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# QUASISYMMETRIC GRAPHS AND ZYGMUND FUNCTIONS 

LEONID V. KOVALEV AND JANI ONNINEN


#### Abstract

A quasisymmetric graph is a curve whose projection onto a line is a quasisymmetric map. We show that this class of curves is related to solutions of the reduced Beltrami equation and to a generalization of the Zygmund class $\Lambda_{*}$. This relation makes it possible to use the tools of harmonic analysis to construct nontrivial examples of quasisymmetric graphs and of quasiconformal maps.


## 1. Introduction

Let $X$ and $Y$ be subsets of a Euclidean space $\mathbb{R}^{n}$. An embedding $f: X \rightarrow$ $Y$ is quasisymmetric if there is a homeomorphism $\eta:[0, \infty) \rightarrow[0, \infty)$ such that for any triple of distinct points $a, b, x \in X$

$$
\begin{equation*}
|f(x)-f(a)| \leqslant \eta(t)|f(x)-f(b)| \quad \text { where } \quad t=\frac{|x-a|}{|x-b|} \tag{1.1}
\end{equation*}
$$

We call a set $\Gamma \subset \mathbb{C}$ a quasisymmetric graph if the orthogonal projection of $\Gamma$ onto $\mathbb{R}$ is a quasisymmetric homeomorphism between $\Gamma$ (with the metric induced from $\mathbb{C}$ ) and $\mathbb{R}$. This should be compared to Lipschitz graphs, which can be defined by requiring the projection to be bi-Lipschitz, a stronger property than quasisymmetry. For instance, we shall see that the graph of any function in the Zygmund class $\Lambda_{*}$ is quasisymmetric.

This paper has three main goals.
(I) Parametrize quasisymmetric graphs by homeomorphic solutions of the reduced Beltrami equation;
(II) Use a generalization of the Zygmund class $\Lambda_{*}$ to construct quasisymmetric graphs;

[^0](III) Use (II) and (III) to solve a problem from [25] concerning the variation of reduced quasiconformal maps.

Our success in (I) is partial in that we can parametrize only quasisymmetric graphs with small distortion. This is made precise with the concept of an $s$-quasisymmetric map introduced by Tukia and Väisälä [34]. Namely, the map $f$ in (1.1) is called $s$-quasisymmetric (where $s>0$ is a constant) if $\eta$ can be chosen so that $\eta(t) \leqslant t+s$ for $0 \leqslant t \leqslant 1 / s$. Observe that any quasisymmetric map is $s$-quasisymmetric for large enough $s$. The term $s$-quasisymmetric graph should be self-explanatory.

Definition 1.1. A $W_{\text {loc }}^{1,2}$-homeomorphism $f: \mathbb{C} \rightarrow \mathbb{C}$ is quasiconformal if there exists a constant $k \in[0,1)$ such that

$$
\begin{equation*}
\left|f_{\bar{z}}\right| \leqslant k\left|f_{z}\right| \quad \text { a.e. in } \mathbb{C} \text {. } \tag{1.2}
\end{equation*}
$$

We sometimes refer to the constant $k$ in (1.2) by writing that $f$ is $k$ quasiconformal. The images of circles and lines under a quasiconformal map are called quasicircles and quasilines, respectively. These curves are ubiquitous in geometric function theory and still pose challenging problems [16, 27, 28, 30].

Inequality (1.2) is a form of the Beltrami equation $f_{\bar{z}}=\nu(z) f_{z}$ where $\|\nu\|_{L^{\infty}}<1$. A closely related equation with $f_{z}$ replaced by $\operatorname{Re} f_{z}\left(\operatorname{or} \operatorname{Im} f_{z}\right)$ arises from consideration of elliptic PDE in the plane and generated considerable interest recently [4, 7, 8, 17, 22, 23, 25]. We state this reduced Beltrami equation as an inequality, without an explicit coefficient $\nu$.

Definition 1.2. A nonconstant continuous $W_{\text {loc }}^{1,2}$-mapping $f: \mathbb{C} \rightarrow \mathbb{C}$ is reduced quasiconformal if there exists a constant $k \in[0,1)$ such that

$$
\begin{equation*}
\left|f_{\bar{z}}\right| \leqslant k \operatorname{Re} f_{z}, \quad \text { a.e. in } \mathbb{C} . \tag{1.3}
\end{equation*}
$$

Definition 1.2 does not explicitly require $f$ to be a homeomorphism, but the injectivity of $f$ is a consequence of inequality (1.3) [21, Corollary 1.5]. In addition, $f$ maps every horizontal line onto a graph over $\mathbb{R}$ [22, Proposition 1.5] except for the degenerate case

$$
\begin{equation*}
f(z)=i \lambda z+b, \quad \lambda \in \mathbb{R}, \quad b \in \mathbb{C}, \tag{1.4}
\end{equation*}
$$

when both sides of (1.3) vanish identically.

We are now ready to state the result that achieves Goal (I) for graphs of small distortion.

Theorem 1.3. There exists a constant $s_{0}>0$ such that any s-quasisymmetric graph $\Gamma \subset \mathbb{C}$ with $s<s_{0}$ is the image of $\mathbb{R}$ under a reduced quasiconformal mapping $f: \mathbb{C} \rightarrow \mathbb{C}$. Moreover, the constant $k$ in (1.3) depends only on $s$ and $k \rightarrow 0$ as $s \rightarrow 0$.

It should be mentioned that even though $\Gamma$ has a natural quasisymmetric parametrization by $\mathbb{R}$ (the inverse of projection), this parametrization cannot in general be extended to a reduced quasiconformal mapping of $\mathbb{C}$. Instead we use the parametrization that comes from the conformal map of upper half-plane onto the domain above $\Gamma$.

Our Goal (II) is achieved by means of Theorem 1.4. It employs the generalized Zygmund class $\Lambda_{\mu}$ which is introduced in Definition 2.6.

Theorem 1.4. Let $\mu$ be a doubling measure on $\mathbb{R}$. Let $u$ and $v$ be real functions on $\mathbb{R}$ such that $u^{\prime}=\mu$ and $v \in \Lambda_{\mu}$. Then the image of $\mathbb{R}$ under the map $\Gamma(t)=u(t)+i v(t)$ is a quasisymmetric graph.

Furthermore, if the doubling constant of $\mu$ and the $\Lambda_{\mu}$-seminorm of $v$ are sufficiently small, then $\Gamma(\mathbb{R})$ is an s-quasisymmetric graph where $s$ is small.

Theorems 1.3 and 1.4 from the basis for the proof of our third main result. To state it, let $\Phi_{q}:[0, \infty) \rightarrow[0, \infty)$ be any convex increasing function such that

$$
\begin{equation*}
\Phi_{q}(t)=\frac{t}{(\log 1 / t)^{q}} \quad \text { for small } t \tag{1.5}
\end{equation*}
$$

We refer to Definition 2.7 for the notion of $\Phi$-variation.
Theorem 1.5. There exists a reduced quasiconformal mapping $f: \mathbb{C} \rightarrow \mathbb{C}$ whose restriction to the line segment $[0,1]$ has infinite $\Phi_{q}$-variation for every $0<q<1$.

