



# Internal structure of two alpine rock glaciers investigated by quasi-3-D electrical resistivity imaging

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**Abstract.** Interactions between different formative processes are reflected in the internal structure of rock glaciers. Therefore, the detection of subsurface conditions can help to enhance our understanding of landform development. For an assessment of subsurface conditions, we present an analysis of the spatial variability of active layer thickness, ground ice content and frost table topography for two different rock glaciers in the Eastern Swiss Alps by means of quasi-3-D electrical resistivity imaging (ERI). This approach enables an extensive mapping of subsurface structures and a spatial overlay between site-specific surface and subsurface characteristics. At Nair rock glacier, we discovered a gradual descent of the frost table in a downslope direction and a constant decrease of ice content which follows the observed surface topography. This is attributed to ice formation by re-freezing meltwater from an embedded snow bank or from a subsurface ice patch which reshapes the permafrost layer. The heterogeneous ground ice distribution at Uertsch rock glacier indicates that multiple processes on different time domains were involved in the development. Resistivity values which represent frozen conditions vary within a wide range and indicate a successive formation which includes several advances, past glacial overrides and creep processes on the rock glacier surface. In combination with the observed topography, quasi-3-D ERI enables us to delimit areas of extensive and compressive flow in close proximity. Excellent data quality was provided by a good coupling of electrodes to the ground in the pebbly material of the investigated rock glaciers. Results show the value of the quasi-3-D ERI approach but advise the application of complementary geophysical methods for interpreting the results.

## 1 Introduction

In areas of sporadic and discontinuous permafrost, subsurface conditions (e.g. thickness of the active layer, frost table topography, ice content) can be highly heterogeneous within small distances and can vary within single landform units (Schneider et al., 2013; Langston et al., 2011; Scapozza et al., 2011; Kneisel, 2010a). This is due to complex interactions between small-scale surface conditions (e.g. grain size composition, snow cover distribution), topographical attributes (e.g. aspect, slope) and characteristics of the contributing area (e.g. source of debris, extent of root zone) (see Monnier et al., 2013; Luetschg et al., 2004; Hanson and Hoelzle, 2004; Harris and Pedersen, 1998) which influence the local ground thermal regime during landform formation (Otto et al., 2012; Lambiel and Pieracci, 2008). For a better understanding of the past and future development of periglacial landforms in areas of sporadic and discontinuous permafrost, which are particularly sensitive to climate change (Schneider et al., 2012; Harris et al., 2009), an enhanced knowledge of these interactions is needed. The detection and mapping of spatial variations within the internal structure can be seen as a first step towards an identification of linkages between surface and subsurface processes, which are key drivers in landform development (Kääb et al., 2007; Haeblerli et al., 2006). This spatial information can be valuable in combination with thermal modelling or process modelling approaches (Frehner et al., 2015; Scherler et al., 2013; Luetschg et al., 2008) which are, due to the heterogeneous subsurface conditions in alpine environments, often reduced to one or two dimensions. Hence, a detailed knowledge of three-dimensional subsurface conditions can support the interpretation of results from such models.

Geophysical techniques such as electrical resistivity tomography (ERT), seismic refraction tomography (SRT) or ground-penetrating radar (GPR) are widely used today and provide a multi-dimensional investigation of subsurface conditions in permafrost environments and corresponding landforms. For rock glaciers and similar periglacial landforms, geophysical investigations enable an assessment of the subsurface material composition and to distinguish between frozen and unfrozen areas (e.g. Schneider et al., 2013; Musil et al., 2006). This information can be used to investigate inferences with creep velocities (Hausmann et al., 2012; Kneisel and Kääh, 2007) or to reveal glacier–permafrost interactions during the development of rock glaciers (see Dusik et al., 2015; Krainer et al., 2012; Ribolini et al., 2010).

In contrast to those numerous one- or two-dimensional field studies, in which vertical and lateral variations of resistivity distribution could be detected, three-dimensional investigations are sparse in the field of periglacial geomorphology. Approaches were presented by Scapozza and Lai-gre (2014) and Langston et al. (2011), who graphically combined results from 2-D ERT surveys to three-dimensional fence diagrams. However, these approaches do not take into account the actual three-dimensionality of the subsurface resistivity distribution and the so-called “3-D effects”, which result from small-scale heterogeneities (Loke et al., 2013). This is achieved by running a 3-D inversion on a data set consisting of multiple intersecting 2-D data sets (“quasi-3-D” approach), which enables a horizontal mapping of resistivity variations, an assessment of the geometry of the detected structures and consequently a more realistic characterisation of three-dimensional subsurface conditions (Kneisel et al., 2014; Rödder and Kneisel, 2012).

The objective of this paper is to describe the internal structure of two morphologically different rock glaciers with regard to frost table variations, active layer thickness (ALT), ice content and ground ice genesis. We therefore analyse the three-dimensional subsurface resistivity distribution which is modelled by quasi-3-D electrical resistivity imaging (ERI) and the results from additionally performed comparative surveys of 2-D ERT and 2-D SRT. Ground truthing is achieved by borehole temperature measurements. We present a qualitative assessment of ground ice content which we presume is sufficient for interpreting the results regarding rock glacier development. Quantitative assessments, as presented e.g. by Pellet et al. (2016), Hausmann et al. (2012) or Hauck et al. (2011), would additionally require a spatial assessment of porosity.

## 2 Study sites

The investigated rock glaciers are located in the Eastern Swiss Alps, an area which is well known for the occurrence of permafrost and numerous rock glaciers. The nearby rock glaciers Murtèl and Muragl probably belong to the best in-

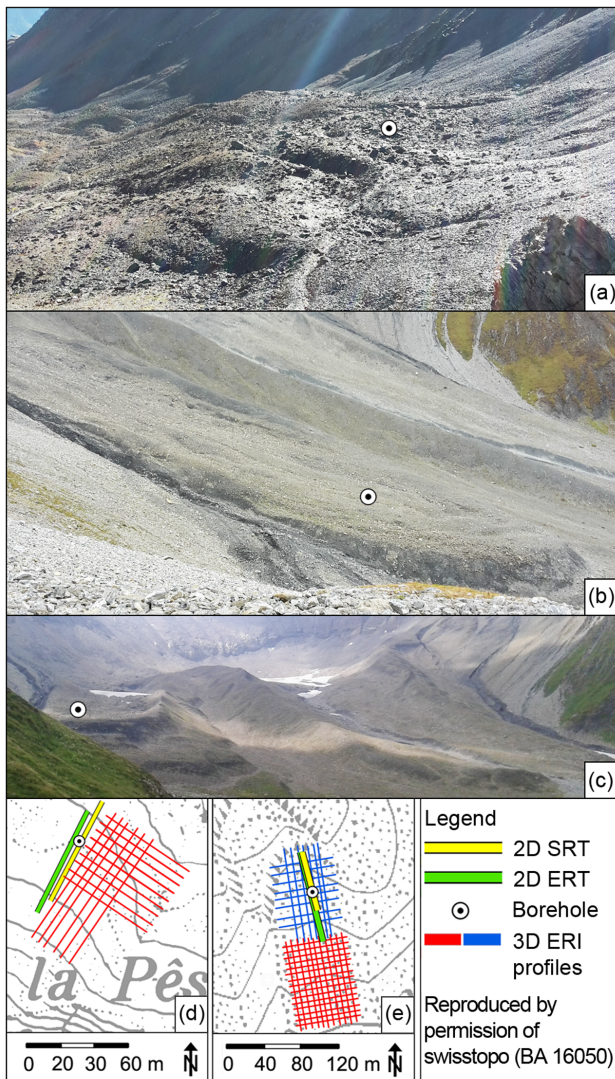
vestigated rock glaciers in the European Alps (e.g. Maurer and Hauck, 2007). For the presented study, two landforms described as “pebbly rock glaciers” according to the relatively small grain size (dominant clast size < 20 cm) of the surface debris (Matsuoka et al., 2005) were chosen. The distance between the two sites is ca. 12 km. In September 2014, one borehole with a depth of 10 m was drilled at Uertsch rock glacier and one borehole with the same depth was drilled at Nair rock glacier. Both boreholes are instrumented with thermistor strings with 15 temperature sensors. The temperature sensors are located at the ground surface and 0.2, 0.4, 0.8, 1.2, 1.6, 2, 3, 4, 5, 6, 7, 8, 9 and 10 m below the surface. As a destructive drilling method was applied, no borehole cores are available. Accuracy of the installed sensor type (Dallas, Geoprecision) is  $\pm 0.25$  °C and a temporal resolution of 1 h is provided.

