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### **Influence of a Vacuum Region on the Stability of a High-Beta Screw Pinch**

# **MASTER**



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## **Influence of a Vacuum Region on the Stability of a High-Beta Screw Pinch**

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**by**

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#### **ABSTRACT**

**To ascertain the influence of a vacuum region on the stability of a high-f} screw pinch, the stability properties of two confinement configurations are compared. Both configurations Involve diffuse equilibrium profiles and a** rigid, perfectly conducting cylindrical shell. In the first **problem, perfectly conducting plasma extends to the rigid conducting wall; the plasma is extremely tenuous in the outer region of the pinch, however. In the second case, profiles identical to those of the first problem are chosen for the central portion of the pinch, but the outer tenuous plasma is replaced by a perfectly insulating vacuum region. The two configurations are found to be unstable for the same range of external parameter values; different modes are unstable in the two cases, however. Thus, the presence of a vacuum region does not affect the stability boundary of the pinch, but it does affect the nature of the unstable modes.**

#### **I. INTRODUCTION**

**In ideal magnetohydrodynamic (MHD) stability analyses of high-g pinch configurations, an uncertainty concerning the outer portion of the pinch is frequently encountered. In many Instances, experimental measurements suggest equilibrium profiles in which current density, pressure, and mass density in the outer region are negligible compared with their values in the central portion of the pinch. Therefore, in the outer region, the magnetic field closely approximates a vacuum field. The uncertainty is this. Does the plasiaa really extend to the vacuum vessel, or does a vacuum region separate the plasma column and the wall? The boundary conditions appropriate for a linear stability analysis are different for the two configurations; therefore, the eigenvalues that result may also differ. The objective of this report is**

to shed some light on the Influence which the outer portion of the pinch exerts on MHD stability.

To ascertain the influence of a vacuum region on the stability of a high- $\beta$  screw pinch, we compare the stability properties of two configurations. Both configurations involve diffuse equilibrium profiles and a rigid, perfectly conducting cylindrical shell. In the first problem, perfectly conducting plasma extends to the rigid conducting wall; the plasma is extremely tenuous in the outer region of the pinch, however. In the second problem, profiles identical to those of the first problem are chosen for the central portion of the pinch, but the outer tenuous plasma is replaced by a perfectly insulating vacuum region. On one hand, the nature of the equilibrium magnetic field in the outer region, together with the very small mass density suggest that there is little distinction between the two configurations. But on the other hand, the electrical conductivity Is uniform throughout the domain of inter st in one case, while in the other case an Interface between perfectly conducting plasma and perfectly Insulating vacuum divides the domain. It is well known that certain perturbations (surface waves) propagate along such surfaces of discontinuity. Since these perturbations may be unstable, and because surface waves have no counterpart in continuous media, a real distinction may exist between" the two configurations. We shall find that the presence of a vacuum region does not affect the stability boundary of the pinch. It does affect the nature of the unstable modes, and their growth rates, however.

The report is organized as follows. The stability problems for the two configurations are formulated in Sec. II. Numerical results are presented in Sec. III. Results are summarized and conclusions are presented in Sec. IV.

#### II. TWO STABILITY PROBLEMS

We use the linearized equations of ideal magnetohydrodynamics in standard cylindrical polar coordinates to examine the stability of diffuse screw pinch equilibria. The equilibrium density,  $\rho$ , pressure,  $p$ , and the magnetic field components,  $B_{\theta}$  and  $B_{z}$ , are functions only of the radial coordinate, r, and they satisfy the equations of ideal magnetohydrostatics,

 $\overline{\mathbf{2}}$ 

$$
\left[p + \frac{1}{2} (B_0^2 + B_2^2)\right] \cdot + \frac{B_0^2}{r} = 0 \quad , \tag{1}
$$

**where a prime denotes diffentiation with respect to r. We use a system of units whose characteristic length, mass, and time are defined in terms of the following physical quantities: 1) the equivalent sharp-boundary radius of the** pinch, a; 2) the mass density measured on axis,  $\rho_0$ ; 3) The magnetic field measured for from the plasma, B<sub>za</sub>.

