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Influence of uncertainties of the empirical models for inferring the E-region electric fields at the dip equator

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Abstract

Daytime E-region electric fields play a crucial role in the ionospheric dynamics at the geomagnetic dip latitudes. Due to their importance, there is an interest in accurately measuring and modeling the electric fields for both climatological and near real-time studies. In this work, we present the daytime vertical (E_z) and eastward (E_y) electric fields for a reference quiet day (February 7, 2001) at the São Luís Space Observatory, Brazil (SLZ, 2.31°S, 44.16°W). The component E_z is inferred from Doppler shifts of type II echoes (gradient drift instability) and the anisotropic factor, which is computed from ion and electron gyro frequencies as well as ion and electron collision frequencies with neutral molecules. The component E_y depends on the ratio of Hall and Pedersen conductivities and E_z . A magnetic field-line-integrated conductivity model is used to obtain the anisotropic factor for calculating E_z and the ionospheric conductivities for calculating E_y . This model uses the NRLMSISE-00, IRI-2007, and IGRF-11 empirical models as input parameters for neutral atmosphere, ionosphere, and geomagnetic field, respectively. Consequently, it is worth determining the uncertainties (or errors) in E_y and E_z associated with these empirical model outputs in order to precisely define the confidence limit for the estimated electric field components. For this purpose, errors of $\pm 10\%$ were artificially introduced in the magnitude of each empirical model output before estimating E_y and E_z . The corresponding uncertainties in the ionospheric conductivity and electric field are evaluated considering the individual and cumulative contribution of the artificial errors. The results show that the neutral densities and temperature may be responsible for the largest changes in E_y and E_z , followed by changes in the geomagnetic field intensity and electron and ions compositions.

Keywords: Space weather, Equatorial aeronomy, E-region electric fields, Empirical models

Introduction

Ionospheric electric fields and their time variations play a dominant role in the ionospheric electrodynamic at low latitudes, especially during daytime at the E-region height in the low-latitude ionosphere (Denardini et al. 2013). The basic global mechanism that generates these electric fields in the ionosphere is known to be the global dynamo action of neutral winds. The zonal electric field (E_y), which is eastward (geographic coordinates) during daytime, controls vertical plasma transport in the

low-latitude ionosphere (Fejer 1997). It also forms a critical input to models that predict ionospheric disturbances in real time (Maruyama et al. 2005; Scherliess et al. 2006). The E_y component drives an eastward Pedersen current and a downward Hall current. Inhibition of the Hall current results in the development of a large vertical Hall polarization electric field (E_z). As a result, E_z induces a strong eastward Hall current, thus enhancing ionospheric conductivity in the equatorial electrojet (EEJ) region (Forbes 1981). Therefore, the EEJ current is strongly dependent on the primary electric field (i.e., E_y), the polarization electric field (i.e., E_z), and ionospheric conductivity (Reddy 1981).

In long-term studies on the equatorial ionosphere, continuous monitoring of E_y and E_z at all ionospheric

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heights and several longitudinal sectors is necessary. Such monitoring leads to a clearer understanding of the EEJ, E- and F-region irregularities, pre-reversal vertical drift (eastward electric field enhancement), spread-F, and Appleton anomaly. Consequently, the ionospheric electric fields have widely been studied using radars, magnetometers, ionosondes, and satellites for many years (see, for example, Woodman 1972; Singh and Cole 1987; Crain et al. 1993; Fejer and Scherliess 1997; Hysell and Burcham 2000; Fejer et al. 2008; Aveiro et al. 2009a, b; Denardini et al. 2009, 2011, 2013, 2015).

The E-region electric fields (EEF) can be inferred from measurements of the Doppler frequency of type II echoes detected by VHF radars. Type II echoes are observed whenever the density gradient has a positive projection along E_z . The Doppler frequency of type II echoes is proportional to E_z , which is related to E_y through the ionospheric conductivities (Cohen 1973; Reddy 1977).

Hall and Pedersen ionospheric conductivities can be computed entirely from the classical conductivity equations reviewed by Forbes (1981), collision frequency expressions given by Bailey and Balan (1996), neutral atmosphere constituents provided by the Mass Spectrometer and Incoherent Scatter Model (Picone et al. 2002), NRLMSISE-00 (hereafter written as MSIS), ionospheric densities based on the International Reference Ionosphere (IRI) model (Bilitza and Reinisch 2008), and the geomagnetic field strength given by the International Geomagnetic Reference Field (IGRF) Model (Finlay et al. 2010). These empirical models, since their first publication, have undergone periodic modifications in attempts to improve their accuracy in representing the neutral atmosphere, ionosphere, and geomagnetic field parameters, respectively, as functions of height, geographic coordinates, local time, and sunspot number. However, these models seem to be less accurate at the equatorial and low-latitude regions in the American sector, a region with diverse electrodynamics and dynamic ionospheric processes, with some being affected by the large magnetic declination angle characteristic of this region (Abdu et al. 1990, 2004). Therefore, it is worth determining the uncertainties (or errors) in the EEF associated with eventual inaccuracies in the MSIS, IRI, and IGRF models. As a result, we can precisely define the confidence limit for the E_y and E_z estimates. In this report, for the first time, the electric field components estimated from the backscatter coherent radar (RESCO) data are examined in detail with 10 % artificially underestimated and overestimated MSIS-2000, IRI-2007, and IGRF-11 outputs. The corresponding uncertainties in the ionospheric conductivities and electric field estimates are evaluated considering the individual and cumulative contributions of the artificial uncertainties from each model.

Coherent radar, electric field inference, and conductivity model

In the following sections, we briefly describe the basic operational parameters of the radar for observing 3-m EEJ waves used in this study. The detailed methodology to infer the EEF is also provided. Finally, the magnetic field-line-integrated ionospheric conductivity model, used for E_y and E_z inference, is described from the original to the current version.

RESCO radar operational parameters

The RESCO radar westward oblique beam (30° in zenith angle, geographic coordinates) data collected on February 7, 2001 (reference quiet day for the present study) are analyzed. The radar is located at the São Luís Space Observatory, São Luís, Brazil (SLZ/INPE-MCTI, 2.31°S, 44.16°W). It operates at 50 MHz, and it is sensitive to the 3-m field aligned irregularities. The peak power used for the present experiment was 40 kW. A collinear coaxial (COCO) array antenna is used for transmission and reception. In order to make observations of the daytime E-region irregularities, RESCO operates with pulse width of 20 μ s and inter-pulse period of 1 ms. Using a sampling gate pulse of constant delay, the time variations of the radar signal parameters corresponding to a fixed radar range have been recorded to cover the height range from about 80 to 120 km, with a height resolution of 2.6 km and 2-min time resolution. The ranges of radar heights used in this work are as follows: from 101.3 to 103.9 km, centered at 102.5 km; from 103.9 to 106.5 km, centered at 105.1 km; from 106.5 to 109.1 km, centered at 107.7 km; and from 109.1 to 111.7 km, centered at 110.3 km. A detailed description of the RESCO and examples of observations are given by Abdu et al. (2002) and Denardini et al. (2004, 2005, 2006, 2009, 2015).

