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A variational multiscale method for steady natural convection problem based on two-grid discretization

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Abstract

In this paper, we propose and analyze a two-grid variational multiscale method for the steady natural convection problem based on two local Gauss integrations technique. This method possesses the best algorithmic characteristics of both variational multiscale method and two-grid discretization. The main idea is to first solve the nonlinear steady natural convection problem on the coarse grid, then to use the coarse grid solution to fix the nonlinear terms, and to solve a linear problem on the fine grid. Stability and optimal error estimates of the discrete solutions in both one-grid and two-grid variational multiscale formulations are established. Finally, some numerical examples are presented to verify the method's promise and testify the theoretical predictions.

Keywords: natural convection problem; two-grid discretization; Oseen iteration; variational multiscale method; error estimates

1 Introduction

The natural convection phenomenon is present in many real situations such as room ventilation, double glass window design, *etc.* More importantly, it is behind the oceanic and atmospheric dynamics. Let $\Omega \subset \mathbb{R}^d$ (d = 2 or 3) be a regular bounded open domain, we consider the following steady natural convection problem:

	$-\operatorname{Pr}\Delta u + (u\cdot\nabla)u + \nabla p = \operatorname{Pr}\operatorname{Ra}\zeta T + \gamma_1,$	$\zeta = e/ e ,$	in Ω,	
	$\nabla \cdot \boldsymbol{\mu} = 0,$		in Ω,	
ł	u = 0,		on $\partial \Omega$,	(1.1)
	$-\nabla \cdot (k \nabla T) + (u \cdot \nabla)T = \gamma_2,$		in Ω,	
	$\nabla \cdot u = 0,$ u = 0, $-\nabla \cdot (k\nabla T) + (u \cdot \nabla)T = \gamma_2,$ $T = 0, \text{ on } \Gamma_T, \qquad \frac{\partial T}{\partial n} = 0, \text{ on } \Gamma_B,$			

where Ω is a bounded convex polyhedral domain, the unknown functions are the velocity *u*, the pressure *p*, and the temperature *T*. *e* is a unit vector in the direction of gravitational acceleration, γ_1 and γ_2 are known functions. *n* is the outward unit normal to Ω , and $\Gamma_T = \partial \Omega \setminus \Gamma_B$ where Γ_B is a regular open subset of $\partial \Omega$. Pr, Ra, and k > 0 denote Prandtl number, Rayleigh number, and thermal conductivity parameter, respectively.

The natural convection problem (1.1) is an important system with dissipative nonlinear terms in atmospheric dynamics. This system not only contains the velocity and pressure,



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but also includes the temperature field, finding the numerical solution of problem (1.1) becomes a difficult task. For the research of the natural convection problem (1.1), there have enormous works been devoted to the development of efficient schemes ([1–9] and the references therein). For example, [3, 4] developed the mixed finite element method (FEM) for problem (1.1). Cibik and Kaya [5] constructed a projection-based stabilization finite element method. Galvin *et al.* [6] studied problem (1.1) with poor mass conservation in mixed finite element algorithm for flow problems of large rotation-free forcing in the momentum equations. Zhang *et al.* [7] developed the decoupled two-grid method. For the timedependent case, Benítez and Bermúdez [9] considered a second order Lagrange-Galerkin method. Boland and Layton [1] presented stability and error estimates for the Galerkin finite element spatial semi-discretization case. Manzari [8] used standard Galerkin FEM in spatial discretization and an explicit multistage Runge-Kutta scheme in the time domain for convection heat transfer problem.

It is well known that the small viscous problem is a challenge subject due to the singularity of the numerical solutions. As a result, much attention has been appealed to the recent years. There are several numerical schemes have been developed for the simulation of small viscous flows, such as the decoupled method [7], the variational multiscale method [10–18], the defect-correction method [19, 20] and so on. Among them, the variational multiscale method is a popular numerical technique. This method is on the base of the decomposition of the flow scales and definition of the large scales that is projected into appropriate subspaces. In this work, we propose a new variational multiscale method by defining the stabilization terms via two local Gauss integrations based on projection operators. A significant feature of this new variational multiscale method is that the stabilization terms are defined by the difference between a consistent and an under-integrated matrix only involving the velocity gradient (and temperature gradient), rather than the projection operator as used in the common variational multiscale method. This new variational multiscale method does not need to introduce extra variables and can keep good accuracy. Zhang et al. have made some numerical examples in [21] to verify the efficiency of this new variational multiscale method for problem (1.1), Shang [22] has presented an error analysis of two level subgrid stabilized Oseen iterative method for time-dependent Navier-Stokes equations. The main contribution of this work can be listed as follows. (1) The theoretical analysis of new variational multiscale method based on two local Gauss integrations for steady natural convection problem is provided. (2) A two-grid variational multiscale Oseen iterative scheme for the steady natural convection problem is developed, the corresponding error estimates are presented. Therefore, our work can be considered as an extension and supplement of the existing results [18, 21, 22].

The paper is organized as follows. In Section 2, we present the notations and mathematical preliminaries for the considered problem and finite element spaces. Based on the elliptic projections of velocity and temperature, we formulate one-grid variational multiscale method, and apply the Oseen iterative scheme to linearize this nonlinear problem in Section 3. Section 4 develops and analyzes a two-grid variational multiscale Oseen iterative method. Finally, some numerical tests are presented to testify the correctness of the theoretical predictions and verify the effectiveness and efficiency of the developed method.

2 Preliminaries

2.1 Mathematical setting and basic results

The function spaces for the velocity u, the pressure p, and the temperature T are defined, respectively, by

$$\begin{split} X &= H_0^1(\Omega)^d = \left\{ \nu \in H^1(\Omega)^d : \nu = 0 \text{ on } \partial \Omega \right\}, \\ M &= L_0^2(\Omega) = \left\{ p \in L^2(\Omega) : (p,1)_\Omega = 0 \right\}, \\ W &= \left\{ S \in H^1(\Omega) : S = 0 \text{ on } \Gamma_B \right\}, \\ V &= H_{0,\text{div}}^1(\Omega) = \{ \nu \in X : \nabla \cdot \nu = 0 \text{ in } \Omega \}, \end{split}$$

where the spaces $L^2(\Omega)^m$, m = 1, 2, 3 are equipped with the standard L^2 -scalar product (\cdot, \cdot) and L^2 -norm $\|\cdot\|_0$, $H^j(\Omega)$ denotes the standard Sobolev space with norm $\|\cdot\|_j$. The space X is endowed with the usual scalar product $(\nabla u, \nabla v)$ and the norm $\|\nabla u\|_0$.

The weak form of (1.1) reads as follows: Find $(u, p, T) \in X \times M \times W$ such that

$$\begin{cases} \Pr a(u,v) + c(u,u,v) + b(v,p) - b(u,q) = \Pr \operatorname{Ra}(T\zeta,v) + (\gamma_1,v), \\ k\bar{a}(T,S) + \bar{c}(u,T,S) = (\gamma_2,S), \end{cases}$$
(2.1)

for all $(\nu, q, S) \in X \times M \times W$, where

$$\begin{split} a(u,v) &= (\nabla u, \nabla v), \qquad \bar{a}(T,S) = (\nabla T, \nabla S), \qquad b(v,q) = -(\nabla \cdot v,q), \\ c(u,v,w) &= \left((u \cdot \nabla)v,w\right) + \frac{1}{2}\left((\nabla \cdot u)v,w\right) = \frac{1}{2}\left((u \cdot \nabla)v,w\right) - \frac{1}{2}\left((u \cdot \nabla)w,v\right), \\ \bar{c}(u,T,S) &= \left((u \cdot \nabla)T,S\right) + \frac{1}{2}\left((\nabla \cdot u)T,S\right) = \frac{1}{2}\left((u \cdot \nabla)T,S\right) - \frac{1}{2}\left((u \cdot \nabla)S,T\right). \end{split}$$

The following lemma and theorem provide some important results for bilinear terms $a(\cdot, \cdot)$, $\bar{a}(\cdot, \cdot)$ and the existence and uniqueness of solutions for problem (1.1).

Lemma 2.1 (see [3]) For all $u, v, w \in X$ and $S, T \in W$, the following estimates hold.

$$\begin{aligned} |a(u,v)| &\leq \|\nabla u\|_{0} \|\nabla v\|_{0}, \qquad |a(u,u)| \geq \|\nabla u\|_{0}^{2}, \\ |\bar{a}(T,S)| &\leq \|\nabla T\|_{0} \|\nabla S\|_{0}, \qquad |\bar{a}(T,T)| \geq \|\nabla T\|_{0}^{2}, \\ |c(u,v,w)| &\leq N_{1} \|\nabla u\|_{0} \|\nabla v\|_{0} \|\nabla w\|_{0}, \qquad |c(u,v,v)| = 0, \\ |\bar{c}(u,T,S)| &\leq N_{2} \|\nabla u\|_{0} \|\nabla T\|_{0} \|\nabla S\|_{0}, \qquad |\bar{c}(u,T,T)| = 0, \end{aligned}$$

where $N_1 = \sup_{0 \neq u, v, w \in X} \frac{|c(u, v, w)|}{\|\nabla u\|_0 \|\nabla v\|_0 \|\nabla w\|_0}$ and $N_2 = \sup_{0 \neq u \in X, 0 \neq \theta, \psi \in W} \frac{|\overline{c}(u, \theta, \psi)|}{\|\nabla u\|_0 \|\nabla \theta\|_0 \|\nabla \psi\|_0}$.

