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Accuracy and Repeatability of a semi-
quantitative barefoot pressure measurement
method: the Derks Calculation Method

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Abstract

Background: This study was designed to assess the accuracy and repeatability of the Derks Calculation Method for results found in the normal foot during walking.

Methods: Measurements were taken from 25 healthy subjects (age 32.0 +/- 12.4), 23 females and 2 males, on five separate occasions at seven days, three weeks, three months, and nine months apart by means of a mid-gait method. Values were calculated for internal rotation (IR) and external rotation of the heel (ER), heel valgus/varus (HV), heel length (HL), heel width (HW), width of the midfoot (WM) and the forefoot (WF), and the length of the foot (LF).

Results: For all five different occasions in 87.5% of the parameters investigated the coefficient of repeatability (CR, expressed as a percentage of the mean) was less than 5%. One parameter showed a higher CR: heel valgus/varus (HV) was extremely high (>800%). The maximum 95% Confidence Interval (CI) for the five different occasions was no higher than 0.2 cm for IR, ER and HV with a standard error (SE) of 0.01 and >0.01 respectively. The maximum 95% CI for WF was 0.4cm (SE 0.1), and for HW, WM and LF the maximum 95% CI was 0.7cm (SE 0.1 or 0.2). HL showed the highest 95% CI (0.9cm) with an SE of 0.2.

Conclusion: The Derks Calculation Method was found to be accurate and repeatable if HV was excluded, which renders this method a viable clinical tool in **settings** where sophisticated computerised systems are still unavailable.

Keywords: Barefoot; Pressure; Derks Calculation Method; Repeatability; Accuracy

- The Derks Calculation Method is repeatable if the values for heel varus/valgus are excluded
- The Derks Calculation Method was found to be accurate if the values for heel varus/valgus are excluded
- The Derks Calculation Method is a viable tool when sophisticated computerised systems are not available

Background

Many attempts have been made to develop a suitable technique for measuring the distribution of pressure underneath the plantar surface of the foot. The range of techniques and equipment that have been devised have been extensive, varying from inexpensive and simple to expensive and extremely complex devices [1]. The first dynamic pressure studies during walking were performed using a rubber mat [2]. The earliest technique developed to accurately capture plantar foot pressure distribution can be attributed to Elftman [3] and Morton [4]. Their deformable rubber mat was adapted to facilitate calibration and popularised by Harris and Beath [5]. As modern technology has advanced, many researchers and particularly industry have turned their attention to the development of quantitative high-resolution pressure mats, matrix arrays of force or pressure transducers, thus providing a powerful tool for conducting a full objective foot pressure investigation. However, while repeatability is generally found to be good for quantitative systems [6,7], there is a relatively high cost to pay. Cheaply available semi-quantitative plantar pressure measurement devices like ink mats and paper pedographs are able to detect high pressure areas [8] but not exact pressure values. In addition, calculation of foot geometry based on plantar pressure measurements has been shown to be reliable [9,10,11,12] as long as the measurements were collected with the same measurement system [13]. Thus, semi-quantitative plantar pressure measurement systems may provide valuable information on foot geometry for foot diagnostics and treatment.

The aim of this current study is to investigate the accuracy and repeatability of a clinical tool based on a manual calculation method as described by Derks-Roskam and Derks [14] for simple rubber mat foot prints. In this method a set of pre-defined lines, points and angles is used to define foot geometry and calcaneal position. Two tangential lines are drawn, one to the medial side of the foot print and one to the lateral side. From these two lines a midline is calculated to define the length of the foot (LF) from the heel to the forefoot. On the LF line three orthogonal lines are determined: one at 1/2 LF for measurement of the width of the midfoot (WM), one at 1/4 LF from the heel to measure calcaneal internal (IR) and external rotation (ER), and one at 3/8 LF from the heel. Where this line crosses the medial tangential line a diagonal line is drawn to the point 1/4 LF from the heel. This line is used to define heel valgus/varus (HV). Heel length (HL) is measured as the distance from the rear of the heel to the point where the medial border of the foot print crosses the midline LF. The width of the foot (WF) is measured from the lateral to the medial tangential point of the forefoot.

