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Estimation of a Panel Stochastic Frontier Model with Unobserved Common Shocks

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Abstract

This paper proposes a panel stochastic frontier model with unobserved common shocks to control cross-sectional dependence among individual firms. The novel feature is that we separate technical inefficiency (decision-dependent heterogeneity) from the effects induced by individual heterogeneity (decision-independent) caused by unobserved common shocks. We propose a feasible maximum likelihood method that does not require estimating the effects of unobserved common shocks and discuss its asymptotic properties. Monte Carlo simulations show that the proposed method has satisfactory finite sample properties when cross-sectional dependence exists. Application is illustrated by comparison of the efficiency of savings and commercial banking industries in the US.

Keywords: fixed effects, common shocks, factor structure, cross-sectional dependence, stochastic frontier

1 Introduction

The use of panel data has become increasingly popular in stochastic frontier models, for analysis of technical or cost inefficiencies of production units and financial institutions. There are two approaches that have been employed to estimate time-varying technical inefficiency, assuming the presence of firm heterogeneity (time-invariant(fixed/random effects) or time-variant). The first considers the linear panel models without imposing distributional assumptions on technical inefficiency; see Cornwell, Schmidt and Sickles (1990), Han, Orea and Schmidt (2005), Lee (2006), Ahn, Lee and Schmidt (2001, 2007, hereafter ALS), Mastromarco, Serlenga and Shin (2012, 2013, 2015, hereafter MSS) and Filippini and Tosetti (2014), among others. The generalized method of moments (GMM, including the least squared method) is adapted in these studies to estimate stochastic frontier models with time-varying technical inefficiency. The second approach assumes that technical inefficiency is random and specific distributional assumptions are required; see Greene (2003, 2005a, b) and Wang and Ho (2010), among others. The maximum likelihood (ML) method, based on suitable distributional assumptions, is suggested to estimate the time-varying technical inefficiency.

However, to the best of our knowledge, except ALS, MSS and Filippini and Tosetti, who tried to use the factor structure to capture the time-varying technical inefficiency in the stochastic frontier panel data model based on the first approach, there are no other related papers taking into account the factor structure, which has been discussed based on the second approach. It is difficult to take the factor structure into account in the ML framework not only because these two approaches have different estimation strategies but also because they have different fundamental philosophies of time-varying technical inefficiency. More specifically, the former treats time-varying firm heterogeneity characterized by factor structure as a part of inefficiency, while the latter explicitly views firm heterogeneity (fixed/random effects, time-invariant) as something different from time-varying inefficiency, named “true” fixed/random effects. Similarly, the same issue arises if the assumption of “true” fixed/random effects is relaxed by allowing the time-varying property, that is, what can be treated as inefficiency and what cannot be. As mentioned by Koopmans (1951),

“The “technique” employed in production is itself the result of managerial choice (going beyond the discarding of unwanted factor quantities). Managers choose between, or employ efficient combinations of several processes to obtain in some sense best results” —Koopmans (1951), p.34

inefficiency can be regarded as the situation where managers “do not” choose an efficient way to generate the expected output from available capital and labour, which includes the choice of technology as well as managerial behaviour. In sum, efficiency should be related to the manager’s decision. Therefore, the relatively clear way to distinguish the time-varying heterogeneity from inefficiency is that the effects of the former are not relevant to efficiency given that they are attributable to firm characteristics which the manager “cannot” change by decisions in the long-run (relatively).

The factor structure used in ALS, MSS and Filippini and Tosetti, by definition, consists of time-varying factors and the corresponding loadings. As mentioned in Bai (2009), these loadings could be innate ability, perseverance and industriousness or firms’ heterogeneity mentioned in Greene (2005a, b), among others; and, factors are the prices (losses) caused by these unmeasured characteristics when facing time-varying economic environment. In fact, some of these are inborn; for instance, firms’ heterogeneities cannot be changed easily but still have impacts on time-varying economic events. Therefore, the estimated technical inefficiency might be distorted when we incorrectly model inefficiency. For example, it is hard to conclude that local and small banks that suffer less from global financial shocks are in general more efficient than multinational banks.

Because of these properties, in our model, the error term is split into three components. The first component is “decision-independent heterogeneity (time-varying),” captured by the factor structure. The term “decision-independent” is used to emphasize that this component is irrelevant to efficiency because a manager cannot change it by himself or herself. Moreover, the “true” fixed effects, as defined in Greene (2003, 2005a, b), Wang and Ho (2010) and Chen, Wang and Schmidt (2014) can be treated as a special case while we let the factors (prices) be a constant. The second component captures the “decision-dependent heterogeneity (time-varying)”, which can be regarded as a measure of “technical inefficiency” similar to most stochastic frontier panel data models. To estimate technical

inefficiency, the scaling function proposed by Wang and Schmidt (2002) is used, that is, technical (managerial) inefficiency can be explained by some relevant variables according to the economic theory or organizational behaviour. The last component is a random shock.¹

In addition to the “decision-independent” heterogeneity, factor structure can also specify the presence of cross-sectional dependence and the correlation between regressors and factors which are prevalent features in panel data. Ignoring correlation between regressors and factors induced by these events can be problematic in estimation of panel regressions; see Andrews (2005), Pesaran (2006), and Bai (2009) for further discussion.²

This paper proposes a panel stochastic frontier model with unobserved factor structure to capture the unobservable “decision-independent” heterogeneity and accommodate the possible phenomenon of cross-sectional dependence among individual firms. To overcome the endogeneity caused by the “decision-independent” heterogeneity, which is irrelevant to inefficiency and to estimate the time-varying technical inefficiency, we follow Pesaran (2006) and propose a likelihood-based method.³ The transformed model obtained by multiplying an annihilator matrix consisting of the cross-sectional averages of the dependent variable and regressors should allow filtering of decision-independent heterogeneity (including true fixed/random effects) asymptotically. However, in our setup, the time-varying technical inefficiency in the right hand side is needed for estimation, which makes the annihilator matrix dependent upon the parameters. To address this issue, we first construct an open ball in the parameter space around the true value of parameters and show that the maximizer of the log-likelihood function calculated from the transformed model (feasible approximated log-likelihood function) will occur in this open ball with probability 1. We then show that under some regular conditions, the difference between the feasible approximated log-likelihood function and the one that treats decision-independent hetero-

¹This specification is also robust to the “omitted variable” problem in the scaling function while the omitted inefficiency can be decomposed to form a factor structure.

²Ackerberg, Caves and Frazer (2006) have mentioned that although some shocks(factors) are unobserved by econometricians, they are potentially predictable by firms when they are making input decisions, such as expected defect rates, expected down-time due to machine breakdowns, or expected government policies. This is the classic endogeneity problem whereby the firm’s optimal choice of inputs will generally be correlated with these unobserved shocks.

³These effects could referred to as common correlated effects (Pesaran, 2006) or interactive effects (Bai, 2009).

generosity as known is negligible and is faster than the usual rate of $(NT)^{-1/2}$ in this open ball. Thus, we can assure that the asymptotic properties of the proposed estimators are the same as those obtained from the transformed model which treats decision-independent heterogeneity as known when $(T, N) \rightarrow \infty$ jointly and $T/N \rightarrow 0$.

There are a few additional features of the proposed method. First, it possesses the scaling property proposed by Wang and Schmidt (2002) and Wang and Ho (2010). In contrast to ALS, MSS and Filippini and Tosesti the scaling-property enables investigation of how firms' efficiency levels vary with exogenous variables.⁴ Second, our approach can be easily extended to estimate the cost function and cost inefficiency. We also conduct some Monte Carlo simulations to investigate the finite sample properties of the proposed method. The simulation results show that the proposed estimator has significantly smaller biases and MSEs than the within-transformation estimator when unobservable time-varying decision-independent heterogeneity exhibits in the data.

To illustrate its relevance, the proposed approach is applied to analyze cost inefficiency of the savings and commercial banking industry in the U.S. Recent studies on bank efficiency do not deal with effects of time-varying decision-independent heterogeneity; see, for example, Lensink et al. (2008) and Sun and Chang (2010). The empirical results show that bank efficiency improved before 2006 and the estimated inefficiency index might be biased if we do not take into account the time-varying decision-independent heterogeneity.

The remainder of this paper is organized as follows. Section 2 describes the panel stochastic frontier model with time-varying decision-independent heterogeneity and discusses asymptotic properties of the proposed estimation procedure. Section 3 conducts some Monte Carlo simulations to investigate the small-sample properties of the proposed estimator. An empirical application is discussed in Section 4. Section 5 concludes this paper. All mathematical proofs are provided in the Appendix.

⁴However, we do not compare the proposed model with the one used in Ahn et al. among others because these two model specifications have different philosophies of time-varying technical inefficiency.

2 Panel Stochastic Frontier Model

2.1 The Model

Consider a panel stochastic frontier model with the following specifications:

$$y_{it} = \alpha_i + \mathbf{x}'_{it}\boldsymbol{\beta} + \boldsymbol{\lambda}'_i\mathbf{f}_t + v_{it} - u_{it}, \quad i = 1, \dots, N, \quad t = 1, \dots, T, \quad (1)$$

$$\mathbf{x}_{it} = \mathbf{A}_i + \boldsymbol{\tau}'_i\mathbf{f}_t + \mathbf{e}_{it} \quad (2)$$

$$u_{it} = h_{it}u_i^* = h(\mathbf{z}'_{it}\boldsymbol{\delta})u_i^*, \quad (3)$$

where y_{it} is the logarithm of output of firm i in period t , \mathbf{x}_{it} is a $k \times 1$ vector of the logarithm of inputs in this production system, α_i denotes individual fixed effects, and v_{it} is a zero-mean idiosyncratic error. Let \mathbf{f}_t be a $r \times 1$ vector of price/cost to unobserved common economic events, $\boldsymbol{\lambda}_i$ be the heterogeneous impact of common shocks on firm i , and u_{it} is the term used to measure inefficiency. The regressors are also affected by individual fixed effects, \mathbf{A}_i , and common shocks, where \mathbf{A}_i is a $k \times 1$ vector which is correlated with α_i , and $\boldsymbol{\tau}_i$ denotes a $r \times k$ vector of factor loadings. The specification not only allows for cross-sectional dependence through three error components but makes for correlation between time-varying heterogeneity and regressors. The idiosyncratic error \mathbf{e}_{it} is independent of all observations on v_{it} and u_{it} . Finally, let h_{it} be a positive function of firms' inefficiency determinants \mathbf{z}_{it} , $u_i^* \sim N^+(\mu, \sigma_u^2)$, where the distribution is truncated from below at zero such that $u_i^* > 0$. This specification is referred to as the scaling property, which allows us to estimate coefficients and inefficiency in a one-step procedure.⁵ The scaling property also allows the inefficiency u_{it} to be correlated over time for a given individual.

A number of features in these specifications are of interest. Firstly, in contrast to the conventional stochastic frontier literature, our model can distinguish the decision-independent heterogeneity, $\boldsymbol{\lambda}'_i\mathbf{f}_t$, from technical inefficiency, u_{it} . The decision-independent heterogeneity is used to capture the heterogeneous impacts of unobservable common eco-

⁵Conditional on \mathbf{z}_{it} , the scaling property means that technical inefficiency equals some function of exogenous variables times a one-sided random variable distributed independently of \mathbf{z}_{it} ; see Wang and Schmidt (2002).

conomic events, which can not be controlled by managers. Secondly, an endogeneity problem may arise because unobserved decision-independent heterogeneity may affect both firms' input decisions, \mathbf{x}_{it} , and their outputs, y_{it} .⁶ Thirdly, the conventional fixed-effect stochastic frontier models proposed by Greene (2005a, b) and Wang and Ho (2010) are special cases of our specification with $\mathbf{f}_t = 1$. Fourthly, compared with Ahn et al. among others, our specification enables us to directly investigate the effects of observed variables \mathbf{z}_{it} on inefficiency and then obtains meaningful policy inferences to improve efficiency.⁷

2.2 Estimation

In this section we propose a transformation to control for the decision-independent heterogeneity (referred to as the CCE transformation⁸), and then apply the maximum likelihood method to consistently estimate the parameters in the stochastic frontier model (1) – (3).

Define

$$\bar{\mathbf{M}}_0 = \mathbf{I}_T - \bar{\mathbf{H}}_0(\bar{\mathbf{H}}_0'\bar{\mathbf{H}}_0)^{-1}\bar{\mathbf{H}}_0',$$

where

$$\bar{\mathbf{H}}_0 = (\mathbf{D}, \bar{\mathbf{Y}}, \bar{\mathbf{h}}_0\mu_0^+),$$

$\mathbf{D} = (d_1, \dots, d_T)' = (1, \dots, 1)'$ is a $T \times 1$ vector of ones, $\bar{\mathbf{Y}} = (\bar{\mathbf{y}}, \bar{\mathbf{X}})$ is the cross-sectional average of $(\mathbf{y}_i, \mathbf{X}_i)$, $\bar{\mathbf{h}}_0$ denotes the cross-sectional average of \mathbf{h}_i evaluated at $\boldsymbol{\delta}_0$, and μ_0^+ denotes the true value of $\mu^+ = \frac{\phi(\frac{-\mu}{\sigma_u})}{1 - \Phi(\frac{-\mu}{\sigma_u})}\sigma_u$, the mean of the truncated normal $u_i^* \sim N^+(\mu, \sigma_u^2)$. Φ and ϕ represent the cumulative density function and probability density function of a standard normal distribution, respectively. Throughout this paper, we use the subscript “0” to indicate that the parameter is evaluated at the true value. The rank of $\bar{\mathbf{M}}_0$, which depends on the dimension of $\bar{\mathbf{H}}_0 = (\mathbf{D}, \bar{\mathbf{Y}}, \bar{\mathbf{h}}_0\mu_0^+)$, is $T - \dim(\bar{\mathbf{H}}_0) = T - s$.

⁶To solve the endogeneity problem, Olley and Pakes (1996) and Levinsohn and Petrin (2003) show that investment and intermediate goods can be used as the proxies of these unobserved state variables; however, they may not be valid in the cost function analysis.

⁷Notice that \mathbf{z}_{it} is allowed to include unobserved common shocks, \mathbf{f}_t .

⁸This transformation share the same spirit with Pesaran (2006) to deal with common correlated effects (CCE).

Transform (1) by multiplying it by $\bar{\mathbf{M}}_0$,

$$\bar{\mathbf{M}}_0 \mathbf{y}_i = \bar{\mathbf{M}}_0 \mathbf{X}_i \boldsymbol{\beta} + \bar{\mathbf{M}}_0 \boldsymbol{\varepsilon}_i + \bar{\mathbf{M}}_0 \mathbf{F} \boldsymbol{\lambda}_i, \quad (4)$$

where $\bar{\mathbf{M}}_0 \boldsymbol{\varepsilon}_i = \bar{\mathbf{M}}_0 \mathbf{v}_i - \bar{\mathbf{M}}_0 \mathbf{u}_i$. In particular, $\mathbf{v}_i = (v_{i1}, \dots, v_{iT})'$ and $\mathbf{u}_i = (u_{i1}, \dots, u_{iT})'$, thus, $\bar{\mathbf{M}}_0 \mathbf{v}_i \sim N(0, \Pi_0)$, $\Pi_0 = \sigma_v^2 \bar{\mathbf{M}}_0$, and $\bar{\mathbf{M}}_0 \mathbf{u}_i = \bar{\mathbf{M}}_0 h(\mathbf{z}'_i \boldsymbol{\delta}) u_i^*$. Furthermore $\mathbf{F} = (\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_T)'$ is a $T \times r$ matrix. Since $\bar{\mathbf{M}}_0$ is an idempotent matrix, we solve the non-invertible problem of $\bar{\mathbf{M}}_0$ based on the method of Khatri (1968). In addition, following Wang and Ho (2010), we obtain the conditional log-likelihood function for each i as

$$\begin{aligned} \ln L_i(\boldsymbol{\theta}) = & -\frac{1}{2} (T - s) (\ln(2\pi) + \ln \sigma_v^2) - \frac{1}{2} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta})' \bar{\mathbf{M}}_0 \Pi_0^{-1} \bar{\mathbf{M}}_0 (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta}) \\ & + \frac{1}{2} \left(\frac{\mu_*^2}{\sigma_*^2} - \frac{\mu^2}{\sigma_u^2} \right) + \ln \left(\sigma_* \Phi \left(\frac{\mu_*}{\sigma_*} \right) \right) - \ln \left(\sigma_u \Phi \left(\frac{\mu}{\sigma_u} \right) \right), \end{aligned} \quad (5)$$

where

$$\mu_* = \frac{\mu / \sigma_u^2 - (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta})' \bar{\mathbf{M}}_0 \Pi_0^{-1} \bar{\mathbf{M}}_0 \mathbf{h}_i}{\mathbf{h}'_i \bar{\mathbf{M}}_0 \Pi_0^{-1} \bar{\mathbf{M}}_0 \mathbf{h}_i + 1 / \sigma_u^2} \quad (6)$$

$$\sigma_*^2 = \frac{1}{\mathbf{h}'_i \bar{\mathbf{M}}_0 \Pi_0^{-1} \bar{\mathbf{M}}_0 \mathbf{h}_i + 1 / \sigma_u^2}. \quad (7)$$

The model parameters can be estimated numerically by maximizing the objective function, $\tilde{Q}_{NT}(\boldsymbol{\theta}) = (NT)^{-1} \sum_{i=1}^N \ln L_i(\boldsymbol{\theta})$, where $\boldsymbol{\theta} \in \boldsymbol{\Theta} \subseteq \mathbb{R}^d$ is an unknown parameter vector, where d is the number of parameters.

Notice that the above estimation procedure is designed for the production system. For the cost function, the model should be modified as

$$y_{it} = \alpha_i + \mathbf{x}'_{it} \boldsymbol{\beta} + \boldsymbol{\lambda}'_i \mathbf{f}_t + v_{it} + u_{it}, \quad (8)$$

where y_{it} denotes the total cost of firm i in period t . The individual log-likelihood function is similar to (5) except that

$$\mu_* = \frac{\mu / \sigma_u^2 + (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta})' \bar{\mathbf{M}}_0 \Pi_0^{-1} \bar{\mathbf{M}}_0 \mathbf{h}_i}{\mathbf{h}'_i \bar{\mathbf{M}}_0 \Pi_0^{-1} \bar{\mathbf{M}}_0 \mathbf{h}_i + 1 / \sigma_u^2}.$$

2.3 The Properties of the Proposed Method

By an analogous argument to Pesaran (2006), we will show that $\bar{\mathbf{M}}_0$ can filter out the unobservable time-varying decision-independent heterogeneity in our three error components stochastic panel data model. To complete the inferences of consistency and the asymptotic normality of the proposed estimator, the following assumptions are used throughout this paper.

Assumption 1.

The error structure contains v_{it} , \mathbf{e}_{it} and u_i^* , which are distributed independently of each other and of the regressors $\mathbf{x}_{it}, \mathbf{z}_{it}, \forall i, t$. We also assume that

$$v_{it} \sim N(0, \sigma_v^2)$$

$$u_i^* \sim N^+(\mu, \sigma_u^2),$$

where the variances σ_v^2 and σ_u^2 are bounded.

Assumption 2. The common factors d_t and \mathbf{f}_t are covariance stationary with absolute summable autocovariances, distributed independently of v_{it}, \mathbf{e}_{it} and $u_i^*, \forall i, t$.

