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DISCONNECTEDNESSES AND CLOSURE OPERATORS (*)

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Abstract

Closure operators which characterize disconnectednesses and relative disconnectednesses are introduced. Such operators are used to find conditions under which a relative disconnectedness is a disconnectedness.

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§1. Preliminaries (**)

In this paper we denote by \mathbf{T} the class of all topological spaces, by \mathbf{T}_i ($i = 0, 1, 2$) the classes of T_i -spaces, by **Sing** the class of spaces which have at most one point. Moreover we denote by \mathbf{P} an arbitrary nonempty subclass of \mathbf{T} and by $\underline{\mathbf{P}}$ the category of spaces of \mathbf{P} and continuous functions. Of course $\underline{\mathbf{P}}$ is a full subcategory of $\underline{\mathbf{T}}$.

Let X be a space and $x \in X$.

1.1 DEFINITION. We call \mathbf{P} -component of x in X the largest subspace Y of X containing x such that for each $P \in \mathbf{P}$ and for each $f: Y \rightarrow P$, f is constant (see [11], p.297).

1.2 DEFINITION. We call \mathbf{P} -quasicomponent of x in X the largest subspace Y of X containing x such that for each $P \in \mathbf{P}$ and for each

(*) This paper is in final form and no version of it will be submitted for publication elsewhere.

(**) Notations and definitions not explicitly given are from [6]. Moreover, the functions we consider are always continuous functions between topological spaces.

$f: X \rightarrow P$, $f|Y$ is constant (see [11], p.297).

1.3. DEFINITION. A space X is called totally P -disconnected if its P -components are singletons, totally P -separated if its P -quasicomponents are singletons (see [11], p.297).

We denote by UP the class of all totally P -disconnected spaces and by QP the class of all totally P -separated spaces.

It follows immediately from the definitions that

$$1.4 \quad P \subset QP \subset UP .$$

1.5 DEFINITION. A class P of spaces is called disconnectedness if $P = UP$, and relative disconnectedness if $P = QP$.

§2. The closure operators E_X and K_X .

Let $f: A \rightarrow B$ be a continuous function.

2.1 DEFINITION. f is said to be P -cancellable if for every $P \in \mathcal{P}$ and for every $g_1, g_2: B \rightarrow P$ such that $g_1 f = g_2 f$, we have $g_1 = g_2$.

Suppose now X is a space containing B as subspace.

2.2 DEFINITION. f is said to be P -cancellable rel X if for every $P \in \mathcal{P}$ and for every $g_1, g_2: X \rightarrow P$ such that $(g_1|B)f = (g_2|B)f$, we have $g_1|B = g_2|B$.

2.3. PROPOSITION. If P' is a class of spaces such that $P \subset P' \subset QP$, we have that $f: A \rightarrow B$ is P' -cancellable (or P' -cancellable rel X) iff f is P -cancellable (or P -cancellable rel X).

PROOF. Since $P \subset P'$ if f is P' -cancellable it is obvious that f is P -cancellable too.

Conversely, suppose $f: A \rightarrow B$ is P -cancellable. Let $P' \in \mathcal{P}'$ and $g_1, g_2: B \rightarrow P'$ be functions such that $g_1 f = g_2 f$. Then for every $P \in \mathcal{P}$ and for every $h: P' \rightarrow P$ we have $h g_1 f = h g_2 f$ and therefore $h g_1 = h g_2$. Since $P' \in \mathcal{Q}P$, the class of all continuous functions from P' whose range is in P distinguishes the points (see [10], 3.3). It follows that $g_1 = g_2$.

Similar arguments can be used to prove the proposition when

the function is cancellable rel X .

From now on we denote by X an arbitrary topological space and by A an arbitrary subspace of X .

2.4 DEFINITION. By $E_X^P(A)$ we denote the largest subspace Y of X such that $A \subset Y$ and the inclusion of A into Y is P -cancellable.

2.5 DEFINITION. By $K_X^P(A)$ we denote the largest subspace Y of X such that $A \subset Y$ and the inclusion of A into Y is P -cancellable rel X .

It can be easily proved that the operators E_X^P and K_X^P are Moore closures and that if $f: X \rightarrow Y$ is a continuous function we have:

$$2.6 \ E_X^P(A) \subset K_X^P(A) ;$$

$$2.7 \ K_X^P(A) = X \iff E_X^P(A) = X ;$$

$$2.8 \ f(E_X^P(A)) \subset E_Y^P(f(A)) ; \ f(K_X^P(A)) \subset K_Y^P(f(A)) ;$$

2.9 the followings are equivalent:

- (i) f is P -cancellable;
- (ii) $E_Y^P(f(X)) = Y$;
- (iii) $K_Y^P(f(X)) = Y$.

