# Program Extraction from Coinductive Proofs and its Application to Exact Real Arithmetic 

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## Eidesstattliche Versicherung

Hermit erkläre ich an Eidesstatt, dass die Dissertation von mir selbstständig, ohne unerlaubte Beihilfe angefertigt ist.

München, 14.11.2013
Kenji Miyamoto

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[^0]
## Abstract

Program extraction has been initiated in the field of constructive mathematics, and it attracts interest not only from mathematicians but also from computer scientists nowadays. From a mathematical viewpoint its aim is to figure out computational meaning of proofs, while from a computer-scientific viewpoint its aim is the study of a method to obtain correct programs. Therefore, it is natural to have both theoretical results and a practical computer system to develop executable programs via program extraction.

In this Thesis we study the computational interpretation of constructive proofs involving inductive and coinductive reasoning. We interpret proofs by translating the computational content of proofs into executable program code. This translation is the procedure we call program extraction and it is given through Kreisel's modified realizability. Here we study a proof-theoretic foundation for program extraction, enriching the proof assistant system Minlog based on this theoretical improvement. Once a proof of a formula is written in Minlog, a program can be extracted from the proof by the system itself, and the extracted program can be executed in Minlog. Moreover, extracted programs are provably correct with respect to the proven formula due to a soundness theorem which we prove. We practice program extraction by elaborating some case studies from exact real arithmetic within our formal theory. Although these case studies have been studied elsewhere, here we offer a formalization of them in Minlog, and also machine-extraction of the corresponding programs.

## Zusammenfassung

Die Methode der Programmextraktion hat ihren Ursprung im Bereich der konstruktiven Mathematik, und stößt in letzter Zeit auf viel Interesse nicht nur bei Mathematikern sondern auch bei Informatikern. Vom Standpunkt der Mathematik ist ihr Ziel, aus Beweisen ihre rechnerische Bedeutung abzulesen, während vom Standpunkt der Informatik ihr Ziel die Untersuchung einer Methode ist, beweisbar korrekte Programme zu erhalten. Es ist deshalb naheliegend, neben theoretischen Ergebnissen auch ein praktisches Computersystem zur Verfügung zu haben, mit dessen Hilfe durch Programmextraktion lauffähige Programme entwickelt werden können.

In dieser Doktorarbeit wird eine rechnerische Interpretation konstruktiver Beweise mit induktiven und koinduktiven Definitionen angegeben und untersucht. Die Interpretation geschieht dadurch, daß der rechnerische Gehalt von Beweisen in eine Programmiersprache übersetzt wird. Diese Übersetzung wird Programmextraktion genannt; sie basiert auf Kreisels modifizierter Realisierbarkeit. Wir untersuchen die beweistheoretischen Grundlagen der Programmextraktion und erweitern den Beweisassistenten Minlog auf der Basis der erhaltenen theoretischen Resultate. Wenn eine Formel in Minlog formal bewiesen ist, läßt sich ein Programm aus dem Beweis extrahieren, und dieses extrahierte Programm kann in Minlog ausgeführt werden. Ferner sind extrahierte Programme beweisbar korrekt bezüglich der entsprechenden Formel aufgrund eines Korrektheitsatzes, den wir beweisen werden. Innerhalb unserer formalen Theorie bearbeiten wir einige aus der Literatur bekannte Fallstudien im Bereich der exakten reellen Arithmetik. Wir entwickeln eine vollständige Formalisierung der entsprechenden Beweise und diskutieren die in Minlog automatisch extrahierten Programme.

## Publications Included in this Thesis

1. Ulrich Berger, Kenji Miyamoto, Helmut Schwichtenberg, and Monika Seisenberger. Minlog - a tool for program extraction supporting algebras and coalgebras. In Andrea Corradini, Bartek Klin, and Corina Cîrstea, editors, CALCO, volume 6859 of Lecture Notes in Computer Science, pages 393-399. Springer, 2011 [BMSS11].
2. Kenji Miyamoto and Helmut Schwichtenberg. Program extraction in exact real arithmetic. Mathematical Structure of Computer Science, 2013. in press [MS13].
3. Kenji Miyamoto, Fredrik Nordvall Forsberg, and Helmut Schwichtenberg. Program extraction from nested definitions. In Sandrine Blazy, Christine Paulin-Mohring, and David Pichardie, editors, ITP, volume 7998 of Lecture Notes in Computer Science, pages 370-385. Springer, 2013 [MFS13].

The author's contribution to the first paper amounts to $25 \%$. The corresponding contents are coinductive definitions in Section 2.3.2, corecursion operators in Section 2.2.2, program extraction in Section 2.5 .2 and the case study in Section 3.2. The author's contribution to the second paper amounts to $50 \%$. The corresponding contents are the case study in Section 3.4. The author's contribution to the third paper amounts to $33 \%$. The corresponding contents are inductive definitions in Section 2.3.1, coinductive definitions in Section 2.3.2, corecursion operators in Section 2.2.2, program extraction in Section 2.5.2 and the case study in Section 3.5 and Section 3.8.

## Chapter 1

## Introduction

An important aspect of constructive mathematics is that a mathematician has to deal with mathematical objects only by realistic and practicable instructions. As a consequence, proofs in constructive mathematics contain algorithms which compute a solution to the corresponding proposition. Program extraction is a method to synthesize from proofs an executable program which is certified with regarding the proposition as a specification. This Thesis studies program extraction from inductive and coinductive proofs within the Theory of Computable Functionals [SW12], TCF in short. Theoretical results are implemented as additional features of the proof assistant Minlog [Min]. Non-trivial case studies in exact real arithmetic due to Berger and Seisenberger Ber09, Ber10, Ber11, BS10, BS12] are formalized on a computer as a concrete practice of Minlog.

### 1.1 Background

The idea of program extraction goes back to the so-called Brouwer-Heyting-Kolmogorov interpretation, BHK interpretation for short, of intuitionistic logic which assigns to each formula a proof. Kleene introduced realizability [Kle45], a main mathematical tool of this Thesis, which assigns to a formula $A$ another formula stating $n$ realizes $A$ where $n$ is a natural number encoding a realizer of $A$. A realizer is intended to be an evidence which constructively justifies a claim. Kreisel introduced modified realizability [Kre59] which adopts Heyting arithmetic, where realizers are given in Gödel's T. Realizability in TCF is based on Kreisel's modified realizability. Within TCF, atomic formulas are given by inductive and coinductive definitions, and realizers are given in $\mathrm{T}^{+}$, an extension of Gödel's T Göd58. One may view realizability as an instance of the BHK interpretation. A procedure called program extraction is defined based on realizability which transforms a proof of a formula $A$ into a realizer of $A$. Considering the formula $A$ as a specification, the realizability statement is read as a correctness statement of a realizer respecting the specification. Program extraction is a way to synthesize a provably correct program with respect to the specification due to a corresponding soundness theorem.

TCF is a framework of program extraction which is based on first-order minimal logic.

The theory is extendable by means of inductive and coinductive definitions. The realizability yields the program extraction procedure in TCF whose target language is $\mathrm{T}^{+}$. The soundness theorem ensures that a proved formula has a realizer, which is in fact given by program extraction. TCF supports so-called general induction principle and also classical proofs due to the A-translation and Gödel's dialectica interpretation.

### 1.2 Inductive and Coinductive Definitions

TCF adopts coinduction, considered as a dual of induction, as a main feature of program extraction study. By inductive and coinductive definitions, we add new predicate constants and axioms involving the predicate constants extending TCF. Such predicates are called inductive and coinductive predicates. The main idea is the following. An inductive definition provides a way of construction. As an example, we define even numbers by a predicate Ev which tells us a way to construct even numbers.

$$
\operatorname{Ev} 0, \quad \forall_{n}(\operatorname{Ev} n \rightarrow \operatorname{Ev}(n+2))
$$

Similarly, we can also specify a list of even numbers by a predicate LE.

$$
\mathrm{LE}[], \quad \forall_{n, n s}(\operatorname{Ev} n \rightarrow \operatorname{LE} n s \rightarrow \operatorname{LE}(n:: n s)) .
$$

These instructions of constructions are called introduction axioms. Assume $P$ and $Q$ are predicates. We derive an instruction of inspection called an elimination axiom which works in a different direction from introduction axioms.

$$
\begin{aligned}
& \forall_{n}\left(\operatorname{Ev} n \rightarrow P 0 \rightarrow \forall_{n}(P n \rightarrow P(n+2)) \rightarrow P n\right), \\
& \forall_{n s}\left(\operatorname{LE} n s \rightarrow Q[] \rightarrow \forall_{n, n s}(\operatorname{Ev} n \rightarrow Q n s \rightarrow Q(n:: n s)) \rightarrow Q n s\right) .
\end{aligned}
$$

We call $P$ and $Q$ competitors. Intuitively, an elimination axiom tells us that the inductively defined predicate is smaller than any competitor if all the introduction axioms replaced by the competitor hold. Obviously it is so-called induction principles in daily mathematics. Coinduction works in the opposite way from induction. A coinductive definition specifies an instruction of inspection called a closure axiom instead of one of construction. Taking an example in lists, we can say that a list is the empty list or consists of the head and the tail which are respectively an even number and a list of even numbers. This is formulated by the following formula.

$$
\forall_{n s}\left(\operatorname{LE} n s \rightarrow n s=[] \vee \exists_{m, m s}(\operatorname{Ev} m \wedge \operatorname{LE} m s \wedge n s=m:: m s)\right)
$$

The duality may be clearer if we formulate the introduction axioms of LE in the following logically equivalent one.

$$
\forall_{n s}\left(n s=[] \vee \exists_{m, m s}(\operatorname{Ev} m \wedge \operatorname{LE} m s \wedge n s=m:: m s) \rightarrow \operatorname{LE} n s\right) .
$$

Differently from the case of inductive definitions, we derive an instruction of construction called a greatest-fixed-point axiom, as follows

$$
\forall_{n s}\left(Q n s \rightarrow \forall_{n s}\left(Q n s \rightarrow n s=[] \vee \exists_{m, m s}(\operatorname{Ev} m \wedge Q m s \wedge n s=m:: m s)\right) \rightarrow \text { LE } n s\right)
$$

Intuitively, a greatest-fixed-point axiom tells us that a coinductively defined predicate is bigger than any competitor, if the closure axiom replaced by the competitor holds. One can consider a coinductive predicate containing lists whose tails are never inspected to be the empty list, as long as we repeatedly apply the closure axiom. Hence, we can make use of coinduction to reason about possibly infinite lists. This is a meaningful alternative to make use of a function to define a sequence, because an infinite list is represented by coinduction as a simpler ground type object instead of a functional type object. Thanks to it, infinite objects may be observed rather directly in the realm of coinduction. This advantage becomes more evident when we consider a function with an uncountable domain, e.g. function spaces, to define an infinite object.

### 1.3 Minlog

Since we consider program extraction as a method of program development, it is crucial to have a computer system which is a realization of our study. The Minlog system is a general purpose proof assistant whose competitive feature is program extraction. The development of Minlog was initiated by Schwichtenberg around 1990 as an implementation of TCF [Sch92]. The current version of Minlog supports extraction from classical proofs through the $A$-translation and Gödel's dialectica interpretation as well as from constructive proofs involving inductive and coinductive arguments.

We review related proof assistants. The NuPRL system Nup, BC85 was founded by Bates and Constable. NuPRL is one of the most important realization of the proofs-as-programs paradigm. The PX system by Hayashi [HN87] features q-realizability. For program extraction support of recent competitive other proof assistants as Coq, Isabelle and Agda, see Section 2.6.5.

### 1.4 Contributions

The contributions of this Thesis are the following:

Theory of program extraction. We study new features to enrich TCF, our theoretical foundation of studying program extraction. In addition to (simultaneous) inductive definitions and (simultaneous) coinductive definitions, we consider nested definitions to combine inductive definitions and coinductive definitions in TCF. This is a reasonable way to use both of induction and coinduction in one definition. Nested definition yields axioms for inductive and coinductive reasoning which also contain nestedness. On the other hand, our formal calculus $\mathrm{T}^{+}$is enriched to accommodate computational aspects of nestedness.

The program extraction procedure is given through a soundness theorem, according to which, if a formula $A$ is proven, then there exists a realizer $t$ such that $t$ realizes $A$. In TCF the target language of program extraction is $\mathrm{T}^{+}$. We extend the soundness theorem to accommodate (strong) induction and (strong) coinduction with nestedness.

Implementation. The theoretical improvements are implemented as additional features of the proof assistant Minlog. Our main contribution is the implementation of nested algebras and nested recursion and corecursion operators as well as of nested inductive and coinductive definitions. The program extraction procedure is also enriched to accommodate the nestedness. The term normalization of arbitrary recursion operators is particularly done via Normalization by Evaluation [BS91, BES03], which is an effective method to implement normalization based on denotational semantics. In order to handle nested recursion operators, the Normalization by Evaluation of Minlog is improved. For corecursion operators Minlog offers bounded unfolding instead.

Practicing constructive mathematics. We apply TCF and Minlog to concrete case studies in exact real arithmetic involving real numbers and uniformly continuous functions. In order to study them, we exploit two kinds of representations: one is the function type representation and the other is the ground type coinductive representation. For simplicity, we restrict our real numbers to be in the interval $[-1,1]$. The function type representation of real numbers, say the type-1 representation, is a pair of a Cauchy sequence and a Cauchy modulus which are of function types. The ground type coinductive representation of real numbers, say the type-0 representation, is a (possibly) infinite list of digits. The more number of digits we observe from a list, the more precise approximation of the represented real number becomes. The representations of uniformly continuous functions follow the same pattern. We understand real numbers and uniformly continuous functions as objects which are approximated as good as we require and are observable more directly than functions. Within coinduction, we achieve such representations straightforwardly; this is why we find an advantage in studying exact real arithmetic coinductively. We present formalization of case studies by Berger and Seisenberger in exact real arithmetic. We extract from proofs non-trivial programs dealing with real numbers and uniformly continuous functions in Minlog system.

### 1.5 Organization of the Thesis

This Thesis is organized in the following way. Chapter 2 describes TCF, our theoretical foundation of program extraction. We review the domain-theoretic background of partial continuous functionals. Free algebras are taken as ground types of our formal calculus $\mathrm{T}^{+}$. We study nested algebras as well as simultaneous algebras. We use $\mathrm{T}^{+}$as the target language of our program extraction as well as the terms of our logical language of minimal logic. We study inductive and coinductive definitions in first-order minimal logic, and the notion of proofs and the realizability are given. Based on the realizability we define program
extraction which transforms proofs into a program code in $\mathrm{T}^{+}$. The soundness theorem, which states that the proven formula has a realizer, is proven. We practice TCF in an elementary part of exact real arithmetic. We briefly review real numbers and uniformly continuous functions in exact real arithmetic, and give case studies in exact real arithmetic due to Berger and Seisenberger in Chapter 3. These case studies involving coinduction are formalized in the proof assistant Minlog as well as in the Thesis. The downloadable Minlog package contains the proof scripts corresponding to Chapter 3 which offer machine-extracted programs running on a computer. Appendix A consists of two parts. The first part describes the implementation of Minlog focusing on Normalization by Evaluation, recursion and corecursion operators in $\mathrm{T}^{+}$and inductive and coinductive definitions. The second part explains a Minlog proof script from Section 3.3 in detail.

## Chapter 2

## Theory of Computable Functionals

In this chapter we study the theoretical foundation for program extraction called Theory of Computable Functionals, TCF in short. TCF provides our theoretical basis to practice program extraction on the computer as well as on the paper. The remarkable character of TCF is its concreteness, which becomes an advantage if one desires to have an implementation of such a theory on a computer.

Computable objects in TCF are partial continuous functionals which model our notion of higher type abstract computability specified by the following two principles: the finite support principle and the monotonicity principle. During the evaluation of some functional $\Phi$, there are only finitely many inputs $\varphi_{0}, \ldots, \varphi_{n-1}$ used. Moreover, each of $\varphi_{i}$ must be presented to $\Phi$ in a finite form. This is the finite support principle. Assume $\Phi\left(\varphi_{0}\right)$ evaluates to a value $k$ and let $\varphi_{1}$ be more informative than $\varphi_{0}$. Then the $\Phi\left(\varphi_{1}\right)$ results in $k$ as well. This is the monotonicity principle. Then, the notion of abstract computability is formulated as follows: an object is computable if its set of finite approximation is primitive recursively enumerable. Such functionals are represented by the term language $\mathrm{T}^{+}$which is an extension of Gödel's T.

The logic of TCF is first order minimal logic formulated in natural deduction. The logic can be extended by inductive and coinductive definitions. Nested definitions and simultaneous definitions enrich the expressivity of definitions in TCF. Especially nested definitions allow a combination of inductive definitions and coinductive ones. Classical logic is also available as a fragment of minimal logic. We can extract from proofs computational content via program extraction. Program extraction is based on Kreisel's modified realizability interpretation which enjoys the soundness theorem in TCF. Realizability statements, e.g. a term $t$ realizes a formula $A$, are formulas in TCF, and its proof is also given in TCF.

This chapter is organized as follows. In Section 2.1, we provide a concrete formulation of partial continuous functionals due to Schwichtenberg [SW12] by means of Scott-Ershov domains. We briefly review that our computational objects are represented by ideals which are special elements in domains. In Section 2.2, we study $\mathrm{T}^{+}$, an extension of Gödel's T. This is a typed lambda calculus with constants as recursion and corecursion operators. We briefly also review that the denotational semantics of $\mathrm{T}^{+}$is given via ideals. A term in Gödel's T with arbitrary algebras denotes a total ideal. A corecursion operator, a proper
extension from Gödel's T, denotes a cototal ideal of a base type which can represent a non-well founded object. In Section 2.3, we describe inductive and coinductive definitions in TCF. Nested inductive/coinductive definitions and simultaneous definitions are also given. Nested definitions specify a new predicate by using old ones, and simultaneous definitions specify more than one predicate at the same time. In Section 2.4, we describe natural deduction and proof normalization involving inductive and coinductive definitions. The notion of proof terms is also introduced based on the Curry-Howard correspondence. In Section 2.5, we describe Kreisel's modified realizability interpretation. The logical connectives of TCF are decorated in order to study computational meaning of them with greater details, then we introduce the notion of realizability and program extraction. We also give the soundness theorem, which claims that the proved proposition is realized by the extracted program from its proof. This justifies the correctness of the program extraction.

### 2.1 Partial Continuous Functionals

We study higher type computability via partial continuous functionals. In this section, we describe the notion of ideals which indeed are concrete representations of partial continuous functionals. In order to provide a concrete construction of such objects we make use of Scott's information systems [Sco82, Win93], then ideals come as special sets which are consistent and deductively closed. Domain theoretically speaking, an ideal is an element in Scott-Ershov domains with free algebras as ground types. In Section 2.1.1 we study Scott's information systems as a way of constructing domains. In Section 2.1 .2 we study types whose ground types are given by (free) algebras. In Section 2.1.3 we study concrete information systems based on types from which we define the notion of a partial continuous functional of finite type.

### 2.1.1 Information Systems and Domains

An information system consists of three ingredients: the tokens, the consistent sets and the entailment relation. Information systems can be viewed as deduction systems. Tokens are assertions about a computation. A consistent set contains tokens which can be true assertions at the same time. The entailment is a way to deduce from a set of assertions another assertion. We first give an account on information systems in general, then we consider concrete ones which are defined on types.
Definition 2.1.1 (Information systems). Let $U$, $V$ range over finite sets. An information system is a structure $\langle$ Tok, Con, $\vdash\rangle$ such that

$$
\begin{aligned}
& U \subseteq V \in \text { Con } \rightarrow U \in \text { Con, } \\
& \{a\} \in \text { Con for any } a \in \text { Tok, } \\
& U \vdash a \rightarrow U \cup\{a\} \in \mathrm{Con}, \\
& a \in U \in \operatorname{Con} \rightarrow U \vdash a, \\
& U, V \in \operatorname{Con} \rightarrow \forall_{a \in V}(U \vdash a) \rightarrow V \vdash b \rightarrow U \vdash b .
\end{aligned}
$$

Intuitively, tokens carry informative content of computation which should be consistent and deductively closed. Assume one computation means 7, then it should not mean 13 at the same time, and it should remain to be 7 in the future. We formulate such tokens as ideals.

Definition 2.1.2 (Ideals). Let IS be an information system $\langle$ Tok, Con, $\vdash\rangle$. The ideals $\mid$ IS $\mid$ are subsets of Tok whose elements $x \in \mid$ IS $\mid$ are

1. consistent: $a \subseteq x \rightarrow a \in \mathrm{Con}$,
2. deductively closed: $x \supseteq U \vdash a \rightarrow a \in x$.

A cpo $(|\mathrm{IS}|, \subseteq, \emptyset)$ forms a Scott-Ershov domain, namely, a bounded complete algebraic cpo. In our theory of computability functionals are of higher type in general. We consider function spaces between information systems.

Definition 2.1.3 (Function spaces). Suppose that $\mathrm{IS}_{A}$ and $\mathrm{IS}_{B}$ are $\left\langle\operatorname{Tok}_{A}, \mathrm{Con}_{A}, \vdash_{A}\right\rangle$ and $\left\langle\operatorname{Tok}_{B}, \operatorname{Con}_{B}, \vdash_{B}\right\rangle$, respectively, and $I$ be a finite set of indices. We define $\mathrm{IS}_{A} \rightarrow \mathrm{IS}_{B}$ to be $\langle$ Tok, Con, $\vdash\rangle$ such that

$$
\begin{aligned}
& \text { Tok }:=\operatorname{Con}_{A} \times \operatorname{Tok}_{B}, \\
& \left\{\left(U_{i}, b_{i}\right) \mid i \in I\right\} \in \operatorname{Con}:=\forall_{J \subseteq I}\left(\bigcup_{j \in J} U_{j} \in \operatorname{Con}_{A} \rightarrow\left\{b_{j} \mid j \in J\right\} \in \operatorname{Con}_{B}\right), \\
& W \vdash(U, b):=W U \vdash_{B} b,
\end{aligned}
$$

where for $W:=\left\{\left(U_{i}, b_{i}\right) \mid i \in I\right\}$ and $U \in \operatorname{Con}_{A}$ an application $W U$ is defined to be $\left\{\left(U_{i}, b_{i}\right) \mid i \in I\right\} U:=\left\{b_{i} \mid U \vdash_{A} U_{i}\right\}$.

We introduce approximable maps as an alternative characterization of the function spaces. An approximable map $r$ is a relation between $\mathrm{Con}_{A}$ and $\mathrm{Tok}_{B}$ which represents an information respecting map from $\mathrm{IS}_{A}$ into $\mathrm{IS}_{B}$. Intuitively $r(U, b)$ means that if we are given the information $U \in \operatorname{Con}_{A}$, then we find at least the token $b \in \operatorname{Tok}_{B}$ in the value.

Definition 2.1.4 (Approximable maps). Suppose that $\mathrm{IS}_{A}$ and $\mathrm{IS}_{B}$ are $\left\langle\mathrm{Tok}_{A}, \mathrm{Con}_{A}, \vdash_{A}\right\rangle$ and $\left\langle\operatorname{Tok}_{B}, \operatorname{Con}_{B}, \vdash_{B}\right\rangle$, respectively. A relation $r \subseteq \operatorname{Con}_{A} \times \operatorname{Tok}_{B}$ is an approximable map if the following conditions are satisfied.

1. If $r\left(U, b_{0}\right), \ldots, r\left(U, b_{n-1}\right)$, then $\left\{b_{0}, \ldots, b_{n-1}\right\} \in \operatorname{Con}_{B}$.
2. If $r\left(U, b_{0}\right), \ldots, r\left(U, b_{n-1}\right)$ and $\left\{b_{0}, \ldots, b_{n-1}\right\} \vdash_{B} b$, then $r(U, b)$.
3. If $r\left(U^{\prime}, b\right)$ and $U \vdash_{A} U^{\prime}$, then $r(U, b)$.

By the following proposition ideals in a function space are indeed approximable maps [SW12].

Proposition 2.1.5 (Ideals in a function space are approximable maps). Let $\mathrm{IS}_{A}$ and $\mathrm{IS}_{B}$ be information systems. The ideals of $\mathrm{IS}_{A} \rightarrow \mathrm{IS}_{B}$, namely, $\left|\mathrm{IS}_{A} \rightarrow \mathrm{IS}_{B}\right|$ are exactly the approximable maps from $\mathrm{IS}_{A}$ to $\mathrm{IS}_{B}$.

### 2.1.2 Algebras and Types

We introduce types for our theory of computability. The ground types are given by algebras. An algebra is specified by constructor types, and provides constructor symbols of the constructor types. For each algebra $\iota$, there is at least one object of type $\iota$ finitely built from the constructor symbols. Such an object is an inhabitant and $\iota$ is said to be inhabited. We define type forms as follows.

Definition 2.1.6 (Type forms). Let $\alpha$ and $\xi$ be variables and $k$ be positive. Type forms are inductively defined as follows.

$$
\rho, \sigma:=\alpha|\rho \rightarrow \sigma| \mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k} .
$$

In an expression $\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi, \rho_{i \nu}$ is a parameter argument if $\xi \notin \mathrm{FV}\left(\rho_{i \nu}\right), \rho_{i \nu}$ is a recursive argument if $\xi \in \mathrm{FV}\left(\rho_{i \nu}\right)$ and $\rho_{i \nu}$ is a nested argument if $\xi$ appears as an argument in another expression of the form $\mu_{\zeta}\left(\left(\rho_{i \nu}^{\prime}\right)_{\nu<n_{i}^{\prime}} \rightarrow \zeta\right)_{i<k^{\prime}}$ in $\rho_{i \nu}$.

Note that $\rho_{0} \rightarrow \rho_{1} \rightarrow \ldots \rightarrow \rho_{n-1} \rightarrow \sigma$ is abbreviated as $\left(\rho_{\nu}\right)_{\nu<n} \rightarrow \sigma$. We define $\mathrm{FV}(\rho)$ to be the set of free type variables in $\rho$.

Definition 2.1.7 (Free variables in a type form). Define free variables in a type form $\tau$ by induction.

$$
\begin{aligned}
& \mathrm{FV}(\alpha):=\{\alpha\} \\
& \operatorname{FV}(\rho \rightarrow \sigma):=\mathrm{FV}(\rho) \cup \operatorname{FV}(\sigma) \\
& \operatorname{FV}\left(\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}\right):=\cup_{i<k} \mathrm{FV}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right) \backslash\{\xi\}
\end{aligned}
$$

We say $\mathrm{FV}(\tau)$ to be free variables of $\tau$.
We denote $\rho(\vec{\alpha})$ to express that $\rho(\vec{\sigma})$ means replacing $\vec{\alpha}$ in $\rho$ by $\vec{\sigma}$. We assume standard $\alpha$-equivalence and substitution. The result of substituting $\vec{\sigma}$ for $\vec{\alpha}$ in $\rho(\vec{\alpha})$ is denoted by $\rho(\vec{\sigma})$. We define $\operatorname{SP}_{\vec{\zeta}}(\rho)$ by induction on $\rho$. When $\operatorname{SP}_{\vec{\zeta}}(\rho)$, the occurrences of $\vec{\zeta}$ in $\rho$ are strictly positive, namely, not in the left hand side of an arrow type. Assume $\mathrm{SP}_{\vec{\zeta}}\left(\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}\right)$, then it is also ensured that each argument $\rho_{i \nu}$ of a constructor type does not have the type variable $\xi$ in the left hand side of an arrow type.

Definition 2.1.8 (Strictly positive occurrence of type). Let $\rho$ and $\sigma$ range over type forms. We define $\mathrm{SP}_{\vec{\zeta}}(\rho)$ by induction on $\rho$.

$$
\operatorname{SP}_{\vec{\zeta}}(\beta), \quad \frac{\operatorname{FV}(\rho) \cap \vec{\zeta}=\emptyset \quad \mathrm{SP}_{\vec{\zeta}}(\sigma)}{\operatorname{SP}_{\vec{\zeta}}(\rho \rightarrow \sigma)}, \quad \frac{\text { For all } i<k, \nu<n_{i}, \mathrm{SP}_{\vec{\zeta}, \xi}\left(\rho_{i \nu}\right)}{\mathrm{SP}_{\vec{\zeta}}\left(\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}\right)}
$$

When $\operatorname{SP}_{\vec{\zeta}}(\rho)$, we say that the occurrences of $\vec{\zeta}$ in $\rho$ are strictly positive. When $\vec{\zeta}$ is empty, we write $\mathrm{SP}(\rho)$ instead of $\mathrm{SP}_{\vec{\zeta}}(\rho)$.

### 2.1. Partial Continuous Functionals

We define inhabitedness of a type form. A type is inhabited if there exists an inhabitant of the type assuming the inhabitedness of its type parameters. A type is absolutely inhabited if its inhabitedness is not dependent on the inhabitednesses of its type parameters.

Definition 2.1.9 (Inhabitedness). We inductively define Inhab.

$$
\frac{\alpha \notin \vec{\zeta}}{\operatorname{Inhab}_{\vec{\zeta}}(\alpha)}, \quad \frac{\operatorname{Inhab}_{\vec{\zeta}}(\sigma)}{\operatorname{Inhab}_{\vec{\zeta}}(\rho \rightarrow \sigma)}, \quad \frac{\text { There exists } i, \text { for all } \nu<n_{i}, \operatorname{Inhab}_{\vec{\zeta}, \xi}\left(\rho_{i \nu}\right)}{\operatorname{Inhab}_{\vec{\zeta}}\left(\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}\right)} .
$$

If $\vec{\zeta}$ is empty, we omit the subscript and denote $\operatorname{Inhab}(\rho)$. When $\operatorname{Inhab}(\rho)$ is derived, $\rho$ is inhabited. When $\operatorname{Inhab}_{\mathrm{FV}(\rho)}(\rho)$ is derived, $\rho$ is absolutely inhabited. A derivation of $\operatorname{Inhab}_{\vec{\zeta}}(\rho)$ is canonical if in each application of the third rule the smallest possible index $i$ is chosen.

In the above definition, the subscripts $\vec{\xi}$ in $\operatorname{Inhab}_{\vec{\xi}}(\rho)$ are type variables whose inhabitedness cannot be used to claim the inhabitedness of $\rho$. Types are inductively defined in the following way.

Definition 2.1.10 (Types). We inductively define Ty.

$$
\begin{aligned}
& \operatorname{Ty}(\alpha), \quad \frac{\operatorname{Ty}(\rho) \operatorname{Ty}(\sigma)}{\operatorname{Ty}(\rho \rightarrow \sigma)}, \\
& \frac{\text { For all } i<k, \nu<n_{i}, \operatorname{Ty}\left(\rho_{i \nu}\right) \text { and } \operatorname{SP}_{\xi}\left(\rho_{i \nu}\right) \quad \operatorname{Inhab}\left(\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}\right)}{\operatorname{Ty}\left(\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}\right)} .
\end{aligned}
$$

When $\operatorname{Ty}(\rho)$ holds, $\rho$ is a type.
In the last rule, the left premise is to ensure algebra definitions to be from strictly positive type forms and the right premise is to ensure the inhabitedness. Algebras come as special kinds of type.

Definition 2.1.11 (Algebra). We call $\iota:=\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$ an algebra if $\iota$ is a type.
Assume $\iota:=\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$. When $\operatorname{Ty}(\iota)$, we refer to each $\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi$ for each $i$ a constructor type of $\iota$. Conventionally we use $\iota$ as a variable ranging over algebras and $\kappa$ over constructor types. An algebra provides for each constructor type a constructor symbol $\mathrm{C}_{\iota, i}$. We abbreviate $\mathrm{C}_{\iota, i}$ as $\mathrm{C}_{i}$ if there is no confusion. Algebras are always inhabited, hence there is no empty algebra.

Example 2.1.12 (Inhabitedness of algebras). We give examples and non-examples of inhabitedness of algebras. Define $\mathbf{L}_{\alpha}$ to be $\mu_{\xi}(\xi, \alpha \rightarrow \xi \rightarrow \xi)$ and $\mathbf{L}_{\alpha}^{+}$to be $\mu_{\xi}(\alpha \rightarrow \xi, \alpha \rightarrow$ $\xi \rightarrow \xi$ ). Then, $\mathbf{L}_{\alpha}$ and $\mathbf{L}_{\mathbf{L}(\alpha)}^{+}$are absolutely inhabited, and $\mathbf{L}_{\alpha}^{+}$is inhabited. Define $\alpha+\beta$ to be $\mu_{\xi}(\alpha \rightarrow \xi, \beta \rightarrow \xi)$ and $\iota_{\alpha}$ to be $\mu_{\xi}(\alpha+\xi \rightarrow \xi)$. A type form $\mu_{\xi}\left(\iota_{\xi} \rightarrow \xi\right)$ is not inhabited, hence not a type. Define $\alpha \times \beta$ to be $\mu_{\xi}(\alpha \rightarrow \beta \rightarrow \xi)$. A type form $\mu_{\xi}(\alpha \times \xi \rightarrow \xi)$ is not inhabited, hence not a type. Both of $\mu_{\xi}(\xi \rightarrow \xi)$ and $\mu_{\xi}(\xi,(\xi \rightarrow \xi) \rightarrow \xi)$ are not inhabited.

We take a look at examples of algebras. Here, conventional names of the constructors are also given. We follow this convention unless it is ambiguous. For convenience, we can write $\mathrm{C}^{\kappa}$ instead of $\kappa$ in order to specify also the constructor's name C .

Example 2.1.13 (Algebras). We first take a look at simple algebra definitions.

$$
\begin{align*}
& \mathbf{U}:=\mu_{\xi}\left(\mathbf{U}^{\xi}\right)  \tag{Unit}\\
& \mathbf{B}:=\mu_{\xi}\left(\mathbf{T}^{\xi}, \mathrm{F}^{\xi}\right) \\
& \mathbf{S D}:=\mu_{\xi}\left(\mathrm{L}^{\xi}, \mathrm{M}^{\xi}, \mathrm{R}^{\xi}\right)  \tag{Signeddigits}\\
& \mathbf{N}:=\mu_{\xi}\left(0^{\xi}, \mathrm{S}^{\xi \rightarrow \xi}\right) \\
& \mathbf{P}:=\mu_{\xi}\left(1^{\xi}, \mathrm{S}_{0}^{\xi \rightarrow \xi}, \mathrm{S}_{1}^{\xi \rightarrow \xi}\right) \\
& \mathbf{Z}:=\mu_{\xi}\left(0^{\xi}, \mathrm{P}^{\mathbf{P} \rightarrow \xi}, \mathbf{N}^{\mathbf{P} \rightarrow \xi}\right)  \tag{Integers}\\
& \mathbf{Q}:=\mu_{\xi}\left(\#^{\mathbf{Z} \rightarrow \mathbf{P} \rightarrow \xi}\right) \\
& \mathbf{D}:=\mu_{\xi}\left(0^{\xi}, \mathrm{D}^{\xi \rightarrow \xi \rightarrow \xi}\right)
\end{align*}
$$

(Booleans)
(Natural numbers)
(Positive numbers)
(Rational numbers)
(Derivations)
The unit algebra is a singleton. The boolean algebra consists of two constructors which are interpreted as true and false. We use the signed digits in particular to study exact real arithmetic. The natural number algebra represents natural numbers by 0 and the successor. The positive number algebra represents binary numbers. Informally, $\mathrm{S}_{b_{0}}\left(\ldots\left(\mathrm{~S}_{b_{n-1}} 1\right) \ldots\right)$ means a binary number $1 b_{n-1} \ldots b_{0}$, i.e., a number $\sum_{i=0}^{n-1} 2^{i} b_{i}+2^{n}$. From a positive number, the positive and the negative part of integers are constructed by injection. The zero element is separately given by the other constructor. In the rational number algebra, a rational number is a pair of a positive number and an integer. The derivation algebra represents binary trees which are constructed by the leaf and the node.

Example 2.1.14 (Algebras with parameters). We give algebra definitions with parameter types.

$$
\begin{align*}
& \mathbf{L}_{\alpha}:=\mu_{\xi}\left([]^{\xi},::^{\alpha \rightarrow \xi \rightarrow \xi}\right)  \tag{Lists}\\
& \times_{\alpha, \beta}:=\mu_{\xi}\left(\operatorname{Pair}^{\alpha \rightarrow \beta \rightarrow \xi}\right)  \tag{Product}\\
& +_{\alpha, \beta}:=\mu_{\xi}\left(\operatorname{InL}^{\alpha \rightarrow \xi}, \operatorname{InR}^{\beta \rightarrow \xi}\right)  \tag{Sum}\\
& \text { Uysum }_{\alpha}:=\mu_{\xi}(\xi, \alpha \rightarrow \xi) \tag{Unitsum}
\end{align*}
$$

Type parameters can be written with parentheses, e.g., $\mathbf{L}(\alpha)$, instead of subscripts. We accept the infix notation for $\times_{\alpha, \beta}$ and $+_{\alpha, \beta}$, e.g., $\alpha \times \beta$ and $\alpha+\beta$, respectively.

The list algebra represents lists of objects of an arbitrary type $\alpha$. The product algebra makes a pair, e.g. a pair of $x^{\alpha}$ and $y^{\beta}$ written as Pair $x y$ which is abbreviated as $\langle x, y\rangle$. The sum algebra is for the left and the right injection. The unit sum is so-called maybe algebra, which is either nothing or just an object of $\alpha$ for example in Haskell. We may call its constructors None and Just. For them, we also write $\operatorname{InL} U$ and $\operatorname{InR}$, respectively, by abusing constructors of $\mathbf{U}$ and + .

Example 2.1.15 (Nested algebras). Using previously defined parameterized algebras, algebras can be nested.

$$
\left.\begin{array}{l}
\text { Nodd }:=\mu_{\xi}\left(\mathrm{S}^{\operatorname{Uysum}_{\xi} \rightarrow \xi}\right) \\
\mathbf{N t}:=\mu_{\xi}\left(\mathrm{Br}^{\mathbf{L} \rightarrow \xi}\right) \\
\mathbf{R}_{\alpha}:=\mu_{\xi}\left(\operatorname{Put}^{\mathbf{S D} \rightarrow \alpha \rightarrow \xi}, \operatorname{Get}^{\xi \rightarrow \xi \rightarrow \xi \rightarrow \xi}\right), \\
\mathbf{W}:=\mu_{\xi}\left(\text { Stop }^{\xi}, \operatorname{Cont}^{\mathbf{R}}{ }_{\xi} \rightarrow \xi\right.
\end{array}\right)
$$

(Nested odd numbers)
(Nested trees)
(Read-write machines)

The nested odd number algebra represents even and odd numbers. Consider None of type Uysum $_{\text {Nodd }}$ to be zero, an even. Then, S None is one, an odd, Just(S None) is two, an even, $\mathrm{S}($ Just(S None)) is three, an odd, and so on. The nested tree algebra represents trees of arbitrary height with arbitrary branching. The argument of Br is a list of Nt , which corresponds to each branch from this node. The read-write machine algebra is a kind of a branching tree which plays a special role in exact real arithmetic. We study it in detail in Section 3.5.

Example 2.1.16 (Non-finitary algebras). We give non-finitary algebras. Constructor types can be of higher types.

$$
\begin{align*}
& \mathbf{O}:=\mu_{\xi}\left(0^{\xi}, \mathbf{S}^{\xi \rightarrow \xi}, \operatorname{Sup}^{(\mathbf{N} \rightarrow \xi) \rightarrow \xi}\right)  \tag{Ordinals}\\
& \mathbf{T}_{0}:=\mathbf{N}, \quad \mathbf{T}_{n+1}:=\mu_{\xi}\left(\xi,\left(\mathbf{T}_{n} \rightarrow \xi\right) \rightarrow \xi\right) \tag{Trees}
\end{align*}
$$

Let $\vec{\xi}$ be a list of types of length $n$ and $i<n$. We define $\vec{\xi}^{(i)}$, the $i$-th tail of $\vec{\xi}$, as follows: $\vec{\xi}^{(0)}:=\vec{\xi},(\zeta, \vec{\xi})^{(j+1)}:=\vec{\xi}^{(j)}$. We modify the above definitions to support simultaneous algebras.

Definition 2.1.17 (Simultaneous algebras). We modify type forms as follows. Let $l$ be the length of $\vec{\xi}$, a non-empty list of type variables.

$$
\rho, \sigma:=\alpha|\rho \rightarrow \sigma| \mu_{\vec{\xi}}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi_{j_{i}}\right)_{i<k}
$$

where $j$ is a surjection from $i \in\{0,1, \ldots, k-1\}$ to $j_{i} \in\{0,1, \ldots, l-1\}$. We also replace the definitions involving $\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$ by the following.

$$
\begin{aligned}
& \operatorname{FV}\left(\mu_{\vec{\xi}}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi_{j_{i}}\right)_{i<k}\right):=\cup_{i<k} \mathrm{FV}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi_{j_{i}}\right) \backslash\{\vec{\xi}\}, \\
& \text { for all } m<|\vec{\xi}| \text {, there exists } i, j_{i}=m \text { and for all } \nu<n_{i}, \operatorname{Inhab}_{\vec{\zeta}, \vec{\xi}(m)}\left(\rho_{i \nu}\right) \\
& \operatorname{Inhab}_{\vec{\zeta}}\left(\mu_{\vec{\xi}}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi_{j_{i}}\right)_{i<k}\right)
\end{aligned}, .
$$

We call $\vec{\imath}:=\mu_{\vec{\xi}}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi_{j_{i}}\right)_{i<k}$ simultaneous algebras if $\operatorname{Ty}(\vec{\iota})$.
The second rule in the above definition is modified to check the inhabitedness of each algebra. We take a look at examples of algebras.

Example 2.1.18 (Simultaneous algebras).

$$
\begin{array}{lr}
\text { Even, Odd }:=\mu_{\xi, \zeta}(\xi, \zeta \rightarrow \xi, \xi \rightarrow \zeta) & \text { (Even and odd numbers) } \\
\text { Ts, } \mathbf{T}:=\mu_{\xi, \zeta}(\xi, \zeta \rightarrow \xi \rightarrow \xi, \xi \rightarrow \zeta) & \text { (Tree lists and trees) }
\end{array}
$$

Tree lists and trees are also called forests and trees Pau00, Coq13. We can observe the similarity between simultaneous algebras and nested ones. The algebras (Even, Odd) can work in a similar way as the pair of Uysum and Nodd. Also algebras (Ts, T) can work in a similar way as the pair of $\mathbf{L}_{\mathbf{N t}}$ and $\mathbf{N t}$. The simultaneity and the nestedness can be mixed.

Example 2.1.19 (Simultaneous nested algebra).

$$
\text { Not, Net }:=\mu_{\zeta, \xi}\left(\mathbf{L}_{\zeta} \rightarrow \xi, \mathbf{L}_{\xi} \rightarrow \zeta\right)
$$

(Nested odd/even trees)
We give translations between simultaneous algebras and nested algebras. Let $\vec{\iota}$ be simultaneous algebras $\mu_{\vec{\xi}}(\vec{\kappa})$ of length $l$. Suppose that for a given $m<l$, $\operatorname{Inhab}_{\left(\xi_{i}\right)_{i<m}}\left(\vec{\kappa}^{\prime}\right)$ holds, where $\vec{\kappa}^{\prime}$ is the greatest sublist of $\vec{\kappa}$ such that the value types of $\vec{\kappa}^{\prime}$ is $\xi_{m}$. We can define $\iota_{m}^{\prime}(\vec{\alpha})$ instead of $\iota_{m}$ where all the depended simultaneous algebras in $\iota_{m}$ are replaced by parameter types, and also $\vec{\iota}$ of length $l-1$ which is similar to $\vec{\iota}$ but $\iota_{m}$ is dropped and is replaced by the independently defined $\iota_{m}^{\prime}(\vec{\alpha})$.

Definition 2.1.20 (Translation from simultaneity to nestedness). Assume simultaneous algebras $\vec{\iota}=\mu_{\vec{\xi}}(\vec{\kappa})$ of length $l$ are given. Suppose that for a given $m<l$, $\operatorname{Inhab}\left(\xi_{i}\right)_{i<m}\left(\kappa_{i}\right)_{k_{m-1} \leq i<k_{m}}$ holds, where $k_{0}=0, k_{l-1}=|\vec{k}|, k_{i}<k_{i+1}$ and all constructor types with the value type $\xi_{m}$ are listed by indices $i, k_{m-1} \leq i<k_{m}$. We define nest ${ }_{m}(\vec{\iota})$ to be the pair of algebras $\mu_{\xi_{m}}\left(\kappa_{i}\right)_{k_{m-1} \leq i<k_{m}}$ and $\mu_{\vec{\xi}-\xi_{m}}\left(\kappa_{0}^{\prime}, \ldots, \kappa_{k_{m-1}-1}^{\prime}, \kappa_{k_{m}}^{\prime}, \ldots, \kappa_{|\vec{k}|}^{\prime}\right)$, where $\vec{\xi}-\xi_{m}$ is the sublist of $\vec{\xi}$ excluding $\xi_{m}$, and $\kappa_{i}^{\prime}$ is obtained by substituting each occurrence of $\xi_{m}$ by $\mu_{\xi_{m}}\left(\kappa_{i}\right)_{k_{m-1} \leq i<k_{m}}$.

Definition 2.1.21 (Translation from nestedness to simultaneity). Assume an algebra $\iota(\alpha)=\mu_{\xi}\left(\vec{\kappa}_{0}\right)$ with at least one parameter type $\alpha$ and (simultaneous) algebras $\vec{\iota}=\mu_{\vec{\xi}}\left(\vec{\kappa}_{1}\right)$ of length $l$ are given. Suppose that for some $m<l, \iota\left(\xi_{m}\right)$ appears in $\overrightarrow{\kappa_{1}}$. We define simul $(\iota, \vec{\iota})$ to be algebras $\mu_{\zeta, \vec{\xi}}\left(\vec{\kappa}_{0}^{\prime}, \vec{\kappa}_{1}^{\prime}\right)$, where $\vec{\kappa}_{0}^{\prime}$ is obtained by replacing $\alpha$ in $\vec{\kappa}_{0}$ by $\xi_{m}$ and $\vec{\kappa}_{1}^{\prime}$ is obtained by replacing $\iota\left(\xi_{m}\right)$ in $\overrightarrow{k_{1}}$ by $\zeta$.

For simplicity, we do not consider to single out simultaneous parameterized algebras from simultaneous algebras, since it is always possible to single out non-simultaneous parameterized algebra. We take a look at an example.

Example 2.1.22 $((\mathbf{T s}, \mathbf{T})$ and $\mathbf{N t})$. Consider $(\mathbf{T s}, \mathbf{T})=\mu_{\xi_{0}, \xi_{1}}\left(\xi_{0}, \xi_{1} \rightarrow \xi_{0} \rightarrow \xi_{0}, \xi_{0} \rightarrow \xi_{1}\right)$, then $\operatorname{Inhab}\left(\xi_{0}, \xi_{1} \rightarrow \xi_{0} \rightarrow \xi_{0}\right)$ holds. We can introduce nestedness as nest ${ }_{0}(\mathbf{T s}, \mathbf{T})=$ $\left\langle\mathbf{L}_{\xi_{1}}, \mu_{\xi_{1}}\left(\mathbf{L}_{\xi_{1}} \rightarrow \xi_{1}\right)\right\rangle=\left\langle\mathbf{L}_{\xi_{1}}, \mathbf{N t}\right\rangle$, where $\mathbf{L}_{\xi_{1}}:=\mu_{\xi_{0}}\left(\xi_{0}, \xi_{1} \rightarrow \xi_{0} \rightarrow \xi_{0}\right)$. In the opposite direction, we can also introduce simultaneity as $\operatorname{simul}\left(\mathbf{L}_{\xi_{1}}, \mu_{\xi_{1}}\left(\mathbf{L}_{\xi_{1}} \rightarrow \xi_{1}\right)\right)=\mu_{\zeta, \xi_{1}}\left(\zeta, \xi_{1} \rightarrow\right.$ $\left.\zeta \rightarrow \zeta, \zeta \rightarrow \xi_{1}\right)=(\mathbf{T s}, \mathbf{T})$.

### 2.1.3 Partial Continuous Functionals

Now, we think about concrete information systems. For a type $\rho$ the information system $\mathrm{IS}_{\rho}$ is defined to be a triple $\left\langle\operatorname{Tok}_{\rho}, \mathrm{Con}_{\rho}, \vdash_{\rho}\right\rangle$. The partial continuous functionals of type $\rho$ are defined by the ideals $\left|\mathrm{IS}_{\rho}\right|$. The partial continuous functionals of type $\rho \rightarrow \sigma$ correspond to the continuous functions from $\left|\mathrm{IS}_{\rho}\right|$ to $\left|\mathrm{IS}_{\sigma}\right|$. The treatment of information systems and ideals are due to Schwichtenberg [SW12].

Definition 2.1.23 (Information systems). We simultaneously define $\operatorname{Tok}_{\iota}, \operatorname{Tok}_{\rho \rightarrow \sigma}, \operatorname{Con}_{\iota}$ and $\mathrm{Con}_{\rho \rightarrow \sigma}$.

1. The tokens in $\mathrm{Tok}_{\iota}$ are the type-correct constructor expressions $C_{\iota} \vec{a}^{*}$ where each $a_{i}^{*}$ is an extended token, namely, a token or the special symbol $*$ which carries no information.
2. The tokens in $\operatorname{Tok}_{\rho \rightarrow \sigma}$ are the pairs of $U$ in $\operatorname{Con}_{\rho}$ and $a$ in $\operatorname{Tok}_{\sigma}$.
3. The consistent set $\mathrm{Con}_{\iota}$ is a finite set $U$ of elements in $\mathrm{Tok}_{\iota}$ such that for a specific constructor $C$, say of type $\tau_{0} \rightarrow \cdots \rightarrow \tau_{n-1} \rightarrow \iota$, all elements of $U$ are of the form $C a_{i 0} \cdots a_{i n-1}$ satisfying that $\left\{a_{0 m}, a_{1 m} \cdots, a_{j m}\right\}$ are consistent for all $m<n$.
4. Let $I$ be a finite set of indices. Pairs $\left\{\left(U_{i}, b_{i}\right) \mid i \in I\right\}$ are in $\operatorname{Con}_{\rho \rightarrow \sigma}$ if and only if $\forall_{J \subseteq I}\left(\bigcup_{j \in J} U_{j} \in \operatorname{Con}_{\rho} \rightarrow\left\{b_{j} \mid j \in J\right\} \in \operatorname{Con}_{\sigma}\right)$.
We define $\vdash_{\iota}$ and $\vdash_{\rho \rightarrow \sigma}$.
5. For any $U, U \vdash_{\rho} *$ and $U \vdash_{\rho \rightarrow \sigma} *$.
6. Let $C$ be a constructor, then $\left\{C \vec{a}_{0}^{*}, \ldots, C \vec{a}_{n-1}^{*}\right\} \vdash{ }_{\iota} C \vec{a}^{*}$ if and only if $\left\{a_{0 m}, \ldots, a_{n-1 m}\right\} \vdash$ $a_{m}$.

Based on information systems developed so far, we define partial continuous functionals to be ideals.

Definition 2.1.24 (Partial continuous functionals). Let $\mathrm{IS}_{\rho}$ be the information system $\left\langle\operatorname{Tok}_{\rho}, \operatorname{Con}_{\rho}, \vdash_{\rho}\right\rangle$ of type $\rho$. The set of partial continuous functionals of type $\rho$ is defined to be the set of ideals in $\mathrm{IS}_{\rho}$.

A partial continuous functional $x$ is computable if $x$ is a recursively enumerable set of tokens. Among ideals, we define cototal and total ideals in which we are especially interested. We give an explicit definition of cototal and total ideals of finitary algebras. In general, we define cototality and totality predicates in Section 2.3 .

Definition 2.1.25 (One-step extension). Consider a constructor expression with at least one occurrence of the special token $*$. We denote $P(*)$ to mean such a constructor expression one of whose occurrences of $*$ is pointed. An arbitrary $P\left(C \vec{a}^{*}\right)$ is one-step extension of $P(*)$, written $P\left(C \vec{a}^{*}\right) \succ_{1} P(*)$. An occurrence of $*$ is non-parametric if the path from the root to this $*$ does not go through a parameter argument of a constructor.

Example 2.1.26 (One-step extension in $\mathbf{N}$ and $\mathbf{L})$. Assume algebras $\mathbf{N}$ and $\mathbf{L}(\mathbf{N})$. Let $P_{1}(*)$ be $\mathrm{S} *$ in $\mathbf{N}$, then $P_{1}(\mathrm{~S} *)$, namely, $\mathrm{S}(\mathrm{S} *)$ and also $P_{1}(0)$, namely, S 0 are one-step extensions, written $P_{1}(*) \succ_{1} P_{1}(\mathrm{~S} *)$ and $P_{1}(*) \succ_{1} P_{1}(0)$, respectively. Let $P_{2}(*)$ be $*:: *$ in $\mathbf{L}(\mathbf{N})$, where the first occurrence of $*$ is pointed, then $P_{2}(*) \succ_{1} P_{2}(0)$. Let $P_{3}$ be $*:: *$, where the second occurrence of $*$ is pointed, then $P_{3}(*) \succ_{1} P_{3}(*:: *)$. The occurrences of $*$ in $P_{1}$ and $P_{3}$ are non-parametric.

Definition 2.1.27 (Cototal ideals and total ideals of finitary algebras). Let $\iota$ be an algebra and $\mathrm{IS}_{\iota}$ be the information system of $\iota$. An ideal $x$ of $\mathrm{IS}_{\iota}$ is cototal if every constructor tree $P(*)$ in $x$ has a $\succ_{1}$-predecessor $P(C \vec{*})$ in $x$. A cototal ideal $x$ is total if the relation $\succ_{1}$ on $x$ is well founded. An ideal is called structure-cototal (structure-total) if $\succ_{1}$ is defined with respect to $P(*)$ with a non-parametric distinguished occurrence of $*$.

Example 2.1.28 (Ideals of $\mathrm{IS}_{\mathbf{N}}$ ). Consider tokens and entailment for $\mathbf{N}$ as in Figure 2.1. A line also means one-step extension of nodes, namely, viewed as tokens. An arbitrary path from a root, 0 or $S *$, forms an ideal. If a path reaches a leaf, which is a finite constructor expression with no $*$, a set of tokens on this path is a total ideal. If a path goes from $S *$ to the right branch, a set of tokens on this path is a cototal ideal $\left\{\mathrm{S}^{n} * \mid n \geq 1\right\}$.


Figure 2.1: Tokens and entailment in $\mathbf{N}$

Every constructor symbol $C$ of algebra $\iota$ generates the ideal in the function space by $r_{C}:=\left\{\left(\vec{U}, C \vec{a}^{*}\right) \mid \vec{U} \vdash \vec{a}^{*}\right\}$. Let $\iota, \vec{\iota}$ and $\vec{\iota}^{\prime}$ be algebras. If $\iota, \vec{\iota}=\operatorname{nest}_{n}\left(\vec{\iota}^{\prime}\right)$ for some $n$ or $\vec{\iota}^{\prime}=\operatorname{simul}(\iota, \vec{\iota})$, the domains $\left|\mathrm{IS}_{\iota}\right|$ and $\left|\mathrm{IS}_{\iota_{0}^{\prime}}\right|$, and the domains $\left|\mathrm{IS}_{\iota_{i}}\right|$ and $\left|\mathrm{IS}_{\iota_{i+1}^{\prime}}\right|$ for each $i$ are isomorphic. We formulate the domain isomorphism by means of approximable maps in the following way.
$\underline{\text { Definition 2.1.29 (Deductive closure). We define the deductive closure of } U \in \text { Con to be }}$ $\bar{U}:=\{a \mid U \vdash a\}$.

Definition 2.1.30 (Domain isomorphism). Let $\iota$ and $\iota^{\prime}$ be algebras. The domains $\mathrm{IS}_{\iota}$ and $\mathrm{IS}_{\iota^{\prime}}$ are isomorphic if there exists an approximable map $r \subseteq \mathrm{Con}_{\iota} \times \mathrm{Tok}_{\iota^{\prime}}$ such that the following holds:

1. $\forall_{U \in \mathrm{Con}_{\iota}}, \exists_{V \in \mathrm{Con}_{\iota^{\prime}}}, U^{r}=\bar{V}$,
2. $\forall_{V \in \operatorname{Con}_{\iota}}, \exists_{U \in \operatorname{Con}_{\iota}}, \bar{V}=U^{r}$,
3. $\forall_{U, V \in \operatorname{Con}_{\iota}}, U^{r} \subseteq V^{r} \rightarrow V \vdash U$,
where for $U \in \operatorname{Con}_{\iota}$ we abbreviate $\left\{b \in \operatorname{Tok}_{\iota^{\prime}} \mid U r b\right\}$ as $U^{r}$.
Proposition 2.1.31 (Domain isomorphism between nestedness and simultaneity). Let $\vec{\imath}$ and $\vec{\iota}$ be algebras of length $l$. If nest $t_{n}(\vec{\iota})=\left\langle\iota_{n}^{\prime}, \vec{\iota}-\iota_{n}^{\prime}\right\rangle$ for some $n<l$, where $\vec{\iota}-\iota_{n}^{\prime}$ is obtained by removing $\iota_{n}^{\prime}$ from $\vec{\iota}^{\prime}$, then $\left|\mathrm{IS}_{\iota_{i}}\right|$ is isomorphic to $\left|\mathrm{IS}_{\iota_{i}^{\prime}}\right|$ for each $i<l$. If $\operatorname{simul}\left(\iota_{n}^{\prime}, \vec{\iota}-\iota_{n}^{\prime}\right)=\left(\iota_{n}, \vec{\iota}-\iota_{n}\right)$, then $\left|\mathrm{IS}_{\iota_{i}}\right|$ is isomorphic to $\left|\mathrm{IS}_{\iota_{i}^{\prime}}\right|$ for each $i<l$.
Proof. For each $m<l$ we denote the constructors of algebras $\iota_{m}$ by $\vec{C}_{m}$ of length $k_{m}$ and the constructors of algebras $\iota_{m}^{\prime}$ by $\vec{C}_{m}^{\prime}$ of length $k_{m}$. We define bijections $\phi_{m}$ from a token of $\iota_{m}$ to a token of $\iota_{m}^{\prime}$.

$$
\phi_{m}(*):=*, \quad \phi_{m}\left(C_{m j}\left(\vec{a}^{*}\right)\right):=C_{m j}^{\prime}\left(\phi\left(a_{\nu}^{*}\right)\right)_{\nu<n_{m}} \text { for each } j<k_{m} .
$$

For each $m<l$ we define $r_{m} \subseteq \operatorname{Con}_{\iota_{m}^{\prime}} \times \operatorname{Tok}_{\iota_{m}}$ to be $U r_{m} b^{\prime}:=\bar{U} \ni \phi_{m}^{-1}\left(b^{\prime}\right)$, where $r_{m}$ is an approximable map. We prove the three conditions of domain isomorphisms. For the first one, we assume $U \in \operatorname{Con}_{\iota_{m}}$ and let $V$ be $\left\{\phi_{m}(b) \mid b \in U\right\}$ which is in $\operatorname{Con}_{\iota_{m}^{\prime}}$. For the second one, we use $\phi^{-1}$ instead. For the third one, we assume $U, V \in \mathrm{Con}_{\iota_{m}}$ and $U^{r} \subseteq V^{r}$, namely, $\forall_{b}(b \in \bar{U} \rightarrow b \in \bar{V})$. We prove $V \vdash U$ which is $\forall_{b \in U}(V \vdash b)$. Assume $b \in U$. By the assumption it implies $b \in \bar{V}$, hence $V \vdash b$.
Example 2.1.32 (Isomorphism between ( $\mathbf{T s}, \mathbf{T})$ and $\left.\left(\mathbf{L}_{\mathbf{N} t}, \mathbf{N t}\right)\right)$. Assume ( $\left.\mathbf{T s}, \mathbf{T}\right)$ and $\mathbf{N t}$. The domains $\left|\mathrm{IS}_{\mathbf{T s}}\right|$ and $\left|\mathrm{IS}_{\mathbf{L}_{\mathbf{N t}}}\right|$ are isomorphic and also $\left|\mathrm{IS}_{\mathbf{T}}\right|$ and $\left|\mathrm{IS}_{\mathbf{N t}}\right|$ are.

## $2.2 \mathrm{~T}^{+}$as an Extension of Gödel's T

We study the syntactic aspect of computation through a formal term language. By extending Gödel's T Göd58], we define a typed calculus $\mathrm{T}^{+}$. In addition to constructors and recursion operators of the original T , we have destructors, corecursion operators and programmable constants. One can define computation rules and also rewriting rules for a programmable constant. The syntax of $\mathrm{T}^{+}$is the following.

Definition 2.2.1 ( $\mathrm{T}^{+}$). Let $\rho, \sigma$ be types and $x$ a variable. Define terms as follows

$$
M, N:=x^{\rho}\left|\left(\lambda_{x^{\rho}} M^{\sigma}\right)^{\rho \rightarrow \sigma}\right|\left(M^{\rho \rightarrow \sigma} N^{\rho}\right)^{\sigma} \mid \mathrm{C}^{\rho}
$$

Here $\mathrm{C}^{\rho}$ is a constant, either a constructor, a recursion operator, a destructor, a corecursion operator or a programmable constant. We study them in the next sections. Following the standard way, we define the $\beta$-conversion.
Definition 2.2.2 (Free variables). We define a set of free variables $\mathrm{FV}(M)$ for a term $M$ by induction on the construction of the term.

$$
\begin{array}{ll}
\mathrm{FV}(x):=\{x\}, & \mathrm{FV}(M N):=\mathrm{FV}(M) \cup \mathrm{FV}(N), \\
\mathrm{FV}(\mathrm{C}):=\emptyset, & \mathrm{FV}\left(\lambda_{x} N\right):=\mathrm{FV}(N) \backslash\{x\} .
\end{array}
$$

The term substitution $M[x / N]$ is intuitively the result of replacing every occurrence of $x$ in $M$ by $N$. Formally we define it in the following way with avoiding the variable capturing.

Definition 2.2.3 (Term substitution). For terms $M, N$ we define the term substitution $M[x / N]$ by induction on the construction of $M$. In the last case we suppose that a fresh variable $z$ is available.

$$
\begin{aligned}
& x[x / N]:=N \\
& \mathrm{C}[x / N]:=\mathrm{C} \\
& z[x / N]:=z \text { where } z \text { is a variable with } z \neq x, \\
& \left(M_{0} M_{1}\right)[x / N]:=M_{0}[x / N]\left(M_{1}[x / N]\right) \\
& \left(\lambda_{x} M\right)[x / N]:=\lambda_{x} M \\
& \left(\lambda_{y} M\right)[x / N]:=\lambda_{y} M[x / N] \text { if } y \notin \mathrm{FV}(M), \\
& \left(\lambda_{y} M\right)[x / N]:=\left(\lambda_{z} M[y / z]\right)[x / N] \text { if } y \in \mathrm{FV}(M) .
\end{aligned}
$$

Definition 2.2.4 ( $\beta$-conversion). $\left(\lambda_{x} M\right) N \mapsto M[x / N]$.
In the rest of this section, we formally develop $\mathrm{T}^{+}$. Constructors and recursion operators are given in Section 2.2.1, corecursion operators and destructors are given in Section 2.2.2 and programmable constants are given in Section 2.2.3.

### 2.2.1 Constructors and Recursion Operators

For each constructor type of algebra, there is a constructor symbol. We adopt each constructor symbol as a special constant called constructors.

Definition 2.2.5 (Constructors). Let $\iota$ be an algebra $\mu_{\xi}\left(\left(\rho_{i \nu}(\xi)\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$. For each constructor type of $\iota$ a constructor $C_{i}$ is defined as a constant of type $\left(\rho_{i \nu}(\iota)\right)_{\nu<n_{i}} \rightarrow \iota$.

Constructors are means to construct (tree structured) objects from the root to the leaves. On the other hand, we have recursion operators to inspect an object which is built by constructors. A recursion operator reads an object from its leaves to the root. We define for each algebra $\iota$ the recursion operator $\mathcal{R}_{\iota}^{\tau}$ where $\tau$ is an arbitrary type parameter. We first define map operators which are used in the definition of the conversion rules of recursion operators. Then we define recursion operators. Later we also use map operators to define corecursion operators.

Definition 2.2.6 (Map operator). Let $\vec{\alpha}$ be a list of type variables of length $l \geq 0, \iota(\vec{\alpha})$ be an algebra $\mu_{\xi}\left(\left(\rho_{i \nu}(\vec{\alpha}, \xi)\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$ and $C_{i}^{\vec{\alpha}}$ be the $i$-th constructor of $\iota(\vec{\alpha})$. Assume a list of function types $\sigma_{i} \rightarrow \tau_{i}$ for $0 \leq i<l$, written $\vec{\sigma} \rightarrow \vec{\tau}$, where $l$ is the length of $\vec{\alpha}$. Assuming $\rho(\vec{\alpha})$ and $\vec{\pi}(\vec{\alpha})$ are a type and a list of types of length $k$, respectively, for where
the occurrences of $\vec{\alpha}$ in $\rho(\vec{\alpha})$ and $\pi_{j}(\vec{\alpha})$ for $j<k$ are strictly positive, we define the map operator $\mathcal{M}_{\lambda_{\vec{\alpha} \rho} \rho(\vec{\alpha})}^{\vec{\sigma} \rightarrow \overrightarrow{7}}$ by induction on the construction of $\rho$.

$$
\begin{aligned}
& \mathcal{M}_{\lambda_{\vec{\alpha}} \rho(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{F}}: \rho(\vec{\sigma}) \rightarrow\left(\sigma_{i} \rightarrow \tau_{i}\right)_{0 \leq i<l} \rightarrow \rho(\vec{\tau}), \\
& \mathcal{M}_{\lambda_{\vec{\alpha}}(\beta \rightarrow \rho(\vec{\alpha}))}^{\vec{\sigma} \rightarrow \vec{\alpha}} N^{\beta \rightarrow \rho(\vec{\sigma})} \vec{M} K^{\beta} \mapsto \mathcal{M}_{\lambda_{\vec{\alpha}} \rho(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{~}}(N K)^{\rho(\vec{\sigma})} \vec{M}, \\
& \mathcal{M}_{\lambda_{\vec{\alpha}} \alpha_{i}}^{\vec{\sigma} \rightarrow \vec{r}} N^{\sigma_{i}} \vec{M} \mapsto M_{i} N, \\
& \mathcal{M}_{\lambda_{\vec{\alpha}} \rho}^{\vec{\sigma} \rightarrow \vec{\tau}} N^{\rho} \vec{M} \mapsto N \quad \text { if } \mathrm{FV}(\rho) \cap \vec{\alpha}=\emptyset, \\
& \mathcal{M}_{\lambda_{\vec{\alpha}\langle\vec{\pi}(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{r}}}\left(C_{i}^{\vec{\pi}(\vec{\sigma})} \vec{N}\right)^{\iota \vec{\pi}(\vec{\sigma})} \vec{M} \mapsto C_{i}^{\vec{\pi}(\vec{\tau})}\left(\mathcal{M}_{\lambda_{\vec{\beta}, \gamma} \boldsymbol{\gamma}_{i \nu}(\vec{\beta}, \gamma)}^{\vec{\pi}(\vec{\sigma}), \iota \vec{\tau}(\vec{\tau}) \rightarrow \vec{r}), \iota_{\vec{\pi}(\vec{\tau})}} N_{\nu} \vec{K}\left(\mathcal{M}_{\iota}^{\vec{\pi}(\vec{\sigma}) \rightarrow \vec{\pi}(\vec{\tau})} \cdot \vec{K}\right)\right)_{\nu<n_{i}},
\end{aligned}
$$

where $\mathcal{M} \cdot \vec{M}$ stands for $\lambda_{x}(\mathcal{M} x \vec{M})$ and $K_{j}:=\mathcal{M}_{\lambda_{\vec{\alpha}} \pi_{j}(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{M}}$ for $j<|\vec{\pi}|$.
We define the type and the conversion rule of recursion operators.
Definition 2.2.7 (Recursion operator). Let $\iota$ be an algebra $\mu_{\xi}\left(\left(\rho_{i \nu}(\vec{\alpha}, \xi)\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$. For an arbitrary type $\tau$, the type of the recursion operator $\mathcal{R}_{\iota}^{\tau}$ is defined to be $\iota \rightarrow \vec{\delta} \rightarrow \tau$ where $\delta_{i}:=\left(\rho_{i \nu}(\vec{\alpha}, \iota \times \tau)\right)_{\nu<n_{i}} \rightarrow \tau$.

The conversion rule of the recursion operators is

$$
\mathcal{R}_{\iota}^{\tau}\left(C_{i} \vec{N}\right) \vec{M} \mapsto M_{i}\left(\mathcal{M}_{\lambda_{\xi} \rho_{i \nu}(\vec{\alpha}, \xi)}^{\iota \rightarrow<\tau} N_{\nu} \lambda_{z}\left\langle z, \mathcal{R}_{\iota}^{\tau} z \vec{M}\right\rangle\right)_{\nu<n_{i}} .
$$

We call each $\delta_{i}$ a step type and each $M_{i}$ a step term. If $\rho_{i \nu}(\vec{\alpha}, \xi)$ is just $\xi$, we conventionally type such a part of the step type $\delta_{i}$ by currying $\iota \times \tau$, namely, with duplicating $\iota$ and $\tau$. Then the conversion rule is given without a map operator, again by duplicating the arguments $N_{i}$ and $\mathcal{R}_{\iota}^{\tau} N_{i} \vec{M}$ in the step term $M_{i}$. Recursion operator $\mathcal{R}_{\iota}$ makes a case distinction on the outermost constructor of the first argument. Assuming the $i$-th constructor is the case, then the $i$-th step term is called with arguments including recursive calls of the recursion operator. An argument consists of two parts, the previous input and the previous output to the recursion operator, which are computed from the argument $N_{\nu}$ of the constructor by means of a map operator.

Example 2.2.8 (Type of $\mathcal{R}_{\mathbf{L}_{\alpha}}^{\tau}$ ). Consider the type of $\mathcal{R}_{\mathbf{L}_{\alpha}}^{\tau}$. In the form of constructor types, $n_{0}=0, n_{1}=2, \rho_{10}=\alpha$ and $\rho_{11}=\xi$ specify the above constructor types. Since $n_{0}=0$, no $\rho_{0 \nu}$ occurs, thus $\delta_{0}=\tau$. Next, $\delta_{1}=\alpha \rightarrow\left(\mathbf{L}_{\alpha} \times \tau\right) \rightarrow \tau$. As mentioned, here we use $\alpha \rightarrow \mathbf{L}_{\alpha} \rightarrow \tau \rightarrow \tau$ instead of the above step type with products by duplicating $\mathbf{L}_{\alpha} \times \tau$. Therefore, the type of $\mathcal{R}_{\mathbf{L}_{\alpha}}^{\tau}$ is $\mathbf{L}_{\alpha} \rightarrow \tau \rightarrow\left(\alpha \rightarrow \mathbf{L}_{\alpha} \rightarrow \tau \rightarrow \tau\right) \rightarrow \tau$.

Example 2.2.9 (Descending list of natural numbers). The recursion operator on natural numbers, $\mathcal{R}_{\mathrm{N}}^{\tau}$, is given as

$$
\begin{aligned}
& \mathcal{R}_{\mathbf{N}}^{\tau}: \mathbf{N} \rightarrow \tau \rightarrow(\mathbf{N} \rightarrow \tau \rightarrow \tau) \rightarrow \tau \\
& \mathcal{R}_{\mathbf{N}}^{\tau} 0 M_{0} M_{1} \mapsto M_{0} \\
& \mathcal{R}_{\mathbf{N}}^{\tau}(\mathrm{S} n) M_{0} M_{1} \mapsto M_{1} n\left(\mathcal{R}_{\mathbf{N}}^{\tau} n M_{0} M_{1}\right)
\end{aligned}
$$

The following term Desc computes a list of natural numbers descending from the given natural number to 1 .

$$
\begin{aligned}
& \text { Desc }: \mathbf{N} \rightarrow \mathbf{L}_{\mathbf{N}} \\
& \operatorname{Desc}:=\lambda_{n}\left(\mathcal{R}_{\mathbf{N}} n[] \lambda_{m, l}(\mathrm{Sm}:: l)\right) .
\end{aligned}
$$

The computation of Desc is as follows:

$$
\operatorname{Desc} 0 \mapsto[], \quad \operatorname{Desc}(\mathrm{S} n) \mapsto \mathrm{S} n:: \operatorname{Desc} n .
$$

Example 2.2.10 (Recursion operator on Nt ). The recursion operator on Nt is given as follows.

$$
\begin{aligned}
& \mathcal{R}_{\mathbf{N t}}^{\tau}: \mathbf{N t} \rightarrow\left(\mathbf{L}_{\mathbf{N t} \times \tau} \rightarrow \tau\right) \rightarrow \tau \\
& \mathcal{R}_{\mathbf{N t}}^{\tau}(\mathrm{Br} a s) M \mapsto M\left(\mathcal{M}_{\lambda_{\alpha} \mathbf{L}_{\alpha}}^{\mathbf{N t} \rightarrow \mathbf{N t} \times \tau}{ }_{\text {as } \lambda_{a}}\langle a, \mathcal{R} a M\rangle\right)
\end{aligned}
$$

An important variant of recursion operators is case operators. It is to make a case distinction on the outermost constructor.

Definition 2.2.11 (Case operator). Under the same assumptions in Definition 2.2.7, we define $\mathcal{C}_{\iota}^{\tau}$ to be a constant of type $\iota \rightarrow \vec{\sigma} \rightarrow \tau$, where $\sigma_{i}:=\left(\rho_{i \nu}(\vec{\alpha}, \iota)\right)_{\nu<n_{i}} \rightarrow \tau$. The conversion rule of the case operators is

$$
\mathcal{C}_{\iota}^{\tau}\left(C_{i} \vec{N}\right) \vec{M} \mapsto M_{i} \vec{N}
$$

Following a common style found in generic programming languages, we adopt to denote a term $\mathcal{C}_{\iota}^{\tau} t^{\iota} \vec{M}$ also in the following way.

where $x_{i \nu}$ is a fresh variable of type $\rho_{i \nu}(\vec{\alpha}, \iota)$ for $\nu<n_{i}$ and $L_{i}$ is a term such that $M_{i} \vec{x}_{i} \mapsto^{*} L_{i}$. We can omit $\vec{x}_{i}$ when $n_{i}=0$. A line break can be replaced by a semicolon (;).

A well-known programming construction of if-then-else is given by $\mathcal{C}_{\mathbf{B}}^{\tau}$ of type $\mathbf{B} \rightarrow \tau \rightarrow$ $\tau \rightarrow \tau$. We accept to denote $\mathcal{C}_{\mathbf{B}}^{\tau} M N_{0} N_{1}$ as follows.

