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# RESEARCH

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# An asymptotic property of the Camassa-Holm equation on the half-line

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# Abstract

The paper addresses the asymptotic properties of Camassa-Holm equation on the half-line. That is, using the method of asymptotic density, under the assumption that it is unique, the paper proves that the positive momentum density of the Camassa-Holm equation is a combination of Dirac measures supported on the positive axis. This means that as time goes to infinity, the momentum density concentrates in small intervals moving right with different constant speeds.

MSC: 35Q53; 37K40

**Keywords:** Camassa-Holm equation; asymptotic density; momentum density; asymptotic property; Dirac measures

### 1 Introduction

In this paper we consider the following initial boundary value problem of the Camassa-Holm equation on the half line:

$$\begin{cases} u_t - u_{txx} + 3uu_x = 2u_x u_{xx} + uu_{xxx}, & t > 0, x \in \mathbb{R}_+, \\ u(0, x) = u_0(x), & x \in \mathbb{R}_+, \\ u_x^{(2k)}(t, 0) = u_x^{(2k-2)}(t, 0) = \dots = u(t, 0) = 0, & t \ge 0, \end{cases}$$
(1.1)

where  $u_0^{(2k)}(0) = u_0^{(2k-2)}(0) = \cdots = u_0(0)$ . Let  $h = u - u_{xx}$  be the momentum density. The Camassa-Holm equation on the half line in momentum density form is

$$\begin{cases} h_t + uh_x + 2u_x h = 0, \quad t > 0, x \in \mathbb{R}_+, \\ h(t,x) = (1 - \partial_x^2)u(t,x), \quad t > 0, x \in \mathbb{R}_+, \\ h(x,0) = h_0(x) = (1 - \partial_x^2)u_0, \quad x \in \mathbb{R}_+, \\ \partial_x^{2k-2}h(t,0) = \dots = \partial_x^2h(t,0) = h(t,0) = 0, \quad t \ge 0. \end{cases}$$
(1.2)

The Camassa-Holm equation is a model for the unidirectional propagation of shallow water waves over a flat bottom. It has a bi-Hamiltonian structure [1] and is completely integrable [2, 3]. Its solitary waves are peaked [4]. The convergence of the solution of the Camassa-Holm equation to the distributional solution of the Burgers one and the solution of the dispersive equation converging to the unique entropy solution of a scalar conservation law are proven [5, 6]. In [4], numerical studies illustrate that some nonnegative initial condition evolves into a train of peakons moving with different velocities. On the



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theoretical side of the topic, there is research on the stability of peakons, which says that at least for initial values close to peakons, it will stay close to the peakons. The shapes of peakons and multipeakon/antipeakons are stable under small perturbations, making them recognizable physically [7–9]. Constantin and Strauss [7] proved the stability of a single peakon among  $C([0; T]; H^1(R))$  solutions. El Dika and Molinet proved the stability of multi-peakons [8] and multi-anti-peakons-peakons [9] among a slightly more regular class of solutions.

In this article, we use the method of asymptotic density of the momentum to show that under the assumption of its uniqueness, at the momentum level, the solution approaches a train of peakons moving right with different speeds. This approach was introduced by Chen and Frid [10] to study the asymptotic behavior of the entropy solutions of conservation laws. It has been used to discuss the asymptotic behavior of the vorticity of the two dimensional incompressible Euler equation by Iftimie, Lopes, and Nussenzveig [11, 12]. Reference [13] is an exposition. Notice that the vorticity in the incompressible Euler equations and the momentum density in the Camassa-Holm equation are similar. They satisfy similar first order nonlinear nonlocal equations and give the velocity through similar integrals. There are also differences. The 2D Euler flow preserves volume and the vorticity is transported along the particle trajectories, but the same do not hold for the Camassa-Holm flow and its momentum density. We have studied the asymptotic property for a global strong solutions of the Camassa-Holm equation by the approach in [14], and the asymptotic property of the solutions of the Degasperis-Procesi equation is studied [15]. Results on the half-line may not automatically follow those on the whole line. For example, if the momentum density is non-positive, the solution on  $\mathbb{R}$  approaches a left moving peakon train whereas on  $\mathbb{R}_+$ , solutions with non-positive initial momentum densities must blow up in finite time (see [16]) and we cannot discuss their asymptotic properties. New, we proceed to a study of the momentum density of the Camassa-Holm equation on the half line.

In this paper, we will investigate initial boundary value problems of the Camassa-Holm equation with initial data  $u_0 \in H^s(\mathbb{R}_+) \cap H_0^1(\mathbb{R}_+)$ ,  $s > \frac{5}{2}$ , where  $\mathbb{R}_+ = [0, \infty)$ . Let  $k \in \mathbb{N} \setminus \{0\}$ , and for  $2k + \frac{1}{2} < s \leq 2k + 2$ , we set

 $G^{s}(\mathbb{R}_{+}) = \left\{ u \in H^{s}(\mathbb{R}_{+}) \mid u^{(2k)}(0) = u^{(2k-2)}(0) = \cdots = u(0) \right\}.$ 

**Theorem 1.1** ([16], Theorem 2.2) Let  $u_0 \in G^s(\mathbb{R}_+)$ , with  $k \in \mathbb{N} \setminus \{0\}$ , and  $2k + \frac{1}{2} < s \le 2k + 2$ . Assume that  $h_0(x) := u_0(x) - u_{0,xx}(x) \ge 0$  for all  $x \in \mathbb{R}_+$ . Then there exists a global solution u(t, x) to (1.1) such that, for all T > 0,

$$u = u(\cdot, u_0) \in C([0, T); G^{s}(\mathbb{R}_+)) \cap C^1([0, T); G^{s-1}(\mathbb{R}_+)).$$

Moreover, the solution depends continuously on the initial data, i.e., the mapping  $u_0 \mapsto u(\cdot, u_0) : G^s(\mathbb{R}_+) \longrightarrow C([0, T); G^s(\mathbb{R}_+)) \cap C^1([0, T); G^{s-1}(\mathbb{R}_+))$  is continuous.

**Definition 1.2** Let *u* be a global solution of (1.1), and the initial momentum density  $h_0 \ge 0$  is compactly supported. For t > 0, let

$$\tilde{h}(t,y) := th(t,ty) \tag{1.3}$$

be the scaled momentum density of u.

**Definition 1.3** Let  $[a,b] \subset \mathbb{R}_+$  be a finite interval, and  $\operatorname{supp} \tilde{h}(t,\cdot) \subset [a,b]$  for all  $t \ge 1$ . Suppose there is a sequence  $t_k \to \infty$  as  $k \to \infty$ , and a positive Radon measure  $\mu \in \mathcal{M}[a,b]$  such that

$$h(t_k, \cdot) \rightarrow \mu$$
, as  $k \rightarrow \infty$ .

