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ORIGINAL ARTICLE



Experimental and finite element simulation study of capsule-free hot isostatic pressing of sintered gears

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Abstract

A novel approach to reach full density in powder metallurgy (PM) components is demonstrated in this work. Water-atomised Moprealloyed steel powder is utilised for manufacturing cylindrical and gear samples through double pressing and double sintering (DPDS) process route. The effect of sample geometry and powder size fraction on densification is investigated and it is found that the DPDS route enables a density level of >95% which is sufficient to eliminate the surface open pores. Reaching such high density is necessary, in order to perform capsule-free hot isostatic pressing (HIP). After HIP, full densification is achieved for the cylindrical samples and only near full density is realised for the gears resulting in neutral zone formation due to the density gradient. In order to predict the densification behaviour during the compaction, FEM simulations considering the gear geometry are performed for both the pressing stages and HIP. The simulation predicted a similar densification behaviour with the formation of the neutral zone. The proposed DPDS route with capsule-free HIP in combination with FEM simulation is demonstrated as a potential route for manufacturing full-density PM steel components, e.g. gears, suitable for high-performance applications.

Keywords PM steels · Gears · Pressing · Capsule-free HIP · Density · Finite element simulations

1 Introduction

Gear manufacturing through powder metallurgy (PM) route has an inherent advantage to form components with complex shapes and profiles from a single pressing operation in large volumes, compared to conventional gear manufacturing, where the typical process involves machining and gear cutting from the blank [1]. Further, PM processing is an economical route as it generates less raw material wastage over the metal cutting process and is also energy efficient [2, 3]. However, PM steels, regardless of all its advantages, are limited by the presence of pores when it comes to high-performance applications especially in dynamic loading conditions [4–6].

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Therefore, there is a need for continuous process improvement, in order to increase the density of PM steel component. The mechanical property of the PM steel component is dependent primarily on the density levels; higher the density better will be the mechanical properties [7]. When it comes to gears for heavy-duty and automotive transmissions, fatigue properties play a vital role and density has a significant effect on the final performance of the gear since it has a direct relation to the mechanical properties. Porosity plays a significant influence on the properties of PM steel [8] and the pore size, pore structure and its distribution within the sample are known to affect the fatigue properties [9-11] by initiating the crack.

Post processing operations, such as surface rolling, will increase the load-bearing capacity of the PM gears, resulting in surface densification and thus improving the fatigue properties [12, 13]. Another approach is to increase the density levels of PM components to around 95%, which in turn enables to reach full density after performing capsule-free hot isostatic pressing (HIP) [14–16]. In order to perform capsule-free HIP, it is necessary to have the surface open pores closed; otherwise, any presence of surface open pores which are interconnected will not be densified after capsule-free HIP [17, 18] whereas closed pores are successfully HIP:ed to reach full density [19, 20]. When it comes to water-atomised

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low-alloyed steel powder, it has been shown that the transition from open to closed porosity occurs around 95% of the density levels after sintering at high temperatures [21] which enables the surface pore closure [16]. Also, reaching such high density is necessary for PM steel components to retain the dimensional stability after HIP. The main advantage of this process is that the HIP capsules are eliminated and in addition to that, with the recent technological advancements in HIP, it is possible to combine the operations, such as heat treatment and quenching, which further reduces the overall processing cost [20, 22].

In this study, an approach for manufacturing fully dense PM steel, utilising Mo-prealloyed water-atomised powder was proposed. The effect of powder particle size and part geometry (cylinders and gears) upon pressing, sintering and HIP on densification was analysed. Techniques such as Hepycnometry and image analysis were used for pore analysis. In order to further develop and optimise the process route, an analytical model using the finite element method (FEM) was established based on the experimental results.

2 Materials and methods

2.1 Experimental

Water-atomised steel powder prealloyed with 1.5 wt% Mo (Astaloy Mo) produced by Höganäs AB, Sweden [23], was used in standard (20 to 180 μ m) and fine (<63 μ m) powder size fractions admixed with 0.6 wt% LubeE lubricant and 0.2 wt% UF4 natural graphite as a carbon source. Cylindrical samples (Ø25 mm × 20 mm) and gear specimens (mn = 1.5875, Z = 18, b = 10 mm and d = 31.75 mm) were compacted and used for investigations as given in Table 1. Figure 1 displays the process flow adopted in this study, where two pressing and sintering stages were considered followed by the HIP. The process begins with the initial compaction stage, first pressing (1P) at 800 MPa and then presintering (1S) at 800 °C in N₂ atmosphere to remove the lubricants and to anneal the material for the next stage of compaction, then repressed (2P) at 800 MPa and sintered (2S) at 1300 °C for 1 h in vacuum in an industrial furnace. Then, the samples were hot isostatically pressed without capsules at 1150 °C for 2 h using argon gas pressure of 100 MPa in QIH21 HIP at Quintus Technologies AB. The selected process parameters are optimum based on the previous studies [14, 15].

