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*Commentationes Mathematicae Universitatis Carolinae*, Vol. 44 (2003), No. 3, 399--411

Persistent URL: <http://dml.cz/dmlcz/119397>

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## Cancellative actions

PIERRE ANTOINE GRILLET

*Abstract.* The following problem is considered: when can the action of a cancellative semigroup  $S$  on a set be extended to a simply transitive action of the universal group of  $S$  on a larger set.

*Keywords:* semigroup action, monoid action, cancellative action, universal actions,  $S$ -set, tensor product

*Classification:* 20M20

### Introduction

The following problem arose in [4]. Let  $S$  be a cancellative semigroup and  $G(S)$  be its universal group. Assume that  $S$  can be embedded in  $G(S)$ . When can the action of  $S$  on a set  $X$  be extended to a simply transitive action of  $G(S)$  on some set  $Y \supseteq X$ ? When  $S$  is commutative the solution of this problem is easy but leads to concepts that are of great importance for finitely generated commutative semigroups [4].

Here we consider the general case of an arbitrary semigroup  $S$  which acts on a set  $X$ . In Section 1 we use the universal group  $G(S)$  of  $S$ , and the canonical homomorphism  $\gamma : S \rightarrow G(S)$ , to construct a set  $Y$ , a mapping  $\iota : X \rightarrow Y$ , and an action of  $G(S)$  on  $Y$  which extends the action of  $S$  in the sense that  $\iota(s \cdot x) = \gamma(s) \cdot \iota(x)$  for all  $s$  and  $x$ , and has a universal property. This leads in Section 2 to necessary and sufficient conditions for extending the action of  $S$  on  $X$  to a simply transitive action of  $G(S)$  on some set  $Z \supseteq X$ , or to a simply transitive action of  $G(S)$  on  $Y$ . A later article will show that the latter conditions are equivalent to explicit sets of implications.

We do not assume that  $S$  is a monoid. But, if  $S$  is a monoid, then we may assume that it acts on  $X$  as a monoid ( $1 \cdot x = x$  for all  $x \in X$ ), since otherwise its action cannot be extended to a group action.

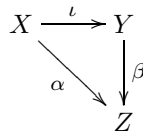
Recall that a *semigroup* is a set with an associative operation, which we write as a multiplication. A semigroup  $S$  is *cancellative* when  $xz = yz$  implies  $x = y$ , and  $zx = zy$  implies  $x = y$  (for all  $x, y, z \in S$ ). A *left semigroup action*  $\cdot$  of a semigroup  $S$  on a set  $X$  is a mapping  $(s, x) \mapsto s \cdot x$  of  $S \times X$  into  $X$ . Then  $S$  acts *simply* on  $X$  when  $s \cdot x = t \cdot x$  implies  $s = t$ ;  $S$  acts *transitively* on  $X$  when, for every  $x, y \in X$ , there exists some  $s \in S$  such that  $s \cdot x = y$ .

### 1. Universal actions

This section takes place in the category *Act* of semigroup acts. The objects of *Act* are all ordered triples  $(S, X, \cdot)$  of a semigroup  $S$ , a set  $X$ , and a left semigroup action  $\cdot$  of  $S$  on  $X$ ; then  $X$  is an  $S$ -set and  $(S, X, \cdot)$  is an  $S$ -act. In *Act*, a morphism from  $(S, X, \cdot)$  to  $(T, Y, \cdot)$  is an ordered pair  $(\varphi, f)$  of a semigroup homomorphism  $\varphi : S \rightarrow T$  and a mapping  $f : X \rightarrow Y$  such that  $f(s \cdot x) = \varphi(s) \cdot f(x)$  for all  $s \in S$  and  $x \in X$ ; if  $\varphi$  and  $f$  are injective, then the action of  $T$  on  $Y$  extends the action of  $S$  on  $X$ . Composition and identity morphisms are componentwise.

1. When  $\varphi : S \rightarrow T$  is a semigroup homomorphism, every  $S$ -act has a universal  $T$ -act:

**Proposition 1.1.** *Let  $(S, X, \cdot)$  be a semigroup act and  $\varphi : S \rightarrow T$  be a homomorphism. There exist a set  $Y$ , an action  $\cdot$  of  $T$  on  $Y$ , and a mapping  $\iota : X \rightarrow Y$  such that  $(\varphi, \iota) : (S, X, \cdot) \rightarrow (T, Y, \cdot)$  is a morphism and, for every morphism  $(\varphi, \alpha) : (S, X, \cdot) \rightarrow (T, Z, \cdot)$ , there exists a unique action-preserving mapping  $\beta : Y \rightarrow Z$  such that  $\beta \circ \iota = \alpha$ .*



PROOF: We construct  $Y$  as a tensor product of  $S$ -sets (as introduced in [5]): namely,  $Y = T^1 \otimes_S X$ , where  $S$  acts on  $T^1$  on the right by  $t \cdot s = t \varphi(s)$ . The details are as follows. Let  $\sim$  be the smallest equivalence relation on the set  $T^1 \times X$  such that

- (1) for all  $t, u, v \in T^1$  and  $x, y \in X$ ,  $(u, x) \sim (v, y)$  implies  $(tu, x) \sim (tv, y)$ ; and
- (2) for all  $s \in S$  and  $x \in X$ ,  $(\varphi(s), x) \sim (1, s \cdot x)$ .

This exists since an intersection of equivalence relations with properties (1) and (2) again has properties (1) and (2). A more detailed description of  $\sim$  is given in Lemma 1.2 below.

We show that  $Y = (T^1 \times X) / \sim$  serves. Let  $\text{cls}(t, x)$  denote the  $\sim$ -class of  $(t, x)$ . The mapping  $\iota : X \rightarrow Y$  is given by

$$\iota(x) = \text{cls}(1, x).$$

By (1), an action  $\cdot$  of  $T^1$  on  $Y$  is well defined by

$$t \cdot \text{cls}(u, x) = \text{cls}(tu, x).$$

This is a monoid action since  $1 \cdot \text{cls}(u, x) = \text{cls}(u, x)$  and

$$t \cdot (u \cdot \text{cls}(v, x)) = t \cdot \text{cls}(uv, x) = \text{cls}(tuv, x) = tu \cdot \text{cls}(v, x).$$

In particular,  $T$  acts on  $Y$ . Also

$$\iota(s \cdot x) = \text{cls}(1, s \cdot x) = \text{cls}(\varphi(s), x) = \varphi(s) \cdot \iota(x)$$

by (2). Thus  $(T, Y, \cdot)$  is an object of  $Act$  and  $(\varphi, \iota)$  is a morphism.