## if $M$ then $N_{0}$ else $N_{1}$

We study simultaneous recursion operators.
Definition 2.2.12 (Simultaneous recursion operator). Let $\vec{\tau}$ and $\vec{\xi}$ be lists of types of length $l>0$ and $\vec{\iota}$ be simultaneous algebras $\mu_{\vec{\xi}}\left(\left(\rho_{i \nu}(\vec{\xi})\right)_{\nu<n_{i}} \rightarrow \xi_{j_{i}}\right)_{i<k}$. We define simultaneous
recursion operators on $\vec{\iota}$. For each $m<l$ let $\sigma_{m}$ be $\iota_{m} \times \tau_{m}$ and the step types $\delta_{j_{i}}$ be $\left(\rho_{i \nu}(\vec{\sigma})\right)_{\nu<n_{i}} \rightarrow \tau_{j_{i}}$, then the types of recursion operators are defined for $m<l$ as follows.

$$
\mathcal{R}_{\vec{l}, m}^{\vec{\tau}}: \iota_{m} \rightarrow \vec{\delta} \rightarrow \tau_{m} .
$$

The conversion rules are

$$
\mathcal{R}_{\vec{\imath}, j_{i}}^{\vec{\tau}}\left(C_{i} \vec{N}\right) \vec{M} \mapsto M_{i}\left(\mathcal{M}_{\left.\lambda_{\vec{\alpha}} \rho_{i \nu} \rightarrow \vec{\alpha}\right)} N_{\nu}\left(\lambda_{x}\left\langle x, \mathcal{R}_{\vec{l}, m}^{\vec{\tau}} x \vec{M}\right\rangle\right)_{m<l}\right)_{\nu<n_{i}} .
$$

Example 2.2.13 (Recursion operator on ( $\mathbf{T s}, \mathbf{T})$ ). Consider simultaneous recursion operators $\mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\vec{\tau}}$ and $\mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\vec{\tau}}$ which are non-nested. For $0 \leq i<3$, let $\delta_{i}$ be

$$
\delta_{0}:=\tau_{0}, \quad \delta_{1}:=\mathbf{T} \rightarrow \tau_{1} \rightarrow \mathbf{T s} \rightarrow \tau_{0} \rightarrow \tau_{0}, \quad \delta_{2}:=\mathbf{T s} \rightarrow \tau_{0} \rightarrow \tau_{1}
$$

The types of $\mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\vec{\tau}}$ and $\mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\vec{r}}$ are

$$
\mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\vec{\tau}}: \mathbf{T s} \rightarrow \delta_{0} \rightarrow \delta_{1} \rightarrow \delta_{2} \rightarrow \tau_{0}, \quad \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\vec{\tau}}: \mathbf{T} \rightarrow \delta_{0} \rightarrow \delta_{1} \rightarrow \delta_{2} \rightarrow \tau_{1}
$$

The conversion rules are as follows.

$$
\begin{aligned}
& \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\vec{\tau}} \text { Empty } \vec{M} \mapsto M_{0} \\
& \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\vec{\tau}}(\text { Tcons a as }) \vec{M} \mapsto M_{1} a\left(\mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\vec{r}} a \vec{M}\right) \text { as }\left(\mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\vec{\tau}} \vec{M} \vec{M}\right) \\
& \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\tau}(\text { Branch as }) \vec{M} \mapsto M_{2} \text { as }\left(\mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\tau} a s \vec{M}\right)
\end{aligned}
$$

Example 2.2.14 (Substitution of trees). We define a function of type $\mathbf{T} \rightarrow \mathbf{T} \rightarrow \mathbf{T}$ which replaces each leaves Branch Empty in the first argument by the second one as follows.

$$
\lambda_{a, b}\left(\mathcal{R}_{(\mathbf{T}, \mathbf{T}), 1} a b \lambda_{-, p,, q}(\operatorname{Branch}(\operatorname{Tcons} p q)) \lambda_{\_p} p\right) .
$$

The underscore ( - ) is used as a place holder for an abstracted variable which is unused.
When only some algebras of simultaneously defined ones are needed to recur, simplified simultaneous recursion operators suffice. Generally, we assume $\mathcal{R}_{\vec{\imath}}^{\vec{\tau}}$ is defined and build a simplified one. We first specify what algebras $\iota_{i_{0}}, \ldots, \iota_{i_{k}}$ from $\vec{\iota}$ are irrelevant, that is, are not needed to recur. We drop all $\delta_{i}$ whose final value type is one of $\tau_{i_{0}}, \ldots, \tau_{i_{k}}$. From argument types of each remaining $\delta_{i}$, we drop all $\iota_{i_{0}}, \ldots, \iota_{i_{k}}$ and $\tau_{i_{0}}, \ldots, \tau_{i_{k}}$. The remaining algebras are on the other hand called the relevant algebras.

For example, we simplify $\mathcal{R}_{\mathbf{T s}, \mathbf{T}}^{\vec{r}}$ in two ways.

1. No recursion on $\mathbf{T}$. Among $\vec{\delta}, \delta_{2}$ and $\delta_{3}$ are dropped because their final value type is $\tau_{1}$ which is irrelevant. Remaining step types are $\delta_{0}$ and $\delta_{1}$. The types $\mathbf{T}$ and $\tau_{1}$ occur in $\delta_{0}$ no more. From $\delta_{1}$ we remove the type arguments $\mathbf{T}$ and $\tau_{1}$. The type and the conversion rules are

$$
\begin{aligned}
& \mathcal{R}_{\mathbf{T s}}^{\tau}: \mathbf{T s} \rightarrow \tau \rightarrow(\mathbf{T s} \rightarrow \tau \rightarrow \tau) \rightarrow \tau \\
& \mathcal{R}_{\mathbf{T s}}^{\tau} \operatorname{Empty} M_{0} M_{1} \mapsto M_{0}, \quad \mathcal{R}_{\mathbf{T s}}^{\tau}(\text { Tcons } \text { a as }) M_{0} M_{1} \mapsto M_{1} a s\left(\mathcal{R}_{\text {Ts }}^{\tau} a s M_{0} M_{1}\right) .
\end{aligned}
$$

2. No recursion on Ts. As we did in 1., we remove irrelevant types. Then the type and the conversion rules are

$$
\mathcal{R}_{\mathbf{T}}^{\tau}: \mathbf{T} \rightarrow \tau \rightarrow \tau, \quad \mathcal{R}_{\mathbf{T}}^{\tau}(\text { Branch } \text { as }) M_{0} \mapsto M_{0}
$$

Example 2.2.15 (Length of a tree). We define a function $L h$ to count the length of a tree, namely, the number of branches at the root node.

$$
L h: \mathbf{T} \rightarrow \mathbf{N}, \quad L h:=\lambda_{a}\left(\mathcal{C} a \lambda_{a s}\left(\mathcal{R}_{\mathbf{T s}}^{\mathbf{N}} \text { as } 0 \lambda_{\_, n}(\mathbf{S} n)\right)\right) .
$$

Due to the inhabitedness of types, for an arbitrary type $\rho$ there is an inhabitant of type $\rho$, namely, a term of type $\rho$. We can find from the derivation of $\operatorname{Inhab}_{\vec{\zeta}}(\rho)$ an inhabitant of type $\rho$.

Definition 2.2.16 (Inhabitant). Assume $\tau$ is a type, a derivation of $\operatorname{Inhab}_{\vec{\zeta}}(\tau)$ is given and an inhabitant $c^{\alpha}$ of each type variable $\alpha \in \operatorname{FV}(\tau)$ is given. We inductively define from the derivation of $\operatorname{Inhab}_{\vec{\zeta}}(\tau)$ an inhabitant of type $\tau$. If $\operatorname{Inhab}_{\vec{\zeta}}(\alpha)$ is derived by the first rule, an inhabitant is $c^{\alpha}$. If $\operatorname{Inhab}_{\vec{\zeta}}(\rho \rightarrow \sigma)$ is derived by the second rule, there is an inhabitant $\lambda_{x \rho} c^{\sigma}$ of type $\rho \rightarrow \sigma$ where $c^{\sigma}$ comes by induction hypothesis. If $\operatorname{Inhab}_{\vec{\zeta}}(\iota)$, where $\iota=\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$, is derived by the third rule, there is an inhabitant $C_{i}\left(c^{\rho_{i \nu}}\right)_{\nu<n_{i}}$ where $C_{i}$ is the $i$-th constructor of $\iota$ and each $c^{\rho_{i \nu}}$ for all $\nu<n_{i}$ comes by induction hypothesis. An inhabitant $c^{\rho}$ is canonical if it is obtained from the canonical derivation of $\operatorname{Inhab}_{\vec{\zeta}}(\rho)$.

### 2.2.2 Destructors and Corecursion Operators

We study destructors and corecursion operators which are defined for each algebra. In contrast to constructors and recursion operators, here we deal with possibly non-well founded objects. Destructors are means to inspect an object. The inspection by destructors does not involve any repetition while the one of recursion operators does. On the other hand, corecursion operators provide means to construct an object. While one can build finite objects by constructors, one can build non-well founded objects by corecursion operators.

We take a look at an idea of the two new constants via an example in lists. Consider a term $M$ of type $\mathbf{L}_{\alpha}$ constructed by the corecursion operator of $\mathbf{L}_{\alpha}$. When the destructor is applied to $M$, the result tells us either

1. that $M$ behaves as an empty list and there is nothing to inspect, or
2. that $M$ behaves as a cons of the head $x$ and the tail $M^{\prime}$ which can be further inspected.

Using the destructor repeatedly, we can inspect $M, M^{\prime}, M^{\prime \prime}, \cdots$, then we observe $x, x^{\prime}$, $x^{\prime \prime}, \cdots$. It can be the case that the first case never happens. Through the observation by means of a destructor, a corecursion operator provides a reasonable way to form non-well founded objects. In fact our formulation of destructors and corecursion operators are slight different from what one expect from the above sketch: Our observation is done through
normalization without an explicit application of a destructor. An advantage is that our theory of abstract computability works also for the two constants due to cototal ideals.

We define finite products and finite sums of a list of types by generalizing the product algebra $\times$ and the sum algebra + . Intuitively the finite product is as an algebra $\mu_{\xi}\left(\alpha_{0} \rightarrow\right.$ $\left.\alpha_{1} \rightarrow \ldots \rightarrow \alpha_{n-1} \rightarrow \xi\right)$, and the finite sum is as $\mu_{\xi}\left(\alpha_{0} \rightarrow \xi, \alpha_{1} \rightarrow \xi, \ldots, \alpha_{n-1} \rightarrow \xi\right)$. Using them, the types of destructors and corecursion operators are given.

Definition 2.2.17 (Product type $\Pi$ ). Let $\vec{\tau}$ be a list of types. We define $\Pi \vec{\tau}$ by induction.

$$
\Pi():=\mathbf{U}, \quad \Pi(\tau):=\tau, \quad \Pi(\tau, \vec{\tau}):=\tau \times \Pi \vec{\tau} .
$$

Let $m$ be the length of $\vec{\tau}$. We define $\prod_{i<m} \tau_{i}$ to be $\prod \vec{\tau}$.
Definition 2.2.18 (Sum type $\sum$ ). We first define $\alpha_{0} \oplus \alpha_{1}$ as follows

$$
\begin{array}{ll}
\mathbf{U} \oplus \mathbf{U}:=\mathbf{B}, & \beta_{0} \oplus \mathbf{U}:=\mathbf{Y s u m u}_{\beta_{0}} \\
\mathbf{U} \oplus \beta_{1}:=\mathbf{U y s u m}_{\beta_{1}}, & \beta_{0} \oplus \beta_{1}:=\beta_{0}+\beta_{1}
\end{array}
$$

where $\beta_{0}$ and $\beta_{1}$ are not $\mathbf{U}$ and $\mathbf{Y s u m u} \boldsymbol{u}_{\alpha}$ is defined to be $\mu_{\xi}\left(\right.$ JustL $^{\alpha \rightarrow \xi}$, NoneR $\left.{ }^{\xi}\right)$. Let $\vec{\tau}$ be a list of types. We define $\sum \vec{\tau}$ by induction.

$$
\sum():=\mathbf{U}, \quad \sum(\tau):=\tau, \quad \sum(\tau, \vec{\tau}):=\tau \oplus \sum \vec{\tau}
$$

Let $m$ be the length of $\vec{\tau}$. We define $\sum_{i<m} \tau_{i}$ to be $\sum \vec{\tau}$.
For readability we can abuse the sum algebra $\alpha+\beta$ instead of $\alpha \oplus \beta$ in the definition of the sum type. Then, we can write $\mathbf{U}+\alpha$ instead of $\mathbf{U y s u m}{ }_{\alpha}, \alpha+\mathbf{U}$ instead of $\mathbf{Y s u m u}_{\alpha}$ and $\mathbf{U}+\mathbf{U}$ instead of $\mathbf{B}$. Corresponding to $\sum$ and $\Pi$, we define the generalized pairing and injection. Then, we consider conversion rules of corecursion operator.

Definition 2.2.19 (Pairing). Suppose that $\vec{t}$ is a non-empty list of terms, $\vec{\tau}$ is a non-empty list of types, where each $t_{i}$ is of type $\tau_{i}$ and a natural number $n$ is greater than 0 and smaller than or equal to the length of $\vec{t}$. We inductively define the pairing pair $\vec{\tau} \vec{t}$ of type $\prod_{i<n} \tau_{i}$.

$$
\operatorname{pair}^{()}():=\mathrm{U}, \quad \operatorname{pair}^{(\tau)}(t):=t, \quad \operatorname{pair}^{(\tau, \vec{\tau})}(t, \vec{t}):=\left\langle t, \operatorname{pair}^{\vec{\tau}}(\vec{t})\right\rangle
$$

The superscript $\vec{\tau}$ can be omitted unless it makes a confusion.
We define the injection without using $\ln _{\alpha, \beta}$ and $\operatorname{In} \mathrm{R}_{\alpha, \beta}$ provided $\alpha=\mathbf{U}$ or $\beta=\mathbf{U}$. If $\alpha=\beta=\mathbf{U}$, we use $\mathbf{T}$ and $\mathbf{F}$ instead of $\operatorname{InL} \mathrm{U}$ and $\operatorname{InRU}$, respectively. Similarly we use None $_{\beta}$ and $J^{\prime} \operatorname{Just}_{\beta} t^{\beta}$ instead of $\operatorname{InL}_{\mathbf{U}, \beta} \mathrm{U}$ and $\operatorname{InR}_{\mathbf{U}, \beta} t$, and Just ${ }_{\alpha} t^{\alpha}$ and NoneR ${ }_{\alpha}$ instead of $\operatorname{lnL} L_{\alpha, \mathrm{U}} t$ and $\operatorname{InR} \mathrm{R}_{\alpha, \mathbf{U}} \mathrm{U}$.

Definition 2.2.20 (Injection). Let $\vec{\tau}$ be a list of types and $m \leq 0$ be its length. We define the injection $\mathbf{i n}_{i<m}^{\vec{T}}$. If $m=0, \mathbf{i n}_{i<0}^{()}$is $\mathbf{U}$ of type $\mathbf{U}$. We can also write $\mathbf{i n}^{0}$ instead. If $m>0$,
let a term $t$ be of type $\tau_{i}$ for $i<m$ and we define the injection $\mathbf{i n}_{i<m}^{\vec{\tau}}$ of type $\tau_{i} \rightarrow \sum \vec{\tau}$. We first define $\mathbf{i n}_{j}^{\left\langle\alpha_{0}, \alpha_{1}\right\rangle}$ of type $\alpha_{j} \rightarrow \alpha_{0} \oplus \alpha_{1}$ for $j \in\{0,1\}$.

$$
\begin{aligned}
& \operatorname{in}_{0}^{\langle\mathbf{U}, \mathbf{U}\rangle}(t):=\mathrm{T}, \\
& \mathbf{i n}_{0}^{\left\langle\beta_{0}, \mathbf{U}\right\rangle}(t):=\operatorname{Just}_{\beta_{1}} t, \\
& \mathbf{i n}_{1}^{\langle\mathbf{U}, \mathbf{U}\rangle}(t):=\mathrm{F}, \\
& \mathbf{i n}_{1}^{\left\langle\beta_{0}, \mathbf{U}\right\rangle}(t):=\text { NoneR }_{\beta_{1}},
\end{aligned}
$$

$$
\mathbf{i n}_{0}^{\left\langle\mathbf{U}, \beta_{1}\right\rangle}(t):=\text { None }_{\beta_{1}}
$$

$$
\operatorname{in}_{0}^{\left\langle\beta_{0}, \beta_{1}\right\rangle}(t):=\ln _{\beta_{0}, \beta_{1}} t
$$

$$
\mathbf{i n}_{1}^{\left\langle\mathbf{U}, \beta_{1}\right\rangle}(t):=\mathrm{JustL}_{\beta_{1}} t
$$

$$
\operatorname{in}_{1}^{\left\langle\beta_{0}, \beta_{1}\right\rangle}(t):=\operatorname{lnR}_{\beta_{0}, \beta_{1}} t .
$$

Then, the injection is as follows

$$
\begin{array}{ll}
\mathbf{i n}_{i<1}^{(\tau)}(t):=t, & \operatorname{in}_{0<n+1}^{(\tau, \vec{\tau})}(t):=\mathbf{i n}_{0}^{\left\langle\tau, \sum \vec{\tau}\right\rangle}(t), \\
\mathbf{i n}_{n<n+1}^{\left(\tau, \tau^{\prime}\right)}(t):=\mathbf{i n}_{1}^{\left\langle\tau, \tau^{\prime}\right\rangle}(t), & \mathbf{i n}_{i+1<n+1}^{(\tau, \vec{\tau})}(t):=\mathbf{i n}_{0}^{\left\langle\tau, \sum \vec{\tau}\right\rangle}\left(\mathbf{i n}_{i<n}^{(\vec{\tau})}(t)\right) \text { if } i<n
\end{array}
$$

Let $m$ be the length of $\vec{\tau}$ We can write $\mathbf{i n}_{i}^{\vec{\tau}}(t)$ instead of $\mathbf{i n}_{i<m}^{\vec{\tau}}(t)$, and also $\mathbf{i n}_{i}^{m}(t)$ if $\vec{\tau}$ can be omitted.

For readability, we can abuse constructors of $\mathbf{U}$ and + in the following way to denote an injection. Let $\mathbf{i n}_{j}^{\left\langle\alpha_{0}, \alpha_{1}\right\rangle}$ of type $\alpha_{j} \rightarrow \alpha_{0}+\alpha_{1}$ for $j \in\{0,1\}$ be:

$$
\begin{array}{ll}
\mathbf{i n}_{0}^{\langle\mathbf{U}, \mathbf{U}\rangle}(t):=\operatorname{lnL} \mathbf{U}, & \operatorname{in}_{0}^{\left\langle\mathbf{U}, \beta_{1}\right\rangle}(t):=\operatorname{lnL} \mathbf{U}, \\
\mathbf{i n}_{0}^{\left\langle\beta_{0}, \mathbf{U}\right\rangle}(t):=\operatorname{lnL} t, & \operatorname{in}_{0}^{\left\langle\beta_{0}, \beta_{1}\right\rangle}(t):=\operatorname{lnL} t, \\
\mathbf{i n}_{1}^{\langle\mathbf{U}, \mathbf{U}\rangle}(t):=\operatorname{lnR} \mathbf{U}, & \operatorname{in}_{1}^{\left\langle\mathbf{U}, \beta_{1}\right\rangle}(t):=\operatorname{lnR} t, \\
\mathbf{i n}_{1}^{\left\langle\beta_{0}, \mathbf{U}\right\rangle}(t):=\operatorname{lnR} \mathbf{U}, & \mathbf{i n}_{1}^{\left\langle\beta_{0}, \beta_{1}\right\rangle}(t):=\operatorname{lnR} t .
\end{array}
$$

Corresponding to the generalized pairing and injection, we give the generalized projection and case distinction. Formally we can define them by means of the recursion operators on $\times$ and + or programmable constants given in Section 2.2.3.
Definition 2.2.21 (Projection). Suppose that $\vec{t}$ is a list of terms of length $n$ whose types are $\vec{\tau}$. We define the projection $\pi_{k}^{n}$ of type $\prod_{i<n} \tau_{i} \rightarrow \tau_{k}$ with the following conversion rule.

$$
\pi_{k}^{n}\left(\operatorname{pair}^{\vec{\tau}} \vec{t}\right) \mapsto t_{k}
$$

We define case operators on a generalized sum type.
Definition 2.2.22 (Case operator on a generalized sum). Suppose that $\vec{\alpha}$ is a list of types of length $n$. Let $x$ be a variable of type $\sum_{i<n} \alpha_{i}=: \rho$ and $M_{i}$ be a term of type $\alpha_{i} \rightarrow \tau$. We define a case operator $\mathcal{C}_{\rho}^{\tau}$ to be a constant of type $\rho \rightarrow\left(\alpha_{i} \rightarrow \tau\right)_{i<n} \rightarrow \tau$ with the conversion rule $\mathcal{C}\left(\mathbf{i n}_{i}^{n} t\right) \vec{M} \mapsto M_{i} t$ for $i<n$. We also adopt a programming language style expression of $\mathcal{C}\left(\mathbf{i n}_{i}^{n} t\right) \vec{M}$ as follows.

$$
\text { Case } x \text { of } \mathbf{i n}_{0}^{n} u_{0} \rightarrow L_{0} \quad \text { Case } x \text { of } \lambda_{u_{0}} L_{0}
$$

$$
\begin{array}{ll}
\vdots & \text { or } \\
\text { in }_{n-1}^{n} u_{n-1} \rightarrow L_{n-1} & \vdots \\
\lambda_{u_{n-1}} L_{n-1}
\end{array}
$$

where $u_{i}$ is a fresh variable of type $\alpha_{i}$ and $L_{i}$ is a term such that $M_{i} u_{i} \mapsto^{*} L_{i}$. Instead of a line break, we can use ";" for a delimitor as in Example 2.2.29. It is converted into $M_{i} y$, provided $x$ is of the form $\operatorname{in}_{i}^{n} y$ for some $i<n$. We also define a term $\left[M_{0}, \ldots, M_{n-1}\right]$ of type $\rho \rightarrow \tau$ to be $\lambda_{x}(\mathcal{C} x \vec{M})$.

We define destructors and corecursion operators.
Definition 2.2.23 (Types of destructor and corecursion operator). Let $\iota$ be an algebra $\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$. We define constants the destructor on $\iota$ and the corecursion operator on $\iota$ with a type parameter $\tau$, denoted by $\mathcal{D}_{\iota}$ and ${ }^{\text {co }} \mathcal{R}_{\iota}^{\tau}$, respectively. The type of $\mathcal{D}_{\iota}$ is

$$
\iota \rightarrow \sum_{i<k} \prod_{\nu<n_{i}} \rho_{i \nu}(\iota)
$$

and the type of ${ }^{\text {co }} \mathcal{R}_{\iota}^{\tau}$ is

$$
\tau \rightarrow\left(\tau \rightarrow \sum_{i<k} \prod_{\nu<n_{i}} \rho_{i \nu}(\iota \oplus \tau)\right) \rightarrow \iota
$$

The type $\tau$ is called the covalue type.
Example 2.2.24 (Types of $\mathcal{D}_{\mathbf{L}_{\alpha}}$ and ${ }^{\text {co }} \mathcal{R}_{\mathbf{L}_{\alpha}}^{\tau}$ ). Consider the type of $\mathcal{D}_{\mathbf{L}_{\alpha}}$. By Definition 2.2.18, $\mathbf{L}_{\alpha} \rightarrow \sum_{i<2} \prod_{\nu<n_{i}} \rho_{i \nu}\left(\alpha, \mathbf{L}_{\alpha}\right)=\mathbf{L}_{\alpha} \rightarrow \mathbf{U y s u m}\left(\alpha \times \mathbf{L}_{\alpha}\right)$. Then, the type of $\mathcal{D}_{\mathbf{L}_{\alpha}}$ is informally denoted as $\mathbf{L}_{\alpha} \rightarrow \mathbf{U}+\alpha \times \mathbf{L}_{\alpha}$. Again by Definition 2.2.18, $\sum_{i<2} \prod_{\nu<n_{i}} \rho_{i \nu}\left(\alpha, \mathbf{L}_{\alpha} \oplus \tau\right)=$ $\operatorname{Uysum}\left(\alpha \times\left(\mathbf{L}_{\alpha} \oplus \tau\right)\right)$ provided $\tau \neq \mathbf{U}$. The type of ${ }^{{ }^{c o} \mathcal{R}_{\mathbf{L}_{\alpha}}^{\tau}}$ is informally denoted as $\tau \rightarrow$ $\left(\tau \rightarrow \mathbf{U}+\alpha \times\left(\mathbf{L}_{\alpha}+\tau\right)\right) \rightarrow \mathbf{L}_{\alpha}$. If $\tau=\mathbf{U}, \sum_{i<2} \prod_{\nu<n_{i}} \rho_{i \nu}\left(\alpha, \mathbf{Y} \operatorname{sumu}\left(\mathbf{L}_{\alpha}\right)\right)=\mathbf{U y s u m}(\alpha \times$ $\left.\left(\mathbf{Y} \operatorname{sumu}\left(\mathbf{L}_{\alpha}\right)\right)\right)$. The type of ${ }^{\text {co }} \mathcal{R}_{\mathbf{L}_{\alpha}}^{\mathbf{U}}$ is simplified and denoted as $\mathbf{U}+\alpha \times\left(\mathbf{L}_{\alpha}+\mathbf{U}\right) \rightarrow \mathbf{L}_{\alpha}$.

The conversion rule of the destructor is given as follows.
Definition 2.2.25 (Conversion rule of destructor). Suppose that $\iota$ is an algebra defined to be $\mu_{\xi}\left(\left(\rho_{i \nu}(\xi)\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}$. The conversion rule of the destructor on $\iota$ is defined as follows.

$$
\mathcal{D}_{\iota}\left(C_{i} \vec{t}\right) \mapsto \operatorname{in}_{i}^{k}(\operatorname{pair}(\vec{t}))
$$

The conversion rules of the corecursion operator are given as follows.
Definition 2.2.26 (Conversion rule of corecursion operator). Let $\iota$ be $\mu_{\xi}\left(\left(\rho_{i \nu}(\xi)\right)_{\nu<n_{i}} \rightarrow\right.$ $\xi)_{i<k}$. For the $\iota$ and an arbitrary type $\tau$, we define the conversion rule of ${ }^{\text {co }} \mathcal{R}_{\iota}^{\tau}$ as follows.

$$
\begin{aligned}
& { }^{\mathrm{co}} \mathcal{R}_{\iota}^{\tau} \mapsto \lambda_{u, v}\left(\text { Case } v u \text { of } \operatorname{in}_{0}^{k} t \rightarrow C_{0}\left(\mathcal{M}_{\lambda_{\beta} \rho_{\rho \nu}(\beta)}^{\iota+\tau \rightarrow \iota}\left(\pi_{\nu}^{n_{0}} t\right)\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R}_{\iota}^{\tau} \cdot v\right]\right)_{\nu<n_{0}}\right. \\
& \vdots \\
& \left.\operatorname{in}_{k-1}^{k} t \rightarrow C_{k-1}\left(\mathcal{M}_{\lambda_{\beta} \rho_{(k-1) \nu}(\beta)}^{\iota+\tau \rightarrow \iota}\left(\pi_{\nu}^{n_{k-1}} t\right)\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R}_{\iota}^{\tau} \cdot v\right]\right)_{\nu<n_{k-1}}\right) .
\end{aligned}
$$

If $n_{i}=0$, we take $\mathbf{i n}_{i}^{k} \mathrm{U} \rightarrow C_{i}$ instead of a line in the above. We can omit the case distinction and the constructor immediately comes when $k=1$.

We take a look at definitions of destructors on some algebras from Example 2.1.13, 2.1.14, 2.1.15 and 2.1.16.

Example 2.2.27 (Destructors on a simple algebra).

$$
\begin{array}{ll}
\mathcal{D}_{\mathbf{U}}: \mathbf{U} \rightarrow \mathbf{U} & \mathcal{D}_{\mathbf{B}}: \mathbf{B} \rightarrow \mathbf{U}+\mathbf{U} \\
\mathcal{D}_{\mathbf{U}} \mathrm{U} \mapsto \mathrm{U} & \mathcal{D}_{\mathbf{B}} F \mapsto \operatorname{lnL} \mathrm{U}, \quad \mathcal{D}_{\mathbf{B}} \mathbf{T} \mapsto \operatorname{lnR} \mathrm{U} \\
& \\
\mathcal{D}_{\mathbf{N}}: \mathbf{N} \rightarrow \mathbf{U}+\mathbf{N} & \mathcal{D}_{\mathbf{D}}: \mathbf{D} \rightarrow \mathbf{U}+(\mathbf{D} \times \mathbf{D}) \\
\mathcal{D}_{\mathbf{N}} 0 \mapsto \operatorname{lnL} \mathrm{U} & \mathcal{D}_{\mathbf{D}} 0 \mapsto \operatorname{lnL} \mathrm{U} \\
\mathcal{D}_{\mathbf{N}}(\mathrm{S} n) \mapsto \operatorname{lnR} n & \mathcal{D}_{\mathbf{D}}\left(\mathrm{D} d_{0} d_{1}\right) \mapsto \operatorname{lnR}\left\langle d_{0}, d_{1}\right\rangle
\end{array}
$$

Example 2.2.28 (Destructors on parameterized, nested and non-finitary algebras).

$$
\begin{array}{ll}
\mathcal{D}_{\mathbf{L}_{\alpha}}: \mathbf{L}_{\alpha} \rightarrow \mathbf{U}+\alpha \times \mathbf{L}_{\alpha} & \mathcal{D}_{\mathbf{N t}}: \mathbf{N t} \rightarrow \mathbf{L}_{\mathbf{N t}} \\
\mathcal{D}_{\mathbf{L}_{\alpha}}[] \mapsto \operatorname{lnL} \mathbf{U} & \mathcal{D}_{\mathbf{N t}}(\operatorname{Br} a s) \mapsto \text { as } \\
\mathcal{D}_{\mathbf{L}_{\alpha}}(x:: x s) \mapsto \operatorname{lnR}\langle x, x s\rangle & \\
& \\
\mathcal{D}_{\mathbf{O}}: \mathbf{O} \rightarrow \mathbf{U}+\mathbf{O}+(\mathbf{N} \rightarrow \mathbf{O}) & \\
\mathcal{D}_{\mathbf{O}} 0 \mapsto \operatorname{lnL} \mathbf{U} & \\
\mathcal{D}_{\mathbf{O}}(\mathrm{S} x) \mapsto \operatorname{lnR}(\operatorname{lnL} x) & \\
\mathcal{D}_{\mathbf{O}}(\operatorname{Sup} f) \mapsto \operatorname{lnR}(\operatorname{lnR} f) &
\end{array}
$$

We take a look at definitions of corecursion operators on some algebras from Example 2.1.13, 2.1.14, 2.1.15 and 2.1.16.

Example 2.2.29 (Corecursion operators on a simple algebra).

$$
\begin{aligned}
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{U}}^{\tau}: \tau \rightarrow(\tau \rightarrow \mathbf{U}) \rightarrow \mathbf{U} \\
& { }^{{ }^{c o}} \mathcal{R}_{\mathbf{B}}^{\tau}: \tau \rightarrow(\tau \rightarrow \mathbf{B}+\mathbf{B}) \rightarrow \mathbf{B} \\
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{U}}^{\tau} \mapsto \lambda_{u, v}(\text { Case } v u \text { of } \mathrm{U} \rightarrow \mathbf{U}) \quad{ }^{\mathrm{co}} \mathcal{R}_{\mathbf{B}}^{\tau} \mapsto \lambda_{u, v}(\text { Case } v u \text { of } \operatorname{InL} \mathrm{U} \rightarrow \operatorname{InL} \mathbf{U} \\
& \operatorname{lnRU} \rightarrow \operatorname{lnRU}) \\
& { }^{\text {co }} \mathcal{R}_{\mathbf{N}}^{\tau}: \tau \rightarrow(\tau \rightarrow \mathbf{U}+(\mathbf{N}+\tau)) \rightarrow \mathbf{N} \\
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{N}}^{\tau} \mapsto \lambda_{u, v}\left(\text { Case } v u \text { of } \operatorname{InL} \mathrm{U} \rightarrow 0 ; \operatorname{lnR} x \rightarrow \mathrm{~S}\left(\mathcal{M} x\left[\mathrm{id}, \lambda_{z}\left({ }^{\mathrm{co}} \mathcal{R}_{\mathrm{N}}^{\tau} z v\right)\right]\right)\right) \\
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{D}}^{\tau}: \tau \rightarrow(\tau \rightarrow \mathbf{U}+(\mathbf{D}+\tau) \times(\mathbf{D}+\tau)) \rightarrow \mathbf{D} \\
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{D}}^{\tau} \mapsto \lambda_{u, v}\left(\text { Case } v u \text { of } \operatorname{InL} \mathrm{U} \rightarrow 0 ; \ln \mathrm{R} x \rightarrow \mathrm{D}\left(\mathcal{M}\left(\pi_{0} x\right)\left[\mathrm{id}, \lambda_{z}\left({ }^{\mathrm{co}} \mathcal{R}_{\mathbf{D}}^{\tau} z v\right)\right]\right)\right. \\
& \left.\left(\mathcal{M}\left(\pi_{1} x\right)\left[\mathrm{id}, \lambda_{z}\left({ }^{\mathrm{Co}} \mathcal{R}_{\mathrm{D}}^{\tau} z v\right)\right]\right)\right)
\end{aligned}
$$

Example 2.2.30 (Corecursion operators on parameterized, nested and non-finitary alge-
bras).

$$
\begin{aligned}
& { }^{c 0} \mathcal{R}_{\mathbf{L}_{\alpha}}^{\tau}: \tau \rightarrow\left(\tau \rightarrow \mathbf{U}+\alpha \times\left(\mathbf{L}_{\alpha}+\tau\right)\right) \rightarrow \mathbf{L}_{\alpha} \\
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{L}_{\alpha}}^{\tau} \mapsto \lambda_{u, v}\left(\text { Case } v u \text { of } \operatorname{InL} \mathrm{U} \rightarrow[] ; \operatorname{lnR} y \rightarrow \pi_{0} y:: \mathcal{M}\left(\pi_{1} y\right)\left[\mathrm{id}, \lambda_{z}\left({ }^{\mathrm{co}} \mathcal{R}_{\mathbf{L}_{\alpha}}^{\tau} z v\right)\right]\right) \\
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{N t}}^{\tau}: \tau \rightarrow\left(\tau \rightarrow \mathbf{L}_{\mathbf{N t + \tau}}\right) \rightarrow \tau \\
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{N t}}^{\tau} \mapsto \lambda_{u, v}\left(\operatorname{Br}\left(\mathcal{M}_{\lambda_{\alpha} \mathbf{L}_{\alpha}}^{\mathbf{N t}+\tau \rightarrow \mathbf{N t}}(v u)\left[\mathrm{id}, \lambda_{z}\left({ }^{\mathrm{co}} \mathcal{R}_{\mathbf{N t}}^{\tau} z v\right)\right]\right)\right) \\
& { }^{\mathrm{co}} \mathcal{R}_{\mathbf{O}}^{\tau}: \tau \rightarrow(\tau \rightarrow \mathbf{U}+(\mathbf{O}+\tau)+(\mathbf{N} \rightarrow \mathbf{O}+\tau)) \rightarrow \mathbf{O} \\
& { }^{c 0} \mathcal{R}_{\mathbf{O}}^{\tau} \mapsto \lambda_{u, v}(\text { Case } v u \text { of } \operatorname{InL} \mathrm{U} \rightarrow 0 \\
& \operatorname{InR}(\operatorname{InL} y) \rightarrow \mathrm{S}\left(\mathcal{M} y\left[\mathrm{id}, \lambda_{z}\left({ }^{\mathrm{co}} \mathcal{R}_{\mathrm{O}}^{\tau} z v\right)\right]\right) \\
& \left.\operatorname{InR}(\operatorname{InR} f) \rightarrow \operatorname{Sup}\left(\mathcal{M} f\left[\operatorname{id}, \lambda_{z}\left({ }^{(\mathrm{co}} \mathcal{R}_{\mathbf{O}} z v\right)\right]\right)\right)
\end{aligned}
$$

Destructors and corecursion operators are also defined on simultaneous algebras. In the definition of destructors, we collect the relevant types of constructors whose value type is same as the argument type of the destructor.

Definition 2.2.31 (Destructors and corecursion operators on simultaneous algebras). Let $\vec{\iota}$ be simultaneous algebras $\mu_{\vec{\xi}}\left(\left(\rho_{i \nu}(\vec{\xi})\right)_{\nu<n_{i}} \rightarrow \xi_{j_{i}}\right)_{i<k}$ of length $l$. For each $m<l$, we can find a list of indices $\vec{r}_{m}$, such that $j_{i}=m$ if and only if $i$ is in $\vec{r}_{m}$. For each $m<l$ let $i$ be in $\vec{r}_{m}$ and $\hat{\imath}$ be an index to get $i$ from $\vec{r}_{m}$, namely, $i=r_{m \hat{\imath}}$. The type and the conversion rule of the destructor are defined to be

$$
\mathcal{D}_{\vec{\imath}, m}: \iota_{m} \rightarrow \sum_{i<\left|\vec{r}_{m}\right|} \prod_{\nu<n_{i}} \rho_{r_{m i} \nu}(\vec{\iota}), \quad \mathcal{D}_{\vec{\iota}, m}\left(C_{i} \vec{t}\right) \mapsto \mathbf{i n}_{i}^{\left|\vec{r}_{m}\right|}(\text { pair } \vec{t}) .
$$

Let $\sigma_{i}$ be a sum type $\iota_{i}+\tau_{i}$. For each $m<l$ we define the $m$-th costep type $\delta_{m}$ to be $\tau_{i} \rightarrow$ $\sum_{i<\left|\vec{r}_{m}\right|} \prod_{\nu<n_{i}} \rho_{i \nu}(\vec{\sigma})$. The type of the $m$-th corecursion operator ${ }^{\text {co }} \mathcal{R}_{\overrightarrow{,}, m}^{\vec{r}}$ is $\tau_{m} \rightarrow \vec{\delta} \rightarrow \iota_{m}$. Its conversion rule is given as

$$
\begin{aligned}
& { }^{\mathrm{c}} \mathcal{R}_{\vec{l}, m}^{\vec{\tau}} \mapsto \lambda_{u, \vec{v}}\left(\text { Case } v_{m} u\right. \text { of } \\
& \operatorname{in}_{0}^{k^{\prime}} t \rightarrow C_{0}\left(\mathcal{M}_{\lambda_{\vec{\beta}} \rho_{0 \nu}(\vec{\beta})}^{\vec{\sigma} \rightarrow \vec{~}}\left(\pi_{\nu}^{n_{0}} t\right)\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R}_{\vec{\imath}, m}^{\vec{T}} \cdot \vec{v}\right]_{m<l}\right)_{\nu<n_{0}} \\
& \quad \vdots \\
& \left.\operatorname{in}_{k^{\prime}-1}^{k^{\prime}} t \rightarrow C_{k^{\prime}-1}\left(\mathcal{M}_{\lambda_{\vec{\beta}} \rho_{\left(k^{\prime}-1\right) \nu}(\vec{\beta})}^{\vec{\sigma} \rightarrow \vec{\beta}}\left(\pi_{\nu}^{n_{k^{\prime}-1}} t\right)\left[\mathrm{id},{ }^{\mathrm{c}} \mathcal{R}_{\vec{\imath}, m}^{\vec{\tau}} \cdot \vec{v}\right]_{m<l}\right)_{\nu<n_{k^{\prime}-1}}\right),
\end{aligned}
$$

where $k^{\prime}:=\left|\vec{r}_{m}\right|$.
We take a look at an example of destructors and corecursion operators on simultaneous algebras.

Example 2.2.32 (Destructors on simultaneous algebras).

$$
\begin{array}{ll}
\mathcal{D}_{(\mathbf{T s}, \mathbf{T}), 0}: \mathbf{T s} \rightarrow \mathbf{U}+\mathbf{T} \times \mathbf{T s} & \mathcal{D}_{(\mathbf{T s}, \mathbf{T}), 1}: \mathbf{T} \rightarrow \mathbf{T s} \\
\mathcal{D}_{(\mathbf{T s}, \mathbf{T}), 0} \text { Empty } \mapsto \operatorname{InL} \mathrm{U} & \mathcal{D}_{(\mathbf{T s}, \mathbf{T}), 1}(\text { Branch } a s) \mapsto a s \\
\mathcal{D}_{(\mathbf{T s}, \mathbf{T}), 0}(\text { Tcons } a a s) \mapsto \operatorname{InR}\langle a, a s\rangle &
\end{array}
$$

Example 2.2.33 (Corecursion operators on simultaneous algebras).

$$
\begin{aligned}
& { }^{\mathrm{co}} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\left(\tau_{0}, \tau_{1}\right)}: \tau_{0} \rightarrow\left(\tau_{0} \rightarrow \mathbf{U}+\left(\mathbf{T}+\tau_{1}\right) \times\left(\mathbf{T s}+\tau_{0}\right)\right) \rightarrow\left(\tau_{1} \rightarrow \mathbf{T s}+\tau_{0}\right) \rightarrow \mathbf{T s} \\
& { }^{\text {co }} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\left(\tau_{0}, \tau_{1}\right)} \mapsto \lambda_{u, v_{0}, v_{1}} \text { (Case } v_{0} u \text { of } \\
& \text { InL U } \rightarrow \text { Empty } \\
& \operatorname{InR} x \rightarrow \operatorname{Tcons}\left(\mathcal{M}\left(\pi_{0} x\right)\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\vec{r}} \cdot \vec{v}\right]\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\vec{r}} \cdot \vec{v}\right]\right) \\
& \left.\left(\mathcal{M}\left(\pi_{1} x\right)\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 0}^{\vec{r}} \cdot \vec{v}\right]\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\vec{\tau}} \cdot \vec{v}\right]\right)\right) \\
& { }^{\mathrm{co}} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\left(\tau_{0}, \tau_{1}\right)}: \tau_{1} \rightarrow\left(\tau_{0} \rightarrow \mathbf{U}+\left(\mathbf{T}+\tau_{1}\right) \times\left(\mathbf{T s}+\tau_{0}\right)\right) \rightarrow\left(\tau_{1} \rightarrow \mathbf{T s}+\tau_{0}\right) \rightarrow \mathbf{T} \\
& { }^{\mathrm{co}} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), 1}^{\left(\tau_{0}, \tau_{1}\right)} \mapsto \lambda_{u, v_{0}, v_{1}}\left(\operatorname{Branch}\left(\mathcal{M}\left(v_{1} u\right)\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R}_{(\mathbf{T s}, \mathbf{T}), m}^{\vec{\tau}} \cdot \vec{v}\right]_{m<l}\right)\right)
\end{aligned}
$$

Example 2.2.34 (Infinite list of ascending natural numbers). By means of corecursion on $\mathbf{L}_{\mathbf{N}}$ we define an infinite list of natural numbers ascending from the given $n$.

$$
\begin{aligned}
& \text { Asc }: \mathbf{N} \rightarrow \mathbf{L}_{\mathbf{N}} \\
& \text { Asc }:=\lambda_{n}\left({ }^{\text {co }} \mathcal{R}_{\mathbf{N}} n \lambda_{m}\langle m, \ln \mathrm{R}(\operatorname{lnR}(\mathrm{~S} m))\rangle\right)
\end{aligned}
$$

The conversion sequence yielded by Ascn is

$$
\text { Asc } n \mapsto^{*} n:: A s c(\mathrm{~S} n) \mapsto^{*} n:: \mathrm{S} n:: \operatorname{Asc}(\mathrm{S}(\mathrm{~S} n)) \mapsto^{*} \ldots
$$

### 2.2.3 Programmable Constants

Programmable constants are constants defined by specifying a name and its type. One can give computational meaning of such a constant by defining computation rules under some conditions. It is also possible to give rewriting rules which are more flexible than computation rules. Following Schwichtenberg [SW12], we first define programmable constants and computation rules, then define rewriting rules as well.

Definition 2.2.35 (Programmable constants). A programmable constant is defined by specifying a name $C$ and its type $\rho$.

We introduce constructor patterns in order to formalize computation of programmable constants.

Definition 2.2.36 (Constructor pattern). We inductively define CP.

$$
\begin{aligned}
& \overline{\mathrm{CP}()}, \quad \frac{\mathrm{CP}_{\vec{x}}(\vec{P}) \quad \mathrm{CP}_{\vec{y}}(Q) \quad \vec{x}, \vec{y} \text { are disjoint }}{\mathrm{CP}_{\vec{x}, \vec{y}}(\vec{P}, Q)} \\
& \overline{\mathrm{CP}_{x}(x)}, \quad \frac{\mathrm{C}_{\vec{r} \rightarrow \iota} \text { is a constructor } \quad \mathrm{CP}_{\vec{x}}(\vec{P})}{\mathrm{CP}_{\vec{x}}\left((\mathrm{C} \vec{P})^{\iota}\right)}
\end{aligned}
$$

When $\mathrm{CP}_{\vec{x}}(P)$ holds, $P$ is a constructor pattern with variables $\vec{x}$.

Definition 2.2.37 (Computation rules). Let $D$ be a programmable constant of type $\vec{\sigma} \rightarrow \tau$. Computation rules of $D$ are finitely many equations of the form

$$
D \vec{P}_{i}\left(\vec{y}_{i}\right)=M_{i},
$$

where free variables of $\vec{P}_{i}\left(\vec{y}_{i}\right)$ and $M$ are among $\vec{y}_{i}$ under the following requirements. Each $\vec{P}_{i}$ is a constructor pattern such that for $i \neq j, \vec{P}_{i}$ and $\vec{P}_{j}$ have disjoint free variables and are not unifiable. Moreover, the lengths of all $\vec{P}_{i}\left(\vec{y}_{i}\right)$ are the same. This length is called the arity of $D$ denoted by $\operatorname{ar}(D)$. Each equation is also adopted as a conversion rule from the left to the right.
Example 2.2.38 (Predecessor). Let $P$ be a programmable constant of type $\mathbf{N} \rightarrow \mathbf{N}$. The following equations define the predecessor of natural numbers.

$$
P 0=0, \quad P(\mathrm{~S} n)=n .
$$

Even if a rule does not satisfy the condition to be a computation rule, the rule can be defined as a rewriting rule.

Definition 2.2.39 (Rewriting rule). Let $D$ be a programmable constant of type $\vec{\sigma} \rightarrow \tau$. Rewriting rules of $D$ are finitely many equations of the form

$$
D \vec{N}=M
$$

where $N_{i}$ is of type $\sigma_{i}$. If $D \vec{N}=M$ is not a proven proposition, the equation has to be added as an axiom. The consistency has to be considered as well. Each equation is also adopted as a conversion rule from the left to the right.
Example 2.2.40 (Addition of natural numbers). Consider the addition on natural numbers by means of a programmable constant. Let $+\mathbf{N} \rightarrow \mathbf{N} \rightarrow \mathbf{N}$ be a programmable constant. In the infix notation we define the following computation rules.

$$
n+0=n, \quad n+(\mathrm{S} m)=\mathrm{S}(n+m) .
$$

In addition, we prove the following three equations,

$$
\begin{aligned}
& \forall_{n}(0+n=n), \quad \forall_{n, m}((\mathrm{~S} m)+n=\mathrm{S}(n+m)), \\
& \forall_{n, m, k}(n+(m+k)=(n+m)+k)
\end{aligned}
$$

then add them as rewriting rules.

### 2.2.4 Denotational Semantics

The term calculus $\mathrm{T}^{+}$is a concrete representation of our abstract notion of computability. We describe denotational semantics of $\mathrm{T}^{+}$due to Schwichtenberg [SW12] and normalization by evaluation due to Berger and Schwichtenberg [BS91]. Considering ideals as denotation of terms of $\mathrm{T}^{+}$, we define the relation between a token $(\vec{U}, b)$ and the denotation of a term $M$, written as $(\vec{U}, b) \in \llbracket M \rrbracket$, by induction on the construction of $M$. We denote $\left(U_{1}, \ldots,\left(U_{n}, b\right) \ldots\right)$ by $(\vec{U}, b)$ and $(\vec{U}, b) \in \llbracket \lambda_{\vec{x}} M \rrbracket$ for all $b \in V$ by $(\vec{U}, V) \subseteq \llbracket \lambda_{\vec{x}} M \rrbracket$.

Definition 2.2.41 (Denotational semantics). Let $b$ range over tokens, $U, V$, and $W$ over sets of tokens, $x$ and $y$ over variables, $M$ and $N$ over terms, $C$ over constructors, and $D$ over a constant with computation rules as $D \vec{P}(\vec{y})=M$ where each of $\vec{P}$ is a constructor pattern. We define the denotation of a term by induction.

$$
\begin{array}{cc}
\frac{U_{i} \vdash b}{(\vec{U}, b) \in \llbracket \lambda_{\vec{x}} x_{i} \rrbracket}(V), & \frac{(\vec{U}, V, b) \in \llbracket \lambda_{\vec{x}} M \rrbracket \quad(\vec{U}, V) \subseteq \llbracket \lambda_{\vec{x}} N \rrbracket}{(\vec{U}, b) \in \llbracket \lambda_{\vec{x}}(M N) \rrbracket}(A) \\
\frac{\vec{V} \vdash \vec{b}^{*}}{\left(\vec{U}, \vec{V}, C \vec{b}^{*}\right) \in \llbracket \lambda_{\vec{x}} C \rrbracket}(C), \quad \frac{(\vec{U}, \vec{V}, b) \in \llbracket \lambda_{\vec{x}, \vec{y}} M \rrbracket \vec{W} \vdash \vec{P}(\vec{V})}{(\vec{U}, \vec{W}, b) \in \llbracket \lambda_{\vec{x}} D \rrbracket}(D) .
\end{array}
$$

The denotation of a term in $\mathrm{T}^{+}$is an ideal as expected. Essential properties as the preservation of values and adequacy with respect to operational semantics based on conversion rules also enjoy. See [BS91, BES03] for details.

One application of the denotational semantics is normalization by evaluation, NbE in short, which is an efficient algorithm to normalize terms BS91, BES03, SW12. It is also a theoretical basis of the implementation of normalization in the Minlog system. A term is a normal form if no conversion rule applies. For a given term $M$ such a long normal form, written $\operatorname{nf}(M)$, is computed by NbE in the following way: We first evaluate $M$ to an object $a$ in some denotational semantics. Then, we retrieve from $a$ the long normal form $\operatorname{nf}(M)$. We define the interpretation of types as follows.

Definition 2.2.42 (Interpretation of types). Let $\Lambda_{\rho}$ be the set of all terms of type $\rho$. We define the interpretation of types by induction on a type.

$$
\llbracket \iota \rrbracket:=\Lambda_{\iota}, \quad \llbracket \rho \rightarrow \sigma \rrbracket:=\llbracket \sigma \rrbracket^{\llbracket \rho \rrbracket}
$$

Meaning of free variables in an object can be given by an assignment $\uparrow$ lifting a variable to an object. We write $\llbracket M \rrbracket_{\uparrow}$ to mean the object of $M$ under the assignment $\uparrow$. We also consider a function $\downarrow$ which retrieves a long normal form from an object. We simultaneously define $\uparrow$ and $\downarrow$, called reflect and reify, respectively. For convenience we define $\uparrow$ on terms rather than on variables.

Definition 2.2.43 (Reflect and reify). We simultaneously define two functions $\uparrow_{\rho}: \Lambda_{\rho} \rightarrow \llbracket \rho \rrbracket$ and $\downarrow_{\rho}: \llbracket \rho \rrbracket \rightarrow \Lambda_{\rho}$.

$$
\begin{array}{ll}
\uparrow_{\iota}(M):=M, & \downarrow_{\iota}(M):=M \\
\uparrow_{\rho \rightarrow \sigma}(M)(a):=\uparrow_{\sigma}\left(M \downarrow_{\rho}(a)\right), & \downarrow_{\rho \rightarrow \sigma}(a):=\lambda_{x}\left(\downarrow_{\sigma}\left(a\left(\uparrow_{\rho}(x)\right)\right)\right),
\end{array}
$$

where $x$ is a fresh variable.
A problem is that what $x$ is in the above definition. Based on the idea of de Bruijn's index, we introduce term families due to Berger and Schwichtenberg [BS91] and Filinski [Fil99] to avoid this difficulty.

Definition 2.2.44 (Term family). To a term $M^{\rho}$ we assign a term family $M^{\infty}: \mathbf{N} \rightarrow \Lambda_{\rho}$ by induction on the construction of $M$.

$$
\begin{array}{ll}
x^{\infty}(k):=x, & \left(\lambda_{y} M\right)^{\infty}(k):=\lambda_{x_{k}}\left(M\left[y / x_{k}\right]^{\infty}(k+1)\right), \\
c^{\infty}(k):=c, & (M N)^{\infty}(k):=M^{\infty}(k) N^{\infty}(k),
\end{array}
$$

where $c$ is a constant.
By using term families, we can formalize Definition 2.2 .43 without using a variable name.

For term families $r: \mathbf{N} \rightarrow \Lambda_{\rho \rightarrow \sigma}$ and $s: \mathbf{N} \rightarrow \Lambda_{\rho}$, the application $r s$ is defined by $r s(k):=r(k) s(k)$. The following is the standard way to get a term from a term family.

Definition 2.2.45 (Extraction from a term family). Let $r$ be a term family and $k$ be the greatest index among indices of free and bound variables $x_{i}$ which occur in $r(0)$ We define $\operatorname{ext}(r)$ by the term $r(k+1)$.

Now we can give a refined version of NbE which is suitable for the implementation.
Definition 2.2.46 (Refined interpretation of types). Let $\Lambda_{\rho}$ be the set of all terms of type $\rho$ and $\Lambda_{\rho}^{\mathbf{N}}$ be the function space from natural numbers to $\Lambda_{\rho}$. We define the refined interpretation of types by induction on a type.

$$
\llbracket \iota \rrbracket:=\Lambda_{\iota}^{\mathbf{N}}, \quad \llbracket \rho \rightarrow \sigma \rrbracket:=\llbracket \sigma \rrbracket^{\llbracket \rho \rrbracket},
$$

Definition 2.2.47 (Refined reflect and reify). We simultaneously define two functions $\uparrow_{\rho}:\left(\mathbf{N} \rightarrow \Lambda_{\rho}\right) \rightarrow \llbracket \rho \rrbracket$ and $\downarrow_{\rho}: \llbracket \rho \rrbracket \rightarrow \mathbf{N} \rightarrow \Lambda_{\rho}$.

$$
\begin{array}{ll}
\uparrow_{\iota}(r):=r, & \downarrow_{\iota}(r):=r \\
\uparrow_{\rho \rightarrow \sigma}(r)(a):=\uparrow_{\sigma}\left(r \downarrow_{\rho}(a)\right), & \downarrow_{\rho \rightarrow \sigma}(a)(k):=\lambda_{x_{k}}^{\rho}\left(\downarrow_{\sigma}\left(a\left(\uparrow_{\rho}\left(x_{k}^{\infty}\right)\right)\right)(k+1)\right) .
\end{array}
$$

For $a_{i} \in \llbracket \rho_{i} \rrbracket, \uparrow_{\vec{\rho} \rightarrow \sigma}(r)\left(a_{1}, \ldots, a_{n}\right):=\uparrow_{\sigma}\left(r \downarrow_{\rho_{1}}\left(a_{1}\right) \ldots \downarrow_{\rho_{n}}\left(a_{n}\right)\right)$ holds. The correctness of NbE is shown as follows.

Theorem 2.2.48 (Correctness of NbE). Let $M$ be a term in $\beta \eta$-long normal form. We have $\downarrow\left(\llbracket M \rrbracket_{\uparrow}\right)=M^{\infty}$ where $\llbracket M \rrbracket_{\uparrow}$ denotes the (semantic) object of $M$ under the assignment given by $\uparrow$.

Proof. By induction on the construction of $M$.

We describe the implementation of NbE in Section A.1.1.

### 2.3 Inductive and Coinductive Definitions

Inductive and coinductive definitions are means to define predicates inductively and coinductively, which makes TCF extensible. These definitions provide a way to specify a prime formula, which is sometimes not concretely given, for example in the Brouwer-HeytingKolmogorov interpretation of intuitionistic logic.

We give the notion of formulas and predicates simultaneously.
Definition 2.3.1 (Formula forms and predicate forms). We simultaneously define formula forms $A, B$ and predicate forms $P$. Let $X$ denote a predicate variable with an arity, and the length of $\vec{t}$ be the same as the length of the arity of $P$.

$$
\begin{aligned}
& A, B::=P \vec{t}|A \rightarrow B| \forall_{x} A \\
& P::=X|\{\vec{x} \mid A\}| \mu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \overrightarrow{t_{i}}\right)\right)_{i<k} \mid \nu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \overrightarrow{t_{i}}\right)\right)_{i<k}
\end{aligned}
$$

We abbreviate $A_{0} \rightarrow \ldots \rightarrow A_{n-1} \rightarrow B$ as $\left(A_{i}\right)_{i<n} \rightarrow B$ and $\forall_{x_{0}} \ldots \forall_{x_{n-1}} A$ as $\forall_{\vec{x}} A$.
Definition 2.3.2 (Free predicate variables). We simultaneously define free predicate variables in a formula form and a predicate form.

$$
\begin{aligned}
& \operatorname{FPV}(P \vec{t}):=\operatorname{FPV}(P), \\
& \operatorname{FPV}(A \rightarrow B):=\operatorname{FPV}(A) \cup \operatorname{FPV}(B), \\
& \operatorname{FPV}\left(\forall_{x} A\right):=\operatorname{FPV}(A), \\
& \operatorname{FPV}(X):=\{X\}, \\
& \operatorname{FPV}(\{\vec{x} \mid A\}):=\operatorname{FPV}(A), \\
& \operatorname{FPV}\left(\mu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \overrightarrow{t_{i}}\right)\right)_{i<k}\right):=\bigcup_{i<k} \bigcup_{\nu<n_{i}} \operatorname{FPV}\left(A_{i \nu}\right) \backslash\{X\}, \\
& \operatorname{FPV}\left(\nu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \vec{t}_{i}\right)\right)_{i<k}\right):=\bigcup_{i<k} \bigcup_{\nu<n_{i}} \operatorname{FPV}\left(A_{i \nu}\right) \backslash\{X\} .
\end{aligned}
$$

We can denote $A(X)$ instead of $A$ to express that $A(Y)$ means replacing $X$ in $A$ by $Y$.
Definition 2.3.3 (Strictly positive occurrence of predicate variables). We define $\mathrm{SP}_{\vec{Y}}$ on a formula form and a predicate form.

$$
\begin{aligned}
& \frac{\operatorname{SP}_{\vec{Y}}(P)}{\operatorname{SP}_{\vec{Y}}(P \vec{t})}, \quad \frac{\operatorname{FPV}(A) \cap \vec{Y}=\emptyset \quad \operatorname{SP}_{\vec{Y}}(B)}{\operatorname{SP}_{\vec{Y}}(A \rightarrow B)} \\
& \text { for all } i<k, \text { for all } \nu<n_{i}, \operatorname{SP}_{\vec{Y}, X}\left(A_{i \nu}\right) \\
& \frac{\mathrm{SP}_{\vec{Y}}\left(\mu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \vec{t}_{i}\right)\right)_{i<k}\right)}{},
\end{aligned} \quad \frac{\mathrm{SP}_{\vec{Y}}(A)}{\operatorname{SP}_{\vec{Y}}\left(\forall_{x} A\right)}, \quad \overline{\operatorname{SP}_{\vec{Y}}(X)}, \quad \frac{\operatorname{SP}_{\vec{Y}}(A)}{\operatorname{SP}_{\vec{Y}}(\{\vec{x} \mid A\})},
$$

Occurrences of $\vec{Y}$ in $A(P)$ is strictly positive if $\mathrm{SP}_{\vec{Y}}(A)\left(\mathrm{SP}_{\vec{Y}}(P)\right)$.
Definition 2.3.4 (Inhabited formula forms and predicate forms). Let variables $X$ and $Y$ range over predicate forms. We simultaneously define $\operatorname{Inhab}_{\vec{Y}}$ on a formula form and a
predicate form as follows.

$$
\begin{aligned}
& \frac{\operatorname{Inhab}_{\vec{Y}}(X)}{\operatorname{Inhab}_{\vec{Y}}(X \vec{t})}, \quad \frac{\operatorname{Inhab}_{\vec{Y}}(B)}{\operatorname{Inhab}_{\vec{Y}}(A \rightarrow B)}, \quad \frac{\operatorname{Inhab}_{\vec{Y}}(A)}{\operatorname{Inhab}_{\vec{Y}}\left(\forall_{\vec{x}} A\right)}, \\
& \text { there exists } i<k, \text { for all } \nu<n_{i}, \operatorname{Inhab}_{\vec{Y}, X}\left(A_{i \nu}\right) \\
& \frac{\left.\operatorname{Inhab}_{\vec{Y}}\left(\mu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \vec{t}_{i}\right)\right)_{i<k}\right)\right)}{\operatorname{Inhab}_{\vec{Y}}(X)}, \\
& \text { there exists } i<k, \text { for all } \nu<n_{i}, \operatorname{Inhab}_{\vec{Y}, X}\left(A_{i \nu}\right) \\
& \left.\operatorname{Inhab}_{\vec{Y}}\left(\nu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \vec{t}_{i}\right)\right)_{i<k}\right)\right)
\end{aligned}, \quad \begin{aligned}
& \operatorname{Inhab}_{\vec{Y}}(\{\vec{x} \mid A\})
\end{aligned},
$$

A formula form $A$ is inhabited if $\operatorname{Inhab}(A)$ holds, where the subscript is omitted to mean that the empty list of predicate variables is given. A formula form $A$ is absolutely inhabited if $\operatorname{Inhab}_{\mathrm{FPV}(A)}(A)$.

Definition 2.3.5 (Formulas and predicates). We simultaneously define F and Pred.

$$
\begin{aligned}
& \frac{\operatorname{Pred}(P)}{\mathrm{F}(P \vec{t})}, \frac{\mathrm{F}(A) \mathrm{F}(B)}{\mathrm{F}(A \rightarrow B)}, \quad \frac{\mathrm{F}(A)}{\mathrm{F}\left(\forall_{x} A\right)}, \quad \overline{\operatorname{Pred}(X)}, \quad \frac{\mathrm{F}(A)}{\operatorname{Pred}(\{\vec{x} \mid A\})}, \\
& \frac{\text { for all } i<k, \mathrm{~F}\left(X \vec{t}_{i}\right) \text { and for all } \nu<n_{i}, \mathrm{~F}\left(A_{i \nu}\right) \text { and } \mathrm{SP}_{X}\left(A_{i \nu}\right) \quad \operatorname{Inhab}(I)}{\operatorname{Pred}(I)}, \\
& \frac{\text { for all } i<k, \mathrm{~F}\left(X \overrightarrow{t_{i}}\right) \text { and for all } \nu<n_{i}, \mathrm{~F}\left(A_{i \nu}\right) \text { and } \mathrm{SP}_{X}\left(A_{i \nu}\right) \quad \operatorname{Inhab}\left({ }^{\mathrm{co}} I\right)}{\operatorname{Pred}\left({ }^{\mathrm{co} I} I\right)},
\end{aligned}
$$

where $I:=\mu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \overrightarrow{t_{i}}\right)\right)_{i<k}$ and ${ }^{\text {co } I}:=\nu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \overrightarrow{t_{i}}\right)\right)_{i<k}$. A formula form $A$ is a formula if $\mathrm{F}(A)$, and a predicate form $P$ is a predicate if $\operatorname{Pred}(P)$.

Inductively defined predicate constants, also called inductive predicates in short, extend the system by adding the introduction and the elimination axioms. Similarly in the case of coinductively defined predicate constants, definitions extend the system by adding the closure and the greatest-fixed-point axioms.

### 2.3.1 Inductive Definitions

We give the definition of inductive predicates and its axioms.
Definition 2.3.6 (Inductively defined predicates). Suppose that formulas $K_{i}$ for $i<k$ are of the form $\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \overrightarrow{t_{i}}\right)$, then $I:=\mu_{X}(\vec{K})$ is an inductively defined predicate if $\operatorname{Pred}(I)$. We denote $A_{i \nu}(X)$ to describe the free occurrences of $X$ in $A_{i \nu}$. The introduction axioms are obtained by replacing each occurrence of $X$ in $\vec{K}$ by $I$.

$$
\forall_{\vec{x}}\left(\left(A_{i \nu}(I)\right)_{\nu<n_{i}} \rightarrow I \vec{t}\right)
$$

$$
I_{i}^{+}
$$

We refer to each introduction axiom of $I$ derived from $K_{i}$ by $I_{i}^{+}$, possibly with additional parentheses for the readability. Let $P$ be a predicate variable of the same arity as $I$. The elimination axiom of $I$ is of the following form,

$$
\forall_{\vec{x}}\left(I \vec{x} \rightarrow\left(B_{i}(I, P)\right)_{i<k} \rightarrow P \vec{x}\right), \quad I^{-}
$$

which is referred to by $I^{-}$. Let $I \cap P$ be $\{\vec{x} \mid I \vec{x} \wedge P \vec{x}\}$, then $B_{i}(I, P)$ is given as follows,

$$
\forall_{\vec{x}}\left(\left(A_{i \nu}(I \cap P)\right)_{\nu<n_{i}} \rightarrow P \vec{t}\right),
$$

namely, by replacing the final occurrence of $X$ in $K_{i}$ by $P$ and all other $X$ by $I \cap P$. Conventionally, when an occurrence of $X$ in the premise of the implication in $K_{i}$ is not given as a parameter argument of another predicate constant, we duplicate $I$ and $P$ by currying rather than using conjunction. We call $A_{i \nu}(X)$ a parameter premise if it does not contain $X$, otherwise a recursive premise. Occurrences of $X$ as parameter arguments of a previously defined predicate are called nested, and predicates involving a nested occurrence of $X$ are called nested inductively defined predicates.

Roughly speaking, the elimination axiom $I^{-}$states that if a predicate $P$ can replace $I$ in $I_{i}^{+}$for all $i<k, I$ is smaller than $P$. In our formulation, the strengthening is used in the step formulas, so that $I \cap P$ is assumed in premises instead of $P$. When there is no confusion, we can give a list of introduction axioms instead of $\mu_{X}(\vec{K})$ in order to define an inductive predicate. To make parameter predicates explicit, we write parameters as subscripts, as $I_{\vec{X}}$ where $\vec{X}$ are parameter predicates of $I$. For readability, it can be written by parentheses as well, i.e., $I(\vec{X})$.

We take a look at one example of inductive definition.
Example 2.3.7 (Leibniz equality). We define Leibniz equality by

$$
\operatorname{eqd}^{\rho}:=\mu_{X}\left(\forall_{x^{\rho}} X(x, x)\right),
$$

where $\rho$ is a type parameter. The introduction and elimination axioms are

$$
\begin{array}{ll}
\forall_{x}(\operatorname{eqd}(x, x)), & \text { eqd }^{+} \\
\forall_{x, y}\left(\operatorname{eqd}(x, y) \rightarrow \forall_{x} P x x \rightarrow P x y\right), & \text { eqd }^{-}
\end{array}
$$

where eqd $(x, y)$ abbreviates eqd ${ }^{\rho}\left(x^{\rho}, y^{\rho}\right)$. We adopt the infix notation as $x$ eqd $y$.
Lemma 2.3.8 (Compatibility of eqd). $\forall_{x, y}(x$ eqd $y \rightarrow P x \rightarrow P y)$.
Proof. Let $x$ and $y$ be given and assume $x$ eqd $y$. We use eqd ${ }^{-}$for $x$ eqd $y$ to prove the goal $P x \rightarrow P y$. The step formula $\forall_{x}(P x \rightarrow P x)$ is trivial.

We define truth $\mathbf{T}$ and falsity $\mathbf{F}$ to be $\mathbf{T}$ eqd $\mathbf{T}$ and $\mathbf{F e q d} \mathbf{T}$, respectively. We have ex-falso-quodlibet for a certain class of formulas in minimal logic. The proof deals with the case of coinductively defined predicates which will be described in Section 2.3.2.

Theorem 2.3.9 (Ex-falso-quodlibet). Let $A$ be an absolutely inhabited formula, then there is a proof of $\mathbf{F} \rightarrow A$.

Proof. First, we claim that arbitrary $x^{\rho}$ and $y^{\rho}$ are Leibniz equal if $\mathbf{F}$ is assumed. Let $x^{\rho}$ and $y^{\rho}$ be given, and assume $\mathbf{F}$. Trivially, $\left(\mathcal{R}_{\mathbf{B}}^{\rho} \mathbf{F} x y\right)$ eqd $\left(\mathcal{R}_{\mathbf{B}}^{\rho} \mathbf{T} y x\right)$ comes by eqd ${ }^{+}$. We use 2.3 .8 with F eqd T , then $\left(\mathcal{R}_{\mathbf{B}}^{\rho} \mathbf{\top} x y\right)$ eqd $\left(\mathcal{R}_{\mathbf{B}}^{\rho} \mathbf{\top} y x\right)$, namely, $x$ eqd $y$ also holds.

Let $\vec{X}$ be free predicate variables in $A$. By induction on the construction of $A$. Case $A_{0} \rightarrow A_{1}$. Assume $\mathbf{F}$ and $A_{0}$, then use induction hypothesis for $A_{1}$. Case $\forall_{\vec{x}} A_{0}$. Assume $\mathbf{F}$ and let $\vec{x}$ be given, then use induction hypothesis for $A_{0}$. Case $I \vec{t}$. We have the derivation of $\operatorname{Inhab}_{\vec{X}}(I \vec{t})$, where an index $i$ is determined in the application of the last rule in Definition 2.3.4. Using the claim at the beginning, our goal is same as $I \vec{s}$, so that the $I_{i}^{+}$applies, then all premises of $I_{i}^{+}$come by induction hypothesis. Case ${ }^{\text {co }} I \vec{t}$. We use ${ }^{\text {co }} I^{+}$ with a competitor predicate $P:=\{\vec{x} \mid \mathbf{F}\}$. The first premise is trivial. We prove the second premise $\forall_{\vec{y}}\left(P \vec{y} \rightarrow \bigvee_{i<k} \exists_{\vec{x}_{i}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}\left({ }^{\mathrm{co}} I \cup P\right) \wedge \bigwedge \vec{E}_{i}\right)\right)$. Let $\vec{y}$ be given and assume $P \vec{y}$. We have the derivation of $\operatorname{Inhab}_{\vec{X}}\left({ }^{\text {c}} I \vec{t}\right)$, where an index $i$ is determined in the application of the last rule in Definition 2.3.4. Using $\bigvee^{+}$, it suffices to prove $\exists_{\vec{x}_{i}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}\left({ }^{(\mathrm{co}} I \cup P\right) \wedge \bigwedge \vec{E}_{i}\right)$ which follows from induction hypothesis.

We can define conjunction, disjunction and existential quantifier in our setting, following Martin-Löf ML71.

Example 2.3.10 (Conjunction, disjunction and existential quantifier). Conjunction, disjunction and the existential quantifier are inductively defined as predicates. Let $A$ and $B$ be propositional variables, i.e., predicate variables of arity 0 , and $C$ be a predicate variable of arity $(\alpha)$. We inductively define Conj, Disj and Ex.

$$
\begin{aligned}
& \operatorname{Conj}_{A, B}:=\mu_{X}(A \rightarrow B \rightarrow X), \quad \operatorname{Disj}_{A, B}:=\mu_{X}(A \rightarrow X, B \rightarrow X) \\
& \operatorname{Ex}_{C}:=\mu_{X}\left(\forall_{x^{\alpha}}(C x \rightarrow X)\right) .
\end{aligned}
$$

We can write $A \wedge B, A \vee B$ and $\exists_{x} A$ instead of $\operatorname{Conj}_{\{\mid A\},\{\mid B\}}, \operatorname{Disj}_{\{\mid A\},\{\mid B\}}$ and $\operatorname{Ex}_{\{x \mid A\}}$. The introduction axioms are as follows.

$$
\begin{array}{ll}
A \rightarrow B \rightarrow A \wedge B, & \wedge^{+} \\
A \rightarrow A \vee B, & \vee_{0}^{+} \\
B \rightarrow A \vee B, & \vee_{1}^{+} \\
\forall_{x^{\alpha}}\left(A \rightarrow \exists_{x} A\right), & \exists^{+}
\end{array}
$$

Let $P$ be a propositional variable. The elimination axioms are given as follows.

$$
\begin{array}{ll}
A \wedge B \rightarrow(A \rightarrow B \rightarrow P) \rightarrow P & \wedge^{-} \\
A \vee B \rightarrow(A \rightarrow P) \rightarrow(B \rightarrow P) \rightarrow P, & \vee^{-} \\
\exists_{x} A \rightarrow \forall_{x}(A \rightarrow P) \rightarrow P . & \exists^{-}
\end{array}
$$

Notice that we need e.g. conjunction in the definition of axioms of inductive predicates with a recursive argument, but the definitions of conjunction, disjunction and existential quantifier are recursive arguments free.

