# STUDY OF A PARABOLIC PROBLEM IN A CONICAL DOMAIN 

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#### Abstract

In this paper we consider the heat equation with Dirichlet boundary conditions in a conical domain. We look for a sufficient condition on the lateral surface of the cone in order to have the optimal regularity of the solution in an anisotropic Sobolev space when the right hand side of the equation is in a Lebesgue space.


## 1. Intoduction

Let $\varphi$ be a locally Lipschitz function $\varphi:(0, T] \rightarrow \mathbb{R}^{+}$where $T>0$, such that

$$
\begin{aligned}
\varphi(0) & =0 \\
\varphi(t) & >0, t \in(0, T]
\end{aligned}
$$

and $\Omega \subset \mathbb{R}^{3}$ be the open subset of conical type :

$$
\Omega=\left\{(t, x, y) \in \mathbb{R}^{3}: 0<t<T, 0 \leq \sqrt{x^{2}+y^{2}}<\varphi(t)\right\} .
$$

Consider in $\Omega$ the parabolic problem

$$
\left\{\begin{array}{c}
\partial_{t} u-\partial_{x}^{2} u-\partial_{y}^{2} u=f \in L^{2}(\Omega),  \tag{1.1}\\
u \mid \partial \Omega \backslash D(T, \varphi(T))=0,
\end{array}\right.
$$

where $D(s, r)$ denotes the disc of radius $r$ centred at $(s, 0,0)$, and $L^{2}(\Omega)$ is the usual Lebesgue space on $\Omega$. We look for the solution $u$ in the anisotropic Sobolev space

$$
H^{1,2}(\Omega)=\left\{u \in H^{1}(\Omega): \partial_{x}^{2} u \in L^{2}(\Omega), \partial_{x y} u \in L^{2}(\Omega), \partial_{y}^{2} u \in L^{2}(\Omega)\right\},
$$

here, $H^{1}(\Omega)$ stands for the Sobolev space defined by

$$
H^{1}(\Omega)=\left\{u \in L^{2}(\Omega): \partial_{t} u \in L^{2}(\Omega), \partial_{x} u \in L^{2}(\Omega), \partial_{y} u \in L^{2}(\Omega)\right\} .
$$

The space $H^{1,2}(\Omega)$ is equipped with the natural norm, that is

$$
\|u\|_{H^{1,2}}=\sqrt{\|u\|_{H^{1}}^{2}+\left\|\partial_{x}^{2} u\right\|_{L^{2}}^{2}+\left\|\partial_{x y} u\right\|_{L^{2}}^{2}+\left\|\partial_{y}^{2} u\right\|_{L^{2}}^{2}} .
$$

[^0]The belonging of the solution $u$ to $H^{1,2}(\Omega)$ depends on the function $\varphi$. Our aim is to find a sufficient condition on $\varphi$, as weak as possible in order to obtain a solution $u \in H^{1,2}(\Omega)$. Our main result is

Theorem 1. Assume that $\varphi(0)=0$ and

$$
\lim _{t \rightarrow 0} \varphi(t) \varphi^{\prime}(t)=0
$$

or

$$
\varphi^{\prime}(t) \geq 0 \text { a.e. in a neighborhood of } 0 .
$$

Then, for all $f \in L^{2}(\Omega)$, Problem (1) admits a (unique) solution $u \in$ $H^{1,2}(\Omega)$.

For example, if $\varphi(t)=a t^{\alpha}$, Problem (1) admits a unique solution for any positive constants $a$ and $\alpha$. The same result holds true if $\varphi(t)=t^{\alpha} \ln t$, with $\alpha>\frac{1}{2}$.

Observe that the main difficulty is due to the condition $\varphi(0)=0$ (instead of $\varphi(0)>0)$ which gives a conical point at $(0,0,0)$ and then, it does not allow to transform the cone $\Omega$ into a usual cylindrical domain. This type of problems has been studied by Sadallah [14] in one space dimension for the parabolic operator $\partial_{t} u+(-1)^{m} \partial_{x}^{2 m} u$ with $m \geq 1$.

Alkhutov [1] has treated, in some weighted Sobolev $L^{p}$-spaces, the heat equation in bounded and unbounded domains of paraboloid type. He has considered in [2] the case of the heat equation in a ball; this case corresponds here to $\varphi(t)=\sqrt{t(2 R-t)}$ in the neighborhood of 0 (for a ball of radius $R$ centred at $(R, 0,0))$. It is clear that this function satisfies the hypothesis of Theorem 1. In [15] Sadallah has obtained the optimal regularity of the solution for any disc $\Omega=\left\{(t, x) \in \mathbb{R}^{2}: 0 \leq \sqrt{t^{2}+x^{2}}<R\right\}$.

In the case of one space variable, the heat equation in non Hilbretian spaces has been considered in some works, for instance in Labbas et al. [10] and [11]. Berroug et al. [3] have treated the same equation with a singular domain in Hölder spaces, whereas Kheloufi et al. [7] have studied the case when the domain is cylindrical, not with respect to the time variable, but with respect to one of space variables.

Some authors have considered the singularities which appear in the solutions when the domain is non cylindrical as Kozlov and Maz'ya in [8] and [9]. We can find in Nazarov [13] some results about the solution of Neumann problem in a conical domains. In Degtyarev [5] a more general parabolic equation has been studied in domains with a conical point.