**Numerical results presented in Sec. Til are obtained using the rigid-rotor profiles of Ref. 1,**

$$
\rho(r) = \rho_0 \frac{\mathrm{sech}^2 (r^2/r_0^2 + \alpha)}{\mathrm{sech}^2 \alpha} \quad , \tag{2}
$$

$$
B_z(r) = B_{z\omega} \tanh (r^2/r_0^2 + \alpha)
$$
 (3)

$$
B_{\theta}(r) = \mu B_{z\omega} \left(\frac{r_0}{r}\right) \frac{\tanh (r^2/r_0^2 + \alpha) - \tanh \alpha}{1 - \tanh \alpha} \qquad , \qquad (4)
$$

where the parameter  $\alpha$  is related to the plasma  $\beta$  by  $\beta$  = sech<sup>2</sup> $\alpha$ , and  $r_0$  = [1 + **(1 - B)l/2]l/2 a.**

Equations  $(1)-(4)$  specify the equilibria in terms of two parameters,  $\beta$ and  $\mu$ . We shall consider two specific equilibria. In the first example, the **plasma is assumed to extend to a rigid perfectly c 'ducting cylindrical shell located at**  $r = r_w$ **; we shall designate this as the P-W system.** In the second case, the plasma region consists of a cylinder of radius r<sub>p</sub> which is enclosed **by a perfectly conducting shell of radius rw > r ; a vacuum region exists between the cylindrical surfaces**  $r = r_p$  **and**  $r = r_w$ **. We shall designate the second configuration as P-V-W system. The two configurations have identical** equilibrium profiles for  $r < r_p$ .  $r_p$  is chosen sufficiently large so that  $p(r = r_0)$   $\langle\langle p(r = 0) \rangle$  and also so that the magnetic field closely approximates **a vacuum field. Surface currents are permitted to flow along the plasma-vacuum interface of the P-V-W system in order that the two configurations exhibit the same values for the magnetic field components at**

the conducting wall,  $r = r_w$ . Thus, the two configurations carry the same axial current. The essential difference between them is that the tenuous **outer region in the P-W system is replaced by a vacuum region in the P-V-W system. This difference is manifest in the profiles of the electrical conductivity. The electrical conductivity is uniform throughout the domain of interest, (0,rw), for the P-W system; an interface between perfectly conducting plasma and perfectly insulating vacuum divides the domain of the P-V-W system.**

**The displacement formulation of linearized MHD is used for the stability analyses. Because of the symmetries of the equilibria, perturbation quantities are assumed to be of the form,**

$$
f(r,\theta,z,t) = f(r) \exp[i(\pi\theta + kz - \omega t)],
$$

where m, k, and w are parameters. These parameters must be chosen so that the displacement,  $\xi = \xi_r \hat{r} + \xi_\theta \hat{\theta} + \xi_z \hat{z}$ , satisfies the equation of motion,

$$
-\rho\omega^2 \xi + \nabla P = T \tag{5}
$$

**and appropriate boundary conditions. The relationship between u and the other parameters is expressed by the other dispersion differential equation which is derived from Eq. (5). In Eq. (5), P is the total perturbed pressure and T is** the tension vector, both of which may be expressed in terms of  $\xi_r$ ,  $\xi_{\beta}$ , and  $\xi_z$ , **and equilibrium quantities. When algebraic quantities are eliminated, Eq. (5) becomes**

$$
\left\{\frac{(\rho\omega^{2} - F^{2})[\rho\omega^{2}(\gamma p + B^{2}) - \gamma p F^{2}]}{r\Delta} (r\xi_{r})^{2}\right\}^{2} + (\rho\omega^{2} - F^{2})\xi_{r}
$$
  
- 2 B<sub>0</sub> $\frac{B_{\theta}}{r}$  $\gamma \xi_{r} - \frac{4k^{2}B_{\theta}^{2}}{r^{2}\Delta} (\rho\omega^{2}B^{2} - \gamma p F^{2})\xi_{r}$   
-  $\frac{2kB_{\theta}(kB_{\theta} - \frac{m}{r}B_{z})[\rho\omega^{2}(\gamma p + B^{2}) - \gamma p F^{2}]}{r^{2}\Delta} \xi_{r} = 0$  (6)

**where y is the ratio of specific heats,**

$$
B^2 \equiv B_\theta^2 + B_z^2 \qquad , \qquad (7)
$$

$$
F \equiv kB_{z} + \frac{m}{r} B_{\theta} \qquad , \qquad (8)
$$

$$
\Delta \equiv (\rho \omega^2)^2 - (k^2 + \frac{m^2}{r^2}) [\rho \omega^2 (\gamma p + B^2) - \gamma p F^2] \qquad . \qquad (9)
$$