Theorem 2.2 (see [3]) Under the condition

$$\operatorname{Ra} \|\gamma_2\|_{-1} + \frac{\operatorname{Pr}^{-1}}{k^{-1} + \operatorname{Pr} N_2 k^{-2}} \|\gamma_1\|_{-1} \le \frac{\operatorname{Pr}}{k^{-1} + \operatorname{Pr} N_2 k^{-2}},$$
(2.2)

problem (1.1) admits a unique solution (u, T) and satisfies

$$\|\nabla u\|_{0} \le \Pr^{-1} \|\gamma_{1}\|_{-1} + \operatorname{Ra} k^{-1} \|\gamma_{2}\|_{-1}, \qquad \|\nabla T\|_{0} \le k^{-1} \|\gamma_{2}\|_{-1}.$$
(2.3)

2.2 The finite element spaces

To introduce the finite element discretization of (2.1), we assume $\mathcal{T}^{\mu}(\Omega) = \{K\}$ (here $\mu = H, h$ with $H \gg h$ to be a shape-regular triangulation of Ω into triangles or quadrilaterals (if d = 2), or tetrahedrons or hexahedrons (if d = 3) with mesh size $0 < \mu < 1$. The fine mesh $\mathcal{T}^h(\Omega)$ is found by a mesh refinement process of the coarse mesh. It is of worth to mention that it is not necessary for our method, nor needed for the results of our convergence theorems to hold. However, we assume the coarse and fine grids nested since it will simplify our analysis substantially. Let $X_{\mu} \subset X$, $M_{\mu} \subset M$, $W_{\mu} \subset W$ be three finite element spaces associated with $\mathcal{T}^{\mu}(\Omega)$ and satisfying the following assumptions.

(A1) Approximation. For each $(u, p, T) \in H^{k+1}(\Omega)^d \times H^k(\Omega) \times H^{k+1}(\Omega)$, there exists an approximation $(\pi_{\mu}^{1}u, \rho_{\mu}p, \pi_{\mu}^{2}T)$ such that

$$\left\|\nabla\left(u-\pi_{\mu}^{1}u\right)\right\|_{0} \le c\mu^{s}\|u\|_{1+s}, \qquad \|p-\rho_{\mu}p\|_{0} \le cu^{s}\|p\|_{s},$$
(2.4)

$$\|\nabla(T - \pi_{\mu}^{2}T)\|_{0} \le c\mu^{s} \|T\|_{1+s}, \quad 0 \le s \le k,$$
(2.5)

here and below, the letters c and C denote the general positive constants dependent at most on the coefficients of the equations and the domain, but independent of the mesh size and the iterative times *m*, furthermore, they are different at their different occurrences.

(A2) inf-sup *condition*. For the finite element spaces X_{μ} and M_{μ} , there exists a constant $\beta > 0$ such that

$$\beta \|q_{\mu}\|_{0} \leq \sup_{\nu_{\mu} \in X_{\mu}, \nu_{\mu} \neq 0} \frac{(\nabla \cdot \nu_{\mu}, q_{\mu})}{\|\nabla \nu_{\mu}\|_{0}}, \quad \forall q_{\mu} \in M_{\mu}.$$

$$(2.6)$$

It is noted that many mixed finite element pairs such as the Taylor-Hood element, the MINI element, and the P_2 - P_0 element satisfy the above assumptions (A1) and (A2). Set

$$V_{\mu} = \left\{ \nu_{\mu} \in X_{\mu} : (\nabla \cdot \nu_{\mu}, q_{\mu}) = 0, \forall q_{\mu} \in M_{\mu} \right\}.$$

It is well known that (see [10])

$$\inf_{\nu_{\mu}\in V_{\mu}}\left\|\nabla(\nu-\nu_{\mu})\right\|_{0} \le C\left(1+\frac{1}{\beta}\right)\inf_{\nu_{\mu}\in X_{\mu}}\left\|\nabla(\nu-\nu_{\mu})\right\|_{0}, \quad \forall \nu \in V.$$
(2.7)

Under the above assumptions, the mixed finite element approximation of (2.1) reads: Find a pair $(u_{\mu}, p_{\mu}, T_{\mu}) \in X_{\mu} \times M_{\mu} \times W_{\mu}$ such that for all $(v_{\mu}, q_{\mu}, S_{\mu})$

$$\Pr a(u_{\mu}, v_{\mu}) + c(u_{\mu}, u_{\mu}, v_{\mu}) + b(v_{\mu}, p_{\mu}) - b(u_{\mu}, q_{\mu}) = \Pr \operatorname{Ra}(T_{\mu}\zeta, v_{\mu}) + (\gamma_{1}, v_{\mu}), k\bar{a}(T_{\mu}, S_{\mu}) + \bar{c}(u_{\mu}, T_{\mu}, S_{\mu}) = (\gamma_{2}, S_{\mu}).$$
(2.8)

The following theorem establishes the existence and uniqueness of the numerical solutions for problem (2.8) and provides the optimal L^2 -norm error estimates.

Theorem 2.3 (see [7]) Under the assumptions of (A1), (A2), and some assumptions as regards the k, Pr, Ra, γ_1 , γ_2 , problem (2.8) possesses a unique solution (u_μ , p_μ , T_μ) and satisfies

$$\|u - u_{\mu}\|_{0} + \|T - T_{\mu}\|_{0} \le C\mu^{2}, \qquad \|\nabla(u - u_{\mu})\|_{0} + \|\nabla(T - T_{\mu})\|_{0} + \|p - p_{\mu}\|_{0} \le C\mu.$$

3 The variational multiscale method based on two local Gauss integrations

In this section, we shall first formulate the variational multiscale method, and then develop the numerical scheme for the considered problem (2.1).

3.1 The variational multiscale method

Our variational multiscale method is based on two elliptic projection operators,

$$\Pi^1_{\mu}: X \to R_1 = \{ \nu \in H^1_0(\Omega)^a : \nu|_K \in (P_1)^a, \forall K \in E^{\mu}(\Omega) \}$$

 $\Pi^{2}_{\mu}: W \to R_{2} = \{S \in H^{1}_{0}(\Omega): S|_{K} \in P_{1}, \forall K \in E^{\mu}(\Omega)\},\$

which can be defined as follows (see [22]):

$$\begin{split} & \left(\nabla \Pi^1_{\mu} u, \nabla v \right) = (\nabla u, \nabla v), \quad \forall u \in X, v \in R_1, \\ & \left(\nabla \Pi^2_{\mu} T, \nabla S \right) = (\nabla T, \nabla S), \quad \forall T \in W, S \in R_2, \end{split}$$

and have the following properties:

$$\left\|\nabla\Pi^{1}_{\mu}u\right\|_{0} \leq \|\nabla u\|_{0}, \quad \forall u \in X, \qquad \left\|\nabla\Pi^{2}_{\mu}T\right\|_{0} \leq \|\nabla T\|_{0}, \quad \forall T \in W,$$
(3.1)

where R_1 and R_2 are two spaces of polynomials of degree less than or equal to one.

Based on projections Π^1_{μ} and Π^2_{μ} , we define the following stabilization terms:

$$G_1(u,v) = \alpha_1 \Big(\nabla \Big(I - \Pi^1_\mu \Big) u, \nabla \Big(I - \Pi^1_\mu \Big) v \Big), \quad \forall u, v \in X,$$
(3.2)

$$G_2(T,S) = \alpha_2 \left(\nabla \left(I - \Pi_{\mu}^2 \right) T, \nabla \left(I - \Pi_{\mu}^2 \right) S \right), \quad \forall T, S \in W,$$
(3.3)

where $\alpha_1, \alpha_2 > 0$ are two user-defined stabilization parameters, typically chosen as $\alpha_1 = \alpha_2 = \mathcal{O}(\mu)^s$ (here s > 0 is a constant related to the finite elements used for the discretization of the considered problem).

Thanks to (3.2) and (3.3), the finite element variational multiscale method for problem (2.1) reads as follows: Find $(u_{\mu}, p_{\mu}, T_{\mu}) \in X_{\mu} \times M_{\mu} \times W_{\mu}$ such that

$$\begin{cases} \Pr a(u_{\mu}, v_{\mu}) + c(u_{\mu}, u_{\mu}, v_{\mu}) + b(v_{\mu}, p_{\mu}) - b(u_{\mu}, q_{\mu}) + G_{1}(u_{\mu}, v_{\mu}) \\ = \Pr \operatorname{Ra}(T_{\mu}\zeta, v_{\mu}) + (\gamma_{1}, v_{\mu}), \\ k\bar{a}(T_{\mu}, S_{\mu}) + \bar{c}(u_{\mu}, T_{\mu}, S_{\mu}) + G_{2}(T_{\mu}, S_{\mu}) = (\gamma_{2}, S_{\mu}), \end{cases}$$
(3.4)

for all $(\nu_{\mu}, q_{\mu}, S_{\mu}) \in X_{\mu} \times M_{\mu} \times W_{\mu}$.

3.2 Stability and convergence of scheme (3.4)

The system (3.4) is nonlinear; it needs to be linearized in computations. A popular linearization process is the one based on the Newton iterative method. However, it is well known that the Newton iterative method is sensitive to the initial guess for the nonlinear iterations, *i.e.*, to guarantee the convergence of the Newton iterations, the initial guess should be close enough to the solution (u_{μ}, T_{μ}) . Here we use the Oseen iterative method to solve (3.4).

From the definitions (3.2) and (3.3) of the projection operators Π^1_{μ} , Π^2_{μ} , we have

$$G_{1}(u,v) = \alpha_{1} \left(\nabla \left(I - \Pi_{\mu}^{1} \right) u, \nabla \left(I - \Pi_{\mu}^{1} \right) v \right)$$
$$= \alpha_{1} \left(\nabla u, \nabla v \right) - \alpha_{1} \left(\nabla \Pi_{\mu}^{1} u, \nabla v \right), \quad \forall u, v \in X,$$
(3.5)

$$G_{2}(T,S) = \alpha_{2} \left(\nabla \left(I - \Pi_{\mu}^{2} \right) T, \nabla \left(I - \Pi_{\mu}^{2} \right) S \right)$$
$$= \alpha_{2} \left(\nabla T, \nabla S \right) - \alpha_{2} \left(\nabla \Pi_{\mu}^{2} T, \nabla S \right), \quad \forall T, S \in W.$$
(3.6)

By applying the Oseen iterative method to the nonlinear problem (3.4) and thanks to (3.5) and (3.6), we develop the variational multiscale Oseen iterative scheme for the natural convection problem: Find an iterative solution $(u_{\mu}^n, p_{\mu}^n, T_{\mu}^n) \in X_{\mu} \times M_{\mu} \times W_{\mu}$ such that

$$\begin{cases} (\Pr + \alpha_1)a(u_{\mu}^n, \nu_{\mu}) + c(u_{\mu}^{n-1}, u_{\mu}^n, \nu_{\mu}) + b(\nu_{\mu}, p_{\mu}^n) - b(u_{\mu}^n, q_{\mu}) \\ = \Pr \operatorname{Ra}(T_{\mu}^n \zeta, \nu_{\mu}) + (\gamma_1, \nu_{\mu}) + \alpha_1(\nabla \Pi_{\mu}^1 u_{\mu}^{n-1}, \nabla \nu_{\mu}), \\ (k + \alpha_2)\bar{a}(T_{\mu}^n, S_{\mu}) + \bar{c}(u_{\mu}^{n-1}, T_{\mu}^n, S_{\mu}) = (\gamma_2, S_{\mu}) + \alpha_2(\nabla \Pi_{\mu}^2 T_{\mu}^{n-1}, \nabla S_{\mu}), \end{cases}$$
(3.7)

for all $(\nu_{\mu}, q_{\mu}, S_{\mu}) \in X_{\mu} \times M_{\mu} \times W_{\mu}$, $n = 1, 2, \dots$, with $u_{\mu}^0 = 0$, $T_{\mu}^0 = 0$.

