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Singular limiting solutions for elliptic problem involving exponentially dominated nonlinearity and convection term

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available at the end of the article**Abstract**

Given Ω bounded open regular set of \mathbb{R}^2 and $x_1, x_2, \dots, x_m \in \Omega$, we give a sufficient condition for the problem

$$-\operatorname{div}(e^{\lambda u} \nabla u) = \rho^2 f(u)$$

to have a positive weak solution in Ω with $u = 0$ on $\partial\Omega$, which is singular at each x_i as the parameters $\rho, \lambda > 0$ tend to 0 and where $f(u)$ is dominated exponential nonlinearities functions.

2000 **Mathematics Subject Classification**: 35J60; 53C21; 58J05.

Keywords: singular limits, Green's function, nonlinear Cauchy-data matching method

1 Introduction and statement of the results

We consider the following problem

$$\begin{cases} -\operatorname{div}(a(u)\nabla u) & = \rho^2 f(u) & \text{in } \Omega \\ u & = 0 & \text{on } \partial\Omega, \end{cases} \quad (1)$$

where ∇ is the gradient and Ω is an open smooth bounded subset of \mathbb{R}^2 . The function a is assumed to be positive and smooth. In the following, we take $a(u) = e^{\lambda u}$ and $f(u) = e^{\lambda u}(e^u + e^{\gamma u})$, for $\lambda > 0$ and $\gamma \in (0, 1)$, then problem (1) take the form

$$\begin{cases} -\Delta u - \lambda|\nabla u|^2 & = \rho^2(e^u + e^{\gamma u}) & \text{in } \Omega \subset \mathbb{R}^2 \\ u & = 0 & \text{on } \partial\Omega. \end{cases} \quad (2)$$

Using the following transformation

$$w = (\lambda\rho^2 e^u)^\lambda,$$

then the function w satisfies the following problem

$$\begin{cases} -\Delta w = w^{\frac{\lambda+1}{\lambda}} + \rho w^{\frac{\gamma-1}{\lambda}} & \text{in } \Omega \subset \mathbb{R}^2 \\ w = (\lambda\rho^2)^\lambda & \text{on } \partial\Omega. \end{cases} \quad (3)$$

with $\varrho = (\lambda\rho^2)^{1-\lambda}$. So when $\lambda \rightarrow 0^+$, the exponent $q = \frac{\lambda+1}{\lambda}$ tends to infinity while the exponent $\frac{\gamma-1}{\lambda}$ tends to $-\infty$. For $\varrho \equiv 0$, problem (3) has been studied by Ren and Wei in [1]. See also [2].

We denote by ε the smallest positive parameter satisfying

$$\rho^2 = \frac{8\varepsilon^2}{(1+\varepsilon^2)^2}. \tag{4}$$

Remark that $\rho \sim \varepsilon$ as $\varepsilon \rightarrow 0$. We will suppose in the following

$$(A_\lambda): \quad \text{If } 0 < \varepsilon < \lambda, \quad \text{then } \lambda^{1+\delta/2}\varepsilon^{-\delta} \rightarrow 0 \quad \text{as } \lambda \rightarrow 0, \text{ for any } \delta \in (0, 1).$$

In particular, if we take $\lambda = \mathcal{O}(\varepsilon^{2/3})$, then the condition (A_λ) is satisfied. Under the assumption (A_λ) , we can treat equation (2) as a perturbation of the following:

$$-\Delta u = \rho^2(e^u + e^{\gamma u}) \quad \text{in } \Omega \subset \mathbb{R}^2$$

for $\gamma \in (0, 1)$.

Our question is: Does there exist $v_{\varepsilon,\lambda}$ a sequence of solutions of (2) which converges to some singular function as the parameters ε and λ tend to 0?

In [3], Baraket et al. gave a positive answer to the above question for the following problem

$$\begin{cases} -\Delta u - \lambda|\nabla u|^2 = \rho^2 e^u & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega, \end{cases} \tag{5}$$

with a regular bounded domain Ω of \mathbb{R}^2 . They give a sufficient condition for the problem (5) to have a weak solution in Ω which is singular at some points $(x_i)_{1 \leq i \leq m}$ as ρ and λ a small parameters satisfying (A_λ) , where the presence of the gradient term seems to have significant influence on the existence of such solutions, as well as on their asymptotic behavior.

In case $\lambda = 0$ the authors in [4] gave also a positive answer for the following problem

$$\begin{cases} -\Delta u = \rho^2(e^u + e^{\gamma u}) & \text{in } \Omega \subset \mathbb{R}^2 \\ u = 0 & \text{on } \partial\Omega, \end{cases} \tag{6}$$

for $\gamma \in (0, 1)$ as ρ tends to 0. When $\lambda = 0$ and $\gamma = 0$, problem (2) reduce to

$$\begin{cases} -\Delta u = \rho^2 e^u & \text{in } \Omega \subset \mathbb{R}^2 \\ u = 0 & \text{on } \partial\Omega. \end{cases} \tag{7}$$

The study of this problem goes back to 1853 when Liouville derived a representation formula for all solutions of (7) which are defined in \mathbb{R}^2 , see [5]. It turns out that, beside the applications in geometry, elliptic equations with exponential nonlinearity also arise in modeling many physical phenomenon, such as thermionic emission, isothermal gas sphere, gas combustion, and gauge theory [6]. When ρ tends to 0, the asymptotic behavior of nontrivial branches of solutions of (7) is well understood thanks to the pioneer work of Suzuki [7] which characterizes the possible limit of nontrivial branches of solutions of (7). His result has been generalized in [8] to (6) with $\gamma < \frac{1}{4}$, and finally by Ye in [9] to any exponentially dominated nonlinearity $f(u)$. The existence of nontrivial branches of solutions with single singularity was first proved by Weston [10] and then a general result has been obtained by Baraket and Pacard [11]. These results were also

extended, applying to the Chern-Simons vortex theory in mind, by Esposito et al. [12] and Del Pino et al. [13] to handle equations of the form $-\Delta u = \rho^2 V(x)e^u$ where V is a nonconstant positive potential. See also [14-16] wherever this rule is applicable. where the Laplacian is replaced by a more general divergence operator and some new phenomena occur. Let us also mention that the construction of nontrivial branches of solutions of semilinear equations with exponential nonlinearities allowed Wentz to provide counter examples to a conjecture of Hopf [17] concerning the existence of compact (immersed) constant mean curvature surfaces in Euclidean space. Another related problem is the higher dimension problem with exponential nonlinearity. For example, the 4-dimensional semilinear elliptic problem with bi-Laplacian is treated in [18] and the problem with an additional singular source term given by Dirac masses is treated in [19] in the radial case. The results in [18,19] are generalized to noncritical points of the reduced function, see [20].

We introduce now the Green's function $G(x, x')$ defined on $\Omega \times \Omega$, to be solution of

$$\begin{cases} -\Delta G(x, x') = 8\pi \delta_{x=x'} & \text{in } \Omega \subset \mathbb{R}^2 \\ G(x, x') = 0 & \text{on } \partial\Omega \end{cases}$$

and let $H(x, x') = G(x, x') + 4\log|x - x'|$, its regular part. Let $m \in \mathbb{N}$, we set

$$\mathcal{F}(x_1, \dots, x_m) = \sum_{j=1}^m H(x_j, x_j) + \sum_{i \neq j} G(x_i, x_j) \tag{8}$$

which is well defined in $(\Omega)^m$ for $x_i \neq x_j$ for $i \neq j$. Our main result is the following

Theorem 1 *Given $\beta \in (0, 1)$. Let Ω an open smooth bounded set of \mathbb{R}^2 , $\lambda > 0$ satisfying the condition (A_λ) , $\gamma \in (0, 1)$ and $S = \{x_1, \dots, x_m\} \subset \Omega$ be a nonempty set. Assume that, the point (x_1, \dots, x_m) is a nondegenerate critical point of the function*

$$\mathcal{F}(x_1, \dots, x_m) = \sum_{j=1}^m H(x_j, x_j) + \sum_{i \neq j} G(x_i, x_j) \quad \text{in } (\Omega)^m,$$

then there exist $\varepsilon_0 > 0$, $\lambda_0 > 0$ and $\{v_{\varepsilon, \lambda}\}_{0 < \varepsilon < \varepsilon_0, 0 < \lambda < \lambda_0}$ a family of solutions of (2), such that

$$\lim_{\substack{\varepsilon \rightarrow 0 \\ \lambda \rightarrow 0}} v_{\varepsilon, \lambda} = \sum_{j=1}^m G(x_j, \cdot) \quad \text{in } C_{loc}^{2, \beta}(\Omega - \{x_1, \dots, x_m\}).$$

One of the purpose of the present paper is to present a rather efficient method: *non-linear Cauchy-data matching method* to solve such singularly problems. This method has already been used successfully in geometric context (constant mean curvature surfaces, constant scalar curvature metrics, extremal Kähler metrics, manifolds with special holonomy, ...) and appeared in the study [18] in the context of partial differential equations.

