

RESEARCH

Open Access



Nonlinear problem with subcritical exponent in Sobolev space

Iqbal H Jebril*

*Correspondence:
iqbal501@hotmail.com
Department of Mathematics, Taibah
University, 344 Almadinah
Almunawwarah, Saudi Arabia

Abstract

Using Brouwer's fixed point theorem, we prove the existence of solutions for some nonlinear problem with subcritical Sobolev exponent in S_+^4 .

MSC: Primary 46E35; 47H10; secondary 35J60

Keywords: Sobolev spaces; subcritical exponent; nonlinear problem

1 Introduction and the main result

The exponent Lebesgue space $L^p(\Omega)$ is defined by

$$L^p(\Omega) = \left\{ u \in L_{\text{loc}}^1(\Omega) : \int_{\Omega} |u(x)|^p dx < \infty \right\}.$$

This space is endowed with the norm

$$\|u\|_{L^p(\Omega)} = \inf \left\{ \lambda > 0 : \int_{\Omega} \left| \frac{u(x)}{\lambda} \right|^p dx \leq 1 \right\}.$$

The Sobolev space $W^{1,p}(\Omega)$ is defined by

$$W^{1,p}(\Omega) = \left\{ u \in W_{\text{loc}}^{1,1}(\Omega) : u \in L^p(\Omega) \text{ and } |\nabla u| \in L^p(\Omega) \right\}.$$

The corresponding norm for this space is

$$\|u\|_{W^{1,p}(\Omega)} = \|u\|_{L^p(\Omega)} + \|\nabla u\|_{L^p(\Omega)}.$$

Define $W_0^1(\Omega) = H_0^1(\Omega)$ as the closure of $C_c^\infty(\Omega)$ with respect to the $W^{1,p}(\Omega)$ norm which is a Hilbert space [1].

We consider the problem of the scalar curvature on the standard four dimensional half sphere under minimal boundary conditions (S):

$$(S) \quad \begin{cases} L_g u := -\Delta_g u + 2u = Ku^3, & u > 0 \text{ in } S_+^4, \\ \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial S_+^4, \end{cases}$$

where $S_+^4 = \{x \in \mathbb{R}^5 / |x| = 1, x_5 > 0\}$, g is the standard metric, and K is a C^3 positive Morse function on $\overline{S_+^4}$.

The scalar curvature problem on S^n and also on S_+^n was the subject of several works in recent years, we can cite for example [2–12].

Recall that the embedding of $H^1(S_+^4)$ into $L^4(S_+^4)$ is noncompact. For this reason, we have focused our study on the family of subcritical problems (S_ε)

$$(S_\varepsilon) \quad \begin{cases} -\Delta_g u + 2u = Ku^{3-\varepsilon}, & u > 0 \quad \text{in } S_+^4, \\ \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial S_+^4, \end{cases}$$

where ε is a small positive parameter.

Note that the solutions of problem (S) can be the limit as $\varepsilon \rightarrow 0$ of some solutions (u_ε) for (S_ε) .

Djadli *et al.* [13] studied this problem in the case of the three dimensional half sphere. Assuming that the critical points of K_1 verify $(\partial K / \partial \nu)(a_i) > 0$ they demonstrated that there exist solutions (u_ε) concentrated at the points (a_1, \dots, a_p) . Moreover, in [14], we established the existence of another type of solutions (u_ε) of (S_ε) such that is concentrated at two points $a_1 \in \partial S_+^4$ and $a_2 \in S_+^4$.

In this work, we aim to construct some positive solutions of (S_ε) which are concentrated at two different points of the boundary. To state our result, we will give the following notations. For $a \in \overline{S_+^4}$ and $\lambda > 0$, let

$$\delta_{(a,\lambda)}(x) = c_0 \frac{\lambda}{(\lambda^2 + 1 + (1 - \lambda^2) \cos d(a, x))}, \tag{1}$$

where d is the geodesic distance on $(\overline{S_+^4}, g)$ and c_0 is chosen so that $\delta_{(a,\lambda)}$ is the family of solutions of the following problem:

$$-\Delta u + 2u = u^3, \quad u > 0, \quad \text{in } S^4.$$

The space $H^1(S_+^4)$ is equipped with the norm $\| \cdot \|$ and its corresponding inner product $\langle \cdot, \cdot \rangle$:

$$\|f\|^2 = \int_{S_+^4} |\nabla f|^2 + 2 \int_{S_+^4} f^2, \quad \text{and} \quad \langle f, g \rangle = \int_{S_+^4} \nabla f \nabla g + 2 \int_{S_+^4} fg, \quad f, g \in H^1(S_+^4).$$

Theorem 1 *Let z_1 and z_2 be a nondegenerate critical points of $K_1 = K|_{\partial S_+^4}$ with $(\partial K / \partial \nu)(z_i) > 0$, $i = 1, 2$. Then there exists $\varepsilon_0 > 0$ such that, for each $\varepsilon \in (0, \varepsilon_0)$, problem (S_ε) has a solution (u_ε) of the form*

$$u_\varepsilon = \alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + v,$$

where, as $\varepsilon \rightarrow 0$, $\alpha_i \rightarrow K(z_i)^{-1/2}$; $\|v\| \rightarrow 0$; $x_i \rightarrow z_i$; $x_i \in \partial S_+^4$; $\lambda_i \rightarrow +\infty$; $\lambda_1 = c\lambda_2(1 + o(1))$.

The rest of this work is summarized as follows. In Section 2, we present a classical preliminaries and we perform a useful estimations of functional (I_ε) associated to the problem (S_ε) for $(\varepsilon > 0)$ and its gradient. Section 3 is devoted to the construction of solutions and the proof of our result.