This result was previously known only for $q<1 / 2$ [25, Remark 4.1]. On the other hand, for $q>1$ every reduced quasiconformal map has finite $\Phi_{q^{-}}$ variation on line segments [25, Theorem 1.7]. The borderline case $q=1$ remains open. Using the additivity of reduced quasiconformal maps, one can strengthen the conclusion of Theorem 1.5 by replacing one line segment
with an arbitrary countable set of lines. See [25] for details. The size of such exceptional sets for Sobolev and quasiconformal maps was recently studied in 9].

We do not know if the restriction $s<s_{0}$ is necessary in Theorem 1.3. The converse statement holds without such restrictions.

Proposition 1.6. If $f: \mathbb{C} \rightarrow \mathbb{C}$ is a reduced quasiconformal map which is not of the form (1.4), then $f(\mathbb{R})$ is an s-quasisymmetric graph with $s=$ $s(k) \rightarrow 0$ as $k \rightarrow 0$. Here $k$ is the constant in (1.3). In addition,

$$
\begin{equation*}
\left.\operatorname{Im} f\right|_{\mathbb{R}} \in \Lambda_{\mu} \quad \text { where } \mu=\frac{d}{d x} \operatorname{Re} f(x) \tag{1.6}
\end{equation*}
$$

This leads to a conjecture.
Conjecture 1.7. The images of $\mathbb{R}$ under reduced quasiconformal maps $\mathbb{C} \rightarrow$ $\mathbb{C}$ are precisely quasisymmetric graphs and vertical lines.

Parametrization of Lipschitz graphs is much easier to achieve. They corresponds to delta-monotone maps, which are defined as follows. A map $f: \mathbb{C} \rightarrow \mathbb{C}$ is delta-monotone if there exists a constant $\delta>0$ such that

$$
\operatorname{Re} \frac{f(z)-f(\zeta)}{z-\zeta} \geqslant \delta \frac{|f(z)-f(\zeta)|}{|z-\zeta|} \quad \text { for all distinct } z, \zeta \in \mathbb{C}
$$

This is a proper subclass of reduced quasiconformal maps [22].
Proposition 1.8. The images of $\mathbb{R}$ under nonconstant delta-monotone maps $\mathbb{C} \rightarrow \mathbb{C}$ are precisely Lipschitz graphs.

Remark 1.9. The concept of a quasisymmetric graph also makes sense for $k$ hypersurfaces in $\mathbb{R}^{n}$, although it reduces to Lipschitz graphs when $2 k>n$. It would be interesting to investigate, e.g., 2-dimensional quasisymmetric graphs in $\mathbb{R}^{4}$, but we do not pursue this direction here.

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## 2. Preliminaries

By an embedding we understand a map that is a homeomorphism onto its image. An embedding $\Gamma: \mathbb{R} \rightarrow \mathbb{C}$ satisfies the Ahlfors condition if there
exists a constant $K$ such that

$$
\begin{equation*}
\operatorname{diam} \Gamma([a, b]) \leqslant K|\Gamma(a)-\Gamma(b)| \quad \text { whenever } a<b \tag{2.1}
\end{equation*}
$$

By a classical theorem of Ahlfors [1], the condition (2.1) characterizes quasilines, i.e., images of lines under quasiconformal maps. Tukia [32] proved that every quasisymmetric embedding $\mathbb{R} \rightarrow \mathbb{C}$ extends to a quasiconformal map $\mathbb{C} \rightarrow \mathbb{C}$. It immediately follows that every quasisymmetric graph is a quasiline. However, a quasiline may be a graph without being a quasisymmetric graph. Such examples are easy to find, e.g., the graphs $y=\sqrt{x^{+}}$and $y=e^{x}$.

The foundational results on $s$-quasisymmetric maps were obtained by Tukia and Väisälä in 1980s. We will use three of them. For simplicity, the theorems are stated here in the planar case.

Theorem 2.1. [34, Theorem 5.4] There is a number $s_{0}>0$ such that for $0 \leqslant s \leqslant s_{0}$ any s-quasisymmetric embedding of $\mathbb{R}$ into $\mathbb{C}$ extends to a $s_{1}$-quasisymmetric mapping $\mathbb{C} \rightarrow \mathbb{C}$. Here $s_{1}=s_{1}(s) \rightarrow 0$ as $s \rightarrow 0$.

Theorem 2.2. [34, Theorem 2.6] Any s-quasisymmetric homeomorphism $f: \mathbb{C} \rightarrow \mathbb{C}$ is $k$-quasiconformal with $k=k(s) \rightarrow 0$ as $s \rightarrow 0$. Conversely, any $k$-quasiconformal homeomorphism $f: \mathbb{C} \rightarrow \mathbb{C}$ is s-quasisymmetric with $s=s(k) \rightarrow 0$ as $k \rightarrow 0$.

Theorem 2.3. [35, Theorem 3.9] Let $0<\varkappa \leqslant \frac{1}{25}$, and let $f: \mathbb{R} \rightarrow \mathbb{C}$ be a map such that for any $a<b$ there is an affine map $h:[a, b] \rightarrow \mathbb{C}$ with

$$
\begin{equation*}
\sup _{[a, b]}|h-f| \leqslant \varkappa|h(a)-h(b)| . \tag{2.2}
\end{equation*}
$$

Then $f$ is s-quasisymmetric, where $s=s(\varkappa) \rightarrow 0$ as $\varkappa \rightarrow 0$.
Definition 2.4. A positive Radon measure $\mu$ on $\mathbb{R}$ is doubling if there exists $\delta>0$ such that

$$
\begin{equation*}
\mu(I) \leqslant(1+\delta) \mu(J) \tag{2.3}
\end{equation*}
$$

for any adjacent intervals $I, J$ of equal length.
Definition 2.5. A continuous function $g: \mathbb{R} \rightarrow \mathbb{R}$ belongs to the Zygmund class $\Lambda_{*}$ if there exists a constant $M>0$ such that

$$
\begin{equation*}
|g(x+h)-2 g(x)+g(x-h)| \leqslant 2 M h \quad \text { for all } x \in \mathbb{R}, h>0 \tag{2.4}
\end{equation*}
$$

The smallest such $M$ is the Zygmund seminorm of $g$.
It is often said that (2.4) is an additive form of (2.3). One can interpret (2.4) by saying that the nonlinearity of $g$ on any interval is controlled by the length of the interval. The relevance of the class $\Lambda_{*}$ to geometric function theory is evident by now [14, 29, 11]. But our subject required a wider class of functions, in which the length is replaced by a general nonatomic Radon measure on $\mathbb{R}$. A measure is nonatomic if it gives zero mass to every singleton. All our measures are positive.