Then we call  $\mu$  an *asymptotic density associated* with the initial momentum density  $h_0$ .

## Remark 1.4

- (a)  $\mathcal{M}[a, b]$  is the space of regular Borel measures on [a, b].
- (b) The convergence is the weak-\* convergence in  $\mathcal{M}[a, b]$ , *i.e.* for all  $\psi \in C[a, b]$ ,  $\int_{a}^{b} \tilde{h}(t, y)\psi(y) dy \rightarrow \langle \mu, \psi \rangle$ .
- (c) The asymptotic densities associated with  $h_0$  may not be unique.

The following is the main result of this article.

**Theorem 1.5** Let u be a global solution of (1.1), and  $h_0(\cdot) = h(0, \cdot) \ge 0$  has compact support. For  $t \ge 0$ , suppose that  $\tilde{h}(t, \cdot)$  has a unique asymptotic density  $\mu$  associated with  $h_0$ . Then there exist finitely or countably infinitely many  $m_i, \alpha_i \in [0, \infty)$  such that

$$\mu = \sum_{i=1}^{\infty} m_i \delta_{\alpha_i},\tag{1.4}$$

where  $\delta_{\alpha_i}$  is the delta function supported at  $\alpha_i$ , and

- (a)  $\alpha_i \leq \frac{3}{2}m_i$ , for all *i*.
- (b)  $\alpha_i \in [0, M)$ , for any *i*, where  $M = ||u||_{L^{\infty}(\mathbb{R}_+ \times \mathbb{R}_+)}$ .
- (c)  $\alpha_i \to 0$  as  $i \to \infty$  and  $\alpha_i \neq \alpha_j$  if  $i \neq j$ .
- (d)  $m_i > 0$  and  $\sum_{i=1}^{\infty} m_i = ||h_0||_{L^1(\mathbb{R}_+)}$ .

In other words, the momentum densities of such global solutions concentrates in slumps moving right approaching different speeds.

#### 2 Preliminaries

Consider the following differential equation:

$$\begin{cases} \frac{dq(t,x)}{dt} = u(t,q(t,x)), \quad t > 0, x \in \mathbb{R}_+, \\ q(0,x) = x, \quad x \in \mathbb{R}_+. \end{cases}$$

$$(2.1)$$

Applying classical results in the theory of ordinary differential equations, one can obtain the following results on q.

**Lemma 2.1** Let  $u \in C([0, T); G^{s}(\mathbb{R}_{+})) \cap C^{1}([0, T); G^{s-1}(\mathbb{R}_{+}))$  be a nonnegative solution of (1.1) for all T > 0, Then the (2.1) has a unique solution  $q \in C^{1}([0, T) \times \mathbb{R}_{+}, \mathbb{R}_{+})$ . Moreover, the map  $q(t, \cdot)$  is an increasing diffeomorphism of  $\mathbb{R}_{+}$ . And

$$h(t,q(t,x))q_x^3(t,x)=h_0(x), \quad (t,x)\in \big([0,T)\times\mathbb{R}_+\big).$$

# Remark 2.2

- (a) If supp  $h_0 \subset [a, b]$ , then, for all  $t \in (0, T)$ , supp  $h(t, \cdot) \subset [q(t, a), q(t, b)]$ .
- (b) If  $h_0 \ge 0$ , then, for  $t \in [0, T)$ ,  $h(t, \cdot) \ge 0$ .

**Lemma 2.3** Let u be a global solution of (1.1). Suppose that  $h_0 \in L^1(\mathbb{R}_+)$  and  $h_0 \ge 0$ . Then, for  $t \ge 0$ , we have

$$\left\|\tilde{h}(t,\cdot)\right\|_{L^{1}(\mathbb{R}_{+})} = \left\|h(t,\cdot)\right\|_{L^{1}(\mathbb{R}_{+})} = \left\|h_{0}(t,\cdot)\right\|_{L^{1}(\mathbb{R}_{+})}.$$
(2.2)

*Proof* From  $h_0 \ge 0$  and Remark 2.2(b)  $h(t, \cdot) \ge 0$ , for t > 0, the first equality of (2.2) results from a change of variable. The seconde equality can be got from (1.2) using integration by parts. That is,

$$\frac{\mathrm{d}}{\mathrm{d}t}\int_{\mathbb{R}_+}h(t,x)\,\mathrm{d}x=\int_{\mathbb{R}_+}\left(-uh_x-2u_xh\right)\mathrm{d}x=\int_{\mathbb{R}_+}-u_xh\,\mathrm{d}x=0.$$

**Proposition 2.4** Let u is a global solution of (1.1), and h is the momentum density of u. Then

$$u(t,x) = \frac{1}{2} \int_{\mathbb{R}_+} \left( e^{-|x-y|} - e^{-|x+y|} \right) h(t,y) \, \mathrm{d}y.$$
(2.3)

Proof Let

$$\overline{h}(t,x) = \begin{cases} h(t,x), & x \ge 0, \\ -h(t,-x), & x < 0, \end{cases}$$
$$\overline{u}(t,x) = \begin{cases} u(t,x), & x \ge 0, \\ -u(t,-x), & x < 0. \end{cases}$$

For convenience, the following proof omits the *t*. When x < 0,

$$\overline{u}^{\prime\prime}(x) = \frac{\mathrm{d}^2}{\mathrm{d}x^2}\overline{u}(x) = \frac{\mathrm{d}^2}{\mathrm{d}x^2} \big[-u(-x)\big] = -u^{\prime\prime}(-x).$$

Then

$$\overline{u}(x) - \overline{u}''(x) = -u(-x) + u''(-x) = -\left[u(-x) - u''(-x)\right] = -h(-x) = \overline{h}(x).$$

So  $\overline{h}(t, x)$  is the momentum density of  $\overline{u}(t, x)$  on the whole line. Then

$$\overline{u}(x) = \frac{1}{2} \int_{\mathbb{R}} e^{-|x-y|} \overline{h}(y) \, \mathrm{d}y = \frac{1}{2} \int_{\mathbb{R}_+} e^{-|x-y|} \overline{h}(y) \, \mathrm{d}y + \frac{1}{2} \int_{\mathbb{R}_-} e^{-|x-y|} \overline{h}(y) \, \mathrm{d}y$$
$$= I + II.$$

Because

$$I = \frac{1}{2} \int_{\mathbb{R}_+} e^{-|x-y|} \overline{h}(y) \, \mathrm{d}y = \frac{1}{2} \int_{\mathbb{R}_+} e^{-|x-y|} h(y) \, \mathrm{d}y$$

and

$$\begin{split} II &= \frac{1}{2} \int_{\mathbb{R}_{-}} e^{-|x-y|} \overline{h}(y) \, dy = \frac{1}{2} \int_{\mathbb{R}_{-}} e^{-|x-y|} \left(-h(-y)\right) dy \\ &= -\frac{1}{2} \int_{\mathbb{R}_{+}} e^{-|x+z|} h(z) \, dz, \end{split}$$

we have

$$\overline{u}(x) = I + II = \frac{1}{2} \int_{\mathbb{R}_+} \left( e^{-|x-y|} - e^{-|x+y|} \right) h(t,y) \, \mathrm{d}y.$$