The method used here is to approach the domain $\Omega$ for $T$ small enough by a sequence of subsomains $\left(\Omega_{n}\right)_{n \in \mathbb{N}}$ in which we can solve Problem (1). More precisely, when $T$ is any positive real number, we divide $\Omega$ into two
parts : $\Omega_{T^{\prime}}$, with $T^{\prime}$ small enough,

$$
\Omega_{T^{\prime}}=\left\{(t, x, y) \in \Omega: 0<t<T^{\prime}\right\}
$$

and

$$
\Omega_{T^{\prime} T}=\left\{(t, x, y) \in \Omega: T^{\prime}<t<T\right\} .
$$

So, we obtain two solutions $u_{1} \in H^{1,2}\left(\Omega_{T^{\prime}}\right)$ in $\Omega_{T^{\prime}}$ and $u_{2} \in H^{1,2}\left(\Omega_{T^{\prime} T}\right)$ in $\Omega_{T^{\prime} T}$. Finally, we prove that the function $u$ defined by

$$
u:=\left\{\begin{array}{c}
u_{1} \text { in } \Omega_{T^{\prime}} \\
u_{2} \text { in } \Omega_{T^{\prime} T}
\end{array}\right.
$$

is the solution of Problem (1) and has the optimal regularity, that is $u \in$ $H^{1,2}(\Omega)$.

It is not difficult to prove the uniqueness of the solution. Indeed, if we consider the inner product $\left(\partial_{t} u-\partial_{x}^{2} u-\partial_{y}^{2} u, u\right)_{L^{2}}$ with $\partial_{t} u-\partial_{x}^{2} u-\partial_{y}^{2} u=0$ and take into account the boundary conditions, we obtain

$$
\begin{aligned}
0 & =\left(\partial_{t} u-\partial_{x}^{2} u-\partial_{y}^{2} u, u\right)_{L^{2}} \\
& =\frac{1}{2} \int_{D(T, \varphi(T))} u^{2} d x d y+\frac{1}{2} \int_{\Omega}|\nabla u|^{2} d t d x d y
\end{aligned}
$$

where $|\nabla u|^{2}=\left(\partial_{x} u\right)^{2}+\left(\partial_{y} u\right)^{2}$. Then $|\nabla u|^{2}=0$. This leads to $\partial_{x} u=\partial_{y} u=0$ and therefore, $\partial_{x}^{2} u=\partial_{y}^{2} u=0$. From the equation $\partial_{t} u-\partial_{x}^{2} u-\partial_{y}^{2} u=0$ we deduce that $\partial_{t} u=0$. Accordingly, the solution $u$ is constant, but it is null on one part of the boundary. So, $u=0$. This proves the uniqueness of the solution of Problem (1). This is why we will be interested in the sequel only by the question of the existence of the solution when $f \in L^{2}(\Omega)$.

Our work is motivated by the interest of researchers for many mathematical questions related to non-regular domains. In fact, some important applied problems reduce to the study of boundary-value problems for partial differential equations (Laplace equation, heat equation, Fokker-Planck equation, Chapman-Kolmogorov equation...) in domains with non-regular points on the boundary.

The plan of the paper is : In Section 2 we give a change of variables which transforms a subdomain of $\Omega$ into a cylindrical domain, so we confine ourselves to the neighborhood of the origin $(0,0,0)$. Section 3 is devoted to the proof of an estimate in order to get a subsequence of functions converging to the solution of Problem (1) in a subdomain of $\Omega$. Finally, in Section 4, we complete the proof of Theorom 1.

## 2. Change of variables

Let $\varepsilon>0$ be a real which we will choose small enough. The continuity of $\varphi$ at 0 proves the existence of a real number $T^{\prime}<T$ such that:

$$
\begin{equation*}
\forall t \in\left(0, T^{\prime}\right),|\varphi(t)| \leq \varepsilon \tag{2.1}
\end{equation*}
$$

Consider a decreasing sequence $\left(t_{n}\right)_{n \in \mathbb{N}}$ of real numbers such that $0<$ $t_{n}<T^{\prime}$ for all $n \in \mathbb{N}$ and $\lim _{t \rightarrow 0^{+}} t_{n}=0$. We define the sequence of subdomains $\left(\Omega_{n}\right)_{n}$ of $\Omega_{T^{\prime}}$ by

$$
\Omega_{n}=\left\{(t, x, y) \in \Omega: t_{n}<t<T^{\prime}\right\}
$$

The solution $u$ of Problem (1) will be approached by the solutions $u_{n}$ of the problems

$$
\left\{\begin{array}{c}
\partial_{t} u_{n}-\partial_{x}^{2} u_{n}-\partial_{y}^{2} u_{n}=f_{n} \in L^{2}\left(\Omega_{n}\right)  \tag{2.2}\\
u_{n \mid \partial \Omega_{n} \backslash D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}=0
\end{array}\right.
$$

where $f_{n}=f_{\mid \Omega_{n}}$.
Then, we perform the change of variables:

$$
\begin{aligned}
\Omega_{n} & \longrightarrow\left(t_{n}, T^{\prime}\right) \times B(0,1) \\
(t, x, y) & \longmapsto\left(t, \frac{x}{\varphi(t)}, \frac{y}{\varphi(t)}\right)=\left(t, x^{\prime}, y^{\prime}\right)
\end{aligned}
$$