Let  $(\varphi, \alpha) : (S, X, \cdot) \longrightarrow (T, Z, \cdot)$  be a morphism. The mapping  $\alpha$  induces a mapping  $\bar{\alpha} : T^1 \times X \longrightarrow Z$  defined by

$$\bar{\alpha}(t, x) = t \cdot \alpha(x)$$

(with  $\bar{\alpha}(1, x) = \alpha(x)$  if  $t = 1 \in T^1$ ). If  $\bar{\alpha}(u, x) = \bar{\alpha}(v, y)$ , then  $u \cdot \alpha(x) = v \cdot \alpha(y)$  and

$$\begin{aligned} \bar{\alpha}(tu, x) &= tu \cdot \alpha(x) = t \cdot (u \cdot \alpha(x)) \\ &= t \cdot (v \cdot \alpha(y)) = tv \cdot \alpha(y) = \bar{\alpha}(tv, y). \end{aligned}$$

Also

$$\bar{\alpha}(\varphi(s), x) = \varphi(s) \cdot \alpha(x) = \alpha(s \cdot x) = 1 \cdot \alpha(s \cdot x) = \bar{\alpha}(1, s \cdot x)$$

by the choice of  $\alpha$ . Thus the equivalence relation induced by  $\bar{\alpha}$  satisfies (1) and (2). It therefore contains  $\sim$ :  $(t, x) \sim (u, y)$  implies  $\bar{\alpha}(t, x) = \bar{\alpha}(u, y)$ . Hence a mapping  $\beta : Y \longrightarrow Z$  is well defined by

$$\beta(\text{cls}(t, x)) = \bar{\alpha}(t, x) = t \cdot \alpha(x).$$

In particular  $\beta(\iota(x)) = \beta(\text{cls}(1, x)) = 1 \cdot \alpha(x) = \alpha(x)$  and  $\beta \circ \iota = \alpha$ . If moreover  $y = \text{cls}(u, x) \in Y$ , then

$$\beta(t \cdot y) = \beta(\text{cls}(tu, x)) = tu \cdot \alpha(x) = t \cdot (u \cdot \alpha(x)) = t \cdot \beta(y).$$

Thus  $\beta$  is action-preserving.

If conversely  $\beta' : Y \longrightarrow Z$  is action-preserving and  $\beta' \circ \iota = \alpha$ , then

$$\begin{aligned} \beta'(\text{cls}(t, x)) &= \beta'(t \cdot \text{cls}(1, x)) = \beta'(t \cdot \iota(x)) \\ &= t \cdot \beta'(\iota(x)) = t \cdot \alpha(x) = \beta(\text{cls}(t, x)); \end{aligned}$$

hence  $\beta$  is unique. □

We give a more precise description of  $\sim$  (which would work more generally in any tensor product of  $S$ -sets). For this it is convenient to regard the elements of  $T^1 \times X$  as the vertices of a directed graph, in which there is a labelled edge  $(t, s \cdot x) \xrightarrow{s} (t\varphi(s), x)$  for every  $(t, x) \in T^1 \times X$  and  $s \in S^1$ . In particular there is an identity edge  $(t, x) \xrightarrow{1} (t, x)$  for every  $(t, x) \in T^1 \times X$ . We note two properties:

If  $a \xrightarrow{s'} b \xrightarrow{s''} c$ , then  $a \xrightarrow{s's''} c$ : indeed, if  $a = (t, -)$  and  $c = (-, x)$ , then  $b = (t\varphi(s'), s'' \cdot x)$ , so that  $a = (t, s' \cdot (s'' \cdot x))$ ,  $c = (t\varphi(s')\varphi(s''), x)$ , and  $a \xrightarrow{s's''} c$ .

If  $(u, s \cdot x) \xrightarrow{s} (u\varphi(s), x)$ , then  $(tu, s \cdot x) \xrightarrow{s} (tu\varphi(s), x)$ .

**Lemma 1.2.** *In  $T^1 \times X$ ,  $a \sim b$  if and only if*

$$a = a_0 \xleftarrow{s_1} a_1 \xrightarrow{s_2} a_2 \cdots a_{2n-2} \xleftarrow{s_{2n-1}} a_{2n-1} \xrightarrow{s_{2n}} a_{2n} = b$$

for some  $n \geq 0$ ,  $a_0, \dots, a_{2n} \in T^1 \times X$ , and  $s_1, s_2, \dots, s_{2n} \in S^1$ .

PROOF: Let  $a \mathcal{C} b$  if and only if

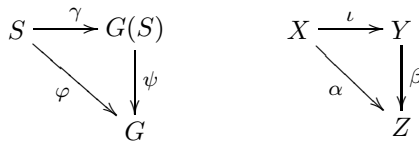
$$a = a_0 \xleftarrow{s_1} a_1 \xrightarrow{s_2} a_2 \cdots a_{2n-2} \xleftarrow{s_{2n-1}} a_{2n-1} \xrightarrow{s_{2n}} a_{2n} = b$$

for some  $n \geq 0$ ,  $a_0, \dots, a_{2n} \in T^1 \times X$ , and  $s_1, \dots, s_{2n} \in S^1$ . It is immediate that  $\mathcal{C}$  is reflexive (let  $n = 0$ ), symmetric, and transitive. Also  $(u, x) \mathcal{C} (v, y)$  implies  $(tu, x) \mathcal{C} (tv, y)$ , since  $(u, s \cdot x) \xrightarrow{s} (u\varphi(s), x)$  implies  $(tu, s \cdot x) \xrightarrow{s} (tu\varphi(s), x)$ ; and  $(\varphi(s), x) \mathcal{C} (1, s \cdot x)$ , since  $(\varphi(s), x) \xleftarrow{s} (1, s \cdot x) \xrightarrow{1} (1, s \cdot x)$ . Thus  $\mathcal{C}$  is an equivalence relation with properties (1) and (2).

