



# Irrigation Management

David L. Bjorneberg,\* Robert G. Evans, and E. John Sadler

## Abstract

Competition for limited water supplies continues to restrict water available for irrigation. Irrigated agriculture must continually improve irrigation management to continue producing food, fiber, and fuel for a growing world population. Precision irrigation is the process of applying the right amount of water at the right time and place to obtain the best use of available water. Precision irrigation management is needed on large irrigation projects so water delivery matches irrigation needs and on individual fields to apply the right amount of water at the right time and place. Technology is commercially available to precisely apply water when and where crops need it; however, user-friendly decision tools are still needed to quantify specific irrigation needs and control water application within fields. Integrating information from various sensors and systems into a decision support program will be critical to highly managed, spatially varied irrigation.

Irrigation supplements precipitation in the hydraulic cycle with the primary goal of meeting the transpiration needs of crops. Ideally, all applied irrigation water would be beneficially used by crops. However, irrigation systems cannot be controlled and operated to apply the exact amount of water that each individual plant requires. Applying too much water in an area can cause deep percolation and leaching. Applying water faster than it can infiltrate results in ponding and runoff. Ponded water can evaporate and therefore is not beneficially used by crops. Runoff water either flows from the field, becoming an off-site problem, or infiltrates in other areas of the field causing nonuniform soil water content in the field. Continued nonuniform irrigation with in-field runoff can cause deep percolation in areas where runoff infiltrates. In addition to being a nonbeneficial use of water, deep percolation and off-site runoff often transport nutrients and sediment.

Irrigation research and development has historically attempted to uniformly irrigate fields even though fields are seldom uniform. Even large irrigation projects often deliver water uniformly to all fields within the project regardless

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Abbreviations: ET, evapotranspiration; ICID, International Commission on Irrigation and Drainage; SSIM, site-specific irrigation management.

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of crops grown or irrigation systems used. The goal of precision irrigation is to apply the right amount of water at the right time and place at any scale. Precision irrigation often confers images of center-pivot irrigation systems with sprinklers pulsing on and off as the machine rotates through the field. Varying irrigation rates within a field, however, is only one facet of precision irrigation. Precision irrigation can be applied at any scale or with any type of irrigation. At the irrigation project scale, managers need to know crop water requirements so irrigation diversions can be adjusted to meet the irrigation demand. Irrigators at the farm scale need similar information to ensure that their water supply can meet the needs of the crops on their farm. On individual fields, farmers need to know crop water requirements to schedule irrigation and have irrigation systems with the capability and flexibility to apply the right amount of water in the right place and time.

In humid, and even semiarid areas, crop irrigation requirements must be determined throughout the growing season to account for precipitation and variations in crop growth to precisely irrigate. In arid areas, precipitation during the growing season is usually minimal; however, arid areas still benefit from in-season measurements of crop water use to precisely apply irrigation water. Precision irrigation requires knowledge of crop water needs, soil water holding capacity, irrigation system capacity, and available water supply. If any one of these factors is not considered, irrigation water can be over- or underapplied. Insufficient irrigation will reduce crop yield and will cause unacceptable quality for some crops. Irrigating too much wastes water and can cause runoff or deep percolation.

All of the precision seeding, tillage, fertility, and conservation concepts for nonirrigated farming apply to irrigated production with the advantage—and complication—of the ability to vary water application. Precision irrigation is perhaps the most complicated aspect of precision agriculture because irrigation decisions are made multiple times each season, and irrigation interacts with fertilizer and disease management. Crop water use, for example, can be greater at higher N fertilization rates (Lenka et al., 2009) or similar between low and high rates (Holmen et al., 1961). Pandey et al. (2000) showed that maize (*Zea mays* L.) yield reductions to water shortage were greater at high N fertilization rates than low rates. Crop response to applied water cannot be assumed to be the same under uniform irrigation management and site-specific irrigation (Sadler et al., 2002). Intuitively, lower-yielding areas in an irrigated field should require less water and fertilizer. However, low-yielding areas may require more water and nutrients per unit of production. If water supply is limited, the best practice may be to not irrigate low-yielding areas and focus irrigation on higher-yielding areas. Precisely applying irrigation water can also alleviate some soil issues by ensuring that water application rates match soil infiltration rates. Technology to precisely apply irrigation water is wasted if the water does not infiltrate into the soil where it was applied and remain in the soil profile for the crop to use.