Example 2.3.11 (Even numbers). Consider a predicate Even of arity (N). We define Even to be $\mu_{X}\left(K_{0}, K_{1}\right)$ such that

$$
K_{0}=X 0, \quad K_{1}=\forall_{n}(X n \rightarrow X(\mathrm{~S}(\mathrm{~S} n)))
$$

The introduction axioms are

$$
\begin{array}{ll}
\text { Even 0, } & \text { Even }_{0}^{+} \\
\forall_{n}(\text { Even } n \rightarrow \operatorname{Even}(S(S n))) . & \text { Even }_{1}^{+}
\end{array}
$$

Let $P$ be a predicate variable of arity $(\mathbf{N})$, then the elimination axiom is

$$
\forall_{n}\left(\text { Even } n \rightarrow P 0 \rightarrow \forall_{n}(\text { Even } n \rightarrow P n \rightarrow P(\mathrm{~S}(\mathrm{~S} n))) \rightarrow P n\right) . \quad \text { Even }^{-}
$$

Example 2.3.12 (Pointwise equality). Apart from the Leibniz equality, the pointwise equality is inductively definable as well. On $\mathbf{N}$, we define the pointwise equality $=\mathbf{N}$ of arity $(\mathbf{N}, \mathbf{N})$ as follows:

$$
={ }_{\mathbf{N}}:=\mu_{X}\left(X 00, \forall_{n, m}(X n m \rightarrow X(\mathrm{~S} n)(\mathrm{S} m))\right)
$$

The introduction and elimination axioms are

$$
\begin{array}{ll}
0=_{\mathbf{N}} 0, & \left(=\mathbf{N}_{\mathbf{N}}\right)_{0}^{+} \\
\forall_{n, m}\left(n=\mathbf{N}_{\mathbf{N}} m \rightarrow \mathrm{~S} n=_{\mathbf{N}} \mathrm{S} m\right), & \left(=\mathbf{N}_{\mathbf{N}}^{+}\right. \\
\forall_{n, m}\left(n==_{\mathbf{N}} m \rightarrow P 00 \rightarrow \forall_{n, m}\left(n={ }_{\mathbf{N}} m \rightarrow \operatorname{Pnm} \rightarrow P(\mathrm{~S} n, \mathrm{~S} m)\right) \rightarrow P n m\right) . & \left(={ }_{\mathbf{N}}\right)^{-}
\end{array}
$$

For any finitary algebra $\iota$, we can also define the pointwise equality on $\mathbf{L}_{\iota}$ which is relativised by a relation $R_{\iota}$ on $\iota$. We define $=\mathbf{L}_{\iota}$ to be

$$
\mu_{X}\left(X[][], \forall_{x, y}\left(R_{\iota} x y \rightarrow \forall_{x s, y s}(X x s y s \rightarrow X(x:: x s)(y:: y s))\right)\right) .
$$

The introduction and elimination axioms are

$$
\begin{aligned}
& {[]=\mathbf{L}_{\iota}[],} \\
& \left(={ }_{\mathbf{L}_{l}}\right)_{0}^{+} \\
& \forall_{x, y}\left(R_{\iota} x y \rightarrow \forall_{x s, y s}\left(x s=_{\mathbf{L}_{\iota}} y s \rightarrow x:: x s=_{\mathbf{L}_{\iota}} y:: y s\right), \quad\left(==_{\mathbf{L}_{\iota}}\right)_{1}^{+}\right. \\
& \forall_{x s, y s}(x s=\mathbf{L} y s \rightarrow P[][] \rightarrow \\
& \forall_{x, y}\left(R_{\iota} x y \rightarrow \forall_{x s, y s}\left(x s=_{\mathbf{L}} y s \rightarrow P x s y s \rightarrow P(x:: x s, y:: y s)\right)\right) \rightarrow \quad\left(=_{\mathbf{L}_{\iota}}\right)^{-} \\
& \text {Pxsys). }
\end{aligned}
$$

See also Example 2.3.21 for nested definitions.

### 2.3.2 Coinductive Definitions

Coinductively defined predicates come as companion predicates of inductively defined ones. We generalize conjunction and disjunction to formulate coinductive predicates.
Definition 2.3.13 (Generalized conjunction). Assume a list of formulas $\vec{A}$ of length $n \geq 0$. We define generalized conjunction $\bigwedge \vec{A}$ by induction on the length of $\vec{A}$.

$$
\bigwedge():=\mathbf{T}, \quad \bigwedge(A):=A, \quad \bigwedge(A, \vec{A}):=A \wedge \bigwedge \vec{A}
$$

Let $n$ be the length of $\vec{A}$. We define $\bigwedge_{i<n} A_{i}$ to be $\bigwedge \vec{A}$.
Instead of repeated application of $\wedge^{+}$, we can call it $\Lambda^{+}$. In the same way, instead of repeated application of $\wedge^{-}$, we can say $\wedge^{-}$.
Definition 2.3.14 (Generalized disjunction). Assume propositions $\vec{A}$ of length $n \geq 0$. We define disjunction $\bigvee \vec{A}$ by induction on the length of $\vec{A}$.

$$
\begin{aligned}
& \bigvee():=\mathbf{F}, \quad \bigvee(A):=I_{A}, \quad \bigvee(A, \vec{A}):=\tilde{\bigvee}(A, \vec{A}) \\
& \tilde{\bigvee}(A):=A, \quad \tilde{\bigvee}(A, \vec{A}):=A \vee \tilde{\bigvee}(\vec{A}),
\end{aligned}
$$

where $I_{Y}:=\mu_{X}(Y \rightarrow X)$. We define $\bigvee_{i<n} \vec{A}$ to be $\bigvee \vec{A}$.
There is a special treatment for the case of a singleton list. This is a way to manage the typing issue of a closure axiom of a one-clause coinductive definition without computational assumptions, for example the cototality predicate of $\mathbf{U}$, in Section 2.5.1. For $n, n^{\prime}$ such that $n \leq n^{\prime} \leq \nu$, we also allow to write $\bigvee_{i ; n \leq i<n^{\prime}}\left(A_{i}\right)_{i<\nu}$ to mean $\bigvee\left(A_{i+n}\right)_{i<\nu-n^{\prime}}$, which is a sublist of $\left(A_{i}\right)_{i<\nu}$ defined to be

$$
\left(A_{i+n}\right)_{i<0}:=(), \quad\left(A_{i+n}\right)_{i<m+1}:=\left(A_{n},\left(A_{i+n+1}\right)_{i<m}\right) .
$$

Instead of repeating $\mathrm{V}_{0}^{+}$and $\mathrm{V}_{1}^{+}$, we can say $\mathrm{V}^{+}$if there is no confusion. In the same way, instead of repeated application of $\mathrm{V}^{-}$, we can say $\mathrm{V}^{-}$. We abbreviate $\bigwedge_{i<n} A_{i}$ and $\bigvee_{i<n} A_{i}$ as $\bigwedge_{i} A_{i}$ and $\bigvee_{i} A_{i}$, respectively, when the length of $\vec{A}$ is not essential or there is no confusion.

Definition 2.3.15 (Coinductively defined predicates). Suppose that for each $i<k$ a formula $K_{i}$ of the form $\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}(X)\right)_{\nu<n_{i}} \rightarrow X \vec{t}_{i}\right)$ is given. Then, ${ }^{\text {co }} I:=\nu_{X}(\vec{K})$ is a coinductively defined predicate if $\operatorname{Pred}\left({ }^{\mathrm{co}} I\right)$. The closure axiom ${ }^{\mathrm{co}} I^{-}$is given as follows. Assume fresh variables $\vec{y}$ with the same length and types of $\overrightarrow{t_{i}}$ and define formulas $E_{j}:=$ $y_{j}$ eqd $t_{j}$ for $0 \leq j<|\vec{t}|$. Then ${ }^{\text {co }} I^{-}$is defined to be

$$
\forall_{\bar{y}}\left({ }^{\mathrm{Co}} I \vec{y} \rightarrow \bigvee_{i<k} \exists_{\vec{x}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}\left({ }^{\mathrm{Co}} I\right) \wedge \wedge \vec{E}_{i}\right)\right)
$$

${ }^{\text {co }}{ }^{-}$
Assume a predicate variable $P$ of the same arity as ${ }^{\text {co }} I$. The greatest-fixed-point axiom ${ }^{\text {co }} I^{+}$ is defined to be

$$
\forall_{\vec{y}}\left(P \vec{y} \rightarrow \forall_{\vec{y}}\left(P \vec{y} \rightarrow \bigvee_{i<k} \exists_{\vec{x}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}\left({ }^{\mathrm{c} \circ} I \cup P\right) \wedge \bigwedge \vec{E}_{i}\right)\right) \rightarrow{ }^{\mathrm{co}} I \vec{y}\right) . \quad{ }^{\mathrm{co}} I^{+}
$$

where ${ }^{\text {co }} I \cup P$ is $\left\{\vec{z} \mid{ }^{\text {co }} I \vec{z} \vee P \vec{z}\right\}$. We call the second premise the costep formula.

Roughly speaking, the greatest fixed point axiom ${ }^{{ }^{\text {co }} I^{+}}$states that ${ }^{\mathrm{co}} I$ is greater than an arbitrary predicate $P$ if $P$ can replace ${ }^{\mathrm{co}} I$ in ${ }^{\mathrm{co}} I^{-}$. In our formulation, the strengthening is used in the costep formula, so that ${ }^{\text {co }} I \cup P$ comes in the conclusion of a costep formula instead of $P$.

Example 2.3.16 (Coeven numbers). We define ${ }^{\text {co }}$ Even, the companion predicate of Even, as well. The closure axiom is

$$
\forall_{n}\left({ }^{(\mathrm{co}} \text { Even } n \rightarrow n \text { eqd } 0 \vee \exists_{m}\left({ }^{\text {co }} \text { Even } m \wedge n \text { eqd } S(\mathrm{~S} m)\right)\right), \quad{ }^{\text {co }} \text { Even }^{-}
$$

and the greatest-fixed-point axiom is

$$
\forall_{n}\left(P n \rightarrow \forall_{n}\left(P n \rightarrow n \text { eqd } 0 \vee \exists_{m}\left(\left({ }^{\text {co }} \text { Even } m \vee P m\right) \wedge n \text { eqd } S(S m)\right)\right) \rightarrow{ }^{\text {co }} \operatorname{Even} n\right)
$$

Example 2.3.17 (Bisimilarity). We consider a companion predicate of $=_{\mathbf{L}_{\iota}}$, written $\approx$ instead of ${ }^{\mathrm{co}}=\mathbf{L}_{\iota}$. Let $R$ be a relation on $\iota$, then $\approx$ is defined by

$$
\begin{aligned}
& \forall_{x s, y s}(x s \approx y s \rightarrow(x s \text { eqd }[] \wedge y s \text { eqd }[]) \vee \\
& \left.\exists_{x^{\prime}, y^{\prime}, x s^{\prime}, y s^{\prime}}^{\mathrm{r}}\left(R x^{\prime} y^{\prime} \wedge x s^{\prime} \approx y s^{\prime} \wedge x s \text { eqd } x^{\prime}:: x s^{\prime} \wedge y s \text { eqd } y^{\prime}:: y s^{\prime}\right)\right) \\
& \forall_{x s, y s}(P x s y s \rightarrow \\
& \forall_{x s, y s}(P \text { xs } y s \rightarrow(x s \text { eqd }[] \wedge y s \text { eqd }[]) \vee \\
& \exists_{x^{\prime}, y^{\prime}, x s^{\prime}, y s^{\prime}}^{\mathrm{r}}\left(R x^{\prime} y^{\prime} \wedge\left(x s^{\prime} \approx y s^{\prime} \vee P x s^{\prime} y s^{\prime}\right) \wedge \quad \approx^{+}\right. \\
& \left.\left.x s \text { eqd } x^{\prime}:: x s^{\prime} \wedge y s \text { eqd } y^{\prime}:: y s^{\prime}\right)\right) \rightarrow \\
& x s \approx y s)
\end{aligned}
$$

We call it the bisimilarity relation relativised by $R$.
Example 2.3.18 (Bisimilarity between infinite lists). As a concrete example of the use of greatest-fixed-point axioms, we prove the bisimilarity of two differently defined infinite lists of even numbers. Here we use $\approx$ relativised by eqd on natural numbers. Define the following two terms.

$$
\begin{aligned}
l_{0} & ={ }^{\mathrm{co}} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}} 0 M_{0}, \text { where } M_{0}:=\lambda_{n} \ln \mathrm{R}\langle n, \ln \mathrm{R}(n+2)\rangle, \\
l_{1} & ={ }^{\mathrm{co}} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathrm{N}} 0 M_{1}, \text { where } M_{1}:=\lambda_{n} \ln \mathrm{R}\langle 2 n, \ln \mathrm{R}(n+1)\rangle .
\end{aligned}
$$

Both of them unfold into a list $0:: 2:: 4:: \ldots$ We prove the bisimilarity of them, i.e., $l_{0} \approx l_{1}$, by means of $\approx^{+}$with the competitor predicate

$$
Q:=\left\{s, t \mid \exists_{n}\left(s \operatorname{eqd}^{\mathrm{co}} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}} 2 n M_{0} \wedge t \mathrm{eqd}^{\mathrm{co}} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}} n M_{1}\right)\right\} .
$$

It suffices to prove $Q l_{0} l_{1}$ and the costep formula. For the latter, let $l_{0}^{\prime}$ and $l_{1}^{\prime}$ be given and assume $Q l_{0}^{\prime} l_{1}^{\prime}$, namely, there is $n^{\prime}$ such that $l_{0}^{\prime}$ eqd ${ }^{\text {co }} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}} 2 n^{\prime} M_{0}$ and $l_{1}^{\prime}$ eqd ${ }^{\text {co }} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}} n^{\prime} M_{1}$. We prove the right disjunct of the costep formula. By unfolding, $l_{0}^{\prime}=2 n^{\prime}::{ }^{\text {co }} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}}\left(2 n^{\prime}+2\right) M_{0}$ and $l_{1}^{\prime}=2 n^{\prime}::{ }^{\text {co }} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}}\left(n^{\prime}+1\right) M_{1}$. Since $2 n^{\prime}+2$ eqd $2\left(n^{\prime}+1\right), Q\left({ }^{\mathrm{co}} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}}\left(2 n^{\prime}+2\right) M_{0},{ }^{\mathrm{c}} \mathcal{R}_{\mathbf{L}_{\mathbf{N}}}^{\mathbf{N}}\left(n^{\prime}+1\right) M_{1}\right)$ holds.

### 2.3.3 Totality and Cototality

We have taken a look at totality and cototality of finitary algebras in Section 2.1. We state them in general for an arbitrary type by inductive and coinductive definitions. We define the totality predicate and the cototality predicate of an arbitrary type.

Definition 2.3.19 (Totality and cototality predicates). Assume $\tau$ is a type and $\theta$ is a mapping from each free variable $\alpha$ in $\tau$ into a predicate variable of arity $(\alpha)$. We define a translation tl from a type $\tau$ into totality and cototality predicates of $\tau$.

$$
\begin{aligned}
& \mathrm{tl}_{\theta}(\alpha):=\theta(\alpha) \quad \text { if } \alpha \text { is a variable, } \\
& \mathrm{tl}_{\theta}(\sigma \rightarrow \tau):=\left\{y^{\sigma \rightarrow \tau} \mid \forall_{z^{\sigma}}\left(\operatorname{tl}_{\theta}(\sigma)(z) \rightarrow \operatorname{tl}_{\theta}(\tau)(y z)\right)\right\} \quad y \text { and } z \text { are fresh, } \\
& \operatorname{tl}_{\theta}\left(\mu_{\xi}\left(\left(\rho_{i \nu}\right)_{\nu<n_{i}} \rightarrow \xi\right)_{i<k}\right):=\hat{\mu}_{X}\left(\forall_{\vec{x}_{i}}\left(\left(\operatorname{tl}_{\theta, \xi \mapsto X}\left(\rho_{i \nu}\right)\left(x_{i \nu}\right)\right)_{\nu<n_{i}} \rightarrow X\left(C_{i} \vec{x}_{i}\right)\right)\right)_{i<k},
\end{aligned}
$$

where $\hat{\mu}$ is an intermediate symbol which is instantiated by $\mu$ or $\nu$. An inductive predicate defined by tl from $\tau$ is called the totality predicate of $\tau$, written $T_{\tau}$, and a coinductive predicate is called the cototality predicate of $\tau$, written ${ }^{\text {co }} T_{\tau}$. When a (co)totality predicate of type $\tau$ has parameter predicate variables $\vec{P}$ associated with free variables in $\tau$, we can explicitly call it a relativised (co)totality predicate, written $R T_{\tau}\left({ }^{\mathrm{co}} R T_{\tau}\right)$.

If there are $n$ occurrences of $\mu$ in the definition of a type $\tau$, there are $2^{n}$ variations of combinations of inductive definitions and coinductive definitions due to the way of instantiating $\hat{\mu}$ in $\operatorname{tl}_{\theta}(\tau)$. For a nested algebra $\iota$ depending on another algebra $\iota^{\prime}$, we can say the $\iota$-(co)totality $\iota^{\prime}$-(co)totality predicate, if there is no confusion. For example, the cototality predicate of $\mathbf{N t}$ which internally uses the totality predicate of $\mathbf{L}_{\alpha}$ can be called the $\mathbf{N t}$-cototality $\mathbf{L}_{\mathbf{N t}}$-totality predicate.

For an algebra $\iota_{\vec{\alpha}}$, we define the structure-totality and the structure-cototality predicates $S T_{\iota_{\vec{\alpha}}}$ and ${ }^{\operatorname{co}} S T_{\iota_{\vec{\alpha}}}$.

Definition 2.3.20 (Structure-totality and -cototality predicates). Assume $\tau$ is a type and $\theta$ is a mapping from each free variable $\alpha$ in $\tau$ into a comprehension term $\left\{x^{\alpha} \mid \mathbf{T}\right\}$. We define the structure-totality and cototality predicates, $S T_{\tau}$ and ${ }^{\text {co }} S T_{\tau}$, of $\tau$ by instantiating $\hat{\mu}$ in $\mathrm{tl}_{\theta}(\tau)$ by $\mu$ and $\nu$, respectively, and identifying formulas $\mathbf{T} \rightarrow A$ and $A$.

Example 2.3.21 (Totality and cototality predicates on $\mathbf{N}$ and $\mathbf{N t}$ ). We obtain from $\operatorname{tl}(\mathbf{N})$ the totality and cototality predicates $T_{\mathbf{N}}=\mu_{X}\left(X 0, \forall_{n}(X n \rightarrow X(\mathrm{~S} n))\right)$ and ${ }^{\mathrm{co}} T_{\mathbf{N}}=$ $\nu_{X}\left(X 0, \forall_{n}(X n \rightarrow X(\mathrm{~S} n))\right)$. We obtain from $\mathrm{tl}(\mathbf{N t})$ the four variations of totality and cototality predicates, the $\mathbf{N t}$-total $\mathbf{L}_{\mathbf{N t}}$-total predicate, the $\mathbf{N t}$-cototal $\mathbf{L}_{\mathbf{N t}}$-total predicate, the $\mathbf{N t}$-total $\mathbf{L}_{\mathbf{N t}}$-cototal predicate and the $\mathbf{N t}$-cototal $\mathbf{L}_{\mathbf{N t}}$-cototal predicate.

Let $R T_{X}$ be the relativised totality predicate on $\mathbf{L}_{\alpha}$. The introduction and elimination axioms of the $\mathbf{N t}$-total $\mathbf{L}_{\mathbf{N t}}$-total predicate $T_{\mathbf{N t}}$ are

$$
\begin{array}{ll}
\forall_{a s}\left(R T_{T_{\mathbf{N t}}} \text { as } \rightarrow T_{\mathbf{N t}}(\mathrm{Br} a s)\right), & T_{\mathbf{N t}}^{+} \\
\forall_{a}\left(T_{\mathbf{N t}} a \rightarrow \forall_{a s}\left(R T_{T_{\mathbf{N t} \cap Q}} \text { as } \rightarrow Q(\mathrm{Br} a s)\right) \rightarrow Q a\right) . & T_{\mathbf{N t}}^{-}
\end{array}
$$

The clause and greatest-fixed-point axioms of the $\mathbf{N t}$-cototal $\mathbf{L}_{\mathbf{N t}}$-total predicate ${ }^{\text {co }} T_{\mathbf{N t}}$ are

$$
\begin{array}{ll}
\forall_{a}\left({ }^{\mathrm{co}} T a \rightarrow \exists_{a s}\left(T_{\mathrm{co}^{\circ} T} \text { as } \wedge a \text { eqd } \operatorname{Br} a s\right)\right) & { }^{\mathrm{co}} T_{\mathrm{Nt}}^{-} \\
\forall_{a}\left(Q a \rightarrow \forall_{a}\left(Q a \rightarrow \exists_{a s}\left(T_{\left({ }^{\mathrm{co}} T \cup Q\right)} \text { as } \wedge a \text { eqd } \mathrm{Br} a s\right)\right) \rightarrow{ }^{\mathrm{co}} T a\right) . & { }^{\mathrm{co}} T_{\mathrm{Nt}}^{+}
\end{array}
$$

Example 2.3.22 (Structure-totality and cototality predicates of $\mathbf{L}_{\alpha}$ ). Let $\alpha$ be a type variable and $\theta$ be a mapping $\left(\alpha \mapsto\left\{x^{\alpha} \mid \mathbf{T}\right\}\right)$. From $\operatorname{tl}_{\theta}\left(\mathbf{L}_{\alpha}\right)$ we obtain $\hat{\mu}_{X}\left(X[], \forall_{x, \alpha s}(\mathbf{T} \rightarrow\right.$ $X x s \rightarrow X(x:: x s)))$ which yields $S T_{\mathbf{L}}=\mu_{X}\left(X[], \forall_{x, x s}(X x s \rightarrow X(x:: x s))\right)$ and ${ }^{\operatorname{co}} S T_{\mathbf{L}}=$ $\nu_{X}\left(X[], \forall_{x, x s}(X x s \rightarrow X(x:: x s))\right)$.

### 2.3.4 Monotonicity

Suppose that the occurrences of predicate variables $\vec{X}$ in a formula $A(\vec{X})$ are strictly positive, i.e., $\mathrm{F}(A(\vec{X}))$ and $\mathrm{SP}_{\vec{X}}(A(\vec{X}))$, then $A(\vec{X})$ satisfies the monotonicity property; $A(\vec{P})$ implies $A(\vec{Q})$ provided $\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)$ for each $i$. This lemma plays an important role in proof normalization involving nestedness. In Section 2.5.3, we prove that the map operator is a realizer of the monotonicity lemma.
Lemma 2.3.23 (Monotonicity). Let $A(\vec{X})$ be a formula, $n$ be the length of $\vec{X}$, and $\vec{P}, \vec{Q}$ be a list of predicates of length $n$. Assume $S P_{\vec{X}}(A(\vec{X}))$, then $A(\vec{X})$ satisfies the monotonicity property, namely, $\forall_{\vec{x}}\left(A(\vec{P}) \rightarrow\left(\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)\right)_{i<n} \rightarrow A(\vec{Q})\right)$.
Proof. By simultaneous induction on the construction of $A$.
Case $A(\vec{X})=\forall_{\tilde{x}} \tilde{A}(\vec{X})$. We prove $\forall_{\vec{x}}\left(\forall_{\tilde{x}} \tilde{A}(\vec{P}) \rightarrow\left(\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)\right)_{i<n} \rightarrow \forall_{\tilde{x}} \tilde{A}(\vec{Q})\right)$. Let $\vec{x}$ be given and assume $\forall_{\tilde{x}} \tilde{A}(\vec{P}), \forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)$ for each $i<n$, and also let $\tilde{x}$ be given. By induction hypothesis, it suffices to prove $\tilde{A}(\vec{P})$, which comes from the assumption $\forall_{\tilde{x}} \tilde{A}(\vec{P})$.

Case $A(\vec{X})=B \rightarrow \tilde{A}(\vec{X}) . \operatorname{FPV}(B) \cap \vec{X}=\emptyset$. Assume $B \rightarrow \tilde{A}(\vec{P}), \forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)$ for each $i<n$ and $B$, then we prove $\tilde{A}(\vec{Q})$. Using the induction hypothesis, it suffices to prove $\tilde{A}(\vec{P})$, which comes from the assumption $B \rightarrow \tilde{A}(\vec{P})$ and $B$.

Case $A(\vec{X})=\tilde{P} \vec{t}$. We proceed by side induction on the construction of $\operatorname{Pred}(\tilde{P})$.
Side case $\tilde{P}=Z$. If $Z=X_{j}$ for some $j$, then the goal is

$$
\forall_{\vec{x}}\left(P_{j} \vec{t} \rightarrow\left(\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)\right)_{i<n} \rightarrow Q_{j} \vec{t}\right)
$$

Use $\forall_{\vec{x}}\left(P_{j} \vec{x} \rightarrow Q_{j} \vec{x}\right)$ in the premise. Otherwise, the goal is of the form $\forall_{\vec{x}}\left(Z \vec{t} \rightarrow\left(\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow\right.\right.\right.$ $\left.\left.\left.Q_{i} \vec{x}\right)\right)_{i<n} \rightarrow Z \vec{t}\right)$, which is trivial.

Side case $\tilde{P}=\{\vec{x} \mid \tilde{A}(\vec{x})\}$. The induction hypothesis is exactly the conclusion we desire.
Side case $\tilde{P}=I(\vec{R}(\vec{X}))$ where $I$ is an inductive predicate $\mu_{Z}(\vec{K})$ and $\vec{R}$ is a list of predicates. Let $n^{\prime}$ be the length of $\vec{R}$. We prove

$$
\forall_{\vec{x}}\left(I(\vec{R}(\vec{P})) \vec{t} \rightarrow\left(\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)\right)_{i<n} \rightarrow I(\vec{R}(\vec{Q})) \vec{t}\right)
$$

If $n^{\prime}=0$, it is trivial. Otherwise, let $\vec{x}$ be given and assume $I(\vec{R}(\vec{P})) \vec{t}$, say $I_{\vec{R}(\vec{P})} \vec{t}$ in short, and $\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)$ for each $i<n$. We prove the goal $I_{\vec{R}(\vec{Q})} \vec{t}$ by using $I^{-}$for $I_{\vec{R}(\vec{P})} \vec{t}$.

Suppose that the clause formulas of $I_{\vec{X}}$ are $K_{i}=\forall_{\vec{x}}\left(\left(A_{i \nu}(\vec{X}, Z)\right)_{\nu<n_{i}} \rightarrow Z \vec{t}\right)$, then the step formulas are $\forall_{\vec{x}}\left(\left(A_{i \nu}\left(\vec{R}(\vec{P}), I_{\vec{R}(\vec{P})} \cap I_{\vec{R}(\vec{Q})}\right)\right)_{\nu<n_{i}} \rightarrow I_{\vec{R}(\vec{Q})} \vec{t}\right)$ for each $i<k$. Let $\vec{x}$ be given and assume $\left(A_{i \nu}\left(\vec{R}(\vec{P}), I_{\vec{R}(\vec{P})} \cap I_{\vec{R}(\vec{Q})}\right)\right)_{\nu<n_{i}}$. Using $I_{i}^{+}$to prove $I_{\vec{R}(\vec{Q})} \vec{t}$, it remains to prove $A_{i \nu}\left(\vec{R}(\vec{Q}), I_{\vec{R}(\vec{Q})}\right)$ for $\nu<n_{i}$. We use induction hypothesis for $\mathrm{F}\left(A_{i \nu}(\vec{X}, Z)\right)$,

$$
\begin{aligned}
& \forall_{\vec{x}}\left(A_{i \nu}\left(\vec{R}(\vec{P}), I_{\vec{R}(\vec{P})} \cap I_{\vec{R}(\vec{Q})}\right) \rightarrow\left(\forall_{\vec{x}}\left(R_{i}(\vec{P}) \vec{x} \rightarrow R_{i}(\vec{Q}) \vec{x}\right)\right)_{i<n^{\prime}} \rightarrow\right. \\
& \left.\quad \forall_{\vec{x}}\left(\left(I_{\vec{R}(\vec{P})} \cap I_{\vec{R}(\vec{Q})}\right) \vec{x} \rightarrow I_{\vec{R}(\vec{Q})} \vec{x}\right) \rightarrow A_{i \nu}\left(\vec{R}(\vec{Q}), I_{\vec{R}(\vec{Q})}\right)\right) .
\end{aligned}
$$

We already have the first premise. The second ones are by side induction hypotheses on $\operatorname{Pred}\left(R_{i}(\vec{X})\right)$. The third one is trivial from the definition of conjunction.

Side case $\tilde{P}={ }^{\text {co }} I(\vec{R}(\vec{X}))$ where ${ }^{\text {co }} I(\vec{Y})$ is a coinductive predicate $\nu_{Z}(\vec{K})$ and $\vec{R}(\vec{X})$ is a list of predicates. We prove

$$
\forall_{\vec{x}}\left({ }^{\mathrm{co}} I(\vec{R}(\vec{P})) \vec{t} \rightarrow\left(\forall_{\vec{x}}\left(P_{j} \vec{x} \rightarrow Q_{j} \vec{x}\right)\right)_{j<n} \rightarrow{ }^{\mathrm{co}} I(\vec{R}(\vec{Q})) \vec{t}\right)
$$

Suppose that the length of $\vec{R}$ is non-zero. Let $\vec{x}$ be given and assume ${ }^{\text {co }} I_{\vec{R}(\vec{P})} \vec{t}$, and $\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow\right.$ $Q_{i} \vec{x}$ ) for each $i<n$. We prove the goal ${ }^{\text {co }} I_{\vec{R}(\vec{Q})} \vec{t}$ by using ${ }^{\text {co } I^{+}}$with the competitor predicate ${ }^{\text {co }} I_{\vec{R}(\vec{P})}$. Suppose the same $\vec{K}$ as in the same way as the previous side case, then the costep formula is $\forall_{\vec{x}}\left({ }^{\mathrm{co}} I_{\vec{R}(\vec{P})} \vec{x} \rightarrow \bigvee_{i<k} \exists_{\vec{y}}\left(\bigwedge_{\vec{E}_{i}} \wedge \bigwedge_{\nu<n_{i}} A_{i \nu}\left(\vec{R}(\vec{Q}),{ }^{\mathrm{co}} I_{\vec{R}(\vec{Q})} \cup{ }^{\mathrm{co}} I_{\vec{R}(\vec{P})}\right)\right)\right.$. Let $\vec{x}$ be given and assume ${ }^{\mathrm{co}} I_{\vec{R}(\vec{P})} \vec{x}$. Applying ${ }^{\mathrm{co}} I^{-}$to ${ }^{\mathrm{co}} I_{\vec{R}(\vec{P})} \vec{x}$, then $\bigvee_{i<k} \exists_{\vec{y}}\left(\bigwedge \vec{E}_{i} \wedge \bigwedge_{\nu<n_{i}} A_{i \nu}\left(\vec{R}(\vec{P}),{ }^{\mathrm{co}} I_{\vec{R}(\vec{P})}\right)\right)$ holds, and use $\vee^{-}$for this disjunction. For the case of $i$-th disjunct, assume $\exists_{\vec{y}}\left(\bigwedge \vec{E}_{i} \wedge\right.$ $\bigwedge_{\nu<n_{i}} A_{i \nu}\left(\vec{R}(\vec{P}),{ }^{c} I_{\vec{R}(\vec{P})}\right)$. By means of $\vee_{0}^{+}, \vee_{1}^{+}, \exists^{-}, \exists^{+}, \Lambda^{-}$and $\Lambda^{+}$, we end up with proving $A_{i \nu}\left(\vec{R}(\vec{Q}),{ }^{\mathrm{c}} I_{\vec{R}(\vec{Q})} \cup{ }^{\mathrm{co}} I_{\vec{R}(\vec{P})}\right)$ from $A_{i \nu}\left(\vec{R}(\vec{P}),{ }^{\mathrm{c}} I_{\vec{R}(\vec{P})}\right)$. By the induction hypothesis for $\mathrm{F}\left(A_{i \nu}(\vec{X}, Z)\right)$,

$$
\begin{aligned}
& \forall_{\vec{x}}\left(A_{i \nu}\left(\vec{R}(\vec{P}),{ }^{\mathrm{c}} I_{\vec{R}(\vec{P})}\right) \rightarrow\left(\forall_{\vec{x}}\left(R_{i}(\vec{P}) \vec{x} \rightarrow R_{i}(\vec{Q}) \vec{x}\right)\right)_{i<m} \rightarrow\right. \\
& \left.\quad \forall_{\vec{x}}\left({ }^{\mathrm{c} \circ} I_{\vec{R}(\vec{P})} \vec{x} \rightarrow\left({ }^{\mathrm{c}} I_{\vec{R}(\vec{Q})} \cup{ }^{\mathrm{co}} I_{\vec{R}(\vec{P})}\right) \vec{x}\right) \rightarrow A_{i \nu}\left(\vec{R}(\vec{Q}),{ }^{\mathrm{c}} I_{\vec{R}(\vec{Q})} \cup{ }^{\mathrm{co}} I_{\vec{R}(\vec{P})}\right)\right) .
\end{aligned}
$$

The first premise is in the assumption and the second and the third ones are from the side induction hypothesis as in the previous side case.

### 2.3.5 Simultaneous Definitions

We consider a generalization of predicate definitions to adopt simultaneously defined predicates. We modify Definition 2.3.5, in the following way.

Definition 2.3.24 (Formulas and predicates with simultaneity). Let $\vec{X}$ be a list of predicate variables of length $l$ and $j$ be a monotone surjective function from $\{0, \ldots, k-1\}$ to $\{0, \ldots, l-1\}$. We define predicate forms $P$ by

$$
P::=X|\{\vec{x} \mid A\}| \mu_{\vec{X}}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X_{j_{i}} \vec{t}_{i}\right)\right)_{i<k} \mid \nu_{\vec{X}}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X_{j_{i}} \vec{t}_{i}\right)\right)_{i<k} .
$$

Let $J$ be $\left.\mu_{\vec{X}}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X_{j_{i}} \vec{t}_{i}\right)\right)_{i<k}\right)$ or $\left.\nu_{\vec{X}}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X_{j_{i}} \vec{t}_{i}\right)\right)_{i<k}\right)$. The definition of free predicate variables FPV is defined also for the above predicate forms.

$$
\operatorname{FPV}(J):=\bigcup_{i<k} \bigcup_{\nu<n_{i}} \operatorname{FPV}\left(A_{i \nu}\right) \backslash\{\vec{X}\}
$$

The strictly positive occurrences of predicate variables are modified in the following way.

$$
\frac{\text { for all } i<k \text {, for all } \nu<n_{i}, \mathrm{SP}_{\vec{Y}, \vec{X}}\left(A_{i \nu}\right)}{\operatorname{SP}_{\vec{Y}}(J)} .
$$

The inhabited predicate forms are modified as follows. Here we mean the $m$-th tail of $\vec{X}$ by $\vec{X}^{(m)}$.
$\underline{\text { for all } m<l \text {, there exists } i, j_{i}=m \text { and for all } \nu<n_{i}, \operatorname{Inhab}_{\vec{Y}, \vec{X}(m)}\left(A_{i \nu}\right)}$

$$
\operatorname{Inhab}_{\vec{Y}}(J)
$$

The predicates are defined as follows.

$$
\text { for all } i<k, \nu<n_{i}, \mathrm{~F}\left(A_{i \nu}\right) \text { and } \mathrm{SP}_{X}\left(A_{i \nu}\right) \quad \operatorname{Inhab}(J)
$$

The introduction and elimination axioms are given in a similar way as the nonsimultaneous case.

Definition 2.3.25 (Introduction and elimination axioms of simultaneous inductive definitions). Let $\vec{X}$ be a list of predicate variables of length $l$ and $\vec{I}$ be a list of simultaneously inductively defined predicates $\left.\mu_{\vec{X}}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}(\vec{X})\right)_{\nu<n_{i}} \rightarrow X_{j_{i}} \vec{t}_{i}\right)\right)_{i<k}\right)$. The introduction axioms of $\vec{I}$ are given as follows.

$$
\begin{equation*}
\left.\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}(\vec{I})\right)_{\nu<n_{i}} \rightarrow I_{j_{i}} \vec{t}_{i}\right)\right) \tag{I}
\end{equation*}
$$

Let $\vec{Q}$ be a list of predicate variables of length $l$ such that the arity of $Q_{m}$ is same as the one of $I_{m}$ for each $m<l$, and $\vec{P}$ be a list of predicates of the form $I_{m} \cap Q_{m}$. For each $m<l$ we define the elimination axioms $I_{m}^{-}$as follows.

$$
\forall_{\vec{x}}\left(I_{m} \vec{x} \rightarrow\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}(\vec{P})\right)_{\nu<n_{i}} \rightarrow Q_{j_{i}} \vec{t}_{i}\right)\right)_{i<k} \rightarrow Q_{m} \vec{x}\right) . \quad(\vec{I})_{m}^{-}
$$

Definition 2.3.26 (Closure and greatest-fixed-point axioms of simultaneous coinductive definitions). Let $\vec{X}$ be a list of predicate variables of length $l$ and $\mathrm{co} I$ be a list of simultaneously coinductively defined predicates $\left.\nu_{\vec{X}}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}(\vec{X})\right)_{\nu<n_{i}} \rightarrow X_{j_{i}} \vec{t}_{i}\right)\right)_{i<k}\right)$. Assume variables $\vec{y}_{i}$ for each of $\overrightarrow{t_{i}}$ to form an equality $E_{i i^{\prime}}:=y_{i i^{\prime}}$ eqd $t_{i i^{\prime}}$. For each $m<l$ we find $i_{m}$ and $i_{m}^{\prime}$ such that $i_{m} \leq i<i_{m}^{\prime}$ implies $j_{i}=m$. For each $m<l$ we define the closure axioms $\left({ }^{\mathrm{c} O} I\right)_{m}^{-}$as follows.

$$
\begin{equation*}
\forall_{\vec{y}}\left({ }^{\mathrm{co}} I_{m} \vec{y} \rightarrow \bigvee_{i ; i_{m} \leq i<i_{m}^{\prime}} \exists_{\vec{x}_{i}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}(\mathrm{co} I) \wedge \bigwedge \vec{E}_{i}\right)\right) \tag{}
\end{equation*}
$$

### 2.3. Inductive and Coinductive Definitions

Let $\vec{Q}$ be a list of predicate variables of length $l$ such that the arity of $Q_{m}$ is same as the one of $I_{m}$ for each $m<l$, and $\vec{P}$ be a list of predicates of the form ${ }^{\text {co }} I_{m} \cup Q_{m}$. For each $m<l$ we define the greatest-fixed-point axioms $(\mathrm{co} I)_{m}^{+}$as follows.

$$
\forall_{\vec{x}}\left(Q_{m} \vec{x} \rightarrow\left(\forall_{\vec{y}}\left({ }^{\mathrm{Co}} I_{m} \vec{y} \rightarrow \bigvee_{i ; i_{m} \leq i<i_{m}^{\prime}} \exists_{\vec{x}_{i}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}(\vec{P}) \wedge \bigwedge \vec{E}_{i}\right)\right)\right)_{m<l} \rightarrow{ }^{\mathrm{co}} I_{m} \vec{x}\right) . \quad\left({ }^{\mathrm{co}}\right)_{m}^{+}
$$

Consider the algebras ( $\mathbf{T s}, \mathbf{T}$ ) of tree lists and trees defined in Example 2.1.18. We define the totality predicates and the cototality predicates of them for example.

Example 2.3.27. Consider the simultaneously defined algebras of tree lists and trees ( $\mathbf{T s}, \mathbf{T}$ ). We simultaneously define the predicates of ( $\mathbf{T s}, \mathbf{T}$ )-totality. The ( $\mathbf{T s}, \mathbf{T}$ )-totality predicates are $\left(T_{\mathbf{T s}}, T_{\mathbf{T}}\right)$ whose arities are $(\mathbf{T s})$ and $(\mathbf{T})$, respectively. Define $\left(T_{\mathbf{T s}}, T_{\mathbf{T}}\right)$ to be $\mu_{X, Y}\left(K_{0}, K_{1}, K_{2}\right)$ where

$$
\begin{aligned}
& K_{0}=X \text { Empty }, \\
& K_{1}=\forall_{a}\left(Y a \rightarrow \forall_{a s}(X \text { as } \rightarrow X(\text { Tcons } a \text { as }))\right), \\
& K_{2}=\forall_{a s}(Y \text { as } \rightarrow X(\text { Branch } a s)) .
\end{aligned}
$$

The introduction and elimination axioms are as follows. Let $P_{0}$ and $P_{1}$ be predicate variables of arities (Ts) and (T).

$$
\begin{array}{ll}
T_{\mathbf{T s}} \text { Empty, } & \left(T_{\mathbf{T s}}, T_{\mathbf{T}}\right)_{0}^{+} \\
\forall_{a}\left(T_{\mathbf{T}} a \rightarrow \forall_{a s}\left(T_{\mathbf{T s}} \text { as } \rightarrow T_{\mathbf{T s}}(\text { Tcons } a \text { as })\right)\right), & \left(T_{\mathbf{T s}}, T_{\mathbf{T}}\right)_{1}^{+} \\
\forall_{a s}\left(T_{\mathbf{T s}} a s \rightarrow T_{\mathbf{T}}(\text { Branch } a s)\right), & \left(T_{\mathbf{T s}}, T_{\mathbf{T}}\right)_{2}^{+} \\
\forall_{a s}\left(T_{\mathbf{T s}} a s \rightarrow S_{0} \rightarrow S_{1} \rightarrow S_{2} \rightarrow P_{0} a s\right), & \left(T_{\mathbf{T s}}, T_{\mathbf{T}}\right)_{0}^{-} \\
\forall_{a}\left(T_{\mathbf{T}} a \rightarrow S_{0} \rightarrow S_{1} \rightarrow S_{2} \rightarrow P_{1} a\right), & \left(T_{\mathbf{T s}}, T_{\mathbf{T}}\right)_{1}^{-}
\end{array}
$$

where

$$
\begin{aligned}
& S_{0}=P_{0} \text { Empty }, \\
& S_{1}=\forall_{a}\left(T_{\mathbf{T}} a \rightarrow P_{1} a \rightarrow \forall_{a s}\left(T_{\mathbf{T s}} a s \rightarrow P_{0} \text { as } \rightarrow P_{0}(\text { Tcons } a \text { as })\right)\right), \\
& \left.S_{2}=\forall_{a s}\left(T_{\mathbf{T s}} a s \rightarrow P_{0} \text { as } \rightarrow P_{1} \text { as }\right)\right) .
\end{aligned}
$$

The companion predicates of the above are simultaneously coinductively defined predicates $\left({ }^{\mathrm{co}} T_{\mathbf{T s}},{ }^{\mathrm{co}} T_{\mathbf{T}}\right)$ of arities $(\mathbf{T s})$ and $(\mathbf{T})$, respectively. They are defined to be $\nu_{X, Y}\left(K_{0}, K_{1}, K_{2}\right)$, then closure and greatest-fixed-point axioms are as follows.

$$
\begin{array}{ll}
\forall_{a s}\left({ }^{\mathrm{co}} T_{\mathbf{T s}} a s \rightarrow a s \text { eqd Empty } V\right. & \left({ }^{\mathrm{co}} T_{\mathbf{T s}},{ }^{\mathrm{co}} T_{\mathbf{T}}\right)_{0}^{-} \\
\left.\quad \exists_{b, b s}\left({ }^{\mathrm{co}} T_{\mathbf{T}} b \wedge{ }^{\mathrm{co}} T_{\mathbf{T s}} b s \wedge \text { as eqd Tcons } b b s\right)\right), & \left({ }^{\mathrm{co}} T_{\mathbf{T s}},{ }^{\mathrm{co}} T_{\mathbf{T}}\right)_{1}^{-} \\
\forall \forall_{a}\left({ }^{\mathrm{co}} T_{\mathbf{T}} a \rightarrow \exists_{a s}\left({ }^{\mathrm{co}} T_{\mathbf{T s}} a s \wedge a \text { eqd Branch as }\right)\right), & \left({ }^{\mathrm{co}} T_{\mathbf{T s}},{ }^{\mathrm{co}} T_{\mathbf{T}}\right)_{0}^{+} \\
\forall_{a s}\left(P_{0} \text { as } \rightarrow{ }^{\mathrm{co}} S_{0} \rightarrow{ }^{\mathrm{co}} S_{1} \rightarrow{ }^{\mathrm{co}} T_{\mathbf{T s}} a s\right), & \left({ }^{\mathrm{co}} T_{\mathbf{T s}},{ }^{\mathrm{co}} T_{\mathbf{T}}\right)_{1}^{+} \\
\forall_{a}\left(P_{1} a s \rightarrow{ }^{\mathrm{co}} S_{0} \rightarrow{ }^{\mathrm{co}} S_{1} \rightarrow{ }^{\mathrm{co}} T_{\mathbf{T}} a\right), &
\end{array}
$$

where,

$$
\begin{aligned}
& { }^{\mathrm{co}} S_{0}=\forall_{a s}\left(P_{0} \text { as } \rightarrow \text { as eqd Empty } \vee \exists_{b, b s}\left(\left({ }^{\mathrm{co}} T_{\mathbf{T}} \cup P_{1}\right) b \wedge\left({ }^{\mathrm{c}} T_{\mathbf{T s}} \cup P_{0}\right) b s \wedge \text { as eqd Tcons } b b s\right)\right), \\
& { }^{{ }^{\mathrm{co}}} S_{1}=\forall_{a}\left(P_{1} a \rightarrow \exists_{a s}\left(\left({ }^{\mathrm{c}} T_{\mathbf{T s}} \cup P_{0}\right) a s \wedge a \text { eqd Branch as }\right)\right) .
\end{aligned}
$$

### 2.4 Proofs

In this section we focus on providing our notion of proofs or derivations in TCF. The word derivation is used for a formal representation of a proof, while the word proof is rather used for the informal level. We formulate the term representation of natural deduction derivations and its conversion. We leave the details of first order logic to the relevant literature vD94, TS00, SW12.

### 2.4.1 Natural Deduction

Our base logic is first-order minimal logic with the implication and the universal quantifier. Axioms given by inductive and coinductive definitions extend the logic. We focus on defining the term representation of derivations which is required in program extraction in Section 2.5. We define the notion of derivations.

Definition 2.4.1 (Derivations). Let $A$ and $B$ be variables which range over formulas, $x$ range over object variables and $r$ range over terms. We inductively define a derivation. Assumption An arbitrary formula $A$ is a derivation from an open assumption $A$.
Axiom An arbitrary axiom $A$ is a derivation.
We depict this derivation by $A$. There are the introduction and elimination rules for the implication and for the universal quantifier.

The introduction rule of the universal quantifier We assume a derivation of $A$ which does not contain any open assumption which has $x$ as a free variable and construct a derivation of $\forall_{x} A$.

The elimination rule of the universal quantifier We assume a derivation of $\forall_{x} A$ and a term $r$ of the same type as $x$ and construct a derivation of $A$.

The introduction rule of the implication We assume a derivation of $B$ and construct a derivation of $A \rightarrow B$ with cancelling all open assumption $A$ in the derivation of $B$.

The elimination rule of the implication We assume a derivation of $A \rightarrow B$ and another one of $B$ and construct a derivation of $B$.

Those derivations are depicted as follows. The introduction rules of the universal quantifier and the implication are denoted by $\forall^{+}$and $\rightarrow^{+}$and the elimination rules of the universal quantifier and the implication are denoted by $\forall^{-}$and $\rightarrow^{-}$, respectively. A use of the introduction of the implication and the corresponding cancelled open assumptions are indicated by an assumption variable and square brackets.

Via the Curry-Howard correspondence we consider derivation terms, a term representation of derivations. We consider each axiom name as a constant of derivation terms. For example, let $I$ and ${ }^{\text {co }} I$ be inductively and coinductively defined predicate constants, respectively, then $I_{i}^{+}, I^{-},{ }^{\text {co }} I^{-}$and ${ }^{c o} I^{+}$, are constants. Let $c$ range over constants.

Definition 2.4.2 (Derivation terms). We define derivation terms by induction on the construction of a derivation.
(Assumption) A derivation term of a derivation $u: A$ is $u^{A}$.
$\vdots D$
$\frac{\dot{A}}{\forall_{x} A} \forall^{+}$
$\frac{\begin{array}{c}\vdots D \\ \forall_{x^{\rho}} A \quad r^{\rho} \\ A(r)\end{array} \forall^{-}}{}$

$$
\begin{gathered}
{[u: A]} \\
\vdots D \\
\frac{\dot{B}}{A \rightarrow B} \rightarrow^{+} u
\end{gathered}
$$

(Axiom) A derivation term of a derivation $A$ by an axiom $c$ is $c^{A}$.
$\left(\forall^{+}\right)$A derivation term of a derivation

$$
\begin{gathered}
\vdots D \\
\frac{\vdots}{\forall_{x} A} \forall^{+}
\end{gathered}
$$

is $\left(\lambda_{x} M\right)^{\forall_{x} A}$, where $M^{A}$ is a derivation term of $D$.
$\left(\forall^{-}\right)$A derivation term of a derivation

$$
\begin{gathered}
\vdots D \\
\frac{\forall_{x^{\rho}} A}{} \quad r^{\rho} \\
A(r)
\end{gathered} \forall^{-}
$$

is $\left(M^{\forall_{x} A} r\right)^{A}$, where $M^{\forall_{x} A}$ is a derivation term of $D$.
$\left(\rightarrow^{+}\right)$A derivation term of a derivation

$$
\begin{gathered}
{[u: A]} \\
\vdots D \\
\frac{\dot{B}}{A \rightarrow B} \rightarrow^{+} u
\end{gathered}
$$

is $\left(\lambda_{x}^{A} M^{B}\right)^{A \rightarrow B}$, where $M^{B}$ is a derivation term of $D$.
$\left(\rightarrow^{-}\right)$A derivation term of a derivation

$$
\begin{array}{cc}
\begin{array}{cc}
D & \vdots \\
A \rightarrow B & A \\
B
\end{array} \rightarrow^{-}
\end{array}
$$

is $\left(M^{A \rightarrow B} N^{A}\right)^{B}$, where $M^{A \rightarrow B}$ and $N^{A}$ are the derivation terms of $D$ and $E$, respectively. Example 2.4.3. Recall Even and $T_{\mathbf{N}}$ defined in Example 2.3.11 and Example 2.3.21, respectively. We prove $\forall_{n}\left(\right.$ Even $\left.n \rightarrow T_{\mathbf{N}} n\right)$ as follows. Suppose that $S_{0}$ and $S_{1}$ are the step
formulas of Even ${ }^{-}$, i.e., $P 0$ and $\forall_{n}($ Even $n \rightarrow P n \rightarrow P(\mathrm{~S}(\mathrm{~S} n)))$. Then,

$$
\begin{aligned}
& \underline{\forall_{n}\left(\text { Even } n \rightarrow S_{0} \rightarrow S_{1} \rightarrow T_{\mathrm{N}} n\right)}{ }^{\text {Even }}{ }^{-} n
\end{aligned}
$$

where $M_{0}$ and $M_{1}$ are

$$
\begin{aligned}
& \overline{T_{\mathbf{N}} 0}\left(T_{\mathbf{N}}\right)_{0}^{+}, \\
& \frac{\overline{\forall_{n}\left(T_{\mathbf{N}} n \rightarrow T_{\mathbf{N}}(\mathrm{S} n)\right)}\left(T_{\mathbf{N}}\right)_{1}^{+} \quad \mathrm{S}_{n} \quad \frac{\overline{\forall_{n}\left(T_{\mathbf{N}} n \rightarrow T_{\mathbf{N}}(\mathrm{S} n)\right)}\left(T_{\mathbf{N}}\right)_{1}^{+}}{} \quad n}{} \begin{array}{l}
\frac{T_{\mathbf{N}} n \rightarrow T_{\mathbf{N}}(\mathrm{S} n)}{T_{\mathbf{N}}(\mathrm{S} n) \rightarrow T_{\mathbf{N}}(\mathrm{S}(\mathrm{~S} n))} \\
\\
\frac{T_{\mathbf{N}}(\mathrm{S}(\mathrm{~S} n))}{\left.T_{\mathbf{N}} n \rightarrow T_{\mathbf{N}} n\right]^{v_{1}}} \\
\frac{\operatorname{Even} n \rightarrow T_{\mathbf{N}} n \rightarrow T_{\mathbf{N}}(\mathrm{S}(\mathrm{~S} n))}{T^{+}} v_{1} \\
\forall_{n}\left(\operatorname{Even} n \rightarrow T_{\mathbf{N}} n \rightarrow T_{\mathbf{N}}(\mathrm{S}(\mathrm{~S} n))\right)
\end{array}
\end{aligned}
$$

Omitting the superscript formulas, the derivation term of the above is

$$
\lambda_{n, u}\left(\operatorname{Even}^{-} n u\left(T_{\mathbf{N}}\right)_{0}^{+}\left(\lambda_{n, v_{0}, v_{1}}\left(T_{\mathbf{N}}\right)_{1}^{+}(\mathrm{S} n)\left(\left(T_{\mathbf{N}}\right)_{1}^{+} n v_{1}\right)\right)\right)
$$

### 2.4.2 Proof Conversion

We adopt the standard conversion rules for $\forall$ and $\rightarrow$. In addition, we extend the conversion in order to support axioms of inductively and coinductively defined predicates.

Definition 2.4.4 (Proof conversion for $\rightarrow$ and $\forall$ ). The conversions for $\rightarrow$ and $\forall$ are defined to be

$$
\begin{aligned}
& \begin{array}{l}
\vdots M_{x} \\
\frac{A(x)}{\forall_{x} A(x)} \forall^{+} r \\
A(r)
\end{array} \forall^{-} \quad \mapsto \quad \begin{array}{c}
\vdots(r) \quad .
\end{array}
\end{aligned}
$$

### 2.4. Proofs

The following conversion rule removes a certain use of the introduction and elimination axioms which is taken as a detour.

Definition 2.4.5 (Proof conversion for inductive predicates). Let $I$ be an inductively defined predicate and $P$ be a predicate variable of the same arity as $I$. Abbreviate the step formulas of $I^{-}$as $\vec{S}$ and suppose that each $I_{i}^{+}$is of the form $\forall_{\vec{x}}\left(\left(A_{i \nu}(I)\right)_{\nu<n} \rightarrow I \vec{t}\right)$. Then, we consider the following derivation:

Suppose that $S_{i}$ is of the form $\forall \underset{\vec{x}}{\mathrm{nc}}\left(\left(A_{i \nu}(I \cap P)\right)_{\nu<n} \rightarrow P \vec{t}\right)$ and Mon abbreviates Lemma 2.3.23. We convert the above derivation into
where $K$ and $L$ are respectively as follows:

As a derivation term, the above conversion reads

$$
I^{-} \vec{t}\left(I_{i}^{+} \vec{x} M_{\nu<n}\right) \vec{N} \mapsto N_{i} \vec{t}\left(\operatorname{Mon} \vec{x} M_{\nu}\left(\lambda_{\vec{x}, u}\left(\wedge^{+} u\left(I^{-} \vec{x} u \vec{N}\right)\right)\right)\right)_{\nu<n} .
$$

We consider conversion involving coinductively defined predicates. A certain use of a closure axiom and a greatest-fixed-point axiom is considered to be a detour and removed.

Definition 2.4.6 (Proof conversion for coinductive predicates). Let ${ }^{\text {co } I}$ be a coinductively defined predicate and $P$ be a predicate variable of the same arity of ${ }^{c \circ} I$. We abbreviate $\bigvee_{i<k}\left(\bigwedge_{\nu<n} A_{i \nu}(X)\right)$ as $C_{X}$ and the costep formula of ${ }^{\text {co }} I^{+}$as ${ }^{c} S$, then we consider the following derivation:


By the conversion rule, the occurrence of ${ }^{\mathrm{co}} \mathrm{I}^{-}$in the above derivation is removed.
where we suppose that $A^{\prime}$ is a formula $\forall_{\vec{x}}\left(\left({ }^{(\mathrm{CO}} I \cup P\right) \vec{t} \rightarrow{ }^{\mathrm{co}} I \vec{t}\right)$ and $B_{X}^{i}$ is a formula $\bigwedge_{\nu<n_{i}} A_{i \nu}(X)$. Omitting $i$ without any confusion, each $K_{i}$ is given as follows:

By using ${ }^{\text {co }} I^{+}$, we can derive ${ }^{\text {co }} I \vec{t}$ from $P \vec{t}$. Note that we can also use the derivation $M$ for the costep formula of ${ }^{\text {co }} I^{+}$, then the derivation $L_{i}$ is given as follows:

As a derivation term, the above conversion rule is

$$
{ }^{\mathrm{co}} I^{-} \vec{t}\left({ }^{\mathrm{co}} I^{+} \vec{t} N M\right) \mapsto \mathrm{V}^{-}(M N)\left(\lambda_{u_{i}}\left(\operatorname{Mon} \vec{t} u_{i} \lambda_{\vec{x}, w}\left(\mathrm{~V}^{-} w v_{0}\left({ }^{\mathrm{co}} I^{+} \vec{x} v_{1} M\right)\right)\right)\right)_{i<n}
$$

### 2.5 Realizability Interpretation

According to Kreisel's modified realizability interpretation, a formula of the form $\forall_{x} A(x)$ is realized by a recursive function which maps a given $x$ to a realizer of $A(x)$. Similarly, a formula of the form $A \rightarrow B$ is realized by a recursive function which maps a realizer of $A$ to a realizer of $B$. In order to fine-tune computational content of proofs, we consider computational and non-computational universal quantifiers and implications, denoted by $\forall^{c}$, $\forall^{\mathrm{nc}}, \rightarrow^{\mathrm{c}}$ and $\rightarrow^{\mathrm{nc}}$. These additional superscript notations are called decorations. The syntax of decorated universal quantifiers and implications are given by modifying Definition 2.3.1 and 2.3.5.

Definition 2.5.1 (Decorated formula forms). We define formula forms by

$$
A, B::=P \vec{t}\left|A \rightarrow{ }^{\mathrm{c}} B\right| \forall_{x}^{\mathrm{c}} A\left|A \rightarrow{ }^{\mathrm{nc}} B\right| \forall_{x}^{\mathrm{nc}} A
$$

and $\forall$ and $\rightarrow$ in the definition of predicate forms are arbitrarily $\forall^{\mathrm{c}}$ or $\forall^{\mathrm{nc}}$, and $\rightarrow^{\mathrm{c}}$ or $\rightarrow^{\mathrm{nc}}$, respectively. Then the rest of definitions are modified to accept the same rules for decorated formula forms replacing the rules for non-decorated formula forms.

The non-computational universal quantifier was first studied by Berger [Ber93]. They are logically equivalent, but computationally different. The computational ones, namely, $\forall^{c}$ and $\rightarrow^{\mathrm{c}}$, are interpreted by functions as commonly done. A realizer of $\forall_{x}^{\text {nc }} A(x)$ is defined to be a realizer of $A(x)$ for an arbitrary $x$. The input $x$ can occur in the formula $A(x)$, but not used to compute the output. A realizer of $A \rightarrow{ }^{\text {nc }} B$ is defined to be a realizer of $B$ provided there exists a realizer of $A$. Here, an existence of a realizer of $A$ is necessary, but it is not used.

Section 2.5.1 is devoted to discuss the decoration of clause formulas of inductive and coinductive definitions due to Ratiu and Schwichtenberg [RS10] and Schwichtenberg [SW12]. In Section 2.5.2, we introduce the notion of realizability interpretation for our setting based on Schwichtenberg [SW12]. We extend it to nested and coinductive definitions, then the program extraction is given. We prove the soundness of our realizability interpretation in Section 2.5.3. Theoretically, it claims that every theorem has a realizer.

### 2.5.1 Decorating Inductive and Coinductive Definitions

We consider computational inductive and coinductive definitions through decorating clause formulas explicitly. Then, we also study non-computational inductive and coinductive definitions. Although decorated formulas are logically the same as non-decorated formulas, they are computationally different. This difference becomes clear from the realizability interpretation given in Section 2.5.2. At the end of this section, we extend the notion of proofs to the inference rules of decorated connectives. Particularly in the introduction axioms of non-computational universal quantifier and implication we pose some restrictions in order to keep the computational consistency.

Definition 2.5.2 (Decorating Inductive Definitions). Suppose that an inductive predicate $I$ is given as

$$
\mu_{X}\left(\forall_{\vec{x}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}(X)\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} X \vec{t}\right)\right)_{i<k}
$$

where $\forall^{\mathrm{c} / \mathrm{nc}}$ and $\rightarrow^{\mathrm{c} / \mathrm{nc}}$ are arbitrarily decorated. The introduction axioms $I_{i}^{+}$are obtained by substituting $I$ for $X$ in $A_{i \nu}$. The elimination axiom $I^{-}$is decorated as

$$
\forall_{\vec{x}}^{\mathrm{nc}}\left(I \vec{x} \rightarrow^{\mathrm{c}}\left(\forall_{\vec{x}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}\left(I \cap^{\mathrm{d}} P\right)\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} P \vec{t}\right)\right)_{i<k} \rightarrow^{\mathrm{c}} P \vec{x}\right)
$$

where $\forall^{\mathrm{c} / \mathrm{nc}}$ and $\rightarrow^{\mathrm{c} / \mathrm{nc}}$ in the step formulas are decorated as the clause formulas are.

We decorate inductively defined conjunction, disjunction and existential quantifier. There are variants in order to specify which part of the formula has the computational significance.

Example 2.5.3 (Decorated conjunction). We define the following decorated conjunctions. Here, the superscripts d, u, l and r stand for double, uniformed, left and right, respectively.

$$
\begin{array}{ll}
A \rightarrow^{\mathrm{c}} B \rightarrow^{\mathrm{c}} A \wedge^{\mathrm{d}} B & \left(\wedge^{\mathrm{d}}\right)^{+} \\
A \wedge^{\mathrm{d}} B \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{c}} B \rightarrow^{\mathrm{c}} P\right) \rightarrow^{\mathrm{c}} P & \left(\wedge^{\mathrm{d}}\right)^{-} \\
A \rightarrow^{\mathrm{nc}} B \rightarrow^{\mathrm{nc}} A \wedge^{\mathrm{u}} B & \left(\wedge^{\mathrm{u}}\right)^{+} \\
A \wedge^{\mathrm{u}} B \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{nc}} B \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}} P & \left(\wedge^{\mathrm{u}}\right)^{-} \\
A \rightarrow^{\mathrm{c}} B \rightarrow^{\mathrm{nc}} A \wedge^{\mathrm{l}} B & \left(\wedge^{\mathrm{l}}\right)^{+} \\
A \wedge^{1} B \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{c}} B \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}} P & \left(\wedge^{\mathrm{l}}\right)^{-} \\
A \rightarrow^{\mathrm{nc}} B \rightarrow^{\mathrm{c}} A \wedge^{\mathrm{r}} B & \left(\wedge^{\mathrm{r}}\right)^{+} \\
A \wedge^{\mathrm{r}} B \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{nc}} B \rightarrow^{\mathrm{c}} P\right) \rightarrow^{\mathrm{c}} P & \left(\wedge^{\mathrm{r}}\right)^{-}
\end{array}
$$

For predicates $Q_{1}$ and $Q_{2}$ of the same arity $(\vec{\tau})$, we define $Q_{1} \cap^{\circ} Q_{2}$ to be $\left\{\vec{x} \mid Q_{1} \vec{x} \wedge^{\circ} Q_{2} \vec{x}\right\}$, where $\circ \in\{\mathrm{d}, \mathrm{l}, \mathrm{r}\}$.

Notice that $\cap$ is not used in the definitions of $\wedge^{\circ}$. Definition 2.5.2 is therefore defined without any circularity. Due to Definition 2.5.12, $\wedge^{u}$ can be treated as a non-computational inductive predicate.

Example 2.5.4 (Decorated disjunction). We define the following decorated disjunctions.

Here, the superscripts d, u, l and r stand for double, uniformed, left and right, respectively.

$$
\begin{array}{ll}
A \rightarrow^{\mathrm{c}} A \vee^{\mathrm{d}} B & \left(\vee^{\mathrm{d}}\right)_{0}^{+} \\
B \rightarrow^{\mathrm{c}} A \vee^{\mathrm{d}} B & \left(\vee^{\mathrm{d}}\right)_{1}^{+} \\
A \vee^{\mathrm{d}} B \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{c}} P\right) \rightarrow^{\mathrm{c}}\left(B \rightarrow^{\mathrm{c}} P\right) \rightarrow^{\mathrm{c}} P & \left(\vee^{\mathrm{d}}\right)^{-} \\
A \rightarrow^{\mathrm{nc}} A \vee^{\mathrm{u}} B & \left(\vee^{\mathrm{u}}\right)_{0}^{+} \\
B \rightarrow^{\mathrm{nc}} A \vee^{\mathrm{u}} B & \left(\vee^{\mathrm{u}}\right)_{1}^{+} \\
A \vee^{\mathrm{u}} B \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}}\left(B \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}} P & \left(\vee^{\mathrm{u}}\right)^{-} \\
A \rightarrow^{\mathrm{c}} A \vee^{\mathrm{l}} B & \left(\vee^{\mathrm{l}}\right)_{0}^{+} \\
B \rightarrow^{\mathrm{nc}} A \vee^{\mathrm{l}} B & \left(\vee^{\mathrm{l}}\right)_{1}^{+} \\
A \vee^{\mathrm{l}} B \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{c}} P\right) \rightarrow^{\mathrm{c}}\left(B \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}} P & \left(\vee^{\mathrm{l}}\right)^{-} \\
A \rightarrow^{\mathrm{nc}} A \vee^{\mathrm{r}} B & \left(\vee^{\mathrm{r}}\right)_{0}^{+} \\
B \rightarrow^{\mathrm{c}} A \vee^{\mathrm{r}} B & \left(\vee^{\mathrm{r}}\right)_{1}^{+} \\
A \vee^{\mathrm{r}} B \rightarrow \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}}\left(B \rightarrow^{\mathrm{c}} P\right) \rightarrow^{\mathrm{c}} P & \left(\vee^{\mathrm{r}}\right)^{-}
\end{array}
$$

For predicates $Q_{1}$ and $Q_{2}$ of the same arity $(\vec{\tau})$, we define $Q_{1} \cup^{\circ} Q_{2}$ to be $\left\{\vec{x} \mid Q_{1} \vec{x} \vee^{\circ} Q_{2} \vec{x}\right\}$, where $\circ \in\{\mathrm{d}, \mathrm{u}, \mathrm{l}, \mathrm{r}\}$.

Example 2.5.5 (Decorated existential quantifier). We define the following decorated existential quantifiers. Here, the superscripts $d, u, l$ and $r$ stand for double, uniformed, left and right, respectively.

$$
\begin{array}{llll}
\forall_{x^{\rho}}^{\mathrm{c}}\left(A \rightarrow^{\mathrm{c}} \exists_{x}^{\mathrm{d}} A\right) & \left(\exists^{\mathrm{d}}\right)^{+} & \forall_{x^{\rho}}^{\mathrm{nc}}\left(A \rightarrow^{\mathrm{nc}} \exists_{\left.x^{\mathrm{u}} A\right)}\right. & \left(\exists^{\mathrm{u}}\right)^{+} \\
\exists_{x}^{\mathrm{d}} A \rightarrow^{\mathrm{c}} \forall_{x^{\rho}}^{\mathrm{c}}\left(A \rightarrow^{\mathrm{c}} P\right) \rightarrow^{\mathrm{c}} P & \left(\exists^{\mathrm{d}}\right)^{-} & \exists_{x}^{\mathrm{u}} A \rightarrow^{\mathrm{c}} \forall_{x^{\rho}}^{\mathrm{nc}}\left(A \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}} P & \left(\exists^{\mathrm{u}}\right)^{-} \\
\forall_{x^{\rho}}^{\mathrm{c}}\left(A \rightarrow \rightarrow^{\mathrm{nc}} \exists_{x}^{\mathrm{l}} A\right) & \left(\exists^{\mathrm{l}}\right)^{+} & \forall_{x^{\rho}}^{\mathrm{nc}}\left(A \rightarrow^{\mathrm{c}} \exists_{x}^{\mathrm{r}} A\right) & \left(\exists^{\mathrm{r}}\right)^{+} \\
\exists_{x}^{\mathrm{l}} A \rightarrow^{\mathrm{c}} \forall_{x^{\rho}}^{\mathrm{c}}\left(A \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}} P & \left(\exists^{\mathrm{l}}\right)^{-} & \exists_{x}^{\mathrm{r}} A \rightarrow^{\mathrm{c}} \forall_{x^{\rho}}^{\mathrm{nc}}\left(A \rightarrow^{\mathrm{c}} P\right) \rightarrow^{\mathrm{c}} P & \left(\exists^{\mathrm{r}}\right)^{-}
\end{array}
$$

Due to Definition 2.5.12, $\exists^{u}$ can be treated as a non-computational inductive predicate.
Example 2.5.6. Let $A, B$ and $C$ be formulas. Assume conjunction is right associative. In a decorated formula $A \wedge^{\mathrm{r}} B \wedge^{\mathrm{d}} C$ the formula $A$ is treated as a non-computational formula. The others, $B$ and $C$ are treated as a computational formulas. In a decorated formula $A \wedge^{1} B \wedge^{1} C$ the formula $A$ is treated as computational formula. The others are treated as non-computational ones.

Example 2.5.7. Let $A$ and $B$ be formulas and $x$ be a variable. In a formula $\exists_{x}^{1}(A)$, the variable $x$ is treated as a computational object, and the formula $A$ is treated as a non-computational formula. In a formula $\exists_{x}^{\mathrm{r}}\left(A \vee^{\mathrm{u}} B\right)$ the formula $A \vee^{\mathrm{u}} B$ is treated as a computational formula. The variable $x$ and the formulas $A$ and $B$ are treated as a non-computational variable and non-computational formulas, respectively.

Definition 2.5.8 (Decorating coinductive predicates). Suppose that a coinductively defined predicate ${ }^{\text {co }} I=\nu_{X}\left(\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}(X)\right)_{\nu<n_{i}} \rightarrow X \vec{t}_{i}\right)\right)_{i<k}$ is given. As in Definition 2.3.15, we form a formula $\exists_{\vec{x}_{i}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}(X) \wedge \bigwedge \vec{E}_{i}\right)=$ : ${ }^{\text {co }} K_{i}(X)$ for each $i<k$ and decorate it. We use $\wedge^{\mathrm{d}}$, $\wedge^{1}, \wedge^{\mathrm{r}}$ and $\wedge^{\mathrm{u}}$ to specify which $A_{i \nu}(X)$ is computational, and also use $\exists^{\mathrm{d}}, \exists^{\mathrm{l}}, \exists^{\mathrm{r}}$ and $\exists^{\mathrm{u}}$ to specify which $x_{i}$ is computational. The following is the rule of decoration:

- $A_{i \nu}$ followed by $\rightarrow^{\mathrm{c}}$ is computational.
- $A_{i \nu}$ followed by $\rightarrow^{\mathrm{nc}}$ is non-computational.
- $x_{i}$ which occurs with $\forall^{\mathrm{c}}$ is computational.
- $x_{i}$ which occurs with $\forall^{\mathrm{nc}}$ is non-computational.

For decorated ${ }^{\text {co }} K_{i}(X)$, we form the disjunction $\bigvee_{i<k}{ }^{\text {co }} K_{i}(X)$ by using $\vee^{\mathrm{d}}, \vee^{1}, \vee^{\mathrm{r}}$ and $\vee^{\mathrm{u}}$. If there is neither $\rightarrow^{\mathrm{c}}$ nor $\forall^{\mathrm{c}}$ in the $i$-th clause formula, ${ }^{\mathrm{c}} K_{i}(X)$ is treated as non-computational disjunct. Otherwise it is computational. The following is the decorated closure axiom.

$$
\forall_{\vec{y}}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I \vec{y} \rightarrow{ }^{\mathrm{c}} \bigvee_{i<k}{ }^{\mathrm{co}} K_{i}\left({ }^{\mathrm{co}} I\right)\right) .
$$

The greatest-fixed-point axioms are decorated as follows.

$$
\forall_{\vec{y}}^{\mathrm{nc}}\left(P \vec{y} \rightarrow^{\mathrm{c}} \forall_{\vec{y}}^{\mathrm{nc}}\left(P \vec{y} \rightarrow^{\mathrm{c}} \bigvee_{i<k}{ }^{\mathrm{co}} K_{i}\left({ }^{\mathrm{co} I} \cup^{\mathrm{d}} P\right)\right) \rightarrow^{\mathrm{c}} \mathrm{co} I \vec{y}\right)
$$

There are two kinds of non-computational definitions. The first kind is an arbitrary inductively and coinductively defined predicate which is marked as a non-computational one under the two restrictions; the predicate parameters are invariant and the competitor predicate in the elimination axiom is non-computational. They are called non-computational inductively (coinductively) defined predicates. The second kind is a so-called special noncomputational inductive definition which is used for an inductive definition with one clause formula involving no recursive premise and containing $\forall^{\mathrm{nc}}$ and $\rightarrow^{\mathrm{nc}}$ only.

Definition 2.5.9 (Non-computational inductive and coinductive definitions). We extend predicate forms in the following way

$$
\begin{aligned}
P::= & X|\{\vec{x} \mid A\}| \mu_{X}\left(\forall_{\vec{x}_{i}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} X \vec{t}_{i}\right)\right)_{i<k}\left|\nu_{X}\left(\forall_{\vec{x}_{i}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} X \overrightarrow{t_{i}}\right)\right)_{i<k}\right| \\
& \mu_{X}^{\mathrm{nc}}\left(\forall_{\vec{x}_{i}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} X \overrightarrow{t_{i}}\right)\right)_{i<k} \mid \nu_{X}^{\mathrm{nc}}\left(\forall_{\vec{x}_{i}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} X \vec{t}_{i}\right)\right)_{i<k},
\end{aligned}
$$

where $\forall^{\mathrm{c} / \mathrm{nc}}$ and $\rightarrow^{\mathrm{c} / \mathrm{nc}}$ are arbitrarily decorated. Let $J$ be $\mu_{X}^{\mathrm{nc}}\left(\forall_{\vec{x}_{i}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} X \overrightarrow{t_{i}}\right)\right)_{i<k}$ or $\nu_{X}^{\mathrm{nc}}\left(\forall_{\vec{x}_{i}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} X \overrightarrow{t_{i}}\right)\right)_{i<k}$. A predicate form $J$ is a predicate if $\operatorname{Pred}(J)$ is derived using the following additional rule for Pred.

```
\(\frac{\text { for all } Y \in \operatorname{FPV}(A) \backslash \vec{X}, Y \text { is invariant }}{\mathrm{NC}_{\vec{X}}(A)}\)
for all \(i<k\), for all \(\nu<n_{i}, \mathrm{~F}\left(A_{i \nu}\right)\) and \(\mathrm{SP}_{X}\left(A_{i \nu}\right)\) and \(\mathrm{NC}_{X}\left(A_{i \nu}\right) \quad \operatorname{Inhab}(J)\)
    Pred( \(J\) )
```

The notion of being invariant is simultaneously given in Definition 2.5.22. Let $I$ and ${ }^{\text {co }} I$ be non-computational. inductive and non-computational coinductive predicates, respectively. The axioms $I_{i}^{+}, I^{-},{ }^{{ }^{\circ} I^{-}}$and ${ }^{{ }^{c o} I^{+}}$are given as the same formulas as the computational axioms, but the competitor predicate of $I^{-}$and ${ }^{{ }^{\text {co }} I^{+}}$are restricted to be non-computational.

We take a look at examples.
Example 2.5.10 (Non-computational disjunction). We give a non-computational disjunction $A \vee^{\text {nc }} B:=\mu_{X}^{\text {nc }}(A \rightarrow X, B \rightarrow X)$. The introduction and elimination axioms are the following.

$$
\begin{array}{ll}
A \rightarrow A \vee^{\mathrm{nc}} B & \left(\vee^{\mathrm{nc}}\right)_{0}^{+} \\
B \rightarrow A \vee^{\mathrm{nc}} B & \left(\vee^{\mathrm{nc}}\right)_{1}^{+} \\
A \vee^{\mathrm{nc}} B \rightarrow(A \rightarrow P) \rightarrow(B \rightarrow P) \rightarrow P & \left(\vee^{\mathrm{nc}}\right)^{-}
\end{array}
$$

We also introduce the notion of $\cup^{\text {nc }}$ in the same way as decorated disjunctions.
Example 2.5.11 (Weak disjunction). For formulas $A$ and $B$, we define $A \widetilde{\vee} B$ to be $((A \rightarrow \mathbf{F}) \wedge(B \rightarrow \mathbf{F})) \rightarrow \mathbf{F}$ which we call weak disjunction. We can prove $A \vee{ }^{\mathrm{nc}} B \rightarrow A \tilde{\vee} B$, but cannot prove $A \tilde{\vee} B \rightarrow A \vee^{\mathrm{nc}} B$. Although the conclusion $A \vee^{\mathrm{nc}} B$ is non-computational, one has to make a decision, either the left or the right, in order to show it. The premise $A \tilde{\vee} B$ does not provide such information.

