

Optimisation technique for improving wind downscaling results by estimating roughness parameters

Gustavo Montero^a, Eduardo Rodríguez^a, Albert Oliver^a, Javier Calvo^b,
José M. Escobar^a, Rafael Montenegro^a

^aUniversity Institute for Intelligent Systems and Numerical Applications in Engineering, SIANI, University of Las Palmas de Gran Canaria, ULPGC, Campus Universitario de Tafira, 35017, Las Palmas de Gran Canaria, Spain

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^bAgencia Estatal de Meteorología, AEMET, Leonardo Prieto Castro, 8, 28040 Madrid, Spain

Abstract

The characterisation of the aerodynamic roughness length (z_0) and the displacement height (d) is critical when modelling the wind field using the log vertical profile. It is known that the values of these parameters depend on land coverage and weather conditions. Thus, many authors have studied their relationship, providing typical values for each land cover. In this paper, we have performed a comprehensive literature review to collect the intervals of z_0 and d values for each land coverage. Using these intervals, we estimate their values using an optimisation technique that improves the results of a downscaling wind model. The downscaling model is a 3D adaptive, mass-consistent finite element model (Wind3D) that takes values from the HARMONIE-AROME or ECMWF mesoscale numerical weather prediction models. The optimisation is carried out by a memetic algorithm that combines the Differential Evolution method, a rebirth operator and the L-BFGS-B algorithm. The fitness function to be minimised is the root mean square error (RMSE) against observed wind data. This fast procedure allows updating the aerodynamic parameters for any weather condition. Numerical experiments have been carried out to show the performance of the methodology.

Keywords: ALADIN-HIRLAM HARMONIE-AROME Model,

Email addresses: gustavo.montero@ulpgc.es (Gustavo Montero),
eduardo.rodriguez@ulpgc.es (Eduardo Rodríguez), albert.oliver@ulpgc.es
(Albert Oliver), fcalvos@aemet.es (Javier Calvo), josem.escobar@ulpgc.es
(José M. Escobar), rafael.montenegro@ulpgc.es (Rafael Montenegro)

1. Introduction

The influence of aerodynamic parameters in the modelling of wind field in the microscale and mesoscale, specially the wind velocity near the ground, is well known [1, 2, 3]. Therefore, the accuracy of these parameters is critical to simulate the wind field used in wind power plants energy prediction, dispersion of air pollution, and wildland fire spread among others. In this paper we propose a strategy to improve the results of a downscaling wind model by estimating the values of the roughness length (z_0) and displacement height (d) using Differential Evolution (DE) and a rebirth operator (RO).

A downscaling wind model uses the prediction of a Numerical Weather Prediction (NWP) model as input wind field to compute a new one in a higher resolution mesh that better captures the terrain features. In this paper, the downscaling wind model is Wind3D [4, 5, 6, 7], a diagnostic mass-consistent wind model, coupled with two different NWP models; specifically the European Centre for Medium-Range Weather Forecasts (ECMWF) model [8] and the HARMONIE-AROME model [9].

Diagnostic models apply conservation of mass, momentum, and energy singularly or fully, considering the terrain effects on an initial flow field. Although these models are used to obtain wind fields at a given time, the results usually represent winds of a time-averaged period. They are limited in comparison with prognostic models because they don't take into account the transient and thermal effects so they cannot simulate the evolution of the boundary layer; however, the computational requirements of the former are much lower than the latter. Diagnostic models can be classified into three different categories according to the conservation laws applied. The first category comprises the diagnostic models that are based only on the conservation of mass; see, e.g., [10, 5, 11]. Mass-consistent models have been applied to the dynamical-downscaling of NWP models for local and regional scale wind forecasting, e.g., the WindNinja model [12]. The second category considers a linearised momentum equation [13, 14]; its computational cost is comparable to mass-consistent models with similar re-

sults [15, 16]. Nevertheless, mass-consistent models are better suited for some atmospheric dispersion problems where a fast response is required [17]. The third type of diagnostic model applies conservation of both mass and momentum to some form of turbulence closure [18, 19, 20, 21], and even conservation of energy [22]. The RANS RNG $k - \varepsilon$ turbulence model has handled non-linear flow effects better than mass-consistent models [21] but it is computationally more expensive. The diagnostic model used in this paper is a new version of Wind3D, with an updated atmospheric parameterisation and wind profile proposed in [23, 24, 25]. Under this new profile, both z_0 and d determine the effect of the terrain on the near-surface airflow [26], therefore it is important to have land use data available. In the last twenty-five years several projects on land cover mapping have been developed mainly using satellite images. In this paper we have used the land cover database of Spain (SIOSE) [27].

For each land cover, the actual values of z_0 and d can be computed using, as a rule of thumb, a ratio of the height of the surface morphology characteristics (h). For instance, for a crop or forest canopy, Brutsaert [28] proposes a value of d between $0.67 h$ and $0.75 h$, and a value of z_0 about $0.12 h$. However, this approach does not hold for non-homogeneous surfaces and a more detailed analysis is required [29]. Different authors have carried out this analysis resulting in diverse values of z_0 and d for the same land cover. For this reason, we have performed a literature review to construct a table with all the ranges for each land coverage in the SIOSE database.

In addition, the values of z_0 and d can be affected by land coverage variations, wind speed and direction, and atmospheric stability [30]. So, the values of z_0 and d have to be known for each weather condition and a general value for each land coverage is not enough to predict the wind field reliably.

To this end, we propose an optimisation algorithm to estimate the values of the aerodynamic parameters for a downscaling wind model. This strategy has been applied to a particular region (Canary Islands) using the SIOSE land cover database and the Wind3D downscaling wind model. We want to remark that the values of z_0 and d obtained in the numerical experiments are not representative values for a given land cover; they only represent the optimal solution compared to the available wind measurements for the land covers in

the domain of interest. However, the general methodology can be applied to any combination of regions, databases, and downscaling wind models. So, the final aim of the proposed strategy is to improve the results of a downscaling wind model by estimating the optimum aerodynamic parameters values.

The content of the paper is organised following the steps of DE. This algorithm generates a random population from the ranges of z_0 and d for a given point. So, as a first step, we need to know the different land covers of our region that, in this case, are given by the SIOSE database described in Sect. 2. Then, we identify the possible range of values for z_0 and d for each land cover; these ranges are given in the literature review performed in Sect. 3. For a given region there exists a combination of different land covers, so we need to compute the actual value of each aerodynamic parameter by using the formula presented in Sect. 4. Then, with these values and the forecast wind field of the NWP models described in Sect. 5 we simulate the resulting wind field with the Wind3D model (Sect. 6). The last step of the algorithm is to compute the fitting function (the root square mean error between the predicted and the observed wind in meteorological stations) and generate the next population of the optimisation algorithm (Sect. 7). Numerical experiments in a test problem and a realistic case in Gran Canaria Island are described in Sect. 8 and the results are discussed in Sect. 9. Finally, the conclusions of this work are summed up in Sect. 10.

2. SIOSE land cover database

In 1990, the first land cover database encompassing the whole national territory was constructed in Spain on a scale of 1 : 100.000. It was developed in the framework of the CORINE Land Cover (CLC) European project [31]. After successive updates in 2000, 2006 and 2012, it became Image & CORINE Land Cover. In short, it consists of an inventory of land cover in 44 classes. The project SIOSE (Spanish acronym for Information System of Land Cover of Spain) was created in 2005 to integrate the local information available from the Autonomous Communities and the General State Administration. Since the requirements at the Spanish national level were higher than those supplied by the European project, the SIOSE generated a new land cover database for all the country on a 1 : 25.000 scale. It was based on reference images from

2005, with a MUM of 0.5 to 2 ha (SIOSE 2005) and a planimetric accuracy of 5 m or better. The project was updated in 2009 and 2011; see National Technique Team SIOSE [27]. Other important differences with the CLC are the land classification and the hierarchy levels, which are much more simplified in the CLC than in the SIOSE.

The SIOSE database consists of different basic and compound coverages. A compound coverage is made up of a combination of basic or compound coverages. Specifically, it considers eight general groups of basic coverages (Crops, Grassland, Forest, Scrubs, No Vegetation, Artificial Coverage, Wet Coverage and Water Coverage) that are further refined into forty specific classes of basic land coverage; see. e.g., [32].

3. Roughness length and displacement height: literature review

To obtain the appropriate values of z_0 and d , the search space of each one must be defined. In this section, we present a methodology to generate a table with the ranges of z_0 and d values for each land coverage. Particularly, it is applied to Gran Canaria Island, but it is suitable to any other location.

To find the ranges of possible z_0 and d values for each land cover, we have carried out a literature review. Table 1 summarises it, and the specific references are listed in the caption. The first and second columns show the SIOSE code and a description for each of the distinct land coverages. The third and fourth, and the fifth and sixth columns present the nominal value and the range of the parameter z_0 and d , respectively. When data are not available, we have used the rule of thumb to obtain the z_0 and d values from the canopy height h ; see Brutsaert [28]. Also, it is worth remarking that d is assumed to be zero for all the water surfaces (ACU, AEM, AES, ALC, ALG, AMO and LAA classes). The z_0 intervals for these water bodies verify the Charnock's formula for typical wind values, i.e., any estimation of z_0 with Charnock's formula will be within the proposed ranges. In the case of hurricane force winds, the z_0 maximum range may be increased if necessary. In such case, the Charnock approach does not apply and the resistance law appears to be more accurate; see, e.g., [33].

