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Liangjun SU<br>Singapore Management University, ljsu@smu.edu.sg<br>Zhentao SHI<br>Yale University<br>Peter C. B. PHILLIPS<br>Singapore Management University, peterphillips@smu.edu.sg

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# Identifying Latent Structures in Panel Data* 

Liangjun Su<br>School of Economics, Singapore Management University<br>Zhentao Shi<br>Department of Economics, Yale University<br>Peter C. B. Phillips<br>Yale University, University of Auckland<br>University of Southampton $\mathcal{E}$ Singapore Management University

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#### Abstract

Panel data typically involve a complex mixture of individual specific and homogeneous effects whose structure is often latent within the panel and must be determined empirically. The present work provides a new mechanism for identifying and estimating latent group structures in panel data using penalized regression techniques. We focus on linear models where the slope parameters are heterogeneous across groups but where group membership is unknown. Two approaches are considered - penalized least squares (PLS) for models without endogenous regressors, and penalized GMM (PGMM) for models with endogeneity. In both cases we develop a new variant of Lasso (Least Absolute Shrinkage and Selection Operator) called classifier-Lasso (C-Lasso) that takes a novel additivemultiplicative penalty form and serves to shrink individual coefficients to the unknown group-specific coefficients. C-Lasso achieves simultaneous classification and consistent estimation in a single step and the classification exhibits the desirable property of uniform consistency. For PLS estimation C-Lasso also achieves the oracle property so that group-specific parameter estimators are asymptotically equivalent to infeasible estimators that use individual group identity information. For PGMM estimation the oracle property of C-Lasso is preserved in some special cases. A BIC-type information criterion is proposed to choose the number of groups consistently and to select a data-driven tuning parameter. Extensions of these methods to a variety of panel data models are discussed. Simulations demonstrate good finite-sample performance of the approach both in classification and estimation.


JEL Classification: C33, C36, C38, C51

[^0]Key Words: Classification; Cluster analysis; Convergence club; Dynamic panel; Group Lasso; High dimensionality; Oracle property; Panel structure model; Parameter heterogeneity; Penalized least squares; Penalized GMM

## 1 Introduction

Panel data models are widely used in empirical analysis in many disciplines across the social and medical sciences. The capacity to store and retrieve vast electronic datasets on individual behavior over time has made these models a particularly prominent research vehicle in economics and finance. Such data usually cover individual units sampled from different backgrounds and with different individual characteristics so that an abiding feature of the data is its heterogeneity, much of which is simply unobserved. Neglecting latent heterogeneity in the data can lead to many difficulties, including inconsistent estimation and misleading inference, as is well explained in the literature (e.g., Hsiao (2003, Chapter 6)). It is therefore widely acknowledged that an important feature of good empirical modeling is to control for heterogeneity in the data as well as for potential heterogeneity in the response mechanisms that figure within the model. Since heterogeneity is a latent feature of the data and its extent is unknown a priori, respecting the potential influence of heterogeneity on model specification is a serious challenge in empirical research. Even in the simplest linear panel data models the challenge is manifest and clearly stated: do we allow for heterogeneous slope coefficients in regression as well as heterogeneous error variances?

While it may be clearly stated, this challenge to the empirical researcher is by no means easily addressed. While allowing for cross-sectional slope heterogeneity in regression may help to avert misspecification bias, it also sacrifices the power of cross section averaging in the estimation of response patterns that may be common across individuals, or more subtly, certain groups of individuals in the panel. In the absence of prior information on such grouping and with data where every new individual to the panel may bring new idiosyncratic elements to be explained, the challenge is demanding and almost universally relevant.

Traditional panel data models frequently deal with this challenge by avoidance. Complete slope homogeneity is assumed for certain specified common parameters in the panel. Under this assumption, the regression parameters are the same across individuals and unobserved heterogeneity is modeled through individual-specific effects which are either fixed or random and (typically) enter the model additively. This approach is an exemplar of a convenient assumption that facilitates estimation and inference.

The cross section homogeneity assumption has been frequently questioned and rejected in empirical studies. The following is only a partial list of work where homogeneity has been found to fail. Burnside (1996) rejects slope homogeneity in the production function of US manufacturing firms; Hsiao and Tahmiscioglu (1997) find parameter heterogeneity in investment functions using the U.S. firm level panel data; Lee, Pesaran, and Smith (1997) find that the convergence rates of per capita output to the steady state level are heterogeneous across countries; Durlauf, Kourtellos, and Minkin (2001) find substantial country-specific heterogeneity in the parameters in Solow growth model that is associated with differences in initial income; Phillips and Sul (2007a) provide a new approach to testing for economic growth
convergence under heterogeneous technology and explore these differences in the Penn World Table; Browning and Carro (2007) present a selective overview on heterogeneity in microeconometric modelling and find that there is more heterogeneity than econometricians usually allow for; Browning and Carro (2010) document heterogeneity in a dynamic discrete choice panel data model for consumer milk-type choices where heterogeneity occurs in both the levels parameter and the state dependence parameter; Browning and Carro (2013) show that individual unemployment dynamics are heterogenous even within a homogeneous group of Danish workers in terms of their observed characteristics; Su and Chen (2013) reject the null of slope homogeneity in an economic growth model for OECD countries even after they control for unobserved heterogeneity through interactive fixed effects. Related to this theme, there has been much work on testing for slope homogeneity and regression poolability in panel data models - see Baltagi, Hidalgo, and Li (1996), Pesaran, Smith, and Im (1996), Phillips and Sul (2003), Pesaran and Yamagata (2008), Lin (2011), Jin and Su (2013), Su and Chen (2013), and Juhl and Lugovskyy (2013), among many others.

Despite general agreement that slope heterogeneity is endemic in empirical work with panels, few methods are available to allow for heterogeneity in the slope parameters when the extent of the heterogeneity is unknown. In the following discussion we group the methods that are available into two broad categories and consider the different approaches pursued within them. In the first category, complete slope heterogeneity is assumed and regression coefficients are taken as differing across individuals. Several approaches are adopted in the literature. Perhaps the most common method is to use a random coefficient structure in which the parameters are assumed to be independent draws from a common distribution see Hsiao and Pesaran (2008) for an overview of the approach. The random coefficient model allows for estimation of the mean coefficient effect but is uninformative about responses at the disaggregate level, thereby missing what is often the object of interest. A second approach uses Bayesian methods to shrink the individual slope estimates towards the overall mean - see Maddala, Trost, Li, and Joutz (1997). This approach is based on the presumption that the slope parameters, while not precisely the same, are sufficiently similar to warrant shrinkage toward the mean - a presumption that may be questionable in some empirical applications. A third approach is to parameterize individual slope coefficients as a function of observed characteristics - see Durlauf, Kourtellos, and Minkin (2001) and Browning, Ejrnæs, and Alvarez (2010). Apparently, this approach depends crucially on the specification of the functional coefficient and is subject to potential misspecification problems. A fourth approach is to estimate the individual slope coefficients using heterogenous time series regressions for each individual, which is only feasible in systems where the time dimension $T$ is large. Even in this case, there is a considerable debate on the options: whether to pool the data and obtain a single estimate for the whole sample, whether to estimate the equations separately for each individual, and whether to rely on the average response from individual time series regressions - see Pesaran and Smith (1995), Baltagi and Griffin (1997), Hsiao, Pesaran, and Tahmiscioglu (1999), Pesaran, Shin and Smith (1999), and the survey by Baltagi, Bresson, and Pirotte (2008).

The second category takes a totally different viewpoint on the nature of the heterogeneity in panels. In place of complete slope homogeneity or heterogeneity an intermediate approach is adopted in which
the panel structure models individuals as belonging to a number of homogeneous groups or clubs within a broadly heterogeneous population. In this framework, the regression parameters are the same within each group but differ across groups. Two essential questions remain: how to determine the unknown number of groups (dubbed convergence clubs in the economic growth literature); and how to identify the individuals belonging to each group. These are longstanding questions of statistical classification in panel data. No completely satisfactory solution has yet been found, although various approaches have been adopted in empirical research. For instance, Bester and Hansen (2013) consider a panel structure model where individuals are grouped according to some external classification, geographic location, or observable explanatory variables. So the group structure is completely known to the researcher, an approach that is common in practical work because of its convenience. In the economic growth literature, for example, countries are often classified according to continental location or economic development levels, which both lead to determinate group structures. In spite of its convenience, this approach to panel inference is inevitably misleading when the number of groups and individual identities are incorrectly classified.

Several approaches have been proposed to determine an unknown group structure in modeling unobserved slope heterogeneity in panels. The first approach is to apply finite mixture models that do not assume a known group structure. For example, Sun (2005) considers a parametric finite mixture panel data model by employing a multinomial logistic regression to model membership probabilities. Sun's model comprises a heterogenous linear panel regression model that relates the response variable to explanatory variables and a logistic regression that identifies individual memberships. This model seeks to bridge the gap between completely homogeneous slopes and completely heterogenous coefficients and works by way of several key assumptions: (a) the number of groups is known; (b) an individual can belong to any group with probability determined by individual-specific characteristics; (c) a multinomial logistic regression characterizes the probability an individual belongs to a particular group; and (d) Gaussianity is needed to facilitate inference. If any of these key conditions is violated, inference is fragile and may be adversely affected with misleading classifications. In a related thematic, Kasahara and Shimotsu (2009) and Browning and Carro (2013) study identification in discrete choice panel data models for a fixed number of groups using nonparametric discrete mixture distributions.

The second approach is based on the K-means algorithm in statistical cluster analysis. Lin and Ng (2012) and Sarafidis and Weber (2011) propose to modify the K-means algorithm to perform conditional clustering to estimate linear panel structure models but no asymptotic properties of that procedure or the estimators are derived. Bonhomme and Manresa (2012) introduce time-varying grouped patterns of heterogeneity in linear panel data models, propose two classification algorithms that are also closely related to the K-means algorithm, and study the asymptotic properties of the resulting estimators. Both Lin and Ng (2012) and Bonhomme and Manresa (2012) assume that $N$ and $T$ pass to infinity jointly. Lin and Ng (2012) propose another method to estimate a panel structure model by turning the problem of parameter heterogeneity into the estimation of a panel threshold model with an unknown threshold value and using the individual time series estimates of the parameters to form threshold variables. Phillips and Sul (2007) develop an algorithm for determining group clusters that relies on the estimation of evaporating trend functions to determine convergence clusters. Again, joint limits as $(N, T) \rightarrow \infty$ are used in the
development of the asymptotic theory.
The present paper proposes a new method for econometric estimation and inference in panel models when the slope parameters are heterogenous across groups, individual group membership is unknown, and classification is to be determined empirically. Our modeling strategy therefore falls within the second category discussed above. It is an automated data-determined procedure and does not require the specification of any modeling mechanism for the unknown group structure. The approach we suggest involves a new variant of Lasso (Tibshirani, 1996) technology that is designed to classify parametric slope coefficients in a heterogeneous panel model into a group structure in which both the groups and the elements in the groups are data determined. Like Lin and Ng (2012), Bonhomme and Manresa (2012) and Phillips and Sul (2007), we assume that $(N, T) \rightarrow \infty$ jointly (Phillips and Moon, 1999). But in our asymptotic theory $T$ can pass to infinity at a very slow rate, even a slowly varying rate such as $O\left((\ln N)^{1+\epsilon}\right)$ for any $\epsilon>0$ in the case of uniformly bounded regressors, thereby opening up empirical applications of the method to short wide panels. The methods proposed here have several novel aspects in relation to earlier research and they contribute to both the Lasso and econometric classification literatures in various ways, which we outline in the following paragraphs.

First, our approach is motivated by one of the key features of Lasso technology that enables the method to deliver simultaneous variable selection and estimation in a single step. This advantage is particularly useful when the set of unknown parameters is potentially very large but may also embody certain sparse features. In a typical panel model structure, the effective number of unknown slope parameters $\left\{\beta_{i}\right.$, $i=1, \ldots, N\}$ is not of order $O(N)$ as it would be if these parameters were all incidental, but rather of some order $O\left(K_{0}\right)$, where $K_{0}$ denotes the number of unknown groups within which the slope coefficients are homogeneous. Moreover, when the number of groups is finite, $K_{0}$ is fixed and so the order of unknown coefficients is then $O(1)$ as $(N, T) \rightarrow \infty$. Hence, in many empirical applications the set of unknown slope parameters in a panel structure model surely exhibits the desirable sparsity feature, making the use of Lasso technology highly appealing.

Second, the procedures developed in the present paper contribute to the fused Lasso literature in which sparsity arises because some parameters take the same value. The fused Lasso was proposed by Tibshirani, Saunders, Rosset, Zhu, and Knight (2005) and was designed for problems with features that can be ordered in some meaningful way (e.g., in time series regression where the time periods have natural ordering). The method cannot be used to classify individuals into different groups because there is no natural ordering across individuals and so a different algorithm to locate common individuals is required. The present paper develops a new variant of the Lasso method that does not rely on the order of individuals in the data and which therefore contributes to the fused Lasso technology.

Third, standard Lasso technology involves an additive penalty term to the least-squares, GMM, or loglikelihood objective function and when multiple penalty terms are needed, they also enter the objective function additively. To achieve simultaneous group classification and estimation in a single step our variant of Lasso involves $N$ additive penalty terms, each of which takes a multiplicative form as a product of $K_{0}$ penalty terms. To the best of our knowledge, this paper is the first to propose a mixed additivemultiplicative penalty form that can serve as an engine for simultaneous classification and estimation.

The method works by using each of the $K_{0}$ penalty terms in the multiplicative expression to shrink the individual-level slope parameter vectors to a particular unknown group-level parameter vector, thereby producing a joint shrinkage process. This process is distinct from the prototypical Lasso method that shrinks an individual parameter to zero and the group Lasso method that shrinks a parameter vector to a vector of zeros (see Yuan and Li, 2006). To emphasize its role as a classifier and for future reference, we describe our new Lasso method as the classifier-Lasso or C-Lasso.

Fourth, we develop a limit theory for the C-Lasso that demonstrates its capacity to achieve simultaneous classification and consistent estimation in a single step. As mentioned in the Abstract, the paper develops two classes of estimators for panel structure models - penalized least squares (PLS) and penalized GMM (PGMM). The former is applicable to panel models without endogenous regressors and with or without dynamic structures, while the latter is applicable to panel models with endogeneity or dynamic structures. In either case, we show uniform classification consistency in the sense that all individuals belonging to a certain group can be classified into the same group correctly uniformly over both individuals and group identities with probability approaching one (w.p.a.1). Conversely, all individuals that are classified into a certain group belong to the same group uniformly over both individuals and group identities w.p.a.1. Under some regularity conditions, such a uniform result allows us to establish an oracle property of the PLS estimator that it is asymptotically equivalent to the corresponding infeasible estimator of the group-specific parameter vector that is obtained by knowing all individual group identities. Note that traditional Lasso only possesses the selection consistency and oracle property under the so-called restrictive irrepresentable condition. This shortcoming of Lasso motivated Zou (2006) to propose the adaptive Lasso that possess these attractive properties. ${ }^{1}$ Unfortunately, our PGMM estimator generally does not have the oracle property despite the uniform selection consistency of the C-Lasso. The uniform classification consistency also allows us to develop a limit theory for post-C-Lasso estimators that are obtained by pooling all individuals in an estimated group to estimate the group-specific parameters.

Fifth, C-Lasso enables empirical researchers to study panel structures without a priori knowledge of the number of groups, without the need to specify any ancillary regression models to model individual group identities, and with no need to make any distributional assumptions. When the number $K_{0}$ of groups is unknown, a BIC-type information criterion is proposed to determine the number of groups and it is shown that this procedure selects the correct number of groups consistently. The same information criterion can also be used to determine a data-driven tuning parameter for the PLS or PGMM estimation.

Sixth, while the focus of the present paper is linear panel data models, the methodology developed here can be extended to nonlinear models such as discrete choice models, to semiparametric and nonparametric models, to models where only a subset of parameters are allowed to be group-specific, and to models where one considers group-specific effects along the time dimension. Extension to panel data models with interactive-fixed effects is also possible and is presently under way.

We envisage a large number of potential empirical applications of the C-Lasso approach within economics and finance and more broadly across the social and business sciences. The following list provides

[^1]three distinct areas of application in international macroeconomics, microeconometrics, and nonstationary panel econometrics.

1. Economic Growth Convergence: Much of the recent literature on economic growth addresses sources of possible heterogeneity, including the occurrence of multiple steady states and historydependence in growth trajectories - see Deissenberg, Feichtinger, Semmler, and Wirl (2004) and Durlauf, Johnson, and Temple (2005) and Eberhardt and Teal (2011) for overviews of the relevant growth theory and empirics. Contingent upon historical conditions economic systems may converge towards distinct steady states, the empirical manifestation of which are the so-called convergence clubs that occur in crosscountry growth studies. In an application to cross-country growth, Phillips and Sul (2007a) evaluated evidence in support of panel data growth clustering, locating three convergence clubs and one divergent group among 88 countries in the Penn World Tables in terms of real per capita GDP over the period 1960-1996. Their methodology involved a stepwise algorithm with multi-level decision making to isolate the convergence clubs. The panel structure framework suggested in the present paper is a natural setting to consider growth convergence and the C-Lasso procedure provides a one step classifier and estimation approach with no sequential decision making. The method can also be used to isolate convergence clubs and remaining divergent elements in the panel.
2. Subsample Studies of Stability: Much empirical research is concerned with studying the stability of certain regression coefficients over subsamples of the data. In this work, the whole sample is split into multiple subsamples and regression relationships are checked for coefficient stability. The groupings may be arbitrarily selected or may be determined by covariates or thresholds, each of which may have a significant impact on the findings. For example, in order to test whether financing constraints affect investment decisions, Fazzari, Hubbard, and Petersen (1988) divided a sample of firms into multiple groups based on empirical proxies such as the dividend-income ratio. Similarly, in testing whether liquidity constraints affect consumption decisions in PSID data, Zeldes (1989) uses two different wealth-to-income ratios as prescribed variables to divide the sample into subsamples. Sample splitting techniques of this type are inevitably vulnerable to the choice of prescribed driver variables. The methodology of the present paper does not require driver variables or thresholds to determine regression stability.
3. Panel Unit Root Grouping: Several approaches are available for testing the presence of unit roots in panel data. Two popular tests in applications are the Levin, Lin, and Chu (2002) and Im, Pesaran, and Shin (2003) tests. Levin, Lin, and Chu (2002) devise an adjusted $t$-test for a unit root for various panel data models, assuming that all individuals (countries, regions, industries, etc.) have the same autoregressive (AR) coefficients while permitting individual specific effects as well as dynamic heterogeneity across individuals. Im, Pesaran, and Shin (2003) propose a test based on the average of the augmented Dickey-Fuller statistics computed for each individual series in heterogenous panels. Both tests rule out the possibility that some individual series have a unit root while others do not - precisely the empirical possibility that many argue is the most relevant in practical work (e.g. Maddala and Kim, 1998). Our methodology is designed to directly address this possibility and can be used to classify a subgroup of unit-root processes in the panel from a wider class of stationary and nonstationary processes.

The rest of the paper is organized as follows. We study the C-Lasso PLS estimation and inference of
panel structure models in Section 2. PGMM estimation and inference is addressed in Section 3. Section 4 reports Monte Carlo simulation findings. Final remarks are contained in Section 5. Proofs of the main results in the body of the paper are given in Appendices A and B. The supplementary Appendices C and D provide primitive conditions for some high level conditions that are used in the body of the paper and bias correction for the C-Lasso estimates, respectively.

NOTATION. Throughout the paper we adopt the following notation. For an $m \times n$ real matrix $A$, we write the transpose $A^{\prime}$, the Frobenius norm $\|A\|\left(\equiv\left[\operatorname{tr}\left(A A^{\prime}\right)\right]^{1 / 2}\right)$, and the Moore-Penrose inverse as $A^{+}$. When $A$ is symmetric, we use $\mu_{\max }(A)$ and $\mu_{\text {min }}(A)$ to denote the largest and smallest eigenvalues, respectively. $I_{p}$ and $\mathbf{0}_{p \times 1}$ denote the $p \times p$ identity and $p \times 1$ vector of zeros. $\mathbf{1}\{\cdot\}$ denotes the indicator function. We use "p.d." and "p.s.d." to abbreviate "positive definite" and "positive semidefinite". The operator $\xrightarrow{P}$ denotes convergence in probability, $\xrightarrow{D}$ convergence in distribution, and plim probability limit. We use $(N, T) \rightarrow \infty$ to signify that $N$ and $T$ pass jointly to infinity.

## 2 Penalized Least Squares Estimation

This section considers panel structure models without endogeneity. It is convenient to assume first that the number of groups is known and later consider the determination of the number of unknown groups.

### 2.1 Panel Structure Models

The dependent variable $y_{i t}$ is measured for individual $i=1, \ldots, N$ over time $t=1, \ldots, T$. The generating mechanism is the panel structure model

$$
\begin{equation*}
y_{i t}=\beta_{i}^{0 \prime} x_{i t}+\mu_{i}+u_{i t} \tag{2.1}
\end{equation*}
$$

where $x_{i t}$ is a $p \times 1$ vector of exogenous or predetermined variables, $\mu_{i}$ is an individual fixed effect that may be correlated with some components of $x_{i t}, u_{i t}$ is the idiosyncratic error term with zero mean, and $\beta_{i}^{0}$ is a $p \times 1$ vector of slope parameters such that

$$
\beta_{i}^{0}=\left\{\begin{array}{cc}
\alpha_{1}^{0} & \text { if } i \in G_{1}^{0}  \tag{2.2}\\
\vdots & \vdots \\
\alpha_{K_{0}}^{0} & \text { if } i \in G_{K_{0}}^{0}
\end{array}\right.
$$

Here $\alpha_{j}^{0} \neq \alpha_{k}^{0}$ for any $j \neq k, \cup_{k=1}^{K_{0}} G_{k}^{0}=\{1,2, \ldots, N\}$, and $G_{k}^{0} \cap G_{j}^{0}=\varnothing$ for any $j \neq k$. Let $N_{k}=\left|G_{k}^{0}\right|$ be the cardinality of the set $G_{k}^{0}$. For the moment, we assume that the number $K_{0}$ of groups is known and fixed but that each individual's group membership is unknown. In addition, following Sun (2005) and Lin and Ng (2012), we implicitly assume that individual group membership does not vary over time. Let

$$
\begin{equation*}
\boldsymbol{\alpha} \equiv\left(\alpha_{1}, \ldots, \alpha_{K_{0}}\right) \text { and } \boldsymbol{\beta} \equiv\left(\beta_{1}, \ldots, \beta_{N}\right) \tag{2.3}
\end{equation*}
$$

The true values of $\boldsymbol{\alpha}$ and $\boldsymbol{\beta}$ are denoted as $\boldsymbol{\alpha}^{0}$ and $\boldsymbol{\beta}^{0}$, respectively. We are interested in developing econometric methods to infer each individual's group identity and to estimate the $p \times K_{0}$ matrix $\boldsymbol{\alpha}^{0}$ of group-specific coefficients.

### 2.2 Penalized Least Squares Estimation of $\alpha$ and $\beta$

Our starting point is to develop PLS estimation of $\boldsymbol{\alpha}$ and $\boldsymbol{\beta}$ when the elements of $x_{i t}$ are either strictly exogenous or predetermined so that least squares criteria are appropriate. We first apply ordinary least squares (OLS) regression, minimizing the following objective function ${ }^{2}$

$$
Q_{0, N T}(\boldsymbol{\beta}, \boldsymbol{\mu})=\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T}\left(y_{i t}-\beta_{i}^{\prime} x_{i t}-\mu_{i}\right)^{2}
$$

where $\boldsymbol{\mu}=\left(\mu_{1}, \mu_{2}, \ldots, \mu_{N}\right)^{\prime}$. Since the individual effects $\mu_{i}$ are not of primary interest, we concentrate them out and obtain the following concentrated function

$$
Q_{1, N T}(\boldsymbol{\beta})=\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\beta_{i}^{\prime} \tilde{x}_{i t}\right)^{2}
$$

giving the OLS estimates $\hat{\beta}_{i}^{O L S}=\left(\frac{1}{T} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{-1}\left(\frac{1}{T} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{y}_{i t}\right)^{-1}$, where $\tilde{x}_{i t}=x_{i t}-T^{-1} \sum_{t=1}^{T} x_{i t}$ and $\tilde{y}_{i t}=y_{i t}-T^{-1} \sum_{t=1}^{T} y_{i t}$.

Motivated by the literature on group Lasso (e.g., Yuan and Li, 2006), we next propose to estimate $\boldsymbol{\beta}$ and $\boldsymbol{\alpha}$ by minimizing the following PLS criterion function

$$
\begin{equation*}
Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}(\boldsymbol{\beta}, \boldsymbol{\alpha})=Q_{1, N T}(\boldsymbol{\beta})+\frac{\lambda_{1}}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K_{0}}\left\|\beta_{i}-\alpha_{k}\right\| \tag{2.4}
\end{equation*}
$$

where $\lambda_{1}=\lambda_{1 N T}$ is a tuning parameter. Minimizing the above criterion function produces classifierLasso (C-Lasso) estimates $\hat{\boldsymbol{\beta}}$ and $\hat{\boldsymbol{\alpha}}$ of $\boldsymbol{\beta}$ and $\boldsymbol{\alpha}$, respectively. Let $\hat{\beta}_{i}$ and $\hat{\alpha}_{k}$ denote the $i^{\text {th }}$ and $k^{\text {th }}$ columns of $\hat{\boldsymbol{\beta}}$ and $\hat{\boldsymbol{\alpha}}$, respectively, i.e., $\hat{\boldsymbol{\alpha}} \equiv\left(\hat{\alpha}_{1}, \ldots, \hat{\alpha}_{K}\right)$ and $\hat{\boldsymbol{\beta}} \equiv\left(\hat{\beta}_{1}, \ldots, \hat{\beta}_{N}\right)$.

The penalty term in (2.4) takes a novel mixed additive-multiplication form that does not appear in the literature. Traditionally Lasso includes an additive penalty term to the least-squares, GMM, or loglikelihood objective function. When multiple penalty terms are needed, they also enter the objective function additively. In contrast, the C-Lasso method has $N$ additive terms, each of which takes a multiplicative form as the product of $K_{0}$ separate penalties. Each of the $K_{0}$ penalty terms in the multiplicative expression shrinks the individual-level slope parameter vector $\beta_{i}$ to a particular unknown group-level parameter vector $\alpha_{k}$. This approach differs from the prototypical Lasso method of Tibshirani (1996) that shrinks a parameter to zero as well as the group Lasso method of Yuan and Lin (2006) that shrinks a parameter vector to a vector of zeros.

Note that the objective function in (2.4) is not convex in $\boldsymbol{\beta}$ even though it is (conditionally) convex in $\alpha_{k}$ when one fixes $\alpha_{j}$ for $j \neq k$. We propose the following iterative algorithm to obtain the estimates $\hat{\boldsymbol{\alpha}}$ and $\hat{\boldsymbol{\beta}}$.

## Numerical Algorithm:

[^2]1. Start with arbitrary initial values $\hat{\boldsymbol{\alpha}}^{(0)}=\left(\hat{\alpha}_{1}^{(0)}, \ldots, \hat{\alpha}_{K_{0}}^{(0)}\right)$ and $\hat{\boldsymbol{\beta}}^{(0)}=\left(\hat{\beta}_{1}^{(0)}, \ldots, \hat{\beta}_{N}^{(0)}\right)$ such that $\sum_{i=1}^{N}\left\|\hat{\beta}_{i}^{(0)}-\hat{\alpha}_{k}^{(0)}\right\| \neq 0$ for each $k=2, \ldots, K_{0} .^{3}$
2. Having obtained $\hat{\boldsymbol{\alpha}}^{(r-1)} \equiv\left(\hat{\alpha}_{1}^{(r-1)}, \ldots, \hat{\alpha}_{K_{0}}^{(r-1)}\right)$ and $\hat{\boldsymbol{\beta}}^{(r-1)} \equiv\left(\hat{\beta}_{1}^{(r-1)}, \ldots, \hat{\beta}_{N}^{(r-1)}\right)$, in step $r \geq 1$, we first choose $\left(\boldsymbol{\beta}, \alpha_{1}\right)$ to minimize

$$
Q_{K_{0} N T}^{(r, 1)}\left(\boldsymbol{\beta}, \alpha_{1}\right)=Q_{1, N T}(\boldsymbol{\beta})+\frac{\lambda_{1}}{N} \sum_{i=1}^{N}\left\|\beta_{i}-\alpha_{1}\right\| \Pi_{k \neq 1}^{K_{0}}\left\|\hat{\beta}_{i}^{(r-1)}-\hat{\alpha}_{k}^{(r-1)}\right\|
$$

and obtain the updated estimate $\left(\hat{\boldsymbol{\beta}}^{(r, 1)}, \hat{\alpha}_{1}^{(r)}\right)$ of $\left(\boldsymbol{\beta}, \alpha_{1}\right)$. Next choose $\left(\boldsymbol{\beta}, \alpha_{2}\right)$ to minimize

$$
Q_{K_{0} N T}^{(r, 2)}\left(\boldsymbol{\beta}, \alpha_{2}\right)=Q_{1, N T}(\boldsymbol{\beta})+\frac{\lambda_{1}}{N} \sum_{i=1}^{N}\left\|\beta_{i}-\alpha_{2}\right\|\left\|\hat{\beta}_{i}^{(r, 1)}-\hat{\alpha}_{1}^{(r)}\right\| \Pi_{k \neq 1,2}^{K_{0}}\left\|\hat{\beta}_{i}^{(r-1)}-\hat{\alpha}_{k}^{(r-1)}\right\|
$$

to obtain the updated estimate $\left(\hat{\boldsymbol{\beta}}^{(r, 2)}, \hat{\alpha}_{2}^{(r)}\right)$ of $\left(\boldsymbol{\beta}, \alpha_{2}\right)$. Repeat this procedure until $\left(\boldsymbol{\beta}, \alpha_{K_{0}}\right)$ is chosen to minimize

$$
Q_{K_{0} N T}^{\left(r, K_{0}\right)}\left(\boldsymbol{\beta}, \alpha_{K_{0}}\right)=Q_{1, N T}(\boldsymbol{\beta})+\frac{\lambda_{1}}{N} \sum_{i=1}^{N}\left\|\beta_{i}-\alpha_{K_{0}}\right\| \Pi_{k=1}^{K_{0}-1}\left\|\hat{\beta}_{i}^{(r, k)}-\hat{\alpha}_{k}^{(r)}\right\|
$$

to obtain the updated estimate $\left(\hat{\boldsymbol{\beta}}^{\left(r, K_{0}\right)}, \hat{\alpha}_{K_{0}}^{(r)}\right)$ of $\left(\boldsymbol{\beta}, \alpha_{K_{0}}\right)$. Let $\hat{\boldsymbol{\beta}}^{(r)}=\hat{\boldsymbol{\beta}}^{\left(r, K_{0}\right)}$ and $\hat{\boldsymbol{\alpha}}^{(r)}=\left(\hat{\alpha}_{1}^{(r)}, \ldots, \hat{\alpha}_{K_{0}}^{(r)}\right)$.
3. Repeat step 2 until a convergence criterion is met, e.g. when

$$
\frac{\sum_{i=1}^{N}\left\|\hat{\beta}_{i}^{(r)}-\hat{\beta}_{i}^{(r-1)}\right\|^{2}}{\sum_{i=1}^{N}\left\|\hat{\beta}_{i}^{(r-1)}\right\|^{2}+0.0001}<\epsilon_{t o l} \text { and } \frac{\sum_{k=1}^{K_{0}}\left\|\hat{\alpha}_{k}^{(r)}-\hat{\alpha}_{k}^{(r-1)}\right\|^{2}}{\sum_{k=1}^{K_{0}}\left\|\hat{\alpha}_{k}^{(r-1)}\right\|^{2}+0.0001}<\epsilon_{t o l}
$$

where $\epsilon_{t o l}$ is some prescribed tolerance level (e.g., 0.0001). Define the final iterative estimate of $\boldsymbol{\alpha}$ as $\hat{\boldsymbol{\alpha}}=\left(\hat{\alpha}_{1}^{(R)}, \ldots, \hat{\alpha}_{K_{0}}^{(R)}\right)$ for sufficiently large $R$ such that the convergence criterion is met. The final iterative estimate of $\boldsymbol{\beta}$ is defined as $\hat{\boldsymbol{\beta}}=\left(\hat{\beta}_{1}, \ldots, \hat{\beta}_{N}\right)$ where

$$
\begin{align*}
\hat{\beta}_{i}= & \sum_{k=1}^{K_{0}} \hat{\alpha}_{k}^{(R)} \mathbf{1}\left\{\hat{\beta}_{i}^{(R, l)}=\hat{\alpha}_{k}^{(R)} \text { for some } l=1, \ldots, K_{0}\right\} \\
& +\hat{\beta}_{i}^{\left(R, K_{0}\right)}\left[1-\sum_{k=1}^{K_{0}} \mathbf{1}\left\{\hat{\beta}_{i}^{(R, l)}=\hat{\alpha}_{k}^{(R)} \text { for some } l=1, \ldots, K_{0}\right\}\right] \tag{2.5}
\end{align*}
$$

where $\hat{\beta}_{i}^{(R, l)}$ denotes the $i^{\text {th }}$ column of $\hat{\boldsymbol{\beta}}^{(R, l)}$ for $l=1,2, \ldots, K$. Intuitively, individual $i$ is classified to group $\hat{G}_{k}$ if $\hat{\beta}_{i}^{(R, l)}=\hat{\alpha}_{k}^{(R)}$ for some $l=1, \ldots, K_{0}$; otherwise it is left unclassified so that $\hat{\beta}_{i}$ is defined as $\hat{\beta}_{i}^{\left(R, K_{0}\right)}$.

[^3]Obviously, each iteration step $r$ has $K_{0}$ substeps and we can use $r$. $k$ to denote substep $k$ within step $r$. Note the objective function $Q_{K_{0} N T}^{(r, k)}\left(\boldsymbol{\beta}, \alpha_{k}\right)$ is convex in $\left(\boldsymbol{\beta}, \alpha_{k}\right)$ in each substep r.k. So the above iteration procedure has fast implementation in practice. Moreover, in view of the fact that
$Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\hat{\boldsymbol{\beta}}^{(r-1)}, \hat{\boldsymbol{\alpha}}^{(r-1)}\right) \geq Q_{K_{0} N T}^{(r, 1)}\left(\hat{\boldsymbol{\beta}}^{(r, 1)}, \hat{\alpha}_{1}^{(r)}\right) \geq \cdots \geq Q_{K_{0} N T}^{(r, 1)}\left(\hat{\boldsymbol{\beta}}^{\left(r, K_{0}\right)}, \hat{\alpha}_{K}^{(r)}\right)=Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\hat{\boldsymbol{\beta}}^{(r)}, \hat{\boldsymbol{\alpha}}^{(r)}\right)$,
the convergence of $\left(\hat{\boldsymbol{\beta}}^{(r)}, \hat{\boldsymbol{\alpha}}^{(r)}\right)$ is readily established and simulations confirm that convergence is rapid, usually occurring after just a few iterations.

### 2.3 Preliminary Rates of Convergence for Coefficient Estimates

We first present sufficient conditions to ensure the consistency of $(\hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\alpha}})$. Let $\tilde{u}_{i t}=u_{i t}-T^{-1} \sum_{t=1}^{T} u_{i t}$, $\hat{Q}_{i, \tilde{x} \tilde{x}}=\frac{1}{T} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}$, and $\hat{Q}_{i, \tilde{x} \tilde{u}}=\frac{1}{T} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}$. We make the following assumption.
ASSUMPTION A1. (i) $\frac{1}{\sqrt{T}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}=O_{P}(1)$ for each $i=1, \ldots, N$.
(ii) $\hat{Q}_{i, \tilde{x} \tilde{x}} \xrightarrow{P} Q_{i, \tilde{x} \tilde{x}}>0$ for each $i=1, \ldots, N$. There exists a constant $\underline{c}_{\tilde{x} \tilde{x}}$ such that $\underline{\lim }_{(N, T) \rightarrow \infty} \min _{1 \leq i \leq N}$ $\mu_{\text {min }}\left(\hat{Q}_{i, \tilde{x} \tilde{x}}\right) \geq \underline{c}_{\tilde{x} \tilde{x}}>0$.
(iii) $\frac{1}{N} \sum_{i=1}^{N}\left\|\hat{Q}_{i, \tilde{x} \tilde{u}}\right\|^{2}=O_{P}\left(T^{-1}\right)$.
(iv) $N_{k} / N \rightarrow \tau_{k} \in(0,1)$ for each $k=1, \ldots, K_{0}$ as $N \rightarrow \infty$.
(v) $\lambda_{1} \rightarrow 0$ as $(N, T) \rightarrow \infty$.

Assumption $\mathrm{A} 1(\mathrm{i})$ is rather weak and will be satisfied in most (stable) large dimensional linear panel data models without endogeneity. Sufficient conditions for A1(i) to hold are

$$
\frac{1}{\sqrt{T}} \sum_{t=1}^{T} x_{i t} u_{i t}, \frac{1}{\sqrt{T}} \sum_{t=1}^{T} u_{i t}, \frac{1}{T} \sum_{t=1}^{T} x_{i t}=O_{P}(1), \text { for each } i=1, \ldots, N
$$

More primitive conditions for $\mathrm{A} 1(\mathrm{i})$ to hold include $\mathbb{E}\left(u_{i t}\right)=0, \mathbb{E}\left(x_{i t} u_{i t}\right)=0$ and suitable moment and weak dependence conditions on the process $\left\{\left(x_{i t}, u_{i t}\right), t \geq 1\right\}$ that ensure CLT validity. Note that we do not require that the panel model be dynamically correctly specified in the sense that $\mathbb{E}\left(u_{i t} \mid \mathcal{F}_{i, t-1}\right)=0$ where $\mathcal{F}_{i, t-1}$ is the sigma-field generated by $\left(x_{i t}, x_{i, t-1}, u_{i, t-1}, \ldots\right)$. Instead, we allow both conditional heteroskedasticity and serial correlation in $\left\{u_{i t}, t \geq 1\right\}$.