The purpose of this chapter is to discuss aspects and technologies affecting precision irrigation. One major aspect affecting precision irrigation is the availability of water to irrigate. Managing an irrigation system connected to a high-capacity well is not restricted by water supply. Off-site water suppliers, however, often restrict irrigation amounts and timing, providing an additional challenge to applying the right amount of water at the right time. Low-capacity wells or regulatory limitations on groundwater withdrawal can also restrict

water supply. Another major aspect of precision irrigation is determining crop water needs so adequate water can be supplied to an entire irrigation project or applied on irrigated farms and fields. Finally, technology for managing irrigation application on fields is discussed.

## Background

Irrigation is the process of artificially applying water to soil with the intention of improving crop yield and quality. Humans have used irrigation to help provide more stable food production for 8000 yr, initially diverting and channeling floodwaters from the Nile or Tigris and Euphrates Rivers. Irrigation equipment and techniques have evolved from hand-dug ditches and wild flooding to carefully controlled microirrigation and variable-rate, center-pivot machines that can be operated remotely from cell phones or computers. Irrigation enhances the magnitude, quality, and reliability of crop production. According to the Food and Agriculture Organization of the United Nations, irrigation contributes to ~40% of the world's food production on <20% of the world's crop production land. In the United States, only 8% of the total cropland is on farms where all crops are irrigated (USDA-NASS, 2014a). These farms produce 27% of the market value of crops and 12% of the total market value of all livestock. Half of the crop value is produced on farms with some irrigated land, and these farms account for only 28% of the total cropland in the United States (USDA-NASS, 2014b).

Certain crops rely heavily on irrigation (Table 1). All rice (*Oryza sativa* L.) in the United States is grown with irrigation, while only 9% of the soybean [*Glycine*

**Table 1. Total and irrigated crop area in the United States.**

Crop	Total area†	Total irrigated crop area‡		Pressurized irrigation§	Gravity irrigation‡
	ha	ha	%	ha	
Corn (grain)	35,389,897	5,189,906	15	4,458,346	921,916
Corn (silage)	2,913,615	665,488	23	487,503	212,642
Sorghum (grain)	2,081,821	253,606	12	277,842	49,923
Wheat	19,854,343	1,363,630	7	1,074,673	219,862
Soybean	30,811,652	2,897,738	9	1,636,397	1,364,930
Dry edible bean	665,100	191,703	29	129,713	45,830
Rice	1,090,591	1,090,591	100	13,640	1,254,738
Other small grains (barley, oats, rye, etc.)	21,727,990	489,687	2	359,500	130,187
Alfalfa (hay and silage)	6,731,106	2,340,591	35	1,435,385	796,547
All other hay	16,371,840	1,575,706	10	592,238	744,154
Peanuts	656,531	211,204	32	145,953	4,506
Cotton	3,799,223	1,543,909	41	882,562	313,574
Orchards, vineyards, and nut trees	2,105,153	1,723,495	82	1,274,689	207,955
All vegetables	1,692,668	1,212,479	72	1,074,192	137,791
All berries	117,374	88,798	76	89,635	2,532
All cropland	157,769,398	22,600,094	14	16,106,891	8,706,350

† From USDA-NASS 2012 Census of Agriculture (USDA-NASS, 2014a).

‡ From USDA-NASS 2013 Farm and Ranch Irrigation Survey (USDA-NASS, 2014b).

§ Pressurized irrigation includes sprinkler, micro, and drip irrigation.

*max* (L.) Merr.] and 7% of the wheat (*Triticum aestivum* L.) in the United States are grown with irrigation. In addition, irrigation is used on 82% of the land in orchards, 72% of land growing vegetables, and 76% of the land growing berries. While irrigation is important for crop production, it accounts for 38% of the total freshwater withdrawal in the United States, which equals freshwater withdrawal for thermoelectric power (Maupin et al., 2014). Approximately 75% of the total freshwater withdrawal in the seven western states is used for irrigation, and 67% of this is surface water (Maupin et al., 2014). Continued improvements in irrigation management, as well as agronomic management, are required to make the best use of limited water resources by applying the appropriate amount of water at the right time to all areas in a field.