If conversely  $\mathcal{A}$  is an equivalence relation with properties (1) and (2), then  $(t\varphi(s), x) \mathcal{A} (t, s \cdot x)$  for all  $t, s$ , and  $x$ ; hence  $(t, s \cdot x) \xrightarrow{s} (t\varphi(s), x)$  implies  $(t, s \cdot x) \mathcal{A} (t\varphi(s), x)$ , and  $a \mathcal{C} b$  implies  $a \mathcal{A} b$ . Therefore  $\mathcal{C}$  coincides with  $\sim$ .  $\square$

2. Proposition 1.1 implies that every semigroup act has a universal group act in *Act*. First recall that every semigroup  $S$  has a universal group in the category of semigroups and homomorphisms: that is, there exist a group  $G(S)$  and a homomorphism  $\gamma : S \rightarrow G(S)$ , such that every homomorphism  $\varphi$  of  $S$  into a group  $G$  factors uniquely through  $\gamma$  ( $\varphi = \psi \circ \gamma$  for some unique homomorphism  $\psi : G(S) \rightarrow G$ ). For instance let  $F$  be the free monoid on the set  $S \cup S'$ , where  $S'$  is disjoint from  $S$  and comes with a bijection  $s \mapsto s'$  of  $S$  onto  $S'$ . Let  $\iota : S \cup S' \rightarrow F$  be the canonical mapping. Let  $\mathcal{C}$  be the smallest congruence on  $F$  such that  $\iota(st) \mathcal{C} \iota(s)\iota(t)$ ,  $\iota(s)\iota(s') \mathcal{C} 1$ , and  $\iota(s')\iota(s) \mathcal{C} 1$ , for all  $s, t \in S$ ; then  $F/\mathcal{C}$  and the canonical mapping  $S \rightarrow F \rightarrow F/\mathcal{C}$  serve as  $G(S)$  and  $\gamma$ . The existence of a universal group also follows from the Adjoint Functor Theorem.

**Proposition 1.3.** *Let  $(S, X, \cdot)$  be a semigroup act. Let  $G(S)$  be the universal group of  $S$  and  $\gamma : S \rightarrow G(S)$  be the canonical homomorphism. The universal  $G(S)$ -set  $Y$  of  $X$  and its canonical morphism  $(\gamma, \iota) : (S, X, \cdot) \rightarrow (G(S), Y, \cdot)$  have the following universal property: for every morphism  $(\varphi, \alpha) : (S, X, \cdot) \rightarrow (G, Z, \cdot)$ , where  $G$  is a group, there exists a unique morphism  $(\psi, \beta) : (G(S), Y, \cdot) \rightarrow (G, Z, \cdot)$  such that  $(\psi, \beta) \circ (\gamma, \iota) = (\varphi, \alpha)$ .*



PROOF: By Proposition 1.1,  $(\gamma, \iota) : (S, X, \cdot) \longrightarrow (G(S), Y, \cdot)$  is a morphism and, for every morphism  $(\gamma, \alpha) : (S, X, \cdot) \longrightarrow (G(S), Z, \cdot)$ , there exists a unique action-preserving mapping  $\beta : Y \longrightarrow Z$  such that  $\beta \circ \iota = \alpha$ . We now prove the stronger universal property in the statement.

Let  $G$  be a group and  $(\varphi, \alpha) : (S, X, \cdot) \longrightarrow (G, Z, \cdot)$  be a morphism. Since  $G(S)$  is the universal group of  $S$  there exists a unique homomorphism  $\psi : G(S) \longrightarrow G$  such that  $\psi \circ \gamma = \varphi$ . The action of  $G$  on  $Z$  then induces an action of  $G(S)$  on  $Z$ , given by

$$g \cdot z = \psi(g) \cdot z$$

for all  $g \in G(S)$  and  $z \in Z$ . Then

$$\alpha(s \cdot x) = \varphi(s) \cdot \alpha(x) = \psi(\gamma(s)) \cdot \alpha(x) = \gamma(s) \cdot \alpha(x)$$

for all  $s \in S$  and  $x \in X$ , and  $(\gamma, \alpha) : (S, X, \cdot) \longrightarrow (G(S), Z, \cdot)$  is a morphism of acts. Hence there is a unique mapping  $\beta : Y \longrightarrow Z$  such that  $\beta \circ \iota = \alpha$  and  $\beta$  preserves the action of  $G(S)$ . This last condition states that

$$\beta(g \cdot y) = g \cdot \beta(y) = \psi(g) \cdot \beta(y)$$

for all  $g \in G(S)$  and  $y \in Y$ , i.e.  $(\psi, \beta) : (G(S), Y, \cdot) \longrightarrow (G, Z, \cdot)$  is a morphism of acts. Thus there is a unique morphism  $(\psi, \beta) : (G(S), Y, \cdot) \longrightarrow (G, Z, \cdot)$  such that  $(\psi, \beta) \circ (\gamma, \iota) = (\varphi, \alpha)$ .  $\square$

3. In Proposition 1.3 (up to isomorphism of acts)  $Y = (G(S) \times X) / \sim$ , where  $\sim$  is the smallest equivalence relation on the set  $G(S) \times X$  such that (1)  $(g, x) \sim (h, y)$  implies  $(kg, x) \sim (kh, y)$  and (2)  $(\gamma(s), x) \sim (1, s \cdot x)$ , for all  $g, h, k \in G(S)$ ,  $x, y \in X$ , and  $s \in S$ ; then  $g \cdot \text{cls}(h, x) = \text{cls}(gh, x)$  and  $\iota(x) = \text{cls}(1, x)$ . Lemma 1.2 then leads to a better description of  $\sim$ .

