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Judul Karya Ilmiah (paper)

: Development of Two Components Acceleration Time Histories for Semarang, Indonesia,

Due to Semarang Fault Earthquake Scenarios Using 30 Meters Soil Deposit Model

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(2018),

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b. ISBN/ISSN

: 2261-236X

c. Tahun Terbit, Tempat Pelaksanaan: Denpasar, 24-26 Agustus 2017

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Prof. Dr. Ir. Sri Tudjono, MS NIP .195303091981031005

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LEMBAR HASIL PENILAIAN SEJAWAT SEBIDANG ATAU PEER REVIEW KARYA ILMIAH: PROSIDING

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2nd International Joint Conference on Advanced Engineering and Technology, IJCAET 2017 and International Symposium on Advanced Mechanical and Power Engineering, ISAMPE 2017; Bali; Indonesia; 24 August 2017 through 26 August 2017; Code 135617

Development of two components acceleration time histories for Semarang, Indonesia, due to Semarang fault earthquake scenarios using 30 meters soil deposit model (Conference Paper) (Open Access)

Partono, W. Q

Civil Engineering Department, Diponegoro University, Semarang, 50275, Indonesia

Abstract View references (11)

Development of surface acceleration time histories is important for dynamic analysis of structure design and evaluation. Acceleration time histories usually developed from seismograph records due to specific earthquake event. Following the research conducted by Team for Revision of Seismic Hazard Maps of Indonesia 2010 and 2016, Lasem fault and Semarang fault are two closest and dangerous shallow crustal fault earthquake sources which must be taken into account for seismic mitigation of Semarang. This paper presents the development two components surface acceleration time histories for Semarang caused by Semarang fault earthquake scenarios, with magnitude from 6 Mw to 7 Mw and maximum epicentre distance 15 Km. This research was performed by conducting deterministic hazard analysis, response spectral matching and site response analysis to obtain a pair of modified acceleration time histories. Site response analysis was performed by conducting 30 meters soil deposit model by taking the assumption that the position of bedrock elevation is 30 meters below the surface layer. Modified acceleration time histories were developed from a pair time histories (North-South/NS and East-West/EW direction) collected from worldwide historical earthquakes. Modified time histories were developed due to limited time histories data caused by Semarang fault earthquake source. © The Authors, published by EDP Sciences, 2018.

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Indexed keywords

Engineering controlled terms:

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Acceleration-time history Dynamic analysis of structures Earthquake scenario

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Table of Contents

Welcome message from General Chair	i
Welcome message from Dean of Faculty of Engineering - Diponegoro University, Indonesia	ii
Welcome message from Dean of College of Engineering - Pukyong National University, South Korea	iii
Welcome message from Dean of Faculty of Engineering - Udayana University, Indonesia	iv
International Advisory Board, Conference Chair, Conference Secretary, Organizing Committee	V
Program Chair, Proceeding Manager	vi
Website/Publicity/Photographer, Treasury	vii
Local Arrangement Committee, Student Volunteer	viii
Scientific Committee	ix
IJCAET & ISAMPE Program at Glance	xii
Keynote Speaker	xiii
Invited Speaker	xiv
Table of Content	ΧV
IJCAET 2017 Submission Title	1
ISAMPE 2017 Submission Title	15
IJCAET Abstract	17
ISAMPE Abstract	97

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Vice Minister of Energy and Mineral Resources, the Republic of Indonesia



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Emeritus Professor of Planning and Urban Development, The University
of New South Wales, Sydney, Australia

"Robots, Wind farms, and the internet: The ethics of technology in a changing world"



3. Prof. Andrew Price
Loughborough University, UK
Civil and Building Engineering Department

"Improving critical infrastructure performance through advanced engineering and innovation"



4. Assoc. Prof. Tomomi Honda

University of Fukui, Japan
Department of Mechanical Engineering, Faculty of Engineering
Graduate School of Engineering

"New diagnosis methods of the lubrication oils for the proactive maintenance"

INVITED SPEAKER



Prof. Buntara Sthenly Gan
Architecture Department Nihon University, Koriyama Japan

"Isogeometric Analysis for Beam Element"



Assoc. Prof. Tegoeh Tjahjowidodo
School of Mechanical and Aerospace Engineering, Nanyang
Technological University (NTU), Singapore

