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Vibration and buckling behaviours of thin-walled composite and functionally graded sandwich I-beams

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Abstract

The paper proposes a Ritz-type solution for free vibration and buckling analysis thinwalled composite and functionally graded sandwich I-beams. The variation of material through the thickness of functionally graded beams follows the power-law distribution. The displacement field is based on the first-order shear deformation theory, which can reduce to non-shear deformable one. The governing equations of motion are derived from Lagrange's equations. Ritz method is used to obtain the natural frequencies and critical buckling loads of thin-walled beams for both non-shear deformable and shear deformable theory. Numerical results are compared to those from previous works and investigate the effects of fiber angle, material distribution, span-to-height's ratio, and shear deformation on the critical buckling loads and natural frequencies of thin-walled I-beams for various boundary conditions.

Keywords: Ritz method; Vibration; Buckling; Thin-walled composite I-beams; Thin-walled functionally graded sandwich I-beams.

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1. Introduction

In recent years, composite and functionally graded materials are commonly used in many fields of mechanical, aeronautical and civil engineering. The most well-known advantages of these materials are high stiffness-to-weight and strength-to-weight ratios, low thermal expansion, enhanced fatigue life and good corrosive resistance. In addition to their extensive use in practice, the available literatures indicate that a large number of studies have been conducted to analyse behaviours of these materials [1-3] in which thin-walled composite and functionally graded (FG) sandwich structures have been considered ([4-11]). One of the first thin-walled beam theories have been presented by Vlasov [12] and Gjelsvik [13]. Bauld and Lih-Shyng [14] then extended Vlasov's thinwalled beam theory of isotropic material to the composite one. Pandey et al. [15] used Galerkin's method to solve the equilibrium differential equation for analysing of the flexural-torsional buckling of thin-walled composite I-beams. Buckling and free vibration of these beams were presented by Lee and Kim [16, 17] based on the finite element method (FEM) and classical beam theory. The FEM was used by Rajasekaran and Nalinaa [18] to investigate static, buckling and vibration behaviours of thin-walled composite beams with generic section. Maddur and Chaturvedi [19, 20] presented a Vlasov-type modified first-order shear deformation theory (FSDT) and analysed the dynamic responses of thin-walled composite open sections beams. Qin and Librescu [21] used an extended Galerkin's method to investigate natural frequencies and static responses of anisotropic thin-walled beams which account for shear deformation effects. A beam element based on the first-order shear deformable beam theory was developed by Lee [22] for the bending analysis of laminated composite I-beams under uniformly distributed loads. Machado and Cortinez [23] presented a stability analysis of thin-

walled composite I-beams with open and closed sections considering shear deformation effects. Vo and Lee [24] extended previous research [22] to study vibration and buckling of thin-walled open section composite beams. Dynamic stiffness matrix method also were used in the studies [25-28] to analyse vibration and buckling of the thin-walled composite beams. Silvestre and Camotim [29] used shear deformable generalised beam theory for buckling behaviours of lipped channel columns. Prokic et al. [30] proposed an analytical solution for free vibration of simply-supported thinwalled composite beams by using Vlasov's beam theory and classical lamination theory. Based on the Carrera Unified Formulation (CUF), Carrera et al. [31-35] analysed static, vibration and elastoplastic thin-walled composite structures. By using FEM, Sheikh et al. [36] conducted the study of free vibration of thin-walled composite beams having open and closed sections to investigate the shear effects. Li et al. [37] investigated hygrothermal effects on free vibration of simply-supported thin-walled composite beams by using Galerkin's method. Recently, the thin-walled FG beams have caught interests of many researchers. Nguyen et al. [38, 39] analysed vibration and lateral buckling of the thin-walled FG beams by FEM. Lanc et al. [40] analysed nonlinear buckling responses of thin-walled FG open section beams based on Euler-Bernoulli-Vlasov theory. Kim and Lee [41, 42] investigated the shear effects on free vibration and buckling behaviours of the thin-walled FG beam by three different types of finite beam elements, namely, linear, quadratic and cubic elements. The studies on the effects of shear deformation on buckling and vibration behaviours of thin-walled FG beams are still limited. On the other hand, Ritz method is simple and efficient to analyse the behaviours of composite beams with various boundary conditions [43-47], however, it has not been used for thin-walled composite and FG sandwich I-beams.

The main novelty of this work is to develop a Ritz solution for the vibration and buckling analyses of thin-walled composite and FG I-beams by using the first-order shear deformation beam theory. The governing equations of motion are derived by using Lagrange's equations. Results of the present element are compared with those in available literature to show its accuracy of the present solution. Parametric study is also performed to investigate the effects of shear deformation, span-to-height's ratio, fiber angle, material anisotropy and material distribution on natural frequencies and critical buckling loads of the thin-walled composite and FG sandwich I-beams.

2. Theoretical formulation

2.1. Kinematics

In this section, a kinematic field of the thin-walled composite and FG I-beams will be presented. The theoretical developments require three sets of coordinate systems as shown in Fig. 1 including the Cartesian coordinate system (x, y, z), local plate coordinate system (n, s, z) and contour coordinate *s* along the profile of the section. θ is an angle of orientation between (n, s, z) and (x, y, z) coordinate systems. The pole *P*, which has coordinate (x_p, y_p) , is called the shear center [48].

The following assumptions are made:

- a. Strains are small and contour of section does not deform in its own plane.
- b. Shear strains $\gamma_{xz}^0, \gamma_{yz}^0$ and warping shear γ_{σ}^0 are uniform over the section.
- c. Local buckling and pre-buckling deformation is not considered.
- d. Poisson's coefficient is constant.

Relation of the mid-surface displacements $(\overline{u}, \overline{v}, \overline{w})$ at a point in the contour coordinate system and global beam displacements (U, V, W) is given by ([22]):

$$\overline{u}(s,z,t) = U(z,t)\sin\theta(s) - V(z,t)\cos\theta(s) - \phi(z,t)q(s)$$
(1a)

$$\overline{v}(s,z,t) = U(z,t)\cos\theta(s) + V(z,t)\sin\theta(s) + \phi(z,t)r(s)$$
(1b)

$$\overline{w}(s,z,t) = W(z,t) + \psi_{y}(z,t)x(s) + \psi_{x}(z,t)y(s) + \psi_{\overline{\omega}}(z,t)\overline{\omega}(s)$$
(1c)

where U, V and W are displacement of P in the x-, y- and z- direction, respectively; ϕ is the rotation angle about pole axis; ψ_x, ψ_y and ψ_{σ} denote rotations of the cross-section with respect to x, y and σ :

$$\psi_{y} = \gamma_{xz}^{0} - U' \tag{2a}$$

$$\psi_x = \gamma_{yz}^0 - V' \tag{2b}$$

$$\psi_{\varpi} = \gamma_{\varpi}^{0} - \phi' \tag{2c}$$

where the prime superscript indicates differentiation with respect to z, and ϖ is warping function given by:

$$\varpi(s) = \int_{s_0}^{s} r(s) ds \tag{3}$$

The displacements (u, v, w) at any generic point on section are expressed by the midsurface displacements $(\overline{u}, \overline{v}, \overline{w})$ as:

$$u(n,s,z,t) = \overline{u}(s,z,t) \tag{4a}$$

$$v(n,s,z,t) = \overline{v}(s,z,t) + n\overline{\psi}_s(s,z,t)$$
(4b)

$$w(n,s,z,t) = \overline{w}(s,z,t) + n\overline{\psi}_z(s,z,t)$$
(4c)

where $\overline{\psi}_s$ and $\overline{\psi}_z$ are determined by ([24]):

$$\overline{\psi}_{z} = \psi_{y} \sin \theta - \psi_{x} \cos \theta - \psi_{\varpi} q \tag{5a}$$

$$\overline{\psi}_{s}(s,z,t) = -\frac{\partial \overline{u}}{\partial s}$$
(5b)

The strain fields are defined as:

$$\mathcal{E}_{s}(n,s,z,t) = \overline{\mathcal{E}}_{s}(s,z,t) + n\overline{\mathcal{K}}_{s}(s,z,t)$$
(6a)

$$\mathcal{E}_{z}(n,s,z,t) = \overline{\mathcal{E}}_{z}(s,z,t) + n\overline{\mathcal{K}}_{z}(s,z,t)$$
(6b)

$$\gamma_{sz}(n,s,z,t) = \overline{\gamma}_{sz}(s,z,t) + n\overline{\kappa}_{sz}(s,z,t)$$
(6c)

$$\gamma_{nz}(n,s,z,t) = \overline{\gamma}_{nz}(s,z,t) + n\overline{\kappa}_{nz}(s,z,t)$$
(6d)

where

$$\overline{\varepsilon}_s = 0 \tag{7a}$$

$$\overline{\varepsilon}_{z} = \frac{\partial \overline{w}}{\partial z} = \varepsilon_{z}^{0} + x\kappa_{y} + y\kappa_{x} + \varpi\kappa_{\sigma}$$
(7b)

$$\bar{\kappa}_s = 0 \tag{7c}$$

$$\bar{\kappa}_{z} = \frac{\partial \bar{\psi}_{z}}{\partial z} = \kappa_{y} \sin \theta - \kappa_{x} \cos \theta - \kappa_{\sigma} q \tag{7d}$$

$$\bar{\kappa}_{sz} = \kappa_{sz} \tag{7e}$$

$$\bar{\kappa}_{nz} = 0 \tag{7f}$$

$$\varepsilon_z^0 = W' \tag{7g}$$

$$\kappa_{x} = \psi_{x}^{'} \tag{7h}$$

$$\kappa_{y} = \psi_{y}^{'}$$
 (7i)

$$\kappa_{\sigma} = \psi_{\sigma}$$
 (7j)

$$\kappa_{sz} = \phi' - \psi_{\sigma} \tag{7k}$$

$$\varepsilon_{z} = \varepsilon_{z}^{0} + (x + n\sin\theta)\kappa_{y} + (y - n\cos\theta)\kappa_{x} + (\varpi - nq)\kappa_{\omega}$$
(71)

$$\gamma_{sz} = \gamma_{xz}^0 \cos\theta + \gamma_{yz}^0 \sin\theta + \gamma_{\varpi}^0 r + n\kappa_{sz}$$
(7m)

$$\gamma_{nz} = \gamma_{xz}^0 \sin \theta - \gamma_{yz}^0 \cos \theta - \gamma_{\sigma}^0 q \tag{7n}$$