When  $x, y \in X$ , a *connected sequence* from  $x$  to  $y$  is a triple of sequences  $x_0, x_1, \dots, x_n \in X$ ,  $s_1, \dots, s_n \in S^1$ ,  $t_1, \dots, t_n \in S^1$  (where  $n \geq 0$ ) such that  $x = x_0$ ,  $x_n = y$ , and

$$t_1 \cdot x_0 = s_1 \cdot x_1, \quad t_2 \cdot x_1 = s_2 \cdot x_2, \quad \dots, \quad t_n \cdot x_{n-1} = s_n \cdot x_n$$

holds in  $X$  (with  $1 \cdot x = x$  in case  $S$  is not a monoid). The *group value* of a connected sequence  $x_0, x_1, \dots, x_n \in X$ ,  $s_1, \dots, s_n \in S^1$ ,  $t_1, \dots, t_n \in S^1$  is

$$\gamma(t_1)^{-1} \gamma(s_1) \gamma(t_2)^{-1} \gamma(s_2) \dots \gamma(t_n)^{-1} \gamma(s_n) \in G(S)$$

(with  $\gamma(1) = 1 \in G(S)$  in case  $S$  is not a monoid).

**Lemma 1.4.**  $(g, x) \sim (h, y)$  if and only if there exists a connected sequence from  $x$  to  $y$  with group value  $g^{-1}h$ .

PROOF: Assume  $(g, x) \sim (h, y)$ . By Lemma 1.2 there exist  $n \geq 0$ ,  $(g_0, x_0)$ ,  $(g_1, x_1), \dots, (g_{2n}, x_{2n}) \in G(S) \times X$ , and  $s_1, \dots, s_{2n} \in S^1$  such that  $(g_0, x_0) = (g, x)$ ,  $(g_{2n}, x_{2n}) = (h, y)$ , and

$$(g_0, x_0) \xleftarrow{s_1} (g_1, x_1) \xrightarrow{s_2} (g_2, x_2) \xleftarrow{s_3} \dots \\ \xrightarrow{s_{2n-2}} (g_{2n-2}, x_{2n-2}) \xleftarrow{s_{2n-1}} (g_{2n-1}, x_{2n-1}) \xrightarrow{s_{2n}} (g_{2n}, x_{2n}).$$

Then  $g_0 = g_1 \gamma(s_1)$ ,  $s_1 \cdot x_0 = x_1 = s_2 \cdot x_2$ , and  $g_2 = g_1 \gamma(s_2) = g_0 \gamma(s_1)^{-1} \gamma(s_2)$ . Similarly  $s_3 \cdot x_2 = s_4 \cdot x_4$ ,  $g_4 = g_2 \gamma(s_3)^{-1} \gamma(s_4)$ ,  $\dots$ ,  $s_{2n-1} \cdot x_{2n-2} = s_{2n} \cdot x_{2n}$ , and  $g_{2n} = g_{2n-2} \gamma(s_{2n-1})^{-1} \gamma(s_{2n})$ . Hence  $x_0, x_2, \dots, x_{2n} \in X$ ,  $s_2, s_4, \dots, s_{2n} \in S^1$ ,  $s_1, s_3, \dots, s_{2n-1} \in S^1$ , is a connected sequence from  $x$  to  $y$ , whose group value is  $g_0^{-1} g_{2n} = g^{-1}h$ , since

$$g_{2n} = g_0 \gamma(s_1)^{-1} \gamma(s_2) \gamma(s_3)^{-1} \gamma(s_4) \dots \gamma(s_{2n-1})^{-1} \gamma(s_{2n}).$$

The converse is similar. Let  $x_0, x_1, \dots, x_n \in X$ ,  $s_1, \dots, s_n \in S^1$ ,  $t_1, \dots, t_n \in S^1$  be a connected sequence from  $x$  to  $y$  with group value  $g^{-1}h$ . Let

$$y_1 = t_1 \cdot x_0 = s_1 \cdot x_1, y_2 = t_2 \cdot x_1 = s_2 \cdot x_2, \dots, y_n = t_n \cdot x_{n-1} = s_n \cdot x_n$$

and  $g_0 = g$ ,  $h_1 = g_0 \gamma(t_1)^{-1}$ ,  $g_1 = h_1 \gamma(s_1)$ ,  $h_2 = g_1 \gamma(t_2)^{-1}$ ,  $g_2 = h_2 \gamma(s_2)$ ,  $\dots$ ,  $h_n = g_{n-1} \gamma(t_n)^{-1}$ ,  $g_n = h_n \gamma(s_n)$ . Then  $g_n = h$ , since

$$g_n = g_0 \gamma(t_1)^{-1} \gamma(s_1) \gamma(t_2)^{-1} \gamma(s_2) \dots \gamma(t_n)^{-1} \gamma(s_n) = g g^{-1}h.$$

Moreover,

$$(g_0, x_0) \xleftarrow{t_1} (h_1, y_1) \xrightarrow{s_1} (g_1, x_1) \xleftarrow{t_2} \dots \\ \dots \xrightarrow{s_{n-1}} (g_{n-1}, x_{n-1}) \xleftarrow{t_n} (h_n, y_n) \xrightarrow{s_n} (g_n, x_n).$$

Hence  $(g, x) \sim (h, y)$ . □

It is convenient to write  $x \xrightarrow{g} y$  when  $x, y \in X$  and there is a connected sequence from  $x$  to  $y$  with group value  $g \in G(S)$ . We note the following properties.

**Lemma 1.5.**  $x \xrightarrow{1} x$  and  $s \cdot x \xrightarrow{\gamma(s)} x$  for every  $x \in X$  and  $s \in S$ . If  $x \xrightarrow{g} y$ , then  $y \xrightarrow{g^{-1}} x$ . If  $x \xrightarrow{g} y$  and  $y \xrightarrow{h} z$ , then  $x \xrightarrow{gh} z$ .

PROOF: When  $x \in X$ , then  $x \xrightarrow{1} x$  since there is a connected sequence with  $n = 0$  (also,  $(1, x) \sim (1, x)$ ). More generally, when  $s \in S^1$ , then  $s \cdot x = x_0$ ,  $x_1 = x \in X$ ,  $s_1 = s \in S^1$ ,  $t_1 = 1 \in S^1$  is a connected sequence from  $s \cdot x$  to  $x$  with group value  $\gamma(s)$ ; hence  $s \cdot x \xrightarrow{\gamma(s)} x$ .