The second kind of non-computational inductive definitions are as follows.
Definition 2.5.12 (One clause special non-computational inductive definitions). A noncomputational inductive definition $I_{\vec{Y}}:=\mu_{X}^{\mathrm{nc}}\left(\forall_{\vec{x}}\left(\left(A_{i \nu}\right)_{\nu<n_{i}} \rightarrow X \vec{t}\right)\right)_{i<k}$ can be a one clause special non-computational inductive definition if the following conditions are satisfied

1. There is only one clause formula, namely, $k=1$.
2. All implications and universal quantifiers are non-computational.
3. Premises $A_{0 \nu}$ for $\nu<n_{i}$ are of the form $Y_{j} \vec{s}_{j}$.

When an inductive predicate satisfies the above condition of one-clause special noncomputational inductive predicates, we always use the special non-computational inductive version. We take a look at an example.

Example 2.5.13 (Leibniz equality, non-computational conjunction and existential quantifier). We define the following special non-computational inductive predicates.

$$
\begin{aligned}
& \text { eqd }:=\mu_{X}^{\mathrm{nc}}\left(\forall_{x^{\alpha}}^{\mathrm{nc}}(X x x)\right), \\
& \wedge^{\mathrm{u}}:=\mu_{X}^{\mathrm{nc}}\left(A \rightarrow^{\mathrm{nc}} B \rightarrow^{\mathrm{nc}} X\right), \\
& \exists^{\mathrm{u}}:=\mu_{X}^{\mathrm{nc}}\left(\forall_{x}^{\mathrm{nc}}\left(Y x \rightarrow^{\mathrm{nc}} X\right)\right) .
\end{aligned}
$$

Their introduction and elimination axioms are as follows.

$$
\begin{array}{lr}
\forall_{x^{\rho}}^{\mathrm{nc}}(x \text { eqd } x) & \text { eqd }^{+} \\
\forall_{x^{\rho}, y^{\rho}}\left(x \text { eqd } y \rightarrow^{\mathrm{nc}} \forall_{x^{\rho}}^{\mathrm{nc}}(P x x) \rightarrow^{\mathrm{c}} P x y\right) & \mathrm{eqd}^{-} \\
A \rightarrow^{\mathrm{nc}} B \rightarrow^{\mathrm{nc}} A \wedge^{\mathrm{u}} B & \left(\wedge^{\mathrm{u}}\right)^{+} \\
A \wedge^{\mathrm{u}} B \rightarrow^{\mathrm{nc}}\left(A \rightarrow^{\mathrm{nc}} B \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}} P & \left(\wedge^{\mathrm{u}}\right)^{-} \\
\forall_{x^{\rho}}^{\mathrm{nc}}\left(A \rightarrow^{\mathrm{nc}} \exists_{x}^{\mathrm{u}} A\right) & \left(\exists^{\mathrm{u}}\right)^{+} \\
\forall_{x^{\rho}}^{\mathrm{nc}}\left(\exists_{x}^{\mathrm{u}} A \rightarrow^{\mathrm{nc}} \forall_{x}^{\mathrm{nc}}\left(A \rightarrow^{\mathrm{nc}} P\right) \rightarrow^{\mathrm{c}} P\right) & \left(\exists^{\mathrm{u}}\right)^{-}
\end{array}
$$

For eqd we adopt the infix notation as $x$ eqd $y$. For predicates $Q_{1}$ and $Q_{2}$ of the same arity $(\vec{\tau})$, we define $Q_{1} \cap^{\mathrm{u}} Q_{2}$ to be $\left\{\vec{x} \mid Q_{1} \vec{x} \wedge^{\mathrm{u}} Q_{2} \vec{x}\right\}$.

Example 2.5.14. Consider conjunction of formulas $A, B$ and $C$. If we are interested in computational content of $A$ only, a formula $A \wedge^{\mathrm{d}} B \wedge^{\mathrm{u}} C$ can instead be decorated as $A \wedge^{1} B \wedge^{\mathrm{u}} C$.

We define the extended type $\tau(A)$ of a formula $A$. The extended type $\tau(A)$ is either a type or the null type denoted by o. When $\tau(A)$ is a type, it tells us what the type of an extracted program from a proof of $A$ is. If any proof of the formula $A$ does not have computational content, there is nothing to extract from a proof and $\tau(A)$ results in the null type. When no confusion may arise, we simply call $\tau(A)$ a type rather than an extended type. Let $\rho$ be a type, then we extend the use of the arrow type in the following way.

$$
(\rho \rightarrow 0):=0, \quad(\circ \rightarrow \rho):=\rho, \quad(\circ \rightarrow 0):=0 .
$$

The types of formulas and predicates are defined by simultaneous induction on the construction of formulas and predicates.

Definition 2.5.15 (Type of formulas and predicates). Let $A$ be a formula and $P$ be a predicate. Assume type variables $\vec{\alpha}$ associated with $\vec{Y} \subseteq \operatorname{FPV}(A)$ and $\vec{Y} \subseteq \operatorname{FPV}(P)$. We define a type or a null type $\tau(A)$ and $\tau(P)$ by simultaneous induction on the construction of formulas and predicates.

$$
\begin{array}{ll}
\tau\left(A \rightarrow^{\mathrm{c}} B\right):=\tau(A) \rightarrow \tau(B), & \tau\left(A \rightarrow^{\mathrm{nc}} B\right):=\tau(B), \\
\tau\left(\forall_{x^{\rho}}^{\mathrm{c}} A\right):=\rho \rightarrow \tau(A), & \tau\left(\forall_{x^{\rho}}^{\mathrm{nc}} A\right):=\tau(A), \\
\tau(P \vec{t}):=\tau(P), & \tau(\{\vec{x} \mid B\}):=\tau(B), \\
\tau(X):=\xi_{X}, & \tau\left(Y_{i}\right):=\alpha_{i},
\end{array}
$$

If $I=\mu_{X}(\vec{K})$ and ${ }^{\text {co }} I=\nu_{X}(\vec{K})$ are computational inductive and coinductive definitions,

$$
\tau(I):=\mu_{\xi_{X}}\left(\tau\left(K_{0}\right), \ldots, \tau\left(K_{n-1}\right)\right), \quad \tau\left({ }^{\mathrm{co}} I\right):=\mu_{\xi_{x}}\left(\tau\left(K_{0}\right), \ldots, \tau\left(K_{n-1}\right)\right)
$$

and else if $I$ and ${ }^{c o} I$ are non-computational inductive and coinductive definitions,

$$
\tau(I):=\tau\left({ }^{\text {co }} I\right):=0 .
$$

Especially for an inductively (and coinductively) defined predicate $I$ (or ${ }^{\text {co }} I$ ), $\tau(I)$ (or $\tau\left({ }^{\text {co }} I\right)$ ) is referred to by the associated algebra of $I$ (or ${ }^{\text {co } I}$ ). Conventionally, we write $\iota_{I}$ for both $\tau(I)$ and $\tau\left({ }^{\mathrm{co}} I\right)$. A formula $A$ is computational or computationally relevant if $\tau(A)$ is not null. Otherwise, $A$ is non-computational. We abbreviate them as c.r. and n.c., respectively. We use these abbreviations also for predicates.

Now we address the issue of the notion of proofs involving $\forall^{\mathrm{nc}}$ and $\rightarrow^{\text {nc }}$. The rules in Definition 2.4.1 are used for $\forall^{\mathrm{c}}$ and $\rightarrow^{\mathrm{c}}$ as they are. Consider formulas $\forall_{x}^{\mathrm{nc}} B$ and $A \rightarrow{ }^{\mathrm{nc}} B$. The idea is that $x$ and $A$ can be used in $B$, but they should not make any computational significance. We formalize computational object variables and computational assumption variables in a proof, then restrict introduction rules of $\forall^{\mathrm{nc}}$ and $\rightarrow^{\mathrm{nc}}$ in order to be computationally consistent. Strictly speaking, the inference rules are simultaneously defined with CV and CA. The following definition of CV is due to Berger [Ber93].

Definition 2.5.16 (Computational object variables). Let $M^{A}$ be a derivation. If $\tau(A)=0$, $\mathrm{CV}(M)=\emptyset$. Otherwise, $\mathrm{CV}(M)$ is defined by induction on the construction of $M$.

$$
\begin{aligned}
\mathrm{CV}\left(c^{A}\right) & :=\emptyset\left(c^{A} \text { is an axiom }\right), \\
\mathrm{CV}\left(u^{A}\right) & :=\emptyset, \\
\mathrm{CV}\left(\left(\lambda_{u^{A}} M^{B}\right)^{A \rightarrow{ }^{\mathrm{c} B} B}\right) & :=\mathrm{CV}\left(\left(\lambda_{u^{A}} M^{B}\right)^{A \rightarrow{ }^{\mathrm{nc}} B}\right):=\mathrm{CV}(M), \\
\mathrm{CV}\left(\left(M^{A \rightarrow \rightarrow^{\mathrm{C}} B} N^{A}\right)^{B}\right) & :=\mathrm{CV}(M) \cup \mathrm{CV}(N), \\
\mathrm{CV}\left(\left(M^{A \rightarrow{ }^{\mathrm{nc}} B} N^{A}\right)^{B}\right) & :=\mathrm{CV}(M), \\
\mathrm{CV}\left(\left(\lambda_{x} M^{A}\right)^{\forall_{x}^{\mathrm{c} A} A}\right) & :=\mathrm{CV}\left(\left(\lambda_{x} M^{A}\right)^{\forall_{x}^{\mathrm{nc}} A}\right):=\mathrm{CV}(M) \backslash\{x\}, \\
\mathrm{CV}\left(\left(M^{\forall_{x}^{\mathrm{c}} A(x)} r\right)^{A(r)}\right) & :=\mathrm{CV}(M) \cup \mathrm{FV}(r), \\
\mathrm{CV}\left(\left(M^{\forall \mathrm{c}} A(x) r\right)^{A(r)}\right) & :=\mathrm{CV}(M) .
\end{aligned}
$$

The following definition of CA is due to Ratiu and Schwichtenberg [RS10].
Definition 2.5.17 (Computational assumption variables). Let $M^{A}$ be a derivation. If $\tau(A)=\circ, \mathrm{CA}(M)=\emptyset$. Otherwise, $\mathrm{CA}(M)$ is defined by induction on the construction of $M$.

$$
\begin{aligned}
\mathrm{CA}\left(c^{A}\right) & :=\emptyset\left(c^{A} \text { is an axiom }\right), \\
\mathrm{CA}\left(u^{A}\right) & :=\{u\}, \\
\mathrm{CA}\left(\left(\lambda_{u^{A}} M^{B}\right)^{A \rightarrow{ }^{\mathrm{c}} B}\right) & :=\mathrm{CA}\left(\left(\lambda_{u^{A}} M^{B}\right)^{A \rightarrow{ }^{\mathrm{nc}} B}\right):=\mathrm{CA}(M) \backslash\{u\}, \\
\mathrm{CA}\left(\left(M^{A \rightarrow{ }^{\mathrm{c}} B} N^{A}\right)^{B}\right) & :=\mathrm{CA}(M) \cup \mathrm{CA}(N), \\
\mathrm{CA}\left(\left(M^{A \rightarrow \rightarrow^{\mathrm{nc}} B} N^{A}\right)^{B}\right) & :=\mathrm{CA}(M), \\
\mathrm{CA}\left(\left(\lambda_{x} M^{A}\right)^{\forall_{x}^{c} A}\right) & :=\mathrm{CA}\left(\left(\lambda_{x} M^{A}\right)^{\forall_{x}^{\mathrm{nc}} A}\right):=\mathrm{CA}(M), \\
\mathrm{CA}\left(\left(M^{\forall_{x}^{c} A(x)} r\right)^{A(r)}\right) & :=\mathrm{CA}\left(\left(M^{\forall_{x}^{\mathrm{nc}} A(x)} r\right)^{A(r)}\right):=\mathrm{CA}(M) .
\end{aligned}
$$

We give the following introduction rules for $\forall^{\mathrm{nc}}$ and $\rightarrow^{\mathrm{nc}}$. It is necessary in order to keep the computational consistency of our notion of proofs.

Definition 2.5.18 (Inference rules of $\forall^{\mathrm{nc}}$ and $\rightarrow^{\mathrm{nc}}$ ). Let $A, B$ be variables which range over formulas, $M$ ranges over derivations, $u$ ranges over assumption variables, $x$ ranges over object variables. The elimination rules of $\forall^{\mathrm{nc}}$ and $\rightarrow^{\mathrm{nc}}$ are the same as ones of $\forall^{-}$and $\rightarrow^{-}$. The introduction rule of $\forall^{\text {nc }}$ is

The introduction rule of $\rightarrow^{\text {nc }}$ is

$$
\begin{gathered}
{\left[u^{A}\right]} \\
\frac{\stackrel{\vdots}{B}}{A \rightarrow^{\mathrm{nc}} B}\left(\rightarrow^{\mathrm{nc}}\right)^{+} u \quad \text { provided } u^{A} \notin \mathrm{CA}(M) .
\end{gathered}
$$

The elimination rules of $\forall^{\mathrm{nc}}$ and $\rightarrow^{\mathrm{nc}}$ are the same as the ones of $\forall^{\mathrm{c}}$ and $\rightarrow^{\mathrm{c}}$.
We introduce the computational equivalence between formulas. Based on it we can omit some decoration to simplify the matter.

Definition 2.5.19 (Computationally equivalent formulas). Formulas $A$ and $A^{\prime}$ is computationally equivalent if one can prove both of $A \rightarrow{ }^{\mathrm{c}} A^{\prime}$ and $A^{\prime} \rightarrow^{\mathrm{c}} A$, and also the identity function is a realizer of them.

It is easy to see that $A \rightarrow^{\mathrm{c}} B$ and $A \rightarrow^{\mathrm{nc}} B$ are computationally equivalent, and so $\forall_{x}^{\mathrm{c}} A$ and $\forall_{x}^{\mathrm{nc}} A$ are, provided $A$ is non-computational. We can omit the decorations and simply write $A \rightarrow B$ and $\forall_{x} A$. If $A$ is n.c. and $B$ is c.r., $A \wedge^{\mathrm{d}} B$ and $A \wedge^{\mathrm{r}} B$ are also computationally equivalent.

### 2.5.2 Program Extraction

We define the program extraction algorithm which translates a proof into a program. The notion of proofs is as given in Section 2.4 with decoration given in Section 2.5.1. The notion of programs is $\mathrm{T}^{+}$given in Section 2.2 . We first define the realizability interpretation which is a relation on a term in $\mathrm{T}^{+}$and a formula. Based on the realizability interpretation, we secondly define the program extraction algorithm. We define the empty term which is a realizer of non-computational formulas.

Definition 2.5.20 (Empty term). Let $t$ be a term. The empty term $\varepsilon$ is an extension of terms which satisfy the following:

$$
t \varepsilon:=t, \quad \varepsilon t:=\varepsilon, \quad \varepsilon \varepsilon:=\varepsilon
$$

For any formula and predicate $A, A \varepsilon:=A$.

The following is the realizability interpretation which is given by simultaneous induction on the structure of formulas and predicates in Definition 2.3.5. For a predicate $P$ of arity $(\vec{\tau})$ where the length of $\vec{\tau} \geq 0$, we define another predicate $P^{\mathbf{r}}$ of arity $(\tau(P), \vec{\tau})$.

Definition 2.5.21 (Realizability interpretation). Assume a formula $A$, a predicate $P$ and for each $Y_{i}$ of arity $\left(\vec{\delta}_{i}\right)$ a predicate variable $Y_{i}^{*}$ of arity $\left(\alpha_{i}, \vec{\delta}_{i}\right)$ for some type variable $\alpha_{i}$. We define the realizability interpretation $A^{\mathbf{r}}$ of $A$ by simultaneous induction on the construction of formulas and predicates.

$$
\begin{array}{ll}
\left(\forall_{x}^{\mathrm{c}} A\right)^{\mathbf{r}}:=\left\{u \mid \forall_{x}\left(A^{\mathbf{r}}(u x)\right)\right\}, & \left(A \rightarrow^{\mathbf{c}} B\right)^{\mathbf{r}}:=\left\{u \mid \forall_{x}\left(A^{\mathbf{r}} x \rightarrow B^{\mathbf{r}}(u x)\right)\right\}, \\
\left(\forall_{x}^{\mathrm{nc}} A\right)^{\mathbf{r}}:=\left\{u \mid \forall_{x}\left(A^{\mathbf{r}} u\right)\right\}, & \left(A \rightarrow^{\mathrm{nc}} B\right)^{\mathbf{r}}:=\left\{u \mid \forall_{x}\left(A^{\mathbf{r}} x \rightarrow B^{\mathbf{r}} u\right)\right\}, \\
(P \vec{s})^{\mathbf{r}}:=\left\{u \mid P^{\mathbf{r}} u \vec{s}\right\}, & Y_{i}^{\mathbf{r}}:=\left\{u, \vec{x} \mid Y_{i}^{*} u \vec{x}\right\} \quad\left(Y_{i} \text { c.r. }\right), \\
\{\vec{x} \mid A\}^{\mathbf{r}}:=\left\{u, \vec{x} \mid A^{\mathbf{r}} u\right\}, & Y_{i}^{\mathbf{r}}:=Y_{i} \quad\left(Y_{i} \text { n.c. }\right) .
\end{array}
$$

For computational inductively and coinductively defined predicates,

$$
\left(J_{\vec{P}}\right)^{\mathbf{r}}:=\left\{u, \vec{x} \mid J_{\vec{P} \mathbf{r}}^{\mathrm{r}} u \vec{x}\right\}, \quad\left({ }^{\mathrm{C}} J_{\vec{P}}\right)^{\mathbf{r}}:=\left\{u,\left.\vec{x}\right|^{\mathrm{co}} J_{\vec{P} \mathbf{r}}^{\mathrm{r}} u \vec{x}\right\} .
$$

For non-computational inductively and coinductively defined predicates,

$$
\left(J_{\vec{P}}\right)^{\mathrm{r}}:=J_{\vec{P}}, \quad\left({ }^{\mathrm{c}} J_{\vec{P}}\right)^{\mathrm{r}}:={ }^{\mathrm{c} \circ} J_{\vec{P}}
$$

For one-clause defined non-computational inductively defined predicates,

$$
\left(J_{\vec{P}}\right)^{\mathbf{r}}:=J_{\left(\exists_{x}^{u}\left(P_{i}^{\mathbf{r}} x\right)\right)_{i<n}}
$$

We can write $u \mathbf{r} A_{\vec{P}}$ instead of $A_{\vec{P} \mathbf{r}}^{\mathbf{r}} u$.
If $P$ is a predicate variable, $P^{\mathbf{r}}$ is same as $P^{*}$ from the above definition. Invariant formulas are defined as follows.

Definition 2.5.22 (Invariant formulas and predicates). A formula $A$ and a predicate $P$ are invariant if $A \leftrightarrow \exists_{x}\left(A^{\mathbf{r}} x\right)$ and $P \vec{t} \leftrightarrow \exists_{x}\left(P^{\mathbf{r}} x \vec{t}\right)$ for any $\vec{t}$ are derivable in TCF, respectively.

The inductive and coinductive predicates with the superscript $\mathbf{r}$, namely, $I^{\mathbf{r}}$, are called witnessing predicates. For each an inductively (or coinductively) defined predicate $J$, we define the n.c. predicate $J^{\mathbf{r}}$, the witnessing predicate of $J$. Suppose that the arity of $J$ is $(\vec{\tau})$, then the arity of $J^{\mathrm{r}}$ is $\left(\iota_{J}, \vec{\tau}\right)$. We define $J^{\mathbf{r}}$ as a non-computational inductive (or coinductive) predicate. By means of them, the notion of realizability can be internalized in the language of TCF.

Definition 2.5.23 (Witnessing predicates). Suppose that $I_{\vec{Y}}=\mu_{X}(\vec{K})$ is an inductive predicate of arity $(\vec{\tau})$, where $Y_{i}$ is of arity $\left(\vec{\sigma}_{i}\right)$. Let $\iota$ be the associated algebra of $I_{\vec{\gamma}}$. Assume predicate variables $\vec{Y}^{*}$ such that $Y_{i}^{*}$ is of arity $\left(\tau\left(Y_{i}\right), \vec{\sigma}_{i}\right)$. Let $C_{i}$ be the $i$-th constructor of $\iota$. Let $X^{*}$ be a predicate variable of arity $(\iota, \vec{\tau})$ and $K_{i}^{*}$ be a formula $C_{i} \mathbf{r} K_{i}$ with replacing each occurrence of $X^{\mathbf{r}}$ by $X^{*}$. The witnessing predicate $I_{\vec{Y}^{\mathbf{r}}}^{\mathrm{r}}$ is defined to be an n.c. inductive
predicate $\mu_{X^{*}}^{\text {nc }}\left(\vec{K}^{*}\right)$ of arity $(\iota, \vec{\tau})$. Suppose that $K_{i}$ is of the form $\forall_{\vec{x}_{i}}\left(\left(A_{i \nu}(X)\right)_{\nu<n_{i}} \rightarrow X \vec{t}_{i}\right)$. The $i$-th introduction axiom of $I_{\vec{Y} \mathbf{r}}^{\mathrm{r}}$ is

$$
\forall_{\vec{x}_{i}, \vec{u}_{i}}\left(\left(A_{i \nu}^{\mathrm{r}}\left(I_{\overrightarrow{Y_{\mathbf{r}}}}^{\mathrm{r}}\right) u_{i \nu}\right)_{\nu<n_{i}} \rightarrow I_{\vec{Y}_{\mathbf{r}}^{\mathbf{r}}}^{\mathrm{r}}\left(C_{i} \vec{x}_{i} \vec{u}_{i}, \vec{t}_{i}\right)\right) \quad\left(I^{\mathbf{r}}\right)_{i}^{+}
$$

where

1. $u_{i \nu}$ occurs if $A_{i \nu}$ is c.r., and it appears as an argument of $C_{i}$ if $A_{i \nu}$ is followed by $\rightarrow^{\mathrm{c}}$,
2. $x_{i i^{\prime}}$ with $\forall^{c}$ appears as an argument of $C_{i}$.

Let $P$ be a predicate variable of the same arity of $I_{\vec{Y} \mathbf{r}}^{\mathrm{r}}$. Recall that $P$ has to be instantiated by a non-computational predicate. The elimination axiom of $I_{\vec{Y}^{\mathbf{r}}}^{\mathrm{r}}$ is as follows.

$$
\begin{equation*}
\forall_{\vec{x}, u}\left(I_{\vec{Y} \mathrm{r}}^{\mathrm{r}} u \vec{x} \rightarrow\left(\forall_{\vec{x}_{i}, \vec{u}_{i}}\left(\left(A_{i \nu}^{\mathrm{r}}\left(I_{\vec{Y}_{\mathrm{r}}^{\mathrm{r}}}^{\mathrm{r}} \cap^{\mathrm{u}} P\right) u_{i \nu}\right)_{\nu<n_{i}} \rightarrow P\left(C_{i} \vec{u}_{i}, \vec{t}_{i}\right)\right)\right)_{i<k} \rightarrow P u \vec{x}\right) \tag{r}
\end{equation*}
$$

Recall that $\cap^{\mathrm{u}}$ is defined in Example 2.5.13.
Suppose that ${ }^{\text {co }} I_{\vec{Y}}$ is the companion predicate of $I_{\vec{Y}}$ above. The witnessing predicate ${ }^{\mathrm{co}} I_{\vec{Y} \mathrm{r}}^{\mathrm{r}}=\nu_{X^{*}}^{\mathrm{nc}}\left(\overrightarrow{K^{\mathbf{r}}}\right)$ of ${ }^{\mathrm{co}} I_{\vec{Y}}$ is an n.c. coinductive predicate of arity $(\iota, \vec{\tau})$. Let $\vec{v}$ be fresh variables of the same length of $\vec{y}$ and $k$ be the length of $\vec{K}^{\mathbf{r}}$. Let $A_{i}^{*}\left(X^{*}\right)$ be $\exists_{\overrightarrow{y_{i}}, \overrightarrow{v_{i}}}^{\mathrm{u}}\left(\bigwedge_{\nu<n_{i}}^{\mathrm{nc}}\left(A_{i \nu}^{\mathbf{r}}\left(X^{*}\right) v_{i \nu}\right) \wedge\right.$ $\bigwedge \vec{E} \wedge \mathcal{D} u$ eqd $\left.\operatorname{in}_{i}^{k}\left(\operatorname{pair} \vec{v}_{i}\right)\right)$, where $v_{i \nu}$ is not there if $A_{i \nu}$ is n.c. The closure axiom of ${ }^{\text {co }} I_{\vec{Y}^{\mathrm{r}}}^{\mathrm{r}}$ is

$$
\begin{equation*}
\forall_{\vec{x}, u}\left({ }^{(\mathrm{Co}} I_{\vec{Y} \mathbf{r}}^{\mathrm{r}} u \vec{x} \rightarrow \bigvee_{i<k}^{\mathrm{nc}} A_{i}^{*}\left({ }^{\mathrm{co}} I_{\vec{Y} \mathbf{r}}^{\mathrm{r}} \mathrm{r}\right)\right) \tag{}
\end{equation*}
$$

Let $P$ be a non-computational predicate variable of the same arity of ${ }^{c o}{ }_{\vec{Y}} \mathrm{r}$. The greatest-fixed-point axiom of ${ }^{\text {co }} I_{\vec{Y}^{\mathrm{r}}}^{\mathrm{r}}$ is

$$
\begin{equation*}
\forall_{\vec{x}, u}\left(P u \vec{x} \rightarrow \forall_{\vec{x}, u}\left(P u \vec{x} \rightarrow \bigvee_{i<k}^{\mathrm{nc}} A_{i}^{*}\left({ }^{\mathrm{co}} I_{\vec{Y} \mathbf{r}}^{\mathrm{r}} \cup^{\mathrm{nc}} P\right)\right) \rightarrow{ }^{\mathrm{co}} I_{\vec{Y} \mathbf{r}}^{\mathrm{r}} u \vec{x}\right), \tag{}
\end{equation*}
$$

where $\cup^{\text {nc }}$ is given in Example 2.5.10.
We give some examples of witnessing predicates.
Example 2.5.24 (Witnessing predicates of conjunction). Let $A$ and $B$ are predicate variables of arities $(\alpha)$ and $(\beta)$, respectively. Let variables $a$ be ranging over $\alpha, b$ over $\beta, w$ over $\alpha \times \beta$. We define the witnessing predicates of the conjunctions, namely, the witnessing versions of Example 2.5.3.

$$
\begin{aligned}
& A\left(\wedge^{\mathrm{d}}\right)^{\mathbf{r}} B:=\mu_{X}^{\mathrm{nc}}\left(\forall_{a, b}\left(A a \rightarrow^{\mathrm{nc}} B b \rightarrow^{\mathrm{nc}} X\langle a, b\rangle\right)\right), \\
& A\left(\wedge^{\mathrm{1}}\right)^{\mathbf{r}} B:=\mu_{X}^{\mathrm{nc}}\left(\forall_{a, b}\left(A a \rightarrow^{\mathrm{nc}} B b \rightarrow^{\mathrm{nc}} X a\right)\right), \\
& A\left(\wedge^{\mathrm{r}}\right)^{\mathbf{r}} B:=\mu_{X}^{\mathrm{nc}}\left(\forall_{a, b}\left(A a \rightarrow^{\mathrm{nc}} B b \rightarrow^{\mathrm{nc}} X b\right)\right) .
\end{aligned}
$$

The introduction and elimination axioms are

$$
\begin{array}{ll}
\forall_{a, b}\left(A a \rightarrow B b \rightarrow\left(A\left(\wedge^{\mathrm{d}}\right)^{\mathbf{r}} B\right)\langle a, b\rangle\right) & \left(\left(\wedge^{\mathrm{d}}\right)^{\mathbf{r}}\right)^{+} \\
\forall_{w}\left(\left(A\left(\wedge^{\mathrm{d}}\right)^{\mathbf{r}} B\right) w \rightarrow \forall_{a, b}(A a \rightarrow B b \rightarrow P\langle a, b\rangle) \rightarrow P w\right) & \left(\left(\wedge^{\mathrm{d}}\right)^{\mathbf{r}}\right)^{-} \\
\forall_{a, b}\left(A a \rightarrow B b \rightarrow\left(A\left(\wedge^{\mathrm{l}}\right)^{\mathbf{r}} B\right) a\right) & \left(\left(\wedge^{\mathrm{l}}\right)^{\mathbf{r}}\right)^{+} \\
\forall_{a}\left(\left(A\left(\wedge^{\mathrm{l}}\right)^{\mathbf{r}} B\right) a \rightarrow \forall_{a, b}(A a \rightarrow B b \rightarrow P a) \rightarrow P a\right) & \left(\left(\wedge^{\mathrm{l}}\right)^{\mathbf{r}}\right)^{-} \\
\forall_{a, b}\left(A a \rightarrow B b \rightarrow\left(A\left(\wedge^{\mathrm{r}}\right)^{\mathbf{r}} B\right) b\right) & \left(\left(\wedge^{\mathrm{r}}\right)^{\mathbf{r}}\right)^{+} \\
\forall_{b}\left(\left(A\left(\wedge^{\mathrm{r}}\right)^{\mathbf{r}} B\right) b \rightarrow \forall_{a, b}(A a \rightarrow B b \rightarrow P b) \rightarrow P b\right) . & \left(\left(\wedge^{\mathrm{r}}\right)^{\mathbf{r}}\right)^{-}
\end{array}
$$

Example 2.5.25 (Witnessing predicates of disjunction). Let $P, A$ and $B$ be predicate variables of arities ()$,(\alpha)$ and $(\beta)$, respectively. We define the witnessing predicates of the decorated disjunctions.

$$
\begin{aligned}
& A\left(\vee^{\mathrm{d}}\right)^{\mathbf{r}} B:=\mu_{X}^{\mathrm{nc}}\left(\forall_{a}(A a \rightarrow X(\operatorname{lnL} a)), \forall_{b}(B b \rightarrow X(\operatorname{lnR} b))\right), \\
& A\left(\vee^{\mathrm{l}}\right)^{\mathbf{r}} P:=\mu_{X}^{\mathrm{nc}}\left(\forall_{a}(A a \rightarrow X(\mathrm{JustL} a)), P \rightarrow X \text { NoneR }\right), \\
& P\left(\vee^{\mathrm{r}}\right)^{\mathbf{r}} B:=\mu_{X}^{\mathrm{nc}}\left(P \rightarrow X \text { None }, \forall_{b}(B b \rightarrow X(\text { Just } b))\right), \\
& P_{0}\left(\vee^{\mathrm{u}}\right)^{\mathbf{r}} P_{1}:=\mu_{X}^{\mathrm{nc}}\left(P_{0} \rightarrow X \mathrm{~T}, P_{1} \rightarrow X \mathrm{~F}\right) .
\end{aligned}
$$

The introduction and elimination axioms are as follows.

$$
\begin{aligned}
& \forall_{a}\left(A a \rightarrow\left(A\left(\mathrm{~V}^{\mathrm{d}}\right)^{\mathbf{r}} B\right)(\operatorname{lnL} a)\right) \quad\left(\left(\mathrm{V}^{\mathrm{d}}\right)^{\mathbf{r}}\right)_{0}^{+} \\
& \forall_{b}\left(B b \rightarrow\left(A\left(\vee^{\mathrm{d}}\right)^{\mathbf{r}} B\right)(\operatorname{lnR} b)\right) \quad\left(\left(\mathrm{V}^{\mathrm{d}}\right)^{\mathbf{r}}\right)_{1}^{+} \\
& \forall_{x}\left(\left(A\left(\vee^{\mathrm{d}}\right)^{\mathbf{r}} B\right) x \rightarrow \forall_{a}(A a \rightarrow Q(\operatorname{lnL} a)) \rightarrow \forall_{b}(B b \rightarrow Q(\operatorname{lnR} b)) \rightarrow Q x\right) \quad\left(\left(\mathrm{V}^{\mathrm{d}}\right)^{\mathbf{r}}\right)^{-} \\
& \forall_{a}\left(A a \rightarrow\left(A\left(\vee^{l}\right)^{\mathbf{r}} P\right)(\mathrm{JustL} a)\right) \quad\left(\left(\vee^{\mathrm{l}}\right)^{\mathbf{r}}\right)_{0}^{+} \\
& P \rightarrow\left(A\left(\vee^{l}\right)^{\mathbf{r}} P\right) \text { NoneR } \quad\left(\left(\vee^{l}\right)^{\mathbf{r}}\right)_{1}^{+} \\
& \forall_{u}\left(\left(A\left(\vee^{1}\right)^{\mathbf{r}} P\right) u \rightarrow \forall_{a}(A a \rightarrow Q(\text { JustL } a)) \rightarrow(P \rightarrow Q \text { NoneR }) \rightarrow Q u\right) \quad\left(\left(\vee^{1}\right)^{\mathbf{r}}\right)^{-} \\
& P \rightarrow\left(P\left(\vee^{\mathrm{r}}\right)^{\mathbf{r}} B\right) \text { None } \quad\left(\left(\mathrm{V}^{\mathrm{r}}\right)^{\mathbf{r}}\right)_{0}^{+} \\
& \forall_{b}\left(B b \rightarrow\left(P\left(\vee^{\mathrm{r}}\right)^{\mathbf{r}} B\right)(\text { Just } b)\right) \\
& \forall_{v}\left(\left(P\left(\vee^{\mathrm{r}}\right)^{\mathbf{r}} B\right) v \rightarrow(P \rightarrow Q \text { None }) \rightarrow \forall_{b}(B b \rightarrow Q(\text { Just } b)) \rightarrow Q v\right) \quad\left(\left(\mathrm{V}^{\mathrm{r}}\right)^{\mathbf{r}}\right)^{-} \\
& P_{0} \rightarrow\left(P_{0}\left(\vee^{\mathrm{u}}\right)^{\mathbf{r}} P_{1}\right) \mathrm{T} \\
& P_{1} \rightarrow\left(P_{0}\left(V^{\mathrm{u}}\right)^{\mathbf{r}} P_{1}\right) \mathrm{F} \\
& \forall_{b}\left(\left(P_{0}\left(\vee^{\mathrm{u}}\right)^{\mathbf{r}} P_{1}\right) b \rightarrow\left(P_{0} \rightarrow Q \mathrm{~T}\right) \rightarrow\left(P_{1} \rightarrow Q \mathrm{~F}\right) \rightarrow Q b\right) \quad\left(\left(\mathrm{V}^{\mathrm{u}}\right)^{\mathbf{r}}\right)^{-}
\end{aligned}
$$

We introduce the notation of $\left(\cap^{\circ}\right)^{\mathbf{r}}$ and $\left(\cup^{\circ}\right)^{\mathbf{r}}$ for $\circ \in\{d, l, r, u\}$ in a similar way as we did for the decorated connectives.

Example 2.5.26 (Witnessing predicates of existential quantifiers). Let $x$ be a variable ranging over $\alpha, v$ ranging over $\tau$, and $w$ ranging over $\alpha \times \tau$. Also let $Y$ be a predicate variable of arity $(\tau, \alpha)$. We define $\operatorname{ExD}_{Y}^{\mathrm{r}}, \operatorname{ExL}_{Y}^{\mathrm{r}}$, and $\operatorname{ExR}_{Y}^{\mathrm{r}}$ of the arities $(\alpha, \tau),(\alpha)$, and $(\tau)$, respectively.

$$
\begin{aligned}
& \operatorname{ExD}_{Y}^{\mathrm{r}}:=\mu_{X}^{\mathrm{nc}}\left(\forall_{x, v}^{\mathrm{nc}}\left(Y v x \rightarrow^{\mathrm{nc}} X\langle x, v\rangle\right)\right), \\
& \operatorname{ExL}_{Y}^{\mathrm{r}}:=\mu_{X}^{\mathrm{nc}}\left(\forall_{x, v}^{\mathrm{nc}}\left(Y v x \rightarrow \rightarrow^{\mathrm{nc}} X x\right)\right), \\
& \operatorname{ExR}_{Y}^{\mathrm{r}}:=\mu_{X}^{\mathrm{nc}}\left(\forall_{x, v}^{\mathrm{nc}}\left(Y v x \rightarrow^{\mathrm{nc}} X v\right)\right) .
\end{aligned}
$$

The introduction and elimination axioms are

$$
\begin{array}{ll}
\forall_{x, v}\left(Y v x \rightarrow \operatorname{ExD}_{Y}^{\mathrm{r}}\langle x, v\rangle\right) & \left(\left(\exists^{\mathrm{d}}\right)^{\mathbf{r}}\right)^{+} \\
\forall_{w}\left(\operatorname{ExD}_{Y}^{\mathrm{r}} w \rightarrow \forall_{x, v}(Y v x \rightarrow P\langle x, v\rangle) \rightarrow P w\right) & \left(\left(\exists^{\mathrm{d}}\right)^{\mathbf{r}}\right)^{-} \\
\forall_{x, v}\left(Y v x \rightarrow \operatorname{ExL}_{Y}^{\mathrm{r}} x\right) & \left(\left(\exists^{\mathrm{l}}\right)^{\mathbf{r}}\right)^{+} \\
\forall_{x}\left(\operatorname{ExL}_{Y}^{\mathrm{r}} x \rightarrow \forall_{x, v}(Y v x \rightarrow P x) \rightarrow P x\right) & \left(\left(\exists^{\mathrm{l}} \mathbf{r}^{\mathbf{r}}\right)^{-}\right. \\
\forall_{x, v}\left(Y v x \rightarrow \operatorname{ExR}_{Y}^{\mathrm{r}} v\right) & \left(\left(\exists^{\mathrm{r}}\right)^{\mathbf{r}}\right)^{+} \\
\forall_{v}\left(\operatorname{ExR}_{Y}^{\mathrm{r}} v \rightarrow \forall_{x, v}(Y v x \rightarrow P v) \rightarrow P v\right) . & \left(\left(\exists^{\mathrm{r}}\right)^{\mathbf{r}}\right)^{-}
\end{array}
$$

For given formulas $\exists_{x}^{\circ} Q$ where $\circ \in\{\mathrm{d}, \mathrm{l}, \mathrm{r}\}$, we can also write $\left(\exists_{x}^{\circ}\right)^{\mathbf{r}} Q^{\mathbf{r}}$ for the corresponding witnessing predicates $\operatorname{ExD}_{Q^{\mathbf{r}}}^{\mathbf{r}}, \operatorname{ExL}_{Q^{\mathbf{r}}}^{\mathbf{r}}$, and $\operatorname{ExR}_{Q^{\mathbf{r}}}^{\mathbf{r}}$.

We define the term extraction algorithm et based on the realizability interpretation.
Definition 2.5.27 (Program extraction). For a proof $M$ of a formula $A$ we define a term et $(M)$ or $\varepsilon$ of type $\tau(A)$ or $\circ$ by induction on the construction of the proof $M$. If $\tau(A)=0$, $\operatorname{et}(M):=\varepsilon$. Otherwise,

$$
\begin{aligned}
& \operatorname{et}\left(u^{A}\right):=x_{u^{A}}^{\tau(A)} \text { where } x_{u^{A}} \text { is uniquely associated with } u^{A} \text {, } \\
& \operatorname{et}\left(I_{i}^{+}\right):=C_{i}, \quad \operatorname{et}\left(I^{-}\right):=\mathcal{R}_{\iota}^{\tau}, \\
& \operatorname{et}\left({ }^{\mathrm{Co}} I^{-}\right):=\mathcal{D}_{\iota}, \quad \operatorname{et}\left({ }^{\mathrm{Co}} I^{+}\right):={ }^{\mathrm{co}} \mathcal{R}_{\iota}^{\tau}, \\
& \operatorname{et}\left(\left(\lambda_{u^{A}} M^{B}\right)^{A \rightarrow{ }^{\mathrm{c}} B}\right):=\lambda_{x_{u}^{\tau(A)}}(\operatorname{et}(M)), \quad \operatorname{et}\left(\left(\lambda_{u^{A}} M^{B}\right)^{A \rightarrow{ }^{\mathrm{nc}} B}\right):=\operatorname{et}(M), \\
& \operatorname{et}\left(M^{A \rightarrow{ }^{\mathrm{c}} B} N^{A}\right):=\operatorname{et}(M) \operatorname{et}(N), \quad \operatorname{et}\left(M^{A \rightarrow{ }^{\mathrm{nc}} B} N^{A}\right):=\operatorname{et}(M) \text {, } \\
& \operatorname{et}\left(\left(\lambda_{x^{\rho}} M^{A}\right)^{\forall_{x}^{\mathrm{c}} A}\right):=\lambda_{x^{\rho}} \operatorname{et}(M), \quad \operatorname{et}\left(\left(\lambda_{x^{\rho}} M^{A}\right)^{\forall r n_{x}^{A}}\right):=\operatorname{et}(M) \text {, } \\
& \operatorname{et}\left(\left(M^{\forall_{x}^{c} A} r\right)^{A(r)}\right):=\operatorname{et}(M) r, \quad \operatorname{et}\left(\left(M^{\forall_{x}^{\mathrm{nc}} A} r\right)^{A(r)}\right):=\operatorname{et}(M),
\end{aligned}
$$

where $I$ and ${ }^{\text {co } I}$ are computational, $\iota:=\tau(I)=\tau\left({ }^{\mathrm{co}} I\right)$ and $\tau$ is determined by the type of the competitor predicate of $I^{-}$or ${ }^{{ }^{\text {co }} I^{+}}$. For a special non-computational predicate $I$, et $\left(I^{-}\right):=\mathrm{id}$.

Example 2.5.28 (Computational content of the identity lemma). We can prove a trivial statement $A \rightarrow A$ which we call the identity lemma. Proving it by assuming $A$ and using it to derive the goal, there is the computational content $\mathrm{Id}_{\alpha}$ extracted from this proof.

$$
\operatorname{Id}_{\alpha}: \alpha \rightarrow \alpha, \quad \operatorname{Id}_{\alpha} x \mapsto x
$$

Although this lemma has no logical use to prove a formula, we can use this lemma to fine tune the extracted program by switching block/unblock of the conversion rule. Assume formulas $A, B$ and $C$ and a proof $M$ of $A$. We prove $\left(A \rightarrow^{\mathrm{c}} B\right) \rightarrow^{\mathrm{c}}\left(A \rightarrow^{\mathrm{c}} C\right) \rightarrow^{\mathrm{c}} B \wedge^{\mathrm{d}} C$. Assume two premises. Asserting $A$, which is proven, and use the identity lemma to $A \rightarrow^{\mathrm{c}} B \wedge^{\mathrm{d}} C$. We assume $A$ and apply the assumptions to derive $B$ and $C$, then by $\left(\wedge^{\mathrm{d}}\right)^{+}$. The extracted program is normalized to be $\lambda_{f, g}\left(\operatorname{Id} \lambda_{u}\langle f u, g u\rangle \mathrm{P}\right)$, where P is the
normalized et $(M)$. When we prove straightforwardly without the identity lemma, the extracted program is normalized to be $\lambda_{f, g}\langle f \mathrm{P}, g \mathrm{P}\rangle$ which involves two times of separated normalization of et $(M)$. We introduce the notation of let-construction for Id in the following way: $\lambda_{f, g}($ let $u=\mathrm{P}$ in $\langle f u, g u\rangle)$.

A use of this technique is also found in Section 3.4.

### 2.5.3 Soundness Theorem

In this section we address the issue of the correctness of our program extraction. We prove the soundness theorem which claims that if there is a proof $M$ of a formula $A$, there is a term which provably realizes $A$ obtained by program extraction from $M$.

Theorem 2.5.29 (Soundness). Let $M$ be a proof of $A$ from assumptions $u_{i}^{B_{i}}$. We have a proof of et $(M) \mathbf{r} A$ from assumptions $x_{u_{i}} \mathbf{r} B_{i}$.

Proof. By induction on the structure of $M$.
Case $u: B$. Trivially, et $(u)=x_{u} \mathbf{r} B$.
Case $\left(\lambda_{u^{A}} M^{B}\right)^{A \rightarrow^{\mathrm{c}} B}$. We find a derivation of et $\left(\lambda_{u} M\right) \mathbf{r} A \rightarrow^{\mathrm{c}} B$, which is $\forall_{x}(x \mathbf{r} A \rightarrow$ $\left.\operatorname{et}(M)\left[x_{u} / x\right] \mathbf{r} B\right)$. By induction hypothesis, we have a derivation of et $(M) \mathbf{r} B$ from $x_{u} \mathbf{r} A$, hence by introduction rules of $\rightarrow$ and $\forall$.

Case $M^{A \rightarrow{ }^{c} B} N^{A}$. We find a derivation of $\operatorname{et}(M N) \mathbf{r} B$, i.e., et $(M) \operatorname{et}(N) \mathbf{r} B$. By induction hypothesis we have derivations of et $(M) \mathbf{r} A \rightarrow^{\mathrm{c}} B$, namely, $\forall_{x}(x \mathbf{r} A \rightarrow$ $\operatorname{et}(M) x \mathbf{r} B$ ) and et $(N) \mathbf{r} A$. The goal is derived by elimination rules of $\forall$ and $\rightarrow$.

Case $\left(\lambda_{x} M^{A}\right)^{\forall_{x}^{c} A}$. We find a derivation of et $\left(\lambda_{x} M\right) \mathbf{r} \forall_{x}^{c} A$, i.e., $\forall_{x}(\operatorname{et}(M) \mathbf{r} A)$. By induction hypothesis we have a derivation of $\operatorname{et}(M) \mathbf{r} A$, hence the goal by an introduction rule of $\forall$.

Case $M^{\forall_{x}^{c} A(x)} t$. We find a derivation of et $(M t) \mathbf{r} A(t)$. By induction hypothesis we have a derivation of et $(M) \mathbf{r} \forall_{x}^{c} A(x)$, i.e., $\forall_{x}(\operatorname{et}(M) x \mathbf{r} A(x))$. Since the goal is same as et $(M) t \mathbf{r} A(t)$, we use the elimination rule of $\forall$.

Case $\left(\lambda_{u^{A}} M^{B}\right)^{A \rightarrow^{\mathrm{nc}} B}$. We find a derivation of et $\left(\lambda_{u} M\right) \mathbf{r} A \rightarrow^{\mathrm{nc}} B$, which is $\forall_{y}(y \mathbf{r} A \rightarrow$ $\operatorname{et}(M) \mathbf{r} B)$. By induction hypothesis, we have a derivation of et $(M) \mathbf{r} B$ from $y \mathbf{r} A$, hence by introduction rules of $\rightarrow$ and $\forall$.

Case $M^{A \rightarrow{ }^{\mathrm{nc}} B} N^{A}$. We find a derivation of $\operatorname{et}(M N) \mathbf{r} B$, i.e., et $(M) \mathbf{r} B$. By induction hypothesis we have derivations of $\operatorname{et}(M) \mathbf{r} A \rightarrow{ }^{\text {nc }} B$, namely, $\forall_{y}(y \mathbf{r} A \rightarrow \operatorname{et}(M) \mathbf{r} B)$ and et $(N) \mathbf{r} A$. The goal is derived by elimination rules of $\forall$ and $\rightarrow$.

Case $\left(\lambda_{x} M^{A}\right)^{\forall_{x}^{\mathrm{nc}} A}$. We find a derivation of et $\left(\lambda_{x} M\right) \mathbf{r} \forall_{x}^{\mathrm{nc}} A$, i.e., $\forall_{x}(\operatorname{et}(M) \mathbf{r} A)$. By induction hypothesis we have a derivation of $\operatorname{et}(M) \mathbf{r} A$, hence the goal by an introduction rule of $\forall$.

Case $M^{\forall_{x}^{\mathrm{nc}} A(x)} t$. We find a derivation of et $(M t) \mathbf{r} A(t)$, i.e., et $(M) \mathbf{r} A(t)$. By induction hypothesis we have a derivation of et $(M) \mathbf{r} \forall_{x}^{\mathrm{nc}} A(x)$, i.e., $\forall_{x}(\operatorname{et}(M) \mathbf{r} A(x))$, hence the goal by using an elimination rule of $\forall$.

If the last inference is the monotonicity, Lemma 2.3.23, we can use Lemma 2.5.30. Otherwise the last inference is an axiom of an inductively or coinductively defined predicate.

If it is $I^{+}, I^{-}$, ${ }^{\text {co }} I^{-}$or ${ }^{\text {co }} I^{+}$of computational predicate, use Lemma 2.5.31. If it is $I^{+}$or $I^{-}$ of non-computational inductive predicate, use Lemma 2.5.32. If it is $I^{+}$or $I^{-}$of special non-computational inductive predicate, use Lemma 2.5.33.

We start proving the case of constants. First, we consider the map operator which appears in the conversion rule of recursion and corecursion operators. A map operator is in fact a realizer of a monotonicity formula, which is exactly the statement of Lemma 2.3.23.

Lemma 2.5.30 (Soundness: the monotonicity formula). Let $A_{\vec{X}}$ be a formula, $n$ be a fixed natural number, $P_{i}, Q_{i}$ be predicates for $i<n$ where $P_{i}$ and $Q_{i}$ are of arity $\left(\vec{\delta}_{i}\right), \sigma_{i}=\tau\left(P_{i}\right)$ and $\tau_{i}=\tau\left(Q_{i}\right)$, and $\rho(\vec{\alpha})$ be $\tau\left(A_{\vec{X}}\right)$ where $\alpha_{i}=\tau\left(X_{i}\right)$. Suppose that $u$ is a variable ranging over $\rho_{\vec{\alpha}}$, which stands for $\rho(\vec{\alpha})$, v ranging over some of $\tau_{i}$ and $w_{i}$ ranging over $\tau_{i} \rightarrow \sigma_{i}$. The map operator $\mathcal{M}_{\lambda_{\vec{\alpha}} \rho(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{F}}$ is a realizer of the monotonicity formula, namely,

$$
\mathcal{M}_{\lambda_{\vec{\alpha}} \rho(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{\tau}} \mathbf{r} \forall_{\vec{x}}\left(A_{\vec{P}} \rightarrow\left(\forall_{\vec{x}}\left(P_{i} \vec{x} \rightarrow Q_{i} \vec{x}\right)\right)_{i<n} \rightarrow A_{\vec{Q}}\right) .
$$

Proof. We prove the claim by simultaneous induction on the structure of $A_{\vec{x}}$.
Case $A_{\vec{X}}=\forall_{\tilde{x}} \tilde{A}_{\vec{X}}$. Assume the induction hypothesis with a parameter variable $\tilde{x}$,

$$
\forall_{\vec{x}, u}\left(\tilde{A}_{\vec{P} \mathbf{r}}^{\mathrm{r}} u \rightarrow \forall_{\vec{w}}\left(\left(\forall_{\vec{x}, v}\left(P_{i}^{\mathrm{r}} v \vec{x} \rightarrow Q_{i}^{\mathrm{r}}\left(w_{i} v\right) \vec{x}\right)\right)_{i<n} \rightarrow \tilde{A}_{\vec{Q}^{\mathbf{r}}}^{\mathrm{r}}\left(\mathcal{M}_{\lambda_{\vec{\alpha}} \rho_{\vec{\alpha}}}^{\vec{\sigma} \rightarrow \vec{\sigma}} u \vec{w}\right)\right)\right) .
$$

We prove

Let $\vec{x}$ and $u$ be given and assume $\forall_{\tilde{x}}\left(\tilde{A}_{\overrightarrow{P r}}^{\mathrm{r}} u\right)$, let $\vec{w}$ be given and assume $\forall_{\vec{x}, v}\left(P_{i}^{\mathbf{r}} v \vec{x} \rightarrow\right.$ $\left.Q_{i}^{\mathrm{r}}\left(w_{i} v\right) \vec{x}\right)$ for each $i<n$, and also let $\tilde{x}$ be given. The assumption $\forall_{\tilde{x}}\left(\tilde{A}_{\vec{P} \mathrm{r}}^{\mathrm{r}} u\right)$ implies $\tilde{A}_{\vec{P} \mathbf{r}}^{\mathrm{r}} u$. We prove $\tilde{A}_{\vec{Q}^{\mathbf{r}}}^{\mathrm{r}}\left(\mathcal{M}_{\lambda_{\vec{\alpha}} \rho_{\vec{\alpha}}}^{\vec{\tau} \rightarrow \vec{w})} u \vec{w}\right)$ by using the i.h. with replacing the free variable $\tilde{x}$ in i.h. as necessary.

Case $A_{\vec{X}}=B \rightarrow \tilde{A}_{\vec{X}}$. Assume $\rho_{\vec{\alpha}}=\tau\left(B \rightarrow \tilde{A}_{\vec{X}}\right)=\pi \rightarrow \tilde{\rho}_{\vec{\alpha}}$. Notice that $\vec{\alpha}$, which came from the free occurrences of $\vec{X}$, don't occur in $\pi$ due to the condition of the formula construction of $B$. Assume the induction hypothesis

$$
\forall_{\vec{x}, u}\left(\tilde{A}_{\overrightarrow{\mathrm{P}}}^{\mathrm{r}} u \rightarrow \forall_{\vec{w}}\left(\left(\forall_{\vec{x}, v}\left(P_{i}^{\mathbf{r}} v \vec{x} \rightarrow Q_{i}^{\mathrm{r}}\left(w_{i} v\right) \vec{x}\right)\right)_{i<n} \rightarrow \tilde{A}_{\vec{Q}^{\mathbf{r}}}^{\mathrm{r}}\left(\mathcal{M}_{\lambda_{\vec{\alpha}} \tilde{\tilde{\rho}}_{\vec{\alpha}}}^{\vec{\sigma} \rightarrow \vec{w}} u \vec{w}\right)\right)\right),
$$

and we prove

$$
\begin{aligned}
& \forall_{\vec{x}, u}\left(\forall_{y}\left(B^{\mathbf{r}} y \rightarrow \tilde{A}_{\vec{P} \mathbf{r}}^{\mathbf{r}}(u y)\right) \rightarrow \forall_{\vec{w}}( \right.\left(\forall_{\vec{x}, v}\left(P_{i}^{\mathbf{r}} v \vec{x} \rightarrow Q_{i}^{\mathbf{r}}\left(w_{i} v\right) \vec{x}\right)\right)_{i<n} \rightarrow \\
&\left.\left.\forall_{y}\left(B^{\mathbf{r}} y \rightarrow \tilde{A}_{\vec{Q}^{\mathbf{r}}}^{\mathrm{r}}\left(\mathcal{M}_{\lambda_{\vec{\alpha}}\left(\pi \rightarrow \vec{r} \rightarrow \tilde{\rho}_{\vec{\alpha}}\right)}^{\overrightarrow{\vec{x}}} u \vec{w} y\right)\right)\right)\right) .
\end{aligned}
$$

Let $\vec{x}$ and $u$ be given and assume $\forall_{y}\left(B^{\mathbf{r}} y \rightarrow \tilde{A}_{\vec{P} \mathbf{r}}^{\mathrm{r}}(u y)\right), \vec{w}$ be given and assume $\forall_{\vec{x}, v}\left(P_{i}^{\mathbf{r}} v \vec{x} \rightarrow\right.$ $\left.Q_{\tilde{i}}^{\mathbf{r}}\left(w_{i} v\right) \vec{x}\right)$ for each $i<n$, and also let $y$ be given and assume $B^{\mathbf{r}} y$. We prove that
 holds, hence the i.h. implies the goal.

Case $A_{\vec{X}}=\tilde{P} \vec{r}$ where $\tilde{P}$ is a predicate. We proceed by induction on $\tilde{P}$.
Side case $\tilde{P}$ is a predicate variable. The conclusion $\tilde{P}^{\mathbf{r}}\left(\mathcal{M}_{\lambda_{\vec{\alpha}} \rho}^{\vec{\sigma} \rightarrow \vec{\tau}} u \vec{w}\right) \vec{r}$ is same as the first premise $\tilde{P}^{\mathbf{r}} u \vec{r}$, because $\mathcal{M}_{\tilde{\sim}}^{\overrightarrow{A_{\vec{\alpha}} \rho} \rightarrow \vec{\tau}} u \vec{w} \mapsto u$.

Side case $\tilde{P}=\{\vec{z} \mid \tilde{A}\}$ where $\tilde{A}$ is a formula. Assume the following side induction hypothesis for $\tilde{A}$.

$$
\forall_{u}\left(\tilde{A}_{\vec{P} \mathbf{r}}^{\mathrm{r}} u \rightarrow \forall_{\vec{w}}\left(\left(\forall_{\vec{x}, v}\left(P_{i}^{\mathbf{r}} v \vec{x} \rightarrow Q_{i}^{\mathbf{r}}\left(w_{i} v\right) \vec{x}\right)\right)_{i<n} \rightarrow \tilde{A}_{\vec{Q}^{\mathbf{r}}}^{\mathrm{r}}\left(\mathcal{M}_{\lambda_{\lambda_{\alpha}} \overrightarrow{\rho_{\vec{\alpha}}}}^{\overrightarrow{\mathrm{F}}} u \vec{w}\right)\right)\right) .
$$

Since $\vec{z}$ are parameters of this i.h., the goal holds by replacing variables.
Side case $\tilde{P}=J\left(\vec{R}_{\vec{X}}\right)$ where $J\left(\vec{X}^{\prime}\right)$ is an inductively defined predicate $\mu_{Z}(\vec{K})$ where $K_{i}=\forall_{\vec{x}}\left(\left(\tilde{A}_{i \nu}\left(\vec{X}^{\prime}, Z\right)\right)_{\nu<n_{i}} \rightarrow Z \vec{t}\right)$ with some decoration, and $\vec{R}$ is a list of predicates of the same length of $\vec{X}^{\prime}$. Then, $\rho_{\vec{\alpha}}=\iota_{\vec{\pi}(\vec{\alpha})}$ where $\iota_{\vec{\beta}}$ is defined to be an algebra $\tau\left(J_{\vec{X}^{\prime}}\right)=\mu_{\xi}(\vec{\kappa})$ where $\kappa_{i}=\left(\rho_{i \nu}(\vec{\beta}, \xi)\right)_{\nu<n_{i}} \rightarrow \xi$ and $\pi_{i}(\vec{\alpha})$ is $\tau\left(R_{i}(\vec{X})\right)$. We prove the following formula

Let $\vec{x}$ and $u$ be given and assume $J_{\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathrm{r}}\right)}^{\mathrm{r}} u \vec{x}$. Also let $\vec{w}$ of type $\vec{\sigma} \rightarrow \vec{\tau}$ be given and assume $\forall_{\vec{x}, v}\left(P_{i}^{\mathbf{r}} v \vec{x} \rightarrow Q_{i}^{\mathbf{r}}\left(w_{i} v\right) \vec{x}\right)$ for each $i<n$. The goal is $J_{\vec{R}^{\mathrm{r}}\left(\vec{Q}^{\mathrm{r}}\right)}^{\mathrm{r}}\left(\mathcal{M}_{\lambda_{\alpha} \iota(\vec{\pi}(\vec{a}))}^{\vec{\sigma} \rightarrow \vec{w}} u \vec{w}\right) \vec{x}$, which is abbreviated as $R u \vec{x}$ for fixed $\vec{w}$. By means of $\left(J^{\mathbf{r}}\right)^{-}$for $J_{\vec{R}^{\mathbf{r}}(\overrightarrow{P r})}^{\mathrm{r}} u \vec{x}$, it suffices to prove each step formula of the form

$$
\forall_{\vec{x}, \vec{u}}\left(\left(\tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathbf{r}}\right), J_{\vec{R}^{\mathbf{r}}\left(\vec{P}^{\mathbf{r}}\right)}^{\mathrm{r}} \cap^{\mathrm{u}} R\right) u_{\nu}\right)_{\nu<n_{i}} \rightarrow R\left(C_{i}^{\vec{\pi}(\vec{\sigma})} \vec{x} \vec{u}, \vec{x}\right)\right),
$$

where $C_{i}^{\vec{\beta}}$ is the corresponding constructor of the algebra $\iota_{\vec{\beta}}$. We let $\vec{x}$ and $\vec{u}$ be given and assume $\tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathbf{r}}\right), J_{\vec{R}(\vec{P} \mathbf{r})}^{\mathrm{r}} \cap^{\mathrm{u}} R\right) u_{\nu}$ for each $\nu<n_{i}$. Let $f_{i}:=\mathcal{M}_{\lambda_{\vec{\alpha}} \pi_{i}(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{w}} \cdot \vec{w}$. Applying the conversion rule of $\mathcal{M}_{\lambda_{\alpha} \iota(\vec{\tau}(\vec{\alpha}))}^{\vec{\sigma} \rightarrow \overrightarrow{\vec{c}})}$, the goal is same as

$$
J_{\vec{R}^{\mathrm{r}}\left(\vec{Q}^{\mathrm{r}}\right)}^{\mathrm{r}}\left(C_{i}^{\vec{\pi}(\vec{\tau})} \vec{x}\left(\mathcal{M}_{\lambda_{\vec{\beta}, \gamma} \gamma_{i \nu}(\vec{\beta}, \gamma)}^{\vec{\pi}(\vec{\pi}), \iota_{\vec{\sigma}(\vec{r})} \rightarrow \overrightarrow{\vec{r}}\left(\overrightarrow{)}, \iota_{\vec{\pi}(\vec{\tau})}\right.} u_{\nu} \vec{f}\left(\mathcal{M}_{\iota}^{\vec{\pi}(\vec{\sigma}) \rightarrow \vec{\pi}(\vec{\tau})} \cdot \vec{f}\right)\right)_{\nu<n_{i}}, \vec{x}\right) .
$$

It suffices to show $\tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{Q}^{\mathbf{r}}\right), J_{\vec{R}^{\mathrm{r}}}^{\mathrm{r}} \vec{Q}^{\mathrm{r}}\right)\left(\mathcal{M}_{\lambda_{\vec{\beta}, \gamma} \rho_{i \nu}(\vec{\beta}, \gamma)}^{\vec{\pi}(\vec{\sigma}), \iota_{\vec{\pi}(\vec{\sigma})} \rightarrow \vec{\pi}(\vec{\tau}), \iota_{\vec{\pi}(\vec{\tau})}} u_{\nu} \vec{f}\left(\mathcal{M}_{\iota}^{\vec{\pi}(\vec{\tau}) \rightarrow \vec{\pi}(\vec{\sigma})} \cdot \vec{f}\right)\right)$ for each $\nu<n_{i}$. Since $\tilde{A}_{i \nu}(\vec{X}, Z)$ is a formula of sub construction, we can use the following induction hypothesis to proceed.

$$
\begin{aligned}
& \forall_{\vec{x}, u}\left(\tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathbf{r}}\right), J_{\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathbf{r}}\right)}^{\mathrm{r}} \cap^{\mathrm{u}} R\right) u \rightarrow\right. \\
& \forall_{\vec{f}, g}\left(\left(\forall_{\vec{x}, v}\left(R_{i}^{\mathbf{r}}\left(\vec{P}^{\mathbf{r}}\right) v \vec{x} \rightarrow R_{i}^{\mathbf{r}}\left(\vec{Q}^{\mathbf{r}}\right)\left(f_{i} v, \vec{x}\right)\right)\right)_{i<n} \rightarrow \forall_{\vec{x}, v}\left(\left(J_{\vec{R}^{\mathbf{r}}\left(\overrightarrow{P^{\mathbf{r}}}\right)}^{\mathrm{r}} \cap^{\mathrm{u}} R\right) v \vec{x} \rightarrow J_{\vec{R}^{\mathbf{r}}\left(\vec{Q}^{\mathbf{r}}\right)}^{\mathrm{r}}(g v, \vec{x})\right)\right.
\end{aligned}
$$

We already have the first premise in the assumption. The second ones are straightforward by induction hypotheses $\forall_{\vec{x}, v}\left(R_{i}^{\mathbf{r}}\left(\vec{P}^{\mathbf{r}}\right) v \vec{x} \rightarrow \forall_{\vec{w}}\left(\left(\forall_{\vec{x}, v}\left(P_{i}^{\mathbf{r}} v \vec{x} \rightarrow Q_{i}^{\mathbf{r}}\left(w_{i} v, \vec{x}\right)\right)\right)_{i<n} \rightarrow\right.\right.$



Side case $\tilde{P}={ }^{c o} J(\vec{R}(\vec{P}))$ where ${ }^{c o} J\left(\vec{X}^{\prime}\right)$ is a coinductively defined predicate $\nu_{X}(\vec{K})$ where $K_{i}=\forall_{\vec{x}}\left(\left(\tilde{A}_{i \nu}\left(\vec{X}^{\prime}, Z\right)\right)_{\nu<n_{i}} \rightarrow Z \vec{t}\right)$, and $\vec{R}$ is a list of predicates. Then, $\rho_{\vec{\alpha}}=\iota_{\vec{\pi}(\vec{\alpha})}$ where $\iota_{\vec{\beta}}$ is defined to be an algebra $\tau\left({ }^{\text {co }} J\left(\vec{X}^{\prime}\right)\right)=\mu_{\xi}(\vec{\kappa})$ where $\kappa_{i}=\left(\rho_{i \nu}(\vec{\beta}, \xi)\right)_{\nu<n_{i}} \rightarrow \xi$, and $\pi_{i}(\vec{\alpha})$ is $\tau\left(R_{i}(\vec{X})\right)$. We prove the following formula

Let $\vec{x}$ and $u$ be given and assume $\left.{ }^{\operatorname{co}} \int_{\vec{R}^{\mathbf{r}}}^{\mathrm{r}} \vec{P}^{\mathbf{r}}\right)$. Also let $\vec{w}$ be given and assume $\forall_{\vec{x}, u}\left(P_{i}^{\mathbf{r}} u \vec{x} \rightarrow\right.$
 competitor predicate $R:=\left\{u, \vec{x} \mid \exists_{v}\left(u\right.\right.$ eqd $\left.\left.\mathcal{M}_{\lambda_{\vec{\alpha}} \vec{\pi}(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{w}} v \vec{w} \wedge^{\mathrm{co}} J_{\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathrm{r}}\right)}^{\mathrm{r}} v \vec{x}\right)\right\}$. It suffices to prove the costep formula

$$
\forall_{\vec{x}, u}\left(R u \vec{x} \rightarrow \bigvee_{i<k}^{\mathrm{nc}}\left(\exists_{\vec{y}, \vec{v}}^{\mathrm{u}}\left(\bigwedge_{\nu<n_{i}} \tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{Q}^{\mathbf{r}}\right), \mathcal{J o g}_{\vec{R}^{\mathrm{r}}\left(\vec{Q}^{\mathrm{r}}\right)}^{\mathrm{r}} \cup^{\mathrm{nc}} R\right) v_{\nu} \wedge \bigwedge_{i} \wedge u \text { eqd } C_{i}^{\vec{\pi}(\vec{\tau})} \vec{v}\right)\right)\right)
$$

Let $\vec{x}$ and $u$ be given and assume $R u \vec{x}$, which yields $v^{\prime}$ such that $u$ eqd $\mathcal{M}_{\lambda_{\vec{\alpha}} \iota \vec{\pi}(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{w}} v^{\prime} \vec{w}$ and ${ }^{\text {co }} J_{\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathrm{r}}\right)}^{\mathrm{r}} v^{\prime} \vec{x}$ hold. Applying $\left({ }^{\mathrm{co}} \mathcal{J}^{\mathbf{r}}\right)^{-}$to ${ }^{\text {co }}{\underset{\overrightarrow{R^{\mathrm{r}}}}{ }\left(\vec{P}^{\mathbf{r}}\right)}_{\mathrm{r}} v^{\prime} \vec{x}$, the following holds.

$$
\begin{equation*}
\bigvee_{i<k}^{\mathrm{nc}}\left(\exists_{\vec{y}, \vec{v}}^{\mathrm{u}}\left(\bigwedge_{\nu<n_{i}} \tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathbf{r}}\right),{ }^{\mathrm{co}_{\vec{R}^{\mathrm{r}}(\vec{P} \mathrm{r})}^{\mathrm{r}}}\right) v_{\nu} \wedge \bigwedge \vec{E}_{i} \wedge v^{\prime} \operatorname{eqd} C_{i}^{\vec{\pi}(\vec{\sigma})} \vec{v}\right)\right) \tag{2.1}
\end{equation*}
$$

We apply $\vee^{-}$for (2.1) to the goal, then it suffices to prove the following for each $i$. Here


$$
\begin{aligned}
& \forall_{\vec{x}, v^{\prime}}\left(\exists_{\vec{y}, \vec{v}}^{\mathrm{u}}\left(\bigwedge_{\nu<n_{i}} \tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathbf{r}}\right),{ }^{\mathrm{co}} J_{\vec{R}^{\mathbf{r}}(\vec{P} \mathbf{r})}^{\mathrm{r}}\right) v_{\nu} \wedge \bigwedge \vec{E}_{i} \wedge v^{\prime} \operatorname{eqd} C_{i}^{\vec{\pi}(\vec{\sigma})} \vec{v}\right) \rightarrow\right.
\end{aligned}
$$

Let $\vec{x}$ and $v^{\prime}$ be given and assume the premise. Using $\left(\exists^{\mathrm{u}}\right)^{-}$, there are $\vec{y}$ and $\vec{v}$ which satisfy the premise. Let $f_{j}$ be $\mathcal{M}_{\lambda_{\vec{\alpha}} \pi_{j}(\vec{\alpha})}^{\vec{\sigma} \rightarrow \vec{w}} \cdot \vec{w}$. We use to the goal $\vee_{i}^{+}$and $\left(\exists^{\mathrm{u}}\right)^{+}$with $\vec{y}$ and $\mathcal{M}_{\lambda_{\vec{\beta}, \gamma} \boldsymbol{\mu}^{\vec{\pi}}(\vec{\sigma}(\vec{\beta}, \gamma)}^{\vec{\beta}(\overrightarrow{)})} v_{\nu} \vec{f}\left(\mathcal{M}_{\iota}^{\vec{\pi}(\vec{\sigma}) \rightarrow \vec{\pi}(\vec{\tau})} \cdot \vec{f}\right)$ for each $\nu<n_{i}$. Then, it suffices to prove the following.

$$
\begin{aligned}
& \mathcal{M}_{\left.\lambda_{\vec{\alpha} \iota} \iota \vec{\pi}(\vec{\alpha})\right)}^{\vec{\sigma} \rightarrow \overrightarrow{\omega_{2}}}\left(C_{i}^{\vec{\pi}(\vec{\sigma})} \vec{v}\right) \vec{w} \text { eqd } C_{i}^{\vec{\pi}(\vec{\tau})}\left(\mathcal{M}_{\lambda_{\vec{\beta}, \gamma}, \iota_{i \nu}(\vec{\pi}, \gamma)}^{\vec{\pi}(\vec{\sigma}) \rightarrow \vec{\tau}(\vec{\tau}), \iota \vec{\pi}(\vec{\tau})} v_{\nu} \vec{f}\left(\mathcal{M}_{\iota}^{\vec{\pi}(\vec{\sigma}) \rightarrow \vec{\pi}(\vec{\tau})} \cdot \vec{f}\right)\right)_{\nu<n_{i}}, \\
& \bigwedge_{\nu<n_{i}} \tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathbf{r}}\right),{ }^{\mathrm{co}} J_{\vec{R}^{\mathrm{r}}(\vec{P} \mathrm{r})}^{\mathrm{r}}\right) v_{\nu} \rightarrow
\end{aligned}
$$

The former one is apparent by the conversion rule. For the latter one, we end up with proving

$\vec{f})$ ) for each $\nu<n_{i}$, by using $\wedge_{i}^{+}$and $\wedge^{-}$. We use the following induction hypothesis to prove it.

$$
\begin{aligned}
& \forall_{\vec{x}, v}\left(\tilde { A } _ { i \nu } ^ { \mathrm { r } } ( \vec { R } ^ { \mathbf { r } } ( \vec { P } ^ { \mathbf { r } } ) , { } ^ { \mathrm { c } O } \underset { \vec { R } ^ { \mathbf { r } } ( \vec { P } \mathbf { r } ) } { \mathbf { r } } ) v \rightarrow \forall _ { \vec { f } } \left(\left(\forall_{\vec{x}, v}\left(R_{i}^{\mathbf{r}}\left(\vec{P}^{\mathbf{r}}\right) v \vec{x} \rightarrow R_{i}^{\mathbf{r}}\left(\vec{Q}^{\mathbf{r}}\right)\left(f_{i} v\right) \vec{x}\right)\right)_{i<n} \rightarrow\right.\right. \\
& \forall_{g}\left(\forall_{\vec{x}, u}\left({ }^{\mathrm{c} \circ} J_{\vec{R}^{\mathrm{r}}\left(\vec{P}^{\mathrm{r}}\right)}^{\mathrm{r}} u \vec{x} \rightarrow\left({ }^{\mathrm{c} \circ} J_{\vec{R}^{\mathrm{r}}}^{\mathrm{r}}\left(\vec{Q}^{\mathrm{r}}\right) \cup^{\mathrm{nc}} R\right)(g u, \vec{x})\right) \rightarrow \tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathrm{r}}\left(\vec{Q}^{\mathrm{r}}\right),{ }^{\mathrm{co}} \mathcal{R}_{\vec{R}^{\mathrm{r}}\left(\vec{Q}^{\mathrm{r}}\right)}^{\mathrm{r}} \cup^{\mathrm{nc}} R\right)\left(\mathcal{M}_{\rho_{i \nu}} v \vec{f} g\right)\right) .
\end{aligned}
$$

It suffices to prove $\tilde{A}_{i \nu}^{\mathrm{r}}\left(\vec{R}^{\mathbf{r}}\left(\vec{P}^{\mathbf{r}}\right),{ }^{\mathrm{co}} \mathcal{R}_{\vec{R}^{\mathbf{r}}\left(\vec{P}_{\mathbf{r}}^{\mathbf{r}}\right)}^{\mathbf{r}}\right) v_{\nu}, \forall_{\vec{x}, v}\left(R_{i}^{\mathbf{r}}\left(\vec{P}^{\mathbf{r}}\right) v \vec{x} \rightarrow R_{i}^{\mathbf{r}}\left(\vec{Q}^{\mathbf{r}}\right)\left(f_{i} v\right) \vec{x}\right)$ for each $i<n$,
 assumption. The second one comes by another induction hypothesis $\forall_{\vec{x}, v}\left(R_{i}^{\mathbf{r}}\left(\overrightarrow{P^{\mathbf{r}}}\right) v \vec{x} \rightarrow\right.$ $\left.\forall_{\vec{w}}\left(\left(\forall_{\vec{x}, u}\left(P_{i}^{\mathbf{r}} u \vec{x} \rightarrow Q_{i}^{\mathbf{r}}\left(w_{i} u\right) \vec{x}\right)\right)_{i<n} \rightarrow R_{i}^{\mathbf{r}}\left(\vec{Q}^{\mathbf{r}}\right)\left(\mathcal{M}_{\lambda_{\vec{\alpha}} \iota \vec{\tau}(\vec{\pi}(\vec{\alpha}))} v \vec{w}\right) \vec{x}\right)\right)$. For the last one, let $\vec{x}$ and $u$ be given and assume ${ }^{c o} J_{\vec{R}^{\mathrm{r}}(\overrightarrow{P r})}^{\mathrm{r}} u \vec{x}$. Our goal is same as ${ }^{\mathrm{co}} J_{\vec{R}^{\mathrm{r}}\left(\vec{Q}^{\mathrm{r}}\right)}^{\mathrm{r}}\left(\mathcal{M}_{\lambda_{\vec{\alpha}} \iota \overrightarrow{(\vec{n}(\vec{\alpha}))}}^{\vec{\sigma}} u \vec{w}, \vec{x}\right) \vee^{\mathrm{nc}}$
 ward by the premise ${ }^{\mathrm{co}} \overline{\vec{R}}^{\mathrm{r}}\left(\overrightarrow{\left.P^{\mathrm{r}}\right)} u \bar{x}\right.$.

