FRAC
Integer J
*----- COMMON BLOCK
Common /ICOUNT/ IC, IT
Integer IC(8), IT(8)
Write(6,*) 'TABX'
do M=1,100

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C---- Write(6,*)TABX(M),TABY(M)
      Enddo

*----- START EXECUTION

IF(X.GE.1.0e-7) THEN
  GOTO 109
ELSE
  X=1.0d-7
ENDIF

109 IF(X.LE.TABX(1))THEN
     X=TABX(1)
     ENDIF

IF(X.GE.TABX(MAX))THEN
  X=TABX(MAX)
ENDIF

IC(8) = IC(8) + 1
J = I
ContInue
If (X.GE.TABX(J).AND.X.LE.TABX(J+1)) Then
  (The appropriate interval is found)
  FRAC = (X-TABX(J)) / (TABX(J+1)-TABX(J))
  Y = TABY(J) + FRAC * (TABY(J+1)-TABY(J))
  Return
End If
J = J + 1
If (J.LT.MAX) Go To 10
Write (3,*) 'ERROR. INTPL'
Write (3,*) 'TABX(1),TABX(MAX),X', TABX(1), TABX(MAX), X
StoP
End

*****
**** TITLE .....: IPR
**** AUTHOR .....: GUNNAR BORTNHE
**** DATE .....: APRIL 1986
**** IN-CALLS .....: WHPRS
**** OUT-CALLS .....: FNPRS
**** FUNCTION .....: The function F is integrated numerically from PRS to
**** PRSMF. PRSMF is the unknown and is found by iterations. If the
**** pressure is trying to move below PRSMIN during integration, then
**** PRSMF is set equal to PRSMIN and a smaller rate is calculated. The
**** input and output units are: pressure, kPa; gas-oil ratio,
**** std.vol/std.vol; rate, m3/D.
****
**** Subroutine IPR(PRS, PRSMIN, RTEK, DGORP, EPSPRS, K, IPRT, IHC, PRSMF, RTEY,
**** QSTOP)
*----- INPUT VARIABLES

Double Precision PRS, PRSMIN, RTEK, DGORP, EPSPRS
Integer K, IPRT, IHC

*----- OUTPUT VARIABLES

Double Precision PRSMF, RTEY
Logical QSTOP

*----- COMMON BLOCK

Common /IPR1/ DPINT, DSKN, PRM, RADEQ, SKN, THK

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Double Precision DPINT, DSKN, PRM, RADEQ, SKN, THK
Common /ICOUNT/ IC, IT
Integer IC(8), IT(8)

*----- LOCAL VARIABLES AND CONVERSION FACTORS

Double Precision AREA, C1, C2, C3, CN0, CN1, DP, DP2, DRVSUM, F1,
* F2, F4, P, P1, P2, PI, SUM1, SUM2, XPRMGO
Integer I
Logical QNORML
Data C1, C2, C3 /1E-12, 1000., 86400/

*----- START EXECUTION

IC(5) = IC(5) + 1
If (IPRT.GE.4) Write (3,*) ' START IPR'
QNORML = .TRUE.
DP = DPINT
DP2 = DP * 2.
PI = 3.141592654
CN0 = LOG(RADEQ) - 0.75 + SKN + DSKN * RTEK
CN1 = CN0 / (2*PI*PRM*C1*THK) / C2
AREA = RTEK * CN1 / C3
(AREA has units kPa/Pa s)
P1 = PRS
P2 = P1
F1 = 0.
(Initialize F2:)
Call FNPRS(DGORP,P2,IHC,IPRT,F2,XPRMGO)
SUM1 = 0.
SUM2 = 0.

*----- START INTEGRATION LOOP

I = 0
10 Continue
I = I + 1
F1 = F2
P1 = P2
P2 = P2 - DP2
If (P2.LT.PRSMIN) Then
  P2 = PRSMIN
  DP2 = P1 - P2
  DP = DP2 / 2.
End If
Call FNPRS(DGORP,(P1-DP),IHC,IPRT,F4,XPRMGO)
Call FNPRS(DGORP,P2,IHC,IPRT,F2,XPRMGO)
(SUM has units kPa/Pa s)
SUM1 = SUM2
SUM2 = SUM2 + (F1+F4+F2) * DP / 3.
If (SUM2.LT.AREA) Then
  If (P2.EQ.PRSMIN) Then
    QNORML = .FALSE.
    Go To 30
  End If
  Go To 10
End If

*----- START LOOP, FIND INTEGRATION LIMIT WITH A MODIFIED NEWTON-RAPHSON
ITERATION METHOD

I = 0
20 Continue
I = I + 1

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If (ABS(P2-P1).GT.EPSPRS) Then
*----- EMERGENCY EXIT
  If (P1-P2.EQ.0..OR.SUM1-SUM2.EQ.0.) Then
    Write (3,*) 'IPR. TIME STEP:', K
    Write (3,5100) ABS(P1-P2), ABS(SUM1-SUM2)
    Write (3,*)
    P = P2
    Go To 30
  End If
  DRVSUM = (SUM2-SUM1) / (P2-P1)
  DF = (SUM2-AREA) / DRVSUM
  P = P2 - DP
  P = MIN(P, PRS)
  P = MAX(P, PRSMIN)
  P1 = P2
  P2 = P
  Call FNPRSD(GORP, P2, IHC, IPRT, F2, XPRMGO)
  SUM1 = SUM2
  SUM2 = SUM2 + (F1+F2) * (P1-P2) / 2.
  Go To 20
End If
30 Continue
If (XPRMGO.LT.0.) Then
  Write (3,*) 'IPR. TIMESTEP:', K
  Write (3,*) 'RELATIVE PERMEABILITY RATIO (KRG/KRO) IS'
  Write (3,*) 'NEGATIVE. EXECUTION STOPS.'
  Write (3,*) 'TRY SMALLER DELTIN OR DPINT.'
  QSTOP = .TRUE.
End If
If (ONORML) Then
*----- PREPARE EXIT, NORMAL PROCEDURE
  PRSMF = P
  RTEY = RTEY
Else
*----- PREPARE EXIT, LACK OF PVT DATA
  PRSMF = PRSMIN
  RTEY = SUM2 / CN1 * C3
  If (IPRT.GE.4) Then
    Write (3,*) 'IPR. TIMESTEP:', K
    Write (3,*) 'The rate is reduced due to lack of PVT data'
    Write (3,*) 'Input rate:', RTEY
    Write (3,*) 'Output rate:', RTEY
  End If
End If
Return
*----- FORMAT STATEMENTS
5000 Format (1X,A14,A14)
5100 Format (1X,'EMERGENCY EXIT',/1X,
* 'LENGTH OF CURRENT PRESSURE INTERVAL (KPA) .....',G15.8,/1
* X,'DIFFERENCE IN SUM (KPA/PA S) .....',G15.8,
* //)
End
*-----
* TITLE ..... ISGN
* AUTHOR ..... GUNNAR BORTHNE
* DATE ..... APRIL 1986

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*----- IN-CALLS ..... RATE, WHPRS, RESPRS
*----- OUT-CALLS ..... NONE
*----- FUNCTION ..... Return sign of argument (-1, 0, +1)
Integer Function ISGN(X)
  Double Precision X
*----- COMMON BLOCK
Common /ICOUNT/ IC, IT
Integer IC(8), IT(8)
IC(7) = IC(7) + 1
If (X.GT.0.) Then
  ISGN = 1
Else If (X.EQ.0.) Then
  ISGN = 0
Else If (X.LT.0.) Then
  ISGN = -1
End If
Return
End
*-----
* TITLE ..... ITEST
* AUTHOR ..... GUNNAR BORTHNE
* DATE ..... APRIL 1986
*----- IN-CALLS ..... GMS
*----- OUT-CALLS ..... NONE
*----- FUNCTION ..... DETECT ERROR IN INTEGER INPUT DATA, AND WRITE ERROR
*-----
Subroutine ITEST(IX, I1, I2, ZTXT, IERR)
*----- INPUT VARIABLES
Integer IX, I1, I2
Character ZTXT*(*)
*----- INPUT AND OUTPUT
Integer IERR
If (IX.LT.I1.OR.IX.GT.I2) Then
  IERR = IERR + 1
  Write (3,*)
  Write (3,*) '*** ERROR ***'
  Write (3,*) 'MESSAGE .....', ZTXT
  Write (3,*) 'VALUE .....', IX
  Write (3,*) 'PERMITTED INTERVAL .....', I1, I2
  Write (3,*)
End If
Return
End
*-----
* TITLE ..... MATBAL
* AUTHOR ..... GUNNAR BORTHNE
* DATE ..... APRIL 1986
*----- IN-CALLS ..... RESPRS
*----- OUT-CALLS ..... INTPL
*-----
*----- FUNCTION ..... Calculate material-balance error and related quantities
* as functions of average reservoir pressure, production rate,