These measures help to define the position of high pressure areas under the foot. From these measures corrective or sensorimotor insoles may be produced to unload high pressure areas under the foot and normalise foot function.

Materials and methods

Twenty-five healthy volunteers were recruited for the study. Subjects were excluded if they had previously experienced musculoskeletal pain or gait abnormalities. The mean age of the group was 32.0 years (+/- 12.4 years). Of the 25 subjects, 23 were female and two were male. Three measurements were taken

from each foot on four occasions: on the first day (T1), with a seven-day (T2), a six-week (T3) and a three-month interval (T4). An additional set of three measurements was taken six months later (T5) from 20 of the 25 originally recruited subjects (age 32.9 +/- 11.1; 19 female and 1 male).

Measurements were taken by means of the PedoPrint® (Bauerfeind GmbH, Germany) semi-quantitative pressure measurement system. The PedoPrint® rubber mat was covered with blue ink on the underside and placed on top of a sheet of blank paper such that a subject walking over the rubber mat would leave a foot print on the paper. The PedoPrint® system was mounted level into a carpet walkway as shown in figure 1. Firstly, one left and one right foot print were taken. Subsequently, three foot prints were taken from each side. Subjects were allowed sufficient time to adapt themselves to the walkway. A mid-gait analysis (third step) was used to resemble normal walking.

The foot prints obtained from the different measurements were manually analysed by an independent researcher according to the guidelines of the Derks Calculation Method [8]. The data was normally distributed. Values were calculated for internal (IR) and external rotation of the heel (ER), heel valgus/varus (HV; positive values resemble heel valgus, negative values resemble heel varus), heel length (HL), heel width (HW), width of the midfoot (WM) and the forefoot (WF), and the length of the foot (LF) as shown in figure 2.

The collected data was analysed using SPSS® 13.0 (SPSS Inc., Chicago) program. Plausibly normal data was summarised and presented in the format mean (SD (standard deviation)). The SD reflects the within-subject and between-subject variations as well as trial-to-trial differences and variation of the calculation method. Repeated measures analysis of variance (ANOVA) was used to investigate the variability of pressures measured during walks conducted on different days. The Bonferonni correction for multiple comparisons was applied to means *post hoc* and the Huynh-Feldt correction was applied for non-sphericity. The standard deviations of the between-day differences identified in the ANOVA were used to determine the coefficient of repeatability (CR) of each parameter [15]. The CR was expressed as a percentage of the mean by using the formula [(coefficient of repeatability)/mean] x 100 [15], i.e., the lower the CR the stronger the repeatability. Plantar pressure measurements during able-bodied gait analysis showed differences between the two lower limbs. These dynamic asymmetries were the result of a natural functional organisation of the supports differentiating a loading foot and a propulsive foot [16]. Therefore, repeatability was investigated for the left and right foot separately and the mean CR determined.

Results

For all five different occasions in 87.5% of the parameters investigated (seven of eight parameters on each occasion or 35 of 40 parameters on five different occasions) the CR (expressed as a percentage of the mean) was less than 5%. One parameter showed a higher CR: heel valgus/varus was extremely high

for T1-T2 (812.8), T2-T2 (737.4), T2-T3 (120.8), T2-T4 (120.1), and T2-T5 (510.3). Table 1 shows the mean values and standard deviation for the different parameters and the different measurement days.

Mean values for the different parameters were consistent for T1-T2, T2-T2, T2-T3, T2-T4, and T2-T5 with values of 2.1 and 2.2cm for IR, 2.4 and 2.5cm for ER, 0.0 and 0.1cm for HV, 8.6 –8.9cm for HL, 3.1 and 3.3cm for HW, 2.6 and 2.7cm for WM, 8.8 and 9.0cm for WF, and 20.0 - 20.3cm for LF.

