

Extensible Parallel Computing for Ultrafast X-Ray Imaging

Matthias Vogelgesang

Institute for Data Processing and Electronics



www.kit.edu





1. Introduction & Motivation

Outline



- 1. Introduction & Motivation
- 2. Technical Background

Outline



- 1. Introduction & Motivation
- 2. Technical Background
- 3. Results

Outline



- 1. Introduction & Motivation
- 2. Technical Background
- 3. Results
- 4. Usage



Large amounts of data



Large amounts of data

High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)
- Automated sample changers



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)
- Automated sample changers

Excessive compute power



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)
- Automated sample changers

Excessive compute power

Prevalance of multicore architectures and GPUs



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)
- Automated sample changers

Excessive compute power

- Prevalance of multicore architectures and GPUs
- ...but often unused due to lack of knowledge and manpower



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)
- Automated sample changers

Excessive compute power

- Prevalance of multicore architectures and GPUs
- ...but often unused due to lack of knowledge and manpower



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)
- Automated sample changers

Excessive compute power

- Prevalance of multicore architectures and GPUs
- ...but often unused due to lack of knowledge and manpower

Increased requirements



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)
- Automated sample changers

Excessive compute power

- Prevalance of multicore architectures and GPUs
- ...but often unused due to lack of knowledge and manpower

Increased requirements

On-site and on-line data processing (e.g. reconstruction)



Large amounts of data

- High resolution detectors (e.g. pco.edge 2560×2160 at 16 Bits)
- Fast acquisition (100s of frames/sec)
- Automated sample changers

Excessive compute power

- Prevalance of multicore architectures and GPUs
- ...but often unused due to lack of knowledge and manpower

Increased requirements

- On-site and on-line data processing (e.g. reconstruction)
- Faster scans to "see" dynamic processes

The UFO framework





Processes data streams (usually 1 to 4 dimensional floating point data)



- Processes data streams (usually 1 to 4 dimensional floating point data)
- Uses all hardware resources to increase throughput



- Processes data streams (usually 1 to 4 dimensional floating point data)
- Uses all hardware resources to increase throughput
- Leverages GPU processing



- Processes data streams (usually 1 to 4 dimensional floating point data)
- Uses all hardware resources to increase throughput
- Leverages GPU processing
- Hides parallelization and concurrency details



- Processes data streams (usually 1 to 4 dimensional floating point data)
- Uses all hardware resources to increase throughput
- Leverages GPU processing
- Hides parallelization and concurrency details
- Accessed via simple end-user interface

Task Graph Abstraction



Read

Task Graph Abstraction

Define algorithms as self-contained tasks

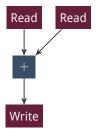






Task Graph Abstraction

- Define algorithms as self-contained tasks
- Specify data flow as edges in a graph

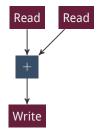




Task Graph Abstraction



- Define algorithms as self-contained tasks
- Specify data flow as edges in a graph
- Map the tasks to processing units such as CPU cores and GPUs



Benefits of graph task decomposition

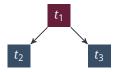


Tasks only depend on internal state and incoming data

Benefits of graph task decomposition



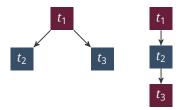
- Tasks only depend on internal state and incoming data
- Sibling tasks can run in parallel



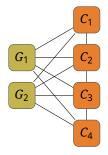
Benefits of graph task decomposition

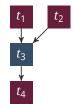


- Tasks only depend on internal state and incoming data
- Sibling tasks can run in parallel
- Tasks in sequences can run in pipelined mode



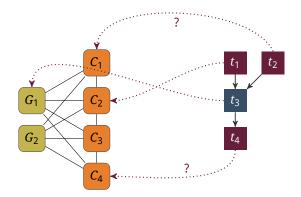






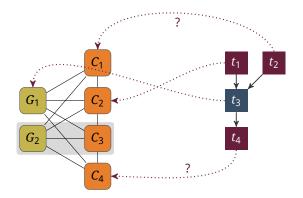


How to map tasks to processing units?