If  $x = x_0, x_1, \dots, x_n = y \in X$ ,  $s_1, \dots, s_n \in S^1$ ,  $t_1, \dots, t_n \in S^1$  is a connected sequence from  $x$  to  $y$  with group value

$$g = \gamma(t_1)^{-1} \gamma(s_1) \gamma(t_2)^{-1} \gamma(s_2) \dots \gamma(t_n)^{-1} \gamma(s_n),$$

then  $y = x_n, x_{n-1}, \dots, x_0 = x \in X$ ,  $t_n, \dots, t_1 \in S^1$ ,  $s_n, \dots, s_1 \in S^1$  is a connected sequence from  $y$  to  $x$  with group value

$$\gamma(s_n)^{-1} \gamma(t_n) \gamma(s_{n-1})^{-1} \gamma(t_{n-1}) \dots \gamma(s_1)^{-1} \gamma(t_1) = g^{-1}.$$

Hence  $x \xrightarrow{g} y$  implies  $y \xrightarrow{g^{-1}} x$ .

If finally  $x = x_0, x_1, \dots, x_m = y \in X$ ,  $s_1, \dots, s_m \in S^1$ ,  $t_1, \dots, t_m \in S^1$  is a connected sequence from  $x$  to  $y$  with group value

$$g = \gamma(t_1)^{-1} \gamma(s_1) \gamma(t_2)^{-1} \gamma(s_2) \dots \gamma(t_m)^{-1} \gamma(s_m),$$

and  $y = y_0, y_1, \dots, y_n = z \in X$ ,  $u_1, \dots, u_n \in S^1$ ,  $v_1, \dots, v_n \in S^1$  is a connected sequence from  $y$  to  $z$  with group value

$$h = \gamma(v_1)^{-1} \gamma(u_1) \gamma(v_2)^{-1} \gamma(u_2) \dots \gamma(v_n)^{-1} \gamma(u_n),$$

then  $x = x_0, x_1, \dots, x_m = y_0, y_1, \dots, y_n \in X$ ,  $s_1, \dots, s_m, u_1, \dots, u_n \in S^1$ ,  $t_1, \dots, t_m, v_1, \dots, v_n \in S^1$  is a connected sequence from  $x$  to  $z$  with group value

$$\begin{aligned} &\gamma(t_1)^{-1} \gamma(s_1) \gamma(t_2)^{-1} \gamma(s_2) \dots \gamma(t_m)^{-1} \gamma(s_m) \\ &\gamma(v_1)^{-1} \gamma(u_1) \gamma(v_2)^{-1} \gamma(u_2) \dots \gamma(v_n)^{-1} \gamma(u_n) = gh. \end{aligned}$$

Hence  $x \xrightarrow{g} y$  and  $y \xrightarrow{h} z$  implies  $x \xrightarrow{gh} z$ . □

When  $S$  acts on  $X$ , the relation

$x \equiv y$  if and only if there exists a connected sequence from  $x$  to  $y$



is by Lemma 1.5 an equivalence relation on  $X$ ; we call its equivalence classes the *connected components* of  $X$ . We write the quotient set  $X/\equiv$  (the set of all connected components of  $X$ ) as a family  $(C_i)_{i \in I}$ .

We say that the action of  $S$  on  $X$  is *connected* when there is only one connected component (when for every  $x, y \in X$  there exists a connected sequence from  $x$  to  $y$ ); we also say that the  $S$ -set  $X$  is connected. This is weaker than the usual transitivity conditions in, say, [3]. The connected components of any  $S$ -set are themselves connected  $S$ -sets.

4. We now give an alternate construction of the universal group act, in which the orbits of  $Y$  (under the action of  $G(S)$ ) are constructed from the connected components of  $X$ . First we note:

**Proposition 1.6.** *In the universal group act  $(G(S), Y, \cdot)$  of  $(S, X, \cdot)$ ,  $\iota(x)$  and  $\iota(y)$  lie in the same orbit if and only if  $x$  and  $y$  lie in the same connected component of  $S$ .*

PROOF: Let  $x, y \in X$ . If  $\iota(x)$  and  $\iota(y)$  lie in the same orbit, then  $\text{cls}(1, x) = g \cdot \text{cls}(1, y) = \text{cls}(g, y)$  for some  $g \in G(S)$  and there exists a connected sequence from  $x$  to  $y$ , by Lemma 1.4. If conversely there exists a connected sequence from  $x$  to  $y$ , and  $g \in G(S)$  is its group value, then  $\iota(x) = \text{cls}(1, x) = \text{cls}(g, y) = g \cdot \iota(y)$ , by Lemma 1.4, so that  $\iota(x)$  and  $\iota(y)$  lie in the same orbit.  $\square$

Stabilizers and orbits in  $Y$  can be retrieved from  $X$  as follows.

**Lemma 1.7.** *Let  $C$  be a connected component of  $X$  and  $c \in C$ . Then*

$$H(C) = \{ h \in G(S) \mid c \xrightarrow{h} c \}$$

is a subgroup of  $G(S)$ ; for every  $x \in C$ ,  $\{ g \in G(S) \mid x \xrightarrow{g} c \}$  is a left coset of  $H(C)$ .

PROOF:  $H = H(C)$  is a subgroup of  $G(S)$  by Lemma 1.5. Let  $x \xrightarrow{g} c$ . If  $c \xrightarrow{h} c$ , then  $x \xrightarrow{gh} c$ . If conversely  $x \xrightarrow{g'} c$ , then  $c \xrightarrow{g^{-1}} x \xrightarrow{g'} c$ ,  $g^{-1}g' \in H$ , and  $g' \in gH$ ; thus  $\{ g' \in G(S) \mid x \xrightarrow{g'} c \} = gH$ .  $\square$

Recall that, when  $H$  is a subgroup of a group  $G$ , then the left cosets of  $H$  constitute a set  $G/H$ , on which  $G$  acts by left multiplication:  $g' \cdot gH = g'gH$ .

**Proposition 1.8.** *Let  $(S, X, \cdot)$  be a semigroup act,  $(G(S), Y, \cdot)$  be its universal group act, and  $(C_i)_{i \in I}$  be its connected components. For any cross-section  $(c_i)_{i \in I}$  of  $\equiv$ ,  $Y$  is (up to an isomorphism of  $G(S)$ -acts) the disjoint union*

$$Y = \bigcup_{i \in I} (G(S)/H(C_i) \times \{i\}),$$

with  $g \cdot (g'H(C_i), i) = (gg'H(C_i), i)$  and  $\iota(x) = (gH(C_i), i)$  when  $x \in C_i$  and  $x \xrightarrow{g} c_i$ .

