Research Article

Iterative Algorithms for Solving the System of Mixed Equilibrium Problems, Fixed-Point Problems, and Variational Inclusions with Application to Minimization Problem

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We introduce a new iterative algorithm for solving a common solution of the set of solutions of fixed point for an infinite family of nonexpansive mappings, the set of solution of a system of mixed equilibrium problems, and the set of solutions of the variational inclusion for a β-inverse-strongly monotone mapping in a real Hilbert space. We prove that the sequence converges strongly to a common element of the above three sets under some mild conditions. Furthermore, we give a numerical example which supports our main theorem in the last part.

1. Introduction

Let C be a closed convex subset of a real Hilbert space H with the inner product $\langle \cdot, \cdot \rangle$ and the norm $\| \cdot \|$. Let F be a bifunction of $C \times C$ into $\mathcal{R}$, where $\mathcal{R}$ is the set of real numbers, $\varphi : C \to \mathcal{R}$ be a real-valued function. Let Λ be arbitrary index set. The *system of mixed equilibrium problem* is for finding $x \in C$ such that

$$F_k(x, y) + \varphi(y) - \varphi(x) \geq 0, \quad k \in \Lambda, \ \forall y \in C. \tag{1.1}$$

The set of solutions of (1.1) is denoted by $\text{SMEP}(F_k)$, that is,

$$\text{SMEP}(F_k) = \left\{ x \in C := F_k(x, y) + \varphi(y) - \varphi(x) \geq 0, \ k \in \Lambda, \ \forall y \in C \right\}. \tag{1.2}$$

If Λ is a singleton, then problem (1.1) becomes the following *mixed equilibrium problem*: finding $x \in C$ such that

$$F(x, y) + \varphi(y) - \varphi(x) \geq 0, \quad \forall y \in C. \tag{1.3}$$

The set of solutions of (1.3) is denoted by MEP(F).

If $\varphi \equiv 0$, the problem (1.3) is reduced into the *equilibrium problem* [1] for finding $x \in C$ such that

$$F(x, y) \geq 0, \quad \forall y \in C. \tag{1.4}$$

The set of solutions of (1.4) is denoted by EP(F). This problem contains fixed-point problems, includes as special cases numerous problems in physics, optimization, and economics. Some methods have been proposed to solve the system of mixed equilibrium problem and the equilibrium problem, please consult [2–19].

Recall that, a mapping $S : C \rightarrow C$ is said to be *nonexpansive* if

$$\|Sx - Sy\| \leq \|x - y\|, \tag{1.5}$$

for all $x, y \in C$. If C is a bounded closed convex and S is a nonexpansive mapping of C into itself, then $F(S)$ is nonempty [20]. Let $A : C \rightarrow H$ be a mapping, the *Hartmann-Stampacchia variational inequality* for finding $x \in C$ such that

$$\langle Ax, y - x \rangle \geq 0, \quad \forall y \in C. \tag{1.6}$$

The set of solutions of (1.6) is denoted by VI(C, A). The variational inequality has been extensively studied in the literature [21–28].

Iterative methods for nonexpansive mappings have recently been applied to solve convex minimization problems. Convex minimization problems have a great impact and influence on the development of almost all branches of pure and applied sciences. A typical problem is to minimize a quadratic function over the set of the fixed points of a nonexpansive mapping on a real Hilbert space H:

$$\theta(x) = \frac{1}{2}\langle Ax, x \rangle - \langle x, y \rangle, \quad \forall x \in F(S), \tag{1.7}$$

where A is a linear bounded operator, $F(S)$ is the fixed point set of a nonexpansive mapping S, and y is a given point in H [29].

We denote weak convergence and strong convergence by notations $\rightharpoonup$ and $\rightarrow$, respectively. A mapping A of C into H is called *monotone* if

$$\langle Ax - Ay, x - y \rangle \geq 0, \tag{1.8}$$

for all $x, y \in C$. A mapping A of C into H is called *α-inverse-strongly monotone* if there exists a positive real number α such that

$$\langle Ax - Ay, x - y \rangle \geq \alpha \|Ax - Ay\|^2, \tag{1.9}$$

for all $x, y \in C$. It is obvious that any α-inverse-strongly monotone mappings A are monotone and Lipschitz continuous mapping. A linear bounded operator A is *strongly positive* if there exists a constant $\overline{\gamma} > 0$ with the property

$$\langle Ax, x \rangle \geq \overline{\gamma} \|x\|^2, \tag{1.10}$$

for all $x \in H$. A self-mapping $f : C \to C$ is a *contraction* on C if there exists a constant $\alpha \in (0, 1)$ such that

$$\|f(x) - f(y)\| \leq \alpha \|x - y\|, \tag{1.11}$$

for all $x, y \in C$. We use Π_C to denote the collection of all contraction on C. Note that each $f \in \Pi_C$ has a unique fixed point in C.

Let $B : H \to H$ be a single-valued nonlinear mapping and $M : H \to 2^H$ be a set-valued mapping. The *variational inclusion problem* is to find $x \in H$ such that

$$\theta \in B(x) + M(x), \tag{1.12}$$

where θ is the zero vector in H. The set of solutions of problem (1.12) is denoted by $I(B, M)$. The variational inclusion has been extensively studied in the literature, see, for example, [30–32] and the reference therein.

A set-valued mapping $M : H \to 2^H$ is called *monotone* if for all $x, y \in H$, $f \in M(x)$, and $g \in M(y)$ impling $\langle x - y, f - g \rangle \geq 0$. A monotone mapping M is *maximal* if its graph $G(M) := \{(f, x) \in H \times H : f \in M(x)\}$ of M is not properly contained in the graph of any other monotone mapping. It is known that a monotone mapping M is maximal if and only if for $(x, f) \in H \times H$, $\langle x - y, f - g \rangle \geq 0$ for all $(y, g) \in G(M)$ impling $f \in M(x)$.

Let B be an inverse-strongly monotone mapping of C into H, and let $N_C v$ be normal cone to C at $v \in C$, that is, $N_C v = \{w \in H : \langle v - u, w \rangle \geq 0, \text{ for all } u \in C\}$, and define

$$Tv = \begin{cases} Bv + N_C v, & \text{if } v \in C, \\ \emptyset, & \text{if } v \notin C. \end{cases} \tag{1.13}$$

Then, T is a maximal monotone and $\theta \in Tv$ if and only if $v \in \text{VI}(C, B)$ (see [33]).

Let $M : H \to 2^H$ be a set-valued maximal monotone mapping, then the single-valued mapping $J_{M,\lambda} : H \to H$ defined by

$$J_{M,\lambda}(x) = (I + \lambda M)^{-1}(x), \quad x \in H, \tag{1.14}$$

is called the *resolvent operator* associated with M, where λ is any positive number and I is the identity mapping. It is worth mentioning that the resolvent operator is nonexpansive,

1-inverse-strongly monotone, and that a solution of problem (1.12) is a fixed point of the operator $J_{M,\lambda}(I - \lambda B)$ for all $\lambda > 0$, (for more details see [34]).

In 2000, Moudafi [35] introduced the viscosity approximation method for nonexpansive mappings and proved that if H is a real Hilbert space, the sequence $\{x_n\}$ defined by the iterative method below, with the initial guess $x_0 \in C$ is chosen arbitrarily,

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)Sx_n, \quad n \geq 0, \tag{1.15}$$

where $\{\alpha_n\} \subset (0,1)$ satisfies certain conditions and converges strongly to a fixed point of S (say $\overline{x} \in C$), which is then a unique solution of the following variational inequality:

$$\langle (I - f)\overline{x}, x - \overline{x} \rangle \geq 0, \quad \forall x \in F(S). \tag{1.16}$$

In 2006, Marino and Xu [29] introduced a general iterative method for nonexpansive mapping. They defined the sequence $\{x_n\}$ generated by the algorithm $x_0 \in C$,

$$x_{n+1} = \alpha_n \gamma f(x_n) + (I - \alpha_n A)Sx_n, \quad n \geq 0, \tag{1.17}$$

where $\{\alpha_n\} \subset (0,1)$, and A is a strongly positive linear bounded operator. They proved that if $C = H$, and the sequence $\{\alpha_n\}$ satisfies appropriate conditions, then the sequence $\{x_n\}$ generated by (1.17) converges strongly to a fixed point of S (say $\overline{x} \in H$) which is the unique solution of the following variational inequality:

$$\langle (A - \gamma f)\overline{x}, x - \overline{x} \rangle \geq 0, \quad \forall x \in F(S), \tag{1.18}$$

which is the optimality condition for the minimization problem

$$\min_{x \in F(S) \cap \text{EP}(F)} \frac{1}{2} \langle Ax, x \rangle - h(x), \tag{1.19}$$

where h is a potential function for γf (i.e., $h'(x) = \gamma f(x)$ for $x \in H$).

For finding a common element of the set of fixed points of nonexpansive mappings and the set of solution of the variational inequalities. Let P_C be the projection of H onto C. In 2005, Iiduka and Takahashi [36] introduced the following iterative process for $x_0 \in C$,

$$x_{n+1} = \alpha_n u + (1 - \alpha_n)SP_C(x_n - \lambda_n Ax_n), \quad \forall n \geq 0, \tag{1.20}$$

where $u \in C$, $\{\alpha_n\} \subset (0,1)$, and $\{\lambda_n\} \subset [a,b]$ for some a,b with $0 < a < b < 2\beta$. They proved that under certain appropriate conditions imposed on $\{\alpha_n\}$ and $\{\lambda_n\}$, the sequence $\{x_n\}$ generated by (1.20) converges strongly to a common element of the set of fixed points of a nonexpansive mapping and the set of solutions of the variational inequality for an inverse-strongly monotone mapping (say $\overline{x} \in C$) which solve some variational inequality

$$\langle \overline{x} - u, x - \overline{x} \rangle \geq 0, \quad \forall x \in F(S) \cap \text{VI}(C, A). \tag{1.21}$$

In 2008, Su et al. [37] introduced the following iterative scheme by the viscosity approximation method in a real Hilbert space: $x_1, u_n \in H$

$$F(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C,$$

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n) SP_C(u_n - \lambda_n A u_n), \tag{1.22}$$

for all $n \in \mathbb{N}$, where $\{\alpha_n\} \subset [0, 1)$ and $\{r_n\} \subset (0, \infty)$ satisfing some appropriate conditions. Furthermore, they proved that $\{x_n\}$ and $\{u_n\}$ converge strongly to the same point $z \in F(S) \cap$ $\mathrm{VI}(C, A) \cap \mathrm{EP}(F)$, where $z = P_{F(S) \cap \mathrm{VI}(C,A) \cap \mathrm{EP}(F)} f(z)$.