### 2.1 Nair rock glacier

Nair rock glacier (46°31' N, 9°47' E; ca. 2845–2820 m a.s.l.; Fig. 1a) is located at the southern slope of a small high mountain valley near the city of Celerina, Upper Engadine. It is part of a widespread rock glacier assembly at the valley slope and roots below a steep talus cone (Figs. 1a, 2a). It is composed of debris material from the sedimentary rocks of the Piz Nair summit area (mainly schist and marlstone). The Alpine Permafrost Index Map (Boeckli et al., 2012) describes the spatial distribution of permafrost in the area of the rock glacier as “permafrost in nearly all conditions”. The investigated rock glacier consists of several adjacent lobes, but our study concentrates on the uppermost eastern lobe, which is about 90 m × 80 m in size. The occurrence of permanently frozen ground within this part of the rock glacier was reported by Ikeda and Matsuoka (2006), who performed a seismic refraction sounding and one 2-D ERT measurement (specified therein as NN12). Their study describes the rock glacier as “active”, but no flow velocity measurements were published. A glaciation of the site during Little Ice Age (LIA) is not indicated by morphological traces but surface ice is displayed on ancient topographical maps from ca. 1917 to 1944 at the position of the present talus cones and at the root zone of the rock glacier (Coaz et al., 1925, 1946).

### 2.2 Uertsch rock glacier

Uertsch rock glacier (46°36' N, 9°51' E; ca. 2570–2434 m a.s.l.; Fig. 1b, c) is located at the head of a north-striking valley near the city of Bergün, ca. 2 km north of Albula Pass. It is tongue-shaped and about 500 m × 100 m in size. It has a marked topography with arcuate ridges contoured by deep furrows (vertical difference ca. 0.5–3 m, Fig. 2d) at the rock glacier snout. A several metres high lateral moraine at the western edge of the rock glacier next to a partly ice-filled depression (80 m × 40 m) at its proximal side indicates that an extensive glaciation existed on the rock



**Figure 1.** Site overview and measurement set-ups: (a) photo of Nair site; (b, c) photos of Uertsch site; (d) quasi-3-D ERI set-up at Nair; (e) quasi-3-D ERI set-up at Uertsch\_01 (blue lines) and Uertsch\_02 (red lines).

glacier (Fig. 2c). Surface ice is displayed on a topographical map from 1878, but pictured there only slightly larger than the extent of the recent ice patch (Coaz and Leuzinger, 1878). A similar lateral moraine is lacking at the eastern edge. Small longitudinal ridges occur in the central part of the rock glacier and several relict lobes in front of the rock glacier indicate a successive formation (Figs. 1c, 2c). On the surface, isolated pioneer plants indicate inactivity. The rock glacier mostly consists of fine-grained schist from the mountain ridge between Piz Üertsch and Piz Blaisun. The rooting zone is part of a wide amphitheatre-like catchment area, where remnant ice from a former glaciation and lateral moraines from the former glacier extent are visible (Figs. 1c, 2c). However, this part is a little cut off from the root zone of

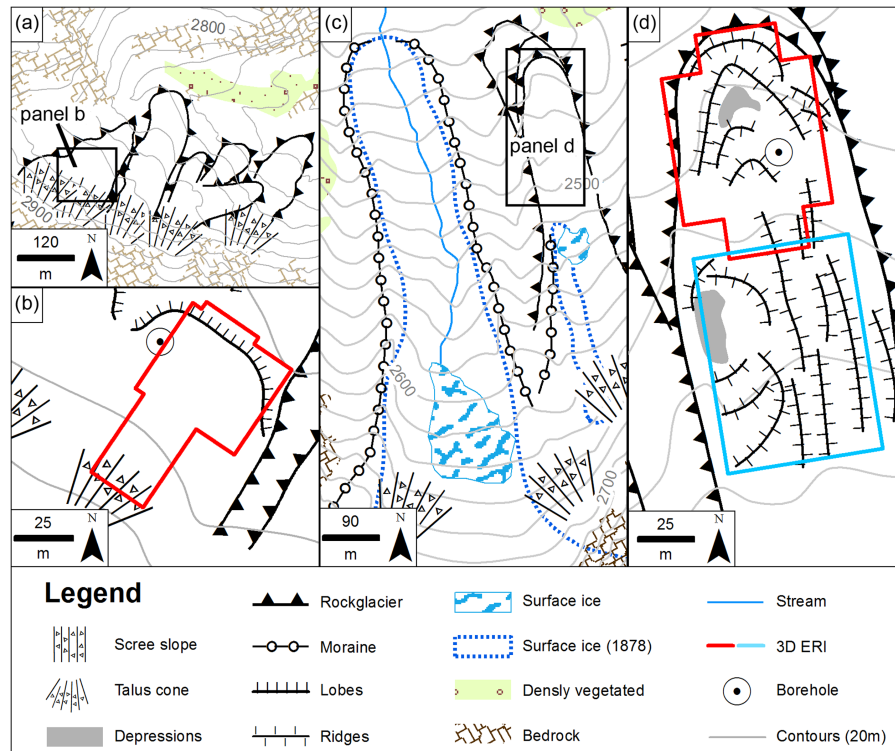
the rock glacier. The Alpine Permafrost Index Map (Boeckli et al., 2012) describes the occurrence of permafrost at the main part of the rock glacier as “permafrost only in very favourable conditions”. Only the area of the rooting zone of the rock glacier is described by the term “permafrost mostly in cold conditions”. The borehole is located in the lower part of the rock glacier, situated at the edge of one of the surface ridges. Some morphometrical attributes (e.g. length, slope aspect, lithology) of the rock glacier were presented by Ikeda and Matsuoka (2006) (specified therein as A8), but no geophysical surveys were published.

### 3 Methods

The application of geophysical measurements for the detection of subsurface conditions is common practice in permafrost research (e.g. Hauck, 2013; Kneisel et al., 2008; Otto and Sass, 2006) and therefore only short descriptions of the basic approaches are given here. As the ranges of resistivity values for frozen and unfrozen conditions are partly overlapping, the application of complementary methods for the detection of frozen subsurface conditions is generally recommended (Schrott and Sass, 2008; Ikeda, 2006).

