

Multivariate prediction of total water storage changes over West Africa from multi-satellite data

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Abstract West-African countries have been exposed to changes in rainfall patterns over the last decades, including a significant negative trend. This causes adverse effects on water resources of the region, for instance, reduced freshwater availability. Assessing and predicting large-scale total water storage (TWS) variations is necessary for West Africa, due to its environmental, social and economical impacts. Hydrological models, however, may perform poorly over West Africa due to data scarcity. This study describes a new statistical, data-driven approach for predicting West African TWS changes from (past) gravity data obtained from the Gravity Recovery and Climate Experiment (GRACE), and (concurrent) rainfall data from the Tropical Rainfall Measuring Mission (TRMM) and sea surface temperature (SST) data over the Atlantic, Pacific and Indian Oceans. The proposed method, therefore, capitalizes on the availability of remotely sensed observations for predicting monthly TWS, a quantity which is hard to observe in the field but important for measuring regional energy balance, as well as for agricultural and water resource management. Major teleconnections within these data sets were identified using independent component analysis (ICA) and linked via low-degree autoregressive models to build a predictive framework. After a learning phase of 72 months, our approach predicted TWS from rainfall and SST data alone that fitted to the observed GRACE-TWS better than that from a global hydrological model. Our results indicated a fit of 79% and 67% for the first year prediction of the two dominant annual and inter-annual modes of TWS variations. This fit reduces to 62% and 57% for the second year of projection. The proposed approach, therefore, represents strong potential to predict the TWS

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over West Africa up to two years. It also has the potential to bridge the present GRACE data gaps of one month about each 162 days as well as a - hopefully - limited gap between GRACE and the GRACE follow-on mission over West Africa. The presented method could also be used to generate a near-real time GRACE forecast over the regions that exhibit strong teleconnections.

Keywords Predicting GRACE-TWS · West Africa · Autoregressive model · ICA · GRACE gap filling

1 Introduction

West African climate is highly variable, ranging from tropical to semi-arid and arid over a limited 1000-km North-South gradient. The main source of precipitation over a large part of West Africa (WA) is driven by the WA monsoon system and tightly linked to large-scale pattern of ocean-atmosphere-land interaction (Giannini et al., 2003, 2008). Inter-decadal rainfall decrease over WA was highlighted as one of the largest precipitation patterns on the planet over the last half century (Ali and Lebel, 2009), leading to high risks of prolonged droughts, as in the 1970s and 1980s. Moreover, global warming adds up multiple threats to the region, with the duration and magnitude of droughts and floods expected to increase (Nicholson, 2000, Speth et al., 2011). It is of critical importance to understand and predict the impact of the WA climatic system on water resources over timescales of several months, as the livelihoods of roughly 70% of the region's population depend on uncertain rainfall and exposure to climate risk (Hansen et al., 2011).

Drought severity is classically expressed in terms of the Palmer drought index, based on moisture data only (Heim 2002). However, this index does not explicitly account for the state of all water storage compartments (Long et al., 2013), as prolonged drought conditions may have an impact on deeper groundwater systems even with limited anthropic pumping (Chen et al., 2010). Houborg et al. (2012) showed significant interest in incorporating total water storage observations (TWS), defined as the sum of all available water storage on and below the surface of the Earth observations, to be used for drought monitoring. Its applicability is due to the fact that TWS can represent all available forms of water resource (Scanlon et al., 2012, Schol et al., 2008), thus, might be a better representative of drought compared to soil moisture or groundwater compartment alone.

Importance of quantifying TWS variations goes beyond its application in water resource studies. In general, the internal states of storage compartments determine their reaction to imposed boundary conditions. Runoff is driven by water stored in soil compartment and groundwater systems. Soil moisture layers - and groundwater to a lesser extend - also control evapotranspiration, cooling the land surface and regulating local energy and water balances (Koster et al., 2004). In this sense, WA has been highlighted as a 'hot spot', where the land-atmosphere coupling could play an important role, through the recycling of precipitation and the modulation of rainfall gradients (Douville et

37 al., 2006). Main processes affecting rainfall and water availability in WA at
38 seasonal to decadal time scales have been extensively studied within the frame-
39 work of international efforts under the AMMA¹ initiative (e.g. Redelsperger et
40 al. 2006). Beside land-atmosphere coupling, WA monsoon variability coincides
41 with other overlapping shifts like those in global temperature and natural sea
42 surface temperature (SST) oscillations in all tropical oceans, showing remote
43 (Pacific) or local (Atlantic and Indian) influences (see Rodríguez-Fonseca et
44 al., 2011 and references therein, Mohino et al., 2011). Diatta and Fink (2014)
45 studied the relationships between climate indices and monsoon rainfall, de-
46 rived from rain gauge data, over West Africa, covering 1921 to 2009, and
47 reported positive correlations between Sahel rainfall and the Atlantic Multi-
48 decadal Oscillation (AMO), as well as the Atlantic Meridional Mode (AMM).
49 Their results also indicated a significant impact of ENSO on inter-annual vari-
50 ability of precipitation over WA. Up to now, however, complex coupled ocean-
51 atmosphere models represented limited skills to accurately simulate the main
52 SST-WA monsoon teleconnections, both at inter-annual and decadal scales.
53 This is reported to be caused by the simplification of different aspects of the
54 climate system and of persistent biases (e.g., Rodríguez-Fonseca et al., 2011).

55 Land surface models (LSMs) and hydrological models are commonly ap-
56 plied to simulate the impact of climate on storage compartments (e.g., Döll et
57 al., 2003, Rodell et al., 2004, van Dijk et al., 2013). However, the quality of
58 the models strongly depends on model structure, boundary conditions (rain-
59 fall and evapotranspiration) and data availability, and also on model calibra-
60 tion/parametrization (Güntner et al., 2007). Over WA, modeling the impact
61 of the monsoon on water resources is restricted by limited data for calibra-
62 tion/validation purposes (Boone et al., 2009, Schuol and Abbaspour, 2006),
63 leading to large magnitude of uncertainties on the water balance and TWS.

64 Time-variable gravity solution of the Gravity And Climate Experiment
65 (GRACE) mission offers an opportunity to remotely measure large-scale TWS
66 changes on regional and global scale (Tapley et al. 2004, Schmidt et al., 2008a).
67 A few studies have highlighted the critical interest of GRACE-TWS observa-
68 tions in WA due to the sparse distribution of in situ observation network with
69 respect to the size of the region (Xie et al., 2012). Nahmani et al. (2012)
70 showed that GRACE accurately estimates the annual variability of WS over
71 WA, when compared to the output of hydrological models and GPS obser-
72 vations. Grippa et al. (2011) carried out a model comparison study between
73 various GRACE products and nine land surface models (LSMs) and showed
74 substantial differences between GRACE-TWS and LSMs. The differences were
75 mainly ascribed to the weakness of the LSMs to correctly simulate water in
76 surface reservoirs and evapotranspiration during the dry seasons.

77 This study presents a multivariate statistical TWS forecasting approach
78 for West Africa (WA). Our goal is to capitalize on the availability of homoge-
79 neously processed, remotely sensed observations of gravity from GRACE, sea
80 surface temperature (SST) from satellite data, as well as rainfall data from the

¹ African Monsoon Multidisciplinary Analysis

81 Tropical Rainfall Measuring Mission (TRMM), and predict large-scale annual
82 and inter-annual variability of West-African TWS changes up to a few years.
83 Therefore, the term ‘prediction’ or ‘forecast’ in this study refers to estimation
84 of the TWS quantity, for the period that TWS has not been observed, using its
85 indicators, which in our case are SST and precipitation changes. A statistical
86 approach, based on ‘system identification’ framework (Ljung, 1987), is chosen
87 here for our predictions (see Section 3) since we are interested in accurate final
88 monthly values of TWS rather than exploring the mechanism of changes in
89 TWS compartments (e.g., soil moisture and groundwater) and their interactions.
90 A similar concept has already been used, e.g., by the USA’s National
91 Oceanic and Atmospheric Administration (NOAA) for predicting climatic parameters
92 (<http://www.cpc.ncep.noaa.gov/>). We should mention here that one
93 could also alternatively use ‘gap-filler’ approaches (e.g., Rietbroek et al., 2014)
94 to estimate (or predict) surface load or TWS over the region of interest. We will
95 show later that the prediction approach here provides up to two years TWS
96 predictions, while retaining the spatial resolution of GRACE products. Reager
97 and Famiglietti (2013) represented an experimental predictions approach that
98 relates water storage changes to precipitation forcing and then generalize the
99 relation based on large-scale basin characteristics. Unlike our propose method,
100 this approach requires extra information about basin characteristics.

101 The predictability skill of the proposed statistical approach would be optimal
102 if major physical processes over the region of study are included in the
103 learning phase. Thus, both ocean-atmosphere and land-atmosphere processes
104 are represented as predictors of West African TWS changes: (i) SST variations
105 over the major oceanic basins of the Atlantic, Pacific and Indian Oceans (ii)
106 rainfall observation of TRMM over West Africa. Although other predictors
107 might also improve the forecasting results (evapotranspiration, soil moisture
108 changes), model quality is related to parsimony and data homogeneity. Here,
109 we only rely on SST and rainfall data since they are more accurately derived
110 from remote sensing observations compared to the other possible indicators
111 (see e.g., Reynolds et al., 2002, Huffman and Bolvin, 2012, Wang and Dickinson,
112 2012).

113 Time-variable maps of predictors (SST and rainfall data) and predictands
114 (TWS data) include large temporal and spatial correlations. This suggests the
115 application of a dimension reduction method before constructing the mathematical
116 relationship between predictors and predictands (e.g., Kaplan et al.,
117 1997). This considerably improves the skill of the forecasting approach (see
118 e.g., Westra et al., 2008). The statistical method of independent component
119 analysis (ICA) was applied to extract individual modes of variability that are
120 mutually independent and successively explain the maximum amount of existing
121 variance in the data (Forootan and Kusche, 2012,2013). An optimum
122 autoregressive model with exogenous variables (ARX) (Ljung, 1987) was then
123 used to relate independent components (ICs) of predictands to ICs of predictors.
124 In the end, the model allows a thorough representation of complex
125 processes in a highly efficient way as compared to physical models. The combination
126 of ICA/ARX modeling can be generalized worldwide, with an ade-

127 quate identification of likely forcing recalibration of the model, with respect
128 to the region of interest. Examples include the regions such as North Amer-
129 ica and the Australian continent, where exhibit strong ocean-land-atmosphere
130 interactions (Douville et al., 2006, Forootan et al., 2012).