where $B(0,1)=\left\{(x, y) \in \mathbb{R}^{2}: x^{2}+y^{2}<1\right\}$. Problem (3) is transformed into the problem

$$
\left\{\begin{array}{c}
\partial_{t} v_{n}-\frac{1}{\varphi^{2}(t)} \Delta v_{n}-\frac{\varphi^{\prime}(t)}{\varphi(t)}\left(x^{\prime} \partial_{x^{\prime}} v_{n}+y^{\prime} \partial_{y^{\prime}} v_{n}\right)  \tag{2.3}\\
=g_{n} \in L^{2}\left(\left(t_{n}, T^{\prime}\right) \times B(0,1)\right), \\
v_{n \mid\left\{t_{n}\right\} \times B(0,1)}=0 \\
v_{n \mid\left(t_{n}, T^{\prime}\right) \times \partial B(0,1)}=0,
\end{array}\right.
$$

here $f_{n}(t, x, y)=g_{n}\left(t, x^{\prime}, y^{\prime}\right), u_{n}(t, x, y)=v_{n}\left(t, x^{\prime}, y^{\prime}\right)$ and $\Delta v_{n}=\partial_{x^{\prime}}^{2} v_{n}+$ $\partial_{y^{\prime}}^{2} v_{n}$. It is easy to see that the operator

$$
\frac{\varphi^{\prime}(t)}{\varphi(t)}\left(x^{\prime} \partial_{x^{\prime}}+y^{\prime} \partial_{y^{\prime}}\right): H^{1,2}\left(\left(t_{n}, T^{\prime}\right) \times B(0,1)\right) \rightarrow L^{2}\left(\left(t_{n}, T^{\prime}\right) \times B(0,1)\right)
$$

is compact and the problem

$$
\left\{\begin{array}{c}
\partial_{t} v_{n}-\frac{1}{\varphi^{2}(t)} \Delta v_{n}=g_{n} \in L^{2}\left(\left(t_{n}, T^{\prime}\right) \times B(0,1)\right), \\
v_{n \mid\left\{t_{n}\right\} \times B(0,1)}=0 \\
v_{n \mid\left(t_{n}, T^{\prime}\right) \times \partial B(0,1)}=0,
\end{array}\right.
$$

admits a unique solution $v_{n} \in H^{1,2}$ in the cylindrical domain $\left(t_{n}, T^{\prime}\right) \times$ $B(0,1)$. This proves that Problem (4) has a unique solution $v_{n} \in H^{1,2}\left(\left(t_{n}, T^{\prime}\right) \times B(0,1)\right)$. The previous change of variables shows that Problem (3) has also a unique solution $u_{n} \in H^{1,2}\left(\Omega_{n}\right)$ for all $n \in \mathbb{N}$. The goal
of the following section is to establish an estimate concerning the sequence $\left(u_{n}\right)$ which allows us to extract a subsequence converging to the solution of Problem (1).

## 3. An estimate

Consider the sequence $\left(u_{n}\right)$ and look for a constant $C>0$ independent of $n$ satisfying the estimate

$$
\begin{equation*}
\left\|u_{n}\right\|_{H^{1,2}\left(\Omega_{n}\right)} \leq C\left\|f_{n}\right\|_{L^{2}\left(\Omega_{n}\right)} \tag{3.1}
\end{equation*}
$$

For this purpose we will estimate $\left\|\partial_{t} u_{n}-\partial_{x}^{2} u_{n}-\partial_{y}^{2} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}$.
Lemma 2. There exists a constant $C>0$ independent of $n$ such that for almost every $t \in\left(0, T^{\prime}\right)$

$$
\begin{aligned}
\left\|u_{n}\right\|_{L^{2}(D(t, \varphi(t)))} & \leq C \varphi^{2}(t)\left\|\Delta u_{n}\right\|_{L^{2}(D(t, \varphi(t)))} \\
\max \left(\left\|\partial_{x} u_{n}\right\|_{L^{2}(D(t, \varphi(t)))},\left\|\partial_{y} u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}\right) & \leq C \varphi(t)\left\|\Delta u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}
\end{aligned}
$$

Proof. Let $H^{2}$ and $H_{0}^{1}$ be the usual Sobolev spaces defined, for instance, in Lions-Magenes [12]. We know that the Laplace operator $\Delta: H^{2}(D(0,1)) \cap$ $H_{0}^{1}(D(0,1)) \rightarrow L^{2}(D(0,1))$ is an isomprphism. Then, there exists a constant $C>0$ such that

$$
\begin{equation*}
\|v\|_{H^{2}(D(0,1))} \leq C\|\Delta v\|_{L^{2}(D(0,1))}, \forall v \in H^{2}(D(0,1)) \tag{3.2}
\end{equation*}
$$

Let $t_{n}<t<T^{\prime}$. The change of variables

$$
\begin{aligned}
D(0,1) & \rightarrow D(t, \varphi(t)) \\
(x, y) & \longmapsto(\varphi(t) x, \varphi(t) y)=\left(x^{\prime}, y^{\prime}\right)
\end{aligned}
$$

allows to write, thanks to (6) :

$$
\begin{aligned}
\|v\|_{L^{2}(D(0,1))} & =\frac{1}{\varphi(t)}\left\|u_{n}\right\|_{L^{2}(D(t, \varphi(t))} \\
& \leq C\|\Delta v\|_{L^{2}(D(0,1))} \\
& =C \varphi(t)\left\|\Delta u_{n}\right\|_{L^{2}(D(t, \varphi(t))}
\end{aligned}
$$

with the notation $v(x, y)=u_{n}\left(x^{\prime}, y^{\prime}\right)$. Notice that $u_{n} \in H^{2}(D(t, \varphi(t))$ for almost every $t \in\left(t_{n}, T^{\prime}\right)$. Hence

$$
\left\|u_{n}\right\|_{L^{2}(D(t, \varphi(t))} \leq C \varphi^{2}(t)\left\|\Delta u_{n}\right\|_{L^{2}(D(t, \varphi(t))}
$$