Assumption A1(ii) contains two parts, the first part being standard and the second part being a highlevel condition. Appendix C. 1 gives primitive conditions to ensure the second part. Intuitively, these conditions impose some restrictions on the moments of $x_{i t}$, the dependence structure on the processes $\left\{x_{i t}, t \geq 1\right\}$, and the relative rates at which $N$ and $T$ pass to infinity. More specifically, under suitable weak dependence conditions, if $\left\|x_{i t}\right\|^{2}$ exhibits only $2 q$-th finite moments for some $q>1$, then we need a stringent (lower rate) condition on the expansion of $T$, viz., $T / N^{\epsilon} \rightarrow c \in(0, \infty]$ for some $\epsilon>1 /(2 q-1)$. On the other hand, if $\left\|x_{i t}\right\|^{2}$ has finite exponential moments with an index parameter $\gamma$ as specified in Assumption C1(iv), then only $T /(\ln N)^{(1+\gamma) / \gamma} \rightarrow \infty$ is required for sufficiency. In the extreme case, if $x_{i t}$ is uniformly bounded (i.e., $\gamma=\infty$ ), it simply suffices that $T / \ln N \rightarrow \infty$.

A1(iii) can be easily verified via the Markov inequality. A1(iv) implies that each group has an asymptotically non-negligible membership number of individuals as $N \rightarrow \infty$. This assumption can be
relaxed at the cost of more lengthy arguments, in which case the estimates of $\alpha_{k}^{0}, k=1, \ldots, K_{0}$, will exhibit different convergence rates. A1(v) implies that the penalty term cannot be too large.

The following theorem establishes the consistency of the PLS estimates $\left\{\hat{\beta}_{i}\right\}$ and $\left\{\hat{\alpha}_{k}\right\}$.
Theorem 2.1 Suppose that Assumption A1 holds. Then
(i) $\hat{\beta}_{i}-\beta_{i}^{0}=O_{P}\left(T^{-1 / 2}+\lambda_{1}\right)$ for $i=1,2, \ldots, N$,
(ii) $\frac{1}{N} \sum_{i=1}^{N}\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\|^{2}=O_{P}\left(T^{-1}\right)$,
(iii) $\left(\hat{\alpha}_{(1)}, \ldots, \hat{\alpha}_{\left(K_{0}\right)}\right)-\left(\alpha_{1}^{0}, \ldots, \alpha_{K_{0}}^{0}\right)=O_{P}\left(T^{-1 / 2}\right)$
where $\left(\hat{\alpha}_{(1)}, \ldots, \hat{\alpha}_{\left(K_{0}\right)}\right)$ is a suitable permutation of $\left(\hat{\alpha}_{1}, \ldots, \hat{\alpha}_{K_{0}}\right)$.
REMARK 1. Parts (i) and (ii) of Theorem 2.1 establish the pointwise and mean-square convergence of $\hat{\beta}_{i}$. Part (iii) of Theorem 2.1 indicates that the group-specific parameters $\alpha_{1}^{0}, \ldots, \alpha_{K}^{0}$ can also be estimated consistently by $\hat{\alpha}_{1}, \ldots, \hat{\alpha}_{K_{0}}$ subject to permutation. As expected and consonant with other Lasso limit theory, the pointwise convergence rate of $\hat{\beta}_{i}$ depends on the rate at which the tuning parameter $\lambda_{1}$ converges to zero. Somewhat unexpectedly, this requirement is not the case either for mean-square convergence of $\hat{\beta}_{i}$ or convergence of $\hat{\alpha}_{k}$. To appreciate why, define

$$
\begin{equation*}
Q_{1 N T, i}\left(\beta_{i}\right)=\frac{1}{T} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\beta_{i}^{\prime} \tilde{x}_{i t}\right)^{2} \text { and } Q_{1 i N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\beta_{i}, \boldsymbol{\alpha}\right)=Q_{1 N T, i}\left(\beta_{i}\right)+\lambda_{1} \Pi_{k=1}^{K_{0}}\left\|\beta_{i}-\alpha_{k}\right\| \tag{2.6}
\end{equation*}
$$

The proof of Theorem 2.1(i) simply relies on the observations that $Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}(\boldsymbol{\beta}, \boldsymbol{\alpha})=\frac{1}{N} \sum_{i=1}^{N} Q_{1 i N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\beta_{i}, \boldsymbol{\alpha}\right)$ and that

$$
\begin{align*}
& Q_{1 i N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\hat{\beta}_{i}, \hat{\boldsymbol{\alpha}}\right)-Q_{1 i N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\beta_{i}^{0}, \hat{\boldsymbol{\alpha}}\right) \\
= & Q_{1 N T, i}\left(\hat{\beta}_{i}\right)-Q_{1 N T, i}\left(\beta_{i}^{0}\right)+\lambda_{1}\left\{\Pi_{k=1}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\|-\Pi_{k=1}^{K_{0}}\left\|\beta_{i}^{0}-\hat{\alpha}_{k}\right\|\right\} \leq 0 . \tag{2.7}
\end{align*}
$$

The inequality in (2.7) holds because once $\hat{\boldsymbol{\alpha}}$ is determined, $\hat{\beta}_{i}$ must minimize $Q_{1 i N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\beta_{i}, \hat{\boldsymbol{\alpha}}\right)$ with respect to $\beta_{i}$. By (2.7) and the repeated use of triangle inequality, we can readily establish the claim in Theorem 2.1(i). Nevertheless, the result in Theorem 2.1(ii) relies on the observation

$$
\begin{equation*}
Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}(\hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\alpha}})-Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\boldsymbol{\beta}^{0}, \boldsymbol{\alpha}^{0}\right) \leq 0 \tag{2.8}
\end{equation*}
$$

We prove it by showing that for any small $\epsilon^{*}>0$, there exists an $L=L\left(\epsilon^{*}\right)$ such that the above inequality cannot hold with probability $1-\epsilon^{*}$ if $\frac{1}{N} \sum_{i=1}^{N}\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\|^{2} \geq L / T$. This forces the claim in Theorem 2.1(ii) to hold. Let $P_{N T}(\boldsymbol{\beta}, \boldsymbol{\alpha})=\frac{1}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K_{0}}\left\|\beta_{i}-\alpha_{k}\right\|$. The proof of Theorem 2.1(iii) is based on the observation that

$$
\begin{equation*}
P_{N T}(\hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\alpha}})-P_{N T}\left(\hat{\boldsymbol{\beta}}, \boldsymbol{\alpha}^{0}\right) \leq 0 \tag{2.9}
\end{equation*}
$$

and the fact that the convergence rate of $\hat{\alpha}_{k}$ (up to permutation) fully depends on the mean-square convergence rate of $\hat{\beta}_{i}$. Apparently if $\lambda_{1}=O\left(T^{-1 / 2}\right)$, we get the usual $\sqrt{T}$-convergence rate for the $\hat{\beta}_{i}$. But this choice of $\lambda_{1}$ may not be optimal for the classification.

For notational simplicity, hereafter we simply write $\hat{\alpha}_{k}$ for $\hat{\alpha}_{(k)}$ as the consistent estimator of $\alpha_{k}^{0}$, and define

$$
\begin{equation*}
\hat{G}_{k}=\left\{i \in\{1,2, \ldots, N\}: \hat{\beta}_{i}=\hat{\alpha}_{k}\right\} \text { for } k=1, \ldots, K_{0} \tag{2.10}
\end{equation*}
$$

### 2.4 Classification Consistency

This section studies classification consistency. Roughly speaking, a classification method is consistent if it classifies each individual to the correct group with probability approaching 1 (w.p.a.1). For a rigorous statement of this property we define the following sequences of events

$$
\begin{equation*}
\hat{E}_{k N T, i}=\left\{i \notin \hat{G}_{k} \mid i \in G_{k}^{0}\right\} \text { and } \hat{F}_{k N T, i}=\left\{i \notin G_{k}^{0} \mid i \in \hat{G}_{k}\right\} \tag{2.11}
\end{equation*}
$$

where $i=1, \ldots, N$ and $k=1, \ldots, K_{0}$. Let $\hat{E}_{k N T}=\cup_{i \in G_{k}^{0}} \hat{E}_{k N T, i}$ and $\hat{F}_{k N T}=\cup_{i \in \hat{G}_{k}} \hat{F}_{k N T, i}$. The events $\hat{E}_{k N T}$ and $\hat{F}_{k N T}$ mimic Type I and II errors in statistical tests: $\hat{E}_{k N T}$ denotes the error event of not classifying an element of $G_{k}^{0}$ into the estimated group $\hat{G}_{k}$; and $\hat{F}_{k N T}$ denotes the error event of classifying an element that does not belong to $G_{k}^{0}$ into the estimated group $\hat{G}_{k}$. To achieve uniform consistency in estimation both error types must be controlled. We use the following definition.

Definition 1. (Uniform consistency of classification) We say that a classification method is individually consistent if $P\left(\hat{E}_{k N T, i}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$ for each $i \in G_{k}^{0}$ and $k=1, \ldots, K_{0}$, and $P\left(\hat{F}_{k N T, i}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$ for each $i \in \hat{G}_{k}$ and $k=1, \ldots, K_{0}$. It is uniformly consistent if $P\left(\cup_{k=1}^{K_{0}} \hat{E}_{k N T}\right) \rightarrow 0$ and $P\left(\cup_{k=1}^{K_{0}} \hat{F}_{k N T}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$.

To establish consistency of the PLS classifier we add the following assumption.
ASSUMPTION A2. (i) $T \lambda_{1} \rightarrow \infty$ and $T \lambda_{1}^{4} \rightarrow c_{0} \in[0, \infty)$ as $(N, T) \rightarrow \infty$.
(ii) For any $c>0, N \max _{1 \leq i \leq N} P\left(\left\|T^{-1} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}\right\| \geq c \sqrt{\lambda_{1}}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$.

Assumption A2(i) is required for individual consistency of the PLS classifier. Assumption A2(ii) is a high level assumption that ensures the uniform consistency of the classifier. In Appendix C, we verify this condition for strong mixing processes with geometric decay rates under certain moment conditions. In particular, if (a) $\left\|x_{i t}\right\|,\left|u_{i t}\right|$, and $\left\|x_{i t} u_{i t}\right\|$ have finite $2 q^{\text {th }}$ moments, then A2(ii) will be satisfied provided

$$
\begin{equation*}
\lambda_{1} \gg \max \left\{T^{-1} \ln N, T^{-2}(N T)^{1 / q}(\ln T)^{4}(\ln N)^{2}\right\} \tag{2.12}
\end{equation*}
$$

(b) if $\left\|x_{i t}\right\|,\left|u_{i t}\right|$, and $\left\|x_{i t} u_{i t}\right\|$ have exponential moments with an index parameter $\gamma$, then A2(ii) will be satisfied provided

$$
\begin{equation*}
\lambda_{1} \gg \max \left\{T^{-1} \ln N, T^{-2}[\ln (N T)]^{2(1+\gamma) / \gamma}\right\} \tag{2.13}
\end{equation*}
$$

In either case, we need $T \lambda_{1} \gg \ln N$. If $T \propto N^{\epsilon_{1}}$ for some $\epsilon_{1}>1 /(q-1)$ in case (a) and $T \propto N^{\epsilon_{2}}$ for some $\epsilon_{2}>0$ in case (b), then we can easily verify that $T \lambda_{1} \gg \ln N$ would also be sufficient to ensure A2(ii). Combining this requirement with A2(i) suggests that under certain conditions on the moments and on the related rates at which $N$ and $T$ pass to infinity, it suffices to require that

$$
\begin{equation*}
\lambda_{1} \propto T^{-a} \text { for any } a \in[1 / 4,1) \tag{2.14}
\end{equation*}
$$

The following theorem establishes uniform consistency for the PLS classifier.
Theorem 2.2 Suppose that Assumptions A1-A2 hold. Then
(i) $P\left(\cup_{k=1}^{K_{0}} \hat{E}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} P\left(\hat{E}_{k N T}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$,
(ii) $P\left(\cup_{k=1}^{K_{0}} \hat{F}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} P\left(\hat{F}_{k N T}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$.

REMARK 2. Theorem 2.2 implies that all individuals within a certain group, say $G_{k}^{0}$, can be simultaneously correctly classified into the same group (denoted $\hat{G}_{k}$ ) w.p.a.1. Conversely, all individuals that are classified into the same group, say $\hat{G}_{k}$, simultaneously correctly belong to the same group $\left(G_{k}^{0}\right)$ w.p.a.1. Let $\hat{G}_{0}$ denote the group of individuals in $\{1,2, \ldots, N\}$ that are not classified into any of the $K_{0}$ groups, i.e., $\hat{G}_{0}=\{1,2, \ldots, N\} \backslash\left(\cup_{k=1}^{K_{0}} \hat{G}_{k}\right)$. Define the events $\hat{H}_{i N T}=\left\{i \in \hat{G}_{0}\right\}$. Theorem 2.2(i) implies that $P\left(\cup_{1 \leq i \leq N} \hat{H}_{i N T}\right) \leq \sum_{k=1}^{K_{0}} P\left(\hat{E}_{k N T}\right) \rightarrow 0$. That is, all individuals can be classified into one of the $K_{0}$ groups w.p.a.1. Nevertheless, when $T$ is not large, it is possible for a small percentage of individuals to be left unclassified if we stick with the classification method defined in (2.10). To ensure that all individuals are classified into one of the $K_{0}$ groups in finite samples, one need only slightly modify the classifier to achieve it. In particular, we classify $i \in \hat{G}_{k}$ if $\hat{\beta}_{i}=\hat{\alpha}_{k}$ for some $k=1, \ldots, K_{0}$, and $i \in \hat{G}_{l}$ for some $l=1, \ldots, K_{0}$ if

$$
\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\|=\min \left\{\left\|\hat{\beta}_{i}-\hat{\alpha}_{1}\right\|, \ldots,\left\|\hat{\beta}_{i}-\hat{\alpha}_{K}\right\|\right\} \text { and } \sum_{k=1}^{K_{0}} 1\left\{\hat{\beta}_{i}=\hat{\alpha}_{k}\right\}=0 .
$$

Since the event $\sum_{k=1}^{K_{0}} \mathbf{1}\left\{\hat{\beta}_{i}=\hat{\alpha}_{k}\right\}=0$ occurs with probability tending to zero uniformly in $i$, we can ignore it in large samples in subsequent theoretical analysis and restrict our attention to the previous classification rule in (2.10) to avoid confusion. That is, $\hat{G}_{k}=\left\{i \in\{1, \ldots, N\}: \hat{\beta}_{i}=\hat{\alpha}_{k}\right\}$ for $k=1, \ldots, K_{0}$.

Let $\hat{N}_{k}=\sum_{i=1}^{N} \mathbf{1}\left\{i \in \hat{G}_{k}\right\}$. The following corollary indicates that we can estimate the number of individuals within each group consistently.

Corollary 2.3 Suppose that Assumptions A1-A2 hold. Then $\hat{N}_{k}-N_{k}=o_{P}(1)$ for $k=1, \ldots, K_{0}$.

### 2.5 The Oracle Property and Asymptotic Properties of Post-Lasso

To establish the oracle property of the PLS estimates $\left\{\hat{\alpha}_{k}\right\}$, we add the following assumption.
ASSUMPTION A3. (i) For each $k=1, \ldots, K_{0}, \bar{\Phi}_{k} \equiv \frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime} \xrightarrow{P} \Phi_{k}>0$ as $(N, T) \rightarrow \infty$.
(ii) For each $k=1, \ldots, K_{0}, \frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}-\mathbb{B}_{k N T} \xrightarrow{D} N\left(0, \Psi_{k}\right)$ as $(N, T) \rightarrow \infty$ where $\mathbb{B}_{k N T}=\frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \mathbb{E}\left(x_{i t} \tilde{u}_{i t}\right)$ is either 0 or $O\left(\sqrt{N_{k} / T}\right)$ depending on whether $x_{i t}$ is strictly exogenous.

Assumption A3 is a convenient high level condition. It can be verified under various commonly occurring primitive conditions. For example, if (a) $\left\{\left(x_{i t}, u_{i t}\right)\right\}$ is a stationary strong mixing process with a geometric mixing rate along the time dimension and is independently and identically distributed (IID) along the cross section dimension for all individuals within the same group $G_{k}^{0}$, (b) $x_{i t}$ and $x_{i t} u_{i t}$ have finite two-plus moments, and (c) $\mathbb{E}\left(x_{i t} \tilde{u}_{i t}\right)=0$ and $\mathbb{E}\left(u_{i t}\right)=0$, then A 3 is satisfied with $\mathbb{B}_{k N T}=0$, $\Phi_{k}=\operatorname{Var}\left(x_{i t}\right)$, and $\Psi_{k}=\lim _{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^{T} \sum_{s=1}^{T} \mathbb{E}\left(x_{i t} x_{i s}^{\prime} u_{i t} u_{i s}\right)$ for any $i \in G_{k}^{0}$. Apparently, condition (c) rules out the case of dynamic panel data models. If $x_{i t}$ contains lagged dependent variables (e.g., $y_{i, t-1}$ ), it is well known that the fixed effects within-group (WG) estimator has asymptotic bias of order $O(1 / T)$ in homogeneous dynamic panel data models. This suggests that $\mathbb{B}_{k N T}=O\left(\sqrt{N_{k} / T}\right)$ in dynamic panel data models and bias correction is required for statistical inference unless $T$ passes to infinity faster than
$N_{k}$. Matters of bias correction and some explicit formulae in this case are discussed below in Remark 5 and Appendix D.1.

The following theorem gives the oracle property of the Lasso estimator $\left\{\hat{\alpha}_{k}\right\}$.
Theorem 2.4 Suppose that Assumptions A1-A3 hold. Then $\sqrt{N_{k} T}\left(\hat{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T} \xrightarrow{D} N(0$, $\Phi_{k}^{-1} \Psi_{k} \Phi_{k}^{-1}$ ) for $k=1, \ldots, K_{0}$.

REMARK 3. If each individual's group membership is known, the WG estimator of $\alpha_{k}^{0}$ is $\bar{\alpha}_{k}=$ $\left(\sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{-1} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{y}_{i t}$, and then $\sqrt{N_{k} T}\left(\bar{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T} \xrightarrow{D} N\left(0, \Phi_{k}^{-1} \Psi_{k} \Phi_{k}^{-1}\right)$ under Assumption A3. Theorem 2.4 indicates that the PLS estimator $\hat{\alpha}_{k}$ achieves the same limit distribution as this oracle WG estimator with knowledge of the exact membership of each individual. In this sense, we say that the PLS estimators $\left\{\hat{\alpha}_{k}\right\}$ have the asymptotic oracle property. In the Appendix, we prove the above theorem by inspection of the Karush-Kuhn-Tucker (KKT) optimality conditions for minimizing the objective function in (2.4) based on subdifferential calculus (e.g., Bertsekas, 1995, Appendix B.5). We then show that $\sqrt{N_{k} T}\left(\hat{\alpha}_{k}-\alpha_{k}^{0}\right)=\sqrt{N_{k} T}\left(\hat{\alpha}_{\hat{G}_{k}}-\alpha_{k}^{0}\right)+o_{P}(1)$, where $\hat{\alpha}_{\hat{G}_{k}}$ is the post-Lasso estimator of $\alpha_{k}^{0}$ given by

$$
\begin{equation*}
\hat{\alpha}_{\hat{G}_{k}}=\left(\sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{-1} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{y}_{i t} . \tag{2.15}
\end{equation*}
$$

The following theorem reports the asymptotic distribution of $\hat{\alpha}_{\hat{G}_{k}}$.
Theorem 2.5 Suppose that Assumptions A1-A3 hold. Then $\sqrt{N_{k} T}\left(\hat{\alpha}_{\hat{G}_{k}}-\alpha_{k}^{0}\right)-\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T} \xrightarrow{D} N(0$, $\Phi_{k}^{-1} \Psi_{k} \Phi_{k}^{-1}$ ) for $k=1, \ldots, K_{0}$.

REMARK 4. The proof of the above theorem is based on the uniform classification consistency results in Theorem 2.2. In a totally different framework, Belloni and Chernozhukov (2013) study post-Lasso estimators which apply OLS to the model selected by first-step penalized estimators and show that the post-Lasso estimators perform at least as well as Lasso in terms of rate of convergence and have the advantage of having a smaller bias. It would also be interesting to compare the high-order asymptotic properties of $\hat{\alpha}_{k}$ and $\hat{\alpha}_{\hat{G}_{k}}$ given that they share the same first-order asymptotic distribution. But that analysis goes beyond the scope of the current paper. We do compare the performance of the post-Lasso estimators and the C-Lasso estimators in simulations reported below.

REMARK 5. As mentioned above, $\mathbb{B}_{k N T}=0$ in Assumption A3(ii) under strict exogeneity. In the case of dynamic panel data models, we have to obtain a consistent estimate of $b_{k N T} \equiv \bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T}$ in order to perform inference. Various methods have been proposed to estimate $b_{k N T}$ in the literature under conditions that are typically simpler than the latent structure model considered here. These methods generally involve first stage consistent estimates that are subsequently plugged-into analytic formulae for the asymptotic bias function to achieve the correction. For example, Kiviet (1995) and Hahn and Kuersteiner (2002) derived bias formulae for the WG estimator of a common autoregressive coefficient in first-order autoregressive (AR(1)) panel data models with exogenous regressors and propose ways to correct the bias such as the use of plug-in corrections. Phillips and Sul (2007b) provide explicit asymptotic
bias formulae for linear dynamic panel regression estimators where the models may or may not exhibit unit roots, incidental trends, exogenous regressors, and cross section dependence, all of which lead to different formulae. Lee (2012) considers bias correction for WG estimators in higher-order autoregressive models with exogenous regressors where the lag order is possibly misspecified. Other methods, such as median unbiased estimation, indirect inference (Gourieroux, Phillips, and Yu, 2010), and X-differencing (Han, Phillips, and Sul, 2013) have been used in dynamic panel data models to avoid bias problems. To conserve space, we refer the readers directly to those papers for details of these particular formulae and the correction procedures employed. In the present case, since the formula for $b_{k N T} \equiv \bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T}$ is known and can be explicitly represented in cases such as the presence of lagged dependent variables in $x_{i t}$, we can also use a plug-in estimator to achieve bias correction. The approach is similar to that proposed in Hahn and Kuersteiner (2002) and recently reviewed in Moon et al. (2013). However, in the present model the bias term $\mathbb{B}_{k N T}=\frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \mathbb{E}\left(x_{i t} \tilde{u}_{i t}\right)$ inevitably reflects the latent structure of the model and thereby involves further complications. For instance, in the panel $\operatorname{AR}(1)$ model there is no longer a single common AR coefficient as in Hahn and Kuersteiner (2002). Implementation therefore requires plug-in estimates of each of the common autoregressive coefficients that appear in the group structures $\left\{G_{k}^{0}\right\}_{k=1}^{K_{0}}$. It follows that consistent group structure estimation by $\left\{\hat{G}_{k}\right\}_{k=1}^{K_{0}}$ is necessary for the plug-in mechanism to be feasible. To fix ideas, suppose the model (2.1) has the panel AR(1) form

$$
\begin{equation*}
y_{i t}=\beta_{i}^{0} y_{i t-1}+\mu_{i}+u_{i t}, \quad\left|\beta_{i}^{0}\right|<1 \text { for all } i, u_{i t} \sim i i d\left(0, \sigma^{2}\right) \tag{2.16}
\end{equation*}
$$

with latent structure (2.2) giving $\beta_{i}^{0}=\alpha_{k}^{0}$ for $i \in G_{k}^{0}$. Since $\mathbb{E}\left(u_{i, t-1-j} u_{i s}\right)=\sigma^{2} \mathbf{1}\{t=s+1+j\}$, we have for $i \in G_{k}^{0}$

$$
\begin{aligned}
\sum_{t=1}^{T} \mathbb{E}\left(y_{i t-1} \tilde{u}_{i t}\right) & =-T^{-1} \sum_{t, s=1}^{T} \mathbb{E}\left(y_{i t-1} u_{i s}\right)=-T^{-1} \sum_{t, s=1}^{T} \sum_{j=0}^{\infty}\left(\alpha_{k}^{0}\right)^{j} \mathbb{E}\left(u_{i, t-1-j} u_{i s}\right) \\
& =-\sigma^{2} \frac{1}{T} \sum_{s=1}^{T} \sum_{j=0}^{T-s-1}\left(\alpha_{k}^{0}\right)^{j}=-\sigma^{2} \frac{1}{T} \sum_{s=1}^{T} \frac{1-\left(\alpha_{k}^{0}\right)^{T-s}}{1-\alpha_{k}^{0}} \\
& =-\frac{\sigma^{2}}{1-\alpha_{k}^{0}}+\frac{\sigma^{2}}{1-\alpha_{k}^{0}} \frac{1}{T} \sum_{s=1}^{T}\left(\alpha_{k}^{0}\right)^{T-s}=-\frac{\sigma^{2}}{1-\alpha_{k}^{0}}+\frac{\sigma^{2}}{1-\alpha_{k}^{0}} \frac{1}{T} \frac{1-\left(\alpha_{k}^{0}\right)^{T}}{1-\alpha_{k}^{0}}
\end{aligned}
$$

so that

$$
\mathbb{B}_{k N T}=\sqrt{\frac{1}{N_{k} T}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \mathbb{E}\left(y_{i t-1} \tilde{u}_{i t}\right)=-\sqrt{\frac{N_{k}}{T}} \frac{\sigma^{2}}{1-\alpha_{k}^{0}}+O\left(\frac{1}{\sqrt{N_{k} T}}\right)
$$

Further, as $\left(N_{k}, T\right) \rightarrow \infty$ we have

$$
\bar{\Phi}_{k} \equiv \frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{y}_{i t-1}^{2} \rightarrow_{a . s} \mathbb{E}\left(y_{i t-1}^{2} \mathbf{1}\left\{i \in G_{k}^{0}\right\}\right)=\frac{\sigma^{2}}{1-\left(\alpha_{k}^{0}\right)^{2}}=\Phi_{k}
$$

so that

$$
\begin{align*}
\sqrt{N_{k} T}\left(\hat{\alpha}_{\hat{G}_{k}}-\alpha_{k}^{0}\right)-\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T}= & \sqrt{N_{k} T}\left(\hat{\alpha}_{\hat{G}_{k}}-\alpha_{k}^{0}\right)+\sqrt{\frac{N_{k}}{T}} \frac{1-\left(\alpha_{k}^{0}\right)^{2}}{1-\alpha_{k}^{0}}+O\left(\frac{1}{\sqrt{N_{k} T}}\right) \\
= & \sqrt{N_{k} T}\left(\hat{\alpha}_{\hat{G}_{k}}-\alpha_{k}^{0}+\frac{1+\alpha_{k}^{0}}{T}\right)+o_{p}(1) \\
& \xrightarrow{D} N\left(0,1-\left(\alpha_{k}^{0}\right)^{2}\right), \tag{2.17}
\end{align*}
$$

since $\Psi_{k}=\sigma^{4} /\left(1-\left(\alpha_{k}^{0}\right)^{2}\right)$ here. As in Hahn and Kuersteiner (2002), (2.17) suggests a simple bias correction within $\hat{G}_{k}$, viz.,

$$
\begin{equation*}
\tilde{\alpha}_{\hat{G}_{k}}=\hat{\alpha}_{\hat{G}_{k}}+\frac{1+\hat{\alpha}_{\hat{G}_{k}}}{T}=\frac{T+1}{T} \hat{\alpha}_{\hat{G}_{k}}+\frac{1}{T}, \quad k=1, \ldots ., K_{0}, \tag{2.18}
\end{equation*}
$$

giving bias corrected estimators for the latent structure panel $\operatorname{AR}(1)$ model (2.16). Of course, formula (2.18) gives appropriate bias correction only in the stationary case where $\left|\alpha_{k}^{0}\right|<1$ for all $k$. For the general case, see the supplementary Appendix D. 1 for the bias correction.

### 2.6 Determination of the Number of Groups

In practice, the exact number $K_{0}$ of groups is typically unknown. We assume that the true number of groups is bounded from above by a finite integer $K_{\max }$ and study the determination of the number of groups via some information criterion. Consider the following PLS criterion

$$
\begin{equation*}
Q_{1 N T, \lambda_{1}}^{(K)}(\boldsymbol{\beta}, \boldsymbol{\alpha})=Q_{1, N T}(\boldsymbol{\beta})+\frac{\lambda_{1}}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K}\left\|\beta_{i}-\alpha_{k}\right\| \tag{2.19}
\end{equation*}
$$

where $1 \leq K \leq K_{\max }$. By minimizing the objective function (2.19), we obtain the C-Lasso estimates $\left\{\hat{\beta}_{i}\left(K, \lambda_{1}\right), \hat{\alpha}_{k}\left(K, \lambda_{1}\right)\right\}$ of $\left\{\beta_{i}, \alpha_{k}\right\}$, where we make the dependence of $\hat{\beta}_{i}$ and $\hat{\alpha}_{k}$ on $\left(K, \lambda_{1}\right)$ explicit. As above, we can classify individual $i$ into group $\hat{G}_{k}\left(K, \lambda_{1}\right)$ if and only if $\hat{\beta}_{i}\left(K, \lambda_{1}\right)=\hat{\alpha}_{k}\left(K, \lambda_{1}\right)$, i.e.,

$$
\begin{equation*}
\hat{G}_{k}\left(K, \lambda_{1}\right)=\left\{i \in\{1,2, \ldots, N\}: \hat{\beta}_{i}\left(K, \lambda_{1}\right)=\hat{\alpha}_{k}\left(K, \lambda_{1}\right)\right\} \text { for } k=1, \ldots, K \tag{2.20}
\end{equation*}
$$

Let $\hat{G}\left(K, \lambda_{1}\right)=\left\{\hat{G}_{1}\left(K, \lambda_{1}\right), \ldots, \hat{G}_{K}\left(K, \lambda_{1}\right)\right\}$. Based on (2.20), define the post-Lasso estimate of $\alpha_{k}^{0}$ by

$$
\begin{equation*}
\hat{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}=\left(\sum_{i \in \hat{G}_{k}\left(K, \lambda_{1}\right)} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{+} \sum_{i \in \hat{G}_{k}\left(K, \lambda_{1}\right)} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{y}_{i t} . \tag{2.21}
\end{equation*}
$$

where $A^{+}$denotes the Moore-Penrose inverse of $A$. Let $\hat{\sigma}_{\hat{G}\left(K, \lambda_{1}\right)}^{2}=\frac{1}{N T} \sum_{k=1}^{K} \sum_{i \in \hat{G}_{k}\left(K, \lambda_{1}\right)} \sum_{t=1}^{T}\left[\tilde{y}_{i t}-\right.$ $\left.\tilde{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}^{\prime} \tilde{x}_{i t}\right]^{2}$. We propose to select the number of groups by choosing $K$ to minimize the following information criterion:

$$
\begin{equation*}
I C_{1}\left(K, \lambda_{1}\right)=\ln \left[\hat{\sigma}_{\hat{G}\left(K, \lambda_{1}\right)}^{2}\right]+\rho_{1 N T} p K \tag{2.22}
\end{equation*}
$$

where $\rho_{1 N T}$ is a tuning parameter. Similar information criteria are used to choose tuning parameters by Wang, Li, and Tsai (2007), Liao (2013), and Lu and Su (2013) for shrinkage estimation in various contexts and have been found to work satisfactorily.

We proceed to describe the asymptotic properties of (2.22). First, some notation. Let $\mathcal{K}=\left\{1,2, \ldots, K_{\max }\right\}$. We divide $\mathcal{K}$ into three subsets $\mathcal{K}_{0}, \mathcal{K}_{-}$and $\mathcal{K}_{+}$as follows

$$
\mathcal{K}_{0}=\left\{K \in \mathcal{K}: K=K_{0}\right\}, \mathcal{K}_{-}=\left\{K \in \mathcal{K}: K<K_{0}\right\}, \text { and } \mathcal{K}_{+}=\left\{K \in \mathcal{K}: K>K_{0}\right\}
$$

The sets $\mathcal{K}_{0}, \mathcal{K}_{-}$and $\mathcal{K}_{+}$denote subsets of $\mathcal{K}$ in which true, under-, and over-fitted models are produced. Let $G^{(K)}=\left(G_{K, 1}, \ldots, G_{K, K}\right)$ be any $K$-partition of the set of individual indices $\{1,2, \ldots, N\}$. Let $\mathcal{G}_{K}$ denote the collection of such partitions. Let $\hat{\sigma}_{G^{(K)}}^{2}=\frac{1}{N T} \sum_{k=1}^{K} \sum_{i \in G_{K, k}} \sum_{t=1}^{T}\left[\tilde{y}_{i t}-\hat{\alpha}_{G_{K, k}}^{\prime} \tilde{x}_{i t}\right]^{2}$, where $\hat{\alpha}_{G_{K, k}}=\left(\sum_{i \in G_{K, k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{+} \sum_{i \in G_{K, k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{y}_{i t}$. The following assumptions are useful in the asymptotic development.
ASSUMPTION A4. $A s(N, T) \rightarrow \infty, \min _{1 \leq K<K_{0}} \inf _{G^{(K)} \in \mathcal{G}_{K}} \hat{\sigma}_{G^{(K)}}^{2} \xrightarrow{P} \underline{\sigma}^{2}>\sigma_{0}^{2}$, where $\sigma_{0}^{2}=p \lim _{(N, T) \rightarrow \infty}$ $\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{u}_{i t}^{2}$.

ASSUMPTION A5. As $(N, T) \rightarrow \infty, \rho_{1 N T} \rightarrow 0$ and $\rho_{1 N T} \delta_{N T}^{2} \rightarrow \infty$ where $\delta_{N T}=N^{1 / 2} T^{1 / 2}$ if $\mathbb{B}_{k N T}=0$ and $\min \left(N^{1 / 2} T^{1 / 2}, T\right)$ otherwise.

Assumption A4 is intuitively clear and applies under primitive conditions in a variety of models, such as panel autoregressions. It requires that all under-fitted models yield asymptotic mean square errors that are larger than $\sigma_{0}^{2}$, which is delivered by the true model. A5 reflects the usual conditions for the consistency of model selection. The penalty coefficient $\rho_{1 N T}$ cannot shrink to zero either too fast or too slowly.

The following theorem justifies the use of $(2.22)$ as a selector criterion for $K$.

Theorem 2.6 Suppose that Assumptions A1-A5 hold. Then

$$
P\left(\inf _{K \in \mathcal{K}-\cup \mathcal{K}_{+}} I C_{1}\left(K, \lambda_{1}\right)>I C_{1}\left(K_{0}, \lambda_{1}\right)\right) \rightarrow 1 \text { as }(N, T) \rightarrow \infty
$$

REMARK 6. Let $K\left(\lambda_{1}\right)=\arg \min _{1 \leq K \leq K_{\max }} I C_{1}\left(K, \lambda_{1}\right)$. As Theorem 2.6 indicates, as long as $\lambda_{1}$ satisfies Assumptions A1(v) and A2, we have $P\left(K\left(\lambda_{1}\right)=K_{0}\right) \rightarrow 1$ as $(N, T) \rightarrow \infty$. Consequently, the minimizer of $I C_{1}\left(K, \lambda_{1}\right)$ with respect to $K$ is equal to $K_{0}$ w.p.a. 1 for a variety of choices of $\lambda_{1}$. In practice, it is desirable to have a data-driven method to choose the tuning parameter $\lambda_{1}$. For this purpose, define

$$
I C_{1}^{*}\left(\lambda_{1}\right)=I C_{1}\left(K\left(\lambda_{1}\right), \lambda_{1}\right)
$$

The tuning parameter can then be chosen as $\hat{\lambda}_{1}=\arg \min _{\lambda_{1} \in \Lambda_{1}} I C_{1}^{*}\left(\lambda_{1}\right)$, where $\Lambda_{1}=\left\{\lambda_{1}: \lambda_{1} \propto T^{-a}\right.$ for any $a \in[1 / 4,1)\}$ provided some conditions on the moments of $\left\|x_{i t}\right\|,\left|u_{i t}\right|$ and $\left\|x_{i t} u_{i t}\right\|$ and on the relative rates at which $N$ and $T$ pass to infinity are satisfied - see the remark after Assumption A2.

### 2.7 Extensions

Several major extensions of the C-Lasso methodology to other models and contexts are worth mentioning. We discuss four possibilities below.