Assumption 3. The unobserved factor loadings λ_i with mean $\boldsymbol{\eta}$ and $\boldsymbol{\tau}_i$ with mean $\boldsymbol{\tau}$, specifically, $\lambda_i = \boldsymbol{\eta} + \boldsymbol{\eta}_i$ and $\boldsymbol{\tau}_i = \boldsymbol{\tau} + \boldsymbol{\vartheta}_i$. Furthermore, they are mutually independent and independent of $v_{it}, \mathbf{e}_{it}, u_i^*$, and the common factors $d_t, \mathbf{f}_t, \forall i, t$. In particular, $\|\lambda_i\|$ and $\|\boldsymbol{\tau}_i\|$ are bounded with a finite second moment.

Assumption 4. The function of the determinants $h(\mathbf{z}'_{it}\boldsymbol{\delta})$ should be assumed to have finite first, second, and fourth moments and to be distributed independently of v_{it}, \mathbf{e}_{it} and $u_i^* \forall i, t$.

Assumption 1 is a standard distributional assumption for the stochastic frontier model.

Assumptions 2 – 4 are similar to the assumptions used in Pesaran (2006) for the panel model with multi-factor error structures.

We rewrite the stochastic frontier model (1) – (3) as

$$\begin{bmatrix} y_{it} \\ \mathbf{x}_{it} \end{bmatrix} = \begin{bmatrix} 1 & \boldsymbol{\beta}' \\ \mathbf{0} & \mathbf{I}_k \end{bmatrix} \begin{bmatrix} \alpha_i \\ \mathbf{A}_i \end{bmatrix} d_t + \begin{bmatrix} 1 & \boldsymbol{\beta}' \\ \mathbf{0} & \mathbf{I}_k \end{bmatrix} \begin{bmatrix} \lambda'_i \\ \boldsymbol{\tau}'_i \end{bmatrix} \mathbf{f}_t - \begin{bmatrix} u_{it} \\ \mathbf{0}_{(k \times 1)} \end{bmatrix} + \begin{bmatrix} v_{it} + \boldsymbol{\beta}' \mathbf{e}_{it} \\ \mathbf{e}_{it} \end{bmatrix}$$

or

$$\mathbf{Y}_{it} = \mathbf{B}'_i d_t + \mathbf{C}'_i \mathbf{f}_t - \mathbf{U}_{it} + \boldsymbol{\xi}_{it};$$

here $d_t = 1$. After taking the cross-sectional average under the equal weight, we have

$$\bar{\mathbf{Y}}_t = \bar{\mathbf{B}}' d_t + \bar{\mathbf{C}}' \mathbf{f}_t - \bar{\mathbf{U}}_t + \bar{\boldsymbol{\xi}}_t, \quad (9)$$

where $\bar{\mathbf{U}}_t = (\bar{u}_t, \mathbf{0}')'$ and $\bar{u}_t = N^{-1} \sum_{i=1}^N u_{it}$. In the light of Pesaran (2006), we obtain $\bar{\boldsymbol{\xi}}_t \xrightarrow{\mathbb{P}} 0$ and $\bar{\mathbf{C}} \xrightarrow{\mathbb{P}} \mathbf{C}$ as $N \rightarrow \infty$, where $\mathbf{C} = \begin{bmatrix} \boldsymbol{\lambda} & \boldsymbol{\tau} \end{bmatrix} \begin{bmatrix} 1 & \mathbf{0}' \\ \boldsymbol{\beta} & \mathbf{I}_k \end{bmatrix}$. Under the assumption $\text{Rank}(\bar{\mathbf{C}}) = r \leq k + 1$, it can be shown that

$$\mathbf{f}_t - (\mathbf{C}\mathbf{C}')^{-1} \mathbf{C} (\bar{\mathbf{Y}}_t - \bar{\mathbf{B}}' d_t + \bar{\mathbf{U}}_t) \xrightarrow{\mathbb{P}} 0. \quad (10)$$

Thus, the set $\{\mathbf{D}, \bar{\mathbf{y}}, \bar{\mathbf{X}}, \bar{\mathbf{U}}\}$ can be regarded as the proxy of the factor structure. Based on Pesaran (2006), to proxy the common factors in our model, we could use

$$\bar{\mathbf{H}}^* = [\mathbf{D} \quad \bar{\mathbf{y}} \quad \bar{\mathbf{X}} \quad \bar{\mathbf{u}}].$$

Notice that u_i^* is not observed in the data. To overcome this problem, we propose using $\bar{h}_0 \mu_0^+$ as a proxy for $\bar{\mathbf{u}}$. Under Assumptions 1 and 4, we have

$$\bar{u}_t - \bar{h}_{t,0} \mu_0^+ \xrightarrow{\mathbb{P}} 0$$

as $N \rightarrow \infty$, where $\bar{\mathbf{h}}_0 = (\bar{h}_{1,0}, \dots, \bar{h}_{T,0})'$. It follows that

$$\mathbf{f}_t - (\mathbf{C}\mathbf{C}')^{-1} \mathbf{C} \left(\bar{\mathbf{Y}}_t - \bar{\mathbf{B}}' d_t + \begin{bmatrix} \bar{h}_{t,0} \mu_0^+ \\ \mathbf{0} \end{bmatrix} \right) \xrightarrow{\mathbb{P}} 0. \quad (11)$$

By substituting $\bar{\mathbf{h}}_0\mu_0^+$ in $\bar{\mathbf{H}}^*$, we obtain

$$\bar{\mathbf{H}}_0 = [\mathbf{D} \quad \bar{\mathbf{y}} \quad \bar{\mathbf{X}} \quad \bar{\mathbf{h}}_0\mu_0^+].$$

The transformed matrix which consists of $\bar{\mathbf{H}}_0$ could work because we construct this matrix by using the true value of $\boldsymbol{\delta}$ and μ^+ . However, it is not reasonable to assume that we know these values *ex ante*. Therefore, we shall prove that the deviation of $\boldsymbol{\delta}$ and μ^+ should lead to the transformed log-likelihood function not converging to the correctly specified log-likelihood function and being less than it with probability one when this deviation does not vanish as the sample size increases. To show this property, we define two log-likelihood functions after transformation by using the transformed matrices $\bar{\mathbf{M}}_0$ and $\bar{\mathbf{M}}$. In contrast to $\bar{\mathbf{M}}_0$, here, $\bar{\mathbf{M}}$ denotes the transformed matrix which is evaluated at estimated $\boldsymbol{\delta}$ and μ^+ . The first of these two functions is the correctly specified log-likelihood function considering the time-varying decision-independent heterogeneity,

$$\begin{aligned} Q_{NT}(\boldsymbol{\theta}) = & (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (T-s) (\ln(2\pi) + \ln \sigma_v^2) \right. \\ & - \frac{1}{2} (\mathbf{y}_i - \mathbf{X}_i\boldsymbol{\beta} - \mathbf{F}_0\boldsymbol{\lambda}_{i,0})' \bar{\mathbf{M}}\Pi^{-1}\bar{\mathbf{M}} (\mathbf{y}_i - \mathbf{X}_i\boldsymbol{\beta} - \mathbf{F}_0\boldsymbol{\lambda}_{i,0}) \\ & \left. + \frac{1}{2} \left(\frac{\mu_c^2}{\sigma_*^2} - \frac{\mu^2}{\sigma_u^2} \right) + \ln \left(\sigma_* \Phi \left(\frac{\mu_c}{\sigma_*} \right) \right) - \ln \left(\sigma_u \Phi \left(\frac{\mu}{\sigma_u} \right) \right) \right\}, \end{aligned} \quad (12)$$

where $\mu_c = \frac{\mu/\sigma_u^2 + (\mathbf{y}_i - \mathbf{X}_i\boldsymbol{\beta} - \mathbf{F}_0\boldsymbol{\lambda}_{i,0})' \bar{\mathbf{M}}\Pi^{-1}\bar{\mathbf{M}}\mathbf{h}_i}{\mathbf{h}_i' \bar{\mathbf{M}}\Pi^{-1}\bar{\mathbf{M}}\mathbf{h}_i + 1/\sigma_u^2}$. The second one is the log-likelihood function ignoring this heterogeneity,

$$\begin{aligned} \tilde{Q}_{NT}(\boldsymbol{\theta}) = & (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (T-s) (\ln(2\pi) + \ln \sigma_v^2) \right. \\ & - \frac{1}{2} (\mathbf{y}_i - \mathbf{X}_i\boldsymbol{\beta})' \bar{\mathbf{M}}\Pi^{-1}\bar{\mathbf{M}} (\mathbf{y}_i - \mathbf{X}_i\boldsymbol{\beta}) \\ & \left. + \frac{1}{2} \left(\frac{\mu_*^2}{\sigma_*^2} - \frac{\mu^2}{\sigma_u^2} \right) + \ln \left(\sigma_* \Phi \left(\frac{\mu_*}{\sigma_*} \right) \right) - \ln \left(\sigma_u \Phi \left(\frac{\mu}{\sigma_u} \right) \right) \right\}. \end{aligned} \quad (13)$$

The main differences between these two functions can be disclosed as follows. In (12), since we assume that the factor structure is known *ex ante* in both factors and corresponding loadings, the model can be correctly specified without ignoring the effects of the factor

structure. Thus, the factor structure appears in the second line of (12) which is the same as the well-known normal distribution with location (mean) and scale (variance) parts. On the other hand, the log-likelihood function defined in (13) is more realistic because we usually cannot observe these factors and their corresponding effects. Thus, the factor structure does not come out in the location part and μ_* of (13). We replace μ_* by μ_c in the third line to characterize the truncated property. This log-likelihood function is “feasible” because the difference between (12) and (13) can be ignored under assumptions 1 – 4 and some regular conditions,

Assumption 5. (i) Let $Q_0(\boldsymbol{\theta}) = \mathbb{E}[Q_{NT}(\boldsymbol{\theta})]$, $\tilde{Q}_0(\boldsymbol{\theta}) = \mathbb{E}[\tilde{Q}_{NT}(\boldsymbol{\theta})]$, and $Q_0(\boldsymbol{\theta})$ is uniquely maximized at $\boldsymbol{\theta}_0$; (ii) Θ is compact; (iii) Q_0 and \tilde{Q}_0 are continuous at $\boldsymbol{\theta}$; and (iv) $Q_{NT}(\boldsymbol{\theta})$ and $\tilde{Q}_{NT}(\boldsymbol{\theta})$ converge uniformly in probability to $Q_0(\boldsymbol{\theta})$ and $\tilde{Q}_0(\boldsymbol{\theta})$, respectively.

We state the main properties of these two functions in the following proposition.

Proposition 1. Let $\mathbb{B} = \{\boldsymbol{\theta}_0 + b_{NT}\mathbf{d} : \|\mathbf{d}\| \leq K\}$, where b_{NT} converges to 0 as $N, T \rightarrow \infty$, along with Assumptions 1-5, the “feasible” log-likelihood function has the following properties:

1. $|Q_{NT}(\boldsymbol{\theta}) - \tilde{Q}_{NT}(\boldsymbol{\theta})| \xrightarrow{\mathbb{P}} 0$ when $\boldsymbol{\theta} \in \mathbb{B}$.
2. $\mathbb{P}[Q_{NT}(\boldsymbol{\theta}_0) - \tilde{Q}_{NT}(\boldsymbol{\theta}) > 0] = 1$, when $\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta$,

as $N, T \rightarrow \infty$ jointly.

The first result of this proposition indicates that if we construct an open ball, \mathbb{B} , with the center $\boldsymbol{\theta}_0$ and its radius converging to zero, we can show that the “feasible” log-likelihood function is uniformly close to the correctly specified likelihood function for all $\boldsymbol{\theta} \in \mathbb{B}$. In addition, the second result implies that, with probability one, there is a positive difference between $Q_{NT}(\boldsymbol{\theta}_0)$ and $\tilde{Q}_{NT}(\boldsymbol{\theta})$, and it does not vanish as $N, T \rightarrow \infty$ if $\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta$. This implies that if we consider a candidate solution of $\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta$, named $\boldsymbol{\theta}'$, we have $Q_{NT}(\boldsymbol{\theta}_0) > \tilde{Q}_{NT}(\boldsymbol{\theta}')$ in probability one. In other words, $\boldsymbol{\theta}'$ is not the solution of the “feasible” likelihood function because we can always find another solution $\boldsymbol{\theta}'' \in \mathbb{B}$

which is closer to θ_0 to make $\tilde{Q}_{NT}(\theta'')$ close to $Q_{NT}(\theta_0)$. Consequently, these results lead to the following theorem about the consistency of the “feasible” log-likelihood function.

Theorem 1. *Assume that the conditions of Proposition 1 hold. Then $\tilde{\theta} \xrightarrow{\mathbb{P}} \theta_0$ as $N, T \rightarrow \infty$ jointly, where $\tilde{\theta}$ is obtained from maximizing the objective function $\tilde{Q}_{NT}(\theta)$.*

Theorem 1 shows that, instead of maximizing the correctly specified log-likelihood function, if we maximize the “feasible” log-likelihood function, then we can obtain a consistent estimator of θ_0 . Although it is expected that $\sqrt{NT}(\hat{\theta} - \theta_0)$ has asymptotic normality, derived from maximizing the correctly specified log-likelihood function in (12), the behavior of $\tilde{\theta}$ obtained from $\tilde{Q}_{NT}(\theta)$ is not trivial. Because the “feasible” function is an approximate function of the true one, we can not apply the traditional method, such as the mean value theorem, to obtain the asymptotic behavior of its estimator. Instead, we apply the framework which is used in Kristensen and Shin (2012). In their paper, they show that as long as the difference of two objective functions converges to zero faster than the usual convergence rate of estimators, for example root- NT , the two estimators obtained from these two functions will share the same asymptotic behavior. Furthermore, since the property of smoothness in log-likelihood function $\tilde{Q}_{NT}(\theta)$ is the same as $Q_{NT}(\theta)$, both of them have the same rate of convergence, root- NT . Therefore, in the following proposition, we show that under what conditions, the difference between $Q_{NT}(\theta)$ and $\tilde{Q}_{NT}(\theta)$, will converge to zero after multiplying by root- NT . We summarize the result of the requirement to ensure a stronger convergence of $Q_{NT}(\theta)$ and $\tilde{Q}_{NT}(\theta)$ as follows:

Proposition 2. *Using the assumptions in Proposition 1 we have the following result:*

$$\sqrt{NT}|Q_{NT}(\theta) - \tilde{Q}_{NT}(\theta)| \xrightarrow{\mathbb{P}} 0 \text{ when } \theta \in \mathbb{B} \text{ and } b_{NT} = o_p(C_{NT}), \text{ where } C_{NT} = \min\{N^{-1/2}, T^{-1/2}, (NT)^{-1/4}\}, \text{ as } N, T \rightarrow \infty \text{ jointly and } T/N \rightarrow 0.$$

This result discloses the required converge rate of b_{NT} to guarantee the stronger convergence property of $Q_{NT}(\theta)$ and $\tilde{Q}_{NT}(\theta)$. This minimum rate of convergence is slower than the converge rate of estimators $\hat{\theta}$ and $\tilde{\theta}$ and therefore proves the hold of the property of Proposition 2 in our “feasible” log-likelihood function. That is, the difference between $Q_{NT}(\theta)$ and $\tilde{Q}_{NT}(\theta)$ after multiplying by root- NT converges to 0 as $N, T \rightarrow \infty$ jointly

and $T/N \rightarrow 0$. This result is crucial because it can be used to show that the asymptotic behavior of $\tilde{\boldsymbol{\theta}}$ is asymptotically equivalent to $\hat{\boldsymbol{\theta}}$ obtained from $Q_{NT}(\boldsymbol{\theta})$ by using Lemma 1 in the Appendix. We state the above result as the following theorem.

Theorem 2. *Using the assumptions in Theorem 1 and an additional assumption (L1): $Q_0(\boldsymbol{\theta})$ is three times continuously differentiable and its derivatives satisfying: (i) $\sqrt{NT}\mathcal{S}(\boldsymbol{\theta}_0) \xrightarrow{D} N(\mathbf{0}, \{E[-\mathcal{H}(\boldsymbol{\theta}_0)]\}^{-1})$; (ii) $\mathcal{H}(\boldsymbol{\theta}_0) \xrightarrow{\mathbb{P}} E[\mathcal{H}(\boldsymbol{\theta}_0)]$; (iii) $\max_{j=1, \dots, d} \sup_{\boldsymbol{\theta}} \|\frac{\partial Q_0(\boldsymbol{\theta})}{\partial \boldsymbol{\theta} \partial \boldsymbol{\theta}' \partial \boldsymbol{\theta}_j}\| = O_p(1)$, we have the following result:*

$$\sqrt{NT}(\tilde{\boldsymbol{\theta}} - \boldsymbol{\theta}_0) \xrightarrow{D} N(\mathbf{0}, \{E[-\tilde{\mathcal{H}}(\boldsymbol{\theta}_0)]\}^{-1}), \text{ and } E[\tilde{\mathcal{H}}(\boldsymbol{\theta}_0)] \xrightarrow{\mathbb{P}} E[\mathcal{H}(\boldsymbol{\theta}_0)],$$

as $N, T \rightarrow \infty$ jointly and $T/N \rightarrow 0$. Here, $\mathcal{S}(\boldsymbol{\theta}_0) = \frac{\partial Q_0(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}}|_{\boldsymbol{\theta}_0}$, and $\tilde{\mathcal{H}}(\boldsymbol{\theta}_0)$ is the Hessian matrix of $\tilde{Q}_0(\boldsymbol{\theta})$ and $\mathcal{H}(\boldsymbol{\theta}_0)$ is the Hessian matrix of $Q_0(\boldsymbol{\theta})$ at $\boldsymbol{\theta}_0$, respectively.

Compared with ALS, MSS, and Filippini and Tosetti, our estimation allows us to focus on z_{it} that is concerned with measuring inefficiency and to treat time-varying decision-independent heterogeneity as a part of the factor structure which can be filtered out by our transformation. According to the above asymptotic properties, our estimation still have asymptotic normality and is asymptotically equivalent to the function which treats the factor structure as the observed structure. Furthermore, the GMM-type(including OLS) method can not distinguish between time-varying decision-independent heterogeneity and technical inefficiency.

2.4 The Inefficiency Index

It is important to measure the inefficiency index in applications. How, then, can the inefficiency index be estimated after the proposed transformation? We follow Wang and Ho (2010), who use the conditional expectation estimator proposed by Jondrow et al. (1982), namely, $E(\mathbf{u}_i|\boldsymbol{\varepsilon}_i)$ evaluated at $\boldsymbol{\varepsilon}_i = \hat{\boldsymbol{\varepsilon}}_i$, to construct the inefficiency index. In the same manner, the inefficiency index in our estimation is the conditional expectation of u_{it} on the vector of the transformed $\boldsymbol{\varepsilon}_i = \mathbf{v}_i - \mathbf{u}_i$, i.e., $\bar{\mathbf{M}}\boldsymbol{\varepsilon}_i$. Note that $\bar{\mathbf{M}}\boldsymbol{\varepsilon}_i$ is evaluated at

$\widehat{\mathbf{M}\boldsymbol{\varepsilon}_i}$, and following Wang and Ho (2010), the conditional inefficiency index is

$$\mathbb{E}(\mathbf{u}_i | \widehat{\mathbf{M}\boldsymbol{\varepsilon}_i}) = h(\mathbf{z}'_i \boldsymbol{\delta}) \left[\mu_* + \frac{\phi\left(\frac{\mu_*}{\sigma_*}\right) \sigma_*}{\Phi\left(\frac{\mu_*}{\sigma_*}\right)} \right] \quad (14)$$

3 Monte Carlo Simulations

In this section, we conduct Monte Carlo simulations to investigate the finite sample properties of our proposed estimator. Consider the following stochastic production frontier model for $i = 1, \dots, N$ and $t = 1, \dots, T$:

$$y_{it} = \alpha_i + x_{it}\beta + \boldsymbol{\lambda}'_i \mathbf{f}_t + v_{it} - \exp(\mathbf{z}'_{it} \boldsymbol{\delta}) u_i^* \quad (15)$$

$$x_{it} = \mathbf{A}_i + \boldsymbol{\tau}'_i \mathbf{f}_t + e_{it}, \quad (16)$$

where $\alpha_i \sim U(0, 1)$, x_{it} is a regressor, $\mathbf{f}_t \sim N(0, \sigma_f)$ is a common factor, $\sigma_f^2 = 0.2$, factor loadings $\boldsymbol{\lambda}_i$ and $\boldsymbol{\tau}_i$ follow $N(1, 0.2)$, and \mathbf{z}_{it} consists of $z_{it,1} \sim N(0, 1)$ and $z_{it,2} = t$, which implies that the inefficiency is time-varying, $v_{it} \sim N(0, \sigma_v^2)$, $u_i^* \sim N^+(\mu, \sigma_u^2)$, v_{it} and u_i^* are mutually independent, and $e_{it} \sim N(0, 1)$. The parameter values are

$$(\beta, \delta_1, \delta_2, \sigma_v^2, \sigma_u^2, \mu) = (0.5, 0.5, 0.1, 0.1, 0.2, 0.5).$$

$N = \{50, 100, 200, 400\}$, $T = \{5, 10, 20\}$, and the number of replications is 1,000 in all simulations.