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**** timestep length and other variables.
*****
Subroutine MATBAL(PRS,RTE,IPRT,IHC,DGASP,DOILP,XMBAL)
.....
INPUT VARIABLES
Double Precision PRS, RTE
Integer IPRT, IHC
.....
OUTPUT VARIABLES
Double Precision DGASP, DOILP, XMBAL
.....
LOCAL VARIABLES
Integer J
Double Precision SATO, SATG, S, XMOBR, X1, X2, X3, ROAV, DOILPQ,
DGASQP, FRAC, Y
.....
COMMON BLOCKS (MATBAL MODIFIES MBAL2, MBAL3)
Double Precision TDENRG(100), TDENRO(100), TFFVG(100),
TFVFX(100), TFVFO(100), TGOGRS(100), TGOGRS(100), TPRMRG(100),
TPRMRG(100), PRMLGO(100), TPRS(100), TSATG(100), TVISG(100),
TVISO(100)
Common /PROP/ TDENRG, TDENRO, TFFVG, TFFVGX, TFVFO, TGOGRS, TGOGRS,
TPRMRG, TPRMRG, PRMLGO, TPRS, TSATG, TVISG, TVISO, NPVT, NRP
Integer NPVT, NRP
Common /MBAL1/ AG1, AO1, CMPF, DTIM, PORI, PRSI, RGI, ROI, SATMI,
VOLBW
Double Precision AG1, AO1, CMPF, DTIM, PORI, PRSI, RGI, ROI,
SATMI, VOLBW
Common /MBAL2/ AO2, AG2, RO2, RG2, RGA
Double Precision AO2, AG2, RO2, RG2, RGA
Common /MBAL3/ DENRG, DENRO, FVFG, FVFO, GORS, OGRS, POR, PRMGO,
SATG1, SATO1, VISC, VISO, XMBAL1
Double Precision DENRG, DENRO, FVFG, FVFO, GORS, OGRS, POR, PRMGO,
SATG1, SATO1, VISC, VISO, XMBAL1
Integer IC(8), IT(8)
.....
START EXECUTION
C--- Write(6,*)'MATBL'
do I=1,NRP
C--- Write(6,*)TSATG(I)
ENDDO
IC(4) = IC(4) + 1
If (IPRT.GE.4) Write (3,*) , START MBAL'
.....
CALCULATE PRESSURE-DEPENDENT PROPERTIES
Call INTPL(TPRS,TGOGRS,PRS,1,NPVT,GORS,FRAC,J)
FVFO = TFVFO(J) + FRAC * (TFVFO(J+1)-TFVFO(J))
VISO = TVISO(J) + FRAC * (TVISO(J+1)-TVISO(J))
OGRS = TGOGRS(J) + FRAC * (TGOGRS(J+1)-TGOGRS(J))
VISC = TVISG(J) + FRAC * (TVISG(J+1)-TVISG(J))
DENRO = TDENRO(J) + FRAC * (TDENRO(J+1)-TDENRO(J))
DENRG = TDENRG(J) + FRAC * (TDENRG(J+1)-TDENRG(J))
FVFG = 1 / (TFVFX(J)+FRAC*(TFVFX(J+1)-TFVFX(J)))
POR = PORI * EXP(CHPFF*(PRS-FRS1))
.....
CALCULATE SATURATIONS
If (IHC.EQ.0) Then
.....
FORMAT SPECIFICATIONS
.....
(Calculate the oil saturation from)
(the gas material balance equation)
DGASQP = RTE * DTIM / VOLBW
X1 = GORS * DENRG / FVFO
X2 = POR * (1-SATMI) / FVFG
X3 = POR * (X1-1)/FVFG
SATO = (AG1-DGASQP-X2) / X3
Else If (IHC.EQ.1) Then
(Calculate the oil saturation from)
(the oil material balance equation)
DOILPQ = RTE * DTIM / VOLBW
X1 = OGRS * DENRO / FVFG
X2 = POR * (1-SATMI) * X1
X3 = POR * (1/FVFO-X1)
SATO = (AO1-DOILPQ-X2) / X3
End If
SATG = 1 - SATMI - SATO
.....
CALCULATE RELATIVE PERMEABILITY RATIO AS A FUNCTION OF GAS
SATURATION. USE S FOR INTERPOLATION
C--- Write(6,*)'T2078'
C--- Write(6,*)TSATG(2),TSATG(NPR-1)
If (SATG.LT.TSATG(1)) Then
S = TSATG(1)
Else If (SATG.GT.TSATG(NRP)) Then
S = TSATG(NRP)
Else
S = SATG
End If
Call INTPL(TSATG,PRMLGO,S,1,NRP,Y,FRAC,J)
PRMGO = (1D+1) ** Y
.....
CALCULATE MOBILITY RATIO AND AO2,AG2,RO2,RG2 WHICH CONTAIN PARTS
OF THE OIL MATERIAL BALANCE EQUATIONS
XMOBR = PRMGO * VISO / VISC
AO2 = POR * (SATO/FVFO+SATG*OGRS*DENRO/FVFG)
AG2 = POR * (SATG/FVFG+SATO*GORS*DENRG/FVFO)
RO2 = (1.+OGRS*DENRO*XMOBR*FVFO/FVFG)
RG2 = GORS * DENRG * XMOBR * FVFO / FVFG
ROAV = (RO1+RG2) / 2.
RGA = (RGI+RG2) / 2.
.....
CALCULATE INCREMENTAL OIL AND GAS PRODUCTION
If (IHC.EQ.0) Then
DOILPQ = DGASQP / RGA * ROAV
Else If (IHC.EQ.1) Then
DGASQP = DOILPQ / ROAV * RGA
End If
DOILP = DOILPQ * VOLBW
DGASP = DGASQP * VOLBW
.....
CALCULATE MATERIAL BALANCE ERROR
XMBAL1 = AO2 - AO1 + DOILPQ * AG2 - AG1 + DGASQP
If (RTE.EQ.0.) XMBAL1 = 0.
XMBAL = XMBAL1
SATO1 = SATO
SATG1 = SATG
.....
FORMAT SPECIFICATIONS
```

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Wellmodel.For

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Return
5000 Format (1X,4A16)
5100 Format (1X,6I16)
5200 Format (1X,4E16.8)
.....
*****
**** TITLE .....: RATE
**** AUTHOR .....: GUNNAR BORTHNE
**** DATE .....: APRIL 1986
**** IN-CALLS .....: GMS
**** OUT-CALLS .....: WHPRS, ISGN
*****
**** FUNCTION .....: Determine a well production rate (RTE) which matches
**** the rate and wellhead pressure requirements.
**** 1. The highest allowed rate (RTEHI) is tried first. If the calculated
**** wellhead pressure (PWHMIN) is greater than or equal to the spec-
**** ified minimum wellhead pressure (PWHMIN), the task is finished. A
**** special situation may occur. If QPVT is true, the rate has been
**** reduced by subroutine RESPRS or IPR. It means that lack of PVT-
**** data is limiting the rate. These results should not be used.
**** Control is passed to the main program and execution is terminated.
**** 2. If PRSMH < PWHMIN the rate is lowered until PRSMH = PWHMIN. This
**** is done first by a stepwise search to establish an interval with a
**** solution. If an interval is found, the rate is calculated by a
**** modified chord method. If an interval is not found, control is
**** passed to the main program and execution is terminated.
*****
**** Summary:
**** 1. PRSMH >= PWHMIN at the first calculation (PM1>=0)
**** a) QPVT is false. No need for further calculations.
**** The pressures and rates are OK. Return and continue.
**** b) QPVT is true. Lack of PVT-data. Rate can not be
**** increased. Return and terminate execution.
**** 2. PRSMH < PWHMIN at the first calc. (PM1<0)
**** Search for a subinterval (R1,R2) on (RTELO,RTEHI)
**** with a solution to PRSMH(RTE)=PWHMIN
**** a) An interval is found (PM1<0,PM2>=0)
**** Solve by modified chord method. Return and continue.
**** b) An interval is not found (R1=R2=RTELO)
**** Rate can not be reduced below RTELO. Return and terminate.
*****
**** INPUT VARIABLES
**** Subroutine RATE(PRSHI,PRSLO,PRSMH,RTEHI,RTELO,EPSPRS,EPSPRS,K,
**** IPRT,IEXE,IHC,PRS,PRSMF,PRSMH,RTE,DCASP,DOILP,DCORP,QSTOP)
*****
**** LOCAL VARIABLES
**** Double Precision PRSHI, PRSLO, PWHMIN, RTEHI, RTELO, EPSPRS,
**** EPSPRTE
**** Integer K, IPRT, IEXE, IHC
*****
**** OUTPUT VARIABLES
**** Double Precision PRS, PRSMF, PRSMH, RTE, DCASP, DOILP, DCORP
**** Logical QSTOP
**** Logical ICRIT
**** Common /FLOW/ ICRIT
*****
**** LOCAL VARIABLES
**** Double Precision DRTE, DR, R1, R2, R, PM1, PM2, PWD, PW
**** Integer I, J, LOOP, MAXITR, ISGN
*****
Logical QPVT
***** COMMON BLOCK
Common /ICOUNT/ IC, IT
Integer IC(8), IT(8)
***** START EXECUTION
IC(1) = IC(1) + 1
If (IPRT.GE.4) Write (3,*) 'START RATE'
QSTOP = .FALSE.
ICRIT = .FALSE.
LOOP = 1
MAXITR = 60
DRTE = (RTEHI-RTELO) / LOOP
DRTE = 1.001 * DRTE
R1 = RTEHI
***** INITIAL CALCULATION OF WELLHEAD PRESSURE, BOTTOMHOLE PRESSURE
RESERVOIR PRESSURE AND RATE
Call WHPRS(PRSHI,PRSLO,R1,EPSPRS,EPSPRS,K,IPRT,IEXE,IHC,PRS,PRSMF,
PRSMH,RTE,DCASP,DOILP,DCORP,QSTOP)
If (QSTOP) Return
If (ICRIT) Return
R1 = RTE
PM1 = PRSMH - PWHMIN
If (PM1.GE.0..AND..NOT.QPVT) Return
If (.NOT.(PM1.GE.0..AND.QPVT)) Then
If (RTE.LT.RTELO) Go To 40
***** START LOOP, SEQUENTIAL SEARCH
IT(1) = IT(1) + 1
10 Continue
J = J + 1
If (J.GT.LOOP) Go To 50
R = MAX(R1-DRTE,RTELO)
***** CALCULATE WELLHEAD PRESSURE, BOTTOMHOLE PRESSURE RESERVOIR
PRESSURE AND RATE
Call WHPRS(PRSHI,PRSLO,R,EPSPRS,EPSPRS,K,IPRT,IEXE,IHC,PRS,
PRSMF,PRSMH,RTE,DCASP,DOILP,DCORP,QSTOP)
If (QSTOP) Return
If (ICRIT) Return
If (RTE.LT.RTELO) Go To 40
R = RTE
PW = PRSMH - PWHMIN
***** TEST IF A SUBINTERVAL WITH A SOLUTION IS FOUND
If (ISGN(PW1)*ISGN(PW).GT.0) Then
R1 = R
PM1 = PW
If (R1.LE.RTELO) Go To 60
Go To 10
End If
***** START LOOP, MODIFIED CHORD METHOD (PRSMH CONTROLS THE RATE)
R2 = R

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```

PM2 = PW
I = 0
20 Continue
I = I + 1
If (I-GE-MAXITR) Go To 70
If (ABS(PW).GE-EFPSRS.OR.ABS(R1-R2).GE-EFSRTE) Then
  PWD = (PW2-PM1) / (R2-R1)
  DR = PW2 / PWD
  R = R2 - DR
*----- EMERGENCY EXIT
      If ((R1-R)*(R-R2)-LE.0) Then
        Write (3,*) 'RATE. TIME STEP', K
        Write (3,*) 'ABS(R1-R2), ABS(DR), PM2
        Write (3,*)
        R = R2
        Go To 30
      End If
*----- CALCULATE WELLHEAD PRESSURE, BOTTOMHOLE PRESSURE RESERVOIR
      PRESSURE AND RATE
      Call WHPRS (PRSHI, PRSLO, R, EFSPRS, EFSRTE, K, IPRT, IEKE, IHC, PRS,
      PRSMF, PRSMH, RTE, DCASP, DOILP, DGORP, QPVT, QSTOP)
      If (QSTOP) Return
      If (ICRIT) Return
      If (R.NE.RTE) Go To 80
      PW = PRSMH - PWHMIN
      If (ISGN(PW)*ISGN(PM2).GE.0) Then
        PM1 = PM1 / 2.
      Else
        R1 = R2
        PM1 = PM2
      End If
      R2 = R
      PW2 = PW
      Go To 20
    End If
30 Continue
RTE = R
PRSMH = PW + PWHMIN
Return
End If
*----- CHECK STOP CONDITIONS, WRITE COMMENTS
      If (PM1.GE.0..AND.QPVT) Then
        Write (3,*) 'RATE. TIME STEP', K
        Write (3,*) 'The rate has been reduced due to'
        Write (3,*) 'Lack of PVT-data below PVTMIN'
        Write (3,*) 'The calculated wellhead pressure is higher'
        Write (3,*) 'than the specified minimum.'
        Write (3,*) 'This means that the rate (RTE) is controlled'
        Write (3,*) 'by the minimum PVT-data pressure and not by'
        Write (3,*) 'the minimum wellhead pressure (PWHMIN).'
        Write (3,*) 'Do not use the results from this time step.'
        Write (3,*) 'Return to the main program and terminate.'
        Write (3,*)
        QSTOP = .TRUE.
      End If
40 Continue
If (RTE.LT.RTELO) Then

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```

        Write (3,*) 'RATE. TIME STEP', K
        Write (3,*) 'The rate (RTE) is now smaller than'
        Write (3,*) 'the minimum allowed rate (RTELO)'
        Write (3,*)
        QSTOP = .TRUE.
      End If
      If (QSTOP) Return
50 Continue
      If (J.GT.LOOP) Then
        Write (3,*) 'RATE. TIME STEP', K
        Write (3,*) 'Sequential search. J=', J
        Write (3,*) 'Too many iterations'
        Write (3,*)
        QSTOP = .TRUE.
      Return
      End If
60 Continue
      If (R1.EQ.RTELO) Then
        Write (3,*) 'RATE. TIME STEP', K
        Write (3,*) 'The target rate results in a too low wellhead'
        Write (3,*) 'pressure. The rate has been reduced stepwise'
        Write (3,*) 'down to the specified minimum rate, but the'
        Write (3,*) 'wellhead pressure is still too low.'
        Write (3,*) 'Return to the main program and terminate.'
        Write (3,*)
        QSTOP = .TRUE.
      Return
      End If
70 Continue
      If (I.GE-MAXITR) Then
        Write (3,*) 'RATE. TIME STEP', K
        Write (3,*) 'Convergence not reached after', I, ' iterations'
        Write (3,*)
        QSTOP = .TRUE.
      Return
      End If
80 Continue
      If (R.NE.RTE) Then
        Write (3,*) 'RATE. ERROR, R .NE. RTE'
        Write (3,*)
        QSTOP = .TRUE.
      Return
      End If
*----- FORMAT STATEMENTS
5000 Format (1X,/15(' ')/1X,A,14,A,14)
5100 Format (1X,A,14,A,14)
5200 Format (1X,'-EMERGENCY EXIT',/1X,
* 'LENGTH OF CURRENT RATE INTERVAL (SM3/D) .....',G15.8,/1
* X.'ESTIMATED ERROR (LENGTH OF NEXT RATE INTERVAL',/1X,
* 'WHICH IS TOO SMALL FOR CONTINUED ITERATION) (SM3/D)',G15.8,/1
* 1X,'WELLHEAD PRESSURE FUNCTION (SHOULD BE ZERO) (KPA) ',G15
* .8,/)
      End
*-----
* TITLE .....: RESPRS
* AUTHOR .....: GUNNAR BORTHNE
* DATE .....: APRIL 1986
* IN-CALLS .....: WHPRS
* OUT-CALLS ....: MATBAL, ISGN
*-----
* FUNCTION .....: Calculate the average reservoir pressure at the end of
* the current timestep. This is done by making the material-balance

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**** error, which is calculated by the subroutine MATBAL, approach
**** zero. Normally, pressure is the free variable. If the maximum
**** pressure is equal to the minimum PVT data pressure, the rate has
**** to be reduced and is used the free variable for calls to MATBAL.
****
**** NOTE: The last call of subroutine MATBAL before the next timestep has
**** to be done with arguments equal to X and C to obtain correct
**** calculation of AOL.AGL,ROL,RG1
****
**** Subroutine RESPRS(PRSHI,PRSLO,RTEX,EPSPRS,EPSRTE,K,IPRT,IHC,PRS,
**** RTEY,DGASP,DOILP,QSTOP)

```

*----- INPUT VARIABLES

```

Double Precision PRSHI, PRSLO, RTEX, EPSPRS, EPSRTE
Integer K, IPRT, IHC

```

*--- OUTPUT VARIABLES

```

Double Precision PRS, RTEY, DGASP, DOILP
Logical QSTOP

```

*----- LOCAL VARIABLES

```

Double Precision DPRS, Y1, Y2, Y, YD, C, X1, X2, X, DX
Character ZMODE*10
Integer J, LOOP, I, MAXITR, ISGN
Parameter (MAXITR = 30)

```

*----- COMMON BLOCK

```

Common /ICOUNT/ IC, IT
Integer IC(8), IT(8)

```

*----- START EXECUTION

```

IC(3) = IC(3) + 1
If (PRSHI.EQ.PRSLO) Then
  ZMODE = 'rate'
  Go To 20
End If
If (IPRT.GE.4) Write (3,*) '      START RESPRS'
QSTOP = .FALSE.
LOOP = 4
X1 = PRSHI
DPRS = (PRSHI-PRSLO) / LOOP * 1.001
Call MATBAL(X1,RTEX,IPRT,IHC,DGASP,DOILP,Y1)