2 Construction of the approximate solution

We first describe the rotationally symmetric approximate solutions of

$$-\Delta u - \lambda |\nabla u|^2 = \rho^2 (e^u + e^{\gamma u}) \tag{9}$$

in \mathbb{R}^2 which will play a central role in our analysis. Given $\varepsilon > 0$, we define

$$u_\varepsilon(x) := 2 \log(1 + \varepsilon^2) - 2 \log(\varepsilon^2 + |x|^2) \tag{10}$$

which is clearly a solution of

$$-\Delta u = \rho^2 e^u. \tag{11}$$

in \mathbb{R}^2 . Let us notice that equations (11) is invariant under dilation in the following sense: If v is a solution of (11) and if $\tau > 0$, then $v(\tau \cdot) + 2 \log \tau$ is also a solution of (11). With this observation in mind, we define for all $\tau > 0$

$$u_{\varepsilon, \tau}(x) := 2 \log(1 + \varepsilon^2) + 2 \log \tau - 2 \log(\varepsilon^2 + |\tau x|^2). \tag{12}$$

2.1 A linearized operator on \mathbb{R}^2

For all $\varepsilon, \tau, \lambda > 0$, we set

$$R_{\varepsilon, \lambda} := \tau r_{\varepsilon, \lambda} / \varepsilon \quad \text{where} \quad r_{\varepsilon, \lambda} := \max(\varepsilon^{2(1-\gamma)-\delta/2}, \sqrt{\lambda}, \sqrt{\varepsilon}). \tag{13}$$

for $\delta \in (0, 1)$. We define the linear second order elliptic operator

$$\mathbb{L} := -\Delta - \frac{8}{(1 + |x|^2)^2} \tag{14}$$

which corresponds to the linearization of (11) about the solution u_1 ($= u_{\varepsilon = \tau = 1}$) given by (10) which has been defined in the previous section. We are interested in the classification of bounded solutions of $\mathbb{L}w = 0$ in \mathbb{R}^2 . Some solutions are easy to find. For example, we can define

$$\phi_0(x) := \frac{r}{2} \partial_r u_1(x) + 1 = 2 \frac{1 - r^2}{1 + r^2},$$

where $r = |x|$. Clearly $\mathbb{L}\phi_0 = 0$ and this reflects the fact that (11) is invariant under the group of dilations $\tau \rightarrow u(\tau \cdot) + 2 \log \tau$. We also define, for $i = 1, 2$

$$\phi_i(x) := -\partial_{x_i} u_1(x) = \frac{2x_i}{1 + |x|^2},$$

which are also solutions of $\mathbb{L}\phi_i = 0$. Since, these solutions correspond to the invariance of the equation under the group of translations $a \rightarrow u(\cdot + a)$. We recall the following result which classifies all bounded solutions of $\mathbb{L}w = 0$ which are defined in \mathbb{R}^2 .

Lemma 1 [11] *Any bounded solution of $\mathbb{L}w = 0$ defined in \mathbb{R}^2 is a linear combination of ϕ_i for $i = 0, 1, 2$.*

Let B_r denote the ball of radius r centered at the origin in \mathbb{R}^2 .

Definition 1 *Given $k \in \mathbb{N}$, $\beta \in (0, 1)$ and $\mu \in \mathbb{R}$, we introduce the Hölder weighted spaces $C_{\mu}^{k, \beta}(\mathbb{R}^2)$ as the space of functions $w \in C_{loc}^{k, \beta}(\mathbb{R}^2)$ for which the following norm*

$$\|w\|_{C_{\mu}^{k, \beta}(\mathbb{R}^2)} := \|w\|_{C^{k, \beta}(\bar{B}_1)} + \sup_{r \geq 1} \left((1 + r^2)^{-\mu/2} \|w(r \cdot)\|_{C_{\mu}^{k, \beta}(\bar{B}_1 - B_{1/2})} \right),$$

is finite.

We define also

$$C_{rad, \mu}^{k, \beta}(\mathbb{R}^2) = \{f \in C_{\mu}^{k, \beta}(\mathbb{R}^2); \text{ such that } f(x) = f(|x|), \forall x \in \mathbb{R}^2\}.$$

As a consequence of the result of Lemma 1, we recall the surjectivity result of \mathbb{L} given in [11].

Proposition 1 [11]

(i) Assume that $\mu > 1$ and $\mu \notin \mathbb{N}$, then

$$\begin{aligned} L_\mu : C_\mu^{2,\beta}(\mathbb{R}^2) &\rightarrow C_{\mu-2}^{0,\beta}(\mathbb{R}^2) \\ w &\mapsto \mathbb{L}w \end{aligned}$$

is surjective.

(ii) Assume that $\delta > 0$ and $\delta \notin \mathbb{N}$ then

$$\begin{aligned} L_\delta : C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2) &\rightarrow C_{\text{rad},\delta-2}^{0,\beta}(\mathbb{R}^2) \\ w &\mapsto \mathbb{L}w \end{aligned}$$

is surjective.

We set $\bar{B}_1^* = \bar{B}_1 - \{0\}$, we define

Definition 2 Given $k \in \mathbb{N}$, $\beta \in (0, 1)$ and $\mu \in \mathbb{R}$, we introduce the Hölder weighted spaces $C_\mu^{k,\beta}(\bar{B}_1^*)$ as the space of functions in $C_{\text{loc}}^{k,\beta}(\bar{B}_1^*)$ for which the following norm

$$\|u\|_{C_\mu^{k,\beta}(\bar{B}_1^*)} = \sup_{r \leq 1/2} \left(r^{-\mu} \|u(r \cdot)\|_{C^{k,\beta}(\bar{B}_2 - B_1)} \right),$$

is finite.

Then, we define the subspace of radial functions in $C_{\text{rad},\delta}^{k,\beta}(\bar{B}_1^*)$ by

$$C_{\text{rad},\delta}^{k,\beta}(\bar{B}_1^*) = \{f \in C_\delta^{k,\beta}(\mathbb{R}^2); \text{ such that } f(x) = f(|x|), \forall x \in \bar{B}_1^*\}.$$

We would like to find a solution u of

$$\Delta u + \lambda |\nabla u|^2 + \rho^2 (e^u + e^{\gamma u}) = 0 \tag{15}$$

in $B_{r,\lambda}$. By using the transformation, $v(x) = u(\frac{\varepsilon}{\tau}x) + 4 \log \varepsilon - 2 \log(\tau(1 + \varepsilon^2)/2)$, then Eq. (15) is equivalent to

$$\Delta v + \lambda |\nabla v|^2 + 2 \left(e^v + \frac{2^{2(1-\gamma)} \varepsilon^{4(1-\gamma)}}{((1 + \varepsilon^2)\tau)^{2(1-\gamma)}} e^{\gamma v} \right) = 0 \tag{16}$$

in $\bar{B}_{R,\lambda}$. We look for a solution of (16) of the form $v(x) = u_1(x) + h(x)$, this amounts to solve

$$\mathbb{L}h := \mathfrak{R}(h) = \frac{8}{(1 + |x|^2)^2} (e^h - h - 1) - \frac{8\varepsilon^{4(1-\gamma)}}{((1 + \varepsilon^2)\tau)^{2(1-\gamma)} (1 + |x|^2)^{2\gamma}} e^{\gamma h + \lambda |\nabla(u_1 + h)|^2} \tag{17}$$

In $\bar{B}_{R,\lambda}$. We will need the following:

Definition 3 Given $\bar{r} \geq 1$, $k \in \infty$, $\beta \in (0, 1)$ and $\mu \in \mathbb{R}$, the weighted space $C_\mu^{k,\beta}(B_{\bar{r}})$ is defined to be the space of functions $w \in C^{k,\beta}(B_{\bar{r}})$ endowed with the norm

$$\|w\|_{C_\mu^{k,\beta}(B_{\bar{r}})} := \|w\|_{C^{k,\beta}(B_1)} + \sup_{1 \leq r \leq \bar{r}} \left(r^{-\mu} \|w(r \cdot)\|_{C^{k,\beta}(\bar{B}_1 - B_{1/2})} \right).$$

For all $\sigma \geq 1$, we denote by $\mathcal{E}_\sigma : C_\mu^{0,\beta}(\bar{B}_\sigma) \rightarrow C_\mu^{0,\beta}(\mathbb{R}^2)$ the extension operator defined by

$$\mathcal{E}_\sigma(f)(x) = \begin{cases} f(x) & \text{for } |x| \leq \sigma \\ \chi \left(\frac{|x|}{\sigma} \right) f \left(\sigma \frac{x}{|x|} \right) & \text{for } |x| \leq \sigma, \end{cases} \tag{18}$$

where $t \alpha \chi(t)$ is a smooth non-negative cutoff function identically equal to 1 for $t \leq 1$ and identically equal to 0 for $t \geq 2$. It is easy to check that there exists a constant $c = c(\mu) > 0$, independent of $\sigma \geq 1$, such that

$$\|\mathcal{E}_\sigma(w)\|_{C_\mu^{0,\beta}(\mathbb{R}^2)} \leq c\|w\|_{C_\mu^{0,\beta}(\bar{B}_\sigma)}. \tag{19}$$

We fix $\delta \in (0, 1)$ and denote by \mathcal{G}_δ to be a right inverse of \mathbb{L}_δ provided by Proposition 1. To find a solution of (17), it is enough to find a fixed point h , in a small ball of $C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)$, solution of

$$h = \mathfrak{N}(h) = \mathcal{G}_\delta \circ \mathcal{E}_\delta \circ \mathfrak{N}(h). \tag{20}$$

We have

$$\mathfrak{N}(0) = \lambda|\nabla u_1|^2 - \frac{8\varepsilon^{4(1-\gamma)}}{((1 + \varepsilon^2)\tau)^{2(1-\gamma)}(1 + |x|^2)^{2\gamma}}.$$