To demonstrate the importance of our transformation in the presence of time-varying decision-independent heterogeneity, we also compare our method with the estimation which only takes the fixed effects into account by means of the Within transformation. Hereafter, we let Within denote the latter method and let CCE denote our estimator.

Our simulation results are reported in Table 1. We find that CCE tends to have a smaller bias than Within for all parameters over all combinations of (N, T) except for δ_2 when $T = 5$. Moreover, CCE uniformly has a smaller RMSE than Within as $T \geq 10$. Even when $T = 5$, the RMSE ratios, $\psi = \text{RMSE(Within)}/\text{RMSE(CCE)}$, increase with

the increase in N . For example, the ψ of $\hat{\delta}$ is 0.614 when $(N, T) = (50, 5)$ and increases to 1.036, which indicates that CCE has a smaller RMSE than Within by 3.6%, when $(N, T) = (50, 5)$. It is also worth noting that the bias and the RMSE of CCE decline as T or N increases for all parameters. By contrast, due to failing to control for the time-varying decision-independent heterogeneity, the Within estimators of β and δ are still biased and cannot be improved even when T or N is large.

For robustness, we further consider the finite sample performance for different degrees of cross-sectional correlation by adjusting the magnitude of σ_f . In particular, we consider three settings with $\sigma_f^2 = 0.1, 1$ and 0 , respectively. As we can see from model (1), when σ_f is smaller, our model is closer to the model with fixed effects only and the time-varying decision-independent heterogeneity become less important. The last case implies the model which has only fixed effects. Furthermore, instead of letting $z_{it,2} = t$ in $h(z'_{it}\delta)$, we consider group-specific inefficiency by letting $z_{it,2}$ be a group dummy such that $z_{it,2} = 1$ for any unit in Group 2; otherwise $z_{it,2} = 0$. The members in Group 1 are randomly assigned in each repetition with the number of units $N_1 = \lfloor U(0.3, 0.7) \times N \rfloor$, regardless of whether $\lfloor A \rfloor$ is the integer closest to A . The other group has $N - N_1$ units. The group membership is known in advance. The parameters in this set of simulations take the following values

$$(\beta, \delta_1, \delta_2, \sigma_v^2, \sigma_u^2, \mu) = (0.5, 0.5, 0.1, 0.1, 0.2, 0.5).$$

The results are summarized in Tables 2 and 3 with $T = \{10, 20\}$, respectively. Since we have similar patterns to the previous simulation, that is, the bias and the RMSE of CCE decline as T or N increases, we do not report the case when $T = 5$. It will be clear from these results that the bias for Within seems to be less serious as $\sigma_f^2 = 0.1$, and becomes more significant as $\sigma_f^2 = 1$. More importantly, the performance of our approach is generally better than that of Within approach even when $\sigma_f^2 = 0.1$, which demonstrates that our method is still robust even when the degree of time-varying property to decision-independent heterogeneity is small in the data. In particular, the estimates of σ_v^2 and σ_u^2 for the Within approach seem to be overestimated in the presence of the time-varying decision-independent heterogeneity. On the contrary, CCE provides less unbiased estimates even

when $\sigma_f^2 = 0.1$. However, the CCE estimator tends to be less efficient when the model only contains fixed effects.

We next consider the experiment in which both x_{it} and z_{it} are correlated with an unobservable common factor. We set $u_{it} = \exp(\mathbf{z}'_{it}\boldsymbol{\delta})u_i^*$ to ensure that u_{it} is positive. Let

$$\mathbf{z}_{it} = \boldsymbol{\gamma}'_i \mathbf{f}_t + \mathbf{e}_{z,it}, \quad (17)$$

and z_{it} is correlated with \mathbf{f}_t . We still have two variables $z_{1,it}$ and $z_{2,it}$ which can affect u_{it} . In particular, the factor loadings $\gamma_{i,1}$ and $\gamma_{i,2}$ follow $N(1, 0.4)$ and $N(1, 0.2)$, respectively, $\mathbf{f}_t \sim N(0, 0.6)$ to indicate that the factor is important in this model, and each of $\mathbf{e}_{z,it}$ follows $N(0, 1)$. x_{it} is similar to the former setting. The parameters in this set of simulations take the following values

$$(\beta, \delta_1, \delta_2, \sigma_v^2, \sigma_u^2, \mu) = (0.5, 0.2, -0.1, 0.1, 0.1, 0.4).$$

Table 4 summarizes the simulation results. A general finding is that our proposed method is relatively much better than Within in all combinations. The bias is almost 0 in CCE except for σ_u^2 , whereas the bias of Within is serious not only for β but also for the δ 's. Notice that the small bias of σ_u^2 in CCE will decrease as N increases. On the contrary, the bias of σ_u^2 in Within is enormous, and it is not surprising because Within does not control the time-varying decision-independent heterogeneity, and the components from the biased \hat{h}_{it} will induce large variations in u_i^* .

In general, the simulation shows the clear results that the estimation without controlling the time-varying decision-independent heterogeneity will bias the estimates. We also conduct a similar simulation for the cost frontier model, which is not reported here. Its pattern again confirms the importance of taking the time-varying decision-independent heterogeneity into account in a stochastic frontier model and the findings are similar to the findings summarized in Tables 1 – 4.

4 Empirical Study

In the years leading up to the 2008 financial crisis, banks in the U.S. suffered from a difficult environment. Given that this crisis was induced by a rise in subprime mortgage delinquencies and foreclosures, a key question that arises concerns for the performance before the said crisis of the banks in the U.S., two basic types of banks co-exist in the market, namely, savings and commercial banks. These two types are generally characterized by their ownership structure and by the services they provide. In the U.S., savings institutions may be owned by shareholders (stock), or by their depositors and borrowers (mutual). Based on the agency theory and property rights theory addressed by the seminal works of Jensen and Meckling (1976) and Fama and Jensen (1983), in contrast to commercial banks which are generally stock corporations, savings banks may not appear to engage in skimping behavior. Particularly in the period before the crisis, as we know, savings banks had to hold a certain proportion of their loan portfolio in housing-related assets to preserve their charter. Therefore, these savings banks faced the problem of overbuilding during the boom period, which resulted in their increasing loans, as well as inappropriate government regulation before the financial crisis. In particular, more and more loans to higher-risk borrowers were offered by the lenders, thus revealing the inappropriate managerial behavior of savings banks before the crisis.

Another aim of this paper is to examine the change in efficiency that resulted from the banking consolidation. According to data compiled by the Federal Deposit Insurance Corporation (FDIC), the number of commercial banks had fallen to 6,279 at the end of 2011, a drop about 49.1% since 1990. Similarly, the number of savings institutions fell from 2,815 to 1,067 over the same period. There is still a debate between the issues of efficiency and the banking consolidation. In general, the consolidation will increase the market power, and therefore lead to a decline in competition. From the viewpoint of competitive efficiency, the efficiency of banks should be lower in this scenario. Put differently, an increase in competition will wear the bank's pricing power away, and increase the bank's risk taking behavior; see Berger et al. (2009b) and Beck, Jonghe and Schepens (2013). Hence, an increase in competition could lead to lower profit and higher cost under the same allocation of inputs; in other words, cost inefficiency. To explore the relationship

between banking consolidation and efficiency, we focus on the banks which have not failed or have merged with other banks. In other words, we collect data for the banks that have existed over the whole sample period under consideration. By building on this situation, we can show, on average, the effects of consolidation without the failed banks .

4.1 Data

We evaluate the cost efficiency of commercial and savings banks in the U.S. by using the proposed transformation allowing for the time-varying decision-independent heterogeneity in the stochastic frontier model. The conventional intermediation approach to measuring the cost faced by a bank is used in this study. Total cost is defined as the sum of interest expenses and non-interest expense. Following Berger et al. (2009a) and Sun and Chang (2010), we consider the following output variables in the cost function: total loans (TL), other earning assets (OEA), total deposits (TD) and liquid assets (LA). We additionally consider the price of capital (PC) and funds (PF), defined by the ratio of non-interest expenses to total fixed assets and the ratio of interest expenses to total deposits, respectively, as our input prices. In order to guarantee linear homogeneity in the input prices of the cost function, we re-scale TC and PC by PF.

The cost function used here is

$$\begin{aligned} \ln \left(\frac{\text{TC}}{\text{PF}} \right)_{it} &= \beta_0 \ln \left(\frac{\text{PC}}{\text{PF}} \right)_{it} + \beta_1 \ln \text{TL}_{it} + \beta_2 \ln \text{OEA}_{it} \\ &+ \beta_3 \ln \text{TD}_{it} + \beta_4 \ln \text{LA}_{it} + \boldsymbol{\lambda}_i \mathbf{f}_t + v_{it} + u_{it}. \end{aligned} \quad (18)$$

To allow the inefficiency across banks to be measured by explanatory variables, we use the scaling function proposed by Wang and Schmidt (2002). The specification of the scaling function is as follows

$$h(z'_{it}\delta) = \exp(\delta_1 \ln \text{TA}_{it} + \delta_2 \text{ETA}_{it} + \delta_3 \text{ROAA}_{it} + \text{Type}), \quad (19)$$

where TA denotes the total assets less liquid assests, ETA denotes the equity to assets, and ROAA denotes the return on average assets. These three variables are commonly

used to control the efficiency. TA measures the relationship between the efficiency and the size of the bank. ETA can represent the equity position of a bank and avoid the scale bias making large banks more efficient (Berger and Mester, 1997). In addition, ETA may reflect the risk preference of a manager of a bank. ROAA can be regarded as a proxy for manager ability. A type dummy variable is also included to capture the effect of different of types of banks.

We consider a balanced panel data set covering 1994-2007 with 223 banks in the U.S. The data are taken from Bankscope and are inflation-adjusted. Except for ETA and ROAA, all the other variables are transformed into natural logs. Table 5 presents the descriptive statistics of these variables.

4.2 Empirical Results

The empirical results obtained by our approaches are summarized in the right panel of Table 6. We report not only the estimates of the coefficients in the cost function β 's, but also the estimates of the parameters in the inefficiency equation δ 's. For comparison purposes, we additionally show the results based on the Within approach in the left panel of Table 6.⁹

Let us consider the coefficients in the cost function using our approach first. The coefficient of the input prices (PC/PF) is positive at the 1% significance level, which indicates that a higher capital cost results in a higher total cost and is similar to the empirical results of Lensink et al. (2008) and Sun and Chang (2010). As expected, the output variables, such as TL, TD and LA, also have positive effects on the total cost. While the estimated coefficient of OEA is negative, it has a rather small effect in contrast to other variables. The empirical results from the Within approach are qualitatively similar to those based on our CCE approach. However, the former tends to deliver smaller estimated coefficients of TL, TD and LA than our approach.

Next, we turn our focus to the coefficients of the inefficiency equation. The coefficient for TA, equal to -0.202, is negative and significant at the 1% level, which implies that

⁹We also consider the trend effects while implementing the Within approach by adding t and t^2 along with intercept to form the idempotent matrix \mathbf{M} .

larger banks are on average more efficient than smaller banks as TA is regarded as a proxy for bank size. The estimated sign of this coefficient is different from that in Han et al. (2005) and Sun and Chang (2010). However, Delis and Papanikolaou (2009) pointed out that the relationship between bank size and efficiency is inverse U-shaped, which implies that the efficiency increases with size and then decreases thereafter. In our data, almost 90% of banks are small and medium-sized and, therefore, are more likely to have a positive relationship with efficiency.¹⁰ In addition, our results indicate that an increase in ETA will raise inefficiency, which can be explained in two ways. First, ETA can be regarded as a proxy for the risk-preference of a manager. A higher equity position reveals that the manager is risk-averse and might not be good at using financial leverage to increase the size of a bank, which indicates that the manager may not seek to minimize the cost. Second, inefficiency will lead to a lower profit and put equity in a high position. Furthermore, the negative relationship between ROAA and inefficiency is also in line with Lensink et al. (2008).

Although the ROAA should exhibit a negative relationship with inefficiency as pointed out by Lensink et al. (2008), we can not find strong evidence to link ROAA with efficiency, even if the sign is negative and has only a very slight effect.

Furthermore, the type dummy variable for identifying the different performance shows the positive effects on commercial banks. The effect is not only statistically, but also economically large. The result shown in the table is equal to -0.263, which provides strong evidence to show that savings banks are less efficient than their commercial counterparts. It supports the view that savings banks had poor managerial behavior before the crisis when they faced overbuilding during the boom period, increasing loans and inappropriate government regulation and did not tend to minimize their costs. On the contrary, commercial banks were more efficient.

Comparing the results of different approaches further reflects the importance of controlling the time-varying decision-independent heterogeneity in the stochastic frontier model. The second column of the table from the alternative approach which only takes account

¹⁰Following Berger et al. (2009a), the classification of bank size is defined as follows. The bank's size is considered to be small if its assets are less than or equal to \$1 billion, its size is medium if the bank's assets are greater than \$1 billion but less than \$20 billion, and the bank is large if its assets exceed \$20 billion.

of the fixed effects provides different results. It shows that the effects of ETA, ROAA and the type dummy are completely opposite to our results. Despite the ETA, it is uncanny to explain the relationship between ROAA and efficiency that is negative.¹¹ Moreover, the result goes against the traditional concept, which implies that the savings banks are efficient. Notice that our CCE approach is consistent and has satisfactory finite sample performance even when there do not exist any or only small time-varying decision-independent heterogeneity as shown in the previous sections. Thus, the different estimated value based on the Within approach appears to reflect the fact that the time-varying decision-independent heterogeneity have been ignored.

Finally, we further compare the pattern of cost efficiency of the savings and commercial banks. Figure 1 plots the average cost efficiency of each group over the 1994-2007 period. Both the Within and CCE approaches exhibit an upward trend for the savings and commercial banks, which implies that the banking industry operates more efficiently under consolidation. This result may support the view that most U.S. banks have faced increasing returns as recently discussed by Wheelock and Wilson (2012). However, the pattern further shows that the difference between savings and commercial banks is relatively small by using the Within approach rather than the CCE approach. As the figure illustrates, savings banks are even more efficient than commercial banks based on the Within estimation. As we discussed before, the efficiency may be affected by ignoring the time-varying decision-independent heterogeneity, which leads to bias in the estimated efficiency.

5 Concluding Remarks

Many studies have revealed the importance of distinguishing fixed effects from inefficiency. However, such research fails to consider the possibility that the specific heterogeneity can have the time-varying property. In this paper, a stochastic frontier model with factor structure is developed to capture the time-varying decision-independent heterogeneity which is irrelevant to inefficiency and explain the cross-sectional dependence among individual

¹¹This result is the same as that of Sun and Chang (2010), while it might arise due to endogeneity.

firms. The novel feature of our model is that it distinguishes the time-varying “decision-independent” heterogeneity and “technical inefficiency” according to a more fundamental definition of inefficiency mentioned by Koopmans (1951). The proposed maximum likelihood method by model transformation does not require estimating unobserved time-varying decision-independent heterogeneity. With the CCE transformation, we can control the time-varying decision-independent heterogeneity and obtain consistent estimates of parameters for the panel stochastic frontier model. Our Monte Carlo simulations show that the modified MLE has satisfactory finite sample properties under a significant degree of cross-sectional dependence for relatively small T . The desirable results and computational ease should appeal to empirical researchers.

Table 1: Simulation results with cross-section dependence

	T = 5						T = 10						T = 20			
	Within		CCE		ψ	Within		CCE		ψ	Within		CCE		ψ	
	Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE		
$N = 50$																
$\hat{\beta}$	0.125	0.150	-0.002	0.058	2.596	0.146	0.159	0.000	0.021	7.695	0.155	0.162	0.000	0.012	13.170	
$\hat{\delta}_1$	-0.010	0.127	0.008	0.208	0.614	-0.002	0.080	-0.002	0.060	1.335	0.000	0.025	0.000	0.015	1.683	
$\hat{\delta}_2$	0.002	0.095	0.032	0.122	0.778	-0.002	0.021	0.001	0.013	1.565	0.000	0.005	0.000	0.002	2.729	
$\hat{\sigma}_v^2$	0.166	0.202	-0.013	0.030	6.663	0.191	0.209	0.000	0.009	23.053	0.199	0.209	0.006	0.009	23.839	
$\hat{\sigma}_u^2$	0.049	0.239	0.039	0.279	0.856	0.031	0.159	0.007	0.116	1.372	0.006	0.086	-0.003	0.070	1.232	
$\hat{\mu}$	0.068	0.263	0.014	0.285	0.924	0.020	0.208	-0.001	0.154	1.347	-0.007	0.137	-0.002	0.113	1.221	
$N = 100$																
$\hat{\beta}$	0.129	0.155	0.000	0.040	3.921	0.147	0.159	0.000	0.014	11.573	0.154	0.161	0.000	0.008	19.771	
$\hat{\delta}_1$	-0.027	0.109	-0.005	0.147	0.739	-0.002	0.071	0.001	0.039	1.800	0.001	0.023	0.000	0.010	2.203	
$\hat{\delta}_2$	-0.006	0.086	0.020	0.095	0.903	-0.002	0.019	0.000	0.010	1.906	0.000	0.005	0.000	0.001	3.499	
$\hat{\sigma}_v^2$	0.177	0.214	-0.009	0.022	9.859	0.194	0.211	0.000	0.006	33.560	0.201	0.210	0.003	0.005	40.385	
$\hat{\sigma}_u^2$	0.060	0.218	0.059	0.256	0.853	0.019	0.111	0.003	0.073	1.514	0.005	0.069	-0.003	0.051	1.348	
$\hat{\mu}$	0.096	0.231	-0.004	0.240	0.963	0.026	0.173	0.004	0.106	1.642	-0.003	0.111	-0.001	0.079	1.412	