Standard deviation values also were consistent for T1-T2, T2-T2, T2-T3, T2-T4, and T2-T5 and show high accuracy with values between 0.3 and 0.4cm for IR, ER, and HV. SD values for WF were shown to be 0.6 or 0.7cm, the mean SD for LF was 1.1cm, values for WM were 1.0cm apart from T1-T2 with a mean SD of 1.4cm, and values for HL were 1.3 or 1.4cm.

The maximum 95% Confidence Interval (CI) for the five different occasions was no higher than 0.2cm for IR, ER and HV with a standard error (SE) of 0.01 and >0.01 respectively. The maximum 95% CI for WF was 0.4cm (SE 0.1), and for HW, WM and LF the maximum 95% CI was 0.7cm (SE 0.1 or 0.2). HL showed the highest 95% CI (0.9cm) with an SE of 0.2 as shown in Table 2.

Discussion

While Young [17] called for standardisation of methodology in foot pressure measurements, abbreviated gait protocols are often employed in plantar pressure studies [18]. One-step and two-step protocols are less time consuming [19] but produce longer contact times [18,19,20]. Young [17] reported that one-step measurements gave pressures which were 7-10% less than mid-gait measurements. Meyers-Rice *et al.* [21] summarised, that a two-step method, in comparison with a one-step protocol, provided closer representative pressure data. Although other authors found that peak pressures measured with different protocols are comparable [18,19,20,21] one-step and two-step protocols do not resemble normal walking [19] due to changes in contact timing. In this current study a mid-gait protocol was applied. Subjects were allowed extra time to accustom themselves to the mid-gait method to optimise the quality of measurement results. While van der Leeden *et al.* [19] stated that a minimum of three measurements were sufficient to obtain a consistent average, McPoil *et al.* [23] found that three to five walking trials are needed to obtain reliable regional peak pressure and pressure-time integral values. Keijsers *et al.* [24] discusses the need for an average of 3.8 steps for an intra-class correlation coefficient of 0.85. In this current study three measurements were taken from each foot.

All feet measured in this study were found to show pronation/supination within a well acceptable range. Thirty-five feet (70%) showed relatively low longitudinal arch with an increased mean WM of 1 +/- 0.69cm which would be interpreted as a pronator foot (0 value represents a normal longitudinal arch, positive values define arch height reduction, negative values define increased arch height). Three feet (6%) showed normal WM (equals 1/3 of the distance between the tangential lines between forefoot and hindfoot) with a minor increased mean WM of 0.02 +/- 0.01cm. Twelve feet (24%) showed a reduced

mean WM of -0.66 ± 0.54 cm which would be interpreted as relatively high instep or supinated foot. HV values for the same sample of feet showed a heel valgus position in 58.1%, varus position in 37.3%, and neutral position in 4.6% of feet.

The first aim of this study was to assess the repeatability of the Derks Calculation Method using the coefficient of repeatability. From the eight **geometric** parameters assessed on five different occasions, the highest CR was 812.8%, observed for HV. The majority of parameters (seven of eight, 87.5%) showed a CR less than 5%, whereas Putti *et al.* [6] reported that 91% of all parameters (111 of 122) had a CR less than 10% for an electronic foot pressure measurement system. Since no two foot steps are identical due to sway during gait in a normal subject [25] CR values as high as 20% are clinically acceptable [6], which suggests that the Derks Calculation Method is repeatable if the values for HV are excluded.

The second aim of our study was to assess the accuracy of this calculation method. IR, ER and HV showed very small confidence intervals of 0.2cm with a SE of 0.1 or less at a 95% level. The high confidence of a small SE for HV (>0.01) was in direct contrast with the high CR values for all occasions, suggesting that HV values vary in a small range of 0.2cm only (SD). However, variability of HV values seemed to be remarkable. This may well be due to pronatory adaptation of the subtalar joint during walking as part of the musculoskeletal suspension system and natural medial/lateral deviation of the body during gait.

