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Development of image-based surgical planning software for boneconduction implants

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Graduate Program in Electrical and Computer Engineering A thesis submitted in partial fulfillment of the requirements for the degree in Master of **Engineering Science** © Carlos D. Salgado 2018

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Abstract

The BONEBRIDGE bone-conduction device is used to treat conductive and mixed hearing losses. The size of its floating mass transducer (FMT) can preclude implantation in certain anatomies, necessitating comprehensive surgical planning. Current techniques are time consuming and difficult to transfer to the operating room. The objective of this thesis was to develop software for calculating skull thickness to the dura mater to find locations for the FMT and to the first air cells which guarantee sufficient bone for the implant screws to grasp. Temporal bone computed tomography (CT) images were segmented and processed and custom Matlab code was written to generate and test thickness colormaps. For validation, measurements performed by a trained otologist were compared to the algorithm estimations achieving sub-millimeter accuracy. Results suggest this software can be used in the surgical workflow to automate thickness estimation and aid in finding an ideal location for the BONEBRIDGE device and screws.

Keywords

Image Processing, BONEBRIDGE, Temporal Bone, Surgical Planning, Computed Tomography, Bone Conduction Devices

Co-Authorship Statement

Chapter 2 consists of a manuscript that has been submitted to and is currently under review by the *Journal of Otolaryngology – Head & Neck Surgery*:

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H. M. Ladak and S. K. Agrawal conceptualized the project and prompted the study. C. D. Salgado developed the algorithm with assistance from S. A. Rohani. C. D. Salgado also wrote the initial manuscript, which was edited by S. K. Agrawal and H. M. Ladak. H. M. Ladak and S. K. Agrawal were primary supervisors for C. D. Salgado.

Dedication

A mi familia

Por ser los mejores ejemplos de superación, por enseñarme de perseverancia. Por su amor y apoyo incondicional y por mantenerse tan cerca aún en la distancia.

A mi amor

Por ser mi fuente de inspiración para crecer y ser mi mejor version. Por motivarme a cumplir mi aspiración y apoyarme tanto sin condición.

A mis amigos

A los se han quedado, a los que llegaron en el camino y me echaron la mano. A los que con una charla me motivaron, los reconozco a todos como mis hermanos.

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List of Abbreviations

2D Two-Dimensional

3D Three-Dimensional

BAHA Bone-Anchored Hearing Aid

BC Bone Conduction

BCD Bone Conduction Device

CHL Conductive Hearing Loss

CI Confidence intervals

CT Computed Tomography

dB HL Decibels of Hearing Loss

FMT Floating Mass Transducer

HU Hounsfield Units

MAD Mean Absolute Difference

MHL Mixed Hearing Loss

PTA Pure Tone Average

SNHL Sensorineural Hearing Loss

SSD Single Sided Deafness

WHO World Health Organization

Chapter 1

Introduction

1.1 Overview

In this thesis, patient data were analyzed for bone conduction implant surgery, an implant designed to alleviate hearing loss. A method was then developed to automate a part of the surgical planning procedure, with the goal of saving clinical time. This introductory chapter begins with a short review on the anatomy and physiology of the ear, followed by an explanation of the degrees and types of hearing loss, current bone conduction devices, and lastly summarizes the image processing approaches adopted in this research.

1.2 The Human Hearing System

The human ear is divided into three sections. External, middle and internal. An overview of the human ear anatomy can be observed in Figure 1-1.

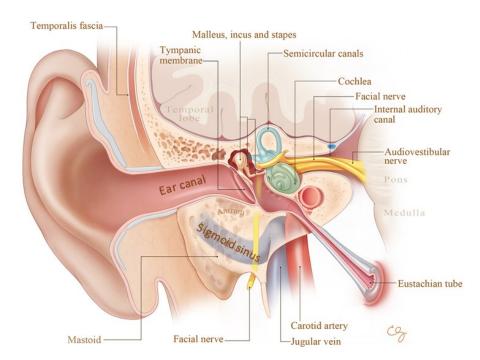


Figure 1-1: Coronal cross-section of ear anatomy. Image courtesy of Stanford
University School of Medicine [1]

The external ear is formed by the auricle and ear canal. It receives sound waves travelling through the air in the ear canal and conducts them into the middle ear.

The middle ear consists of the tympanic membrane and the internal bones that form the ossicular chain (incus, malleus and stapes). The sound waves in the ear canal vibrate the tympanic membrane, which in turn triggers the ossicular chain that sends the mechanical vibrations into the inner ear.

The inner ear consists of both the vestibular system, which is related to balance, and the cochlea and auditory nerve, which are related to hearing. Inside the cochlea, hair cells convert the received vibrations into electrical impulses of different frequencies that are then sent to the brain via the auditory nerve. Figure 1-2 depicts the main components of the middle and inner ears.

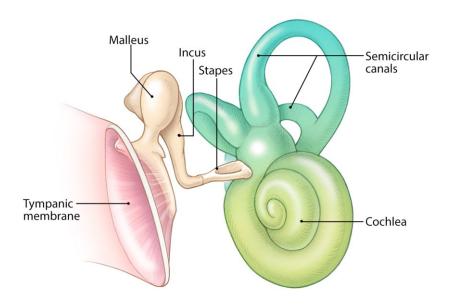


Figure 1-2: Middle and inner ear anatomy. Image courtesy of Stanford University

School of Medicine [1]

1.3 The Temporal Bone

The human skull has two temporal bones, one on either side of the skull as shown in Figure 1-3a.

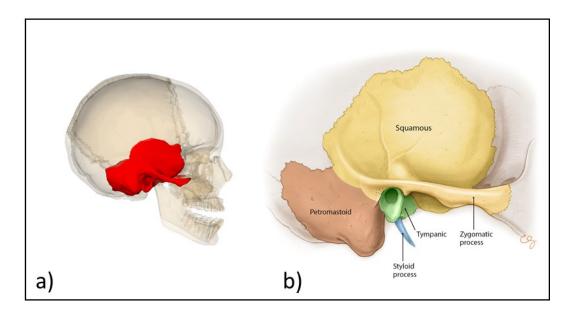


Figure 1-3: Location of the temporal bone in the skull (a) from [2] and its components (b) from [1]

Each temporal bone is divided into several main sections that can be observed in Figure 1-3b. The petromastoid is a combination of the petrous and the mastoid sections of the temporal bone, and contains the essential organs required for hearing. The fissure between the petromastoid and tympanic sections leads into the middle ear, or tympanic cavity. The tympanic cavity houses the external acoustic meatus (ear canal). The zygomatic process contains the junction where the squamous section and the mandible meet. The styloid process serves as an anchor point for several muscles associated with the tongue and larynx. The squamous section is formed by thin bone and forms the lateral wall of the middle cranial fossa. The squamous section overlaps superiorly with the parietal bone, which occupies the largest space of the top and side of the head. The parietal bone is delineated in Figure 1-4.

