# (n-2)-TIGHTNESS AND CURVATURE OF SUBMANIFOLDS WITH BOUNDARY 

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ABSTRACT. The purpose of this note is to establish a connection between the notion of ( $\mathrm{n}-2$ )-tightness in the sense of N.H. Kuiper and T.F. Banchoff and the total absolute curvature of compact submanifolds-with-boundary of even dimension in Euclidean space. The argument used is a certain geometric inequality similar to that of S.S. Chern and R.K. Lashof where equality characterizes ( $\mathrm{n}-2$ )-tightness.

KEY WORDS AND PHRASES. tight manifolds, total absolute curvature.
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1. INTRODUCTION.

Let $M$ be a compact $n$-dimensional smooth manifold with or without boundary where the boundary is assumed to be smooth - and let

$$
\mathrm{f}: \mathrm{M} \longrightarrow \mathrm{E}^{\mathrm{n}+\mathrm{k}}
$$

be a smooth immersion of $M$ into the $(n+k)$-dimensional euclidean space. This leads to the notion of total absolute curvature

$$
\operatorname{TA}(\mathrm{f})=\frac{1}{\mathrm{c}_{\mathrm{n}+\mathrm{k}-1}} \int_{\mathrm{N}}|\mathrm{~K}| * 1
$$

where $K$ denotes the Lipschitz-Killing curvature of $f$ in each normal direction, $N$ the unit normal bundle (with only the 'outer' normals at points of $\partial \mathrm{M}$ ), and $\mathrm{c}_{\mathrm{m}}$ denotes the volume of the unit sphere $S^{m} \subseteq E^{m+1}$. For detailed definitions, in particular in the case of manifolds with boundary, see[5] or [6]. Let us state the following equation ( $[6], 2.2$ )

$$
\begin{equation*}
T A(f)=T A\left(\left.f\right|_{M \backslash \partial_{M}}\right)+\frac{1}{2} T A\left(\left.f\right|_{\partial M}\right) \tag{1.1}
\end{equation*}
$$

The famous result of S.S. Chern and R.F. Lashof gives a connection between total absolute curvature and the number of critical points of so-called height functions

$$
\text { zf }: M \longrightarrow \mathbb{R}
$$

defined by $(z f)(p)=<z, f(p)>\quad, \quad z \in S^{n+k-1}$
Extending this result to the case of manifolds with boundary we can write

$$
\begin{equation*}
\operatorname{TA}(f)=\frac{1}{c_{n+k-1}} \quad z \in S^{n+k-1} \sum_{i}^{\sum_{i}\left(\mu_{i}(z f)+\mu_{i}^{+}(z f)\right) * 1} \tag{1.2}
\end{equation*}
$$

where $\mu_{i}(z f)$ denotes the number of critical points of $z f$ of index $i$ in $M \backslash \partial M$, and $\mu_{i}^{+}(z f)$ denotes the number of (+)-critical points of $z f$ of index $i$ in $\partial M$. Here a point $p \in \partial M$ is called (+)-critical if $p$ is critical
for $\quad z f f_{M}$ and $\operatorname{grad}_{p} f$ is a nonvanishing inner vector on $M$ (for details, see [2], [4] or [6] ).

The i-th curvature $\tau_{i}$ introduced by N.H. Kuiper (cf. [7] ) can be expressed by

$$
\tau_{i}(f)=\frac{1}{c_{n+k-1}} \quad \int_{z \in S^{n+k-1}}\left(\mu_{i}(z f)+\mu_{i}^{+}(z f)\right) *_{1}
$$