Let $\{T_i\}$ be an infinite family of nonexpansive mappings of H into itself, and let $\{\lambda_i\}$ be a real sequence such that $0 \leq \lambda_i \leq 1$ for every $i \in N$. For $n \geq 1$, we defined a mapping W_n of H into itself as follows:

$$U_{n,n+1} := I,$$

$$U_{n,n} := \lambda_n T_n U_{n,n+1} + (1 - \lambda_n) I,$$

$$\vdots$$

$$U_{n,k} := \lambda_k T_k U_{n,k+1} + (1 - \lambda_k) I, \tag{1.23}$$

$$\vdots$$

$$U_{n,2} := \lambda_2 T_2 U_{n,3} + (1 - \lambda_2) I,$$

$$W_n := U_{n,1} := \lambda_1 T_1 U_{n,2} + (1 - \lambda_1) I.$$

In 2011, He et al. [38] introduced the following iterative process for $\{T_n : C \to C\}$ which is a sequence of nonexpansive mappings. Let $\{z_n\}$ be the sequence defined by

$$z_{n+1} = \epsilon_n \gamma f(z_n) + (I - \epsilon_n) W_n K^1_{r_1,n} K^2_{r_2,n} \cdots \cdots K^K_{r_K,n} z_n, \quad \forall n \in N. \tag{1.24}$$

The sequence $\{z_n\}$ defined by (1.24) converges strongly to a common element of the set of fixed points of nonexpansive mappings, the set of solutions of the variational inequality, and the generalized equilibrium problem. Recently, Jitpeera and Kumam [39] introduced the following new general iterative method for finding a common element of the set of solutions of fixed point for nonexpansive mappings, the set of solution of generalized mixed equilibrium problems, and the set of solutions of the variational inclusion for a β-inverse-strongly monotone mapping in a real Hilbert space.

In this paper, we modify the iterative methods (1.17), (1.22), and (1.24) by purposing the following new general viscosity iterative method: $x_0, u_n \in C$,

$$u_n = K^{F_N}_{r_n,n} \cdot K^{F_{N-1}}_{r_{n-1},n} \cdot K^{F_{N-2}}_{r_{n-2},n} \cdots \cdots K^{F_2}_{r_2,n} \cdot K^{F_1}_{r_1,n} \cdot x_n, \quad \forall n \in N$$

$$x_{n+1} = P_C[\epsilon_n \gamma f(x_n) + (I - \epsilon_n A) W_n J_{M,\lambda}(u_n - \lambda B u_n)], \tag{1.25}$$

for all $n \in \mathbb{N}$, where $\{\alpha_n\} \subset (0,1)$, $\{r_n\} \subset (0,2\sigma)$, and $\lambda \in (0,2\beta)$ satisfy some appropriate conditions. The purpose of this paper shows that under some control conditions the sequence $\{x_n\}$ converges strongly to a common element of the set of common fixed points of nonexpansive mappings, the solution of the system of mixed equilibrium problems, and the set of solutions of the variational inclusion in a real Hilbert space. Moreover, we apply our results to the class of strictly pseudocontractive mappings. Finally, we give a numerical example which supports our main theorem in the last part. Our results improve and extend the corresponding results of Marino and Xu [29], Su et al. [37], He et al. [38], and some authors.

2. Preliminaries

Let H be a real Hilbert space and C be a nonempty closed and convex subset of H. Recall that the (nearest point) projection P_C from H onto C assigns to each $x \in H$ and the unique point in $P_C x \in C$ satisfies the property

$$\|x - P_C x\| = \min_{y \in C} \|x - y\|, \tag{2.1}$$

which is equivalent to the following inequality

$$\langle x - P_C x, P_C x - y \rangle \geq 0, \quad \forall y \in C. \tag{2.2}$$

The following characterizes the projection P_C. We recall some lemmas which will be needed in the rest of this paper.

Lemma 2.1. *The function $u \in C$ is a solution of the variational inequality if and only if $u \in C$ satisfies the relation $u = P_C(u - \lambda Bu)$ for all $\lambda > 0$.*

Lemma 2.2. *For a given $z \in H$, $u \in C$, $u = P_C z \Leftrightarrow \langle u - z, v - u \rangle \geq 0$, $\forall v \in C$.*
   It is well known that P_C is a firmly nonexpansive mapping of H onto C and satisfies

$$\|P_C x - P_C y\|^2 \leq \langle P_C x - P_C y, x - y \rangle, \quad \forall x, y \in H. \tag{2.3}$$

Moreover, $P_C x$ is characterized by the following properties: $P_C x \in C$ and for all $x \in H, y \in C$,

$$\langle x - P_C x, y - P_C x \rangle \leq 0. \tag{2.4}$$

Lemma 2.3 (see [40]). *Let $M : H \rightarrow 2^H$ be a maximal monotone mapping, and let $B : H \rightarrow H$ be a monotone and Lipshitz continuous mapping. Then the mapping $L = M + B : H \rightarrow 2^H$ is a maximal monotone mapping.*

Lemma 2.4 (see [41]). *Each Hilbert space H satisfies Opial's condition, that is, for any sequence $\{x_n\} \subset H$ with $x_n \rightharpoonup x$, the inequality $\liminf_{n \to \infty} \|x_n - x\| < \liminf_{n \to \infty} \|x_n - y\|$, hold for each $y \in H$ with $y \neq x$.*

Lemma 2.5 (see [42]). *Assume $\{a_n\}$ is a sequence of nonnegative real numbers such that*

$$a_{n+1} \leq (1 - \gamma_n)a_n + \delta_n, \quad \forall n \geq 0, \tag{2.5}$$

where $\{\gamma_n\} \subset (0, 1)$ and $\{\delta_n\}$ is a sequence in $\mathcal{R}$ such that

(i) $\sum_{n=1}^{\infty} \gamma_n = \infty$,

(ii) $\limsup_{n \to \infty} \delta_n / \gamma_n \leq 0$ or $\sum_{n=1}^{\infty} |\delta_n| < \infty$.

Then $\lim_{n \to \infty} a_n = 0$.

Lemma 2.6 (see [43]). *Let C be a closed convex subset of a real Hilbert space H, and let $T : C \to C$ be a nonexpansive mapping. Then $I - T$ is demiclosed at zero, that is,*

$$x_n \longrightarrow x, \qquad x_n - Tx_n \longrightarrow 0, \tag{2.6}$$

implying $x = Tx$.

For solving the mixed equilibrium problem, let us assume that the bifunction $F : C \times C \to \mathcal{R}$ and the nonlinear mapping $\varphi : C \to \mathcal{R}$ satisfy the following conditions:

(A1) $F(x, x) = 0$ for all $x \in C$;

(A2) F is monotone, that is, $F(x, y) + F(y, x) \leq 0$ for any $x, y \in C$;

(A3) for each fixed $y \in C$, $x \mapsto F(x, y)$ is weakly upper semicontinuous;

(A4) for each fixed $x \in C$, $y \mapsto F(x, y)$ is convex and lower semicontinuous;

(B1) for each $x \in C$ and $r > 0$, there exist a bounded subset $D_x \subseteq C$ and $y_x \in C$ such that for any $z \in C \setminus D_x$,

$$F(z, y_x) + \varphi(y_x) - \varphi(z) + \frac{1}{r}\langle y_x - z, z - x \rangle < 0, \tag{2.7}$$

(B2) C is a bounded set.

Lemma 2.7 (see [44]). *Let C be a nonempty closed and convex subset of a real Hilbert space H. Let $F : C \times C \to \mathcal{R}$ be a bifunction mapping satisfying (A1)–(A4), and let $\varphi : C \to \mathcal{R}$ be a convex and lower semicontinuous function such that $C \cap \text{dom}\, \varphi \neq \emptyset$. Assume that either (B1) or (B2) holds. For $r > 0$ and $x \in H$, then there exists $u \in C$ such that*

$$F(u, y) + \varphi(y) - \varphi(u) + \frac{1}{r}\langle y - u, u - x \rangle \geq 0. \tag{2.8}$$

Define a mapping $K_r : H \to C$ as follows:

$$K_r(x) = \left\{ u \in C : F(u, y) + \varphi(y) - \varphi(u) + \frac{1}{r}\langle y - u, u - x \rangle \geq 0, \ \forall y \in C \right\}, \tag{2.9}$$

for all $x \in H$. Then, the following hold:

(i) *K_r is single-valued;*

(ii) *K_r is firmly nonexpansive, that is, for any $x, y \in H$, $\|K_r x - K_r y\|^2 \leq \langle K_r x - K_r y, x - y \rangle$;*

(iii) *$F(K_r) = \text{MEP}(F)$;*

(iv) *$\text{MEP}(F)$ is closed and convex.*

Lemma 2.8 (see [29]). *Assume A is a strongly positive linear bounded operator on a Hilbert space H with coefficient $\overline{\gamma} > 0$ and $0 < \rho \leq \|A\|^{-1}$, then $\|I - \rho A\| \leq 1 - \rho \overline{\gamma}$.*

Lemma 2.9 (see [38]). *Let C be a nonempty closed and convex subset of a strictly convex Banach space. Let $\{T_i\}_{i \in N}$ be an infinite family of nonexpansive mappings of C into itself such that $\cap_{i \in N} F(T_i) \neq \emptyset$, and let $\{\lambda_i\}$ be a real sequence such that $0 \leq \lambda_i \leq b < 1$ for every $i \in N$. Then $F(W) = \cap_{i \in N} F(T_i) \neq \emptyset$.*

Lemma 2.10 (see [38]). *Let C be a nonempty closed and convex subset of a strictly convex Banach space. Let $\{T_i\}$ be an infinite family of nonexpansive mappings of C into itself, and let $\{\lambda_i\}$ be a real sequence such that $0 \leq \lambda_i \leq b < 1$ for every $i \in N$. Then, for every $x \in C$ and $k \in N$, the limit $\lim_{n \to \infty} U_{n,k}$ exist.*

In view of the previous lemma, we define

$$Wx := \lim_{n \to \infty} U_{n,1} x = \lim_{n \to \infty} W_n x. \tag{2.10}$$

3. Strong Convergence Theorems

In this section, we show a strong convergence theorem which solves the problem of finding a common element of the common fixed points, the common solution of a system of mixed equilibrium problems and variational inclusion of inverse-strongly monotone mappings in a Hilbert space.