On the other hand, we have

$$
\begin{aligned}
\left\|\partial_{x^{\prime}} u_{n}\right\|_{L^{2}(D(t, \varphi(t)))} & =\left\|\partial_{x} v\right\|_{L^{2}(D(0,1))} \\
& \leq C\|\Delta v\|_{L^{2}(D(0,1))}
\end{aligned}
$$

$$
=C \varphi(t)\left\|\Delta u_{n}\right\|_{L^{2}(D(t, \varphi(t))}
$$

The same result is true for $\left\|\partial_{y^{\prime}} u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}$.
The following lemma (see Theorem 2.1, Lions-Magenes [12]) will justify some calculations in this section.

Lemma 3. The space

$$
\left\{u \in H^{2}((0, T) \times D(0,1)): u_{\mid\{0\} \times D(0,1)}=0, u_{\mid\left(0, T^{\prime}\right) \times \partial D(0,1)}=0\right\}
$$

is dense in the space

$$
\left\{u \in H^{1,2}((0, T) \times D(0,1)): u_{\mid\{0\} \times D(0,1)}=0, u_{\mid\left(0, T^{\prime}\right) \times \partial D(0,1)}=0\right\}
$$

Now, consider the solution $u_{n} \in H^{1,2}\left(\Omega_{n}\right)$ of Problem (3) and let $\Delta u_{n}=$ $\partial_{x}^{2} u_{n}+\partial_{y}^{2} u_{n}$. Expanding the inner product $\left\|f_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}=\left(\partial_{t} u_{n}-\Delta u_{n}, \partial_{t} u_{n}-\right.$ $\left.\Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)}$ we obtain

$$
\begin{equation*}
\left\|f_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}=\left\|\partial_{t} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}+\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}-2\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)} \tag{3.3}
\end{equation*}
$$

We deduce the following result from Lemma 2 and Grisvard-Ioss [6] (see Theorem 2.2).

Lemma 4. There exists a constant $C>0$ independent of $n$ such that

$$
\begin{equation*}
\left\|\partial_{x y} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}+\left\|\partial_{x}^{2} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}+\left\|\partial_{y}^{2} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} \leq C\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} \tag{3.4}
\end{equation*}
$$

We have to estimate the term $\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)}$. For this end, we need to prove the result

Proposition 5. One has

$$
\begin{aligned}
& -2\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)} \\
& =\int_{0}^{2 \pi} \int_{t_{n}}^{T^{\prime}}\left|\nabla u_{n}\right|^{2}(t, \varphi(t) \cos \theta, \varphi(t) \sin \theta) \varphi(t) \varphi^{\prime}(t) d t d \theta \\
& +\int_{D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y
\end{aligned}
$$

Proof. To establish this relationship we perform the following parametrization of $\Gamma_{1}$ :

$$
\begin{aligned}
\left(t_{n}, T^{\prime}\right) \times(0,2 \pi) & \rightarrow \Gamma_{1} \\
(t, \theta) & \mapsto(t, \varphi(t) \cos \theta, \varphi(t) \sin \theta)=(t, x, y)
\end{aligned}
$$

and we denote by $\nu=\frac{1}{\sqrt{1+\varphi^{\prime 2}(t)}}\left(-\varphi^{\prime}(t), \cos \theta, \sin \theta\right)=\left(\nu_{t}, \nu_{x}, \nu_{y}\right)$ the outward unit normal vector to the part $\Gamma_{1}$ of $\partial \Omega_{n}$ defined by

$$
\Gamma_{1}=\left\{(t, x, y): \sqrt{x^{2}+y^{2}}=\varphi(t)\right\}
$$

The other part of $\partial \Omega_{n}$ will be denoted by $\Gamma_{T^{\prime}}$, i.e., $\Gamma_{T^{\prime}}=D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)$. We have

$$
\begin{aligned}
\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)}= & \int_{\Omega_{n}} \partial_{t} u_{n} \cdot \Delta u_{n} d t d x d y \\
= & \int_{\partial \Omega_{n}} \partial_{t} u_{n} \cdot\left(\nu_{x} \partial_{x} u_{n}+\nu_{y} \partial_{y} u_{n}\right) d \sigma \\
& -\frac{1}{2} \int_{\Omega_{n}} \partial_{t}\left(\left(\partial_{x} u_{n}\right)^{2}+\left(\partial_{y} u_{n}\right)^{2}\right) d t d x d y \\
= & \int_{\Gamma_{1}} \partial_{t} u_{n} \cdot\left(\cos \theta \cdot \partial_{x} u_{n}+\sin \theta \cdot \partial_{y} u_{n}\right) \frac{1}{\sqrt{1+\varphi^{\prime 2}(t)}} d \sigma \\
& +\frac{1}{2} \int_{\Gamma_{1}}\left|\nabla u_{n}\right|^{2} \frac{\varphi^{\prime}(t)}{\sqrt{1+\varphi^{\prime 2}(t)}} d \sigma-\frac{1}{2} \int_{\Gamma_{T^{\prime}}}\left|\nabla u_{n}\right|^{2} d x d y
\end{aligned}
$$

