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Upper Hölder continuity of parametric vector optimization problems

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available at the end of the article**Abstract**

This paper is concerned with upper Hölder continuity and Hölder calmness of a perturbed vector optimization problem. We establish some new sufficient conditions for upper Hölder continuity and Hölder calmness of the perturbed solution mappings and the perturbed optimal value mappings of a vector optimization problem under the case that the objective function and the feasible set are, respectively, perturbed by parameters. Our results generalize and extend the corresponding ones of Li and Li (Appl. Math. Comput. 232:908-918, 2014).

MSC: 49K30; 90C29**Keywords:** vector optimization problem; solution mapping; optimal value mapping; Hölder continuity; Hölder calmness**1 Introduction**

The quantitative analysis of various optimal value mappings and optimal solution mappings for optimization problems is an interesting and important topic in optimization theories and applications. In general, it is understood as the optimal value mappings or optimal solution mappings possess some geometric properties, such as Hölder continuity, Lipschitz continuity, calmness, differentiability and sub-differentiability, and so on. It has implications in model formulation, optimality characterizations, approximation theory (especially for infinite dimensional problems), and in particular for numerical procedures. Thus, it is necessary to obtain some results for various optimal value mappings or various optimal solution mappings of optimization problems from a quantitative viewpoint. Up to now, there have been many papers to discuss Hölder continuity of solution mappings to perturbed variational inequalities or perturbed equilibrium problems; see [2–9] and the references therein.

However, there are a few papers to study this topic for perturbed optimization problems; see [1, 10, 11] and the references therein. Bonnans and Shapiro [10] have used the growth conditions for real-valued mappings to consider a perturbed scalar optimization problem. They have derived upper Hölder continuity of the optimal solution mapping and the differentiability of the optimal value mapping. Bednarczuk [11] generalized the main results of [10] to the vector-valued mapping. Recently, Li and Li [1] introduced the strong convexity of the objective functions to derive Hölder continuity of the optimal solution mapping of a perturbed vector optimization problem. The main assumptions and proof

techniques are very different from [10, 11]. However, there are many examples to show that the strong convexity of the objective functions of perturbed optimization problem is very strict. Thus, it is necessary to investigate Hölder continuity of the optimal solution mapping or the optimal value mapping for perturbed optimization problems.

In this paper, we introduce a new strong domination property, which is different from the corresponding ones in the related paper, for an unperturbed vector optimization problem. Based on this property and the Hölder-related assumptions, we establish the sufficient conditions for upper Hölder continuity and Hölder calmness of the various solution mappings and the optimal value mappings to a vector optimization problem under the case that the objective function and the feasible set are, respectively, perturbed by parameters. Comparing our results of this paper with the corresponding ones of [1], we can easily see that our results are not included in [1], and generalize and extend the corresponding ones of [1].

The rest of the paper is organized as follows. In Section 2, we first recall some definitions and their properties which are needed in the sequel. In Section 3, we discuss the upper Hölder continuity and Hölder calmness of the optimal solution mapping and the weak optimal solution mapping for a vector optimization problem. In Section 4, we further discuss the upper Hölder continuity of the optimal value mapping and the weak optimal value mapping for a vector optimization problem.

2 Preliminaries

Throughout this paper, we assume that $Y := (Y, \|\cdot\|)$ is a normed space partially ordered by a point, closed and convex cone $C \subset Y$, which has a nonempty interior, denoted by $\text{int } C$. Let D be a nonempty subset of Y . A point $y \in D$ is called an efficient point if $(D - y) \cap (-C) = \{0\}$ and a weak efficient point if $(D - y) \cap (-\text{int } C) = \emptyset$. We denote by $E(D)$ and $WE(D)$ the set of all efficient points and the set of all weak efficient points of D , respectively.

Let $X := (X, \|\cdot\|)$, $\Lambda := (\Lambda, \|\cdot\|)$ and $M := (M, \|\cdot\|)$ be normed spaces. We consider the perturbed vector optimization problem of form

$$(VOP_{\lambda,\mu}) \quad C - \min f(x, \lambda) \text{ subject to } x \in \Phi(\mu), \tag{2.1}$$

depending on the parameters $\lambda \in \Lambda$ and $\mu \in M$, and $f : X \times \Lambda \rightarrow Y$ is a vector-valued mapping and $\Phi : M \rightarrow 2^X$ is a set-valued mapping with nonempty values.

