

Expected Graduation Date: June 2011

### **Motivation**

"A battle plan seldom survives first contact with the enemy. Strategy is a system of expedients"

> lelmuth von Moltke the Elder German Generalfeldmarscha



Like a battle plan, a test plan is predicated on incomplete information. We don't know what failures our testing will uncover, so even the best test plan can be "overcome by events" at any time.

Embracing the second part of von Moltke's famous quote, we realize that the best "strategy" for T&E is adaptation. We propose a Prescriptive and Adaptive Testing Framework (PATFrame) that enables testers to address the rapidly evolving needs of Unmanned and Autonomous Systems Test (UAST).

# The PATFrame Team The University of Texas **ARLINGTON**<sub>TM</sub> **SOFTST** R

- •How much testing is enough?
- •How do I test effectively given the compressed schedule of a "Rapid Acquisition" program?
- •How do I measure the quality of my tests?
- •What are the most valuable tests for my system?
- •How should I prioritize my tests?
- •How do I make sure my tests are representative of the operational environment?
- •How do I get more knowledge for my dollar?
- •What are the unique challenges in testing UAS's and Systems of Systems (SoS's)?
- •How do I test a SoS without explicit requirements? •How does my system affect the SoS in which it operates? •What are the most valuable tests for my SoS?



## Adaptive Test Strategies Using PATFrame

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What is **PATFrame**?

#### PATFrame is a Decision Support System Addressing **Questions Posed by the Test Community:**

•How long will testing take? How much will it cost?

### **Sponsors and Transition Partners**





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### Methodologies Leveraged

- •Design of Experiments
- •Defect Modeling
- Simulation
- Real Options
- Decision Theory
- Ontologies
- •Value Based Testing

- •Cost Modeling
- Exploratory Testing
- Evolutionary Testing
- Mission Based Test and Evaluation
- Bayesian Probability
- •System Dynamics

#### **Unmanned Systems from MIT**



Images courtesy of mit.edu

#### Acknowledgments

This material is based upon work supported by the Department of Defense United States Army, White Sands Missile Range, NM. under contract # W9124Q-09-P-0230



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