```

*----- START LOOP, SEQUENTIAL SEARCH

```

IT(3) = IT(3) + 1
J = 0
10 Continue
If (J.GT.LOOP) Go To 50
X2 = MAX(X1-DPRS,PRSLO)
Call MATBAL(X2,RTEX,IPRT,IHC,DGASP,DOILP,Y2)

```

*----- TEST IF A SUBINTERVAL WITH A SOLUTION IS FOUND

```

If (ISGN(Y1)*ISGN(Y2).LE.0) Then
  ZMODE = 'pressure'
  Go To 20
End If

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```

X1 = X2
Y1 = Y2
If (X1.LT.PRSLO) Go To 60
*----- TEST IF THE RATE HAS TO BE USED AS THE FREE VARIABLE
If (X1.EQ.PRSLO) Then
  ZMODE = 'rate'
  Go To 20
End If
Go To 10

```

*----- APPLY THE MODIFIED CHORD METHOD TO FIND THE SOLUTION

```

20 Continue
If (ZMODE.EQ.'pressure') Then
  C = RTEY
  X = X2
  If (Y1.EQ.0.) Then
    X = X1
    Go To 40
  End If
  If (Y2.EQ.0.) Then
    X = X2
    Go To 40
  End If
Else If (ZMODE.EQ.'rate') Then
  C = PRSLO
  X1 = RTEY
  X2 = 0.
  X = 0.
  Call MATBAL(C,X1,IPRT,IHC,DGASP,DOILP,Y1)
  Call MATBAL(C,X2,IPRT,IHC,DGASP,DOILP,Y2)
  If (Y1.EQ.0.) Then
    X = X1
    Go To 40
  End If
  If (Y2.EQ.0.) Then
    X = X2
    Go To 40
  End If

```

```

Else
  Write (3,*) 'RESPRS. ERROR'
  Write (3,*)
  QSTOP = .TRUE.
  Return
End If

```

*----- START LOOP, CHORD METHOD

```

I = 0
30 Continue
I = I + 1
If (I.GE.MAXITR) Go To 80
If (X2-X1.EQ.0..OR.Y2-Y1.EQ.0.) Go To 70
If (ABS(X1-X2).GE.EPSPRS.OR.ZMODE.NE.'pressure') Then
  If (ABS(X1-X2).GE.EPSRTE.OR.ZMODE.NE.'rate') Then
    DX = (Y2-Y1) / (X2-X1)
    DX = Y2 / YD
    X = X2 - DX

```

*----- EMERGENCY EXIT

```

If ((X1-X)*(X-X2).LE.0) Then

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Write (3,*) 'RESPRS. TIME STEP:', K
If (ZMODE.EQ.'pressure') Then
  Write (3,5100) ABS(X1-X2), ABS(DX), Y2
Else If (ZMODE.EQ.'rate') Then
  Write (3,5200) ABS(X1-X2), ABS(DX), Y2
End If
Write (3,*)
X = X2
Go To 40
End If

*----- CALCULATE MATERIAL-BALANCE ERROR

If (ZMODE.EQ.'pressure') Then
  Call MATBAL(X,C,IPRT,IHC,DGASP,DOILP,Y)
Else If (ZMODE.EQ.'rate') Then
  Call MATBAL(C,X,IPRT,IHC,DGASP,DOILP,Y)
End If
If (ISGN(Y)*ISGN(Y2).GE.0) Then
  Y1 = Y1 / 2.
Else
  X1 = X2
  Y1 = Y2
End If
X2 = X
Y2 = Y
Go To 30
End If
End If

*----- PREPARE TO EXIT

40 Continue
RTEY = C
If (ZMODE.EQ.'rate') Then
  PRS = C
  RTEY = X
End If
If (RTEY.LT.RTEX) Then
  Write (3,*) 'RESPRS. TIME STEP:', K
  Write (3,*) 'THE RATE IS REDUCED DUE TO LACK OF PVT DATA'
  Write (3,*) 'INPUT RATE: ', RTEY
  Write (3,*) 'OUTPUT RATE: ', RTEY
  Write (3,*)
End If
Return

*----- CHECK ERROR CONDITIONS

50 Continue
If (J.GT.LOOP) Then
  Write (3,*) 'RESPRS. TIME STEP:', K
  Write (3,*) 'SEARCH ROUTINE, J=', J
  Write (3,*)
  OSTOP = .TRUE.
Return
End If

60 Continue
If (X1.LT.PRSLO) Then
  Write (3,*) 'RESPRS. TIME STEP:', K
  Write (3,*) 'ERROR, X1 < PRSLO'
  Write (3,*)
  OSTOP = .TRUE.
End If

Return
End If

If (X2-X1.EQ.0.) Then
  Write (3,*) 'RESPRS. TIME STEP:', K
  Write (3,*) 'X2-X1 .EQ. 0.'
  Write (3,*)
  OSTOP = .TRUE.
Return
End If

If (Y2-Y1.EQ.0.) Then
  Write (3,*) 'RESPRS. TIME STEP:', K
  Write (3,*) 'Y2-Y1 .EQ. 0.'
  Write (3,*)
  OSTOP = .TRUE.
Return
End If

If (I.GE.MAXITR) Then
  Write (3,*) 'RESPRS. TIME STEP:', K
  Write (3,5000) 'CONVERGENCE NOT REACHED AFTER', I, ' ITERATIONS'
  Write (3,*)
  OSTOP = .TRUE.
Return
End If

*----- FORMAT STATEMENTS

5000 Format (1X,A,I4,A,I4)
5100 Format (1X,'EMERGENCY EXIT',/1X,
  * 'LENGTH OF CURRENT PRESSURE INTERVAL (KPA) .....',G15.8,/1
  * X,'ESTIMATED ERROR (LENGTH OF NEXT PRESSURE INTERVAL',/1X,
  * 'WHICH IS TOO SMALL FOR CONTINUED ITERATION) (KPA) ',G15.8,//
  * 1X,'MATERIAL BALANCE ERROR (DIMENSIONLESS) .....',G15
  * .8.//)
5200 Format (1X,'EMERGENCY EXIT',/1X,
  * 'LENGTH OF CURRENT RATE INTERVAL (SM3/D) .....',G15.8,/1
  * X,'ESTIMATED ERROR (LENGTH OF NEXT RATE INTERVAL',/1X,
  * 'WHICH IS TOO SMALL FOR CONTINUED ITERATION) (SM3/D)',G15.8,//
  * 1X,'MATERIAL BALANCE ERROR (DIMENSIONLESS) .....',G15
  * .8.//)

*----- INPUT VARIABLES
***** TITLE .....: SKIP
***** AUTHOR .....: GUNNAR BORTHNE
***** DATE .....: APRIL 1986
***** IN-CALLS .....: GMS
***** OUT-CALLS .....: NONE
***** FUNCTION .....: Skip text lines in data files
Subroutine SKIP(IUNT)

*----- LOCAL VARIABLES
Integer IUNT

*----- LOCAL VARIABLES
Integer I, N
Character ZA*80, ZSPACE*80, ZB*160, Z*1
Save ZSPACE
Data ZSPACE /

*----- START EXECUTION
```

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10 Continue
Read (IUNT,5000,End=30) ZA
I = 0
ZB = ZA // ZSPACE
N = INDEX(ZB,ZSPACE)
20 Continue
I = I + 1
Z = ZB(I:1)
If (Z.EQ.' ' .AND. I.LT.N) Go To 20
If (Z.GE.'0' .AND. Z.LE.'9' .OR. Z.EQ.'.' .OR. Z.EQ.'-' .OR. Z.EQ.'+' )
Then
Backspace IUNT
Go To 30
End If
Go To 10
30 Continue

Return
5000 Format (ZA)
End

**** TITLE .....: TEST
**** AUTHOR .....: GUNNAR BORTHNE
**** DATE .....: APRIL 1986
**** IN-CALLS .....: GMS
**** OUT-CALLS .....: NONE
**** FUNCTION .....: DETECT ERROR IN NUMERICAL INPUT DATA, AND WRITE ERROR
****
Subroutine TEST(X,X1,X2,ZTXT,IERR)
****
**** INPUT VARIABLES
****
Double Precision X, X1, X2
Character ZTXT*(*)

**** INPUT AND OUTPUT
Integer IERR

If (X.LT.X1.OR.X.GT.X2) Then
IERR = IERR + 1
Write (3,*)
**** ERROR ****
Write (3,*) 'MESSAGE .....: ', ZTXT
Write (3,*) 'VALUE .....: ', X
Write (3,*) 'PERMITTED INTERVAL .....: ', X1, X2
Write (3,*)
End If

Return
End

**** TITLE .....: TESTGE
**** AUTHOR .....: GUNNAR BORTHNE
**** DATE .....: APRIL 1986
**** IN-CALLS .....: GMS
**** OUT-CALLS .....: NONE
**** FUNCTION .....: DETECT ERROR IN NUMERICAL INPUT DATA, AND WRITE ERROR
****
Subroutine TESTGE(X1,X2,ZTXT,IERR)

```

```

**** INPUT VARIABLES
****
Double Precision X1, X2
Character ZTXT*(*)

**** INPUT AND OUTPUT
Integer IERR

If (X1.GE.X2) Then
IERR = IERR + 1
Write (3,*)
**** ERROR ****
Write (3,*) 'VARIABLE .....: ', ZTXT
Write (3,*) 'VALUE .....: ', X1, X2
Write (3,*) 'NOT INCREASING'
Write (3,*)
End If

Return
End

**** TITLE .....: WHPRS
**** AUTHOR .....: GUNNAR BORTHNE
**** DATE .....: APRIL 1986
**** IN-CALLS .....: RATE
**** OUT-CALLS .....: RESPRS, IPR, TRAVERS, ISGN
**** FUNCTION .....: Calculate the wellhead pressure as a function of rate
**** and other variables. To do so, the average reservoir pressure,
**** bottomhole flowing pressure and pressure loss in tubing must be
**** calculated. While calculating the average reservoir pressure and
**** the well flowing pressure, the rate might get reduced due to lack
**** of PVT data below PVTMIN. QPVT is then set true. This should not
**** stop the execution since the rate might get further reduced
**** because of the specified minimum wellhead pressure. RTEHI is the
**** rate input variable and is generally different from RTEHI
****
Subroutine WHPRS(PRSHI,PRSLO,RTEHI,EPSPRS,EPSPRTE,K,IPRT,IEXE,IHC,
PRSP,PRSMF,PRSMH,RTE,DGASP,DOILP,DGORP,QPVT,QSTOP)
****
**** INPUT VARIABLES
****
Implicit Double Precision (A-Z)
Integer K, IPRT, IEXE, IHC, CORR, LOOP, I, J, ISGN, MAXITR,
NPVT, NRP, IC(8), IT(8)
Logical QPVT, QSTOP, ICRIT
Dimension TDENRG(100), TDENRO(100), TFFVFG(100), TVISO(100),
TFVFG(100), TFVFO(100), TGOORS(100), TGOGRS(100), TPRHRG(100),
TPRPRO(100), PRMLGO(100), TPRS(100), TSATG(100), TVISG(100)

**** COMMON BLOCK
****
Common /CONTAM/ NZ, CO2, H2S, NAACL, RSI
Common /MBALL/ AGI, AOI, CMPF, DTIM, PORI, PRSI, RGI, ROI, SATWI,
VOLBW
Common /TBG/ API, GRVG, AROUGH, DIAM, LENGTH, TWF, TMH, SIGMAO,
CORR
Common /PROP/ TDENRG, TDENRO, TFFVFG, TTVFGX, TFVFO, TGOORS, TGOGRS,
TPRHRG, TPRPRO, PRMLGO, TPRS, TSATG, TVISG, TVISO, NPVT, NRP
Common /ICOUNT/ IC, IT
Common /FLOW/ ICRIT

**** START EXECUTION

```


Wellmodel.For

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QSTOP = .TRUE.
Return
End If

*----- FORMAT STATEMENTS
5000 Format (1X,/1X,A,I4,A,I4)
5100 Format (1X,A,I4,A,I4)
5200 Format (1X,'EMERGENCY EXIT',/1X,
  * 'LENGTH OF CURRENT RATE INTERVAL (SM3/D) .....',G15.8,/1
  * X,'ESTIMATED ERROR (LENGTH OF NEXT RATE INTERVAL',/1X,
  * 'WHICH IS TOO SMALL FOR CONTINUED ITERATION) (SM3/D)',G15.8./)
End

*----- Subroutine TRAVERS .....
* Author James Carroll
* Date November, 1990
* In-calls
* Out-calls
* Function This subroutine performs the pressure traverse
calculations for a given multi-phase flow routine.
* Reference Two-Phase Flow in Pipes, J.A. Brill & H.D. Beggs, 1989
* Subroutine TRAVERS(TWH,TMF,PRSMF,GRVG,API,QO,QG,DIAM,L,AROUGH,
  * SIGMAO,CORR,PMH)

Implicit Double Precision (A-Z)
Integer ITER, CORR, IREG
Logical ICRIT
Common /CONTAM/ N2, CO2, H2S, NACL, RSI
Common /FLOW/ ICRIT

*----- Initialize parameters
ICRIT = .FALSE.
WGRAV = 1.07
NACL = .001
SIGMAW = 70.
QM = 0.

*----- Make the necessary conversions
QO = QO * 5.615
QW = QW * 5.615
DIAM = DIAM / 12

*----- Start pressure traverse
PSTAR = PWF
ZSTAR = 0.
DZ = L / 10.
DP = 100.

*----- Start main loop
* Test if dZ will make Zstar greater than L
10 ITER = 0
If ((L-ZSTAR).LT.DZ) DZ = L - ZSTAR

*----- (Re) Evaluate Z and T
20 Z = ZSTAR + DZ / 2.

