



Work package 2: Real-time Data Processing

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HDRI / PanData Workshop 4.-5.3.2013, DESY



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Real-time Data Processing: Overview



Task 1: Dedicated Hardware



Actions:

- Survey of available solutions for programmable signal processing hardware
- Adopt existing solutions to the needs of PNI or join a running HGF or other development
- Introduce the solutions in PNI

Flexible high-throughput FPGA platform





PCIe DMA IP-core



PCIe x8 up to 24Gb/sec + royalty-free IP-core under development

FPGA IP-cores



Disadvantages of commercial IP-cores :

- Expensive
 - North-West DMA → 20K€ (only netlist) and 35k€ (Source code)
 - PLDA → 10K€ (for netlist) and 60k€ for (source code) EZDMA/QuickPCIe
- Limited to unique FPGA family (e.g. Virtex 6, speed grade -2)

Portfolio detector technology starts project database

1 GbE UDP



Collection of IP-Cores

The information of commonly available resources is collected on the wiki page

The sources will not be available on the wiki page, they can be get via the contact person

The structure of the entries in the databases is:

- $\circ~$ Name of the project
- Type (IP core, FPGA project, FMC card, ...)
- Description
- Platform (e.g. VERTEX 4)
- o Status
- o Contact person

High-throughput camera platform



Prototype



Application: Grating-based phase-contrast imaging



according to the users needs

Piezo Drive:

- Directly connected with detector electronics.
- Allows control of the phase-step size
 during the experiment



HZG + KIT

Application: Hot-electron bolometer (HEB)

Concept

- Signal splitter \rightarrow 4 signal
- 4 fast ADC + Pico sec delay

Characterization of 1 branch with 500MHz Pulses







F HELMHOLTZ

Application: HEB – ANKA long time bunch behaviour



Results with YBCO – terahertz detector:



New tool for machine analysis Contributes to portfolio ARD in program matter + technology

Flexible high-throughput FPGA platform



Summary:

- Data rates up to 2GB/sec Requirement for the next generation
 - Camera 5GB/sec
 - Hot electron bolometer 3GB/sec
- Involved IP-cores:
 - Serializer/Deserializers
 - DDR Memory
 - PCI Express w DMA
 - Preliminary version of next generation of DMA IP core ~3GB/sec
 - 64bit Linux drivers

Everybody is invited to join the Development of the ultrafast DAQ readout system

Real-time Data Processing





Actions:

- Computation system based on GPU co-processors
- Online tomographic reconstruction
- Prototype adoption of a complete crystallography data flow using the HDRI standard format
- General environment for parallel image processing

 a) Independent from available hardware (e.g. OpenCL)
 b) Library of standard algorithms
 c) Easy adaption to new problems
- Further applications

GPUs for Ultrasound computer tomography



Measurement Principle

- Lying patient, breast is surrounded by many ultrasound transducers
- Recording of interaction of ultrasound waves with tissue from many different angles
- Reconstruction of volume image



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GPUs for Ultrasound computer tomography



Scaling performance with multiple GPUs



8-core GPU box: Optimization of air flow



Scaling performance with multiple GPUs





Hardware selection is crucial for high-performance GPUs More on computing hardware \rightarrow Talk: S Chilingaryan

Computing and power efficiency



- Supermicro X8DTG-QF GPU-workstation
- 2 × Intel XEON E5540 @2.53GHz (QPI-connected), 192 GB memory
- 4 × Fermi C2070 (PCI-Express 16 ×)



Independent, embedded measurement setup

- Powermeters monitor voltages and currents in lines powering chipset, the hard- disks and the GPUs (including PCI)
- 250 k Samples/second

Computing and power efficiency



Energy footprint of tomographic reconstruction, PyHST:



CPU: 22Wh, 455s GPU: 5Wh, 58s A. Anzt et at., ENA-HPC, 12-14.9.2012 Cooperation w Exa2Green project

Parallel Computing Framework



Applications

(E.g. tomographic reconstruction, ...)

Load balancing + management

(CPU ⇔ GPU ⇔ frame grabber / Single ⇔ double precision)

Primitives for image processing

(2d FFT, filters, Radon transform, image conversion, ...)

Core functions, hardware access

(data transfer, file storage, camera buffering, ROI, ...)

Framework: Basics



Image processing =

composition of f lter nodes

- One thread per node
- Mapping to CPU or GPU
- Encourages recycling of tested components

Core system is built on top of **OpenCL** and **GLib/GObject**

Bindings to any language

Documented using Sphinx and Gtk-Doc

I/O are refs to data in memory

Filter object = node



Framework: Algorithms



- Filtered back projection
- Precise calculation of the center of rotation
- Laminography
- De-noising filters
- Simulation of test data

Under development:

- Algebraic reconstruction (better results)
 - Precise forward transform model and compressive sampling
- DFI-based reconstruction (faster processing)



Application: <u>ROFEX – Rossendorf</u> <u>Fast</u> <u>Electron beam X-ray tomograph</u>



U. Hampel, et al., Flow Meas. Instrument. 16, pp. 85-90, 2005 Fischer et al., Meas. Sci. Technol. 19, pp. 094002, 2008.



DAQ frame rate: < 10.000 fps Data rate ~ 1 GB/sec

Reconstruction with UFO-Framework

- Result: 256 x 256
- 600 frames \rightarrow 0.35 sec
- Frame-rate: 1.7 kfps (1 GPU)

\rightarrow **RT-Operation possible**

Further task "Post processing":

- Bubble detection
- Velocity measurement

Camera Abstraction



- Generalized access to streaming cameras (C-API)
- 64-bit linux support for PCO cameras
- Licensed under LGPL with permission from PCO
- TANGO driver



Summary



- Linux drivers for
 - High-throughput DAQ platform (KIT)
 - for PCO cameras (libuca by KIT)
 - Discussion with LImA developers (Soleil)
- Development + Optimization of GPU platforms
 - Cooling, power consumption
- Parallel processing framework for streamed data (KIT, HZG, Soleil)
 - Simplifies GPU programming
 - Possible standard interfaces for GPU algorithms ?
- Tomographic reconstruction (ESRF, KIT)
 - Advanced algorithms

Overlap with

- Supercomputing
- Matter and Technology ARD, Detectors, LSDMA