Throughout this paper, we assume that μ is small enough such that the iterative scheme (3.7) is convergent. In order to keep notation brief, we define

$$A = \Pr^{-1} \|\gamma_1\|_{-1} + \operatorname{Ra} k^{-1} \|\gamma_2\|_{-1}, \qquad B = k^{-1} \|\gamma_2\|_{-1}.$$

Theorem 3.1 The iterative solution $(u_{\mu}^{n}, T_{\mu}^{n})$ defined by (3.7) satisfies

$$\left\|\nabla u_{\mu}^{n}\right\|_{0} \leq A, \qquad \left\|\nabla T_{\mu}^{n}\right\|_{0} \leq B, \quad \forall n \geq 1.$$

$$(3.8)$$

Proof Let $S_{\mu} = T_{\mu}^{n}$ in the second equation of (3.7), we have

$$(k+\alpha_2)\bar{a}(T^n_{\mu},T^n_{\mu})=(\gamma_2,T^n_{\mu})+\alpha_2(\nabla\Pi^2_{\mu}T^{n-1}_{\mu},\nabla T^n_{\mu}).$$

We use the Cauchy-Schwarz inequality and (3.1) to obtain

$$(k + \alpha_2) \|\nabla T_{\mu}^n\|_0 \le \|\gamma_2\|_{-1} + \alpha_2 \|\nabla \Pi_{\mu}^2 T_{\mu}^{n-1}\|_0 \le \|\gamma_2\|_{-1} + \alpha_2 \|\nabla T_{\mu}^{n-1}\|_0$$

When n = 1, we get

$$(k+\alpha_2) \|\nabla T^1_{\mu}\|_0 \le \|\gamma_2\|_{-1} \quad \Rightarrow \quad \|\nabla T^1_{\mu}\|_0 \le \frac{1}{k+\alpha_2} \|\gamma_2\|_{-1} \le k^{-1} \|\gamma_2\|_{-1}$$

which shows that the second inequality of (3.8) holds for n = 1. We now assume it holds for n = J and prove it holds for n = J + 1,

$$(k+\alpha_2) \|\nabla T_{\mu}^{J+1}\|_0 \le \|\gamma_2\|_{-1} + \alpha_2 \|\nabla T_{\mu}^{J}\|_0 \le k^{-1}(k+\alpha_2) \|\gamma_2\|_{-1}.$$

As a consequence one finds

$$\left\|\nabla T_{\mu}^{J+1}\right\|_{0} \le k^{-1} \|\gamma_{2}\|_{-1}.$$
(3.9)

Taking $v_{\mu} = u_{\mu}^{n}$ and $q_{\mu} = p_{\mu}^{n}$ in the first equation of (3.7), and using (3.1), we obtain

$$\begin{aligned} (\Pr + \alpha_1) \| \nabla u_{\mu}^n \|_0 &\leq \|\gamma_1\|_{-1} + \alpha_1 \| \nabla \Pi_{\mu}^1 u_{\mu}^{n-1} \|_0 + \Pr \operatorname{Ra} \| T_{\mu}^n \|_{-1} \\ &\leq \|\gamma_1\|_{-1} + \alpha_1 \| \nabla u_{\mu}^{n-1} \|_0 + \Pr \operatorname{Ra} k^{-1} \| \gamma_2 \|_{-1}. \end{aligned}$$

Due to the facts that $\alpha_1 > 0$ and $u_{\mu}^0 = 0$, we know that (3.8) holds for n = 1. Assume that the first inequality of (3.8) holds for n = J. Taking $(v_{\mu}, q_{\mu}) = (u_{\mu}^{J+1}, p_{\mu}^{J+1}) \in X_{\mu} \times M_{\mu}$ in the first equation of (3.7) with n = J + 1, we get

$$\begin{aligned} (\Pr + \alpha_1) \| \nabla u_{\mu}^{J+1} \|_0 &\leq \| \gamma_1 \|_{-1} + \alpha_1 \| \nabla u_{\mu}^{J} \|_0 + \Pr \operatorname{Ra} k^{-1} \| \gamma_2 \|_{-1} \\ &\leq \| \gamma_1 \|_{-1} + \alpha_1 \left(\Pr^{-1} \| \gamma_1 \|_{-1} + \operatorname{Ra} k^{-1} \| \gamma_2 \|_{-1} \right) + \Pr \operatorname{Ra} k^{-1} \| \gamma_2 \|_{-1} \\ &\leq \frac{\Pr + \alpha_1}{\Pr} \| \gamma_1 \|_{-1} + (\Pr + \alpha_1) \operatorname{Ra} k^{-1} \| \gamma_2 \|_{-1}. \end{aligned}$$

Consequently, we obtain

$$\|\nabla u_{\mu}^{J+1}\|_{0} \leq \Pr^{-1} \|\gamma_{1}\|_{-1} + \operatorname{Ra} k^{-1} \|\gamma_{2}\|_{-1},$$

which with (3.9) completes the proof.

Theorem 3.2 Assume that (u, T) is the nonsingular solution to the natural convection problem (1.1), α_1 and α_2 tend to zero as μ tends to zero. Under the condition of

$$\Pr + 2\alpha_1 - 2N_1A - 2(k + \alpha_2)^{-1} \cdot \Pr \operatorname{Ra} N_2B > 0, \qquad (3.10)$$

there exists $\mu_0 > 0$ such that for all $\mu \le \mu_0$, the solution $(u_{\mu}^n, p_{\mu}^n, T_{\mu}^n)$ of (3.7) satisfies

$$\begin{aligned} \frac{1}{2} \Pr \|\nabla(u - u_{\mu}^{n})\|_{0} \\ &\leq C(\beta) \left(\frac{3}{2} \Pr + \alpha_{1} + 2N_{1}A + \frac{\Pr \operatorname{Ra} N_{2}B}{k + \alpha_{2}}\right) \inf_{\bar{u} \in X_{\mu}} \|\nabla(u - \bar{u})\|_{0} \\ &+ \sqrt{d} \inf_{\lambda_{\mu} \in M_{\mu}} \|p - \lambda_{\mu}\|_{0} + 2\alpha_{1}A + \left(N_{1}A + \frac{\Pr \operatorname{Ra} N_{2}B}{k + \alpha_{2}}\right) \|\nabla(u_{\mu}^{n} - u_{\mu}^{n-1})\|_{0} \\ &+ \frac{\Pr \operatorname{Ra}(2k + 2\alpha_{2} + N_{2}A)}{k + \alpha_{2}} \inf_{\bar{T} \in W_{\mu}} \|\nabla(T - \bar{T})\|_{0} + \frac{2\Pr \operatorname{Ra} \alpha_{2}B}{k + \alpha_{2}}, \end{aligned}$$
(3.11)
$$\|p - p_{\mu}^{n}\|_{0} \leq \left(\frac{\sqrt{d}}{\beta} + 1\right) \inf_{\lambda_{\mu} \in M_{\mu}} \|p - \lambda_{\mu}\|_{0} + \frac{1}{\beta} (\Pr + \alpha_{1} + 2N_{1}A) \|\nabla(u - u_{\mu}^{n})\|_{0} \\ &+ \frac{N_{1}A}{\beta} \|\nabla(u_{\mu}^{n} - u_{\mu}^{n-1})\|_{0} + \frac{2\alpha_{1}A}{\beta} + \frac{\Pr \operatorname{Ra}}{\beta} \|\nabla(T - T_{\mu}^{n})\|_{0}, \end{aligned}$$
(3.12)

$$+\frac{N_2B}{k+\alpha_2} \|\nabla (u_{\mu}^n - u_{\mu}^{n-1})\|_0 + \frac{2\alpha_2B}{k+\alpha_2}.$$
(3.13)

Here \bar{u} , λ_{μ} , and \bar{T} are the approximations of u, p, and T in X_{μ} , M_{μ} , and W_{μ} , respectively.

Remark 3.1 As the velocity u and temperature T are coupled in system (2.1), the error estimation for $T - T^n_{\mu}$ is coupled with the error $u - u^n_{\mu}$.