131 From a methodological point of view, we prefer the ICA algorithm for di-
132 mension reduction over, e.g., principal component analysis (PCA, Preisendor-
133 fer, 1988); this view is rooted in the improved performance of ICA in ex-
134 tracting trends, annual patterns as well as slow dynamic patterns such as the
135 El Niño-Southern Oscillation (ENSO) from climate observations (e.g., Aires
136 et al., 2002, Ilin et al., 2005)). In a preliminary study, Forootan and Kusche
137 (2012) and Forootan et al. (2012) applied the ICA method to global and local
138 GRACE-TWS time series and demonstrated its value in extracting climate
139 related patterns. We also evaluated the use of PCA in our proposed statistical
140 TWS forecast (results are not shown here), and found that ICA improves the
141 extraction of teleconnections e.g., ENSO and the Indian Ocean Dipole (IOD)
142 patterns, as well as the performance of the prediction. A similar conclusion
143 was reached by Westra et al. (2007), who assessed the performance of ICA
144 and PCA for simulating hydrological time series. Finally, we prefer the ARX
145 model over the common canonical correlation analysis (CCA) approach (e.g.,
146 von Storch and Navara, 1999) for relating predictors and predictands since
147 ARX offers more flexibility to relate multiple parameters as exemplified in
148 e.g., Westra et al. (2008).

149 To implement our prediction approach, first, we begin by decomposing
150 the following data sets individually into statistically independent modes: (i)
151 GRACE-TWS changes over West Africa, to provide the dominant independent
152 patterns of total water storage (TWS) that are subsequently identified with the
153 predictands of the ARX process; (ii) SSTs over the Atlantic, Pacific, and Indian
154 Ocean basins, to extract ocean-atmospheric interactions and teleconnections;
155 and (iii) TRMM data over West Africa, for extracting the main patterns of
156 rainfall over the region. Then, the modes found by the analysis (ii) and (iii) are
157 introduced as predictors of (i) within the ARX process model, while using the
158 first 72 months of (i), (ii) and (iii) for the training step (statistical simulation).
159 The fitted ARX model, along with the independent modes of SST and rainfall
160 (i.e. the predictors of the ARX model) after the 72'th month are then used
161 to predict TWS after the simulation period. The prediction is evaluated using
162 those GRACE-derived TWS anomalies that are available after the simulation
163 period. Forecasting error levels are also predicted using a Monte Carlo error
164 estimation process. We should mention here that to decompose water storage
165 and rainfall data in (i) and (iii), we introduce the West Africa region as a simple
166 box (latitude between 0° to $25^\circ N$ and longitude between -20° to $10^\circ E$). The
167 method, however, can be extended to be applied on grids delineated by basin
168 shape or basin-averaged time series.

169 This contribution is organized as follows; in Section 2, we briefly present the
170 data sets used in the study. The dimension reduction and the ARX forecasting
171 methods are introduced in Section 3, followed in Section 4 by a discussion of the
172 leading independent modes found in the GRACE, WGHM, SST and TRMM

173 data sets. In Section 5, we discuss the results of ARX-TWS simulations and
174 forecasts over West Africa. The study is concluded in Section 6. The paper
175 also contains two appendices. In Appendix A, the details of GRACE-TWS
176 estimations over West Africa are described, and in Appendix B, we present
177 the details of mathematical methods, used in this study, including ICA and
178 the ARX model as well as their uncertainty estimations.

179 **2 Data**

180 2.1 Total Water Storage from GRACE and WGHM

181 The GRACE mission consists of two low-earth orbiting satellites in the same
182 orbital plane at the current altitude of ~ 450 km and in an inclination of 89.5° .
183 The separation distance between the two satellites is measured precisely by
184 a K-band ranging system and the location of each satellite is determined by
185 GPS receivers on-board the spacecraft (Tapley et al., 2004). These data, after
186 application of several corrections, are then used by a number of analysis to gener-
187 ate time-variable (usually monthly) Level-2 gravity field products (Flechtner,
188 2007). In this study, we used monthly GRACE products from the German Re-
189 search Centre (GFZ) Potsdam (Flechtner, 2007) for computing TWS fields,
190 covering August 2002 to May 2011. We did not interpolate the missing solu-
191 tions of January 2003, 2004, May 2003 and December 2008 in order to avoid
192 creating artifacts. For comparison, we also used monthly GRACE-ITG2010
193 products from Bonn University, Germany (Mayer-Gürr et al., 2010) which are
194 available for the period between September 2002 and August 2009, and are
195 provided together with full variance-covariance information. The covariance
196 matrices were used to estimate the accuracy of the GRACE-TWS grids. To-
197 tal water storage from GRACE is also compared with TWS output from the
198 WGHM model (Döll et al., 2003), covering the years 2003 to 2010. WGHM
199 represents the major hydrological components, such as soil moisture, rainfall,
200 snow accumulation, melting, evaporation, runoff, and the lateral transport
201 of water within river networks. For this study, we prefer WGHM over using
202 land surface models since it also contains a groundwater simulation model
203 and, therefore, its vertically aggregated storage can be directly compared to
204 GRACE TWS. The details of our data preparation are described in Appendix
205 A.

206 2.2 SST

207 Monthly reconstructed global $1^\circ \times 1^\circ$ Reynolds sea surface temperature (SST)
208 data (Reynolds et al., 2002) were used over the period 2002 to 2012. The
209 Reynolds SST has been frequently used for climate studies, including some
210 addressing African rainfall variability in relation to SST (e.g., Mohino et al.,
211 2011, Omondi et al., 2012). Similar to Omondi et al. (2012), the SST data

cover three major ocean basins: we include an Atlantic Ocean box (-66° to 13° E and -20° to 31° N), a Pacific Ocean box (159° to 275° E and -30° to 19° N) and an Indian Ocean box (34° to 114° E and -50° to 1° N). Sea surface temperatures in these regions are then extracted analyzed through the ICA approach (Section 4). We found that a slight difference in the size of the selected boxes would not change the results of ICA significantly.

2.3 TRMM

Version 7 of the TRMM-3B42 products (Huffman and Bolvin, 2012) covering 2002 to 2012 (<http://mirador.gsfc.nasa.gov/>) was used. The downloaded 3-hourly rainfall rates have been converted to rainfall amount and aggregated to monthly basis. TRMM was previously used e.g., by Nicholson et al. (2003) to study the patterns of precipitation over West Africa. Huffman and Bolvin (2012) and Fleming and Awange (2013) reported a significant improvement of the version 7 over the previous version, likely as a result of including more microwave sounding and imagery records as well as implementing better processing algorithms.

3 Methodology

3.1 Identifying Dominant Independent Patterns from Available Data

In order to keep the problem of identifying independent modes on a grid, including the statistical relationships between them, numerically manageable, it is mandatory to first apply a dimension reduction method before constructing the mathematical relationship between predictors and predictands (e.g., Kaplan et al., 1997). This improves the prediction skill of the statistical approach, since the redundant information within the data sets, both predictors and predictands, will be reduced. Dimension reduction is implemented here by applying a 2-step independent component analysis (ICA) algorithm (Frootan and Kusche, 2012, 2013) to the TWS, rainfall, and SST data sets. Frootan and Kusche (2012) formulate two alternative ways of applying ICA, in which either temporally independent components or spatially independent components are constructed. The temporal ICA method, which we simply abbreviate here as ICA, is preferred in this study since it provides temporally independent components that allow the development of a prediction model that is univariate in the predictand (see Section 3.2).

Let us assume that GRACE-TWS fields (in mm), after removing the temporal mean, are stored in the matrix $\mathbf{X}_{TWS} = \mathbf{X}_{TWS}(s, t)$, where t is the time, and s stands for spatial coordinate (grid points). Applying ICA means that \mathbf{X}_{TWS} is decomposed into spatial and temporal components as

$$\mathbf{X}_{TWS} = \mathbf{Y}_j \mathbf{A}_j^T, \quad (1)$$

249 where the columns of \mathbf{Y}_j contain the j dominant unit-less temporally inde-
 250 pendent components (ICs) of TWS, and the columns of \mathbf{A}_j represent the cor-
 251 responding spatial maps. Each temporal pattern (i.e. a column of \mathbf{Y}_j) along
 252 with the corresponding spatial pattern (a column of \mathbf{A}_j) represent an indepen-
 253 dent mode of variability. Similarly, the temporally centered maps of rainfall
 254 over West Africa $\mathbf{X}_{Rainfall}$, and of SST over the major oceans. Thus, \mathbf{X}_{SST}
 255 or $\mathbf{X}_{Rainfall}$ can separately be written as

$$\mathbf{X}_{SSTorRainfall} = \mathbf{U}_{j'} \mathbf{B}_{j'}^T, \quad (2)$$

256 where $\mathbf{U}_{j'}$ stores the j' dominant unit-less temporally independent components
 257 of SST or rainfall, and the columns of $\mathbf{B}_{j'}$ contain the associated spatial maps.
 258 We used different indices j and j' in Eqs. (1) and (2) to emphasize that the
 259 number of retained modes from different data sets are not necessarily the same.
 260 Selecting a proper subset (j or j') is addressed in Appendix B.

261 In our analysis, we found the spatial patterns associated with independent
 262 modes of total water storage anomalies, i.e. the columns of \mathbf{A}_j (Eq. (1)) to
 263 be sufficiently stable. This means that, for instance, the spatial patterns (\mathbf{A}_j)
 264 derived from 10 years of TWS data do not differ significantly from those de-
 265 rived from 8 or 12 years of data. Therefore, for building the forecasting model,
 266 we only link the temporal components (ICs) of the predictor data sets (all
 267 columns of $\mathbf{U}_{j'}$ derived from SSTs and TRMM-rainfall) to individual ICs of
 268 the predictand (each column of \mathbf{Y}_j in Eq. (1)). Finally, we will use the \mathbf{A}_j
 269 derived from TWS in order to reconstruct the forecasting maps. Details of the
 270 ICA decomposition and the corresponding error estimation are addressed in
 271 Appendix B.

272 3.2 Prediction using an Autoregressive Model with Exogenous Variables 273 (ARX)

274 An ARX process is governed by a system of linear difference equations, which
 275 describe the relationship between the current and previous values of the system
 276 output and the values of inputs. In our case, the ARX model is formulated
 277 as a multiple-inputs (the independent modes or ICs of SST and rainfall all
 278 together) and single-output (each IC of TWS) model (Ljung, 1987):

$$y(t) + \sum_{i=1}^{n_a} a_i y(t-i) = \sum_{q=1}^m \sum_{l=1}^{n_b} b_{q,l} u_q(t-k_q-(l-1)) + \xi(t), \quad (3)$$

279 where y represents a particular mode of TWS, i.e. $y(t)$, $t = 1, \dots, n$, represent
 280 a column of \mathbf{Y}_j in Eq. (1). In Eq. (3), n_a is the order of the ARX model with
 281 respect to the predictand, $u_q(t)$, $q = 1, \dots, m$, and $t = 1, \dots, n$, are ICs of
 282 SSTs and rainfall from $\mathbf{U}_{j'}$ in Eq. (2), while m is the number of predictors.
 283 The order of the ARX model with respect to the predictors is n_b , and k_q
 284 denotes the number of time-steps before the q 'th input (predictor) affects the
 285 output y , i.e. the dead time of the system. Finally, ξ allows for a white-noise

random input. The coefficients of the ARX models a_i , $i = 1, \dots, n_a$, and $b_{q,l}$, $q = 1, \dots, m$, and $l = 1, \dots, n_b$, have to be derived in the simulation step, using both predictand and predictors (Ljung, 1987). Once the coefficients are computed, in the forecasting step only the predictors (ICs of SST and rainfall) are used to estimate the values of TWS after the simulation period. Details of the computations and error propagation are addressed in Appendix B.