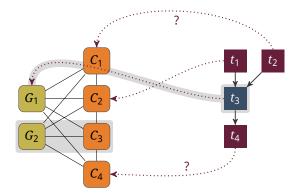


- How to map tasks to processing units?
- How to use all processing units?





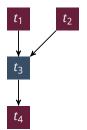
- How to map tasks to processing units?
- How to use all processing units?
- What about hardware-specific tasks?



Graph expansion



Using all processing units

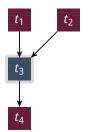


Graph expansion



Using all processing units

1. Breadth-first search to find chains of tasks that run on GPUs

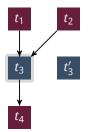


Graph expansion



Using all processing units

- 1. Breadth-first search to find chains of tasks that run on GPUs
- 2. Duplicate each chain n GPU times

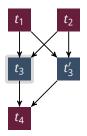


Graph expansion

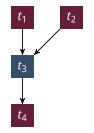


Using all processing units

- 1. Breadth-first search to find chains of tasks that run on GPUs
- 2. Duplicate each chain n GPU times
- 3. Insert the new chain







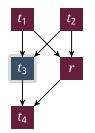
Local master

8 4 Mar 2013 M. Vogelgesang - Extensible Parallel Computing for Ultrafast X-Ray Imaging

Institute for Data Processing and Electronics



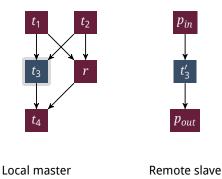
1. For each compute-intensive chain, insert a new remote node



Local master

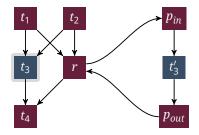


- 1. For each compute-intensive chain, insert a new remote node
- 2. Send information to the remote and setup proxy nodes



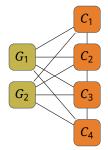


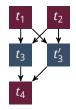
- 1. For each compute-intensive chain, insert a new remote node
- 2. Send information to the remote and setup proxy nodes
- 3. Transfer data using ØMQ



Local master

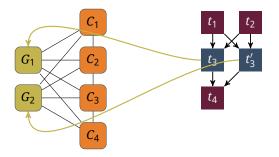






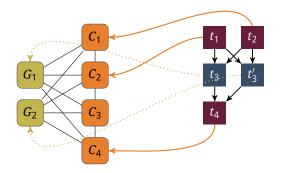


Each chain of GPU nodes is mapped to one GPU



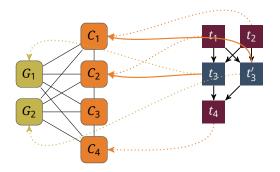


- Each chain of GPU nodes is mapped to one GPU
- Each CPU node is mapped to one of the CPUs





- Each chain of GPU nodes is mapped to one GPU
- Each CPU node is mapped to one of the CPUs
- A GPU node receives the same CPU affinity as the adjacent CPU node





Dependencies & Tools

- Standard C99
- GLib/GObject + GObject introspection
- OpenCL 1.1 or 1.2
- ZeroMQ 3.2
- Nightly builds and unit test execution via Jenkins
- API documentation built with Gtk-Doc, manual with Sphinx



Dependencies & Tools

- Standard C99
- GLib/GObject + GObject introspection
- OpenCL 1.1 or 1.2
- ZeroMQ 3.2
- Nightly builds and unit test execution via Jenkins
- API documentation built with Gtk-Doc, manual with Sphinx

High-level architecture



Dependencies & Tools

- Standard C99
- GLib/GObject + GObject introspection
- OpenCL 1.1 or 1.2
- ZeroMQ 3.2
- Nightly builds and unit test execution via Jenkins
- API documentation built with Gtk-Doc, manual with Sphinx

High-level architecture

Core framework manages OpenCL resources, graph and execution



Dependencies & Tools

- Standard C99
- GLib/GObject + GObject introspection
- OpenCL 1.1 or 1.2
- ZeroMQ 3.2
- Nightly builds and unit test execution via Jenkins
- API documentation built with Gtk-Doc, manual with Sphinx

High-level architecture

- Core framework manages OpenCL resources, graph and execution
- Shared library plugins implement actual functionality (reading, writing, filtering, ...)