The density was measured according to ISO 3369 for sintered samples using Archimedes' method. The metallographic samples were prepared after 1S, 2S and HIP to investigate the pressing and sintering effect on densification. The optical images were obtained using a Leica DMRX optical microscope and SEM images were obtained using an FEGSEM LEO 1550 Gemini scanning electron microscope.

Table 1Overview of process variants using Astaloy Mo + 0.2 wt%C + 0.6 wt% lubricants

Samples	Powders	Designation
Cylinders	Standard (20 to 180 μm) Fine (<63 μm)	Cylinder B Cylinder C
Gears	Standard (20 to 180 μm) Fine (<63 μm)	Gear B Gear C

Porosity analysis was performed on 10 images taken at \times 200 magnification using the ImageJ software. The theoretical density of this is material is 7.89 g/cm³ and it is used to calculate the total porosity after measuring the density from the Archimedes method. To determine the amount of open and closed porosity, He-pycnometer measurements were performed [24] using an AccuPycII 1340 He-pycnometer. It provides the pycnometer density, from this value the closed porosity is estimated and by subtracting it from the total porosity, the amount of open porosity is obtained.

2.2 FEM process simulations

In order to formulate the material response under the two pressing stages and HIP, a selection of suitable material model is necessary for the FEM simulations to describe the development of the local density distribution.

2.2.1 Material model

Two groups of constitutive models are developed in order to simulate the powder behaviour during powder pressing and HIP. The first group includes models based on porous material densification mechanism, appropriate for high-density PM components.

Classical Von Mises model is used to develop a porous model by adding the modifications to consider the influence of porosities in the material structure which will take into account the effects of hydrostatic pressure on the yield criterion. The second group of constitutive models are adopted from soil mechanics and are used for simulation of initial metal powder pressing when there are no bonds between powder particles [25].

In this work, 1P simulation is performed using the "modified Drucker-Prager" or "CAP" model which is a well-known granular model. The overall dimensions and density distribution of the components during pressing were captured using



Fig. 1 PM process flow used in this study

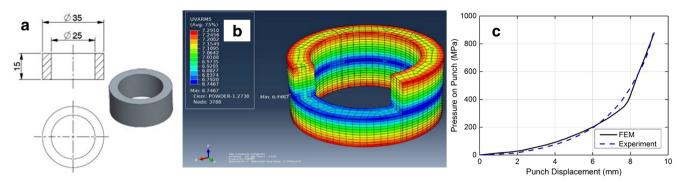


Fig. 2 Specimen drawing for the experimental compaction tests (a), simulation of the compaction test result (b), and the fitted curve for the experimental material response with optimised CAP parameters (c)

Table 2Modified Drucker-Prager model CAP plasticity parameters inABAQUS for the simulation of 1P

Material cohesion [MPa]	Angle of friction [°]	Cap eccentricity [-]	Initial yield surface position [MPa]	Transition surface radius [–]	Flow stress ratio [-]
0.059	70.55	0.5	0.01	0.01	1

this model [26]. According to Hrari et al., this model has shown acceptable accuracy in predicting the results during cold die pressing [25]. Whereas to describe the component behaviour for 2P and HIP simulations, the "Gurson" model is used [27]. It is integrated into ABAQUS as a continuum model and is able to predict the global density and overall dimensional changes of the porous metals with high accuracy. However, both the sintering processes 1S and 2S are not modelled by FEM simulation, and the sintering effect after 1S on the relative density (RD) distribution is considered with a linear modification factor. For this purpose, the resulted density distribution after 1P is modified by applying a modification factor on the relative densities of the mesh nodes from the 1P output file and then used as the input RD file for 2P simulation. The same method is used to modify the results of RD distribution after 2P and using it as the input RD file for HIP simulation.