Methodology to infer the E-region electric fields

The RESCO data collected on February 7, 2001, revealed the presence of EEJ plasma irregularities from 8 to 18 LT. In addition, there were no magnetic disturbances on this day ($\sum Kp = 13^-$). Therefore, these data were selected to serve as the probe data in the present study. The purpose of the basic radar data analysis was to determine the representative Gaussian parameters through estimates of the moment similar to that used by Reddy et al. (1987). The Doppler frequency of type II irregularities is obtained from the Gaussian center of frequency distribution and is converted into Doppler velocity (V_{DII}) taking into account the RESCO operating frequency and the speed of light. V_{DII} , in turn, is associated with the drift velocity of E-region electrons (V_e) through the following relation (Reddy 1977):

$$V_e = V_{DII}(1 + \Psi_0), \quad (1)$$

where $\Psi_0 = v_{in}v_{en}/\Omega_i\Omega_e$ is known as anisotropic factor, v_{in} and v_{en} are the ion–neutral and electron–neutral collision frequencies, respectively. The anisotropic factor is ≈ 0.3 near the center of the EEJ region (Fejer and Kelley 1980). The ions and electron gyro frequencies are calculated by the following expressions:

$$\Omega_i = \frac{q_i B}{m_i}, \quad (2a)$$

$$\Omega_e = \frac{q_e B}{m_e}, \quad (2b)$$

where $m_{i,e}$ is the mass average, $q_{i,e}$ is the electrical charge, and B is the Earth's magnetic field flux density. The subscripts i and e indicate ion and electron terms, respectively. The Doppler velocities of type II irregularities are proportional to E_z , as given in Eq. 3 (Cohen 1973; Reddy 1977):

$$E_z = \frac{V_{DII}(1 + \Psi_0) B^2}{\sin(\Theta) H}, \quad (3)$$

where Θ is the zenith angle of the radar beam and H is the horizontal component of the geomagnetic field. Physical features of the EEJ were examined by Richmond (1973) using a numerical model, which includes the two-stream instability. He showed that the electric field and current at a given point are strongly dependent on conditions along the entire magnetic field line. Therefore, a conductivity model is used to calculate the Hall (σ_H) and Pedersen (σ_P) conductivities along the magnetic meridian overhead the RESCO radar site, and the field line coordinates with grid resolution of 1 km in vertical and magnetic north–south directions, in order to infer E_y using Eq. 4 (Richmond 1973):

$$E_y = \frac{\int_{-\theta}^{+\theta} \sigma_P \mathbf{r} \cdot d\boldsymbol{\theta}}{\int_{-\theta}^{+\theta} \sigma_H \mathbf{r} \cdot d\boldsymbol{\theta}} \cdot E_z \Rightarrow E_y = \frac{\Sigma_P}{\Sigma_H} \cdot E_z. \quad (4)$$

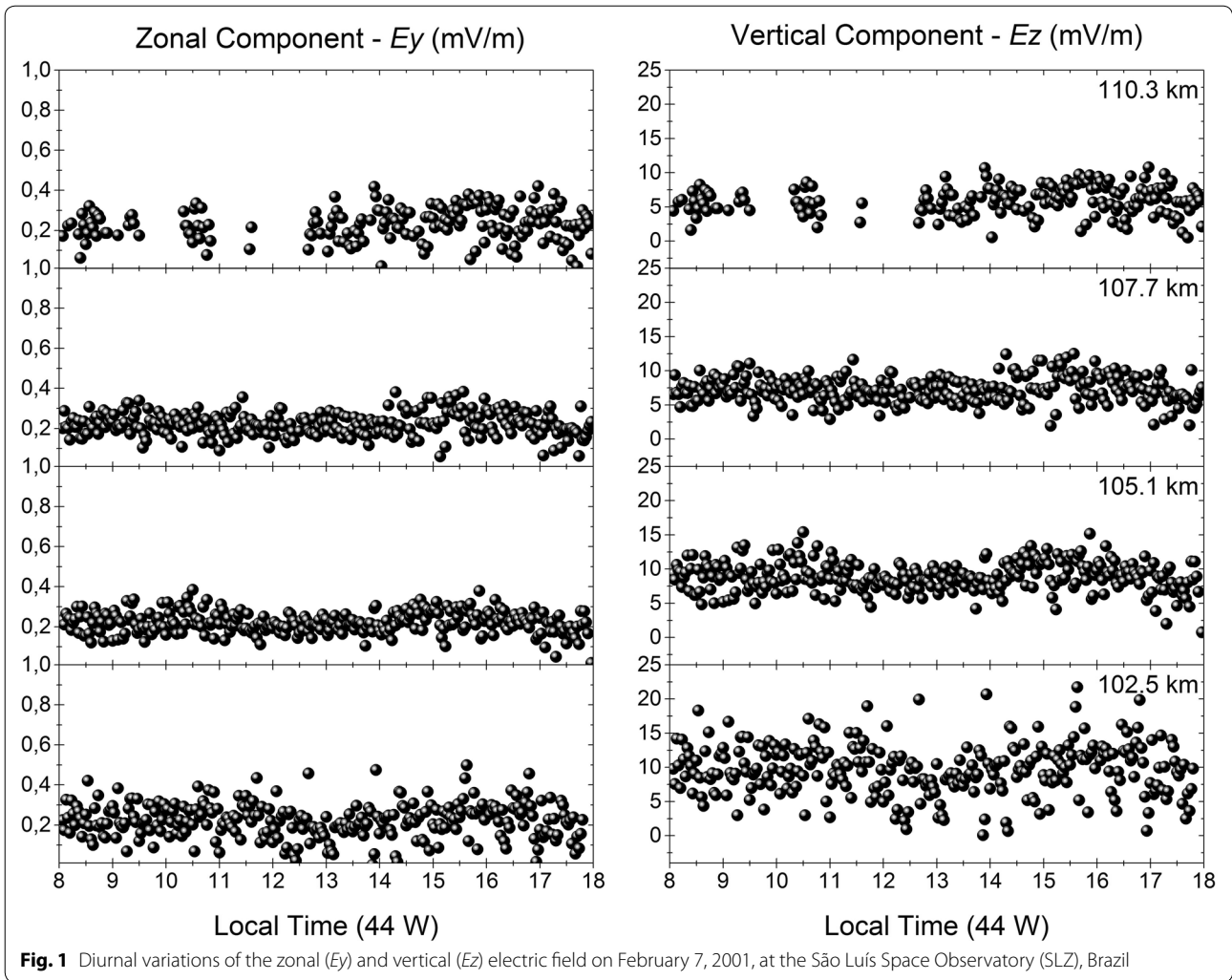
In Eq. 4, \mathbf{r} is the position of the magnetic field line element considering dipole geometry, θ is the magnetic latitude, $d\boldsymbol{\theta}$ is the differential magnetic latitude element vector, and Σ_H and Σ_P are the Hall and Pedersen field-line-integrated conductivities, respectively.

The diurnal variation of the E_y and E_z inferred from the RESCO measurement on February 7, 2001, is shown in Fig. 1. The vertical axes are set in mV/m, and the local time (44°W) runs along the horizontal axes. The graphs of the figure correspond to the four height ranges centered at 110.3, 107.7, 105.7 and 102.5 km used in this study (shown on the top right corner of each graph in right panel). The main features of the E_y and E_z components are: E_y shows a diurnal variability that varies from 0.01 to 0.51 mV/m, depending on the height range of

the observation. The mean diurnal E_y in the four height ranges is 0.22 ± 0.04 mV/m. The E_z component varies from 0.51 to 20.67 mV/m. The mean diurnal E_z is 8.12 ± 1.51 mV/m. The geomagnetic field-line-integrated ionospheric conductivity model used to calculate the ionospheric conductivities in Eq. 4 will be briefly discussed in the next section since it has recently been updated to include more realistic atmospheric parameters.

Magnetic field-line-integrated ionospheric conductivity model

The magnetic field-line-integrated conductivity model was developed by Denardini (2007). It is essentially composed of: (a) neutral densities and temperature provided by the MSIS model; (b) electron density and ions compositions in the momentum transfer collision frequency equation provided by the IRI model; (c) adjustments to the mean electron density obtained from f_oE at three stations across the magnetic equator to compensate the IRI underestimation of the E-region peak density in the Brazilian sector (Abdu et al. 2004); and (d) geomagnetic field strength and its horizontal component provided by the IGRF model. The summary of the information given in this section is provided in the flowchart of “Appendix.” The ion–neutral and electron–neutral collision frequencies were calculated by equations given by Chapman (1956) and Kelley (1989). The model offered results consistent with the conductivity model developed by the Kyoto University. Later, this model was extended (version 2009) to include several ionic and neutral species by Denardini et al. (2013). A new set of ion–neutral and electron–neutral collision frequencies was included, and the momentum transfer collision frequency equation was used to balance these rates (Bailey and Balan 1996; Schunk and Nagy 2004). A further extension of the model (version 2015) includes the daily Ap index (a measurement of the geomagnetic activity related to the space weather) and the F10.7 solar flux, which corresponds to the electromagnetic solar emission at wavelength of 10.7 cm (equivalent to the 2.8 GHz frequency, measured in $\text{sfu} = 10^{-22} \text{ W m}^{-2} \text{ Hz}^{-1}$). The integrated solar flux density at 10.7 cm wavelength was used as a proxy for the solar activity due to its known relation to ionizing radiation and terrestrial effects (Chatterjee and Das 1995). Indeed, the F10.7 does not interact with the Earth's atmosphere. It is considered to be a good generalized solar proxy for EUV irradiance (which ionizes it) since the F10.7 originates from the cool corona, a solar region that is closely coupled with magnetic structures responsible for creating the XUV–EUV irradiances (Bruevich et al. 2014). The 81-day average of F10.7 solar flux was included as well.