Clinically, an SD of ± 0.4 cm is relevant while the maximum accuracy of a pencil and ruler calculation may be expected at approximately 0.1cm. Therefore, the lack of repeatability of HV values must be considered during planning of an intervention procedure. Ninety-five percent CI of 0.4cm with a SE of 0.1 were found for WF, and 0.7cm for HW, WM and LF (SE 0.1 or 0.2). HL showed the highest CI with 0.9cm (SE 0.2), which may be adaptive to walking speed and/or suspensory function of the foot. HL represents the contact length of the heel bone in the sagittal plane. A smaller angle between the heel bone and the ground produces a lower instep while the heel leaves a longer blueprint mark on the paper. With increased walking speed the longitudinal arch of the foot will adapt with increasing deformation as part of its suspensor function.

Conclusion

The Derks Calculation Method was found to be accurate and repeatable if HV was excluded, which renders this method a viable clinical tool in **settings** where sophisticated computerised systems are still unavailable.

Conflict of interest

All authors have no financial or personal relationships with other people or organisations that could inappropriately influence (bias) their work.

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Tables

Table 1: Mean, standard deviation (SD) and coefficient of repeatability (CR) for internal (IR) and external rotation of the heel (ER), heel varus/valgus (HV), heel length (HL), heel width (HW), width of the midfoot (WM), forefoot width (WF), and the length of the foot (LF) for different measurement days: day one (T1), 7 days later (T2), 6 weeks later (T3), 3 months later (T4), and 9 months later (T5).

Parameter (cm)	T1-T2		T2-T2		T2-T3		T2-T4		T2-T5	
	Mean (SD)	CR ^a	Mean (SD)	CR	Mean (SD)	CR	Mean (SD)	CR	Mean (SD)	CR
IR	2.1 (0.3)	1.1	2.1 (0.3)	1.9	2.2 (0.3)	1.9	2.1 (0.3)	0.5	2.1 (0.3)	0.9
ER	2.5 (0.3)	3.4	2.4 (0.3)	1.3	2.4 (0.3)	1.3	2.4 (0.3)	1.1	2.4 (0.3)	2.2
HV	0.0 (0.4)	812.8	0.0 (0.4)	737.4	0.1 (0.4)	120.8	0.0 (0.4)	120.1	0.0 (0.4)	510.3
HL	8.6 (1.3)	3.8	8.7 (1.4)	1.1	8.9 (1.4)	1.1	8.7 (1.4)	1.8	8.6 (1.3)	1.3
HW	3.1 (1.1)	1.8	3.1 (1.1)	4.7	3.3 (1.1)	4.4	3.1 (1.1)	1.3	3.1 (1.1)	2.5
WM	2.6 (1.4)	4.1	2.6 (1.0)	0.1	2.7 (1.0)	0.1	2.6 (1.0)	2.9	2.6 (1.0)	3.4
WF	9.0 (0.6)	0.8	9.0 (0.6)	0.3	9.0 (0.6)	0.3	9.0 (0.7)	0.2	8.8 (0.6)	1.0
LF	20.1 (1.1)	0.6	20.1 (1.1)	0.8	20.3 (1.1)	0.8	20.1 (1.1)	0.4	20.0 (1.1)	0.0

^a CR: expressed as a percentage of the mean.

Table 2: 95% Confidence Intervals (CI, Lower Bound (lower) and Upper Bound (upper)) and standard error (S.E.) for internal (IR) and external rotation of the heel (ER), heel varus/valgus (HV), heel length (HL), heel width (HW), width of the midfoot (WM) and the forefoot (WF), and the length of the foot (LF) for different measurement days: day one (T1), 7 days later (T2), 6 weeks later (T3), 3 months later (T4), and 9 months later (T5).

