

Research Article On Attractivity and Positivity of Solutions for Functional Integral Equations of Fractional Order

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We investigate a class of functional integral equations of fractional order given by $x(t) = q(t) + f_1(t, x(\alpha_1(t)), x(\alpha_2(t))) + (f_2(t, x(\beta_1(t)), x(\beta_2(t)))/\Gamma(\alpha)) \times \int_0^t (t-s)^{\alpha-1} f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s))) ds$: sufficient conditions for the existence, global attractivity, and ultimate positivity of solutions of the equations are derived. The main tools include the techniques of measures of noncompactness and a recent measure theoretic fixed point theorem of Dhage. Our investigations are placed in the Banach space of continuous and bounded real-valued functions defined on unbounded intervals. Moreover, two examples are given to illustrate our results.

1. Introduction

Nonlinear functional integral equations with bounded intervals have been studied extensively in the literature as regards various qualitative properties. This includes existence, uniqueness, stability, boundedness, monotonicity and extremality of solutions. But the study of nonlinear functional integral equations with unbounded intervals is relatively rare and exploited for the characteristics of attractivity and asymptotic attractivity of solutions. There are two methods for dealing with these characteristics of solutions, namely, classical fixed point theorems involving the hypotheses from analysis and topology and the fixed point theorems involving the use of measure of noncompactness. Each one of these methods has some advantages and disadvantages over the others [1–11].

The theory of integral equations of fractional order plays a very important role in describing some real world problems; it has recently received a lot of attention and now constitutes a significant branch of nonlinear analysis. In recent years, differential and integral equations of fractional order have found wide applications in physics, mechanics, engineering, electro chemistry, economics, and other fields [12– 19]; meanwhile, numerous research papers and monographs have appeared devoted to differential and integral equations of fractional order [20–38]. These papers contain various qualitative properties such as existence, uniqueness, stability, and asymptotic behavior for equations of fractional order.

The aim of this paper is to study the existence, global attractivity, and positivity of solutions for a functional integral equation of fractional order. The mentioned equation has rather general form and contains, as particular cases, a lot of fractional functional equations and nonlinear fractional integral equations of Volterra type. The main technique used in our considerations is the measures of noncompactness and a fixed point theorem of Dhage [3]. Our investigations will be situated in the Banach space of real functions which are defined, continuous, and bounded on the right-hand real half axis \mathbb{R}_+ .

The measures of noncompactness used in this paper allow us not only to obtain the existence of solutions of the mentioned fractional functional integral equations but also to characterize those solutions in terms of global attractivity and positivity on unbounded intervals. This assertion means that all possible solutions of the equations in question are globally uniformly attractive and positive in the sense which will be defined further on.

It is worthwhile mentioning that the novelty of our approach consists mainly in the possibility of obtaining the global attractivity, asymptotic attractivity, and positivity of solutions for the considered fractional functional integral equations. We hope that the concept of measure of noncompactness considered here may be a stimulant for further investigations concerning solutions of nonlinear fractional differential and integral equations of other types.

2. Notations, Definitions, and Auxiliary Facts

This section is devoted to collect some notations, definitions, and auxiliary facts which will be used in the further considerations of this paper.

Let *E* be a Banach space, $\mathscr{P}(E)$, a class of subsets of *E* and let $\mathscr{P}_p(E)$ denote the class of all nonempty subsets of *E* with property *p*. Here *p* may be *p* = closed (in short cl), *p* = bounded (in short bd), *p* = relatively compact (in short rcp), and so forth. Thus, $\mathscr{P}_{cl}(E)$, $\mathscr{P}_{bd}(E)$, $\mathscr{P}_{cl,bd}(E)$, and $\mathscr{P}_{rcp}(E)$ denote, respectively, the classes of closed, bounded, closed and bounded, and relatively compact subsets of *E*. A function $d_H : \mathscr{P}(E) \times \mathscr{P}(E) \to \mathbb{R}_+$ defined by

$$d_{H}(A,B) = \max\left\{\sup_{a\in A} D(a,B), \sup_{b\in B} D(b,A)\right\}$$
(1)

satisfies all the conditions of a metric on $\mathscr{P}(E)$ and is called a Hausdorff-Pompeiu metric on *E*, where $D(a, B) = \inf\{||a - b|| : b \in B\}$. It is known that the hyperspace $(\mathscr{P}_{cl}(E), d_H)$ is a complete metric space.

The auxiliary way of defining the measures of noncompactness has been adopted in several papers in the literature; see Akhmerov et al. [39], Appell [40], Banaś and Goebel [41], in the works Väth [42] and the references therein. In this paper, we adopt the following axiomatic definition of the measure of noncompactness in a Banach space given by Dhage [3]. The other useful forms appear in the work of Banaś and Goebel [41] and the references therein.

Before giving definition of measure of noncompactness, we need the following definitions.

Definition 1 (see [43]). A sequence $\{A_n\}$ of nonempty sets in $\mathscr{P}_p(E)$ is said to converge to a set A, called the limiting set if $d_H(A_n, A) \to 0$ as $n \to \infty$. A mapping $\mu : \mathscr{P}_p(E) \to \mathbb{R}_+$ is called continuous if for any sequence $\{A_n\}$ in $\mathscr{P}_p(E)$ one has that

$$d_H(A_n, A) \longrightarrow 0 \Longrightarrow |\mu(A_n) - \mu(A)| \longrightarrow 0 \quad \text{as } n \longrightarrow \infty.$$
(2)

Definition 2 (see [43]). A mapping μ : $\mathscr{P}_p(E) \to \mathbb{R}_+$ is called nondecreasing, if for *A*, *B* ∈ $\mathscr{P}_p(E)$ with *A* ⊆ *B*, then $\mu(A) \le \mu(B)$, where ⊆ is an order relation by inclusion $\mathscr{P}_p(E)$.

Now we are equipped with the necessary details to define the measures of noncompactness for a bounded subset of the Banach space *E*.

Definition 3 (see [43]). A function $\mu : \mathscr{P}_p(E) \to \mathbb{R}_+$ is called a measure of noncompactness if it satisfies $1^o \emptyset \neq \mu^{-1}(0) \subset \mathscr{P}_{\rm rcp}(E), 2^o \mu(A) = \mu(\overline{A})$, where \overline{A} is the closure of A, $3^o \mu(A) = \mu({\rm Conv}(A))$, where ${\rm Conv}(A)$ is the convex hull of A and $4^o \mu$ is nondecreasing, and 5^o if $\{A_n\}$ is a decreasing sequence of sets in $\mathscr{P}_{\mathrm{bd}}(E)$ such that $\lim_{n\to\infty} (A_n) = 0$, then the limiting set $A_{\infty} = \lim_{n\to\infty} \overline{A}_n = \bigcap_{n=0}^{\infty} \overline{A}_n$ is nonempty.

The family ker μ described in 1° is said to be the kernel of μ and

$$\ker \mu = \{A \in \mathscr{P}_{bd}(E) \mid \mu(A) = 0\} \subset \mathscr{P}_{rcp}(E).$$
(3)

A measure μ is called complete or full if the kernel ker μ of μ consists of all possible relatively compact subsets of *E*. Next, a measure μ is called sublinear if it satisfies

$$6^{o}\mu(\lambda A) = |\lambda|\mu(A) \quad \text{for } \lambda \in \mathbb{R},$$

$$7^{o}\mu(A+B) \le \mu(A) + \mu(B).$$
(4)

There do exist the sublinear measures of noncompactness on Banach spaces E. Indeed, the Kuratowskii and Hausdorff measures of noncompactness are sublinear in E. A good collection of different types of measures of noncompactness appears in Appell [40].

Observe that the limiting set A_{∞} from 5° is a member of the family ker μ . In fact, since

$$\mu(A_{\infty}) \le \mu(\overline{A}_n) = \mu(A_n), \quad \text{for any } n, \tag{5}$$

one infers that $\mu(A_{\infty}) = 0$. This yields that $A_{\infty} \in \ker \mu$. This simple observation will be essential in our further investigations.

Now we state a key fixed point theorem of Dhage [3] which will be used in the sequel. Before stating this fixed point result, we give a useful definition.

Definition 4 (see [43]). A mapping $Q : E \to E$ is called *D*-set-Lipschitz if there exists a continuous nondecreasing function $\varphi : \mathbb{R}_+ \to \mathbb{R}_+$ such that $\mu(Q(A)) \leq \varphi(\mu(A))$ for all $A \in \mathscr{P}_{bd}(E)$ with $Q(A) \in \mathscr{P}_{bd}(E)$, where $\varphi(0) = 0$. Sometimes we call the function φ to be a *D*-function of *Q* on *E*. In the special case, when $\varphi(r) = kr, k > 0, Q$ is called a *k*-set-Lipschitz mapping, and if k < 1, then *Q* is called a *k*set-contraction on *E*. Further, if $\varphi(r) < r$ for r > 0, then *Q* is called a nonlinear *D*-set-contraction on *E*.

Theorem 5 (see, Dhage [43]). Let C be a nonempty, closed, convex, and bounded subset of a Banach space E and let Q : $C \rightarrow C$ be a continuous and nonlinear D-set-contraction. Then Q has a fixed point.

Remark 6. Denote by Fix(*Q*) the set of all fixed points of the operator *Q* which belong to *C*. It can be shown that the set Fix(*Q*) existing in Theorem 5 belongs to the family ker μ . In fact if Fix(*Q*) \notin ker μ , then μ (Fix(*Q*)) > 0 and *Q*(Fix(*Q*)) = Fix(*Q*). Now from nonlinear *D*-set-contraction it follows that μ (*Q*(Fix(*Q*))) $\leq \varphi(\mu$ (Fix(*Q*))) which is a contradiction, since $\varphi(r) < r$ for r > 0. Hence, Fix(*Q*) \in ker μ .

Our further considerations will be placed in the Banach space $BC(\mathbb{R}_+, \mathbb{R})$ consisting of all real functions x = x(t) defined, continuous, and bounded on \mathbb{R}_+ . This space is equipped with the standard supremum norm $||x|| = \sup\{|x(t)| : t \in \mathbb{R}_+\}$.

For our purposes we will use the Hausdorff or ball measure of noncompactness in $BC(\mathbb{R}_+, \mathbb{R})$. A handy formula for

Hausdorff measure of noncompactness useful in application is defined as follows. Fix a nonempty and bounded subset *X* of the space $BC(\mathbb{R}_+, \mathbb{R})$ and a positive number *T*. For $x \in X$ and $\varepsilon > 0$, denote by $\omega^T(x, \varepsilon)$ the modulus of continuity of the function *x* on the closed and bounded interval [0, T] defined by

$$\omega^{T}(x,\varepsilon) = \sup\left\{ |x(t) - x(s)| : t, s \in [0,T], |t-s| < \varepsilon \right\}.$$
(6)

Next, put

$$\omega^{T}(X,\varepsilon) = \sup \left\{ \omega^{T}(x,\varepsilon) : x \in X \right\},$$

$$\omega_{0}^{T}(X) = \lim_{\varepsilon \to 0} \omega^{T}(X,\varepsilon).$$
 (7)

It is known that ω_0^T is a measure of noncompactness in the Banach space $C([0, T], \mathbb{R})$ of continuous and real-valued functions defined on a closed and bounded interval [0, T]in \mathbb{R} which is equivalent to Hausdorff or ball measure χ of noncompactness in it. In fact, one has $\chi(X) = (1/2)\omega_0^T(X)$ for any bounded subset X of $C([0, T], \mathbb{R})$ (see Banaś and Goebel [41] and the references therein). Finally, define $\omega_0(X) = \lim_{T \to \infty} \omega_0^T(X)$.