Theorem 3.1. *Let H be a real Hilbert space and C a nonempty close and convex subset of H, and let B be a β-inverse-strongly monotone mapping. Let $\varphi : C \to R$ be a convex and lower semicontinuous function, $f : C \to C$ a contraction mapping with coefficient α ($0 < \alpha < 1$), and $M : H \to 2^H$ a maximal monotone mapping. Let A be a strongly positive linear bounded operator of H into itself with coefficient $\overline{\gamma} > 0$. Assume that $0 < \gamma < \overline{\gamma}/\alpha$ and $\lambda \in (0, 2\beta)$. Let $\{T_n\}$ be a family of nonexpansive mappings of H into itself such that*

$$\theta := \bigcap_{n=1}^{\infty} F(T_n) \cap \left(\bigcap_{k=1}^{N} \text{SMEP}(F_k) \right) \cap I(B, M) \neq \emptyset. \tag{3.1}$$

Suppose that $\{x_n\}$ is a sequence generated by the following algorithm for $x_0 \in C$ arbitrarily and

$$u_n = K_{r_n,n}^{F_N} \cdot K_{r_{n-1},n}^{F_{N-1}} \cdot K_{r_{n-2},n}^{F_{N-2}} \cdots \cdot K_{r_2,n}^{F_2} \cdot K_{r_1,n}^{F_1} \cdot x_n, \quad \forall n \in N$$

$$x_{n+1} = P_C \left[\epsilon_n \gamma f(x_n) + (I - \epsilon_n A) W_n J_{M,\lambda} (u_n - \lambda B u_n) \right], \tag{3.2}$$

for all $n = 1, 2, 3, \ldots$, where

$$K_{r_{i,n}}^{F_i}(x) = \left\{ u_n \in C : F_i(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_{i,n}}\langle y - u_n, u_n - x_n \rangle \geq 0, \ \forall y \in C \right\},$$

$$i = 1, 2, 3, \ldots, N,$$

(3.3)

and the following conditions are satisfied

(C1): $\{\epsilon_n\} \subset (0, 1), \lim_{n \to 0} \epsilon_n = 0, \sum_{n=1}^{\infty} \epsilon_n = \infty, \sum_{n=1}^{\infty} |\epsilon_{n+1} - \epsilon_n| < \infty$;

(C2): $\{r_n\} \subset [c, d]$ *with* $c, d \in (0, 2\sigma)$ *and* $\sum_{n=1}^{\infty} |r_{n+1} - r_n| < \infty$.

Then, the sequence $\{x_n\}$ converges strongly to $q \in \theta$, where $q = P_\theta(\gamma f + I - A)(q)$ which solves the following variational inequality:

$$\langle (\gamma f - A)q, p - q \rangle \leq 0, \quad \forall p \in \theta,$$

(3.4)

which is the optimality condition for the minimization problem

$$\min_{q \in \theta} \frac{1}{2}\langle Aq, q \rangle - h(q),$$

(3.5)

where h is a potential function for γf (i.e., $h'(q) = \gamma f(q)$ for $q \in H$).

Proof. For condition (C1), we may assume without loss of generality, and $\epsilon_n \in (0, \|A\|^{-1})$ for all n. By Lemma 2.8, we have $\|I - \epsilon_n A\| \leq 1 - \epsilon_n \bar{\gamma}$. Next, we will assume that $\|I - A\| \leq \|1 - \bar{\gamma}\|$.

Next, we will divide the proof into six steps.

Step 1. First, we will show that $\{x_n\}$ and $\{u_n\}$ are bounded. Since B is β-inverse-strongly monotone mappings, we have

$$\begin{aligned}
\|(I - \lambda B)x - (I - \lambda B)y\|^2 &= \|Ix - \lambda Bx - Iy + \lambda By\|^2 \\
&= \|x - y - \lambda Bx + \lambda By\|^2 \\
&= \|(x - y) - \lambda(Bx + By)\|^2 \\
&\leq \|x - y\|^2 - 2\lambda\langle x - y \rangle\langle Bx + By \rangle + \lambda^2\|Bx - By\|^2 \\
&\leq \|x - y\|^2 - 2\lambda\beta\|Bx + By\|^2 + \lambda^2\|Bx - By\|^2 \\
&\leq \|x - y\|^2 + \lambda(\lambda - 2\beta)\|Bx + By\|^2,
\end{aligned}$$

(3.6)

if $0 < \lambda < 2\beta$, then $I - \lambda B$ is nonexpansive.

Put $y_n := J_{M,\lambda}(u_n - \lambda B u_n), n \geq 0$. Since $J_{M,\lambda}$ and $I - \lambda B$ are nonexpansive mapping, it follows that

$$
\begin{aligned}
\|y_n - q\| &= \|J_{M,\lambda}(u_n - \lambda B u_n) - J_{M,\lambda}(q - \lambda B q)\| \\
&\leq \|(u_n - \lambda B u_n) - (q - \lambda B q)\| \\
&\leq \|u_n - q\|.
\end{aligned}
\tag{3.7}
$$

By Lemma 2.7, we have

$$
\begin{aligned}
u_n &= K_{r_n,n}^{F_N} \cdot K_{r_{n-1},n}^{F_{N-1}} \cdot K_{r_{n-2},n}^{F_{N-2}} \cdot \cdots \cdot K_{r_2,n}^{F_2} \cdot K_{r_1,n}^{F_1} \cdot x_n, \quad \text{for } n \geq 0 \\
\tau_n^k &= K_{r_k,n}^{F_k} \cdot K_{r_{k-1},n}^{F_{k-1}} \cdot \cdots \cdot K_{r_2,n}^{F_2} \cdot K_{r_1,n}^{F_1}, \quad \text{for } k \in \{0, 1, 2, \ldots, N\},
\end{aligned}
\tag{3.8}
$$

and $\tau_n^0 = I$ for all $n \in N$, $q = \tau_{r_k,n}^{F_k} q$, $u_n = \tau_{r_k,N}^{N} x_n$ Then, we have

$$
\begin{aligned}
\|u_n - q\|^2 &= \left\| \tau_{r_k,n}^{N} x_n - \tau_{r_k,n}^{F_k} q \right\|^2 \\
&= \|x_n - q\|^2.
\end{aligned}
\tag{3.9}
$$

Hence, we get

$$
\|y_n - q\| \leq \|x_n - q\|.
\tag{3.10}
$$

From (3.2), we deduce that

$$
\begin{aligned}
\|x_{n+1} - q\| &= \|P_C(\epsilon_n \gamma f(x_n) + (I - \epsilon_n A)W_n y_n) - P_C q\| \\
&\leq \|\epsilon_n(\gamma f(x_n) - Aq) + (I - \epsilon_n A)(W_n y_n - q)\| \\
&\leq \epsilon_n \|\gamma f(x_n) - Aq\| + (1 - \epsilon_n \bar{\gamma})\|y_n - q\| \\
&\leq \epsilon \gamma \epsilon_n \|x_n - q\| + \epsilon_n \|\gamma f(g) - Aq\| \\
&\quad + (1 - \epsilon_n \bar{\gamma})\|x_n - q\| \\
&= (1 - (\bar{\gamma} - \gamma \epsilon)\epsilon_n)\|x_n - q\| - \epsilon_n \|\gamma f(q) - Aq\| \\
&= (1 - (\bar{\gamma} - \gamma \epsilon)\epsilon_n)\|x_n - q\| + (\bar{\gamma} - \gamma \epsilon)\epsilon_n \frac{\|\gamma f(q) - Aq\|}{\bar{\gamma} - \gamma \epsilon} \\
&\quad \vdots \\
&\leq \max \left\{ \|x_n - q\|, \frac{\|\gamma f(q) - Aq\|}{\bar{\gamma} - \gamma \epsilon} \right\}.
\end{aligned}
\tag{3.11}
$$

It follows by induction that

$$\|x_n - q\| \le \max\left\{ \|x_0 - q\|, \frac{\|\gamma f(q) - Aq\|}{\bar{\gamma} - \gamma\epsilon} \right\}, \quad n \ge 0. \tag{3.12}$$

Therefore $\{x_n\}$ is bounded, so are $\{y_n\}$, $\{Bu_n\}$, $\{f(x_n)\}$, and $\{AW_n y_n\}$.

