

Hindawi Publishing Corporation
Mathematical Problems in Engineering
Volume 2016, Article ID 5762502, 1 page
<http://dx.doi.org/10.1155/2016/5762502>



Corrigendum

Corrigendum to “Observer-Based Sliding Mode Control for Stabilization of a Dynamic System with Delayed Output Feedback”

Bo Wang,^{1,2} Peng Shi,^{3,4} Hamid Reza Karimi,⁵ and Cheng Chew Lim³

¹School of Electrical and Information Engineering, Xihua University, Chengdu 610096, China

²School of Applied Mathematics, University Electronic Science and Technology of China, Chengdu 610054, China

³School of Electrical and Electronic Engineering, The University of Adelaide, Adelaide, SA 5005, Australia

⁴College of Engineering and Science, Victoria University, Melbourne, VIC 8001, Australia

⁵Department of Engineering, Faculty of Engineering and Science, University of Agder, 4898 Grimstad, Norway

Correspondence should be addressed to Cheng Chew Lim; cheng.lim@adelaide.edu.au

Received 23 October 2016; Accepted 25 October 2016

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In the article titled “Observer-Based Sliding Mode Control for Stabilization of a Dynamic System with Delayed Output Feedback” [1] the order of the first and second affiliations was incorrect. The correct order of affiliations is shown above.

References

- [1] B. Wang, P. Shi, H. R. Karimi, and C. Lim, “Observer-based sliding mode control for stabilization of a dynamic system with delayed output feedback,” *Mathematical Problems in Engineering*, vol. 2013, Article ID 537414, 6 pages, 2013.



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