We record here two formulas frequently used later. From (2.3), we get

$$u(t,tx) = \frac{1}{2} \int_{\mathbb{R}_+} \left( e^{-|tx-y|} - e^{-|tx+y|} \right) h(t,y) \, \mathrm{d}y = \frac{1}{2} \int_{\mathbb{R}_+} \left( e^{-t|x-z|} - e^{-t|x+z|} \right) \widetilde{h}(t,z) \, \mathrm{d}z.$$
(2.4)

Differentiate (2.3) with respect to the spatial variable to get

$$u_x(t,x) = \frac{1}{2} \int_{\mathbb{R}_+} \left( \operatorname{sgn}(y-x)e^{-|x-y|} + e^{-|x+y|} \right) h(t,y) \, \mathrm{d}y$$
  
=  $\frac{1}{2} \int_{\mathbb{R}_+} \left( \operatorname{sgn}(tz-x)e^{-|x-tz|} + e^{-|x+tz|} \right) \widetilde{h}(t,z) \, \mathrm{d}z.$ 

Hence

$$u_{x}(t,tx) = \frac{1}{2} \int_{\mathbb{R}_{+}} \left( \text{sgn}(z-x)e^{-t|x-z|} + e^{-t|x+z|} \right) \widetilde{h}(t,z) \, \mathrm{d}z.$$
(2.5)

**Lemma 2.5** Let u be a global solution of (1.1). Suppose that  $h_0 \ge 0$  and  $supp(h_0) \subset [a, b] \subset \mathbb{R}_+$ . Then, for  $t \ge 1$ ,

$$\operatorname{supp} \tilde{h}(t, \cdot) \subset \left[\frac{a}{t}, \frac{b}{t} + M\right].$$
(2.6)

*Here*  $M := ||u||_{L^{\infty}(\mathbb{R}_+ \times \mathbb{R}_+)}$ . *There exists* d > M, *such that, for*  $t \ge 1$ , supp  $\tilde{h}(t, \cdot) \subset [0, d]$ .

*Proof* Notice that  $u_0 \in G^s(\mathbb{R}_+)$ , with  $k \in \mathbb{N} \setminus \{0\}$ , and  $2k + \frac{1}{2} < s \leq 2k + 2$ , implies that  $h_0 \in H^{s-2}(\mathbb{R}_+) \subset L^{\infty}(\mathbb{R}_+)$ , and that the  $h_0$  has compact support implies that  $h_0 \in L^1(\mathbb{R}_+)$ . From (2.6) and the Remark 2.2(b),  $h(t, \cdot) \geq 0$  for all  $t \geq 0$ . Equation (2.3) and Lemma 2.3 imply that, for all  $(t, x) \in [0, \infty) \times \mathbb{R}_+$ ,

$$0 \le u(t,x) \le \frac{1}{2} \left\| h(t,\cdot) \right\|_{L^1(\mathbb{R}_+)} = \frac{1}{2} \| h_0 \|_{L^1(\mathbb{R}_+)} < \infty.$$
(2.7)

Let  $M := ||u||_{L^{\infty}(\mathbb{R}_+ \times \mathbb{R}_+)}$ . By the Remark 2.2(a), supp  $h(t, \cdot) \subset [a, b + Mt]$ , then

$$\operatorname{supp} \tilde{h}(t, \cdot) \subset \left[\frac{a}{t}, \frac{b}{t} + M\right].$$

**Lemma 2.6** ([13, 17]) Let  $\mu \in \mathcal{M}[c,d]$  be a nonnegative measure. Then there exist a nonnegative continuous measure  $v \in \mathcal{M}[c,d]$ , countably (including finitely) many real numbers  $m_i > 0$ , and  $\alpha_i \in [c,d]$  such that

$$\mu = \nu + \Sigma_i m_i \delta_{\alpha_i}. \tag{2.8}$$

In particular, given  $\varepsilon > 0$ , there exists  $\delta > 0$  such that, for an interval  $I \subset [c,d]$  with  $|I| < \delta$ ,  $v(I) < \varepsilon$ .

### 3 Proof of the main theorem

We prove Theorem 1.5 in this section. We will obtain information on the asymptotic density  $\mu$  by testing it with  $\varphi \in C_c(\mathbb{R}_+)$ .

**Proposition 3.1** Suppose that h satisfies (1.2). Then  $\tilde{h}$  satisfies

$$\frac{\partial}{\partial t}\tilde{h}(t,y) - \frac{\partial}{\partial y} \left[ \frac{y\tilde{h}(t,y)}{t} \right] + \frac{u(t,ty)}{t} \frac{\partial}{\partial y} \tilde{h}(t,y) + 2u_x(t,ty)\tilde{h}(t,y) = 0.$$
(3.1)

Proof Calculate directly to get

$$\begin{split} \frac{\partial}{\partial t}\tilde{h}(t,y) &= h(t,ty) + th_t(t,ty) + tyh_x(t,ty), \\ -\frac{\partial}{\partial y} \left[ \frac{y\tilde{h}(t,y)}{t} \right] &= -h(t,ty) - tyh_x(t,ty), \\ \frac{u(t,ty)}{t} \frac{\partial}{\partial y}\tilde{h}(t,y) &= tu(t,ty)h_x(t,ty), \\ 2u_x(t,ty)\tilde{h}(t,y) &= 2tu_x(t,ty)h(t,ty). \end{split}$$

From (1.2), we get (3.1).