2 Useful estimations

We introduce the structure variational associated to the problem (S_ε) for $\varepsilon > 0$

$$I_\varepsilon(u) = \frac{1}{2} \int_{S_+^4} |\nabla u|^2 + \int_{S_+^4} u^2 - \frac{1}{4-\varepsilon} \int_{S_+^4} K|u|^{4-\varepsilon}, \quad u \in H^1(S_+^4). \tag{2}$$

It is well known that there is an equivalence between the existence of solutions for (S_ε) and the positive critical point of I_ε . Moreover, in order to reduce our problem to \mathbb{R}_+^4 we will perform some stereographic projection. We denote $D^{1,2}(\mathbb{R}_+^4)$ for the completion of $C_c^\infty(\mathbb{R}_+^4)$ with respect to the Dirichlet norm. Recall that an isometry $\iota : H^1(S_+^4) \rightarrow D^{1,2}(\mathbb{R}_+^4)$ is induced by the stereographic projection π_a about a point $a \in \partial S_+^4$ following the formula

$$(\iota\phi)(y) = \left(\frac{2}{1+|x|^2} \right) \phi(\pi_a^{-1}(y)), \quad \phi \in H^1(S_+^4), y \in \mathbb{R}_+^4. \tag{3}$$

For every $\phi \in H^1(S_+^4)$, one can check that the following holds true:

$$\int_{S_+^4} (|\nabla\phi|^2 + 2\phi^2) = \int_{\mathbb{R}_+^4} |\nabla(\iota\phi)|^2 \quad \text{and} \quad \int_{S_+^4} |\phi|^4 = \int_{\mathbb{R}_+^4} |\iota\phi|^4.$$

Furthermore, using (3) with π_{-a} , it is easy to see that $\iota\delta_{(a,\lambda)}$ is given by

$$\iota\delta_{(a,\lambda)} = \frac{c_0\lambda}{1 + \lambda^2|x - a|^2}.$$

$\delta_{(a,\lambda)}$ will be written instead of $\iota\delta_{(a,\lambda)}$ in the sequel.

Let

$$M_\varepsilon = \left\{ m = (\alpha, \lambda, x, v) \in \mathbb{R}^2 \times (\mathbb{R}_+^*)^2 \times (\partial S_+^4)^2 \times H^1(S_+^4) : v \in E_{(x,\lambda)}, \|v\| < v_0; \right. \\ \left. \left| \frac{\alpha_i^2 K(x_i)}{\alpha_j^2 K(x_j)} - 1 \right| < v_0, \lambda_i > \frac{1}{v_0}, \varepsilon \log \lambda_i < v_0, \forall i; c_0 < \frac{\lambda_1}{\lambda_2} < c_0^{-1}; |x_1 - x_2| > d_0; \right. \\ \left. \left| -2c_3 \frac{\partial K}{\partial v}(x_i) \frac{1}{\lambda_i} + \frac{\varepsilon K(x_i) S_4}{8} \right| < \varepsilon^{1+\frac{\sigma}{2}} \right\},$$

where v_0 is a small positive constant, σ, c_0, d_0 are some suitable positive constants, and

$$E_{(x,\lambda)} = \left\{ w \in H^1(S_+^4) / \langle w, \varphi \rangle = 0 \quad \forall \varphi \in \text{Span} \left\{ \delta_i, \frac{\partial \delta_i}{\partial \lambda_i}, \frac{\partial \delta_i}{\partial x_i^j}, i = 1, 2; j \leq 4 \right\} \right\}.$$

Here, x_i^j denotes the j th component of x_i . Also

$$\Psi_\varepsilon : M_\varepsilon \rightarrow \mathbb{R}; \quad m = (\alpha, \lambda, x, v) \mapsto I_\varepsilon(\alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + v). \tag{4}$$

In the sequel, we will write δ_i instead of $\delta_{(x_i, \lambda_i)}$ and $u = \alpha_1 \delta_1 + \alpha_2 \delta_2 + v$ for the sake of simplicity.

In the remainder of this section, we will give expansions of the gradient of the functional I_ε associated to (S_ε) for $\varepsilon > 0$. Thus estimations are needed in Section 3. We need to recall

that [15] proved the following remark when $n = 3$, but the same argument is available for the dimension 4.

Remark 2 For $\varepsilon > 0$ and $\delta_{(a,\lambda)}$ defined in (1), we have

$$\delta_{(a,\lambda)}^{-\varepsilon}(x) = 1 - \varepsilon \log \delta_{(a,\lambda)} + O(\varepsilon^2 \log^2 \lambda) \quad \text{in } S_+^4.$$

Now, explicit computations, using Remark 2, yield the following propositions.

Proposition 3 Let $(\alpha, \lambda, x, \nu) \in M_\varepsilon$. Then, for $u = \alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + \nu$, we have the following expansion:

$$\langle \nabla I_\varepsilon(u), \delta_i \rangle = \frac{\alpha_i S_4}{2} (1 - \alpha_i^{2-\varepsilon} K(x_i)) + O\left(\varepsilon \log \lambda_i + \frac{1}{\lambda_i} + \varepsilon_{12} + \|\nu\|^2\right),$$

where

$$\varepsilon_{ij} = \frac{1}{\frac{\lambda_i}{\lambda_j} + \frac{\lambda_j}{\lambda_i} + \lambda_i \lambda_j |a_i - a_j|^2},$$

$$S_4 = 64 \int_{\mathbb{R}^4} \frac{dx}{(1 + |x|^2)^4}.$$

Proof We have

$$\langle \nabla I_\varepsilon(u), h \rangle = \int_{S_+^4} \nabla u \nabla h + 2 \int_{S_+^4} u h - \int_{S_+^4} K u^{3-\varepsilon} h. \tag{5}$$