We prove the cases of four constants, constructors, recursion operators, destructors and corecursion operators.

Lemma 2.5.31 (Soundness: Computational inductive and coinductive predicates). We define $I_{\vec{X}}$ of arity $(\vec{\tau})$ to be $\mu_{Z}(\vec{K})$ where $K_{i}$ is a formula $\forall_{\vec{x}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}(\vec{X}, Z)\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} Z \vec{t}\right)$. Let an algebra $\iota_{\vec{\alpha}}$ be $\tau\left(I_{\vec{X}}\right)$ where $\alpha_{i}=\tau\left(X_{i}\right)$.

1. For $i$ such that $0 \leq i<k$, the introduction axiom $I_{i}^{+}$is realized by the constructor $C_{i}$ of the algebra $\iota_{\vec{\alpha}}$.
2. The elimination axiom $I^{-}$is realized by the recursion operator $\mathcal{R}_{{ }_{l}}$.

We define ${ }^{\mathrm{co}} I_{\vec{X}}$ of arity $(\vec{\tau})$ to be $\nu_{X}(\vec{K})$ where $\vec{K}$ is given as the above. Let $\iota_{\alpha}$ be $\tau\left({ }^{\mathrm{co}} I\right)$ where $\alpha_{i}=\tau\left(X_{i}\right)$.
3. The closure axiom ${ }^{{ }^{\mathrm{oo}} I^{-}}$is realized by the destructor $\mathcal{D}_{\iota_{\vec{\alpha}}}$.
4. The greatest-fixed-point axiom ${ }^{\text {co }} I^{+}$is realized by the corecursion operator ${ }^{\mathrm{co}} \mathcal{R}_{t_{\vec{\alpha}}}$.

Proof. 11 We prove $C_{i} \mathbf{r} \forall_{\vec{x}}^{\mathrm{c} / \mathrm{nc}}\left(\left(A_{i \nu}\left(\vec{X}, I_{\vec{X}}\right)\right)_{\nu<n_{i}} \rightarrow^{\mathrm{c} / \mathrm{nc}} I_{\vec{X}} \vec{t}\right)$. It unfolds into

$$
\forall_{\vec{x}, \vec{u}}\left(\left(A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathrm{r}}, I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}\right) u_{\nu}\right)_{\nu<n_{i}} \rightarrow I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}\left(C_{i} \vec{x} \vec{u}, \vec{t}\right)\right)
$$

with the understanding that

1. only those $x_{j}$ with a computational $\forall_{x_{j}}^{\mathrm{c}}$ in $K_{i}$, and
2. only those $u_{\nu}$ with $A_{i \nu}$ c.r. and followed by $\rightarrow^{\mathrm{c}}$ in $K_{i}$,
occur as arguments in $C_{i} \vec{x} \vec{u}$. The goal is same as ${\left(I^{\mathbf{r}}\right)_{i}^{+}}^{\text {with }} \vec{X}^{\mathbf{r}}$ for the parameter predicates.
(2) Let $P$ be a predicate variable of the same arity of $I_{\vec{X}}$, and $\rho:=\tau(P)$. We prove $\mathcal{R}_{\iota_{\vec{\alpha}}}^{\rho} \mathbf{r} \forall_{\vec{x}}\left(I_{\vec{X}} \vec{x} \rightarrow\left(K_{i}\left(I_{\vec{X}}, P\right)\right)_{i<n} \rightarrow P \vec{x}\right)$, where each step formula $K_{i}\left(I_{\vec{X}}, P\right)$ is $\forall_{\vec{x}}\left(\left(A_{i \nu}\left(\vec{X}, I_{\vec{X}} \cap^{\mathrm{d}} P\right)\right)_{\nu<n_{i}} \rightarrow P \vec{t}\right)$ for each $i$. By unfolding, the goal is same as

$$
\forall_{\vec{x}, u}\left(I_{\vec{X} \overrightarrow{\mathbf{r}}}^{\mathbf{r}} u \vec{x} \rightarrow \forall_{\vec{w}}\left(\left(K_{i}^{\mathbf{r}}\left(I_{\vec{X} \vec{r}}^{\mathbf{r}}, P^{\mathbf{r}}\right) w_{i}\right)_{i<k} \rightarrow P^{\mathbf{r}}\left(\mathcal{R}_{\iota_{\vec{\alpha}}} u \vec{w}, \vec{t}\right)\right)\right) .
$$

Let $\vec{x}$ and $u$ be given and assume $I_{\vec{X}}^{\mathrm{r}} \mathrm{r} u \vec{x}$. Also let $\vec{w}$ be given and assume for each $i<k$,

$$
\begin{equation*}
K_{i}^{\mathbf{r}}\left(I_{\vec{X} \mathbf{r}}^{\mathrm{r}}, P^{\mathbf{r}}\right) w_{i} \tag{2.2}
\end{equation*}
$$

Let $Q u \vec{t}$ be our goal $P^{\mathbf{r}}\left(\mathcal{R}_{\iota_{\vec{\alpha}}} u \vec{w}, \vec{t}\right)$. By using $\left(I^{\mathbf{r}}\right)^{-}$for $I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}} u \vec{x}$ with the competitor predicate $Q$, it suffices to prove all the step formulas

$$
\forall_{\vec{x}} \forall_{\vec{u}}\left(\left(A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathbf{r}}, I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}} \cap^{\mathrm{u}} Q\right) u_{\nu}\right)_{\nu<n_{i}} \rightarrow Q\left(C_{i} \vec{x} \vec{u}, \vec{t}\right)\right),
$$

with the understanding that only relevant $x_{j}$ and $u_{j}$ occur as arguments in $C_{i} \vec{x} \vec{u}$. Let $\vec{x}$ and $\vec{u}$ be given and assume for each $\nu<n_{i}$,

$$
\begin{equation*}
A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathbf{r}}, I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}} \cap^{\mathrm{u}} Q\right) u_{\nu} \tag{2.3}
\end{equation*}
$$

We prove $Q\left(C_{i} \vec{x} \vec{u}, \vec{t}\right)$, which is same as

$$
\begin{equation*}
P^{\mathbf{r}}\left(w_{i} \vec{x}\left(\mathcal{M}_{\lambda_{\beta} \rho_{i \nu}(\vec{\alpha}, \beta)}^{\iota_{\vec{\alpha}} \rightarrow \iota_{\bullet} \times \tau} u_{\nu} \lambda_{a}\left\langle a, \mathcal{R}_{\iota_{\vec{\alpha}}} a \vec{w}\right\rangle\right)_{\nu<n_{i}}, \vec{t}\right) \tag{2.4}
\end{equation*}
$$

where $\rho_{i \nu}(\vec{\alpha}, \beta)$ is defined to be a type $\tau\left(A_{i \nu}(\vec{X}, Z)\right)$. Note that $\left(I \cap^{\mathrm{d}} P\right)^{\mathbf{r}}$ is same as $\left\{q^{\iota \times \tau}, \vec{x} \mid\left(\left\{v^{\iota} \mid I^{\mathbf{r}} v \vec{x}\right\}\left(\wedge^{\mathrm{d}}\right)^{\mathbf{r}}\left\{\tilde{v}^{\tau} \mid P^{\mathbf{r}} \tilde{v} \vec{x}\right\}\right) q\right\}$, where $\iota$ and $\tau$ are the types of realizers of $I$ and $P$, respectively. By unfolding (2.2), we have

$$
\forall_{\vec{x}, \vec{q}}\left(\left(A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}}, I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}}\left(\cap^{\mathbf{d}}\right)^{\mathbf{r}} P^{\mathbf{r}}\right) q_{\nu}\right)_{\nu<n_{i}} \rightarrow P^{\mathbf{r}}\left(w_{i} \vec{x}_{i} \vec{q}, \vec{t}\right)\right)
$$

which implies our goal (2.4) provided the following holds for all $\nu<n_{i}$,

$$
A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}}, I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}}\left(\cap^{\mathrm{d}}\right)^{\mathbf{r}} P^{\mathbf{r}}\right)\left(\mathcal{M}_{\lambda_{\beta} \rho_{i \nu}(\vec{\alpha}, \beta)}^{\iota_{\vec{\alpha}} \rightarrow \iota_{\alpha} \times \tau} u_{\nu} \lambda_{a}\langle a, \mathcal{R} a \vec{w}\rangle\right) .
$$

Instantiating Lemma 2.5.30 as

$$
\begin{gathered}
\forall_{\vec{x}, u}\left(A _ { i \nu } ^ { \mathrm { r } } ( \vec { X } ^ { \mathbf { r } } , I _ { \vec { X } ^ { \mathbf { r } } } ^ { \mathrm { r } } \cap ^ { \mathrm { u } } Q ) u \rightarrow \forall _ { g } \left(\forall_{\vec{x}, u}\left(\left(I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}} \cap^{\mathrm{u}} Q\right) u \vec{x} \rightarrow\left(I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}\left(\cap^{\mathrm{d}}\right)^{\mathbf{r}} P^{\mathbf{r}}\right)(g u, \vec{x})\right) \rightarrow\right.\right. \\
\left.\left.A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathbf{r}}, I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}}\left(\cap^{\mathrm{d}}\right)^{\mathbf{r}} P^{\mathbf{r}}\right)\left(\mathcal{M}_{\left.\lambda_{\beta} \stackrel{\rightharpoonup}{\alpha}^{\rho_{\vec{\alpha}} \times \tau} \times \tau, \beta\right)} u g\right)\right)\right),
\end{gathered}
$$

we prove the goal. The first premise $A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}}, I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}} \cap^{\mathrm{u}} Q\right) u_{\nu}$ comes by the assumption 2.3 . We prove $\forall_{\vec{x}, u}\left(\left(I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}} \cap^{\mathbf{u}} Q\right) u \vec{x} \rightarrow\left(I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}}\left(\cap^{\mathrm{d}}\right)^{\mathbf{r}} P^{\mathbf{r}}\right)\left(\left(\lambda_{a}\langle a, \mathcal{R} a \vec{w}\rangle\right) u, \vec{x}\right)\right)$. Let $\vec{x}, u$ be given and assume $\left(I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}} \cap^{\mathrm{u}} Q\right) u \vec{x}$, namely, $I_{\vec{X} \mathrm{r}}^{\mathrm{r}} u \vec{x} \wedge^{\mathrm{u}} Q u \vec{x}$. Using $\left(\wedge^{\mathrm{u}}\right)^{-}$, we let $\vec{x}, u$, assume $I_{\vec{X} \mathrm{r}}^{\mathrm{r}} u \vec{x}$ and $Q u \vec{x}$ and then prove $\left(I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}}\left(\cap^{\mathrm{d}}\right)^{\mathbf{r}} P^{\mathbf{r}}\right)\left(\left(\lambda_{a}\langle a, \mathcal{R} a \vec{w}\rangle\right) u, \vec{x}\right)$, namely, $\left(\left\{v \mid I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}} v \vec{x}\right\}\left(\wedge^{\mathrm{d}}\right)^{\mathbf{r}}\left\{\tilde{v} \mid P^{\mathbf{r}} \tilde{v} \vec{x}\right\}\right)\langle u, \mathcal{R} u \vec{w}\rangle$.

By means of $\left(\wedge^{\mathbf{r}}\right)_{0}^{+}$, it suffices to prove $I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}} u \vec{x}$ and $P^{\mathbf{r}}(\mathcal{R} u \vec{w}, \vec{x})$. The first one is in the assumption, and the second one is same as $Q u \vec{x}$ which is again in the assumption.
(3) We prove $\mathcal{D}_{\iota_{\vec{\alpha}}} \mathbf{r} \forall_{\vec{x}}\left({ }^{\mathrm{co}} I_{\vec{X}} \vec{x} \rightarrow \bigvee_{i<k}\left(\exists_{\vec{y}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}\left(\vec{X},{ }^{\mathrm{co}} I_{\vec{X}}\right) \wedge^{1} \bigwedge \vec{E}_{i}\right)\right)\right)$, which unfolds into

$$
\forall_{\vec{x}, u}\left({ }^{\mathrm{c}} I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}} u \vec{x} \rightarrow\left(\bigvee_{i<k}^{\mathrm{r}}\left(\exists \exists_{\vec{y}}^{\mathrm{r}}\left(\bigwedge_{\nu<n_{i}}^{\mathrm{r}} A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{c}} \Gamma_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}\right)\left(\Lambda^{\mathrm{l}}\right)^{\mathbf{r}} \bigwedge^{\mathrm{r}} \vec{E}_{i}\right)\right)\right)(\mathcal{D} u)\right) .
$$

Let $\vec{x}$ and $u$ be given and assume ${ }^{\text {co }} \Gamma_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}} u \vec{x}$. Applying ${ }^{\left.{ }^{\text {co }} I^{\mathbf{r}}\right)^{-} \text {to the assumption, the following }}$ holds.

$$
\bigvee_{i<k}^{\mathrm{nc}}\left(\exists_{\vec{y}, \vec{v}}^{\mathrm{u}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathrm{r}},{ }^{\mathrm{co}} I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}}\right) v_{\nu} \wedge \bigwedge \vec{E}_{i} \wedge u \text { eqd } C_{i} \vec{v}\right)\right)
$$

$\operatorname{Using}\left(\bigvee^{\mathrm{nc}}\right)^{-},\left(\vee^{\mathbf{r}}\right)_{i}^{+},\left(\exists^{\mathrm{u}}\right)^{-},\left(\exists^{\mathbf{r}}\right)^{+},\left(\wedge^{\mathrm{u}}\right)^{-}$and $\left(\wedge^{\mathbf{r}}\right)^{+}$, we end up with proving $A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{co}} I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}}\right) v_{\nu}$ from the very same premise. Here we used $\mathcal{D}\left(C_{i} \vec{v}\right) \mapsto \operatorname{in}_{i}^{k}($ pair $\vec{v})$.
(4) We prove

$$
{ }^{\mathrm{co}} \mathcal{R}_{\iota_{\vec{x}}} \mathbf{r} \forall_{\vec{x}}\left(P \vec{x} \rightarrow \forall_{\vec{x}}\left(P \vec{x} \rightarrow \bigvee_{i<k}\left(\exists_{\vec{y}_{i}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}\left(\vec{X},{ }^{\mathrm{co}} I_{\vec{X}} \cup P\right) \wedge^{1} \bigwedge \vec{E}_{i}\right)\right)\right) \rightarrow{ }^{\mathrm{co}} \overrightarrow{\vec{X}}_{\vec{X}} \vec{x}\right)
$$

which unfolds into

$$
\begin{aligned}
& \forall_{\vec{x}, u}\left(P ^ { \mathbf { r } } u \vec { x } \rightarrow \forall _ { w } \left(\forall_{\vec{x}, u}\left(P^{\mathbf{r}} u \vec{x} \rightarrow\left(\bigvee_{i<k}^{\mathbf{r}}\left(\exists_{\vec{y}_{i}}^{\mathbf{r}}\left(\bigwedge_{\nu<n_{i}}^{\mathbf{r}} A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{co}} I_{\overrightarrow{X^{\mathbf{r}}}}^{\mathbf{r}} \cup^{\mathbf{r}} P^{\mathbf{r}}\right)\left(\wedge^{1}\right)^{\mathbf{r}} \bigwedge \vec{E}_{i}\right)\right)\right)(w u)\right) \rightarrow\right.\right. \\
& \left.{ }^{\mathrm{co}} I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}\left({ }^{\mathrm{co}} \mathcal{R}_{\iota_{\vec{\alpha}}} u w, \vec{x}\right)\right) \text { ). }
\end{aligned}
$$

Let $\vec{x}, u$ be given and assume $P^{\mathbf{r}} u \vec{x}$. Let $w$ be given and assume

$$
\begin{equation*}
\forall_{\vec{x}, u}\left(P^{\mathbf{r}} u \vec{x} \rightarrow\left(\bigvee_{i<k}^{\mathbf{r}}\left(\exists_{\vec{y}_{i}}^{\mathrm{r}}\left(\bigwedge_{\nu<n_{i}}^{\mathbf{r}} A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{co}} \tilde{X}_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}} \cup^{\mathbf{r}} P^{\mathbf{r}}\right)\left(\wedge^{1}\right)^{\mathbf{r}} \bigwedge \vec{E}_{i}\right)\right)\right)(w u)\right) . \tag{2.5}
\end{equation*}
$$

Recall that ${ }^{\mathrm{co}} I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}} \cup^{\mathbf{r}} P^{\mathbf{r}}$ stands for $\left\{q^{\iota+\tau}, \vec{x} \mid\left(\left\{\left.v\right|^{\mathrm{co}} I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}} v \vec{x}\right\} \vee^{\mathbf{r}}\left\{\tilde{v} \mid P^{\mathbf{r}} \tilde{v} \vec{x}\right\}\right) q\right\}$. We prove ${ }^{\mathrm{co}} I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}}\left({ }^{\mathrm{co}} \mathcal{R}_{\iota_{\alpha}} u w, \vec{x}\right)$ by using ${ }^{{ }^{\text {co }} I^{+} \text {with a competitor predicate } Q:=\left\{v, \vec{x} \mid \exists \exists_{\tilde{v}}\left(v \text { eqd }{ }^{\mathrm{co}} \mathcal{R}_{\iota_{\bar{\alpha}}} \tilde{v} w \wedge\right.\right.}$ $\left.\left.P^{\mathbf{r}} \tilde{v} \vec{x}\right)\right\}$. It suffices to prove the following costep formula.

$$
\forall_{\vec{x}, v}\left(Q v \vec{x} \rightarrow \bigvee_{i<k}^{\mathrm{nc}} \exists \exists_{\vec{y}, \vec{u}}^{\mathrm{u}}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{co}} I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}} \cup^{\mathrm{nc}} Q\right) u_{\nu} \wedge \bigwedge \vec{E}_{i} \wedge v \operatorname{eqd} C_{i} \vec{u}\right)\right)
$$

Let $\vec{x}, v$ be given and assume $Q v \vec{x}$, which yields some $\tilde{v}$ such that $v \operatorname{eqd}^{\mathrm{co}} \mathcal{R}_{\iota \stackrel{\alpha}{\alpha}} \tilde{v} w$ and $P^{\mathbf{r}} \tilde{v} \vec{x}$. By the conversion rule ${ }^{\text {co }} \mathcal{R} \tilde{v} w$ goes to

$$
\begin{aligned}
& \text { Case } w \tilde{v} \text { of } \operatorname{in}_{0}^{k} v_{0} \rightarrow C_{0}\left(\mathcal{M}_{\lambda_{\beta} \rho_{0 \nu}(\vec{\alpha}, \beta)}^{\tau \rightarrow \rightarrow+\iota}\left(\pi_{\nu}^{n_{0}} v_{0}\right)\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R} \cdot w\right]\right)_{\nu<n_{0}} \\
& \quad \vdots \\
& \quad \operatorname{in}_{k-1}^{k} v_{k-1} \rightarrow C_{k-1}\left(\mathcal{M}_{\lambda_{\beta} \rho_{(k-1) \nu}(\vec{\alpha}, \beta)}^{\tau \rightarrow \tau+\iota}\left(\pi_{\nu}^{n_{k-1}} v_{k-1}\right)\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R} \cdot w\right]\right)_{\nu<n_{k-1}} .
\end{aligned}
$$

Let $t(w \tilde{u})$ be the above term. Applying (2.5) to the assumption $P^{\mathbf{r}} \tilde{u} \vec{x}$,

$$
\left(\bigvee_{i<k}^{\mathbf{r}}\left(\exists_{\vec{y}}^{\mathbf{r}}\left(\bigwedge_{\nu<n_{i}}^{\mathbf{r}} A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{c}} I_{\vec{X}_{\mathbf{r}}}^{\mathrm{r}} \cup^{\mathbf{r}} P^{\mathbf{r}}\right)\right)\left(\wedge^{\mathrm{l}}\right)^{\mathbf{r}} \bigwedge^{\mathbf{r}} \vec{E}_{i}\right)\right)(w \tilde{u})
$$

holds. Using $\left(V^{\mathbf{r}}\right)^{-}$for this formula to the following goal

$$
\left.\bigvee_{i<k}^{\mathrm{nc}} \exists \vec{y}, \vec{u}, \bigwedge_{\nu<n_{i}} A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathrm{r}},{ }^{\mathrm{co}} I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}} \cup^{\mathrm{nc}} Q\right) u_{\nu} \wedge \bigwedge \vec{E}_{i} \wedge t(w \tilde{u}) \text { eqd } C_{i} \vec{u}\right),
$$

it suffices to prove for each $i<k$ that the following holds

$$
\begin{aligned}
& \forall_{q}\left(\left(\exists_{\vec{y}}^{\mathbf{r}}\left(\bigwedge_{\nu<n_{i}}^{\mathbf{r}} A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{co}} \tilde{X}_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}} \cup^{\mathbf{r}} P^{\mathbf{r}}\right)\left(\wedge^{1}\right)^{\mathbf{r}} \bigwedge \vec{E}_{i}\right)\right) q \rightarrow\right. \\
& \quad \bigvee_{i<k}^{\mathrm{nc}} \exists \vec{y}, \vec{u} \\
& \left.\left(\bigwedge_{\nu<n_{i}}^{\mathrm{nc}} A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{co}} I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}} \cup^{\mathrm{nc}} Q\right) u_{\nu} \wedge \bigwedge \vec{E}_{i} \wedge t\left(\mathbf{i n}_{i}^{k} q\right) \operatorname{eqd} C_{i} \vec{u}\right)\right)
\end{aligned}
$$

Let $q$ be given and assume the premise. We use $\left(V^{\text {nc }}\right)_{i}^{+}$to the goal. Using $\left(\exists^{\mathbf{r}}\right)^{-}$, $\left(\exists^{\mathrm{u}}\right)^{+}$and $\left(\wedge^{\mathbf{r}}\right)^{-}$, it suffices to prove $\forall_{\vec{x}, \vec{y}}\left(\bigwedge \vec{E}_{i} \rightarrow \forall_{\vec{s}}^{\mathrm{nc}}\left(\left(A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathrm{r}},{ }^{\mathrm{co}} I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}} \cup^{\mathbf{r}} P^{\mathbf{r}}\right) s_{\nu}\right)_{\nu<n_{i}} \rightarrow\right.\right.$ $\exists_{\vec{u}}^{u}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}},{ }^{\mathrm{c}}{ }_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}} \cup^{\mathrm{nc}} Q\right) u_{\nu} \wedge \bigwedge \vec{E}_{i} \wedge t\left(\mathbf{i n}_{i}^{k}(\mathbf{p a i r} \vec{s})\right)\right.$ eqd $\left.\left.\left.C_{i} \vec{u}\right)\right)\right)$. By the conversion rule,

$$
t\left(\mathbf{i n}_{i}^{k}(\mathbf{p a i r} \vec{s})\right) \mapsto C_{i}\left(\mathcal{M} s_{0}\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R} \cdot w\right]\right) \ldots\left(\mathcal{M} s_{n_{i}-1}\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R} \cdot w\right]\right)
$$

$\operatorname{Using}\left(\exists^{\mathrm{u}}\right)^{+}$with $u_{\nu}:=\mathcal{M} s_{\nu}\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R} \cdot w\right]$ and also $\wedge^{+}$, we end up with proving $A_{i \nu}^{\mathrm{r}}\left(\vec{X}^{\mathrm{r}},{ }^{\mathrm{co}} I_{\overrightarrow{X^{\mathrm{r}}}}^{\mathrm{r}} \cup^{\mathrm{nc}}\right.$ $Q)\left(\mathcal{M} s_{\nu}\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R} \cdot w\right]\right)$. By Lemma 2.5 .30 it suffices to prove $\forall_{\vec{x}, q^{++\tau}}\left(\left({ }^{\mathrm{co}} I_{\vec{X}^{\mathbf{r}}}^{\mathbf{r}} \cup^{\mathbf{r}} P^{\mathbf{r}}\right)^{\mathbf{r}} q \vec{x} \rightarrow\right.$ $\left.\left({ }^{\mathrm{co}} \Gamma_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}} \cup^{\text {nc }} Q\right)\left(\left[\mathrm{id},{ }^{\mathrm{co}} \mathcal{R} \cdot w\right] q, \vec{x}\right)\right)$. Let $\vec{x}, q$ be given and assume $\left({ }^{\mathrm{co}} I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}} \cup^{\mathrm{r}} P^{\mathbf{r}}\right) q \vec{x}$, namely, $\left(\left\{v \mid{ }^{\mathrm{Co}} I_{\vec{X} \mathrm{r}}^{\mathrm{r}} v \vec{x}\right\} \vee^{\mathbf{r}}\left\{\tilde{v} \mid P^{\mathbf{r}} \tilde{v} \vec{x}\right\}\right) q$. We use $\left(V^{\mathbf{r}}\right)^{-}$. From ${ }^{\mathrm{c}} I_{\vec{X}}{ }_{\overrightarrow{\mathrm{r}}} \mathrm{v} \vec{x}$ and $q=\operatorname{InL} v$, the goal is straightforward. From $P^{\mathbf{r}} \tilde{v} \vec{x}$ and $q=\operatorname{lnR} \tilde{v}$, the right disjunct, which is same as $Q\left({ }^{\text {co }} \mathcal{R} \tilde{v} w, \vec{x}\right)$, is implied from the premise.

We also address the soundness result for non-computational predicates.
Lemma 2.5.32 (Soundness: non-computational inductive and coinductive predicates). Let $I_{\vec{Y}}$ be a non-computational inductive predicate defined to be $\mu_{Z}^{\mathrm{nc}}(\vec{K})$ and an algebra $\iota_{\vec{\alpha}}$ to be $\tau\left(I_{\vec{X}}\right)$ where $\alpha_{i}=\tau\left(X_{i}\right)$.

1. The introduction axiom $I_{i}^{+}$is realized by the empty term $\varepsilon$.
2. The elimination axiom $I^{-}$is realized by $\varepsilon$.

Let ${ }^{\text {co }} I_{\vec{X}}$ be a non-computational coinductive predicate defined to be $\nu_{Z}^{\mathrm{nc}}(\vec{K})$ and an algebra $\iota_{\vec{\alpha}}$ to be $\tau\left({ }^{\mathrm{co}} I_{\vec{X}}\right)$ where each $\alpha_{i}$ is $\tau\left(X_{i}\right)$.
3. The closure axiom ${ }^{\text {co }} I^{-}$is realized by the empty term $\varepsilon$.
4. The greatest-fixed-point axiom ${ }^{\text {co }} I^{+}$is realized by the empty term $\varepsilon$.

Proof. (1) We prove $\varepsilon \mathbf{r} \forall_{\vec{x}}\left(\left(A_{i \nu}\left(I_{\vec{X}}\right)\right)_{\nu<n_{i}} \rightarrow I_{\vec{X}} \vec{t}\right)$. By unfolding and also by the definition of $\varepsilon$, our goal is same as $\forall_{\vec{x}} \forall_{\vec{u}}\left(\left(A_{i \nu}^{\mathrm{r}}\left(I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}}\right) u_{\nu}\right)_{\nu<n_{i}} \rightarrow I_{\vec{X}^{\mathrm{r}}}^{\mathrm{r}}(\varepsilon \vec{x} \vec{u}, \vec{t})\right)$. Let $\vec{x}, \vec{u}$ be given and assume $A_{i \nu}^{\mathbf{r}}\left(I_{\vec{X} \mathbf{r}}^{\mathbf{r}}\right) u_{\nu}$ for each $\nu<n_{i}$. The formula $I_{\vec{X} \mathbf{r}}^{\mathbf{r}}(\varepsilon \vec{x} \vec{u}, \vec{t})$ is same as $I_{\vec{X}} \vec{t}$, because the formula $I_{\vec{X}} \vec{t}$ is non-computational. We use $I_{i}^{+}$, then it suffices to prove $A_{i \nu}\left(I_{\vec{X}}\right)$ for each $\nu<n_{i}$. Since $A_{i \nu}\left(I_{\vec{X}}\right)$ is invariant by the definition of non-computational inductive predicates, the assumption $A_{i \nu}^{\mathrm{r}}\left(I_{\vec{X} \mathrm{r}}^{\mathrm{r}}\right) u_{\nu}$ yields $A_{i \nu}\left(I_{\vec{X}}\right)$.
(2) Let $P$ be a predicate variable of the same arity of $I_{\vec{X}}$. We prove $\varepsilon \mathbf{r} \forall_{\vec{x}}\left(I_{\vec{X}} \vec{x} \rightarrow\right.$ $\left.\left(K_{i}\left(I_{\vec{X}}, P\right)\right)_{i<k} \rightarrow P \vec{x}\right)$ where $K_{i}\left(I_{\vec{X}}, P\right)$ is given by $\forall_{\vec{x}}\left(\left(A_{i \nu}\left(\vec{X}, I_{\vec{X}} \cap P\right)\right)_{\nu<n_{i}} \rightarrow P \vec{t}\right)$. By unfolding the proposition, it is same as

$$
\forall_{\vec{x}, u}\left(I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}(u, \vec{x}) \rightarrow \forall_{\vec{w}}\left(\left(K_{i}^{\mathbf{r}}\left(I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}, P^{\mathbf{r}}\right) w_{i}\right)_{i<k} \rightarrow P^{\mathbf{r}}(\varepsilon u \vec{w}, \vec{x})\right)\right) .
$$

Assume $\vec{x}, u, I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}(u, \vec{x}), \vec{w}$, and $\left(K_{i}^{\mathbf{r}}\left(I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}, P^{\mathbf{r}}\right) w_{i}\right)_{i<k}$. We prove $P^{\mathbf{r}}(\varepsilon u \vec{w}, \vec{x})$, which is same as $P \vec{x}$ because $P$ is non-computational. Using $I^{-}$with the competitor $\{\vec{x} \mid P \vec{x}\}$, it suffices to prove $I_{\vec{X}} \vec{x}$ and step formulas $\left(K_{i}\left(I_{\vec{X}}, P\right)\right)_{i<k}$. Since $I_{\vec{X}}$ is n.c., the assumption $I_{\vec{X}^{\mathbf{r}}}^{\mathrm{r}}(u, \vec{x})$ is same as $I_{\vec{X}} \vec{x}$. The assumption $\left(K_{i}^{\mathbf{r}}\left(I_{\vec{X}} \mathbf{r}, P^{\mathbf{r}}\right) w_{i}\right)_{i<k}$ is same as $\forall_{\vec{x}, \vec{u}}\left(\left(A_{i \nu}^{\mathbf{r}}\left(\vec{X}^{\mathbf{r}}, I_{\vec{X}}^{\mathbf{r}} \cap^{\mathbf{r}} P^{\mathbf{r}}\right) u_{\nu}\right)_{\nu<n_{i}} \rightarrow\right.$ $\left.P^{\mathbf{r}}\left(w_{i} \vec{u}, \vec{t}\right)\right)$. This formula is same as the goal, because $A_{i \nu}\left(\vec{X}, I_{\vec{X}} \cap P\right)$ for each $i$ and $P$ are all invariant.
(3) We prove $\varepsilon \mathbf{r} \forall_{\vec{x}}\left({ }^{\mathrm{co}} I_{\vec{X}} \vec{x} \rightarrow \bigvee_{i<k}^{\mathrm{nc}} \exists \vec{y}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}\left({ }^{(\mathrm{co}} I_{\vec{X}}\right) \wedge \bigwedge \vec{E}_{i}\right)\right)$. Since ${ }^{\mathrm{co}} I_{\vec{X}} \vec{x}$ and the disjunction $\bigvee^{\text {nc }}$ are non-computational, the goal is same as ${ }^{\text {co } I^{-} \text {, }}$
(4) We probe

$$
\varepsilon \mathbf{r} \forall_{\vec{x}}\left(Q \vec{x} \rightarrow \forall_{\vec{x}}\left(Q \vec{x} \rightarrow \bigvee_{i<k}^{\mathrm{nc}} \exists \vec{y}\left(\bigwedge_{\nu<n_{i}} A_{i \nu}\left({ }^{\mathrm{co}} I_{\vec{X}} \cup^{\mathrm{nc}} Q\right) \wedge \bigwedge \vec{E}_{i}\right)\right) \rightarrow{ }^{\mathrm{co}} I_{\vec{X}} \vec{x}\right) .
$$

Recall that $Q$, the disjunction $\bigvee^{\mathrm{nc}}$ and ${ }^{\text {co }} I$ are non-computational. Then by unfolding, the goal is same as ${ }^{{ }^{\text {co }} I^{-}}$.

Finally, we prove the soundness results of special non-computational inductively defined predicates.

Lemma 2.5.33 (Soundness: special non-computational inductive predicates). Let $I_{\vec{Y}}$ be a special non-computational inductive predicate $\mu_{X}^{\mathrm{nc}}\left(\forall_{\vec{x}}^{\mathrm{nc}}\left(\left(A_{\nu}\right)_{\nu<n} \rightarrow^{\mathrm{nc}} X \vec{t}\right)\right)$ where $A_{\nu}$ is of the form $Y_{j} \vec{s}_{i}$. The empty term $\varepsilon$ realizes $I^{+}$and the identity id realizes $I^{-}$.

Proof. We prove $\varepsilon \mathbf{r} \forall_{\vec{x}}^{\mathrm{nc}}\left(\left(A_{\nu}\right)_{\nu<n} \rightarrow{ }^{\mathrm{nc}} I_{\vec{Y}} \vec{t}\right)$. By the definition, this formula is same as
 use $I^{+}$to prove $\left.I_{\left\{\vec{z} \mid \exists_{v}^{u}\left(Y_{i}^{\mathrm{r}} v \vec{z}\right)\right\}_{i<l}} \vec{x}\right)$. It suffices to prove $\left(\exists_{v}^{\mathrm{u}}\left(A_{\nu}^{\mathbf{r}} v\right)\right)_{\nu<n}$ which is from the assumption, since $A_{\nu}$ is of the form $Y_{i} \vec{s}$. We prove id $\mathbf{r} \forall \vec{x}\left(I_{\vec{Y}} \vec{x} \rightarrow \forall_{\vec{x}}^{\mathrm{nc}}\left(\left(A_{\nu}\right)_{\nu<n} \rightarrow{ }^{\mathrm{nc}} P \vec{t}\right) \rightarrow^{\mathrm{c}}\right.$ $P \vec{x})$. This formula is same as $\forall_{\vec{x}, \vec{u}}\left(I_{\left\{\vec{z}_{i} \mid\right.} \mid \exists_{v}^{u}\left(Y_{i}^{\mathrm{r}} v \vec{z}_{i}\right)\right\}_{i<l} \vec{x} \rightarrow \forall_{w}\left(\forall_{\vec{x}, \vec{u}}\left(\left(A_{\nu}^{\mathbf{r}} u_{\nu}\right)_{\nu<n} \rightarrow P^{\mathbf{r}} w \vec{t}\right) \rightarrow^{\mathrm{c}}\right.$ $\left.\left.P^{\mathbf{r}} w \vec{x}\right)\right)$ ). Let $\vec{x}$ and $\vec{u}$ be given and assume $I_{\left\{\vec{z}_{i} \mid \exists_{v}^{u}\left(Y_{i}^{\mathrm{r}} v \vec{z}_{i}\right)\right\}_{i<l}} \vec{x}$, and let $w$ be given and assume $\forall \vec{x}, \vec{u}\left(\left(A_{\nu}^{\mathbf{r}} u_{\nu}\right)_{\nu<n} \rightarrow{ }^{\mathrm{nc}} P^{\mathbf{r}} w \vec{t}\right)$. We use $I^{-}$for $I_{\left\{\vec{z}_{i} \mid \exists_{v}^{\mathrm{u}}\left(Y_{i}^{\mathbf{r}} v \vec{z}_{i}\right)\right\}_{i<l}} \vec{x}$ to prove the goal $Q \vec{x}:=P^{\mathbf{r}} w \vec{x}$. It suffices to prove the step formula $\forall_{\vec{x}}^{\mathrm{nc}}\left(\left(\exists_{v}^{\mathrm{u}}\left(A_{\nu}^{\mathrm{r}} v\right)\right)_{\nu<n} \rightarrow{ }^{\mathrm{nc}} Q \vec{t}\right)$. Let $\vec{x}$ be given and assume $\left(\exists_{v}^{\mathrm{u}}\left(A_{\nu}^{\mathrm{r}} v\right)\right)_{\nu<n}$ which yields $\vec{v}$ such that $A_{\nu}^{\mathrm{r}} v_{\nu}$ for each $\nu<n$, hence the conclusion comes by the assumption.

Realizability statement $t \mathbf{r} A$ can be viewed as a correctness assertion of $t$ with respect to a specification $A$, namely, $t$ is correct with respect to $A$. The soundness theorem tells us how to construct such a correctness proof from a proof of $A$. In TCF, this correctness is indeed provable inside of TCF. Informal computational content from the soundness proof offers an algorithm to generate a correctness proof of program extraction.

### 2.6 Notes

We describe related work and possible future work to conclude this chapter.

### 2.6.1 $\quad \mathrm{T}^{+}$and Partial Continuous Functionals

Our notion of computability is based on the notion of partial continuous functionals, which provides the denotational semantics of the formal calculus $\mathrm{T}^{+}$. Within the current formulation of $\mathrm{T}^{+}$, it is not possible to talk about approximation of partial continuous functionals. Huber, Karadais and Schwichtenberg [HKS10] study the theory $\mathrm{TCF}^{+}$in order to make the notion of approximation explicit so that it is possible to talk about approximation in the object language. Petrakis [Pet13] has formalized Scott's information systems within $\mathrm{TCF}^{+}$and Minlog. One motivation is a formalization of a constructive proof of Kreisel's density theorem, which seems to be feasible if the base theory is as strong as $\mathrm{TCF}^{+}$.

### 2.6.2 Non-Computational Part of Proofs

The notion of non-computational part of proofs has been used by Goad Goa80. In the field of proof theory, Berger studies the distinction between computational and non-computational ingredients of proofs via computational and non-computational universal quantifiers [Ber93]. Ratiu and Schwichtenberg study the same distinction in implications RS10. Such logical connectives are further studied by Benl, Berger, Schwichtenberg, Seisenberger and Zuber [BBS ${ }^{+} 98$ ], Berger [Ber05] and Schwichtenberg and Wainer [SW12]. Our formulation follows the one by Schwichtenberg and Wainer [SW12]. Paulin-Mohring [PM89] studies a realizability for the Calculus of Construction, considering a distinction between informative and non-informative propositions, which is used to ignore non-computational parts of proofs during program extraction. Based on such a distinction, Letouzey [Let02] studies an extraction mechanism for the Coq proof assistant whose type system is the Calculus of Construction.

### 2.6.3 Inductive and Coinductive Definitions

Tatsuta studies theories of program extraction TID Tat91 and $\nu$ TID Tat98 for inductive and coinductive definitions, respectively. While inductive and coinductive definitions in TCF are by means of strictly positive formulas, inductive and coinductive definitions in TID and $\nu$ TID are by monotone formulas which are not necessarily strictly positive. The target language of the program extraction of TID and $\nu$ TID is untyped. Berger [Ber09, Ber11] studies program extraction from inductive and coinductive definitions. Essentially our formal system is similar to Berger's one. The difference is mainly in the way of formalization.

### 2.6.4 Normalizability

Normalizability of TCF proofs involving nested inductive coinductive predicates is left as a future work. The computational content of such a normalization proof is expected to be a proof normalizer as studied by Berger [Ber93] and by Berger, Berghofer, Letouzey and Schwichtenberg [BBLS06]. Although corecursion operators in $\mathrm{T}^{+}$are not meant to be terminating, normalizability of nested recursion operators should be proven. Abel and Altenkirch gave a predicative proof of a lambda calculus with nested inductive and coinductive types AA99. Differently from our case, their corecursion is designed to be terminating as Hagino Hag87b, Hag87a.

### 2.6.5 Program Extraction in Other Proof Assistants

There are implementations of proof assistants which support program extraction. Letouzey recently study program extraction based on realizability in the proof assistant Coq [Let08]. The extraction machinery of Coq can extract from proofs programs in OCaml. It is different from one of Minlog in the sense that extracted programs in OCaml are outside of the formal system of Coq, i.e., Calculus of Construction, while $\mathrm{T}^{+}$of Minlog is inside of TCF. This machinery of Minlog comes as an advantage, because the realizability relation is still inside the system. It results in an automated program certification via the soundness proof in Minlog. This feature is currently available for proofs involving at most non-nested inductive definitions. Berghofer [Ber02] studies program extraction in Isabelle. This is based on the work by Berghofer and Nipkow [BN02] considering the execution of proof terms in HOL which is the logical foundation of Isabelle. There are more proof assistants which uses the Curry-Howard correspondence to execute proof objects. The Nuprl [BC85, Nup is the first proof assistant which makes use of the proofs-as-programs paradigm. There are other formalization works in program extraction in exact real arithmetic. One is due to Chuang Chu11 who studies computational content of proofs in Martin-Löf's type theory by using Agda. Proof terms in Martin-Löf's type theory require a special care for non-computational ingredients which come from "postulates" in contrast to the cases of Coq and Minlog.

Chapter 2. Theory of Computable Functionals

## Chapter 3

## Program Extraction in Exact Real Arithmetic

This chapter describes concrete applications of TCF, defined in Chapter 2, to exact real number computation. All case studies in this chapter are not only written in this text but also available as running examples in Minlog Min]. Formalization is strictly done and proofs and extracted programs are accessible and executable. The material in this chapter is heavily based on works by Berger [Ber09, Ber11] and Berger and Seisenberger [BS10, BS12]. Precisely speaking, the program cauchysds is in [Ber09], the program ave is in [BS10, BS12] and the programs ucf1to0, ucf0to1, app, cmp, int are in Ber09, Ber11].

The main contribution in this chapter is strict formalization of non-trivial case studies in exact real arithmetic and the machine-extraction of programs on the computer. The latter one makes a major difference from the former works. In order to illustrate our work in a readable way, we are going to be informal rather than to show strictly formalized results in this text. In Section A. 2 we provide a detailed explanation of the Minlog formalization of the material in Section 3.3 to complement the informality of this chapter. The Minlog package, which is downloadable at http://www.minlog-system.de/, contains the implemented version of this chapter. Among other examples, the directory examples/analysis/ of the Minlog package contains the files organized as follows: Section 3.2 is in ratsds.scm, Section 3.3 is in cauchysds. scm, Section 3.4 is in average. scm, Section 3.5, Section 3.6, Section 3.7, Section 3.8 are in readwrite.scm.

To conclude the introduction, we give a road map for our development. There are two dimensions in our present work. One is the extraction of algorithms in exact real arithmetic, and the other is the representation of objects in exact real arithmetic. Our material consists of real numbers and uniformly continuous functions in concrete representations. Each of them appear in two ways, namely, type- 1 and type- 0 . The type- 1 representation of real numbers and uniformly continuous functions are of function type. We review basics of exact real arithmetic of them in Section 3.1. In contrast to it, the type-0 representation of real numbers and uniformly continuous functions are of ground type, namely, of non-function types. Such ground-type representations are available via cototal ideals, which we have seen in Chapter 2.

### 3.1 Basics of Exact Real Arithmetic

In this section we illustrate exact real arithmetic, restricting to relevant material concerning our case studies in this chapter. For a comprehensive account of this field, consult the standard textbooks on constructive analysis by Bishop [Bis67] and by Bishop and Bridges BB85. A treatment of Schwichtenberg Sch06a, Sch06b, Sch12] is also relevant to study computational content from proofs via realizability interpretation.

An aim to study real arithmetic in a constructive setting is to clarify the algorithmic basis of arguments in real arithmetic. We describe an example to find a difficulty to see an algorithmic ground in the classical setting. Assume we have natural numbers, integers and rational numbers. A Cauchy real is defined to be a sequence of rational numbers $\left(a_{n}\right)_{n}$ satisfying the Cauchyness condition: $\forall_{k} \exists_{l} \forall_{n, m \geq l}\left(\left|a_{n}-a_{m}\right| \leq 2^{-k}\right)$. In this classical construction of Cauchy reals, one cannot compute a concrete $l$ from an arbitrary fixed $k$ in general. We start with constructivising the definition of Cauchy reals, such that the index $l$ of the convergence is practically computable. In this section, $k$ ranges over integers and $n$, $m$ range over natural numbers.

### 3.1.1 Real Numbers

We give a constructive definition of Cauchy reals. A problem in the classical definition of Cauchy reals is that we cannot effectively find an index to ensure the convergence of a rational sequence. We can solve this by providing an additional information to compute such an index.

Definition 3.1.1 (Cauchy reals). A pair of a sequence of rational numbers $\left(a_{n}\right)_{n}$ and a Cauchy modulus $M: \mathbb{Z} \rightarrow \mathbb{Q}$ is a Cauchy real if the following condition is satisfied.

$$
\forall_{k} \forall_{n, m \geq M(k)}\left(\left|\alpha_{n}-\alpha_{m}\right| \leq 2^{-k}\right)
$$

We consider two kinds of inequalities, $x \leq y$ and $x<y$ for Cauchy reals $x, y$. We define nonnegative Cauchy reals and positive Cauchy reals.

Definition 3.1.2 (Nonnegative and positive Cauchy reals). Let $x:=\left\langle\left(a_{n}\right)_{n}, M\right\rangle$ be a Cauchy real. Define $x \in \mathbb{R}^{0+}$ to be that $-2^{-k} \leq a_{M(k)}$ for all $k \in \mathbb{Z}$. If $x \in \mathbb{R}^{0+}, x$ is nonnegative. Also define $x \in_{k} \mathbb{R}^{+}$to be that $2^{-k} \leq a_{M\left(k_{1}\right)}$. If $x \in_{k} \mathbb{R}^{+}, x$ is $k$-positive. We can omit $k$ when there is no confusion.

By the following lemma, we can find an upper bound of a real number.
Lemma 3.1.3 (Bound of reals). For every Cauchy real $x:=\left\langle\left(a_{n}\right)_{n}, M\right\rangle$ we can find an upper bound $2^{k_{x}}$ on the elements of the Cauchy sequence: $\left|a_{n}\right| \leq 2^{k_{x}}$ for all $n$.

Proof. Let $k_{x}$ be max $\left\{\left|a_{n}\right| \mid n \leq M(0)\right\}+1 \leq 2^{k_{x}}$. Then, $\left|a_{n}\right| \leq 2^{k_{x}}$ holds for all $n$.
We use an informal lambda notation to denote an anonymous function. We can write $\lambda_{x} M$ instead of a named function $f$ defined by $f(x):=M$. We use the notation $k_{x}$ as given in Lemma 3.1.3.

Definition 3.1.4 (Arithmetic functions). For Cauchy reals $x:=\left\langle\left(a_{n}\right)_{n}, M\right\rangle$ and $y:=$ $\left\langle\left(b_{n}\right)_{n}, N\right\rangle$, we define $x+y,-x,|x|, x \cdot y$ and $x^{-1}$ (provided that $|x| \in_{l} \mathbb{R}^{+}$) as follows.

$$
\begin{aligned}
& x+y:=\left\langle\left(a_{n}+b_{n}\right)_{n}, \lambda_{k} \max (M(k+1), N(k+1))\right\rangle, \\
& -x:=\left\langle\left(-a_{n}\right)_{n}, M\right\rangle, \\
& |x|:=\langle | a_{n}|, M\rangle, \\
& x \cdot y:=\left\langle\left(a_{n} \cdot b_{n}\right)_{n}, \lambda_{k} \max \left(M\left(k+1+k_{|y|}\right), N\left(k+1+k_{|x|}\right)\right)\right\rangle, \\
& x^{-1}:=\left\langle c_{n}, \lambda_{k} M(2(l+1)+k)\right\rangle, \quad c_{n}:= \begin{cases}\left(a_{n}\right)^{-1} & \text { if } a_{n} \neq 0 \\
0 & \text { if } a_{n}=0 .\end{cases}
\end{aligned}
$$

Results of the above defined functions are indeed Cauchy reals.
Definition 3.1.5 (Inequalities of Cauchy reals). Let $x, y$ be Cauchy reals. Define $x \leq y$ by $y-x \in \mathbb{R}^{0+}$ and $x<_{k} y$ by $y-x \in_{k} \mathbb{R}^{+}$. We can omit $k$ when there is no confusion.

An important consequence in constructive real numbers is that we can not compare two reals as in the classical setting. Concretely speaking, this means that we cannot decide $x \leq y$ or $y \leq x$ for arbitrarily given $x$ and $y$. However, it is possible to compare a real with an interval [Bis67, BB85]. We give this result as the approximate split property.

Lemma 3.1.6 (Approximate split property). Let $x, y$ and $z$ be given. If $x<y$ then either $x \leq z$ or $z \leq y$.

Proof. See Bis67, BB85].
Remark 3.1.7. The algorithmic ground of the above lemma is a decision procedure which can be extracted as an executable program from the proof of the lemma if we formalize them in a suitable framework.

### 3.1.2 Uniformly Continuous Functions

We can give a constructive definition of uniformly continuous functions on a Cauchy real in the same spirit. The application of a uniformly continuous function to a Cauchy real and the composition of uniformly continuous functions are also given.

Definition 3.1.8 (Uniformly continuous functions). We define a uniformly continuous function $f: I \rightarrow \mathbb{R}$, where $I$ is a rational interval. Let $h$ be a function of $I \cap \mathbb{Q} \rightarrow \mathbb{N} \rightarrow \mathbb{Q}$, $\alpha$ be a function of $\mathbb{Z} \rightarrow \mathbb{N}, \omega$ be a function of $\mathbb{Z} \rightarrow \mathbb{N}$ and $\mu$ and $\nu$ be of $\mathbb{Q}$. A tuple $\langle h, \alpha, \omega, \mu, \nu\rangle$ defines a uniformly continuous function $f$ if the following conditions are satisfied.

$$
\begin{aligned}
& \forall_{a, k} \forall_{n, m \geq \alpha(k)}\left(|h a n-h a m| \leq 2^{-k}\right) \\
& \forall_{a, b, k} \forall_{n \geq \alpha(k)}\left(|a-b|<2^{-\omega(k)+1} \rightarrow|h a n-h b n| \leq 2^{-k}\right), \\
& \forall_{a, n}(\mu \leq h a n \leq \nu)
\end{aligned}
$$

We call $h$ a rational mapping, $\alpha$ a uniform Cauchy modulus, $\omega$ a modulus of uniform continuity and $\mu, \nu$ the lower and the upper bound of $h$, respectively. For a uniformly continuous function $f$, we let $h_{f}, \alpha_{f}, \omega_{f}, \mu_{f}$ and $\nu_{f}$ denote the the above five components, respectively.

We define application of a uniformly continuous function to a Cauchy real.
Definition 3.1.9 (Application of a uniformly continuous function). Let $f$ be a uniformly continuous function and $x:=\left\langle\left(a_{n}\right)_{n}, M\right\rangle$ be a Cauchy real. Application of $f$ to $x$, written $f(x)$, is defined to be

$$
\left\langle\left(h_{f}\left(a_{n}, n\right)\right)_{n}, \lambda_{k} \max \left(\alpha_{f}(k+2), M\left(\omega_{f}(k+1)-1\right)\right)\right\rangle .
$$

The application $f(x)$ is indeed a Cauchy real.
Lemma 3.1.10 (Application $f(x)$ is a Cauchy real). Under the assumptions of the above definition, $f(x)$ is a Cauchy real.

We define composition of uniformly continuous functions.
Definition 3.1.11 (Composition of uniformly continuous functions). Let $I, J$ be rational intervals and $f: I \rightarrow \mathbb{R}, g: J \rightarrow \mathbb{R}$ be uniformly continuous functions. Assume $\nu_{f}, \mu_{f} \in J$. The composition $g \circ f$ is defined as follows.

$$
\begin{aligned}
& h_{g \circ f}:(I \cap \mathbb{Q}) \rightarrow \mathbb{N} \rightarrow \mathbb{Q}, \quad h_{g \circ f}:=\lambda_{a, n} h_{g}\left(h_{f}(a, n), n\right), \\
& \alpha_{g \circ f}:=\lambda_{k} \max \left(\alpha_{g}(k+2), \alpha_{f}\left(\omega_{g}(k+1)-1\right)\right), \\
& \omega_{g \circ f}:=\lambda_{k} \omega_{f}\left(\omega_{g}(k)-1\right)+1, \quad \mu_{g \circ f}:=\mu_{g}, \quad \nu_{g \circ f}:=\nu_{g} .
\end{aligned}
$$

The above composition is indeed a uniformly continuous function.
Lemma 3.1.12 (Composition $g \circ f$ is a uniformly continuous function). Under the assumption of the above definition, the composition $g \circ f$ is indeed a uniformly continuous function.

### 3.2 Rational Number into Signed Digit Stream

The goal of this section is to extract from proofs programs which translate a rational number into a signed digit stream, SDS in short. The extracted program takes a rational number in $[-1,1]$ as an input, and computes an SDS representation of the input rational number. An SDS is a possibly non-well founded list of $-1,0$ and 1 . Suppose that $d_{i}$ ranges over $\{-1,0,1\}$. An SDS $d_{0}:: d_{1}:: \ldots:: d_{k-1}:: \ldots$ approximates a real number as precisely as required via rational intervals

$$
\begin{equation*}
\left[\sum_{i=0}^{n-1} \frac{d_{i}}{2^{i+1}}-\frac{1}{2^{n}}, \sum_{i=0}^{n-1} \frac{d_{i}}{2^{i+1}}+\frac{1}{2^{n}}\right] \tag{3.1}
\end{equation*}
$$

The SDS representation of real numbers is also referred to by the type-0 representation of real numbers, because signed digit streams are of ground type. A finite list $d_{0}:: d_{1}:: \ldots:: d_{k-1}::[]$ means a rational number $\sum_{i=0}^{k-1} \frac{d_{i}}{2^{i+1}}$, which is located at the center of the $k$-th interval.

We refer to the intervals $[-1,0],\left[-\frac{1}{2}, \frac{1}{2}\right]$ and $[0,1]$ by basic intervals, and denote them by $\square_{L}, \square_{M}$ and $\mathbb{\square}_{R}$, respectively. The algorithm in the extracted program is based on the procedure determining for a given real number $x \in[-1,1]$, written $x \in \mathbb{\square}$, which of the basic intervals contains $x$. Repeatedly applying this procedure to a given rational number $a$ we obtain an SDS representation of $a$.

### 3.2.1 Definitions

We start by defining algebras for our case study in rational numbers.
Definition 3.2.1 (Numbers). Algebras of positive numbers, integers and rational numbers are defined as follows.

$$
\mathbf{P}:=\mu_{\xi}\left(1^{\xi}, S_{0}^{\xi \rightarrow \xi}, S_{1}^{\xi \rightarrow \xi}\right), \quad \mathbf{Z}:=\mu_{\xi}\left(0^{\xi}, \mathbf{P}^{\mathbf{P} \rightarrow \xi}, \mathbf{N}^{\mathbf{P} \rightarrow \xi}\right), \quad \mathbf{Q}:=\mu_{\xi}\left(\#^{\mathbf{P} \rightarrow \mathbf{Z} \rightarrow \xi}\right)
$$

The constructor \# is an infix operator so that we write $i \# p$ for $p^{\mathbf{P}}$ and $i^{\mathbf{Z}}$. We assume that the rational arithmetic is already given.

Definition 3.2.2 (Totality of $\mathbf{P}, \mathbf{Z}$ and $\mathbf{Q}$ ). We define the totality predicates $T_{\mathbf{P}}$ of positive numbers, $T_{\mathbf{Z}}$ of integers and $T_{\mathbf{Q}}$ of rational numbers. The introduction and elimination axioms are as follows.

$$
\begin{array}{lcl}
T_{\mathbf{P}} 1, & \left(T_{\mathbf{P}}\right)_{0}^{+} & \forall_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow T_{\mathbf{P}}\left(\mathrm{S}_{0} p\right)\right) \\
\forall_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow T_{\mathbf{P}}\left(\mathrm{S}_{1} p\right)\right) & \left(T_{\mathbf{P}}\right)_{2}^{+} & \left(T_{\mathbf{P}}\right)_{1}^{+} \\
\forall_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow P 1 \rightarrow \forall_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow P p \rightarrow P\left(\mathrm{~S}_{0} p\right)\right) \rightarrow\right. & \\
& \left.\forall_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow P p \rightarrow P\left(\mathrm{~S}_{1} p\right)\right) \rightarrow P p\right) & \left(T_{\mathbf{P}}\right)^{-} \\
\forall_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow T_{\mathbf{Z}}(\mathrm{P} p)\right) & \left(T_{\mathbf{Z}}\right)_{0}^{+} & \left(T_{\mathbf{Z}}\right)_{1}^{+} \\
\forall_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow T_{\mathbf{Z}}(\mathrm{N} p)\right) & \left(T_{\mathbf{Z}}\right)_{2}^{+} & \\
\forall_{i}^{\mathrm{nc}}\left(T_{\mathbf{Z}} i \rightarrow{ }_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow P(\mathrm{P} p)\right) \rightarrow P 0 \rightarrow \forall_{p}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow P(\mathrm{~N} p)\right) \rightarrow P i\right) \\
\forall_{p, i}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow T_{\mathbf{Z}} i \rightarrow T_{\mathbf{Q}}(p \# i)\right), & \left(T_{\mathbf{Z}}\right)^{-} \\
\forall_{q}^{\mathrm{nc}}\left(T_{\mathbf{Q}} q \rightarrow \forall_{p, i}^{\mathrm{nc}}\left(T_{\mathbf{P}} p \rightarrow T_{\mathbf{Z}} i \rightarrow P(p \# i)\right) \rightarrow P q\right) & \left(T_{\mathbf{Q}}\right)^{+}  \tag{Q}\\
\left(T_{\mathbf{Q}}\right)^{-}
\end{array}
$$

The following algebra is used to represent SDSs.
Definition 3.2.3 (Interval algebra $\mathbf{I}$ ). We define the interval algebra $\mathbf{I}$ to be

$$
\mu_{\xi}\left(I^{\xi}, C_{L}{ }^{\xi \rightarrow \xi}, C_{M}{ }^{\xi \rightarrow \xi}, C_{R}{ }^{\xi \rightarrow \xi}\right)
$$

Cototal ideals of the algebra $\mathbf{I}$ represent SDSs. We are interested in rational numbers in $[-1,1]$. For this restriction, we define a comprehension term $Q$ of arity ( $\mathbf{Q}$ ) to mean total ideals of rational numbers in $[-1,1]$.

Definition 3.2.4 (Rational numbers in $[-1,1]$ ). We define a comprehension term $Q$ to be $\left\{a \mid T_{\mathbf{Q}} a \wedge^{1} a \in \mathbb{0}\right\}$.

We define an inductive predicate $I$ and a coinductive predicate ${ }^{\text {co } I}$ of arity (Q). Finite continued fractions of the specified form are in $I$. The companion predicate ${ }^{\text {co }} I$ contains even non-well founded continued fractions which are real numbers.

Definition 3.2.5 ( $I$ and ${ }^{\text {co }} I$ ). We inductively define a predicate $I$ of arity $(\mathbf{Q})$. Let $P$ be a predicate variable of arity $(\mathbf{Q})$. The introduction and elimination axioms are as follows.

$$
\begin{array}{lll}
I 0 & I_{0}^{+} & \forall_{a}^{\mathrm{nc}}\left(I a \rightarrow I\left(\frac{a-1}{2}\right)\right) \\
\forall_{a}^{\mathrm{nc}}\left(I a \rightarrow I\left(\frac{a}{2}\right)\right) & \forall_{a}^{\mathrm{nc}}\left(I a \rightarrow I\left(\frac{a+1}{2}\right)\right) & I_{1}^{+} \\
\\
\forall_{a}^{\mathrm{nc}}\left(I a \rightarrow P 0 \rightarrow \forall_{a}^{\mathrm{nc}}\left(I a \rightarrow P a \rightarrow P\left(\frac{a-1}{2}\right)\right) \rightarrow\right. & \\
\forall_{a}^{\mathrm{nc}\left(I a \rightarrow P a \rightarrow P\left(\frac{a}{2}\right)\right) \rightarrow \forall_{a}^{\mathrm{nc}}\left(I a \rightarrow P a \rightarrow P\left(\frac{a+1}{2}\right)\right) \rightarrow} & \\
P a) . &
\end{array}
$$

We coinductively define ${ }^{\text {co }} I$, the companion predicate of $I$. The closure and greatest-fixedpoint axioms are as follows.

$$
\begin{aligned}
& \forall_{a}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I a \rightarrow a \text { eqd } 0 \vee^{\mathrm{r}} \exists_{a_{0}}^{\mathrm{r}}\left({ }^{\mathrm{co}} I a_{0} \wedge^{1} a \text { eqd } \frac{a_{0}-1}{2}\right) \vee^{\mathrm{d}}\right. \\
& \left.\exists_{a_{0}}^{\mathrm{r}}\left({ }^{\mathrm{c} \circ} I a_{0} \wedge^{1} a \text { eqd } \frac{a_{0}}{2}\right) \vee^{\mathrm{d}} \exists_{a_{0}}^{\mathrm{r}}\left({ }^{\mathrm{co}} I a_{0} \wedge^{\mathrm{l}} a \text { eqd } \frac{a_{0}+1}{2}\right)\right) . \\
& \forall_{a}^{\mathrm{nc}}\left(P a \rightarrow \forall _ { a } ^ { \mathrm { nc } } \left(P a \rightarrow a \text { eqd } 0 \vee^{\mathrm{r}} \exists_{a_{0}}^{\mathrm{r}}\left(\left({ }^{\mathrm{co}} I a_{0} \vee^{\mathrm{d}} P a_{0}\right) \wedge^{1} a \text { eqd } \frac{a_{0}-1}{2}\right) \vee^{\mathrm{d}}\right.\right. \\
& \exists_{a_{0}}^{\mathrm{r}}\left(\left({ }^{\mathrm{co}} I a_{0} \vee^{\mathrm{d}} P a_{0}\right) \wedge^{\mathrm{I}} a \text { eqd } \frac{a_{0}}{2}\right) \vee^{\mathrm{d}} \\
& \left.\exists_{a_{0}}^{\mathrm{r}}\left(\left({ }^{\mathrm{Co}} I a_{0} \vee^{\mathrm{d}} P a_{0}\right) \wedge^{1} a \text { eqd } \frac{a_{0}}{2}\right)\right) \rightarrow \\
& \left.{ }^{\mathrm{co}} \mathrm{I} a\right) \text {, }
\end{aligned}
$$

The associated algebra of $I$ and ${ }^{c o} I$ is $\mathbf{I}$. Note that a list of signed digits, namely, an ideal of $\mathbf{I}$, suffices to represent a construction of our fractions. Some rational numbers cannot be finitely represented by our fraction. This is the reason that we make use of cototal ideals in this case study.

### 3.2.2 Proofs

From a proof of the Proposition 3.2.6 we extract a program which translates a rational number into an SDS. The proof depends on Lemma 3.2 .9 below which determines where the given rational number is located.

Proposition 3.2.6 (A rational number to an SDS). $\forall_{a}^{\mathrm{nc}}\left(Q a \rightarrow{ }^{\mathrm{co}} I a\right)$.

Proof. Let $a$ be given and assume $Q a$. Prove ${ }^{\text {co }} I a$ by ${ }^{{ }^{\text {co }} I^{+}}$,

$$
\left.\begin{array}{rl}
\forall_{a}^{\mathrm{nc}}(Q a \rightarrow & \forall_{a}^{\mathrm{nc}}(Q a \rightarrow
\end{array}\right) a \text { eqd } 0 \vee^{\mathrm{r}} \exists_{a_{0}}^{\mathrm{r}}\left(\left({ }^{\mathrm{co}} I a_{0} \vee^{\mathrm{d}} Q a_{0}\right) \wedge^{1} a \text { eqd } \frac{a_{0}-1}{2}\right) \vee^{\mathrm{d}} .
$$

It suffices to prove the second premise. Let $a$ be given and assume $Q a$. By Lemma 3.2.9, we can determine whether $a \in \mathbb{\square}_{\mathbf{L}}, a \in \mathbb{\square}_{\mathrm{M}}$ or $a \in \mathbb{\square}_{\mathbf{R}}$. If $a \in \mathbb{\square}_{\mathrm{L}}$, let $a_{0}$ be $2 a+1$. If $a \in \mathbb{\square}_{\mathrm{M}}$, let $a_{0}$ be $2 a$. If $a \in \mathbb{L}_{\mathrm{L}}$, let $a_{0}$ be $2 a-1$. In each case the equality and $Q a_{0}$ hold.

The above proof depends on the next lemmas which are proved by considering the construction of rational numbers.

Lemma 3.2.7 (Above 0 or below 0 ). $\forall_{a}^{\mathrm{nc}}\left(T_{\mathbf{Q}} a \rightarrow a \leq 0 \vee 0 \leq a\right)$.
Proof. Assume $a$ and $T_{\mathbf{Q}} a$. Using $\left(T_{\mathbf{Q}}\right)^{-}$for $T_{\mathbf{Q}} a$, it suffices to prove

$$
\forall_{i \mathbf{z}, p^{\mathbf{P}}}^{\mathrm{nc}}\left(T_{\mathbf{Z}} i \rightarrow T_{\mathbf{P}} p \rightarrow(i \# p) \leq 0 \vee 0 \leq(i \# p)\right)
$$

Let $i$ and $p$ be given and assume $T_{\mathbf{Z}} i$ and $T_{\mathbf{P}} p$. We use $\left(T_{\mathbf{Z}}\right)$ for $T_{\mathbf{Z}} i$ to prove $i \# p \leq 0 \vee 0 \leq$ $i \# p$. There are three step cases. Case $i=0$. $i \# p$ is 0 in $\mathbf{Q}$, hence the goal is trivial. Case $i=\mathrm{P} p^{\prime} . i>0$, hence $0 \leq \mathrm{P} p^{\prime} \# p$. Case $i=\mathrm{N} p^{\prime}$. $i<0$, hence $\mathrm{N} p^{\prime} \# p \leq 0$.

Lemma 3.2.8 (Comparing two rational numbers). $\forall_{a, b}^{\mathrm{nc}}\left(T_{\mathbf{Q}} a \rightarrow T_{\mathbf{Q}} b \rightarrow a \leq b \vee b \leq a\right)$.
Proof. Let $a$ and $b$ be given and assume $T_{\mathbf{Q}} a$ and $T_{\mathbf{Q}} b$. By Lemma 3.2.7 we can determine $a-b \leq 0 \vee 0 \leq a-b$. If the left disjunct holds, we prove $a \leq b$, otherwise we prove $b \leq a$. We use the fact that $T_{\mathbf{Q}}(a-b)$ holds provided that $T_{\mathbf{Q}} a$ and $T_{\mathbf{Q}} b$ hold.

Lemma 3.2.9 (Standard split of rational numbers). $\forall_{a}^{\mathrm{nc}}\left(Q a \rightarrow-1 \leq a \leq 0 \vee-\frac{1}{2} \leq a \leq\right.$ $\frac{1}{2} \vee 0 \leq a \leq 1$ ).

Proof. Let $a$ be given and assume $Q a$, namely, $a \in \mathbb{\square}$ and $T_{\mathbf{Q}} a$. By Lemma 3.2 .8 we determine $a \leq b_{0} \vee b_{0} \leq a$ for any $-\frac{1}{2} \leq b_{0} \leq 0$. Let $b_{0}$ be $-\frac{1}{3}$ in this proof. We consider two cases from the disjunction. If $a \leq-\frac{1}{3}$, we have $a \in \mathbb{\square}_{\mathrm{L}}$. If $-\frac{1}{3} \leq a$, we derive $a \leq \frac{1}{3} \vee \frac{1}{3} \leq a$ again by Lemma 3.2.8. We consider two cases. If $a \leq \frac{1}{3}, a \in \square_{\mathrm{M}}$ holds. If $\frac{1}{3} \leq a, a \in \square_{\mathrm{R}}$ holds.

From a finite segment of an SDS, we can compute a rational number which approximates the SDS. Such a program is extracted from a proof of $\forall_{a \in 0}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I a \rightarrow \forall_{n}^{\mathrm{c}} \exists_{b \in \mathbb{0}}^{1}\left(|a-b| \leq 2^{-n}\right)\right)$. The result is essentially the same as Proposition 3.3.9.

$$
\begin{aligned}
& \lambda_{a}\left({ } ^ { \mathrm { co } } \mathcal { R } a \lambda _ { b } \left(\text { if }\left(b \leq-\frac{1}{3}\right) \text { then } \operatorname{in}_{2}^{4}(\operatorname{InR}(2 b+1))\right.\right. \\
& \text { else if }\left(b \leq \frac{1}{3}\right) \text { then } \operatorname{in}_{3}^{4}(\operatorname{lnR} 2 b) \\
&\text { else } \left.\left.\operatorname{in}_{4}^{4}(\operatorname{lnR}(2 b-1))\right)\right)
\end{aligned}
$$

Figure 3.1: ratsds $^{\mathbf{Q} \rightarrow \mathbf{I}}$

### 3.2.3 Program Extraction

We extract from the proof of Proposition 3.2 .6 the program ratsds of type $\mathbf{Q} \rightarrow \mathbf{I}$ shown in Figure 3.2.3. Assume that a rational number $a$ in $[-1,1]$ is given. The corecursion operator applies the costep term to $a$, then it determines which of $a \leq-\frac{1}{3},-\frac{1}{3}<a<\frac{1}{3}$ or $\frac{1}{3} \leq a$ is the case. The result is a term of sum type $\mathbf{U}+(\mathbf{I}+\mathbf{Q})+(\mathbf{I}+\mathbf{Q})+(\mathbf{I}+\mathbf{Q})$. In our case, it is an injection of a value whether in the second, in the third or in the fourth position of the sum. Depending on where the value is, the corecursion operator chooses which constructor, i.e., $C_{L}, C_{M}$ or $C_{R}$, comes next. Since the value is always the right injection of a rational number, the unfolding can carry on with this rational number.

### 3.2.4 Experiments

A rational number -1 is translated into an SDS as follows. Let $M$ be the costep term, then ratsds( -1 ) unfolds as follows.

$$
\begin{aligned}
\text { ratsds }(-1) & \mapsto{ }^{\mathrm{co}} \mathcal{R}(-1) M \\
& \mapsto \mathrm{C}_{\mathrm{L}}\left({ }^{\mathrm{c}} \mathcal{R}(-1) M\right) \\
& \mapsto \mathrm{C}_{\mathrm{L}}\left(\mathrm{C}_{\mathrm{L}}\left({ }^{\mathrm{c}} \mathcal{R}(-1) M\right)\right) \\
& \mapsto \ldots
\end{aligned}
$$

For another rational number $\frac{11}{7}$, ratsds computes the following.

$$
\text { ratsds }(11 \# 7) \mapsto^{*} C_{R}\left(C_{R}\left(C_{M}\left(C_{M}\left(C_{R}\left(C_{M}\left(C_{M}\left(C_{R}\left(C_{M}\left(C_{M}\left({ }^{\mathrm{co}} \mathcal{R}(4 \# 7) M\right)\right)\right)\right)\right)\right)\right)\right)\right)\right)
$$

### 3.3 Representations of Real Numbers

In this section we deal with representations of real numbers of type-1 and type- 0 . The type-1 representation of real numbers is Cauchy reals which we saw in Section 3.1.1. We extract from formal proofs programs to transform a real number of type-1 into a real number of type-0, and vice versa. In contrast to Section 3.2, we are going to deal with real numbers including irrational numbers. From the technical viewpoint, we make use of abstract theory due to Berger for reasoning about real numbers, whereas our case study in Section 3.2 was based on the concrete rational numbers.

The rational numbers we used in Section 3.2 are concrete in the sense that they are ideals of the algebra Q. Notice that the rational numbers which appear in the extracted program ratsds are independent from the rational numbers which are used in predicate definitions and proofs. According to our realizability interpretation, arguments of predicates are irrelevant to realizers. Hence whatever the terms in formulas and proofs are, the extracted term is not affected by them at all. In fact, the algebra $\mathbf{Q}$ which appears in the extracted program ratsds comes from the associated algebra $\tau\left(T_{\mathbf{Q}}\right)$ in the definition of $Q$ via the realizability interpretation, but not from rational numbers in proofs. Based on this observation, the rational numbers in proofs can be something else as long as we can work consistently.

In this section, we work with the axiomatic theory of real numbers instead of a concrete one, e.g. some theory of Cauchy reals. Here we make use of the idea of abstract theories in order to formulate the axiomatic theory of real numbers. When we specify a new axiom, the realizability interpretation of the axiom should be given. If the axiom comes from an inductive or a coinductive definition, the realizer is given as a special constant. Even if this is not the case, non-computational (or Harrop) formulas are harmless as axioms because the empty term is the trivial realizer of such formulas. We refer to theories given by non-computational axiom formulas as abstract theories. We define abstract theories by using abstract types. Abstract types are just used to identify the kind of objects we are talking about, thus type variables are suitable. The use of abstract theories results in a clear separation between computational and non-computational ingredients of objects, hence it is beneficial to the implementation work as well.

### 3.3.1 Definitions

We first define constants and axioms of our abstract theory of real number, then define a coinductive predicate. The idea is to have a theory to reason about real numbers in the standard interval $[-1,1]$. We give the real number constant zero and some restricted arithmetic operation on real numbers. Then, a relation " $\in$ " is introduced in order to mean that a real number is in a rational interval.

Let $\rho$ be an abstract type of real numbers. The algebras $\mathbf{N}, \mathbf{S D}, \mathbf{Q}$ and etc. are all defined in Section 2.1. The totality predicate of $\mathbf{S D}$ is needed.