**Proposition 3.2** Suppose  $h_0 \ge 0$  and has compact support. Let  $\varphi \in C_c(\mathbb{R}_+)$ , and  $\phi \in C^1(\mathbb{R}_+)$  be an antiderivative of  $\varphi$ . Let  $t_k \to \infty$  be a sequence of time such that  $\tilde{h}(t_k, \cdot) \rightharpoonup \mu$ , an asymptotic density with  $\mu = \nu + \sum_i m_i \delta_{\alpha_i}$ ,  $\nu$  continuous,  $m_i > 0$ ,  $\alpha_i \in [c, d]$  as given by Lemma 2.6. Then

$$\begin{aligned} \limsup_{k \to \infty} \left| \int_{\mathbb{R}_{+}} \phi(y) u(t_{k}, t_{k}y) \frac{\partial}{\partial y} \left[ \tilde{h}(t_{k}, y) \right] dy + 2 \int_{\mathbb{R}_{+}} t_{k} \phi(y) u_{x}(t_{k}, t_{k}y) \tilde{h}(t_{k}, y) dy \right| \\ \leq \frac{3}{2} \sum_{i} \left| \varphi(\alpha_{i}) \right| m_{i}^{2}. \end{aligned}$$
(3.2)

*Proof* Fix  $\varphi \in C_c(\mathbb{R}_+)$ . We divide the proof into three steps:

Step 1. Given  $\varepsilon > 0$ , since  $\sum_{i=1}^{\infty} m_i < \infty$ , there exists an  $N = N(\varepsilon)$  such that  $\sum_{i>N} m_i < \frac{\varepsilon}{4}$ . Choose  $\delta = \delta(\varepsilon) > 0$  such that when  $|I| < \delta$ ,  $\nu(I) \le \frac{\varepsilon}{4}$  and

 $\mu([\alpha_i - 2\delta, \alpha_i + 2\delta]) < m_i(1 + \varepsilon), \quad i = 1, \dots, N,$ (3.3)

$$[\alpha_i - \delta, \alpha_i + \delta] \cap [\alpha_j - \delta, \alpha_j + \delta] = \emptyset, \quad \text{for } i \neq j, \text{and } 1 \le i, j \le N,$$
(3.4)

$$\left|\varphi(y) - \varphi(\alpha_i)\right| < \varepsilon, \quad \forall y \in [\alpha_i - 2\delta, \alpha_i + 2\delta], i = 1, \dots, N.$$
(3.5)

As  $\tilde{h}(t_k, \cdot) \rightarrow \mu$ , there is a  $K_0 > 0$  such that, for any integer  $k > K_0$ ,

$$\int_{[\alpha_i - 2\delta, \alpha_i + 2\delta]} \tilde{h}(t_k, y) \, \mathrm{d}y < m_i(1 + \varepsilon), \quad \forall i = 1, \dots, N,$$
(3.6)

and for any interval  $I \subset \mathbb{R}_+ \setminus \bigcup_{i=1}^N (\alpha_i - \frac{1}{2}\delta, \alpha_i + \frac{1}{2}\delta)$ , with  $|I| < \delta$ , we claim that

$$\int_{I} \tilde{h}(t_k, y) \,\mathrm{d}y < \varepsilon. \tag{3.7}$$

To see this, recall from the first paragraph of step 1, we get

$$(\mu - \nu)(I) \leq \sum_{i>N} m_i < \frac{\varepsilon}{4},$$

then

$$\mu(I) < \frac{\varepsilon}{2}.\tag{3.8}$$

Let supp  $\tilde{h}(t, \cdot) \subset J \subset \mathbb{R}_+$ . Write  $J \setminus \bigcup_{i=1}^N (\alpha_i - \frac{1}{2}\delta, \alpha_i + \frac{1}{2}\delta)$  as  $\bigcup_{i=1}^L J_j$ , with  $J_j$  mutually disjoint and  $|J_j| \leq \delta$ . From (3.8), we get

$$\mu(J_j) < \frac{\varepsilon}{2}, \quad \forall j = 1, \dots, L.$$

As  $\tilde{h}(t_k, \cdot) \rightharpoonup \mu$ , there is a sufficiently big  $K_0$ , such that (3.6) holds, and

$$\int_{J_j} \tilde{h}(t_k, y) \,\mathrm{d}y < \frac{\varepsilon}{2}, \quad \forall j = 1, \dots, L, k > K_0.$$
(3.9)

It is obvious that *I* intersect two  $J_j$  at most, then from (3.9), we obtain equation (3.7). Step 2. For  $i \in \{1, ..., N\}$ , Let

$$E_i = [\alpha_i - \delta, \alpha_i + \delta], \qquad F_i = [\alpha_i - 2\delta, \alpha_i + 2\delta]$$

and

$$E=E_1\cup\cdots\cup E_N.$$

Define

$$B_{k} := \int_{\mathbb{R}_{+}} \phi(y)u(t_{k}, t_{k}y) \frac{\partial}{\partial y} \left[\tilde{h}(t_{k}, y)\right] dy + 2 \int_{\mathbb{R}_{+}} \phi(y)u_{x}(t_{k}, t_{k}y)\tilde{h}(t_{k}, y)t_{k} dy$$
$$= -\int_{\mathbb{R}_{+}} \varphi(y)u(t_{k}, t_{k}y)\tilde{h}(t_{k}, y) dy + \int_{\mathbb{R}_{+}} \phi(y)u_{x}(t_{k}, t_{k}y)\tilde{h}(t_{k}, y)t_{k} dy$$
$$:= C_{k} + D_{k}.$$
(3.10)

By (2.4), we get

$$C_{k} = -\int_{\mathbb{R}_{+}} \varphi(y) u(t_{k}, t_{k}y) \tilde{h}(t_{k}, y) \, dy$$
  
$$= -\frac{1}{2} \int_{\mathbb{R}_{+}} \int_{\mathbb{R}_{+}} \varphi(y) \left( e^{-t_{k}|y-z|} - e^{-t_{k}|y+z|} \right) \tilde{h}(t_{k}, y) \tilde{h}(t_{k}, z) \, dy \, dz$$
  
$$= \left( -\frac{1}{2} \sum_{i=1}^{N} \iint_{\substack{|z-y| < \frac{\delta}{2} \\ y \in E_{i}, z \in \mathbb{R}_{+}}} -\frac{1}{2} \iint_{\substack{|z-y| < \frac{\delta}{2} \\ y \in E^{c}, z \in \mathbb{R}_{+}}} -\frac{1}{2} \iint_{|z-y| > \frac{\delta}{2}} \right)$$
  
$$\times \varphi(y) \left( e^{-t_{k}|y-z|} - e^{-t_{k}|y+z|} \right) \tilde{h}(t_{k}, y) \tilde{h}(t_{k}, z) \, dy \, dz := C_{k1} + C_{k2} + C_{k3}.$$
(3.11)