The operator K_X^P was introduced in [12] and studied in [4]. The operator E_X^P coincides with the epiclosure defined in [2] when P is productive, hereditary and $X \in P$.

When there is no confusion about the class P , we indicate the introduced operators only by E_X and by K_X .

2.10 PROPOSITION. If P' is a class of spaces such that $P \subset P' \subset QP$, we have

$$E_X^P = E_X^{P'} ; \ K_X^P = K_X^{P'} .$$

PROOF. It follows immediately from 2.3.

2.11 PROPOSITION. Let $x \in X$. We have:

- (a) $E_X^P(\{x\})$ is the P - component of x in X ;
- (b) $K_X^P(\{x\})$ is the P -quasicomponent of x in X .

PROOF. (a) It follows immediately from the fact that if V is a subspace of X such that $x \in X$, the inclusion $j: \{x\} \rightarrow V$ is P -cancel-

lable iff for each $P \in \mathcal{P}$ the functions from V to P are all constant.

(b) It can be proved in a similar way as (a).

2.12 COROLLARY. (a) \mathcal{UP} is the class of all spaces X whose points are E_X^P -closed.

(b) \mathcal{QP} is the class of all spaces X whose points are K_X^P -closed.

PROOF. It follows from 2.11.

2.13 PROPOSITION. The followings are equivalent:

(a) $\mathcal{P} \subset \mathcal{T}_2$;

(b) $\bar{A} \subset E_X^P(A)$;

(c) $\bar{A} \subset K_X^P(A)$.

PROOF. (a) \Rightarrow (b) It follows from the fact that the inclusion $j: A \rightarrow \bar{A}$ is \mathcal{T}_2 -cancellable and therefore \mathcal{P} -cancellable.

(b) \Rightarrow (c) It follows from 2.6.

(c) \Rightarrow (a) See [12] (p.555).

2.14 LEMMA. A space X belongs to \mathcal{QP} iff the diagonal Δ_X is $K_{X \times X}^P$ -closed.

PROOF. If $X \in \mathcal{QP}$, the projections $p_1, p_2: X \times X \rightarrow X$ coincide exactly on Δ_X , and therefore (see 2.3) $K_{X \times X}^P(\Delta_X) = \Delta_X$.

Conversely, suppose $K_{X \times X}^P(\Delta_X) = \Delta_X$. Then **there are** two functions $f, g: X \times X \rightarrow P$, with $P \in \mathcal{QP}$, such that $f|_{\Delta_X} = g|_{\Delta_X}$ and $f(x, y) \neq g(x, y)$ whenever $x \neq y$. If z is an arbitrary point of X , we consider the embedding $j: X \rightarrow X \times X$ defined by $j(x) = (x, z)$. We have: $fj(z) = gj(z)$ and $fj(t) \neq gj(t)$ for every $t \in X - \{z\}$. Hence $K_X^P(\{z\}) = \{z\}$, and from 2.12 $X \in \mathcal{QP}$.

2.15 PROPOSITION. The followings are equivalent:

(a) $\mathcal{QP} \subset \mathcal{QP}'$;

(b) $K_X^P(A) \supset K_X^{P'}(A)$.

PROOF. (a) \Rightarrow (b) It follows easily from the definitions and 2.3.

(b) \Rightarrow (a) If (b) holds for each space X we have

$$K_{X \times X}^{P'}(\Delta_X) \subset K_{X \times X}^P(\Delta_X).$$

If $X \in \mathbf{QP}$, by 2.14 we have $K_{X \times X}^{\mathbf{P}}(\Delta_X) = \Delta_X$ and so Δ_X is $K_{X \times X}^{\mathbf{P}'}$ -closed. By 2.14 again we have $X \in \mathbf{QP}'$.

2.16 COROLLARY. The followings are equivalent:

- (a) $\mathbf{P} \subset \mathbf{T}_0$;
- (b) $b_X(A) \subset E_X^{\mathbf{P}}(A)$;
- (c) $b_X(A) \subset K_X^{\mathbf{P}}(A)$.

PROOF. (a) \Rightarrow (b) It follows from the fact that the inclusion $j: A \rightarrow b_X(A)$ is \mathbf{T}_0 -cancellable (see [13]) and therefore \mathbf{P} -cancellable.

(b) \Rightarrow (c) It follows from 2.6.

