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1	Numerical study on spout elevation of a gas-particle spout fluidized
2	bed in microwave-vacuum dryer
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17	Abstract:
18	The dynamic characteristics of gas-particle spout fluidized bed in a pulsed spouted
19	microwave-vacuum drying system (PSMVD) were investigated. The spout fluidization
20	process in a pseudo-2-D spout fluidized bed was simulated by computational fluid dynamics
21	(CFD) using the inviscid two-fluid theory method (TFM) based on the kinetic theory of
22	granular flow. The dynamic characteristics of the spout fluidized bed and the effect of spout

elevation on the particle movement were revealed, which could be used to improve the uniformity of particle mixing and microwave heating. The mathematical model demonstrated that the spout fluidization process includes isolated, merged and transitional jets and the fluidization at a specific spout gas velocity has a start-up stage and a quasi-steady fluidization stage. The spout velocity was an important factor controlling particle status in the spout fluidized bed and a critical velocity was identified for effect transition of the flow pattern. There was an approximately linear correlation between the jet penetration depth and the spout velocity. When the spout gas velocity increased up to the critical velocity region, the pressure drop tended to convert from negative pressure to positive pressure.

Keywords: Microwave-vacuum dryer; Spout fluidized bed; Fluid dynamics; CFD model

Nomenc	lature	Δt	time step (s)				
C _D	drag force coefficient	ū	velocity vector (m/s)				
d_p	particle diameter (m)	u _{spout}	spout velocity (m/s)				
$\vec{\mathbf{r}}$, $\vec{\mathbf{r}}$, $\vec{\mathbf{r}}$		Greek symbols					
F	net force (N/m ⁻)	3	volume fraction				
8	acceleration due to gravity (m/s^2)	ρ	density (kg/m ³)				
Н	bed height (m)	μ	viscosity (Ns/m ²)				
L	nozzle width (m)	Subscr	ipts				
Р	pressure (N/m ²)	g	gas				
ΔP	bed pressure drop (N/m ²)	р	particle				
Re	Reynolds number						
t	time (s)						

36 **1. Introduction**

37 In recent years, microwave-vacuum drying (MVD) has been tentatively applied in food 38 industry as a potential drying method for obtaining high quality food products, including dried 39 fruits, vegetables and grains (Zhang et al. 2010, Li et al. 2011). MVD possesses the 40 advantages of both microwave heating and vacuum drying. The combination of low 41 temperature and fast mass transfer conferred by vacuum drying and rapid energy transfer by microwave heating generates a very rapid, low temperature drying process and has the 42 43 potential to improve energy efficiency and product quality. Although MVD can offer unique 44 advantages, the inherent problem preventing its widespread application is the nonuniform temperature distribution caused by uneven spatial distribution of the electromagnetic field 45 46 inside the drying cavity, which results in hot and cold spots in the dried product (Li et al, 47 2011). The nonuniform temperature distribution in microwave drying also causes an issue of microbial safety in food products (Vadivambal et al. 2010, Jangam et al. 2011). 48

49 The heating uniformity of MVD is influenced by many factors, such as vacuum cavity 50 effects, product physical attributes and geometry, spatial location, and spatial electromagnetic 51 field intensity in the microwave cavity (Zhang et al. 2006, 2010). Many researchers have 52 studied the MVD characteristics of food materials, both experimentally (Hu et al. 2006, 53 Huang et al. 2011, Nahimana et al. 2011) and theoretically using analytical and mathematical 54 methods (Giri et al. 2007, Han et al. 2010, de Jesus et al. 2011). Various field-averaging 55 methods have been developed to achieve the heating uniformity. The MW energy averaging 56 can be accomplished by either mechanical means (Torringa et al. 1996) or through pneumatic 57 agitation (Feng et al. 1998; Balakrishnan et al. 2011).