4 Dominant Independent Modes of TWS, SST, and Rainfall

When following the decomposition procedure as described in Section 3.1, we identify two independent, statistically significant, modes in GRACE GFZ-TWS (abbreviated as GFZ-TWS), four independent modes in SST changes over the Atlantic Ocean, three modes over the Pacific Ocean, and four modes over the Indian Ocean. For the rainfall changes, also four significant independent modes were obtained. Our approach for separating significant modes from the insignificant ones is also presented in Appendix B. Finally, table 1 summarizes the variance percentage of the modes discussed so far.

TABLE 1

Dominant Independent Modes Identified in Total Water Storage Variability

The first and second independent modes the we find in TWS anomalies derived from GRACE (GFZ solutions) are shown in Fig. 1,a. The first dominant independent mode, which explains 62.4% of variance, represents the annual water variability over West Africa. Here a damping of the signal magnitude can be seen in the year 2005 (temporal IC1 of GRACE GFZ-TWS). From the spatial pattern of IC1 GFZ-TWS, a concentration of annual variability appears to be dominant over the tropic and coastal regions. The second mode of GRACE-TWS contains inter-annual variations, along with periodic components of ~ 3 and 5 years period. Nicholson (2000) found a similar period in rainfall variations over West Africa. The second independent mode of GFZ-TWS represents 20.4% of the TWS variance, thus, the first two leading modes in Fig. 1 represent more than 80% of the total water storage variance over West Africs. In fact, the dominating annual and inter-annual variability of TWS are found well separated, and thus can be treated separately within the ARX simulation and prediction steps. We ascribe this behavior to the properties of the ICA decomposition method.

The separate treatments of the two annual and inter-annual variability of water storage components seems to be reasonable since they are likely due to different physical influences from environment (here the indicators SST and rainfall). Therefore, the mathematical relationship between TWS and its indicators must be separately weighted (i.e. coefficients a_i , $i = 1, \dots, n_a$, and $b_{q,l}$, $q = 1, \dots, m$ of IC1-GRACE and IC2-GRACE will be separately computed in Eq. 3). We would like to mention here that the oscillations that exist in

325 the extracted dominant independent modes are not necessarily explained by
 326 a fundamental annual or inter-annual cycle and its overtones. Therefore, for
 327 the decomposition and prediction procedures we chose not to reduce any such
 328 pre-defined oscillations (see also Schmidt et al. 2008b).

329 For comparison, we then projected WGHM-TWS and ITG2010-TWS on to
 330 the spatial patterns of Fig. 1,a, using Eq. (B2) (Appendix B). The results are
 331 shown by the black and gray lines in Fig. 1,a. The temporal patterns indicate
 332 that the annual TWS changes from WGHM (IC1 in Fig. 1,a) are comparable to
 333 those seen by GRACE, whereas at the inter-annual time scale they are different
 334 (see IC2 in Fig. 1,a). To confirm this finding, we also applied ICA (Eq. (1)) to
 335 the WGHM-TWS data, individually, with the results shown in Fig. 1,b. The
 336 first independent mode of WGHM-TWS (60.4% of variance) is comparable
 337 to that of GRACE-TWS, while the second mode of WGHM-TWS (spatial
 338 and temporal pattern of IC2-WGHM) that accounts for 16.4% of variance is
 339 found quite different from those of GRACE-TWS (both GFZ and ITG2010).
 340 This finding shows that WGHM-TWS and GRACE-TWS are not consistent at
 341 inter-annual time scale; compare Fig. 1,a with Fig. 1,b. We hypothesize that
 342 the difference could be attributed to the possible miss-modeling of surface
 343 water storage or water withdrawals over the region. Further research will be
 344 needed to address the exact cause of differences, but this is outside the scope
 345 of the current study.

FIGURE 1

346 *Dominant Independent Modes of Sea Surface Temperature and Rainfall Data*

347 Applying the ICA approach (Eq. (2)) to SST changes over the three ocean
 348 boxes shows that their first two independent modes are related to the annual
 349 variability of SST (IC1 and IC2 in Fig. 2,a,b, and c). Over the Atlantic, for
 350 instance, IC1 and IC2 are related to the annual dipole structure, which also
 351 very much correlate with IC1 of GFZ-TWS. The same damping of the annual
 352 amplitude in the year 2005 is seen for IC2-Atlantic SST, similar as with IC1
 353 of GFZ-TWS. Our result confirms that the recent annual variability of total
 354 water storage over West Africa is highly correlated with the Atlantic ocean-
 355 atmospheric interactions, reflected in the SST data (see similar findings in e.g.,
 356 Mohino et al., 2011). For the variance percentages that each mode represents,
 357 we refer to Table 1.

358 We find that the third mode of SST changes over the Atlantic and In-
 359 dian Ocean boxes represents semi-annual variability, while IC3-Pacific SST
 360 represents the ENSO pattern; we compared IC3-Pacific SST with the monthly
 361 ENSO pattern (shown by the Southern Oscillation Index (SOI)) provided by
 362 the Australian Bureau of Meteorology (<http://www.bom.gov.au/climate/enso/>).
 363 This showed a high correlation of 0.84 suggesting that the pattern is physically
 364 meaningful (IC3 in Fig. 2,b). We also found a significant correlation of 0.68
 365 between IC2 of GRACE-TWS (Fig. 1,a) and SOI, revealing a relationship
 366 between total water storage variability over West Africa and ENSO.

367 IC4-Atlantic SST represents a complicated pattern, which we do not at-
 368 tempt to interpret here. IC4-Indian SST (Fig. 2,c) follows the Indian Ocean
 369 Dipole (IOD) pattern (see e.g., Saji et al., 1999). Comparing our results to
 370 the IOD index derived from the Japan Agency for Marine-Earth Science and
 371 Technology (JAMSTEC, [http://www.jamstec.go.jp/frcgc/research/
 372 d1/iod/HTML/Dipole%20Mode%20Index.html](http://www.jamstec.go.jp/frcgc/research/d1/iod/HTML/Dipole%20Mode%20Index.html)) represents a significant cor-
 373 relation of 0.73. This shows that ICA fairly well extracts teleconnection pat-
 374 terns from SST data.

FIGURE 2

375 Four independent modes were extracted from TRMM-rainfall data, from
 376 which IC1-TRMM and IC2-TRMM relate to the annual rainfall variability
 377 with three months phase differences (Fig. 3). In 2005, a damping of the signal
 378 magnitude can be seen in IC2-TRMM, but it is less pronounced compared
 379 to that of IC2-Atlantic SST. This might be due to the fact that IC2-TRMM
 380 represents a local impact, compared to the large-scale interaction that IC2-
 381 Atlantic SST represents. IC3-TRMM and IC4-TRMM apparently represent
 382 the semi-annual rainfall variations. We found a lag of two months between the
 383 ICs of rainfall and those of TWS.

FIGURE 3

384 5 Predicting Total Water Storage with an Autoregressive Model

385 *Training Step*

386 To compute the best-fitting ARX model, we have inserted the first 72 months
 387 of each mode of GRACE GFZ-TWS (IC1 and IC2 in Fig. 1,a) and the first
 388 72 months of all temporal modes of SST and rainfall (ICs of Figs. 2 and 3)
 389 in Eq. (3). Before performing the training step of the ARX model, the data
 390 for January 2003, 2004, May 2003 and December 2008 were excluded from
 391 the input time series (ICs of SSTs and rainfall) to synchronize them with the
 392 GFZ-TWS time series. Then, we had to choose optimum n_a and n_b ; these were
 393 found experimentally by varying them between one to three. The time delay
 394 k_q was searched for between zero to three months. This was then followed by
 395 running the ARX simulation step (Eq. (3)). We did not consider higher orders
 396 for n_a and n_b since we would like to keep the forecasting model as simple as
 397 possible (e.g., Westra et al., 2008). For k_q , previous studies (e.g., Ahmed et
 398 al., 2011) found a delay of up to three months between SST-rainfall and TWS
 399 changes. The required coefficients for each ARX model Θ were computed using
 400 Eq. (B5) in Appendix B.

401 Our numerically simulated results for both IC1 and IC2 of GFZ-TWS sug-
 402 gest that an ARX model with $n_a=1$ and $n_b=3$ provides the best fit with the
 403 residuals passing the normality test. The RMS of differences between the sim-
 404 ulated TWS values from the ARX process and the ICs of GFZ-TWS (Eq.

(B6) in Appendix B) was used as the fit criterion. Two sets of k_q corresponding to the simulations of the IC1 and IC2 of GFZ-TWS were found and are presented in Table 2. Our simulation results indicate that the ARX models provide a fit of 93% and 83% for simulating the two dominant components of GFZ-TWS (IC1 and IC2 in Fig. 1,a), respectively. The simulation fit of ARX corresponding to IC2 of GFZ-TWS is, however, lower than that of IC1 since its temporal pattern appears much more complicated than the annual pattern in IC1. Therefore, it might have not been fully captured by the predictors (see Fig. 4).

TABLE 2

FIGURE 4

To assess the sensitivity of the ARX models (Eq. (3)) with respect to each input, first, for each IC of GFZ-TWS, each IC of Figs. 2 and 3 was individually inserted in Eq. (3) and the ARX model evaluated. For each IC of GFZ-TWS, therefore, an ensemble of 15 ARX-modeled TWS outputs was generated, and the correlations of these outputs and the ICs of GFZ-TWS were then computed. From the 15 ARX-generated TWS, those that represented the largest correlations with their corresponding IC of GFZ-TWS were likely to have the most influence on the prediction. Our results show that the ARX-outputs generated by IC1, IC2-Atlantic SST, and IC1-rainfall had the largest influences on the ARX model of IC1 GFZ-TWS. The prediction of IC2 GFZ-TWS was found to be sensitive to IC3-Pacific SST, IC3-Atlantic SST, and IC3-rainfall. The most sensitive indicators and the correlations of the associated outputs with the ICs of GFZ-TWS are presented in Table 3. One might use these results for model reduction of the original ARX process (see e.g., Westra et al., 2008), however, such a reduction was not applied in this study since (i) the fit derived from each of the 15 model run was smaller than that of original ARX run, and (ii) the ARX models apparently possessed sufficient degree of freedom to be computed based on the current indicators.