2.2. Constitutive relations

2.2.1 Thin-walled composite beam

The composite beam is constituted by a finite number of orthotropic layers. The constitutive relation at the k^{th} – layer in (n, s, z) coordinate systems can be expressed as:

$$\begin{cases} \sigma_{z} \\ \sigma_{sz} \\ \sigma_{nz} \end{cases}^{(k)} = \begin{pmatrix} \bar{Q}_{11}^{*} & \bar{Q}_{16}^{*} & 0 \\ \bar{Q}_{16}^{*} & \bar{Q}_{66}^{*} & 0 \\ 0 & 0 & \bar{Q}_{55}^{*} \end{pmatrix}^{(k)} \begin{cases} \varepsilon_{z} \\ \gamma_{sz} \\ \gamma_{nz} \end{cases}$$
(8)

where

$$\bar{Q}_{11}^* = \bar{Q}_{11} - \frac{\bar{Q}_{12}^2}{\bar{Q}_{22}}$$
(9a)

$$\bar{Q}_{16}^* = \bar{Q}_{16} - \frac{\bar{Q}_{12}\bar{Q}_{26}}{\bar{Q}_{22}}$$
(9b)

$$\bar{Q}_{66}^* = \bar{Q}_{66} - \frac{\bar{Q}_{26}^2}{\bar{Q}_{22}} \tag{9c}$$

$$\bar{Q}_{55}^* = \bar{Q}_{55}$$
 (9d)

where \bar{Q}_{ij} are the transformed reduced stiffnesses (see [49] for more details).

2.2.2. Thin-walled functionally graded (FG) sandwich beam

The constitutive relation of the FG sandwich I-beams can be written as follows:

$$\begin{cases} \sigma_{z} \\ \sigma_{sz} \\ \sigma_{nz} \end{cases} = \begin{pmatrix} \overline{Q}_{11}^{*} & 0 & 0 \\ 0 & \overline{Q}_{66}^{*} & 0 \\ 0 & 0 & \overline{Q}_{55}^{*} \end{pmatrix} \begin{cases} \varepsilon_{z} \\ \gamma_{sz} \\ \gamma_{nz} \end{cases}$$
(10)

where

$$\bar{Q}_{11}^* = E(n) \tag{11a}$$

$$\bar{Q}_{66}^* = \bar{Q}_{55}^* = \frac{E(n)}{2(1+\nu)}$$
(11b)

E(n) is Young's modulus; ν is Poisson's coefficient. The effective mass density ρ and Young's modulus E of the thin-walled FG sandwich beam are approximated by:

$$\rho = \rho_c V_c + \rho_m (1 - V_c) \tag{12a}$$

$$E = E_c V_c + E_m \left(1 - V_c \right) \tag{12b}$$

where the subscripts c and m are used to indicate the ceramic and metal constituents, respectively; V_c is the volume fraction of ceramic material. Two type of material distributions are considered in this study:

Type A (for the flange, see Fig. 2b):

$$V_c = \left[\frac{n+0.5h}{(1-\alpha)h}\right]^p, \quad -0.5h \le n \le (0.5-\alpha)h \tag{13a}$$

$$V_c = 1, \ (0.5 - \alpha)h \le n \le 0.5h$$
 (13b)

where $h(h_1, h_2)$, p, $\alpha(\alpha_1, \alpha_2)$ are the thickness of the flange, material parameter and thickness ratio of ceramic material of the flange, respectively.

Type B (for the web, see Fig. 2b):

$$V_{c} = \left[\frac{-|n| + 0.5h}{0.5(1 - \beta)h}\right]^{p}, \quad -0.5h \le n \le -0.5\beta h \quad \text{or} \quad 0.5\beta h \le n \le 0.5h \quad (14a)$$

$$V_c = 1, -0.5\beta h \le n \le 0.5\beta h$$
 (14b)

where $h = h_3$ is the thickness of the web; β is thickness ratio of the ceramic material of the web.

2.3. Variational formulation

The strain energy Π_E of the thin-walled beams is defined by:

$$\Pi_{E} = \frac{1}{2} \int_{\Omega} \left(\sigma_{z} \varepsilon_{z} + \sigma_{sz} \gamma_{sz} + k^{s} \sigma_{nz} \gamma_{nz} \right) d\Omega$$
(15a)

where k^s and Ω are shear correction factor and volume of beam, respectively. It is well-known that the models based on the first-order shear deformation theory require a

correct value of the shear correction factors. Several authors made contributions in order to improve the models used for the FSDT. Nguyen et al. [50] proposed shear correction factors for analysis of functionally graded beams and plates. Hutchinson [51], Gruttmann and Wagner [52], and Barbero et al. [53] presented formulas in order to compute the shear factors of different cross-sections of a Timoshenko's beam. In this paper, the shear factor is assumed to be a unity, which was suggested by some previous authors ([21, 22, 24]). Substituting Eqs. (71), (7m), (7n), (8) and (10) into Eq. (15a) leads to:

$$\Pi_{E} = \frac{1}{2} \int_{0}^{L} \left[E_{11} W^{2} + 2E_{16} W^{'} U^{'} + 2E_{17} W^{'} V^{'} + 2\left(E_{15} + E_{18}\right) W^{'} \phi^{'} + 2E_{12} W^{'} \psi^{'}_{y} + 2E_{16} W^{'} \psi^{'}_{y} + 2E_{13} W^{'} \psi^{'}_{x} + 2E_{17} W^{'} \psi^{'}_{x} + 2E_{14} W^{'} \psi^{'}_{\sigma} + 2\left(E_{18} - E_{15}\right) W^{'} \psi^{'}_{\sigma} + E_{66} U^{'2} + 2E_{67} U^{'} V^{'} + 2\left(E_{56} + E_{68}\right) U^{'} \phi^{'}_{s} + 2E_{26} U^{'} \psi^{'}_{y} + 2E_{36} U^{'} \psi^{'}_{x} + 2E_{67} U^{'} \psi^{'}_{x} + 2E_{46} U^{'} \psi^{'}_{\sigma} + 2\left(E_{68} - E_{56}\right) U^{'} \psi^{'}_{\sigma} + E_{77} V^{'2} + 2\left(E_{57} + E_{78}\right) V^{'} \phi^{'}_{s} + 2E_{27} V^{'} \psi^{'}_{y} + 2E_{67} V^{'} \psi^{'}_{y} + 2E_{37} V^{'} \psi^{'}_{x} + 2E_{77} V^{'} \psi^{'}_{x} + 2E_{47} V^{'} \psi^{'}_{\sigma} + 2\left(E_{78} - E_{57}\right) V^{'} \psi^{'}_{\sigma} + \left(E_{55} + 2E_{58} + E_{88}\right) \phi^{'2} + 2\left(E_{25} + E_{28}\right) \phi^{'} \psi^{'}_{y} + 2\left(E_{56} + E_{68}\right) \phi^{'} \psi^{'}_{y} + 2\left(E_{53} + E_{38}\right) \phi^{'} \psi^{'}_{x} + 2\left(E_{45} + E_{48}\right) \phi^{'} \psi^{'}_{x} + 2\left(E_{88} - E_{55}\right) \phi^{'} \psi^{'}_{\sigma} + 2\left(E_{29} \psi^{'}_{y} + 2\left(E_{29} - E_{25}\right) \psi^{'}_{y} \psi^{'}_{x} + 2E_{27} \psi^{'}_{y} \psi^{'}_{x} + 2E_{36} \psi^{'}_{y} \psi^{'}_{x} + 2E_{67} \psi^{'}_{y} \psi$$

where the stiffness coefficients E_{ij} are given in [24], L is length of beam.