Table 2: Simulation results with cross-section dependence under different σ_f

$(T=10)$	$\sigma_f^2 = 0$ (only fixed effects)					$\sigma_f^2 = 0.1$					$\sigma_f^2 = 1$				
	Within		CCE			Within		CCE			Within		CCE		
$N = 50$	Bias	RMSE	Bias	RMSE	ψ	Bias	RMSE	Bias	RMSE	ψ	Bias	RMSE	Bias	RMSE	ψ
$\hat{\beta}$	0.000	0.015	0.000	0.020	0.776	0.087	0.097	-0.001	0.020	4.963	0.433	0.446	-0.000	0.019	24.016
$\hat{\delta}_1$	0.001	0.031	0.004	0.066	0.478	0.001	0.075	0.006	0.077	0.971	0.014	0.126	0.002	0.074	1.694
$\hat{\delta}_2$	0.000	0.007	0.000	0.016	0.446	0.001	0.200	-0.003	0.232	0.862	0.015	0.280	0.004	0.216	1.299
$\hat{\sigma}_v^2$	0.000	0.007	-0.002	0.009	0.763	0.109	0.119	-0.001	0.009	13.655	0.592	0.604	-0.001	0.009	67.373
$\hat{\sigma}_u^2$	0.012	0.103	0.012	0.129	0.801	0.017	0.152	0.009	0.151	1.008	0.077	0.258	0.017	0.158	1.629
$\hat{\mu}$	-0.020	0.150	-0.009	0.172	0.870	0.007	0.182	0.010	0.181	1.006	-0.038	0.226	-0.003	0.177	1.272
$N = 100$	Within		CCE			Within		CCE			Within		CCE		
	Bias	RMSE	Bias	RMSE	ψ	Bias	RMSE	Bias	RMSE	ψ	Bias	RMSE	Bias	RMSE	ψ
$\hat{\beta}$	0.000	0.011	0.000	0.014	0.781	0.089	0.098	-0.000	0.014	7.041	0.427	0.439	-0.001	0.014	31.009
$\hat{\delta}_1$	-0.001	0.022	0.005	0.049	0.458	0.001	0.052	0.001	0.050	1.037	0.002	0.096	-0.001	0.051	1.871
$\hat{\delta}_2$	0.000	0.005	-0.001	0.012	0.420	0.009	0.130	0.001	0.162	0.805	0.002	0.182	0.004	0.162	1.125
$\hat{\sigma}_v^2$	0.000	0.005	-0.001	0.006	0.816	0.112	0.123	-0.000	0.006	19.624	0.596	0.607	-0.000	0.006	98.686
$\hat{\sigma}_u^2$	0.003	0.064	0.000	0.081	0.786	0.009	0.103	0.009	0.105	0.982	0.082	0.229	0.011	0.107	2.143
$\hat{\mu}$	0.001	0.092	0.001	0.111	0.833	-0.009	0.128	-0.001	0.125	1.026	-0.040	0.192	-0.004	0.136	1.412

(continued)

$(T=10)$	$\sigma_f^2 = 0$ (only fixed effects)					$\sigma_f^2 = 0.1$					$\sigma_f^2 = 1$				
$N = 200$	Within		CCE		ψ	Within		CCE		ψ	Within		CCE		ψ
	Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE	
$\hat{\beta}$	0.000	0.008	0.000	0.010	0.789	0.089	0.096	-0.000	0.009	10.234	0.430	0.441	0.000	0.010	45.506
$\hat{\delta}_1$	0.000	0.015	-0.001	0.035	0.430	0.002	0.037	0.001	0.037	0.995	0.001	0.068	-0.002	0.037	1.845
$\hat{\delta}_2$	0.000	0.003	0.001	0.010	0.353	0.003	0.094	0.008	0.114	0.824	-0.007	0.133	-0.003	0.115	1.154
$\hat{\sigma}_v^2$	0.000	0.004	-0.001	0.005	0.765	0.111	0.121	0.000	0.004	28.167	0.597	0.608	-0.000	0.004	135.998
$\hat{\sigma}_u^2$	0.002	0.043	0.004	0.059	0.736	0.005	0.068	0.002	0.070	0.978	0.083	0.195	0.009	0.076	2.560
$\hat{\mu}$	-0.001	0.064	0.001	0.081	0.801	-0.008	0.088	-0.003	0.089	0.987	-0.060	0.152	0.003	0.087	1.754
$N = 400$	Within		CCE		ψ	Within		CCE		ψ	Within		CCE		ψ
	Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE	
$\hat{\beta}$	0.000	0.006	0.000	0.007	0.803	0.088	0.094	-0.000	0.007	13.411	0.426	0.438	0.000	0.007	65.428
$\hat{\delta}_1$	-0.001	0.011	0.001	0.026	0.416	0.003	0.026	0.001	0.024	1.068	-0.003	0.049	0.002	0.025	1.980
$\hat{\delta}_2$	0.000	0.002	0.000	0.009	0.283	0.002	0.067	-0.000	0.079	0.843	-0.007	0.094	0.004	0.077	1.229
$\hat{\sigma}_v^2$	0.000	0.003	0.000	0.003	0.808	0.109	0.119	-0.000	0.003	38.680	0.594	0.606	-0.000	0.003	193.373
$\hat{\sigma}_u^2$	0.001	0.032	-0.001	0.042	0.755	0.002	0.049	0.000	0.043	1.124	0.086	0.178	0.003	0.046	3.831
$\hat{\mu}$	0.001	0.043	0.000	0.056	0.761	-0.009	0.062	-0.002	0.063	0.986	-0.060	0.119	-0.008	0.060	1.963

¹ ψ is the ratio of RMSE(Within)/RMSE(CCE).² The true values of the parameter set are $\beta = 0.5$, $\delta_1 = 0.5$, $\delta_2 = 0.5$, $\sigma_v^2 = 0.1$, $\sigma_u^2 = 0.2$, and $\mu = 0.5$.

Table 3: Simulation results with cross-section dependence under different σ_f

$(T=20)$	$\sigma_f^2 = 0$ (only fixed effects)					$\sigma_f^2 = 0.1$					$\sigma_f^2 = 1$				
	Within		CCE		ψ	Within		CCE		ψ	Within		CCE		ψ
$N = 50$	Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE	
$\hat{\beta}$	0.000	0.011	0.001	0.012	0.912	0.089	0.094	0.000	0.011	8.272	0.447	0.453	0.000	0.012	38.062
$\hat{\delta}_1$	0.000	0.007	0.000	0.014	0.466	-0.002	0.044	-0.003	0.035	1.257	-0.000	0.089	-0.002	0.038	2.332
$\hat{\delta}_2$	0.000	0.001	0.000	0.002	0.759	0.000	0.171	-0.002	0.194	0.885	0.002	0.209	-0.006	0.193	1.084
$\hat{\sigma}_v^2$	0.000	0.005	-0.001	0.005	0.923	0.110	0.116	-0.000	0.005	22.063	0.626	0.631	-0.000	0.005	122.391
$\hat{\sigma}_u^2$	0.006	0.079	0.004	0.080	0.988	0.010	0.110	-0.001	0.101	1.096	0.054	0.207	-0.000	0.102	2.030
$\hat{\mu}$	-0.015	0.122	-0.014	0.124	0.988	0.001	0.141	0.015	0.130	1.080	-0.013	0.171	0.011	0.131	1.310
$N = 100$	Within		CCE		ψ	Within		CCE		ψ	Within		CCE		ψ
	Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE		Bias	RMSE	Bias	RMSE	
$\hat{\beta}$	0.000	0.008	0.000	0.009	0.909	0.089	0.093	0.000	0.008	11.114	0.443	0.448	0.000	0.008	53.979
$\hat{\delta}_1$	0.000	0.004	0.000	0.010	0.437	0.000	0.033	0.000	0.025	1.299	0.000	0.062	0.001	0.025	2.512
$\hat{\delta}_2$	0.000	0.001	0.000	0.001	0.778	0.002	0.118	-0.003	0.135	0.875	-0.008	0.140	-0.006	0.133	1.055
$\hat{\sigma}_v^2$	0.000	0.003	0.000	0.004	0.908	0.110	0.116	-0.000	0.004	31.880	0.629	0.635	-0.000	0.004	169.412
$\hat{\sigma}_u^2$	0.003	0.053	0.003	0.054	0.973	0.003	0.078	-0.002	0.069	1.127	0.041	0.148	-0.002	0.069	2.133
$\hat{\mu}$	-0.009	0.082	-0.008	0.085	0.974	-0.004	0.094	0.003	0.091	1.037	-0.018	0.125	0.004	0.087	1.428

(continued)

$(T=20)$	$\sigma_f^2 = 0$ (only fixed effects)					$\sigma_f^2 = 0.1$					$\sigma_f^2 = 1$				
	Within		CCE			Within		CCE			Within		CCE		
$N = 200$	Bias	RMSE	Bias	RMSE	ψ	Bias	RMSE	Bias	RMSE	ψ	Bias	RMSE	Bias	RMSE	ψ
$\hat{\beta}$	0.000	0.005	0.000	0.006	0.906	0.088	0.092	-0.000	0.006	16.425	0.442	0.447	-0.000	0.006	77.077
$\hat{\delta}_1$	0.000	0.003	0.000	0.007	0.437	-0.000	0.023	-0.000	0.017	1.314	-0.001	0.044	-0.000	0.017	2.558
$\hat{\delta}_2$	0.000	0.001	0.000	0.001	0.681	0.003	0.085	0.004	0.090	0.940	-0.003	0.101	-0.001	0.094	1.081
$\hat{\sigma}_v^2$	0.000	0.002	0.000	0.003	0.902	0.110	0.115	-0.000	0.003	44.603	0.631	0.636	0.000	0.003	244.367
$\hat{\sigma}_u^2$	0.000	0.035	0.000	0.037	0.966	0.005	0.052	-0.001	0.045	1.165	0.040	0.116	0.000	0.049	2.383
$\hat{\mu}$	-0.003	0.053	-0.003	0.054	0.977	-0.008	0.057	-0.001	0.053	1.067	-0.028	0.087	0.002	0.053	1.644

$N = 400$	Within		CCE			Within		CCE			Within		CCE		
	Bias	RMSE	Bias	RMSE	ψ	Bias	RMSE	Bias	RMSE	ψ	Bias	RMSE	Bias	RMSE	ψ
$\hat{\beta}$	0.000	0.004	0.000	0.004	0.906	0.088	0.091	-0.000	0.004	22.551	0.444	0.449	-0.000	0.004	107.029
$\hat{\delta}_1$	0.000	0.002	0.000	0.005	0.441	0.001	0.015	-0.000	0.012	1.291	0.001	0.030	0.000	0.013	2.374
$\hat{\delta}_2$	0.000	0.001	0.000	0.001	0.593	0.007	0.059	0.004	0.065	0.919	-0.003	0.075	-0.002	0.066	1.126
$\hat{\sigma}_v^2$	0.000	0.002	0.000	0.002	0.911	0.109	0.114	-0.000	0.002	62.508	0.635	0.639	0.000	0.002	354.291
$\hat{\sigma}_u^2$	0.001	0.025	0.001	0.026	0.956	0.002	0.035	0.001	0.032	1.097	0.031	0.082	0.001	0.033	2.524
$\hat{\mu}$	-0.002	0.040	-0.002	0.040	0.978	-0.010	0.040	-0.002	0.035	1.140	-0.031	0.067	-0.002	0.037	1.815

¹ ψ is the ratio of RMSE(Within)/RMSE(CCE).

² The true values of the parameter set are $\beta = 0.5$, $\delta_1 = 0.5$, $\delta_2 = 0.5$, $\sigma_v^2 = 0.1$, $\sigma_u^2 = 0.2$, and $\mu = 0.5$.

³ The bias is defined by (Estimated value - True Value).

Table 4: Simulation results: x and z are affected by an unobservable common shock ($T=20$).

	Within		CCE		ψ
	Bias	RMSE	Bias	RMSE	
$N = 50$					
$\hat{\beta}$	0.292	0.534	0.000	0.012	45.393
$\hat{\delta}_1$	-0.139	0.431	0.001	0.066	6.514
$\hat{\delta}_2$	0.102	0.373	0.001	0.037	10.198
$\hat{\sigma}_v^2$	1.507	9.953	-0.001	0.005	1837.170
$\hat{\sigma}_u^2$	34721.845	68882.385	1.412	13.975	4928.831
$\hat{\mu}$	0.038	0.225	0.036	0.234	0.959
	Within		CCE		
	Bias	RMSE	Bias	RMSE	ψ
$N = 100$					
$\hat{\beta}$	0.272	0.446	0.000	0.008	54.281
$\hat{\delta}_1$	-0.140	0.342	0.001	0.054	6.370
$\hat{\delta}_2$	0.089	0.304	0.000	0.028	10.693
$\hat{\sigma}_v^2$	0.917	3.523	-0.001	0.004	968.563
$\hat{\sigma}_u^2$	39725.677	76044.209	0.180	0.866	87785.493
$\hat{\mu}$	0.054	0.214	0.008	0.174	1.227
	Within		CCE		
	Bias	RMSE	Bias	RMSE	ψ
$N = 200$					
$\hat{\beta}$	0.287	0.486	-0.000	0.006	85.221
$\hat{\delta}_1$	-0.124	0.372	0.003	0.039	9.653
$\hat{\delta}_2$	0.093	0.288	-0.001	0.020	14.582
$\hat{\sigma}_v^2$	1.135	5.096	-0.000	0.003	2004.083
$\hat{\sigma}_u^2$	32871.244	65416.402	0.078	0.444	147318.408
$\hat{\mu}$	0.039	0.213	-0.011	0.106	2.004
	Within		CCE		
	Bias	RMSE	Bias	RMSE	ψ
$N = 400$					
$\hat{\beta}$	0.249	0.390	-0.000	0.004	95.194
$\hat{\delta}_1$	-0.136	0.349	-0.000	0.027	12.743
$\hat{\delta}_2$	0.098	0.230	0.000	0.014	16.608
$\hat{\sigma}_v^2$	0.856	2.493	-0.000	0.002	1348.341
$\hat{\sigma}_u^2$	40286.341	76224.203	0.050	0.319	238843.857
$\hat{\mu}$	0.048	0.213	-0.007	0.050	4.282

¹ ψ is the ratio of RMSE(Within)/RMSE(CCE).

² The true values of the parameter set are $\beta = 0.5$, $\delta_1 = 0.2$, $\delta_2 = -0.1$, $\sigma_v^2 = 0.1$, $\sigma_u^2 = 0.4$, and $\mu = 0.5$.

³ The bias is defined by (Estimated value - True Value).

Table 5: Statistics of variables used in the cost function

Variables	Mean	Std. Dev.	Min	Max
<i>Total Cost</i>	1.11×10^3	4.60×10^3	4.10	8.08×10^4
<i>Output quantities</i>				
Total loans	1.06×10^4	4.29×10^4	42.60	6.77×10^5
Other earning assets	5.77×10^3	3.30×10^4	0.50	6.92×10^5
Total deposits	1.20×10^4	5.21×10^4	1.80	7.94×10^5
Liquid assets	3.28×10^3	2.59×10^4	0.10	6.48×10^6
<i>Input prices</i>				
Price of capital	0.04	0.05	1.99×10^{-3}	1.24
Price of funds	5.29	1.48×10^3	0.34	7.56×10^4
<i>Other variables' quantity and ratios</i>				
Total assets	1.86×10^4	8.31×10^4	62.00	1.32×10^6
Return on average assets	1.32	1.20	-3.18	24.04
Equity to assets	9.77	5.39	4	82.36

¹ The variables in total cost and output quantities are measured in U.S. \$ millions.

² There are a total of 3,122 bank-year observations.

Table 6: Estimation results of the cost frontier

	Exp. Sign	Within		CCE	
		$\hat{\theta}$	Std. Dev.	$\hat{\theta}$	Std. Dev.
<i>Effects on cost function</i>					
ln(PC/PF)	(+)	0.371 ***	0.018	0.184 ***	0.006
ln(TL)	(+)	0.033 *	0.019	0.216 ***	0.015
ln(OEA)	(+)	0.002	0.018	-0.012 **	0.005
ln(TD)	(+)	0.696 ***	0.020	0.861 ***	0.014
ln(LA)	(+)	0.048 ***	0.018	0.027 ***	0.003
<i>Effects on inefficiency</i>					
ln(TA)	(?)	-0.347 ***	0.022	-0.202 ***	0.018
ETA	(+)	-0.166 **	0.018	0.068 ***	0.010
ROAA	(-)	0.470 ***	0.024	-0.005 ***	0.002
TYPE	(-)	0.117 ***	0.018	-0.263 ***	0.085
σ_v^2		0.153		0.004	
σ_u^2		518.796		38.127	

¹ * Significant at the 10% level, ** Significant at the 5% level and *** Significant at the 1% level.

² Exp. Sign explains the expected relationship between inefficiency and variables.

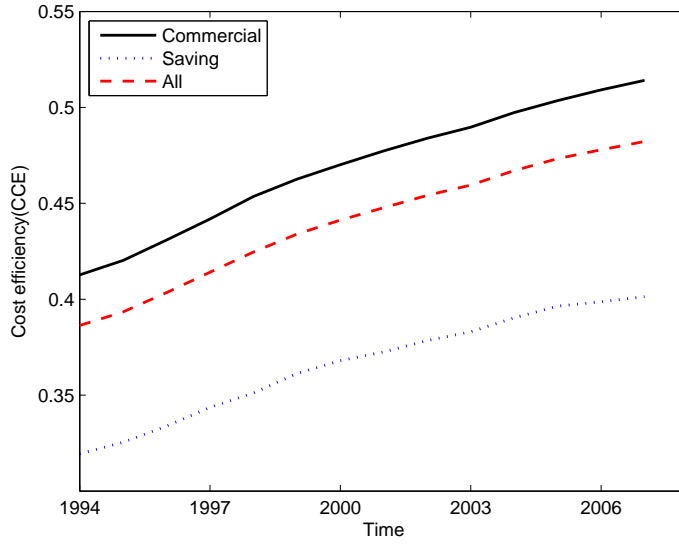
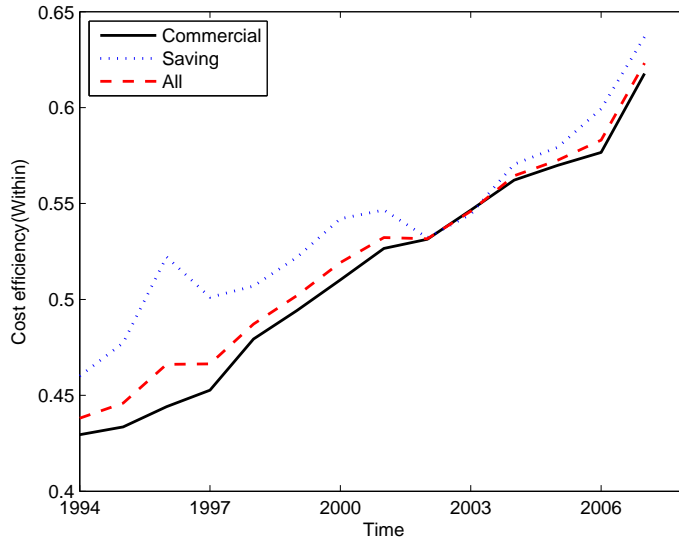


Figure 1: Average Cost Efficiency in All Banks

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Appendix A-Useful Lemmas

Below we introduce some useful lemmas for proving the main results in our paper. The proof can be founded in the Supplementary Material.

Assumption for Lemma 1:

(L1) $Q_0(\boldsymbol{\theta})$ is three times continuously differentiable with its derivatives satisfying

$$\begin{aligned}\sqrt{NT}S(\boldsymbol{\theta}_0) &\xrightarrow{D} N(\mathbf{0}, \{\mathbb{E}[-\mathcal{H}(\boldsymbol{\theta}_0)]\}^{-1}), \\ \mathcal{H}(\boldsymbol{\theta}_0) &\xrightarrow{P} \mathbb{E}[\mathcal{H}(\boldsymbol{\theta}_0)], \\ \max_{j=1,\dots,d} \sup_{\boldsymbol{\theta}} \left\| \frac{\partial Q_0(\boldsymbol{\theta})}{\partial \boldsymbol{\theta} \partial \boldsymbol{\theta}' \partial \boldsymbol{\theta}_j} \right\| &= O_p(1),\end{aligned}$$

where $S(\boldsymbol{\theta}_0) = \frac{\partial Q_0(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}}|_{\boldsymbol{\theta}_0}$ and $\mathcal{H}(\boldsymbol{\theta}_0) = \frac{\partial^2 Q_0(\boldsymbol{\theta})}{\partial \boldsymbol{\theta} \partial \boldsymbol{\theta}'}|_{\boldsymbol{\theta}_0}$.