2.2.2 Model parameters

The 1P, 2P and HIP parameters, together with the sintering modification factors for 1S and 2S, are given in this section. In order to define CAP parameters, an initial estimate based on the previous work is made [28, 29].

The ring compaction tests were performed on the specimen as shown in Fig. 2a using the standard powder size fraction. Then, the compaction test in FEM simulation is performed using the CAP model as in Fig. 2b and it is optimised to reach an accurate fit between the FEM and experimental results as shown in Fig. 2c. Based on this procedure, CAP parameters for PM gear simulation is obtained as given in Table 2, whereas for 2P and HIP simulations, all the pores are assumed to be spherical in shape. Hence, all of the three parameters of the Gurson model (q1, q2 and q3) will be equal to 1 and that is used in the FEM simulations [30, 31]. To consider the sintering effects, the modification factor of relative density equal to -0.69% and -0.50% for 1S and 2S respectively is applied to the FE model results of

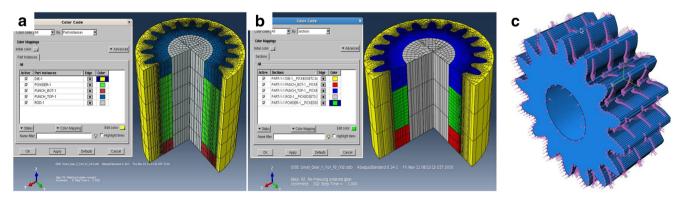
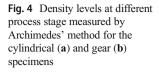
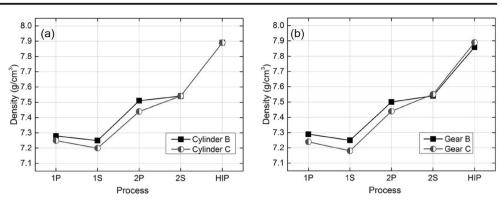


Fig. 3 3D geometrical model simulation from ABAQUS for first pressing (a), second pressing (b) and HIP simulation with isostatic pressure applied all over all the gear (c)





1P and 2P simulations. This modification factor is defined by the results of experiments and density measurements before and after 1S and 2S.

2.2.3 Mesh setup, boundary conditions and friction effects

The geometrical model of the 1P, 2P and HIP process are presented in Fig. 3a–c.

The FEM simulations are performed using ABAQUS Standard, with the mesh density of 1 element per 1 mm in the radial direction and 2 mm in the face-width direction.

To mesh the PM component, 8 node linear brick elements (C3D8R) were used.

In order to simplify the model, and also to reduce the calculation time and cost, all the dies and punches were considered to be rigid in these simulations. The 1P and 2P are modelled with displacement control for the two punches. Top punch and bottom punch are pressing the gear while the outer die and central rod are fixed in space and the PM gear is able to be compacted and densified due to pressure generated from punch movements. For HIP simulation, the PM gear freedom of rotation is fixed in and the isostatic pressure applied to all the gear surfaces. A friction factor of 0.2 was defined for all the contacting

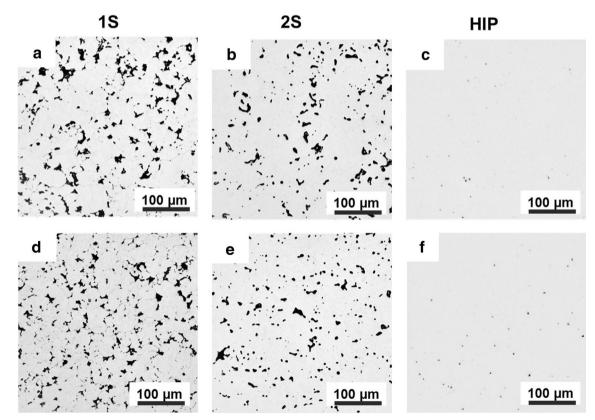


Fig. 5 Polished micrographs of the gear samples after 1S, 2S and HIP. Gear B (a-c) and Gear C (d-f)

Table 3Density and totalporosity of the bulk samples fromArchimedes' open and closedporosity from He-pycnometermeasurements and total porosityfrom image analysis after 1S, 2Sand HIP process stage