For a given point $(\lambda_0, \mu_0) \in \Lambda \times M$, we view the corresponding problem (VOP_{λ_0,μ_0}) as an unperturbed problem, and we identify the unperturbed problem (VOP_{λ_0,μ_0}) with the problem (VOP) considered in the classical vector optimization theories and applications. That is, we use $f(\cdot) \equiv f(\cdot, \lambda_0)$ and $\Phi \equiv \Phi(\mu_0)$ and rewrite the unperturbed problem in the form

$$(VOP) \quad C - \min f(x) \text{ subject to } x \in \Phi. \tag{2.2}$$

For any $(\lambda, \mu) \in \Lambda \times M$, the optimal value mapping and weak optimal value mapping for problem (2.1) are, respectively, defined by

$$V(\lambda, \mu) := E(f(\Phi(\mu), \lambda)) \quad \text{and} \quad WV(\lambda, \mu) := WE(f(\Phi(\mu), \lambda)).$$

Then the solution mapping and weak solution mapping for problem (2.1) are, respectively, defined as

$$S(\lambda, \mu) := \{x \in \Phi(\mu) : f(x, \lambda) \in V(\lambda, \mu)\} \quad \text{and}$$

$$WS(\lambda, \mu) := \{x \in \Phi(\mu) : f(x, \lambda) \in WV(\lambda, \mu)\}.$$

For the convenience, we will use the abbreviated notations V , WV , S , and WS to denote the optimal value mapping, the weak optimal value mapping, the solution mapping and the weak solution mapping for problem (2.2), respectively.

In this paper, we mainly study the behavior of the (weak) optimal value mapping and (weak) solution mapping for (2.1) when (λ, μ) varies around the given point (λ_0, μ_0) . Moreover, precisely speaking, we will discuss upper Hölder continuity of $V(\cdot)$, $WV(\cdot)$, $S(\cdot)$, $WS(\cdot)$ as set-valued mappings at (λ, μ) .

For any nonempty subsets A, B of normed space, $d(x, B) =: \inf_{b \in B} \|x - b\|$ and $e(A, B) = \sup_{a \in A} d(a, B)$. Let $G : M \rightrightarrows X$ be a set-valued mapping. The graph and domain of G are, respectively, defined in the usual way as

$$\text{graph } G := \{(\mu, x) \in M \times X \mid x \in G(\mu)\} \quad \text{and} \quad \text{dom } G := \{\mu \in M \mid G(\mu) \neq \emptyset\}.$$

Definition 2.1 (i) G is said to be Hölder of order $\alpha > 0$ around $\mu_0 \in \text{dom } G$ with constants $k_G > 0, t_G > 0$ if and only if for any $\mu, \mu' \in \mu_0 + t_G \mathbb{B}_M$,

$$e(G(\mu), G(\mu')) \leq k_G \|\mu - \mu'\|^\alpha;$$

(ii) G is said to be upper Hölder of order $\alpha > 0$ around $\mu_0 \in \text{dom } G$ with constants $k_G > 0, t_G > 0$ if and only if for any $\mu \in \mu_0 + t_G \mathbb{B}_M$,

$$e(G(\mu), G(\mu_0)) \leq k_G \|\mu - \mu_0\|^\alpha;$$

(iii) G is said to be lower Hölder of order $\alpha > 0$ around $\mu_0 \in \text{dom } G$ with constants $k_G > 0, t_G > 0$ if and only if for any $\mu, \mu' \in \mu_0 + t_G \mathbb{B}_M$,

$$e(G(\mu_0), G(\mu)) \leq k_G \|\mu - \mu_0\|^\alpha;$$

(iv) G is said to be pseudo-Hölder of order $\alpha > 0$ at $(\mu_0, x_0) \in \text{graph } G$ with constants $k_G > 0, t_G > 0$ if and only if there exists a neighborhood W of zero in X such that, for any $\mu, \mu' \in \mu_0 + t_G \mathbb{B}_M$,

$$e(G(\mu) \cap (x_0 + W), G(\mu')) \leq k_G \|\mu - \mu'\|^\alpha;$$

(v) G is said to be Hölder calm or upper pseudo-Hölder of order $\alpha > 0$ at $(\mu_0, x_0) \in \text{graph } G$ with constants $k_G > 0, t_G > 0$ if and only if there exists a neighborhood W of zero in X such that, for any $\mu, \mu' \in \mu_0 + t_G \mathbb{B}_M$,

$$e(G(\mu) \cap (x_0 + W), G(\mu_0)) \leq k_G \|\mu - \mu_0\|^\alpha;$$

(vi) G is said to be lower pseudo-Hölder of order $\alpha > 0$ at $(\mu_0, x_0) \in \text{graph } G$ with constants $k_G > 0, t_G > 0$ if and only if there exists a neighborhood W of zero in X such that, for any $\mu \in \mu_0 + t_G \mathbb{B}_M$,

$$e(G(\mu_0) \cap (x_0 + W), G(\mu)) \leq k_G \|\mu - \mu_0\|^\alpha.$$

From Definition 2.1, we have the following relations:

$$\begin{aligned} (i) \Rightarrow (ii) \Rightarrow (v), & \quad (i) \Rightarrow (iv) \Rightarrow (v), \\ (i) \Rightarrow (iv) \Rightarrow (vi), & \quad (i) \Rightarrow (iii) \Rightarrow (vi). \end{aligned}$$