"An Integrated-Intelligent Re-manufacturing Process"



Prof. Niro Nagai
Mechanical Engineering Department, University of Fukui, Japan

"Boiling research in Japan, cooling technology of high-temperature material"



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Electrical and Electronics Engineering Department, Universiti Teknologi Petronas (UTP), Malaysia Dean of Centre for Graduate Studies (UTP)

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- IJCAET 5 EFFECTS OF DIFFERENT HEEL HEIGHTS ON HEEL PRESSURE DISTRIBUTION FOR CALCANEAL SPUR PATIENTS DURING STANDING: FINITE ELEMENT ANALYSIS Dwi Basuki Wibowo, Achmad Widodo, Gunawan Dwi Haryadi and Agus Suprihanto
- IJCAET 10 SYNTHESIS SENSITIVE LAYER OF ETHYLENE GAS SENSOR BASED TIN OXIDE NANOPARTICLES USING WATER AS SOLVENT IN PRECIPITATION METHOD Erica Caesariaty Harni Prima Nabena, Brian Yuliarto and Nugraha
- IJCAET 12 DEVELOPMENT OF 6 DOF SUPERNUMERARY ROBOTIC FINGERS INTEGRATED WITH 3D ANIMATION

 Mochammad Ariyanto, Joga D. Setiawan, M Munadi, Rifky Ismail and Zainal Arifin
- IJCAET 14 COMPARISON VARIATION CEMENT AGAINST PROPERTIES CONCRETE MASONRY BRICK CLC Erwin Sutandar, Asep Supriyadi and Cek Putra Andalan
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 Syaiful, Imam Syarifudin, Maria F. Soetanto and Myung Whan Ba
- IJCAET 19 A SIMPLIFIED FIVE-LEVEL VOLTAGE SOURCE INVERTER FOR DC-AC POWER CONVERSION
 Suroso Suroso and Abdullah Nur Azis
- IJCAET 23 3D NUMERICAL STUDY OF THE EFFECT OF THE SHAFT ECCENTRICITY ON THE TRIBOLOGICAL PERFORMANCE OF THE LUBRICATED SLIDING CONTACT Mohammad Tauviqirrahman, Bayu Kurniawan and J Jamari
- IJCAET 24 EFFECT OF LIQUID ADDITIVE ON DRY GRINDING FOR DESIRED SURFACE STRUCTURE OF CAO CATALYST
 Wiyanti Fransisca Simanullang and Shinya Yamanaka
- IJCAET 25 RIGHT TURN COEFICIENT EVALUATION ANALYSIS ON INTERSECTION CAPASITY FUNCTION AT INDONESIA HIGHWAY CAPASITY MANUAL 1997 USING VEHICLE TRACKING SIMULATION

 Basuki Kami Hari and Purwanto Dioko
- IJCAET 26 FABRICATION DYE SENSITIZED SOLAR CELLS (DSSCS) USING NATURAL DYE FROM PIGMENT PHOTOSYNTHESIS OF SYNGONIUM SP.
 Wa Ode Nirwana Sari Halidun, Eka Cahya Prima and Brian Yuliarto
- IJCAET -31 COMPARISON OF RATIO LOADED AND UNLOADED FOOT AREA OF FLAT FOOT AND HEALTHY FOOT IN YOUNGER ADULTS
 Gunawan Dwi Haryadi, Dwi Basuki Wibowo, Achmad Widodo and Agus Suprihanto
- IJCAET 32 FAILURE ANALYSIS CIRCULATING WATER PUMP (CWP) SHAFT USED IN POWER PLANT
 Abdul Hamid, Sri Nugroho, Gunawan Dwi Haryadi, Deni Fajar Fitriyana and Suluh Pertiwanda
- IJCAET 34 ANALYSIS OF CALCIUM CARBONATE POLYMORPHS DEPOSITED IN WATER PIPING SYSTEM AND THE EFFECT OF TARTARIC ACID ADDITIVE Wahyu Putranto, Yusuf Umardani, Sulistyo Sulistyo, Yurianto Yurianto and Athanasius Bayuseno

