



Karlsruhe Reports in Informatics 2010,11

Edited by Karlsruhe Institute of Technology, Faculty of Informatics ISSN 2190-4782

Dynamic Frames in Java Dynamic Logic Formalisation and Proofs

Peter H. Schmitt, Mattias Ulbrich, Benjamin Weiß

2010

KIT – University of the State of Baden-Wuerttemberg and National Research Center of the Helmholtz Association



Please note:

This Report has been published on the Internet under the following Creative Commons License: http://creativecommons.org/licenses/by-nc-nd/3.0/de.

Dynamic Frames in Java Dynamic Logic Formalisation and Proofs

Peter H. Schmitt, Mattias Ulbrich, and Benjamin Weiß

Karlsruhe Institute of Technology Institute for Theoretical Computer Science D-76128 Karlsruhe, Germany {pschmitt,mulbrich,bweiss}@ira.uka.de

Abstract. This report is a companion to the paper *Dynamic Frames* in Java Dynamic Logic [2]. It contains complementary formal definitions and proofs.

1 Formalisation

1.1 Syntax

Definition 1 (Signatures). A signature Σ is a tuple

$$\Sigma = (\mathcal{T}, \sqsubseteq, \mathcal{V}, \mathcal{PV}, \mathcal{F}, \mathcal{P}, \alpha, Prg)$$

where \mathcal{T} is a finite set of types; where \sqsubseteq is a partial order on \mathcal{T} called the subtype relation; where \mathcal{V} is a set of (logical) variables; where $\mathcal{P}\mathcal{V}$ is a set of program variables; where \mathcal{F} is a set of function symbols; where \mathcal{P} is a set of predicate symbols; where α is a static typing function such that $\alpha(v) \in \mathcal{T}$ for all $v \in \mathcal{V} \cup \mathcal{P}\mathcal{V}$, $\alpha(f) \in \mathcal{T}^* \times \mathcal{T}$ for all $f \in \mathcal{F}$, and $\alpha(p) \in \mathcal{T}^*$ for all $p \in \mathcal{P}$; and where Prq is some Java program, i.e., a set of Java classes and interfaces.

We use the notation v: A for $\alpha(v) = A$, the notation $f: A_1, \ldots, A_n \rightarrow A$ for $\alpha(f) = ((A_1, \ldots, A_n), A)$, and the notation $p: A_1, \ldots, A_n$ for $\alpha(p) = (A_1, \ldots, A_n)$.

We require that the following types, program variables, function and predicate symbols are present in every signature:

- Any, Boolean, Int, Null, LocSet, Field, Heap $\in \mathcal{T}$
- all reference types of Prg also appear as types in \mathcal{T} ; in particular, $Object \in \mathcal{T}$
- all local variables **a** of Prg with Java type T also appear as program variables $\mathbf{a}: A \in \mathcal{PV}$, where A = T if T is a reference type, A = Boolean if T = boolean, and A = Int if T = int (in this paper we do not consider other primitive types, and we ignore integer overflows)
- heap: $Heap \in \mathcal{PV}$
- $cast_A : Any \to A \in \mathcal{F} \ (for \ every \ type \ A \in \mathcal{T})$
- TRUE, FALSE : Boolean $\in \mathcal{F}$
- select_A: Heap, Object, Field $\rightarrow A \in \mathcal{F}$ (for every type $A \in \mathcal{T}$)

- store : Heap, Object, Field, Any \rightarrow Heap $\in \mathcal{F}$
- anon: Heap, LocSet, Heap \rightarrow Heap $\in \mathcal{F}$
- null: $Null \in \mathcal{F}$
- all Java fields f of Prg also appear as constant symbols $f: Field \in \mathcal{F}$
- $arr: Int \rightarrow Field \in \mathcal{F}, \quad created: Field \in \mathcal{F}$
- $allLocs: LocSet \in \mathcal{F}, allFields: Object \rightarrow LocSet \in \mathcal{F}, freshLocs: Heap \rightarrow LocSet \in \mathcal{F}$
- $-\emptyset: LocSet \in \mathcal{F}, \quad singleton: Object, Field \rightarrow LocSet \in \mathcal{F}$
- $\dot{\cup}, \dot{\cap}, \dot{\setminus}: LocSet, LocSet \rightarrow LocSet \in \mathcal{F}$
- $exactInstance_A : Any \in \mathcal{P}$ (for every type $A \in \mathcal{T}$)
- wellFormed : Heap $\in \mathcal{P}$
- $\doteq : Any, Any \in \mathcal{P}$
- $\doteq : Object, Field, LocSet \in \mathcal{P}, \quad \doteq, disjoint : LocSet, LocSet \in \mathcal{P}$

We also require that Boolean, Int, Object, LocSet \sqsubseteq Any; that for all $C \in \mathcal{T}$ with $C \sqsubseteq$ Object we have Null $\sqsubseteq C$; that for all types A, A' of Prg we have $A' \sqsubseteq A$ if and only if A' is a subtype of A in Prg; that the types explicitly mentioned in this definition are otherwise unrelated to each other wrt. \sqsubseteq ; and that the types Boolean, Int, Null, LocSet, Field and Heap do not have subtypes except themselves. Finally, we demand that $\mathcal{V}, \mathcal{PV}, \mathcal{F}$ and \mathcal{P} each contain an infinite number of symbols of every typing.

For illustration, the type hierarchy is visualised in Fig. 1. In the following, we assume a fixed signature $\Sigma = (\mathcal{T}, \sqsubseteq, \mathcal{V}, \mathcal{PV}, \mathcal{F}, \mathcal{P}, \alpha, Prg)$.



Fig. 1. Type hierarchy

Definition 2 (Syntax). The sets Trm_{Σ}^{A} of terms of type A, Fma_{Σ} of formulas and Upd_{Σ} of updates are defined by the following grammar:

$$\begin{split} \operatorname{Trm}_{\Sigma}^{A} &::= x \mid \mathbf{a} \mid f(\operatorname{Trm}_{\Sigma}^{B'_{1}}, \dots, \operatorname{Trm}_{\Sigma}^{B'_{n}}) \mid if(\operatorname{Fma}_{\Sigma}) then(\operatorname{Trm}_{\Sigma}^{A}) else(\operatorname{Trm}_{\Sigma}^{A}) \mid \\ & \{ Upd_{\Sigma} \} \operatorname{Trm}_{\Sigma}^{A} \end{split}$$

 $Fma_{\Sigma} ::= true \mid false \mid p(Trm_{\Sigma}^{B'_{1}}, \dots, Trm_{\Sigma}^{B'_{n}}) \mid \neg Fma_{\Sigma} \mid Fma_{\Sigma} \wedge Fma_{\Sigma} \mid Fma_{\Sigma} \wedge Fma_{\Sigma} \mid Fma_{\Sigma} \wedge Fma_{\Sigma} \mid Fma_{\Sigma} \leftrightarrow Fma_{\Sigma} \mid$