#### **A. P-W Stability**

**Equation (6) applies to the entire domain. Appropriate boundary conditions are**

$$
\xi_r(r = 0) = \text{finite},\tag{10}
$$

**and**

$$
\xi_{\mathbf{r}}(\mathbf{r} = \mathbf{r}_{\omega}) = 0. \tag{11}
$$

Equations (6), (10), and (11) determine  $\omega$  and  $\xi_r(r)$  for given m, k, and **equilibrium profiles**  $\rho(r)$ **,**  $p(r)$ **,**  $B_\theta(r)$ **, and**  $B_z(r)$ **.** 

#### **B. P-V-W Stability**

**Equation (6) applies only to the plasma region. In the vacuum region, the source-free Maxwell equations determine the electromagnetic field. The solutions in the two regions are matched at the plasma-vacuum interface. This** interface is displaced from its equilibrium position,  $r = r_p$ , and its shape is **distorted by the perturbation. The linearized equation of the perturbed interface is**

$$
r = r_n + \xi_r(r_n) \exp\left[i(m\theta + kz - It)\right] \quad . \tag{12}
$$

The unit normal,  $\hat{n}$ , to the surface of the perfectly conducting plasma is

$$
\hat{\mathbf{n}} = \hat{\mathbf{r}} - i\left(\frac{\mathbf{m}}{\mathbf{r}_p}\hat{\mathbf{e}} + k\hat{\mathbf{z}}\right)\mathbf{\xi}_r(\mathbf{r}_p)\exp\left[i(\mathbf{m}\theta + k\mathbf{z} - \mathbf{w}\mathbf{t})\right]
$$
 (13)

**In the vacuum region bounded by the perturbed piassa-vacuum Interface and the rigid,** perfectly conducting wall at  $r = r_w$ , the perturbed magnetic field has **the following components.**

$$
\delta B_{r}^{V} = i\left(\frac{m}{r_{p}} B_{\theta}^{V} + kB_{z}^{V}\right)\xi_{r}(r_{p}) - \frac{\left[K_{m}^{\prime}(|k|r) - I_{m}^{\prime}(|k|r)\frac{K_{m}^{\prime}(|k|r_{w})}{I_{m}^{\prime}(|k|r_{w})}\right]}{\left[K_{m}^{\prime}(|k|r_{p}) - I_{m}^{\prime}(|k|r_{p})\frac{K_{m}^{\prime}(|k|r_{w})}{I_{m}^{\prime}(|k|r_{w})}\right]},
$$
\n(14)

$$
\delta B_{\theta}^{V} = -\frac{\underline{m}}{|k|r} \left( \frac{\underline{m}}{r_{p}} B_{\theta}^{V} + kB_{z}^{V} \right) \xi_{r}(r_{p}) - \frac{\left[ K_{\underline{m}}(|k|r) - I_{\underline{m}}(|k|r) \frac{K_{\underline{m}}^{V}(ik|r_{w})}{I_{\underline{m}}^{V}(ik|r_{w})} \right]}{\left[ K_{\underline{m}}^{V}(ik|r_{p}) - I_{\underline{m}}^{V}(ik|r_{p}) \frac{K_{\underline{m}}^{V}(ik|r_{w})}{I_{\underline{m}}^{V}(ik|r_{w})} \right]}, \quad (15)
$$

$$
\delta B_Z^V = -\frac{k}{|k|} \left( \frac{m}{r_p} B_\theta^V + kB_z^V \right) \xi_T(r_p) \frac{\left[ K_m(|k|r) - I_m(|k|r) \frac{K_m^Z(|k|r_w)}{I_m^Z(|k|r_w)} \right]}{\left[ K_m^Z(|k|r_p) - I_m^Z(|k|r_p) \frac{K_m^Z(|k|r_w)}{I_m^Z(|k|r_w)} \right]},
$$
(16)

where K<sub>m</sub> and I<sub>m</sub> are modified Bessel functions of order m, primes designate differentiation of these functions with respect to the<sup>1</sup>r argument, and B<sub>0</sub> and  $B^V_z$  are the  $\theta$  and z components of the equilibrium magnetic field in the vacuum **region.**