The potential energy Π_w of thin-walled beam subjected to axial compressive load N_0 can be expressed as:

$$\Pi_{W} = \frac{1}{2} \int_{\Omega} \frac{N_{0}}{A} \left(u^{'2} + v^{'2} \right) d\Omega$$

$$= \frac{1}{2} \int_{0}^{L} N_{0} \left(U^{'2} + V^{'2} + 2y_{p} U^{'} \phi^{'} - 2x_{p} V^{'} \phi^{'} + \frac{I_{p}}{A} \phi^{'2} \right) dz$$
(16)

where A is the cross-sectional area, I_p is polar moment of inertia of the cross-

section about the centroid defined by:

$$I_P = I_x + I_y \tag{17}$$

where I_x and I_y are second moment of inertia with respect to x- and y-axis, defined by:

$$I_x = \int_A y^2 dA \tag{18a}$$

$$I_{y} = \int_{A} x^{2} dA \tag{18b}$$

The kinetic energy Π_K of the thin-walled beam is given by:

$$\Pi_{\kappa} = \frac{1}{2} \int_{\Omega} \rho(n) (\dot{u}^{2} + \dot{v}^{2} + \dot{w}^{2}) d\Omega$$

$$= \frac{1}{2} \int_{0}^{L} \left[m_{0} \dot{W}^{2} + 2m_{s} \dot{W} \dot{\psi}_{y} - 2m_{c} \dot{W} \dot{\psi}_{x} + 2(m_{\sigma} - m_{q}) \dot{W} \dot{\psi}_{\sigma} + m_{0} \dot{U}^{2} + 2(m_{c} + m_{0} y_{P}) \dot{U} \dot{\phi} + m_{0} \dot{V}^{2} + 2(m_{s} - m_{0} x_{P}) \dot{V} \dot{\phi} + (m_{p} + m_{2} + 2m_{r}) \dot{\phi}^{2} + (m_{x2} + 2m_{xs} + m_{s2}) \dot{\psi}_{y}^{2}$$

$$+ 2(m_{xycs} - m_{cs}) \dot{\psi}_{y} \dot{\psi}_{x} + 2(m_{x\sigma} + m_{x\sigma qs} - m_{qs}) \dot{\psi}_{y} \dot{\psi}_{\sigma} + (m_{y2} - 2m_{yc} + m_{c2}) \dot{\psi}_{x}^{2}$$

$$+ 2(m_{y\sigma} - m_{y\sigma qc} + m_{qc}) \dot{\psi}_{x} \dot{\psi}_{\sigma} + (m_{\sigma 2} - 2m_{q\sigma} + m_{q2}) \dot{\psi}_{\sigma}^{2} \right] dz$$

$$(19)$$

where dot-superscript denotes the differentiation with respect to the time t, $\rho(n)$ is the mass density and the inertia coefficients are given in [24]. The total potential energy of thin-walled beam is expressed by:

$$\Pi = \Pi_E + \Pi_W - \Pi_K \tag{20}$$

2.4. Ritz solution

By using the Ritz method, the displacement field is approximated by:

$$W(z,t) = \sum_{j=1}^{m} \varphi_{j}(z) W_{j} e^{i\omega t}$$
(21a)

$$U(z,t) = \sum_{j=1}^{m} \varphi_j(z) U_j e^{i\omega t}$$
(21b)

$$V(z,t) = \sum_{j=1}^{m} \varphi_j(z) V_j e^{i\omega t}$$
(21c)

$$\phi(z,t) = \sum_{j=1}^{m} \varphi_j(z) \phi_j e^{i\omega t}$$
(21d)

$$\psi_{y}(z,t) = \sum_{j=1}^{m} \varphi_{j}(z) \psi_{yj} e^{i\omega t}$$
(21e)

$$\psi_x(z,t) = \sum_{j=1}^m \varphi_j(z) \psi_{xj} e^{i\omega t}$$
(21f)

$$\psi_{\varpi}(z,t) = \sum_{j=1}^{m} \varphi_{j}(z) \psi_{\varpi j} e^{i\omega t}$$
(21g)

where ω is the frequency, $i^2 = -1$ the imaginary unit; $W_j, U_j, V_j, \phi_j, \psi_{xj}, \psi_{xj}$ and $\psi_{\sigma j}$ are unknown and need to be determined; $\phi_j(z)$ are shape functions, which satisfy the specified essential boundary conditions (BCs) [49]. It is clear that these shape functions in Table 1 satisfy various the BCs such as simply-supported (S-S), clamped-free (C-F) and clamped-clamped (C-C).

By substituting Eqs. (21) into Eq. (20) and using Lagrange's equations:

$$\frac{\partial \Pi}{\partial p_j} - \frac{d}{dt} \frac{\partial \Pi}{\partial \dot{p}_j} = 0$$
(22)

with p_j representing the values of $(W_j, U_j, V_j, \phi_j, \psi_{xj}, \psi_{xj}, \psi_{\pi j})$, the vibration and buckling behaviours of the thin-walled beam can be obtained by solving the following equations:

$$\left[\begin{bmatrix} \mathbf{K}^{11} & \mathbf{K}^{12} & \mathbf{K}^{13} & \mathbf{K}^{14} & \mathbf{K}^{15} & \mathbf{K}^{16} & \mathbf{K}^{17} \\ {}^{T}\mathbf{K}^{12} & \mathbf{K}^{22} & \mathbf{K}^{23} & \mathbf{K}^{24} & \mathbf{K}^{25} & \mathbf{K}^{26} & \mathbf{K}^{27} \\ {}^{T}\mathbf{K}^{13} & {}^{T}\mathbf{K}^{23} & \mathbf{K}^{33} & \mathbf{K}^{34} & \mathbf{K}^{35} & \mathbf{K}^{36} & \mathbf{K}^{37} \\ {}^{T}\mathbf{K}^{14} & {}^{T}\mathbf{K}^{24} & {}^{T}\mathbf{K}^{34} & \mathbf{K}^{44} & \mathbf{K}^{45} & \mathbf{K}^{46} & \mathbf{K}^{47} \\ {}^{T}\mathbf{K}^{15} & {}^{T}\mathbf{K}^{25} & {}^{T}\mathbf{K}^{35} & {}^{T}\mathbf{K}^{45} & \mathbf{K}^{55} & \mathbf{K}^{56} & \mathbf{K}^{57} \\ {}^{T}\mathbf{K}^{16} & {}^{T}\mathbf{K}^{26} & {}^{T}\mathbf{K}^{36} & {}^{T}\mathbf{K}^{46} & {}^{T}\mathbf{K}^{56} & \mathbf{K}^{66} & \mathbf{K}^{67} \\ {}^{T}\mathbf{K}^{17} & {}^{T}\mathbf{K}^{27} & {}^{T}\mathbf{K}^{37} & {}^{T}\mathbf{K}^{47} & {}^{T}\mathbf{K}^{57} & {}^{T}\mathbf{K}^{67} & \mathbf{K}^{77} \end{bmatrix} \right]$$

$$- \omega^{2} \begin{bmatrix} \mathbf{M}^{11} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{M}^{15} & \mathbf{M}^{16} & \mathbf{M}^{17} \\ \mathbf{0} & \mathbf{M}^{22} & \mathbf{0} & \mathbf{M}^{24} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{M}^{33} & \mathbf{M}^{34} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{M}^{33} & \mathbf{M}^{34} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{T}\mathbf{M}^{15} & \mathbf{0} & \mathbf{0} & \mathbf{M}^{55} & \mathbf{M}^{56} & \mathbf{M}^{57} \\ {}^{T}\mathbf{M}^{16} & \mathbf{0} & \mathbf{0} & \mathbf{0} & {}^{T}\mathbf{M}^{56} & \mathbf{M}^{66} & \mathbf{M}^{67} \\ {}^{T}\mathbf{M}^{17} & \mathbf{0} & \mathbf{0} & \mathbf{0} & {}^{T}\mathbf{M}^{57} & {}^{T}\mathbf{M}^{67} & \mathbf{M}^{77} \end{bmatrix} \right]$$

where the stiffness matrix ${\bf K}$ and mass matrix ${\bf M}$ are expressed by:

$$\begin{split} K_{ij}^{11} &= E_{11} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{12} &= E_{16} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{13} &= E_{17} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{14} &= \left(E_{15} + E_{18}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \\ K_{ij}^{15} &= E_{12} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ E_{16} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{16} &= E_{13} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ E_{17} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \\ K_{ij}^{17} &= E_{14} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ \left(E_{18} - E_{15}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{22} &= E_{66} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ N_{0} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \\ K_{ij}^{24} &= \left(E_{56} + E_{68}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ N_{0} y_{p} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{25} &= E_{26} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ E_{66} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \\ K_{ij}^{26} &= E_{36} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ E_{67} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{27} &= E_{46} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ \left(E_{68} - E_{56}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \\ K_{ij}^{33} &= E_{77} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ N_{0} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{34} &= \left(E_{57} + E_{78}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} \phi_{j}^{*} dz \,, \\ K_{ij}^{35} &= E_{27} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ E_{67} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{36} &= E_{37} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ E_{77} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \\ K_{ij}^{35} &= E_{27} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ \left(E_{78} - E_{57}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{36} &= E_{37} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ E_{77} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \\ K_{ij}^{37} &= E_{47} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ \left(E_{78} - E_{57}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} \varphi_{j}^{*} dz \,, \quad K_{ij}^{44} &= \left(E_{55} + 2E_{58} + E_{88}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,+ \frac{N_{0} I_{p}} \frac{I}{A} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \,, \\ K_{ij}^{37} &= E_{47} \int_{0}^{L} \varphi_{i}^{*} \varphi_$$