TABLE 3

ARX Forecasting Step and Validation

Having simulated the ARX model parameters for the two dominant independent modes of GFZ-TWS ($\hat{\Theta}$ is known from Eq. (B5), within the training step), we used the indicator time series, i.e. all ICs shown in Figs. 2 and 3 after the 72-months training period alone to predict ICs of GRACE GFZ-TWS changes for the years 2010 and 2011. The predictions were derived from Eq. (B8), and their uncertainties were evaluated using the Monte Carlo approach described in Appendix B. Training and forecast results are shown in Fig. 4a,b. Our prediction approach, therefore, uses only the process structure described in Section 3.2 and the determined lag relation between the predictors and ICs

442 of GFZ-TWS changes (i.e. Table 2). The fit of the forecast for the first leading
 443 mode of total water storage, when compared to the observed GFZ-TWS val-
 444 ues, after one year was found 79%, while after two years this reduced to 62%.
 445 As Fig. 4a also shows, after two years, the standard deviation of the propa-
 446 gated uncertainty is quite large. This suggests that the proposed approach is
 447 more or less reliable for predictions of up to two years. Fig. 4b shows that the
 448 fit of the forecast for the second leading independent pattern of total water
 449 storage after one year was reduced to 67%. After two years, a fit of 57% was
 450 found. Comparing projected values of WGHM-TWS (black lines in Fig. 1a)
 451 with the ICs of GFZ-TWS, during the first year of forecast, we found a fit of
 452 78% for the annual and a moderate fit of 53% for the inter-annual pattern.
 453 This result indicates that the TWS prediction from the proposed statistical
 454 method is indeed closer to the observed GFZ-TWS changes over West Africa,
 455 when compared to hydrological modeling. See the fit values in Table 4.

TABLE 4

456 Comparing the ARX-derived TWS predictions with the ICs of GFZ-TWS,
 457 during the forecast period, we found no apparent deviations between TWS
 458 time series (see Fig. 4a,b), thus, the reported fit values are significant. For
 459 the inter-annual time-scale, however, specific care should be taken since the
 460 simulation and prediction of the ARX-TWS method is very much sensitive
 461 to the temporal patterns of the input parameters. When the ICs of SSTs or
 462 rainfall are not well defined, the inter-annual forecast of ARX-TWS might
 463 perform poor or be biased. This has been tested by replacing the ICs of SSTs
 464 and TRMM-rainfall with temporal components derived e.g., from the principal
 465 component analysis (PCA) decomposition for running the ARX predictions
 466 (results are not shown). A bias was found in the prediction of IC2 GFZ-TWS,
 467 which was most likely due to the fact that the PCA-derived indicators (PCs
 468 of SST and rainfall) do not reflect the inter-annual TWS changes sufficiently.

469 In order to assess the robustness of the performed forecast with respect
 470 to the training period, we performed a backward simulation and forecast, i.e.
 471 the last 72 months of both indicators (ICs of SSTs and TRMM-rainfall) and
 472 predictands (individual ICs of GFZ-TWS) were used in the simulation step to
 473 predict the first two years of GFZ-TWS. The results, summarized in Fig. 5,
 474 show a fit similar to the forward forecast in Table 4. Therefore, even though the
 475 training step was quite short, no temporally variable bias was found in both
 476 forward and backward predictions. This confirms the robust performance of
 477 the proposed ICA-ARX approach, at least, with respect to the performed tests.

FIGURE 5

478 Inserting the time series of the prediction and the spatial components of
 479 Fig. 1,a in Eq. (1), one may reconstruct the TWS maps for the period when the
 480 ARX model and their inputs are available. In this case, our prediction values
 481 provide \mathbf{Y} and the spatial maps of Fig 1,a provide \mathbf{A} in Eq. (1). Fig. 6 compares
 482 the original GRACE GFZ-TWS values of the year 2010, after removing the

483 temporal mean of 2003 to 2011 and the contribution of Lake Volta (as derived
484 in Section 3), with the values of the ARX-TWS forecast. The predictions fit
485 quite well to GFZ-TWS fields. Fig. 6,c shows the difference between GFZ-TWS
486 and the predicted ARX-TWS. The patterns of the differences are similar to
487 the striping noise of GRACE solutions (Kusche, 2007). Our results, therefore,
488 support the idea of using the presented statistical approach for forecasting
489 TWS changes of West Africa.

FIGURE 6

490 6 Conclusions and Outlooks

491 This study suggests and investigates a new statistical multivariate seasonal
492 forecasting approach for total water storage (TWS), which uses sea surface
493 temperature and rainfall data alone to estimate TWS changes over West
494 Africa. The proposed ICA/ARX approach does not directly simulate the com-
495 plex physical process of ocean-land-atmosphere, but instead, it statistically
496 learns the relationships between main known physical processes of the region
497 (such as teleconnections and the soil-precipitation feedback) and uses it to
498 predict TWS (the parameter of interest). The successful implementation of
499 the proposed ICA/ARX approach relies on the proper selection of TWS in-
500 dicators and avoiding over-parametrization of the model, data homogeneity
501 and a learning phase that contains a thorough range of processes and impacts.
502 Therefore, the dependence of the statistical model on the climate characteris-
503 tics of the calibration period is often referred as a lack of model robustness. To
504 investigate this issue, we performed a numerical validation, which showed that
505 the seasonal forecast of TWS is close to TWS that is actually measured by
506 GRACE, see Table 4. Both forward and backward predictions indicate that the
507 proposed approach provides relatively stable large-scale seasonal TWS forecast
508 over West Africa. We also carried out an extensive uncertainty analysis and
509 were able to show that the predictability skills of the model is stable. However,
510 due to the estimated uncertainties, the results might not be significant after
511 about one year of forecast. We would like to mention here that the proposed
512 method is only able to provide predictions of total water storage, therefore,
513 hydrological modeling would be still required to partition TWS into different
514 compartments. Since the prediction method relies on the relationships be-
515 tween SST and rainfall as an indicator of TWS, we expect that the ICA/ARX
516 method, with its current parameterization, is most appropriate to be used over
517 those regions that exhibit strong interactions between ocean-atmosphere and
518 land water storage changes, which is the case over West Africa.

519 Since the proposed method is trained on GRACE products, it provides
520 relatively coarse resolution TWS maps. The approach also assumes that the
521 spatial pattern of TWS changes remains stationary within the two years of the
522 forecast. Before application, one should therefore analyze whether this assump-
523 tion is fulfilled for different time frames. This can be achieved by applying the

ICA technique to TWS time series of different length, and evaluating whether the dominant spatial patterns appear indeed invariant. Another issue is that the training of the ARX model was performed based on six years of the data. Since SST and rainfall are available for a longer period (e.g., for TRMM, since 1998), one could use TWS outputs of models for the time before 2002.8 and extend the training period. Addressing the impact of such extension in terms of the quality of the ARX coefficients and the consistency of the model-derived TWS with GRACE-TWS requires further research.

Our numerical results lead us to the hope that the presented statistical method could be helpful for filling the current gaps of the GRACE products (once every 162 days, one or two months of data is missing) and a possible gap period between GRACE and its successor mission GRACE-FO at least for certain regions such as West Africa. Another application of the presented approach could be the generation of near-real time GRACE forecasts. Product latency time of GRACE fields is currently two to three months, while using the suggested approach, one is able to forecast GRACE total water storage maps immediately as soon as rainfall and sea surface temperature data become available. Such near-real time predictions could be used for various drought/flood monitoring applications. Generating total water storage predictions, close to GRACE products, would be also possible by calibrating and/or assimilating GRACE products in hydrological models. Models improved in this way will then be used to simulate total water storage. Examples of such implementations can be found in studies e.g., Zaitchik et al. (2008), Werth et al. (2009b), Houborg et al. (2012), Xie et al. (2012), and Eicker et al. (2014). The computational load of such approaches is however much more heavy than with the proposed statistical ICA/ARX approach.

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Appendix A (Computational Details of Total Water Storage Fields)

In order to prepare the data sets for analysis, the following processing steps were applied.

- The GRACE Level-2 data that are used here, are derived in terms of fully normalized spherical harmonic (SH) coefficients of the geopotential fields (Flechtner, 2007). Firstly, the fields were augmented by the degree-1 term from Rietbroek et al. (2009) in order to include the variation of the Earth’s center of mass with respect to a crust-fixed reference system.
- GRACE SHs at higher degrees are affected by correlated noise and are, therefore, smoothed by applying the DDK2 decorrelation filter (Kusche et al., 2009). Werth et al. (2009a) found that the DDK2 filtered GRACE solutions are generally in good agreement with the output of global hydrological models. However, GRACE solutions are also contaminated by errors due to incomplete reduction of short-term mass variations by de-aliasing models (Forootan et al., 2013, 2014). We found that the impact of atmospheric de-aliasing errors on the GRACE-derived TWS over West Africa is negligible (see atmospheric errors over the Niger Basin in Forootan et al., 2014).
- GRACE DDK2 filtered solutions up to degree and order 120 were then used to generate the global TWS values according to the approach of Wahr et al. (1998).
- Similar to the GRACE products above, the DDK2 filter was applied to the gridded WGHM-TWS data set in order to preserve exactly the same spectral content as with the filtered GRACE products.
- After filtering, all data sets were converted to $0.5^\circ \times 0.5^\circ$ grids similar to the WGHM-TWS outputs.
- From each data set, a rectangular region that includes West Africa (latitude between 0° to $25^\circ N$ and longitude between -20° to $10^\circ E$) was selected.

Lake Volta (see Fig. A1) is one of the largest man-made reservoirs in the world, created by the Akosombo Dam, which holds back the water for generating hydro-electric power (for details see Speth et al., 2011). Satellite altimetry observations indicate a sharp increase of water level since mid 2007, where much of the excess water resulted from heavy rainfall within the catchment (Crétaux et al., 2011). This introduces an artificial TWS anomaly located over the lake, which is removed to avoid its misinterpretation with subsurface TWS changes. The equivalent water height (EWH) change of Volta was computed by assuming a grid mask representing a unit change in EWH of 1 mm over the entire lake surface and zero elsewhere. The grid mask has been converted into a set of spherical harmonic coefficients up to degree 120 and subsequently filtered using the same DDK2 filter used for filtering the original GRACE-TWS data. Then, each field was scaled using the lake height time-series (in mm) derived from the results of Crétaux et al. (2011). The averaged storage changes derived from GRACE-TWS (from GFZ) and altimetry are shown in Fig. A1. Both altimetry and GRACE GFZ-TWS indicate an increase of water

836 storage within the lake. The amplitude of the signal derived from GRACE
 837 GFZ-TWS is larger than that of the altimetry likely since GRACE-TWS also
 838 reflects the groundwater signal of the surrounding area of the lake. For the lake
 839 area, we estimate a TWS increase of $2.95 \pm 1.32 \text{ km}^3.\text{yr}^{-1}$, during 2003 to
 840 2010. The time series of Lake Volta water storage changes were then removed
 841 from GRACE-TWS fields (including both GFZ and ITG2010).