The momentum transfer collision frequency equation for the i th molecular ion (molecular oxygen: O_2^+ , nitric oxide: NO^+ , atomic oxygen: O^+), when the winds and relative velocities between ions are neglected, is (for deductions, see Bailey and Balan 1996):

$$g \sin(I) + \frac{k_B T}{m_i N_i} \frac{\partial N_i}{\partial s} + \frac{k_B T}{m_i N_e} \frac{\partial N_e}{\partial s} + \frac{k_B}{m_i} \frac{\partial(2T)}{\partial s} + \sum_n \nu_{in} = 0, \tag{5}$$

where g is the acceleration due to gravity, I is the inclination angle of the magnetic field from the horizontal, k_B is the Boltzmann constant, T is neutral temperature, N_i represents ion densities, N_e represents electron density, s is the distance along magnetic field line, and ν_{in} is the collision frequency for momentum transfer between the i th ion and the n th neutral gas. The collision frequencies for momentum transfer between ions and electron with neutrals are given in Table 1. These collision frequency expressions are obtained from Bailey and Balan (1996),

which describe the Sheffield University Plasmasphere Ionosphere Model (SUPIM). SUPIM has been developed over the last three decades and includes numerous physical and chemical processes of the Earth’s mid- and low-latitude ionosphere and plasmasphere (Bailey et al. 1997). The set of collision frequencies presented in Table 1 was also used to infer the E-region electric fields by Denardini et al. (2013, 2015).

The neutral densities of O, O_2 , and N_2 are represented by $n(O)$, $n(O_2)$, and $n(N_2)$, respectively. The electron and ion temperatures were approximated to the neutral temperature, which is possible without significantly affecting the conductivity in the lower E-region (Denardini 2007). The last term in Eq. 5 can be written as $\nu_{in} = \sum_{k=1}^9 \nu_k$, and the electron–neutral collision frequency is the summation of $\nu_{en} = \sum_{k=1}^3 \nu_k$, as shown in the second column in Table 1.

One of the outputs of the geomagnetic field-line-integrated ionospheric conductivity model is the collision

Table 1 Collision frequencies for momentum transfer between ions and electrons with neutrals (s^{-1})

Molecular oxygen (O_2^+)–neutral	$\nu_{in} = \sum_{k=1}^9 \nu_k$
$\nu_{O_2^+ \rightarrow O} = 2.31 \times 10^{-10} n(O)$	
$\nu_{O_2^+ \rightarrow O_2} = 2.59 \times 10^{-11} n(O_2) T^{\frac{1}{2}} (1 - 0.073 \log T)^2$	
$\nu_{O_2^+ \rightarrow N_2} = 4.13 \times 10^{-10} n(N_2)$	
Nitric oxide (NO^+)–neutral	
$\nu_{NO^+ \rightarrow O} = 2.44 \times 10^{-10} n(O)$	
$\nu_{NO^+ \rightarrow O_2} = 4.27 \times 10^{-10} n(O_2)$	
$\nu_{NO^+ \rightarrow N_2} = 4.34 \times 10^{-10} n(N_2)$	
Atomic oxygen (O^+)–neutral	
$\nu_{O^+ \rightarrow O} = 4.45 \times 10^{-11} n(O) T^{\frac{1}{2}} (1.04 - 0.067 \log T)^2$	
$\nu_{O^+ \rightarrow O_2} = 6.64 \times 10^{-10} n(O_2)$	
$\nu_{O^+ \rightarrow N_2} = 6.82 \times 10^{-10} n(N_2)$	
Electron–neutral	$\nu_{en} = \sum_{k=1}^3 \nu_k$
$\nu_{e \rightarrow O} = 8.9 \times 10^{-11} n(O) (1 + 5.7 \times 10^{-4} T) T^{\frac{1}{2}}$	
$\nu_{e \rightarrow O_2} = 1.82 \times 10^{-10} n(O_2) (1 + 3.6 \times 10^{-2} T^{\frac{1}{2}}) T^{\frac{1}{2}}$	
$\nu_{e \rightarrow N_2} = 2.33 \times 10^{-11} n(N_2) (1 - 1.21 \times 10^{-4} T) T$	

frequencies for ions and electrons with neutral gas as functions of altitude. Figure 2 shows an example of the variations of the ion (continuous line) and electron (dashed lines) collision frequencies at 12 LT on February 7, 2001, without introducing any uncertainty, i.e., using the standard values provided by the composing model. It is seen that in the lower E-region (90 km), ν_{en} is higher than $3 \times 10^6 s^{-1}$ and decreases to about $2 \times 10^3 s^{-1}$ at 130 km. On the other hand, ν_{in} decreases from around to $8 \times 10^5 s^{-1}$ to about $4 \times 10^2 s^{-1}$ in the same height

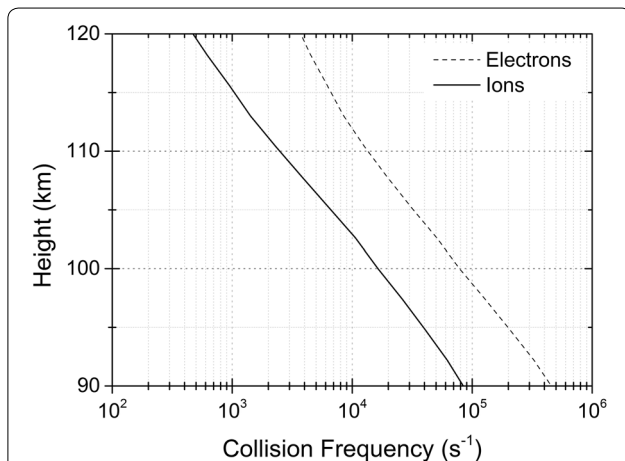


Fig. 2 Vertical profiles of the collision frequencies for ions (continuous line) and electrons (dashed line) with neutral gas as functions of altitude at 12 LT on February 7, 2001, at the São Luís Space Observatory (SLZ), Brazil

range. Therefore, this figure can be taken as an example of the classical behavior of the collision frequency, with the electron–neutral collision frequency (ν_{en}) always having larger magnitude than the ions–neutral collision frequency (ν_{in}).