Definition 3.3.1 (The totality predicate of $\mathbf{S D}$ ). Define $T_{\text {SD }}$, the totality predicate of $\mathbf{S D}$, to be $\mu_{X}(X \mathrm{~L}, X \mathrm{M}, X \mathrm{R})$. Its introduction and elimination axiom are as follows.

$$
\begin{array}{ccc}
T_{\mathbf{S D}} \mathrm{L} & \left(T_{\mathbf{S D}}\right)_{0}^{+} & T_{\mathbf{S D}} \mathrm{M} \\
T_{\mathbf{S D}} \mathrm{R} & \left(T_{\mathbf{S D}}\right)_{2}^{+} & \left(T_{\mathbf{S D}}\right)_{1}^{+} \\
& & \\
& \forall_{d}^{\mathrm{nc}}\left(T_{\mathbf{S D}} d \rightarrow P \mathrm{~L} \rightarrow P \mathrm{M} \rightarrow P \mathrm{R} \rightarrow P d\right) & \left(T_{\mathbf{S D}}\right)^{-}
\end{array}
$$

Suppose that $a$ ranges over $\mathbf{Q}, n$ ranges over $\mathbf{N}, d$ ranges over $\mathbf{S D}$ and $x, y$ range over abstract real numbers of type $\rho$.

Definition 3.3.2 (Z). Z is a constant of type $\rho$.
We have the following arithmetic operations on $\rho$.
Definition 3.3.3 $\left.\frac{x+d}{2}, 2 x-d\right)$. Let $x$ and $d$ be of type $\rho$ and SD, respectively. $\frac{x+d}{2}$ and $2 x-d$ are terms of type $\rho$.

Definition 3.3.4 $\left(x \in \mathbb{\square}_{a, n}\right)$. Let $x, a$ and $n$ be of type $\rho, \mathbf{Q}$ and $\mathbf{N}$, respectively, then $x \in \mathbb{\square}_{a, n}$ is a term of type $\mathbf{B}$. We abbreviate $x \in \mathbb{\square}_{0,0}$ and $x \in \mathbb{\square}_{\frac{d}{2}, 1}$ by $x \in \mathbb{\mathbb { C }}$ and $x \in \mathbb{\square}_{d}$, respectively.

Intuitively, $x \in \mathbb{\square}_{a, n}$ means $a-2^{-n} \leq x \leq a+2^{-n}$. We refer to $\mathbb{\square}_{d}$ by basic intervals.
Suppose that $\leq$ is the "equal or less than" relation on $\mathbf{Q}$ and eqd is the Leibniz equality. In formulas, we identify terms $t$ of type $\mathbf{B}$ and the Leibniz equality $t$ eqd $\mathbf{T}$. The axioms of the abstract theory of real numbers are given as follows. Recall that the signed digits are taken to be integers, e.g. $M$ to be 0 .

Axiom 3.3.5 (Abstract Real Numbers).

$$
\begin{align*}
& \forall_{x}(x \in \mathbb{C}) \text {, }  \tag{RealBound}\\
& \frac{\mathrm{Z}+\mathrm{M}}{2} \text { eqd } \mathrm{Z} \text {. }  \tag{AvZero}\\
& \forall_{x, a}\left(a \leq-\frac{1}{4} \rightarrow x \in \mathbb{\square}_{a, 2} \rightarrow x \in \mathbb{\square}_{\mathrm{L}}\right),  \tag{RealLeft}\\
& \forall_{x, a}\left(-\frac{1}{4} \leq a \leq \frac{1}{4} \rightarrow x \in \mathbb{\square}_{a, 2} \rightarrow x \in \mathbb{\square}_{\mathrm{M}}\right),  \tag{RealMiddle}\\
& \forall_{x, a}\left(\frac{1}{4} \leq a \rightarrow x \in \mathbb{\square}_{a, 2} \rightarrow x \in \mathbb{\square}_{\mathrm{R}}\right), \\
& \forall_{x, d}\left(x \in \mathrm{\square}_{d} \rightarrow x \text { eqd } \frac{(2 x-d)+d}{2}\right), \\
& \forall x, d, a, n\left(x \in \mathbb{\square}_{d} \rightarrow x \in \mathbb{\square}_{a, n+1} \rightarrow 2 x-d \in \mathbb{\square}_{2 a-d, n}\right), \\
& \forall_{x, d, a, n}\left(x \in \rrbracket_{a, n} \rightarrow \frac{x+d}{2} \in \square_{\frac{a+d}{2}, n+1}\right) .
\end{align*}
$$

Notice that all formulas of Axiom 3.3.5 are non-computational.
We consider real numbers in the interval $[-1,1]$. This is characterized by (REALBOUND). The property of the constant Z is given by AvZERO. Informally, it means $\frac{0+0}{2}=0$ as we commonly expect. The properties of the relation $x \in \square_{a, n}$ come from the rest of the axioms. The three axioms, (REALLEFT), (REALMIDDLE) and (REALRIGHT), characterize the relation between a real number and an interval. In each case, a basic interval is decided from the center $a$ of the rational interval $\square_{a, n}$. Since $a$ is a rational number, the inequalities in the first premises of the axioms are decidable. The last three axioms, AvVAIDENT, (VAINTRO) and AVINTRO, characterize the properties of the arithmetic operations which also interact with rational intervals.

There is no computational content in abstract real numbers, but there is in the coinductively defined predicate ${ }^{\text {co } I}$. Due to the realizability interpretation, the argument of the predicate ${ }^{\text {co } I} I$ is discarded by program extraction. The associated algebra of ${ }^{\text {co }} I$ is $\mathbf{I}$, a cototal ideal of which represents a real number in $[-1,1]$ through an SDS. The following definition differs from Definition 3.2.3 in the use of abstract real numbers.

Definition 3.3.6 $\left({ }^{\mathrm{co}} I\right)$. Define a coinductive predicate ${ }^{\text {co } I}$ of arity $(\rho)$ to be

$$
\nu_{X}\left(X \mathrm{Z}, \forall_{x}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(X x \rightarrow^{\mathrm{c}} X\left(\frac{x+d}{2}\right)\right)\right)
$$

The closure and greatest-fixed-point axioms are as follows.

$$
\begin{array}{ll}
\forall_{x}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I x \rightarrow x \text { eqd } \mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left({ }^{\mathrm{co}} I y \wedge^{1} x \text { eqd } \frac{y+d}{2}\right)\right), & { }^{\mathrm{co}} I^{-} \\
\forall_{x}^{\mathrm{nc}}\left(P x \rightarrow \forall_{x}^{\mathrm{nc}}\left(P x \rightarrow x \text { eqd } \mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{1} x \text { eqd } \frac{y+d}{2}\right)\right) \rightarrow{ }^{\mathrm{co}} I x\right) . & { }^{\mathrm{co}} I^{+}
\end{array}
$$

This coinductively defined predicate ${ }^{\text {co } I}$ tells us the approximability of abstract real numbers via intervals.

### 3.3.2 Proofs

We prove two main propositions. From the proofs of the propositions, we will extract translators from a fast Cauchy real into an SDS and vice versa. Here, a fast Cauchy real is a Cauchy real whose Cauchy modulus is the identity function.

Let an abstract real number $x$ be given. The premise of the first proposition claims that for any given precision $n$, there is a rational number $a$ which approximates the $x$. The proof depends on Lemma 3.3.8 which we prove later.

Proposition 3.3.7 (Cauchy to SDS). $\forall_{x}^{\mathrm{nc}}\left(\forall_{n}^{\mathrm{c}} \exists_{a}^{1}\left(x \in \square_{a, n}\right) \rightarrow{ }^{\mathrm{co}} I x\right)$.
Proof. Let $x$ be given and assume $\forall_{n}^{\mathrm{c}} \exists_{a}^{\mathrm{l}}\left(x \in \square_{a, n}\right)$. Define the competitor predicate $Q=$
 $x$ eqd $Z \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{(\mathrm{co}} I y \vee^{\mathrm{d}} Q y\right) \wedge^{1} x\right.$ eqd $\left.\left.\frac{y+d}{2}\right)\right)$. Let $x$ be given and assume $Q x$, i.e., $\forall_{n}^{\mathrm{c}} \exists_{a}^{\mathrm{l}}\left(x \in \mathbb{\square}_{a, n}\right)$, hence $\exists_{a}^{1}\left(x \in \square_{a, 2}\right)$ which then yields some $d^{\prime}$ such that $x \in \square_{d^{\prime}}$ by Lemma 3.3.8. We prove the right disjunct of the goal. Apply $\left(\exists^{\mathrm{r}}\right)^{+}$and $\left(\exists^{\mathrm{d}}\right)^{+}$with $2 x-d^{\prime}$ and $d^{\prime}$, respectively. For the left conjunct, we prove the right disjunct $Q\left(2 x-d^{\prime}\right)$, i.e., $\forall_{n}^{\mathrm{c}} \exists_{a}^{1}\left(2 x-d^{\prime} \in \square_{a, n}\right)$. Let $n_{0}$ be given, then $Q x$ implies that there is some $a_{0}$ such that $x \in \square_{a_{0}, n_{0}+1}$. By (VAINTRO, $2 x-d^{\prime} \in \mathbb{\square}_{2 a_{0}-d^{\prime}, n_{0}}$ holds, hence $\exists_{a}^{1}\left(2 x-d^{\prime} \in \square_{a, n_{0}}\right)$ as we desired. For the right conjunct use AVVAIDENT).

Lemma 3.3 .8 claims the following. Suppose that a real number $x \in[-1,1]$ is covered by a rational interval $\left[a-\frac{1}{4}, a+\frac{1}{4}\right]$. Then, we can determine a basic interval which covers $x$.

Lemma 3.3.8. $\forall_{x}^{\mathrm{nc}}\left(\exists_{a}^{1}\left(x \in \square_{a, 2}\right) \rightarrow \exists_{d}^{1}\left(x \in \square_{d}\right)\right)$.
Proof. Let $x$ be given and assume $\exists_{a}^{1}\left(x \in \square_{a, 2}\right)$, which yields some rational number $a$ such that $x \in \mathbb{\square}_{a, 2}$ holds. Because it is decidable which of $a \leq-\frac{1}{4},-\frac{1}{4} \leq a \leq \frac{1}{4}$ or $\frac{1}{4} \leq a$ holds by Lemma 3.2.8, we find a $d$ for the conclusion. For example if $a \leq-\frac{1}{4}, x \in \mathbb{\square}_{\mathbf{L}}$ holds by (REALLEFT). Recall that $\exists_{a}^{1} A$ abbreviates $\exists_{a}^{\mathrm{r}}\left(T_{\mathbf{Q}} a \wedge^{1} A\right)$.

From a proof of the converse of Proposition 3.3.7, we can extract a program which translates an SDS into a Cauchy real.

Proposition 3.3.9 (SDS to Cauchy). $\forall_{x}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I x \rightarrow \forall_{n}^{\mathrm{c}} \exists_{a}^{\mathrm{l}}\left(x \in \mathbb{\square}_{a, n}\right)\right)$.
Proof. The proposition is same as $\forall_{n}^{\mathrm{c}} \forall_{x}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I x \rightarrow \exists_{a}^{\mathrm{l}}\left(x \in \mathbb{\square}_{a, n}\right)\right)$. We prove by induction on $n$. Case $n=0$. Let $x$ be given and assume ${ }^{\text {co }} I x$. To prove $\exists_{a}^{1}\left(x \in \square_{a, 0}\right)$, let $a$ be 0 . Then $x \in \mathbb{\square}_{0,0}$ by (REALBOUND). Case $n \mapsto n+1$. Assume the induction hypothesis $\forall_{x}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I x \rightarrow \exists_{a}^{\mathrm{l}}\left(x \in \mathbb{\square}_{a, n}\right)\right)$. We prove $\forall_{x}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I x \rightarrow \exists_{a}^{\mathrm{l}}\left(x \in \square_{a, n+1}\right)\right)$. Let $x$ be given and assume ${ }^{\mathrm{co}} I x$, then ${ }^{\text {co }} I^{-}$implies $x$ eqd $\mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left({ }^{\mathrm{co}} I y \wedge^{1} x\right.$ eqd $\left.\frac{y+d}{2}\right)$. For the left case, suppose that $x$ eqd $Z$. By the induction hypothesis there is $a_{0}$ such that $\mathrm{Z} \in \square_{a_{0}, n}$. Using AvINTRO with $M, \frac{Z+M}{2} \in \square_{\frac{a_{0}+M}{2}, n+1}$ holds. Then the conclusion is trivial by AVZERO. For the right case, there are $y$ and $d$ such that $x$ eqd $\frac{y+d}{2}$ and ${ }^{\text {co }} I y$. By the induction hypothesis, there is an $a^{\prime}$ such that $y \in \mathbb{I}_{a^{\prime}, n}$. By AVINTRO, $\frac{y+d}{2} \in \mathbb{\square}_{\frac{a^{\prime}+d}{2}, n+1}$, hence the goal, $\exists_{a}^{1}\left(x \in \mathbb{\square}_{a, n+1}\right)$.

### 3.3.3 Program Extraction

We extract from the proof of Proposition 3.3.7 a program cauchysds which translates a fast Cauchy real into a signed digit stream. Corresponding to the use of Lemma 3.3.8 in the proof of the proposition, there is another program $L$, which is extracted from the lemma, appearing inside of cauchysds. By convention, we denote a fast Cauchy real of type $\mathbf{N} \rightarrow \mathbf{Q}$ by $x$. Note that variables of abstract type $\rho$ are discarded by program extraction, hence don't appear in extracted terms at all. The extracted programs cauchysds and L are shown in Figure 3.2. In cauchysds, the given fast Cauchy real $x$ is passed to the corecursion

$$
\begin{aligned}
& \text { cauchysds }=\lambda_{x^{\mathrm{N} \rightarrow \mathbf{Q}}}\left({ }^{\mathrm{co}} \mathcal{R}_{\mathbf{I}}^{\mathbf{N} \rightarrow \mathbf{Q}} x \lambda_{x}\left(\operatorname{lnR}\left\langle\mathrm{~L} x, \operatorname{lnR}\left(\lambda_{n}(2 x(n+1)-\mathrm{L} x)\right)\right\rangle\right)\right) \\
& \mathrm{L}=\lambda_{x}\left(\text { Case }\left(x(2)+\frac{1}{4}\right)\right. \text { of } \\
& i_{0} \# p \rightarrow \text { Case } i_{0} \text { of } \\
& \text { P } p_{0} \rightarrow \text { Case }\left(x(2)-\frac{1}{4}\right) \text { of } \\
& i_{1} \# p_{0} \rightarrow \text { Case } i_{1} \text { of } \\
& \text { P } p_{1} \rightarrow \mathrm{R} \\
& 0 \rightarrow \mathrm{M} \\
& \mathrm{~N} p_{1} \rightarrow \mathrm{M} \\
& 0 \rightarrow \mathrm{~L} \\
& \left.\mathrm{~N} p_{0} \rightarrow \mathrm{~L}\right)
\end{aligned}
$$

Figure 3.2: cauchysds ${ }^{(\mathbf{N} \rightarrow \mathbf{Q}) \rightarrow \mathbf{I}}$ and $\mathrm{L}^{(\mathbf{N} \rightarrow \mathbf{Q}) \rightarrow \mathbf{S D}}$
operator. When the corecursion operator unfolds, this $x$ is given to the costep term which computes a term of type $\mathbf{U}+\mathbf{S D} \times(\mathbf{I}+(\mathbf{N} \rightarrow \mathbf{Q}))$, where the actual values are injected in the positions of $\mathbf{S D}$ and $\mathbf{N} \rightarrow \mathbf{Q}$. As we will see, L determines from the given $x$ a signed digit $d$ such that $x \in \square_{d}$. By using this signed digit, the corecursion operator outputs this $d$
as the head of the SDS and carries on with the fast Cauchy real $\lambda_{n}(2 x(n+1)-d)$ for the next step. This Cauchy real is intended to take a closer look at $x$.

In L , for the given fast Cauchy real $x$ it determines if either $x \in \mathbb{\square}_{\mathrm{L}}, x \in \mathbb{\square}_{\mathrm{M}}$ or $x \in \mathbb{\square}_{\mathrm{R}}$. The procedure of L is based on rational number reasoning. The given fast Cauchy real $x$ is applied to 2 , then it results in a rational number, say $a$. This $a$ approximates $x$ with an error of at most $2^{-2}$. In other words, $x$ is covered by a rational interval of length $\frac{1}{2}$ whose center is $a$. Whatever the center $a$ is, we can find a basic interval which covers $x$. This is computed by testing $a \leq-\frac{1}{4}$ and $\frac{1}{4} \leq a$.

$$
\begin{array}{ll}
\text { sdscauchy }=\lambda_{v^{\mathbf{I}}, n^{\mathbf{N}}}\left(\mathcal{R}_{\mathbf{N}}^{\mathbf{I} \rightarrow \mathbf{Q}} n\right. \\
& \lambda_{u} 0 \\
& \lambda_{m, f, u}\left(\operatorname{Case}\left(\mathcal{D}_{\mathbf{I}} u\right) \text { of } \operatorname{lnL} \mathrm{U} \rightarrow 0\right. \\
& \left.\quad \operatorname{lnR} y^{\mathbf{S D} \times \mathbf{I}} \rightarrow \frac{f\left(\pi_{1} y\right)+\pi_{0} y}{2}\right)
\end{array}
$$

Figure 3.3: sdscauchy
As shown in Figure 3.3, we extract from the proof of Proposition 3.3.9 a program sdscauchy which translates a signed digit stream into a fast Cauchy real. Informally speaking, this program computes from the given $\operatorname{SDS} d s=d_{0}:: d_{1}:: \ldots:: d_{n}:: \ldots$ the following.

$$
\lambda_{n} \sum_{i=0}^{n}\left(\frac{d_{i}}{2^{i+1}}\right)
$$

Suppose that an SDS $d s$ and a natural number $n$ is given, then it computes the rational approximation of the given SDS by recursion on $n$. In one recursion step it destructs $d s$ and observes nothing or a pair of $d$ and $d s^{\prime}$, namely, the head and the tail of $d s$. In the former case it results in 0 . In the latter case, we first assume that the previous value $p$ of the recursion is available, then it computes $\frac{p+d}{2}$ where $d$ is viewed as an integer.

### 3.3.4 Experiments

We define the square root of a rational number by recursion, then translate them into SDS by means of cauchysds. The following function sqrt computes a Cauchy real of the square root of a rational number with a modulus $M n:=n+1$.

$$
\begin{aligned}
& \text { sqrt }: \mathbf{Q} \rightarrow \mathbf{N} \rightarrow \mathbf{Q} \\
& \text { sqrt }:=\lambda_{a, n}\left(\mathcal{R}_{\mathbf{N}} n 1 \lambda_{-b}\left(\frac{b+\frac{a}{b}}{2}\right)\right)
\end{aligned}
$$

The Cauchy reals representing $\sqrt{\frac{1}{2}}$ and $\sqrt{\frac{1}{3}}$ are defined to be sqrt $\frac{1}{2}$ and sqrt $\frac{1}{3}$, respectively. By means of cauchysds, they are translated into SDSs as follows:

$$
\begin{aligned}
& \text { cauchysds(sqrt } \left.\frac{1}{2}\right)=\mathrm{R}:: \mathrm{R}:: \mathrm{M}:: \mathrm{L}:: \mathrm{R}:: \mathrm{L}:: \mathrm{M}:: \mathrm{R}:: \mathrm{M}:: \mathrm{M}:: \ldots, \\
& \text { cauchysds(sqrt } \left.\frac{1}{3}\right)=\mathrm{R}:: \mathrm{M}:: \mathrm{R}:: \mathrm{L}:: \mathrm{M}:: \mathrm{R}:: \mathrm{M}:: \mathrm{M}:: \mathrm{M}:: \mathrm{L}:: \ldots .
\end{aligned}
$$

It has taken around a minute to compute the first 20 digits on the author's computer. In the opposite direction, sdscauchy computes a Cauchy real from an SDS. We give the first digits from the above results and 20 to sdscauchy.

$$
\begin{aligned}
& \text { sdscauchy ("the first digits of } \sqrt{\frac{1}{2}} \text { ") } 20=741455 \# 1048576 \\
& \text { sdscauchy ("the first digits of } \sqrt{\frac{1}{3}} \text { ") } 20=151349 \# 262144
\end{aligned}
$$

As specified in Proposition 3.3.9, the results are rational approximations with the numerical error less than $2^{-20}$.

$$
\begin{aligned}
& \left|\frac{741455}{1048576}-\sqrt{\frac{1}{2}}\right|=1.90915 \ldots \times 10^{-7}<2^{-20} \\
& \left|\frac{151349}{262144}-\sqrt{\frac{1}{3}}\right|=3.47265 \ldots \times 10^{-7}<2^{-20}
\end{aligned}
$$

### 3.4 Average

We develop elementary arithmetic in exact real numbers via program extraction. Instead addition of two real numbers, we rather consider the average of two real numbers so that the operation is closed in the interval $[-1,1]$. The program of average comes from a proof of the following proposition

$$
\begin{equation*}
\forall_{x, y}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I x \rightarrow{ }^{\mathrm{co}} I y \rightarrow{ }^{\mathrm{co}} I\left(\frac{x+y}{2}\right)\right) . \tag{3.2}
\end{equation*}
$$

The extracted term, which is of type $\mathbf{I} \rightarrow \mathbf{I} \rightarrow \mathbf{I}$, computes an average of two SDSs. For the brevity, assume two input $d s$ and $e s$ of type $\mathbf{I}$ are of the form $d_{0}:: d_{1}:: d_{2}:: \ldots$ and $e_{0}:: e_{1}:: e_{2}:: \ldots$, respectively. The average $\tilde{d}_{0}:: \tilde{d}_{1}:: \tilde{d}_{2}:: \ldots$ is computed by the extracted program step by step from the left end, i.e., $\tilde{d}_{0}$, to the right digits. Here we introduce notations. Consider an SDS $d s=d_{0}:: d_{1}:: d_{2}:: \ldots$ Then, $d s_{0}$ and $d s^{\prime}$ stand for the head $d_{0}$ and the tail $d_{1}:: d_{2}:: \ldots$, respectively. Also the $n$-th tail can be written as $d s^{(n)}$ instead of using "'"" for $n$ times. Firstly, it computes $i_{0}:=d_{0}+e_{0} \in[-2,2]$. We call this $i_{0}$ the 0 -th carry. Secondly, the corecursive step computes from $i_{0}$, $d s^{\prime}$ and $e s^{\prime}$ the following four values: a digit $\tilde{d}_{0}$, the next carry $i_{1}, d s^{\prime \prime}$ and $e s^{\prime \prime}$. The last three outputs are the inputs for the next corecursion step. In general, $i_{n}, d s^{n+1}$ and $e s^{n+1}$ are given as inputs to the corecursive step.

### 3.4. Average

We determine $\tilde{d}_{n}$ and $i_{n+1}$ in the following way:

$$
\begin{align*}
\tilde{d}_{n} & =\left\{\begin{array}{ll}
-1 & \text { if }-6 \leq d_{n+1}+e_{n+1}+2 i_{n} \leq-2 \\
0 & \text { if }-2 \leq d_{n+1}+e_{n+1}+2 i_{n} \leq 2 \\
1 & \text { if } 2 \leq d_{n+1}+e_{n+1}+2 i_{n} \leq 6
\end{array},\right.  \tag{3.3}\\
i_{n+1} & =d_{n+1}+e_{n+1}+2 i_{n}-4 \tilde{d}_{n} . \tag{3.4}
\end{align*}
$$

It is explained by considering intervals. To determine the first digit $\tilde{d}_{0}$, it is insufficient just to read off $d_{0}$ and $e_{0}$. A counter example is the inputs $1:: \ldots$ and $0:: \ldots$ which indicate two intervals $[0,1]$ and $\left[-\frac{1}{2}, \frac{1}{2}\right]$. Their average is somewhere in an approximated interval $\left[-\frac{1}{4}, \frac{3}{4}\right]$. However, we cannot determine the first digit $\tilde{d}_{0}$ because neither of the basic intervals, i.e., $[-1,0]$, $\left[-\frac{1}{2}, \frac{1}{2}\right]$, and $[0,1]$, can approximate such a real number. It suffices to use five distinctive tokens to memorize this 1-length interval. The carry $i_{0}:=d_{0}+e_{0} \in[-2,2]$ is responsible for it.


Figure 3.4: Intervals indicated by a carry $i_{n} \in\{-2,-1,0,1,2\}$.
From now we take a look at our corecursive part. The average is approximated by $\frac{1}{2}$-length interval by reading off the digits once more from the two streams. This interval is represented by an integer $k_{0}:=d_{1}+e_{1}+2 i_{0} \in[-6,6]$. For example, assume $i_{0}=-2$,

$$
\begin{aligned}
& k_{n}=-2 \longrightarrow \\
& k_{n}=-3 \\
& k_{n}=-4 \square \\
& k_{n}=-5 \square \\
& k_{n}=-6 \longrightarrow
\end{aligned}
$$

Figure 3.5: Intervals indicated by $k_{n}$ for the case $i_{n}=-2$.
then the left most case happens if both of $d_{1}$ and $e_{1}$ are -1 . There are five cases from
the combinations of $d_{1}$ and $e_{1}$. It is then possible to determine $\tilde{d}_{0}$ meaning either of $[-1,0],\left[-\frac{1}{2}, \frac{1}{2}\right]$ or $[0,1]$. We formalized this procedure to compute $\tilde{d}_{n}$ in (3.3). For further computation we reuse this corecursive part by mapping a $\frac{1}{2}$-length interval indicated by $k_{0}$ into a 1-length interval. It is done by applying $\operatorname{Out}_{\tilde{d}_{0}}(x):=2 x-\tilde{d}_{0}$. We find an $i_{1}$ which corresponds to the expected 1-length interval. For example in the case of $\tilde{d}_{0}=-1$, Out ${ }_{-1}(x)$ maps each $\frac{1}{2}$-length interval indicated by $k_{0} \in[-6,-2]$ into a 1-length interval indicated by $i_{1} \in[-2,2]$, where $i_{1}=k_{0}-4 \cdot(-1)$. We formalized this procedure to compute $i_{n+1}$ in (3.4).

### 3.4.1 Definitions

According to our informal idea, the following extended signed digits suffice to be the carries.
Definition 3.4.1 (Extended signed digits).

$$
\mathrm{SD}_{2}=\mu_{\xi}\left(\mathrm{LL}^{\xi}, \mathrm{LT}^{\xi}, \mathrm{MT}^{\xi}, \mathrm{RT}^{\xi}, \mathrm{RR}^{\xi}\right)
$$

We define the addition on $\mathbf{S D}$ in $\mathbf{S D}_{2}$. Intuitively, it is clear by considering $\mathbf{S D}$ and $\mathbf{S D}_{2}$ in integers, $\{-1,0,1\}$ and $\{-2,-1,0,1,2\}$, respectively. Formally, we define the following function JOne.

Definition 3.4.2 (JOne).

$$
\begin{array}{lll}
\text { JOne }: S D \rightarrow S D \rightarrow S D_{2} & \\
\operatorname{JOne}(\mathrm{~L}, \mathrm{~L}):=\mathrm{LL}, & \operatorname{JOne}(\mathrm{~L}, \mathrm{M}):=\mathrm{LT}, & \mathrm{JOne}(\mathrm{~L}, \mathrm{R}):=\mathrm{MT}, \\
\operatorname{JOne}(\mathrm{M}, \mathrm{~L}):=\mathrm{LT}, & \operatorname{JOne}(\mathrm{M}, \mathrm{M}):=\mathrm{MT}, & \mathrm{JOne}(\mathrm{M}, \mathrm{R}):=\mathrm{RT}, \\
\operatorname{JOne}(\mathrm{R}, \mathrm{~L}):=\mathrm{MT}, & \operatorname{JOne}(\mathrm{R}, \mathrm{M}):=\mathrm{RT}, & \mathrm{JOne}(\mathrm{R}, \mathrm{R}):=\mathrm{RR} .
\end{array}
$$

We abuse the common notation of addition + for JOne.
We formalize the idea depicted in the introduction of this section. For the given $d, e$ and $i$, we compute $d+e+2 i=: k \in[-6,6]$ which indicate an interval of length $\frac{1}{2}$, and we then determine $d^{\prime}$ and $j$ for the next step. That idea yields the definitions of the following function $J$ and $D$. In arithmetic formula, $J^{\prime}$ and $D^{\prime}$ can also be defined for the same purpose.

$$
\begin{aligned}
& J^{\prime}: \mathbf{Z} \rightarrow \mathbf{Z}, \quad D^{\prime}: \mathbf{Z} \rightarrow \mathbf{Z} \\
& J^{\prime}(k):=\text { if }(|k| \bmod 4=3) \text { then }(-\operatorname{sg} k) \text { else }(\operatorname{sg} k) \cdot(|k| \bmod 4) \\
& D^{\prime}(k):=\text { if }|k| \leq 2 \text { then } 0 \text { else }(\operatorname{sg} k) \\
& \operatorname{sg}(k):= \begin{cases}-1 & k<0 \\
0 & k=0 \\
1 & k>0\end{cases}
\end{aligned}
$$

We define functions $J$ and $D$.

Definition 3.4.3 ( $J$ and $D$ ). Define functions $J$ and $D$ of the following types,

$$
\begin{aligned}
& J: \mathbf{S D} \rightarrow \mathbf{S D} \rightarrow \mathbf{S D}_{2} \rightarrow \mathbf{S D}_{2}, \\
& D: \mathbf{S D} \rightarrow \mathbf{S D} \rightarrow \mathbf{S D}_{2} \rightarrow \mathbf{S D},
\end{aligned}
$$

as shown in Figure 3.6 and Figure 3.7, respectively.

| $J(\mathrm{~L}, \mathrm{~L}, \mathrm{LL}):=\mathrm{LL}$ | $J(\mathrm{M}, \mathrm{L}, \mathrm{LL}):=\mathrm{LT}$ | $J(\mathrm{R}, \mathrm{L}, \mathrm{LL}):=\mathrm{MT}$ |
| :--- | :--- | :--- |
| $J(\mathrm{~L}, \mathrm{~L}, \mathrm{LT}):=\mathrm{MT}$ | $J(\mathrm{M}, \mathrm{L}, \mathrm{LT}):=\mathrm{RT}$ | $J(\mathrm{R}, \mathrm{L}, \mathrm{LT}):=\mathrm{LL}$ |
| $J(\mathrm{~L}, \mathrm{~L}, \mathrm{MT}):=\mathrm{LL}$ | $J(\mathrm{M}, \mathrm{L}, \mathrm{MT}):=\mathrm{LT}$ | $J(\mathrm{R}, \mathrm{L}, \mathrm{MT}):=\mathrm{MT}$ |
| $J(\mathrm{~L}, \mathrm{~L}, \mathrm{RT}):=\mathrm{MT}$ | $J(\mathrm{M}, \mathrm{L}, \mathrm{RT}):=\mathrm{RT}$ | $J(\mathrm{R}, \mathrm{L}, \mathrm{RT}):=\mathrm{RR}$ |
| $J(\mathrm{~L}, \mathrm{~L}, \mathrm{RR}):=\mathrm{RR}$ | $J(\mathrm{M}, \mathrm{L}, \mathrm{RR}):=\mathrm{LT}$ | $J(\mathrm{R}, \mathrm{L}, \mathrm{RR}):=\mathrm{MT}$ |
| $J(\mathrm{~L}, \mathrm{M}, \mathrm{LL}):=\mathrm{LT}$ | $J(\mathrm{M}, \mathrm{M}, \mathrm{LL}):=\mathrm{MT}$ | $J(\mathrm{R}, \mathrm{M}, \mathrm{LL}):=\mathrm{R} T$ |
| $J(\mathrm{~L}, \mathrm{M}, \mathrm{LT}):=\mathrm{RT}$ | $J(\mathrm{M}, \mathrm{M}, \mathrm{LT}):=\mathrm{LL}$ | $J(\mathrm{R}, \mathrm{M}, \mathrm{LT}):=\mathrm{LT}$ |
| $J(\mathrm{~L}, \mathrm{M}, \mathrm{MT}):=\mathrm{LT}$ | $J(\mathrm{M}, \mathrm{M}, \mathrm{MT}):=\mathrm{MT}$ | $J(\mathrm{R}, \mathrm{M}, \mathrm{MT}):=\mathrm{R} T$ |
| $J(\mathrm{~L}, \mathrm{M}, \mathrm{RT}):=\mathrm{RT}$ | $J(\mathrm{M}, \mathrm{M}, \mathrm{RT}):=\mathrm{RR}$ | $J(\mathrm{R}, \mathrm{M}, \mathrm{RT}):=\mathrm{LT}$ |
| $J(\mathrm{~L}, \mathrm{M}, \mathrm{RR}):=\mathrm{LT}$ | $J(\mathrm{M}, \mathrm{M}, \mathrm{RR}):=\mathrm{MT}$ | $J(\mathrm{R}, \mathrm{M}, \mathrm{RR}):=\mathrm{RT}$ |
| $J(\mathrm{~L}, \mathrm{R}, \mathrm{LL}):=\mathrm{MT}$ | $J(\mathrm{M}, \mathrm{R}, \mathrm{LL}):=\mathrm{RT}$ | $J(\mathrm{R}, \mathrm{R}, \mathrm{LL}):=\mathrm{LL}$ |
| $J(\mathrm{~L}, \mathrm{R}, \mathrm{LT}):=\mathrm{LL}$ | $J(\mathrm{M}, \mathrm{R}, \mathrm{LT}):=\mathrm{LT}$ | $J(\mathrm{R}, \mathrm{R}, \mathrm{LT}):=\mathrm{MT}$ |
| $J(\mathrm{~L}, \mathrm{R}, \mathrm{MT}):=\mathrm{MT}$ | $J(\mathrm{M}, \mathrm{R}, \mathrm{MT}):=\mathrm{RT}$ | $J(\mathrm{R}, \mathrm{R}, \mathrm{MT}):=\mathrm{RR}$ |
| $J(\mathrm{~L}, \mathrm{R}, \mathrm{RT}):=\mathrm{RR}$ | $J(\mathrm{M}, \mathrm{R}, \mathrm{RT}):=\mathrm{LT}$ | $J(\mathrm{R}, \mathrm{R}, \mathrm{RT}):=\mathrm{MT}$ |
| $J(\mathrm{~L}, \mathrm{R}, \mathrm{RR}):=\mathrm{MT}$ | $J(\mathrm{M}, \mathrm{R}, \mathrm{RR}):=\mathrm{RT}$ | $J(\mathrm{R}, \mathrm{R}, \mathrm{RR}):=\mathrm{RR}$ |

Figure 3.6: Function $J$
Based on concrete rational numbers and integers, we define the abstract theory of average.

Axiom 3.4.4 (Abstract theory of average). Suppose that $+_{\mathrm{z}}$ is the addition on $\mathbf{Z}$. We define the axioms of the abstract theory of average as follows.

$$
\begin{array}{ll}
\frac{x+k}{2}+l=\frac{x+(k+\mathbf{z} 2 l)}{2}, & x+0=x, \\
\frac{x+k}{4}+l=\frac{x+(k+\mathbf{z} 4 l)}{4}, & 0+y=y, \\
\frac{x+k}{2}+\frac{y+l}{2}=\frac{(x+y)+(k+\mathbf{z} l)}{4}, & \frac{0}{2}=0, \\
k+l=k+\mathbf{z} l, & \frac{2 k}{2}=k .
\end{array}
$$

In the proof, while we use equations in Axiom 3.4.4 in order to replace the left hand side by the right hand side, the opposite way is never needed in our proofs. Moreover,

| $D(\mathrm{~L}, \mathrm{~L}, \mathrm{LL}):=\mathrm{L}$ | $D(\mathrm{M}, \mathrm{L}, \mathrm{LL}):=\mathrm{L}$ | $D(\mathrm{R}, \mathrm{L}, \mathrm{LL}):=\mathrm{L}$ |
| :--- | :--- | :--- |
| $D(\mathrm{~L}, \mathrm{~L}, \mathrm{LT}):=\mathrm{L}$ | $D(\mathrm{M}, \mathrm{L}, \mathrm{LT}):=\mathrm{L}$ | $D(\mathrm{R}, \mathrm{L}, \mathrm{LT}):=\mathrm{M}$ |
| $D(\mathrm{~L}, \mathrm{~L}, \mathrm{MT}):=\mathrm{M}$ | $D(\mathrm{M}, \mathrm{L}, \mathrm{MT}):=\mathrm{M}$ | $D(\mathrm{R}, \mathrm{L}, \mathrm{MT}):=\mathrm{M}$ |
| $D(\mathrm{~L}, \mathrm{~L}, \mathrm{RT}):=\mathrm{M}$ | $D(\mathrm{M}, \mathrm{L}, \mathrm{RT}):=\mathrm{M}$ | $D(\mathrm{R}, \mathrm{L}, \mathrm{RT}):=\mathrm{M}$ |
| $D(\mathrm{~L}, \mathrm{~L}, \mathrm{RR}):=\mathrm{M}$ | $D(\mathrm{M}, \mathrm{L}, \mathrm{RR}):=\mathrm{R}$ | $D(\mathrm{R}, \mathrm{L}, \mathrm{RR}):=\mathrm{R}$ |
| $D(\mathrm{~L}, \mathrm{M}, \mathrm{LL}):=\mathrm{L}$ | $D(\mathrm{M}, \mathrm{M}, \mathrm{LL}):=\mathrm{L}$ | $D(\mathrm{R}, \mathrm{M}, \mathrm{LL}):=\mathrm{L}$ |
| $D(\mathrm{~L}, \mathrm{M}, \mathrm{LT}):=\mathrm{L}$ | $D(\mathrm{M}, \mathrm{M}, \mathrm{LT}):=\mathrm{M}$ | $D(\mathrm{R}, \mathrm{M}, \mathrm{LT}):=\mathrm{M}$ |
| $D(\mathrm{~L}, \mathrm{M}, \mathrm{MT}):=\mathrm{M}$ | $D(\mathrm{M}, \mathrm{M}, \mathrm{MT}):=\mathrm{M}$ | $D(\mathrm{R}, \mathrm{M}, \mathrm{MT}):=\mathrm{M}$ |
| $D(\mathrm{~L}, \mathrm{M}, \mathrm{RT}):=\mathrm{M}$ | $D(\mathrm{M}, \mathrm{M}, \mathrm{RT}):=\mathrm{M}$ | $D(\mathrm{R}, \mathrm{M}, \mathrm{RT}):=\mathrm{R}$ |
| $D(\mathrm{~L}, \mathrm{M}, \mathrm{RR}):=\mathrm{R}$ | $D(\mathrm{M}, \mathrm{M}, \mathrm{RR}):=\mathrm{R}$ | $D(\mathrm{R}, \mathrm{M}, \mathrm{RR}):=\mathrm{R}$ |
| $D(\mathrm{~L}, \mathrm{R}, \mathrm{LL}):=\mathrm{L}$ | $D(\mathrm{M}, \mathrm{R}, \mathrm{LL}):=\mathrm{L}$ | $D(\mathrm{R}, \mathrm{R}, \mathrm{LL}):=\mathrm{M}$ |
| $D(\mathrm{~L}, \mathrm{R}, \mathrm{LT}):=\mathrm{M}$ | $D(\mathrm{M}, \mathrm{R}, \mathrm{LT}):=\mathrm{M}$ | $D(\mathrm{R}, \mathrm{R}, \mathrm{LT}):=\mathrm{M}$ |
| $D(\mathrm{~L}, \mathrm{R}, \mathrm{MT}):=\mathrm{M}$ | $D(\mathrm{M}, \mathrm{R}, \mathrm{MT}):=\mathrm{M}$ | $D(\mathrm{R}, \mathrm{R}, \mathrm{MT}):=\mathrm{M}$ |
| $D(\mathrm{~L}, \mathrm{R}, \mathrm{RT}):=\mathrm{M}$ | $D(\mathrm{M}, \mathrm{R}, \mathrm{RT}):=\mathrm{R}$ | $D(\mathrm{R}, \mathrm{R}, \mathrm{RT}):=\mathrm{R}$ |
| $D(\mathrm{~L}, \mathrm{R}, \mathrm{RR}):=\mathrm{R}$ | $D(\mathrm{M}, \mathrm{R}, \mathrm{RR}):=\mathrm{R}$ | $D(\mathrm{R}, \mathrm{R}, \mathrm{RR}):=\mathrm{R}$ |

Figure 3.7: Function $D$
the right hand sides are simpler than the left hand sides. Due to these conditions, we can make use of the (proper) rewriting rules to specify the above axiom in Minlog. Then, the normalization mechanism automatically applies axioms instead of manually applying each axiom one by one, so that proof writing in Minlog becomes much easier.

### 3.4.2 Proofs

We present a proof of the formula (3.2) by closely following [BS10]. By convention on variable names, $d$ and $e$ are for $\mathbf{S D}$, and $i$ and $j$ are for $\mathbf{S D}_{2}$.

Proposition 3.4.5 (Average). $\forall_{x, y}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I x \rightarrow{ }^{\mathrm{co}} I y \rightarrow{ }^{\mathrm{co}} I \frac{x+y}{2}\right)$
Proof. Let $x$ and $y$ be given. Assume ${ }^{\text {co } I x}$ and ${ }^{c o} I y$. By Lemma 3.4.6, there exist $x^{\prime}, y^{\prime}$ and $i$ such that $x+y=\frac{x^{\prime}+y^{\prime}+i}{2}$. We prove ${ }^{\text {co }} I \frac{x^{\prime}+y^{\prime}+i}{4}$ by using $\left({ }^{\text {co }} I\right)^{+}$with the competitor predicate $P:=\left\{z \left\lvert\, \exists_{x, y}^{\mathrm{r}} \exists_{i}^{\mathrm{d}}\left({ }^{\mathrm{co}} I x \wedge{ }^{\mathrm{co}} I y \wedge z=\frac{x+y+i}{4}\right)\right.\right\}$. Obviously $P \frac{x^{\prime}+y^{\prime}+i}{4}$ holds. It suffices to prove the following costep formula.

$$
\forall_{x}^{\mathrm{nc}}\left(P x \rightarrow x=0 \vee \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee P y\right) \wedge x=\frac{y+d}{2}\right)\right) .
$$

Let $x$ be given. Assume $P x$. Here, it makes computational sense to use the identity lemma before assuming $P x$. By unfolding $P$, there exist $\tilde{x}, \tilde{y}, i$ such that $x=\frac{\tilde{x}+\tilde{y}+i}{4},{ }^{\text {co }} I \tilde{x}$,
${ }^{\text {co }} I \tilde{y}, T_{\mathbf{S D}_{2}} i$. By Lemma 3.4.7, there exist $\tilde{x}^{\prime}, \tilde{y}^{\prime}, j, d$ such that $\tilde{x}+\tilde{y}+i=\frac{\tilde{x}^{\prime}+\tilde{y}^{\prime}+j+4 d}{2}$. Let $y=\frac{\tilde{x}^{\prime}+\tilde{y}^{\prime}+j}{4}$, then $x=\frac{y+d}{2}$ and Py hold.

We prove the two lemmas used in the above proof. In the following we abbreviate $\forall_{x}^{\mathrm{nc}}\left({ }^{\mathrm{co}} I x \rightarrow A\right)$ and $\exists_{x}^{\mathrm{r}}\left({ }^{\mathrm{co}} I x \wedge A\right)$ by $\forall_{x \in{ }^{\mathrm{co}} I}^{\mathrm{nc}} A$ and $\exists_{x \in{ }^{\mathrm{r} \circ I}}(A)$, respectively.

Lemma 3.4.6. $\forall_{x, y \in \mathrm{co}^{\mathrm{nc}} I}^{\exists_{i}^{\mathrm{d}}} \exists_{x^{\prime}, y^{\prime} \in \mathrm{Co} I}\left(\frac{x+y}{2}=\frac{x^{\prime}+y^{\prime}+i}{4}\right)$.
Proof. Assume $x \in{ }^{\mathrm{co}} I$ and $y \in{ }^{\mathrm{co}} I$. Applying $\left({ }^{\mathrm{co}} I\right)^{-}$to ${ }^{\mathrm{co}} I x$ and ${ }^{\mathrm{co}} I y$, there are four cases from the following two disjunctions.

$$
\begin{aligned}
& x \text { eqd } Z \vee^{\mathrm{r}} \exists_{x_{0} \in^{\mathrm{co} I} I}^{\mathrm{r}} \exists_{d_{0}}^{\mathrm{d}}\left(x \text { eqd } \frac{x_{0}+d_{0}}{2}\right), \\
& y \text { eqd } \mathrm{Z} \vee^{\mathrm{r}} \exists_{y_{0} \in^{\mathrm{co} I} I} \exists_{e_{0}}^{\mathrm{d}}\left(y \text { eqd } \frac{y_{0}+e_{0}}{2}\right) .
\end{aligned}
$$

We prove the goal $\exists_{i}^{\mathrm{d}} \exists_{x^{\prime}, y^{\prime} \in \operatorname{cog} I} \frac{x+y}{2}$ eqd $\frac{x^{\prime}+y^{\prime}+i}{4}$ for each case. (1) Assume $x$ eqd $Z$ and $y$ eqd $Z$, then $\frac{x+y}{2}$ is Z. Let $x^{\prime}, y^{\prime}$ be Z and $i$ be MT. (2) Assume $x$ eqd Z and $\exists_{y_{0} \in^{\mathrm{co} I} \exists_{e_{0}}}^{\mathrm{d}}\left(y\right.$ eqd $\frac{y_{0}+e_{0}}{2}$ ). For the given $y_{0}$ and $e_{0}, \frac{x+y}{2}$ is $\frac{y_{0}+e_{0}}{4}$. Let $x^{\prime}$ be $\mathbf{Z}, y^{\prime}$ be $y_{0}$ and $i$ be $e_{0}$. (3) Similar to (2). (4) Assume $x_{0} \in{ }^{\mathrm{co}} I, d_{0} \in \mathbf{S D}, y_{0} \in{ }^{\mathrm{co}} I, e_{0} \in \mathbf{S D}$ such that $x$ eqd $\frac{x_{0}+d_{0}}{2}$ and $y$ eqd $\frac{y_{0}+e_{0}}{2}$, then $\frac{x+y}{2}$ is $\frac{x_{0}+y_{0}+\left(d_{0}+e_{0}\right)}{4}$. Let $x^{\prime}$ be $x_{0}, y^{\prime}$ be $y_{0}$ and $i$ be $d_{0}+e_{0}$.

Lemma 3.4.7. $\forall_{x, y \in{ }^{\mathrm{coI} I}}^{\mathrm{nc}} \forall_{i}^{\mathrm{c}} \exists_{x^{\prime}, y^{\prime} \in{ }^{\mathrm{\circ} I I}} \exists_{j, d}^{\mathrm{d}}\left(x+y+i=\frac{x^{\prime}+y^{\prime}+j+4 d}{2}\right)$.
Proof. Let $x, y$ and $i$ be given and assume ${ }^{\text {co }} I x$ and ${ }^{\text {co }} I y$. By using $\left({ }^{\mathrm{co}} I\right)^{-}$, we have the same case distinction as in Lemma 3.4.6. (1) Suppose that $x$ eqd $Z$ and $y$ eqd Z. Let $x^{\prime}$ and $y^{\prime}$ be both Z , then it suffices to find $j$ and $d$ such that $i=\frac{j+4 d}{2}$. It is solved by $j:=J(i, 0,0)$ and $d:=D(i, 0,0)$. (2) Suppose that $x$ eqd Z and $\exists \exists_{y_{0} \in \operatorname{coI}_{I}}^{\mathrm{r}} \exists_{e_{0}}^{\mathrm{d}}\left(y\right.$ eqd $\left.\frac{y_{0}+e_{0}}{2}\right)$. Let $x^{\prime}$ be Z and $y^{\prime}$ be $y_{0}$, then it suffices to find $j$ and $d$ such that $\frac{e_{0}}{2}+i=\frac{j+4 d}{2}$. The equation is solved by $j:=J\left(i, 0, e_{0}\right)$ and $d:=D\left(i, 0, e_{0}\right)$. (3) Similar to (2). (4) Suppose that $x_{0} \in{ }^{\mathrm{co}} I$, $d_{0} \in \mathbf{S D}, y_{0} \in{ }^{\mathrm{co}} I, e_{0} \in \mathbf{S D}$ such that $x$ eqd $\frac{x_{0}+d_{0}}{2}$ and $y$ eqd $\frac{y_{0}+e_{0}}{2}$. Let $x^{\prime}$ be $x_{0}, y^{\prime}$ be $y_{0}$, then it suffices to find $j$ and $d$ such that $\frac{d_{0}}{2}+\frac{e_{0}}{2}+i=\frac{j+4 d}{2}$. The equation is solved by $j:=J\left(i, d_{0}, e_{0}\right)$ and $d:=D\left(i, d_{0}, e_{0}\right)$.

### 3.4.3 Program Extraction

We extract programs from the proofs. From Lemma 3.4 .6 , we extract cPreprocess as shown in Figure 3.8. Here $d s$ is a name for variables ranging over I, and $u$ for variables ranging over $\mathbf{S D} \times \mathbf{I}$. This cPreprocess satisfies the following equations.

$$
\begin{aligned}
& \operatorname{cPreprocess}([],[])=\langle\mathrm{M},[],[]\rangle \\
& \operatorname{cPreprocess}([], e:: e s)=\langle e,[], e s\rangle \\
& \operatorname{cPreprocess}(d:: d s,[])=\langle d, d s,[]\rangle \\
& \operatorname{cPreprocess}(d:: d s, e:: e s)=\langle d+e, d s, e s\rangle .
\end{aligned}
$$

$$
\begin{aligned}
& \lambda_{d s_{0}, d s_{1}}\left(\text { Case } \mathcal{D}_{\mathbf{I}} d s_{0}\right. \text { of } \\
& \\
& \quad \lambda_{-}\left(\text {Case } \mathcal{D}_{\mathbf{I}} d s_{1} \text { of } \lambda_{-}\left\langle\mathrm{MT}, d s_{0}, d s_{1}\right\rangle\right. \\
& \left.\quad \lambda_{u}\left\langle\mathrm{M}+\pi_{0} u, d s_{0}, \pi_{1} u\right\rangle\right) \\
& \\
& \lambda_{u_{0}}\left(\text { Case } \mathcal{D}_{\mathbf{I}} d s_{1} \text { of } \lambda_{-}\left\langle\pi_{0} u_{0}+\mathrm{M}, \pi_{1} u_{0}, d s_{1}\right\rangle\right. \\
& \\
& \left.\left.\lambda_{u_{1}}\left\langle\pi_{0} u_{0}+\pi_{0} u_{1}, \pi_{1} u_{0}, \pi_{1} u_{1}\right\rangle\right)\right)
\end{aligned}
$$

Figure 3.8: cPreprocess ${ }^{\mathbf{I} \rightarrow \mathbf{I} \rightarrow \mathbf{S D}_{2} \times \mathbf{I} \times \mathbf{I}}$

For the given two streams cPreprocess computes the sum of the two head digits (regarding [] as $\mathrm{M}::[])$, and its tails. This sum of digits of type $\mathbf{S D}_{2}$ is a carry which contains intermediate information to compute the average as we saw in the informal idea.

From the proof of Lemma 3.4.7, we extract the term cRoutine as shown in Figure 3.9. The constant cRoutine of type $\mathbf{S D}_{2} \rightarrow \mathbf{I} \rightarrow \mathbf{I} \rightarrow \mathbf{S D}_{2} \times \mathbf{S D} \times \mathbf{I} \times \mathbf{I}$ is defined to be the

$$
\begin{aligned}
& \lambda_{i, d s_{0}, d s_{1}}\left(\text { Case } \mathcal{D}_{\mathbf{I}} d s_{0}\right. \text { of } \\
& \qquad \begin{array}{l}
\lambda_{-}\left(\text {Case } \mathcal{D}_{\mathbf{I}} d s_{1}\right. \text { of } \\
\lambda_{-}\left\langle\mathrm{MM} i, D \mathrm{MM} i, d s_{0}, d s_{1}\right\rangle \\
\left.\lambda_{u}\left\langle J \mathrm{M}\left(\pi_{0} u\right) i, D \mathrm{M}\left(\pi_{0} u\right) i, d s_{0}, \pi_{1} u\right\rangle\right) \\
\lambda_{u_{0}}\left(\text { Case } \mathcal{D}_{\mathbf{I}} d s_{1}\right. \text { of } \\
\lambda_{-}\left\langle J \mathrm{M}\left(\pi_{0} u_{0}\right), D\left(\pi_{0} u_{0}\right) \mathrm{M} i, \pi_{1} u_{0}, d s_{1}\right\rangle \\
\left.\left.\quad \lambda_{u_{1}}\left\langle J\left(\pi_{0} u_{0}\right)\left(\pi_{0} u_{1}\right) i, D\left(\pi_{0} u\right)\left(\pi_{0} u_{1}\right) i, \pi_{1} u_{0}, \pi_{1} u_{1}\right\rangle\right)\right)
\end{array}
\end{aligned}
$$

Figure 3.9: cRoutine ${ }^{\mathbf{S D}_{2} \rightarrow \mathbf{I} \rightarrow \mathbf{I} \rightarrow \mathbf{S D}_{2} \times \mathbf{S D} \times \mathbf{I} \times \mathbf{I}}$
term above. It satisfies the equations

$$
\begin{aligned}
& \text { cRoutine }(i,[],[])=\langle J(0,0, i), D(0,0, i),[],[]\rangle \\
& \text { cRoutine }(i,[], e:: e s)=\langle J(0, e, i), D(0, e, i),[], e s\rangle \\
& \text { cRoutine }(i, d:: d s,[])=\langle J(d, 0, i), D(d, 0, i), d s,[]\rangle \\
& \text { cRoutine }(i, d:: d s, e:: e s)=\langle J(d, e, i), D(d, e, i), d s, e s\rangle .
\end{aligned}
$$

For the given carry and two signed digit streams, cRoutine computes the carry for the next step, the first signed digit of the average of the streams, and the tails of the input streams.

From the proof of Proposition 3.4.5, we extract ave as shown in Figure 3.10. Here $q$ is a name for variables ranging over $\mathbf{S D}_{2} \times \mathbf{I} \times \mathbf{I}$ and $w$ for variables ranging over $\mathbf{S D}_{2} \times \mathbf{S D} \times \mathbf{I} \times \mathbf{I}$. Also recall that the let construction in Example 2.5.28. Note that we have three times of cRoutine if we do not use the identity lemma in the proof of Proposition 3.4.5. It calls

$$
\begin{aligned}
& \lambda_{d s_{0}, d s_{1}}\left({ }^{\mathrm{co}} \mathcal{R}\left(\mathrm{cPreprocess} d s_{0} d s_{1}\right)\right. \\
& \lambda_{q}\left(\operatorname { I n L } \left(\text { let } w=\mathrm{cRoutine}\left(\pi_{0} q\right)\left(\pi_{0}\left(\pi_{1} q\right)\right)\left(\pi_{1}\left(\pi_{1} q\right)\right)\right.\right. \\
& \left.\left.\left.\operatorname{in}\left\langle\pi_{0}\left(\pi_{1} w\right), \operatorname{lnR}\left\langle\pi_{0} w, \pi_{1}\left(\pi_{1} w\right)\right\rangle\right\rangle\right)\right)\right)
\end{aligned}
$$

Figure 3.10: $\mathrm{ave}^{\mathbf{I} \rightarrow \mathbf{I} \rightarrow \mathbf{I}}$
cPreprocess to compute the first carry and the tails of the inputs. Then CoRec repeatedly calls cRoutine in order to compute the average step by step. The second argument of the corecursion operator, namely, $M: \mathbf{S D}_{2} \times \mathbf{I} \times \mathbf{I} \rightarrow \mathbf{U}+\mathbf{S D} \times\left(\underset{\sim}{\mathbf{I}}+\mathbf{S D}_{2} \times \mathbf{I} \times \mathbf{I}\right)$, operates on an argument $\langle i, d s, e s\rangle$ as follows. Let cRoutine $(i, d s, e s)=\left\langle j, \tilde{d}, d s^{\prime}, e s^{\prime}\right\rangle$. Then $M\langle i, d s, e s\rangle=$ $\ln \mathrm{R}\left\langle\tilde{d}, \ln \mathrm{R}\left\langle j, d s^{\prime}, e s^{\prime}\right\rangle\right\rangle$. Given $d s$ and $e s$, let cPreprocess $(d s, e s)=\langle i, d s, e s\rangle:=N$. Then $M N$ is $\ln \mathrm{R}\left\langle\tilde{d}, \ln \mathrm{R}\left\langle j, d s^{\prime}, e s^{\prime}\right\rangle\right\rangle$. Therefore by the conversion rule for the corecursion operator the result is $\tilde{d}::\left({ }^{\mathrm{co}} \mathcal{R}\left\langle j, d s^{\prime}, e s^{\prime}\right\rangle M\right)$.

The term above can be used as a program to compute the average of stream represented real numbers. Comparing with a result by Berger and Seisenberger [BS12], our extracted program behaves almost the same as theirs except for a difference coming from the data type of streams. They use the type of necessarily infinite streams, written as fix $\alpha$. $\mathrm{SD} \times \alpha$, whereas we accept possibly infinite streams.

### 3.4.4 Experiments

We compute the average of $\frac{5}{8}$ and $\frac{3}{4} \cdot \frac{5}{8}=\frac{1}{2}+\frac{0}{4}+\frac{1}{8}$ and $\frac{3}{4}=\frac{1}{2}+\frac{1}{4}$, and hence those numbers are $\mathrm{R}:: \mathrm{M}:: \mathrm{R}::[]$ and $\mathrm{R}:: \mathrm{R}::[]$ in the algebra $\mathbf{I}$, respectively. Unfolding up to 10 times, the average program results in

$$
\mathrm{R}:: \mathrm{R}:: \mathrm{M}:: \mathrm{L}:: \mathrm{M}:: \mathrm{M}:: \mathrm{M}:: \mathrm{M}:: \mathrm{M}:: \mathrm{M}::\left({ }^{\mathrm{co}} \mathcal{R}\langle\mathrm{M},[],[]\rangle M\right) .
$$

It is verified as

$$
\frac{\frac{5}{8}+\frac{3}{4}}{2}=\frac{11}{16}=\frac{1}{2}+\frac{1}{4}-\frac{1}{16}
$$

Next, we try computing the average of two irrational numbers, $\frac{1}{\sqrt{2}}$ and $\frac{1}{\sqrt{3}}$. By means of cauchysds, which we extracted in Section 3.3, the first digits of these numbers are the following.

$$
\begin{aligned}
& \text { cauchysds(sqrt } \left.\frac{1}{2}\right)=\mathrm{R}:: \mathrm{R}:: \mathrm{M}:: \mathrm{L}:: \mathrm{R}:: \mathrm{L}:: \mathrm{M}:: \mathrm{R}:: \mathrm{M}:: \mathrm{M}:: \ldots, \\
& \text { cauchysds(sqrt } \left.\frac{1}{3}\right)=\mathrm{R}:: \mathrm{M}:: \mathrm{R}:: \mathrm{L}:: \mathrm{M}:: \mathrm{R}:: \mathrm{M}:: \mathrm{M}:: \mathrm{M}:: \mathrm{L}:: \ldots
\end{aligned}
$$

The average of them are computed to be
R::R::L::M::M::R::M::M::R::M:: . . . .

To verify the error, we first transform it into rational numbers, $329 \# 512$. The error is

$$
\left|\frac{\frac{1}{\sqrt{2}}+\frac{1}{\sqrt{3}}}{2}-\frac{329}{512}\right|=3.49 \ldots \times 10^{-4}
$$

which is smaller than $2^{-10}=9.765625 \times 10^{-4}$ as expected.

### 3.5 Representations of Uniformly Continuous Functions

We already saw a constructive representation of uniformly continuous functions in Section 3.1. There, the representation of uniformly continuous functions involves first order function types, hence it is called the type-1 representation of uniformly continuous functions. In this section, we study a representation of unary uniformly continuous functions by means of coinduction. We refer to this by type-0 uniformly continuous functions, since they are ground type objects in contrast to type-1 uniformly continuous functions. Our main result in this section is an extracted program which translates a type-1 uniformly continuous function into a type-0 uniformly continuous function, and vice versa.

Recall that $\left\langle h^{\mathbf{Q} \rightarrow \mathbf{N} \rightarrow \mathbf{Q}}, \alpha^{\mathbf{N} \rightarrow \mathbf{N}}, \omega^{\mathbf{N} \rightarrow \mathbf{N}}\right\rangle$ defines a type-1 uniformly continuous function if the following conditions are satisfied.

$$
\begin{aligned}
& \forall_{f, a^{\boldsymbol{Q}}, k^{\mathbf{N}}, n \geq \alpha(k), m \geq \alpha(k)}\left(|h(a, n)-h(a, m)| \leq 2^{-k}\right) \\
& \forall_{f, a^{\boldsymbol{Q}}, b^{\mathbf{Q}}, k^{\mathbf{N}}, n \geq \alpha(k)}\left(|a-b| \leq 2^{-\omega(k)+1} \rightarrow|h(a, n)-h(b, n)| \leq 2^{-k}\right)
\end{aligned}
$$

As our type-0 uniformly continuous functions, we adopt so-called read-write machines [Ber11] or stream processors GHP06, HPG09. It is a $\mathbf{W}$-cototal $\mathbf{R}_{\mathbf{W}}$-total ideal, where algebras $\mathbf{R}_{\alpha}$ and $\mathbf{W}$ are defined by

$$
\begin{aligned}
& \mathbf{R}_{\alpha}:=\mu_{\xi}\left(\text { Put }^{\text {SD } \rightarrow \alpha \rightarrow \xi}, \text { Get }^{\xi \rightarrow \xi \rightarrow \xi \rightarrow \xi}\right) \\
& \mathbf{W}:=\mu_{\xi}\left(\text { Stop }^{\xi}, \text { Cont }^{\mathbf{R}_{\xi} \rightarrow \xi}\right)
\end{aligned}
$$

A $\mathbf{W}$-cototal $\mathbf{R}_{\mathbf{W}}$-total ideal is a non-well founded tree which consists of total trees of type $\mathbf{R}_{\mathbf{W}}$. It represents a translation of an SDS into another in the following way. The root of the tree is either Stop or Cont $r$. If it is Stop, the rest of the input stream goes to the output stream. If it is Cont $r$, we continue with $r$ which is either Put $d w$ or Get $r_{\mathrm{L}} r_{\mathrm{M}} r_{\mathrm{R}}$. If it is Put $d w$, it outputs one signed digit $d$ and continue with $w$. If it is Get $r_{\mathrm{L}} r_{\mathrm{M}} r_{\mathrm{R}}$, it reads one signed digit $e^{\mathbf{S D}}$ from the input and continue with $r_{e}$. Observe that there is a nested structure in the procedure: the outer repetition on $\mathbf{W}$ and the inner one on $\mathbf{R}_{\mathbf{W}}$. It is crucial to have a well founded structure inside of a non-well founded structure in order to ensure the uniform continuity. We define a read-write machine to be a $\mathbf{W}$-cototal $\mathbf{R}_{\mathbf{W}}$-total ideal which can produce infinite signed digits, whereas its each internal component, i.e., an $\mathbf{R}_{\mathbf{W}}$-total ideal, has to put one signed digit by Put after getting finite signed digits by Get.

### 3.5.1 Definitions

We describe the abstract theory of uniformly continuous functions. Let $\phi$ be an abstract type of uniformly continuous functions. We define constants using this abstract type $\phi$, then the properties are specified via non-computational axioms.

Suppose that $p, q$ range over $\mathbf{Q}, k, l$ range over $\mathbf{N}, d$ ranges over $\mathbf{S D}$ and $f, g$ range over $\phi$. We define constants for the identity function and arithmetic operations Out and In on functions such that intuitively $\left(\mathrm{Out}_{d} \circ f\right)(x)=2 f(x)-d$ and $\left(f \circ \operatorname{In}_{d}\right)(x)=f\left(\frac{x+d}{2}\right)$ hold.

Definition 3.5.1 (Id). Id is a constant of type $\phi$.
Definition 3.5.2 (Out, In). Out and In are constants of type $\mathbf{S D} \rightarrow \phi \rightarrow \phi$. Out $d f$ and In $d f$ are abbreviated as $\mathrm{Out}_{d} \circ f$ and $f \circ \operatorname{In}_{d}$, respectively.

We also define an abstract inclusion relation on intervals.
Definition 3.5.3 (Sub). Sub is a constant of type $\phi \rightarrow \mathbf{Q} \rightarrow \mathbf{N} \rightarrow \mathbf{Q} \rightarrow \mathbf{N} \rightarrow \mathbf{B}$. Sub $f p l q k$ is abbreviated as $f\left[\square_{p, l}\right] \subseteq \square_{q, k}$.

The axioms of the abstract theory of uniformly continuous functions are defined as follows.

Axiom 3.5.4 (Abstract Theory of Uniformly Continuous Functions).

$$
\begin{align*}
& \forall_{p, l}\left(\operatorname{Id}\left[\square_{p, l}\right] \subseteq \square_{p, l}\right),  \tag{UcFID}\\
& \forall f, p\left(f\left[\square_{p, 0}\right] \subseteq \mathbb{0}\right) \text {, } \\
& \forall_{f, p, l, q, k}\left(f\left[\square_{p, l}\right] \subseteq \square_{q, k} \rightarrow f\left[\square_{p, l+1}\right] \subseteq \square_{q, k}\right),  \tag{UcFInPutSucc}\\
& \forall_{f, d, p, l, q, k}\left(f[0] \subseteq \square_{d} \rightarrow\left(\text { Out }_{d} \circ f\right)\left[\square_{p, l}\right] \subseteq \square_{q, k} \rightarrow f\left[\square_{p, l}\right] \subseteq \square_{\frac{q+d}{2}, k+1}\right),  \tag{OutElim}\\
& \forall_{f, d, p, l, q, k}\left(f[0] \subseteq \square_{d} \rightarrow f\left[\square_{p, l}\right] \subseteq \square_{\frac{q+d}{2}, k+1} \rightarrow\left(\operatorname{Out}_{d} \circ f\right)\left[\square_{p, l}\right] \subseteq \square_{q, k}\right),  \tag{OutIntro}\\
& \forall_{f, d, p, l, q, k}\left(\left(f \circ \operatorname{In}_{d}\right)\left[\square_{p, l}\right] \subseteq \square_{q, k} \rightarrow f\left[\square_{\frac{p+d}{2}, l+1}\right] \subseteq \square_{q, k}\right),  \tag{InElim}\\
& \forall_{f, d, p, l, q, k}\left(f\left[\square_{\frac{p+d}{2}, l+1}\right] \subseteq \square_{q, k} \rightarrow\left(f \circ \operatorname{In}_{d}\right)\left[\square_{p, l}\right] \subseteq \square_{q, k}\right),  \tag{InIntro}\\
& \forall_{f, q}\left(q \leq-\frac{1}{4} \rightarrow f[0] \subseteq \square_{q, 2} \rightarrow f[0] \subseteq \square_{\mathrm{L}}\right),  \tag{UcFLEFT}\\
& \forall_{f, q}\left(-\frac{1}{4} \leq q \leq \frac{1}{4} \rightarrow f[0] \subseteq \square_{q, 2} \rightarrow f[0] \subseteq 0_{M}\right), \\
& \forall_{f, q}\left(\frac{1}{4} \leq q \rightarrow f[0] \subseteq \square_{q, 2} \rightarrow f[0] \subseteq \square_{\mathrm{R}}\right) .
\end{align*}
$$

Note that the above axioms are all non-computational. The property of Id is specified by (UCFID). Our functions are bounded due to (UCFBOUND). The more the input given to a function is precise, the same or the more the output is precise due to UCFInPUTSUCC). For the two operations on functions, our intuition is kept by four axioms, (OUTELIM), (OutIntro), (InElim) and (InIntro). For example in (OutIntro), assume that the codomain of the function is in $\square_{d}$, and the image of $\square_{p, l}$ by $f$ is covered by $\square_{\frac{q+d}{2}, k+1}$. As $\left(\right.$ Out $\left._{d} \circ f\right)(x)$ is intuitively $2 f(x)-d$, the image of $\mathbb{\square}_{p, l}$ by $\left(\right.$ Out $\left._{d} \circ f\right)(x)$ is covered by $\mathbb{\square}_{q, k}$
whose center is shifted by $\lambda_{x}(2 x-d)$ and length is two times in comparison with $\square_{\frac{q+d}{2}, k+1}$. The last three axioms, UCFLEFT, UCFMIDDLE and UCFRIGHT reduce our reasoning on abstract functions to one on rational numbers.

We give definitions of two predicates $C$ and ${ }^{\text {co }}$ Write which are corresponding to the type- 1 and the type- 0 representations, respectively. First, we define $C$ of arity ( $\phi$ ).

Definition 3.5.5 (Uniform continuity of abstract real functions). We define a predicate $C$ of arity $(\phi)$ to state the uniform continuity of abstract real functions as follows:

$$
C:=\left\{f \mid \forall_{k}^{\mathrm{c}} \exists_{l}^{\mathrm{d}} \mathrm{~B}_{l, k} f\right\}, \text { where } \mathrm{B}_{l, k}:=\left\{f \mid \forall_{p}^{\mathrm{c}} \exists_{q}^{\mathrm{l}}\left(f\left[\mathrm{a}_{p, l}\right] \subseteq \square_{q, k}\right)\right\} .
$$

Suppose that $C f$ holds and let $k$ be given to specify the precision of the output of $f$. Then, there exists $l$ specifying the required precision of the input of $f$, and also there exists $q$ for any $p$ such that the image of the interval $\rrbracket_{p, l}$ is covered by the interval $\rrbracket_{q, k}$. According to the realizability interpretation, the extracted term type of the above predicate $C$ is

$$
\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})
$$

which can be used as a type- 1 uniformly continuous functions. It is considered to be a pair of an approximating map $h$ and a modulus of uniform continuity $\omega$. The Cauchy modulus $\alpha$ is fixed to be the identity.

Next, we define an inductive predicate $\operatorname{Read}_{X}$ and a coinductive predicate ${ }^{\text {co }}$ Write. Both of them are of arity $(\phi)$.

Definition 3.5.6 (Read). Let $X$ and $P$ be predicate variables of arity $(\phi)$. Define an inductive predicate $\operatorname{Read}_{X}$ of arity $(\phi)$ as follows.

$$
\begin{array}{cc}
\forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(f[\mathrm{\square}] \subseteq \mathrm{a}_{d} \rightarrow X\left(\operatorname{Out}_{d} \circ f\right) \rightarrow \operatorname{Read}_{X} f\right), & \operatorname{Read}_{0}^{+} \\
\forall_{f}^{\mathrm{nc}}\left(\operatorname{Read}_{X}\left(f \circ \operatorname{In}_{\mathrm{L}}\right) \rightarrow \operatorname{Read}_{X}\left(f \circ \operatorname{In}_{\mathrm{M}}\right) \rightarrow \operatorname{Read}_{X}\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \rightarrow \operatorname{Read}_{X} f\right), & \operatorname{Read}_{1}^{+} \\
\forall_{f}^{\mathrm{nc}}\left(\operatorname{Read}_{X} f \rightarrow \forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(f[I] \subseteq I_{d} \rightarrow X\left(\operatorname{Out}_{d} \circ f\right) \rightarrow P f\right) \rightarrow\right. & \\
\forall_{f}^{\mathrm{nc}}\left(\operatorname{Read}_{X}\left(f \circ \operatorname{In}_{\mathrm{L}}\right) \rightarrow P\left(f \circ \operatorname{In}_{\mathrm{L}}\right) \rightarrow\right. & \\
\operatorname{Read}_{X}\left(f \circ \operatorname{In}_{\mathrm{M}}\right) \rightarrow P\left(f \circ \operatorname{In}_{\mathrm{M}}\right) \rightarrow & \operatorname{Read}^{-} \\
\left.\operatorname{Read}_{X}\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \rightarrow P\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \rightarrow P f\right) \rightarrow & \\
P f) . &
\end{array}
$$

Definition 3.5.7 ( ${ }^{\text {co } W r i t e) . ~ L e t ~} Q$ be a predicate variable of arity $\phi$. Define a coinductive predicate ${ }^{\text {co }}$ Write of arity $(\phi)$ as follows.

$$
\begin{array}{ll}
\forall_{f}^{\text {nc }}\left({ }^{\text {co }} \text { Write } f \rightarrow f \text { eqd Id } \vee^{\mathrm{r}} \operatorname{Read}^{\text {co }}{ }_{\text {Write }} f\right), & { }^{\text {co }} \mathrm{Write}^{-} \\
\forall_{f}^{\text {nc }}\left(Q f \rightarrow \forall_{f}^{\text {nc }}\left(Q f \rightarrow f \text { eqd Id } \vee^{\mathrm{r}} \operatorname{Read}_{\text {co } \text { Writev }^{\mathrm{d}} Q} f\right) \rightarrow{ }^{\text {co }} \text { Write } f\right) . & { }^{\text {co }} \mathrm{Write}^{+}
\end{array}
$$

### 3.5.2 Proofs

We have two main results in this section: Proposition 3.5.11 and Proposition 3.5.14. We start from Proposition 3.5.11 which is dependent on Lemma 3.5.8, Lemma 3.5.9 and Lemma 3.5.10.

## Lemma 3.5.8.

1. $\forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}} \forall_{k, l}\left(f[0] \subseteq \mathrm{\square}_{d} \rightarrow \mathrm{~B}_{l, k+1} f \rightarrow \mathrm{~B}_{l, k}\left(\mathrm{Out}_{d} \circ f\right)\right)$.
2. $\forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(f[\mathrm{\square}] \subseteq \square_{d} \rightarrow \mathrm{C} f \rightarrow \mathrm{C}\left(\mathrm{Out}_{d} \circ f\right)\right)$.
3. $\forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}} \forall_{k, l}\left(\mathrm{~B}_{l+1, k} f \rightarrow \mathrm{~B}_{l, k}\left(f \circ \operatorname{In}_{d}\right)\right)$.
4. $\forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(\mathrm{C} f \rightarrow \mathrm{C}\left(f \circ \operatorname{In}_{d}\right)\right)$.

