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# KACHINA: an Eulerian Computer Program for Multifield Fluid Flows

by

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KACHINA: AN EULERIAN COMPUTER PROGRAM  
FOR MULTIFIELD FLUID FLOWS

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Anthony A. Amuden and Francis B. Harlow

ABSTRACT

Many fluid flow problems of interest involve the presence of bubbles, droplets, or chunks in a fluid. Because of the resulting likelihood for relative motion, more than one set of field variables is required to describe the dynamics. Until recently, numerical techniques for studying such flows have had very limited usefulness. This report presents a new computing program, named KACHINA, that significantly advances the ability to handle multifield flows. KACHINA uses the powerful new Implicit, Multifield (IMF) computing method for handling different material fields, in which the multifield treatment is coupled with an implicit formulation of the equations, permitting calculation of fully interpenetrating flows that at any instant may have both supersonic and far subsonic or incompressible regions in the domain of interest. Although IMF-KACHINA development is a continuing project, the results have already proved its usefulness, even in its present state. This report includes the current KACHINA flow diagram and program listing.

1. BASIC DESCRIPTION OF THE COMPUTING METHOD

A. Introduction

The Implicit Continuous-fluid Eulerian (ICE) method<sup>1</sup> has become well known and widely accepted since its introduction, as it was the first technique to afford a means for numerical solution of multidimensional flows in which the Mach number might range from zero (the incompressible limit) to greater than unity (the supersonic regime). The ICE concept has been recast in various formulations; for example, in the YAQUI program,<sup>2</sup> ICE was combined with the Arbitrary Lagrangian-Eulerian (ALE) technique,<sup>3</sup> to provide the additional capability of fully variable zoning and rezoning. Other programs based on the ICE concept have included effects such as reactive chemistry,<sup>4</sup> magnetohydrodynamics,<sup>5</sup> and multiple fluids.<sup>6</sup> This ability to calculate a wide variety of flows has contributed significantly to an understanding of atmospheric explosion phenomena,

laser design theory, plasma physics in the CTR program, many flows in biological systems, and even advanced astrophysical concepts, to name just a few.

Development of numerical techniques still has a long way to go, however, in providing man an understanding of all the fluid dynamic processes that interest him. One common type of flow has defied really successful numerical modeling. It involves the presence of bubbles, droplets, or chunks in a fluid, implying that relative motions must be considered, and a complex set of field variables is required to describe the dynamics with any accuracy. Examples of such flows are:

- Ordinary snow, rain, or hail falling through the atmosphere.
- Cavitation or flashing flow, in which bubbles of vapor are formed from the fluid itself. (Visualize the formation of steam by boiling,

or the propagation of a flame front through a confined explosive such as encased gunpowder.)

- Liquid or vapor rising through a bed of solid grains in a fluidized dust bed.
- Jet entrainment, in which immiscible or mutually diffusing liquid droplets are carried along or mixed with another liquid.

Until recently, numerical techniques for examining such multifield processes were extremely limited. A powerful new computing technique,<sup>7</sup> known as the Implicit, Multifield (IMF) method and based, once again, on ICE, is now available to help overcome these limitations and thus significantly advance the art of modeling multifield flows. This report discusses a program named KACHINA, which embodies the IMF methodology. Our treatment is based upon an implicit formulation of the coupled set of differential equations for multidimensional, multifield flow. Because of the program's Eulerian aspects, it can follow completely interpenetrating material motions over long periods of time, and because of the implicit treatment of mass convection and the equation of state, the flows at any instant may have both supersonic and far subsonic regions in the domain of interest. Further, the implicit coupling of the fields allows forces to range from negligibly weak to strong enough to tie the fields together completely. The program also can pile up a particulate field into a close-packed region with a variable boundary position, and possibly reopen such a region later.

Development of IMF and KACHINA is an expanding and continuing project. In its present basic state, KACHINA is still fairly limited and does not take into account a number of physical processes that will be required for future applications. It has, however, proved its usefulness even at this point, and has permitted meaningful calculations of a variety of one- and two-dimensional two-field flow situations that could not have been made using previous techniques. This report includes the current version of the KACHINA flow diagram and program listing. The derivation of the technique is fully described in Ref. 7, which also includes examples of a variety of test calculations illustrating some of KACHINA's capabilities. We therefore omit such aspects here, and concentrate on the solution pro-

cedure and the equations as they appear in KACHINA.

## B. The Variables and the Computing Mesh

For simplicity, we presently limit our consideration to two primary material fields, although the IMF principle is not restricted to these two, but will be developed further into a three-field model, including full treatment of phase transitions among the fields. We label these two fields "vapor" and "droplets." The vapor field may be considered to be a gas in bubble form or with dispersed droplets in it, and the droplet field to be a fluid or an aggregate of solid particles. The components of each field have constituents and properties that can vary in space and time, but pressure is assumed to be in local equilibrium between the two fields. The pressure is related directly to the equation of state of the vapor when the droplet field is dispersed, or to the maintenance of incompressibility when the droplet field is close-packed.

At present, the coupled fields are represented on a two-dimensional axisymmetric grid of fixed Eulerian cells through which the fluid moves. Cells have uniform dimensions  $\delta r$  and  $\delta z$ , measured in the radial ( $r$ ) and axial ( $z$ ) directions, respectively, and they are labeled by indices located at their centers, with  $i$  counted in the  $r$  direction and  $j$  in the  $z$  direction. The mesh of cells is  $\bar{I}$  cells wide by  $\bar{J}$  cells high, as shown in Fig. 1.

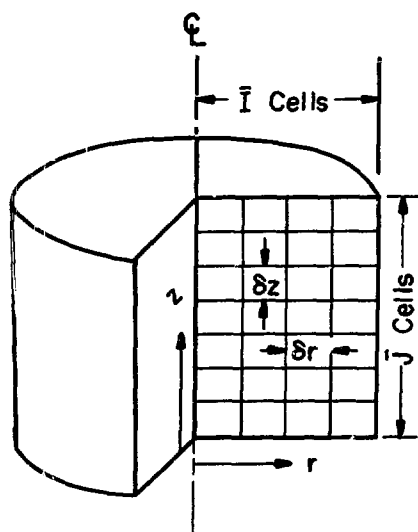


Fig. 1. The KACHINA axisymmetric two-dimensional computing mesh.

Variables may be defined either at cell centers or at cell edges, in which case they are labeled by half-integer indices in the finite-difference notation. The location of the principal KACHINA variables about a cell (i,j) is illustrated in Fig. 2, where u and v are velocity components in the radial and axial directions, respectively,  $\rho$  is the density, and I is the specific internal energy. Each of these four variables has both vapor and droplet components, denoted by the subscripts "v" and "d," respectively. The pressure, p, has only a single value in the cell because of the local equilibrium between the two fields.

The treatment of such a mixture of droplets and vapor, and the procedure for applying the equation of state to the vapor, requires a knowledge of the proportions of vapor and droplets within any given cell volume. For this purpose, we use the void fraction,  $\theta$ , defined as the volume per unit total volume occupied by vapor. Consequently,  $(1-\theta)$  is the volume per unit total volume occupied by droplets.

In addition, we allow two components within each field, designating them by subscripts 1 and 2. One must be able to describe the varying relative proportions of the two components in a way that ensures the separate conservation of each. For either field,

$$\theta_1 = \theta_2 \quad ,$$

and

$$\rho' \equiv \rho_1' + \rho_2' \quad ,$$

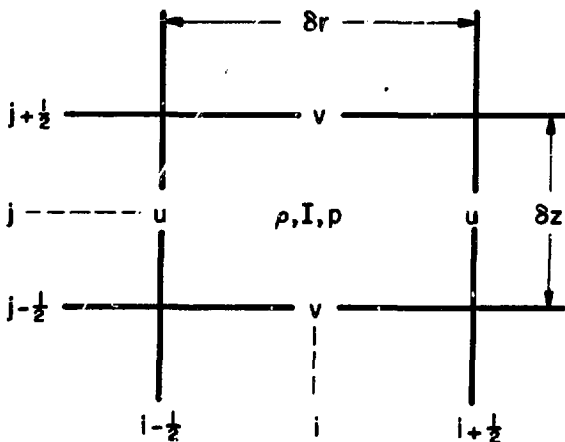


Fig. 2. Location of variables and indices about a KACHINA cell.

in which the prime signifies the mass per unit total volume. For the droplets, we use conservative explicit equations to transport the two densities  $\rho_{d1}'$  and  $\rho_{d2}'$ , and get the value of  $\rho_d'$  simply by subtraction when necessary. Then, with the corresponding normal material densities  $\rho_1$  and  $\rho_2$  defined, microscopic incompressibility allows derivation of an expression for the region's effective  $\theta$ .

For the vapor, an equation for  $\rho_v'$ , the sum of the two vapor densities, is required for the implicit coupling with the momentum equations. After this advanced-time density and the corresponding advanced-time velocities have been determined,  $\rho_{v1}'$  can be obtained by means of a second implicit solution. As in the case of the droplets, the value of  $\rho_{v2}'$  is available by subtraction when needed.

Thus, it is seen that the complete arrays of four densities must be stored and maintained, two for each field, and that we have chosen these to be  $\rho_{d1}'$  and  $\rho_d'$  for the droplets, and  $\rho_{v1}'$  and  $\rho_v'$  for the vapor.

The input data used to create the droplet and vapor fields specify the initial values of  $\rho_{d1}'$ ,  $\rho_{d2}'$ ,  $\rho_{v1}'$ ,  $\rho_{v2}'$ ,  $I_v$ , and  $I_d$  for all cells of the mesh, where  $\rho_{v1}$  and  $\rho_{v2}$  are the actual microscopic (partial) densities of the two vapor components. Using this information, one may place  $I_v$ ,  $I_d$ , and  $\rho_{d1}'$  directly in cell storage, but generation of the initial fields of  $\rho_d'$ ,  $\rho_{v1}'$ , and  $\rho_v'$ , along with  $\theta$ , requires some preliminary calculation.

- The field of  $\rho_d'$  is formed simply from the sum of  $\rho_{d1}'$  and  $\rho_{d2}'$ .
- With the normal material densities  $\rho_1$  and  $\rho_2$  of the droplet field components also specified in the input data, the initial void fraction is obtained from the relationship

$$\theta = 1 - \frac{\rho_{d1}'}{\rho_1} - \frac{\rho_{d2}'}{\rho_2} \quad .$$

- The values of  $\rho_{v1}$  and  $\rho_{v2}$  are then combined with  $\theta$  to obtain the fields of  $\rho_{v1}'$  and  $\rho_v'$ :

$$\rho_{v1}' = \theta \rho_{v1} \quad ,$$

$$\rho_v' = \theta (\rho_{v1} + \rho_{v2}) \quad .$$

Care must be taken to ensure that the input data are not specified incorrectly so that  $\theta < 0$  results.

In the present code, the dynamics are assumed to arise from pressure gradients from internal heat sources, or as the result of externally applied boundary conditions and/or gravitational effects. Therefore, all four velocity components,  $u_v$ ,  $u_d$ ,  $v_v$ , and  $v_d$  are initially set to zero throughout the interior of the mesh.

Because the vapor and droplet fields are bound by forces that can create conditions ranging from a complete tying together to the allowance of freely independent motion, a drag function,  $K$ , is used to relate the momentum exchange between the fields.

Other cell quantities will be introduced in the discussion of the full calculation cycle, but those described so far may be considered the principal KACHINA variables.

Solution of the dynamics evolves through a sequence of cycles, or time steps, each of duration  $\delta t$ . For each time step, the full coupled set of equations is solved to get the new values of all the field variables at a time  $\delta t$  later. This solution uses the results of the previous cycle or the set of initial conditions, and it is stored so as to allow the processing to be repeated in the next cycle.

Each cycle in KACHINA is composed of two distinct phases. The explicit calculations are performed in Phase 1, and all implicit aspects are then handled in Phase 2.

### C. Phase 1 - Explicit Calculations

In Phase 1, we have collected all the explicit calculations for the cycle. There are two major parts in this phase, the first concerned with calculating new values of scalar variables defined at cell centers, and the second with calculating new values of the cell-edge momenta. Performance of the first part is the responsibility of a sweep over all the interior cells of the mesh, which solves the equations for  $n+1(\rho'_d)_i^j$ ,  $n+1(\rho'_{dl})_i^j$ ,  $n+1\theta_i^j$ ,  $A_i^j$ ,  $\tilde{p}_i^j$ ,  $K_i^j$ ,  $n+1I_v^j$ , and  $n+1I_d^j$ . In our notation, the superscript "n" indicates the old value of a quantity at the beginning of the cycle, and "n+1" indicates the new value at the end of the cycle. Immediately at the beginning of a cycle, we can calculate the final values in that cycle of all these quantities, except the pressure  $\tilde{p}$ , as they are not subject to further modification in Phase 2. The subsidiary quantity

$A_i^j$  has the dimensions of an internal energy  $I_v^j$ ; it appears in Phase 1 to supply the energy term for the equation-of-state pressure for the vapor, as will be described below. It is subscripted and saved for later use as a necessary coefficient in Phase 2.

The droplet density equations are

$$n+1(\rho'_d)_i^j = n(\rho'_d)_i^j + \frac{\delta t}{r_i \delta r} \left[ n \langle u_d r \rho'_d \rangle_{i-\frac{1}{2}}^j - n \langle u_d r \rho'_d \rangle_{i+\frac{1}{2}}^j \right] + \frac{\delta t}{\delta z} \left[ n \langle v_d \rho'_d \rangle_i^{j-\frac{1}{2}} - n \langle v_d \rho'_d \rangle_i^{j+\frac{1}{2}} \right],$$

and

$$n+1(\rho'_{dl})_i^j = n(\rho'_{dl})_i^j + \frac{\delta t}{r_i \delta r} \left[ n \langle u_d r \rho'_{dl} \rangle_{i-\frac{1}{2}}^j - n \langle u_d r \rho'_{dl} \rangle_{i+\frac{1}{2}}^j \right] + \frac{\delta t}{\delta z} \left[ n \langle v_d \rho'_{dl} \rangle_i^{j-\frac{1}{2}} - n \langle v_d \rho'_{dl} \rangle_i^{j+\frac{1}{2}} \right],$$

where the angular brackets  $\langle \rangle$  indicate a partial donor-cell treatment of the convective flux of the enclosed quantity. The use of the donor-cell differencing facilitates automatic mitigation of truncation-error effects<sup>8</sup> without requiring an explicit artificial diffusion. According to our formulation, the convective flux of some cell-centered quantity,  $Q_i^j$ , at cell boundary  $(i+\frac{1}{2}, j)$  would be given by

$$\langle urQ \rangle_{i+\frac{1}{2}}^j = (ur)_{i+\frac{1}{2}}^j \left[ (\xi + \frac{1}{2}) Q_i^j + (\frac{1}{2} - \xi) Q_{i+1}^j \right],$$

where

$$\xi = \beta_0 \left( \frac{u_{i+\frac{1}{2}}^j \delta r}{\delta r} \right) + \alpha_0 \text{ sign} \left( u_{i+\frac{1}{2}}^j \right),$$

and  $\alpha_0$  and  $\beta_0$  are input coefficients. For  $\alpha_0 = 0$  and  $\beta_0 = \frac{1}{2}$ ,  $\xi$  will give an automatically interpolated donor-cell form. More commonly, however, we use

$\beta_0 = 0$  and  $0 < \alpha_0 \leq \frac{1}{2}$ . With  $\beta_0 = 0$ , use of  $\alpha_0 = 0$  would give pure space-centered differencing, which is numerically unstable in the absence of a mitigating diffusive process, whereas use of  $\alpha_0 = \frac{1}{2}$  would give pure donor-cell differencing, which offers the greatest smoothing. The formulation of  $\xi$  assumes that  $|u_{\max}| \delta t / \delta r < \frac{1}{2}$  everywhere, ordinarily a reasonable upper limit on  $\delta t$  for accuracy.

The above transport equations for  ${}^{n+1}(\rho'_d)_i^j$  and  ${}^{n+1}(\rho'_{dl})_i^j$  allow us to rigorously conserve the masses of the two components separately, and with their values known,  ${}^{n+1}\theta_i^j$  is calculated from

$${}^{n+1}\theta_i^j = 1 - \frac{{}^{n+1}(\rho'_{dl})_i^j}{\rho_1} - \frac{{}^{n+1}(\rho'_d)_i^j - {}^{n+1}(\rho'_{dl})_i^j}{\rho_2}$$

With  ${}^{n+1}\theta_i^j$  now available, we can determine the energy term  $A_i^j$ . As an example, assume that we are using the polytropic gas equation of state, as we, in fact, do in this version of KACHINA. In this case, the pressure ordinarily would be given by

$$p = (\gamma_v - 1) \rho_v I_v$$

in which  $\gamma_v$  is the ratio of specific heats in the vapor. This basic form, however, is insensitive to variations in the proportions of components within the vapor, and it is unsatisfactory for direct use. To overcome this deficiency, we first define  $A_i^j$ , a necessary coefficient for Phase 2 iteration purposes, as

$$A_i^j = \frac{{}^n(I_v)_i^j}{{}^{n+1}\theta_i^j} \left[ \frac{{}^n(\rho'_{v1})_i^j b_{v1} (\gamma_1 - 1) + {}^n(\rho'_{v2})_i^j b_{v2} (\gamma_2 - 1)}{{}^n(\rho'_{v1})_i^j b_{v1} + {}^n(\rho'_{v2})_i^j b_{v2}} \right]$$

in which  $\gamma$ 's and the specific heats,  $b_v$ 's, are specified separately for each of the two components, and are provided in the input data. With  $A_i^j$  determined, the KACHINA equation-of-state pressure is then calculated directly as

$$p_{EOS} = A_i^j {}^n(\rho'_v)_i^j$$

The initializing pressure,  $\tilde{p}$ , actually stored in Phase 1 for a given cell after the first cycle is some mixture of  $p_{EOS}$  and the pressure  ${}^n p$  left over from the Phase 2 pressure iteration of the previous cycle. This treatment is required to allow the code to account for large variations in the flow Mach number from place to place or as a function of time. We use a function  $f$  of the local flow Mach number  $M$  to determine the exact proportions of this mixture, where

$$\tilde{p} = f {}^n p + (1 - f) p_{EOS}$$

in which the desired limits are  $f = 1$  when  $M \rightarrow 0$  and  $f = 0$  when  $M \rightarrow \infty$ . We have found that relating  $f$  to the square of the local Mach number,

$$f = \frac{1}{1 + 10 \left( \frac{M}{M_0} \right)^2}$$

gives satisfactory results, with  $M_0 = 0.5$  and the coefficient 10 chosen to allow the equation of state to exert a strong enough influence. The Mach number is calculated using the standard  $M = u/c$  form appropriate for a polytropic gas.<sup>9</sup> Choosing a squared Mach number function makes  $(1 - f)$  vary inversely in proportion to the vapor internal energy as that quantity becomes large, consistent with the dependence of  $p_{EOS}$  on that same variable. The choice also allows us to avoid taking a square root in the calculation of the sound speed,  $c$ . For calculations in which the sound speed becomes very large, the exponent should be greater than 2.0, in order that the equation-of-state effects disappear in that limit. Thus we have

$$\left( \frac{M}{M_0} \right)^2 = \frac{u^2}{c_{M_0}^2}$$

where the square of an appropriate average velocity for the cell  $(i, j)$  is calculated as

$$u^2 = \frac{1}{4} \left\{ \left[ {}^n(u_v)_{i+\frac{1}{2}}^j \right]^2 + \left[ {}^n(u_v)_{i-\frac{1}{2}}^j \right]^2 \right\}$$



$$+ \left[ n \left( v_v \right)_i^{j+\frac{1}{2}} \right]^2 + \left[ n \left( v_v \right)_i^{j-\frac{1}{2}} \right]^2 \left. \right\} ,$$

$$+ \left[ n \left( v_v \right)_i^{j-\frac{1}{2}} - n \left( v_d \right)_i^{j+\frac{1}{2}} + n \left( v_v \right)_i^{j-\frac{1}{2}} - n \left( v_d \right)_i^{j-\frac{1}{2}} \right]^2 \left. \right\}^{\frac{1}{2}} ,$$

and the square of a sufficiently accurate approximation to the sound speed can be shown to be

$$c^2 = \frac{n_{I_v} \left\{ \gamma_{v1} (\gamma_{v1} - 1) \left( \frac{\rho'_{v1}}{\rho'_v} \right) + \gamma_{v2} (\gamma_{v2} - 1) \left[ 1 - \left( \frac{\rho'_{v1}}{\rho'_v} \right) \right] \right\}}{\left( n+1 \theta_i^j \right)^2 \left[ \frac{n \rho'_d}{n \rho'_v} + 1 \right]} .$$

To allow greater generality, it is desirable to replace  $U^2$  by  $(U^2 + p/\rho)$ , in which  $p/\rho$  is given by  $n_p/\rho_v = n_p \theta / \rho'_v$ . A flow starting from rest and driven by its own internal pressure will have an initial  $p/\rho$  comparable to  $c^2$ , and later will develop  $U^2$  comparable to  $c^2$ , thus tending to make  $M^2$  always comparable to unity. This formulation also automatically handles far subsonic flows, as in such cases,  $p/\rho$  values and  $U^2$  values will be much smaller than  $c^2$ , resulting in a small  $M^2$  and  $f$  of order unity.

The initializing vapor density,  $\tilde{\rho}'_v$ , for the cell is also stored at this time. It is based similarly on  $f$ ,

$$\tilde{\rho}'_v = f \theta \rho_{v0} + (1-f) \frac{\tilde{p}}{A} ,$$

where  $\rho_{v0}$  may be a specified constant for completely incompressible flow, or may be allowed to vary in case of buoyancy effects.

The next consideration is the drag function,  $K_i^j$ , which we calculate as

$$K_i^j = \frac{3 n \left( \rho'_v \right)_i^j \left( 1 - n+1 \theta_i^j \right)}{2 \left( n+1 \theta_i^j \right)^2 r_p^2} \left[ 3 v_v + \left( \frac{r_p c_{DR}}{4} \right) \left| \vec{u}_v - \vec{u}_d \right| \right] ,$$

where

$$\left| \vec{u}_v - \vec{u}_d \right| \equiv \frac{1}{2} \left\{ \left[ n \left( u_v \right)_{i+\frac{1}{2}}^j - n \left( u_d \right)_{i+\frac{1}{2}}^j + n \left( u_v \right)_{i-\frac{1}{2}}^j - n \left( u_d \right)_{i-\frac{1}{2}}^j \right]^2 \right.$$

$v_v$  is the coefficient of kinematic viscosity for the vapor,  $r_p$  is the mean linear dimension of a droplet, and  $c_{DR}$  is a drag coefficient. In the present version of KACHINA, these three quantities are simply read-in constants. In a future version,  $r_p$  will be vastly generalized to include droplet growth or decrease in size, by such processes as evaporation, condensation, rupture, and coalescence. This generalization will be accomplished by means of a transport equation for  $r_p$ . At first, the generalization will involve the cell quantity  $r_p^j$ , and perhaps, later, an  $r_p$  distribution that can vary with position and time. Our present constant value for  $r_p$  is a useful first approximation, however, and it allows us to derive information about dependence of the results on the choice of droplet scale.

In theory, the  $\theta_i^j$ 's appearing in the  $K_i^j$  equation could be either  $n \theta$ 's or  $n+1 \theta$ 's, but our specific choice of  $n+1 \theta$  is based on computational requirements for suddenly incompressible flow. This point will be clarified in Sec. I.F.

The final quantities calculated in the first sweep in Phase I are the specific internal energies  $n+1 I_v$  and  $n+1 I_d$ .

$$n+1 \left( I_v \right)_i^j = n \left( I_v \right)_i^j$$

$$+ \delta t \left\{ \frac{1}{r_i \delta r} \left[ \left\langle u_v I_v r \right\rangle_{i-\frac{1}{2}}^j - \left\langle u_v I_v r \right\rangle_{i+\frac{1}{2}}^j \right] \right.$$

$$\left. + \frac{1}{\delta z} \left[ \left\langle v_v I_v \right\rangle_i^{j-\frac{1}{2}} - \left\langle v_v I_v \right\rangle_i^{j+\frac{1}{2}} \right] \right\}$$

$$\begin{aligned}
& + \frac{\delta t}{n(\rho'_v)_i^j} \left\{ \tilde{R}_i^j \left[ (T_d)_i^j - (T_v)_i^j \right] \right. \\
& + K_i^j \left[ (u_{di}^j - u_{vi}^j)^2 + (v_{di}^j - v_{vi}^j)^2 \right] \\
& + \frac{k_v}{r_i \delta r^2} \left[ \theta_{i+\frac{1}{2}}^j r_{i+\frac{1}{2}} (T_{vi+1}^j - T_{vi}^j) \right. \\
& - \theta_{i-\frac{1}{2}}^j r_{i-\frac{1}{2}} (T_{vi}^j - T_{vi-1}^j) \left. \right] \\
& + \frac{k_v}{\delta z^2} \left[ \theta_i^{j+\frac{1}{2}} (T_{vi}^{j+1} - T_{vi}^j) \right. \\
& - \theta_i^{j-\frac{1}{2}} (T_{vi}^j - T_{vi}^{j-1}) \left. \right] \left. \right\} \\
& - \frac{\tilde{p}_i^j \delta t}{n(\rho'_v)_i^j} \left( \frac{1}{r_i \delta r} \left\{ r_{i+\frac{1}{2}} \left[ \theta u_v + (1-\theta) u_d \right]_{i+\frac{1}{2}}^j \right. \right. \\
& - r_{i-\frac{1}{2}} \left[ \theta u_v + (1-\theta) u_d \right]_{i-\frac{1}{2}}^j \left. \right\} \\
& + \frac{1}{\delta z} \left\{ \left[ \theta v_v + (1-\theta) v_d \right]_{i+\frac{1}{2}}^{j+\frac{1}{2}} \right. \\
& - \left. \left[ \theta v_v + (1-\theta) v_d \right]_{i-\frac{1}{2}}^{j-\frac{1}{2}} \right\} \\
& + n(I_v)_i^j \delta t \left\{ \frac{1}{r_i \delta r} \left[ u_{vi+\frac{1}{2}}^j r_{i+\frac{1}{2}} - u_{vi-\frac{1}{2}}^j r_{i-\frac{1}{2}} \right] \right. \\
& + \frac{1}{\delta z} \left[ v_{vi}^{j+\frac{1}{2}} - v_{vi}^{j-\frac{1}{2}} \right] \left. \right\} ,
\end{aligned}$$

and

$$\begin{aligned}
n+1(I_d)_i^j &= n(I_d)_i^j \\
& + \delta t \left\{ \frac{1}{r_i \delta r} \left[ \langle u_d I_d r \rangle_{i-\frac{1}{2}}^j - \langle u_d I_d r \rangle_{i+\frac{1}{2}}^j \right] \right. \\
& + \frac{1}{\delta z} \left[ \langle v_d I_d \rangle_{i-\frac{1}{2}}^{j-\frac{1}{2}} - \langle v_d I_d \rangle_{i+\frac{1}{2}}^{j+\frac{1}{2}} \right] \left. \right\}
\end{aligned}$$

Time level  $n$  is assumed for all quantities in the right-hand sides of both of the above equations, except for  $K_i^j$  and  $\tilde{p}_i^j$ , which are coefficients for the drag and work terms, respectively, in  $n+1(I_v)_i^j$ .

These two quantities are those just obtained, as described above. Several new quantities appear in  $n+1(I_v)_i^j$  and  $n+1(I_d)_i^j$ , and they require discussion.

$R_i^j$  is an exchange function that controls the heat transferred between the two fields per unit volume per unit time, as a result of surface conduction. In general,  $R_i^j$  will be a cell variable, although now it is a constant and no array is stored. It is a coefficient that multiplies the local temperature difference, in which the temperature  $T$  is now given simply by the  $I = bT$  relationship, and is calculated as

$$n(T_v)_i^j = \frac{n(I_v \rho'_v)_i^j}{n(\rho'_{v1})_i^j b_{v1} + n(\rho'_{v2})_i^j b_{v2}}$$

and

$$n(T_d)_i^j = \frac{n(I_d \rho'_d)_i^j}{n(\rho'_{d1})_i^j b_{d1} + n(\rho'_{d2})_i^j b_{d2}}$$

Because the four specific heat coefficients that appear are presently constants, we are relieved of having to store the two T arrays. The constants  $k_v$  and  $k_d$  are heat conduction coefficients.  $E_i^j$  represents the energy contribution from some optional heat source, such as chemical or nuclear processes.

The velocities appearing in the drag term in the  $n^{+1}(I_v)_i^j$  equation are calculated as

$$(u_{di}^j - u_{vi}^j)^2 \equiv \left[ \frac{1}{2} (u_{di+\frac{1}{2}}^j + u_{di-\frac{1}{2}}^j - u_{vi+\frac{1}{2}}^j - u_{vi-\frac{1}{2}}^j) \right]^2$$

and

$$(v_{di}^j - v_{vi}^j)^2 \equiv \left[ \frac{1}{2} (v_{di}^{j+\frac{1}{2}} + v_{di}^{j-\frac{1}{2}} - v_{vi}^{j+\frac{1}{2}} - v_{vi}^{j-\frac{1}{2}}) \right]^2$$

When it becomes available, the new  $n^{+1}I_v$  value is used to adjust the A for use in Phase 2,

$$A_i^j = A_i^j n^{+1}(I_v)_i^j / n(I_v)_i^j$$

The second major pass through the mesh in Phase 1 is concerned with calculating a set of momentum fluxes, comprised of the four arrays  $(\rho'_v u_v)$ ,  $(\rho'_v v_v)$ ,  $(\rho'_d u_d)$ , and  $(\rho'_d v_d)$ . These fluxes are defined at the same cell-edge positions as the velocities  $u_v$ ,  $v_v$ ,  $u_d$ , and  $v_d$ , respectively. While dealing with momentum, it is convenient simply to replace each velocity in computer storage by the corresponding momentum, which will be reconverted to a velocity in Phase 2. The four equations used are:

$$\begin{aligned} \overline{(\rho'_v u_v)}_{i+\frac{1}{2}}^j &= n(\rho'_v u_v)_{i+\frac{1}{2}}^j \\ &+ \frac{\delta t}{r_i \delta r} \left[ n \langle \rho'_v u_v^2 r \rangle_i^j - n \langle \rho'_v u_v^2 r \rangle_{i+1}^j \right] \\ &+ \delta t n(F_{vr})_{i+\frac{1}{2}}^j \end{aligned}$$

$$+ \frac{\delta t}{\delta z} \left[ n \langle \rho'_v u_v v_v \rangle_{i+\frac{1}{2}}^{j-\frac{1}{2}} - n \langle \rho'_v u_v v_v \rangle_{i+\frac{1}{2}}^{j+\frac{1}{2}} \right]$$

$$\overline{(\rho'_v v_v)}_i^{j+\frac{1}{2}} = n(\rho'_v v_v)_i^{j+\frac{1}{2}}$$

$$+ \frac{\delta t}{r_i \delta r} \left[ n \langle \rho'_v u_v v_v r \rangle_{i-\frac{1}{2}}^{j+\frac{1}{2}} - n \langle \rho'_v u_v v_v r \rangle_{i+\frac{1}{2}}^{j+\frac{1}{2}} \right]$$

$$+ \delta t n(F_{vz})_{i+\frac{1}{2}}^{j+\frac{1}{2}}$$

$$+ \frac{\delta t}{\delta z} \left[ n \langle \rho'_v v_v^2 \rangle_i^j - \langle \rho'_v v_v^2 \rangle_{i+1}^{j+1} \right] + (\rho'_v)_i^{j+\frac{1}{2}} g \delta t$$

$$\overline{(\rho'_d u_d)}_{i+\frac{1}{2}}^j = n(\rho'_d u_d)_{i+\frac{1}{2}}^j$$

$$+ \frac{\delta t}{r_{i+\frac{1}{2}} \delta r} \left[ n \langle \rho'_d u_d^2 r \rangle_i^j - n \langle \rho'_d u_d^2 r \rangle_{i+1}^j \right]$$

$$+ \delta t n(F_{dr})_{i+\frac{1}{2}}^j$$

$$+ \frac{\delta t}{\delta z} \left[ n \langle \rho'_d u_d v_d \rangle_{i+\frac{1}{2}}^{j-\frac{1}{2}} - n \langle \rho'_d u_d v_d \rangle_{i+\frac{1}{2}}^{j+\frac{1}{2}} \right]$$

and

$$\overline{(\rho'_d v_d)}_i^{j+\frac{1}{2}} = n(\rho'_d v_d)_i^{j+\frac{1}{2}}$$

$$+ \frac{\delta t}{r_i \delta r} \left[ n \langle \rho'_d u_d v_d r \rangle_{i-\frac{1}{2}}^{j+\frac{1}{2}} - n \langle \rho'_d u_d v_d r \rangle_{i+\frac{1}{2}}^{j+\frac{1}{2}} \right]$$

$$+ \delta t n(F_{dz})_{i+\frac{1}{2}}^{j+\frac{1}{2}}$$

$$+ \frac{\delta t}{\delta z} \left[ n \langle \rho'_d v_d^2 \rangle_i^j - n \langle \rho'_d v_d^2 \rangle_{i+1}^{j+1} \right] + (\rho'_d)_i^{j+\frac{1}{2}} g \delta t$$

The donor-cell formulations in the convective flux terms are analogous to those previously described for the quantities in the first sweep, but, because the centerings of the variables involved are different, we include several representative examples. In the  $\bar{u}$  equations:

$$\langle \rho u^2 r \rangle_i^j = (ur)_i^j \left[ (\frac{1}{2} + \xi) (\rho u)_{i-\frac{1}{2}}^j + (\frac{1}{2} - \xi) (\rho u)_{i+\frac{1}{2}}^j \right],$$

where

$$\xi = \beta_o \left( \frac{u_i^j \delta t}{\delta r} \right) + \alpha_o \text{sign} \left( u_i^j \right),$$

and

$$u_i^j = \frac{1}{2} \left( u_{i+\frac{1}{2}}^j + u_{i-\frac{1}{2}}^j \right).$$

$$\langle \rho uv \rangle_{i+\frac{1}{2}}^{j-\frac{1}{2}} = v_{i+\frac{1}{2}}^{j-\frac{1}{2}} \left[ (\frac{1}{2} + \xi) (\rho u)_{i+\frac{1}{2}}^{j-1} + (\frac{1}{2} - \xi) (\rho u)_{i+\frac{1}{2}}^j \right],$$

where

$$\xi = \beta_o \left( \frac{v_{i+\frac{1}{2}}^{j-\frac{1}{2}} \delta t}{\delta z} \right) + \alpha_o \text{sign} \left( v_{i+\frac{1}{2}}^{j-\frac{1}{2}} \right),$$

and

$$v_{i+\frac{1}{2}}^{j-\frac{1}{2}} = \frac{1}{2} \left( v_i^{j-\frac{1}{2}} + v_{i+1}^{j-\frac{1}{2}} \right).$$

In the  $\overline{\rho v}$  equations:

$$\langle \rho uv r \rangle_{i-\frac{1}{2}}^{j+\frac{1}{2}} = u_{i-\frac{1}{2}}^{j+\frac{1}{2}} r_{i-\frac{1}{2}} \left[ (\frac{1}{2} + \xi) (\rho v)_{i-1}^{j+\frac{1}{2}} + (\frac{1}{2} - \xi) (\rho v)_i^{j+\frac{1}{2}} \right],$$

where

$$\xi = \beta_o \left( \frac{u_{i-\frac{1}{2}}^{j+\frac{1}{2}} \delta t}{\delta r} \right) + \alpha_o \text{sign} \left( u_{i-\frac{1}{2}}^{j+\frac{1}{2}} \right),$$

and

$$u_{i-\frac{1}{2}}^{j+\frac{1}{2}} = \frac{1}{2} \left( u_{i-\frac{1}{2}}^j + u_{i-\frac{1}{2}}^{j+1} \right).$$

In addition to the convective flux terms, the  $\overline{\rho v}$  equations contain terms for including the effect of gravitational acceleration, with  $g$  being constant.

In many KACHINA applications, the flows to be studied will involve interaction with some confining and at least partially nonfalling structural elements, which may not be practical to include in the

computer model in complete detail. Such interactions may be significantly nonisotropic in orientation. To properly incorporate their effects will require interaction terms with material strength effects capable of representing added inertia, nonisotropic drag, energy dissipation, and elastic-plastic deformation. In the present KACHINA version, the  $F_r$  and  $F_z$  terms in the momentum equations represent a simple preliminary approach to including nonisotropic effects. These terms contribute a dissipationless turning that tends to constrict motion primarily to the axial direction. The direction of the force is orthogonal to the velocity, and the strength is proportional to the departure of the velocity from the axial direction. Thus, if

$$\vec{u} = \hat{i}u + \hat{j}v,$$

and

$$\vec{F} = \hat{i}a + \hat{j}b,$$

then

$$au + bv = 0,$$

and

$$a^2 + b^2 = \epsilon^2 u^2 / (u^2 + v^2),$$

with magnitude proportional to  $|u|$ .

Therefore,

$$a = \pm \epsilon uv / (u^2 + v^2),$$

and

$$b = \mp \epsilon u^2 / (u^2 + v^2),$$

or

$$a = -\epsilon uv \text{sign}(v) / (u^2 + v^2),$$

and

$$b = +\epsilon u^2 \text{sign}(v) / (u^2 + v^2).$$

Because  $v$  sign ( $v$ ) is always positive ( $\equiv |v|$ ),  $a$  is always directed against  $u$ , whereas  $b$  works to increase positive  $v$  or to decrease negative  $v$ . Our form for the nonisotropic term in this version of KACHINA is

$$\vec{F} = - \frac{\epsilon_{\ell} u_{\ell} \text{sign}(v_{\ell})}{u_{\ell}^2 + v_{\ell}^2} (\hat{i}v_{\ell} - \hat{j}u_{\ell}),$$

where  $\ell = d$  or  $v$ , thereby requiring a different  $\epsilon$  for the term in a droplet equation from that in a vapor equation. With  $F_r = a$  and  $F_z = b$ , the equations used are:

$$n(F_{vr})_{i+\frac{1}{2}}^j = - \frac{\epsilon_v n \left[ \frac{u_v v_v \text{sign}(v_v)}{u_v^2 + v_v^2} \right]_{i+\frac{1}{2}}^j}{n \left( \frac{u_v^2 + v_v^2}{i+\frac{1}{2}} \right)^j},$$

$$n(F_{dr})_{i+\frac{1}{2}}^j = - \frac{\epsilon_d n \left[ \frac{u_d v_d \text{sign}(v_d)}{u_d^2 + v_d^2} \right]_{i+\frac{1}{2}}^j}{n \left( \frac{u_d^2 + v_d^2}{i+\frac{1}{2}} \right)^j},$$

$$n(F_{vz})_i^{j+\frac{1}{2}} = + \frac{\epsilon_v n \left[ \frac{u_v^2 \text{sign}(v_v)}{u_v^2 + v_v^2} \right]_i^{j+\frac{1}{2}}}{n \left( \frac{u_v^2 + v_v^2}{i} \right)^{j+\frac{1}{2}}},$$

and

$$n(F_{dz})_i^{j+\frac{1}{2}} = + \frac{\epsilon_d n \left[ \frac{u_d^2 \text{sign}(v_d)}{u_d^2 + v_d^2} \right]_i^{j+\frac{1}{2}}}{n \left( \frac{u_d^2 + v_d^2}{i} \right)^{j+\frac{1}{2}}}.$$

Generally,  $\epsilon_{\ell}(r, z, t)$  may be prescribed in its  $r$ - $z$  variations, and  $\epsilon_{\ell}$  may decay during the course of a

calculation, representing the loss of integrity of the confining structure. At present, however, we simply specify  $\epsilon_v$  and  $\epsilon_d$  as constants. Note that if  $\epsilon_v$  or  $\epsilon_d$  is large, the corresponding term may require an implicit treatment to ensure that all motions are constrained to the desired trajectory.

Further, this nonisotropic force cannot be incorporated into the drag term, because it includes the effects of droplets colliding with other droplets that are constrained into axial channels by material strength, and such collisions are precluded by our two-field approach.

Note that this version of the momentum equations omits all viscous terms because they are required neither for numerical stability (because of our partial donor-cell convection treatment), nor for the physical processes that we wish to represent in this initial version of the code. Their later inclusion will be accomplished entirely by addition of the appropriate stress terms to those equations defining the  $\bar{\rho}u$  and  $\bar{\rho}v$  quantities.<sup>7</sup>

This completes the explicit part of the calculation cycle. In summary, at the end of Phase 1, we have in computer storage the  $n+1$  values of  $\rho'_d$ ,  $\rho'_{d1}$ ,  $\theta$ ,  $I_v$ , and  $I_d$ , along with the values of  $n\rho'_v$ ,  $n\rho'_{v1}$ ,  $A$ ,  $\tilde{p}$ ,  $K$ ,  $(\overline{\rho'_v u_v})$ ,  $(\overline{\rho'_v v_v})$ ,  $(\overline{\rho'_d u_d})$ , and  $(\overline{\rho'_d v_d})$ .

#### D. Phase 2—Implicit Calculations

The Phase 2 calculations start with conversion of the momenta from Phase 1 back into velocity components  $\tilde{u}_v$ ,  $\tilde{v}_v$ ,  $\tilde{u}_d$ , and  $\tilde{v}_d$ . These are the tentative final velocities for the cycle, as symbolized by the tildes, and they include the first-guess effects of pressure acceleration and drag, both of which will be corrected as the tilde velocities converge to their final values for the cycle. The velocities are given by the (explicit) expressions:

$$\begin{aligned} (\tilde{u}_v)_{i+\frac{1}{2}}^j &= \frac{n+1 \left( \rho'_d \right)_{i+\frac{1}{2}}^j \mathcal{E}_{i+\frac{1}{2}}^j + \delta t n_{K_{i+\frac{1}{2}}}^j \left( \mathcal{E}_{i+\frac{1}{2}}^j + \mathcal{E}_{i+\frac{1}{2}}^j \right)}{n_{\rho'_{vi+\frac{1}{2}}} \left[ n+1 \left( \rho'_d \right)_{i+\frac{1}{2}}^j + \delta t n_{K_{i+\frac{1}{2}}}^j \right] + \delta t n+1 \left( \rho'_d \right)_{i+\frac{1}{2}}^j n_{K_{i+\frac{1}{2}}}^j}, \\ (\tilde{v}_v)_i^{j+\frac{1}{2}} &= \frac{n+1 \left( \rho'_d \right)_i^{j+\frac{1}{2}} \mathcal{E}_i^{j+\frac{1}{2}} + \delta t n_{K_i}^{j+\frac{1}{2}} \left( \mathcal{E}_i^{j+\frac{1}{2}} + \mathcal{E}_i^{j+\frac{1}{2}} \right)}{n_{\rho'_{vi}} \left[ n+1 \left( \rho'_d \right)_i^{j+\frac{1}{2}} + \delta t n_{K_i}^{j+\frac{1}{2}} \right] + \delta t n+1 \left( \rho'_d \right)_i^{j+\frac{1}{2}} n_{K_i}^{j+\frac{1}{2}}}, \end{aligned}$$

$$\left(\tilde{u}_d\right)_{i+\frac{1}{2}}^j = \frac{n \left(\rho'_v\right)_{i+\frac{1}{2}}^j \tilde{\rho}_{i+\frac{1}{2}}^j + \delta t \frac{n_{K_{i+\frac{1}{2}}}^j}{\rho_{vi+\frac{1}{2}}^j} \left(\tilde{\rho}_{i+\frac{1}{2}}^j + \rho_{i+\frac{1}{2}}^j\right)}{n_{\rho_{vi+\frac{1}{2}}}^j \left[ n+1 \left(\rho'_d\right)_{i+\frac{1}{2}}^j + \delta t \frac{n_{K_{i+\frac{1}{2}}}^j}{\rho_{vi+\frac{1}{2}}^j} \right] + \delta t \frac{n+1}{\rho_{vi+\frac{1}{2}}^j} \left(\rho'_d\right)_{i+\frac{1}{2}}^j n_{K_{i+\frac{1}{2}}}^j},$$

$$\left(\tilde{v}_d\right)_i^{j+\frac{1}{2}} = \frac{n \left(\rho'_v\right)_i^{j+\frac{1}{2}} \tilde{\rho}_i^{j+\frac{1}{2}} + \delta t \frac{n_{K_i}^{j+\frac{1}{2}}}{\rho_{vi}^{j+\frac{1}{2}}} \left(\tilde{\rho}_i^{j+\frac{1}{2}} + \rho_i^{j+\frac{1}{2}}\right)}{n_{\rho_{vi}^{j+\frac{1}{2}}}^{j+\frac{1}{2}} \left[ n+1 \left(\rho'_d\right)_i^{j+\frac{1}{2}} + \delta t \frac{n_{K_i}^{j+\frac{1}{2}}}{\rho_{vi}^{j+\frac{1}{2}}} \right] + \delta t \frac{n+1}{\rho_{vi}^{j+\frac{1}{2}}} \left(\rho'_d\right)_i^{j+\frac{1}{2}} n_{K_i}^{j+\frac{1}{2}}},$$

where:

$$\tilde{\rho}_{i+\frac{1}{2}}^j = \left(\rho'_d u_d\right)_{i+\frac{1}{2}}^j + \left(1 - n+1 \theta_{i+\frac{1}{2}}^j\right) \frac{\delta t}{\delta r} \left(\tilde{p}_i^j - \tilde{p}_{i+1}^j\right),$$

$$\rho_{i+\frac{1}{2}}^j = \left(\rho'_v u_v\right)_{i+\frac{1}{2}}^j + n+1 \theta_{i+\frac{1}{2}}^j \frac{\delta t}{\delta r} \left(\tilde{p}_i^j - \tilde{p}_{i+1}^j\right),$$

$$\tilde{\rho}_i^{j+\frac{1}{2}} = \left(\rho'_d v_d\right)_i^{j+\frac{1}{2}} + \left(1 - n+1 \theta_i^{j+\frac{1}{2}}\right) \frac{\delta t}{\delta z} \left(\tilde{p}_i^j - \tilde{p}_{i+1}^j\right),$$

$$\rho_i^{j+\frac{1}{2}} = \left(\rho'_v v_v\right)_i^{j+\frac{1}{2}} + n+1 \theta_i^{j+\frac{1}{2}} \frac{\delta t}{\delta z} \left(\tilde{p}_i^j - \tilde{p}_{i+1}^j\right).$$

An implicit treatment is now required to help increase computational stability, in particular to eliminate the usual Courant-like restriction on high sound speed, by allowing signals to traverse more than one cell per time step. This is accomplished by iterating the quantities  $\tilde{p}$ ,  $\tilde{\rho}'_v$ ,  $\tilde{u}_v$ ,  $\tilde{v}_v$ ,  $\tilde{u}_d$ , and  $\tilde{v}_d$  to obtain new velocities that have been accelerated with time-advanced pressure gradients. The new velocities depend on the new pressures and densities, which, in turn, depend on the velocities; therefore the technique is implicit. It is best solved by an iterative process to provide the generality of initial and boundary conditions that usually are precluded by direct solution techniques.

The final  $(n+1)$  values of  $p$  are accumulated from the tilde values, in which each iteration contributes an increment to  $\tilde{p}$ , designated by  $\xi p$ .

The source term for the iteration is labeled  $\tilde{D}$ ; it is composed of a  $\partial \rho'_v / \partial t$  term plus a  $\nabla \cdot (\rho' \tilde{u})$  term, both of which use the most recently updated tilde values:

$$\begin{aligned} \tilde{D}_i^j &= \frac{1}{\delta t} \left[ \left(\tilde{\rho}'_v\right)_i^j - n \left(\rho'_v\right)_i^j \right] \\ &+ \frac{1}{r_i \delta r} \left[ \left\langle \tilde{\rho}'_v \tilde{u}_v r \right\rangle_{i+\frac{1}{2}}^j - \left\langle \tilde{\rho}'_v \tilde{u}_v r \right\rangle_{i-\frac{1}{2}}^j \right] \\ &+ \frac{1}{\delta z} \left[ \left\langle \tilde{\rho}'_v \tilde{v}_v \right\rangle_i^{j+\frac{1}{2}} - \left\langle \tilde{\rho}'_v \tilde{v}_v \right\rangle_i^{j-\frac{1}{2}} \right]. \end{aligned}$$

Note that two levels of the total vapor density  $\rho'_v$  must be maintained throughout this iterative process, as indicated in the first term of  $\tilde{D}$ . The donor-cell formulation of the second and third terms of  $\tilde{D}$  is calculated in a manner similar to that used in Phase 1. For example,

$$\left\langle \tilde{\rho}'_v \tilde{u}_v r \right\rangle_{i+\frac{1}{2}}^j = \left(u_v r\right)_{i+\frac{1}{2}}^j \left[ (\xi_2 + \xi) \left(\tilde{\rho}'_v\right)_i^j + (\xi_2 - \xi) \left(\tilde{\rho}'_v\right)_{i+1}^j \right],$$

in which

$$\xi = \beta_0 \left[ \frac{\left(\tilde{u}_v\right)_{i+\frac{1}{2}}^j \delta t}{\delta r} \right] + \alpha_0 \left[ \text{sign} \left( \tilde{u}_v \right)_{i+\frac{1}{2}}^j \right].$$

The necessary pressure change for the cell is given by

$$\delta p_i^j = - \omega_p \left( \beta_p \tilde{D} \right)_i^j,$$

in which  $\omega_p$  is an under- or overrelaxation coefficient of order unity. Straight relaxation is given by  $\omega_p = 1$ , but, because we are using a relaxation procedure based on Jacobi's method, the iteration will converge only if  $0 < \omega_p \leq 1$ . Also,

$$\begin{aligned}
\frac{1}{\beta_{pi}^j} &= \frac{\partial D_i^j}{\partial p_i^j} = \frac{1}{A_i^j \delta t} + \frac{\delta t}{r_i \delta r} \left[ \frac{r_{i+\frac{1}{2}}^{n+1} \theta_{i+\frac{1}{2}}^j + r_{i-\frac{1}{2}}^{n+1} \theta_{i-\frac{1}{2}}^j}{\delta r} + r_{i+\frac{1}{2}}^j K_{i+\frac{1}{2}}^j \left[ \frac{\partial (u_d)_i^j}{\partial p_i^j} - \frac{\partial (u_v)_i^j}{\partial p_i^j} \right] \right. \\
&- r_{i-\frac{1}{2}}^j K_{i-\frac{1}{2}}^j \left[ \frac{\partial (u_d)_i^j}{\partial p_i^j} - \frac{\partial (u_v)_i^j}{\partial p_i^j} \right] \left. \right] + \frac{\delta t}{\delta z} \left[ \frac{n+1 \theta_i^{j+\frac{1}{2}} + n+1 \theta_i^{j-\frac{1}{2}}}{\delta z} + K_i^{j+\frac{1}{2}} \left[ \frac{\partial (v_d)_i^j}{\partial p_i^j} - \frac{\partial (v_v)_i^j}{\partial p_i^j} \right] \right. \\
&- K_i^{j-\frac{1}{2}} \left[ \frac{\partial (v_d)_i^j}{\partial p_i^j} - \frac{\partial (v_v)_i^j}{\partial p_i^j} \right] \left. \right] ,
\end{aligned}$$

in which the partial derivatives are calculated by means of the following equations. Note that the second and fourth equations are not obtained merely by index changes from the first and third equations.

$$\left[ \frac{\partial (u_d)_i^j}{\partial p_i^j} - \frac{\partial (u_v)_i^j}{\partial p_i^j} \right] = + \frac{\tilde{\rho}_{vi+\frac{1}{2}}^{j+1} \left( 1 - n+1 \theta_{i+\frac{1}{2}}^j \right) \frac{\delta t}{\delta r} - n+1 (\rho_d')_{i+\frac{1}{2}}^j \left( \frac{n+1 \theta_{i+\frac{1}{2}}^j \delta t}{\delta r} - \frac{(\tilde{u}_v)_i^j}{2\Lambda_i^j} \right)}{\tilde{\rho}_{vi+\frac{1}{2}}^{j+1} \left[ n+1 (\rho_d')_{i+\frac{1}{2}}^j + \delta t n_{K_{i+\frac{1}{2}}}^j \right] + \delta t n+1 (\rho_d')_{i+\frac{1}{2}}^j n_{K_{i+\frac{1}{2}}}^j} ,$$

$$\left[ \frac{\partial (u_d)_i^j}{\partial p_i^j} - \frac{\partial (u_v)_i^j}{\partial p_i^j} \right] = - \frac{\tilde{\rho}_{vi-\frac{1}{2}}^{j+1} \left( 1 - n+1 \theta_{i-\frac{1}{2}}^j \right) \frac{\delta t}{\delta r} - n+1 (\rho_d')_{i-\frac{1}{2}}^j \left( \frac{n+1 \theta_{i-\frac{1}{2}}^j \delta t}{\delta r} + \frac{(\tilde{u}_v)_i^j}{2\Lambda_i^j} \right)}{\tilde{\rho}_{vi-\frac{1}{2}}^{j+1} \left[ n+1 (\rho_d')_{i-\frac{1}{2}}^j + \delta t n_{K_{i-\frac{1}{2}}}^j \right] + \delta t n+1 (\rho_d')_{i-\frac{1}{2}}^j n_{K_{i-\frac{1}{2}}}^j} ,$$

$$\left[ \frac{\partial (v_d)_i^j}{\partial p_i^j} - \frac{\partial (v_v)_i^j}{\partial p_i^j} \right] = + \frac{\tilde{\rho}_{vi}^{j+\frac{1}{2}} \left( 1 - n+1 \theta_i^{j+\frac{1}{2}} \right) \frac{\delta t}{\delta z} - n+1 (\rho_d')_i^{j+\frac{1}{2}} \left( \frac{n+1 \theta_i^{j+\frac{1}{2}} \delta t}{\delta z} - \frac{(\tilde{v}_v)_i^j}{2\Lambda_i^j} \right)}{\tilde{\rho}_{vi}^{j+\frac{1}{2}} \left[ n+1 (\rho_d')_i^{j+\frac{1}{2}} + \delta t n_{K_i}^{j+\frac{1}{2}} \right] + \delta t n+1 (\rho_d')_i^{j+\frac{1}{2}} n_{K_i}^{j+\frac{1}{2}}} ,$$

$$\left[ \frac{\partial (v_d)_i^j}{\partial p_i^j} - \frac{\partial (v_v)_i^j}{\partial p_i^j} \right] = - \frac{\tilde{\rho}_{vi}^{j-\frac{1}{2}} \left( 1 - n+1 \theta_i^{j-\frac{1}{2}} \right) \frac{\delta t}{\delta z} - n+1 (\rho_d')_i^{j-\frac{1}{2}} \left( \frac{n+1 \theta_i^{j-\frac{1}{2}} \delta t}{\delta z} + \frac{(\tilde{v}_v)_i^j}{2\Lambda_i^j} \right)}{\tilde{\rho}_{vi}^{j-\frac{1}{2}} \left[ n+1 (\rho_d')_i^{j-\frac{1}{2}} + \delta t n_{K_i}^{j-\frac{1}{2}} \right] + \delta t n+1 (\rho_d')_i^{j-\frac{1}{2}} n_{K_i}^{j-\frac{1}{2}}} .$$

We have found that it is sufficient to calculate an array of  $\tilde{\rho}_p^j$ 's for all cells and store them before entering the iterations and hold them invariant throughout the iterations to enhance computer efficiency.

With  $\delta p$  calculated, the next step is to update  $\tilde{p}$  and  $\tilde{\rho}_v^j$ .

$$\text{new } (\tilde{p})_i^j = \text{old } (\tilde{p})_i^j + \delta p_i^j ,$$

$$\text{new } (\tilde{\rho}_v^j)_i^j = f_i^j \theta_i^j \rho_{vo}^j + (1 - f_i^j) \frac{\text{new } (\tilde{p})_i^j}{\Lambda_i^j} ,$$

thus allowing direct calculation of the new velocity values:

$$\text{new}(\tilde{u}_v)_i^{j+1/2} = \frac{n+1(\rho'_d)_i^j R_{i+1/2}^j + \delta t n_{K_{i+1/2}}^j (R_{i+1/2}^j + U_{i+1/2}^j)}{\text{new}(\tilde{\rho}'_v)_i^{j+1/2} [n+1(\rho'_d)_{i+1/2}^j + \delta t n_{K_{i+1/2}}^j] + \delta t n+1(\rho'_d)_{i+1/2}^j n_{K_{i+1/2}}^j}$$

$$\text{new}(\tilde{u}_d)_i^j = \frac{\text{new}(\tilde{\rho}'_v)_i^j U_{i+1/2}^j + \delta t n_{K_{i+1/2}}^j (R_{i+1/2}^j + U_{i+1/2}^j)}{\text{new}(\tilde{\rho}'_v)_i^j [n+1(\rho'_d)_{i+1/2}^j + \delta t n_{K_{i+1/2}}^j] + \delta t n+1(\rho'_d)_{i+1/2}^j n_{K_{i+1/2}}^j}$$

$$\text{new}(\tilde{v}_v)_i^{j+1/2} = \frac{n+1(\rho'_d)_i^{j+1/2} g_i^{j+1/2} + \delta t n_{K_i}^{j+1/2} (g_i^{j+1/2} + y_i^{j+1/2})}{\text{new}(\tilde{\rho}'_v)_i^{j+1/2} [n+1(\rho'_d)_i^{j+1/2} + \delta t n_{K_i}^{j+1/2}] + \delta t n+1(\rho'_d)_i^{j+1/2} n_{K_i}^{j+1/2}}$$

$$\text{new}(\tilde{v}_d)_i^{j+1/2} = \frac{\text{new}(\tilde{\rho}'_v)_i^{j+1/2} y_i^{j+1/2} + \delta t n_{K_i}^{j+1/2} (g_i^{j+1/2} + y_i^{j+1/2})}{\text{new}(\tilde{\rho}'_v)_i^{j+1/2} [n+1(\rho'_d)_i^{j+1/2} + \delta t n_{K_i}^{j+1/2}] + \delta t n+1(\rho'_d)_i^{j+1/2} n_{K_i}^{j+1/2}}$$

where

$$R_{i+1/2}^j = \text{old}(\tilde{\rho}'_v \tilde{u}_v)_{i+1/2}^j + \delta t n_{K_{i+1/2}}^j \text{old}(\tilde{u}_v - \tilde{u}_d)_{i+1/2}^j + \frac{\delta t (\delta p_i^j - \delta p_{i+1}^j)}{\delta r} n+1_{\rho_i}^j$$

$$U_{i+1/2}^j = n+1(\rho'_d)_{i+1/2}^j \text{old}(\tilde{u}_d)_{i+1/2}^j - \delta t n_{K_{i+1/2}}^j \text{old}(\tilde{u}_v - \tilde{u}_d)_{i+1/2}^j + \frac{\delta t (\delta p_i^j - \delta p_{i+1}^j)}{\delta r} (1 - n+1_{\rho_i}^j)$$

$$g_i^{j+1/2} = \text{old}(\tilde{\rho}'_v \tilde{v}_v)_i^{j+1/2} + \delta t n_{K_i}^{j+1/2} \text{old}(\tilde{v}_v - \tilde{v}_d)_i^{j+1/2} + \frac{\delta t (\delta p_i^j - \delta p_{i+1}^{j+1})}{\delta z} n+1_{\rho_i}^{j+1/2}$$

$$y_i^{j+1/2} = n+1(\rho'_d)_i^{j+1/2} \text{old}(\tilde{v}_d)_i^{j+1/2} - \delta t n_{K_i}^{j+1/2} \text{old}(\tilde{v}_v - \tilde{v}_d)_i^{j+1/2} + \frac{\delta t (\delta p_i^j - \delta p_{i+1}^{j+1})}{\delta z} (1 - n+1_{\rho_i}^{j+1/2})$$

Each iteration consists of two sweeps over the entire mesh; the first sweep provides  $\text{new} \tilde{p}$  for all cells, then the second sweep calculates updated values of  $\tilde{\rho}'_v$ ,  $\tilde{u}_v$ ,  $\tilde{u}_d$ ,  $\tilde{v}_v$ , and  $\tilde{v}_d$  for all cells. This two-sweep-per-iteration procedure is required because the neighboring values of  $\delta p_{i+1}^j$  and  $\delta p_i^{j+1}$  must be available for the  $R$ ,  $U$ ,  $g$ , and  $Y$  equations.