A computation similar to the one performed in [16] shows that, for $i = 1, 2$,

$$\|\delta_i\|^2 = \int_{\mathbb{R}^4} |\nabla \delta_i|^2 = \frac{S_4}{2} \tag{6}$$

and

$$\int_{S_+^4} \nabla \delta_i \nabla \delta_j + 2 \int_{S_+^4} \delta_i \delta_j = \int_{\mathbb{R}^4} \nabla \delta_i \nabla \delta_j = \int_{\mathbb{R}^4} \delta_i^3 \delta_j = O(\varepsilon_{12}). \tag{7}$$

For the other integral, we write

$$\int_{S_+^4} K u^{3-\varepsilon} \delta_i = \int_{S_+^4} K (\alpha_1 \delta_1 + \alpha_2 \delta_2)^{3-\varepsilon} \delta_i + O(\varepsilon_{12}^2 \log \varepsilon_{12}^{-1} + |\nu|^2). \tag{8}$$

We also write

$$\begin{aligned} \int_{S_+^4} K (\alpha_1 \delta_1 + \alpha_2 \delta_2)^{3-\varepsilon} \delta_i &= \alpha_i^{3-\varepsilon} \int_{S_+^4} K \delta_i^{4-\varepsilon} + \alpha_j^{3-\varepsilon} \int_{S_+^4} K \delta_j^{3-\varepsilon} \delta_i \\ &\quad + (3 - \varepsilon) \alpha_i^{2-\varepsilon} \alpha_j \int_{S_+^4} K \delta_i^{3-\varepsilon} \delta_j + O(\varepsilon_{12}^2 \log \varepsilon_{12}^{-1}). \end{aligned} \tag{9}$$

Expansions of K around x_i and x_j give

$$\int_{S_+^4} K \delta_i^{4-\varepsilon} = \int_{\mathbb{R}_+^4} K \delta_i^{4-\varepsilon} = K(x_i) \frac{S_4}{2} + O\left(\varepsilon \log \lambda_i + \frac{1}{\lambda_i}\right), \tag{10}$$

$$\int_{S_+^4} K \delta_j^{3-\varepsilon} \delta_i = \int_{\mathbb{R}_+^4} K \delta_j^{3-\varepsilon} \delta_i = O(\varepsilon \log \lambda_i + \varepsilon_{12}), \tag{11}$$

$$\int_{S_+^4} K \delta_i^{3-\varepsilon} \delta_j = \int_{\mathbb{R}_+^4} K \delta_i^{3-\varepsilon} \delta_j = O(\varepsilon \log \lambda_i + \varepsilon_{12}). \tag{12}$$

Combining (5)-(12), we derive our proposition. □

Proposition 4 *Let $(\alpha, \lambda, x, \nu) \in M_\varepsilon$. Then, for $u = \alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + \nu$, we have*

$$\begin{aligned} \left\langle \nabla I_\varepsilon(u), \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} \right\rangle &= \alpha_j (1 - \alpha_j^{2-\varepsilon} K(x_j) - \alpha_i^{2-\varepsilon} K(x_i)) c_2 \lambda_i \frac{\partial \varepsilon_{12}}{\partial \lambda_i} + \alpha_i^{3-\varepsilon} \frac{\varepsilon S_4 K(x_i)}{8} \\ &\quad + \alpha_i^{3-\varepsilon} \frac{2c_3}{\lambda_i} \frac{\partial K}{\partial \nu}(x_i) + O\left(\|\nu\|^2 + \frac{1}{\lambda_i^2} + \varepsilon^2 \log \lambda_i + \frac{\varepsilon \log \lambda_i}{\lambda_i}\right) \\ &\quad + O\left(\varepsilon \varepsilon_{12} (\log \varepsilon_{12}^{-1})^{1/2} + \varepsilon_{12}^2 \log \varepsilon_{12}^{-1} + \frac{\varepsilon_{12}}{\lambda_j} (\log \varepsilon_{12}^{-1})^{1/2}\right), \end{aligned}$$

where

$$S_4 = 64 \int_{\mathbb{R}^4} \frac{dx}{(1 + |x|^2)^4}, \quad c_2 = 64 \int_{\mathbb{R}^4} \frac{dx}{(1 + |x|^2)^3}, \quad c_3 = 64 \int_{\mathbb{R}_+^4} \frac{x_4(|x|^2 - 1)}{(1 + |x|^2)^5} dx.$$

Proof Observe that (see [16])

$$\int_{\mathbb{R}_+^4} \nabla \delta_i \nabla \left(\lambda_i \frac{\partial \delta_i}{\partial \lambda_i} \right) = \int_{\mathbb{R}_+^4} \delta_i^3 \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} = 0, \tag{13}$$

$$\int_{\mathbb{R}_+^4} \nabla \delta_j \nabla \left(\lambda_i \frac{\partial \delta_i}{\partial \lambda_i} \right) = \int_{\mathbb{R}_+^4} \delta_j^3 \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} = \frac{1}{2} c_2 \lambda_i \frac{\partial \varepsilon_{12}}{\partial \lambda_i} + O(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1})). \tag{14}$$