Proof Setting $(e_{\mu}^{n}, \eta_{\mu}^{n}, \phi_{\mu}^{n}) = (u - u_{\mu}^{n}, p - p_{\mu}^{n}, T - T_{\mu}^{n})$ and subtracting (3.7) from (2.1), we obtain the following error equations for the variational multiscale Oseen iterative scheme:

$$\begin{cases} (\Pr + \alpha_1)(\nabla e_{\mu}^n, \nabla v_{\mu}) + c(u, u, v_{\mu}) - c(u_{\mu}^{n-1}, u_{\mu}^n, v_{\mu}) + b(v_{\mu}, \eta_{\mu}^n) - b(e_{\mu}^n, q_{\mu}) \\ = \Pr \operatorname{Ra}(\phi_{\mu}^n \zeta, v_{\mu}) + \alpha_1(\nabla u, \nabla v_{\mu}) - \alpha_1(\nabla \Pi_{\mu}^1 u_{\mu}^{n-1}, \nabla v_{\mu}), \\ (k + \alpha_2)\bar{a}(\phi_{\mu}^n, S_{\mu}) + \bar{c}(u, T, S_{\mu}) - \bar{c}(u_{\mu}^{n-1}, T_{\mu}^n, S_{\mu}) \\ = \alpha_2(\nabla T, \nabla S_{\mu}) - \alpha_2(\nabla \Pi_{\mu}^2 T_{\mu}^{n-1}, \nabla S_{\mu}), \end{cases}$$
(3.14)

for all $(\nu_{\mu}, q_{\mu}, S_{\mu}) \in X_{\mu} \times M_{\mu} \times W_{\mu}$. Taking $\nu_{\mu} \in V_{\mu}$ and $q_{\mu} = 0$, we get for any $\lambda_{\mu} \in M_{\mu}$

$$(\operatorname{Pr} + \alpha_{1}) \left(\nabla e_{\mu}^{n}, \nabla v_{\mu} \right) + c(u, u, v_{\mu}) - c \left(u_{\mu}^{n-1}, u_{\mu}^{n}, v_{\mu} \right) - \left(\nabla \cdot v_{\mu}, p - \lambda_{\mu} \right)$$
$$= \operatorname{Pr} \operatorname{Ra} \left(\phi_{\mu}^{n} \zeta, v_{\mu} \right) + \alpha_{1} (\nabla u, \nabla v_{\mu}) - \alpha_{1} \left(\nabla \Pi_{\mu}^{1} u_{\mu}^{n-1}, \nabla v_{\mu} \right).$$
(3.15)

Splitting $e_{\mu}^{n} = \rho_{1} - \xi_{\mu}^{n}$ into $\rho_{1} = u - \bar{u}$ and $\xi_{\mu}^{n} = u_{\mu}^{n} - \bar{u}$, \bar{u} is an approximation of u in V_{μ} , splitting $\phi_{\mu}^{n} = \rho_{2} - \varepsilon_{\mu}^{n}$ with $\rho_{2} = T - \bar{T}$ and $\varepsilon_{\mu}^{n} = T_{\mu}^{n} - \bar{T}$, \bar{T} is an approximation of T in W_{μ} , noting that

$$c(u, u, v_{\mu}) - c(u_{\mu}^{n-1}, u_{\mu}^{n}, v_{\mu})$$

$$= c(u, u - u_{\mu}^{n} + u_{\mu}^{n}, v_{\mu}) - c(u_{\mu}^{n-1}, u_{\mu}^{n}, v_{\mu})$$

$$= c(u, e_{\mu}^{n}, v_{\mu}) + c(e_{\mu}^{n}, u_{\mu}^{n}, v_{\mu}) + c(u_{\mu}^{n} - u_{\mu}^{n-1}, u_{\mu}^{n}, v_{\mu})$$

$$= c(u, \rho_{1}, v_{\mu}) - c(u, \xi_{\mu}^{n}, v_{\mu}) + c(\rho_{1}, u_{\mu}^{n}, v_{\mu})$$

$$- c(\xi_{\mu}^{n}, u_{\mu}^{n}, v_{\mu}) + c(u_{\mu}^{n} - u_{\mu}^{n-1}, u_{\mu}^{n}, v_{\mu}).$$
(3.16)

In the same way, we have

$$\bar{c}(u, T, S_{\mu}) - \bar{c}\left(u_{\mu}^{n-1}, T_{\mu}^{n}, S_{\mu}\right) = \bar{c}(u, \rho_{2}, S_{\mu}) - \bar{c}\left(u, \varepsilon_{\mu}^{n}, S_{\mu}\right) + \bar{c}\left(e_{\mu}^{n}, T_{\mu}^{n}, S_{\mu}\right) + \bar{c}\left(u_{\mu}^{n} - u_{\mu}^{n-1}, T_{\mu}^{n}, S_{\mu}\right).$$
(3.17)

From the second equation of (3.14), one finds

$$\begin{split} (k+\alpha_2) \Big(\nabla \varepsilon_{\mu}^n, \nabla S_{\mu} \Big) &= (k+\alpha_2) (\nabla \rho_2, \nabla S_{\mu}) + \bar{c}(u,T,S_{\mu}) - \bar{c} \Big(u, T_{\mu}^n, S_{\mu} \Big) \\ &+ \alpha_2 \Big(\nabla \Pi_{\mu}^2 T_{\mu}^{n-1}, \nabla S_{\mu} \Big) - \alpha_2 (\nabla T, \nabla S_{\mu}). \end{split}$$

We take $S_{\mu} = \varepsilon_{\mu}^{n}$ using (3.17) to obtain

$$(k+\alpha_2)\left(\nabla\varepsilon_{\mu}^n,\nabla\varepsilon_{\mu}^n\right) = (k+\alpha_2)\left(\nabla\rho_2,\nabla\varepsilon_{\mu}^n\right) + \bar{c}\left(u,\rho_2,\varepsilon_{\mu}^n\right) + \bar{c}\left(e_{\mu}^n,T_{\mu}^n,\varepsilon_{\mu}^n\right) \\ + \bar{c}\left(u_{\mu}^n - u_{\mu}^{n-1},T_{\mu}^n,\varepsilon_{\mu}^n\right) + \alpha_2\left(\nabla\Pi_{\mu}^2T_{\mu}^{n-1},\nabla\varepsilon_{\mu}^n\right) - \alpha_2\left(\nabla T,\nabla\varepsilon_{\mu}^n\right).$$

Thanks to Theorem 2.2, (3.1) and Theorem 3.1 we derive that

$$(k + \alpha_2) \| \nabla \varepsilon_{\mu}^n \|_0 \le (k + \alpha_2 + N_2 A) \| \nabla \rho_2 \|_0 + N_2 B \| \nabla e_{\mu}^n \|_0 + N_2 B \| \nabla (u_{\mu}^n - u_{\mu}^{n-1}) \|_0 + 2\alpha_2 B.$$

With the help of the triangle inequality one finds

$$\begin{aligned} (k+\alpha_2) \|\nabla \phi_{\mu}^{n}\|_{0} &\leq (2k+2\alpha_2+N_2A) \|\nabla \rho_2\|_{0} + N_2B \|\nabla e_{\mu}^{n}\|_{0} \\ &+ N_2B \|\nabla (u_{\mu}^{n}-u_{\mu}^{n-1})\|_{0} + 2\alpha_2B. \end{aligned}$$

We can get the error estimation (3.13) for $T - T^n_{\mu}$ by taking the infimum over W_{μ} . Now let us to prove (3.11). The applications of (3.15) and (3.16) lead to

$$(\Pr + \alpha_1) \left(\nabla \xi_{\mu}^n, \nabla v_{\mu} \right) = (\Pr + \alpha_1) (\nabla \rho_1, \nabla v_{\mu}) + c(u, \rho_1, v_{\mu}) - c(u, \xi_{\mu}^n, v_{\mu}) + c(\rho_1, u_{\mu}^n, v_{\mu}) - c(\xi_{\mu}^n, u_{\mu}^n, v_{\mu}) + c(u_{\mu}^n - u_{\mu}^{n-1}, u_{\mu}^n, v_{\mu}) - \Pr \operatorname{Ra}(\phi_{\mu}^n \zeta, v_{\mu}) - \alpha_1 (\nabla u, \nabla v_{\mu}) + \alpha_1 (\nabla \Pi_{\mu}^1 u_{\mu}^{n-1}, \nabla v_{\mu}) - (\nabla \cdot v_{\mu}, p - \lambda_{\mu}).$$

Taking $v_{\mu} = \xi_{\mu}^{n}$, we get

$$\begin{aligned} (\Pr + \alpha_1) \Big(\nabla \xi_{\mu}^n, \nabla \xi_{\mu}^n \Big) \\ &= (\Pr + \alpha_1) \Big(\nabla \rho_1, \nabla \xi_{\mu}^n \Big) + c \Big(u, \rho_1, \xi_{\mu}^n \Big) + c \Big(\rho_1, u_{\mu}^n, \xi_{\mu}^n \Big) - c \Big(\xi_{\mu}^n, u_{\mu}^n, \xi_{\mu}^n \Big) \\ &+ c \Big(u_{\mu}^n - u_{\mu}^{n-1}, u_{\mu}^n, \xi_{\mu}^n \Big) - \Pr \operatorname{Ra} \Big(\phi_{\mu}^n \zeta, \xi_{\mu}^n \Big) - \alpha_1 \Big(\nabla u, \nabla \xi_{\mu}^n \Big) \\ &+ \alpha_1 \Big(\nabla \Pi_{\mu}^1 u_{\mu}^{n-1}, \nabla \xi_{\mu}^n \Big) - \big(\nabla \cdot \xi_{\mu}^n, p - \lambda_{\mu} \Big). \end{aligned}$$

Thus

$$\begin{aligned} (\Pr + \alpha_{1}) \| \nabla \xi_{\mu}^{n} \|_{0} \\ &\leq \left(\Pr + \alpha_{1} + N_{1} \| \nabla u \|_{0} + N_{1} \| \nabla u_{\mu}^{n} \|_{0} \right) \| \nabla \rho_{1} \|_{0} + N_{1} \| \nabla u_{\mu}^{n} \|_{0} \| \nabla \left(u_{\mu}^{n} - u_{\mu}^{n-1} \right) \|_{0} \\ &+ \Pr \operatorname{Ra} \| \nabla \phi_{\mu}^{n} \|_{0} + \alpha_{1} \| \nabla u \|_{0} + \alpha_{1} \| \nabla \Pi_{\mu}^{1} u_{\mu}^{n-1} \|_{0} \\ &+ N_{1} \| \nabla u_{\mu}^{n} \|_{0} \| \nabla \xi_{\mu}^{n} \|_{0} + \sqrt{d} \| p - \lambda_{\mu} \|_{0}. \end{aligned}$$

Making use of Theorem 2.2 and Theorem 3.1, we obtain

$$(\Pr + \alpha_{1}) \| \nabla \xi_{\mu}^{n} \|_{0} \leq (\Pr + \alpha_{1} + 2N_{1}A) \| \nabla \rho_{1} \|_{0} + N_{1}A \| \nabla (u_{\mu}^{n} - u_{\mu}^{n-1}) \|_{0} + \Pr \operatorname{Ra} \| \nabla \phi_{\mu}^{n} \|_{0} + 2\alpha_{1}A + N_{1}A \| \nabla \xi_{\mu}^{n} \|_{0} + \sqrt{d} \| p - \lambda_{\mu} \|_{0}.$$
(3.18)