The Dirichlet boundary condition on $\Gamma_{1}$ leads to

$$
\begin{aligned}
\partial_{t} u_{n} & =-\varphi^{\prime}(t)\left(\cos \theta \cdot \partial_{x} u_{n}+\sin \theta \cdot \partial_{y} u_{n}\right) \\
\sin \theta \cdot \partial_{x} u_{n} & =\cos \theta \cdot \partial_{y} u_{n}
\end{aligned}
$$

Taking into account these relationships we deduce

$$
\begin{aligned}
\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)}= & -\int_{\Gamma_{1}}\left(\cos \theta \cdot \partial_{x} u_{n}+\sin \theta \cdot \partial_{y} u_{n}\right)^{2} \frac{\varphi^{\prime}(t)}{\sqrt{1+\varphi^{\prime 2}(t)}} d \sigma \\
& +\frac{1}{2} \int_{\Gamma_{1}}\left|\nabla u_{n}\right|^{2} \frac{\varphi^{\prime}(t)}{\sqrt{1+\varphi^{\prime 2}(t)}} d \sigma \\
& -\frac{1}{2} \int_{\Gamma_{T^{\prime}}}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y \\
= & -\int_{0}^{2 \pi} \int_{t_{n}}^{T^{\prime}}\left(\cos \theta \cdot \partial_{x} u_{n}+\sin \theta \cdot \partial_{y} u_{n}\right)^{2} \varphi(t) \varphi^{\prime}(t) d t d \theta \\
& +\frac{1}{2} \int_{0}^{2 \pi} \int_{t_{n}}^{T^{\prime}}\left|\nabla u_{n}\right|^{2} \varphi(t) \varphi^{\prime}(t) d t d \theta \\
& -\frac{1}{2} \int_{D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y \\
= & -\int_{0}^{2 \pi} \int_{t_{n}}^{T^{\prime}}\left|\nabla u_{n}\right|^{2} \varphi(t) \varphi^{\prime}(t) d t d \theta \\
& +\frac{1}{2} \int_{0}^{2 \pi} \int_{t_{n}}^{T^{\prime}}\left|\nabla u_{n}\right|^{2} \varphi(t) \varphi^{\prime}(t) d t d \theta \\
& -\frac{1}{2} \int_{D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y
\end{aligned}
$$

$$
\begin{aligned}
= & -\frac{1}{2} \int_{0}^{2 \pi} \int_{t_{n}}^{T^{\prime}}\left|\nabla u_{n}\right|^{2} \varphi(t) \varphi^{\prime}(t) d t d \theta \\
& -\frac{1}{2} \int_{D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y
\end{aligned}
$$

This ends the proof of the proposition.
Remark 6. Observe that the integral $\int_{D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y$ which appears in Proposition 5 is non negative. This is a good sign for our estimate because we can deduce immediately

$$
\begin{aligned}
\left\|f_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} \geq & \left\|\partial_{t} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}+\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} \\
& +\int_{0}^{2 \pi} \int_{t_{n}}^{T^{\prime}}\left|\nabla u_{n}\right|^{2}(t, \varphi(t) \cos \theta, \varphi(t) \sin \theta) \varphi(t) \varphi^{\prime}(t) d t d \theta
\end{aligned}
$$

So, in the sequel, we will attach no importance to this integral. On the other hand, if $\varphi$ is an increasing function in the interval $\left(t_{n}, T^{\prime}\right)$, then

$$
\int_{0}^{2 \pi} \int_{t_{n}}^{T^{\prime}}\left|\nabla u_{n}\right|^{2}(t, \varphi(t) \cos \theta, \varphi(t) \sin \theta) \varphi(t) \varphi^{\prime}(t) d t d \theta \geq 0
$$

Consequently,

$$
\begin{equation*}
\left\|f_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} \geq\left\|\partial_{t} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}+\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} \tag{3.5}
\end{equation*}
$$

But, thanks to Lemma 2

$$
\begin{aligned}
\int_{t_{n}}^{T^{\prime}}\left\|u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}^{2} d t & \leq C^{2} \int_{t_{n}}^{T^{\prime}} \varphi^{4}(t)\left\|\Delta u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}^{2} d t \\
\int_{t_{n}}^{T^{\prime}}\left\|\partial_{x} u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}^{2} d t & \leq C^{2} \int_{t_{n}}^{T^{\prime}} \varphi^{2}(t)\left\|\Delta u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}^{2} d t \\
\int_{t_{n}}^{T^{\prime}}\left\|\partial_{y} u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}^{2} d t & \leq C^{2} \int_{t_{n}}^{T^{\prime}} \varphi^{2}(t)\left\|\Delta u_{n}\right\|_{L^{2}(D(t, \varphi(t)))}^{2} d t
\end{aligned}
$$

Since $\varphi$ is bounded on $(0, T)$, there exists a constant $C^{\prime}>0$ such that

$$
\max \left(\left\|u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2},\left\|\partial_{x} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2},\left\|\partial_{y} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}\right) \leq C^{\prime}\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}
$$