For the other part, we have the expansions of K around x_i and using Remark 2,

$$\int_{\mathbb{R}_+^4} K \delta_i^{3-\varepsilon} \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} = -\frac{\varepsilon S_4 K(x_i)}{8} - \frac{2c_3}{\lambda_i} \nabla K(x_i) e_4 + O\left(\varepsilon^2 \log \lambda_i + \frac{1}{\lambda_i^2} + \frac{\varepsilon}{\lambda_i}\right), \tag{15}$$

$$\begin{aligned} \int_{\mathbb{R}_+^4} K P \delta_j^{3-\varepsilon} \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} &= K(x_j) \frac{1}{2} c_2 \lambda_i \frac{\partial \varepsilon_{12}}{\partial \lambda_i} + O\left(\varepsilon \varepsilon_{12} (\log(\varepsilon_{12}^{-1}))^{1/2} + \frac{1}{\lambda_j^2}\right) \\ &\quad + O(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1})), \end{aligned} \tag{16}$$

$$\begin{aligned} (3 - \varepsilon) \int_{\mathbb{R}_+^4} K \delta_i^{2-\varepsilon} \delta_j \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} &= K(x_i) \frac{1}{2} c_2 \lambda_i \frac{\partial \varepsilon_{12}}{\partial \lambda_i} + O(\varepsilon \varepsilon_{12} (\log(\varepsilon_{12}^{-1}))^{1/2}) \\ &\quad + O\left(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1}) + \frac{\varepsilon_{12}}{\lambda_j} (\log(\varepsilon_{12}^{-1}))^{1/2}\right). \end{aligned} \tag{17}$$

Combining (5), (13), (14), (15), (16), and (17), the proof follows. □

Proposition 5 *Let $(\alpha, \lambda, x, v) \in M_\varepsilon$. Then, for $u = \alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + v$, we have the following expansion:*

$$\begin{aligned} \left\langle \nabla I_\varepsilon(u), \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} \right\rangle &= \left(\alpha_i c_4 (1 - \alpha_i^{2-\varepsilon} K(x_i)) + \alpha_i^{3-\varepsilon} K(x_i) \varepsilon (c_4 \log \lambda_i + c_7) \right. \\ &\quad \left. + 2 \alpha_i^{3-\varepsilon} \frac{c_5}{\lambda_i} \frac{\partial K}{\partial v}(x_i) \right) e_4 + \alpha_j \left(1 - \sum \alpha_i^{2-\varepsilon} K(x_i) \right) \frac{c_2}{\lambda_i} \frac{\partial \varepsilon_{12}}{\partial x_i} \\ &\quad - 2 \alpha_i^{3-\varepsilon} c_5 \frac{\nabla_T K(x_i)}{\lambda_i} + O \left(\|v\|^2 + \lambda_j |x_1 - x_2| \varepsilon_{12}^{\frac{5}{2}} + \frac{\varepsilon \log \lambda_i}{\lambda_i} |\nabla_T K(x_i)| \right) \\ &\quad + O \left(\varepsilon \varepsilon_{12} (\log \varepsilon_{12}^{-1})^{\frac{1}{2}} + \varepsilon_{12}^2 \log \varepsilon_{12}^{-1} + \frac{\varepsilon_{12}}{\lambda_j} (\log \varepsilon_{12}^{-1})^{\frac{1}{2}} + \frac{1}{\lambda_i^2} + \varepsilon^2 \log^2 \lambda_i \right), \end{aligned}$$

where

$$c_4 = 132 \int_{\mathbb{R}_+^4} \frac{x_4}{(1 + |x|^2)^5} dx, \quad c_5 = 16 \int_{\mathbb{R}^4} \frac{x_4^2}{(1 + |x|^2)^5} dx.$$

Proof We have

$$\int_{\mathbb{R}_+^4} \nabla \delta_i \nabla \left(\frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} \right) = \int_{\mathbb{R}_+^4} \delta_i^3 \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} = c_4 e_4, \tag{18}$$

$$\int_{\mathbb{R}_+^4} \nabla \delta_j \nabla \left(\frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} \right) = \int_{\mathbb{R}_+^4} \delta_j^3 \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} = \frac{1}{2} \frac{c_2}{\lambda_i} \frac{\partial \varepsilon_{12}}{\partial x_i} + O \left(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1}) + \varepsilon_{12}^{\frac{5}{2}} \lambda_j |x_1 - x_2| \right). \tag{19}$$

For the other part

$$\begin{aligned} \int_{\mathbb{R}_+^4} K \delta_i^{3-\varepsilon} \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} &= K(x_i) c_4 e_4 + 2 \frac{c_5}{\lambda_i} \nabla K(x_i) - \varepsilon \log \lambda_i K(x_i) c_4 e_4 \\ &\quad - \varepsilon K(x_i) c_7 e_4 + O \left(\frac{1}{\lambda_i^2} + \varepsilon^2 \log^2 \lambda_i \right), \end{aligned} \tag{20}$$

$$\begin{aligned} \int_{\mathbb{R}_+^4} K \delta_j^{3-\varepsilon} \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} &= K(x_j) \frac{1}{2} c_2 \frac{1}{\lambda_i} \frac{\partial \varepsilon_{12}}{\partial x_i} + O \left(\varepsilon_{12}^{\frac{5}{2}} \lambda_j |x_1 - x_2| \right) \\ &\quad + O \left(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1}) + \frac{1}{\lambda_j} \varepsilon_{12} (\log(\varepsilon_{12}^{-1}))^{\frac{1}{2}} \right), \end{aligned} \tag{21}$$

$$\begin{aligned} (3 - \varepsilon) \int_{\mathbb{R}_+^4} K \delta_i^{2-\varepsilon} \delta_j \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} &= K(x_i) \frac{1}{2} c_2 \frac{1}{\lambda_i} \frac{\partial \varepsilon_{12}}{\partial x_i} + O \left(\varepsilon_{12}^{\frac{5}{2}} \lambda_j |x_1 - x_2| \right) \\ &\quad + O \left(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1}) + \frac{1}{\lambda_i} \varepsilon_{12} (\log(\varepsilon_{12}^{-1}))^{\frac{1}{2}} \right). \end{aligned} \tag{22}$$