To complete the proof, the bound (3.13) is inserted into the one of (3.18), this gives

$$\begin{aligned} (\Pr + \alpha_1) \| \nabla \xi_{\mu}^n \|_0 \\ &\leq (\Pr + \alpha_1 + 2N_1 A) \| \nabla \rho_1 \|_0 + N_1 A \| \nabla (u_{\mu}^n - u_{\mu}^{n-1}) \|_0 + 2\alpha_1 A + N_1 A \| \nabla \xi_{\mu}^n \|_0 \\ &+ \sqrt{d} \| p - \lambda_{\mu} \|_0 + \Pr \operatorname{Ra} \left[\frac{2k + 2\alpha_2 + N_2 A}{k + \alpha_2} \inf_{\bar{T} \in W_{\mu}} \| \nabla (T - \bar{T}) \|_0 \\ &+ \frac{N_2 B}{k + \alpha_2} \| \nabla (u - u_{\mu}^n) \|_0 + \frac{N_2 B}{k + \alpha_2} \| \nabla (u_{\mu}^n - u_{\mu}^{n-1}) \|_0 + \frac{2\alpha_2 B}{k + \alpha_2} \right], \end{aligned}$$

thus

$$\left(\Pr + \alpha_{1} - N_{1}A - \frac{\Pr \operatorname{Ra} N_{2}B}{k + \alpha_{2}}\right) \|\nabla \xi_{\mu}^{n}\|_{0} \leq \left(\Pr + \alpha_{1} + 2N_{1}A + \frac{\Pr \operatorname{Ra} N_{2}B}{k + \alpha_{2}}\right) \|\nabla \rho_{1}\|_{0} + \left(N_{1}A + \frac{\Pr \operatorname{Ra} N_{2}B}{k + \alpha_{2}}\right) \|\nabla \left(u_{\mu}^{n} - u_{\mu}^{n-1}\right)\|_{0} + 2\alpha_{1}A + \sqrt{d}\|p - \lambda_{\mu}\|_{0} + \frac{\Pr \operatorname{Ra}(2k + 2\alpha_{2} + N_{2}A)}{k + \alpha_{2}}\inf_{\tilde{T} \in W_{\mu}} \|\nabla (T - \tilde{T})\|_{0} + \frac{2\Pr \operatorname{Ra} \alpha_{2}B}{k + \alpha_{2}}.$$
(3.19)

Under the condition of (3.10) we find that

$$\frac{1}{2} \operatorname{Pr} \|\nabla e_{\mu}^{n}\|_{0} \leq \frac{1}{2} \operatorname{Pr} \left(\|\nabla \rho_{1}\|_{0} + \|\nabla \xi_{\mu}^{n}\|_{0} \right) \\
\leq \left(\frac{3}{2} \operatorname{Pr} + \alpha_{1} + 2N_{1}A + \frac{\operatorname{Pr}\operatorname{Ra}N_{2}B}{k + \alpha_{2}} \right) \|\nabla \rho_{1}\|_{0} + \sqrt{d} \|p - \lambda_{\mu}\|_{0} \\
+ 2\alpha_{1}A + \frac{2\operatorname{Pr}\operatorname{Ra}\alpha_{2}B}{k + \alpha_{2}} + \left(N_{1}A + \frac{\operatorname{Pr}\operatorname{Ra}N_{2}B}{k + \alpha_{2}} \right) \|\nabla \left(u_{\mu}^{n} - u_{\mu}^{n-1}\right)\|_{0} \\
+ \frac{\operatorname{Pr}\operatorname{Ra}(2k + 2\alpha_{2} + N_{2}A)}{k + \alpha_{2}} \inf_{\bar{T} \in W_{\mu}} \|\nabla (T - \bar{T})\|_{0}. \tag{3.20}$$

Taking the infimum over $\bar{u} \in V_{\mu}$, $\lambda_{\mu} \in M_{\mu}$, and using (2.7), we get the required result (3.11).

Now, we present the convergence of $p - p_{\mu}^n$. Letting λ_{μ} be an approximation of p in M_{μ} and setting $p - p_{\mu}^n = (p - \lambda_{\mu}) - (p_{\mu}^n - \lambda_{\mu})$, from the first equation of (3.14) and (3.16) we get

$$\begin{split} \left(\nabla \cdot v_{\mu}, p_{\mu}^{n} - \lambda_{\mu}\right) \\ &= (\nabla \cdot v_{\mu}, p - \lambda_{\mu}) - (\Pr + \alpha_{1}) \left(\nabla e_{\mu}^{n}, \nabla v_{\mu}\right) - c \left(u, e_{\mu}^{n}, v_{\mu}\right) - c \left(e_{\mu}^{n}, u_{\mu}^{n}, u_{\mu}\right) \\ &- c \left(u_{\mu}^{n} - u_{\mu}^{n-1}, u_{\mu}^{n}, v_{\mu}\right) + \alpha_{1} (\nabla u, \nabla v_{\mu}) - \alpha_{1} \left(\nabla \Pi_{\mu}^{1} u_{\mu}^{n-1}, \nabla v_{\mu}\right) + \Pr \operatorname{Ra}(\phi_{\mu}^{n} \zeta, v_{\mu}) \\ &\leq \left[\sqrt{d} \|p - \lambda_{\mu}\|_{0} + \left(\Pr + \alpha_{1} + N_{1} \|\nabla u\|_{0} + N_{1} \|\nabla u_{\mu}^{n}\|_{0}\right) \|\nabla e_{\mu}^{n}\|_{0} + \Pr \operatorname{Ra} \|\nabla \phi_{\mu}^{n}\|_{0} \\ &+ N_{1} \|\nabla u_{\mu}^{n}\|_{0} \|\nabla (u_{\mu}^{n} - u_{\mu}^{n-1})\|_{0} + \alpha_{1} (\|\nabla u\|_{0} + \|\nabla u_{\mu}^{n-1}\|_{0})] \|\nabla v_{\mu}\|_{0}, \end{split}$$

which together with the inf-sup condition and the bounds of $\|\nabla u\|_0$, $\|\nabla u_{\mu}^{n-1}\|_0$, $\|\nabla u_{\mu}^n\|_0$ yields

$$\begin{split} \beta \left\| p_{\mu}^{n} - \lambda_{\mu} \right\|_{0} \\ &\leq \sqrt{d} \| p - \lambda_{\mu} \|_{0} + \left(\Pr + \alpha_{1} + N_{1} \| \nabla u \|_{0} + N_{1} \| \nabla u_{\mu}^{n} \|_{0} \right) \| \nabla e_{\mu}^{n} \|_{0} \\ &+ N_{1} \| \nabla u_{\mu}^{n} \|_{0} \| \nabla \left(u_{\mu}^{n} - u_{\mu}^{n-1} \right) \|_{0} + \alpha_{1} \left(\| \nabla u \|_{0} + \| \nabla u_{\mu}^{n-1} \|_{0} \right) + \Pr \operatorname{Ra} \| \nabla \phi_{\mu}^{n} \|_{0} \\ &\leq \sqrt{d} \| p - \lambda_{\mu} \|_{0} + \left(\Pr + \alpha_{1} + 2N_{1}A \right) \| \nabla \left(u - u_{\mu}^{n} \right) \|_{0} \\ &+ N_{1}A \| \nabla \left(u_{\mu}^{n} - u_{\mu}^{n-1} \right) \|_{0} + 2\alpha_{1}A + \Pr \operatorname{Ra} \| \nabla \left(T - T_{\mu}^{n} \right) \|_{0}. \end{split}$$

Using the triangle inequality and taking the infimum over $\lambda_{\mu} \in M_{\mu}$, we finish the proof.

Corollary 3.2 Under the condition of Theorem 3.2, the solution $(u_{\mu}^{n}, p_{\mu}^{n}, T_{\mu}^{n}) \in X_{\mu} \times M_{\mu} \times W_{\mu}$ defined by (3.7) satisfies

$$\begin{aligned} \left\| \nabla \left(u - u_{\mu}^{n} \right) \right\|_{0} + \left\| p - p_{\mu}^{n} \right\|_{0} + \left\| \nabla \left(T - T_{\mu}^{n} \right) \right\|_{0} \\ \leq c \mu^{s} + C_{1} \alpha_{1} + C_{2} \alpha_{2} + C_{3} \left\| \nabla \left(u_{\mu}^{n} - u_{\mu}^{n-1} \right) \right\|_{0}. \end{aligned}$$

Remark 3.3 Corollary 3.2 shows that to ensure a good approximation, the variational multiscale Oseen iterations should converge sufficiently. Moreover, the estimator suggests the choice of the stabilization parameters $\alpha_1 = O(\mu^s)$ and $\alpha_2 = O(\mu^s)$ which ensure optimal convergence.

4 Two-grid variational multiscale method

Combining two-grid discretization strategy with the variational multiscale Oseen iterative method presented in the previous section, we develop the two-grid variational multiscale Oseen iterative method as follows.

Step 1. Find a coarse grid iterative solution $(u_H^m, p_H^m, T_H^m) \in X_H \times M_H \times W_H$ such that

$$(\Pr + \alpha_1)a(u_H^m, v_H) + c(u_H^{m-1}, u_H^m, v_H) + b(v_H, p_H^m) - b(u_H^m, q_H) = \Pr \operatorname{Ra}(T_H^m \zeta, v_H) + (\gamma_1, v_H) + \alpha_1(\nabla \Pi_H^1 u_H^{m-1}, \nabla v_H), (k + \alpha_2)\bar{a}(T_H^m, S_H) + \bar{c}(u_H^{m-1}, T_H^m, S_H) = (\gamma_2, S_H) + \alpha_2(\nabla \Pi_H^2 T_H^{m-1}, \nabla S_H),$$

for all $(v_H, q_H, S_H) \in X_H \times M_H \times W_H$, n = 1, 2, ..., m, and $u_H^0 = 0$, $T_H^0 = 0$.