Now, for a fixed number $t \in \mathbb{R}_+$, denote

$$X(t) = \{x(t) : x \in X\},\$$
$$\|X(t)\| = \sup\{|x(t)| : x \in X\},\$$
(8)
$$\|X(t) - c\| = \sup\{|x(t) - c| : x \in X\}.$$

Finally, consider the functions μ 's defined on the family $\mathscr{P}_{cl.bd}(X)$ by the formulas

$$\mu_a(X) = \max\left\{\omega_0(X), \limsup_{t \to \infty} \operatorname{diam} X(t)\right\}, \qquad (9)$$

$$\mu_b(X) = \max\left\{\omega_0(X), \limsup_{t \to \infty} \|X(t)\|\right\}, \qquad (10)$$

$$\mu_{c}(X) = \max\left\{\omega_{0}(X), \limsup_{t \to \infty} \|X(t) - c\|\right\}.$$
(11)

Let T > 0 be fixed. Then for any $x \in BC(\mathbb{R}_+, \mathbb{R})$, define $\delta_T(x) = \sup\{||x(t)| - x(t)| : t \ge T\}$. Similarly, for any bounded subset X of $BC(\mathbb{R}_+, \mathbb{R})$, define

$$\delta_T (X) = \sup \left\{ \delta_T (x) : x \in X \right\},$$

$$\delta (X) = \lim_{T \to \infty} \delta_T (X).$$
 (12)

Define the functions μ_{ad} , μ_{bd} , $\mu_{cd} : \mathscr{P}_{bd}(E) \to \mathbb{R}_+$ by the formulas

$$\mu_{ad} (X) = \max \{ \mu_a (X), \delta (X) \}, \mu_{bd} (X) = \max \{ \mu_b (X), \delta (X) \},$$
(13)
$$\mu_{cd} (X) = \max \{ \mu_c (X), \delta (X) \},$$

for all $X \in \mathscr{P}_{cl,bd}(E)$.

Remark 7. It can be shown as in Banaś and Goebel [41] that the functions μ_a , μ_b , μ_c , μ_{ad} , μ_{bd} , and μ_{cd} are measures of noncompactness in the space $BC(\mathbb{R}_+,\mathbb{R})$. The kernels ker μ_a , ker μ_b , and ker μ_c of the measures μ_a , μ_b , and μ_c consist of nonempty and bounded subsets X of $BC(\mathbb{R}_+, \mathbb{R})$ such that functions from X are locally equicontinuous on \mathbb{R}_{\perp} and the thickness of the bundle formed by functions from X tends to zero at infinity. Moreover, the functions from ker μ_c come closer along a line y(t) = c and the functions from ker μ_b come closer along the line y(t) =0 as t increases to ∞ through \mathbb{R}_+ . A similar situation is also true for the kernels $\ker\mu_{\rm ad},\,\ker\mu_{\rm bd},\,{\rm and}\,\ker\mu_{\rm cd}$ of the measures of noncompactness μ_{ad} , μ_{bd} , and μ_{cd} . Moreover, these measures μ_{ad} , μ_{bd} , and μ_{cd} characterize the ultimate positivity of the functions belonging to the kernels of $\ker\mu_{\rm ad},$ ker μ_{bd} , and ker μ_{cd} . The above expressed property of ker μ_a , ker μ_b , ker μ_c , and ker μ_{ad} , ker μ_{bd} , ker μ_{cd} permits us to characterize solutions of the fractional functional integral equations considered in the sequel.

In order to introduce further concepts used in this paper, let us assume that $E = BC(\mathbb{R}_+, \mathbb{R})$ and let Ω be a subset of X. Let $Q : E \to E$ be an operator and consider the following operator equation in E:

$$Qx(t) = x(t), \quad \forall t \in \mathbb{R}_+.$$
(14)

Below we give different characterizations of the solutions for (14) on \mathbb{R}_+ .

Definition 8. We say that solutions of (14) are locally attractive if there exists a closed ball $B_r(x_0)$ in the space $BC(\mathbb{R}_+, \mathbb{R})$ for some $x_0 \in BC(\mathbb{R}_+, \mathbb{R})$ such that for arbitrary solutions x = x(t) and y = y(t) of (14) belonging to $B_r(x_0) \cap \Omega$ one has that

$$\lim_{t \to \infty} \left(x\left(t\right) - y\left(t\right) \right) = 0.$$
(15)

In the case when the limit (15) is uniform with respect to the set $B_r(x_0) \cap \Omega$, that is, when for each $\varepsilon > 0$ there exists T > 0 such that

$$\left|x\left(t\right) - y\left(t\right)\right| < \varepsilon,\tag{16}$$

for all $x, y \in B_r(x_0) \cap \Omega$ being solutions of (14) and for all $t \ge T$, we will say that solutions of (14) are uniformly locally attractive on \mathbb{R}_+ .

Definition 9. The solution x = x(t) of (14) is said to be globally attractive if (15) holds for each solution y = y(t) of (14) on Ω . In other words, we may say that solutions of (14) are globally attractive, if for arbitrary solutions x(t) and y(t)of (14) on Ω , the condition (15) is satisfied. In the case when the condition (15) is satisfied uniformly with respect to the set Ω , that is, if for every $\varepsilon > 0$ there exists T > 0 such that the inequality (16) is satisfied for all $x, y \in \Omega$ being the solutions of (14) and for all $t \ge T$, we will say that solutions of (14) are uniformly globally attractive on \mathbb{R}_+ . The following definitions appear in the work of Dhage [7].

Definition 10. A line y(t) = c, where *c* is a real number, is called an attractor for a solution $x \in BC(\mathbb{R}_+, \mathbb{R})$ to (14) if $\lim_{t\to\infty} [x(t) - c] = 0$. In this case the solution *x* to (14) is also called to be asymptotic to the line y(t) = c and the line is an asymptote for the solution *x* on \mathbb{R}_+ .

Now we introduce the following definitions which are useful in the sequel.

Definition 11. The solutions of (14) are said to be globally asymptotically attractive if for any two solutions x = x(t) and y = y(t) of (14), the condition (15) is satisfied, and there is a line which is a common attractor to them on \mathbb{R}_+ . In the case when condition (15) is satisfied uniformly, that is, if for every $\varepsilon > 0$ there exists T > 0 such that the inequality (16) is satisfied for all $t \ge T$ and for all x, y being the solutions of (14) and having a line as a common attractor, we will say that solutions of (14) are uniformly globally asymptotically attractive on \mathbb{R}_+ .

Definition 12. A solution *x* of (14) is called locally ultimately positive if there exists a closed ball $B_r(x_0)$ in $BC(\mathbb{R}_+, \mathbb{R})$ for some $x_0 \in BC(\mathbb{R}_+, \mathbb{R})$ such that $x \in B_r(x_0)$ and

$$\lim_{t \to \infty} ||x(t)| - x(t)| = 0.$$
(17)

In the case when the limit (17) is uniform with respect to the solution set of the operator equation (14), that is, when for each $\varepsilon > 0$ there exists T > 0 such that

$$||x(t)| - x(t)| < \varepsilon, \tag{18}$$

for all *x* being solutions of (14) and for all $t \ge T$, we will say that solutions of (14) are uniformly locally ultimately positive on \mathbb{R}_+ .

Definition 13. A solution $x \in C(\mathbb{R}_+, \mathbb{R})$ of (14) is called globally ultimately positive if (17) is satisfied. In the case when the limit (17) is uniform with respect to the solution set of the operator equation (14) in $C(\mathbb{R}_+, \mathbb{R})$, that is, when for each $\varepsilon > 0$ there exists T > 0 such that (18) is satisfied for all x being solutions of (14) and for all $t \ge T$, we will say that solutions of (14) are uniformly globally ultimately positive on \mathbb{R}_+ .

Remark 14. Note that the global attractivity and global asymptotic attractivity imply, respectively, the local attractivity and local asymptotic attractivity of the solutions for the operator equation (14) on \mathbb{R}_+ . Similarly, global ultimate positivity implies local ultimate positivity of the solutions for the operator equation (14) on unbounded intervals. However, the converse of the above two statements may not be true. A few details of ultimate positivity are given in the work of Dhage [44].

Finally, we introduce the concept of the fraction integral and the Riemann-Liouville fractional derivative.

Definition 15 (see [45, 46]). The fractional integral of order $\alpha > 0$ with the lower limit t_0 for a function f is defined as

$$I^{\alpha}f(t) = \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} f(s) \, \mathrm{d}s, \quad t > t_0,$$
(19)

provided the right-hand side is pointwise on $[t_0, \infty)$, where $\Gamma(\alpha)$ is the Gamma function.

Definition 16 (see [45, 46]). The Riemann-Liouville derivative of order $\alpha > 0$ with the lower limit t_0 for a function $f : [t_0, \infty) \to \mathbb{R}$ can be written as

$$D_{t}^{\alpha} f(t) = \frac{1}{\Gamma(n-\alpha)} \frac{d^{n}}{dt^{n}} \int_{t_{0}}^{t} (t-s)^{\alpha+1-n} f(s) \, \mathrm{d}s,$$

$$t > t_{0}, \ n-1 < \alpha < n.$$
(20)

The first and maybe the most important property of the Riemann-Liouville fractional derivative is that for $t > t_0$ and $\alpha > 0$, one has $D^{\alpha}(I^{\alpha}f(t)) = f(t)$, which means that the Riemann-Liouville fractional differentiation operator is a left inverse to the Riemann-Liouville fractional integration operator of the same order α .

In the following section we prove the main results of this paper.

3. Attractivity and Positivity Results

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1.5

In this section we will investigate the following functional integral equation of fractional order with deviating arguments:

$$x(t) = q(t) + f_{1}(t, x(\alpha_{1}(t)), x(\alpha_{2}(t))) + \frac{f_{2}(t, x(\beta_{1}(t)), x(\beta_{2}(t)))}{\Gamma(\alpha)}$$

$$\times \int_{0}^{t} (t - s)^{\alpha - 1} f_{3}(t, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) ds,$$
(21)

where $t \in \mathbb{R}_+, q : \mathbb{R}_+ \to \mathbb{R}, f_1, f_2 : \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}, f_3 : \mathbb{R}_+ \times \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}, \alpha_1, \alpha_2, \beta_1, \beta_2, \gamma_1, \gamma_2 : \mathbb{R}_+ \to \mathbb{R}_+, \alpha \in (0, 1), \text{ and } \Gamma(\alpha) \text{ denotes the Gamma function.}$

Equation (21) has rather general form, when

$$f_{1}(t, x(\alpha_{1}(t)), x(\alpha_{2}(t))) = 0,$$

$$f_{2}(t, x(\beta_{1}(t)), x(\beta_{2}(t))) = f(t, x(t)),$$

$$f_{3}(t, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) = u(t, s, x(t)).$$

(22)

Equation (21) reduces to the following quadratic Volterra integral equation of fractional order

$$x(t) = q(t) + \frac{f(t, x(t))}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha - 1} u(t, s, x(s)) \, \mathrm{d}s.$$
(23)

Equation (23) has been studied in the work of Banaś and O'Regan [47] for the existence and local attractivity of solutions via classical hybrid fixed point theory, when

$$q(t) = 0,$$

$$f_{1}(t, x(\alpha_{1}(t)), x(\alpha_{2}(t))) = g(t, x(\eta(t))),$$

$$f_{2}(t, x(\beta_{1}(t)), x(\beta_{2}(t))) = f(t, x(\beta(t))),$$

$$f_{3}(t, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) = h(t, s) u(s, x(\gamma(s))).$$
(24)

Equation (21) reduces to the following functional integral equation of fractional order considered in Balachandran et al. [48] for the local attractivity of solutions

$$x(t) = g(t, x(\eta(t))) + \frac{f(t, x(\beta(t)))}{\Gamma(\alpha)}$$

$$\times \int_{0}^{t} (t-s)^{\alpha-1} h(t, s) u(s, x(\gamma(s))) ds.$$
(25)

Therefore, (21) is more general and contains as particular cases a lot of fractional functional equations and nonlinear fractional integral equations of Volterra type.

By a solution of (21) we mean a function $x \in C(\mathbb{R}_+, \mathbb{R})$ that satisfies (21), where $C(\mathbb{R}_+, \mathbb{R})$ is the space of continuous real-valued functions defined on \mathbb{R}_+ .

Equation (21) will be considered under the following assumptions.

 (H_0) the functions $\alpha_1, \alpha_2, \beta_1, \beta_2 : \mathbb{R}_+ \to \mathbb{R}_+$ are continuous and satisfy

$$\begin{aligned} &\alpha_1(t), \alpha_2(t), \beta_1(t), \beta_2(t) \ge t, \\ &\alpha_1(t), \alpha_2(t), \beta_1(t), \beta_2(t) \longrightarrow \infty \quad \text{as } t \longrightarrow \infty. \end{aligned}$$

 (H_1) the function $q: \mathbb{R}_+ \to \mathbb{R}$ is continuous and bounded.

