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A Problem Solving Environment for Network Computing*

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*A chapter in Problem Solving Environments book,
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Abstract

The current advances in high-speed networks and WWW technologies have made network computing a cost-effective high performance computing environment. New software development models and problem solving environments must be developed to utilize the network computing environment efficiently. In this paper we present Virtual Distributed Computing Environment (VDCE), which provides a problem solving environment for high-performance distributed computing over wide-area networks. VDCE enables scientists to develop distributed applications without knowing the detailed architecture of the underlying resources. VDCE provides well-defined library functions that relieve end users from tedious task implementations and it supports software reusability. The VDCE software architecture consists of two modules: Application Editor, and VDCE Runtime System. Application Editor is a Web-based graphical user interface that helps user to develop network applications and specifies the computing and communication properties of each task within the applications. The VDCE Runtime System schedules the individual tasks of the application to the best available resources, runs, and manages the application execution on the assigned resources. We also present how VDCE can be used as a problem solving environment and how the users can experiment and evaluate the performance of their applications for different VDCE hardware and/or software configurations.

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1 Introduction

The current advances in networking protocols (including ATM and Fast Ethernet), software development tools, and emerging WWW technologies have enabled the development of a cost-effective, high-performance distributed computing environment, *network-based computing* [1]. The network-based computing (or network computing (NC)) environment can provide the computational and storage requirements for solving large scale applications that used to run only on massively parallel processors and supercomputers.

The available software tools for an high-performance computing environment still requires detailed understanding of the underlying architecture and the components of the application. Writing a parallel/distributed program overwhelms most of the users due to the complexity of communication and synchronization issues. Therefore, over the last few years, a number of application development and representing tools have become available to relieve users from this tedious process, including Code [2], HeNCE [3], and Zoom [3, 4], which are all graph-based programming environments. The graph representation of parallel programming simplifies programming, debugging, and visualization phases. However, most of these tools do not provide users the ability to experiment and evaluate the parallel/distributed programs with different underlying software and hardware components.

There is a growing interest to combine the computational and storage resources that are available over the Internet or over high speed networks (i.e VBNS, NYNET testbed) which provides a new computing environment, called *metacomputing*. In this paper, we present an overview of the Virtual Distributed Computing Environment (VDCE), a meta-computing environment that is currently being developed at Syracuse University. We also present how VDCE can be used as a problem solving environment for large scale network applications. Our problem solving environment enables users to focus on the solution approach to the problem rather than worrying about the parallel/distributed computing and network implementation issues.

The software architecture of the VDCE problem solving environment has a web-based graphical user interface, called *Application Editor*, to develop parallel/distributed network applications and evaluate the application performance for the different combinations of hardware/software tools. The Application Editor provides menu-driven functional building blocks of task libraries for building high performance distributed computing applications. VDCE Application Editor provides a large set of task libraries grouped in terms of their functionality, such as matrix algebra library, C^3I (command and control applications) library. By providing these functional building blocks, VDCE addresses the reusability issue of the problem solving environments. The visualization capability to show the performance for different hardware/software configurations is another important feature of the Application Editor.

Once the application is designed/developed using the Application Editor, VDCE Runtime System is invoked to schedule, to run and to manage the execution of the application in a transparent manner. The VDCE Runtime System is responsible for task-to-resource

mapping, monitoring the VDCE resources, setting up the execution environment for a given application, monitoring the execution of the application tasks on the assigned computers, and maintaining the performance, fault tolerance, and quality of service (QoS) requirements.

The rest of the paper is organized as follows. Section 2 introduces the issues of software development process for network-based computing and related work. In Section 3, we present an overview of VDCE and its applicability as a problem solving environment. In Section 4, we demonstrate through several examples how VDCE can be used to easily develop distributed applications as well as experiment and evaluate their performance. Concluding remarks are given in Section 5.

2 Software Development Issues and Stages

Software development in any high performance (parallel/distributed) computing environment is a non-trivial process and requires a through understanding of the application and the underlying computer architecture [10]. The software development process is described as a set of stages which correspond to the phases encountered by a developer. Each stage requires different kinds of supports, such as portable application description/design support, program implementation and run-time support, visualization support and reusability support. The stages in the process, which forms a development pipeline, are: *Application Design and Specification Stage*, *Application Configuration and Scheduling Stage*, *Application Execution and Runtime Stage*.

2.1 Application Design and Specification Stage.

The software development process considers two types of application development.

- *“New” Application Development*: This class of applications involves solving new problems that require developers to start from scratch using a textual description of the problem or some means of formal and/or informal application specifications techniques.
- *Porting of Existing Applications (Dusty-Decks)*: This class includes developers attempting to port and update the existing codes written.

In this stage, the application is specified (represented) in the form of a functional flow description of the application and its computation and communications requirements. Each node (termed as functional module) in the functional flow diagram is a black-box and contains information about (1) its input(s), (2) the function to be performed, (3) the desired output(s) and (4) the requirements at each node. The output of this stage is a detailed process flow graph where the nodes represent the functional components and the edges represent interdependencies.