Irrigation is generally categorized by the three main methods of applying water: surface, sprinkler, and microirrigation. Water flows over the soil by gravity for surface irrigation. Sprinkler irrigation applies water to soil by sprinkling or spraying water droplets from fixed or moving irrigation systems under pressure. Microirrigation applies frequent, small applications by dripping, bubbling, or spraying at low pressures and usually only wets a portion of the soil surface in the field. A fourth, and minor, irrigation method is subirrigation, where the water table is raised to or held near the plant root zone using ditches or subsurface drains to supply the water, used mostly in humid regions. According to the International Commission on Irrigation and Drainage (ICID), surface irrigation is used on about 85% of the 299 Mha of irrigated cropland in the world (ICID, 2013). India and China each irrigate >60 Mha of cropland (FAO, 2013) and ~95% of this land is surface irrigated (ICID, 2013). The United States and Pakistan each have about 20 Mha of irrigated land. These four countries account for 55% of the irrigated land in the world; all other countries each have <10 Mha of irrigated land. Of these four countries, only the United States uses sprinkler and microirrigation on a significant portion of the irrigated cropland. Sprinkler irrigation is used on 57% of the 22 Mha of cropland irrigated in the United States, while microirrigation is used on ~8% of the irrigated cropland, and these percentages continue to increase (Fig. 1). The amount of US farmland irrigated by center pivots has increased almost linearly since they were first marketed in the late 1960s. Center-pivot irrigation in the United States has increased ~240,000 ha yr<sup>-1</sup> and is used on 80% of the sprinkler-irrigated land and 45% of all irrigated land (USDA-NASS, 2014b).

### Available Water Supply

Irrigation water for ~25% of the US irrigated land is supplied by off-farm sources (USDA-NASS, 2014b). The percentage is likely higher in China, India, and Pakistan. Precision irrigation on farms in these irrigation projects must include allowances for water delivery limitations. Irrigation projects have rules for irrigation water delivery that govern how far in advance a request must be made and whether the request is for a volume or flow rate for a specified time. In general, irrigation projects are either supply oriented (rigid schedule) or demand oriented (flexible schedule). Some projects may shift from demand-based to supply-based operation as irrigation demand increases during the season to a point where irrigation demand exceeds the capacity of the canal system (Lozano and Mateos, 2008). Supply-oriented systems generally operate canals at constant flow rates to efficiently use the canal system that required large capital investment to construct (Merriam

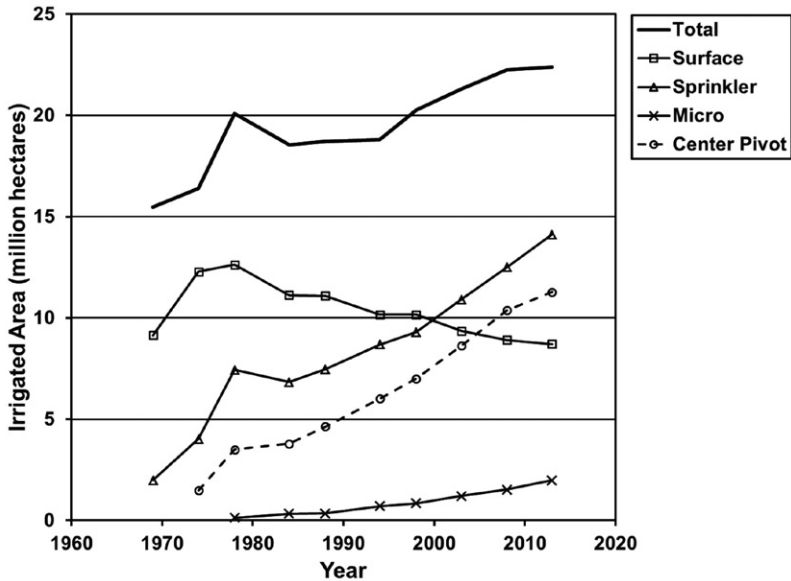


Fig. 1. Trends in US irrigated acreage for 1969 through 2013 (from USDA-NASS, 2014a).

et al., 2007). However, this operating method does not account for specific crop irrigation needs in specific fields, which led Merriam et al. (2007) to call supply-oriented delivery an engineer's dream and a farmer's nightmare. Clemmens (2006) referred to supply-oriented delivery as water disposal not irrigation water management. Supply-oriented systems tend to be hydraulically efficient but inefficient for crop water management.

Irrigation projects using supply-oriented schedules may allocate water on a flow rate per unit area, a volume per unit area, or flow rate for specified time interval. A specific example of a flow-rate allocation project is the Twin Falls Canal Company in southern Idaho. The Twin Falls Canal Company was established in 1900 and originally planned to divert  $85 \text{ m}^3 \text{ s}^{-1}$  from the Snake River to irrigate 97,000 ha (Bjorneberg et al., 2008). Since the canal company has a natural-flow water right, irrigation water is continually available at  $52 \text{ L m}^{-1} \text{ ha}^{-1}$  (total flow rate divided by total project area) during the entire irrigation season. If flow in the river is not adequate to meet this supply, the allocation per hectare is reduced proportionally to all users. This flow-rate allocation continues today even though water stored in upstream reservoirs supplements the natural river flow so the need to reduce allocations is much less. While a flow rate is available during the entire irrigation season, it is not practical to continually use this flow rate, especially in the spring and fall. In the summer however, the flow rate allocation of  $52 \text{ L m}^{-1} \text{ ha}^{-1}$  is only  $7.5 \text{ mm d}^{-1}$ , which does not meet peak irrigation demand for many crops. Consequently, farmers grow a variety of crops to spread irrigation demand throughout the irrigation season to better balance irrigation supply with crop demand. The flow rate allocation is unlikely to change as long

as the natural-flow water right exists, demonstrating how policies and regulations impact irrigation management.