Definition 2.6. Let $\mu$ be a nonatomic Radon measure on $\mathbb{R}$. A continuous function $g: \mathbb{R} \rightarrow \mathbb{R}$ belongs to the generalized Zygmund class $\Lambda_{\mu}$ if there exists a constant $M>0$ such that

$$
\begin{equation*}
|g(x+h)-2 g(x)+g(x-h)| \leqslant M \mu([x-h, x+h]) \tag{2.5}
\end{equation*}
$$

for all $x \in \mathbb{R}, h \geqslant 0$. The smallest such $M$ is the seminorm of $g$ in $\Lambda_{\mu}$.
We should make precise the remark about the controlled nonlinearity of $g$. Given distinct points $a, b \in \mathbb{R}$, let

$$
\begin{equation*}
g_{a b}(x)=\frac{b-x}{b-a} g(a)+\frac{x-a}{b-a} g(b) \tag{2.6}
\end{equation*}
$$

denote the affine function that agrees with $g$ at $a$ and $b$. If $g$ satisfies (2.5), then

$$
\begin{equation*}
\sup _{[a, b]}\left|g-g_{a b}\right| \leqslant M \mu([a, b]) \quad \text { whenever } a<b \tag{2.7}
\end{equation*}
$$

Indeed, we lose no generality in assuming that $g(a)=g(b)=0$ and $|g|$ attains its maximum on $[a, b]$ at a point $\xi \leqslant \frac{a+b}{2}$. Applying (2.5) with $x=\xi$ and $h=\xi-a$, we find

$$
|g(2 \xi-a)-2 g(\xi)| \leqslant M \mu([a, b]), \quad \text { hence } \quad|g(\xi)| \leqslant M \mu([a, b])
$$

Conversely, (2.7) yields (2.5) with $2 M$ in place of $M$.
Definition 2.7. Let $\Phi:[0, \infty) \rightarrow[0, \infty)$ be a convex increasing function. A function $v:[a, b] \rightarrow \mathbb{R}$ has finite $\Phi$-variation if

$$
\begin{equation*}
\sup \sum_{j=1}^{N} \Phi\left(\left|v\left(x_{j}\right)-v\left(x_{j-1}\right)\right|\right)<\infty \tag{2.8}
\end{equation*}
$$

where the supremum is taken over all partitions $a=x_{0}<\cdots<x_{N}=b$ and over all $N \geqslant 1$. If $v$ is defined on $\mathbb{R}$, we say that it has locally finite $\Phi$-variation if (2.8) holds for every bounded interval.

In the sequel, the constants $C$ and $c$ in estimates may be different from one line to another.

## 3. Proof of Propositions 1.6 and 1.8

Two of the results stated in the introduction admit simple proofs.
Proof of Proposition 1.6. To a reduced quasiconformal map $f$ we associate the one-parameter family $f_{\lambda}(z)=f(z)+i \lambda z, \lambda \in \mathbb{R}$. Unless $f$ is of the form (1.4), each $f_{\lambda}$ is also reduced quasiconformal, as it is nonconstant and satisfies (1.3) with the same constant as $f$. Therefore, $f_{\lambda}$ is $\eta$-quasisymmetric with $\eta$ independent of $\lambda$. In particular, for any triple of distinct points $a, b, x \in \mathbb{R}$ we have

$$
\begin{equation*}
\left|f_{\lambda}(x)-f_{\lambda}(a)\right| \leqslant \eta(|\tau|)\left|f_{\lambda}(x)-f_{\lambda}(b)\right|, \quad \tau=\frac{x-a}{x-b} . \tag{3.1}
\end{equation*}
$$

Setting $\lambda=-\operatorname{Im} \frac{f(x)-f(b)}{x-b}$ results in

$$
\begin{equation*}
|f(x)-f(a)-i \tau \operatorname{Im}(f(x)-f(b))| \leqslant \eta(|\tau|)|\operatorname{Re}(f(x)-f(b))| . \tag{3.2}
\end{equation*}
$$

There are two ways to use (3.2). First, we can take the real part and obtain

$$
\begin{equation*}
|\operatorname{Re}(f(x)-f(a))| \leqslant \eta(|\tau|)|\operatorname{Re}(f(x)-f(b))| \tag{3.3}
\end{equation*}
$$

which simply says that $\operatorname{Re} f$ is a quasisymmetric map from $\mathbb{R}$ onto $\mathbb{R}$. Combining (3.3) with the quasisymmetry of $f$, we conclude that the projection $w \mapsto \operatorname{Re} w$ is a quasisymmetric map from $\Gamma$ to $\mathbb{R}$.

Let $\mu$ denote the distributional derivative of $\operatorname{Re} f(x)$ with respect to $x$. Since $\operatorname{Re} f$ is quasisymmetric, $\mu$ is a doubling measure on $\mathbb{R}$ [20, Remark 13.20 b ]. Taking the imaginary part in (3.2) yields

$$
\begin{equation*}
|\operatorname{Im}(f(x)-f(a))-\tau \operatorname{Im}(f(x)-f(b))| \leqslant \eta(|\tau|)|\operatorname{Re}(f(x)-f(b))| . \tag{3.4}
\end{equation*}
$$

Choosing $x=\frac{a+b}{2}$, we conclude that $\operatorname{Im} f \in \Lambda_{\mu}$.
Remark 3.1. Every quasisymmetric graph $y=g(x)$ admits a natural quasisymmetric parametrization by $\mathbb{R}$, namely $f(x)=x+i g(x)$. In general, this function $f$ does not satisfy (1.6) and therefore cannot be extended to a
reduced quasiconformal map of the plane. For a concrete example, take the graph $y=x^{1 / 3}$.

Proof of Proposition 1.8. It is obvious that $f(\mathbb{R})$ is a Lipschitz graph for every delta-monotone map $f: \mathbb{C} \rightarrow \mathbb{C}$. Conversely, for any $L$-Lipschitz real function $g$ the mapping

$$
f(z):=\operatorname{Re} z+i L^{2} \operatorname{Im} z+i g(\operatorname{Re} z)
$$

satisfies

$$
\begin{equation*}
\operatorname{Re} f_{z}=\frac{L^{2}+1}{2}, \quad\left|\operatorname{Im} f_{z}\right| \leqslant \frac{L}{2} \leqslant \operatorname{Re} f_{z}, \tag{3.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|f_{\bar{z}}\right| \leqslant \sqrt{\frac{\left(L^{2}-1\right)^{2}}{4}+\frac{L^{2}}{4}} \leqslant k \operatorname{Re} f_{z} \tag{3.6}
\end{equation*}
$$

with $k=k(L)<1$. The combination of (3.5) and (3.6) implies that $f$ is delta-monotone, see [24, Lemma 12].

## 4. Proof of Theorem 1.3

Let $\mathbb{H}=\{z: \operatorname{Im} z>0\}$ denote the upper half-plane. By Theorems 2.1 and 2.2 the curve $\Gamma$ is a $k$-quasiline where $k$ is small if $s$ is.