FIGURE A1

842 In order to compare the signal strength over the region, the signal root-
 843 mean-square value (RMS) and the linear trend of the three mentioned TWS
 844 data sets (GFZ, ITG2010, and WGHM) are computed for the period January
 845 2003 to August 2009, in which the three data sets were available (see Fig.
 846 A2). From the RMS, one concludes that all the three data sets show a strong
 847 variability over the tropical and the Gulf of Guinea coastal regions. The com-
 848 puted linear trends, however, are not consistent. Particularly, GRACE-derived
 849 TWS changes show a mass gain over Volta Lake, which we remove from the
 850 GRACE-TWS fields before performing decomposition. Removing such artifi-
 851 cial anomaly is necessary, since otherwise the amplitude of TWS forecast over
 852 the lake will be overestimated.

FIGURE A2

853 Appendix B (Details of ICA and ARX Methods)

854 This appendix provides details of computations regarding to the methodology
 855 described in Section 3.

856 The ICA Computations

857 ICA decomposition is performed here by applying a 2-step algorithm (Footan
 858 and Kusche, 2012) on the available data sets, where step 1 consists of data
 859 decorrelation using principal component analysis (PCA). In step 2, the j -
 860 dominant components of PCA are rotated to be as independent from each
 861 other as possible. Storing the available data in a $n \times p$ data matrix \mathbf{X} , after
 862 removing their temporal mean, where n is the number of months and p is the
 863 number of grid points, ICA decomposes \mathbf{X} as

$$\mathbf{X} \simeq \mathbf{X}_j = \bar{\mathbf{P}}_j \mathbf{R}_j \mathbf{\Lambda}_j \mathbf{R}_j^T \bar{\mathbf{E}}_j^T. \quad (\text{B1})$$

864 In Eq. (B1), $\bar{\mathbf{P}}_j \mathbf{\Lambda}_j \bar{\mathbf{E}}_j^T$ is derived from the PCA decomposition of \mathbf{X} in step
 865 1. Therefore, $\mathbf{\Lambda}_j$ is an $j \times j$ diagonal matrix that stores the singular values
 866 arranged with respect to the magnitude, $\bar{\mathbf{E}}_j$ ($j \times p$) contains the corresponding
 867 unit-length spatial eigenvectors, $\bar{\mathbf{P}}_j$ ($n \times j$) contains the associated normalized
 868 temporal components, and $j < n$ is the number of retained dominant modes

869 (Preisendorfer, 1988). The orthogonal rotation matrix $\hat{\mathbf{R}}_j$ ($j \times j$) is defined in
 870 step 2, so that it rotates PCs and make them as statistically independent as
 871 possible. The method equals to temporal ICA (Forootan and Kusche, 2012),
 872 which is simply called ICA in the paper. Considering Eqs. (1) and (2), \mathbf{Y}
 873 and \mathbf{U} are equivalent to $\bar{\mathbf{P}}\mathbf{R}$, while \mathbf{A} and \mathbf{B} are equivalent to $\mathbf{\Lambda}\bar{\mathbf{E}}\mathbf{R}$. An
 874 optimum \mathbf{R} was found by diagonalization of the fourth-order cross cumulants
 875 of the dominant temporal components $\bar{\mathbf{P}}$ (see details in Forootan and Kusche,
 876 2012).

877 For properly selecting the subspace dimension j or j' , we used a Monte
 878 Carlo approach which simulates data from a random distribution $\mathbf{N}(\mathbf{0}, \mathbf{\Sigma})$,
 879 with $\mathbf{\Sigma}$ containing the column variance of \mathbf{X} . The null hypothesis is that \mathbf{X}
 880 is drawn from such a distribution (see also Preisendorfer, 1988, pages 199 to
 881 205). To apply the rule, 100 time series realizations of $\mathbf{N}(\mathbf{0}, \mathbf{\Sigma})$ are generated,
 882 their eigenvalues computed and placed in decreasing order. The 95th and 5th
 883 percentile of the cumulative distribution are then plotted (red lines in Fig.
 884 B1). Eigenvalues from the actual data sets that are above the derived confi-
 885 dence boundaries are unlikely to result from a data set consisting of only
 886 noise. To estimate the uncertainties of the eigenvalues, we randomly selected
 887 a subsample of \mathbf{X} and applied PCA, then selected another subsample and
 888 repeated this operation 200 times. This approach follows the ‘bootstrapping’
 889 method as presented e.g., in Efron (1979) and yields uncertainty estimates (see
 890 error-bars in Fig. B1). The repeat number of 200 is chosen experimentally to
 891 be sure that the distribution of the estimated eigenvalues is independent from
 892 the selections of the subsamples.

893 To illustrate what we described above, Fig. B1 shows the eigenvalue spec-
 894 trum of the centered time series of GRACE GFZ-derived TWS, SST and
 895 rainfall computed using PCA. The significance levels are shown by red lines
 896 and the error-bars show the uncertainties of eigenvalues. The eigenvalues above
 897 the red lines are statistically significant. The significant eigenvalues along with
 898 their orthogonal components are rotated towards independence using Eq. (B1)
 899 and interpreted in Section 4.

FIGURE B1

900 Based on the uncertainties of the PCA results (Fig. B1), in order to es-
 901 timate the uncertainty of the ICs (Eq. (B1)), we generated 100 realizations
 902 of \mathbf{X} , reconstructed by $\bar{\mathbf{P}}_j$, $\mathbf{\Lambda}_j$, and $\bar{\mathbf{E}}_j$ along with 100 realizations of their
 903 errors. Then, applying Eq. (B1) to the realizations allows the estimation of
 904 uncertainties (see e.g., error-bars in Figs. 1, 2, and 3).

905 The projection of the data \mathbf{X} onto the i 'th spatial pattern of the ICA
 906 $\hat{\mathbf{p}}_i = \mathbf{X}\hat{\mathbf{e}}_i$, provides its corresponding temporal evolution

$$\hat{\mathbf{p}}_i(t) = \sum_{s=1}^p x(t, s) \hat{\mathbf{e}}_i(s), \quad (\text{B2})$$

907 where t is time ($1, \dots, n$) and s is the number of grid points ($1, \dots, p$).

908 The ARX Computations

909 Considering Eq. (3) as the ARX model, the ARX-forecast requires two steps:
 910 (i) The coefficients (a_1, \dots, a_{n_a}) and $(b_{q,1}, b_{q,2}, \dots, b_{q,n_b}), q = 1, \dots, m$ are
 911 estimated, e.g., using a least squares approach. This step is usually referred
 912 as ‘simulation’ or ‘training step’ in literature (see e.g., Ljung, 1987). Step (i)
 913 is performed under the assumption that the output and inputs up to the time
 914 $t = t_n - 1$ are known. Furthermore, the outputs and exogenous values on
 915 the right hand side of Eq. (3) are not stochastic. To avoid negative indices,
 916 one might consider the observations $\mathbf{y}(t) = [y(t), y(t-1), \dots, y(c)]^T$, where
 917 $c = \max(n_a, n_b) + \max(k_q) + 1$. Eq. (3) is expanded as

$$\mathbf{y} = \begin{bmatrix} -y(t-1) & \dots & -y(t-n_a) & u_q(t-k_q) & \dots & u_q(t-k_q-n_b+1) \\ -y(t-2) & \dots & -y(t-n_a-1) & u_q(t-k_q-1) & \dots & u_q(t-k_q-n_b) \\ \vdots & & \vdots & \vdots & & \vdots \\ -y(c-1) & \dots & -y(c-n_a) & u_q(c-k_q) & \dots & u_q(c-k_q-n_b+1) \end{bmatrix} \begin{bmatrix} a_1 \\ \vdots \\ a_{n_a} \\ b_{q,1} \\ \vdots \\ b_{q,n_b} \end{bmatrix} + \boldsymbol{\Xi}(t), \quad (\text{B3})$$

918 $q = 1, \dots, m$ and $\boldsymbol{\Xi}(t) = [\xi(t), \xi(t-1), \dots, \xi(c)]^T$. Eq. (B3) can be re-written
 919 compactly as

$$\mathbf{y}(t) = \boldsymbol{\Phi}(t)\boldsymbol{\Theta} + \boldsymbol{\Xi}(t). \quad (\text{B4})$$

920 The least squares estimation of the unknown coefficients is derived from

$$\hat{\boldsymbol{\Theta}} = \left(\boldsymbol{\Phi}(t)^T \boldsymbol{\Phi}(t) \right)^{-1} \boldsymbol{\Phi}(t)^T \mathbf{y}(t). \quad (\text{B5})$$

921 The quality of the fit (η) can be assessed by computing the signal-to-noise
 922 ratio as

$$\eta = 1 - \frac{\mathbf{y}(t)^T \boldsymbol{\Phi}(t) \hat{\boldsymbol{\Theta}}}{\mathbf{y}(t)^T \mathbf{y}(t)}. \quad (\text{B6})$$

923 The residual of the ARX model ($\hat{\boldsymbol{\Xi}}(t) = [\hat{\xi}(t), \hat{\xi}(t-1), \dots, \hat{\xi}(c)]^T$) can be
 924 estimated as

$$\hat{\boldsymbol{\Xi}}(t) = \mathbf{y}(t) - \boldsymbol{\Phi}(t) \hat{\boldsymbol{\Theta}}. \quad (\text{B7})$$

925 In step (ii), based on $\hat{\boldsymbol{\Theta}} = [\hat{a}_1 \dots \hat{a}_{n_a} \hat{b}_{q,1} \hat{b}_{q,2} \dots \hat{b}_{q,n_b}]^T$, when the inputs
 926 $u_q(t)$ are known, one can forecast the output $\hat{y}(t_n)$ at time t_n using

$$\hat{y}(t_n) = - \sum_{i=1}^{n_a} a_i y(t_n - i) + \sum_{q=1}^m \sum_{l=1}^{n_b} b_{q,l} u_q(t_n - k_q - (l-1)). \quad (\text{B8})$$

927 To estimate the uncertainty of the ARX simulation, using Monte Carlo sam-
 928 pling, we numerically generate several realizations of the ICs (described be-
 929 fore). By inserting them into Eq. (3) and fitting ARX models, we are able

930 to perform an error assessment of the fitted model up to the time t_n . For er-
931ror estimation of the forecast (the ARX value at the time $t_n + 1$ and later),
932 however, one should compute an accumulated error, since there is no observed
933value for the output y at time $t_n + 1$ and later.