58 Fluidization provides a pneumatic agitation for particles in the drying bed. It also facilitates 59 heat and mass transfers due to a constantly renewed boundary layer on the particle surface 60 (Feng et al. 2001, Jambhale et al. 2008). Therefore, combination of fluidized or spouted bed 61 drying with MVD is considered as an effective means of solving the uneven heating problem. 62 It is well known that coarse food particles such as diced or sliced materials are difficult to be 63 fluidized by a conventional fluid bed, especially when their moisture content is relatively high 64 and surface is sticky. However, pulsed spouted bed can be used for fluidizing the coarse 65 particles. Although a few researchers have performed some experimental investigations on the 66 drying characteristics of food materials by this new technique (Wang et al. 2012, 2013), more work about fluidization need to conducted to understand the drying mechanism in pulsed 67 68 spouted microwave-vacuum drying (PSMVD).

69 Computational fluid dynamic (CFD) approach has been recognized as a useful tool to 70 obtain detailed hydrodynamics of a complex gas-solid flow (Rahimi et al. 2013). Two 71 different methods are generally used for modeling dispersed phase flows in fluidized and 72 spouted bed, namely, Eulerian-Eulerian (EE) and Eulerian-Lagrangian (EL) methods (Pai and 73 Subramaniam 2009). In EL or discrete element method (DEM), the continuous phase flow is 74 evaluated by Eulerian approach, while the individual particle trajectories are evaluated by 75 Lagrangian approach. Although the EL approach requires less modeling assumption for the 76 particulate phase, it requires highly efficient computation to analyze dense gas-solid fluidized 77 beds (Pritchett et al. 1978, Bouillard et al. 1989). Two-fluid model (TFM) based on the EE 78 method is a popular approach requiring smaller CPU and memory resources, and has been 79 used in a large number of studies (Gidaspow et al. 1994, 2004). In the TFM model, the two

80 phases are treated as interpenetrating continua. This approach has been successfully utilized 81 for predicting and validating hydrodynamics of the gas-solid systems. For example, 82 Passalacqua and Marmo (2009) used the TFM to predict bubble diameter in a bubbling fluid 83 bed with a central jet and the bubble diameter distribution in a uniformly fed bubbling 84 fluidized bed. Zhong et al. (2010), Wang et al. (2007) and Pei et al. (2009) have also applied 85 the TFM in studying hydrodynamics of spout-fluid bed, fluidized bed coal gasification, 86 circulating fluidized beds and jet fluidized beds, respectively. The success of a TFM depends on the proper description of the interfacial forces and the constitutive models for solid and 87 88 fluid stresses. The interfacial forces are used to describe the momentum transfer between the 89 phases, which significantly affects the hydrodynamic behavior of the two-phase flows.

In the present study, the effect of combining a pseudo two-dimensional spout fluidized bed in a pulsed spouted microwave-vacuum drying system (PSMVD) was investigated using the TFM method. The dynamic characteristics of the gas-particle spout fluidized bed and the effect of spout elevation on particle movement at different spout gas velocity conditions were revealed, which could be used to improve the uniformity of particle mixing and heating in a PSMVD system.

96

97 **2. PSMVD equipment and materials**

98 2.1. PSMVD equipment

An experimental equipment was designed in our laboratory for the PSMVD study, which
 consisted of the following seven basic components. The schematic diagram of the PSMVD
 system was shown in Figure 1.

- 102 (1) a cylindrical multimode microwave cavity (Figure.1-3), equipped with four microwave
- 103 generators (at 2,450 MHz);
- 104 (2) a circular duct vacuum drying chamber (Figure.1-6);
- 105 (3) a pulse-spouted system (Figure.1-11,12,13,14), equipped with a set of adjustable gas
- 106 flow and distributive unit as well as a set of air handing units of 1m3/min capacity;
- 107 (4) a heat supply system (Figure.1-4). Each magnetron's power output was in the range of
- 108 0.1 to 1.0kW by a GPA-1800W microwave power controller;
- 109 (5) a water load system (Figure.1-5), which was added to prevent the magnetron from
- 110 overheating;
- 111 (6) a vacuum system (Figure.1-7,8,9,10) equipped with a cooler and a water-ring vacuum
- 112 pump with a pumping rate of 1m3/min.
- 113 The pressure inside the drying chamber could be regulated in the range of 3.5 to 100 kPa.