1. Mixed Panel Structure Models: Consider the case where some of the parameters in $\beta_{i}^{0}$ are common across all individuals whereas others are group-specific. Write $\beta_{i}^{0}=\left(\beta_{i(1)}^{0 \prime}, \beta_{i(2)}^{0 \prime}\right)^{\prime}$ where $\beta_{i 1}^{0}=\beta_{(1)}^{0}$ for all $i=1, \ldots, N$. Partition $x_{i t}$ conformably as $x_{i t}=\left(x_{i t(1)}^{\prime}, x_{i t(2)}^{\prime}\right)^{\prime}$. The panel structure becomes

$$
\begin{equation*}
y_{i t}=\beta_{(1)}^{0 \prime} x_{i t(1)}+\beta_{i(2)}^{0 \prime} x_{i t(2)}+\mu_{i}+u_{i t} \tag{2.23}
\end{equation*}
$$

where $\beta_{i(2)}^{0}=\alpha_{k}^{0}$ if $i \in G_{k}^{0}$ where $k=1, \ldots, K_{0}$ and $G_{1}^{0}, \ldots, G_{K_{0}}^{0}$ form a partition for $\{1,2, \ldots, N\}$. The model (2.23) is closely related to the model studied by Pesaran, Shin, and Smith (1999) in which longrun coefficients are constrained to be identical across individuals while short-run coefficients may be heterogenous. In this case, the PLS objective function becomes

$$
\begin{equation*}
Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\beta_{(1)}, \boldsymbol{\beta}_{(2)}, \boldsymbol{\alpha}\right)=Q_{1, N T}\left(\beta_{(1)}, \boldsymbol{\beta}_{(2)}\right)+\frac{\lambda_{1}}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K_{0}}\left\|\beta_{i(2)}-\alpha_{k}\right\| \tag{2.24}
\end{equation*}
$$

where $Q_{1, N T}\left(\beta_{(1)}, \boldsymbol{\beta}_{(2)}\right)=\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\beta_{(1)}^{\prime} \tilde{x}_{i t(1)}-\beta_{i(2)}^{\prime} \tilde{x}_{i t(2)}\right)^{2}, \boldsymbol{\beta}_{(2)}=\left(\beta_{1(2)}, \ldots, \beta_{N(2)}\right)$, and $\tilde{x}_{i t(r)}=x_{i t(r)}-T^{-1} \sum_{s=1}^{T} x_{i s(r)}$ for $s=1,2$. Our previous analysis can now be followed to establish uniform consistency for the classifier and the oracle property for the resulting estimators of $\beta_{(1)}^{0}$ and $\alpha_{k}^{0}$ 's.
2. Nonlinear Panel Data Models: Bester and Hansen (2013) consider estimation of nonlinear panel data models with common and group-specific parameters where the group structure is completely known, e.g., based on some external classification or geographic location. They provide conditions under which their group effects estimators of the common parameter are asymptotically unbiased. To fix ideas, consider minimizing the following objective function

$$
\begin{equation*}
Q_{1, N T}(\theta, \boldsymbol{\mu})=\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T} \varphi\left(w_{i t}, \theta, \mu_{i}\right) \tag{2.25}
\end{equation*}
$$

where $\theta$ is a finite dimensional common parameter, $\boldsymbol{\mu}=\left(\mu_{1}, \ldots, \mu_{N}\right), \varphi=-\ln f$, and $f\left(w_{i t}, \theta, \mu_{i}\right)$ is the density function of $w_{i t}$ with respect to some measure. Here the $\mu_{i}$ denote time invariant individualspecific effects that are held constant according to an observed group structure: $\mu_{i}^{0}=\alpha_{k}^{0}$ if $i \in G_{k}^{0}$ where $k=1, \ldots, K_{0}$ and $\left\{G_{1}^{0}, \ldots, G_{K_{0}}^{0}\right\}$ forms a partition for $\{1,2, \ldots, N\} .^{4}$ Interestingly, the PLS C-Lasso method can be extended to study such nonlinear panel data models straightforwardly without the need to know each individual's group membership. The PLS objective function here takes the form

$$
\begin{equation*}
Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}(\theta, \boldsymbol{\mu}, \boldsymbol{\alpha})=Q_{1, N T}(\theta, \boldsymbol{\mu})+\frac{\lambda_{1}}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K_{0}}\left\|\mu_{i}-\alpha_{k}\right\| \tag{2.26}
\end{equation*}
$$

One can readily modify our numerical algorithm to estimate both the common parameter $\theta^{0}$ and the group-specific parameters $\left\{\alpha_{k}^{0}\right\}$. The uniform consistency of the C-Lasso classifier and the oracle properties of the parametric estimates can also be established.

[^4]3. Group Patterns of Heterogeneity: Bonhomme and Manresa (2012) consider a linear panel data model with grouped patterns of heterogeneity that take the following form
\[

$$
\begin{equation*}
y_{i t}=\theta^{0 \prime} x_{i t}+\mu_{g_{i} t}+u_{i t} \tag{2.27}
\end{equation*}
$$

\]

where the group membership variables $g_{i} \in\left\{1, \ldots, K_{0}\right\}$ map individual units into groups. They propose to estimate the group membership along with the common parameter $\theta^{0}$ in the model based on some variants of the K-means algorithm and establish the asymptotic distributions for the resulting estimators. In view of the fact that $\mu_{g_{i} t}$ has a factor structure $\mu_{g_{i} t}=\lambda_{i}^{\prime} f_{t}$ where $f_{t}=\left(\mu_{1 t}, \ldots, \mu_{K_{0} t}\right)^{\prime}, \lambda_{i}=(0, \ldots 1, \ldots 0)^{\prime}$ with 1 in the $k^{\text {th }}$ position if $i \in G_{k}^{0}$ for $k=1, \ldots, K_{0}$ and zeros elsewhere, we may embed (2.27) in the more general model

$$
\begin{equation*}
y_{i t}=\theta^{0 \prime} x_{i t}+\lambda_{i}^{0 \prime} f_{t}^{0}+u_{i t}, \tag{2.28}
\end{equation*}
$$

where $\lambda_{i}^{0}=\alpha_{k}^{0}$ if $i \in G_{k}^{0}$ where $k=1, \ldots, K_{0}$ and $\left\{G_{1}^{0}, \ldots, G_{K_{0}}^{0}\right\}$ forms a partition for $\{1,2, \ldots, N\}$. In the economic growth literature, $f_{t}$ represents unobserved global shocks to the economy, and $\lambda_{i}^{0}$ the marginal effects of the shocks to country $i$ 's economic growth. It is sensible to assume that the marginal effects are identical for countries that exhibit similar features. To estimate (2.28) with the unknown group structure, we propose a two-step approach. In the first step, we follow Bai (2009) and obtain the Gaussian quasimaximum likelihood estimates $\breve{\theta}, \breve{\lambda}_{i}$, and $\breve{f}_{t}$ of $\theta^{0}, \lambda_{i}^{0}$, and $f_{t}^{0}$ under the identification restrictions that $T^{-1} \sum_{t=1}^{T} f_{t} f_{t}^{\prime}=I_{K_{0}}$ and $N^{-1} \sum_{i=1}^{N} \lambda_{i} \lambda_{i}^{\prime}$ is diagonal. In the second step, we consider the following regression

$$
\begin{equation*}
y_{i t}=\theta^{0 \prime} x_{i t}+\lambda_{i}^{0 \prime} \breve{f}_{t}+u_{i t} \tag{2.29}
\end{equation*}
$$

by imposing the unknown group structure: $\lambda_{i}^{0}=\alpha_{k}^{0}$ if $i \in G_{k}^{0}$ where $k=1, \ldots, K_{0}$. The PLS objective function is similar to that in (2.24). In this framework, we can readily show that C-Lasso yields uniform consistency for the classification and the oracle properties of the estimators of $\theta^{0}$ and $\alpha_{k}^{0}$ just as if we were able to observe the exact group structure.
4. Granger-causality, Unit Root, and Cointegration in Heterogenous Panels: The CLasso methodology can also be extended to analyze Granger-causality, unit roots, and cointegration in heterogenous panels. In Granger-causality analysis we may consider either completely homogenous or completely heterogenous relationships. The former may produce misleading conclusions if the causal or non-causal relationship is heterogeneous; the latter may yield imprecise estimates and low power in hypothesis testing. An intermediate specification is to allow the relationship to be group-specific. Similar remarks hold for panel unit root and cointegration tests - see Breitung and Pesaran (2008) for an overview on this. As usual in nonstationary settings, careful attention must be given to allow for different convergence rates for different parameters in such systems (Phillips and Moon, 1999).

The C-Lasso approach is also well suited to testing for structural change in heterogeneous panel data models, to nonparametric and semiparametric panel data models, and to models with heterogeneous parametric or nonparametric time trends (e.g., Kneip, Sickles, and Song (2012), Zhang, Su, and Phillips (2012)). We can expect C-Lasso to deliver substantial efficiency gains in some of these cases where there is only partial heterogeneity in the structure. These and other applications of the methodology will be examined in separate studies.

## 3 Penalized GMM Estimation of Panel Structure Models

This section considers penalized GMM estimation of panel structure models when some regressors are lagged dependent variables or endogenous. As before, we first assume that the number of groups is known and then consider the determination of the number of groups when that information is unknown.

### 3.1 Penalized GMM Estimation of $\alpha$ and $\boldsymbol{\beta}$

We consider the first differenced system

$$
\begin{equation*}
\Delta y_{i t}=\beta_{i}^{0 \prime} \Delta x_{i t}+\Delta u_{i t} \tag{3.1}
\end{equation*}
$$

where, e.g., $\Delta y_{i t}=y_{i t}-y_{i, t-1}$ for $t=1, \ldots, T$ and $i=1, \ldots, N$, and we assume that we have observations on $y_{i 0}$ and $x_{i 0}$. Let $z_{i t}$ be a $d \times 1$ vector of instruments for $\Delta x_{i t}$ where $d \geq p$. Define $\Delta y_{i}=\left(\Delta y_{i 1}, \ldots, \Delta y_{i T}\right)^{\prime}$, with similar definitions for $\Delta x_{i}$ and $\Delta u_{i}$.

We propose to estimate $\boldsymbol{\beta}$ and $\boldsymbol{\alpha}$ by minimizing the following penalized GMM (PGMM) criterion function ${ }^{5}$

$$
\begin{equation*}
Q_{2 N T, \lambda_{2}}^{\left(K_{0}\right)}(\boldsymbol{\beta}, \boldsymbol{\alpha})=Q_{2, N T}(\boldsymbol{\beta})+\frac{\lambda_{2}}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K_{0}}\left\|\beta_{i}-\alpha_{k}\right\| \tag{3.2}
\end{equation*}
$$

where $Q_{2, N T}(\boldsymbol{\beta})=\frac{1}{N} \sum_{i=1}^{N}\left[\frac{1}{T} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\beta_{i}^{\prime} \Delta x_{i t}\right)\right]^{\prime} W_{i N T}\left[\frac{1}{T} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\beta_{i}^{\prime} \Delta x_{i t}\right)\right], W_{i N T}$ is a $d \times d$ matrix that is positive definite asymptotically and $\lambda_{2}=\lambda_{2 N T}$ is a tuning parameter. Minimizing the above criterion function produces the PGMM estimates $\tilde{\boldsymbol{\alpha}}$ and $\tilde{\boldsymbol{\beta}}$. Let $\tilde{\beta}_{i}$ and $\tilde{\alpha}_{k}$ denote the $i^{\text {th }}$ and $k^{\text {th }}$ columns of $\tilde{\boldsymbol{\beta}}$ and $\tilde{\boldsymbol{\alpha}}$, respectively, so that $\tilde{\boldsymbol{\alpha}} \equiv\left(\tilde{\alpha}_{1}, \ldots, \tilde{\alpha}_{K_{0}}\right)$ and $\tilde{\boldsymbol{\beta}} \equiv\left(\tilde{\beta}_{1}, \ldots, \tilde{\beta}_{N}\right)$.

As before, the objective function in (3.2) is convex in $\alpha_{k}$ but not in $\boldsymbol{\beta}$. With minor modifications, the numerical algorithm described in Section 2.2 can be used to obtain the estimates $\tilde{\boldsymbol{\alpha}}$ and $\tilde{\boldsymbol{\beta}}$.

### 3.2 Preliminary Rates of Convergence for Coefficient Estimates

We first present sufficient conditions to ensure the consistency of $(\tilde{\boldsymbol{\beta}}, \tilde{\boldsymbol{\alpha}})$. Let $\tilde{Q}_{i, z \Delta x}=\frac{1}{T} \sum_{t=1}^{T} z_{i t}\left(\Delta x_{i t}\right)^{\prime}$, $\tilde{Q}_{i, z \Delta y}=\frac{1}{T} \sum_{t=1}^{T} z_{i t} \Delta y_{i t}, \bar{Q}_{i, z \Delta x}=\frac{1}{T} \sum_{t=1}^{T} \mathbb{E}\left[z_{i t}\left(\Delta x_{i t}\right)^{\prime}\right]$, and $\bar{Q}_{i, z \Delta y}=\frac{1}{T} \sum_{t=1}^{T} \mathbb{E}\left[z_{i t} \Delta y_{i t}\right]$. Let $\xi_{i t}=$ $\left(\Delta y_{i t},\left(\Delta x_{i t}\right)^{\prime}, z_{i t}^{\prime}\right)^{\prime}$. Define

$$
\rho\left(\xi_{i t}, \beta\right)=z_{i t}\left(\Delta y_{i t}-\beta^{\prime} \Delta x_{i t}\right) \text { and } \bar{\rho}_{i, T}(\beta)=\frac{1}{\sqrt{T}} \sum_{t=1}^{T}\left\{\rho\left(\xi_{i t}, \beta\right)-\mathbb{E}\left[\rho\left(\xi_{i t}, \beta\right)\right]\right\}
$$

Let $\mathcal{B}_{i}$ denote the parameter space of $\beta_{i} .{ }^{6}$ We make the following assumption.
ASSUMPTION B1. (i) $\mathbb{E}\left[\rho\left(\xi_{i t}, \beta_{i}^{0}\right)\right]=0$ for each $i=1, \ldots, N$ and $t=1, \ldots, T$.

[^5](ii) $\sup _{\beta \in \mathcal{B}_{i}} \bar{\rho}_{i, T}(\beta)=O_{P}(1)$ and $\frac{1}{N} \sum_{i=1}^{N}\left\|\bar{\rho}_{i, T}\left(\beta_{i}\right)\right\|^{2}=O_{P}(1)$ for any $\beta_{i} \in \mathcal{B}_{i}$ and $i=1, \ldots, N$.
(iii) $\tilde{Q}_{i, z \Delta x}=\bar{Q}_{i, z \Delta x}+o_{P}(1)$ for each $i=1, \ldots, N$ and $\liminf \operatorname{in}_{(N, T) \rightarrow \infty} \min _{1 \leq i \leq N} \mu_{\min }\left(\bar{Q}_{i, z \Delta x}^{\prime} \bar{Q}_{i, z \Delta x}\right)$ $=\underline{c}_{\bar{Q}}>0$.
(iv) There exist nonrandom matrices $W_{i}$ such that $\max _{1 \leq i \leq N}\left\|W_{i N T}-W_{i}\right\|=o_{P}(1)$ and $\lim \inf _{N \rightarrow \infty}$ $\min _{1 \leq i \leq N} \mu_{\min }\left(W_{i}\right)=\underline{c}_{W}>0$.
(v) $N_{k} / N \rightarrow \tau_{k} \in(0,1)$ for each $k=1, \ldots, K_{0}$ as $N \rightarrow \infty$.
(vi) $\lambda_{2} \rightarrow 0$ as $(N, T) \rightarrow \infty$.

Assumption $\mathrm{B} 1(\mathrm{i})$ specifies moment conditions to identify $\beta_{i}^{0}$. B 1 (ii) is a high level condition because we do not specify the data structure (or instruments) along with either the cross section or time series dimension. Its first part can generally be verified by applying Donsker's theorem to specific cases. For example, if there exists $\mathcal{F}_{i t}$, a $\sigma$-field, such that $\left\{\xi_{i t}, \mathcal{F}_{i t}\right\}$ is a stationary ergodic adapted mixingale with size -1 (e.g., White, 2001, pp. 124-125), and $\operatorname{Var}\left(T^{1 / 2} \omega^{\prime} \rho_{i, T}\left(\beta_{i}\right)\right) \rightarrow \omega^{\prime} \Sigma_{i} \omega \in(0, \infty)$ as $T \rightarrow \infty$ for some positive definite matrix $\Sigma_{i}$ and any $\omega \in \mathbb{R}^{d}$ with $\|\omega\|=1$, then $T^{1 / 2} \rho_{i, T}\left(\beta_{i}\right) \xrightarrow{d} N\left(0, \Sigma_{i}\right)$ and the first part of B 1 (ii) follows. In conjunction with $\mathrm{B} 1(\mathrm{i})$, B 1 (iii) provides a rank condition for the identification of $\beta_{i}^{0}$. It may also be used to establish the mean square convergence of $\tilde{\beta}_{i}$ as it implicitly requires that $\bar{Q}_{i, z \Delta x}$ is of full rank uniformly in $i$. B1(iv) is automatically satisfied if one sets $W_{i N T}=I_{d}$, the $d \times d$ identity matrix. Conditions B1(v)-(vi) parallel the earlier conditions A1(iv)-(v).

Theorem 3.1 If Assumption B1 holds, then
(i) $\tilde{\beta}_{i}-\beta_{i}^{0}=O_{P}\left(T^{-1 / 2}+\lambda_{2}\right)$ for $i=1, \ldots, N$,
(ii) $\frac{1}{N} \sum_{i=1}^{N}\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|^{2}=O_{P}\left(T^{-1}\right)$,
(iii) $\left(\tilde{\alpha}_{(1)}, \ldots, \tilde{\alpha}_{\left(K_{0}\right)}\right)-\left(\alpha_{1}^{0}, \ldots, \alpha_{K_{0}}^{0}\right)=O_{P}\left(T^{-1 / 2}\right)$,
where $\left(\tilde{\alpha}_{(1)}, \ldots, \tilde{\alpha}_{\left(K_{0}\right)}\right)$ is a suitable permutation of $\left(\tilde{\alpha}_{1}, \ldots, \tilde{\alpha}_{K_{0}}\right)$.
REMARK 7. Parts (i) and (ii) of Theorem 3.1 establish the pointwise and mean-square convergence of $\hat{\beta}_{i}$. Part (iii) indicates that the group-specific parameters $\left\{\alpha_{1}^{0}, \ldots, \alpha_{K}^{0}\right\}$ can also be estimated consistently by $\left\{\tilde{\alpha}_{1}, \ldots, \tilde{\alpha}_{K_{0}}\right\}$ subject to permutation. For notational simplicity, hereafter we simply write $\tilde{\alpha}_{k}$ for $\tilde{\alpha}_{(k)}$ as the consistent estimator of $\alpha_{k}^{0}$, and define

$$
\begin{equation*}
\tilde{G}_{k}=\left\{i \in\{1,2, \ldots, N\}: \tilde{\beta}_{i}=\tilde{\alpha}_{k}\right\} \text { for } k=1, \ldots, K_{0} \tag{3.3}
\end{equation*}
$$

### 3.3 Classification Consistency

Define the following sequences of events:

$$
\begin{equation*}
E_{k N T, i}=\left\{i \notin \tilde{G}_{k} \mid i \in G_{k}^{0}\right\} \text { and } \tilde{F}_{k N T, i}=\left\{i \notin G_{k}^{0} \mid i \in \tilde{G}_{k}\right\} \tag{3.4}
\end{equation*}
$$

where $i=1, \ldots, N$ and $k=1, \ldots, K_{0}$. Let $\tilde{E}_{k N T}=\cup_{i \in G_{k}^{0}} \tilde{E}_{k N T, i}$ and $\tilde{F}_{k N T}=\cup_{i \in \tilde{G}_{k}} \tilde{F}_{k N T, i}$. We add the following assumption.
ASSUMPTION B2. (i) $T \lambda_{2} \rightarrow \infty$ and $T \lambda_{2}^{4} \rightarrow c_{0} \in[0, \infty)$ as $(N, T) \rightarrow \infty$.
(ii) For any $c>0, N \max _{1 \leq i \leq N} P\left(\left\|T^{-1} \sum_{t=1}^{T} z_{i t} \Delta u_{i t}\right\| \geq c \sqrt{\lambda_{2}}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$.

Assumptions B2(i)-(ii) parallel A2(i)-(ii). Like the case of A2(ii), one can also verify B2(ii) under some primitive conditions on the process $\left\{z_{i t} \Delta u_{i t}, t \geq 1\right\}$. The required moment conditions are now imposed on $\left\|z_{i t} \Delta u_{i t}\right\|$. Following the remark after Assumption A2, for a large range of moment conditions on $\left\|z_{i t} \Delta u_{i t}\right\|$ and the relative rates at which $N$ and $T$ pass to infinity, it suffices to require that

$$
\begin{equation*}
\lambda_{2} \propto T^{-a} \text { for any } a \in[1 / 4,1) \tag{3.5}
\end{equation*}
$$

Uniform consistency of the classification is established in the next theorem.
Theorem 3.2 If Assumptions B1-B2 hold, then
(i) $P\left(\cup_{k=1}^{K_{0}} \tilde{E}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} P\left(\tilde{E}_{k N T}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$,
(ii) $P\left(\cup_{k=1}^{K_{0}} \tilde{F}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} P\left(\tilde{F}_{k N T}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$.

REMARK 8. Remark 2 also holds for the above theorem with obvious modifications. In particular, let $\tilde{G}_{0}$ denote the group of individuals in $\{1,2, \ldots, N\}$ that are not classified into any of the $K_{0}$ groups, i.e., $\tilde{G}_{0}=\{1,2, \ldots, N\} \backslash\left(\cup_{k=1}^{K_{0}} \tilde{G}_{k}\right)$. Define the events $\tilde{H}_{i N T}=\left\{i \in \tilde{G}_{0}\right\}$. Theorem 3.2(i) implies that $P\left(\cup_{1 \leq i \leq N} \tilde{H}_{i N T}\right) \leq \sum_{k=1}^{K_{0}} P\left(\tilde{E}_{k N T}\right) \rightarrow 0$. That is, all individuals can be classified into one of the $K_{0}$ groups w.p.a.1.

Let $\tilde{N}_{k}=\sum_{i=1}^{N} \mathbf{1}\left\{i \in \tilde{G}_{k}\right\}$. Following the proof of Corollary 2.3 , one can also prove that $\tilde{N}_{k}$ consistently estimates $N_{k}$.

Corollary 3.3 Suppose that Assumptions B1-B2 hold. Then $\tilde{N}_{k}-N_{k}=o_{P}(1)$.

### 3.4 Improved Convergence and Asymptotic Properties of Post-Lasso

To obtain an improved rate of convergence in C-Lasso estimation of $\left\{\tilde{\alpha}_{k}\right\}$ we provide more specific conditions with the following assumption.
ASSUMPTION B3. (i) For each $k=1, \ldots, K_{0}, \frac{1}{N_{k}} \sum_{i \in G_{k}^{0}}\left\|\tilde{Q}_{i, z \Delta x}-\bar{Q}_{i, z \Delta x}\right\|^{2}=o_{P}(1)$ and $W_{i N T} \xrightarrow{P}$ $W_{i}>0$ for $i \in G_{k}^{0}$.
(ii) For each $k=1, \ldots, K_{0}, \bar{A}_{k} \equiv \frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} \bar{Q}_{i, z \Delta x}^{\prime} W_{i} \bar{Q}_{i, z \Delta x} \rightarrow A_{k}>0$ as $(N, T) \rightarrow \infty$.
(iii) For each $k=1, \ldots, K_{0}, \frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \sum_{t=1}^{T} z_{i t} \Delta u_{i t}-B_{k N T} \xrightarrow{D} N\left(0, C_{k}\right)$ as $(N, T) \rightarrow$ $\infty$.

Assumptions B3(i)-(iii) can be verified under various primitive conditions. For example, B3(i) can be verified by the Markov inequality under (standard) conditions that (a) $\mathbb{E}\left\|z_{i t}\left(\Delta x_{i t}\right)^{\prime}\right\|^{2+\sigma}>0$ for some $\sigma>0$ and (b) $\left\{\left(\Delta x_{i t}, z_{i t}, \Delta u_{i t}\right), t \geq 1\right\}$ is strong mixing for each $i$ with mixing coefficients $\alpha_{i}(\tau)$ that satisfy $\frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} \sum_{\tau=1}^{\infty} \alpha_{i}(\tau)^{(2+\sigma) / \sigma}<\infty$. If, in addition, (c) $\left\{\left(\Delta x_{i t}, z_{i t}\right)\right\}$ is also stationary along the time dimension and IID along the individual dimension for all individuals within the same group $G_{k}^{0}$, and (d) $W_{i}=W$ for all $i \in G_{k}^{0}$, then B3(ii) is satisfied with $A_{k}=\left\{\mathbb{E}\left[z_{i t}\left(\Delta x_{i t}\right)^{\prime}\right]\right\}^{\prime} W \mathbb{E}\left[z_{i t}\left(\Delta x_{i t}\right)^{\prime}\right]$ for any
$i \in G_{k}^{0}$. To verify B3(iii), for simplicity we assume that $W_{i N T}=I_{d}$ and make the following decomposition

$$
\begin{align*}
& \frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \tilde{Q}_{i, z \Delta x}^{\prime} \sum_{t=1}^{T} z_{i t} \Delta u_{i t} \\
= & \frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right) \\
& +\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime}\right) z_{i t} \Delta u_{i t} \\
& +\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T}\left\{\left[\Delta x_{i s} z_{i s}^{\prime}-\mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime}\right)\right] z_{i t} \Delta u_{i t}-\mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)\right\} \\
\equiv & B_{k N T}+V_{k N T}+R_{k N T}, \text { say, } \tag{3.6}
\end{align*}
$$

where $B_{k N T}$ and $V_{k N T}$ contributes to the asymptotic bias and variance, respectively, and $R_{k N T}$ is term that is asymptotically negligible under suitable conditions. Then B3(iii) will be satisfied with $W_{i N T}=I_{d}$ if $V_{k N T}=\frac{1}{N_{k}^{1 / 2} T^{1 / 2}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \bar{Q}_{i, z \Delta x}^{\prime} z_{i t} \Delta u_{i t} \xrightarrow{d} N\left(0, C_{k}\right)$ and $R_{k N T}=o_{P}(1)$, both of which can be verified by strengthening the conditions in (a)-(c). Note that $\bar{A}_{k}^{-1} B_{k N T}$ signifies the asymptotic bias of $\tilde{\alpha}_{k}$, which may not be vanish asymptotically but can be corrected; see Appendix D.2. ${ }^{7}$

The following theorem establishes the asymptotic distribution of the C-Lasso estimator $\left\{\tilde{\alpha}_{k}\right\}$.
Theorem 3.4 Suppose that Assumptions B1-B3 hold. Then $\sqrt{N_{k} T}\left(\tilde{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{A}_{k}^{-1} B_{k N T} \xrightarrow{D} N(0$, $A_{k}^{-1} C_{k} A_{k}^{-1}$ ) for $k=1, \ldots, K_{0}$.

REMARK 9. In contrast to the PLS case, the PGMM estimators $\left\{\tilde{\alpha}_{k}\right\}$ may fail to possess the oracle property. If the group identities were known in advance, one could obtain the GMM estimate $\breve{\alpha}_{k}$ of $\alpha_{k}^{0}$ by minimizing the following objective function

$$
\begin{equation*}
\tilde{Q}_{N T}\left(\alpha_{k}\right)=\left[\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\alpha_{k}^{\prime} \Delta x_{i t}\right)\right]^{\prime} W_{N T}^{(k)}\left[\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\alpha_{k}^{\prime} \Delta x_{i t}\right)\right] \tag{3.7}
\end{equation*}
$$

where for each $k=1, \ldots, K_{0}, W_{N T}^{(k)}$ is a $d \times d$ symmetric positive definite matrix. Let $Q_{z \Delta x, N T}^{(k)}=$ $\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} z_{i t}\left(\Delta x_{i t}\right)^{\prime}$ and $Q_{z \Delta y, N T}^{(k)}=\frac{1}{N T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} z_{i t} \Delta y_{i t}$. Then $\breve{\alpha}_{k}=\left[Q_{z \Delta x, N T}^{(k) \prime} W_{N T}^{(k)} Q_{z \Delta x, N T}^{(k)}\right]^{-1}$ $Q_{z \Delta x, N T}^{(k) \prime} W_{N T}^{(k)} Q_{z \Delta y, N T}^{(k)}$. We can readily show that the asymptotic distribution of $\breve{\alpha}_{k}$ is typically different from that of $\tilde{\alpha}_{k}$ under some regularity conditions. See also the remark after Theorem 3.5 below.

[^6]When the individuals have group identities that are unknown, we can replace $G_{k}^{0}$ by its C-Lasso estimate $\tilde{G}_{k}$ in the GMM objective function (3.7) and obtain the post-Lasso GMM estimator of $\alpha_{k}^{0}$ given by

$$
\tilde{\alpha}_{\tilde{G}_{k}}=\left[\tilde{Q}_{z \Delta x}^{(k) \prime} W_{N T}^{(k)} \tilde{Q}_{z \Delta x}^{(k)}\right]^{-1} \tilde{Q}_{z \Delta x}^{(k) \prime} W_{N T}^{(k)} \tilde{Q}_{z \Delta y}^{(k)}
$$

where $\tilde{Q}_{z \Delta x}^{(k)}=\frac{1}{N_{k} T} \sum_{i \in \tilde{G}_{k}} \sum_{t=1}^{T} z_{i t}\left(\Delta x_{i t}\right)^{\prime}$ and $\tilde{Q}_{z \Delta y}^{(k)}=\frac{1}{N T} \sum_{i \in \tilde{G}_{k}} \sum_{t=1}^{T} z_{i t} \Delta y_{i t}$. To study the asymptotic normality of $\tilde{\alpha}_{\tilde{G}_{k}}$, we add the following assumption.
ASSUMPTION B4. (i) For each $k=1, \ldots, K_{0}, W_{N T}^{(k)} \xrightarrow{P} W^{(k)}>0$ as $(N, T) \rightarrow \infty$.
(ii) $Q_{z \Delta x, N T}^{(k)} \xrightarrow{P} Q_{z \Delta x}^{(k)}$ where $Q_{z \Delta x}^{(k)}$ has rank $p$.
(iii) $\frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} z_{i t} \Delta u_{i t} \xrightarrow{D} N\left(0, V_{k}\right)$.

Assumption B4 is standard in the literature on GMM estimation. The assumption can be verified under various primitive conditions that allow for both conditional heteroskedasticity and serial correlation in $\left\{z_{i t} \Delta u_{i t}\right\}$. The following theorem establishes the asymptotic normality of $\tilde{\alpha}_{\tilde{G}_{k}}$.
Theorem 3.5 Suppose that Assumptions B1-B4 hold. Then $\sqrt{N_{k} T}\left(\tilde{\alpha}_{\tilde{G}_{k}}-\alpha_{k}^{0}\right) \xrightarrow{D} N\left(0, \Omega_{k}\right)$ where $\Omega_{k}=\left[Q_{z \Delta x}^{(k) \prime} W^{(k)} Q_{z \Delta x}^{(k)}\right]^{-1} Q_{z \Delta x}^{(k) \prime} W^{(k)} V_{k} W^{(k)} Q_{z \Delta x}^{(k)}\left[Q_{z \Delta x}^{(k) \prime} W^{(k)} Q_{z \Delta x}^{(k)}\right]^{-1}$ and $k=1, \ldots, K_{0}$.

REMARK 10. As in the proof of Theorem 2.5, one can apply Theorem 3.2 and demonstrate that

$$
\sqrt{N_{k} T}\left(\tilde{\alpha}_{\tilde{G}_{k}}-\alpha_{k}^{0}\right)=\sqrt{N_{k} T}\left(\breve{\alpha}_{k}-\alpha_{k}^{0}\right)+o_{P}(1)
$$

That is, the post-Lasso GMM estimator $\tilde{\alpha}_{\tilde{G}_{k}}$ is asymptotically equivalent to the infeasible estimate $\breve{\alpha}_{k}$ which an oracle could obtain with knowledge of each individual's group identity. To obtain the most efficient estimator among the class of GMM estimators based on the moment conditions specified in Assumption B1(i), one can set $W_{N T}^{(k)}$ to be a consistent estimator of $V_{k}^{-1}$. The procedure is standard and we omit the details for brevity.
REMARK 11. If $W_{i N T}=W_{N T}^{(k)}, \bar{Q}_{i, z \Delta x}=Q_{z \Delta x}^{(k)}$ for each $i \in G_{k}^{0}$ in Assumptions B3(i)-(ii), and $B_{k N T}=0$ in Assumption B3(iii), then $A_{k}=Q_{z \Delta x}^{(k) \prime} W^{(k)} Q_{z \Delta x}^{(k)}, C_{k}=Q_{z \Delta x}^{(k) \prime} W^{(k)} \Omega_{k} W^{(k)} Q_{z \Delta x}^{(k)}$, and $\sqrt{N_{k} T}\left(\tilde{\alpha}_{k}-\alpha_{k}^{0}\right) \xrightarrow{D} N\left(0, \Omega_{k}\right)$. That is, in this special case, the C-Lasso estimator $\tilde{\alpha}_{k}$ also has the oracle property. But as remarked before, $B_{k N T}=0$ would typically require $T \gg N$, a condition that we do not usually want to impose. For this reason, we recommend the post-Lasso estimator $\tilde{\alpha}_{\tilde{G}_{k}}$ for the general case. ${ }^{8}$

### 3.5 Determination of the Number of Groups

When the true number of groups $K_{0}$ is unknown, we continue to assume that it is bounded from above by a finite integer $K_{\max }$. We consider the following PGMM criterion function

$$
\begin{equation*}
Q_{2 N T, \lambda_{2}}^{(K)}(\boldsymbol{\beta}, \boldsymbol{\alpha})=Q_{2, N T}(\boldsymbol{\beta})+\frac{\lambda_{2}}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K}\left\|\beta_{i}-\alpha_{k}\right\| \tag{3.8}
\end{equation*}
$$

[^7]where $1 \leq K \leq K_{\max }$. Minimizing the above objective function, we obtain the C-Lasso estimates $\left\{\tilde{\beta}_{i}\left(K, \lambda_{2}\right), \tilde{\alpha}_{k}\left(K, \lambda_{2}\right)\right\}$ of $\left\{\beta_{i}, \alpha_{k}\right\}$, where we make the dependence of $\tilde{\beta}_{i}$ and $\tilde{\alpha}_{k}$ on $\left(K, \lambda_{2}\right)$ explicit. As above, we classify individual $i$ into group $\tilde{G}_{k}\left(K, \lambda_{2}\right)$ if and only if $\tilde{\beta}_{i}\left(K, \lambda_{2}\right)=\tilde{\alpha}_{k}\left(K, \lambda_{2}\right)$, i.e.,
\[

$$
\begin{equation*}
\tilde{G}_{k}\left(K, \lambda_{2}\right)=\left\{i \in\{1,2, \ldots, N\}: \tilde{\beta}_{i}\left(K, \lambda_{2}\right)=\tilde{\alpha}_{k}\left(K, \lambda_{2}\right)\right\} \text { for } k=1, \ldots, K \tag{3.9}
\end{equation*}
$$

\]

Let $\tilde{G}\left(K, \lambda_{1}\right)=\left\{\tilde{G}_{1}\left(K, \lambda_{1}\right), \ldots, \tilde{G}_{K}\left(K, \lambda_{1}\right)\right\}$. Based on (3.9), we define the post-Lasso GMM estimate of $\alpha_{k}^{0}$ by

$$
\begin{equation*}
\tilde{\alpha}_{\tilde{G}_{k}\left(K, \lambda_{2}\right)}=\left[\tilde{Q}_{z \Delta x}^{(K, k) \prime} W_{N T}^{(k)} \tilde{Q}_{z \Delta x}^{(K, k)}\right]^{+} \tilde{Q}_{z \Delta x}^{(K, k) \prime} W_{N T}^{(k)} \tilde{Q}_{z \Delta y}^{(K, k)} \tag{3.10}
\end{equation*}
$$

where $\tilde{Q}_{z \Delta x}^{(K, k)}=\frac{1}{N_{k} T} \sum_{i \in \tilde{G}_{k}\left(K, \lambda_{2}\right)} \sum_{t=1}^{T} z_{i t}\left(\Delta x_{i t}\right)^{\prime}, \tilde{Q}_{z \Delta y}^{(K, k)}=\frac{1}{N_{k} T} \sum_{i \in \tilde{G}_{k}\left(K, \lambda_{2}\right)} \sum_{t=1}^{T} z_{i t} \Delta y_{i t}$, and $W_{N T}^{(k)}$ is defined as before but with $k=1,2, \ldots, K$.

Let $\tilde{\sigma}_{\tilde{G}\left(K, \lambda_{2}\right)}^{2}=\frac{1}{N T} \sum_{k=1}^{K} \sum_{i \in \tilde{G}_{k}\left(K, \lambda_{2}\right)} \sum_{t=1}^{T}\left[\Delta y_{i t}-\tilde{\alpha}_{\tilde{G}_{k}\left(K, \lambda_{1}\right)}^{\prime} \Delta x_{i t}\right]^{2}$. We propose to select $K$ to minimize the following information criterion:

$$
I C_{2}\left(K, \lambda_{2}\right)=\ln \left[\tilde{\sigma}_{\tilde{G}\left(K, \lambda_{2}\right)}^{2}\right]+\rho_{2 N T} p K
$$

where $\rho_{2 N T}$ is a tuning parameter. As before, for any $G^{(K)}=\left(G_{K, 1}, \ldots, G_{K, K}\right) \in \mathcal{G}_{K}$, define $\tilde{\sigma}_{G^{(K)}}^{2}=$ $\frac{1}{N T} \sum_{k=1}^{K} \sum_{i \in G_{K, k}} \sum_{t=1}^{T}\left[\Delta y_{i t}-\tilde{\alpha}_{G_{K, k}}^{\prime} \Delta x_{i t}\right]^{2}$, where $\tilde{\alpha}_{G_{K, k}}$ is analogously defined as $\tilde{\alpha}_{\tilde{G}_{k}\left(K, \lambda_{2}\right)}$ with $\tilde{G}_{k}\left(K, \lambda_{2}\right)$ being replaced by $G_{K, k}$.

To proceed, we add the following two assumptions.
ASSUMPTION B5. As $(N, T) \rightarrow \infty, \min _{1 \leq K<K_{0}} \inf _{G^{(K)} \in \mathcal{G}_{K}} \tilde{\sigma}_{G^{(K)}}^{2} \xrightarrow{P} \underline{\sigma}_{\Delta u}^{2}>\sigma_{\Delta u}^{2}$, where $\sigma_{\Delta u}^{2}=$ $\operatorname{plim}_{(N, T) \rightarrow \infty} \frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T}\left(\Delta u_{i t}\right)^{2}$.
ASSUMPTION B6. As $(N, T) \rightarrow \infty, \rho_{2 N T} \rightarrow 0$ and $\rho_{2 N T} N T \rightarrow \infty$.
Assumptions B5-B6 parallel earlier Assumptions A4-A5. The following theorem proves consistency of this choice of $K$ as the minimizer of $I C_{2}\left(K, \lambda_{2}\right)$ with respect to $K$.