#### 3.1 Electrical resistivity tomography and quasi-3-D electrical resistivity imaging

Geoelectrical measurements are based on the varying electrical conductivity of different materials (e.g. minerals, sediments, air and water), which are assumed to be heterogeneously distributed within the subsurface. Hence, the detection of potential difference patterns can be used to derive information on the geometry of structural heterogeneities and their electrical properties. The wide range of resistivity values for most loose materials is caused by their porosity, the varying water content and its state of matter. This connection allows us to convert the image of resistivity distribution into an image of subsurface conditions. Resistivity measurements are carried out by injecting direct current into the ground via two current electrodes. Two potential electrodes are then used to measure the resulting voltage difference. The arrangement of these four electrodes is described by the “electrode array”, which determines investigation depth and sensitivity pattern of the measurement. For the quasi-3-D ERI approach (see Kneisel et al., 2014, for more details) data points from a 2-D network of parallel and perpendicular survey lines are merged and treated as one 3-D data set. Each of our 2-D profiles uses 36 electrodes, connected to a multi-electrode resistivity imaging system (Syscal Pro, IRIS Instruments). Inter-line electrode spacings of 2 and 3 m were used for profile lines in  $x$  and  $y$  direction, respectively. Each datum point was measured between two and four times and standard deviation between these reciprocal measurements was saved for quality checks. Further specifications



**Figure 2.** Geomorphological setting: (a, b) Nair and (c, d) Uertsch. Legend adapted from Kneisel et al. (1998).

**Table 1.** Details on quasi-3-D ERI surveys.

	NAIR	UERTSCH_01	UERTSCH_02
Acquisition dates	12–14 August 2014	11–13 September 2014	26–31 July 2015
Number of grid lines	17 (9 X, 8 Y)	17 (9 X, 8 Y)	30 (17 X, 13 Y)
Outline of investigated area	70 m × 105 m	70 m × 105 m	74 m × 105 m
Number of collated 2-D profiles	17	20	60
Array types for 2-D profiles	17 DipDip	17 DipDip + 3 WenSI	30 DipDip + 30 WenSI
Number of data points for inversion	6294 (of max. 6936)	7372 (of max. 7800)	20 523 (of max. 20 880)
Absolute error (iteration)	7.77 (5)	5.85 (5)	8.86 (5)

of the quasi-3-D ERI data sets of this study are summarised in Table 1 and the networks of 2-D lines are presented in Fig. 1d, e. Dipole–dipole (DipDip) electrode array was performed preferably due to its high resolution in the shallow subsurface and the provided time efficiency by our multi-channel device, but also measurements with the more robust Wenner–Schlumberger (WenSI) array were performed at all sites (and partly included into the 3-D data sets) to reach a higher level of reliability. Where no complete rectangular-shaped grid could be set up due to topographical reasons, the model sections are partly blanked out. The measured apparent resistivity data sets were quality checked and bad datum points (standard deviation between reciprocal measurements > 5 %) were deleted manually. The measured 2-D data sets were inverted independently for 2-D interpretation and further quality checks following the procedures proposed by

Loke (2014) were performed. This includes an elimination of datum points with root mean square errors of > 100 % in a trial inversion. The 2-D data sets were merged into one single 3-D file using the software RES2DINVx64 (Geotomo Software). Topography (see Fig. 8) was measured at each electrode using an RTK-GNSS system (Uertsch\_02) or estimated visually in the field (Nair, Uertsch\_01). The estimated topography data sets were corrected afterwards using digital elevation data. Topography was incorporated into the merged 3-D data sets, which were inverted using the software RES3DINVx64 Professional (Geotomo Software). We used the robust inversion scheme (L1-norm) for the smoothness-constrained regularisation, which tends to produce models with sharp boundaries (Loke and Barker, 1996). The optimisation method tries to reduce the absolute difference between the calculated and the measured apparent resistivity



values by adjusting the resistivity of the model blocks. These differences are quantified as a mean absolute misfit error value (absolute error). The inversion continues until acceptable convergence between the calculated and the measured data is reached (see Rödder and Kneisel, 2012, for more details on inversion settings). To investigate model reliability, a resolution matrix approach (Hilbich et al., 2009; Wilkinson et al., 2006; Stummer et al., 2004) was performed on all data sets. This approach provides a measure of the information content of the model cells. It enables an assessment of the independence of the modelled resistivity values from neighbouring cells or inversion settings. We also used the approach to evaluate investigation depth. In RES3DINV, the model resolution values are transferred into index values, which additionally take into account the model discretization (Loke, 2015). We followed the suggested index value of 10 as a lower limit to rate model cells as sufficiently resolved. For the conversion from resistivity values to subsurface conditions, we applied qualitative attributions based on direct observations by Ikeda and Matsuoka (2006) as their study was performed in the same area, as well as appraisals from our own borehole measurements.

### 3.2 Seismic refraction tomography

SRT is a suitable complementary method to geoelectrical investigations as it is based on the independent parameter of seismic *P*-wave velocity (Kneisel et al., 2008). We used SRT to confirm the occurrence of frozen ground and to derive a broad threshold value to distinguish between frozen and unfrozen subsurface conditions (Seppi et al., 2015). On each rock glacier, one SRT profile was performed. The 2-D SRT survey lines were set up next to 2-D ERT survey lines and in close proximity to the boreholes (Fig. 1d, e). Twenty-four geophones were used with an along-line separation of 3 m. We used a Geode Seismograph (Geometrics Inc.) and a sledge hammer as source of the seismic signal. Shot points were located between the geophones at Nair rock glacier and between every second geophone at Uertsch rock glacier. Additionally, offset shots outside the profile lines were performed. We used the software package SeisImager 2-D (Geometrics Inc.) for data processing and analyses. This included a detection of the first onset of the seismic waves on the geophones and a reciprocity check of their travel time between source and receiver location (Geometrics, 2009). A tomographic inversion scheme with an initial model based on a prior time-term inversion was used, as this method is well suited for the assumed heterogenic subsurface conditions (Schrott and Hoffmann, 2008). Surveys of comparative ERT and SRT were performed on 6 September 2015 (Nair) and 27 July 2015 (Uertsch), respectively.