 $\begin{array}{l} \forall A \, x; Fma_{\varSigma} \ \left| \ \exists A \, x; Fma_{\varSigma} \ \right| \ [\mathbf{p}] Fma_{\varSigma} \ \left| \ \langle \mathbf{p} \rangle Fma_{\varSigma} \ \right| \ \{Upd_{\varSigma}\} Fma_{\varSigma} \\ Upd_{\varSigma} ::= \mathbf{a} := \ Trm_{\varSigma}^{A'} \ \left| \ Upd_{\varSigma} \ \right\| Upd_{\varSigma} \ \left| \ \{Upd_{\varSigma}\} Upd_{\varSigma} \end{array}$

for any variable $x : A \in \mathcal{V}$, any program variable $\mathbf{a} : A \in \mathcal{PV}$, any function symbol $f : B_1, \ldots, B_n \to A \in \mathcal{F}$ and any predicate symbol $p : B_1, \ldots, B_n$ where $B'_1 \sqsubseteq B_1, \ldots, B'_n \sqsubseteq B_n$, any executable Java fragment \mathbf{p} , and any type $A' \in \mathcal{T}$ with $A' \sqsubseteq A$.

A sequent is a syntactical construct $\Gamma \Rightarrow \Delta$, where $\Gamma, \Delta \in 2^{Fma_{\Sigma}}$ are finite sets of formulas.

We use infix notation for the binary symbols $\dot{\cup}$, $\dot{\cap}$, $\dot{\cdot}$, \doteq , and $\dot{\subseteq}$. Furthermore, we use the notation (A)t for $cast_A(t)$, the notation o.f for $select_A(\texttt{heap}, o, f)$ where $f: Field \in \mathcal{F}$ is a Java field, the notation a[i] for $select_A(\texttt{heap}, a, arr(i))$, the notation o.* for allFields(o), the notation $\{(o, f)\}$ for singleton(o, f), the notation $t_1 \neq t_2$ for $\neg(t_1 \doteq t_2)$, the notation $(o, f) \in s$ for $\dot{\in}(o, f, s)$, and the notation $(o, f) \notin s$ for $\neg(o, f) \in (s)$.

1.2 Semantics

Definition 3 (Kripke structures). A Kripke structure \mathcal{K} for a signature Σ is a tuple

$$\mathcal{K} = (\mathcal{D}, \delta, I, \mathcal{S}, \rho)$$

where \mathcal{D} is a set of semantical values called the domain; where δ is a dynamic typing function $\delta : \mathcal{D} \to \mathcal{T}$; where (using the definition $\mathcal{D}^A = \{d \in \mathcal{D} \mid \delta(d) \sqsubseteq A\}$) I is an interpretation function that maps every function symbol $f: A_1, \ldots, A_n \to A \in \mathcal{F}$ to a function $I(f) : \mathcal{D}^{A_1}, \ldots, \mathcal{D}^{A_n} \to \mathcal{D}^A$ and every predicate symbol $p: A_1, \ldots, A_n \in \mathcal{P}$ to a relation $I(p) \subseteq \mathcal{D}^{A_1} \times \cdots \times \mathcal{D}^{A_n}$; where S is the set of all states, which are functions $s \in S$ mapping every program variable $\mathbf{a}: A \in \mathcal{PV}$ to a value $s(a) \in \mathcal{D}^A$; and where ρ is a function associating with every executable Java fragment \mathbf{p} in the context of Prg a transition relation $\rho(\mathbf{p}) \subseteq S^2$ such that $(s_1, s_2) \in \rho(\mathbf{p})$ iff \mathbf{p} , when started in s_1 , terminates normally in s_2 (according to the Java semantics [1]). We consider Java programs to be deterministic, so for all program fragments \mathbf{p} and all $s_1 \in S$, there is at most one s_2 such that $(s_1, s_2) \in \rho(\mathbf{p})$.

We require that every Kripke structure satisfies the following:

- $\begin{array}{l} \mathcal{D}^{Boolean} = \{tt, ff\}, \ \mathcal{D}^{Int} = \mathbb{Z}, \ \mathcal{D}^{Null} = \{I(\texttt{null})\}, \ \mathcal{D}^{LocSet} = 2^{\mathcal{D}^{Object} \times \mathcal{D}^{Field}}, \\ \mathcal{D}^{Heap} = \mathcal{D}^{Object} \times \mathcal{D}^{Field} \rightarrow \mathcal{D}^{Any} \end{array}$
- $-\delta(d) \neq T$ for all $d \in \mathcal{D}$, if $T \in \mathcal{T}$ represents an interface or an abstract class
- $\{d \in \mathcal{D} \mid \delta(d) = T\}$ is infinite for all $T \sqsubseteq Object, T \neq Null$ not representing an interface or an abstract class
- $I(cast_A)(d) = d \text{ for all } d \in \mathcal{D}^A$
- I(TRUE) = tt, I(FALSE) = ff
- $I(select_A)(h, o, f) = I(cast_A)(h(o, f)) \text{ for all } h \in \mathcal{D}^{Heap}, \ o \in \mathcal{D}^{Object}, \ f \in \mathcal{D}^{Field}$

$$- I(store)(h, o, f, d)(o', f') = \begin{cases} d & \text{if } o = o' \text{ and } f = f' \\ h(o', f') & \text{otherwise} \end{cases}$$

$$for \ all \ h \in \mathcal{D}^{Heap}, \ o, o' \in \mathcal{D}^{Object}, \ f, f' \in \mathcal{D}^{Field}, \ d \in \mathcal{D}^{Any}$$

$$- I(anon)(h, s, h')(o, f) = \begin{cases} h'(o, f) & \text{if } ((o, f) \in s \text{ and } f \neq I(created)) \\ or \ (o, f) \in I(freshLocs)(h) \\ h(o, f) & \text{otherwise} \end{cases}$$

$$for \ all \ h, h' \in \mathcal{D}^{Heap}, \ s \in \mathcal{D}^{LocSet}, \ o \in \mathcal{D}^{Object}, \ f \in \mathcal{D}^{Field}$$