We have searched in the literature the minimum and the maximum values of each parameter and canopy. In addition, the values most used by different

Table 1: Nominal values and ranges of z_0 and d for the land cover classes provided by SIOSE. The superindex indicates the source.

Code	Land Cover	z_0 (m)	$z_{0min}-z_{0max}$	d (m)	$d_{min}-d_{max}$
ACM	Sea Cliffs	0.05 ^[35]	0.05 ^[34] –0.19 ^[34]	57 ^[34]	3.3 ^[34] –85 ^[34]
ACU	Water Courses	0.00025 ^[37]	0.0001 ^[38] –0.01 ^[31]	0 ^[28, 39]	–
AEM	Water body. Reservoirs	0.00025 ^[38]	0.0001 ^[38] –0.005 ^[40]	0 ^[28, 39]	–
AES	Estuaries	0.0002 ^[41]	0.0001 ^[38] –0.01 ^[31]	0 ^[28, 39]	–
ALC	Coastal Lagoons	0.005 ^[40]	0.0001 ^[38] –0.01 ^[31]	0 ^[28, 39]	–
ALG	Water body. Lakes and Lagoons	0.0005 ^[42]	0.0001 ^[38] –0.005 ^[40]	0 ^[28, 39]	–
AMO	Seas and Oceans	0.0002 ^[41]	0.0001 ^[38] –0.03 ^[35]	0 ^[28, 39]	–
ARR	Rocky Outcrops and Rocks	0.005 ^[31]	0.0003 ^[43] –0.18 ^[44]	0.03 ^[28]	0 ^[28] –0.96 ^[28]
CCH	Screes	0.1 ^[35]	0.05 ^[45] –0.15 ^[46]	0.6 ^[47]	0.56 ^[47] –0.66 ^[47]
CLC	Quaternary lava flow	0.0286 ^[48]	0.0013 ^[48] –0.0735 ^[48]	0.15 ^[28]	0 ^[28] –0.4 ^[28]
CNF	Forest. Conifers	1.28 ^[49]	0.25 ^[50] –1.93 ^[51]	13.1 ^[52, 53]	4.87 ^[51] –22 ^[47]
CHA	Herbaceous crops. Rice	0.072 ^[54]	0.001 ^[55] –0.11 ^[54]	0.85 ^[54]	0.1 ^[54] –1.55 ^[54]
CHL	Herbaceous crops. Different from Rice	0.1 ^[56]	0.004 ^[57] –0.74 ^[58]	0.25 ^[57]	0.1 ^[57] –3 ^[59]
EDF	Artificial Coverage. Buildings	1.5 ^[60]	0.7 ^[60] –3.7 ^[58]	14 ^[60]	7 ^[60] –19.73 ^[28]
FDC	Forest. Leafy. Deciduous	1 ^[61]	0.18 ^[61] –1.4 ^[35]	11.8 ^[62]	3 ^[62] –21.6 ^[62]
FDP	Forest. Leafy. Evergreen	0.72 ^[44]	0.6 ^[37] –2.65 ^[63]	9.7 ^[62]	3 ^[62] –31 ^[60]

Table 1: *Continued*

Code	Land Cover	z_0 (m)	$z_{0min}-z_{0max}$	d (m)	$d_{min}-d_{max}$
GNP	No Vegetation. Glaciers and Perpetual Snow	0.001 ^[31]	0.00001 ^[64] –0.012 ^[60]	0.01 ^[28]	0 ^[28] –0.06 ^[28]
HMA	Salt Marshes	0.11 ^[44]	0.0002 ^[43] –0.17 ^[43]	0.6 ^[28]	0 ^[28] –0.93 ^[28]
HPA	Wetlands	0.1 ^[31]	0.005 ^[61] –0.55 ^[44]	0.55 ^[28]	0.03 ^[28] –3 ^[28]
HSA	Continental Salt Mines	0.01 ^[31]	0.0005 ^[31] –0.04 ^[40]	0.05 ^[28]	0 ^[28] –0.22 ^[28]
HSM	Salt Lakes	0.01 ^[31]	0.0005 ^[31] –0.04 ^[40]	0.05 ^[28]	0 ^[28] –0.22 ^[28]
HTU	Peat bogs	0.03 ^[31]	0.0005 ^[31] –0.03 ^[31]	0.16 ^[28]	0 ^[28] –0.16 ^[28]
LAA	Artificial Coverage. Artificial water body	0.0001 ^[31]	0.0001 ^[31] –0.005 ^[40]	0 ^[31, 39]	–
LFC	Woody Crops. Citrus Fruit Trees	0.31 ^[65]	0.03 ^[38] –0.4 ^[66]	3 ^[47]	0 ^[59] –4 ^[59]
LFN	Woody Crops. No Citrus Fruit Trees	0.25 ^[31]	0.03 ^[38] –1 ^[67]	0.92 ^[68]	0 ^[59] –4 ^[59]
LOC	Other Woody Crops	0.0615 ^[28, 36]	0.0369 ^[28, 36] –0.0861 ^[28, 36]	0.33 ^[28, 36]	0.2 ^[28, 36] –0.47 ^[28, 36]
LOL	Olive Groves	0.48 ^[69]	0.25 ^[31] –0.61 ^[69]	2.67 ^[69]	2 ^[69] –3 ^[69]
LVI	Vineyards	0.2 ^[70]	0.08 ^[71] –0.55 ^[70]	0.75 ^[70]	0.31 ^[71] –1.4 ^[72]
MTR	Scrubs	0.16 ^[61]	0.016 ^[61] –1 ^[35]	4.8 ^[73]	0.9 ^[60] –7.1 ^[73]
OCT	Artificial Coverage. Other Buildings	0.5 ^[31]	0.06 ^[44] –1 ^[31]	4 ^[74]	2 ^[74] –14 ^[60]
PDA	No Vegetation. Beaches, Dunes and Sandy Areas	0.0003 ^[31]	0.0003 ^[31] –0.06 ^[43]	0 ^[28]	0 ^[28] –0.33 ^[28]
PRD	Crops. Meadows	0.03 ^[31]	0.001 ^[64] –0.1 ^[31]	0.013 ^[60]	0.007 ^[59] –0.035 ^[60]

Table 1: *Continued*

Code	Land Cover	z_0 (m)	$z_{0min}-z_{0max}$	d (m)	$d_{min}-d_{max}$
PST	Grasslands	0.09 ^[64]	0.001 ^[64] –0.15 ^[64]	0.171 ^[75]	0.013 ^[60] –0.66 ^[59]
RMB	No Vegetation. Ravines	0.0012 ^[76]	0.0003 ^[38] –0.005 ^[77]	0.03 ^[28, 41]	0 ^[28] –0.03 ^[28]
SDN	No Vegetation. Bare Soil	0.001 ^[43]	0.0002 ^[77] –0.04 ^[44]	0.03 ^[28, 41]	0 ^[28] –0.22 ^[28]
SNE	Artificial Coverage. Unbuilt Land	0.0003 ^[43]	0.0002 ^[77] –0.04 ^[35]	0 ^[28]	0 ^[28] –0.22 ^[28]
VAP	Artificial Coverage. Road, Parking or Unvegetated Pedestrian Areas	0.03 ^[31]	0.0035 ^[76] –0.5 ^[31]	1 ^[39, 78]	0.02 ^[78] –2.5 ^[78]
ZAU	Artificial Coverage. Artificial Green Area and Urban Trees	0.4 ^[38]	0.03 ^[43] –1.3 ^[58]	3.5 ^[39, 78]	3.5 ^[60] –14 ^[60]
ZEV	Artificial Coverage. Extraction or Waste Areas	0.1 ^[31]	0.0003 ^[43] –0.18 ^[44]	0.16 ^[28, 77]	0 ^[28] –1 ^[28]
ZQM	No Vegetation. Burnt Areas	0.6 ^[31]	0.1 ^[31] –1.1 ^[43]	3.27 ^[28]	0.54 ^[28] –6 ^[28]

∞

authors have been selected as nominal values, but these are not used in our approach. In fact, we used the ranges of Table 1 as searching space for the solution of each parameter in the characteristic wind situations shown in Table 3. Then, we performed an extended literature review on the assigned values to the roughness parameters of each coverage. For this reason, in general, we think that the proposed ranges completely cover the variation interval of z_0 and d corresponding to each coverage, respectively, not only for the region studied in this paper, but also for any region if the specific coverage is included in that literature review. Nevertheless, some ranges have been defined according to the local characteristics of certain coverages. This is the case of the high sea cliffs in Gran Canaria, for example, where the range of z_0 and d have been adapted to such heights. For instance, the works of Roballo and Fisch [34] and Fry et al. [35] have been employed to characterise *Sea Cliffs*. The former study proposes a value of $d = 3.3$ m for a cliff of 40 m. Using this same ratio, the values for the Andén Verde (690 m) and the Risco de Faneque (1027 m) cliffs are 57 m and 85 m, respectively. These values have been taken as lower bound (3.3 m), nominal value (57 m) and upper bound (85 m). Another case is *Other Woody Crops* related to Aloe Vera plantations on the island. In this case, Molero-Paredes and Matos [36] studied the typical canopy height ranges for the Aloe Vera. Using these ranges and the rule of thumb, we have obtained the z_0 and d ranges and nominal values. So, in general, these are the only particular cases to review for the application of ranges given in Table 1 to any other region.