```

```

End If
30 Continue
RTE = R

*----- CALCULATE WELLHEAD PRESSURE
If ((EXE.GE.2.AND.RTE.NE.0.) Then
  TWF = TWF * 1.8 * 460
  TWH = TWH * 1.8 * 460
  PRSMF = PRSMF * 0.14503774
  QO = RTE * 6.289811
  QG = RTE * DCORP * 35.314667
  DIAM = DIAM * 3.28084 * 12.
  LENGTH = LENGTH * 3.28084
  AROUGH = AROUGH * 3.28084
  Call TRAVERS(TWH,TMF,PRSMF,GRVG,API,QO,QG,DIAM,LENGTH,AROUGH,
  * SIGMAO,CORR,PRSMH)
  TWF = (TWF*460) / 1.8
  TWH = (TWH*460) / 1.8
  PRSMF = PRSMF / 0.14503774
  DIAM = DIAM / 3.28084 / 12.
  LENGTH = LENGTH / 3.28084
  AROUGH = AROUGH / 3.28084
  PRSMH = PRSMH / 0.14503774
Else
  PRSMH = PRSMF
End If
If (QSTOP) Return
If (ICRIT) Return
Return

*----- CHECK ERROR CONDITIONS
40 Continue
If (RI.LE.0.) Then
  Write (3,*) 'WHPRS. TIME STEP:', K
  Write (3,*) 'Interval with solution not found'
  Write (3,*)
  QSTOP = .TRUE.
  Return
End If
50 Continue
If (I.GE.MAX(ITER)) Then
  Write (3,*) 'WHPRS. TIME STEP:', K
  Write (3,5100) 'convergence not reached after', I, ' iterations'
  Write (3,*)
  QSTOP = .TRUE.
  Return
End If
60 Continue
If (J.GT.LOOP) Then
  Write (3,*) 'WHPRS. TIME STEP:', K
  Write (3,*) 'Sequential search. J=', J
  Write (3,*) 'Too many iterations'
  Write (3,*)
  QSTOP = .TRUE.
  Return
End If
If (ABS(RTEA).LE.0.001.OR.ABS(RTEB).LE.0.001) Then
  Write (3,*) 'WHPRS. TIME STEP:', K
  Write (3,*) 'The rate is zero (or nearly zero)'
  Write (3,*) 'Terminate execution'
  Write (3,*)

```



Wellmodel.For

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T = TWF - (TWF-TWH) * Z / L
*----- (Re) Evaluate P and solve for dpnew given dz
30 ITER = ITER + 1
P = PSTAR - DP / 2.
If (CORR.EQ.1) Then
  Call AZIZIT,P,GGRAV,WGRAV,API,QO,QM,QG,DIAM,DZ,AROUGH,SIGMAO,
  * SIGMA,NX,NY,DPDZ,DPNEW,IREG,EK)
Else If (CORR.EQ.2) Then
  Call HAGBRMN(T,P,GGRAV,WGRAV,API,QO,QM,QG,DIAM,DZ,AROUGH,SIGMAO,
  * SIGMA,NX,NY,DPDZ,DPNEW,IREG,EK)
Else If (CORR.EQ.3) Then
  Call ORK(T,P,GGRAV,WGRAV,API,QO,QM,QG,DIAM,DZ,AROUGH,SIGMAO,
  * SIGMA,NX,NY,DPDZ,DPNEW,IREG,EK)
Else
  Print *, 'Invalid correlation number in TRAVERS.FOR: ', CORR
Stop
End If
*----- Test for Critical Flow
If (.NOT.ICRIT) Then
*----- Test for excessive iterations
  If (ITER.GT.10) Then
    DZ = .95 * DZ
    DP = .95 * DPNEW
    ITER = 0
    Go To 20
  End If
*----- Test if dp is greater than 100 psi
  If (DPNEW.GT.100.) Then
    DZ = 90 * DZ / DPNEW
    DP = 90
    Go To 20
  End If
*----- Test for convergence
  If (ABS(DPNEW-DP).GT.0.1) Then
    DP = DPNEW
    Go To 30
  End If
*----- Update Zstar and Pstar and repeat if necessary
  ZSTAR = ZSTAR + DZ
  DP = DPNEW
  PSTAR = PSTAR + DP
  If (ZSTAR.LT.L) Go To 10
  PMH = PSTAR
  End If
  QO = QO / 5.615
  QM = QM / 5.615
  DIAM = DIAM * 12
  Return
End
*-----
*----- Subroutine AZIZ
*----- Author James Carroll
*----- Date November, 1990
*----- In-calls
*----- Out-calls
*----- Function Performs the Aziz, Govier, and Fogaraal multi-phase
*----- flow correlation.
*----- Reference The Flow of Complex Mixtures in Pipes, Govier & Aziz,
*----- 1972. Pressure Drop in Wells Producing Oil and Gas,
*----- Aziz, Govier, Fogatasi, 1972.
*----- Subroutine AZIZIT,P,GGRAV,WGRAV,API,QO,QM,QG,DIAM,L,AROUGH,SIGMAO,
*----- SIGMA,NX,NY,DPDZ,DP,IFLOW,EK)
*----- This program determines the pressure loss for a certain flow
*----- regime and a certain length of travel.
*----- Implicit Double Precision (A-Z)
*----- Integer IFLOW
*----- Logical ICRIT
*----- Common /CONTAM/ N2, CO2, H2S, NACL, RSI
*----- Common /FLOW/ ICRIT
*----- Solve for basic variables.
  ICRIT = .FALSE.
  EK = 0.
  GC = 12.2
  G = GC
  RROUGH = AROUGH / DIAM
  AREA = 3.141592654 * DIAM * DIAM / 4
  QL = QO + QM
  FO = QO / QL
  FW = QM / QL
  SIGMAL = SIGMAO * FO + SIGMAW * FW
*----- Determine superficial velocities
  Call ZFACTOR(T,P,GGRAV,Z)
  Call SCOR(T,P,GGRAV,API,RS)
  Call BPP(T,GGRAV,API,PBP)
  Call FVF(T,P,GGRAV,API,RS,PBP,CO,BO,BM)
  VSG = ((QG-RS*QO/5.615)*14.696*T*Z) / (AREA*86400*P*520)
  If (VSG.LT.0) VSG = .01
  VSL = QL * (BO*FO+BM*FW) / (AREA*86400)
  VM = VSL + VSG
*----- Determine densities.
  Call DENS(T,P,GGRAV,WGRAV,API,DENSO,DENSW,DENSG)
  DENSL = DENSO * FO + DENSM * FW
*----- Determine viscosities.
  Call VISC(T,P,GGRAV,API,RS,PBP,UG,UO,UM)
  UL = UO * FO + UM * FW
*----- Determine the current flow conditions and flow regime boundaries.
  DIMMY = ((72.*DENSL)/(62.4*SIGNAL)) ** .25
  NY = VSL * DIMMY
  NX = VSG * DIMMY * (DENSG/.0764) ** .33333
  BOUND1 = .51 * (100.*NY) ** .172
  BOUND2 = 8.6 + 3.8 * NY

```

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BOUND3 = 70. * (100.*NV) ** (-.152)
*----- Determine the flow regime.
*
* 1 = Bubble
* 2 = Slug
* 3 = Transition
* 4 = Annular mist
*
If (NV.LT.4.) Then
  If (NX.LT.BOUND1) Then
    IFLOW = 1
  Else If (NX.LT.BOUND2) Then
    IFLOW = 2
  Else If (NX.LT.BOUND3) Then
    IFLOW = 3
  Else
    IFLOW = 4
  End If
Else
  If (NX.LT.BOUND1) Then
    IFLOW = 1
  Else If (NX.LT.26.5) Then
    IFLOW = 2
  Else
    IFLOW = 4
  End If
End If

*----- Transfer control to the appropriate correlation
*
Go To (10,20,20,30)IFLOW

*----- BUBBLE FLOW
*
* Determine the pressure gradient of elevation change.
*
10 VBS = 1.41 * (SIGNAL*G*(DENSL-DENSG)/DENSL**2) ** .25
VBF = 1.2 * VM * VBS
HL = 1 - VSG / VBF
DENSG = DENSL * HL + DENSG * (1-HL)
DPDZEL = DENSG / 144

*----- Determine the pressure gradient due to friction.
*
Call FRICFAC(DENSL,VM,DIAM,UL,ROUGH,FM)
DPDZF = FM * DENSG * VM * VM / (2*GC*DIAM*144)

*----- Determine the total pressure gradient, ignoring acceleration.
*
DPDZ = DPDZEL + DPDZF

Go To 40

*----- SLUG FLOW
*
* Determine the pressure gradient due to elevation.
*
20 NE = G * DIAM * DIAM * (DENSL-DENSG) / SIGNAL
NV = (DIAM*DIAM*DIAM*G*(DENSL-DENSG)) ** .5 / UL
If (NV.LE.18) Then
  M = 25.
Else If (NV.LT.250) Then
  M = 69. * NV ** (-.15)
Else
  M = 10.
End If

*----- Determine the total pressure gradient, ignoring acceleration.
*
C = .345 * (1.-DEXP(-.029*NV)) * (1.-DEXP((3.37-NE)/M))
VBS = C * (C*DIAM*(DENSL-DENSG)/DENSL) ** .5
VBF = 1.2 * VM * VBS
HL = 1 - VSG / VBF
DENSG = DENSL * HL + DENSG * (1-HL)
DPDZEL = DENSG / 144

*----- Determine the pressure gradient due to friction.
*
Call FRICFAC(DENSL,VM,DIAM,UL,ROUGH,FM)
DPDZF = FM * DENSL * HL * VM * VM / (2*GC*DIAM*144)

*----- Determine the total pressure gradient, ignoring acceleration.
*
DPDZ = DPDZEL + DPDZF

If (IFLOW.EQ.2) Go To 40
DPDZSLG = DPDZ

*----- MIST FLOW
*
* Determine the pressure gradient of the elevation.
*
30 DENSN = DENSL * VSL / VM + DENSG * VSG / VM
DPDZEL = DENSN / 144

*----- Determine the pressure gradient due to friction.
*
DUMMY = (VSG*UL/SIGNAL) ** 2 * DENSG / DENSL
If (DUMMY.LE.0.005) Then
  MROUGH = .0749 * SIGNAL / (DENSG*VSG*VSG*DIAM)
Else
  MROUGH = .3713 * SIGNAL * DUMMY ** .302 / (DENSG*VSG*VSG*DIAM)
End If
If (MROUGH.LT.MROUGH) MROUGH = MROUGH
If (MROUGH.GT..5) MROUGH = .5
If (MROUGH.LT..001) MROUGH = .001
If (MROUGH.GT..05) Then
  FM = 4 * (1/((4*DLOG10(-.27*MROUGH))**2)+.067*MROUGH**1.73)
Else
  Call FRICFAC(DENSG,VSG,DIAM,UG,MROUGH,FM)
End If
DPDZF = FM * DENSG * VSG * VSG / (2*GC*DIAM*144)

*----- Determine the total pressure gradient, including acceleration
* effects.
*
EK = VM * VSG * DENSN / GC / P / 144
DPDZ = (DPDZEL+DPDZF) / (1-EK)

*----- TRANSITION FLOW
*
If (IFLOW.NE.4) Then
  DPDZMST = DPDZ
  WEIGHT = (BOUND3-NX) / (BOUND3-BOUND2)
  DPDZ = WEIGHT * DPDZSLG + (1-WEIGHT) * DPDZMST
End If

*----- Test for Critical Flow
*
If (DPDZ.GT..6) ICRT = .TRUE.

*----- Determine the total pressure loss.
*
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Wellmodel.For

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40 DP = DPDZ * L
?return
Lad
*****
***** Subroutine HAGBRWN
***** Author James Carroll
***** Date November, 1990
***** In-calls
***** Out-calls
***** Function Performs the Hagedorn & Brown Multi-phase flow
***** correlation.
***** Reference Two-Phase Flow in Pipes, Brill & Beggs, 1989. Original
***** paper, Hagedorn & Brown, JPT, April, 1965. Gas
***** Production Operations, H.D. Beggs, 1984.
*****
***** Subroutine HAGBRWN(T,P,GGRAV,WGRAV,API,RS,PBP,UG,DO,UM)
***** SIGMAO,SIGMAW,NX,NY,DPDZ,DP,IREG,EK)
*----- This program determines the pressure loss in a vertical flow
* string using the Hagedorn and Brown correlation.
Implicit Double Precision (A-Z)
Integer IREG, K
Logical ICRIT
Common /CONTAM/ N2, CO2, H2S, NACL, RSI
Common /FLOW/ ICRIT
Dimension XHL(12), YHL(12), XCNL(10), YCNL(10), XPSI(12),
YPSI(12), XHLL(12), XCNLL(10), YCNLL(10)
*----- Enter data arrays for liquid holdup correlation.
Data XHL / .2, .5, 1., 2., 5., 10., 20., 50., 100., 200., 300.,
1000. /
Data YHL / .04, .09, .15, .18, .25, .34, .44, .65, .82, .92, .96,
1. /
Data XCNL / .002, .005, .01, .02, .03, .06, .1, .15, .2, .4 /
Data YCNL / .0019, .0022, .0024, .0028, .0033, .0047, .0064, .008,
.009, .0115 /
Data XPSI / .01, .02, .025, .03, .035, .04, .045, .05, .06, .07,
.08, .09 /
Data YPSI / 1., 1.1, 1.23, 1.4, 1.53, 1.6, 1.65, 1.68, 1.74, 1.78,
1.8, 1.83 /
*----- Solve for basic variables.
EK = 0.
ICRIT = .FALSE.
RROUGH = AROUGH / DIAM
AREA = 3.141592654 * DIAM * DIAM / 4
QL = QO * QM
FO = QO / QL
FW = QM / QL
SIGMAW = SIGMAO * FO + SIGMAW * FW
*----- Determine superficial velocities
Call ZFACTOR(T,P,GGRAV,Z)
Call SCOR(T,P,GGRAV,API,RS)
Call BPP(T,GGRAV,API,PBP)
Call FVF(T,P,GGRAV,API,RS,PBP,CO,BO,BM)
VSG = ((QO-RS*QO/5-.615)*14.696*F*Z) / (P*520.*AREA*86400)
If (VSG-LT.0) VSG = 0.01
VSL = QL * (BO*FO+BM*FW) / (AREA*86400)
*****
VM = VSG + VSL
HLNS = VSL / VM
*----- Determine densites.
Call DENS(T,P,GGRAV,WGRAV,API,DENSO,DENSW,DENSG)
DENSU = DENSO * FO + DENSW * FW
*----- Determine viscosities.
Call VISC(T,P,GGRAV,API,RS,PBP,UG,DO,UM)
UL = UO * FO + UW * FW
*----- Determine plotting parameters
DUMMY = ((72.*DENSU)/(62.4*SIGMAU)) ** .25
NY = VSL * DUMMY
NX = VSG * DUMMY * (DENSG/.0764) ** .33333
*----- Determine if single phase flow exists.
If (HLNS-GE.1) Then
HL = 1.
HLNS = 1.
IREG = 1
Go To 30
Else If (HLNS.LE.0) Then
HL = 0.
HLNS = 0.
IREG = 2
Go To 30
End If
*----- Check for bubble flow
XLB = 1.071 - .2281 * VM * VM / DIAM
If (XLB-LT-.13) XLB = .13
HGNS = VSG / (VSG+VSL)
If (HGNS-LT.XLB) Then
IREG = 3
VS = .8
HL = 1. - .5 * (1.+VM/VS-SQRT((1.+VM/VS)**2-.4*VSG/VS))
If (HL-LT.HLNS) HL = HLNS
DENS = DENSU * HL + DENSG * (1-HL)
DPDZEL = DENSG / 144
Call FRICFAC(DENSU,(VSL/HL),DIAM,UL,ROUGH,FF)
DPDZF = FF * DENSL * (VSL/HL) ** 2 / (2.*32.2*DIAM*144)
EK = 0.
Go To 40
End If
*----- Determine dimensionless numbers
XNLV = 1.938 * VSL * (DENSU/SIGMAU) ** .25
XNGV = 1.938 * VSG * (DENSU/SIGMAU) ** .25
XND = 120.872 * DIAM * (DENSU/SIGMAU) ** .5
XNL = 0.15726 * UL * (1/DENSU/SIGMAU**3) ** .25
*----- Prepare holdup correlations for interpolation.
Do 10 K = 1, 10
XCNLL(K) = DLOG(XCNL(K))
YCNLL(K) = DLOG(YCNL(K))
10 Continue

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Do 20 K = 1, 12
  XHLL(K) = DLOG(1.-E-05*XHL(K))
20 Continue

*----- Calculate liquid holdup

IREG = 4
XX = DLOG(XNL)
CNL = DEXP(FLAGR*(CNLL, YCNLL, XX, 2, 10))
XX = DLOG(XNLV*CNL/(XNGV**575*XND))*(P/14.7)**.1
HL = FLAGR*(XHL, YHL, XX, 2, 12)
XX = XNGV * XNL ** 0.38 / XND ** 2.14
PSI = FLAGR*(XPSI, YPSI, XX, 2, 12)
If (PSI.LT.1.) PSI = 1.
HL = HL * PSI
If (HL.LT.0) HL = 0.
If (HL.GT.1) HL = 1.

*----- Calculate slip and no-slip mixture densities

30 DENSN = DENSL * HLNS + DENSG * (1.-HLNS)
DENSS = DENSL * HL + DENSG * (1.-HL)

*----- Calculate friction factor

US = UL ** HL * UG ** (1-HL)
Call FRICFAC(DENSN, VM, DIAM, US, RROUGH, FF)

*----- Determine the total pressure loss.

DPDZEL = DENSG / 144
DPDZF = FF * DENSN ** 2 * VM ** 2 / (2.*32.2*DIAM*DENSS*144)
VSG = VM * (1-HLNS)
EK = DENSS * VM * VSG / (32.2*P*144)
40 DPDZ = (DPDZEL+DPDZF) / (1.-EK)
DP = DPDZ * L

*----- Test for Critical Flow

If (DPDZ.GT..6) ICRT = .TRUE.

Return
End
*****
***** Subroutine ORK
***** Author James Carroll
***** Date November, 1990
***** In-calls
***** Out-calls
***** Function Performs the Orkiszewski Multi-Phase Flow correlation.
***** Reference Two-Phase Flow in Pipes, Brill & Beggs, 1989.
*****
***** Subroutine ORK(T,P,GGRAV,WGRAV,API,QO,QM,OG,DIAM,L,AROUGH,SIGMAO,
* SIGMAW,NLV,NGV,DPDZ,DP,IFLOW,EK)

*----- This program determines the pressure loss given by the
Orkiszewski multiphase flow correlation.

Implicit Double Precision (A-Z)
Integer IFLOW, I
Logical ICRT
Common /CORTAM/ N2, CO2, H2S, NAACL, RSI
Common /FUW/ ICRT