- let $UniqueFunctions \subseteq \mathcal{F}$ be the set consisting of the constant symbols representing Java fields, of arr and of created; then we require that for all $f, g \in UniqueFunctions$ the function I(f) is injective, and that the ranges of the functions I(f) and I(g) are disjoint. - $I(allLocs) = \mathcal{D}^{Object} \times \mathcal{D}^{Field}$, $I(allFields)(o) = \{(o, f) \mid f \in \mathcal{D}^{Field}\}$,
- $I(freshLocs)(h) = \{(o, f) \in I(allLocs) \mid o \neq I(\texttt{null}), h(o, I(created)) = ff\}$
- $I(\emptyset) = \emptyset, I(singleton)(o, f) = \{(o, f)\}, I(\dot{\cup}) = \cup, I(\dot{\cap}) = \cap, I(\dot{\setminus}) = \setminus$
- $I(exactInstance_A) = \{ d \in \mathcal{D} \mid \delta(d) = A \}$
- $-I(wellFormed) = \{h \in \mathcal{D}^{Heap'} | \text{ for all } o \in \mathcal{D}^{Object}, f \in \mathcal{D}^{Field}:$ if $h(o, f) \in \mathcal{D}^{Object}$, then h(o, f) = I(null)or h(h(o, f), I(created)) = tt
- $\begin{array}{l} I(\doteq) = \{(d,d) \in \mathcal{D}^2\} \\ I(\dot{\in}) = \{(o,f,s) \in \mathcal{D}^{Object} \times \mathcal{D}^{Field} \times \mathcal{D}^{LocSet} \mid (o,f) \in s\}, I(\dot{\subseteq}) = \{(s_1,s_2) \in (\mathcal{D}^{LocSet})^2 \mid s_1 \subseteq s_2\}, I(disjoint) = \{(s_1,s_2) \in (\mathcal{D}^{LocSet})^2 \mid s_1 \cap s_2 = \emptyset\} \end{array}$

Definition 4 (Semantics). Given a Kripke structure $\mathcal{K} = (\mathcal{D}, \delta, I, \mathcal{S}, \rho)$, a state $s \in S$ and a variable assignment $\beta : V \to D$ (where for every $x : A \in V$ we have $\beta(x) \in \mathcal{D}^A$), we evaluate terms $t \in Trm_{\Sigma}^A$ to a value val_{\mathcal{K},s,β} $(t) \in \mathcal{D}^A$, formulas $\varphi \in Fma_{\Sigma}$ to a truth value $val_{\mathcal{K},s,\beta}(\varphi) \in \{tt, ff\}, and updates u \in Upd_{\Sigma}$ to a state transformer $val_{\mathcal{K},s,\beta}(u): \mathcal{S} \to \mathcal{S}$ as defined below.

$$\begin{aligned} val_{\mathcal{K},s,\beta}(x) &= \beta(x) \\ val_{\mathcal{K},s,\beta}(\mathbf{a}) &= s(\mathbf{a}) \\ val_{\mathcal{K},s,\beta}(f(t_1,\ldots,t_n)) &= I(f)(val_{\mathcal{K},s,\beta}(t_1),\ldots,val_{\mathcal{K},s,\beta}(t_n)) \\ val_{\mathcal{K},s,\beta}(f(\varphi)then(t_1)else(t_2)) &= \begin{cases} val_{\mathcal{K},s,\beta}(t_1) \text{ if } val_{\mathcal{K},s,\beta}(\varphi) &= tt \\ val_{\mathcal{K},s,\beta}(t_2) \text{ otherwise} \end{cases} \\ val_{\mathcal{K},s,\beta}(\{u\}t) &= val_{\mathcal{K},s',\beta}(t), \text{ where } s' = val_{\mathcal{K},s,\beta}(u)(s) \\ val_{\mathcal{K},s,\beta}(false) &= ff \\ val_{\mathcal{K},s,\beta}(p(t_1,\ldots,t_n)) &= tt \text{ iff } (val_{\mathcal{K},s,\beta}(t_1),\ldots,val_{\mathcal{K},s,\beta}(t_n)) \in I(p) \\ val_{\mathcal{K},s,\beta}(\varphi) &= tt \text{ iff } val_{\mathcal{K},s,\beta}(\varphi) &= ff \\ val_{\mathcal{K},s,\beta}(\varphi_1 \wedge \varphi_2) &= tt \text{ iff } ff \notin \{val_{\mathcal{K},s,\beta}(\varphi_1), val_{\mathcal{K},s,\beta}(\varphi_2)\} \\ val_{\mathcal{K},s,\beta}(\varphi_1 \rightarrow \varphi_2) &= val_{\mathcal{K},s,\beta}(\varphi_1 \rightarrow \varphi_2 \rightarrow \varphi_1) \end{aligned}$$

$$\begin{split} & \operatorname{val}_{\mathcal{K},s,\beta}(\forall A\,x;\varphi) = tt \; \operatorname{iff}\; ff \notin \{\operatorname{val}_{\mathcal{K},s,\beta_x^d}(\varphi) \mid d \in \mathcal{D}^A\} \\ & \operatorname{val}_{\mathcal{K},s,\beta}(\exists A\,x;\varphi) = tt \; \operatorname{iff}\; tt \in \{\operatorname{val}_{\mathcal{K},s,\beta_x^d}(\varphi) \mid d \in \mathcal{D}^A\} \\ & \operatorname{val}_{\mathcal{K},s,\beta}([\mathbf{p}]\varphi) = tt \; \operatorname{iff}\; ff \notin \{\operatorname{val}_{\mathcal{K},s',\beta}(\varphi) \mid (s,s') \in \rho(\mathbf{p})\} \\ & \operatorname{val}_{\mathcal{K},s,\beta}(\langle \mathbf{p} \rangle \varphi) = tt \; \operatorname{iff}\; tt \in \{\operatorname{val}_{\mathcal{K},s',\beta}(\varphi) \mid (s,s') \in \rho(\mathbf{p})\} \\ & \operatorname{val}_{\mathcal{K},s,\beta}(\{u\}\varphi) = \operatorname{val}_{\mathcal{K},s',\beta}(\varphi), \; where \; s' = \operatorname{val}_{\mathcal{K},s,\beta}(u)(s) \\ & \operatorname{val}_{\mathcal{K},s,\beta}(\mathbf{a} := t)(s')(\mathbf{b}) = \begin{cases} \operatorname{val}_{\mathcal{K},s,\beta}(t) & \operatorname{if}\; \mathbf{b} = \mathbf{a} \\ s'(\mathbf{b}) & \operatorname{otherwise} \\ & \operatorname{for}\; \operatorname{all}\; s' \in \mathcal{S}, \; \mathbf{b} \in \mathcal{PV} \\ & \operatorname{val}_{\mathcal{K},s,\beta}(u_1 \parallel u_2)(s') = \operatorname{val}_{\mathcal{K},s,\beta}(u_2)(\operatorname{val}_{\mathcal{K},s,\beta}(u_1)(s')) \; \operatorname{for}\; \operatorname{all}\; s' \in \mathcal{S} \\ & \operatorname{val}_{\mathcal{K},s,\beta}(\{u_1\}u_2) = \operatorname{val}_{\mathcal{K},s',\beta}(u_2), \; where\; s' = \operatorname{val}_{\mathcal{K},s,\beta}(u_1)(s) \end{split}$$

We sometimes write $(\mathcal{K}, s, \beta) \models \varphi$ instead of $val_{\mathcal{K}, s, \beta}(\varphi) = tt$. A formula $\varphi \in Fma_{\Sigma}$ is called logically valid, in symbols $\models \varphi$, iff $(\mathcal{K}, s, \beta) \models \varphi$ for all Kripke structures \mathcal{K} , all states $s \in S$, and all variable assignments β .