(cf. [6], lemma 4.2 or [9], lemma 3.1). So we get

$$
T A(f)=\sum_{i} \tau_{i}(f)
$$

The Morse-relations give the following connections between the curvatures and some topological invariants of $M$ :

$$
\begin{gather*}
\tau_{i}(f) \geqslant b_{i}(M)  \tag{1.3}\\
T A(f) \geqslant b(m):=\sum_{i} b_{i}(M) \\
\sum_{i}(-1)^{i} \tau_{i}(f)=\chi(M)=\sum_{i}(-1)^{i} b_{i}(M)
\end{gather*}
$$

where $b_{i}(M)$ denotes the $i-t h$ Betti-number of homology with coefficients in a suitable field. (cf. [7]).
$f$ is called $\underline{k-t i g h t}$ if for $a 11 k^{\prime} \leq k$ and for almost all $z \in S^{n+k-1}$ and all real numbers $c$ the inclusion map

$$
j:(z f)_{c}:=\{p \in M /(z f)(p) \leqq c\} \longrightarrow M
$$

induces a monomorphism in the $k^{\prime}$-th homology :

$$
\mathrm{H}_{k^{\prime}}(\mathrm{j}): \mathrm{H}_{k^{\prime}}\left((z f)_{c}\right) \longrightarrow \mathrm{H}_{k^{\prime}}(\mathrm{M})
$$

As usual we write shortly 'tight' instead of 'n-tight'.
Then the results of N.H. Kuiper show

