April 12, 2018 7:17

WSPC - Proceedings Trim Size: 9.75in x 6.5in main

1

INFERRING THE NEUTRON STAR EQUATION OF STATE FROM BINARY INSPIRAL WAVEFORMS

CHARALAMPOS MARKAKIS¹, JOCELYN S. READ², MASARU SHIBATA³,

KŌJI URYŪ⁴, JOLIEN D. E. CREIGHTON¹ and JOHN L. FRIEDMAN¹

¹Department of Physics, University of Wisconsin–Milwaukee PO Box 413, Milwaukee, WI 53201, USA

² Max-Planck-Institut für Gravitationsphysik, Albert-Einstein-Institut Golm, Germany

³Yukawa Institute for Theoretical Physics, Kyoto University Kyoto 606-8502, Japan

⁴Department of Physics, University of the Ryukyus 1 Senbaru, Nishihara, Okinawa 903-0213, Japan

The properties of neutron star matter above nuclear density are not precisely known. Gravitational waves emitted from binary neutron stars during their late stages of inspiral and merger contain imprints of the neutron-star equation of state. Measuring departures from the point-particle limit of the late inspiral waveform allows one to measure properties of the equation of state via gravitational wave observations. This and a companion talk by J. S. Read reports a comparison of numerical waveforms from simulations of inspiraling neutron-star binaries, computed for equations of state with varying stiffness. We calculate the signal strength of the difference between waveforms for various commissioned and proposed interferometric gravitational wave detectors and show that observations at frequencies around 1 kHz will be able to measure a compactness parameter and constrain the possible neutron-star equations of state.

In simulations of the late inspiral and merger of binary neutron-star systems, one typically specifies an equation of state (EOS) for the matter, performs a numerical evolution and extracts the gravitational waveforms produced in the inspiral. In this talk we report work on the inverse problem: if gravitational waves from an inspiraling neutron-star binary are observed, can they be used to infer the bulk properties of neutron star matter and, if so, with what accuracy? To answer this question, we performed a number of simulations,¹⁻³ using the evolution and initial data codes of Shibata and Uryū, while systematically varying the stiffness of a parameterized EOS. This parameterized EOS was previously developed in Refs. 3.4 and is of piecewise polytropic form, $p(\rho) = K_i \rho^{\Gamma_i}$ in a set of three intervals $\rho_{i-1} \leq \rho \leq \rho_i$ in rest-mass density, with the constants K_i determined by requiring continuity on each dividing ρ_i and the energy density determined by the first law of thermodynamics. As described in Refs. 3,4, the nonpolytropic EOS of the crust $(0 \leq \rho \leq \rho_0)$ as well as the dividing densities ρ_1, ρ_2 are fixed while the parameters $\{p_1 \equiv p(\rho_1), \Gamma_1, \Gamma_2, \Gamma_3\}$ are generally varied. In this first set of simulations we set $\Gamma_1 = \Gamma_2 = \Gamma_3 = 3$ and change the EOS stiffness by varying only p_1 , while keeping the Schwarzschild mass of each neutron star fixed at $1.35 M_{\odot}$. The choice of EOS parameter varied in this work is motivated by the fact that neutron-star radius is closely tied to the pressure at density not far above nuclear equilibrium density.⁵

 $\mathbf{2}$

Variation of the adiabatic exponents is the scope of a next set of simulations.

We compared the gravitational waveforms from the simulations to point-particle waveforms (see, for example, Ref. 6) and calculated the signal strength of the difference in waveforms using the sensitivity curves of commissioned and proposed gravitational wave detectors. We find that, as the stars approach their final plunge and merger, the gravitational phase accumulates more rapidly for larger values of p_1 or smaller values of the neutron-star compactness (the ratio of the neutron-star mass to its radius). The waveform analysis indicates that realistic EOS will result in waveforms that are distinguishable from point-particle inspiral at an effective distance (the distance to an optimally oriented and located system that would produce an equivalent waveform amplitude) of $D_0 = 100$ Mpc or less with gravitational wave detectors with the sensitivity of broadband Advanced LIGO. We further estimate that observations of this sensitivity will be able to constrain p_1 for a source at effective distance D with an accuracy of $\delta p_1/p_1 \sim 0.2D/D_0$. Related estimates of radius measurability show that such observations can determine the radius to an accuracy of $\delta R \sim 1 \text{ km } D/D_0$. These first estimates neglect other details of internal structure which are expected to give smaller tidal effect corrections. This is the subject of work underway, which involves improving the accuracy of the estimates with variation of the adiabatic exponents, determination of surfaces in the equation of state (EOS) parameter space associated with a given departure from the waveform of point-particle inspiral and numerical simulation of more orbits in the late inspiral. Also, the results mentioned above do not take into account multiple detectors, parameter correlation, or multiple observations. The latter possibility is briefly discussed below.