The semantics of a sequent $\Gamma \Rightarrow \Delta$ is the same as that of a formula $\bigwedge \Gamma \rightarrow \bigvee \Delta$, where $\bigvee \{\varphi_1, \ldots, \varphi_n\} = \varphi_1 \lor \cdots \lor \varphi_n$, and $\bigwedge \{\varphi_1, \ldots, \varphi_n\} = \varphi_1 \land \cdots \land \varphi_n$.

1.3 Observations

The propositions below are used as assumptions in the proofs in Sect. 2. We do not prove them, but consider them obvious.

Proposition 1 (Non-occurring program variables). For all Kripke structures \mathcal{K} , all states $s, s' \in \mathcal{S}$, all variable assignments β , and all $t \in Trm_{\Sigma} \cup$ $Fma_{\Sigma} \cup Upd_{\Sigma}$: if for all program variables $\mathbf{a} \in \mathcal{PV}$ that syntactically occur in twe have $s(\mathbf{a}) = s'(\mathbf{a})$, then we also have $val_{\mathcal{K},s,\beta}(t) = val_{\mathcal{K},s',\beta}(t)$.

Note that a program variable **b** not occurring in t can play a role in evaluating t, namely if t contains a program which calls a method that in turn manipulates **b**. Still, in a Java program a called method can never read the value of a local variable **b** before assigning to **b**; thus, the initial value of **b** as defined by s or s' does not matter. We consider $\texttt{heap} \in \mathcal{PV}$ to implicitly occur in field access expressions o.f, in array access expressions a[i], and in method calls $\texttt{o.m}(\ldots)$.

Proposition 2 (Non-occurring function and predicate symbols). For all Kripke structures $\mathcal{K} = (\mathcal{D}, \delta, I, \mathcal{S}, \rho)$ and $\mathcal{K}' = (\mathcal{D}, \delta, I', \mathcal{S}, \rho)$ differing only in the interpretation functions I vs. I', all states $s \in \mathcal{S}$, all variable assignments β , and all $t \in \operatorname{Trm}_{\Sigma} \cup \operatorname{Fma}_{\Sigma} \cup Upd_{\Sigma}$: if for all function and predicate symbols $f \in \mathcal{F} \cup \mathcal{P}$ that syntactically occur in t we have I(f) = I'(f), then we also have $val_{\mathcal{K},s,\beta}(t) = val_{\mathcal{K}',s,\beta}(t)$.

Proposition 3 (Overwritten program variables). For all Kripke structures \mathcal{K} , all states $s, s' \in \mathcal{S}$, all variable assignments β , all updates $(a := t') \in Upd_{\Sigma}$

where **a** does not occur in t', all $t \in Trm_{\Sigma} \cup Fma_{\Sigma} \cup Upd_{\Sigma}$, all $\varphi \in Fma_{\Sigma}$, and all program fragments **p**: if for all program variables $\mathbf{b} \in \mathcal{PV} \setminus \{\mathbf{a}\}$ which occur in t or φ we have $\mathbf{s}(\mathbf{b}) = \mathbf{s}'(\mathbf{b})$, then we also have:

$$\begin{aligned} val_{\mathcal{K},s,\beta}(\{\mathbf{a}:=t'\}t) &= val_{\mathcal{K},s',\beta}(\{\mathbf{a}:=t'\}t)\\ val_{\mathcal{K},s,\beta}([\mathbf{a}=t'; \mathbf{p}]\varphi) &= val_{\mathcal{K},s',\beta}([\mathbf{a}=t'; \mathbf{p}]\varphi)\\ val_{\mathcal{K},s,\beta}(\langle \mathbf{a}=t'; \mathbf{p}\rangle\varphi) &= val_{\mathcal{K},s',\beta}(\langle \mathbf{a}=t'; \mathbf{p}\rangle\varphi) \end{aligned}$$

Prop. 3 holds because the initial value of the program variable **a** is overwritten by the preceding update or assignment, and thus cannot influence the evaluation of t or φ , respectively.

Proposition 4 (Method calls). Let p be a method call statement (res = this.m(p_1, \ldots, p_n);), let hPre: Heap $\in \mathcal{PV}$, let reachableState $\in Fma_{\Sigma}$ be as in Def. 3 of [2], let reachableState' $\in Fma_{\Sigma}$ be as in Def. 4, and let noDeallocs $\in Fma_{\Sigma}$ be as in Def. 7. Then the following holds:

 \models reachableState \rightarrow {hPre := heap}[p](reachableState' \land noDeallocs)

Prop. 4 is guaranteed by the semantics of Java.

2 Proofs

2.1 Preparation

Lemma 1 (Relation between frame and anon). Let $mod \in Trm_{\Sigma}^{LocSet}$, hPre: $Heap \in \mathcal{PV}$, frame $\in Fma_{\Sigma}$ be as in Def. 3 of [2], noDeallocs $\in Fma_{\Sigma}$ be as in Def. 7, and let frame' $\in Fma_{\Sigma}$ be the formula

 $heap \doteq anon(hPre, \{heap := hPre\} mod, heap).$

Then the following holds:

$$\models (frame \land noDeallocs) \leftrightarrow frame'$$

Proof. Let \mathcal{K} be a Kripke structure, $s \in \mathcal{S}$ be a state, β be a variable assignment, $h = s(\text{heap}), h' = val_{\mathcal{K},s,\beta}(anon(\text{hPre}, \{\text{heap} := \text{hPre}\}mod, \text{heap}), s^{pre} = val_{\mathcal{K},s,\beta}(\text{heap} := \text{hPre})(s), h^{pre} = s^{pre}(\text{heap}), m^{pre} = val_{\mathcal{K},s^{pre},\beta}(mod), fl = I(freshLocs)(h), and fl^{pre} = I(freshLocs)(h^{pre}).$ Note that $h^{pre} = s(\text{hPre})$. By definition of I(anon), we know that the following holds for all $o \in \mathcal{D}^{Object}, f \in \mathcal{D}^{Field}$:

$$h'(o, f) = \begin{cases} h(o, f) & \text{if } ((o, f) \in m^{pre} \text{ and } f \neq I(created)) \\ & \text{or } (o, f) \in fl^{pre} \\ h^{pre}(o, f) & \text{otherwise} \end{cases}$$
(1)

We first show that $(\mathcal{K}, s, \beta) \models frame \land noDeallocs$ implies that $(\mathcal{K}, s, \beta) \models frame'$, and then the other way round.