 (H_2) the function $f_1 : \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ is continuous and there exists a bounded function $\ell : \mathbb{R}_+ \to \mathbb{R}$ with bound L and a positive constant M such that

$$|f_{1}(t, x_{1}, y_{1}) - f_{1}(t, x_{2}, y_{2})|$$

$$\leq \frac{\ell(t) \max\{|x_{1} - x_{2}|, |y_{1} - y_{2}|\}}{M + \max\{|x_{1} - x_{2}|, |y_{1} - y_{2}|\}},$$
(27)

for all $t \in \mathbb{R}_+$ and $x_1, x_2, y_1, y_2 \in \mathbb{R}$. Moreover, we assume that $L \leq M$.

 (H_3) the function $f_2 : \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ is continuous and there exists a function $m : \mathbb{R}_+ \to \mathbb{R}_+$ being continuous on \mathbb{R}_+ and such that

$$|f_{2}(t, x_{1}, y_{1}) - f_{2}(t, x_{2}, y_{2})|$$

$$\leq m(t) (|x_{1} - x_{2}| + |y_{1} - y_{2}|), \qquad (28)$$

for all $t \in \mathbb{R}_+$ and $x_1, x_2, y_1, y_2 \in \mathbb{R}$.

 (H_4) the function $F_1(t) = f_1(t, 0, 0)$ is bounded with $F_1 = \sup\{|f_1(t, 0, 0)| : t \in \mathbb{R}_+\}.$

 (H_5) the function $f_3 : \mathbb{R}_+ \times \mathbb{R}_+ \times \mathbb{R} \to \mathbb{R}$ is continuous and there exists a function $n : \mathbb{R}_+ \to \mathbb{R}_+$ being continuous on \mathbb{R}_+ and a function $\varphi : \mathbb{R}_+ \to \mathbb{R}_+$ being continuous and nondecreasing on \mathbb{R}_+ with $\varphi(0) = 0$ such that

$$|f_{3}(t, s, x_{1}, y_{1}) - f_{3}(t, s, x_{2}, y_{2})| \\\leq n(t) \varphi(|x_{1} - x_{2}| + |y_{1} - y_{2}|),$$
(29)

for all $t \in \mathbb{R}_+$ and $x_1, x_2, y_1, y_2 \in \mathbb{R}$.

For further purposes, define the functions $F_2 : \mathbb{R}_+ \to \mathbb{R}_+$ by putting $F_2(t) = f_2(t, 0, 0)$ and $F_3 : \mathbb{R}_+ \to \mathbb{R}_+$ by putting $F_3(t) = \max\{|f_3(t, s, 0, 0)| : 0 \le s \le t\}$. Obviously the functions F_2 and F_3 are continuous on \mathbb{R}_+ .

 (H_6) the functions $a, b, c, d : \mathbb{R}_+ \to \mathbb{R}_+$ defined by the formulas

$$a(t) = 2m(t)n(t)t^{\alpha}, \qquad b(t) = 2m(t)F_{3}(t)t^{\alpha},$$

$$c(t) = n(t)|F_{2}(t)|t^{\alpha}, \qquad d(t) = |F_{2}(t)|F_{3}(t)t^{\alpha}$$
(30)

are bounded on \mathbb{R}_+ and the functions a(t), b(t), c(t), d(t) vanish at infinity, that is,

$$\lim_{t \to \infty} a(t) = \lim_{t \to \infty} b(t) = \lim_{t \to \infty} c(t) = \lim_{t \to \infty} d(t) = 0.$$
(31)

Keeping in mind assumption (H_6) , define the following finite constants:

$$A = \sup \{a(t) : t \in \mathbb{R}_{+}\}, \qquad B = \sup \{b(t) : t \in \mathbb{R}_{+}\},$$

$$C = \sup \{c(t) : t \in \mathbb{R}_{+}\}, \qquad D = \sup \{d(t) : t \in \mathbb{R}_{+}\}.$$
(32)

Now we formulate the last assumption.

 (H_7) There exists a positive solution r_0 of the inequality

$$\left\|q\right\| + \frac{Lr}{M+r} + F_1 + \frac{Ar\varphi\left(2r\right) + Br + C\varphi\left(2r\right) + D}{\Gamma\left(\alpha + 1\right)} < r.$$
(33)

Remark 17. Hypothesis (H_2) is satisfied if in particular f_1 satisfies the condition,

$$|f_{1}(t, x_{1}, y_{1}) - f_{1}(t, x_{2}, y_{2})|$$

$$\leq \frac{\ell(t) [|x_{1} - x_{2}| + |y_{1} - y_{2}|]}{2M + [|x_{1} - x_{2}| + |y_{1} - y_{2}|]},$$
(34)

for all $t \in \mathbb{R}_+$ and $x_1, x_2, y_1, y_2 \in \mathbb{R}$, where $L \leq M$, and the function ℓ is defined as in hypothesis (H_2) which further yields the usual Lipschitz condition on the function f_1 ,

$$\left|f_{1}(t, x_{1}, y_{1}) - f_{1}(t, x_{2}, y_{2})\right| \leq \frac{\ell(t)}{2M} \left[\left|x_{1} - x_{2}\right| + \left|y_{1} - y_{2}\right|\right],$$
(35)

for all $t \in \mathbb{R}_+$ and $x_1, x_2, y_1, y_2 \in \mathbb{R}$ provided L < M. As mentioned in the work of Dhage [11], our hypothesis (H_2) is more general than that existing in the literature.

Now, consider the operators *F*, *G*, *U*, and *Q* defined on the space $BC(\mathbb{R}_+, \mathbb{R})$:

$$(Gx) (t) = q(t) + f_1 (t, x (\alpha_1 (t)), (\alpha_2 (t))),$$

$$(Fx) (t) = f_2 (t, x (\beta_1 (t)), (\beta_2 (t))),$$

$$(Ux) (t) = \frac{1}{\Gamma (\alpha)} \int_0^t (t - s)^{\alpha - 1} f_3 (t, s, x (\gamma_1 (s)), x (\gamma_2 (s))) ds,$$

$$(Qx) (t) = (Gx) (t) + (Fx) (t) (Ux) (t).$$

(36)

Then one has the following lemma.

Lemma 18. Under the above assumptions the operator Q transforms the ball B_{r_0} in the space $BC(\mathbb{R}_+, \mathbb{R})$ into itself. Moreover, all solutions of (21) belonging to the space $BC(\mathbb{R}_+, \mathbb{R})$ are fixed points of the operator Q.

Proof. Observe that for any function $x \in BC(\mathbb{R}_+, \mathbb{R})$, Gx and Fx are continuous on \mathbb{R}_+ . We show that the same holds also for Ux. Take an arbitrary function $x \in BC(\mathbb{R}_+, \mathbb{R})$ and fix T > 0, $\varepsilon > 0$. Next assume that $t_1, t_2 \in [0, T]$ such that $|t_2 - t_1| < \varepsilon$. Without loss of generality one can assume that $t_1 < t_2$. Then, in view of imposed assumptions, one has

$$\begin{split} |(Ux)(t_{2}) - (Ux)(t_{1})| \\ &= \frac{1}{\Gamma(\alpha)} \left| \int_{0}^{t_{1}} (t_{2} - s)^{\alpha - 1} f_{3}(t_{2}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) ds \right. \\ &+ \int_{t_{1}}^{t_{2}} (t_{2} - s)^{\alpha - 1} f_{3}(t_{2}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) ds \\ &- \int_{0}^{t_{1}} (t_{1} - s)^{\alpha - 1} f_{3}(t_{1}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) ds \right| \\ &\leq \frac{1}{\Gamma(\alpha)} \int_{0}^{t_{1}} \left| (t_{2} - s)^{\alpha - 1} f_{3}(t_{2}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) - (t_{2} - s)^{\alpha - 1} f_{3}(t_{1}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) \right| ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_{0}^{t_{1}} \left| (t_{2} - s)^{\alpha - 1} f_{3}(t_{1}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) - (t_{1} - s)^{\alpha - 1} f_{3}(t_{1}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) \right| ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_{0}^{t_{2}} \left| (t_{2} - s)^{\alpha - 1} f_{3}(t_{2}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) \right| ds \\ &\leq \frac{1}{\Gamma(\alpha)} \int_{0}^{t_{1}} (t_{2} - s)^{\alpha - 1} \left| f_{3}(t_{2}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) \right| ds \\ &\leq \frac{1}{\Gamma(\alpha)} \int_{0}^{t_{1}} \left| f_{3}(t_{1}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) \right| ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_{0}^{t_{1}} \left| f_{3}(t_{1}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) \right| ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_{0}^{t_{1}} \left| f_{3}(t_{1}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) \right| ds \end{split}$$

$$+ \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha - 1} |f_3(t_2, s, x(\gamma_1(s)), x(\gamma_2(s)))| ds$$

$$\leq \frac{1}{\Gamma(\alpha)} \int_0^{t_1} \omega_1^T (f_3, \varepsilon, ||x||) (t_2 - s)^{\alpha - 1} ds$$

$$+ \frac{1}{\Gamma(\alpha)} \int_0^{t_1} (|f_3(t_1, s, x(\gamma_1(s)), x(\gamma_2(s))) - f_3(t_1, s, 0, 0)| + F_3(t_1))$$

$$\times [(t_1 - s)^{\alpha - 1} - (t_2 - s)^{\alpha - 1}] ds$$

$$+ \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha - 1} (|f_3(t_2, s, x(\gamma_1(s)), x(\gamma_2(s))) - f_3(t_2, s, 0, 0)| + F_3(t_2)) ds$$

$$\leq \frac{\omega_{1}^{t} (f_{3}, \varepsilon, \|x\|)}{\Gamma(\alpha)} \frac{t_{2}^{\alpha} - (t_{2} - t_{1})^{\alpha}}{\alpha} + \frac{1}{\Gamma(\alpha)}$$

$$\times \int_{0}^{t_{1}} [n(t_{1}) \varphi(2\|x\|) + F_{3}(t_{1})]$$

$$\times [(t_{1} - s)^{\alpha - 1} - (t_{2} - s)^{\alpha - 1}] ds$$

$$+ \frac{1}{\Gamma(\alpha)} \int_{t_{1}}^{t_{2}} (t_{2} - s)^{\alpha - 1} [n(t_{2}) \varphi(2\|x\|) + F_{3}(t_{2})] ds$$

$$\leq \frac{\omega_{1}^{T} (f_{3}, \varepsilon, \|x\|)}{\Gamma(\alpha + 1)} t_{1}^{\alpha} + \frac{n(t_{1}) \varphi(2\|x\|) + F_{3}(t_{1})}{\Gamma(\alpha + 1)}$$

$$\times [t_{1}^{\alpha} - t_{2}^{\alpha} + (t_{2} - t_{1})^{\alpha}]$$

$$+ \frac{n(t_{2}) \varphi(2\|x\|) + F_{3}(t_{2})}{\Gamma(\alpha + 1)} (t_{2} - t_{1})^{\alpha}$$

$$\leq \frac{1}{\Gamma(\alpha + 1)} \left\{ t_{1}^{\alpha} \omega_{1}^{T} (f_{3}, \varepsilon, \|x\|) + (t_{2} - t_{1})^{\alpha} \\\times [n(t_{1}) \varphi(2\|x\|) + F_{3}(t_{1})] \\+ (t_{2} - t_{1})^{\alpha} [n(t_{2}) \varphi(2\|x\|) + F_{3}(t_{2})] \right\},$$
(37)

where

$$\omega_{1}^{T}(f_{3},\varepsilon,\|x\|) = \sup \left\{ \left| f_{3}(t_{2},s,y_{1},y_{2}) - f_{3}(t_{1},s,y_{1},y_{2}) \right| : s,t_{1},t_{2} \in [0,T], \\ s \le t_{1}, s \le t_{2}, \left| t_{2} - t_{1} \right| \le \varepsilon, \left| y_{1} \right| \le \|x\|, \left| y_{2} \right| \le \|x\| \right\}.$$
(38)

Obviously, in view of the uniform continuity of $f_3(t, s, y_1, y_2)$ on the set $[0, T] \times [0, T] \times [-\|x\|, \|x\|] \times [-\|x\|, \|x\|]$, one has that $\omega_1^T(f_3, \varepsilon, \|x\|) \to 0$ as $\varepsilon \to 0$. In what follows, denote

$$\overline{n}(T) = \max\{n(t) : t \in [0, T]\},\$$

$$\overline{F}_{3}(T) = \max\{F_{3}(t) : t \in [0, T]\}.$$
(39)

Then, keeping in mind the estimate (37) one obtains

$$\left| (Ux) \left(t_{2} \right) - (Ux) \left(t_{1} \right) \right|$$

$$\leq \frac{1}{\Gamma \left(\alpha + 1 \right)} \left\{ T^{\alpha} \omega_{1}^{T} \left(f_{3}, \varepsilon, \|x\| \right) + 2\varepsilon^{\alpha} \left[\overline{n} \left(T \right) \varphi \left(2 \|x\| \right) + \overline{F}_{3} \left(T \right) \right] \right\}.$$

$$(40)$$

From the above inequality one can infer that the function Ux is continuous on the interval [0, T] for any T > 0. This yields the continuity of Ux on \mathbb{R}_+ .