PROOF: We need a cross-section  $(c_i)_{i \in I}$  of  $\equiv$  (with  $c_i \in C_i$ ) to define  $H(C_i) = \{h \in G(S) \mid c_i \xrightarrow{h} c_i\}$ . Let

$$Z = \bigcup_{i \in I} (G(S)/H(C_i) \times \{i\}),$$

with  $g \cdot (g'H(C_i), i) = (gg'H(C_i), i)$  as in the statement. Then  $Z$  is a  $G(S)$ -set. By Lemma 1.7, a mapping  $\alpha : X \rightarrow Z$  is well-defined by

$$\alpha(x) = (gH(C_i), i) \text{ when } x \in C_i \text{ and } x \xrightarrow{g} c_i.$$

Let  $x \in X$ ,  $x \in C_i$ , and  $s \in S$ . Then  $s \cdot x \xrightarrow{\gamma(s)} x$  by Lemma 1.5, in particular  $s \cdot x \in C_i$ . If  $x \xrightarrow{g} c_i$ , so that  $\alpha(x) = (gH(C_i), i)$ , then  $s \cdot x \xrightarrow{\gamma(s)g} c_i$  and

$$\alpha(s \cdot x) = (\gamma(s)gH(C_i), i) = \gamma(s) \cdot \alpha(x).$$

Thus  $(\gamma, \alpha) : (S, X, \cdot) \rightarrow (G(S), Z, \cdot)$  is a morphism of acts.

By Proposition 1.1, there exists an action-preserving mapping  $\beta : Y \rightarrow Z$  such that  $\beta \circ \iota = \alpha$ . We show that  $\beta$  is bijective. Since  $\beta$  is action-preserving, we have

$$\beta(\text{cls}(g, x)) = \beta(g \cdot \text{cls}(1, x)) = \beta(g \cdot \iota(x)) = g \cdot \beta(\iota(x)) = g \cdot \alpha(x)$$

for all  $x \in X$  and  $g \in G(S)$ . Now  $\alpha(c_i) = (H(C_i), i)$ , since  $c_i \xrightarrow{1} c_i$ ; hence  $(gH(C_i), i) = g \cdot \alpha(c_i)$  and  $\beta$  is surjective.

Now assume that  $\beta(\text{cls}(g, x)) = \beta(\text{cls}(h, y))$ . Let  $x \in C_i$ ,  $x \xrightarrow{a} c_i$  and  $y \in C_j$ ,  $y \xrightarrow{b} c_j$ , so that  $\alpha(x) = (aH(C_i), i)$  and  $\alpha(y) = (bH(C_j), j)$ . We have

$$(gaH(C_i), i) = g \cdot \alpha(x) = h \cdot \alpha(y) = (hbH(C_j), j),$$

so that  $i = j$  ( $x$  and  $y$  lie in the same connected component) and  $gaH(C_i) = hbH(C_i)$ . Hence  $aH(C_i) = g^{-1}hbH(C_i)$ , there exists  $x \xrightarrow{g^{-1}hb} c_i$  by Lemma 1.7, and  $x \xrightarrow{g^{-1}hb} c_i \xrightarrow{b^{-1}} y$  yields  $x \xrightarrow{g^{-1}h} y$  and  $\text{cls}(g, x) = \text{cls}(h, y)$ , by Lemma 1.4. Thus  $\beta$  is injective.  $\square$

5. A notable particular case occurs when  $S$  acts on itself by left multiplication.

**Proposition 1.9.** *When a semigroup  $S$  acts on itself by left multiplication, the connected components of  $S$  are left ideals, and  $\equiv$  is the smallest congruence  $\mathcal{C}$  on  $S$  such that  $S/\mathcal{C}$  is a right zero semigroup.*

PROOF: For all  $x, y \in S$  the equality  $x \cdot y = xy = 1 \cdot xy$  shows that  $y \equiv xy$ ; hence the  $\equiv$ -classes  $(L_i)_{i \in I}$  are left ideals. In particular  $L_i L_j \subseteq L_j$  for all  $i, j$ ; hence  $\equiv$  is a congruence and  $S/\equiv$  is a right zero semigroup ( $ab = b$  for all  $a, b \in S/\equiv$ ). Conversely let  $\mathcal{C}$  be a right zero semigroup congruence on  $S$ . If  $x, y \in S$  and  $s, t \in S^1$ , then  $sx = ty$  implies  $x \mathcal{C} sx \mathcal{C} ty \mathcal{C} y$ ; therefore  $\equiv$  is contained in  $\mathcal{C}$ .  $\square$

Proposition 1.9 goes back to Dubreil [2]. A semigroup  $S$  may be called *left connected* when  $S$ , as an  $S$ -set under left multiplication, has only one connected component. For example, every monoid is left connected ( $s \sim 1$  for every  $s$  since  $1 \cdot s = s \cdot 1$ ). (On the other hand, nontrivial right zero bands, and free semigroups with two or more generators, are not left connected.) Proposition 1.9 implies that every semigroup is a right zero band of left-connected semigroups. Additional results on band decompositions, including right zero band decompositions, can be found in [1].

**Lemma 1.10.** *When  $S$  acts on itself by left multiplication, every connected sequence from  $x$  to  $y$  has group value  $\gamma(x) \gamma(y)^{-1}$ .*

PROOF: As in the proof of Lemma 1.4, let  $x_0, x_1, \dots, x_n \in X$ ,  $s_1, \dots, s_n \in S$ ,  $t_1, \dots, t_n \in S$  be a connected sequence from  $x$  to  $y$  with group value  $g$ . Then

$$t_1 x_0 = s_1 x_1, \quad t_2 x_1 = s_2 x_2, \quad \dots, \quad t_n x_{n-1} = s_n x_n$$

and  $\gamma(t_1)^{-1} \gamma(s_1) \gamma(t_2)^{-1} \gamma(s_2) \dots \gamma(t_n)^{-1} \gamma(s_n) = g$ . In  $G(S)$  we have

$$\begin{aligned} \gamma(t_1)^{-1} \gamma(s_1) &= \gamma(x_0) \gamma(x_1)^{-1}, & \gamma(t_2)^{-1} \gamma(s_2) &= \gamma(x_1) \gamma(x_2)^{-1}, \\ \dots, & & \gamma(t_n)^{-1} \gamma(s_n) &= \gamma(x_{n-1}) \gamma(x_n)^{-1}. \end{aligned}$$