The iteration procedure is repeated until

$$|\tilde{p}_i^j| < \epsilon_1 \left\{ \left( \frac{|u_v| R_{i+1/2}^j |u_v| L}{2\delta r} + \frac{|v_v| I_{i+1/2}^j |v_v| B}{2\delta z} \right) \rho'_v \right\}_{\text{max}} + \epsilon_2$$

is satisfied for all cells, at which time the fields of  $\tilde{p}$ ,  $\tilde{\rho}'_v$ ,  $\tilde{u}_v$ ,  $\tilde{u}_d$ ,  $\tilde{v}_v$ , and  $\tilde{v}_d$  are considered to have become the final ( $n+1$ ) values for the cycle. In the above test, the fineness of the convergence is governed by the input constant  $\epsilon_1$ , which typically ranges from  $10^{-6}$  to  $10^{-3}$ . The  $\epsilon_2$  provides a cutoff minimum at the beginning of a problem, when the velocity field has yet to be established; it, too, is problem dependent and has the dimensions of 1/time. We have found that a value  $\epsilon_2 = 10^{-6}$  suffices for most problems run on the CDC 6600 or 7600, which carry about 14 or 15 significant digits in floating-point numbers. Thus, if  $\epsilon_1 = 10^{-2}$ , the convergence requirement with all zero velocities is  $(10^{-2}) (10^{-6}) = 10^{-8}$ , which is certainly within accuracy



standards, but if  $\varepsilon_2$  were reduced to  $10^{-10}$ , however, the resulting  $10^{-14}$  would border on machine significance, and convergence could not be obtained. The  $\left[ \right]_{\max}$  portion of the convergence test above represents the magnitude of the largest initial tilde velocity times  $\rho'_v$  product in the entire mesh, found upon an examination of all cells that was performed concurrently with the  $\beta_p$  calculation, back before the iteration began.

In practice, it is wise to specify some maximum allowable number of iterations per cycle, simply terminating the iterative process if this number is ever reached, and considering the current values of  $\tilde{p}$ ,  $\tilde{\rho}'_v$ ,  $\tilde{u}_v$ ,  $\tilde{u}_d$ ,  $\tilde{v}_v$ , and  $\tilde{v}_d$  to be satisfactory. In our test runs, this procedure has worked well with a cutoff of 100 iterations. If the cutoff is encountered because the solution is diverging, obviously the calculation is in serious trouble, but the cutoff will occasionally terminate an iteration that is converging properly. In such instances, computer time is saved by this termination, and the current pressure, density, and velocity values are accurate enough that the iteration can be expected to converge more rapidly in the next cycle. Typical runs encounter this cutoff only very rarely, the usual number of iterations per cycle seldom exceeding 10.

At the end of this iterative solution, we have in computer storage the  $n+1$  values of  $\rho'_d$ ,  $\rho'_{d1}$ ,  $\theta$ ,  $I_v$ ,  $I_d$ ,  $\rho'_v$ ,  $p$ ,  $u_v$ ,  $u_d$ ,  $v_v$ , and  $v_d$ , along with  $A$ ,  $K$ , and  ${}^n\rho'_{v1}$ . Because the new velocities are now available, we can solve for the one remaining unknown field variable,  ${}^{n+1}\rho'_{v1}$ . We use a similar Newton-Raphson iteration scheme again, but this time based on the Gauss-Seidel method. The first guess for  $\tilde{\rho}'_{v1}$  is simply  ${}^n\rho'_{v1}$ , and the changes are accumulated from the relationship

$$\delta(\tilde{\rho}'_{v1})_i^j = -\omega_\rho (\beta_\rho Q)_i^j .$$

Here,  $\omega_\rho$  is a relaxation coefficient lying in the range  $0 < \omega_\rho < 2$ . The term  $\beta_\rho$  remains constant throughout this iteration, and is given by

$$(\beta_\rho)_i^j = \frac{1}{\frac{1}{\delta t} + \frac{1}{2r_i \delta r} \left[ {}^{n+1}(ru_v)_{i+\frac{1}{2}}^j - {}^{n+1}(ru_v)_{i-\frac{1}{2}}^j \right] + \frac{1}{2\delta z} \left[ {}^{n+1}(v_v)_i^{j+\frac{1}{2}} - {}^{n+1}(v_v)_i^{j-\frac{1}{2}} \right]} .$$

The denominator in the  $\beta_\rho$  equation will not vanish if  $|u_v|_{\max} \delta t / \delta r < 0.5$  and  $|v_v|_{\max} \delta t / \delta z < 0.5$ . The source term  $Q$  is continually recalculated using the latest values of  $\tilde{\rho}'_{v1}$  :

$$Q_i^j = \frac{(\tilde{\rho}'_{v1})_i^j - {}^n(\rho'_{v1})_i^j}{\delta t} + \frac{1}{r_i \delta r} \left[ \langle {}^{n+1}u_v r \tilde{\rho}'_{v1} \rangle_{i+\frac{1}{2}}^j - \langle {}^{n+1}u_v r \tilde{\rho}'_{v1} \rangle_{i-\frac{1}{2}}^j \right] + \frac{1}{\delta z} \left[ \langle {}^{n+1}v_v \tilde{\rho}'_{v1} \rangle_i^{j+\frac{1}{2}} - \langle {}^{n+1}v_v \tilde{\rho}'_{v1} \rangle_i^{j-\frac{1}{2}} \right] .$$

The  $\tilde{\rho}'_{v1}$  values are iterated until  $Q \approx 0$  for every cell, at which time the current  $\tilde{\rho}'_{v1}$  values are considered to have become the  ${}^{n+1}\rho'_{v1}$  values. In practice, we have found that  $Q$  can be tested against the same convergence term used for the  $\tilde{D}$  test. Although  $Q$  is analogous to  $\tilde{D}$  of the first iteration, and many of the same comments apply equally, one should note that the  $n+1$   $u$ 's and  $v$ 's result solely from the first iteration and remain unchanged through this second iteration. The second and third terms in  $Q_i^j$  are written in a manner like that used in the  $\tilde{D}$  equation. For example,

$$\langle {}^{n+1}u_v r \tilde{\rho}'_{v1} \rangle_{i+\frac{1}{2}}^j = {}^{n+1}(u_v)_{i+\frac{1}{2}}^j r_{i+\frac{1}{2}} \left[ (\xi_2 + \xi) (\tilde{\rho}'_{v1})_i^j + (\xi_2 - \xi) (\tilde{\rho}'_{v1})_{i+1}^j \right] ,$$

in which

$$\xi = \frac{\beta_\rho \delta t}{\delta r} \left[ {}^{n+1}(u_v)_{i+\frac{1}{2}}^j \right] + \alpha_0 \text{ sign} \left[ {}^{n+1}(u_v)_{i+\frac{1}{2}}^j \right] .$$

The solution of the second iteration completes the calculations associated with Phase 2, the implicit half of the cycle.

### E. Boundary Conditions

A variety of boundary conditions have been successfully tested in the KACHINA code. Figure 3 illustrates the currently available boundary options for the bottom, right, and top edges of the computing mesh, as specified by the input data for each particular problem. In all instances, the left boundary of the mesh serves as the axis of cylindrical symmetry. Typical configurations we have used include a box with three rigid free-slip walls, or the other extreme of three continuative outflow boundaries, in which the rigid section of the right-hand wall has been reduced to zero height. A set of studies of fluidized dust beds used a specified inflow bottom boundary, a rigid right wall, and outflow along the top. On the right boundary, the transition point from rigid free slip to outflow, noted in Fig. 3, can lie at any desired cell boundary from bottom to top, and it allows the extremes of an all-rigid free-slip boundary or an all-outflow boundary.

As Fig. 4 shows, the boundary conditions considered here are described in relation to the bottom boundary, the treatment being entirely analogous at the other boundaries. These conditions are more easily applied if the computing mesh shown in Fig. 1 is surrounded on all four sides by a belt of fictitious or outside cells. These cells provide convenient exterior storage locations for functions of

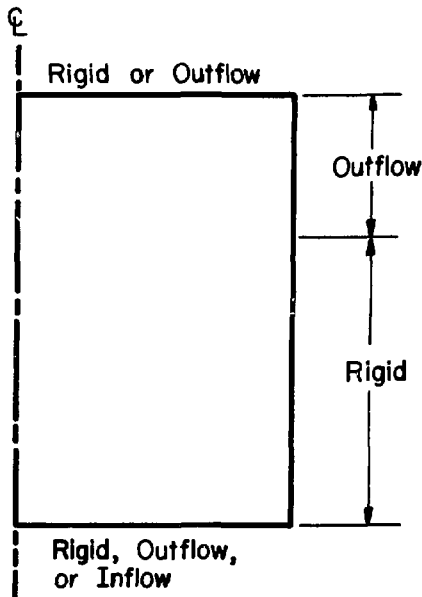


Fig. 3. Boundary conditions available in KACHINA.

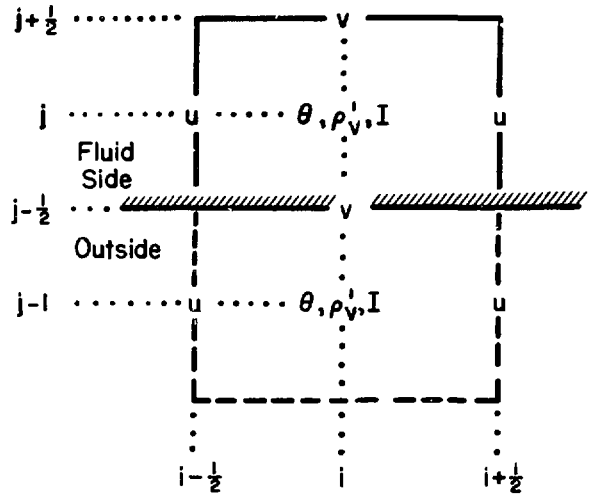


Fig. 4. Quantities involved in boundary conditions at the bottom of the KACHINA mesh.

the neighboring inside cell variables, chosen so that when they are referenced in the equations the desired boundary condition is satisfied automatically without any testing of the boundary type.

(1) RIGID (FREE-SLIP): A rigid free-slip boundary represents an axis or plane of symmetry, or a nonadhering surface that exerts no drag upon the fluid. The normal component of velocity vanishes at the wall, and there is no gradient in scalar variables across the boundary. If the boundary is insulated:

$$\theta_i^{j-1} = \theta_i^j,$$

$$(v_v)_i^{j-1/2} = (v_d)_i^{j-1/2} = 0,$$

$$(\rho'_{v1})_i^{j-1} = (\rho'_{v1})_i^j,$$

$$(\rho'_v)_i^{j-1} = (\rho'_v)_i^j,$$

$$(I_v)_i^{j-1} = (I_v)_i^j.$$

(2) INFLOW (Specified): The inflow boundary allows vapor, only, to move into the system at a prescribed rate that, in principle, can vary with position and time, although in the present KACHINA it is constant.

$$\theta_i^{j-1} = \theta_{\text{specified}} ,$$

$$(v_v)_i^{j-1/2} = v_{\text{specified}} ,$$

$$(v_d)_i^{j-1/2} = 0 ,$$

$$(\rho'_{v1})_i^{j-1} = \theta_{\text{specified}} (\rho_{v1})_{\text{specified}} ,$$

$$(\rho'_v)_i^{j-1} = \theta_{\text{specified}} (\rho_{v1} + \rho_{v2})_{\text{specified}} ,$$

$$(I_v)_i^{j-1} = (I_v)_{\text{specified}} .$$

(3) **OUTFLOW (Continuative):** A continuative outflow boundary allows fluid to leave the system at its own chosen rate, hopefully with minimal upstream flow disturbance whether the flow is subsonic or supersonic. Nothing precludes an outflow boundary from becoming a continuative inflow boundary (without specification), should the velocity field at the boundary become reversed. An example is shown in the final sample calculation discussed in Ref. 7:

$$\theta_i^{j-1} = \theta_i^j ,$$

$$(v_v)_i^{j-1/2} = (v_v)_i^{j+1/2} ,$$

$$(v_d)_i^{j-1/2} = (v_d)_i^{j+1/2} ,$$

$$(\rho'_{v1})_i^{j-1} = (\rho'_{v1})_i^j ,$$

$$(\rho'_v)_i^{j-1} = (\rho'_v)_i^j ,$$

$$(I_v)_i^{j-1} = (I_v)_i^j .$$

For all three types of boundary conditions, there is no gradient in droplet densities or internal energies across the boundary:

$$(\rho'_{d1})_i^{j-1} = (\rho'_{d1})_i^j ,$$

$$(\rho'_d)_i^{j-1} = (\rho'_d)_i^j ,$$

$$(I_d)_i^{j-1} = (I_d)_i^j ,$$

nor is there any gradient in the tangential component of velocity across the boundary:

$$(u_v)_{i-1/2}^{j-1} = (u_v)_{i-1/2}^j ,$$

$$(u_d)_{i-1/2}^{j-1} = (u_d)_{i-1/2}^j ,$$

$$(u_v)_{i+1/2}^{j-1} = (u_v)_{i+1/2}^j ,$$

$$(u_d)_{i+1/2}^{j-1} = (u_d)_{i+1/2}^j .$$

This specification of tangential velocity is required only for marker particle movement, discussed in Sec. II.E. Because there is no shear viscosity in this version of the code, the external tangential velocities are not otherwise referenced.

The momentum components in Phase 1 have values at the boundary that are based on the density and velocity of vapor or droplets, as appropriate, at that boundary position, in accordance with the above treatments.

The boundary conditions are initially set in the problem setup. The exterior values of the explicit variables are reset in Phase 1 as the neighboring fluid-side  $n+1$  values become available. During the pressure iteration in Phase 2, the exterior values of  $\bar{p}$ ,  $\bar{\rho}'_v$ , and the wall velocities are updated continuously to keep them appropriate to the continuously changing interior values, and  $\rho'_{v1}$  is treated similarly in the second iteration.

Note that KACHINA requires no special pressure boundary conditions. This is a direct benefit of the Chorin-Hirt method<sup>10</sup> chosen for the Phase 2 iteration procedure, which also contributes to efficiency and simplification of the solution process.

### F. Sudden Incompressibility

In certain flow situations, the vapor can be almost completely extruded from some cell or number of cells. We conclude that the droplets have come into rigid contact with one another, so that the  $\vec{u}_d$  field has suddenly become essentially incompressible. An analogous situation is that of a set of billiard balls on a table, which may be moved about with great freedom until they are drawn together and racked into the triangle, whereupon they become tightly packed. The billiard balls may subsequently be separated and resume their previous freedom of movement; similarly, the flow that became so suddenly incompressible may open up again at some later time.

Sudden incompressibility must be allowed for and treated in a special manner in a multifield computing model; otherwise, the calculation will almost surely break down sooner or later. Fortunately, the void fraction will forewarn of the situation if it is carefully monitored on a cell-by-cell basis, as in such instances  $\theta$  will become small. We test whether each  $\theta^{n+1} < \theta_0$ , where the value  $\theta_0 = 0.02$  has been found appropriate, at least for the test problems we have run. Usually, of course,  $\theta^{n+1} > \theta_0$ , and the calculational procedure is the standard one described in the preceding sections. For those cells in which  $\theta^{n+1} < \theta_0$ , in principle the only modification required would be simply to force the velocity divergence to vanish by reducing the  $\tilde{D}$  equation in Phase 2 to a  $\nabla \cdot \vec{u}_d = 0$  expression. In KACHINA, we begin by setting  $\theta^{n+1} \equiv 0$ , principally to make such cells highly visible in the numerical printout. Alternatively, we could leave  $\theta$  at its calculated value, which would be the required procedure if  $\theta_0$  were somewhat larger, as for example in a relatively porous bed of close-packed granules. In practice, there are actually several places in each of the two phases at which we change the computational procedure. In Phase 1:

(1) We set

$$\theta_i^{n+1,j} = 0 \quad ,$$

$$\tilde{p}_i^j = p_i^j \quad ,$$

$$A_i^j = A_\infty \quad ,$$

$$K_i^j = K_\infty \quad ,$$

where  $A_\infty$  and  $K_\infty$  are some large numbers, say about  $10^{10}$  times the ordinarily expected magnitudes of these quantities. The choice of time level  $n+1$  for the  $\theta$ 's appearing in the standard  $K$  equation is dictated by the fact that when a suddenly incompressible region opens up again, the restored condition  $\theta^{n+1} > \theta_0$  will allow passing of this test and re-establishment of the standard procedure for the cell. However,  $\theta = 0$  because of the previous state of the cell, and use of this old flag as  $\theta$  in the  $K$  equation would cause the computer to try a division by zero.

(2) In the  $I_V^{n+1}$  equations, we eliminate two terms. The drag term is omitted on the assumption that  $\vec{u}_v$  and  $\vec{u}_d$  must be very closely tied together, and the work term is omitted because no work can be done on the vapor in such cells.

(3) Neither the momentum equations nor the initialization of the tilde velocities at the beginning of Phase 2 requires changing, because with  $K = K_\infty$ , the initializations force  $\vec{u}_v \equiv \vec{u}_d$ .

In Phase 2:

(4) Those cells with  $\theta^{n+1} < \theta_0$  require different expressions for both  $\beta_p$  and  $\tilde{D}$ :

$$(\beta_p)_i^j \equiv \frac{\delta r^2 \delta z^2}{2\delta t (\delta r^2 + \delta z^2)} (\rho'_d)_i^j \quad ,$$

$$\begin{aligned} \tilde{D}_i^j = & \frac{1}{r_i \delta r} \left[ r_{i+\frac{1}{2}} (\tilde{u}_d)_{i+\frac{1}{2}}^j - r_{i-\frac{1}{2}} (\tilde{u}_d)_{i-\frac{1}{2}}^j \right] \\ & + \frac{1}{\delta z} \left[ (\tilde{v}_d)_i^{j+\frac{1}{2}} - (\tilde{v}_d)_i^{j-\frac{1}{2}} \right] \quad . \end{aligned}$$

Note that no consideration of donor-cell formulations arises in this  $\nabla \cdot \vec{u}_d$  form of the  $\tilde{D}$  equation.

(5) Neither the intermediate nor final values of pressure, density  $\rho'_v$ , or velocity in Phase 2 require changing. As in (3) above, the equations will automatically provide  $\vec{u}_v^{new} \equiv \vec{u}_d^{new}$ , and they arrive at values that ensure  $\nabla \cdot \vec{u}_d = 0$  for those particular cells.

(6) The  $\rho'_{v1}$  iteration requires no changes.

## II. THE KACHINA COMPUTING PROGRAM

### A. General Structure

KACHINA was written for the CDC-7600, to provide a tool for several specific studies and for further methodology development. It embodies a number of features to make efficient use of computer storage and time, and it follows the better programming concepts, ill-defined but popularly called "structured programming," that have received so much attention recently. The basic KACHINA will be extended in several directions by a number of investigators, and its modular form has already worked successfully in other recent computing programs. The physical arrangement and the top-to-bottom flow in the coding correspond to the logical sequence of the computing cycle to the greatest degree practicable. The efficiency loss that results from writing the entire code in a higher level language rather than in machine language is hopefully counterbalanced by increased readability for most users and the simplification of adapting it in the future for use at other installations and for computers other than the CDC-6000/7000 series. Computing efficiency can be increased substantially by carefully rewriting the iteration sections in machine language, which we strongly recommend to anyone doing a significant amount of calculation with a FORTRAN program containing any iterative solutions.

As depicted in Fig. 5, KACHINA is built in an overlay fashion to minimize the use of Small Core Memory (SCM), the fast memory on the CDC-7600. The main overlay (0,0) always resides in SCM, and it contains the main controlling program, KACHINA. Subserving to it are the longer programs in the two primary overlays, (1,0) and (2,0), which reside on disk storage. KASET is the setup program, and KACHYDR performs the two-phase hydrodynamics described in Sec. I.

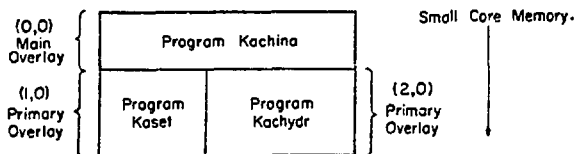


Fig. 5. The KACHINA three-program overlay structure.

The structure within each of these three programs is further detailed in Fig. 6, which introduces the UPDATE notation used in the actual code.

In addition to the main program, KACHINA, the (0,0) overlay contains the common KSC, which is the SCM portion of the information written on tape for restarting purposes and is therefore the natural repository for all the SCM data that must be retained from cycle to cycle. Any subroutines that will be referenced by the primary overlays should also be placed in (0,0) to ensure that they are always resident in SCM and directly accessible by all programs. At present, LOOP is the only such subroutine; its function is described in Secs. II.C and II.D.

To set up a calculation from initial input data, the main program calls the (1,0) overlay program KASET from the disk and surrenders control to it. This overlay is placed in SCM immediately following the (0,0) overlay. KASET itself is only a two-instruction program; it prints "SETUP" to indicate that control has reached (1,0), and then immediately calls subroutine SETUP to perform the actual setup, creating the computing mesh with its initial cell quantities, and generating marker particles if they

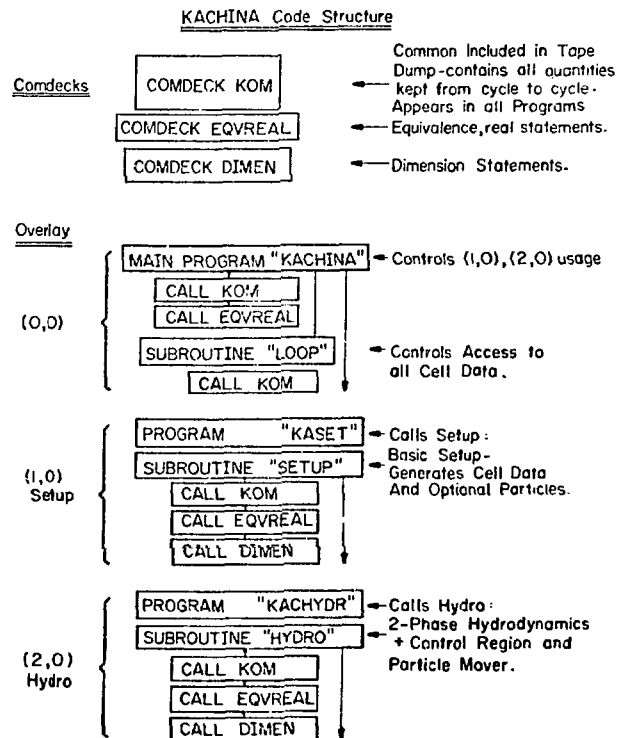


Fig. 6. The KACHINA overlays, showing the functions of all sections and the UPDATE nomenclature.

are specified. SETUP also sets boundary conditions for the edges of the mesh and determines parameters for microfilm plotting. When the problem setup is completed, SETUP returns control to the (0,0) main overlay program.

To calculate after setting up, the main program calls the (2,0) primary overlay KACHYDR from the disk and surrenders control to it. Because this overlay is of the same level as (1,0), it covers the image of (1,0) in SCM, as it is read in to the same locations following the (0,0) overlay and thus allows reuse of the SCM space. Like KASET, KACHYDR is a two-instruction program: it prints "HYDRO" and immediately calls subroutine HYDRO. Should the job abort because of an unexpected error, the printed message allows the user to ascertain quickly which program he is in, which might otherwise be difficult inasmuch as the range of instruction addresses for both the (1,0) and (2,0) overlays starts at the same point.

HYDRO is the largest section of code in the computer program. It contains the two-phase hydrodynamics, the calculational cycles of which are repeated continuously under the direction of a "control region." This region is strategically placed at the beginning of the subroutine, at which point in the cyclic process the quantities of greatest interest representing the solution at a given instant in problem time, are available. The control region provides all microfilm plots and numerical listings of cell data. It also increments the problem time  $t$  by the current  $\delta t$ , performs tape dumps and tape restarts, and senses problem completion or an impending operating system time limit. In the latter two events, it returns control to the main program, which, in turn, always searches the input queue for further tasks. If there are none, the job is ended.

To restart a calculation from a tape dump, the main program bypasses the (1,0) overlay and calls (2,0) instead. HYDRO senses the restart condition immediately, and the control region reads the information from tape into memory and turns control over to the point in the calculation cycle that will continue the problem from where it left off when the tape dump was made.

### B. The Indexing Notation

Figures 2 and 4 show that some variables are defined at cell centers and some at cell edges, as is typical of a number of Eulerian computing methods. In FORTRAN, one can represent  $p_i^j$  simply by "P(I,J)," but  $u_{i+\frac{1}{2}}^j$  cannot be represented by a "half-integer" index, so our convention is that "U(I,J)" denotes this particular velocity. Thus the indices I and J denote a quantity located at the center of cell (i,j), at the right edge ( $i+\frac{1}{2},j$ ), or at the top edge ( $i,j+\frac{1}{2}$ ), depending on where the quantity is defined to be by the difference equations. In KACHINA, "(I,J)" is replaced simply by "(IJ)," as only single subscripts are used for computer efficiency. In the KACHINA subscript notation, the letter "P" stands for "+," and "M" stands for "-." Thus, we write

$$IJ = (i,j) ,$$

$$IMJ = (i-1,j) ,$$

$$IJM = (i,j-1) ,$$

$$IPJP = (i+1,j+1) ,$$

etc.

Such a notation permits easy reading of programmed difference equations in the code. Figure 7 shows the single subscripts used to define cell quantities about a cell (i,j).

As the number of cell edges in either direction is one greater than the number of cells, it is

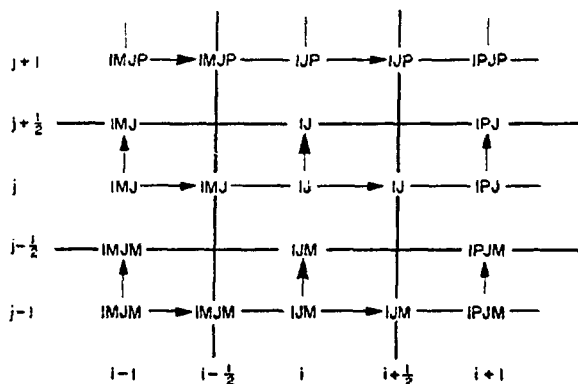


Fig. 7. Single-subscript notation for cell and cell-edge quantities about cell (i,j).

apparent that the grid in computer storage must be at least  $(\bar{I}+1)$  by  $(\bar{J}+1)$  in size. Because our indexing refers to cell centers and right and top edges, one extra column of storage on the left and one extra row along the bottom are provided. KACHINA also includes an extra row of cells across the top and an extra column up the right, giving a mesh that is  $(\bar{I}+2)$  by  $(\bar{J}+2)$  in extent. As described in Sec. I.E, these exterior zones are known as outside or fictitious cells, and surrounding the mesh with them helps in treating the boundary conditions.

An example of the actual KACHINA mesh for the virtual mesh of Fig. 1 is shown in Fig. 8, from which it is evident that double DO loops in FORTRAN to sweep all cell centers would have the limits  $J=2$  to  $JPI$  and  $I=2$  to  $IPI$ . Similarly, DO loops with limits  $J=2$  to  $JPI$  and  $I=2$  to  $IBAR$  will access all interior u velocity components, and those with limits of  $J=2$  to  $JBAR$  and  $I=2$  to  $IPI$  will access all interior v velocity components. Boundary velocities and exterior values of the cell-centered variables receive special treatment and are not normally included within the limits of the DO loops.

### C. Storage of Cell Data

Although the present modest size of the code certainly doesn't warrant overlay construction, the basic KACHINA of this report has been built to allow for considerable expansion in two respects. First, calculations will become more finely resolved, implying use of several thousand computing cells. Second, more coding will be added to deal with other physical phenomena. This coding will include such features

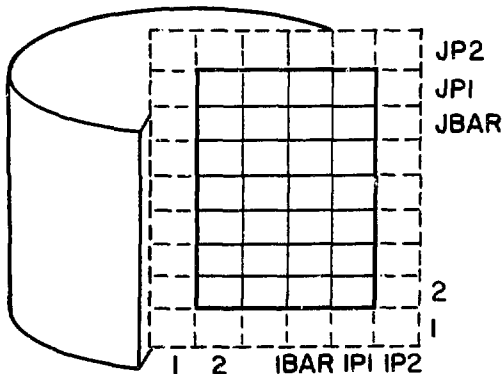


Fig. 8. KACHINA indexing scheme for the virtual mesh of Fig. 1, showing an example with many fewer cells than ordinarily are used for a calculation.

as phase transitions, a third field, more realistic equations of state, chemical and nuclear processes, and better isotropic force treatments, to name only a few. Both these considerations will greatly increase the demands on SCM space, and it is far better to allow for such growth in the initial architecture of a program than to have to add it later in some fashion that would require substantial rewriting to retain reasonable efficiency.

In addition to the overlay structure, KACHINA has several provisions for storage of cell data to allow efficient use of SCM. SCM requirements are significantly reduced by our use of only 19 storage words per cell, although the full calculation cycle requires 32 variables. Use of so few storage words is made possible by retaining quantities during a cycle only as long as they are needed, and then using their storage words for other quantities. Figure 9 shows the allocation of the 19 storage words for a KACHINA cell in the (1,0) and (2,0) overlays. The ordering from left to right corresponds to the actual order in which quantities are calculated in the code. A black dot indicates that the quantity currently in the given storage word is referenced to calculate the quantity specified at the top of the column.

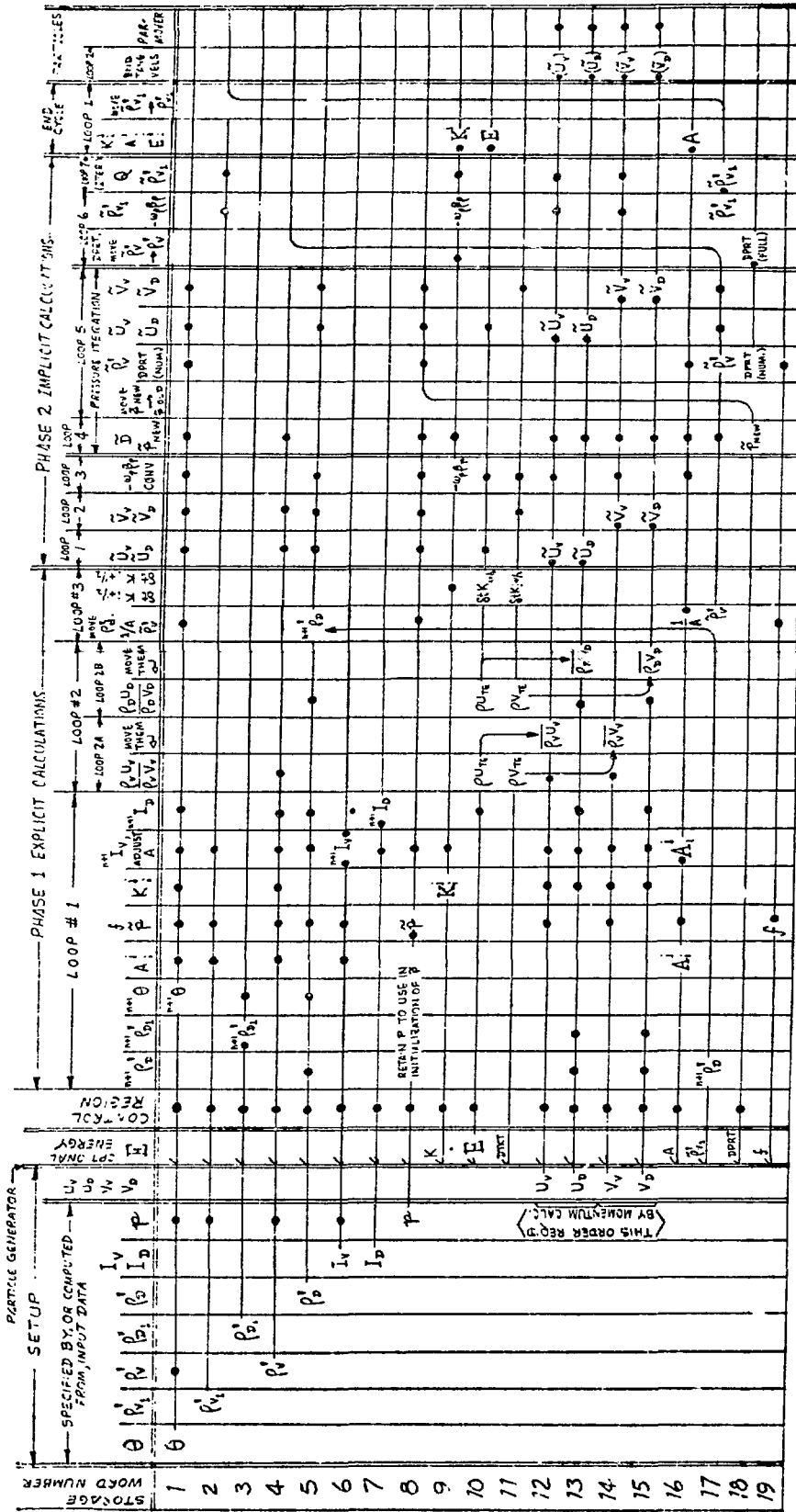
Note that before the iterations, the cell edge quantities  $\delta t K_{i+\frac{1}{2}}^j$  and  $\delta t K_i^{j+\frac{1}{2}}$  and the cell quantity  $(-\omega_p \beta_p)_i^j$  are formed, and that  $A_i^j$  is converted to its reciprocal. Because all these quantities remain invariant in the iterative process, it is expedient to compute them throughout the mesh beforehand to avoid needless repetitive calculation within the iteration itself.

During the pressure iteration,  $\tilde{\rho}_p^{new}$  replaces  $\tilde{\rho}_p^{old}$  as soon as there is no further need to keep  $\delta p$  available in memory. As the iterations are completed, the field values of  $\tilde{D}$ ,  $K$ , and  $A$  are retrieved in case they are to be listed numerically in an output routine in the next pass through the control region. Also,  $\tilde{\rho}_v'$  replaces  $\rho_v^n$  in word 4, becoming  $\rho_v^{n+1}'$  by doing so, and similarly  $\tilde{\rho}_{v1}'$  replaces  $\rho_{v1}^n$  in word 2, becoming  $\rho_{v1}^{n+1}'$ .

In the Phase 1 explicit calculations, the convection equations require neighboring values (on all four sides of the cell) of the variable being solved for. To maintain the correct time level (n) of these

# KACHINA STORAGE CHART

REV. TO 6/19/74



WORD #:	EQUIN:	NAME:	TH	WORD #:	EQUIN:	NAME:
1	$\theta$	ROVPR1	10	11	$E, \rho_{uTe}, \rho_{K, vTe}$	E, ROUTE, DTKR
2	$\rho_1^i$	RODPR1	11	12	$UV, \rho_{UV}$	ROVTE, DTKT
3	$\rho_2^i$	ROVPR	12	13	$Uv, \rho_{Uv}$	UV, ROUV
4	$\rho_3^i$	RODPR	13	14	$U_b, \rho_{U_b}$	UD, ROUD
5	$\rho_4^i$	ROVPR	14	15	$V_v, \rho_{V_v}$	VV, ROVV
6	$\rho_5^i$	SLEV	15	16	$V_b, \rho_{V_b}$	VD, ROVD
7	$I_v$	SIED	16	17	$A, 1/A$	A, RA
8	$I_b$	P	17	18	$CQ, \rho_{UVPR1}, \rho_{DPR1}, \rho_{RNPRT}$	CQ, ROVPR1, RODPR1, RONPR1
9	$K, I, \rho_{K, vTe}, \rho_{K, vTe}$	KIJ, GAMBETA	18	19	$P_{NEW}, D$	PP, DPR1
						F

Fig. 9. The storage of cell data in KACHINA, showing how the 19 words per cell are allocated among 32 named variables during the cycle.



referenced variables, the new (n+1) values could be stored in completely separate arrays and later transferred, just as  $\rho'_v$  and  $\rho'_{v1}$  are handled. We have chosen, instead, to temporarily store aside  $\bar{I}$ -length vectors of the (n+1) values, transferring them at the end of each row to relieve the demands on cell storage.

It appears that using fewer than 19 words per cell would complicate the computer logic significantly while providing very little gain, and using more than 19 would begin to waste space. Our various storage treatments have been governed by a balance between these considerations.

The contour quantity (CQ) in the control region denotes the field of some chosen cell variable for which a contour plot is drawn on microfilm. The present choices are all of the quantities in words 1 through 10, which are automatically plotted in sequence by placing the complete field of each quantity in CQ as its plotting turn occurs. This transfer to CQ could be avoided by simple indexing through words 1 to 10, but intermediate storage in CQ allows values to be adjusted specifically for plotting purposes, as is sometimes necessary.

Charts such as Fig. 9 have proven extremely useful in initially planning the storage before a code is written, but they are equally useful thereafter in visualizing the quantities available at any given point in the calculation cycle, and the locations of storage vacancies. The storage layout changes frequently during the development of the code, and the version in Fig. 9 is certainly not final for KACHINA.

Reducing the number of storage words per cell, as discussed above, will help to allow larger meshes to fit in SCM, but eventually SCM space is exhausted. The next step is to transfer all the cell data to Large Core Memory (LCM), reading only some part of the mesh at a time into an SCM buffer for processing, and then rewriting it back out to LCM. The optimum procedure is that which requires the minimum number of read/write references to LCM, and one could, indeed, tailor the logic for each problem to do this. The procedure we have chosen, however, simply deals with three j-rows of cells at a time in SCM processing, without regard to overall mesh dimensions. To facilitate inclusion of the LCM routine described in Appendix C, the cell variables are stored "interleaved"

with all the variables for a given cell stored contiguously, followed by all the variables for the next cell, etc. (Contrast this with the other method of storing cell variables in individual  $\bar{I}$  by  $\bar{J}$  blocks for each variable. That scheme is competitive only when the computing code is designed for smaller meshes that will always fit in SCM.)

In the SCM version of this report, the storage block AASC contains all cell data. At present, it has a dimension of 26 676 words, allowing any combination of  $1P2$  by  $JP2 \leq 1404$  cells, at 19 words per cell. A 25 by 50 logical mesh, requiring an actual 27 by 52 mesh, dictated this particular choice. With the transfer of cell data to LCM, however, it is no longer appropriate to retain AASC within the main SCM common KSC, because KSC should contain only the tape restart information. Therefore, AASC is defined in a separate SCM common that is never written on tape, and the tape dump/restart routines are modified to write/read the entire LCM storage block of complete cell data. These and related matters are discussed in detail in Appendix C.

Next, we must consider how the code actually accesses cell data.

The single-subscript index notation described in Sec. II.B can remain the same, whether the cell data are stored in SCM or LCM, because the actual location of the data is transparent to the primary overlays. Subroutine LOOP in the (0,0) overlay is of crucial importance here, as it has complete control over all references to cell data and relieves the primary overlays of any direct concern with cell data transfers.

In essence, LOOP's responsibility is simply to have three rows of the mesh,  $j$ ,  $j+1$ , and  $j-1$ , available in SCM for processing, and to have the corresponding indices  $IJ$ ,  $IJP$ , and  $IJM$  set properly to the column  $i=2$  cells to begin the processing of each row. At the end of each row, LOOP must step up the one row in  $j$  and reset the three indices accordingly.

In the SCM version of the program, this process is trivial because no LCM logic is involved. Sweeps over the mesh always begin at the lower left corner and move across to the right edge, then up by rows of cells. To begin a typical sweep, the calling program CALLS the "START" entry in LOOP, which merely sets  $IJ$  to reference the lower left cell (2,2),

IJP to reference the cell (2,3) above it, and IJM to reference the cell (2,1) below. Control is then RETURNed to the calling program, which then initiates an ordinary double DO loop.

Secondary indices are often needed to reference cells located in columns to the left or right of the column identified by IJ, IJP, and IJM. These indices are easily obtained by applying increments or decrements of the variable NQ, the number-of-quantities, that is, the number-of-storage-words-per-cell, to the three primary indices. In this manner, reference can be made to any neighbor of cell IJ shown in Fig. 7.

Similarly, the calling program can progress across the row from left to right by adding NQ to each index, to advance one column at a time. At the end of the row, the I DO loop falls through, leaving IJ, IJP, and IJM referring to cells in column IP1. A CALL is then issued to the "LOOP" entry point in LOOP, which increments the three indices over two additional columns by adding (2\*NQ) to each index. This actually sets the indices back to the left and up through column 1 of the next row, stopping at column 2. Control is again RETURNed to the calling program, and this process is repeated until the entire mesh has been swept, as indicated by the fact that the outer DO loop on J falls through.

The number of storage words per cell in this KACHINA version is seen to be  $NQ = 19$ , as per Fig. 9. This number may be increased very simply by adding the new variables to the EQUIVALENCE and DIMENSION statements in the Comdecks EQVREAL and DIMEN, and re-defining NQ in the (0,0) main program at one place only.

#### D. An Optional Three-Row Buffering Scheme

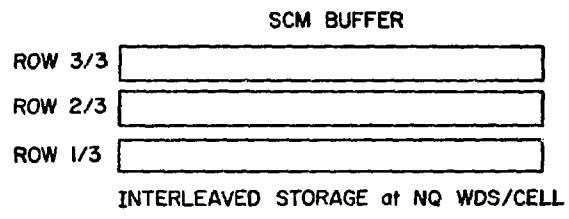
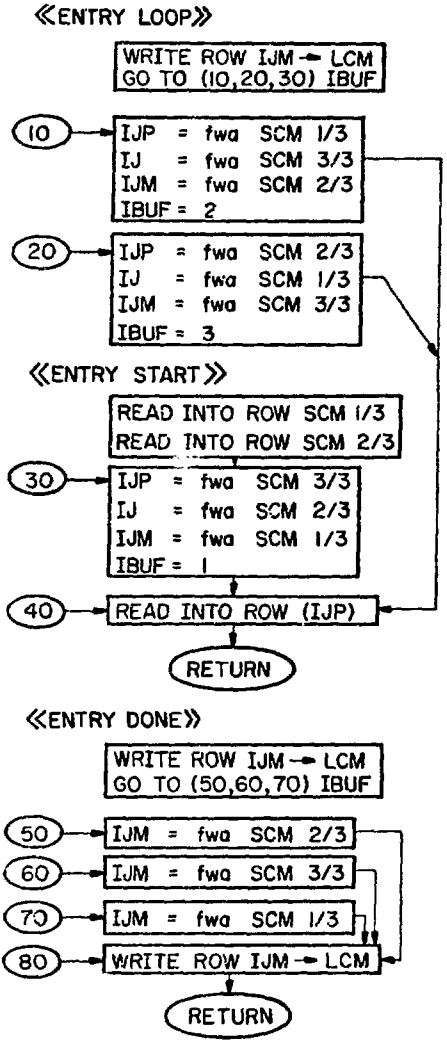
When placing all the cell data in LCM, the most significant modification to the code logic is to replace subroutine LOOP by an expanded version that will shuttle the cell data between the large LCM array and the small SCM buffer where it is operated on. These changes are detailed in Appendix C. Generally, LOOP will keep three complete rows of the mesh in SCM at any one time: the row being processed and the rows above and below, again referred to by IJ, IJP, and IJM. All calculations affecting cell data are actually performed directly on the current contents of the buffer. The merit of interleaving the cell data now becomes evident, as all quantities pertain-

ing to the three rows of cells are instantly available. The schematic flow diagram and sample FORTRAN DO loop in Fig. 10 enlarge on the previous discussion to show how buffering can be added.

(1) As in the SCM version, the "START" entry of LOOP is CALLED before the double DO loops are initiated. But now, START reads in the entire contents of the bottommost three rows of the mesh from LCM to the SCM buffer, placing row  $j=1$  in the buffer section designated "row 1/3;" likewise, row  $j=2$  is read into "row 2/3," and row  $j=3$  is read into "row 3/3." Rows 1/3, 2/3, and 3/3 are contiguous in SCM, and like their counterparts in LCM, each contains  $NQI = NQ * IP2$  words. With the three rows read in, the calling program needs to know how to access data in the buffer. As before, this information is provided by setting IJM, IJ, and IJP to point to the first words of the  $i=2$  column of cells in each row. Thus, IJM points to an address NQ words into SCM row 1/3, as do IJ in row 2/3 and IJP in row 3/3. Note the indicator IBUF, which is set to 1; it will control the subsequent reading and writing of individual rows and the resetting of the three indices. With the first three rows of cells read in and the basic indices set, control can be RETURNed to the calling program.

(2) The double DO loops are initiated, and processing is performed exactly as previously described for the SCM version. In the example shown in Fig. 10, we calculate the average  $u_v$  and  $v_v$  at the center of cell (i,j). The terminal statement of the inner DO loop, which again counts columns within each row, is statement No. 89. Note how the primary indices IJ and IJM are advanced to the next column in the row. The inner loop on I is repeated until the row is completed, at which time control passes to the "CALL LOOP" statement.

(3) The LOOP entry immediately writes row IJM back into LCM, and, depending on the value of IBUF, goes to statement No. 10, 20, or 30. Because IBUF was initially set to 1, control passes to statement No. 10 in our example. Note that now the indices IJP, IJ, and IJM are reset to point to different SCM rows -- IJP to the vacated row 1/3, IJ to J/3, and IJM to 2/3. IBUF is reset to 2 to control the next entry to LOOP, and control passes to statement No. 40 which will read the new IJP row, row  $j=4$ , into



LOOP EXAMPLE:

```

    CALL START
    DO 99 J = 2, JPI
    DO 89 I = 2, IPI
    IMJ = IJ - NQ
    UIJ = 0.5 * (UV(IJ) + UV(IMJ))
    VIJ = 0.5 * (VV(IJ) + VV(IMJ))
    IJ = IJ + NQ
    IJM = IJM + NQ
    CALL LOOP
    CALL DONE
  
```

ROW 3/3	→ (IJP) 3	(IJ) 3	(IJM) 3	(IJP) 6	(IJ) 6	(IJM) 6	(IJP) 9
ROW 2/3	→ (IJ) 2	(IJM) 2	(IJP) 5	(IJ) 5	(IJM) 5	(IJP) 8	(IP) 8
ROW 1/3	→ (IJM) 1	(IJP) 4	(IJ) 4	(IJM) 4	(IJP) 7	(IJ) 7	(IJM) 7

Fig. 10. KACHINA three-row buffer.

SCM row 1/3. Observe that there has been no unnecessary shuffling of data in SCM: row  $j-1$  was read out and replaced by row  $j+1$ , and the three indices were reset to point to the locations of rows  $j+1$ ,  $j$ , and  $j-1$ . As shown at the bottom of Fig. 10, the grid rows in SCM are in their actual logical order only every third row.

(4) LOOP returns to the calling program, advancing the outer DO-loop index J, and rows are processed similarly until all those specified by index J have been processed. Then control passes to the "CALL DONE" statement, an entry point that simply RETURNed in the SCM version.

(5) DONE is really only a cleaning-up operation. Because no further LCM reads are required, it merely writes the final two rows,  $j$  and  $j+1$  (JP1 and JP2, respectively) back out into LCM. CALL DONE can be omitted on those loops, such as certain output routines, that reference but do not alter cell data.

Not indicated in the flow of Fig. 10 is the incrementing of the relative address indices for reading and writing LCM. These indices are initially set to 0 and incremented by NQI as processing progresses up the mesh.

Complete information on converting KACHINA to an LCM version with the three-row buffer routine is provided in Appendix C, which lists the changes required to convert the basic SCM version of KACHINA provided in Appendixes A and B.

The SCM version has been built so that the (1,0) and (2,0) overlays are completely compatible with LCM usage and require no modification in the conversion.

Recall that the SCM buffer AASC becomes separated from the SCM common block KSC. A dimension of only  $5814_{10}$  words ( $=3$  rows  $\times$  19 words per cell  $\times$  102 columns) will allow any  $\bar{I} \leq 100$ . Considering the reduction from the present 26 676 words, and also the great capacity of LCM (on the order of  $400K_{10}$  words are available), it becomes evident that very large problems can be run with the LCM version of KACHINA. Further, the goal of freeing a considerable amount of SCM space is achieved.

#### E. Marker Particles

Marker particles are a purely optional feature in KACHINA, as they do not influence the flow, but are simply carried along with it. Microfilm plots of

particle coordinates are often a very useful form of visual output, as they not only distinguish readily the regions occupied by the various components, but also indicate relative proportions of the interpenetrating components within each region. Marker particle plots also aid in the location of shock fronts, rarefaction waves, and regions that have become incompressible. These benefits become especially evident when motion pictures are generated by drawing a plot each calculation cycle. For these reasons, marker particles are a valuable part of most KACHINA studies.

Although the markers are moved by fluid velocities in the usual fashion, which will be described at the end of this section, the concept of our multifield KACHINA model introduces some novel aspects of marker creation.

First, it is appropriate to have a separate set of particles for each field component. This is necessary to allow accurate particle movement in our interpenetrating fluid model and to provide the proper visual distinction between the fields and their components. Each particle is tagged to indicate the component with which it is associated. This tag not only specifies whether the particle is to be moved according to  $u_v$  and  $v_v$  velocities or  $u_d$  and  $v_d$  velocities, but also indicates the plotting symbol chosen to identify the component.

The second novel aspect is the initial particle distribution. In the typical fluid-dynamics computer code, the density and spacing of particles is determined by specifying the total number of particles per cell in each direction, but in KACHINA we specify the total number of particles per unit area, called NPUA, expressed in cell units. In combination with the initial void fraction and the densities in each particular area, NPUA is subdivided into appropriate parts to determine the effective number of particles per unit area (PNEFF) for each type of particle. Therefore, a region with a large void fraction will contain a higher ratio of vapor particles to droplet particles than will a region with a smaller void fraction. The larger  $\theta$  is, the smaller the number of droplet particles dispersed over the region, and at the limit  $\theta = 1$ , no droplet particles at all will be generated. The situation reverses as  $\theta \rightarrow 0$ , and at  $\theta = 0$ , no vapor particles are generated.

The densities play a similar role in the initial particle distribution, allowing for the distinction between the components themselves by controlling the number of particles of each component generated. Thus, the particles mirror the proportions of the components, a useful and desirable feature.

Particle generation over some fluid region takes place in KACHINA according to the following method. We assume a rectangular region of the mesh, encompassing some integer number of cells, where the number of cells in the radial direction is denoted by  $w$ , and that in the axial direction by  $h$ . Also specified for this region are NPUA and the initial values of  $\rho'_{d1}$ ,  $\rho'_{d2}$ , and  $\theta$ , as we presently allow the creation of two types of droplet particles, but only one of vapor. In this case, three passes rather than four will be made to generate the particles for the region, one pass for each particle type. The major steps repeated for each of these three passes are as follows.

(1) PNEFF is calculated, and is given by one of the following equations, depending on which of the three passes is being performed.

(a) For droplet component number 1,

$$PNEFF = (NPUA) \left( \rho'_{d1} / \rho'_{d2} \right) (1 - \theta) ;$$

(b) For droplet component number 2,

$$PNEFF = (NPUA) \left[ 1 - \left( \rho'_{d1} / \rho'_{d2} \right) \right] (1 - \theta) ;$$

(c) For the vapor,  $PNEFF = (NPUA) \theta$ .

(2) A uniform matrix of particles is to be laid down over the region, the total number to be given by the product of XNP particles in the  $r$  direction times YNP particles in the  $z$  direction. By this definition,

$$\frac{XNP}{YNP} \equiv \frac{w}{h} ,$$

and

$$(XNP) (YNP) \equiv wh (PNEFF) .$$

These equations are combined and solved for XNP and then YNP:

$$XNP = w (PNEFF)^{\frac{1}{2}} ,$$

$$YNP = (XNP) h/w ,$$

which are then rounded up to the nearest integers. The product  $(XNP)^2(YNP)$  is checked to ensure that it is greater than zero before proceeding to Step (3). If the product is zero, the logic should skip ahead to the pass for the next particle type.

(3) With the number of particles in each direction now determined for the type at hand, the spacing ( $s$ ) between particles is given by

$$x_s = w/XNP ,$$

and

$$y_s = h/YNP ,$$

and the coordinates of the first particle ( $x_1, y_1$ ) closest to the bottom left corner ( $c$ ) of the rectangular region are given by

$$x_1 = x_c + \frac{x_s}{2} ,$$

and

$$y_1 = y_c + \frac{y_s}{2} .$$

(4) This information is next fed into a double DO loop with limits given by XNP and YNP. This loop generates and stores the array of particles and appends to each  $x$  coordinate some identifying tag, depending on the number of the pass.

If desired, the variable "OFFSET" may be changed from its usual 0.0 to 1.0 to uniformly displace the entire particle matrix to the upper right by a distance  $x_s/4$  and  $y_s/4$ . For the use of OFFSET, refer to the description of a "part card" in Sec. II.F.

A set of three such passes is performed for each discrete fluid region in the mesh, each pass contributing some number of particles, which are accumulated into the total collection.

An example of the above scheme, with actual numbers and complete with drawings and chart, is given on the page labeled 4 in the Flow Diagram in Appendix A, where the complete flow for Marker Particle Generation also appears in detail.

The next particle consideration to be discussed is the scheme for moving them. For this purpose, the fluid (cell) velocities resulting from Phase I are sufficient, if the exterior tangential velocities are set, as mentioned in the discussion of Boundary Conditions. The particles are moved by use of a typical averaging scheme involving the nearest velocity components. As shown in Fig. 11, the reference cell (shaded) is defined as the cell lying between the lower pair of  $u$  velocities when the  $u$  of the  $k$ th particle ( $u_k$ ) is calculated. Similarly, the cell lying between the leftmost pair of  $v$  velocities is the reference cell when the  $v$  of the particle ( $v_k$ ) is calculated. These velocities are either vapor or droplet velocities, depending upon the type of particle  $k$ . The reference cells provide an indexing base for obtaining the four  $u$ 's and four  $v$ 's. The donor cell is defined as the cell containing the particle before it is moved, and there is a 10-10 chance that the reference cell is the donor cell for either  $u_k$  or  $v_k$ . If we denote the reference cell by (IR, JR) and the donor cell by (ID, JD), we can show with the aid of Fig. 11 that it is possible to calculate  $u_k$  in every possible case by using ID and JR in the formula

$$u_k = A_2 u(1D-1, JR+1) + A_1 u(1D, JR+1) \\ + A_3 u(1D-1, JR) + A_4 u(1D, JR) ,$$

without ever calculating the quadrant of the cell in which the particle  $k$  lies. Similarly,  $v_k$  is calculated using IR and JD:

$$v_k = A_2 v(IR, JD) + A_1 v(IR+1, JD) \\ + A_3 v(IR, JD-1) + A_4 v(IR+1, JD-1) .$$

The Flow Diagram and FORTRAN listing in Appendixes A and B show how the partial areas  $A_1$  through  $A_4$  and the single subscript equivalents to IR, JR, ID, and JD are obtained quickly without ever testing the particle's position. After  $u_k$  and  $v_k$  have been determined, the particles are moved according to

$$x_{k+1} = x_k + u_k \Delta t \\ y_{k+1} = y_k + v_k \Delta t ,$$

and

$$x_{k+1} = x_k + u_k \Delta t \\ y_{k+1} = y_k + v_k \Delta t .$$

Note that the particles in KACHINA are both generated and stored in units of cell distance rather than problem distance.

KACHINA allows for outflow, automatically destroying any particle that crosses a mesh boundary. This is done by using one index (KI) to pick up particles and a second index (KPI) to store the new coordinates. Both are identical initially, but whenever a particle leaves the system, KPI is not advanced, so the storage of all the remaining unmoved particles is shifted by one position. This shift automatically destroys the affected particle, as the next particle is stored over it.