Designing and implementing parallel/distributed programs overwhelms most users due to the difficulty of expressing communication and synchronization among the computations [5]. Some text-based parallel programming environments support the data parallel paradigm, which requires advanced compilation techniques and compilers. Most of the other environments require explicit insertion of communication and synchronization primitives within the programs, which makes parallel programs difficult to understand.

However, a graph-based programming environment provides simple and easy-to-use mechanisms for expressing the interaction of multiple threads within a parallel program [5]. In a graph-based programming environment (or graph-based application development tool), a program is defined as a directed graph where nodes denote computations and links denote communication and synchronization between nodes [6]. The graph representation of parallel programming simplifies programming, debugging, and visualization phases. Over the last few years a number of graph-based application development and representation tools have become available, including Code [2], HeNCE [3], and Zoom [3, 4]. However, most of these tools do not provide users the ability to experiment and evaluate the generated parallel/distributed programs with different underlying software and hardware components, different implementation techniques, interconnection networks and message-passing tools.

On the other hand, application development tools and environments supports web-based user interfaces; since World Wide Web is becoming a low-cost standard interface mechanism [7] to access the computational resources that are distributed all over the world. The Application Editor module of VDCE (which is explained in Section 3.) is a web-based graphical user interface for designing/specifying parallel and distributed applications. It provides a menu-driven functional building blocks of task libraries, which addresses the reusability issue of the software development process.

2.2 Application Configuration and Scheduling Stage

The application development stage receives the application specifications (in terms of application flow graph or another specification syntax). This stage determines the hardware and software requirements of the application by interpreting the application specifications and assigns current best available resources for running the application tasks in order to minimize the total execution time. This stage includes mapping module and estimation module.

The mapping module has two consecutive parts according to its hierarchy: domain-mapping part, resource-mapping part. The information provided by application design and development stage is used to map the functional components of the application to the domain by domain-mapping part and specifically appropriate computing elements (or processors) by resource-mapping part. Both parts of this module use estimation module to get feedback for selecting between the existing candidates.

Estimation Module is a critical component of the application development stage. This module evaluates different options available and identifies the option that provides the best

performance. Estimation Module receives information about the hardware configuration, application flow information/requirements and the possible mappings. Then it estimates the performance of each mapping scheme and identifies the one which gives the best performance.

Since the general form of scheduling problem is NP-hard, researchers have been working on near-optimal scheduling decisions. The research in this area has produced many different types of scheduling algorithms (i.e, static, dynamic, centralized, distributed, etc.). Most of these algorithms are not general; instead they are targeted for specific application and specific resource types. There are some research projects that target application-level resource allocation issues such as APPLoS [9], and MARS [8] projects.

VDCE provides application-based scheduling algorithm that runs on VDCE Server at each site. The required parameters of scheduling include task-specific, resource-specific, and user-specific parameters, which are stored in the site repositories. The task scheduling approach is based on developing efficient techniques to predict the performance of each task execution on each existing VDCE computing resource. Furthermore, our resource allocation approach is efficient, since it uses a combination of performance analysis and measurement and benchmarking techniques to estimate the execution time of a task running on any VDCE computing platform under network contention and varying load conditions.

2.3 Application Execution and Run-Time Stage.

This stage handles the task of executing the developed and configured application and produce the required output. The runtime stage integrates the assigned resources that will be involve in execution, and supports inter-module communications, which is based on either a message-passing tool such as PVM, p4, MPI, NCS or a distributed shared memory (DSM). During the execution of the application, this stage accepts data from different computing elements and combines them for proper visualization. It intercepts the error messages generated and provides proper interpretation. The runtime system handles dynamic load-balancing, application and resource-level fault tolerance capabilities.

Most of these functionalities are provided by VDCE Runtime System, which is the kernel of our problem solving environment. VDCE Runtime System is explained in Section 3. VDCE allows an end user to experiment and evaluate his/her application for the different combinations of hardware and software medium. VDCE gives user the ability to select any message passing tool (NCS, P4, PVM, etc) and to select the types of network (Ethernet, ATM etc) to connect the computing resources.

3 Overview of VDCE

The objective of the Virtual Distributed Computing Environment is to provide a general software development environment to design and construct large scale HPDC applications

on a network of heterogeneous computers. As a problem-solving environment, VDCE provides users with a set of task libraries to solve one class of applications. These task libraries can be used to compose any HPDC application as an application flow graph. VDCE is composed of geographically distributed computation sites, each of which runs its own VDCE Server. An end user views the underlying VDCE resources, interconnected by a global wide area network, as a single seamless computation resource (see Figure 1).

The VDCE Server functions as a site manager that bridges the other components to the Web-based repository. VDCE-based resource information within the site such as site resource configuration, user information, application development data, and application run-time information are stored in the repository. VDCE Server implementation is based on JAVA Web Server technology.