**Now, we impose force balance at the perturbed plasma-vacuum interface, finding:**

$$
\frac{(\rho\omega^{2} - F^{2})[\rho\omega^{2}(\gamma p + B^{2}) - \gamma pF^{2}]}{\Delta} \frac{(\mathbf{r}\xi_{r})^{2}}{(\mathbf{r}\xi_{r})|_{r} = r_{p}} = \frac{B_{0}^{\gamma^{2} + B_{0}^{2}}}{r_{p}}
$$
  

$$
(\mathbf{k}B_{z}^{\gamma} + \frac{m}{r_{p}}B_{0}^{\gamma})^{2} \frac{[\kappa_{m}(|\mathbf{k}|r_{p}) - I_{m}(|\mathbf{k}|r_{p})\frac{K_{m}^{\prime}(|\mathbf{k}|r_{w})}{I_{m}^{\prime}(|\mathbf{k}|r_{w})}]}{[\kappa_{m}^{\prime}(|\mathbf{k}|r_{p}) - I_{m}^{\prime}(|\mathbf{k}|r_{p})\frac{K_{m}^{\prime}(|\mathbf{k}|r_{w})}{I_{m}^{\prime}(|\mathbf{k}|r_{w})}]}
$$

$$
+\left[\frac{2kB_{\theta}(kB_{\theta}-\frac{m}{r}B_{z})\rho\omega^{2}B^{2}}{r\Delta}+\frac{2k\gamma B_{\theta}(kB_{\theta}-\frac{m}{r}B_{z})(\rho\omega^{2}-F^{2})}{r\Delta}\right]_{r=r_{p}},
$$
\n(17)

**where p, p, Bg and Bz are equilibrium quantities in the plasma region.** For the P-V-W system, Eq. (6), the regularity condition at r=0,

$$
\xi_r(r = 0) = \text{finite},\tag{18}
$$

**and Eq. (17) determine u and £r(r) for given m, k, and equilibrium profiles. Equations (14) - (16) determine the perturbed vacuum magnetic field; Eq. (12) determines the position and shape of the perturbed interface.**

#### **III. NUMERICAL RESULTS**

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**In this =Tction we present numerical results obtained from the dispersion differential equation for the P-W system, Eqs. (6), (10), and (11), and the P-V-W system, Eqs. (6), (17), and (18).**

**In Fig. 1, the growth rate squared is plotted against axial wavevector, ka,** for  $m = 1$ ,  $\beta = 0.5$ ,  $\mu = 0.3$ ,  $r_p = 2.0 r_0$ , and  $r_w = 4.0 r_0$ . For  $\{ka\} \ge$ **0.06, the eigenvalues for the P-W and P-V-W system do not differ preceptlvely**

**and only one solution, w(k), i« shown; for these modes the singular surface, defined by**  $F(r_g) \equiv (kB_g + \frac{m}{r}B_g)|_{r_g} = 0$ , occurs at  $r = r_g < r_p$ . The growth **rates for the P-W and P-V-W systems differ considerably when |ka| < 0.06; in** this case the singular surface occurs at  $r = r_c > r_n$ . The singular surface **lies in the vacuum region of the P-V-W system and the growth rates of these modes are considerably larger than those of the P-W system. Both the P-W and P-V-W system are stable when the singular surface reaches the conducting wall**  $r_{\rm g}$  =  $r_{\rm w}$  (ka = -0.014). Thus, the two configurations are unstable for the **same range of ka, but the growth rates of the unstable modes can be considerably different for the two systems.**

**Figure 2 shows the eigenfunctions,**  $\xi_r(r)$ **, of the unstable modes of the P-W** and P-V-W systems when ka = -0.07,  $m = 1$ ,  $\beta = 0.5$ ,  $\mu = 0.3$ ,  $r_n = 2.0$  r<sub>0</sub>, and  $r_w = 4.0 r_0$ . In this case the eigenvalues are almost identical, and the eigenfunctions do not differ perceptibly for  $r/r_0 \le 2.0$ . For the P-V-W system, the plasma solution is joined to the vacuum solution at  $r/r_0 = 2.0$ ; the displacement  $\xi$  is not defined for  $r/r_0 > 2.0$ . In the P-W system, the **displacement is defined for the entire domain**  $0 \le r/r_0 \le 4.0$ **.** The singular surface for these modes lies in the plasma region,  $r_s < r_p$ .