Taking into account (8) and (9), this proves (5). So, it remains to establish (5) under the hypothesis $\lim _{t \rightarrow 0^{+}} \varphi(t) \varphi^{\prime}(t)=0$. For this purpose, we need the following proposition

Proposition 7. One has

$$
-2\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)}=2 \int_{\Omega_{n}} \frac{\varphi^{\prime}(t)}{\varphi(t)}\left(x \partial_{x} u_{n}+y \partial u_{n}\right) \Delta u_{n} d t d x d y
$$

$$
+\int_{D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y
$$

Proof. For $t_{n}<t<T^{\prime}$, denote by $D_{t}$ the disc $D(t, \varphi(t))$ and consider the inner product $\left(\Delta u_{n}, x \partial_{x} u_{n}+y \partial u_{n}\right)_{L^{2}\left(D_{t}\right)}$. We have

$$
\begin{aligned}
\left(\Delta u_{n}, x \partial_{x} u_{n}+y \partial_{y} u_{n}\right)_{L^{2}\left(D_{t}\right)}= & \frac{1}{2} \int_{D_{t}}\left(x \partial_{x}\left(\partial_{x} u_{n}\right)^{2}+y \partial_{y}\left(\partial_{y} u_{n}\right)^{2}\right) d x d y \\
& +\int_{\partial D_{t}}\left(x \nu_{y}+y \nu_{x}\right) \partial_{x} u_{n} \partial_{y} u_{n} d \sigma \\
& -\int_{D_{t}}\left(x \partial_{y} u_{n} \partial_{x y} u_{n}+y \partial_{x} u_{n} \partial_{x y} u_{n}\right) d x d y
\end{aligned}
$$

Then

$$
\begin{aligned}
\left(\Delta u_{n}, x \partial_{x} u_{n}+y \partial_{y} u_{n}\right)_{L^{2}\left(D_{t}\right)}= & \frac{1}{2} \int_{\partial D_{t}}\left(x \nu_{x}\left(\partial_{x} u_{n}\right)^{2}+y \nu_{y}\left(\partial_{y} u_{n}\right)^{2}\right) d \sigma \\
& -\frac{1}{2} \int_{D_{t}}\left|\nabla u_{n}\right|^{2} d x d y \\
& +2 \int_{\partial D_{t}} \partial_{x} u_{n} \partial_{y} u_{n} \cos \theta \sin \theta d \sigma \\
& -\frac{1}{2} \int_{D_{t}}\left(x \partial_{x}\left(\partial_{y} u_{n}\right)^{2}+y \partial_{y}\left(\partial_{x} u_{n}\right)^{2}\right) d x d y
\end{aligned}
$$

The boundary condition $u(t, \varphi(t) \cos \theta, \varphi(t) \sin \theta)=0$ leads to $\sin \theta \partial_{x} u_{n}=$ $\cos \theta \partial_{y} u_{n}$. Consequently

$$
\begin{aligned}
\left(\Delta u_{n}, x \partial_{x} u_{n}+y \partial_{y} u_{n}\right)_{L^{2}\left(D_{t}\right)}= & \left.\frac{\varphi^{2}(t)}{2} \int_{0}^{2 \pi}\left(\cos \theta \cdot \partial_{x} u_{n}\right)^{2}+\left(\sin \theta \cdot \partial_{y} u_{n}\right)^{2}\right) d \theta \\
& \left.+\varphi^{2}(t) \int_{0}^{2 \pi}\left(\sin \theta \cdot \partial_{x} u_{n}\right)^{2}+\left(\cos \theta \cdot \partial_{y} u_{n}\right)^{2}\right) d \theta \\
& -\frac{1}{2} \int_{D_{t}}\left|\nabla u_{n}\right|^{2} d x d y \\
& \left.-\frac{\varphi^{2}(t)}{2} \int_{0}^{2 \pi}\left(\sin \theta \cdot \partial_{x} u_{n}\right)^{2}+\left(\cos \theta \cdot \partial_{y} u_{n}\right)^{2}\right) d \theta \\
& +\frac{1}{2} \int_{D_{t}}\left|\nabla u_{n}\right|^{2} d x d y
\end{aligned}
$$

So

$$
\left(\Delta u_{n}, x \partial_{x} u_{n}+y \partial_{y} u_{n}\right)_{L^{2}\left(D_{t}\right)}=\frac{\varphi^{2}(t)}{2} \int_{0}^{2 \pi}\left|\nabla u_{n}\right|^{2} d \theta
$$

and

$$
2 \int_{\Omega_{n}} \frac{\varphi^{\prime}(t)}{\varphi(t)}\left(x \partial_{x} u_{n}+y \partial_{y} u_{n}\right) \Delta u_{n} d t d x d y=\int_{t_{n}}^{T^{\prime}} \int_{0}^{2 \pi}\left|\nabla u_{n}\right|^{2} \varphi(t) \varphi^{\prime}(t) d \theta d t
$$

Finally, in virtue of Proposition 5, it follows

$$
\begin{aligned}
-2\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)}= & 2 \int_{\Omega_{n}} \frac{\varphi^{\prime}(t)}{\varphi(t)}\left(x \partial_{x} u_{n}+y \partial_{y} u_{n}\right) \Delta u_{n} d t d x d y \\
& +\int_{D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y
\end{aligned}
$$