The bibliography of Table 1 may be classified according to the procedure used to obtain z_0 and d . Several authors proposed parameterisations of the roughness parameters from measures of the wind and other physical magnitudes. This is the case of [28] which is used here in many coverages; [38] in water surfaces; [45] in screens; [47] in screens, conifers, and citrus fruit trees; [52, 53] in conifers; [55] in rice crops; [74] in low buildings; [69] in olive groves; [71] in vineyards; [39] in water surfaces; and [78] in artificial coverages. Some other works are based on the canopy morphology, such as [40] used in water and saline coverages; [61] in deciduous forests, wetlands and scrubs; and [36] in Aloe Vera crops.

Another extended approach is the use of measurements and wind profile: [34] used in cliffs; [46] in screens; [48] in Quaternary lava flow; [49, 50, 51] in

conifers; [54] in rice crops; [57] in crops different from rice; [68] in no citrus fruit trees; [70, 72] in vineyards; [73] in scrubs; and [77] in soils without vegetation and artificial coverages.

Also in Table 1, there are some values of z_0 and d arising from applications of specific numerical models with their land cover databases. For example, [42] used them in lakes and lagoons; [44] in rocky outcrops and rocks, evergreen forests, salt marshes, wetlands, bare soils, and artificial coverages; [63] in evergreen forests; [67] used in no citrus fruit trees; [75] in grasslands; and [76] in ravine and road, parking or unvegetated pedestrian areas.

Some papers dealing with collections of data, specially from old publications, were useful too. In particular, the one by [41] used in estuaries, seas and oceans, and soils without vegetation; [58] in crops different from rice and artificial coverage; [60] in buildings, evergreen forests, glaciers and perpetual snow, scrubs, meadows, grasslands and artificial green area and urban trees; [62] in deciduous and evergreen forests; and [59] in crops different from rice, woody crops, meadows and grasslands. Also some early publications were used for constructing Table 1, such as [56], used in crops different from rice; [64] in glaciers and perpetual snow, meadows and grasslands; and [65, 66] in citrus fruit trees.

Finally, some of the current land cover databases based on remote sensing surveys (specifically, aircraft lidar and satellite images) that were taken into account are [35]: the NLCD database used in cliffs; [37]: the 1-km land cover data set DISCOVER (IGBP-DIS) for water courses; [31]: the CLC database applied in many coverages; and [43]: the LGN3 database used in rocky outcrops and rocks, salt marshes, soils without vegetation, and artificial coverages.

4. Roughness length and displacement height characterisation

The SIOSE project uses a vectorial format, but, for convenience, we will translate it to a raster format. For this, we will define a grid with n_p points and, for each point, we will look for the mean value of basic coverages. Once we have the values of z_0 and d for each basic coverage, we can compute the specific z_0 and d values at any point using an appropriate weighted mean.

This way, the SIOSE database will let us create a matrix with the percentage of the basic coverages at any point. This matrix is defined as follows: let M

be an $n_p \times n_b$ matrix, with components $m_{i,j}$, where n_b is the number of basic coverages. For each row i of M , $m_{i,j}$ is the fraction of the basic coverage j at the point n_i ($m_{i,j} < 1$ and $\sum_{j=1}^{n_b} m_{i,j} = 1$).

When the ranges of z_0 and d are set for each basic land coverage, we can compute its values at any point of the terrain. Assuming that the values of z_0 and d are a certain mean of the values of the basic coverages z_{0j} and d_j , $j = 1, \dots, n_b$, we can compute their values at any point. A simple weighted average may produce differences with the effective roughness of one order of magnitude. In this case, only the formula proposed by [79] was applied; in this approach, for a coverage i composed by n_b basic canopies with roughness length z_{0j} ; $j = 1, \dots, n_b$ on a fraction m_{ij} of the area, respectively, an approximation to the effective roughness length is given by computing the weighted geometric mean roughness length z_0 :

$$z_0 = \prod_{j=1}^{n_b} z_{0j}^{m_{ij}}. \quad (1)$$

The study by [80] for the effective roughness length improves the formula proposed by [79], taking into account a non-dimensional patchiness parameter to consider the textural information about the spatial dependence of the primitives (regions with specific properties) characterising the surface inhomogeneity. However, the coverage information provided by the land cover databases (e.g., SIOSE) does not include the spatial distribution of basic coverages in a composed one, but only the fraction of the area covered by each surface type.

Regarding the displacement height, d , [80] and [79] did not study its estimation. In any case, equation (1) is not appropriate for d , since, in the case of a basic coverage with displacement height equal to zero, it would produce a mean $d = 0$ independently of the d_j values of the other basic coverages. Some other works have studied the variation of d in several specific coverages, e.g., in urban [81] and vegetation [82, 83] canopies. One important conclusion is that the effective displacement height of a heterogeneous coverage can exceed the surface mean canopy height significantly. Taking this into account, we propose to use a weighted root mean square to obtain a higher mean value than Taylor's one:

$$d = \sqrt{\sum_{j=1}^{n_b} m_{ij} d_j^2}, \quad (2)$$

where d_j and m_{ij} are the displacement height and the fraction of the basic coverage j in the composed one i , respectively. Figures 1(a) and (b) show the resulting composed z_0 and d values in Gran Canaria Island, considering the nominal values of the basic coverages given in Table 1.

It can be noted that the application of this methodology to another database is straightforward.

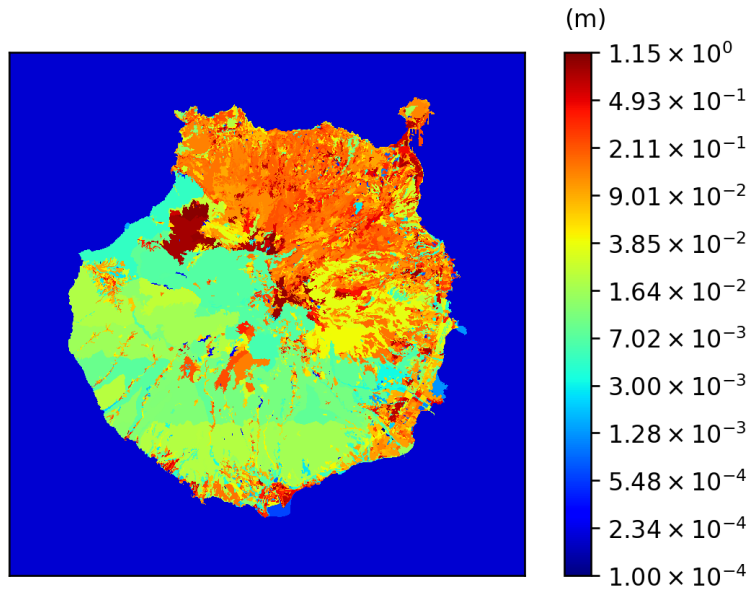
5. Mesoscale numerical weather prediction model

The wind field model used in this work is a diagnostic model (Wind3D). To provide the model with predictive capacity, we downscaled the results from a mesoscale numerical weather prediction model. Specifically, the mesoscale models considered in this paper are the ECMWF and the HARMONIE-AROME models, as proposed in Oliver et al. [7].

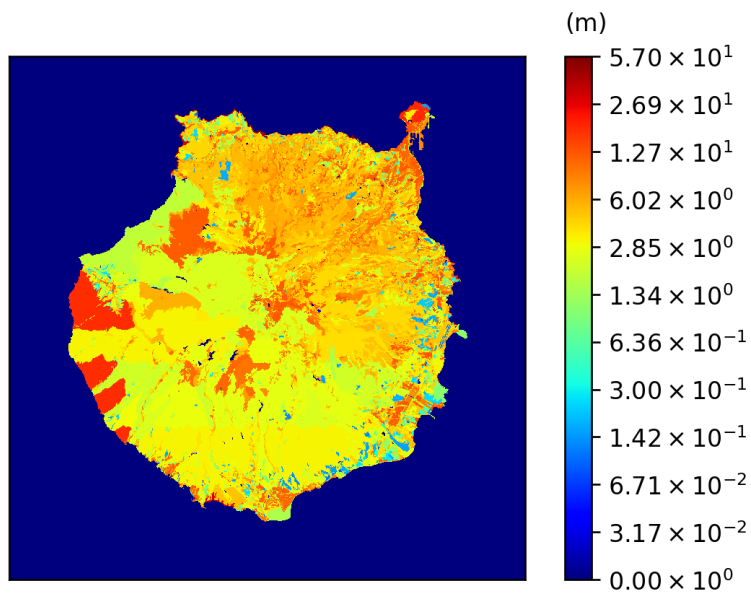
The Integrated Forecasting System (IFS) is the global atmospheric model operational at ECMWF (<http://www.ecmwf.int>). The dynamical core is spectral, semi-implicit, 2 time-level and semi-Lagrangian. The version used in this work corresponds to the high resolution deterministic version of the model based on cy41r1 having a T1279 spectral truncation which corresponds approximately to 16 km horizontal resolution. Non-linear processes, physical parameterisations, water species and tracers are treated in grid point space. In the vertical it uses a finite element discretisation with 137 levels including 20 levels below 1000 m and model top at 1 hPa.