Rigid water allocation policies like the previous example provide little incentive for growers to adopt advanced irrigation systems and management practices such as precision irrigation. On the other hand, flexible irrigation water delivery strives to match delivery with irrigation demand. This is complicated in large irrigation projects (e.g., >20,000 ha) because it may take one or more days for water to travel from the diversion point to the field. Changing the flow rate at the main diversion causes a sudden flow-rate change in the canal that dissipates downstream. Operators further downstream often need to make multiple adjustments to account for the gradual flow-rate change (Clemmens, 2006). Automated diversion gates can be used to maintain desired flow rates within the irrigation project (van Overloop et al., 2010). Bautista et al. (2006) demonstrated a control system that used pre-established canal hydraulic relationships to make upstream flow changes to meet downstream delivery changes. Automated control of canal systems, however, is complicated, requiring excellent measurement and control equipment, good communication systems, and algorithms and strategies for controlling the equipment. Implementation usually involves problems that require adjustments to algorithms and control equipment (Burt and Piao, 2004), but these problems should not prohibit irrigation projects from implementing advanced control systems.

Flexible water delivery requires adequate canal design to carry and deliver varied flow rates that meet irrigation demand throughout the irrigation system for the entire irrigation season. Canal systems that provide flexible delivery tend to be more costly to construct and operate than canals designed for supply-based delivery. Exceeding existing canal flow capacity is an obvious problem. Low irrigation demand can also be a problem if the canal system requires a minimum flow rate before water reaches a specific elevation required for water delivery gates. Additional check structures may be needed to allow water delivery at lower flow rates. Additional small water storage facilities distributed within the canal system may also be necessary to store excess water during low demand periods and to more quickly supply water as demand increases.

On-farm water storage also increases irrigation flexibility when off-farm or on-farm water supplies are limited by flow rate or time. Continuous off-farm water supply can be stored to enable daytime only irrigation or odd irrigation set times for better surface irrigation management. Pressurized irrigation systems may be able to use off-peak electric supplies by storing water from an off-farm supplier during peak electrical usage time. Farms with low-capacity wells can also benefit from on-farm storage. The low-capacity well can continuously pump water into storage even if the field is not being irrigated as a result of precipitation or field operations. A disadvantage of on-farm storage is that land is taken out of production for the reservoir, and some water will be lost to evaporation and seepage. Producers need to compare the lost production from the reservoir area with the increased yield from the remaining irrigated land on the farm.

Although applying irrigation when the crop needs water is the best practice, Schlegel et al. (2012) determined that many irrigation systems cannot meet peak crop water demands and must rely on stored soil water to meet crop water needs. They found that preseason irrigation was profitable for wells with 2.5 to 5 mm d<sup>-1</sup> capacities in Kansas, and water use efficiency (crop yield per unit water applied)

was not significantly affected by preseason irrigation. In this case, the soil is the on-farm storage reservoir.

## Crop Water Needs

At the project, farm, and field scales, the first step for precision irrigation is to know how much water a crop needs at a given time. This is typically done by calculating evapotranspiration (ET), which is the amount of water that evaporates from the soil and plant surfaces and transpires from plants. Evapotranspiration can be estimated from meteorological data, remotely sensed information (e.g., temperature and reflectance), soil water depletion, or crop condition. Precision irrigation requires ET information sufficiently in advance so water can be delivered (if supplied from an off-farm source) and applied when needed by the crop. At the field scale, irrigation systems typically cannot instantaneously irrigate the entire field, so allowances must be made for the physical ability to apply water over several days on an individual field. Irrigation system limitations can result in certain parts of the field being overirrigated, while other parts may experience some level of water stress.