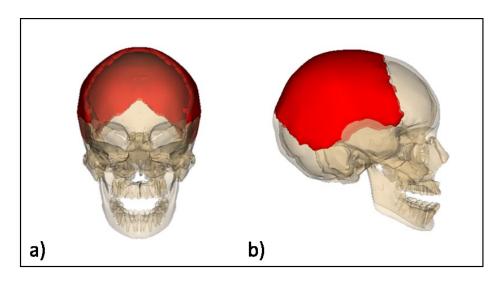


Figure 1-4: Location of the two parietal bones (red) in the skull. (a) Frontal and (b) lateral views from [3]

1.4 Hearing Loss

Hearing loss is a global public health concern recognized by the World Health Organization (WHO). It is the second impairment, after anemia, that affects the greatest number of people around the globe [4]. Approximately 1.33 billion people endure hearing loss [4], of which 473 million people suffer from disabling hearing loss [5], making up 5% of the worldwide population. There are currently 34 million children suffering from disabling hearing loss where language skills and educational development require special attention and are often delayed if the impairment is left unattended, even when hearing loss is unilateral [6]. According to the WHO, 60% of childhood hearing loss is preventable through public health strategies that deal with infections, birth complications and treatment of expectant mothers [7, 8]. In elderly adults (over 65 years), one in every three have disabling hearing loss, which can contribute to dementia and cognitive decline when untreated [7]. Approximately 19% of the Canadian population from ages 20 to 79 currently suffer from hearing loss [9], and a billion young people worldwide are at risk of permanent damage due to their listening habits [10]. Hearing loss is also more likely in households with low income and/or low educational attainment [9]. Hearing loss has a worldwide economic impact of 750 billion US dollars annually, with costs associated to healthcare, educational support and productivity losses [4, 7]. If causes of irreversible and disabling hearing loss, like with chronic ear infections, occupational noise and ototoxic medications are left unattended, the global statistic could rise to 630 million people by 2030 and to 900 million in 2050 [7], doubling the current occurrence up to 10% of the population. To prevent this, the WHO recommends early identification of the issue to prompt the use of hearing aids or implants to improve quality of life. It is estimated that 72 million people could potentially benefit from a hearing device [7], adding to the challenge of supplying sufficient access to physicians.

1.4.1 Types and Degrees of Hearing Loss

Hearing loss can be classified by type and degree. There are three main types of hearing loss. Conductive hearing loss (CHL) is the reduction of sound transmission in the middle or outer ear. CHL can be caused by a damaged or perforated tympanic membrane; abnormalities preventing the proper movement of the ossicular chain, such as fixed malleus syndrome [11]; or pathologies, such as otitis media or middle ear malformations [12] in the aforementioned structures; among other causes. Sensorineural hearing loss (SNHL) is caused by abnormalities in the inner ear, where speech recognition is often decreased. Mixed hearing loss (MHL) is a combination of problems in the outer, middle and inner ears, and shares elements from CHL and SNHL. Table 1-1 presents degrees of hearing loss in accordance with the American Speech-Language-Hearing Association; values are in decibels of hearing loss (dB HL) which measures the degree of hearing loss in relation to the standard of normal hearing.

Table 1-1: Hearing loss categorized by the degree of loss [13]

Hearing Loss Degree	Hearing Loss Range (dB HL)
Normal	Up to 15
Slight	16-25
Mild	26-40
Moderate	41-55
Moderately Severe	56-70
Severe	71-90
Profound	>91

1.4.2 Treatment of Hearing Loss

Various treatment options are available depending on the type (conductive, sensorineural, or mixed) and degree of hearing loss. Patients with mild to moderate hearing loss, regardless of type, can largely benefit from wearing hearing aids. Hearing aids deliver amplified sound into the ear and do not require surgery.

Severe to profound hearing loss is most commonly sensorineural, and can be treated with a cochlear implant, which involves an electrode that is surgically implanted into a patient's cochlea. Cochlear implants deliver electrical impulses to the cochlear nerve, bypassing the outer and middle ear, in order to allow the patient to hear an array of frequencies that permit the interpretation of speech.

Conductive and mild MHL are typically treated with hearing aids. However, many patients cannot wear hearing aids due to previous surgery, recurrent infections, or atresia (where the external auditory canal and/or pinna are congenitally malformed). These patients can be treated with a bone conduction device (BCD), which bypass the external auditory canal and middle ear by transmitting sound vibrations through the temporal bone into the cochlea.

1.5 Bone Conduction Devices

Bone conduction is the transmission of sound through the bones of the skull, it occurs when the vibrations representing sound that normally happen in the middle ear take place in the skull instead. These vibrations compress and expand the skull forcing the movement of the fluids in the cochlea. The intensity of the transmission depends on the incoming sound frequency and bone structure [14].

BCDs are embedded in the temporal bone and convert sound into vibrations in the skull, which are picked up by the cochlea and then sent to the brain, therefore bypassing the middle and outer ears to produce the sensation of hearing. BCDs are a recommended treatment for patients with CHL or MHL that do not attain sufficient audiological improvement from, or are unable to wear, conventional hearing aids. This can be caused by a number of reasons including occlusion of the outer ear canal, recurrent infections, or

persistent drainage [15, 16]. BCDs are the only option to treat CHL when it is accompanied by bony atresia or intractable drainage [15].

Percutaneous devices were the first type of BCD developed during the 1970s out the necessity to improve on the discomforts of conventional hearing aids, such as auditory feedback and pressure [14]. The most commonly used device of this category is the Bone-Anchored Hearing Aid (BAHA), introduced in Sweden in the late 1970s [17]. The BAHA stimulates the temporal bone via an osseointegrated (adhered to bone) screw made of titanium and an abutment through the skin (percutaneous) connected to the external unit. After no longer being able to wear conventional hearing aids, patients have reported improvement in speech recognition, sound quality, and comfort with the BAHA [18]. Even though the complication rate for the BAHA is low, the percutaneous abutment and the interface with the titanium screw can represent risk of recurring infection, skin overgrowth, or wound dehiscence [16].

Passive transcutaneous BCDs avoid the issues related to the percutaneous nature of the BAHA by stimulating a magnet implanted transcutaneously through an external stimulator, vibrating the bone through the skin instead of directly. However, it has been reported that in comparison with the BAHA, the hearing improvement at higher frequencies is considerably lower, and the vibration in the soft tissue may cause a variety of skin problems such as swelling or infection after fitting [19]. A transcutaneous version of the BAHA was introduced in 2013 [20].

In active transcutaneous BCDs, vibrations are transmitted directly to the temporal bone via a floating mass transducer (FMT) that converts sound into vibrations. This active component is implanted in the bone under the skin. In contrast with the percutaneous BAHA, the electrical signal from the processor is transmitted through the skin instead of through mechanical vibrations [19]. Active transcutaneous BCDs have fewer complications than percutaneous and passive BCDs, but they can be surgically challenging to insert [19].

1.6 The BONEBRIDGE

The BONEBRIDGE is a partially implantable, active transcutaneous BCD developed by MED-EL (Innsbruck, Austria) that was first implanted in June 2011 as part of a clinical trial and was launched onto the European market in September 2012. The first BONEBRIDGE implant in North America was performed at London Health Sciences Centre in April, 2013 [21, 22].