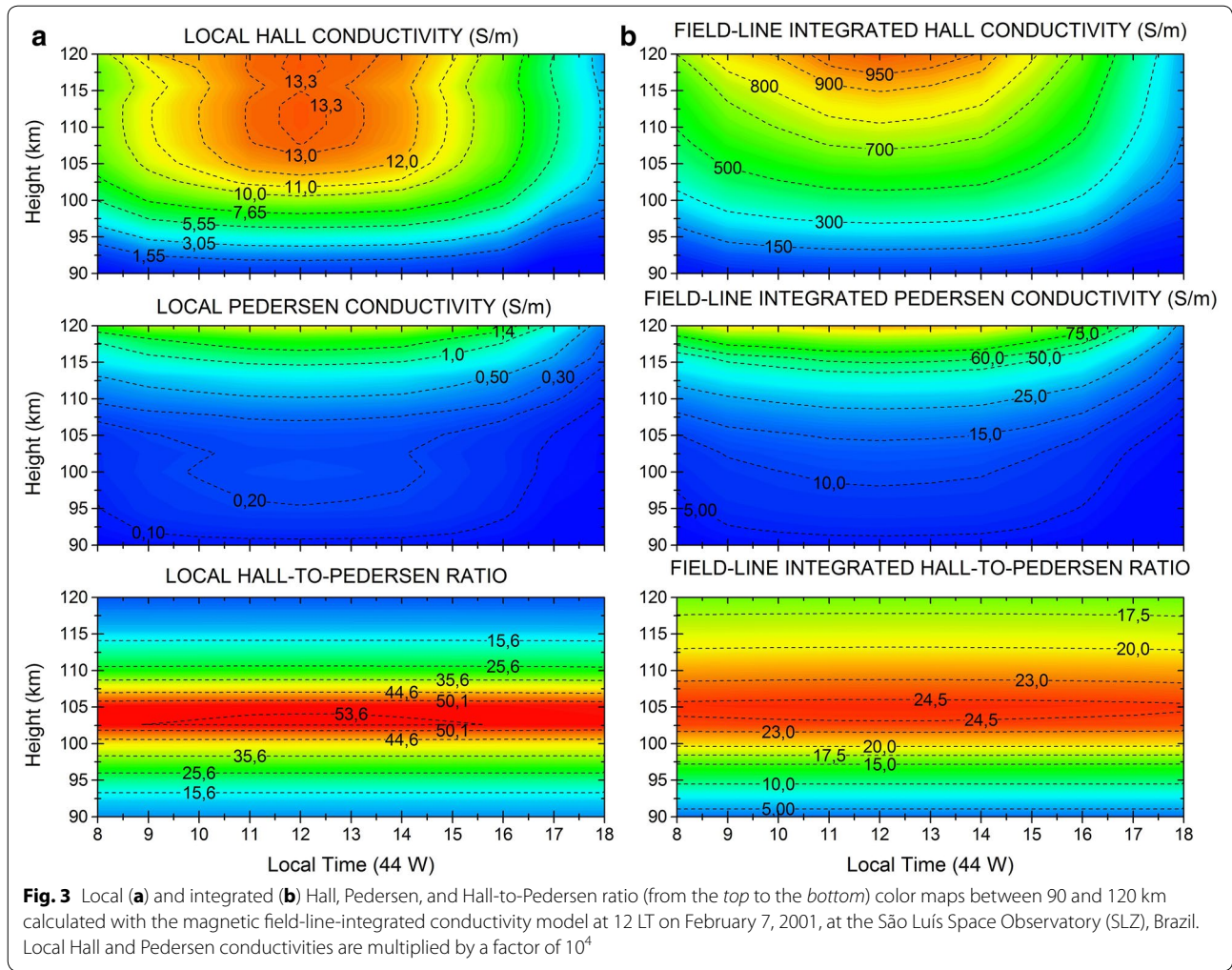
The collision frequency all over the E-region in our model was analyzed, and the typical altitude distribution of the daytime local Hall (σ_H) and Pedersen (σ_P) conductivity, and Hall-to-Pedersen ratio (σ_{HP}) is presented as color maps between 90 and 120 km in Fig. 3a (from top to bottom). These maps are essentially vertical profiles of the corresponding quantities grouped in the proper temporal sequence with a time resolution of 2 min (the same as for the electric fields presented in Fig. 1). Note that a 10^{-4} factor of magnitude scale is applied in the local profiles of Hall and Pedersen conductivities. The color scale represents the intensity of the conductivities in S/m.

As shown, σ_H and σ_P grow with height due to the decrease in the collision frequencies for both ions and electrons. It is clear that σ_H is larger than σ_P between 90 and 120 km. The daily peak of σ_H occurs from 10:30 to 13:30 LT between 105 and 120 km. Below 100 km, σ_H decreases to 50 % as compared to the maximum intensity at 12 LT. At an altitude of 130 km (not shown here), the Hall conductivity reaches its maximum and then decreases rapidly with height because the drift motion at decreasing collision rates does not lead to charge separation anymore.

The Pedersen conductivity initially increases with height due to decreasing collision frequency. It reaches its maximum at ~ 150 km (not shown here) and then gradually decreases to the reduction in collision between particles, leading to a purely drift motion. The local Hall-to-Pedersen conductivity ratio shows a maximum of 53 at the central region of the EEJ during the reference day soundings (on February 7, 2001). Field-line-integrated Hall (Σ_H), Pedersen (Σ_P), and Hall-to-Pedersen ratio (Σ_{HP}) calculated by Eq. 4 are also shown in Fig. 3b. The ratio Σ_{HP} is typically around 25 at ~ 105 km, decreasing in both downward and upward directions.

Methods

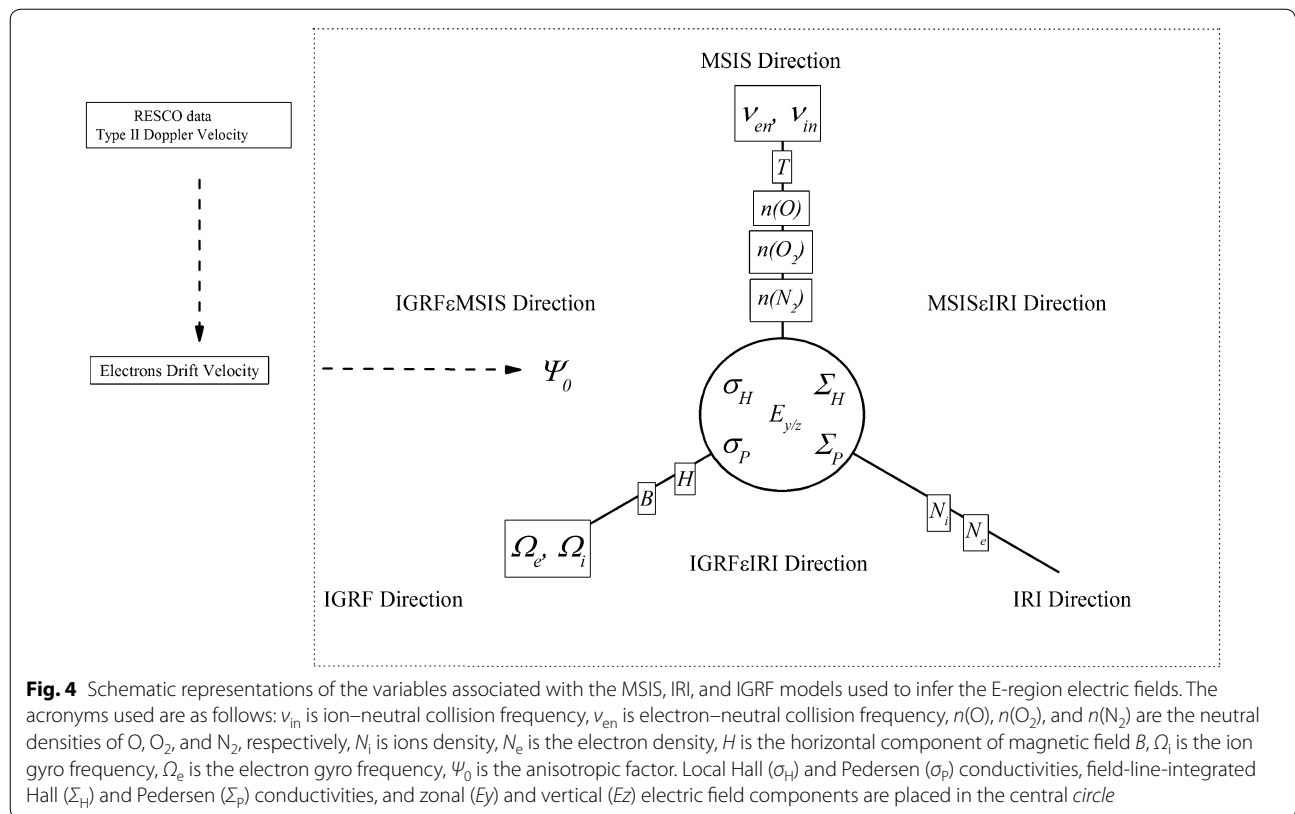
In the following, we describe the methodology for evaluating the empirical models, which are components of the magnetic field-line-integrated conductivity model, providing most of the variables needed to infer the EEf (from Eqs. 1 to 5). Figure 4 shows a schematic representation of these variables associated with the respective empirical model. In this diagram, the variables provided by each one of the three model dimensions are aligned with one of the three axes lines (named after the model) representing a three-dimensional diagram, which start in the center of the circle and extend to the periphery.