$$\begin{split} & \mathcal{K}_{q}^{45} = \left(E_{25} + E_{23} \right)_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + \left(E_{36} + E_{38} \right)_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{46} = \left(E_{35} + E_{33} \right)_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + \left(E_{57} + E_{78} \right)_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{47} = \left(E_{45} + E_{44} \right)_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + \left(E_{88} - E_{55} \right)_{0}^{t} \phi \dot{\phi} \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{55} = E_{22} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{28} \int_{0}^{t} \left(\phi \dot{\phi} \dot{\phi} + \phi \dot{\phi} \right) dz + E_{46} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{55} = E_{22} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{25} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{45} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{57} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{57} = E_{22} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{23} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{45} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{57} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{57} = E_{31} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{53} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{57} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{57} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{57} = E_{31} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + (E_{38} - E_{33}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{57} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + (E_{58} - E_{57}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{57} = E_{41} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + (E_{58} - E_{43}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + E_{57} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz + (E_{58} - 2E_{58}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{K}_{q}^{57} = E_{41} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \quad \mathcal{M}_{q}^{59} = m_{1}^{t} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \quad \mathcal{M}_{q}^{50} = -m_{2}^{t} \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \quad \mathcal{M}_{q}^{50} = (m_{q} - m_{q}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{M}_{q}^{51} = m_{0} \int_{0}^{t} \phi \phi \dot{\phi} dz , \quad \mathcal{M}_{q}^{50} = (m_{c} + m_{0} y_{c}) \int_{0}^{t} \phi \phi \dot{\phi} dz , \quad \mathcal{M}_{q}^{51} = (m_{q} - m_{q}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{M}_{q}^{51} = (m_{s} - m_{0} y_{s}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \quad \mathcal{M}_{q}^{50} = (m_{3} - 2 m_{3} - m_{0}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \\ & \mathcal{M}_{q}^{51} = (m_{s} - m_{0} y_{s}) \int_{0}^{t} \phi \dot{\phi} \dot{\phi} dz , \quad \mathcal{M}_{q}^{50} = (m_{s$$

$$M_{ij}^{67} = \left(m_{y\varpi} - m_{y\varpi qc} + m_{qc}\right) \int_{0}^{L} \varphi_{i}^{'} \varphi_{j}^{'} dz , \quad M_{ij}^{77} = \left(m_{\varpi 2} - 2m_{q\varpi} + m_{q2}\right) \int_{0}^{L} \varphi_{i}^{'} \varphi_{j}^{'} dz$$
(24)

If the shear effect is ignored, Eq. (2) degenerates to $\psi_y = -U'$, $\psi_x = -V'$, $\psi_{\varpi} = -\phi'$. By setting $\gamma_{xz}^0 = \gamma_{yz}^0 = \gamma_{\varpi}^0 = 0$ into the above equations, the number of unknown variables reduces to four (W, U, V, ϕ) as the Euler-Bernoulli-Vlasov beam model. Finally, the natural frequencies and critical buckling loads of the thin-walled beams without shear effects can be found:

$$\begin{pmatrix} \begin{bmatrix} {}_{NS}\mathbf{K}^{11} & {}_{NS}\mathbf{K}^{12} & {}_{NS}\mathbf{K}^{13} & {}_{NS}\mathbf{K}^{13} & {}_{NS}\mathbf{K}^{14} \\ {}_{NS}^{T}\mathbf{K}^{12} & {}_{NS}\mathbf{K}^{22} & {}_{NS}\mathbf{K}^{23} & {}_{NS}\mathbf{K}^{24} \\ {}_{NS}^{T}\mathbf{K}^{13} & {}_{NS}^{T}\mathbf{K}^{23} & {}_{NS}\mathbf{K}^{33} & {}_{NS}\mathbf{K}^{34} \\ {}_{NS}^{T}\mathbf{K}^{14} & {}_{NS}^{T}\mathbf{K}^{24} & {}_{NS}^{T}\mathbf{K}^{34} & {}_{NS}\mathbf{K}^{44} \end{bmatrix} - \omega^{2} \begin{bmatrix} {}_{NS}\mathbf{M}^{11} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & {}_{NS}\mathbf{M}^{22} & \mathbf{0} & {}_{NS}\mathbf{M}^{24} \\ \mathbf{0} & {}_{NS}\mathbf{M}^{33} & {}_{NS}\mathbf{M}^{34} \\ \mathbf{0} & {}_{NS}^{T}\mathbf{M}^{24} & {}_{NS}^{T}\mathbf{M}^{34} & {}_{NS}\mathbf{M}^{44} \end{bmatrix} \begin{pmatrix} \mathbf{w} \\ \mathbf{u} \\ \mathbf{v} \\ \mathbf{0} \end{pmatrix} = \begin{cases} \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{cases}$$
(25)

where the stiffness matrix **K**, mass matrix **M** are given by:

$${}_{NS}K_{ij}^{11} = E_{11} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{12} = -E_{12} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{13} = -E_{13} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{14} = 2E_{15} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz - E_{14} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{22} = E_{22} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz + N_{0} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{23} = E_{23} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{23} = E_{23} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz + N_{0} y_{p} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz + N_{0} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{33} = E_{33} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{34} = E_{34} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz - 2E_{35} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz - N_{0} x_{p} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{34} = E_{34} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz - 2E_{35} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz + \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{34} = E_{44} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz - 2E_{45} \left(\int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz + \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz \right) + 4E_{55} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz + \frac{N_{0}I_{p}}{A} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}K_{ij}^{34} = E_{44} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j}^{*} dz, \quad {}_{NS}M_{ij}^{22} = m_{0} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j} dz , \quad {}_{NS}M_{ij}^{24} = \left(m_{c} + m_{0}y_{p}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j} dz, \quad {}_{NS}M_{ij}^{33} = m_{0} \int_{0}^{L} \varphi_{i}^{*} \varphi_{j} dz, \quad {}_{NS}M_{ij}^{34} = \left(m_{s} - m_{0}x_{p}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j} dz, \quad {}_{NS}M_{ij}^{44} = \left(m_{p} + m_{2} + 2m_{p}\right) \int_{0}^{L} \varphi_{i}^{*} \varphi_{j} dz$$

3. Numerical results

Results for natural frequencies and critical buckling loads of thin-walled composite and FG sandwich I-beams with various configurations including boundary conditions, layups and thickness ratio of the ceramic material are presented in this section. Convergence and comparison with the available literature are made to show the accuracy of the present solution. In addition, some new results, which may be used as reference data for future, are presented. The material properties and geometry of thin-walled I-beams are given in Table 2 and Fig. 2. The effect of the fiber angle, shear deformation, material parameter, span-to-height's ratio and thickness ratio of ceramic material on vibration and buckling behaviours of the thin-walled I-beams are investigated. The shear effect is defined by $(R_{NS} - R_s)/R_{NS} \times 100\%$ where R_s and R_{NS} denote the results with and without the shear effects, respectively.

Unless otherwise stated, the following non-dimensional terms are used:

For composite I-beams:
$$\overline{\omega} = \frac{\omega L^2}{b_3} \sqrt{\frac{\rho}{E_2}}, \quad \overline{N}_{cr} = \frac{N_{cr}L^2}{hE_2 b_3^3}$$
 (27)

For FG sandwich I-beams:
$$\overline{\omega} = \frac{\omega L^2}{b_3} \sqrt{\frac{\rho_m}{E_m}}, \quad \overline{N}_{cr} = \frac{N_{cr}L^2}{hE_m b_3^3}$$
 (28)

3.1. Convergence study

For purpose of testing convergence of present solution, the composite I-beams (MAT I, $b_1 = b_2 = b_3 = 5 \text{ cm}$, $h_1 = h_2 = h_3 = 0.208 \text{ cm}$ and $L = 40b_3$) and FG sandwich I-beams (MAT III, $b_1 = b_2 = 15 \text{ cm}$, $b_3 = 20 \text{ cm}$, $h_1 = h_2 = h_3 = 0.5 \text{ cm}$, $\alpha_1 = \alpha_2 = \beta = 0.1$, p = 5 and $L = 10b_3$) with the various BCs are considered. It is noted that both flanges and web of composite I-beams are assumed to be symmetrically laminated angle-ply $[45/-45]_{4s}$ with respect to its mid-plane. The fundamental frequencies and critical buckling loads of thin-walled I-beams are presented in Table 3 with various series number m. As can be seen, a rapid convergence is obtained and m=10 is sufficient to guarantee the numerical convergence.

3.2. Composite I-beams

3.2.1. Example 1

The first example demonstrates accuracy and validity of present solutions. The symmetric angle-ply I-beams (MAT I) with the various BCs are considered. The flanges and web are 0.208 cm thickness, and made of symmetric laminates that consist of 16 layers ($[\eta / -\eta]_{45}$). The first natural frequencies of S-S I-beams ($b_1 = b_2 = b_3 = 5$ cm and $L = 40b_3$), C-F I-beams ($b_1 = b_2 = 4$ cm, $b_5 = 5$ cm and $L = 20b_3$) and C-C I-beams ($b_1 = b_2 = b_3 = 5$ cm and $L = 40b_3$) are showed in Table 4 and Fig. 3. It can be seen that the present results are coincided with existing ones. The critical buckling loads of S-S I-beams ($b_1 = b_2 = b_3 = 5$ cm and $L = 80b_3$), C-F I-beams ($b_1 = b_2 = b_3 = 5$ cm and $L = 80b_3$), C-F I-beams ($b_1 = b_2 = b_3 = 5$ cm and $L = 80b_3$), are displayed in Table 5 and Fig. 4, respectively. Good agreements between the present results and those of Vo and Lee [24], Kim et al. [27, 28] are found again. It is also stated that there are not much differences between shear and no shear results because these beams are slender.