This implies that given $\kappa > 0$, there exist $c_\kappa > 0$ (only depend on κ), such that for $\delta \in (0,1)$ and $|x| = r$, we have

$$\begin{aligned} \sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\delta} |\mathfrak{N}(0)| &\leq \sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\delta} \left(\lambda|\nabla u_1|^2 + \frac{8\varepsilon^{4(1-\gamma)}}{((1 + \varepsilon^2)\tau)^{2(1-\gamma)}(1 + |x|^2)^{2\gamma}} \right) \\ &\leq c_\kappa \left(\lambda + \max\{\varepsilon^{4(1-\gamma)}, \varepsilon^{2+\delta} r_{\varepsilon,\lambda}^{-2-\delta}\} \right). \end{aligned}$$

Making use of Proposition 1 together with (19), we conclude that

$$\|h\|_{C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)} \leq 2c_\kappa r_{\varepsilon,\lambda}^2. \tag{21}$$

Now, let h_1, h_2 such that $\|h_i\| \leq 2c_\kappa r_{\varepsilon,\lambda}^2$ in $C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)$, then for $\delta \in (0, 1 - r]$ we have

$$\begin{aligned} &\sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\delta} |\mathfrak{N}(h_2) - \mathfrak{N}(h_1)| \\ &\leq c_\kappa \sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\delta} (1 + |x|^2)^{-2} |e^{h_2} - e^{h_1} + h_1 - h_2| + c_\kappa \lambda \sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\delta} (|\nabla(u_1 + h_2)|^2 - |\nabla(u_1 + h_1)|^2) \\ &\quad + c_\kappa \sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\delta} (1 + |x|^2)^{-2\gamma} |e^{\gamma h_1} - e^{\gamma h_2}| \\ &\leq c_\kappa \max\{\varepsilon^{4(1-\gamma)}, \varepsilon^{2+\delta} r_{\varepsilon,\lambda}^{-2-\delta}\} \|h_2 - h_1\|_{C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)} + c_\kappa \lambda \|h_2 - h_1\|_{C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)} \\ &\quad + c_\kappa \max\{\varepsilon^{4(1-\gamma)}, \varepsilon^2 r_{\varepsilon,\lambda}^{-2}\} \|h_2 - h_1\|_{C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)}. \end{aligned}$$

Similarly, making use of Proposition 1 together with condition (A_λ) and (19), we conclude that given $\kappa > 0$, there exist $\varepsilon_\kappa > 0$, $\lambda_\kappa > 0$ and $\bar{c}_\kappa > 0$ (only depend on κ) such that

$$\|\mathfrak{N}(h_2) - \mathfrak{N}(h_1)\|_{C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)} \leq \bar{c}_\kappa r_{\varepsilon,\lambda}^2 \|h_2 - h_1\|_{C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)}. \tag{22}$$

Reducing $\lambda_\kappa > 0$ and $\varepsilon_\kappa > 0$ if necessary, we can assume that, $\bar{c}_\kappa r_{\varepsilon,\lambda}^2 \leq \frac{1}{2}$ for all $\lambda \in (0, \lambda_\kappa)$ and $\varepsilon \in (0, \varepsilon_\kappa)$. Then, (21) and (22) are enough to show that $h \mapsto \mathfrak{N}$ is a contraction from $\{h \in C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2) : \|h\|_{C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)} \leq 2c_\kappa r_{\varepsilon,\lambda}^2\}$ into itself and hence has a unique fixed point h in this set. This fixed point is solution of (20) in $\bar{B}_{R_{\varepsilon,\lambda}}$. We summarize this in the:

Proposition 2 Given $\delta \in (0, 1 - \gamma]$ and $\kappa > 1$, then there exist $\bar{c}_\kappa > 0$ (independent of ε and λ) and a unique $h \in C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)$ with $\|h\|_{C_{\text{rad},\delta}^{2,\beta}(\mathbb{R}^2)} \leq 2c_\kappa r_{\varepsilon,\lambda}^2$ such that

$$v(x) = u_1(x) + h(x)$$

solves (16) in $\bar{B}_{R_{\varepsilon,\lambda}}$.

2.2 Analysis of the Laplace operator in weighted spaces

In this section, we study the mapping properties of the Laplace operator in weighted Hölder spaces. Given $x_1, \dots, x_m \in \Omega$, we define $\mathbf{x} := (x_1, \dots, x_m)$

$$\bar{\Omega}^*(\mathbf{x}) := \bar{\Omega} - \{x_1, \dots, x_m\},$$

and we choose $r_0 > 0$ so that the balls $B_{r_0}(x_i)$ of center x_i and radius r_0 are mutually disjoint and included in Ω . For all $r \in (0, r_0)$, we define

$$\bar{\Omega}_r(\mathbf{x}) := \bar{\Omega} - \cup_{i=1}^m B_r(x_i).$$

With these notations, we have:

Definition 4 Given $k \in \mathbb{R}$, $\beta \in (0,1)$ and $v \in \mathbb{R}$, we introduce the Hölder weighted space $C_v^{k,\beta}(\bar{\Omega}^*(\mathbf{x}))$ as the space of functions $w \in C_{\text{loc}}^{k,\beta}(\bar{\Omega}^*(\mathbf{x}))$ for with the following norm

$$\|w\|_{C_v^{k,\beta}(\bar{\Omega}^*(\mathbf{x}))} := \|w\|_{C^{k,\beta}(\bar{\Omega}_{r_0/1})} + \sum_{i=1}^m \sup_{0 < r \leq r_0/2} \left(r^{-v} \|w(x_i + r \cdot)\|_{C^{k,\beta}(\bar{B}_2 - B_1)} \right)$$

is finite.

When $k \geq 2$, we denote by $[C_v^{k,\beta}(\bar{\Omega}^*(\mathbf{x}))]_0$ be the subspace of functions $w \in C_v^{k,\beta}(\bar{\Omega}^*(\mathbf{x}))$ satisfying $w = 0$ on $\partial\Omega$. We recall the

Proposition 3 [21] Assume that $v < 0$ and $v \notin \mathbb{Z}$, then

$$\begin{aligned} \mathcal{L}_v : [C_v^{2,\beta}(\bar{\Omega}^*(\mathbf{x}))]_0 &\rightarrow C_{v-2}^{0,\beta}(\bar{\Omega}^*(\mathbf{x})) \\ w &\mapsto \Delta w \end{aligned}$$

is surjective. Denote by $\tilde{\mathcal{G}}_v$ a right inverse of \mathcal{L}_v .

Remark 1 Observe that, when $v < 0$, $v \notin \mathbb{Z}$, the right inverse even though is not unique and can be chosen to depend smoothly on the points x_1, \dots, x_m at least locally. Once a right inverse is fixed for some choice of the points x_1, \dots, x_m a right inverse which depends smoothly on some points $\tilde{x}_1, \dots, \tilde{x}_m$ close to x_1, \dots, x_m can be obtained using a simple perturbation argument. This argument will be used later in the non-linear exterior problem, since we will move a little bit the points (x_i) .

2.3 Harmonic extensions

We study the properties of interior and exterior harmonic extensions. Given $\varphi \in C^{2,\beta}(S^1)$ and define $H^i (=H^i(\varphi; \cdot))$ to be the solution of

$$\begin{cases} \Delta H^i = 0 & \text{in } B_1 \\ H^i = \varphi & \text{on } \partial B_1 \end{cases} \tag{23}$$

We denote by e_1, e_2 the coordinate functions on S^1 .

Lemma 2 [21] *If we assume that*

$$\int_{S^1} \varphi \, dv_{S^1} = 0 \quad \text{and} \quad \int_{S^1} \varphi e_\ell \, dv_{S^1} = 0 \quad \text{for} \quad \ell = 1, 2 \quad (24)$$

then there exists $c > 0$ such that

$$\|H^i(\varphi; \cdot)\|_{C^{2,\beta}(\bar{B}_1^*)} \leq c \|\varphi\|_{C^{2,\beta}(S^1)}.$$

Given $\tilde{\varphi} \in C^{2,\beta}(S^1)$, we define $H^e (= H^e(\tilde{\varphi}; \cdot))$ to be the solution of

$$\begin{cases} \Delta H^e = 0 & \text{in } \mathbb{R}^2 - B_1 \\ H^e = \tilde{\varphi} & \text{on } \partial B_1 \end{cases} \quad (25)$$

which decays at infinity.

Definition 5 *Given $k \in \mathbb{N}$, $\beta \in (0,1)$ and $\nu \in \mathbb{R}$, we define the space $C_v^{k,\beta}(\mathbb{R}^2 - B_1)$ as the space of functions $w \in C_{loc}^{k,\beta}(\mathbb{R}^2 - B_1)$ for which the following norm*

$$\|w\|_{C_v^{k,\beta}(\mathbb{R}^2 - B_1)} = \sup_{r \geq 1} \left(r^{-\nu} \|w(r \cdot)\|_{C_v^{k,\beta}(\bar{B}_2 - B_1)} \right),$$

is finite.

Lemma 3 [21] *If we assume that*

$$\int_{S^1} \tilde{\varphi} \, dv_{S^1} = 0. \quad (26)$$

Then there exists $c > 0$ such that

$$\|H^e(\tilde{\varphi}; \cdot)\|_{C_{-1}^{2,\beta}(\mathbb{R}^2 - B_1)} \leq c \|\tilde{\varphi}\|_{C^{2,\beta}(S^1)}.$$

If $F \subset L^2(S^1)$ is a space of functions defined on S^1 , we define the space F_\perp to be the subspace of functions F of which are $L^2(S^1)$ -orthogonal to the functions $1, e_1, e_2$. We will need the:

Lemma 4 [21] *The mapping*

$$\begin{array}{ccc} \mathcal{P} : & C^{2,\beta}(S^1)_\perp & \rightarrow & C^{1,\beta}(S^1)_\perp \\ & \psi & \mapsto & \partial_r H^i - \partial_r H^e \end{array}$$

where $H^i (= H^i(\psi; \cdot))$ and $H^e = H^e(\psi; \cdot)$, is an isomorphism.

