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3	Living on the edge: biofilms developing in oscillating environmental conditions
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20 Abstract

21 For the first time, densities and diversity of microorganisms developed on the ocean glider 22 were investigated using flow cytometry and Illumina MiSeq sequencing of 16S and 18S rRNA 23 genes. Ocean gliders are autonomous buoyancy-driven underwater vehicles, equipped with 24 sensors continuously recording physical, chemical, and biological parameters. Biofilms on 25 the glider were exposed to periodical oscillations of salinity, oxygen, temperature, pressure, 26 depth and light, due to periodic ascending and descending of the vehicle. Among the 27 unpainted surfaces, the highest microbial abundance was observed on the bottom of the glider's body, while the lowest density was recorded on the glider's nose. Antifouling paints 28 29 had the lowest densities of microorganisms. Multidimentional analysis showed that 30 microbial communities formed on unpainted parts of the glider shared some similarity with 31 non-toxic paint but they were significantly different from ones on toxic antifouling paint and 32 seawater. 33

Keywords: biofilm, antifouling, chitosan, next generation sequencing, ocean glider, IndianOcean.

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38 Introduction

39 Ocean gliders are a relatively recent tool in oceanography, which allow autonomous 40 collection of long-term oceanographic data over long distances (Figure 1A). Ocean gliders 41 are autonomous buoyancy-driven autonomous underwater vehicles (AUV), equipped with 42 sensors continuously recording physical, chemical, and biological parameters. Compare to 43 other AUV, the lithium sulfuryl chloride battery enables ocean gliders to be operational for 44 up to 10 months and powers different sensors that can be directly controlled by an 45 operator. The examples of sensors typically installed on ocean gliders include temperature, 46 salinity, oxygen and chlorophyll sensors (Eriksen 2001). During the collection of the data, 47 ocean gliders can dive from the surface to the sea bottom through changes in their 48 buoyancy (Figure 1B). At such times, the glider and, in particular, its sensors may be 49 vulnerable to transient biofouling. Intensity of biofouling on ocean gliders depends on the 50 environment (Lobe et al. 2010). Generally, more organisms accumulate on surfaces in 51 tropical waters compare to temporal ones (Moline and Wendt 2011).

52 Marine biofouling is the undesirable growth of organisms on submerged surfaces 53 (Wahl 1989). Any clean artificial substrata will be colonized by bacteria and later by diatoms 54 and other microscopic unicellular eukaryotes within hours after submersion (Salta et al. 55 2013). At this stage, a well-developed biofilm will be formed composed of multiple species 56 of prokaryotic and eukaryotic organisms with dominance of bacteria and diatoms 57 (Dobretsov 2010).

58 Biofouling has huge economic impacts on maritime industries. Worldwide, countries 59 spend billions of dollars in order to manage and prevent this problem (Callow and Callow 60 2011). Biofouling may significantly increase vehicle drag of the ocean glider, interfere with 61 the stability of the scientific sensors and limit good data collection (Davis et al. 2003; 62 Medeot et al. 2011). In order to prevent biofouling, maritime industries use biocides or 63 other toxic compounds applied as antifouling paints (Yebra et al. 2004; Lobe et al. 2010). 64 Biocidal paints kill marine organisms and cause undesirable environmental impacts, hence 65 new low toxic and non-toxic antifouling paints are urgently needed.

In this regard, chitosan has been proposed as a promising non-toxic antifouling agent
 (Pelletier et al. 2009) due to its antimicrobial properties (Kim and Rajapakse 2005). Chitosan
 is a naturally occurring linear polysaccharide composed of D-glucosamine and N-acetyl-D-

69 glucosamine obtained by deacetylation of crustacean waste (Xiao 2012). Our previous 70 laboratory and mesocosm experiments showed that chitosan led to a reduction of densities 71 of diatoms and bacteria on experimental paints (Al-Naamani et al. 2017). Another study 72 demonstrated that chitosan-based paints reduced growth of bacteria for 4 days and 73 inhibited densities of photosynthetic organisms for 14 days in northern estuarine waters 74 (Pelletier et al. 2009). Antifouling properties of chitosan have not been studied in long-term 75 field marine experiments in tropical waters.

76 The Sea of Oman, previously known as the Gulf of Oman, is situated between the 77 shallow, (less 50 m) high salinity waters of the Arabian Gulf and the deeper (>1000 m) 78 Arabian Sea, and hence possesses a unique hydrological regime (Al-Hashmi et al. 2010; 79 Banse 1997; Vic et al. 2015). One of the most intensive coastal upwelling phenomena in the 80 world characterizes Oman coastal waters (Reynolds 1993; Al-Hashmi et al. 2010). The 81 circulation is driven by reversing summer and winter monsoons, impacting the depth of high 82 salinity Persian (Arabian) Gulf outflow water and exchanging at the eastern boundary with 83 the Arabian Sea (Vic et al. 2015). The unique circulation and high production in the Sea of 84 Oman create an oxygen minimum zone where there is almost no oxygen in the water 85 column (< 2 μmol kg⁻¹, Banse and Piontkovski 2006; Piontkovski et al. 2017). The Sea of 86 Oman provides a unique opportunity to investigate formation of microbial biofilms on ocean 87 gliders at the gradients of salinity, temperature, oxygen and pressure.

In this study, we investigated the formation of microbial biofilms on coated and uncoated parts of an ocean glider during its deployment in the Sea of Oman. Biofilms developed on the glider over 3 months and were exposed to continuous variations of salinity, oxygen, light, temperature and pressure. The main objectives of this study were to investigate: 1) the composition of prokaryotic and eukaryotic communities formed on painted and unpainted parts of the glider, and 2) the antifouling effect of commercial and non-toxic experimental paints.