Specimens	Process	Density g/cm ³	Porosity %			Total porosity %
			Total	Open	Closed	
Cylinder B	1S	7.26	8.0	7.2	0.7	8.2 ± 0.6
	2S	7.55	4.4	-	4.4	4.7 ± 0.5
	HIP	7.89	0.2	-	0.2	_
Cylinder C	1S	7.22	8.5	8.0	0.5	8.4 ± 0.7
	2S	7.55	4.6	-	4.6	4.9 ± 0.3
	HIP	7.89	0.1	-	0.1	_
Gear B	1S	7.22	8.5	7.5	1.0	8.3 ± 1.0
	2S	7.49	5.1	0.8	4.3	5.2 ± 0.6
	HIP	7.85	0.6	-	0.6	_
Gear C	1S	7.16	9.3	8.8	0.5	8.8 ± 0.7
	2S	7.52	4.7	-	4.7	5.8 ± 0.4
	HIP	7.87	0.5	_	0.5	_

surfaces in the simulation models of 1P and 2P to consider the effects of friction during the process by using Coulomb friction.

3 Results and discussions

3.1 Effect of DPDS and HIP process on densification

The densification behaviour of the samples during double pressing and double sintering and HIP is presented and discussed in this section. The density of cylindrical and gear specimens after pressing, sintering and HIP is given in Fig. 4a, b. The major densification is from the two pressing stages and the density reached after 1P is around ~7.25 to 7.3 g/cm³ at 800 MPa. The maximum density that can be achieved without any delamination or cracks during pressing is 98% of the pore-free density (PFD) [32, 33], which is around 7.4 g/cm³ in this case with 0.2 wt% graphite and 0.6 wt% lubricant. Also, the standard powder samples (Cylinder B and Gear B) display a better densification after 1P as compared to the fine powder specimens. The effect of part geometry on the densification is evident from the increase in density after 1P for the cylindrical specimens.

The first sintering process (1S) at 800 °C is mainly to remove the admixed lubricants and to anneal the compact for subsequent pressing. For both the cylinder and gear samples, 1S results in a minor drop in the density levels due to lubricant removal as observed in Fig. 4a, b. For the standard powder specimens (Cylinder B and Gear B), the decrease in density is ~0.4% and 0.5% and for the fine powder specimens (Cylinder C and Gear C), the decrease in density is ~0.7% and 0.8%. The optical micrographs in Fig. 5a, d show the typical pore structure after the 1S stage and Table 3 summarises the results from He-pycnometer measurements and image analysis.

The results obtained show more open pores for gear specimens when compared to the cylinders. This is connected to the geometrical effect arising from the gear, generating high frictional forces from the high surface area in contact with the die during pressing resulting in the density gradient. Furthermore, the fine powder samples (Cylinder C and Gear C) exhibit a larger fraction of open pores than that of the standard powder samples (Cylinder B and Gear B), due to the powder-packing characteristic of standard and fine powder. Even though the fine powder specimens exhibit a larger amount of total porosity, the average pore size is observed to be smaller than the standard specimens [15] and this can be noted from Fig. 5a, d. The lower fraction of closed porosity after 1S indicates the presence of open porosity as a continuous network of interconnected pores which assists in an effective removal of the lubricants and resulting in more voids for

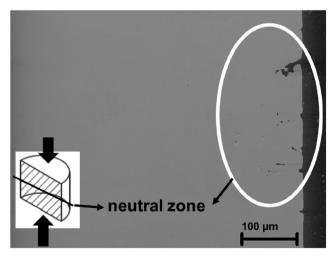


Fig. 6 SEM micrograph of the polished cross section from Cylinder C after HIP

 Table 4
 Porosity from image

 analysis at the neutral zone cross
 section from the tooth and centre

 of the gear specimens
 section

Specimens	Porosity %, in the neutral zone						
	18		28		HIP		
	Tooth	Centre	Tooth	Centre	Tooth	Centre	
Gear B	12.1 ± 1.8	8.4 ± 1.0	5.3 ± 0.6	4.0 ± 0.2	6.8 ± 1.0	_	
Gear C	12.7 ± 1.9	8.2 ± 1.1	6.2 ± 0.7	4.2 ± 0.3	-	-	

further densification. Second pressing (2P) results in a drastic increase in density after 1S by closing the pores left from the lubricant removal. The densification trend follows the previous process steps and prior effect still persists.