Lemma 1. *As assumption (L1) holds with Θ which is compact, and $\sqrt{NT} \sup_{\boldsymbol{\theta}} |\tilde{Q}_{NT}(\boldsymbol{\theta}) - Q_{NT}(\boldsymbol{\theta})| = o_p(1)$ as $N, T \rightarrow \infty$. Then $\sqrt{NT}(\tilde{\boldsymbol{\theta}} - \boldsymbol{\theta}_0) \xrightarrow{D} N(\mathbf{0}, \{\mathbb{E}[-\mathcal{H}(\boldsymbol{\theta}_0)]\}^{-1})$, where $\tilde{\boldsymbol{\theta}}$ is obtained from maximizing the objective function $\tilde{Q}_{NT}(\boldsymbol{\theta})$.*

Throughout the following lemmas, we use the following notations: $\bar{\boldsymbol{\xi}} = (\bar{\boldsymbol{\xi}}_1, \dots, \bar{\boldsymbol{\xi}}_T)'$, $\boldsymbol{\xi}_i = (\boldsymbol{\xi}_{i1}, \dots, \boldsymbol{\xi}_{iT})'$, $\mathbf{v}_i = (v_{i1}, \dots, v_{iT})'$, $\bar{\mathbf{u}} = (\bar{u}_1, \dots, \bar{u}_T)'$, $\bar{\boldsymbol{\zeta}} = \bar{h}_0 \mu_0^+ - \bar{\mathbf{u}}$, $\bar{u}_i = T^{-1} \sum_{t=1}^T u_{it}$, $\bar{h}_i = T^{-1} \sum_{t=1}^T h_{it}$ and $\mathbf{G} = [\mathbf{D} \quad \mathbf{F} \quad \bar{\mathbf{u}}]$. Recall that $\bar{\mathbf{H}}_0 = [\mathbf{D}, \bar{\mathbf{y}}, \bar{\mathbf{X}}, \bar{h}_0 \mu_0^+]$, together with equation (9), $\bar{\mathbf{H}}_0$ can be rewritten as $\bar{\mathbf{H}}_0 = [\mathbf{G}\bar{\mathbf{P}} + \bar{\boldsymbol{\psi}} + \bar{\boldsymbol{\xi}}^*]$, where

$$\bar{\mathbf{P}} = \begin{bmatrix} \mathbf{1} & \bar{\mathbf{B}} & \mathbf{0} \\ \mathbf{0} & \bar{\mathbf{C}} & \mathbf{0} \\ 0 & \mathbf{e}'_{(k+1)_1} & 1 \end{bmatrix}, \quad \mathbf{G} = [\mathbf{D} \quad \mathbf{F} \quad \bar{\mathbf{u}}]$$

and

$$\bar{\boldsymbol{\xi}}^* = \begin{bmatrix} \mathbf{0}_{(T \times 1)} & \bar{\boldsymbol{\xi}} & \mathbf{0}_{(T \times 1)} \end{bmatrix}, \quad \bar{\boldsymbol{\psi}} = \begin{bmatrix} \mathbf{0}_{(T \times 1)} & \mathbf{0}_{(T \times (k+1))} & \bar{\boldsymbol{\zeta}} \end{bmatrix},$$

and $\mathbf{e}_{(k+1)_1}$ denotes a $k+1$ vector where the first element is $-1/1$ for production/cost function and the others are zero.

Lemma 2. *As assumptions 1-4 hold, we have*

$$(B1) \quad T^{-1} \bar{\boldsymbol{\xi}}' \bar{\boldsymbol{\xi}} = O_p(N^{-1});$$

$$(B2) \quad T^{-1} \boldsymbol{\xi}'_i \bar{\boldsymbol{\xi}} = O_p(N^{-1}) + O_p((NT)^{-1/2});$$

$$(B3) \quad T^{-1}\mathbf{D}'\bar{\boldsymbol{\xi}} = O_p((NT)^{-1/2});$$

$$(B4) \quad T^{-1}\mathbf{F}'\bar{\boldsymbol{\xi}} = O_p((NT)^{-1/2});$$

$$(B5) \quad T^{-1}\mathbf{D}'\mathbf{v}_i = O_p(T^{-1/2});$$

$$(B6) \quad T^{-1}\mathbf{F}'\mathbf{v}_i = O_p(T^{-1/2}).$$

Lemma 3. *As assumptions 1–4 hold, we have*

$$(C1) \quad T^{-1}(\bar{\mathbf{u}}'\bar{\boldsymbol{\xi}}) = O_p((NT)^{-1/2});$$

$$(C2) \quad T^{-1}(\bar{\boldsymbol{\xi}}'\bar{\boldsymbol{\zeta}}) = O_p(N^{-1}T^{-1/2});$$

$$(C3) \quad T^{-1}(\mathbf{G}'\bar{\boldsymbol{\zeta}}) = O_p(N^{-1/2});$$

$$(C4) \quad T^{-1}(\bar{\boldsymbol{\zeta}}'\bar{\boldsymbol{\zeta}}) = O_p(N^{-1});$$

$$(C5) \quad T^{-1}(\boldsymbol{\xi}_i'\bar{\boldsymbol{\zeta}}) = O_p((NT)^{-1/2});$$

$$(C6) \quad T^{-1}(\boldsymbol{\xi}_i'\mathbf{G}) = O_p(T^{-1/2});$$

$$(C7) \quad T^{-1}((\mathbf{u}_i - \bar{u}_i)'\bar{\boldsymbol{\xi}}) = O_p((NT)^{-1/2});$$

$$(C8) \quad T^{-1}((\mathbf{u}_i - \bar{u}_i)'\bar{\boldsymbol{\zeta}}) = O_p(N^{-1}) + O_p((NT)^{-1/2});$$

$$(C9) \quad T^{-1}((\mathbf{u}_i - \bar{u}_i)'\mathbf{G}) = O_p(N^{-1}) + O_p(T^{-1/2});$$

$$(C10) \quad T^{-1}(\mathbf{h}_i - \bar{h}_i)'N^{-1}\sum_{j=1}^N \mathbf{h}_j u_j^* = O_p(N^{-1}) + O_p(T^{-1/2}).$$

Appendix B-Proof of Main Propositions and Theorems

Recall the transformed log-likelihood functions of (12) and (13),

$$Q_{NT}(\boldsymbol{\theta}) = (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (T-s) (\ln(2\pi) + \ln \sigma_v^2) - \frac{1}{2} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta} - \mathbf{F}_0 \boldsymbol{\lambda}_{i,0})' \times \right. \\ \left. \bar{\mathbf{M}} \Pi^{-1} \bar{\mathbf{M}} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta} - \mathbf{F}_0 \boldsymbol{\lambda}_{i,0}) + \frac{1}{2} \left(\frac{\mu_c^2}{\sigma_*^2} - \frac{\mu^2}{\sigma_u^2} \right) + \ln \left(\sigma_* \Phi \left(\frac{\mu_c}{\sigma_*} \right) \right) - \ln \left(\sigma_u \Phi \left(\frac{\mu}{\sigma_u} \right) \right) \right\}, \quad (12)$$

and

$$\tilde{Q}_{NT}(\boldsymbol{\theta}) = (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (T-s) (\ln(2\pi) + \ln \sigma_v^2) - \frac{1}{2} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta})' \times \right. \\ \left. \bar{\mathbf{M}} \Pi^{-1} \bar{\mathbf{M}} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta}) + \frac{1}{2} \left(\frac{\mu_*^2}{\sigma_*^2} - \frac{\mu^2}{\sigma_u^2} \right) + \ln \left(\sigma_* \Phi \left(\frac{\mu_*}{\sigma_*} \right) \right) - \ln \left(\sigma_u \Phi \left(\frac{\mu}{\sigma_u} \right) \right) \right\}. \quad (13)$$

Proof of Proposition 1. To complete the proof of Proposition 1, we separate (13) into five parts:

$$P1 = (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (T-s) (\ln(2\pi) + \ln \sigma_v^2) \right\}, \\ P2 = (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta})' \bar{\mathbf{M}} \Pi^{-1} \bar{\mathbf{M}} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta}) \right\}, \\ P3 = (NT)^{-1} \sum_{i=1}^N \left\{ \frac{1}{2} \left(\frac{\mu_*^2}{\sigma_*^2} - \frac{\mu^2}{\sigma_u^2} \right) \right\}, \\ P4 = (NT)^{-1} \sum_{i=1}^N \left\{ \ln \left(\sigma_* \Phi \left(\frac{\mu_*}{\sigma_*} \right) \right) \right\}, \\ P5 = (NT)^{-1} \sum_{i=1}^N \left\{ -\ln \left(\sigma_u \Phi \left(\frac{\mu}{\sigma_u} \right) \right) \right\}.$$

Since $P1$ and $P5$ are the same as part of (12), we only need to investigate the differences of $P2$, $P3$ and $P4$ between (12) and (13).

Consider $P2$. By the facts that $\mathbf{y}_i = \mathbf{D} \alpha_i + \mathbf{X}_i \boldsymbol{\beta} + \mathbf{F} \boldsymbol{\lambda}_i + \boldsymbol{\varepsilon}_i$, $\bar{\mathbf{M}} \mathbf{D} \alpha_i = \mathbf{0}$ and $\bar{\mathbf{M}} \Pi^{-1} \bar{\mathbf{M}} = \sigma_v^{-2} \bar{\mathbf{M}}$,

$P2$ can be rewritten as,

$$\begin{aligned}
& (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta})' \bar{\mathbf{M}} \Pi^{-1} \bar{\mathbf{M}} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta}) \right\} \\
&= \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta})' \bar{\mathbf{M}} (\mathbf{y}_i - \mathbf{X}_i \boldsymbol{\beta}) \right\} \\
&= \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (\mathbf{F}_0 \boldsymbol{\lambda}_{i0} + \boldsymbol{\varepsilon}_i + \mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}} (\mathbf{F}_0 \boldsymbol{\lambda}_{i0} + \boldsymbol{\varepsilon}_i + \mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta})) \right\} \\
&= \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \left\{ -\frac{1}{2} (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}} (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta})) \right\} \\
&\quad - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \{ (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\lambda}_{i0} \} - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \{ (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}} \boldsymbol{\varepsilon}_i \} \\
&\quad - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \boldsymbol{\varepsilon}_i' \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\lambda}_{i0} - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \frac{1}{2} \boldsymbol{\lambda}_{i0}' \mathbf{F}_0' \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\lambda}_{i0} - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \frac{1}{2} \boldsymbol{\varepsilon}_i' \bar{\mathbf{M}} \boldsymbol{\varepsilon}_i \\
&=: A_1(\boldsymbol{\theta}) + A_2(\boldsymbol{\theta}) + A_3(\boldsymbol{\theta}) + A_4(\boldsymbol{\theta}) + A_5(\boldsymbol{\theta}) + A_6(\boldsymbol{\theta}).
\end{aligned}$$

Particularly, $A_1(\boldsymbol{\theta})$, $A_3(\boldsymbol{\theta})$ and $A_6(\boldsymbol{\theta})$ do not affected by the factor structure, therefore we will focus on the properties of $A_2(\boldsymbol{\theta})$, $A_4(\boldsymbol{\theta})$ and $A_5(\boldsymbol{\theta})$ respectively. For $A_2(\boldsymbol{\theta})$,

$$\begin{aligned}
A_2(\boldsymbol{\theta}) &= -\sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\lambda}_{i0} \\
&= -\sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}} \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\eta}_{i0} \\
&= -\sigma_v^{-2} T^{-1} (\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \bar{\mathbf{X}}' \bar{\mathbf{M}} \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\eta}_{i0} \\
&= 0 - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}}_0 \mathbf{F}_0 \boldsymbol{\eta}_{i0} - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i (\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT} \\
&=: A_{2,1}(\boldsymbol{\theta}) + A_{2,2}(\boldsymbol{\theta}).
\end{aligned}$$

Since $\boldsymbol{\lambda}_{i0} = \boldsymbol{\eta} + \boldsymbol{\eta}_{i0}$, after taking cross-sectional average of $\boldsymbol{\lambda}_{i0}$, we have $\bar{\boldsymbol{\lambda}} = \boldsymbol{\eta} + \bar{\boldsymbol{\eta}}$. The second equality holds by replacing $\boldsymbol{\lambda}_{i0}$ by $\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}} + \boldsymbol{\eta}_{i0}$. The fourth equality holds because $\bar{\mathbf{M}} \bar{\mathbf{X}} = 0$ and $\bar{\mathbf{M}} = \bar{\mathbf{M}}_0 + \kappa_{NT}$, where $\kappa_{NT} = O(b_{NT})$ by $\boldsymbol{\theta} \in \mathbb{B}$. Note that for easy to state, we use $A_{2,1}(\boldsymbol{\theta})$ and $A_{2,2}(\boldsymbol{\theta})$ to denote the rest of terms we need to discuss.

Consider $A_{2,1}(\boldsymbol{\theta})$, because of the fact that $\mathbf{F}_0 = -(\bar{\boldsymbol{\xi}} + \bar{\mathbf{U}}) \bar{\mathbf{C}}' (\bar{\mathbf{C}} \bar{\mathbf{C}}')^{-1}$ from equation (10) and $\bar{\mathbf{U}} = (\bar{\mathbf{U}}_1, \dots, \bar{\mathbf{U}}_T)'$, we have

$$\begin{aligned}
A_{2,1}(\boldsymbol{\theta}) &= \sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i(\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}}_0(\bar{\boldsymbol{\xi}} + \bar{\mathbf{U}}) \bar{\mathbf{C}}' (\bar{\mathbf{C}}\bar{\mathbf{C}}')^{-1} \boldsymbol{\eta}_{i0} \\
&= \sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i(\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}}_0 \bar{\boldsymbol{\xi}} \bar{\mathbf{C}}' (\bar{\mathbf{C}}\bar{\mathbf{C}}')^{-1} \boldsymbol{\eta}_{i0} \\
&\quad + \sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i(\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}}_0 \bar{\mathbf{U}} \bar{\mathbf{C}}' (\bar{\mathbf{C}}\bar{\mathbf{C}}')^{-1} \boldsymbol{\eta}_{i0}.
\end{aligned}$$

The property of the first term can be obtained from the fact that $\bar{\mathbf{C}}'(\bar{\mathbf{C}}\bar{\mathbf{C}}')^{-1}$ is bounded and the result that $\frac{(\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \mathbf{X}_i' \bar{\mathbf{M}}_0 \sqrt{N} \bar{\boldsymbol{\xi}}}{\sqrt{T}} = O_p(1)$ proved by Pesaran (2006). Therefore, with $\boldsymbol{\eta}_{i0}$ which is distributed independently of \mathbf{X}_i , $\bar{\boldsymbol{\xi}}$ and elements in $\bar{\mathbf{M}}_0$, we have

$$N^{-1} \sum_{i=1}^N \frac{(\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \mathbf{X}_i' \bar{\mathbf{M}}_0 \sqrt{N} \bar{\boldsymbol{\xi}}}{\sqrt{T}} \bar{\mathbf{C}}' (\bar{\mathbf{C}}\bar{\mathbf{C}}')^{-1} \boldsymbol{\eta}_{i0} = O_p(N^{-1/2}),$$

that is $\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\mathbf{X}_i(\boldsymbol{\beta}_0 - \boldsymbol{\beta}))' \bar{\mathbf{M}}_0 \bar{\boldsymbol{\xi}} \bar{\mathbf{C}}' (\bar{\mathbf{C}}\bar{\mathbf{C}}')^{-1} \boldsymbol{\eta}_{i0} = O_p(N^{-1}T^{-1/2})$. We can prove the second term in $A_{2,1}(\boldsymbol{\theta})$ in the similar way because $\bar{\mathbf{M}}_0 \bar{\mathbf{U}} = \bar{\mathbf{M}}_0(\bar{\mathbf{U}} - [\bar{\mathbf{h}}_0 \mu_0^+, \mathbf{0}]) = [\bar{\mathbf{M}}_0 \bar{\boldsymbol{\zeta}}, \mathbf{0}]$, and

$$N^{-1} \sum_{i=1}^N \frac{(\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \mathbf{X}_i' \bar{\mathbf{M}}_0 \sqrt{N} \bar{\boldsymbol{\zeta}}}{\sqrt{T}} \bar{\mathbf{C}}' (\bar{\mathbf{C}}\bar{\mathbf{C}}')^{-1} \boldsymbol{\eta}_{i0} = O_p(N^{-1/2}).$$

Thus, we have $A_{2,1}(\boldsymbol{\theta}) = O_p(N^{-1}T^{-1/2})$.

Next, consider $A_{2,2}(\boldsymbol{\theta})$. We have

$$\begin{aligned}
A_{2,2}(\boldsymbol{\theta}) &= -\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \mathbf{X}_i' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT} \\
&= -\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\beta}_0 - \boldsymbol{\beta})' (\mathbf{F}_0 \boldsymbol{\tau}_{i0} + \mathbf{e}_i)' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT} \\
&= -\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \boldsymbol{\tau}_{i0}' \mathbf{F}_0' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT} - \sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \mathbf{e}_i' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT},
\end{aligned}$$

where the first equality comes from facts that $\mathbf{X}_i = \mathbf{D}\mathbf{A}_i' + \mathbf{F}\boldsymbol{\tau}_i + \mathbf{e}_i$ and $\mathbf{D}\mathbf{A}_i'$ has been removed by $\bar{\mathbf{M}}$. The first term of the last equation can be rearranged as $-\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \boldsymbol{\tau}_{i0}' \frac{\mathbf{F}_0' \mathbf{F}_0}{T} \boldsymbol{\eta}_{i0} \kappa_{NT}$. Since $\frac{\mathbf{F}_0' \mathbf{F}_0}{T} = O_p(1)$ and $\boldsymbol{\eta}_{i0}$ is distributed independently of $\boldsymbol{\tau}_{i0}$ and \mathbf{F}_0 , we have $-\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \boldsymbol{\tau}_{i0}' \mathbf{F}_0' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT} = O_p(N^{-1/2}b_{NT})$. Further, according to the result of $\frac{\mathbf{e}_i' \mathbf{F}_0}{T} = O_p(T^{-1/2})$ and the property of $\boldsymbol{\eta}_{i0}$ we used before. We can show that $-\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\beta}_0 - \boldsymbol{\beta})' \mathbf{e}_i' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT} = O_p((NT)^{-1/2}b_{NT})$. Combining these results, we have $A_{2,2}(\boldsymbol{\theta}) = O_p(N^{-1/2}b_{NT})$. Therefore, $A_2(\boldsymbol{\theta}) = O_p(N^{-1}T^{-1/2}) + O_p(N^{-1/2}b_{NT})$.