The device consists of a floating mass transducer (FMT) surgically implanted into the temporal bone, which is powered trancutaneously by a transmitter coil [16, 23] and a digital audio processor that is magnetically held in place by the aforementioned coil beneath the skin [24]. In addition to CHL and MHL, the BONEBRIDGE can in some cases treat severe-to-profound SNHL in one ear, also known as Single Sided Deafness (SSD) if the contralateral ear has normal hearing. The BONEBRIDGE device is displayed in Figure 1-5.

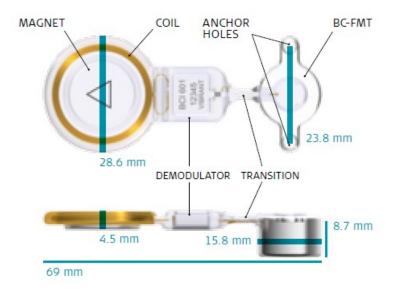


Figure 1-5: The BONEBRIDGE, its components and dimensions. Image courtesy of MED-EL [25]

As opposed to the BAHA, the two screws securing the device in the temporal bone do not need to be osseointegrated, therefore the BONEBRIDGE can be activated approximatively three weeks after implantation surgery [24]. Furthermore,

osseointegration of screws with the BAHA have been shown to fail in some pediatric cases [26].

The BONEBRIDGE is indicated for patients who are aged 5 years and above, have conductive or mixed mild-to-moderate hearing loss and can still benefit from sound amplification. The main audiological requirement is that the pure tone average (PTA) bone conduction (BC) threshold measured at 0.5, 1, 2, 3 and 4 kHz should be better than or equal to 45 dB of hearing loss per ear. PTA refers to the average hearing threshold of a given set of frequencies. This parameter helps determine the degree of residual hearing the patient has and their capacity to interpret speech.

Individuals with any of the following conditions in their medical history may benefit from the BONEBRIDGE, being that they are unable to wear conventional hearing aids: revision tympanoplasty, ear canal stenosis or chronically draining ears, otosclerosis or tympanosclerosis that cannot be rectified by surgery, or congenital malformations where ear canals are absent and cannot be restored through conventional surgery. The screening process to determine candidacy for the BONEBRIDGE also involves checking for sudden deafness, acoustic neuroma, or other conditions which cause severe to profound sensorineural hearing loss on one side [14].

The BONEBRIDGE was developed to improve the audiological outcomes associated with passive transcutaneous BCDs and to reduce the complications associated with percutaneous BCDs. A recent systematic review of 29 studies, of which 12 studied safety, found that implant-related complications occurred in only 6 out of 117 patients, where minor adverse events such as headaches and wound pain were experienced and only one case required superficial revision surgery [14]. Other events included postoperative wound pain and dizziness, temporary tinnitus, headache, vertigo, seroma, and skin infection. Another study by Lassaletta et al. evaluated 27 postoperative BONEBRIDGE patients using pain questionnaires and found no significant postoperative pain irrespective of the sigmoid sinus (venous channels to the brain) or dural compression (external layer of the brain), and postoperative pain scores were similar to those experienced by patients with other transcutaneous auditory implants [27].

1.6.1 Implant Surgery

The implant surgery for the BONEBRIDGE consists of drilling a bed in the temporal bone which allows for the placement of the FMT in accordance with the implant's dimensions. There are currently three surgical approaches described in the literature and each is performed depending on a patient's specific anatomy. The transmastoid approach is the most common approach for cases with previous middle ear surgeries with normal anatomy and is dependent on the volume of the mastoid. The venous sinuses and the dura mater are least likely to be compromised in this approach. The retrosigmoid approach is indicated for patients with difficult mastoid anatomy and is ideal for patients who have undergone previous mastoidectomy for chronic otitis media. However, the bone in this region is often curved, and surgery requires dissection of the nuchal musculature. The middle fossa approach may also be used as an alternative to the transmastoid approach. In this approach, the incision is located above the ear in the squamous temporal bone and is approximately 3 cm in length (comparatively smaller than in the other two approaches), and cosmetically hidden in the hairline. Since the bone in this area can be thin, dura may be exposed; however there is minimal risk or sequelae [28, 29]. Approximate locations for the mentioned approaches are displayed in Figure 1-6.

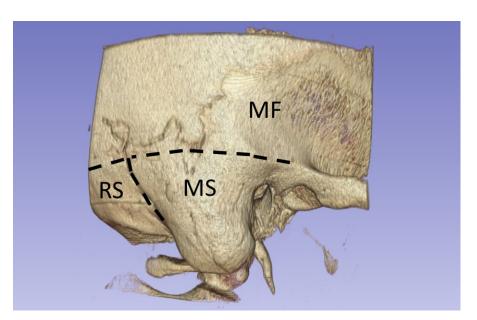


Figure 1-6: Locations for BONEBRIDGE implant. Mastoid (MS), retrosigmoid (RS) and middle fossa (MF)

In difficult cases, compression of the sigmoid sinus or dura can appear unavoidable, but it can be minimized by using BCI lifts. The BCI lifts are washers ranging in size from 1 to 4 mm and can be attached to the BONEBRIDGE FMT to allow it to fit difficult anatomies [14]. Figure 1-7 showcases the BCI lifts.



Figure 1-7: The BCI lifts, from 1 to 4 mm in size, aid in the implantation of the BONEBRIDGE in difficult anatomies. Image courtesy of MED-EL [25]

1.6.2 Computed Tomography

Computed tomography (CT) is an imaging modality capable of generating cross-sectional images (slices) by using X-rays taken from different angles of the target anatomy. CT images are displayed in grayscale representing the intensity of the light absorbed by the observed tissue. Head CT scans are typically used to detect head injury, where the darker structures indicate less tissue density and brighter structures indicate denser tissue. A head CT scan is employed in determining if a patient's anatomy is appropriate for the placement of the BONEBRIDGE implant. CT allows for good visualization of anatomical landmarks relevant to the implant surgery, such as the sigmoid sinus and the cochlea [14, 30]. Figure 1-8 displays a single axial head CT slice.

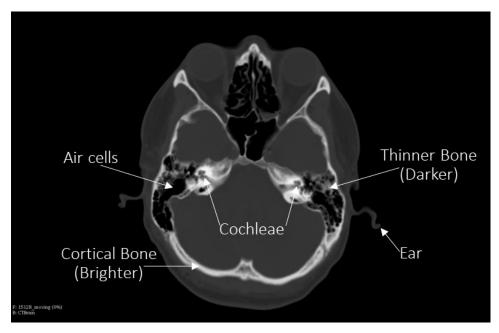


Figure 1-8: Axial slice view of a head CT scan. Only one slice of a sequence of slices is shown. Image courtesy of 3D Slicer [31, 32]

CT datasets consist of stacks of multiple two-dimensional (2D) slice images of the same specimen. Figure 1-9a represents a stack of axial head CT slices forming a 3D dataset. Slice data can be displayed in three-dimensional (3D) environments using medical image visualization software such as the open-source 3D Slicer software (www.slicer.org) [31, 32]. Figure 1-9b demonstrates the 3D rendering of the same dataset.