3.2.2. Example 2

This example is to investigate the effects of shear deformation on the vibration and buckling behaviors of I-beams. The composite I-beams (MAT II, $b_1 = b_2 = 20 \text{ cm}$, $b_3 = 30 \text{ cm}$, $h_1 = h_2 = h_3 = 1 \text{ cm}$ and $L = 20b_3$) are considered. The top and bottom flanges are angle-ply lay-up $[\eta/-\eta]$ and the web is unidirectional one. The results of

I-beams with different BCs are displayed in Tables 6-9. From these tables, it can be seen that the present results comply with those of Vo and Lee [24], and both natural frequencies and critical buckling loads decrease as the fiber angle increases for all BCs. The shear effects of I-beams with [15/-15] angle-ply in flanges for various BCs are conducted. Figs. 5 and 6 show the shear effects of fundamental frequencies and critical buckling load with respect to span-to-height's ratio, respectively. It can be seen that the shear effects are biggest for beams with C-C BCs, and are significant for beams with small span-to-height's ratio.

In order to clearly investigate the shear effects and fiber angle to the natural frequencies, the above composite I-beams with different geometry and material properties (MAT I, $b_1 = b_2 = b_3 = 30 \text{ cm}$, $h_1 = h_2 = h_3 = 2 \text{ cm}$ and $L = 10b_3$) are considered. Fig. 7 displays the shear effects on first three frequencies of beams for C-C BC. It is clear to see that the shear effects are significant for high modes. It is also interesting to see that the shear effects on third mode (mode V) are smallest at fiber angle 55° . This phenomenon can be explained in Fig. 8 which shows the ratio of flexural rigidity (E_{33}) to shear rigidity (E_{77}) with respect to η . It is observed that the ratio of E_{33}/E_{77} is the smallest at this angle (55°). Figs. 9-11 also show first three mode shapes of C-C I-beams with [45/-45] angle-ply in flanges with shear and without shear effect. It can be seen that the vibration modes 1, 2 and 3 are first flexural mode in x-direction (mode U), torsional mode (mode ϕ) and flexural mode in y-direction (mode V), respectively. 3.2.3. Example 3

The third example aims to investigate the effect of modulus ratio E_1/E_2 on natural frequencies and critical buckling loads of composite I- beams (MAT II, $b_1 = b_2 = 20$ cm,

 $b_3 = 30 \text{ cm}$, $h_1 = h_2 = h_3 = 1 \text{ cm}$ and $L = 20b_3$) with various BCs. The flanges are symmetric cross-ply $[0/90]_s$ lay-up and the web is unidirectional one. The variation of fundamental frequencies and critical buckling loads in case of including shear effects with respect to the ratio of E_1/E_2 is displayed in Figs. 12 and 13. It is observed that the results increase as E_1/E_2 increases for all BCs, and the beams with C-C BC have the biggest variation.

3.3. Functionally graded sandwich I-beams.

3.3.1. Example 4

This example is to assess the accuracy and efficiency of the present solution for thinwalled FG sandwich I-beams. Non-dimensional fundamental frequencies of S-S beams (MAT III, $b_1 = 20h$, $b_2 = 10h$, $b_3 = 40h$, $h_1 = h_2 = h_3 = h$, $\alpha_1 = 0.1$, $\alpha_2 = 0.9$ and $L = 40b_3$) with p = 1 and p = 5 are displayed in Fig 14. The critical buckling load of I-beams (MAT IV, $b_1 = b_2 = 10$ cm , $b_3 = 20$ cm , $h_1 = h_2 = h_3 = 0.5$ cm , $\alpha_1 = \alpha_2 = 0.7$, $\beta = 0.4$ and $L = 12.5b_3$) with different BCs is printed in Table 10. It can be found that the present solutions are in good agreements with previous results of Nguyen et al. [39], Lanc et al. [40] and Kim and Lee [41]. Results in Table 10 also indicated that the critical buckling loads decrease as material parameter p increases.

3.3.2. Example 5

In order to investigate the effects of thickness ratio of ceramic material on free vibration and buckling behaviours, the FG sandwich I-beams (MAT III, $b_1 = b_2 = 30h$, $b_3 = 40h$, $h_1 = h_2 = h_3 = h$ and $L = 10b_3$) are considered. Figs. 15 and 16 show the effect of ceramic thickness ratio in flanges on the non-dimensional fundamental frequencies and critical buckling loads of beams with $\beta = 0.3$ and p = 10 for the different BCs. It can be seen that frequencies and critical buckling load significantly increase as ceramic thickness ratio increases. Figs. 17 and 18 show the non-dimensional fundamental frequencies and critical buckling loads of beams ($\alpha_1 = \alpha_1 = 0.1$ and p = 10) with respect to the ceramic thickness ratio in web for different BCs. It is observed that increasing of ceramic thickness ratio in web causes slightly decrease fundamental frequencies, and slightly increase critical loads.

3.3.3. Example 6

The FG sandwich I-beams (MAT III, $b_1 = b_2 = b_3 = 20h$, $h_1 = h_2 = h_3 = h$, $\alpha_1 = \alpha_2 = \beta = 0.1$) are considered to investigate the effects of shear deformation. Figs. 19 and 20 show shear effect on fundamental frequencies and critical buckling loads of beams with p = 1 and with respect to the span-to-height ratio. From these figures, it can be seen that the shear effects decrease as the span-to-height ratio increases as expected. Effects of the material parameter on the shear effect of the C-C I-beams with $L = 10b_3$ are indicated in Fig. 21. It can be seen that the shear effect is significant with high modes, and is not effected by the material parameter for first three vibration modes.

4. Conclusions

Ritz method is developed to analyse buckling and vibration of composite and FG sandwich I-beams in this paper. The theory is based on the first-order shear deformation theory. The governing equations of motion are derived from Lagrange's equations. Ritz shape functions are developed to solve problems. The natural frequencies, critical buckling loads of thin-walled composite and FG sandwich I-beams with various BCs are obtained and compared with those of the previous works. The results indicate that the present study is simply and significant for predicting buckling and vibration

behaviours of composite and FG sandwich I-beams.

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Figure Captions

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Figure 3. Variation of the fundamental frequencies (Hz) of thin-walled C-C I-beams with respect to fiber angle.

Figure 4. Variation of the critical buckling loads (N) of thin-walled C-C I-beams with respect to fiber angle.

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Figure 6. Shear effect on the critical buckling loads for various BCs

Figure 7. Shear effect on first three natural frequencies of thin-walled C-C I-beams

Figure 8. Variation of E_{33}/E_{77} ratio with respect to η

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Figure 17. Non-dimensional fundamental frequency with respect to β ($\alpha_1 = \alpha_2 = 0.1$, and p = 10)

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Figure 21. Shear effect on first three frequency of C-C I-beams with respect to material parameter

Table Captions

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Table 2. Material properties of thin-walled I-beams.

Table 3. Convergence studies for thin-walled composite and FG sandwich I-beams.

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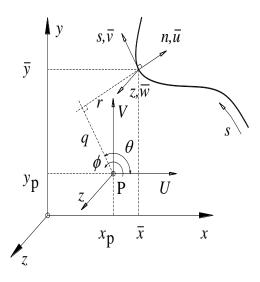
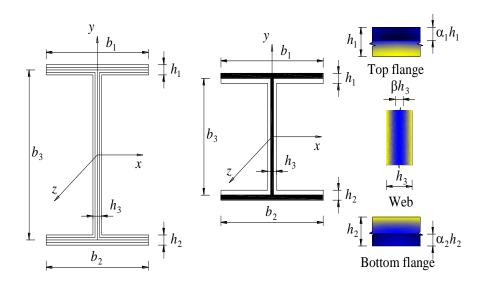


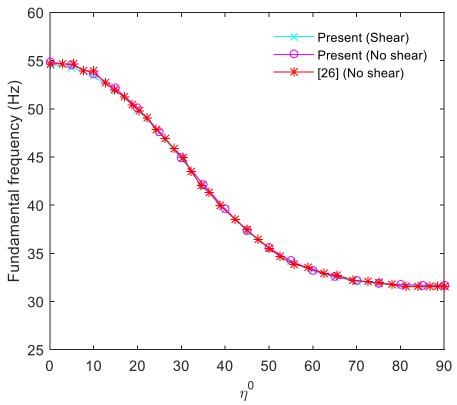
Figure 1. Thin-walled coordinate systems



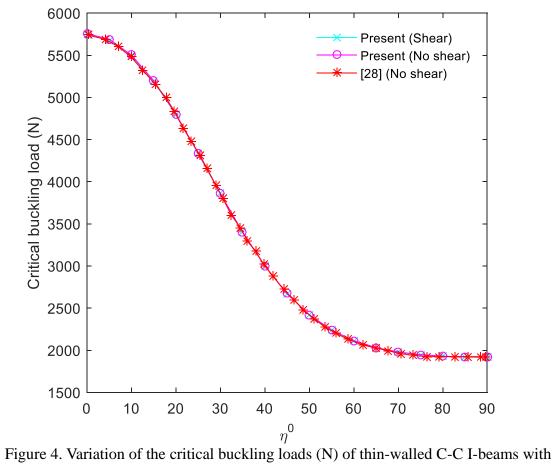
a. Composite I-beams

b. FG sandwich I-beams

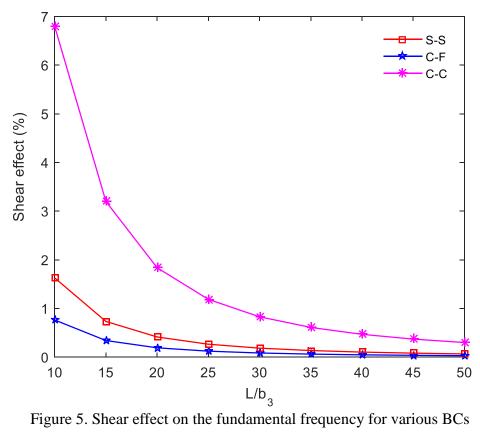
Figure 2. Geometry of thin-walled I-beams