No provision has been made yet to create particles at an inflow boundary (if one exists), but this would logically be done after all the particles have been moved. Generally, at least one column or row of new particles would be generated each cycle and stored on the index KPI where it was left after the particle movement. See Ref. 11 for details of logic for creation of particles at a typical inflow boundary.

#### F. The Input Data

BCD data cards punched according to specific formats can provide all the parameters required to set up a KACHINA calculation. The number of cards varies depending upon the complexity of the mesh geometry. However, the following cards must always appear.

**Card No. 1:** IBAR, JBAR, DR, DZ, AO, BO, ROTO, NUV, CDR, RPAR (Format 214, SFS.1), where:

IBAR =  $\bar{I}$ , the number of real (interior) zones in the radial direction.

JBAR =  $\bar{J}$ , the number of real (interior) zones in the axial direction.

DR =  $\delta r$ , the cell size in the radial direction.

DZ =  $\delta z$ , the cell size in the axial direction.

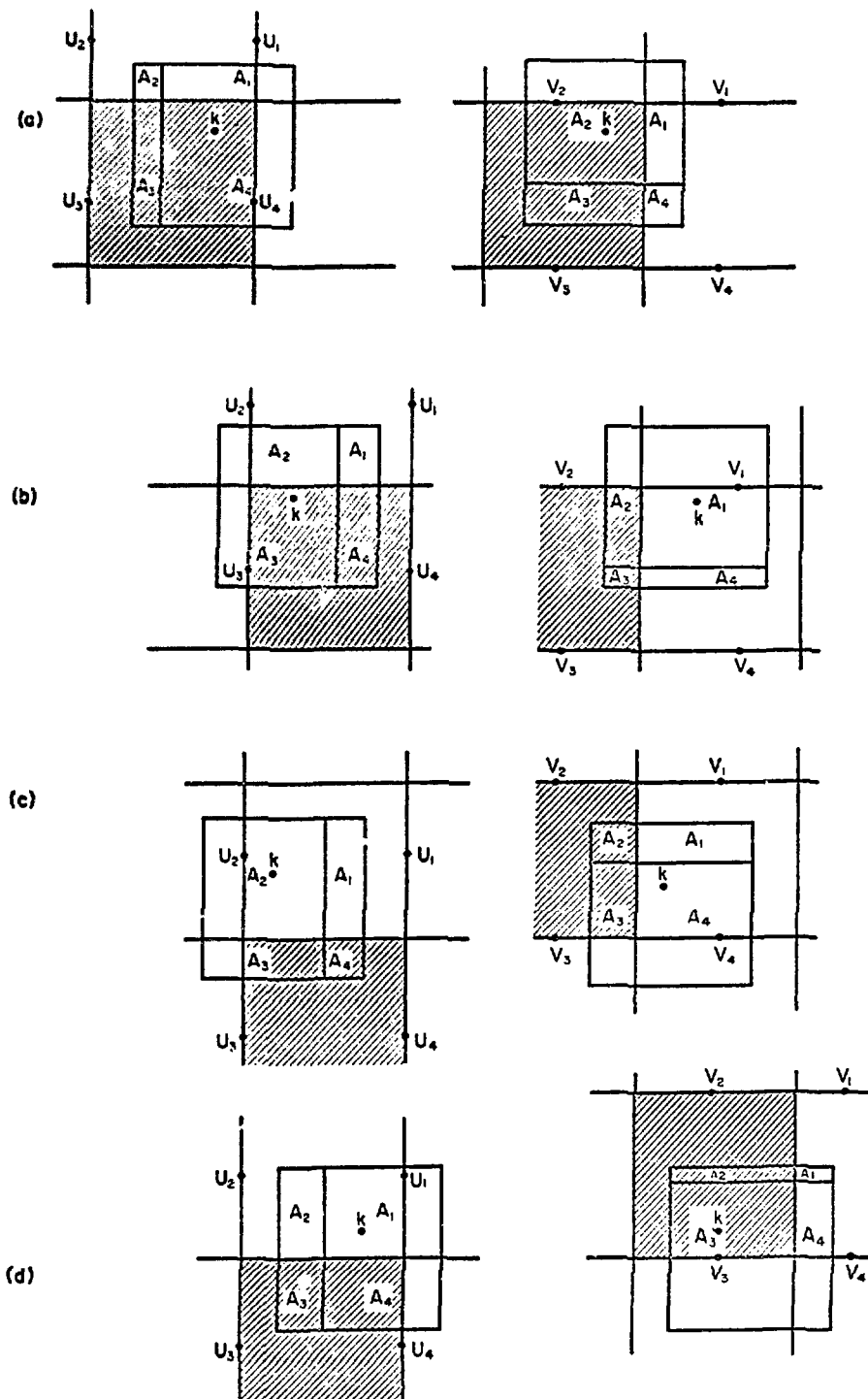


Fig. 11. Area velocity weighting scheme for  $u_k$  and  $v_k$ , with particle  $k$  shown for each of the four quadrants of the cell. The reference cell is shaded in each case. The subscripted  $u$  and  $v$  velocities are those of either vapor or droplets, depending upon the type of particle  $k$ .

$A0 = \alpha_0$  } constants denoting proportions of donor-cell  
 $B0 = \beta_0$  } convective fluxing. See Secs. I.C. and I.D.  
 $R0V0 = \rho_{v0}$ , specified vapor density for incompressible flow.  
 $NUV = \nu_v$ , kinematic viscosity coefficient for the vapor field.  
 $CDR = C_{DR}$ , the drag coefficient.  
 $RPAR = r_p$ , the mean linear dimension of a droplet.

Card No. 2: NAME (Format 8A10), where columns 2-80 are used for problem identification on prints and all film frames.

Card No. 3: IDC0MP (Format 8A10), where columns 2-80 are used to identify material components once at the beginning of the film and printer output. (On both these cards, column 1 is treated as a carriage control, so it should be left blank. If desired, both cards may be left entirely blank, but they must always appear in the input deck.)

Card No. 4: 0MP, 0MR0, EPS, G, KV, KD, EPV, EPD, R (Format 9F8.3), where:

$0MP = \omega_p$  } Phase-2 iteration relaxation parameters.  
 $0MR0 = \omega_p$  } See Sec. I.D for description.

$EPS = \epsilon_1$ , the convergence criterion for both iterative solutions in Phase 2. (With reference to Sec. I.D, only  $\epsilon_1$  appears in the input, whereas  $\epsilon_2$  is specified directly in the coding.)

$G = g$ , gravity felt by both vapor and droplets, acting only in the axial direction, which may be + or - to pull up or down, respectively.

$KV = k_v$  } Heat conduction coefficients for the vapor and droplet fields.  
 $KD = k_d$  }

$EPV = \epsilon_v$  } Epsilons for the Phase-1 nonisotropic force terms,  
 $EPD = \epsilon_d$  } for vapor and droplet fields, respectively.

$R = R$ , the exchange function that describes heat transfer between vapor and droplet fields.

Card No. 5: R01, R02, GAM1, GAM2, BV1, BV2, BD1, BD2 (Format 8F8.3), where:

$R01 = \rho_1$  } The actual microscopic material densities of the two droplet components.  
 $R02 = \rho_2$  }  
 $GAM1 = \gamma_1$  } The ratio of specific heats for the two vapor components,  
 $GAM2 = \gamma_2$  } appearing in Phase-1 A equation and pressure calculation.  
 $BV1 = b_{v1}$  } Specific heat constants for vapor and droplet components,  
 $BV2 = b_{v2}$  }  
 $BD1 = b_{d1}$  } appearing in Phase-1 A and T equations.  
 $BD2 = b_{d2}$  }

Card No. 6: JRIGID, IB0T, THIN, R0VIN1, R0VIN2, SIEVIN, VVIN, IT0P (Format 2I4, 5F8.3, I4), where:

$JRIGID$  = the integral number of cells up the right boundary that are to be treated as rigid free-slip. Any cells above  $JRIGID$  are treated as continuative outflow.  
 $0 \leq JRIGID \leq JBAR$ . See Sec. I.E.

$IB0T$  = Boundary condition for the (entire) bottom boundary, = 0 for rigid free-slip, = 1 for continuative outflow, = 2 for specified inflow, where:

$THIN = \theta_{in}$  } Parameters for specified inflow along bottom boundary when  
 $R0VIN1 = (\rho_{v1})_{in}$  }  $IB0T = 2$ ;  $\theta_{in}$ ,  $(\rho_{v1})_{in}$ ,  $(\rho_{v2})_{in}$ , and  $(I_v)_{in}$  refer to the  
 $R0VIN2 = (\rho_{v2})_{in}$  } center of the outside cell, and  
 $(v_v)_{in}$  is defined on the  
 $SIEVIN = (I_v)_{in}$  } boundary. See Sec. I.E.  
 $VVIN = (v_v)_{in}$  }

$IT0P$  = Boundary condition for the (entire) top boundary, 0 = rigid free-slip, 1 = continuative outflow.

Card No. 7: T, DT, T20MD, TLIMD, TWFIN, LPR, ISPR, (C0L0UR(N), N = 1, 3) (Format 5F8.3, 2I4, 3F4.1), where:

$T = t_0$ , the problem starting time, usually zero.

$DT = \delta t_0$ , the initial  $\delta t$ . Except in movie runs,  $\delta t$  is chosen automatically after cycle 10, according to the condition  $\delta t = 0.1 \min(\delta r/u_{max}, \delta z/v_{max})$ , where



$u_{\max} = \max(|u_v|, |u_d|)$  and  
 $v_{\max} = \max(|v_v|, |v_d|)$ , in which all  
 velocities over the mesh are considered.

T20MD = 1.0 to force tape dumps every 20 min of  
 central processor (CP) time for restart-  
 ing, or = 0.0 to bypass this option.  
 TLIMD = 1.0 to force a tape dump and RETURN to the  
 (0,0) overlay just before the CP time limit  
 specified on the JOB card is reached;  
 > 1.0 to force tape dump and RETURN imme-  
 diately after cycle 0 output; = 0.0 to run  
 out to a full time limit with no tape dump.  
 TWFIN = problem finish time. When this time  
 ( $t \geq TWFIN$ ) is reached, control returns to  
 the (0,0) overlay. (Upon RETURN to (0,0)  
 for either the TLIMD or TWFIN condition,  
 the (0,0) main program KACHINA searches  
 the input queue for further tasks.)

LPR = "Long Print" Control, where:  
 0 = movie option, 1 = cell-data listing on  
 microfilm only, 2 = cell-data listing on  
 both film and printer, 3 = cell-data list-  
 ing on printer only. These options are  
 described more fully in Sec. II.G.

ISPR = "Short Print" Control, where:  
 the four-line listing of summations of  
 mass, momentum, and energy is provided  
 each cycle if ISPR = 2, or only on those  
 cycles that have the "long print" of cell  
 data if ISPR = 1.

COLOUR(N), N = 1, 3 These parameters are effective only  
 for color microfilm processing, and are  
 intended for movies of particles, where  
 COLOUR(1) refers to droplet component  
 No. 1, COLOUR(2) refers to droplet com-  
 ponent No. 2, and COLOUR(3) refers to  
 vapor. Seven basic color choices are  
 available: 0.0 = white, 1.0 = red, 1.6 =  
 yellow, 2.0 = green, 2.6 = cyan, 3.0 =  
 blue, and 3.6 = magenta.

Card No. 8: (DTØ(N), N = 1, 10) is used in conjunction  
 with

Card No. 9: (DTØC(N), N = 1, 10) (both are Format  
 10F8.3), where DTØ<sub>n</sub> specifies the problem time out-  
 put interval for both plots and prints. DTØC<sub>n</sub> speci-  
 fies the time at which the change to DTØ<sub>n+1</sub>. As an  
 example, assume that t is in seconds, and that output  
 is wanted every 1/4 s for the first second, then

every 2 s up to 8 s of problem time, then every 1/8 s  
 up to t = 10, then more infrequently again, with out-  
 put only every 10 s until t = 200. One would use

DTØ (1-10) = 0.25, 2.0, 0.125, 10.0 ,

DTØC (1-10) = 1.0, 8.0, 10.0, 200.0 .

To keep the output time interval fixed throughout a  
 run, specify DTØ(1) = (interval) and DTØC(1) > TWFIN.  
 When an output time is being approached, the auto-  
 matic δt routine (see DT on Card No. 7) will choose  
 a special δt for one cycle so that the output occurs  
 at the precise time desired.

The above nine cards pertain to all KACHINA  
 setups. They have defined a mesh and provided the  
 parameters for its use. What remains to be defined  
 is the contents of this mesh -- fluid regions to fill  
 it in, and associated marker particles if desired.  
 One "part card" is used to define each fluid region  
 and any associated particles. Because the number of  
 fluid regions can vary with problem geometry, the  
 number of part cards also varies accordingly. The  
 present definition of a "part" is limited to a cy-  
 lindrical annulus, encompassing some rectangular  
 region of cells, and constrained to follow cell  
 boundaries. As shown in Fig. 12, four dimensions  
 are adequate to define each part. A part card con-  
 tains the following information:

NB, NR, NT, NL, RØDPRI1, RØDPRI2, RØV1, RØV2,  
 SIEVI, SIEDI, NPUA (Format 4I4, 6F8.3, I4), where:  
 NB } are four dimensions (see Fig. 12),  
 NR } specified in integer numbers of cells to  
 NT } emphasize that the part is constrained  
 NL } to follow cell boundaries. Thus, NL and  
 NB specify how many cells in from the  
 left and up from the bottom to locate

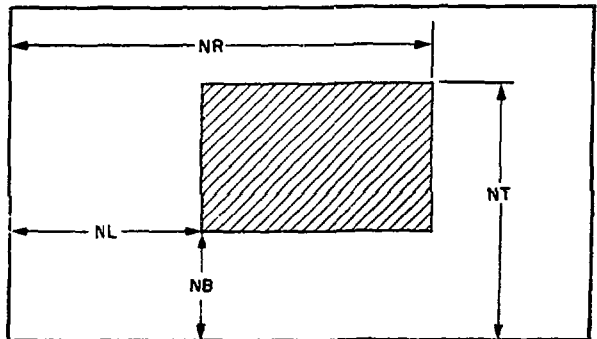


Fig. 12. Part shape available for fluid regions in  
 KACHINA, defined by the integral number of  
 cells over and up to the two corners.

the lower left corner of the region, and NR and NT similarly locate the upper right corner. As an example, if a single region is to cover the entire mesh, set NL = NB = 0, NR =  $\bar{I}$ , and NT =  $\bar{J}$ .

$R\bar{O}DPRI1 = (\rho_{d1})_i$   
 $R\bar{O}DPRI2 = (\rho_{d2})_i$   
 $R\bar{O}V1 = \rho_{v1}$   
 $R\bar{O}V2 = \rho_{v2}$   
 $SIEVI = (I_v)_i$   
 $SIEDI = (I_d)_i$   
 NPUA = number of particles per unit area, as described in Sec. II.E. Typical NPUA values in our test calculations have ranged from 1 to 4. To bypass the particle option, simply set NPUA = 0 for any or all parts. (Recall also the variable OFFSET appearing in the particle generator, which may be used to displace the particle arrays to the upper right. See Sec. II.E.)

Initial values of the variables necessary to completely specify all cells in the fluid region, as described in Sec. I.B. (All velocities are initially set to zero.)

The part cards are processed individually, and the number of fluid regions is unlimited, clear up to the extreme of one region for each cell. If different parts refer to the same zone or zones, the latest information will override any earlier specifications for the cells, but any particles that have been created will be retained, suggesting one possible use for the OFFSET parameter.

The set of part cards terminates with the final card having NR = 0 and the rest of the card unused. Therefore, at least two part cards must appear in a KACHINA input deck.

This completes the discussion of the input data cards. We see that an input deck must consist of at least 11 cards, but the maximum number is unlimited. The final card normally placed at the end of the input deck is in reality the first card for the next problem. The first quantity on Card No. 1 is IBAR, and it determines the action to be taken by KACHINA. If IBAR > 0, it is valid for use as  $\bar{I}$ , and the setup is called. The value IBAR = 0 indicates a tape restart, and IBAR < 0 indicates that the end of data has been reached. Thus, a negative IBAR card is the appropriate way to terminate a deck, and hence, the job.

#### G. Output - Plots, Prints, and Motion Pictures

The KACHINA output is in the usual two forms, visual information on 35-mm microfilm or 16-mm

motion-picture film and printed information on microfilm or fanfold paper. Both forms are provided automatically in cycles 0 and 1, and thereafter at intervals specified by DT0 and DT0C in the input data. The microfilm plots are generally the most immediately useful output, and they are made on the III FR-80 or the S-C 4020 computer output microfilm devices. As many as 16 plots are provided in the basic package, four particle plots, velocity vector plots of both fields, and contour plots of  $\phi$ ,  $\rho'_{v1}$ ,  $\rho'_{d1}$ ,  $\rho'_{v2}$ ,  $\rho'_{d2}$ ,  $I_v$ ,  $I_d$ ,  $p$ ,  $K$ , and  $E$ .

The particle plots are made by plotting the x and y coordinates of all particles, and they are provided automatically when particles are used. Of the four different particle plots, the first is a composite plot of all particles in which a different plotting symbol or color is used for each type of particle. This is followed by a set of three individual particle plots, for each of which KACHINA sorts through the particles and plots only those tagged to correspond to the currently specified type.

Whereas particle plots are useful in following the motions of the components of each field, they cannot convey complete information on the flow details. Velocity vector plots are useful because they show at a glance both the direction of flow and the relative magnitude of the velocities. They are provided separately for both the vapor and droplet fields. Vectors are plotted as if originating at each cell center, denoted by a "+," and their length and direction are proportional to the velocity components. If  $(x_1, y_1)$  are the coordinates of the center of cell  $(i, j)$ , the coordinates of the vector end points  $(x_2, y_2)$  are given by

$$x_2 = x_1 + \left( \frac{u_{i+\frac{1}{2}}^j + u_{i-\frac{1}{2}}^j}{2} \right) DR\bar{O}U,$$

and

$$y_2 = y_1 + \left( \frac{v_{i+\frac{1}{2}}^j + v_{i-\frac{1}{2}}^j}{2} \right) DR\bar{O}U,$$

where u and v refer either to  $(u_v$  and  $v_v)$  or  $(u_d$  and  $v_d)$ , and DR0U is a scaling coefficient defined as

$$DR\theta U = 0.9 \delta r (VEL_{max})^2 .$$

This coefficient is recalculated for each individual velocity-vector plot, and it scales the length of a vector drawn for the largest  $|u|$  or  $|v|$  velocity in the system at that instant,  $VEL_{max}$ , to be 9/10ths of the radial cell dimension  $\delta r$ . This method ensures that the vectors are always of reasonable length, regardless of velocity magnitudes. The plot is omitted if there are no significant velocities ( $VEL_{max} < 10^{-10}$ ) in a particular field.

Contour plots are drawn for any cell-centered quantity stored in CQ, and they are composed of connected vector segments joining points of equal value, just as the lines on a contour map join points of equal elevation. At present, the plots are all linear in contour increment.

In addition to the various plots described above, three different types of numerical listed data are provided.

The "long print" is a complete numerical listing of the principal field variables over the entire mesh. Two lines containing the  $i$  and  $j$  and 16 field quantities are given for each cell. They appear as follows. On the first line:

$$i, j, \theta_i^j, (u_v)_{i+\frac{1}{2}}^j, (v_v)_{i+\frac{1}{2}}^j, (I_v)_i^j, (\rho'_{v1})_i^j, (\rho'_v)_i^j, D_i^j, \rho_i^j. \text{ On the second line: } E_i^j, (u_d)_{i+\frac{1}{2}}^j, (v_d)_{i+\frac{1}{2}}^j, (I_d)_i^j, (\rho'_{d1})_i^j, (\rho'_d)_i^j, A_i^j, K_i^j.$$

The "short print" is a four-line listing of sums over the mesh of mass (M), momentum (MOM) in the  $r$  and  $z$  directions, internal energy (IE), kinetic energy (KE), and total energy (E). In addition to first specifying the current problem time and cycle number, the 4 lines provide 20 summations in the following order.

$$\begin{array}{lllll} \Sigma \theta & \Sigma (MOM_r)_{v+d} & \Sigma (MOM_z)_v & \Sigma (MOM_z)_d & \Sigma (MOM_z)_{v+d} \\ \Sigma (M_v)_1 & \Sigma (M_d)_1 & \Sigma IE_v & \Sigma IE_d & \Sigma IE_{v+d} \\ \Sigma (M_v)_2 & \Sigma (M_d)_2 & \Sigma KE_v & \Sigma KE_d & \Sigma KE_{v+d} \\ \Sigma (M_v)_{1+2} & \Sigma (M_d)_{1+2} & \Sigma E_v & \Sigma E_d & \Sigma E_{v+d} \end{array}$$

This short print is provided every cycle if the input variable ISPR=2, or only on those cycles that have a long print if ISPR=1. LPR, another variable

in the input data, has primary control of the destination of both the long and short prints, where:

- LPR=1 gives prints on microfilm only,
- LPR=2 gives prints on microfilm and fanfold paper,
- LPR=3 gives prints on fanfold paper only.

If LPR=0, both long and short prints are omitted, and no alphanumeric writing of any kind appears on microfilm. LPR=0 is intended for motion picture use, and the only microfilm output is the first (complete) particle plot. For movies, KACHINA bypasses the automatic  $\delta t$  that normally would begin after cycle 10, and the user must be sure to choose an input  $\delta t$  that is at least as small as the minimum  $\delta t$  required at any time during the course of the problem, usually determined by a preceding run with normal output, and also to set  $DT\theta = \delta t$  and  $DT\theta C \geq TWFIN$ . For color processing, the chosen colors are specified by C\thetaLOUR(N),  $N=1, 3$  in the input data, as described in Sec. II.F. The code is easily altered to provide some plot other than this particle plot for the movie or to have a frame shared by several different types of plots.

Finally, a one-line print is provided on fanfold paper every cycle, regardless of the LPR setting, and also on microfilm if LPR=1 or 2. This line contains the following nine quantities.

- T is the current problem time.
- CYC is the current cycle number.
- DT is the current  $\delta t$ .
- CP is the current central processor (CP) clock time.
- GRINDS =  $\delta CP / (\bar{I} * \bar{J})$ , the elapsed CP time for the cycle just completed, divided by the total number of cells. The CP time per cell per cycle is a useful indicator of the code's computing efficiency.
- IIP is the number of iterations required for convergence in the preceding Phase-2 pressure iteration.
- CELLS is the number of cells that failed to converge in the pressure iteration, and is zero unless the iteration failed to converge and was cut off at ITERS=100.
- IITR\theta } The analogous information from the pre-  
CELLS } ceding Phase-2  $\tilde{\rho}'_{v1}$  iteration.

## H. Tape Dump and Restart

Tape dumps are staged out as Fileset 8 in the control region under influence of the quantities T20MD and/or TLIMD, as described in Sec. II.F. The variables dumped are the contents of the SCM common KSC and also the LCM block, if cell data have been transferred to LCM storage, as described in Secs. II.C and II.D and Appendix C.

A tape restart is performed by staging in the dump tape as Fileset 7. The input deck consists of an IBAR = 0 data card, where JBAR = the dump number on the tape and is used as a check.

### I. The Common Block KSC

The following list provides the names, descriptions, and sources of all quantities in the SCM COMMON/KSC/ in the (0,0) overlay. This common is of

fundamental importance in communication among the various overlays and their subroutines. By design, it contains all the SCM-based information that must be maintained from cycle to cycle, as it is the SCM portion of the tape-dump data.

The sources in the list are keyed to the following symbols.

I = Supplied as part of the standard input data.

The parenthetical symbol that follows I specifies where this quantity is read,

O = (0,0) Main Program,

L = (0,0) Subroutine L00P,

S = (1,0) Subroutine SETUP,

H = (2,0) Subroutine HYDRØ.

Multiple sources indicate that the quantity is recalculated.

NAME	DESCRIPTION	SOURCE
AA	Dummy word, always the first word in the COMMON.	---
AASC	Cell storage, appears in this COMMON for SCM version only.	---
AKINFI	$A_\infty, K_\infty$ for sudden incompressibility. See Sec. I.F.	S
AO	$\alpha_o$ , a constant in the convective fluxing. See Secs. I.C and I.D.	I(0)
BDTØDR	$\beta_o \delta t / \delta r$ .	S
BDTØDZ	$\beta_o \delta t / \delta z$ .	S
BD1	$b_{d1}$ } Specific heat constants for the droplet field.	I(S)
BD2		
BINF	= 1.0 if bottom boundary has specified inflow; = 0.0 otherwise.	S
BØUT	= 1.0 if bottom boundary has continuative outflow; = 0.0 otherwise.	S
BV1	$b_{v1}$ .	I(S)
BV1GM11	$(b_{v1})(Y_1 - 1)$ .	S
BV2	$b_{v2}$ .	I(S)
BV2GM12	$(b_{v2})(Y_2 - 1)$ .	S
BO	$\beta_o$ , a constant in the convective fluxing, used in conjunction with $\alpha_o$ .	I(0)
CDR	$C_{DR}$ , drag coefficient appearing in the K equation.	I(0)
CØLØUR	Colors for movie. See Secs. II.F and II.G.	I(S)
C1	The h/min/s on the wall clock when the job began. Printed with D1.	0
DR	$\delta r$ , the cell size in the radial direction.	I(0)
DRØ2	$\delta r / 2$ .	S
DRSQ	$\delta r^2$ .	S
DT	$\delta t$ , the time step, subject to automatic recalculation.	I(S), H
DTØ	Problem time interval between outputs (plots and prints).	I(S)
DTØC	Problem time at which to change to next DTØ in the set.	I(S)
DTØDR	$\delta t / \delta r$ .	S, H
DTØDZ	$\delta t / \delta z$ .	S, H
DTØ2	$\delta t / 2$ .	S, H
DTPØS	$\delta t$ possible for the cycle, but $\delta t$ used may be reduced to adjust to output time.	S, H
DZ	$\delta z$ , the cell size in the axial direction.	I(0)

<u>NAME</u>	<u>DESCRIPTION</u>	<u>SOURCE</u>
DZØ2	$\delta z/2$ .	S
DZSQ	$\delta z^2$ .	S
D1	The month/day/year when the job began. Printed with C1.	0
EM10	$10^{-10}$ .	S
EM3	$10^{-3}$ .	S
EM6	$10^{-6}$ .	S
EPS	$\epsilon_1$ , convergence criterion for both Phase-2 iterations.	I(S)
EPV	$\epsilon_v$ and $\epsilon_d$ , appearing in the F (nonisotropic force) terms.	I(S)
EP9	$10^9$ .	S
EP10	$10^{10}$ .	S
EP20	$10^{20}$ .	S
FIBAR	Floating-point equivalent of $\bar{I}$ .	S
FIXL	Floating-point frame coordinate for left edge of plots.	S
FIXR	Floating-point frame coordinate for right edge of plots.	S
FIYB	Floating-point frame coordinate for bottom edge of plots.	S
FIYT	Floating-point frame coordinate for top edge of plots.	S
FJBAR	Floating-point equivalent of $\bar{J}$ .	S
G	g, gravity felt by both vapor and droplets, $\pm$ .	I(S)
GAM1	$\gamma_1$ .	I(S)
GAM2	$\gamma_2$ .	I(S)
GDT	$g\delta t$ .	S
GGM11	$(\gamma_{v1})(\gamma_{v1}-1)$ .	S
GGM12	$(\gamma_{v2})(\gamma_{v2}-1)$ .	S
GM11	$(\gamma_{v1}-1)$ .	S
GM12	$(\gamma_{v2}-1)$ .	S
I	Index i. In COMMON because of ENTRY SETIJ in LOOP.	---
IABRT	Abort indicator, set to 1 if the setup encounters a $\theta < 0$ .	0,S
IALL	JP2*NQI, the total amount of cell storage required.	S
IBAR	$\bar{I}$ , the number of interior cells in the r direction.	I(0)
IDTØ	Index for DTØ and DTØC tables.	S
IJ	Index for cell (i,j), initialized by LOOP.	L
IJM	Index for cell (i,j-1), initialized by LOOP.	L
IJP	Index for cell (i,j+1), initialized by LOOP.	L
IP1	$\bar{I}+1$ , index of rightmost column of interior cells.	S
IP2	$\bar{I}+2$ , index of column of exterior cells on the right.	S
ISPR	Short print control, described in Sec. II.G.	I(S)
IXL	Integer frame coordinate for left edge of plots.	S
IXR	Integer frame coordinate for right edge of plots.	S
IYB	Integer frame coordinate for bottom edge of plots.	S
IYT	Integer frame coordinate for top edge of plots.	S
J	Index j, in COMMON because of ENTRY RIRØW in LOOP.	---
JBAR	$\bar{J}$ , the number of interior cells in the z direction.	I(0)
JNM	Job name identification assigned by the operating system.	0
JP1	$\bar{J}+1$ , index of the topmost row of interior cells.	S
JP2	$\bar{J}+2$ , index of row of exterior cells along the top.	S
JRIGID	Number of rigid cells up the right boundary; continuative above this point.	I(S)

<u>NAME</u>	<u>DESCRIPTION</u>	<u>SOURCE</u>
JTØP	= JP1 if top is rigid, = JP2 if top is outflow; controls $\tilde{v}$ initialization in Phase 2.	S
JX1	1+NQ, first word address (fwa) of col. 2, row j=1 (or 1/3 if LCM), set by LØØP as an index.	S
JX2	J2+NQ, fwa of col. 2, row j=2 (or 2/3 if LCM), set by LØØP as an index.	S
JX3	J3+NQ, fwa of col. 2, row j=3 (or 3/3 if LCM), set by LØØP as an index.	S
J2	1+NQI, fwa of col. 1 of row j=2/3, used by LØØP, LCM version only.	S
J3	J2+NQI, fwa of col. 1 of row j=3/3, used by LØØP, LCM version only.	S
KD	$k_d$ , heat conduction coefficient for the droplet field.	I(S)
KDØDRSQ	$k_d/\delta r^2$ .	S
KDØDZSQ	$k_d/\delta z^2$ .	S
KV	$k_v$ , heat conduction coefficient for the vapor field.	I(S)
KVØDRSQ	$k_v/\delta r^2$ .	S
KVØDZSQ	$k_v/\delta z^2$ .	S
LCM	= 1 if LCM is used for cell storage, = 0 if SCM is used for cell storage.	L
LPR	Determines output options on film and printer.	I(S)
MUSTPR	Number of cells failing to converge in pressure iteration.	H
MUSTRØ	Number of cells failing to converge in $\tilde{\rho}'_{v1}$ iteration.	H
NAME	Problem identification from columns 2-80 of input card No. 2.	I(S)
NCYC	Number of calculation cycles completed.	S,H
NLC	Number of words to tape dump from LCM cell storage, if used.	S
NPTØT	Total number of particles in the system at a given instant.	S,H
NQ	Number of quantities, or storage words, per cell.	Ø
NQI	NQ*IP2, the number of words for one full row of cells.	S
NQI2	NQI+NQI, the number of words for two full rows of cells.	S
NQL	NQ*(1-LCM), used as index adjustment if SCM version.	S
NQ2	NQ+NQ, the number of words in two cells, used by LØØP, SCM version.	S
NQ2L	NQL+NQL, used as index adjustment if SCM version.	S
NSC	Number of words in this SCM common, for tape dump.	S,H
NUMIT	Number of iterations required for Phase-2 pressure convergence.	H
NUMRØ	Number of iterations required for Phase-2 ( $\tilde{\rho}'_{v1}$ ) convergence.	H
NUMTD	Number of the next tape dump.	S,H
NUV	$\nu_v$ , kinematic viscosity coefficient for the vapor field	I(O)
NUV3	$3*\nu_v$ , appears in K equation in Phase 1.	S
NVAP	= 1 if $\rho_{v1} = 0$ and $\rho_{v2} > 0$ , = 2 if $\rho_{v1} > 0$ and $\rho_{v2} = 0$ , = 3 if $\rho_{v1}$ and $\rho_{v2} > 0$ .	S
ØMBAS	$-\omega_p \delta r^2 \delta z^2 / 2(\delta r^2 + \delta z^2)$ , base of complete ØMBSPL.	S
ØMBSPL	ØMBAS/ $\delta t$ , stored for $(-\omega_p \beta_p)_i^j$ when $\theta_i^j < \theta_o$ .	S,H
ØMP	$\omega_p$ , the Phase-2 pressure iteration relaxation coefficient.	I(S)
ØMRØ	$\omega_p$ , the Phase-2 ( $\tilde{\rho}'_{v1}$ ) iteration relaxation coefficient.	I(S)
R	Exchange function for heat transfer between the two fields.	I(S)
RCØNT	Right boundary table, on index J; = 0.0 where rigid, = 1.0 where outflow.	S
RDR	$1/\delta r$ .	S
RDRSQ	$1/\delta r^2$ .	S
RDT	$1/\delta t$ .	S
RDZ	$1/\delta z$ .	S

<u>NAME</u>	<u>DESCRIPTION</u>	<u>SOURCE</u>
RDZSQ	$1/\delta z^2$ .	S
RI	Table of $r_i$ 's, of length IP2.	S
RIBAR	Reciprocal of $\bar{I}$ .	S
RIBJB	Reciprocal of $(\bar{I}*\bar{J})$ , used in control region grid calculation.	S
RIP	Table of $r_{i+\frac{1}{2}}$ 's, of length IP2.	S
RJBAR	Reciprocal of $\bar{J}$ .	S
RØ1	$\rho_1$ , microscopic material density of droplet component 1.	I(S)
RØ2	$\rho_2$ , microscopic material density of droplet component 2.	I(S)
RØVPIN	$(\rho'_v)_{j=1}$ , for specified inflow bottom boundary, = THIN*(RØVIN1 + RØVIN2).	S
RØVPIN1	$(\rho'_{v1})_{j=1}$ , for specified inflow bottom boundary, = THIN*RØVIN1.	S
RØVO	$\rho_{vo}$ , specified vapor density for incompressible flow.	I(O)
RPAR	$r_p$ , the mean linear dimension of a droplet.	I(O)
RPCDR	$r_p C_{DR}$ , = RPAR*CDR, appears in K equation.	S
RPCØF	$3/2r_p^2 = 1.5/RPAR**2$ , appears in K equation.	S
RR1	Table of $1/r_i$ 's, of length IP2.	S
RRIP	Table of $1/r_{i+\frac{1}{2}}$ 's, of length IP2.	S
RRIDR	Table of $1/(r_i \delta r)$ 's, of length IP2.	S
RRØ1	$1/r_1$ .	S
RRØ2	$1/r_2$ .	S
R2DR	$1/(2\delta r)$ .	S
R2DZ	$1/(2\delta z)$ .	S
SIEVIN	$(I_v)_{j=1}$ , for specified inflow on bottom boundary.	I(S)
SQMO	$M_o^2$ in Mach No. ratio in Phase-1 $\tilde{p}$ initialization, usually = $(0.5)^2$ .	S
T	t, the problem time.	I(S),H
THIN	$\tau_{j=1}$ , for specified inflow on bottom boundary.	I(S)
THO	$\theta_o$ , the critical value for sudden incompressibility, usually = 0.02.	S
TLIND	= 1.0 to force a tape dump and RETURN before time limit.	I(S)
TØP	= 0.0 if top boundary is rigid, or = 1.0 if top is outflow.	S
TØUT	The next problem output time for plots/prints.	S,H
TWFIN	Time-When-To-Finish: calculation completed when $t \geq TWFIN$ .	I(S)
T20MC	= 1.0 to force tape dumps every 20 min of CP time.	I(S)
VØL	Table of $V_i$ 's, of length IP2, where $V_i = 2\pi r_i \delta r \delta z$ .	S
VØLR	Table of $V_{i+\frac{1}{2}}$ 's, of length IP2, where $V_{i+\frac{1}{2}} = 2\pi r_{i+\frac{1}{2}} \delta r \delta z$ .	S
VVIN	$(v_v)_{j=1}$ , the specified velocity at inflow bottom boundary.	I(S)
XCOØNV	Plotting factor, converts x's from problem units to 4020 units.	S
XL	= 0.0, the left edge of the mesh, for plots.	S
XP	Storage block for x coordinates of marker particles.	S,H
XR	= $\bar{I}*\delta r$ , the right edge of the mesh, for plots.	S
YB	= 0.0, the bottom edge of the mesh, for plots.	S
YCOØNV	Plotting factor, converts y's from problem units to 4020 units.	S
YP	Storage block for y coordinates of marker particles.	S,H
YT	= $\bar{J}*\delta z$ , the top edge of the mesh, for plots.	S
ZZ	Dummy word, always the final word in the COMMON.	---

J. Microfilm Plots — Scaling and Subroutine CALLs

The microfilm plots discussed in Sec. II.G are generally the most useful form of output from our fluid dynamics codes, as they often can quickly convey information about a flow process that would be less readily grasped by examining numerical listings alone.

Our original Computer Output Microfilm (COM) device is the S-C 4020, which has a matrix of 1024 by 1024 raster points on the CRT face, as is shown in Fig. 13. Usefulness of the 4020 has been increased by addition of a set of three color filters between the tube face and the camera, individually movable under control commands. The III FR-80 COM device has a resolvable matrix of 10K by 10K points which allows more accurate plotting, and it is also a programmable computer in its own right. For our relatively simple plots, whatever COM is assigned to our offline film output is treated as a 4020, the FR-80 becoming a 4020 simulator when used in this manner. Therefore, the following description of our plot scaling is based on the 4020 film frame of Fig. 13.

Note from Fig. 13 that the origin of the x-y coordinate system lies at the upper left corner of the frame and the values of the two integer indices increase to the right and down. This coordinate system obviously does not match that of the fluid

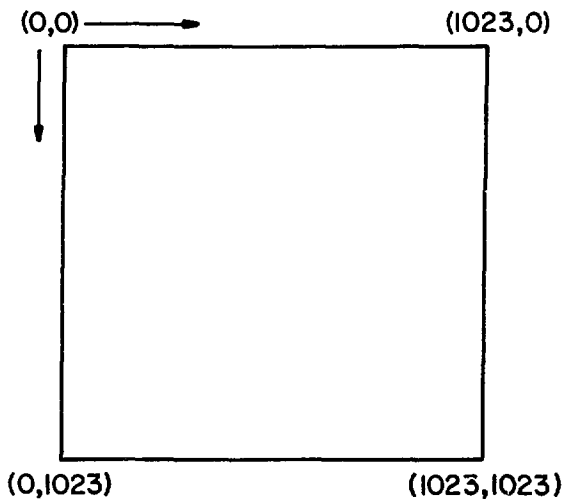


Fig. 13. The 4020 grid is a reflection of the first quadrant, and contains a matrix of 1024 by 1024 raster points, with the origin located at the upper left corner. x increases to the right, and y increases downward.

dynamics computing mesh shown in Figs. 1 and 8, where the origin is at the lower left corner. A conversion from physical mesh position to a corresponding 4020 frame position is required for all plotting. In KACHINA, the left, bottom, right, and top edges of the physical mesh are specified by:

$$XL = YB = 0.0 ,$$

$$XR = \bar{I}\delta r ,$$

$$YT = \bar{J}\delta z ,$$

and their counterparts in 4020 coordinates are given by the integers IXL, IYB, IXR, and IYT, calculated in accordance with the following considerations. First, we reserve areas across the top and bottom of the frame for plot identification, problem time, cycle number, and so forth. These are indicated by the shaded areas in Fig. 14. (The technique for generating alphanumeric information in these regions is discussed below.) The unshaded area that remains is 1024 points wide by 900 points high, although we consider the available width to the 1022 points, to ensure frame separation. Second, within this rectangular region, we maximize the size of the plot that is drawn, while maintaining its true physical proportion of height to width. Thus, if the physical area encompassed by the computing mesh is higher than it is wide,  $XR < YT$ , the resulting plot occupies the region exemplified by the fine shading in Fig. 15. The coordinates in this case are given by:

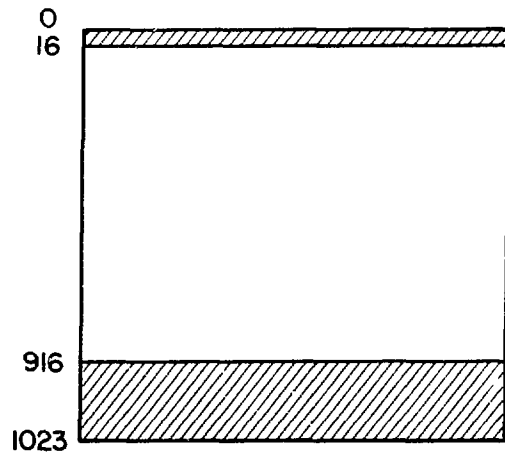


Fig. 14. The area in the center, available for plotting, encompasses 1024 by 900 raster points. The shaded areas are reserved for labeling, allowing two lines at the top and six at the bottom.



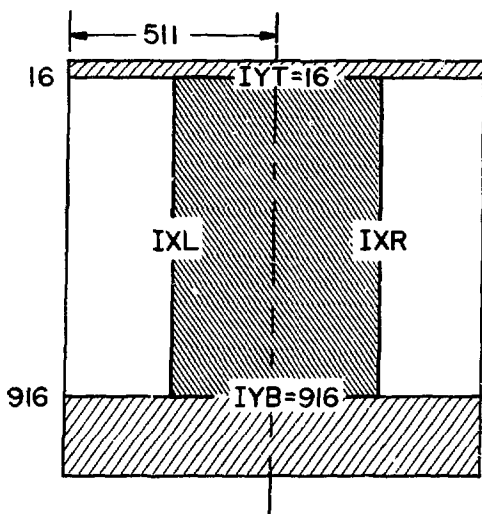


Fig. 15. The plotting area when the computing mesh is higher than it is wide,  $XR < YT$ .

$$FIXL = 511. - 450. \left( \frac{XR}{YT - YB} \right),$$

$$FIXR = 511. + 450. \left( \frac{XR}{YT - YB} \right),$$

$$FIYB = 916. ,$$

$$FIYT = 16.$$

Conversely, if the computing area is wider than it is high,  $XR > YT$ , the plot occupies the region exemplified by the fine shading in Fig. 16. Here the coordinates are given by:

$$FIXL = 0. ,$$

$$FIXR = 1022. ,$$

$$FIYB = 916. ,$$

$$FIYT = 916. - 1022. \left( \frac{YT - YB}{XR} \right).$$

In either case, the equivalent integers  $IXL$ ,  $IXR$ ,  $IYB$ , and  $IYT$  are then simply set directly from  $FIXL$ ,  $FIXR$ ,  $FIYB$ , and  $FIYT$ . The "4020 Setup" in SETUP calculates these eight quantities, and then calculates the two conversion factors that will be required for translating physical mesh coordinates to 4020 frame coordinates. These are given by the ratios

$$XC\phi NV = (FIXR - FIXL)/(XR - XL) ,$$

and

$$YC\phi NV = (FIYT - FIYB)/(YT - YB) .$$

A physical mesh coordinate is multiplied by the appropriate factor to convert it, and this product is then added to  $FIXL$  or  $FIYB$  and the sum is converted to an integer to locate the position on the 4020 frame of Fig. 13. A conversion subroutine is available that would handle this task for us, but it is more efficient for KACHINA to do it, thus avoiding recalculation of these two ratios whenever a point is plotted or a vector segment is drawn.

A set of local software subroutines provided by the Computer Sciences and Services Division of the Los Alamos Scientific Laboratory handles the communication between the problem program and the COM devices by producing 4020-format commands. KACHINA uses a number of these subroutines, which are accessed by the following FORTRAN calling sequences.

CALL ADV (nf) advances the film by nf frames.

CALL FRAME (IXL, IXR, IYB, IYT) draws a rectangular outline of the computing mesh. Two horizontal axes are drawn through  $IYT$  and  $IYB$  from  $IXL$  to  $IXR$ , and two vertical axes are drawn through  $IXL$  and  $IXR$  from  $IYT$  to  $IYB$ .

CALL PLT (IX, IY, ch) plots the 4020 character identified by ch at 4020 frame coordinates (IX, IY).

CALL DRV (IX1, IY1, IX2, IY2) draws a straight line vector segment connecting the 4020 point (IX1, IY1) with the 4020 point (IX2, IY2).

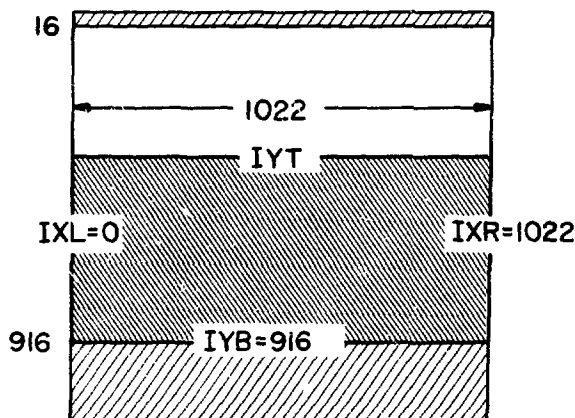


Fig. 16. The plotting area when the computing mesh is wider than it is high,  $XR > YT$ .

CALL  $COLOR$  ( $c$ ) controls the filter selection for color processing;  $c$  is a floating-point variable with a value in the range 0.0 to 4.0. Single-filter selections are determined as follows:

- $c = 0.0$  No filter (white),
- $c = 1.6$  Yellow filter,
- $c = 2.6$  Cyan filter,
- $c = 3.6$  Magenta filter.

The primary colors are obtained by appropriate filter combinations:

- $c = 1.0$  Red (= yellow + magenta),
- $c = 2.0$  Green (= yellow + cyan),
- $c = 3.0$  Blue (= cyan + magenta).

Several additional subroutines are available for writing alphanumeric information on the frame. Whereas some of these write large characters composed of dot patterns, the basic CRT tube has a set of small alphanumeric characters that can be generated in the "typewriter" command mode, and it is this latter form that is used in KACHINA. In typewriter mode, the 4020 frame of Fig. 13 is composed of 64 lines of 128 characters each. Each character occupies a rectangular region 8 raster points wide by 16 high. The first character of a line is treated as a carriage control, completely analogous to line printer use.

CALL  $LINCNT$  ( $\ell$ ) locates the first column of line  $\ell$ , where  $\ell$  ranges from 0 (top line of the frame) through  $\ell = 63$  (bottom line of frame), and  $t = 64$  advances the film to the top of the next frame. After  $LINCNT$  locates the desired starting line position, ordinary formatted  $WRITE$  statements generate the actual alphanumeric information. The  $FORMAT$  statements are identical to those appropriate for a line printer, provided the 128 character per line restriction is observed. Line advancement is automatic, as on a line printer, until either line 63 has been written on, after which the film is automatically advanced to the top of the next frame, or another  $CALL LINCNT$  is issued to specify any desired line (0-63) of the current frame.

$CALL EMPTY$  ensures that if the film buffer contains any words, they are written on the 4020 tape.  $EMPTY$  generally appears as the final command to a sequence of 4020 instructions. Thus no residual commands are left in the film buffer, where they would be susceptible to possible loss in the event of a hardware or system failure.

#### K. Miscellaneous System Subroutine CALLs

KACHINA uses a number of other  $CALL$ s to access various local operating system subroutines not directly related to microfilm usage. These are, briefly, as follows.

$CALL GETQ$  ( $key, q$ ) (Get Quantity) is available for retrieving a variety of job task parameters from the operating system. Here,  $key$  is the task parameter identifier, in left-justified display code, and  $q$  is the name of the problem program location to which the value of the quantity is returned. In KACHINA, we use two task parameters:  $KJBN$  is the job name, composed of 10 symbols, the first 7 symbols from the job card name field, followed by a one-digit input station ID and a two-character job sequence number.  $KTLM$  is the time limit specified on the job card, converted to CDC 7600 clock cycles, where one clock cycle =  $27.5 \cdot 10^{-9}$  seconds.

$CALL DATE1$  ( $D1$ ) stores the current date in display code in the location specified by  $D1$ . The form is eight characters,  $MM/DD/YY$ , where  $MM$  is the month,  $DD$  is the day, and  $YY$  is the year.

$CALL CLØCK1$  ( $C1$ ) stores the current time of day in display code in the location specified by  $C1$ . The form is eight characters,  $HH \cdot MM \cdot SS$ , where  $HH$  is the hour (00 through 23),  $MM$  is the number of minutes, and  $SS$  is the number of seconds.

CALL SECØND (T1) stores the elapsed central processor time for the job in the location specified by T1. This time is expressed as a real number representing seconds, to the nearest thousandth of a second.

CALL AFSREL ( ), or Active Fileset Release, is used in two ways in KACHINA. First, upon a tape restart, it is called to release LCM space the the operating system has devoted to Fileset 7, as soon as that fileset becomes inactive. Second, it is also called to initiate output processing of active filesets ØUT and FILM at each tape dump, assuming that the dump is before job completion and is an intermediate one.

CALL DATAREL ( ), or Data Release, is used to stage a restart dump from the disk onto a physical tape. Otherwise, tape dumps would be accumulated on disk storage during job execution and not actually staged to tape until job completion, leaving them vulnerable to loss in event of hardware or system failure.

If the descriptions of system subroutines provided in Secs. II.J and II.K are inadequate, contact the Los Alamos Scientific Laboratory Computer Sciences and Services Division.

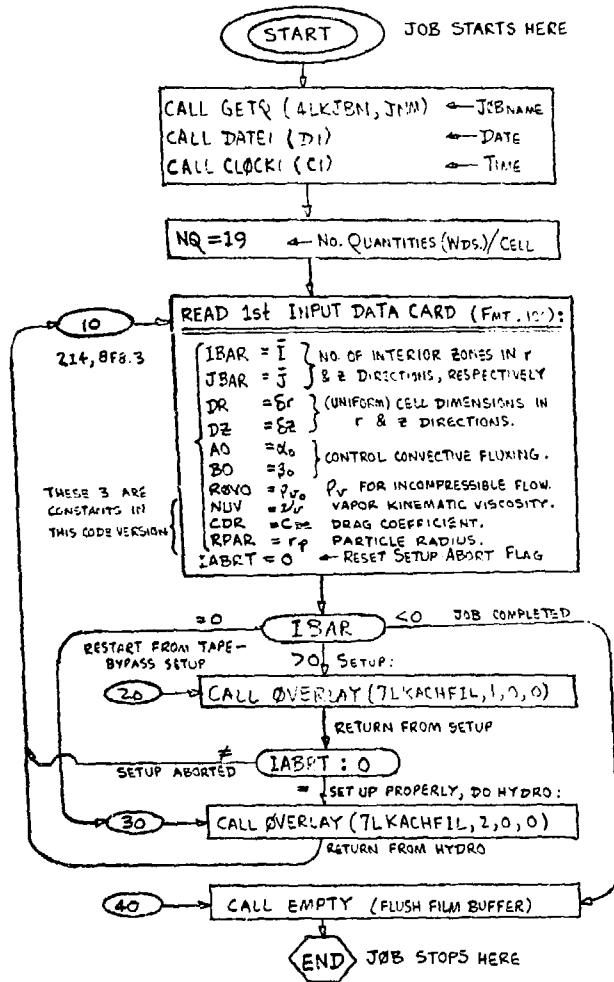
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APPENDIX A  
FLOW DIAGRAM FOR THE KACHINA PROGRAM  
(June 19, 1974 Status)

# KACHINA

PROGRAM KACHINA - 0,0 OVERLAY:



— A MULTI-FIELD HYDRO CODE

1

◀◀ 0,0 SUBROUTINE LOOP ▶▶

SETS INDICES ONLY IN THIS SCM VERSION:

```

IJP = IJP + NQ2 } BYPASS
IJ = IJ + NQ2 } COLUMNS
IJM = IJM + NQ2 } IP2 & 1
  
```

RETURN

◀◀ ENTRY START ▶▶

```

IJP = JX3 = F.W.A. ROW j=3
IJ = JX2 = F.W.A. ROW j=2
IJM = JX1 = F.W.A. ROW j=1
  
```

POINT TO COLUMN 2 IN ALL THREE ROWS

RETURN

◀◀ ENTRY DONE ▶▶

RETURN

◀◀ ENTRY RIR'W ▶▶

```
JJ = (J-1) * NQI + 1
```

RETURN

◀◀ ENTRY SETIJ ▶▶

```
IJ = JJ + (I-1) * NQ
```

RETURN

◀◀ ENTRY WIR'W ▶▶

RETURN

◀◀ ENTRY LCMFLG ▶▶

```
LCM = 0
```

RETURN

◀◀ ENTRY RIJP2 ▶▶

```
KK = (J+1) * NQI
DB 299 K=1, NQI
```

PLACES ROW j+2 IN SPECIAL STORAGE, TO BE COMPATIBLE W/ LCM VERSION

999

```
AAROW(K) = AASC(KK+K)
```

↑ DONE

RETURN

◀◀ ENTRY RPARU ▶▶

```
IJ = NQI * (J-1)
```

RETURN

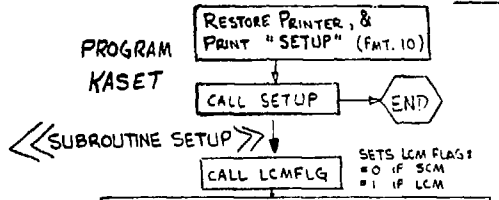
SET SINGLE-SUBSCRIPT INDEX (j PORTION), TO BE COMPATIBLE W/ LCM VERSION

◀◀ ENTRY RPARV ▶▶

```
IJ = NQI * (J-1)
```

RETURN

# 1.0 OVERLAY - THE PROBLEM SETUP:



**READ INPUT DATA CARDS # 2 THRU # 9:**

#2 = I.D. CARD → NAME = PROBLEM ID, FMT. 810, 810, 8A10

#3 = I.D. COMPONENTS → ICOMP (THIS IDENTIFIES MATERIALS ASSOCIATED WITH VAPOR 1, VAPOR 2, DROPLETS 1, & DROPLETS 2) (FMT. 820, 868, 3)

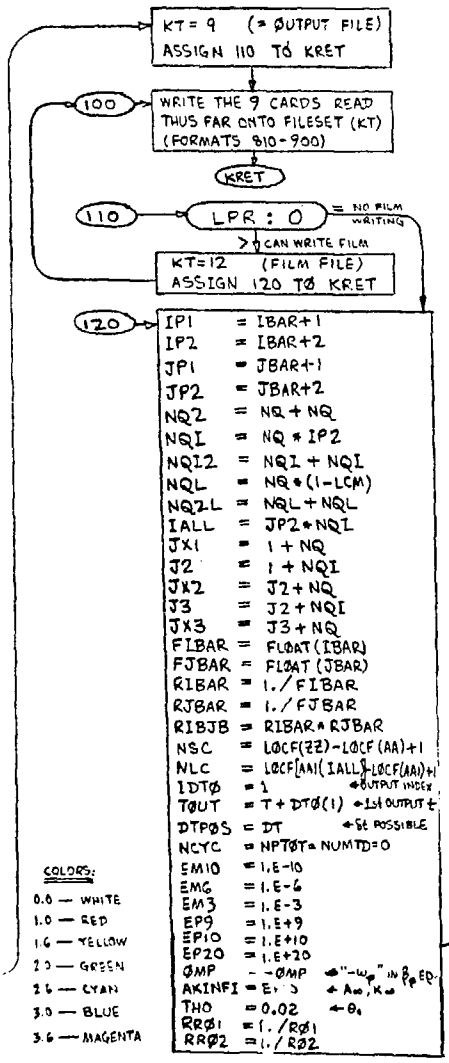
#4 = COMP =  $w_p$  RELAXATION COEFFICIENTS  
 DMR0 =  $w_p$  FOR PRESSURE & P. ITERATION  
 EPS =  $\epsilon$  ITERATION CONVERGENCE  
 G =  $g$  GRAVITY  
 KV, KD =  $k_v, k_d$  HEAT CONDUCTION COEFFS  
 EPV(1), EPD =  $e_v, e_d$  NON-ISOTROPIC COEFFS.  
 R =  $r$  FOR SIE EPSN.

#5 = MATERIAL CONSTANTS: (FMT. 870, 8FB.3)  
 RP1, RP2 =  $P_1, P_2$  (DROPLET MATS.)  
 GAM1, GAM2 =  $\gamma_1, \gamma_2$  (VAPOR MATS.)  
 BV1, BV2 =  $b_{v1}, b_{v2}$  SPECIFIC HEATS  
 BD1, BD2 =  $b_{d1}, b_{d2}$

#6 = BOUNDARY CONDITIONS: (FMT. 885, 814, 8FC.3, 1+)  
 JRGID = NO. RIGID CELLS ON RT. UP TO OUTFLOW  
 IBST BOTM: 0=RIGID, 1=OUTFLOW, 2=INFLOW  
 THIN  $\theta$  FOR INFLOW ALONG BOTTOM.  
 ROVIN1, 2  $\rho_{v1}, \rho_{v2}$  SET IBST=2.  
 SIEVIN  $\rho_v$  (IF IBST=0 OR 1, THESE  
 VVIN  $v_v$  SHOULD BE INPUT AS ZERO.  
 ITOP TOP: 0=RIGID, 1=OUTFLOW.

#7 = CONTROL: (FMT. 840, 8FB.3, 14, 3F4.1)  
 T =  $t_0$   
 DT =  $\Delta t$   
 T20MD 1=20'CP TAPE DUMP  
 TLMD 1=TIME-LIMIT TAPE DUMP  
 TWFIN TIME-WHEN-TO-FINISH  
 LPR MOVIE & PRINT/WRITE CONTROL  
 ISPR SMART PRINTS: 1=H/LP, 2=EACH CYCLE  
 COLOUR(1-3) IF COLOR MOVIES, THESE ARE  
 COLORS OF DROPLETS #1, DROPLETS  
 #2, AND VAPOR, RESP.