In CT, gray level intensities are described by the Hounsfield scale. The values in the scale are related to the linear attenuation coefficient of tissues and are expressed in non-dimensional units, called Hounsfield units (HU) or CT numbers, that are determined by the following formula:

$$HU = \left[\frac{\mu_{material} - \mu_{water}}{\mu_{water}}\right] \times 1000$$

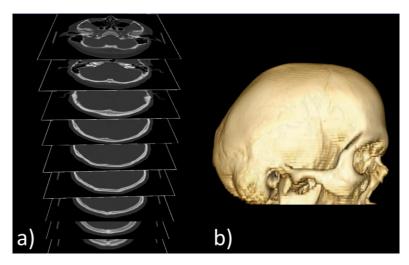


Figure 1-9: Sample head CT scan. (a) Representation as a stack of 2D slices forming a (b) 3D Rendering of the same dataset. Image courtesy of 3D Slicer [31, 32]

where μ_{water} tends to zero and is the linear coefficient of water. Medical grade CT scanners are calibrated with water as the reference. Table 1-2 lists HU values for common biological materials. The Hounsfield scale is used in image analysis applications to locate the boundaries of a material within an image with a known HU number.

Table 1-2: Reference intensity values in the Hounsfield Scale [33–36]

Substance	HU
Air	-1000
Lung	-600 to -700
Fat	-50
Water	0
Blood	+13 to +75
Muscle	+50
Brain	0 to +100
D4 Bone (Fine	+150 to +350
trabecular bone)	
D3 Bone (Porous	+350 to +850
trabecular bone)	
D2 Bone (Thick	+850 to +1250
porous cortical bone)	
D1 Bone (Dense	>1250
cortical bone)	

1.6.3 Surgical Planning

For BONEBRIDGE implantation, the patient's anatomy is analyzed by visualizing the bony anatomical structures to determine if it allows for appropriate placement of the FMT implant. Specifically, the region of the skull that is selected must be thick enough to fully house the implant.

Manually finding a suitable location is achieved by performing a CT scan of the patient's head and navigating through the axial orientation CT slices to try to find a suitable location for the FMT based on the distance to the dura mater (the outer layer of membrane protecting the brain). It is essential that during this procedure, the anatomy is analyzed to avoid the risk of injury to important anatomical structures, including the chorda tympani [37], the sigmoid sinus or the facial nerve [38] during implantation [39]; or significant modification of the temporal bone pneumatisation (the air cell¹ system) that could affect the middle ear pressure buffers [40].

Manually determining the most suitable location to implant the FMT is time consuming and hinders the surgical workflow, which is why surgeons have expressed a need for quick and intuitive skull thickness estimation tools. A few attempts have been made to develop algorithms to estimate the thickness of the skull from each patient's CT scan and generate a map that can visually guide the surgeon in selecting a location that is thick enough to house the implant.

1.7 Image segmentation

Segmentation is an image processing technique used to partition a digital image to simplify its analysis. Image segmentation is employed in medical imaging to separate anatomical structures for visualization and diagnosis. Thresholding is the simplest form of segmentation, where an HU number is used as the lower grayscale intensity boundary to binarize an image into two values: pixels with HU equal to or above the threshold

¹Air cells in bone are cavities filled by air. Air cells are present in human temporal bones. The air cells connect to the middle ear.

represent pixels inside the segmentation (assuming the region of interest is brighter than other tissue) and HU values below the threshold are considered outside the segmentation. The opposite applies if the threshold is set as an upper boundary (i.e., the tissue of interest is darker than the other tissue). Figure 1-10 shows the segmentation result when using a lower threshold value of 150 HU, therefore labelling all pixels within the data with intensities 150 HU and above as the segmented part. Because the thinner type of bone is described as having a CT number of 150 HU, the figure displays the skull within the dataset.

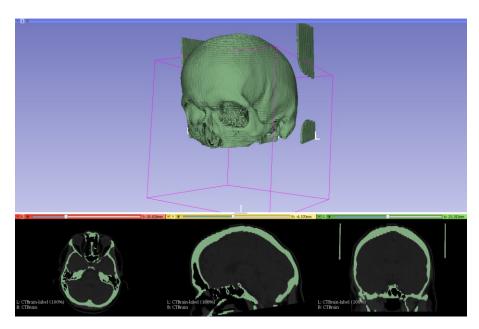


Figure 1-10: Segmentation results (BELOW) and 3D model (ABOVE) of sample data using 150 HU threshold to segment bone.

1.8 Literature Review

To improve on slice-by-slice manual processing to find a suitable implant location, some surgeons have reported using volume rendering of the BONEBRIDGE FMT inside CT images of the head, and simultaneously navigating through axial slices to determine a location with sufficient space to house the implant [14]. A common tool used for this approach is the BB FASTVIEW (CEIT, Guipuzcoa, Spain) software. The only guidance to find the location for the implant are the anatomical landmarks and the patient's clinical history [14]. This approach does not consider the air cells in the skull which are important

for screw placement as described below. Also, processing times have been reported to be over an hour long [41].

Other approaches overlay color maps on temporal bone models using different colors to depict the thickness of the bone from the cortical layer, but with no consideration of the air cells of the skull [42, 43]. This is problematic as the inclusion of the air cells in the segmentation can lead to over-estimation of the bone thickness, which may result in surgical complications if an implant location where there is not enough bone to hold the surgical screws is selected. Figure 1-11 represents a fictional case where the segmentation would prevent the visualization of the air cells, and the implant (overlaid) would be placed in an area without enough thick bone to hold it. Improper placement of the implant can result in secretory otitis media, among other complications such as cholesteatoma [40]. The software developed for this approach was presented as a C++ application with much quicker run rimes than the BB FASTVIEW approach, but it is not available to the public for download [42].

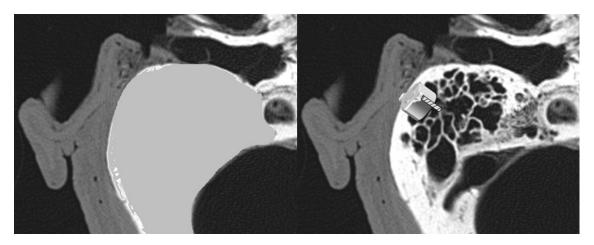


Figure 1-11: Representation of an axial slice view of a segmentation where air cells are considered bone (LEFT). Example of implant location where there is not enough bone to hold the BONEBRIDGE's surgical screws (RIGHT)

1.9 Objective

The main objective of this work was to develop a prototype thickness estimation software tool that would consider the air cells in the estimates to produce colored thickness maps of the distances from the cortical bone layer to the first air cell and from the cortical layer

to the dura mater, therefore aiding in the surgical planning of the BONEBRIDGE FMT, as well as the placement of the screws. The second objective was to validate the tool by comparing a sample of the algorithm's thickness estimations to measurements made by a surgeon with BONEBRIDGE implantation experience.

1.10 Hypothesis

It was hypothesized that bone thickness estimates obtained from both the proposed algorithm and expert measurements to air and to dura would not differ significantly from each other.