(c) \Rightarrow (a) It follows from 2.15 and [12] (p.557).

Examples.

Let S be a singleton, C the two-points indiscrete space, D the Sierpinski dyad, I the real interval $[0,1]$.

If $\mathbf{P} = \{S\}$ then $\mathbf{QP} = \mathbf{UP} = \mathbf{Sing}$ and $E_X^{\mathbf{P}}(A) = K_X^{\mathbf{P}}(A) = X$.

If $\mathbf{P} = \{C\}$ then $\mathbf{QP} = \mathbf{UP} = \mathbf{T}$ and $E_X^{\mathbf{P}}(A) = K_X^{\mathbf{P}}(A) = A$.

If $\mathbf{P} = \{D\}$ then $\mathbf{QP} = \mathbf{UP} = \mathbf{T}_0$ and $E_X^{\mathbf{P}}(A) = K_X^{\mathbf{P}}(A) = b_X(A)$, where $b_X(A)$ is the b -closure of A in X (see [13] , 2.5; [12], p.557).

If $\mathbf{P} = \{D_2\}$, where D_2 is the two-points discrete space, then \mathbf{QP} is the class of all totally separated spaces and \mathbf{UP} is the class of all totally disconnected spaces. Moreover

$$K_X^{\mathbf{P}}(A) = \bigcap \{B \mid A \subset B \subset X, B \text{ is clopen in } X\}.$$

If $\mathbf{P} = \{I\}$ then \mathbf{QP} is the class of all functionally Hausdorff spaces. Moreover

$$K_X^{\mathbf{P}}(A) = \bigcap \{B \mid A \subset B \subset X, B \text{ is a zeroset in } X\} .$$

We observe that when $\mathbf{P} = \{I\}$ and in many other cases it is not easy to know how the operator $E_X^{\mathbf{P}}$ works and how the class \mathbf{UP} is.

§3. Disconnectedness and relative disconnectedness.

UP and QP are subcategories of T closed under products and injective functions. Therefore they are extremal epireflective in T (see [8]).

We indicate by $R: T \rightarrow UP$, $S: T \rightarrow QP$ the corresponding epireflectors and by $r_X: X \rightarrow RX$ and $s_X: X \rightarrow SX$ the epireflection maps associated to R and S respectively. We remind that r_X is the quotient map which identifies the points of each P-component (see [1], Th.3.7) and s_X is the quotient map which identifies the points of each P-quasicomponent (see [10], p.304).

3.1. PROPOSITION. A function $f: X \rightarrow Y$ is P-cancellable iff $Sf: SX \rightarrow SY$ is an epimorphism in QP.

PROOF. Let $f: X \rightarrow Y$ be P-cancellable, $P \in QP$ and $f_1, f_2: SY \rightarrow P$ such that $f_1(Sf) = f_2(Sf)$. Then $f_1(Sf)s_X = f_2(Sf)s_X$. Since $(Sf)s_X = s_Y f$ we have $f_1 s_Y f = f_2 s_Y f$. By 2.3 f is QP-cancellable, hence $f_1 s_Y = f_2 s_Y$. Since s_Y is an epimorphism in T, we obtain $f_1 = f_2$.

Conversely, let Sf be an epimorphism in QP. If $P \in P$ and $f_1, f_2: Y \rightarrow P$ are functions such that $f_1 f = f_2 f$, there exist two functions $g_1, g_2: SY \rightarrow P$ such that $g_1 s_Y = f_1$, $g_2 s_Y = f_2$. Thus $g_1 s_Y f = g_2 s_Y f$, and therefore $g_1(Sf)s_X = g_2(Sf)s_X$. Since s_X is an epimorphism in T and Sf is an epimorphism in QP, we obtain $g_1 = g_2$.

3.2 PROPOSITION. $K_X^P(A) = s_X^{-1}(K_{SX}^P(s_X(A)))$.

PROOF. By 2.8 we have $K_X(A) \subset s_X^{-1}(K_{SX}^P(s_X(A)))$. Suppose there exists a point $y \in s_X^{-1}(K_{SX}^P(s_X(A))) - K_X(A)$. Then we can find two functions $f_1, f_2: X \rightarrow P$, with $P \in P$, such that $f_1|_A = f_2|_A$ and $f_1(y) \neq f_2(y)$. If we consider the functions $g_1, g_2: SX \rightarrow P$, such that $g_1 s_X = f_1$, $g_2 s_X = f_2$, we obtain $g_1 s_X(y) \neq g_2 s_X(y)$. Since $g_1|_{s_X(A)} = g_2|_{s_X(A)}$ we deduce that $s_X(y) \notin K_{SX}^P(s_X(A))$, and this is absurd.