Proof. 1. Let $f, d, k$ and $l$ be given and assume $f[0] \subseteq \square_{d}$ and $\mathrm{B}_{l, k+1} f$, which is by unfolding $\forall_{p \in I}^{\mathrm{c}} \exists_{q}^{\mathrm{l}}\left(f\left[\mathrm{a}_{p, l}\right] \subseteq \square_{q, k+1}\right)$. We prove $\mathrm{B}_{l, k}\left(\mathrm{Out}_{d} \circ f\right)$, i.e., $\forall_{p \in I}^{\mathrm{c}} \exists_{q}^{\mathrm{l}}\left(\mathrm{Out}_{d} \circ f\left[\square_{p, l}\right] \subseteq\right.$ $\left.\square_{q, k}\right)$. Let $p$ be given. Applying $\forall_{p \in I}^{c} \exists_{q}^{l}\left(f\left[\square_{p, l}\right] \subseteq \square_{q, k+1}\right)$ to $p$, it yields some $q_{0}$ such that $f\left[\square_{p, l}\right] \subseteq \square_{q_{0}, k+1}$. To prove the goal $\exists_{q}^{1}\left(\right.$ Out $\left._{d} \circ f\left[\square_{p, l}\right] \subseteq \square_{q, k}\right)$, let $q$ be $2 q_{0}-d$, then it suffices to prove Out ${ }_{d} \circ f\left[\mathbb{0}_{p, l}\right] \subseteq \mathbb{\square}_{2 q_{0}-d, k}$. It is done by applying OUTINTRO to the assumptions $f[\square] \subseteq \mathbb{a}_{d}$ and $f\left[\square_{p, l}\right] \subseteq \mathbb{\square}_{q_{0}, k+1}$.
2. Let $f$ and $d$ be given and assume $f[0] \subseteq \square_{d}$ and $\mathrm{C} f$, i.e., $\forall_{k}^{\mathrm{c}} \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k} f$. We prove $\mathrm{C}\left(\mathrm{Out}_{d} \circ f\right)$, i.e., $\forall_{k}^{\mathrm{c}} \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k}\left(\mathrm{Out}_{d} \circ f\right)$. Let $k$ by given and prove $\exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k}\left(\mathrm{Out}_{d} \circ f\right)$. Applying $\forall_{k}^{\mathrm{c}} \exists \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k} f$ to $k+1$, it further yields $l_{0}$ such that $\mathrm{B}_{l_{0}, k+1} f$. Let $l$ be $l_{0}$ in our goal, the by Lemma 3.5.8 $1 \mathrm{~B}_{l_{0}, k}\left(\mathrm{Out}_{d} \circ f\right)$ holds.
3. Let $f, d, k$ and $l$ be given and assume $\mathrm{B}_{l+1, k} f$, i.e., $\forall_{p \in I}^{\mathrm{c}} \exists_{q}^{1}\left(f\left[\square_{p, l+1}\right] \subseteq \square_{q, k}\right)$. We prove $\mathrm{B}_{l, k}\left(f \circ \mathrm{In}_{d}\right)$, i.e., $\forall_{p \in I}^{\mathrm{c}} \exists_{q}^{1}\left(f \circ \operatorname{In}_{d}\left[\square_{p, l}\right] \subseteq \square_{q, k}\right)$. Let $p$ be given. Applying $\forall_{p \in I}^{c} \exists_{q}^{1}\left(f\left[\square_{p, l+1}\right] \subseteq\right.$ $\left.\square_{q, k}\right)$ to $\frac{p+d}{2}$, then it further yields $q_{0}$ such that $f\left[\square_{\frac{p+d}{2}, l+1}\right] \subseteq \square_{q_{0}, k}$. To prove the goal $\exists_{q}^{1}\left(f \circ \operatorname{In}_{d}\left[\square_{p, l}\right] \subseteq \square_{q, k}\right)$, let $q$ be $q_{0}$ and use ININTRO).
4. Let $f$ and $d$ be given and assume $\mathrm{C} f$, i.e., $\forall_{k}^{\mathrm{c}} \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k} f$. We prove $\mathrm{C}\left(f \circ \operatorname{In}_{d}\right)$, i.e., $\forall_{k}^{\mathrm{c}} \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k} f \circ \mathrm{In}_{d}$. Let $k$ be given. Applying $\forall_{k}^{\mathrm{c}} \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k} f$ to $k$, then it further yields $l_{0}$ such that $\mathrm{B}_{l_{0}, k} f$, i.e., $\forall_{p \in I}^{\mathrm{c}} \exists_{q}^{\mathrm{l}}\left(f\left[\square_{p, l_{0}}\right] \subseteq \square_{q, k}\right)$. Now we show that $\mathrm{B}_{l_{0}+1, k} f \circ \operatorname{In}_{d}$, i.e., $\forall_{p \in I}^{\mathrm{c}} \exists_{q}^{\mathrm{l}}\left(f\left[\square_{p, l_{0}+1}\right] \subseteq \square_{q, k}\right)$, also holds. Let $p$ be given. Applying $\forall_{p \in I}^{\mathrm{c}} \exists_{q}^{\mathrm{l}}\left(f\left[\square_{p, l_{0}}\right] \subseteq \square_{q, k}\right)$ to $p$, it further yields $q_{0}$ such that $f\left[\square_{p, l_{0}}\right] \subseteq \square_{q_{0}, k}$. To prove $\exists_{q}^{1}\left(f\left[\square_{p, l_{0}+1}\right] \subseteq \square_{q, k}\right)$, let $q$ be $q_{0}$ and apply (UCFINPUTSUCC) to $f\left[\mathrm{D}_{p, l_{0}}\right] \subseteq \square_{q_{0}, k}$. For the main goal $\exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k} f \circ \mathrm{In}_{d}$, let $l$ be $l_{0}$ and we prove $\mathrm{B}_{l_{0}, k} f \circ \mathrm{In}_{d}$, which is implied by Lemma 3.5.8 3 and $\mathrm{B}_{l_{0}+1, k} f$.

Lemma 3.5.9. $\forall_{f}^{\mathrm{nc}}\left(\mathrm{B}_{0,2} f \rightarrow \exists_{d}^{1}\left(f[0] \subseteq \square_{d}\right)\right)$.

Proof. Let $f$ be given and assume $\mathrm{B}_{0,2} f$ which implies $\exists_{q}^{1}\left(f\left[\square_{0,0}\right] \subseteq \square_{q, 2}\right)$ from the definition. Hence for some $q, f\left[\square_{0,0}\right] \subseteq \square_{q, 2}$ holds. We prove $\exists_{d}^{1}\left(f[0] \subseteq \square_{d}\right)$ by finding a $d$ such that $f[0] \subseteq \square_{d}$ holds. By case distinction on $q$, either $q \leq-\frac{1}{4},-\frac{1}{4} \leq q \leq \frac{1}{4}$ or $\frac{1}{4} \leq q$ holds. For each case we respectively choose $\mathbf{L}, \mathrm{M}$ or $\mathbf{R}$ for $d$. This $d$ satisfies $f[0] \subseteq \square_{d}$ due to the corresponding axiom, UcFLEFT), UcFMidDLE or UCFRIGHT).

Lemma 3.5.9 determines a signed digit which approximates the output of uniformly continuous functions. Suppose that we input the interval $\mathbb{D}$ to an abstract function and the length of its output interval is less than $\frac{1}{2}$. Then, the output of the abstract function is either in $\square_{L}, \square_{M}$ or $\square_{R}$.

Lemma 3.5.10. $\forall_{l}^{\mathrm{c}} \forall_{f}^{\mathrm{nc}}\left(\mathrm{B}_{l, 2} f \rightarrow \mathrm{C} f \rightarrow\right.$ Read $\left._{\mathrm{co}{ }_{W r i t e V c}} f\right)$.
Proof. By induction on $l$. Base: $l=0$. Let $f$ be given and assume $\mathrm{B}_{0,2} f$ and $\mathrm{C} f$. We prove $\operatorname{Read}^{\mathrm{co}}{ }_{\mathrm{WriteVC}} f$ by means of $\operatorname{Read}_{0}^{+}$. It suffices to prove $f[0] \subseteq \square_{d}$ and $\mathrm{C}\left(\mathrm{Out}_{d} \circ f\right)$ for some $d$. By Lemma 3.5.9, there is some $d$ with $f[0] \subseteq \square_{d}$ for the first one. Moreover, $\mathrm{C} f$ implies $\mathrm{C}\left(\mathrm{Out}_{d} \circ f\right)$ provided $f[0] \subseteq \square_{d}$ by Lemma 3.5.82, hence ( $\left.{ }^{\mathrm{co}} \mathrm{Write}^{\mathrm{d}} \mathrm{C}\right)\left(\mathrm{Out}_{d} \circ f\right)$ as desired. Step: $l \mapsto l+1$. Assume the following induction hypothesis

$$
\begin{equation*}
\forall_{f}^{\mathrm{nc}}\left(\mathrm{~B}_{l, 2} f \rightarrow \mathrm{C} f \rightarrow \operatorname{Read}_{\mathrm{co}_{\text {WritevC }}} f\right) \tag{3.5}
\end{equation*}
$$

and prove $\forall_{f}^{\mathrm{nc}}\left(\mathrm{B}_{l+1,2} f \rightarrow \mathrm{C} f \rightarrow \operatorname{Read}_{\mathrm{cow}_{\mathrm{WriteV}}} f\right)$ by means of the introduction axiom Read Red $_{1}^{+}$. It suffices to prove $\operatorname{Read}_{{ }^{\circ}{ }_{W r i t e V C}} f \circ \operatorname{In}_{d}$ for all $d$. Let $f$ be given and assume $\mathrm{B}_{l+1,2} f$ and $\mathrm{C} f$. By Lemma $3.5 .8,3$ and Lemma 3.5.8|4, which imply $\mathrm{B}_{l, 2} f \circ \mathrm{In}_{d}$ and $\mathrm{C} f \circ \operatorname{In}_{d}$ for all $d$. The induction hypothesis (3.5) yields Read ${ }_{c o W_{r i t e V C}} f \circ \operatorname{In}_{d}$ for all $d$ as desired.

Proposition 3.5.11 (Type-1 u.c.f. to type-0 u.c.f.). $\forall_{f}^{\mathrm{nc}}\left(\mathrm{C} f \rightarrow{ }^{\mathrm{co}}\right.$ Write $\left.f\right)$.
Proof. Let $f$ be given and assume $\mathrm{C} f$. We prove ${ }^{\text {co }}$ Write $f$ by the greatest fixed point axiom. It suffices to prove $\forall_{f}^{\mathrm{nc}}\left(\mathrm{C} f \rightarrow f\right.$ eqd $\operatorname{Id} \vee^{\mathrm{r}} \operatorname{Read}_{\left.\mathrm{co}_{W_{r i t e}{ }^{\mathrm{d}} \mathrm{C}} f\right) \text {. Let } f \text { be given and } \mathrm{C} f \text {, which }}$ implies $\exists_{l}^{\mathrm{d}} \mathrm{B}_{l, 2} f$. By Lemma 3.5.10, Read ${ }_{\mathrm{co}{ }_{W r i t e v}{ }^{\mathrm{d}} \mathrm{C}} f$ holds.

Next, we prove Proposition 3.5 .14 , i.e., the opposite direction of Proposition 3.5.11. The following two lemmas are needed.

Lemma 3.5.12. $\forall_{f, k, l}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(f[0] \subseteq \mathrm{a}_{d} \rightarrow \mathrm{~B}_{l, k}\left(\mathrm{Out}_{d} \circ f\right) \rightarrow \mathrm{B}_{l, k+1} f\right)$.
Proof. Let $f, k, l$ and $d$ be given and assume $f[0] \subseteq \square_{d}$ and

$$
\begin{equation*}
\mathrm{B}_{l, k}\left(\mathrm{Out}_{d} \circ f\right) \tag{3.6}
\end{equation*}
$$

We prove $\mathrm{B}_{l, k+1} f$, i.e., $\forall_{p \in I}^{c} \exists_{q}^{\mathrm{l}}\left(f\left[\square_{p, l}\right] \subseteq \square_{q, k+1}\right)$. Let $p_{0}$ be given such that $\exists_{q}^{1}\left(f\left[\square_{p_{0}, l}\right] \subseteq\right.$ $\square_{q, k+1}$ ). Our goal is to find a $q$ such as $f\left[\square_{p_{0}, l}\right] \subseteq \square_{q_{0}, k+1}$. The assumption (3.6), i.e., $\forall_{p \in I}^{\mathrm{c}} \exists_{q}^{1}\left(\left(\right.\right.$ Out $\left.\left._{d} \circ f\right)\left[\square_{p, l}\right] \subseteq \square_{q, k}\right)$, implies $\exists_{q}^{1}\left(\left(\right.\right.$ Out $\left.\left._{d} \circ f\right)\left[\square_{2 p_{0}-d, l}\right] \subseteq \square_{q, k}\right)$. Hence there is some $q_{0}$ such that $\left(\right.$ Out $\left._{d} \circ f\right)\left[\left[_{2 p_{0}-d, l}\right] \subseteq \square_{q_{0}, k}\right.$. For this $q_{0}$, we can derive $f\left[\square_{p_{0}, l}\right] \subseteq \square_{q_{0}, k+1}$ by means of OutElim.

Lemma 3.5.13. We prove

$$
\forall_{f, k, l_{\mathrm{L}}, l_{\mathrm{M}}, l_{\mathrm{R}}}^{\mathrm{nc}}\left(\mathrm{~B}_{l_{\mathrm{L}}, k+1}\left(f \circ \operatorname{In}_{\mathrm{L}}\right) \rightarrow \mathrm{B}_{l_{\mathrm{M}}, k+1}\left(f \circ \mathrm{In}_{\mathrm{M}}\right) \rightarrow \mathrm{B}_{l_{\mathrm{R}}, k+1}\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \rightarrow \mathrm{B}_{l, k+1} f\right),
$$

where $l:=\max \left\{l_{\mathrm{L}}, l_{\mathrm{M}}, l_{\mathrm{R}}\right\}+1$.
Proof. Let $f, k, l_{\mathrm{L}}, l_{\mathrm{M}}$ and $l_{\mathrm{R}}$ be given and assume $\mathrm{B}_{l_{\mathrm{L}}, k+1}\left(f \circ \mathrm{In}_{\mathrm{L}}\right), \mathrm{B}_{l_{\mathrm{M}}, k+1}\left(f \circ \mathrm{In}_{\mathrm{M}}\right)$ and $\mathrm{B}_{l_{\mathrm{R}}, k+1}\left(f \circ \mathrm{In}_{\mathrm{R}}\right)$. We prove $\mathrm{B}_{l, k+1} f$, i.e., $\forall_{p}^{\mathrm{c}} \exists_{q}^{1}\left(f\left[\square_{p, l}\right] \subseteq \square_{q, k+1}\right)$. Let $p_{0}$ be given, then our goal is $\exists_{q}^{1}\left(f\left[\square_{p_{0}, l}\right] \subseteq \square_{q, k+1}\right)$. By case distinction on $p_{0}$, either of $p_{0} \leq-\frac{1}{4},-\frac{1}{4} \leq p_{0} \leq \frac{1}{4}$ or $\frac{1}{4} \leq p_{0}$ holds. For each case we let $d$ be $\mathrm{L}, \mathrm{M}$ or R , respectively. For any $d$ we can proceed the following to prove the goal. The assumption $\mathrm{B}_{l_{d}, k+1}\left(f \circ \operatorname{In}_{d}\right)$ i.e., $\forall_{p}^{\mathrm{c}} \exists_{q}\left(\left(f \circ \mathrm{In}_{d}\right)\left[\square_{p, l_{d}}\right] \subseteq \square_{q, k+1}\right)$ $\operatorname{implies}\left(f \circ \mathrm{In}_{d}\right)\left[\square_{2 p_{0}-d, l_{d}}\right] \subseteq \square_{q_{0}, k+1}$ for some $q_{0}$. By (INELIM), $f\left[\square_{p_{0}, l_{d}+1}\right] \subseteq \square_{q_{0}, k+1}$ holds. For this $q_{0}$ we can prove the goal $f\left[\square_{p_{0}, l}\right] \subseteq \square_{q_{0}, k+1}$ because of $l \geq l_{0}+1$ and (UCFInPUTSUCC).

Proposition 3.5.14 (Type-0 u.c.f. into type-1 u.c.f.). $\forall_{f}^{\mathrm{nc}}\left({ }^{(\mathrm{co}} \mathrm{Write} f \rightarrow \mathrm{C} f\right)$.
Proof. It suffices to prove $\forall_{k}^{\mathrm{c}} \forall_{f}^{\mathrm{nc}}\left({ }^{\mathrm{co}} \mathrm{Write} f \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k} f\right)$ by induction on $k$. Case $k=0$. Our goal is $\forall_{f}^{\mathrm{nc}}\left({ }^{\text {co }}\right.$ Write $\left.f \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, 0} f\right)$. Let $f$ be given and ${ }^{\text {co }}$ Write $f$. Let $l$ be 0 and prove $\mathrm{B}_{0,0} f$, i.e., $\forall_{p}^{\mathrm{c}} \exists_{q}^{\mathrm{l}} f\left[\square_{p, 0}\right] \subseteq \square_{q, 0}$. Let $p$ be given $q$ be 0 . From the axiom, $f\left[\square_{p, 0}\right] \subseteq \square_{0,0}$ trivially holds. Case $k \mapsto k+1$. Our induction hypothesis is

$$
\begin{equation*}
\forall_{f}^{\mathrm{nc}}\left({ }^{\mathrm{co}} \text { Write } f \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{~B}_{l, k} f\right) . \tag{3.7}
\end{equation*}
$$

Our goal is $\forall_{f}^{\mathrm{nc}}\left({ }^{\mathrm{co}}\right.$ Write $\left.f \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k+1} f\right)$. Let $f$ be given and assume ${ }^{\text {co }}$ Write $f$. We prove $\exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k+1} f$. Using ${ }^{{ }^{\text {co }} \mathrm{Write}^{+}}$and our assumption ${ }^{\text {co }}$ Write $f$, the following holds.

$$
f \text { eqd Id } \vee{\text { Readco }{ }_{\text {Write }} f . ~}_{\text {. }}
$$

Consider two cases from the disjunction. Left case. Assume $f$ eqd Id. We prove $\exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k+1} \mathrm{Id}$, i.e., $\exists_{l}^{\mathrm{d}} \forall_{p}^{\mathrm{c}} \exists{ }_{q}^{\mathrm{l}}\left(\operatorname{Id}\left[\square_{p, l}\right] \subseteq \square_{q, k+1}\right)$. Let $l$ be $k+1$ and assume $p$, and also let $q$ be $p$, then it suffices to prove $\operatorname{Id}\left[\square_{p, k+1}\right] \subseteq \square_{p, k+1}$, which is direct from UCFID. Right case. Assume Readcowrite $f$ and prove $\exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k+1} f$. By using Read $^{-}$for Readco Write $f$, we have the following two new goals.

$$
\forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(f[\square] \subseteq \square_{d} \rightarrow{ }^{\mathrm{co}} \text { Write }\left(\text { Out }_{d} \circ f\right) \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{~B}_{l, k+1} f\right)
$$

and

$$
\begin{aligned}
& \forall_{f}^{\mathrm{nc}}\left(\operatorname{Readco~Write~}^{\left(f \circ \mathrm{In}_{\mathrm{L}}\right) \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{~B}_{l, k+1}\left(f \circ \mathrm{In}_{\mathrm{L}}\right) \rightarrow}\right. \\
& \quad \operatorname{Read}_{\mathrm{co}} \text { Write }\left(f \circ \mathrm{In}_{\mathrm{M}}\right) \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{~B}_{l, k+1}\left(f \circ \mathrm{In}_{\mathrm{M}}\right) \rightarrow \\
& \left.\quad \operatorname{Readco}_{\text {Write }}\left(f \circ \mathrm{In}_{\mathrm{R}}\right) \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{~B}_{l, k+1}\left(f \circ \mathrm{In}_{\mathrm{R}}\right) \rightarrow \exists_{l}^{\mathrm{d}} \mathrm{~B}_{l, k+1} f\right)
\end{aligned}
$$

For the former one, let $f$ and $d$ be given and assume $f[0] \subseteq \square_{d}$ and ${ }^{\text {co }}$ Write $\left(\mathrm{Out}_{d} \circ f\right)$. By our induction hypothesis 3.7 ) and ${ }^{\text {co }} \mathrm{Write}^{\left(\mathrm{Out}_{d} \circ f\right), ~} \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k}\left(\mathrm{Out}_{d} \circ f\right)$ holds, i.e., there is some $l$ such that $\mathrm{B}_{l, k}\left(\mathrm{Out}_{d} \circ f\right)$. It implies $\mathrm{B}_{l, k+1} f$ by Lemma 3.5.12 as desired. For the latter one, let $f$ be given and assume $\operatorname{Readco}_{\text {write }}\left(f \circ \operatorname{In}_{\mathrm{L}}\right), \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k+1}\left(f \circ \operatorname{In}_{\mathrm{L}}\right), \operatorname{Readco}_{\text {Write }}(f \circ$ $\left.\mathrm{In}_{\mathrm{M}}\right), \exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k+1}\left(f \circ \mathrm{In}_{\mathrm{M}}\right)$, Readcowrite $\left(f \circ \mathrm{In}_{\mathrm{R}}\right)$ and $\exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k+1}\left(f \circ \mathrm{In}_{\mathrm{R}}\right)$. We prove $\exists_{l}^{\mathrm{d}} \mathrm{B}_{l, k+1} f$. From assumptions, there are $l_{\mathrm{L}}, l_{\mathrm{M}}$ and $l_{\mathrm{R}}$ such that $\mathrm{B}_{l_{\mathrm{L}}, k+1}\left(f \circ \mathrm{In}_{\mathrm{L}}\right), \mathrm{B}_{l_{\mathrm{M}}, k+1}\left(f \circ \mathrm{In}_{\mathrm{M}}\right)$ and $\mathrm{B}_{l_{\mathrm{R}}, k+1}\left(f \circ \mathrm{In}_{\mathrm{R}}\right)$. By Lemma 3.5.13. $\mathrm{B}_{l, k+1} f$ holds for $l:=\max \left\{l_{\mathrm{L}}, l_{\mathrm{M}}, l_{\mathrm{R}}\right\}+1$ as desired.

### 3.5.3 Program Extraction

We study the computational contents of the proofs by program extraction. From Proposition 3.5.11 the term ucf 1 to0 shown in Figure 3.11 is extracted. This program corecursively

$$
\lambda_{g}\left({ }^{(\mathrm{Co}} \mathcal{R}_{\mathbf{W}}^{\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})} g \lambda_{g_{0}}\left(\text { Case } g_{0}(2) \text { of }\langle k, h\rangle \rightarrow \mathrm{L}_{10} k g_{0} h\right)\right)
$$

Figure 3.11: ucf1to $0^{(\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})) \rightarrow \mathbf{W}}$
constructs a $\mathbf{W}$-cototal $\mathbf{R}_{\mathbf{W}}$-total ideal by stacking $\mathbf{R}_{\mathbf{W}}$-total ideals computed by $\mathrm{L}_{10}$, which is extracted from Lemma 3.5 .10 as shown in Figure 3.12. The modulus of continuity $k$ at

$$
\begin{array}{r}
\lambda_{k}\left(\mathcal{R}_{\mathbf{N}} k \lambda_{h, g}\left(\operatorname{Put}\left(\mathrm{~L}_{9} h\right)\left(\operatorname{lnR}\left(\mathrm{L}_{8 \mathrm{ii}}\left(\mathrm{~L}_{9} h\right) g\right)\right)\right)\right. \\
\lambda_{l, g_{0}, h, g_{1}}\left(\operatorname{Get}\left(g_{0}\left(\mathrm{~L}_{8 \mathrm{iii}} \mathrm{~L} h\right)\left(\mathrm{L}_{8 \mathrm{iv}} \mathrm{~L} g_{1}\right)\right)\right. \\
\left(g_{0}\left(\mathrm{~L}_{8 \mathrm{iii}} \mathrm{M} h\right)\left(\mathrm{L}_{8 \mathrm{iv}} \mathrm{M} g_{1}\right)\right) \\
\left.\left.\left(g_{0}\left(\mathrm{~L}_{8 \mathrm{iii}} \mathrm{R} h\right)\left(\mathrm{L}_{8 \mathrm{iv}} \mathrm{R} g_{1}\right)\right)\right)\right)
\end{array}
$$

Figure 3.12: $\mathrm{L}_{10} \mathbf{N} \rightarrow(\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow(\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})) \rightarrow \mathbf{R}_{\mathbf{W}+(\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q}))}$
precision 2 is fed to $\mathrm{L}_{10}$, then an approximation of $h$ as an $\mathbf{R}_{\mathbf{W}}$-total ideal is computed. In fact, $k$ is the number of input signed digits to be read to determine one output signed digit.

The extracted term $\mathrm{L}_{10}$ takes as input a natural number $k$, a rational function $g$ and a function $h: \mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})$ (in our application, we only call $\mathrm{L}_{10}$ with $\langle n, w\rangle=h 2$ ). Using recursion over $n$, it computes an approximation of $h$ by a complete tree of height $n$ with $3^{n}$ leaves - an $\mathbf{R}_{\mathbf{W}+(\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q}))}$-total ideal. At the leaves, a signed digit $d$ - computed from $w$ using $\mathrm{L}_{9}$ in Figure 3.13 - and the remainder of the approximation of $h$ - computed by $\mathrm{L}_{8 \mathrm{ii}}$ below, using $d$ - is stored. At internal branching nodes, we split the domain of $h$

$$
\begin{gathered}
\lambda_{g}\left(\text { if } g(0)+\frac{1}{4}>0 \text { then if } g(0)-\frac{1}{4}>0 \text { then } \mathrm{R}\right. \\
\text { else M else } \mathrm{L})
\end{gathered}
$$

Figure 3.13: $\mathrm{L}_{\mathbf{9}}(\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow \mathbf{S D}$
into three subdomains - left, middle and right - modify $w$ and $h$ accordingly (using $\mathrm{L}_{8 \mathrm{iii}}$ and $\mathrm{L}_{8 \mathrm{iv}}$ below), and recurse.

There are several more programs extracted from lemmas. From Lemma 3.5.9 we extract $\mathrm{L}_{9}$ which is similar to L we extracted from Lemma 3.3.8. This program determines a $d$ such that the whole values of the given $g$ is covered by $\rrbracket_{d}$. In our extracted program, it is used
under the assumption that the values of $g$ given to $L_{9}$ is covered by an interval of length $\frac{1}{2}$. Therefore, it suffices to check the value of $g$ at 0 . The terms in Figure 3.14 are extracted from each of Lemma 3.5.8. Next, we consider the extracted program from Proposition 3.5.14

$$
\begin{aligned}
& \mathrm{L}_{8 \mathrm{i}} \mathbf{S D} \rightarrow(\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow(\mathbf{Q} \rightarrow \mathbf{Q}) \\
& \mathrm{L}_{8 \mathrm{i}}:=\lambda_{d, h}\left(\lambda_{a}(2 h(a)-d)\right) \\
& \mathrm{L}_{8 \mathrm{ii}} \mathbf{S D} \rightarrow(\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})) \rightarrow(\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})) \\
& \mathrm{L}_{8 \mathrm{ii}}:=\lambda_{d, g, k}\left(\text { Case } g(k+1) \text { of }\langle l, h\rangle \rightarrow\left\langle l, \mathrm{~L}_{8 \mathrm{i}} d h\right\rangle\right) \\
& \mathrm{L}_{8 \mathrm{iii}} \mathrm{SD} \rightarrow(\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow(\mathbf{Q} \rightarrow \mathbf{Q}) \\
& \mathrm{L}_{8 \mathrm{iii}}:=\lambda_{d, h}\left(\lambda_{a}\left(h\left(\frac{a+d}{2}\right)\right)\right) \\
& \mathrm{L}_{8 \mathrm{iv}} \mathrm{SD} \rightarrow(\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})) \rightarrow(\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})) \\
& \mathrm{L}_{8 \mathrm{iv}}:=\lambda_{d, g, k}\left(\text { Case } g ( k ) \text { of } \langle l , h \rangle \rightarrow \left(\text { Case } l \text { of } 0 \rightarrow\left\langle 0, \mathrm{~L}_{8 \mathrm{iii}} d h\right\rangle\right.\right. \\
& \left.\left.\quad \mathrm{S} n \rightarrow\left\langle n, \mathrm{~L}_{8 \mathrm{iii}} d h\right\rangle\right)\right)
\end{aligned}
$$

Figure 3.14: Programs extracted from Lemma 3.5.8
shown in Figure 3.15. Let $f$ be a name of a variable ranging over $\mathbf{W} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})$,

$$
\begin{aligned}
& \lambda_{w, n}\left(\mathcal{R}_{\mathbf{N}}^{\mathbf{W} \rightarrow \mathbf{N} \times(\mathbf{N} \rightarrow \mathbf{Q})} n\right. \\
& \lambda_{-}\left\langle 0, \lambda_{a} 0\right\rangle \\
& \lambda_{n_{0}, f, w_{0}}\left(\text { Case } \mathcal{D} w_{0}\right. \text { of } \\
& \lambda_{-}\left\langle\mathrm{S} n_{0}, \lambda_{a} a\right\rangle \\
& \lambda_{r}\left(\mathcal{R}_{\mathbf{R}_{\mathbf{W}}}^{\mathbf{N} \times(\mathbf{N} \rightarrow \mathbf{Q})} r \lambda_{d, w_{1}}\left(\text { Case } f w_{1} \text { of } \lambda_{m, g}\left\langle m, \mathrm{~L}_{12} d g\right\rangle\right)\right. \\
& \lambda_{-, q_{\mathrm{L},,}, q_{\mathrm{M}},, q_{\mathrm{R}}}\left(\text { Case } q_{\mathrm{L}}\right. \text { of } \\
& \lambda_{n_{\llcorner }, g_{\mathrm{L}}} \text { Case } q_{\mathrm{M}} \text { of } \\
& \lambda_{n_{M}, g_{M}} \text { Case } q_{R} \text { of } \\
& \left.\left.\left.\lambda_{n_{\mathrm{R}}, g_{\mathrm{R}}}\left\langle\mathrm{~S}\left(\max n_{\mathrm{L}} n_{\mathrm{M}} n_{\mathrm{R}}\right), \mathrm{L}_{13} g_{\mathrm{L}} g_{\mathrm{M}} g_{\mathrm{R}}\right\rangle\right)\right)\right)
\end{aligned}
$$

w)

Figure 3.15: ucf0to1 $\mathbf{W \rightarrow \mathbf { N } \rightarrow \mathbf { N } \times ( \mathbf { Q } \rightarrow \mathbf { Q } )}$
$q$ ranging over $\mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})$ and $g$ ranging over $\mathbf{Q} \rightarrow \mathbf{Q}$. This program computes a uniformly continuous function of type-1 from one of type- 0 . The second argument $n$ of type $\mathbf{N}$ specifies the precision of the rational approximation of the function. If $n$ is 0 , the result is a pair of 0 and a function whose value is constantly 0 . It trivially satisfies the required
precision; the error of the output has to be less than $2^{0}$ for any input with the error less than $2^{0}$. If $n$ is $\mathrm{S} n_{0}$, we assume that $n_{0}$, the previous result $f$ of the precision $n_{0}$. It is going to compute a pair of $\mathbf{N}$ and $\mathbf{Q} \rightarrow \mathbf{Q}$ with the precision $S n_{0}$ for the given input $w_{0}$. There are two cases to consider depending on $w_{0}$. If $\mathcal{D} w_{0}$ is $\operatorname{InL} \mathrm{U}$, the expected outcome is the identity function with the precision $\mathrm{S} n_{0}$, i.e., the pair of $\mathrm{S} n_{0}$ and $\lambda_{a} a$. If $\mathcal{D} w_{0}$ is $\operatorname{lnR} r$, it inspects $r$ by side recursion. If $r$ is Put $d w_{1}$, we apply $f$ to $w_{1}$, which is the result for $w_{1}$ of the precision $n_{0}$. Since $d$ tells us where to go to get a better precision, it shifts the result by using $\mathrm{L}_{12}$ which is extracted from Lemma 3.5 .12 and shown in Figure 3.16. If $r$ is

$$
\lambda_{d, g, a}\left(\frac{g(a)+d}{2}\right)
$$

Figure 3.16: $\mathrm{L}_{12}{ }^{\mathbf{S D} \rightarrow(\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow \mathbf{Q} \rightarrow \mathbf{Q}}$
Get $r_{\mathrm{L}} r_{\mathrm{M}} r_{\mathrm{R}}$, there are three previous results $q_{\mathrm{L}}, q_{\mathrm{M}}$ and $q_{\mathrm{R}}$ available. It takes components $n_{d}$ and $g_{d}$ of each $q_{d}$ and computes the maximum of $n_{\mathrm{L}}, n_{\mathrm{M}}$ and $n_{\mathrm{R}}$. We require one more precision of this maximum because we read one signed digit from the input at Get. The other component of the pair is the composition of $g_{\mathrm{L}}, g_{\mathrm{M}}$ and $g_{\mathrm{R}}$ by $\mathrm{L}_{13}$ which is extracted from Lemma 3.5.13 shown in Figure 3.17. For the input rational $a$, it checks which basic

$$
\begin{aligned}
& \lambda_{g_{\mathrm{L}}, g_{\mathrm{M}}, g_{\mathrm{R}}, a}\left(\text { if }\left(a \leq-\frac{1}{4}\right) \text { then } g_{\mathrm{L}}(2 a+1)\right. \\
& \left.\quad \text { else if }\left(-\frac{1}{4} \leq a \leq \frac{1}{4}\right) \text { then } g_{\mathrm{M}}(a) \text { else } g(2 a-1)\right)
\end{aligned}
$$

Figure 3.17: $\mathrm{L}_{13}(\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow(\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow(\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow \mathbf{Q} \rightarrow \mathbf{Q}$
interval covers this $a$ and selects the appropriate $g_{d}$.
Remark 3.5.15. Note that there is a slight difference between the extracted programs in Minlog and ones presented in this section. In the case study in Minlog, there is an algebra algB which is defined to be $\mu_{\xi}((\mathbf{Q} \rightarrow \mathbf{Q}) \rightarrow \xi)$. Since there is no feature in Minlog to name a comprehension term, we defined $B_{l, k}$ of Definition 3.5.5 as an inductively defined predicate in order to avoid writing a long formula repeatedly. We omit the occurrences of algB in order to focus on algorithmic contents.

### 3.5.4 Experiments

From a type-1 uniformly continuous function $f$, we compute a type- 0 uniformly continuous function by means of our extracted program. We define $f$ by $\langle h, \alpha, \omega\rangle$ where $h a n:=-a$, $\alpha n:=0$ and $\omega n:=n+1$. The input of type1to 0 is $\lambda_{n}\left\langle\omega n, \lambda_{a}(h a(\alpha n))\right\rangle$ whose type is $\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})$. The output is graphically presented in Figure 3.18, where Cont is
omitted, Get is a branching node and Put $d$ is denoted by,- 0 or + respectively for $d=\mathrm{L}, \mathrm{M}$ or R.


Figure 3.18: Type-0 representation of $f(x)=-x$.

We try the opposite direction, i.e., from type-0 to type-1. Applying type0to1 to the tree $t$ from the first example, we obtain a function of type $\mathbf{N} \rightarrow \mathbf{N} \times(\mathbf{Q} \rightarrow \mathbf{Q})$. Giving some $k$ to the argument of the outcome, it results in a pair of a natural number $l$ and a rational function $g$. For the experiment we give $k=3$, then $l=4$ and the function $g$ is a step function as presented in Figure 3.19. It is observable that if the error of the input is


Figure 3.19: Type-1 representation of $f(x)=2 x^{2}-1$ approximated by 3 .
less than $2^{-4}$, the output approximates $f(x)=2 x^{2}-1$ with the error less than $2^{-3}$.

### 3.6 Application of Uniformly Continuous Functions

We study application of a type-0 uniformly continuous function to a type-0 real number. We extract a program which takes a type-0 uniformly continuous function $f$ and a type-0 real number $x$, and computes the application $f(x)$ in type- 0 real numbers.

For given $w$ and $d s$ of type $\mathbf{W}$ and $\mathbf{L}_{\mathbf{S D}}$, the application builds another SDS to output. In order to illustrate an intuition, we focus on Get and Put nodes of $w$, so that we regard $w$ simply as a tree with 1-branching nodes labelled with a signed digit and 3-branching nodes. The application procedure takes a look at the root of $w$. If it is a 1 -branching node, it outputs the label of this node and goes on with the subtree. If it is a 3-branching node, it reads the head of the input SDS, say $d$, and chooses the left, the middle, or the right branch corresponding to $d$. The procedure goes on with the chosen subtree and the tail of the input SDS.

### 3.6.1 Definitions

The abstract theory of the function application is based on the abstract theory of real numbers in Section 3.3 and the abstract theory of uniformly continuous functions in Section 3.5. We define a constant Apply for the abstract function application additionally to the abstract theories from the previous sections.

Definition 3.6.1 (Apply). Recall that $\rho$ and $\phi$ are used for abstract types of real numbers and uniformly continuous functions, respectively. Apply is a constant of type $\rho \rightarrow \phi \rightarrow \rho$. Apply $f x$ is abbreviated as $f(x)$.

Then, we enrich the axiom to talk about the function application.

## Axiom 3.6.2.

$$
\begin{align*}
& \forall_{x}(\operatorname{Id}(x) \operatorname{eqd} x),  \tag{AppId}\\
& \forall_{f, x, d}\left(f[0] \subseteq \square_{d} \rightarrow \operatorname{Va}_{d}(f(x)) \text { eqd }\left(\operatorname{Out}_{d} \circ f\right)(x)\right),  \tag{VaOut}\\
& \forall_{f, x, d}\left(f\left(\operatorname{Av}_{d} x\right) \text { eqd }\left(f \circ \operatorname{In}_{d}\right)(x)\right),  \tag{AvIn}\\
& \forall_{f, x, q, k}\left(f[0] \subseteq \square_{q, k} \rightarrow f(x) \in \square_{q, k}\right) \tag{AppSubElem}
\end{align*}
$$

The constant Id works as we commonly expect due to APPID. The operations $\mathrm{Va}_{d}$ and Out ${ }_{d}$ can replace each other by (VAOUT), and the same happens to $\mathrm{Av}_{d}$ and $\mathrm{In}_{d}$ by (AvIn). The relation $\subseteq$ can be replaced by $\in$ due to APPSUBElEm,

The following equality between two real numbers is also used.

## Axiom 3.6.3.

$$
\begin{equation*}
\forall_{x, d}\left(x \text { eqd } \operatorname{Va}_{d}\left(\operatorname{Av}_{d} x\right)\right) \tag{VAAvIdent}
\end{equation*}
$$

We use the predicates ${ }^{\text {co }} I$, Read and ${ }^{\text {co }}$ Write which are defined in Definition 3.3.6, Definition 3.5.6 and Definition 3.5.7, respectively.

### 3.6.2 Proofs

We prove the following proposition in order to extract a program of the function application.
Proposition 3.6.4. $\forall_{f, x}^{\mathrm{nc}}\left({ }^{\mathrm{co}}\right.$ Write $\left.f \rightarrow{ }^{\mathrm{co}} I x \rightarrow{ }^{\mathrm{co}} I(f(x))\right)$.
Proof. Let $f$ and $x$ be given, and assume ${ }^{\text {co }}$ Write $f$ and ${ }^{\text {co }} I x$. We use ${ }^{\text {co } I^{+} \text {with a competitor }}$ predicate $P=\left\{z \mid \exists \exists_{f, x}^{\mathrm{r}}\left({ }^{\mathrm{co}}\right.\right.$ Write $f \wedge^{\mathrm{d}}{ }^{\mathrm{co}} I x \wedge^{\mathrm{l}} z$ eqd $\left.\left.f(x)\right)\right\}$ to prove ${ }^{\mathrm{co}} I(f(x))$. Since the first premise $P(f(x))$ is clear from the assumptions, it suffices to prove the costep formula $\forall_{z}^{\mathrm{nc}}\left(P z \rightarrow z \operatorname{eqd} \mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{\mathrm{l}} z \operatorname{eqd} \mathrm{Av}_{d}(y)\right)\right)$. Let $z$ be given and assume $P z$.

 $f_{0}$ eqd Id $\vee^{\mathrm{r}}$ Readco ${ }_{\text {Write }} f_{0}$ makes two cases. Left case. Assume $f_{0}$ eqdId. Applying ${ }^{\text {co }} I^{-}$to ${ }^{\mathrm{co}} I x_{0}, x_{0}$ eqd $\mathrm{Z} \vee^{\mathrm{r}} \exists_{y_{0}}^{\mathrm{r}} \exists_{d_{0}}^{\mathrm{d}}\left({ }^{\mathrm{co}} I y_{0} \wedge^{1} x_{0}\right.$ eqd $\left.\mathrm{Av}_{d_{0}}\left(y_{0}\right)\right)$ makes two subcases. Each side case comes by APPID). Right case. Assume Readco ${ }_{\text {Write }} f_{0}$. We also have ${ }^{\text {co }} I x_{0}$ and $z$ eqd $f_{0}\left(x_{0}\right)$, hence Lemma 3.6.5 applies.

The Lemma 3.6.5 below is responsible for determining an output signed digit by recursion on an $\mathbf{R}_{\mathbf{W}}$-total tree.

Lemma 3.6.5. Let $P:=\left\{z \mid \exists_{f, x}^{\mathrm{r}}\left({ }^{\mathrm{co}}\right.\right.$ Write $f \wedge^{\mathrm{d} \mathrm{co}} I x \wedge^{1} z$ eqd $\left.\left.f(x)\right)\right\}$, then

$$
\forall_{f, x}^{\mathrm{nc}}\left(\operatorname{Read}_{\mathrm{co}_{\text {Write }}} f \rightarrow{ }^{\mathrm{co}} I x \rightarrow f(x) \text { eqd } \mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{1} f(x) \operatorname{eqd} \mathrm{Av}_{d}(y)\right)\right)
$$

Proof. We prove the following formula which is same as the proposition.

$$
\forall_{f}^{\mathrm{nc}}\left(\operatorname{Read}_{\mathrm{co} \text { Write }} f \rightarrow \forall_{x}^{\mathrm{nc}}\left({ }^{(\mathrm{co}} I x \rightarrow f(x) \text { eqd } \mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{1} f(x) \text { eqd } \mathrm{Av}_{d}(y)\right)\right)\right)
$$

Let $f$ be given and assume $\operatorname{Read}_{c^{\circ} W_{\text {Write }}} f$. By using $\operatorname{Read}^{-}$for Read ${ }_{\text {co }}^{\text {Write }}$ $f$, it suffices to prove the following two step cases

$$
\forall_{e}^{\mathrm{c}} \forall_{f}^{\mathrm{nc}}\left(f[0] \subseteq \square_{e} \rightarrow{ }^{\mathrm{co}} \operatorname{Write}\left(\mathrm{Out}_{e} \circ f\right) \rightarrow Q f\right)
$$

and

$$
\begin{aligned}
& \forall_{f}^{\mathrm{nc}}\left(\operatorname{Read}_{\mathrm{co}_{\text {Write }}}\left(f \circ \mathrm{In}_{\mathrm{L}}\right) \rightarrow Q\left(f \circ \mathrm{In}_{\mathrm{L}}\right) \rightarrow\right. \\
& \operatorname{Read}_{\text {co }}^{\text {Write }}\left(f \circ \operatorname{In}_{\mathrm{M}}\right) \rightarrow Q\left(f \circ \operatorname{In}_{\mathrm{M}}\right) \rightarrow \\
& \left.\operatorname{Read}_{\text {co }}^{\text {Write }}\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \rightarrow Q\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \rightarrow Q f\right),
\end{aligned}
$$

where $Q:=\left\{f \mid \forall_{x}^{\mathrm{nc}}\left({ }^{\text {co }} I x \rightarrow f(x)\right.\right.$ eqd $\mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{1} f(x)\right.$ eqd $\left.\left.\left.\operatorname{Av}_{d}(y)\right)\right)\right\}$. First step case. Let $e$ and $f$ be given and assume $f[0] \subseteq \square_{e}$ and ${ }^{\text {co }}$ Write (Out $\circ f$ ). Also let $x$ be given and assume ${ }^{\text {co }} I x$. We prove the right disjunct of the conclusion. Use $\left(\exists^{\mathrm{r}}\right)^{+}$ and $\left(\exists^{\mathrm{d}}\right)^{+}$with $y=\left(\mathrm{Out}_{e} \circ f\right)(x)$ and $d=e$, respectively. The equality is obvious from VAOUT and AVVAIDENT). In order to prove Py, we use $\left(\exists^{\mathrm{r}}\right)^{+}$with Out $\circ f$ and with $x$, then three conjuncts are trivial. Second step case. Let $f$ be given and assume $\operatorname{Read}_{\text {co }}^{\text {Write }}$ $\left(f \circ \operatorname{In}_{e}\right)$ and $\forall_{x}^{\text {nc }}\left({ }^{\text {co }} I x \rightarrow\left(f \circ \operatorname{In}_{e}\right)(x)\right.$ eqd Z $\vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{1}(f \circ\right.$
$\left.\operatorname{In}_{e}\right)(x)$ eqd $\left.\left.\operatorname{Av}_{d}(y)\right)\right)$ for each $e \in \mathbf{S D}$. Also let $x$ be given and assume ${ }^{c o} I x$. We prove $f(x)$ eqd $\mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{1} f(x)\right.$ eqd $\left.\mathrm{Av}_{d}(y)\right)$. Applying ${ }^{\mathrm{co}} I^{+}$to ${ }^{\mathrm{co}} I x$, there are two cases from $x$ eqd $Z \vee^{\mathrm{r}} \exists_{y_{0}}^{\mathrm{r}} \exists_{d_{0}}^{\mathrm{d}}\left({ }^{\mathrm{c}} I y_{0} \wedge^{1} x\right.$ eqd $\left.\mathrm{Av}_{d_{0}}\left(y_{0}\right)\right)$. Left case. Assume $x$ eqd Z. Applying the induction hypothesis for $e=\mathrm{M}$ to ${ }^{\mathrm{co}} I(\mathrm{Z}),\left(f \circ \mathrm{In}_{\mathrm{M}}\right)(\mathrm{Z})$ eqd $\mathrm{Z} \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{e}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{1}(f \circ\right.$ $\left.\operatorname{In}_{M}\right)(Z)$ eqd $\left.\operatorname{Av}_{e}(y)\right)$ holds, and moreover $\left(f \circ \operatorname{In}_{M}\right)(Z)$ eqd $f(Z)$ holds by means of AvIn) and AVZERO, hence the goal is implied. Right case. There exist $y_{0}$ and $d_{0}$ such that ${ }^{\text {co }} y_{0}$ and $x$ eqd $\mathrm{Av}_{d_{0}}\left(y_{0}\right)$ hold. Applying the induction hypothesis corresponding to $d_{0}$ to ${ }^{\text {co }} I y_{0}$, $\left(f \circ \operatorname{In}_{d_{0}}\right)\left(y_{0}\right)$ eqd $Z \vee^{\mathrm{r}} \exists_{y}^{\mathrm{r}} \exists_{e}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I y \vee^{\mathrm{d}} P y\right) \wedge^{1}\left(f \circ \operatorname{In}_{d_{0}}\right)\left(y_{0}\right)\right.$ eqd $\left.\mathrm{Av}_{e}(y)\right)$ holds and we are done because $\left(f \circ \operatorname{In}_{d_{0}}\right)\left(y_{0}\right)$ eqd $f(x)$ holds by the assumption $x$ eqd $\operatorname{Av}_{d_{0}}\left(y_{0}\right)$ and AvIN).

### 3.6.3 Program Extraction

We extract a program from the proof of 3.6.4. Note that Remark 3.5.15 applies in this section as well. Suppose that $u$ is a variable name ranging over $\mathbf{W} \times \mathbf{I}$ and $q$ ranging over $\mathbf{S D} \times \mathbf{I}$. The result is app which is shown in Figure 3.20. Intuitively, this function computes

$$
\begin{aligned}
& \lambda_{w, d s}\left({ }^{\mathrm{co}} \mathcal{R}_{\mathbf{I}}^{\mathbf{W} \times \mathbf{I}}\langle w, d s\rangle\right. \\
& \lambda_{u}\left(\text { Case } \mathcal{D}_{\mathbf{W}}\left(\pi_{0} u\right)\right. \text { of } \\
& \lambda_{-} \operatorname{Case} \mathcal{D}\left(\pi_{1} u\right) \text { of } \\
& \lambda_{-} \operatorname{InLU} \\
& \lambda_{q} \operatorname{lnR}\left\langle\pi_{0} q, \operatorname{lnL}\left(\pi_{1} q\right)\right\rangle \\
& \left.\left.\lambda_{r}\left(\text { Case } \operatorname{ApplyAux}\left(r\left(\pi_{1} u\right)\right) \text { of } \lambda_{-}(\operatorname{lnL} \mathrm{U}) \lambda_{v}(\operatorname{lnR} v)\right)\right)\right)
\end{aligned}
$$

Figure 3.20: $\mathrm{app}^{\mathbf{W} \rightarrow \mathbf{I} \rightarrow \mathbf{I}}$
a trace from the root of the given type-0 function to the above by choosing at Get a branch indicated by the input type-0 real number. The output is an SDS which consists of signed digits which occur at Put on the computed trace.

Assume $w$ and $d s$ of types $\mathbf{W}$ and $\mathbf{I}$, respectively, are given. The costep term first destruct $w$. If $\mathcal{D} w$ is $\operatorname{lnL} \mathrm{U}$, the output is identical to the given $d s$. Otherwise, it results in an $\mathbf{R}_{\mathbf{W}}$-total ideal $r$. We apply cApplyAux to this $r$ and $d s$, then it determines that the result SDS is either the empty list or a pair of the head and the tail, i.e., a signed digit and an SDS, respectively.

We extract from the Lemma 3.6.5 a program cApplyAux shown in Figure 3.21. Let $f$ be a variable name ranging over $\mathbf{I} \rightarrow \mathbf{U}+(\mathbf{S D} \times(\mathbf{I}+\mathbf{W} \times \mathbf{I}))$. For the input $r$ and $d s$, this program computes by reading finite signed digits from $d s$ a finite path in $r$, so that a signed digit is determined. There are two cases due to the recursion on $r$. If $r$ is Put $d w$ it does not touch $d s$ and outputs $\ln \mathrm{R}\langle d, \ln \mathrm{R}\langle w, d s\rangle\rangle$. It makes the corecursion operator in app to produce a stream with the head $d$ and the rest app $w d s$. Otherwise, $r$ is Get $r_{\mathrm{L}} r_{\mathrm{M}} r_{\mathrm{R}}$. If $\mathcal{D} d s$ is $\operatorname{InL} \mathrm{U}$, it interprets the $d s$ as a rational number $\mathrm{M}:: \mathrm{M}:: \ldots$ and the middle branch is

$$
\begin{aligned}
& \lambda_{r}\left(\mathcal{R}_{\mathbf{R}_{\mathbf{W}}}^{\mathbf{I} \rightarrow \mathbf{U}+(\mathbf{S D} \times(\mathbf{I}+\mathbf{W} \times \mathbf{I}))}\right. \\
& r \\
& \lambda_{d, w, d s}(\ln \mathrm{R}\langle d, \ln \mathrm{R}\langle w, d s\rangle\rangle) \\
& \lambda_{-, f f_{\mathrm{L}},-, f_{\mathrm{M}},-f_{\mathrm{R}}, d s}\left(\text { Case } \mathcal{D}_{\mathbf{I}} d s\right. \text { of } \\
& \lambda_{-}\left(f_{\mathrm{M}} d s\right) \\
& \left.\left.\lambda_{q}\left(\text { Case } \pi_{0} q \text { of } \lambda_{-}\left(f_{\mathrm{L}}\left(\pi_{1} q\right)\right) \lambda_{-}\left(f_{\mathrm{M}}\left(\pi_{1} q\right)\right) \lambda_{-}\left(f_{\mathrm{R}}\left(\pi_{1} q\right)\right)\right)\right)\right)
\end{aligned}
$$

Figure 3.21: cApplyAux $\mathbf{R}_{\mathbf{W} \rightarrow \mathbf{I} \rightarrow \mathbf{U}+(\mathbf{S D} \times(\mathbf{I}+\mathbf{W} \times \mathbf{I}))}$
taken to reach the leaf. Otherwise if $\mathcal{D} d s$ is $\operatorname{InR}\left\langle d, d s^{\prime}\right\rangle$, it takes a branch corresponding to $d$ and then the recursion carries on with $d s^{\prime}$.

### 3.6.4 Experiments

Define a function $f(x)=2 x^{2}-1$ and consider its roots $\pm \frac{1}{\sqrt{2}}$. It is expected that the value $f\left( \pm \frac{1}{\sqrt{2}}\right)$ is arbitrarily close to 0 . We use app to compute the value of $f\left(\frac{1}{\sqrt{2}}\right)$.

A type-1 uniformly continuous function for $f$ is defined to be $\langle h, \alpha, \omega\rangle$ where $h a n=$ $2 a^{2}-1, \alpha n=n+1$ and $\omega n=n+1$. Then by means of ucf 1 to0, we obtain the type-0 representation of $\langle h, \alpha, \omega\rangle$. On the other hand, the type-0 representation of $\frac{1}{\sqrt{2}}$ is computed by cauchysds and sqrt as in Section 3.3.4. Using app, we can compute $\operatorname{app}(\operatorname{ucf} 1$ to0 $f)\left(\right.$ cauchysds(sqrt $\left.\left.\frac{1}{2}\right)\right)$ in an SDS as follows:
M :: M :: M :: M :: M :: M :: M :: . . .

### 3.7 Composition of Uniformly Continuous Functions

From formalized proofs we extract a program which computes the composition of two type-0 uniformly continuous functions. The input of the composition algorithm is two type-0 uniformly continuous functions and the output is a type-0 uniformly continuous function. For simplicity we regard a uniformly continuous function as a tree with 3-branching nodes and 1-branching nodes labelled with a signed digit. It takes a look at the root of the two input trees. When both of them are a 3-branching node, let the three subtrees of the first input be $r_{0}, r_{1}$ and $r_{2}$, then it makes a 3 -branching node for the output with three subtrees computed by composing $r_{0}, r_{1}$ and $r_{2}$ with the second input, respectively. When the first input is a 3 -branching node and the second one is a 1 -branching node with a signed digit $d$, the output is a composition of the subtree of the first input corresponding to $d$, namely, the left, the middle, or the right, and the subtree of the second input. When the first input
is a 1-branching tree, it puts the very same 1-branching tree for the output and the rest is a composition of the subtree of the first input and the original second input.

### 3.7.1 Definitions

In order to talk about the composition of abstract functions, define a constant Cmp whose properties are given by the abstract theory.

Definition 3.7.1 (Cmp). Cmp is a constant of type $\phi \rightarrow \phi \rightarrow \phi . \mathrm{Cmp} f g$ is abbreviated as $f \circ g$.

We extend the abstract theory of uniformly continuous functions in Section 3.5.1 with the following axioms.

## Axiom 3.7.2.

$$
\begin{align*}
& \forall_{f}(f \circ \operatorname{Id} \operatorname{eqd} f)  \tag{CompIdR}\\
& \forall_{f}(\operatorname{Id} \circ f \text { eqd } f)  \tag{CompIdL}\\
& \forall_{d}\left(\left(\operatorname{Id} \circ \operatorname{In}_{d}\right)[\square] \subseteq \square_{d}\right)  \tag{IdIn}\\
& \forall_{f, d}\left(\operatorname{Out}_{d} \circ\left(\operatorname{Id} \circ \operatorname{In}_{d}\right) \text { eqd Id }\right)  \tag{OutIdIn}\\
& \forall_{f_{1}, f_{2}, d}\left(f_{1}[0] \subseteq \square_{d} \rightarrow\left(f_{1} \circ f_{2}\right)[0] \subseteq \square_{d}\right)  \tag{CompBound}\\
& \forall_{f, p, l d}\left(f[0] \subseteq \square_{p, l} \rightarrow\left(f \circ \operatorname{In}_{d}\right)[\square] \subseteq \square_{p, l}\right)  \tag{UcFInputIn}\\
& \forall_{f_{1}, f_{2}, d}\left(f_{2}[0] \subseteq \square_{d} \rightarrow f_{1} \circ f_{2} \operatorname{eqd}\left(f_{1} \circ \operatorname{In}_{d}\right) \circ\left(\mathrm{Out}_{d} \circ f_{2}\right)\right) \\
& \forall_{f, d_{1}, d_{2}}\left(\mathrm{Out}_{d_{1}} \circ\left(f \circ \operatorname{In}_{d_{2}}\right) \text { eqd }\left(\mathrm{Out}_{d_{1}} \circ f\right) \circ \operatorname{In}_{d_{2}}\right) \\
& \forall_{f_{1}, f_{2}, d}\left(\left(f_{1} \circ f_{2}\right) \circ \operatorname{In}_{d} \operatorname{eqd} f_{1} \circ\left(f_{2} \circ \operatorname{In}_{d}\right)\right) \\
& \forall_{f_{1}, f_{2}, d}\left(\operatorname{Out}_{d} \circ\left(f_{1} \circ f_{2}\right) \text { eqd }\left(\mathrm{Out}_{d} \circ f_{1}\right) \circ f_{2}\right)
\end{align*}
$$

We also use the predicates ${ }^{\mathrm{co}} I$, Read and ${ }^{\text {co }}$ Write from Definition 3.3.6, 3.5.6 and 3.5.7, respectively.

### 3.7.2 Proofs

We extract from a proof a program which composes two type-0 uniformly continuous functions. Let variable names $f, g$ and $h$ range over $\phi$.
Proposition 3.7.3. $\forall_{f, g}^{\mathrm{nc}}\left({ }^{(\mathrm{co}}\right.$ Write $f \rightarrow{ }^{\mathrm{co}}$ Write $g \rightarrow{ }^{\mathrm{co}}$ Write $\left.(f \circ g)\right)$.
Proof. Let $f$ and $g$ be given and assume ${ }^{\text {co }}$ Write $f$ and ${ }^{\text {co }}$ Write $g$. We use ${ }^{\text {co }{ }^{\text {Write }}{ }^{+} \text {with }}$ a competitor predicate $P:=\left\{h \mid \exists_{f, g}^{\mathrm{r}}\left({ }^{\text {co }}\right.\right.$ Write $f \wedge{ }^{\text {co }}$ Write $g \wedge f \circ g$ eqd $\left.\left.h\right)\right\}$. It suffices to show $\forall_{h}^{\text {nc }}\left(P h \rightarrow h\right.$ eqd $\operatorname{Id} V^{\mathrm{r}}$ Read $\left._{{ }^{c o}{ }_{W r i t e v}{ }^{\mathrm{d}} P} h\right)$. Let $h$ be given and assume $P h$, i.e., ${ }^{\text {co } W r i t e ~} f$, ${ }^{c o}$ Write $g$ and $f \circ g$ eqd $h$. We prove the goal $f \circ g$ eqd $\operatorname{Id} \vee^{\mathrm{r}} \operatorname{Read}_{\mathrm{co}^{\circ}{ }_{W r i t e V}{ }^{\mathrm{d}} P}(f \circ g)$. Applying ${ }^{\text {co }}$ Write ${ }^{-}$to ${ }^{\text {co }}$ Write $f$ and to ${ }^{\text {co }}$ Write $g$, there are four cases from the following two disjunctions.

$$
f \text { eqd Id } \vee^{\mathrm{r}} \operatorname{Read}_{\mathrm{co}_{\mathrm{Write}}} f, \quad g \text { eqd Id } \vee^{\mathrm{r}} \operatorname{Read}_{\text {co }}^{\text {Write }} \text { } g .
$$

(1) Assume $f$ eqd Id and $g$ eqd Id. The left disjunct of the goal holds due to CompIDL or (COMPIDR). (2) Assume $\operatorname{Read}_{{ }_{c o} W_{\text {Write }}} f$ and $g$ eqd Id. We prove the right disjunct of the goal. By (ComPIDR), the goal is $\operatorname{Read}_{\text {co }_{W r i t e v}{ }^{\text {d }} P} f$. By $\operatorname{Read}^{-}$for Read ${ }^{c_{W r i t e}} f$, it suffices to prove the following two step formulas.

$$
\begin{aligned}
& \forall_{f} \forall_{d}^{\mathrm{c}}\left(f[0] \subseteq \square_{d} \rightarrow{ }^{\mathrm{co}} \mathrm{Write}^{\left.\left(\mathrm{Out}_{d} \circ f\right) \rightarrow \operatorname{Read}_{\mathrm{co}^{\circ} \operatorname{Writev}^{\mathrm{d}} P} f\right),}\right. \\
& \forall_{f}\left(\operatorname{Read}_{\text {co Write }}\left(f \circ \operatorname{In}_{\mathrm{L}}\right) \rightarrow \operatorname{Read}_{\mathrm{co}_{\text {WriteV }}(P)}\left(f \circ \mathrm{In}_{\mathrm{L}}\right) \rightarrow\right. \\
& \operatorname{Read}_{{ }_{c o} \text { Write }}\left(f \circ \operatorname{In}_{\mathrm{M}}\right) \rightarrow \operatorname{Read}_{\text {co WriteV }^{\mathrm{d}} P}\left(f \circ \operatorname{In}_{\mathrm{M}}\right) \rightarrow
\end{aligned}
$$

$$
\begin{aligned}
& \left.\operatorname{Read}_{c o W_{\text {ritev }}(P)} f\right) \text {. }
\end{aligned}
$$

For the first one, let $f, d$ be given and assume $f[0] \subseteq \square_{d}$ and ${ }^{\text {co }}$ Write $\left(\right.$ Out $\left._{d} \circ f\right)$. Prove the goal Read ${ }_{\text {co }_{\text {WriteV } P}} f$ by using $\operatorname{Read}_{0}^{+}$with $d$. It suffices to prove the premises $f[0] \subseteq \square_{d}$ and $\left({ }^{\mathrm{co}}\right.$ Write $\left.\vee^{\mathrm{d}} P\right)\left(\mathrm{Out}_{d} \circ f\right)$. The former one is in the assumption and the latter comes from the assumption by $\left(\mathrm{V}^{\mathrm{d}}\right)_{0}^{+}$. For the second one, let $f$ be given and assume the premises. Since Readco ${ }_{W r i t e v}\left(f \circ \operatorname{In}_{d}\right)$ holds for each $d \in \mathbf{S D}$, we apply Read ${ }_{1}^{+}$to prove
 $\forall_{g}^{\mathrm{nc}}\left({ }^{\mathrm{co}}\right.$ Write $\left.g \rightarrow \operatorname{Read}^{\mathrm{co} W_{\text {WriteV }}(P)}(f \circ g)\right)$ by Read ${ }^{-}$, in order the right disjunct of the goal holds. Base case. We prove

$$
\forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(f[0] \subseteq \square_{d} \rightarrow{ }^{\mathrm{co}} \text { Write }\left(\mathrm{Out}_{d} \circ f\right) \rightarrow \forall_{g}^{\mathrm{nc}}\left({ }^{\mathrm{co}} \text { Write } g \rightarrow \operatorname{Read}_{\mathrm{co}_{\mathrm{Writev}} P}(f \circ g)\right)\right)
$$

Let $f$ and $d$ be given and assume $f[0] \subseteq \square_{d}$ and ${ }^{\text {co }}$ Write $\left(\right.$ Out $\left._{d} \circ f\right)$. Furthermore, let $g$ be given and assume ${ }^{\text {co }}$ Write $g$. We prove $\operatorname{Read}_{\text {co }_{W_{r i t e v}} P}(f \circ g)$. Using $\operatorname{Read}_{0}^{+}$with $d$, it suffices to prove $(f \circ g)[0] \subseteq \square_{d}$ and ( $\left.{ }^{\text {co } W r i t e ~} \vee{ }^{\mathrm{d}} P\right)\left(\mathrm{Out}_{d} \circ(f \circ g)\right)$. The former one comes by (ComPBoUND). We prove $P\left(\mathrm{Out}_{d} \circ(f \circ g)\right)$, the right disjunct of the latter one. By AsSOCOUTCOMP), the conclusion comes from ${ }^{\text {co }} \mathrm{Write}\left(\mathrm{Out}_{d} \circ f\right)$ and ${ }^{\text {co } W r i t e ~} g$. Step case. We prove

$$
\begin{aligned}
& \forall_{g}^{\mathrm{nc}}\left({ }^{\mathrm{co}} \text { Write } g \rightarrow \operatorname{Read}_{\mathrm{co}_{\mathrm{Write}} P}(f \circ g)\right) \text { ). }
\end{aligned}
$$

Let $f$ be given and assume the premises. Also let $g$ be given and assume ${ }^{\text {co } W r i t e ~} g$. Applying ${ }^{{ }^{c o}}{ }^{W}$ Write ${ }^{-}$to ${ }^{\text {co }}$ Write $g$, $g$ eqd Id $\vee^{\text {r }}$ Read ${ }^{c o}{ }_{\text {Write }} g$ holds. From it, there are two cases. Left case. Assume $g$ eqd Id, then $f \circ g$ eqd $f$ by (COMPIDR). Applying each induction hypothesis
 imply the goal. Right case. Assume Read ${ }_{\text {co }{ }_{W r i t e}} g$. We prove ${\operatorname{Read}{ }^{{ }^{\circ}{ }_{W r i t e V} P}(f \circ g) \text { by using }}^{\text {a }}$ Read $^{-}$for Read ${ }^{\circ}{ }_{W r i t e} g$. Side base case. We prove

Let $g$ and $d$ be given and assume $g[0] \subseteq \square_{d}$ and ${ }^{\text {co }} \mathrm{Write}^{\left(\mathrm{Out}_{d} \circ g\right) \text {. Applying the assumption }}$ $\forall_{g}^{\mathrm{nc}}\left({ }^{\mathrm{co}}\right.$ Write $\left.g \rightarrow \operatorname{Read}_{\mathrm{co}_{\text {Writevd }} P}\left(\left(f \circ \mathrm{In}_{d}\right) \circ g\right)\right)$ to ${ }^{\mathrm{co}^{\mathrm{W}} \mathrm{Write}\left(\mathrm{Out}_{d} \circ g\right) \text { and using INOUTIDENT, }, ~}$ we can prove $\operatorname{Read}_{\mathrm{co}_{\mathrm{WriteV}}{ }^{\mathrm{d}}( }(f \circ g)$. Side step case. We prove

$$
\begin{aligned}
& \forall_{g}^{\mathrm{nc}}\left(\operatorname{Read}_{\text {co }_{\text {Write }}}\left(g \circ \operatorname{In}_{\mathrm{L}}\right) \rightarrow \operatorname{Read}_{\mathrm{co}_{\text {Write }} P}\left(f \circ\left(g \circ \operatorname{In}_{\mathrm{L}}\right)\right) \rightarrow\right. \\
& \operatorname{Read}_{{ }_{\text {co }}^{\text {Write }}}\left(g \circ \operatorname{In}_{M}\right) \rightarrow \operatorname{Read}_{{ }_{\text {co }}^{\text {Write } V} P}\left(f \circ\left(g \circ \operatorname{In}_{M}\right)\right) \rightarrow \\
& {\operatorname{Read}{ }_{c o}{ }_{\text {Write }}\left(g \circ \operatorname{In}_{\mathrm{R}}\right) \rightarrow \operatorname{Read}_{\mathrm{co}_{\mathrm{Write}} P}\left(f \circ\left(g \circ \operatorname{In}_{\mathrm{R}}\right)\right) \rightarrow}(f) \\
& \left.\operatorname{Readco}^{\mathrm{Write} V} P(f \circ g)\right) \text {. }
\end{aligned}
$$

 of $\operatorname{Read}_{1}^{+}$.

Remark 3.7.4. Berger's proof of the proposition of composition (Proposition 4.2 in [Ber11]) uses a lemma $\forall_{f}^{\mathrm{nc}}\left({ }^{\mathrm{co}} \mathrm{Write} f \rightarrow{ }^{\mathrm{co}} \operatorname{Write}\left(f \circ \operatorname{In}_{i, d}\right)\right)$ (Lemma 4.1 in [Ber11]). This is needed to deal with arbitrary $n$-ary functions. Since we restricted our case study to unary functions, it is unnecessary to consider this lemma.

### 3.7.3 Program Extraction

We extract from the proof of Proposition 3.7 .3 a program cmp as shown in Figure 3.22 . Inside of cmp, there is an occurrence of $M$ which stands for a program separately shown in Figure 3.23 . Suppose that $w_{0}$ and $w_{1}$ of type $\mathbf{W}$ are given to cmp. Unfolding the corecursion

$$
\begin{aligned}
& \lambda_{w_{0}, w_{1}}\left({ }^{(\mathrm{co}} \mathcal{R}_{\mathbf{W}}^{\mathbf{W} \times \mathbf{W}}\right. \\
& \left\langle w_{0}, w_{1}\right\rangle \\
& \lambda_{w w}\left(\text { Case } \mathcal{D}\left(\text { Case } w w \text { of } \lambda_{w_{2}, w_{3}} w_{2}\right)\right. \text { of } \\
& \lambda_{-} \text {Case } \mathcal{D}\left(\text { Case } w w \text { of } \lambda_{w_{2}, w_{3}} w_{3}\right) \text { of } \\
& \lambda_{-}(\operatorname{InL} \mathbf{U}) \\
& \lambda_{r w}\left(\operatorname { l n R } \left(\mathcal{R}_{\mathbf{R}_{\mathbf{W}}} r w\right.\right. \\
& \lambda_{d, w_{4}}\left(\operatorname{Put} d\left(\operatorname{InL} w_{4}\right)\right) \\
& \left.\left.\lambda_{-, q_{0},, q_{1},, q_{2}}\left(\operatorname{Get} q_{0} q_{1} q_{2}\right)\right)\right) \\
& \lambda_{r w}\left(\text { Case } \mathcal{D}\left(\operatorname{Case} w w \text { of } \lambda_{w_{2}, w_{3}} w_{3}\right)\right. \text { of } \\
& \lambda_{-}\left(\operatorname { I n R } \left(\mathcal{R}_{\mathbf{R}_{\mathbf{W}}} r w\right.\right. \\
& \lambda_{d, w_{4}}\left(\operatorname{Put} d\left(\operatorname{InL} w_{4}\right)\right) \\
& \left.\left.\lambda_{-, q_{0},, q_{1},, q_{2}}\left(\operatorname{Get} q_{0} q_{1} q_{2}\right)\right)\right) \\
& \left.\left.\left.\lambda_{-}\left(\mathrm{M} r w\left(\operatorname{Case} w w \text { of } \lambda_{w_{0}, w_{1}} w_{1}\right)\right)\right)\right)\right)
\end{aligned}
$$

Figure 3.22: $\mathrm{cmp}^{\mathbf{w}} \rightarrow \mathbf{w} \rightarrow \mathbf{w}$
operator, there are four cases comming from $\mathcal{D} w_{0}$ and $\mathcal{D} w_{1}$ as in the proof. If both of them are the left injection of the unit, it results in Stop. If one is the right injection of some $r$ of type $\mathbf{R}_{\mathbf{W}}$ and the other is the left injection of the unit, it works so that the corecursion produces Cont $r$. By means of the corecursion on $\mathbf{W}$, every $\mathbf{W}$-cototal ideals appearing at the end of $r$ is tagged as the next output by being injected to the left at Put. Considering the type of the costep term $\tau \rightarrow \mathbf{U}+\mathbf{R}_{\mathbf{W}+\tau}$, the value is injected at the position of $\mathbf{W}$ by $\operatorname{lnL}$. The last case is taken care of by M. If both of the results of destructing $w_{0}$ and $w_{1}$ are the right injection, suppose that $\mathcal{D} w_{0}=\ln \mathrm{R} r$. Inside of the recursion on this $r$, it generates

$$
\begin{aligned}
& \lambda_{r w, w}\left(\operatorname { l n } \mathrm { R } \left(\mathcal{R}_{\mathbf{R}_{\mathbf{W}}} r w\right.\right. \\
& \lambda_{d, w_{0}, w_{1}}\left(\operatorname{Put} d\left(\operatorname{lnR}\left\langle w_{0}, w_{1}\right\rangle\right)\right) \\
& \lambda_{-, f_{0},-, f_{1},-, f_{2}, w_{0}} \text { (Case } \mathcal{D} w_{0} \text { of } \\
& \lambda_{-}\left(\operatorname{Get}\left(f_{0} w_{0}\right)\left(f_{1} w_{0}\right)\left(f_{2} w_{0}\right)\right) \\
& \lambda_{r w}(\mathcal{R} r w \\
& \lambda_{d, w_{1}} \text { (Case } d \text { of }\left(f_{0} w_{1}\right) \\
& \left(f_{1} w_{1}\right) \\
& \left.\left(f_{2} w_{1}\right)\right) \\
& \left.\left.\lambda_{\_, r_{0},-, r_{1},-, r_{2}}\left(\operatorname{Get} r_{0} r_{1} r_{2}\right)\right)\right) \\
& \text { w)) }
\end{aligned}
$$

Figure 3.23: $\mathbf{M}^{\mathbf{R}_{\mathbf{W}} \rightarrow \mathbf{W} \rightarrow \mathbf{U}+\mathbf{R}_{\mathbf{W}+\mathbf{w} \times \mathbf{w}}}$
one $\mathbf{R}_{\mathbf{W}}$-total ideal by reading off finite information of $w_{1}$ from its root. The number of $\mathbf{R}_{\mathbf{W}}$-total trees to read depends on the height of $r$.

### 3.7.4 Experiments

We compose two uniformly continuous functions $f_{1}(x)=2 x^{2}-1$ and $f_{2}(x)=\sqrt{\frac{x}{2}+1} \frac{\text {. We }}{}$ define type- 1 uniformly continuous functions $\left\langle h_{1}, \alpha_{1}, \omega_{1}\right\rangle$ and $\left\langle h_{2}, \alpha_{2}, \omega_{2}\right\rangle$ as follows.

$$
\begin{aligned}
& h_{1} a n=a^{2}-1, \quad \alpha_{1} n=n+1, \quad \omega_{1} n=n+1, \\
& h_{2} a n=\mathcal{R} n 1 \lambda_{b, n}\left(\frac{b+\frac{c_{a}}{b}}{2}\right), \quad \alpha_{2} n=n+1, \quad \omega_{2} n=n,
\end{aligned}
$$

where $c_{a}=\frac{\frac{a}{2}+1}{2}$. The type- 0 represented functions are obtained by means of ucf 1 to 0 . Then cmp computes the composition, which results in $g(x)=\frac{x}{2}$.

### 3.8 Integration

For the last case study of this chapter, we study definite integration. We extract a program to compute the definite integral of a type- 0 uniformly continuous function in type- 1 real numbers. As in the last sections, we consider uniformly continuous functions with domain and codomain being $[-1,1]$. For simplicity of the formalization, we consider the half of the integral value, so that the integration of a uniformly continuous function is in $[-1,1]$ without loss of the information. The basic idea of integration is said to be "split and accumulate". The computational content of our proof is exactly an implementation of this idea.

### 3.8.1 Definitions

We define the abstract theory to study definite integral. Let $\rho$ and $\phi$ be abstract types of real numbers and uniformly continuous functions, respectively. Suppose that $x$ and $y$ range over $\rho, f$ ranges over $\phi, p$ and $q$ range over $\mathbf{Q}, d$ ranges over $\mathbf{S D}$ and $n$ ranges over $\mathbf{N}$. As in Definition 3.3.2, Z is a constant of type $\rho$. We extend Axiom 3.3.5 by adding the followings.