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Chapter 2

Development and Validation of a Surgical Planning Tool for Bone-Conduction Implants

2.1 Background

The BONEBRIDGE® (Med-El GmbH, Innsbruck, Austria) is a transcutaneous bone-conduction device (BCD) intended to treat conductive (CHL) and mixed hearing losses (MHL). The device consists of an externally worn audio processor and a subcutaneous floating mass transducer (FMT) implant that is surgically anchored to the temporal bone [1]. The external component powers the FMT, classifying the BONEBRIDGE as an active, semi-implantable BCD [2]. The active nature of the FMT avoids the transfer of vibrational energy transcutaneously, thus overcoming the shortcomings of percutaneous and passive transcutaneous bone conduction devices [3, 4].

One disadvantage of the BONEBRIDGE is that the FMT is 8.7mm in height and 15.8mm in diameter, therefore surgical planning is required in order to find safe locations for implantation. Currently described locations include the mastoid, retrosigmoid, and middle fossa areas [5]. In the mastoid, there can often be limited room between the sigmoid sinus, tegmen mastoideum², external auditory canal, and facial nerve to safely house the implant. This location is often excluded in patients with chronic otitis media or previous mastoidectomies [4]. The retrosigmoid and middle fossa areas are alternatives in these cases, however the skull thickness can often preclude complete implantation without dural compression and/or the use of BCI lifts [5–9]. In addition, the screws securing the implant typically require 3-4 mm of cortical bone thickness for fixation, however in

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² The thin plate of bone that covers the middle ear.

highly pneumatized temporal bones, the cortex adjacent to the air cells can be very thin. An implanted BONEBRIDGE is shown in Figure 2-1.



Figure 2-1: Cross-section of an implanted BONEBRIDGE bone-conduction device [10]

Current surgical planning techniques use computed tomography (CT) images to perform manual thickness measurements [10]. As these are conducted on two dimensional slices, the eventual location is difficult to transfer to the patient in the operating room. Some research groups such as Zernotti [5] and Weiss et al. [7] have experimented with the BB FASTVIEW tool (Center for Technical Studies and Research at the University of Navarra, Spain) which allows visualization of the FMT inside CT slices and three-dimensional (3D) reconstructions. In their work, they described three potential implantation sites and their subjective experience with the tool. Kong et al. [11] also used BB Fast View combined with image guidance to find potential implantation locations on one patient in the operating room. This approach, however, was time consuming with the navigation process taking over 90 minutes [11].

Plontke [12] proposed a similar planning tool that implemented 3D visualization with AMIRA (Thermo Fisher Scientific, Waltham, MA, USA), however this commercial tool is costly and not readily available to surgeons for pre-operative planning. This technique also required manually moving the virtual implant to determine the optimal location, with no automated guidance for the surgeon.

Treece et al. [13, 14] developed a technique to calculate the cortical thickness in cadaveric femurs. This method consisted of thresholding to find an initial approximate surface, then fitting the surface to the data by comparing the intensity values on the cortical layer. Next, a new surface was interpolated and its vertices and normals were used to guide the thickness calculation, which was solved with a generic curve fitting algorithm that found the local image minima. This algorithm estimated the cortical thickness for each surface vertex, yielding approximately 17,000 thickness estimates per sample. Lillie et al. adapted this algorithm to measure cranial vault cortical thickness, which was found to be below 4 mm on average in multiple areas of the skull [15, 16].

Wimmer et al. [17] described a different technique to measure the thickness of the temporal bone for the surgical planning of bone-conduction implants. This method incorporated thresholding, cropping, manual editing, and then morphological filtering to find the inner and outer surfaces of the bone. The thickness was estimated by calculating the Euclidean distance (straight-line distance) between their vertices. This generated a distance from the cortical bone to the dura, however the air cells were not considered as they had been filled via a morphological hole filter. The last iteration of this group's technique, described by Barakchieva et al. [18], was developed using the C++ programming language.

The primary objective of the current study was to develop an open-source, automated thickness estimation algorithm for surgical planning of the BONEBRIDGE. This novel technique would include the total thickness of the bone for FMT placement, as well as consideration of the air cells for placement of the screws. The secondary objective was to validate this algorithm against manual measurements made by an experienced surgeon.

2.2 Methods

2.2.1 Clinical CT images

Twelve cadaveric temporal bone CT images were obtained using a Discovery CT750 HD Clinical Scanner (GE Healthcare, Chicago, IL). The scanner was set to acquire images at a resolution of 234 μ m, a slice thickness of 0.625 mm, and an x-ray voltage of 120 kV. Ethics approval was obtained through Western University's Committee for Cadaveric Use in Research (approval number #19062014). The data used in the current study are available from the corresponding author upon request.

2.2.2 Algorithm Development

2.2.2.1 Segmentation

To prototype the algorithm, the images were first processed using the open source software 3D Slicer (www.slicer.org). The region of interest (ROI) contained the entire temporal bone, including the mastoid, retrosigmoid, and middle fossa areas. Segmentation was then performed utilizing a thresholding filter to separate bone from surrounding soft tissues. Depending on the case, dilation was used to add single layers of voxels to the nearest eight integers; a connectivity filter was used to remove regions smaller than 400 voxels not connected to the enclosed segmentation, and the morphological remove islands filter was used to remove regions partly connected to the segmentation smaller than 200 voxels. This ensured the final segmentations were closed surfaces. Lastly, the resulting closed surfaces were converted into models.

2.2.2.2 Post-Processing

The segmented models were exported to Geomagic (3D Systems, Morrisville, North Carolina, USA) for smoothing and averaging. This was done to reduce the number of triangles in the surface mesh, thereby preventing long computation times. The intersections and small components parameters were set to zero in the Mesh Doctor function of Geomagic to ensure convergence of the algorithm. The outer surfaces of the models were then separated from the rest of the model and used to initialize thickness estimation.

2.2.2.3 Ray Casting

A custom program was written in Matlab (MathWorks, Natick, Massachusetts, USA) to implement a traversal ray casting algorithm, adopted from Amanatides and Woo [19], on the segmented models. The primary parameters of the algorithm were the voxel intensity thresholds of the cortical bone, air cells and the dura mater (Figure 2-2). The first two thresholds used in this experiment were selected in accordance with the Misch classification of bone [20]. The threshold for bone was set to 600 Hounsfield units (HU), corresponding to thin cortical bone, and the threshold for air was set to 150 HU, below the fine trabecular bone intensity. These parameters were determined during development by visualizing the algorithm results on test images. HU values tested for thicknesses to air are displayed in Figure 2-3.

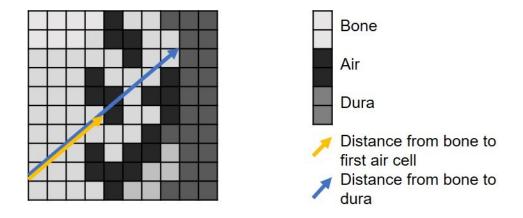


Figure 2-2: Schematic illustrating the ray casting algorithm to the first air cell and to dura

The program obtained the outer surface model triangulation and used the triangle centers as starting points for the thickness estimations. Each ray was cast from the first bone voxel in the normal direction of its respective triangle towards the inside of the skull. The traversed distance was measured at the intersecting voxels, which were found to be below the grey levels in HU set for air and dura. The script was written to inspect 20 consecutive voxels beyond the voxel where the threshold was reached to ensure that the

algorithm had actually found dura, and not a large air cell.