```

*----- Solve for basic variables.

ICRT = .FALSE.

EK = 0.

GC = 32.2

G = GC

RROUGH = AROUGH / DIAM

AREA = 3.141592654 * DIAM * DIAM / 4

QL = QO + QW

FO = QO / QL

FW = QW / QL

SIGMAL = SIGMAO * FO + SIGMAW * FW

*----- Determine superficial velocities

Call ZFACTOR(T,P,GGRAV,Z)

Call SCOR(T,P,GGRAV,API,RS)

Call BPP(T,GGRAV,API,PBP)

Call FVF(T,P,GGRAV,API,RC,PBP,CO,BO,BW)

VSG = ((QG-RS*QO/5.615)*14.696*T*Z) / (AREA*86400*P*520)

If (VSG.LT.0) VSG = .01

VSL = QL * (BO*FO+BW*FW) / (AREA*86400)

VM = VSL + VSG

HGNS = VSG / VM

HLNS = VSL / VM

*----- Determine densities.

Call DENST(T,P,GGRAV,WGRAV,API,DENSO,DENSW,DENSG)

DENSL = DENSO * FO + DENSW * FW

*----- Determine viscosities.

Call VISC(T,P,GGRAV,API,RS,PBP,UG,UO,UM)

UL = UO * FO + UM * FW

*----- Determine the current flow conditions and flow regime boundaries.

DUMMY = 1.938 * (DENSL/SIGMAL) ** .25

NLV = VSL * DUMMY

NGV = VSG * DUMMY

BOUND1 = 1.071 - .2218 * VM * VM / DIAM

If (BOUND1.LT..13) BOUND1 = .13

BOUND2 = 50 + 36 * NLV

BOUND3 = 75 + 84 * NLV ** .75

*----- Determine the flow regime.

1 = Bubble

2 = Slug

3 = Transitional

4 = Mist

If (HGNS.LT.BOUND1) Then

IFLOW = 1

Else If (NGV.LT.BOUND2) Then

IFLOW = 2

Else If (NGV.LT.BOUND3) Then

IFLOW = 3

Else

IFLOW = 4

End If

*----- Transfer control to appropriate correlation



Wellmodel.For

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Go To (10,20,30,50)IFLOW
*----- BUBBLE FLOW
10 VS = .8
HL = 1. - .5 * (1.+VM/VS-SQRT((1.+VM/VS)**2-4*VSG/VS))
If (HL.LT.HLNS) HL = HLNS
DENS = DENS1 * HL + DENS2 * (1-HL)
DPDZEL = DENS / 144
Call FRICFAC(DENS, (VSL/HL), DIAM, UL, RROUGH, FF)
DPDZF = FF * DENS * (VSL/HL) ** 2 / (2.*32.*DIAM*144)
EK = 0.
DPDZ = (DPDZEL+DPDZF) / (1.-EK)
Go To 60

*----- SLUG FLOW
Determine Vb
20 VB = .5 * SQRT(G*DIAM)
Do 30 I = 1, 5
NREB = DENS * VB * DIAM / UL
NREL = DENS * VM * DIAM / UL
If (NREB.LE.3000) Then
VB = (.546+.8.74D-6*NREL) * SQRT(G*DIAM)
Else If (NREB.GE.8000) Then
VB = (.35+.8.74D-6*NREL) * SQRT(G*DIAM)
Else
PSI = (.251+.8.74D-6*NREL) * SQRT(G*DIAM)
VB = .5 * (PSI+SQRT(PSI*PSI+13.59*UL/DENS/SQRT(DIAM)))
End If
30 Continue
If ((QM/(QO+QM)).GT..75) Then
If (VM.LT.10) Then
DEL = (0.013*DLOG10(UL)) / DIAM ** 1.38 - .681 + .232 *
DLOG10(VM) - .428 * DLOG10(DIAM)
Else
DEL = (0.045*DLOG10(UL)) / DIAM ** .799 - .709 - .162 *
DLOG10(VM) - .888 * DLOG10(DIAM)
End If
Else
If (VM.LT.10) Then
DEL = (0.0127*DLOG10(UL+1)) / DIAM ** 1.415 - .284 + .167 *
DLOG10(VM) + .113 * DLOG10(DIAM)
Else
XX = -DLOG10(VM) * (.01*DLOG10(UL+1)/DIAM**1.571+.397+.63*
DLOG10(DIAM))
DEL = (0.0274*DLOG10(UL+1)) / DIAM ** 1.371 + .161 + .569 *
DLOG10(DIAM) + XX
End If
End If
XX = -.065 * VM
If (VM.LE.10.AND.DEL.LT.XX) DEL = XX
40 DENS = (DENS*(VSL+VB)+DENS*VSG) / (VM+VB) + DENS * DEL
XX = (-VB/(VM+VB)) * (1-DENS/DENS1)
If (VM.GT.10.AND.DEL.LT.XX) Then
DEL = XX
Go To 40
End If
DPDZEL = DENS / 144

*----- Determine friction gradient
Call FRICFAC(DENS,VM,DIAM,UL,RROUGH,FM)
DPDZF = FM * DENS * VM * (VSL+VB)/(VM+VB)+DEL / (2*GC*DIAM

```

```

* .144)
*----- Determine the total pressure gradient, ignoring acceleration.
DPDZ = DPDZEL + DPDZF
If (IFLOW.EQ.2) Go To 60
DPDZSLG = DPDZ
*----- MIST FLOW
* Determine the pressure gradient of the elevation.
50 DENS = DENS1 * VSL / VM + DENS2 * VSG / VM
DPDZEL = DENS / 144
*----- Determine the pressure gradient due to friction.
DUMMY = (VSG*UL/SIGMAL) ** 2 * DENS / DENS1
If (DUMMY.LE.0.005) Then
MROUGH = .0749 * SIGMAL / (DENS*VSG*VSG*DIAM)
Else
MROUGH = .3713 * SIGMAL * DUMMY ** .302 / (DENS*VSG*VSG*DIAM)
End If
If (MROUGH.LT.RROUGH) MROUGH = RROUGH
If (MROUGH.GT..5) MROUGH = .5
If (MROUGH.LT..001) MROUGH = .001
If (MROUGH.GT..05) Then
FM = 4 * (1/((4*DLOG10(.27*MROUGH)**2)+.067*MROUGH**1.73)
Else
Call FRICFAC(DENS,VSG,DIAM,UG,MROUGH,FM)
End If
DPDZF = FM * DENS * VSG * VSG / (2*GC*DIAM*144)
*----- Determine the total pressure gradient, including acceleration
effects.
EK = VM * VSG * DENS / GC / P / 144.
DPDZ = (DPDZEL+DPDZF) / (1-EK)
If (IFLOW.NE.4) Then
DPDZMST = DPDZ
*----- TRANSITION FLOW
WEIGHT = (BOUND3-NGV) / (BOUND3-BOUND2)
DPDZ = WEIGHT * DPDZSLG + (1-WEIGHT) * DPDZMST
End If
*----- Test for Critical Flow
If (DFJZ.GT..6) ICRT = .TRUE.
*----- Determine the total pressure loss.
60 DP = DPDZ * L
Return
End
*----- Subroutine FLAGR
* Author James Carroll
* Date November, 1990
* In-calls
* Out-calls

```