Theorem 3.6 Suppose that Assumptions B1-B2 and B4-B6 hold. Then

$$
P\left(\inf _{K \in \mathcal{K}-\cup \mathcal{K}_{+}} I C_{2}\left(K, \lambda_{2}\right)>I C_{2}\left(K_{0}, \lambda_{2}\right)\right) \rightarrow 1 \text { as }(N, T) \rightarrow \infty
$$

REMARK 12. The remark after 2.6 also holds here after obvious modifications. To obtain a data-driven choice of the tuning parameter $\lambda_{2}$, define

$$
K\left(\lambda_{2}\right)=\arg \min _{K} I C_{2}\left(K, \lambda_{2}\right) \text { and } I C_{2}^{*}\left(\lambda_{2}\right)=I C_{2}\left(K\left(\lambda_{2}\right), \lambda_{2}\right)
$$

We can select the tuning parameter as $\hat{\lambda}_{2}=\arg \min _{\lambda_{2} \in \Lambda_{2}} I C_{2}^{*}\left(\lambda_{2}\right)$, where $\Lambda_{2}=\left\{\lambda_{2} \propto T^{-a}\right.$ for some $a \in[1 / 4,1)\}$ provided some conditions on the moments of $\left\|z_{i t} \Delta u_{i t}\right\|$ and on the relative rates at which $N$ and $T$ pass to infinity are satisfied. See the remarks after Assumptions A2 and B2.

## 4 Simulation

In this section, we evaluate the finite-sample performance of the C-Lasso and post-Lasso estimates.

### 4.1 Data Generating Processes

We consider three data generating processes (DGPs) that cover static as well as dynamic panels. All through these DGPs, the fixed effect $\mu_{i}$ and the idiosyncratic error $u_{i t}$ follow the standard normal distribution and are mutually independent all across $i$ and $t$. The observations in each DGP are drawn from three groups, with the proportion of the number of observations $N_{1}: N_{2}: N_{3}=0.3: 0.3: 0.4$. We try six combinations of the sample sizes with $N=100,200$ and $T=10,20,40$.

DGP 1 (Static panel with two exogenous regressors). The observations ( $y_{i t}, x_{i t}$ ) are generated from the panel structure model (2.1) where $x_{i t}=\left(x_{i t 1}, x_{i t 2}\right)^{\prime}$, and the two exogenous regressors

$$
\begin{aligned}
x_{i t, 1} & =0.2 \mu_{i}+e_{i t 1} \\
x_{i t, 2} & =0.2 \mu_{i}+e_{i t 2}
\end{aligned}
$$

and $e_{i t, 1}$ and $e_{i t, 2}$ are each IID $N(0,1)$ and mutually independent. The true coefficients are

$$
\left(\alpha_{1}^{0}, \alpha_{2}^{0}, \alpha_{3}^{0}\right)=\left(\binom{0.4}{1.6}, \quad\binom{1}{1}, \quad\binom{1.6}{0.4}\right)
$$

DGP 2 (Static panel with endogeneity). We maintain the panel structure model (2.1) with two regressors in $x_{i t} . x_{i t, 2} \sim N(0,1)$ is independent of the idiosyncratic shock $u_{i t}$ while $x_{i t, 1}$ is generated from the following underlying reduced-form equation

$$
x_{i t, 1}=0.2 \mu_{i}+0.5 z_{i t, 1}+0.5 z_{i t, 2}+0.5 e_{i t}
$$

where $z_{i t, 1}$ and $z_{i t, 2}$ are each IID $N(0,1)$, mutually independent, and two excluded instrumental variables independent of $u_{i t}$ and $e_{i t}$. Endogeneity arises as the reduced-form error term $e_{i t}$ and the structural-equation idiosyncratic shock $u_{i t}$ follow a bivariate normal distribution:

$$
\binom{u_{i t}}{e_{i t}} \sim N\left(\binom{0}{0},\left(\begin{array}{cc}
1 & 0.3 \\
0.3 & 1
\end{array}\right)\right) .
$$

An econometrician observes $\left(y_{i t}, x_{i t}, z_{i t}\right)$ with $x_{i t}=\left(x_{i t, 1}, x_{i t, 2}\right)^{\prime}$ and $z_{i t}=\left(z_{i t, 1}, z_{i t, 2}\right)^{\prime}$. The true coefficients are

$$
\left(\alpha_{1}^{0}, \alpha_{2}^{0}, \alpha_{3}^{0}\right)=\left(\binom{0.2}{1.8}, \quad\binom{1}{1}, \quad\binom{1.8}{0.2}\right)
$$

We set the gaps between the groups of the coefficients larger than those in DGP1 to compensate the weaker signal strength caused by instrumentation.

DGP 3 (Panel AR(1) with two exogenous regressors). The model is

$$
y_{i t}=\beta_{i 1}^{0} y_{i, t-1}+\beta_{i 2}^{0} x_{i t, 2}+\beta_{i 3}^{0} x_{i t, 3}+\mu_{i}\left(1-\beta_{i 1}^{0}\right)+u_{i t}
$$

where $x_{i t, 2}$ and $x_{i t, 3}$ are two exogenous regressors. They follow the standard normal distributions, mutually independent, and are independent of the error term. For each $i$, the initial value is
$y_{i 0}=\beta_{i 2}^{0} x_{i 0,2}+\beta_{i 3}^{0} x_{i 0,3}+\mu_{i}+u_{i 0}$ so that the $i$-th time series is strictly stationary with mean $\mu_{i}$.
The true coefficients are

$$
\left(\alpha_{1}^{0}, \alpha_{2}^{0}, \alpha_{3}^{0}\right)=\left(\left(\begin{array}{l}
0.8 \\
0.4 \\
0.4
\end{array}\right), \quad\left(\begin{array}{c}
0.6 \\
1 \\
1
\end{array}\right), \quad\left(\begin{array}{l}
0.4 \\
1.6 \\
1.6
\end{array}\right)\right)
$$

The choices of the lag term coefficients represent strong, moderate, and weak persistence, respectively. The choices of the coefficients of the exogenous regressors balance the different signal strength that stems from the dynamic structure.

### 4.2 Classification and Point Estimation

In this section, we assume that we know the number of groups, and focus on the pointwise classification error and the point estimation. We estimate the parameters in DGP 1 with PLS, in DGP 2 with PGMM, and in DGP 3 with both PLS and PGMM. The tuning parameter $\lambda_{1}$ or $\lambda_{2}$ is set to be $C_{\lambda} s_{Y}^{2} T^{-1 / 2}$ where $s_{Y}^{2}$ is the sample variance of $\tilde{y}_{i t}$ for PLS or the sample variance of $\Delta y_{i t}$ for PGMM, respectively. $C_{\lambda}$ is a sequence of geometrically increasing constants; here we try 5 values for $C_{\lambda}$, namely, $0.2,0.4,0.8$, 1.6, and 3.2. Regarding the initial values, we set $\hat{\alpha}_{k}^{(0)}=\tilde{\alpha}_{k}^{(0)}=0$ and $\left\{\hat{\beta}_{i}^{(0)}\right\}_{i=1}^{N}$ or $\left\{\tilde{\beta}_{i}^{(0)}\right\}_{i=1}^{N}$ to be the within-group estimates. ${ }^{9}$

The bias of the estimators for the dynamic model in DGP 3 is calculated via the one-sided kernel as discussed in Appendices D. 1 and D. 2 with a tuning parameter $M_{T}=\left\lceil T^{1 / 6}\right\rceil$, where $\left\lceil T^{1 / 6}\right\rceil$ denotes the smallest integer that is not smaller than $T^{1 / 6}$. DGP 3 gives a comparison of PLS and PGMM under the same DGP, but the instrumentation of PGMM costs a few time-dimensional observations. We feed into the PGMM objective function with

$$
\begin{aligned}
\Delta y_{i t} & =y_{i t}-y_{i, t-1} \\
\left(\Delta x_{i t, 1}, \Delta x_{i t, 2}, \Delta x_{i t, 3}\right) & =\left(y_{i, t-1}-y_{i, t-2}, x_{i t, 2}-x_{i, t-2,2}, x_{i t, 3}-x_{i, t-2,3}\right) \\
\left(z_{i t, 1}, z_{i t, 2}, z_{i t, 3}, z_{i t, 4}\right) & =\left(y_{i, t-2}, y_{i, t-3}, \Delta x_{i t, 2}, \Delta x_{i t, 3}\right)
\end{aligned}
$$

While many choices of instruments are valid in the dynamic panel model, we use two instruments for $\Delta y_{i, t-1}$ for over-identification. We lose three time-series observations in PGMM: one for the lagged regressor, and two for the construction of the instruments. On the other hand, we only lose one timeseries observation in PLS for the lagged regressor. We generate $T+3$ observations for each group in the simulation, which gives PLS $T+2$ effective observations and PGMM $T$ effective observations.

We run 500 replications for each scenario. Table 1 reports the classification results. As is discussed in Remark 2, we classify all observations into the group whose $\hat{\alpha}_{k}$ is the closest to $\hat{\beta}_{i}$. We summarize the pointwise classification errors by averaging over $i=1, \ldots, N$, as we have no space to report results

[^8]for each individual $i$. The values in the table are the means of the average classification errors $\bar{P}(\hat{E})=$ $\frac{1}{N} \sum_{i=1}^{N} \hat{P}\left(\hat{E}_{k N T, i}\right)$ and $\bar{P}(\hat{F})=\frac{1}{N} \sum_{i=1}^{N} \hat{P}\left(\hat{F}_{k N T, i}\right)$ where $\hat{P}$ denotes the empirical mean across the 500 replications.

In Table 1 the classification errors quickly shrink toward 0 as $T$ increases. Particularly, when $T=40$ the PLS classification errors $\bar{P}(\hat{E})$ and $\bar{P}(\hat{F})$ typically take on values $0.5-3 \%$, and PGMM classification errors are also small. The results are not very sensitive to the choice of the tuning parameter via $C_{\lambda}$. In DGP 3 where both PLS and PGMM are applied, PLS appears more accurate than PGMM. This is expected since (i) PLS utilizes more effective observations; (ii) PLS does not incur extra randomness from instrumentation; (iii) we do not have an optimal weighting scheme so we use the simple equal weighting for the PGMM, i.e., by setting $W_{i N T}=I_{d}$ throughout. We recommend PLS in the cases where both deliver classification consistency.

We now move on to the point estimation. Tables $2-5$ report the root-mean-squared error (RMSE) and the bias of the estimates of the first element $\beta_{i, 1}$ in $\beta_{i}$ in each model. ${ }^{10}$ Since each DGP has three groups of different coefficients, the outcomes of the coefficient estimation are not directly comparable across groups. Due to space limit, we weight the RMSEs and the biases by their proportions in the population. For example, $\operatorname{RMSE}\left(\hat{\beta}_{1}\right)$ is calculated as $\frac{1}{N} \sum_{k=1}^{K_{0}} N_{k} \operatorname{RMSE}\left(\hat{\alpha}_{k, 1}\right)$ with $\hat{\alpha}_{k, 1}$ being the first element in $\hat{\alpha}_{k}$, and so is the bias. For the bias corrected estimates in DGPs 2 and 3, we use the formulae detailed in Appendix D. Note that for the PGMM method, we only need to correct the biases for the C-Lasso estimates but not for the post-Lasso estimates; whereas for the PLS method, we need to correct the biases for both C-Lasso and post-Lasso estimates when $x_{i t}$ contains lagged dependent variables or endogenous regressors. In Tables $3-5$, the bias-corrected estimates are denoted as C-Lasso BC and post-Lasso BC for the C-Lasso and post-Lasso estimates, respectively.

The general pattern is clear in Tables $2-5$. First, the RMSE and bias of C-Lasso shrink towards zero when $T$ increases and $N$ remains fixed. Second, post-Lasso estimates tend to outperform the C-Lasso estimates in terms of bias biases and RMSEs. Although the RMSEs of C-Lasso estimators are relatively large, C-Lasso classifies the observations to make the refinement of the other estimators feasible. Third, Tables 3-5 suggest that bias correction is useful when $T$ is small. In particular, bias correction helps reduce the bias substantially when $T$ equals 10 and it is still effective for PGMM when $T=20$. When $T$ grows to 40 , the bias of C-Lasso is small whereas the bias correction slightly over-corrects in some instances. Post-Lasso is insusceptible to this bias when the classification works well in finite samples. Fourth, Tables 2 and 4 suggest that the finite-sample performance of the PLS post-Lasso's estimate becomes closer and closer to that of the oracle estimator as $T$ increases, which demonstrates the practical relevance of the oracle property. The RMSE of post-Lasso remains the smallest in comparison with CLasso and bias-corrected C-Lasso in PGMM where the oracle property is missing. We recommend the post-Lasso estimator for practical use.

[^9]Table 1. Results of classification

|  | $C_{\lambda}$ |  | 0.2 |  | 0.4 |  | 0.8 |  | 1.6 |  |  | 3.2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $N$ | $T$ | $\bar{P}(\hat{E})$ | $\bar{P}(\hat{F})$ | $\bar{P}(\hat{E})$ | $\bar{P}(\hat{F})$ | $\bar{P}(\hat{E})$ | $\bar{P}(\hat{F})$ | $\bar{P}(\hat{E})$ | $\bar{P}(\hat{F})$ | $\bar{P}(\hat{E})$ | $\bar{P}(\hat{F})$ |
| DGP1 | 100 | 10 | 0.1805 | 0.0901 | 0.1899 | 0.0954 | 0.2236 | 0.1115 | 0.2777 | 0.1305 | 0.4216 | 0.1897 |
| PLS | 100 | 20 | 0.0593 | 0.0289 | 0.0585 | 0.0292 | 0.0576 | 0.0290 | 0.0805 | 0.0396 | 0.1304 | 0.0598 |
|  | 100 | 40 | 0.0103 | 0.0049 | 0.0098 | 0.0046 | 0.0093 | 0.0045 | 0.0094 | 0.0048 | 0.0149 | 0.0070 |
|  | 200 | 10 | 0.1691 | 0.0848 | 0.1771 | 0.0894 | 0.2097 | 0.1054 | 0.2766 | 0.1322 | 0.3976 | 0.1746 |
|  | 200 | 20 | 0.0586 | 0.0284 | 0.0556 | 0.0275 | 0.0552 | 0.0277 | 0.0719 | 0.0362 | 0.1338 | 0.0613 |
|  | 200 | 40 | 0.0092 | 0.0044 | 0.0083 | 0.0040 | 0.0081 | 0.0039 | 0.0078 | 0.0040 | 0.0141 | 0.0066 |
| DGP2 | 100 | 10 | 0.2082 | 0.0993 | 0.2001 | 0.0974 | 0.2024 | 0.1004 | 0.2145 | 0.1076 | 0.2527 | 0.1274 |
| PGMM | 100 | 20 | 0.1027 | 0.0485 | 0.0958 | 0.0462 | 0.0888 | 0.0437 | 0.0878 | 0.0440 | 0.0996 | 0.0504 |
|  | 100 | 40 | 0.0321 | 0.0152 | 0.0307 | 0.0147 | 0.0266 | 0.0130 | 0.0230 | 0.0115 | 0.0227 | 0.0116 |
|  | 200 | 10 | 0.2037 | 0.0980 | 0.1982 | 0.0971 | 0.1968 | 0.0984 | 0.2113 | 0.1071 | 0.2482 | 0.1257 |
|  | 200 | 20 | 0.1020 | 0.0483 | 0.0942 | 0.0456 | 0.0872 | 0.0432 | 0.0841 | 0.0424 | 0.0942 | 0.0480 |
|  | 200 | 40 | 0.0332 | 0.0158 | 0.0299 | 0.0144 | 0.0266 | 0.0130 | 0.0222 | 0.0111 | 0.0212 | 0.0109 |
| DGP3 | 100 | 10 | 0.2063 | 0.1038 | 0.1839 | 0.0908 | 0.1913 | 0.0937 | 0.2305 | 0.1092 | 0.4058 | 0.1715 |
| PLS | 100 | 20 | 0.1000 | 0.0501 | 0.0826 | 0.0404 | 0.0750 | 0.0357 | 0.0800 | 0.0391 | 0.1968 | 0.0886 |
|  | 100 | 40 | 0.0277 | 0.0137 | 0.0222 | 0.0106 | 0.0183 | 0.0085 | 0.0158 | 0.0072 | 0.0373 | 0.0177 |
|  | 200 | 10 | 0.2025 | 0.1026 | 0.1714 | 0.0853 | 0.1709 | 0.0844 | 0.2079 | 0.0998 | 0.3539 | 0.1498 |
|  | 200 | 20 | 0.0983 | 0.0490 | 0.0794 | 0.0386 | 0.0703 | 0.0333 | 0.0716 | 0.0347 | 0.1451 | 0.0657 |
|  | 200 | 40 | 0.0255 | 0.0126 | 0.0209 | 0.0100 | 0.0173 | 0.0080 | 0.0151 | 0.0069 | 0.0220 | 0.0103 |
| DGP3 | 100 | 10 | 0.3173 | 0.1566 | 0.2991 | 0.1482 | 0.2924 | 0.1437 | 0.3016 | 0.1471 | 0.3379 | 0.1650 |
| PGMM | 100 | 20 | 0.1688 | 0.0833 | 0.1525 | 0.0753 | 0.1405 | 0.0683 | 0.1335 | 0.0629 | 0.1422 | 0.0665 |
|  | 100 | 40 | 0.0729 | 0.0355 | 0.059 | 0.029 | 0.0495 | 0.0239 | 0.0436 | 0.0203 | 0.0421 | 0.0189 |
|  | 200 | 10 | 0.3151 | 0.1557 | 0.2919 | 0.1449 | 0.2789 | 0.1381 | 0.2876 | 0.1415 | 0.3243 | 0.1597 |
|  | 200 | 20 | 0.1714 | 0.0847 | 0.1503 | 0.0745 | 0.1345 | 0.0655 | 0.1288 | 0.0609 | 0.1363 | 0.0638 |
|  | 200 | 40 | 0.0731 | 0.0356 | 0.0575 | 0.0284 | 0.0486 | 0.0236 | 0.0426 | 0.0199 | 0.0406 | 0.0183 |

## 5 Conclusion

In this paper we propose a novel approach to identifying and estimating latent group structures in panel data. We focus on linear panel data models where the slope parameters are heterogenous across groups but homogenous within a group and the group identity is unknown. We propose PLS and PGMM classification and estimation methods and both classification methods enjoy the desirable property of uniform consistency. The PLS estimation method also enjoys the oracle property while the PGMM estimation method typically does not. Post Lasso estimates are also studied and a BIC-type information criterion is proposed to determine the number of groups. Simulations are conducted to demonstrate the finite sample performance of our methods.

Table 2. Estimation of $\beta_{i, 1}$ in DGP 1 by PLS

|  |  | $C_{\lambda}$ | 0.2 |  | 0.4 |  |  | 0.8 |  | 1.6 |  | 3.2 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $N$ | $T$ |  | RMSE | Bias | RMSE | Bias | RMSE | Bias | RMSE | Bias | RMSE | Bias |
| 100 | 10 | C-Lasso | 0.1010 | 0.0364 | 0.1116 | 0.0364 | 0.1303 | 0.0293 | 0.1780 | -0.0150 | 0.3206 | -0.0968 |
|  |  | Post-lasso | 0.0907 | 0.0282 | 0.1035 | 0.0293 | 0.1274 | 0.0254 | 0.1788 | -0.0162 | 0.3216 | -0.0984 |
|  |  | Oracle | 0.0583 | -0.0033 | 0.0583 | -0.0033 | 0.0583 | -0.0033 | 0.0583 | -0.0033 | 0.0583 | -0.0033 |
|  |  |  |  |  |  |  |  |  |  |  |  |  |
| 100 | 20 | C-Lasso | 0.0590 | 0.0154 | 0.0560 | 0.0183 | 0.0507 | 0.0154 | 0.0690 | 0.0054 | 0.0856 | 0.0012 |
|  |  | Post-lasso | 0.0450 | 0.0066 | 0.0467 | 0.0092 | 0.0470 | 0.0090 | 0.0687 | 0.0038 | 0.0846 | 0.0012 |
|  |  | Oracle | 0.0399 | -0.0021 | 0.0399 | -0.0021 | 0.0399 | -0.0021 | 0.0399 | -0.0021 | 0.0399 | -0.0021 |
| 100 | 40 | C-Lasso | 0.0347 | 0.0096 | 0.0348 | 0.0047 | 0.0305 | 0.0053 | 0.0301 | 0.0023 | 0.0347 | 0.0011 |
|  |  | Post-lasso | 0.0292 | 0.0012 | 0.0293 | 0.0002 | 0.0291 | 0.0010 | 0.0290 | 0.0008 | 0.0337 | 0.0010 |
|  |  | Oracle | 0.0281 | -0.0010 | 0.0281 | -0.0010 | 0.0281 | -0.0010 | 0.0281 | -0.0010 | 0.0281 | -0.0010 |
| 200 | 10 | C-Lasso | 0.0767 | 0.0312 | 0.0856 | 0.0319 | 0.1017 | 0.0256 | 0.1457 | -0.0004 | 0.3127 | -0.0985 |
|  |  | Post-lasso | 0.0630 | 0.0225 | 0.0759 | 0.0237 | 0.0963 | 0.0210 | 0.1441 | -0.0009 | 0.3137 | -0.1001 |
|  |  | Oracle | 0.0410 | 0.0019 | 0.0410 | 0.0019 | 0.0410 | 0.0019 | 0.0410 | 0.0019 | 0.0410 | 0.0019 |
| 200 | 20 | C-Lasso | 0.0491 | 0.0152 | 0.0424 | 0.0151 | 0.0366 | 0.0137 | 0.0501 | 0.0102 | 0.0930 | -0.0032 |
|  |  | Post-lasso | 0.0320 | 0.0056 | 0.0327 | 0.0067 | 0.0329 | 0.0077 | 0.0473 | 0.0089 | 0.0916 | -0.0031 |
|  |  | Oracle | 0.0280 | 0.0007 | 0.0280 | 0.0007 | 0.0280 | 0.0007 | 0.0280 | 0.0007 | 0.0280 | 0.0007 |
| 200 | 40 | C-Lasso | 0.0276 | 0.0122 | 0.0259 | 0.0048 | 0.0222 | 0.0062 | 0.0210 | 0.0036 | 0.0233 | 0.0016 |
|  |  | Post-lasso | 0.0204 | 0.0023 | 0.0203 | 0.0012 | 0.0202 | 0.0018 | 0.0204 | 0.0021 | 0.0222 | 0.0016 |
|  |  | Oracle | 0.0193 | 0.0004 | 0.0193 | 0.0004 | 0.0193 | 0.0004 | 0.0193 | 0.0004 | 0.0193 | 0.0004 |

## APPENDIX

## A Proof of the Results in Section 2

Proof of Theorem 2.1. (i) Let $Q_{1 N T, i}\left(\beta_{i}\right)$ and $Q_{1 i N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\beta_{i}, \boldsymbol{\alpha}\right)$ be as defined in (2.6). Let $b_{i}=\beta_{i}-\beta_{i}^{0}$ and $\hat{b}_{i}=\hat{\beta}_{i}-\beta_{i}^{0}$. Note that

By the triangle and reverse triangle inequality,

$$
\begin{align*}
& \left|\Pi_{k=1}^{K_{0}}\left\|\hat{\beta}_{i}-\alpha_{k}\right\|-\Pi_{k=1}^{K_{0}}\left\|\beta_{i}^{0}-\alpha_{k}\right\|\right| \\
\leq & \left|\Pi_{k=1}^{K_{0}-1}\left\|\hat{\beta}_{i}-\alpha_{k}\right\|\left\{\left\|\hat{\beta}_{i}-\alpha_{K_{0}}\right\|-\left\|\beta_{i}^{0}-\alpha_{K_{0}}\right\|\right\}\right| \\
& +\left|\Pi_{k=1}^{K_{0}-2}\left\|\hat{\beta}_{i}-\alpha_{k}\right\|\left\|\beta_{i}^{0}-\alpha_{K_{0}}\right\|\left\{\left\|\hat{\beta}_{i}-\alpha_{K_{0}-1}\right\|-\left\|\beta_{i}^{0}-\alpha_{K_{0}-1}\right\|\right\}\right| \\
& +\ldots \\
& +\left|\Pi_{k=2}^{K_{0}}\left\|\beta_{i}^{0}-\alpha_{k}\right\|\left\{\left\|\hat{\beta}_{i}-\alpha_{1}\right\|-\left\|\beta_{i}^{0}-\alpha_{1}\right\|\right\}\right| \\
\leq & \hat{c}_{i N T}(\boldsymbol{\alpha})\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\| \tag{A.2}
\end{align*}
$$

Table 3. Estimation of $\beta_{i, 1}$ in DGP 2 by PGMM

| $N$ | $T$ | $C_{\lambda}$ | 0.2 |  | 0.4 |  | 0.8 |  | 1.6 |  | 3.2 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | RMSE | Bias | RMSE | Bias | RMSE | Bias | RMSE | Bias | RMSE | Bias |
| 100 | 10 | C-Lasso | 0.1906 | 0.1093 | 0.1907 | 0.1241 | 0.2018 | 0.1388 | 0.2096 | 0.1490 | 0.2220 | 0.1581 |
|  |  | Post-lasso | 0.1416 | 0.0152 | 0.1367 | 0.0251 | 0.1413 | 0.0325 | 0.1421 | 0.0381 | 0.1533 | 0.0443 |
|  |  | C-Lasso BC | 0.1570 | 0.0192 | 0.1512 | 0.0296 | 0.1558 | 0.0378 | 0.1580 | 0.0432 | 0.1706 | 0.0491 |
|  |  | Oracle | 0.0993 | -0.0001 | 0.0993 | -0.0001 | 0.0993 | -0.0001 | 0.0993 | -0.0001 | 0.0993 | -0.0001 |
| 100 | 20 | C-Lasso | 0.1179 | 0.0560 | 0.1176 | 0.0683 | 0.1182 | 0.0798 | 0.1239 | 0.0898 | 0.1321 | 0.0985 |
|  |  | Post-lasso | 0.0838 | 0.0138 | 0.0815 | 0.0181 | 0.0810 | 0.0200 | 0.0826 | 0.0211 | 0.0871 | 0.0216 |
|  |  | C-Lasso BC | 0.1221 | -0.0100 | 0.1174 | -0.0091 | 0.1163 | -0.0114 | 0.1159 | -0.0145 | 0.1211 | -0.0180 |
|  |  | Oracle | 0.0680 | -0.0004 | 0.0680 | -0.0004 | 0.0680 | -0.0004 | 0.0680 | -0.0004 | 0.068 | -0.0004 |
| 100 | 40 | C-Lasso | 0.0712 | 0.0400 | 0.0754 | 0.0422 | 0.0761 | 0.0464 | 0.0753 | 0.0504 | 0.0772 | 0.0557 |
|  |  | Post-lasso | 0.0519 | 0.0136 | 0.0522 | 0.0129 | 0.0519 | 0.0122 | 0.0516 | 0.0112 | 0.0522 | 0.0108 |
|  |  | C-Lasso BC | 0.1368 | -0.0290 | 0.1413 | -0.0337 | 0.1398 | -0.0418 | 0.1397 | -0.0508 | 0.1405 | -0.0603 |
|  |  | Oracle | 0.0492 | 0.0007 | 0.0492 | 0.0007 | 0.0492 | 0.0007 | 0.0492 | 0.0007 | 0.0492 | 0.0007 |
| 200 | 10 | C-Lasso | 0.1606 | 0.1139 | 0.1726 | 0.1285 | 0.1797 | 0.1424 | 0.1897 | 0.1525 | 0.1989 | 0.1585 |
|  |  | Post-lasso | 0.0963 | 0.0230 | 0.1034 | 0.0282 | 0.1063 | 0.0371 | 0.1117 | 0.0417 | 0.1201 | 0.0436 |
|  |  | C-Lasso BC | 0.1072 | 0.0260 | 0.1141 | 0.0314 | 0.1172 | 0.0410 | 0.1235 | 0.0459 | 0.1299 | 0.0475 |
|  |  | Oracle | 0.0687 | 0.0007 | 0.0687 | 0.0007 | 0.0687 | 0.0007 | 0.0687 | 0.0007 | 0.0687 | 0.0007 |
| 200 | 20 | C-Lasso | 0.0961 | 0.0588 | 0.1000 | 0.0708 | 0.1029 | 0.0820 | 0.1071 | 0.0902 | 0.1118 | 0.0949 |
|  |  | Post-lasso | 0.0572 | 0.0169 | 0.0581 | 0.0207 | 0.0578 | 0.0225 | 0.0582 | 0.0220 | 0.0601 | 0.0197 |
|  |  | C-Lasso BC | 0.0825 | -0.0034 | 0.0826 | -0.0035 | 0.0801 | -0.0064 | 0.0818 | -0.0114 | 0.0860 | -0.0167 |
|  |  | Oracle | 0.0501 | -0.0007 | 0.0501 | -0.0007 | 0.0501 | -0.0007 | 0.0501 | -0.0007 | 0.0501 | -0.0007 |
| 200 | 40 | C-Lasso | 0.0642 | 0.0386 | 0.0627 | 0.0411 | 0.0649 | 0.0443 | 0.0636 | 0.0486 | 0.0661 | 0.0539 |
|  |  | Post-lasso | 0.0411 | 0.0106 | 0.0377 | 0.0097 | 0.0374 | 0.0084 | 0.0370 | 0.0075 | 0.0373 | 0.0072 |
|  |  | C-Lasso BC | 0.1093 | -0.0349 | 0.1080 | -0.0413 | 0.1122 | -0.0497 | 0.1105 | -0.0588 | 0.1137 | -0.0680 |
|  |  | Oracle | 0.0346 | 0.0006 | 0.0346 | 0.0006 | 0.0346 | 0.0006 | 0.0346 | 0.0006 | 0.0346 | 0.0006 |

Table 4. Estimation of $\beta_{i, 1}$ in DGP 3 by PLS

|  |  | $C_{\lambda}$ | 0.2 |  | 0.4 |  | 0.8 |  | 1.6 |  | 3.2 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $N$ | $T$ |  | RMSE | Bias | RMSE | Bias | RMSE | Bias | RMSE | Bias | RMSE | Bias |
| 100 | 10 | C-Lasso | 0.1336 | -0.1223 | 0.1268 | -0.1147 | 0.1203 | -0.1044 | 0.1135 | -0.0878 | 0.1521 | -0.0549 |
|  |  | Post-lasso | 0.1009 | -0.0868 | 0.1043 | -0.0906 | 0.1080 | -0.0887 | 0.1082 | -0.0798 | 0.1527 | -0.0543 |
|  |  | C-Lasso BC | 0.0580 | 0.0233 | 0.0556 | 0.0223 | 0.0667 | 0.0250 | 0.0848 | 0.0365 | 0.1735 | 0.0599 |
|  |  | Post-Lasso BC | 0.0643 | 0.0384 | 0.0598 | 0.0328 | 0.0704 | 0.0321 | 0.0864 | 0.0401 | 0.1741 | 0.0602 |
|  |  | Oracle | 0.0928 | -0.0855 | 0.0928 | -0.0855 | 0.0928 | -0.0855 | 0.0928 | -0.0855 | 0.0928 | -0.0855 |
| 100 | 20 | C-Lasso | 0.0782 | -0.0702 | 0.0743 | -0.0663 | 0.0674 | -0.0598 | 0.0581 | -0.0497 | 0.0693 | -0.0255 |
|  |  | Post-lasso | 0.0538 | -0.0426 | 0.0557 | -0.0464 | 0.0563 | -0.0476 | 0.0528 | -0.0434 | 0.0693 | -0.0235 |
|  |  | C-Lasso BC | 0.0534 | 0.0464 | 0.0518 | 0.0445 | 0.0528 | 0.0458 | 0.0581 | 0.0520 | 0.0913 | 0.0730 |
|  |  | Post-Lasso BC | 0.0640 | 0.0582 | 0.0596 | 0.0536 | 0.0578 | 0.0517 | 0.0609 | 0.0550 | 0.0921 | 0.0740 |
|  |  | Oracle | 0.0527 | -0.0469 | 0.0527 | -0.0469 | 0.0527 | -0.0469 | 0.0527 | -0.0469 | 0.0527 | -0.0469 |
| 100 | 40 | C-Lasso | 0.0425 | -0.0366 | 0.0403 | -0.0345 | 0.0362 | -0.0306 | 0.0325 | -0.0268 | 0.0320 | -0.0205 |
|  |  | Post-lasso | 0.0293 | -0.0220 | 0.0301 | -0.0235 | 0.0302 | -0.0239 | 0.0299 | -0.0238 | 0.0321 | -0.0196 |
|  |  | C-Lasso BC | 0.0416 | 0.0383 | 0.0417 | 0.0381 | 0.0433 | 0.0399 | 0.0453 | 0.0423 | 0.0528 | 0.0477 |
|  |  | Post-Lasso BC | 0.0494 | 0.0466 | 0.0478 | 0.0449 | 0.0473 | 0.0444 | 0.0472 | 0.0444 | 0.0537 | 0.0483 |
|  |  | Oracle | 0.0285 | -0.0236 | 0.0285 | -0.0236 | 0.0285 | -0.0236 | 0.0285 | -0.0236 | 0.0285 | -0.0236 |
| 200 | 10 | C-Lasso | 0.1281 | -0.1227 | 0.1203 | -0.1146 | 0.1104 | -0.1035 | 0.0970 | -0.0853 | 0.1251 | -0.0510 |
|  |  | Post-lasso | 0.0931 | -0.0851 | 0.0957 | -0.0891 | 0.0939 | -0.0857 | 0.0897 | -0.0757 | 0.1257 | -0.0505 |
|  |  | C-Lasso BC | 0.0968 | 0.0899 | 0.0924 | 0.0854 | 0.0947 | 0.0864 | 0.1075 | 0.0964 | 0.1567 | 0.1196 |
|  |  | Post-Lasso BC | 0.1025 | 0.0968 | 0.0960 | 0.0898 | 0.0973 | 0.0897 | 0.1088 | 0.0983 | 0.1574 | 0.1196 |
|  |  | Oracle | 0.0898 | -0.0859 | 0.0898 | -0.0859 | 0.0898 | -0.0859 | 0.0898 | -0.0859 | 0.0898 | -0.0859 |
| 200 | 20 | C-Lasso | 0.0747 | -0.0703 | 0.0700 | -0.0661 | 0.0630 | -0.0593 | 0.0540 | -0.0501 | 0.0527 | -0.0317 |
|  |  | Post-lasso | 0.0486 | -0.0420 | 0.0513 | -0.0462 | 0.0514 | -0.0473 | 0.0482 | -0.0438 | 0.0525 | -0.0298 |
|  |  | C-Lasso BC | 0.1002 | 0.0980 | 0.0952 | 0.0930 | 0.0941 | 0.0923 | 0.0979 | 0.0963 | 0.1164 | 0.1114 |
|  |  | Post-Lasso BC | 0.1050 | 0.1030 | 0.0996 | 0.0977 | 0.0974 | 0.0957 | 0.0996 | 0.0980 | 0.1170 | 0.1119 |
|  |  | Oracle | 0.0492 | -0.0460 | 0.0492 | -0.0460 | 0.0492 | -0.0460 | 0.0492 | -0.0460 | 0.0492 | -0.0460 |
| 200 | 40 | C-Lasso | 0.0404 | -0.0371 | 0.0382 | -0.0351 | 0.0337 | -0.0308 | 0.0295 | -0.0267 | 0.0261 | -0.0223 |
|  |  | Post-lasso | 0.0255 | -0.0217 | 0.0263 | -0.0229 | 0.0267 | -0.0235 | 0.0265 | -0.0233 | 0.0255 | -0.0214 |
|  |  | C-Lasso BC | 0.0720 | 0.0710 | 0.0710 | 0.0699 | 0.0719 | 0.0708 | 0.0738 | 0.0728 | 0.0770 | 0.0759 |
|  |  | Post-Lasso BC | 0.0777 | 0.0768 | 0.0763 | 0.0754 | 0.0756 | 0.0746 | 0.0755 | 0.0746 | 0.0775 | 0.0764 |
|  |  | Oracle | 0.0261 | -0.0231 | 0.0261 | -0.0231 | 0.0261 | -0.0231 | 0.0261 | -0.0231 | 0.0261 | -0.0231 |