Each axis represents an independent dimension meaning the influence of each empirical model in the resulting electric field. The MSIS dimension label is placed in the vertical axis and the model outputs T , $n(O)$, $n(O_2)$, and $n(N_2)$ are placed along its axis. Since these variables are used to calculate the electron–neutral and ion–neutral collision frequencies, ν_{en} and ν_{in} are positioned on this axis as well. The IRI and IGRF dimensions are placed in the clockwise direction in the next two axes. Also, their model outputs, N_e , N_i and B , H , are placed along the respective axis. Once B is used to calculate the ions and electron gyro frequencies, Ω_i and Ω_e are also located in the IGRF dimension. The terms depending on the three empirical models are placed in the central circle: local conductivities (Hall and Pedersen), field-line-integrated conductivities (Hall and Pedersen), and E_y and E_z components of the electric fields. As mentioned above, ν_{en} , ν_{in} , Ω_e , and Ω_i are used to compute the anisotropic

factor. Therefore, Ψ_0 is placed between the IGRF and MSIS in the “IGRF ϵ MSIS” direction. Type II Doppler velocity derived from the EEJ radar soundings is located in the upper left rectangle. They are related to E-region electron drift velocity through Eq. 1.

Considering this three-dimensional diagram, we performed several runs of the magnetic field-line-integrated conductivity model. In each of the runs, the magnitude of the empirical model outputs (the variable over the axis) was artificially increased/decreased by $\pm 10\%$, and the impact on the E_y and E_z was evaluated in order to determine the uncertainties associated with the conditions established in that specific run. Accordingly, 12 runs were carried out, with six of them underestimating the model outputs (alone and two-by-two) by 10% and six others overestimating them. Therefore, the confidence limit of the electric field estimates can be defined in this 3-D system based on such evaluation.



Results

The results of the 12 runs described in the methodology are given in Table 2.

The first two columns of the table provide information about the modification applied to the amplitude of the variables provided by empirical models composing the geomagnetic field-line-integrated conductivity model during runs. The first column lists the modified models and the second column lists models without any changes in their quantities during the simulation. The subscripts O and U indicate that the magnitude of the variables of the composing model was artificially *overestimated* or *underestimated* by 10 %, respectively. For instance, the first line in Table 2 specifies that E_y and E_z were inferred when the magnitude of the T , $n(O)$, $n(O_2)$, and $n(N_2)$ (which are the MSIS outputs) were artificially underestimated (U) by 10 %, while the magnitude of the N_e , N_i , B , and H remained as they were provided by the IRI and IGRF models to that specific run.

The last two columns of Table 2 show the daily averaged percentage variation of the electric field components obtained considering the applied changes on the magnitude of the variables (first column) with respect to the same electric field component with no modification in the variables provided by the MSIS, IRI, and IGRF models, as per the following equations:

Table 2 Results of the ΔE_y and ΔE_z evaluation when variables provided by the MSIS, IRI, and IGRF models are artificially underestimated (U) or overestimated (O) by 10 %

Model status during the run		Daily averaged uncertainties	
Altered	Constant	ΔE_y (%)	ΔE_z (%)
MSIS _(U)	IRI, IGRF	−9.46	−9.87
MSIS _(O)	IRI, IGRF	+14.22	+12.00
MSIS&IRI _(U)	IGRF	−5.25	−12.58
MSIS&IRI _(O)	IGRF	+13.39	+16.89
IRI _(U)	IGRF, MSIS	+3.01	−3.70
IRI _(O)	IGRF, MSIS	−2.16	+3.70
IGRF&IRI _(U)	MSIS	+8.47	+4.11
IGRF&IRI _(O)	MSIS	−6.36	−3.36
IGRF _(U)	IRI, MSIS	+6.55	+8.68
IGRF _(O)	IRI, MSIS	−3.67	−6.42
IGRF&MSIS _(U)	IRI	−6.71	−3.50
IGRF&MSIS _(O)	IRI	+6.96	+3.49

$$\Delta E_y = \frac{E_{yU/O} - E_y}{E_y} \times 100, \tag{6a}$$

$$\Delta E_z = \frac{E_{zU/O} - E_z}{E_z} \times 100. \tag{6b}$$

In Eqs. 6a and 6b, E_y and E_z are the electric field components inferred from the runs with no modification in the variables provided by the MSIS, IRI, and IGRF models, while the $E_{y_{U/O}}$ and $E_{z_{U/O}}$ are the electric field components inferred from the runs with the variables provided by the models underestimated (U) or overestimated (O) by 10 % according to the indication in the first column. The ΔE_y and ΔE_z are, therefore, considered the daily averaged “uncertainties” introduced in the calculations due to the underestimation or overestimation in the empirical models.

Discussions

The results presented above were briefly discussed in Denardini et al. (2015) in terms of the simultaneous underestimation and overestimation of the variables provided by the MSIS, IRI, and IGRF models. Now, we focus the discussions in terms of the individual contributions of eventual underestimations and overestimations in the empirical models as well as simultaneous underestimations or overestimations in two out of three models. In addition, we discuss in the following paragraphs the consequences of these uncertainties in the E-region during daytime. We analyze it in terms of the electric fields, changes in ionospheric conductivities during the radar operation, and the linear fit applied between the EEF components inferred on February 7, 2001, and the corresponding components inferred from the 12 simulations ($E_{y_{U/O}}$ and $E_{z_{U/O}}$) given in Table 2.

Analysis of the uncertainties in the electric field components

From the results presented in Table 2, it is evident that the degree of uncertainties in the variables provided by the empirical models will lead to uncertainties in electric field estimations based on the coherent radar measurements. Also, the variation in the amplitudes of the outputs from some empirical models causes more uncertainties in the electric fields than others. For instance, changes in the amplitude of the variable provided by $MSIS_{\epsilon IRI_{(O)}}$ lead to much more uncertainty in the electric field components than changes in the amplitude of the variables provided by $IRI_{(O)}$ alone.

The observed daily averaged uncertainties are highest in runs that involve changes in the amplitude of the variables provided by the MSIS (alone and two-by-two with IRI model: $MSIS_{(U)}$, $MSIS_{(O)}$, $MSIS_{\epsilon IRI_{(U)}}$, and $MSIS_{\epsilon IRI_{(O)}}$), lowest when the IRI outputs are changed ($IRI_{(U)}$, $IRI_{(O)}$), and moderate in the remaining runs. The higher values in ΔE_y and ΔE_z observed in this analysis are +14.22 % in the $MSIS_{(O)}$ run and +16.89 % in the $MSIS_{\epsilon IRI_{(O)}}$, respectively. The lower uncertainties in ΔE_y is -2.16 % in the $IRI_{(O)}$ run and in ΔE_z is 3.36 % in the

$IGRF_{\epsilon IRI_{(O)}}$. In regard to changes in the amplitude of the variable provided by the IGRF models, we observed that the electric field components present moderate daily averaged uncertainties. Also, it is seen that out of 12 simulations, 3 show uncertainties higher than 10 % ($MSIS_{(O)}$, $MSIS_{\epsilon IRI_{(O)}}$, and $MSIS_{\epsilon IRI_{(U)}}$) and 2 show uncertainties <5 % in both components ($IRI_{(U)}$ and $IRI_{(O)}$). It is strongly evidenced that any variation in the MSIS outputs leads to much more uncertainty in the EEF, whereas variations in the IRI outputs cause much smaller effects.