### Evapotranspiration

Various methods are available to calculate ET from meteorological data. A common method is the American Society of Civil Engineers' standardized Penman–Monteith method (Allen et al., 2005), which is used to calculate alfalfa (*Medicago sativa* L.) reference ET. The reference ET is multiplied by a crop coefficient to estimate ET for a specific crop during the growing season. Crop coefficients can be determined by methods described in FAO Irrigation and Drainage Paper No. 56 (Allen et al., 1998). Since calculating reference ET and crop coefficients for daily use is cumbersome and time consuming, various ET networks provide crop water use information to users for irrigation scheduling. The US Bureau of Reclamation, for example, has AgriMet, a network of over 70 automatic agricultural weather stations covering irrigated areas in the Pacific Northwest (<http://www.usbr.gov/pn/agrimet/>). Similarly, many state networks exist such as California Irrigation Management Information System (CMIS, <http://www.cimis.water.ca.gov/>), Texas ET Network (<http://texaset.tamu.edu/>), and Colorado Agricultural Meteorological Network (CoAgMet, <http://www.coagmet.colostate.edu>). It is important to remember that these networks provide potential ET values for a crop; actual ET could be greater or less depending on local field and crop conditions such as soil, fertility, disease, and precipitation. Specific knowledge about each field, and locations within fields, is required to precisely irrigate that field. Evett et al. (2012a) noted that crop coefficient values are sensitive to local climate conditions and often are not transferable to other areas. Specific soil or plant monitoring within the field is necessary to determine if net applied irrigation water is meeting or exceeding actual crop use.

Evapotranspiration can be directly measured using micrometeorological methods such as eddy covariance (e.g., Swinbank, 1951; Twine et al., 2000), Bowen ratio (e.g., Sinclair et al., 1975; Payero et al., 2003), or surface renewal (Paw U et al., 1995; Snyder et al., 2008). Eddy covariance and Bowen ratio methods require careful attention to site conditions and instrument operation. The surface renewal method has a relatively lower cost than other micrometeorological methods



because sensible heat flux is determined with high frequency air-temperature measurements with fine-wire thermocouples (Mengistu and Savage, 2010). The disadvantage of surface renewal is the need to calibrate a weighting factor for a particular plant canopy (Snyder et al., 2008). All three methods require that measurements must be made in areas that represent the field conditions where the data will be applied, so these methods are not readily applicable for identifying variable irrigation requirements within a field. Furthermore, Evett et al. (2012b) concluded that it was difficult to estimate ET well using eddy covariance and Bowen ratio even with the best equipment and expert operators.

### Soil Water Depletion

A key aspect of precision irrigation is measuring soil water content throughout the crop root zone to quantify the amount of water added to soil by irrigation and precipitation and removed from the soil by crops, evaporation, or deep percolation. These measurements can be used to schedule irrigation by applying enough water to replace water used since the last irrigation. Soil water content may also be used to verify and reset irrigation scheduling models that are based on ET estimations. A variety of direct and indirect methods can be used to measure soil water content. Direct measurement involves collecting a soil sample of known volume, determining the mass of the sample, drying the sample, and determining the mass of the dry sample. Direct measurement is highly accurate but time consuming, so it is mainly used to verify or calibrate indirect measurement methods rather than monitor soil moisture conditions for irrigation scheduling.

Indirect methods include neutron moisture meter and various sensors that use electromagnetic methods. The neutron moisture meter is an accurate method for repeated measurements of soil profile water content (Evett and Steiner, 1995). However, measurements cannot be automated, and a permit is required for the radiation source in the meter so neutron moisture meters have seen limited use beyond research. Time domain reflectometry is another indirect method of measuring soil water content that has been shown to be accurate and repeatable (Evett, 1998; Herkelrath et al., 1991). A variety of other electromagnetic sensors are now available for measuring soil water content. Evett et al. (2009) compared three capacitance-type sensors with neutron moisture meter and gravimetric measurements. Spatial variations of measured soil water profiles were similar between the neutron moisture meter and gravimetric methods. The electromagnetic sensors, however, had greater variability and were relatively inaccurate even though soil-specific calibrations were used. Evett et al. (2012b) found that capacitance sensors used in access tubes had soil water content errors up to  $0.05 \text{ m}^3 \text{ m}^{-3}$ , which implied errors in soil water flux estimation of up to  $50 \text{ mm d}^{-1}$ . They concluded that capacitance-based soil water sensing was not suited to accurate measurement primarily because the electromagnetic field does not uniformly permeate the soil around the access tube in structured soils. For accurate determination of ET and crop water production, they recommended using neutron probe, gravimetric sampling, or conventional time domain reflectometry methods.

Soil water potential can be measured in addition to soil water content. Soil water potential indicates the amount of work required for a plant to take up water from the soil. While plants directly respond to soil water potential, it does not directly tell the irrigator how much water to apply. Relationships can be developed between soil water content and water potential so water potential can be used for



scheduling irrigation. Various instruments are available to directly or indirectly measure soil water potential. Tensiometers have been used for the last 100 yr (Or, 2001) to directly measure soil water potential. The original measurement device on tensiometers was a mercury manometer, then bourdon-type gauges, and now digital pressure sensors can be used to continuously and remotely measure soil water potential. Two common indirect measurement devices are gypsum blocks and granular matrix sensors, which measure soil water potential over a wider range than tensiometers. Both sensors have porous material that loses water as the soil dries and gains water as the soil becomes wetter. While gypsum blocks are relatively inexpensive, they are better suited to measure relative soil water changes to determine when to irrigate rather than determining irrigation amounts. If properly calibrated, granular matrix sensors indicate trends that can be used for irrigation scheduling.