**OUTPUT TIME CONTROLS:**  
 #8 = DT0(1-10) (FMT. 845, 10FB.3)  
 #9 = DT0C(1-10)



- COLORS:**
- 0.0 - WHITE
  - 1.0 - RED
  - 1.6 - YELLOW
  - 2.0 - GREEN
  - 2.6 - CYAN
  - 3.0 - BLUE
  - 3.6 - MAGENTA

**REAL**

GM11 = GAM1 - 1.      =  $\gamma_1 - 1$   
 GG11 = GAM1 \* GM11      =  $\gamma_1(\gamma_1 - 1)$   
 BV1GM11 = BV1 \* GM11      =  $b_{v1}(\gamma_1 - 1)$   
 GM12 = GAM2 - 1.      =  $\gamma_2 - 1$   
 GG12 = GAM2 \* GM12      =  $\gamma_2(\gamma_2 - 1)$   
 BV2GM12 = BV2 \* GM12      =  $b_{v2}(\gamma_2 - 1)$   
 SQM0 = (.5)\*\*2      =  $M_0^2$   
 RPODF = 1.5/RPAR\*\*2      =  $3/2 * P^2$   
 NUV3 = 3.\*NUV      =  $3\nu$   
 RPCR = .25 \* RPAR \* RCDR      =  $\tau_p C_{pr} / 4$   
 RDR = 1./DR      =  $1/\delta r$   
 DR02 = .5 \* DR      =  $5r/2$   
 RDE = 1./DE      =  $1/\delta e$   
 DE02 = .5 \* DE      =  $5e/2$   
 RDRSQ = RDR \* RDR      =  $1/\delta r^2$   
 RDZSQ = RDE \* RDE      =  $1/\delta e^2$   
 DRSQ = DR \* DR      =  $\delta r^2$   
 DESQ = DE \* DE      =  $\delta e^2$   
 OMBAS = .5 \* (MP \* DRSQ + DRZSQ)      =  $k_c / 8 C_0$   
 RZDR = 1./DRSQ + DRZSQ      =  $1/(8 S_1)$   
 R2DR = .5 \* R02      =  $1/(2 S_2)$   
 KV0DRSQ = KV \* RDRSQ      =  $k_v / \delta r^2$   
 KD0DRSQ = KD \* RDRSQ      =  $k_d / \delta r^2$   
 KD0DESQ = KD \* RDESQ      =  $k_d / \delta e^2$   
 DT02 = 1.0 / DT      =  $1/\Delta t$   
 DT0DR = DT \* DR      =  $\Delta t / \delta r$   
 BD0DR = B0 \* DTADR      =  $8 S_1 / \nu$   
 DT0DE = DT \* DE      =  $\Delta t / \delta e$   
 BD0DE = B0 \* DT0DE      =  $8 S_1 / \nu$   
 GDT = G \* DT      =  $g \Delta t$   
 VCON = 2. \* P \* (JK + DE)      =  $2 P (JK + DE)$   
 RI(1) = 1. + S \* DR      =  $1 + S \delta r$   
 RR(1) = 1. + S \* DE      =  $1 + S \delta e$   
 RRDR(1) = RR(1) \* RDR      =  $(1 + S \delta r) / \delta r$   
 RIP(1) = RRIP(1) \* 0.

**Form**  
 "L"  
 "V"  
**Tables**

129  
 D0 I29 I=2, IP2  
 RI(I) = RI(I-1) + DR  
 RR(I) = 1. / RI(I)  
 RRDR(I) = RR(I) \* RDR  
 RIP(I) = RIP(I-1) + DR  
 VOL(I) = VCON \* RI(I)  
 VOLR(I) = VCON \* RIP(I)  
 RRIP(I) = 1. / RIP(I)

**FORA: RIGHT: BOUNDARY: 1-TABLE:**

```

    graph TD
      J2[DS 139 J=2, JP2] --> RECONT[RECONT(J)=0. (RIGID)]
      RECONT --> JRGID{J: JRGID+2}
      JRGID --> RECONT
      JRGID --> CONTINUE[CONTINUE]
      CONTINUE --> BOUT{BOUT = BINF = 0.}
      BOUT --> IBST{IBST}
      IBST --> ROVIN[ROVIN = THIN * ROVIN1]
      ROVIN --> TWFIN[TWFIN = THIN * (ROVIN1 + ROVIN2)]
      TWFIN --> ITAP[ITAP = JPI + ITAP]
      ITAP --> TO_NEXT[TO NEXT PAGE]
  
```

# 1,0 OVERLAY - THE PROBLEM SETUP - CONTINUED:

## 4020 SETUP:

→ FROM PREVIOUS PAGE...

```

XR = FIBAR * DR
YT = FJBAR * DR
XL = YB = 0.0
FIYB = 916.0
XD = XR / (YT - YB)
YY = 0.0
    
```

MAXIMIZE  
PLOT SIZE  
ON FRAME

```

XD = 1.13556
YY = 1.0
    
```

```

FIXL = A MAXI [0., (511. - 450. * XD) * YY] - 1022.
FIXR = (511. + 450. * XD) * YY + 1022. * (1. - YY)
FIYT = 16. * YY + (916. - 1022. / XD) * (1. - YY)
XC0NV = (FIXR - FIXL) / (XR - XL) } CONVERSION
YC0NV = (FIYT - FIYB) / (YT - YB) } FACTORS
IXL = FIXL
IXR = FIXR
IYB = FIYB
IYT = FIYT
    
```

INTEGER EQUIVALENTS

CLEAR  
CELL  
STORAGE,  
SCM OR LCM:

```

NQM1 = NQ - 1
CALL START
DO 199 J=1, JP2
KF = IJM - NQ
KL = KF + NQM1
DO 179 K=KF, KL
    
```

```
179 AAJC(K) = 0.
```

```
189 IJM = IJM + NQ
CALL LOOP
```

```
199 IJM = IJM - NQ2L
CALL DONE
```

BACK UP INDEX, IF  
SCM VERSION,  
BY 2 CELLS

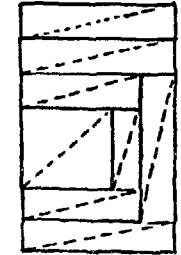
```
SR0V1 = SR0V2 = 0.
```

(SUM OF FLUID-REGION  $P_v$ 'S INDICATES  
WHETHER VAPOR #1 &/OR VAPOR #2 APPEAR.  
THIS DETERMINES SUBSEQUENT  $P_v$ 'S TREATMENT.)

200 READ A FLUID-REGION CARD: (F=t. 916)

414,6F8.3,14

NB	INTEGER NOS. OF CELLS, DEFINING OPPOSITE DIAGONAL CORNERS	
NR		
NT		
NL		
R0DPRI1	INITIAL $P_{v1}, P_{v2}, P_{v3}$	
R0DPRI2	$P_{v2}, P_{v3}, I_1$ FOR ALL CELLS IN REGION.	
R0V1	(NO VELOCITIES IN SETUP - LEAVE ALL U'S & V'S INITIALIZED AT ZERO (01590 LOOP))	
R0V2		
SIEVI		
SIEDI		
NPLUA	NO PARTICLES PER UNIT AREA - REFER TO NEXT PAGE.	



EXAMPLE OF A TYPICAL SETUP - (6 FLUID REGIONS, BUT 8 FLUID-REGION CARDS REQUIRED.)

```
NR = 0
300 ALL FLUID REGIONS HAVE BEEN CREATED; SET EXTERIOR VALUES.
```

```
PRINT CONTENTS OF ABOVE CARD. FORMAT 920
```

```
LPR = 0
WRITE SAME INFO ON FILM.
```

ADD  $P_{v1}, P_{v2}$   
INTO RUNNING  
SUMS.

```
SR0V1 = SR0V1 + R0V1
SR0V2 = SR0V2 + R0V2
```

DON'T ALTER  
NB, NR, NT OR NL  
AS THEY ARE  
USED IN  
PARTICLE GENERATOR.

```

NB2 = NB + 2
NR1 = NR + 1
NT1 = NT + 1
NL2 = NL + 2
TH1 = 1. - R2DPRI1 * R0V1 - R0DPRI2 * R0V2
    
```

```
THJ = 0.0
400 INPUT BAD - ABORT W/ MESSAGE.
```

CALC.  $P_{v1}, P_{v2}$   
 $P_{v3}$

```

R0VPRI1 = TH1 * R0V1
R0VPRI = TH1 * (R0V1 + R0V2)
R0DPRI = R0DPRI1 + R0DPRI2
R0VPRI2 = R0VPRI - R0VPRI1
    
```

```

TH(IJ) = TH1
R0VPRI(IJ) = R0VPRI
R0VPR(IJ) = R0VPRI
R0DPRI(IJ) = R0DPRI
R0DPR(IJ) = R0DPRI
SIEV(IJ) = SIEVI
SIED(IJ) = SIEDI
P(IJ) = PNI
    
```

```

PNI = SIEVI * (R0VPRI1 * BV1GM1 + R0VPRI2 * BV2GM2) /
[TH1 * (R0VPRI1 * BV1 + R0VPRI2 * BV2)] * R0VPRI
GET ROW J ->
DO 219 J = NB2, NT1
CALL RIROW
DO 209 I = NL2, NR1
CALL SETI
    
```

```
209 IJ = IJ + NQ
CALL WIROW
```

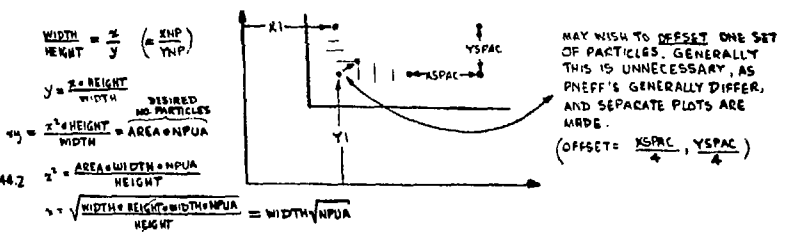
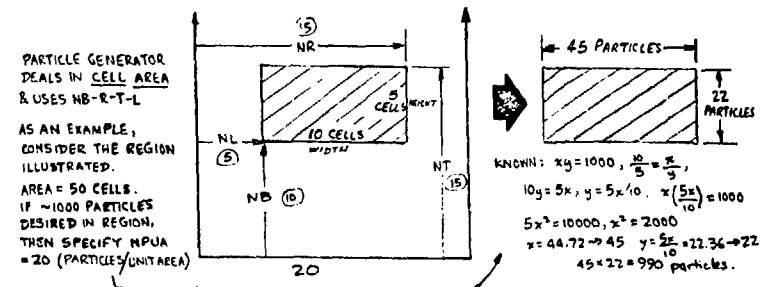
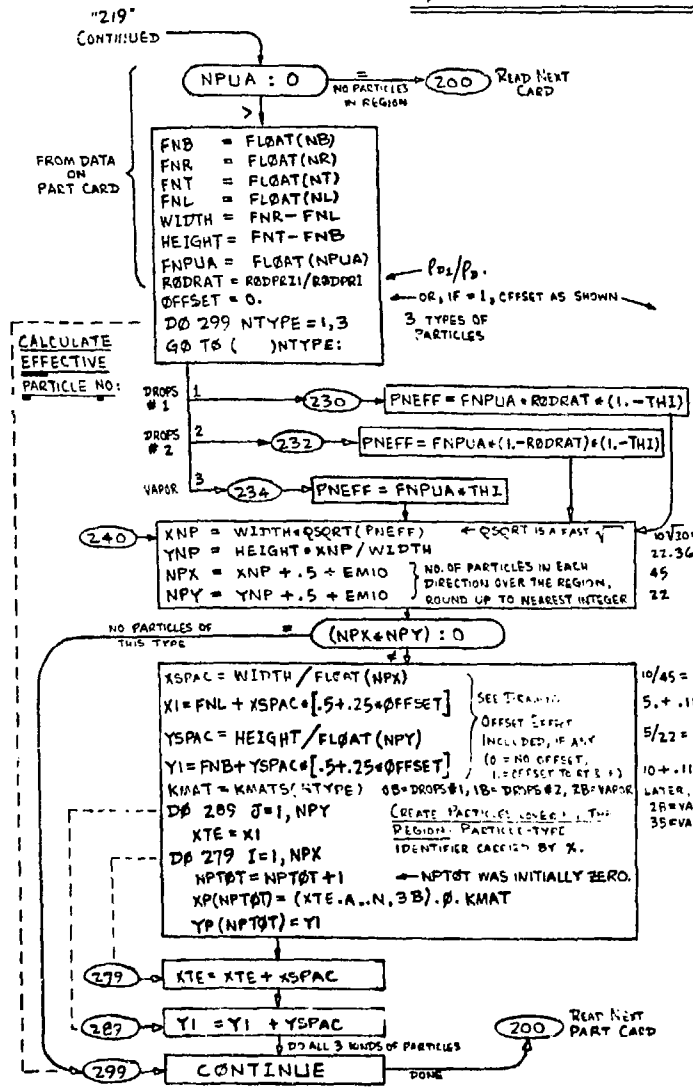
TO NEXT CELL IN ROW  
STORE ROW, IF LCM. (NO "CALL LOOP"  
REQ'D, AS RIROW WILL GET NEXT ROW UP.)

```
219 CONTINUE
```

NO "CALL DONE" IF SCM-ONLY  
VERSION

→

# 1,0 OVERLAY - MARKER PARTICLE GENERATION:



		REGION NO.					
TYPE OF PARTICLES:		1A	1B	2	3	4	
DROPS # 1:							
PNEFF = $\frac{P_{21}}{P_2} (1 - \theta) NPUA$		0	0	2.4	2.4	0.04	
NPX		0	0	6	5	1	
NPY		0	0	15	15	2	
DROPS # 2:							
PNEFF = $(1 - \frac{P_{21}}{P_2}) (1 - \theta) NPUA$		3.96	3.96	0	0	0	
NPX		20	6	0	0	0	
NPY		6	40	0	0	0	
VAPOR:							
PNEFF = $(\theta) NPUA$		0.04	0.04	1.6	1.6	3.96	
NPX		1	4	5	4	14	
NPY		1	4	13	13	20	
TOTAL NO. OF PARTICLES = 930							

(a) 167 DROPS #1 PARTICLES

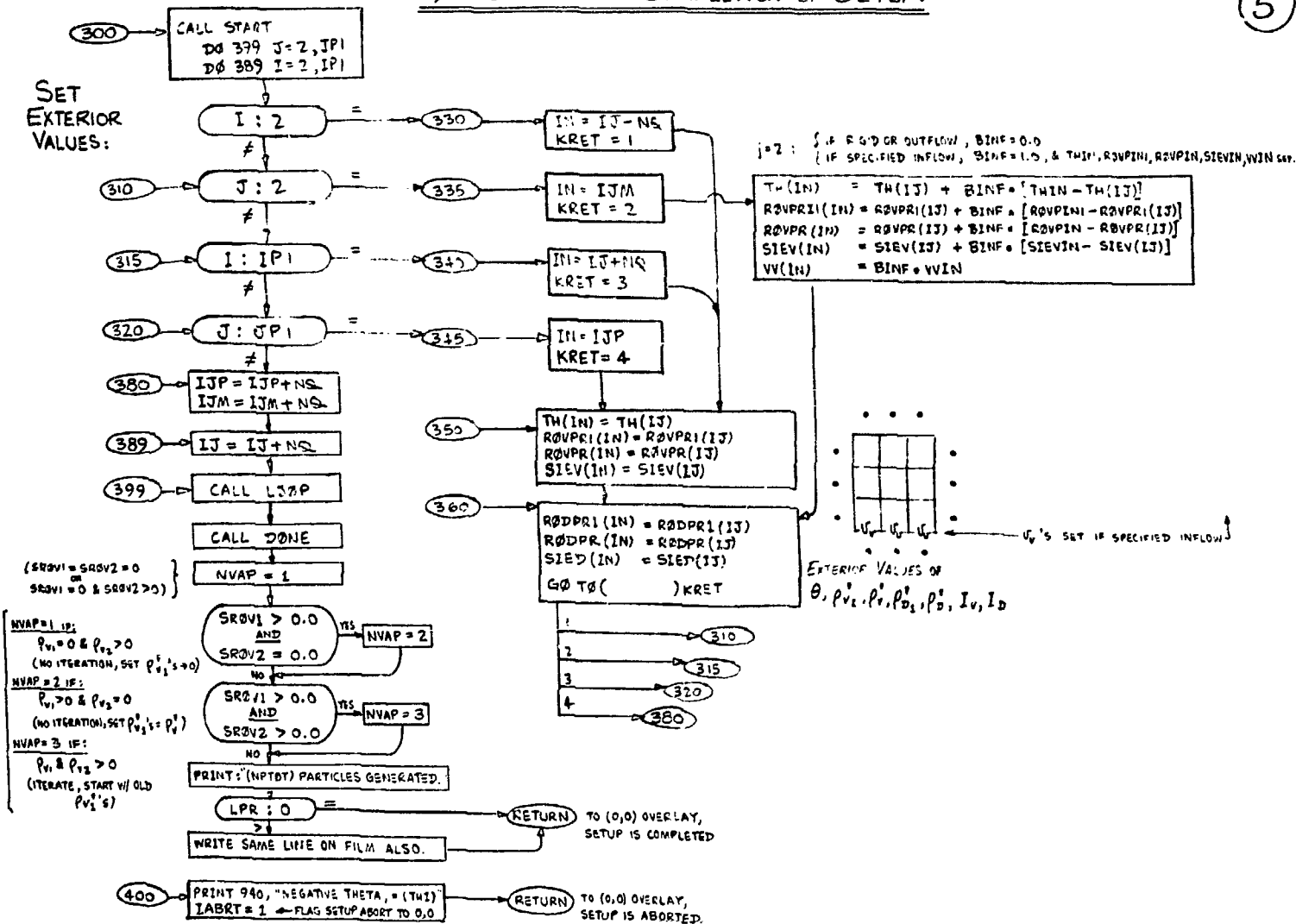
(b) 360 DROPS #2 PARTICLES

(c) 403 VAPOR PARTICLES



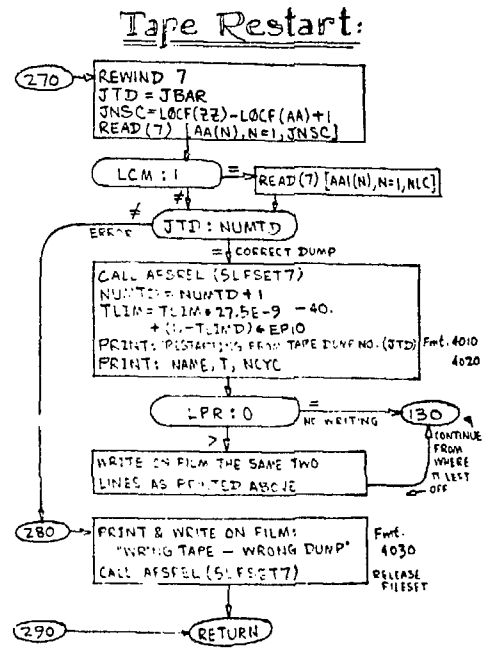
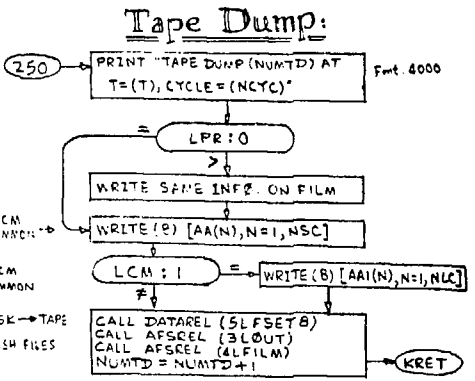
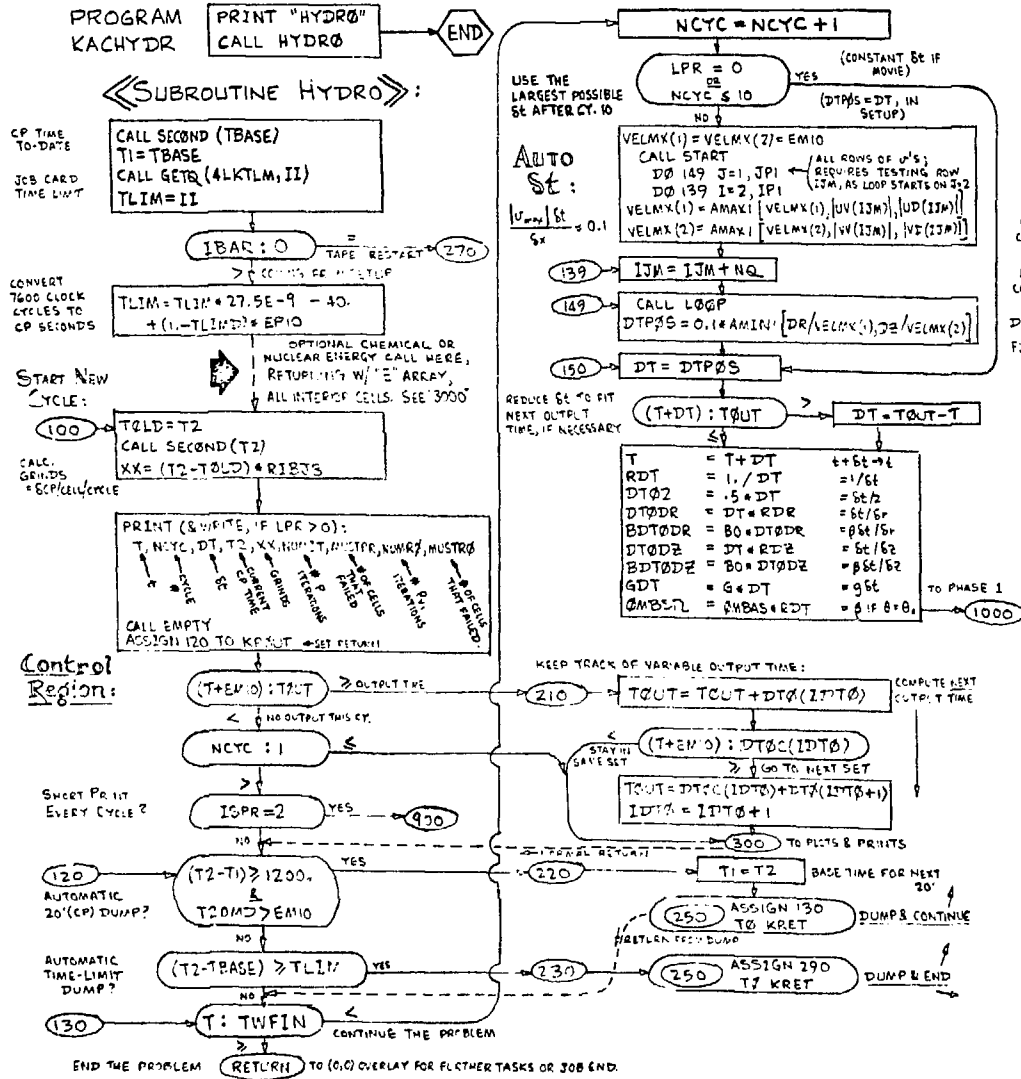
1,0 OVERLAY — COMPLETION OF SETUP:

5



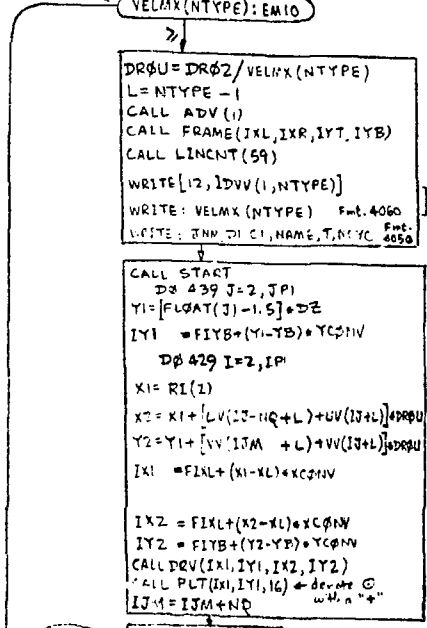
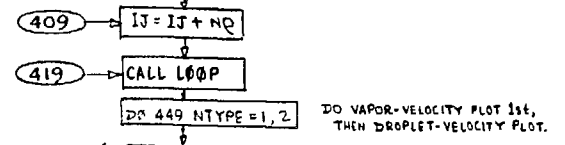
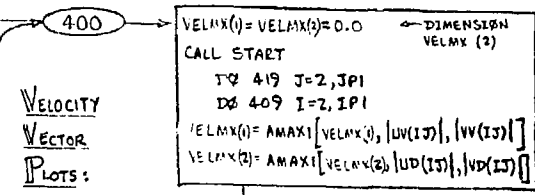
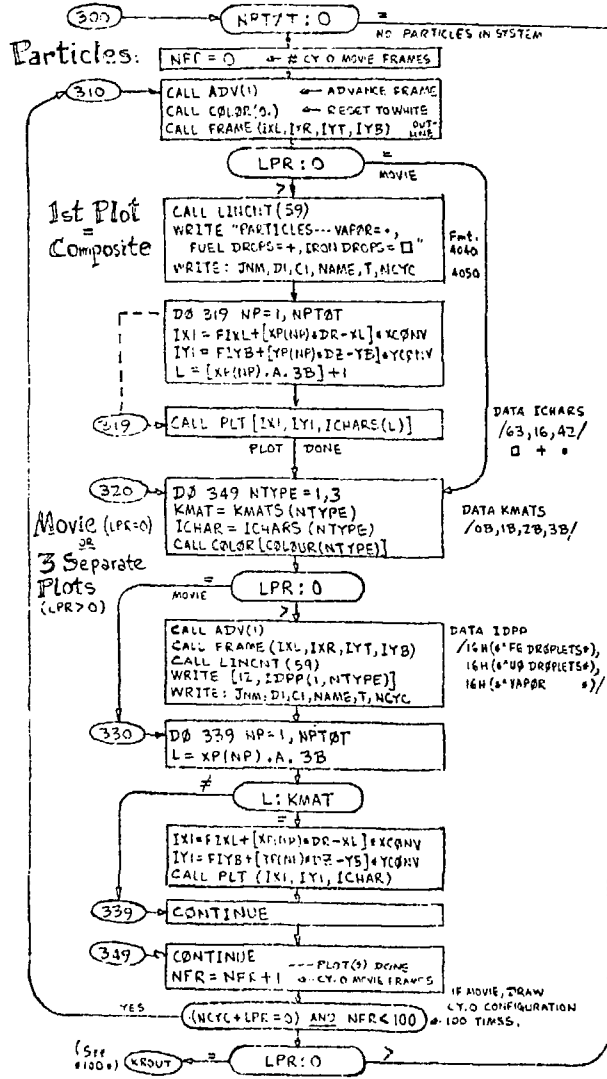
# START OF 2,0 OVERLAY — CONTROL REGION:

6



PARTICLE PLOTS & VELOCITY VECTOR PLOTS:

7

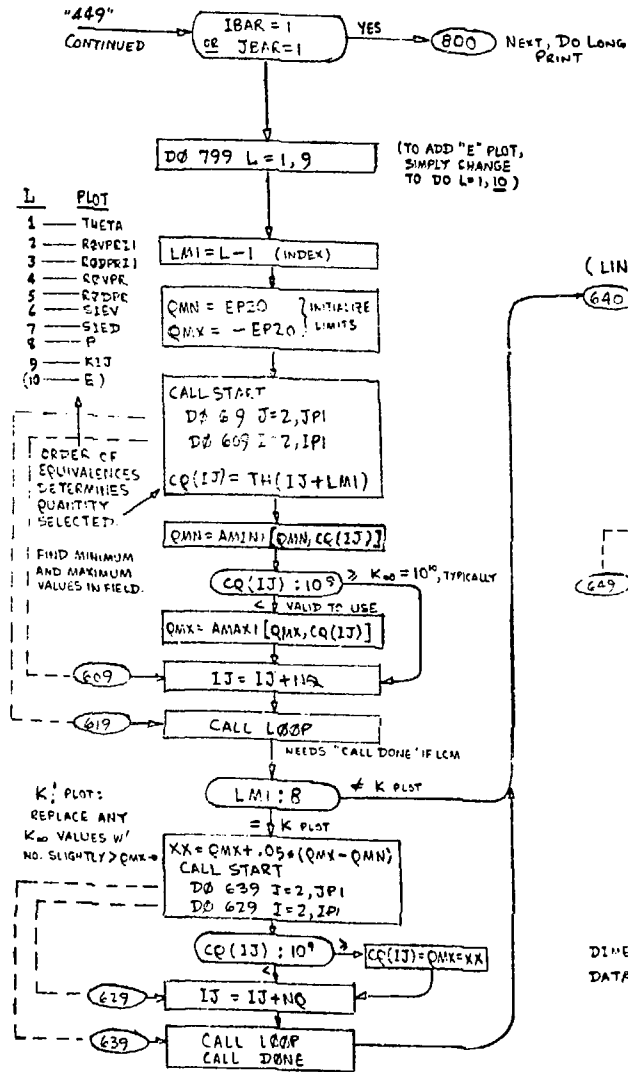


$DRDU \approx 0.5 \left( \frac{0.9 * DR}{VMAX} \right)$   
 WHERE 0.9 DR IS SLIGHTLY LESS THAN A TYPICAL CELL DIMENSION, AS IN VAPOR, & THE 0.5 COEFF. IS FOR VELOCITY-AVERAGING IN X2 & Y2, BELOW.

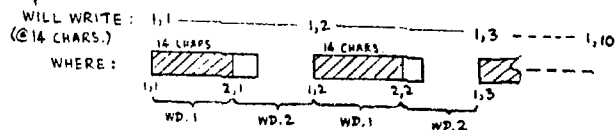
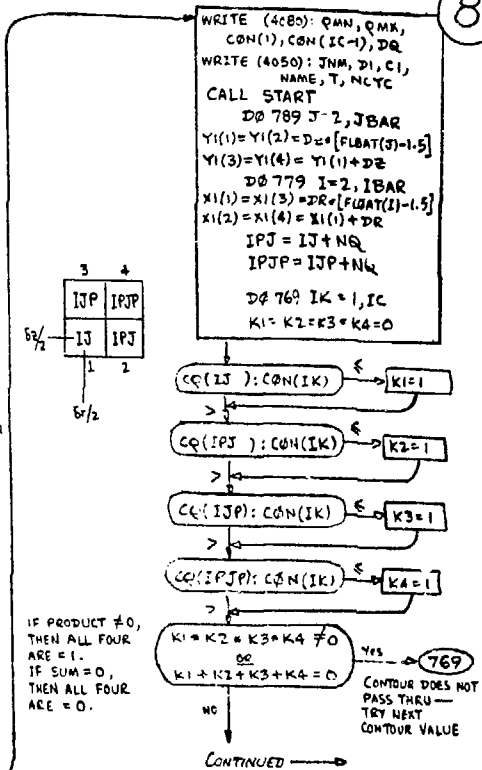
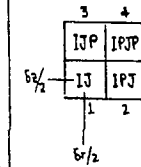
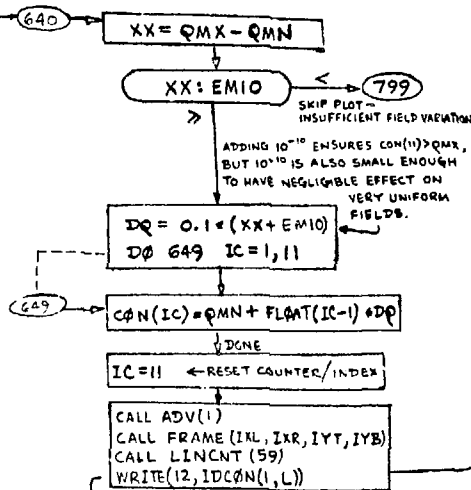
**DATA IDW** /14H(\*VAPOR, \*\*\*), 14H(\*DROPLETS, \*)//  
 4060 FORMAT (1H+, 16X \* MAXIMUM VELOCITY = \* IPEI2.5)



# CONTOUR PLOTS - PAGE 1 OF 2:



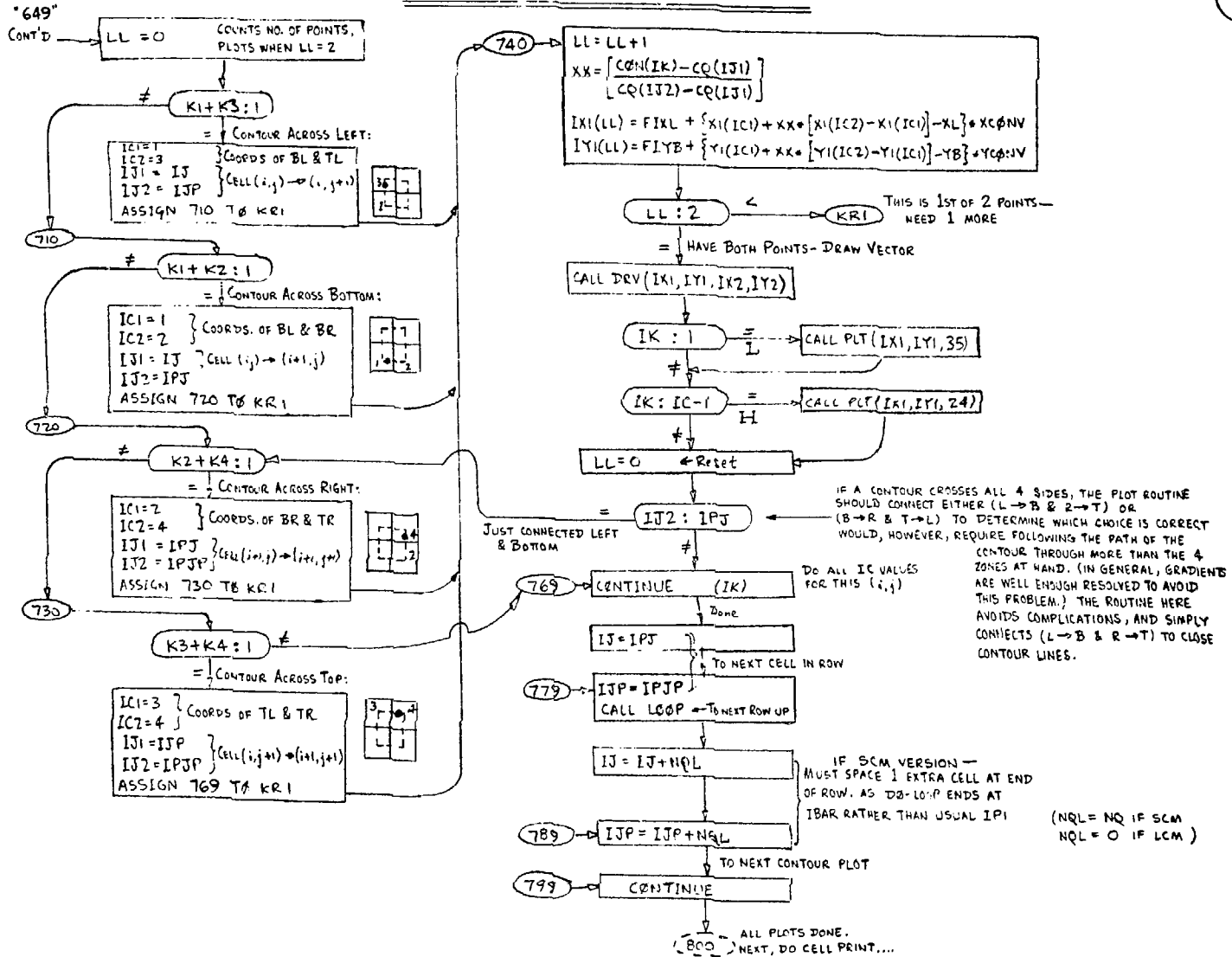
(LINEAR PLOT)



DIMENSION IDCEN(2, 10)  
 DATA IDCEN/16H(\* \* VOID \* FRACTNS), 16H(\* \* RHB - V \* PR., 1\*),  
 16H(\* \* RHB - D \* PR., 1\*), 14H(\* \* RHB - VAPOR \*),  
 14H(\* \* RHB - DRAPS \*), 14H(\* \* SIE - VAPOR \*),  
 14H(\* \* SIE - DRAPS \*), 13H(\* \* PRESSURE \*),  
 13H(\* \* DRAG \* (K) \*), 15H(\* \* ENERGY \* (E) \*)

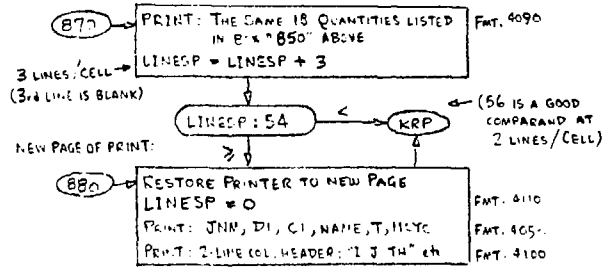
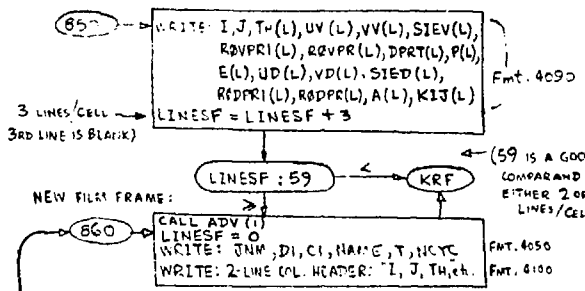
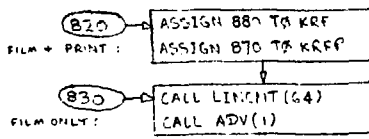
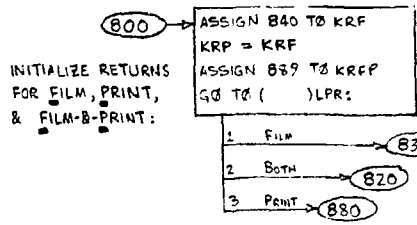
CONTOUR PLOTS — PAGE 2 OF 2:

9

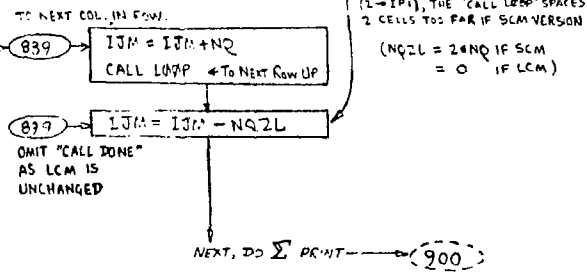
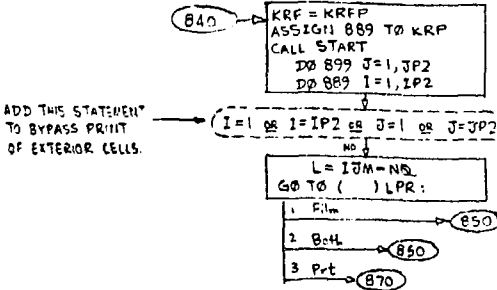


# LONG PRINT:

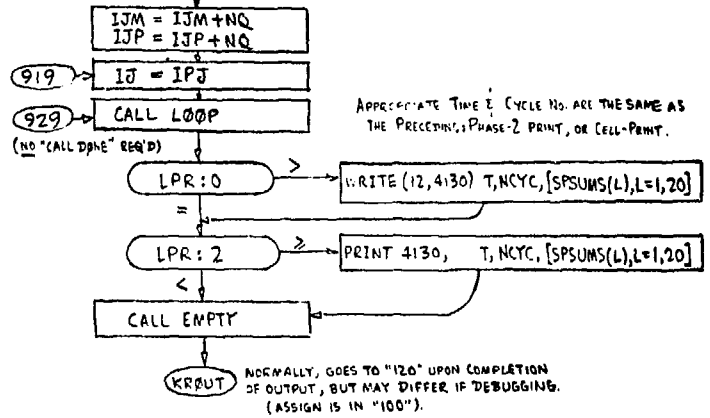
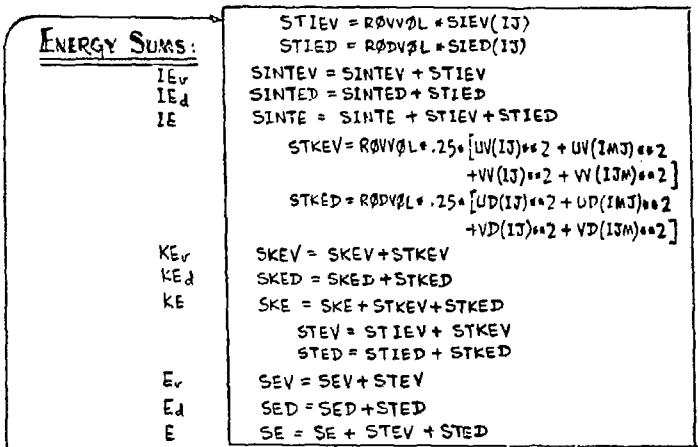
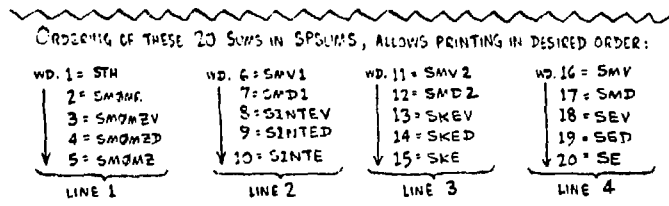
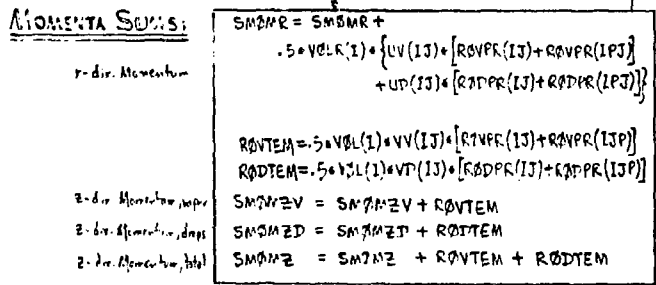
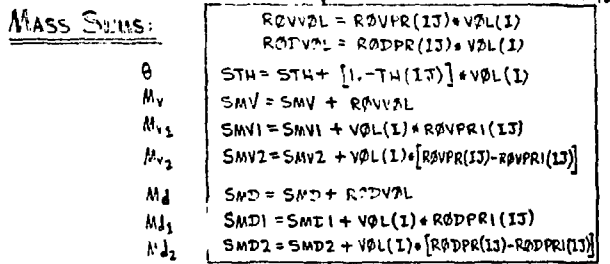
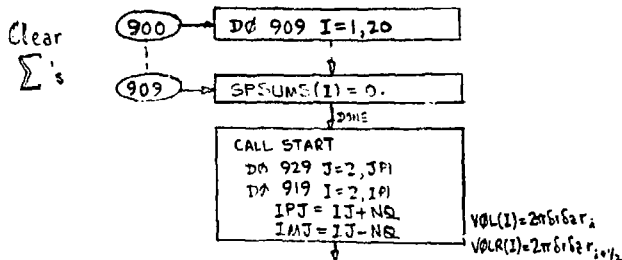
I J @ UV VV SIEV RQVPRI RQVPR D P } 2-LINE FORMAT  
 E UD VD SIED RQDPRI RQDPRA K



BECAUSE "IJ" STARTS AT (i=2, j=2), ROUTINE MUST START AT (i=1, j=1) (= IJM-NQ) IN ORDER TO OBTAIN PROPER VALUES TO MATCH I & J OF THE DO-LOOP:



# SHORT PRINT:



CHOICE —  
 — DO SHORT PRINT:  
 — EVERY CYCLE (ISPR=2)  
 — LONG-PRINT CYCLES ONLY (ISPR=1)

PHASE 1 - P.1 - CALCULATE  $\rho'_d, \rho'_{d1}, \theta, A, \tilde{p}, K$ :

12

BEGIN  
NEW  
CYCLE:

```

1000 CALL START
      D0 1089 J=2, JPI
      D0 1079 I=2, IPI
      IPJ = IJ + NQ
      IMJ = IJ - NQ
    
```

```

XIVL = BDTODR * UV(IMJ) + SIGN(A0, UV(IMJ))
HPXIVL = .5 + XIVL
HMXIVL = .5 - XIVL
XIVR = BDTODR * UV(IJ) + SIGN(A0, UV(IJ))
HPXIVR = .5 + XIVR
HMXIVR = .5 - XIVR
XIVB = BDTODZ * W(IJM) + SIGN(A0, W(IJM))
HPXIVB = .5 + XIVB
HMXIVB = .5 - XIVB
XIVT = BDTODZ * VV(IJ) + SIGN(A0, VV(IJ))
HPXIVT = .5 + XIVT
HMXIVT = .5 - XIVT
    
```

COLLECT TERMS FOR  
CONNECTIVE FLUXES

```

XIDL = BDTODR * UP(IMJ) + SIGN(A0, UP(IMJ))
HPXIDL = .5 + XIDL
HMXIDL = .5 - XIDL
XIDR = BDTODR * UD(IJ) + SIGN(A0, UD(IJ))
HPXIDR = .5 + XIDR
HMXIDR = .5 - XIDR
XIDB = BDTODZ * VV(IJM) + SIGN(A0, VV(IJM))
HPXIDB = .5 + XIDB
HMXIDB = .5 - XIDB
XIDT = BDTODZ * VD(IJ) + SIGN(A0, VD(IJ))
HPXIDT = .5 + XIDT
HMXIDT = .5 - XIDT
    
```

```

UVRR = UV(IJ) * RIP(I) (u,r) : 1/2
UVRL = UV(IMJ) * RIP(I-1) (u,r) : -1/2
UDRR = UD(IJ) * RIP(I) (u,d) : 1/2
UDRL = UD(IMJ) * RIP(I-1) (u,d) : -1/2
THIJ = TH(IJ) "θ"
RR = 1 / ROVPR(IJ)
    
```

NEXT, CALC.  $\rho'_d, \rho'_{d1}, \theta \dots$

$$\rho'_d(IJ) = \rho_{dPR}(IJ) + DTODR * RRI(I) \left\{ \begin{aligned} &UDRL * [HPXIDL * \rho_{dPR}(IMJ) + HMXIDL * \rho_{dPR}(IJ)] \\ &- UDRR * [HPXIDR * \rho_{dPR}(IJ) + HMXIDR * \rho_{dPR}(IPJ)] \end{aligned} \right\} \\ + DTODZ * \left\{ \begin{aligned} &VD(IJM) * [HPXIDB * \rho_{dPR}(IJM) + HMXIDB * \rho_{dPR}(IJP)] \\ &- VD(IJ) * [HPXIDT * \rho_{dPR}(IJ) + HMXIDT * \rho_{dPR}(IJP)] \end{aligned} \right\}$$

$$\rho'_{d1}(IJ) = \rho_{dPR1}(IJ) + DTODR * RRI(I) \left\{ \begin{aligned} &UDRL * [HPXIDL * \rho_{dPR1}(IMJ) + HMXIDL * \rho_{dPR1}(IJ)] \\ &- UDRR * [HPXIDR * \rho_{dPR1}(IJ) + HMXIDR * \rho_{dPR1}(IPJ)] \end{aligned} \right\} \\ + DTODZ * \left\{ \begin{aligned} &VD(IJM) * [HPXIDB * \rho_{dPR1}(IJM) + HMXIDB * \rho_{dPR1}(IJP)] \\ &- VD(IJ) * [HPXIDT * \rho_{dPR1}(IJ) + HMXIDT * \rho_{dPR1}(IJP)] \end{aligned} \right\}$$

```

9 THTE = 1.0 - R0DPR1 * RR01 - [R0DPR1(IJ) - R0DPR1T] * RR02
    
```

(TEST CYCLE > 1 TO ENSURE THAT  $\tilde{p}$  WILL BE INITIALIZED WHEN COMING FROM SETUP. SETUP ENSURES  $B > 0$ )

( $\theta \geq 0.01$  IS CONSIDERED NORMAL.)

```

ROVPR2 = ROVPR(IJ) - ROVPR1(IJ)
A(IJ) = SIEV(IJ) * [ROVPR1(IJ) * BV1GM11 + ROVPR2 * BV2GM12] / {THTE * [ROVPR1(IJ) * BV1 + ROVPR2 * BV2]}
    
```

```

VEL = .25 * [UV(IJ) * 2 + UV(IMJ) * 2 + VV(IJ) * 2 + VV(IJM) * 2]
GAMTE = GGM11 * ROVPR1(IJ) * RR + GGM12 * [1 - ROVPR1(IJ) * RR]
GIR0M = GAMTE * SIEV(IJ) * ROVPR(IJ) * SQMO
THTESQ = THTE * THTE
VEL = VEL + P(IJ) * THTE * RR
RMSQ = {VEL * THTESQ * [ROVPR(IJ) + R0DPR(IJ)] / GIR0M} * 2
    
```

INITIAL  $\tilde{p}$  (AND  $\rho'_d$ ) EACH CYCLE DEPEND ON FUNCTION (P) OF LOCAL MACH NO.

```

P(IJ) = 1. / (1. + 10. * RMSQ)
P(IJ) = F(IJ) * P(IJ) + [1 - F(IJ)] * A(IJ) * ROVPR(IJ)
    
```

```

VECVEL = .5 * RSQR * {UV(IJ) - UD(IJ) + UV(IMJ) - UD(IMJ)} * 2 + VV(IJ) - VT(IJ) + VV(IJM) - VT(IJM) * 2
THTERM = (1 - THTE) / THTESQ
K(IJ) = R(COF) * ROVPR(IJ) * THTERM * (NUV3 + RPCDR * VECVEL)
    
```

USE  $\tilde{p}$  IN K IF  $\tilde{p}$  IS USED, IT MAY = 0, w/  $\theta \geq \theta_0$ , CAUSING A ZERO DIVIDE IN THTESQ

```

1010 SUDGEN
      THTE = 0.0
      A(IJ) = K(IJ) * AKINF1
      (LEAVES "p = \tilde{p}" AKINF1 TYPICALLY = 10)
    
```

```

1020 SIEVC = SIEV(IJ)
      SIEDC = SIED(IJ)
      TYC = SIEVC * ROVPR(IJ) / [ROVPR1(IJ) * BV1 + [ROVPR(IJ) - ROVPR1(IJ)] * BV2]
      TVL = SIEV(IMJ) * ROVPR(IMJ) / [ROVPR1(IMJ) * BV1 + [ROVPR(IMJ) - ROVPR1(IMJ)] * BV2]
      TVR = SIEV(IPJ) * ROVPR(IPJ) / [ROVPR1(IPJ) * BV1 + [ROVPR(IPJ) - ROVPR1(IPJ)] * BV2]
      TVB = SIEV(IJM) * ROVPR(IJM) / [ROVPR1(IJM) * BV1 + [ROVPR(IJM) - ROVPR1(IJM)] * BV2]
      TVT = SIEV(IJP) * ROVPR(IJP) / [ROVPR1(IJP) * BV1 + [ROVPR(IJP) - ROVPR1(IJP)] * BV2]
    
```

DO LOOP CONTINUES ON NEXT PAGE



PHASE 1 - P.2 - CALCULATE  ${}^{n+1}I_V$  AND  ${}^{n+1}I_D$ :

13

CONTINUE  
COLLECTING  
TERMS:

$$\begin{aligned} TDC &= SIEDC \cdot RDPFR(IJ) / \{ RDPRI(IJ) \cdot BD1 + [RDPDR(IJ) - RDPRI(IJ)] \cdot BD2 \} \\ TDL &= SIED(IJ) \cdot RDPFR(IMJ) / \{ RDPRI(IMJ) \cdot BD1 + [RDPDR(IMJ) - RDPRI(IMJ)] \cdot BD2 \} \\ TDR &= SIED(IPJ) \cdot RDPFR(IPJ) / \{ RDPRI(IPJ) \cdot BD1 + [RDPDR(IPJ) - RDPRI(IPJ)] \cdot BD2 \} \\ TDB &= SIED(IJM) \cdot RDPFR(IJM) / \{ RDPRI(IJM) \cdot BD1 + [RDPDR(IJM) - RDPRI(IJM)] \cdot BD2 \} \\ TDT &= SIED(IJP) \cdot RDPFR(IJP) / \{ RDPRI(IJP) \cdot BD1 + [RDPDR(IJP) - RDPRI(IJP)] \cdot BD2 \} \end{aligned}$$

$$\begin{aligned} THLB &= .5 \cdot [THIJ + TH(IMJ)] \\ \text{OMTHLB} &= 1. - THLB \\ THRB &= .5 \cdot [THIJ + TH(IPJ)] \\ \text{OMTHRB} &= 1. - THRB \\ THBB &= .5 \cdot [THIJ + TH(IJM)] \\ \text{OMTHBB} &= 1. - THBB \\ THTB &= .5 \cdot [THIJ + TH(IJP)] \\ \text{OMHTB} &= 1. - THTB \end{aligned}$$

$$\begin{aligned} CFKL &= UVRL \cdot [HPXIVL \cdot SIEV(IJ) + HMXIVL \cdot SIEVC] \\ CFXR &= UVRR \cdot [HPXIVR \cdot SIEVC + HMXIVR \cdot SIEV(IPJ)] \\ CFXB &= VV(IJM) \cdot [HPXIVB \cdot SIEV(IJM) + HMXIVB \cdot SIEVC] \\ CFXT &= VV(IJ) \cdot [HPXIVT \cdot SIEVC + HMXIVT \cdot SIEV(IJP)] \\ SIEDEL &= SIEVC \cdot \{ RRIDR(I) \cdot [RIP(I) \cdot UV(IJ) - RIP(I-1) \cdot UV(IMJ)] \\ &\quad + RTZ \cdot [VV(IJ) - VV(IJM)] \} \\ VEL &= PTE = 0. \end{aligned}$$

THTE: TH<sub>0</sub>

$$\begin{aligned} VEL &= KIJ(IJ) \cdot \{ .5 \cdot [UD(IJ) + UD(IMJ) - UV(IJ) - UV(IMJ)] \cdot \cdot 2 \\ &\quad + .5 \cdot [VD(IJ) + VD(IMJ) - VV(IJ) - VV(IMJ)] \cdot \cdot 2 \} \\ PTE &= P(IJ) \cdot RR \cdot \{ RRIDR(I) \cdot [RIP(I) \cdot [THBB \cdot UV(IJ) + \text{OMTHBB} \cdot UD(IJ)] \\ &\quad - RIP(I-1) \cdot [THLB \cdot UV(IMJ) + \text{OMTHLB} \cdot UD(IMJ)]] \\ &\quad + RTZ \cdot [THTB \cdot VV(IJ) + \text{OMHTB} \cdot VD(IJ)] \\ &\quad - T \cdot RR \cdot VV(IJM) - \text{OMTHBB} \cdot VV(IJM) \} \end{aligned}$$

1030

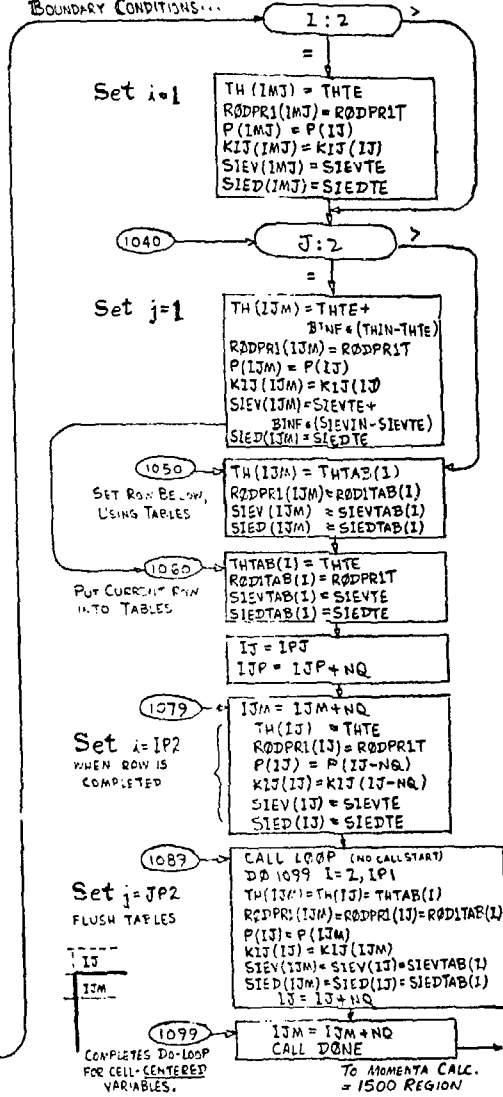
$$\begin{aligned} SIEVTE &= SIEVC + DT \cdot \{ RRIDR(I) \cdot (CFKL - CFXR) + RTZ \cdot (CFXB - CFXT) \\ &\quad + RR \cdot [R \cdot (TDC - TVC) + VEL] \\ &\quad + RRI(I) \cdot KVTEISQ \cdot [THBB \cdot RIP(I) \cdot (TVR - TVC) - THLB \cdot RIP(I-1) \cdot (TVC - TVL)] \\ &\quad + KVDFSSQ \cdot [THTB \cdot (TVT - TVC) - THBB \cdot (TVC - TVB)] \} \cdot PTE + SIEDEL \end{aligned}$$

A(IJ): AKINFJ  $\neq$  NORMAL  $\rightarrow$  A(IJ) = A(IJ) \* SIEVTE / SIEVC ADJUST A<sub>ij</sub> FOR PHASE 2

$$\begin{aligned} CFKL &= UDRL \cdot [HPXIDL \cdot SIED(IPJ) + HMXIDL \cdot SIEDC] \\ CFXR &= UDRR \cdot [HPXIDR \cdot SIEDC + HMXIDR \cdot SIED(IPJ)] \\ CFXB &= VD(IJM) \cdot [HPXIDB \cdot SIED(IJM) + HMXIDB \cdot SIEDC] \\ CFXT &= VD(IJ) \cdot [HPXIDT \cdot SIEDC + HMXIDT \cdot SIED(IJP)] \\ SIEDEL &= SIEDC \cdot \{ RRI(I) \cdot [UD(IJ) \cdot RIP(I) - UD(IMJ) \cdot RIP(I-1)] \\ &\quad + RTZ \cdot [VD(IJ) - VD(IJM)] \} \\ SIEDTE &= SIEDC + DT \cdot \{ RRIDR(I) \cdot (CFKL - CFXR) + RTZ \cdot (CFXB - CFXT) \\ &\quad + 1. / RDPDR(IJ) \cdot [R \cdot (TVC - TDC) + E(IJ)] \\ &\quad + RRI(I) \cdot KVDFSSQ \cdot [\text{OMTHRB} \cdot RIP(I) \cdot (TDR - TDC) - \text{OMTHLB} \cdot RIP(I-1) \cdot (TDC - TDL)] \\ &\quad + KVDFSSQ \cdot [\text{OMHTB} \cdot (TDT - TDC) - \text{OMTHBB} \cdot (TDC - TDB)] \} \\ &\quad + SIEDEL \end{aligned}$$

n+1  
I  
I  
E FROM NEUTRONICS

BOUNDARY CONDITIONS...



