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STABILITY OF THE PEXIDER FUNCTIONAL EQUATION

ROMAN BADORA, BARBARA PRZEBIERACZ, AND PETER VOLKMANN

Abstract. A stability result for the Pexider equation will be derived from a stability theorem published in [9] for the Cauchy functional equation. Then we discuss the quality of some constants occuring in this context; as a model case we consider functions defined on the multiplicative semigroup $\{1,0\}$.

1. Introduction

In Theorem 1 below we describe the stability result for the Cauchy equation, which had been mentioned in the Abstract.

Let S be a groupoid, i.e., S is a set and for all $x, y \in S$ we have a product $xy \in S$. For $x \in S$ and k = 0, 1, 2, ... the powers x^{2^k} are recursively defined by

$$x^{2^0} = x^1 = x, \ x^{2^{k+1}} = x^{2^k} x^{2^k}.$$

Józef Tabor [8] pointed out the usefulness of the following condition for stability investigations:

(T) For $x, y \in S$ there always is an entire $k \ge 1$ such that

(1)
$$(xy)^{2^k} = x^{2^k}y^{2^k}.$$

In the present paper, groupoids S satisfying (T) are called Tabor groupoids. Three examples are particular cases of them; they are ordered in decreasing generality:

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1. Groupoids S with a square-symmetric operation, i.e.,

$$(xy)^2 = x^2y^2, \quad x, y \in S$$

(cf. the joint paper with Zsolt Páles and R. Duncan Luce [6]). Then (1) is true for all $x, y \in S$ with the same k, viz. k = 1.

2. Groupoids S with a bisymmetric operation, i.e.,

$$(xy)(\bar{x}\bar{y}) = (x\bar{x})(y\bar{y}), \quad x, y, \bar{x}, \bar{y} \in S.$$

Here $\bar{x} = x$, $\bar{y} = y$ leads to square-symmetry.

3. Commutative semigroups S.

Let us mention that Zbigniew Gajda and Zygfryd Kominek [1] considered semigroups satisfying condition (T). Inspired by Józef Tabor [8], they call them weakly commutative.

Now let E be a Banach space. A subset V of E is called *ideally convex* (E. A. Lifšic [3]), if for every bounded sequence d_1, d_2, d_3, \ldots in V and for every numerical sequence $\alpha_1, \alpha_2, \alpha_3, \ldots \geq 0$ such that $\sum_{k=1}^{\infty} \alpha_k = 1$ we get

$$\sum_{k=1}^{\infty} \alpha_k d_k \in V.$$

The following theorem is taken from [9]; in the case of a commutative semigroup S it goes back to Jacek Tabor [7].

Theorem 1. Let S be a Tabor groupoid, and let V be a bounded and ideally convex subset of the Banach space E. For $f: S \to E$ we suppose

$$f(xy) - f(x) - f(y) \in V, \quad x, y \in S.$$

Then there exists a (unique) function $F: S \to E$ such that

$$F(xy) = F(x) + F(y), \quad F(x) - f(x) \in V, \quad x, y \in S.$$

2. The Pexider equation

Theorem 2. Let S be a Tabor groupoid having a neutral element n, i.e., $n \in S$ and

$$nx = xn = x, \quad x \in S.$$

Let V be a symmetric, bounded, and ideally convex subset of a Banach space E (the symmetry means -V = V). For $f, g, h: S \to E$ we suppose

(2)
$$f(xy) - g(x) - h(y) \in V, \quad x, y \in S.$$

Then there are $F, G, H: S \to E$ satisfying the Pexider equation

(3)
$$F(xy) = G(x) + H(y), \quad x, y \in S,$$

as well as the conditions

(4)
$$F(x) - f(x) \in 3V$$
, $G(x) - g(x) \in 4V$, $H(x) - h(x) \in 4V$, $x \in S$.