1. Let $o \in \mathcal{D}^{Object}$, $f \in \mathcal{D}^{Field}$. Using the definitions of *frame*, *noDeallocs* and *frame'*, we assume

$$(o, f) \in m^{pre} \cup fl^{pre}$$
 or $h(o, f) = h^{pre}(o, f)$ (2)

if
$$(o, f) \in \mathfrak{fl}$$
, then $(o, f) \in \mathfrak{fl}^{pre}$ (3)

$$h(I(\texttt{null}), I(created)) = h^{pre}(I(\texttt{null}), I(created))$$
(4)

and aim to show

$$h'(o, f) = h(o, f).$$
 (5)

From (2) we get that one of the following three cases must apply:

 $(o, f) \in m^{pre}$. If $f \neq I(created)$ or $(o, f) \in fl^{pre}$, then (5) immediately follows from (1). We thus assume

$$f = I(created) \tag{6}$$

$$(o,f) \notin fl^{pre}.$$
(7)

Now, (1) yields

$$h'(o, f) = h^{pre}(o, f).$$
 (8)

If o = I(null), then we get from (4) that $h(o, f) = h^{pre}(o, f)$, which together with (8) immediately yields (5). Thus we assume

$$o \neq I(\texttt{null}).$$
 (9)

From (3) and (7) we get that

 $(o, f) \notin fl.$

This, (9), and the definition of I(freshLocs) imply h(o, I(created)) = tt. Analogously, (7) and (9) imply $h^{pre}(o, I(created)) = tt$. Together, we have $h(o, I(created)) = h^{pre}(o, I(created))$, which because of (6) can be written as $h(o, f) = h^{pre}(o, f)$. We combine this with (8) to get (5).

- $(o, f) \in fl^{pre}$. Then (1) immediately yields (5).
- $-h(o, f) = h^{pre}(o, f)$. If $(o, f) \in m^{pre}$ or $(o, f) \in fl^{pre}$, then the proof proceeds as for the respective case above. Otherwise, (1) guarantees that $h'(o, f) = h^{pre}(o, f)$, and thus we have (5).
- 2. Let $o \in \mathcal{D}^{Object}$, $f \in \mathcal{D}^{Field}$. We assume (5), and show first (2), then (3), and finally (4).
 - (a) If $(o, f) \in m^{pre}$ or $(o, f) \in fl^{pre}$, then (2) holds trivially. Otherwise, (5) and (1) imply $h(o, f) = h^{pre}(o, f)$, which also implies (2).
 - (b) We prove (3) by contradiction: we assume that $(o, f) \in fl \setminus fl^{pre}$. By definition of I(freshLocs), this means that $o \neq I(\texttt{null})$, that h(o, I(created)) = ff, and that $h^{pre}(o, I(created)) = tt$. From (5) and (1) we get that $h(o, I(created)) = h^{pre}(o, I(created))$. Together, we have ff = tt.
 - (c) The definition of I(freshLocs) tells us that $(I(null), I(created)) \notin fl^{pre}$. Thus, (5) and (1) immediately guarantee (4).

2.2 Method Contracts

Theorem 1 (Soundness of useMethodContract). Let $\Gamma, \Delta \in 2^{Fma_{\Sigma}}, u \in Upd_{\Sigma}, [\![\cdot]\!] \in \{[\cdot], \langle \cdot \rangle\}, \mathbf{r} \in \mathcal{PV}, \mathbf{o} \in Trm_{\Sigma}, the method <math>\mathfrak{m}, \mathfrak{p}'_1, \ldots, \mathfrak{p}'_n \in Trm_{\Sigma}, \varphi \in Fma_{\Sigma}, A \in \mathcal{T}, mct = (\mathfrak{m}, \mathtt{this}, (\mathfrak{p}_1, \ldots, \mathfrak{p}_n), \mathtt{res}, \mathtt{hPre}, pre, post, mod, \tau), reachableState, reachableState' \in Fma_{\Sigma}, v, w \in Upd_{\Sigma}, and h, r' \in \mathcal{F} all be as in Def. 4 of [2]. If$

$$\models \Gamma \Rightarrow \{u\}\{w\}(pre \land reachableState), \Delta$$
⁽¹⁰⁾

 $\models \Gamma \Rightarrow \{u\}\{w\}\{\texttt{hPre} := \texttt{heap}\}\{v\}(post \land reachableState' \rightarrow \llbracket \dots \rrbracket \varphi), \Delta \quad (11)$

and if for all types $B \sqsubseteq A$ we have

$$\models CorrectMethodContract(mct, B), \tag{12}$$

then the following holds:

(

$$\models \Gamma \Rightarrow \{u\} \llbracket \mathbf{r} = \mathbf{o}.\mathbf{m}(\mathbf{p}'_1, \dots, \mathbf{p}'_n); \ \dots \rrbracket \varphi, \Delta.$$

Proof. Let (10), (11) and (12) hold. Let furthermore $\mathcal{K} = (\mathcal{D}, \delta, I, \mathcal{S}, \rho)$ be a Kripke structure, $s \in \mathcal{S}$, and β be a variable assignment. Our goal is to show

$$(\mathcal{K}, s, \beta) \models \Gamma \Rightarrow \{u\} \llbracket \mathbf{r} = \mathbf{o}.\mathbf{m}(\mathbf{p}'_1, \dots, \mathbf{p}'_n); \ \dots \rrbracket \varphi, \Delta.$$

If there is $\gamma \in \Gamma$ with $val_{\mathcal{K},s,\beta}(\gamma) = ff$ or if there is $\delta \in \Delta$ with $val_{\mathcal{K},s,\beta}(\delta) = tt$, then this is trivially true. We therefore assume that

$$(\mathcal{K}, s, \beta) \models \bigwedge (\Gamma \cup \neg \Delta), \tag{13}$$

and aim to show that $(\mathcal{K}, s, \beta) \models \{u\} \llbracket \mathbf{r} = \mathbf{o} \cdot \mathbf{m}(\mathbf{p}'_1, \dots, \mathbf{p}'_n); \dots \rrbracket \varphi$.