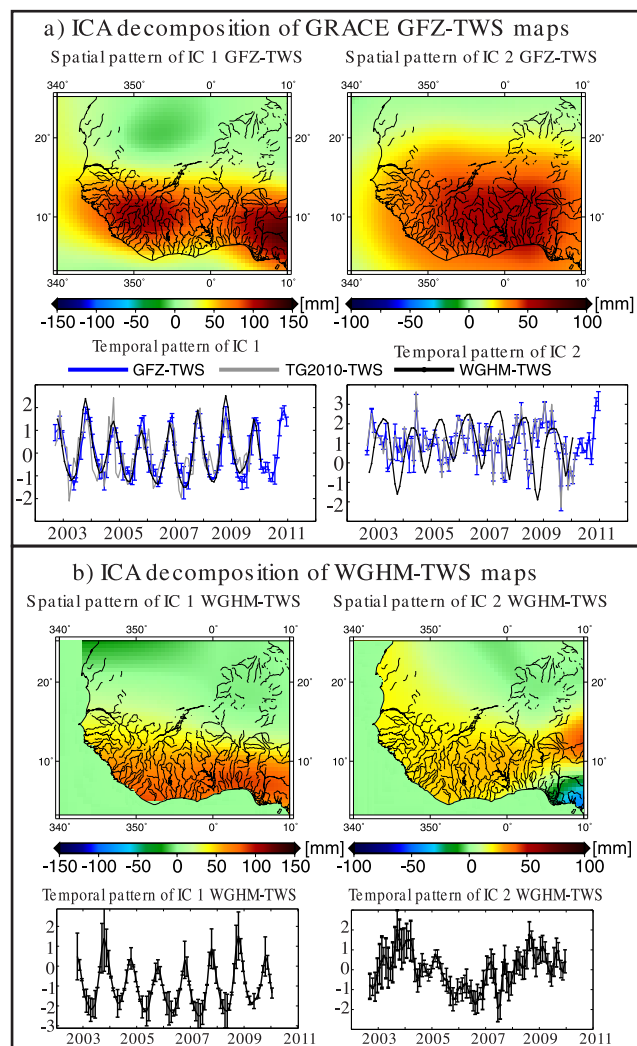


Fig. 1 Overview of the ICA decomposition of TWS changes over West Africa (counted as predictands). a) ICA decomposition of GRACE GFZ-TWS data (GFZ-TWS). For comparisons, WGHM-TWS and ITG2010-TWS changes are projected on the spatial patterns of IC1 and IC2, using Eq. B2 in Appendix B. The results are presented along with temporal ICs of GFZ-TWS. b) ICA decomposition of WGHM-TWS maps. The variance fraction of each independent mode is presented in Table 1. Uncertainties are shown by error-bars around temporal components. Details of uncertainty computations can be found in Appendix B.

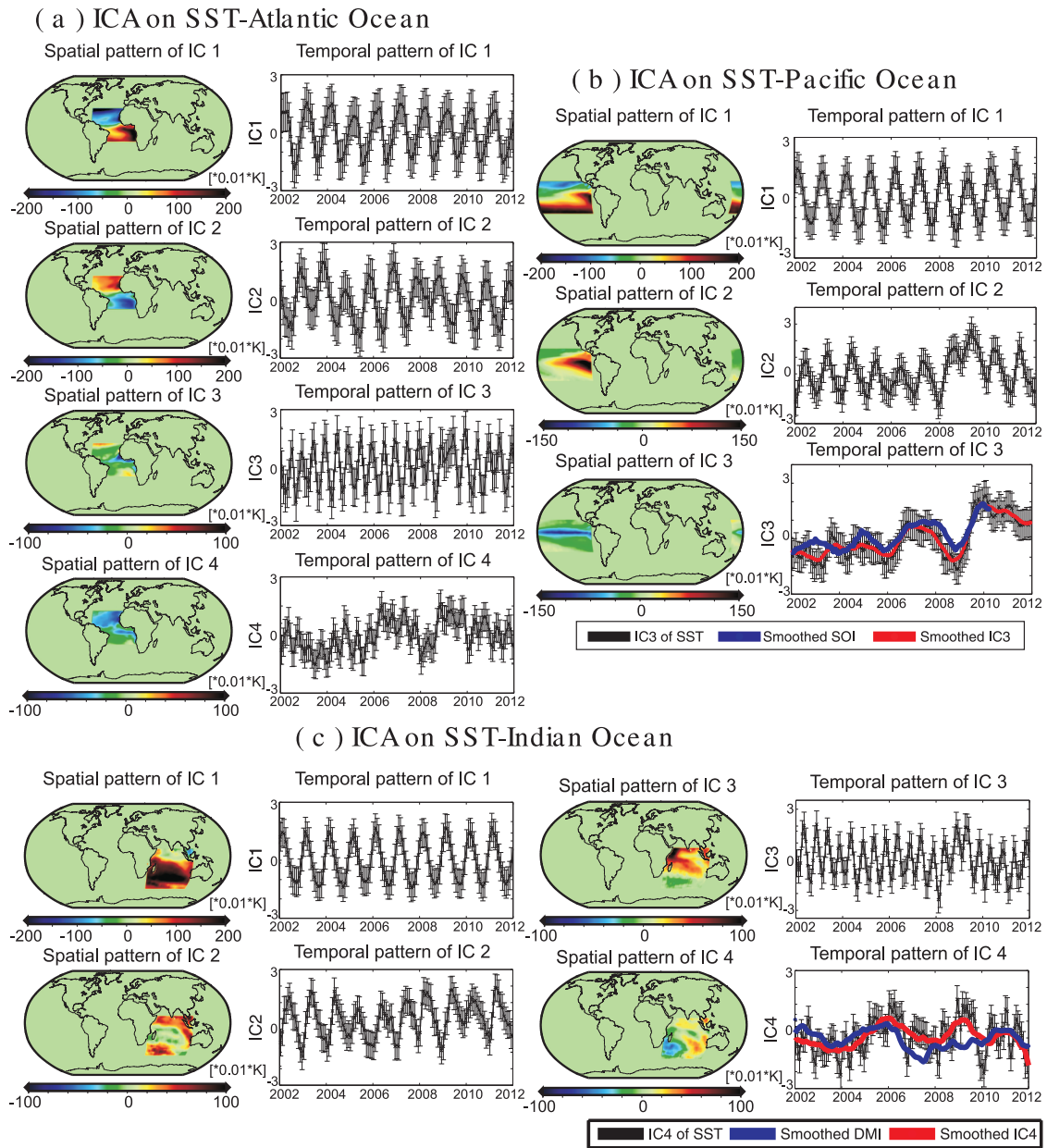


Fig. 2 Overview of ICA decomposition applied on the SST changes over (a) the Atlantic, (b) Pacific, and (c) Indian Oceans. The variance fraction of each independent mode is presented in Table 1. Uncertainties are shown by error-bars around temporal components. The smoothed temporal patterns in (a) and (b) are derived by applying a 12-month moving average filter.

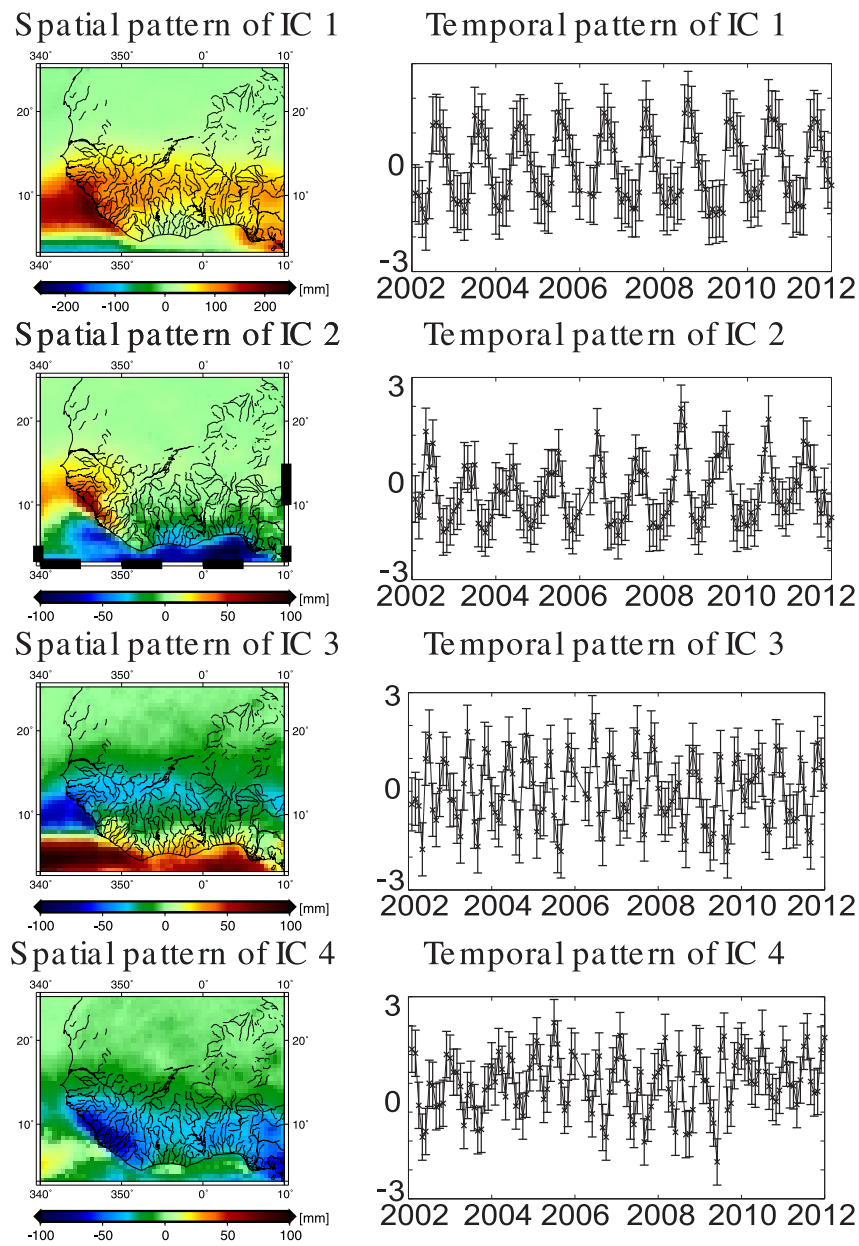


Fig. 3 Overview of ICA decomposition applied on rainfall changes over West Africa. The variance fraction of each independent mode is presented in Table 1. Uncertainties are shown by error-bars around temporal components.