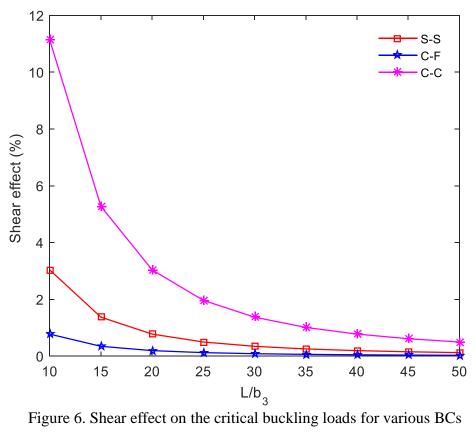


 η^0 Figure 3. Variation of the fundamental frequencies (Hz) of thin-walled C-C I-beams with respect to fiber angle.



respect to fiber angle.





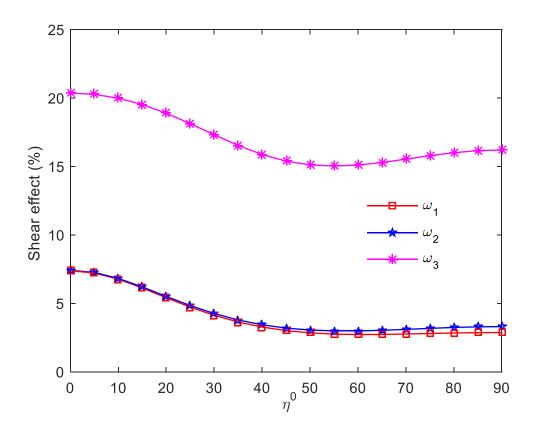
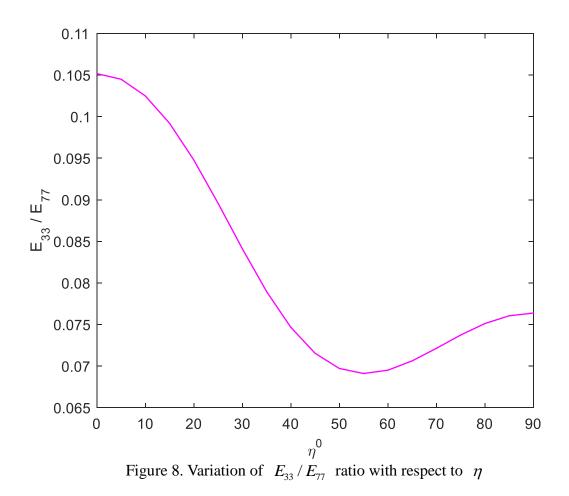


Figure 7. Shear effect on first three natural frequencies of thin-walled C-C I-beams



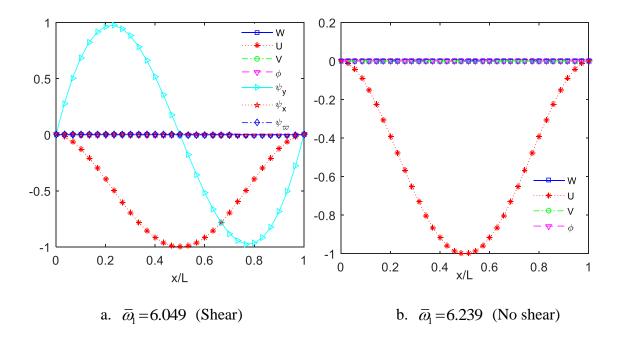


Figure 9. Mode shape 1 of thin-walled C-C I-beams

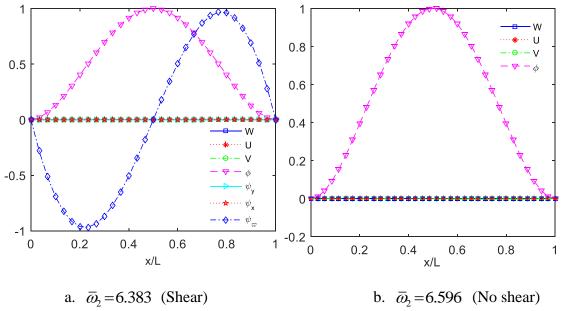


Figure 10. Mode shape 2 of thin-walled C-C I-beams

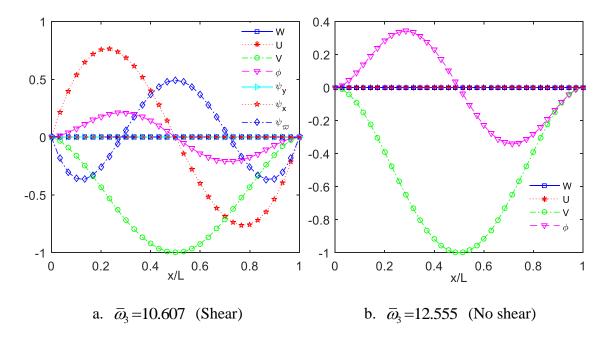


Figure 11. Mode shape 3 of thin-walled C-C I-beams

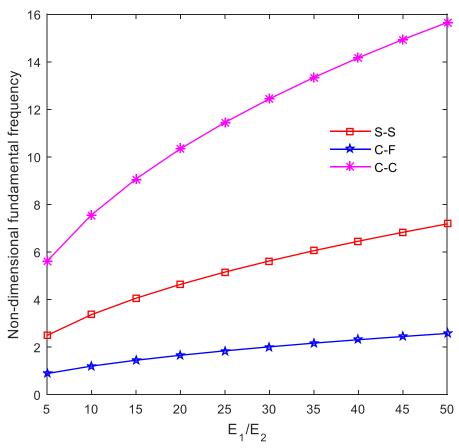


Figure 12. Non-dimensional fundamental frequency for various BCs

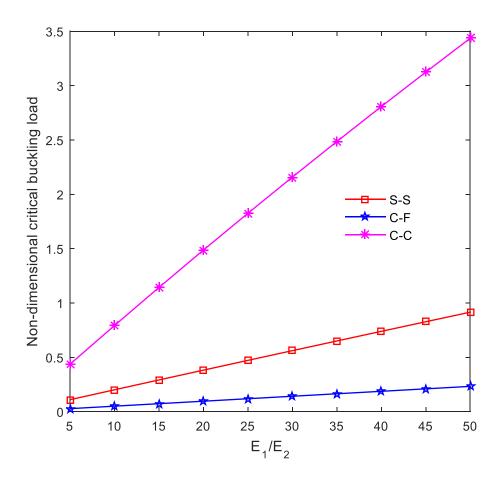


Figure 13. Non-dimensional critical buckling load for various BCs

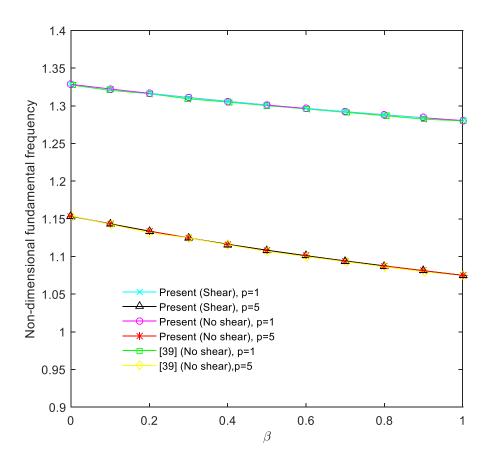


Figure 14. Non-dimensional fundamental frequency of thin-walled FG sandwich Ibeams.