The set-valued mapping $G(\cdot)$ is Lipschitz (resp. upper Lipschitz, lower Lipschitz) around $\mu_0 \in \text{dom } G$ if $G(\cdot)$ is Hölder (resp. upper Hölder, lower Hölder) of order $\alpha = 1$ around $\mu_0 \in \text{dom } G$; the set-valued mapping $G(\cdot)$ is pseudo-Lipschitz (resp. upper pseudo-Lipschitz, lower pseudo-Lipschitz) at $(\mu_0, x_0) \in \text{graph } G$ if $G(\cdot)$ is pseudo-Hölder (resp. upper pseudo-Hölder, lower pseudo-Hölder) of order $\alpha = 1$ at $(\mu_0, x_0) \in \text{graph } G$. Pseudo-Lipschitzness and upper pseudo-Lipschitzness are also called the Aubin property and calmness, respectively. The role of Lipschitzness and its variants in optimization is widely recognized; see [10] and the references therein.

Definition 2.2 A vector-valued mapping $g : M \rightarrow X$ is Hölder of order $\alpha > 0$ around $\mu_0 \in M$ with constants $k_g, t_g > 0$ if and only if for any $\mu, \mu' \in \mu_0 + t_g \mathbb{B}_M$,

$$\|g(\mu) - g(\mu')\| \leq k_g \|\mu - \mu'\|^\alpha.$$

Let D be a subset of Y . Luc [12] introduced the domination property (for short, DP) for D :

$$D \subset E(D) + C.$$

Then the domination property (DP) for problem (VOP) can be similarly defined by

$$f(\Phi) \subset f(S) + C,$$

that is, for each $x \in \Phi$, there exists $x_0 \in S$ such that

$$f(x) - f(x_0) \in C.$$

Motivated by the above property, we introduce the following concepts for problem (VOP) to discuss Hölder continuity of the perturbed solution mapping and perturbed optimal value mapping of $(\text{VOP}_{\lambda, \mu})$.

Definition 2.3 (i) The strong global domination property (for short, SGDP) holds on S (resp. WS) of order $\alpha > 0$ with constant $h_s > 0$ for (VOP) if and only if for each $x \in \Phi$, there exists $x_0 \in S$ (resp. WS) such that

$$f(x) - f(x_0) + h_s \|x - x_0\|^\alpha \mathbb{B}_Y \subset C. \tag{2.3}$$

(ii) The strong local domination property (for short, SLDP) holds around $x_0 \in W$ (resp. WS) of order $\alpha > 0$ with constant $h_s > 0$ for (VOP) if and only if there exists a neighborhood U of x_0 such that, for each $x \in \Phi \cap U$, there exists $x_0 \in S \cap U$ (resp. $WS \cap U$) satisfies (2.3).

Remark 2.1 (i) For any $y \in Y$, let $\|y\|_+ := d(y, Y \setminus C)$. Then equation (2.3) becomes

$$h_s \|x - x_0\|^\alpha \leq \|f(x) - f(x_0)\|_+.$$

(ii) The concepts of Definition 2.3 are mainly to establish Hölder-type continuity of problem (VOP), which was discussed by Li and Li [1]. In [1], they mainly introduced the strong convexity of the objective function in (VOP) to investigate this topic. However, the assumption on strong convexity of the objective function is very strict. In many cases, the strong global (local) domination property for (VOP) holds but the strong convexity of the objective function fails as the following example shows.

Example 2.1 Let $X = \mathbb{R}$, $Y = \mathbb{R}^2$, $C = \mathbb{R}_+^2$, $\Phi = [-1, 1]$, and $f : X \rightarrow Y$ is $f(x) = (x, x)$. We can easily see that f is not strongly convex on Φ ; the solution sets $S = WS = [-1, 0]$. Hence, for any $x \in \Phi$, there exist a constant $h_s = \frac{\sqrt{2}}{2}$ and $x_0 = 0 \in S = WS$ such that

$$f(x) - f(x_0) + \frac{\sqrt{2}}{2} \|x - x_0\| \mathbb{B}_Y \subset C.$$

That is, the strong global domination property for (VOP) on S (resp. WS) holds.

3 Upper Hölder continuity of the solution mappings for (VOP $_{\lambda, \mu}$)

In this section, we mainly discuss upper Hölder behavior of the perturbed (weak) solution mapping for problem (2.1) where both the objective function f and the feasible set Φ are perturbed by different parameters. Namely, this section is devoted to derive the upper bounds for the distance from the perturbed (weak) solution mapping of (2.1) to the (weak) solution mapping for problem (2.2).