```

***** Function
***** Interpolation routine similar to FLAGR in Applied
***** Numerical Method by Carnhan, Luther and Wilkes, John
***** Wiley and Sons, Pg. 31. FLAGR uses the Lagrange formula
***** to evaluate the interpolating polynomial of degree Ideg
***** for argument XARG using the data values X(min)...X(max)
***** and Y(min)...Y(max) where MIN=MAX-IDEG. The X(i) values
***** are not necessarily evenly spaced and can be in either
***** increasing or decreasing order. X is the array of
***** independent variable data point. Y is the array of
***** dependent variable data points. XARG is the argument
***** for which an interpolated value is desired. IDEG is the
***** degree of interpolated polynomial (1 is linear, 2 is
***** quadratic, etc.) NPTS is the number of data points in X
***** and Y.
***** Reference Taken from Gas Production Operations, Beggs, 1984.
*****
***** Function FLAGR(X,Y,XARG,IDEG,NPTS)
*****
***** Implicit Double Precision (A-Z)
***** Integer IDEG, NPTS, N, NI, L, MIN, MAX, I, J
***** Dimension X(1), Y(1)
*****
***** N = IABS(NPTS)
***** NI = IDEG + 1
***** L = 1
***** If (X(2)-LE.X(1)) L = 2
*****
***** Check to be sure that XARG is within range of X(i) values
***** for interpolation purposes. If it is not, set FLAGR equal
***** to the appropriate terminal value (Y91) or Y(n)) and return.
***** Note that this precludes extrapolation of data.
*****
***** Go To (10,20), L
***** 10 If (XARG-LE.X(1)) Go To 30
***** If (XARG-GE.X(N)) Go To 40
***** Go To 50
***** 20 If (XARG-LT.X(1)) Then
***** If (XARG-LE.X(N)) Go To 40
***** Go To 50
***** End If
***** 30 FLAGR = Y(1)
***** Return
***** 40 FLAGR = Y(N)
***** Return
*****
***** Determine value of Max
***** 50 Go To (60,80), L
*****
***** Data are in order of increasing values of X.
***** 60 Do 70 MAX = NI, N
***** If (XARG-LT.X(MAX)) Go To 100
***** 70 Continue
*****
***** Data are in order of decreasing values of X.
***** 80 Do 90 MAX = NI, N
***** If (XARG-GT.X(MAX)) Go To 100
***** 90 Continue
*****
***** Compute value of factor.
***** 100 MIN = MAX IDEG

```

```

*****
***** FACTOR = 1.
***** Do 110 I = MIN, MAX
***** If (XARG.EQ.X(I)) Then
***** FLAGR = Y(I)
***** Return
***** End If
***** FACTOR = FACTOR * (XARG-X(I))
***** 110 Continue
*****
***** Evaluate interpolating polynomial
***** YEST = 0.
***** Do 130 I = MIN, MAX
***** TERM = Y(I) * FACTOR / (XARG-X(I))
***** Do 120 J = MIN, MAX
***** If (I.NE.J) TERM = TERM / (X(I)-X(J))
***** 120 Continue
***** YEST = YEST + TERM
***** 130 Continue
***** FLAGR = YEST
*****
***** Return
***** End
*****
***** Subroutine BPP
***** Author James Carroll
***** Date November, 1990
***** In-calls
***** Out-calls
***** Function Estimates the bubble point pressure of a black oil
***** mixture using the correlation of Vasquez and Beggs.
***** Reference Thesis, M.E. Vasquez, University of Tulsa, 1976. HP41C
***** Petroleum Fluids Pack Manual.
*****
***** Subroutine BPP(T,GGRAV,API,PBP)
*****
***** Implicit Double Precision (A-Z)
***** Common /CONTAM/ N2, CO2, H2S, NACL, RSI
*****
***** If (API.GT.30) Then
***** A = .0178
***** B = 1.187
***** C = 23.931
***** Else
***** A = .0362
***** B = 1.0937
***** C = 25.724
***** End If
*****
***** Estimate the bubble-point pressure.
***** PBP = (RSI*.5.615/(A*GGRAV*DEXP(C*API/T))) ** (1/B)
*****
***** Return
***** End
*****
***** Subroutine SGOR
***** Author James Carroll
***** Date November, 1990
***** In-calls
***** Out-calls
***** Function Estimates the solution gas oil ration of a black oil
***** mixture.
***** Reference Thesis, M.E. Vasquez, University of Tulsa, 1976. HP41C

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..... Petroleum Fluids Pack Manual.
..... Subroutine SCOR(T,P,GGRAV,API,RS)
..... Implicit Double Precision (A-Z)
..... Common /CONTAM/ N2, CO2, H2S, NAACL, RSI

If (API.GT.30) Then
  A = .0178
  B = 1.187
  C = 23.931
Else
  A = .0362
  B = 1.0937
  C = 25.724
End If

RS = A * GGRAV * P ** B * DEXP(C*API/T)

If (RS.GT.RSI*5.615) RS = RSI * 5.615

Return
End
..... Subroutine DENS
..... Author James Carroll
..... Date November, 1990
..... In-calls
..... Out-calls
..... Function Determines the density of oil, water, and gas.
..... Reference Thesis, M.E. Vasquez, University of Tulsa, 1976. HP41C
..... Petroleum Fluids Pack Manual.
..... Subroutine DENS(T,P,GGRAV,WGRAV,API,DENSO,DENSW,DENSG)

Implicit Double Precision (A-Z)
Common /CONTAM/ N2, CO2, H2S, NAACL, RSI

*----- Determine PVT parameters

Call ZFACTOR(T,P,GGRAV,Z)
Call SCOR(T,P,GGRAV,API,RS)
Call BPP(T,GGRAV,API,PBP)
Call FVF(T,P,GGRAV,API,RS,PBP,CO,BO,BW)

*----- Compute the density of oil.

OGRAV = 141.5 / (131.5*API)
If (P.LT.PBP) Then
  DENSO = (350.4*OGRAV+.0764*GGRAV*RS) / (5.615*BO)
Else
  DENSO = (350.4*OGRAV+.0764*GGRAV*RS)*5.615 / (5.615*BO)
DENSO = DENSO * DEXP(CO*(P-PBP))
End If

*----- Compute the density of water.

DENSW = 62.4 * WGRAV / BW

*----- Compute the density of gas.

DENSG = 2.7 * P * GGRAV / Z / T

Return
..... End
..... Subroutine FRICFAC
..... Author James Carroll
..... Date November, 1990
..... In-calls
..... Out-calls
..... Function Estimates the Darcy (or Moody) friction factor based on
..... the method of Zigrang and Sylvester.
..... Reference Explicit Approximations to the Solution of Colebrook's
..... Friction Factor Equation, D.J. Zigrang and N.D.
..... Sylvester, AIChE Journal (Vol 28, No 3), May, 1982.
..... Subroutine FRICFAC(RHO,V,D,U,ROUGH,F)

Implicit Double Precision (A-Z)

*----- Compute the Reynold's number.

NRE = 1488 * RHO * V * D / U

*----- Compute the Darcy friction factor.

AA = RROUGH / 3.7
BB = 5.02 / NRE
TEMP = -2 * DLOG10(AA-BB*DLOG10(AA-BB*DLOG10(AA+13/NRE)))
F = (1/TEMP) ** 2

Return
End
..... Subroutine FVF
..... Author James Carroll
..... Date November, 1990
..... In-calls
..... Out-calls
..... Function Estimates the formation volume factors of oil and water
..... using the correlation of Vasquez and Beggs.
..... Reference Thesis, M.E. Vasquez, University of Tulsa, 1976. HP41C
..... Petroleum Fluids Pack Manual.
..... Subroutine FVF(T,P,GGRAV,API,RS,PBP,CO,BO,BW)

Implicit Double Precision (A-Z)
Common /CONTAM/ N2, CO2, H2S, NAACL, RSI

*----- Define constants

TF = T - 460
If (API.GT.30) Then
  A = 1.1E-5
  B = 4.67E-4
  C = 1.337E-9
Else
  A = 1.751E-5
  B = 4.677E-4
  C = -1.811E-8
End If

*----- Determine Bo with respect to bubble point pressure.

CO = (-1433+5*RS)*5.615+17.2*TF-1180*GGRAV+12.61*API / (P*IE5)
If (P.LE.PBP) Then
  BO = 1 + A * (TF-60) * (API/GGRAV) + (B+C*(TF-60))*(API/GGRAV) *

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```

*
RS
Else
BOBP = 1 + A * (TF-60) * (API/GGRAV) + (B * C * (TF-60) * (API/GGRAV))
*
RSI = 5.615
BO = BOBP * EXP(CO * (PBP-P))
End If

*----- Estimate the FVF of gas-free water.
A = .9947 + 5.8E-6 * TF + 1.02E-6 * TF ** 2
B = -4.228E-6 + 1.8176E-8 * TF - 6.77E-11 * TF ** 2
C = 1.1E-10 - 1.3855E-12 * TF + 4.285E-15 * TF ** 2
BW = A + B * P + C * P * P

*----- Apply the salinity correction
BW = BW * ((5.1E-8 * P + (5.47E-6 - 1.95E-10 * P) * (TF-60)) * (-3.23E-8 +
8.5E-13 * P) * (TF-60) ** 2) * NACL * 1

Return
End
*----- Subroutine VISC
*
* Author James Carroll
* Date November, 1990
* In-calls
* Out-calls
* Function
*
* This subprogram uses the Dempsey correlation to determine
* gas viscosity. This subroutine estimates the live oil
* viscosity, both above and below the bubble point pressure
* using the correlations of Beggs and Robinson and Vasquez
* and Beggs. Water viscosity is estimated from an empirical
* correlation.
*
* Reference Thesis, M.E. Vasquez, University of Tulsa, 1976. Estimating
* the Viscosity of Crude Oil Systems, H.D. Beggs and J.F.
* Robinson, JPT, Sept, 1985. HP41C Petroleum Fluids Pack
* Manual.
*-----
Subroutine VISC(T,P,GGRAV,API,RS,PBP,UG,UO,UM)
Implicit Double Precision (A-Z)
Common /CONTAM/ N2, CO2, H2S, NACL, RSI

*----- Solve for critical temperature and pressure.
PURE = 1. - H2S - CO2 - N2
GRAVHC = (GGRAV-.9672*N2-1.5195*CO2-1.1765*H2S) / PURE

TCHC = 187. + 330. * GRAVHC - 71.5 * GRAVHC * GRAVHC
PCHC = 706. - 51.7 * GRAVHC - 11.1 * GRAVHC * GRAVHC

TC = PUKE * TCHC + 227.3 * N2 + 547.6 * CO2 + 672.4 * H2S
PC = PURE * PCHC + 491. * N2 + 1071. * CO2 + 1306. * H2S

*----- Adjust Tc and Pc for gas contaminants.
CWA = 120 * ((CO2+H2S)**0.9 - (CO2+H2S)**1.6)
CWA = CWA + 15 * (H2S**-.5 - H2S**4.)

TCP = TC - CWA
PCP = (PC*(1-CWA)) / (TC+H2S*(1-H2S)*CWA)

*----- Define constants

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```

A0 = -2.4621182
A1 = 2.97054714
A2 = -.286264054
A3 = 8.05420522E-03
A4 = 2.80860949
A5 = -3.49803305
A6 = .36037302
A7 = -.010443241
A8 = -.793385684
A9 = 1.39643306
A10 = -.149144925
A11 = .00441015512
A12 = 8.39387178E-02
A13 = -.186408848
A14 = .0203367881
A15 = -.000609579263

*----- Determine pseudoreduced temperature and pressure
TR = T / TCP
PR = P / PCP

*----- Determine Dempsey correction factors
UA = ((1.709E-5) - (2.062E-6) * GGRAV) * (T-460) + (.008188) - (.00615
) * DLOG10(GGRAV)
UB = N2 * ((-.00848) * DLOG10(GGRAV) + .00959)
UC = CO2 * ((-.00908) * DLOG10(GGRAV) + .00624)
UD = H2S * ((-.00849) * DLOG10(GGRAV) + .00373)

UI = UA + UB + UC + UD

X = A0 + A1 * PR + A2 * PR * PR + A3 * PR ** 3 + TR * (A4 + A5 * PR + A6
* PR * PR + A7 * PR ** 3) + TR * (A8 + A9 * PR + A10 * PR * PR + A11 * PR ** 3) +
* TR ** 3 * (A12 + A13 * PR + A14 * PR * PR + A15 * PR ** 3)

UG = UI * DEXP(X) / TR

*----- Compute the oil viscosity
* Estimate the dead oil viscosity.
TF = T - 460
C = 3.0324 - .02023 * API
B = 10 ** C
A = B * TF ** (-1.163)
UOD = 10 ** A - 1.