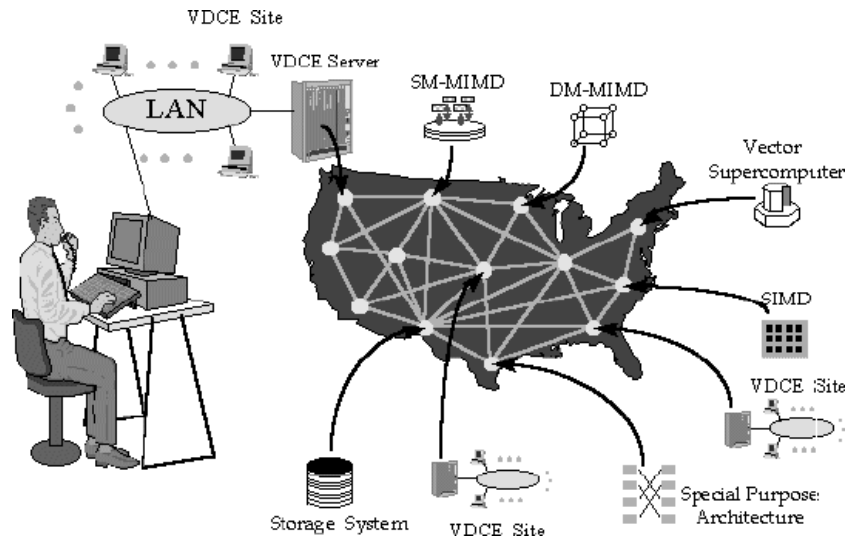


Figure 1: An example of a Virtual Distributed Computing Environment (VDCE)

Site repository, the web-based storage environment within a VDCE site, consists of four different databases. *User-info database* is used to handle the user authentication. In user-account database, each VDCE user account is represented with a 5-tuple: user name, password, user ID, priority, access domain type. The *resource-performance database* provides the resource (machine and network) attributes/parameters. These attributes are grouped into two parts: a) *static attributes* that are stored in the database once (i.e host name, IP address, Architecture type, OS type, total memory size); and b) *dynamic attributes* that are updated periodically, such as recent load measurement, and available memory. In order to find locations of task's executables, VDCE stores location information of each task (i.e the absolute path of the task executable) for each host in the *task-constraints database*. Due to specific library requirements some task executables may reside only on some of the hosts. The *task-performance database* provides performance characteristics for each task available in the system. Each task implementation is specified

by several parameters, i.e, computation size, communication size, required memory size etc.

The software development cycle for network applications can be viewed in terms of three phases: application design and development phase, application configuration and scheduling phase, and application execution and runtime phase. VDCE Application Editor module within a site provides the required functionality of the first phase. Application Editor is a Web-based graphical user interface that helps user to develop network application and specifies the computing and communication properties of each task within the application. The Application Editor generates its output as an application flow graph (AFG). The second phase, handles the scheduling of each component (i.e task) of the network application to the best available resource; and application execution/runtime phase starts, runs and manages the application execution on the assigned machines. VDCE Runtime System provides all the functions of the last two phases; i.e interpreting the generated AFG and assigning the current best available resources for running the tasks, setting up an execution environment for each submitted task, managing the execution to meet successfully the requirements of the application. In what follows we describe the VDCE components (Application Editor and VDCE Runtime System) in more detail.

3.1 Application Editor

The Application Editor is implemented in the JAVA programming language and integrated with web-browsers. To develop an application, the end user establishes a URL connection to the VDCE Server within the site. After user authentication, the Application Editor will be loaded into the user's local web browser, so that, user can develop his/her network application.

In Application Editor, tasks are grouped into domain libraries. A selected task is represented as a clickable and draggable graphical icon in the active editor area. Each such icon includes the task name and a set of markers for logical ports. Color coding used in this visual representation helps to distinguish input ports from output ports. Operationally, the Application Editor can be in the *task mode*, *link mode*, or *run mode*. In the *task mode*, the user can select-and-add new tasks, and/or click-and-drag icons to position them conveniently in the active editor area. In the *link mode*, the user can specify connections between tasks. In the *run mode*, Editor submits the graph for the execution and visualizes performance and runtime characteristics of an ongoing computation.

The process of building a network application with the Application Editor can be grouped into two steps: building the application flow graph (AFG), and specifying the task properties of the application. Figure 2 shows the building of application flow graph of a Linear Equation Solver with the help of Application Editor. The nodes of this application, i.e, LU decomposition, matrix inversion, matrix multiplication etc., are selected from matrix operations menu and linked to form the application flow graph, as shown in Figure 2. After the application flow graph is generated, the next step in the application

