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Assessment of the positioning accuracy of a small articulated robot during machining operations

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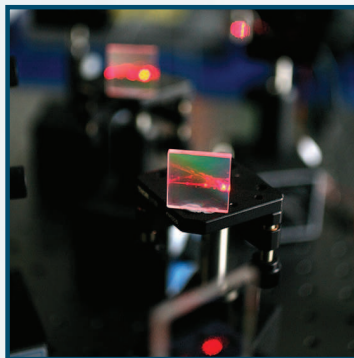


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