$$
T A(f)=b(M) \quad \text { if and only if } \quad f \text { is tight, }
$$

```
    \tau}\mp@subsup{\mp@code{k}}{(f)= b}{k
for almost all z, all c (cf. [7] ).
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Results on tightness are collected in the survey article [10] by T.J. Willmore, for results on k-tightness we refer in addition to the notes [1] by T. Banchoff and [9] by L. Rodriguez, who has shown that in some sense ( $n-2$ )-tightness is closely related to convexity.

## 2. RESULTS

As mentioned above there is a relation between tightness on one hand and total absolute curvature and the sum of the Betti-numbers on the other hand. The following results give certain connections between ( $\mathrm{n}-2$ )-tightness on one hand and usual curvature terms and the sum of the Betti-numbers on the other hand. Note that in case $\partial M=\phi$ by duality arguments tightness is equivalent to $k$-tightness for $k=\frac{n}{2}-1$ if $n$ is even and for $k=\frac{n-1}{2}$ if $n$ is odd. But in case $\partial M \neq \phi$ there are examples of ( $n-2$ )-tight immersions which are not tight (for example: consider the round hemi-sphere).

THEOREM A . Let $M^{n}$ be an even-dimensional manifold with non-void boundary and $f: M \rightarrow E^{n+k}$ be an immersion. Let $N_{0}$ be the unit normal bundle of $f_{M \backslash \partial}$ and denote by $N_{*} C_{=} N_{0}$ the open set of unit normals where the second fundamental form of $f$ is positive or negative definite.

Then there holds the following inequality

$$
\begin{equation*}
\frac{1}{2} T A\left(\left.f\right|_{\partial M}\right)+\frac{1}{c_{n+k-1}} \int_{N_{0} \backslash N_{*}}|k| *_{1} \geq b(m) \tag{2.1}
\end{equation*}
$$

where equality characterizes ( $n-2$ )-tightness of $f$.

In case of hypersurfaces $(k=1)$ (2.1) becomes

$$
\begin{equation*}
\frac{1}{2} T A\left(\left.f\right|_{\partial M}\right)+T A\left(\left.f\right|_{M \backslash M_{*} \backslash \partial M}\right) \geq b(M) \tag{2.2}
\end{equation*}
$$

where $M_{*}$ denotes the set of points in $M \backslash 2 M$ with positive or negative definite second fundamental form.

In case $n=2 M_{*}$ is just the set of points with positive Gaussian curvature, so we get

COROLLARY A 1. Assume $n=2$ and $k=1 \ddots$ Then there holds the following inequality

$$
\begin{equation*}
\frac{1}{2 \pi} \int_{K<0}|K| \text { do }+\frac{1}{2 \pi} \int_{\partial M}|x| d s \geqq b(M) \geqq 2-\chi(M) \tag{2.3}
\end{equation*}
$$

where equality characterizes 0 -tightness of $f$. Here $|\boldsymbol{x}|$ denotes the usual curvature of $f f_{\partial M}$ considered as a space curve. For part of this result see [8] , Prop. 9.

COROLLARY A 2. Assume $b(\partial M)=2 b(M)$. Then ( $n-2$ )-tightness of $f$ implies that $f_{\partial M}$ is tight and that the second fundamental form of $f$ has either nonmaximal rank of is positive or negative definite.

This is shown in [9], Prop. 5.2 under the assumption that $M^{n}$ can be embedded in $E^{n}$. This condition implies $b(\partial M)=2 b(M)$ by Alexander duality.

Under the additional assumption that $\partial M$ consists of a certain number of ( $\mathrm{n}-1$ )-spheres L. Rodriguez has shown that ( $\mathrm{n}-1$ )-tightness is equivalent to convexity (cf. [9] , Theorem 2). This is not true in general, (See Corollary B 2 below).

THEOREM B. Let $n$ be even and $f: M^{n} \rightarrow E^{n+1}$ be ( $n-2$ )-tight (if $\partial M \neq \phi$ ) or tight (if $\partial M=\phi$ ), and let $\tilde{M} \leqq M \backslash \partial M$ be a compact submanifold of dimension $n$ which is contained in some coordinate neighborhood in $M$. As above $M_{*}$ denotes the set of points in $M \backslash \partial M$ with positive or negative definite second fundamental form. Then there holds the following inequality

$$
\begin{equation*}
\operatorname{TA}(f \mid \partial \tilde{M}) \geq b(\partial \tilde{M})+2 \operatorname{TA}\left(f_{M \backslash M_{\star} \backslash} \tilde{M}^{\sim}\right) \tag{2.4}
\end{equation*}
$$

where equality characterizes (n-2)-tightness of $\left.f\right|_{M \backslash(\tilde{M} \backslash \partial \tilde{M})}$.