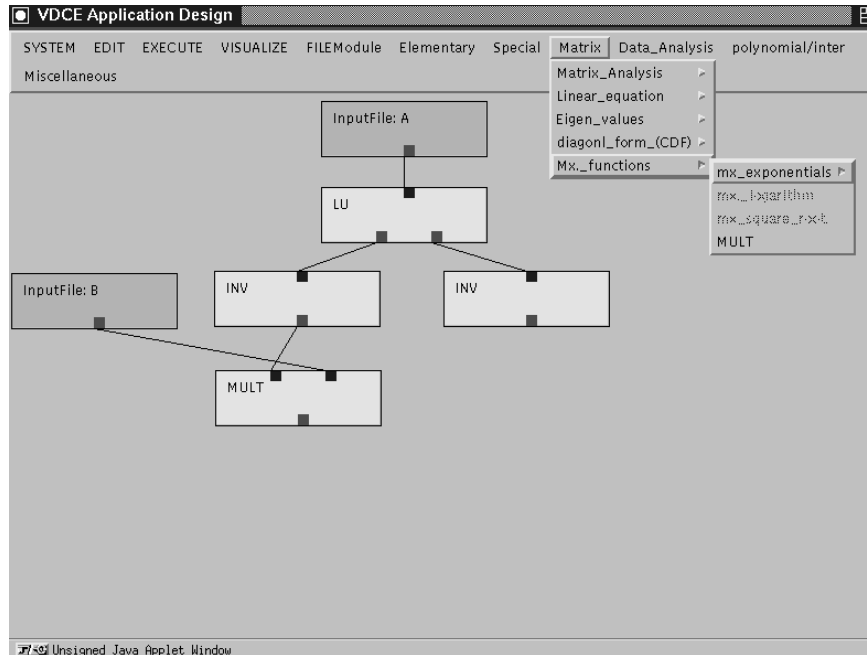


Figure 2: Building Application Flow Graph of Linear Equation Solver Application

development process is to specify the properties of each task. A double click on the task icon generates a popup panel that allows the user to specify (optional) preferences such as computational mode (sequential or parallel), machine type, and the number of processors to be used in a parallel implementation of a given task (see Figure 3). In this figure, for the LU Decomposition task of Linear Equation Solver, the user has selected parallel execution mode using 2 nodes of Solaris machines interconnected by an ATM network.

Apart from the application development process, Application Editor provides different visualization supports that are grouped as:

- **Module/Application Visualization:** The performance (i.e, the execution time) of any individual task or an overall application is shown as a post-mortem visualization. Application visualization includes the visualization of all tasks within the application.
- **Workload Visualization:** Up-to-date load information on the resources (machines and networks) can be visualized.
- **Comparative Visualization:** VDCE provides an end user to experiment and evaluate his/her application for different combinations of hardware and software medium. VDCE gives the ability to select any message passing tool (NCS, P4, PVM, etc) on any network type (Ethernet, ATM etc) for the execution of the application. These alternatives are given in the task properties window/panel of the Application Editor. For the comparative visualization case, performance data is shown for all hardware/software alternatives provided by VDCE.

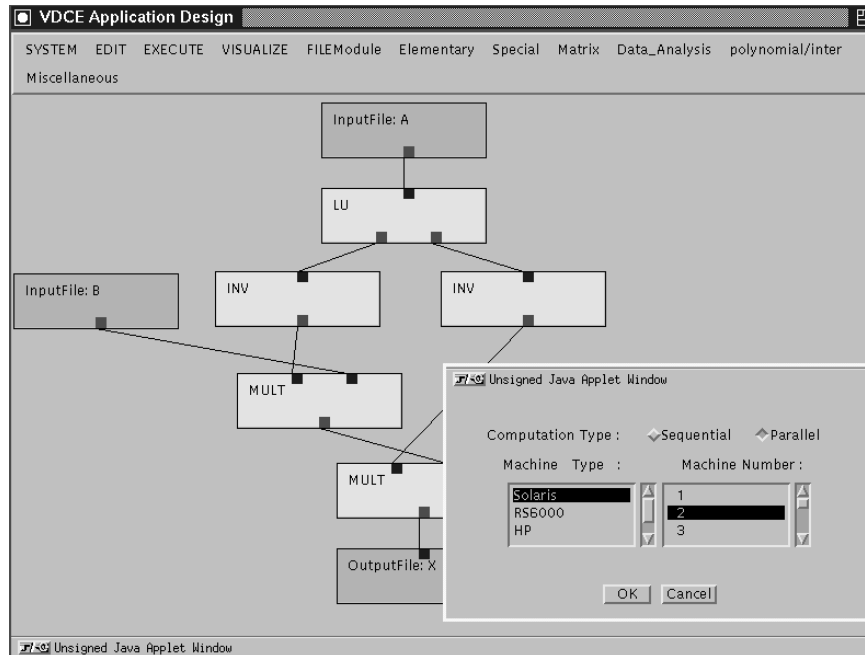


Figure 3: Snapshot of the Application Editor while Specifying Task Properties

3.2 VDCE Runtime System

The functionalities of VDCE Runtime System, which is the kernel of our problem solving environment, can be viewed in terms of two machines: Control Virtual Machine (CVM) and Data Virtual Machine (DVM). *Control Virtual Machine* is responsible for scheduling the application, monitoring and managing the execution of the application on assigned VDCE resources. CVM handles the load measurement of resources (hosts and networks) and periodically updates the *resource-performance database*. CVM supports real-time and post-mortem visualization of the application execution.