95

96 Material and methods

97 Ocean glider's deployment

A Kongsberg ocean glider was deployed 5km off the coast of Muscat, Oman, at 23°41.66'N,
58°40.7'W (Figure 1C) on 4th of March 2015 and was retrieved on 3^d of June 2015 (at
23°43.01'N, 58°39.7'W). The intention was to collect data throughout the end of the North-

101 East monsoon and the onset of the spring inter-monsoon period. The ocean glider consisted 102 of an aluminium pressure hull surrounded by a flooded fiberglass fairing. The body of the 103 instrument was not coated with any specific antifouling agents. Yellow coloured fiberglass 104 maximises durability and visibility of the glider at the sea. A total of 712 dives with 1424 105 vertical profiles of environmental parameters covering over 2080 km and repeating the 106 survey transects 24 times out over a period of 91 days were carried out. The ocean glider 107 was equipped with a Seabird free-flushing CT sail, an Aanderaa 4330F oxygen optode, a 108 Biospherical QSP-2150 PAR sensor (spectral region - 400-700 nm), a Wetlabs Triplet ECO 109 sensor measuring chlorophyll *a* (based on fluorescence intensity) and backscatter at 470 and 110 700 nm (Piontkovski et al. 2017). Satellite communication was used for retrieval of the data 111 in near real time after every dive at a speed of about 25 cm s⁻¹.

112

113 Paints

114 In total, five different coatings were tested (Table 1). These include two types of biocidal 115 antifouling paints (International Micron Extra YBA 920 and Hempel Olympic 86950, later 116 "paint", PIn and PHe), one experimental non-biocidal chitosan paint (later "paint", PCh) and 117 two primer base (Intershield 300 and Hempel primer, later "base", BIn and BHe). Base did 118 not contain biocides and served as controls for antifouling paints. Chitosan paint was 119 prepared according to Al-Naamani et al. (2007). Briefly, chitosan paints were made using 120 1.5% chitosan (Sigma Aldrich, UK) solution in 1% acetic acid (Sigma Aldrich, UK). The solution 121 was mixed for 10 min and then sonicated for 15 min. The fibreglass surface of the glider was 122 not protected with any specific antifouling agents (later "unprotected", U). Before 123 application of paints, the surface of the ocean glider was cleaned with ethanol (96%, Sigma, 124 USA). All paints were applied in strips (10 x 70 cm) at the top and bottom of the ocean glider 125 using brushes. The paints were air dried at room temperature for 24h before the glider was 126 deployed into the sea.

127

128 Sampling

On 3^d of June 2015, the ocean glider was gently lifted to the surface of the Research Vessel
 Al Jamiya, Muscat, Oman. Biofilms from the painted area ~700 cm² (paint and base, Figure
 1D) were scraped off using sterilized microscope slides and collected into individual sterile
 tubes. Remaining biofilms were washed with sterilized seawater and collected into the same

133 tube. Replicated samples of undisturbed biofilms were scraped off as described above from 134 unprotected parts of the ocean glider covering an area of ~500 cm²: top (UGT) and bottom (UGB) of the body, and the top of the wings (UWT) (Figure 1D, Table 1). Biofilms from the 135 136 bottom parts of the wings were disturbed during withdraw of the ocean glider and, thus, 137 were not sampled. The smaller areas (~100 cm²) were also sampled as described above from 138 the glider's nose (UN), the top tail wing (UTT) and the bottom tail wing (UTB) (Figure 1D). 139 Additionally, one-litre seawater samples (seawater) were collected on 3^d of June 2015 from 140 the area of the ocean glider retrieval with Niskin bottles (volume 5L) from the depth 15m 141 (SW1), 25m (SW2), 35m (SW3) and 50 m (SW4). Biofilm and water samples were 142 immediately brought on ice to the Sultan Qaboos University laboratories and processed (see 143 below).

- 144
- 145 Sample analysis
- 146 Abundance of microbes

147 Abundances of phytoplankton eukaryotes in water were determined by direct count in the 148 Niskin bottle samples using a Zeiss inverted microscope (Germany, 50× and 100× 149 magnification). The taxonomic composition of the phytoplankton eukaryotic community was 150 characterised according to Piontkovski et al. (2017). Abundance of prokaryotes in each 151 sample was estimated using flow cytometry (FC). FC measurements were performed using 152 BD FACSAriaTM III (BD Biosciences, Franklin Lakes, NJ, USA). Before the analysis, each 153 sample was filtered through 40 µm nylon cell strainer Falcon[™] (Fischer Scientific, USA) to exclude large cells, cell clumps and detritus particles. Samples were stained with SYBR green 154 155 I stain (Molecular Probes, Invitrogen, Carlsbad, CA, USA, excitation/emission wavelengths: 156 497 nm/520 nm; dilution 1:10,000) and incubated for 10 minutes in the dark. Each sample 157 was divided onto three independent fractions. Thus, three independent FC readings were 158 recorded for each sample. The average number of cells ml⁻¹ for each sample was calculated. 159 The density of microorganisms on the surface of the ocean glider was calculated taking into 160 account the size of sampled area and the amount of liquid used to wash it. Densities of 161 prokaryotes in the water column at different sampling depths and on different parts of the 162 glider were compared using factorial analysis of variance (ANOVA) using Statistica 11 163 (Statsoft, USA). Normality of the data was verified using the Shapiro-Wilk's W test. Post-hoc 164 Tukey's HSD test was used to test significance of differences between microbial 165 abundances. In all cases, a *p* value < 0.05 was considered statistically significant.