For $A_4(\boldsymbol{\theta})$, using the same fact that $\boldsymbol{\lambda}_{i0} = \bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}} + \boldsymbol{\eta}_{i0}$, we have

$$\begin{aligned}
A_4(\boldsymbol{\theta}) &= -\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N \boldsymbol{\varepsilon}'_i \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\lambda}_{i0} \\
&= -\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N \boldsymbol{\varepsilon}'_i \bar{\mathbf{M}} \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) - \sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N \boldsymbol{\varepsilon}'_i \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\eta}_{i0} \\
&= -\sigma_v^{-2} T^{-1} \bar{\boldsymbol{\varepsilon}}' \bar{\mathbf{M}} \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) - \sigma_v^{-2} (NT)^{-1} \sum_{i=1}^N \boldsymbol{\varepsilon}'_i \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\eta}_{i0} \\
&=: A_{4,1}(\boldsymbol{\theta}) + A_{4,2}(\boldsymbol{\theta}).
\end{aligned}$$

In particular,

$$\begin{aligned}
A_{4,1}(\boldsymbol{\theta}) &= -\sigma_v^{-2} T^{-1} \bar{\boldsymbol{\varepsilon}}' \bar{\mathbf{M}}_0 \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) - \sigma_v^{-2} T^{-1} \bar{\boldsymbol{\varepsilon}}' \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) \kappa_{NT} \\
&= -\sigma_v^{-2} T^{-1} (\bar{\mathbf{v}} + (\bar{\mathbf{u}} - \bar{\mathbf{h}}_0 \mu_0^+))' \bar{\mathbf{M}}_0 \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) - \sigma_v^{-2} T^{-1} (\bar{\mathbf{v}} + \bar{\mathbf{u}})' \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) \kappa_{NT}.
\end{aligned}$$

We can rewrite the first term of the above equation as

$$\begin{aligned}
& -\sigma_v^{-2} T^{-1} (\bar{\mathbf{v}} + (\bar{\mathbf{u}} - \bar{\mathbf{h}}_0 \mu_0^+))' \bar{\mathbf{M}}_0 \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) \\
&= -\sigma_v^{-2} T^{-1} \bar{\mathbf{v}}' \bar{\mathbf{M}}_0 \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) - \sigma_v^{-2} T^{-1} (\bar{\mathbf{u}} - \bar{\mathbf{h}}_0 \mu_0^+)' \bar{\mathbf{M}}_0 \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}).
\end{aligned}$$

Using the fact $\frac{1}{T} \bar{\mathbf{v}}' \bar{\mathbf{M}}_0 \mathbf{F}_0 = \frac{1}{T} \bar{\mathbf{v}}' \mathbf{F}_0 - \frac{1}{T} \bar{\mathbf{v}}' \bar{\mathbf{H}}_0 (\bar{\mathbf{H}}_0 \bar{\mathbf{H}}_0')^{-1} \bar{\mathbf{H}}_0' \mathbf{F}_0$ and the results from lemmas (B1), (B3), (B4), (C1)-(C4) and the fact $\bar{\mathbf{v}} = O_p(N^{-1/2})$, we have

$$\begin{aligned}
\frac{1}{T} \bar{\mathbf{v}}' \bar{\mathbf{H}}_0 (\bar{\mathbf{H}}_0 \bar{\mathbf{H}}_0')^{-1} \bar{\mathbf{H}}_0' \mathbf{F}_0 &= \frac{\bar{\mathbf{v}}' \bar{\mathbf{H}}_0}{T} \left(\frac{\bar{\mathbf{H}}_0 \bar{\mathbf{H}}_0'}{T} \right)^{-1} \frac{\bar{\mathbf{H}}_0' \mathbf{F}_0}{T} \\
&= \left(\underbrace{\frac{\bar{\mathbf{v}}' \mathbf{G}}{T} \bar{\mathbf{P}}}_{O_p(N^{-1/2})} + \underbrace{\frac{\bar{\mathbf{v}}' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1})} \right) \left(\underbrace{\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{G}}{T} \bar{\mathbf{P}} + \bar{\mathbf{P}}' \frac{\mathbf{G}' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T} + \frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' \mathbf{G}}{T} \bar{\mathbf{P}} + \frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1/2})} \right)^{-1} \\
&\quad \times \left(\underbrace{\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{F}_0}{T}}_{O_p((NT)^{-1/2})} + \underbrace{\frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' \mathbf{F}_0}{T}}_{O_p((NT)^{-1/2})} \right) \\
&= \frac{\bar{\mathbf{v}}' \mathbf{G}}{T} \bar{\mathbf{P}} \left(\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{G}}{T} \bar{\mathbf{P}} \right)^{-1} \bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{F}_0}{T} + O_p(N^{-1}).
\end{aligned}$$

Notice that we keep the first term of the above equation to illustrate the fact that $\frac{1}{T} \bar{\mathbf{v}}' \mathbf{F}_0 - \frac{\bar{\mathbf{v}}' \mathbf{G}}{T} \bar{\mathbf{P}} \left(\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{G}}{T} \bar{\mathbf{P}} \right)^{-1} \bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{F}_0}{T} = \frac{1}{T} \bar{\mathbf{v}}' \bar{\mathbf{M}}_{\mathbf{G}} \mathbf{F}_0 = \mathbf{0}$ because $\mathbf{F}_0 \in \mathbf{G}$. Combining these results, we have $\frac{1}{T} \bar{\mathbf{v}}' \bar{\mathbf{M}}_0 \mathbf{F}_0 = O_p(N^{-1})$. In the same manner, we have $\frac{1}{T} (\bar{\mathbf{u}} - \bar{\mathbf{h}}_0 \mu_0^+)' \bar{\mathbf{M}}_0 \mathbf{F}_0 = O_p(N^{-1})$. In addition, the term, $\sigma_v^{-2} T^{-1} (\bar{\mathbf{v}} + \bar{\mathbf{u}})' \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) \kappa_{NT}$ is needed to investigate. The property of this term can be obtained by using $\frac{1}{T} \bar{\mathbf{v}}' \mathbf{F}_0 = O_p((NT)^{-1/2})$ and $\frac{1}{T} \bar{\mathbf{u}}' \mathbf{F}_0 = O_p(T^{-1/2})$. Thus, $\sigma_v^{-2} T^{-1} (\bar{\mathbf{v}} + \bar{\mathbf{u}})' \mathbf{F}_0 (\bar{\boldsymbol{\lambda}} - \bar{\boldsymbol{\eta}}) \kappa_{NT} = O_p(T^{-1/2} b_{NT})$. These give $A_{4,1}(\boldsymbol{\theta}) = O_p(N^{-1}) + O_p(T^{-1/2} b_{NT})$.

Next, consider $A_{4,2}(\boldsymbol{\theta})$,

$$A_{4,2}(\boldsymbol{\theta}) = -\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \bar{\mathbf{M}}_0 \mathbf{F}_0 \boldsymbol{\eta}_{i0} - \sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT}.$$

The first term of $A_{4,2}(\boldsymbol{\theta})$ can be decomposed into $\frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \bar{\mathbf{M}}_0 \mathbf{F}_0 = \frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{F}_0 - \frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \bar{\mathbf{H}}_0 (\bar{\mathbf{H}}_0 \bar{\mathbf{H}}_0')^{-1} \bar{\mathbf{H}}_0' \mathbf{F}_0$ and using lemmas (B2), (C5) and (C7)-(C8), with $\frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{G} = O_p(N^{-1}) + O_p(T^{-1/2})$ by lemmas (C6) and (C9), we have

$$\begin{aligned} & \frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \bar{\mathbf{H}}_0 (\bar{\mathbf{H}}_0 \bar{\mathbf{H}}_0')^{-1} \bar{\mathbf{H}}_0' \mathbf{F}_0 \\ &= \left(\underbrace{\frac{(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{G} \bar{\mathbf{P}}}{T}}_{O_p(N^{-1}) + O_p(T^{-1/2})} + \underbrace{\frac{(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1}) + O_p((NT)^{-1/2})} \right) \left(\underbrace{\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{G} \bar{\mathbf{P}}}{T}}_{O_p(N^{-1/2})} + \underbrace{\bar{\mathbf{P}}' \frac{\mathbf{G}' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1/2})} + \underbrace{\frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' \mathbf{G} \bar{\mathbf{P}}}{T}}_{O_p(N^{-1})} + \underbrace{\frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1})} \right)^{-1} \\ & \quad \times \left(\underbrace{\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{F}_0}{T}}_{O_p(N^{-1/2})} + \underbrace{\frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' \mathbf{F}_0}{T}}_{O_p((NT)^{-1/2})} \right) \\ &= \frac{(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{G} \bar{\mathbf{P}}}{T} \left(\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{G} \bar{\mathbf{P}}}{T} \right)^{-1} \bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{F}_0}{T} + O_p(N^{-1}) + O_p((NT)^{-1/2}). \end{aligned}$$

Similarly, we keep the first interaction term, together with $\frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{F}_0$, then we have $\frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{F}_0 - \frac{(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{G} \bar{\mathbf{P}}}{T} \left(\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{G} \bar{\mathbf{P}}}{T} \right)^{-1} \bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{F}_0}{T} = \frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \bar{\mathbf{M}}_0 \mathbf{F}_0 = \mathbf{0}$. Thus, $\frac{1}{T}(\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \bar{\mathbf{M}}_0 \mathbf{F}_0 = O_p(N^{-1}) + O_p((NT)^{-1/2})$. Since $\boldsymbol{\eta}_{i0}$ is distributed independently of \mathbf{F}_0 , \mathbf{v}_i and \mathbf{u}_i , we can conclude that $-\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \bar{\mathbf{M}}_0 \mathbf{F}_0 \boldsymbol{\eta}_{i0} = O_p(N^{-3/2}) + O_p(N^{-1}T^{-1/2})$. Finally, since $\frac{1}{T} \mathbf{v}_i' \mathbf{F}_0 = \frac{1}{T} (\mathbf{u}_i - \bar{\mathbf{u}}_i)' \mathbf{F}_0 = O_p(T^{-1/2})$, we therefore have $-\sigma_v^{-2}(NT)^{-1} \sum_{i=1}^N (\boldsymbol{\varepsilon}_i - \bar{\boldsymbol{\varepsilon}}_i)' \mathbf{F}_0 \boldsymbol{\eta}_{i0} \kappa_{NT} = O_p((NT)^{-1/2} b_{NT})$. Taking these results from $A_{4,1}(\boldsymbol{\theta})$ and $A_{4,2}(\boldsymbol{\theta})$, we have $A_4(\boldsymbol{\theta}) = O_p(N^{-1}) + O_p(N^{-1}T^{-1/2}) + O_p((NT)^{-1/2} b_{NT})$.

Now, consider $A_5(\boldsymbol{\theta})$. By using the following inequality

$$\left\| \frac{1}{T} \boldsymbol{\lambda}'_{i0} \mathbf{F}'_0 \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\lambda}_{i0} \right\| = \left\| \frac{1}{T} \boldsymbol{\lambda}'_{i0} \mathbf{F}'_0 \bar{\mathbf{M}} \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\lambda}_{i0} \right\| \leq \frac{1}{T} \sum_{t=1}^T \left\| \bar{\mathbf{M}} \mathbf{F}_0 \boldsymbol{\lambda}_{i0(t)} \right\|^2,$$

where $\bar{\mathbf{M}}\mathbf{F}_0\boldsymbol{\lambda}_{i0(t)}$ denotes the t -th element of $\bar{\mathbf{M}}\mathbf{F}_0\boldsymbol{\lambda}_{i0}$. Since

$$\begin{aligned}
\boldsymbol{\lambda}'_{i0}\mathbf{F}'_0\bar{\mathbf{M}} &= \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0\kappa_{NT} + \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0 - \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0\bar{\mathbf{H}}_0(\bar{\mathbf{H}}_0\bar{\mathbf{H}}_0)^{-1}\bar{\mathbf{H}}'_0 \\
&= \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0\kappa_{NT} + \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0 - \boldsymbol{\lambda}'_{i0}\left(\frac{\mathbf{F}'_0\mathbf{G}}{T}\bar{\mathbf{P}} + \underbrace{\frac{\mathbf{F}'_0(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p((NT)^{-1/2})}\right) \\
&\quad \left(\underbrace{\bar{\mathbf{P}}'\frac{\mathbf{G}'\mathbf{G}}{T}\bar{\mathbf{P}} + \bar{\mathbf{P}}'\frac{\mathbf{G}'(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T} + \frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})'\mathbf{G}}{T}\bar{\mathbf{P}}}_{O_p(N^{-1/2})} + \underbrace{\frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})'(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1})}\right)^{-1} \times \left(\bar{\mathbf{P}}'\mathbf{G}' + \underbrace{\frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1/2})}\right) \\
&= \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0\kappa_{NT} + \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0 - \boldsymbol{\lambda}'_{i0}\frac{\mathbf{F}'_0\mathbf{G}}{T}\bar{\mathbf{P}}\left(\bar{\mathbf{P}}'\frac{\mathbf{G}'\mathbf{G}}{T}\bar{\mathbf{P}}\right)^{-1}\bar{\mathbf{P}}'\mathbf{G}' + O_p(N^{-1/2}) \\
&= \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0\kappa_{NT} + \boldsymbol{\lambda}'_{i0}\mathbf{F}'_0\bar{\mathbf{M}}\mathbf{G} + O_p(N^{-1/2}) \\
&= O_p(b_{NT}) + O_p(N^{-1/2}),
\end{aligned}$$

we have $\frac{1}{T}\sum_{t=1}^T\|\bar{\mathbf{M}}\mathbf{F}_0\boldsymbol{\lambda}_{i0(t)}\|^2 = O_p(b_{NT}^2) + O_p(N^{-1}) + O_p(N^{-1/2}b_{NT})$ and $A_5(\boldsymbol{\theta}) = O_p(b_{NT}^2) + O_p(N^{-1}) + O_p(N^{-1/2}b_{NT})$. Combining the above results of $A_2(\boldsymbol{\theta})$, $A_4(\boldsymbol{\theta})$ and $A_5(\boldsymbol{\theta})$, we have $P2 = O_p(N^{-1}) + O_p(N^{-1/2}b_{NT}) + O_p(b_{NT}^2)$.

So far, we still need to examine $P3$ and $P4$. First, we define

$$(NT)^{-1}\sum_{i=1}^N\ln\Phi\left(\frac{\mu_c}{\sigma_*}\right) =: (NT)^{-1}\sum_{i=1}^N f\left(\frac{\mu_c}{\sigma_*}\right),$$

and by the first order of Taylor expansion at $\frac{\mu_*}{\sigma_*}$, we have

$$(NT)^{-1}\sum_{i=1}^N f\left(\frac{\mu_c}{\sigma_*}\right) \approx (NT)^{-1}\sum_{i=1}^N \left[f\left(\frac{\mu_*}{\sigma_*}\right) + f'\left(\frac{\mu_*}{\sigma_*}\right) \frac{(\mathbf{h}_i - \bar{h}_i)'\bar{\mathbf{M}}\mathbf{F}\boldsymbol{\lambda}_i/\sigma_v^2}{(\mathbf{h}'_i\bar{\mathbf{M}}\mathbf{h}_i/\sigma_v^2 + 1/\sigma_u^2)^{1/2}} \right],$$

where $\bar{h}_i = T^{-1}\sum_{t=1}^T h_{it}$. Rewrite the second term in the brackets of right hand side as

$$\begin{aligned}
(NT)^{-1}\sum_{i=1}^N &\left[f'\left(\frac{\mu_*}{\sigma_*}\right) \frac{(\mathbf{h}_i - \bar{h}_i)'\bar{\mathbf{M}}\mathbf{F}\boldsymbol{\lambda}_i/\sigma_v^2}{(\mathbf{h}'_i\bar{\mathbf{M}}\mathbf{h}_i/\sigma_v^2 + 1/\sigma_u^2)^{1/2}} \right] \\
&= N^{-1}T^{-1/2}\sum_{i=1}^N \left[\underbrace{f'\left(\frac{\mu_*}{\sigma_*}\right) \left(\frac{\mathbf{h}'_i\bar{\mathbf{M}}\mathbf{h}_i/\sigma_v^2 + 1/\sigma_u^2}{T}\right)^{-1/2}}_{O_p(1)} \left(\frac{(\mathbf{h}_i - \bar{h}_i)'\bar{\mathbf{M}}\mathbf{F}\boldsymbol{\lambda}_i/\sigma_v^2}{T}\right) \right].
\end{aligned}$$

Here,

$$\frac{(\mathbf{h}_i - \bar{h}_i)'\bar{\mathbf{M}}\mathbf{F}\boldsymbol{\lambda}_i/\sigma_v^2}{T} = \frac{(\mathbf{h}_i - \bar{h}_i)'\bar{\mathbf{M}}_0\mathbf{F}\boldsymbol{\lambda}_i/\sigma_v^2}{T} + \frac{(\mathbf{h}_i - \bar{h}_i)'\mathbf{F}\boldsymbol{\lambda}_i/\sigma_v^2}{T} \times \kappa_{NT}.$$

The first term can be decomposed into $\frac{1}{T}(\mathbf{h}_i - \bar{h}_i)'\bar{\mathbf{M}}_0\mathbf{F}\boldsymbol{\lambda}_i/\sigma_v^2 = \frac{1}{T}(\mathbf{h}_i - \bar{h}_i)'\mathbf{F}_0 - \frac{1}{T}(\mathbf{h}_i - \bar{h}_i)'\bar{\mathbf{H}}_0(\bar{\mathbf{H}}_0\bar{\mathbf{H}}_0)^{-1}\bar{\mathbf{H}}'_0\mathbf{F}_0$.

We use the results similar to Lemmas (C7)-(C8) and obtain

$$\begin{aligned} & \frac{1}{T}(\mathbf{h}_i - \bar{h}_i)' \bar{\mathbf{H}}_0 (\bar{\mathbf{H}}_0 \bar{\mathbf{H}}_0')^{-1} \bar{\mathbf{H}}_0' \mathbf{F}_0 \\ &= \left(\frac{(\mathbf{h}_i - \bar{h}_i)' \mathbf{G}}{T} \bar{\mathbf{P}} + \underbrace{\frac{(\mathbf{h}_i - \bar{h}_i)' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1}) + O_p((NT)^{-1/2})} \right) \left(\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{G}}{T} \bar{\mathbf{P}} + \underbrace{\bar{\mathbf{P}}' \frac{\mathbf{G}' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T} + \frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' \mathbf{G}}{T} \bar{\mathbf{P}}}_{O_p(N^{-1/2})} + \underbrace{\frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' (\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})}{T}}_{O_p(N^{-1})} \right)^{-1} \\ & \times \left(\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{F}_0}{T} + \underbrace{\frac{(\bar{\boldsymbol{\xi}}^* + \bar{\boldsymbol{\psi}})' \mathbf{F}_0}{T}}_{O_p((NT)^{-1/2})} \right). \end{aligned}$$

Notice that $\frac{1}{T}(\mathbf{h}_i - \bar{h}_i)' \mathbf{G} = O_p(N^{-1}) + O_p(T^{-1/2})$ because of lemma (C10) and a similar argument of (C9), thus

$$\begin{aligned} \frac{1}{T}(\mathbf{h}_i - \bar{h}_i)' \bar{\mathbf{H}}_0 (\bar{\mathbf{H}}_0 \bar{\mathbf{H}}_0')^{-1} \bar{\mathbf{H}}_0' \mathbf{F}_0 &= \frac{(\mathbf{h}_i - \bar{h}_i)' \mathbf{G}}{T} \bar{\mathbf{P}} \left(\bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{G}}{T} \bar{\mathbf{P}} \right)^{-1} \bar{\mathbf{P}}' \frac{\mathbf{G}' \mathbf{F}_0}{T} \\ &+ O_p(N^{-1}) + O_p((NT)^{-1/2}). \end{aligned}$$

Further, together with a similar argument of (C9), the second term $\frac{(\mathbf{h}_i - \bar{h}_i)' \mathbf{F} \boldsymbol{\lambda}_i / \sigma_v^2}{T} \times \kappa_{NT} = O_p(T^{-1/2} b_{NT})$. Thus

$$\frac{(\mathbf{h}_i - \bar{h}_i)' \bar{\mathbf{M}} \mathbf{F} \boldsymbol{\lambda}_i / \sigma_v^2}{T} = O_p(N^{-1}) + O_p((NT)^{-1/2}) + O_p(T^{-1/2} b_{NT}).$$

Using this result, the term $f' \left(\frac{\mu_*}{\sigma_*} \right) \left(\frac{\mathbf{h}_i' \bar{\mathbf{M}} \mathbf{h}_i / \sigma_v^2 + 1 / \sigma_u^2}{T} \right)^{-1/2} \left(\frac{(\mathbf{h}_i - \bar{h}_i)' \bar{\mathbf{M}} \mathbf{F} \boldsymbol{\lambda}_i / \sigma_v^2}{T} \right)$ should be $O_p(N^{-1}) + O_p((NT)^{-1/2}) + O_p(T^{-1/2} b_{NT})$. It implies that the difference between $(NT)^{-1} \sum_{i=1}^N f \left(\frac{\mu_*}{\sigma_*} \right)$ and $(NT)^{-1} \sum_{i=1}^N f \left(\frac{\mu_*}{\sigma_*} \right)$ is $O_p(N^{-1} T^{-1/2}) + O_p(N^{-1/2} T^{-1}) + O_p(T^{-1/2} b_{NT})$. The results of P3 and P4 are readily obtained.