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 Dong-Youn Shin, Chonticha Kunpai, Min Gu Kang and Hee-Eun Song
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 Ian Yulianti, Ngurah Made Darma Putra, Yuni Lestiyanti and Ojo Kurdi
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 Fahrudin
- IJCAET 39 MECHANICAL PROPERTIES OF POLYMETHYL METHACRYLATE IN MEDICAL IMPLANT MANUFACTURING USING THREE-DIMENSIONAL PRINTING Siti Norsyahirah Abdul Razak, Jamaluddin Abdullah and Hazizan Md Akil
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 Hartomo Soewardi, Aldano Bridaga Putra and Faisal Rm
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- IJCAET 45 FABRICATION AND CHARACTERIZATION OF FISH COLLAGEN/ALGINATE BASED SCAFFOLD CONTAINING CHITOOLIGOSACCHARIDES FOR SKIN TISSUE ENGINEERING

 Won-Kyo Jung and Milan Pathum Chandika Srirangadeniye Don Patabedige
- IJCAET 46 BULBOUS BOW APPLICATIONS ON A FISHING VESSEL CATAMARAN FOR IMPROVED PERFORMANCE Samuel Samuel, Dong-Joon Kim, Aldias Bahatmaka, May Thu Zaw and Muhammad Iqbal
- IJCAET 47 DESIGN OPTIMIZATION OF SUSTAINABLE AUTOMOTIVE PARTS BY RKPM BASED CAE

 Kyu-Taek Han
- IJCAET 48 INVESTIGATION ON THE PERFORMANCE OF THE TRADITIONAL INDONESIAN FISHING VESSEL
 Aldias Bahatmaka, Dong-Joon Kim, Samuel Samuel and May Thu Zaw
- IJCAET 49 DESIGN AND PERFORMANCE ANALYSIS OF I-PID CONTROLLERS FOR AUTOMATIC VOLTAGE REGULATOR (AVR) SYSTEM Yeonwook Choe
- IJCAET 52 THE STRUCTURAL RESPONSE INVESTIGATION OF MODULAR PONTOON COLLAR FLOATING CAGE DUE TO CURRENT LOAD TO SUPPORT FISH FARMING ACTIVITIES Aulia Windyandari and Ahmad Zakki
- IJCAET 53 3D FEM ANALYSIS FOR A LONG-THIN MAGNETIC OBJECT BY USING A BOUNDARY CONDITION TECHNIQUE Young-Hak Kim
- IJCAET 54 EFFICIENT CLASSIFICATION OF ISAR IMAGES USING MOMENTS INVARIANT TO TRANSLATION AND ROTATION Sang-Hong Park
- IJCAET 56 CHARACTERISTICS OF LATERITIC NICKEL MINERALIZATION IN MID PART OF MADANG AND SERAKAMAN AREAS, SEBUKU ISLAND, SOUTH KALIMANTAN Yudi Syahputra and Yoga Aribowo

- IJCAET 57 MORPHOLOGY EVOLUTION OF ZnO THIN FILMS DEPOSITED BY NITROGEN MEDIATED CRYSTALLIZATION METHOD Iping Suhariadi, Naho Itagaki and Masaharu Shiratani
- IJCAET 58 WET-CHEMICAL SYNTHESIS OF NITROGEN-DOPED GRAPHENE FOR ENERGY CONVERSION AND STORAGE Dong Wook Chang
- IJCAET 59 DEVELOPMENT OF CONCENTRIC ANNULAR HEAT PIPE FOR PASSIVE COOLING SYSTEM OF SPENT FUEL POOL Jongsoo Kim
- IJCAET 60 MULTI-OBJECTIVE HULL FORM OPTIMIZATION TO IMPROVE PERFORMANCE OF FISHING VESSELS

 May Thu Zaw, Dong Joon Kim, Seung Woo Shin, Samuel Samuel and Aldias Bahatmaka
- IJCAET 63 IMPACT PHENOMENA ASSESSMENT: PART I STRUCTURAL PERFORMANCE OF A TANKER SUBJECTED TO SHIP GROUNDING IN THE ARCTIC OCEAN Aditya Rio Prabowo, Dong Myung Bae, Jung Min Sohn and Joung Hyung Cho
- IJCAET 64 THE EFFECT OF SHEAR WALL CONFIGURATION ON SEISMIC PERFORMANCE IN THE HOTEL BUILDING