Step 2. We claim that $\lim_{n \to \infty} \|x_{n+1} - x_n\| = 0$ and $\lim_{n \to \infty} \|y_{n+1} - y_n\| = 0$. From (3.2), we have

$$
\begin{aligned}
\|x_{n+1} - x_n\| &= \left\| P_C(\epsilon_n \gamma f(x_n) + (I - \epsilon_n A)W_n y_n) - P_C(\epsilon_{n-1}\gamma f(x_{n-1}) + (I - \epsilon_{n-1}A)W_n y_{n-1}) \right\| \\
&\le \left\| (I - \epsilon_n A)(W_n y_n - W_n y_{n-1}) - (\epsilon_n - \epsilon_{n-1})AW_n y_{n-1} \right. \\
&\quad \left. + \gamma\epsilon_n(f(x_n) - f(x_{n-1})) + \gamma(\epsilon_n - \epsilon_{n-1})f(x_{n-1}) \right\| \\
&\le (1 - \epsilon_n\bar{\gamma})\|y_n - y_{n-1}\| + |\epsilon_n - \epsilon_{n-1}|\|AW_n y_n\| + \gamma\epsilon\epsilon_n\|x_n - x_{n-1}\| \\
&\quad + \gamma|\epsilon_n - \epsilon_{n-1}|\|f(x_{n-1})\|.
\end{aligned}
\tag{3.13}
$$

Since $J_{M,\lambda}$ and $I - \lambda B$ are nonexpansive, we also have

$$
\begin{aligned}
\|y_n - y_{n-1}\| &= \|J_{M,\lambda}(u_n - \lambda B u_n) - J_{M,\lambda}(u_{n-1} - \lambda B u_{n-1})\| \\
&\le \|(u_n - \lambda B u_n) - (u_{n-1} - \lambda B u_{n-1})\| \\
&\le \|u_n - u_{n-1}\|.
\end{aligned}
\tag{3.14}
$$

On the other hand, from $u_{n-1} = \tau^N_{r_k, n-1} x_{n-1}$ and $u_n = \tau^N_{r_k, n} x_n$, it follows that

$$F(u_{n-1}, y) + \varphi(y) - \varphi(u_{n-1}) + \frac{1}{r_{n-1}}\langle y - u_{n-1}, u_{n-1} - x_{n-1}\rangle \ge 0, \quad \forall y \in C, \tag{3.15}$$

$$F(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n}\langle y - u_n, u_n - x_n\rangle \ge 0, \quad \forall y \in C. \tag{3.16}$$

Substituting $y = u_n$ into (3.15) and $y = u_{n-1}$ into (3.16), we get

$$
\begin{aligned}
&F(u_{n-1}, u_n) + \varphi(u_n) - \varphi(u_{n-1}) + \frac{1}{r_{n-1}}\langle u_n - u_{n-1}, u_{\text{n}-1} - x_{n-1}\rangle \ge 0, \\
&F(u_n, u_{n+1}) + \varphi(u_{n+1}) - \varphi(u_n) + \frac{1}{r_n}\langle u_{n+1} - u_n, un - x_n\rangle \ge 0.
\end{aligned}
\tag{3.17}
$$

From (A2), we obtain

$$\left\langle u_n - u_{n-1}, \frac{u_{n-1} - x_{n-1}}{r_{n-1}} - \frac{u_n - x_n}{r_n} \right\rangle \geq 0,$$

$$\left\langle u_n - u_{n-1}, u_{n-1} - x_{n-1} - \frac{r_{n-1}}{r_n} (u_n - x_n) \right\rangle \geq 0, \tag{3.18}$$

so,

$$\left\langle u_n - u_{n-1}, u_{n-1} - u_n + u_n - x_{n-1} - \frac{r_{n-1}}{r_n} (u_n - x_n) \right\rangle \geq 0. \tag{3.19}$$

It follows that

$$\left\langle u_n - u_{n-1}, u_{n-1} - u_n + u_n - x_n - \frac{r_{n-1}}{r_n} (u_n - x_n) \right\rangle \geq 0,$$

$$\langle u_n - u_{n-1}, u_{n-1} - u_n \rangle + \left\langle u_n - u_{n-1}, \left(1 - \frac{r_{n-1}}{r_n} \right) (u_n - x_n) \right\rangle \geq 0. \tag{3.20}$$

Without loss of generality, let us assume that there exists a real number c such that $r_{n-1} > c > 0$, for all $n \in \mathbb{N}$. Then, we have

$$\| u_n - u_{n-1} \|^2 \leq \left\langle u_n - u_{n-1}, \left(1 - \frac{r_{n-1}}{r_n} \right) (u_n - x_n) \right\rangle$$

$$\leq \| u_n - u_{n-1} \| \left\{ \left| 1 - \frac{r_{n-1}}{r_n} \right| \| u_n - x_n \| \right\}, \tag{3.21}$$

and hence

$$\| u_n - u_{n-1} \| \leq \| x_n - x_{n-1} \| + \frac{1}{r_n} |r_n - r_{n-1}| \| u_n - x_n \|$$

$$\leq \| x_n - x_{n-1} \| + \frac{M_1}{c} |r_n - r_{n-1}|, \tag{3.22}$$

where $M_1 = \sup \{ \| u_n - x_n \| : n \in \mathbb{N} \}$. Substituting (3.22) into (3.14), we have

$$\| y_n - y_{n-1} \| \leq \| x_n - x_{n-1} \| + \frac{M_1}{c} |r_n - r_{n-1}|. \tag{3.23}$$

Substituting (3.23) into (3.13), we get

$$
\begin{aligned}
\|x_{n+1} - x_n\| &\le (1 - \epsilon_n \bar{\gamma}) \left(\|x_n - x_{n-1}\| + \frac{M_1}{c} |r_n - r_{n-1}| \right) + |\epsilon_n - \epsilon_{n-1}| \|AW_n y_{n-1}\| \\
&\quad + \gamma \epsilon \epsilon_n \|x_n - x_{n-1}\| + \gamma |\epsilon_n - \epsilon_{n-1}| \|f(x_{n-1})\| \\
&= (1 - \epsilon_n \bar{\gamma}) \|x_n - x_{n-1}\| + (1 - \epsilon_n \bar{\gamma}) \frac{M_1}{c} |r_n - r_{n-1}| + |\epsilon_n - \epsilon_{n-1}| \|AW_n y_{n-1}\| \\
&\quad + \gamma \epsilon \epsilon_n \|x_n - x_{n-1}\| + \gamma |\epsilon_n - \epsilon_{n-1}| \|f(x_{\mathrm{n}-1})\| \\
&\le (1 - (\bar{\gamma} - \gamma \epsilon) \epsilon_n) \|x_n - x_{n-1}\| + \frac{M_1}{c} |r_n - r_{n-1}| + |\epsilon_n - \epsilon_{n-1}| \|AW_n y_{n-1}\| \\
&\quad + \gamma |\epsilon_n - \epsilon_{n-1}| \|f(x_{n-1})\| \\
&\le (1 - (\bar{\gamma} - \gamma \epsilon) \epsilon_n) \|x_n - x_{n-1}\| + \frac{M_1}{c} |r_n - r_{n-1}| + M_2 |\epsilon_n - \epsilon_{n-1}|,
\end{aligned}
\tag{3.24}
$$

where $M_2 = \sup\{\max\{\|AW_n y_{n-1}\|, \|f(x_{n-1})\| : n \in \mathbb{N}\}\}$. Since conditions (C1)-(C2) and by Lemma 2.5, we have $\|x_{n+1} - x_n\| \to 0$ as $n \to \infty$. From (3.23), we also have $\|y_{n+1} - y_n\| \to 0$ as $n \to \infty$.

Step 3. Next, we show that $\lim_{n \to \infty} \|Bu_n - Bq\| = 0$.
   For $q \in \theta$ hence $q = J_{M,\lambda}(q - \lambda Bq)$. By (3.6) and (3.9), we get

$$
\begin{aligned}
\|y_n - q\|^2 &= \|J_{M,\lambda}(u_n - \lambda Bu_n) - J_{M,\lambda}(q - \lambda Bq)\|^2 \\
&\le \|(u_n - \lambda Bu_n) - (q - \lambda Bq)\|^2 \\
&\le \|u_n - q\|^2 + \lambda(\lambda - 2\beta) \|Bu_n - Bq\|^2 \\
&\le \|x_n - q\|^2 + \lambda(\lambda - 2\beta) \|Bu_n - Bq\|^2.
\end{aligned}
\tag{3.25}
$$

It follows that

$$
\begin{aligned}
\|x_{n+1} - q\|^2 &= \|P_C(\epsilon_n \gamma f(x_n) + (I - \epsilon_n A) W_n y_n) - P_C(q)\|^2 \\
&\le \|\epsilon_n(\gamma f(x_n) - Aq) + (I - \epsilon_n A)(W_n y_n - q)\|^2 \\
&\le (\epsilon_n \|\gamma f(x_n) - Aq\| + (1 - \epsilon_n \bar{\gamma}) \|y_n - q\|)^2 \\
&\le \epsilon_n \|\gamma f(x_n) - Aq\|^2 + (1 - \epsilon_n \bar{\gamma}) \|y_n - q\|^2 \\
&\quad + 2\epsilon_n(1 - \epsilon_n \bar{\gamma}) \|\gamma f(x_n) - Aq\| \|y_n - q\|
\end{aligned}
$$

$$\leq \epsilon_n \|\gamma f(x_n) - Aq\|^2 + 2\epsilon_n(1 - \epsilon_n\bar{\gamma})\|\gamma f(x_n) - Aq\|\|y_n - q\|$$

$$+ (1 - \epsilon_n\bar{\gamma})\left(\|x_n - q\|^2 + \lambda(\lambda - 2\beta)\|Bu_n - Bq\|^2\right)$$

$$\leq \epsilon_n \|\gamma f(x_n) - Aq\|^2 + 2\epsilon_n(1 - \epsilon_n\bar{\gamma})\|\gamma f(x_n) - Aq\|\|y_n - q\|$$

$$+ \|x_n - q\|^2 + (1 - \epsilon_n\bar{\gamma})\lambda(\lambda - 2\beta)\|Bu_n - Bq\|^2. \tag{3.26}$$

So, we obtain

$$(1 - \epsilon_n\bar{\gamma})\lambda(2\beta - \lambda)\|Bu_n - Bq\|^2 \leq \epsilon_n\|\gamma f(x_n) - Aq\|^2$$
$$+ \|x_n - x_{n+1}\|(\|x_n - q\| + \|x_{n+1} - q\|) + \xi_n, \tag{3.27}$$

where $\xi_n = 2\epsilon_n(1-\epsilon_n\bar{\gamma})\|\gamma f(x_n)-Aq\|\|y_n-q\|$. By conditions (C1), (C3) and $\lim_{n\to\infty}\|x_{n+1}-x_n\| = 0$, then, we obtain that $\|Bu_n - Bq\| \to 0$ as $n \to \infty$.

Step 4. We show the following:

(i) $\lim_{n\to\infty}\|x_n - u_n\| = 0$;

(ii) $\lim_{n\to\infty}\|u_n - y_n\| = 0$;

(iii) $\lim_{n\to\infty}\|y_n - W_n y_n\| = 0$.