Axiom 3.8.1 (Abstract theory of real numbers for definite integration).

$$
\begin{align*}
& \forall_{n}\left(\mathrm{Z} \in \mathbb{\square}_{0, n}\right)  \tag{RealZero}\\
& \forall_{x, y, p, q, n}\left(x \in \mathbb{\square}_{p, n} \rightarrow y \in \mathbb{\square}_{q, n} \rightarrow \frac{x+y}{2} \in \mathbb{\square}_{\frac{p+q}{2}, n}\right) \tag{RealAvrg}
\end{align*}
$$

The rest is to deal with integration in the abstract setting.
Definition 3.8.2 (Integration). Let $\int^{\mathrm{H}}$ be a constant of type $\phi \rightarrow \rho$.
This constant is intended to mean the half of the definite integration. The properties of this integration is specified by the following axioms. The constants Id, Out ${ }_{d}$ and $\mathrm{In}_{d}$ are as defined in Section 3.5,

Axiom 3.8.3 (Abstract Theory of Integration).

$$
\begin{align*}
& \forall_{f}\left(\int^{\mathrm{H}} f \in \mathbb{\square}\right)  \tag{HIntBound}\\
& \int^{\mathrm{H}} \operatorname{Id} \text { eqd Z }  \tag{HIntId}\\
& \forall_{f, d}\left(\int^{\mathrm{H}} f \text { eqd } \frac{1}{2}\left(\int^{\mathrm{H}}\left(\mathrm{Out}_{d} \circ f\right)+d\right)\right)  \tag{HIntOut}\\
& \forall_{f}\left(\int^{\mathrm{H}} f \operatorname{eqd} \frac{1}{2}\left(\int^{\mathrm{H}}\left(f \circ \mathrm{In}_{\mathrm{L}}\right)+\int^{\mathrm{H}}\left(f \circ \mathrm{In}_{\mathrm{R}}\right)\right)\right) \tag{HIntIn}
\end{align*}
$$

The definite integration is bounded in $[-1,1]$ by (HInTBOUND). The definite integral of the identity function is 0 due to (HINTID). Recall that intuitively Out ${ }_{d} \circ f(x)=2 f(x)-d$. A special case of the property $\int f(x) d x=\frac{1}{2} \int 2 f(x) d x$ is given by HIntOUT). In usual settings, $\int_{a}^{b} f$ can be computed by $\int_{a}^{c} f+\int_{c}^{b} f$. A special case of this property holds by (HInTIN) which postulates that $\int_{-1}^{1} f$ is equal to $\int_{-1}^{0} f+\int_{0}^{1} f$.

### 3.8.2 Proofs

We prove the following proposition from which we extract a program to compute integration.

## Proposition 3.8.4.

$$
\forall_{f}^{\mathrm{nc}}\left({ }^{\mathrm{co}} \text { Write } f \rightarrow \forall_{n}^{\mathrm{c}} \exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \square_{p, n}\right)\right) .
$$

Proof. The statement is same as $\forall_{n}^{\mathrm{c}} \forall_{f}^{\mathrm{nc}}\left({ }^{\text {co }}\right.$ Write $\left.f \rightarrow \exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \square_{p, n}\right)\right)$. We prove it by induction on $n$. Case $n=0$. Our goal is $\forall_{f}^{\mathrm{nc}}\left({ }^{\mathrm{co}}\right.$ Write $\left.f \rightarrow \exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \mathbb{a}_{p, 0}\right)\right)$. Let $f$ be given and assume ${ }^{\text {co }}$ Write $f$. Let $p$ be 0 , then it is clear by (HIntBound). Case $n \mapsto n+1$. From the following induction hypothesis,

$$
\begin{equation*}
\forall_{f}^{\mathrm{nc}}\left({ }^{\mathrm{co}} \text { Write } f \rightarrow \exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \mathbb{\square}_{p, n}\right)\right), \tag{3.8}
\end{equation*}
$$

we prove $\forall_{f}^{\text {nc }}\left({ }^{\text {co }}\right.$ Write $\left.f \rightarrow \exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \mathbb{\square}_{p, n+1}\right)\right)$. Let $f$ be given and assume ${ }^{\text {co }}$ Write $f$. We prove $\exists_{p}^{\mathrm{l}}\left(\int^{\mathrm{H}} f \in \mathbb{a}_{p, n+1}\right)$. Applying ${ }^{{ }^{\mathrm{c}}{ }^{\circ} \text { Write }^{+}}$to ${ }^{\text {co }}$ Write $f$, there are two cases from
 $\square_{0, n+1}$, which holds by RealZero. Right case. Assume Readco ${ }_{\text {Write }} f$ and use Read ${ }^{-}$for it. Side base case. We prove

$$
\forall_{f}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(f[0] \subseteq \square_{d} \rightarrow{ }^{\mathrm{co}} \operatorname{Write}\left(\mathrm{Out}_{d} \circ f\right) \rightarrow \exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \mathbb{a}_{p, n+1}\right)\right) .
$$

Let $f, d$ be given and assume $f[\square] \subseteq \square_{d}$ and ${ }^{\text {co }} \operatorname{Write}\left(\operatorname{Out}_{d} \circ f\right)$. Our goal is $\exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \square_{p, n+1}\right)$. Applying (3.8) to ${ }^{\text {co }} \mathrm{Write}\left(\mathrm{Out}_{d} \circ f\right)$, there is some $p^{\prime}$ such that $\int^{\mathrm{H}}\left(\mathrm{Out}_{d} \circ f\right) \in \rrbracket_{p^{\prime}, n}$, which implies $\frac{1}{2}\left(\int^{\mathrm{H}}\left(\mathrm{Out}_{d} \circ f\right)+d\right) \in \mathbb{\square}_{\frac{p^{\prime}+d}{2}, n+1}$ by AvINTRO. It moreover implies $\int^{\mathrm{H}} f \in \mathbb{\square}_{\frac{p^{\prime}+d}{2}, n+1}$
by HIntOut). We use $\left(\exists^{1}\right)^{+}$with $\frac{p^{\prime}+d}{2}$ to derive the goal. Side step case. We prove

$$
\begin{aligned}
& \forall_{f}^{\mathrm{nc}}\left(\operatorname{Read}_{\mathrm{co} \text { Write }}\left(f \circ \operatorname{In}_{\mathrm{L}}\right) \rightarrow \exists_{p}^{1}\left(\int^{\mathrm{H}}\left(f \circ \operatorname{In}_{\mathrm{L}}\right) \in \mathbb{D}_{p, n+1}\right) \rightarrow\right.
\end{aligned}
$$

$$
\begin{aligned}
& \left.\operatorname{Read}_{{ }_{\mathrm{o}}{ }_{\text {Write }}}\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \rightarrow \exists_{p}^{1}\left(\int^{\mathrm{H}}\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \in \mathbb{\square}_{p, n+1}\right) \rightarrow \exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \mathbb{\square}_{p, n+1}\right)\right) .
\end{aligned}
$$

Let $f$ be given and assume the premises. To prove our goal $\exists_{p}^{1}\left(\int^{\mathrm{H}} f \in \square_{p, n+1}\right)$, the following two side induction hypotheses are used:

$$
\exists_{p}^{1}\left(\int^{\mathrm{H}}\left(f \circ \operatorname{In}_{\mathrm{L}}\right) \in \mathbb{a}_{p, n+1}\right) \text { and } \exists_{p}^{\mathrm{l}}\left(\int^{\mathrm{H}}\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \in \mathbb{a}_{p, n+1}\right) .
$$

From the above side induction hypotheses, there are $p_{\mathrm{L}}$ and $p_{\mathrm{R}}$ such that $\int^{\mathrm{H}}\left(f \circ \mathrm{In}_{\mathrm{L}}\right) \in \mathbb{\square}_{p_{\llcorner }, n+1}$ and $\int^{\mathrm{H}}\left(f \circ \operatorname{In}_{\mathrm{R}}\right) \in \mathbb{a}_{p_{\mathrm{R}}, n+1}$. Using REALAVRG and HINTIN, $\int^{\mathrm{H}} f \in \frac{p_{\frac{p_{L}+p_{\mathrm{R}}}{2}, n+1}}{}$ holds. Then the goal comes by $\left(\exists^{1}\right)^{+}$.

### 3.8.3 Program Extraction

We extract from Proposition 3.8 .2 the program int which computes the half of the integral of a type-0 uniformly continuous function. This program reads the given type-0 function

$$
\begin{aligned}
& \lambda_{w, n}\left(\mathcal{R}_{\mathbf{N}}^{\mathbf{W} \rightarrow \mathbf{Q}} n \lambda_{-} 0\right. \\
& \lambda_{-, g} \mathbf{w} \rightarrow \mathbf{Q}, w_{0}\left(\text { Case } \mathcal{D} w_{0}\right. \text { of } \\
& \text { InL U } \rightarrow 0 \\
& \operatorname{InR} r \rightarrow \mathcal{R}_{\mathbf{R}_{\mathbf{W}}}^{\mathbf{Q}} r \lambda_{d, w_{2}}\left(\frac{g\left(w_{2}\right)+d}{2}\right) \\
& \left.\lambda_{-, p_{\mathrm{L}},, p_{\mathrm{M}},,, p_{\mathrm{R}}}\left(\frac{p_{\mathrm{L}}+p_{\mathrm{R}}}{2}\right)\right)
\end{aligned}
$$

w)

## Figure 3.24: int $^{\mathbf{W} \rightarrow \mathbf{N} \rightarrow \mathbf{Q}}$

to accumulate the possible output digits to compute the definite integral. The second argument is a number $n$ to specify the bound of the computation in such a way that the program processes the read-write machine from its root up to the $n$-th $\mathbf{R}_{\mathbf{W}}$-total ideals. At a branch, the recursively computed integral from the middle interval, which is denoted by
an unused variable $p_{\mathrm{M}}$, is ignored because it suffices to see value on the left and the right subintervals, namely, $[-1,0]$ and $[0,1]$. At a leaf, the output digit is counted to contribute to the output with concerning its height in the tree. The base case of the the side recursion takes care of it by computing a value with division by 2 . Consider $\mathbf{R}_{\mathbf{W}}$-total ideals inside of a $\mathbf{W}$-cototal $\mathbf{R}_{\mathbf{W}}$-total ideal. In the $n$-th height from the root, there are $2^{n}$ signed digits to count at the Put nodes. Indeed, this int is an implementation of what Bishop and Bridges [BB85] have mentioned, namely, the averaging process.

### 3.8.4 Experiments

We compute half of the definite integral for the function $f(x):=\sqrt{x+2}-1$. This integrand is defined to be $\langle h, \alpha, \omega\rangle$, where $h$ a $n:=\left(\mathcal{R}_{\mathbf{N}} n 1 \lambda_{-, b}\left(\frac{b+\frac{a+2}{b}}{2}\right)\right)-1, \alpha n:=n+1$, and $\omega n:=n$ where Pred : $\mathbf{N} \rightarrow \mathbf{N}$ is the predecessor function given in Example 2.2.38. We give two arguments to int, a type-0 function and a natural number. The first input to int is computed by ucf1to0 from the above type- 1 function. Specifying 8 as the second input, the output is $\frac{1633}{4096}$ whose decimal expansion is $0.398681640625 \cdots$. Comparing our result with the manually calculated definite integral $\frac{1}{2} \int_{-1}^{1} f(x) d x=\sqrt{3}-\frac{4}{3}$, the error is $0.00003583 \cdots$, which is smaller than $2^{-8}=0.00390625$.

### 3.9 Notes

We describe related work, future work and remarks for concluding this chapter.

### 3.9.1 Exact Real Arithmetic via Streams

An early work on algorithms of stream represented real numbers is by Wiedmer Wie77, Wie80. He describes exact computation of real numbers and foundation of computability of infinite objects, and shows many case studies including the average of real numbers in the SDS representation. Ciaffaglione and Di Gianantonio CG99, CG00, CG06 study the stream representation of real numbers by means of coinduction in Coq, namely, in a logical framework. Plume Plu98] describes an informative report on exact real arithmetic and an implementation of a calculator for exact real number computation. His work includes an implementation of the average of signed digit streams as which our extracted program is essentially the same. Ghani, Hancock and Pattinson [GHP06, HPG09] study type-0 uniformly continuous functions, so-called stream processors, in coalgebraic setting. Abel Abe07 studies mixed inductive/coinductive types and describes the composition of stream processors in a setting of equi-inductive types and equi-coinductive types. Formal certification of algorithms of exact real arithmetic is studied by Hou Hou06, Berger and Hou [BH08]. They have certified algorithms which compute multiplication, division and limit of real sequences as well as translators between Cauchy reals and SDSs and average.

### 3.9.2 Program Extraction

Berger and Seisenberger [BS10, BS12] study a framework of program extraction supporting induction and coinduction, and informally reading-off the extracted program for the average of type-0 real numbers. Berger Ber09, Ber11] gives a case study for type-0 representation of uniformly continuous functions, so-called read and write machines. Being heavily based on their work, we have given computer implemented case studies on exact real arithmetic. An extraction of the average program is done in Agda by Chuang [Chu11] by making use of Agda postulates. In contrast to the case of TCF (cf. also [MS13]), it requires a special care to guarantee that Agda postulates do not prevent normalization. It is taken care of by non-computational logical connectives in TCF and Minlog. Chuang Chu11 moreover studies extraction of multiplication of exact real numbers in Agda.

### 3.9.3 Abstract Theory

The idea to make use of abstract theory in the context of program extraction is due to Berger [Ber09]. In our case studies, axioms are supposed to be valid in some model. For example, we can take a concrete theory of uniformly continuous functions in $[-1,1]$, e.g. formulated by type-1 uniformly continuous functions. Instantiating the abstract type $\phi$ of uniformly continuous functions by the concrete type of type- 1 uniformly continuous functions, the axioms can be proven. An issue arises when we consider to give arguments to an extracted program, although the extracted program itself is certified by soundness. A hand prepared input given to an extracted program should also be correct in the theory of program extraction. For example, a hand prepared type-1 uniformly continuous function $\left\langle\lambda_{a, n}(-a), n+1\right.$, Pred $\left.n\right\rangle$ in Section 3.5.4 should be a realizer of $C f$ for some $f$. If we can specify a term $f$ of the abstract type $\phi$ or instantiate the abstract theory by a concrete one, the problem is solved.

### 3.9.4 Formalizing $n$-Ary Uniformly Continuous Functions

According to Berger, $n$-ary type-0 uniformly continuous functions can be viewed as $3^{n}$ branching trees Ber09. Although the theoretical treatment can be cleanly generalized through the general view by Berger, it still requires the base theory to be able to formalize algebras, predicates and abstract theories in a generalized way. We consider an extension of the algebra $\mathbf{R}_{\alpha}$ and $\mathbf{W}$. Let $\mathbf{S D}^{n}$ be an $n$-products of $\mathbf{S D}$. For instance, $\mathbf{S D}^{0}$ is empty, $\mathbf{S D}^{1}$ is same as $\mathbf{S D}$ and $\mathbf{S D}^{2}$ is a type of pairs of $\mathbf{S D}$. We define $\mathbf{R}_{\alpha}^{n}$ to be $\mu_{\xi}\left(\mathbf{S D} \rightarrow \alpha \rightarrow \xi,\left(\mathbf{S D}^{n} \rightarrow \xi\right) \rightarrow \xi\right)$. The algebra $\mathbf{W}^{n}$ is defined to be $\mu_{\xi}\left(\xi, \mathbf{R}_{\xi}^{n} \rightarrow \xi\right)$. Then, $\mathbf{W}^{0}$ is another way to represent $\mathbf{I}, \mathbf{W}^{1}$ is same as $\mathbf{W}$ and $\mathbf{W}^{n}$ consists of finite trees of $\mathbf{R}_{\mathbf{W}^{n}}^{n}$, where there are $3^{n}$ branches at the get node and the put node carries $\mathbf{S D}^{n}$ and $\mathbf{W}^{n}$. This represents $n$-ary uniformly continuous functions. In the same manner, one can also consider an extension of the predicates Read and ${ }^{\text {co }}$ Write. Let $f$ range over $\phi^{n}$, an abstract $n$-ary uniformly continuous function, and $e$ range over $\mathbf{S D}^{n}$. The constants $\mathrm{Id}^{n}$, Out ${ }_{n}$ and $\mathrm{In}_{n}$ of types $\phi^{n}, \mathbf{S D}^{n} \rightarrow \phi^{n} \rightarrow \phi^{n}$ and $\mathbf{S D}^{n} \rightarrow \phi^{n} \rightarrow \phi^{n}$, respectively, can be given as well.

We denote by $\square^{n}$ the unit interval of $n$-dimension. Then, the introduction axioms and the closure axiom look as follows. Let $d$ and $e$ range over $\mathbf{S D}$ and $\mathbf{S D}^{n}$, respectively.

$$
\begin{aligned}
& \forall_{f} \forall_{d}^{\mathrm{c}}\left(f\left[\left[^{n}\right] \subseteq \square_{d} \rightarrow X\left(\operatorname{Out}_{n, d} \circ f\right) \rightarrow \operatorname{Read}_{X}^{n} f\right), \quad\left(\operatorname{Read}^{n}\right)_{0}^{+}\right. \\
& \forall_{f}\left(\forall_{e}^{c}\left(\operatorname{Read}_{X}^{n}\left(f \circ \operatorname{In}_{n, e}\right)\right) \rightarrow \operatorname{Read}_{X}^{n} f\right), \quad\left(\operatorname{Read}^{n}\right)_{1}^{+} \\
& \forall_{f}\left({ }^{\left({ }^{c o} W_{i t e}\right.}{ }^{n} f \rightarrow f \text { eqd Id }{ }^{n} \vee \operatorname{Read}_{\text {co Write }}^{n} f\right) . \quad\left({ }^{\text {co }}{ }^{n} \text { Write }^{n}\right)^{-}
\end{aligned}
$$

For $n=0,\left(\operatorname{Read}^{n}\right)_{0}^{+}$works as the right disjunct of the conclusion of ${ }^{c o} I^{-}$, and $\left(\operatorname{Read}^{n}\right)_{1}^{+}$ becomes empty because the type of $e$ is empty. Since they generally work for $n$-ary uniformly continuous functions, the application in Section 3.6 can be done by means of ${ }^{\text {co }}$ Write ${ }^{0}$ and ${ }^{\text {co }}$ Write ${ }^{1}$, the composition can be done by ${ }^{\text {co }}$ Write ${ }^{1}$ and ${ }^{\text {co } W r i t e ~}{ }^{1}$. Berger [Ber11 proves the following in his framework: Let $f$ be an $n$-ary real function and $g_{i}$ be $m$-ary ones for $i=1, \ldots, n$, then ${ }^{\text {co }}$ Write $^{n} f$ and ${ }^{\text {co }} W_{\text {Write }}{ }^{m} g_{i}$ for each $i$ imply ${ }^{\text {co }}{ }^{W}$ Write $^{m}\left(f \circ\left(g_{1}, \ldots, g_{n}\right)\right)$. It is a possible future work to extract from a formalized proof of the above proposition a program which computes a composition of $n$-ary and $m$-ary type- 0 uniformly continuous functions.

## Chapter 4

## Concluding Remarks

### 4.1 Overview of this Thesis

In this Thesis we have studied program extraction from nested inductive and coinductive proofs. Our aim is to present a formalized theoretical framework for program extraction supporting nested inductive and coinductive definitions and a proof assistant within which program extraction can be practiced. We have enriched the Theory of Computable Functionals, so that nested inductive and coinductive definitions can be used for program extraction. We have implemented additional features for nested inductive and coinductive definitions to the proof assistant Minlog, which has been developed at the logic group of the University of Munich for more than 20 years. In order to practice program extraction in our framework with nestedness, we have formalized case studies in exact real arithmetic due to Berger and Seisenberger using Minlog. Non-trivial algorithms dealing with exact real numbers and uniformly continuous functions are mechanically extracted from proofs as executable programs in Minlog.

### 4.2 Contributions

We have enriched the Theory of Computable Functionals by introducing nestedness. Inductive and coinductive definitions can be combinated by nestedness in the proof theoretical side. The recursion and corecursion operators in the formal calculus $\mathrm{T}^{+}$have been enriched to support nestedness in the computational side. Concerning the realizability interpretation, the soundness theorem and the program extraction procedure have been extended to accommodate nestedness and coinductive definitions.

The theoretical improvement of the Theory of Computable Functionals has been implemented as additional features of the proof assistant Minlog, a computer implementation of the Theory of Computable Functionals. The current Minlog is able to deal with nested algebra definitions, constants, e.g. recursion and corecursion operators, on nested algebras, coinductive and nested definitions, proofs involving such definitions, and program extraction from nested inductive and coinductive proofs.

Within the Theory of Computable Functionals and the proof assistant Minlog, we formalized case studies due to Berger and Seisenberger in exact real arithmetic based on coinductive setting. Computational content from their proof, which was informally read off by Berger and Seisenberger, has been formally extracted by Minlog. Our formalization of exact real arithmetic in Minlog, which contains topics listed below, is currently a part of the downloadable Minlog package.

1. A translator from a rational number into a real number of type-0 [BMSS11].
2. A translator between a real number of type-1 and a real number of type-0 [Ber09].
3. The average of two real numbers of type-0 Chu11, BS12, MS13.
4. A translator between a uniformly continuous function of type-1 and a uniformly continuous function of type-0 [Ber09, Ber11, MFS13].
5. The application of a uniformly continuous function of type-0 to a real number of type-0 Ber09, Ber11].
6. The composition of two uniformly continuous functions of type-0 [Ber09, Ber11].
7. The definite integration of a uniformly continuous function of type-0 Ber09, Ber11, MFS13.

### 4.3 Future Work

We illustrate three possible topics for future work. The first one is proof normalization involving coinductively defined predicates. The second is extending a feature of Minlog for automatic generation of program certifications involving nested definitions and coinductive definitions. The third is further exploration of program extraction in exact real arithmetic.

### 4.3.1 Proof Normalization

Through coinductive definitions, TCF is extended by additional closure and greatest-fixedpoint axioms. As we saw, proof conversion rules are applicable if a greatest-fixed-point axiom is followed by a closure axiom, so that the use of closure axiom is eliminated. The proof normalization theorem for TCF with coinductive definitions is expected to hold, and it is a possible future work. Applying program extraction to a proof of the normalization theorem, an NbE algorithm supporting coinductive definitions can be obtained Ber93, BBLS06.

### 4.3.2 Automatic Program Certification

The proof of Theorem 2.5.29 (Soundness) contains an informal algorithm to generate soundness proofs, namely, a given proof $M$ of $A$ can be transformed into a proof $M^{\prime}$ of $A^{\mathbf{r}}(\operatorname{et}(M))$. An implementation of the computational content of the proof of the soundness
theorem enables Minlog to automatically generate the proof $M^{\prime}$ from $M$. In other words, this is a feature to issue a certification of an extracted program. Currently, Minlog is able to deal with proofs involving simultaneous non-nested inductive definitions to generate soundness proofs. Minlog can automatically generate a soundness proof also for an extracted program from a nested and coinductive proof, provided the current feature is improved to cover the absent cases. This is a crucial step for Minlog to become a software development environment for certified programs.

The roadmap is as follows. The current Minlog feature for automation has to be extended to cover the cases of closure axioms and greatest-fixed-point axioms of coinductively defined predicates. The use of Lemma 2.5.30 (Soundness for monotonicity formulas) has to be taken care of. The computational content of this lemma generates a proof stating that a monotonicity formula is realized by the corresponding map operator. Generated soundness proofs are needed to complete the nested cases of $I^{-}$and ${ }^{\text {co } I^{+} \text {in the proof of Lemma 2.5.31 }}$ (Soundness for axioms of inductive and coinductive definitions).

### 4.3.3 Formalizing $n$-Ary Uniformly Continuous Functions

In contrast to the original work by Berger, our formalization is limited to unary uniformly continuous functions. It is left as a future work to formalize $n$-ary uniformly continuous functions in a coinductive setting. While 3-branching trees are used in the unary case, $3^{n}$-branching trees suffice to represent $n$-ary uniformly continuous functions. We propose to use the type $\mathbf{S D}^{n}$ which is $n$-tuple of the signed digit algebra $\mathbf{S D}$ instead of $\mathbf{S D}$ as we used. It can be done by using another framework as Martin-Löf's type theory, or by extending the type system of TCF to dependent types. The type $\mathbf{S D}^{n}$ is defined as a type dependent on a term $n$, and the algebras $\mathbf{R}_{\alpha}$ and $\mathbf{W}$ are also parameterized by $n$. Terms in $\mathrm{T}^{+}$and inductive and coinductive definitions are also to be extended to formalize the idea of Berger.

## Appendix A

## Proof Assistant Minlog

This appendix describes the proof assistant Minlog. Minlog has been developed by Schwichtenberg and his colleagues for more than 20 years [Sch92, Min. Minlog is an implementation of TCF, namely, the goal is to make any activity based on TCF doable in Minlog. Proofs are interactively built by a human with some support of automated proof searching. It extracts from constructive proofs computational content based on Kreisel's modified realizability interpretation. Program extraction from non-constructive proofs is also supported by means of the refined A-translation [BBS02, Rat11] and Gödel's dialectica interpretation [Sch08, Tri12]. Terms in $\mathrm{T}^{+}$can be exported to general-purpose programming language as Scheme and Haskell. Especially, $\mathrm{T}^{+}$is fully supported for the Haskell export which is due to Nordvall MFS13]. Minlog is implemented in Scheme, and interfaces for human to use Minlog are provided as Scheme procedures.

This appendix consists of two sections. In the first section we discuss technical aspects of the Minlog implementation, being focused on normalization by evaluation, recursion and corecursion operators and inductive and coinductive definitions. In the second section we provide a commentary to work with the Minlog code to the case study given in Section 3.3.

## A. 1 Implementation

This section describes three selected topics from the implementation of Minlog. The first topic is term normalization of Minlog which is done by means of normalization by evaluation, NbE for short, described in Section 2.2.4. The second topic is the internal representation of recursion and corecursion operators. The third topic is the internal representation of inductive and coinductive definitions.

## A.1.1 Normalization by Evaluation

Minlog's normalization is done by means of the technique of NbE. The implementation is based on Section 2.2.4. The idea is that a term in $\mathrm{T}^{+}$is first sent to its denotation, and then we retrieve from the denotational object a term which is in normal form. The
representation of a semantic object in Minlog is a pair of a type and a native Scheme procedure. We call such a pair an $N b E$ object, and call a native Scheme procedure in an NbE object an $N b E$ value. Minlog has procedures to deal with NbE objects. Corresponding to term families mentioned in Section 2.2 .4 we also introduce procedures to send a term to a term family and vice versa. Proof normalization is also done by NbE through the correspondence between proofs and terms. Note that the extracted term from a proof carries less information than the proof, since non-computational information is thrown away due to the realizability. In order to recover the Curry-Howard correspondence, Minlog regards non-computational parts of formulas in the same way as computational ones in the case of proof normalization. Minlog uses the NbE algebras instead of the associated algebras of the defined predicate constants. In contrast to associated algebras, NbE algebras are defined with regard to non-computational universal quantifiers and implications in the same way as computational ones. Moreover, constants as recursion operators are allowed to carry reproduction data, which are used to reproduce the formula of the axiom from which these constants are extracted.

In this section, we describe technical details of the implementation of NbE in Minlog system.

## A.1.1.1 Term Family

In order to implement NbE , we have to deal with bound variables in in reifying an NbE object of higher type. A term family is used to implement the way to create bound variables. There is a procedure to form a term family.

## (nbe-make-termfam type proc)

The internal representation of term families is of the form ('termfam type proc) where the type, type, is an internal representation of a type and the NbE value, proc, is a native Scheme function procedure from a natural number $k$ to an internal representation of terms. The following procedure applies a term family termfam : $\mathbb{N} \rightarrow \Lambda_{\rho}$ to a natural number $k: \mathbb{N}$ to get a term of $\Lambda_{\rho}$.

$$
\text { (nbe-fam-apply termfam } k \text { ) }
$$

This procedure applies the NbE value of termfam of the form (lambda (k) ...) to $k$. The following procedures sends a term to a term family and vice versa.

```
(nbe-term-to-termfam term)
(nbe-extract termfam)
```

The procedure nbe-term-to-termfam gives the term family by making a case distinction on the construction of the given term. In any case the type is computed by term-to-type. If the outermost construction of term is a variable or a constant, the NbE value of the result is (lambda (k) term). If term is an abstraction $\lambda_{x} t$, the term family is given by

Listing A.1: Abstraction case in nbe-term-to-termfam

```
(let* ((var (term-in-abst-form-to-var term))
    (type (var-to-type var))
    (kernel (term-in-abst-form-to-kernel term)))
    (nbe-make-termfam
        (term-to-type term)
    (lambda (k)
        (let ((var-k (make-var type k (var-to-t-deg var) (var-to-name var))))
            (make-term-in-abst-form
                var-k
                (nbe-fam-apply
                    (nbe-term-to-termfam
                            (term-subst kernel var (make-term-in-var-form var-k)))
                            (+ 1 k)))))))
```

Listing A.2: Application case in nbe-term-to-termfam

```
(let ((op (term-in-app-form-to-final-op term))
    (args (term-in-app-form-to-args term)))
    (nbe-make-termfam
        (term-to-type term)
        (lambda (k)
            (apply mk-term-in-app-form
                    (map (lambda (x) (nbe-fam-apply (nbe-term-to-termfam x) k))
                    (cons op args))))))
```

the following code snippet. Let term be the given term. For the given term $\lambda_{x} t$, var and kernel in lines 1 and 3 correspond to $x$ and $t$, respectively. The variable name $x$ of abstraction is renamed to $x_{k}$, i.e., var- k , then the body of the function procedure is $\lambda_{x_{k}}\left(t\left[x / x_{k}\right]^{\infty}(k+1)\right)$. If term is an application $t \vec{s}$, where $|\vec{s}| \geq 1$, the term family is given by the following code snippet. Let term be the given term. For the given $t \vec{s}$, op and args correspond to $t$ and $\vec{s}$, respectively. Then, the body of the function (lines 6-8) constructs $t^{\infty}(k) s^{\infty}(k)$.

For a term family $r$ the procedure nbe-extract first computes the least natural number $k$ which is larger than any index of a variable in $r(0)$, then the term $r(k)$ is returned.

## A.1.1.2 Reflect and Reify

There are two (simultaneous) procedures which translate from a term family into an NbE object and vice versa.

```
(nbe-reflect termfam)
(nbe-reify object)
```

A term family is sent to an NbE object by nbe-reflect and the opposite direction is done by nbe-reify. The procedure nbe-reflect makes a case distinction on the type of the term family. If it is a type variable or an algebra, the NbE value is the term family, a native Scheme procedure. If it is an arrow type, the NbE value of the result is computed by the

Listing A.3: Arrow type case in nbe-reflect

```
(lambda (obj)
    (nbe-reflect (nbe-make-termfam
    (arrow-form-to-val-type type)
    (lambda (k)
        (make-term-in-app-form
                (nbe-fam-apply termfam k)
                (nbe-fam-apply (nbe-reify obj) k))))))
```

Listing A.4: Algebra case in nbe-reify

```
(let ((args (nbe-constr-value-to-args value)))
    (nbe-make-termfam
    type
        (lambda (k)
            (apply mk-term-in-app-form
                (cons (make-term-in-const-form
                            (nbe-constr-value-to-constr value))
            (map (lambda (obj)
                            (nbe-fam-apply (nbe-reify obj) k))
                args)))))(
```

following code snippet. Let type be the type of the given term family. Let a term family $\lambda_{x} t^{\infty}$ be given to nbe-reflect. The outermost (lambda (obj) ...) is a representation of the abstraction $\lambda_{x} \ldots$ as a native Scheme procedure. Intuitively the body is given by applying $t^{\infty}$ to obj. Formally, it first constructs a term family $\downarrow$ obj by reifying, then the body $t^{\infty}(k)(\downarrow \mathrm{obj})(k)$ is computed. Finally, nbe-make-termfam is applied to the body abstracted by k. At the end, we apply nbe-reflect which is corresponding to $\uparrow$.

The procedure nbe-reify takes an NbE object and retrieves a term family. A term family is built by induction on the type of the NbE object. If the type is a type variable, it returns the NbE value of the NbE object. If the type is an algebra, it checks by means of nbe-constr-value? whether this NbE object expresses $C \vec{t}$, a constructor $C$ with arguments $\vec{t}$. If this is the case, it makes a term family by the following code snippet. Assume type and value are the type and the NbE value of the given term family. Assume arguments args are prepared as NbE objects corresponding to $\vec{t}$ in line 1 . They become reified terms in lines $8-10$, then are given to the constructor to be an NbE value. If this is not the case, e.g. it is a variable, then it returns the NbE value of the NbE object. The next case is the arrow type. The following code snippet gives a term family from the NbE object. The procedure nbe-object-apply is for function application of NbE objects. Let type be the type of the given term family. The variable var-k is created with the index k which is abstracted by the native Scheme function abstraction. The NbE object obtained by applying the given NbE object obj to the NbE object of var-k is reified to the term family $\downarrow(\operatorname{obj}(\uparrow(\operatorname{var}-\mathrm{k})))$. Further applying this term family to $\mathrm{k}+1$ and abstracting by var- k , we obtain the very term in Definition 2.2.47.

Listing A.5: Arrow type case in nbe-reify

```
(let ((type1 (arrow-form-to-arg-type type)))
    (nbe-make-termfam
        type
        (lambda (k)
            (let ((var-k (make-var type1 k 1 (default-var-name type1))))
                (make-term-in-abst-form
                var-k (nbe-fam-apply
                            (nbe-reify
                        (nbe-object-apply
                        obj
                        (nbe-reflect (nbe-term-to-termfam
                        (+ k 1)))))))
```


## A.1.2 Recursion and Corecursion

Recursion and corecursion operators are constants which play an important role in the computational interpretation of inductive and coinductive definitions. We study the implementation of recursion and corecursion operators in Minlog.

It suffices to give (simultaneous) algebras $\vec{\iota}$ and types $\vec{\tau}$ to specify the recursion operator $\mathcal{R}_{\vec{l}, i}^{\vec{\tau}}$. We have the following procedure to compute a list of the internal representation of recursion operators.

```
(arrow-types-to-rec-consts . arrow-types)
```

For the argument arrow-types we give a list of types of the form $\iota_{i} \rightarrow \tau_{i}$ to specify the recursion operators. The following procedure makes an internal representation of a constant in general.

> (make-const obj-or-arity name kind uninst-type tsubst $t$-deg token-type . repro-data)

The internal representation of constant is just a list consists of 'const, the identifier for constants, as the head and the arguments given to the above procedure as the rest. The content of obj-or-arity in the case of recursion operator is an NbE object of the recursion operator. From the next components, name, kind, $t$-deg and token-type are for the name of the constant, the kind of the computation rule of the constant, the totality degree and the kind of token. In the case of recursion operators, name is "Rec", kind is 'fixed-rules meaning it is not user changeable, $t$-deg is 1 meaning it is a total functional, and tokentype is 'const meaning that this constant is written in a usual function application style, respectively. For uninst-type and tsubst we give the uninstantiated type of recursion operator and the type substitution which makes the instantiated type. An uninstantiated type is represented by taking all parameter types $\vec{\alpha}$ of algebras $\vec{\iota}$ and all covalue types $\vec{\tau}$ as type variables. The type substitution tells us what substitutes $\vec{\alpha}$ by $\vec{\tau}$. Some type variables may be left. A procedure arrow-types-to-uninst-recop-types-and-tsubst computes the
types of $\mathcal{R}_{\vec{\imath}, i}^{\vec{\tau}}$.
(arrow-types-to-uninst-recop-types-and-tsubst . arrow-types)
The return value of this procedure is a pair of a list of uninstantiated types of recursion operators and a type substitution. The last argument repro-data of make-const is optionally given when we normalize a proof. Proof normalization is implemented based on term normalization. Terms in $\mathrm{T}^{+}$are not sufficient to represent proofs. Minlog manages missing information by keeping additional information in the internal representation of recursion operator, so that it maintains the Curry-Howard isomorphism.

We explore the procedure rec-at which computes the NbE object of recursion operators and see what the NbE object of a recursion operator and how Minlog deals with it.

```
(rec-at alg-name uninst-recop-type tsubst inst-recop-type
    f rel-constr-names rel-simalg-names-with-uninst-recop-types .
    repro-data)
```

Consider the NbE object of a recursion operator $\mathcal{R}_{\vec{i}, i}^{\vec{\tau}}$ through rec-at. The first argument alg-name, which is $\iota_{i}$, determines on which algebra this recursion operator is defined. The type of the recursion operator is represented by a pair of the uninstantiated type of the recursion operator uninst-recop-type, and the substitution tsubst. For the efficiency reason, the instantiated type inst-recop-type is also given. The next argument $f$ carries the number of free variables (or parameters), which is needed in the case of proof normalization, when variables are quantified by the outermost non-computational universal quantifier of an elimination axiom. The following two arguments rel-constr-names and rel-simalg-names-with-uninst-recop-types depend on the simplification of recursion operators. Considering relevant simultaneous algebra names among all simultaneous algebras, rel-constr-names is a list of the names of constructors from the relevant algebras, and rel-simalg-names-with-uninst-recop-types is the list of pairs of a relevant algebra name and the uninstantiated type of a recursion operator on the relevant algebra. Assume that we are normalizing a proof involving an elimination axiom which is instantiated as $I \vec{t} \rightarrow \ldots \rightarrow P \vec{t}$. The last argument plays an important role when this recursion operator is used for proof normalization via the Curry-Howard correspondence. The reproduction data, repro-data, are then an implication formula $I \vec{t} \rightarrow P \vec{t}$ which is sufficient to recover how the elimination rule is used. The definition of rec-at is as follows. Let inst-recop-type, uninst-recop-type and repro-data be the given inst-recop-type, uninst-recop-type and repro-data, respectively. The return value is an NbE object constructed by the instantiated type of the recursion operator and the NbE value. The procedure nbe-curry does currying one argument objs into arguments of the number depicted by arity which is the sum of the number of step cases, parameters and 1 . The last 1 in line 4 is for the argument at which the recursion works. We take a closer look at the inside of the first argument of nbe-curry, namely, lines $10-11$. Let f be the given $f$ and suppose that nbe-for-idps? is an already computed boolean value. All arguments given to the recursion operator are kept by objs. There

Listing A.6: Structure of rec-at

```
(let* ((f-plus-s ; number f of free variables plus number s of step types
        (- (length (arrow-form-to-arg-types uninst-recop-type)) 1))
        (s (- f-plus-s f))
        (arity (+ f-plus-s 1))
        (nbe-for-idps? (and (pair? repro-data)
                            (imp-form? (car repro-data)))))
    (nbe-make-object
    inst-recop-type
    (nbe-curry
        (lambda objs
            ... )
    inst-recop-type
    arity)))
```

Listing A.7: NbE value given in rec-at

```
(lambda objs
    (let* ((rec-obj (list-ref objs f))
        (rec-val (nbe-object-to-value rec-obj)))
        (cond
        ((or (nbe-fam-value? rec-val) (not REC-UNFOLDING-FLAG))
        ... )
        ((and (nbe-constr-value? rec-val) (not nbe-for-idps?))
        ... )
        ((and (nbe-constr-value? rec-val) nbe-for-idps?)
        ... )
        (else (myerror "rec-at" "value expected" rec-val)))))
```

Listing A.8: Case of term family

```
((or (nbe-fam-value? rec-val) (not REC-UNFOLDING-FLAG))
    (nbe-reflect
        (nbe-make-termfam
        (arrow-form-to-final-val-type inst-recop-type (length objs))
        (lambda (k)
            (apply mk-term-in-app-form
                (make-term-in-const-form ;rec-const
                        (apply alg-name-etc-to-rec-const
                alg-name uninst-recop-type tsubst
                inst-recop-type f rel-constr-names
                                rel-simalg-names-with-uninst-recop-types
                                repro-data))
                (map (lambda (x) (nbe-fam-apply (nbe-reify x) k))
                    objs))))))
```

are two bindings: the recursion object rec-obj for the argument at which the recurrence works and the recursion value rec-val for the NbE value of rec-obj. It makes a case distinction by the recursion value. There are four cases. The first case happens if the rec-val is the denotation of a term family or REC-UNFOLDING-FLAG is false. The flag REC-UNFOLDING-FLAG is true by default to enable unfolding of recursion operators, but a user can set it to be false to unblock the unfolding. The second and the third are the case if the rec-val is the denotation of a term with a constructor as the outermost operator. A value of such a term is called a constructor value. The flag nbe-for-idps?, which stands for "NbE for inductively defined predicate constants?", is true if it is for proof normalization of an elimination axiom. It is false if it is for term normalization or for proof normalization of induction axiom by a computational universal quantifier $\forall^{c}$. Depending on nbe-for-idps?, either the second or the third is chosen. If the none of the above cases are applicable, Minlog gives up the execution with putting an error message. From now we study the first two cases to see how term normalization works. The third one deals with parameters to recover the Curry-Howard isomorphism in addition to the second case, in order to perform proof normalization. The following list is of the first case. A value returned by this branch is the NbE object from a term family which is exactly the same as what we are normalizing, namely, this code makes the reproduction of the same thing. This is what we expect for example in the case of normalizing $\mathcal{R} x \vec{t}$ where $x$ is not formed by any constructor. In the code, the recursion constant is generated by the lines $7-12$. The arguments are prepared from objs by the lines $13-14$ by fixing an index k given to the term families.

When the rec-val is a constructor value, the recursion operator is converted with respect to the constructor. The following code gives a value for such a case in term normalization. What it computes as the result is the line 9 , which is the step term corresponding to the constructor of the value object applied to the arguments. From the name of the constructor constr-name, the step-obj is chosen. It suffices to compute the arguments called step-args which are fed to step-obj. From the list of the arguments to the recursion operator, rel-args is a sublist of the arguments which are relevant for recurring. The NbE objects for the relevant simultaneous recursion operators are computed for each of

Listing A.9: Case of constructor

```
((and (nbe-constr-value? rec-val) (not nbe-for-idps?))
    (let*
        ((constr-name (nbe-constr-value-to-name rec-val))
        (step-obj ... )
        (rel-args ... )
        (step-arg-lists ... )
        (step-args (apply append step-arg-lists)))
    (apply nbe-object-app step-obj step-args)))
```

relevant simultaneous algebras. In the code, recobjs is their name. The argument types of the constructor determine what the arguments to the step-obj are. The arguments are computed and bound to step-arg-lists in the code. The internally defined function between lines 3-25 takes two arguments, rel-arg and rel-constr-arg-type due to map, and has three cases. The first case is for parameter arguments of the constructor, namely, the argument type $\rho_{i \nu}$ of the step case is a type variable. The condition between lines 5-7 checks that there is no common algebra both in the list of algebras appear as an argument type of the constructor and the list of the relevant algebras of the recursion operator. The second case is for non-nested recursive arguments of the constructor. The condition between lines $9-14$ checks that the value type of the constructor type is an algebra which is among the relevant simultaneous algebras. This case is separated from nested cases because we duplicate the previous input, i.e., rel-arg, and the recursive call. The last case is for nested recursive arguments of the constructor. The main point is the use of map operators. Instead of the duplication in the non-nested case, the previous input and the recursive call are paired by the constructor of the product algebra and abstracted to be $\lambda_{x}\langle x, \mathcal{R} x \vec{t}\rangle$ which is bound to ih-fctobjs in the code. The NbE object of the relevant map operator is on the other hand computed by means of map-at and bound to mapobj. Finally, it returns the NbE object representing $\mathcal{M} N\left(\lambda_{x}\langle x, \mathcal{R} x \vec{t}\rangle\right)_{i<n}$.

Corecursion operators ${ }^{\text {co }} \mathcal{R}_{\vec{l}, i}^{\vec{\tau}}$ are specified by the following procedure.

```
(alg-or-arrow-types-to-corec-consts . alg-or-arrow-types)
```

The argument alg-or-arrow-types is a list of arrow types $\tau_{i} \rightarrow \iota_{i}$. When $\vec{\tau}$ is a list of the nulltype, we can give $\vec{\iota}$ instead. The difference from the case of recursion operators is the following.

1. There is corec-at to compute the NbE object.
2. The (internal) name of the constant is "corec".
3. There is alg-or-arrow-types-to-uninst-corecop-types-and-tsubst to compute the type.

Listing A.10: Three cases in the function definition

```
(step-arg-lists
    (map
        (lambda (rel-arg rel-constr-arg-type)
            (cond
                ((null? ; param-arg-type: take original arg
                    (intersection (type-to-alg-names rel-constr-arg-type)
                        rel-simalg-names))
                (list rel-arg))
                ((and (alg-form? (arrow-form-to-final-val-type
                        rel-constr-arg-type))
                    (member (alg-form-to-name
                        (arrow-form-to-final-val-type
                        rel-constr-arg-type))
                        rel-simalg-names))
                (list
                rel-arg
                (nbe-object-rec-compose ; first recobj
                    (cadr (assoc (alg-form-to-name
                        (arrow-form-to-final-val-type
                        rel-constr-arg-type))
                        rel-simalg-names-to-recobjs-alist))
            step-objs
            rel-arg)))
        (else ;nested recarg-type: use mapop
            ... )))
        rel-args rel-constr-arg-types))
```

Listing A.11: Nested case

Currently, corecursion operators are unchanged during NbE. Instead of NbE, terms involving corecursion operators can be unfolded by the following procedure,

> (undelay-delayed-corec term bound)
where term is a term and bound is the number of unfoldings. The procedure corec-at has only the reproduction case which we saw in rec-at. Types of corecursion operators are computed by the procedure alg-or-arrow-types-to-uninst-corecop-types-and-tsubst in a similar way as recursion operators.

```
(alg-name-etc-to-rec-const
    alg-name uninst-recop-type tsubst inst-recop-type
    frel-constr-names rel-simalg-names-with-uninst-recop-types . repro-data)
```


## A.1.3 Inductive and Coinductive Definitions

Inductive definitions are taken care of by the procedure add-ids in Minlog.

$$
\begin{gathered}
\text { (add-ids } \text { idpc-names-with-arities-and-opt-alg-names . } \\
\text { clause-strings-with-opt-names) }
\end{gathered}
$$

In order to define (simultaneous) inductive predicates $\vec{I}$, we have to specify the names of the predicates, the arities and the clause formulas. For idpc-names-with-arities-and-opt-alg-names we give a list of the name of the predicate, the arity and optionally the associated type by an algebra name. There is a naming convention algI for a predicate name I used to define a new algebra automatically by the name algI. One can also specify an existing algebra name instead. For clause formulas we give a list of an introduction axiom and optionally its name as clause-strings-with-opt-names. Most of the businesses of add-ids is to validate the given definition. For instance, if an existing algebra name is provided for the associated algebra, it checks if the computed associated algebra from clause formulas matches indeed. A coinductively defined predicate can be generated by dualizing an inductively defined predicate by add-co.
(add-co idpc-name . opt-prim-prod-flag)

This function forms the closure axiom of a coinductive predicate from the introduction axioms of a given inductive predicate idpc-name. If opt-prim-prod-flag is not given or true, the axiom is formed with the primitive existential quantifier and conjunction, which sometimes are preferable for efficiency reasons. If the flag is false, i.e., \#f, inductively defined existential quantifier and conjunction are used.

We give an example of proof normalization to sketch how the third case of rec-at, at line 9 and 10 in Listing A.7, works for inductively defined predicates. A recursion operator can encode an elimination axiom due to reproduction data. We use special algebras so-called $N b E$ algebras as well as reproduction data to let recursion operators and also constructors to carry free variables needed to restore the proof.

Example A.1.1 (Proof normalization involving the inductive predicate Even). Recall the predicate Even defined in Example 2.3.11 with a proper decoration and consider the following proof of Even $(n+4) \rightarrow^{\mathrm{c}} P 0 \rightarrow^{\mathrm{c}} \forall_{n}^{\mathrm{nc}}\left(\operatorname{Even} n \rightarrow^{\mathrm{c}} P n \rightarrow^{\mathrm{c}} P(n+2)\right) \rightarrow^{\mathrm{c}} P 4$. We refer to $P 0$ and $\forall_{n}^{\mathrm{nc}}\left(\right.$ Even $\left.n \rightarrow{ }^{\mathrm{c}} P n \rightarrow{ }^{\mathrm{c}} P(n+2)\right)$ by $A_{0}$ and $A_{1}$, respectively, and abuse the name of axioms for their conclusion in the proofs.

The NbE algebra of Even is $\iota:=\mu_{\xi}^{\mathrm{NbE}}\left(C_{0}^{\xi}, C_{1}^{\mathrm{N} \rightarrow \xi \rightarrow \xi}\right)$ where the $\mathbf{N}$ in the second constructor type comes from the $\forall_{n}^{\mathrm{nc}}$ in $\operatorname{Even}_{1}^{+}$and is treated as a parameter. From this special algebra Minlog generates a recursion operator $\mathcal{R}_{\iota}$ : $\mathbf{N} \rightarrow \iota \rightarrow \tau \rightarrow(\mathbf{N} \rightarrow \iota \rightarrow \tau \rightarrow \tau) \rightarrow \tau$. The conversion rules are $\mathcal{R}_{\iota}^{\tau} n C_{0} M N \mapsto M$ and $\mathcal{R}_{\iota}^{\tau} n\left(C_{1} m u\right) M N \mapsto N m u\left(\mathcal{R}_{\iota}^{\tau} m u M N\right)$ where the first argument $n$ is considered as a parameter. The number of the parameters is given as the argument $f$ of rec-at. The term representation of the proof is $\lambda_{u}\left(\mathcal{R}_{\iota}(n+\right.$ $\left.4)\left(C_{1}(n+2)\left(C_{1} n u\right)\right)\right)$. Each constructor $C_{i}$ carries the number $i$ and the inductively defined predicate constant Even as the reproduction data. The recursion operator $\mathcal{R}_{\iota}$ carries the formula $\operatorname{Even}(n+4) \rightarrow P(n+4)$ instead. The normal form of the term is $\lambda_{u, w_{0}, w_{1}}\left(w_{1}(n+2)\left(C_{1} n u\right)\left(w_{1} n u\left(\mathcal{R}_{\iota} n u w_{0} w_{1}\right)\right)\right)$ which represents the following normalized proof.

If there are free variables in a competitor predicate of an elimination axiom or a predicate parameter of an inductive predicate, the types of axioms are given differently to carry all free variables as parameters.

## A. 2 Commentary to cauchysds.scm

All of the case studies in Chapter 3 are formalized and running in the Minlog system [Min]. To complement the proofs illustrated rather informally, we take a look at Minlog proof scripts on Cauchy reals and SDSs in Section 3.3 with focus on Proposition 3.3.7. In the Minlog distribution, this is in examples/analysis/cauchysds.scm.

Using standard procedures to define algebras, axioms, predicates and etc., the corresponding Scheme global variables are modified to store internal representations of definitions.

Listing A.12: Loading libraries

```
;(load "~/minlog/init.scm")
;; Contents
;; 1. A Cauchy real to an SDS. (PropA)
;; 2. An SDS to a Cauchy real. (PropB)
;; 3. Experiments.
(set! COMMENT-FLAG #f)
(libload "nat.scm")
(libload "numbers.scm")
(exload "analysis/real.scm")
(set! COMMENT-FLAG #t)
```

Proofs in Minlog are interactively built by proof tactics commands, which in fact manipulate the goal and context stored in a global variable. Computational content from proofs is mechanically extracted. The program in $\mathrm{T}^{+}$can be exported to general-purpose programming languages as Scheme and Haskell. The imlementation of the feature for Haskell is due to Nordvall MFS13. In this section the file path refers to a relative path from the Minlog directory minlog/ of the distribution.

## A.2.1 Definitions

The beginning of the code is to load the necessary libraries. The first line can be uncommented to start up the Minlog system. In line 9, the library for natural number is loaded. The entity of a library is a Scheme file placed at lib/. In line 10, the library for numbers including rational, (type-1) real and complex numbers is loaded. We use positive numbers, integers and rational numbers out of it. In line 11, an existing case study on real numbers is loaded. Although we do not use existing real numbers from the library, we make use of a proof tactic, called ord-field-simp-bwd, defined in this file for rational number reasoning. In lines 8 and 12, the flag to allow/disallow Minlog to output a message is switched, so that Minlog is silent except error messages during loading libraries.

It starts from declaring variable names. In lines 15 and 16, an existing variable name M is removed. It is used in lib/numbers.scm for a variable name ranging over $\mathbf{Z} \rightarrow \mathbf{N}$ which we are going to use for another purpose. In line 18, a type variable $r$ is declared for the type $\rho$ of abstract real numbers. In line 19 and 20, it declares that the variable $x$ ranges over $r$ after removing the existing declaration. We define the algebra $\mathbf{S D}$ of the signed digits and the programmable constant SDToInt of type $\mathbf{S D} \rightarrow \mathbf{Z}$ with the computation rules. By means of add-alg, $\mathbf{S D}$ is defined to be $\mu_{\xi}\left(\mathrm{L}^{\xi}, \mathrm{M}^{\xi}, \mathrm{R}^{\xi}\right)$. The totality predicate of an algebra is derived by add-totality. A programmable constant is declared by using add-program-constant. It is required to give a name and a type, where a type can also be constructed by the arrow type " $=>$ ". Then, the computation rules are defined by add-computation-rule. It is obvious that the programmable constant SDToInt has a computational content to coerce a signed digit to an integer. Here, the types of "0" and " 1 " in the second arguments are inferred by Minlog. In line 26, 1 is a positive number which is given to the constructor

Listing A.13: Variable names declaration

```
;; 1. A Cauchy real to an SDS
(remove-var-name "M") ;will be used as constructor for sd
(remove-token "M")
(add-tvar-name "r")
(remove-var-name "x")
(add-var-name "x" (py "r"))
```

Listing A.14: Algebra SD

```
(add-alg "sd" (("L" "sd") ,("M" "sd") ("R" "sd"))
(add-totality "sd")
(add-program-constant "SDToInt" (py "sd=>int"))
(add-computation-rule (pt "SDToInt L") (pt "IntN 1"))
(add-computation-rule (pt "SDToInt M") (pt "O"))
(add-computation-rule (pt "SDToInt R") (pt "1"))
```

IntN of type pos=>int. On the other hand in lines 27 and 28, Minlog recognizes that 0 and 1 are of type int, but neither of nat nor pos. Due to the nature of TCF, everything is partial in principle. Therefore, one has to prove the totality if it is necessary. In line 30 , there are three commands, set-goal, term-to-totality-formula and pt. The last one stands for "parse term." It first parses the string to generate an internal term representation. The totality statement of SDToInt, namely, $\forall_{d}^{\mathrm{nc}}\left(T_{\mathbf{S D}} d \rightarrow T_{\mathbf{Z}}\right.$ (SDToInt $\left.d\right)$ ), is given by term-to-totality-formula. Finally, this formula is set to be the goal to prove. In line 31 , a universally quantified variable and a premise are assumed by the command assume with the specified names. In line $32,\left(T_{\mathbf{S D}}\right)^{-}$is used to the current goal. Since there are three step cases, the Minlog generates three new goals, which are proved in lines 33-35, $36-37$ and 38-40, respectively. After using ng, standing for "normalizing goal," the first goal becomes $T_{\mathbf{Z}}(\mathrm{N} 1)$. The argument \#t is used in order to normalize only the goal, but no context. Applying $\left(T_{\mathbf{Z}}\right)_{0}^{+}$, then prove $T_{\mathbf{P}} 1$ by using $\left(T_{\mathbf{P}}\right)_{0}^{+}$. The second goal is $T_{\mathbf{Z}} 0$ which is proven by $\left(T_{\mathbf{Z}}\right)_{1}^{+}$. The last one is by $\left(T_{\mathbf{Z}}\right)_{2}^{+}$, then prove $T_{\mathbf{P}} 1$ as in the fist case. When all sub goals have been closed, the Minlog tells us that the proof is finished. The internally built proof can be saved by the save command with giving a name. One can access the proof object later by the name. In line 44, we define the algebra I which works in a similar way as $\mathbf{L}_{\mathbf{S D}}$. Although this algebra can be automatically extracted from the definition of an inductively defined predicate in line 51 , we manually define it here in order to give user specified names of the algebra and its constructors. In lines 46-49, the constants in Definition 3.3.2, 3.3.3 and 3.3 .4 are given. If a programmable constant involves type variables, type arguments have to be given as in the line 52. In lines 51-55, the coinductive predicate ${ }^{\text {co } I} I$ in Definition 3.3 .6 is given. It first defines the inductive predicate $I$ of arity $(\rho)$ with specified associated algebra $\mathbf{I}$. In lines $52-53$, the clause formulas are given to define $I$ to be $\mu_{X}\left(X \mathrm{Z}, \forall_{x}^{\mathrm{nc}} \forall_{d}^{\mathrm{c}}\left(X x \rightarrow X\left(\frac{x+d}{2}\right)\right)\right.$ ) with the names InitI and GenI for $I_{0}^{+}$and $I_{1}^{+}$, respectively. A string can represent a formula in the following syntax: allnc for $\forall^{\mathrm{nc}}$,

Listing A.15: Totality of SDToInt

```
(set-goal (term-to-totality-formula (pt "SDToInt")))
(assume "sd~" "Td")
(elim "Td")
(ng #t)
(use "TotalIntIntNeg")
(use "TotalPosOne")
(ng #t)
(use "TotalIntIntZero")
(ng #t)
(use "TotalIntIntPos")
(use "TotalPosOne")
; Proof finished.
(save "SDToIntTotal")
```

Listing A.16: Inductively defined predicate $I$

```
(add-alg "iv" ,("II" "iv") '("C" "sd=>iv=>iv"))
(add-program-constant "Elem" (py "r=>rat=>nat=>boole"))
(add-program-constant "Z" (py "r")) ; zero
(add-program-constant "Av" (py "r=>sd=>r")) ; average
(add-program-constant "Va" (py "r=>sd=>r")) ;inverse of average
(add-ids (list (list "I" (make-arity (py "r")) "iv"))
    '("I(Z r)" "InitI")
    '("allnc x^ all sd(I x^ -> I((Av r)x^ sd))" "GenI"))
(add-co "I")
```

all for $\forall^{c},->$ for $\rightarrow^{\mathrm{c}}$ and $-->$ for $\rightarrow^{\mathrm{nc}}$. A variable followed by a hat " $n$ " means a partial variable, whereas a variable without it means a total variable. Apart from declared variable names, the algebra name can be used as a variable name, e.g. sd in the line 53. In line 55, the coinductively defined predicate ${ }^{\text {co }} I$ is derived from $I$. The last part of the definitions is the axioms of the abstract theory of real numbers. By means of add-global-assumption, we postulates a formula to be an axiom with a specified name. In addition to the syntax which we have seen, there are <= for "less than or equal" on rational numbers, \# standing for the constructor of $\mathbf{Q}$, and PosToNat is for the type coercion. Also some arithmetic on rational numbers,,,$+- *$ and $/$, are there. For example, IntN $1 \# 4$ stands for $\frac{-1}{4}$.

## A.2.2 Proofs

We prove Lemma 3.2.7 and 3.2.8. In line 60 , ori stands for a logical connective "or," which is parsed to be one of $V^{\mathrm{d}}, \vee^{\mathrm{r}}, \vee^{\mathrm{l}}, \vee^{\mathrm{u}}$ depending on the computational content from the left and the right hand formulas. In this case, it becomes $\vee^{u}$ since the inequality is non-computational from its definition, thus the statement is $\forall_{a}^{\mathrm{c}}\left(a \leq 0 \vee^{\mathrm{u}} 0 \leq a\right)$.

The first cases does case distinction on the construction of the rational number rat to yield $i$ and $p$ such that rat $=i \# p$. In fact this proof tactic is a restricted form of the elimination axiom. The second cases does the same for the integer i. There are three

Listing A.17: Axioms

```
; ;Axioms for PropA
(add-global-assumption
    "AxRealLeft"
    "all x^,a(a<=(IntN 1#4) -> (Elem r) x^ a(PosToNat 2) ->
        (Elem r) x^(IntN 1#2)(PosToNat 1))")
(add-global-assumption
    "AxRealMiddle"
    "all x^,a((IntN 1#4)<=a -> a<=(1#4) -> (Elem r)x^ a(PosToNat 2) ->
        (Elem r)x^(0#2)(PosToNat 1))")
(add-global-assumption
    "AxRealRight"
    "all x^,a((1#4)<=a -> (Elem r) x^ a(PosToNat 2) ->
            (Elem r) x^(1#2)(PosToNat 1))")
(add-global-assumption
    "AxAvVaIdent"
    "all x^,sd(((Elem r)x^(SDToInt sd#2)(PosToNat 1) ->
        x^ eqd(Av r)((Va r) x^ sd)sd)")
(add-global-assumption
    "AxVaIntro"
    "all x^,sd,a,n((Elem r) x^(SDToInt sd#2)(PosToNat 1) ->
        (Elem r)x^ a(Succ n) -> (Elem r) ((Va r)x^ sd) (2*a-SDToInt sd)n)")
```

cases since $i$ is either positive, zero or negative. In any case, it is easy to determine whether
 the universal quantifier. New assumptions come with specified names. In lines 64,67 and 70 , the proof tactic intro applies the introduction axiom to the goal. Minlog finds an appropriate predicate $\mathrm{V}^{\mathrm{u}}$ from the goal formula, and chooses $\left(\mathrm{V}^{\mathrm{u}}\right)_{0}^{+}$or $\left(\mathrm{V}^{\mathrm{u}}\right)_{1}^{+}$by the given number. The use tactic applies the specified assumption, axiom, or theorem to the goal. The name "Truth-Axiom" refers to the truth $\mathbf{T}$, which is available as an axiom. One can save the constructed proof by save command, and also can use it later as a theorem. The following is the proof of Lemma 3.2.8. In the lines 78, 81 and so on, assert does the implication elimination. Assume that the formula $A$ is given as an argument and the goal is $B$, then two new goals, $B$ and $B->A$, are then required to be proven. In the line 79, the proof tactic ord-field-simp-bwd solves the equality of rational numbers, $a=a-b+b$. This is one thing which we need from the external file examples/analysis/real.scm. The proven lemma can be referred to by the name as it is done in the line 82 . The elim tactic uses the elimination axiom of an inductively defined predicate. In the line 84, elim is called with the assumption formula $\mathrm{a}-\mathrm{b}<=0$ oru $0<=\mathrm{a}-\mathrm{b}$, then internally it applies $\left(\mathrm{V}^{\mathrm{u}}\right)^{-}$to the goal and yields step formulas which become new sub goals. The drop command is to make the specified assumption invisible in the context. It just changes the display, but there is no mathematical effect. The name RatPlusLe2 is the following global assumption which is postulated in examples/analysis/real.scm.

$$
\forall_{a_{1}, a_{2}, b_{1}, b_{2}}\left(a_{1} \leq a_{2} \rightarrow b_{1} \leq b_{2} \rightarrow a_{1}+a_{2} \leq b_{1}+b_{2}\right)
$$

Listing A.18: Lemma NegOrPos

```
; "NegOrPos"
(set-goal "all rat(rat<=0 ori 0<=rat)")
(cases)
(cases)
(assume "pos0" "pos1")
(intro 1)
(use "Truth-Axiom")
(assume "pos0")
(intro 0)
(use "Truth-Axiom")
(assume "pos0" "pos1")
(intro 0)
(use "Truth-Axiom")
; Proof finished.
(save "NegOrPos")
```

The simp tactic rewrites the goal by the given equality. Now the following proof is clear. In the proof of Lemma 3.2.9 named "StandardSplit" in the proof script, we use inst-with-to which is a tactic for the forward reasoning. The first argument is an assumption and the next arguments are used to eliminate $\forall$ and $\rightarrow$, then the obtained new assumption is named by the last argument. For example the line 111 makes from SplitAtRational, $a$, and $-\frac{1}{4}$ a new assumption formula $a \leq-\frac{1}{4} \vee^{\mathrm{u}}-\frac{1}{4} \leq a$ with the name "at $-1 \# 4$ ". By means of similar tactics we can prove the lemma "SplitProp" in line 173. The following code snippet is the proof script of Proposition 3.3.7. The goal formula is set to be $\forall_{x}^{\mathrm{nc}}\left(\forall_{n}^{\mathrm{c}} \exists_{a}^{\mathrm{l}} x \in \square_{a, n} \rightarrow{ }^{\mathrm{co}} I x\right)$ in line 209. We assume $x$ and $\forall_{n}^{\mathrm{c}} \exists_{a}^{\mathrm{l}} x \in \square_{a, n}$ as $Q x$ in line 210, then use ${ }^{\text {co }} I^{+}$for the competitor $Q x$ to prove ${ }^{\text {co }} I x$. It suffices to prove the costep formula $\forall_{x}^{\mathrm{nc}}\left(Q x \rightarrow x\right.$ eqd Z $\vee^{\mathrm{r}} \exists_{x_{0}}^{\mathrm{r}} \exists_{d}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I x_{0} \vee^{\mathrm{d}} Q x_{0}\right) \wedge^{\mathrm{l}} x\right.$ eqd $\left.\left.\frac{x_{0}+d}{2}\right)\right)$. Assume $x_{1}$ and $Q x_{1}$ in line 290, then we use $\left(\vee^{\mathrm{r}}\right)_{1}^{+}$to prove the right disjunct in line 291. Applying the split property lemma to $x_{1}$ and $Q x_{1}$, we have $\exists_{d}^{1}\left(x_{1} \in \square_{d}\right)$ in the context by the name "SP". This is done by the command inst-with-to. We assert the same formula by assert. Invoking (assert $A$ ), the current goal $B$ turn into the two subgoals $A$ and $A \rightarrow^{\text {c }} B$. Although It looks logically non-sense, the application of the identity lemma in line 223 fine-tunes the computational content. See Example 2.5.28. The command elim in line 224 is an application of $\left(\exists^{1}\right)^{-}$for the formula "SP". The goal is then $\forall_{d}^{\mathrm{c}}\left(x_{1} \in \mathbb{\square}_{d} \rightarrow{ }^{\mathrm{nc}} \exists_{x}^{\mathrm{r}}\left(\exists_{d_{0}}^{\mathrm{d}}\left(\left({ }^{\mathrm{co}} I x \vee^{\mathrm{d}} \forall_{n}^{\mathrm{c}} \exists_{a}^{\mathrm{l}} x \in \mathbb{\square}_{a, n}\right) \wedge^{1} x_{1}\right.\right.\right.$ eqd $\left.\left.\frac{x+d_{0}}{2}\right)\right)$. We assume $d$ and $x_{1} \in \square_{d}$ as HElem in line 225, and use $\left(\exists^{\mathrm{r}}\right)^{+}$with $2 x_{1}-d$ and also $\left(\exists^{\mathrm{d}}\right)^{\dagger}$ with $d$. The command split turns the goal of the form $A \wedge B$ into the two subgoals $A$ and $B$. The lines $230-238$ is to prove ${ }^{\mathrm{co}} I x \vee^{\mathrm{d}} \forall_{n}^{\mathrm{c}} \exists_{a}^{\mathrm{l}} x \in \mathbb{\square}_{a, n}$. We go to the right disjunct in line 230 and assume $n$ in the next line. The formula $Q x_{1}$ in the context is instantiated to $\exists_{a}^{1} x_{1} \in \square_{a, n+1}$ as Hex in line 232, then we use $\left(\exists^{\mathrm{l}}\right)^{-}$for this formula in line 233. Assume $a$ as a and $x_{1} \in \mathbb{\square}_{a, n+1}$ as HElem2. Using $\left(\exists^{1}\right)^{+}$with $2 a-d$, we get the new goal $2 x_{1}-d \in \mathbb{1}_{2 a-d, n}$. By the axiom AxVaIntro it suffices to show $x_{1} \in \square_{d}$ and $x_{1} \in \square_{a, n+1}$ which are HElem and HElem2, respectively. The right conjunct is $x_{1}$ eqd $\frac{2 x_{1}-d+d}{2}$ which is proven by AxAvVaIntro and HElem. The proof is done and saved as PropA.

Listing A.19: Lemma SplitAtRational

```
; "SplitAtRational"
(set-goal "all a,b(a<=b ori b<=a)")
(assume "a" "b")
(assert "a=a-b+b")
    (ord-field-simp-bwd)
(assume "Eq")
(assert (pf "a-b<=0 ori 0<=a-b"))
    (use "NegOrPos")
(assume "NegOrPos inst")
(elim "NegOrPos inst")
(drop "NegOrPos inst")
(assume "Hneg")
(intro 0)
(assert (pf "(a-b)+b<=0+b"))
    (use "RatPlusLe2")
    (use "Hneg")
    (use "Truth-Axiom")
(assume "HO")
(simp "Eq")
(use "HO")
(assume "Hpos")
(intro 1)
(assert (pf "0+b<=(a-b)+b"))
    (use "RatPlusLe2")
    (use "Hpos")
    (use "Truth-Axiom")
(assume "HO")
(simp "Eq")
(use "HO")
; Proof finished.
(save "SplitAtRational")
```

Listing A.20: Lemma Standard Split

```
; "Standard Split"
(set-goal "all a(a <= (IntN 1#4) ori
    ((IntN 1#4) <= a & a <= (IntP 1#4)) ori (IntP 1#4) <= a)")
(assume "a")
(inst-with-to "SplitAtRational" (pt "a") (pt "IntN 1#4") "at -1#4")
(elim "at -1#4")
(assume "a<=-1#4")
(intro 0)
(use "a<=-1#4")
(assume "-1#4<=a")
(inst-with-to "SplitAtRational" (pt "a") (pt "IntP 1#4") "at 1#4")
(elim "at 1#4")
(assume "a<=1#4")
(intro 1)
(intro 0)
(split)
(use "-1#4<=a")
(use "a<=1#4")
(assume "1#4<=a")
(intro 1)
(intro 1)
(use "1#4<=a")
; proof finished
(save "StandardSplit")
```

Listing A.21: Split Property Lemma
; Split Property Lemma for Abstract Reals
(set-goal "allnc $x^{\wedge}\left(a l l n\right.$ exi a((Elem r) $x^{\wedge}$ a $n$ ) -> exi sd (Elem r) $\left.\left.x^{\wedge}(S D T o I n t ~ s d \# 2) 1\right) "\right)$

Listing A.22: PropA

```
; "PropA"
(set-goal (pf "allnc x^(all n exi a((Elem r)x^ a n) -> CoI x^)"))
(assume "x^" "Q x")
(coind "Q x")
;; ?_3:allnc x^(
    all n exl a (Elem r)x^ a n ->
    x^ eqd(Z r) orr
        exr x^0
        ex sd(
            (CoI x^0 ord all n exl a (Elem r)x^0 a n) andl ( x^ eqd(Av r) x^0 sd))
(assume "x^1" "Q x1")
(intro 1)
(inst-with-to "SplitProp" (pt "x^1") "Q x1" "SP")
(assert (pf "exl sd (Elem r)x^1(SDToInt sd#2)(PosToNat 1)"))
(use "SP")
(use "Id")
(elim)
(assume "sd" "HElem")
(intro 0 (pt "(Va r)x^1 sd"))
(ex-intro (pt "sd"))
(split)
;CoI
(intro 1)
(assume "n")
(inst-with-to "Q x1" (pt "Succ n") "Hex")
(elim "Hex")
(assume "a" "HElem2")
(intro 0 (pt "2*a-(SDToInt sd)"))
(use "AxVaIntro")
(use "HElem")
(use "HElem2")
; x^1 eqd ...
(use "AxAvVaIdent")
(use "HElem")
; proven
(save "PropA")
```

Listing A.23: Program extraction

```
; ; 3. Experiments
; 3.1. Cauchy Sequence -> SDS
(define eterm-a
    (proof-to-extracted-term (theorem-name-to-proof "PropA")))
(define neterm-a (nt eterm-a))
```

Listing A.24: Animating

```
(animate "SplitProp")
(animate "NegOrPos")
(animate "SplitAtRational")
(animate "StandardSplit")
```


## A.2.3 Program Extraction

We extract a program from the proof of PropA and experiment it. The command theorem-name-to-proof gives the proof object of PropA. Program extraction is done by proof-to-extracted-term. The extracted program is named as eterm-a. In the next line, let neterm-a be the normal form of eterm-a. The computational contents from the lemmas used in the proof of PropA should be activated. The save command also define the constant corresponding to the computational content of the proof to save. The animate command activates the computational content of the constant through program extraction. The following line 294 normalizes the term neterm-a using also the animated computational contents and prints out the result with the case expression by ppc which stands for pretty printing with cases. Now we activate the computational content from the identity lemma as well. The following program constant sqrt is a hand-implemented function computing the square root of the given rational number. The result is of type $\mathbf{N} \rightarrow \mathbf{Q}$. For instance, the following code computes the SDS representation of $\sqrt{\frac{1}{2}}$. Programs in $\mathrm{T}^{+}$involving corecursion operators can be exported to Haskell. The file examples/analysis/simpreal.scm is required for numeric terms we used so far. Then, the next line outputs the Haskell translation of the extracted programs in cauchysds.scm and the hand implemented square root program to the file cauchysds.hs in the working directory.

Listing A.25: Extracted program

```
;; extracting a program from PropA
(ppc (nt neterm-a))
;; [as0]
    (CoRec (nat=>rat)=>iv)aso
    ([as1]
        Inr[let sdz
            [let az
        (as1(Succ(Succ Zero)))
        [case (a2-(IntN 1#4))
        (k3#p4 ->
        [case k3
            (p5 ->
                    [case (a2-(1#4))
                        (k6#p7 -> [case k6 (p8 -> R) (0 -> M) (IntN p8 -> M)])])
                    (0 -> L)
                    (IntN p5 -> L)])]J
            (sd2@(InR nat=>rat iv)([n3]2*as1(Succ n3)-SDToInt sd2))])
```

Listing A.26: Animating the identity lemma

```
(animate "Id")
```

Listing A.27: Square root

```
;; a rational number to the square root of it
(add-program-constant "sqrt" (py "rat=>nat=>rat"))
(add-program-constant "sqrtaux" (py "rat=>nat=>rat"))
(add-computation-rule "sqrtaux a Zero" "Succ Zero")
(add-computation-rule "sqrtaux a (Succ n)"
    "((sqrtaux a n) + (a / (sqrtaux a n)))/2")
(add-computation-rule "sqrt a n" "sqrtaux a (Succ n)")
```

Listing A.28: Unfolding corecursion operators

```
(pp (nt (undelay-delayed-corec
    (make-term-in-app-form neterm-a (pt "sqrt (1#2)"))
    5)))
;; C R(C R(C M(C L(C R((CoRec (nat=>rat)=>iv) ... )))))
```

Listing A.29: Haskell translation

```
; 3.3. Haskell translation
(load "~/minlog/examples/analysis/simpreal.scm")
(terms-to-haskell-program "cauchysds.hs"
    (list (list neterm-a "cauchysds")
    (list neterm-b "sdscauchy")
    (list (pt "sqrt") "rattosqrt")))
```


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