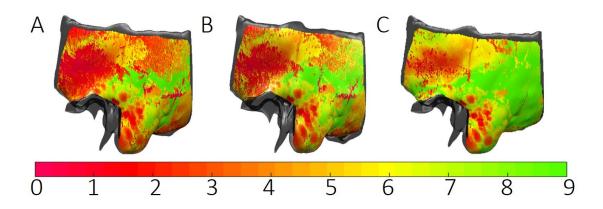


Figure 2-3: Thickness color maps from bone to air cells at (A) 400, (B) 150 and (C) 1000 HU. The units of the colorbar are mm.

2.2.2.4 Visualization

The voxels traversed by the rays were converted to distance in millimeters. Two sets of thickness estimates per sample were then saved; the first being the thickness from the outer surface to the first air cell, and the second being the distance from the outer surface to the dura. Two color maps showing these estimates were visually overlaid onto the segmented models. The color maps for the distance to the first air cell were specifically set from 0 to 4 mm, corresponding to the amount of cortical thickness needed to fully embed the screws. The color map to the dura was set from 0 to 9 mm, which corresponds to the thickness of the actual FMT (8.7 mm).

2.2.3 Validation

To compare the algorithm's estimations with expert observations, a neurotologist experienced in BONEBRIDGE implantation (S.K.A.) performed measurements using a set of uniformly distributed points (n=200) laid on the cortical layer of the temporal bone. These points were distributed to cover the most common implantation areas in the mastoid, retrosigmoid, and middle fossa areas. The expert visualized each point in the axial slice view and placed fiducials on the cortical bone, first air cell, and dura as shown

in Figure 2-4. The fiducials were converted to a distance in millimeters to correspond to the same distances calculated by the algorithm.

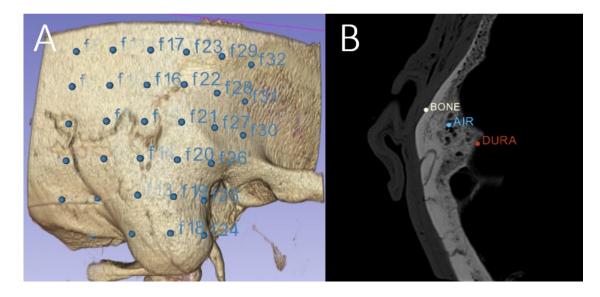


Figure 2-4: Grid of evenly distributed points laid by the program (A). Expert measurements from the cortical bone in reference to the first air cell and to dura (B)

2.2.3.1 Statistical Analyses

The data were analyzed using IBM SPSS Statistics (Version 23.0. Armonk, IBM Corp., New York USA) and graphed with GraphPad Prism (Version 7.00, GraphPad Software, La Jolla California USA). The means, 95% confidence intervals (95% CI), differences, and mean absolute differences (MAD) were calculated. Normality was evaluated using skewness, kurtosis, and the Shapiro-Wilk test. The Spearman's ranked correlation coefficient was calculated, and the Wilcoxon signed-rank test was used to determine differences between the algorithm and expert measurements. Significance was set to p < 0.05. Multiple comparisons were controlled using the Holm–Bonferroni method. The differences and absolute differences between the algorithm and expert observations were then calculated and included in the database.

2.3 Results

2.3.1 Algorithm

The ray-casting algorithm was successfully implemented and a surgical planning tool was developed to be used by surgeons pre-operatively. Each cortical surface consisted of approximately 135,000 triangles, and the program was multi-threaded allowing for the processing of multiple samples simultaneously. The workstation had a core-i7 (Intel Corporation, Santa Clara, CA, USA) processor, 24 GB memory, and an Nvidia GTX 970 graphics card (Nvidia Corporation, Santa Clara, CA, USA). The total computation time was approximately 10 minutes per sample.

The top part of Figure 2-5 shows a thickness color map of a thick sample bone, where most areas except for the most anterior part of the middle fossa can hold the screws. The same applies to the FMT, while also avoiding the most inferior part of the mastoid. Areas with thinner bone would require dural compression and/or BCI lifts for successful implantation. A thinner sample bone is shown in the bottom part of Figure 2-5, where the sigmoid sinus is visible in the bone to dura thickness map. In this case, the most appropriate location for the FMT and the screws would be in the medial mastoid. The tool is meant to suggest potential implantation areas which are to then be confirmed by the surgeon.

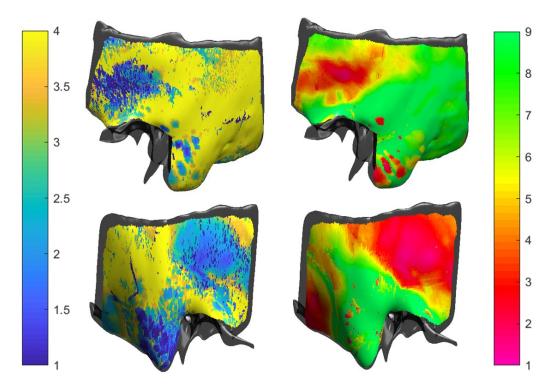


Figure 2-5: Thickness color map from bone to air cell (LEFT) and bone to dura (RIGHT). Sample with thick cortical bone (TOP). Sample with thinner cortical bone (BOTTOM). Units in mm.

2.3.2 Validation

2.3.2.1 Bone to air Cell Measurements

When comparing all points (n=200), the automated (mean=4.7 mm, CI of 4.3-5.0 mm) and expert (mean=4.7 mm, CI of 4.4-5.0 mm) bone to air thickness measurements were not significantly different, p=0.36. The MAD was small (0.30 mm, CI of 0.26-0.34 mm). The raw data are graphed in Figure 2-6, revealing excellent correlation between the algorithm and expert measurements (r=0.98, p>0.001).

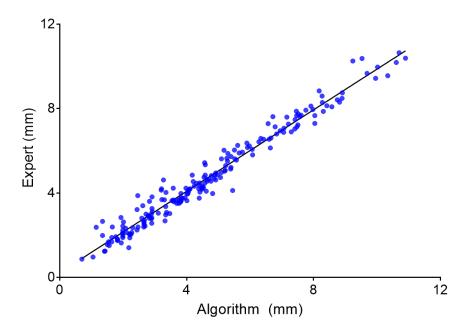


Figure 2-6: Scatter-plot of measurements from bone to air cell by the algorithm and expert.

An analysis by sub-site is provided in Figure 2-7. In the mastoid area (n=17), the automated (mean=4.4 mm, CI of 3.2-5.7 mm) and expert measurements (mean=4.5 mm, CI of 3.2-5.8 mm) were not significantly different, p=0.98. Similarly, for the middle fossa (n=140), the automated (mean=4.3 mm, CI of 3.9-4.7 mm) and expert (mean=4.3 mm, CI of 4.0-4.7 mm) thicknesses were not significantly different, p=0.76. Nonetheless, in the retrosigmoid area (n=23), the automated (mean=5.6 mm, CI of 4.5-6.6 mm) thickness measurements were statistically smaller than the expert (mean=5.8 mm, CI of 4.9-6.7 mm) markings, Z = -2.1, p=0.03. In addition, when controlling for family-wise error with the Holm-Bonferroni method, all *p-values* for the subsets of air measurements remained above a=0.05 after correction, thereby not rejecting the null hypothesis in any case.