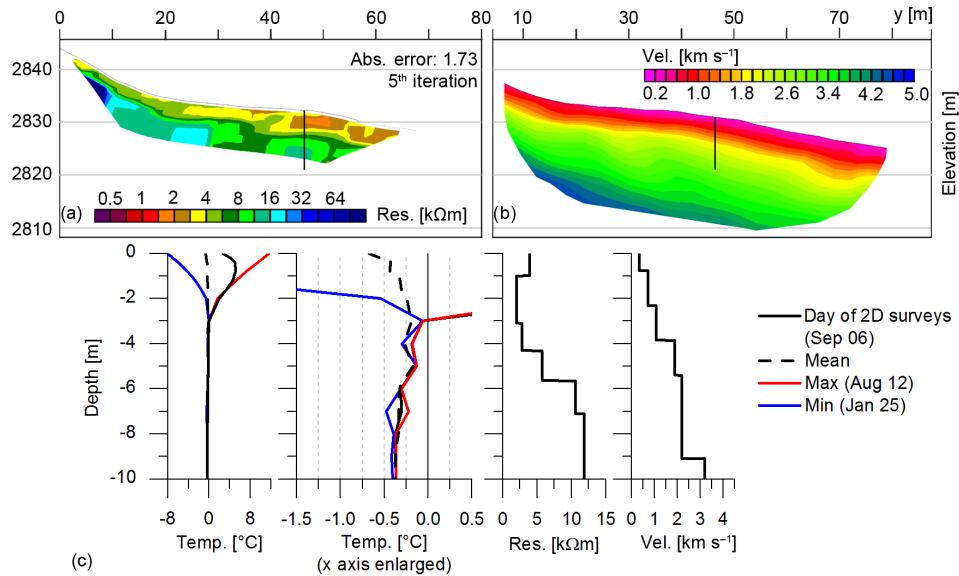
## 4 Results

### 4.1 Frozen ground verification and characteristics

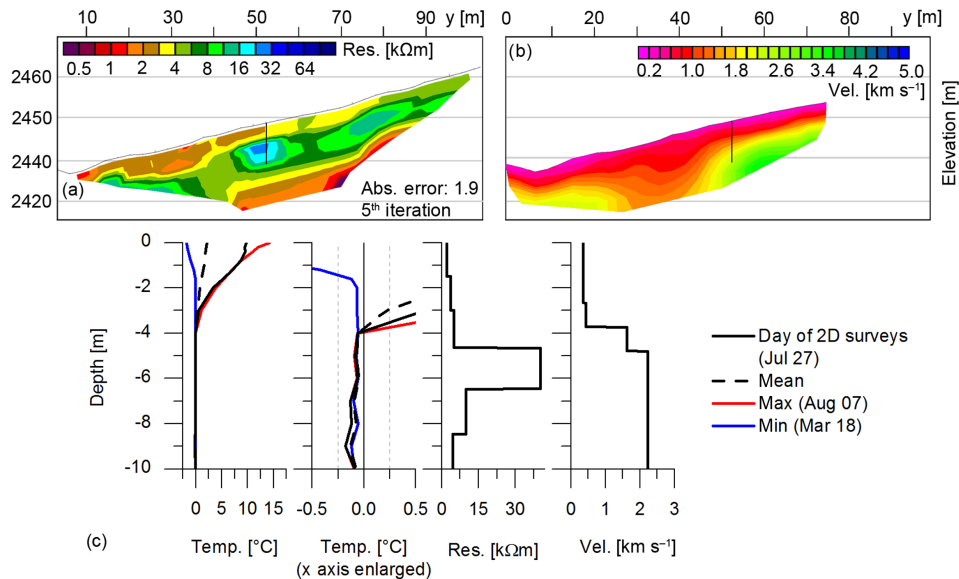
A comparative analysis of single ERT and SRT profiles provides initial two-dimensional information on the local subsurface characteristics. The information of this comparative approach is valuable for interpreting the quasi-3-D ERI models, which are solely based on resistivity data. Additionally presented data from borehole temperature loggers give information on the ground thermal regime and verify the permanently frozen state of the subsurface of the investigated rock glaciers.

#### 4.1.1 Nair rock glacier

A boundary which reflects the characteristic sharp increase in both resistivity and *P*-wave velocity at the transition from unfrozen to frozen subsurface conditions can be obtained through the complete profiles at Nair rock glacier (Fig. 3a, b). Corresponding values for this boundary are around 7 k $\Omega$ m in the ERT profile and 2 km s<sup>-1</sup> in the SRT profile, respectively. At the position of the borehole, the boundary reaches a depth of 4 m, which is not in accordance with the depth at which the temperature profile from the day of the geophysical measurements (daily means) undercuts the 0 °C line (Fig. 3c). However, values from the temperature sensors installed between depths of 3 and 5 m vary between -0.07 and -0.19 °C. This means that the difference from the freezing point is below the accuracy range of the sensors ( $\pm 0.25$  °C). Year-round temperature logging (see exemplary plots in Fig. 3c) shows that values of daily mean temperatures are consistently negative below a depth of 3 m, but only the sensors at 9 and 10 m depth show values that are consistently lower than -0.25 °C and hence confirm permafrost conditions. The upslope part of the profiles, where the geophysical profiles are overlapping ( $Y = 10$ –25 m), represents the steep talus cone at the root zone of the rock glacier. Active layer thickness in this part is 2 m. Resistivity values are around 4 k $\Omega$ m in the unfrozen active layer and vary between 7 and 20 k $\Omega$ m in the frozen layer. The latter values are considerably lower than the maximum values of the ERT model, which are in the range of several hundred k $\Omega$ m in an area that is not included in the SRT profile. Only the SRT model, not the shallower ERT model, shows a second boundary at a depth of 12 m, where *P*-wave velocity values rise from 3.6 to 4.6 km s<sup>-1</sup>. However, it must be noted that data coverage is low in this part. The downslope following part of the profiles ( $Y = 25$ –65 m) shows a steady increase of ALT from 3 to 5 m with decreasing resistivity values from 5 to 2 k $\Omega$ m. This can be linked to an increase in water content as runoff of unconfined water is reduced in this less steep part of the survey line. Resistivity values in the frozen layer are lower in this part of the model and vary between 12 and 8 k $\Omega$ m. The lower boundary, which is detected only from the SRT model, descends and disap-



**Figure 3.** Comparative analysis of (a) 2-D ERT profile, (b) 2-D SRT profile and (c) 1-D temperature, resistivity and  $P$ -wave velocity profiles at Nair rock glacier. Profiles of resistivity and  $P$ -wave velocity are extracted from the tomograms above at the marked borehole position (black line).



**Figure 4.** Comparative analysis of (a) 2-D ERT profile, (b) 2-D SRT profile and (c) 1-D temperature, resistivity and  $P$ -wave velocity profiles at Uertsch rock glacier. Profiles of resistivity and  $P$ -wave velocity are extracted from the tomograms above at the marked borehole position (black line).

pears at  $Y = 36$  m. The dip angle of this boundary is much steeper than the slope angle of the rock glacier surface at this position. It therefore likely represents the depth of bedrock. The permafrost layer is shaped in a slightly wavy form in both models, which shows an undulating frost table topography. The courses of this boundary are not fully synchronous between the models, but this variation can be explained by the small parallel shift between the survey lines (Fig. 1d).

#### 4.1.2 Uertsch rock glacier

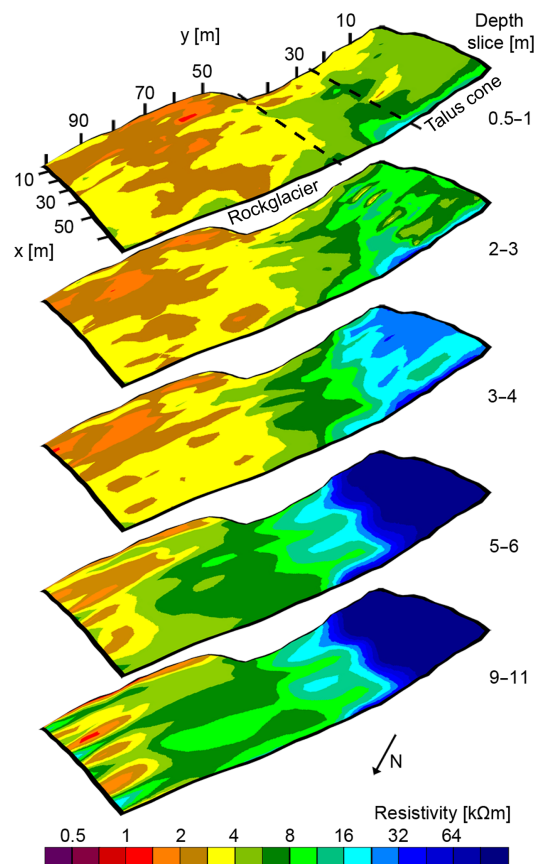
Similarly shaped structures can be observed in the geophysical results from Uertsch rock glacier (Fig. 4a, b), although the positions of the structures seem to be slightly shifted between the profiles. At the position of the borehole, results are in good agreement with the observed subsurface temperatures from the day of the measurements (Fig. 4c). At