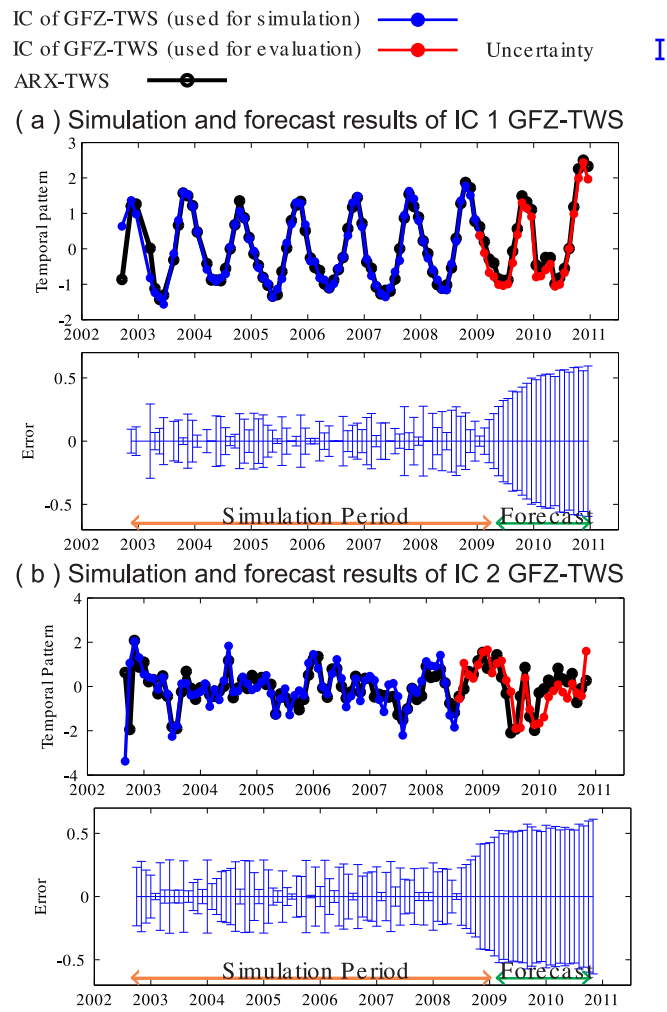


Fig. 4 Results of simulations and forecasts of IC1 and IC2 of GRACE GFZ-TWS (Fig. 1,a), using the ARX models (shown by black-lines). Fig. 4a(top) represents the results for IC1 of GRACE GFZ-TWS while assuming the ICs of Figs. 2 and 3 as indicators. Fig. 4a(bottom) shows the uncertainty of the forecast on top. Fig. 4b(top) represents the same results as (a) but corresponding to IC2 of GRACE GFZ-TWS. Fig. 4b(bottom) indicates the uncertainty of the forecast on top. For simulation, the first 72 months of TWS are used (shown in blue). TWS values after the 72th month are then used for evaluating the forecasts (shown in red). Reconstructing the forecast for the year 2010 and its comparison with the original GRACE GFZ-TWS fields are presented in Fig. 6.

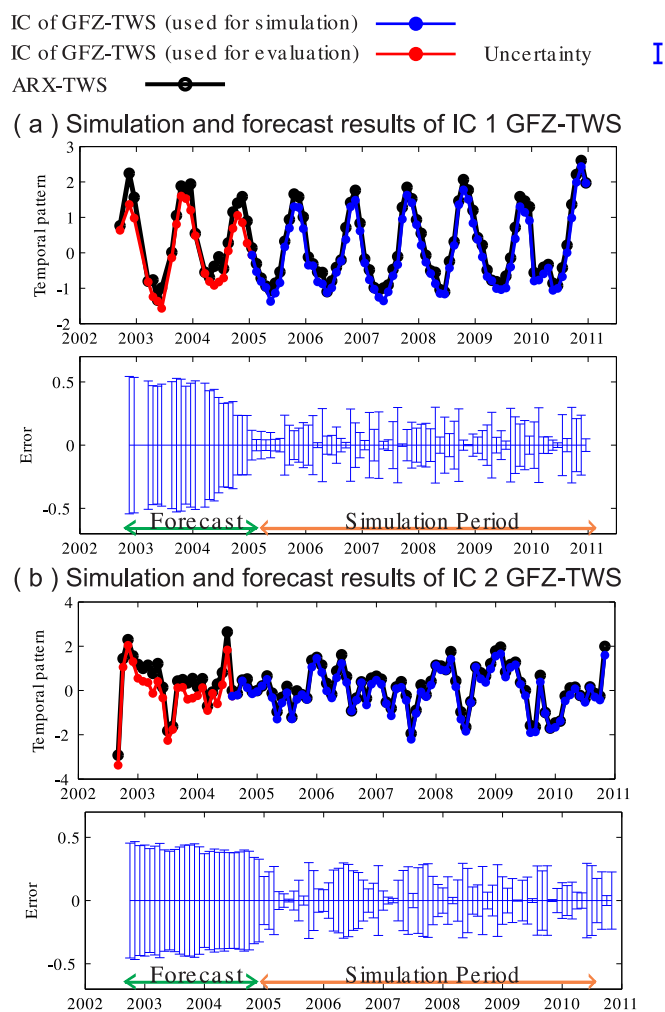


Fig. 5 Backward simulations and forecasts of IC1 and IC2 of GRACE GFZ-TWS (Fig. 1,a), using the ARX models (shown by black-lines). The results are similar to those of Fig. 4, however here, the last 72 months of both indicators (ICs of SSTs and TRMM-rainfall) and predictands (individual ICs of GRACE GFZ-TWS) are used in the simulations and the first two years of IC1 and IC2 of GRACE GFZ-TWS predicted. Fig. 5a(top) represents the results for IC1 of GRACE GFZ-TWS. Fig. 5a(bottom) shows uncertainty of the forecast on top. Fig. 5b(top) represents the same results as (a) but corresponding to IC2 of GRACE GFZ-TWS. Fig. 5b(bottom) indicates the uncertainty of the forecast on top.

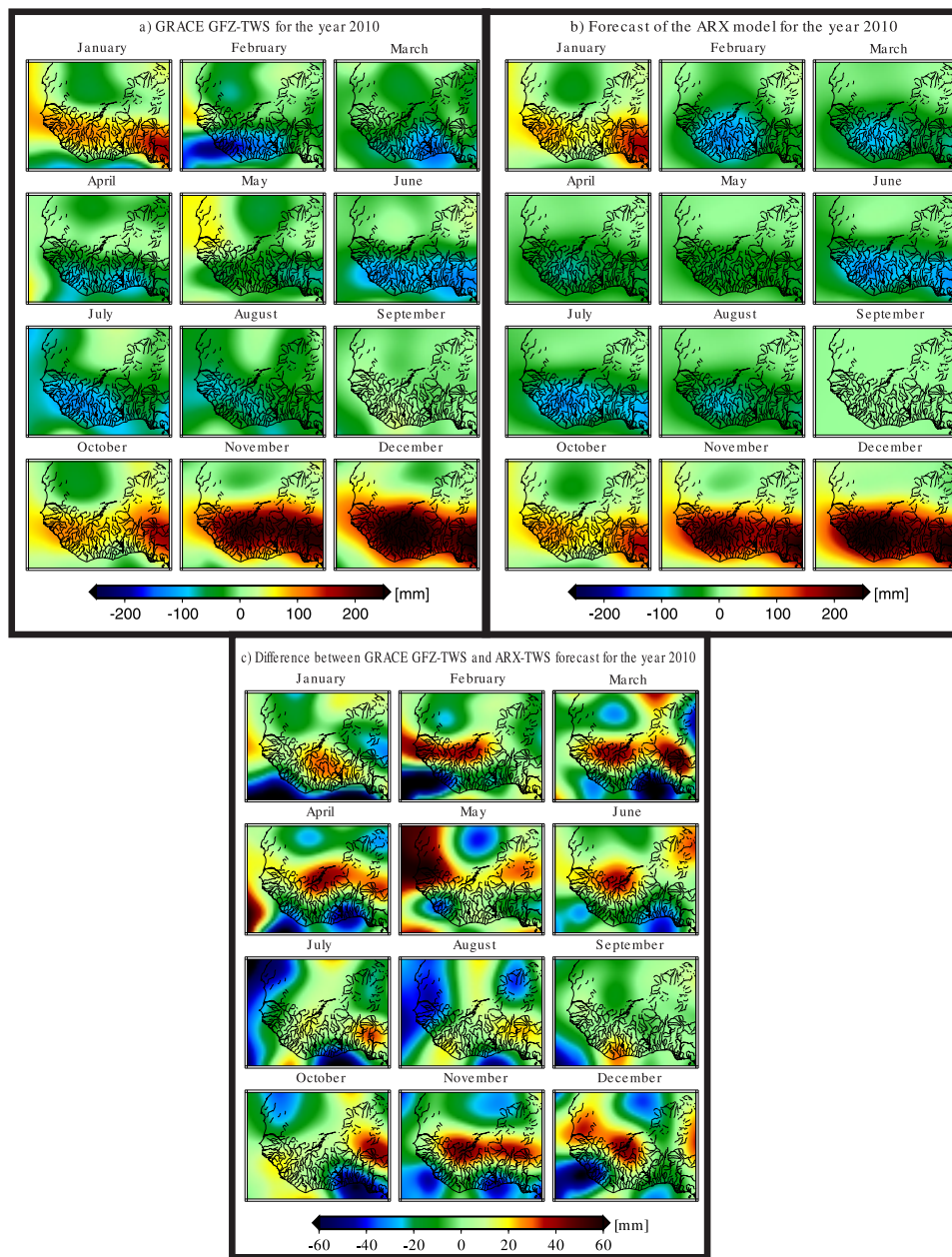


Fig. 6 Overview of TWS maps for the year 2010 over West Africa, without the signal of Volta, and after removing the temporal mean of 2003 to 2011. (a) TWS maps derived from GRACE (GFZ RL04 data), (b) TWS maps derived from the statistical forecast (the ARX models and ICA results), and (c) the differences between (a) and (b).