Let $s_1 = val_{\mathcal{K},s,\beta}(u)(s)$. Then our goal is to show

$$(\mathcal{K}, s_1, \beta) \models \llbracket \mathbf{r} = \mathbf{o}.\mathbf{m}(\mathbf{p}'_1, \dots, \mathbf{p}'_n); \ \dots \rrbracket \varphi$$

Let $s_2 = val_{\mathcal{K},s_1,\beta}(w)(s_1)$. Because of the definition of w, it holds for all $\mathbf{a} \in \mathcal{PV} \setminus \{\mathtt{this}, \mathtt{p}_1, \ldots, \mathtt{p}_n\}$ that $s_1(\mathbf{a}) = s_2(\mathbf{a})$. Since by Def. 4 neither this nor $\mathtt{p}_1, \ldots, \mathtt{p}_n$ occur in the above formula, Prop. 1 tells us that the interpretation of this formula is the same in s_1 and s_2 . It is therefore sufficient if we show

$$(\mathcal{K}, s_2, \beta) \models \llbracket \mathbf{r} = \mathbf{o}.\mathbf{m}(\mathbf{p}'_1, \dots, \mathbf{p}'_n); \ \dots \rrbracket \varphi$$

The definition of w and Prop. 1 ensure that $s_2(\text{this}) = val_{\mathcal{K},s_2,\beta}(\mathsf{o})$, and that $s_2(\mathsf{p}_1) = val_{\mathcal{K},s_2,\beta}(\mathsf{p}'_1), \ldots, s_2(\mathsf{p}_n) = val_{\mathcal{K},s_2,\beta}(\mathsf{p}'_n)$. Thus, we can aim to prove the formula below instead of the formula above:

$$(\mathcal{K}, s_2, \beta) \models \llbracket \mathbf{r} = \mathtt{this.m}(\mathbf{p}_1, \dots, \mathbf{p}_n); \dots \rrbracket \varphi$$

Since by Def. 4 the program variable **res** does not occur in the above formula, the Java semantics allows us to instead show

$$\mathcal{K}, s_2, \beta) \models \llbracket \text{res} = \text{this.m}(\mathbf{p}_1, \dots, \mathbf{p}_n); \ \mathbf{r} = \text{res}; \ \dots \rrbracket \varphi.$$

Let $s_3 = val_{\mathcal{K}, s_2, \beta}$ (hPre := heap) (s_2) . Since by Def. 4 the program variable hPre does not occur in the above formula, by Prop. 1 it is sufficient if we prove

$$(\mathcal{K}, s_3, \beta) \models \llbracket \texttt{res} = \texttt{this.m}(\texttt{p}_1, \dots, \texttt{p}_n) \texttt{; } \texttt{r} = \texttt{res}\texttt{; } \dots \rrbracket \varphi. \qquad (\texttt{thm1-goal})$$

We combine (13) with (10) to get

$$(\mathcal{K}, s, \beta) \models \{u\}\{w\}(pre \land reachableState),\$$

which by definition of s_2 is the same as

$$(\mathcal{K}, s_2, \beta) \models pre \land reachableState.$$
(14)

Let $C = \delta(s_2(\texttt{this}))$. This means that

$$(\mathcal{K}, s_2, \beta) \models exactInstance_C(\texttt{this}). \tag{15}$$

Since $\alpha(\texttt{this}) = A$, we have $C \sqsubseteq A$ because of well-typedness. Instantiating (12) with C and s_2 yields

$$(\mathcal{K}, s_2, \beta) \models pre \land reachableState \land exactInstance_C(\texttt{this}) \\ \rightarrow \{\texttt{hPre} := \texttt{heap}\}[\![\texttt{res} = \texttt{this.m}(\texttt{p}_1, \dots, \texttt{p}_n);]\!]'(post \land frame)$$

where $\llbracket \cdot \rrbracket'$ is $\langle \cdot \rangle$ if $\llbracket \cdot \rrbracket$ is $\langle \cdot \rangle$, and where $\llbracket \cdot \rrbracket'$ is either $\langle \cdot \rangle$ or $[\cdot]$ otherwise. Together with (14) and (15), this implies

$$(\mathcal{K}, s_2, \beta) \models \{ hPre := heap \} [[res = this.m(p_1, \dots, p_n);]]'(post \land frame).$$

With the definition of s_3 , this becomes

$$(\mathcal{K}, s_3, \beta) \models \llbracket \text{res} = \text{this.m}(\mathbf{p}_1, \dots, \mathbf{p}_n); \rrbracket'(post \land frame).$$
(16)

If there is no $s_4 \in S$ such that $(s_3, s_4) \in \rho(\text{res} = \text{this.m}(p_1, \ldots, p_n);)$ (i.e., if the method call does not terminate when started in s_3), then (16) implies that $\llbracket \cdot \rrbracket'$ must be $[\cdot]$, and thus $\llbracket \cdot \rrbracket$ also must be $[\cdot]$. Then, (thm1-goal) holds trivially, because there is no final state which would have to satisfy φ .

We can thus find $s_4 \in S$ such that $(s_3, s_4) \in \rho(\text{res} = \text{this.m}(p_1, \dots, p_n);)$. As our programs are deterministic, s_4 is the only such state. Our proof goal (thm1-goal) now becomes

$$(\mathcal{K}, s_4, \beta) \models \llbracket \mathbf{r} = \mathbf{res}; \ldots \rrbracket \varphi.$$
 (thm1-goal')

From (16) and the definition of s_4 we get

$$(\mathcal{K}, s_4, \beta) \models post \land frame. \tag{17}$$

Let $noDeallocs \in Fma_{\Sigma}$ be as in Def. 7. Prop. 4 tells us that

 $(\mathcal{K}, s_2, \beta) \models reachableState$

 $\rightarrow \{ \texttt{hPre} := \texttt{heap} \} [\texttt{res} = \texttt{this.m}(\texttt{p}_1, \dots, \texttt{p}_n; \texttt{)}] \\ (reachableState' \land noDeallocs).$

Together with (14) and the definition of s_4 , this turns into

$$(\mathcal{K}, s_4, \beta) \models reachableState' \land noDeallocs.$$
(18)

Let $\mathcal{K}' = (\mathcal{D}, \delta, I', \mathcal{S}, \rho)$ be a Kripke structure identical to \mathcal{K} , except that $I'(h) = s_4(\texttt{heap})$, and except that $I'(r') = s_4(\texttt{res})$. Since by Def. 4 the symbols h and r' do not occur in Γ nor in Δ , we get from (13) that $(\mathcal{K}', s, \beta) \models \bigwedge(\Gamma \cup \neg \Delta)$. This and (11) imply

$$(\mathcal{K}', s, \beta) \models \{u\}\{w\}\{\texttt{hPre} := \texttt{heap}\}\{v\}(\textit{post} \land \textit{reachableState}' \rightarrow \llbracket \dots \rrbracket \varphi).$$

As h and r' do not occur in u, in w or in hPre := heap, the above and Prop. 2 imply that

$$(\mathcal{K}', s_3, \beta) \models \{v\}(post \land reachableState' \rightarrow \llbracket \dots \rrbracket \varphi).$$

Let $s'_4 = val_{\mathcal{K}', s_3, \beta}(v)(s_3)$. Then the above implies

$$(\mathcal{K}', s'_4, \beta) \models post \land reachableState' \rightarrow \llbracket \dots \rrbracket \varphi.$$

Since h and r' do not occur in the above formula, by Prop. 2 we get that

$$(\mathcal{K}, s'_4, \beta) \models post \land reachableState' \to \llbracket \dots \rrbracket \varphi.$$
⁽¹⁹⁾