3 The nonlinear interior problem

We are interested in studying equations of type

$$\Delta w + \lambda |\nabla w|^2 + 2(e^w + e^{\gamma w}) = 0. \quad (27)$$

In $\bar{B}_{R_{\varepsilon,\lambda}}$.

Given $\varphi \in C^{2,\beta}(S^1)$ satisfying (24), we define

$$\mathbf{v} := u_1 + H^i(\varphi, \cdot/R_{\varepsilon,\lambda}) + h.$$

Then, we look for a solution of (27) of the form $w = \mathbf{v} + \nu$ and using the fact that H^i is harmonic, this amounts to solve

$$\begin{aligned} \mathbb{L}v := \mathfrak{S}(v) = & \frac{8}{(1+r^2)^2} e^h \left(e^{H^i(\varphi, \cdot/R_{\varepsilon,\lambda})+v} - v - 1 \right) + \frac{8}{(1+r^2)^2} (e^h - 1) v \\ & + \lambda |\nabla[u_1 + H^i(\varphi, \cdot/R_{\varepsilon,\lambda}) + h + v]|^2 - \lambda |\nabla(u_1 + h)|^2 \\ & + \frac{8\varepsilon^{4(1-\gamma)}}{((1+\varepsilon^2)\tau)^{2(1-\gamma)}(1+|x|^2)^{2\gamma}} e^{\gamma h} \left(e^{\gamma H^i(\varphi, \cdot/R_{\varepsilon,\lambda})+\gamma v} - 1 \right). \end{aligned} \tag{28}$$

We fix $\mu \in (1,2)$ and denote by \mathcal{G}_μ to be a right inverse of \mathbb{L}_μ provided by Proposition 1. To find a solution of (28), it is sufficient to find $v \in \mathcal{C}_\mu^{2,\beta}(\mathbb{R}^2)$ solution of

$$v = \mathcal{G}_\mu \circ \mathcal{E}_\mu \circ \mathfrak{S}(v). \tag{29}$$

We denote by $\mathcal{N}(= \mathcal{N}_{\varepsilon,\tau,\varphi})$, the nonlinear operator appearing on the right-hand side of equation (29).

Given $\kappa > 0$ (whose value will be fixed later on), we further assume that the functions ϕ satisfy

$$\|\phi\|_{\mathcal{C}^{2,\beta}(S^1)} \leq \kappa r_{\varepsilon,\lambda}^2. \tag{30}$$

Then, we have the following result

Lemma 5 *Given $\kappa > 0$. There exist $\varepsilon_\kappa > 0$, $\lambda_\kappa > 0$, $c_\kappa > 0$ and $\bar{c}_\kappa > 0$ (only depend on κ) such that for all $\lambda \in (0, \lambda_\kappa)$ and $\varepsilon \in (0, \varepsilon_\kappa)$*

$$\|\mathcal{N}(0)\|_{\mathcal{C}_\mu^{2,\beta}(B_{R_{\varepsilon,\lambda}})} \leq c_\kappa r_{\varepsilon,\lambda}^2.$$

and

$$\|\mathcal{N}(v_2) - \mathcal{N}(v_1)\|_{\mathcal{C}_\mu^{2,\beta}(B_{R_{\varepsilon,\lambda}})} \leq c_\kappa r_{\varepsilon,\lambda}^2 \|v_2 - v_1\|_{\mathcal{C}_\mu^{2,\beta}(B_{R_{\varepsilon,\lambda}})}$$

provided $v_1, v_2 \in \mathcal{C}_\mu^{2,\beta}(\mathbb{R}^2)$ satisfying $\|v_i\|_{\mathcal{C}_\mu^{2,\beta}(\mathbb{R}^2)} \leq 2c_\kappa r_{\varepsilon,\lambda}^2$.

Proof. The proof of the first estimate follows from the asymptotic behavior of H^i together with the assumption on the norm of boundary data ϕ given by (30). Indeed, let c_κ be a constant depending only on κ (provided ε and λ are chosen small enough) it follows from the estimate of H^i , given by lemma 2, that

$$\|H^i(\cdot/R_{\varepsilon,\lambda})\|_{\mathcal{C}_2^{2,\beta}(\bar{B}_{R_{\varepsilon,\lambda}})} \leq c_\kappa R_{\varepsilon,\lambda}^{-2} \|\phi\|_{\mathcal{C}^{2,\beta}} \leq c_\kappa \varepsilon^2.$$

Since for each $x \in B_{R_{\varepsilon,\lambda}}$, we have

$$|h(x)| \leq c_\kappa r_{\varepsilon,\lambda}^{2+\delta} \varepsilon^{-\delta} \leq \begin{cases} \varepsilon^{(1+\gamma)/2} \rightarrow 0 \text{ as } \varepsilon \text{ tends to } 0, \text{ for } r_{\varepsilon,\lambda} = \sqrt{\varepsilon}, \\ \lambda^{1+\delta/2} \varepsilon^{-\delta} \rightarrow 0 \text{ as } \lambda \text{ tends to } 0 \text{ by } (A_\lambda), \text{ for } r_{\varepsilon,\lambda} = \sqrt{\lambda}, \\ \varepsilon^{2(1-\gamma)} \rightarrow 0 \text{ as } \varepsilon \text{ tends to } 0, \text{ for } r_{\varepsilon,\lambda} = \varepsilon^{2(1-\gamma)-\delta/2}, \end{cases}$$

where $\delta \in (0, 1 - \gamma]$. Then

$$\left\| (1 + |\cdot|^2)^{-2} e^h \left(e^{H^i(\varphi; \cdot/R_{\varepsilon,\lambda})} - 1 \right) \right\|_{\mathcal{C}_{\mu-2}^{0,\beta}(\bar{B}_{R_{\varepsilon,\lambda}})} \leq c_\kappa \varepsilon^2.$$

On the other hand, using the condition (A_λ) , we have

$$\begin{aligned} \lambda \sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\mu} |\nabla[u_1 + H^i(\varphi, \cdot/R_{\varepsilon,\lambda}) + h]|^2 & \leq c_\kappa r_{\varepsilon,\lambda}^2, \\ \lambda \sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\mu} |\nabla[u_1 + h]|^2 & \leq c_\kappa r_{\varepsilon,\lambda}^2. \end{aligned}$$

and

$$\left\| \frac{8\varepsilon^{4(1-\gamma)}}{((1+\varepsilon^2)\tau)^{2(1-\gamma)}(1+|x|^2)^{2\gamma}} e^{\gamma h} \left(e^{\gamma H^i(\varphi, \cdot/R_{\varepsilon,\lambda})} - 1 \right) \right\|_{C_{\mu-2}^{0,\beta}(\bar{B}_{R_{\varepsilon,\lambda}})} \leq c_{\kappa} \varepsilon^2 \varepsilon^{4(1-\gamma)-\mu} \leq c_{\kappa} r_{\varepsilon,\lambda}^2.$$

Making use of Proposition 1 together with (20), we get

$$\|\mathcal{N}(0)\|_{C_{\mu}^{2,\beta}(B_{R_{\varepsilon,\lambda}})} \leq c_{\kappa} r_{\varepsilon,\lambda}^2. \tag{31}$$

In order to derive the second estimate, we use the fact that, for $v_1, v_2 \in C_{\mu}^{2,\beta}(\mathbb{R}^2)$ satisfying $\|v_i\|_{C_{\mu}^{2,\beta}(\mathbb{R}^2)} \leq 2c_{\kappa} r_{\varepsilon,\lambda}^2$ for $i = 1, 2$, $\mu \in (1, 2)$ and the condition (A_{λ}) , then there exist $c_{\kappa} > 0$ (only depend on κ) such that

$$\begin{aligned} & \sup_{r \leq R_{\varepsilon,\lambda}} r^{2-\mu} |\mathfrak{S}(v_2) - \mathfrak{S}(v_1)| \\ & \leq c_{\kappa} r_{\varepsilon,\lambda}^2 \|v_2 - v_1\|_{C_{\mu}^{2,\beta}(\mathbb{R}^2)} + c_{\kappa} \lambda \|v_2 - v_1\|_{C_{\mu}^{2,\beta}(\mathbb{R}^2)} + c_{\kappa} r_{\varepsilon,\lambda}^2 \|v_2 - v_1\|_{C_{\mu}^{2,\beta}(\mathbb{R}^2)}. \end{aligned}$$

Similarly, making use of Proposition 1 together with (19), we conclude that there exists $\bar{c}_{\kappa} > 0$ (only depend on κ) such that

$$\|\mathcal{N}(v_2) - \mathcal{N}(v_1)\|_{C_{\mu}^{2,\beta}(B_{R_{\varepsilon,\lambda}})} \leq \bar{c}_{\kappa} r_{\varepsilon,\lambda}^2 \|v_2 - v_1\|_{C_{\mu}^{2,\beta}(B_{R_{\varepsilon,\lambda}})}. \tag{32}$$