# PHASE 1-P.3 - CALCULATE $(\overline{p_v u_v})$ OR $(\overline{p_d u_d})$ :

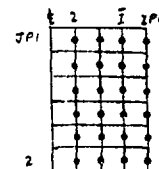
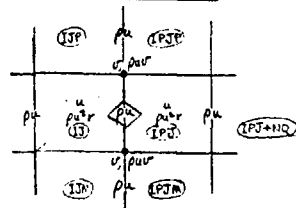
From Previous Page  
 KREQ = 0 ← To Calc.  $(\overline{p_v u_v})$  &  $(\overline{p_d u_d})$  FIRST

SEE NOTE AT EIGHT  
 1500  
 REENTRY POINT FROM "1600"

IBAR: 1 = 1550  
 CALL START  
 DD 1549 J=2, JPI  
 DD 1539 I=2, IBAR

IJA = KREQ + IJ  
 IJPA = KREQ + IJP  
 IJMA = KREQ + IJM  
 IPJA = IJA + NQ  
 IMJA = IJA - NQ  
 IPJPA = IJPA + NQ  
 IPJMA = IJMA - NQ

WILL SHIFT BY 1 WD. ON 2nd PASS, AUTOMATICALLY GOING TO  $(\overline{p_d u_d})$  CALC.  
 (NOTE - DON'T ALTER IJ, IJP, IJM.)



$\overline{p_v u_v}$  VALUES IN THESE LOCATIONS ARE SET BY CODE 1500-1549 (I=1 VALUES = 0.0)

URB = UV(IJA)  
 UC = .5 \* [URB + UV(IMJA)]  
 UR = .5 \* [URB + UV(IPJA)]  
 R0ULB = .5 \* [R0VPR(IJA) + R0VPR(IMJA)] \* UV(IMJA)  
 R0URB = .5 \* [R0VPR(IJA) + R0VPR(IPJA)] \* URB  
 R0UK2B = .5 \* [R0VPR(IPJA) + R0VPR(IPJA+NQ)] \* UV(IPJA)  
 VTRC = .5 \* [VV(IJA) + VV(IPJA)]  
 VBRC = .5 \* [VV(IJMA) + VV(IPJMA)]  
 VRB = .5 \* [VTRC + VBRC]  
 R0UJP = .5 \* [R0VPR(IJPA) + R0VPR(IPJPA)] \* UV(IJPA)  
 R0UJM = .5 \* [R0VPR(IJMA) + R0VPR(IPJMA)] \* UV(IJMA)  
 FR = - [SIGN [EPV(KREQ+1), VRB] \* URB \* VRB] / [URS\*\*2 + VRS\*\*2 + 10\*\*11]

IF I=1, IT IS SIMPLEST TO BYPASS 1550 REGION, BUT CARE MUST BE TAKEN IN 1600 LOOP. (NOTE THAT A CONTINUATIVE RT. BDRY. IS NOT AN OPTION WHEN I=1, BECAUSE EVEN IF ITS U IS SET, IT IS SET TO ZERO)

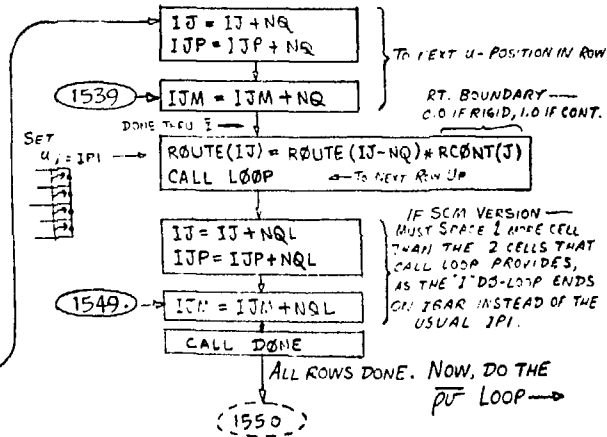
BECAUSE: DIMENSION EPV(2) EQUIVALENCE [EPV(2), EPD] IT WILL AUTOMATICALLY USE EPD ON 2nd PASS

AVOID 2D WHEN I=0, WHEN ALL VELS. ARE 0

XIC = BDT0DR \* UC + SIGN[A0, UC]  
 XIR = BDT0DR \* UR + SIGN[A0, UR]  
 XIBR = BDT0DZ \* VBRC + SIGN[A0, VBRC]  
 XITR = BDT0DZ \* VTRC + SIGN[A0, VTRC]  
 ROUTE(IJ) = R0URB + FR \* DT +  
 RRIPI \* BDT0DR \* { UC \* RI(I) \* { [.5 + XIC] \* R0ULB + [.5 - XIC] \* R0URB }  
 - UR \* RI(I+1) \* { [.5 + XIR] \* R0URB + [.5 - XIR] \* R0UR2B } }  
 + BDT0DZ \* { VBRC \* { [.5 + XIBR] \* R0UJM + [.5 - XIBR] \* R0URB }  
 - VTRC \* { [.5 + XITR] \* R0URB + [.5 - XITR] \* R0UJP } }

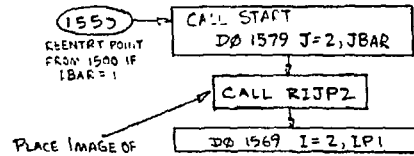
$(\overline{p_v u_v})_{i=1/2}$   
 IF KREQ=1,  
 OR:

$(\overline{p_d u_d})_{i=1/2}$   
 IF KREQ=2

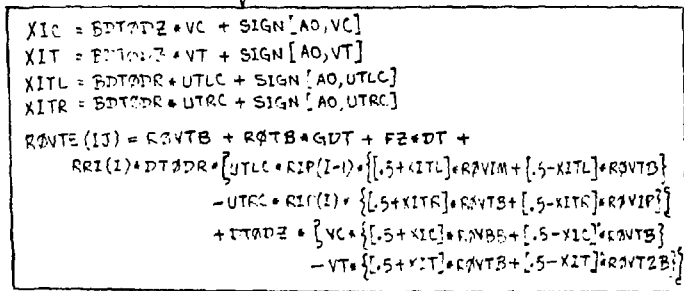
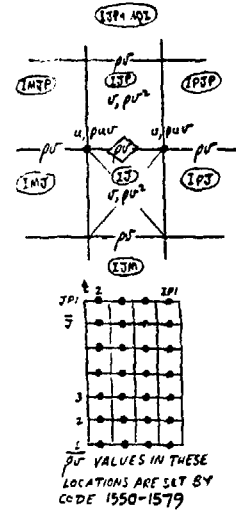
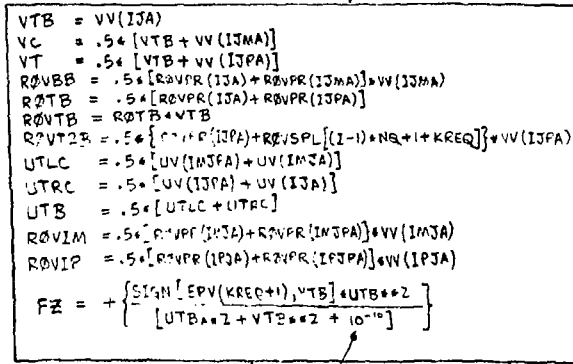
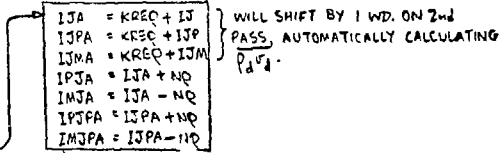


PHASE 1-P.4 - CALCULATE  $(P_v, V_v)$  OR  $(P_D, V_D)$ :

15

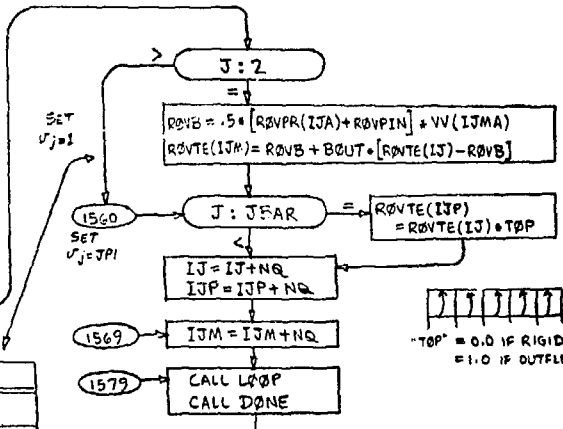


PLACE IMAGE OF  
ROW j+2 INTO  
AAROW, FOR  
USE IN ROWTB  
(NECESSARY IF  
LCM W/ 3-ROW  
BUFFERING, BUT  
DONE W/ SCM  
VERSION ALSO  
FOR COMPATIBILITY)



$(P_v, V_v)^{1/2}$   
IF KREQ = 1,  
CR:

$(P_d, V_d)^{1/2}$   
IF KREQ = 2



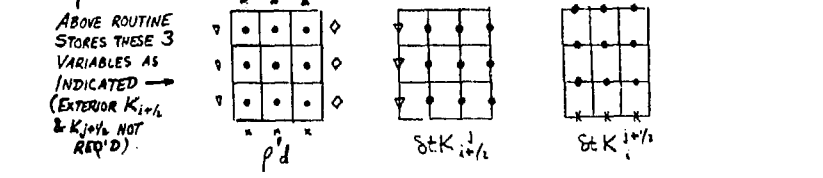
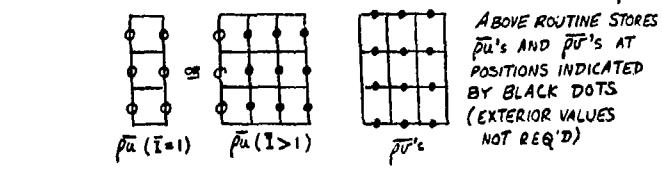
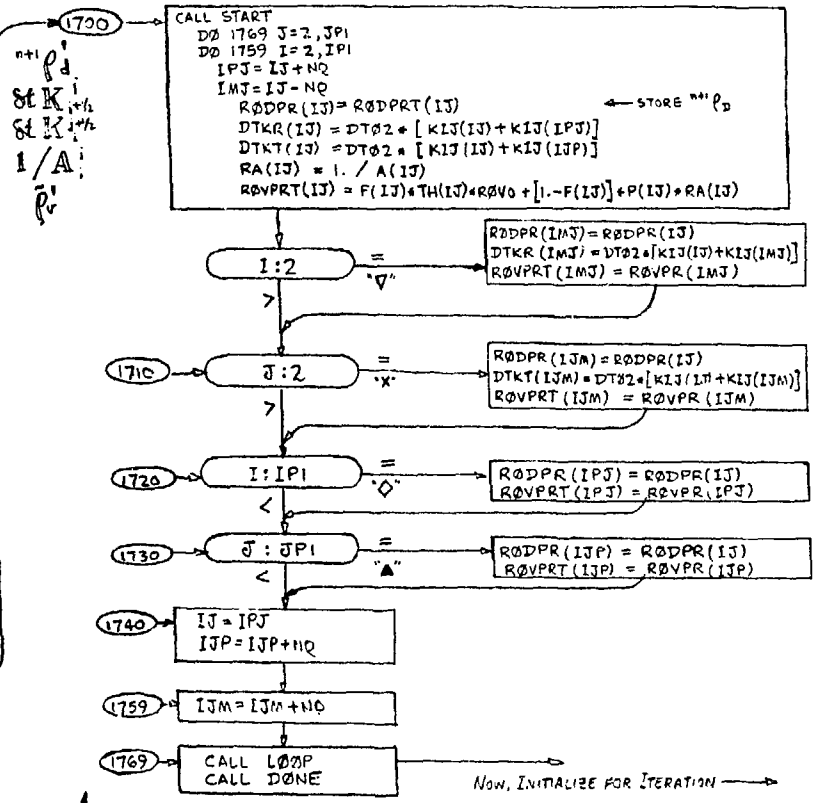
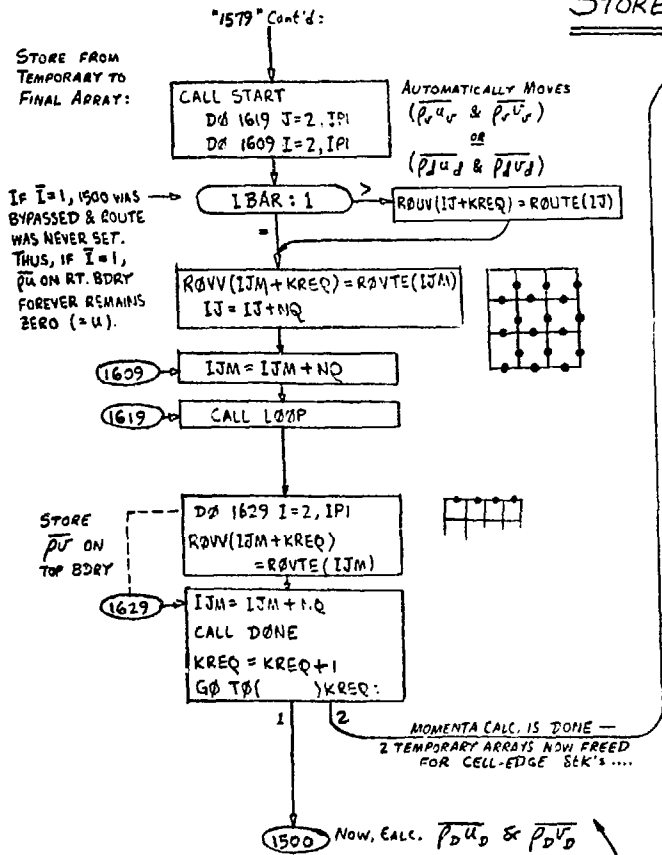
BOTTOM:	ROWTE(IJM) =
RIGHT:	= 0.0 [AS VV(IJMA) = 0.0]
OUTFLOW:	= ROWTE(IJ) [ ] [ ] [ ] [ ] [ ]
INFLOW:	= $P_v$ SPECIFIED
$P_v, V_v$ ALSO WORKS, AS VV(IJMA) = VD = 0	

CONTINUED ON NEXT PAGE →

PHASE 1 - P.5 - COMPLETION OF MOMENTUM CALCULATION,

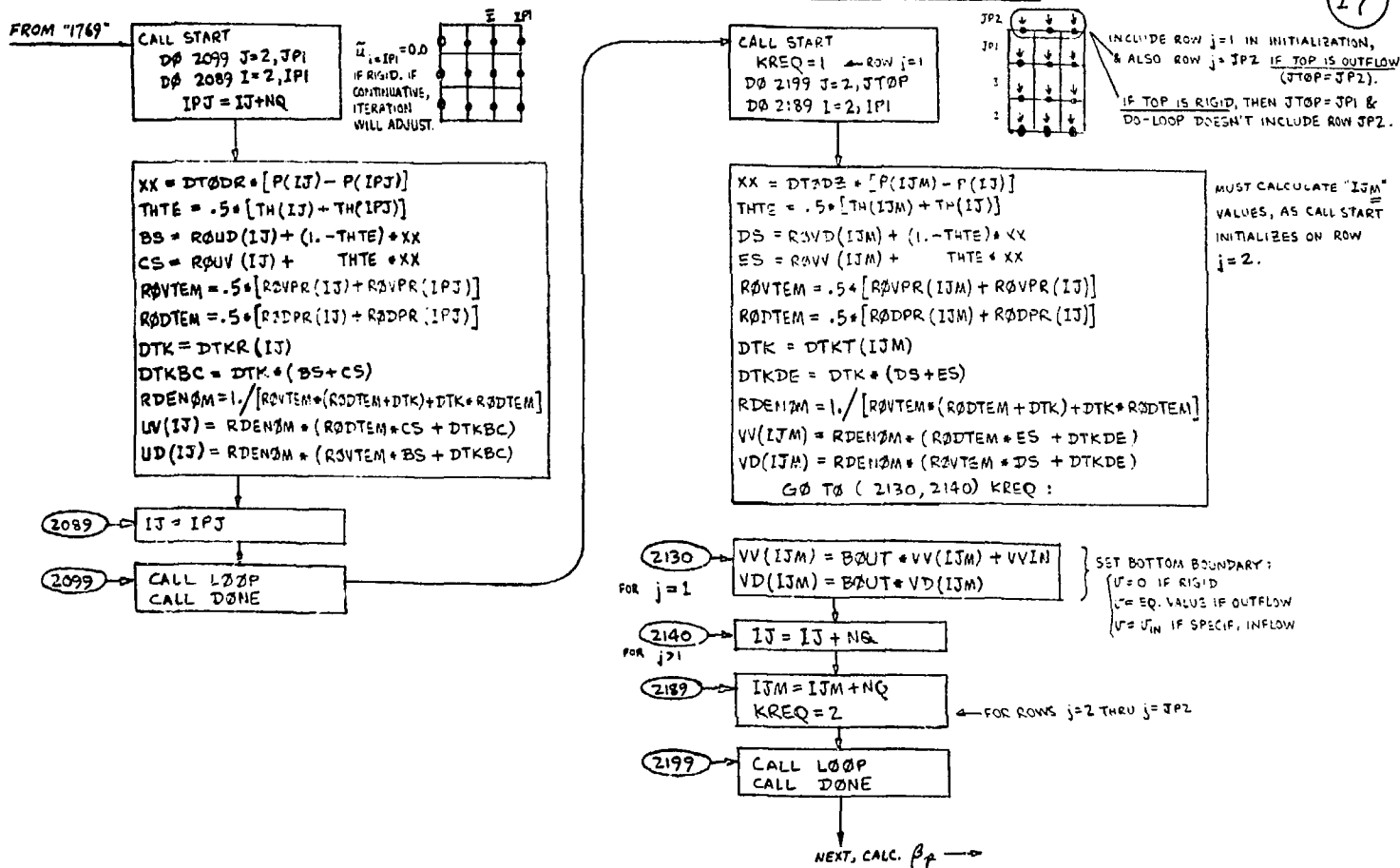
16

STORE  $\bar{p}_D^{n+1}$ , SET  $\delta t K$ 's &  $\bar{p}_V$ :



## PHASE 2 - P.1 - INITIALIZE TILDE VELOCITIES:

17



# PHASE 2 - P.2 - CALCULATE $\beta$ AND CONVERGENCE :

```

2199 CONTINUED
CONV = 0.0
CALL START
DØ 2299 J=2, JP1
DØ 2289 I=2, IP1
IMJ = IJ - NQ
IPJ = IJ + NQ
R2A = .5 * RA(IJ) - (1/2A!)
LVR = UV(IJ)
UVL = UV(IMJ)
VVT = VV(IJ)
VVB = VV(IJM)
    
```

```

I: 2
DTK = DTKR(IMJ)
THTEL = .5 * [TH(IJ) + TH(IMJ)]
RØVL = .5 * [RØVPR(IJ) + RØVPR(IMJ)]
RØDL = .5 * [RØDPR(IJ) + RØDPR(IMJ)]
PUDENL = 1. / [RØVL * (RØDT + DTK) + DTK * RØDL]
TERMIL = RØVL * (1. - THTEL) * DTØDR
TERM1L = THTEL * DTØDR
    
```

```

J: 2
DTK = DTKT(IJM)
THTEB = .5 * [TH(IJ) + TH(IJM)]
RØVB = .5 * [RØVPR(IJ) + RØVPR(IJM)]
RØDB = .5 * [RØDPR(IJ) + RØDPR(IJM)]
PVDENB = 1. / [RØVB * (RØDT + DTK) + DTK * RØDB]
TERMB = RØVB * (1. - THTEB) * DTØDZ
TERM1B = THTEB * DTØDZ
    
```

EQUIVALENCE TO USE SAME i-TABLES AS TH1B, CV1B, & CD1B IN PHASE 1, + 2 MORE TABLES.

```

I +
DTK = DTKR(IJ)
THTER = .5 * [TH(IJ) + TH(IPJ)]
RØVR = .5 * [RØVPR(IJ) + RØVPR(IPJ)]
RØDR = .5 * [RØDPR(IJ) + RØDPR(IPJ)]
PUDENR = 1. / [RØVR * (RØDR + DTK) + DTK * RØDR]
TERMIR = RØVR * (1. - THTER) * DTØDR
TERM1R = THTER * DTØDR
    
```

```

J +
DTK = DTKT(IJ)
THTET(I) = .5 * [TH(IJ) + TH(IJP)]
RØVT = .5 * [RØVPR(IJ) + RØVPR(IJP)]
RØDT(I) = .5 * [RØDPR(IJ) + RØDPR(IJP)]
PVDENT(I) = 1. / [RØVT * (RØDT(I) + DTK) + DTK * RØDT(I)]
TERMIT(I) = RØVT * [1. - THTET(I)] * DTØDZ
TERM1T(I) = THTET(I) * DTØDZ
    
```

```

INCOMPRESSIBLE?
TH(IJ): TH0
INCOMP. <
NORMAL >
PARUL = - [TERMIL - RØDL * [TERM1L + UVL * R2A]] * PUDENL
PARVB = - [TERMB - RØDB * [TERM1B + VVB * R2A]] * PVDENB
PARUR = + [TERMIR - RØDR * [TERM1R - UVR * R2A]] * PUDENR
PARVT = + [TERMIT(I) - RØDT(I) * [TERM1T(I) - VVT * R2A]] * PVDENT(I)
RBETA = RA(IJ) * RDT +
RDR * RRI(I) * DTØDR * [RIP(I) * THTER + RIP(I-1) * THTEL]
+ RIP(I) * DTKR(IJ) * PARUR - RIP(I-1) * DTKR(IJM) * PARUL
+ RØZ * [DTØDZ * [THTET(I) + THTEB]
+ DTKT(IJ) * PARVT - DTKT(IJM) * PARVB]
ØMBETA(IJ) = ØMP / RBETA
    
```

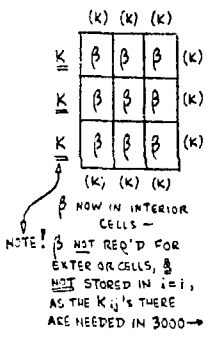
```

2250 ØMBETA(IJ) = ØMBSPL * RØDPR(IJ)
CONV = AMAXI [CONV, {RØDR * [ABS(UVR) + ABS(UVL)]
+ RØDZ * [ABS(VVT) + ABS(VVB)]} * RØVPR(IJ)]
    
```

```

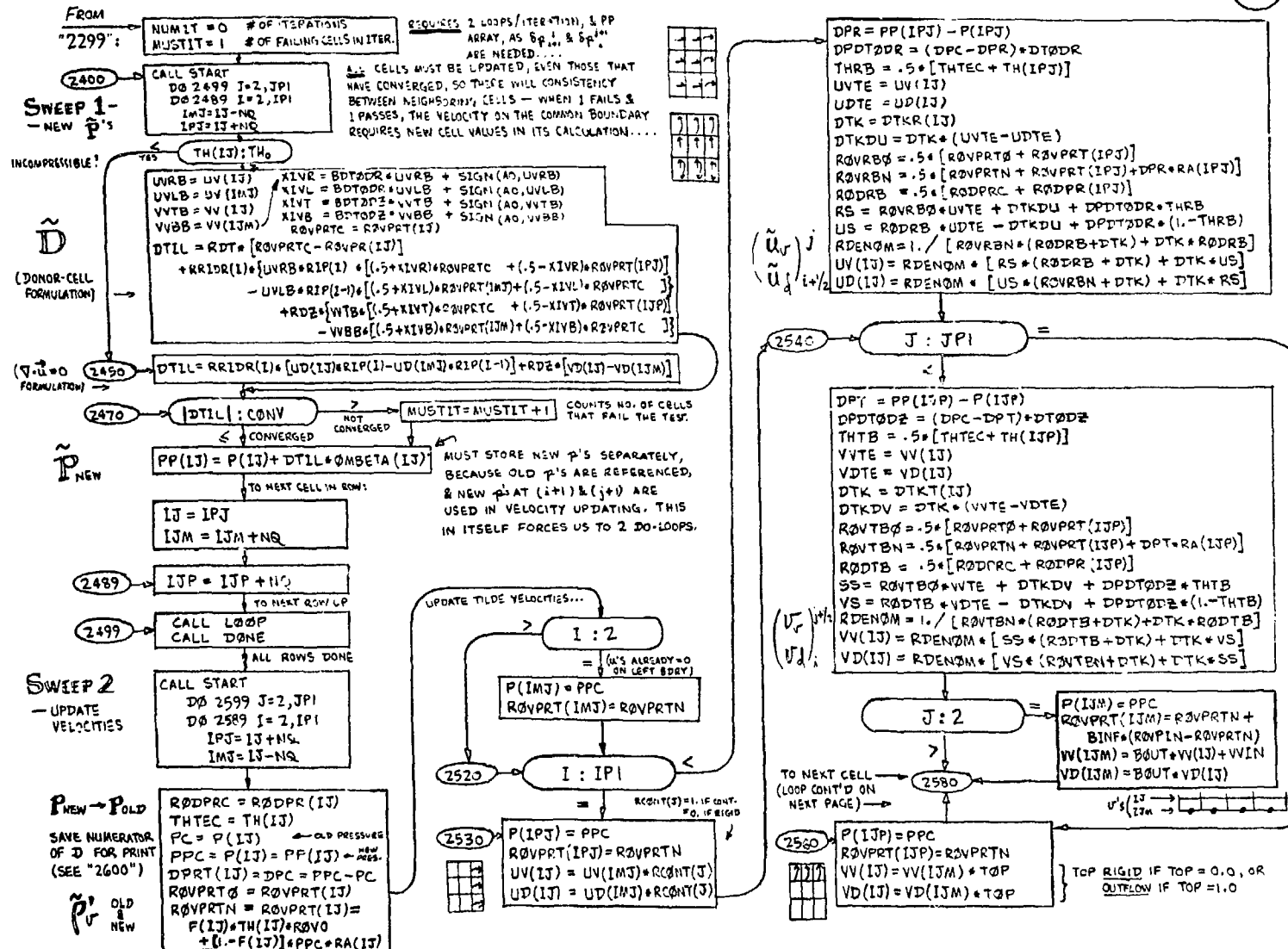
IJ = IPJ
IJP = IJP + NQ
2289 IJM = IJM + NQ
2299 CALL LOOP
CALL DONE
    
```

COMPLETE CONVERGENCE CRITERIA:  
 IF EPS = 10<sup>-4</sup>, THEN THE LIMIT WITH ZERO VELOCITIES IS 10<sup>-6</sup> - 10<sup>-6</sup> = 10<sup>-10</sup>, WELL WITHIN ACCURACY STANDARDS. (IF FINER E WERE 10<sup>-10</sup>, HOWEVER, THE RESULTING 10<sup>-14</sup> WOULD NOT ALLOW CONVERGENCE, AS IT IS ON THE EDGE OF MACHINE SIGNIFICANCE.)



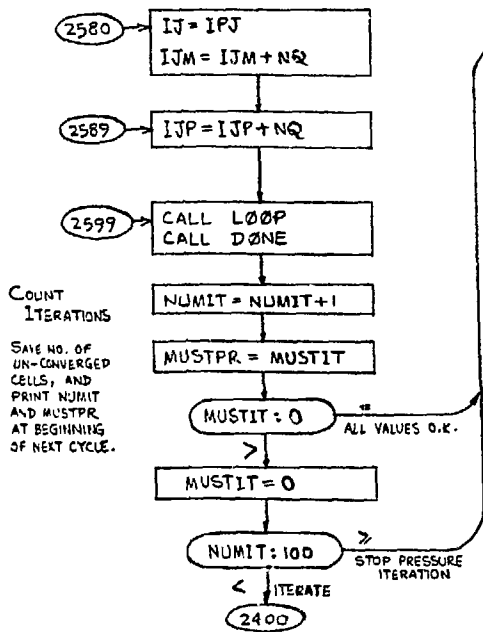
NEXT, THE ITERATION LOOPS →

PHASE 2 - P.3 - PRESSURE ITERATION:



PHASE 2 - P. 4 - END  $\tilde{P}$  ITERATION. STORE  $D$ ,  ${}^{n+1}P_v^i$ , AND  $\tilde{P}_{v1}^i$ :

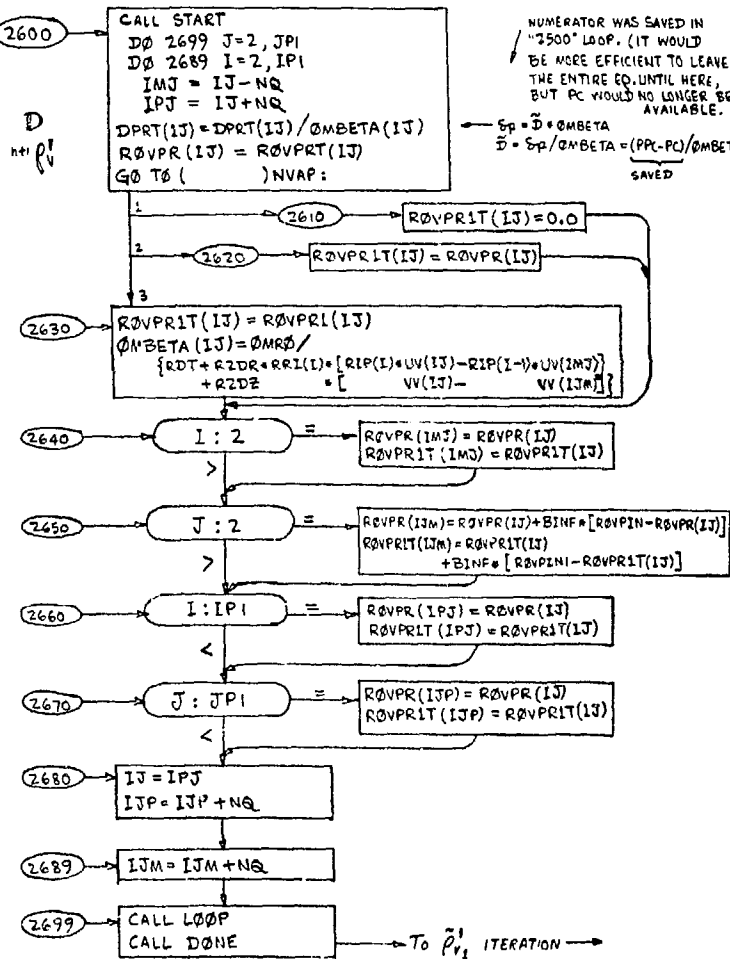
20



COUNT ITERATIONS  
SAVE NO. OF UN-CONVERGED CELLS, AND PRINT NUMIT AND MUSTPR AT BEGINNING OF NEXT CYCLE.

NVAP:	CONDITION:	TREATMENT:
1	$P_{v1} = 0$ & $P_{v2} > 0$	NO ITERATION; SET $P_{v1}^i \rightarrow 0$
2	$P_{v1} > 0$ & $P_{v2} = 0$	NO ITERATION; SET $P_{v1}^i = P_v^i$
3	$P_{v1} > 0$ & $P_{v2} > 0$	ITERATE; STARTING GUESS IS OLD $P_{v1}^i$ 's

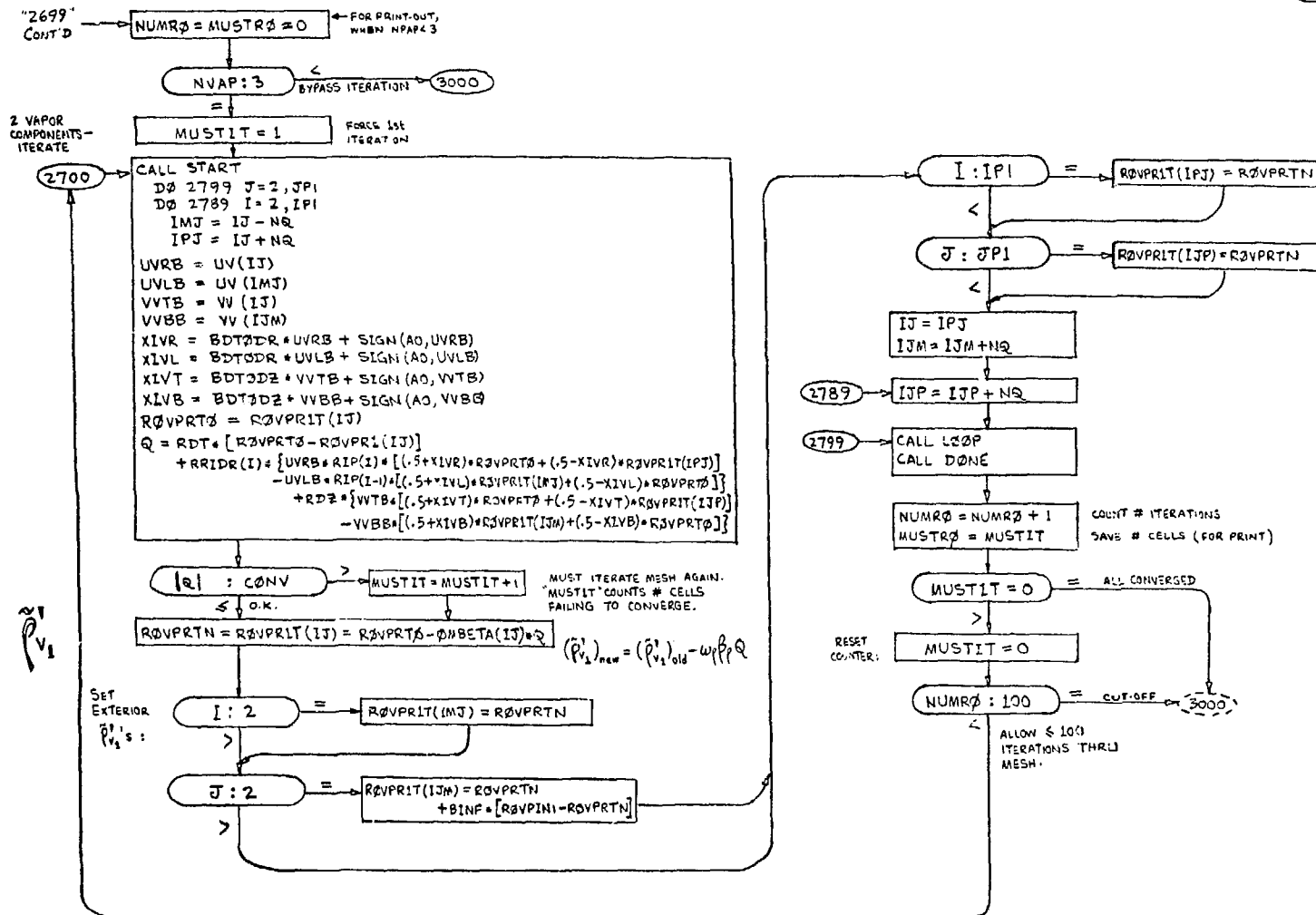
CALC. D HERE, AS OMBETA WILL BE REPLACED BY  $(\omega_p \beta_p)$  BELOW.  
STORE  ${}^{n+1}P_v^i$  TO FREE ARRAY FOR  $\tilde{P}_{v1}^i$ .



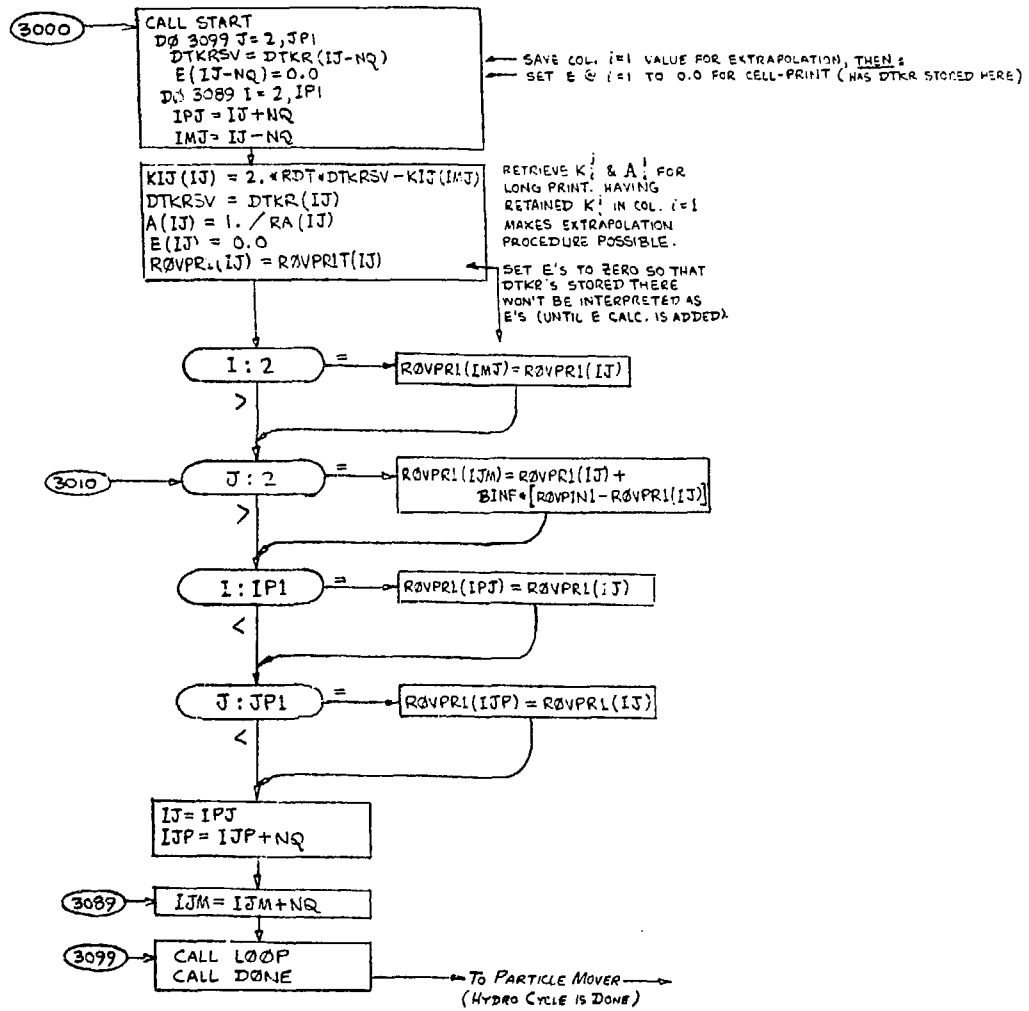
NUMERATOR WAS SAVED IN "2500" LOOP. (IT WOULD BE MORE EFFICIENT TO LEAVE THE ENTIRE EQ. UNTIL HERE, BUT PC WOULD NO LONGER BE AVAILABLE.)  
 $S_p = \tilde{D} * OMBETA$   
 $\tilde{D} = S_p / OMBETA = (PPR - PC) / OMBETA$   
SAVED



PHASE 2 - P.5 -  $\bar{p}'_{vi}$  ITERATION:

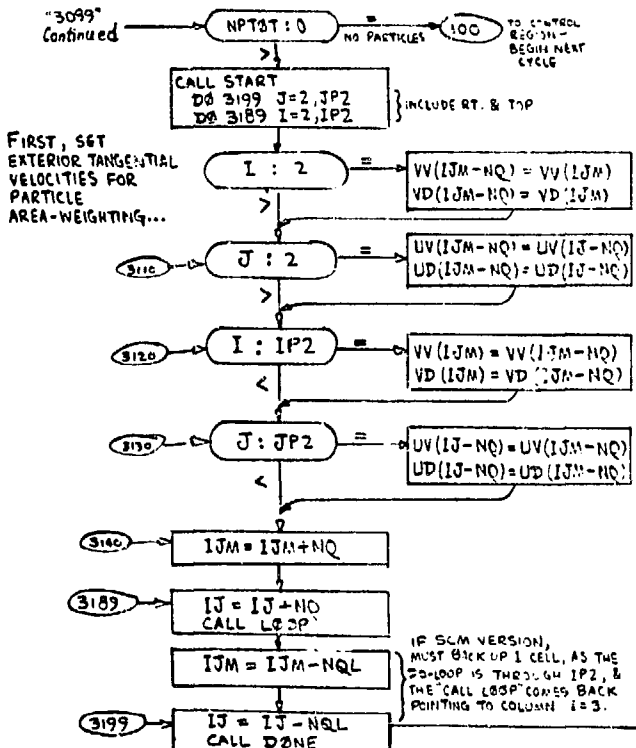


PHASE 2 - P.6 — STORE  $K$ ,  $A$ , AND  $\rho_{vi}$ :



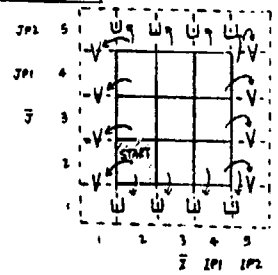
# PARTICLE MOVER:

23

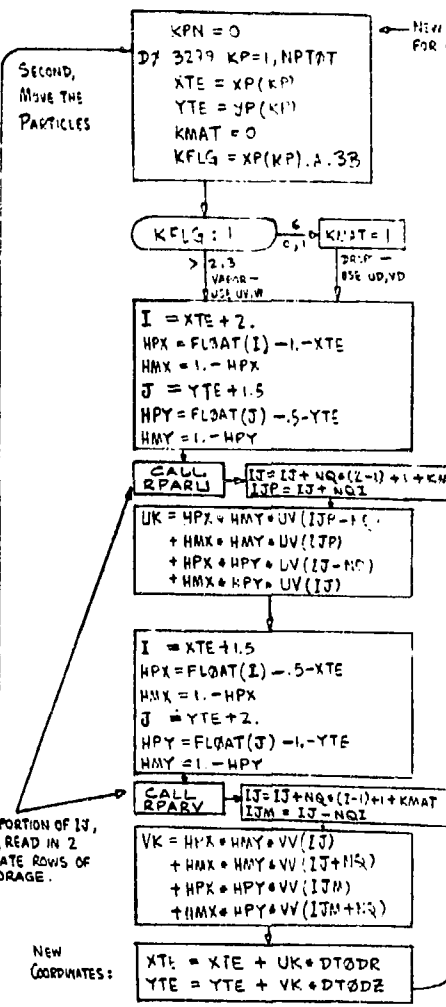


FIRST, SET EXTERIOR TANGENTIAL VELOCITIES FOR PARTICLE AREA-WEIGHTING...

{ NQL = NQ IF SCM  
= 0 IF LCM }



SET "J" PORTION OF IJ, & IF LCM, READ IN 2 APPROPRIATE ROWS OF CELL STORAGE.

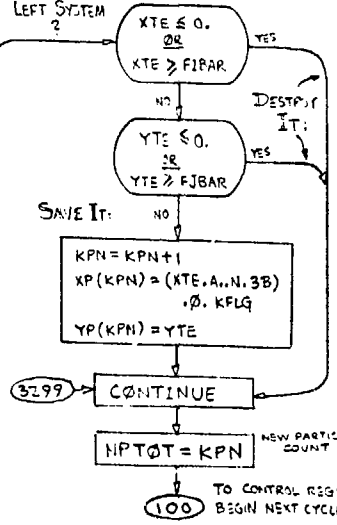


NEW INDEX & COUNTER FOR PACKED PARTICLES

PARTICLE FLAG (KFLG)	SUBSTANCE REPRESENTED	ADD KMAT:	TO USE VELOCITIES
0, 1	DROPS	1	(UD, VD)
2, 3	VAPOR	0	(UV, VV)

ADDING KMAT TO IJ MAKES IT AUTOMATICALLY USE (UV, VV) OR (UD, VD) AS APPROPRIATE FOR EACH PARTICLE. REQUIRES THAT STORAGE ARRANGEMENT BE: UV, UD, VV, VD (AS IN PH. 1 P. 0, P. 0 CALC.).

HAS PARTICLE LEFT SYSTEM?



APPENDIX B  
FORTRAN IV INDEX LISTING OF THE KACHINA PROGRAM  
(June 19, 1974 Status)

LASL identification: LP-0335

```

.....
INDEX COMPILED ON 06/11/74
INDEX START TIME IS 2.629 SECONDS
.....

```

VARIABLES ARE DESCRIBED BY TYPE  
FOR ARRAYS TYPE IS PRECEDED BY ( )

CODE	MEANING OF CODE ASSOCIATED WITH LINE REFERENCES
*	STATEMENT NUMBER DEFINED
=	VARIABLE APPEARS ON LEFT OF = SIGN
AG	ARGUMENT IN SUBROUTINE, FUNCTION OR CALL
AS	ASSIGN STATEMENT
BI	BUFFER IN
BO	BUFFER OUT
CN	NAME OF LABELLED COMMON
CO	VARIABLE IN COMMON
CX	COMPLEX
DA	DATA STATEMENT
DA	DOUBLE PRECISION
DC	DECODE
DI	DIMENSION
DO	DO LOOP
EC	ENCODE
EN	ENTRY POINT
EQ	EQUIVALENCE
F	FUNCTION
IN	INTEGER
LA	LARGE
LC	VARIABLE IN LCM
LG	LOGICAL
LX	LEFT ROUTINE
NM	NAMelist
PA	PARAMETER
PR	PRINT
PU	PUNCH
RD	READ
RL	REAL
SI	SMALL IN
SM	SMALL
SO	SMALL OUT
SU	SUBROUTINE
TI	TINY IN
TO	TINY OUT
WR	WRITE

INDEX 01/00/75

OVERLAY (KACHFIL,0,0)

PAGE 1

1 OVERLAY (KACHFIL,0,0)

KACHINA 2

INDEX 01/00/75

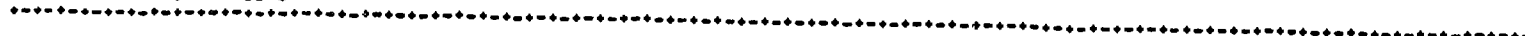
PROGRAM KACHINA (INP,OUT,FILM,FSET9=OUT,FSET12=FILM,FSET7,FSET8)

PAGE 2

1	PROGRAM KACHINA (INP,OUT,FILM,FSET9=OUT,FSET12=FILM,FSET7,FSET8)	KACHINA	3
2	COMMON /KSB/ AA1(1),AAROW(988)	KOM	2
3	COMMON /KSC/ AA(1),AASC(26676),AKINFI,A0,BDODR,BDODZ,	KOM	3
	BD1,BD2,BTNF,ROUT,RV1,RV1GM11,RV2,RV2GM12,	KOM	4
1	BC,CDR,COI,OUR(J),C1,DR,DR02,DRSQ,DT,DT0(10),	KOM	5
2	UTOC(I0),DODR,DTODZ,DT02,DTPOS,DZ,DZ02,	KOM	6
3	DZSQ,D1,EM10,EM3,EM6,EPS,EPV(?),EP9,EP10,EP20,	KOM	7
4	FIBAR,F1XL,F1XR,F1YB,F1YT,FJBAR,G,GAM1,GAM2,GDT,	KOM	8
5	GGM11,GGM12,GM11,GM12,I,TABRT,IALL,IBAR,IOTO,IJ,	KOM	9
6	IJM,IJP,IP1,IP2,ISPR,IXL,IXR,IYB,IYT,J,JRAR,JNM,JPI,	KOM	10
7	JP2,JRIGID,JTOP,JX1,JX2,JX3,JZ,J3,KD,KDODRSQ,	KOM	11
8	KDODZSQ,KV,KVODRSQ,KVODZSQ,LCM,LPR,MUSTPR,	KOM	12
9	MUSTRO,NAME(B),NCYC,NLC,NPTOT,NQ,NQI,NQI2,	KOM	13
1	NQL,NQ2,NQ21,NSC,NUMTI,NUMRO,NUMTD,NIIV,	KOM	14
1	NUV3,NVAP,OMBAS,OMBSPL,OMP,OMRO,R,RCONT(66),RDR,	KOM	15
2	RDRSQ,RDT,RDZ,RDZSQ,PI(34),RIBAR,RIBJB,RIP(34),	KOM	16
3	RJBAR,R01,R02,HOVPTN,ROVIN1,ROVO,RPAR,RPCDR,RPCOF,	KOM	17
4	RRI(34),RRJP(34),RRTDR(34),RR01,RR02,RZDR,RZDZ,	KOM	18
5	STEVIN,SQMH,T,THIN,THD,TLIMD,TOP,TOUT,TWFIN,	KOM	19
6	T2MD,VOL(34),VOLR(34),VVIN,XCONV,XL,XP(4000),XR,	KOM	20
7	YB,YCONV,YP(4000),YT,ZZ	KOM	21
4	EQUIVALENCE (AASC(1),TH),(AASC(2),ROVPR1),(AASC(3),RODPR1),	EQVREAL	2
1	(AASC(4),ROVPR),(AASC(5),RODPR),(AASC(6),SIEV),	EQVREAL	3
2	(AASC(7),SIED),(AASC(8),P),(AASC(9),KIJ,OMBETA),	EQVREAL	4
3	(AASC(10),E,ROUFE,DTKR),(AASC(11),ROVTE,DTKT),	EQVREAL	5
4	(AASC(12),IIV,ROUV),(AASC(13),UD,ROUD),	EQVREAL	6
5	(AASC(14),VV,ROVV),(AASC(15),VD,ROVD),	EQVREAL	7
6	(AASC(16),A,RA),(AASC(17),CQ,ROVPRT,RODPRT,ROVPR1),	EQVREAL	8
7	(AASC(18),PP,DPRT),(AASC(19),F)	EQVREAL	9
5	EQUIVALENCE (AAROW(4),ROVSPL)	EQVREAL	10
6	EQUIVALENCE (EPV(2),EPD)	EQVREAL	11
7	REAL KD,KDODRSQ,KDODZSQ,KIJ,KV,KVODRSQ,KVODZSQ,NUV,NUV3	EQVREAL	12
8	CALL GETO (4LKJBN,JNM;	KACHINA	6
9	CALL DATE1 (D1)	KACHINA	7
10	CALL CLOCK1 (C1)	KACHINA	8
11	NQ = 19	KACHINA	9
12	10 READ 100, THAR,JBAR,DR,DZ,A0,B0,ROVO,NUV,CDR,RPAR	KACHINA	10
13	IABRT = 0	KACHINA	11
14	IF (IBAR) 40,30,20	KACHINA	12
15	20 CALL OVERLAY (7LKACHFIL,1,0,0)	KACHINA	13
16	IF (IABRT.NE.0) GO TO 10	KACHINA	14
17	30 CALL OVERLAY (7LKACHFIL,2,0,0)	KACHINA	15
18	GO TO 10	KACHINA	16
19	40 CALL EMPTY	KACHINA	17
	C	KACHINA	18
20	100 FORMAT (2I4,8F8,3)	KACHINA	19
21	END	KACHINA	20



KIJ	-R	4EQ	7RL	
KV	-R	3CO	7RL	
KVGDZSG	-R	3CO	7RL	
KVGDZSG	-R	3CO	7RL	
NG	-I	3CO	11=	
NUV	-R	3CO	7RL	12RD
NUV3	-R	3CO	7RL	
OUT	-R	1AG	1AG	
OVERLAY	-	1SSU	17SU	
ROV0	-R	3CO	12RD	
RPAR	-R	3CO	12RD	





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1	SUBROUTINE LOOP	KACHINA	21
2	COMMON /KSB/ AAL(1),AAROW(988)	KOM	2
3	COMMON /KSC/ AA(1),AASC(25676),AKINFI,A0,BDTODR,BDTODZ,	KOM	3
1	BD1,BDZ,BINF,BOUT,BV1,HV1GM11,BV2,BV2GM12,	KOM	4
2	B0,CDR,COLOR(3),C1,DR,DR02,DRSQ,DT,DT0(10),	KOM	5
2	DTOC(10),DTODR,DTODZ,DTQ2,DTPOS,DZ,DZQ2,	KOM	6
3	DZSQ,D1,EM10,EM3,EM6,EPS,EPV(2),EP9,EP10,EP20,	KOM	7
3	FIBAR,FXL,FXR,FIYB,FIYT,FJBAR,G,GAM1,GAM2,GDT,	KOM	8
4	GGM11,GGM12,GM11,GM12,I,TABRT,TALL,IBAR,IDTO,IJ,	KOM	9
5	IJM,IJP,IP1,IP2,ISPR,IXL,IXR,IYR,IYT,J,JBAR,JNM,JP1,	KOM	10
6	JP2,JRTGID,JTOP,JX1,JX2,JX3,J2,J3,KD,KDQRSQ,	KOM	11
7	KDOZSQ,KV,KVQRSQ,KVOZSQ,LCM,LPR,MUSTPR,	KOM	12
8	MUSTHQ,NAME(8),NCYC,NLC,NPTOT,NQ,NQ1,NQ12,	KOM	13
9	NQL,NQ2,NQ2L,NSC,NUMIT,NUMRO,NUMTD,NUV,	KOM	14
1	NUV3,NVAP,OMHAS,OMBSP,OHF,OMRO,R,RCONT(66),RDR,	KOM	15
1	RDRSQ,RDT,RDZ,HDZSQ,RJ(34),RIPAR,RIRJB,MIP(34),	KOM	16
2	RJBAR,ROL,R02,HOVPIN,ROVPIN1,ROVD,RPAR,RPCDR,RPCOF,	KOM	17
3	RRI(34),RRIP(34),RRIDR(34),RROI,RRO2,RZDR,RZDZ,	KOM	18
4	SIEVIN,SOMO,T,THIN,THO,TLMD,TOP,TOUT,TWFIN,	KOM	19
5	TZUMD,VOL(34),VOLR(34),VVIN,XCONV,XL,XP(4000),XR,	KOM	20
6	YR,YCONV,YP(4000),YT,ZZ	KOM	21
4	IJP = IJP + NQ2	KACHINA	23
5	IJ = IJ + NQ2	KACHINA	24
6	IJM = IJM + NQ2	KACHINA	25
7	RETURN	KACHINA	26
8	ENTRY START	KACHINA	27
9	IJP = JX3	KACHINA	28
10	IJ = JX2	KACHINA	29
11	IJM = JX1	KACHINA	30
12	RETURN	KACHINA	31
12	ENTRY DONE	KACHINA	32
14	RETURN	KACHINA	33
15	ENTRY RIROW	KACHINA	34
16	JJ = (J-1)*NQI + 1	KACHINA	35
17	RETURN	KACHINA	36
18	ENTRY SETIJ	KACHINA	37
19	IJ = JJ + (I-1)*NQ	KACHINA	38
20	RETURN	KACHINA	39
21	ENTRY WIROW	KACHINA	40
22	RETURN	KACHINA	41
23	ENTRY LCMFLG	KACHINA	42
24	LCM = 0	KACHINA	43
25	RETURN	KACHINA	44
26	ENTRY RIJP2	KACHINA	45
27	KK = (J+1)*NQI	KACHINA	46
28	DO 299 K=1,NQI	KACHINA	47
29	299 AAROW(K) = AASC(KK,K)	KACHINA	48
30	RETURN	KACHINA	49
31	ENTRY RPARU	KACHINA	50
32	IJ = NQI*(J-1)	KACHINA	51
33	RETURN	KACHINA	52
34	ENTRY RPARV	KACHINA	53
35	IJ = NQI*(J-1)	KACHINA	54
36	RETURN	KACHINA	55
37	END	KACHINA	56