114 <Figure 1>

- 115 **2.2. Materials**
- 116 Fresh stem lettuce (Lactuca sativa) obtained from Haitong Food Group farm in Ningbo
- 117 city, China, was used as a model drying material. In this study, the lettuce particle is
- simplified as spherical particle with a diameter of 5 mm. The physical properties of lettuce
- dices were measured and the details were shown in Table 1, which represented a typical food
- 120 particle for drying (Wang et al. 2012).
- 121 **3.** Computational models and method

122 **3.1. The hydrodynamic model**

123 In the present study, the inviscid two-fluid theory (Gidaspow 1994; 2004) was used to

124 investigate both the fluid and particle movements in a gas-solid spout fluidized bed under 125 vacuum pressure conditions. The continuity and momentum equations of describing gas and 126 particle flows are given below:

127 Continuity equations:

128 Particle phase
$$\frac{\partial \varepsilon_p}{\partial t} + \nabla \cdot \left(\varepsilon_p \vec{u}_p\right) = 0$$
 (1)

- 129 Gas phase $\frac{\partial \varepsilon_g}{\partial t} + \nabla \cdot \left(\varepsilon_g \vec{u}_g\right) = 0$ (2)
- 130 Momentum equations:

131 Particle phase
$$\frac{\partial \left(\varepsilon_{p}\rho_{p}\vec{u}_{p}\right)}{\partial t} + \nabla \cdot \left(\varepsilon_{p}\rho_{p}\vec{u}_{p}\vec{u}_{p}\right) = \vec{F}_{p,net}$$
(3)

132

133 Gas phase
$$\frac{\partial \left(\varepsilon_{g} \rho_{g} \vec{u}_{g}\right)}{\partial t} + \nabla \cdot \left(\varepsilon_{g} \rho_{g} \vec{u}_{g} \vec{u}_{g}\right) = \vec{F}_{g,net}$$
(4)

134 Where ε represents the volume fraction ($\varepsilon_p + \varepsilon_g = 1$), *u* is the flow velocity, and \vec{F} is the

135 net force. The subscripts g and p indicate gas and particle phase, respectively.

136 Particle-phase force component:

137
$$\vec{F}_{p,net} = -\varepsilon_p \nabla p + \nabla \cdot \overline{\tau_p} + \varepsilon_p \rho_p \vec{g} + \sum_{p=1}^n K_{pg} (\vec{u}_p - \vec{u}_g) + \vec{F}_p$$
(5)

138 Gas-phase force component:

139
$$\vec{F}_{g,net} = -\varepsilon_g \nabla p + \nabla \cdot \overline{\tau}_g + \varepsilon_g \rho_g \vec{g} + \sum_{g=1}^n K_{gp} (\vec{u}_g - \vec{u}_p) + \vec{F}_g$$
(6)

140 Where *p* is the pressure shared by all phases, $\overline{\tau}$ is the phase stress-strain tensor, and *K* is 141 the momentum exchange coefficient.

142 Gas-particle momentum exchange is calculated based on the Syamlal-O'Brien model

143 (Syamlal and O'Brien, 1989):

144
$$K_{pg} = K_{gp} = \frac{\varepsilon_p \rho_p f}{\tau_p}, f = \frac{C_D \operatorname{Re}_p \varepsilon_g}{24u_{r,p}^2}$$
(7)

145 Where $u_{r,p}$ is the terminal velocity correlation for the solid phase (Garside and Al-Dibouni,

147
$$u_{r,p} = 0.5(A - 0.06 \operatorname{Re}_{p} + \sqrt{(0.06 \operatorname{Re}_{p})^{2} + 0.12 \operatorname{Re}_{p}(2B - A) + A^{2}}),$$