a depth of 4 m, a sharp increase of resistivity and  $P$ -wave velocity can be observed. The vertical temperature profile (daily means) of the borehole from the day of the geophysical surveys, reaches  $0^{\circ}\text{C}$  at the same depth and shows that the detected boundary represents the frost table. Results from year-round temperature logging at the borehole (see exemplary plots in Fig. 4c) show that down from a depth of 4 m to the end of the thermistor chain, maximum daily mean temperature values remain between 0 and  $-0.18^{\circ}\text{C}$ . This represents permanently frozen conditions but is within the accuracy range of the sensors. In the permafrost layer of the ERT models, resistivity values are between 8 and  $39\text{ k}\Omega\text{m}$ . These values can be linked to strong variations of ice content, which range between ice-cemented and ice-supersaturated conditions (Ikeda and Matsuoka, 2006).  $P$ -wave velocity values of this layer are between 2 and  $3.2\text{ km s}^{-1}$ . An area of maximum high  $P$ -wave velocity and maximum high resistivity values, slightly shifted upslope in the SRT profile, is visible around the borehole location. Within the ERT profile, the detected permafrost layer ends at a depth of 11 m, where resistivity values decrease again. However, low model resolution values in the bottom part of the model (not shown) indicate that this lower boundary is not necessarily constrained by the measured data.  $P$ -wave velocity values in the SRT section show a further increase with depth below the lower end of the thermistor chain, which indicates that the frozen layer is underlain by unfrozen material with a high level of compaction. As for the ERT profile, it must be noted that data coverage is low in this deeper part of the model. Following the profile in a downslope direction, the layer of high  $P$ -wave velocity sharply descends in the SRT model between  $Y = 45\text{ m}$  and  $Y = 19\text{ m}$ . This coincides with a decrease of resistivity values to below  $5\text{ k}\Omega\text{m}$  and therefore likely represents unfrozen conditions over the complete depth in this part of the profile. The position of this unfrozen part corresponds to the end of the surface ridge structure on which the borehole is placed. In the further downslope part of the profile, the detected structures resemble again those from the upslope part. Near the surface, low resistivity and low  $P$ -wave velocity values indicate an ALT of 6 m, which is larger than the ALT of the upslope part.

## 4.2 3-D subsurface models

### 4.2.1 Nair rock glacier

The 3-D model of subsurface resistivity distribution at Nair rock glacier (Fig. 5) shows a strong and stepwise decrease of resistivity values in  $y$  direction. The range of modelled resistivity values spans from  $420\text{ k}\Omega\text{m}$  in the part of the model which corresponds to the talus cone (see Fig. 5, model slice 0.5–1 m) to  $<1\text{ k}\Omega\text{m}$  in the shallow subsurface of the downslope part of the model. Variations in  $x$  direction are less pronounced and only show a slight increase of resistivity values

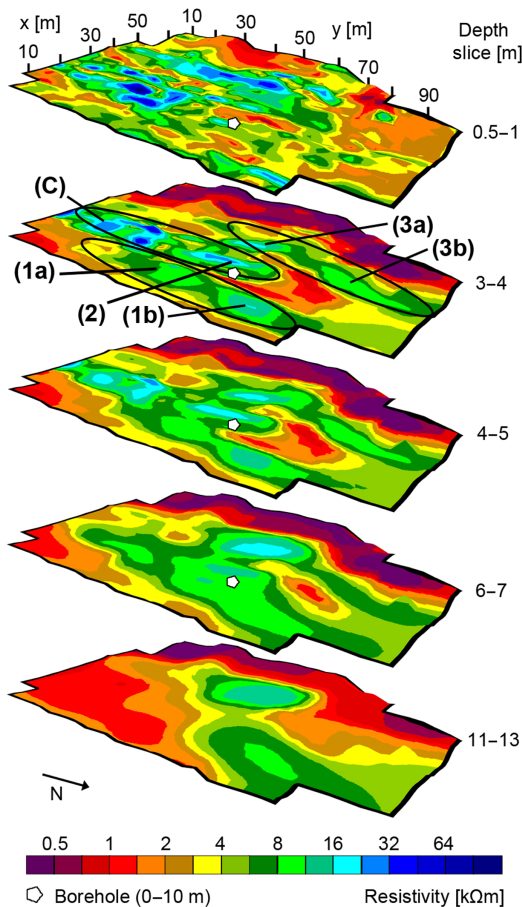


**Figure 5.** Selected depth slices of the quasi-3-D ERI model for Nair.

from the margin of the rock glacier towards the centre of the rock glacier.

The highest resistivity values aggregate in a 15–25 m long and 40 m wide structure where values between 200 and  $400\text{ k}\Omega\text{m}$  in its central part indicate a frozen state. It is overlain by a 2 m thick layer of lower resistivity values, which vary between 4 and  $8\text{ k}\Omega\text{m}$ , and is therefore regarded as the unfrozen active layer. The structure of high resistivity is not shaped homogeneously but narrows slightly along the  $x$  axis towards the blanked out part from  $Y = 42\text{ m}$  to  $Y = 30\text{ m}$ . The vertical extent of the structure exceeds the maximum depth of the model (15 m).

In a downslope direction, at the transition between talus cone and rock glacier, the structure of very high resistivity values ends with a sharp drop of resistivity to values between 20 and  $12\text{ k}\Omega\text{m}$ . These values, although over 1 magnitude lower than the maximum values, also represent frozen material as confirmed by the 2-D models but indicate a different type of ice genesis and/or a lower ice content. The upper layer with lower resistivity values increases in thickness in a downslope direction and towards the lateral margin of this upslope part of the rock glacier (up to 4 m thickness), while it remains thin in the central upslope part of the rock glacier near the transition zone (2–3 m thickness). Resistivity values



**Figure 6.** Selected depth slices of the quasi-3-D ERI model for Uertsch\_01. Numbers refer to structures described in the text.

in the upper layers are also reduced in this part of the model and vary between 4 and 6 kΩm, which corresponds to similar observations from the 2-D models.

The adjacent part, which corresponds to the main part of the rock glacier, generally shows much lower resistivity values. Like the upslope parts of the model, it can be divided vertically into two layers. An upper layer with values from 1 to 3 kΩm can be delimited from deeper parts of the model where resistivity values vary between 7 and 16 kΩm. In *y* direction, the boundary between the two layers is descending to a vertical difference of 4 m. This forms a wedge-shaped outline of the high-resistivity layer which penetrates into the rock glacier from the talus cone.