Data Virtual Machine provides an execution environment for a given VDCE application by binding tasks so that they can interact and communicate efficiently. DVM supports a socket-based point-to-point inter-task communication system. DVM Kernel sets up dynamic execution environment depending on the service requirements of the application and manages the application execution to meet its requirements.

3.2.1 Control Virtual Machine

The functionalities of CVM process can be group into two servers, according to where it is located: Site CVM (S_CVM) and Local CVM (L_CVM).

Site CVM (S_CVM) . S_CVM is located at the VDCE Server. The S_CVM daemon manages the execution of three processes: scheduler process, database manager process, and visualization process.

- **Scheduler Process.** After the Application Flow Graph (AFG) is generated by the Application Editor, it is sent to the VDCE Server. The VDCE Server saves the AFG and activates the scheduler process. The scheduler process interprets the AFG and assigns the current best available resources for running the application tasks in order to minimize the total execution time. The scheduling algorithm computes the predicted execution time of each task and selects the best available machine within the site. The schedule decision is based on software and hardware requirements of the application, locations and configurations of the resources, up-to-date machine/network loads. The execution of the scheduling algorithm is completed by generating resource allocation information in terms of two forms: Application Configuration Table (ACT) and Channel Information Table (CIT).

The Application Configuration Table (ACT) includes resource allocation information of each task of the application. Each task entity includes assigned machine information, i.e., hostname, IP address, architecture type, OS type, thread type, communication protocol type. For the parallel execution of a task, CIT is used to generate the hostfiles (for PVM applications) or procgroup files (for P4 applications) dynamically. A Host file (or a procgroup file) lists the name, address and communication state for each host. Channel Information Table (CIT) is used to establish the socket connections among the individual tasks of an application. Each link in the Application Flow Graph has a related entity in the CIT. If a task T_i is linked to the task T_j , its CIT entity includes related information (i.e, task number, machine IP address, port number, socket) for both source task, T_i , and the destination task, T_j .

- **Database Manager Process** The database manager process handles user-specific, task-specific and resource-specific data-retrieval requests from the site repository from VDCE components. The monitored load data are updated periodically at the repository, by the monitor threads located on each machine. Database manager periodically assigns a positive random number to the *alive* field of VDCE Server. When the monitor thread of any machine updates machine's load measurement, it retrieves server-generated number and updates current machines *alive* field with this number. At the next random-number update phase, database manager thread checks *alive* fields; i.e. at this point, if a machine's alive field is different than VDCE Server's alive field, it is thought as crashed and its field is set to -1 (dead).
- **Visualization Process** The visualization process collects the visualization data from client machines and shows the results on user screen by Application Editor. VDCE supports both post-mortem visualization (i.e after the execution is completed) and real-time visualization. VDCE provides application/module visualization, workload visualization and comparative visualization, which were explained at the previous section.

Local CVM (L_CVM) After the resource allocation tables (ACT and CIT) are generated by scheduler process of S_CVM, VDCE Server parses the ACT and multicasts a signal

to the L_CVM of the machines that will be involved in the execution. Each activated L_CVM invokes a *DVM proxy*, which sets up the application execution environment on the machine. DVM proxy manages DVM activities that provides the requested service functions and the execution environment. In addition to DVM proxy, L_CVM manages the execution of a) *monitor thread*, which periodically measures the up_to_date processor parameters, i.e, CPU load and memory availability, and updates the site repository, b) *visualization thread*, which periodically sends the visualization data to the S_CVM after the task execution starts. For the other machines that will not be involved in the application execution, the only active L_CVM process will be the monitor thread.

3.3 Data Virtual Machine

DVM Kernel sets up the dynamic execution environment and provides specific services shown in Figure 4. The requested services are selected by the user during the application development phase with specifying the appropriate parameters. To provide these services, DVM Kernel has interaction with the CVM and Application Editor. Table 1 shows the supported methods for each VDCE kernel service type.

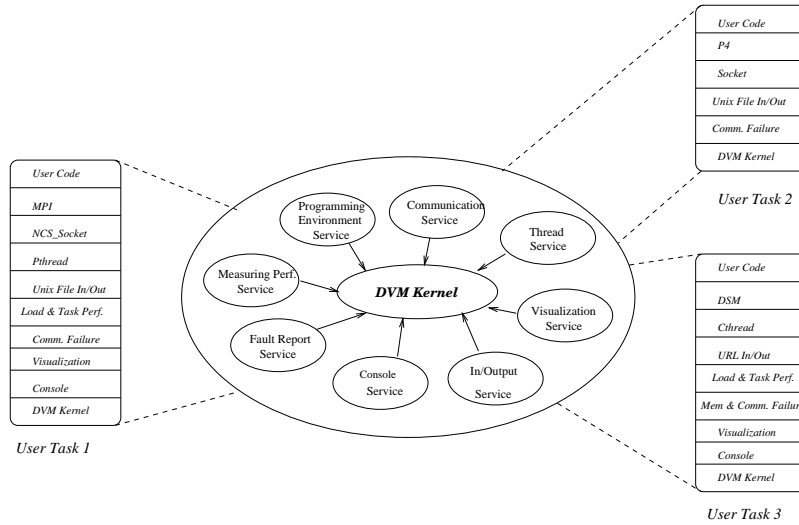


Figure 4: VDCE Runtime Service

At each participating machine, L_CVM activates a copy of the DVM Kernel, called Control DVM (*C_DVM*). *C_DVM* manages the communication interface between LCVM and user task. The communication channel number and the task ID (name) is provided to the *C_DVM*. In Figure 5.a, the channel number is 5000 and task ID is LU (LU Decomposition). After the connection is established, *CDVM* activates the user task (in our example LU) and user task reports results and errors to L_CVM through *C_DVM*.