Analysis of diurnal conductivity profiles

Some implications of the uncertainties coming from the variables provided by the empirical models are more clearly visible by analyzing the Hall-to-Pedersen field-line-integrated conductivity ratio profiles (Σ_{HP}), given that this ratio is directly used in Eq. 4. In order to evaluate them, we took the difference of each individual vertical Hall-to-Pedersen field-line-integrated conductivity profile (Σ_{HP}^*) obtained during the 12 runs listed in Table 2 to the corresponding profile obtained with no modification in the variables provided by MSIS, IRI, and IGRF models during the reference day (Σ_{HP}). Afterward, we grouped the differential profiles in a proper temporal sequence with a time resolution of 2 min, in a similar manner as in the profiles presented in the color map in the bottom panel of Fig. 3b.

Twelve color maps corresponding to the differential analysis of the 12 runs are shown in Fig. 5. The 6 color maps on the left side of the figure correspond to the differential analysis when the variables provided by the empirical models were underestimated during the run. The model being evaluated during the run is identified in the top right corner of each graph in correspondence to the information provided in the first two columns of Table 2. The same applies to the remaining 6 other color maps, but corresponding to the overestimation of the variables. The color bar on the right side of the figure indicates that the absolute difference varies from 0 to 2.5.

In general, Σ_{HP}^* is the highest when the MSIS outputs are artificially underestimated or overestimated by 10 %. Indeed, simulations that involve changes in the amplitude of the variables provided by MSIS, such as $MSIS_{\epsilon IRI}$ and $IGRF_{\epsilon MSIS}$, appear to have consistently larger Σ_{HP}^* than those with the MSIS outputs constant, such as IRI, $IGRF_{\epsilon IRI}$, and IGRF runs. Taking the differential analysis results when the variables provided by MSIS are modified, it is seen that Σ_{HP}^* is 2.2 in $MSIS_{(U)}$ and 2 in $MSIS_{(O)}$, at around 100 km, and decreases in both downward and upward directions of the vertical profile. There is a clear reduction in Σ_{HP}^* when the magnitude of the IRI and IGRF outputs is altered by ± 10 %. The results show that the difference in the conductivity

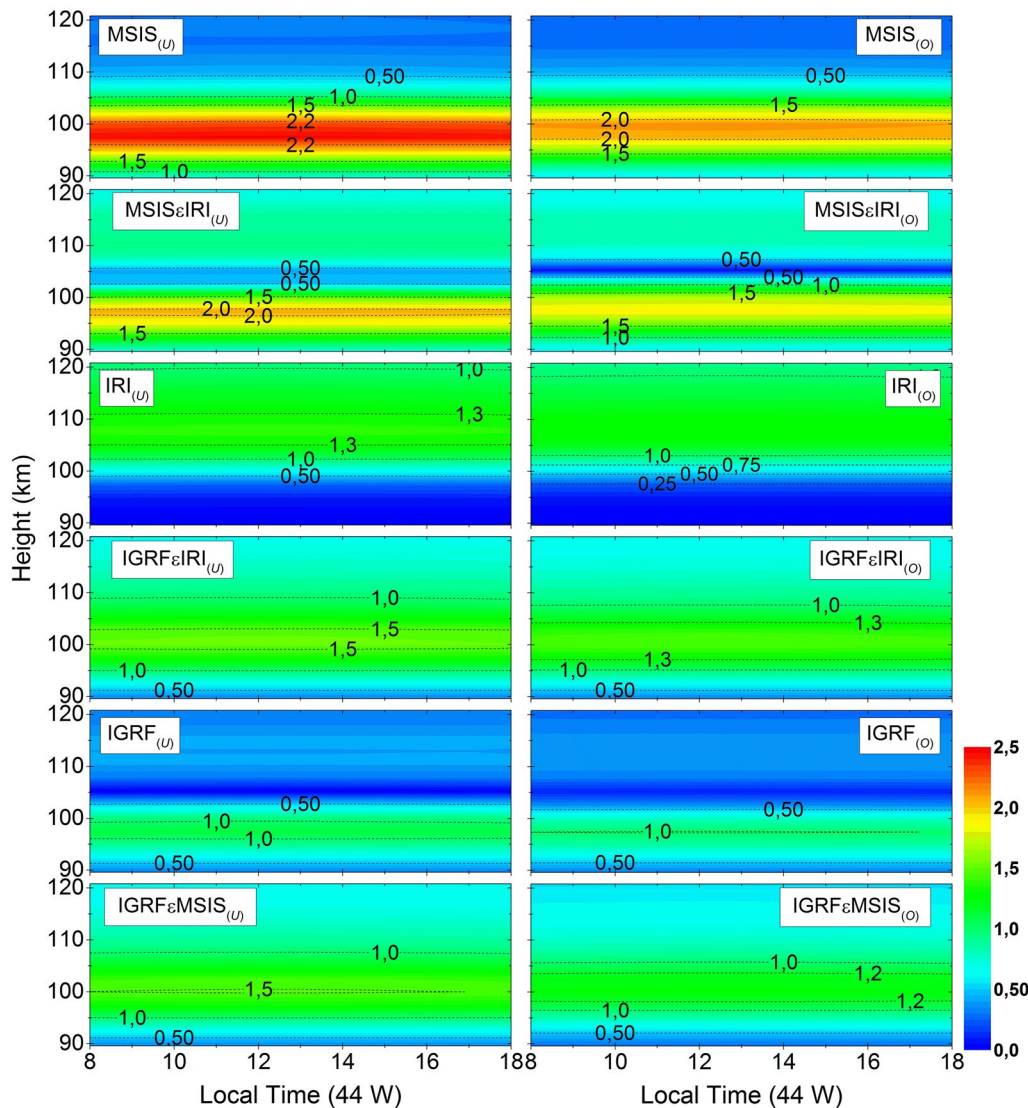


Fig. 5 Absolute differences in the Hall-to-Pedersen conductivity ratio profiles when the variables provided by the empirical models were underestimated (on the left) and overestimated (on the right) in the 12 runs given in Table 2

ratio did not surpass 1.3 when the variables provided by IRI are modified and remained around the unit when the variables provided by IGRF are modified. However, modifications in these two models present opposite effects. The higher values of differential analysis for the IRI evaluation are above 105 km, whereas those for the IGRF evaluation are observed below 105 km. The absolute difference increases when both model outputs are simultaneously varied by $\pm 10\%$ (IGRF ϵ IRI), leading to changes in the conductivity ratio by up to 1.5 times the original values.

The results above evidenced that higher differences in the EEF and conductivities are observed if neutral densities and neutral temperature provided by the MSIS model

are varied, followed by variations in the geomagnetic field given by the IGRF model and variations in electron and ion densities provided by the IRI model. A general investigation of the uncertainties in ΔE_y and ΔE_z involves considering the meaning of the numerator and denominator terms of the anisotropic factor (Ψ_0 defined after Eq. 1). It is noticed that the numerator term is the ion–neutral and electron–neutral collision frequencies, calculated from the neutral densities and neutral temperature provided by the MSIS model. The denominator term encompasses the ions and electron gyro frequencies calculated from the magnetic field provided by the IGRF model. An increase (decrease) in the MSIS model is then always accompanied by an increase (decrease) in E_y and E_z , when the

other quantities remain unaltered. On the other hand, an increase (decrease) in the variables provided by the IGRF model will result in a decrease (increase) in ΔEy and ΔEz , also considering that the other quantities remain unaltered. It might explain the results obtained for the run $MSIS_{(U)}$, $MSIS_{(O)}$, $IGRF_{(U)}$, and $IGRF_{(O)}$ in Table 2. Furthermore, changes in the IRI model outputs lead to uncertainties up to 3.01 % in ΔEy and up to 3.70 % in ΔEz and, the lowest electric field uncertainty obtained in this study resulted from the $IRI_{(O)}$ run, -2.16 % in ΔEy . Consequently, we may assume that ΔEy and ΔEz are less sensitive to changes in the variables provided by the IRI outputs as compared to the variables provided by the MSIS model. Therefore, it seems fair to attribute the high uncertainties (more than 10 %) in ΔEy and ΔEz obtained in the runs $MSIS\epsilon IRI_{(U)}$ and $MSIS\epsilon IRI_{(O)}$ to the MSIS outputs.