Since $K_{r_n}(x)$ is firmly nonexpansive and (2.3), we observe that

$$\|u_n - q\|^2 = \left\|\tau_{r_n,n}^N x_n - \tau_{r_n,n}^N q\right\|^2$$
$$\leq \langle x_n - q, u_n - q \rangle$$
$$= \frac{1}{2}\left(\|x_n - q\|^2 + \|u_n - q\|^2 - \|x_n - q - u_n - q\|^2\right)$$
$$\leq \frac{1}{2}\left(\|x_n - q\|^2 + \|u_n - q\|^2 - \|x_n - u_n\|^2\right), \tag{3.28}$$

it follows that

$$\|u_n - q\|^2 \leq \|x_n - q\|^2 - \|x_n - u_n\|^2. \tag{3.29}$$

Since $J_{M,\lambda}$ is 1-inverse-strongly monotone and by (2.3), we compute

$$
\begin{aligned}
\left\|y_n - q\right\|^2 &= \left\|J_{M,\lambda}(u_n - \lambda B u_n) - J_{M,\lambda}(q - \lambda B q)\right\|^2 \\
&\leq \left\langle (u_n - \lambda B u_n) - (q - \lambda B q), y_n - q \right\rangle \\
&= \frac{1}{2}\left(\left\|(u_n - \lambda B u_n) - (q - \lambda B q)\right\|^2 + \left\|y_n - q\right\|^2 \right. \\
&\quad \left. - \left\|(u_n - \lambda B u_n) - (q - \lambda B q) - (y_n - q)\right\|^2\right) \\
&\leq \frac{1}{2}\left(\left\|u_n - q\right\|^2 + \left\|y_n - q\right\|^2 - \left\|(u_n - y_n) - \lambda(B u_n - B q)\right\|^2\right) \\
&= \frac{1}{2}\left(\left\|u_n - q\right\|^2 + \left\|y_n - q\right\|^2 - \left\|u_n - y_n\right\|^2 \right. \\
&\quad \left. + 2\lambda\left\langle u_n - y_n, B u_n - B q\right\rangle - \lambda^2\left\|B u_n - B q\right\|^2\right),
\end{aligned}
\tag{3.30}
$$

which implies that

$$
\left\|y_n - q\right\|^2 \leq \left\|u_n - q\right\|^2 - \left\|u_n - y_n\right\|^2 + 2\lambda\left\|u_n - y_n\right\|\left\|B u_n - B q\right\|.
\tag{3.31}
$$

Substituting (3.31) into (3.26), we have

$$
\begin{aligned}
\left\|x_{n+1} - q\right\|^2 &\leq \epsilon_n\left\|\gamma f(x_n) - Aq\right\|^2 + \left\|y_n - q\right\|^2 + 2\epsilon_n(1 - \epsilon_n\bar{\gamma})\left\|\gamma f(x_n) - Aq\right\|\left\|y_n - q\right\| \\
&\leq \epsilon_n\left\|\gamma f(x_n) - Aq\right\|^2 + \left(\left\|u_n - q\right\|^2 - \left\|u_n - y_n\right\|^2 + 2\lambda_n\left\|u_n - y_n\right\|\left\|B u_n - B q\right\|\right) \\
&\quad + 2\epsilon_n(1 - \epsilon_n\bar{\gamma})\left\|\gamma f(x_n) - Aq\right\|\left\|y_n - q\right\|.
\end{aligned}
\tag{3.32}
$$

Then, we derive

$$
\begin{aligned}
\left\|x_n - u_n\right\|^2 + \left\|u_n - y_n\right\|^2 &\leq \epsilon_n\left\|\gamma f(x_n) - Aq\right\|^2 + \left\|x_n - q\right\|^2 - \left\|x_{n+1} - q\right\|^2 \\
&\quad + 2\lambda\left\|u_n - y_n\right\|\left\|B u_n - B q\right\| + 2\epsilon_n(1 - \epsilon_n\bar{\gamma})\left\|\gamma f(x_n) - Aq\right\|\left\|y_n - q\right\|. \\
&= \epsilon_n\left\|\gamma f(x_n) - Aq\right\|^2 + \left\|x_n - x_{n+1}\right\|\left(\left\|x_n - q\right\| + \left\|x_{n+1} - q\right\|\right) \\
&\quad + 2\lambda\left\|u_n - y_n\right\|\left\|B u_n - B q\right\| + 2\epsilon_n(1 - \epsilon_n\bar{\gamma})\left\|\gamma f(x_n) - Aq\right\|\left\|y_n - q\right\|.
\end{aligned}
\tag{3.33}
$$

By condition (C1), $\lim_{n\to\infty}\|x_n - x_{n+1}\| = 0$ and $\lim_{n\to\infty}\|B u_n - B q\| = 0$.
So, we have $\|x_n - u_n\| \to 0, \|u_n - y_n\| \to 0$ as $n \to \infty$. It follows that

$$
\left\|x_n - y_n\right\| \leq \left\|x_n - u_n\right\| + \left\|u_n - y_n\right\| \longrightarrow 0, \quad \text{as } n \longrightarrow \infty.
\tag{3.34}
$$

From (3.2), we have

$$
\begin{aligned}
\|x_n - W_n y_n\| &\leq \|x_n - W_n y_{n-1}\| + \|W_n y_{n-1} - W_n y_n\| \\
&\leq \|P_C(\epsilon_{n-1}\gamma f(x_{n-1}) + (I - \alpha_{n-1}A)W_n y_{n-1}) - P_C(W_n y_{n-1})\| + \|y_{n-1} - y_n\| \\
&\leq \epsilon_{n-1}\|\gamma f x_{n-1} - A W_n y_{n-1}\| + \|y_{n-1} - y_n\|.
\end{aligned}
\tag{3.35}
$$

By condition (C1) and $\lim_{n\to\infty}\|y_{n-1} - y_n\| = 0$, we obtain that $\|x_n - W_n y_n\| \to 0$ as $n \to \infty$.
Hence, we have

$$
\begin{aligned}
\|x_n - W_n x_n\| &\leq \|x_n - W_n y_n\| + \|W_n y_n - W_n x_n\| \\
&\leq \|x_n - W_n y_n\| + \|y_n - x_n\|.
\end{aligned}
\tag{3.36}
$$

By (3.34) and $\lim_{n\to\infty}\|x_n - W_n y_n\| = 0$, we obtain $\|x_n - W_n x_n\| \to 0$ as $n \to \infty$.
Moreover, we also have

$$
\|y_n - W_n y_n\| \leq \|y_n - x_n\| + \|x_n - W_n y_n\|.
\tag{3.37}
$$

By (3.34) and $\lim_{n\to\infty}\|x_n - W_n y_n\| = 0$, we obtain $\|y_n - W_n y_n\| \to 0$ as $n \to \infty$.

Step 5. We show that $q \in \theta := \bigcap_{n=1}^{\infty} F(T_n) \cap (\bigcap_{k=1}^{N} \mathrm{SMEP}(F_k)) \cap I(B, M)$ and $\limsup_{n\to\infty}\langle(\gamma f - A)q, W_n y_n - q\rangle \leq 0$. It is easy to see that $P_\theta(\gamma f + (I - A))$ is a contraction of H into itself.
Indeed, since $0 < \gamma < \overline{\gamma}/\epsilon$, we have

$$
\begin{aligned}
\|P_\theta(\gamma f + (I - A))x - P_\theta(\gamma f + (I - A))y\| &\leq \gamma\|f(x) - f(y)\| + \|I - A\|\|x - y\| \\
&\leq \gamma\epsilon\|x - y\| + (1 - \overline{\gamma})\|x - y\| \\
&\leq (1 - \overline{\gamma} + \gamma\epsilon)\|x - y\|.
\end{aligned}
\tag{3.38}
$$

Since H is complete, then there exists a unique fixed point $q \in H$ such that $q = P_\theta(\gamma f + (I - A))(q)$. By Lemma 2.2, we obtain that $\langle(\gamma f - A)q, w - q\rangle \leq 0$ for all $w \in \theta$.
Next, we show that $\limsup_{n\to\infty}\langle(\gamma f - A)q, W_n y_n - q\rangle \leq 0$, where $q = P_\theta(\gamma f + I - A)(q)$ is the unique solution of the variational inequality $\langle(\gamma f - A)q, w - q\rangle \geq 0$ for all $w \in \theta$. We can choose a subsequence $\{y_{n_i}\}$ of $\{y_n\}$ such that

$$
\limsup_{n\to\infty}\langle(\gamma f - A)q, W_n y_n - q\rangle = \lim_{i\to\infty}\langle(\gamma f - A)q, W_n y_{n_i} - q\rangle.
\tag{3.39}
$$

As $\{y_{n_i}\}$ is bounded, there exists a subsequence $\{y_{n_{i_j}}\}$ of $\{y_{n_i}\}$ which converges weakly to w. We may assume without loss of generality that $y_{n_i} \rightharpoonup w$.
Next we claim that $w \in \theta$. Since $\|y_n - W_n y_n\| \to 0$, $\|x_n - W_n x_n\| \to 0$, and $\|x_n - y_n\| \to 0$, and by Lemma 2.6, we have $w \in \bigcap_{n=1}^{\infty} F(T_n)$.

Next, we show that $w \in \bigcap_{k=1}^{\infty} \text{SMEP}(F_k)$. Since $u_n = \tau_{r_k,n}^N x_n$, for $k = 1, 2, 3, \ldots, N$, we know that

$$F_k(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n}\langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C. \tag{3.40}$$

It follows by (A2) that

$$\varphi(y) - \varphi(u_n) + \frac{1}{r_n}\langle y - u_n, u_n - x_n \rangle \geq F_k(y, u_n), \quad \forall y \in C. \tag{3.41}$$

Hence, for $k = 1, 2, 3, \ldots, N$, we get

$$\varphi(y) - \varphi(u_{n_i}) + \frac{1}{r_{n_i}}\langle y - u_{n_i}, u_{n_i} - x_{n_i} \rangle \geq F_k(y, u_{n_i}), \quad \forall y \in C. \tag{3.42}$$

For $t \in (0, 1]$ and $y \in H$, let $y_t = ty + (1 - t)w$. From (3.42), we have

$$0 \geq \varphi(y_t) + \varphi(u_{n_i}) - \frac{1}{r_{n_i}}\langle y_t - u_{n_i}, u_{n_i} - x_{n_i} \rangle + F_k(y_t, u_{n_i}). \tag{3.43}$$

Since $\|u_{n_i} - x_{n_i}\| \to 0$, from (A4) and the weakly lower semicontinuity of φ, $(u_{n_i} - x_{n_i})/r_{n_i} \to 0$ and $u_{n_i} \rightharpoonup w$. From (A1) and (A4), we have

$$\begin{aligned}
0 &= F_k(y_t, y_t) - \varphi(y_t) + \varphi(y_t) \\
&\leq t F_k(y_t, y) + (1 - t)F_k(y_t, w) + t\varphi(y) + (1 - t)\varphi(w) - \varphi(y_t) \\
&\leq t[F_k(y_t, y) + \varphi(y) - \varphi(y_t)].
\end{aligned} \tag{3.44}$$

Dividing by t, we get

$$F_k(y_t, y) + \varphi(y) - \varphi(y_t) \geq 0. \tag{3.45}$$

The weakly lower semicontinuity of φ for $k = 1, 2, 3, \ldots, N$, we get

$$F_k(w, y) + \varphi(y) \geq \varphi(w). \tag{3.46}$$

So, we have

$$F_k(w, y) + \varphi(y) - \varphi(w) \geq 0, \quad \forall k = 1, 2, 3, \ldots, N. \tag{3.47}$$

This implies that $w \in \bigcap_{k=1}^{N} \text{SMEP}(F_k)$.