PROOF. With y = n and with x = n in (2) we get

(5)
$$f(x) - g(x) - h(n) \in V, \quad f(y) - g(n) - h(y) \in V,$$

hence $f(x) \in g(x) + h(n) + V$, $f(y) \in h(y) + g(n) + V$, thus

$$f(xy) - f(x) - f(y) + g(n) + h(n) \in f(xy) - g(x) - h(y) + V + V$$

$$\subset V + V + V = 3V$$

the last equality being true, since V is convex. For

(6)
$$\tilde{f}(x) := f(x) - g(n) - h(n), \quad x \in S,$$

this means

$$\tilde{f}(xy) - \tilde{f}(x) - \tilde{f}(y) \in 3V, \quad x, y \in S,$$

and by Theorem 1 there is a function $\Phi \colon S \to E$ such that

$$\Phi(xy) = \Phi(x) + \Phi(y), \quad \Phi(x) - \tilde{f}(x) \in 3V, \quad x, y \in S.$$

Now it is easily seen that for $F(x) := \Phi(x) + g(n) + h(n)$, $G(x) := \Phi(x) + g(n)$, $H(x) := \Phi(x) + h(n)$, $x \in S$, we get (3) and (4):

(3) is obvious; $F(x) - f(x) \in 3V$ follows from (6) and $\Phi(x) - \tilde{f}(x) \in 3V$; the remaining formulae in (4) are consequences of (5), (6), and $\Phi(x) - \tilde{f}(x) \in 3V$.

REMARK 1. Theorem 2 should be compared to other stability results for the Pexider equation, e.g. to those of Kazimierz Nikodem [5] and Zygfryd Kominek [2], where the target space for the functions is more general than a Banach space.

When choosing $V = \{x \mid x \in E, ||x|| \le \varepsilon\}$, then we get from Theorem 2 the following Corollary, which had been obtained by Nikodem [5] in the case of a commutative semigroup S.

COROLLARY 1. Let S be a Tabor groupoid having a neutral element, and let E be a Banach space. For $f, g, h: S \to E$ we suppose

$$||f(xy) - g(x) - h(y)|| \le \varepsilon, \quad x, y \in S.$$

Then there are $F, G, H: S \to E$ such that

$$F(xy) = G(x) + H(y), \quad x, y \in S,$$

$$(7) ||F(x)-f(x)|| \le 3\varepsilon, ||G(x)-g(x)|| \le 4\varepsilon, ||H(x)-h(x)|| \le 4\varepsilon, x \in S.$$

REMARK 2. If S is a commutative semigroup, then according to Zenon Moszner's survey [4], the constants 4ε in (7) can be replaced by 3ε . We do not know, wether this also holds for arbitrary Tabor groupoids.

REMARK 3. In the next paragraph we shall consider the commutative semigroup $S = \{1,0\}$. It will follow that 3ε in (7) cannot be replaced by a number less than 2ε . It also will follow that, when having in (7) the better inequality $||F(x) - f(x)|| \le 2\varepsilon$, then the constants 4ε cannot be replaced by numbers less than $3\varepsilon/2$.

REMARK 4. By calculations similar to those in the next paragraph, it can be shown that for the cyclic groups $S = Z_2$, $S = Z_3$ of two and of three elements, respectively, all the numbers 3ε , 4ε in (7) can be replaced by ε .

3. The semigroup $S = \{1, 0\}$

In $S = \{1,0\}$ we have $1 \cdot 1 = 1$, $1 \cdot 0 = 0 \cdot 1 = 0 \cdot 0 = 0$. It is easily seen that in this case solutions of the Pexider equation (3) necessarily are constant functions:

$$G(1) = G(0) = a$$
, $H(1) = H(0) = b$, $F(1) = F(0) = a + b$.