Finally, combining the continuity of the functions Gx, Fx, and Ux, one deduces that the function Qx is continuous on on \mathbb{R}_+ .

Now, taking an arbitrary function $x \in BC(\mathbb{R}_+, \mathbb{R})$, then, using our assumptions, for a fixed $t \in \mathbb{R}_+$, one has

$$\begin{split} |Qx(t)| \\ &\leq |q(t)| + |f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))| \\ &+ \frac{|f_2(t, x(\beta_1(t)), x(\beta_2(t)))|}{\Gamma(\alpha)} \\ &\times \int_0^t (t-s)^{\alpha-1} |f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s)))| \, ds \\ &\leq |q(t)| + |f_1(t, x(\alpha_1(t)), x(\alpha_2(t))) - F_1(t)| + F_1 \\ &+ \frac{1}{\Gamma(\alpha)} \left[|f_2(t, x(\beta_1(t)), (\beta_2(t))) - F_2(t)| + |F_2(t)| \right] \\ &\times \int_0^t (t-s)^{\alpha-1} \left[|f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s))) \\ &- f_3(t, s, 0, 0) | + F_3(t) \right] \, ds \\ &\leq ||q|| + \frac{\ell(t) \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}}{M + \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}} + F_1 \\ &+ \frac{2 ||x|| m(t) + |F_2(t)|}{\Gamma(\alpha)} \\ &\times \int_0^t (t-s)^{\alpha-1} \left[n(t) \varphi(2 ||x||) + F_3(t) \right] \, ds \\ &\leq ||q|| + \frac{L ||x||}{M + ||x||} + F_1 + \frac{2 ||x|| m(t) + |F_2(t)|}{\Gamma(\alpha)} \\ &\times \left[n(t) \varphi(2 ||x||) + F_3(t) \right] \int_0^t (t-s)^{\alpha-1} \, ds \\ &\leq ||q|| + \frac{L ||x||}{M + ||x||} + F_1 \\ &+ (t^{\alpha} \left[2m(t) n(t) ||x|| \varphi(2 ||x||) \\ &+ 2 ||x|| m(t) F_3(t) + |F_2(t)| n(t) \varphi(2 ||x||) \\ &+ |F_2(t)| F_3(t) \right]) \times (\Gamma(\alpha+1))^{-1} \end{split}$$

$$\leq \|q\| + \frac{L \|x\|}{M + \|x\|} + F_1 + \frac{a(t) \|x\| \varphi(2\|x\|) + b(t) \|x\| + c(t) \varphi(2\|x\|) + d(t)}{\Gamma(\alpha + 1)}.$$
(41)

Hence, in view of assumption (H_6) one can infer that the function Qx is bounded on \mathbb{R}_+ . This assertion in conjunction with the continuity of Qx on \mathbb{R}_+ allows us to conclude that $Qx \in BC(\mathbb{R}_+,\mathbb{R})$. Moreover, from the estimate (41) one obtains

$$\begin{aligned} |Qx(t)| &\leq \left\|q\right\| + \frac{L \|x\|}{M + \|x\|} \\ &+ F_1 + \frac{A \|x\| \varphi(2 \|x\|) + B \|x\| + C\varphi(2 \|x\|) + D}{\Gamma(\alpha + 1)}. \end{aligned}$$
(42)

Linking this estimate with assumption (H_7) , one deduces that there exists $r_0 > 0$ such that the operator Q transforms the ball B_{r_0} into itself.

Finally, let us notice that the second assertion of our lemma is obvious in the light of the fact that the operator Q transforms the space $BC(\mathbb{R}_+, \mathbb{R})$ into itself. The proof is complete.

Now, we are prepared to state and prove our main theorem of this section.

Theorem 19. Under the above assumptions $(H_0)-(H_7)$, (21) has at least one solution in the space $BC(\mathbb{R}_+, \mathbb{R})$. Moreover, these solutions are globally uniformly attractive on \mathbb{R}_+ .

Proof. In what follows we will consider the operator Q as a mapping from B_{r_0} into itself. Now we show that the operator Q is continuous on the ball B_{r_0} . To do this, fix arbitrarily $\varepsilon > 0$ and take $x, y \in B_{r_0}$ such that $||x - y|| < \varepsilon$. Then one gets

$$\begin{aligned} Qx(t) - Qy(t) \\ &= |f_1(t, x(\alpha_1(t)), x(\alpha_2(t))) \\ &- f_1(t, y(\alpha_1(t)), y(\alpha_2(t))) | \\ &+ \left| \frac{f_2(t, x(\beta_1(t)), x(\beta_2(t)))}{\Gamma(\alpha)} \right. \\ &\times \int_0^t (t - s)^{\alpha - 1} f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s))) \, ds \\ &- \frac{f_2(t, y(\beta_1(t)), y(\beta_2(t)))}{\Gamma(\alpha)} \\ &\times \int_0^t (t - s)^{\alpha - 1} f_3(t, s, y(\gamma_1(s)), y(\gamma_2(s))) \, ds \\ &\leq |f_1(t, x(\alpha_1(t)), x(\alpha_2(t))) \\ &- f_1(t, y(\alpha_1(t)), y(\alpha_2(t)))| \end{aligned}$$

$$+ \left(\left|f_{2}\left(t, x\left(\beta_{1}\left(t\right)\right), x\left(\beta_{2}\left(t\right)\right)\right)\right| \times (\Gamma\left(\alpha\right)\right)^{-1} \right. \\ \left. + \left[\frac{f_{2}\left(t, y\left(\beta_{1}\left(t\right)\right), y\left(\beta_{2}\left(t\right)\right)\right)\right]}{\left(t-s\right)^{1-\alpha}}\right] ds \\ \left. + \frac{\left|f_{2}\left(t, y\left(\beta_{1}\left(t\right)\right), y\left(\beta_{2}\left(t\right)\right)\right)\right|}{\Gamma\left(\alpha\right)} \right] \\ \left. \times \int_{0}^{t} \left(\left(\left|f_{3}\left(t, s, x\left(\gamma_{1}\left(s\right)\right), x\left(\gamma_{2}\left(s\right)\right)\right)\right| \right) \\ \left. -f_{3}\left(t, s, y\left(\gamma_{1}\left(s\right)\right), y\left(\gamma_{2}\left(s\right)\right)\right)\right] \right) \\ \left. \times \left(\left(t-s\right)^{1-\alpha}\right)^{-1}\right) ds \\ \leq \left(\ell\left(t\right) \max\left\{\left|x\left(\alpha_{1}\left(t\right)\right) - y\left(\alpha_{1}\left(t\right)\right)\right|\right\}\right) \\ \left. \times \left(M + \max\left\{\left|x\left(\alpha_{1}\left(t\right)\right) - y\left(\alpha_{2}\left(t\right)\right)\right|\right\}\right) \right] \right)^{-1} \\ \left. + \left(m\left(t\right)\left(\left|x\left(\beta_{1}\left(t\right)\right) - y\left(\beta_{2}\left(t\right)\right)\right|\right)\right) \times \left(\Gamma\left(\alpha\right)\right)^{-1} \right] \\ \left. \times \int_{0}^{t} \left(\left(\left|f_{3}\left(t, s, x\left(\gamma_{1}\left(s\right)\right), x\left(\gamma_{2}\left(s\right)\right)\right) - f_{3}\left(t, s, 0, 0\right)\right| \\ \left. +F_{3}\left(t\right)\right) \times \left(\left(t-s\right)^{1-\alpha}\right)^{-1}\right) ds \\ + \frac{\left|f_{2}\left(t, y\left(\beta_{1}\left(t\right)\right), y\left(\beta_{2}\left(t\right)\right)\right) - F_{2}\left(t\right)\right| + \left|F_{2}\left(t\right)\right|}{\Gamma\left(\alpha\right)} \\ \times \int_{0}^{t} \left(n\left(t\right)\varphi\left(\left|x\left(\gamma_{1}\left(s\right)\right) - y\left(\gamma_{1}\left(s\right)\right)\right| \\ \left. + \left|x\left(\gamma_{2}\left(s\right)\right) - y\left(\gamma_{2}\left(s\right)\right)\right|\right) \times \left(\left(t-s\right)^{1-\alpha}\right)^{-1}\right) ds \\ \leq \frac{L \left\|x-y\right\|}{M + \left\|x-y\right\|} + \frac{2m\left(t\right)\left\|x-y\right\|}{\Gamma\left(\alpha\right)} \\ \times \left[n\left(t\right)\varphi\left(2\left\|x\right\|\right) + F_{3}\left(t\right)\right) \int_{0}^{t} \left(t-s\right)^{\alpha-1} ds \\ + \frac{2m\left(t\right)\left\|y\right\| + \left|F_{2}\left(t\right)\right]}{\Gamma\left(\alpha\right)} n\left(t\right)\varphi\left(2\left\|x-y\right\|\right) \\ \times \left(\frac{1}{43}\right)$$

Now, linking the above established facts one concludes that the operator Q maps continuously the closed ball B_{r_0} into itself.

Further, taking a nonempty subset X of the ball B_{r_0} , fixing arbitrarily T > 0 and $\varepsilon > 0$ and choosing $x \in X$ and

 $t_1,t_2 \in [0,T]$ with $|t_2 - t_2| < \varepsilon$, without loss of generality we may assume that $t_1 < t_2$. Then, taking into account our assumptions (H_2) and (H_4) , one gets

$$\begin{split} |(Qx)(t_{2}) - (Qx)(t_{1})| \\ &\leq |q(t_{1}) - q(t_{2})| \\ &+ |f_{1}(t_{2}, x(\alpha_{1}(t_{2})), (\alpha_{2}(t_{2})))) \\ &- f_{1}(t_{2}, x(\alpha_{1}(t_{1})), (\alpha_{2}(t_{1})))| \\ &+ |f_{1}(t_{2}, x(\alpha_{1}(t_{1})), (\alpha_{2}(t_{1})))| \\ &+ |f_{1}(t_{2}, x(\alpha_{1}(t_{1})), (\alpha_{2}(t_{1})))| \\ &+ |(Fx)(t_{2})(Ux)(t_{2}) - (Fx)(t_{1})(Ux)(t_{2})| \\ &+ |(Fx)(t_{1})(Ux)(t_{2}) - (Fx)(t_{1})(Ux)(t_{1})| \\ &\leq \omega^{T}(q, \varepsilon) + (\ell(t)\max\{|x(\alpha_{1}(t_{2})) - x(\alpha_{1}(t_{1}))|, \\ &|x(\alpha_{2}(t_{2})) - x(\alpha_{2}(t_{1}))|\}) \\ &\times (M + \max\{|x(\alpha_{1}(t_{2})) - x(\alpha_{1}(t_{1}))|, \\ &|x(\alpha_{2}(t_{2})) - x(\alpha_{2}(t_{1}))|\})^{-1} \\ &+ \omega_{1}^{T}(f_{1}, \varepsilon) \\ &+ ((|f_{2}(t_{2}, x(\beta_{1}(t_{2})), x(\beta_{2}(t_{2})))) \\ &- f_{2}(t_{1}, x(\beta_{1}(t_{1})), x(\beta_{2}(t_{1})))|] \times (\Gamma(\alpha))^{-1}) \\ &\times \int_{0}^{t_{2}} \frac{|f_{3}(t_{2}, s, x(\gamma_{1}(s)), x(\gamma_{2}(s)))||}{(t_{2} - s)^{1-\alpha}} ds \\ &+ \frac{|f_{2}(t_{1}, x(\beta_{1}(t_{1})), x(\beta_{2}(t_{1})))|}{\Gamma(\alpha + 1)} \\ &\times \{T^{\alpha}\omega_{1}^{T}(f_{3}, \varepsilon, r_{0}) + 2\varepsilon^{\alpha}[\overline{n}(T)\varphi(2r_{0}) + \overline{F}_{3}(T)]\} \\ &\leq \omega^{T}(q, \varepsilon) \\ &+ (\ell(t)\max\{|x(\alpha_{1}(t_{2})) - x(\alpha_{1}(t_{1}))|, \\ &|x(\alpha_{2}(t_{2})) - x(\alpha_{2}(t_{1}))|\}) \\ &\times (M + \max\{|x(\alpha_{1}(t_{2})) - x(\alpha_{1}(t_{1}))|, \\ &|x(\alpha_{2}(t_{2})) - x(\alpha_{2}(t_{1}))|\}) \\ &\times (M + \max\{|x(\alpha_{1}(t_{2})) - x(\alpha_{2}(t_{1}))|\}) \\ &+ |f_{2}(t_{2}, x(\beta_{1}(t_{1})), x(\beta_{2}(t_{1})))| \\ &+ |f_{2}(t_{1}, x(\beta_{$$

