

# SPATIOTEMPORAL SEMANTICS AND MOVING OBJECTS RESEARCH

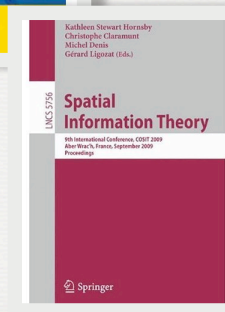
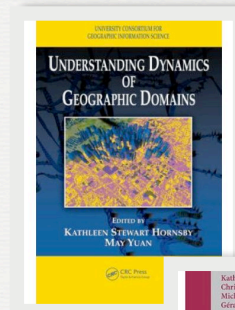
**Kathleen Stewart Hornsby**

Department of Geography, The University of Iowa  
kathleen-stewart@uiowa.edu



# WHO I AM...

- **GIScience faculty** in Department of Geography, The **University of Iowa**
- Interested in **spatiotemporal modeling, moving objects** research, **geospatial semantics, ontologies** for GIS



# THE REAL WORLD...

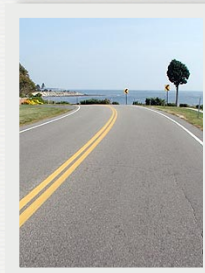
- Interconnected...
- Continuous
- Dynamic



# CONTINUANTS VS OCCURRENTS

- **Continuant** entities endure through some extended interval of time

Houses, roads, cities



# CONTINUANTS VS OCCURRENTS

- **Occurrent** entities happen and then are gone

Traffic jams  
Volcanic eruptions  
Landslides, avalanches



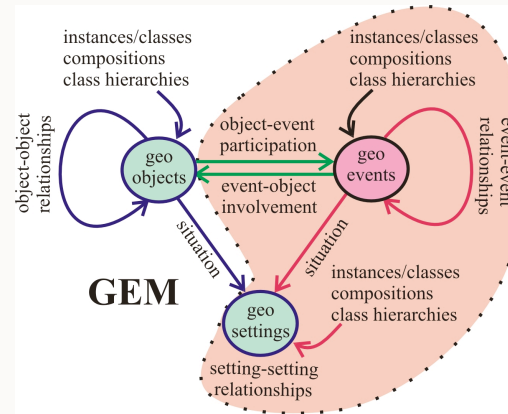
## NOW FOR OUR PURPOSES...

- Continuants *map to* **objects**
- Occurrents *map to* **events**
- **Both** are needed to model fully a dynamic system



# GEOSPATIAL EVENTS MODEL

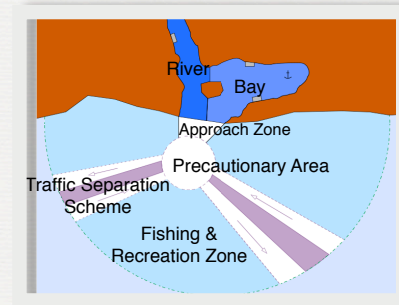
(GEM) WORBOYS AND HORNSBY 2004



# PROTOTYPICAL GEOSPATIAL DOMAIN

WITH STEPHEN COLE

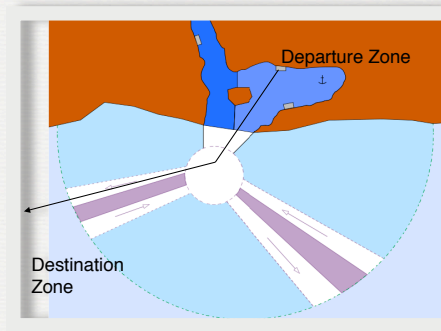
- A geospatial domain (e.g., a harbor) is partitioned into **zones**





# ZONES...

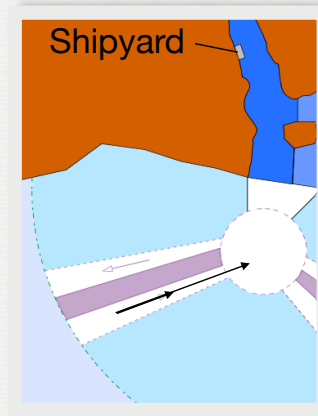
- A **zone** may be a **departure** or **destination zone**.
- If a vessel heads for the sea from the harbor, the **departure zone** is the **ferry landing** and the **destination zone** is the **offshore zone**.