Lastly, we show that $w \in I(B, M)$. In fact, since B is β-inverse strongly monotone, hence B is a monotone and Lipschitz continuous mapping. It follows from Lemma 2.3 that

$M + B$ is a maximal monotone. Let $(v, g) \in G(M + B)$, since $g - Bv \in M(v)$. Again since $y_{n_i} = J_{M,\lambda}(u_{n_i} - \lambda Bu_{n_i})$, we have $u_{n_i} - \lambda Bu_{n_i} \in (I + \lambda M)(y_{n_i})$, that is, $(1/\lambda)(u_{n_i} - y_{n_i} - \lambda Bu_{n_i}) \in M(y_{n_i})$. By virtue of the maximal monotonicity of $M + B$, we have

$$\left\langle v - y_{n_i}, g - Bv - \frac{1}{\lambda}(u_{n_i} - y_{n_i} - \lambda Bu_{n_i}) \right\rangle \geq 0, \tag{3.48}$$

and hence

$$\langle v - y_{n_i}, g \rangle \geq \left\langle v - y_{n_i}, Bv + \frac{1}{\lambda}(u_{n_i} - y_{n_i} - \lambda Bu_{n_i}) \right\rangle$$

$$= \langle v - y_{n_i}, Bv - By_{n_i} \rangle + \langle v - y_{n_i}, By_{n_i} - Bu_{n_i} \rangle + \left\langle v - y_{n_i}, \frac{1}{\lambda}(u_{n_i} - y_{n_i}) \right\rangle. \tag{3.49}$$

It follows from $\lim_{n\to\infty}\|u_n - y_n\| = 0$, we have $\lim_{n\to\infty}\|Bu_n - By_n\| = 0$ and $y_{n_i} \rightharpoonup w$, it follows that

$$\limsup_{n\to\infty}\langle v - y_n, g \rangle = \langle v - w, g \rangle \geq 0. \tag{3.50}$$

It follows from the maximal monotonicity of $B + M$ that $\theta \in (M + B)(w)$, that is, $w \in I(B, M)$. Therefore, $w \in \theta$. We observe that

$$\limsup_{n\to\infty}\langle (\gamma f - A)q, W_n y_n - q \rangle = \lim_{i\to\infty}\langle (\gamma f - A)q, W_n y_{n_i} - q \rangle = \langle (\gamma f - A)q, w - q \rangle \leq 0. \tag{3.51}$$

Step 6. Finally, we prove $x_n \to q$. By using (3.2) and together with Schwarz inequality, we have

$$\|x_{n+1} - q\|^2 = \|P_C(\epsilon_n \gamma f(x_n) + (I - \epsilon_n A)W_n y_n) - P_C(q)\|^2$$

$$\leq \|\epsilon_n(\gamma f(x_n) - Aq) + (I - \epsilon_n A)(W_n y_n - q)\|^2$$

$$\leq (I - \epsilon_n A)^2 \|(W_n y_n - q)\|^2 + \epsilon_n^2 \|\gamma f(x_n) - Aq\|^2$$

$$\quad + 2\epsilon_n \langle (I - \epsilon_n A)(W_n y_n - q), \gamma f(x_n) - Aq \rangle$$

$$\leq (1 - \epsilon_n \bar{\gamma})^2 \|y_n - q\|^2 + \epsilon_n^2 \|\gamma f(x_n) - Aq\|^2$$

$$\quad + 2\epsilon_n \langle W_n y_n - q, \gamma f(x_n) - Aq \rangle - 2\epsilon_n^2 \langle A(W_n y_n - q), \gamma f(x_n) - Aq \rangle$$

$$\leq (1 - \epsilon_n \bar{\gamma})^2 \|x_n - q\|^2 + \epsilon_n^2 \|\gamma f(x_n) - Aq\|^2 + 2\epsilon_n \langle W_n y_n - q, \gamma f(x_n) - \gamma f(q) \rangle$$

$$\quad + 2\epsilon_n \langle W_n y_n - q, \gamma f(q) - Aq \rangle - 2\epsilon_n^2 \langle A(W_n y_n - q), \gamma f(x_n) - Aq \rangle$$

$$
\begin{aligned}
&\leq (1 - \epsilon_n \bar{\gamma})^2 \|x_n - q\|^2 + \epsilon_n^2 \|\gamma f(x_n) - Aq\|^2 + 2\epsilon_n \|W_n y_n - q\| \|\gamma f(x_n) - \gamma f(q)\| \\
&\quad + 2\epsilon_n \langle W_n y_n - q, \gamma f(q) - Aq \rangle - 2\epsilon_n^2 \langle A(W_n y_n - q), \gamma f(x_n) - Aq \rangle \\
&\leq (1 - \epsilon_n \bar{\gamma})^2 \|x_n - q\|^2 + \epsilon_n^2 \|\gamma f(x_n) - Aq\|^2 + 2\gamma \epsilon \epsilon_n \|y_n - q\| \|x_n - q\| \\
&\quad + 2\epsilon_n \langle W_n y_n - q, \gamma f(q) - Aq \rangle - 2\epsilon_n^2 \langle A(W_n y_n - q), \gamma f(x_n) - Aq \rangle \\
&\leq (1 - \epsilon_n \bar{\gamma})^2 \|x_n - q\|^2 + \epsilon_n^2 \|\gamma f(x_n) - Aq\|^2 + 2\gamma \epsilon \epsilon_n \|x_n - q\|^2 \\
&\quad + 2\epsilon_n \langle W_n y_n - q, \gamma f(q) - Aq \rangle - 2\epsilon_n^2 \langle A(W_n y_n - q), \gamma f(x_n) - Aq \rangle \\
&\leq \left((1 - \epsilon_n \bar{\gamma})^2 + 2\gamma \epsilon \epsilon_n \right) \|x_n - q\|^2 \\
&\quad + \epsilon_n \Big\{ \epsilon_n \|\gamma f(x_n) - Aq\|^2 + 2 \langle W_n y_n - q, \gamma f(q) - Aq \rangle \\
&\quad\quad -2\epsilon_n \|A(W_n y_n - q)\| \|\gamma f(x_n) - Aq\| \Big\} \\
&= (1 - 2(\bar{\gamma} - \gamma \epsilon)\epsilon_n) \|x_n - q\|^2 \\
&\quad + \epsilon_n \Big\{ \epsilon_n \|\gamma f(x_n) - Aq\|^2 + 2 \langle W_n y_n - q, \gamma f(q) - Aq \rangle \\
&\quad\quad - 2\epsilon_n \|A(W_n y_n - q)\| \|\gamma f(x_n) - Aq\| \\
&\quad\quad + \epsilon_n \bar{\gamma}^2 \|x_n - q\|^2 \Big\}.
\end{aligned}
\tag{3.52}
$$

Since $\{x_n\}$ is bounded, where $\eta \geq \|\gamma f(x_n) - Aq\|^2 - 2\|A(W_n y_n - q)\| \|\gamma f(x_n) - Aq\| + \bar{\gamma}^2 \|x_n - q\|^2$ for all $n \geq 0$. It follows that

$$
\|x_{n+1} - q\|^2 \leq (1 - 2(\bar{\gamma} - \gamma \epsilon)\epsilon_n) \|x_n - q\|^2 + \epsilon_n \delta_n,
\tag{3.53}
$$

where $\delta_n = 2\langle W_n y_n - q, \gamma f(q) - Aq \rangle + \eta \alpha_n$. Since $\limsup_{n \to \infty} \langle (\gamma f - A)q, W_n y_n - q \rangle \leq 0$, we get $\limsup_{n \to \infty} \delta_n \leq 0$. Applying Lemma 2.5, we can conclude that $x_n \to q$. This completes the proof. $\qquad\square$

Corollary 3.2. *Let H be a real Hilbert space and C a nonempty closed and convex subset of H. Let B be β-inverse-strongly monotone and $\varphi : C \to \mathcal{R}$ a convex and lower semicontinuous function. Let $f : C \to C$ be a contraction with coefficient α $(0 < \alpha < 1)$, $M : H \to 2^H$ a maximal monotone mapping, and $\{T_n\}$ a family of nonexpansive mappings of H into itself such that*

$$
\theta := \bigcap_{n=1}^{\infty} F(T_n) \cap \left(\bigcap_{k=1}^{N} \mathrm{SMEP}(F_k) \right) \cap I(B, M) \neq 0.
\tag{3.54}
$$

Suppose that $\{x_n\}$ is a sequence generated by the following algorithm for $x_0, u_n \in C$ arbitrarily:

$$u_n = K_{r_n,n}^{F_N} \cdot K_{r_{n-1},n}^{F_{N-1}} \cdot K_{r_{n-2},n}^{F_{N-2}} \cdot \cdots \cdot K_{r_2,n}^{F_2} \cdot K_{r_1,n}^{F_1} \cdot x_n, \quad \forall n \in N$$

$$x_{n+1} = P_C \left[\epsilon_n f(x_n) + (I - \epsilon_n) W_n J_{M,\lambda}(u_n - \lambda B u_n) \right],$$

(3.55)

for all $n = 0, 1, 2, \ldots$, and the conditions (C1)–(C3) in Theorem 3.1 are satisfied.