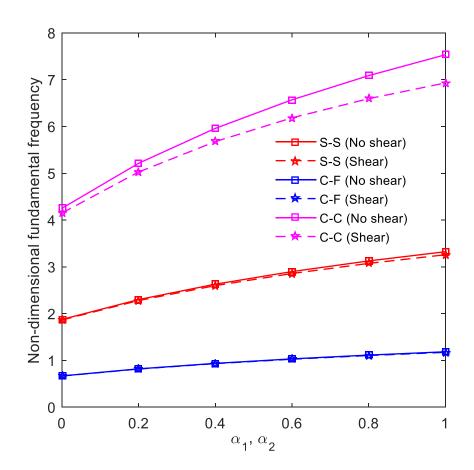


Figure 15. Non-dimensional fundamental frequency with respect to α_1 , α_2 ($\alpha_1 = \alpha_2$, $\beta = 0.3$ and p = 10)

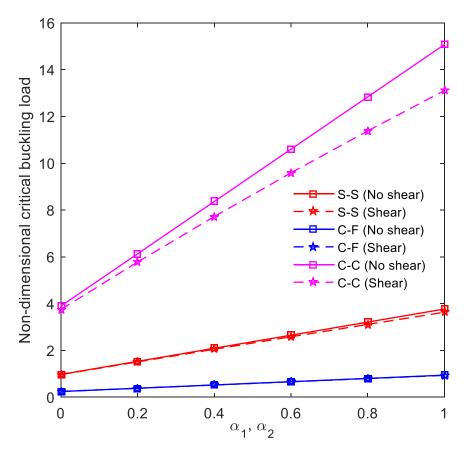


Figure 16. Non-dimensional critical buckling load with respect to α_1 , α_2 ($\beta = 0.3$ and p = 10)

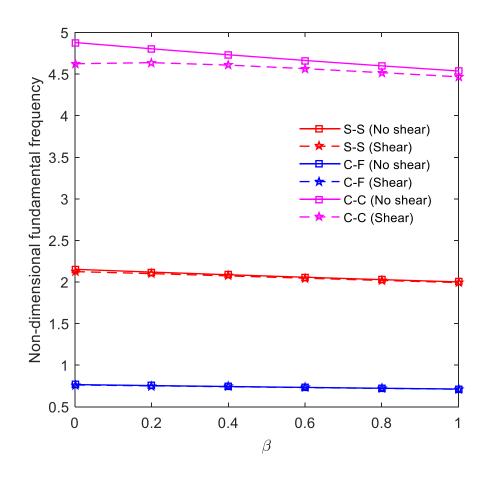


Figure 17. Non-dimensional fundamental frequency with respect to β ($\alpha_1 = \alpha_2 = 0.1$, and p = 10)

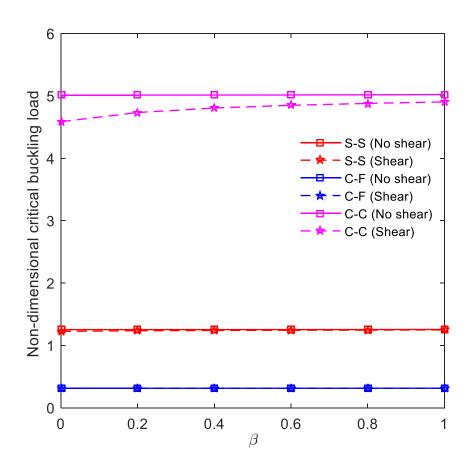


Figure 18. Non-dimensional critical buckling load with respect to β ($\alpha_1 = \alpha_2 = 0.1$, and p = 10)

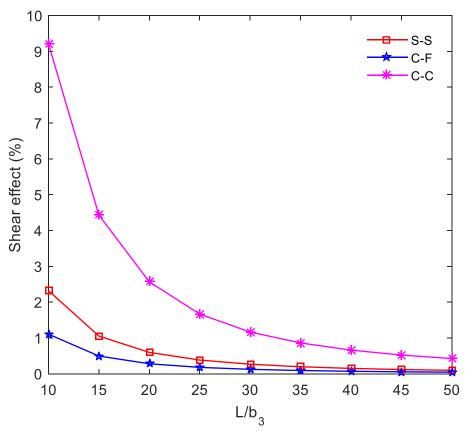
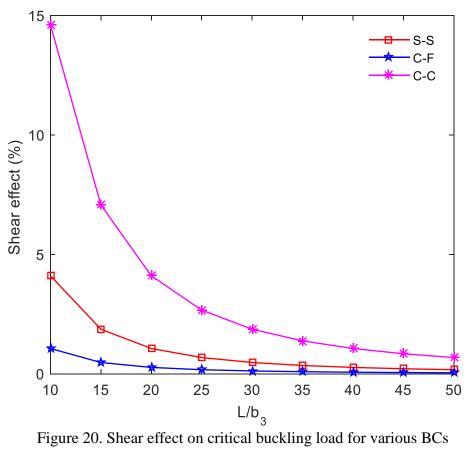


Figure 19. Shear effect on fundamental frequency for various BCs



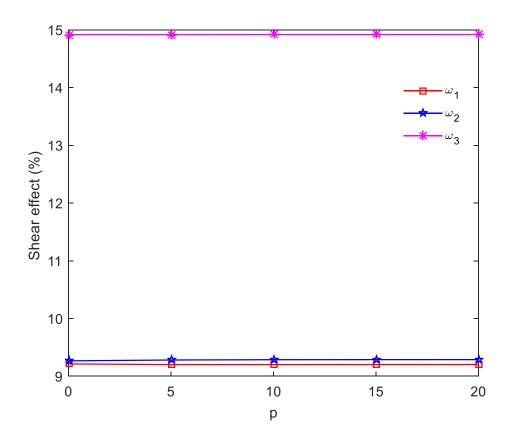


Figure 21. Shear effect on first three frequency of C-C I-beams with respect to material parameter

BC	$\frac{\varphi_j(x)}{e^{\frac{-jx}{L}}}$	<i>x</i> =0	x=L
S-S	$\frac{x}{L}\left(1-\frac{x}{L}\right)$	$U=V=\phi=0$	$U = V = \phi = 0$
C-F	$\left(\frac{x}{L}\right)^2$	$U = V = \phi = 0$ $U' = V' = \phi' = 0$ $W = \psi_y = \psi_x = \psi_{\sigma} = 0$	
C-C	$\left(\frac{x}{L}\right)^2 \left(1 - \frac{x}{L}\right)^2$	$U = V = \phi = 0$ $U' = V' = \phi' = 0$ $W = \psi_y = \psi_x = \psi_{\sigma} = 0$	$U = V = \phi = 0$ $U' = V' = \phi' = 0$ $W = \psi_y = \psi_x = \psi_{\sigma} = 0$

Table 1. Shape functions and essential BCs of thin-walled I-beams.

	1 1			
Material properties	MAT I	MAT II	MAT III	MAT IV
E_1 , E_c (GPa)	53.78	25	380	320.7
$E_2 = E_3$, E_m (GPa)	17.93	1	70	101.69
$G_{12} = G_{13}$ (GPa)	8.96	0.6	-	-
<i>G</i> ₂₃ (GPa)	3.45	0.6	-	-
$V, V_{12} = V_{13}$	0.25	0.25	0.30	0.3
ho (kg/m ³)	1968.90	-	-	-
$\rho_c (\mathrm{kg/m^3})$	-	-	3960	-
$\rho_m (\mathrm{kg/m^3})$	-	-	2702	-

Table 2. Material properties of thin-walled I-beams.

BC				ľ	n		
		2	4	6	8	10	12
1. Thi	n-walled comp	posite I-bea	ms				
a. Fun	damental freq	uency (Hz)					
S-S	Shear	16.763	16.544	16.482	16.481	16.481	16.481
	No shear	16.773	16.553	16.491	16.490	16.490	16.490
C-F	Shear	5.958	5.878	5.873	5.873	5.873	5.873
	No shear	5.959	5.880	5.875	5.875	5.875	5.875
C-C	Shear	37.433	37.307	37.304	37.303	37.302	37.301
	No shear	37.502	37.382	37.382	37.382	37.382	37.382
b. Crit	ical buckling	load (kN)					
S-S	Shear	2.752	2.690	2.671	2.671	2.671	2.671
	No shear	2.755	2.692	2.673	2.673	2.673	2.673
C-F	Shear	0.706	0.668	0.668	0.668	0.668	0.668
	No shear	0.706	0.668	0.668	0.668	0.668	0.668
C-C	Shear	10.797	10.678	10.657	10.657	10.657	10.657
	No shear	10.832	10.712	10.691	10.691	10.691	10.691
2. Thi	n-walled funct	tionally grad	ded sandw	ich I-beam	S		
a. Fun	damental freq	uency (Hz)					
S-S	Shear	92.715	91.522	91.184	91.180	91.180	91.180
	No shear	93.701	92.474	92.127	92.122	92.122	92.122
C-F	Shear	33.137	32.690	32.663	32.660	32.660	32.660
	No shear	33.291	32.846	32.820	32.818	32.818	32.818
C-C	Shear	201.801	200.434	200.127	199.973	199.885	199.830
	No shear	209.499	208.830	208.828	208.828	208.828	208.828
b. Crit	ical buckling	load (MN)					
S-S	Shear	1.036	1.013	1.006	1.006	1.006	1.006
	No shear	1.055	1.031	1.024	1.024	1.024	1.024
C-F	Shear	0.269	0.255	0.255	0.255	0.255	0.255
	No shear	0.271	0.256	0.256	0.256	0.256	0.256
C-C	Shear	3.867	3.827	3.820	3.820	3.820	3.820
	No shear	4.150	4.104	4.096	4.096	4.096	4.096

Table 3. Convergence studies for thin-walled composite and FG sandwich I-beams.