SINGLY REFERENCED VARIABLES

AA	()R	3C0	DT0	()R	3C0	FJ9AR	-R	3C0	JP2	-I	3C0	NQL	-I	3C0	RIJP2	=	26EN	SQ40	-R	3C0
AA1	()R	2C0	DT0C	()R	3C0	G	-R	3C0	JRIGID	-I	3C0	NQ2L	-I	3C0	RIP	()R	3C0	START	-	8EN
AKINFI	-R	3C0	DT0DR	-R	3C0	GAM1	-R	3C0	JTOP	-I	3C0	NSC	-I	3C0	RIBAR	-R	3C0	T	-R	3C0
A0	-R	3C0	DT0DZ	-R	3C0	GAM2	-R	3C0	J2	-I	3C0	NUMIT	-I	3C0	RLPIN	-R	3C0	THIN	-R	3C0
BDTODR	-R	3C0	DT0Z	-R	3C0	GDT	-R	3C0	J3	-I	3C0	NUMRO	-I	3C0	ROV N1	-R	3C0	TH0	-R	3C0
BDTODZ	-R	3C0	DTPOS	-R	3C0	GGM11	-R	3C0	KD	-I	3C0	NUMTD	-I	3C0	ROV0	-R	3C0	TLTMD	-R	3C0
BD1	-R	3C0	DZ	-R	3C0	GGM12	-R	3C0	KD0DRSQ	-I	3C0	NUV	-I	3C0	RO1	-R	3C0	TOP	-R	3C0
BD2	-R	3C0	DZSQ	-R	3C0	GM11	-R	3C0	KD0DZSQ	-I	3C0	NUV3	-I	3C0	RO2	-R	3C0	TOUT	-R	3C0
BINF	-R	3C0	0ZSQ	-R	3C0	GM12	-R	3C0	KSB	-	2CN	NVAP	-I	3C0	RPAR	-R	3C0	TWFIN	-R	3C0
BOUT	-R	3C0	D1	-R	3C0	IARAT	-I	3C0	KSC	-	3CN	OMBAS	-R	3C0	RPARU	-	31EN	TZ0MD	-R	3C0
BV1	-R	3C0	EM10	-R	3C0	IALL	-I	3C0	KV	-I	3C0	OMBSP	-R	3C0	RPARV	-	34EN	VOL	()R	3C0
BV1GM11	-R	3C0	EM3	-R	3C0	IBAR	-I	3C0	KV0DRSQ	-I	3C0	OMP	-R	3C0	RPCDR	-R	3C0	VOLR	()R	3C0
BV2	-R	3C0	EM6	-R	3C0	IDT0	-I	3C0	KV0DZSQ	-I	3C0	OMRO	-R	3C0	RPCOF	-R	3C0	VVIN	-R	3C0
BV2GM12	-R	3C0	EPS	-R	3C0	IP1	-I	3C0	LCMFLG	-	23EN	R	-R	3C0	RR1	()R	3C0	W1ROW	-	21EN
B0	-R	3C0	EPV	()R	3C0	IP2	-I	3C0	LOOP	-	15U	RCONT	()R	3C0	RR1DR	()R	3C0	XCONV	-R	3C0
CDR	-R	3C0	EP10	-R	3C0	ISPR	-I	3C0	LPR	-I	3C0	ROR	-R	3C0	RRIP	()R	3C0	XL	-R	3C0
COLOUR	()R	3C0	EP20	-R	3C0	IXL	-I	3C0	MUSTPR	-I	3C0	RDRSQ	-R	3C0	RH01	-R	3C0	XP	()R	3C0
C1	-R	3C0	EP9	-R	3C0	JXR	-I	3C0	MUSTRO	-I	3C0	ROT	-R	3C0	RR07	-R	3C0	XR	-R	3C0
DONE	-	13EN	FIBAR	-R	3C0	IYB	-I	3C0	NAME	()I	3C0	RDZ	-R	3C0	R1ROW	-	15EN	YR	-R	3C0
DR	-R	3C0	FIXL	-R	3C0	IYT	-I	3C0	NCYC	-I	3C0	ROZSQ	-R	3C0	R2DR	-R	3C0	YCONV	-R	3C0
DR02	-R	3C0	FIXR	-R	3C0	JBAR	-I	3C0	NLC	-I	3C0	RI	()R	3C0	R2DZ	-R	3C0	YP	()R	3C0
DRSQ	-R	3C0	FIYB	-R	3C0	JNM	-I	3C0	NPT0T	-I	3C0	RIBAR	-R	3C0	SETIJ	-	18EN	YT	-R	3C0
DT	-R	3C0	FIYT	-R	3C0	JP1	-I	3C0	NQT2	-I	3C0	RIBJB	-R	3C0	SIEVIN	-R	3C0	Z7	-R	3C0

MULTIPLY-REFERENCED VARIABLES

290	=	28D0	29*																		
AAROW	()R	2C0	29*																		
AASC	()R	3C0	29																		
COMMON	-	2F	3F																		
ENTRY	-	8F	13F	15F	18F	21F	23F	26F	31F	34F											
I	-I	3C0	19																		
IJ	-I	3C0	5=	5	10=	19=	32=	35=													
IJM	-I	3C0	6=	6	11=																
IJP	-I	3C0	4=	4	0=																
J	-I	3C0	16	27	32	35															
JJ	-I	16=	19																		
JX1	-I	3C0	11																		
JX2	-I	3C0	10																		
JX3	-I	3C0	9																		
K	-I	28D0	29	29																	
KK	-I	27=	29																		
LCH	-I	3C0	24=																		
N0	-I	3C0	19																		
N01	-I	3C0	16	27	28D0	32	35														
NG2	-I	3C0	4	5	6																
RETURN	-	7F	12F	14F	17F	20F	22F	25F	30F	33F	36F										

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OVERLAY (KACHFIL+1.0)

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PROGRAM KASET

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2

PRINT 10

KASET 4

3

CALL SETUP

KASET 5

4

10

FORMAT (1H1\* SETUP\*)

KASET 6

5

END

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SINGLY REFERENCED VARIABLES

FORMAT - 4F KASET - 1SU PRINT - 2F SETUP - 3SU

MULTIPLY-REFERENCED VARIABLES

10 - 2PR \*

1	SUBROUTINE SETUP		
2	COMMON /K5B/ AAL(1),AAPOW(988)	KASET	8
3	COMMON /K5C/ AA(1),AASC(26676),AKNFT,A0,BUTODR,ROTDZ,	KOM	2
1	B01,BD2,BINF,BOU1,BV1,BV1GM1,BV2,BV2GM12,	KOM	3
2	B0,CDR,COLOUR(3),C1,DR,DR02,DRSQ,DT,DT0(10),	KOM	4
2	DTOC(10),DTODR,DTODZ,DT02,DTPOS,DZ,DZ02,	KOM	5
3	DZSQ,D1,EM10,EM3,EM6,EP5,EPV(2),EP9,EP10,EP20,	KOM	6
3	FJBAR,FXL,FXR,FIYB,FIYT,FJBAR,G,GAM1,GAM2,GDT,	KOM	7
4	GGM1,GGM2,GM1,GM2,I,IABRT,IALL,IBAR,IDTO,IJ,	KOM	8
5	IJM,IJP,IP1,IP2,ISPR,IXL,IXR,IYB,IYT,J,JBAR,JNM,JP1,	KOM	9
6	JP2,JRIGID,JTOP,JX1,JX2,JX3,J2,J3,KD,KODORSQ,	KOM	10
7	K00DZSQ,KV,KVODRSQ,KVODZSQ,LCM,LPR,MUSTPR,	KOM	11
8	MUSTRO,NAME(R),NCYC,NLC,NPTOT,NQ,NQ1,NQ12,	KOM	12
9	NOL,NQ2,NQ2L,NSC,NUMIT,NUMRO,NUMTD,NUV,	KOM	13
1	NUV3,NVAP,OMRAS,OMBSPL,OMP,OMRO,R,RCNT(66),RDR,	KOM	14
1	RDRSQ,RDT,RDZ,RDZSQ,RI(34),RIBAR,RIBJ,RIP(34),	KOM	15
2	RJBAR,ROL,RO2,ROVPIN,ROVPIN1,ROV0,RPAR,RPCOR,PCOF,	KOM	16
3	RR1(34),RPIP(34),RRIDR(34),RROL,RRO2,R2DR,R2DZ,	KOM	17
4	SIEVIN,SQMD,T,THIN,THC,TLIMD,TOP,TOUT,TWFIN,	KOM	18
5	TZOMD,VOL(34),VOLR(34),VVIN,XCONV,XL,XP(4000),XR,	KOM	19
6	YB,YCONV,YP(4000),YT,ZZ	KOM	20
4	EQUIVALENC (AASC(1),TH),(AASC(2),ROVPR1),(AASC(3),RODPR1),	KOM	21
1	(AASC(4),POVPR),(AASC(5),RODPR),(AASC(6),SIEV),	EQVREAL	2
2	(AASC(7),SIED),(AASC(8),P),(AASC(9),KIJ,OMBETA),	EQVREAL	3
3	(AASC(10),E,ROUTE,DTKR),(AASC(11),ROVTE,DTKT),	EQVREAL	4
4	(AASC(12),UV,ROUV),(AASC(13),UD,ROUD),	EQVREAL	5
5	(AASC(14),VV,ROVV),(AASC(15),VD,ROVD),	EQVREAL	6
6	(AASC(16),A,PA),(AASC(17),CG,ROVPRT,RODPRT,ROVPRIT),	EQVREAL	7
7	(AASC(18),PP,DPRT),(AASC(19),F)	EQVREAL	8
5	EQUIVALENC (AAHOW(4),ROVSPL)	EQVREAL	9
6	EQUIVALENC (EPV(2),EPD)	EQVREAL	10
7	REAL KD,KODORSQ,KODZSQ,KIJ,KV,KVODRSQ,KVODZSQ,NUV,NUV3	EQVREAL	11
8	DIMENSION TH(1),ROVPR1(1),RODPR1(1),ROVPR(1),RODPR(1),SIEV(1),	EQVREAL	12
1	SIED(1),P(1),KIJ(1),OMBETA(1),E(1),ROUTE(1),DTKR(1),	DIMEN	2
2	ROVTE(1),DTKT(1),UV(1),ROUV(1),UD(1),ROUD(1),VV(1),	DIMFN	3
3	POVV(1),VD(1),ROVD(1),A(1),RA(1),CG(1),ROVPRT(1),	DIMFN	4
4	RODPRT(1),ROVPRIT(1),PP(1),DPRT(1),F(1)	DIMFN	5
9	DIMENSION ROVSPL(1)	DIMFN	6
10	DATA PI / 3.1415 92653 58979 32384 626 /	DIMFN	7
11	DIMENSION IDCOMP(R),KMATS(4)	KASET	12
12	DATA KMATS /0B,1B,2B,3B/	KASET	13
13	CALL LCMFLG	KASET	14
14	READ 810, NAME	KASET	15
15	READ 810, IDCOMP	KASET	16
16	READ 820, OMP,OMHO,EP5,G,KV,KD,EPV(1),EPD,R	KASET	17
17	READ 830, R01,RO2,GAM1,GAM2,BV1,BV2,BD1,RD2	KASET	18
18	READ 835, JRIGID,I0T,THIN,ROVIN1,ROVIN2,SIEVIN,VVIN,ITOP	KASET	19
19	READ 840, T,DT,TZOMD,TLIMD,TWFIN,LPR,ISPR,(COLOUR(N),N=1,3)	KASET	20
20	READ 845, (DTC(N),N=1,10)	KASET	21
21	READ 845, (DTC(N),N=1,10)	KASET	22
22	KT = 9	KASET	23
23	ASSIGN 110 TO KRET	KASET	24
24	WRITE (KT,810) NAME	KASET	25
25	WRITE (KT,810) IDCOMP	KASET	26
26	WRITE (KT,850) IBAR,JBAR,DR,DZ,A0,B0,ROV0,NUV,CDR,RPAR	KASET	27
27	WRITE (KT,860) OMP,OMRO,EP5,G,KV,KD,EPV(1),EPD,R	KASET	28

28		WRITE (KT,870) R01,R02,GAM1,GAM2,BV1,BV2,BD1,BD2	KASET	30
29		WRITE (KT,875) JRI,IGID,IBOT,THIN,ROVIN1,ROVIN2,SIEVIN,VVIN,ITOP	KASET	31
30		WRITE (KT,880) T,DT,T20MD,TLIMD,TWFIN,LPR,ISPR,(COLOUR(N),N=1,3)	KASET	32
31		WRITE (KT,890) (DT0(N),N=1,10)	KASET	33
32		WRITE (KT,900) (DT0C(N),N=1,10)	KASET	34
33		GO TO KRET	KASET	35
34	11 <sup>n</sup>	IF (LPR.EQ.0) GO TO 120	KASET	36
35		KT = 12	KASET	37
36		ASSIGN 120 TO KRET	KASET	38
37		GO TO 100	KASET	39
38	12 <sup>n</sup>	IP1 = IBAR + 1	KASET	40
39		IP2 = IBAR + 2	KASET	41
40		JP1 = JBAR + 1	KASET	42
41		JP2 = JBAR + 2	KASET	43
42		NQ2 = NQ + NQ	KASET	44
43		NQI = NQ * IP2	KASET	45
44		NQI2 = NQI + NQI	KASET	46
45		NQL = NQ*(1-LCM)	KASET	47
46		NQ2L = NQL + NQL	KASET	48
47		IALL = JP2 * NQI	KASET	49
48		JX1 = 1 + NQ	KASET	50
49		J2 = 1 + NQI	KASET	51
50		JX2 = J2 + NQ	KASET	52
51		J3 = J2 + NQI	KASET	53
52		JX3 = J3 + NQ	KASET	54
53		FIBAR = FLOAT(IBAR)	KASET	55
54		FJBAR = FLOAT(JBAR)	KASET	56
55		RIBAR = 1. / FIBAR	KASET	57
56		RJBAR = 1. / FJBAR	KASET	58
57		RIBJB = RIBAR * RJBAR	KASET	59
58		NSC = LOCF(ZZ) - LOCF(AA) * 1	KASET	60
59		NLC = LOCF(AA1(JP2*NQI)) - LOCF(AA1) * 1	KASET	61
60		IOTO = 1	KASET	62
61		TOUT = T + DT0(I)	KASET	63
62		DTPOS = DT	KASET	64
63		NCYC = NPTOT * NUMTD = 0	KASET	65
64		EM10 = 1.E-10	KASET	66
65		EM6 = 1.E-6	KASET	67
66		EM3 = 1.E-3	KASET	68
67		EP9 = 1.E+9	KASET	69
68		EP10 = 1.E+10	KASET	70
69		EP20 = 1.E+20	KASET	71
70		OMP = -OMP	KASET	72
71		AKINF1 = EP10	KASET	73
72		TH0 = 0.02	KASET	74
73		HR01 = 1. / R01	KASET	75
74		HR02 = 1. / R02	KASET	76
75		GM11 = GAM1 - 1.	KASET	77
76		GGM11 = GAM1 * GM11	KASET	78
77		BV1GM11 = BV1 * GM11	KASET	79
78		GM12 = GAM2 - 1.	KASET	80
79		GGM12 = GAM2 * GM12	KASET	81
80		BV2GM12 = BV2 * GM12	KASET	82
81		SQMD = (.5)**2	KASET	83
82		RPCOF = 1.5/RPAR**2	KASET	84
83		NUV3 = 3. * NUV	KASET	85

84	RPCDR = .25 * RPAR * CDR	KASET	86
85	RDR = 1. / DR	KASET	87
86	DR02 = .5 * CR	KASET	88
87	RDZ = 1. / DZ	KASET	89
88	DZ02 = .5 * DZ	KASET	90
89	RDRSQ = RDR * RDR	KASET	91
90	RDZSQ = RDZ * RDZ	KASET	92
91	DRSQ = DR * DR	KASET	93
92	DZSQ = DZ * DZ	KASET	94
93	OMBAS = .5 * OMP * DRSQ + DZSQ / (DRSQ + DZSQ)	KASET	95
94	R2DR = .5 * RDR	KASET	96
95	R2DZ = .5 * RDZ	KASET	97
96	KVODRSQ = KV * RDRSQ	KASET	98
97	KVODZSQ = KV * RDZSQ	KASET	99
98	KDODRSQ = KD * RDRSQ	KASET	100
99	KDODZSQ = KD * RDZSQ	KASET	101
100	RDT = 1. / DT	KASET	102
101	DT02 = .5 * DT	KASET	103
102	DTODR = DT * RDR	KASET	104
103	DTODZ = DT * RDZ	KASET	105
104	DTODZ = DT * RDZ	KASET	106
105	BDTODZ = B0 * DTODZ	KASET	107
106	GDT = G * DT	KASET	108
107	OMBSPL = OMBAS * RDT	KASET	109
108	VCON = 2. * PI * DR * DZ	KASET	110
109	RI(1) = -.5 * DR	KASET	111
110	RRI(1) = -2. * RDR	KASET	112
111	RRIDR(1) = RRI(1) * RDR	KASET	113
112	RIP(1) = RRI(1) * DR	KASET	114
113	DO 129 I=2,IP2	KASET	115
114	RI(I) = RI(I-1) * DR	KASET	116
115	RRI(I) = 1. / RI(I)	KASET	117
116	RRIDR(I) = RRI(I) * RDR	KASET	118
117	RIP(I) = RRI(I-1) * DR	KASET	119
118	VOL(I) = VCON * RI(I)	KASET	120
119	VOLR(I) = VCON * RIP(I)	KASET	121
120	RRIP(I) = 1. / RIP(I)	KASET	122
121	DO 139 J=2,JP2	KASET	123
122	RCONT(J) = 0.	KASET	124
123	IF (J.GE.JRIGID*2) RCONT(J) = 1.	KASET	125
124	CONTINUE	KASET	126
125	BOUT = BINF = 0.	KASET	127
126	IF (IBOT.EQ.1) BOUT = 1.	KASET	128
127	IF (IBOT.EQ.2) BINF = 1.	KASET	129
128	ROVPIN1 = THIN * ROVIN1	KASET	130
129	ROVPIN = THIN * (ROVIN1 + ROVIN2)	KASET	131
130	ITOP = ITOP	KASET	132
131	JTOP = JP1 + ITOP	KASET	133
132	XR = FIBAR * DR	KASET	134
133	YT = FJBAR * DZ	KASET	135
134	XL = YB = 0.	KASET	136
135	F1YB = 916.	KASET	137
136	XD = XR / (YT - YB)	KASET	138
137	YY = 0.	KASET	139
138	IF (XD.LE.-.13556) YY = 1.	KASET	140
139	FIXL = AMAX1(0.,(S11.-.450.*XD)*YY)	KASET	141

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140		FIXR = (S11.*+50.*XD)*YY + 1022.*(1.-YY)	KASET	142
141		FIYT = 16.*YY + (916.-1022./XD)* (1.-YY)	KASET	143
142		XCONV = (FIXR-FIXL) / (XR-XL)	KASET	144
143		YCONV = (FIYT-FIYB) / (YT-YB)	KASET	145
144		IXL = FIXL	KASET	146
145		IXR = FIXR	KASET	147
146		IYB = FIYB	KASET	148
147		IYT = FIYT	KASET	149
148		NQM1 = NQ - 1	KASET	150
149		CALL START	KASET	151
150		GO 199 J=1,JP2	KASET	152
151		DO 189 I=1,IP2	KASET	153
152		KF = IJM - NQ	KASET	154
153		KL = KF + NQM1	KASET	155
154		DO 179 K=KF,KL	KASET	156
155	179	AASC(K) = 0.	KASET	157
156	189	IJM = IJM + NQ	KASET	158
157		CALL LOOP	KASET	159
158	199	IJM = IJM - NQ2L	KASET	160
159		CALL DONE	KASET	161
160		SROV1 = SROV2 = 0.	KASET	162
161	200	READ 910, NB, NR, NT, NL, RODPRI1, RODPRI2, ROV1, ROV2, SIEVI, SIEDI, NPUA	KASET	163
162		IF (NR.EQ.0) GO TO 300	KASET	164
163		PRINT 920, NB, NR, NT, NL, RODPRI1, RODPRI2, ROV1, ROV2, SIEVI, SIEDI, NPUA	KASET	165
164		IF (LPR.GT.0) WRITE (12,920) NB, NR, NT, NL, RODPRI1, RODPRI2, ROV1, ROV2, SIEVI, SIEDI, NPUA	KASET	166
165		1 SROV1 = SROV1 + ROV1	KASET	167
166		SROV2 = SROV2 + ROV2	KASET	168
167		NB2 = NB * 2	KASET	169
168		NR1 = NR + 1	KASET	170
169		NT1 = NT + 1	KASET	171
170		NL2 = NL + 2	KASET	172
171		TH1 = 1. - RODPRI1*RR01 - RODPRI2*RR02	KASET	173
172		IF (TH1.LT.0.) GO TO 400	KASET	174
173		ROVPR1 = TH1 * ROV1	KASET	175
174		ROVPR1 = TH1 * (ROV1+ROV2)	KASET	176
175		RODPR1 = RODPRI1 + RODPRI2	KASET	177
176		ROVPR12 = ROVPR1 - ROVPR11	KASET	178
177		PNI = SIEVI*(ROVPR11*BV1G111 + ROVPR12*BV2GM12) / (TH1*(ROVPR11*BV1 + ROVPR12*BV2)) * ROVPR1	KASET	179
178		1 DO 219 J=NB2,NT1	KASET	180
179		CALL RIROW	KASET	181
180		DO 202 I=NL2,NR1	KASET	182
181		CALL SETIJ	KASET	183
182		TH(IJ) = TH1	KASET	184
183		ROVPR1(IJ) = ROVPR11	KASET	185
184		ROVPR(IJ) = ROVPR1	KASET	186
185		RODPR1(IJ) = RODPRI1	KASET	187
186		RODPR(IJ) = RODPRI	KASET	188
187		SIEV(IJ) = SIEVI	KASET	189
188		SIED(IJ) = SIEDI	KASET	190
189		PIIJ) = PNI	KASET	191
190	209	IJ = IJ + NQ	KASET	192
191		CALL WIROW	KASET	193
192	219	CONTINUE	KASET	194
193		IF (NPUA.EQ.0) GO TO 200	KASET	195
			KASET	196
			KASET	197

194		FNB = FLOAT (NB)	KASET	198
195		FNR = FLOAT (NR)	KASET	199
196		FNT = FLOAT (NT)	KASET	200
197		FNL = FLOAT (NL)	KASET	201
198		WIDTH = FNR * FNL	KASET	202
199		HEIGHT = FNT * FNB	KASET	203
200		FNPUA = FLOAT(NPUA)	KASET	204
201		RODRAT = RODPRI1 / RODPRI	KASET	205
202		OFFSET = 0.	KASET	206
203		DO 299 NTYPE=1,3	KASET	207
204		GO TO (230,232,234) NTYPE	KASET	208
205	230	PNEFF = FNPUA * RODRAT*(1.-THI)	KASET	209
206		GO TO 240	KASET	210
207	232	PNEFF = FNPUA * (1.-RODRAT)*(1.-THI)	KASET	211
208		GO TO 240	KASET	212
209	234	PNEFF = FNPUA * THI	KASET	213
210	240	XNP = WIDTH*QSRT(PNEFF)	KASET	214
211		YNP = HEIGHT*XNP/WIDTH	KASET	215
212		NPX = XNP*.5*EM10	KASET	216
213		NPY = YNP*.5*EM10	KASET	217
214		IF (NPX*NPY.EQ.0) GO TO 299	KASET	218
215		XSPAC = WIDTH / FLOAT(NPX)	KASET	219
216		X1 = FNL * XSPAC*(1.5+.25*OFFSET)	KASET	220
217		YSPAC = HEIGHT / FLOAT(NPY)	KASET	221
218		Y1 = FNB * YSPAC*(1.5+.25*OFFSET)	KASET	222
219		KMAT = KMATS(NTYPE)	KASET	223
220		DO 289 J=1,NPY	KASET	224
221		XTE = X1	KASET	225
222		DO 279 I=1,NPX	KASET	226
223		NPTOT = NPTOT + 1	KASET	227
224		XP(NPTOT) = (XTE.A..N.3B) .0. KMAT	KASET	228
225		YP(NPTOT) = Y1	KASET	229
226	279	XTE = XTE + XSPAC	KASET	230
227	289	Y1 = Y1 + YSPAC	KASET	231
228	299	CONTINUE	KASET	232
229		GO TO 200	KASET	233
230	300	CALL START	KASET	234
231		DO 399 J=2,JP1	KASET	235
232		DO 389 I=2,IP1	KASET	236
233		IF (I.EQ.2) GO TO 330	KASET	237
234	310	IF (J.EQ.2) GO TO 335	KASET	238
235	315	IF (I.EQ.IP1) GO TO 340	KASET	239
236	320	IF (J.EQ.JP1) GO TO 345	KASET	240
237		GO TO 380	KASET	241
238	330	IN = IJ * NQ	KASET	242
239		KRET = 1	KASET	243
240		GO TO 350	KASET	244
241	335	IN = IJM	KASET	245
242		KRET = 2	KASET	246
243		TH(IN) = TH(IJ) * BINF*(THIN-TH(IJ))	KASET	247
244		ROVPR1(IN) = ROVPR1(IJ) * BINF*(ROVPR1IN-ROVPR1(IJ))	KASET	248
245		ROVPR(IN) = ROVPR(IJ) * BINF*(ROVPRIN-ROVPR(IJ))	KASET	249
246		SIEV(IN) = SIEV(IJ) * BINF*(SIEVIN-SIEV(IJ))	KASET	250
247		VV(IN) = BINF*VVIN	KASET	251
248		GO TO 360	KASET	252
249	340	IN = IJ * NQ	KASET	253



250		KRET = 3		
251		GO TO 350	KASET	254
252	345	IN = IJP	KASET	255
253		KRET = 4	KASET	256
254	350	TH(IN) = TH(IJ)	KASET	257
255		ROVPR1(IN) = ROVPR1(IJ)	KASET	258
256		RQVPR(IN) = RQVPR(IJ)	KASET	259
257		SIEV(IN) = SIEV(IJ)	KASET	260
258	360	RODPR1(IN) = RODPR1(IJ)	KASET	261
259		RDDPR(IN) = RDDPR(IJ)	KASET	262
260		SIEO(IN) = SIEO(IJ)	KASET	263
261		GO TO (310,315,320,380) KRET	KASET	264
262	380	IJP = IJP * NQ	KASET	265
263		IJM = IJM * NQ	KASET	266
264	389	IJ = IJ * NQ	KASET	267
265	399	CALL LOOP	KASET	268
266		CALL DONE	KASET	269
267		NVAP = 1	KASET	270
268		IF (SROV1.GT.0. *A, SROV2.EQ.0.) NVAP = 2	KASET	271
269		IF (SHOV1.GT.0. *A, SHOV2.GT.0.) NVAP = 3	KASET	272
270		PHINT 930, NPTOT	KASET	273
271		IF (LPR.GT.0) WRITE (12,930) NPTOT	KASET	274
272		RETURN	KASET	275
273	400	PRINT 940, TH1	KASET	276
274		IABRT = 1	KASET	277
275		RETURN	KASET	278
		C	KASET	279
276	810	FORMAT (8A10)	KASET	280
277	820	FORMAT (9F8.3)	KASET	281
278	830	FORMAT (8F8.3)	KASET	282
279	835	FORMAT (2I4,5F8.3,14)	KASET	283
280	840	FORMAT (5F8.3,2I4,3F4.1)	KASET	284
281	845	FORMAT (10F8.3)	KASET	285
282	850	FORMAT (3X*IRAR=*I4/3X*JRAR=*I4/5X*DR=*IPE12.5/5X*OZ=*E12.5/5X*A0=* 1*E12.5/5X*80=*E12.5/3X*ROV0=*E12.5/4X*NUUV=*E12.5/4X*COR=*E12.5/3X* 2RPAR=*E12.5)	KASET	287
283	860	FORMAT (4X*OMP=*IPE12.5/3X*OMRD=*E12.5/4X*FPS=*E12.5/6X*G=*E12.5/ 15X*KV=*E12.5/5X*KD=*E12.5/4X*EPV=*E12.5/4X*EPD=*E12.5/6X*R=*E12.5)	KASET	289
284	870	FORMAT (4X*RO1=*IPE12.5/4X*RO2=*E12.5/3X*GAM1=*E12.5/3X*GAM2=* 1E12.5/4X*8V1=*E12.5/4X*8V2=*E12.5/4X*8D1=*E12.5/4X*8D2=*E12.5)	KASET	291
285	875	FORMAT (* JRIGID=*I4/3X*IBOT=*I4/3X*THIN=*IPE12.5/* ROVIN1=*E12.5/ 1* ROVIN2=*E12.5/* SIEVIN=*E12.5/3X*VVIN=*E12.5/3X*ITOP=*I4)	KASET	293
286	880	FORMAT (6X*1=*IPE12.5/5X*DT=*E12.5/* T20MD=*E12.5/* TLIMD=*E12.5/ 1/* TWFIN=*E12.5/4X*LPR=*I4/3X*ISPR=*I4/* COLOUR(1-3)=* 2 3(0PF3,1, )	KASET	295
287	890	FORMAT (* DT0(1-10)=*5(IPE12.5,2X)/12X*5(E12.5,2X))	KASET	297
288	900	FORMAT (* DT0C(1-10)=*5(IPE12.5,2X)/12X*5(E12.5,2X))	KASET	298
289	910	FORMAT (4I4,6F8.3,14)	KASET	299
290	920	FORMAT (* NB=*I3* NR=*I3* NT=*I3* NL=*I3* RODPRI1=*IPE12.5* 1RODPR12=*E12.5* ROV1=*E12.5* ROV2=*E12.5/36X*SIEV1=*E12.5,4X*SIE 2V2=*E12.5* NPUA=*I4)	KASET	301
291	930	FORMAT (11I6* PARTICLES GENERATED. SETUP COMPLETED.)*	KASET	302
292	940	FORMAT (10X*NEGATIVE THETA,=*IPE12.5)	KASET	303
293		END	KASET	304
			KASET	305
			KASET	306
			KASET	307

## SINGLY REFERENCED VARIABLES

AMAX1	=	1395J	JNM	=	-I	3C0	LCMFLG	=	135U	NUMYT	=	-I	3C0	REAL	=	7F	SETUP	=	15U	
C1	=	-R	3C0	K5B	=	2CN	MUSTPR	=	-I	3C0	NUMRO	=	-I	3C0	R1ROW	=	179SU	W1ROW	=	191SU
D1	=	-R	3C0	K5C	=	3CN	MUSTRO	=	-I	3C0	QSORT	=	-	210SU	SETIJ	=	1Q1SU			

## MULTIPLY-REFERENCED VARIABLES

109	=	24*	37																	
110	=	23AS	34*																	
120	=	34	36AS	38*																
129	=	11300	120*																	
139	=	12100	124*																	
179	=	15400	155*																	
189	=	15100	156*																	
199	=	15800	158*																	
200	=	161*	193	229																
209	=	18000	190*																	
219	=	17800	192*																	
230	=	204	235*																	
232	=	204	207*																	
234	=	204	299*																	
240	=	20A	208	210*																
279	=	22200	226*																	
289	=	22100	227*																	
299	=	20300	214	228*																
300	=	152	230*																	
310	=	234*	261																	
315	=	235*	261																	
320	=	23A*	261																	
330	=	233	238*																	
335	=	234	241*																	
340	=	235	249*																	
345	=	236	252*																	
350	=	240	251	254*																
360	=	24A	250*																	
360	=	237	261	262*																
389	=	23200	264*																	
399	=	23100	265*																	
400	=	172	273*																	
810	=	1400	1580	244R	244R	276*														
820	=	1600	277*																	
830	=	1700	274*																	
835	=	1400	270*																	
840	=	1900	280*																	
845	=	2100	2140	281*																
850	=	26WR	282*																	
860	=	27WR	283*																	
870	=	28WR	284*																	
875	=	29WR	285*																	
880	=	30WR	286*																	
890	=	31WR	287*																	
900	=	32WR	288*																	
910	=	16100	289*																	
920	=	1A3PR	164WR	290*																
930	=	270PR	271WR	291*																
940	=	273PR	292*																	

A

(1)R 3EQ 80J



FIXR	-R	3C0	140#	142	145														
FIYR	-R	3C0	135#	143	146														
FIYT	-R	3C0	141#	143	147														
FJBAR	-R	3C0	54#	56	133														
FLOAT	-	535U	545U	1945U	1955U	1965U	1975U	2005U	2155U	2175U									
FNR	-R	164#	199	218															
FNL	-R	167#	198	216															
FNPQA	-R	290#	205	207	209														
FNR	-R	195#	198																
FNT	-R	196#	199																
FORNAT	-	276F	277F	278F	279F	281F	282F	283F	284F	285F	286F	287F	288F	289F	290F	291F	292F		
G	-R	3C0	16ND	27#R	106														
GAM1	-R	3C0	17ND	20#R	75	1													
GAM2	-R	3C0	17ND	28#R	7#	79													
GDT	-R	3C0	10A#																
GGM11	-R	3C0	76#																
GGM12	-R	3C0	70#																
GM11	-R	3C0	75#	76	77														
GM12	-R	3C0	7#	79	80														
HEIGHT	-R	199#	211	217															
I	-I	3C0	11300	114	114	115	115	116	116	117	117	118	118	119	119	120	120	15100	
IABRT	-I	3C0	22700	23200	233	235													
IALL	-I	3C0	47#																
IBAR	-I	3C0	26#R	38	39	53													
IBOT	-I	1ARD	29#R	126	127														
IDCOMP	(1)	110I	15RD	25#R															
IDTO	-I	3C0	60#																
IJ	-I	3C0	187	183	184	185	186	187	188	189	190	190	238	243	243	244	244	245	
IJM	-I	3C0	245	246	249	254	255	256	257	258	259	260	264#	264	243	244	244	245	
IJP	-I	3C0	157	156#	156	158#	158	241	263#	263									
IN	-I	238#	241#	243	244	245	246	247	249#	252#	254	255	256	257	258	259	260		
IP1	-I	3C0	38#	23200	235														
IP2	-I	3C0	39#	63	11300	15100													
ISPR	-I	3C0	19RD	30#R															
ITGP	-I	18RD	29#R	130	131														
IXL	-I	3C0	144#																
IXR	-I	3C0	145#																
IYB	-I	3C0	146#																
IYT	-I	3C0	147#																
J	-I	3C0	12100	122	123	123	15600	17800	22600	23100	234	236							
JBAR	-I	3C0	26#R	40	41	54													
JP1	-I	3C0	40#	131	23100	236													
JP2	-I	3C0	41#	47	56	12100	15600												
JRIGID	-I	3C0	18RD	29#R	123														
JTGP	-I	3C0	131#																
JX1	-I	3C0	48#																
JX2	-I	3C0	50#																
JX3	-I	3C0	52#																
J2	-I	3C0	49#	50	51														
J3	-I	3C0	51#	52															
K	-I	15400	155																
KD	-R	3C0	7#L	16RD	27#R	98	99												
KDDRS0	-R	3C0	7#L	98#															
KDDZS0	-R	3C0	7#L	99#															



RA	(R)	4E0	RD1							
RCONT	(R)	3C0	122=	123=						
RDR	-R	3C0	85=	89	86	94	102	110	111	116
RDRSO	-R	3C0	84=	96	98					
RDT	-R	3C0	100=	107						
RDZ	-R	3C0	H7=	90	90	95	104			
RDZSO	-R	3C0	90=	97	99					
READ	-	14F	15F	16F	17F	18F	19F	20F	21F	161F
RETURN	-	272F	275F							
RI	(R)	3C0	104=	114=	114	115	118			
RIJ3R	-R	3C0	55=	57						
RIJ3B	-R	3C0	57=							
RIJ	(R)	3C0	112=	117=	117	119	120			
RJ3AR	-R	3C0	56=	57						
ROCPA	(R)	4E0	80I	186=	259=	259				
ROCPA1	-R	175=	18A	201						
ROCPA11	-R	161RD	163PR	164WR	171	175	185	201		
ROCPA12	-R	161RD	163PR	164WR	171	175				
ROCPAT	(R)	4E0	RD1							
ROCPA1	(R)	4E0	RD1	185=	258=	258				
ROCPAT	-R	201=	205	207						
ROLD	(R)	4E0	RD1							
ROUTE	(R)	4E0	RD1							
ROV	(R)	4E0	RD1							
ROV3	(R)	4E0	RD1							
ROVIN1	-R	18RD	29WR	128	129					
ROVIN2	-R	18RD	29WR	129						
ROVIN	-R	3C0	129=	245						
ROVIN1	-R	3C0	128=	245						
ROVPR	(R)	4E0	RD1	184=	245=	245	245	256=	266	
ROVPR1	-R	174=	176	177	184					
ROVPR11	-R	173=	176	177	177	183				
ROVPR12	-R	176=	177	177						
ROVPR1	(R)	4E0	RD1							
ROVPR1	(R)	4E0	RD1	183=	244=	244	244	255=	255	
ROVPR1T	(R)	4E0	RD1							
ROVSP1	(R)	5E9	RD1							
ROVTE	(R)	4E0	RD1							
ROVJ	(R)	4E0	RD1							
ROV3	-R	3C0	26WR							
ROV1	-R	161RD	163PR	164WR	165	173	174			
ROV2	-R	161RD	163PR	164WR	166	174				
RO1	-R	3C0	17RD	28WR	73					
RO2	-R	3C0	17RD	28WR	74					
RPAR	-R	3C0	26WR	U2	84					
RPCDR	-R	3C0	84=							
RPCOF	-R	3C0	82=							
RR1	(R)	3C0	110=	111	115=	116				
RR1DR	(R)	3C0	111=	116=						
RR1P	(R)	3C0	112=	120=						
RR01	-R	3C0	73=	171						
RR02	-R	3C0	74=	171						
RRDR	-R	3C0	94=							
RR0Z	-R	3C0	95=							
SIED	(R)	4E0	RD1	188=	260=	260				
SIED1	-R	161RD	163PR	164WR	188					



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OVERLAY (KACHFIL,2,0)

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1 OVERLAY (KACHFIL,2,0)

KACHYDR 2

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PROGRAM KACHYDR

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1 PROGRAM KACHYDR  
2 PRINT 10  
3 CALL HYDRO  
4 10 FORMAT (\* HYDRD\*)  
5 END

KACHYDR 3  
KACHYDR 4  
KACHYDR 5  
KACHYDR 6  
KACHYDR 7

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PROGRAM KACHYDR

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SINGLY REFERENCED VARIABLES

FORMAT - 4F HYDRO - 3SU KACHYDR - 1SU PRINT - 2F

MULTIPLY-REFERENCED VARIABLES

10 - 2PR 4\*



1	SUBROUTINE HYDRO		
2	COMMON /KSB/	A41(1),AAROW(98R)	KACHYDR 8
3	COMMON /KSC/	AA(1),AASC(26676),AKINFI,A0,BNTOUR,HDODZ, HD1,BD2,BTWF,BOUT,RV1,RV1GM1,BV2,BV2GM12, B0,C0Q,CULOUR(3),C1,DR,DR02,DRSQ,DT,DT0(10), DT0C(I0),DTODR,DTODZ,DT02,DTPOS,DZ,DZ02, DZSQ,D1,EM1,EM3,EM6,EPS,EPV(2),EP9,EP10,EP20, FJBAR,FXL,FXR,FIYB,FIYT,FJBAR,G,GAM1,GAM2,GDT, GGM1,GGM12,GM11,GM12,I,IABRT,IALL,IHAR,IT0,IJ, IJM,IJP,I21,I22,ISPR,IXL,IXR,IYB,IYT,J,JBAR,JNM,JP1, JP2,JRTGID,JTOP,JX1,JX2,JX3,J2,J3,KD,KDORSQ, KQDZSQ,KV,KVODRSQ,KVODZSQ,LCM,LPR,MUSTPR, MUSTRO,NAME(8),NCYC,NLC,NPTOT,NO,NQI,NQI2, NQL,NQ2,NQ2L,NSC,NUMIT,NUMRO,NUMTD,NUV, NUV3,NVAP,OMBAS,OMBSP,OMR,OMRO,R,RCOAT(66),RDR, RDRSQ,ROD,ROZ,ROZSQ,RI(34),RIHAR,RIHAR,RI(34), RJBAR,RO1,RO2,ROVPIN,ROVPIN1,ROVD,RPAR,RPCDR,RPCOF, RRI(34),RRIP(34),RRINR(34),RRO1,RRO2,R2DR,R2DZ, SIEVIN,SQMD,T,TMIN,TH0,TLJMD,TOP,TOUT,TWFIN, T2MD,VOL(34),VOLH(34),VVIN,XCONV,XL,XP(4000),XR, YB,YCONV,YP(4000),YT,ZZ	KOM 2 KOM 3 KOM 4 KOM 5 KOM 6 KOM 7 KOM 8 KOM 9 KOM 10 KOM 11 KOM 12 KOM 13 KOM 14 KOM 15 KOM 16 KOM 17 KOM 18 KOM 19 KOM 20 KOM 21
4	EQUIVALENCE	(AASC(1),TH),(AASC(2),ROVPR1),(AASC(3),RODPR1), (AASC(4),ROVPR),(AASC(5),RODPR),(AASC(6),SIEV), (AASC(7),STED),(AASC(8),P),(AASC(9),KIJ,OMBETA), (AASC(10),E,ROUTE,DTKR),(AASC(11),ROVTE,DTKT), (AASC(12),UV,ROUV),(AASC(13),UD,ROUD), (AASC(14),VV,ROVV),(AASC(15),VD,ROVD), (AASC(16),A,RA),(AASC(17),CQ,ROVPRT,RODPRT,ROVPRIT), (AASC(18),PP,OPRT),(AASC(19),F)	EQVREAL 2 EQVREAL 3 EQVREAL 4 EQVREAL 5 EQVREAL 6 EQVREAL 7 EQVREAL 8 EQVREAL 9
5	EQUIVALENCE	(AAROW(4),ROVSPL)	EQVREAL 10
6	EQUIVALENCE	(EPV(2),EPD)	EQVREAL 11
7	REAL	KN,KDORSQ,KDORSQ,KIJ,KV,KVODRSQ,KVODZSQ,NUV,NUV3	EQVREAL 12
8	DIMENSION	TH(1),ROVPR1(1),ROVPR(1),RODPR(1),SIFV(1), SIFD(1),P(1),KIJ(1),OMBETA(1),E(1),ROUTE(1),DTKR(1), ROVTE(1),DTKT(1),UV(1),ROUV(1),UD(1),ROUD(1),VV(1), ROVV(1),VD(1),ROVD(1),A(1),RA(1),CQ(1),ROVPRT(1), RODPRT(1),ROVPRIT(1),PP(1),OPRT(1),F(1)	DIMEN 2 DIMEN 3 DIMEN 4 DIMEN 5 DIMEN 6
9	DIMENSION	ROVSPL(1)	DIMEN 7
10	DIMENSION	THTAB(34),RODITAR(34),SIEVTAB(34),SIEDTAB(34), THTET(1),RODT(1),PVDENT(1),TERMIT(1),TERM2T(34), IX(1),IX2(1),IY1(1),IY2(1),X1(4),Y1(4),CON(11), SPSUNS(20),KMATS(4),IDPP(2,3),ICHARS(3),VELMX(2), TUVV(2,2),IDCON(2,10)	KACHYDR 12 KACHYDR 13 KACHYDR 14 KACHYDR 15 KACHYDR 16
11	EQUIVALENCE	(THTAB,IX1),(THTAB,IX2),(THTAB(3),IY1), (THTAB(4),IY2),(THTAB(5),X1),(THTAB(9),Y1), (THTAB(13),CON),(THTAB,THTET),(RODITAR,RODT), (SIEVTAB,PVDENT),(SIEDTAB,TERMIT)	KACHYDR 17 KACHYDR 18 KACHYDR 19 KACHYDR 20
12	EQUIVALENCE	(RODT,SPSUNS),(RODT(1),STH),(RODT(2),SMOMR), (RODT(3),SMOMZ),(RODT(4),SMOMZD),(RODT(5),SMOMZ), (RODT(6),SHV1),(RODT(7),SMD1),(RODT(8),SINTEV), (RODT(9),SINTED),(RODT(10),SINTE),(RODT(11),SMV2), (RODT(12),SMD2),(RODT(13),SKEV),(RODT(14),SKED), (RODT(15),SKE),(RODT(16),SMV),(RODT(17),SMD), (RODT(18),SEV),(RODT(19),SED),(RODT(20),SE)	KACHYDR 21 KACHYDR 22 KACHYDR 23 KACHYDR 24 KACHYDR 25 KACHYDR 26
13	DATA	KMATS /08,1H,2B,3B/	KACHYDR 27
14	DATA	IDPP /16H(* DROPLETS, 1*),16H(* DROPLETS, 2*),	KACHYDR 28 KACHYDR 29

	1	16H(* VAPOR *)/			
15		DATA ICHARS /16,63,42/			KACHYDR 30
16		DATA IDVV /14H(* VAPOR, *) ,14H(* DROPLETS,*)/			KACHYDR 31
17		DATA IDCON /16H(* VOID FRACTN*), 16H(* RHO-V PR.,1*),			KACHYDR 32
	1	16H(* RHO-D PR.,1*), 16H(* RHO-V PRIME*),			KACHYDR 33
	2	16H(* RHO-D PRIME*), 14H(* SIE-VAPOR*),			KACHYDR 34
	3	14H(* SIE-DROPS*), 13H(* PRESSURE*),			KACHYDR 35
	4	13H(* DRAG (K)*), 15H(* ENERGY (E)*)/			KACHYDR 36
18		DATA TOLD,T2 /0.,0./			KACHYDR 37
19		CALL SECOND (TBASE)			KACHYDR 38
20		T1 = TBASE			KACHYDR 39
21		CALL GETO (4LKTLM,11)			KACHYDR 40
22		TLIM = 11			KACHYDR 41
23		IF (IBAR.EQ.0) GO TO 270			KACHYDR 42
24		TLIM = TLIM*27.5E-9 + 40. + (1.-TLIMD)*EPIV			KACHYDR 43
25	100	CONTINUE			KACHYDR 44
	C	CALC. OPTIONAL E ARRAY HERE = CHEMICAL OR NUCLEAR ENERGY.			KACHYDR 45
26		TOLD = T2			KACHYDR 46
27		CALL SECOND (T2)			KACHYDR 47
28		XX = (T2-TOLD)*RIBJH			KACHYDR 48
29		PRINT 4120, T,NCYC,DT,T2,XX,NUMIT,MUSTPR,NUMRO,MUSTRO			KACHYDR 49
30		IF (LPR.GT.0) WRITE (12,4120) T,NCYC,DT,T2,XX,NUMIT,MUSTPR,NUMRO,			KACHYDR 50
		MUSTRO			KACHYDR 51
31		CALL EMPTY			KACHYDR 52
32		ASSIGN 120 TO KROUT			KACHYDR 53
33		IF (T*EM10.GE.TOUT) GO TO 210			KACHYDR 54
34		IF (NCYC.LE.1) GO TO 300			KACHYDR 55
35		IF (LSPR.EQ.2) GO TO 970			KACHYDR 56
36	120	IF (T2-T1.GE.1200. *A. T20MD.GT.EM10) GO TO 220			KACHYDR 57
37		IF (T2-TBASE.GE.TLIM) GO TO 230			KACHYDR 58
38	130	IF (T.GE.TWFIN) RETURN			KACHYDR 59
39		NCYC = NCYC + 1			KACHYDR 60
40		IF (LPR.EQ.0 + 0. NCYC.LE.10) GO TO 150			KACHYDR 61
41		VELMX(1) = VELMX(2) = EM10			KACHYDR 62
42		CALL START			KACHYDR 63
43		DO 149 J=1,JPI			KACHYDR 64
44		DO 139 I=2,IPI			KACHYDR 65
45		VELMX(1) = AMAX1(VELMX(1),ABS(VV(IJM)),ABS(UD(IJM)))			KACHYDR 66
46		VELMX(2) = AMAX1(VELMX(2),ABS(VV(IJM)),ABS(VD(IJM)))			KACHYDR 67
47	139	IJM = IJM + NQ			KACHYDR 68
48	149	CALL LOOP			KACHYDR 69
49		DTPOS = 0.1*AMINI(DR/VELMX(1)+DZ/VELMX(2))			KACHYDR 70
50	150	DT = DTPOS			KACHYDR 71
51		IF (T+DT.GT.TOUT) DT = TOUT - T			KACHYDR 72
52		T = T + DT			KACHYDR 73
53		RDT = 1. / DT			KACHYDR 74
54		DTDZ = .5 * DZ			KACHYDR 75
55		DTGDR = DT * RDP			KACHYDR 76
56		RDTGDR = RDT * DTGDR			KACHYDR 77
57		DTDZ = DT * RDZ			KACHYDR 78
58		RDTDZ = RDT * DTDZ			KACHYDR 79
59		GDT = G * DT			KACHYDR 80
60		DMBSPL = DMBS * RDT			KACHYDR 81
61		GO TO 1000			KACHYDR 82
62	210	TOUT = TOUT + DT*(1+DTD)			KACHYDR 83
63		IF (T*EM10.LT.DTDC(IDT0)) GO TO 300			KACHYDR 84
					KACHYDR 85

64		TOUT = DTOC(IDTO) * DTO(IDTO * 1)	KACHYDR	86
65		IDTO = IDTO * 1	KACHYDR	87
66		GO TO 300	KACHYDR	88
67	220	T1 = T2	KACHYDR	89
68		ASSIGN 130 TO KRET	KACHYDR	90
69		GO TO 250	KACHYDR	91
70	230	ASSIGN 290 TO KRET	KACHYDR	92
71	250	PRINT 4000, NUMTD, T, NCYC	KACHYDR	93
72		IF (LPR.GT.0) WRITE (12,4000) NUMTD, T, NCYC	KACHYDR	94
73		WRITE (8) (AA(N), N=1, NSC)	KACHYDR	95
74		IF (LCM.EQ.1) WRITE (8) (AA1(N), N=1, NLC)	KACHYDR	96
75		CALL DATAREL (5LFSF78)	KACHYDR	97
76		CALL AFSREL (3LQUT)	KACHYDR	98
77		CALL AFSREL (4LFILM)	KACHYDR	99
78		NUMTD = NUMTD * 1	KACHYDR	100
79		GO TO KRET	KACHYDR	101
80	270	REWIND 7	KACHYDR	102
81		JTD = JBAR	KACHYDR	103
82		JNSC = LOCF(ZZ) - LOCF(AA) * 1	KACHYDR	104
83		READ(7) (AA(N), N=1, JNSC)	KACHYDR	105
84		IF (LCM.EQ.1) READ(7) (AA1(N), N=1, NLC)	KACHYDR	106
85		IF (JTD.NE.NUMTD) GO TO 280	KACHYDR	107
86		CALL AFSREL (5LFSF77)	KACHYDR	108
87		NUMTD = NUMTD * 1	KACHYDR	109
88		TLIM = TLIM*27.5E-9 - 40. + (1.-TLIM)*EP10	KACHYDR	110
89		PRINT 4010, JTD	KACHYDR	111
90		PRINT 4020, NAME, T, NCYC	KACHYDR	112
91		IF (LPR.EQ.0) GO TO 130	KACHYDR	113
92		WRITE (12,4010) JTD	KACHYDR	114
93		WRITE (12,4020) NAME, T, NCYC	KACHYDR	115
94		GO TO 130	KACHYDR	116
95	280	PRINT 4030	KACHYDR	117
96		CALL AFSREL (5LFSF77)	KACHYDR	118
97	290	RETURN	KACHYDR	119
98	300	IF (NPTOT.EQ.0) GO TO 400	KACHYDR	120
99		NFR = 0	KACHYDR	121
100	310	CALL ADV (1)	KACHYDR	122
101		CALL COLOR (0.)	KACHYDR	123
102		CALL FRAME (IXL, IXR, IYT, IYB)	KACHYDR	124
103		IF (LPH.EQ.0) GO TO 320	KACHYDR	125
104		CALL LINCNT (59)	KACHYDR	126
105		WRITE (12,4040)	KACHYDR	127
106		WRITE (12,4050) JNM, D1, C1, NAME, T, NCYC	KACHYDR	128
107		DO 319 NP=1, NPTOT	KACHYDR	129
108		IXI = FIXL * (XP(NP)*DR-XL)*XCONV	KACHYDR	130
109		IYI = FIYB * (YP(NP)*DZ-YB)*YCONV	KACHYDR	131
110		L = (XP(NP).A, 38) * 1	KACHYDR	132
111	319	CALL PLT (IXI, IYI, ICHARS(L))	KACHYDR	133
112	320	DO 349 NTYPF=1, 3	KACHYDR	134
113		KMAT = KMATS(NTYPE)	KACHYDR	135
114		ICHR = ICHARS(NTYPE)	KACHYDR	136
115		CALL COLOR (COLOUR, NTYPE)	KACHYDR	137
116		IF (LPH.EQ.0) GO TO 330	KACHYDR	138
117		CALL ADV (1)	KACHYDR	139
118		CALL FRAME (IXL, IXR, IYT, IYB)	KACHYDR	140
119		CALL LINCNT (59)	KACHYDR	141

120		WRITE (12,1000) (1,NTYPE)	KACHYDR	142
121		WRITE (12,4050) JNM,DI,C1,NAME,T,NCYC	KACHYDR	143
122	330	DO 339 NP=1,NPTOT	KACHYDR	144
123		L = XP(NP) * A * 3E	KACHYDR	145
124		IF (L.NE.KMAT) GO TO 339	KACHYDR	146
125		IX1 = FIXL * (XP(NP)*DR-XL)*XCONV	KACHYDR	147
126		IY1 = FIYB * (YP(NP)*DZ-YB)*YCONV	KACHYDR	148
127		CALL PLT (IX1,IY1,1,CHAR)	KACHYDR	149
128	339	CONTINUE	KACHYDR	150
129	349	CONTINUE	KACHYDR	151
130		NFR = NFR * 1	KACHYDR	152
131		IF (NCYC*LPR.EQ.0 * A * NFR.LT.100) GO TO 310	KACHYDR	153
132		IF (LPR.EQ.0) GO TO KROUT	KACHYDR	154
133	400	VELMX(1) = VELMX(2) = 0.	KACHYDR	155
134		CALL START	KACHYDR	156
135		DO 419 J=2,JP1	KACHYDR	157
136		DO 409 I=2,IP1	KACHYDR	158
137		VELMX(1) = AMAX1(VELMX(1),ABS(UV(IJ)),ABS(VV(IJ)))	KACHYDR	159
138		VELMX(2) = AMAX1(VELMX(2),ABS(UV(IJ)),ABS(VV(IJ)))	KACHYDR	160
139	409	IJ = IJ * NQ	KACHYDR	161
140	419	CALL LOOP	KACHYDR	162
141		DO 449 NTYPE=1,2	KACHYDR	163
142		IF (VELMX(NTYPE).LT.EM10) GO TO 449	KACHYDR	164
143		DROU = DRO2 / VELMX(NTYPE)	KACHYDR	165
144		L = NTYPE - 1	KACHYDR	166
145		CALL ADV (1)	KACHYDR	167
146		CALL FRAME (IXL,IXR,IYT,IYB)	KACHYDR	168
147		CALL LINCNT (59)	KACHYDR	169
148		WRITE (12,1000) (1,NTYPE)	KACHYDR	170
149		WRITE (12,4060) VELMX(NTYPE)	KACHYDR	171
150		WRITE (12,4050) JNM,DI,C1,NAME,T,NCYC	KACHYDR	172
151		CALL START	KACHYDR	173
152		DO 439 J=2,JP1	KACHYDR	174
153		Y1 = (FLGAT(J)-1.5) * DZ	KACHYDR	175
154		IY1 = FIYB * (Y1-YB)*YCONV	KACHYDR	176
155		DO 429 I=2,IP1	KACHYDR	177
156		X1 = RI(I)	KACHYDR	178
157		X2 = X1 * (UV(IJ-NQ+L)+UV(IJ+L))*DROU	KACHYDR	179
158		Y2 = Y1 * (VV(IJ-NQ+L)+VV(IJ+L))*DROU	KACHYDR	180
159		IX1 = FIXL * (X1-XL)*XCONV	KACHYDR	181
160		IX2 = FIXL * (X2-XL)*XCONV	KACHYDR	182
161		IY2 = FIYB * (Y2-YB)*YCONV	KACHYDR	183
162		CALL DRV (IX1,IY1,IX2,IY2)	KACHYDR	184
163		CALL PLT (IX1,IY1,16)	KACHYDR	185
164		IJM = IJM * NQ	KACHYDR	186
165	429	IJ = IJ * NQ	KACHYDR	187
166	439	CALL LOOP	KACHYDR	188
167	449	CONTINUE	KACHYDR	189
168		IF (IBAR.EQ.1 * 0 * JBAR.EQ.1) GO TO 800	KACHYDR	190
169		DO 799 L=1,9	KACHYDR	191
170		LM1 = L - 1	KACHYDR	192
171		QMN = EP20	KACHYDR	193
172		QMX = -EP20	KACHYDR	194
173		CALL START	KACHYDR	195
174		DO 619 J=2,JP1	KACHYDR	196
175		DO 609 I=2,IP1	KACHYDR	197

176		CQ(IJ) = TH(IJ+LM)	KACHYDR	198
177		QMN = AMIN1(QMN+CQ(IJ))	KACHYDR	199
178		IF (CQ(IJ).LT.EP9) QMX = AMAX1(QMX,CQ(IJ))	KACHYDR	200
179	609	IJ = IJ + NQ	KACHYDR	201
180	619	CALL LOOP	KACHYDR	202
181		IF (LM1.NE.8) GO TO 640	KACHYDR	203
182		XX = QMX + .05*(QMX-QMN)	KACHYDR	204
183		CALL START	KACHYDR	205
184		DO 639 J=2,JP1	KACHYDR	206
185		DO 629 I=2,IP1	KACHYDR	207
186		IF (CQ(IJ).GE.EP9) CQ(IJ) = QMX = XX	KACHYDR	208
187	629	IJ = IJ + NQ	KACHYDR	209
188	639	CALL LOOP	KACHYDR	210
189		CALL DONE	KACHYDR	211
190	640	XX = QMX - QMN	KACHYDR	212
191		IF (XX.LT.EM10) GO TO 799	KACHYDR	213
192		DQ = .1*(XX+EM10)	KACHYDR	214
193		DO 649 IC=1,11	KACHYDR	215
194	649	CON(IC) = QMN + FLOAT(IC-1)*DQ	KACHYDR	216
195		IC = 11	KACHYDR	217
196		CALL ADV (1)	KACHYDR	218
197		CALL FRAME (IAL,IXR,IYT,IYB)	KACHYDR	219
198		CALL LINCNT (59)	KACHYDR	220
199		WRITE (12,IDCON(1,L))	KACHYDR	221
200		WRITE (12,4080) QMN,QMX,CON(1),CON(IC-1),DQ	KACHYDR	222
201		WRITE (12,4050) JNM,D1,C1,NAME,T,NCYC	KACHYDR	223
202		CALL START	KACHYDR	224
203		DO 789 J=2,JBAR	KACHYDR	225
204		Y1(1) = Y1(2) = DZ*(FLOAT(J)-1.5)	KACHYDR	226
205		Y1(3) = Y1(4) = Y1(1) * DZ	KACHYDR	227
206		DO 179 I=2,IBAR	KACHYDR	228
207		X1(1) = X1(3) = DR*(FLOAT(I)-1.5)	KACHYDR	229
208		X1(2) = X1(4) = X1(1) * DR	KACHYDR	230
209		IPJ = IJ + NQ	KACHYDR	231
210		IPJP = IJP + NQ	KACHYDR	232
211		DO 769 IK = 1,IC	KACHYDR	233
212		K1 = K2 = K3 = K4 = 0	KACHYDR	234
213		IF (CQ(IJ).LE.CON(IK)) K1 = 1	KACHYDR	235
214		IF (CQ(IPJ).LE.CON(IK)) K2 = 1	KACHYDR	236
215		IF (CQ(IJP).LE.CON(IK)) K3 = 1	KACHYDR	237
216		IF (CQ(IPJP).LE.CON(IK)) K4 = 1	KACHYDR	238
217		IF (K1*K2*K3*K4.NE.0 .OR. K1+K2+K3+K4.EQ.0) GO TO 769	KACHYDR	239
218		LL = 0	KACHYDR	240
219		IF (K1+K3.NE.1) GO TO 710	KACHYDR	241
220		IC1 = 1	KACHYDR	242
221		IC2 = 3	KACHYDR	243
222		IJ1 = IJ	KACHYDR	244
223		IJ2 = IJP	KACHYDR	245
224		ASSIGN 710 TO KR1	KACHYDR	246
225		GO TO 740	KACHYDR	247
226	710	IF (K1+K2.NE.1) GO TO 720	KACHYDR	248
227		IC1 = 1	KACHYDR	249
228		IC2 = 2	KACHYDR	250
229		IJ1 = IJ	KACHYDR	251
230		IJ2 = IPJ	KACHYDR	252
231		ASSIGN 720 TO KR1	KACHYDR	253