$$\begin{split} & \times \int_{0}^{t_{2}} \left(\left(\left| f_{3}\left(t_{2}, s, x\left(\gamma_{1}\left(s\right) \right), x\left(\gamma_{2}\left(s\right) \right) \right) \\ & -f_{3}\left(t_{2}, s, 0, 0 \right) \right| + F_{3}\left(t_{2} \right) \right) \times \left(\left(t_{2} - s \right)^{1 - \alpha} \right)^{-1} \right) ds \\ & + \frac{\left| f_{2}\left(t_{1}, x\left(\beta_{1}\left(t_{1} \right) \right), x\left(\beta_{2}\left(t_{1} \right) \right) \right) - F_{2}\left(t_{1} \right) \right| + \left| F_{2}\left(t_{1} \right) \right| \right) \\ & \times \left\{ T^{\alpha} \omega_{1}^{T}\left(f_{3}, \varepsilon, r_{0} \right) + 2\varepsilon^{\alpha} \left[\overline{n}\left(T \right) \varphi\left(2r_{0} \right) + \overline{F}_{3}\left(T \right) \right] \right\} \\ & \leq \omega^{T}\left(q, \varepsilon \right) \\ & + \frac{L \max\left\{ w^{T}\left(x, w^{T}\left(\alpha_{1}, \varepsilon \right) \right), w^{T}\left(x, w^{T}\left(\alpha_{2}, \varepsilon \right) \right) \right\} \\ & + w_{1}^{T}\left(f_{1}, \varepsilon \right) \\ & + \left(m(t_{2})\left(\left| x\left(\beta_{1}\left(t_{2} \right) \right) - x\left(\beta_{1}\left(t_{1} \right) \right) \right| \right) \\ & + \left| x\left(\beta_{2}\left(t_{2} \right) \right) \right| \right) \right) \times \left(\Gamma\left(\alpha \right) \right)^{-1} \\ & + w_{1}^{T}\left(f_{2}, \varepsilon \right) \int_{0}^{t_{2}} \frac{n\left(t_{2} \right) \varphi\left(2 \left\| x \right\| \right) + F_{3}\left(t_{2} \right) }{\left(t_{2} - s \right)^{1 - \alpha}} ds \\ & + \frac{m\left(t_{1} \right) \left(\left| x\left(\beta_{1}\left(t_{1} \right) \right) \right| + \left| x\left(\beta_{2}\left(t_{1} \right) \right) \right| \right) \right| \right) \left| F_{2}\left(t_{1} \right) \right| }{\Gamma\left(\alpha + 1 \right)} \\ & \times \left\{ T^{\alpha} \omega_{1}^{T}\left(f_{3}, \varepsilon, r_{0} \right) + 2\varepsilon^{\alpha} \left[\overline{n}\left(T \right) \varphi\left(2r_{0} \right) + \overline{F}_{3}\left(T \right) \right] \right\} \\ & \leq \omega^{T}\left(q, \varepsilon \right) \\ & + \frac{L \max\left\{ w^{T}\left(x, \omega^{T}\left(\alpha_{1}, \varepsilon \right) \right), w^{T}\left(x, \omega^{T}\left(\alpha_{2}, \varepsilon \right) \right) \right\} \\ & + w_{1}^{T}\left(f_{1}, \varepsilon \right) \\ & + \frac{2m\left(t_{1} \right) r_{0} + \left| F_{2}\left(t_{1} \right) \right| }{\Gamma\left(\alpha + 1 \right)} \\ & \times \left\{ T^{\alpha} w_{1}^{T}\left(f_{3}, \varepsilon, r_{0} \right) + 2\varepsilon^{\alpha} \left[\overline{n}\left(T \right) \varphi\left(2r_{0} \right) + \overline{F}_{3}\left(T \right) \right] \right\} \\ & \times \left\{ T^{\alpha} w_{1}^{T}\left(f_{3}, \varepsilon, r_{0} \right) + 2\varepsilon^{\alpha} \left[\overline{n}\left(T \right) \varphi\left(2r_{0} \right) + \overline{F}_{3}\left(T \right) \right] \right\} \\ & + \frac{2m\left(t_{1} \right) r_{0} + \left| F_{2}\left(t_{1} \right) \right| }{\Gamma\left(\alpha + 1 \right)} \\ & \times \left\{ T^{\alpha} w_{1}^{T}\left(f_{3}, \varepsilon, r_{0} \right) + 2\varepsilon^{\alpha} \left[\overline{n}\left(T \right) \varphi\left(2r_{0} \right) + \overline{F}_{3}\left(T \right) \right] \right\} \\ & \times \left\{ T^{\alpha} w_{1}^{T}\left(f_{3}, \varepsilon, r_{0} \right) + 2\varepsilon^{\alpha} \left[\overline{n}\left(T \right) \varphi\left(2r_{0} \right) + \overline{F}_{3}\left(T \right) \right] \right\} \\ & \leq \omega^{T}\left(q, \varepsilon \right) \\ & + \frac{2m\left(t_{1} \left(t_{2} \right) n\left(t_{2} \right) \varphi\left(2r_{0} \right) + m\left(t_{2} \right) \left(\tau \left(\alpha_{2} \right) \right) \right) \right\} \\ & + \frac{2m\left(t_{1} \left(t_{1} \right) \left(t_{2} \right) \left(t_{2} \left(t_{1} \right) \right) \left(t_{1} \left(t_{1} \right) \right) \left(t_{1} \left(t_{2} \right) \right) \left(t_{1} \left(t_{1} \right) \right) \right) \right$$

$$+ \frac{2m(t_{1})r_{0} + |F_{2}(t_{1})|}{\Gamma(\alpha + 1)}$$

$$\times \left\{ T^{\alpha}\omega_{1}^{T}(f_{3},\varepsilon,r_{0}) + 2\varepsilon^{\alpha}\left[\overline{n}(T)\varphi(2r_{0}) + \overline{F}_{3}(T)\right] \right\}$$

$$\leq \omega^{T}(q,\varepsilon)$$

$$+ \frac{L\max\left\{\omega^{T}\left(x,\omega^{T}\left(\alpha_{1},\varepsilon\right)\right),\omega^{T}\left(x,\omega^{T}\left(\alpha_{2},\varepsilon\right)\right)\right\}}{M + \max\left\{\omega^{T}\left(x,\omega^{T}\left(\alpha_{1},\varepsilon\right)\right),\omega^{T}\left(x,\omega^{T}\left(\alpha_{2},\varepsilon\right)\right)\right\}}$$

$$+ \omega_{1}^{T}(f_{1},\varepsilon)$$

$$+ \left(\left[A\varphi(2r_{0}) + B\right]\left[\omega^{T}\left(x,\omega^{T}\left(\beta_{1},\varepsilon\right)\right) + \omega^{T}\left(x,\omega^{T}\left(\beta_{2},\varepsilon\right)\right)\right]\right) \times (2\Gamma(\alpha + 1))^{-1}$$

$$+ \frac{\omega_{1}^{T}(f_{2},\varepsilon)t_{2}^{\alpha}\left[n(t_{2})\varphi(2r_{0}) + F_{3}(t_{2})\right]}{\Gamma(\alpha + 1)}$$

$$+ \frac{2m(t_{1})r_{0} + |F_{2}(t_{1})|}{\Gamma(\alpha + 1)}$$

$$\times \left\{T^{\alpha}\omega_{1}^{T}(f_{3},\varepsilon,r_{0}) + 2\varepsilon^{\alpha}\left[\overline{n}(T)\varphi(2r_{0}) + \overline{F}_{3}(T)\right]\right\},$$
(44)

where

$$\omega^{T}(q,\varepsilon) = \sup \{q(t_{2}) - q(t_{1}) : t_{1}, t_{2} \in [0,T], |t_{2} - t_{1}| < \varepsilon\},
\omega_{1}^{T}(f_{1},\varepsilon) = \sup \{f_{1}(t_{2}, x, y) - f_{1}(t_{1}, x, y) : t_{1}, t_{2} \in [0,T],
|t_{2} - t_{1}| < \varepsilon, x, y \in [-r_{0}, r_{0}]\},
\omega_{1}^{T}(f_{2},\varepsilon) = \sup \{f_{2}(t_{2}, x, y) - f_{2}(t_{1}, x, y) : t_{1}, t_{2} \in [0,T],
|t_{2} - t_{1}| < \varepsilon, x, y \in [-r_{0}, r_{0}]\}.$$
(45)

Moreover, mention that other notations used in the above estimate were introduced earlier.

From the above estimate one can derive the following inequality:

$$\begin{split} &\omega^{T}\left(Qx,\varepsilon\right) \\ &\leq \omega^{T}\left(q,\varepsilon\right) \\ &+ \frac{L\max\left\{\omega^{T}\left(x,\omega^{T}\left(\alpha_{1},\varepsilon\right)\right),\omega^{T}\left(x,\omega^{T}\left(\alpha_{2},\varepsilon\right)\right)\right\}}{M+\max\left\{\omega^{T}\left(x,\omega^{T}\left(\alpha_{1},\varepsilon\right)\right),\omega^{T}\left(x,\omega^{T}\left(\alpha_{2},\varepsilon\right)\right)\right\}} \\ &+ \omega_{r}^{T}\left(f_{1},\varepsilon\right) \\ &+ \frac{\left[A\varphi\left(2r_{0}\right)+B\right]\left[\omega^{T}\left(x,\omega^{T}\left(\beta_{1},\varepsilon\right)\right)+\omega^{T}\left(x,\omega^{T}\left(\beta_{2},\varepsilon\right)\right)\right]}{2\Gamma\left(\alpha+1\right)} \end{split}$$

$$+ \frac{\omega_{1}^{T}(f_{2},\varepsilon)t_{2}^{\alpha}[n(t_{2})\varphi(2r_{0}) + F_{3}(t_{2})]}{\Gamma(\alpha+1)} + \frac{2m(t_{1})r_{0} + |F_{2}(t_{1})|}{\Gamma(\alpha+1)} \times \left\{T^{\alpha}\omega_{1}^{T}(f_{3},\varepsilon,r_{0}) + 2\varepsilon^{\alpha}\left[\bar{n}(T)\varphi(2r_{0}) + \bar{F}_{3}(T)\right]\right\}.$$
(46)

Observe that $\omega^T(q,\varepsilon) \to 0, \omega_1^T(f_1,\varepsilon) \to 0, \omega_1^T(f_2,\varepsilon) \to 0$ and $\omega_1^T(f_3,\varepsilon) \to 0$ as $\varepsilon \to 0$, which is a simple consequence of the uniform continuity of the functions q, f_1, f_2 , and f_3 on the sets $[0,T], [0,T] \times [-r_0,r_0] \times [-r_0,r_0], [0,T] \times$ $[-r_0,r_0] \times [-r_0,r_0]$ and $[0,T] \times [0,T] \times [-r_0,r_0] \times [-r_0,r_0]$, respectively. Moreover, it is obvious that the constant

$$\omega^{T}(\alpha_{1},\varepsilon) \longrightarrow 0, \qquad \omega^{T}(\alpha_{2},\varepsilon) \longrightarrow 0,$$
$$\omega^{T}(\beta_{1},\varepsilon) \longrightarrow 0, \qquad \omega^{T}(\beta_{2},\varepsilon) \longrightarrow 0, \qquad (47)$$
as $\varepsilon \longrightarrow 0.$

Thus, linking the established facts with the estimate (46) one gets

$$\omega_0^T(QX) \le \frac{L\omega_0^T(X)}{M + \omega_0^T(X)}.$$
(48)