The HARMONIE-AROME non-hydrostatic convection permitting model is a particular configuration of the ALADIN-HIRLAM shared system resulting from the collaboration between ALADIN and HIRLAM Consortia. This configuration described in [84] is based on the AROME-France model [85].

The State Meteorological Agency of Spain (AEMET) is running HARMONIE-AROME (or just HARMONIE) at 2.5 km horizontal grid spacing over two domains (Iberian Peninsula-Balearic Islands and the Canary Islands). The vertical discretisation includes 65 levels with 15 levels below 1000 m and the model top at 10 hPa. The model updates the atmospheric and surfaces variables every 3 hours using a cutoff time of 1 hour and 10 minutes for the observations. For the boundary conditions, the model is relaxed to the forecasts provided by the



(a) Roughness length (z_0) map



(b) Displacement height (d) map

Figure 1: Roughness length and displacement height maps of Gran Canaria island (m) corresponding to the nominal values stated in Table 1 and using the mean values given in equations (1) and (2), respectively.

ECMWF-IFS integrations corresponding to a cycle 6 hours earlier than the Limited Area Model cycle. The HARMONIE 2.5 km model significantly improves local and extreme forecasts of coarser grid models like HIRLAM or ECMWF [86].

6. Diagnostic wind model

We consider a mass-consistent model [10, 5, 6, 87] to compute a wind field u in a domain Ω with a boundary $\Gamma = \Gamma_a \cup \Gamma_b$, which satisfies the mass continuity equation in Ω , for an incompressible flow, and the impermeability condition on the terrain Γ_a :

$$\nabla \cdot u = 0 \quad \text{in } \Omega, \quad (3a)$$

$$n \cdot u = 0 \quad \text{on } \Gamma_a, \quad (3b)$$

where n is the outward-pointing normal unit vector and Γ_b the free boundary. The model formulates a least-squares problem in the domain Ω to find a wind field $u = (u_x, u_y, u_z)$, such that it is adjusted as much as possible to an interpolated wind field $u_0 = (u_{0x}, u_{0y}, u_{0z})$. The adjusting functional for a field $v = (v_x, v_y, v_z)$ is defined as:

$$e(v) = \frac{1}{2} \int_{\Omega} (v - u_0)^T P (v - u_0) d\Omega, \quad (4)$$

where $(v - u_0)^T$ is the transpose of $(v - u_0)$, P is the 3×3 diagonal transmissivity matrix with $P_{1,1} = P_{2,2} = 2\alpha_1^2$ and $P_{3,3} = 2\alpha_2^2$, being α_1 and α_2 the Gauss Precision moduli. The Lagrange multiplier technique is used to minimise the functional (4), with the restrictions (3). Considering the Lagrange multiplier λ , the Lagrangian is defined as:

$$L(v, \lambda) = e(v) + \int_{\Omega} \lambda \nabla \cdot v d\Omega, \quad (5)$$

and the solution u is obtained by finding the saddle point (u, ψ) of the Lagrangian (5). This resulting wind field satisfies the Euler-Lagrange equation:

$$u = u_0 + P^{-1} \nabla \psi, \quad (6)$$

where ψ is the Lagrange multiplier. Since α_1 and α_2 are constant in Ω and substituting (6) in (3), the variational formulation is the following elliptic problem

in ψ :

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \alpha \frac{\partial^2 \psi}{\partial z^2} = -2\alpha_1^2 \left(\frac{\partial u_{0x}}{\partial x} + \frac{\partial u_{0y}}{\partial y} + \frac{\partial u_{0z}}{\partial z} \right) \quad \text{in } \Omega, \quad (7a)$$

$$-n \cdot P^{-1} \nabla \psi = n \cdot u_0 \quad \text{on } \Gamma_a, \quad (7b)$$

$$\psi = 0 \quad \text{on } \Gamma_b, \quad (7c)$$

where $\alpha = \alpha_1/\alpha_2$ is the ratio of the Gauss Precision Moduli. To solve it, we will use the finite element method.

6.1. Construction of the interpolated wind field

The interpolated wind field is computed in the whole domain Ω from point-wise wind data. The wind data can come from measurement stations or a numerical weather prediction system. In this work, we will use the HARMONIE-AROME forecast wind field, as proposed by Oliver et al. [7]. Using these data, we construct the interpolated wind field, u_0 in two steps: first, a horizontal interpolation and, then, a vertical extrapolation.

6.1.1. Horizontal interpolation

At this stage, we want to interpolate the available wind data at any point located at a height z_m over $z_t + d$, where z_t is the terrain surface height. If we have a set of dispersed data, a simple technique for this interpolation is formulated as a weighted sum of the inverse-square law and the height difference interpolation [5]:

$$u_0(z_m) = \xi \frac{\sum_{i=1}^{n_h} \frac{u_i^h}{\delta_i^2}}{\sum_{i=1}^{n_h} \frac{1}{\delta_i^2}} + (1 - \xi) \frac{\sum_{i=1}^{n_h} \frac{u_i^h}{|\Delta h_i|}}{\sum_{i=1}^{n_h} \frac{1}{|\Delta h_i|}}, \quad (8)$$

where the value of u_i^h is the wind velocity at the point i ; n_h is the number of available points; δ_i is the horizontal distance between point i and the point of interest; $|\Delta h_i|$ is their height difference, and ξ is a weighting parameter ($0 \leq \xi \leq 1$) that determines to what degree the focus is put on the inverse-square law or the height difference interpolation.

When a grid of wind data is available, e.g., HARMONIE-AROME or ECMWF wind results, it is preferable to interpolate the wind field with a simple bilinear Lagrange interpolation in the cell containing the studied point.

6.1.2. Vertical extrapolation

Further than the Monin-Obukhov similarity theory, the concepts of Neutral and Stable Boundary Layers (SBL) have been revised to consider the effect of the free-flow static stability and baroclinicity on the turbulent transport of momentum and scalars in the boundary layer, as well as the model of turbulent entrainment for Convective Boundary Layers (CBL) [25]. Accordingly, different types of SBL regimes can be distinguished: truly neutral (absence of any buoyancy effects throughout the PBL); conditionally neutral (buoyancy flux at the surface is negligible); short-lived nocturnal (separated from the free atmosphere by near-neutral residual layers); and long-lived (immediately adjoining the stably stratified free atmosphere). The SBL height, h , may be evaluated according to the expression recently introduced by [88]. This expression represents a multi-limit equation for the equilibrium PBL height that covers the types mentioned earlier of neutral and stable conditions in the atmosphere. In contrast to the stable and neutral cases, the estimation of the CBL height is not straightforward, since our model is diagnostic and the recommended parameterisations are prognostic. To overcome this problem, some prognostic data must be used. In this approach, the CBL height is obtained from the results of the mesoscale model, e.g., HARMONIE-AROME model.

The estimation of the PBL height is calculated separately for stable/neutral conditions and convective conditions. For this, the Brunt-Väisälä frequency N in the PBL and the surface buoyancy flux B_s allow to characterise atmospheric stability:

$$N^2 = \frac{g}{T} \left(\frac{\partial T}{\partial z} + \Gamma_d \right), \quad (9)$$

g being the gravity acceleration, T a reference value of the air absolute temperature, z the height variable and $\Gamma_d = 9.8 \cdot 10^{-3}$ K/m the dry adiabatic lapse rate. If $N^2 \geq 0$, the atmosphere is considered stable/neutral. However, $N^2 < 0$ indicates a CBL.

In stable/neutral atmosphere (SBL), the formula to compute the SBL height was proposed by [88]:

$$h = \gamma u_* / f, \quad (10)$$

where u_* is the surface friction velocity, f the Coriolis parameter defined as $f =$

$2\omega \sin \phi$ (ω is the angular frequency of the Earth rotation and ϕ the latitude), and γ is a function of the imposed-stability parameter $\mu_N = N_{2h-h}/f$ in the free atmosphere:

$$\gamma = \gamma_0 \left(1 + \frac{\gamma_0^2 C_{uN}}{C_s^2} \mu_N \right)^{-1/2}, \quad (11)$$

Experimental data suggest $\gamma_0 = 0.5$, $C_{uN}/C_s^2 = 0.6$; N_{2h-h} is the free-flow Brunt-Väisälä frequency in the free atmosphere immediately above the SBL ($h < z < 2h$). In particular, the stable/neutral PBL may be classified as: truly neutral (TN) at $\mu_N = 0$ (B_s and $N_{2h-h} = 0$); conditionally neutral (CN) usually at $0.5 \times 10^2 < \mu_N < 3 \times 10^2$ ($B_s \geq 0$ and $N_{2h-h} > 0$); nocturnal stable (NS) at ($B_s < 0$ and $N_{2h-h} = 0$); and long-lived stable (LS) at ($B_s < 0$ and $N_{2h-h} > 0$).