Hence

$$\begin{aligned} g &= \gamma(t_1)^{-1} \gamma(s_1) \gamma(t_2)^{-1} \gamma(s_2) \gamma(t_n)^{-1} \gamma(s_n) \\ &= \gamma(x_0) \gamma(x_n)^{-1} = \gamma(x) \gamma(y)^{-1}. \end{aligned}$$

$\square$

Lemma 1.10 implies that  $H(C) = \{1\}$  for every connected component  $C$  of  $S$ . Proposition 1.8 then yields:

**Corollary 1.11.** *Let  $S$  act on itself by left multiplication. The universal group act of  $S$  is isomorphic to a disjoint union of copies of  $G(S)$ , one for every connected component of  $S$ , on which  $G(S)$  acts by left multiplication.*

If in particular  $S$  is left connected (e.g. if  $S$  is a monoid), then the universal group act of  $S$  is isomorphic to  $G(S)$ , acting on itself by left multiplication.

## 2. Simply transitive actions

1. We now turn to the general problem posed in the beginning: can the action of  $S$  on a set  $X$  be extended to a simply transitive action of  $G(S)$ ? that is, is there an action-preserving injection  $\alpha : X \rightarrow Z$ , where  $G(S)$  acts simply and transitively on  $Z$ ?

We note some necessary conditions.

**Proposition 2.1.** *Let  $(S, X, \cdot)$  be a semigroup act,  $(G(S), Y, \cdot)$  be its universal group act, and  $(\gamma, \alpha) : (S, X, \cdot) \rightarrow (G(S), Z, \cdot)$  be a morphism of acts, so that  $\alpha = \beta \circ \iota$ . If  $\alpha$  is injective, then  $\iota$  is injective. If  $G(S)$  acts simply on  $Z$ , then  $G(S)$  acts simply on  $Y$ . If  $X \neq \emptyset$  and  $G(S)$  acts simply and transitively on  $Z$ , then  $\beta : Y \rightarrow Z$  is surjective; moreover, for every  $z \in Z$ ,  $\beta^{-1}(z)$  contains a single element of every orbit of  $Y$ .*

PROOF: By Proposition 1.1 there is a unique action-preserving mapping  $\beta : Y \rightarrow Z$  such that  $\alpha = \beta \circ \iota$ . If  $\alpha$  is injective, then so is  $\iota$ .

If  $G(S)$  acts simply on  $Z$  and  $g \cdot y = h \cdot y$  for some  $y \in Y$ , then  $g \cdot \beta(y) = \beta(g \cdot y) = \beta(h \cdot y) = h \cdot \beta(y)$  and  $g = h$ ; thus  $G(S)$  acts simply on  $Y$ .

If  $X \neq \emptyset$  and  $G(S)$  acts simply and transitively on  $Z$ , then  $Y \neq \emptyset$  and, for any  $z \in Z$  and  $y \in Y$ , we have  $z = g \cdot \beta(y) = \beta(g \cdot y)$  for some unique  $g \in G(S)$ ; thus  $\beta$  is surjective, and  $\beta^{-1}(z)$  contains exactly one element  $g \cdot y$  of the orbit of  $y$ . □

When  $\alpha$  is injective and  $G(S)$  acts simply and transitively on  $Z$ , Proposition 2.1 implies that  $\beta$  is made of bijections from every orbit of  $Y$  onto  $Z$ .

As in Section 1, let  $(C_i)_{i \in I}$  be the family of connected components of  $X$ , and let  $(c_i)_{i \in I}$  be a cross-section of  $\equiv$  (with  $c_i \in C_i$ ). Let  $V_i$  be the set of all  $g \in G(S)$  such that  $g$  is the group value of a connected sequence from some  $x \in C_i$  to  $c_i$ :

$$V_i = \{g \in G(S) \mid x \xrightarrow{g} c_i \text{ for some } x \in C_i\}.$$

By Lemma 1.7,  $V_i$  is a union of left cosets of  $H(C_i)$ .

**Lemma 2.2.** *In Proposition 2.1, let  $\alpha$  be injective and  $G(S)$  act simply and transitively on  $Z$ . Let  $p \in Z$ . Then*

$$\alpha(x) = \delta(x) \cdot p$$

*defines an injective mapping  $\delta : X \rightarrow G(S)$ . Moreover*

$$\delta(C_i) = V_i \delta(c_i)$$

*for every connected component  $C_i$  of  $X$  and  $c_i \in C_i$ .*

PROOF:  $\delta$  is well-defined: since  $G(S)$  act simply and transitively on  $Z$  there is for every  $x \in X$  a unique  $\delta(x) \in G(S)$  such that  $\alpha(x) = \delta(x) \cdot p$ . Then  $\delta$  is injective, since  $\alpha$  is injective.

If  $x \xrightarrow{g} c_i$ , then  $(1, x) \sim (g, c_i)$  by Lemma 1.4 and  $\iota(x) = g \cdot \iota(c_i)$ . Applying  $\beta$  yields

$$\alpha(x) = \beta(\iota(x)) = \beta(g \cdot \iota(c_i)) = g \cdot \beta(\iota(c_i)) = g \cdot \alpha(c_i).$$

Hence  $\delta(x) \cdot p = g\delta(c_i) \cdot p$  and  $\delta(x) = g\delta(c_i)$ . Therefore  $\delta(C_i) = V_i \delta(c_i)$ . □

We say that the connected components of  $S$  have disjoint images in  $G(S)$  (relative to a cross-section of  $\equiv$ ) if there exist  $g_i \in G(S)$  such that the sets  $V_i g_i$  are disjoint. If the action of  $S$  on a set  $X$  can be extended to a simply transitive action of  $G(S)$ , then (relative to any cross-section of  $\equiv$ ) the connected components of  $S$  have disjoint images in  $G(S)$ , by Lemma 2.2.