Then, the sequence $\{x_n\}$ converges strongly to $q \in \theta$, where $q = P_\theta(f + I)(q)$ which solves the following variational inequality:

$$\langle (f - I)q, p - q \rangle \leq 0, \quad \forall p \in \theta.$$

(3.56)

Proof. Putting $A \equiv I$ and $\gamma \equiv 1$ in Theorem 3.1, we can obtain the desired conclusion immediately. □

Corollary 3.3. *Let H be a real Hilbert space and C a nonempty closed and convex subset of H. Let B be β-inverse-strongly monotone, $\varphi : C \to \mathcal{R}$ a convex and lower semicontinuous function, and $M : H \to 2^H$ a maximal monotone mapping. Let $\{T_n\}$ be a family of nonexpansive mappings of H into itself such that*

$$\theta := \bigcap_{n=1}^{\infty} F(T_n) \cap \left(\bigcap_{k=1}^{N} \text{SMEP}(F_k) \right) \cap I(B, M) \neq 0.$$

(3.57)

Suppose that $\{x_n\}$ is a sequence generated by the following algorithm for $x_0, u \in C$ and $u_n \in C$:

$$u_n = K_{r_n,n}^{F_N} \cdot K_{r_{n-1},n}^{F_{N-1}} \cdot K_{r_{n-2},n}^{F_{N-2}} \cdot \cdots \cdot K_{r_2,n}^{F_2} \cdot K_{r_1,n}^{F_1} \cdot x_n, \quad \forall n \in N$$

$$x_{n+1} = P_C [\epsilon_n u + (I - \epsilon_n) W_n J_{M,\lambda}(u_n - \lambda B u_n)],$$

(3.58)

for all $n = 0, 1, 2, \ldots$, and the conditions (C1)–(C3) in Theorem 3.1 are satisfied.

Then, the sequence $\{x_n\}$ converges strongly to $q \in \theta$, where $q = P_\theta(q)$ which solves the following variational inequality:

$$\langle u - q, p - q \rangle \leq 0, \quad \forall p \in \theta.$$

(3.59)

Proof. Putting $f(x) \equiv u$, for all $x \in C$ in Corollary 3.2, we can obtain the desired conclusion immediately. □

Corollary 3.4. *Let H be a real Hilbert space and C a nonempty closed and convex subset of H, and let B be β-inverse-strongly monotone mapping and A a strongly positive linear bounded operator of H into itself with coefficient $\overline{\gamma} > 0$. Assume that $0 < \gamma < \overline{\gamma}/\alpha$. Let $f : C \to C$ be a contraction with coefficient $\alpha(0 < \alpha < 1)$ and $\{T_n\}$ be a family of nonexpansive mappings of H into itself such that*

$$\theta := \bigcap_{n=1}^{\infty} F(T_n) \cap \text{VI}(C, B) \neq \emptyset.$$

(3.60)

Suppose that $\{x_n\}$ is a sequence generated by the following algorithm for $x_0 \in C$ arbitrarily:

$$x_{n+1} = P_C\left[\epsilon_n \gamma f(x_n) + (I - \epsilon_n A)W_n P_C(x_n - \lambda B x_n)\right], \tag{3.61}$$

for all $n = 0, 1, 2, \ldots$, and the conditions (C1)–(C3) in Theorem 3.1 are satisfied.

Then, the sequence $\{x_n\}$ converges strongly to $q \in \theta$, where $q = P_\theta(\gamma f + I - A)(q)$ which solves the following variational inequality:

$$\langle (\gamma f - A)q, p - q \rangle \leq 0, \quad \forall p \in \theta. \tag{3.62}$$

Proof. Taking $F \equiv 0$, $\varphi \equiv 0$, $u_n = x_n$, and $J_{M,\lambda} = P_C$ in Theorem 3.1, we can obtain the desired conclusion immediately. □

Remark 3.5. Corollary 3.4 generalizes and improves the result of Klin-Eam and Suantai [45].

4. Applications

In this section, we apply the iterative scheme (1.25) for finding a common fixed point of nonexpansive mapping and strictly pseudocontractive mapping.

Definition 4.1. A mapping $S : C \rightarrow C$ is called a *strictly pseudocontraction* if there exists a constant $0 \leq \kappa < 1$ such that

$$\|Sx - Sy\|^2 \leq \|x - y\|^2 + \kappa \|(I - S)x - (I - S)y\|^2, \quad \forall x, y \in C. \tag{4.1}$$

If $\kappa = 0$, then S is nonexpansive. In this case, we say that $S : C \rightarrow C$ is a κ-strictly pseudocontraction. Putting $B = I - S$. Then, we have

$$\|(I - B)x - (I - B)y\|^2 \leq \|x - y\|^2 + \kappa \|Bx - By\|^2, \quad \forall x, y \in C. \tag{4.2}$$

Observe that

$$\|(I - B)x - (I - B)y\|^2 = \|x - y\|^2 + \|Bx - By\|^2 - 2\langle x - y, Bx - By \rangle, \quad \forall x, y \in C. \tag{4.3}$$

Hence, we obtain

$$\langle x - y, Bx - By \rangle \geq \frac{1 - \kappa}{2}\|Bx - By\|^2, \quad \forall x, y \in C. \tag{4.4}$$

Then, B is a $((1 - \kappa)/2)$-inverse-strongly monotone mapping.

Using Theorem 3.1, we first prove a strongly convergence theorem for finding a common fixed point of a nonexpansive mapping and a strictly pseudocontraction.

Theorem 4.2. *Let H be a real Hilbert space and C a nonempty closed and convex subset of H, and let B be an β-inverse-strongly monotone, $\varphi : C \to \mathcal{R}$ a convex and lower semicontinuous function, and $f : C \to C$ a contraction with coefficient α ($0 < \alpha < 1$), and let A be a strongly positive linear bounded operator of H into itself with coefficient $\overline{\gamma} > 0$. Assume that $0 < \gamma < \overline{\gamma}/\alpha$. Let $\{T_n\}$ be a family of nonexpansive mappings of H into itself, and let S be a κ-strictly pseudocontraction of C into itself such that*

$$\theta := \bigcap_{n=1}^{\infty} F(T_n) \cap \left(\bigcap_{k=1}^{N} \text{SMEP}(F_k) \right) \cap F(S) \neq 0. \tag{4.5}$$

Suppose that $\{x_n\}$ is a sequence generated by the following algorithm for $x_0, u_n \in C$ arbitrarily:

$$u_n = K_{r_n,n}^{F_N} \cdot K_{r_{n-1},n}^{F_{N-1}} \cdot K_{r_{n-2},n}^{F_{N-2}} \cdot \cdots \cdot K_{r_2,n}^{F_2} \cdot K_{r_1,n}^{F_1} \cdot x_n, \quad \forall n \in N$$

$$x_{n+1} = P_C[\epsilon_n \gamma f(x_n) + (I - \epsilon_n A)W_n(1 - \lambda)x_n + \lambda S x_n], \tag{4.6}$$

for all $n = 0, 1, 2, \ldots$, and the conditions (C1)–(C3) in Theorem 3.1 are satisfied.

Then, the sequence $\{x_n\}$ converges strongly to $q \in \theta$, where $q = P_\theta(\gamma f + I - A)(q)$ which solves the following variational inequality:

$$\langle (\gamma f - A)q, p - q \rangle \leq 0, \quad \forall p \in \theta, \tag{4.7}$$

which is the optimality condition for the minimization problem

$$\min_{q \in \theta} \frac{1}{2} \langle Aq, q \rangle - h(q), \tag{4.8}$$

where h is a potential function for γf (i.e., $h'(q) = \gamma f(q)$ for $q \in H$).

Proof. Put $B \equiv I - T$, then B is $(1 - \kappa)/2$ inverse-strongly monotone and $F(S) = I(B, M)$, and $J_{M,\lambda}(x_n - \lambda B x_n) = (1 - \lambda)x_n + \lambda T x_n$. So by Theorem 3.1, we obtain the desired result. $\square$

Corollary 4.3. *Let H be a real Hilbert space and C a closed convex subset of H, and let B be β-inverse-strongly monotone and $\varphi : C \to \mathcal{R}$ a convex and lower semicontinuous function. Let $f : C \to C$ be a contraction with coefficient α ($0 < \alpha < 1$) and T_n a nonexpansive mapping of H into itself, and let S be a κ-strictly pseudocontraction of C into itself such that*

$$\theta := \bigcap_{n=1}^{\infty} F(T_n) \cap \left(\bigcap_{k=1}^{N} \text{SMEP}(F_k) \right) \cap F(S) \neq 0. \tag{4.9}$$

Suppose that $\{x_n\}$ is a sequence generated by the following algorithm for $x_0 \in C$ arbitrarily:

$$u_n = K_{r_n,n}^{F_N} \cdot K_{r_{n-1},n}^{F_{N-1}} \cdot K_{r_{n-2},n}^{F_{N-2}} \cdot \dots \cdot K_{r_2,n}^{F_2} \cdot K_{r_1,n}^{F_1} \cdot x_n, \quad \forall n \in N$$

$$x_{n+1} = P_C \left[\epsilon_n f(x_n) + (I - \epsilon_n) W_n ((1 - \lambda) u_n + \lambda S u_n) \right], \tag{4.10}$$

for all $n = 0, 1, 2, \ldots$, and the conditions (C1)–(C3) in Theorem 3.1 are satisfied.

Then, the sequence $\{x_n\}$ converges strongly to $q \in \theta$, where $q = P_\theta(f + I)(q)$ which solves the following variational inequality:

$$\langle (f - I)q, p - q \rangle \leq 0, \quad \forall p \in \theta, \tag{4.11}$$

which is the optimality condition for the minimization problem

$$\min_{q \in \theta} \frac{1}{2} \langle Aq, q \rangle - h(q), \tag{4.12}$$

where h is a potential function for γf (i.e., $h'(q) = \gamma f(q)$ for $q \in H$).