Using (5), (18)-(22), our proposition follows. □

3 Construction of the solution

The method of this type of theorem was followed first by Bahri, Li and Rey [17] when they studied an approximation problem of the Yamabe-type problem on domains. Many authors used this idea to construct some solutions to other problems. The method becomes standard. Here we will follow the idea of [17] and take account of the new estimates since

we have an equation different from the one studied in [17]. From the idea of [17], using the coefficients of Euler-Lagrange, we obtain

Proposition 6 *Let A point $m = (\alpha, \lambda, x, v) \in M_\varepsilon$ is a critical point of the function Ψ_ε if and only if $u = \alpha_1\delta_1 + \alpha_2\delta_2 + v$ is a critical point of functional I_ε , which means the existence of some $(A, B, C) \in \mathbb{R}^2 \times \mathbb{R}^2 \times (\mathbb{R}^4)^2$ with the following:*

$$(E_{\alpha_i}) \frac{\partial \Psi_\varepsilon}{\partial \alpha_i} = 0, \quad \forall i = 1, 2, \tag{23}$$

$$(E_{\lambda_i}) \frac{\partial \Psi_\varepsilon}{\partial \lambda_i} = B_i \left\langle \frac{\partial^2 \delta_i}{\partial \lambda_i^2}, v \right\rangle + \sum_{j=1}^4 C_{ij} \left\langle \frac{\partial^2 \delta_i}{\partial x_i^j \partial \lambda_i}, v \right\rangle, \quad \forall i = 1, 2, \tag{24}$$

$$(E_{x_i}) \frac{\partial \Psi_\varepsilon}{\partial x_i} = B_i \left\langle \frac{\partial^2 \delta_i}{\partial \lambda_i \partial x_i}, v \right\rangle + \sum_{j=1}^4 C_{ij} \left\langle \frac{\partial^2 \delta_i}{\partial x_i^j \partial x_i}, v \right\rangle, \quad \forall i = 1, 2, \tag{25}$$

$$(E_v) \frac{\partial \Psi_\varepsilon}{\partial v} = \sum_{i=1,2} \left(A_i \delta_i + B_i \frac{\partial \delta_i}{\partial \lambda_i} + \sum_{j=1}^4 C_{ij} \frac{\partial \delta_i}{\partial x_i^j} \right). \tag{26}$$

Now, by a careful study of equation (E_v) , we get the following.

Proposition 7 [12] *For any $(\varepsilon, \alpha, \lambda, x)$ with $(\alpha, \lambda, x, 0) \in M_\varepsilon$, there exists a smooth map which associates $\bar{v} \in E_{(x,\lambda)}$ with $\|\bar{v}\| < v_0$ and equation (26) in the previous proposition is verified for some $(A, B, C) \in \mathbb{R}^2 \times \mathbb{R}^2 \times (\mathbb{R}^4)^2$. Such a \bar{v} is unique, minimizes $\Psi_\varepsilon(\alpha, \lambda, x, v)$ with respect to v in $\{v \in E_{(x,\lambda)} / \|v\| < v_0\}$, and*

$$\|\bar{v}\| = O\left(\varepsilon + \frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \varepsilon_{12}(\log \varepsilon_{12}^{-1})^{1/2}\right). \tag{27}$$

Proof of Theorem 1 Once \bar{v} is defined by Proposition 7, we estimate the corresponding numbers A, B, C by taking the scalar product in $H^1(S_+^4)$ of (E_v) with $\delta_i, \partial \delta_i / \partial \lambda_i, \partial \delta_i / \partial x_i$ for $i = 1, 2$, respectively. So we get the following coefficients of a quasi-diagonal system:

$$\begin{aligned} \int_{\mathbb{R}_+^4} |\nabla \delta_i|^2 &= \frac{S_4}{2}; & \int_{\mathbb{R}_+^4} \nabla \delta_1 \nabla \delta_2 &= O\left(\frac{1}{\lambda_2 \lambda_1}\right); & \int_{\mathbb{R}_+^4} \nabla \delta_i \nabla \frac{\partial \delta_i}{\partial \lambda_i} &= 0; \\ \int_{\mathbb{R}_+^4} \nabla \delta_1 \nabla \frac{\partial \delta_2}{\partial \lambda_2} &= O\left(\frac{1}{\lambda_1 \lambda_2^2}\right), & \int_{\mathbb{R}_+^4} \nabla \delta_2 \nabla \frac{\partial \delta_1}{\partial \lambda_1} &= O\left(\frac{1}{\lambda_1^2 \lambda_2}\right); & \int_{\mathbb{R}_+^4} \left| \nabla \frac{\partial \delta_i}{\partial \lambda_i} \right|^2 &= \frac{\Gamma_1}{2\lambda_i^2}; \\ \int_{\mathbb{R}_+^4} \nabla \frac{\partial \delta_1}{\partial \lambda_1} \nabla \frac{\partial \delta_2}{\partial \lambda_2} &= O\left(\frac{1}{\lambda_1^2 \lambda_2^2}\right), & \int_{\mathbb{R}_+^4} \left| \nabla \frac{\partial \delta_i}{\partial x_i} \right|^2 &= \frac{\Gamma_2}{2} \lambda_i^2; & \int_{\mathbb{R}_+^4} \nabla \delta_i \nabla \frac{\partial \delta_i}{\partial x_i} &= O(\lambda_i); \\ \int_{\mathbb{R}_+^4} \nabla \delta_1 \nabla \frac{\partial \delta_2}{\partial x_2} &= O\left(\frac{1}{\lambda_1}\right), & \int_{\mathbb{R}_+^4} \nabla \delta_2 \nabla \frac{\partial \delta_1}{\partial x_1} &= O\left(\frac{1}{\lambda_2}\right); \\ \int_{\mathbb{R}_+^4} \nabla \frac{\partial \delta_1}{\partial x_1} \nabla \frac{\partial \delta_2}{\partial x_2} &= \frac{n+2}{n-2} \int_{\mathbb{R}_+^4} \delta_2^{\frac{4}{n-2}} \nabla \frac{\partial \delta_2}{\partial x_2} \frac{\partial \delta_1}{\partial x_1} &= O\left(\frac{1}{\lambda_1}\right), \end{aligned}$$

with $|x_1 - x_2| \geq c > 0$ and Γ_1, Γ_2 are positive constants.