The curve $\Gamma$ divides the plane into two domains; let $\Omega$ denote the upper one. Let $f: \mathbb{H} \rightarrow \Omega$ be a conformal mapping such that $f(\infty)=\infty$ in the sense of boundary correspondence. Since $\Gamma$ is a $k$-quasiline, $f$ extends to $\Gamma$ by continuity. It then extends to the entire plane by quasiconformal reflection, and the extended mapping is $\frac{2 k}{1+k^{2}}$-quasiconformal [1]. By Theorem [2.2 the correspondence $x \mapsto \operatorname{Re} f(x)$ is $s_{1}$-quasisymmetric where $s_{1}$ is small if $k$ is.

We claim that there exists $\tilde{k} \in[0,1)$ such that $\tilde{k} \rightarrow 0$ as $k \rightarrow 0$ and

$$
\begin{equation*}
2 \operatorname{Im} z\left|f^{\prime \prime}(z)\right| \leqslant \tilde{k} \operatorname{Re} f^{\prime}(z) \quad \text { for all } z \in \mathbb{H} . \tag{4.1}
\end{equation*}
$$

Assume (4.1) for now and complete the proof of the theorem.
The Koebe $1 / 4$-theorem [26, (I.6.7)] yields

$$
\begin{equation*}
\operatorname{Im} z\left|f^{\prime}(z)\right| \leqslant 2 \operatorname{dist}(f(z), \mathbb{C} \backslash f(\mathbb{H})) \quad \text { for all } z \in \mathbb{H} . \tag{4.2}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\lim _{z \rightarrow \zeta} \operatorname{Im} z\left|f^{\prime}(z)\right|=0 \quad \text { for any } \zeta \in \mathbb{R} \tag{4.3}
\end{equation*}
$$

We extend $f$ to $\mathbb{C}$ following the method that goes back to Ahlfors and Weill 3 and was further developed in [2, [5, 19]. Namely, we define $F: \mathbb{C} \rightarrow \mathbb{C}$ by

$$
F(z)= \begin{cases}f(z) & \operatorname{Im} z \geqslant 0  \tag{4.4}\\ f(\bar{z})+(z-\bar{z}) f^{\prime}(\bar{z}) & \operatorname{Im} z<0 .\end{cases}
$$

By virtue of (4.3) the mapping $F$ is continuous in $\mathbb{C}$. For $z \in \mathbb{C} \backslash \overline{\mathbb{H}}$ we have

$$
\begin{equation*}
F_{z}=f^{\prime}(\bar{z}) \quad \text { and } \quad F_{\bar{z}}=(z-\bar{z}) f^{\prime \prime}(\bar{z}) . \tag{4.5}
\end{equation*}
$$

The comparison of (4.1) and (4.5) shows that $F$ is reduced quasiconformal. The theorem is proved, modulo (4.1).

Proof of (4.1). The first step is to observe that $\operatorname{Re} f^{\prime}>0$ in $\mathbb{H}$. To this end, introduce the function

$$
u_{h}(z):=\arg (f(z+h)-f(z)) \quad \text { for a fixed } h>0
$$

Here we choose the branch of arg so that $\left|u_{h}\right|<\pi / 2$ on $\partial \mathbb{H}$ : this is possible because $f$ extends to a homeomorphism $f: \overline{\mathbb{H}} \rightarrow \bar{\Omega}$ and $\partial \Omega$ is a graph. The maximum principle implies $\left|u_{h}\right|<\pi / 2$ in $\mathbb{H}$, and letting $h \rightarrow 0$ we obtain the desired conclusion $\operatorname{Re} f^{\prime}>0$.

The harmonic function $u=\operatorname{Re} f^{\prime}$, being positive in $\mathbb{H}$, admits the Herglotz representation [15, Theorem I.3.5]

$$
\begin{equation*}
u(z)=\beta \operatorname{Im} z+\frac{1}{\pi} \int_{\mathbb{R}} \operatorname{Im} \frac{1}{t-z} d \mu(t) \tag{4.6}
\end{equation*}
$$

where $\beta \geqslant 0$ and $\mu$ is a positive measure on $\mathbb{R}$ such that

$$
\begin{equation*}
\int_{\mathbb{R}} \frac{1}{1+t^{2}} d \mu(t)<\infty . \tag{4.7}
\end{equation*}
$$

Integration of (4.6) yields $\mu([a, b])=\operatorname{Re}(f(b)-f(a))$ for any finite interval $[a, b] \subset \mathbb{R}$. Recall that the map $x \mapsto \operatorname{Re} f(x)$ is $s_{1}$-quasisymmetric where $s_{1} \rightarrow 0$ as $k \rightarrow 0$. Therefore, the measure $\mu$ satisfies the doubling condition (2.3) where $\delta \rightarrow 0$ as $k \rightarrow 0$.

To proceed further, we must establish that $\beta=0$ in (4.6). To this end, we need the following growth estimate for univalent functions $F: \mathbb{H} \rightarrow \mathbb{C}$ :

$$
\begin{equation*}
|F(x+i y)| \leqslant|F(i)|+\frac{(y+1)^{4}}{y^{2}}\left|F^{\prime}(i)\right| \quad \text { for } y \geqslant 1, \quad|x| \leqslant y+1 . \tag{4.8}
\end{equation*}
$$

To prove (4.8), introduce

$$
\begin{equation*}
G(\zeta)=\frac{-i}{2 F^{\prime}(i)}\left\{F\left(i \frac{1+\zeta}{1-\zeta}\right)-F(i)\right\}, \quad|\zeta|<1 \tag{4.9}
\end{equation*}
$$

and observe that $G(0)=G^{\prime}(0)-1=0$. The growth theorem for class $S$ [13, Theorem 2.6] asserts that

$$
\begin{equation*}
|G(\zeta)| \leqslant \frac{|\zeta|}{(1-|\zeta|)^{2}}=\frac{|\zeta|(1+|\zeta|)^{2}}{\left(1-|\zeta|^{2}\right)^{2}} \leqslant \frac{4}{\left(1-|\zeta|^{2}\right)^{2}} \tag{4.10}
\end{equation*}
$$

We set $x+i y=i \frac{1+\zeta}{1-\zeta}$ and observe that $|\zeta|^{2} \leqslant \frac{y^{2}+1}{(y+1)^{2}}$. Combinng this with (4.10) and (4.9) the inequality (4.8) follows.