Theorem 8. Assume that $\lim _{t \rightarrow 0} \varphi(t) \varphi^{\prime}(t)=0$ or $\varphi^{\prime}(t) \geq 0$ in a neighborhood of 0 .Then, there exists a constant $C>0$ independent of $n$ satisfying the estimate

$$
\left\|u_{n}\right\|_{H^{1,2}\left(\Omega_{n}\right)} \leq C\left\|f_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}
$$

Proof. The case when $\varphi^{\prime}(t) \geq 0$ in a neighborhood of 0 has been treated in Remark 6. Then, assume that $\lim _{t \rightarrow 0} \varphi(t) \varphi^{\prime}(t)=0$. We have

$$
\begin{align*}
\left|\int_{\Omega_{n}} \frac{\varphi^{\prime}(t)}{\varphi(t)}\left(x \partial_{x} u_{n}+y \partial_{y} u_{n}\right) \Delta u_{n} d t d x d y\right| \leq & \left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}\left\|\frac{x \cdot \varphi^{\prime}(t)}{\varphi(t)} \partial_{x} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)} \\
& +\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}\left\|\frac{y \cdot \varphi^{\prime}(t)}{\varphi(t)} \partial_{y} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)} \tag{3.6}
\end{align*}
$$

but Lemma 2 yields

$$
\begin{aligned}
\left\|\frac{x \cdot \varphi^{\prime}(t)}{\varphi(t)} \partial_{x} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} & =\int_{t_{n}}^{T^{\prime}} \varphi^{\prime 2}(t) \int_{D(t, \varphi(t))}\left(\frac{x}{\varphi(t)}\right)^{2}\left(\partial_{x} u_{n}\right)^{2} d t d x d y \\
& \leq \int_{t_{n}}^{T^{\prime}} \varphi^{\prime 2}(t) \int_{D(t, \varphi(t))}\left(\partial_{x} u_{n}\right)^{2} d t d x d y \\
& \leq C^{2} \int_{t_{n}}^{T^{\prime}}\left(\varphi(t) \varphi^{\prime}(t)\right)^{2} \int_{D(t, \varphi(t))}\left(\Delta u_{n}\right)^{2} d t d x d y
\end{aligned}
$$

The hypothesis $\lim _{t \rightarrow 0} \varphi(t) \varphi^{\prime}(t)=0$ implies the existence of $0<\alpha<\frac{1}{2}$ such that $\left|\varphi(t) \varphi^{\prime}(t)\right|<\frac{\alpha}{2 C}$ for all $t \in\left(0, T^{\prime}\right)$ since $T^{\prime}$ is chosen small enough. So

$$
\left\|\frac{x \cdot \varphi^{\prime}(t)}{\varphi(t)} \partial_{x} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} \leq \frac{\alpha^{2}}{4}\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}
$$

It is clear that we have also

$$
\left\|\frac{y \cdot \varphi^{\prime}(t)}{\varphi(t)} \partial_{y} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} \leq \frac{\alpha^{2}}{4}\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}
$$

Accordingly, Relationship (10) leads to

$$
2\left|\int_{\Omega_{n}} \frac{\varphi^{\prime}(t)}{\varphi(t)}\left(x \partial_{x} u_{n}+y \partial_{y} u_{n}\right) \Delta u_{n} d t d x d y\right| \leq 2 \alpha\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}
$$

Therefore, Proposition 7 shows that

$$
\begin{aligned}
-2\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)} \geq & -2\left|\int_{\Omega_{n}} \frac{\varphi^{\prime}(t)}{\varphi(t)}\left(x \partial_{x} u_{n}+y \partial_{y} u_{n}\right) \Delta u_{n} d t d x d y\right| \\
& +\int_{D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}\left|\nabla u_{n}\right|^{2}\left(T^{\prime}, x, y\right) d x d y \\
\geq & -2 \alpha\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}
\end{aligned}
$$

Hence

$$
\begin{aligned}
\left\|f_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2} & =\left\|\partial_{t} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}+\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}-2\left(\partial_{t} u_{n}, \Delta u_{n}\right)_{L^{2}\left(\Omega_{n}\right)} \\
& \geq\left\|\partial_{t} u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}+(1-2 \alpha)\left\|\Delta u_{n}\right\|_{L^{2}\left(\Omega_{n}\right)}^{2}
\end{aligned}
$$

Since $2 \alpha<1$, this inequality with Lemma 4 completes the proof.

## 4. Proof of Theorom 1

From the previous theorem we deduce that $\left\|u_{n}\right\|_{H^{1,2}\left(\Omega_{n}\right)} \leq C\|f\|_{L^{2}(\Omega)}$ for all $n \in \mathbb{N}$ because $\left\|f_{n}\right\|_{L^{2}\left(\Omega_{n}\right)} \leq\|f\|_{L^{2}(\Omega)}$. For any function $v$ defined in $\Omega_{n}$, denote by $\tilde{v}$ the function

$$
\tilde{v}=\left\{\begin{array}{c}
v: \text { in } \Omega_{n} \\
0: \text { in } \Omega_{T^{\prime}} \backslash \Omega_{n}
\end{array}\right.
$$