148
$$A = \varepsilon_g^{4.14}, B = \varepsilon_g^{2.65} \ (\varepsilon_g \ge 0.85)$$
 (8)

149 The empirical Dallavalle relation is used to express drag coefficient C_{D} :

150
$$C_D = \left(0.6 \, \Im \, \frac{4.8}{\sqrt{\operatorname{Re}_p u_{r,p}}}\right)^2,$$
 (9)

151 Where Re_{p} is particle Reynolds number, defined as

152
$$\operatorname{Re}_{p} = \frac{\rho_{g} \left| \vec{u}_{p} - \vec{u}_{g} \right| d_{p}}{\mu_{g}}$$
(10)

153 Where d_p is particle diameter, and μ_g is gas viscosity.

154 **3.2. Numerical method**

Knudsen is a dimensionless parameter of rarefied gas. Because the Knudsen of the vacuum
flow (absolute pressure, 7000Pa) in the present PSMVD equipment was far lower than 1, the
flow was consistent with fluid continuum hypothesis and solved by the Navier-Stokes equation
(Shen, 2005). Simulations of a gas-solid flow in PSMVD equipment were carried out on a
CFD package (ANSYS FLUENT, USA). Two-fluid model of Eulerian-Eulerian was used to
capture gas-solid flow hydrodynamic.
In the present pseudo two-dimensional spout fluidized bed (pseudo-2D spout fluidized

162 bed), the spouted flow was simplified to a two dimensional flow as shown in Figure 2. The

width of the drying chamber was 40 mm and cavity height H 516 mm; the width of air
distribution nozzle L was 8 mm and air distributor angle was 45 °. Air and lettuce particle
were used as gas and particle phase, respectively (Table 1).

The two dimension flow field was computed with the software of ANSYS FLUENT by solving the Reynolds-Averaged Navier-Stokes equations. An implicit scheme of volume fraction, a laminar viscous model, a phase coupled simple scheme, a least squares cell based first order upwind spatial discretization, and a first order implicit transient formulation were employed. The spouted air and lettuce particulates were set as primary phase and secondary phase, respectively. The interactions between air and particulates were considered as drag and collisions of granular flow.

A structure mesh was generated by using a grid generation ANSYS ICEM. In the flow passage, the mesh contained 370,000 cells. The minimum size of cell was 0.01 mm. Comparisons of the coarser mesh model (70,000 cells), the mid-mesh model (370,000 cells) and the refined mesh model (750,000 cells) were carried out to ensure that the computational results were independent of mesh size. The failure of the coarser-mesh may be caused by bad transition elements.

179 <Figure.2>

Boundary conditions were defined as follows. The inlet was specified as velocity inlet, and the primary phase velocity is specified. The inlet spouting gas is specified as an ideal gas under the atmosphere pressure, whose properties were calculated by ideal gas state equation. The outlet was specified as vacuum pressure outlet. The gravity and volume fraction of particles were specified. The detailed numerical parameters of granular flow of lettuce

185	particles are listed in Table 1. The instantaneous time step was set 0.001 s. Numerical
186	simulations were carried out at the different spout gas velocities ($u_{spout} = 3.5$ m/s, 7 m/s, 14 m/s,
187	28 m/s, and 56 m/s respectively).
188	< Table 1>
189	4. Results and discussion
190	To investigate the elevation characteristics of the spout fluidized lettuce particles, the
191	hydrodynamics of the gas-solid spout fluidized bed with an increasing uniform inlet gas
192	velocity were simulated.
193	4.1. Validation of the model
194	In order to validate this model to obtain the minimum fluidization in the spout fluidized bed,
195	the minimum fluidization velocity was identified with the spout velocity of 3.5 m/s. The solid
196	volume fraction, the phase 2 velocity and pressure at the minimum fluidization velocity were
197	shown in Figure 3, Figure 4 and Figure 5. The lettuce particles kept the traditional fixed-bed
198	state after running for 1s when the inlet gas velocity was equal to or smaller than the
199	minimum fluidization velocity.