We may assume $0 \in \partial \Omega$. For $r>0$ let $\Gamma$ be the connected component of the set $\{z \in \mathbb{C} \backslash \Omega:|z|=r\}$ that contains the point $-i r$. By virtue of the Ahlfors condition (2.1) the length of $\Gamma$ is bounded from below by $c r$, with $c>0$ independent of $r$. Therefore the mapping $z \mapsto z^{p}$, where $p=\frac{2 \pi}{2 \pi-c}>1$, is univalent in $\Omega$. This allows us to apply (4.8) with $F=f^{p}$ and conclude that $|f(x+i y)|=O\left(y^{2 / p}\right)$ as $y \rightarrow \infty,|x| \leqslant y$. The Cauchy inequality for $f^{\prime}$ yields $\left|f^{\prime}(i y)\right|=O\left(y^{\frac{2}{p}-1}\right)$ as $y \rightarrow \infty$. Since the exponent of $y$ is strictly less than 1 , the coefficient $\beta$ in (4.6) must vanish.

Returning to (4.6), we compute

$$
\begin{equation*}
f^{\prime \prime}(z)=2 \frac{\partial u}{\partial z}(z)=\frac{1}{\pi i} \int_{\mathbb{R}} \frac{1}{(t-z)^{2}} d \mu(t) \tag{4.11}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{Re} f^{\prime}(z)=u(z)=\frac{\operatorname{Im} z}{\pi} \int_{\mathbb{R}} \frac{1}{|t-z|^{2}} d \mu(t) \tag{4.12}
\end{equation*}
$$

Thus, the desired inequality (4.1) takes the form

$$
\begin{equation*}
\left|\int_{\mathbb{R}} \frac{1}{(t-z)^{2}} d \mu(t)\right| \leqslant \frac{\tilde{k}}{2} \int_{\mathbb{R}} \frac{1}{|t-z|^{2}} d \mu(t) \tag{4.13}
\end{equation*}
$$

The following lemma yields (4.13). It is not particularly new; one can find a similar, but less precise, statement in [12, p. 157].

Lemma 4.1. For any $\varepsilon>0$ there exists $\delta>0$ such that the following holds.
If $\mu$ satisfies the doubling condition (2.3) then

$$
\begin{equation*}
\left|\int_{\mathbb{R}} \frac{1}{(t-z)^{2}} d \mu(t)\right| \leqslant \varepsilon \int_{\mathbb{R}} \frac{1}{|t-z|^{2}} d \mu(t)<\infty \quad \text { for all } z \in \mathbb{H} \text {. } \tag{4.14}
\end{equation*}
$$

Proof. We write $|I|$ for the length of an interval $I$. Repeated application of the doubling property yields the growth/decay estimate

$$
\begin{equation*}
(1-\gamma) \min \left(\tau, \tau^{-1}\right)^{\gamma} \leqslant \frac{\mu(I)}{\tau \mu(J)} \leqslant(1+\gamma) \max \left(\tau, \tau^{-1}\right)^{\gamma}, \quad \tau=\frac{|I|}{|J|} \tag{4.15}
\end{equation*}
$$

for any two intervals $I$ and $J$ with a common point. Here $\gamma \in(0,1)$ depends only on $\delta$, and $\gamma \rightarrow 0$ as $\delta \rightarrow 0$.

Using shift, scaling, and normalization, we reduce (4.14) to the case $z=i$ and $\mu([-1,1])=1$. By virtue of (4.15), for all $t>0$ we have

$$
\begin{equation*}
(1-\gamma) t \min \left(t, t^{-1}\right)^{\gamma} \leqslant \mu([-t, t]) \leqslant(1+\gamma) t \max \left(t, t^{-1}\right)^{\gamma} \tag{4.16}
\end{equation*}
$$

For small $\gamma$ the estimates (4.15) yield the following uniform bounds in $t$,

$$
|\mu([-t, t])-t|= \begin{cases}O(\gamma) & \text { if } 0<t<1  \tag{4.17}\\ O\left(\gamma t^{1+\gamma}(1+\log t)\right) & \text { if } t>1\end{cases}
$$

We proceed to estimate both sides of (4.14) via integration by parts followed by (4.17).

$$
\begin{align*}
\int_{\mathbb{R}} \frac{1}{t^{2}+1} d \mu(t) & =\int_{0}^{\infty} \frac{2 t}{\left(t^{2}+1\right)^{2}} \mu([-t, t]) d t  \tag{4.18}\\
& =\pi+\int_{0}^{\infty} \frac{2 t}{\left(t^{2}+1\right)^{2}}(\mu([-t, t])-t) d t
\end{align*}
$$

which in view of (4.17) implies

$$
\begin{equation*}
\int_{\mathbb{R}} \frac{1}{t^{2}+1} d \mu(t)=\pi+O(\gamma) \quad \text { as } \gamma \rightarrow 0 \tag{4.19}
\end{equation*}
$$

Next,

$$
\begin{align*}
\operatorname{Re} \int_{\mathbb{R}} \frac{1}{(t-i)^{2}} d \mu(t) & =\int_{\mathbb{R}} \frac{t^{2}-1}{\left(t^{2}+1\right)^{2}} d \mu(t) \\
& =\int_{0}^{\infty} \frac{2 t\left(t^{2}-3\right)}{\left(t^{2}+1\right)^{3}} \mu([-t, t]) d t  \tag{4.20}\\
& =\int_{0}^{\infty} \frac{2 t\left(t^{2}-3\right)}{\left(t^{2}+1\right)^{3}}(\mu([-t, t])-t) d t \\
& =O(\gamma)
\end{align*}
$$

Finally,

$$
\begin{align*}
\operatorname{Im} \int_{\mathbb{R}} \frac{1}{(t-i)^{2}} d \mu(t) & =\int_{\mathbb{R}} \frac{2 t}{\left(t^{2}+1\right)^{2}} d \mu(t) \\
& =\int_{0}^{\infty} \frac{2\left(3 t^{2}-1\right)}{\left(t^{2}+1\right)^{3}}(\mu([0, t])-\mu([-t, 0])) d t  \tag{4.21}\\
& \leqslant \delta \int_{0}^{\infty} \frac{2\left(3 t^{2}-1\right)}{\left(t^{2}+1\right)^{3}} \mu([0, t]) d t \\
& =O(\delta)
\end{align*}
$$

The combination of (4.19)-(4.21) proves (4.14).

## 5. Proof of Theorem 1.4

By virtie of the doubling condition, the map $u: \mathbb{R} \rightarrow \mathbb{R}$ is $s$-quasisymmetric where $s$ is small if $\delta$ is small. Thus we may consider the map $t \mapsto \Gamma(t)$ instead of the projection $\Gamma(t) \mapsto u(t)$.

Fix $a, b \in \mathbb{R}, a<b$. The growth estimate for $\mu$, (4.15), yields

$$
\begin{equation*}
\sup _{[a, b]}\left|u-u_{a, b}\right| \leqslant C(u(b)-u(a)) \tag{5.1}
\end{equation*}
$$

where $C=C(\delta) \rightarrow 0$ as $\delta \rightarrow 0$. On the other hand, the definition of $\Lambda_{\mu}$ implies

$$
\begin{equation*}
\sup _{[a, b]}\left|v-v_{a, b}\right| \leqslant\|v\|_{\Lambda_{\mu}}(u(b)-u(a)) \tag{5.2}
\end{equation*}
$$

When $\delta$ and $\|v\|_{\Lambda_{\mu}}$ are small, Theorem 2.3]implies that $\Gamma$ is $s$-quasisymmetric with small $s$.