The flow fields associated with the unstable modes of the P-W and P-V-W systems are shown in Figs. 3 and 4, respectively, for the parameter value given in Fig. 2. The region  $r/r_0 < 2.0$  is shown. An arrow depicts the displacement vector associated with the position at the tail of the arrow. The two flow patterns do not differ perceptively. These flow fields are **Indicative of internal or bulk modes which translate the cross section of the** plasma; recirculation occurs in the vicinity of the singular surface,  $r/r_0$ **plasma; recirculation occurs in the vicinity of the singular surface, T/TQ ~**

**Figure 5 shows the eigenfunctions,**  $\xi_{\text{r}}(\text{r})$ **, of the unstable modes of the P-V-W and P-W systems when the singular surface occurs in the vacuum region, P-V-W and P-W systems when the singular surface occurs in the vacuum region,**  $r_s$  /  $r_p$ , a =  $\sim$ 0.04, m  $\sim$  1, p = 0.5,  $\mu$  = 0.5,  $r_p$  = 2.0 r<sub>Q</sub>, and  $r_w$  = 4.0 r<sub>Q</sub>. The eigenfunctions reflect the differences in the eigenvalues and are considerably different also. In the P-W system, the eigenfunction resembles the one shown in Fig. 2; but in the P-V-W system, the eigenfunction now attains its maximum value at the edge of the plasma, whereas in Fig. 2, it attains its minimum value there. A perturbation which decreases wapidly with **attains its minimum value there. A perturbation which decreases rapidly with distance from the boundary is characteristic of a surface mode.<sup>2</sup>\* 3**





**Fig. 1. Growth rate squared versus axial wavevector. The two curves do not differ perceptively when |ka| > 0.06. Mode structures are examined in Figs. 2-4** for  $ka = -0.07$ , and in Figs.  $5-7$  for  $ka = -0.04.$ 

**Fig. 2. Eigenfunctions associated with unsta** $ble$  modes with  $ka = -0.07$ . The two **functions do not differ perceptively in the range**  $0 \le r/r_0 \le 2.0$ **.** 





**Fig. 3. Flow pattern for the P-W mode. The** region  $r/r_0$  < 2.0 is shown.

**Fig. 4. Flow pattern for the P-V-W mode. The** region  $r/r_0 \leq 2.0$  is shown.

Other features of the unstable modes may be distinguished from their **flow** fields which are shown in Fig. 6, for the P-W system, and Fig. 7, for the P-V-W system; parameter values are the same as in Fig. 5. The region  $r/r_0$  < 2.0 is shown. For the P-W system, the flow field resembles the one in Fig. 3. The flow causes translation of the cross section of the plasma; recirculation occurs near the singular surface,  $r = r_s > r_p$ , which is outside the field of view. This is an internal or bulk mode. The flow pattern of the unstable





Fig. 6. Flow pattern for the P-W mode. The region  $r/r_0$  < 2.0 is shown.



Fig. 5. Eigenfunctions associated with unstable modes with ka =  $-0.04$ . The P-V-W eigenfunction is typical of a surface mode.



Flow pattern for the **P-V-W mode. The** region  $r/r_0$  < 2.0 is shown.

P-V-W mode, Fig. 7, is completely different. There is no recirculation; rather, the mode peels-off the edge of the plasma column.

Figures 5 and 7 indicate that the P-V-W system supports unstable surface modes. The growth rates of the modes depend upon the properties of plasma in the vicinity of the interface; this is a general feature of surface modes.

#### IV. DISCUSSION

We have compared the stability properties of two screw pinch equilibria in order to ascertain the influence of a vacuum region on MHD stability. We have found that the stability boundary for this pinch is not affected when the outer tenuous plasma is replaced by a vacuum region. The presence of a vacuum region does affect the nature of the unstable modes and their growth rates, however. The P-W system supports only bulk modes; but the P-V-W system supports both bulk modes and surface modes. Surface modes have no counterpart in the P-W system. On the other hand, some of the bulk modes of the P-W system have no counterpart in the P-V-W system. Some of the P-W bulk modes are unstable, but they cannot exist in the P-V-W configuration; unstable surface modes appear in the latter configuration which cannot exist in the former. Thus, the presence of a vacuum region does not affect the stability boundary of the pinch, but it does affect the nature of the unstable modes and their growth rates.

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