□

Reducing $\lambda_{\kappa} > 0$ and $\varepsilon_{\kappa} > 0$ if necessary, we can assume that, $\bar{c}_{\kappa} r_{\varepsilon,\lambda}^2 \leq \frac{1}{2}$ for all $\lambda \in (0, \lambda_{\kappa})$ and $\varepsilon \in (0, \varepsilon_{\kappa})$. Then, (31) and (32) are enough to show that $v \mapsto \mathcal{N}(v)$ is a contraction from $\{v \in C_{\mu}^{2,\beta}(\mathbb{R}^2) : \|v\|_{C_{\mu}^{2,\beta}(\mathbb{R}^2)} \leq 2c_{\kappa} r_{\varepsilon,\lambda}^2\}$ into itself and hence has a unique fixed point $v(= \bar{v}_{\varepsilon,\tau,\varphi})$ in this set. This fixed point is solution of (20) in \mathbb{R}^2 . We summarize this in the following:

Proposition 4 *Given $\kappa > 0$, there exist $\varepsilon_{\kappa} > 0$, $\lambda_{\kappa} > 0$ and $c_{\kappa} > 0$ (only depending on κ) such that for all $\varepsilon \in (0, \varepsilon_{\kappa})$, $\lambda \in (0, \lambda_{\kappa})$ satisfying (A), for all τ in some fixed compact subset of $[\tau^-, \tau^+] \subset (0, \infty)$ and for a given ϕ satisfying (24)-(30), then there exists a unique $v(= \bar{v}_{\varepsilon,\tau,\varphi})$ solution of (29) such that*

$$w := u_1 + H^i(\varphi, \cdot/R_{\varepsilon,\lambda}) + h + \bar{v}_{\varepsilon,\tau,\varphi}$$

Solve (27) in $\bar{B}_{R_{\varepsilon,\lambda}}$. In addition,

$$\|v\|_{C_{\mu}^{2,\beta}(\mathbb{R}^2)} \leq 2c_{\kappa} r_{\varepsilon,\lambda}^2.$$

Observe that the function $v(= \bar{v}_{\varepsilon,\tau,\varphi})$ being obtained as a fixed point for contraction mappings, it depends continuously on the parameter τ .

4 The nonlinear exterior problem

Recall that $G(\cdot, \tilde{x})$ denote the unique solution of

$$-\Delta G(\cdot, \tilde{x}) = 8\pi \delta_{\tilde{x}}$$

in Ω , with $G(\cdot, \tilde{x}) = 0$ on $\partial\Omega$. In addition, the following decomposition holds

$$G(x, \tilde{x}) = -4 \log|x - \tilde{x}| + H(x, \tilde{x})$$

where $x \mapsto H(x, \tilde{x})$ is a smooth function. Here, we give an estimate of the gradient of $H(x, \tilde{x})$ without proof (see [14], Lemma 2.1), there exists a constant $c > 0$, so that

$$\|\nabla H(\cdot, \tilde{x})\|_\infty \leq c d(\tilde{x}, \partial\Omega)^{-1}.$$

Let $\tilde{\mathbf{x}} := (\tilde{x}_1, \dots, \tilde{x}_m)$ close enough to $\mathbf{x} := (x_1, \dots, x_m)$, $\tilde{\eta} := (\tilde{\eta}^1, \dots, \tilde{\eta}^m) \in \mathbb{R}^m$ close to 0 and $\tilde{\varphi} := (\tilde{\varphi}^1, \dots, \tilde{\varphi}^m) \in (C^{2,\beta}(S^1))^m$ satisfying (26). We define

$$\tilde{\mathbf{v}} := \sum_{i=1}^m (1 + \tilde{\eta}^i) G(\cdot, \tilde{x}_i) + \sum_{i=1}^m \chi_{r_0}(\cdot - \tilde{x}_i) H^e(\tilde{\varphi}^i; (\cdot - \tilde{x}_i)/r_{\varepsilon,\lambda}). \tag{33}$$

where χ_{r_0} is a cutoff function identically equal to 1 in $B_{r_0/2}$ and identically equal to 0 outside B_{r_0} .

We would like to find a solution of

$$\Delta v + \lambda |\nabla v|^2 + \rho^2 (e^v + e^{\gamma v}) = 0 \tag{34}$$

in $\tilde{\Omega}_{r_{\varepsilon,\lambda}}(\tilde{\mathbf{x}}) := \tilde{\Omega} - \cup_{i=1}^m B_{r_{\varepsilon,\lambda}}(\tilde{x}_i)$ which is a perturbation of $\tilde{\mathbf{v}}$. Writing $v = \tilde{\mathbf{v}} + \tilde{v}$. This amounts to solve

$$-\Delta \tilde{v} = \rho^2 (e^{\tilde{\mathbf{v}}+\tilde{v}} + e^{\gamma \tilde{\mathbf{v}}+\gamma \tilde{v}}) + \lambda |\nabla(\tilde{\mathbf{v}} + \tilde{v})|^2 + \Delta \tilde{\mathbf{v}}.$$

We need to define some auxiliary weighted spaces:

Definition 6 Let $\tilde{r} \in (0, r_0/2)$, $k \in \mathbb{R}$, $\beta \in (0, 1)$ and $\nu \in \mathbb{R}$, we define the Hölder weighted space $C_{\nu}^{k,\beta}(\tilde{\Omega}_{\tilde{r}}(\mathbf{x}))$ as the set of functions $w \in C^{k,\beta}(\tilde{\Omega}_{\tilde{r}}(\mathbf{x}))$ for which the following norm

$$\|w\|_{C_{\nu}^{k,\beta}(\tilde{\Omega}_{\tilde{r}}(\mathbf{x}))} := \|w\|_{C^{k,\beta}(\tilde{\Omega}_{r_0/2}(\mathbf{x}))} + \sum_{i=1}^m \sup_{r \in [\tilde{r}, r_0/2]} \left(r^{-\nu} \|w(x_i + r \cdot)\|_{C^{k,\beta}(\tilde{B}_2 - B_1)} \right).$$

is finite

For all $\sigma \in (0, r_0/2)$ and all $Y = (y_1, \dots, y_m) \in \Omega^m$ such that $\|X - Y\| \leq r_0/2$, where $X = (x_1, \dots, x_m)$, we denote by

$$\tilde{\mathcal{E}}_{\sigma,Y} : C_{\nu}^{0,\beta}(\tilde{\Omega}_{\sigma}(Y)) \rightarrow C_{\nu}^{0,\beta}(\tilde{\Omega}^*(Y)),$$

the extension operator defined by $\tilde{\mathcal{E}}_{\sigma,Y}(f) = f$ in $\tilde{\Omega}_{\sigma}(Y)$

$$\tilde{\mathcal{E}}_{\sigma,Y}(f)(y_i + x) = \tilde{\chi} \left(\frac{|x|}{\sigma} \right) f \left(y_i + \sigma \frac{x}{|x|} \right)$$

for each $i = 1, \dots, m$ and $\tilde{\mathcal{E}}_{\sigma,Y}(f) = 0$ in each $B_{\sigma/2}(y_i)$, where $t \mapsto \tilde{\chi}(t)$ is a cutoff function identically equal to 1 for $t \geq 1$ and identically equal to 0 for $t \leq 1/2$. It is easy to check that there exists a constant $c = c(\nu) > 0$ only depending on ν such that

$$\|\tilde{\mathcal{E}}_{\sigma,Y}(w)\|_{C_{\nu}^{0,\beta}(\tilde{\Omega}^*(Y))} \leq c \|w\|_{C_{\nu}^{0,\beta}(\tilde{\Omega}_{\sigma}(Y))}. \tag{35}$$

We fix

$$\nu \in (-1, 0)$$

and denote by $\tilde{\mathcal{G}}_{\nu} : C_{\nu-2}^{0,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}})) \rightarrow C_{\nu}^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))$ a right inverse of Δ provided by Proposition 3 with $\tilde{\Omega}^*(\tilde{\mathbf{x}}) = \tilde{\Omega} - \{\tilde{x}_1, \dots, \tilde{x}_m\}$. Clearly, it is enough to find $\tilde{v} \in C_{\nu}^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))$

solution of

$$\tilde{v} = \tilde{\mathcal{G}}_v \circ \tilde{\mathcal{E}}_{r_{\varepsilon,\lambda}, \tilde{\mathbf{x}}} \left(\rho^2 \left(e^{\tilde{v}+\tilde{v}} + e^{\gamma\tilde{v}+\gamma\tilde{v}} \right) + \lambda |\nabla(\tilde{\mathbf{v}} + \tilde{v})|^2 + \Delta\tilde{\mathbf{v}} \right) = \tilde{\mathcal{G}}_v \circ \tilde{\mathcal{E}}_{r_{\varepsilon,\lambda}, \tilde{\mathbf{x}}} \circ \tilde{\mathfrak{N}}(\tilde{v}). \quad (36)$$

where

$$\tilde{\mathfrak{N}}(\tilde{v}) = \rho^2 \left(e^{\tilde{v}+\tilde{v}} + e^{\gamma\tilde{v}+\gamma\tilde{v}} \right) + \lambda |\nabla(\tilde{\mathbf{v}} + \tilde{v})|^2 + \Delta\tilde{\mathbf{v}}.$$