In the calculations mentioned above we estimated the error σ_0 in measuring an EOS parameter (such as p_1 or, more precisely, a related parameter that labels surfaces of constant departure from point-particle inspiral) from observation of one event at a reference effective distance $D_0 = 100$ Mpc. Here we wish to estimate the effect of multiple observations on the measurement accuracy. If N_i identical events, each with measurement uncertainty σ_i , occurred at the same effective distance D_i , then the overall uncertainty (standard error) of the combined measurement would be $\sigma_i/\sqrt{N_i}$. However, events do not occur at the same effective distance. Instead, we shall assume that events are homogeneously distributed in a sphere of effective radius $D_{\max} \simeq 300$ Mpc. (A uniform probability distribution of events in space is also uniform in effective space.) We divide this sphere into I shells of effective distance $D_i = D_{\max}(i-\frac{1}{2})/I$ with i = 1, ..., I and assume that detections will only be counted for sources with effective distance, we have $\sigma_i = \sigma_0 D_i/D_0$. Combining measurements at different distances will then result in an overall uncertainty σ given by

$$\frac{1}{\sigma^2} = \sum_{i=1}^{I} \frac{N_i}{\sigma_i^2} = \frac{D_0^2}{\sigma_0^2} \sum_{i=1}^{I} \frac{N_i}{D_i^2}$$
(1)

where N_i is the number of events in the *i*-th shell. Note that the N_i are random

variables, so σ is also a random variable with some probability distribution. The total number of events in a given year,

$$N = \sum_{i=1}^{I} N_i, \tag{2}$$

is itself a random variable and is Poisson-distributed around the rate of events $\mathcal{R} \equiv \langle N \rangle$ (average number of events per year). The probability distribution function $\mathcal{P}(\sigma|\mathcal{R})$ of σ given \mathcal{R} , and its moments $\langle \sigma \rangle$, $\langle \sigma^2 \rangle$ etc., are more easily computed via Monte-Carlo simulation rather than analytically. However, an analytical estimate for the moment $\langle \sigma^{-2} \rangle$ can be obtained by assuming a constant density n of events per year per unit effective volume and converting the sums (2) and (1) to integrals:

$$\langle N \rangle = \int_{0}^{D_{\text{max}}} 4\pi n \, D^2 dD = \frac{4\pi n}{3} D_{\text{max}}^3$$
(3)

$$\left\langle \frac{1}{\sigma^2} \right\rangle = \frac{D_0^2}{\sigma_0^2} \int_0^{D_{\max}} \frac{1}{D^2} 4\pi n \, D^2 dD = \frac{D_0^2}{\sigma_0^2} 4\pi n \, D_{\max} \tag{4}$$

Eliminating n from eqs. (3) and (4) yields the simple formula

$$\langle \sigma^{-2} \rangle^{-1/2} = \sigma_0 \frac{D_{\max}}{D_0} (3\mathcal{R})^{-1/2}$$
 (5)

Our Monte-Carlo simulations confirm that, while $\langle \sigma \rangle$, $\langle \sigma^2 \rangle^{1/2}$ and other moments do not in general scale proportionately to $\mathcal{R}^{-1/2}$ for fixed D_{max} , the moment $\langle \sigma^{-2} \rangle^{-1/2}$ scales exactly as dictated by eq. (5). This formula indicates that, for example, three events randomly distributed in a sphere of effective radius $D_{\text{max}} = 3D_0$ give the same "average" uncertainty $\langle \sigma^{-2} \rangle^{-1/2} = \sigma_0$ as one event at effective distance D_0 . Although the above calculation was done for measurement of a single parameter, it can be straightforwardly generalized for more parameters, by replacing the uncertainty σ^2 with a Fisher information matrix. As noted above, we have restricted consideration to neutron stars with a single fixed mass. Independent variation of the mass of each companion is the subject of future work.

Acknowledgements: This work was supported in part by NSF grants PHY-0503366, PHY-0701817 and PHY-0200852, the Greek State Scholarships Foundation and JSPS Grants 20540275 and 19540263. CM gratefully acknowledges travel support by NSF grant PHY-0919134 and assistance with the manuscript by M. Bakopoulou.

References

- 1. J. S. Read et al., Phys. Rev. D 79, p. 124033 (2009).
- 2. C. Markakis et al., Journal of Physics: Conference Series 189, p. 012024 (2009).
- 3. J. S. Read, PhD thesis, University of Wisconsin Milwaukee (WI, USA, 2008).
- 4. J. S. Read et al., Phys. Rev. D 79, p. 124032 (2009).
- 5. J. M. Lattimer and M. Prakash, The Astrophysical Journal 550, 426 (2001).
- 6. M. Boyle et al., Phys. Rev. D 76, p. 124038 (2007).