**Theorem 2.3.** *Let  $(S, X, \cdot)$  be a semigroup act and  $(G(S), Y, \cdot)$  be its universal group act. The action of  $S$  on  $X$  can be extended to a simply transitive action of  $G(S)$  on some set  $Z \supseteq X$  if and only if  $\iota$  is injective,  $G(S)$  acts simply on  $Y$ , and, relative to some cross-section of  $\equiv$ , the connected components of  $S$  have disjoint images in  $G(S)$ .*

PROOF: These conditions are necessary by Proposition 2.1 and Lemma 2.2. Conversely, assume that  $\iota$  is injective,  $G(S)$  acts simply on  $Y$ , and, relative to a cross-section  $(c_i)_{i \in I}$  of  $\equiv$ , the connected components of  $S$  have disjoint images in  $G(S)$ : the sets  $V_i g_i$  are disjoint for some  $g_i \in G(S)$ .

Construct  $\alpha : X \rightarrow G(S)$  as follows. Let  $x \in C_i$ . When  $x \xrightarrow{g} c_i$ , then  $(1, x) \sim (g, c_i)$  by Lemma 1.4 and  $\iota(x) = \text{cls}(1, x) = \text{cls}(g, c_i) = g \cdot \iota(c_i)$ . Since  $G(S)$  acts simply on  $Y$ ,  $g$  depends only on  $x$  (all connected sequences from  $x$  to  $c_i$  have the same group value). Therefore a mapping  $\alpha : X \rightarrow G(S)$  is well-defined by

$$\alpha(x) = gg_i \text{ when } x \in C_i \text{ and } x \xrightarrow{g} c_i.$$

Let  $x, y \in X$ . If  $x$  and  $y$  lie in different connected components  $C_i$  and  $C_j$ , then  $\alpha(x) \neq \alpha(y)$ , since the sets  $V_i g_i$  and  $V_j g_j$  are disjoint. Now let  $x$  and  $y$  lie in the same connected component  $C_i$ . Let  $x \xrightarrow{g} c_i$  and  $y \xrightarrow{h} c_i$ . If  $\alpha(x) = \alpha(y)$ , then  $g = h$ ,

$$\iota(x) = g \cdot \iota(c_i) = \iota(y)$$

by Lemma 1.4, and  $x = y$  since  $\iota$  is injective. Thus  $\alpha$  is injective.

Now  $G(S)$  acts simply and transitively on itself by left multiplication. We show that  $(\gamma, \alpha) : (S, X, \cdot) \rightarrow (G(S), Z, \cdot)$  is a morphism of acts. Let  $x \in X$  and  $s \in S$ . Let  $x \in C_i$  and  $x \xrightarrow{g} c_i$ . By Lemma 1.5,  $s \cdot x \xrightarrow{\gamma(s)} x$ ,  $s \cdot x \xrightarrow{\gamma(s)g} c_i$ , and

$$\alpha(s \cdot x) = \gamma(s)gg_i = \gamma(s)\alpha(x).$$

□

2. The following results complete Theorem 2.3.

**Proposition 2.4.** *In the universal group act  $(G(S), Y, \cdot)$  of  $(S, X, \cdot)$ ,  $\iota(x) = \iota(y)$  if and only if there exists a connected sequence from  $x$  to  $y$  with group value 1. If  $\iota$  is injective, then  $S$  acts by injections.*

PROOF:  $\iota(x) = \iota(y)$  if and only if  $(1, x) \sim (1, y)$ , so the first part of the statement follows from Lemma 1.4. Now assume that  $\iota$  is injective. If  $s \cdot x = s \cdot y$ , then  $x_0 = x, x_1 = y, s_1 = s, t_1 = s$  is a connected sequence from  $x$  to  $y$  with group value 1; hence  $x = y$ ; thus  $S$  acts by injections.  $\square$

**Proposition 2.5.** *In the universal group act  $(G(S), Y, \cdot)$  of  $(S, X, \cdot)$ ,  $G(S)$  acts simply on  $Y$  if and only if, for every  $x \in X$ , every connected sequence from  $x$  to  $x$  has group value 1.*

PROOF: This follows from Proposition 1.8, but we give a direct proof. If  $x \xrightarrow{g} x$ , then  $(1, x) \sim (g, x)$  by Lemma 1.4 and  $1 \cdot \text{cls}(1, x) = g \cdot \text{cls}(1, x)$ ; if  $G(S)$  acts simply on  $Y$  this implies  $g = 1$ . Conversely let  $g \cdot \text{cls}(k, x) = h \cdot \text{cls}(k, x)$ . Then  $(gk, x) \sim (hk, x)$ ; by Lemma 1.4, there is a connected sequence from  $x$  to  $x$  with group value  $(gk)^{-1} (hk)$ . If all such sequences have group value 1, then  $gk = hk$  and  $g = h$ ; thus  $G(S)$  acts simply on  $Y$ .  $\square$

Propositions 2.4 and 2.5 will be made more explicit in Section 4.

If  $X$  is connected, then the universal  $G(S)$ -set  $Y$  of  $X$  serves in Theorem 2.3:

**Proposition 2.6.** *In the universal group action  $(G(S), Y, \cdot)$  of  $(S, X, \cdot)$ ,  $G(S)$  acts transitively on  $Y$  if and only if  $X$  is connected.*

PROOF: This follows from Proposition 1.6, and from Proposition 1.8, but can be shown directly as follows. Let  $x, y \in X$ . If  $G(S)$  acts transitively on  $Y$ , then  $\text{cls}(1, x) = g \cdot \text{cls}(1, y) = \text{cls}(g, y)$  for some  $g \in G(S)$  and there exists a connected sequence from  $x$  to  $y$ , by Lemma 1.4; thus  $X$  is connected. Conversely let  $\text{cls}(h, x), \text{cls}(k, y) \in Y$ . If  $X$  is connected, there exists a connected sequence from  $x$  to  $y$  and  $(h, x) \sim (g, y)$  for some  $g \in G(S)$ , by Lemma 1.4; then  $kg^{-1} \cdot \text{cls}(h, x) = kg^{-1} \cdot \text{cls}(g, y) = \text{cls}(k, y)$ . Thus  $G(S)$  acts transitively on  $Y$ .  $\square$

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(Received August 8, 2002, revised March 11, 2003)