Step 2. Find a fine grid solution $(u_{mh}, p_{mh}, T_{mh}) \in X_h \times M_h \times W_h$ such that for all $(v_h, q_h, S_h) \in X_h \times M_h \times W_h$

$$\Pr a(u_{mh}, v_h) + c(u_H^m, u_{mh}, v_h) + c(u_{mh}, u_H^m, v_h) + b(v_h, p_{mh}) - b(u_{mh}, q_h) = \Pr \operatorname{Ra}(T_{mh}\zeta, v_h) + (\gamma_1, v_h) + c(u_H^m, u_H^m, v_h), k\bar{a}(T_{mh}, S_h) + \bar{c}(u_H^m, T_{mh}, S_h) + \bar{c}(u_{mh}, T_H^m, S_h) = (\gamma_2, S_h) + \bar{c}(u_H^m, T_H^m, S_h).$$
(4.1)

Remark 4.1 In our two-grid method, stabilization is only employed for the coarse grid nonlinear problem, while the fine grid linear problem is a standard one-step Newton linearization. Therefore, Pr, Ra, *k* should be in the range such that the standard linear problem on the fine grid is nonsingular and solvable.

Remark 4.2 The numerical algorithm (4.1) is a full linearization problem based on the Newton iterative scheme. Similarly, based on the Oseen iterative scheme, we can develop the following partial linearization problem: Find a fine grid solution $(u_{mh}, p_{mh}, T_{mh}) \in X_h \times M_h \times W_h$ such that for all $(v_h, q_h, S_h) \in X_h \times M_h \times W_h$

$$\begin{cases} \Pr a(u_{mh}, v_h) + c(u_H^m, u_{mh}, v_h) + b(v_h, p_{mh}) - b(u_{mh}, q_h) \\ = \Pr \operatorname{Ra}(T_{mh}\zeta, v_h) + (\gamma_1, v_h), \\ k\bar{a}(T_{mh}, S_h) + \bar{c}(u_H^m, T_{mh}, S_h) = (\gamma_2, S_h). \end{cases}$$
(4.2)

Theorem 4.1 Assume $(\tilde{u}, \lambda_h, \tilde{T})$ be an approximation of (u, p, T) in $X_h \times M_h \times W_h$, under the conditions of Theorem 3.2 and $\frac{1}{2} \operatorname{Pr} - N_1 A - k^{-1} \operatorname{Pr} \operatorname{Ra} N_2 B > 0$. The solution (u_{mh}, p_{mh}, T_{mh}) defined by scheme (4.1) satisfies

$$\frac{1}{2} \operatorname{Pr} \left\| \nabla(u - u_{mh}) \right\|_{0} \leq C(\beta) \left(\frac{3}{2} \operatorname{Pr} + 2N_{1}A + \operatorname{Pr} \operatorname{Ra} k^{-1}N_{2}B \right) \inf_{\tilde{u} \in X_{h}} \left\| \nabla(u - \tilde{u}) \right\|_{0} + \sqrt{d} \inf_{\lambda_{h} \in M_{h}} \left\| p - \lambda_{h} \right\|_{0} + \left(N_{1} \left\| \nabla(u - u_{H}^{m}) \right\|_{0} + \operatorname{Pr} \operatorname{Ra} k^{-1}N_{2} \left\| \nabla(T - T_{H}^{m}) \right\|_{0} \right) \left\| \nabla(u - u_{H}^{m}) \right\|_{0} + \operatorname{Pr} \operatorname{Ra} k^{-1} (2k + N_{2}A + N_{2} \left\| \nabla(u - u_{H}^{m}) \right\|_{0}) \inf_{\tilde{T} \in W_{h}} \left\| \nabla(T - \tilde{T}) \right\|_{0}, \quad (4.3)$$

$$\|p - p_{mh}\|_{0} \leq \left(1 + \frac{\sqrt{d}}{\beta}\right) \inf_{\lambda_{h} \in M_{h}} \|p - \lambda_{h}\|_{0} + \frac{1}{\beta} (\Pr + 2N_{1}A) \|\nabla(u - u_{mh})\|_{0} + \frac{N_{1}}{\beta} \|\nabla(u - u_{H}^{m})\|_{0}^{2} + \frac{\Pr \operatorname{Ra}}{\beta} \|\nabla(T - T_{mh})\|_{0},$$

$$(4.4)$$

$$\nabla (T - T_{mh}) \|_{0} \leq k^{-1} (2k + N_{2}A + N_{2} \| \nabla (u - u_{H}^{m}) \|_{0}) \inf_{\tilde{T} \in W_{h}} \| \nabla (T - \tilde{T}) \|_{0} + k^{-1} N_{2} B \| \nabla (u - u_{mh}) \|_{0} + k^{-1} N_{2} \| \nabla (u - u_{H}^{m}) \|_{0} \| \nabla (T - T_{H}^{m}) \|_{0}.$$

$$(4.5)$$

Proof Setting $(e_m, \eta_m, \phi_m) = (u - u_{mh}, p - p_{mh}, T - T_{mh})$ and subtracting (4.1) from (2.1), for all $(v_h, q_h, S_h) \in X_h \times M_h \times W_h$ we have

$$\begin{cases} \Pr(\nabla e_m, \nabla v_h) + c(u, u, v_h) - c(u_H^m, u_{mh}, v_h) - c(u_{mh}, u_H^m, v_h) - (\nabla \cdot v_h, p - p_{mh}) \\ + (\nabla \cdot e_m, q_h) = \Pr \operatorname{Ra}(\phi_m \zeta, v_h) - c(u_H^m, u_H^m, v_h), \\ k(\nabla \phi_m, \nabla S_h) + \bar{c}(u, T, S_h) - \bar{c}(u_H^m, T_{mh}, S_h) - \bar{c}(u_{mh}, T_H^m, S_h) \\ = -\bar{c}(u_H^m, T_H^m, S_h). \end{cases}$$
(4.6)

The remainder of the proof follows that of Theorem 3.2. Let $(\tilde{u}, \lambda_h, \tilde{T})$ be an approximation of (u, p, T). By limiting $v_h \in V_h$, splitting $e_m = \chi_1 - \varphi_h$ with $\chi_1 = u - \tilde{u}$, $\varphi_h = u_{mh} - \tilde{u}$, and splitting $\phi_m = \chi_2 - \psi_h$ with $\chi_2 = T - \tilde{T}$, $\psi_h = T_{mh} - \tilde{T}$, the trilinear terms transform into

$$c(u, u, v_h) - c(u_H^m, u_{mh}, v_h) - c(u_{mh}, u_H^m, v_h) + c(u_H^m, u_H^m, v_h)$$

= $c((u - u_H^m) + u_H^m, u, v_h) - c(u_H^m, u_{mh}, v_h) + c(u - u_{mh}, u_H^m, v_h) - c(u - u_H^m, u_H^m, v_h)$
= $c(e_m, u_H^m, v_h) + c(u_H^m, e_m, v_h) + c(u - u_H^m, u - u_H^m, v_h).$ (4.7)

In the same way, one finds

$$\bar{c}(u, T, S_h) - \bar{c}(u_H^m, T_{mh}, S_h) - \bar{c}(u_{mh}, T_H^m, S_h) + \bar{c}(u_H^m, T_H^m, S_h)$$

= $\bar{c}(u, \phi_m, S_h) - \bar{c}(u - u_H^m, \phi_m, S_h) + \bar{c}(e_m, T_H^m, S_h) + \bar{c}(u - u_H^m, T - T_H^m, S_h).$ (4.8)

Inserting (4.7) and (4.8) into (4.6) we get

$$\begin{cases} \Pr(\nabla e_m, \nabla v_h) + c(e_m, u_H^m, v_h) + c(u_H^m, e_m, v_h) + c(u - u_H^m, u - u_H^m, v_h) \\ - (\nabla \cdot v_h, p - p_{mh}) + (\nabla \cdot e_m, q_h) = \Pr \operatorname{Ra}(\phi_m \zeta, v_h), \\ k(\nabla \phi_m, \nabla S_h) + \bar{c}(u, \phi_m, S_h) - \bar{c}(u - u_H^m, \phi_m, S_h) + \bar{c}(e_m, T_H^m, S_h) \\ + \bar{c}(u - u_H^m, T - T_H^m, S_h) = 0. \end{cases}$$
(4.9)

Setting $S_h = \psi_h$, the second equation of (4.9) can be written as

$$k(\nabla \psi_h, \nabla \psi_h)$$

$$= k(\nabla \chi_2, \nabla \psi_h) + \bar{c}(u, \phi_m, \psi_h) - \bar{c}(u - u_H^m, \phi_m, \psi_h)$$

$$+ \bar{c}(e_m, T_H^m, \psi_h) + \bar{c}(u - u_H^m, T - T_H^m, \psi_h)$$

$$= k(\nabla \chi_2, \nabla \psi_h) + \bar{c}(u, \chi_2, \psi_h) - \bar{c}(u - u_H^m, \chi_2, \psi_h)$$

$$+ \bar{c}(e_m, T_H^m, \psi_h) + \bar{c}(u - u_H^m, T - T_H^m, \psi_h),$$

as a consequence we derive that

$$k \| \nabla \psi_{h} \|_{0} \leq (k + N_{2} \| \nabla u \|_{0} + N_{2} \| \nabla (u - u_{H}^{m}) \|_{0}) \| \nabla \chi_{2} \|_{0} + N_{2} \| \nabla T_{H}^{m} \|_{0} \| \nabla e_{m} \|_{0}$$

+ $N_{2} \| \nabla (u - u_{H}^{m}) \|_{0} \| \nabla (T - T_{H}^{m}) \|_{0}$
$$\leq (k + N_{2}A + N_{2} \| \nabla (u - u_{H}^{m}) \|_{0}) \| \nabla \chi_{2} \|_{0} + N_{2}B \| \nabla e_{m} \|_{0}$$

+ $N_{2} \| \nabla (u - u_{H}^{m}) \|_{0} \| \nabla (T - T_{H}^{m}) \|_{0}.$ (4.10)

Applying the triangle inequality, and taking the infimum over W_h , we obtain the proof (4.5).