Parameter (cm)	T1-T2			T2-T2			T2-T3			T2-T4			T2-T5		
	95% CI		S.E.	95% CI		S.E.	95% CI		S.E.	95% CI		S.E.	95% CI		S.E.
	lower	upper		lower	upper		lower	upper		lower	upper		lower	upper	
IR	2.0	2.2	>0.1	2.0	2.2	>0.1	2.1	2.2	>0.1	2.0	2.2	>0.1	2.0	2.1	>0.1
ER	2.4	2.6	0.1	2.4	2.5	>0.1	2.4	2.5	>0.1	2.3	2.5	>0.1	2.3	2.4	>0.1
HV	-0.1	0.1	0.0	-0.1	0.1	>0.1	0.0	0.2	>0.1	-0.1	0.1	0.1	-0.1	0.1	>0.1
HL	8.2	9.0	0.2	8.3	9.1	0.2	8.5	9.3	0.2	8.3	9.2	0.2	8.2	9.0	0.2
HW	2.8	3.4	0.2	2.8	3.4	0.2	2.9	3.6	0.2	2.8	3.5	0.2	2.8	3.4	0.1
WM	2.2	2.9	0.2	2.3	2.9	0.1	2.3	3.0	0.1	2.3	2.9	0.1	2.3	2.8	0.1
WF	8.8	9.2	0.1	8.8	9.2	0.1	8.8	9.2	0.1	8.8	9.2	0.1	8.7	9.0	0.1
LF	19.7	20.4	0.2	19.8	20.5	0.2	19.9	20.7	0.2	19.8	20.5	0.2	19.7	20.3	0.1

Figures

Figure 1: PedoPrint® system mounted along carpet walkway.

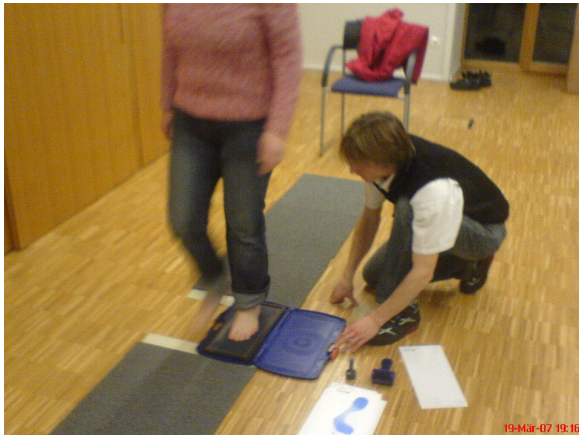
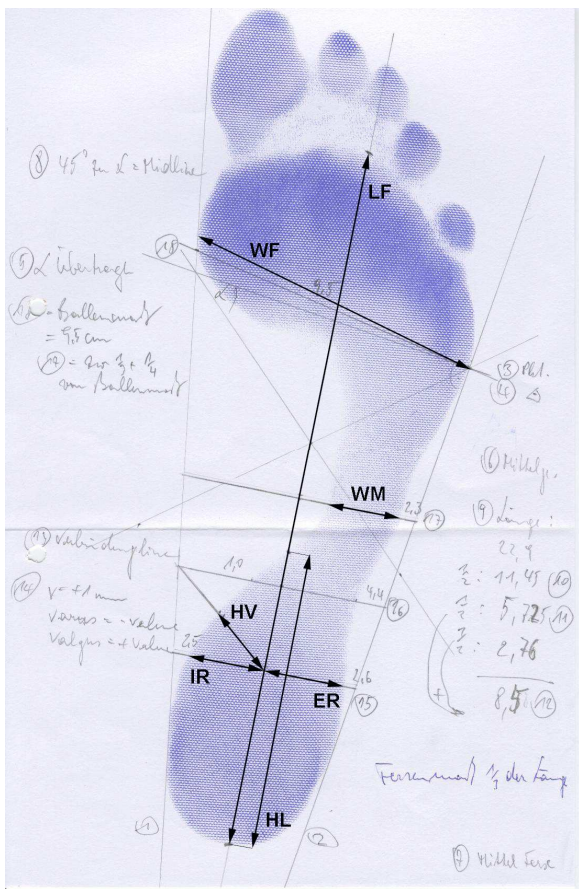


Figure 2: Calculation of variables for foot geometry: length of the foot (LF), forefoot width (WF), width of the midfoot (WM), heel length (HL), heel width (HW), heel varus/valgus (HV), and internal (IR) and external rotation of the heel (ER).



Conflict of interest

All authors have no financial or personal relationships with other people or organisations that could inappropriately influence (bias) their work.