# MOVEMENT AS EVENTS

- The **movement** of an object across a zone boundary is modeled as a ***ChangeZoneEvent***

- *KWY cze precautionary 0230*



## SUCCESSIONS OF MOVEMENTS ARE MODELED AS SEQUENCES

- An **event sequence**,  $E$ , is defined as a set of events  $e$  that capture movements of an object,

$$\left\{ id\ e_{t_1}^{zone}, id\ e_{t_2}^{zone}, \dots, id\ e_{t_n}^{zone} \right\} \text{ where,}$$

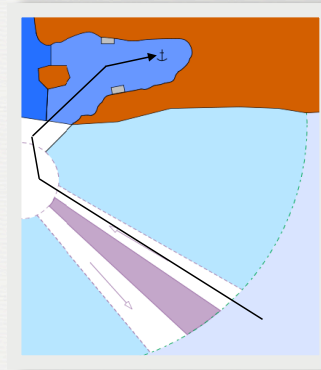
- $id\ e_{t_1}^{zone} < id\ e_{t_2}^{zone} < \dots < id\ e_{t_m}^{zone}$

For any two events, one precedes the other

# TRANSITS

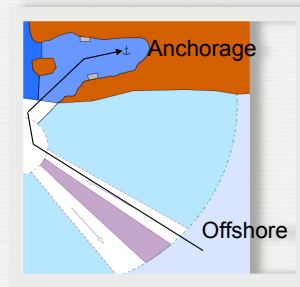
- An event sequence that models an object's movement through a geospatial domain is referred to as a **transit**

$${}_{ID}T = \{e \in E \mid e.id = ID\}$$



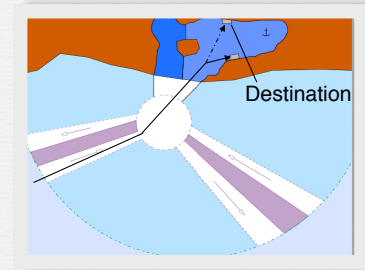
- ${}_{FRY} cze_{i1}^{inbd\_SE\_TSS} < {}_{FRY} cze_{i2}^{precautionary} < {}_{FRY} cze_{i3}^{approach} < {}_{FRY} cze_{i4}^{bay} < {}_{FRY} cze_{i5}^{anchorage}$

# TRANSITS CAPTURE SPECIAL KINDS OF MOVEMENTS



*oldZone:offshore*  
WFG **dep**<sub>t1</sub> *inbd\_SE\_TSS* < WFG *cze*<sub>t2</sub> *precautionary* < WFG *cze*<sub>t3</sub> *approach* <  
WFG *cze*<sub>t4</sub> *bay* < *expectedDest:anchorage* WFG **arr**<sub>t5</sub> *anchorage*

- The transit is not ended with an **arr** event, but with an **ude** event



- $$\begin{array}{l} \text{oldZone: offshore} \\ \text{FRB } \mathbf{dep}_{11} \text{ } \text{inbd\_W\_TSS} < \text{FRB } \mathbf{cze}_{12} \text{ } \text{precautionary} < \text{FRB } \mathbf{cze}_{13} \text{ } \text{approach} \\ \text{FRB } \mathbf{cze}_{14} \text{ } \text{bay} < \text{expectedDest: ferryLanding} \\ \text{FRB } \mathbf{ude}_{15} \text{ } \text{petroleumTerminal} \end{array}$$