Theorem 3. Consider $S = \{1,0\}$, let N be a normed space, and let $f,g,h \colon S \to N$ satisfy

(8)
$$||f(xy) - g(x) - h(y)|| \le \varepsilon, \quad x, y \in S.$$

Then there exist $a, b \in N$ such that

(9)
$$||g(1) - a|| \le \frac{1}{2}\varepsilon, \quad ||h(1) - b|| \le \frac{1}{2}\varepsilon,$$

(10)
$$||g(0) - a|| \le \frac{3}{2}\varepsilon, \quad ||h(0) - b|| \le \frac{3}{2}\varepsilon,$$

(11)
$$||f(x) - a - b|| \le 2\varepsilon, \quad x = 0, 1.$$

Proof. Indeed, (8) means

(12)
$$f(1) - g(1) - h(1) = r_1,$$
$$f(0) - g(1) - h(0) = r_2,$$
$$f(0) - g(0) - h(1) = r_3,$$
$$f(0) - g(0) - h(0) = r_4,$$

where

(13)
$$||r_j|| \le \varepsilon, \quad j = 1, 2, 3, 4.$$

We easily get

$$(14) g(0) - g(1) = r_2 - r_4,$$

$$(15) h(0) - h(1) = r_3 - r_4,$$

(16)
$$f(0) - g(1) - h(1) = r_2 + r_3 - r_4.$$

We define

$$a = g(1) + \frac{1}{2}r_2, \quad b = h(1) + \frac{1}{2}r_3,$$

then (13) already leads to (9). From (14), (15) we now get

(17)
$$g(0) = g(1) + r_2 - r_4 = a + \frac{1}{2}r_2 - r_4,$$

(18)
$$h(0) = h(1) + r_3 - r_4 = b + \frac{1}{2}r_3 - r_4,$$

and this gives (10). From (12), (16) we finally have

$$f(1) - a - b = r_1 + g(1) - a + h(1) - b = r_1 - \frac{1}{2}r_2 - \frac{1}{2}r_3,$$

$$f(0) - a - b = f(0) - g(1) - \frac{1}{2}r_2 - h(1) - \frac{1}{2}r_3 = \frac{1}{2}r_2 + \frac{1}{2}r_3 - r_4,$$

and these two lines prove (11).

EXAMPLE. The following example shows that

- I) 2ε in (11) is best possible,
- II) having 2ε in (11), then also $\frac{1}{2}\varepsilon$ in (9) and $\frac{3}{2}\varepsilon$ in (10) are best possible: We define $f, g, h \colon S \to \mathbb{R}$ by

$$f(1) = 2$$
, $f(0) = -2$, $g(1) = 1$, $g(0) = -1$, $h(1) = 0$, $h(0) = -2$.

Then

$$f(1) - g(1) - h(1) = 2 - 1 - 0 = 1,$$

$$f(0) - g(1) - h(0) = -2 - 1 + 2 = -1,$$

$$f(0) - g(0) - h(1) = -2 + 1 - 0 = -1,$$

$$f(0) - g(0) - h(0) = -2 + 1 + 2 = 1,$$

hence (8) holds for

$$(19) \varepsilon = 1$$

(with absolute value in \mathbb{R} being the norm).

PROOF OF I). Suppose (11) to hold for some $a+b \in \mathbb{R}$ and with 2ε replaced by some η :

$$(20) \quad |2-a-b| = |f(1)-a-b| \le \eta, \quad |-2-a-b| = |f(0)-a-b| \le \eta.$$

Then $4 \le |2 - a - b| + |2 + a + b| \le 2\eta$, hence (cf. (19)) $2\varepsilon = 2 \le \eta$.

PROOF OF II). Inequality (11) with $2\varepsilon = 2$ leads to (20) with $\eta = 2$, hence to a+b=0, i.e., b=-a. Then (10) with η instead of $\frac{3}{2}\varepsilon$ leads to

$$|-1-a| = |g(0)-a| \le \eta, \quad |-2+a| = |h(0)-b| \le \eta,$$

which implies $3 = (2 - a) + (1 + a) \le 2\eta$, hence $\frac{3}{2}\varepsilon = \frac{3}{2} \le \eta$.

In the same way we get from (9) with $\frac{1}{2}\varepsilon$ replaced by η that

$$|1 - a| = |g(1) - a| \le \eta, \quad |0 + a| = |h(1) - b| \le \eta,$$

which implies $1 = (1 - a) + (0 + a) \le 2\eta$, hence $\frac{1}{2}\varepsilon = \frac{1}{2} \le \eta$.

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