Using (3.5) and (3.6), we obtain

$$\begin{aligned} |C_{k1}| &\leq \sum_{i=1}^{N} \iint_{\substack{|y-z| < \frac{\delta}{2} \\ y \in E_{i}, z \in \mathbb{R}_{+}}} |\varphi(y)| \tilde{h}(t_{k}, y) \tilde{h}(t_{k}, z) \, \mathrm{d}y \, \mathrm{d}z \leq \sum_{i=1}^{N} \iint_{\substack{y \in E_{i} \\ z \in F_{i}}} |\varphi(y)| \tilde{h}(t_{k}, y) \tilde{h}(t_{k}, z) \, \mathrm{d}y \, \mathrm{d}z \\ &\leq \sum_{i=1}^{N} \left( \left|\varphi(\alpha_{i})\right| + \varepsilon \right) m_{i}^{2} (1 + \varepsilon)^{2}. \end{aligned}$$

$$(3.12)$$

By (3.36) and (3.7), we have

$$|C_{k2}| \leq \iint_{\substack{|z-y|<\frac{\delta}{2}\\y\in E^{c}, z\in\mathbb{R}_{+}}} |\varphi(y)|\tilde{h}(t_{k}, y)\tilde{h}(t_{k}, z) \,\mathrm{d}y \,\mathrm{d}z \leq \|\varphi\|_{L^{\infty}} \int_{\substack{y\in E^{c}\\z\in\mathbb{R}_{+}}} \tilde{h}(t_{k}, y) \,\mathrm{d}y \int_{\substack{|z-y|<\frac{\delta}{2}\\z\in\mathbb{R}_{+}}} \tilde{h}(t_{k}, z) \,\mathrm{d}z$$
$$\leq \varepsilon \|\varphi\|_{L^{\infty}} \left(\int_{y\in E^{c}} \tilde{h}(t_{k}, y) \,\mathrm{d}y\right) \leq \varepsilon \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \|h_{0}\|_{L^{1}(\mathbb{R}_{+})}.$$
(3.13)

Notice that, for  $|y - z| > \frac{\delta}{2}$ ,  $|y + z| > \frac{\delta}{2}$ , and using equation (3.36), we have

$$|C_{k3}| \leq \frac{1}{2} \iint_{|z-y|>\frac{\delta}{2}} |\varphi(y)| e^{-t_k \frac{\delta}{2}} \tilde{h}(t_k, y) \tilde{h}(t_k, z) \, \mathrm{d}y \, \mathrm{d}z$$
  
$$\leq \frac{1}{2} e^{-t_k \frac{\delta}{2}} \|\varphi\|_{L_{\infty}(\mathbb{R}_+)} \|h_0\|_{L^1(\mathbb{R}_+)}^2.$$
(3.14)

Using (2.5), we have

$$D_{k} = \frac{1}{2} \int_{\mathbb{R}_{+}} \int_{\mathbb{R}_{+}} \phi(y) t_{k} \Big[ \operatorname{sgn}(z-y) e^{-t_{k}|z-y|} + e^{-t_{k}|z+y|} \Big] \tilde{h}(t_{k},z) \tilde{h}(t_{k},y) \, \mathrm{d}z \, \mathrm{d}y.$$
(3.15)

As  $D_k$  is symmetric in y and z, there is a  $\theta \in (0, 1)$  such that

$$\begin{split} D_{k} &= \frac{1}{2} \int_{\mathbb{R}_{+}} \int_{\mathbb{R}_{+}} \phi(z) t_{k} \big[ \operatorname{sgn}(y-z) e^{-t_{k}|y-z|} + e^{-t_{k}|y+z|} \big] \tilde{h}(t_{k},z) \tilde{h}(t_{k},y) \, dz \, dy \\ &= \frac{1}{4} \int_{\mathbb{R}_{+}} \int_{\mathbb{R}_{+}} \big[ \phi(y) - \phi(z) \big] \big[ \operatorname{sgn}(z-y) e^{-t_{k}|z-y|} + e^{-t_{k}|z+y|} \big] \tilde{h}(t_{k},y) \tilde{h}(t_{k},z) \, dy \, dz \\ &= \frac{1}{4} \int_{\mathbb{R}_{+}} \int_{\mathbb{R}_{+}} \varphi(y + \theta(z-y)) t_{k}(y-z) \big[ \operatorname{sgn}(z-y) t_{k} e^{-t_{k}|z-y|} + e^{-t_{k}|z+y|} \big] \\ &\times \tilde{h}(t_{k},y) \tilde{h}(t_{k},z) \, dy \, dz \end{split}$$

$$= \left(\frac{1}{4}\sum_{i=1}^{N}\iint_{\substack{|y-z|<\frac{\delta}{2}\\y\in E_{i},z\in\mathbb{R}_{+}}} + \frac{1}{4}\iint_{\substack{|y-z|<\frac{\delta}{2}\\y\in E^{c},z\in\mathbb{R}_{+}}} + \frac{1}{4}\iint_{|y-z|>\frac{\delta}{2}}\right) \\ \times \varphi(y+\theta(z-y))t_{k}(y-z)[\operatorname{sgn}(z-y)e^{-t_{k}|z-y|} + e^{-t_{k}|z+y|}]\tilde{h}(t_{k},y)\tilde{h}(t_{k},z)\,\mathrm{d}y\,\mathrm{d}z$$
  
$$:= D_{k1} + D_{k2} + D_{k3}.$$
(3.16)

Using (3.5) and (3.6), get

$$|D_{k1}| \leq \frac{1}{2} \sum_{i=1}^{N} (|\varphi(\alpha_i)| + \varepsilon) \int_{y \in E_i} \tilde{h}(t_k, y) \, \mathrm{d}y \int_{z \in F_i} \tilde{h}(t_k, z) \, \mathrm{d}z$$
  
$$\leq \frac{1}{2} \sum_{i=1}^{N} (|\varphi(\alpha_i)| + \varepsilon) m_i^2 (1 + \varepsilon)^2.$$
(3.17)

As  $\xi > 0$ ,  $\xi e^{-\xi} \le 1$ , from (3.36) and (3.7),

$$|D_{k2}| \leq \frac{1}{4} \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \iint_{\substack{|y-z| < \frac{\delta}{2} \\ y \in E^{c}, z \in \mathbb{R}_{+} \ }} t_{k} |y-z| |\operatorname{sgn}(z-y) e^{-t_{k} |z-y|} + e^{-t_{k} |z+y|} |\tilde{h}(t_{k}, y) \tilde{h}(t_{k}, z) \, dy \, dz \leq \frac{1}{2} \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \int_{y \in E_{c}} \tilde{h}(t_{k}, y) \left( \int_{z \in [y - \frac{\delta}{2}, y + \frac{\delta}{2}]} \tilde{h}(t_{k}, z) \, dz \right) \, dy \leq \frac{\varepsilon}{2} \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \int_{y \in \mathbb{R}_{+}} \tilde{h}(t_{k}, y) \, dy \leq \frac{\varepsilon}{2} \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \|h_{0}\|_{L^{1}(\mathbb{R}_{+})}.$$
(3.18)