After setting up communication channel between L_CVM and DVM, L_CVM sends Channel information Table(CIT) to DVM task through *C_DVM*. DVM task sends an acknowledgment signal to L_CVM through *C_DVM*. Server CVM waits all acknowledgments from DVM tasks which

Table 1: VDCE Kernel Services

VDCE Kernel Services	
Service Type	Supported Methods
Program Environment Service	Message-Passing(p4,PVM,MPI,NCS), DSM
Communication Service	NCS-ATM, NCS-socket, NEXUS
Thread Service	Pthread, Qthread, Cthread
I/O Service	File I/O, URL I/O
Performance Service	Execution Time, User-defined Measurements
Fault Report Service	Socket Conn., Data Transmission, Resource Allocation
Visualization Service	Real-time Visualization, Post-mortem Visualization
Console Service	Suspend Execution, Restart Execution

are participating of an application execution. After Server CVM collects all acknowledgments, it sends a task activation message to all participating tasks to start the task executions. Figure 5b shows the required steps of the task initialization.

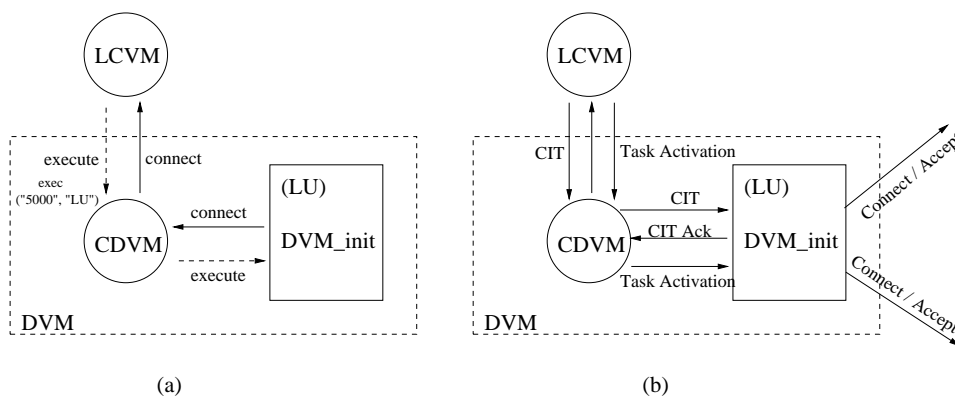


Figure 5: a.Setup the Execution Environment b.Initialize the Task Execution

The socket-based inter-task communication is handled using *VDCE_send*, *VDCE_rcv* calls. After a data communication path is established, source task sends the data with *VDCE_send* call, and target task receives it with *VDCE_rcv* call. After the *VDCE_send* call is completed without any error, the send message is written to a specific directory (in current prototype, the directory is tmp). The message copy can be used by VDCE to support fault (recovery) service. After the destination task receives (with *VDCE_rcv* call) the message successfully, it reports the received data size to its LCVM via CDVM.

4 VDCE-based Application Design and Development

As mentioned earlier in this paper, VDCE problem solving environment provides a large set of task libraries to solve applications in different domains, such as C^3I (command, control, communication, and information) applications and matrix algebra applications. In order to solve a

problem in VDCE, the user builds the application flow graph (AFG) with the Application Editor and specifies the module/task properties of the application. During this process, menu-driven functional building blocks of task libraries is used to generate the application flow graph. In what follows we will present in more detail how VDCE can be used as a problem solving environment for C^3I and matrix algebra applications.

C^3I Applications An end user can integrate large scale Command and Control systems from the provided set of independent, specialized functions given in the C^3I library menu of the Application Editor. We received a suite of such functions from the Parallel C^3I Benchmarking Project at Rome Laboratory. The VDCE C^3I library menu includes the following tasks:

- Terrain Masking - This function generates evasive low visibility terrain domains with respect to a set of threats.
- Plot-Track Assignment - It computes track continuation by matching sensor measurements at time $t+1$ with the current set of tracks reconstructed at time t .
- Hypothesis Testing - It generates and tests the track initiation hypothesis given the sensor measurements in a set of time frames.
- Route Optimization - This function finds the minimal risk terrain routes from the base to a destination for a given set of threats
- Threat Analysis - It computes interception intervals for a set of ballistic threats with elliptic orbits and a set of interceptor bases.