Taking results from P2, P3 and P4, we have

$$P2 + P3 + P4 = O_p(N^{-1}) + O_p(N^{-1/2} T^{-1}) + O_p(T^{-1/2} b_{NT}) + O_p(N^{-1/2} b_{NT}) + O_p(b_{NT}^2). \quad (\text{M.1})$$

The first result of Proposition 1 can be proved because when $b_{NT} \rightarrow 0$, $P2 + P3 + P4 \xrightarrow{\mathbb{P}} 0$. The second result about $\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta$ can be proved by assuming b_{NT} does not converge to zero. In this case, it implies that the difference of $P2 + P3 + P4$ will be dominated by the term $O_p(b_{NT}^2)$ which comes from the quadratic term of $A_4(\boldsymbol{\theta})$. Thus the difference between $Q_{NT}(\boldsymbol{\theta}_0)$ and $\tilde{Q}_{NT}(\boldsymbol{\theta})$ is greater than zero in probability one when $\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta$. \square

Proof of Theorem 1. For any $\epsilon > 0$, we have (a) $\tilde{Q}_{NT}(\tilde{\boldsymbol{\theta}}) > \tilde{Q}_{NT}(\boldsymbol{\theta}_0) - \frac{\epsilon}{3}$; (b) $\tilde{Q}_{NT}(\boldsymbol{\theta}_0) > Q_0(\boldsymbol{\theta}_0) - \frac{\epsilon}{3}$ and (c) $\tilde{Q}_0(\boldsymbol{\theta}) > \tilde{Q}_{NT}(\boldsymbol{\theta}) - \frac{\epsilon}{3}$. (a) holds because $\tilde{\boldsymbol{\theta}}$ maximizes \tilde{Q}_{NT} , (b) holds because

the result 1 from Proposition 1 by letting $\boldsymbol{\theta} = \boldsymbol{\theta}_0$, and (c) holds because Assumption 5 (iv). Therefore, we have

$$\tilde{Q}_0(\tilde{\boldsymbol{\theta}}) > \tilde{Q}_{NT}(\tilde{\boldsymbol{\theta}}) - \frac{\epsilon}{3} > \tilde{Q}_{NT}(\boldsymbol{\theta}_0) - \frac{2\epsilon}{3} > Q_0(\boldsymbol{\theta}_0) - \epsilon.$$

Using the same definitions of b_{NT} and \mathbb{B} , we have $Q_{NT}(\boldsymbol{\theta}_0) - \tilde{Q}_{NT}(\boldsymbol{\theta}) > 0$ with probability 1 for all $\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta$ from the first result of Proposition 1. Taking this result with conditions (iii) and (iv) of Assumption 5, for any given $\epsilon > 0$, there is a constant $K > 0$ such that

$$\mathbb{P}[|Q_0(\boldsymbol{\theta}_0) - \tilde{Q}_0(\boldsymbol{\theta})| > K] \geq 1 - \epsilon,$$

for all $\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta$. Also $Q_0(\boldsymbol{\theta}_0) = \tilde{Q}_0(\boldsymbol{\theta}_0)$ if and only if $Q_0 = \tilde{Q}_0$ and $Q_0(\boldsymbol{\theta}_0) > \tilde{Q}_0(\boldsymbol{\theta})$ for all $\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta$. Therefore, by $\mathbb{B}^c \cap \Theta$ is compact, $\boldsymbol{\theta}_0$ maximizes $Q_0(\boldsymbol{\theta})$ and (i) of Assumption 5, $\sup_{\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta} \tilde{Q}_0(\boldsymbol{\theta}) = Q_0(\boldsymbol{\theta}^*) < Q_0(\boldsymbol{\theta}_0)$ for some $\boldsymbol{\theta}^* \in \mathbb{B}^c \cap \Theta$. Thus, choosing $\epsilon = Q_0(\boldsymbol{\theta}_0) - \sup_{\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta} \tilde{Q}_0(\boldsymbol{\theta})$, it follows that

$$\tilde{Q}_0(\tilde{\boldsymbol{\theta}}) > \sup_{\boldsymbol{\theta} \in \mathbb{B}^c \cap \Theta} \tilde{Q}_0(\boldsymbol{\theta}).$$

with probability one, and hence $\tilde{\boldsymbol{\theta}} \in \mathbb{B}$. □

Proof of Proposition 2. It can be proved immediately by multiplying \sqrt{NT} and equation (M.1) from Proposition 1. □

Proof of Theorem 2. Since the result from Proposition 2 satisfies the requirement of Lemma 1, we can prove the asymptotic normality of our proposed estimator immediately. □

Supplementary Material

Proof of Lemma 1. See Theorem A.5 of Kristensen and Shin (2012). \square

Proof of Lemma 2. It can be shown based on Lemma 2 of Pesaran (2006). \square

Through out these proofs, we use K to denote a positive number which is bounded and subscript “0” to denote the parameter which is evaluated at the true value.

Proof of Lemma (C1). Let $\bar{\xi}_l = (\bar{\xi}_{1,l}, \bar{\xi}_{2,l}, \dots, \bar{\xi}_{T,l})'$ denotes the l -th element of $\bar{\xi}$. Since $h_{it,0}$, u_i^* , v_{it} and e_{it} are mutually independent and note that $E(h_{it,0}) < K$ and $E(u_i^*) < K$, $\forall i, j$. We have

$$E \left(N^{-1} \sum_{i=1}^N \mathbf{h}'_{i,0} u_i^* \bar{\xi}_l \right) = 0 \quad (\text{S.1})$$

and

$$\begin{aligned} E(\bar{u}_t^2) &= E \left[\left(N^{-1} \sum_{i=1}^N h_{it,0} u_i^* \right)^2 \right] \\ &= N^{-2} E \left(\sum_{i=1}^N h_{it,0}^2 u_i^{*2} + \sum_{i=1}^N \sum_{j \neq i}^N h_{it,0} h_{jt,0} u_i^* u_j^* \right) \\ &= N^{-2} \sum_{i=1}^N E(h_{it,0}^2) E(u_i^{*2}) + N^{-2} \sum_{i=1}^N \sum_{j \neq i}^N E(h_{it,0}) E(h_{jt,0}) E(u_i^*) E(u_j^*) = O(1). \end{aligned}$$

Thus,

$$\begin{aligned} \text{Var} \left(N^{-1} \sum_{i=1}^N \mathbf{h}'_{i,0} u_i^* \bar{\xi}_l \right) &= \text{Var} \left(\sum_{t=1}^T \bar{u}_t \bar{\xi}_{t,l} \right) = \sum_{t=1}^T \text{Var} (\bar{u}_t \bar{\xi}_{t,l}) \\ &= \sum_{t=1}^T E(\bar{u}_t^2) E(\bar{\xi}_{t,l}^2) = O(TN^{-1}), \end{aligned} \quad (\text{S.2})$$

the second equality comes from the fact,

$$\begin{aligned} \text{Cov} (\bar{u}_t \bar{\xi}_{t,l}, \bar{u}_s \bar{\xi}_{s,l}) &= E (\bar{u}_t \bar{\xi}_{t,l} \bar{u}_s \bar{\xi}_{s,l}) - E (\bar{u}_t \bar{\xi}_{t,l}) E (\bar{u}_s \bar{\xi}_{s,l}) \\ &= E (\bar{\xi}_{t,l}) E (\bar{\xi}_{s,l}) E (\bar{u}_t \bar{u}_s) - E (\bar{\xi}_{t,l}) E (\bar{u}_t) E (\bar{\xi}_{s,l}) E (\bar{u}_s) = 0, \end{aligned}$$

where the last equality holds by $E(v_{it} v_{is}) = 0$ and $E(e_{it} e'_{is}) = \mathbf{0}$ for all i, j , and the last equality of (S.2) holds by $E(\bar{\xi}_{t,l}^2) = O(N^{-1})$. Together with (S.1) and (S.2), we obtain

$$\text{Var} (T^{-1} \bar{\mathbf{u}}' \bar{\xi}) = O((NT)^{-1}),$$

hence, $T^{-1} \bar{\mathbf{u}}' \bar{\xi} = O_p((NT)^{-1/2})$. \square

Proof of Lemma (C2). Recall that $\bar{\boldsymbol{\zeta}} = \bar{\mathbf{h}}_0 \mu_0^+ - \bar{\mathbf{u}}$, the mean of $\bar{\boldsymbol{\xi}}_t \bar{\mathbf{u}}_t$ is equal to $\mathbf{0}$ for all t by the fact that $h_{it,0}$, u_i^* , v_{it} and \mathbf{e}_{it} are mutually independent. Furthermore,

$$\begin{aligned} & \text{Var} \left[(NT)^{-1} \sum_{t=1}^T \bar{\boldsymbol{\xi}}_t \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right] \\ &= (NT)^{-2} \sum_{t=1}^T E(\bar{\boldsymbol{\xi}}_t \bar{\boldsymbol{\xi}}_t') E \left[\left(\sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right)^2 \right] \\ &= (NT)^{-2} \sum_{t=1}^T E(\bar{\boldsymbol{\xi}}_t \bar{\boldsymbol{\xi}}_t') \sum_{i=1}^N E(h_{it,0}^2) E[(\mu_0^+ - u_i^*)^2], \end{aligned}$$

in particular, the second and third equalities hold by $E(\bar{\boldsymbol{\xi}}_t \bar{\boldsymbol{\xi}}_s') = \mathbf{0} \forall t \neq s$ and $E[(\mu_0^+ - u_i^*)(\mu_0^+ - u_j^*)] = 0 \forall i \neq j$, respectively. Moreover, $E(h_{it,0}^2) < K$, $E[(\mu_0^+ - u_i^*)^2] < K$ and $(\bar{\boldsymbol{\xi}}_t \bar{\boldsymbol{\xi}}_t') = O_p(N^{-1})$, thus,

$$\text{Var} \left[(NT)^{-1} \sum_{t=1}^T \bar{\boldsymbol{\xi}}_t \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right] = O(N^{-2}T^{-1}).$$

We therefore have $(NT)^{-1} \sum_{t=1}^T \bar{\boldsymbol{\xi}}_t \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) = O_p(N^{-1}T^{-1/2})$. \square

Proof of Lemma (C3). Recall $\mathbf{G} = [\mathbf{D} \quad \mathbf{F} \quad \bar{\mathbf{u}}]$, we prove (C3) for each element of \mathbf{G} , first, we turn our focus on $(NT)^{-1} \sum_{t=1}^T D_t \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*)$. Notice that the mean is equal to 0 by u_i^* and $h_{it,0}$ are mutually independent, and

$$\begin{aligned} & \text{Var} \left[(NT)^{-1} \sum_{t=1}^T D_t \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right] \\ &= (NT)^{-2} E \left[\sum_{t=1}^T D_t \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right]^2 \\ &= (NT)^{-2} E \left[\sum_{t=1}^T D_t^2 \left(\sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right)^2 \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} D_t D_s \left(\sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right) \left(\sum_{j=1}^N h_{js,0} (\mu_0^+ - u_j^*) \right) \right]. \end{aligned}$$

The first term can be written as

$$\begin{aligned} & E \left[(NT)^{-2} \sum_{t=1}^T D_t^2 \left(\sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right)^2 \right] \\ &= (NT)^{-2} \sum_{t=1}^T D_t^2 \sum_{i=1}^N E(h_{it,0}^2) E[(\mu_0^+ - u_i^*)^2] \\ &= O((NT)^{-1}), \end{aligned} \tag{S.3}$$

where the second equality comes from the fact that $E[(\mu_0^+ - u_i^*)(\mu_0^+ - u_j^*)] = 0 \forall i \neq j$, and u_i^*

is independent of $h_{jt,0}$ for all i, j . The last equality holds by $E(h_{it,0}^2) < K$, $E[(\mu_0^+ - u_i^*)^2] < K$.

The second term,

$$\begin{aligned} & E \left[(NT)^{-2} \sum_{t=1}^T \sum_{s \neq t} D_t D_s \left(\sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right) \left(\sum_{j=1}^N h_{js,0}(\mu_0^+ - u_j^*) \right) \right] \\ & = (NT)^{-2} \sum_{t=1}^T \sum_{s \neq t} D_t D_s \sum_{i=1}^N E(h_{it,0} h_{is,0}) E(\mu_0^+ - u_i^*)^2 = O(N^{-1}), \end{aligned} \quad (\text{S.4})$$

the second equality holds for the same reason that $E[(\mu_0^+ - u_i^*)(\mu_0^+ - u_j^*)] = 0$, and the desired result can be obtained with the assumption of finite first moment of $h_{it,0}$. To sum up (S.3) and (S.4), we obtain

$$\text{Var} \left((NT)^{-1} \sum_{t=1}^T D_t \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right) = O(N^{-1}),$$

and which implies $(NT)^{-1} \sum_{t=1}^T D_t \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) = O_p(N^{-1/2})$.

Next, consider the l -th row of $T^{-1} [\mathbf{F}' N^{-1} \sum_{i=1}^N \mathbf{h}_{i,0}(\mu_0^+ - u_i^*)]$, which can be written as $T^{-1} [\sum_{t=1}^T f_{lt} N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*)]$. Notice that its mean is equal to 0 by the similar argument in the previous case, and the variance,

$$\begin{aligned} & \text{Var} \left[T^{-1} \left(\sum_{t=1}^T f_{lt} N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right) \right] \\ & = (NT)^{-2} E \left[\sum_{t=1}^T f_{lt} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right]^2 \\ & = (NT)^{-2} E \left[\sum_{t=1}^T f_{lt}^2 \left(\sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right)^2 \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} f_{lt} f_{ls} \left(\sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right) \left(\sum_{j=1}^N h_{js,0}(\mu_0^+ - u_j^*) \right) \right] \\ & = (NT)^{-2} \left[\sum_{t=1}^T E(f_{lt}^2) \sum_{i=1}^N E(h_{it,0}^2) E(\mu_0^+ - u_i^*)^2 \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} E(f_{lt} f_{ls}) \left(\sum_{i=1}^N E(h_{it,0} h_{is,0}) E(\mu_0^+ - u_i^*)^2 \right) \right], \end{aligned}$$

the third equality holds by $E[(\mu_0^+ - u_i^*)(\mu_0^+ - u_j^*)] = 0$. Furthermore, because \mathbf{F} is covariance stationary process distributed independently of u_i^* , the autocovariance function decays exponentially

in $|t - s|$. By these assumptions,

$$\begin{aligned} & \text{Var} \left[T^{-1} \left(\sum_{t=1}^T f_{lt} N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right) \right] \\ &= (NT)^{-2} \left[\sum_{t=1}^T E(f_{lt}^2) \sum_{i=1}^N E(h_{it,0}^2) E(\mu_0^+ - u_i^*)^2 \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} \Gamma_{fl}(|t - s|) \left(\sum_{i=1}^N E(h_{it,0} h_{is,0}) E(\mu_0^+ - u_i^*)^2 \right) \right] = O((NT^{-1})), \end{aligned}$$

where Γ_{fl} is the autocovariance function of f_{lt} , and the last equality holds by $E(f_{lt}^2) < K$, $E(h_{it,0}^2) < K$, $E(\mu_0^+ - u_i^*)^2 < K$ and $E(h_{it,0} h_{is,0}) < K$, which establishes $T^{-1} \left[\mathbf{F}' N^{-1} \sum_{i=1}^N \mathbf{h}_{i,0} (\mu_0^+ - u_i^*) \right] = O_p((NT)^{-1/2})$.

Finally, we analyze the last term. Notice that

$$\begin{aligned} & E \left[T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right) \left(N^{-1} \sum_{j=1}^N h_{jt,0} u_j^* \right) \right] \\ &= N^{-2} T^{-1} \sum_{t=1}^T \sum_{i=1}^N E(h_{it,0}^2) E(\mu_0^+ - u_i^*) u_i^* \\ &= O(N^{-1}), \end{aligned} \tag{S.5}$$

the first equality holds by the assumption that $E[(\mu_0^+ - u_i^*) u_j^*] = 0$, $\forall i \neq j$, and the last equality is true by $E(h_{it,0}^2) < K$, and $E(u_i^{*2}) < K$. The variance,

$$\begin{aligned} & \text{Var} \left[T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right) \left(N^{-1} \sum_{j=1}^N h_{jt,0} u_j^* \right) \right] \\ &= E \left[T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right) \left(N^{-1} \sum_{j=1}^N h_{jt,0} u_j^* \right) \right]^2 \\ & \quad - \left[E \left(T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right) \left(N^{-1} \sum_{j=1}^N h_{jt,0} u_j^* \right) \right) \right]^2, \end{aligned}$$

where the first term can be rearranged as

$$\begin{aligned}
& T^{-2}E \left[\sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right)^2 \left(N^{-1} \sum_{j=1}^N h_{jt,0}u_j^* \right)^2 \right] \\
& + T^{-2}E \left[\sum_{t=1}^T \sum_{s \neq t} \left(N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right) \left(N^{-1} \sum_{j=1}^N h_{jt,0}u_j^* \right) \right. \\
& \quad \left. \times \left(N^{-1} \sum_{j=1}^N h_{js,0}(\mu_0^+ - u_j^*) \right) \left(N^{-1} \sum_{j=1}^N h_{js,0}u_j^* \right) \right] \\
& =: A_1 + A_2.
\end{aligned}$$

Consider A_1 ,

$$A_1 = N^{-4}T^{-2}E \sum_{t=1}^T \left[\sum_{i=1}^N \sum_{j=1}^N \sum_{k=1}^N \sum_{l=1}^N h_{it,0}h_{jt,0}h_{kt,0}h_{lt,0}(\mu_0^+ - u_i^*)(\mu_0^+ - u_j^*)u_k^*u_l^* \right],$$

in which expectation is non-zero only in the following three cases: (i) $i = j = k = l$, (ii) $i = j$ and $j = l$, and (iii) $i = l$ and $j = k$ by assuming that the fourth moment of $h_{it,0}$ exists. It follows that

$$\begin{aligned}
A_1 = & N^{-4}T^{-2}E \sum_{t=1}^T \left[\sum_{i=1}^N h_{it,0}^4(\mu_0^+ - u_i^*)^2 u_i^{*2} + \sum_{i=1}^N \sum_{k \neq i} \sum_{l \neq i} h_{it,0}^2 h_{kt,0} h_{lt,0} (\mu_0^+ - u_i^*)^2 u_k^* u_l^* \right. \\
& \left. + \sum_{i=1}^N \sum_{j \neq i} h_{it,0}^2 h_{jt,0}^2 (\mu_0^+ - u_i^*)(\mu_0^+ - u_j^*) u_i^* u_j^* \right] = O((NT)^{-1}).
\end{aligned}$$