Analysis of linear fitting

To further investigate the uncertainties associated with the empirical model outputs as a function of height, a linear fitting is applied between Ey and Ez inferred at the four different radar range heights (Fig. 1) and the corresponding component inferred from the 12 simulations ($Ey_{U/O}$ and $Ez_{U/O}$), respectively. As a result, we have δEy and δEz obtained from the slope of the fitted line, which is used to determine the corresponding uncertainties in the electric field estimates, i.e., the amount of changes in $Ey_{U/O}$ and $Ez_{U/O}$ compared to Ey and Ez . The results are shown in the charts of Fig. 6 among the three dimensions (MSIS, IRI, and IGRF) and the intermediary directions ($MSIS\epsilon IRI$, $IGRF\epsilon IRI$, and $IGRF\epsilon MSIS$) for δEy (left panels) and δEz (right panels). The dimensions of each empirical model are shown in the three axes, analogous to Fig. 4. The uncertainties in the electric fields due to the eventual errors in the variables provided by the MSIS model alone are placed in the vertical axis. The uncertainties in the electric fields due to eventual errors in the variables provided by the IRI model alone are placed in the axes 120° clockwise, and the uncertainties in the electric fields due to eventual errors in the variables provided by the IGRF model alone are placed 120° from both previous axes. All axes are then arranged radially, with equal distances between each other, while maintaining the same scale between all axes defined to have a minimum of -20 % uncertainties (where the axes intersect) and a maximum of $+40$ % uncertainties (outer ring) within a 10 % interval. Grid lines that connect axis to axis are used as a guide. Note that the level of zero percent uncertainty is set to be the second grid line from the center of the chart. The axes are linearly connected so that the uncertainties in the electric fields set can be visualized as a polygon. Finally, the dashed lines/spheres (continuous

line-stars) are the uncertainties in the electric fields obtained after underestimating (overestimating) the model outputs by 10 %. The labels of the uncertainties are shown in the bottom chart on the left.

Some general characteristics are evident in this slope analysis. For instance, the lower (higher) the radar sounding region of study, the higher (lower) the uncertainties caused by eventual errors in the empirical models. The electric field components inferred from the runs with the variables provided by the models underestimated or overestimated by 10 % change significantly in relation to Ey and Ez . MSIS dimensions present the highest uncertainties at 102.5 km (lower charts) in both underestimating and overestimating situations, including the $MSIS\epsilon IRI$ direction. When Ey_O increases by $+29.76$ % during the $MSIS_{(O)}$ run compared to the $+2.24$ % obtained during the $IRI_{(O)}$ run, the overestimations in the variables during the $MSIS\epsilon IRI_{(O)}$ run lead to 34 % changes in Ey_O , which is mostly due to the MSIS model. Also, the EEf has uncertainties around 10 % in the IGRF dimension and no expressive values in the IRI dimension.

It is also notable from the analysis of Fig. 6 that the magnitude of the uncertainties in the electric field decreases in all dimensions in the central region of the EEf (panels for 105.1 km), except for the MSIS dimension, which may lead to higher uncertainties. The smaller uncertainties are located at 107.7 and 110.3 km. It is remarkable that a 10 % reduction (increase) in quantities provided by the models will not impact the electric fields with a reduction (increase) of the same magnitude. As noted from Fig. 6, the lower uncertainties in the EEf are located in the IRI dimension in the higher E-region (107.7 and 110.3 km), where changes in the slope are near the level of zero percent uncertainty.

According to the results given in Table 2 and Figs. 5 and 6, we determined the uncertainties in the conductivity and the EEf associated with the empirical model outputs in order to precisely determine the confidence limit in their magnitude. Although a large number of works deal with the comparisons between neutral atmosphere data and MSIS model prediction (Richards 2002; Liu et al. 2005; Burke et al. 2007; Park et al. 2008; Jeon et al. 2011), observed ionospheric data and IRI model predictions (Abdu et al. 1996; Batista et al. 1996; de Souza et al. 2003; Sethi et al. 2004; Bertoni et al. 2006; Lühr and Xiong 2010; Kenpankho et al. 2011; Oyekola and Fagundes 2012; Yue et al. 2013; Kumar et al. 2014, 2015), and geomagnetic field data and IGRF predictions (Loves 2000; Loves and Olsen 2004), uncertainties (or potential errors) of these empirical models have not been published, even in Bilitza and Reinisch (2008), Picone et al. (2002), and Finlay et al. (2010).

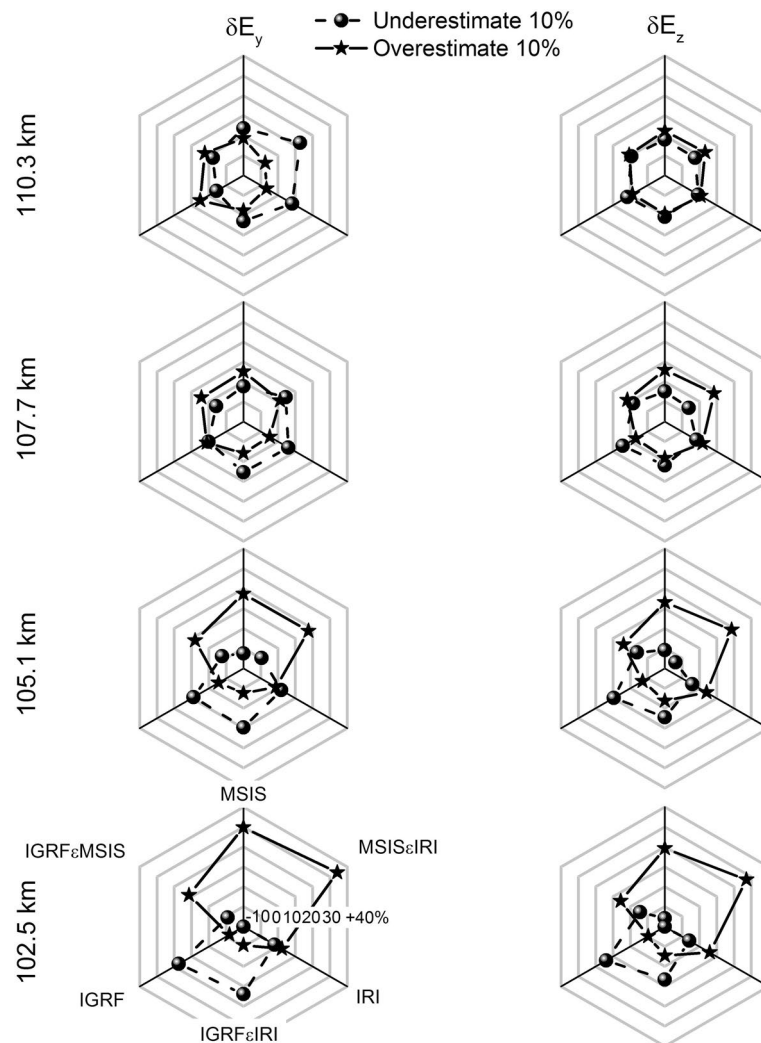


Fig. 6 Error analysis obtained from the slope of the linear fit applied between the components inferred on February 7, 2001, and the components inferred from the 12 runs given in Table 2

Several authors realized that the empirical models have shortcomings, especially in the equatorial region. However, some of them did not consider the effects of changes in their parameter distributions in their results. They assumed that these empirical models are accurate (e.g., Du and Stening 1999). Nevertheless, Alken and Maus (2010) were concerned about this issue in their work. The authors developed a technique to estimate the equatorial electric fields from a latitudinal profile of the EEJ current as the CHAMP satellite crossed the magnetic equator. In order to calculate the ionospheric conductivities, the authors used the collision frequency expressions given by Kelley (1989) and the MSIS and IRI models to obtain the neutral densities and the ion and electron densities,

respectively. They investigated how daily departures of neutral atmosphere and ionospheric parameters from the climatological mean given by MSIS and IRI models may affect their electric field estimates. Their results show that errors in the neutral density model have small effects in the electric fields derived by satellite data, and they concluded that the main source of uncertainties in the electric fields comes from the IRI model, especially in the calculation of the electron and ion densities. In the present work, the main source of uncertainties in the electric field derived by radar data comes from the MSIS model.