### Remote Sensing to Determine Crop Water Needs

Remote sensing can be used to determine crop water use at project, farm, and field scales. Satellite-based remote sensing has advanced to where submeter resolution and daily coverage are possible with many defined spectral indices available besides normalized difference vegetation index (Mulla, 2013). Sensors are also available to mount on tractors, sprayers, or moving irrigation systems to provide real-time information. The same remote sensing technologies and management can be applied on irrigated farms and nonirrigated farms with the obvious exception that remote sensing can inform and guide water application decisions for irrigated farms. Irrigation also allows fertilizer or other chemicals to be applied during the growing season when ground-based applicators will damage the crop.

Remote sensing is useful for systematic measurements with time over large areas (Bastiaanssen et al., 2000). Jackson et al. (1977) first related the difference between canopy temperature and air temperature to ET. Satellite or aerial remote sensing can provide repeated field observations for an entire irrigation project that can be used in models to guide diversions of irrigation water or identify variations within fields. Remote sensing can also identify the actual irrigated area of specific crops within an irrigation project so managers can better plan diversions to match crop water needs. Michael and Bastiaanssen (2000) developed a technique to define crop coefficient maps from satellite images. Total crop water use for an irrigated area can then be calculated by multiplying reference ET by the crop coefficient. SEBAL (Bastiaanssen et al., 1998), METRIC (Allen et al., 2007), and ALEXI (Anderson et al., 2012) are energy balance models that use thermal infrared imagery for estimating ET for large areas. The Surface Energy Balance Algorithm for Land (SEBAL) model describes the spatial variability of most micrometeorological variables with semiempirical functions. SEBAL can be applied for diverse agroecosystems and does not require ancillary information on land use or crop types (Bastiaanssen et al., 1998). Validation efforts have shown that the error at a 1-ha scale varies between 10 and 20% and that the uncertainty diminishes with increasing scale. For an area of 1000 ha, the error is reduced to 5% and for regions of 1 million ha of farmland, the error becomes negligibly small (Bastiaanssen et al., 2000). Mapping EvapoTranspiration at High Resolution and Internalized Calibration (METRIC) uses the same basic energy balance algorithms as SEBAL to calculate ET from satellite imagery (Allen et al., 2007, 2011). However, METRIC uses reference ET calculated from micrometeorological data to extrapolate ET

between instantaneous satellite images. The Atmosphere-Land Exchange Inverse (ALEXI) model (Anderson et al., 1997; Mecikalski et al., 1999) was developed as an auxiliary means for estimating surface fluxes over large regions using primarily remote-sensing data. This flux model is unique in that no information regarding antecedent precipitation or moisture storage capacity is required because the surface moisture status is deduced from a radiometric temperature change signal. Therefore, ALEXI can provide independent information for updating soil moisture variables in more complex regional models. However, these models require significant processing time, so real-time daily ET estimates are not available.

Direct ET measurements like eddy covariance, Bowen ratio, and surface renewal do not provide information about spatial variability within a field. Satellite and air-based remote sensing provide spatial information, but measurement intervals are usually >1 d. Combining direct or reference ET measurements from micrometeorological methods with remotely sensed spatial information can provide daily, site-specific ET information within fields. Jackson et al. (1977) developed a technique to calculate daily ET from one-time-of-day measurements. Peters and Evett (2004) used one-time-of-day measurements with a reference temperature curve from a fixed location to model diurnal canopy temperature dynamics within a field. Ben Asher et al. (2013) combined the Penman-Monteith ET equations with infrared radiometers mounted on a linear-move irrigation system to calculate hourly ET to control an irrigation system without monitoring soil water. This system provided a bulk representation of the field not site-specific information within the field. Remotely sensed thermal and reflectance information from the crop canopy can be used to calculate site-specific water use. Colaizzi et al. (2012) used a two-source energy balance model to predict daily ET of corn, cotton (*Gossypium hirsutum* L.), grain sorghum [*Sorghum bicolor* (L.) Moench], and wheat. Their technique may allow the center pivot to be the remote sensing platform for collecting real-time information for calculating site-specific ET.