We have also

$$\left\langle \frac{\partial \Psi_\varepsilon}{\partial v}, \delta_i \right\rangle = \frac{\partial \Psi_\varepsilon}{\partial \alpha_i}; \quad \left\langle \frac{\partial \Psi_\varepsilon}{\partial v}, \frac{\partial \delta_i}{\partial \lambda_i} \right\rangle = \frac{1}{\alpha_i} \frac{\partial \Psi_\varepsilon}{\partial \lambda_i}; \quad \left\langle \frac{\partial \Psi_\varepsilon}{\partial v}, \frac{\partial \delta_i}{\partial x_i} \right\rangle = \frac{1}{\alpha_i} \frac{\partial \Psi_\varepsilon}{\partial x_i}.$$

Using Propositions 3, some computations yield

$$\frac{\partial \Psi_\varepsilon}{\partial \alpha_i} = -S_4 \beta_i + V_{\alpha_i}(\varepsilon, \alpha, \lambda, x), \tag{28}$$

with $\beta_i = \alpha_i - 1/K(z_i)^{\frac{1}{2}}$ and

$$V_{\alpha_i} = O\left(\beta_i^2 + \varepsilon \log \lambda_i + \frac{1}{\lambda_i} + |x_i - z_i|^2\right). \tag{29}$$

In the same way, using Propositions 4, we get

$$\frac{\partial \Psi_\varepsilon}{\partial \lambda_i} = \frac{1}{K(z_i)} \left(\frac{2c_3}{\lambda_i^2} \frac{\partial K}{\partial v}(x_i) + \frac{\varepsilon K(x_i) S_4}{8\lambda_i} \right) + V_{\lambda_i}(\varepsilon, \alpha, \lambda, x), \tag{30}$$

where c_2 and c_3 are defined in Proposition 4 and

$$V_{\lambda_i} = O\left[\frac{1}{\lambda_i} \left(\frac{1}{\lambda_i^2} + \varepsilon^2 \log \lambda_i + \frac{\varepsilon \log \lambda_i}{\lambda_i} \right) + (|\beta| + \varepsilon + |x_i - z_i|^2) \left(\frac{\varepsilon}{\lambda_i} + \frac{1}{\lambda_i^2} \right)\right]. \tag{31}$$

Lastly, using Propositions 5, we have

$$\frac{\partial \Psi_\varepsilon}{\partial x_i} = -2c_5 \nabla_T K(x_i) + V_{x_i}(\varepsilon, \alpha, \lambda, x), \tag{32}$$

where

$$V_{x_i} = O\left(\frac{1}{\lambda_i} + (|\beta| + \varepsilon \log \lambda_i + |x_i - z_i|^2) |x_i - z_i|\right). \tag{33}$$

From these estimates, we deduce

$$\begin{aligned} \frac{\partial \Psi_\varepsilon}{\partial \alpha_i} &= O\left(|\beta| + \varepsilon \log \lambda_i + \frac{1}{\lambda_i} + |x_i - z_i|^2\right), \\ \frac{\partial \Psi_\varepsilon}{\partial \lambda_i} &= O\left(\frac{\varepsilon^{1+\sigma/2}}{\lambda_i}\right); \quad \frac{\partial \Psi_\varepsilon}{\partial x_i} = O\left(|x_i - z_i| + \frac{1}{\lambda_i}\right). \end{aligned}$$

By solving the system in A , B , and C , we find

$$\begin{cases} A_i = O(|\beta| + \varepsilon \log \lambda_i + \frac{1}{\lambda_i} + |x_i - z_i|^2), \\ B_i = O(\varepsilon^{1+\sigma/2} \lambda_i); \quad C_i = O\left(\frac{|x_i - z_i|}{\lambda_i^2} + \frac{1}{\lambda_i^3}\right). \end{cases} \tag{34}$$

Now, we can evaluate the right hand side in (E_{λ_i}) and (E_{x_i}) ,

$$B_i \left\langle \frac{\partial^2 \delta_i}{\partial \lambda_i^2}, \bar{v} \right\rangle + \sum_{j=1}^4 C_{ij} \left\langle \frac{\partial^2 \delta_i}{\partial x_i^j \partial \lambda_i}, \bar{v} \right\rangle = O\left(\left(\frac{\varepsilon^{1+\sigma/2}}{\lambda_i} + \frac{|x_i - z_i|}{\lambda_i^2} + \frac{1}{\lambda_i^3}\right) \|\bar{v}\|\right), \tag{35}$$

$$B_i \left\langle \frac{\partial^2 \delta_i}{\partial \lambda_i \partial x_i}, \bar{v} \right\rangle + \sum_{j=1}^4 C_{ij} \left\langle \frac{\partial^2 \delta_i}{\partial x_i^j \partial x_i}, \bar{v} \right\rangle = O\left(\left(\varepsilon^{1+\sigma/2} \lambda_i + |x_i - z_i| + \frac{1}{\lambda_i}\right) \|\bar{v}\|\right), \tag{36}$$

where

$$\left\| \frac{\partial^2 P\delta_i}{\partial \lambda_i^2} \right\| = O\left(\frac{1}{\lambda_i^2}\right); \quad \left\| \frac{\partial^2 P\delta_i}{\partial x_i \partial \lambda_i} \right\| = O(1); \quad \left\| \frac{\partial^2 P\delta_i}{\partial x_i^2} \right\| = O(\lambda_i^2).$$