A final sintering is necessary to impart the strength through bond formation by generating inter-particle necks. Sintering at a temperature of 1300 °C is necessary in order to transform all the open pores to closed pores [15]. Second sintering (2S) at 1300 °C for 1 h revealed a small increase in density for standard samples, but it is prominent for fine fraction samples (Cylinder C and Gear C), with an increase in density up to 1.5%. However, the standard powdered samples (Cylinder B and Gear B) displayed an increase in density only up to \sim 0.5%, whereas the fine powder samples (Cylinder C and Gear C) displayed a better sintering effect resulting in a better densification than the standard powder samples, see Fig. 4. Optical micrograph from Fig. 5b, e displays the typical pore morphology after high temperature sintering, and from Hepycnometer results (Table 3), it is evident that all the open pores are transformed to closed pores after 2S for Cylinder B, C and Gear C, except Gear B which retains small amount of open pores. It has been shown earlier [15], for the samples with fine powders, the resulting average pore size is finer, which makes it easier to close the pores after 2S and that enables capsule-free HIP to reach full densification, as seen in Table 3.

Finally, HIP without any capsule results in almost full densification, see Fig. 5c, f. The important requirement to do capsule-free HIP is 95% relative density or above in order to have a surface closure of pores to enable full densification [16]. Results from Table 3 indicate almost full density after HIP, except for the gear sample which is left with ~ 0.5 to 1% residual closed porosity. HIP:ing will not eliminate the pores if they are connected to the surface [17, 18] as indicated in Fig. 6.

The middle section of the sample experiences a density gradient during die pressing as the pressure effect is minimum resulting in a low density region called the neutral zone [15]. This region with lower density at the middle will have open pores which are not possible to be closed after capsule-free HIP. Meanwhile, the neutral zone arises after first pressing and dominant in the gear specimen [15, 29]. In order to map the regions where the presence of pores is evident in the samples, the samples were sectioned exactly at the neutral zone and prepared for analysing the porosity.

The amount of porosity within the gear tooth and centre region from image analysis after 1S, 2S and HIP process stage is given in Table 4. As observed, there is a clear difference in porosity levels between the two regions for all the samples and the tooth region shows a higher amount of porosity reaching density levels of ~ 6.9 g/cm^3 after 1S for Gear B and Gear C samples. After 2S, the porosity level decreases, reaching density levels up to ~ 7.5 g/cm^3 in the centre and at the tooth, it varies from ~ $7.4 \text{ to } 7.47 \text{ g/cm}^3$ for Gears B and C. Figure 6 shows the SEM micrograph of Cylinder C sample along the axis at the neutral zone after HIP, where only small pore openings are visible, but for the gear samples after HIP, the presence of porosity is evident inside the gear tooth, as indicated in Fig. 7. The cross section of Gears B and C after HIP from Fig. 7b, c shows the presence of pores in the

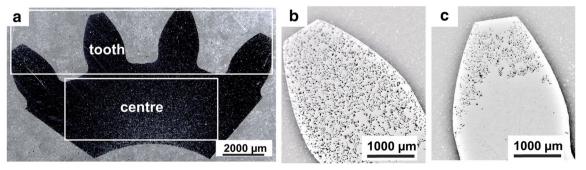


Fig. 7 Micrographs of the gear cross section showing the analysed tooth and the centre region for the gear samples (a), tooth region of the samples after HIP sectioned at the neutral zone, Gear B (b) and Gear C (c)

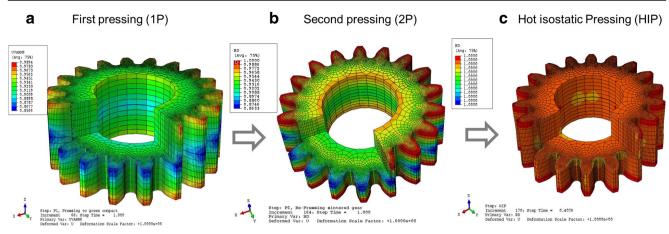


Fig. 8 Results from FEM simulation of the gears at different processing stages. First pressing (a), second pressing (b) and HIP (c)

neutral zone where Gear C is less porous than Gear B. The effect of pressing (1P) on the initial density affects the final densification after HIP by not reaching to full density, especially for gears.