Without the smallness condition, we can still conclude from (5.1)-(5.2) that

$$
\begin{equation*}
\left|\Gamma(x)-\Gamma_{a, b}(x)\right| \leqslant K(u(b)-u(a)), \quad x \in[a, b] \tag{5.3}
\end{equation*}
$$

with $K$ independent of $a, b$. We shall demonstrate the existence of a constant $H$ such that

$$
\begin{equation*}
|\Gamma(x)-\Gamma(a)| \leqslant H|\Gamma(x)-\Gamma(b)| \quad \text { whenever }|x-a| \leqslant|x-b| \tag{5.4}
\end{equation*}
$$

The property (5.4) implies the quasisymmetry of $\Gamma$ [20, Theorem 10.19]. We split the proof of (5.4) in two cases. If $a \leqslant x \leqslant b$, then (5.3) yields

$$
|\Gamma(x)-\Gamma(a)| \leqslant \frac{x-a}{b-x}|\Gamma(x)-\Gamma(b)|+K(u(b)-u(a))
$$

Since $|x-a| \leqslant|x-b|$, the doubling condition implies

$$
u(b)-u(a) \leqslant(2+\delta)(u(b)-u(x)),
$$

hence

$$
|\Gamma(x)-\Gamma(a)| \leqslant[1+K(2+\delta)]|\Gamma(x)-\Gamma(b)| .
$$

The other case to consider is $x<a<b$. Now

$$
\left|\Gamma(a)-\Gamma_{x, b}(a)\right| \leqslant K(u(x)-u(b)) \leqslant K|\Gamma(x)-\Gamma(b)|
$$

and

$$
\left|\Gamma(x)-\Gamma_{x, b}(a)\right| \leqslant|\Gamma(x)-\Gamma(b)| .
$$

Hence

$$
|\Gamma(x)-\Gamma(a)| \leqslant(K+1)|\Gamma(x)-\Gamma(b)|
$$

from which (5.4) follows.

## 6. Generalized variation of Zygmund functions

Any function in the Zygmund class $\Lambda_{*}$ has a modulus of continuity of the form $C \delta \log (1 / \delta)$ on every finite interval [36, Theorem II.3.4]. The example $g(x)=x \log x$ demonstrates that this modulus of continuity is best possible. However, at most points the local modulus of continuity can be improved to $C \delta \sqrt{\log (1 / \delta) \log \log (1 / \delta)}$, see [6, Theorem 1]. Such an improvement is also possible on the average, i.e., in terms of generalized variation. This fact may be known, but being unable to find a reference, we give a proof.

Proposition 6.1. Any function of class $\Lambda_{*}$ has locally finite $\Phi_{q}$ variation for every $q>1 / 2$. Here $\Phi_{q}$ is the gauge function from (1.5).

We need a lemma.
Lemma 6.2. [25, Lemma 3.4]. If a function $g:[a, b] \rightarrow \mathbb{R}$ satisfies

$$
\sum_{j=1}^{N}\left|g\left(x_{j}\right)-g\left(x_{j-1}\right)\right| \leqslant C \log ^{p}(N+1)
$$

for any partition $a=x_{0}<\cdots<x_{N}=b$, then $g$ has finite $\Phi_{q}$ variation for every $q>p$.

Proof of Proposition 6.1. Let $g \in \Lambda_{*}$. We claim that there exists a constant $C$ such that for any triple $a<x<b$

$$
\begin{equation*}
\frac{(g(x)-g(a))^{2}}{x-a}+\frac{(g(x)-g(b))^{2}}{b-x} \leqslant \frac{(g(b)-g(a))^{2}}{b-a}+C(b-a) . \tag{6.1}
\end{equation*}
$$

Using the linear interpolant (2.6) we rewrite the left-hand side of (6.1) in terms of the difference $\delta:=g(x)-g_{a b}(x)$ :

$$
\begin{aligned}
\frac{(g(x)-g(a))^{2}}{x-a} & +\frac{(g(x)-g(b))^{2}}{b-x} \\
& =\frac{\delta^{2}}{x-a}+\frac{\delta^{2}}{b-x}+\frac{\left(g_{a b}(x)-g(a)\right)^{2}}{x-a}+\frac{\left(g_{a b}(x)-g(b)\right)^{2}}{b-x} \\
& =\frac{\delta^{2}}{x-a}+\frac{\delta^{2}}{b-x}+\frac{(g(b)-g(a))^{2}}{b-a}
\end{aligned}
$$

It remains to prove that

$$
\begin{equation*}
\frac{\delta^{2}}{\min (x-a, b-x)} \leqslant C(b-a) . \tag{6.2}
\end{equation*}
$$

Recall that $\delta \leqslant C(b-a)$ by (2.7). This immediately implies (6.2) when $(x-a)$ is comparable to $(b-x)$. If $x$ is very close to, say, $a$, then we use the $\log$-Lipschitz estimate $\delta \leqslant C(x-a)|\log (x-a)|$, see [10, Proposition 1]. Thus (6.2) holds in either case.

Repeated application of (6.1) shows that for any partition $x_{0}, \ldots, x_{N}$ of the interval $[a, b]$ we have

$$
\sum_{j=1}^{N} \frac{\left|g\left(x_{j}\right)-g\left(x_{j-1}\right)\right|^{2}}{x_{j}-x_{j-1}} \leqslant C \log (N+1) .
$$

where $C$ is independent of $N$. The Cauchy-Schwarz inequality yields

$$
\sum_{j=1}^{N}\left|g\left(x_{j}\right)-g\left(x_{j-1}\right)\right| \leqslant C \log ^{1 / 2}(N+1),
$$

and Lemma 6.2 completes the proof.
Turning to the generalized Zygmund class $\Lambda_{\mu}$, we immediately find that the modulus of continuity is not log-Lipschitz in general. Indeed, $\Lambda_{\mu}$ always contains an antiderivative of $\mu$. On the other hand, a version of Proposition 6.1 holds in this generality, albeit with a worse exponent.

Proposition 6.3. Let $\mu$ be a nonatomic Radon measure on $\mathbb{R}$. Any function of class $\Lambda_{\mu}$ has locally finite $\Phi_{q}$ variation for every $q>1$.