We denote by $\tilde{\mathcal{N}} (= \tilde{\mathcal{N}}_{\varepsilon, \tilde{\eta}, \tilde{\mathbf{x}}, \tilde{\varphi}})$ the nonlinear operator which appears on the right hand side of Eq.(36). Given $\kappa > 0$ (whose value will be fixed later on), we assume that the points $\tilde{\mathbf{x}} = (\tilde{x}_1, \dots, \tilde{x}_m)$, the functions $\tilde{\varphi} = (\tilde{\varphi}^1, \dots, \tilde{\varphi}^m)$ and the parameters $\tilde{\eta} = (\tilde{\eta}^1, \dots, \tilde{\eta}^m)$ to satisfy

$$|\tilde{x}_i - x_i| \leq \kappa r_{\varepsilon,\lambda}, \quad (37)$$

$$\|\tilde{\varphi}^i\|_{C^{2,\beta}(S^1)} \leq \kappa r_{\varepsilon,\lambda}^2, \quad (38)$$

and

$$|\tilde{\eta}^i| \leq \kappa r_{\varepsilon,\lambda}^2. \quad (39)$$

Then, the following result holds

Lemma 6 *Given $\kappa > 0$, there exist $\varepsilon_{\kappa} > 0$, $\lambda_{\kappa} > 0$, $c_{\kappa} > 0$ and $\bar{c}_{\kappa} > 0$ (depending on κ) such that for all $\varepsilon \in (0, \varepsilon_{\kappa})$, $\lambda \in (0, \lambda_{\kappa})$*

$$\|\tilde{\mathcal{N}}(0)\|_{C_v^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))} \leq c_{\kappa} r_{\varepsilon,\lambda}^2$$

and

$$\|\tilde{\mathcal{N}}(\tilde{v}_2) - \tilde{\mathcal{N}}(\tilde{v}_1)\|_{C_v^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))} \leq c_{\kappa} r_{\varepsilon,\lambda}^2 \|\tilde{v}_2 - \tilde{v}_1\|_{C_v^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))}$$

provided $\tilde{v}_1, \tilde{v}_2 \in C_v^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))$ and satisfy $\|\tilde{v}_i\|_{C_v^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))} \leq 2c_{\kappa} r_{\varepsilon,\lambda}^2$.

Proof: Recall that $\tilde{\mathcal{N}}(\tilde{v}) = \tilde{\mathcal{G}}_v \circ \tilde{\mathfrak{N}}(\tilde{v})$, we will estimate $\tilde{\mathcal{N}}(0)$ in different subregions of $\tilde{\Omega}^*(\tilde{\mathbf{x}})$.

* In $B_{r_0}(\tilde{x}_i)$, we have $\chi_{r_0}(x - \tilde{x}_i) = 1$, $\Delta\tilde{\mathbf{v}} = 0$ and

$$|H^e(\tilde{\varphi}^i; (x - \tilde{x}_i)/r_{\varepsilon,\lambda})| \leq \kappa r_{\varepsilon,\lambda}^3 r^{-1} \quad (40)$$

so that

$$\begin{aligned} |\tilde{\mathfrak{N}}(0)| &\leq c_{\kappa} \varepsilon^2 |x - \tilde{x}_i|^{-4(1+\tilde{\eta}^i)} \prod_{\ell=1, \ell \neq i}^m |x - \tilde{x}_{\ell}|^{-4(1+\tilde{\eta}^{\ell})} \\ &\quad + \varepsilon^2 |x - \tilde{x}_i|^{-4\gamma(1+\tilde{\eta}^i)} \prod_{\ell=1, \ell \neq i}^m |x - \tilde{x}_{\ell}|^{-4\gamma(1+\tilde{\eta}^{\ell})} + \lambda |\nabla\tilde{\mathbf{v}}|^2 \\ &\leq c_{\kappa} \varepsilon^2 r^{-4(1+\tilde{\eta}^i)} + \lambda \left| (1 + \tilde{\eta}^i) r^{-1} + (1 + \tilde{\eta}^i) |\nabla H(x, \tilde{\mathbf{x}})| + |\nabla H^e(\tilde{\varphi}^i; (\cdot - \tilde{x}_i)/r_{\varepsilon,\lambda})| \right|^2 \\ &\leq c_{\kappa} \varepsilon^2 r^{-4(1+\tilde{\eta}^i)} + c_{\kappa} \lambda \left((1 + \tilde{\eta}^i) r^{-1} + (1 + \tilde{\eta}^i) \log r + r_{\varepsilon,\lambda}^2 r^{-2} \right)^2. \end{aligned}$$

Hence, for $\nu \in (-1, 0)$ and for $\tilde{\eta}^i$ small enough, we get

$$\|\tilde{\mathfrak{N}}(0)\|_{C_{\nu-2}^{0,\beta}(\cup_{i=1}^m B_{r_0}(\tilde{x}_i))} \leq \sup_{r_{\varepsilon,\lambda} \leq r \leq r_0/2} r^{2-\nu} |\tilde{\mathfrak{N}}(0)| \leq c_{\kappa} \varepsilon^2 r_{\varepsilon,\lambda}^{-2} + c_{\kappa} \lambda.$$

* In $\Omega - B_{r_0}(\tilde{x}_i)$, we have $\chi_{r_0}(x - \tilde{x}_i) = 1$ and $\Delta \tilde{v} = 0$. Thus

$$|\tilde{\mathfrak{H}}(0)| \leq c_\kappa \varepsilon^2 \prod_{\ell=1}^m e^{(1+\tilde{\eta}^\ell)G(x,\tilde{x}_\ell)} + c_\kappa \lambda \left((1 + \tilde{\eta}^i)r^{-1} + (1 + \tilde{\eta}^i) \log r + r_{\varepsilon,\lambda}^2 r^{-2} \right)^2.$$

So, for $\nu \in (-1, 0)$, we have

$$\|\tilde{\mathfrak{H}}(0)\|_{C_{\nu-2}^{0,\beta}(\Omega - \cup_{i=1}^m B_{r_0}(\tilde{x}_i))} \leq \sup_{r_0 \leq r} r^{2-\nu} |\tilde{\mathfrak{H}}(0)| \leq c_\kappa \varepsilon^2 + c_\kappa \lambda.$$

* In $B_{r_0}(\tilde{x}_i) - B_{r_0/2}(\tilde{x}_i)$, using the estimat (40), then we have

$$\begin{aligned} |\tilde{\mathfrak{H}}(0)| &\leq c_\kappa \varepsilon^2 r^{-4(1+\tilde{\eta}^i)} + c_\kappa \lambda \left((1 + \tilde{\eta}^i)r^{-1} + (1 + \tilde{\eta}^i) \log r + r_{\varepsilon,\lambda}^2 r^{-2} \right)^2 \\ &\quad + \sum_{i=1}^m \|\Delta, \chi_{r_0}(x - \tilde{x}_i)\| |H^\beta(\tilde{\varphi}^i; (x - \tilde{x}_i)/r_{\varepsilon,\lambda})| \\ &\leq c_\kappa (\varepsilon^2 + c_\kappa \lambda \left((1 + \tilde{\eta}^i)r^{-1} + (1 + \tilde{\eta}^i) \log r + r_{\varepsilon,\lambda}^2 r^{-2} \right)^2 + r^{-1} r_{\varepsilon,\lambda}^3), \end{aligned}$$

where

$$[\Delta, \chi_{r_0}]w = \Delta w \chi_{r_0} + w \Delta \chi_{r_0} + 2 \nabla w \cdot \nabla \chi_{r_0}.$$

Then

$$\|\tilde{\mathfrak{H}}(0)\|_{C_{\nu-2}^{0,\beta}(\cup_{i=1}^m (B_{r_0}(\tilde{x}_i) - B_{r_0/2}(\tilde{x}_i)))} \leq \sup_{r_0/2 \leq r \leq r_0} r^{2-\nu} |\tilde{\mathfrak{H}}(0)| \leq c_\kappa r_{\varepsilon,\lambda}^2 + c_\kappa \lambda.$$

So,

$$\|\tilde{\mathfrak{H}}(0)\|_{C_{\nu-2}^{0,\beta}(\cup_{i=1}^m (\Omega - B_{r_0}(\tilde{x}_i)))} \leq c_\kappa r_{\varepsilon,\lambda}^2. \tag{41}$$

Making use of Proposition 3 together with (34), we conclude that

$$\|\tilde{\mathcal{N}}(0)\|_{C_v^{2,\beta}(\tilde{\Omega}^*(\mathbf{x}))} \leq c_\kappa r_{\varepsilon,\lambda}^2 \tag{42}$$

For the proof of the second estimate, let \tilde{v}_1 and $\tilde{v}_2 \in C_v^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))$ satisfying $\|\tilde{v}_i\|_{C_\mu^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))} \leq 2c_\kappa r_{\varepsilon,\lambda}^2$ for $i = 1, 2$, we have

$$|\tilde{\mathfrak{H}}(\tilde{v}_2) - \tilde{\mathfrak{H}}(\tilde{v}_1)| \leq c_\kappa \varepsilon^2 e^{\tilde{v}} |e^{\tilde{v}_2} - e^{\tilde{v}_1}| + c_\kappa \varepsilon^2 e^{\gamma \tilde{v}} |e^{\gamma \tilde{v}_2} - e^{\gamma \tilde{v}_1}| + \lambda \left| |\nabla(\tilde{v} + \tilde{v}_2)|^2 - |\nabla(\tilde{v} + \tilde{v}_1)|^2 \right|.$$

Then for $\gamma \in (0, 1)$, we get

$$\begin{aligned} \left| \tilde{\mathfrak{H}}(\tilde{v}_2) - \tilde{\mathfrak{H}}(\tilde{v}_1) \right| &\leq c_\kappa \varepsilon^2 |x - x_i|^{-4(1+\tilde{\eta}^i)} |\tilde{v}_2 - \tilde{v}_1| + c_\kappa \lambda |\nabla(\tilde{v}_2 - \tilde{v}_1)| (|\nabla(\tilde{v}_2 + \tilde{v}_1)| + 2|\nabla \tilde{v}|) \\ &\leq c_\kappa \varepsilon^2 r^{-4(1+\tilde{\eta}^i)} |\tilde{v}_2 - \tilde{v}_1| + c_\kappa \lambda |\nabla(\tilde{v}_2 - \tilde{v}_1)| (|\nabla(\tilde{v}_2 + \tilde{v}_1)| + 2|\nabla \tilde{v}|). \end{aligned}$$