3.2 FEM simulations

The resulted density distribution from FE simulation after 1P, 2P and HIP stages is shown in Fig. 8 and the average density is calculated based on the nodal values. An average density of 7.24 g/cm³ after 1P is predicted from FEM which is around 91.8% of the relative density. The resulted density distribution in the component is illustrated in Fig. 8b for 2P and is predicted to be 7.5 g/cm³ which is around 95.1% of the relative density. Finally, the output from 2P was used as an input for the HIP FE simulation, using a similar approach for average density from past two simulations. As indicated in Fig. 9, the dimensions were measured in those gear regions and the average density of the component is predicted to be 7.89 g/cm³, see Fig. 10a.

The FE model, shown in Fig. 8, illustrates the neutral zone generation in the middle section of the gear having a lower density even after 2P. This neutral zone will cause geometrical distortions afterwards during HIP due to the high-density gradients close to that area of the gear. In order to develop a method for manufacturing gears with high precision, it would be necessary to predict maximum distortions occurring beneath this area, and then compensate for those in the process of die design; however, it is not the scope of this present study.

Figure 10a is showing the average density in the component after each process step from the simulations and experiments. The results show that the used simulation model is precise in predicting the material response during the process and necessary for further development of the process route. Khodaee et al. [29] have shown, by using the same material model and modifying the gear geometry, the density gradient can be eliminated by having lower gear width and higher gear module. The formation of neutral zone is predicted well by the FE simulations for the geometry studied in this work. The FE model also predicts the distortions that occur in each process

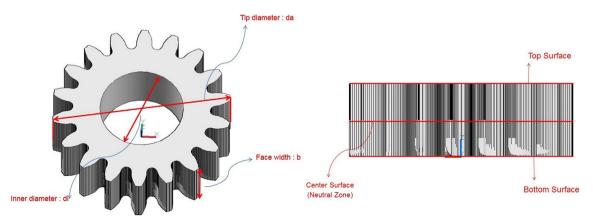
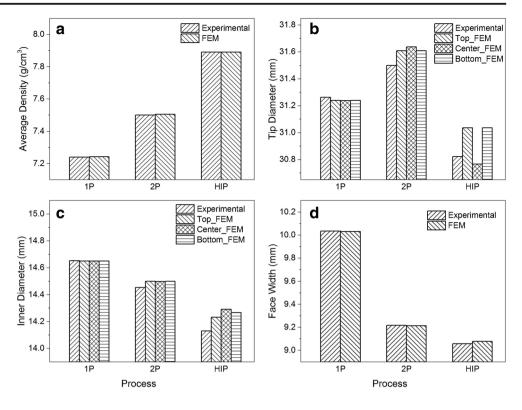


Fig. 9 Gear illustration showing the parameters measured from the different regions for the actual and FEM measurements

Fig. 10 Comparison between actual measurements and results from FEM simulation at different stages. Average density (a), tip diameter (b), inner diameter (c) and face width (d)



stage by simulating the density distribution along the neutral zone, see Fig. 10b–d and HIP results in more deviations.

An FE model for 1P, 2P and HIP was developed based on valid experiments from this study. The proposed simulation model can help to optimise the tool design for compaction in a way that distortions can be compensated in the process prior to HIP and by optimising the die geometry, the pressure effects in the HIP stage can be predicted. The validated model can be used for process development as a numerical approach with economical and time-efficient experiments by testing the process for new geometries.

4 Conclusions

The double pressing and double sintering process route with capsule-free HIP was utilised in this study, for manufacturing PM steel components especially aiming at the full-density gears. In order to simulate the experimental conditions and to further optimise the process parameters, FEM modelling considering CAP and Gurson material models for the compaction were used. The results indicated that full-density PM steel components can be reached through capsule-free HIP. The DPDS process enables PM steel components to reach ~95% of density levels for surface pore closure that assists in full densification during capsule-free HIP. Sintering at a high temperature of 1300 °C for 1 h is necessary for surface pore closure and the fine powder shows better densification after sintering. The geometry of the component has an effect on densification during pressing, as observed from the densities of cylindrical samples compared to the gears. Neutral zone problem arises from the initial compaction process especially for the gear samples due to the geometrical effect. The implemented FE simulation model indicated a good agreement with the experimental results by predicting the formation of the neutral zone during the initial compaction stage. Also, the simulation helps in predicting the distortions that arise in each process as a result of the existing density gradients. FE simulation is a vital tool in designing the processing route for manufacturing PM gears which is time and cost efficient for developing an optimised gear geometry.

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