

Application of the situational management methods to ensure safety in intelligent transport systems

Makarova I., Pashkevich A., Mukhametdinov E., Mavrin V.
Kazan Federal University, 420008, Kremlevskaya 18, Kazan, Russia

Abstract

Copyright © 2017 by SCITEPRESS-Science and Technology Publications, Lda. All rights reserved. The article shows directions of intellectualization of vehicles, analyzed issues and ways to improve safety, reliability and sustainability of transport systems. Methods of situational management are shown. They are based on intelligent technologies for improving safety of complex technical systems. Development and application of precedent expert systems is actual for systems with incomplete information and high complexity of object of management. Such systems reflect decisions by analogy, i.e. according to reports of critical situations, which are potentially dangerous for this object. The object-oriented case model describing the dynamics of dangerous conditions object is developed. Measures on prevention, localization and mitigation of dangerous conditions (such as identification of the dangerous conditions, identify their causes, the safety evaluation, forecasting of development scenarios) are envisaged.

Keywords

Autonomous vehicle, Intelligent transport system, Road safety, Road transport, Situational management

References

- [1] Antov, D. et al., 2007. Investigating drivers' behaviour at non-signalised pedestrian crossings. *The Baltic Journal of Road and Bridge Engineering* 3 pp. 111-118.
- [2] Costello, T.M. et al., 2009. Risk factors for a farm vehicle public road crash. *Accident Analysis and Prevention*. 41 pp. 42-47.
- [3] Durech, J. et al., 2016. Modelling of Security Principles within Car-To-Car Communications in Modern Cooperative Intelligent Transportation Systems. *Information and safety-related systems*, vol. 14. num. 1. pp. 49-58.
- [4] Etherington, T.J. et al., 2016. Quantifying pilot contribution to flight safety for normal and non-normal airline operations. *35th Digital Avionics Systems Conference*.
- [5] Franzè, G., Lucia W., 2015. The obstacle avoidance motion planning problem for autonomous vehicles: A low-demanding receding horizon control scheme. *Systems & Control Letters* 77 pp.1-10.
- [6] Goniewicz, K. et al., 2016, Road accident rates: strategies and programmes for improving road traffic safety. *Eur J Trauma Emerg Surg* pp. 42:433-438.
- [7] González D. et al., 2016. A Review of Motion Planning Techniques for Automated Vehicles. *IEEE Transactions on intelligent transportation systems*, vol. 17, no. 4, pp.1135-1145.
- [8] Le Vine, Scott et al., 2015. Autonomous cars: The tension between occupant experience and intersection capacity. *Transportation Research Part C* 52 pp. 1-14.

- [9] Ma Zh. et al., 2015. Exploring factors contributing to crash injury severity on rural two-lane highways. *Journal of Safety Research* 55 pp. 171-176.
- [10] Makarova, I. et al. 2016. Ensuring sustainability of the city transportation system: problems and solutions. *E3S Web of Conferences (ICSC 2016)*. Vol. 6.
- [11] Moran, M. et al., 2010. Causes of road accidents as perceived by Arabs in Israel: A qualitative study. *Transportation Research Part F* vol.13, pp. 377-387.
- [12] Ohn-Bar, E., Trivedi M.M., 2017. Are all objects equal? Deep spatio-temporal importance prediction in driving videos. *Pattern Recognition* 64 pp.425-436.
- [13] Peek-Asa, C. et al., 2010. Teenage driver crash incidence and factors influencing crash injury by rurality. *Journal of Safety Research* 41 pp. 487-492.
- [14] Richardson, N. et al., 2016. Assessing Truck Drivers' and Fleet Managers' Opinions Towards Highly Automated Driving. Vol. 484 of the book series *Advances in Intelligent Systems and Computing* pp. 473-484.
- [15] Schoettle, B. & Sivak M., 2015. Potential Impact of Self-Driving Vehicles on Household Vehicle Demand and Usage. Report No. UMTRI-2015-3. 16p.
- [16] Steinberger, F. et al., 2016. The antecedents, experience, and coping strategies of driver boredom in young adult males. *Journal of Safety Research* 59 pp.69-82.
- [17] Vanlaar, W., Yannis, G., 2006. Perception of road accident causes. *Accident Analysis and Prevention* 38 pp. 155-161.
- [18] Vilca, J. et al., 2015. Optimal Multi-Criteria Waypoint Selection for Autonomous Vehicle Navigation in Structured Environment. *Journal of Intelligent & Robotic Systems*. pp 1-24.
- [19] Xu, Ch. et al., 2013. Development of a Crash Risk Index to Identify Real Time Crash Risks on Freeways. *KSCE Journal of Civil Engineering* 17(7):1788-1797.