Now, we consider a point $(z_1, z_2) \in \partial S_+^4 \times \partial S_+^4$ such that z_1 and z_2 are nondegenerate critical points of K_1 . We set

$$\frac{1}{\lambda_i} = \varepsilon \frac{S_4}{16c_3} K(z_i) \left(\frac{\partial K}{\partial v}(z_i) \right)^{-1} (1 + \zeta_i); \quad x_i = z_i + \xi_i,$$

where $\zeta_i \in \mathbb{R}$ and $(\xi_1, \xi_2) \in \mathbb{R}^3 \times \mathbb{R}^3$ are assumed to be small.

Using (28) and these changes of variables, (E_{α_i}) becomes

$$\beta_i = V_{\alpha_i}(\varepsilon, \beta, \zeta, \xi) = O(\beta^2 + \varepsilon |\log \varepsilon| + |\xi|^2). \tag{37}$$

Also, we use (30), we have

$$\begin{aligned} & \frac{2c_3}{\lambda_i^2} \frac{\partial K}{\partial v}(z_i + \xi_i) + \frac{\varepsilon K(z_i + \xi_i) S_4}{8\lambda_i} \\ &= \frac{\varepsilon^2 S_4^2 K(z_i)^2}{128c_3} \left(\frac{\partial K}{\partial v}(z_i) \right)^{-2} (1 + 2\zeta_i) \left(-\frac{\partial K}{\partial v}(z_i) + D^2 K(z_i)(e_4, \xi_i) \right) \\ & \quad + \frac{\varepsilon^2 S_4^2 K(z_i)^2}{128c_3} \left(\frac{\partial K}{\partial v}(z_i) \right)^{-1} (1 + \zeta_i) + O(\varepsilon^2(\zeta_i^2 + |\xi_i|^2)) \\ &= -\frac{\varepsilon^2 S_4^2 K(z_i)^2}{128c_3} \left(\frac{\partial K}{\partial v}(z_i) \right)^{-1} \zeta_i \\ & \quad + \frac{\varepsilon^2 S_4^2 K(z_i)^2}{128c_3} \left(\frac{\partial K}{\partial v}(z_i) \right)^{-2} D^2 K(z_i)(e_4, \xi_i) \\ & \quad + O(\varepsilon^2(\zeta_i^2 + |\xi_i|^2)). \end{aligned}$$

Combining this with (31), then (E_{λ_i}) becomes

$$\begin{aligned} -\zeta_i + \left(\frac{\partial K}{\partial v}(z_i) \right)^{-1} D^2 K_1(z_i)(e_4, \xi_i) &= V_{\lambda_i}(\varepsilon, \beta, \zeta, \xi) \\ &= O(\varepsilon |\log \varepsilon| + |\beta|^2 + \zeta_i^2 + |\xi|^2). \end{aligned} \tag{38}$$

Using (32), (33), and (36), (E_{x_i}) is equivalent to

$$D^2 K_1(z_i) \xi_i = V_{x_i}(\varepsilon, \beta, \zeta, \xi) = O(\varepsilon^{1/2} + |\beta|^2 + |\zeta|^2 + |\xi|^2). \tag{39}$$

Observe that the functions V_{α_i} , V_{λ_i} , and V_{x_i} are smooth.

We can also write the system as

$$\begin{cases} \beta = V(\varepsilon, \beta, \zeta, \xi), \\ L(\zeta, \xi) = W(\varepsilon, \beta, \zeta, \xi), \end{cases} \tag{40}$$

where L is a fixed linear operator on \mathbb{R}^8 defined by

$$L(\zeta, \xi) = \left(-\zeta_1 + \left(\frac{\partial K}{\partial v}(z_1) \right)^{-1} D^2 K_1(z_1)(e_4, \xi_1); -\zeta_2 + \left(\frac{\partial K}{\partial v}(z_2) \right)^{-1} D^2 K_1(z_2)(e_4, \xi_2); \right. \\ \left. D^2 K_1(z_1)\xi_1; D^2 K_1(z_2)\xi_2 \right),$$

and V, W are smooth functions satisfying

$$\begin{cases} V(\varepsilon, \beta, \zeta, \xi) = O(\varepsilon^{1/2} + |\beta|^2 + |\xi|^2), \\ W(\varepsilon, \beta, \zeta, \xi) = O(\varepsilon^{\frac{1}{2}} + |\beta|^2 + |\zeta|^2 + |\xi|^2). \end{cases}$$

Now, by an easy computation, we see that the determinant of the linear operator L is not 0. Hence L is invertible, and according to Brouwer’s fixed point theorem, there exists a solution $(\beta^\varepsilon, \zeta^\varepsilon, \xi^\varepsilon)$ of (40) for ε small enough, such that

$$|\beta^\varepsilon| = O(\varepsilon^{1/2}); \quad |\zeta^\varepsilon| = O(\varepsilon^{1/2}); \quad |\xi^\varepsilon| = O(\varepsilon^{1/2}).$$