Given the definition of s_4 , the semantics of Java tells us that for all $a \in \mathcal{PV} \setminus \{\text{heap}, \text{res}\}$ we have $s_3(a) = s_4(a)$. Similarly, the definition of s'_4 implies that for all $a \in \mathcal{PV} \setminus \{\text{heap}, \textbf{r}, \textbf{res}\}$ we have $s_3(a) = s'_4(a)$. Together, we have

for all
$$\mathbf{a} \in \mathcal{PV} \setminus \{ \text{heap}, \mathbf{r}, \text{res} \} : s_4'(\mathbf{a}) = s_4(\mathbf{a}).$$
 (20)

The definition of s'_4 also guarantees that

$$s'_{4}(\texttt{heap}) = val_{\mathcal{K}', s_{3}, \beta}(anon(\texttt{heap}, mod, h))$$
(21)

$$s'_4(\mathbf{r}) = I'(r') = s_4(\text{res})$$
 (22)

$$s'_4(res) = I'(r') = s_4(res)$$
(23)

Using (17) and (18), Lemma 1 tells us that

 $(\mathcal{K}, s_4, \beta) \models \texttt{heap} \doteq anon(\texttt{hPre}, \{\texttt{heap} := \texttt{hPre}\} mod, \texttt{heap}),$

which we can also express as

$$s_4(\texttt{heap}) = val_{\mathcal{K}, s_4, \beta}(anon(\texttt{hPre}, \{\texttt{heap} := \texttt{hPre}\}mod, \texttt{heap})).$$

Since by Def. 4 the function symbols h and r' do not occur in the above formula, and since \mathcal{K}' is otherwise identical to \mathcal{K} , Prop. 2 yields

$$s_4(\texttt{heap}) = val_{\mathcal{K}', s_4, \beta}(anon(\texttt{hPre}, \{\texttt{heap} := \texttt{hPre}\}mod, \texttt{heap})).$$

As we defined \mathcal{K}' such that $I'(h) = s_4(\texttt{heap})$, this implies

$$s_4(\texttt{heap}) = val_{\mathcal{K}', s_4, \beta}(anon(\texttt{hPre}, \{\texttt{heap} := \texttt{hPre}\} mod, h)).$$

Since s_3 and s_4 are identical except for heap and res, and since res does not occur in {heap := hPre}mod, Prop. 3 tells us that $val_{\mathcal{K},s_4,\beta}$ ({heap := hPre}mod) = $val_{\mathcal{K},s_3,\beta}$ ({heap := hPre}mod). As heap and res do not occur in the other arguments of *anon*, we can transform the statement above into

$$s_4(\texttt{heap}) = val_{\mathcal{K}', s_3, \beta}(anon(\texttt{hPre}, \{\texttt{heap} := \texttt{hPre}\} mod, h)).$$

The definition of s_3 implies $s_3(\texttt{heap}) = s_3(\texttt{hPre})$. Thus, the update heap := hPre has no effect in s_3 . This allows simplifying the above into

$$s_4(\texttt{heap}) = val_{\mathcal{K}', s_3, \beta}(anon(\texttt{hPre}, mod, h)),$$

and replacing hPre with heap to get

$$s_4(\texttt{heap}) = val_{\mathcal{K}', s_3, \beta}(anon(\texttt{heap}, mod, h)).$$

This, together with (21), implies that $s_4(\text{heap}) = s'_4(\text{heap})$. Combining this result with (20) and (23) yields that s_4 and s'_4 differ at most in **r**. Since by Def. 4 the program variable **r** does not occur in *post*, (17) and Prop. 1 imply

$$(\mathcal{K}, s_4', \beta) \models post. \tag{24}$$

As \mathbf{r} also does not occur in *reachableState'*, we get from (18) that

$$(\mathcal{K}, s'_{\mathcal{A}}, \beta) \models reachableState'.$$

This, (24) and (19) together imply

$$(\mathcal{K}, s'_4, \beta) \models \llbracket \dots \rrbracket \varphi.$$

By (22) and (23), we know that $s'_4(res) = s'_4(r)$. Thus, the Java semantics allows us to rewrite the above statement into

$$(\mathcal{K}, s'_4, \beta) \models \llbracket \mathbf{r} = \mathbf{res}; \ldots \rrbracket \varphi.$$

Finally, as s_4 and s'_4 differ at most in **r**, Prop. 3 tells us that

$$(\mathcal{K}, s_4, \beta) \models \llbracket \mathbf{r} = \mathbf{res}; \ldots \rrbracket \varphi$$

and this is property (thm1-goal') which we aimed to show.

2.3 Dependency Contracts

Theorem 2 (Soundness of useDependencyContract). Let $\Gamma, \Delta \in 2^{Fma_{\Sigma}}$, $obs \in \mathcal{F} \cup \mathcal{P}$, $h^{new} = (f_1(f_2(\dots(f_m(h^{base},\dots)))))$, $o, p'_1, \dots, p'_n) \in Trm_{\Sigma}$, $A \in \mathcal{T}$, $depct = (obs, \texttt{this}, (p_1, \dots, p_n), pre, dep)$, $hPre \in \mathcal{PV}$, $mod = allLocs \setminus dep$, reachableState, frame, noDeallocs \in Fma $_{\Sigma}$, $w \in Upd_{\Sigma}$, guard, equal \in Fma $_{\Sigma}$ all be as in Def. 7 of [2]. If

$$\models \Gamma, \ guard \to equal \ \Rightarrow \ \Delta \tag{25}$$

and if for all types $B \sqsubseteq A$ we have

$$= CorrectDependencyContract(depct, B),$$
(26)

then the following holds:

$$\models \Gamma \Rightarrow \Delta.$$

Proof. Let (25) and (26) hold, and let $\mathcal{K} = (\mathcal{D}, \delta, I, \mathcal{S}, \rho)$ be a Kripke structure. Our goal is to show $(\mathcal{K}, s, \beta) \models \Gamma \Rightarrow \Delta$. We will do a proof by contradiction and assume that this does *not* hold, or in other words, that $(\mathcal{K}, s, \beta) \models \bigwedge(\Gamma \cup \neg \Delta)$ holds. This and (25) imply $(\mathcal{K}, s, \beta) \models \neg(guard \rightarrow equal)$, which means that $(\mathcal{K}, s, \beta) \models guard \land \neg equal$. If we insert the definitions of guard and equal, and distribute the update w over the conjuncts of guard, then this reads as

$$\begin{aligned} (\mathcal{K}, s, \beta) &\models \{w\} \{ \texttt{heap} := h^{base} \} (pre \land reachableState) \\ (\mathcal{K}, s, \beta) &\models \{w\} \{ \texttt{hPre} := h^{base} \parallel \texttt{heap} := h^{new} \} (frame \land noDeallocs) \\ (\mathcal{K}, s, \beta) &\models \neg \big(obs(h^{new}, \texttt{o}, \texttt{p}'_1, \dots, \texttt{p}'_n) \equiv obs(h^{base}, \texttt{o}, \texttt{p}'_1, \dots, \texttt{p}'_n) \big) \end{aligned}$$
(27)