Notice that, for  $\xi > 0$ ,  $\xi e^{-\xi} = \frac{\xi}{1+\xi+\xi^2/2+\cdots} \le \frac{\xi}{\xi^2/2} = \frac{2}{\xi}$ . Hence for  $|y-z| > \frac{\delta}{2}$ ,

$$\begin{aligned} t_{k}|y-z|e^{-t_{k}|y-z|} &\leq \frac{2}{t_{k}|y-z|} < \frac{4}{t_{k}\delta}, \\ |D_{k3}| &\leq \frac{1}{4} \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \iint_{|y-z|>\frac{\delta}{2}} t_{k}|y-z| |\operatorname{sgn}(z-y)e^{-t_{k}|z-y|} \\ &+ e^{-t_{k}|z+y|} |\tilde{h}(t_{k},y)\tilde{h}(t_{k},z) \, \mathrm{d}y \, \mathrm{d}z \\ &\leq \frac{1}{2} \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \iint_{|y-z|>\frac{\delta}{2}} \frac{4}{t_{k}\delta} \tilde{h}(t_{k},y)\tilde{h}(t_{k},z) \, \mathrm{d}y \, \mathrm{d}z \leq \frac{2\|\varphi\|_{L^{\infty}(\mathbb{R}_{+})}}{t_{k}\delta} \|h_{0}\|_{L^{1}(\mathbb{R}_{+})}^{2}. \end{aligned}$$
(3.19)

Step 3. From (3.10)-(3.19), we obtain

$$\begin{split} |B_{k}| &\leq \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \|h_{0}\|_{L^{1}(\mathbb{R}_{+})} \bigg( \frac{3}{2}\varepsilon + \frac{1}{2}e^{-t_{k}\frac{\delta}{2}} \|h_{0}\|_{L^{1}(\mathbb{R}_{+})} + \frac{2\|h_{0}\|_{L^{1}(\mathbb{R}_{+})}}{t_{k}\delta} \bigg) \\ &+ \frac{3}{2}\sum_{i=1}^{N} \big( \big|\varphi(\alpha_{i})\big| + \varepsilon \big) m_{i}^{2}(1+\varepsilon)^{2}. \end{split}$$

Let  $k \to \infty$ , we have

$$\limsup_{k\to\infty}|B_k|\leq \frac{3\varepsilon}{2}\|\varphi\|_{L^{\infty}(\mathbb{R}_+)}\|h_0\|_{L^1(\mathbb{R}_+)}+\frac{3}{2}\sum_{i=1}^N(|\varphi(\alpha_i)|+\varepsilon)m_i^2(1+\varepsilon)^2.$$

As  $\varepsilon$  is arbitrary, the proposition is proved.

**Lemma 3.3** Let  $\varphi \in C_c(\mathbb{R}_+)$ , and  $\phi \in C^1(\mathbb{R}_+)$  be an antiderivative of  $\varphi$ , and

$$\begin{split} &A[t;\varphi] = -\int_{\mathbb{R}_{+}} \phi(y) \frac{\partial}{\partial y} \big[ y \tilde{h}(t,y) \big] \, \mathrm{d}y, \\ &B[t;\varphi] = -\int_{\mathbb{R}_{+}} \phi(y) u(t,ty) \frac{\partial}{\partial y} \big[ \tilde{h}(t,y) \big] \, \mathrm{d}y - 2 \int_{\mathbb{R}_{+}} \phi(y) t u_{x}(t,ty) \tilde{h}(t,y) \, \mathrm{d}y. \end{split}$$

Then

$$\limsup_{t \to \infty} \left( B[t;\varphi] - A[t;\varphi] \right) \ge 0. \tag{3.20}$$

*Proof* We divide the proof into three steps.

Step 1. Define  $f(t) := \int_{\mathbb{R}} \phi(y) \tilde{h}(t, y) \, dy$ . Then from (3.1),

$$f'(t) = \int_{\mathbb{R}_{+}} \phi(y) \frac{\partial}{\partial t} \tilde{h}(t, y) \, dy$$
  
$$= \frac{1}{t} \int_{\mathbb{R}_{+}} \phi(y) \frac{\partial}{\partial y} \left[ y \tilde{h}(t, y) \right] \, dy$$
  
$$- \frac{1}{t} \int_{\mathbb{R}_{+}} \phi(y) u(t, ty) \frac{\partial}{\partial y} \tilde{h}(t, y) \, dy - \frac{1}{t} \int_{\mathbb{R}_{+}} 2\phi(y) u_{x}(t, ty) \tilde{h}(t, y) t \, dy$$
  
$$= -\frac{1}{t} A[t; \varphi] + \frac{1}{t} B[t; \varphi].$$
(3.21)

Integrating (3.21) from t to  $t^2$ , we get

$$f(t^2) - f(t) = \int_t^{t^2} \frac{B[s;\psi] - A[s;\psi]}{s} \,\mathrm{d}s.$$

Step 2. We claim that  $Q := \limsup(B[s;\varphi] - A[s;\varphi]) < \infty$ . Recall from Lemma 2.5 that there exists  $d > ||u||_{L^{\infty}(\mathbb{R}_+ \times \mathbb{R}_+)}$  such that, for all  $t \ge 1$ ,  $\sup \tilde{h}(t, \cdot) \subset [0, d]$ . From (3.36), we have

$$\begin{aligned} \left| A[t;\varphi] \right| &= \left| -\int_{\mathbb{R}_{+}} \phi(y) \frac{\partial}{\partial y} \left[ y \tilde{h}(t,y) \right] dy \right| &= \left| \int_{\mathbb{R}_{+}} \varphi(y) y \tilde{h}(t,y) dy \right| \\ &\leq \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \int_{\operatorname{supp} \tilde{h}(t,\cdot)} |y| \tilde{h}(t,y) dy \leq \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} d\|h_{0}\|_{L^{1}(\mathbb{R}_{+})}. \end{aligned}$$
(3.22)

We claim that  $B[t; \varphi]$  is also bounded. To see this, write

$$B[t;\varphi] = -\int_{\mathbb{R}_{+}} \phi(y)u(t,ty)\frac{\partial}{\partial y} \left[\tilde{h}(t,y)\right] dy - 2\int_{\mathbb{R}_{+}} \phi(y)tu_{x}(t,ty)\tilde{h}(t,y) dy$$
$$= -\int_{\mathbb{R}_{+}} \phi(y)\frac{\partial}{\partial y} \left[u(t,ty)\tilde{h}(t,y)\right] dy - \int_{\mathbb{R}_{+}} \phi(y)tu_{x}(t,ty)\tilde{h}(t,y) dy$$
$$:= G_{1} + G_{2}.$$
(3.23)

From (2.7) and (3.36), we have

$$|G_{1}| = \left| \int_{\mathbb{R}_{+}} \varphi(y) u(t, ty) \tilde{h}(t, y) \, \mathrm{d}y \right| \le \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \|u\|_{L^{\infty}(\mathbb{R}_{+} \times \mathbb{R}_{+})} \|h_{0}\|_{L^{1}(\mathbb{R}_{+})}.$$
(3.24)