We have implemented the log wind profile proposed in [24] for stable/neutral conditions:

$$u = \frac{u_*}{k} \left(\ln \frac{\zeta}{\zeta_0} + b_1 (\zeta - \zeta_0) + b_2 (\zeta - \zeta_0)^2 + b_3 (\zeta - \zeta_0)^3 \right), \quad (12a)$$

$$v = -\frac{u_*}{k} \delta \left(-(\zeta - \zeta_0) \ln (\zeta - \zeta_0) + a_1 (\zeta - \zeta_0) + a_2 (\zeta - \zeta_0)^2 + a_3 (\zeta - \zeta_0)^3 \right), \quad (12b)$$

for $z > d + z_0$, where u and v are the components of the horizontal wind velocity along the x and y axis of a right-hand Cartesian coordinate system with the x -axis along the surface stress; $\zeta = (z - d)/h$ and $\zeta_0 = z_0/h$ are dimensionless heights; $k \approx 0.4$ is the von Kármán constant; $\delta = fh/(ku_*) = \gamma/k$ is the dimensionless rotation rate parameter; $a_1 = 4/\delta^2 + \bar{\Pi}$, $a_2 = -\frac{3}{2}\bar{\Pi}$, $a_3 = \frac{1}{3}(1 - 4/\delta^2 + 2\bar{\Pi})$, $b_1 = \Pi - 3$, $b_2 = -\frac{3}{2}\Pi$, $b_3 = \frac{2}{3}(\Pi + 1)$, with $\Pi = C_R \delta^2 + C_L \frac{kh}{L} + C_N \frac{Nh}{u_*}$ and $\bar{\Pi} = \bar{C}_R \delta^2 + \bar{C}_L \frac{kh}{L} + \bar{C}_N \frac{Nh}{u_*}$; and $L = -u_*^3/(kB_s)$ is the Monin-Obukhov length. This model uses the values of estimates of the dimensionless constants obtained by [24] on the basis of empirical and numerical (LES) data: $C_R = 7$, $C_L = 4.5$, $C_N = 0.4$, $\bar{C}_R = 0$, $\bar{C}_L = -7$, $\bar{C}_N = -1$. In addition, the original expression in [24] has been slightly modified to verify $u(z) = 0$ and $v(z) = 0$ at $z = d + z_0$. The vertical component w of the wind velocity is assumed to be zero. From (12a), the surface friction velocity may be computed using the horizontal wind velocity interpolated at $z = z_m$, $u_0(z_m)$:

$$\begin{aligned} & \ln \frac{z_m - d}{z_0} u_*^3 - \left[k u_0(z_m) - \left(C_R \frac{\gamma}{k^2} + \frac{C_N N_{2h-h}}{f} - \frac{3}{\gamma} \right) f (z_m - (d + z_0)) \right] u_*^2 \\ & - C_L k^2 B_s (z_m - (d + z_0)) = 0 \end{aligned} \quad (13)$$

where the squared and cubic terms of the wind profile were neglected at $z = z_m$.

The estimation of the CBL height is provided by the mesoscale model estimations. If the ratio between the mechanical velocity scale $V_* = (2Uu_*)^{1/3}$ and the convective velocity scale $W_* = (B_s h)^{1/3}$ is negligible, i.e., $V_*/W_* \ll 1$, we have a Purely Convective Layer (PC). Otherwise, it is a Mechanically-Convective Layer (MC) [25]. The log wind profile in the CBL was given in [23] as follows:

$$|u| = \begin{cases} \frac{u_*}{k} \ln \frac{z-d}{z_0} & z_0 + d < z < \frac{\zeta_u |L|}{k} + d, \quad (14a) \\ \frac{u_*}{k} \left[a_u + C_u \left(\frac{k(z-d)}{L} \right)^{-\frac{1}{3}} + \ln \frac{-L}{kz_0} \right] & \frac{\zeta_u |L|}{k} + d \leq z \leq h, \quad (14b) \end{cases}$$

where $\zeta_u \approx 0.1$, $a_u \approx 0.7$ and $C_u \approx 1.4$ are dimensionless constants (see [11]).

The angle of wind turn in the boundary layer is given by the expression:

$$\sin \alpha = \sin(\alpha_s - \alpha_{h-0}) = \frac{a_\alpha}{k} \left(\frac{hk}{|L|} \right)^{-\frac{1}{3}} \frac{u_*}{|\bar{u}|} \text{sign } f, \quad (15)$$

where α_s and α_{h-0} are the angles between the wind direction and x -axis at the terrain and $z = h$, respectively. The estimation of $a_\alpha = 3$ was proposed in [23].

The mean wind velocity $|\bar{u}|$ in the CBL is obtained from:

$$|\bar{u}| = |u|_{h-0} = \frac{u_*}{k} \left[a_u + \ln \frac{-L}{kz_0} \right], \quad (16)$$

if we consider $h \gg |L|$. In practice, we assume that the wind turn angle varies linearly with height and reaches zero at the top of the CBL. Finally, note that in the CBL wind profile, the calculation of the surface friction velocity u_* from the horizontal wind velocity interpolated at $z = z_m$, $u_0(z_m)$, is generally straightforward using (14a):

$$u_* = \frac{k |u_0(z_m)|}{\ln \frac{z_m - d}{z_0}}. \quad (17)$$

In the case that $z_m \geq \frac{\zeta_u |L|}{k} + d$, we have to use (14b).

Some limitations of this wind profile should be mentioned. First, an important issue in wind modelling is that near-surface wind speeds in the zone near the crests of topographic features such as ridges and hills show mark increases when compared to the equivalent wind speeds measured at the same height above flat terrain. This aspect is more significant when the initial wind profile is constructed from a set of measures of distributed stations in a region with pronounced topographic features, where there is a chance of a hill not containing wind speed information. This issue is less usual in downscaling procedures

where the wind field information arises from the regular grid of a NWP model. This effect is related to the following aspects of our model. On the one hand, the accuracy of the wind speed results near the terrain is related with the quality of the surface discretisation. This aspect is handled by using adaptive meshes of tetrahedra that are refined around drastic geographical features. On the other hand, the terrain surface boundary condition applied in the mass-consistent model (no flow through boundary condition) forces the wind to be tangent to the terrain and, since the mass is preserved, it generates an speed up in the ridges and hills. Other aspects related to the wind speed up as, for example, isolated surfaces are not considered in this model.

Second, this model does not consider the inner boundary layers caused by a terrain with different roughness. This phenomenon is somehow approached by the application of the mass-consistent model to the initial wind profile that we construct in terms of z_0 and d . Since, the optimisation of z_0 and d is subject to some measured or predicted values, an initial, but partial, solution of this problem could be to use some data given at a suitable height. Unfortunately, in practice there is not sufficient (measured or predicted) wind information at each land cover type location and, therefore, this strategy is not always possible.

7. Parameter estimation

The results of the mass-consistent modelling have proved to be very sensitive to the values of α , ξ , z_0 , and d . Thus, an accurate definition of these parameters is critical to obtain a reliable wind field. We have to estimate a value of α and ξ for the whole domain [6], and a value of z_0 and d for each land cover class. This means that the number of unknowns depends on the number of different land covers in the region of interest. These parameters are estimated using a memetic method to optimise a fitness function that we describe in this section.

7.1. Fitness function

The objective of the optimisation is to find the values of the parameters such that the wind computed with the model is the most similar to a known wind at some control points. The wind values at the control points can be known from the HARMONIE-AROME model or measurement stations. To measure

the error between the model and the known data, we will use the RMSE, i.e.,

$$RMSE = \sqrt{\frac{1}{n_c} \sum_{i=1}^{n_c} (u_{xi} - u_{xi}^c)^2 + (u_{yi} - u_{yi}^c)^2 + (u_{zi} - u_{zi}^c)^2}, \quad (18)$$

where n_c is the number of control points, (u_{xi}, u_{yi}, u_{zi}) and $(u_{xi}^c, u_{yi}^c, u_{zi}^c)$ are, respectively, the wind velocity obtained with the mass-consistent model and the known wind at the i^{th} control point. So, the parameter estimation consists of the minimisation of the RMSE. Note that for each evaluation of the fitness function, the wind model has to be executed.