166

167 DNA extraction and MiSeq analyses

168 The scraped samples from painted and unprotected surfaces of the glider were frozen and 169 kept at -80° C until the analysis of microbial community composition using next generation 170 sequencing. Prior to DNA extraction, water samples were filtrated through 0.2 µm Whatman 171 (USA) filter. DNA from each sample from the glider and water column was extracted using a 172 Power Biofilm (MoBio, USA) kit following the manufacturer's instructions. Purified DNAs 173 were analysed at the Molecular Research (MRDNA) company (Shallowater, TX, USA). 174 Illumina MiSeq was used to sequence the 16S and 18S rRNA genes. Bacterial V3-V4 regions 175 of 16S rRNA genes were sequenced using the primers 515F (5'-GTGCCAGCMGCCGCGGTAA-176 3') and 806R (5'-GGACTACHVGGGTWTCTAAT-3'). Eukaryotic 18S rRNA genes were 177 sequenced using the primers Euk7F (5'- AACCTGGTTGATCCTGCCAGT -3') and Euk570R (5'-178 GCTATTGGAGCTGGAATTAC-3').

179 Sequence data was processed using MRDNA analysis pipeline (MRDNA, Shallowater, TX, 180 USA). In summary, sequences were joined, barcodes were deleted. Then, sequences <150bp 181 and sequences with ambiguous base calls were removed. Sequences were de-noised. OTUs 182 generated and chimeras were removed. Operational taxonomic units (OTUs) were defined 183 by clustering at 3% divergence and 97% similarity. Final OTUs were taxonomically classified 184 using BLASTn against a curated database derived from RDPII and NCBI 185 (http://rdp.cme.msu.edu, http://ncbi.nlm.nih.gov).

186 Rarefaction curves and diversity indices (OTU richness, Chao-1 and ACE) were calculated using the Mothur software (Schloss et al. 2009). Statistical analysis of sequencing 187 188 data was carried out using the PAST program (Paleontological Statistics, ver. 1.47, 189 http://folk.uio.no/ohammer/past) and the R v.2.15.0 statistical platform using the Vegan 190 package. The table containing samples by OTUs was used to calculate pairwise similarities 191 among samples based on Bray-Curtis dissimilarity index (Clarke 1993). A multivariate 192 analysis of all samples was performed using multidimensional scaling (MDS) based on Bray-193 Curtis dissimilarities as between biofouling communities developed on paint, base, 194 unprotected and present in seawater. Ordination of the Bray-Curtis dissimilarities was 195 performed using non-metric MDS, with 100 random restarts, taking into account the

196 presence/absence, as well as the relative abundance of OTUs in all samples. The MDS 197 results were plotted in two dimensions. Analysis of similarities (ANOSIM) with Bonferroni 198 corrected P values was carried out to test for significant differences between the defined 199 sample groupings. ANOSIM produces a sample statistic R, which represents the degree of 200 separation between test groups (Clarke 1993). Similarity percentage (SIMPER) analysis was 201 performed using the PRIMER[®] software to compare microbial communities from seawater, 202 coated with paint and base, as well as unprotected parts of the glider. OTU partitioning was 203 used to find out the number of OTUs that are specific for each dataset in the MDS analysis 204 and the number of shared OTUs between different datasets. This was done on OTUs 205 datasets using Microsoft Excel and a custom R script.

206

207 **Results**

208 Environmental parameters

209 During the study, the ocean glider dove from the surface to a depth of 1015m. Vertical 210 profiles of physical, chemical and biological characteristics recorded by the glider showed 211 high variability during the study period (Supplementary Figure S1). This variation was 212 attributed to the movement of the ocean glider and of mesoscale eddies, as well as seasonal 213 changes.

The average seawater temperature during the period of investigation varied from 215 27.8° to 12.2° C (Figure S1A). As expected, the highest temperatures were recorded at the 216 surface, while the lowest ones were measured at depth > 560m. The averaged vertical 217 temperature profile implied that the surface mixed layer extended to ~25m and followed by 218 the seasonal thermocline (Figure S1A). In turn, the thermocline layer was underlined by the 219 Persian (Arabian) Gulf waters, with the core at 250m. This water mass, located between 150 220 and 350 m, flowed eastward.

The vertical profile of salinity differed from that of temperature (Figure S1B). The highest salinity of 36.9 ppt was recorded at the depth of ~260m, co-occurring with the Gulf outflow, while the lowest salinity was found at depth. The average salinity varied from 35.7 to 36.9 ppt during this study.

The photosynthetically active radiation (PAR) varied from 0 to 2400 μ E m⁻² sec⁻¹, during thus study. A characteristic feature in the vertical distribution of the fluorescence intensity was the fluorescence peak observed at ~30-40m deep, persisting throughout the

deployment period (Figure S1C). This peak was formed by the phytoplankton community
 dominated by the dinoflagellate *Noctiluca scintillans* (see abundance of microbes).

230 Vertical distribution of the dissolved oxygen concentration showed a decline from 231 saturated surface water (~220 μ mol kg⁻¹) to near anoxic conditions in the oxygen minimum 232 zone (< 2 μ mol kg⁻¹; below 400m). This pattern was interrupted by the outflow of Gulf 233 water, injecting high salinity oxygenated water (~140 μ mol kg⁻¹) between 150 and 350 m 234 (Figure S1D).