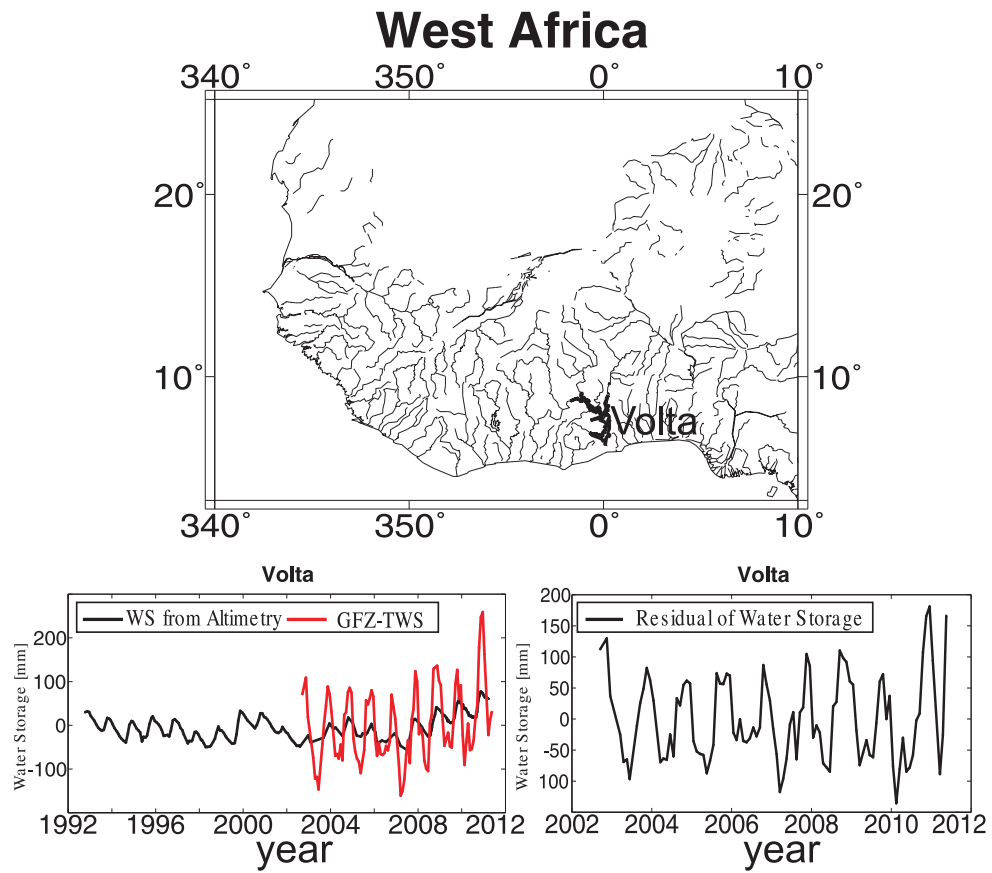


Figure A1: Overview of water storage changes of Volta Lake. The graph on top shows the location of the lake, while that of the bottom-left compares the averaged contribution of Volta lake level changes (derived from altimetry in black) with the averaged TWS variations derived from GRACE (GFZ-TWS products, in red). The bottom-right graph shows the GRACE GFZ-TWS signal after removing the water storage signal of Lake Volta.

Results for the period January 2003 to August 2009

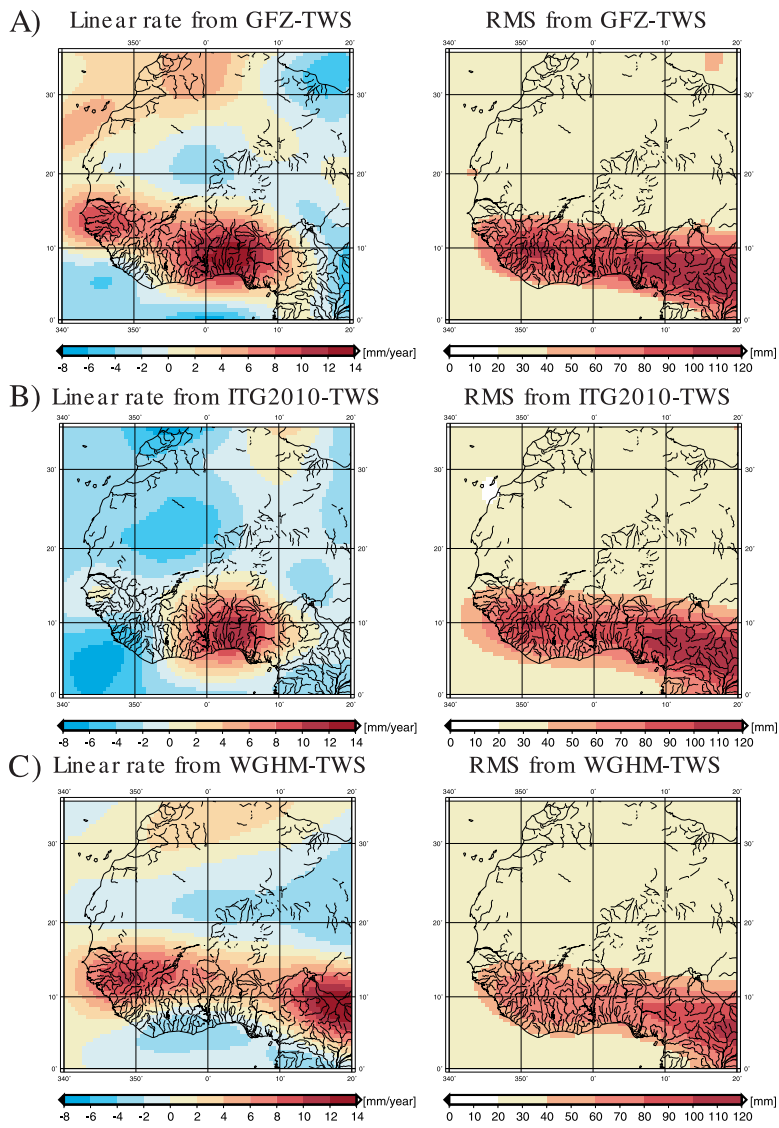


Figure A2: Comparing the signal variability (RMS) and linear trends of TWS data used in this study after smoothing using the Kusche et al. [2009]'s DDK2 filter. (A) TWS data of GRACE GFZ RL04, (B) TWS data of GRACE ITG2010, and (C) TWS of WGHM.

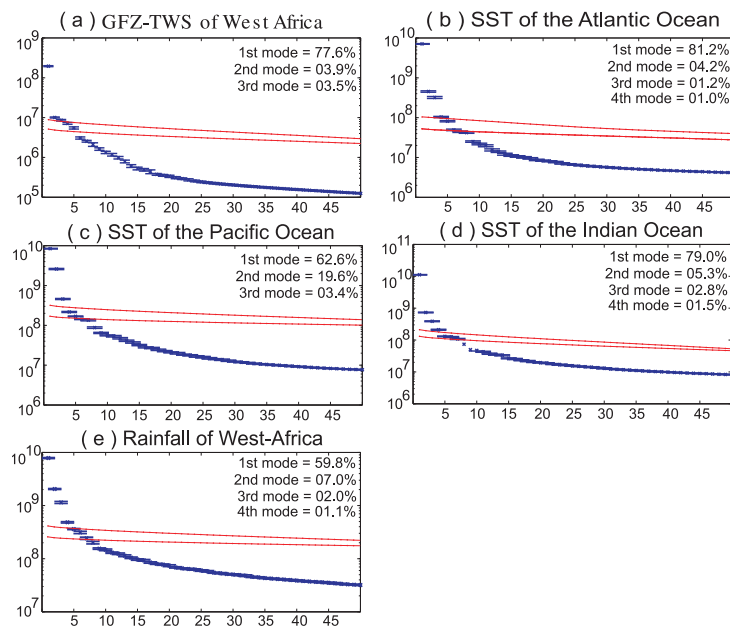


Figure B1: Eigenvalue results derived from implementing the PCA method on (a) time series of GRACE GFZ-TWS maps, (b) maps of SST over the Atlantic, (c) maps of SST over the Pacific, (d) maps of SST over the Indian Ocean basins, and (e) West-African rainfall maps from TRMM. Uncertainties are shown by error-bars around each eigenvalues. The red lines correspond to the significant test, described in Appendix B. The variance fractions of the dominant eigenvalues are represented in each graph.

Table 1 List of the variance percentage that each of the independent mode in Section 4 represents. Independent modes of GRACE GFZ-TWS are shown in Fig. 1, a and b, those of the Atlantic, Pacific and Indian Ocean-SST are shown in Fig. 2. Fig. 3 contains the independent modes of TRMM-rainfall.

	First Independent Mode	Second Independent Mode	Third Independent Mode	Fourth Independent Mode
GRACE GFZ-TWS	62.4%	20.4%		
WGHM-TWS	60.4%	16.4%		
Atlantic Ocean-SST	46.4%	25.4%	11.7%	4.1%
Pacific Ocean-SST	55.6%	15.4%	14.6%	
Indian Ocean-SST	47.8%	15.4%	14.3%	11.1%
TRMM-rainfall	44.2%	12.3%	6.9%	6.4%

Table 2 Time delays k_q derived from simulation of IC1-GRACE GFZ-TWS and IC2-GRACE GFZ-TWS. The values are in month and denote the number of time-steps before each predictor (ICs of SSTs and ICs of TRMM-rainfall respectively in Figs. 2 and 3) affect the output (each individual IC of GRACE GFZ-TWS in Fig. 1, a).

	IC1 SST Atlantic Ocean	IC2 SST Atlantic Ocean	IC3 SST Atlantic Ocean	IC4 SST Atlantic Ocean	IC1 SST Pacific Ocean	IC2 SST Pacific Ocean	IC3 SST Pacific Ocean	IC1 SST Indian Ocean	IC2 SST Indian Ocean	IC3 SST Indian Ocean	IC4 SST Indian Ocean	IC1 TRMM West Africa	IC2 TRMM West Africa	IC3 TRMM West Africa	IC4 TRMM West Africa
k_q related to IC1 of GFZ-TWS	1	0	2	1	0	3	1	1	0	1	0	0	3	3	1
k_q related to IC2 of GFZ-TWS	1	0	1	1	0	1	1	0	1	0	1	1	3	1	3

Table 3 List of the most sensitive indicators derived from the ARX models for each input and the computed correlation of the output with IC1 and IC2 of GRACE GFZ-TWS. Correlations are derived at 95% level of confidence.

Rank:	1	2	3
Model run by:	IC1 SST Atlantic Ocean	IC2 SST Atlantic Ocean	IC1 TRMM-rainfall West Africa
Correlation with IC1 of GFZ-TWS	0.81	0.61	0.52
Model run by:	IC3 SST Pacific Ocean (ENSO)	IC3 SST Atlantic Ocean	IC3 TRMM-rainfall West Africa
Correlation with IC2 of GFZ-TWS	0.59	0.46	0.42

Table 4 List of the computed fit values (Eq. B6) derived from comparing the ARX-TWS outputs with the IC1 and IC2 of GRACE GFZ-TWS. We also compared the projected values of WGHM-TWS in Fig. 1 with the IC1 and IC2 of GRACE GFZ-TWS. The values indicate that the ARX outputs are closer to that of GRACE GFZ-TWS.

	Simulation period (72 months)	First year of the forecast	Second year of the forecast
Fit values of the ARX model with respect to IC1 of GFZ-TWS:	93%	79%	62%
Fit values of the ARX model with respect to IC2 of GFZ-TWS:	83%	67%	57%
Fit values of the WGHM model with respect to IC1 of GFZ-TWS:	91%	78%	43%
Fit values of the WGHM model with respect to IC2 of GFZ-TWS:	54%	53%	31%