232		GO TO 740	KACHYDR	254
233	720	IF (K2+K4.NE.1) GO TO 730	KACHYDR	255
234		IC1 = 2	KACHYDR	256
235		IC2 = 4	KACHYDR	257
236		IJ1 = IPJ	KACHYDR	258
237		IJ2 = IPJP	KACHYDR	259
238		ASSIGN 730 TO KR1	KACHYDR	260
239		GO TO 740	KACHYDR	261
240	730	IF (K3+K4.NE.1) GO TO 769	KACHYDR	262
241		IC1 = 3	KACHYDR	263
242		IC2 = 4	KACHYDR	264
243		IJ1 = IJP	KACHYDR	265
244		IJ2 = IPJP	KACHYDR	266
245		ASSIGN 769 TO KR1	KACHYDR	267
246	740	LL = LL + 1	KACHYDR	268
247		XX = (CON(IK)-CQ(IJ1)) / (CQ(IJ2)-CQ(IJ1))	KACHYDR	269
248		IX1(LL) = FIXL * (X1(IC1)+XX*(X1(IC2)-X1(IC1))-XL)*XCONV	KACHYDR	270
249		IY1(LL) = FIYB * (Y1(IC1)+XX*(Y1(IC2)-Y1(IC1))-YB)*YCONV	KACHYDR	271
250		IF (LL.LT.2) GO TO KR1	KACHYDR	272
251		CALL DRV (IX1,IY1,IX2,IY2)	KACHYDR	273
252		IF (IK.EQ.J) CALL PLT (IX1,IY1,35)	KACHYDR	274
253		IF (IK.EQ.IC-1) CALL PLT (IX1,IY1,24)	KACHYDR	275
254		LL = 0	KACHYDR	276
255		IF (IJ2.EQ.IPJ) GO TO 720	KACHYDR	277
256	769	CONTINUE	KACHYDR	278
257		IJ = IPJ	KACHYDR	279
258	779	IJP = IPJP	KACHYDR	280
259		CALL LOOP	KACHYDR	281
260		IJ = IJ + NQL	KACHYDR	282
261	789	IJP = IJP + NQL	KACHYDR	283
262	799	CONTINUE	KACHYDR	284
263	800	ASSIGN 840 TO KRF	KACHYDR	285
264		KRP = KRF	KACHYDR	286
265		ASSIGN 889 TO KRFP	KACHYDR	287
266		GO TO (830,820,880) LPR	KACHYDR	288
267	820	ASSIGN 880 TO KRF	KACHYDR	289
268		ASSIGN 870 TO KRFP	KACHYDR	290
269	830	CALL LINCHT (64)	KACHYDR	291
270		CALL ADV (1)	KACHYDR	292
271		GO TO 860	KACHYDR	293
272	840	KRF = KRFP	KACHYDR	294
273		ASSIGN 889 TO KRP	KACHYDR	295
274		CALL START	KACHYDR	296
275		DO 899 J=1,JP2	KACHYDR	297
276		DO 889 I=1,IP2	KACHYDR	298
277		L = IJM = NQ	KACHYDR	299
278		GO TO (850,850,870) LPR	KACHYDR	300
279	850	WRITE (12,4090) I,J,TH(L),UV(L),VV(L),SIEV(L),ROVPR1(L),ROVPR(L),	KACHYDR	301
		1 DPR1(L),P(L),E(L),UD(L),VD(L),SIED(L),RODPR1(L),	KACHYDR	302
		2 RODPR(L),A(L),KIJ(L)	KACHYDR	303
280		LINESF = LINESF + 3	KACHYDR	304
281		IF (LINESF.LT.59) GO TO KRF	KACHYDR	305
282	860	CALL ADV (1)	KACHYDR	306
283		LINESF = 0	KACHYDR	307
284		WRITE (12,4050) JNM,D1,C1,NAME,T,NCYC	KACHYDR	308
285		WRITE (12,4100)	KACHYDR	309

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286		GO TO KRF				
287	870	PRINT 4090,	I,J,TH(L),UV(L),VV(L),SIEV(L),ROVPR1(L),ROVPR(L),	KACHYDR	310	
	1		DPRT(L),P(L),E(L),UD(L),VD(L),SIED(L),RODPR1(L),	KACHYDR	311	
	2		RODPR(L),A(L),KIJ(L)	KACHYDR	312	
288		LINESP = LINESP + 3		KACHYDR	313	
289		IF (LINESP.LT.54) GO TO KRF		KACHYDR	314	
290	880	PRINT 4110		KACHYDR	315	
291		LINESP = 0		KACHYDR	316	
292		PRINT 4050, JNM,D1,C1,NAME,T,NCYC		KACHYDR	317	
293		PRINT 4100		KACHYDR	318	
294		GO TO KRF		KACHYDR	319	
295	889	IJM = IJM + NQ		KACHYDR	320	
296		CALL LOOP		KACHYDR	321	
297	899	IJM = IJM - NQ2L		KACHYDR	322	
298	900	DO 909 I=1,20		KACHYDR	323	
299	909	SPSUMS(I) = 0.		KACHYDR	324	
300		CALL START		KACHYDR	325	
301		DO 929 J=2,JP1		KACHYDR	326	
302		DO 919 I=2,IP1		KACHYDR	327	
303		IPJ = IJ + NQ		KACHYDR	328	
304		IMJ = IJ - NQ		KACHYDR	329	
305		ROVVOL = ROVPR(IJ)*VOL(I)		KACHYDR	330	
306		RODVOL = RODPR(IJ)*VOL(I)		KACHYDR	331	
307		STM = STM + (1.-TH(IJ))*VOL(I)		KACHYDR	332	
308		SMV = SMV + ROVVOL		KACHYDR	333	
309		SMV1 = SMV1 + VOL(I)*ROVPR1(IJ)		KACHYDR	334	
310		SMV2 = SMV2 + VOL(I)*(ROVPR(IJ)-ROVPR1(IJ))		KACHYDR	335	
311		SMD = SMD + ROVVOL		KACHYDR	336	
312		SMD1 = SMD1 + VOL(I)*RODPR1(IJ)		KACHYDR	337	
313		SMD2 = SMD2 + VOL(I)*(RODPR(IJ)-RODPR1(IJ))		KACHYDR	338	
314		SMOMR = SMOMR + .5*VOLR(I)*(UV(IJ)*(ROVPR(IJ)+ROVPR(IPJ))		KACHYDR	339	
	1		+UD(IJ)*(RODPR(IJ)+RODPR(IPJ)))	KACHYDR	340	
315		ROVTEM = .5*VOL(I)*VV(IJ) * (ROVPR(IJ)+ROVPR(IPJ))		KACHYDR	341	
316		RODTEM = .5*VOL(I)*VD(IJ) * (RODPR(IJ)+RODPR(IPJ))		KACHYDR	342	
317		SMOMZV = SMOMZV + ROVTEM		KACHYDR	343	
318		SMOMZD = SMOMZD + RODTEM		KACHYDR	344	
319		SMOMZ = SMOMZ + ROVTEM + RODTEM		KACHYDR	345	
320		STIEV = ROVVOL*SIEV(IJ)		KACHYDR	346	
321		STIED = RODVOL*SIED(IJ)		KACHYDR	347	
322		SINTEV = SINTEV + STIEV		KACHYDR	348	
323		SINTED = SINTED + STIED		KACHYDR	349	
324		SINTE = SINTE + STIEV + STIED		KACHYDR	350	
325		STKEV = ROVVOL*.25*(UV(IJ)**2+UV(IJM)**2		KACHYDR	351	
	1		+VV(IJ)**2+VV(IJM)**2)	KACHYDR	352	
326		STKED = ROVVOL*.25*(UD(IJ)**2+UD(IJM)**2		KACHYDR	353	
	1		+VD(IJ)**2+VD(IJM)**2)	KACHYDR	354	
327		SKEV = SKEV + STKEV		KACHYDR	355	
328		SKED = SKED + STKED		KACHYDR	356	
329		SKE = SKE + STKEV + STKED		KACHYDR	357	
330		STEV = STIEV + STKEV		KACHYDR	358	
331		STED = STIED + STKED		KACHYDR	359	
332		SEV = SEV + STEV		KACHYDR	360	
333		SED = SED + STED		KACHYDR	361	
334		SE = SE + STEV + STED		KACHYDR	362	
335		IJM = IJM + NQ		KACHYDR	363	
336		IJP = IJP + NQ		KACHYDR	364	
				KACHYDR	365	

337	910	IJ = IPJ	KACHYDR	366
338	929	CALL LOOP	KACHYDR	367
339		IF (LPR.GT.0) WRITE (12,4130) T,NCYC,(SPSUMS(L),L=1,20)	KACHYDR	368
340		IF (LPR.GE.2) PRINT 4130, T,NCYC,(SPSUMS(L),L=1,20)	KACHYDR	369
341		CALL EMPTY	KACHYDR	370
342		GO TO KROUT	KACHYDR	371
343	1000	CALL START	KACHYDR	372
344		DO 1009 J=2,JP1	KACHYDR	373
345		DO 1079 I=2,IP1	KACHYDR	374
346		IPJ = IJ + NQ	KACHYDR	375
347		IMJ = IJ - NQ	KACHYDR	376
348		XIVL = BDTODR*UV(IMJ) + SIGN(A0,UV(IMJ))	KACHYDR	377
349		HPXIVL = .5 + XIVL	KACHYDR	378
350		HMXIVL = .5 - XIVL	KACHYDR	379
351		XIVR = BDTODR*UV(IJ) + SIGN(A0,UV(IJ))	KACHYDR	380
352		HPXIVR = .5 + XIVR	KACHYDR	381
353		HMXIVR = .5 - XIVR	KACHYDR	382
354		XIVB = BDTODZ*VV(IJM) + SIGN(A0,VV(IJM))	KACHYDR	383
355		HPXIVB = .5 + XIVB	KACHYDR	384
356		HMXIVB = .5 - XIVB	KACHYDR	385
357		XIVT = BDTODZ*VV(IJ) + SIGN(A0,VV(IJ))	KACHYDR	386
358		HPXIVT = .5 + XIVT	KACHYDR	387
359		HMXIVT = .5 - XIVT	KACHYDR	388
360		XIDL = BDTODR*UD(IMJ) + SIGN(A0,UD(IMJ))	KACHYDR	389
361		HPXIDL = .5 + XIDL	KACHYDR	390
362		HMXIDL = .5 - XIDL	KACHYDR	391
363		XIDR = BDTODR*UD(IJ) + SIGN(A0,UD(IJ))	KACHYDR	392
364		HPXIDR = .5 + XIDR	KACHYDR	393
365		HMXIDR = .5 - XIDR	KACHYDR	394
366		XIOB = BDTODZ*VD(IJM) + SIGN(A0,VD(IJM))	KACHYDR	395
367		HPXIOB = .5 + XIOB	KACHYDR	396
368		HMXIOB = .5 - XIOB	KACHYDR	397
369		XIDT = BDTODZ*VD(IJ) + SIGN(A0,VD(IJ))	KACHYDR	398
370		HPXIDT = .5 + XIDT	KACHYDR	399
371		HMXIDT = .5 - XIDT	KACHYDR	400
372		UVRR = UV(IJ)*RIP(I)	KACHYDR	401
373		UVRL = UV(IMJ)*RIP(I-1)	KACHYDR	402
374		UDRR = UD(IJ)*RIP(I)	KACHYDR	403
375		UDRL = UD(IMJ)*RIP(I-1)	KACHYDR	404
376		THIJ = TH(IJ)	KACHYDR	405
377		RR = 1. / ROVPR(IJ)	KACHYDR	406
378		RODPR(IJ) = RODPR(IJ)	KACHYDR	407
	1	+DTODR*RR(I)*(UDRL*(HPXIDL*RODPR(IJ)+HMXIDL*RODPR(IJ))	KACHYDR	408
	2	-UDRR*(HPXIDR*RODPR(IJ)+HMXIDR*RODPR(IJ)))	KACHYDR	409
	3	+DTODZ*(VD(IJM)*(HPXIOB*RODPR(IJM)+HMXIOB*RODPR(IJ))	KACHYDR	410
	4	-VD(IJ)*(HPXIDT*RODPR(IJ)+HMXIDT*RODPR(IJ)))	KACHYDR	411
379		RODPR(I) = RODPR(I)	KACHYDR	412
	1	+DTODR*RR(I)*(UDRL*(HPXIDL*RODPR(IJM)+HMXIDL*RODPR(IJ))	KACHYDR	413
	2	-UDRR*(HPXIDR*RODPR(IJ)+HMXIDR*RODPR(IJ)))	KACHYDR	414
	3	+DTODZ*(VD(IJM)*(HPXIOB*RODPR(IJM)+HMXIOB*RODPR(IJ))	KACHYDR	415
	4	-VD(IJ)*(HPXIDT*RODPR(IJ)+HMXIDT*RODPR(IJ)))	KACHYDR	416
380		THTE = 1. - RODPR1*RR01 - (RODPR(IJ)-RODPR1)*RR02	KACHYDR	417
381		IF (THTE.LT.TH0 .A. NCYC.GT.1) GO TO 1010	KACHYDR	418
382		ROVPR2 = ROVPR(IJ) - ROVPR1(IJ)	KACHYDR	419
383		A(IJ) = SIEV(IJ)*(ROVPR1(IJ)*BV1GM1 + ROVPR2*BV2GM12)	KACHYDR	420
	1	/ (THTE*(ROVPR1(IJ)*BV1 + ROVPR2*BV2))	KACHYDR	421



384	VEL = .25 * (UV(IJ)**2+UV(IMJ)**2+VV(IJ)**2+VV(IJM)**2)	KACHYDR	422
385	GAMTE = GGM11*ROVPR1(IJ)*RR + GGM12*(I.-ROVPR1(IJ)*RR)	KACHYDR	423
386	GIRDM = GAMTE*SIEV(IJ)*ROVPR1(IJ)*SQM0	KACHYDR	424
387	THTESQ = THTE * THTE	KACHYDR	425
388	VEL = VEL + P(IJ)*THTE*RR	KACHYDR	426
389	RMSQ = (VEL*THTESQ+(ROVPR(IJ)+RODPR(IJ))/GIROM) **2	KACHYDR	427
390	F(IJ) = 1. / (1.+10.*RMSQ)	KACHYDR	428
391	P(IJ) = F(IJ)*P(IJ) + (1.-F(IJ))*A(IJ)*ROVPR(IJ)	KACHYDR	429
392	VECVEL = .5*QSQR((UV(IJ)-UD(IJ)+UV(IMJ)-UD(IMJ))**2	KACHYDR	430
	1 + (VV(IJ)-VD(IJ)+VV(IJM)-VD(IJM))**2)	KACHYDR	431
393	THTERM = (1.-THTE) / THTESQ	KACHYDR	432
394	KIJ(IJ) = RPCDF*ROVPR(IJ)*THTERM*(NUV3*RPCDR*VECVEL)	KACHYDR	433
395	GO TO 1020	KACHYDR	434
396	1010 THTE = 0.	KACHYDR	435
397	A(IJ) = KIJ(IJ) = AKINFI	KACHYDR	436
398	1020 SIEVC = SIEV(IJ)	KACHYDR	437
399	SIEDC = SIED(IJ)	KACHYDR	438
400	TVC = SIEVC *ROVPR(IJ)	KACHYDR	439
	1 / (ROVPR1(IJ)*BV1 + (ROVPR(IJ)-ROVPR1(IJ))*BV2)	KACHYDR	440
401	TVL = SIEV(IMJ)*ROVPR(IMJ)	KACHYDR	441
	1 / (ROVPR1(IMJ)*BV1 + (ROVPR(IMJ)-ROVPR1(IMJ))*BV2)	KACHYDR	442
402	TVH = SIEV(IPJ)*ROVPR(IPJ)	KACHYDR	443
	1 / (ROVPR1(IPJ)*BV1 + (ROVPR(IPJ)-ROVPR1(IPJ))*BV2)	KACHYDR	444
403	TVB = SIEV(IJM)*ROVPR(IJM)	KACHYDR	445
	1 / (ROVPR1(IJM)*BV1 + (ROVPR(IJM)-ROVPR1(IJM))*BV2)	KACHYDR	446
404	TVT = SIEV(IJP)*ROVPR(IJP)	KACHYDR	447
	1 / (ROVPR1(IJP)*BV1 + (ROVPR(IJP)-ROVPR1(IJP))*BV2)	KACHYDR	448
405	TDC = SIEDC *RODPR(IJ)	KACHYDR	449
	1 / (RODPR1(IJ)*BD1 + (RODPR(IJ)-RODPR1(IJ))*BD2)	KACHYDR	450
406	TDL = SIED(IMJ)*RODPR(IMJ)	KACHYDR	451
	1 / (RODPR1(IMJ)*BD1 + (RODPR(IMJ)-RODPR1(IMJ))*BD2)	KACHYDR	452
407	TDR = SIED(IPJ)*RODPR(IPJ)	KACHYDR	453
	1 / (RODPR1(IPJ)*BD1 + (RODPR(IPJ)-RODPR1(IPJ))*BD2)	KACHYDR	454
408	TDB = SIED(IJM)*RODPR(IJM)	KACHYDR	455
	1 / (RODPR1(IJM)*BD1 + (RODPR(IJM)-RODPR1(IJM))*BD2)	KACHYDR	456
409	TDT = SIED(IJP)*RODPR(IJP)	KACHYDR	457
	1 / (RODPR1(IJP)*BD1 + (RODPR(IJP)-RODPR1(IJP))*BD2)	KACHYDR	458
410	THLB = .5 * (THIJ + TH(IMJ))	KACHYDR	459
411	OMTHLB = 1. - THLB	KACHYDR	460
412	THRB = .5 * (THIJ + TH(IPJ))	KACHYDR	461
413	OMTHRB = 1. - THRB	KACHYDR	462
414	THBB = .5 * (THIJ + TH(IJM))	KACHYDR	463
415	OMTHBB = 1. - THBB	KACHYDR	464
416	THTB = .5 * (THIJ + TH(IJP))	KACHYDR	465
417	OMTHTB = 1. - THTB	KACHYDR	466
418	CFXL = UVRL * (HPXIVL*SIEV(IMJ)+HMXIVL*SIEVC)	KACHYDR	467
419	CFXR = UVRR * (HPXIVR*SIEVC +HMXIVR*SIEV(IPJ))	KACHYDR	468
420	CFXB = VV(IJM) * (HPXIVB*SIEV(IJM)+HMXIVB*SIEVC)	KACHYDR	469
421	CFXT = VV(IJ) * (HPXIVT*SIEVC +HMXIVT*SIEV(IJP))	KACHYDR	470
422	SIEDEL = SIEVC*(RRIDR(IJ)+(RIP(IJ)*UV(IJ)-RIP(I-1)*UV(IMJ))	KACHYDR	471
	1 +ROZ*( VV(IJ)- VV(IJM)))	KACHYDR	472
423	VEL = PTE = 0.	KACHYDR	473
424	IF (THTE.LT.TH0) GO TO 1030	KACHYDR	474
425	VEL = KIJ(IJ) * ((.5*(UD(IJ)+UD(IMJ)-UV(IJ)-UV(IMJ))**2	KACHYDR	475
	1 +(.5*(VD(IJ)+VD(IJM)-VV(IJ)-VV(IJM))**2)	KACHYDR	476
426	PTE = P(IJ)*RR*(RRIDR(IJ)*(RIP(IJ)*(THRB*UV(IJ) +OMTHRB*UD(IJ) )	KACHYDR	477

	1	-RIP(I-1)*(THLB=UV(IMJ)+OMTHLE*UD(IMJ))	KACHYDR	478
	2	+RDZ*(THTB=VV(IJ)+OMTHTB=VD(IJ))	KACHYDR	479
427	1030	SIEVTE = SIEVC+DT*(RRIDR(I)*(CFXL-CFXR)+RDZ*(CFXB-CFXT)	KACHYDR	480
	1	+RR*(R*(TDC-TVC)+VEL	KACHYDR	481
	2	+RRI(I)*KVODRSQ*(THRBRIP(I)*(TVR-TVC)-THLB*IP(I-1)*(TVC-TVL))	KACHYDR	482
	3	+KVODZSQ*(THTB*(TVT-TVC)-THBB*(TVC-TVB))) - PTE + SIEDEL	KACHYDR	483
428		IF (A(IJ).NE.AKINF1) A(IJ) = A(IJ)*SIEVTE/SIEVC	KACHYDR	484
429		CFXL = UDR1 * (HPXIDL*SIED(IMJ)+HMXIDL*SIEDC)	KACHYDR	485
430		CFXR = UDRR * (HPXIDR*SIEDC +HMXIDR*SIED(IPJ))	KACHYDR	486
431		CFXB = VD(IJM)* (HPXIDB*SIED(IJM)+HMXIDB*SIEDC)	KACHYDR	487
432		CFXT = VD(IJ) * (HPXIDT*SIEDC +HMXIDT*SIED(IJP))	KACHYDR	488
433		SIEDFL = SIEDC*(RRIDR(I)*(UD(IJ)*RIP(I)-UD(IMJ)*RIP(I-1))	KACHYDR	489
	1	+RDZ*(VD(IJ) -VD(IJM) )	KACHYDR	490
434		SIEDTE = SIEDC+DT*(RRIDR(I)*(CFXL-CFXR)+RDZ*(CFXB-CFXT)	KACHYDR	491
	1	=1./RODPR1(IJ) * (R*(TVC-TDC)+E(IJ) + RRI(I)*	KACHYDR	492
	2	KDODRSQ*(OMTHRB*RRIP(I)*(TDR-TDC)-OMTHLB*IP(I-1)*(TDC-TDL))	KACHYDR	493
	3	+KDODZSQ*(OMTHTB*(TOT-TDC)-OMTHBB*(TDC-TDB))) + SIEDEL	KACHYDR	494
435		IF (I.GT.2) GO TO 1040	KACHYDR	495
436		TH(IMJ) = THTE	KACHYDR	496
437		RODPR1(IMJ) = RODPR1T	KACHYDR	497
438		P(IMJ) = P(IJ)	KACHYDR	498
439		KIJ(IMJ) = KIJ(IJ)	KACHYDR	499
440		SIEV(IMJ) = SIEVTE	KACHYDR	500
441		SIED(IMJ) = SIEDTE	KACHYDR	501
442	1040	IF (J.GT.2) GO TO 1050	KACHYDR	502
443		TH(IJM) = THTE + BINF*(THIN-THYE)	KACHYDR	503
444		RODPR1(IJM) = RODPR1T	KACHYDR	504
445		P(IJM) = P(IJ)	KACHYDR	505
446		KIJ(IJM) = KIJ(IJ)	KACHYDR	506
447		SIEV(IJM) = SIEVTE + BINF*(SIEVIN-SIEVTE)	KACHYDR	507
448		SIED(IJM) = SIEDTE	KACHYDR	508
449		GO TO 1060	KACHYDR	509
450	1050	TH(IJM) = THTAB(I)	KACHYDR	510
451		RODPR1(IJM) = RODITAB(I)	KACHYDR	511
452		SIEV(IJM) = SIEVTAB(I)	KACHYDR	512
453		SIED(IJM) = SIEDTAB(I)	KACHYDR	513
454	1060	THTAB(I) = THTE	KACHYDR	514
455		RODITAB(I) = RODPR1T	KACHYDR	515
456		SIEVTAB(I) = SIEVTE	KACHYDR	516
457		SIEDTAB(I) = SIEDTE	KACHYDR	517
458		IJ = IPJ	KACHYDR	518
459		IJP = IJP + NQ	KACHYDR	519
460	1079	IJM = IJM + NQ	KACHYDR	520
461		TH(IJ) = THTE	KACHYDR	521
462		RODPR1(IJ) = RODPR1T	KACHYDR	522
463		P(IJ) = P(IJ-NQ)	KACHYDR	523
464		KIJ(IJ) = KIJ(IJ-NQ)	KACHYDR	524
465		SIEV(IJ) = SIEVTE	KACHYDR	525
466		SIED(IJ) = SIEDTE	KACHYDR	526
467	1089	CALL LOOP	KACHYDR	527
468		DO 1099 I=2,IP1	KACHYDR	528
469		TH(IJM) = TH(IJ) = THTAB(I)	KACHYDR	529
470		RODPR1(IJM) = RODPR1(IJ) = RODITAB(I)	KACHYDR	530
471		P(IJ) = P(IJM)	KACHYDR	531
472		KIJ(IJ) = KIJ(IJM)	KACHYDR	532
			KACHYDR	533

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473		SIEV(IJM) = SIEV(IJ) = SIEVTAB(I)	KACHYDR	534
474		SIED(IJM) = SIED(IJ) = SIEDTAB(I)	KACHYDR	535
475		IJ = IJ * NQ	KACHYDR	536
476	1099	IJM = IJM * NQ	KACHYDR	537
477		CALL NONE	KACHYDR	538
478		KREQ = 0	KACHYDR	539
479	1500	IF (IBAR.EQ.1) GO TO 1550	KACHYDR	540
480		CALL START	KACHYDR	541
481		DO 1549 J=2,JP1	KACHYDR	542
482		DO 1539 I=2,IBAR	KACHYDR	543
483		IJA = KREQ * IJ	KACHYDR	544
484		IJPA = KREQ * IJP	KACHYDR	545
485		IJMA = KREQ * IJM	KACHYDR	546
486		IPJA = IJA * NQ	KACHYDR	547
487		IMJA = IJA * NQ	KACHYDR	548
488		IPJPA = IJPA * NQ	KACHYDR	549
489		IPJMA = IJMA * NQ	KACHYDR	550
490		URB = UV(IJA)	KACHYDR	551
491		UC = .5*(URB+UV(IMJA))	KACHYDR	552
492		UR = .5*(URB+UV(IPJA))	KACHYDR	553
493		ROULB = .5*(ROVPR(IJA) + ROVPR(IMJA))*UV(IMJA)	KACHYDR	554
494		ROUPB = .5*(ROVPR(IJA) + ROVPR(IPJA))*UR	KACHYDR	555
495		ROURB = .5*(ROVPR(IPJA) + ROVPR(IPJA*NQ))*UV(IPJA)	KACHYDR	556
496		VTRC = .5*(VV(IJA) + VV(IPJA))	KACHYDR	557
497		VHRC = .5*(VV(IMJA) + VV(IPJMA))	KACHYDR	558
498		VRB = .5*(VTRC + VHRC)	KACHYDR	559
499		ROUJP = .5*(ROVPR(IPJA) + ROVPR(IPJPA))*UV(IPJA)	KACHYDR	560
500		ROUJM = .5*(ROVPR(IMJA) + ROVPR(IPJMA))*UV(IMJA)	KACHYDR	561
501		FR = - (SIGN(EPV(KREQ-1),VRB)*URB+VRB) / (URB**2+VRB**2+EM10)	KACHYDR	562
502		XIC = BDT04*UC * SIGN(A0,UC)	KACHYDR	563
503		XIR = BDT04*UR * SIGN(A0,UR)	KACHYDR	564
504		XIBR = BDT02*VHRC * SIGN(A0,VHRC)	KACHYDR	565
505		XITR = BDT02*VTRC * SIGN(A0,VTRC)	KACHYDR	566
506		ROUTE(IJ) = ROURB * FR*DT	KACHYDR	567
	1	RRIP(I) = BDT04*(UC*R(I)*(1.5-XIC) + ROULB*(1.5-XIC) + ROUJM)	KACHYDR	568
	2	-UR*R(I)*(1.5-XIR) + ROURB*(1.5-XIR) + ROUR2B)	KACHYDR	569
	3	.BDT02*(VHRC*(1.5-XIBR) + ROUJM*(1.5-XIBR) + ROURB)	KACHYDR	570
	4	-VTRC*(1.5-XITR) + ROULRB*(1.5-XITR) + ROUJP)	KACHYDR	571
507		IJ = IJ * NQ	KACHYDR	572
508		IJP = IJP * NQ	KACHYDR	573
509	1539	IJM = IJM * NQ	KACHYDR	574
510		ROUTE(IJ) = ROUTE(IJ-NQ)*RCONT(IJ)	KACHYDR	575
511		CALL LOOP	KACHYDR	576
512		IJ = IJ * NQL	KACHYDR	577
513		IJP = IJP * NQL	KACHYDR	578
514	1549	IJM = IJM * NQL	KACHYDR	579
515		CALL NONE	KACHYDR	580
516	1550	CALL START	KACHYDR	581
517		GO 1579 J=2,JBAR	KACHYDR	582
518		CALL H1JP2	KACHYDR	583
519		DO 1560 I=2,IP1	KACHYDR	584
520		IJA = KREQ * IJ	KACHYDR	585
521		IJPA = KREQ * IJP	KACHYDR	586
522		IJMA = KREQ * IJM	KACHYDR	587
523		IPJA = IJA * NQ	KACHYDR	588
524		IMJA = IJA * NQ	KACHYDR	589

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525      IJPA = IJUB + KU
526      IJPA = IJUB - N0
527      VTB = VV(IJA)
528      VC = S*VTB*VV(IJMA)
529      VT = S*VTB*VV(IJPA)
530      ROVB = S*(ROVP(IJJA)-ROVP(IJMA))*VV(IJMA)
531      ROTM = S*(ROVM(IJLI)-ROVM(IJPA))
532      ROVB = ROTB + VTB
533      ROVTB = S*(ROVP(IJJA)-ROVSPL(I-I-1)*NO-I*KREQ)) + VV(IJPA)
534      UTLC = S*(UV(IJPA)-UV(IJLI))
535      UTAC = S*(UV(IJPA)-UV(IJLI))
536      UTB = S*UTLC*UTAC
537      ROVM = S*(ROVP(IJMA)-ROVP(IJPA))*VV(IJMA)
538      ROVIP = S*(ROVP(IJPA)-ROVP(IJPA))*VV(IJJA)
539      FZ = S*(SIG(I*P(KREQ),I)*VTB)*UTBEEZ) / (UTBEEZ*VTBEEZ*EM10)
540      XIC = BDTORZVC + SIG(I*AV*CI)
541      XIL = BDTORZVC + SIG(I*AD*VI)
542      XIL = BDTORZVC*UTLC + SIG(I*AD*UTLC)
543      XITR = BDTORZVC*UTAC + SIG(I*AD*UTAC)
544      ROVT(IJ) = ROVB + ROVB*EDI + FZ*GT *
1      RRT(I)*OTORZ*UTLC*AP(I-I-1)*((S*XIL)*ROVM*(S-XITL)*ROVTB)
2      *UTAC*AP(I) *((S*XITR)*ROVM*(S-XITL)*ROVIP)
3      *OTORZ*(VC*(I-S*XIC) *ROVM*(S-XIC) *ROVTB)
4      *VT*((S*XIT) *ROVTB*(S-XIT) *ROVTB))
545      IF (J.GT.2) GO TO 1560
546      ROVB = S*(ROVP(IJJA)-ROVM) + VV(IJMA)
547      ROVT(IJ) = ROVB + ROVT*(ROVT(IJ)-ROV)
548      IF (J.EQ.UBAR) ROVT(IJ) = ROVT(IJ)*ETOP
549      IJ = IJ + NU
1560      IJ = IJ + NU
550      IJM = IJM + N0
551      IJM = IJM + N0
552      CALL LOOP
553      CALL DONE
554      CALL START
555      DO 1619 J=2:JP1
556      IF ((BAR.GT.1)) MOVV(IJ-KREQ) = ROVT(IJ)
557      ROVV(IJM-KREQ) = ROVT(IJM)
558      IJ = IJ + N0
1609      IJM = IJM + N0
560      CALL LOOP
561      DO 1629 I=2:IP1
562      ROVV(IJM-KREQ) = ROVT(IJM)
563      IJM = IJM + KU
1629      CALL DONE
564      KREQ = KREQ + 1
565      GO TO (1500,1700) KREQ
566      CALL START
567      DO 1769 J=2:JP1
568      DO 1759 I=2:IP1
569      IJ = IJ + NU
570      IJ = IJ + NU
571      HUDPRT(IJ) = RDHPRT(IJ)
572      DTKE(IJ) = OTORZ*(R(IJ)*K(IJ)*P(J))
573      DTKE(IJ) = DTORZ*(R(IJ)*K(IJ)*P(J))
574      HATI(J) = 1. / A(IJ)
575
576      KACHYDR 500
577      KACHYDR 501
578      KACHYDR 532
579      KACHYDR 523
580      KACHYDR 524
581      KACHYDR 525
582      KACHYDR 526
583      KACHYDR 627
584      KACHYDR 628
585      KACHYDR 629
586      KACHYDR 630
587      KACHYDR 631
588      KACHYDR 632
589      KACHYDR 633
590      KACHYDR 634
591      KACHYDR 635
592      KACHYDR 636
593      KACHYDR 637
594      KACHYDR 638
595      KACHYDR 639
596      KACHYDR 640
597      KACHYDR 641
598      KACHYDR 642
599      KACHYDR 643
600      KACHYDR 644
601      KACHYDR 645
602      KACHYDR 646
603      KACHYDR 647
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606      KACHYDR 650
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611      KACHYDR 655
612      KACHYDR 656
613      KACHYDR 657
614      KACHYDR 658
615      KACHYDR 659
616      KACHYDR 660
617      KACHYDR 661
618      KACHYDR 662
619      KACHYDR 663
620      KACHYDR 664
621      KACHYDR 665

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577		ROVPR(IJ) = F(IJ)*TH(IJ)*ROVO + (1.-F(IJ))*P(IJ)*RA(IJ)	KACHYDR	646
578		IF (I.GT.2) GO TO 1710	KACHYDR	647
579		RODPR(IJ) = RODPR(IJ)	KACHYDR	648
580		DTKR(IJ) = DT02*(K(IJ)+K(IJ))	KACHYDR	649
581		ROVPR(IJ) = ROVPR(IJ)	KACHYDR	650
582	1710	IF (J.GT.2) GO TO 1720	KACHYDR	651
583		RODPR(IJ) = RODPR(IJ)	KACHYDR	652
584		DTKT(IJ) = DT02*(K(IJ)+K(IJ))	KACHYDR	653
585		ROVPR(IJ) = ROVPR(IJ)	KACHYDR	654
586	1720	IF (I.LT.IP) GO TO 1730	KACHYDR	655
587		RODPR(IP) = RODPR(IJ)	KACHYDR	656
588		ROVPR(IP) = ROVPR(IJ)	KACHYDR	657
589	1730	IF (J.LT.JP) GO TO 1740	KACHYDR	658
590		RODPR(IJ) = RODPR(IJ)	KACHYDR	659
591		ROVPR(IJ) = ROVPR(IJ)	KACHYDR	660
592	1740	IJ = IP	KACHYDR	661
593		IJP = IJP + NQ	KACHYDR	662
594	1750	IJM = IJM + NQ	KACHYDR	663
595	1760	CALL LOOP	KACHYDR	664
596		CALL DONE	KACHYDR	665
597		CALL START	KACHYDR	666
598		DO 2099 J=2,JP	KACHYDR	667
599		DO 2089 I=2,IP	KACHYDR	668
600		IPJ = IJ + NQ	KACHYDR	669
601		XX = DT02*(P(IJ)-P(IPJ))	KACHYDR	670
602		THTE = .5*(TH(IJ)+TH(IPJ))	KACHYDR	671
603		BS = ROVD(IJ) + (1.-THTE)*XX	KACHYDR	672
604		CS = ROVV(IJ) + THTE*XX	KACHYDR	673
605		ROVTEM = .5*(ROVPR(IJ)+ROVPR(IPJ))	KACHYDR	674
606		RODTEM = .5*(RODPR(IJ)+RODPR(IPJ))	KACHYDR	675
607		DTK = DTKR(IJ)	KACHYDR	676
608		DTKBC = DTK*(BS+CS)	KACHYDR	677
609		RDENOM = 1. / (ROVTEM*(RODTEM+DTK)+DTK*RODTEM)	KACHYDR	678
610		UV(IJ) = RDENOM*(RODTEM*CS+DTKBC)	KACHYDR	679
611		UD(IJ) = RDENOM*(ROVTEM*BS+DTKBC)	KACHYDR	680
612	2089	IJ = IPJ	KACHYDR	681
613	2099	CALL LOOP	KACHYDR	682
614		CALL DONE	KACHYDR	683
615		CALL START	KACHYDR	684
616		KREQ = 1	KACHYDR	685
617		DO 2199 J=2,JTOP	KACHYDR	686
618		DO 2189 I=2,IP1	KACHYDR	687
619		XX = DT02*(P(IJM)-P(IJ))	KACHYDR	688
620		THTE = .5*(TH(IJM)+TH(IJ))	KACHYDR	689
621		DS = ROVD(IJM) + (1.-THTE)*XX	KACHYDR	690
622		ES = ROVV(IJM) + THTE*XX	KACHYDR	691
623		ROVTEM = .5*(ROVPR(IJM)+ROVPR(IJ))	KACHYDR	692
624		RODTEM = .5*(RODPR(IJM)+RODPR(IJ))	KACHYDR	693
625		DTK = DTKT(IJM)	KACHYDR	694
626		DTKDE = DTK*(DS+ES)	KACHYDR	695
627		RDENOM = 1. / (ROVTEM*(RODTEM+DTK)+DTK*RODTEM)	KACHYDR	696
628		VV(IJM) = RDENOM*(RODTEM*ES+DTKDE)	KACHYDR	697
629		VD(IJM) = RDENOM*(ROVTEM*DS+DTKDE)	KACHYDR	698
630		GO TO (2130,2140) KREQ	KACHYDR	699
631	2130	VV(IJM) = BCUT*VV(IJM) + VVIN	KACHYDR	700
632		VD(IJM) = BCUT*VD(IJM)	KACHYDR	701

633	2140	IJ = IJ + NQ	KACHYDR	702
634	2189	IJM = IJM + NQ	KACHYDR	703
635		KREQ = 2	KACHYDR	704
636	2199	CALL LOOP	KACHYDR	705
637		CALL DONE	KACHYDR	706
638		CONV = 0.	KACHYDR	707
639		CALL START	KACHYDR	708
640		DO 2299 J=2,JP1	KACHYDR	709
641		DO 2289 I=2,IP1	KACHYDR	710
642		IMJ = IJ - NQ	KACHYDR	711
643		IPJ = IJ + NQ	KACHYDR	712
644		RZA = .5*RA(IJ)	KACHYDR	713
645		UVR = UV(IJ)	KACHYDR	714
646		UVL = UV(IMJ)	KACHYDR	715
647		VVT = VV(IJ)	KACHYDR	716
648		VVB = VV(IJM)	KACHYDR	717
649		IF (I.EQ.2) GO TO 2210	KACHYDR	718
650		THTEL = THTER	KACHYDR	719
651		RODL = RODR	KACHYDR	720
652		PUDENL = PUDENR	KACHYDR	721
653		TERM1L = TERM1R	KACHYDR	722
654		TERM2L = TERM2R	KACHYDR	723
655		GO TO 2220	KACHYDR	724
656	2210	DTK = DTKR(IMJ)	KACHYDR	725
657		THTEL = .5*(TH(IJ)+TH(IMJ))	KACHYDR	726
658		ROVL = .5*(ROVPR(IJ) + ROVPR(IMJ))	KACHYDR	727
659		RODL = .5*(RODPR(IJ) + RODPR(IMJ))	KACHYDR	728
660		PUDENL = 1. / (ROVL*(RODL+DTK)+DTK*RODL)	KACHYDR	729
661		TERM1L = ROVL*(1.-THTEL)*DTODR	KACHYDR	730
662		TERM2L = THTEL*DTODR	KACHYDR	731
663	2220	IF (J.EQ.2) GO TO 2230	KACHYDR	732
664		THTEB = THTE(I)	KACHYDR	733
665		RODB = RODT(I)	KACHYDR	734
666		PVDENB = PVDENT(I)	KACHYDR	735
667		TERM1B = TERM1T(I)	KACHYDR	736
668		TERM2B = TERM2T(I)	KACHYDR	737
669		GO TO 2240	KACHYDR	738
670	2230	DTK = DTKT(IJM)	KACHYDR	739
671		THTEB = .5*(TH(IJ)+TH(IJM))	KACHYDR	740
672		ROVB = .5*(ROVPR(IJ) + ROVPR(IJM))	KACHYDR	741
673		RODB = .5*(RODPR(IJ) + RODPR(IJM))	KACHYDR	742
674		PVDENB = 1. / (ROVB*(RODB+DTK)+DTK*RODB)	KACHYDR	743
675		TERM1B = ROVB*(1.-THTEB)*DTODZ	KACHYDR	744
676		TERM2B = THTEB*DTODZ	KACHYDR	745
677	2240	DTK = DTKR(IJ)	KACHYDR	746
678		THTER = .5*(TH(IJ)+TH(IPJ))	KACHYDR	747
679		ROVR = .5*(ROVPR(IJ)+ROVPR(IPJ))	KACHYDR	748
680		RODR = .5*(RODPR(IJ)+RODPR(IPJ))	KACHYDR	749
681		PUDENR = 1. / (ROVR*(RODR+DTK)+DTK*RODR)	KACHYDR	750
682		TERM1R = ROVR*(1.-THTER)*DTODR	KACHYDR	751
683		TERM2R = THTER*DTODR	KACHYDR	752
684		DTK = DTKT(IJ)	KACHYDR	753
685		THTE(I) = .5*(TH(IJ)+TH(IPJ))	KACHYDR	754
686		ROVT = .5*(ROVPR(IJ)+ROVPR(IPJ))	KACHYDR	755
687		RODT(I) = .5*(RODPR(IJ)+RODPR(IPJ))	KACHYDR	756
688		PVDENT(I) = 1. / (ROVT*(RODT(I)+DTK)+DTK*RODT(I))	KACHYDR	757

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689      TERM1(I) = ROVT*(I.-THTET(I))*DTODZ
690      TERM2(I) = THTET(I)*DTODZ
691      IF (TH(IJ),LT,TH0) GO TO 2250
692      PARUL = (TERM1L -RNDL *(TERM2L +UVL*R2A))*PUDENL
693      PARVB = (TERM1B -RNDR *(TERM2B +VVR*R2A))*PVDENB
694      PARUR = (TERM1R -RNDR *(TERM2R -UVR*R2A))*PUDENR
695      PARVT = (TERM1T)-RNDT*(TERM2T)-VVT*R2A))*PVDENT(I)
696      RBETA = RA(IJ)*RDI,RDR*RI(I)*(DTODR*(RIP(I)*THTER*RIP(I-1)*THTEL)
1      *RIP(I)*DTKR(IJ)*PARUR-RIP(I-1)*DTKR(IMJ)*PARUL)
2      *RDZ*(DTODZ*(THTET(I)*THTEB)*DTKT(IJ)*PARVT-DTKT(IMJ)*PARVB)
697      OMBETA(IJ) = OMP / RBETA
698      GO TO 2270
699      OMBETA(IJ) = OMBSP1 * ROPPR(IJ)
700      2270 CONV = AMAX1(CONV,(R2DR*(ABS(UVR)+ABS(UVL))
1      *R2DZ*(ABS(VVT)+ABS(VVB)))*ROVPR(IJ))
701      IJ = IPJ
702      IJP = IJP * NQ
703      2249 IJM = IJM * NQ
704      2249 CALL LOOP
705      CALL DONE
706      CONV = EPS*(CONV*EM6)
707      NUMIT = 0
708      MUSTIT = 1
709      2400 CALL START
710      DO 2499 J=2,JP1
711      DO 2489 I=2,IP1
712      IMJ = IJ - NQ
713      IPJ = IJ * NQ
714      IF (TH(IJ),LT,TH0) GO TO 2450
715      UVRB = UV(IJ)
716      UVLB = UV(IMJ)
717      VVTB = VV(IJ)
718      VVBB = VV(IMJ)
719      XIVR = BDTODR*UVRB * SIGN(A0,UVRB)
720      XIVL = BDTODR*UVLB * SIGN(A0,UVLB)
721      XIVT = BDTODZ*VVTB * SIGN(A0,VVTB)
722      XIVB = BDTODZ*VVBB * SIGN(A0,VVBB)
723      ROVPRTC = ROVPRT(IJ)
724      UTIL = RDT*(ROVPRTC-ROVPR(IJ)) + RRIDR(I)
1      *(UVRB*RIP(I) * ((.5*XIVR)*ROVPRTC * (.5-XIVR)*ROVPRT(IPJ))
2      *UVLB*RIP(I-1))*((.5*XIVL)*ROVPRT(IMJ)*(.5-XIVL)*ROVPRTC ))
3      *RUZ*(VVTB*((.5*XIVT)*ROVPRTC * (.5-XIVT)*ROVPRT(IJP))
4      *VVBB*((.5*XIVB)*ROVPRT(IMJ)*(.5-XIVB)*ROVPRTC ))
725      GO TO 2470
726      2450 DTIL = RRIDR(I)*(UD(IJ)*RIP(I)-UD(IMJ)*RIP(I-1)
1      *RDZ*(VD(IJ) -VD(IMJ) )
727      2470 IF (ABS(DTIL).GT,CONV) MUSTIT = MUSTIT * I
728      PP(IJ) = P(IJ) * DTIL*OMBETA(IJ)
729      IJ = IPJ
730      IJM = IJM * NQ
731      2489 IJP = IJP * NQ
732      2499 CALL LOOP
733      CALL DONE
734      CALL START
735      DO 2599 J=2,JP1
736      DO 2589 I=2,IP1

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KACHYDR 758
KACHYDR 759
KACHYDR 760
KACHYDR 761
KACHYDR 762
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KACHYDR 813

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737	IPJ = IJ * NJ	KACHYDR	814
738	IMJ = IJ - NJ	KACHYDR	815
739	RODPRC = RODPR(IJ)	KACHYDR	816
740	THTEC = TH(IJ)	KACHYDR	817
741	PC = P(IJ)	KACHYDR	818
742	PPC = P(IJ) = PP(IJ)	KACHYDR	819
743	UPRT(IJ) = UPC = PPC - PC	KACHYDR	820
744	ROVPRT0 = ROVPRT(IJ)	KACHYDR	821
745	ROVPRTN = ROVPRT(IJ) = F(IJ)*TH(IJ)*ROV0 + (1.-F(IJ))*PPC*RA(IJ)	KACHYDR	822
746	IF (1.GT.2) GO TO 2520	KACHYDR	823
747	P(IMJ) = PPC	KACHYDR	824
748	ROVPRT(IMJ) = ROVPRTN	KACHYDR	825
749	2520 IF (1.EQ.IP1) GO TO 2530	KACHYDR	826
750	DPR = PP(IPJ) - P(IPJ)	KACHYDR	827
751	DPDTODR = (DPC-DPR)*DTODR	KACHYDR	828
752	THRB = .5*(THTEC+TH(IPJ))	KACHYDR	829
753	UVTE = UV(IJ)	KACHYDR	830
754	UDTE = UD(IJ)	KACHYDR	831
755	DTK = DTKR(IJ)	KACHYDR	832
756	DTKDU = DTK*(UVTE-UDTE)	KACHYDR	833
757	ROVRB0 = .5*(ROVPRTN+ROVPRT(IPJ))	KACHYDR	834
758	ROVRBN = .5*(ROVPRTN+ROVPRT(IPJ))*DPR*RA(IPJ)	KACHYDR	835
759	RODRB = .5*(RODPRC + RODPR(IPJ))	KACHYDR	836
760	RS = ROVRB0*UVTE + DTKDU + DPDTODR*THRB	KACHYDR	837
761	US = RODRB *UDTE - DTKDU + DPDTODR*(1.-THRB)	KACHYDR	838
762	RDENOM = 1. / (ROVRBN*(RODRB+DTK)+DTK*RODRB)	KACHYDR	839
763	UV(IJ) = RDENOM*(RS*(RODRB +DTK)+DTK*US)	KACHYDR	840
764	UD(IJ) = RDENOM*(US*(ROVRBN+DTK)+DTK*RS)	KACHYDR	841
765	GO TO 2540	KACHYDR	842
766	2530 P(IPJ) = PPC	KACHYDR	843
767	ROVPRT(IPJ) = ROVPRTN	KACHYDR	844
768	UV(IJ) = UV(IMJ) * RCONT(J)	KACHYDR	845
769	UD(IJ) = UD(IMJ) * RCONT(J)	KACHYDR	846
770	2540 IF (J.EQ.JP1) GO TO 2560	KACHYDR	847
771	DPT = PP(IJP) - P(IJP)	KACHYDR	848
772	DPDTODZ = (DPC-DPT)*DTODZ	KACHYDR	849
773	THTB = .5*(THTEC+TH(IJP))	KACHYDR	850
774	VVTE = VV(IJ)	KACHYDR	851
775	VDTE = VD(IJ)	KACHYDR	852
776	DTK = DTK(IJ)	KACHYDR	853
777	DTKDV = DTK*(VVTE-VDTE)	KACHYDR	854
778	ROVTB0 = .5*(ROVPRT0+ROVPRT(IJP))	KACHYDR	855
779	ROVTBN = .5*(ROVPRTN+ROVPRT(IJP))*DPT*RA(IJP)	KACHYDR	856
780	RODTB = .5*(RODPRC + RODPR(IJP))	KACHYDR	857
781	SS = ROVTB0*VVTE + DTKDV + DPDTODZ*THTB	KACHYDR	858
782	VS = RODTB *VDTE - DTKDV + DPDTODZ*(1.-THTB)	KACHYDR	859
783	RDENOM = 1. / (ROVTBN*(RODTB+DTK)+DTK*RODTB)	KACHYDR	860
784	VV(IJ) = RDENOM*(SS*(RODTB +DTK)+DTK*VS)	KACHYDR	861
785	VD(IJ) = RDENOM*(VS*(ROVTBN+DTK)+DTK*SS)	KACHYDR	862
786	IF (J.GT.2) GO TO 2580	KACHYDR	863
787	P(IJM) = PPC	KACHYDR	864
788	ROVPRT(IJM) = ROVPRTN + BINP*(ROVPIN-ROVPRTN)	KACHYDR	865
789	VV(IJM) = BOUT*VV(IJ) + VVIN	KACHYDR	866
790	VD(IJM) = BOUT*VD(IJ)	KACHYDR	867
791	GO TO 2580	KACHYDR	868
792	2560 P(IJP) = PPC	KACHYDR	869



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793		ROVPR1(IJP) = ROVPR1N		
794		VV(IJ) = VV(IJM)*TOP	KACHYDR	870
795		VD(IJ) = VD(IJM)*TOP	KACHYDR	871
796	2580	IJ = IPJ	KACHYDR	872
797		IJM = IJM + NQ	KACHYDR	873
798	2589	IJP = IJP + NQ	KACHYDR	874
799	2599	CALL LOOP	KACHYDR	875
800		CALL DONE	KACHYDR	876
801		NUMIT = NUMIT + 1	KACHYDR	877
802		MUSTPR = MUSTIT	KACHYDR	878
803		IF (MUSTIT.EQ.0) GO TO 2600	KACHYDR	879
804		MUSTIT = 0	KACHYDR	880
805		IF (NUMIT.LT.100) GO TO 2400	KACHYDR	881
806	2600	CALL START	KACHYDR	882
807		DO 2699 J=2,JP1	KACHYDR	883
808		DO 2689 I=2,IP1	KACHYDR	884
809		IMJ = IJ + NQ	KACHYDR	885
810		IPJ = IJ + NQ	KACHYDR	886
811		DPRT(IJ) = DPRT(IJ) / OMBETA(IJ)	KACHYDR	887
812		ROVPR(IJ) = ROVPR1(IJ)	KACHYDR	888
813		GO TO (2610,2620,2630) NVAP	KACHYDR	889
814	2610	ROVPR1(IJ) = 0.	KACHYDR	890
815		GO TO 2640	KACHYDR	891
816	2620	ROVPR1(IJ) = ROVPR(IJ)	KACHYDR	892
817		GO TO 2640	KACHYDR	893
818	2630	ROVPR1(IJ) = ROVPR(IJ)	KACHYDR	894
819		OMBETA(IJ) = OMR0 /	KACHYDR	895
		1 (RDI-R2D0+RRI(I)*{RIP(I)*VV(IJ)-RIP(I-1)*VV(IMJ)})	KACHYDR	897
		2 R2D2	KACHYDR	898
820	2640	IF (I.GT.2) GO TO 2650	KACHYDR	899
821		ROVPR(IMJ) = ROVPR(IJ)	KACHYDR	900
822		ROVPR1(IMJ) = ROVPR1(IJ)	KACHYDR	901
823	2650	IF (J.GT.2) GO TO 2660	KACHYDR	902
824		ROVPR(IJM) = ROVPR(IJ)*BINF*(ROVPR1N-ROVPR(IJ))	KACHYDR	903
825		ROVPR1(IJM) = ROVPR1(IJ) + BINF*(ROVPR1N-ROVPR1(IJ))	KACHYDR	904
826	2660	IF (I.LT.IP1) GO TO 2670	KACHYDR	905
827		ROVPR(IPJ) = ROVPR(IJ)	KACHYDR	906
828		ROVPR1(IPJ) = ROVPR1(IJ)	KACHYDR	907
829	2670	IF (J.LT.JP1) GO TO 2680	KACHYDR	908
830		ROVPR(IJP) = ROVPR(IJ)	KACHYDR	909
831		ROVPR1(IJP) = ROVPR1(IJ)	KACHYDR	910
832	2680	IJ = IPJ	KACHYDR	911
833		IJP = IJP + NQ	KACHYDR	912
834	2689	IJM = IJM + NQ	KACHYDR	913
835	2699	CALL LOOP	KACHYDR	914
836		CALL DONE	KACHYDR	915
837		NUMRO = MUSTRO = 0	KACHYDR	916
838		IF (NVAP.LT.3) GO TO 3000	KACHYDR	917
839		MUSTIT = 1	KACHYDR	918
840	2700	CALL START	KACHYDR	919
841		DO 2799 J=2,JP1	KACHYDR	920
842		DO 2789 I=2,IP1	KACHYDR	921
843		IMJ = IJ + NQ	KACHYDR	922
844		IPJ = IJ + NQ	KACHYDR	923
845		UVRB = UV(IJ)	KACHYDR	924
846		UVLB = UV(IMJ)	KACHYDR	925

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847      VVIB = VV(IJ)
848      VVBB = VV(IJM)
849      XIVR = BDTODR*UVRB + SIGN(A0,UVRB)
850      XIVL = BDTODR*UVLB + SIGN(A0,UVLB)
851      XIVT = BDTODZ*VVTR + SIGN(A0,VVTR)
852      XIVB = BDTODZ*VVBR + SIGN(A0,VVBR)
853      ROVPRTO = ROVPRIT(IJ)
854      Q = RDT*(ROVPRTO-ROVPR1(IJ)) + RHIDR(I)
      1 *(UVRB*RIPI) *((.5-XIVR)*ROVPRTO + (.5-XIVR)*ROVPRIT(IPJ))
      2 -UVLB*RIPI(I-1)*((.5-XIVL)*ROVPRIT(IMJ)+(.5-XIVL)*ROVPRTO )
      3 + RDZ*(VVTR*((.5-XIVT)*ROVPRTO + (.5-XIVT)*ROVPRIT(IJP))
      4 -VVBB*((.5-XIVB)*ROVPRIT(IJM)+(.5-XIVB)*ROVPRTO ))
855      IF (ABS(Q).GT.CONV) MUSTIT = MUSTIT + 1
856      ROVPRTN = ROVPRIT(IJ) = ROVPRTO - OMBETA(IJ)*Q
857      IF (I.EQ.2) ROVPRIT(IMJ) = ROVPRTN
858      IF (J.EQ.2) ROVPRIT(IJM) = ROVPRTN + BINF*(ROVPRIN1-ROVPRTN)
859      IF (I.EQ.IPI) ROVPRIT(IPJ) = ROVPRTN
860      IF (J.EQ.JPI) ROVPRIT(IJP) = ROVPRTN
861      IJ = IPJ
862      IJM = IJM + NQ
863      2789 IJP = IJP + NQ
864      2799 CALL LOOP
865      CALL DONE
866      NUMRO = NUMRO + 1
867      MUSTRO = MUSTIT
868      IF (MUSTIT.EQ.0) GO TO 3000
869      MUSTIT = 0
870      IF (NUMRO.LT.100) GO TO 2700
871      3000 CALL START
872      DO 3099 J=2,JP1
873      DTKRSV = DTKR(IJ-NQ)
874      E(IJ-NQ) = 0.
875      DO 3089 I=2,IP1
876      IPJ = IJ + NQ
877      IMJ = IJ - NQ
878      KIJ(IJ) = 2.*RDT*DTKRSV - KIJ(IMJ)
879      DTKRSV = DTKR(IJ)
880      A(IJ) = 1. / RA(IJ)
881      E(IJ) = 0.
882      ROVPR1(IJ) = ROVPRIT(IJ)
883      IF (I.EQ.2) ROVPR1(IMJ) = ROVPR1(IJ)
884      IF (J.EQ.2) ROVPR1(IJM) = ROVPR1(IJ) + BINF*(ROVPRIN1-ROVPR1(IJ))
885      IF (I.EQ.IPI) ROVPR1(IPJ) = ROVPR1(IJ)
886      IF (J.EQ.JPI) ROVPR1(IJP) = ROVPR1(IJ)
887      IJ = IPJ
888      IJP = IJP + NQ
889      3089 IJM = IJM + NQ
890      3099 CALL LOOP
891      CALL DONE
892      IF (NPTOT.EQ.0) GO TO 100
893      CALL START
894      DO 3199 J=2,JP2
895      DO 3189 I=2,IP2
896      IF (I.GT.2) GO TO 3110
897      VV(IJM-NQ) = VV(IJM)
898      VD(IJM-NQ) = VD(IJM)