So, for $\tilde{\eta}^i$ small enough and using the estimate (35), there exist \bar{c}_κ (depending on κ), such that:

$$\|\tilde{\mathcal{N}}(\tilde{v}_2) - \tilde{\mathcal{N}}(\tilde{v}_1)\|_{C_v^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))} \leq c_\kappa r_{\varepsilon,\lambda}^2 \|\tilde{v}_2 - \tilde{v}_1\|_{C_v^{2,\beta}(\tilde{\Omega}^*(\tilde{\mathbf{x}}))}. \tag{43}$$

□

Reducing $\lambda_\kappa > 0$ and $\varepsilon_\kappa > 0$ if necessary, we can assume that, $\bar{c}_\kappa r_{\varepsilon,\lambda}^2 \leq \frac{1}{2}$ for all $\lambda \in (0, \lambda_\kappa)$ and $\varepsilon \in (0, \varepsilon_\kappa)$. Then, (42) and (43) are enough to show that $\tilde{v} \mapsto \tilde{\mathcal{N}}(\tilde{v})$ is a contraction from $\{\tilde{v} \in C_v^{2,\beta}(\mathbb{R}^2) : \|\tilde{v}\|_{C_v^{2,\beta}(\mathbb{R}^2)} \leq 2c_\kappa r_{\varepsilon,\lambda}^2\}$ into itself and hence has a

unique fixed point $\tilde{v}(= \bar{v}_{\varepsilon, \tau, \varphi})$ in this set. This fixed point is solution of (35). We summarize this in the following

Proposition 5 *Given $\kappa > 0$, there exists $\varepsilon_\kappa > 0$ and $\lambda_\kappa > 0$ (depending on κ) such that for all $\varepsilon \in (0, \varepsilon_\kappa)$ and $\lambda \in (0, \lambda_\kappa)$, for all set of parameter $\tilde{\eta}^i$ satisfying (39) and function $\tilde{\varphi}$ satisfying (26), there exists a unique $\tilde{v}(= \tilde{v}_{\varepsilon, \tilde{\eta}, \tilde{x}, \tilde{\varphi}})$ solution of (36) such that*

$$\|\tilde{v}\|_{C_v^{2,\beta}(\bar{\Omega}^*(\mathbf{x}))} \leq 2\bar{c}_\kappa r_{\varepsilon,\lambda}^2.$$

As in the previous section, observe that the function $\tilde{v}(= \tilde{v}_{\varepsilon, \tilde{\eta}, \tilde{x}, \tilde{\varphi}})$ being obtained as a fixed point for contraction mapping, depends smoothly on the parameters $\tilde{\eta}$ and the points $\tilde{\mathbf{x}}$.

5 The nonlinear Cauchy-data matching

Keeping the notations of the previous sections, we gather the results of Proposition 4 and 5. Assume that $\tilde{\mathbf{x}} := (\tilde{x}_1, \dots, \tilde{x}_m) \in \Omega^m \subset \Omega^m$ are given close to $\mathbf{x} := (x_1, \dots, x_m)$ and satisfy (37). Assume also that $\tau := (\tau_1, \dots, \tau_m) \in [\tau_-, \tau_+]^m \subset (0, \infty)^m$ are given (the values of τ_- and τ_+ will be fixed shortly). First, we consider some set of boundary data $\varphi := (\varphi^1, \dots, \varphi^m) \in (C^{2,\beta}(S^1))^m$ satisfying (24). We set

$$R_{\varepsilon,\lambda}^i = \tau_i r_{\varepsilon,\lambda} / \varepsilon.$$

According to the result of Proposition 4, we can find v_{int}^i a solution of

$$\Delta v + \lambda |\nabla v|^2 + \rho^2 (e^v + e^{\gamma v}) = 0 \tag{44}$$

in each $B_{r_{\varepsilon,\lambda}}(\tilde{x}_i)$ that can be decomposed as

$$v_{int}^i(x) = v_{\varepsilon, \tau_i}(x - \tilde{x}_i) + h(R_{\varepsilon,\lambda}^i(x - \tilde{x}_i)/r_{\varepsilon,\lambda}) + H^i(\varphi^i; (x - \tilde{x}_i)/r_{\varepsilon,\lambda}) + \tilde{v}_{\varepsilon, \tau_i, \varphi^i}(R_{\varepsilon,\lambda}^i(x - \tilde{x}_i)/r_{\varepsilon,\lambda}),$$

where the function $v^i = \tilde{v}_{\varepsilon, \tau_i, \varphi^i}$ satisfies

$$\|v^i\|_{C_\mu^{2,\beta}(\mathbb{R}^2)} \leq 2c_\kappa r_{\varepsilon,\lambda}^2. \tag{45}$$

Similarly, given some boundary data $\tilde{\varphi} = (\tilde{\varphi}^1, \dots, \tilde{\varphi}^m) \in (C^{2,\beta}(S^1))^m$ satisfying (26), some parameters $\tilde{\eta} := (\tilde{\eta}^1, \dots, \tilde{\eta}^m) \in \mathbb{R}^m$ satisfying (38), provide $\varepsilon \in (0, \varepsilon_\kappa)$ and $\lambda \in (0, \lambda_\kappa)$, we use the result of Proposition 5, to find a solution v_{ext} of (43) which can be decomposed as

$$v_{ext} = \sum_{i=1}^m (1 + \tilde{\eta}^i) G(\cdot, \tilde{x}_i) + \sum_{i=1}^m \chi_{r_0}(\cdot - \tilde{x}_i) H^e(\tilde{\varphi}^i; (\cdot - \tilde{x}_i)/r_{\varepsilon,\lambda}) + \tilde{v}_{\varepsilon, \tilde{\eta}, \tilde{x}, \tilde{\varphi}}$$

in $\bar{\Omega}_{r_{\varepsilon,\lambda}}$ where, the function $\tilde{v}(= \tilde{v}_{\varepsilon, \tilde{\eta}, \tilde{x}, \tilde{\varphi}}) \in C_v^{2,\beta}(\bar{\Omega}^*(\tilde{\mathbf{x}}))$ satisfies

$$\|\tilde{v}\|_{C_v^{2,\beta}(\bar{\Omega}^*(\tilde{\mathbf{x}}))} \leq 2c_\kappa r_{\varepsilon,\lambda}^2. \tag{46}$$

It remains to determine the parameters and the functions in such a way that the function which is equal to v_{int}^i in $\cup_{i=1}^m B_{r_{\varepsilon,\lambda}}(\tilde{x}_i)$ and that is equal to v_{ext} in $\bar{\Omega}_{r_{\varepsilon,\lambda}}(\tilde{\mathbf{x}})$ is a smooth function. This amounts to find the boundary data and the parameters so that, for each $i = 1 \dots, m$

$$v_{int}^i = v_{ext} \quad \text{and} \quad \partial_r v_{int}^i = \partial_r v_{ext}, \tag{47}$$

on $\partial B_{r_{\varepsilon,\lambda}}(\tilde{x}_i)$. Assuming we have already done so, this provides for each ε and λ small enough a function $v_{\varepsilon,\lambda} \in C^{2,\beta}$ (which is obtained by patching together the functions v_{int}^i and the function v_{ext}) solution of $-\Delta v - \lambda |\nabla v|^2 = \rho^2 (e^v + e^{\rho v})$ and elliptic regularity theory implies that this solution is in fact smooth. This will complete the proof of our result since, as ε and λ tend to 0, the sequence of solutions we have obtained satisfies the required properties, namely, away from the points x_i the sequence $v_{\varepsilon,\lambda}$ converges to $\sum_i G(\cdot, x_i)$. Before we proceed, the following remarks are due. First, it will be convenient to observe that the function v_{ε,τ_i} can be expanded as

$$v_{\varepsilon,\tau_i}(x) = -2 \log \tau_i - 4 \log |x| + \mathcal{O}\left(\frac{\varepsilon^2 \tau_i^{-2}}{|x|^2}\right) \tag{48}$$

near $\partial B_{r_{\varepsilon,\lambda}}$. The function

$$\sum_{\ell=1}^m (1 + \tilde{\eta}^\ell) G(x, \tilde{x}_\ell)$$

which appear in the expression of v_{ext} can be expanded as

$$\sum_{\ell=1}^m (1 + \tilde{\eta}^\ell) G(x + \tilde{x}_i, \tilde{x}_\ell) = -4(1 + \tilde{\eta}^i) \log |x| + \mathcal{F}_i(\tilde{\mathbf{x}}; \tilde{x}_i) + \nabla \mathcal{F}_i(\tilde{\mathbf{x}}; \tilde{x}_i) \cdot x + \mathcal{O}(r_{\varepsilon,\lambda}^2) \tag{49}$$

Near $\partial B_{r_{\varepsilon,\lambda}}(\tilde{x}_i)$. Here, we have defined

$$\mathcal{F}_i(\tilde{\mathbf{x}}; \cdot) := H(\tilde{x}_i, \cdot) + \sum_{\ell \neq i} G(\tilde{x}_\ell, \cdot).$$