7.2. Optimisation algorithm

The optimisation strategy is based on a memetic method composed of three tools: DE [89], a Rebirth Operator (RBO) [90], and the L-BFGS-B algorithm [91]. DE is an evolutionary algorithm that utilises a population composed of a fixed number n_v of D -dimensional parameter vectors $p_{i,g}$ for each generation g ; $g = 1, \dots, n_g$. The initial population, which must cover the parameter searching space, is chosen randomly. The mutation procedure modifies an existing vector by adding to itself a weighted difference between two other vectors. In the crossover step, these mutated vectors are mixed with another target vector to obtain the so-called trial vector. If the trial vector yields a lower fitness function value than the target vector, the target vector is replaced by the trial vector (selection). Each population vector has to serve as target vector at least once, so n_v competitions will take place per generation.

The accuracy of the results obtained using DE may be insufficient. To increase it, we have run n_e DE experiments and have performed a statistic analysis of the results obtained for each one. This analysis will allow us to reduce the search interval. Let p_{i,n_g}^j ($j = 1, \dots, n_e$; $i = 1, \dots, n_u$) be the estimation of the n_u unknown parameters obtained in each of the n_e experiments. We can compute its average \bar{p}_{i,n_g} , and standard deviation σ_{i,n_g} . Then, the search interval can be reduced to the confidence interval of each variable, i.e., $\bar{p}_{i,n_g} \pm \frac{\sigma_{i,n_g}}{\sqrt{n_e}} T_{n_e-1, \frac{\tau}{2}}$, where $1 - \tau$ is the confidence coefficient and T , the Student's t-distribution. If one extreme of the new interval exceeds the old extreme, the latter is preserved. This allows the rebirth of a new population to restart

DE. This procedure may be repeated as many times as required. Note that the n_e DE experiments can be run in parallel.

When the last generation of the last reborn population is evaluated, the best parameter vector among all the DE experiments is selected to be the starting point of the L-BFGS-B algorithm. This algorithm is a procedure for solving large non-linear optimisation problems with simple bounds. It is based on the gradient projection method and uses a limited memory BFGS matrix to approximate the Hessian of the fitness function. The results of this final minimisation will be the estimated parameters.

8. Results

In this section, two experiments are presented. The first one validated the methodology in a simple test involving a near flat terrain. The values of the parameters were known in advance, and we used our methodology to recover them. The second experiment was an application in an eastern location of Gran Canaria Island, using the HARMONIE-AROME and ECMWF models and the measurement wind data from the AEMET network of stations.

8.1. Test numerical experiment

The domain of this experiment is a $2 \text{ km} \times 1.5 \text{ km}$ rectangular region composed of a grid of 6×5 different land cover polygons; see Fig. 2. The height of the domain was 2 km. The terrain surface contained three artificial hills of 50 m height (smooth terrain). A mesh of 8526 nodes and 42 568 tetrahedra, adapted to the terrain, was generated using the meccano mesh generator [92, 93].

For a more realistic example, each of the thirty polygons of the test was defined as a compound coverage made up as a weighted average of some basic ones. Note that some cells had the same configuration, e.g., cells 2, 4 and 8, and 10, 11, 15 and 17, respectively. This configuration increased the difficulty of the problem since the effect of some types of coverage was negligible in the RMSE.

To define the test input data for the mass-consistent model, first, we fix $\alpha = 0.1$ and $\xi = 0.5$ in the whole domain. The values of z_0 and d are equal to the corresponding mean of the nominal values given in Table 1 (Eq. 1 for z_0 and

Eq. 2 for d) for each polygon configuration. In addition, we considered a Truly Neutral atmosphere, i.e., $\mu_n = 0$ and $B_s = 0$. Next, we selected 10 points at 10 m above $z_t + d$, and imposed constant wind of 10 m s^{-1} and East direction. Once the input data were defined, we computed a three-dimensional wind field using our mass-consistent model. The results obtained at 5 different heights for 5 locations per polygon were used as control points in the optimisation problem ($5 \times 5 \times 30$ control points). The objective was to recover the prescribed values of α , ξ , z_0 , and d using the memetic procedure described in Sect. 7. The initial search intervals were $[10^{-2}, 10]$ for α , $[0, 1]$ for ξ , and the ranges of variation given in Table 1 for z_0 and d . The number of parallel DE experiments (n_e) was 8.

25 3.04 2.11×10^{-2}	26 6×10^{-1} 1.1×10^{-1}	27 5×10^{-2} 1×10^{-2}	28 8.18 2.39×10^{-1}	29 4.68 1.16×10^{-1}	30 1.52 2.1×10^{-3}
19 6.93 2.73×10^{-1}	20 2.27 1.85×10^{-2}	21 2.15 1.26×10^{-2}	22 8.4 1.49×10^{-1}	23 2.17 5.56×10^{-3}	24 4.82 1.82×10^{-1}
13 5.07 1.8×10^{-2}	14 3.12×10^1 5.68×10^{-3}	15 6.81 2.08×10^{-2}	16 3.04 5.69×10^{-2}	17 6.81 2.08×10^{-2}	18 3.35 5.92×10^{-2}
7 7.38 2.33×10^{-1}	8 5.1 2.25×10^{-1}	9 8.34 3.33×10^{-1}	10 6.81 2.08×10^{-2}	11 6.81 2.08×10^{-2}	12 3.72 1.3×10^{-2}
1 2.55×10^1 7.85×10^{-4}	2 5.1 2.25×10^{-1}	3 6.09 1.99×10^{-1}	4 5.1 2.25×10^{-1}	5 6.93 2.73×10^{-1}	6 8.3 3.41×10^{-1}

Figure 2: Test region with the 30 polygons related to SIOSE compound coverages. In each cell, from top, we have the cell number related to results in Table 2, d (m) and z_0 (m), respectively.

Table 2 summarises the results of this experiment. Columns 2 and 3 list the values of the relative errors in percentage between the estimated z_0 and d and the corresponding target values for each polygon, respectively, after 8 DE processes were run. This first stage of the optimisation process yielded an $RMSE$ of 3.57×10^{-3} and the relative errors of α and ξ were 0.07% and 8.77%, respectively. The results seem to be accurate, except for the cells 20, 26 and 27, where d estimations were quite far from the target values. Next, we reduced the search intervals by applying Student’s t-distribution to the 8 DE results. Then, eight more DE processes were run with the new intervals, and the best result was improved using L-BFGS-B, obtaining $RMSE = 8.15 \times 10^{-4}$,

Table 2: Results of the test experiment. Relative errors were computed against target values.

Cell	DE (z_0) Relative error (%)	Rebirth DE + L-BFGS-B (z_0) Rel. error (%)	DE (d) Relative error (%)	Rebirth DE + L-BFGS-B (d) Rel. error (%)
1	5,87	0,51	0,42	0,06
2	1,64	0,07	0,48	0,08
3	2,33	0,69	2,32	0,67
4	1,64	0,07	0,48	0,08
5	1,92	0,11	1,59	0,17
6	0,85	0,68	0,01	0,44
7	0,55	0,19	0,45	0,03
8	1,64	0,07	0,48	0,08
9	1,31	0,19	0,04	0,10
10	0,96	0,19	0,63	0,10
11	0,96	0,19	0,63	0,10
12	4,35	0,35	6,92	1,05
13	4,85	3,41	1,62	0,55
14	0,96	0,77	0,42	0,06
15	5,58	0,19	0,63	0,10
16	0,96	0,84	6,74	1,02
17	1,92	0,19	0,63	0,10
18	10,83	2,95	2,48	4,17
19	1,07	0,11	1,59	0,17
20	0,23	2,37	23,70	2,87
21	5,38	0,49	5,16	2,09
22	6,53	0,13	0,04	0,08
23	5,07	0,70	5,77	1,21
24	7,45	0,11	8,06	0,20
25	6,84	1,42	5,37	1,88
26	6,88	0,56	41,04	6,39
27	0,21	1,20	39,85	69,69
28	0,61	0,68	0,32	0,43
29	6,37	1,18	7,01	0,99
30	9,26	0,77	7,02	0,98

$\alpha = 0.1$ and $\xi = 6,81 \times 10^{-1}$ (relative errors of 0.01% and 36.2%, respectively). The new relative errors of z_0 and d at this stage are shown in columns 4 and 5, in this order. The rebirth procedure improved the estimations of most of the roughness parameters. However, there were a few cases where the relative error was increased. In particular, the case of d in cell 27 that reached an error of 69.69%. This was because the target value of d in that cell is very small (5.00×10^{-2} m) in comparison with other cells and, therefore, the model is not sensitive to this value. This is also the case of ξ . In equation (8), any value of ξ would have produced the same result since all the measures have the same value and the same height over $z_t + d$. Thus, any of them would be a correct estimation.

Regarding the computational cost of this experiment, the average runtime of the DE procedures was about 4 h 47 min for 300 iterations, with a population size of 342, involving 57 unknown parameters; this led to 102,942 evaluations of the fitness function (0.167 s/evaluation). The rebirth procedure, including the L-BFGS-B algorithm, run during 5 h 39 min with the same DE strategy but 117,964 fitness function evaluations. All the processes were run in parallel on a cluster of 24 nodes. Each node is composed of 2 Intel Xeon E5645 Westmere-EP processors, each of them with 6 cores. Therefore, in general, the results of this experiment indicate, for this case, the effectiveness of our methodology and the convenience of applying the rebirth strategy.

