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Corrigendum

Corrigendum to "Robust Control of Underactuated Systems: Higher Order Integral Sliding Mode Approach"

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In the article titled "Robust Control of Underactuated Systems: Higher Order Integral Sliding Mode Approach" [1], the affiliation of the first author should be "Department of Electrical Engineering, Capital University of Science and Technology (CUST), Kahuta Road, Express Highway, Islamabad 44000, Pakistan" only. The updated authors' list and affiliations are shown above.

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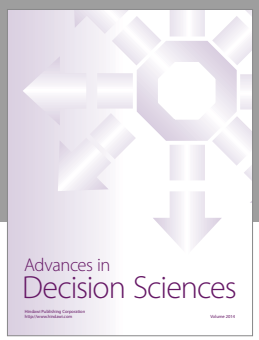
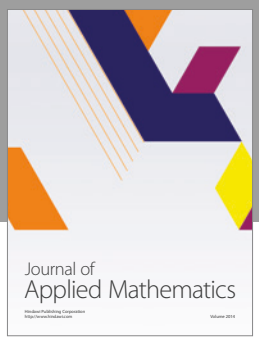
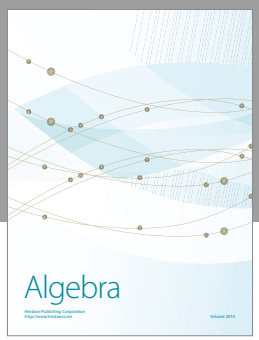
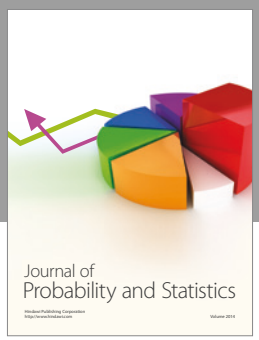
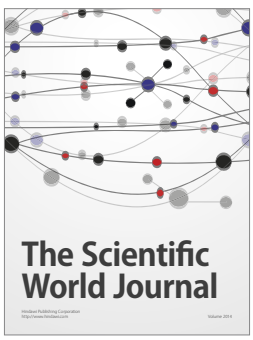
[1] S. ud Din, Q. Khan, F. U. Rehman, and R. Akmeliawati, "Robust Control of Underactuated Systems: Higher Order Integral Sliding Mode Approach," *Mathematical Problems in Engineering*, vol. 2016, Article ID 5641478, 11 pages, 2016.

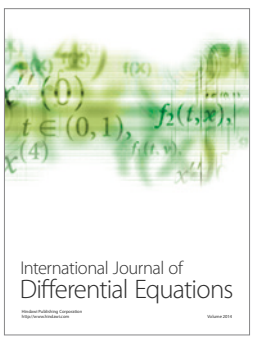


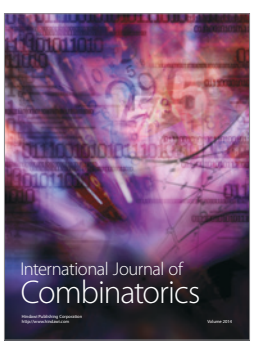


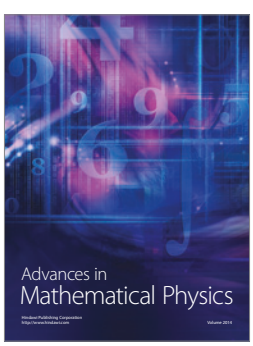


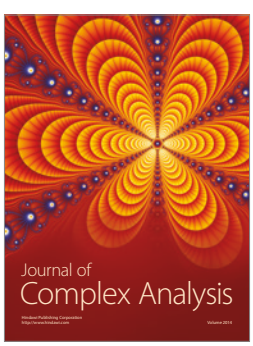


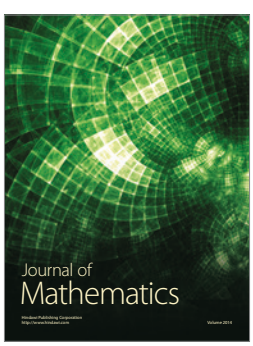


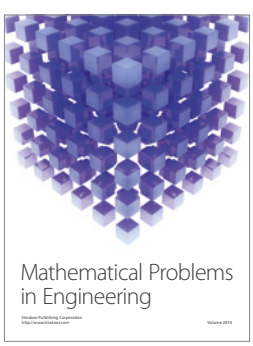


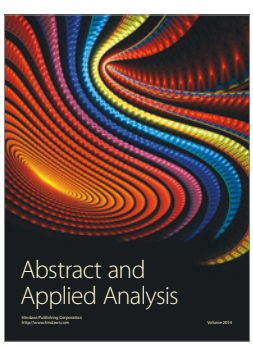


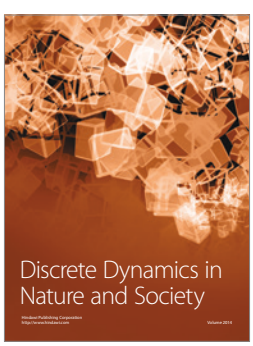


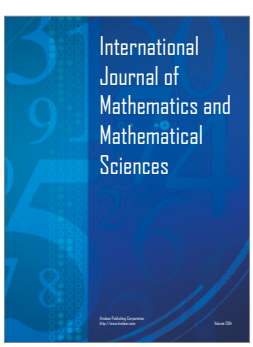


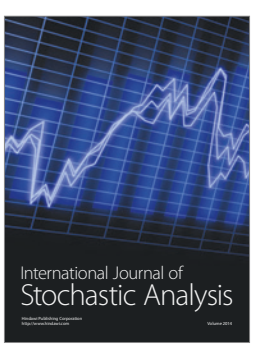












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