REMARK. If $\tilde{M}$ contains only points of vanishing curvature or definite second fundamental form, then $\tilde{M} M_{*}=\phi$ and (2.4) reduces to the inequality of S.S Chern and R.K. Lashof for $\partial \tilde{M}$, otherwise (2.4) is sharper and reflects the additional condition that $\tilde{M}$ lies inside of some given $M$. For example in case $n=2$ and $\tilde{M}$ being a disk we get

$$
\begin{equation*}
\int_{\partial \mathcal{M}}|x| d s \geq 2 \pi+\int_{\operatorname{M} \cap\{K<0\}}|K| \text { do } \tag{2.5}
\end{equation*}
$$

COROLLARY B 1. Let $f$ be as in Theorem $B$ and assume moreover that there is an open region $U \subseteq M$ which is embedded by $f$ in a hyperplane of $E^{n+1}$ which implies $\left.K\right|_{U}=0$. Let $\tilde{M}^{n}$ be an embedded compact submanifold of $E^{n}$ and assume by changing the scale $\tilde{M} \cong f(U)$.

Then $f{ }_{M \backslash f}{ }^{-1} \tilde{(M \backslash \partial \tilde{M})}$ is (n-2)-tight if and only if $\partial \tilde{M}$ is tightly embedded in $E^{n}$.
Note that for $\tilde{M}^{n} \cong E^{n}$ tightness of $\tilde{M}$ and tightness of $\partial \tilde{M}$ are equivalent: this can be obtained easily using the equations $T A(M)=\frac{1}{2} T A(\partial M)$ and $b(\tilde{M})=\frac{1}{2} b(\partial \tilde{M})$.

Roughly spoken Corollary B 1 says: ( $n-2$ )-tight minus tight gives ( $n-2$ )-tight. In particular we get the following

COROLLARY B 2. In each even dimension there exist ( $n-2$ )-tight hypersurfaces which are not tight and not convex in the sense of [9], in particular where $f(\partial M)$ is not contained in the boundary of the convex hull of $f(M)$.
3. PROOFS.

In all proofs the immersion $f$ is fixed and so we may write $T A(\partial M)$ instead
of $T A\left(\left.f\right|_{\partial M}\right)$ and so on.

PROOF OF THEOREM A.
From

$$
T A(M)=\sum_{i} \tau_{i}(M)
$$

and
we get

$$
\begin{gathered}
\chi(M)=\sum_{i}(-1)^{i} \tau_{i}(M) \\
T A(M)+\chi(M)=2 \sum_{i} \tau_{i}(M)
\end{gathered}
$$

On the other hand by definition $\tau_{n}(M)$ is the average of the number of critical points of $z f$ of index $n$ which are precisely the strict local maxima in $M \backslash \partial M$. But a point is a strict local extremum of some height function $z f$ if and only if the second fundamental form in the direction of $z$ is positive or negative definite. Hence we get

$$
2 \tau_{n}(M)=\frac{1}{c_{n+k-1}} \int_{N_{*}}|K| * 1
$$

leading to

$$
\begin{aligned}
T A(M) & -\frac{1}{c_{n+k-1}} \int|K| * 1 \\
& =2\left(\tau_{0}(M)+\tau_{2}(M)+\ldots+\tau_{n-2}(M)\right)-\chi(M) \\
& \geq 2\left(b_{0}(M)+b_{2}(M)+\ldots+b_{n-2}(M)\right)-\chi(M) \\
& =b(M),
\end{aligned}
$$

where we have used the assumption that $n$ is even and $\partial M \neq \phi$ which implies $b_{n}(M)=0$.

The case of equality is equivalent to the following equations:

$$
\begin{equation*}
\tau_{0}(M)=b_{o}(M), \tau_{2}(M)=b_{2}(M), \ldots, \tau_{n-2}(M)=b_{n-2}(M) \tag{2.6}
\end{equation*}
$$

But the equality $\tau_{i}(M)=b_{i}(M)$ is equivalent to injectivity of $H_{i}(j)$ and $H_{i-1}(j)$ for all inclusions $j:(z f)_{c} \rightarrow M$, so (2.6) is equivalent to ( $n-2$ )-tightness of $f$.

The assertion of the theorem then follows from the inequality above using the equation (1.1)

$$
T A(M)=T A(M \backslash \partial M)+\frac{1}{2} T A(\partial M)
$$

PROOF of Corollary A 2. By theorem A ( $n-2$ )-tightness of $f$ implies

$$
\begin{aligned}
b(M) & =\frac{1}{2} T A(\partial M)+\frac{1}{c_{n+k-1}} \int_{N_{0} \backslash N_{*}}|K| * 1 \\
& \geqq \frac{1}{2} T A(\partial M) \geqq \frac{1}{2} b(\partial M)=b(M)
\end{aligned}
$$

which implies tightness of $\left.f\right|_{\partial M}$ and moreover the vanishing of the integral of $|K|$ over $N_{0} \backslash N_{*}$, hence $K=0$ on $N_{0} \backslash N_{*}$.

PROOF of Theorem B. By assumption and by theorem A we have

$$
\begin{array}{r}
T A\left(M \backslash M_{\star} \backslash \partial M\right)+\frac{1}{2} T A(\partial M)=b(M), \text { if } \partial M \neq \phi,  \tag{2.7}\\
T A(M)=b(M), \text { if } \partial M=\phi
\end{array}
$$

or
which last equality is equivalent to

$$
\begin{equation*}
T A\left(M \backslash M_{\star}\right)=b(M)-2 \tag{2.8}
\end{equation*}
$$