### Field-Scale Precision Irrigation

For at least the last 50 yr, irrigation research has attempted to understand crop water needs and to apply water uniformly to fields. Good irrigation management should strive to optimize crop yield in a field. When irrigation is not uniform, some areas receive more water than required and some areas receive less. To reduce the assumed negative effects of too little irrigation, operators may apply additional water to the entire field, which means a larger portion of the field is overirrigated and may actually reduce total crop yield from the field. Soils are seldom uniform within a field, indicating that infiltration rates and potential crop yields will also vary within a field. Although modern center-pivot irrigation systems uniformly apply irrigation water, water will not uniformly infiltrate if soil properties are not uniform. Uniformly applied irrigation water, or rainfall, that runs off and infiltrates in another area in the field leads to nonuniform infiltration. This in-field runoff causes variations in stored soil water, which in turn causes variable irrigation requirements. Couple this with variable productivity and noncropped areas within fields and the justification for site-specific irrigation management (SSIM) becomes evident. However, there is little scientific information demonstrating its cost-effectiveness or documenting the capability

of site-specific sprinkler irrigation to conserve water or energy on a field scale (Evans and King, 2012).

Center-pivot and linear-move sprinkler irrigation systems are well suited to precision irrigation management. These moving irrigation systems can be designed and controlled to apply different rates of water on different locations in the field. Solid set or permanent sprinkler irrigation systems, including microirrigation, can also be designed to differentially apply water. Since these systems do not move, sprinkler application rates can be permanently or seasonally adjusted by changing sprinklers or nozzles to meet water needs for specific areas. Varying the duration of irrigation events among management zones can also be used provided that the irrigation zones match the field variability. Set-move irrigation systems (e.g., side-roll systems) can apply variable amounts of water if sprinkler nozzles vary along the system or are changed between irrigation sets. At this time, this would require extensive manual labor. Varying application rates to precisely meet irrigation requirements within a field is nearly impossible with surface irrigation because water flows by gravity on the soil surface through the field. Individual basins, borders, or furrows can be irrigated for different time intervals, but application depth cannot be controlled spatially within these units. Even if surface irrigation could be controlled to spatially vary water application, the irrigator would need to know how much water will infiltrate in a specific time period (through measurement or models) to precisely apply the right amount of water in the right location.

Moving sprinkler irrigation systems, like center-pivot and linear-move irrigation systems, are probably the most appropriate platform for SSIM in crop fields. Center-pivot irrigation systems mechanically move through the entire field multiple times per year enabling irrigation amounts and rates to vary within the season and between seasons. Technology for controlling center-pivot operation is continually changing from the original on-off switch and speed control dial. Operators can now communicate with irrigation machines by cell phones, satellite radios, and internet-based systems (Kranz et al., 2012). Center-pivot manufacturers now offer control panels that can change pivot speed in 1 to 10° increments (Evans et al., 2013). Controlling center-pivot speed allows the operator to change application depth in pie-shaped areas within fields; however, field variability seldom occurs in triangular-shaped parcels. Center-pivot manufacturers also offer variable-rate irrigation systems that can change application rates along the lateral by pulsing individual or groups of sprinklers on and off. Using variable speed and rate enables a field to be divided into several thousand parcels to accurately match the management zones within a field.

Although center-pivot irrigation systems are commercially available to precisely apply water to management zones within a field, user-friendly systems to manage SSIM are not. To fully implement SSIM, sensor systems are needed to measure crop, soil, and weather factors so the plants and soil control the amount and timing of irrigation in each zone in the field. Within-season temporal variation in rainfall, infiltration, and water use require periodic feedback of plant and soil status. Temporal feedback can be used for real-time irrigation management and improved decision support.

Most current irrigation scheduling programs calculate the timing and duration of water applications using algorithms based on historical weather patterns and predicted crop water use over a relatively short period (e.g., 3–14 d). Feedback to estimate crop water use is usually made by spot measurements of soil water or

other data after the irrigation is completed, and adjustments are made for the following irrigation event. Specialized software programs need to be developed for SSIM so that data obtained from multiple sources can be used to determine the amount and timing of irrigation for each zone in a field.

Recent innovations in low-voltage sensors and wireless radio frequency data communications combined with advances in internet technologies offer tremendous opportunities for advancement of SSIM. Spatially distributed, within-field plant and soil sensors in combination with agroweather stations are potentially more accurate for controlling irrigation than historical or static map-based input projections. Sensor systems can be used to measure climatic, soil water, plant density, canopy temperature differences, irrigation application amounts, and other types of variability. Remote sensing by satellites can also provide synoptic crop feedback in both space and time to supplement real-time measurements. Real-time feedback from multiple sources, in combination with modern wireless communication and computerized control systems, are fundamental to the development and implementation of optimal site-specific irrigation management strategies.