Now, taking into account our assumptions, for arbitrarily fixed $T \in \mathbb{R}_+$ as well as for $x_1, x_2, y_1, y_2 \in X$ one can deduce the following estimate (cf. the estimate (41)–(44)):

$$\begin{split} &|Qx(t) - Qy(t)| \\ \leq (L \max \{ |x(\alpha_{1}(t)) - y(\alpha_{1}(t))|, \\ &|x(\alpha_{2}(t)) - y(\alpha_{2}(t))| \}) \\ \times (M + \max \{ |x(\alpha_{1}(t)) - y(\alpha_{1}(t))|, \\ &|x(\alpha_{2}(t)) - y(\alpha_{2}(t))| \})^{-1} \\ + (m(t)(|x(\beta_{1}(t)) - y(\beta_{1}(t))| \\ &+ |x(\beta_{2}(t)) - y(\beta_{2}(t))|) \times (\Gamma(\alpha))^{-1} \\ \times \int_{0}^{t} ((|f_{3}(t, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) - f_{3}(t, s, 0, 0)| \\ &+ F_{3}(t)) \times ((t - s)^{1 - \alpha})^{-1}) ds \\ + \frac{|f_{2}(t, y(\beta_{1}(t)), y(\beta_{2}(t))) - F_{2}(t)| + |F_{2}(t)|}{\Gamma(\alpha)} \\ \times \int_{0}^{t} ((n(t)\varphi(|x(\gamma_{1}(s)) - y(\gamma_{1}(s))| \\ &+ |x(\gamma_{2}(s)) - y(\gamma_{2}(s))|)) \\ \times ((t - s)^{1 - \alpha})^{-1}) ds \end{split}$$

$$\leq \frac{L \max \{\dim X(\alpha_{1}(t)), \dim X(\alpha_{2}(t))\}}{M + \max \{\dim X(\alpha_{1}(t)), \dim X(\alpha_{2}(t))\}} \\+ \frac{m(t)(|x(\beta_{1}(t)) - y(\beta_{1}(t))| + |x(\beta_{2}(t)) - y(\beta_{2}(t))|)}{\Gamma(\alpha)} \\\times \int_{0}^{t} \frac{n(t) \varphi(|x(\gamma_{1}(s))| + |x(\gamma_{2}(s))|) + F_{3}(t)}{(t - s)^{1-\alpha}} ds \\+ \frac{m(t)(|y(\beta_{1}(t))| + |y(\beta_{2}(t))|) + |F_{2}(t)|}{\Gamma(\alpha)} \\\times \int_{0}^{t} (n(t) \varphi(|x(\gamma_{1}(s)) - y(\gamma_{1}(s))| \\+ |x(\gamma_{2}(s)) - y(\gamma_{2}(s))|) \\\times ((t - s)^{1-\alpha})^{-1}) ds \\\leq \frac{L \max \{\dim X(\alpha_{1}(t)), \dim X(\alpha_{2}(t))\}}{M + \max \{\dim X(\alpha_{1}(t)), \dim X(\alpha_{2}(t))\}} \\+ (m(t) n(t)(|x(\beta_{1}(t))| + |y(\beta_{1}(t))| \\+ |x(\beta_{2}(t))| + |y(\beta_{2}(t))|)) \\\times (\Gamma(\alpha))^{-1} \\\times \int_{0}^{t} \frac{\varphi(|x(\gamma_{1}(s))| + |x(\gamma_{2}(s))|)}{(t - s)^{1-\alpha}} ds \\+ (m(t) F_{3}(t)(|x(\beta_{1}(t))| + |y(\beta_{1}(t))| \\+ |x(\beta_{2}(t))| + |y(\beta_{2}(t))|)) \\\times (\Gamma(\alpha))^{-1} \\\times \int_{0}^{t} \frac{\varphi(|x(\gamma_{1}(s))| + |x(\gamma_{2}(s))|)}{(t - s)^{1-\alpha}} ds \\+ \frac{m(t) n(t)(|y(\beta_{1}(t))| + |y(\beta_{2}(t))|)}{(t - s)^{1-\alpha}} ds \\+ \frac{m(t) n(t)(|y(\beta_{1}(t))| + |y(\beta_{2}(t))|)}{(t - s)^{1-\alpha}} ds \\+ \frac{m(t) n(t)(|y(\beta_{1}(t))| + |y(\beta_{2}(t))|)}{\Gamma(\alpha)} \\\times \int_{0}^{t} (\varphi(|x(\gamma_{1}(s))| + |y(\gamma_{1}(s))| \\+ |x(\gamma_{2}(s))| + |y(\gamma_{2}(s))|) \\\times ((t - s)^{1-\alpha})^{-1} ds$$

$$+ \frac{n(t) |F_{2}(t)| (|y(\beta_{1}(t))| + |y(\beta_{2}(t))|)}{\Gamma(\alpha)}$$

$$\times \int_{0}^{t} \left(\varphi(|x(\gamma_{1}(s))| + |y(\gamma_{1}(s))| + |x(\gamma_{2}(s))| + |x(\gamma_{2}(s))| + |y(\gamma_{2}(s))|) \times ((t-s)^{1-\alpha})^{-1}\right) ds$$

$$\leq \frac{L \max\{\operatorname{diam} X(\alpha_{1}(t)), \operatorname{diam} X(\alpha_{2}(t))\}}{M + \max\{\operatorname{diam} X(\alpha_{1}(t)), \operatorname{diam} X(\alpha_{2}(t))\}}$$

$$+ \frac{4m(t)n(t)r_0\varphi(2r_0)}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \mathrm{d}s$$

$$+ \frac{4m(t) F_{3}(t) r_{0} \varphi(2r_{0})}{\Gamma(\alpha)} \int_{0}^{t} (t-s)^{\alpha-1} ds + \frac{2m(t) n(t) r_{0} \varphi(4r_{0})}{\Gamma(\alpha)} \int_{0}^{t} (t-s)^{\alpha-1} ds + \frac{n(t) |F_{2}(t)| \varphi(4r_{0})}{\Gamma(\alpha)} \int_{0}^{t} (t-s)^{\alpha-1} ds = \frac{L \max \{ \operatorname{diam} X(\alpha_{1}(t)), \operatorname{diam} X(\alpha_{2}(t)) \}}{M + \max \{ \operatorname{diam} X(\alpha_{1}(t)), \operatorname{diam} X(\alpha_{2}(t)) \}} + \frac{2a(t) r_{0} \varphi(2r_{0})}{\Gamma(\alpha+1)} + \frac{a(t) r_{0} \varphi(4r_{0})}{\Gamma(\alpha+1)} + \frac{c(t) \varphi(4r_{0})}{\Gamma(\alpha+1)} + \frac{2b(t) r_{0} \varphi(2r_{0})}{\Gamma(\alpha+1)}.$$
(49)

In view of assumptions (H_0) and (H_6) this yields

$$\limsup_{t \to \infty} \operatorname{diam} QX(t)$$

$$\leq \frac{L \limsup_{t \to \infty} \max\left\{\operatorname{diam} X\left(\alpha_{1}(t)\right), \operatorname{diam} X\left(\alpha_{2}(t)\right)\right\}}{M + \limsup_{t \to \infty} \max\left\{\operatorname{diam} X\left(\alpha_{1}(t)\right), \operatorname{diam} X\left(\alpha_{2}(t)\right)\right\}}$$

$$\leq \frac{L \limsup_{t \to \infty} \operatorname{diam} X(t)}{M + \limsup_{t \to \infty} \operatorname{diam} X(t)}.$$
(50)

Further, using the measure of noncompactness μ_a defined by the formula (9) and keeping in mind the estimates (48) and (50), one obtains

$$\mu_{a}(QX)$$

$$= \max \left\{ \omega_{0}(QX), \limsup_{t \to \infty} \max \operatorname{diam}(QX) \right\}$$

$$\leq \max \left\{ \frac{L\omega_{0}(X)}{M + \omega_{0}(X)}, \frac{L \limsup_{t \to \infty} \operatorname{diam} X(t)}{M + \limsup_{t \to \infty} \operatorname{diam} X(t)} \right\} \quad (51)$$

$$\leq \frac{L \max \left\{ \omega_{0}(X), \limsup_{t \to \infty} \operatorname{diam} X(t) \right\}}{M + \max \left\{ \omega_{0}(X), \limsup_{t \to \infty} \operatorname{diam} X(t) \right\}}$$

$$= \frac{L\mu_{a}(X)}{M + \mu_{a}(X)}.$$

Since $L \leq M$ in view of assumption (H_2) , from the above estimate one infers that $\mu_a(QX) \leq \varphi(\mu_a(X))$, where $\varphi(r) = Lr/(M+r) < r$ for r > 0. Hence, apply Theorem 5 to deduce that the operator Q has a fixed point x in the ball B_{r_0} . On the other hand, from Remark 6 one concludes that the set Fix(Q) belongs to the family ker μ_a . Now, taking into account the description of sets belonging to ker μ_a (given in Section 2) one deduces that all solutions for (21) are globally uniformly attractive on \mathbb{R}_+ . This completes the proof.

Remark 20. When $q \equiv 0$, $f_1(t, x, y) = f_1(t, x)$, $f_2(t, x, y) = f_2(t, x)$ and $f_3(t, s, x, y) = f_3(t, s, x)$, according to our

Theorem 19, one can obtain the global attractivity result for (23) which has been studied by Banaś and O'Regan in [47]. Meanwhile when

$$q(t) = 0,$$

$$f_{1}(t, x(\alpha_{1}(t)), x(\alpha_{2}(t))) = g(t, x(\eta(t))),$$

$$f_{2}(t, x(\beta_{1}(t)), x(\beta_{2}(t))) = f(t, x(\beta(t))),$$

$$f_{3}(t, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) = h(t, s) u(s, x(\gamma(s))),$$
(52)

from our Theorem 19, one can obtain the global attractivity result for (23) which has been studied by Balachandran et al. in [48].

To prove next result concerning the asymptotic positivity of the attractive solutions, we need the following hypothesis in the sequel.

 (H_8) The functions q and f_1 satisfy $\lim_{t\to\infty} [|q(t)| - q(t)] = 0$, $\lim_{t\to\infty} [|f_1(t, x, y)| - f_1(t, x, y)] = 0$ for all $x, y \in \mathbb{R}$.

Theorem 21. Under the hypotheses of Theorem 19 and (H_8) , (21) has at least one solution on \mathbb{R}_+ . Moreover, these solutions are uniformly globally attractive and ultimately positive on \mathbb{R}_+ .

Proof. Consider the closed ball B_{r_0} in the Banach space $BC(\mathbb{R}_+, \mathbb{R})$, where the real number r_0 is given as in the proof of Theorem 19, and define a mapping $Q : BC(\mathbb{R}_+, \mathbb{R}) \rightarrow BC(\mathbb{R}_+, \mathbb{R})$ by (36). Then it is shown as in the proof of Theorem 19 that Q defines a continuous mapping from the space $BC(\mathbb{R}_+, \mathbb{R})$ into B_{r_0} . In particular, Q maps B_{r_0} into itself. Next we show that Q is a nonlinear D-set-contraction with respect to the measure μ_{ad} of noncompactness in $BC(\mathbb{R}_+, \mathbb{R})$. We know that, for any $x, y \in \mathbb{R}$, one has the inequality, $|x| + |y| \ge |x + y| \ge x + y$, and therefore,

$$||x + y| - (x + y)| \le ||x| + |y| - (x + y)|$$

$$\le ||x| - x| + ||y| - y|$$
(53)

for all $x, y \in \mathbb{R}$. Now for any $x \in B_{r_0}$, one has

$$\begin{aligned} ||Qx(t)| - Qx(t)| \\ &\leq ||q(t)| - q(t)| \\ &+ ||f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))| \\ &- f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))| \\ &+ \left\| \frac{f_2(t, x(\beta_1(t)), x(\beta_2(t)))}{\Gamma(\alpha)} \right\| \\ &\times \int_0^t (t - s)^{\alpha - 1} f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s))) \, ds \\ &- \frac{f_2(t, x(\beta_1(t)), x(\beta_2(t)))}{\Gamma(\alpha)} \\ &\times \int_0^t (t - s)^{\alpha - 1} f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s))) \, ds \end{aligned}$$

$$\leq \delta_{T}(q) + \delta_{T}(f_{1}) + 2 \left| \frac{f_{2}(t, x(\beta_{1}(t)), x(\beta_{2}(t)))}{\Gamma(\alpha)} \times \int_{0}^{t} (t-s)^{\alpha-1} f_{3}(t, s, x(\gamma_{1}(s)), x(\gamma_{2}(s))) ds \right| \\\leq \delta_{T}(q) + \delta_{T}(f_{1}) + (2 [a(t) ||x|| \varphi(2 ||x||) + b(t) ||x|| + c(t) \varphi(2 ||x||) + d(t)]) \times (\Gamma(\alpha+1))^{-1}.$$
(54)