Thus for x near $\partial B_{r_{\varepsilon,\lambda}}$ we have

$$\begin{aligned} (v_{\text{int}}^i - v_{\text{ext}})(x) &= -2 \log \tau_i + 4\tilde{\eta}^i \log |x - \tilde{x}_i| + h(R_{\varepsilon,\lambda}^i(x - \tilde{x}_i)/r_{\varepsilon,\lambda}) \\ &\quad + H^i(\varphi^i; (x - \tilde{x}_i)/r_{\varepsilon,\lambda}) - H^e(\tilde{\varphi}^i; (x - \tilde{x}_i)/r_{\varepsilon,\lambda}) \\ &\quad - \left((1 + \tilde{\eta}^i)H(x, \tilde{x}_i) + \sum_{\ell=1, \ell \neq i}^m (1 + \tilde{\eta}^\ell)G(x, \tilde{x}_\ell) \right) + \mathcal{O}\left(\frac{\varepsilon^2 \tau_i^{-2}}{|x - \tilde{x}_i|^2}\right) + \mathcal{O}(r_{\varepsilon,\lambda}^2) \\ &= -2 \log \tau_i + 4\tilde{\eta}^i \log |x| - \left((1 + \tilde{\eta}^i)H(\tilde{x}_i, \tilde{x}_i) + \sum_{\ell=1, \ell \neq i}^m (1 + \tilde{\eta}^\ell)G(\tilde{x}_i, \tilde{x}_\ell) \right) \\ &\quad + \mathcal{O}(|x - \tilde{x}_i|^2) + \mathcal{O}\left(\frac{\varepsilon^2 \tau_i^{-2}}{|x - \tilde{x}_i|^2}\right) + \mathcal{O}(r_{\varepsilon,\lambda}^2) \\ &= -2 \log \tau_i + 4\tilde{\eta}^i \log r_{\varepsilon,\lambda} - \mathcal{F}_i(\tilde{\mathbf{x}}_i, \tilde{x}) + \mathcal{O}(\varepsilon) + \mathcal{O}(r_{\varepsilon,\lambda}^2) \\ &= -2 \log \tau_i + 4\tilde{\eta}^i \log r_{\varepsilon,\lambda} - \mathcal{F}_i(\tilde{\mathbf{x}}_i, \tilde{x}) + \mathcal{O}(r_{\varepsilon,\lambda}^2) \end{aligned} \tag{50}$$

where $\tilde{\mathbf{x}} = (\tilde{x}_1, \dots, \tilde{x}_m)$.

Next, in (47), all functions are defined on $\partial B_{r_{\varepsilon,\lambda}}(\tilde{x}_i)$, but it will be convenient to solve the following equations

$$(v_{\text{int}}^i - v_{\text{ext}})(\tilde{x}_i + r_{\varepsilon,\lambda} \cdot) = 0 \quad \text{and} \quad \partial_r((v_{\text{int}}^i - v_{\text{ext}})(\tilde{x}_i + r_{\varepsilon,\lambda} \cdot)) = 0 \tag{51}$$

on S^1 . Here, all functions are considered as functions of $y \in S^1$ and we have simply used the change of variables $x = \tilde{x}_i + r_{\varepsilon,\lambda} y$ to parameterize $\partial B_{r_{\varepsilon,\lambda}}(\tilde{x}_i)$.

Since the boundary data, we have chosen satisfy (24) and (26), we can decompose

$$\varphi^i = \varphi_0^i + \varphi_1^i + \varphi^{i,\perp} \quad \text{and} \quad \tilde{\varphi}^i = \tilde{\varphi}_0^i + \tilde{\varphi}_1^i + \tilde{\varphi}^{i,\perp}$$

where $\varphi_0^i, \tilde{\varphi}_0^i \in \mathbb{E}_0 = \mathbb{R}$ are constant functions on S^1 , $\varphi_1^i, \tilde{\varphi}_1^i$ belong to $\mathbb{E}_1 = \ker(\Delta_{S^1} + 1) = \text{Span}\{e_1, e_2\}$ and where $\varphi^{i,\perp}, \tilde{\varphi}^{i,\perp}$ are $L^2(S^1)$ orthogonal to \mathbb{E}_0 and \mathbb{E}_1 . Projecting the equations (51) over \mathbb{E}_0 will yield the system

$$\begin{cases} -2 \log \tau_i + 4\tilde{\eta}^i \log r_{\varepsilon,\lambda} - \mathcal{F}_i(\tilde{x}_i, \tilde{\mathbf{x}}) + \mathcal{O}(r_{\varepsilon,\lambda}^2) = 0 \\ 4\tilde{\eta}^i + \mathcal{O}(r_{\varepsilon,\lambda}^2) = 0. \end{cases} \quad (52)$$

Let us comment briefly on how these equations are obtained. They simply come from (51) when expansions (48) and (49) are used, together with the expression of H^i and H^e given in Lemma 2 and Lemma 3, and also the estimates (45) and (46). The system (52) can be readily simplified into

$$\frac{1}{\log r_{\varepsilon,\lambda}} [2 \log \tau_i + \mathcal{F}_i(\tilde{x}_i, \tilde{\mathbf{x}})] = \mathcal{O}(r_{\varepsilon,\lambda}^2) \quad \text{and} \quad \tilde{\eta}^i = \mathcal{O}(r_{\varepsilon,\lambda}^2).$$

We are now in a position to define τ_- and τ_+ since, according to the above, as ε and λ tend to 0 we expect that \tilde{x}_i will converge to x_i and that τ_i will converge to τ_i^* satisfying

$$2 \log \tau_i^* = -\mathcal{F}_i(x_i, \mathbf{x})$$

and hence, it is enough to choose τ_- and τ_+ in such a way that

$$2 \log(\tau_-) < -\sup_i \mathcal{F}_i(x_i, \mathbf{x}) \leq -\inf_i \mathcal{F}_i(x_i, \mathbf{x}) < 2 \log(\tau_+).$$

We now consider the L^2 -projection of (51) over \mathbb{E}_1 . Given a smooth function f defined in Ω , we identify its gradient $\nabla f = (\partial_{x_1} f, \partial_{x_2} f)$ with the element of \mathbb{E}_1

$$\bar{\nabla} f = \sum_{i=1}^2 \partial_{x_i} f e_i.$$

With these notations in mind, we obtain the equations

$$\bar{\nabla} \mathcal{F}_i(\tilde{x}_i, \tilde{\mathbf{x}}) = \mathcal{O}(r_{\varepsilon,\lambda}^2) \quad \text{and} \quad \varphi_1^i = \mathcal{O}(r_{\varepsilon,\lambda}^2) \quad (53)$$

Finally, we consider the L^2 -projection onto $L^2(S^1)^\perp$. This yields the system

$$\begin{cases} \varphi^{i,\perp} - \tilde{\varphi}^{i,\perp} + \mathcal{O}(r_{\varepsilon,\lambda}^2) = 0 \\ \partial_r(H^{i,\perp} - H^{e,\perp}) + \mathcal{O}(r_{\varepsilon,\lambda}^2) = 0. \end{cases} \quad (54)$$

Thanks to the result of Lemma 4, this last system can be re-written as

$$\varphi^{i,\perp} = \mathcal{O}(r_{\varepsilon,\lambda}^2) \quad \text{and} \quad \tilde{\varphi}^{i,\perp} = \mathcal{O}(r_{\varepsilon,\lambda}^2).$$

If we define the parameters $\mathbf{t} = (t_i) \in \mathbb{R}^m$ by

$$t_i = \frac{1}{\log r_{\varepsilon,\lambda}} [2 \log \tau_i + \mathcal{F}_i(\tilde{x}_i, \tilde{\mathbf{x}})], \quad \text{for } i = 1, \dots, m$$

then, the system we have to solve reads

$$(\mathbf{t}, \tilde{\eta}, \varphi_0, \tilde{\varphi}_0, \varphi_1, \tilde{\varphi}_1, \bar{\nabla} \mathcal{F}(\tilde{\mathbf{x}}, \mathbf{x}), \varphi^\perp, \tilde{\varphi}^\perp) = \mathcal{O}(r_{\varepsilon,\lambda}^2), \quad (55)$$

where as usual, the terms $\mathcal{O}(r_{\varepsilon,\lambda}^2)$ depend nonlinearly on all the variables on the left side, but is bounded (in the appropriate norm) by a constant (independent of ε and λ) time $r_{\varepsilon,\lambda}^2$, provide $\varepsilon \in (0, \varepsilon_\kappa)$ and $\lambda \in (0, \lambda_\kappa)$. Then, the nonlinear mapping which appears on the right-hand side of (55) is continuous and compact. In addition, reducing ε_κ and λ_κ if necessary, this nonlinear mapping sends the ball of radius $\kappa r_{\varepsilon,\lambda}^2$ (for

the natural product norm) into itself, provided κ is fixed large enough. Applying Schauder's fixed Theorem in the ball of radius $\kappa r_{\varepsilon, \lambda}^2$ in the product space where the entries live yields the existence of a solution of Eq. (55) and this completes the proof of our Theorem 1. \square

Acknowledgements

The authors extend their appreciation to the Deanship of Scientific Research at King Saud University for funding the work through the research group project No RGP-VPP-087.

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Authors' contribution

The authors declare that the work was realized in collaboration with same responsibility. All authors read and approved the final manuscript.

Competing interests

The authors declare that they have no competing interests.

Received: 22 March 2011 Accepted: 12 August 2011 Published: 12 August 2011

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doi:10.1186/1687-2770-2011-10

Cite this article as: Baraket et al.: Singular limiting solutions for elliptic problem involving exponentially dominated nonlinearity and convection term. *Boundary Value Problems* 2011 **2011**:10.