Using (2.5),

$$G_{2} = -\frac{1}{2} \iint_{\mathbb{R}_{+} \times \mathbb{R}_{+}} \phi(y) t [\operatorname{sgn}(z - y)e^{-t|y-z|} + e^{-t|y+z|}] \tilde{h}(t, z) \tilde{h}(t, y) dz dy$$
  
$$= -\frac{1}{2} \left( \iint_{|y-z| \ge 1} + \iint_{|y-z| < 1} \right) \phi(y) t [\operatorname{sgn}(z - y)e^{-t|y-z|} + e^{-t|y+z|}] \tilde{h}(t, z) \tilde{h}(t, y) dz dy$$
  
$$:= G_{21} + G_{22}.$$
(3.25)

Noticing that, for  $y, z \ge 0$ ,  $te^{-t|y+z|} \le te^{-t|y-z|} \le \frac{t}{t|y-z|} \le 1$ , then

$$\begin{aligned} |G_{21}| &\leq \frac{1}{2} \iint_{[0,d]^2} |\phi(y)| t |\operatorname{sgn}(z-y) e^{-t|y-z|} + e^{-t|y+z|} |\tilde{h}(t,y)\tilde{h}(t,z) \, \mathrm{d}y \, \mathrm{d}z \\ &\leq \|\phi\|_{L^{\infty}(\mathbb{R}_+)} \|h_0\|_{L^1(\mathbb{R}_+)}^2 \leq \|\varphi\|_{L^1(\mathbb{R})} \|h_0\|_{L^1(\mathbb{R}_+)}^2, \end{aligned} \tag{3.26} \\ G_{22} &= -\frac{1}{2} \iint_{|y-z|<1} \phi(y) t \operatorname{sgn}(z-y) e^{-t|y-z|} \tilde{h}(t,z) \tilde{h}(t,y) \, \mathrm{d}z \, \mathrm{d}y \\ &+ \left(-\frac{1}{2}\right) \iint_{|y-z|<1} \phi(y) t e^{-t|y+z|} \tilde{h}(t,z) \tilde{h}(t,y) \, \mathrm{d}z \, \mathrm{d}y := G_{221} + G_{222}. \end{aligned} \tag{3.27}$$

As  $G_{221}$  is symmetric in y and z, there is a  $\theta \in (0, 1)$  such that

$$|G_{221}| \leq \left| \frac{1}{2} \iint_{|y-z|<1} \phi(z)t [\operatorname{sgn}(y-z)] e^{-t|y-z|} \tilde{h}(t,z) \tilde{h}(t,y) \, dz \, dy \right|$$
  

$$\leq \left| \frac{1}{4} \iint_{|y-z|<1} [\phi(y) - \phi(z)] t [\operatorname{sgn}(z-y)] e^{-t|y-z|} \tilde{h}(t,z) \tilde{h}(t,y) \, dz \, dy \right|$$
  

$$\leq \frac{1}{4} \iint_{|y-z|<1} |\varphi(z + \theta(y-z))| t |y-z| e^{-t|y-z|} \tilde{h}(t,z) \tilde{h}(t,y) \, dz \, dy$$
  

$$\leq \frac{1}{4} \|\varphi\|_{L^{\infty}(\mathbb{R}_{+})} \|h_{0}\|_{L^{1}(\mathbb{R}_{+})}^{2}.$$
(3.28)

For  $G_{222}$ , choose the anti-derivative  $\phi(y) = \int_0^y \varphi(s) \, ds$ . Noticing that  $\|\phi\|_{L^{\infty}(\mathbb{R}_+)} \le \|\varphi\|_{L^1(\mathbb{R}_+)}$ ,

$$\begin{aligned} |G_{222}| &= \left| \frac{1}{2} \int_{0}^{\infty} \phi(y) t e^{-ty} \tilde{h}(t, y) \left( \int_{|y-z|<1} e^{-tz} \tilde{h}(t, z) \, \mathrm{d}z \right) \mathrm{d}y \right| \\ &\leq \frac{1}{2} \|h_0\|_{L^1(\mathbb{R}_+)} \int_{0}^{\infty} \left| \phi(y) \right| t e^{-ty} \tilde{h}(t, y) \, \mathrm{d}y \\ &\leq \frac{1}{2} \|h_0\|_{L^1(\mathbb{R}_+)} \int_{0}^{\infty} \left| \frac{\phi(y) - \phi(0)}{y} \right| t y e^{-ty} \tilde{h}(t, y) \, \mathrm{d}y \\ &\leq \frac{1}{2} \|h_0\|_{L^1(\mathbb{R}_+)} \int_{0}^{d} \left| \varphi(\theta y) \right| \tilde{h}(t, y) \, \mathrm{d}y \leq \frac{1}{2} \|h_0\|_{L^1(\mathbb{R}_+)}^2 \|\varphi\|_{L^\infty(\mathbb{R}_+)}, \end{aligned}$$
(3.29)

where  $\theta \in (0, 1)$ .

From (3.23)-(3.28),  $|B[t; \varphi]|$  is bounded in *t*. Together with (3.22),  $-\infty < Q < \infty$ .

Step 3. For each  $\varepsilon > 0$ , there exists K > 0 such that when s > K,  $B[s; \psi] - A[s; \psi] < Q + \varepsilon$ . Hence when  $t^2 > t > K$ ,

$$f(t^2) - f(t) < \int_t^{t^2} \frac{Q + \varepsilon}{s} \, \mathrm{d}s < (Q + \varepsilon) \log t,$$

that is, 
$$\frac{f(t^2)-f(t)}{\log t} \leq Q + \varepsilon$$
. For  $r \in [1, \infty)$ ,

$$f(r) = \int_{a}^{b} \phi(y)\tilde{h}(r,y) \, \mathrm{d}y \le \|\phi\|_{C[a,b]} \|h_0\|_{L^1(\mathbb{R}_+)} \le \|\varphi\|_{L^1(\mathbb{R})} \|h_0\|_{L^1(\mathbb{R}_+)}$$

Hence

$$0 = \lim_{t \to \infty} \frac{f(t^2) - f(t)}{\log t} \le Q + \varepsilon.$$

As  $\varepsilon$  is arbitrary, Lemma 3.3 is proved.