From the above inequality, it follows that

$$\delta_{T} (X) \leq \delta_{T} (q) + \delta_{T} (f_{1}) + (2 [a(t) ||x|| \varphi (2 ||x||) + b(t) ||x|| + c(t) \varphi (2 ||x||) + d(t)]) \times (\Gamma (\alpha + 1))^{-1}.$$
(55)

For all closed $X \in B_{r_0}$. Taking the limit superior as $T \to \infty$, one obtains

$$\limsup_{T \to \infty} \delta_T(X) \le \limsup_{T \to \infty} \delta_T(q) + \limsup_{T \to \infty} \delta_T(f_1)$$
(56)

for all closed $X \,\subset B_{r_0}$. Hence $\delta(QX) = \lim_{T \to \infty} \delta_T(X) = 0$ for all closed subsets X of B_{r_0} . Further, using the measure of noncompactness μ_a defined by the formula (9) and keeping in mind the estimates (50) and (51), one obtains

$$\mu_{ad} (QX) = \max \left\{ \mu_a (QX), \delta (QX) \right\}$$

$$\leq \max \left\{ \frac{L\mu_a (X)}{M + \mu_a (X)}, 0 \right\}$$

$$\leq \frac{L \max \left\{ \mu_a (X), 0 \right\}}{M + \max \left\{ \mu_a (X), 0 \right\}} \leq \frac{L\mu_{ad} (X)}{M + \mu_{ad} (X)}.$$
(57)

Since $L \leq M$ in view of assumption (H_2) , from the above estimate one infers that $\mu_{ad}(QX) \leq \varphi(\mu_{ad}(QX))$, where $\varphi(r) = Lr/(M + r) < r$ for r > 0. Hence, applying Theorem 5 to deduce that the operator Q has a fixed point x in the ball B_{r_0} . Obviously x is a solution of (21). Now, taking into account the description of sets belonging to ker μ_{ad} (given in Section 2) one deduces that all solutions of (21) are uniformly globally attractive and ultimately positive on \mathbb{R}_+ . This completes the proof.

Next we prove the global asymptotic attractivity results for (21). We need the following hypotheses in the sequel.

 (H_9) The function $q : \mathbb{R}_+ \to \mathbb{R}$ is continuous and $\lim_{t\to\infty} q(t) = c$.

 $(H_{10}) f_1(t, 0, 0) = 0$ for all $t \in \mathbb{R}_+$, and

 $(H_{11}) \lim_{t\to\infty} \ell(t) = 0$, where the function ℓ is defined as in hypothesis (H_2) .

Theorem 22. Assume that the hypotheses (H_0) , $(H_2)-(H_7)$ and $(H_9)-(H_{11})$ hold. Then (21) has at least one solution in the space $BC(\mathbb{R}_+, \mathbb{R})$. Moreover, these solutions are uniformly globally asymptotically attractive on \mathbb{R}_+ .

Proof. Consider the closed ball B_{r_0} in the Banach space $BC(\mathbb{R}_+, \mathbb{R})$, where the real number r_0 is given as in the proof of Theorem 19 and define a mapping $Q : B_{r_0} \to B_{r_0}$ by (36). Then Q is continuous and maps the space $BC(\mathbb{R}^+, \mathbb{R})$ and, in particular, B_{r_0} into B_{r_0} . We show that Q is a nonlinear D-set-contraction with respect to the measure μ_c of noncompactness in $BC(\mathbb{R}_+, \mathbb{R})$. Let $x \in B_{r_0}$ be arbitrary. Then one has

$$\begin{split} |Qx(t) - c| \\ &\leq |q(t) - c| + |f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))| \\ &+ \left| \frac{f_2(t, x(\beta_1(t)), x(\beta_2(t)))}{\Gamma(\alpha)} \\ &\times \int_0^t (t - s)^{\alpha - 1} f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s))) \, ds \right| \\ &\leq |q(t) - c| + |f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))| \\ &+ \frac{|f_2(t, x(\beta_1(t)), x(\beta_2(t)))|}{\Gamma(\alpha)} \\ &\times \int_0^t (t - s)^{\alpha - 1} |f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s)))| \, ds \\ &\leq |q(t) - c| + |f_1(t, x(\alpha_1(t)), x(\alpha_2(t))) - F_1(t)| \\ &+ \frac{1}{\Gamma(\alpha)} [|f_2(t, x(\beta_1(t)), (\beta_2(t))) - F_2(t)| + |F_2(t)|] \\ &\times \int_0^t (t - s)^{\alpha - 1} [|f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s))) \\ &- f_3(t, s, 0, 0) | + F_3(t)] \, ds \\ &\leq |q(t) - c| + \frac{\ell(t) \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}}{M + \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}} \\ &+ \frac{2 ||x|| m(t) + |F_2(t)|}{\Gamma(\alpha)} \\ &\times \int_0^t (t - s)^{\alpha - 1} [n(t) \varphi(2 ||x||) + F_3(t)] \, ds \\ &\leq |q(t) - c| + \frac{\ell(t) \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}}{M + \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}} \\ &+ \frac{2 ||x|| m(t) + |F_2(t)|}{\Gamma(\alpha)} [n(t) \varphi(2 ||x||) + F_3(t)] \, ds \\ &\leq |q(t) - c| + \frac{\ell(t) \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}}{M + \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}} \\ &+ \frac{2 ||x|| m(t) + |F_2(t)|}{\Gamma(\alpha)} [n(t) \varphi(2 ||x||) + F_3(t)] \, ds \\ &\leq |q(t) - c| + \frac{\ell(t) \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}}{M + \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}} \\ &+ \frac{2 ||x|| m(t) + |F_2(t)|}{\Gamma(\alpha)} [n(t) \varphi(2 ||x||) + F_3(t)] \\ &\times \int_0^t (t - s)^{\alpha - 1} \, ds \\ &\leq |q(t) - c| + \frac{\ell(t) \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}}{M + \max\{|x(\alpha_1(t))|, |x(\alpha_2(t))|\}} \\ \end{aligned}$$

$$+ \left(t^{\alpha} \left[2m(t) n(t) \|x\| \varphi(2 \|x\|) + 2 \|x\| m(t) F_{3}(t) + |F_{2}(t)| n(t) \varphi(2 \|x\|) + |F_{2}(t)| F_{3}(t)]\right) \times (\Gamma(\alpha + 1))^{-1}$$

$$\leq |q(t) - c| + \frac{\ell(t) \max\{|x(\alpha_{1}(t))|, |x(\alpha_{2}(t))|\}}{M + \max\{|x(\alpha_{1}(t))|, |x(\alpha_{2}(t))|\}}$$

$$+ \frac{a(t) \|x\| \varphi(2 \|x\|) + b(t) \|x\| + c(t) \varphi(2 \|x\|) + d(t)}{\Gamma(\alpha + 1)}$$

$$= |q(t) - c| + \frac{\ell(t) \max\{|x(\alpha_{1}(t))|, |x(\alpha_{2}(t))|\}}{M + \max\{|x(\alpha_{1}(t))|, |x(\alpha_{2}(t))|\}} + v(t),$$
(58)

for all $t \in \mathbb{R}_+$. This further implies that $||QX(t) - c|| \le |q(t) - c| + \ell(t) + \nu(t)$. Taking the limit superior in the above inequality, one obtains

$$\limsup_{t \to \infty} \|QX(t) - c\| \le \limsup_{t \to \infty} |q(t) - c| + \limsup_{t \to \infty} \ell(t) + \limsup_{t \to \infty} v(t).$$
(59)

Further, using the measure of noncompactness μ_c defined by the formula (11) and keeping in mind the estimates (48) and (59), one obtains

$$\mu_{c}(QX) = \max\left\{\omega_{0}(QX), \limsup_{t \to \infty} \|QX(t) - c\|\right\}$$

$$\leq \max\left\{\frac{L\omega_{0}(X)}{M + \omega_{0}(X)}, 0\right\} \leq \frac{L\max\left\{\omega_{0}(X), 0\right\}}{M + \max\left\{\omega_{0}(X), 0\right\}}$$

$$\leq \frac{L\mu_{c}(X)}{M + \mu_{c}(X)}.$$
(60)

Since $L \leq M$ in view of assumption (H_2) , from the above estimate one infers that $\mu_c(QX) \leq \varphi(\mu_c(QX))$, where $\varphi(r) = Lr/(M + r) < r$ for r > 0. Hence, apply Theorem 5 to deduce that the operator Q has a fixed point x in the ball B_{r_0} . Obviously x is a solution of the fractional functional integral equation (21). Now, taking into account the description of sets belonging to ker μ_c (given in Section 2) one deduces that all solutions of (21) are uniformly globally asymptotically attractive on \mathbb{R}_+ . This completes the proof.

Theorem 23. Under the hypotheses of Theorem 22 and (H_8) , (21) has at least one solution on \mathbb{R}_+ . Moreover, solutions of (21) are uniformly globally asymptotically attractive and ultimately positive on \mathbb{R}_+ .

Proof. The proof is similar to Theorem 21 with appropriate modifications. Now the desired conclusion follows an application of the measure of noncompactness μ_{cd} in $BC(\mathbb{R}_+, \mathbb{R})$. This completes the proof.

4. Applications

In what follows, we show that the assumptions imposed in Theorems 19 and 21 admit some natural realizations. First, we indicate some possible forms for expressing the function f_1 that satisfies the hypothesis (H_2) . Define a class Θ of functions $\theta : \mathbb{R}_+ \to \mathbb{R}_+$ satisfying the following properties: (i) θ is continuous; (ii) θ is nondecreasing (iii) θ is subadditive, that is, $\theta(x + y) \le \theta(x) + \theta(y)$ for all $x, y \in \mathbb{R}_+$.

Notice that if $\theta \in \Theta$, then after simple computation it can be shown that $|\theta(x) - \theta(y)| \le \theta(|x - y|)$ for all $x, y \in \mathbb{R}_+$. Now consider the function $f_1 : \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R} \to \mathbb{R}$ defined by

$$f_{1}(t, x, y) = \ell(t) \frac{\theta_{1}(|x|) + \theta_{2}(|y|)}{2M + \theta_{1}(|x|) + \theta_{2}(|y|)} + m(t),$$
(61)

where the functions $\ell, m : \mathbb{R}_+ \to \mathbb{R}$ are continuous and bounded on \mathbb{R}_+ , that is, $\ell, m \in BC(\mathbb{R}_+, \mathbb{R})$ with $\sup_{t \ge 0} \ell(t) = L$, $\theta_1, \theta_2 \in \Theta$ satisfying $\theta_1(r) \le r$, $\theta_2(r) \le r$, and M is a positive constant such that $L \le M$. It is shown as in the work of Dhage [11] that the function f_1 satisfies the condition (34) and consequently the hypothesis (H_2) . There do exist functions θ given in the expression (61). Indeed, the following functions

$$\theta(r) = r, \qquad \theta(r) = \ln(1+r),$$

$$\theta(r) = \arctan(r), \qquad \theta(r) = 2\left(\sqrt{1+r} - 1\right)$$
(62)

satisfy all the requirements of θ_1 and θ_2 given in (61) (cf. in the work of Banaś and Dhage [49]).

Finally, we provide two examples of the nonlinear fractional functional integral equations of the form (21) for which there are global attractive and ultimate positive solutions.