 Daud Rahmat Wiyono, Roi Milyardi and Cindrawaty Lesmana
- IJCAET 65 IMPACT PHENOMENA ASSESSMENT: PART II BUFFER CONTAINER AS A MEASURE TO REDUCE CARGO LEAKAGE IN COLLISION Aditya Rio Prabowo, Jung Min Sohn, Dong Myung Bae, Aldias Bahatmaka, Chul Soo Kim and Myung Soo Kim
- IJCAET 66 A STUDY ON OBJECT RECOGNITION USING IR-UWB RADAR BASED ON KNN(K-NEAREST NEIGHBOUR)

 Dong Heon Lee, Jae Hoon Jeong, Min Kim, Mihret Gebreslassie and Gi Sig Byun
- IJCAET 67 DESIGN OF AN OFF GRID TYPE HIGH EFFICIENCY SOLAR CHARGING SYSTEM WITH MPPT (MAXIMUM POWER POINT TRACKING) USING MATLAB/SIMULINK Mihret Gebreslassie, Dong Heon Lee, Jae Hoon Jeong, Jae Jun Lim, Min Kim and Gi Sig Byun
- IJCAET 69 EXPERIMENTAL STUDY ON THE PERFORMANCE AND EXHAUST EMISSIONS OF A
 DIESEL ENGINE FUELLED WITH HEVEA BRASILIENSIS BIODIESEL BLENDS
 Khairil Daud, Samsul Bahri, Iskandar and Arridina Susan Silitonga
- IJCAET 71 BGA Shape Inspection using Reflection Image Jee Hong Kim
- IJCAET 73 BARRIERS TO THE APPLICATION OF PASSIVE HOUSE TO INDIVIDUAL HOUSING IN VIETNAM

 Hai Pham, Soo-Yong Kim, Truong-Van Luu and Minh-Hong Le
- IJCAET 75 DESIGN OF FRACTAL FEATURES-BASED PARTIAL DISCHARGE PATTERN RECOGNITION USING MULTI SUPPORT VECTOR MACHINE METHOD Rahayu, Gama Titis Anuraga, Hikmah Prasetia and Umar Khayam
- IJCAET 78 THE EXPERIMENTAL STUDY OF RETROFITTING R410A CHARGED SPLIT-TYPE AIR CONDITIONER INTO R290 WITH VARYING THE CHARGED MASS OF R290 Berkah Fajar Tk. and Geraldus Dipto
- IJCAET 80 COMPARISON OF GENETIC ALGORITHM AND HARMONY SEARCH METHOD FOR 2D GEOMETRY OPTIMIZATION Mohammad Ghozi and Anik Budiati

- IJCAET 81 THE CHARACTERISTICS INFLUENCE OF COMMODITIES FREIGHT GENERATION PRODUCTION IN THE INTERNAL -REGIONAL ZONE TOWARD SUSTAINABLE HIGHWAY FREIGHT TRANSPORTATION NETWORK SYSTEM

 Juang Akbardin, Danang Parikesit, Bambang Riyanto and Agus Taufik Mulyono
- IJCAET 82 CONNECTIVITY RELATIONSHIP OF FLUID FLOW ON SHEAR BAND: STUDY CASE AT PETANI FORMATION, RIAU, INDONESIA.

 Tiggi Choanji, Novia Rita, Aulia Pradana and Yuniarti Yuskar
- IJCAET 83 EFFECT OF QUENCHING AGENT ON DIMENSION STABILITY OF AL 6061-Al2O3 COMPOSITE Hammar Ilham Akbar, Eko Surojo and Dody Ariawan
- IJCAET 85 PHYSICO-CHEMICAL ANALYSIS TO DETERMINE GROUNDWATER QUALITY IN JANGKANG AND DELUK VILLAGE, BENGKALIS REGENCY, RIAU PROVINCE Dewandra Bagus Eka Putra, Yuniarti Yuskar and M. Sapari Dwi Hadian
- IJCAET 86 STUDY ON SC-BEARING LATERITIC NI DEPOSITS IN ULTRAMAFIC ROCK FROM SULAWESI: A NEW PARADIGM IN INDONESIA METAL MINING INDUSTRY.