It was observed that the whole fluidization process in a spout fluidized bed included an initial stage and a steady stage (Figure 3, Figure 4 and Figure 5). The initial stage was an instantaneous developing process where the jet flow penetrated the bed, in which the jet appeared originally and then broke up periodically into bubbles without interference. The second stage was a steady circulation process where the particles circulated in a fixed pattern. A suspending surface of particles was formed at a height of 0.029 m from the inlet at spout velocity $u_{spout} = 3.5$ m/s. Most particles occupied the bottom and few particles were able to 207 escape from this surface; the maximum particle velocity was up to 0.1 m/s.

208 <Figure.3>

209 <Figure.4>

210 <Figure.5>

4.2 Flow pattern

With the inlet spout gas velocity increase, the hydrodynamics of the gas-solid spout fluidized bed began to change. The flow pattern in a long vacuum cavity could be considered as a single jet, flow transition, and flow coalescence based on the frame-by-frame analysis (Guo et al. 2001 and Hong et al. 2003), which was simplified as a pseudo-2D cavity in this study. The detailed description of the flow pattern in wider operation conditions was presented below. The single jet characteristic was observed at a very low fluidized velocity, such as spout gas velocity 3.5 m/s as shown in Figure 3, Figure 4 and Figure 5.

4.2.1 Flow stability

220 Figure 6 shows the static pressure at the middle point located at the initial particle surface at 221 different spout gas velocity. There was a clear unsteady initial process for about 1s, and after 222 this fluctuating stage it tended to become steady when the gas spout velocity was lower than 223 21m/s. The duration of the unsteady status increased with the increase of spout velocity, and 224 the pressure value tended to decrease and fluctuated as gas spout velocity increased. The 225 particle velocity at the same point is shown in Figure 7. The particle velocity varied sharply at 226 the initial stage, and became steady when spout velocity was lower than 21 m/s. When spout 227 velocity was up to 28 m/s, particle velocity increased and was characterized by periodical 228 fluctuation, and the fluidization presented an oscillatory nature. The above findings indicated

- that the spout velocity was an important factor in a spout fluidized bed. The whole process
- 230 could be divided into two stages: a start-up stage and a quasi-steady fluidization stage.

231 <Figure.6>

- 232 <Figure.7>
- 233 **4.2.2. Particle flow developing process**

Considering the fluctuation characteristics of particle flow when spout velocity was up to 235 28 m/s, the particle flow patterns at spout velocity $u_{spout} = 14$ m/s and 28 m/s were discussed 236 respectively to verify a key spout velocity affecting transition of the flow pattern, i.e. critical 237 velocity. The effect of geometry structure of 2D spout fluidized bed on particle flow pattern 238 was also evaluated.

239 Figures 8 and 9 show the instantaneous particle flow pattern during spout time of 3.0 s at 240 spout velocity of $u_{spout} = 14$ m/s. The instantaneous particle flow patterns at the initial time of 241 1.0 s were obtained. It was noted that compared with spout velocity 3.5 m/s, the jet appeared 242 and developed with more and stronger bubbles, causing more motion of the particles in the 243 annulus region. Although most particles were elevated by spout gas flow, a small portion of 244 particles was found near the wall of the air distributor. The occupancy of particles occurred 245 near the bottom of the air distributor, and formed a spherical region. During the spout time 246 from 1.0 s to 3.0 s with a 0.5 s interval, the distribution of particle velocity and maximum 247 suspending height were shown in Figure 9. When the particle flow pattern was in a steady 248 status, a suspending surface of particles was formed at a height of 0.045 m above the nozzle. 249 Most high particle velocities were located at the upper region of air distributor with a 250 spherical feature, which indicated that there were two particle circulation tracks in the spout fluidized bed. Few particles escape from the suspending surface and the maximum value ofparticle velocity was up to 0.26 m/s in the present study.