Theorem 3.1 For problem (2.1), assume that the solutions exist in a neighborhood of considered point $(\lambda_0, \mu_0) \in \text{dom } S$. Moreover, assume that the following conditions are satisfied:

- (i) the set-valued mapping $\Phi : M \rightrightarrows X$ is Hölder of order $\alpha > 0$ around $\mu_0 \in \text{dom } \Phi$ with constants $h_\Phi > 0$, $t_\Phi > 0$;
- (ii) the strong global domination property (SGDP) of order $\beta \geq 1$ for (VOP) holds on S with a constant $l_s > 0$;
- (iii) for any $\lambda \in \Lambda$, $f(\cdot, \lambda)$ is Hölder of order $\gamma > 0$ on X with constant $m_f > 0$ as well as for any $x \in X$, $f(x, \cdot)$ is Hölder of order $\delta > 0$ around λ_0 with constants $n_f > 0$, $t_f > 0$.

Then $S : \Lambda \times M \rightrightarrows X$ is upper Hölder around $(\lambda_0, \mu_0) \in \text{dom } S$ with constants $t_f > 0$, $t_\Phi > 0$, that is, for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda$, $\mu \in \mu_0 + t_\Phi \mathbb{B}_M$,

$$e(S(\lambda, \mu), S) \leq h_\Phi \|\mu - \mu_0\|^\alpha + \left(\frac{2m_f h_\Phi^\gamma}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha\gamma}{\beta}} + \left(\frac{2n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}}. \tag{3.1}$$

Proof Take any $x(\lambda, \mu) \in S(\lambda, \mu)$, for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda$, $\mu \in \mu_0 + t_\Phi \mathbb{B}_M$. By the definition of $S(\lambda, \mu)$, we have

$$x(\lambda, \mu) \in \Phi(\mu) \quad \text{and} \quad f(x, \lambda) - f(x(\lambda, \mu), \lambda) \notin -C \setminus \{0\} \quad \text{for any } x \in \Phi(\mu). \tag{3.2}$$

Then it follows from (i) that there exists $x(\mu_0) \in \Phi(\mu_0)$ such that

$$\|x(\lambda, \mu) - x(\mu_0)\| \leq h_\Phi \|\mu - \mu_0\|^\alpha. \tag{3.3}$$

By the strong domination property, for $x(\mu_0)$, there exists $x(\lambda_0, \mu_0) \in S$ such that

$$f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0) + l_s \|x(\mu_0) - x(\lambda_0, \mu_0)\|^\beta \mathbb{B}_Y \subset C. \tag{3.4}$$

The conclusion (3.1) is trivial whether $x(\mu_0) = x(\lambda_0, \mu_0)$ or $f(x(\mu_0), \lambda_0) = f(x(\lambda_0, \mu_0), \lambda_0)$. Therefore, $x(\mu_0) \neq x(\lambda_0, \mu_0)$ and $f(x(\mu_0), \lambda_0) \neq f(x(\lambda_0, \mu_0), \lambda_0)$ are always assumed in the sequel. Clearly, $x(\lambda_0, \mu_0) \in \Phi(\mu_0)$. By (i), there exists $x(\mu) \in \Phi(\mu)$ such that

$$\|x(\lambda_0, \mu_0) - x(\mu)\| \leq h_\Phi \|\mu - \mu_0\|^\alpha. \tag{3.5}$$

Then we have

$$f(x(\mu), \lambda) - f(x(\lambda, \mu), \lambda) = f(x(\lambda_0, \mu_0), \lambda_0) - f(x(\mu_0), \lambda_0) + w, \tag{3.6}$$

where

$$w := [f(x(\mu), \lambda) - f(x(\lambda_0, \mu_0), \lambda)] + [f(x(\lambda_0, \mu_0), \lambda) - f(x(\lambda_0, \mu_0), \lambda_0)] \\ + [f(x(\mu_0), \lambda_0) - f(x(\mu_0), \lambda)] + [f(x(\mu_0), \lambda) - f(x(\lambda, \mu), \lambda)].$$

Then it follows from (iii) that

$$\|w\| \leq m_f \|x(\mu) - x(\lambda_0, \mu_0)\|^\gamma + m_f \|x(\mu_0) - x(\lambda, \mu)\|^\gamma + 2n_f \|\lambda - \lambda_0\|^\delta,$$

which together with (3.3) and (3.5) yields

$$\|w\| \leq 2m_f h_\Phi^\gamma \|\mu - \mu_0\|^{\alpha\gamma} + 2n_f \|\lambda - \lambda_0\|^\delta. \tag{3.7}$$