Now, we present the error for $u - u_{mh}$. Setting $v_h \in V_h$ and $q_h = 0$, the first equation of (4.6) can be written as

$$Pr(\nabla \varphi_h, \nabla v_h) = Pr(\nabla \chi_1, \nabla v_h) + c(e_m, u_H^m, v_h) + c(u_H^m, e_m, v_h)$$

+ $c(u - u_H^m, u - u_H^m, v_h) - (\nabla \cdot v_h, p - \lambda_h) - Pr \operatorname{Ra}(\phi_m \zeta, v_h).$

Taking $v_h = \varphi_h$, which leads to

$$\begin{aligned} \Pr(\nabla\varphi_h, \nabla\varphi_h) &= \Pr(\nabla\chi_1, \nabla\varphi_h) + c\big(e_m, u_H^m, \varphi_h\big) + c\big(u_H^m, \chi_1, \varphi_h\big) \\ &+ c\big(u - u_H^m, u - u_H^m, \varphi_h\big) - (\nabla \cdot \varphi_h, p - \lambda_h) - \Pr \operatorname{Ra}(\phi_m \zeta, \varphi_h). \end{aligned}$$

Using Theorem 3.1 we obtain

$$\Pr \|\nabla \varphi_{h}\|_{0} \leq \left(\Pr + 2N_{1} \|\nabla u_{H}^{m}\|_{0}\right) \|\nabla \chi_{1}\|_{0} + N_{1} \|\nabla (u - u_{H}^{m})\|_{0}^{2} + \Pr \operatorname{Ra} \|\nabla \phi_{m}\|_{0} + \sqrt{d} \|p - \lambda_{h}\|_{0} + N_{1} \|\nabla u_{H}^{m}\|_{0} \|\nabla \varphi_{h}\|_{0} \leq \left(\Pr + 2N_{1}A\right) \|\nabla \chi_{1}\|_{0} + N_{1} \|\nabla (u - u_{H}^{m})\|_{0}^{2} + \Pr \operatorname{Ra} \|\nabla \phi_{m}\|_{0} + \sqrt{d} \|p - \lambda_{h}\|_{0} + N_{1}A \|\nabla \varphi_{h}\|_{0}.$$
(4.11)

Inserting (4.5) into (4.11) to derive that

$$\begin{aligned} \Pr \|\nabla \varphi_{h}\|_{0} &\leq (\Pr + 2N_{1}A) \|\nabla \chi_{1}\|_{0} + N_{1} \|\nabla (u - u_{H}^{m})\|_{0}^{2} + \sqrt{d} \|p - \lambda_{h}\|_{0} + N_{1}A \|\nabla \varphi_{h}\|_{0} \\ &+ \Pr \operatorname{Ra} \Big[k^{-1} (2k + N_{2}A + N_{2} \|\nabla (u - u_{H}^{m})\|_{0}) \inf_{\tilde{T} \in W_{h}} \|\nabla (T - \tilde{T})\|_{0} \\ &+ k^{-1}N_{2}B \|\nabla (u - u_{mh})\|_{0} + k^{-1}N_{2} \|\nabla (u - u_{H}^{m})\|_{0} \|\nabla (T - T_{H}^{m})\|_{0} \Big] \\ &\leq (\Pr + 2N_{1}A + k^{-1}\Pr \operatorname{Ra} N_{2}B) \|\nabla \chi_{1}\|_{0} + N_{1} \|\nabla (u - u_{H}^{m})\|_{0}^{2} + \sqrt{d} \|p - \lambda_{h}\|_{0} \\ &+ (N_{1}A + k^{-1}\Pr \operatorname{Ra} N_{2}B) \|\nabla \varphi_{h}\|_{0} \\ &+ k^{-1}\Pr \operatorname{Ra} N_{2} \|\nabla (u - u_{H}^{m})\|_{0} \|\nabla (T - T_{H}^{m})\|_{0} \\ &+ k^{-1}\Pr \operatorname{Ra} (2k + N_{2}A + N_{2} \|\nabla (u - u_{H}^{m})\|_{0}) \inf_{\tilde{T} \in W_{h}} \|\nabla (T - \tilde{T})\|_{0}. \end{aligned}$$

Under the assumption of Theorem 4.1 one finds

$$\frac{1}{2} \Pr \|\nabla \varphi_h\|_0 \le \left(\Pr + 2N_1A + k^{-1} \Pr \operatorname{Ra} N_2B\right) \|\nabla \chi_1\|_0 + N_1 \|\nabla (u - u_H^m)\|_0^2 + \sqrt{d} \|p - \lambda_h\|_0 + k^{-1} \Pr \operatorname{Ra} N_2 \|\nabla (u - u_H^m)\|_0 \|\nabla (T - T_H^m)\|_0 + k^{-1} \Pr \operatorname{Ra}(2k + N_2A + N_2 \|\nabla (u - u_H^m)\|_0) \inf_{\tilde{T} \in W_h} \|\nabla (T - \tilde{T})\|_0.$$

Thanks to the triangle inequality and (2.7), and taking the infimum over $(\tilde{u}, \lambda_h) \in X_h \times M_h$, we finish the proof of (4.3).

Finally, we take $q_h = 0$ in the first equation of (4.6) to derive that

$$(\nabla \cdot v_h, p_{mh} - \lambda_h)$$

$$= (\nabla \cdot v_h, p - \lambda_h) - \Pr(\nabla e_m, \nabla v_h) - c(e_m, u_H^m, v_h) - c(u_H^m, e_m, v_h)$$

$$- c(u - u_H^m, u - u_H^m, v_h) + \Pr \operatorname{Ra}(\phi_m \zeta, v_h)$$

$$\leq \left[\sqrt{d} \| p - \lambda_h \|_0 + (\Pr + 2N_1 \| \nabla u_H^m \|_0) \| \nabla e_m \|_0 + N_1 \| \nabla (u - u_H^m) \|_0^2$$

$$+ \Pr \operatorname{Ra} \| \nabla \phi_h \|_0 \right] \| \nabla v_h \|_0,$$

which combining (2.6) with Theorem 3.2 yields

$$\beta \|p_{mh} - \lambda_h\|_0 \le \sqrt{d} \|p - \lambda_h\|_0 + (\Pr + 2N_1 A) \|\nabla e_m\|_0 + N_1 \|\nabla (u - u_H^m)\|_0^2 + \Pr \operatorname{Ra} \|\nabla \phi_h\|_0,$$

by using $\|p - p_{mh}\|_0 \le \|p_{mh} - \lambda_h\|_0 + \|p - \lambda_h\|_0$ we have

$$\|p - p_{mh}\|_{0} \leq \left(1 + \frac{\sqrt{d}}{\beta}\right) \|p - \lambda_{h}\|_{0} + \frac{1}{\beta} (\Pr + 2N_{1}A) \|\nabla(u - u_{mh})\|_{0} + \frac{N_{1}}{\beta} \|\nabla(u - u_{H}^{m})\|_{0}^{2} + \frac{\Pr \operatorname{Ra}}{\beta} \|\nabla(T - T_{mh})\|_{0}.$$

We derive the error estimation (4.5) by taking the infimum over $\lambda_h \in M_h$.

5 Numerical experiments

In order to gain insights on the established theoretical results of one-grid and two-grid variational multiscale methods for the natural convection problem in Sections 3 and 4, we present two numerical examples in this section. Our main interests are to verify the orders of convergence and compare the performances of different numerical schemes. For comparison, the numerical results of the standard Galerkin FEM (2.8) are also provided. In all experiments, the steady natural convection problem is defined on a convex domain $\Omega = [0,1] \times [0,1]$ and the variational multiscale parameters $\alpha_1 = \alpha_2 = 0.1h^2$. The mesh consists of triangular elements that are obtained by dividing Ω into subsquares of equal size and then drawing the diagonal in each sub-square. The software FreeFEM++, developed by Hecht *et al.* [23], is used in our experiments and the linear solver UMFPACK is adopted in our program. All numerical experiments reported in this paper were performed on a PC with a core process (i5-3210M) and 4GB of random access memory.

5.1 An analytical solution: convergence validation

In this test our purpose is to verify the theoretical results of Theorems 2.3, 3.2, and 4.1 which have been established in Sections 3 and 4, respectively. The model parameters Pr, Ra, and *k* are simply set to 1, the functions γ_1 and γ_2 are given by the following exact solution:

$$\begin{cases} u_1 = 10x^2(x-1)^2y(y-1)(2y-1), \\ u_2 = -10x(x-1)(2x-1)y^2(y-1)^2, \\ p = 10(2x-1)(2y-1), \\ T = 10x^2(x-1)^2y(y-1)(2y-1) - 10x(x-1)(2x-1)y^2(y-1)^2, \end{cases}$$

where the components of u are denoted by u_1 and u_2 for convenience.

In order to show the prominent features of the two-grid variational multiscale Oseen iterative scheme (4.1), we compare the numerical results of one-grid variational multiscale scheme (3.7) and the standard Galerkin FEM (2.8). We consider the second order discretization, where the Taylor-Hood element is applied to approximate the velocity and pressure; the piecewise quadratic element is used to simulate the temperature. In this case, the orders of convergence of velocity in H^1 norm, pressure in L^2 norm, and temperature in H^1 norm should be 2. In the following test, we will verify these orders of convergence. $\|\cdot\|_0$ denotes the L^2 -norm and $\|\nabla \cdot\|_0$ is the H^1 -semi-norm.

In Table 1, we show the relative errors of the standard Galerkin FEM (2.8) between the exact solution and the numerical approximations. As observed from Table 1, the contraction factors of errors $\frac{\|\nabla(u-u_h)\|_0}{\|\nabla u\|_0}$, $\frac{\|\nabla(T-T_h)\|_0}{\|\nabla T\|_0}$, and $\frac{\|p-p_h\|_0}{\|p\|_0}$ become smaller and smaller as the mesh is refined, and the orders of these relative errors are around $\frac{1}{4}$ as the mesh is refined once.

In contrast, we show the errors between the exact solution and the numerical solutions of both one-grid and two-grid variational multiscale Oseen iterative schemes (2.8) and (4.1) in Tables 2-3, respectively. We observe almost no differences when comparing the errors in Tables 2-3 with the same mesh sizes $h = \frac{1}{4}, \frac{1}{9}, \frac{1}{16}, \frac{1}{25}, \frac{1}{36}, \frac{1}{49}$ with $H = \sqrt{h}$. From these data we can see that the one-grid and two-grid variational multiscale schemes retain the same order of accuracy with second order discretization as the standard Galerkin FEM.