It is then possible to extract a subsequence $\left(\tilde{u}_{n_{j}}\right)_{j}$ from $\left(\tilde{u}_{n}\right) \in L^{2}\left(\Omega_{T^{\prime}}\right)$ which converges weakly in $H^{1,2}\left(\Omega_{T^{\prime}}\right)$. Denote by $u_{1}$ the limit of $\left(\tilde{u}_{n_{j}}\right)_{j}$. Therefore, passing to the limit for $n_{j} \rightarrow+\infty$, we get

$$
\left\{\begin{array}{c}
\partial_{t} u_{1}-\partial_{x}^{2} u_{1}-\partial_{y}^{2} u_{1}=f_{\mid \Omega_{T^{\prime}}} \in L^{2}\left(\Omega_{T^{\prime}}\right)  \tag{4.1}\\
u_{1 \mid \partial \Omega_{T^{\prime}} \backslash D(T, \varphi(T))}=0
\end{array}\right.
$$

This proves Theorem 1 in the subdomain $\Omega_{T^{\prime}}$.
Let $T$ be any positive real number, $f \in L^{2}(\Omega)$, and $T^{\prime}<T$ small enough in order to Problem 11 admits a solution $u_{1} \in H^{1,2}\left(\Omega_{T^{\prime}}\right)$

We have to solve Problem (1) in $\Omega$. We know (see Section 2) that the Cauchy-Dirichlet problem

$$
\left\{\begin{array}{c}
\partial_{t} v-\partial_{x}^{2} v-\partial_{y}^{2} v=f_{\mid \Omega_{T^{\prime} T}} \in L^{2}\left(\Omega_{T^{\prime} T}\right),  \tag{4.2}\\
v_{\mid \partial \Omega_{T^{\prime} T} \backslash D(T, \varphi(T))}=0 .
\end{array}\right.
$$

has a unique solution $v \in H^{1,2}\left(\Omega_{T^{\prime} T}\right)$.
We need the following trace result (see Lions-Magenes [12])
Lemma 9. For $v \in H^{1,2}\left(\Omega_{T^{\prime} T}\right)$, one has $v_{\mid D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)} \in H^{1}\left(D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)\right)$. Moreover, for each $\psi \in H_{0}^{1}\left(D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)\right)$, there exists $w \in H^{1,2}\left(\Omega_{T^{\prime} T}\right)$ such that $w_{\mid D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}=\psi$ and $w_{\mid \partial \Omega_{T^{\prime} T} \backslash D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}=0$.

Since $u_{1} \in H^{1,2}\left(\Omega_{T^{\prime}}\right)$, from this lemma and the homogeneous Problem (12), we obtain

Proposition 10. The problem

$$
\left\{\begin{array}{c}
\partial_{t} u_{2}-\partial_{x}^{2} u_{2}-\partial_{y}^{2} u_{2}=f_{\mid \Omega_{T^{\prime}}} \in L^{2}\left(\Omega_{T^{\prime} T}\right),  \tag{4.3}\\
u_{2 \mid D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}=u_{1 \mid D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right),}, \\
u_{2 \mid \partial \Omega_{T^{\prime} T} \backslash D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right) \cup D(T, \varphi(T))}=0 .
\end{array}\right.
$$

admits a unique solution $u_{2} \in H^{1,2}\left(\Omega_{T^{\prime} T}\right)$.
Now, define the function $u$ in $\Omega$ by

$$
u:=\left\{\begin{array}{c}
u_{1} \text { in } \Omega_{T^{\prime}} \\
u_{2} \text { in } \Omega_{T^{\prime} T}
\end{array}\right.
$$

where $u_{1}$ and $u_{2}$ are the solutions of Problem (11) and Problem (13) respectively. Observe that inasmuch as the boundary condition $u_{2 \mid D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}=$ $u_{1 \mid D\left(T^{\prime}, \varphi\left(T^{\prime}\right)\right)}$ is satisfied, it follows that $\partial_{x}^{2} u \in L^{2}(\Omega)$ and $\partial_{y}^{2} u \in L^{2}(\Omega)$, so, we have also $\partial_{x y} u \in L^{2}(\Omega)$. Moreover, in view of the equations given in Problem (11) and Problem (13) we deduce that $\partial_{t} u \in L^{2}(\Omega)$ and $\partial_{t} u-\partial_{x}^{2} u-\partial_{y}^{2} u=f$.

Finally, the function $u \in H^{1,2}(\Omega)$ is a solution of Problem (1). This completes the proof of Theorem 1.

Remark 11. This study can be extended to the case when the function $\varphi$ depends also on an angle $\theta \in(0,2 \pi)$. For instance, the domain $\Omega$ may be defined by

$$
\Omega=\left\{(t, x, y) \in \mathbb{R}^{3}: 0<t<T, 0 \leq \theta \leq 2 \pi, 0 \leq \sqrt{x^{2}+y^{2}}<\varphi(t, \theta)\right\}
$$

where $\varphi$ is a Lipschitz function $\varphi:[0, T] \times[0,2 \pi] \rightarrow \mathbb{R}^{+}$satisfying the condition $\varphi(0, \theta)=0$ for $0 \leq \theta \leq 2 \pi$ and $\varphi(t, 0)=\varphi(t, 2 \pi)$ Then, a new condition on $\varphi$ depending on $\theta$ will be appear. In particular, if $\varphi(t, \theta)=0$ for $0<t<T$ and $0 \leq \theta \leq \theta_{0}$ with $0<\theta_{0}<2 \pi$ the solution may contain some singularities, and no conditions on $\varphi$ could avoid these singularities.This problem will be treated later.

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