We claim that

$$\|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\|_+ \leq \|w\|. \tag{3.8}$$

Indeed, suppose to the contrary that $\|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\|_+ > \|w\|$. Then, by the definition of $\|\cdot\|_+$,

$$f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0) + \|w\| \mathbb{B}_Y \subset \text{int } C. \tag{3.9}$$

If $\|w\| = 0$, then $w = 0$. By (3.4) and (3.6), we have

$$f(x(\mu), \lambda) - f(x(\lambda, \mu), \lambda) \in -\text{int } C,$$

which contradicts (3.2). If $\|w\| \neq 0$, then, by $-\frac{w}{\|w\|} \in \mathbb{B}_Y$ and (3.9),

$$f(x(\lambda, \mu), \lambda) - f(x(\mu), \lambda) = f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0) + \|w\| \left(-\frac{w}{\|w\|}\right) \in \text{int } C,$$

which also contradicts (3.2).

Therefore, combining (3.4), (3.7), (3.8), and (3.9), we have

$$\begin{aligned}
 l_s \|x(\mu_0) - x(\lambda_0, \mu_0)\|^\beta &\leq \|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\|_+ \\
 &\leq 2m_f h_\Phi^\gamma \|\mu - \mu_0\|^{\alpha\gamma} + 2n_f \|\lambda - \lambda_0\|^\delta.
 \end{aligned}$$

So

$$\begin{aligned}
 \|x(\mu_0) - x(\lambda_0, \mu_0)\| &\leq \sqrt[\beta]{\frac{2m_f h_\Phi^\gamma \|\mu - \mu_0\|^{\alpha\gamma}}{l_s} \|\mu - \mu_0\|^{\alpha\gamma} + \frac{2n_f}{l_s} \|\lambda - \lambda_0\|^\delta} \\
 &\leq \left(\frac{2m_f h_\Phi^\gamma}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha\gamma}{\beta}} + \left(\frac{2n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}}, \tag{3.10}
 \end{aligned}$$

where the last inequality holds as $\beta \geq 1$.

Finally, from (3.2) and (3.10) it follows that

$$\begin{aligned}
 d(x(\lambda, \mu), S) &\leq \|x(\lambda, \mu) - x(\lambda_0, \mu_0)\| \leq \|x(\lambda, \mu) - x(\mu_0)\| + \|x(\mu_0) - x(\lambda_0, \mu_0)\| \\
 &\leq h_\Phi \|\mu - \mu_0\|^\alpha + \left(\frac{2m_f h_\Phi^\gamma}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha\gamma}{\beta}} + \left(\frac{2n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}},
 \end{aligned}$$

which means that the conclusion (3.1) holds and the proof is complete. □

Theorem 3.2 *For problem (2.1), assume that the weak solutions exist in a neighborhood of considered point $(\lambda_0, \mu_0) \in \text{dom WS}$. Furthermore, assume that all conditions of Theorem 3.1 are satisfied except that (ii) is replaced by*

- (ii') *the strong global domination property (SGDP) of order $\beta \geq 1$ for (VOP) holds on WS with a constant $l_s > 0$.*

Then $WS : \Lambda \times M \rightrightarrows X$ is upper Hölder around $(\lambda_0, \mu_0) \in \text{dom WS}$ with constants $t_f > 0$, $t_\Phi > 0$, that is, for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda$, $\mu \in \mu_0 + t_\Phi \mathbb{B}_M$,

$$e(WS(\lambda, \mu), WS) \leq h_\Phi \|\mu - \mu_0\|^\alpha + \left(\frac{2m_f h_\Phi^\gamma}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha\gamma}{\beta}} + \left(\frac{2n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}}.$$

Proof The proof is similar to Theorem 3.1 and is omitted here. □

Theorem 3.3 *For problem (2.1), assume that the solutions exist in a neighborhood of considered point $(\lambda_0, \mu_0) \in \text{dom S}$. Let $x_0 \in S$. Furthermore, assume that the following conditions are satisfied:*

- (i) *the set-valued mapping $\Phi : M \rightrightarrows X$ is Hölder calm and lower pseudo-Hölder of order $\alpha > 0$ around $(\mu_0, x_0) \in \text{graph } \Phi$ with a neighborhood V of zero in X , and constants $h_\Phi > 0$, $c_\Phi > 0$;*
- (ii) *the strong local domination property (SLDP) of order $\beta \geq 1$ holds for (VOP) around x_0 with a neighborhood Q of zero in X , $Q + Q \subset V$, and a constant $l_s > 0$;*
- (iii) *for any $x \in x_0 + V$, $f(x, \cdot)$ is Hölder of order $\delta > 0$ around λ_0 with constants $n_f > 0$, $t_f > 0$ as well as for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda$, $f(\cdot, \lambda)$ is Hölder of order $\gamma > 0$ with a neighborhood V of zero in X , and a constant $m_f > 0$.*