 Adi Maulana, Kenzo Sanematsu, Sufriadin Sufriadin and Sakakibara Masayuki
- IJCAET 87 ANALOG SANDSTONES RESERVOIR BASED ON SURFICIAL GEOLOGICAL DATA AT BEKASAP FORMATION, CENTRAL SUMATRA BASIN
 Yuniarti Yuskar, Dewandra Bagus Eka Putra, Tiggi Choanji, Ziadul Faiez and Muhammad Habibi
- IJCAET 88 OPTIMUM ROBUST CONTROL FOR AN OIL COOLER SYSTEM WITH VARIABLE SPEED DRIVE OF MACHINE TOOLS

 Seokkwon Jeong, Taeeun Kwon and Seungseob Park
- IJCAET 89 A RENDERING TECHNIQUES OF MEDICAL BIG DATA USING GPUS Joseph Yoon, Keon-Kuk Park, Oh-Seok Kwon and Young-Bong Kim
- IJCAET 90 AN INTEGRATION PSO-BASED FEATURE SELECTION AND RANDOM FOREST FOR ANOMALY DETECTION IN LOT NETWORK
 Bayu Adhi Tama and Kyung-Hyune Rhee
- IJCAET 91 CHARACTERIZATION OF STINGING NETTLE FIBERS AS A REINFORCING OF COMPOSITE MATERIAL BASED ON ITS GROWING REGION
 Igp Agus Suryawan, Ngakan Putu Gede Suardana, I Nyoman Suprapta Winaya and I Wayan Budiarsa Suyasa
- IJCAET 93 GHG'S EMISSION REDUCTION MEASURES AND VERIFICATION CHALLENGE AT TRANSPORT SECTOR
 Haryono Huboyo, Hari Wibowo and Winda Retnasari
- IJCAET 94 APPLICATION OF AQUIFER VULNERABILITY INDEX (AVI) METHOD TO ASSESS GROUNDWATER VULNERABILITY TO CONTAMINATION IN SEMARANG URBAN AREA Thomas Triadi Putranto, Narulita Santi, Dian Agus Widiarso and Dimas Wahyu Pamungkas
- IJCAET 97 HOUSING TYPOLOGY OF BALI AGA ARCHITECTURE IN SUKAWANA VILLAGE: DEVELOPMENTS AND CHALLENGES
 Ni Made Yudantini and Agus Surya Darma
- IJCAET 99 ON THE SOUND ABSORPTION IMPROVEMENT OF WATER HYACINTH AND COCONUT HUSK BASED FIBER REINFORCED POLYMER PANEL Erni Setyowati, Iwan Yahya, Edi Supriyo, Intan Cahya Romadhona and Aris Minardi
- IJCAET 100 A STUDY OF CHIP CHARACTERISTICS AND SURFACE ROUGHNESS ON LOW SPEED TURNING PROCESS ON VARIOUS COMMERCIAL STEELS Mudjijanto, Lis Prasetyo, Wahyu Isti Nugroho, Sulistyo and Rusnaldy

- IJCAET 101 FABRICATION OF MWCNT/PU COMPOSITE NANOFIBROUS SCAFFOLDS WITH CONTROLLABLE NANOTOPOGRAPHY FOR NEURAL REPAIR Jeong In Kim, Cheol Sang Kim and Chan Hee Park
- IJCAET 102 A FAIL-SAFE SCHEME FOR OPTICAL CAMERA COMMUNICATION Willy Anugrah Cahyadi and Yeon Ho Chung
- IJCAET 103 BARRIERS IN APPLYING PASSIVE HOUSE IN VIETNAMESE PRIVATE HOUSES Soo-Yong Kim, Truong-Van Luu, Minh-Hong Le, Chi-Han Ho and Hai Pham
- IJCAET 104 HETEROGENEOUS NANOPARTICLE ASSEMBLIES IN PS-B-PAA MICELLES WITH ENHANCED SERS ACTIVITY

 Maulida Zakia, Namjin Je, Limpat Nulandaya, Chang Hyun Song and Seong II Yoo
- IJCAET 105 FACTORS CONTRIBUTING CORRUPTION IN THE CONSTRUCTION PROJECTS IN IRAN KIYANOOSH
 Golchin Rad, Soo Yong Kim and Hwan Woo Lee
- IJCAET 106 DYNAMIC STATE SPACE MODELING USING NONPARAMETRIC BAYESIAN HMMS Bong-Kee Sin and Sung-Un Kim
- IJCAET 108 DEVELOPMENT OF SEISMIC RISK MICROZONATION MAP FOR SEMARANG DUE TO SEMARANG FAULT EARTHQUAKE SCENARIO WITH MAXIMUM MAGNITUDE 6.9 MW
 Windu Partono, Masyhur Irsyam and Sri Wardani
- IJCAET 109 ADDITIONAL OCCUPATIONAL SKILLS FOR SMART WORKERS OF SMART WORK CENTERS