Furthermore, A_2 has the similar result except that we have to sum up the terms for all $t \neq s$, $t, s = 1, \dots, T$. Thus, we have $A_2 = O((N)^{-1})$. Taking A_1, A_2 and (S.5) together, we have

$$\text{Var} \left[T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right) \left(N^{-1} \sum_{j=1}^N h_{jt,0}u_j^* \right) \right] = O(N^{-1}),$$

which implies $T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right) \left(N^{-1} \sum_{j=1}^N h_{jt,0}u_j^* \right) = O(N^{-1/2})$. Therefore

$$T^{-1} \left[\mathbf{G}' N^{-1} \sum_{i=1}^N \mathbf{h}_{i,0}(\mu_0^+ - u_i^*) \right] = O_p(N^{-1/2})$$

as required. □

Proof of Lemma (C4). Write

$$\begin{aligned} & E \left[T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right)^2 \right] \\ &= N^{-2} T^{-1} \sum_{t=1}^T \sum_{i=1}^N E(h_{it,0}^2) E(\mu_0^+ - u_i^*)^2 = O(N^{-1}), \end{aligned} \quad (\text{S.6})$$

which holds by the assumption that $E[(\mu_0^+ - u_i^*)(\mu_0^+ - u_j^*)] = 0$, $E(h_{it,0}^2) < K$ and $E(\mu_0^+ - u_i^*)^2 < K$. Furthermore,

$$\begin{aligned} & E \left[T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right)^2 \right]^2 \\ &= T^{-2} E \left[\sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right)^4 \right] \\ &+ T^{-2} E \left[\sum_{t=1}^T \sum_{s \neq t} \left(N^{-1} \sum_{i=1}^N h_{it,0} (\mu_0^+ - u_i^*) \right)^2 \left(N^{-1} \sum_{j=1}^N h_{js,0} (\mu_0^+ - u_j^*) \right)^2 \right] \\ &=: A_1 + A_2. \end{aligned}$$

Consider A_1 , in which expectation is non-zero only in the following case

$$\begin{aligned} A_1 &= N^{-4} T^{-2} E \left[\sum_{t=1}^T \left(\sum_{i=1}^N h_{it,0}^4 (\mu_0^+ - u_i^*)^4 \right) \right] \\ &+ N^{-4} T^{-2} E \sum_{t=1}^T \left[\sum_{i=1}^N \sum_{j \neq i} h_{it,0}^2 h_{jt,0}^2 (\mu_0^+ - u_i^*)^2 (\mu_0^+ - u_j^*)^2 \right] = O(N^{-2} T^{-1}), \end{aligned}$$

where the result comes from assuming $h_{it,0}$ and u_i^* are independently distributed with finite fourth moment, and the fact that u_i^* 's are cross-sectional independent. Now consider A_2 ,

$$\begin{aligned} A_2 &= N^{-4} T^{-2} E \sum_{t=1}^T \sum_{s \neq t} \left[\sum_{i=1}^N \sum_{k=1}^N h_{it,0} h_{kt,0} (\mu_0^+ - u_i^*) (\mu_0^+ - u_k^*) \right] \\ &\times \left[\sum_{j=1}^N \sum_{l=1}^N h_{js,0} h_{ls,0} (\mu_0^+ - u_j^*) (u_l^* - \mu_0^+) \right], \end{aligned}$$

in which expectation is non-zero only in the following cases: (i) $i = j = k = l$, (ii) $i = k, j = l$ (iii) $i = j, k = l$, it follows that

$$\begin{aligned} A_2 &= N^{-4} T^{-2} E \sum_{t=1}^T \sum_{s \neq t} \left[\sum_{i=1}^N h_{it,0}^2 h_{is,0}^2 (\mu_0^+ - u_i^*)^4 + \sum_{i=1}^N \sum_{j \neq i} h_{it,0}^2 h_{js,0}^2 (\mu_0^+ - u_i^*)^2 (\mu_0^+ - u_j^*)^2 \right. \\ &\left. + \sum_{i=1}^N \sum_{k \neq i} h_{it,0} h_{is,0} h_{kt,0} h_{ks,0} (\mu_0^+ - u_i^*)^2 (\mu_0^+ - u_k^*)^2 \right] = O(N^{-2}). \end{aligned}$$

Taking A_1 , A_2 and (S.6) together, we have

$$\text{Var} \left[T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right)^2 \right] = O(N^{-2}),$$

which implies $T^{-1} \sum_{t=1}^T \left(N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right)^2 = O_p(N^{-1})$. \square

Proof of Lemma (C5). Recall that $\boldsymbol{\xi}_{it} = \begin{bmatrix} v_{it} + \boldsymbol{\beta}' \mathbf{e}_{it} \\ \mathbf{e}_{it} \end{bmatrix}$, it is easy to show that its expectation is $\mathbf{0}$ by the fact that v_{it} , \mathbf{e}_{it} , $h_{it,0}$ and u_i^* are distributed independently. So we can write the variance as

$$\begin{aligned} & \text{Var} \left[T^{-1} \sum_{t=1}^T \boldsymbol{\xi}_{it} N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right] \\ &= (NT)^{-2} E \left[\sum_{t=1}^T \boldsymbol{\xi}_{it} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right]^2 \\ &= (NT)^{-2} \left[\sum_{t=1}^T E(\boldsymbol{\xi}_{it} \boldsymbol{\xi}_{it}') E \left(\sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right)^2 \right] \\ &= (NT)^{-2} \left[\sum_{t=1}^T E(\boldsymbol{\xi}_{it} \boldsymbol{\xi}_{it}') E \left(\sum_{i=1}^N h_{it,0}^2(\mu_0^+ - u_i^*)^2 \right) \right], \end{aligned} \quad (\text{S.7})$$

the second equality holds by the fact that v_{it} and \mathbf{e}_{it} are serially uncorrelated, and the third equality holds by u_i^* are cross-sectionally independent. Furthermore, the term $E\|\boldsymbol{\xi}_{it} \boldsymbol{\xi}_{it}'\| < K$ by v_{it} and \mathbf{e}_{it} have finite variance, together with $E(h_{it,0}^2) < K$ and $E(\mu_0^+ - u_i^*)^2 < K$, we can obtain $\text{Var} \left[T^{-1} \sum_{t=1}^T \boldsymbol{\xi}_{it} N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) \right] = O((NT)^{-1})$. Therefore $T^{-1} \sum_{t=1}^T \boldsymbol{\xi}_{it} N^{-1} \sum_{i=1}^N h_{it,0}(\mu_0^+ - u_i^*) = O_p((NT)^{-1/2})$. \square

Proof of Lemma (C6). Given Lemmas (B5) and (B6), we already discussed two of three elements in \mathbf{G} . It remains to show the rate of $T^{-1} \sum_{t=1}^T \boldsymbol{\xi}_{it} N^{-1} \sum_{i=1}^N h_{it,0} u_i^*$. Consider its mean. Again, given the fact that v_{it} , \mathbf{e}_{it} , $h_{it,0}$ and u_i^* are distributed independently, it can be shown that

the mean is $\mathbf{0}$. The variance,

$$\begin{aligned}
& \text{Var} \left[T^{-1} \sum_{t=1}^T \boldsymbol{\xi}_{it} N^{-1} \sum_{i=1}^N h_{it,0} u_i^* \right] \\
&= (NT)^{-2} E \left[\sum_{t=1}^T \boldsymbol{\xi}_{it} \sum_{i=1}^N h_{it,0} u_i^* \right]^2 \\
&= (NT)^{-2} \left[\sum_{t=1}^T E(\boldsymbol{\xi}_{it} \boldsymbol{\xi}'_{it}) E \left(\sum_{i=1}^N h_{it,0} u_i^* \right)^2 \right] \\
&= (NT)^{-2} \left[\sum_{t=1}^T E(\boldsymbol{\xi}_{it} \boldsymbol{\xi}'_{it}) \left(\sum_{i=1}^N \sum_{j=1}^N E(h_{it,0} h_{jt,0}) E(u_i^* u_j^*) \right) \right],
\end{aligned}$$

where the second equality holds as the same as preceding discuss that v_{it} and \mathbf{e}_{it} are serially uncorrelated. However, by expanding $\left(\sum_{i=1}^N h_{it,0} u_i^* \right)^2$, it is $O_p(N^2)$ by the assumptions that $E(h_{it,0} h_{jt,0}) < K$ and $E(u_i^* u_j^*) < K$ for all i, j . Together with $E\|\boldsymbol{\xi}_{it} \boldsymbol{\xi}'_{it}\| < K$, we get

$$\text{Var} \left[T^{-1} \sum_{t=1}^T \boldsymbol{\xi}_{it} N^{-1} \sum_{i=1}^N h_{it,0} u_i^* \right] = O(T^{-1}),$$

which implies $T^{-1} \sum_{t=1}^T \boldsymbol{\xi}_{it} N^{-1} \sum_{i=1}^N h_{it,0} u_i^* = O_p(T^{-1/2})$. \square

Proof of Lemma (C7). Consider the mean. Because v_{it} , \mathbf{e}_{it} , $h_{it,0}$ and u_i^* are mutually independent, we can obtain the mean is $\mathbf{0}$ easily. Next, the variance,

$$\begin{aligned}
\text{Var} \left[T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) \bar{\boldsymbol{\xi}}_t \right] &= T^{-2} \sum_{t=1}^T E \left(u_i^* (h_{it,0} - \bar{h}_{i,0}) \right)^2 E(\bar{\boldsymbol{\xi}}_t \bar{\boldsymbol{\xi}}'_t) \\
&= T^{-2} \sum_{t=1}^T E(u_i^{*2}) E(h_{it,0} - \bar{h}_{i,0})^2 E(\bar{\boldsymbol{\xi}}_t \bar{\boldsymbol{\xi}}'_t).
\end{aligned}$$

Notice that the above holds by the fact v_{it} and \mathbf{e}_{it} are serially uncorrelated and assumptions we used in the mean. Because we have $E(u_i^{*2}) < K$, $E(h_{it,0} - \bar{h}_{i,0})^2 < K$ and the order of $E(\bar{\boldsymbol{\xi}}_t \bar{\boldsymbol{\xi}}'_t)$ is $O(N^{-1})$. Thus, we have $\text{Var} \left[T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) \bar{\boldsymbol{\xi}}_t \right] = O((NT)^{-1})$, and it follows that $T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) \bar{\boldsymbol{\xi}}_t = O_p((NT)^{-1/2})$. \square

Proof of Lemma (C8). We first consider its mean. Write,

$$\begin{aligned}
& E \left[T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) N^{-1} \sum_{j=1}^N h_{jt,0} (\mu_0^+ - u_j^*) \right] \\
&= (NT)^{-1} \left[E \sum_{t=1}^T (u_{it} - \bar{u}_i) h_{it,0} (\mu_0^+ - u_i^*) + E \sum_{t=1}^T (u_{it} - \bar{u}_i) \sum_{j \neq i}^N h_{jt,0} (\mu_0^+ - u_j^*) \right],
\end{aligned}$$

where the second term inside the square brackets is 0 by the assumption that u_i^* is cross-sectional independent. Further, since $u_{it} = h_{it,0}u_i^*$ and using the assumptions that $h_{it,0}$ and u_i^* are mutually independent with finite mean and variance, we get

$$\begin{aligned} & E \left[T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) N^{-1} \sum_{j=1}^N h_{jt,0} (\mu_0^+ - u_j^*) \right] \\ &= (NT)^{-1} \sum_{t=1}^T [E(h_{it,0}^2 - h_{it,0}\bar{h}_{i,0})E(u_i^{*2} - u_i^*\mu^+)] = O(N^{-1}). \end{aligned} \quad (\text{S.8})$$

Consider the variance, we first evaluate the term

$$\begin{aligned} & (NT)^{-2} E \left[\sum_{t=1}^T (u_{it} - \bar{u}_i) \sum_{j=1}^N h_{jt,0} (\mu_0^+ - u_j^*) \right]^2 \\ &= (NT)^{-2} E \left[\sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0})^2 u_i^{*2} \left(\sum_{j=1}^N h_{jt,0} (\mu_0^+ - u_j^*) \right) \left(\sum_{k=1}^N h_{kt,0} (\mu_0^+ - u_k^*) \right) \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} (h_{it,0} - \bar{h}_{i,0})(h_{is,0} - \bar{h}_{i,0}) u_i^{*2} \left(\sum_{j=1}^N h_{jt,0} (\mu_0^+ - u_j^*) \right) \left(\sum_{k=1}^N h_{ks,0} (\mu_0^+ - u_k^*) \right) \right]. \end{aligned}$$

Note that the expected value of above equation is non-zero only in the case that $j = k$, so we can rewrite them as

$$\begin{aligned} & (NT)^{-2} E \left[\sum_{t=1}^T (u_{it} - \bar{u}_i) \sum_{j=1}^N h_{jt,0} (\mu_0^+ - u_j^*) \right]^2 \\ &= (NT)^{-2} E \left[\sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0})^2 u_i^{*2} \sum_{j=1}^N h_{jt,0}^2 (\mu_0^+ - u_j^*)^2 \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} (h_{it,0} - \bar{h}_{i,0})(h_{is,0} - \bar{h}_{i,0}) u_i^{*2} \left(\sum_{j=1}^N h_{jt,0} h_{js,0} (\mu_0^+ - u_j^*)^2 \right) \right] \\ &= (NT)^{-2} E \left[\sum_{t=1}^T (h_{it,0}^2 - h_{it,0}\bar{h}_{i,0})^2 (u_i^* \mu_0^+ - u_i^{*2})^2 + \sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0}) u_i^{*2} \sum_{j \neq i}^N h_{jt,0}^2 (\mu_0^+ - u_j^*)^2 \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} (h_{it,0}^2 - h_{it,0}\bar{h}_{i,0})(h_{is,0}^2 - h_{is,0}\bar{h}_{i,0}) (u_i^* \mu_0^+ - u_i^{*2})^2 \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} (h_{it,0} - \bar{h}_{i,0})(h_{is,0} - \bar{h}_{i,0}) u_i^{*2} \left(\sum_{j \neq i}^N h_{jt,0} h_{js,0} (\mu_0^+ - u_j^*)^2 \right) \right]. \end{aligned} \quad (\text{S.9})$$

Given the assumptions that $h_{it,0}$ and u_i^* are mutually independent with finite fourth moment, the first term inside square brackets divided by $(NT)^2$ is $O(N^{-2}T^{-1})$. Using the similar argument, the third term divided by $(NT)^2$ is $O(N^{-2})$. Further, since u_i^* is cross-sectional independent and $h_{it,0}$ is covariance stationary process, the second and fourth terms divided by $(NT)^2$ are $(NT)^{-1}$. Thus, by summarizing (S.8) and (S.9), we have $\text{Var} \left[T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) N^{-1} \sum_{j=1}^N h_{jt,0} (\mu_0^+ - u_j^*) \right] =$

$O(N^{-2}) + O((NT)^{-1})$. Therefore, we obtain $T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) N^{-1} \sum_{j=1}^N h_{jt,0} (\mu_0^+ - u_j^*) = O_p(N^{-1}) + O_p((NT)^{-1/2})$. \square

Proof of Lemma (C9). Since $h_{it,0}$, D_t and \mathbf{f}_t are independent stationary process, it is easy to obtain $T^{-1}((\mathbf{u}_i - \bar{u}_i)' D) = O_p(T^{-1/2})$ and $T^{-1}((\mathbf{u}_i - \bar{u}_i)' \mathbf{F}) = O_p(T^{-1/2})$. The remains can be denoted as $T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) N^{-1} \sum_{j=1}^N h_{jt,0} u_j^*$, and using the similar arguments in Lemma (C8), the mean,

$$\begin{aligned} & E \left[T^{-1} \sum_{t=1}^T (u_{it} - \bar{u}_i) N^{-1} \sum_{j=1}^N h_{jt,0} u_j^* \right] \\ &= (NT)^{-1} \left[E \sum_{t=1}^T (h_{it,0}^2 - h_{it,0} \bar{h}_{i,0}) u_i^{*2} + E \sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0}) u_i^* \sum_{j \neq i}^N h_{jt,0} u_j^* \right] \\ &= (NT)^{-1} \left[\sum_{t=1}^T E(h_{it,0}^2 - h_{it,0} \bar{h}_{i,0}) E(u_i^{*2}) \right] = O(N^{-1}). \end{aligned} \quad (\text{S.10})$$

The second equality holds by the fact that $h_{it,0}$ is cross-sectional independent with $E[\sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0})] = 0$. The result holds by $h_{it,0}$ and u_i^* are mutually independent with finite mean and variance.

Next, we consider

$$\begin{aligned} & (NT)^{-2} E \left[\sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0}) u_i^* \sum_{j=1}^N h_{jt,0} u_j^* \right]^2 \\ &= (NT)^{-2} E \left[\sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0})^2 u_i^{*2} \left(\sum_{j=1}^N h_{jt,0} u_j^* \right) \left(\sum_{k=1}^N h_{kt,0} u_k^* \right) \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t}^T (h_{it,0} - \bar{h}_{i,0})(h_{is,0} - \bar{h}_{i,0}) u_i^{*2} \left(\sum_{j=1}^N h_{jt,0} u_j^* \right) \left(\sum_{k=1}^N h_{ks,0} u_k^* \right) \right] \\ &= (NT)^{-2} E \left[\sum_{t=1}^T (h_{it,0}^2 - h_{it,0} \bar{h}_{i,0})^2 u_i^{*4} + \sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0})^2 u_i^{*2} \left(\sum_{j \neq i}^N \sum_{k \neq i}^N h_{jt,0} h_{kt,0} u_j^* u_k^* \right) \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} (h_{it,0}^2 - h_{it,0} \bar{h}_{i,0})(h_{is,0}^2 - h_{is,0} \bar{h}_{i,0}) u_i^{*4} \right. \\ & \quad \left. + \sum_{t=1}^T \sum_{s \neq t} (h_{it,0} - \bar{h}_{i,0})(h_{is,0} - \bar{h}_{i,0}) \left(\sum_{j \neq i}^N \sum_{k \neq i}^N h_{jt,0} h_{ks,0} u_j^* u_k^* \right) \right]. \end{aligned} \quad (\text{S.11})$$

The above expressions are quite similar with (C8), the assumptions that $h_{it,0}$ and u_i^* are mutually independent with finite fourth moment imply the first and third terms divided by $(NT)^2$ are $O(N^{-2}T^{-1})$ and $O(N^{-2})$. The difference is that the case $j \neq k$ is non-zero here, thus the second and fourth terms divided by $(NT)^2$ are $O(T^{-1})$. Taking (S.10) and (S.11) together, we have $\text{Var} \left[T^{-1} \sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0}) u_i^* N^{-1} \sum_{j=1}^N h_{jt,0} (u_j^* - \mu_0^+) \right] = O(N^{-2}) + O(T^{-1})$, which implies

$$T^{-1} \sum_{t=1}^T (h_{it,0} - \bar{h}_{i,0}) u_i^* N^{-1} \sum_{j=1}^N h_{jt,0} (u_j^* - \mu_0^+) = O_p(N^{-1}) + O_p(T^{-1/2}). \quad \square$$

Proof of Lemma (C10). The proof of (C10) is quite similar to the last part of (C9) except we drop u_i^* from $(u_{it} - \bar{u}_i)$ and do not evaluate at true value of δ . We still have the same result that is $T^{-1} \sum_{t=1}^T (h_{it} - \bar{h}_i) N^{-1} \sum_{j=1}^N h_{jt,0} u_j^* = O_p(N^{-1}) + O_p(T^{-1/2})$. \square