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KACHYDR 926
KACHYDR 927
KACHYDR 928
KACHYDR 929
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KACHYDR 978
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KACHYDR 980
KACHYDR 981

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899	3110	IF (J.GT.2) GO TO 3120	KACHYDR	982
900		UV(IJM-NQ) = UV(IJ-NQ)	KACHYDR	983
901		UD(IJM-NQ) = UD(IJ-NQ)	KACHYDR	984
902	3120	IF (I.LI.IP2) GO TO 3130	KACHYDR	985
903		VV(IJM) = VV(IJM-NQ)	KACHYDR	986
904		VD(IJM) = VD(IJM-NQ)	KACHYDR	987
905	3130	IF (J.LT.JP2) GO TO 3140	KACHYDR	988
906		UV(IJ-NQ) = UV(IJM-NQ)	KACHYDR	989
907		UD(IJ-NQ) = UD(IJM-NQ)	KACHYDR	990
908	3140	IJM = IJM + NQ	KACHYDR	991
909	3169	IJ = IJ + NQ	KACHYDR	992
910		CALL LOOP	KACHYDR	993
911		IJM = IJM - NQL	KACHYDR	994
912	3199	IJ = IJ - NQL	KACHYDR	995
913		CALL DONE	KACHYDR	996
914		KPN = 0	KACHYDR	997
915		DO 3299 KP=1,NPTOT	KACHYDR	998
916		XTE = XP(KP)	KACHYDR	999
917		YTE = YP(KP)	KACHYDR	1000
918		KMAT = 0	KACHYDR	1001
919		KFLG = XP(KP).A.3B	KACHYDR	1002
920		IF (KFLG.LE.1) KMAT = 1	KACHYDR	1003
921		I = XTE + 2.	KACHYDR	1004
922		HPX = FLOAT(I) - 1. - XTF	KACHYDR	1005
923		HMX = 1. - HPX	KACHYDR	1006
924		J = YTE + 1.5	KACHYDR	1007
925		HPY = FLOAT(J) - .5 - YTE	KACHYDR	1008
926		HMY = 1. - HPY	KACHYDR	1009
927		CALL RPARU	KACHYDR	1010
928		IJ = IJ + NQ*(I-1) + 1 + KMAT	KACHYDR	1011
929		IJP = IJ + NQI	KACHYDR	1012
930		UK = HPX*HMY*UV(IJP-NQ) + HMX*HMY*UV(IJP)	KACHYDR	1013
931		1 +HPX*HPY*UV(IJ-NQ) + HMX*HPY*UV(IJ)	KACHYDR	1014
932		I = XTE + 1.5	KACHYDR	1015
933		HPX = FLOAT(I) - .5 - XTE	KACHYDR	1016
934		HMX = 1. - HPX	KACHYDR	1017
935		J = YTE + 2.	KACHYDR	1018
936		HPY = FLOAT(J) - 1. - YTE	KACHYDR	1019
937		HMY = 1. - HPY	KACHYDR	1020
938		CALL RPARV	KACHYDR	1021
939		IJ = IJ + NQ*(I-1) + 1 + KMAT	KACHYDR	1022
940		IJM = IJ - NQI	KACHYDR	1023
		VK = HPX*HMY*VV(IJ) + HMX*HMY*VV(IJ+NQ)	KACHYDR	1024
		1 +HPX*HPY*VV(IJM) + HMX*HPY*VV(IJM+NQ)	KACHYDR	1025
941		XTE = XTE + UK*DTODR	KACHYDR	1026
942		YTE = YTE + VK*DTODZ	KACHYDR	1027
943		IF (XTE.LE.0. .0. XTE.GE.FIBAR) GO TO 3299	KACHYDR	1028
944		IF (YTE.LE.0. .0. YTE.GE.FJBAR) GO TO 3299	KACHYDR	1029
945		KPN = KPN + 1	KACHYDR	1030
946		XP(KPN) = (XTE.A.*N.3B) .0. KFLG	KACHYDR	1031
947		YP(KPN) = YTE	KACHYDR	1032
948	3299	CONTINUE	KACHYDR	1033
949		NPTOT = KPN	KACHYDR	1034
950		GO TO 100	KACHYDR	1035
		C	KACHYDR	1036
951	4000	FORMAT (00 TAPE DUMP*13* AT I=*1PE12.5* CYCLE*15)	KACHYDR	1037

952	4070	FORMAT (00 RESTARTING FROM TD*I3)	KACHYDR	1038
953	4020	FORMAT (3X,8A10° T=*1PE12.5° CYCLE=*15)	KACHYDR	1039
954	4030	FORMAT (00 WRONG TAPP = WRONG DUMP,°)	KACHYDR	1040
955	4040	FORMAT (20X°PARTICLES--- VAPOR=., DROPS1=°, DROPS2=SQ,°)	KACHYDR	1041
956	4050	FORMAT (5XA10,2(5XA8),5XA8A10/40X° T=*1PE12.5° CYCLE=*14)	KACHYDR	1042
957	4060	FORMAT (1H,°16X°MAXIMUM VELOCITY=*1PE12.5)	KACHYDR	1043
958	4080	FORMAT (12X° MIN=*1PE12.5° MAX=*E12.5° L=*E12.5° H=*E12.5° DG=* 1 E12.5)	KACHYDR	1044
959	4090	FORMAT (2(1X13),3X,8(2X,1PE12.5)/11X,8(2X,1PE12.5)/)	KACHYDR	1045
960	4100	FORMAT (° I J°10X°TH°12X°U°12X°VV°11X°STEV°10X°ROVPR1°8X°ROVPR 1°10X°D°13X°P°/ 17X°E° 13X°UD°12X°VD°11X°STED°10X°RODPR1°8X°RODPR 2°10X°A°13X°K°)	KACHYDR	1046
961	4110	FORMAT (1H1)	KACHYDR	1049
962	4120	FORMAT (° T=*1PE12.5° CYC=*15° DT=*E12.5° CP=*E12.5° GRINDS=* 1E12.5° ITP=*I3°, CELLS=*I4° ITR0=*I3°, CELLS=*I4)	KACHYDR	1050
963	4130	FORMAT (/° T=*1PE12.5°, CYC=*14° HAS THE FOLLOWING SUMMATIONS...°/ I 5X°TH=*1PE15.8° MOMR=*E15.8° MOMZV=*E15.8° MOMZD=*E15. 18° MOMZ=*E15.8/° MV1=*E15.8° MD1=*E15.6,4X°IEV=*E15.8,4X°I ZED=*E15.8,5X°IE=*E15.8/° MV2.*E15.8° MD2=*E15.8,4X°KEV=*E15. 38,4X°KED=*E15.8,5X°KE=*E15.8/5X°MV=*E15.8,5X°MD=*E15.8,5X°EV=*E15. 48,5X°ED=*E15.8,6X°E=*E15.8)	KACHYDR	1051
964		END	KACHYDR	1052
			KACHYDR	1053
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IC1	-I	22C=	227=	234=	241=	248	24A	249	249									
IC2	-I	271=	228=	235=	242=	248	249											
IOCON	(I)	10DI	17UA	199WR														
IDPP	(I)	10DI	14DA	120WR														
IDTO	-I	3C0	62	63	64	64	65=	65										
IDVV	(I)	10DI	16DA	148WR														
II	-I	21AG	22															
IJ	-I	3C0	137	137	138	138	139=	139	157	157	158	165=	165	176	176	177	178	178
		179=	179	186	186	187=	187	209	213	222	229	257=	260=	260	303	304	305	306
		307	309	310	310	312	313	313	314	314	314	314	315	316	316	316	320	321
		325	325	326	326	337=	346	347	351	351	357	357	363	363	369	369	372	374
		376	377	378	378	378	378	378	378	378	379	379	379	379	379	379	380	382
		382	383	383	383	383	384	384	385	385	386	386	388	389	389	390	391	391
		391	391	391	391	392	392	392	392	394	394	397	397	398	399	400	400	400
		400	405	405	405	405	421	422	422	425	425	425	425	425	426	426	426	426
		426	428	428	428	432	433	433	434	434	438	439	445	446	458=	461	462	463
		463	464	464	465	466	469	470	471	472	473	474	475=	475	483	506	507=	507
		510	510	512=	512	520	544	547	548	549=	549	557	557	559=	559	571	572	573
		573	574	574	575	575	576	576	577	577	577	577	577	579	580	583	584	584
		587	590	592=	600	601	602	603	604	605	606	607	610	611	612=	619	620	623
		624	633=	633	642	643	644	645	647	657	658	659	671	672	673	677	678	679
		680	684	685	686	687	691	696	696	696	697	699	699	700	701=	712	713	714
		715	717	723	724	726	726	726	728	728	728	729=	737	738	739	740	741	742
		743	744	745	745	745	745	745	753	754	755	763	764	768	769	774	775	776
		764	785	789	799	754	795	796=	809	810	811	811	811	812	812	814	816	816
		810	818	819	819	819	821	822	824	824	825	825	827	828	830	831	832=	843
		844	845	847	853	854	856	856	861=	873	874	876	877	878	879	880	880	881
		882	882	883	884	884	885	886	887=	900	901	906	907	909=	909	912=	912	928=
		928	929	930	930	938=	938	939	940	940								
IJA	-I	483=	486	487	490	493	494	496	520=	523	524	527	530	531	535	546		
IJM	-I	3C0	45	45	46	46	47=	47	158	164=	164	277	295=	295	297=	297	325	326
		335=	335	354	354	366	366	378	378	378	379	384	392	392	403	403	403	403
		403	408	408	408	408	408	414	420	420	422	425	425	426	426	431	431	433
		443	444	445	446	447	448	450	451	452	453	460=	460	469	470	471	472	473
		474	476=	476	485	5094	519	514=	514	522	547	551=	551	558	558	560=	560	563
		563	564=	564	583	584	584	585	585	594=	594	619	620	621	622	623	624	625
		628	629	631	631	632	632	634=	634	648	670	671	672	673	696	703=	703	718
		724	726	730=	730	787	788	784	790	794	795	797=	797	819	824	825	834=	834
		848	854	858	862=	862	884	864=	889	897	897	898	898	900	901	903	903	904
		904	906	907	908=	908	911=	911	939=	940	940							
IJWA	-I	485=	489	497	500	500	522=	528	530	530	546							



KP	-I	91500	916	917	919														
KPN	-I	914=	945=	945	946	947	949												
KREQ	-I	478=	483	484	485	501	520	521	522	533	539	557	558	563	566=	566	567	616=	
		630	635=																
KRET	-I	68AS	70AS	79															
KRF	-I	263AS	264	267AS	272=	281	286												
KRFP	-I	265AS	268AS	272															
KROUT	-I	32AS	132	342															
KRP	-I	264=	273AS	289	294														
KH1	-I	224AS	231AS	238AS	245AS	250													
KV	-R	3CO	7RL																
KV00RSQ	-R	3CO	7RL	427															
KV00ZSQ	-R	3CO	7RL	427															
K1	-I	212=	213=	217	217	219	226												
K2	-I	212=	214=	217	217	226	233												
K3	-I	212=	215=	217	217	219	240												
K4	-I	212=	216=	217	217	233	240												
L	-I	110=	111AG	123=	124	144=	157	158	158	169D0	170	199WR	277=	279WR	279WR	279WR	279WR	279WR	
		279WR	279WR	279WR	279WR	279WR	279WR	279WR	279WR	279WR	279WR	279WR	287PR	287WR	287WR	287WR	287WR	287WR	
		287PR	287PR	287PR	287PR	287PR	287PR	287PR	287PR	287PR	287PR	339WR	339WR	340PR	340PR				
LCM	-I	3CO	74	84															
LINONT	-	104SU	119SU	147SU	198SU	269SU													
LINESF	-I	280=	280	281	283=														
LINESP	-I	288=	288	289	291=														
LL	-I	218=	246=	246	248	249	250	254=											
LH1	-I	170=	176	181															
LOCF	-	82SU	82SU																
LOOP	-	48SU	140SU	166SU	180SU	188SU	259SU	296SU	338SU	467SU	511SU	552SU	561SU	595SU	613SU	636SU	704SU	732SU	
		799SU	835SU	864SU	890SU	910SU													
LPR	-I	3CO	30	40	72	91	103	116	131	132	266	278	339	340					
MUSTIT	-I	70R=	727=	727	802	803	804=	839=	855=	855	867	868	869=						
MUSTPR	-I	3CO	29PR	30WR	802=														
MUSTRD	-I	3CO	29PR	30WR	837=	867=													
N	-I	73WR	73WR	74WR	74WR	83RD	83RD	84RD	84RD										
NAME	(I)	3CO	90PR	93WR	104WR	121WR	150WR	201WR	284WR	292PR									
NCYC	-I	3CO	29PR	30WR	34	39=	39	40	71PR	72WR	90PR	93WR	106WR	121WR	131	150WR	201WR	284WR	
		292PR	339WR	340PR	381														
NFR	-I	99=	130=	130	131														
NLC	-I	3CO	74WR	84RD															
NP	-I	107D0	108	109	110	122D0	123	125	126										
NPOT	-I	3CO	98	107D0	122D0	892	91500	949=											
NQ	-I	3CO	47	139	157	164	165	179	187	209	210	277	295	303	304	335	376	346	
		347	459	460	464	464	475	476	486	487	488	489	495	507	508	509	510	523	
		524	525	526	533	549	550	551	559	560	564	571	572	593	594	600	633	634	
		642	643	702	703	712	713	730	731	737	738	797	798	809	810	833	834	843	
		844	862	863	873	874	876	877	888	889	897	898	900	900	901	901	903	904	
		905	906	907	907	908	909	928	930	930	938	940	940						
NOI	-I	3CO	929	939															
NQL	-I	3CO	260	261	517	513	514	911	912										
NOZL	-I	3CO	297																
NSC	-I	3CO	73WR																
NTYPE	-I	112D0	113	114	115AG	120WR	141D0	142	143	144	148WR	149WR							
NUMIT	-I	3CO	29PR	30WR	707=	801=	801	805											
NUMHO	-I	3CO	29PR	30WR	837=	866=	866	870											
NUMTD	-I	3CO	71PR	72WR	7A=	78	85	87=	87										
NUV	-R	3CO	7RL																



RODR	-R	651	680=	681	681	694												
RODRB	-R	759=	761	762	762	763												
RODT	(1R	10DI	11EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ	12EQ
RODTB	-R	780=	782	783	783	784												
RODTEM	-R	316=	318	319	606=	609	609	610	624=	627	627	628						
RODVOL	-R	306=	311	321	326													
RODITAB	(1R	10DI	11EQ	451	455=	470												
ROTR	-R	531=	532	544														
ROUN	(1R	4EQ	8D1	603														
ROUJM	-R	500=	505															
ROUJP	-R	499=	506															
ROULR	-R	493=	506															
ROURR	-R	494=	506	506	506	506	506	506										
ROUR2B	-R	495=	506															
ROUTE	(1R	4EQ	8D1	506=	510=	510	557											
ROUV	(1R	4EQ	8D1	557=	604													
ROVR	-R	546=	547	547	672=	674	675											
ROV2B	-R	530=	544															
ROVD	(1R	4EQ	8D1	621														
ROVTM	-R	537=	544															
ROVTP	-R	538=	544															
ROVL	-R	658=	660	661														
ROVPIV	-R	3C0	546	788	824													
ROVPIV1	-R	3C0	825	858														
ROVPR	(1R	4EQ	8D1	279WR	287WR	305	310	314	314	315	315	377	382	386	389	391	394	400
		400	401	401	402	402	403	403	404	404	493	493	494	494	495	495	499	499
		500	500	530	530	531	531	533	537	537	538	538	546	546	585	588	591	605
		605	623	623	658	658	672	672	679	679	686	686	700	724	812=	816	821=	821
		824	824	824	827=	827	830=	830										
ROVPR1	(1R	4EQ	8D1	577=	581=	585=	588=	591=	723	724	724	724	724	744	745=	748=	757	758
		767=	778	779	788=	793=	812											
ROVPR1C	-R	723=	724	724	724	724	724											
ROVPR1N	-R	745=	748	758	767	779	788	788										
ROVPR1C	-R	744=	757	778	853=	854	854	854	856=	857	858	858	859	860				
ROVPR1	(1R	4EQ	8D1	279WR	287WR	309	310	382	383	387	385	385	400	400	401	401	402	402
		403	403	404	404	818	854	862=	883=	883	884=	884	884	885=	885	886=	886	
ROVPR1T	(1R	4EQ	8D1	814=	816=	818=	822=	822	825=	825	825	828=	828	831=	831	853	854	854
		854	854	856=	857=	858=	859=	860=	882									
ROVPR2	-R	382=	383	383														
ROVR	-R	679=	681	692														
ROVR2B	-R	758=	762	764														
ROVR2B0	-R	757=	760															
ROVSPL	(1R	5EQ	9D1	533														
ROVT	-R	686=	688	689														
ROVTB	-R	532=	544	544	544	544	544											
ROVTBN	-R	779=	783	785														
ROVTB0	-R	778=	781															
ROVTE	(1R	4EQ	8D1	544=	547=	547	548=	548	558	563								
ROVTEM	-R	315=	317	319	605=	609	611	623=	627	629								
ROVT2B	-R	533=	544															
ROVV	(1R	4EQ	8D1	558=	563=	622												
ROVVOL	-R	305=	308	320	325													
ROVB	-R	3C0	577	745														
RPCDR	-R	3C0	394															
RPCDF	-R	3C0	394															



T	-R	3C0	29PR	30WR	33	38	51	51	52=	52	63	71PR	72WR	90PR	93WR	106WR	121WR	150WR
TSASE	-R	201WR	284WR	292PR	339WR	340PR												
TDB	-R	19AG	20	37														
TDC	-R	408=	434	434	434	434	434	434										
TDL	-R	406=	434															
TDR	-R	407=	434															
TDT	-R	409=	434															
TERM1B	-R	667=	675=	693														
TERM1L	-R	653=	661=	692														
TERM1R	-R	653	682=	694														
TERM1T	()R	10DI	11EQ	667	689=	695												
TERM2R	-R	668=	676=	693														
TERM2L	-R	654=	662=	692														
TERM2R	-R	654	683=	694														
TERM2T	()R	10DI	668	690=	695													
TH	()R	4EQ	8DI	176	279WR	287PR	307	376	410	412	414	416	436=	443=	450=	461=	469=	469=
		577	602	602	620	620	657	657	671	671	678	678	685=	685=	691=	714=	740=	745=
		752	773															
THBB	-R	414=	415	426	427													
THIJ	-R	376=	410	412	414	416												
THIN	-R	3C0	443															
THLB	-R	410=	411	426	427													
THRB	-R	412=	413	426	427	752=	760	761										
THTAB	()R	10DI	11EQ	11EQ	11EQ	11EQ	11EQ	11EQ	11EQ	11EQ	450	454=	469					
THTB	-R	416=	417	426	427	773=	781	782										
THTE	-R	380=	381	383	387	387	388	393	396=	424	436	443	443	454	461	602=	603	604
		620=	621	622														
THTEB	-R	664=	671=	675	676	696												
THTEC	-R	740=	752	773														
THTEL	-R	650=	657=	661	662	696												
THTER	-R	650	678=	682	683	696												
THTERM	-R	393=	394															
THTESQ	-R	387=	389	393														
THTET	()R	10DI	11EQ	664	685=	689	690	696										
THO	-R	3C0	381	424	691	714												
TLIM	-R	22=	24=	24	37	88=	88											
TLIMD	-R	3C0	24	88														
TOLD	-R	18DA	26=	28														
TOP	-R	3C0	548	794	795													
TOUT	-R	3C0	33	51	51	62=	62	64=										
TVB	-R	403=	427															
TVC	-R	400=	427	427	427	427	427	434										
TVL	-R	401=	427															
TVR	-R	402=	427															
TVT	-R	404=	427															
TWFTN	-R	3C0	38															
T1	-R	20=	36	67=														
T2	-R	18DA	26	27AG	28	29PR	30WR	36	37	67								
TZOMD	-R	3C0	36															
UC	-R	491=	502	502	506													
UD	()R	4EQ	8DI	45	138	279WR	287PR	314	326	326	340	360	363	363	374	375	392	392
		425	426	426	426	433	433	611=	726	726	754	764=	769=	769	901=	901	907=	907
UDRL	-R	375=	378	379	429													
UDRR	-R	374=	378	379	436													
UDTE	-R	754=	756	761														





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XIT	-R	541=	544	544															
XITL	-R	542=	544	544															
XITR	-R	505=	506	506	543=	544	544												
XIVB	-R	354=	355	356	722=	724	724	852=	854	854									
XIVL	-R	348=	349	350	720=	724	724	850=	854	854									
XIVR	-R	351=	352	353	719=	724	724	849=	854	854									
XIVT	-R	357=	358	359	721=	724	724	851=	854	854									
XL	-R	3C0	108	125	159	160	248												
XP	( )R	3C0	108	110	123	125	916	919	946=										
XTE	-R	916=	921	922	931	932	941=	941	943	946									
XX	-R	28=	29PR	30W4	182=	186	190=	191	192	247=	248	249	601=	603	604	619=	621	622	
X1	( )R	10DI	11EQ	156=	157	159	207=	207=	208=	208=	208	248	248	248					
X2	-R	157=	160																
YB	-R	3C0	107	126	154	161	249												
YCONV	-R	3C0	109	126	154	161	249												
YP	( )R	3C0	109	126	917	947=													
YTE	-R	917=	924	925	934	935	942=	942	944	944	947								
Y1	( )R	10DI	11EQ	153=	154	158	204=	204=	205=	205=	205	249	249	249					
Y2	-R	158=	161																
ZZ	-R	3C0	82																

## LIST OF ALL VARIABLES DEFINED IN INPUT

C MEANS VARIABLE WAS DEFINED IN COMMON IN THAT ROUTINE  
 D MEANS VARIABLE WAS DEFINED IN OTHER DECLARATIONS  
 NON-BLANK NUMERIC IS NUMBER OF NON-DECLARATORY REFERENCES  
 S PRECEDING MEANS SUBROUTINE (PROGRAM-FUNCTION) NAME  
 L PRECEDING MEANS COMMON(LCN) NAME  
 F PRECEDING MEANS FORTRAN KEYWORD  
 \* PRECEDING MEANS VARIABLE IS DECLARED, NOT USED ANYWHERE

VARIABLE	ROUTINE	TYPE	ROUTINE	TYPE	ROUTINE	TYPE	ROUTINE	TYPE
A	KACHINA	D	SETUP	D	HYDRO	10D		
AA	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	3C
AAROW	KACHINA	CD	LOOP	1C	SETUP	CD	HYDRO	CD
AASC	KACHINA	CD	LOOP	1C	SETUP	1CD	HYDRO	CD
AA1	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	2C
S ABS	HYDRO	14						
S ADV	HYDRO	6						
S AFSREL	HYDRO	4						
AKINF1	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	2C
S AMAX1	SETUP	1	HYDRO	6				
S AHINI	HYDRO	2						
F ASSIGN	SETUP	2	HYDRO	12				
AD	KACHINA	1C	LOOP	C	SETUP	1C	HYDRO	24C
BDTODR	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	13C
BDTODZ	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	13C
BD1	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	5C
BD2	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	5C
BINF	KACHINA	C	LOOP	C	SETUP	7C	HYDRO	7C
BOUT	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	5C
BS	HYDRO	3						
BV1	KACHINA	C	LOOP	C	SETUP	4C	HYDRO	6C
BV1GM11	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C
BV2	KACHINA	C	LOOP	C	SETUP	4C	HYDRO	6C
BV2GM12	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C
B0	KACHINA	1C	LOOP	C	SETUP	3C	HYDRO	2C
CDR	KACHINA	1C	LOOP	C	SETUP	2C	HYDRO	C
CFXB	HYDRO	4						
CFXL	HYDRO	4						
CFXR	HYDRO	4						
CFXT	HYDRO	4						
S CLOCK1	KACHINA	1						
S COLOR	HYDRO	2						
COLOUR	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C
F COMMON	KACHINA	2	LOOP	2	SETUP	2	HYDRO	2
CON	HYDRO	8D						
CONV	HYDRO	7						
CQ	KACHINA	D	SETUP	D	HYDRO	13D		
CS	HYDRO	3						
C1	KACHINA	1C	LOOP	C	SETUP	C	HYDRO	6C
S DATAREL	HYDRO	1						
F DATA	SETUP	2	HYDRO	6				
S DATE1	KACHINA	1						
F DIMENS1	SETUP	3	HYDRO	3				
DONE	LOOP	1	SETUP	2	HYDRO	15		
DPC	HYDRO	3						

	DPD0DR	HYDRO	3						
	DPD00Z	HYDRO	3						
	DPR	HYDRO	3						
	DPRT	KACHINA	D	SETUP	D	HYDRO	5D		
	DPT	HYDRO	3						
	DQ	HYDRO	3						
	DR	KACHINA	1C	LOOP	C	SETUP	10C	HYDRO	5C
	DROU	HYDRO	3						
	DROZ	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C
	DRSQ	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C
S	DRV	HYDRO	2						
	DS	HYDRO	3						
	DT	KACHINA	C	LOOP	C	SETUP	8C	HYDRO	15C
	DTIL	HYDRO	4						
	DTK	HYDRO	36						
	DTKBC	HYDRO	3						
	DTKDE	HYDRO	3						
	DTKDU	HYDRO	3						
	DTKDV	HYDRO	3						
	DTKR	KACHINA	D	SETUP	D	HYDRO	10D		
	DTKRSV	HYDRO	3						
	DTKT	KACHINA	D	SETUP	D	HYDRO	8D		
	DTO	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	2C
	DTOC	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	2C
	DTODR	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	14C
	DTODZ	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	14C
	DTOP	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	5C
	DTPOS	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	2C
	DZ	KACHINA	1C	LOOP	C	SETUP	7C	HYDRO	6C
	DZ0Z	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	C
	DZSQ	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C
	D1	KACHINA	1C	LOOP	C	SETUP	C	HYDRO	6C
	E	KACHINA	D	SETUP	D	HYDRO	5D		
S	EMPTY	KACHINA	1	HYDRO	2				
	EM10	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	8C
	EM3	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	C
	EM6	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C
F	ENTRY	LOOP	9						
	EPD	KACHINA	D	SETUP	2D	HYDRO	D		
	EPS	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C
	EPV	KACHINA	CD	LOOP	C	SETUP	2CD	HYDRO	2CD
	EP10	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	2C
	EP20	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	2C
	EP9	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	2C
F	EQUIVAL	KACHINA	3	SETUP	3	HYDRO	5		
	ES	HYDRO	3						
	F	KACHINA	D	SETUP	D	HYDRO	7D		
	FIBAR	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	1C
	FILM	KACHINA	2						
	FIXL	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	5C
	FIXR	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C
	FIYB	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	5C
	FIYT	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C
	FJBAR	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	1C
S	FLOAT	SETUP	9	HYDRO	8				
	FNB	SETUP	3						

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FNL	SETUP	3								
FNPUA	SETUP	4								
FNR	SETUP	2								
FNT	SETUP	2								
F FORMAT	KACHINA	1	KASET	1	SETUP	17	KACHYDR			
FR	HYDR0	2						HYDR0	13	
S FRAME	HYDR0	4								
FSET12	KACHINA	1								
FSET7	KACHINA	1								
FSET8	KACHINA	1								
FSET9	KACHINA	1								
FZ	HYDR0	2								
G	KACHINA	C	LOOP	C	SETUP	1C	HYDR0		1C	
GAMTE	HYDR0	2								
GAM1	KACHINA	C	LOOP	C	SETUP	4C	HYDR0		C	
GAM2	KACHINA	C	LOOP	C	SETUP	4C	HYDR0		C	
GDT	KACHINA	C	LOOP	C	SETUP	1C	HYDR0		2C	
S GET0	KACHINA	1	HYDR0	1						
GGM11	KACHINA	C	LOOP	C	SETUP	1C	HYDR0		1C	
GGM12	KACHINA	C	LOOP	C	SETUP	1C	HYDR0		1C	
GIROM	HYDR0	2							1C	
GM11	KACHINA	C	LOOP	C	SETUP	3C	HYDR0		C	
GM12	KACHINA	C	LOOP	C	SETUP	3C	HYDR0		C	
HEIGHT	SETUP	3								
HXX	HYDR0	6								
HXXIDR	HYDR0	4								
HXXIDL	HYDR0	4								
HXXIDR	HYDR0	4								
HXXIDT	HYDR0	4								
HXXIVB	HYDR0	2								
HXXIVL	HYDR0	2								
HXXIVR	HYDR0	2								
HXXIVT	HYDR0	2								
HXY	HYDR0	6								
HDX	HYDR0	8								
HDXIDR	HYDR0	4								
HDXIDL	HYDR0	4								
HDXIDR	HYDR0	4								
HDXIDT	HYDR0	4								
HDXIVB	HYDR0	2								
HDXIVL	HYDR0	2								
HDXIVR	HYDR0	2								
HDXIVT	HYDR0	2								
HPY	HYDR0	8								
S HYDR0	KACHINA	1	HYDR0	1						
I	KACHINA	C	LOOP	1C	SETUP	21C	HYDR0		99C	
IARRT	KACHINA	2C	LOOP	C	SETUP	1C	HYDR0		C	
IALL	KACHINA	C	LOOP	C	SETUP	1C	HYDR0		C	
IBAP	KACHINA	2C	LOOP	C	SETUP	4C	HYDR0		C	
IBOT	SETUP	4								
IC	HYDR0	7								
ICMAR	HYDR0	2								
ICMARS	HYDR0	2D								
IC1	HYDR0	8								
IC2	HYDR0	6								
INDCMP	SETUP	2D								

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I000N	WYDRO	10						
I00P	WYDRO	10						
I070	KACMINA	C	LOOP	C	SETUP	10	WYDRO	0C
I0VV	WYDRO	10						
I1	WYDRO	2						
I1J	KACMINA	C	LOOP	0C	SETUP	20C	WYDRO	09C
I1JA	WYDRO	15						
I1JM	KACMINA	C	LOOP	3C	SETUP	0C	WYDRO	09C
I1JH	WYDRO	10						
I1JP	KACMINA	C	LOOP	3C	SETUP	3C	WYDRO	70C
I1JA	WYDRO	12						
I1J1	WYDRO	5						
I1J2	WYDRO	5						
I1K	WYDRO	8						
I1WJ	WYDRO	73						
I1WJA	WYDRO	8						
I1WJA	WYDRO	3						
I1W	SETUP	10						
I1W	KACMINA	1						
I1PJ	WYDRO	69						
I1WJA	WYDRO	10						
I1WJA	WYDRO	3						
I1WJA	WYDRO	5						
I1WJA	WYDRO	6						
I1P1	KACMINA	C	LOOP	C	SETUP	3C	WYDRO	25C
I1P2	KACMINA	C	LOOP	C	SETUP	4C	WYDRO	3C
I1P0	KACMINA	C	LOOP	C	SETUP	2C	WYDRO	1C
I1OP	SETUP	4						
I1L	KACMINA	C	LOOP	C	SETUP	1C	WYDRO	4C
I10	KACMINA	C	LOOP	C	SETUP	1C	WYDRO	4C
I11	WYDRO	110						
I12	WYDRO	30						
I10	KACMINA	C	LOOP	C	SETUP	1C	WYDRO	4C
I1Y	KACMINA	C	LOOP	C	SETUP	1C	WYDRO	4C
I1Y	WYDRO	110						
I1Z	WYDRO	30						
J	KACMINA	C	LOOP	0C	SETUP	10C	WYDRO	09C
J000	KACMINA	1C	LOOP	C	SETUP	4C	WYDRO	5C
J1	LOOP	2						
J1M	KACMINA	1C	LOOP	C	SETUP	C	WYDRO	0C
J1SC	WYDRO	2						
J1P1	KACMINA	C	LOOP	C	SETUP	4C	WYDRO	20C
J1P2	KACMINA	C	LOOP	C	SETUP	5C	WYDRO	3C
J1RIG10	KACMINA	C	LOOP	C	SETUP	3C	WYDRO	C
J10	WYDRO	4						
J10P	KACMINA	C	LOOP	C	SETUP	1C	WYDRO	1C
J11	KACMINA	C	LOOP	1C	SETUP	1C	WYDRO	1C
J12	KACMINA	C	LOOP	1C	SETUP	1C	WYDRO	1C
J13	KACMINA	C	LOOP	1C	SETUP	1C	WYDRO	1C
J2	KACMINA	C	LOOP	C	SETUP	3C	WYDRO	1C
J3	KACMINA	C	LOOP	C	SETUP	3C	WYDRO	1C
K	LOOP	3						
S	KACMINA	1						
S	KACMINA	1						
S	KACMINA	1						
K0	KACMINA	00	LOOP	C	SETUP	400	WYDRO	00

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	KDODRSQ	KACHINA	CD	LOOP	C	SETUP	1CD	HYDRO	1CD
	KDODZSQ	KACHINA	CD	LOOP	C	SETUP	1CD	HYDRO	1CD
	KF	SETUP	3						
	KFLG	HYDRO	3						
	KIJ	KACHINA	D	SETUP	D	HYDRO	23D		
	KK	LOOP	2						
	KL	SETUP	2						
	KMAT	SETUP	2	HYDRO	6				
	KHATS	SETUP	1D	HYDRO	1D				
	KP	HYDRO	4						
	KPN	HYDRO	6						
	KREQ	HYDRO	14						
	KRET	SETUP	H	HYDRO	3				
	KRF	HYDRO	6						
	KRFP	HYDRO	3						
	KROUT	HYDRO	3						
	KRP	HYDRO	4						
	KRI	HYDRO	5						
L	KSB	KACHINA	1	LOOP	1	SETUP	1	HYDRO	1
L	KSC	KACHINA	1	LOOP	1	SETUP	1	HYDRO	1
	KT	SETUP	11						
	KV	KACHINA	CD	LOOP	C	SETUP	4CD	HYDRO	CD
	KVODRSQ	KACHINA	CD	LOOP	C	SETUP	1CD	HYDRO	1CD
	KVODZSQ	KACHINA	CD	LOOP	C	SETUP	1CD	HYDRO	1CD
	K1	HYDRO	6						
	K2	HYDRO	6						
	K3	HYDRO	6						
	K4	HYDRO	6						
	L	HYDRO	49						
	LCM	KACHINA	C	LOOP	1C	SETUP	1C	HYDRO	2C
	LCHFLG	LOOP	1	SETUP	1				
S	LINCNT	HYDRO	5						
	LINESF	HYDRO	4						
	LINESP	HYDRO	4						
	LL	HYDRO	7						
	LH1	HYDRO	3						
S	LOCF	SETUP	4	HYDRO	2				
S	LOOP	LODP	1	SETUP	2	HYDRO	22		
	LPR	KACHINA	C	LOOP	C	SETUP	5C	HYDRO	12C
	MUSTIT	HYDRO	12						
	MUSTPR	KACHINA	C	LOOP	C	SETUP	C	HYDRO	3C
	MUSTPO	KACHINA	C	LOOP	C	SETUP	C	HYDRO	4C
	N	SETUP	12	HYDRO	8				
	NAME	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	8C
	NB	SETUP	5						
	NB2	SETUP	2						
	NCYC	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	20C
	NFR	HYDRO	4						
	NL	SETUP	5						
	NLC	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	2C
	NL2	SETUP	2						
	NP	HYDRO	8						
	NPTDT	KACHINA	C	LOOP	C	SETUP	7C	HYDRO	6C
	NPUA	SETUP	5						
	NPX	SETUP	4						
	NPY	SETUP	4						

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NO	KACHINA	1C	LOOP	1C	SETUP	16C	HYDRO	96C
NO1	KACHINA	C	LOOP	5C	SETUP	7C	HYDRO	2C
NO12	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	C
NO1	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	7C
NO2	SETUP	2						
NO2	KACHINA	C	LOOP	3C	SETUP	1C	HYDRO	C
NO2L	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C
NR	SETUP	6						
NR1	SETUP	2						
NSC	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C
NT	SETUP	5						
NTYPE	SETUP	3	HYDRO	11				
NT1	SETUP	2						
NUMIT	KACHINA	C	LOOP	C	SETUP	C	HYDRO	6C
NUMRO	KACHINA	C	LOOP	C	SETUP	C	HYDRO	6C
NUMTD	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	7C
NUV	KACHINA	1CD	LOOP	C	SETUP	2CD	HYDRO	CD
NUV3	KACHINA	CD	LOOP	C	SETUP	1CD	HYDRO	1CD
NVAP	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	2C
OFFSET	SETUP	3						
OMHAS	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C
OMBETA	KACHINA	D	SETUP	D	HYDRO	6D		
OMBSPL	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	2C
OMP	KACHINA	C	LOOP	C	SETUP	5C	HYDRO	1C
OMRO	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C
OMTHBB	HYDRO	3						
OMTHLR	HYDRO	3						
OMTHRB	HYDRO	3						
OMHTB	HYDRO	3						
OUT	KACHINA	2						
S OVERLAY	KACHINA	2						
P	KACHINA	D	SETUP	1D	HYDRO	28D		
PARUL	HYDRO	2						
PARUR	HYDRO	2						
PARVB	HYDRO	2						
PARVT	HYDRO	2						
PC	HYDRO	2						
PI	SETUP	10						
S PLT	HYDRO	5						
PNEFF	SETUP	4						
PNI	SETUP	2						
PP	KACHINA	D	SETUP	D	HYDRO	4D		
PPC	HYDRO	7						
F PRINT	KASET	1	SETUP	3	KACHYDR	1	HYDRO	10
PTE	HYDRO	3						
PUDENL	HYDRO	3						
PUDENR	HYDRO	3						
PVDENB	HYDRO	3						
PVDENT	HYDRO	3D						
Q	HYDRO	3						
QMN	HYDRO	7						
QMX	HYDRO	8						
S QSORT	SETUP	1	HYDRO	1				
R	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	2C
RA	KACHINA	D	SETUP	D	HYDRO	8D		
RBETA	HYDRO	2						



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RCONT	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	3C
RDENOM	HYDRO	12						
RDR	KACHINA	C	LOOP	C	SETUP	8C	HYDRO	2C
RDRSQ	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C
RDT	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	7C
RDZ	KACHINA	C	LOOP	C	SETUP	5C	HYDRO	10C
RDZSQ	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C
F READ	KACHINA	1	SETUP	9	HYDRO	?		
F REAL	KACHINA	1	SETUP	1	HYDRO	1		
F RETURN	LOOP	10	SETUP	2	HYDRO	2		
F REWIND	HYDRO	1						
RI	KACHINA	C	LOOP	C	SETUP	5C	HYDRO	3C
RIBAR	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	C
RIBJB	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C
RIJP2	LOOP	1	HYDRO	1				
RIP	KACHINA	C	LOOP	C	SETUP	5C	HYDRO	28C
RJBAR	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	C
RMSO	HYDRO	2						
RODB	HYDRO	5						
RODL	HYDRO	5						
RODPP	KACHINA	D	SETUP	3D	HYDRO	54D		
RODPRC	HYDRO	3						
RODPRI	SETUP	3						
RODPRI1	SETUP	7						
RODPRI2	SETUP	5						
RODPRT	KACHINA	D	SETUP	D	HYDRO	3D		
RODPRI	KACHINA	D	SETUP	3D	HYDRO	29D		
RODPRI1	HYDRO	7						
RODR	HYDRO	5						
RODRAT	SETUP	3						
RODRB	HYDRO	5						
RODT	HYDRO	5D						
RODTB	HYDRO	5						
RODTEM	HYDRO	11						
RODVOL	HYDRO	4						
RODJTAB	HYDRO	3D						
ROTB	HYDRO	3						
ROUO	KACHINA	D	SETUP	D	HYDRO	1D		
ROUJM	HYDRO	2						
ROUJP	HYDRO	2						
ROULB	HYDRO	2						
ROURB	HYDRO	6						
ROUR2B	HYDRO	2						
ROUTE	KACHINA	D	SETUP	D	HYDRO	4D		
ROUV	KACHINA	D	SETUP	D	HYDRO	2D		
ROVB	HYDRO	6						
ROVBB	HYDRO	2						
ROVD	KACHINA	D	SETUP	D	HYDRO	1D		
ROVIN	HYDRO	2						
ROVIN1	SETUP	4						
ROVIN2	SETUP	3						
ROVIP	HYDRO	2						
ROVL	HYDRO	3						
ROVPTN	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	3C
ROVPI1	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	3C
ROVPR	KACHINA	D	SETUP	6D	HYDRO	73D		

ROVPR1	SETUP	4							
ROVPR11	SETUP	5							
ROVPR12	SETUP	3							
ROVPR1T	KACHINA	D	SETUP	D	HYDRO	21D			
ROVPR1T	HYDRO	6							
ROVPR1T	HYDRO	14							
ROVPR1T	HYDRO	10							
ROVPR1	KACHINA	D	SETUP	6D	HYDRO	31D			
ROVPR1T	KACHINA	D	SETUP	D	HYDRO	23D			
ROVPR2	HYDRO	3							
ROVR	HYDRO	3							
ROVRBN	HYDRO	3							
ROVRB0	HYDRO	2							
ROVSPL	KACHINA	D	SETUP	D	HYDRO	1D			
ROVT	HYDRO	3							
ROVTB	HYDRO	6							
ROVTBN	HYDRO	3							
ROVTB0	HYDRO	2							
ROVTE	KACHINA	D	SETUP	D	HYDRO	7D			
ROVTEM	HYDRO	9							
ROVT28	HYDRO	2							
ROVV	KACHINA	D	SETUP	D	HYDRO	3D			
ROVVOL	HYDRO	4							
ROV0	KACHINA	1C	LOOP	C	SETUP	1C	HYDRO	2C	
ROV1	SETUP	6							
ROV2	SETUP	5							
RO1	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C	
RO2	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C	
RPAR	KACHINA	1C	LOOP	C	SETUP	3C	HYDRO	C	
RPARU	LOOP	1	HYDRO	1					
RPARV	LOOP	1	HYDRO	1					
RPCDR	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C	
RPCOF	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C	
RR	HYDRO	6							
RR1	KACHINA	C	LOOP	C	SETUP	4C	HYDRO	7C	
RR1DR	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	8C	
RR1P	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C	
RR01	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C	
RR02	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C	
RS	HYDRO	3							
R1ROW	LOOP	1	SETUP	1					
R2A	HYDRO	5							
R2DR	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	2C	
R2DZ	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	2C	
SE	HYDRO	2D							
S SECOND	HYDRO	2							
SED	HYDRO	2D							
SET:J	LOOP	1	SETUP	1					
S SETUP	KASET	1	SETUP	1					
SEV	HYDRO	2D							
SIED	KACHINA	D	SETUP	3D	HYDRO	18D			
SIEDC	HYDRO	8							
SIEDEL	HYDRO	4							
SIEDT	SETUP	4							
SIEDTAB	HYDRO	3D							
SIEDTE	HYDRO	5							

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	STEV	KACHINA	D	SETUP	0D	HYDRO	20D		
	SIEVC	HYDRO	9						
	SIEVT	SETUP	5						
	SIEVTH	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	1C
	SIEVTAB	HYDRO	3D						
	SIEVTE	HYDRO	7						
S	SIGN	HYDRO	26						
	SINTE	HYDRO	2D						
	SINTEO	HYDRO	2D						
	SINTEV	HYDRO	2D						
	SKE	HYDRO	2D						
	SKED	HYDRO	2D						
	SKEV	HYDRO	2D						
	SMD	HYDRO	2D						
	SMD1	HYDRO	2D						
	SMD2	HYDRO	2D						
	SMOMR	HYDRO	2D						
	SMOMZ	HYDRO	2D						
	SMOMZD	HYDRO	2D						
	SMOMZV	HYDRO	2D						
	SMV	HYDRO	2D						
	SMV1	HYDRO	2D						
	SMV2	HYDRO	2D						
	SPSUMS	HYDRO	3D						
	SC40	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C
	SR0V1	SETUP	5						
	SR0V2	SETUP	5						
	SS	HYDRO	3						
	START	LOOP	1	SETUP	2	HYDRO	22		
	STED	HYDRO	3						
	STEV	HYDRO	3						
	STM	HYDRO	2D						
	STIED	HYDRO	4						
	STIEV	HYDRO	4						
	STKED	HYDRO	4						
	STKEV	HYDRO	4						
	T	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	21C
	TBASE	HYDRO	3						
	TDB	HYDRO	2						
	TDC	HYDRO	7						
	TDL	HYDRO	2						
	TDR	HYDRO	2						
	TDI	HYDRO	2						
	TERM1B	HYDRO	3						
	TERM1L	HYDRO	3						
	TERM1R	HYDRO	3						
	TERM1T	HYDRO	3D						
	TERM2B	HYDRO	3						
	TERM2L	HYDRO	3						
	TERM2R	HYDRO	3						
	TERM2T	HYDRO	3D						
	TH	KACHINA	D	SETUP	6D	HYDRO	34D		
	THBB	HYDRO	4						
	THI	SETUP	10						
	THIJ	HYDRO	5						
	THIN	KACHINA	C	LOOP	C	SETUP	5C	HYDRO	1C

THLB	HYDRO	4						
THRB	HYDRO	7						
THTAB	HYDRO	30						
THTB	HYDRO	7						
THTE	HYDRO	20						
THTEB	HYDRO	5						
THTEC	HYDRO	3						
THTEL	HYDRO	5						
THTER	HYDRO	5						
THTERM	HYDRO	2						
THTESQ	HYDRO	3						
THTET	HYDRO	50						
THO	KACHINA	6	LOOP	C	SETUP	1C	HYDRO	4C
TLIM	HYDRO	6						
TLIMD	KACHINA	20	LOOP	C	SETUP	2C	HYDRO	2C
TOLD	HYDRO	C						
TOP	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	3C
TOUT	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	6C
TVB	HYDRO	2						
TVC	HYDRO	7						
TVL	HYDRO	2						
TVR	HYDRO	2						
TVI	HYDRO	2						
TWFIN	KACHINA	2	LOOP	C	SETUP	2C	HYDRO	1C
T1	HYDRO	3						
T2	HYDRO	80						
T20MD	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	1C
UC	HYDRO	4						
UD	KACHINA	D	SETUP	D	HYDRO	32D		
UDRL	HYDRO	4						
UDRR	HYDRO	4						
UDTE	HYDRO	3						
UK	HYDRO	2						
UR	HYDRO	4						
URB	HYDRO	6						
US	HYDRO	3						
UTB	HYDRO	3						
UTLC	HYDRO	5						
UTRC	HYDRO	5						
UV	KACHINA	D	SETUP	D	HYDRO	57D		
UVL	HYDRO	3						
UVLB	HYDRO	8						
UVR	HYDRO	3						
UVRR	HYDRO	8						
UVRL	HYDRO	2						
UVRR	HYDRO	2						
UVTE	HYDRO	3						
VBRC	HYDRO	5						
VC	HYDRO	4						
VCON	SETUP	3						
VD	KACHINA	D	SETUP	D	HYDRO	40D		
VDTE	HYDRO	3						
VECVEL	HYDRO	2						
VEL	HYDRO	7						
VELMX	HYDRO	17D						
VK	HYDRO	2						

INDEX		01/00/75		MASTER INDEX				
VOL	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	6C
VOLR	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C
VRB	HYDRO	4						
VS	HYDRO	3						
VT	HYDRO	4						
VYB	HYDRO	6						
VTRC	HYDRO	5						
VV	KACHINA	D	SETUP	1D	HYDRO	62D		
VVB	HYDRO	3						
VVBB	HYDRO	8						
VVIN	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	2C
VVT	HYDRO	3						
VVTB	HYDRO	8						
VVTE	HYDRO	3						
WIDTH	SETUP	4						
F WRITE	SETUP	11	HYDRO	20				
WIR0W	LOOP	1	SETUP	1				
XCONV	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	5C
XD	SETUP	5						
XIBR	HYDRO	3						
XIC	HYDRO	6						
XIOB	HYDRO	3						
XIOL	HYDRO	3						
XIDR	HYDRO	3						
XIDT	HYDRO	3						
XIR	HYDRO	3						
XIT	HYDRO	3						
XITL	HYDRO	3						
XITR	HYDRO	6						
XIVB	HYDRO	9						
XIVL	HYDRO	9						
XIVR	HYDRO	9						
XIVT	HYDRO	9						
XL	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	5C
XNP	SETUP	3						
XP	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	7C
XR	KACHINA	C	LOOP	C	SETUP	2C	HYDRO	C
XSPAC	SETUP	3						
XTE	SETUP	4	HYDRO	10				
XX	HYDRO	17						
X1	SETUP	2	HYDRO	11D				
X2	HYDRO	2						
YB	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	5C
YCONV	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	5C
YHP	SETUP	2						
YP	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	4C
YSPAC	SETUP	3						
YT	KACHINA	C	LOOP	C	SETUP	3C	HYDRO	C
YTE	HYDRO	10						
YY	SETUP	7						
Y1	SETUP	4	HYDRO	11D				
Y2	HYDRO	2						
ZZ	KACHINA	C	LOOP	C	SETUP	1C	HYDRO	1C

ROUTINES INDEXED

ROUTINE	PAGE	ROUTINE	PAGE	ROUTINE	PAGE	ROUTINE	PAGE	ROUTINE	PAGE	ROUTINE	PAGE	ROUTINE	PAGE
DONE	5	KACHINA	2	KASET	8	LOOP	5	RPARU	5	RIROW	5	SETUP	10
HYDRO	25	KACHYDR	23	LCMFLG	5	RIJP2	5	RPARV	5	SETIJ	5	START	5
MASTER INDEX	59												

\*\*\*\*\*END OF COMPUTATION\*\*\*\*\*

1535 CARDS PROCESSED

3084 MAXIMUM BUFFER USED BY ANY ROUTINE

2048 TOTAL ECS REQUIRED BY INDEX

5.868 SECONDS OF CP TIME USED

\*\*\*\*\*

APPENDIX C

MODIFICATIONS FOR LCM STORAGE OF CELL DATA

The basic SCM version of KACHINA shown in Appendixes A and B has been purposely designed so that both the (1,0) and (2,0) overlays are completely compatible with LCM usage and require no modifications in conversion to LCM storage of cell data. This limits the necessary changes to the following two places in the (0,0) overlay.

(1) Storage Definition. An LCM cell-storage block is defined, and the SCM buffer AASC is shortened and moved out of the main common KSC into the scratchpad common KSB. Thus, the beginning of the storage definition card set reads as follows.

```
LCM/KLC1/AAL(131000)
COMMON/KSB/AASC(5814),AAROW(1938)
COMMON/KSC/AA(1),AKINFI,AO,BDTODR,BDTODZ,
(etc.)
```

The dimension of 5814 words for AASC allows any  $\bar{I} \leq 100$  with  $NQ = 19$  words per cell.  $\bar{J}$  is limited only by available LCM.

(2) Cell Data Handling. The entire instruction part of SUBROUTINE LOOP is replaced by the following version.

```
CALL ECWR (AASC(JW),IECW,NQI,NE)
IECW = IECW + NQI
GO TO (10, 20, 30) IBUF
10 JR = 1
JW = J2
IJP = JX1
IJ = JX3
IJM = JX2
IBUF = 2
GO TO 40
20 JR = J2
JW = J3
IJP = JX2
IJ = JX1
IJM = JX3
```

```
IBUF = 3
GO TO 40
ENTRY START
CALL ECRD (AASC,0,NQI2,NE)
IECR = NQI2
IECW = 0
30 JR = J3
JW = IBUF = 1
IJP = JX3
IJ = JX2
IJM = JX1
40 CALL ECRD (AASC(JR),IECR,NQI,NE)
IECR = IECR + NQI
RETURN
ENTRY DONE
CALL ECWR (AASC(JW),IECW,NQI,NE)
IECW = IECW + NQI
GO TO (50, 60, 70) IBUF
50 JW = J2
GO TO 80
60 JW = J3
GO TO 80
70 JW = 1
80 CALL ECWR (AASC(JW),IECW,NQI,NE)
RETURN
ENTRY RIROW
IEC = (J - 1) * NQI
CALL ECRD (AASC,IEC,NQI,NE)
RETURN
ENTRY SETIJ
IJ = (I - 1) * NQ + 1
RETURN
ENTRY WIROW
```

```

CALL ECWR (AASC,IEC,NQI,NE)
RETURN
ENTRY LCMFLG
LCM = 1
RETURN
ENTRY RIJP2
CALL ECRD (AARØW,IECR,NQI,NE)
RETURN
ENTRY RPARU
IEC = (J - 1) * NQI
IJ = 0
CØ TØ 300
ENTRY RPARV
IEC = (J - 2) * NQI
IJ = NQI
300 CALL ECRD (AASC,IEC,NQI2,NE)
RETURN
END

```

The SETUP and HYDRØ subroutines contain several peculiarities that are specially treated to make them compatible with either SCM or LCM usage. The required modifications deserve some explanation.

(1) The routine that initially sets all required cell-storage to zeros (DØ loops 189 and 199 in SETUP) is designed to handle either SCM or LCM cell storage automatically without testing.

(2) Note that the SCM version of ENTRY LØØP advances the three row indices IJ, IJP, and IJM over two columns of cells ( $i = IP2$  and  $i = 1$ ), the assumption being that the I DØ loops normally encompass all interior cells in the row ( $i = 2$  through  $i = IP1$ ). Several DØ loops in the code, however, have I DØ loops with a lesser or greater range of columns, requiring some increment or decrement of these indices upon RETURN from LØØP, to keep the indexing properly phased.

In the LCM version, though, such adjustments are unnecessary, as here LØØP invariably sets IJ, IJP, and IJM to point to column  $i = 2$  cells. This distinction between the versions is handled automatically because the values of the increments or decrements

used (NQL and NQ2L) are set to zero in SETUP in the LCM version. Again, this allows affected DØ loops to be fully general with no required testing of whether SCM or LCM is being used.

In the present version, I DØ loops so treated are those with terminal statement numbers of 189 in SETUP, and 779, 889, 1539, and 3189 in HYDRØ. Remember that a similar treatment may be required if new code is constructed that has I DØ loops with ranges other than the usual  $i = 2$  through  $i = IP1$ .

(3) In the calculation of  $(\overline{\rho'v})_1^{j+1/2}$  in region 1550 in HYDRØ, reference is made to  $(\overline{\rho'v})_1^{j+3/2}$  to obtain a donor cell term for the equation. Because this reference, in turn, involves the use of  $\rho_i^{j+2}$ , which is not available in the three rows that have been read from LCM, cell data from row  $j+2$  must be read in separately. This is the responsibility of ENTRY RIJP2 in LØØP. In the LCM version, it simply reads in row  $j+2$ , whose address is specified by the current setting of the LCM read index, to the one-row buffer AARØW. The statement in region 1550 that calculates  $(\rho'v)_1^{j+3/2}$  (named RØVT2B) then references the density  $(\rho')_1^{j+2}$  (RØVSPL) from this one-row buffer.

The problem of referencing quantities in rows beyond  $j+1$  and  $j-1$  obviously doesn't exist in the pure SCM version, but for compatibility between the two versions, we use ENTRY RIJP2 to place an image of row  $j+2$  in AARØW. Remember that the same technique and buffer are available to any code addition requiring data lying beyond rows  $j+1$  or  $j-1$ .

(4) In the particle movement, the area-weighting scheme requires  $u$  or  $v$  velocities from two adjacent rows of cells. In the LCM version, entries RPARU and RPARV in LØØP obtain the two appropriate rows from LCM, and initialize that part of index IJ that is a function of J.

In the SCM version, these two ENTRY points perform only this latter task, and, again, the procedure is such that the particle mover is not concerned with whether the velocities were obtained from LCM or SCM.

(5) In the Tape Dump and Tape Restart (Regions 250 and 270, respectively, in the HYDRØ Control Region), tests that determine whether LCM data are involved in the dump information are included, so the user need not be concerned with this aspect.

From the above, it can be seen that the philosophy of the LCM package has been to achieve a user-oriented conversion at the expense of some computer



efficiency. The additional CP time required for LCM storage of cell data is not an unreasonable increase over the SCM version. For a sample calculation with  $\bar{I}=20$  and  $\bar{J}=45$ , the LCM version grind time was about 16% greater than that of the SCM version when running at three iterations per cycle. This percentage decreases as the number of iterations increases, becoming less than 13% at 11 iterations per cycle, for example.

In the present version of KACHINA, there is provision in SCM for storing the coordinates of up to 4000 particles. If necessary, particle storage could be effectively doubled by storing coordinates at a half word each, and/or particle storage could also be moved to LCM.

With storage block AASC dimensioned at 26 676 words, as discussed in Sec. II.C, approximately 3500 words of SCM remain available for code expansion. In the LCM conversion described here, this number increases to nearly 20 000 words, and at the same time the available number of cells increases from 1250 to nearly 10 000.

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The SCM KACHINA user who can be sure that his memory requirements are so small that he will never require the LCM compatibility feature can definitely reduce grind time by eliminating SUBROUTINE LOOP entirely and replacing all CALLS to its ENTRY points by copies of the instructions that the SCM version of LOOP performs. In addition, the special considerations of the five items discussed above can be completely eliminated with very little code modification.

One final note concerning LCM usage: be sure to request LCM on both the \$JOB card (we add the field "LC = 400000") and on the \$LDGØ card (we add the field "LC = 1000000B"). Failure to request LCM will cause an immediate LCM Block Range Error and task abortion.

Note in proof: A "CALL DONE" should be added permanently, immediately following statement No. 619 in HYDRØ. (Without this CALL, the LCM version will reference erroneous values in row  $j=JP1$  when constructing contour plots.)