235

236 Abundance of microbes

Taxonomic analysis of Niskin seawater samples collected within the layer of fluorescence peak (see Figure S1C) showed the presence of the dinoflagellate *Noctiluca scintillans*. This species made up about 90% of the total phytoplankton abundance (data are not shown). As for the upper mixed layer, processed samples showed that *Noctiluca* abundance was equal to ~120,000 cell L⁻¹ at the beginning of the experiment. At the end of the study, *Noctiluca* abundance became ~20,000 cell L⁻¹.

243 The highest densities of microorganisms were recorded at a depth of 35 m, which 244 correlated well with the presence of N. scintillans (Figure 2). The densities of microorganisms at the other depths were 14-fold to 23-fold lower. Densities of 245 246 microorganisms on the ocean glider were significantly (ANOVA p<0.05) different (Figure 2). 247 Among unprotected surfaces, the highest density of prokaryotes was observed on the ocean 248 glider bottom (UGB) followed by the glider's wing (UWT) and the glider's top (UGT). The 249 lowest density (HSD p<0.05) was recorded on the glider nose (UN). Among paints, the 250 lowest density (HSD p<0.05) of microorganisms was found on PChT. The densities of 251 microbes on the top and bottom surfaces were different (ANOVA p<0.05; Figure 2). There 252 were significant differences (HSD p<0.05) in the densities of microbes on different bases 253 tested; 3-fold higher densities were observed on BIn in comparison to that on BHe. The 254 density on BIn was 1.5–2-fold lower (HSD p<0.05) than on the unprotected glider (UG) 255 surfaces. The densities of microbes on antifouling paints (PInB) were 1.3-fold lower than on 256 UGB (Figure 2). There was a significant difference between densities of microorganisms in 257 biofilms collected from the top and the bottom of the unprotected parts of the ocean 258 gliders (HSD p<0.05). Generally, the density of microbes was lower on the top of the glider than on the bottom (Figure 2). Similarly, the density of microbes on PInT was 9-fold lower
(HSD *p*<0.05) than the density on the same paint located at the bottom of the glider (PInB).

261

262 Microbial diversity

263 A total of 1,259,486 and 584,473 of 16S and 18S rDNA sequences, respectively, were 264 obtained by Illumina MiSeq sequencing (Table 2). The lowest number of OTUs was observed 265 on the ocean glider wing (UWT) and the highest number – on the primer BHeT (Table 2). A 266 similar pattern was observed for Chao-1 and ACE indices. For eukaryotic communities, the 267 highest number of sequences was found on the bottom of the ocean glider top tail (UTT), 268 while the lowest number – on the bottom of the tail (UTB). The highest number of OTUs and 269 the highest diversity Chao-1 and ACE indices were observed on the antifouling paint PInB 270 and the lowest at the bottom of the glider's top tail (UTT) (Table 2).

The bacterial communities that developed on paints, base and uncoated surfaces had 1158 OTUs in common. The eukaryotic communities shared 355 OTUs (Figure 3). The highest number of unique bacterial OTUs was observed for paints, while the lowest one was found in biofilms on base. For eukaryotic communities, biofilms developed on unprotected parts of the glider had 138 unique OTUs, while the numbers of OTUs on base and antifouling paints were lower (Figure 3).

277 Multidimentional analysis (MDS) showed that bacterial communities formed on the 278 ocean glider and present in seawater were different (Figure 4), which was supported by 279 ANOSIM analysis (r=0.94, p=0.006). While bacterial communities formed on unprotected 280 parts of the glider (U) shared some similarity with the base (BIn and BHe) and the 281 experimental chitosan paint (PCh), they were different from the copper-based paints (PIn 282 and PHe) (Figure 4). Similar tendency was observed for eukaryotic communities. MDS 283 analysis showed that eukaryotic communities in the seawater and on the ocean glider were 284 significantly different (ANOSIM r=0.62, p>0.05). Eukaryotic communities formed on 285 unprotected and base surfaces shared some similarities, as well as communities from the 286 base and paints.

SIMPER analysis demonstrated that bacteria belonging to genera *Dasania, Pantoea* and *Vibrio* contributed from 14% to 22% of dissimilarity between communities developed on the ocean glider and existing in seawater (Table 3). Additionally, bacterial communities formed on unprotected and base surfaces differed by the presence of the genera *Exiguobacterium*. Eukaryotes belonging to Bacillariophyceae and Hydrozoa accounted for more than 21% each between communities developed on the glider and existing in seawater (Table 4). Additionally, Holozoa (Ichthyosporea) and different fungi (Agaricomycetes and Dothideomycetes) contributed for more than 10% each for dissimilarities between eukaryotic communities.

296 Bacteria belonging to the classes Gamma- and Alpha-proteobacteria dominated 297 biofilms developed on the ocean glider during the experiment (Figure 5A). These were 298 mainly represented by the genera Vibrio, Pseudomonas, Alteromonas, Marinobacter, 299 Dasania, Teredinibacter and Cycloclasticus (Gamma-proteobacteria), Pseudoruegeria, 300 Parvibaculum, Sphingomonas, Hyphomonas, Erythrobacter and Tateyamaria (Alpha-301 proteobacteria). The class Bacilli (mainly genus Exiquobacterium) was abundant on all 302 unprotected parts of the ocean glider. Sequences belonging to chloroplasts of diatoms 303 (Bacillariophyceae and Fragillariophyceae) were detected. There were clear difference 304 between the compositions of bacterial communities developed on antifouling paints, base 305 and unprotected parts of the ocean glider (Figure 5A). Copper-based antifouling paints had 306 high (51-66%) relative abundance of Gamma-proteobacteria. Among antifouling paints, the 307 chitosan paint (PChT and PChB) were characterized by the lower relative abundance of 308 Gamma-proteobacteria (14-33%) and the higher relative abundance of Beta-proteobacteria 309 (28-29%). Bacteria belonging to the genera Dasania, Erythrobacter and Cycloclasticus were 310 the most common on paints containing copper. In contrast, *Ralstonia* sp. was dominant on 311 chitosan experimental paint (PCh) and base. Among base, the high relative abundance of 312 Beta-proteobacteria was observed on BHeT and BHeB, while the high abundance of Bacilli 313 was observed on BInT and BInB. The bacterial genera Pantoea and Exiguobacterium were 314 dominant on base and unprotected parts of the ocean glider. Different unprotected parts of 315 the ocean glider had distinct communities. For example, biofilms on the wing (UWT) 316 dominated with Gamma-proteobacteria (85%), while the lower relative abundance of Alpha-317 proteobacteria (7%) and Bacilli (7%) was also recorded. On the other hand, there were no 318 Bacilli in the biofilms on the glider's nose (UN).