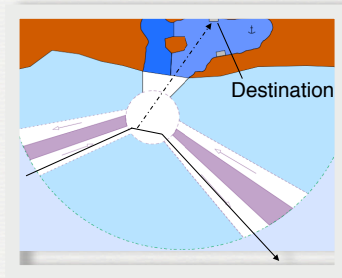
# NOTEWORTHY EVENTS

- This type of event is distinguished by comparing the movements associated with an object with the movements with which that object is **expected to be associated...**
  - E.g., an *UnexpectedZoneEvent uze* where,  
 $cze.zone \neq cze'.expectedNext$
  - And *cze* is the previous *changeZoneEvent*
  - *UnexpectedDestinationEvent ude* where an *arr* is expected at a certain destination zone but instead occurs at a different destination

# ADDITIONAL SEMANTICS

- **Aborted Transit**

A vessel enters the harbor waters and then leaves again without ever reaching its intended destination



*oldZone: offshore*  
FRY1 *dep* *inbd\_W\_TSS* *t1* < *FRY1* *cze* *precautionary* *i2* <  
*expectedNext:approach*  
FRY1 *uze* *outbd\_SE\_TSS* *i3* < *expectedDest: ferryLanding* *ude* *offshore* *i4*

# MIXTURE OF SEMANTICS

- Event sequences, therefore, can represent a **mixture of movement semantics** in a domain, modeling both
- **routine** and
- **noteworthy** (possibly unexpected) movements

# MOVEMENT PATTERNS

- So far we have discussed **individual events** within a transit in order to model the semantics associated with particular movements of objects

In addition, the **pattern of movements** themselves can also be meaningful

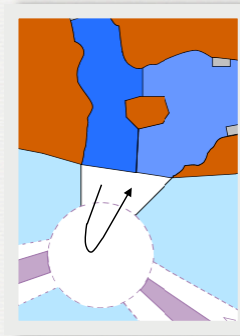
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# COLLOCATING PATTERN

- An unexpected reversal of a moving object reflected by events in the same zone

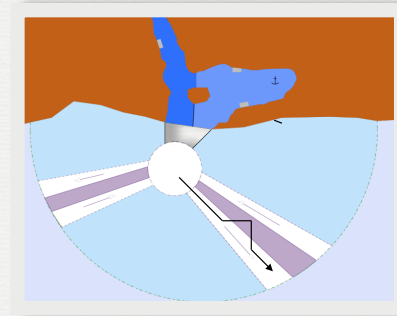
$G([e_1, e_2])$  where  $(id_1 = id_2), (name_1 \neq name_2), (zone_1 = zone_2)$

$G\left(\left[ \begin{array}{c} RTN \\ Cze_{10:15}^{approach} \end{array}, \begin{array}{c} expectedNext.outbnd\_SW\_TSS \\ RTN \\ Uze_{10:55}^{approach} \end{array} \right] \right)$



# REPEATING PATTERN

- The same event is experienced twice in the same zone

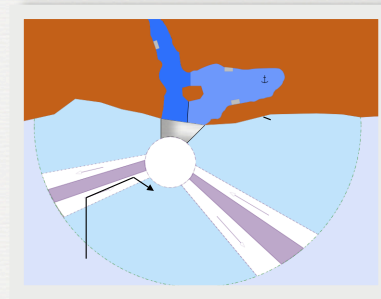


... < L21 *Cze* <sup>out\_SE\_TSS</sup><sub>20:30</sub> < *expectedNext:offshore* L21 *uze* <sup>sep\_SE\_TSS</sup><sub>20:45</sub> <  
L21 *Cze* <sup>out\_SE\_TSS</sup><sub>21:00</sub> < ...