For $\left.\quad f\right|_{M \backslash(\tilde{M} \backslash \partial \tilde{M})}$ theorem A yields

$$
\begin{equation*}
T A\left(M \backslash \tilde{M} \backslash M_{*} \backslash \partial M \backslash \partial \tilde{M}\right)+\frac{1}{2} T A(\partial M)+\frac{1}{2} T A(\partial \tilde{M}) \geqq b(M \backslash \tilde{M}) \tag{2.9}
\end{equation*}
$$

where equality characterizes (n-2)-tightness of $\left.f\right|_{M \backslash(\tilde{M} \backslash \partial \tilde{M})}$.
Subtracting (2.9) from (2.7) or (2.8) respectively we get

$$
\begin{align*}
& T A\left(\tilde{M} \backslash M_{\star} \backslash \tilde{M}\right)-\frac{1}{2} T A(\partial \tilde{M}) \leqq b(M)-b(M \backslash \tilde{M})  \tag{2.10}\\
& T A\left(\tilde{M} \backslash M_{\star} \backslash \partial \tilde{M}\right)-\frac{1}{2} T A(\partial \tilde{M}) \leqq b(M)-b(M \backslash \tilde{M})-2 \tag{2.11}
\end{align*}
$$

respectively.
Now the assertion follows directly from the following lemma

LEMMA. Let $M, \tilde{M}$ be $n$-dimensional dompact connected manifolds with $\tilde{M} \leqq$ MlaM and assume that $\tilde{M}$ is contained in some coordinate neighborhood of $M$ Then

$$
\begin{array}{ll} 
& b(M \mid \tilde{M})-b(M)=\frac{1}{2} b(\partial \tilde{M}) \text { if } \partial M \neq \phi, \\
\text { or } \quad b(M \mid \tilde{M})-b(M)=\frac{1}{2} b(\partial \tilde{M})-2 \text { if } \partial M=\phi
\end{array}
$$

PROOF. Let $B$ be an open coordinate neighborhood in $M$ such that $\bar{B}$ is topologically a closed n-ball. We can assume $\tilde{M} \leqq B \subseteq \bar{B} \subseteq M \backslash M$. To compute the Betti-numbers of $M \backslash \tilde{M}$ in terms of that of $M$ and $\tilde{M}$ we apply the MayerVietoris sequence to the following three decompostions
I.

$$
\begin{aligned}
M= & (M \backslash B) \cup \bar{B} \\
& (M \backslash B) \cap \bar{B}=\partial \bar{B} \cong S^{n-1},
\end{aligned}
$$

II. $\quad \bar{B}=(\bar{B} \backslash(\tilde{M} \backslash \partial \tilde{M})) \cup \tilde{M}$ $(\bar{B} \backslash(\tilde{M} \backslash \tilde{M})) \cap \tilde{M}=\partial \tilde{M}$,
III.

$$
M \backslash(\tilde{M} \backslash \partial \tilde{M})=(M \backslash B) \bigcup^{\prime}(\bar{B} \backslash(\tilde{M} \backslash \partial \tilde{M}))
$$

$$
(M \backslash B) \cap(\bar{B} \backslash(\tilde{M} \backslash \partial \tilde{M}))=\partial \bar{B} \cong s^{n-1} .
$$

The first decomposition leads to

$$
\begin{array}{ll}
b(M)=b(M \backslash B)-1 & \text { if } \partial M \neq \phi \\
b(M)=b(M \backslash B)+1 & \text { if } \partial M=\phi, \tag{2.13}
\end{array}
$$

the second one to

$$
\begin{equation*}
b(B \backslash \tilde{M})+b(\tilde{M})=b(\partial \tilde{M})+1 \tag{2.14}
\end{equation*}
$$

the third one to

$$
\begin{equation*}
b(M \backslash \tilde{M})=b(M \backslash B)+b(\bar{B} \backslash \tilde{M})-2 \tag{2.15}
\end{equation*}
$$

At last we have the equation

$$
\begin{equation*}
b(\partial \tilde{M})=2 b(\tilde{M}) \tag{2.16}
\end{equation*}
$$

because by assumption $\tilde{M}$ can be embedded in $B \leqq E^{n}$ (cf. [9] Prop. 5.1).
Now the lemma follows directly from (2.12) - (2.16) .
PROOF of Corollary B 2 . Consider for example an embedding of $S^{k} X S^{n-k}$ in $E^{n+1} \quad(k \geq 1$ arbitrary) as a tight hypersurface of rotation (like the standard-torus in $E^{3}$ ) and change this embedding a little bit such that there is an open region $U$ contained in some hyperplane of $E^{n+1}$. Now define $M$ by removing a small tight 'solid torus' of type $S^{m} \times B^{n-m}$ from $U$ ( $m \geqq 1$ ). By Corollary B 1 M is (n-2)-tight but of course it is not tight. By suitable choice of the embedding of $S^{k} X S^{n-k}$ we started from we can assume that $U$ lies not in the boundary of the convex hull $X$. So we can obtain an example where $\partial M$ lies not in the boundary of $x$.

REMARK. In the examples of corollary B 2 the boundary $\partial M$ was always tightly embedded in $E^{n+1}$. The natural question whether there exist in higher dimensions ( $\mathrm{n}-2$ )-tight immersions with non-tight boundary seems to be open. For $\mathrm{n}=2$ an example is due to $L$. Rodriguez.

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