The Application Editor is used to describe large scale C^3I applications using these tasks/functions. Figure 6 illustrates a more complete Command and Control application, constructed by connecting the individual C^3I tasks.

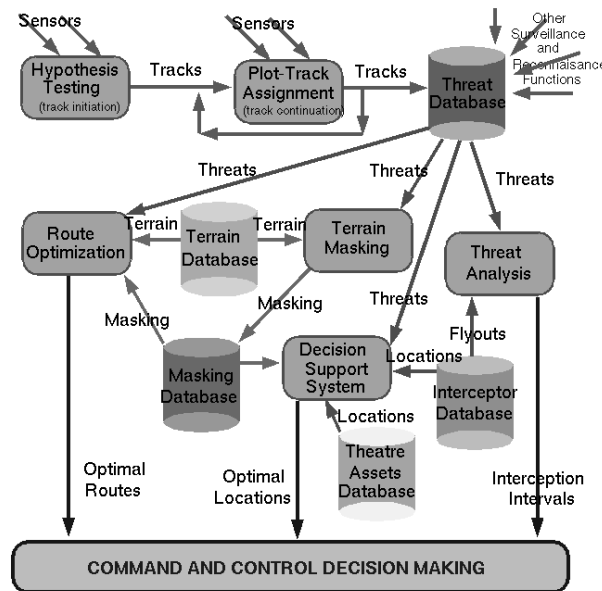


Figure 6: C^3I System

Matrix Algebra Applications VDCE Problem solving environment supports several modules to solve matrix-algebra based problems. Linear Equation Solver application is an example problem that can be solved with the help of the functions in the matrix algebra menu. In this application, the problem is to find the solution vector x in an equation $Ax = b$, where A is a known $N \times N$ matrix and b is a known vector. The Linear Equation Solver can be solved based on Gauss-Jordan elimination, Gaussian Elimination with back-substitution, or LU Decomposition. With LU Decomposition any matrix can be decomposed into the product of a lower triangular matrix L and upper triangular matrix U . Once LU Decomposition is solved, the solution vector, x , is derived as shown below:

$$\begin{aligned} Ax &= b \\ (LU)x &= b \\ Ux &= L^{-1}b \\ x &= U^{-1}(L^{-1}b) \end{aligned}$$

Figure 2 shows the building the application flow graph of a Linear Equation Solver (based on LU Decomposition) with the Application Editor. To construct the flow graph of this application, the user creates nodes by selecting the LU_Decomposition, Matrix_Inverse(2), and Matrix_Multiply(2) tasks from the Matrix_Operations menu. Figure 3 shows how user can specify the task properties (i.e machine type, sequential or parallel execution, number of machines for parallel execution case) of Linear Equation Solver application.

4.1 Experiments and Results

Additionally, VDCE can provide support to experiment and evaluate application executions for different underlying hardware/software configurations. In what follows we explain the results of FFT (fast Fourier Transformation) experiments for different message passing tools and machine configurations, and Linear Equation Solver experiments for different network types and machine configurations.

Fast Fourier Transform (FFT) Given the input sample signal $s(k)$, $k = 0, 1, \dots, M-1$, computation of FFT gives the output $X(i)$, $i = 0, 1, \dots, M-1$ such that

$$X(i) = \sum_{k=0}^{M-1} s(k) \cdot W^{ik}$$

where $W = e^{j2\pi/M}$, $j = \sqrt{-1}$ and $M =$ number of sample points.

Suppose we have N workstations on the network and $M = N \cdot 2^n$ ($n \geq 1$), the DIF (Decimation in Frequency) algorithm for FFT can be mapped onto the network of workstations. A case of $M = 8$ and $N = 2$ is shown in Figure 7. Each of the small circles represents a computation which takes two sample inputs and gives two outputs. If sample size is M , then there are $M/2$ rows of computation. Each process takes $M/(2 \cdot N)$ rows. The lines crossing the bold lines represent interprocessor communication. There are $\log_2 M$ computation steps and $\log_2 N$ communication steps. The algorithm has been implemented using the master/slave programming model.