Eukaryotic communities on the ocean glider were highly diverse and represented by different groups of fungi, microalgae, nematodes, arthropods and hydrozoans (Figure 5B). Sequences of some macrofouling genera, such as *Megabalanus, Hydractinia, Actinostola, Dicoryne* were found. Additionally, sequences belonging to some planktonic species, like

323 *Nectopyramis* sp. (Siphonoporae) were detected. Hydrozoa had high relative abundance on 324 base (BInB 58%; BHeT 79%), the glider's nose (UN 79%) and the antifouling paint (PInB 53%). 325 High fungal diversity (represented by 5 different classes) in marine biofilms was detected 326 (Figure 5B). The fungal class Agaricomycetes was highly abundant (relative abundance 72%) 327 on paint PHeT, while the class Dothideomycetes (relative abundance 46%) and 328 Eurotiomycetes (relative abundance 14%) were highly abundant on unprotected parts 329 (UTB). The relative abundance of the fundal class Sordariomycetes on the antifouling paint 330 PHeB was 7%. The highest relative abundance (89%) of the class Ichtyosporea 331 (Mesomycetozoea, Holozoa) on PInT was recorded (Figure 5B). Diatoms (Bacillariophycaea), 332 mainly Amphora and Cylindrotheca species, dominated biofilms on the ocean glider 333 unprotected surfaces (UWT 82% and UTT 94%), chitosan paint (PChB 71%; PChT 59%) and 334 base (BInT 73%). More than half of the sequences (54%) obtained from the unprotected 335 bottom of the ocean glider (UGB) belonged to Chlorophyta (*Pycnococcus* sp.).

336

337 Discussion

This is the first study that investigated microbial fouling on the ocean glider by next generation sequencing. Previous studies reported presence of macrofouling organisms on ocean gliders (Nicholson et al. 2008; Moline and Wendt 2011), but neglected microbial biofilms, which may also affect the performance of the glider and its sensors (Davis et al. 2003; Cetinic et al. 2009).

343 During the study period, vertical profiles of temperature, oxygen, chlorophyll and 344 salinity showed high variability. The study area is highly influenced by three hydro-345 dynamical processes: (1) the outflow from the Persian (Arabian) Gulf, (2) the inflow from the 346 northern Arabian Sea, and (3) the mesoscale (cyclonic and anti-cyclonic) eddies persisting in 347 the region (across the Gulf) and connecting the northern-banked inflow and the southern-348 banked outflow (Al-Hashmi et al. 2010; Vic et al. 2015). Thus, we assume that variations of 349 the physical and biological parameters in the study region could be attributed to the spatial 350 shifts in the location of the mesoscale eddy affecting regional circulation over the shelf in 351 Muscat region. Additionally, seasonal changes (i.e. increase of temperature from March to 352 June) have affected vertical profiles of the physical and biological parameters (Piontkovski et 353 al. 2017).

354 Biofilms on the surface of the ocean glider were exposed to continuous 355 fluctuations of oxygen (0 – 287 μ mol kg⁻¹), temperature (12.2- 32.3° C), salinity (35.4-38.0 356 ppt), depth (0- 1015 m), pressure (0.04- 102 Bar) and light intensity (0- 2400 µE m⁻² sec⁻¹) 357 for more than 3 months. We expected that microbes on the glider would differ from those 358 in the water column. Indeed, as shown by the MDS plots, the composition of bacterial and 359 eukaryotic organisms on the ocean glider and in the water column was very different. 360 Previously it was reported that attached and particle-bind bacteria are more abundant and 361 more metabolically active than unattached bacteria (Kirchman and Mitchell 1982; Dang and 362 Lovell 2016). The densities of microorganisms on the glider's surface varied from 8,820 to 363 228,000 cell/mm². Among unprotected surfaces the lowest densities of microbes were 364 found on the nose of the ocean glider (UN). Probably, it is due to the higher dynamic 365 pressure and velocities on that part of the glider (Isa et al. 2014; Chen et al. 2015). 366 Additionally, the densities of microorganisms on the top of the ocean glider were generally 367 lower than on the bottom. The orientation of different parts of the ocean glider could affect 368 the densities of microbes (Bellou et al. 2012).

369 Ocean glider's parts painted with antifouling paints had lower densities of 370 microorganisms than unprotected parts of the glider. This is not surprising, as antifouling 371 paints contain chemical compounds that kill or prevent growth of microfouling organisms 372 (Casse and Swain 2006; Mollino et al. 2009; Briand et al. 2012; Briand et al. 2017). The 373 lowest densities of microorganisms were observed on the antifouling paints PHeT and PHeB 374 that contained biocides cuprous oxide and zineb. In previous studies, both biocides were 375 recognised as effective antifouling agents (Hunter and Evans 1991). Among 11 commercial 376 antifouling paints tested during a 1 year study in Oman coastal waters, the lowest microbial 377 biomass was recoded on the paint with these biocides (Muthukrishnan et al. 2014).