REMARK. We do not know whether an analogous proposition for the operator E_X^P and the epireflection map r_X holds. By 2.13 it could only be proved that such equality holds when $P \subset T_2$.

We remind that if \mathbf{P} is productive and hereditary and $X \in \mathbf{P}$, for each $A \subset X$ the inclusion $j: A \rightarrow X$ is an extremal monomorphism iff $E_X^{\mathbf{P}}(A) = A$, and j is a regular monomorphism iff $K_X^{\mathbf{P}}(A) = A$ (see [2]).

As a consequence of this fact and of corollaries 3.5, 3.6 in [3], we obtain the following

3.3 PROPOSITION. If \mathbf{P} is a disconnectedness contained in \mathbf{T}_1 and different from **Sing** we have

$$E_X^{\mathbf{P}}(A) = K_X^{\mathbf{P}}(A) = A .$$

3.4 PROPOSITION. The following conditions are equivalent:

- (a) $\mathbf{UP} = \mathbf{QP}$;
- (b) $E_X^{\mathbf{P}} = K_X^{\mathbf{P}}$ for each $X \in \mathbf{T}$;
- (c) $E_X^{\mathbf{P}}(\{x\}) = K_X^{\mathbf{P}}(\{x\})$ for each $X \in \mathbf{T}$ and $x \in X$;
- (d) $K_X^{\mathbf{P}}(A) = K_B^{\mathbf{P}}(A)$ for each X, A, B such that $A \subset B \subset X$ and $K_X^{\mathbf{P}}(B) = B$.

PROOF. (a) \Rightarrow (b) If \mathbf{QP} coincides with \mathbf{T} , \mathbf{T}_0 or $\mathbf{Q(S)}$, then $\mathbf{QP} = \mathbf{UP}$ and $E_X^{\mathbf{P}} = K_X^{\mathbf{P}}$ (see examples in §2).

Moreover the only disconnectednesses which are not contained in \mathbf{T}_1 are \mathbf{T} and \mathbf{T}_0 (see [1], Prop. 2.10). Thus we have only to consider the case $\mathbf{QP} = \mathbf{UP} \subset \mathbf{T}_1$, with $\mathbf{QP} \neq \mathbf{Q(S)}$. If X is a space and $A \subset X$, by 3.3 we have $K_{S_X}(s_X(A)) = s_X(A)$ and by 3.2

$$K_X^{\mathbf{P}}(A) = s_X^{-1}(K_{S_X}(s_X(A))) = s_X^{-1}(s_X(A)) .$$

It follows

$$K_X^{\mathbf{P}}(A) = s_X^{-1}(s_X(A)) = r_X^{-1}(r_X(A)) = \bigcup \{E_X^{\mathbf{P}}(\{x\}) \mid x \in A\} \subset E_X^{\mathbf{P}}(A) ,$$

hence, by 2.6, $K_X^{\mathbf{P}}(A) = E_X^{\mathbf{P}}(A)$.

(b) \Rightarrow (c) Obvious.

(c) \Rightarrow (a) It follows immediately from 2.12.

(c) \Leftrightarrow (d) It can be proved in a similar way as in Prop.1.8 in [2], even though the present assertion is more general.

REMARKS. (a) If \mathbf{P} is a class of Hausdorff spaces, the operators $E_X^{\mathbf{P}}$ and $K_X^{\mathbf{P}}$ coincide if and only if $\mathbf{QP} = \mathbf{Sing}$. For if $E_X^{\mathbf{P}} = K_X^{\mathbf{P}}$

and $QP \neq \text{Sing}$, for every $X \in \mathbf{P}$ and $A \in X$ we have by 2.13 and 3.3:

$$\overline{A} \subset E_X^{\mathbf{P}}(A) = K_X^{\mathbf{P}}(A) = A .$$

This would imply that every $X \in \mathbf{P}$ is discrete and this is not possible. As a consequence we get again that in \mathbf{T}_2 there are no disconnectednesses different from **Sing** (see [1]).

(b) The notions given in this paper can be introduced in a topological category. In particular Preuß introduced and studied the relative disconnectednesses in this more general setting ([10]). The situation seems to be a little more complicated for the disconnectednesses. A reason is that in \mathbf{T} the quotient space obtained by identifying the points of each \mathbf{P} -component is \mathbf{P} -totally disconnected and this fact is not always true in a topological category. For instance this is not true in the bireflective hull in \mathbf{T} of the Hausdorff spaces.

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