Proof. Let $g \in \Lambda_{\mu}$. We claim that there exists a constant $C$ such that for any triple $a<x<b$

$$
\begin{equation*}
|g(x)-g(a)|+|g(x)-g(b)| \leqslant|g(a)-g(b)|+C \mu([a, b]) \tag{6.3}
\end{equation*}
$$

Indeed, in terms of the linear interpolant (2.6) we have

$$
\begin{aligned}
|g(x)-g(a)| & +|g(x)-g(b)| \\
& \leqslant\left|g_{a b}(x)-g(a)\right|+\left|g_{a b}(x)-g(b)\right|+2\left|g(x)-g_{a b}(x)\right| \\
& =|g(a)-g(b)|+2\left|g(x)-g_{a b}(x)\right|
\end{aligned}
$$

where the last term is controlled by $\mu([a, b])$ by the definition of $\Lambda_{\mu}$.
Consider a partition $a=x_{0}<\cdots<x_{N}=b$ where $N=2^{m}$. Applying (6.3) to the triples like $x_{0}, x_{1}, x_{2}$, we obtain

$$
\sum_{j=1}^{2^{m}}\left|g\left(x_{j}\right)-g\left(x_{j-1}\right)\right| \leqslant C \mu([a, b])+\sum_{j=1}^{2^{m-1}}\left|g\left(x_{j}\right)-g\left(x_{j-1}\right)\right|
$$

After $m$ iterations of this process the estimate becomes

$$
\sum_{j=1}^{2^{m}}\left|g\left(x_{j}\right)-g\left(x_{j-1}\right)\right| \leqslant C m \mu([a, b])+|g(a)-g(b)|
$$

Thus, for any $N$ point partition of $[a, b]$ we have the estimate

$$
\begin{equation*}
\sum_{j=1}^{N}\left|g\left(x_{j}\right)-g\left(x_{j-1}\right)\right| \leqslant C \log (N+1) \tag{6.4}
\end{equation*}
$$

where $C$ is independent of $N$. An application of Lemma 6.2 completes the proof.

In the next section we prove that Proposition 6.3 is essentially sharp, even if the measure $\mu$ is assumed to be doubling with a small constant.

## 7. Infinite generalized variation

The principal result of this section concerns the class $\Lambda_{\mu}$ for singular measures $\mu$.

Theorem 7.1. Let $\delta>0$. There exists a Radon measure $\mu$ on $\mathbb{R}$ with the doubling property (2.3) such that the class $\Lambda_{\mu}$ contains a function which has infinite $\Phi_{q}$-variation on $[a, b]$ for any $0<q<1$ and any $a<b$.

Together with previous results this quickly yields Theorem 1.5.

Proof of Theorem 1.5. We use the function $v \in \Lambda_{\mu}$ provided by Theorem[7.1, scaling it down to make the $\Lambda_{\mu}$ seminorm of $v$ as small as needed for Theorem [1.4. Then use Theorem 1.3 to produce the desired reduced quasiconformal map.

Proof of Theorem [7.1. Consider 4-adic intervals

$$
I_{n, j}=\left\{x: 0 \leqslant 4^{n} x-j<1\right\}=\left[\frac{j}{4^{n}}, \frac{j+1}{4^{n}}\right), \quad n=1,2, \ldots, j \in \mathbb{Z}
$$

and define, for $n \geqslant 1$, the Rademacher-type functions

$$
\rho_{n}(x)=\left\{\begin{array}{lll}
0, & x \in I_{n, j}, & j \equiv 0,3 \bmod 4 \\
1, & x \in I_{n, j}, & j \equiv 1 \quad \bmod 4 \\
-1, & x \in I_{n, j}, & j \equiv 2 \bmod 4
\end{array}\right.
$$

For future references we record several properties of the family $\left\{\rho_{n}\right\}$.
(i) $\rho_{n}$ is constant on $I_{m, j}$ when $m \geqslant n$;
(ii) $\rho_{n}$ has zero mean on $I_{m, j}$ when $m<n$.
(iii) the set of discontinuities of $\rho_{n}$ is $\left\{j 4^{-n}: n \geqslant 1,4 \nmid j\right\}$;
(iv) if $\rho_{n}$ is discontinuous at $x$, then $\rho_{m}(y)=0$ whenever $m>n$ and $|x-y|<4^{-m} ;$
(v) the antiderivative $R_{n}(x):=\int_{0}^{x} \rho_{n}(t) d t$ is $4^{1-n}$-periodic and $\left|R_{n}\right| \leqslant$ $4^{-n}$;
(vi) the product $R_{n} \rho_{m}$ is continuous on $\mathbb{R}$ provided that $m<n$;
(vii) if $\Psi$ is a function of $\rho_{1}, \ldots, \rho_{n-1}, \rho_{n+1}, \ldots \rho_{m}$, then

$$
\int_{0}^{1} \Psi(x) d x=4 \int_{[0,1] \cap\left\{\rho_{n}=1\right\}} \Psi(x) d x .
$$

(viii) Under the assumptions of (viii), $\int_{0}^{1} \rho_{n}(x) \Psi(x) d x=0$.

Fix a number $\gamma \in(0,1)$ and define for $n \geqslant 1$

$$
v_{n}(x)=\prod_{k=1}^{n}\left(1+\gamma \rho_{2 k-1}(x)\right)
$$

The measures $v_{n}(x) d x$ have a weak* limit, denoted $\mu$. It is routine to check that $\mu$ satisfies the doubling condition (2.3) where $\delta \rightarrow 0$ as $\gamma \rightarrow 0$. Indeed, the weights $v_{n}$ are doubling with a uniformly controlled constant, and $\mu(I)$ can be compared to $\int_{I} v_{n}$ as long as the length of $I$ is comparable to $4^{-2 n}$. See [33].

Let us introduce

$$
\begin{equation*}
g(x)=\sum_{n=1}^{\infty} R_{2 n}(x) v_{n}(x) \tag{7.1}
\end{equation*}
$$

where $R_{2 n}$ is the antiderivative of $\rho_{2 n}$. Each summand is continuous by virtue of (vil). The property (v) ensures that the series converges uniformly and at an exponential rate.

Step 1: $g \in \Lambda_{\mu}$. For this we will show that (2.7) holds for all $a, b \in \mathbb{R}$ such that $a<b$. Since $g$ is bounded, it suffices to consider the case $b-a<1 / 16$. Let $m$ be the greatest integer such that

$$
\begin{equation*}
b-a<4^{-2 m} . \tag{7.2}
\end{equation*}
$$

By virtue of ( ( $\mathbf{v}$ ) the difference between $g$ and the partial sum

$$
g_{m}(x)=\sum_{n=1}^{m} R_{2 n}(x) v_{n}(x)
$$

on the interval $[a, b]$ does not exceed

$$
\left(\sup _{[a, b]} v_{m}\right) \sum_{n>m} 4^{-2 n}(1+\gamma)^{n-m} \leqslant C 4^{-2 m} \sup _{[a, b]} v_{m} \leqslant C \mu([a, b]) .
$$