The reasons for the difference between the present work and the interpretation presented by Alken and Maus (2010) can be attributed to the different methodologies

applied for the radar and satellite data to infer the electric fields. In the present work, the electron density is simplified in the equations when the ratio of Hall to Pedersen conductivities is computed to infer E_y (Eq. 4), minimizing its uncertainties and consequently the errors related to the IRI model. Alken and Maus (2010) modeled and used each of the three components of the ionospheric conductivity (direct, Pedersen, and Hall) to achieve their results (please, see Eq. 14 in their work). Since each component has an electron density dependence, the IRI might become another source of errors. Lühr and Xiong (2010) found that the IRI-2007 model overestimates the electron density by a factor of more than 1.5 in the height range 300–500 km during the deep solar minimum of solar cycle 23/24. Moreover, different sets of collision expressions were applied in each of these studies to obtain the conductivities. We use the set of expressions found in Bailey and Balan (1996), which are the most updated expressions available in the literature as far as we know, since they are used in the SUPIM model (Bailey et al. 1997). Moreover, the altitude range is different in these works. We studied the influence of uncertainties of the empirical models for inferring the E-region electric fields between 100 and 110 km, while Alken and Maus (2010) (please, see Eq. 9 in their work) focused on an altitude range of 65–465 km. Therefore, the evidences provided in this work show that the MSIS model is responsible for the largest change in E_y and E_z inferred from the radar data, and the IRI model is responsible for the largest change in E_y inferred from satellite data. Therefore, it is difficult to judge whether IRI and MSIS models are best or worst without a detailed discussion about the methodology applied in the work.

The MSIS, IRI, and IGRF models have been used by the scientific community for many years in diverse areas for a wide range of objectives. The models have been validated in several works and in several longitude sectors and geomagnetic conditions against experimental data in order to improve its accuracy in representing the neutral atmosphere, ionosphere, and geomagnetic field parameters. However, these models appear to be less accurate in the equatorial and low-latitude regions in the American sector due to the effects of some complex processes, which provide unique challenges for empirical modeling of the region. As there are no other empirical models available for the Brazilian equatorial region, it is assumed that their results are the best information available for the neutral atmosphere, ionosphere, and geomagnetic field. However, the reliability of these empirical models

has to be considered when evaluating their outputs. The present study provides such an estimation of their accuracies for EEF inferred from the Doppler shifts of type II echoes measured by coherent radars, and the disparities pointed out here will be helpful for advancement of the MSIS, IRI, and IGRF models, especially over equatorial latitudes, where ionospheric data from this region are quite scarce.

Conclusions

The applications of empirical models have been extending to diverse areas, and they have been in use for a wide range of objectives since the last decades. Researchers usually use the models with no deep investigation about the influence of their uncertainties on the results. Using Doppler shifts of type II echoes measured by the RESCO radar, we have shown, for the first time, the influence of uncertainties of the MSIS-2000, IRI-2007, and IGRF-11 model outputs in the diurnal profiles of the ionospheric conductivity and the E-region electric fields for the Brazilian equatorial region. One of the most significant results of this study is that the variations in O, N₂, and O₂ densities and neutral temperature provided by the MSIS-2000 cause the largest changes in the E-region conductivity and electric fields. It is observed that the electric fields can differ by almost 40 % if the empirical models have ± 10 % errors in their output parameters. The effects are higher in the lower E-region (below ~ 105 km). Uncertainties in the geomagnetic field strength and its horizontal component provided by the IGRF-11 lead to smaller effects, followed by electron and O₂⁺, NO⁺, and O⁺ densities given by the IRI-2007. Further research on this topic includes analyses of the empirical model outputs in the F-region and outputs provided by the IRI-2012, the new version of the IRI model.

Authors' contributions

JM and CMD designed the study, analyzed, and interpreted the data and wrote the manuscript. LCAR, SSC, and NJS helped to improve the manuscript. All authors read and approved the final manuscript.

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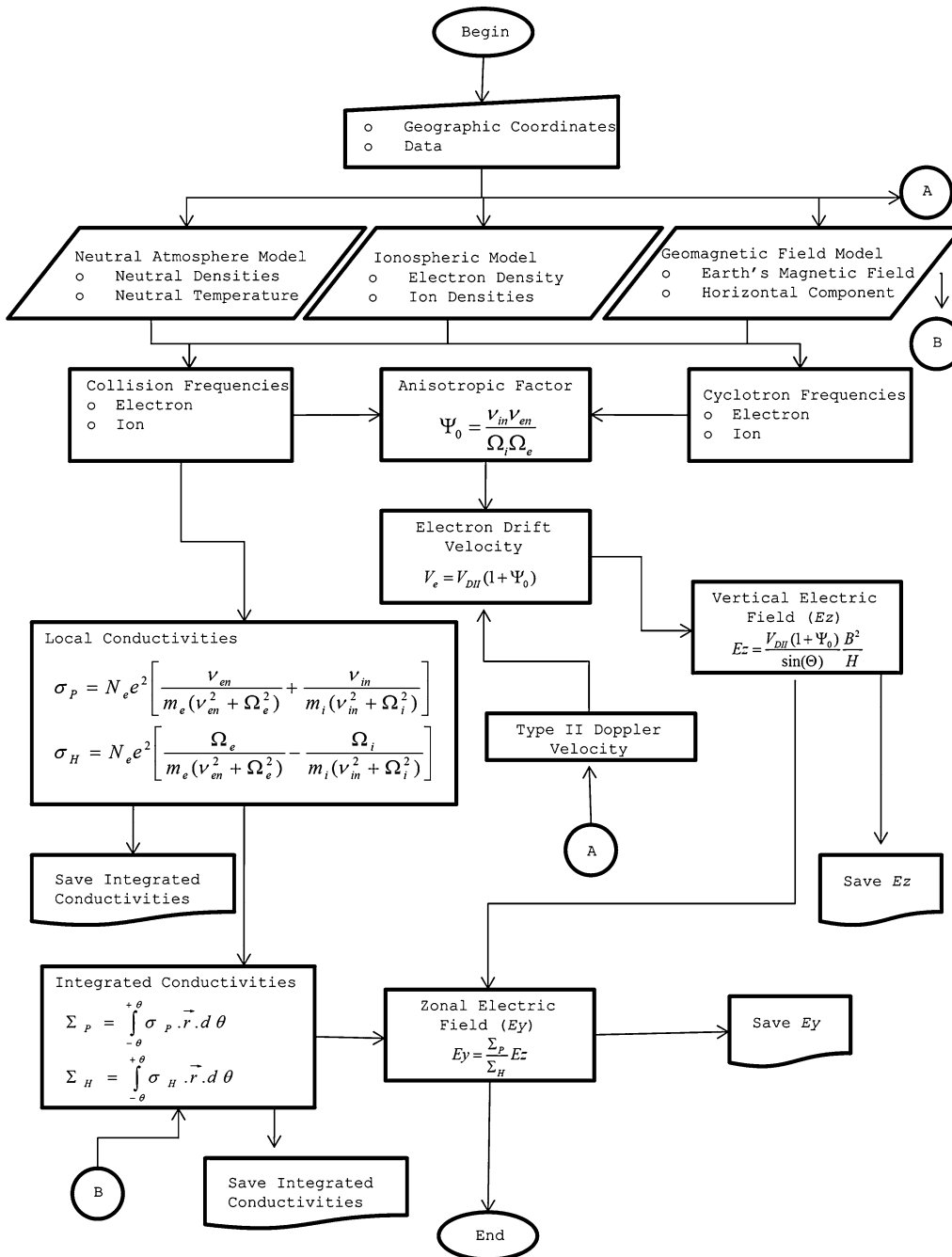
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Competing interests

The authors declare that they have no competing interests.

Appendix

Flowchart of the magnetic field-line-integrated ionospheric conductivity model.



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