Table 5. Estimation of $\beta_{i, 1}$ in DGP 3 by PGMM

|  |  | $C_{\lambda}$ |  | 2 |  | . 4 |  |  |  | 6 |  | . 2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $N$ | $T$ |  | RMSE | Bias | RMSE | Bias | RMSE | Bias | RMSE | Bias | RMSE | Bias |
| 100 | 10 | C-Lasso | 0.1823 | -0.1065 | 0.1892 | -0.1241 | 0.1980 | -0.1417 | 0.2090 | -0.1627 | 0.2271 | -0.1816 |
|  |  | Post-lasso | 0.1304 | -0.0352 | 0.1231 | -0.0331 | 0.1161 | -0.0311 | 0.1137 | -0.0352 | 0.1201 | -0.0427 |
|  |  | C-Lasso BC | 0.1482 | -0.0224 | 0.1422 | -0.0250 | 0.1336 | -0.0263 | 0.1300 | -0.0355 | 0.1398 | -0.0488 |
|  |  | Oracle | 0.0664 | -0.0013 | 0.0664 | -0.0013 | 0.0664 | -0.0013 | 0.0664 | -0.0013 | 0.0664 | -0.0013 |
| 100 | 20 | C-Lasso | 0.0808 | -0.0319 | 0.0858 | -0.0478 | 0.0974 | -0.0687 | 0.1114 | -0.0888 | 0.1247 | -0.1035 |
|  |  | Post-lasso | 0.0584 | -0.001 | 0.0565 | -0.0031 | 0.0546 | -0.0068 | 0.0538 | -0.0109 | 0.0554 | -0.0138 |
|  |  | C-Lasso BC | 0.0994 | 0.0199 | 0.0987 | 0.0241 | 0.0990 | 0.0282 | 0.0987 | 0.0300 | 0.0970 | 0.0310 |
|  |  | Oracle | 0.0399 | -0.0027 | 0.0399 | -0.0027 | 0.0399 | -0.0027 | 0.0399 | -0.0027 | 0.0399 | -0.0027 |
| 100 | 40 | C-Lasso | 0.0442 | -0.0126 | 0.0447 | -0.0198 | 0.0519 | -0.0329 | 0.0646 | -0.0491 | 0.0742 | -0.0606 |
|  |  | Post-lasso | 0.0356 | 0.0025 | 0.0334 | 0.0006 | 0.0327 | -0.0018 | 0.0325 | -0.0037 | 0.0320 | -0.0046 |
|  |  | C-Lasso BC | 0.1029 | 0.0315 | 0.1031 | 0.0378 | 0.1105 | 0.0521 | 0.1238 | 0.0721 | 0.1351 | 0.0869 |
|  |  | Oracle | 0.0274 | -0.0011 | 0.0274 | -0.0011 | 0.0274 | -0.0011 | 0.0274 | -0.0011 | 0.0274 | -0.0011 |
| 200 | 10 | C-Lasso | 0.1640 | -0.1003 | 0.1676 | -0.1183 | 0.1748 | -0.1393 | 0.1883 | -0.1591 | 0.2101 | -0.1823 |
|  |  | Post-lasso | 0.1030 | -0.0271 | 0.0902 | -0.0247 | 0.0835 | -0.0269 | 0.0855 | -0.0320 | 0.0908 | -0.0412 |
|  |  | C-Lasso BC | 0.1121 | -0.0174 | 0.1016 | -0.0182 | 0.0952 | -0.0248 | 0.0985 | -0.0343 | 0.1040 | -0.0475 |
|  |  | Oracle | 0.0476 | -0.0009 | 0.0476 | -0.0009 | 0.0476 | -0.0009 | 0.0476 | -0.0009 | 0.0476 | -0.0009 |
| 200 | 20 | C-Lasso | 0.0764 | -0.0326 | 0.0800 | -0.0487 | 0.0910 | -0.0700 | 0.1056 | -0.0903 | 0.1167 | -0.1039 |
|  |  | Post-lasso | 0.0463 | -0.0021 | 0.0417 | -0.0037 | 0.0408 | -0.0075 | 0.0401 | -0.0116 | 0.0401 | -0.0143 |
|  |  | C-Lasso BC | 0.0701 | 0.0146 | 0.0679 | 0.0201 | 0.0703 | 0.0243 | 0.0707 | 0.0268 | 0.0694 | 0.0281 |
|  |  | Oracle | 0.0287 | -0.0010 | 0.0287 | -0.0010 | 0.0287 | -0.0010 | 0.0287 | -0.0010 | 0.0287 | -0.0010 |
| 200 | 40 | C-Lasso | 0.0395 | -0.0137 | 0.0395 | -0.0214 | 0.0466 | -0.0348 | 0.0591 | -0.0511 | 0.0689 | -0.0621 |
|  |  | Post-lasso | 0.0269 | 0.0011 | 0.0235 | -0.0007 | 0.0233 | -0.0028 | 0.0231 | -0.0049 | 0.0227 | -0.0055 |
|  |  | C-Lasso BC | 0.0791 | 0.0253 | 0.0751 | 0.0328 | 0.0836 | 0.0483 | 0.0982 | 0.0683 | 0.1105 | 0.0836 |
|  |  | Oracle | 0.0192 | -0.0010 | 0.0192 | -0.0010 | 0.0192 | -0.0010 | 0.0192 | -0.0010 | 0.0192 | -0.0010 |

where $\hat{c}_{i N T}(\boldsymbol{\alpha})=\Pi_{k=1}^{K_{0}-1}\left\|\hat{\beta}_{i}-\alpha_{k}\right\|+\Pi_{k=1}^{K_{0}-2}\left\|\hat{\beta}_{i}-\alpha_{k}\right\|\left\|\beta_{i}^{0}-\alpha_{K_{0}}\right\|+\ldots+\Pi_{k=2}^{K_{0}}\left\|\beta_{i}^{0}-\alpha_{k}\right\|=O_{P}(1)$. Combining (2.7), (A.1), and (A.2) yields $\underline{c}_{i, \tilde{x} \tilde{x}}\left\|\hat{b}_{i}\right\|^{2} \leq\left(\left\|2 \hat{Q}_{i, \tilde{x} \tilde{u}}\right\|+\hat{c}_{i N T}(\hat{\boldsymbol{\alpha}}) \lambda_{1}\right)\left\|\hat{b}_{i}\right\|$ where $\underline{c}_{i, \tilde{x} \tilde{x}}=$ $\mu_{\min }\left(\hat{Q}_{i, \tilde{x} \tilde{x}}\right)$. Then, by Assumptions A1(i)-(ii)

$$
\begin{equation*}
\left\|\hat{b}_{i}\right\| \leq \underline{c}_{i, \tilde{x} \tilde{x}}^{-1}\left(2\left\|\hat{Q}_{i, \tilde{x} \tilde{u}}\right\|+\hat{c}_{i N T}(\hat{\boldsymbol{\alpha}}) \lambda_{1}\right)=O_{P}\left(T^{-1 / 2}+\lambda_{1}\right) . \tag{A.3}
\end{equation*}
$$

(ii) By Minkowski's inequality and the result in (i), as $(N, T) \rightarrow \infty$,

$$
\begin{align*}
\hat{c}_{i N T}(\boldsymbol{\alpha}) \leq & \Pi_{k=1}^{K_{0}-1}\left\{\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\|+\left\|\beta_{i}^{0}-\alpha_{k}\right\|\right\}+\Pi_{k=1}^{K_{0}-2}\left\{\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\|+\left\|\beta_{i}^{0}-\alpha_{k}\right\|\right\}\left\|\beta_{i}^{0}-\alpha_{K_{0}}\right\| \\
& +\ldots+\Pi_{k=2}^{K_{0}}\left\|\beta_{i}^{0}-\alpha_{k}\right\| \\
= & \sum_{s=0}^{K_{0}-1}\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\|^{s} \Pi_{k=1}^{s} a_{k s}\left\|\beta_{i}^{0}-\alpha_{k}\right\|^{K_{0}-1-s} \\
\leq & C_{K_{0} N T}(\boldsymbol{\alpha}) \sum_{s=0}^{K_{0}-1}\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\|^{s} \leq C_{K_{0} N T}(\boldsymbol{\alpha})\left(1+2\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\|\right), \tag{A.4}
\end{align*}
$$

where $a_{k s}$ 's are finite integers and $C_{K_{0} N T}(\boldsymbol{\alpha})=\max _{1 \leq i \leq N} \max _{1 \leq s \leq k \leq K_{0}-1} \Pi_{k=1}^{s} a_{k s}\left\|\beta_{i}^{0}-\alpha_{k}\right\|^{K_{0}-1-s}$ $=\max _{1 \leq l \leq K_{0}} \max _{1 \leq s \leq k \leq K_{0}-1} \Pi_{k=1}^{s} a_{k s}\left\|\alpha_{l}^{0}-\alpha_{k}\right\|^{K_{0}-1-s}=O(1)$ as $K_{0}$ is finite. Let $\hat{C}_{K_{0}}=C_{K_{0} N T}(\hat{\boldsymbol{\alpha}})$. Combining (A.3)-(A.4) yields $\left\|\hat{b}_{i}\right\| \leq \frac{c_{i, i}^{-1} \tilde{x}}{1-2 \hat{C}_{K_{0}} \lambda_{1} c_{i, i, \tilde{x}}^{-1}}\left\{2\left\|\hat{Q}_{i, \tilde{x} \tilde{u}}\right\|+\hat{C}_{K_{0}} \lambda_{1}\right\}$. It follows that

$$
\frac{1}{N} \sum_{i=1}^{N}\left\|\hat{b}_{i}\right\|^{2} \leq\left(\frac{\underline{c}_{\tilde{x} \tilde{x}, N T}^{-1}}{1-2 \hat{C}_{K_{0}} \lambda_{1} c_{\tilde{x} \tilde{x}, N T}^{-1}}\right)^{2} \frac{1}{N} \sum_{i=1}^{N}\left[2\left\|\hat{Q}_{i, \tilde{x} u}\right\|+\hat{C}_{K_{0}} \lambda_{1}\right]^{2}=O_{P}\left(T^{-1}+\lambda_{1}^{2}\right)
$$

by Assumptions A1(ii)-(iii), where $\underline{c}_{\tilde{x} \tilde{x}, N T}=\min _{1 \leq i \leq N} \underline{c}_{i, \tilde{x} \tilde{x}}$.
We now demonstrate $\frac{1}{N} \sum_{i=1}^{N}\left\|\hat{b}_{i}\right\|^{2}=O_{P}\left(T^{-1}\right)$. Let $\beta=\beta^{0}+T^{-1 / 2} v$ where $v=\left(v_{1}, \ldots, v_{N}\right)$ is a $p \times N$ matrix. We want to show that for any given $\epsilon^{*}>0$, there exists a large constant $L=L\left(\epsilon^{*}\right)$ such that, for sufficiently large $N$ and $T$ we have

$$
\begin{equation*}
P\left\{\inf _{N^{-1} \sum_{i=1}^{N}\left\|v_{i}\right\|^{2}=L} Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\boldsymbol{\beta}^{0}+T^{-1 / 2} \mathbf{v}, \hat{\boldsymbol{\alpha}}\right)>Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\boldsymbol{\beta}^{0}, \boldsymbol{\alpha}^{0}\right)\right\} \geq 1-\epsilon^{*} . \tag{A.5}
\end{equation*}
$$

This implies that w.p.a. 1 there is a local minimum $\{\hat{\beta}, \hat{\alpha}\}$ such that $N^{-1} \sum_{i=1}^{N}\left\|\hat{b}_{i}\right\|^{2}=O_{P}\left(T^{-1}\right)$ regardless of the property of $\hat{\alpha}$. By (A.1) and the Cauchy-Schwarz inequality

$$
\begin{aligned}
& T\left[Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\boldsymbol{\beta}^{0}+T^{-1 / 2} \mathbf{v}, \hat{\boldsymbol{\alpha}}\right)-Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\boldsymbol{\beta}^{0}, \boldsymbol{\alpha}^{0}\right)\right] \\
= & \frac{1}{N} \sum_{i=1}^{N} v_{i}^{\prime} \hat{Q}_{i, \tilde{x} \tilde{x}} v_{i}-\frac{2 \sqrt{T}}{N} \sum_{i=1}^{N} v_{i}^{\prime} \hat{Q}_{i, \tilde{x} \tilde{u}}+\frac{\lambda_{1}}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\| \\
\geq & \underline{c}_{\tilde{x} \tilde{x}, N T} \frac{1}{N} \sum_{i=1}^{N}\left\|v_{i}\right\|^{2}-2\left\{\frac{1}{N} \sum_{i=1}^{N}\left\|v_{i}\right\|^{2}\right\}^{1 / 2}\left\{\frac{T}{N} \sum_{i=1}^{N}\left\|\hat{Q}_{i, \tilde{x} \tilde{u}}\right\|^{2}\right\}^{1 / 2} \\
\equiv & D_{1 N T}-D_{2 N T}, \text { say. }
\end{aligned}
$$

By Assumptions A1(ii)-(iii), $\underline{c}_{\tilde{x} \tilde{x}, N T}$ is bounded below by $\underline{c}_{\tilde{x} \tilde{x}}>0$ in large samples and $\frac{T}{N} \sum_{i=1}^{N}\left\|\hat{Q}_{i, \tilde{x} \tilde{u}}\right\|^{2}=$ $O_{P}(1)$. So $D_{1 N T}$ dominates $D_{2 N T}$ for sufficiently large $L$. That is $T\left[Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\left(\boldsymbol{\beta}^{0}+T^{-1 / 2} \mathbf{v}, \hat{\boldsymbol{\alpha}}\right)-Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}\right.$ $\left.\left(\boldsymbol{\beta}^{0}, \boldsymbol{\alpha}^{0}\right)\right]>0$ for sufficiently large $L$. Consequently, we must have $N^{-1} \sum_{i=1}^{N}\left\|\hat{b}_{i}\right\|^{2}=O_{P}\left(T^{-1}\right)$.
(iii) Let $P_{N T}(\boldsymbol{\beta}, \boldsymbol{\alpha})=\frac{1}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K_{0}}\left\|\beta_{i}-\alpha_{k}\right\|$. By (A.2) and (A.4), as $(N, T) \rightarrow \infty$,

$$
\begin{align*}
\left|P_{N T}(\hat{\boldsymbol{\beta}}, \boldsymbol{\alpha})-P_{N T}\left(\boldsymbol{\beta}^{0}, \boldsymbol{\alpha}\right)\right| & \leq C_{K_{0} N T}(\boldsymbol{\alpha}) \frac{1}{N} \sum_{i=1}^{N}\left\|\hat{b}_{i}\right\|+2 C_{K_{0} N T}(\boldsymbol{\alpha}) \frac{1}{N} \sum_{i=1}^{N}\left\|\hat{b}_{i}\right\|^{2} \\
& \leq C_{K_{0} N T}(\boldsymbol{\alpha})\left\{\frac{1}{N} \sum_{i=1}^{N}\left\|\hat{b}_{i}\right\|^{2}\right\}^{1 / 2}+O_{P}\left(T^{-1}\right)=O_{P}\left(T^{-1 / 2}\right) \tag{A.6}
\end{align*}
$$

By (2.9), (A.6), and the fact that $P_{N T}\left(\boldsymbol{\beta}^{0}, \boldsymbol{\alpha}^{0}\right)=0$, we have

$$
\begin{align*}
0 & \geq P_{N T}(\hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\alpha}})-P_{N T}\left(\hat{\boldsymbol{\beta}}, \boldsymbol{\alpha}^{0}\right)=P_{N T}\left(\boldsymbol{\beta}^{0}, \hat{\boldsymbol{\alpha}}\right)-P_{N T}\left(\boldsymbol{\beta}^{0}, \boldsymbol{\alpha}^{0}\right)+O_{P}\left(T^{-1 / 2}\right) \\
& =\frac{1}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K_{0}}\left\|\beta_{i}^{0}-\hat{\alpha}_{k}\right\|+O_{P}\left(T^{-1 / 2}\right) \\
& =\frac{N_{1}}{N} \Pi_{k=1}^{K_{0}}\left\|\hat{\alpha}_{k}-\alpha_{1}^{0}\right\|+\frac{N_{2}}{N} \Pi_{k=1}^{K_{0}}\left\|\hat{\alpha}_{k}-\alpha_{2}^{0}\right\|+\ldots+\frac{N_{K_{0}}}{N} \Pi_{k=1}^{K_{0}}\left\|\hat{\alpha}_{k}-\alpha_{K_{0}}^{0}\right\|+O_{P}\left(T^{-1 / 2}\right) . \tag{A.7}
\end{align*}
$$

By Assumption A1 $(i v), N_{k} / N \rightarrow \tau_{k} \in(0,1)$ for each $k=1, \ldots, K_{0}$. So (A.7) implies that $\Pi_{k=1}^{K_{0}}\left\|\hat{\alpha}_{k}-\alpha_{l}^{0}\right\|=$ $O_{P}\left(T^{-1 / 2}\right)$ for $l=1, \ldots, K_{0}$. It follows that $\left(\hat{\alpha}_{(1)}, \ldots, \hat{\alpha}_{\left(K_{0}\right)}\right)-\left(\alpha_{1}^{0}, \ldots, \alpha_{K_{0}}^{0}\right)=O_{P}\left(T^{-1 / 2}\right)$.

Proof of Theorem 2.2. (i) Fix $k \in\left\{1, \ldots, K_{0}\right\}$. By the consistency of $\hat{\alpha}_{k}$ and $\hat{\beta}_{i}$, we have $\hat{\beta}_{i}-\hat{\alpha}_{l} \xrightarrow{P}$ $\alpha_{k}^{0}-\alpha_{l}^{0} \neq 0$ for all $i \in G_{k}^{0}$ and $l \neq k$. It follows that w.p.a. $\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\| \neq 0$ for all $i \in G_{k}^{0}$ and $l \neq k$. Now, suppose that $\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\| \neq 0$ for some $i \in G_{k}^{0}$. Then the first order condition (with respect to $\beta_{i}$ ) for the minimization problem in (2.4) implies that

$$
\begin{align*}
\mathbf{0}_{p \times 1}= & \frac{-2}{\sqrt{T}} \sum_{t=1}^{T} \tilde{x}_{i t}\left(\tilde{y}_{i t}-\tilde{x}_{i t}^{\prime} \hat{\beta}_{i}\right)+\sqrt{T} \lambda_{1} \sum_{j=1}^{K_{0}} \frac{\hat{\beta}_{i}-\hat{\alpha}_{j}}{\left\|\hat{\beta}_{i}-\hat{\alpha}_{j}\right\|} \Pi_{l=1, l \neq j}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\| \\
= & \frac{-2}{\sqrt{T}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}+\left(2 \hat{Q}_{i, \tilde{x} \tilde{x}}+\frac{\lambda_{1} \hat{c}_{k i}}{\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\|} I_{p}\right) \sqrt{T}\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right) \\
& +2 \hat{Q}_{i, \tilde{x} \tilde{x}} \sqrt{T}\left(\hat{\alpha}_{k}-\beta_{i}^{0}\right)+\sqrt{T} \lambda_{1} \sum_{j=1, j \neq k}^{K_{0}} \frac{\hat{\beta}_{i}-\hat{\alpha}_{j}}{\left\|\hat{\beta}_{i}-\hat{\alpha}_{j}\right\|} \Pi_{l=1, l \neq j}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\| \\
\equiv & -\hat{B}_{i 1}+\hat{B}_{i 2}+\hat{B}_{i 3}+\sum_{j=1, j \neq k}^{K_{0}} \hat{B}_{i 4, j}, \text { say, } \tag{A.8}
\end{align*}
$$

where $\hat{c}_{k i}=\Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\| \xrightarrow{P} c_{k}^{0} \equiv \Pi_{l=1, l \neq k}^{K_{0}}\left\|\alpha_{k}^{0}-\alpha_{l}^{0}\right\|>0$ for $i \in G_{k}^{0}$ by Theorem 2.1.
Clearly $\hat{B}_{i 1}=O_{P}(1)$ by Assumption A1(i) and $\hat{B}_{i 3}=O_{P}(1)$ by Theorem 2.1(iii) as $i \in G_{k}^{0}$. One can also show that $\hat{B}_{i 4, j}=\sqrt{T} \lambda_{1} O_{P}\left(T^{-1 / 2}+\lambda_{1}\right)=O_{P}(1)$ for each $i$ and $j$ by Theorems 2.1(i) and (iii) and Assumption A2(i). Let $\hat{R}_{i}=\hat{B}_{i 3}+\sum_{j=1, j \neq k}^{K_{0}} \hat{B}_{i 4, j}$. Noting that $\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{B}_{i 2} \geq 2 \underline{c}_{i, \tilde{x} \tilde{x}} \sqrt{T}\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\|^{2}+$
$\sqrt{T} \lambda_{1} \hat{c}_{k i},\left|\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{R}_{i}\right|=O_{P}\left(\lambda_{1}\right)$, we have $\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{B}_{i 2}-\left|\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{R}_{i}\right| \geq\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{B}_{i 2} / 2$ as $(N, T) \rightarrow \infty$. It follows that for all $i \in G_{k}^{0}$

$$
\begin{aligned}
P\left(\hat{E}_{k N T, i}\right) & =P\left(i \notin \hat{G}_{k} \mid i \in G_{k}^{0}\right)=P\left(\hat{B}_{i 1}=\hat{B}_{i 2}+\hat{R}_{i}\right) \\
& \leq P\left(\| \hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{B}_{i 1}\left|\geq\left|\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{B}_{i 2}+\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{R}_{i}\right|\right) \\
& \leq P\left(\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\|\left\|\hat{B}_{i 1}\right\| \geq\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{B}_{i 2}-\left|\left(\hat{\beta}_{i}-\hat{\alpha}_{k}\right)^{\prime} \hat{R}_{i}\right|\right) \\
& \leq P\left(\left\|\hat{B}_{i 1}\right\| \geq \underline{c}_{i, \tilde{x} \tilde{x}} \sqrt{T}\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\|+\frac{\sqrt{T} \lambda_{1} \hat{c}_{k i}}{2\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\|}\right) \\
& \leq P\left(\left\|\hat{B}_{i 1}\right\| \geq \sqrt{2 \underline{c}_{i, \tilde{x} \tilde{x}} \hat{c}_{k i} T \lambda_{1}}\right) \rightarrow 0 \text { as }(N, T) \rightarrow \infty
\end{aligned}
$$

where the second and fourth inequalities follow from the Cauchy-Schwarz and triangle inequalities, and Cauchy-Schwarz inequality, respectively, and the last convergence result follows from Assumptions A1(ii) and A2(i) and the fact that $\hat{c}_{k i} \xrightarrow{P} c_{k}^{0}$ for $i \in G_{k}^{0}$. Consequently, we may conclude that w.p.a. 1 the differences $\hat{\beta}_{i}-\hat{\alpha}_{k}$ must reach the point where $\left\|\beta_{i}-\alpha_{k}\right\|$ is not differentiable with respect to $\beta_{i}$ for any $i \in G_{k}^{0}$. That is $P\left(\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\|=0 \mid i \in G_{k}^{0}\right) \rightarrow 1$ as $(N, T) \rightarrow \infty$.

For uniform consistency, observe that $P\left(\cup_{k=1}^{K_{0}} \hat{E}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} P\left(\hat{E}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(\hat{E}_{k N T, i}\right)$ and

$$
\begin{align*}
\sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(\hat{E}_{k N T, i}\right) & \leq \sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(\left\|\hat{B}_{i 1}\right\| \geq \sqrt{2 \underline{c}_{i, \tilde{x} \tilde{x}} \hat{c}_{k} T \lambda_{1}}\right) \\
& \leq N \max _{1 \leq i \leq N} P\left(\left\|\frac{1}{T} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}\right\| \geq \sqrt{\frac{\underline{c}_{i, \tilde{x} \tilde{x}} \hat{c}_{k i} \lambda_{1}}{2}}\right) \\
& \rightarrow 0 \text { as }(N, T) \rightarrow \infty \text { by Assumption A2(ii). } \tag{A.9}
\end{align*}
$$

This completes the proof of (i).
(ii) By pretending each individual's membership is random, we have $P\left(i \in G_{k}^{0}\right)=N_{k} / N \rightarrow \tau_{k} \in(0,1)$ for $k=1, \ldots, K_{0}$ and can interpret previous results as conditional on the group membership assignment. By Bayes theorem,

$$
\begin{align*}
P\left(\hat{F}_{k N T, i}\right) & =1-P\left(i \in G_{k}^{0} \mid i \in \hat{G}_{k}\right) \\
& =\frac{\sum_{l=1, l \neq k}^{K_{0}} P\left(i \in \hat{G}_{k} \mid i \in G_{l}^{0}\right) P\left(i \in G_{l}^{0}\right)}{P\left(i \in \hat{G}_{k} \mid i \in G_{k}^{0}\right) P\left(i \in G_{k}^{0}\right)+\sum_{l=1, l \neq k}^{K_{0}} P\left(i \in \hat{G}_{k} \mid i \in G_{l}^{0}\right) P\left(i \in G_{l}^{0}\right)} \tag{A.10}
\end{align*}
$$

For the numerator, we have by (A.9)

$$
\sum_{l=1, l \neq k}^{K_{0}} \sum_{i \in \hat{G}_{k}} P\left(i \in \hat{G}_{k} \mid i \in G_{l}^{0}\right) P\left(i \in G_{l}^{0}\right) \leq\left(K_{0}-1\right) \sum_{l=1}^{K_{0}} \sum_{i \in G_{l}^{0}} P\left(i \notin \hat{G}_{l} \mid i \in G_{l}^{0}\right)=o(1) .
$$

In addition, noting that $P\left(i \in \hat{G}_{k} \mid i \in G_{k}^{0}\right)=1-P\left(i \notin \hat{G}_{k} \mid i \in G_{k}^{0}\right)=1-o(1)$ uniformly in $i$ and $k$ by (i), we have that $P\left(i \in \hat{G}_{k} \mid i \in G_{k}^{0}\right) P\left(i \in G_{k}^{0}\right)+\sum_{l=1, l \neq k}^{K_{0}} P\left(i \in \hat{G}_{k} \mid i \in G_{l}^{0}\right) P\left(i \in G_{l}^{0}\right) \geq P\left(i \in G_{k}^{0}\right) / 2$ w.p.a.1. It follows that

$$
\begin{aligned}
P\left(\cup_{k=1}^{K_{0}} \hat{F}_{k N T}\right) & \leq \sum_{k=1}^{K_{0}} P\left(\hat{F}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} \sum_{i \in \hat{G}_{k}} P\left(\hat{F}_{k N T, i}\right) \\
& \leq \frac{\sum_{l=1, l \neq k}^{K_{0}} \sum_{i \in \hat{G}_{k}} P\left(i \in \hat{G}_{k} \mid i \in G_{l}^{0}\right) P\left(i \in G_{l}^{0}\right)}{\min _{1 \leq i \leq N} \min _{1 \leq k \leq K_{0}} P\left(i \in G_{k}^{0}\right) / 2} \\
& =\frac{o(1)}{\min _{1 \leq k \leq K_{0}} \tau_{k} / 2}=o(1) .
\end{aligned}
$$

Proof of Corollary 2.3. Noting that $\hat{N}_{k}=\sum_{i=1}^{N} 1\left\{i \in \hat{G}_{k}\right\}, N_{k}=\sum_{i=1}^{N} 1\left\{i \in G_{k}^{0}\right\}$, and $1\left\{i \in \hat{G}_{k}\right\}-1\{i \in$ $\left.G_{k}^{0}\right\}=1\left\{i \in \hat{G}_{k} \backslash G_{k}^{0}\right\}-1\left\{i \in G_{k}^{0} \backslash \hat{G}_{k}\right\}$, we have $\hat{N}_{k}-N_{k}=\sum_{i=1}^{N}\left[\mathbf{1}\left\{i \in \hat{G}_{k} \backslash G_{k}^{0}\right\}-\mathbf{1}\left\{i \in G_{k}^{0} \backslash \hat{G}_{k}\right\}\right]$. Then by the implication rule and Markov inequality, for any $\epsilon>0$,

$$
\begin{aligned}
P\left(\left|\hat{N}_{k}-N_{k}\right| \geq 2 \epsilon\right) & \leq P\left(\sum_{i=1}^{N} \mathbf{1}\left\{i \in \hat{G}_{k} \backslash G_{k}^{0}\right\} \geq \epsilon\right)+P\left(\sum_{i=1}^{N} \mathbf{1}\left\{i \in G_{k}^{0} \backslash \hat{G}_{k}\right\} \geq \epsilon\right) \\
& =\frac{1}{\epsilon} \sum_{i=1}^{N} P\left(\hat{F}_{k N T, i}\right)+\frac{1}{\epsilon} \sum_{i=1}^{N} P\left(\hat{E}_{k N T, i}\right)
\end{aligned}
$$

By (A.9), $\sum_{i=1}^{N} P\left(\hat{E}_{k N T, i}\right)=\sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(\hat{E}_{k N T, i}\right)=o(1)$. By the proof of Theorem 2.2(i), $\sum_{i=1}^{N} P\left(\hat{F}_{k N T, i}\right)=\sum_{k=1}^{K_{0}} \sum_{i \in \hat{G}_{k}} P\left(\hat{F}_{k N T, i}\right)=o(1)$. Consequently, $P\left(\left|\hat{N}_{k}-N_{k}\right| \geq 2 \epsilon\right)=o(1)$ and the conclusion follows.

Proof of Theorem 2.4. To study the oracle property of the Lasso estimator, we utilize conditions from subdifferential calculus (e.g., Bersekas (1995, Appendix B.5)). In particular, necessary and sufficient conditions for $\left\{\hat{\beta}_{i}\right\}$ and $\left\{\hat{\alpha}_{k}\right\}$ to minimize the objective function in (2.4) is that for each $i=1, \ldots, N$ (resp. $\left.k=1, \ldots, K_{0}\right), 0_{p \times 1}$ belongs to the subdifferential of $Q_{1 N T, \lambda_{1}}^{\left(K_{0}\right)}(\boldsymbol{\beta}, \boldsymbol{\alpha})$ with respect to $\beta_{i}$ (resp. $\alpha_{k}$ ) evaluated at $\left\{\hat{\beta}_{i}\right\}$ and $\left\{\hat{\alpha}_{k}\right\}$. That is, for each $i=1, \ldots, N$ and $k=1, \ldots, K_{0}$, we have

$$
\begin{align*}
& \mathbf{0}_{p \times 1}=\frac{-2}{N T} \sum_{t=1}^{T} \tilde{x}_{i t}\left(\tilde{y}_{i t}-\hat{\beta}_{i}^{\prime} \tilde{x}_{i t}\right)+\frac{\lambda_{1}}{N} \sum_{j=1}^{K_{0}} \hat{e}_{i j} \Pi_{l=1, l \neq j}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\|, \text { and }  \tag{A.11}\\
& \mathbf{0}_{p \times 1}=\frac{\lambda_{1}}{N} \sum_{i=1}^{N} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\| \tag{A.12}
\end{align*}
$$

where $\hat{e}_{i j}=\frac{\hat{\beta}_{i}-\hat{\alpha}_{j}}{\left\|\hat{\beta}_{i}-\hat{\alpha}_{j}\right\|}$ if $\left\|\hat{\beta}_{i}-\hat{\alpha}_{j}\right\| \neq 0$ and $\left\|\hat{e}_{i j}\right\| \leq 1$ if $\left\|\hat{\beta}_{i}-\hat{\alpha}_{j}\right\|=0$. Fix $k \in\left\{1, \ldots, K_{0}\right\}$. Observe that (a) $\left\|\hat{\beta}_{i}-\hat{\alpha}_{k}\right\|=0$ for any $i \in \hat{G}_{k}$ by the definition of $\hat{G}_{k}$, and $(b) \hat{\beta}_{i}-\hat{\alpha}_{l} \xrightarrow{P} \alpha_{k}^{0}-\alpha_{l}^{0} \neq 0$ for any $i \in \hat{G}_{k}$ and $l \neq k$. It follows that $\left\|\hat{e}_{i k}\right\| \leq 1$ for any $i \in \hat{G}_{k}$ and $\hat{e}_{i j}=\frac{\hat{\beta}_{i}-\hat{\alpha}_{j}}{\left\|\hat{\beta}_{i}-\hat{\alpha}_{j}\right\|}=\frac{\hat{\alpha}_{k}-\hat{\alpha}_{j}}{\left\|\hat{\alpha}_{k}-\hat{\alpha}_{j}\right\|}$ w.p.a. 1 for any $i \in \hat{G}_{k}$ and $j \neq k$. This further implies that w.p.a. 1

$$
\sum_{i \in \hat{G}_{k}} \sum_{j=1, j \neq k}^{K_{0}} \hat{e}_{i j} \Pi_{l=1, l \neq j}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\|=\sum_{i \in \hat{G}_{k}} \sum_{j=1, j \neq k}^{K_{0}} \frac{\hat{\alpha}_{k}-\hat{\alpha}_{j}}{\left\|\hat{\alpha}_{k}-\hat{\alpha}_{j}\right\|} \Pi_{l=1, l \neq j}^{K_{0}}\left\|\hat{\alpha}_{k}-\hat{\alpha}_{l}\right\|=0
$$

and

$$
\begin{aligned}
\sum_{i=1}^{N} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\|= & \sum_{i \in \hat{G}_{k}} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\alpha}_{k}-\hat{\alpha}_{l}\right\|+\sum_{i \in \hat{G}_{0}} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\| \\
& +\sum_{j=1, j \neq k}^{K_{0}} \sum_{i \in \hat{G}_{j}} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\alpha}_{j}-\hat{\alpha}_{l}\right\| \\
= & \sum_{i \in \hat{G}_{k}} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\alpha}_{k}-\hat{\alpha}_{l}\right\|+\sum_{i \in \hat{G}_{0}} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\|=0 .
\end{aligned}
$$

Then by (A.11) we have $\frac{2}{N T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t}\left(\tilde{y}_{i t}-\hat{\alpha}_{k}^{\prime} \tilde{x}_{i t}\right)+\frac{\lambda_{1}}{N} \sum_{i \in \hat{G}_{0}} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\|=0_{p \times 1}$. It follows that

$$
\begin{aligned}
\hat{\alpha}_{k}= & \left(\frac{1}{N T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{-1} \frac{1}{N T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{y}_{i t} \\
& +\left(\frac{1}{N T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{-1} \frac{\lambda_{1}}{2 N} \sum_{i \in \hat{G}_{0}} \hat{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\hat{\beta}_{i}-\hat{\alpha}_{l}\right\| \equiv \hat{\alpha}_{\hat{G}_{k}}+\hat{\mathcal{R}}_{k}, \text { say. }
\end{aligned}
$$

Noting that for any $\epsilon>0$

$$
P\left(\sqrt{N T}\left\|\hat{\mathcal{R}}_{k}\right\| \geq \epsilon\right) \leq \sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(i \in \hat{G}_{0} \mid i \in G_{k}^{0}\right) \leq \sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(i \notin \hat{G}_{k} \mid i \in G_{k}^{0}\right)=o(1) \text { by (A.9), }
$$

we have $\left\|\hat{\mathcal{R}}_{k}\right\|=o_{P}\left((N T)^{-1 / 2}\right)$. Then the limit distribution result follows from Theorem 2.5 below.
Proof of Theorem 2.5. Noting that $\tilde{y}_{i t}=\tilde{x}_{i t}^{\prime} \alpha_{k}^{0}+\tilde{x}_{i t}^{\prime}\left(\beta_{i}^{0}-\alpha_{k}^{0}\right)+\tilde{u}_{i t}$, we have

$$
\begin{aligned}
\sqrt{N_{k} T}\left(\hat{\alpha}_{\hat{G}_{k}}-\alpha_{k}^{0}\right)= & \left(\frac{1}{N_{k} T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{-1} \frac{1}{\sqrt{N_{k} T}} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t} \\
& +\left(\frac{1}{N_{k} T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\right)^{-1} \frac{1}{\sqrt{N_{k} T}} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\left(\beta_{i}^{0}-\alpha_{k}^{0}\right) .
\end{aligned}
$$

By Assumption A3 and Slutsky theorem, it suffices to prove the theorem by showing that (i) $S_{k N T, 1} \equiv$ $\frac{1}{N_{k} T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}=\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}+o_{P}(1)$, (ii) $S_{k N T, 2} \equiv \frac{1}{\sqrt{N_{k} T}} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}=$ $\frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}+o_{P}(1)$, (iii) $S_{k N T, 3} \equiv \frac{1}{\sqrt{N_{k} T}} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}\left(\beta_{i}^{0}-\alpha_{k}^{0}\right)=o_{P}$ (1), and (iv) $S_{k N T, 4} \equiv\left(S_{k N T, 1}^{-1}-\bar{\Phi}_{k}^{-1}\right) B_{K N T} \equiv o_{P}(1)$.

Using the fact that $1\left\{i \in \hat{G}_{k}\right\}=1\left\{i \in G_{k}^{0}\right\}+1\left\{i \in \hat{G}_{k} \backslash G_{k}^{0}\right\}-1\left\{i \in G_{k}^{0} \backslash \hat{G}_{k}\right\}$, we have
$S_{k N T, 1}-\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}=\frac{1}{N_{k} T} \sum_{i \in \hat{G}_{k} \backslash G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}-\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0} \backslash \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime} \equiv S_{k N T, 11}-S_{k N T, 12}$, say.
Let $\epsilon>0$. By Theorem 2.2, $P\left(\left\|S_{k N T, 11}\right\| \geq \epsilon\right) \leq P\left(\hat{F}_{k N T}\right) \rightarrow 0$, and $P\left(\left\|S_{k N T, 12}\right\| \geq \epsilon\right) \leq P\left(\hat{E}_{k N T}\right) \rightarrow 0$. Then (i) follows. Analogously, writing $S_{k N T, 2}-\frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}=\frac{1}{\sqrt{N_{k} T}} \sum_{i \in \hat{G}_{k} \backslash G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}$
$-\frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0} \backslash \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t} \equiv S_{k N T, 21}-S_{k N T, 22}$, we have $P\left(\left\|S_{k N T, 21}\right\| \geq \epsilon\right) \leq P\left(\hat{F}_{k N T}\right) \rightarrow 0$ and $P\left(\left\|S_{k N T, 22}\right\| \geq \epsilon\right) \leq P\left(\hat{E}_{k N T}\right) \rightarrow 0$. Then (ii) follows. Noting that $\beta_{i}^{0}-\alpha_{k}^{0}=0$ if $i \in G_{k}^{0}, P\left(\left\|S_{k N T, 3}\right\| \geq \epsilon\right) \leq$ $P\left(\hat{E}_{k N T}\right)+P\left(\hat{F}_{k N T}\right) \rightarrow 0+0=0$. Lastly, $P\left(\left\|S_{k N T, 4}\right\| \geq \epsilon\right) \leq P\left(\hat{E}_{k N T}\right)+P\left(\hat{F}_{k N T}\right) \rightarrow 0+0=0$.