Then $S : \Lambda \times M \rightrightarrows X$ is Hölder calm around $((\lambda_0, \mu_0), x_0) \in \text{graph } S$ with constants $t_f > 0$, $t_\Phi > 0$. Precisely, there exists a neighborhood W of zero in X such that for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda$, $\mu \in \mu_0 + t_\Phi \mathbb{B}_M$,

$$\begin{aligned}
 & e(S(\lambda, \mu) \cap (x_0 + W), S) \\
 & \leq h_\Phi \|\mu - \mu_0\|^\alpha + \left(\frac{2m_f h'_\Phi}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha\gamma}{\beta}} + \left(\frac{2n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}}. \tag{3.11}
 \end{aligned}$$

Proof Let W be any neighborhood of zero in X such that

$$W + h_\Phi t_\Phi \mathbb{B}_X \subset Q.$$

Then W is the desired neighborhood of zero in X . Indeed, take any $x(\lambda, \mu) \in S(\lambda, \mu) \cap (x_0 + W)$, for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda$, $\mu \in \mu_0 + t_\Phi \mathbb{B}_M$. By the Hölder calmness of Φ , there exists $x(\mu_0) \in \Phi(\mu_0)$ such that

$$\|x(\lambda, \mu) - x(\mu_0)\| \leq h_\Phi \|\mu - \mu_0\|^\alpha \leq h_\Phi t_\Phi^\alpha. \tag{3.12}$$

Then we have

$$x(\mu_0) - x_0 = x(\mu_0) - x(\lambda, \mu) + x(\lambda, \mu) - x_0 \in h_\Phi t_\Phi^\alpha \mathbb{B}_X + W \subset Q.$$

For $x(\mu_0) \in \Phi(\mu_0) \cap (x_0 + Q)$, by (ii), there exists $x(\lambda_0, \mu_0) \in S \cap (x_0 + Q)$ such that

$$f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0) + l \|x(\mu_0) - x(\lambda_0, \mu_0)\|^\beta \mathbb{B}_Y \subset C. \tag{3.13}$$

Without loss of generality, we assume that $x(\mu_0) \neq x(\lambda_0, \mu_0)$ and $f(x(\mu_0), \lambda_0) \neq f(x(\lambda_0, \mu_0), \lambda_0)$. Otherwise, the conclusion (3.11) is trivial. Obviously, $x(\lambda_0, \mu_0) \in \Phi(\mu_0) \cap (x_0 + Q)$. By the lower-pseudo Hölder property of Φ , there exists $x(\mu) \in \Phi(\mu)$ such that

$$\|x(\lambda_0, \mu_0) - x(\mu)\| \leq h_\Phi \|\mu - \mu_0\|^\alpha \leq h_\Phi t_\Phi^\alpha. \tag{3.14}$$

So, we have

$$x(\mu_0) - x_0 = x(\mu_0) - x(\lambda_0, \mu_0) + x(\lambda_0, \mu_0) - x_0 \in h_\Phi t_\Phi^\alpha \mathbb{B}_X + W \subset Q \subset V$$

and

$$f(x(\mu), \lambda) - f(x(\lambda, \mu), \lambda) = f(x(\lambda_0, \mu_0), \lambda_0) - f(x(\mu_0), \lambda_0) + w,$$

where

$$\begin{aligned}
 w := & [f(x(\mu), \lambda) - f(x(\lambda_0, \mu_0), \lambda)] + [f(x(\lambda_0, \mu_0), \lambda) - f(x(\lambda_0, \mu_0), \lambda_0)] \\
 & + [f(x(\mu_0), \lambda_0) - f(x(\mu_0), \lambda)] + [f(x(\mu_0), \lambda) - f(x(\lambda, \mu), \lambda)].
 \end{aligned}$$

Then, by (iii), we have

$$\|w\| \leq m_f \|x(\mu) - x(\lambda_0, \mu_0)\|^\gamma + m_f \|x(\mu_0) - x(\lambda, \mu)\|^\gamma + 2n_f \|\lambda - \lambda_0\|^\delta,$$

which together with (3.12) and (3.14) yields

$$\|w\| \leq 2m_f h_\Phi^\gamma \|\mu - \mu_0\|^{\alpha\gamma} + 2n_f \|\lambda - \lambda_0\|^\delta. \tag{3.15}$$

By the same arguments as in the proof of Theorem 3.1, we have

$$\|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\|_+ \leq \|w\|. \tag{3.16}$$