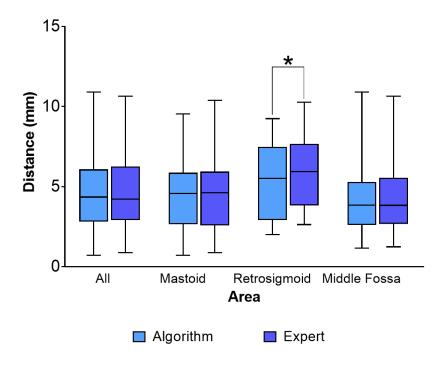


Figure 2-7: Box-plot of algorithm and expert measurements to the first air cell. All points, mastoid, middle fossa, and retrosigmoid areas. The star represents significant difference, p<0.05

2.3.2.2 Bone to dura Measurements

When comparing all points (n=200), the automated (mean=6.0 mm, CI of 5.4-6.5 mm) and expert (mean=5.9 mm, CI of 5.4-6.5 mm) bone to dura thickness measurements were significantly different, Z = -3.7, p<0.01. The MAD was small (0.31 mm, CI of 0.28-0.35 mm). The raw data are graphed in Figure 2-8, revealing excellent correlation between the algorithm and expert measurements (r=0.99, p>0.001).

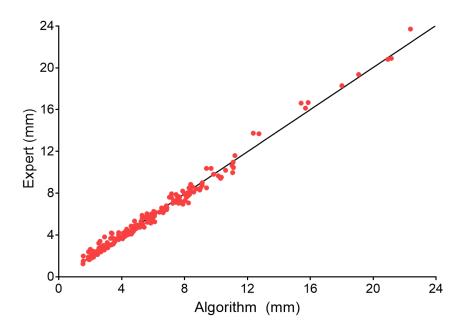


Figure 2-8: Scatter-plot of measurements from bone to dura by the algorithm and expert

Sub-site results can be observed in Figure 2-9. In the mastoid (n=17), the automated (mean=14.5 mm, CI of 11.2-17.7 mm) and expert (mean=14.8 mm, CI of 11.5-18.2 mm) measurements were not significantly different, p=0.06. This was also the case in the retrosigmoid area (n=23), where the automated (mean=6.1 mm, CI of 5.1-7.1 mm) and expert (mean=6.3 mm, CI of 5.4-7.2 mm) measurements were not statistically different, p=0.16. However, in the middle fossa (n=140), the automated (mean=4.8 mm, CI of 4.4-5.2 mm) bone to dura thickness measurements were significantly different than the expert (mean=4.6 mm, CI of 4.3-5.0 mm) markings, Z=-5.8, p<0.01. In addition, when controlling for family-wise error with the Holm-Bonferroni method, the middle fossa was the only subset of dura measurements where the *p-values* were below a=0.05 after correction, being the only area where the null hypothesis was rejected.

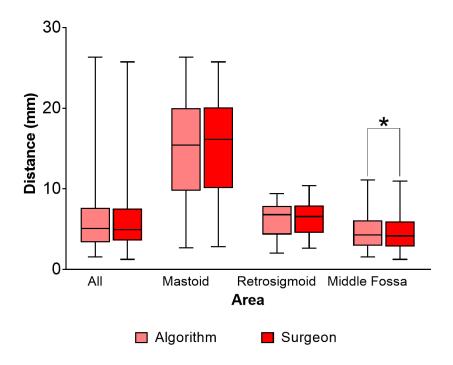


Figure 2-9: Box-plot of algorithm and expert measurements to the dura. All points, mastoid, middle fossa, and retrosigmoid areas. The star represents significant difference, p<0.05

The differences between the expert and algorithm for bone to air cell and bone to dura measurements are shown in Figure 2-10. For bone to air measurements, the MAD values by sub-site were 0.37 mm, CI of 0.14-0.60 mm for the mastoid; 0.28 mm, CI of 0.31-0.60 mm for the middle fossa; and 0.45 mm, CI of 0.23-0.32 mm for the retrosigmoid. The MAD for dura measurements were 0.60 mm, CI of 0.4-0.80 mm for the mastoid; 0.26 mm, CI of 0.23-0.30 mm for the middle fossa; and 0.46 mm, CI of 0.35-0.60 mm for the retrosigmoid.

An overview of the variance within the populations is summarized in Table 2-1, where the algorithm, expert and MAD means are displayed along with their respective 95% confidence intervals (95% CI).

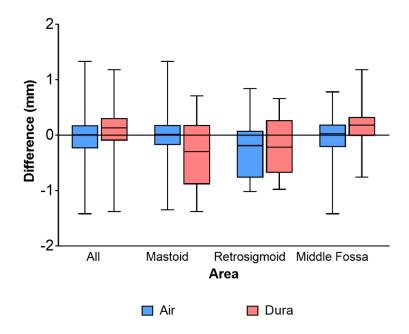


Figure 2-10: Box-plot of algorithm and surgeon differences in millimeters. Positive results indicate the algorithm had a larger estimate than the expert. Negative results indicate larger measurements by the surgeon

Table 2-1: Mean absolute difference (MAD) results by area with 95% confidence intervals. Measurements in millimeters (mm).

Thickness to Air Cells						
Area	Algorithm		Expert		MAD	
	Mean	95% CI	Mean	95% CI	Mean	95% CI
Mastoida	4.4	3.2-5.7	4.5	3.2-5.8	0.37	0.14-0.60
Middle Fossa ^b	4.3	3.9-4.7	4.3	4.0-4.7	0.28	0.23-0.32
Retrosigmoid ^c	5.6	4.5-6.6	5.8	4.9-6.7	0.45	0.31-0.60
All ^d	4.7	4.3-5.0	4.7	4.4-5.0	0.30	0.26-0.34
Thickness to Du	ura					
Area	Algorithm		Expert		MAD	
	Mean	95% CI	Mean	95% CI	Mean	95% CI
Mastoida	14.5	11.2-17.7	14.8	11.5-18.2	0.60	0.4-0.80
Middle Fossa ^b	4.8	4.4-5.2	4.6	4.3-5.0	0.26	0.23-0.30
Retrosigmoid ^c	6.1	5.1-7.1	6.3	5.4-7.2	0.46	0.35-0.60
$Al1^d$	6.0	5.4-6.5	5.9	5.4-6.5	0.31	0.28-0.35
^a n=17, ^b n=	$140.^{\circ}$ n=2.	3, d = 200 inc	cluding 20) points close	to impla	ntation sites

2.4 Discussion

Current approaches to the surgical planning of the BONEBRIDGE reported in the literature include manual image-guided placement. This approach consists of using CT images to visualize an implant model that is manually placed by the surgeon inside regions of the CT corresponding to potential placement locations; thickness maps are not provided for guidance. Plontke et al. [12] and Cho et al. [21] used commercial software to simulate the implant inside the images. Kong et al. [11] used a freely available program, BB Fast View (CEIT, Guipuzcoa, Spain), and Todt et al. developed [22] and reviewed [23] a similar simulator using open-source software ZIBAMIRA (Zuse Institute Berlin, Germany). Law et al. [24] used the program 3D Slicer to visualize the FMT and screws to find a suitable implantation location by measuring bone thickness in the skull landmarks. In Matsumoto and colleague's work [25], a surface template guide was also visualized as a guide for surgery. Among these studies, Law and colleagues [24] did not consider perforating large air cells, whereas most other studies considered air cells as part of the bone in their manual estimations. In contrast, Inui et al. [26] presented ray casting as a general application to determine thickness and clearance in 3D objects. In the current study, a thickness estimation algorithm was prototyped that accounted for the air cells in the temporal bone, thereby preventing overestimation of the thicknesses to air and to the dura mater.