378 Compared to other studies of marine biofilms on artificial surfaces utilizing the 379 Illumina MiSeg technique, the diversity of communities formed on the ocean glider was 380 similar to that found in Australia (Tan et al. 2015) and Swedish (Oberbeckmann et al. 2016) 381 coastal waters. Bacteria belonging to the classes Gamma- and Alpha-proteobacteria, mostly 382 Vibrio, Pseudomonas, Teredinibacter, Cycloclasticus, Pseudoruegeria, Parvibaculum, 383 Sphingomonas, Erythrobacter and Tateyamaria, dominated in biofilms. Similarly, previous 384 investigations demonstrated the dominance of Alpha- and Gamma-proteobacteria in marine 385 biofilms on various artificial substrata (Dobretsov et al. 2013; Tan et al. 2015; Sathe et al. 386 2016; Flach et al. 2017; Hunsucker et al. 2018). Differences between bacterial communities 387 developed on the ocean glider were due to the genera Dasania, Pantoea, Exiguobacterium 388 and Vibrio as indicated by SIMPER analysis. Dasania are obligately aerobic bacteria (Lee et 389 al. 2007), which previously found associated with the deep sea tubeworm (Forget and 390 Juniper 2013). Exiguobacterium profundum was previously isolated from a deep sea 391 hydrothermal vent (Crapart et al. 2007). This might suggest possible adaptations of these 392 bacteria to high pressure and low oxygen conditions. Archaea dominate deep sea waters 393 (De Long 1992; Jensen et al. 2012) but this group was not detected in this study. While the 394 universal 16S RNA 515F/806R primers used in this research have been used to study both 395 archaea and bacteria (Bates et al. 2010; Walters et al. 2011), it is possible that the absence 396 of archaea in this study was due to poor amplification of this group of microorganisms (Eloe-397 Fadrosh et al. 2016).

398 Eukaryotic communities on the ocean glider were predominantly represented by 399 fungi, hydrozoans and arthropods. While only biofilms were observed on the glider, 400 sequences of macrofouling organisms, such as the barnacle Megabalanus sp. and the 401 hydrozoan *Hydractinia* sp., might indicate recruitment of these species on the ocean glider. 402 Barnacles are reported as the main fouling species on ocean gliders (Lobe et al. 2010). 403 Additionally, sequences of photosynthetic species belonging to the classes Bacillariophyta, 404 Dinophycae, Chlorophyta and Mediophycae were recorded. This might indicate that some 405 photosynthetic species on the ocean glider, like Amphora sp. and Cylindrotheca sp., can 406 sustain some time without light. It has been shown that the benthic diatoms Amphora 407 coffeaeformis and Cylindrotheca closterium can survive in the dark, anoxic conditions for 6-408 28 weeks (Kamp et al. 2011). The researchers have found that these diatoms accumulated 409 nitrate and used it for their respiration in the absence of oxygen and light.

410 The composition of microbial communities developed on paints, primer and 411 unprotected parts of the glider was different. This could be explained by different chemical 412 (chemical composition) and physical (wettability) properties of unprotected and coated 413 surfaces. For example, biologically and physically inert substrates, like glass, fouled quicker 414 and had more diverse communities than active substrates, like copper-nickel alloys 415 (Marszalek et al. 1979). 454 pyrosequencing of 16S genes revealed the presence of different 416 microbial communities on different antifouling paints (Muthukrishnan et al. 2014; Briand et 417 al. 2017). The copper antifouling paint resulted in significant changes in both bacterial and 418 eukaryotic communities in New Zealand waters (von Ammon et al. 2018). Similar results 419 were obtained in the experiments with plastic panels painted and not painted with 420 antifouling paints in Swedish waters (Flach et al. 2017). Bacteria belonging to 421 Cryomorphaceae and Alcanivoraceaea were exclusively present on polyethylene 422 terephthalate but not on glass surfaces in another study in the North Sea (Oberbeckmann et 423 al. 2016). In our study, bacteria belonging to the genera Dasania, Erythrobacter and 424 Cycloclasticus were common on antifouling paints containing cuprous oxide. While the 425 genus Dasania was previously detected on antifouling paints, the genus Erythrobacter was 426 observed in biofilms on cuprous oxide antifouling paints (Muthukrishnan et al. 2014). 427 *Cycloclasticus* was one of the two most abundant genera in biofilms on antifouling paints 428 exposed to fouling in Swedish coastal waters (Flach et al. 2017). This could suggest that 429 bacteria belonging to Dasania, Erythrobacter and Cycloclasticus are commonly associated 430 with antifouling paints.

431 Bacterial and eukaryotic communities on the chitosan paint were different from 432 other antifouling paints. Differences in antifouling mechanisms can explain differences 433 between community composition of chitosan and copper-based paints. Copper-based paints 434 kill microorganisms due to the displacement of essential metals in proteins (Thurman et al. 435 1989). Copper ions may alter enzyme and nucleic acids structure and function, facilitate 436 their hydrolysis and have an adverse effect on oxidative phosphorylation and osmotic 437 balance (Borkow and Gabbay 2005). On the other hand, chitosan inhibits biofouling due to 438 its cationic nature and interactions with positively charged microbial cell membranes 439 (Alisashi and Aider 2012).