Finally, we compare the CPU time among different algorithms in Tables 1-3. From these tables, we can see that the two-grid variational multiscale Oseen iterative method (4.1)

	$\ \nabla(u, u,)\ _{2}$		n n. .		UV(T T .) U		
1/h	<u>∥∇(u−u_h)∥₀</u> ∥∇u∥₀	Rate	<u> P-Ph 0</u> P 0	Rate	$\frac{\ \nabla(T-T_h)\ _{0}}{\ \nabla T\ _{0}}$	Rate	CPU(S)
4	0.166184	-	0.0485766	-	0.0962482	-	0.066
9	0.0354715	1.90444	0.00956673	2.00369	0.0211698	1.86743	0.305
16	0.0114207	1.96978	0.00302598	2.00057	0.00682614	1.96713	0.977
25	0.00470301	1.98792	0.00123938	2.00012	0.0028114	1.98789	2.503
36	0.00227273	1.99434	0.000597686	2.00003	0.00135839	1.99453	5.081
49	0.00122789	1.99702	0.000322615	2.00001	0.000733861	1.99718	9.981

Table 1 The errors of standard Galerkin FEM (2.8) for the steady natural convection equations

Table 2 The errors of variational multiscale method (3.7) for the steady natural convection equations

1/h	$\frac{\ \nabla(u-u_h)\ _0}{\ \nabla u\ _0}$	Rate	<u> p-p_h o</u> p o	Rate	$\frac{\ \nabla(\tau-\tau_h)\ _0}{\ \nabla\tau\ _0}$	Rate	CPU(S)
4	0.166197	-	0.0485818	-	0.0962482	-	0.08
9	0.0354721	1.90451	0.009566804	2.0038	0.0211698	1.86743	0.283
16	0.0114203	1.96981	0.00302599	2.00059	0.00682614	1.96713	0.901
25	0.00470303	1.98793	0.00123938	2.00012	0.0028114	1.98789	2.207
36	0.00227273	1.99434	0.000597686	2.00003	0.00135839	1.99453	4.682
49	0.00122789	1.99703	0.000322615	2.00001	0.000733861	1.99718	8.804

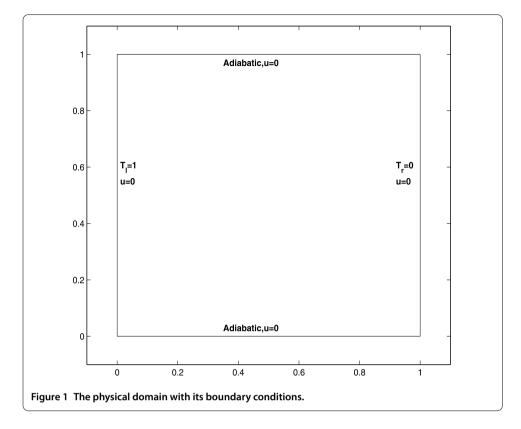
Table 3 The errors of two-grid variational multiscale method (4.1) for the steady natural convection equations

1 <i>/H</i>	1 <i>/h</i>	<u>∥⊽(u–u_h)∥o</u> ∥⊽u∥o	Rate	<u> p-p_h o</u> p o	Rate	$\frac{\ \nabla(\tau-\tau_h)\ _0}{\ \nabla\tau\ _0}$	Rate	CPU(S)
2	4	0.166184	-	0.0485766	-	0.0962505	-	0.044
3	9	0.0354715	1.90444	0.00956675	2.00369	0.0211715	1.86736	0.143
4	16	0.0114202	1.96978	0.00302598	2.00057	0.00682667	1.96713	0.393
5	25	0.00470301	1.98792	0.00123938	2.00012	0.00281136	1.98788	0.915
6	36	0.00227273	1.99434	0.000597686	2.00003	0.0013585	1.99451	1.834
7	49	0.00122789	1.99702	0.000322615	2.00001	0.000733929	1.99716	3.390

uses less time than the numerical schemes (2.8) and (3.7). From the above tables, we can see that the two-grid variational multiscale Oseen iterative method shows a good performance for the steady natural convection equations due to this scheme not only keeping a good accuracy but also taking the least computational cost.

5.2 Thermal driven cavity problem

The problem of thermal driven cavity is used as a suitable benchmark for testing the natural convection problem in the literature. The simplicity of the geometry and the clear boundary conditions make this test attractive. The domain consists of a square cavity with differentially heated vertical walls where the right and left walls are kept at T_r and T_l , respectively, with $T_r > T_l$. The remaining walls are insulated and there is no heat transfer through them. The boundary conditions are no-slip boundary conditions for the velocity at four walls (u = 0) and Dirichlet boundary conditions for the temperature at vertical walls. As the horizontal walls are adiabatic, we employ $\frac{\partial T}{\partial n} = 0$. Figure 1 shows the physical domain of the thermal driven cavity flow problem. In this test, we follow the parameters set by Cibik and Kaya in [5] and take k = 1, b = 0, $T_l = 0$, and $T_r = 1$. While we consider the air as the cavity filling fluid in our model, we take the fixed value Pr = 0.71. We perform our computations for a Rayleigh number varying from 10^3 to 10^5 . The performance of the two-grid variational multiscale method (4.1) is compared with the famous benchmark so-



lution of [24] and some other authors such as Cibik and Kaya [5], Manzari [8], and Wan *et al.* [25]. We also present the results of the standard Galekrkin FEM (2.8) where we keep the same mesh sizes for the two-grid variational multiscale method (4.1) and the one-grid variational multiscale method (3.7). Numerical simulations are obtained on the uniform grid 64 × 64. The mesh sizes of two-grid algorithms are $H = \frac{1}{8}$ and $h = \frac{1}{64}$.

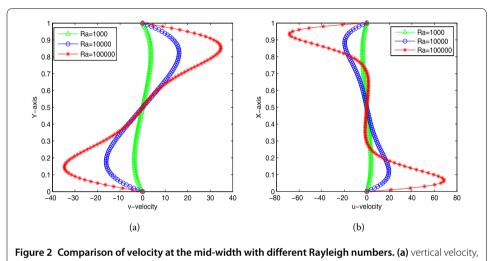
We start our illustrations by giving peak values of the vertical velocity at y = 0.5 and the horizontal velocity at x = 0.5. Table 4 summarizes the maximum vertical velocity values at mid-height and at mid-width for different Rayleigh numbers. We use SGFEM, OGVMM, TGVMM to denote standard Galerkin FEM, one-grid, and two-grid variational multiscale methods, respectively. For quantitative assessment, we include those velocity values obtained by [5, 8, 24, 25]. As can be observed, as the Rayleigh number takes values 10^3 to 10^5 , the results of two-grid variational multiscale Oseen iterative method are in excellent agreement with the benchmark data even at coarser grid $H = \frac{1}{9}$.

Next, we present the vertical and horizontal velocity at the mid-height and mid-width in Figure 2. It is obvious that as the Rayleigh numbers increase, the differences in the profiles provided in Figure 2 are getting larger. These profiles are also comparable with a similar one in [5, 25]. Combining with Table 4, we can see that the two-grid variational multiscale Oseen iterative method is in good agreement with [5, 8, 24, 25].

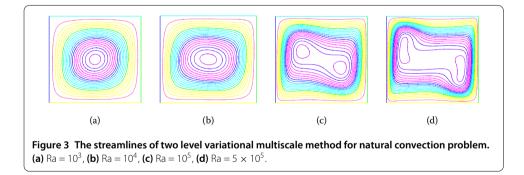
Finally, we show the isotherms and streamlines of natural convection problem with the two-grid variational multiscale Oseen iterative scheme (4.1) at different Rayleigh numbers. We present these patterns in Figures 3 and 4. It is clear from the streamline pattern that, as the Rayleigh number increases, the circular vortex at the cavity center begins to deform into an ellipse and then breaks up into two vortices tending to approach to the corners of differentially heated sides of the cavity. Therefore, we can conclude that the flow is faster

	SGFEM	OGVMM	TGVMM	Ref. [8]	Ref. [5]	Ref. [24]	Ref. [25]
$Ra = 10^{3}$							
x = 0.5	3.6487	3.64869	3.64902	3.68	-	3.65	3.489
y = 0.5	3.69729	3.69777	3.69732	3.73	-	3.70	3.686
$Ra = 10^{4}$							
x = 0.5	16.18	16.1815	16.1928	16.10	15.90	16.18	16.122
y = 0.5	19.6244	19.6317	19.6381	19.90	19.91	19.51	19.79
$Ra = 10^{5}$							
x = 0.5	34.7186	34.8201	34.7183	34.00	33.51	34.81	33.39
y = 0.5	68.4705	68.5433	68.5738	70.00	70.60	68.22	70.63

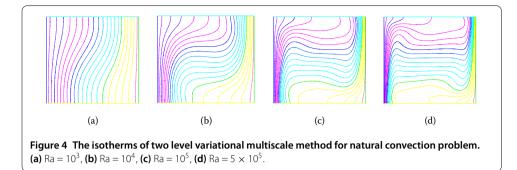
Table 4 Comparisons of maximum velocity at y = 0.5 and x = 0.5 with different methods $(h = \frac{1}{64}, H = \frac{1}{8})$



(b) horizontal velocity.



as the thermal convection is concentrated. With the increase of Rayleigh numbers, the parallel behavior of temperature isolines is distorted as these lines seem to have a flat behavior in the central part of the region. Near the sides of the cavity, isolines tend to be vertical only. The temperature slopes with $Ra = 5 \times 10^5$ at the corners of the differentially heated sides are more immersed than the case of lower Rayleigh number. We note that these graphics are also perfectly comparable with the ones given in the investigations of [5, 8, 24, 25]. Both the data and the graphics show the efficiency and effectiveness of the two-grid variational multiscale method.



Competing interests

The authors declare that no conflict of competing interests exists.

Authors' contributions

XSM carried out the main theorem and checked this paper, ZZT wrote this article. XSM, ZZT, and TZ read and approved the final manuscript.

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