The first applied topographical thickness map was presented in Wimmer's original publication [17]. His group used Amira (thermofisher.com/amira-avizo) to process the images and lay a color map. Later, Barakchieva et al. [18] presented an approach using C++. In the current study, we present a prototype for which the running time of the

algorithm per bone was approximatively ten minutes. Our results suggest that with the current parameters, this algorithm can aid in the surgical planning of the BONEBRIDGE FMT in all three implantation areas.

Measurements to the dura had statistically significant variation (p<0.01). Despite this, the overall MAD was 0.31 mm (CI of 0.28-0.35 mm) which is below the 0.625 mm slice thickness, making the magnitude of the variance not clinically relevant. The MAD by area was 0.6 mm for the mastoid, 0.26 mm for the retrosigmoid and 0.46 mm for the middle fossa; all below the axial resolution of 0.625 mm, therefore confirming acceptable variance in clinical CT images. The MAD between air measurements was also below the image resolution, being 0.3 mm for all (n=200) measurements. The variance in the dura can be attributed to the way it was calculated, being from temporal bone images with no actual dura or brain. The algorithm was therefore programmed to find a location where it would expect to see the dura, sometimes mistaking large air pockets with the expected location of the brain. With full-head images, HU values of the brain areas or dura can be inputted within the program's parameters, along with the original code, to increase the overall accuracy of the algorithm.

Each of the major steps in the image-processing pipeline (segmentation, post-processing and ray casting) was implemented in different software packages (3D Slicer, Geomagic and a custom MATLAB program, respectively). This adds to the processing time and could be made more efficient by developing custom C++ functionality and incorporating it into a single 3D Slicer module. The parameters can be further constrained to reduce the variation and facilitate the porting of the algorithm to an open-source, downloadable tool. A path towards computational efficiency can be found by limiting the number of triangles

in the triangulation while maintaining accuracy as in Ramm's work [23]; his team segment the data using a statistical shape model approach that has several limitations, which make it unsuitable for thickness estimation.

Some measurements made by the algorithm were very different from the surgeon's. These outliers were caused by the algorithm calculating the normal directions using the triangles from the outer cortical surface in 3D, as opposed to the surgeon performing thickness measurements only using the axial orientation, which is typically observed to analyze head CT scans but represents 2D data. These points were excluded from the statistical analyses since the 3D calculation of the normals would be closer to the actual ones. The points that were used in the analyses therefore reflected the program and the surgeon measuring the same thicknesses, from very similar angles, while maintaining a high sample size for statistical power.

2.5 Conclusion

At the prototype stage, our algorithm allowed the visualization of faithful representations of the bone to air and bone to dura distances at clinical CT resolution. With further automation and porting, it can be developed into a viable surgical planning tool to suggest implant locations for the BONEBRIDGE and similar BCDs with submillimeter accuracy. It is intended that in its final stage, the algorithm will reduce the amount of preclinical time spent analyzing patient anatomy for these types of implants.

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Chapter 3

Conclusions and Future Work

3.1 Contribution

Software for estimating skull thickness for the surgical placement of bone-conduction devices, such as the BONEBRIDGE, was developed and presented in this thesis. The software computed the local thickness at discrete locations on the skull and color-mapped the estimated thicknesses onto the segmented skull, displaying the measurements on two colormaps. One colormap was for thickness estimates obtained as the distance from bone to the first air cell, and the other colormap was from bone to dura. The colormaps can be used by surgeons to visually locate a region of the skull that is thick enough to house the BONEBRIDGE and its screws.

Previous software reported in the literature included the air cells in the thickness calculations, allowing the possibility of overestimation. The software developed in this work differs in a surgically important manner, as it presents the results of two thickness calculations: a colormap of bone to the air cells and a colormap of bone to the dura. In other words, instead of only considering the thickness from the cortical bone to dura, it allows computation of thickness from bone to the first encountered air cell as well. This is important because the screws of the BONEBRIDGE cannot be secured in pneumatized areas of the skull. Moreover, as the screws of the BONEBRIDGE transmit vibrations into the skull, they must grasp cortical bone.

The computation time of the algorithm to calculate and display both colormaps was approximatively 10 minutes per temporal bone, which is reasonably short. Previous approaches where the implant location was determined by visualizing the FMT within CT images ranged from 30 [1] to 90 minutes [2] in manual image navigation time. Other colormapping approaches in the literature have comparable running times [3, 4]; however, due to the exclusion of the air cells in their estimates, they are more prone to over-estimation if ported to a clinical application.

The thickness estimates in the current study were validated by comparing to an expert with several years of experience implanting the BONEBRIDGE device. Thicknesses estimated by the algorithm to air and to dura were very close to the expert measurements, suggesting that the software can be used in the surgical workflow to automate thickness estimation and aid in finding a location for the BONEBRIDGE on a patient-specific basis. This contribution is a step towards implementing decision support for surgical planning of the BONEBRIDGE and similar BCDs.

3.2 Limitations and Future Work

3.2.1Additional Testing

The BONEBRIDGE is a relatively new device and is only used at a limited number of hospitals. In London, Ontario, BONEBRIDGE surgeries are only performed by one surgeon, who is also trained with respect to image-based planning for BONEBRIDGE implantation. Hence, a limitation of this study is that the thickness estimation algorithm was only tested with respect to one surgeon. To account for inter-observer variability, testing needs to be expanded to include other surgeons, preferably with experience in the BONEBRIDGE device as well. This would require coordination among multiple hospitals and could result in several collaborative studies.

3.2.2 Decision Support

The current version of the program is still at the prototype stage, requiring supplementary research and augmentation before its clinical use. A decision support system can be developed to display candidate implant locations, with or without the BCI lifts, and automatically recommending the safest, simplest surgical route. This system can be validated with a user study. Identifying skull landmarks is also important for the transfer of the image coordinates to the patient's skull, therefore future versions of the algorithm can implement this function and investigate its accuracy to minimize complications from improper implant placement. The algorithm will require an intuitive user interface after all additional functions are implemented and validated to provide surgical planning of the BONEBRIDGE in the clinic.

3.2.3 Porting

Currently, a user's manual describes all of the processing steps and software packages used. Once validated at multiple institutions, the intent is to make the software publicly available for the community to use. The C++ programming environment can be employed to port the algorithm into a single application as it works with available image processing toolkits such as the Insight Toolkit (https://itk.org)[5]. This would allow for the incorporation of the algorithm into a single 3D Slicer module with a dedicated graphical user interface for easier use. Multi-threading and GPU processing can also be explored to achieve the maximum computing efficiency.

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