Moving irrigation systems provide a unique platform to collect data from sensors in the field in addition to applying irrigation water. O'Shaughnessy and Evett (2010) demonstrated that wireless infrared thermometers functioned reliably when mounted on a center-pivot irrigation system. Peters and Evett (2008) used infrared temperature to automate irrigation with a center pivot. There was no difference in irrigation efficiency or water use efficiency compared with manual irrigation scheduling using a neutron probe to measure soil water content. This system used the temperature–time threshold method (Wanjura et al., 1995) to determine when irrigation was required. The center pivot traveled through the field each day to measure canopy temperature. If a threshold canopy temperature is exceeded for a predetermined threshold time, an irrigation event is scheduled.

Presently, there has been limited adoption of site-specific irrigation systems. One estimate is that there are <200 center-pivot systems with variable-rate technology in the United States (Evans et al., 2013). One reason for limited adoption is that variable-rate irrigation technology has only recently been commercially marketed by center-pivot system manufacturers. Another potential barrier to installing variable-rate irrigation technology is the current limited use of soil or plant sensing to schedule irrigation. The USDA Farm and Ranch Irrigation Survey showed that <10% of irrigated farms used soil or plant sensing or a scheduling service (Table 2). Furthermore, the trend is not increasing for any of these technologies. These results indicate that acceptable technology is currently not available, or the need for more sophisticated scheduling has not been realized by irrigators. In addition to demonstrating the benefits of SSIM, reliable, easy-to-use equipment is needed for large-scale adoption of SSIM. The common use of yield monitors in today's harvesting equipment allows farmers to see the variability in their fields and may increase interest in spatially varying irrigation.

Integrating information from various sensors and systems into a decision support program will be critical to highly managed, spatially varied irrigation (Evans and King, 2012). Advanced decision systems should integrate real-time monitoring with plant growth and pest models to seamlessly interface with the irrigation system to optimally manage crop production. For example, the best response to an identified diseased area in a field may be a pesticide treatment to limit the disease spread or may be eliminating further irrigation so a limited

**Table 2. Percent of farms reporting a method of deciding when to irrigate. Respondents could select more than one method (USDA NASS, 2014b).**

Method	2013	2008	2003	1998	1994	1988
	----- % -----					
Crop Condition	78	78	80	74	68	72
Feel of Soil	39	43	35	41	39	36
Calendar	21	25	19	17	17	15
Scheduled by water delivery organization	16	12	12	10	14	11
Other method	8	9	9	7	9	5
Soil moisture sensing device	10	9	7	8	10	7
Scheduling service	8	8	6	4	5	5
Neighbors	6	7	6	NA	NA	NA
Plant moisture sensing device	2	2	1	NA	NA	NA
Computer simulation model	1	1	1	1	2	0

water supply can be saved for healthy areas of the field. Advanced decision systems also need to consider the whole farm to best use water and other resources among multiple fields, crops, and even years. For example, if groundwater use for irrigation is limited to 400 mm yr<sup>-1</sup> on a 3-yr average, using <400 mm in 1 yr allows an irrigator to use >400 mm in future years.

## Summary

Precision irrigation involves applying the right amount of water at the right time and location. Precision irrigation management is needed on large irrigation projects and on individual fields to make the best use of irrigation water, especially in water-limited areas. On large irrigation projects, managers need to adjust irrigation delivery to match the irrigation needs of the crops in the project. On individual farms and fields, managers need specific information about crop water needs on their fields to apply the right amount of water at the right time and place.

Technology is commercially available to precisely apply water when and where it is needed by crops; however, user-friendly decision tools are still needed to quantify specific irrigation needs and control water application within fields. Researchers and managers need to remember that the technology to precisely apply irrigation water is wasted if the water does not infiltrate where it was applied. Irrigation system design must consider soil properties along with irrigation capacity.

Satellite imagery can be used to calculate actual crop water use in fields, but this information is not available in real-time for daily irrigation management. Combining direct or reference ET measurements from micrometeorological methods with remotely sensed spatial information can provide daily, site-specific ET information within fields. Unmanned aerial vehicles are a developing technology that may make it feasible to collect frequent, high-resolution aerial imagery for managing irrigation. An alternative to satellite-based remote sensing is in-field sensors that provide information to a decision support system to precisely manage field irrigation. Integrating information from various sensors into a decision support program is the next potential advancement to precisely apply the right amount of water at the right time to unique areas within a field.

Water rights and policies can be a barrier to adopting precision irrigation practices by restricting water delivery amounts or timing at the district or field level. However, irrigation managers and designers can partially account for these restrictions through on-farm storage, irrigation system design, or crop choice, allowing the right amount of water to be applied at the right time and place.

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