#### 4.2.2 Uertsch rock glacier

The resistivity model of the lower part of Uertsch rock glacier (Uertsch\_01, Fig. 6) shows a heterogeneous pattern of small units. Extraordinary low resistivity values (up to 1.5 kΩm) aggregate in a 10 m wide curved structure in the western part of the model. The areas of the model which show high resistivity values can be divided into several tongue-shaped

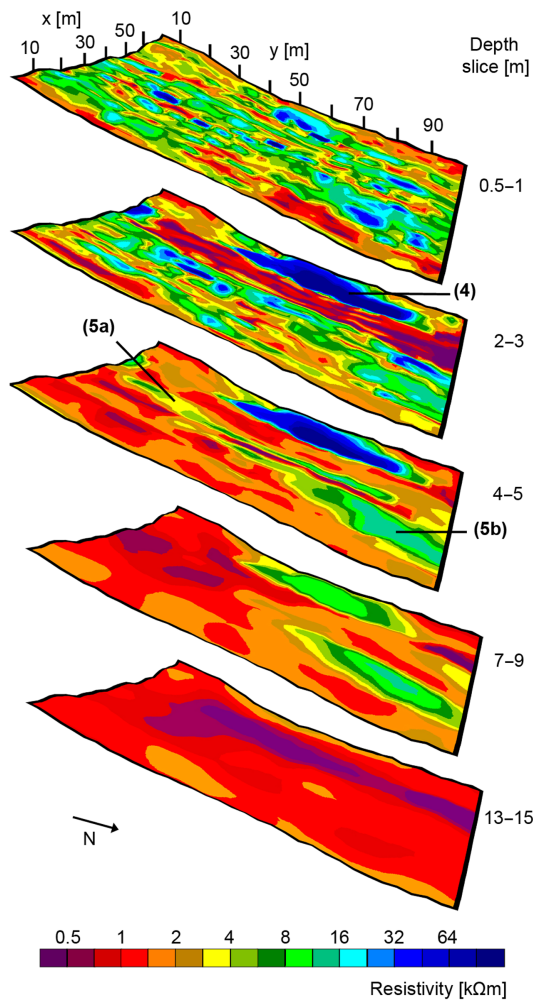
structures which root in a common zone (marked as (C) in Fig. 6). These structures (named (1) to (3) in the following, as marked in Fig. 6) can be delimited by extrapolating the threshold value for frozen and unfrozen conditions which was gained from the comparison of geophysical and temperature data (the rock glacier is rather homogenous regarding debris size composition). Down to a depth of 6 m, three of those structures are visible at  $X = 12$  m (1a, b),  $X = 24$  m (2) and  $X = 38$  m (3a, b). They are outlined by a band of lower resistivity values. Below a model depth of 6 m, the boundaries between the tongue-shaped structures vanish, but some parts of the high-resistivity structures remain.

The first of the three structures is 60 m long and reaches a depth of 7 m in the upslope part (1a). In the downslope part (1b), the lower boundary could not be delimited within the model. Resistivity values vary between 7 and 14 kΩm. The layer above this structure is highly variable in thickness. The second structure (2) is about 70 m long and 10 m wide. This structure is penetrated by the borehole as marked in Fig. 6. High resistivity values of up to 30 kΩm aggregate in a layer of 6–8 m thickness. A shallow covering layer of low resistivity values exists only partly and shows values of up to 1.5 kΩm. Below the layer of high resistivity, values decrease again. Resistivity values of around 1–3 kΩm are reached in the front of the structure, where a prominent U-shaped patch of lower resistivity values is visible (Fig. 6, depth slices 3–4 and 4–5 m). The third area of high resistivity values is 70 m long and reaches to the northern boundary of the model. The upslope part of the structure (3a) can be obtained in the first model slice, while the downslope part (3b) can be obtained below a depth of 3 m underneath a layer of resistivity values of around 5 kΩm. A lower boundary of the structure could not be delimited within the model boundaries in the upslope part, while the downslope part can be detected down to a depth of 9 m (no depth slice displayed).

The resistivity model of the upper part of Uertsch rock glacier (Uertsch\_02, Fig. 7) directly follows the Uertsch\_01 model in an upslope direction (see Figs. 1e, 2d). One dominant high-resistivity anomaly occurs at the central western part of the model (4) (see Fig. 7 for structures (4) and (5)). It reaches resistivity values from 35 to 250 kΩm. While the upslope part of the structure partly occurs directly below the surface in the first model slice, the downslope part is only visible down from a depth of 2 m where the structure reaches its maximum spatial extent. It remains spatially nearly constant down to a depth of 5 m and decreases in extent and resistivity further downwards.

A second, rather undefined, pattern of high resistivity values (5a, b) becomes apparent as a spatial structure below a depth of 2 m, although some model cells in the area already display high resistivity values in upper depth slices. Attaching this structure to the resistivity distribution of the Uertsch\_01 model, reveals that this structure forms a precursor of the three tongue-shaped high-resistivity structures in the lower part of the rock glacier. In the shallow subsurface





**Figure 7.** Selected depth slices of the quasi-3-D ERI model for Uertsch\_02. Numbers refer to structures described in the text.

of the Uertsch\_02 model, the structure displays values from 7 to 18 kΩm. At a depth of 6 m, it loses an elongated segment (5a) and is reduced in extent to an area of 14 m × 30 m. It is detectable down to a depth of 11 m.

The described resistivity distribution clearly reflects the observed surface morphology (see Fig. 2d for morphological structures). It shows high resistivity values within the arcuate (rock glacier snout) and longitudinal ridges (upslope part of the rock glacier) and low resistivity values below the interrupting furrows and surface depressions.

## 5 Discussion

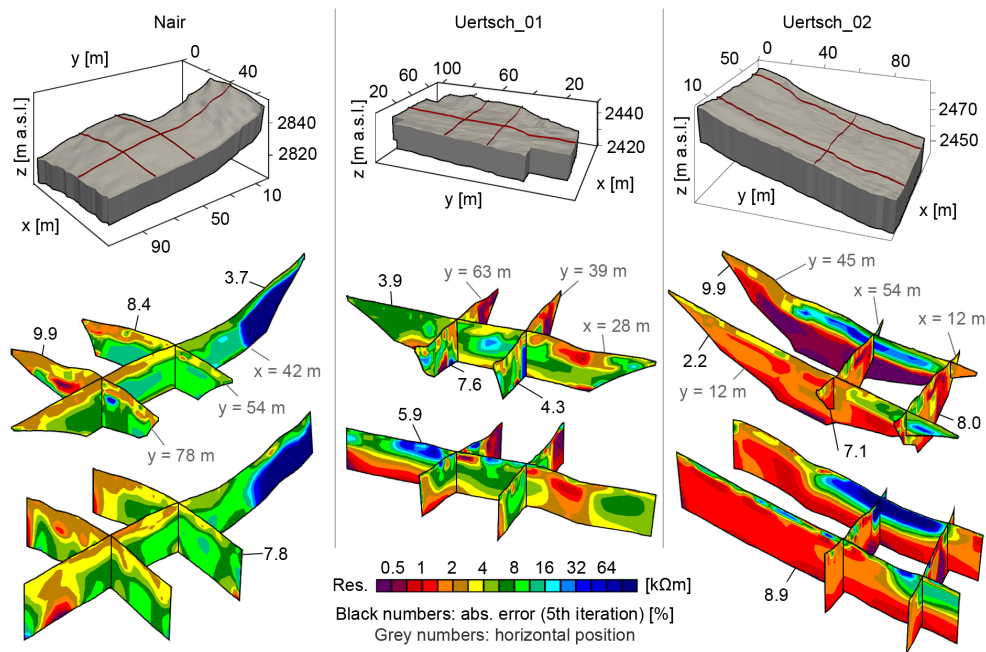
### 5.1 Methodological aspects

A comparison between independently inverted 2-D models and corresponding 2-D slices of the 3-D models (Fig. 8) shows differences between the results of both approaches.