Let $s_1 = val_{\mathcal{K},s,\beta}(w)(s)$. Then the first two statements above become

$$\begin{aligned} (\mathcal{K}, s_1, \beta) &\models \{\texttt{heap} := h^{base}\}(pre \land reachableState) \\ (\mathcal{K}, s_1, \beta) &\models \{\texttt{hPre} := h^{base} \,\|\, \texttt{heap} := h^{new}\}(frame \land noDeallocs) \end{aligned}$$

Let $s_1^{base} = val_{\mathcal{K},s,\beta}(\texttt{heap} := h^{base})(s_1), \ s_1^{new} = val_{\mathcal{K},s,\beta}(\texttt{hPre} := h^{base} \parallel \texttt{heap} := h^{new})(s_1)$. Then the statements above turn into

$$(\mathcal{K}, s_1^{base}, \beta) \models pre \land reachableState \tag{28}$$

$$(\mathcal{K}, s_1^{new}, \beta) \models frame \land noDeallocs \tag{29}$$

As this, p_1, \ldots, p_n do not occur in (27), and as s and s_1 are otherwise identical, we get by Prop. 1 that

$$(\mathcal{K}, s_1, \beta) \models \neg \big(obs(h^{new}, \mathbf{o}, \mathbf{p}'_1, \dots, \mathbf{p}'_n) \equiv obs(h^{base}, \mathbf{o}, \mathbf{p}'_1, \dots, \mathbf{p}'_n) \big),$$

which because of the definition of s_1 implies that

$$(\mathcal{K}, s_1, \beta) \models \neg \big(obs(h^{new}, \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n) \equiv obs(h^{base}, \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n)\big).$$
(30)

Lemma 1 and (29) tell us that

$$(\mathcal{K}, s_1^{new}, \beta) \models \texttt{heap} \doteq anon(\texttt{hPre}, \{\texttt{heap} := \texttt{hPre}\} mod, \texttt{heap}),$$

which because of the definition of s_1^{new} is the same as

$$(\mathcal{K}, s_1, \beta) \models h^{new} \doteq anon(h^{base}, \{\texttt{heap} := h^{base}\} mod, h^{new}).$$
(31)

Let $C = \delta(s_1^{base}(\texttt{this}))$. This means that

$$(\mathcal{K}, s_1^{base}, \beta) \models exactInstance_C(\texttt{this}). \tag{32}$$

Let $\mathcal{K}' = (\mathcal{D}, \delta, I', \mathcal{S}, \rho)$ be a Kripke structure identical to \mathcal{K} , except that $I'(h) = val_{\mathcal{K},s_{1},\beta}(h^{new})$. Since $\alpha(\texttt{this}) = A$, we have $C \sqsubseteq A$. Instantiating (26) with C, \mathcal{K}' and s_1^{base} yields

$$\begin{split} (\mathcal{K}', s_1^{base}, \beta) &\models pre \land reachableState \land exactInstance_C(\texttt{this}) \\ &\rightarrow obs(\texttt{heap}, \texttt{this}, \texttt{p}_1, \dots, \texttt{p}_n) \\ &\equiv \{\texttt{heap} := anon(\texttt{heap}, mod, h)\} \\ &\quad obs(\texttt{heap}, \texttt{this}, \texttt{p}_1, \dots, \texttt{p}_n). \end{split}$$

As h does not occur in (28) or (32), we have $(\mathcal{K}', s_1^{base}, \beta) \models pre \wedge reachableState \wedge exactInstance_C(this)$ by Prop. 2, which we can combine with the statement above to get

$$\begin{split} (\mathcal{K}', s_1^{base}, \beta) &\models obs(\texttt{heap}, \texttt{this}, \texttt{p}_1, \dots, \texttt{p}_n) \\ &\equiv \{\texttt{heap} := anon(\texttt{heap}, mod, h)\} obs(\texttt{heap}, \texttt{this}, \texttt{p}_1, \dots, \texttt{p}_n). \end{split}$$

Applying the update yields

$$\begin{split} (\mathcal{K}', s_1^{base}, \beta) &\models obs(\texttt{heap}, \texttt{this}, \texttt{p}_1, \dots, \texttt{p}_n) \\ &\equiv obs(anon(\texttt{heap}, mod, h), \texttt{this}, \texttt{p}_1, \dots, \texttt{p}_n). \end{split}$$

Because of the definition of s_1^{base} , this is the same as

$$\begin{split} (\mathcal{K}', s_1, \beta) &\models obs(h^{base}, \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n) \\ &\equiv obs(anon(h^{base}, \{\mathtt{heap} := h^{base}\} mod, h), \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n). \end{split}$$

By definition of \mathcal{K}' , we have $I'(h) = val_{\mathcal{K},s_1,\beta}(h^{new})$. As h does not occur in h^{new} , and as \mathcal{K} and \mathcal{K}' are otherwise identical, Prop. 2 guarantees that $val_{\mathcal{K},s_1,\beta}(h^{new}) = val_{\mathcal{K}',s_1,\beta}(h^{new})$. Thus, we have $I'(h) = val_{\mathcal{K}',s_1,\beta}(h^{new})$, and can thus write the statement above as

$$\begin{split} (\mathcal{K}', s_1, \beta) &\models obs(h^{base}, \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n) \\ &\equiv obs(anon(h^{base}, \{\mathtt{heap} := h^{base}\} mod, h^{new}), \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n). \end{split}$$

As the function symbol h does not occur in the above formula, and as \mathcal{K} and \mathcal{K}' are otherwise identical, Prop. 2 tells us that

$$\begin{split} (\mathcal{K}, s_1, \beta) &\models obs(h^{base}, \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n) \\ &\equiv obs(anon(h^{base}, \{\mathtt{heap} := h^{base}\} mod, h^{new}), \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n). \end{split}$$

We can combine this with (31) to get

$$(\mathcal{K}, s_1, \beta) \models obs(h^{base}, \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n) \equiv obs(h^{new}, \mathtt{this}, \mathtt{p}_1, \dots, \mathtt{p}_n),$$

which contradicts (30).

References

- J. Gosling, B. Joy, G. Steele, and G. Bracha. The Java Language Specification, Second Edition. Addison-Wesley, 2000.
- P. H. Schmitt, M. Ulbrich, and B. Weiß. Dynamic frames in Java dynamic logic. In B. Beckert and C. Marché, editors, *Proceedings, International Conference on Formal Verification of Object-Oriented Software (FoVeOOS 2010)*, LNCS. Springer, 2010. To appear.