Proof of Theorem 2.6. Using Theorems 2.2 and 2.5 and Assumption A5, we can readily show that

$$
\begin{aligned}
I C_{1}\left(K_{0}, \lambda_{1}\right) & =\ln \left[\hat{\sigma}_{\hat{G}\left(K_{0}, \lambda_{1}\right)}^{2}\right]+\rho_{N T} p K_{0} \\
& =\ln \left[\frac{1}{N T} \sum_{k=1}^{K_{0}} \sum_{i \in \hat{G}_{k}\left(K_{0}, \lambda_{1}\right)} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\tilde{\alpha}_{\hat{G}_{k}\left(K_{0}, \lambda_{1}\right)}^{\prime} \tilde{x}_{i t}\right)^{2}\right]+o(1) \xrightarrow{P} \ln \left(\sigma_{0}^{2}\right) .
\end{aligned}
$$

We consider the cases of under- and over-fitted models separately.
Case 1: Under-fitted model. In this case, we have $K<K_{0}$. Noting that

$$
\begin{aligned}
\hat{\sigma}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}^{2} & =\frac{1}{N T} \sum_{k=1}^{K} \sum_{i \in \hat{G}_{k}\left(K, \lambda_{1}\right)} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\tilde{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}^{\prime} \tilde{x}_{i t}\right)^{2} \\
& \geq \min _{1 \leq K<K_{0}} \inf _{G^{(K)} \in \mathcal{G}_{K}} \frac{1}{N T} \sum_{k=1}^{K} \sum_{i \in G_{K, k}} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\tilde{\alpha}_{G_{K, k}}^{\prime} \tilde{x}_{i t}\right)^{2}=\min _{1 \leq K<K_{0}} \inf _{G^{(K)} \in \mathcal{G}_{K}} \hat{\sigma}_{G^{(K)}}^{2},
\end{aligned}
$$

we have by Assumptions A4-A5 and the Slutsky Lemma

$$
\min _{1 \leq K<K_{0}} I C_{1}\left(K, \lambda_{1}\right) \geq \min _{1 \leq K<K_{0}} \inf _{G^{(K)} \in \mathcal{G}_{K}} \ln \left(\hat{\sigma}_{G^{(K)}}^{2}\right)+\rho_{N T} p K \xrightarrow{P} \ln \left(\underline{\sigma}^{2}\right)>\ln \left(\sigma_{0}^{2}\right) .
$$

It follows that $P\left(\min _{K \in \Omega_{-}} I C_{1}\left(K, \lambda_{1}\right)>I C_{1}\left(K_{0}, \lambda_{1}\right)\right) \rightarrow 1$.
Case 2: Over-fitted model. Let $K \in \Omega_{+}$. By Lemma A. 1 below and the fact that $\delta_{N T}^{2} \rho_{N T} \rightarrow \infty$ under Assumption A5, we have

$$
\begin{aligned}
& P\left(\min _{K \in \Omega_{+}} I C_{1}\left(K, \lambda_{1}\right)>I C_{1}\left(K_{0}, \lambda_{1}\right)\right) \\
= & \left.P\left(\min _{K \in \Omega_{+}}\left[\delta_{N T}^{2} \ln \left(\hat{\sigma}_{\hat{G}\left(K, \lambda_{1}\right)}^{2}\right) \hat{\sigma}_{\hat{G}\left(K_{0}, \lambda_{1}\right)}^{2}\right)+\delta_{N T}^{2} \rho_{N T}\left(K-K_{0}\right)\right]>0\right) \\
= & P\left(\min _{K \in \Omega_{+}} \delta_{N T}^{2}\left(\hat{\sigma}_{\hat{G}\left(K, \lambda_{1}\right)}^{2}-\hat{\sigma}_{\hat{G}\left(K_{0}, \lambda_{1}\right)}^{2}\right) / \hat{\sigma}_{\hat{G}\left(K_{0}, \lambda_{1}\right)}^{2}+\delta_{N T}^{2} \rho_{N T}\left(K-K_{0}\right)+o_{P}(1)>0\right) \\
\rightarrow & 1 \text { as }(N, T) \rightarrow \infty .
\end{aligned}
$$

Lemma A. 1 Suppose that the conditions in Theorem 2.6 hold. Let $\bar{\sigma}_{G^{0}}^{2}=\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T} \tilde{u}_{i t}^{2}$. Then $\max _{K_{0} \leq K \leq K_{\max }}\left|\hat{\sigma}_{\hat{G}\left(K, \lambda_{1}\right)}^{2}-\bar{\sigma}_{G^{0}}^{2}\right|=O_{P}\left(\delta_{N T}^{-2}\right)$.

Proof. When $K \geq K_{0}$, following the proof of Theorem 2.1, we can show that

$$
\left\|\hat{\beta}_{i}-\beta_{i}^{0}\right\|=O_{P}\left(T^{-1 / 2}+\lambda_{1}\right) \text { for each } i \text { and } \frac{1}{N} \sum_{i=1}^{N} \Pi_{k=1}^{K}\left\|\beta_{i}^{0}-\hat{\alpha}_{k}\right\|=O_{P}\left(T^{-1 / 2}\right) .
$$

Noting that $\beta_{i}^{0}, i=1, \ldots, N$, only take $K_{0}$ distinct values, the latter implies that the collection $\left\{\hat{\alpha}_{k}, k=\right.$ $1, \ldots, K\}$ contains at least $K_{0}$ distinct vectors, say, $\hat{\alpha}_{(1)}, \ldots, \hat{\alpha}_{\left(K_{0}\right)}$, such that $\hat{\alpha}_{(k)}-\alpha_{k}^{0}=O_{P}\left(T_{1}^{-1 / 2}\right)$ for $k=$
$1, \ldots, K_{0}$. For notational simplicity, we rename the other vectors in the above collection as $\hat{\alpha}_{\left(K_{0}+1\right)}, \ldots, \hat{\alpha}_{(K)}$. As before, we classify $i \in \hat{G}_{k}\left(K, \lambda_{1}\right)$ if $\left\|\hat{\beta}_{i}-\hat{\alpha}_{(k)}\right\|=0$ for $k=1, \ldots, K$, and $i \in \hat{G}_{0}\left(K, \lambda_{1}\right)$ otherwise. Using arguments like those used in the proof of Theorem 2.2, we can show that

$$
\sum_{i \in G_{k}^{0}} P\left(\hat{E}_{k N T, i}\right)=o(1) \text { for } k=1, \ldots, K_{0} \text { and } \sum_{i \in \hat{G}_{k}\left(K, \lambda_{1}\right)} P\left(\hat{F}_{k N T, i}\right)=o(1) \text { for } k=1, \ldots, K_{0}
$$

The first part implies that $\sum_{i=1}^{N} P\left(i \in \hat{G}_{0}\left(K, \lambda_{1}\right) \cup \hat{G}_{K_{0}+1}\left(K, \lambda_{1}\right) \cup \cdots \cup \hat{G}_{K}\left(K, \lambda_{1}\right)\right)=o(1)$.
Using the fact that $1\left\{i \in \hat{G}_{k}\right\}=1\left\{i \in G_{k}^{0}\right\}+1\left\{i \in \hat{G}_{k} \backslash G_{k}^{0}\right\}-1\left\{i \in G_{k}^{0} \backslash \hat{G}_{k}\right\}$, we have

$$
\begin{aligned}
\hat{\sigma}_{\hat{G}\left(K, \lambda_{1}\right)}^{2}= & \frac{1}{N T} \sum_{k=1}^{K} \sum_{i \in \hat{G}_{k}\left(K, \lambda_{1}\right)} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\tilde{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}^{\prime} \tilde{x}_{i t}\right)^{2} \\
= & \frac{1}{N T} \sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\tilde{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}^{\prime} \tilde{x}_{i t}\right)^{2}+\frac{1}{N T} \sum_{k=1}^{K_{0}} \sum_{i \in \hat{G}_{k}\left(K, \lambda_{1}\right) \backslash G_{k}^{0}} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\tilde{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}^{\prime} \tilde{x}_{i t}\right)^{2} \\
& -\frac{1}{N T} \sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0} \backslash \hat{G}_{k}\left(K, \lambda_{1}\right)} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\tilde{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}^{\prime} \tilde{x}_{i t}\right)^{2}+\frac{1}{N T} \sum_{k=K_{0}+1}^{K} \sum_{i \in \hat{G}_{k}\left(K, \lambda_{1}\right)} \sum_{t=1}^{T}\left(\tilde{y}_{i t}-\tilde{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}^{\prime} \tilde{x}_{i t}\right)^{2} \\
\equiv & D_{1 N T}+D_{2 N T}-D_{3 N T}+D_{4 N T}, \text { say. }
\end{aligned}
$$

Following the proof of Theorem 2.5, for $k=1, \ldots, K_{0}$, we have $\tilde{\alpha}_{\hat{G}_{k}\left(K, \lambda_{1}\right)}-\alpha_{k}^{0}=O_{P}\left(\delta_{N T}^{-1}\right)$. In addition, we can readily show that

$$
D_{1 N T}=\bar{\sigma}_{G^{0}}^{2}+O_{P}\left(\delta_{N T}^{-2}\right)
$$

For $D_{2 N T}, D_{3 N T}$, and $D_{4 N T}$, we have that for any $\epsilon>0$,

$$
\begin{aligned}
& P\left(D_{2 N T} \geq \delta_{N T}^{-2} \epsilon\right) \leq \sum_{i=1}^{K_{0}} P\left(\hat{F}_{k N T}\right) \rightarrow 0 \\
& P\left(D_{3 N T} \geq \delta_{N T}^{-2} \epsilon\right) \leq \sum_{i=1}^{K_{0}} P\left(\hat{E}_{k N T}\right) \rightarrow 0, \text { and } \\
& P\left(D_{4 N T} \geq \delta_{N T}^{-2} \epsilon\right) \leq \sum_{i=1}^{N} \operatorname{Pr}\left(i \in \cup_{K_{0}+1 \leq k \leq K} \hat{G}_{k}\left(K, \lambda_{1}\right)\right) \rightarrow 0
\end{aligned}
$$

It follows that $\hat{\sigma}_{\hat{G}\left(K, \lambda_{1}\right)}^{2}=\bar{\sigma}_{G^{0}}^{2}+O_{P}\left(\delta_{N T}^{-2}\right)$ for all $K_{0} \leq K \leq K_{\max }$.

## B Proof of the Results in Section 3

We start by proving a useful technical result and then proceed to prove the main results.
Let $V_{i N T}\left(\beta_{i}\right) \equiv\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right]^{\prime} W_{i N T}\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right]$, and $\bar{V}_{i}\left(\beta_{i}\right) \equiv\left\{\frac{1}{T} \sum_{t=1}^{T} E\left[\rho\left(\xi_{i t}, \beta_{i}\right)\right]\right\}^{\prime}$ $W_{i} \frac{1}{T} \sum_{t=1}^{T} E\left[\rho\left(\xi_{i t}, \beta_{i}\right)\right]$. Let $R_{i, T}\left(\beta_{i}\right)=\left[\frac{1}{T} \sum_{t=1}^{T}\left\{\rho\left(\xi_{i}, \beta_{i}\right)-E\left[\rho\left(\xi_{i}, \beta_{i}\right)\right]\right\}\right]^{\prime} W_{i}\left[\frac{1}{T} \sum_{t=1}^{T}\left\{\rho\left(\xi_{i}, \beta_{i}\right)-\right.\right.$ $\left.\left.E\left[\rho\left(\xi_{i}, \beta_{i}\right)\right]\right\}\right]$.

Lemma B. 1 Suppose Assumption B1(iv) hold. Then $\underline{c}\left[\frac{1}{2} \bar{V}_{i}\left(\beta_{i}\right)-R_{i, T}\left(\beta_{i}\right)\right] \leq V_{i N T}\left(\beta_{i}\right) \leq \bar{c}\left[2 \bar{V}_{i}\left(\beta_{i}\right)\right.$ $\left.+2 R_{i, T}\left(\beta_{i}\right)\right]$ for all $\beta_{i} \in B$ w.p.a.1, where $\underline{c}$ and $\bar{c}$ are some generic positive constants that do not depend on $i$ with $0<\underline{c}<1<\bar{c}<\infty$.

Proof. Noting that $W_{i N T}=W_{i}+o_{P}(1)$ uniformly in $i$ under Assumption B1(iv), we have w.p.a. 1

$$
\begin{equation*}
\underline{c}\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right]^{\prime} W_{i}\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right] \leq V_{i N T}\left(\beta_{i}\right) \leq \bar{c}\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right]^{\prime} W_{i}\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right] \tag{B.1}
\end{equation*}
$$

for all $\beta_{i} \in B_{i}$. By the positive definiteness of $W_{i}$ and the matrix version of the Cauchy-Schwarz inequality, we can readily show that

$$
(a-b)^{\prime} W_{i}(a-b) \geq \frac{1}{2} a^{\prime} W_{i} a-b^{\prime} W_{i} b \text { and }(a-b)^{\prime} W_{i}(a-b) \leq 2 a^{\prime} W_{i} a+2 b^{\prime} W_{i} b
$$

for any conformable vectors $a$ and $b$. Taking $a=\frac{1}{T} \sum_{t=1}^{T} E\left[\rho\left(\xi_{i t}, \beta_{i}\right)\right]$ and $b=\frac{1}{T} \sum_{t=1}^{T}\left\{\rho\left(\xi_{i t}, \beta_{i}\right)-\right.$ $\left.E\left[\rho\left(\xi_{i t}, \beta_{i}\right)\right]\right\}$, we have

$$
\begin{align*}
& {\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right]^{\prime} W_{i}\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right] \geq \frac{1}{2} \bar{V}_{i}\left(\beta_{i}\right)-R_{i, T}\left(\beta_{i}\right) \text { and }}  \tag{B.2}\\
& {\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right]^{\prime} W_{i}\left[\frac{1}{T} \sum_{t=1}^{T} \rho\left(\xi_{i t}, \beta_{i}\right)\right] \leq 2 \bar{V}_{i}\left(\beta_{i}\right)+2 R_{i, T}\left(\beta_{i}\right)} \tag{B.3}
\end{align*}
$$

Combining (B.1)-(B.3) yields the desired results.
Proof of Theorem 3.1. (i) Let $Q_{2 i N T, \lambda_{2}}^{\left(K_{0}\right)}\left(\beta_{i}, \boldsymbol{\alpha}\right)=V_{i N T}\left(\beta_{i}\right)+\lambda_{2} \Pi_{k=1}^{K_{0}}\left\|\beta_{i}-\alpha_{k}\right\|$. By the definition of $\tilde{\beta}$ and $\tilde{\alpha}$ and the fact that $Q_{2 N T, \lambda_{2}}^{\left(K_{0}\right)}(\boldsymbol{\beta}, \boldsymbol{\alpha})=\frac{1}{N} \sum_{i=1}^{N} Q_{2 i N T, \lambda_{2}}^{\left(K_{0}\right)}\left(\beta_{i}, \boldsymbol{\alpha}\right)$, we have

$$
\begin{align*}
& Q_{2 i N T, \lambda_{2}}\left(\tilde{\beta}_{i}, \tilde{\boldsymbol{\alpha}}\right)-Q_{2 i N T, \lambda_{2}}\left(\beta_{i}^{0}, \tilde{\boldsymbol{\alpha}}\right) \\
= & V_{i N T}\left(\tilde{\beta}_{i}\right)-V_{i N T}\left(\beta_{i}^{0}\right)+\lambda_{2}\left\{\Pi_{k=1}^{K}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|-\Pi_{k=1}^{K}\left\|\beta_{i}^{0}-\tilde{\alpha}_{k}\right\|\right\} \leq 0 . \tag{B.4}
\end{align*}
$$

By Lemma B. 1 and Assumptions B1(i) and (iv), we have that $V_{i N T}\left(\tilde{\beta}_{i}\right) \geq \underline{c}\left[\frac{1}{2} \bar{V}_{i}\left(\tilde{\beta}_{i}\right)-\tilde{R}_{i, T}\right]$ and $V_{i N T}\left(\beta_{i}^{0}\right) \leq \bar{c}\left[2 \bar{V}_{i}\left(\beta_{i}^{0}\right)+2 R_{i, T}^{0}\right]=2 \bar{c} R_{i, T}^{0}$ w.p.a.1, where $\tilde{R}_{i, T}=R_{i, T}\left(\tilde{\beta}_{i}\right)$ and $R_{i, T}^{0}=R_{i, T}\left(\beta_{i}^{0}\right)$. It follows that

$$
\underline{c}\left[\frac{1}{2} \bar{V}_{i}\left(\tilde{\beta}_{i}\right)-\tilde{R}_{i, T}\right]-2 \bar{c} R_{i, T}^{0}+\lambda_{2}\left\{\Pi_{k=1}^{K}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|-\Pi_{k=1}^{K}\left\|\beta_{i}^{0}-\tilde{\alpha}_{k}\right\|\right\} \leq 0
$$

which can be rewritten as

$$
\begin{equation*}
\bar{V}_{i}\left(\tilde{\beta}_{i}\right) \leq \frac{2}{\underline{c}}\left[2 \bar{c} R_{i, T}^{0}+\underline{c} \tilde{R}_{i, T}-\lambda_{2}\left(\Pi_{k=1}^{K}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|-\Pi_{k=1}^{K}\left\|\beta_{i}^{0}-\tilde{\alpha}_{k}\right\|\right)\right] \tag{B.5}
\end{equation*}
$$

Using arguments like those applied to obtain (A.2) and (A.4), we have

$$
\begin{equation*}
\left|\Pi_{k=1}^{K}\left\|\tilde{\beta}_{i}-\alpha_{k}\right\|-\Pi_{k=1}^{K}\left\|\beta_{i}^{0}-\alpha_{k}\right\|\right| \leq C_{K_{0} N T}(\boldsymbol{\alpha})\left(\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|+2\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|^{2}\right) \tag{B.6}
\end{equation*}
$$

Noting that $\frac{1}{T} \sum_{t=1}^{T} E\left[\rho\left(\xi_{i}, \beta_{i}\right)\right]=-\bar{Q}_{i, z \Delta x}\left(\beta_{i}-\beta_{i}^{0}\right)$, we have

$$
\begin{equation*}
\max _{1 \leq i \leq N} \bar{V}_{i}\left(\tilde{\beta}_{i}\right)=\max _{1 \leq i \leq N}\left(\tilde{\beta}_{i}-\beta_{i}^{0}\right)^{\prime} \bar{Q}_{i, z \Delta x}^{\prime} W_{i} \bar{Q}_{i, z \Delta x}\left(\tilde{\beta}_{i}-\beta_{i}^{0}\right) \geq \underline{c}_{1 N T} \max _{1 \leq i \leq N}\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|^{2} \tag{B.7}
\end{equation*}
$$

where $\underline{c}_{1 N T} \equiv \min _{1 \leq i \leq N} \mu_{\min }\left(\bar{Q}_{i, z \Delta x}^{\prime} W_{i} \bar{Q}_{i, z \Delta x}\right)$ satisfies that $\liminf \inf _{(N, T) \rightarrow \infty} \underline{c}_{1 N T} \geq \underline{c}_{W} \underline{c}_{\bar{Q}}>0$ by Assumptions B1(iii)-(iv). Combining (B.5)-(B.7) yields

$$
\underline{c}_{1 N T}\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|^{2} \leq \frac{2}{\underline{c}}\left[2 \bar{c} R_{i, T}^{0}+\underline{c} \tilde{R}_{i, T}+\lambda_{2} \tilde{C}_{K_{0}}\left(\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|+2\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|^{2}\right)\right]
$$

or equivalently, $\left(\underline{c_{1 N T}}-\frac{4}{\underline{c}} \lambda_{2} \tilde{C}_{K_{0}}\right)\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|^{2} \leq \frac{2}{\underline{c}}\left[2 \bar{c} R_{i, T}^{0}+\underline{c} \tilde{R}_{i, T}+\lambda_{2} \tilde{C}_{K_{0}}\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|\right]$, where $\tilde{C}_{K_{0}}=$ $C_{K_{0} N T}(\tilde{\boldsymbol{\alpha}})$. It follows that

$$
\begin{equation*}
\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\| \leq \frac{\frac{2}{\underline{c}} \lambda_{2} \tilde{C}_{K_{0}}+\left[\left(\frac{2}{\underline{c}} \lambda_{2} \tilde{C}_{K_{0}}\right)^{2}+\frac{8}{\underline{c}}\left(\underline{c}_{1 N T}-\frac{4}{\underline{c}} \lambda_{2} \tilde{C}_{K_{0}}\right)\left(2 \bar{c} R_{i, T}^{0}+\underline{c} \tilde{R}_{i, T}\right)\right]^{1 / 2}}{2\left(\underline{c}_{1 N T}-\frac{4}{\underline{c}} \lambda_{2} \tilde{C}_{K_{0}}\right)}=O_{P}\left(\eta_{2 N T}\right) \tag{B.8}
\end{equation*}
$$

where $\eta_{2 N T} \equiv T^{-1 / 2}+\lambda_{2}$. Further, noting that $\frac{1}{N} \sum_{i=1}^{N} \tilde{R}_{i, T}^{2}=O_{P}(1)$ and $\frac{1}{N} \sum_{i=1}^{N}\left(R_{i, T}^{0}\right)^{2}=O_{P}(1)$ under Assumptions B1(ii) and (iv), we can readily show that $\frac{1}{N} \sum_{i=1}^{N}\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|^{2}=O_{P}\left(\eta_{2 N T}^{2}\right)$. As in the proof of Theorem 2.1(ii), we can further demonstrate that $\frac{1}{N} \sum_{i=1}^{N}\left\|\tilde{\beta}_{i}-\beta_{i}^{0}\right\|^{2}=O_{P}\left(T^{-1}\right)$.

The proof of (iii) is completely analogous to that of Theorem 2.1(iii), now using the facts that $\left|P_{N T}(\tilde{\boldsymbol{\beta}}, \boldsymbol{\alpha})-P_{N T}\left(\boldsymbol{\beta}^{0}, \boldsymbol{\alpha}\right)\right|=O_{P}\left(T^{-1}\right)$ and that $0 \geq P_{N T}(\tilde{\boldsymbol{\beta}}, \tilde{\boldsymbol{\alpha}})-P_{N T}\left(\tilde{\boldsymbol{\beta}}, \boldsymbol{\alpha}^{0}\right)$.

Proof of Theorem 3.2. (i) Fix $k \in\left\{1, \ldots, K_{0}\right\}$. By the consistency of $\tilde{\alpha}_{k}$ and $\tilde{\beta}_{i}$ with $\alpha_{k}^{0}$ for $i \in G_{k}^{0}$, we have $\tilde{\beta}_{i}-\tilde{\alpha}_{l} \xrightarrow{P} \alpha_{k}^{0}-\alpha_{l}^{0} \neq 0$ for all $l \neq k$. It follows that w.p.a. $1\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{l}\right\| \neq 0$ for all $i \in G_{k}^{0}$ and $l \neq k$. Now, suppose that $\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\| \neq 0$ for some $i \in G_{k}^{0}$. Then the first order condition (with respect to $\beta_{i}$ ) for the minimization problem in (3.2) implies that

$$
\begin{aligned}
0= & -2 \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \frac{1}{\sqrt{T}} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\tilde{\beta}_{i}^{\prime} \Delta x_{i t}\right)+\sqrt{T} \lambda_{2} \sum_{j=1}^{K_{0}} \frac{\tilde{\beta}_{i}-\tilde{\alpha}_{j}}{\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{j}\right\|} \Pi_{l=1, l \neq j}^{K_{0}}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{l}\right\| \\
= & -2 \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \frac{1}{\sqrt{T}} \sum_{t=1}^{T} z_{i t} \Delta u_{i t}+\left(2 \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \tilde{Q}_{i, z \Delta x}+\frac{\lambda_{2} \tilde{c}_{k i}}{\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|}\right) \sqrt{T}\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right) \\
& +2 \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \tilde{Q}_{i, z \Delta x} \sqrt{T}\left(\tilde{\alpha}_{k}-\beta_{i}^{0}\right)+\sqrt{T} \lambda_{2} \sum_{j=1, j \neq k}^{K_{0}} \frac{\tilde{\beta}_{i}-\tilde{\alpha}_{j}}{\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{j}\right\|} \Pi_{l=1, l \neq j}^{K_{0}}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{l}\right\| \\
\equiv & -\tilde{B}_{i 1}+\tilde{B}_{i 2}+\tilde{B}_{i 3}+\sum_{j=1, j \neq k}^{K_{0}} \tilde{B}_{i 4, j}, \text { say, }
\end{aligned}
$$

where $\tilde{c}_{k i}=\Pi_{l=1, l \neq k}^{K_{0}}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{l}\right\| \xrightarrow{P} c_{k}^{0} \equiv \Pi_{l=1, l \neq k}^{K_{0}}\left\|\alpha_{k}^{0}-\alpha_{l}^{0}\right\|>0$ for any $i \in G_{k}^{0}$ by Theorem 3.1.
As in the proof of Theorem 2.2, we can readily show that $\tilde{B}_{i 1}=O_{P}(1), \tilde{B}_{i 3}=O_{P}(1)$, and $\tilde{B}_{i 4, j}=$ $\sqrt{T} \lambda_{2} O_{P}\left(T^{-1 / 2}+\lambda_{2}\right)=O_{P}(1)$ for each $i \in G_{k}^{0}$ and $j=1, \ldots, K_{0}$. Let $\tilde{R}_{i}=\tilde{B}_{i 3}+\sum_{j=1, j \neq k}^{K_{0}} \tilde{B}_{i 4, j}$ and $\tilde{\delta}_{1 i} \equiv \mu_{\min }\left(\tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \tilde{Q}_{i, z \Delta x}\right)$. Noting that $\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{B}_{i 2} \geq 2 \tilde{\delta}_{1 i} \sqrt{T}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|^{2}+\sqrt{T} \lambda_{2} \tilde{c}_{k i}$, and $\left|\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{R}_{i}\right|=O_{P}\left(\lambda_{2}\right)$, we have $\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{B}_{i 2}-\left|\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{R}_{i}\right| \geq\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{B}_{i 2} / 2$ as $(N, T) \rightarrow \infty$.

It follows that by Assumption B2(i)

$$
\begin{aligned}
P\left(\tilde{E}_{k N T, i}\right) & =P\left(i \notin \tilde{G}_{k} \mid i \in G_{k}^{0}\right)=P\left(\tilde{B}_{i 1}=\tilde{B}_{i 2}+\tilde{R}_{i}\right) \\
& \leq P\left(\| \tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{B}_{i 1}\left|\geq\left|\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{B}_{i 2}+\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{R}_{i}\right|\right) \\
& \leq P\left(\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|\left\|\tilde{B}_{i 1}\right\| \geq\left(\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right)^{\prime} \tilde{B}_{i 2} / 2\right) \\
& \leq P\left(\left\|\tilde{B}_{i 1}\right\| \geq \tilde{\delta}_{1 i} \sqrt{T}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|+\frac{\sqrt{T} \lambda_{2} \tilde{c}_{k i}}{2\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|}\right) \\
& \leq P\left(\left\|\tilde{B}_{i 1}\right\| \geq \sqrt{2 \tilde{\delta}_{1 i} \tilde{c}_{k i} T \lambda_{2}}\right) \rightarrow 0 \text { as }(N, T) \rightarrow \infty
\end{aligned}
$$

where we use the fact that $\tilde{c}_{k i} \xrightarrow{P} c_{k}^{0}$ for $i \in G_{k}^{0}$ and $\tilde{\delta}_{1 i} \xrightarrow{P} \mu_{\text {min }}\left(\bar{Q}_{i, z \Delta x}^{\prime} W_{i} \bar{Q}_{i, z \Delta x}\right) \geq \mu_{\text {min }}\left(\bar{Q}_{i, z \Delta x}^{\prime} \bar{Q}_{i, z \Delta x}\right)$ $\mu_{\min }\left(W_{i}\right)>0$ by Assumptions B1(iii)-(iv). It follows that $P\left(\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{k}\right\|=0 \mid i \in G_{k}^{0}\right) \rightarrow 1$ as $(N, T) \rightarrow$ $\infty$. Now, observe that $P\left(\cup_{k=1}^{K_{0}} \hat{E}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} P\left(\hat{E}_{k N T}\right) \leq \sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(\hat{E}_{k N T, i}\right)$ and

$$
\begin{aligned}
\sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(\tilde{E}_{k N T, i}\right) & \leq \sum_{k=1}^{K_{0}} \sum_{i \in G_{k}^{0}} P\left(\left\|\tilde{B}_{i 1}\right\| \geq \sqrt{2 \tilde{\delta}_{i} \tilde{c}_{k i} T \lambda_{2}}\right) \\
& \leq N \max _{1 \leq i \leq N} P\left(\left\|\tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \frac{1}{T} \sum_{t=1}^{T} z_{i t} \Delta u_{i t}\right\| \geq \sqrt{\tilde{\delta}_{1 i} \tilde{c}_{k i} \lambda_{2} / 2}\right) \\
& \leq N \max _{1 \leq i \leq N} P\left(\left\|\frac{1}{T} \sum_{t=1}^{T} z_{i t} \Delta u_{i t}\right\| \geq \sqrt{\frac{\tilde{\delta}_{1 i} \tilde{c}_{k i} \lambda_{2}}{2 \tilde{\delta}_{2 i}}}\right) \\
& \rightarrow 0 \text { by Assumption B2(ii), }
\end{aligned}
$$

where $\tilde{\delta}_{2 i} \equiv\left\|\tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T}\right\|^{2} \xrightarrow{P} \operatorname{tr}\left(\bar{Q}_{i, z \Delta x}^{\prime} W_{i} W_{i} \bar{Q}_{i, z \Delta x}\right) \leq\left[\mu_{\max }\left(W_{i}\right)\right]^{2}\left[\mu_{\max }\left(\bar{Q}_{i, z \Delta x}^{\prime} \bar{Q}_{i, z \Delta x}\right)\right]^{1 / 2}<\infty$ by Assumption B1(iii)-(iv). Consequently, we have shown (i).
(ii) The proof of (i) is almost identical to that of Theorem 2.2(ii) and is omitted.

Proof of Theorem 3.4. The proof follows closely from that of Theorem 2.4 and we only sketch it. Based on the subdifferential calculus, the KKT conditions for the minimization of (3.2) are that for each $i=1, \ldots, N$ and $k=1, \ldots, K_{0}$,

$$
\begin{aligned}
& \mathbf{0}_{p \times 1}=-2 \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \frac{1}{N T} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\tilde{\beta}_{i}^{\prime} \Delta x_{i t}\right)+\frac{\lambda_{2}}{N} \sum_{j=1}^{K_{0}} \tilde{e}_{i j} \Pi_{l=1, l \neq j}^{K_{0}}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{l}\right\|, \text { and } \\
& \mathbf{0}_{p \times 1}=\frac{\lambda_{1}}{N} \sum_{i=1}^{N} \tilde{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{l}\right\|,
\end{aligned}
$$

where $\tilde{e}_{i j}=\frac{\tilde{\beta}_{i}-\tilde{\alpha}_{j}}{\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{j}\right\|}$ if $\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{j}\right\| \neq 0$ and $\left\|\tilde{e}_{i j}\right\| \leq 1$ if $\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{j}\right\|=0$. Fix $k \in\left\{1, \ldots, K_{0}\right\}$. As in the proof of Theorem 2.4, we can show that $\frac{2}{N T} \sum_{i \in \tilde{G}_{k}} \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\tilde{\alpha}_{k}^{\prime} \Delta x_{i t}\right)+\frac{\lambda_{2}}{N} \sum_{i \in \tilde{G}_{0}} \tilde{e}_{i k}$
$\Pi_{l=1, l \neq k}^{K_{0}}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{l}\right\|=0_{p \times 1}$ w.p.a.1. It follows that

$$
\begin{aligned}
\tilde{\alpha}_{k}= & \left(\frac{1}{N} \sum_{i \in \tilde{G}_{k}} \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \tilde{Q}_{i, z \Delta x}\right)^{-1} \frac{1}{N T} \sum_{i \in \tilde{G}_{k}} \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \sum_{t=1}^{T} z_{i t} \Delta y_{i t} \\
& +\left(\frac{1}{N} \sum_{i \in \tilde{G}_{k}} \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \tilde{Q}_{i, z \Delta x}\right)^{-1} \frac{\lambda_{2}}{2 N} \sum_{i \in \tilde{G}_{0}} \tilde{e}_{i k} \Pi_{l=1, l \neq k}^{K_{0}}\left\|\tilde{\beta}_{i}-\tilde{\alpha}_{l}\right\| \equiv \tilde{\alpha}_{1 k}+\tilde{\mathcal{R}}_{k}, \text { say. }
\end{aligned}
$$

By Theorem 3.2, we can readily show that $P\left(\sqrt{N T}\left\|\tilde{\mathcal{R}}_{k}\right\| \geq \epsilon\right)=o(1)$ for any $\epsilon>0$, and

$$
\sqrt{N_{k} T}\left(\tilde{\alpha}_{1 k}-\alpha_{k}^{0}\right)=\left(\frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \tilde{Q}_{i, z \Delta x}\right)^{-1} \frac{1}{\sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \sum_{t=1}^{T} z_{i t} \Delta u_{i t}+o_{P}(1)
$$

Under Assumptions B1(iv) and B3(i)-(ii), we have $\frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} \tilde{Q}_{i, z \Delta x}^{\prime} W_{i N T} \tilde{Q}_{i, z \Delta x}=\frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} \bar{Q}_{i, z \Delta x}^{\prime} W_{i} \bar{Q}_{i, z \Delta x}$ $+o_{P}(1)=A_{k}+o_{P}(1)$. Then the result follows from Assumption B3(iii) and Slutsky theorem.

Proof of Theorem 3.5. Following the proof of Theorem 2.5, we can readily show that

$$
\begin{aligned}
\sqrt{N_{k} T}\left(\tilde{\alpha}_{\tilde{G}_{k}}-\alpha_{k}^{0}\right) & =\left[\tilde{Q}_{z \Delta x}^{(k) \prime} W_{N T}^{(k)} \tilde{Q}_{z \Delta x}^{(k)}\right]^{-1} \tilde{Q}_{z \Delta x}^{(k) \prime} W_{N T}^{(k)} \sqrt{N_{k} T} \tilde{Q}_{z \Delta u}^{(k)}+o_{P}(1) \\
& =\left[Q_{z \Delta x, N T}^{(k) \prime} W_{N T}^{(k)} Q_{z \Delta x, N T}^{(k)}\right]^{-1} Q_{z \Delta x, N T}^{(k) \prime} W_{N T}^{(k)} \sqrt{N_{k} T} Q_{z \Delta u, N T}^{(k)}+o_{P}(1)
\end{aligned}
$$

where $\tilde{Q}_{z \Delta u}^{(k)}=\frac{1}{N_{k} T} \sum_{i \in \tilde{G}_{k}} \sum_{t=1}^{T} z_{i t} \Delta u_{i t}$ and $Q_{z \Delta u, N T}^{(k)}=\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} z_{i t} \Delta u_{i t}$. The results then follow from analysis arguments as used in the proof of Theorem 2.5, Assumption B3, and Slutsky theorem.

Proof of Theorem 3.6. The proof is analogous to that of Theorem 2.6 and is omitted.

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Supplementary Material On<br>"Identifying Latent Structures in Panel Data"<br>Liangjun Su ${ }^{a}$, Zhentao Shi ${ }^{b}$, and Peter C. B. Phillips ${ }^{a, b, c, d}$<br>${ }^{a}$ School of Economics, Singapore Management University<br>${ }^{b}$ Department of Economics, Yale University<br>${ }^{c}$ Department of Economics, University of Auckland<br>${ }^{d}$ Department of Economics, University of Southampton

## THIS APPENDIX PROVIDES SOME ADDITIONAL RESULTS FOR THE ABOVE PAPER.

## C Some Primitive Assumptions and Technical Lemmas

This appendix presents some primitive assumptions to ensure that the high level condition in Assumptions A1(ii) and A2(ii) hold for non-dynamic panel data models. Then we discuss primitive conditions that ensure they hold for dynamic panels. The verification of Assumption B2(ii) is similar.

ASSUMPTION C1 (i) For each $i=1, \ldots, N,\left\{\left(x_{i t}, u_{i t}\right): t=1,2, \ldots\right\}$ is strong mixing with mixing coefficients $\left\{\alpha_{i}(\cdot)\right\} . \alpha(\cdot) \equiv \max _{1 \leq i \leq N} \alpha_{i}(\cdot)$ satisfies $\alpha(\tau) \leq c_{\alpha} \rho^{\tau}$ for some $c_{\alpha}=O(1)$ and $\rho \in(0,1)$. $E\left(x_{i t} u_{i t}\right)=0$ for each $i$ and $t$.
(ii) There exists a constant $\underline{c}_{\tilde{x} \tilde{x}}$ such that $0<\underline{c}_{\tilde{x} \tilde{x}} \leq \min _{1 \leq i \leq N} \mu_{\min }\left(Q_{i, \tilde{x} \tilde{x}}\right)$.
(iii) Either one of the following two conditions is satisfied: (a) $\sup _{i \geq 1} \sup _{t \geq 1} E\left\|x_{i t}\right\|^{4 q} \leq C$ and $\sup _{i \geq 1} \sup _{t \geq 1} E\left\|x_{i t} u_{i t}\right\|^{2 q} \leq C$ for some $q>1$ and $C<\infty$; (b) There exist three constants $c_{x x}, c_{x u}$, and $c_{u}$ such that $\sup _{i \geq 1} \sup _{t \geq 1} E\left[\exp \left(c_{x x}\left\|x_{i t}\right\|^{2 \gamma}\right)\right] \leq C_{x x}, \sup _{i \geq 1} \sup _{t \geq 1} E\left[\exp \left(c_{x x}\left\|x_{i t} u_{i t}\right\|^{\gamma}\right)\right] \leq C_{x u}$, and $\sup _{i \geq 1} \sup _{t \geq 1} E\left[\exp \left(c_{u}\left\|u_{i t}\right\|^{\gamma}\right)\right] \leq C_{u}$ for some $C_{x x}<\infty, C_{x u}<\infty, C_{u}<\infty$, and $\gamma \in(0, \infty]$.
(iv) $T$ satisfies one of the following two conditions: (a) $T / N^{\epsilon} \rightarrow(0, \infty]$ for $\epsilon>1 /(2 q-1)$ if C 1 (iii.a) is satisfied; (b) $T /(\ln N)^{(1+\gamma) / \gamma} \rightarrow \infty$ if C 1 (iii.b) is satisfied.
(v) $T$ satisfies one of the following two conditions: (a) $\left.T \lambda_{1}\left\{(\ln N)^{-1}+T(N T)^{-1 / q}(\ln T)^{-4}(\ln N)^{-2}\right]\right\} \rightarrow$ $\infty$ if C 1 (iii.a) is satisfied; (b) $T \lambda_{1}\left\{(\ln N)^{-1}+T[\ln (N T)]^{-2(1+\gamma) / \gamma}\right\} \rightarrow \infty$ if C 1 (iii.b) is satisfied.
$\mathrm{C} 1(\mathrm{i})$ requires that each individual time series $\left\{x_{i t}: t=1,2, \ldots\right\}$ be strong-mixing with geometric mixing rate. If $\left\{x_{i t}\right\}$ are identically distributed for all individuals within the same group, then the sup $\max _{1 \leq i \leq N}$ is effectively taken with respect to $K_{0}$ groups. C1(ii) requires that the matrices $Q_{i, \tilde{x} \tilde{x}}$ be positive definite uniformly in $i$ and the uniformity is required only over the $K_{0}$ groups in the case of group-wise identical distributions. The conditions stated in Assumption C1(iii) pertain to two specific cases related to the moments of $\left\|x_{i t}\right\|^{2}$ and $x_{i t} u_{i t}$ : part (a) only requires finite $2 q$-th moments whereas part (b) requires the existence of exponential moments. By the Markov inequality, part (b) implies that

$$
P\left(\left\|x_{i t}\right\|^{2} \geq v\right) \leq \exp \left(1-\left(\frac{v}{K / c_{x x}}\right)^{\gamma}\right)
$$

where $K=\max \left(1, \ln C_{x x}\right)$. That is, the distribution of $\left\|x_{i t}\right\|^{2}$ has to decay exponentially fast. The case $\gamma=\infty$ in part (b) corresponds to the case where $\left\|x_{i t}\right\|$ is uniformly bounded. Similarly remarks hold for $\left\|x_{i t} u_{i t}\right\|$ and $\left\|u_{i t}\right\|$. When combined with $\mathrm{C} 1(\mathrm{i})$, the conditions in C 2 (iii) allow us to apply some exponential inequalities for strong mixing processes; see, e.g., Merlevède, Peilgrad, and Rio (2009, 2011). C1(iv) and (v) are needed to verify Assumption A1(ii) and A2(ii), respectively.