253 <Figure.8>

- 254 < Figure.9>
- 255 < Figure.10>
- 256 < Figure.11>

The instantaneous particle flow pattern at spout velocity $u_{spout} = 28$ m/s was obtained as 257 258 shown in Figures 10 and 11. The instantaneous flow patterns at the initial time of 1.0s 259 indicated that the jet rapidly appeared with more and stronger bubbles, penetrated the particle 260 bed, and developed with significant elevation of most particles. The particles that 261 accumulated on the wall of the air distributor were carried to the upper region as spout jet 262 flow developed. Under this condition, the spout jet flow caused the motion of most particles 263 in the annulus and axial regions. When spout velocity was up to 28 m/s, the particle flow pattern fluctuated and suspending height of particles was formed in a height range from 0.15 264 265 m to 0.25 m above the nozzle where the particle flow tended to be unsteady (Figure 11). 266 Compared with particle flow at spout velocity of $u_{spout} = 14$ m/s, the maximum value of 267 particle velocity was up to 1.63 m/s, and location of the higher velocity particles moved to the upper region at a height range from 0.02 m to 0.1 m. There was a narrow region with low 268 269 particle velocity, which might have been caused by main spout gas flow.

The characteristics of flow patterns at different spout velocities indicated that there was a correlation between spout gas flow velocity and particle status. There was a critical velocity in

272 which effect transition of the flow pattern occurred as the spout velocity increased.

4.3. Effect of spout velocity on particle circulation pattern

The particle circulation during drying indicates the particle mixing, and affects the heat and mass transfer between different particles in a spout fluidized bed in a microwave-assisted vacuum drying cavity. Penetration characteristics of spout gas flow and particle movement were investigated to understand the effect of spout velocity on particle circulation pattern in a pseudo-2-D spout fluidized bed.

4.3.1. Penetration of spout fluidization in a pseudo-2-D spout fluidized bed

280 In a spout fluidized bed, no matter whether the gas leaves the nozzle as bubbles, pulsating 281 jet, or permanent jet, the fact is that there exists extensive gas and solid mixing in the jet 282 region (Hong et al. 2003). The jet penetration depth is a key parameter to characterize the 283 spout gas flow, which increases with increasing jet gas velocity in the spout fluidized bed. The 284 discrepancies among various models for predicating the jet penetration depth were essentially 285 due to the different definitions of jet boundary (Musmarra, 2000). In this study, jet penetration depth was defined as the contour line of voidage as 0.8 (Gidaspow and Ettehadleh 1983). 286 287 Figure 12 shows the influence of spout gas velocity on the penetration depths and pressure drop in a 2D vacuum cavity. The penetration depth increased slowly below the spout gas 288 289 velocity of 28 m/s, and then increased rapidly until 56 m/s. There was an approximately linear 290 correlation between the jet penetration depth and gas spout velocity.

The bed pressure drop is another important parameter for characterizing the particle circulation pattern in a vacuum fluid bed dryer, defined as pressure difference (ΔP) between the inlet and outlet of solid-gas mixture in the quasi-steady stage. The bed pressure drop at different spout gas velocity is present in Figure 12. The results indicated that the pressure drop changed from negative pressure to positive pressure, when the spout gas velocity increased from 14 m/s to 21 m/s. This phenomenon suggested a significant change of particle circulation pattern that the elevated force acting on particles by the spout gas flow has overcome the gravity of particles, and particles begin to be elevated from the bottom of air distributor to the upper region of the vacuum cavity. Therefore, the velocity range from 14 m/s to 28 m/s was a critical velocity region to influence the particle circulation pattern.