This affects the modelled resistivity values as well as the depths of the detected structures. At Nair rock glacier, resistivity values in the centre of the longitudinal profile (between the perpendicular profiles) are between 12 and 16 kΩm in the 2-D model while they are between 8 and 12 kΩm in the 3-D model. Greater differences are shown in the upslope part of the longitudinal profile of Uertsch\_01. Around  $Y = 90$  m, the 3-D model shows a high-resistivity structure which is displayed with much lower resistivity values by the independently inverted 2-D data. The high-resistivity structure in the Uertsch\_02 model (referred to as (4) in Fig. 7) shows a shallow active layer in the results of the 2-D approach, while it appears directly below the surface in the 3-D model. Structures detected by the 3-D approach are more smoothly shaped than the same structures detected by the 2-D approach, which is likely the result of diagonal filters and interpolation effects.

The quality of quasi-3-D ERI models is influenced by the separation of the survey grid lines. In our investigation, the chosen value of twice the along-line electrode separation as distance between the  $Y$  lines of all survey grids provides an adequate data coverage for investigations of the shallow subsurface (Gharibi and Bentley, 2005). The separation factor of  $X$  lines was adjusted due to site-specific reasons, like deep snow fields or topographical obstacles and ranges between a factor of 3 and 6 of the along-line electrode spacing. However, this is still assumed to be sufficient as the application of perpendicular grid lines is not a mandatory requirement for 3-D data acquisition but useful for the delimitation of small-scale structures orthogonal to the survey line direction (Loke et al., 2013; Rödder and Kneisel, 2012; Chambers et al., 2002). Despite the known limitations of the DipDip electrode array under rough surface conditions (rather low signal strength), its application as a basic electrode array in this study provided very good results. This was likely promoted by the pebbly debris material, which improved the coupling of the electrodes to the ground.

The suitability of the approach is shown by the excellent data quality (only 4 % of all data points were removed during processing; see Sect. 3.1 and Table 1) and by a comparison between 3-D results from the independently inverted DipDip data points and WenSI data points of the Uertsch\_02 data set, which provided similar results (not shown). Additionally, we observed only a slight increase in misfit errors for the 3-D models compared to the independently inverted 2-D models, which indicates a precise grid set-up. The resolution matrix approach, which was performed to evaluate the information content of the model cells and hence to assess model reliability and penetration depth (see Sect. 3.1), shows that most parts of the 3-D models are significantly resolved (not shown). Only those parts of the model layers which are underneath the high-resistivity anomalies and furthermore deeper than 9 m are weakly resolved and are hence interpreted carefully. Results from the comparative 2-D SRT/2-D



**Figure 8.** Comparison between independently inverted 2-D (central row) and 3-D (lower row) models. Upper row shows model representations as blocks and positions of the selected slices.

ERT surveys show good structural accordance and validate the chosen approach.

The detected structures from our geoelectrical investigations of Nair rock glacier broadly resemble the structures which were detected by Ikeda and Matsuoka (2006), who performed a single 2-D ERT survey on the same rock glacier. The  $P$ -wave velocity values from their study for a two-layered subsurface ( $0.34$  and  $2.9 \text{ km s}^{-1}$ ) were also broadly reproduced in our study. However, they observed an ALT of  $2.2$ – $2.4$  m, which is lower than what we observed in our results. This is likely caused by differences in the methodological approach or in the acquisition geometry. However, the impact of atmospheric warming during the last decade is also conceivable.

## 5.2 Range of resistivity values

For most parts of the presented rock glacier models, the range of resistivity values for frozen conditions is rather low compared to other rock glacier sites (Seppi et al., 2015; Dusik et al., 2015; Kneisel, 2010b; Hilbich et al., 2009; Maurer and Hauck, 2007) and is closer to those of landforms in fine-grained environments (Lewkowicz et al., 2011; Farbrot et al., 2007; Kneisel et al., 2007; Ross et al., 2007). Nevertheless, borehole temperature measurements and comparative SRT surveys presented in this study indicate the occurrence of permafrost, although  $P$ -wave velocity values are in the lowermost range for frozen ground (see compilation of Draebing, 2016). The detected threshold values for a frozen state of around  $7 \text{ k}\Omega\text{m}$  at Nair rock glacier and around  $8 \text{ k}\Omega\text{m}$

at Uertsch rock glacier are plausible for the sites as Ikeda and Matsuoka (2006) found similar values for frozen conditions at a similar rock glacier by a comparison between direct observations in a pit and ERT. However, the extrapolation of a single threshold value on a whole rock glacier can be problematic due to variations of grain size and porosity. We think that the extrapolation is suitable at the investigated sites, as such variations are not visible on the surface. The low level of resistivity values at the investigated sites can be explained by the small grain size of the debris material, which is known to show much lower resistivity values in a frozen state than ice-bearing bouldery materials. This is caused by the physical properties of fine materials, which can store a relatively high amount of liquid water at temperatures close to the melting point or even at sub-zero temperatures, resulting in the observed low resistivity values (e.g. Schneider et al., 2013). Additionally, the lower pore space volume can generally lower the ground ice volume, which can develop by freezing of unconfined water (Scapozza et al., 2011; Vonder Mühl et al., 2000). The non-crystalline origin of the talus material can be listed as another factor which influences the local resistivity regime (Etzelmüller et al., 2006). A high proportion of unfrozen water can also be a reason for the mismatch between the observed frost table depths in the vertical profiles of resistivity,  $P$ -wave velocity and temperature at Nair rock glacier (Fig. 3c). As the geophysical approaches are affected by material properties and not directly by temperature, the characteristic increase of resistivity and  $P$ -wave velocity does not coincide with the depth of the ob-

served sub-zero temperatures (Pogliotti et al., 2015; Hauck, 2002). However, sensor accuracy must also be taken into account. Results from ERT and SRT at Uertsch borehole do not show this mismatch phenomenon. This might be linked to an unhindered drain of unconfined water into the adjacent unfrozen part of the transect.

### 5.3 Structure of Nair rock glacier

Ice content distribution at Nair rock glacier is probably determined by an ice patch of sedimentary origin, buried under the steep talus cone. This is indicated by resistivity values of up to 420 k $\Omega$ m which display highly ice-supersaturated conditions. The occurrence of such structures in the root zone of rock glaciers is a well-known phenomenon which develops from buried snow banks or ice patches which were incorporated into the subsurface, e.g. by rockfall (Monnier et al., 2011; Lugon et al., 2004; Isaksen et al., 2000; Haeberli and Vonder Mühll, 1996). A high geomorphological activity is present at Nair rock glacier where frequent rockfall events were observed during several field campaigns. The sharp drop in resistivity values to 20 k $\Omega$ m shows that a clear distinction between the embedded snow bank and the adjacent part is present. This may indicate a relatively young age of incorporation on timescales of landform development, as this contrast would probably diminish through time. A qualitatively similar drop of resistivity values was observed by Ribolini et al. (2010) at Schiantala rock glacier (French Maritime Alps), where it separates an area of debris-covered sedimentary ice and an area of typical permafrost ice at the margin of an LIA glaciation. However, linking the incorporation of sedimentary ice into Nair rock glacier to the end of LIA, for which a glaciation is displayed on ancient maps (Coaz and Leuzinger, 1878), is speculative. The occurrence of ice of sedimentary origin below the talus cone is also an adequate interpretation for the downslope following part of Nair rock glacier which shows resistivity values typical for congelation ice and a decrease from 20 to 12 k $\Omega$ m.