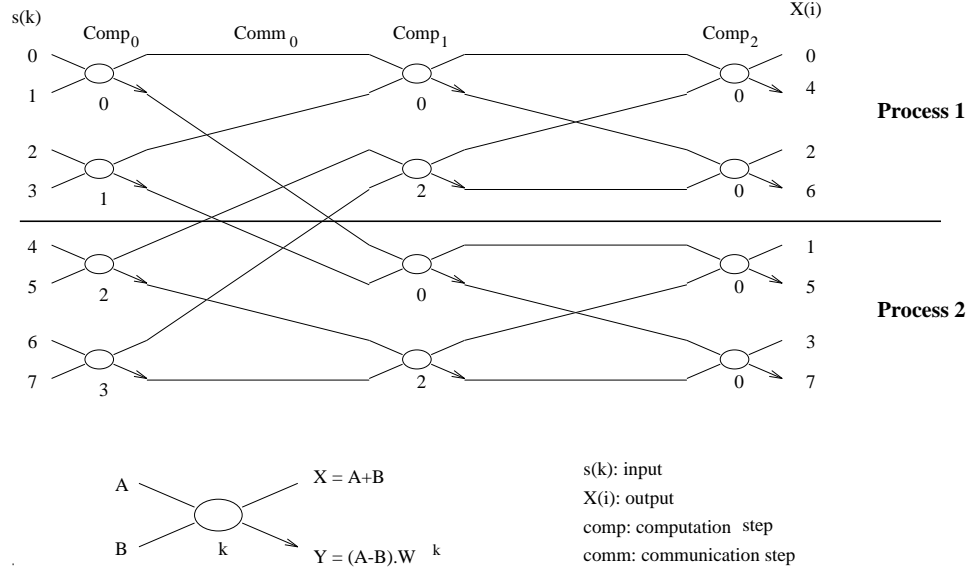


Figure 7: Computation of a 8 point FFT using 2 workstations

In this case, the performance of running FFT on 2, 4 and 8 workstations interconnected by an ATM network is evaluated. The parallel FFT implementation is based on NCS, MPI, p4, and PVM message passing tools. Therefore the VDCE user is provided with 12 different experiments in the system. Table 2 shows the benchmarking results of FFT for these 12 cases, when it is run in VDCE. For four nodes, the total execution time of NCS is 1506.365 *milliseconds*. This performance is about 22 % improvement versus MPI implementation (1848.056 *milliseconds*), 12 % improvement versus p4 implementation (1700.832 *milliseconds*), and 15 % improvement versus PVM implementation (1739.750 *milliseconds*). For the eight nodes, the performance gains of NCS versus MPI, p4, and PVM are around 38%, 32%, 36%, respectively. From these performance benchmarking, VDCE end user can select the NCS implementation over 8 nodes to achieve better performance.

Table 2: Performance of FFT (Sample Points: 1024, Set Size: 8) (msec)

No. of nodes	NCS	MPI	p4	PVM
2 nodes	1738.237	2145.398	2015.830	1989.461
4 nodes	1506.365	1848.056	1700.832	1739.750
8 nodes	1148.320	1587.914	1517.796	1561.961

Linear Equation Solver As explained in the previous section, Linear Equation Solver application finds the the solution vector x in an equation $Ax = b$, where A is a known $N \times N$ matrix and b is a known vector. We experimented with Linear Equation Solver based on LU Decomposition method (see Figure 3). The problems size in the experiments is 128×128 . Each task was executed with 1, 2 and 4 solaris machines interconnected by both ATM and Ethernet networks. Therefore VDCE user is provided with 6 different experiments for each task. The Table 2 shows

the benchmarking results of individual tasks (LU (LU Decomposition), INV (matrix inversion) and MULT (matrix multiplication)).

Table 3: Performance of Linear Equation Solver tasks on ATM and Ethernet (msec)

No. of nodes	LU	LU	INV	INV	MULT	MULT
	Ethernet	ATM	Ethernet	ATM	Ethernet	ATM
1 node	226073	217191	280626	278534	49903	48392
2 nodes	236180	233573	276193	273654	49205	44091
4 nodes	253731	253089	274421	270139	53088	50311

LU gives better performance for sequential execution than 2-node and 4-node cases, because of its implementation is communication-bound. For an $N \times N$ problem size and P processors, LU task requires $\frac{N}{P}$ all-to-all communication and 2 one-to-all communication steps. For INV task, 4-node is the best and for MULT task, 2-node is the best among others; since INV and MULT implementations require communication only for data distribution phase, and result gathering phase. Therefore their implementations require only 2 one-to-all communication steps. ATM-based network gives better results than Ethernet-based case for all task implementations. According to these results, if the VDCE user chooses 1 node for LU, 4 nodes for INV and 2 nodes for MULT while developing his/her application, this combination will achieve better performance than other possibilities.

Our current VDCE prototype is not complete and we are currently working on adding more performance evaluation capabilities. The linear equation solver example presented here serves as a proof-of-concept on the benefits that can be gained from allowing users to experiment with different implementation algorithms to determine the configuration that lead to better performance results.

5 Conclusion

We have proposed a problem-solving environment, called Virtual Distributed Computing Environment (VDCE), for large-scale network applications. VDCE enables scientists to develop parallel/distributed applications without specialized knowledge of the underlying computer hardware and software. End users can access to VDCE through web-browsers to write parallel/distributed network applications and experiment and evaluate the applications for the different combinations of hardware and/or software tools. VDCE can be described by two main modules: Application Editor and VDCE Runtime System. The Application Editor provides users with all software tools and library functions required to develop a VDCE application. VDCE Runtime System maps the tasks of the application onto the resources, monitors the resources, enables a high-performance communication medium among the modules of VDCE applications, sets up the application execution environment and manages the execution to meet the requirements of the application. We also showed how the VDCE can be used to develop network applications and evaluate the performance of the application tasks. We are improving the current implementation of the VDCE so that it can support access to several sites which are geographically distributed. We are also implementing distributed shared memory to allow VDCE users to describe their application using

shared memory paradigm.

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