301 <Figure.12>

302 **4.3.2. Particles movement**

303 Because the particle movement maintained similar features when the spout fluidized 304 process enters the quasi-steady stage (spout time is generally over 1 s), the effect of spout 305 velocity on the particle movement at spout time 3.0 s was analyzed. The distribution of 306 particle volume fraction at t = 3.0 s is shown in Figure 13. The particle volume fraction was 307 defined as the percentage of the volume the lettuce particles occupied in the drying cavity. 308 When the spout velocity was 7 m/s, most particles accumulated near the air distributor, and 309 only a small amount of particles moved up. As the spout velocity increased to 14 m/s, most 310 particles participated in an upside movement, and formed a ball like distribution, though the 311 particles were still around the air distributor. When the velocity was increased to 21 m/s and 312 28 m/s, the particles' movements expanded to a distance of about 0.2 m from the air 313 distributor and most particles were located in this region. Finally, when the velocity was 56 314 m/s, some particles moved up to the height of 0.5 m, and most of them were located 0.2 m above the jet nozzle. The results indicated that, at a constant amount of particles, particle 315 316 distribution was controlled by the spout gas velocity. This information might be helpful to

317 improve the microwave-assisted spout fluidized bed heating to obtain a uniform particle318 temperature.

319 < Figure.13>

320 Figure 14 shows the particle flow patterns under different spout velocities at t = 3.0 s and 321 the same amount of particles. The particle velocity increased from 0.1 m/s to 3 m/s with the 322 increased spout velocity. Although the velocity distribution in the upper region above the particle suspending surface was observed at low spout velocity ($u_{spout} = 7 \text{ m/s}$, 14 m/s), the 323 324 particles' movements were mainly maintained below the particle suspending surface, and few 325 particles were existed in the region above the particle suspending surface according to the 326 distribution of the particle volume fraction. With the increase in spout velocity and 327 development of a spout jet flow, particles accumulated on the wall of the air distributor were 328 carried to the upper region. When spout velocity was increased to 56 m/s, the particle 329 movement was more spacious and significantly different from that of the transitional fluidized 330 bed. Below this spout velocity, most particles moved up instantaneously, and some of them 331 moved out of the vacuum cavity, while no apparent particle suspending surface was observed. 332 Although there was a higher particle velocity in the region with a height range from bottom to 333 0.2 m, the effect of these particles was slight because there were few particles in this region 334 according to the distribution of particle volume fraction.

335 < Figure.14>

The results showed that the particle circulation pattern was different under different gas spout velocities. In a spout fluidized bed in a microwave-assisted vacuum dryer, the particle circulation pattern was one of the important factors affecting the heating uniformity. A spacious particle distribution was beneficial to obtain uniform microwave energy, andimprove convective heat transfer under fluidization.

341 **5 Conclusions**

In the present study, the TFM method was verified to successfully obtain the gas-particle flow in this pseudo-2-D spout fluidized bed in a vacuum drying cavity. The dynamic characteristics of spout fluidized bed and the effect of spout elevation on particle movement at different operating conditions were obtained based on simulation results.

The model simulation illustrated that the spout fluidized process included isolated, merged and transitional jets when the spout gas velocity was increased. The isolated jet turned into the merged jet via the transitional jet. The fluidization at a certain velocity could be divided into two stages: a start-up stage and a quasi-steady fluidization stage. The spout velocity was an important factor controlling particle status in the spout fluidized bed. There was a critical velocity range from 14 m/s to 28 m/s where the particle flow pattern was changed from steady flow to unsteady flow.

There was an approximately linear correlation between the jet penetration depth and gas spout velocity. The pressure drop tended to convert from negative pressure to positive pressure as spout velocity increased up to the critical velocity. In the quasi-steady stage, particle circulation pattern significantly changed with increased spout velocity, and particles began to be elevated from the bottom of air distributor to the upper region of the vacuum drying cavity.

359

360 Acknowledgements

361 The authors thank the China 863 HI-TECH Research and Development Program	(No
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- 362 2011AA100802), China Postdoctoral Program, and Natural Science Foundation of Jiangsu
- 363 Province (Grant No: BK20130150) for financial supports. The authors also thank Mr Paul
- 364 Dubois, from Curtin University, for his professional English editing.