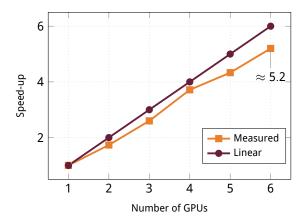
Scaling on a single compute node



Scaling on a single compute node



Tomographic reconstruction on a single compute server with 2 Xeon X5650 and 6 NVIDIA GTX 580.



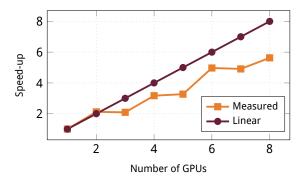
Scaling on a (small) cluster



Scaling on a (small) cluster



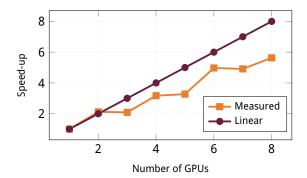
4 GPU nodes connected via Infiniband, each node has 2 GTX 580.



Scaling on a (small) cluster



4 GPU nodes connected via Infiniband, each node has 2 GTX 580.



Some problems left ...







Okay, none of you is interested in how things are performed



Okay, none of you is interested in how things are performed
Use as a C library



- Okay, none of you is interested in how things are performed
- Use as a C library
- Programmatic access through bindings (e.g. Python)

Programmatic access through bindings (e.g. Python)

Okay, none of you is interested in **how** things are performed

Simplified Python wrapper for straightforward tasks



- Okay, none of you is interested in **how** things are performed
- Use as a C library
- Programmatic access through bindings (e.g. Python)
- Simplified Python wrapper for straightforward tasks
- JSON serialization format



- Okay, none of you is interested in **how** things are performed
- Use as a C library
- Programmatic access through bindings (e.g. Python)
- Simplified Python wrapper for straightforward tasks
- JSON serialization format
- WIP: Graphical user interface based on GTK+



Simple example using the bindings



```
from gi.repository import Ufo
pm = Ufo.PluginManager()
reader = pm.get task('reader')
writer = pm.get_task('writer')
bp = g.get task('backproject')
bp.props.axis_pos = 413.5
bp.props.rotation angle = 0.012
g = Ufo.TaskGraph()
g.connect nodes(reader, bp)
g.connect nodes(bp, writer)
s = Ufo.Scheduler()
s.run(g)
```



```
writer(bp(reader)).run()
```

No code with JSON



\$ runjson description.json





Simple functionality

- Write OpenCL kernel code
- Use opencl task node and specify file and/or kernel name



Simple functionality

- Write OpenCL kernel code
- Use opencl task node and specify file and/or kernel name

More complex computing

- Create . c and . h files from a template script
- Implement method that receives a compute environment and data buffers to read from and write into



Simple functionality

- Write OpenCL kernel code
- Use opencl task node and specify file and/or kernel name

More complex computing

- Create . c and . h files from a template script
- Implement method that receives a compute environment and data buffers to read from and write into

Extending from within Python

- Numpy data sources and sinks possible
- Writing tasks in Python code is challenging due to the GIL



- No built-in management
- But could be added on a higher level based on existing primitives









UFO framework

Provides a simple but powerful processing abstraction



- Provides a simple but powerful processing abstraction
- Utilizes multiple GPUs on multiple machines



- Provides a simple but powerful processing abstraction
- Utilizes multiple GPUs on multiple machines
- Is modular, extensible and free software



- Provides a simple but powerful processing abstraction
- Utilizes multiple GPUs on multiple machines
- Is modular, extensible and free software
- Can be integrated as a C library, via language bindings or a JSON description



UFO framework

- Provides a simple but powerful processing abstraction
- Utilizes multiple GPUs on multiple machines
- Is modular, extensible and free software
- Can be integrated as a C library, via language bindings or a JSON description

More information at ufo.kit.edu



Thanks for your attention. Any questions?



```
$ git clone http://ufo.kit.edu/git/ufo-core
$ mkdir build
$ cd build
$ cmake ../ufo-core
$ make && make test && make install
```

or

\$ sudo ufo-core/tools/deploy.sh \$HOME/usr