Hence, we have constructed $m^\varepsilon = (\alpha_1^\varepsilon, \alpha_2^\varepsilon, \lambda_1^\varepsilon, \lambda_2^\varepsilon, \chi_1^\varepsilon, \chi_2^\varepsilon)$ such that $u_\varepsilon := \sum \alpha_i^\varepsilon \delta_{(\alpha_i^\varepsilon, \lambda_i^\varepsilon)} + \bar{v}_\varepsilon$, verifies (23)-(27). From Proposition 6, u_ε is a critical point of I_ε , which implies that u_ε verify

$$-\Delta u_\varepsilon + 2u_\varepsilon = K|u_\varepsilon|^{2-\varepsilon} u_\varepsilon \quad \text{in } S_+^4, \quad \partial u_\varepsilon / \partial v = 0 \quad \text{on } \partial S_+^4. \tag{41}$$

We multiply equation (41) by $u_\varepsilon^- = \max(0, -u_\varepsilon)$ and we integrate on S_+^4 , we get

$$\int_{S_+^4} |\nabla u_\varepsilon^-|^2 + 2 \int_{S_+^4} (u_\varepsilon^-)^2 = \int_{S_+^4} K(u_\varepsilon^-)^{4-\varepsilon}. \tag{42}$$

We know also from the Sobolev embedding theorem that

$$|u_\varepsilon^-|_{4-\varepsilon}^2 := \left(\int_{S_+^4} K(u_\varepsilon^-)^{4-\varepsilon} \right)^{\frac{2}{4-\varepsilon}} \leq C \|u_\varepsilon^-\|^2. \tag{43}$$

Equations (42) and (43) imply that either $u_\varepsilon^- \equiv 0$, or $|u_\varepsilon^-|_{4-\varepsilon}$ is far away from zero. Since $m^\varepsilon \in M^\varepsilon$, we have $\|\bar{v}_\varepsilon\| < \nu_0$, where ν_0 is a small positive constant (see the definition of M_ε). This implies that $|u_\varepsilon^-|_{4-\varepsilon}$ is very small. Thus, $u_\varepsilon^- \equiv 0$ for ε small enough. Then u_ε is a non-negative function which satisfies (41). Finally, the maximum principle completes the proof of our theorem. □

4 Conclusion

Thus it has been concluded that under some assumptions on the function K , there exist solutions of the nonlinear problem (S_ε) which are concentrated at two different points of the boundary.

Competing interests

The author declares to have no competing interests.

Acknowledgements

I would like to thank Deanship of Scientific Research at Taibah University for the financial support of this research project.

Received: 28 July 2016 Accepted: 14 November 2016 Published online: 25 November 2016

References

1. Diening, L, Harjulehto, P, Hasto, P, Ruzicka, M: Lebesgue and Sobolev Spaces with Variable Exponents. Lecture Notes in Mathematics, vol. 2011. Springer, Heidelberg (2011) MR2790542
2. Ambrosetti, A, Garcia Azorero, J, Peral, A: Perturbation of $\Delta u + u^{\frac{n-2}{n-2}} = 0$, the scalar curvature problem in \mathbb{R}^n and related topics. *J. Funct. Anal.* **165**, 117-149 (1999)
3. Bahri, A, Coron, JM: The scalar curvature problem on the standard three dimensional spheres. *J. Funct. Anal.* **95**, 106-172 (1991)
4. Bianchi, G, Pan, XB: Yamabe equations on half spheres. *Nonlinear Anal.* **37**, 161-186 (1999)
5. Chang, SA, Yang, P: A perturbation result in prescribing scalar curvature on S^n . *Duke Math. J.* **64**, 27-69 (1991)
6. Cherrier, P: Problèmes de Neumann non linéaires sur les variétés riemanniennes. *J. Funct. Anal.* **57**, 154-207 (1984)
7. Escobar, J: Conformal deformation of Riemannian metric to scalar flat metric with constant mean curvature on the boundary. *Ann. Math.* **136**, 1-50 (1992)
8. Escobar, J, Schoen, R: Conformal metrics with prescribed scalar curvature. *Invent. Math.* **86**, 243-254 (1986)
9. Han, ZC, Li, YY: The existence of conformal metrics with constant scalar curvature and constant boundary mean curvature. *Commun. Anal. Geom.* **8**, 809-869 (2000)
10. Hebey, E: The isometry concentration method in the case of a nonlinear problem with Sobolev critical exponent on compact manifolds with boundary. *Bull. Sci. Math.* **116**, 35-51 (1992)
11. Li, YY: Prescribing scalar curvature on S^n and related topics, Part I. *J. Differ. Equ.* **120**, 319-410 (1995); Part II. Existence and compactness. *Comm. Pure Appl. Math.* **49** 437-477 (1996).
12. Ould Bouh, K: Blowing up of sign-changing solutions to a subcritical problem. *Manuscr. Math.* **146**, 265-279 (2015)
13. Djadli, Z, Malchiodi, A, Ould Ahmedou, M: Prescribing the scalar and the boundary mean curvature on the three dimensional half sphere. *J. Geom. Anal.* **13**, 233-267 (2003)
14. Ben Ayed, M, Ghoudi, R, Ould Bouh, K: Existence of conformal metrics with prescribed scalar curvature on the four dimensional half sphere. *Nonlinear Differ. Equ. Appl.* **19**, 629-662 (2012)
15. Rey, O: The topological impact of critical points at infinity in a variational problem with lack of compactness: the dimension 3. *Adv. Differ. Equ.* **4**, 581-616 (1999)
16. Bahri, A: An invariant for Yamabe-type flows with applications to scalar curvature problems in high dimension. A celebration of J. F. Nash jr. *Duke Math. J.* **81**, 323-466 (1996)
17. Bahri, A, Li, YY, Rey, O: On a variational problem with lack of compactness: The topological effect of the critical points at infinity. *Calc. Var. Partial Differ. Equ.* **3**, 67-94 (1995)

Submit your manuscript to a SpringerOpen® journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Immediate publication on acceptance
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► springeropen.com