**Lemma 3.4** Suppose that  $\tilde{h}(t, \cdot)$  has a unique asymptotic density, that is,  $a \ \mu \in \mathcal{M}[c,d]$  such that  $\tilde{h}(t, \cdot) \rightarrow \mu$  as  $t \rightarrow \infty$ . Suppose  $\mu = v + \sum_{i=1}^{\infty} m_i \delta_{\alpha_i}$  is the decomposition of  $\mu$  into continuous and discrete parts (Lemma 2.6). Then, for all  $\varphi \in C_c(\mathbb{R}_+), A[t;\varphi] \rightarrow \langle y\mu, \varphi(y) \rangle$  as  $t \rightarrow \infty$ , and

$$\left|\left\langle y\mu,\varphi(y)\right\rangle\right| \le \frac{3}{2} \sum_{i=1}^{\infty} \left|\varphi(\alpha_i)\right| m_i^2.$$
(3.30)

*Proof* It is easy to see that

$$A[t;\varphi] = -\int_{\mathbb{R}_{+}} \phi(y) \frac{\partial}{\partial y} \left[ y\tilde{h}(t,y) \right] dy = \int_{\mathbb{R}_{+}} \varphi(y) y\tilde{h}(t,y) \, dy \to \langle y\mu,\varphi(y) \rangle.$$
(3.31)

From Proposition 3.2, we get

$$\limsup_{k\to\infty} |B[t;\varphi]| \leq \frac{3}{2} \sum_{i=1}^{\infty} |\varphi(\alpha_i)| m_i^2.$$

Together with (3.31) and Lemma 3.3,

$$\langle y\mu,\varphi(y)\rangle = \lim_{t\to\infty} \int_{\mathbb{R}_+} \varphi(y)y\tilde{h}(t,y) \,\mathrm{d}y$$
  
= 
$$\liminf_{t\to\infty} A[t;\varphi] \le \limsup_{t\to\infty} B[t;\varphi] \le \frac{3}{2} \sum_{i=1}^{\infty} |\varphi(\alpha_i)| m_i^2.$$

Replacing  $\varphi$  by  $-\varphi$ , we obtain (3.30).

*Proof of Theorem* 1.5 For (a), fix *i*, if  $\alpha_i = 0$ , the conclusion holds. Assume  $\alpha_i > 0$ , given  $\varepsilon > 0$ , there exists a  $\delta \in (0, \alpha_i)$  such that  $\mu([\alpha_i - \delta, \alpha_i + \delta]) \le m_i + \varepsilon$ .

If  $\alpha_j \in [\alpha_i - \delta, \alpha_i + \delta], j \neq i, m_i \delta_{\alpha_i} + m_j \delta_{\alpha_j} \leq \mu$  implies that  $m_j \leq \varepsilon$ .

Let  $\varphi \in C_c(\mathbb{R}_+)$ ,  $\varphi \ge 0$ , supp  $\varphi \subset (\alpha_i - \delta, \alpha_i + \delta) \subset \mathbb{R}_+$ , max  $\varphi = \varphi(\alpha_i)$ . From (3.30) and  $\mu \ge 0$  we obtain

$$m_i lpha_i \varphi(lpha_i) = \langle m_i \delta_{lpha_i}, y \varphi(y) 
angle \leq \langle \mu, y \varphi(y) 
angle \leq rac{3}{2} \left( m_i^2 \varphi(lpha_i) + \sum_{j \neq i} \varphi(lpha_j) m_j^2 
ight).$$

If 
$$\alpha_j \notin [\alpha_i - \delta, \alpha_i + \delta]$$
, then  $\psi(\alpha_j) = 0$ . In any case,

$$\varphi(\alpha_i)m_i^2 \leq \varphi(\alpha_i)m_i\varepsilon \leq \varphi(\alpha_i)m_i\varepsilon.$$

Hence

$$m_i \alpha_i \varphi(\alpha_i) \leq \frac{3}{2} \varphi(\alpha_i) \bigg[ m_i^2 + \varepsilon \sum_{j \neq i} m_j \bigg].$$

Let  $\varepsilon \to 0$ , we get

$$\alpha_i \le \frac{3}{2} m_i. \tag{3.32}$$

For (b), from Lemma 2.5 and  $\tilde{h}(t, \cdot) \rightarrow \mu$  we get supp  $\mu \in [0, M]$ . Together with  $\nu \geq 0, m_i > 0$ , and (2.8), we obtain

$$\operatorname{supp} v \subset [0, M], \quad \text{and} \quad \alpha_i \in [0, M]. \tag{3.33}$$

For (c), since  $\mu = \nu + \sum_i m_i \delta_{\alpha_i}$  is a finite measure,  $\nu \ge 0$ ,  $m_i > 0$  implies that

$$\sum_i m_i < \infty.$$

Hence  $m_i \rightarrow 0$ , as  $i \rightarrow \infty$ , then from (3.32) we get

$$\alpha_i \to 0, \quad \text{as } i \to \infty.$$
 (3.34)

For (d), suppose  $\mu$  does not have discrete parts over  $(e, f) \subset \mathbb{R}_+ \setminus \{0\}$ , that is, no  $\alpha_i$  is in (e, f). Let  $\varphi \in C_c(e, f)$ , Then supp  $\varphi \cap \{\alpha_1, \alpha_2, \ldots\} = \emptyset$ , from (3.30) we obtain  $\langle \mu(y), y\varphi(y) \rangle = 0$ , hence  $y\mu|_{(e,f)} = 0$ , so  $\mu|_{(e,f)} = 0$ .

Notice that  $\sup v \subset [0, M]$ , as  $\sup \mu \subset [0, M]$ , v continuous and  $\mu - v$  discrete. If  $\alpha > 0$ , then it is not an accumulation point of  $\{\alpha_i\}$ . Hence there exists a  $\delta \in (0, \alpha)$  such that  $\bigcup_{i=1}^{\infty} \{\alpha_i\} \cap [(\alpha - \delta, \alpha + \delta) \setminus \{\alpha\}] = \emptyset$ . Since  $v|_{(\alpha - \delta, \alpha) \cup (\alpha, \alpha + \delta)} = 0$ , as v is a continuous measure,  $v|_{(\alpha - \delta, \alpha + \delta)} = 0$ . Hence v = 0 in some neighborhood of each point of  $(0, \infty)$ , and hence  $v|_{\mathbb{R}_+ \setminus \{0\}} = 0$ . As v is a continuous measure, v = 0, that is,

$$\mu = \sum_{i=1}^{\infty} m_i \delta_{\alpha_i}.$$
(3.35)

We have

$$\left\|\widetilde{h}(t,\cdot)\right\|_{L^{1}(\mathbb{R}_{+})} = \left\|h(t,\cdot)\right\|_{L^{1}(\mathbb{R}_{+})} = \left\|h_{0}(\cdot)\right\|_{L^{1}(\mathbb{R}_{+})}.$$
(3.36)

Together with (3.35) and (3.36), we obtain

$$\sum_{i=1}^{\infty} m_i = \sum_{i=1}^{\infty} m_i \delta_{\alpha_i}(\mathbb{R}_+) = \mu(\mathbb{R}_+) = \lim_{t \to \infty} \int_{\mathbb{R}_+} \tilde{h}(t, y) \, \mathrm{d}y = \|h_0\|_{L^1(\mathbb{R}_+)}.$$
(3.37)

#### **Competing interests**

None of the authors have any competing interests as regards the manuscript.

#### Authors' contributions

All authors contributed equally and all authors approved the manuscript.

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