*----- Estimate the live oil viscosity below the bubble point pressure.
If (P.LE.PBP) Then
B = 5.44 * (RS+150) ** (-.338)
A = 10.715 * (RS+100) ** (-.515)
UO = A * UOD ** B

*----- Estimate the live oil viscosity above the bubble point pressure.
Else
C = 2.6 * P ** 1.187 * DEXP(-8.98E-5 * P - 11.513)
B = 5.44 * (RSI*5.615+150) ** (-.338)
A = 10.715 * (RSI*5.615+100) ** (-.515)
UOBP = A * UOD ** B
UO = UOBP * (P/PBP) ** C

End If

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Wellmodel.For

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*----- Estimate the water viscosity
MU = DEXP(1.003-1.479E-2*TF+1./82E-5*TF**2)

Return
End
*****
***** Subroutine ZFACTOR
***** Author James Carroll
***** Date November, 1990
***** In-calls
***** Out-calls
***** Function
***** This subroutine calculates the z-factor using the
***** method of Dranchuk, Purvis, and Robinson. Critical
***** temperature and pressure are estimated with Standing's
***** correlation. The Wichert-Aziz correction is made for
***** gas contaminants. The gas gravity is considered to be
***** measured in-situ.
***** Reference Comparisons Made for Computer Z-Factor Calculations,
***** Oil & Gas Journal, Dec., 1976. HP41C Petroleum Fluid
***** Pack Manual.
***** Subroutine ZFACTOR(T,P,GRAV,Z)
*****
Implicit Double Precision (A-Z)
Common /CONTAM/ N2, CO2, H2S, NACL, RSI

*----- Determine the critical temperature and pressure.
PURE = 1. - H2S - CO2 - N2
GRAVHC = (GRAV-.9672*N2-1.5195*CO2-1.1765*H2S) / PURE

TCHC = 187. + 330. * GRAVHC - 71.5 * GRAVHC * GRAVHC
PCHC = 706. - 51.7 * GRAVHC - 11.1 * GRAVHC * GRAVHC

TC = PURE * TCHC + 227.3 * N2 + 547.6 * CO2 + 672.4 * H2S
PC = PURE * PCHC + 493. * N2 + 1071. * CO2 + 1306. * H2S

*----- Adjust Tc and Pc for gas contaminants.
CWA = 120 * ((CO2+H2S)**0.9-(CO2+H2S)**1.6)
CWA = CWA + 15 * (H2S**.5-H2S**4.)

TCP = TC - CWA
PCP = (PC*(T*(-CWA))) / (TC+H2S*(1-H2S)*CWA)

*----- Compute reduced temperature and pressure.
TR = T / TCP
PR = P / PCP

*----- Determine constants for iteration.
A = .06423
B = .5353 * TR - .6123
C = .3151 * TR - 1.0467 - .5783 / TR / TR
D = TR
E = .6816 / TR / TR
F = .6845
G = .27 * PR

*----- Perform Newton-Raphson iteration to obtain pseudoreduced density.

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```

RN = -.27 * PR / TR
R = 2 * RN

Do 10, I = 1, 50
If (ABS(RN-R).LT..001) GO TO 20
R = RN
FR = A * R ** 6 + B * R ** 3 + C * R * R + D * R + E * R ** 3 *
  (1+F*R*R) * DEXP(-F*R*R) - G
FRP = 6 * A * R ** 5 + 3 * B * R * R + 2 * C * R + D
FRF = FRP + E * R * R * (3+F*R*R*(3-2*F*R*R)) * DEXP(-F*R*R)
RN = R - FR / FRP
10 Continue

20 Z = -.27 * PR / RN / TR

Return
End
*****
***** Subroutine SEPARAT
***** Author James Carroll
***** Date December, 1990
***** In-calls
***** Out-calls
***** Function
***** Models the flash separation of oil and gas with a two-
***** stage separation process. This subroutine serves mainly
***** to link the separator model to the rest of the program.
***** Subroutine SEPARAT(I)
*****
Implicit Double Precision (A-Z)
Integer N1, N2, IVMWEL, IMCTR, K, NMWEL, CORR, NMWELLS, IERR, IEEXE,
  IHC, IPRT, IUNIN, NMT, NSTEP, I

Parameter (N1 = 100, N2 = 500)
Dimension VGASP(0:N2), VGOR(0:N2), VOILP(0:N2), VPRSR(0:N2),
  VPRSMF(0:N2), VPRSMH(0:N2), VRTEG(0:N2), VRTEO(0:N2),
  VTIME(0:N2), IVMWEL(0:N2), TTMIN(N1), TRTEFM(N1),
  TRTEFT(N1), TSKN(N1), NMWELLS, TRTEFM, TRTEFT, TFMIN, TSKN, RADW,
  Common /TRANSI/ TTM, NMWELLS, TRTEFM, TRTEFT, TFMIN, TSKN, RADW,
  Common /SEP/ TSEP, PSEP
Common /TRANS4/ VGASP, VGOR, VOILP, VPRSR, VPRSMF, VPRSMH, VRTEG,
  VRTEO, VTIME, IMCTR, NMWEL, OILTI, GASTI, IVMWEL, K
Common /TBG/ API, GRVG, AROUGH, DIAM, LENGTH, TWF, TWH, SIGMAO,
  CORR

*----- Input is in Metric Units. Make necessary conversions to English
  units.
TSEP = TSEP * 1.8 + 460
TWH = TWH * 1.8 + 460
PSEP = PSEP * .14503774
GRVM = 1.
NSTEP = IDINT(DNINT(XMXTIM/DELTIM))
Call DENS(TSEP,PSEP,GRVG,GRVM,API,DENSO,DENSW,DENSG)

C Do 10 I = 1, NSTEP
  PMH = VPRSMH(I) * .14503374
  Call DENS(TWH,PMH,GRVG,GRVM,API,DENSO,DENSW,DENSG)
  QO = VRTEO(I) * 6.289811
  QG = VRTEG(I) * 35.314667

*----- If Oil and Gas rate is zero then dont flash!

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Wellmodel.For

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          If((QG.LE.0.0).AND.(QG.LE.0.0)) then
            Goto 99
          Else
            Endif
          Call FLASHCAL(TSEP,PSEP,DENSO,DENSG,QO,QG)
          VRTEO(I) = QO / 6.289811
          VRTEG(I) = QG / 35.314667
          C 10 Continue

          TSEP = (TSEP-460) / 1.8
          TWH = (TWH-460) / 1.8
          PSEP = PSEP / .14503774

          Return
        End

        *****
        ***** Subroutine FLASHCAL
        ***** Author James Carroll
        ***** Date December, 1990
        ***** In-calls
        ***** Out-calls
        ***** Function Controls the flash separation process.
        ***** Reference Notes from PE 251, Fall 1988, Dr. Orr, Stanford. The
        ***** Properties of Petroleum Fluids, McCain, 1973. Surface
        ***** Production Operations, Arnold and Stewart, 1986.
        ***** Classical Thermodynamics of Nonelectrolyte Solutions,
        ***** Van Ness and Abbot, 1982.
        *****
        ***** Variables:
        *****
        ***** (a alpha)j
        ***** ai
        ***** a1 coefficient of z^2
        ***** a2 coefficient of z
        ***** a3 constant coefficient
        ***** bi
        ***** bip binary interaction parameter
        ***** comp dummy composition
        ***** tol convergence criteria
        ***** f fugacity
        ***** flag flag for convergence
        ***** fx liquid fugacity
        ***** fy vapor fugacity
        ***** k k values (y/x)
        ***** name name of component
        ***** nc number of components
        ***** nx liquid mole fraction
        ***** ny vapor mole fraction
        ***** p pressure in psia
        ***** pc critical pressure in psia
        ***** t universal gas constant
        ***** sa sum of ai
        ***** sb sum of bi
        ***** sumaa sum of aa
        ***** t temperature in fahrenheit
        ***** tc critical temperature in rankine
        ***** vx liquid molar volume
        ***** vy vapor molar volume
        ***** w pitzer's accentric factor
        ***** x liquid composition
        ***** y vapor composition
        ***** z total mixture composition

        *****
        ***** Subroutine FLASHCAL(TSEP,PSEP,DENSO,DENSG,QO,QG)
        ***** Implicit Double Precision (A-Z)
        ***** Integer NC, FLAG, I
        ***** Dimension YI(9), X(9), Y(9), Z(9), AA(9,9), BI(9), COMP(9), F(9),
        ***** FX(9), FY(9), K(9)
        ***** Common /TP/ T, P, NC
        ***** Common /XY/ X, Y, Z, NX, NY, ZX, ZY
        ***** Common /MISC1/ AA, BI, COMP, F, SA, SB, V, VX, SB, V, VX, VY, R
        ***** Common /FUG/ FX, FY, K, TOL, FLAG
        ***** Common /Molar/ MLL, MGG
        ***** Set initial conditions.

        PSC = 14.696
        TSC = 520.
        MG = 25.
        MO = 90.
        R = 10.732
        TOL = 1D-2

        ***** Determine molar flow rate

        NT = QG * DENSG / MG + QO * DENSO * 5.615 / MO
        MLL = QO * DENSO * 5.615
        MGG = QG * DENSG

        Call INIT

        ***** Perform flash for first-stage separation

        P = PSEP
        T = TSEP

        Call EQUILIB

        NY1 = NY
        NX1 = NX

        Do 10 I = 1, NC
          Z(I) = X(I)
          Y(I) = Y(I)
        10 Continue

        ***** Perform flash for second-stage separation of oil stream

        P = PSC
        T = TSC

        Call EQUILIB

        NY2 = NY
        NX2 = NX
        VY2 = ZY
        VX2 = ZX

        ***** Perform flash for second-stage separation of gas stream

        P = PSC
        T = TSC

        Do 20 I = 1, NC
          Z(I) = Y(I)
        20 Continue

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Call EQUILIB
NY3 = NY
NX3 = NX
VY3 = ZY
VX3 = ZX

*----- Determine volumetric flow rates
NG = NY1 * NY3 * VY3 + VX3 * NX1 * NY2 * VY2
NO = NY1 * NK3 * VX3 + NK1 * NK2 * VX2
QG = NT * NG / DENSQ
QO = NT * NO / 5.615 / DENSO

C Write(6,'NG',NG,'NO',NO,'QG',QG,'QO',QO,'NT',NT)
Return
End
*-----
Subroutine EQUILIB
*----- Author James Carroll
*----- Date December, 1990
*----- In-calls
*----- Out-calls
*----- Function Controls the equilibrium determination process based
on flash calculations.
*----- Reference Notes from PE 251, Fall 1988, Dr. Orr, Stanford.
Classical Thermodynamics of Nonelectrolyte Solutions,
Van Ness and Abbot, 1982.
*-----
Subroutine EQUILIB
Implicit Double Precision (A-Z)
Integer NC, FLAG, I
Dimension X(9), Y(9), Z(9), AA(9,9), BI(9), COMP(9), F(9), FX(9),
FY(9), K(9)
Common /TP/ T, P, NC
Common /XY/ X, Y, Z, NX, NY, ZX, ZY
Common /MISC/ AA, BI, COMP, F, SA, SB, V, VX, VY, R
Common /FUG/ FX, FY, K, TOL, FLAG

*----- Flag: 1 = normal operation
*----- 2 = all vapor
*----- 3 = all liquid
*----- 4 = flash didn't converge in 500 iterations
*----- 5 = new k's are within tolerance

Call INITBIP
GUESS = 0.05D+00
10 NX = GUESS
FLAG = 1
COUNT = 0.

Call WILSON

20 If (FLAG.EQ.1) Then
Call FLASH
COUNT = COUNT + 1
SUMBP = 0
SUMDP = 0
Do 30 I = 1, NC
SUMBP = SUMBP + Z(I) * K(I)
SUMDP = SUMDP + Z(I) / K(I)

```