BC	Reference	Lay-up						
		[0] ₁₆	$\begin{bmatrix} 15 / \\ -15 \end{bmatrix}_{4s}$	$\begin{bmatrix} 30 / \\ -30 \end{bmatrix}_{4s}$	$\begin{bmatrix} 45 / \\ -45 \end{bmatrix}_{4s}$	$\begin{bmatrix} 60 / \\ -60 \end{bmatrix}_{4s}$	$\begin{bmatrix} 75 / \\ -75 \end{bmatrix}_{4s}$	$\begin{bmatrix} 90 / \\ -90 \end{bmatrix}_{4s}$
S-S	Present (Shear)	24.169	22.977	19.806	16.481	14.660	14.071	13.964
	Present (No shear)	24.198	23.001	19.820	16.490	14.668	14.079	13.972
	Vo and Lee [24] (Shear)	24.150	22.955	19.776	16.446	14.627	14.042	13.937
	Sheikh et al. [36] (Shear)	24.160	22.970	19.800	16.480	14.660	14.070	13.960
	Kim et al. [26] (No shear)	24.194	22.997	19.816	16.487	14.666	14.077	13.970
C-F	Present (Shear)	26.479	25.174	21.699	18.057	16.063	15.417	15.299
	Present (No shear)	26.514	25.202	21.717	18.069	16.072	15.427	15.309
	Kim and Lee [9] (Shear)	26.460	25.160	21.700	18.060	16.060	15.420	15.300
	Kim and Lee [9] (No shear)	26.510	25.200	21.710	18.070	16.070	15.420	15.310

Table 4. The fundamental frequency (Hz) of thin-walled S-S and C-F I-beams

BC	Reference	Lay-up						
		[0] ₁₆	$\begin{bmatrix} 15 / \\ -15 \end{bmatrix}_{4s}$	$\begin{bmatrix} 30 / \\ -30 \end{bmatrix}_{4s}$	$\begin{bmatrix} 45 / \\ -45 \end{bmatrix}_{4s}$	$\begin{bmatrix} 60 / \\ -60 \end{bmatrix}_{4s}$	$\begin{bmatrix} 75 / \\ -75 \end{bmatrix}_{4s}$	$\begin{bmatrix} 0 \\ 90 \end{bmatrix}_{4s}$
S-S	Present (Shear)	1438.1	1299.4	965.0	668.1	528.6	487.0	959.0
	Present (No shear)	1438.8	1300.0	965.2	668.2	528.7	487.1	959.3
	Kim et al. [27] (No shear)	1438.8	1300.0	965.2	668.2	528.7	487.1	964.4
C-F	Present (Shear)	5743.3	5191.0	3856.8	2670.6	2113.2	1946.7	3831.4
	Present (No shear)	5755.2	5199.7	3861.0	2672.7	2114.7	1948.3	3837.3
	Vo and Lee [24] (Shear)	5741.5	5189.0	3854.5	2668.4	2111.3	1945.1	3829.8
	Kim et al. [27] (No shear)	5755.2	5199.8	3861.0	2672.7	2114.7	1948.3	3857.8

Table 5. Critical buckling load (N) of thin-walled S-S and C-F I-beams

Reference	Frequency	Lay-up						
		[0]	[15/ _15]	$\begin{bmatrix} 30 \\ -30 \end{bmatrix}$	[45/ _45]	60/ -60	[75/ _75]	90/ _90]
Present (Shear)	ω_{1}	7.107	6.327	3.755	2.151	1.627	1.493	1.468
	ω_{2}	8.189	7.528	5.137	3.610	2.967	2.713	2.645
	ω_{3}	19.140	17.594	12.904	8.583	6.495	5.958	5.860
	\mathcal{O}_4	27.542	24.998	14.957	10.445	8.577	7.849	7.685
	ω_5	30.741	28.408	17.791	11.078	9.976	9.841	9.817
Present (No shear)	ω_{1}	7.186	6.353	3.761	2.153	1.628	1.494	1.469
	ω_{2}	8.303	7.561	5.145	3.614	2.970	2.715	2.648
	ω_{3}	20.856	18.903	13.404	8.611	6.513	5.974	5.876
	\mathcal{O}_4	28.743	25.412	15.043	10.654	8.606	7.876	7.713
	ω_5	32.408	28.935	17.917	11.191	10.213	10.069	10.045

Table 6. Non-dimensional natural frequency of thin-walled S-S I-beams

Reference	Frequency	Lay-up							
		[0]	[15/ _15]	$\begin{bmatrix} 30 / \\ -30 \end{bmatrix}$	[45/ _45]	60/ _60]	[75/ _75]	90/ _90]	
Present (Shear)	ω_1	2.547	2.259	1.339	0.767	0.580	0.532	0.523	
	ω_{2}	3.174	3.057	2.423	1.877	1.572	1.438	1.400	
	ω_{3}	7.123	6.538	4.746	3.821	3.597	3.327	3.272	
	\mathcal{O}_4	15.492	13.995	8.357	4.793	3.627	3.548	3.540	
	ω_{5}	17.559	16.307	10.755	7.177	5.780	5.285	5.162	
Present (No shear)	ω_1	2.560	2.263	1.340	0.767	0.580	0.532	0.523	
	ω_{2}	3.197	3.064	2.426	1.879	1.574	1.439	1.401	
	ω_{3}	7.430	6.772	4.835	3.896	3.635	3.335	3.280	
	\mathcal{O}_4	16.043	14.183	8.396	4.806	3.637	3.587	3.578	
	ω_5	18.333	16.549	10.811	7.199	5.796	5.300	5.177	

Table 7. Non-dimensional natural frequency of thin-walled C-F I-beams

Reference	Frequency	Lay-up						
		[0]	[15/]	[30/]	[45/]	[60/]	[75/]	[90/]
			[-15]	[−30]	<u></u> [−45]	[-60]	<u></u> _75 <u></u>]	└ −90 」
Present (Shear)	$\omega_{_{1}}$	15.480	14.129	8.474	4.865	3.682	3.378	3.322
	ω_2	17.239	16.086	10.104	6.206	4.839	4.423	4.332
	ω_{3}	34.221	32.379	23.221	13.368	10.121	9.285	9.131
	ω_4	40.918	38.293	25.221	15.901	12.265	11.221	11.004
	ω_{5}	44.983	43.101	27.483	22.047	19.739	18.106	17.804
Present (No shear)	$\omega_{_{1}}$	16.289	14.401	8.525	4.880	3.691	3.386	3.330
	ω_{2}	18.362	16.429	10.172	6.228	4.854	4.438	4.346
	$\omega_{_3}$	44.902	39.698	23.499	13.452	10.175	9.334	9.180
	ω_4	47.279	42.154	26.604	16.021	12.342	11.294	11.079
	ω_5	50.406	45.561	31.022	24.622	19.946	18.298	17.996
Vo and Lee [24] (Shear)	$\omega_{_{1}}$	15.460	14.122	8.471	4.862	3.678	3.374	3.319
	ω_2	17.211	16.064	10.092	6.202	4.836	4.421	4.330
	ω_{3}	33.996	32.174	23.209	13.392	10.147	9.308	9.152
	ω_4	40.271	38.063	25.126	15.919	12.286	11.239	11.022
	ω_{5}	44.134	42.818	27.457	21.991	19.855	18.211	17.905
Vo and Lee [24] (No shear)	$\omega_{_{1}}$	16.289	14.401	8.525	4.880	3.691	3.386	3.330
	ω_2	18.362	16.429	10.172	6.228	4.854	4.438	4.346
	ω_3	44.903	39.698	23.499	13.452	10.175	9.334	9.180
	ω_4	47.279	42.154	26.604	16.021	12.342	11.294	11.079
	ω_{5}	50.406	45.561	31.022	24.622	19.946	18.298	17.996

Table 8. Non-dimensional natural frequency of thin-walled C-C I-beams

BC	Reference	Lay-up						
		[0]	[15/ 15]	$\begin{bmatrix} 30 / \\ -30 \end{bmatrix}$	45/ _45]	60/ _60]	[75/ _75]	90/ -90
S-S	Present (Shear)	11.947	9.468	3.336	1.094	0.626	0.527	0.510
	Present (No shear)	12.208	9.542	3.344	1.096	0.627	0.527	0.510
C-F	Present (Shear)	3.035	2.381	0.835	0.274	0.157	0.132	0.128
	Present (No shear)	3.052	2.385	0.836	0.274	0.157	0.132	0.128
C-C	Present (Shear)	44.914	37.007	13.249	4.363	2.498	2.102	2.034
	Present (No shear)	48.830	38.167	13.374	4.383	2.507	2.110	2.041

Table 9. Non-dimensional critical buckling load of thin-walled composite I-beams

BC	р			Reference		
		Pre	esent	Kim and	d Lee [41]	Lanc et al. [40]
		Shear	No shear	Shear	No shear	No shear
S-S	0	421633	423079	422359	423083	423296
	0.25	404154	405602	405208	405933	406130
	0.5	392508	393960	393783	394515	394692
	1	377958	379420	379533	380286	380412
	2	363420	364899	365280	366056	366150
	5	348899	350404	351058	351825	351914
	10	342305	343826	344601	345333	345451
	20	338539	340070	340906	341605	341762
C-F	0	105679	105770	105725	105771	105773
	0.25	101310	101401	101435	101483	101484
	0.5	98399	98490	98577	98629	98626
	1	94763	94855	95013	95072	95057
	2	91132	91225	91448	91514	91494
	5	87507	87601	87891	87957	87936
	10	85861	85957	86277	86334	86321
	20	84922	85018	85353	85403	85400
C-C	0	1669413	1692317	1680840	1692352	1705050
	0.25	1599491	1622408	1612410	1623751	1635900
	0.5	1552860	1575838	1566830	1578078	1589830
	1	1494551	1517678	1509950	1521156	1532310
	2	1436213	1459595	1453060	1464229	1474860
	5	1377838	1401613	1396270	1407293	1417520
	10	1351288	1375299	1370490	1381317	1391480
	20	1336111	1360275	1355730	1366399	1376630

Table 10. The critical buckling load (N) of FG sandwich I-beams