In this part of the rock glacier, the ability of the pebbly material to store water and to reduce the speed of runoff (Ikeda et al., 2008) supports the refreezing of the meltwater from the embedded sedimentary ice. This results in a gradual decrease of ice content in a downslope direction and towards the lateral margin of the rock glacier, which is less affected by meltwater flow than the main part of the rock glacier. Thus, it can explain the observed stepwise increase of ALT and forms the wedge-shaped structure. If we consider the described processes as a current phenomenon, the ice-free parts at Nair rock glacier are equal to the permafrost-free parts and vice versa. Stable ground ice conditions at the rock glacier are indicated by the gradual shape of the continuous frost table, the generally permafrost-favourable conditions according to the Alpine Permafrost Index Map (Boeckli et al., 2012) and the authors' own year-round measurements of ground surface temperatures (not shown).

### 5.4 Structure of Uertsch rock glacier

The observed resistivity variations of the Uertsch rock glacier models indicate variations in ice content and show that different processes were involved in rock glacier development. The investigated part of the rock glacier lacks a continuous frost table and the strongly varying ALT indicates a disturbed development. It likely reflects a disequilibrium between the modern environmental conditions and those at the time of ground ice formation.

The ice-free and hence probably unfrozen ridge at the western edge of the rock glacier (extension of the lateral moraine) seems to be unconnected to the more differentiated central part. The observed lateral moraine and the surface ice patch suggest that interactions between glacial and periglacial processes occurred, like they were assumed for multiple other rock glaciers (Monnier et al., 2011; Ribolini et al., 2010; Berger et al., 2004; Lugon et al., 2004). Glaciation during LIA, as illustrated on an ancient topographical map from the 1870s, was only slightly more extensive than the recent surface ice patch and remained upslope of the today ridge-affected part (see Fig. 2c; Coaz and Leuzinger, 1878). However, like Monnier et al. (2013) pointed out for Sachette rock glacier (French Alps), one of the several other glacier advances during Holocene could have overridden the rock glacier.

The occurrence of buried ice of sedimentary origin is conceivable only for the well-defined structure in the central western part of Uertsch rock glacier (Uertsch\_02 model), which corresponds to the presumably glacial depression. Next to a surface snow field which existed during the days of the 3-D survey within this depression, maximum resistivity values were detected (250 k $\Omega$ m). Although this is still not in the range of sedimentary ice which typically reaches up to several M $\Omega$ m (Haeberli and Vonder Mühll, 1996), a subsurface formation of congelation ice by refreezing meltwater from sedimentary surface ice or an alteration of remnant sedimentary ice by multiple freeze–thaw cycles seems possible, especially in the case of a former glaciation. The occurrence of buried ice of glacial origin within the rock glacier snout, as also frequently observed at other sites, can be excluded by the range of the modelled resistivity values (< 70 k $\Omega$ m), which indicates distinct patches of congelation ice within the ridges by the three tongue-shaped structures of high resistivity values. A similarly shaped elongated geometry of frozen structures was mapped in the Dolomites by Seppi et al. (2015).

The observed pattern of frozen conditions below the ridges and unfrozen conditions below the furrows contrasts the commonly known distribution pattern, which shows colder temperatures in the furrows due to topographic or microclimatic effects (Hoelzle 1999; Harris and Pedersen, 1998). The formation of the characteristic ridge–furrow topography on the rock glacier surface is known to result from compressive processes (Frehner et al., 2015; Springman et al., 2012; Kääh and Weber, 2004). At our study site, the model of overthrust-

ing lobes, as generally presented by Käab and Weber (2004), fits well to the observations. Ridge formation is assumed to induce a local enrichment of ice content through a thickening of ice-saturated layers (Ikeda and Matsuoka, 2006) and can therefore explain the relatively high ice content within the transverse parts of the arcuate ridges in contrast to the lower ice content of the upslope longitudinal ridges. A patchy occurrence of relatively high ice content within the ridges may also explain the low variation of borehole temperatures around the freezing point as much thermal energy will likely be lost by phase transitions of water. A thickening of the active layer as described by Haerberli and Vonder Mühl (1996) could only be detected in the lowermost part of the ridges where the deformation is strongest. The upslope central part of the rock glacier, where ridges are shaped in longitudinal direction and show resistivity values from 8 to 20 k $\Omega$ m, lacks this thickening, likely due to a reduced dynamic forming. Regarding again the model of overthrusting processes, Käab and Weber (2004) presumed that those lateral ridges are the result of ridge deformation by a decrease in speed at the margins of the flow area. This former marginal position of the longitudinal ridges supports the concept of a successive rock glacier development. We assume that ridge formation at Uertsch rock glacier is connected to tongue-shaped areas of creep activity on the rock glacier surface. The lower resistivity values of the extensive flow structures are likely caused by freezing of ionically enriched water at the permafrost base (Haerberli and Vonder Mühl, 1996). However, a glacial formation of the ridges, e.g. as observed by Monnier et al. (2011) at Thabor rock glacier, cannot be excluded because a general influence of surface ice on the formation of Uertsch rock glacier is obvious.

## 6 Conclusions

The application of quasi-3-D ERI enables the detection and mapping of permafrost conditions in a spatially extensive way. At Uertsch rock glacier, the approach showed its value for the delimitation of several small-scale frozen structures within heterogeneous subsurface conditions. The rather homogenous subsurface layering at Nair rock glacier excludes the occurrence of major structural anomalies and shows an undulating frost table topography as well as a gradually decreasing ice content. An excellent data quality was promoted by the pebbly grain size of the investigated rock glaciers and permitted the extensive application of DipDip electrode array. However, due to the specific conditions at pebbly investigation sites, concerning e.g. the range of resistivity values and the influence of grain size on the occurring processes, results should be extrapolated to bouldery rock glaciers only carefully. Inversion characteristics and additionally performed comparative surveys indicate reliable results and emphasise the suitability of the approach. Our results show that the following subsurface characteristics and

their small-scale spatial variations can be derived from quasi-3-D ERI and interpreted in combination with geomorphological observations from the investigated rock glaciers:

- Quasi-3-D ERI results in combination with the observed surface ridge structures show that areas of compressional and extensional flow occur in close proximity and indicate a successive rock glacier development.
- Buried ice of sedimentary origin is a crucial factor for rock glacier development as related processes (e.g. meltwater flow) can influence ground ice content distribution and reflect past glacier–permafrost interactions.
- Meltwater can strongly increase ground ice content in downslope and less inclined parts of rock glaciers and changes its distribution to a gradual decrease which follows the observed rock glacier topography and results in a wedge-shaped outline of the permafrost body.
- Mapping frost table topography and consistency allow us to infer the occurrence of shaping processes and hence to assess whether a state of equilibrium or disequilibrium to modern environmental conditions exists.

To further improve our understanding of landform development, the additional application of GPR and the set-up of a denser network of SRT profiles are advised as these approaches are preferably used for the detection of layer boundaries. The presented resistivity mapping further allows an overlay of resistivity distribution with mapping of surface flow velocity and subsurface porosity. This might be a next step towards an identification of surface–subsurface process interactions.

## 7 Data availability

Geophysical data are available upon request from the authors.

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