Lemma C. 1 Let $\left\{\xi_{t}, t=1,2, \ldots\right\}$ be a zero-mean strong mixing process, not necessarily stationary, with the mixing coefficients satisfying $\alpha(\tau) \leq c_{\alpha} \rho^{\tau}$ for some $c_{\alpha}>0$ and $\rho \in(0,1)$.
(i) If $\sup _{1 \leq t \leq T}\left|\xi_{t}\right| \leq M_{T}$, then there exists a constant $C_{0}$ depending on $c_{\alpha}$ and $\rho$ such that for any $T \geq 2$ and $\epsilon>0$,

$$
P\left(\left|\sum_{t=1}^{T} \xi_{t}\right|>\epsilon\right) \leq \exp \left(-\frac{C_{0} \epsilon^{2}}{v_{0}^{2} T+M_{T}^{2}+\epsilon M_{T}(\ln T)^{2}}\right)
$$

where $v_{0}^{2}=\sup _{t \geq 1}\left[\operatorname{Var}\left(\xi_{t}\right)+2 \sum_{s=t+1}^{\infty}\left|\operatorname{Cov}\left(\xi_{t}, \xi_{s}\right)\right|\right]$.
(ii) If $\sup _{t \geq 1} P\left(\left|\xi_{t}\right|>v\right) \leq \exp \left(1-(v / b)^{\gamma}\right)$ for some $b \in(0, \infty)$ and $\gamma \in(0, \infty]$, then there exist constants $C_{1}$ and $C_{2}$ depending only on $b, c_{\alpha}, \rho$, and $\gamma$ such that for any $T \geq 4$ and $\epsilon \geq C_{0}(\ln T)^{\eta_{0}}$ with $\eta_{0}, C_{0}>0$,

$$
P_{\mathcal{D}}\left(\left|\sum_{t=1}^{T} \xi_{t}\right|>\epsilon\right) \leq(T+1) \exp \left(-\frac{\epsilon^{\frac{\gamma}{1+\gamma}}}{C_{1}}\right)+\exp \left(-\frac{\epsilon^{2}}{T C_{2}}\right)
$$

Proof. (i) Merlevède, Peilgrad, and Rio (2009, Theorem 2) prove (i) under the condition $\alpha(\tau) \leq$ $\exp (-2 c \tau)$ for some $c>0$. If $c_{\alpha}=1$, we can take $\rho=\exp (-2 c)$ and apply the theorem to obtain the claim in (i). Other values of $c_{\alpha}$ do not alter the conclusion.
(ii) Merlevède, Peilgrad, and Rio (2011, Theorem 1) prove a result that is more general than that in (ii) under the condition $\alpha(\tau) \leq \exp \left(-c_{1} \tau^{\gamma_{1}}\right)$ for some $c_{1}, \gamma_{1}>0$. If $c_{\alpha}=1$ and $\gamma_{1}=1$, we can take $\rho=\exp \left(-2 c_{1}\right)$ and apply the theorem to obtain the claim in (ii). Other values of $c_{\alpha}$ do not alter the conclusion.

Lemma C. 2 Let $\hat{Q}_{i, \tilde{x} \tilde{x}} \equiv T^{-1} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}$. Suppose that Assumptions C1(i)-(iii) hold.
(i) If C1(iv) holds, then $\min _{1 \leq i \leq N} \mu_{\min }\left(\hat{Q}_{i, \tilde{x} \tilde{x}}\right) \geq \min _{1 \leq i \leq N} \mu_{\min }\left(Q_{i, \tilde{x} \tilde{x}}\right)-o_{P}(1)$;
(ii) If C1(v) holds, then $N \max _{1 \leq i \leq N} P\left(\left\|\frac{1}{T} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}\right\| \geq c \sqrt{\lambda_{1}}\right) \rightarrow 0$ as $(N, T) \rightarrow \infty$.

Proof. (i) By the Weyl inequality and the fact that $\left|\mu_{\max }(A)\right| \leq\|A\|$ for any symmetric matrix $A$, we have

$$
\mu_{\min }\left(\hat{Q}_{i, \tilde{x} \tilde{x}}\right) \geq \mu_{\min }\left(Q_{i, \tilde{x} \tilde{x}}\right)-\left\|\hat{Q}_{i, \tilde{x} \tilde{x}}-Q_{i, \tilde{x} \tilde{x}}\right\|
$$

We are left to show that $\max _{1 \leq i \leq N}\left\|\hat{Q}_{i, \tilde{x} \tilde{x}}-Q_{i, \tilde{x} \tilde{x}}\right\|=o_{P}(1)$. Noting that $\hat{Q}_{i, \tilde{x} \tilde{x}}=T^{-1} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}=$ $T^{-1} \sum_{t=1}^{T} x_{i t} x_{i t}^{\prime}-\bar{x}_{i} . \bar{x}_{i}^{\prime}$, it suffices to show that (i1) $\max _{1 \leq i \leq N}\left\|T^{-1} \sum_{t=1}^{T}\left[x_{i t} x_{i t}^{\prime}-\mathbb{E}\left(x_{i t} x_{i t}^{\prime}\right)\right]\right\|=o_{P}(1)$ and (i2) $\max _{1 \leq i \leq N}\left\|T^{-1} \sum_{t=1}^{T}\left[x_{i t}-\mathbb{E}\left(x_{i t}\right)\right]\right\|=o_{P}(1)$. We only prove (i1) as the proof of (i2) is analogous.

We first consider the case where Assumption C1(iii.a) hold. Let $\eta_{N T}=(N T)^{1 /(2 q)}$. Let $\iota_{s p}$ be an arbitrary $p \times 1$ unit vector such that $\left\|\iota_{s p}\right\|=1$ for $s=1,2$. Let $\zeta_{i t} \equiv \iota_{1 p}^{\prime}\left[x_{i t} x_{i t}^{\prime}-\mathbb{E}\left(x_{i t} x_{i t}^{\prime}\right)\right] \iota_{2 p}, \zeta_{1 i t} \equiv$ $\iota_{1 p}^{\prime}\left[x_{i t} x_{i t}^{\prime} \mathbf{1}_{i t}-\mathbb{E}\left(x_{i t} x_{i t}^{\prime} \mathbf{1}_{i t}\right)\right] \iota_{2 p}$ and $\zeta_{2 i t} \equiv \iota_{1 p}^{\prime}\left[x_{i t} x_{i t}^{\prime} \overline{\mathbf{1}}_{i t}-\mathbb{E}\left(x_{i t} x_{i t}^{\prime} \overline{\mathbf{1}}_{i t}\right)\right] \iota_{2 p}$, where $1_{i t} \equiv 1\left\{\left\|x_{i t}\right\|^{2} \leq \eta_{N T}\right\}$ and $\overline{1}_{i t}=1-1_{i t}$. Note that $\zeta_{i t}=\zeta_{1 i t}+\zeta_{2 i t}$. Let $v_{i}^{2}=\sup _{t \geq 1}\left[\operatorname{Var}\left(\zeta_{1 i t}\right)+2 \sum_{s=t+1}^{\infty} \operatorname{Cov}\left(\zeta_{1 i t}, \zeta_{1 i s}\right)\right]$ and $\bar{v}^{2}=\sup _{N \geq 1} \max _{1 \leq i \leq N} v_{i}^{2}$. The moment conditions in C1(iii.a) and Davydov inequality ensure that
$\bar{v}^{2}=O(1)$. By the Boole inequality and Lemma C.1(i), for any $\epsilon>0$,

$$
\begin{aligned}
P\left(\max _{1 \leq i \leq N}\left|T^{-1} \sum_{t=1}^{T} \zeta_{1 i t}\right| \geq \epsilon\right) & \leq N \max _{1 \leq i \leq N} P\left(\left|\sum_{t=1}^{T} \zeta_{1 i t}\right| \geq T \epsilon\right) \\
& \leq N \max _{1 \leq i \leq N} \exp \left(-\frac{C_{0} T^{2} \epsilon^{2}}{v_{i}^{2} T+4 \eta_{N T}^{2}+2 T \epsilon \eta_{N T}(\ln T)^{2}}\right) \\
& \leq \exp \left(-\frac{C_{0} T^{2} \epsilon^{2}}{\bar{v}^{2} T+4(N T)^{1 / q}+2 T \epsilon(N T)^{1 /(2 q)}(\ln T)^{2}}+\ln N\right) \\
& \rightarrow 0 \operatorname{as} T \rightarrow \infty
\end{aligned}
$$

By Assumption C1(iii.a), the Boole and Markov inequalities, and the dominated convergence theorem,

$$
\begin{aligned}
P\left(\max _{1 \leq i \leq N}\left|\frac{1}{T} \sum_{t=1}^{T} \zeta_{2 i t}\right| \geq \epsilon\right) & \leq P\left(\max _{1 \leq i \leq N} \max _{1 \leq t \leq T}\left\|x_{i t}\right\|^{2} \geq \eta_{N T}\right) \leq N T \max _{1 \leq i \leq N} \max _{1 \leq t \leq T} P\left(\left\|x_{i t}\right\|^{2} \geq \eta_{N T}\right) \\
& \leq \frac{N T}{\eta_{N T}^{2 q}} \max _{1 \leq i \leq N} \max _{1 \leq t \leq T} \mathbb{E}\left[\left\|x_{i t}\right\|^{4 q} \mathbf{1}\left\{\left\|x_{i t}\right\|^{2} \geq \eta_{N T}\right\}\right] \rightarrow 0 \text { as } T \rightarrow \infty
\end{aligned}
$$

Noting that $\iota_{1 p}$ and $\iota_{2 p}$ are arbitrary unit vectors, we infer that $\max _{1 \leq i \leq N}\left\|\frac{1}{T} \sum_{t=1}^{T}\left[x_{i t} x_{i t}^{\prime}-\mathbb{E}\left(x_{i t} x_{i t}^{\prime}\right)\right]\right\|$ $=o_{P}(1)$. Then (i) follows.

Next consider the case where Assumption C1(iii.b) holds. By the Boole inequality and Lemma C.1(ii), for any $\epsilon>0$,

$$
\begin{aligned}
P\left(\max _{1 \leq i \leq N}\left|T^{-1} \sum_{t=1}^{T} \zeta_{i t}\right| \geq \epsilon\right) & \leq N \max _{1 \leq i \leq N} P\left(\left|\sum_{t=1}^{T} \zeta_{i t}\right| \geq T \epsilon\right) \\
& \leq N \max _{1 \leq i \leq N}\left[(T+1) \exp \left(-\frac{(T \epsilon)^{\gamma /(1+\gamma)}}{C_{1}}\right)+\exp \left(-\frac{(T \epsilon)^{2}}{T C_{2}}\right)\right] \\
& \leq \exp \left(-\frac{(T \epsilon)^{\gamma /(1+\gamma)}}{C_{1}}+\ln (T+1)+\ln N\right)+\exp \left(-\frac{T \epsilon^{2}}{C_{2}}+\ln N\right) \\
& \rightarrow 0 \text { as } T \rightarrow \infty,
\end{aligned}
$$

provided $T \gg(\ln N)^{(1+\gamma) / \gamma}$. It follows that $\max _{1 \leq i \leq N}\left\|\frac{1}{T} \sum_{t=1}^{T}\left[x_{i t} x_{i t}^{\prime}-\mathbb{E}\left(x_{i t} x_{i t}^{\prime}\right)\right]\right\|=o_{P}(1)$.
(ii) Noting that $T^{-1} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{u}_{i t}=T^{-1} \sum_{t=1}^{T} x_{i t} u_{i t}-\bar{x}_{i} . \bar{u}_{i}$., we prove (ii) by showing that (ii1) $N \max _{1 \leq i \leq N} P\left(\left\|T^{-1} \sum_{t=1}^{T} x_{i t} u_{i t}\right\| \geq c \sqrt{\lambda_{1}}\right) \rightarrow 0,($ ii2 $) N \max _{1 \leq i \leq N} P\left(\left\|T^{-1} \sum_{t=1}^{T}\left[x_{i t}-\mathbb{E}\left(x_{i t}\right)\right]\right\| \geq c \sqrt{\lambda_{1}}\right)$ $\rightarrow 0$, and (ii3) $N \max _{1 \leq i \leq N} P\left(\left\|T^{-1} \sum_{t=1}^{T} u_{i t}\right\| \geq c \sqrt{\lambda_{1}}\right) \rightarrow 0$. We only outline the proof of (ii1) as the other two claims can be proved analogously. If Assumption C1(iii.a) holds, by letting $\varsigma_{i t} \equiv \iota_{1 p}^{\prime}\left[x_{i t} u_{i t}-\right.$ $\left.E\left(x_{i t} u_{i t}\right)\right], \varsigma_{1 i t} \equiv \iota_{1 p}^{\prime}\left[x_{i t} u_{i t} 1_{i t}-E\left(x_{i t} u_{i t} \mathbf{1}_{i t}\right)\right]$ and $\varsigma_{2 i t} \equiv \iota_{1 p}^{\prime}\left[x_{i t} u_{i t} \overline{1}_{i t}-E\left(x_{i t} u_{i t} \overline{\mathbf{1}}_{i t}\right)\right]$ where now $1_{i t} \equiv$ $1\left\{\left\|x_{i t} u_{i t}\right\| \leq \eta_{N T}\right\}$ and $\overline{1}_{i t}=1-1_{i t}$, we have

$$
\begin{aligned}
P\left(\max _{1 \leq i \leq N}\left|\frac{1}{T} \sum_{t=1}^{T} \varsigma_{1 i t}\right| \geq c \sqrt{\lambda_{1}}\right) & \leq N \max _{1 \leq i \leq N} P\left(\left|\sum_{t=1}^{T} \varsigma_{1 i t}\right| \geq c T \sqrt{\lambda_{1}}\right) \\
& \leq \exp \left(-\frac{c^{2} C_{0} T^{2} \lambda_{1}}{v^{2} T+4(N T)^{1 / q}+2 c T \sqrt{\lambda_{1}}(N T)^{1 /(2 q)}(\ln T)^{2}}+\ln N\right) \\
& \rightarrow 0 \text { as } T \rightarrow \infty
\end{aligned}
$$

and $P\left(\max _{1 \leq i \leq N}\left|\frac{1}{T} \sum_{t=1}^{T} \varsigma_{2 i t}\right| \geq c \sqrt{\lambda_{1}}\right) \leq N T \max _{1 \leq i \leq N} \max _{1 \leq t \leq T} P\left(\left\|x_{i t} u_{i t}\right\| \geq \eta_{N T}\right) \rightarrow 0$ as $T \rightarrow$ $\infty$. Here $v^{2}=\sup _{N \geq 1} \max _{1 \leq i \leq N} \sup _{t \geq 1}\left[\operatorname{Var}\left(\varsigma_{1 i t}\right)+2 \sum_{s=t+1}^{\infty} \operatorname{Cov}\left(\varsigma_{1 i t}, \varsigma_{1 i s}\right)\right]=O(1)$ under Assumption C1(iii.a). Similarly, if Assumption C1(iii.b) holds, then

$$
\begin{aligned}
P\left(\max _{1 \leq i \leq N}\left|\frac{1}{T} \sum_{t=1}^{T} \varsigma_{i t}\right| \geq c \sqrt{\lambda_{1}}\right) & \leq N \max _{1 \leq i \leq N} P\left(\left|\sum_{t=1}^{T} \varsigma_{i t}\right| \geq c T \sqrt{\lambda_{1}}\right) \\
& \leq N \max _{1 \leq i \leq N}\left[(T+1) \exp \left(-\frac{\left(c T \sqrt{\lambda_{1}}\right)^{\gamma /(1+\gamma)}}{C_{1}}\right)+\exp \left(-\frac{\left(c T \sqrt{\lambda_{1}}\right)^{2}}{T C_{2}}\right)\right] \\
& \leq \exp \left(-\frac{\left(c T \sqrt{\lambda_{1}}\right)^{\gamma /(1+\gamma)}}{C_{1}}+\ln (T+1)+\ln N\right)+\exp \left(-\frac{c^{2} T \lambda_{1}}{C_{2}}+\ln N\right) \\
& \rightarrow 0 \operatorname{as} T \rightarrow \infty
\end{aligned}
$$

provided $T \lambda_{1}\left\{(\ln N)^{-1}+T[\ln (N T)]^{-2(1+\gamma) / \gamma}\right\} \rightarrow \infty$.
Evidently Lemma C.2(i) ensures the second part of Assumption A1(ii) and Lemma C.2(ii) ensures Assumption A2(ii). These results rely on the use of Bernstein-type inequalities for strong mixing processes that are not necessarily stationary.

To verify Assumptions A1(ii) and A2(ii) for dynamic panel data models, we need to distinguish two cases based on whether we treat the fixed effects $\mu_{i}$ in (2.1) as random or not. If we follow Hahn and Kuersteiner (2011) and assume that the individual fixed effects are nonrandom and uniformly bounded, then we can assume that $\left\{\left(z_{i t} \Delta u_{i t}\right), t \geq 1\right\}$ is strong mixing for each $i$ and verify the assumptions as above. On the other hand, if we assume that $\mu_{i}$ 's are random fixed effects, then the notion of strong mixing is generally no longer appropriate for dynamic models. To appreciate the point, take the simple panel AR(1) model as an example:

$$
\begin{equation*}
y_{i t}=\rho_{0} y_{i, t-1}+\mu_{i}+u_{i t}, i=1, \ldots, N, t=1, \ldots, T \tag{C.1}
\end{equation*}
$$

where $x_{i t}=y_{i, t-1}$ and an example of the IV for $\Delta y_{i, t-1}$ would be $z_{i t}=y_{i, t-2}$. Even if $\left\{u_{i t}, t \geq 1\right\}$ is a strong mixing process, $\left\{y_{i t}, t \geq 1\right\}$ is generally not so if $\mu_{i}$ is stochastic as the dependence between $y_{i t}$ and $y_{i s}$ is not asymptotically vanishing as $|t-s|$ passes to infinity. In this case, as Hahn and Kuersteiner (2011) suggest, it is natural to adopt the concept of conditional strong mixing (see, e.g., Prakasa Rao (2009)) where the mixing coefficient is defined by conditioning on the fixed effects. Su and Chen (2013) adopt the latter approach in their study of panel data models with interactive fixed effects and show that the well known Davydov and Bernstein-type inequalities that hold for strong mixing processes also hold for conditional strong mixing processes. A conditional version of the results in Lemma C. 1 are also satisfied where all probabilities are defined by conditioning on the $\sigma$-field generated by $\left(\mu_{1}, \ldots, \mu_{N}\right)$. Then one can verify Assumptions A1(ii) and A2(ii) by following analogous arguments as used in the proof of Lemma C.2(ii).

## D Bias Correction

## D. 1 Bias Correction for the PLS C-Lasso Estimator

Recall from Theorems 2.4 and 2.5 that the bias takes the form

$$
b_{k N T}=\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T}
$$

where $\bar{\Phi}_{k} \equiv \frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}$, and $B_{k N T}=\frac{1}{N_{k}^{1 / 2} T^{1 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} E\left(x_{i s} \tilde{u}_{i s}\right)=-\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}}$ $\sum_{s=1}^{T} \sum_{t=1}^{T} E\left(x_{i s} u_{i t}\right)$ as $E\left(x_{i t} u_{i t}\right)=0$. Let $\hat{u}_{i s}=y_{i t}-x_{i t}^{\prime} \hat{\alpha}_{\hat{G}_{k}}-\hat{\mu}_{i}$ and $\hat{\mu}_{i}=\frac{1}{T} \sum_{t=1}^{T}\left(y_{i t}-x_{i t}^{\prime} \hat{\alpha}_{\hat{G}_{k}}\right)$ for all $i \in \hat{G}_{k} \cdot{ }^{11}$ We propose to estimate $b_{k N T}$ by

$$
\hat{b}_{k N T}=\hat{\Phi}_{k}^{-1} \hat{\mathbb{B}}_{k N T}
$$

where

$$
\hat{\Phi}_{k}=\frac{1}{\hat{N}_{k} T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime} \text { and } \hat{\mathbb{B}}_{k N T}=-\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in \hat{G}_{k}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) x_{i s} \hat{u}_{i t} .
$$

Here $k_{M_{T}}(t, s)=k_{M_{T}}^{0}(|t-s|)$ and $k_{M_{T}}^{0}(u)$ denotes the Bartlett kernel:

$$
k_{M_{T}}^{0}(u)=\left(1-|u| / M_{T}\right) \mathbf{1}\left\{|u| \leq M_{T}\right\} .
$$

Note that we allow dynamic misspecification here. If one is sure that the model is dynamically correctly specified in the sense that $E\left(u_{i t} \mid \mathcal{F}_{i, t-1}\right)=0$ where $F_{i, t-1}=\sigma\left(u_{i, t-1}, u_{i, t-2}, \ldots ; x_{i t}, x_{i t-1}, \ldots\right)$, one can use the one-sided kernel: $k_{M_{T}}(t, s)=k_{M_{T}}^{1}(s-t)$, where

$$
k_{M_{T}}^{1}(u)=\left(1-u / M_{T}\right) \mathbf{1}\left\{0 \leq u \leq M_{T}\right\} .
$$

Other choices of kernels are possible. So the bias-corrected PLS C-Lasso estimator is given by

$$
\hat{\alpha}_{k}^{(c)}=\hat{\alpha}_{k}-\frac{1}{\sqrt{\hat{N}_{k} T}} \hat{\Phi}_{k}^{-1} \hat{\mathbb{B}}_{k N T} .
$$

Similarly, we can obtain the bias-corrected estimator for the post-Lasso estimator $\hat{\alpha}_{\hat{G}_{k}}$.
Let $\|A\|_{a}=\left\{E\|A\|^{a}\right\}^{1 / a}$ for any $a \geq 1$. Let $C$ denote a generic positive constant that does not depend on $N$ and $T$. We add the following assumption.

ASSUMPTION D1. (i) For each $i=1, \ldots, N,\left\{\left(x_{i t}, u_{i t}\right): t=1,2, \ldots\right\}$ is strong mixing with mixing coefficients $\left\{\alpha_{i}(\cdot)\right\}$ such that $\alpha_{i}(\tau) \leq c_{\alpha, i} \rho^{\tau}$ for some $c_{\alpha, i}<\infty$ and $\rho \in(0,1) \cdot \frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} c_{\alpha, i}^{(2 q-1) /(2 q)}=O(1)$.
(ii) Let $x_{i} \equiv\left(x_{i 1}, \ldots, x_{i T}\right)^{\prime}$ and $u_{i} \equiv\left(u_{i 1}, \ldots, u_{i T}\right)^{\prime} .\left(x_{i}, u_{i}\right)$ are independent across $i \in G_{k}^{0}$ where $k=1, \ldots, K_{0}$.
(iii) $\max _{i, t} E\left\|x_{i t}\right\|^{4 q}<C<\infty$ and $\max _{i, t} E\left\|u_{i t}\right\|^{4 q}<C<\infty$ for some $q \geq 1$.
(iv) $\operatorname{As}(N, T) \rightarrow \infty, M_{T} \rightarrow \infty, M_{T}^{2} / T \rightarrow 0, M_{T}^{2} N_{k} / T^{3} \rightarrow 0$, and $N_{k}^{-1 / 2} T^{1 / 2} \sum_{i \in G_{k}^{0}} \alpha_{i}\left(M_{T}\right)^{(2 q-1) /(2 q)}$ $\rightarrow 0$ for each $k=1, \ldots, K_{0}$.

Assumption D1(i) assumes the usual mixing condition. D1(ii) assumes cross sectional independence to simplify the proof which can be relaxed at the cost of lengthy arguments. D1(iii) assumes moment conditions. The second condition in $\mathrm{D} 1(\mathrm{iv})$ can be easily ensured under D 1 (i) because for any $M_{T} \gg$ $-\frac{2 q}{(2 q-1) \ln q} \ln \left(N^{1 / 2} T^{1 / 2}\right)\left(\right.$ e.g., $M_{T}=\left(\ln \left(N^{1 / 2} T^{1 / 2}\right)\right)^{1+\epsilon}$ for some $\epsilon>0$ ), we have

$$
\begin{aligned}
N_{k}^{-1 / 2} T^{1 / 2} \sum_{i \in G_{k}^{0}} \alpha_{i}\left(M_{T}\right)^{(2 q-1) /(2 q)} & \leq\left(N_{k}^{-1} \sum_{i \in G_{k}^{0}} c_{\alpha, i}^{(2 q-1) /(2 q)}\right) N_{k}^{1 / 2} T^{1 / 2} \rho^{M_{T}(2 q-1) /(2 q)} \\
& =O(1) \exp \left(\ln \left(N_{k}^{1 / 2} T^{1 / 2}\right)+\frac{(2 q-1) M_{T}}{2 q} \ln \rho\right) \rightarrow 0 .
\end{aligned}
$$

[^10]The first three requirements in D1(iv) can be easily satisfied too. For example, if $N_{k} \propto T^{a}$ for some $a<3$, it suffices to set $M_{T} \propto T^{1 / b}$ for some $b>\max \{2,2 /(3-a)\}$.

Proposition D. 1 Suppose that the conditions in Theorem 2.4 hold. Suppose Assumption D1 holds. Then $\hat{\Phi}_{k}^{-1} \hat{B}_{k N T}-\bar{\Phi}_{k}^{-1} B_{k N T}=o_{P}(1)$.

Proof. Noting that $\hat{\Phi}_{k}^{-1} \hat{B}_{k N T}-\bar{\Phi}_{k}^{-1} B_{k N T}=\left(\hat{\Phi}_{k}^{-1}-\bar{\Phi}_{k}^{-1}\right) B_{k N T}+\left(\hat{\Phi}_{k}^{-1}-\bar{\Phi}_{k}^{-1}\right)\left(\hat{\mathbb{B}}_{k N T}-\mathbb{B}_{k N T}\right)+$ $\bar{A}_{k}^{-1}\left(\hat{\mathbb{B}}_{k N T}-\mathbb{B}_{k N T}\right), \bar{\Phi}_{k}^{-1}=O(1)$, and $B_{k N T}=O\left(\sqrt{N_{k} / T}\right)$, it suffices to show that (i) $\hat{\Phi}_{k}-\bar{\Phi}_{k}=$ $o_{P}\left(\min \left(1, \sqrt{T / N_{k}}\right)\right)$ and (ii) $\hat{B}_{k N T}-B_{k N T}=o_{P}(1)$.

We first prove (i). Note that

$$
\begin{aligned}
\hat{\Phi}_{k}-\bar{\Phi}_{k} & =\frac{1}{\hat{N}_{k} T} \sum_{i \in \hat{G}_{k}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}-\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime} \\
& =\frac{1}{\hat{N}_{k} T}\left(\sum_{i \in \hat{G}_{k}}-\sum_{i \in G_{k}^{0}}\right) \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime}+\frac{N_{k}-\hat{N}_{k}}{\hat{N}_{k} N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \tilde{x}_{i t} \tilde{x}_{i t}^{\prime} \\
& \equiv \Phi_{k, 1}+\Phi_{k, 2}, \text { say. }
\end{aligned}
$$

By Corollary 2.3, we can readily show that $\Phi_{k, 2}=O_{P}\left(N_{k}^{-1}\right)=o_{P}\left(\min \left(1, \sqrt{T / N_{k}}\right)\right)$. Let $\nu_{N T}=$ $\min \left(1, \sqrt{T / N_{k}}\right)$. For any $\epsilon>0$, we have by the proof of Theorem $2.2, P\left(\left\|\Phi_{k, 1}\right\| \geq \nu_{N T} \epsilon\right) \leq P\left(\hat{F}_{k N T}\right)+$ $P\left(\hat{E}_{k N T}\right)=o(1)$. It follows that $\hat{\Phi}_{k}-\bar{\Phi}_{k}=o_{P}\left(\min \left(1, \sqrt{T / N_{k}}\right)\right)$.

We now prove (ii). We first make the following decomposition:

$$
\begin{aligned}
\mathbb{B}_{k N T}-\hat{\mathbb{B}}_{k N T}= & \frac{1}{\hat{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in \hat{G}_{k}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) x_{i s} \hat{u}_{i t}-\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \mathbb{E}\left(x_{i s} u_{i t}\right) \\
= & \frac{1}{\hat{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) x_{i s} \hat{u}_{i t}-\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \mathbb{E}\left(x_{i s} u_{i t}\right)+o_{P}(1) \\
= & \frac{1}{\hat{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) x_{i s}\left(\hat{u}_{i t}-u_{i t}\right) \\
& +\frac{1}{\hat{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s)\left[x_{i s} u_{i t}-\mathbb{E}\left(x_{i s} u_{i t}\right)\right] \\
& +\frac{N_{k}^{-1 / 2}-\hat{N}_{k}^{-1 / 2}}{T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \mathbb{E}\left(x_{i s} u_{i t}\right) \\
& +\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T}\left[1-k_{M_{T}}(t, s)\right] \mathbb{E}\left(x_{i s} u_{i t}\right)+o_{P}(1) \\
\equiv & \hat{B}_{k N T, 1}+\hat{B}_{k N T, 2}+\hat{B}_{k N T, 3}+\hat{B}_{k N T, 4}+o_{P}(1), \text { say, }
\end{aligned}
$$

where the $o_{P}(1)$ term arises due to the replacement of $\hat{G}_{k}$ by $G_{k}^{0}$ and this can be easily justified by using the uniform classification consistency result and arguments as used in the proof of Theorems 2.5 and 3.5. We prove (ii) by demonstrating that $\hat{B}_{k N T, s}=o_{P}(1)$ for $s=1,2,3$, and 4 .

We first study $\hat{B}_{k N T, 1}$. Noting that $\hat{u}_{i t}=y_{i t}-x_{i t}^{\prime} \hat{\alpha}_{\hat{G}_{k}}-\hat{\mu}_{i}=y_{i t}-x_{i t}^{\prime} \hat{\alpha}_{\hat{G}_{k}}-\frac{1}{T} \sum_{t=1}^{T}\left(y_{i t}-x_{i t}^{\prime} \hat{\alpha}_{\hat{G}_{k}}\right)$ and $y_{i t}=x_{i t}^{\prime} \alpha_{k}^{0}+\mu_{i}+u_{i t}$ for $i \in G_{k}^{0}$, we have that for $i \in G_{k}^{0}$

$$
\begin{aligned}
\hat{u}_{i t}-u_{i t} & =y_{i t}-x_{i t}^{\prime} \hat{\alpha}_{\hat{G}_{k}}-\frac{1}{T} \sum_{t=1}^{T}\left(y_{i t}-x_{i t}^{\prime} \hat{\alpha}_{\hat{G}_{k}}\right)-u_{i t} \\
& =\left[x_{i t}^{\prime}\left(\alpha_{k}^{0}-\hat{\alpha}_{\hat{G}_{k}}\right)-\frac{1}{T} \sum_{t=1}^{T} x_{i t}^{\prime}\left(\alpha_{k}^{0}-\hat{\alpha}_{\hat{G}_{k}}\right)\right]-\frac{1}{T} \sum_{t=1}^{T} u_{i t} \\
& =\tilde{x}_{i t}^{\prime}\left(\alpha_{k}^{0}-\hat{\alpha}_{\hat{G}_{k}}\right)-\bar{u}_{i}
\end{aligned}
$$

where $\bar{u}_{i}=\frac{1}{T} \sum_{t=1}^{T} u_{i t}$. Then

$$
\begin{aligned}
\hat{B}_{k N T, 1} & =\frac{1}{\hat{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) x_{i s} \tilde{x}_{i t}^{\prime}\left(\alpha_{k}^{0}-\hat{\alpha}_{\hat{G}_{k}}\right)-\frac{1}{\hat{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) x_{i s} \bar{u}_{i} \\
& \equiv B_{k N T, 1}(1)-B_{k N T, 1}(2), \text { say. }
\end{aligned}
$$

In view of the fact that $\hat{\alpha}_{\hat{G}_{k}}-\alpha_{k}^{0}=O_{P}\left(\left(N_{k} T\right)^{-1 / 2}+T^{-1}\right)$ and $\hat{N}_{k}=N_{k}\left(1+o_{P}(1)\right)$, we have

$$
\begin{aligned}
\left\|B_{k N T, 1}(1)\right\| & =\frac{1}{\hat{N}_{k}^{1 / 2} T^{3 / 2}}\left\|\sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) x_{i s} \tilde{x}_{i t}^{\prime}\left(\alpha_{k}^{0}-\hat{\alpha}_{\hat{G}_{k}}\right)\right\| \\
& \leq \frac{N_{k} T^{1 / 2}}{\hat{N}_{k}^{1 / 2}}\left\|\alpha_{k}^{0}-\hat{\alpha}_{\hat{G}_{k}}\right\| \frac{1}{N_{k} T^{2}} \sum_{i \in G_{k}^{0}|s-t| \leq M_{T}}\left\|x_{i s} \tilde{x}_{i t}^{\prime}\right\| \\
& =N_{k}^{1 / 2} T^{1 / 2} O_{P}\left(\left(N_{k} T\right)^{-1 / 2}+T^{-1}\right) O_{P}\left(M_{T} / T\right) \\
& =O_{P}\left(1+N_{k}^{1 / 2} T^{-1 / 2}\right) O_{P}\left(M_{T} / T\right)=o_{P}(1)
\end{aligned}
$$

where we use the fact that $\frac{1}{N_{k} T^{2}} \sum_{i \in G_{k}^{0}} \sum_{|s-t| \leq M_{T}}\left\|x_{i s} \tilde{x}_{i t}^{\prime}\right\|=O_{P}\left(M_{T} / T\right)$ by moment calculation and Markov inequality. Let $\bar{B}_{k N T, 1}(2) \equiv \frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \omega^{\prime} x_{i s} \bar{u}_{i}$ where $\omega$ is any $p \times 1$ nonrandom vector such that $\|\omega\|=1$. Then by Assumptions D1(i), (iii) and (iv),

$$
\begin{aligned}
\left|\mathbb{E}\left[\bar{B}_{k N T, 1}(2)\right]\right| & \leq \frac{1}{N_{k}^{1 / 2} T^{5 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \sum_{r=1}^{T} k_{M_{T}}(t, s)\left|\mathbb{E}\left(\omega^{\prime} x_{i s} u_{i r}\right)\right| \\
& \leq \frac{8}{N_{k}^{1 / 2} T^{5 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \sum_{r=1}^{T} k_{M_{T}}(t, s)\left\|\omega^{\prime} x_{i s}\right\|_{4 q}\left\|u_{i r}\right\|_{4 q} \alpha_{i}(|r-s|)^{(2 q-1) /(2 q)} \\
& \leq \frac{C N_{k}^{1 / 2}}{T^{3 / 2}}\left\{\frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} c_{\alpha, i}^{(2 q-1) /(2 q)}\right\}\left\{\frac{1}{T} \sum_{t, s, r:|s-t| \leq M_{T}} \rho^{|r-s|(2 q-1) /(2 q)}\right\} \\
& =N_{k}^{1 / 2} T^{-3 / 2} O(1) O\left(M_{T}\right)=O\left(M_{T} N_{k}^{1 / 2} T^{-3 / 2}\right)=o(1) .
\end{aligned}
$$

Similarly, by Assumptions D1(i)-(iv),

$$
\begin{aligned}
\operatorname{Var}\left(\bar{B}_{k N T, 1}(2)\right) & =\frac{1}{N_{k} T^{5}} \sum_{i \in G_{k}^{0}} \operatorname{Var}\left(\sum_{s=1}^{T} \sum_{t=1}^{T} \sum_{r=1}^{T} k_{M_{T}}(t, s) \omega^{\prime} x_{i s} u_{i r}\right) \\
& \leq \frac{1}{N_{k} T^{5}} \sum_{i \in G_{k}^{0}} \mathbb{E}\left[\left(\sum_{s=1}^{T} \sum_{t=1}^{T} \sum_{r=1}^{T} k_{M_{T}}(t, s) \omega^{\prime} x_{i s} u_{i r}\right)^{2}\right] \\
& =\frac{1}{N_{k} T^{5}} \sum_{i \in G_{k}^{0}} \sum_{1 \leq t_{1}, t_{2}, \ldots, t_{6} \leq T} k_{M_{T}}\left(t_{1}, t_{2}\right) k_{M_{T}}\left(t_{4}, t_{5}\right) \mathbb{E}\left(\omega^{\prime} x_{i t_{2}} u_{i t_{3}} \omega^{\prime} x_{i t_{5}} u_{i t_{6}}\right) \\
& \leq \frac{1}{N_{k} T^{5}} \sum_{i \in G_{k}^{0}} \sum_{\substack{1 \leq t_{1}, t_{2}, \ldots, t_{6} \leq T \\
\left|t_{1}-t_{2}\right| \leq M_{T},\left|t_{4}-t_{5}\right| \leq M_{T}}}\left|\mathbb{E}\left(\omega^{\prime} x_{i t_{2}} u_{i t_{3}} \omega^{\prime} x_{i t_{5}} u_{i t_{6}}\right)\right| \\
& =O\left(M_{T}^{2} / T\right)=o(1)
\end{aligned}
$$

Consequently, $\bar{B}_{k N T, 1}(2)=o_{P}(1)$. This, in conjunction with Corollary 2.3, implies that $B_{k N T, 1}(2)=$ $o_{P}(1)$ as $\omega$ is arbitrary. Thus we have shown that $\hat{B}_{k N T, 1}=o_{P}(1)$.