```

30 Continue
If ((SUMDP.LE.1.) .AND. (COUNT.GT.2.)) FLAG = 2
If ((SUMBP.LE.1.) .AND. (COUNT.GT.2.)) FLAG = 3
If ((FLAG.EQ.3) .AND. (GUESS.LT.1.)) Then
FLAG = 4
Else If ((FLAG.EQ.3) .AND. (GUESS.GE.1.)) Then
Do 40 I = 1, NC
X(I) = Z(I)
Y(I) = 0.
Continue
ZX = VX
ZY = 0.
NX = 1.
NY = 0.
Else If ((FLAG.EQ.2) .AND. (GUESS.LT.1.)) Then
FLAG = 4
Else If ((FLAG.EQ.2) .AND. (GUESS.GE.1.)) Then
Do 50 I = 1, NC
Y(I) = Z(I)
X(I) = 0.
Continue
ZY = VY
ZX = 0.
NY = 1.
NX = 0.
Else
Do 60 I = 1, NC
If (Y(I).LE.0) Y(I) = 0.00001
COMP(I) = Y(I)
Call MIXRULE
Call CUBIC
V = VY
ZY = VY
Call SRKFUG
Do 70 I = 1, NC
FY(I) = F(I)
Continue
Do 80 I = 1, NC
If (X(I).LE.0) X(I) = 0.00001
COMP(I) = X(I)
Continue
Call MIXRULE
Call CUBIC
V = VX
ZY = VX
Call SRKFUG
Do 90 I = 1, NC
FX(I) = F(I)
Continue
Call NEWK
End If
Go To 20
End If
If (FLAG.EQ.4 .AND. GUESS.LT.1.) Then
GUESS = GUESS + 0.05
Go To 10
Else If (FLAG.EQ.4 .AND. GUESS.GE.1.) Then
Write (6,5000)
Return
End If

```

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NY = 1 - NX

Return
5000 Format ('Failed to converge')

End
.....
Subroutine INIT
.....
Author James Carroll
Date December, 1990
.....
In-calls
.....
Out-calls
.....
Function Initializes flash separation data.
.....

Subroutine INIT
Implicit Double Precision (A-Z)
Integer NC, I
Character*16 NAME(9)
Dimension BIP(9,9), GAMMA(9), TC(9), PC(9), X(9), Y(9),
Z(9)
Common /TP/ T, P, NC
Common /TFC/ BIP, GAMMA, TC, PC, W
Common /CHAR/ NAME
Common /XY/ X, Y, Z, NX, NY, ZX, ZY

NC = 9

Z(1) = 0.8013
Z(2) = 0.0537
Z(3) = 0.0409
Z(4) = 0.0195
Z(5) = 0.0100
Z(6) = 0.0137
Z(7) = 0.0085
Z(8) = 0.0153
Z(9) = 0.0334

NAME(1) = 'METHANE'
NAME(2) = 'ETHANE'
NAME(3) = 'PROPANE'
NAME(4) = 'n-BUTANE'
NAME(5) = 'i-BUTANE'
NAME(6) = 'n-PENTANE'
NAME(7) = 'i-PENTANE'
NAME(8) = 'HEXANE'
NAME(9) = 'HEPTANE'

PC(1) = 667.80
PC(2) = 707.80
PC(3) = 616.30
PC(4) = 550.70
PC(5) = 529.10
PC(6) = 488.60
PC(7) = 490.40
PC(8) = 436.90
PC(9) = 421.90

TC(1) = -116.63 + 460.
TC(2) = 90.09 + 460.
TC(3) = 206.01 + 460.
TC(4) = 305.65 + 460.
TC(5) = 274.98 + 460.
TC(6) = 385.70 + 460.
TC(7) = 369.10 + 460.
TC(8) = 453.70 + 460.

TC(9) = 616.73 + 460.

W(1) = 0.0104
W(2) = 0.0986
W(3) = 0.1524
W(4) = 0.2010
W(5) = 0.1848
W(6) = 0.2539
W(7) = 0.2223
W(8) = 0.3007
W(9) = 0.3590

GAMMA(1) = 0.3000
GAMMA(2) = 0.3564
GAMMA(3) = 0.5077
GAMMA(4) = 0.5844
GAMMA(5) = 0.5631
GAMMA(6) = 0.6310
GAMMA(7) = 0.6247
GAMMA(8) = 0.6640
GAMMA(9) = 0.7653

Return
End

.....
Subroutine SRKFUG
.....
Author James Carroll
Date December, 1990
.....
In-calls
.....
Out-calls
.....
Function This subroutine computes fugacity of components using
the Soave Redlich Kwong equation of state.
Notes from PE 251, Fall 1988, Dr. Orr, Stanford.
Reference Classical Thermodynamics of Nonelectrolyte Solutions,
Van Ness and Abbot, 1982.
.....

Subroutine SRKFUG
Implicit Double Precision (A-Z)
Integer NC, I, J
Dimension AA(9,9), BI(9), COMP(9), F(9)
Common /TP/ T, P, NC
Common /MISC1/ AA, BI, COMP, F, SA, SB, V, VX, VY, R

Do 20 I = 1, NC

SUMAA = 0

Do 10 J = 1, NC

SUMAA = SUMAA + COMP(J) * AA(I,J)

10 Continue

DUM1 = DLOG(V/(V-SB)) + BI(I) / (V-SB)

DUM2 = (2.0*SUMAA/(R*T*SB)) * DLOG(V/(V+SB))

DUM3 = ((SA*BI(I))/(R*T*SB*SB)) * (DLOG((V+SB)/V) - SB/(V+SB))

DUM4 = DLOG((P*V)/(R*T*COMP(I)))

F(I) = P * DEXP(DUM1+DUM2+DUM3-DUM4)

20 Continue

Return

End

.....
Subroutine INITBIP
.....

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..... Author      James Carroll
..... Date        December, 1990
..... In-calls
..... Out-calls
..... Function    This subroutine initializes the array of binary
.....            interaction parameters. For SRK eos, hydrocarbon to
.....            hydrocarbon bip's are defined to be zero.
..... Reference   Notes from PE 251, Fall 1988, Dr. Orr, Stanford.
.....            Classical Thermodynamics of Nonelectrolyte Solutions,
.....            Van Ness and Abbot, 1982.
.....
.....
Subroutine INITBIP
Implicit Double Precision (A-Z)
Integer NC, I, J
Dimension BIP(9,9), GAMMA(9), TC(9), PC(9), W(9)
Common /TP/ T, P, NC
Common /TCPC/ BIP, GAMMA, TC, PC, W

Do 20 I = 1, NC
  Do 10 J = 1, NC
    BIP(I,J) = 0
  10 Continue
  20 Continue

Do 30 I = 2, NC
  BIP(I,1) = 0.1285713 * GAMMA(I) - 0.05857134
  BIP(I,1) = 0.1285713 * GAMMA(I) - 0.05857134
  30 Continue

Return
End
.....
..... Subroutine WILSON
..... Author      James Carroll
..... Date        December, 1990
..... In-calls
..... Out-calls
..... Function    Wilson equation is used to approximate the initial K
.....            values.
..... Reference   Notes from PE 251, Fall 1988, Dr. Orr, Stanford.
.....            Classical Thermodynamics of Nonelectrolyte Solutions,
.....            Van Ness and Abbot, 1982.
.....
.....
Subroutine WILSON
Implicit Double Precision (A-Z)
Integer NC, FLAG, I
Dimension FX(9), FY(9), K(9), BIP(9,9), GAMMA(9), TC(9), PC(9),
      W(9)
Common /TP/ T, P, NC
Common /FUG/ FX, FY, K, TOL, FLAG
Common /TCPC/ BIP, GAMMA, TC, PC, W

Do 10 I = 1, NC
  TR = T / TC(I)
  PR = P / PC(I)
  K(I) = DEXP(5.37*(1+W(I))*(1-1/TR)) / PR
  10 Continue

Return
End
.....
..... Subroutine FLASH
.....
.....

```

```

..... Author      James Carroll
..... Date        December, 1990
..... In-calls
..... Out-calls
..... Function    Given the overall composition (z) and the k values(k),
.....            it will find the liquid (x) and vapor (y) mole fractions.
..... Reference   Notes from PE 251, Fall 1988, Dr. Orr, Stanford.
.....            Classical Thermodynamics of Nonelectrolyte Solutions,
.....            Van Ness and Abbot, 1982.
.....
.....
Subroutine FLASH
Implicit Double Precision (A-Z)
Integer NC, FLAG, M, J, I, COUNT
Dimension X(9), Y(9), Z(9), FX(9), FY(9), K(9)
Common /TP/ T, P, NC
Common /XY/ X, Y, Z, NX, NY, ZX, ZY
Common /FUG/ FX, FY, K, TOL, FLAG

COUNT = 0

Do 30 J = 1, 500
  FL = 0
  DFDL = 0
  COUNT = COUNT + 1

Do 10 I = 1, NC
  FL = FL + (Z(I)*(1-K(I))) / ((K(I)+(1-K(I))*NX)**2)
  DFDL = DFDL - (Z(I)*(1-K(I)))**2 / ((K(I)+(1-K(I))*NX)**2)
  10 Continue

NEWNX = NX - FL / DFDL

If ((NEWNX.LE.0.) .AND. (COUNT.GT.5)) Then
  NX = 0.
  FLAG = 2
  Return
Else If ((NEWNX.GE.1.) .AND. (COUNT.GT.5)) Then
  NX = 1.
  FLAG = 3
  Return
End If

If ((ABS(FL).LT.TOL) .AND. (ABS(NEWNX-NX).LT.TOL)) Then
  NX = NEWNX
  Do 20 M = 1, NC
    X(M) = Z(M) / (K(M)+NX*(1-K(M)))
    Y(M) = K(M) * X(M)
  20 Continue
  Return
End If

NX = NEWNX
30 Continue

FLAG = 4
Return
End
.....
..... Subroutine MIXRULE
..... Author      James Carroll
..... Date        December, 1990
..... In-calls
.....

```


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End If
*----- Determine which is the correct root
If (NR.EQ.3) Then
  VX = DMINI(R1,R2,R3)
  VY = DMAXI(R1,R2,R3)
Else
  VX = R1
  VY = R1
End If
Return
End
*----- Subroutine NEWK
*----- Author James Carroll
*----- Date December, 1990
*----- In-calls
*----- Out-calls
*----- Function A successive substitution scheme is used to compute new
*----- K values for a flash calculation.
*----- Reference Notes from PE 251, Fall 1988, Dr. Orr, Stanford.
*----- Classical Thermodynamics of Nonelectrolyte Solutions,
*----- Van Ness and Abbot, 1982.
*----- Subroutine NEWK
Implicit Double Precision (A-Z)
Integer NC, FLAG, I
Dimension FX(9), FY(9), K(9)
Common /TP/ T, P, NC
Common /FUG/ FX, FY, K, TOL, FLAG
Do 10 I = 1, NC
  FRATIO = FX(I) / FY(I)
  K(I) = FRATIO * K(I)
  TEST = ABS(FRATIO-1.)
  If (TEST.LE.TOL) FLAG = 5
10 Continue
Return
End
*----- Subroutine Getcpu(Cpusec)
real*4 tarray(2),etime
real*8 Cpusec
cpusec = etime(tarray)
return
end
*----- Subroutine PLOTOUT(Cpu)
*----- VARIABLES AND CONSTANTS
Implicit Double Precision (A-Z)
Integer N1, N2, IVNWEI, NWELLS, I, IERR, IEIXE, IHC, IPRT, IUMIN,
* IWCTR, J, K, NWELL, NWT, CORR, NPVT, NRP, IC, IT, NSTEP
Character ZJC8ID*60, ZC(8)*6
Logical QMCTR, QSTOP, ICRIT
Parameter (N1 = 100, N2 = 500)
Dimension TPWMIN(N1), TRTEFM(N1), TRTEFT(N1), TSKN(N1), TTIM(N1),

```

```

*----- COMMON BLOCKS
Common /CONTAM/ NITRO, CO2, H2S, NAEL, RSI
Common /TBG/ API, GRVG, AROUGH, DIAM, LENGTH, TWF, TMH, SIGMAO,
* CORR
Common /PROP/ TDENRG, TDENRO, TFEVFG, TFEVFX, TFVFO, TGORS, TOGRS,
* TPRMRG, TPRMRO, PRMLGO, TPRS, TSATG, TVISG, TVISO, NPVT, NRP
Common /MBAL1/ AG1, A01, CMPF, DTIM, POR1, PRSI, RGI, ROI, SATWI,
* VOLBW
Common /MBAL2/ AO2, AG2, RO2, RG2, RGAU
Common /MBAL3/ DENRG, DENRO, FVFG, FVFO, GORS, OGRS, POR, PRMGO,
* SATG1, SATO1, VISG, VISO, XMBAL1
Common /IPRI/ PRINT, DSKN, PRM, RADEQ, SKN, THK
Common /ICOUNT/ IC, IT
Common /FINANCE/ INFRATE, DISRATE, OILPRIC, GASPRIC
Common /TRANS1/ TTIM, NWELLS, TRTEFM, TRTEFT, TPWMIN, TSKN, RADW,
* DELTIM, MXITIM, HCPV, IHC, IUMIN, IPRT, IEIXE, NWT, IERR, NSTEP
Common /TRANS2/ C1, C2, C3, C4, C5, C6, C7, C8, C9
Common /TRANS3/ ZC, ZJOBID
Common /TRANS4/ VGASP, VGOR, VOILP, VPRSR, VPRSWF, VPRSMH, VRTEG,
* VRTEO, VTIME, IWCTR, NWELL, OILTI, GASTI, IVNWEI, K
Common /RESULTS/ NPV, NPVI
Common /FLOW/ ICRIT
Common /SEP/ TSEP, PSEP
Common /BHRATE/ VRTEO1, VRTEG1
Open (Unit=9,File='Oil')
Open (Unit=10,File='Gas')
Open (Unit=11,File='Resp')
Open (Unit=12,File='Bhp')
Open (Unit=13,File='Fcp')
Open (Unit=14,File='OilPS')
Open (Unit=15,File='GasPS')
Open (Unit=16,File='Cost')
Write(9,*)NSTEP
Do I=1,NSTEP
  Write(9,*)I, VRTEO1(I)*6.2898
End do
Write(14,*)NSTEP
Do I=1,NSTEP
  Write(14,*)I,VRTEO1(I)*6.2898
End do
Write(15,*)NSTEP
Do I=1,NSTEP
  Write(15,*)I,VRTEG1(I)*35.14
End do
Write(10,*)NSTEP
Do I=1,NSTEP

```

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Write(10,*)I,VRTEGI(I)*35.14
End do
Write(11,*)NSTEP
Do I=1,NSTEP
Write(11,*)I,VPRSR(I)*(14.74/101.325)
End do
Write(12,*)NSTEP
Do I=1,NSTEP
Write(12,*)I,VPRSMF(I)*(14.74/101.325)
End do
Write(13,*)NSTEP
Do I=1,NSTEP
Write(13,*)I,VPRSMH(I)*(14.74/101.325)
End do
Write(16,*)NSTEP
Do I=1,NSTEP
Write(16,*)I,NPVI(I)
End do
Close (Unit=9)
Close (Unit=10)
Close (Unit=11)
Close (Unit=12)
Close (Unit=13)
Close (Unit=14)
Close (Unit=15)
Close (Unit=16)
Return
End
```

END

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