Therefore, it suffices to prove the desired property (2.7) for $g_{m}$. Differentiation of $g_{m}$ yields

$$
\begin{equation*}
g_{m}^{\prime}(x)=\sum_{n=1}^{m} \rho_{2 n}(x) v_{n}(x) \tag{7.3}
\end{equation*}
$$

because $v_{n}$ is locally constant on the support of $R_{2 n}$. If $g_{m}^{\prime}$ is constant on $[a, b]$ then we are done. Suppose otherwise. By virtue of (iiii) the set of discontinuities of $g_{m}^{\prime}$ is a subset of $\left\{j 4^{-2 n}: 1 \leqslant n \leqslant m, 4 \nmid j\right\}$. Therefore $g_{m}^{\prime}$ has exactly one point of discontinuity on $[a, b]$, say $\theta=\ell \cdot 4^{-2 r}, 4 \nmid \ell$. The oscillation of $g_{m}^{\prime}$ at this point is at most $2 v_{r}(\theta)$. The property (iv) implies that $v_{m}(x) \equiv v_{r}(\theta)$ for $x \in[a, b]$. Hence, the deviation of $g_{m}$ from an affine function on the interval $[a, b]$ does not exceed

$$
2 v_{r}(\theta)(b-a)=2 \int_{a}^{b} v_{m}(x) \leqslant C \mu([a, b])
$$

as desired.
Step 2: the variation of $g$. Fix $0<q<1$. We must show that $g$ has infinite $\Phi_{q}$-variation on every 4 -adic interval. It suffices to consider the
interval $[0,1]$. Note that $g$ coincides with the partial sum $g_{m}$ at all points of the form $j 4^{-2 m}, j \in \mathbb{Z}$. Hence

$$
\begin{equation*}
\sum_{j=1}^{4^{2 m}}\left|g\left(j 4^{-2 m}\right)-g\left((j-1) 4^{-2 m}\right)\right| \geqslant \int_{0}^{1}\left|g_{m}^{\prime}(x)\right| d x \tag{7.4}
\end{equation*}
$$

Let $v_{m}^{*}=\max \left(v_{1}, \ldots, v_{m}\right)$. For $\lambda>0$ and $k=1, \ldots, m$ define

$$
E_{k}(\lambda)=\left\{x \in[0,1]: v_{k}(x)=v_{m}^{*}(x)=\lambda, v_{n}(x)<\lambda \text { for } n<k\right\}
$$

By definition, the sets $E_{k}(\lambda)$ from a finite partition of the interval $[0,1]$. We claim that

$$
\begin{equation*}
\int_{E_{k}(\lambda)}\left|g_{m}^{\prime}(x)\right| d x \geqslant \frac{\lambda}{4}\left|E_{k}(\lambda)\right| \tag{7.5}
\end{equation*}
$$

where $|\cdot|$ denotes the Lebesgue measure. To this end, restrict the set of integration to $E^{\prime}=E_{k}(\lambda) \cap\left\{\rho_{2 k}=1\right\}$. The property (vii) implies $\left|E^{\prime}\right|=$ $1 / 4\left|E_{k}(\lambda)\right|$. According to (viii),

$$
\int_{E^{\prime}} \rho_{2 n} v_{n}= \begin{cases}\lambda\left|E^{\prime}\right| & \text { if } n=k \\ 0 & \text { otherwise }\end{cases}
$$

From (7.3) we obtain

$$
\int_{E^{\prime}}\left|g_{m}^{\prime}(x)\right| d x \geqslant \int_{E^{\prime}} g_{m}^{\prime}(x) d x=\lambda\left|E^{\prime}\right|=\frac{\lambda}{4}\left|E_{k}(\lambda)\right|
$$

which proves (7.5).
Summing (7.5) over all $k=1, \ldots, m$ and all $\lambda>0$ yields

$$
\begin{equation*}
\int_{0}^{1}\left|g_{m}^{\prime}(x)\right| d x \geqslant \frac{1}{4} \int_{0}^{1} v_{m}^{*}(x) d x \tag{7.6}
\end{equation*}
$$

We need a lemma, the proof of which is postponed to the end of this section.
Lemma 7.2. There exists a positive constant $c>0$ such that

$$
\begin{equation*}
\int_{0}^{1} v_{m}^{*}(x) d x \geqslant c m, \quad m=1,2, \ldots \tag{7.7}
\end{equation*}
$$

From (7.4), (7.6) and (7.7) it follows that

$$
\sum_{j=1}^{4^{2 m}}\left|g\left(j 4^{-2 m}\right)-g\left((j-1) 4^{-2 m}\right)\right| \geqslant c m, \quad m=1,2, \ldots
$$

Jensen's inequality yields

$$
\sum_{j=1}^{4^{2 m}} \Phi_{q}\left(\left|g\left(j 4^{-2 m}\right)-g\left((j-1) 4^{-2 m}\right)\right|\right) \geqslant 4^{2 m} \Phi_{q}\left(\frac{c m}{4^{2 m}}\right) \sim m^{1-q} \rightarrow \infty
$$

as $m \rightarrow \infty$.

Proof of Lemma 7.2. Introduce the random variables

$$
X_{k}=\log \left(1+\gamma \rho_{k}\right)-\frac{1}{4} \log \left(1-\gamma^{2}\right)
$$

with $[0,1]$ being the probability space. Since $X_{k}$ are independent, identically distributed, and have zero mean, the large deviation bound (Bernstein's inequality [18, Theorem 5.11.4]) yields

$$
\begin{equation*}
\mathbf{P}\left\{\sum_{k=1}^{m} X_{2 k-1}>\log \frac{1}{4}-\frac{m}{4} \log \left(1-\gamma^{2}\right)\right\} \leqslant e^{-c m} \tag{7.8}
\end{equation*}
$$

where $c>0$ depends only on $\gamma$. An equivalent form of (7.8) is

$$
\begin{equation*}
\left|\left\{x \in[0,1]: v_{m} \geqslant 1 / 4\right\}\right| \leqslant e^{-c m} . \tag{7.9}
\end{equation*}
$$

For $\lambda \geqslant 1$ let $A(\lambda)=\left\{x \in[0,1]: v_{m}(x) \geqslant \lambda\right\}$. The estimate (7.9) yields

$$
\begin{equation*}
\int_{[0,1] \backslash A(\lambda)} v_{m} \leqslant \frac{1}{4}+\lambda e^{-c m} . \tag{7.10}
\end{equation*}
$$

The right-hand side of (7.10) is less than $1 / 2$ provided that $\lambda \leqslant \frac{1}{4} e^{c m}$. Hence

$$
\begin{equation*}
\int_{A(\lambda)} v_{m} \geqslant \frac{1}{2}, \quad 1 \leqslant \lambda \leqslant \frac{1}{4} e^{c m} . \tag{7.11}
\end{equation*}
$$

Recall a lower bound for maximal function [31, p. 32]

$$
\begin{equation*}
\left|\left\{x \in[0,1]: v_{m}^{*}(x) \geqslant c_{1} \lambda\right\}\right| \geqslant \frac{c_{2}}{\lambda} \int_{A(\lambda)} v_{m} \tag{7.12}
\end{equation*}
$$

with universal constants $c_{1}, c_{2}>0$. Integrating (7.12) with respect to $\lambda$ and using (7.11), we arrive at (7.7).

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