For $\hat{B}_{k N T, 2}$, note that $\hat{B}_{k N T, 2}=\bar{B}_{k N T, 2} N_{k}^{1 / 2} / \tilde{N}_{k}^{1 / 2}=b_{k N T, 2}\left(1+o_{P}(1)\right)$, where $\bar{B}_{k N T, 2}=\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}}$ $\sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s)\left[x_{i s} u_{i t}-E\left(x_{i s} u_{i t}\right)\right]$. By construction $E\left(\bar{B}_{k N T, 2}\right)=0$. By Assumptions D1(ii)-(iii) and Jensen inequality,

$$
\begin{aligned}
\operatorname{Var}\left(\omega^{\prime} \bar{B}_{k N T, 2}\right) & =\frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \operatorname{Var}\left[\sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \omega^{\prime}\left[x_{i s} u_{i t}-\mathbb{E}\left(x_{i s} \Delta u_{i t}\right)\right]\right] \\
& \leq \frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \sum_{r=1}^{T} \sum_{l=1}^{T} k_{M_{T}}(t, s) k_{M_{T}}(r, l) \mathbb{E}\left(\omega^{\prime} x_{i s} u_{i t} u_{i r} x_{i l} \omega\right) \\
& \leq \frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \sum_{\|s-t\| \leq M_{T}} \sum_{\|r-l\| \leq M_{T}}\left|\mathbb{E}\left(\omega^{\prime} x_{i s} u_{i t} u_{i r} x_{i l} \omega\right)\right|=O\left(M_{T}^{2} / T\right)=o(1)
\end{aligned}
$$

where the last equality follows from the fact that $\left\|\mathbb{E}\left(\omega^{\prime} x_{i s} u_{i t} u_{i r} x_{i l} \omega\right)\right\| \leq \max _{i, s, t}\left\|x_{i s} u_{i t}\right\|_{2}^{2} \leq \max _{i, t}\left\|x_{i t}\right\|_{4}^{2}$ $\times \max _{i, t}\left\|u_{i t}\right\|_{4}^{2}<C<\infty$ by Assumption D1(iii). Then $\bar{B}_{k N T, 2}=o_{P}(1)$ by Chebyshev inequality and thus $\hat{B}_{k N T, 2}=o_{P}(1)$.

By Corollary 2.3 and Davydov inequality,

$$
\begin{aligned}
\left\|\hat{B}_{k N T, 3}\right\| & =\frac{\left|N_{k}^{-1}-\tilde{N}_{k}^{-1}\right|}{T^{3 / 2}\left(N_{k}^{-1 / 2}+\tilde{N}_{k}^{-1 / 2}\right)}\left\|\sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \mathbb{E}\left(x_{i s} u_{i t}\right)\right\| \\
& \leq \frac{\left|\tilde{N}_{k}-N_{k}\right|}{T^{1 / 2} \tilde{N}_{k}\left(N_{k}^{-1 / 2}+\tilde{N}_{k}^{-1 / 2}\right)}\left\{\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{\|s-t\| \leq M_{T}}\left\|\mathbb{E}\left(x_{i s} u_{i t}\right)\right\|\right\} \\
& =o_{P}\left(N_{k}^{-1 / 2} T^{-1 / 2}\right) O(1)=o_{P}(1) .
\end{aligned}
$$

By Assumptions D1(i)-(iv) and Davydov inequality,

$$
\begin{aligned}
\left\|\hat{B}_{k N T, 4}\right\| & =\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T}\left[1-k_{M_{T}}(t, s)\right] \mathbb{E}\left(x_{i s} u_{i t}\right) \\
& =\left\|\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T}\left[1-k_{M_{T}}(t, s)\right] \mathbb{E}\left(x_{i s} u_{i t}\right)\right\| \\
& \leq \frac{8}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{\|s-t\|>M_{T}} \alpha_{i}(|s-t|)^{(2 q-1) /(2 q)}\left\|x_{i s}\right\|_{4 q}\left\|u_{i t}\right\|_{4 q} \\
& \leq C N_{k}^{-1 / 2} T^{1 / 2} \sum_{i \in G_{k}^{0}} \alpha_{i}\left(M_{T}\right)^{(2 q-1) /(2 q)}=o(1)
\end{aligned}
$$

This completes the proof of the proposition.
With the above result, we can readily show that

$$
\begin{aligned}
\sqrt{N_{k} T}\left(\hat{\alpha}_{k}^{(c)}-\alpha_{k}^{0}\right)= & {\left[\sqrt{N_{k} T}\left(\hat{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T}\right]+\left(N_{k} / \hat{N}_{k}\right)^{1 / 2}\left[\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T}-\hat{\Phi}_{k}^{-1} \hat{\mathbb{B}}_{k N T}\right] } \\
& +\left[1-\left(N_{k} / \hat{N}_{k}\right)^{1 / 2}\right] \bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T} \\
= & {\left[\sqrt{N_{k} T}\left(\hat{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T}\right]+o_{P}(1)+o_{P}\left(N_{k}^{-1}\right) O\left(\left(N_{K} / T\right)^{1 / 2}\right) } \\
= & {\left[\sqrt{N_{k} T}\left(\hat{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{\Phi}_{k}^{-1} \mathbb{B}_{k N T}\right]+o_{P}(1) }
\end{aligned}
$$

That is, $\sqrt{N_{k} T}\left(\hat{\alpha}_{k}^{(c)}-\alpha_{k}^{0}\right)$ has the desired limiting distribution that centers around 0.

## D. 2 Bias Correction for the PGMM C-Lasso Estimator

The bias correction for the PGMM C-Lasso estimator in dynamic panel data models can be done analogously. For simplicity we focus on the case where $W_{i N T}=I_{d}$ for all $i$. Recall from Theorem 3.4 and the remark regarding Assumption B3(iii) (see (3.6) in particular) that

$$
\sqrt{N_{k} T}\left(\tilde{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{A}_{k}^{-1} B_{k N T} \xrightarrow{D} N\left(0, A_{k}^{-1} C_{k} A_{k}^{-1}\right) \text { for } k=1, \ldots, K_{0}
$$

where $\bar{A}_{k} \equiv \frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} \bar{Q}_{i, z \Delta x}^{\prime} \bar{Q}_{i, z \Delta x}$ and $B_{k N T}=\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} E\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)$. Based on (3.6), in order to verify Assumption B3(iii) we also need to show

$$
\begin{align*}
V_{k N T} & =\frac{1}{N_{k}^{1 / 2} T^{1 / 2}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \bar{Q}_{i, z \Delta x}^{\prime} z_{i t} \Delta u_{i t} \xrightarrow{D} N\left(0, C_{k}\right), \text { and }  \tag{D.1}\\
R_{k N T} & =\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T}\left\{\left[\Delta x_{i s} z_{i s}^{\prime}-\mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime}\right)\right] z_{i t} \Delta u_{i t}-\mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)\right\}=o_{P}(1 \gamma \mathrm{D} .2) \tag{1〕D.2}
\end{align*}
$$

The first part is ensured by a version of CLT. Below we first propose an estimate of the bias $\bar{A}_{k}^{-1} B_{k N T}$ and then demonstrate (D.2).

To correct the bias, we propose to obtain consistent estimates of $\bar{A}_{k}$ and $B_{k N T}$ respectively by

$$
\tilde{A}_{k}=\frac{1}{\tilde{N}_{k}} \sum_{i \in \tilde{G}_{k}} \tilde{Q}_{i, z \Delta x}^{\prime} \tilde{Q}_{i, z \Delta x}, \text { and } \tilde{B}_{k N T}=\frac{1}{\tilde{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in \tilde{G}_{k}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta \tilde{u}_{i t}
$$

where $\Delta \tilde{u}_{i t}=\Delta y_{i t}-\tilde{\alpha}_{\tilde{G}_{k}}^{\prime} \Delta x_{i t}$ for all $i \in \tilde{G}_{k},{ }^{12} k_{M_{T}}(t, s)$ is defined as above: $k_{M_{T}}(t, s)=k_{M_{T}}^{0}(|t-s|)$ and $k_{M_{T}}^{0}(u)$ denotes the Bartlett kernel: $k_{M_{T}}^{0}(u)=\left(1-|u| / M_{T}\right) 1\left\{|u| \leq M_{T}\right\}$. Note that we also allow dynamic misspecification here. If one is sure that the model is dynamically correctly specified in the sense that $E\left(\Delta u_{i t} \mid \mathcal{F}_{i, t-1}\right)=0$ where $F_{i, t-1}=\sigma\left(\Delta u_{i, t-1}, \Delta x_{i t-1}, z_{i t} ; \Delta u_{i, t-2}, \Delta x_{i t-2}, z_{i, t-1} ; \ldots\right)$, one can use the one-sided kernel: $k_{M_{T}}(t, s)=k_{M_{T}}^{1}(s-t)$, where $k_{M_{T}}^{1}(u)=\left(1-u / M_{T}\right) 1\left\{0 \leq u \leq M_{T}\right\}$. The bias-corrected C-Lasso estimator of $\alpha_{k}^{0}$ would be

$$
\tilde{\alpha}_{k}^{(c)}=\tilde{\alpha}_{k}-\frac{1}{\sqrt{\tilde{N}_{k} T}} \tilde{A}_{k}^{-1} \tilde{B}_{k N T}
$$

Note that Theorem 3.5 indicates that there is no need to consider bias correction for the post Lasso estimator $\tilde{\alpha}_{\tilde{G}_{k}}$.

We add the following assumption.
ASSUMPTION D2. (i) For each $i=1, \ldots, N,\left\{\left(\Delta x_{i t}, z_{i t}, \Delta u_{i t}\right): t=1,2, \ldots\right\}$ is strong mixing with mixing coefficients $\left\{\alpha_{i}(\cdot)\right\}$. In addition, $\alpha_{i}(\tau) \leq c_{\alpha, i} \rho^{\tau}$ for some $c_{\alpha, i}<\infty$ and $\rho \in(0,1)$ where $\frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} c_{\alpha, i}^{(2 q-1) /(2 q)}=O(1)$ and $\frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} c_{\alpha, i}^{(q-1) / q}=O(1)$.
(ii) Let $x_{i} \equiv\left(x_{i 1}, \ldots, x_{i T}\right)^{\prime}$ and $u_{i} \equiv\left(u_{i 1}, \ldots, u_{i T}\right)^{\prime} .\left(x_{i}, u_{i}\right)$ are independent across $i \in G_{k}^{0}$ where $k=1, \ldots, K_{0}$.
(iii) $\max _{i, t} E\left\|\Delta x_{i t} z_{i t}^{\prime}\right\|^{4 q}<C<\infty$ and $\max _{i, t} E\left\|z_{i t} \Delta u_{i t}\right\|^{4 q}<C<\infty$ for some $q>1$.
(iv) As $(N, T) \rightarrow \infty, M_{T} \rightarrow \infty, M_{T}^{2} / T \rightarrow 0$ and $N_{k}^{-1 / 2} T^{1 / 2} \sum_{i \in G_{k}^{0}} \alpha_{i}\left(M_{T}\right)^{(2 q-1) /(2 q)} \rightarrow 0$ for each $k=1, \ldots, K_{0}$.

Assumptions D2(i)-(iv) parallel D1(i)-(iv). The major difference is that we don't need $M_{T}^{2} N_{k} / T^{3} \rightarrow 0$ in D2(iv) but require $q>1$ in D2(iii).

Proposition D. 2 Suppose that the conditions of Theorem 3.4 hold. Suppose Assumption D2 holds. Then $\tilde{A}_{k}^{-1} \tilde{B}_{k N T}-\bar{A}_{k}^{-1} B_{k N T}=o_{P}(1)$.

Proof. Noting that $\tilde{A}_{k}^{-1} \tilde{B}_{k N T}-\bar{A}_{k}^{-1} B_{k N T}=\left(\tilde{A}_{k}^{-1}-\bar{A}_{k}^{-1}\right) B_{k N T}+\left(\tilde{A}_{k}^{-1}-\bar{A}_{k}^{-1}\right)\left(\tilde{B}_{k N T}-B_{k N T}\right)+$ $\bar{A}_{k}^{-1}\left(\tilde{B}_{k N T}-B_{k N T}\right), \bar{A}_{k}^{-1}=O(1)$, and $B_{k N T}=O\left(\sqrt{N_{k} / T}\right)$, it suffices to show that (i) $\tilde{A}_{k}-\bar{A}_{k}=$ $o_{P}\left(\min \left(1, \sqrt{T / N_{k}}\right)\right)$ and (ii) $\tilde{B}_{k N T}-B_{k N T}=o_{P}(1)$.

We first prove (i). Note that

$$
\begin{aligned}
\tilde{A}_{k}-\bar{A}_{k} & =\frac{1}{\tilde{N}_{k}} \sum_{i \in \tilde{G}_{k}} \tilde{Q}_{i, z \Delta x}^{\prime} \tilde{Q}_{i, z \Delta x}-\frac{1}{N_{k}} \sum_{i \in G_{k}^{0}} \tilde{Q}_{i, z \Delta x}^{\prime} \tilde{Q}_{i, z \Delta x} \\
& =\frac{1}{\tilde{N}_{k}}\left(\sum_{i \in \tilde{G}_{k}}-\sum_{i \in G_{k}^{0}}\right) \tilde{Q}_{i, z \Delta x}^{\prime} \tilde{Q}_{i, z \Delta x}+\frac{N_{k}-\tilde{N}_{k}}{\tilde{N}_{k} N_{k}} \sum_{i \in G_{k}^{0}} \tilde{Q}_{i, z \Delta x}^{\prime} \tilde{Q}_{i, z \Delta x} \\
& \equiv A_{k, 1}+A_{k, 2}, \text { say. }
\end{aligned}
$$

By Corollary 3.3, $A_{k, 2}=O_{P}\left(N_{k}^{-1}\right)=o_{P}\left(\min \left(1, \sqrt{T / N_{k}}\right)\right)$. Let $\nu_{N T}=\min \left(1, \sqrt{T / N_{k}}\right)$. For any $\epsilon>0$, we have by the proof of Theorem 3.2, $P\left(\left\|A_{k, 1}\right\| \geq \nu_{N T} \epsilon\right) \leq P\left(\tilde{F}_{k N T}\right)+P\left(\tilde{E}_{k N T}\right)=o(1)$. It follows that $\tilde{A}_{k}-\bar{A}_{k}=o_{P}\left(\min \left(1, \sqrt{T / N_{k}}\right)\right)$.

[^11]Now we prove (ii). We make the following decomposition:

$$
\begin{aligned}
& \tilde{B}_{k N T}-B_{k N T} \\
= & \frac{1}{\tilde{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in \tilde{G}_{k}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta \tilde{u}_{i t}-\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right) \\
= & \frac{1}{\tilde{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta \tilde{u}_{i t}-\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)+o_{P}(1) \\
= & \frac{1}{\tilde{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \Delta x_{i s} z_{i s}^{\prime} z_{i t}\left(\Delta \tilde{u}_{i t}-\Delta u_{i t}\right) \\
& +\frac{1}{\tilde{N}_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s)\left[\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}-\mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)\right] \\
& +\frac{N_{k}^{-1 / 2}-\tilde{N}_{k}^{-1 / 2}}{T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right) \\
& +\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T}\left[1-k_{M_{T}}(t, s)\right] \mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)+o_{P}(1) \\
\equiv & B_{k N T, 1}+B_{k N T, 2}+B_{k N T, 3}+B_{k N T, 4}+o_{P}(1), \text { say, }
\end{aligned}
$$

where the $o_{P}(1)$ term arises due to the replacement of $\tilde{G}_{k}$ by $G_{k}^{0}$ and this can be easily justified by using the uniform classification consistency result and arguments as used in the proof of Theorems 2.5 and 3.5. We prove (ii) by demonstrating that $B_{k N T, s}=o_{P}(1)$ for $s=1,2,3,4$.

First, noting that $\Delta \tilde{u}_{i t}-\Delta u_{i t}=\left(\alpha_{k}^{0}-\tilde{\alpha}_{\tilde{G}_{k}}\right)^{\prime} \Delta x_{i t}, \tilde{\alpha}_{\tilde{G}_{k}}-\alpha_{k}^{0}=O_{P}\left(\left(N_{k} T\right)^{-1 / 2}\right)$, and that $N_{k} / \tilde{N}_{k}=$ $1+o_{P}(1)$, we have

$$
\begin{aligned}
\left\|B_{k N T, 1}\right\| & =\frac{1}{\tilde{N}_{k}^{1 / 2} T^{3 / 2}}\left\|\sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \Delta x_{i s} z_{i s}^{\prime} z_{i t}\left(\Delta x_{i t}\right)^{\prime}\left(\alpha_{k}^{0}-\tilde{\alpha}_{\tilde{G}_{k}}\right)\right\| \\
& \leq\left(\tilde{N}_{k} T\right)^{1 / 2}\left\|\alpha_{k}^{0}-\tilde{\alpha}_{\tilde{G}_{k}}\right\| \frac{N_{k}}{\tilde{N}_{k}} \frac{1}{N_{k} T^{2}} \sum_{i \in G_{k}^{0}} \sum_{\|s-t\| \leq M_{T}}\left\|\Delta x_{i s} z_{i s}^{\prime} z_{i t}\left(\Delta x_{i t}\right)^{\prime}\right\| \\
& =O_{P}(1) b_{k N T, 1}
\end{aligned}
$$

where $b_{k N T, 1}=\frac{1}{N_{k} T^{2}} \sum_{i \in G_{k}^{0}} \sum_{\|s-t\| \leq M_{T}}^{T}\left\|\Delta x_{i s} z_{i s}^{\prime} z_{i t}\left(\Delta x_{i t}\right)^{\prime}\right\|$. By Markov inequality, $b_{k N T, 1}=O_{P}\left(M_{T} / T\right)$. It follows that $\left\|B_{k N T, 1}\right\|=O_{P}\left(M_{T} / T\right)=o_{P}(1)$ under Assumption D2(iv).

For $B_{k N T, 2}$, note that $B_{k N T, 2}=b_{k N T, 2} N_{k}^{1 / 2} / \tilde{N}_{k}^{1 / 2}=b_{k N T, 2}\left(1+o_{P}(1)\right)$, where

$$
b_{k N T, 2}=\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s)\left[\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}-\mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)\right]
$$

Let $\omega$ be any $p \times 1$ nonrandom vector such that $\|\omega\|=1$. Then $E\left(\omega^{\prime} b_{k N T, 2}\right)=0$. By Assumptions

D2(ii)-(iv) and Jensen inequality,

$$
\begin{aligned}
& \operatorname{Var}\left(\omega^{\prime} b_{k N T, 2}\right) \\
= & \frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \operatorname{Var}\left[\sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \omega^{\prime}\left\{\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}-\mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)\right\}\right] \\
\leq & \frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} \sum_{r=1}^{T} \sum_{l=1}^{T} k_{M_{T}}(t, s) k_{M_{T}}(r, l) \omega^{\prime} \mathbb{E}\left[\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t} \Delta x_{i l} z_{i l}^{\prime} z_{i r} \Delta u_{i r}\right] \omega \\
\leq & \frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \sum_{\|s-t\| \leq M_{T}} \sum_{\|r-l\| \leq M_{T}}\left\|\mathbb{E}\left[\omega^{\prime} \Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t} \Delta x_{i l} z_{i l}^{\prime} z_{i r} \Delta u_{i r} \omega\right]\right\| \\
= & O\left(M_{T}^{2} / T\right)=o(1)
\end{aligned}
$$

where the last equality follows from the fact that $\left\|\mathbb{E}\left[\omega^{\prime} \Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t} \Delta x_{i l} z_{i l}^{\prime} z_{i r} \Delta u_{i r} \omega\right]\right\| \leq \max _{i, s}\left\{\mathbb{E}\left\|\Delta x_{i s} z_{i s}^{\prime}\right\|^{4}\right\}^{1 / 2}$ $\times \max _{i, t}\left\{\mathbb{E}\left\|z_{i t} \Delta u_{i t}\right\|^{4}\right\}^{1 / 2}<C<\infty$ by Assumption D2(iii). It follows that $B_{k N T, 2}=o_{P}(1)$.

By Corollary 3.3 and Davydov inequality,

$$
\begin{aligned}
\left\|B_{k N T, 3}\right\| & =\frac{\left|N_{k}^{-1}-\tilde{N}_{k}^{-1}\right|}{T^{3 / 2}\left(N_{k}^{-1 / 2}+\tilde{N}_{k}^{-1 / 2}\right)}\left\|\sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T} k_{M_{T}}(t, s) \mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)\right\| \\
& \leq \frac{\left|\tilde{N}_{k}-N_{k}\right|}{T^{1 / 2} \tilde{N}_{k}\left(N_{k}^{-1 / 2}+\tilde{N}_{k}^{-1 / 2}\right)}\left\{\frac{1}{N_{k} T} \sum_{i \in G_{k}^{0}} \sum_{\|s-t\| \leq M_{T}}\left\|\mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)\right\|\right\} \\
& =o_{P}\left(N_{k}^{-1 / 2} T^{-1 / 2}\right) O(1)=o_{P}(1) .
\end{aligned}
$$

By Assumptions D2(i)-(iii) and Davydov inequality,

$$
\begin{aligned}
\left\|B_{k N T, 4}\right\| & =\left\|\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T}\left[1-k_{M_{T}}(t, s)\right] \mathbb{E}\left(\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right)\right\| \\
& \leq \frac{8}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{\|s-t\|>M_{T}} \alpha_{i}(|s-t|)^{(2 q-1) /(2 q)}\left\|\Delta x_{i s} z_{i s}^{\prime}\right\|_{4 q}\left\|z_{i t} \Delta u_{i t}\right\|_{4 q} \\
& \leq C N_{k}^{-1 / 2} T^{1 / 2} \sum_{i \in G_{k}^{0}} \alpha_{i}\left(M_{T}\right)^{(2 q-1) /(2 q)}=o(1)
\end{aligned}
$$

This completes the proof of the proposition.
With the above result, we can readily show that

$$
\begin{aligned}
\sqrt{N_{k} T}\left(\tilde{\alpha}_{k}^{(c)}-\alpha_{k}^{0}\right)= & {\left[\sqrt{N_{k} T}\left(\tilde{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{A}_{k}^{-1} B_{k N T}\right]+\left(N_{k} / \tilde{N}_{k}\right)^{1 / 2}\left[\bar{A}_{k}^{-1} B_{k N T}-\tilde{A}_{k}^{-1} \tilde{B}_{k N T}\right] } \\
& +\left[1-\left(N_{k} / \tilde{N}_{k}\right)^{1 / 2}\right] \bar{A}_{k}^{-1} B_{k N T} \\
= & {\left[\sqrt{N_{k} T}\left(\tilde{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{A}_{k}^{-1} B_{k N T}\right]+o_{P}(1)+o_{P}\left(N_{k}^{-1}\right) O\left(\left(N_{K} / T\right)^{1 / 2}\right) } \\
= & {\left[\sqrt{N_{k} T}\left(\tilde{\alpha}_{k}-\alpha_{k}^{0}\right)-\bar{A}_{k}^{-1} B_{k N T}\right]+o_{P}(1) . }
\end{aligned}
$$

That is, $\sqrt{N_{k} T}\left(\tilde{\alpha}_{k}^{(c)}-\alpha_{k}^{0}\right)$ has the desired limiting distribution that centers around 0.
Now, we demonstrate (D.2). Let $\xi_{i s}=\Delta x_{i s} z_{i s}^{\prime}-E\left(\Delta x_{i s} z_{i s}^{\prime}\right)$ and $\eta_{i t}=z_{i t} \Delta u_{i t}$. Noting that $E\left(\xi_{i s}\right)=0$ and $E\left(\eta_{i t}\right)=0$, we have

$$
\begin{aligned}
R_{k N T}= & \frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{s=1}^{T} \sum_{t=1}^{T}\left[\xi_{i s} \eta_{i t}-\mathbb{E}\left(\xi_{i s} \eta_{i t}\right)\right] \\
= & \frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T}\left[\xi_{i t} \eta_{i t}-\mathbb{E}\left(\xi_{i t} \eta_{i t}\right)\right]+\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{1 \leq s<t \leq T}\left[\xi_{i s} \eta_{i t}-\mathbb{E}\left(\xi_{i s} \eta_{i t}\right)\right] \\
& +\frac{1}{N_{k}^{1 / 2} T^{3 / 2}} \sum_{i \in G_{k}^{0}} \sum_{1 \leq t<s \leq T}\left[\xi_{i s} \eta_{i t}-\mathbb{E}\left(\xi_{i s} \eta_{i t}\right)\right] \\
\equiv & R_{k N T, 1}+R_{k N T, 2}+R_{k N T, 3}, \text { say. }
\end{aligned}
$$

It is trivial to show that $R_{k N T, 1}=O_{P}\left(T^{-1}\right)$ by Chebyshev inequality and Davydov inequality. For $R_{k N T, 2}$, we have $E\left(R_{k N T}\right)=0$ by construction, and by Assumption D2(ii) and Jensen inequality

$$
\begin{aligned}
\mathbb{E}\left(R_{k N T, 2}^{2}\right) & =\frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \operatorname{Var}\left(\sum_{1 \leq t_{1}<t_{2} \leq T}\left[\xi_{i t_{1}} \eta_{i t_{2}}-\mathbb{E}\left(\xi_{i t_{1}} \eta_{i t_{2}}\right)\right]\right) \\
& \leq \frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \sum_{1 \leq t_{1}<t_{2} \leq T} \sum_{1 \leq t_{3}<t_{4} \leq T} \mathbb{E}\left(\xi_{i t_{1}} \eta_{i t_{2}} \xi_{i t_{3}} \eta_{i t_{4}}\right) \equiv S_{k N T}, \text { say. }
\end{aligned}
$$

To bound $S_{k N T}$, we can consider three subcases: (a) $\#\left\{t_{1}, t_{2}, t_{3}, t_{4}\right\}=4$, (b) $\#\left\{t_{1}, t_{2}, t_{3}, t_{4}\right\}=3$, and (c) $\#\left\{t_{1}, t_{2}, t_{3}, t_{4}\right\}=2$, and use $S_{k N T, a}, S_{k N T, b}$, and $S_{k N T, c}$ to denote the last summation when the time indices are restricted to these three cases in order. Apparently, $S_{k N T, c}=O(1 / T)$ under Assumption D 2 (iii). In case (a), without loss of generality (wlog) assume that $1 \leq t_{1}<t_{2}<t_{3}<t_{4} \leq T$ and denote $S_{k N T, a}^{(1)}$ as $S_{k N T, a}$ when the time indices are restricted to this subcase. [Note that the other subcases can be analyzed analogously.] Let $d_{c}$ be the $c$-th largest difference among $t_{j+1}-t_{j}$ for $j=1,2,3$. Then

$$
\begin{aligned}
S_{k N T, a}^{(1)}= & \frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}}\left\{\sum_{1 \leq t_{1}<t_{2}<t_{3}<t_{4} \leq T, t_{2}-t_{1}=d_{1}}+\sum_{1 \leq t_{1}<t_{2}<t_{3}<t_{4} \leq T, t_{3}-t_{2}=d_{1}}+\sum_{1 \leq t_{1}<t_{2}<t_{3}<t_{4} \leq T, t_{4}-t_{3}=d_{1}}\right\} \\
& \times \mathbb{E}\left(\xi_{i t_{1}} \eta_{i t_{2}} \xi_{i t_{3}} \eta_{i t_{4}}\right) \\
\equiv & S_{k N T, a 1}^{(1)}+S_{k N T, a 2}^{(1)}+S_{k N T, a 3}^{(1)}, \text { say. }
\end{aligned}
$$

By Davydov inequality and Assumptions D2(i) and (iii),

$$
\begin{aligned}
S_{N T, a 1}^{(1)} & \leq \frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \sum_{t_{1}=1}^{T-3} \sum_{t_{2}=t_{1}+\max _{j \geq 3}\left\{t_{j}-t_{j-1}\right\}}^{T-2} \sum_{t_{3}=t_{2}+1}^{T-1} \sum_{t_{4}=t_{3}+1}^{T}\left\|\xi_{i t_{1}}\right\|_{4 q}\left\|\eta_{i t_{2}} \xi_{i t_{3}} \eta_{i t_{4}}\right\|_{4 q / 3} \alpha_{i}\left(t_{2}-t_{1}\right)^{(q-1) / q} \\
& \leq \frac{C}{N_{k} T^{3}} \sum_{i=1}^{N} \sum_{t_{1}=1}^{T-3} \sum_{t_{2}=t_{1}+1}^{T-2}\left(t_{2}-t_{1}\right)^{2} \alpha_{i}\left(t_{2}-t_{1}\right)^{(q-1) / q} \\
& \leq \frac{1}{N_{k} T} \sum_{i=1}^{N} \sum_{\tau=1}^{\infty} \tau \alpha_{i}(\tau)^{(q-1) / q}=O\left(\frac{1}{T}\right)
\end{aligned}
$$

Similarly, we can show that $S_{k N T, a s}^{(1)}=O(1 / T)$ for $s=2,3$. It follows that $S_{k N T, a}^{(1)}=O(1 / T)$ and $S_{k N T, a}^{(1)}=O(1 / T)=o(1)$. In case (b), wlog assume that $t_{4}=t_{2}$ and $1 \leq t_{1}<t_{2}<t_{3} \leq T$ and we use
$S_{k N T, b}^{(1)}$ to $S_{k N T, b}$ when the time indices are restricted to this subcase. Then by Davydov inequality and Assumptions D2(i) and (iii)

$$
\begin{aligned}
\left|S_{k N T, b}^{(1)}\right| & =\frac{1}{N_{k} T^{3}} \sum_{i \in G_{k}^{0}} \sum_{1 \leq t_{1}<t_{2}<t_{3} \leq T}\left|\mathbb{E}\left(\xi_{i t_{1}} \eta_{i t_{2}}^{2} \xi_{i t_{3}}\right)\right| \\
& \leq \frac{8}{N_{k} T^{3}} \sum_{i=1}^{N} \sum_{1 \leq t_{1}<t_{2}<t_{3} \leq T}\left\|\xi_{i t_{1}} \eta_{i t_{2}}^{2}\right\|_{4 q / 3}\left\|\xi_{i t_{3}}\right\|_{4 q} \alpha_{i}\left(t_{3}-t_{2}\right)^{(q-1) / q} \\
& \leq \frac{8 C}{N_{k} T} \sum_{i=1}^{N} \sum_{\tau=1}^{\infty} \alpha_{i}(\tau)^{(q-1) / q}=O\left(\frac{1}{T}\right) .
\end{aligned}
$$

So $S_{k N T, b}=O(1 / T)$. Consequently, $S_{k N T}=O(1 / T)$ and $R_{k N T, 2}=O_{P}\left(T^{-1 / 2}\right)$ by Chebyshev inequality. By the same token, $R_{k N T, 3}=O_{P}\left(T^{-1 / 2}\right)$. Thus we have shown that $R_{k N T}=O_{P}\left(T^{-1 / 2}\right)=o_{P}(1)$.

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[^0]:    ${ }^{*}$ Su acknowledges support from the Singapore Ministry of Education for Academic Research Fund under grant number MOE2012-T2-2-021. Phillips acknowledges NSF support under Grant No. SES-0956687. Address Correspondence to: Liangjun Su, School of Economics, Singapore Management University, 90 Stamford Road, Singapore 178903; E-mail: ljsu@smu.edu.sg, Phone: +65 68280386.

[^1]:    ${ }^{1}$ Other methods that possess the selection consistency and oracle property include the Bridge and SCAD (smoothly clipped absolute deviation) procedures; see Knight and Fu (2000) and Fan and Li (2001).

[^2]:    ${ }^{2}$ If $\beta_{i}$ 's are identical across $i$, the approach will yield the well known within-group (WG) estimator or least squares dummy variable (LSDV) estimator, or fixed effects Guassian maximum likelihood estimator (MLE) in the literature; see, e.g., Kiviet (1995), Hahn and Kuersteiner (2002), and Alvarez and Arellano (2003). As will be clear, this appraoch can be easily extended to nonlinear panel data models.

[^3]:    ${ }^{3}$ When $T \geq d$, we can obtain the preliminary estimate $\hat{\beta}_{i}^{(0)}$ as $\hat{\beta}_{i}^{O L S}$. Under the condition that $T$ diverges to the infinity, these preliminary estimates are consistent for the corresponding $\beta_{i}^{0}$ 's. In addition, one can simply set $\hat{\alpha}_{k}^{(0)}$ 's as zero or the average of $\hat{\beta}_{i}^{(0)}$,s.

[^4]:    ${ }^{4}$ In traditional nonlinear panel data models, the individual effect $\mu_{i}$ is a scalar, but our theory allows it to be a vector. The $\alpha_{k}^{0}$ 's are referred to as the group (fixed) effects in the literature.

[^5]:    ${ }^{5}$ We were unable to establish asymptotic theory for the case where the criterion $Q_{2, N T}(\boldsymbol{\beta})$ is replaced by the fully pooled criterion $\tilde{Q}_{2, N T}(\boldsymbol{\beta})=\left[\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\beta_{i}^{\prime} \Delta x_{i t}\right)\right]^{\prime} W_{N T}\left[\frac{1}{N T} \sum_{i=1}^{N} \sum_{t=1}^{T} z_{i t}\left(\Delta y_{i t}-\beta_{i}^{\prime} \Delta x_{i t}\right)\right]$, where $W_{N T}$ is a $d \times d$ symmetric positive definite matrix. Use of the criterion $Q_{2, N T}(\boldsymbol{\beta})$ means that the PGMM estimator has the oracle property only in some specical cases.
    ${ }^{6}$ When the $\beta_{i}$ 's are group-specific, we can also regard the respective parameter spaces $\mathcal{B}_{i}$ to be group-specific.

[^6]:    ${ }^{7}$ If Conditions (a)-(b) after Assumption B3 are satisfied and $E\left\|z_{i t} \Delta u_{i t}\right\|^{2+\sigma}>0$, one can simply apply Davydov's inequality to obtain

    $$
    \left\|B_{k N T}\right\|=\left\|E\left(\mathcal{B}_{k N T}\right)\right\| \leq \frac{1}{T \sqrt{N_{k} T}} \sum_{i \in G_{k}^{0}} \sum_{t=1}^{T} \sum_{s=1}^{T}\left\|E\left[\Delta x_{i s} z_{i s}^{\prime} z_{i t} \Delta u_{i t}\right]\right\|=O\left((N / T)^{-1 / 2}\right)
    $$

    which is $o(1)$ if $T \gg N$ and usually not asymptocially negligible otherwise. For general choices of $W_{i N T}$, it may be difficult to verify Assumption B3(iii).

[^7]:    ${ }^{8}$ Of course one cannot choose $W_{i N T}$ to be group-specific (i.e., $W_{N T}^{(k)}$ ) because we do not know the group structure.

[^8]:    ${ }^{9}$ We experimented with $\hat{\beta}_{i}^{(0)}=\tilde{\beta}_{i}^{(0)}=1$ for all $i$ and $\hat{\alpha}_{k}^{(0)}=\tilde{\alpha}_{k}^{(0)}=0$ for all $k$. The latter choice delivers similar classification and estimation results. This suggests that the algorithm is insensitive to the initial value at least under the sensible choices, although the high-dimensionality hinders a straightforward visualization of the shapes of the objective functions with respect to the parameters.

[^9]:    ${ }^{10}$ The results for the estimation of the other coefficients are available upon request.

[^10]:    ${ }^{11}$ Observing that $\hat{\alpha}_{k}-\alpha_{k}^{0}=O_{P}\left(\left(N_{k} T\right)^{-1 / 2}+T^{-1}\right)$ and $\hat{\alpha}_{\hat{G}_{k}}-\alpha_{k}^{0}=O_{P}\left(\left(N_{k} T\right)^{-1 / 2}+T^{-1}\right)$, one can use either estimator in the definition of the residuals. We recommend using the post-Lasso estimator $\hat{\alpha}_{\hat{G}_{k}}$ because of its better finite sample performance.

[^11]:    ${ }^{12}$ Observe that $\tilde{\alpha}_{k}-\alpha_{k}^{0}=O_{P}\left(\left(N_{k} T\right)^{-1 / 2}+T^{-1}\right)$ and $\tilde{\alpha}_{\tilde{G}_{k}}-\alpha_{k}^{0}=O_{P}\left(\left(N_{k} T\right)^{-1 / 2}\right)$. We recommend using the postLasso estimator $\tilde{\alpha}_{\tilde{G}_{k}}$.