 Man-Gon Park and Hyun-Ki Park
- IJCAET 111 REAR WHEEL DRIVE RECUMBENT BICYCLE FOR URBAN TRANSPORTATION IN A TROPICAL EMERGING COUNTRY

 Bambang Suhardi, Ilham Priadythama and Pringgo Widyo Laksono
- IJCAET 116 FINITE ELEMENT ANALYSIS ON THE BELLOWS FOR METAL EXPANSION JOINTS Doo-Hyung Jeong, Byung-Tak Kim, In-Pil Kang, Chan-Jung Kim and Sung-Wi Koh
- IJCAET 117 THE INFLUENCE OF WELDING SPEED VARIATIONS ON GMAW TO THE MECHANICAL PROPERTIES OF AUSTENITIC STEEL AISI 316L
 I Made Wicaksana Ekaputra, Sudi Mungkasi, Gunawan Dwi Haryadi, Rando Tungga Dewa and Seon Jin Kim
- IJCAET 118 UVC UPCONVERSION OF Y2SIO5:PR3+ THIN-FILM PHOSPHOR FOR THE STERILIZATION
 Youngwoo Jeong, Jaehyoung Park, Jongsu Kim and Heelack Choi
- IJCAET 119 SECURITY FRAMEWORK FOR LOT SERVICES BASED ON FOG AND CLOUD COMPUTING
 Minjeong Shin, Bong-Kee Sin and Sung-Un Kim
- IJCAET 120 TOP-EMISSION ELECTROLUMINESCENT DEVICES BASED ON GA-DOPED ZNO ELECTRODES

 Wunho Lee, Wontae Jang, Semo Son, Jongsu Kim and Sangnam Lee
- IJCAET 121 THE MODELING OF A CONCEPTUAL ENGINEERING DESIGN SYSTEM USES THE DECISION-MATRIX LOGIC Safarudin Ramdhani and J Jamari
- IJCAET 122 NUMERICAL ANALYSIS ON THE THERMAL PERFORMANCE IN THE AIR DUCT OF PV-T SYSTEM
 Hwiung Choi, Fatkhur Rokhman, Changhyo Son, Jungin Yoon, Youngbok Kim and Kwanghwan Choi

- IJCAET 123 EXPERIMENTAL STUDY PERFORMANCE OF AC MACHINE FILLED BY REFRIGERANT R290 99,5% AND R290 95% Imam Ridwan Tanaka, Berkah Fajar Tk, Eflita Yohana, Tony Suryo Utomo and Mustaqim
- IJCAET 125 ELECTRIC RESISTANCE HEATED FRICTION STIR SPOT WELDING OF OVERLAPPED MG AZ31 ALLOY SHEETS
 Intai Jin
- IJCAET 126 ENHANCEMENT SURFACE COATING STAINLESS STEEL AND COPPER USING ULTRASONIC BATCH
 Sendie Yuliarto Margen, Sulistyo, Sri Nugroho and Yoga Setiawan Adi Nugroho
- IJCAET 131 A HEURISTIC ALGORITHM FOR A VEHICLE ROUTING PROBLEM WITH DELIVERY AND PICK-UP OF MULTIPLE INDUSTRIAL GAS CONTAINERS

 Woon-Seek Lee, Kyung Joo Yoo, Sanghuck Seo, Jaehee Won, Jiwon Park, Dahun Kim and Moonjung Kim
- IJCAET 132 DEVELOPMENT OF AN AUTOMATIC CALIBRATION PROGRAM OF SWMM AND ITS USER INTERFACE Sangho Lee, Taeuk Kang and Taehun Jung
- IJCAET 133 PROCESS INNOVATION OF TIG WELDING AS A GREEN TECHNOLOGY IN SMART FACTORY
 Sang-Myung Cho, Byung-Woo Lee and Won-Chan Seo
- IJCAET 134 TRAJECTORY TRACKING AND BACKSTEPPING CONTROL FOR AUTOMATIC GUIDED VEHICLE(AGV)