Therefore, (3.13), (3.15), and (3.16) together yield

$$l_s \|x(\mu_0) - x(\lambda_0, \mu_0)\|^\beta \leq 2m_f h_\Phi^\gamma \|\mu - \mu_0\|^{\alpha\gamma} + 2n_f \|\lambda - \lambda_0\|^\delta.$$

So, we have

$$\|x(\mu_0) - x(\lambda_0, \mu_0)\| \leq \left(\frac{2m_f h_\Phi^\gamma}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha\gamma}{\beta}} + \left(\frac{2n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}}. \tag{3.17}$$

Finally, from (3.12) and (3.17) it follows that

$$d(x(\lambda, \mu), S) \leq h_\Phi \|\mu - \mu_0\|^\alpha + \left(\frac{2m_f h_\Phi^\gamma}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha\gamma}{\beta}} + \left(\frac{2n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}},$$

which means that the conclusion (3.11) holds and the proof is complete. □

Theorem 3.4 *For problem (2.1), assume that the weak solutions exist in a neighborhood of considered point $(\lambda_0, \mu_0) \in \text{dom } WS$. Let $x_0 \in WS$. Furthermore, assume that the following conditions of Theorem 3.2 are satisfied. Then $WS : \Lambda \times M \rightrightarrows X$ is Hölder calm around $((\lambda_0, \mu_0), x_0) \in \text{graph } WS$ with constants $t_f > 0$, $t_\Phi > 0$, that is, there exists a neighborhood W of zero in X such that for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda$, $\mu \in \mu_0 + t_\Phi \mathbb{B}_M$,*

$$\begin{aligned} & e(WS(\lambda, \mu) \cap (x_0 + W), WS) \\ & \leq h_\Phi \|\mu - \mu_0\|^\alpha + \left(\frac{2m_f h_\Phi^\gamma}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha\gamma}{\beta}} + \left(\frac{2n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}}. \end{aligned}$$

Proof The proof is similar to Theorem 3.3 and is omitted here. □

4 Upper Hölder of the optimal value mappings for $(VOP_{\lambda, \mu})$

This section is devoted to an investigation of the Hölder behavior of the perturbed optimal value mappings for problem (2.1).

Theorem 4.1 *Assume that all conditions of Theorem 3.1 are satisfied. Moreover, assume that $\gamma = 1$ in Theorem 3.1. Then $V : \Lambda \times M \rightrightarrows X$ is upper Hölder around $(\lambda_0, \mu_0) \in \text{dom } S$*

with constants $t_f > 0, t_\Phi > 0$. Precisely, for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda, \mu \in \mu_0 + t_\Phi \mathbb{B}_M$,

$$e(V(\lambda, \mu), V) \leq m_f h_\Phi \|\mu - \mu_0\|^\alpha + n_f \|\lambda - \lambda_0\|^\delta + \left(\frac{2m_f^2 h_\Phi}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^{\frac{\alpha}{\beta}} + \left(\frac{2m_f n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^{\frac{\delta}{\beta}}.$$

Moreover, if $\beta = 1$, then

$$e(V(\lambda, \mu), V) \leq \frac{(2m_f + l_s)m_f h_\Phi}{l_s} \|\mu - \mu_0\|^\alpha + \frac{(2m_f + l_s)n_f}{l_s} \|\lambda - \lambda_0\|^\delta.$$

Proof Take any $f(x(\lambda, \mu), \lambda) \in V(\lambda, \mu)$, for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda, \mu \in \mu_0 + t_\Phi \mathbb{B}_M$. Then $x(\lambda, \mu) \in \Phi(\mu)$ and there exists $x(\mu_0) \in \Phi(\mu_0)$ such that

$$\|x(\lambda, \mu) - x(\mu_0)\| \leq h_\Phi \|\mu - \mu_0\|^\alpha. \tag{4.1}$$

Then it follows from (ii) that, for $x(\mu_0)$, there exists $x(\lambda_0, \mu_0) \in S$ such that

$$f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0) + l_s \|x(\mu_0) - x(\lambda_0, \mu_0)\|^\beta \mathbb{B}_Y \subset C.$$

So, the Lipschitzness of $f(\cdot, \lambda_0)$ implies that

$$f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0) + \frac{l_s}{m_f} \|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\|^\beta \mathbb{B}_Y \subset C. \tag{4.2}$$

Clearly, $x(\lambda_0, \mu_0) \in \Phi(\mu_0)$. Then, by (i), there exists $x(\mu) \in \Phi(\mu)$ such that

$$\|x(\lambda_0, \mu_0) - x(\mu)\| \leq h_\Phi \|\mu - \mu_0\|^\alpha. \tag{4.3}$$