The current study was conducted using one ocean glider. While the replicated samples were collected, these cannot be treated as true replicates. It is partially difficult to replicate naval structures. There are several similar studies of biofilms on ship hulls that did not have true replicates (Hunsucker et al. 2014; Inbakandan et al. 2010; Zargiel et al. 2011). Gliders are expensive autonomous vehicles and cannot be easily replicated. In fact, we tried to have two independent replicates but the second ocean glider was lost during the experiment. Thus, conclusions of this study need to be treated with caution.

In conclusion, for the first time the presence of diverse microbial biofilms for med
 on the surface of the ocean glider exposed to oscillating environmental conditions was
 demonstrated using next generation sequencing techniques. Densities and compositions of

450 microbial communities on different parts of the glider were different, which could be 451 explained by differences in hydrodynamic conditions on different parts of the glider. 452 Additionally, chemical composition of unprotected surfaces and coated with base and paint 453 shaped the composition of microbial communities on the surface of the ocean glider. This is 454 the first attempt to investigate of biofouling on ocean gliders and much work is required in 455 the future to confirm our findings. Differential antifouling performance of paints, suggested 456 that proper antifouling solutions for long endurance autonomous underwater vehicles need 457 to be developed.

458

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465

466 **Disclosure statement**

467 The authors declare that they have no conflicts of interest related to this work.

468

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- 597

599 Figure legends

- 600 Figure 1. A. Ocean glider on the boat of the research vessel. B. The scheme of a glider's dive
- 601 (from http://www.kronberg.com and http://www.ueaseaglider.uea.ac.uk/DIVES/). C.
- 602 Google Map showing the sampling area. Insert: Location of ocean glider's transects in the
- 603 Sea of Oman. **D**. The sampled locations on the glider (modified from
- 604 http://auvac.org/platforms/view/160).
- 605
- 606 **Figure 2.** Total microbial abundance of microbial cells in seawater samples, on unprotected
- 607 ocean glider surface and coated with paints and base. Data are the mean + standard
- 608 deviation (SD). For the sample abbreviations, see Table 1.
- 609
- 610 **Figure 3.** Vienn diagram showing the number of shared and unique OTUs in bacterial and
- 611 eukaryotic communities developed on paints, base and the gilder's unprotected surface.
- 612
- 613 **Figure 4.** Multidimentional scaling (MDS) plots of bacterial and eukaryotic microbial
- 614 communities obtained from seawater and developed on the ocean glider. For the codes, see
- 615 Table 1.
- 616
- 617 **Figure 5.** Heat map showing the relative abundance (%) of the main **A**: prokaryotic and **B**:
- 618 eukaryotic classes present in biofilms developed on the ocean glider. For the codes, see
- 619 Table 1.
- 620
- 621
- 622







628 Figure 2



Eukaryotic communities







A





646 Figure 5

648 Tables

Table 1. Samples taken from the ocean glider and characteristics of paints used in this study650

Code	Treatment	Location Paint		Type of	Active		
				paint	ingredient		
РНеТ	Paint	Glidertop	Hempel Olympic	Biocidal	Cuprouse		
			86950		oxide and		
					Zineb		
PHeB	Paint	Glider	Hempel Olympic	Biocidal	Cuprouse		
		bottom	86950		oxide and		
					Zineb		
PInT	Paint	Glidertop	International	Biocidal	Cuprous oxide		
			micron extra		Dichlofluanid		
			YBA920				
PInB	Paint	Glider	International	Biocidal	Cuprous oxide		
		bottom	micron extra		Dichlofiuanid		
DCLT	Deint	Clistenten	YBA920	Nieve leteretelet	Chitaaaa		
PCHI	Paint	Gildertop	experimental	Non-biocidai	Chitosan		
DChD	Daint	Glidar	Evporimontal	Non biocidal	Chitocon		
PCIID	Faille	bottom	chitosan	NOII-DIOCIUAI	CHILOSan		
BInT	Base	Gliderton	Primer	Non-biocidal	No		
Biill	Dase	Glider top	Intershield				
			300				
BInB	Base	Glider	Primer	Non-biocidal	No		
		bottom	Intershield				
			300				
BHeT	Base	Glidertop	Hempel Primer	Non-biocidal	No		
			26050				
BHeB	Base	Glider	Hempel Primer	Non-biocidal	No		
		bottom	26050				
UGT	Unprotected	Glidertop	No	No	No		
UGB	Unprotected	Glider	No	No	No		
		bottom					
UTT	Unprotected	Glider's tail	No	No	No		
		wingtop					
UTB	Unprotected	Glider's tail	No	No	No		
		wing bottom					
UWI	Unprotected	Glider's	NO	NO	NO		
LINI	lloprotostad	wings top	No	No	No		
	unprotected	Gilder shose	INU	INU	INU		

Table 2. Amplicon library size and diversity estimators for bacterial and eukaryotic

- 654 communities of the samples using MiSeq. Operational taxonomic units (OTUs) at 3%
- 655 sequence dissimilarity were calculated based on equal subsets of sequences for all samples.

656 For the codes see Table 1.

	L	1	1						
Sample ID	B	acterial com	munities		Eukaryotic communities				
	No.of	No. of			No.of	No. of			
	sequences	OTUs 0.03	Chao-1	ACE	sequences	OTUs 0.03	Chao-1	ACE	
СТ	98674	762	1093	1088	36456	195	304	308	
CB	83526	707	1015	975	30834	281	404	414	
BT	82157	703	1047	1024	46547	207	313	311	
BB	93168	727	1059	1031	43754	313	439	449	
CHT	77260	701	1059	1055	30718	241	361	396	
CHB	44662	657	937	991	34850	205	325	338	
GT	100276	593	931	917	30879	289	395	361	
GB	101425	645	978	985	29418	228	363	344	
TT	110038	605	906	904	47224	156	297	286	
TB	69545	619	945	949	29047	188	283	277	
NT1	62828	840	1171	1240	40020	235	345	352	
W1	64661	561	946	912	36698	261	343	330	
PR1	81755	660	977	986	30779	226	307	320	
PR2	64634	628	957	984	45861	286	359	352	
PD1	63290	879	1142	1166	36206	245	364	364	
PD2	61587	766	1148	1134	35182	263	346	342	

- **Table 3.** The contribution of particular bacterial genera towards the total dissimilarity (in per
- 661 cent) between the bacterial communities using similarity percentage (SIMPER) analysis.