Proof. Put $A \equiv I$ and $\gamma \equiv 1$ in Theorem 4.2, we obtain the desired result. □

5. Numerical Example

Now, we give a real numerical example in which the condition satisfies the ones of Theorem 3.1 and some numerical experiment results to explain the main result Theorem 3.1 as follows.

Example 5.1. Let $H = R$, $C = [-1, 1]$, $T_n = I$, $\lambda_n = \beta \in (0, 1)$, $n \in N$, $F_k(x, y) = 0$, for all $x, y \in C$, $r_{n,n} = 1$, $k \in \{1, 2, 3, \ldots, N\}$, $\varphi(x) = 0$, for all $x \in C$, $B = A = I$, $f(x) = (1/5)x$, for all $x \in H$, $\lambda = 1/2$ with contraction coefficient $\alpha = 1/10$, $\epsilon_n = 1/n$ for every $n \in N$, and $\gamma = 1$. Then $\{x_n\}$ is the sequence generated by

$$x_{n+1} = \left(\frac{1}{2} - \frac{3}{10n} \right) x_n, \tag{5.1}$$

and $x_n \to 0$ as $n \to \infty$, where 0 is the unique solution of the minimization problem

$$\min_{x \in C} = \frac{2}{5} x^2 + q. \tag{5.2}$$

Proof. We prove Example 5.1 by Step 1, Step 2, and Step 3. By Step 4, we give two numerical experiment results which can directly explain that the sequence $\{x_n\}$ strongly converges to 0.

Step 1. We show

$$K_{r_n,n}^{F_N} x = P_C x, \quad \forall x \in H, \ F_N \in \{1, 2, 3, \ldots, N\}, \tag{5.3}$$

where

$$P_C x = \begin{cases} \dfrac{x}{|x|}, & x \in H \setminus C \\ x, & x \in C. \end{cases} \tag{5.4}$$

Indeed, since $F_k(x, y) = 0$ for all $x, y \in C$, $n \in \{1, 2, 3, \ldots, N\}$, due to the definition of $K_r(x)$, for all $x \in H$, as Lemma 2.7, we have

$$K_r(x) = \{u \in C : \langle y - u, u - x \rangle \geq 0, \ \forall y \in C\}. \tag{5.5}$$

Also by the equivalent property (2.2) of the nearest projection P_C from $H \to C$, we obtain this conclusion, when we take $x \in C$, $K_{r_n,n}^{F_N} x = P_C x = Ix$. By (iii) in Lemma 2.7, we have

$$\bigcap_{k=1}^{N} \text{SMEP}(F_k) = C. \tag{5.6}$$

Step 2. We show that

$$W_n = I. \tag{5.7}$$

Indeed. By (1.23), we have

$$\begin{aligned} W_1 &= U_{11} = \lambda_1 T_1 U_{12} + (1 - \lambda_1)I = \lambda_1 T_1 + (1 - \lambda_1)I, \\ W_2 &= U_{21} = \lambda_1 T_1 U_{22} + (1 - \lambda_1)I = \lambda_1 T_1 (\lambda_2 T_2 U_{23} + (1 - \lambda_2)I) + (1 - \lambda_1)I \\ &= \lambda_1 \lambda_2 T_1 T_2 + \lambda_1(1 - \lambda_2)T_1 + (1 - \lambda_1)I, \\ W_3 &= U_{31} = \lambda_1 T_1 U_{32} + (1 - \lambda_1)I = \lambda_1 T_1 (\lambda_2 T_2 U_{33} + (1 - \lambda_2)I) + (1 - \lambda_1)I \\ &= \lambda_1 \lambda_2 T_1 T_2 U_{33} + \lambda_1(1 - \lambda_2)T_1 + (1 - \lambda_1)I, \\ &= \lambda_1 \lambda_2 T_1 T_2 (\lambda_3 T_3 U_{34} + (1 - \lambda_3 I)) + \lambda_1(1 - \lambda_2)T_1 + (1 - \lambda_1)I, \\ &= \lambda_1 \lambda_2 \lambda_3 T_1 T_2 T_3 + \lambda_1 \lambda_2(1 - \lambda_3)T_1 T_2 + \lambda_1(1 - \lambda_2)T_1 + (1 - \lambda_1)I. \end{aligned} \tag{5.8}$$

Computing in this way by (1.23), we obtain

$$\begin{aligned} W_n = U_{n1} &= \lambda_1 \lambda_2 \cdots \lambda_n T_1 T_2 \cdots T_n + \lambda_1 \lambda_2 \cdots \lambda_{n-1}(1 - \lambda_n)T_1 T_2 \cdots T_{n-1} \\ &\quad + \lambda_1 \lambda_2 \cdots \lambda_{n-2}(1 - \lambda_{n-1})T_1 T_2 \cdots T_{n-2} + \cdots + \lambda_1(1 - \lambda_2)T_1 + (1 - \lambda_1)I. \end{aligned} \tag{5.9}$$

Since $T_n = I, \lambda_n = \beta, n \in N$, thus

$$W_n = \left[\beta^n + \beta^{n-1}(1 - \beta) + \cdots + \beta(1 - \beta) + (1 - \beta) \right] I = I. \tag{5.10}$$

Table 1: This table shows the value of sequence $\{x_n\}$ on each iteration step (initial value $x_1 = 1$).

n	x_n	n	x_n
1	1.000000000000000	31	0.000000000054337
2	0.200000000000000	32	0.000000000026643
3	0.070000000000000	33	0.000000000013072
4	0.028000000000000	34	0.000000000006417
$\vdots$	$\vdots$	$\vdots$	$\vdots$
19	0.000000301580666	39	0.000000000000184
20	0.000000146028533	40	0.000000000000091
21	0.000000070823839	41	0.000000000000045
$\vdots$	$\vdots$	$\vdots$	$\vdots$
29	0.000000000226469	47	0.000000000000001
30	0.000000000110892	48	0.000000000000000

Step 3. We show that

$$x_{n+1} = \left(\frac{1}{2} - \frac{3}{10n}\right)x_n, \quad x_{n+1} \longrightarrow 0, \text{ as } n \longrightarrow \infty, \tag{5.11}$$

where 0 is the unique solution of the minimization problem

$$\min_{x \in C} \frac{2}{5}x^2 + q. \tag{5.12}$$

Indeed, we can see that $A = I$ is a strongly position bounded linear operator with coefficient $\overline{\gamma} = 1/2$ and γ is a real number such that $0 < \gamma < \overline{\gamma}/\alpha$, so we can take $\gamma = 1$. Due to (5.1), (5.4), and (5.7), we can obtain a special sequence $\{x_n\}$ of (3.2) in Theorem 3.1 as follows:

$$x_{n+1} = \left(\frac{1}{2} - \frac{3}{10n}\right)x_n. \tag{5.13}$$

Since $T_n = I, n \in N$, so,

$$\bigcap_{n=1}^{\infty} F(T_n) = H, \tag{5.14}$$

combining with (5.6), we have

$$\theta := \bigcap_{n=1}^{\infty} F(T_n) \cap \left(\bigcap_{k=1}^{N} \text{SMEP}(F_k)\right) \cap I(B, M) = C = [-1, 1]. \tag{5.15}$$

Table 2: This table shows the value of sequence $\{x_n\}$ on each iteration step (initial value $x_1 = 1/2$).

n	x_n	n	x_n
1	0.500000000000000	31	0.000000000027168
2	0.100000000000000	32	0.000000000013321
3	0.035000000000000	33	0.000000000006536
4	0.014000000000000	34	0.000000000003208
⋮	⋮	⋮	⋮
19	0.000000150790333	39	0.000000000000092
20	0.000000073014267	40	0.000000000000045
21	0.000000035411919	41	0.000000000000022
⋮	⋮	⋮	⋮
29	0.000000000113235	46	0.000000000000001
30	0.000000000055446	47	0.000000000000000
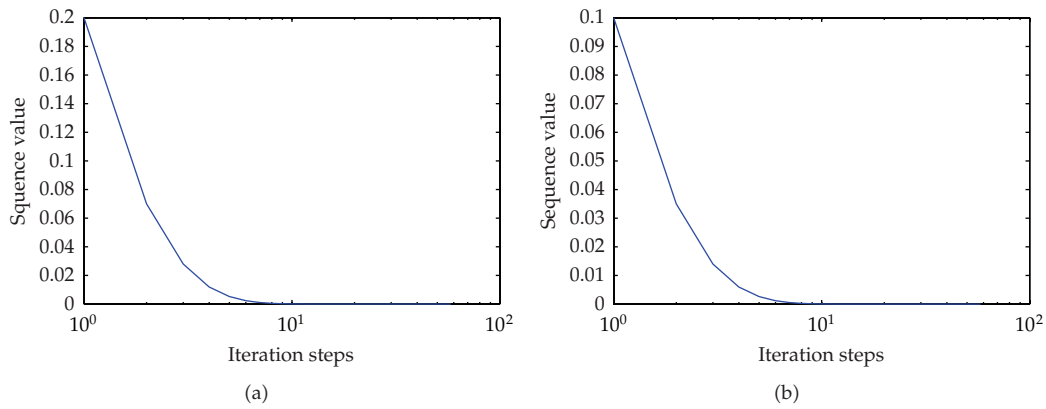
Figure 1: The iteration comparison chart of different initial values. (a) $x_1 = 1$ and (b) $x_1 = 1/2$.

By Lemma 2.5, it is obviously that $z_n \rightarrow 0$, 0 is the unique solution of the minimization problem

$$\min_{x \in C} \frac{2}{5} x^2 + q,\tag{5.16}$$

where q is a constant number.

Step 4. We give the numerical experiment results using software Mathlab 7.0 and get Table 1 to Table 2, which show that the iteration process of the sequence $\{x_n\}$ is a monotone-decreasing sequence and converges to 0, but the more the iteration steps are, the more showily the sequence $\{x_n\}$ converges to 0. □

Now, we turn to realizing (3.2) for approximating a fixed point of T. We take the initial valued $x_1 = 1$ and $x_1 = 1/2$, respectively. All the numerical results are given in Tables 1 and 2. The corresponding graph appears in Figures 1(a) and 1(b).

The numerical results support our main theorem as shown by calculating and plotting graphs using Matlab 7.11.0.

Acknowledgments

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