Example 24. Consider the following nonlinear functional integral equation:

3

$$c(t) = \frac{1}{2}te^{-t^{2}/2} + \frac{t^{2} + 1}{t^{2} + 4} \times \frac{\arctan(|x(t)|) + \arctan(|x(2t)|)}{9 + \arctan(|x(t)|) + \arctan(|x(2t)|)} + \frac{t + \sqrt{t} [x(t) + x(2t)]}{\Gamma(2/3)} \times \int_{0}^{t} \frac{e^{-3t - s\sqrt[3]{x^{2}(s) + x^{2}(2s)/4}} + 1/(10t^{8/3} + 1))}{(t - s)^{1/3}} ds.$$
(63)

Observe that the above equation is a special case of the fractional functional integral equation (21). Indeed, if we put $\alpha = 2/3$ and

$$\alpha_1(t) = \beta_1(t) = \gamma_1(t) = t,$$

$$\alpha_2(t) = \beta_2(t) = \gamma_2(t) = 2t, \qquad q(t) = \frac{1}{2}te^{-t^2/2},$$

$$f_{1}(t, x(\alpha_{1}(t)), x(\alpha_{2}(t)))$$

$$= \frac{t^{2} + 1}{t^{2} + 4} \times \frac{\arctan(|x(t)|) + \arctan(|x(2t)|)}{9 + \arctan(|x(t)|) + \arctan(|x(2t)|)},$$

$$f_{2}(t, x(\beta_{1}(t)), x(\beta_{2}(t))) = t + \sqrt{t}[x(t) + x(2t)],$$

$$f_{3}(t, s, x(\gamma_{1}(s)), x(\gamma_{2}(s)))$$

$$= e^{e^{-3t - s\sqrt[3]{x^{2}(s) + x^{2}(2s)/4}} + \frac{1}{10t^{8/3} + 1}.$$
(64)

Obviously the functions α_1 , α_2 , β_1 , β_2 and γ_1 , γ_2 satisfy hypothesis (H_0) . Further notice that the function $q(t) = (1/2)te^{-t^2/2}$ is continuous and bounded on \mathbb{R}_+ with $\|q\| = q(1) = (1/2)e^{-1/2} = 0.30327...$ Thus assumption (H_1) is satisfied. On the other hand, the function $f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))$ has the form (61) with $\ell(t) = (t^2 + 1)/(t^2 + 4)$. Moreover, $\theta(r) = \arctan(r)$ and M = 9/2. Since $\|\ell\| = L = 1$ one has that $L \leq M$. Additionally one has that the function θ satisfies above discussed requirements of the class of functions Θ , so the function $f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))$ satisfies assumption (H_2) and (H_4) .

Further observe that the function $f_2(t, x(\beta_1(t)), x(\beta_2(t)))$ satisfies assumption (H_3) with $m(t) = \sqrt{t}$ and $|F_2(t)| = f_2(t, 0, 0) = t$. Next, the function $f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s)))$ satisfies assumption (H_5) , where $n(t) = e^{-3t}$, $\varphi(r) = \sqrt[3]{r^2}/4$ and $f_3(t, s, 0, 0) = 1/(10t^{8/3}+1)$. Thus $F_3(t) = 1/(10t^{8/3}+1)$. To check that assumption (H_6) is satisfied let us observe that the functions *a*, *b*, *c*, *d* appearing in that assumption take the form

$$a(t) = 2t^{7/6}e^{-3t}, \qquad b(t) = \frac{2t^{7/6}}{10t^{8/3} + 1},$$

$$c(t) = t^{5/3}e^{-3t}, \qquad d(t) = \frac{t^{5/3}}{10t^{8/3} + 1}.$$
(65)

Thus, it is easily seen that $a(t) \rightarrow 0$ as $t \rightarrow \infty$ and $A = a(7/18) = 2(7/18)^{7/6}e^{-7/6} = 0.2069266...$ Further one has that $b(t) \rightarrow 0$ as $t \rightarrow \infty$ and $B = b((7/90)^{3/8}) = 0.0594821...$ It is also easy to check that $c(t) \rightarrow 0$ as $t \rightarrow \infty$. Moreover, one has that $C = c(5/9) = (5/9)^{5/3}e^{-5/3} = 0.0709235...$ Also one sees that $d(t) \rightarrow 0$ as $t \rightarrow \infty$ and $D = d((1/6)^{3/8}) = 0.1223733...$ Finally, let us note that the inequality from assumption (H_7) has the form

$$\frac{1}{2}e^{-1/2} + \frac{r}{9+r} + \frac{Ar\varphi(2r) + Br + C\varphi(2r) + D}{\Gamma(5/3)} < r.$$
(66)

Let us write this inequality in the form

$$\frac{1}{2}\Gamma\left(\frac{5}{3}\right)e^{-1/2} + \frac{\Gamma\left(5/3\right)r}{9+r} + Ar\varphi\left(2r\right) + Br + C\varphi\left(2r\right) + D < \Gamma\left(\frac{5}{3}\right)r.$$
(67)

Denoting by L(r) the left-hand side of this inequality, that is,

$$L(r) = \frac{1}{2}\Gamma\left(\frac{5}{3}\right)e^{-1/2} + \frac{\Gamma(5/3)r}{9+r} + Ar\varphi(2r) + Br + C\varphi(2r) + D$$
(68)

and keeping in mind the above established values of A, B, C, D, for r = 1 one obtains

$$L(1) = \frac{1}{2}\Gamma\left(\frac{5}{3}\right)e^{-1/2} + \frac{\Gamma(5/3)}{10} + A\varphi(2) + B + C\varphi(2) + D$$
$$= \frac{1}{2}\Gamma\left(\frac{5}{3}\right)0.60653\dots + \frac{\Gamma(5/3)}{10} + 0.963727\dots$$
(69)

Hence, taking into account that $\Gamma(5/3) > 0.8856$ (cf. [50]), one obtains that the number $r_0 = 1$ is a solution of the inequality (63).

Now, based on Theorem 19 one can conclude that the functional integral equation (63) has solutions in the space $BC(\mathbb{R}_+, \mathbb{R})$ and all solutions of this equation are uniformly globally attractive on \mathbb{R}_+ . Furthermore,

$$\left| f_3\left(t, s, x\left(\gamma_1\left(s\right)\right), x\left(\gamma_2\left(s\right)\right)\right) \right|$$

= $e^{-3t-s\sqrt[3]{x^2(s)+x^2(2s)/4}} + \frac{1}{10t^{8/3}+1}$ (70)
= $f_3\left(t, s, x\left(\gamma_1\left(s\right)\right), x\left(\gamma_2\left(s\right)\right)\right)$

for all $t \in \mathbb{R}_+$ and $x, y \in \mathbb{R}$. Hence the functions q and $f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s)))$ satisfy the hypothesis (H_8) . Hence by Theorem 21, solutions of (63) are uniformly globally attractive and ultimately positive on \mathbb{R}_+ .

Example 25. Consider the following nonlinear functional integral equation:

$$\begin{aligned} x(t) &= \frac{1}{2} t e^{-t^2/2} \\ &+ e^{-t} \frac{\arctan\left(|x(t)|\right) + \arctan\left(|x(2t)|\right)}{9 + \arctan\left(|x(t)|\right) + \arctan\left(|x(2t)|\right)} \\ &+ \frac{t + \sqrt{t} \left[x(t) + x(2t)\right]}{\Gamma(2/3)} \\ &\times \int_0^t \frac{e^{-3t - s\sqrt[3]{x^2(s) + x^2(2s)/4}} + 1/\left(10t^{8/3} + 1\right)}{(t - s)^{1/3}} ds. \end{aligned}$$
(71)

Observe that (71) is a special case of (21), where one has

$$\begin{aligned} \alpha_{1}(t) &= \beta_{1}(t) = \gamma_{1}(t) = t, \\ \alpha_{2}(t) &= \beta_{2}(t) = \gamma_{2}(t) = 2t, \qquad q(t) = \frac{1}{2}te^{-t^{2}/2}, \\ f_{1}(t, x(\alpha_{1}(t)), x(\alpha_{2}(t))) \\ &= e^{-t}\frac{\arctan(|x(t)|) + \arctan(|x(2t)|)}{9 + \arctan(|x(t)|) + \arctan(|x(2t)|)}, \\ f_{2}(t, x(\beta_{1}(t)), x(\beta_{2}(t))) &= t + \sqrt{t}[x(t) + x(2t)], \\ &= e^{-3t - s\sqrt[3]{x^{2}(s) + x^{2}(2s)/4}} + \frac{1}{10t^{8/3} + 1}. \end{aligned}$$

$$(72)$$

Obviously, the functions α_1 , α_2 , β_1 , β_2 and γ_1 , γ_2 satisfy hypothesis (H_0) and it is shown as in Example 24 that assumption (H_1) is satisfied. Further, notice that the function $f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))$ has the form (61) with $\ell(t) = e^{-t}$ and $\lim_{t\to\infty} \ell(t) = \lim_{t\to\infty} e^{-t} = 0$. Moreover, $\theta(r) = \arctan(r)$, M = 9/2. Since $\|\ell\| = 1$ one has that $L \leq M$. Additionally one has that $\theta \in \Theta$, so the function $f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))$ satisfies assumption (H_2) and (H_4) .

Finally, it is shown as in Example 24 that the functions $f_2(t, x(\beta_1(t)), x(\beta_2(t)))$ and $f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s)))$ are continuous on $\mathbb{R}_+ \times \mathbb{R} \times \mathbb{R}$ and $\mathbb{R}_+ \times \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R}$, respectively; moreover, they satisfy hypotheses (H_3) and $(H_5)-(H_7)$. Now, based on Theorem 22 one concludes that the fractional functional integral equation (61) has solutions in the space $BC(\mathbb{R}_+, \mathbb{R})$ and all solutions of this equation are uniformly globally asymptotically attractive on \mathbb{R}_+ . Furthermore,

$$\begin{aligned} \left| f_1(t, x(\alpha_1(t)), x(\alpha_2(t))) \right| \\ &= e^{-t} \frac{\arctan(|x(t)|) + \arctan(|x(2t)|)}{9 + \arctan(|x(t)|) + \arctan(|x(2t)|)} \end{aligned}$$
(73)
$$&= f_1(t, x(\alpha_1(t)), x(\alpha_2(t))) \end{aligned}$$

for all $t \in \mathbb{R}_+$ and $x, y \in \mathbb{R}$. Hence the functions q and $f_1(t, x(\alpha_1(t)), x(\alpha_2(t)))$ satisfy the hypotheses $(H_8)-(H_{11})$. Hence by Theorem 23, solutions of (71) are uniformly globally asymptotically attractive and ultimately positive on \mathbb{R}_+ .

Remark 26. Note that the global existence as well as attractivity and positivity results of (21) can be extended to the following fractional functional integral equation:

$$\begin{aligned} x(t) &= q(t) + f_1(t, x(\alpha_1(t)), x(\alpha_2(t)), \dots, x(\alpha_n(t))) \\ &+ \frac{f_2(t, x(\beta_1(t)), x(\beta_2(t)), \dots, x(\beta_n(t)))}{\Gamma(\alpha)} \\ &\times \int_0^t (t-s)^{\alpha-1} f_3(t, s, x(\gamma_1(s)), x(\gamma_2(s)), \dots, x(\gamma_n(s))) \, \mathrm{d}s, \end{aligned}$$
(74)

with similar method under appropriate modifications. Then so obtained results are useful in determining the global attractivity and positivity and global asymptotic attractivity and positivity of solutions for the fractional functional integral equations defined, respectively, by

$$\begin{aligned} x\left(t\right) &= \frac{1}{2}te^{-t^{2}/2} \\ &+ \frac{t^{2}+1}{t^{2}+4} \times \frac{\sum_{i=1}^{n} \arctan\left(|x\left(it\right)|\right)}{9 + \arctan\left(\sum_{i=1}^{n}|x\left(it\right)|\right)} \\ &+ \frac{t + \sqrt{t}\left[\sum_{i=1}^{n}x\left(it\right)\right]}{\Gamma\left(2/3\right)} \\ &\times \int_{0}^{t} \frac{e^{-3t-s\sqrt[3]{\sum_{i=1}^{n}x^{2}\left(is\right)/4}}{(t-s)^{1/3}} ds, \end{aligned}$$

$$\begin{aligned} x\left(t\right) &= \frac{1}{2}te^{-t^{2}/2} \\ &+ e^{-t}\frac{\sum_{i=1}^{n} \arctan\left(|x\left(it\right)|\right)}{9 + \arctan\left(\sum_{i=1}^{n}\left(|x\left(it\right)|\right)\right)} + \frac{t + \sqrt{t}\left[\sum_{i=1}^{n}x\left(it\right)\right]}{\Gamma\left(2/3\right)} \\ &\times \int_{0}^{t} \frac{e^{-3t-s\sqrt[3]{\sum_{i=1}^{n}x^{2}(is)}/4} + 1/\left(10t^{8/3} + 1\right)}{(t-s)^{1/3}} \mathrm{d}s. \end{aligned}$$

$$(75)$$

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