8.2. Application to Gran Canaria Island

In this experiment, we apply the described methodology to a region of the Gran Canaria island. The downscaling model uses the forecast from HARMONIE-AROME and ECMWF. The memetic algorithm estimates the roughness length and displacement height.

The region of interest is a rectangular domain of $12 \text{ km} \times 28.5 \text{ km} \times 3 \text{ km}$ located at the East of Gran Canaria Island. The tetrahedral mesh is adapted to the terrain with additional local refinement around the measurement stations and the shoreline; see a detail of the terrain triangulation in Fig. 3. The mesh contains 44970 tetrahedra and 10070 nodes.

The land coverages are taken from the SIOSE database. Since, in Gran Canaria, the range of variation of environmental temperature is rather small

throughout the year, the land coverages may be considered constant in size and shape. Precisely, in the region of interest, there are 1216 land cover polygons, each with a particular combination of 26 basic coverages.

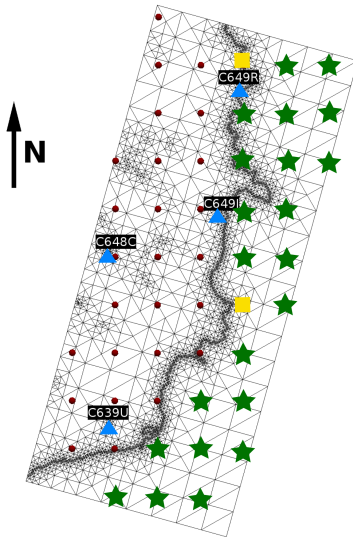


Figure 3: Detail of the terrain of the adaptive mesh of Gran Canaria Island. The symbols indicate the locations of the data falling inside the domain: the triangles represent the measurement stations; the stars, the control points of HARMONIE-AROME only; the squares, the control points of both HARMONIE-AROME and ECMWF; and the circles, the additional grid points of HARMONIE-AROME used in the mass-consistent model.

The roughness parameters depend on wind velocity and stability due to the fact that they characterise the surface that influences the wind speed profile (so-called footprint). This footprint is dependent on stability and height (in general, boundary layer conditions), and so indirectly are the roughness parameters. The stability dependence of the roughness length and displacement height was demonstrated by [94]. For this reason, we have chosen six episodes to carry out the experiment, each one corresponding to a different stability class. Table 3 shows the selected episodes indicating the stability class, the 10 m wind speed and direction, and the values of the B_s , N_{2h-h} , W_* , and V_* . These values are the HARMONIE-AROME predictions for June 2015. The stability class has been defined using the B_s values and N_{2h-h} or the comparison between W_* and V_* values, according to Zilitinkevich et al. [25]. We want to emphasise that,

Table 3: Selected wind episodes in an Eastern region of Gran Canaria Island during June 2015.

BL stability	HARMONIE 10 m wind speed (ms^{-1})	HARMONIE 10 m wind direction ($^\circ$)	Surf. buoy. flux, B_s (m^2s^{-3})	B-V freq., N_{2h-h} (s^{-1})	Ratio V_*/W_*
LS	10.18	336.92 – NNW	-1.38×10^{-4}	1.68×10^{-2}	–
NS	6.10	331.46 – NNW	-9.78×10^{-4}	≈ 0	–
TN	7.51	331.82 – NNW	≈ 0	≈ 0	–
CN	8.52	340.72 – NNW	3.68×10^{-3}	1.04×10^{-2}	–
PC	1.59	116.78 – ESE	6.22×10^{-3}	1.54×10^{-2}	0.17
MC	6.87	358.98 – N	3.02×10^{-3}	1.74×10^{-2}	0.76

although we have defined the third episode of Table 3 as Truly Neutral (the only case out of 240 for the whole period), it corresponds to a Conditionally Neutral boundary layer with very small B_s and N_{2h-h} . The same occurs with the Nocturnal Stable case, which may also be considered as a Long-Lived Stable boundary layer with a very small N_{2h-h} . Moreover, the selected PC episode is the only one with ESE wind direction in that month. In the studied period, most episodes were LS (44.58%), MC (41.25%), or CN (9.58%).

For each of the six chosen episodes, the memetic algorithm estimates the values of α , and the 26 basic coverages z_0 and d . The searching space for the aerodynamic parameters is the one given in Table 1. Regarding α , its values ranges from 10×10^{-2} to 1 in SBL and from 1 to 5 in CBL.

Table 4: Location in UTM zone 28N coordinates and heights above the sea level of the anemometers used in the numerical application in Gran Canaria Island.

Code	Name	x (m)	y (m)	z (m)
C639U	San Bartolomé de Tirajana, El Matorral	455345	3076503	51
C648C	Aguimes	455326	3086484	316
C649I	Gran Canaria, Aeropuerto	461659	3088640	34
C649R	Telde, Melenara	462855	3095805	19

Wind measures at four stations of the AEMET network are available in the studied region. Their UTM coordinates and heights above sea level are given

in Table 4 and shown in Fig. 3. It should be noted that data from more wind stations should have been desirable to achieve a more definite validation.

Two different experiments have been carried out; one using data from HARMONIE-AROME, and the other using data from ECMWF. Figure 3 shows the grid points from both NWP models. The wind velocities are plotted for a particular episode. The interpolated wind field is constructed from the NWP wind velocities at 10 m.

Finally, we estimate the parameters using the memetic algorithm described in Sect. 7. The control points used to compute the RMSE are different for the two experiments. In the case of the HARMONIE-AROME, there are 28 control points: the four stations wind data and the 24 HARMONIE-AROME 10 m wind located over the sea. In the ECMWF experiment, there are the four stations and two more ECMWF points over the sea (see Fig. 3).

Table 5: Results of the experiments in Gran Canaria Island using data from HARMONIE-AROME (z_0 and d in meters).

Wind direction	NNW	NNW	NNW	NNW	N	N
Wind speed (ms^{-1})	$v > 6$	$v > 6$	$v > 6$	$v > 6$	$v \leq 2$	$v > 6$
Stability	LS	NS	TN	CN	PC	MC
RMSE(H-A)	8.47	3.12	5.94	7.89	3.29	2.46
RMSE(H-A/W3D) nominal values	4.00	3.47	4.74	6.21	2.55	2.40
RMSE(H-A/W3D) estimated values	2.44	2.59	3.47	4.78	2.27	1.31
RMSE(ECMWF)	7.08	3.88	3.16	6.14	2.97	2.98
RMSE(ECMWF/W3D) nominal values	4.00	3.47	4.74	6.21	2.55	5.90
RMSE(ECMWF/W3D) estimated values	2.56	2.91	3.68	4.79	2.53	2.35

The results of the experiments are condensed in Table 5 as the RMSE values for the six episodes. These RMSE values are always constructed against the measurement wind data from the meteorological stations.

The first three rows correspond to the HARMONIE-AROME experiment, while the last three correspond to the ECMWF experiment. Each group of three rows has to be read the same way: the first row is the RMSE obtained by NWP forecast; the second row is the error obtained by the downscaling model Wind3D using the nominal values from Table 1; i.e. without using the memetic algorithm; and the third row are the errors obtained by the complete procedure

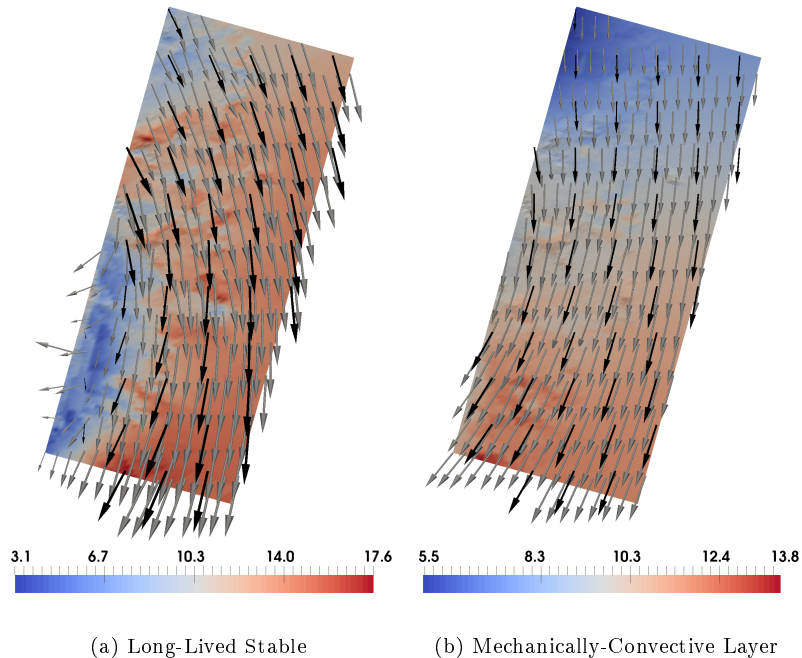


Figure 4: Detail of 10 m wind velocities in the (a) LS and (b) MC cases of Table 3. The colours represent the wind speed obtained by Wind3D. The black vectors are the wind velocities provided by HARMONIE-AROME. The grey vectors are the downscaled wind velocities.

described in this paper.