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457 Table 1

458 Physical and numerical parameters of the particle and gas used in the experiment

Particle phase		Gas phase				
Particle	Lettuce	Fluid	Air			
Diameter, d _p (mm)	0.005	Inlet gas density, ρ_g	1.205			
		(kg/m^3)				
Density, $\rho_g(kg/m^3)$	1387	Viscosity, $\mu_{\rm g}$ (Pa/s)	18.1×10^{-6}			
Volume fraction	0.003	Cavity height, H	516			
		(mm)				
Granular viscosity(Pa/s)	Syamlal-Obrien drag model	Vacuum pressure(Pa)	7000			
Granular bulk	Lun-et-al model	Air distributor angle,	45			
viscosity(Pa/s)		(°)				
Frictional Viscosity(Pa/s)	Schaeffer, Johnson-et-al	Nozzle width, L(mm)	8			
	model					
Granular	algebraic model	Grid number	370,000			
Temperature (m^2/s^2)						
Solid pressure(Pa)	Lun-et-al model	Grid type	Structure			
Radial Distribution	Lun-et-al model	Time step, Δt (s)	1×10^{-3}			
Elasticity Modulus(Pa)	Lun-et-al model					
Packing limit	0.63					

459

461	Figure captions
462	Figure.1 Schematic diagram of a pulsed spouted microwave-vacuum drying system
463	Figure.2 Computational models of air distribution structure
464	Figure.3 Particle volume fraction at the minimum spout fluidization velocity (u_{spout} =
465	3.5m/s, t = 0.2s-1.0s)
466	Figure.4 Pressure at the minimum spout fluidization velocity ($u_{spout} = 3.5 \text{ m/s}$, t=0.2s-1.0s)
467	Figure.5 Particle velocity ($u_{spout} = 3.5 \text{ m/s}$, t =1.0s-3.0s)
468	Figure.6 Fluctuation of static pressure at different spout gas velocity
469	Figure.7 Fluctuation of particle velocity at different spout gas velocity
470	Figure.8 Particle volume fraction at the critical spout fluidization velocity at initial stage
471	$(u_{spout} = 14 \text{m/s}, t = 0.1 \text{s} - 1.0 \text{s})$
472	Figure.9 Particle velocity distribution at different spout time ($u_{spout} = 14$ m/s)
473	Figure.10 Particle volume fraction distribution during spout time from 0.1s-1.0s ($u_{spout} =$
474	28m/s, t = 0.1s-1.0s)
475	Figure.11 Particle velocity ($u_{spout} = 28m/s$) of separation surface position
476	Figure.12 Penetration depth and pressure drop for a 2D vacuum cavity
477	Figure.13 Contour plot of the particle volume fraction in pseudo-2D spout fluidized bed
478	at different spout velocity at $t = 3.0s$
479	Figure.14 Contour plot of the particle velocity in pseudo-2D spout fluidized bed at
480	different spout velocity at steady stage ($t = 3.0s$)
481	
482	



484 Figure.1 Schematic diagram of a laboratory pulsed spouted microwave-vacuum
 485 drying system

1 feeding ball valve, 2 plate valve, 3 microwave heating cavity, 4 magnetron, 5
circulating water unit, 6 drying chamber, 7 and 13pressure gauge, 8 solid–gas separator,
9 vapor condenser, 10 vacuum pump unit, 11 gas flow electromagnetic valve, 12 gas
flow adjustable valve, 14 gas source, 15 control panel, 16 water load pipe, 17 gas
distributer, 18 spout pipe, 19 silicon rubber stopper, 20 sample, 21 drying chamber, 22
fixed unit, 23 fiber optic temperature sensor





Figure.2 Computational models of air distribution structure















Figure. 6 Fluctuation of static pressure at different spout gas velocity





Figure. 7 Fluctuation of particle velocity at different spout gas velocity





Figure.9 Particle velocity distribution at different spout time (u_{spout} =14m/s)













Figure. 12 Penetration depth and Pressure drop for a 2D vacuum cavity





Figure. 14 Contour plot of the particle velocity in pseudo-2D spout fluidized bed at different spout velocity at steady stage (t=3.0s)