Obviously, we have

$$f(x(\mu), \lambda) - f(x(\lambda, \mu), \lambda) = f(x(\lambda_0, \mu_0), \lambda_0) - f(x(\mu_0), \lambda_0) + w,$$

where

$$w := [f(x(\mu), \lambda) - f(x(\lambda_0, \mu_0), \lambda)] + [f(x(\lambda_0, \mu_0), \lambda) - f(x(\lambda_0, \mu_0), \lambda_0)] + [f(x(\mu_0), \lambda_0) - f(x(\mu_0), \lambda)] + [f(x(\mu_0), \lambda) - f(x(\lambda, \mu), \lambda)].$$

Then it follows from (iii) that

$$\|w\| \leq m_f \|x(\mu) - x(\lambda_0, \mu_0)\| + m_f \|x(\mu_0) - x(\lambda, \mu)\| + 2n_f \|\lambda - \lambda_0\|^\delta,$$

which together with (4.1) and (4.3) yields

$$\|w\| \leq 2m_f h_\Phi \|\mu - \mu_0\|^\alpha + 2n_f \|\lambda - \lambda_0\|^\delta. \tag{4.4}$$

By the same arguments as in the proof of Theorem 3.1, we have

$$\|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\|_+ \leq \|w\|. \tag{4.5}$$

Thus, (4.2), (4.4), and (4.5) together yield

$$\frac{l_s}{m_f} \|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\|^\beta \leq 2m_f h_\Phi \|\mu - \mu_0\|^\alpha + 2n_f \|\lambda - \lambda_0\|^\delta.$$

So, we have

$$\begin{aligned} & \|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\| \\ & \leq \left(\frac{2m_f^2 h_\Phi}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^\frac{\alpha}{\beta} + \left(\frac{2m_f n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^\frac{\delta}{\beta}. \end{aligned} \tag{4.6}$$

Finally, from (4.1) and (4.6) it follows that

$$\begin{aligned} & d(f(x(\lambda, \mu), \lambda), V) \\ & \leq \|f(x(\lambda, \mu), \lambda) - f(x(\lambda_0, \mu_0), \lambda_0)\| \\ & \leq \|f(x(\lambda, \mu), \lambda) - f(x(\mu_0), \lambda)\| + \|f(x(\mu_0), \lambda) - f(x(\lambda_0, \mu_0), \lambda_0)\| \\ & \quad + \|f(x(\mu_0), \lambda_0) - f(x(\lambda_0, \mu_0), \lambda_0)\| \\ & \leq m_f h_\Phi \|\mu - \mu_0\|^\alpha + n_f \|\lambda - \lambda_0\|^\delta + \left(\frac{2m_f^2 h_\Phi}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^\frac{\alpha}{\beta} \\ & \quad + \left(\frac{2m_f n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^\frac{\delta}{\beta}. \end{aligned}$$

The proof is complete. □

Theorem 4.2 *Assume that all conditions of Theorem 3.2 are satisfied. Moreover, assume that $\gamma = 1$ in Theorem 3.2. Then $WV : \Lambda \times M \rightrightarrows X$ is upper Hölder around $(\lambda_0, \mu_0) \in \text{dom } WS$ with constants $t_f > 0, t_\Phi > 0$. Precisely, for any $\lambda \in \lambda_0 + t_f \mathbb{B}_\Lambda, \mu \in \mu_0 + t_\Phi \mathbb{B}_M$,*

$$\begin{aligned} e(WV(\lambda, \mu), WV) & \leq m_f h_\Phi \|\mu - \mu_0\|^\alpha + n_f \|\lambda - \lambda_0\|^\delta + \left(\frac{2m_f^2 h_\Phi}{l_s}\right)^{\frac{1}{\beta}} \|\mu - \mu_0\|^\frac{\alpha}{\beta} \\ & \quad + \left(\frac{2m_f n_f}{l_s}\right)^{\frac{1}{\beta}} \|\lambda - \lambda_0\|^\frac{\delta}{\beta}. \end{aligned}$$

Moreover, if $\beta = 1$, then

$$e(WV(\lambda, \mu), WV) \leq \frac{(2m_f + l_s)m_f h_\Phi}{l_s} \|\mu - \mu_0\|^\alpha + \frac{(2m_f + l_s)n_f}{l_s} \|\lambda - \lambda_0\|^\delta.$$

Proof The proof is similar to Theorem 4.1 and is omitted here. □

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

The authors contributed equally and significantly in writing this paper. All authors read and approved the final manuscript.

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Acknowledgements

Xian-Fu Hu would like to thank Dr. Xue for his hospitality during his stay from July 2016 to August 2016 at College of Mathematics and Statistics of the Nanyang Normal University in China.

Received: 23 September 2016 Accepted: 8 November 2016 Published online: 29 November 2016

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