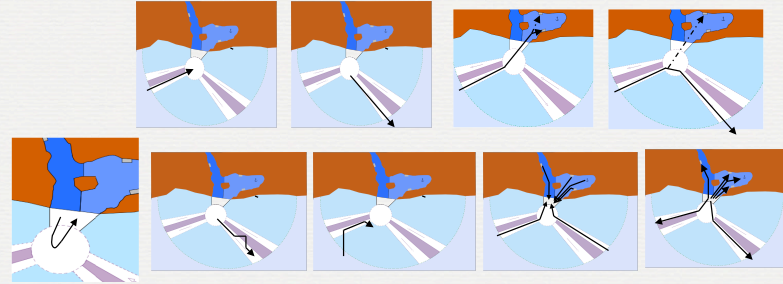
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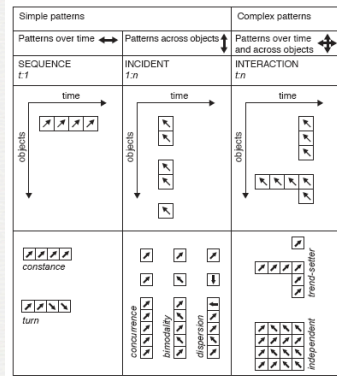


... < *expectedNext:inbd\_W\_TSS*  
H13 *uze* *S\_F&R* 09:14 < H13 *cze* *inbd\_W\_TSS* 09:32 <  
*expectedNext:precautionary*  
H13 *uze* *S\_F&R* 09:48 < ...

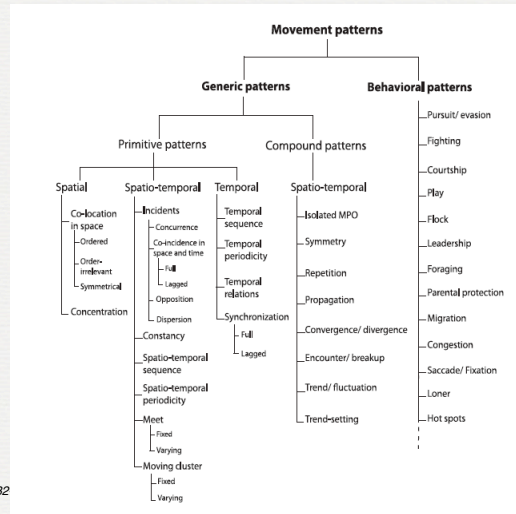
# CLASSIFICATION OF MOVEMENTS



# RELATIVE MOTION PATTERNS



Laube, P., and Imfeld, S. (2002) *Proceedings of GIScience 2002*, 132



Dodge, S., Weibel, R., and Lautenschütz, A-K. (2008) *Towards a taxonomy of movement patterns*, *Information Visualization*, 7, 240-252

## WHAT'S NEXT?

- So far we have been modeling total orders of events
- focus on *before* and *after* relation
- Creates temporal and spatial patterns of event common for simulations

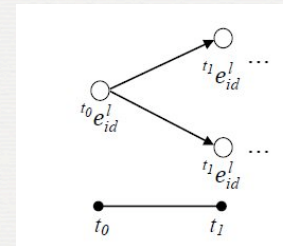
# BRANCHING EVENTS MODEL

*WITH SHANE HUBBARD*

- Extend this research to capture **multiple possibilities**
- For example, what might happen in the **future** or what might have happened in the **past**
- Useful for emergency response, public safety, spatial decision support

# BRANCHING: DIVERGENCE

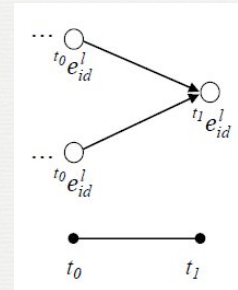
- **Divergence**
- A key element of branching
- **After an initial event, two more are possible**
- recursive





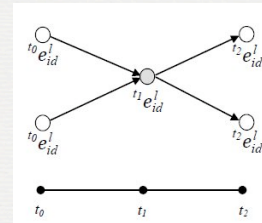
# BRANCHING:CONVERGENCE

- **Convergence**
- Where **prior to an event**, two or more events are possible



# COMBINING ALL ELEMENTS

- Both converging and diverging can be combined



# SUMMARY

- Have been considering **spatiotemporal semantics** associated with moving objects
- Different kinds of **events**
  - routine, noteworthy, unexpected...
- Different classes of **paths** of **moving objects**
- Extend underlying temporal model to support **branching events**
-

# QUESTIONS?

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