662 Groups with contribution \geq 2% are shown.

Paint vs. Control		Paint vs.	Base	Paint vs. Sea	Paint vs. Seawater Control vs. Base		Control vs. Seawater		Base vs. Seawater		
Taxon	Con trb. %	Taxon	Con trb. %	Taxon	Con trb. %	Taxon	Con trb. %	Taxon	Con trb. %	Taxon	Con trb. %
Dasania	21.7	Dasania	21.4	Dasania	22.8	Pantoea	22.6	Vibrio	21.1	Vibrio	21.4
Pantoea	14.6	Pantoea	16.7			Exiguoba					
Exiguoba	12.7	Ralstonia	13.6	Vibrio Erythrobac	20.3	cterium	14.7	Pantoea Exiguobact	16	Pantoea	14.4
cterium Erythrob	10.6	Erythrob	11.1	ter Alteromon	11.4	Ralstonia Pseudom	13.2	erium Alteromon	11.9	Ralstonia Alteromon	11.3
acter Pseudom	6.99	acter Exiquoba	8.86	as Cycloclastic	8.77	onas	9.29	as Pseudomo	9.75	as Exiguobact	10.0
onas Cvcloclas	4.72	cterium Cvcloclas	4.66	us Idiomarina	5.26	Dasania Sphinaob	6.40	nas	7.5	erium	7.60
ticus Pseudoru	3 77	ticus Pseudoru	3 68	Pseudoalte	4.40	ium Frythroh	3.97	Idiomarina Sphinaohiu	4.63	Dasania	5.41
egeria Sphinach	3 70	egeria Alteromo	3.00	romonas	4.10	acter Cycloclas	3.90	m Pseudoalte	4.52	Idiomarina Pseudoalte	4.67
ium Alteromo	2.96	nas Caulobac	3.40	geria Exiguolaet	3.78	ticus Caulobac	3.49	romonas Brevundim	4.31	romonas	4.35
nas Provundi	2.50	ter Marinoh	2.00	erium	3.59	ter Provundi	3.26	onas Sabingomo	2.72	ter	3.33
monas Gilvibact	2.44	acter Gilvibact	2.52	Pantoea	3.33	monas Enhydroh	3.18	nas	2.07	r Cucloclastic	2.75
er	2.19	er	2.27	Gilvibacter	2.16	acter	2.49			us	2.49
Marinob acter	2.10					Sphingo monas	2.41			Sphingobiu m	2.06
						Massilia	2.04				

Paint vs. Control		Paint vs. Base		Paint vs. Seawater		Control vs. Base		Control vs. Seawater		Base vs. Seawater	
Taxon	Contrb. %	Taxon	Contrb. %	Taxon	Contrb. %	Taxon	Contrb. %	Taxon	Contrb. %	Taxon	Contrb. %
Bacillariophyceae	21.5	Hydrozoa	25.05	Bacillariophyceae	22.56	Bacillariophyceae	26.43	Bacillariophyceae	26.43	Hydrozoa	25.49
Hydrozoa	16.81	Ichthyosporea	23.77	Ichthyosporea	18.18	Hydrozoa	25.54	Dothideomycetes	15.02	Bacillariophyceae	25.41
Ichthyosporea	16.25	Agaricomycetes	16.74	Agaricomycetes	14.51	Dothideomycetes	13.89	Hydrozoa	12.18	Ichthyosporea	10.02
Agaricomycetes	13.92	Bacillariophyceae	16.39	Hydrozoa	14.31	Ichthyosporea	9.358	Agaricomycetes	8.322	Agaricomycetes	6.903
Dothideomycetes	12	Mediophyceae	4.042	Chlorophyta	6.706	Chlorophyta	6.921	Dinophyceae	5.238	Maxillopoda	4.522
Chlorophyta	5.508	Sordariomycetes	2.538	Dinophyceae	4.657	Mediophyceae	3.704	Trebouxiophyceae	4.607	Trebouxiophyceae	4.271
Dinophyceae	2.245	Maxillopoda	2.063	Maxillopoda	4.316	Dinophyceae	2.537	Maxillopoda	4.035	Mediophyceae	4.04
Sordariomycetes	2.242			Trebouxiophyceae	3.754	Agaricomycetes	2.293	Bangiophyceae	2.299	Bangiophyceae	2.305
				Sordariomycetes	2.52			Arachnida	2.027	Arachnida	2.083
				Bangiophyceae	2.049						

Table 4. The contribution of particular eukaryotic taxis towards the total dissimilarity (in percent) between the bacterial communities using similarity percentage (SIMPER) analysis. Groups with contribution ≥ 2% are shown.

Supplementary

Figure S1. Vertical profiles of mean values of **A**: temperature, **B**: salinity, **C**: fluorescence intensity (λ = 695nm) and **D**: oxygen concentrations (µmol kg⁻¹) during the period of investigations. The data plotted until the depth of 650m, as measured parameters did not change after that depth. Dashed curves represented minimal and maximal values.