Looking at the results, in the HARMONIE-AROME experiment, there has been an improvement between 16.99% and 71.19% comparing the results from the NWP and the wind obtained using the described procedure. In the ECMWF experiment, the improvement is similar to the one obtained in the HARMONIE-AROME experiment, except in the TN episode. In this case, the downscaling model has not been able to improve the ECMWF forecasting. Looking at the differences in RMSE between the downscaling forecast using nominal or estimated values, the necessity of estimating z_0 and d gets clear; the errors are always smaller for the estimated values.

Figure 4 represents the forecast 10m wind velocities for the LS and MC episodes. The wind field represented is the HARMONIE-AROME forecast and the Wind3D with estimated values results. We observe that the mass-consistent model reproduced the HARMONIE-AROME wind, but providing a more accu-

rate wind in the microscale and improving the predictions in the surroundings of the measurement stations, as seen in Table 5.

A note on computational time is relevant. The average runtime of each DE procedure is 6 h and 39 min. The DE algorithm consists of 300 iterations, with a population size of 294, involving 49 unknown parameters, which leads to 88 493 evaluations of the fitness function (0.271 s per evaluation). The rebirth procedure, including the L-BFGS-B algorithm, runtime is 5 h 28 min consisting of 232 iterations with 71 810 fitness function evaluations. All the processes were run in the same cluster described in the test experiment.

9. Discussion

The selected experiments are located over non-complex terrain to overcome the limitations of the mass-consistent model and provide reliable and meaningful results of wind adjustment. The literature indicates that the values of the parameters change for different atmospheric states (wind speed, direction and stability). This dependence can be seen if we study the estimated values of z_0 and d in the Gran Canaria experiment for the different episodes.

Studying the largest coverage, AMO (47.74 % of the domain), for the ECMWF experiment, the estimated values of z_0^{AMO} are the maximum in the searching interval; in the HARMONIE-AROME experiment they tend to the maximum limit in the CBL cases. Since there are not any control points over the sea in the ECMWF experiments, we consider the results from HARMONIE-AROME more reliable. The largest land coverage in the domain is MTR (15.54 %). In this case, the estimated values of z_0^{MTR} and d^{MTR} vary from the minimum to the maximum values depending on the BL stability. In the SDN coverage (9.24 %), both NWP models reach similar results of the roughness parameters, except for the LS case. Also, for CHL coverage (5.68 %) both models agree about the values of z_0^{CHL} , reaching the maximum in SBL and the minimum in CBL. For both NWP models, the d^{CHL} values are similar, except for the PC stability. Regarding the EDF coverage, the displacement height reaches the maximum value for any stability and NWP model. However, z_0^{EDF} tends to the minimum value in LS, NS, TN and MC, while in PC reaches the maximum value, for both models. In CN the results differ about a 20 % of the total range

near the minimum. Each of the other coverages represents less than a 3% of the domain surface.

One valuable observation is that the estimated values of z_0 and d are always different from the nominal values found in the literature. This can be explained, not only because they are fitting parameters, but also because the values of z_0 and d are dependent on regional characteristics of the land coverages. The results found in the experiments indicate that the estimated values always yield a smaller error. For this reason, we think that it is critical to estimate the parameters. It is important to remember that the proposed method estimates the values of z_0 and d that are better suited for the combination of basic coverages found in the land cover database; so the estimated values may not be an accurate value for the aerodynamic parameters as such.

Concerning the values of α , it is normally lower in SBL (stable and neutral conditions) than in CBL (unstable conditions). In our experiments, α tends to the upper bound (1) in SBL cases, i.e., the model tried to adjust the wind velocities changing the vertical component and preserving the horizontal ones as much as possible. However, in CBL episodes a greater variation of the vertical component is allowed, and the values of α also tend to the upper bound (5) in all cases except for the MC stability in the ECMWF experiment where the value estimated is 4. The parameter ξ could affect the wind results if the input data of wind were given on a dispersed grid, but it is not the usual case in downscaling problems; therefore, ξ does not apply.

Comparing the values of the estimated parameters for the HARMONIE-AROME and the ECMWF experiments, there is general agreement between the values for each stability condition. However, while some parameters reach the same values, e.g., z_0^{EDF} , d^{EDF} , α , others are estimated in the opposite bound of the interval, e.g., z_0^{ACM} , z_0^{LFN} , d^{PDA} , d^{VAP} , d^{ZAU} . Moreover, for both experiments, some parameters are estimated to the same values most days, there are others that differ greatly between days, e.g., z_0^{ARR} , z_0^{LAA} , z_0^{PST} , z_0^{SDN} , z_0^{SNE} , z_0^{ZAU} , z_0^{ZEV} , d^{MTR} , d^{LFC} . These divergences show that the proposed methodology is strongly dependent on the forecast values of the mesoscale model, which determine the quality of the predicted wind field. For this reason, we suggest running the methodology for each NWP independently.

An important aspect to be considered is a sensitivity analysis of the involved parameters. Some coverages may show little effect on the resulting wind field. As a result, a reduction of the number of unknowns may be possible by not considering those parameters. Another aspect that can be considered is the fact that a basic coverage may affect different regions with very diverse characteristics. In the current implementation, each parameter is represented by a single value, even when their optimal values could be different in each region. The more a basic cover appears in different locations, the more a unique estimation is not optimal for each of them separately. For this reason, if the sensitivity analysis determines that the results of the model are highly dependent on those parameters, it may be worth to consider different unknowns for each region.

Finally, this methodology can be applied to construct a reduced basis for its use in wind forecasting. To this end, a larger period should be studied (at least one year). This would allow to analyse all the wind condition types (speed, direction, atmosphere stability) occurring in Gran Canaria Island. Reduced Basis (RB) methods consist of seeking, for any new parameter value, in a subspace of lower dimension than the discretised PDE problem (high-fidelity problem), an approximate solution of that Hi-Fi problem, expressed as a linear combination of suitable basis functions that are dependent on the problem. To generate these basis functions, the set of solutions to the finite element problem (snapshots) are used; a suitably chosen set of parameter values may be, e.g., a selection of representative wind conditions. The procedure has two stages. On the one hand, the offline block including the high-fidelity discretisation, the generation of solution snapshots by Proper Orthogonal Decomposition (POD) and the construction of the projection matrices. On the other hand, for a chosen parameter value, we have to assemble and solve the RB system to obtain the projected solution and, then, recover the solution in the original dimension. A detailed description of RB can be found in [95, 96].

10. Conclusions

This paper presents a methodology to improve the downscaling forecasting by estimating the parameters involved. These parameters are the ratio of the Gauss precision moduli α , that appears in the elliptic problem of the PDE

(eq. 7a, 7b, 7c); the weighting parameter ξ of the horizontal interpolation of wind velocities (eq. 8); and the roughness length z_0 and the displacement height d of each basic cover class in the logarithmic wind profile (eq. 12a, 12b, 14a, 14b). To estimate these parameters, a memetic algorithm, consisting of the DE method and L-BFGS-B algorithm, combined with a rebirth procedure based on Student t-distribution confidence interval, is proposed.

This procedure has been applied to two different experiments. The first is a synthetic test with known target values of the parameters, where the method was able to estimate the values of most of them with a small error. Just one estimation of d for a compound coverage was not successfully obtained because the model was not sensitive to such a small value of d . Nevertheless, the effect of this error in the downscaling wind was negligible. In the second experiment, a real case in Gran Canaria Island was carried out. In this case, the input values of the model came from two different models: HARMONIE-AROME, and ECMWF; and the control points were some measurement stations and the mesoscale model nodes over the sea. Different episodes with different atmospheric conditions have been considered. In all cases, the wind prediction of the mass-consistent model with the estimated parameters was closer to the measurement data than the one provided by the mesoscale model.

Accordingly, we conclude that the proposed approach—combining parameter estimation and a mass-consistent model—is an efficient tool for NWP downscaling. Nevertheless, since this diagnostic model has limitations, in future research, we will implement the momentum conservation law into our wind model to improve the accuracy of diagnostic wind modelling in complex terrain. Another issue to be studied is the hypothesis, admitted in this work, that the mass-consistent model, with mass continuity law and no flow through boundary condition on the terrain surface, faithfully reproduces the near-surface speed up caused by topographic features. This should be checked and compared with any correction procedure like MS-Micro; see, e.g., [13, 97]. Finally, further research should be carried out to add the footprint effect to the wind profile formulation of Wind3D model to consider inner boundary layers in the starting wind.

We remark that the parameter estimations obtained for different wind and atmospheric conditions show that the mass-consistent model results are sensitive

to the aerodynamic parameters for most coverages. In fact, small variations in the wind speed or direction may lead to considerably different parameter values, in agreement with the literature. For this reason, we propose to use this method combined with reduced basis. The reduced basis is grounded on the resulting parameters for a set of representative atmospheric conditions. Using the reduced basis, the microscale wind field could be computed using the mass-consistent model in a cost-efficient manner. However, further discussion about a suitable construction of such reduced basis from the results obtained in this work should be carried out.

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