 Dae Hwan Kim, Hyuk Yim and Sang Bong Kim
- IJCAET 136 AN APPLICATION OF AHP FOR THE SELECTION OF LNG FUELED ENGINE TYPE FOR 1000TEU CLASS CONTAINER SHIP & 50K TANKER Yeun-Hee Song, Dong-Joon Kim and Kyong-Cheol Min
- IJCAET 137 INTERVAL CONFINEMENT IN COMPRESSION ZONE TO EVALUATED BEAMS PERFORMANCE SUBJECTED MONOTONIC LOADS
 Yulita Arni Priastiwi, Iswandi Imran, Nuroji and Rudi Yuniarto Adi
- IJCAET 138 MACHINE HEALTH PROGNOSIS BASED ON MULTI-REGIME CONDITION MONITORING SIGNALS Achmad Widodo, Toni Prahasto, Djoeli Satrijo, Budi Setiyana, Sugiyanto Sugiyanto, Didik Djoko Susilo and Ismoyo Haryanto
- IJCAET 142 AN EXPERIMENTAL REALIZATION OF A TWO-DIMENSIONAL LOCAL DEFECT TYPE SONIC CRYSTAL Hanief Beta Azimut, Iwan Yahya and Harjana Harjana
- IJCAET 143 THE TUNING OPTION FOR SPHERICAL RESONANT SOUND SCATTERER WITH VARIOUS ORIFICE TYPES
 Aris Minardi, Iwan Yahya, Harjana Harjana and Hanief Beta Azimut
- IJCAET 145 THE EFFECT OF ACID LEACHING TIME IN MODIFYING NATURAL ZEOLITE AS CATALYST FOR TOLUENE STEAM REFORMING

 Joko Waluyo, Igbn Makertihartha and Herri Susanto
- IJCAET 146 AN INVESTIGATION OF SPATIAL ARRANGEMENT, FORM AND STRUCTURAL SYSTEM OF TRADITIONAL HOUSES IN PEDAWA INDIGENOUS VILLAGE- BALI Tri Anggraini Prajnawrdhi
- IJCAET 147 DESIGN OF KEY PERFORMANCE INDICATORS (KPI) FOR SUSTAINABLE SUPPLY CHAIN MANAGEMENT (SSCM) PALM OIL INDUSTRY IN INDONESIA Elisa Kusrini and Rangga Primadasa

- IJCAET 149 CLUSTER READINESS LEVEL: DEVELOPMENT OF READINESS LEVEL
 MEASUREMENT
 Novi Marlyana, Alva Edy Tontowi and Hari Agung Yuniarto
- IJCAET 151 A REVIEW ON SENSORS FOR REAL-TIME MONITORING AND CONTROL SYSTEMS
 ON MACHINING AND SURFACE FINISHING PROCESSES
 Wijaya, Wahyu Caesarendra, Tegoeh Tjahjowidodo and Bobby K Pappachan
- IJCAET 152 THE ANALYSIS OF VOLCANIC ACTIVITY INFLUENCES AT THE LOWER AND MIDDLE PART OF SENTOLO FORMATION, KULON PROGO USING PETROGRAPHIC METHOD

Tri Winarno, Jenian Marin and Ilham Hani Pratama

- IJCAET 153 EFFECT OF BLANCHING-BRINE-CALCIUM PRETREATMENT ON CHILI (CAPSICUM FRUTESCENS) DRYING KINETICS

 Uma Fadzilia Arifin and Mohamad Djaeni
- IJCAET 155 ANALYSIS OF LAND SLIDE DISASTER IMPACT IDENTIFICATIO USING UNMANNED AERIAL VEHICLE (UAV) AND GEOGRAPHIC INFORMATION SYSTEM (CASE STUDY: NGESREP SUB DISTRICT, SEMARANG CITY)
 Yudo Prasetyo, Nurhadi Bashit and Reyhan Azeriansyah
- IJCAET 156 DETECTION OF GEARS SYSTEM DEFECTS USING METHOD OF WAVELET DECOMPOSITION AND CROSS CORRELATION EXPERIMENTS TO DEVELOPE A FEASIBLE DETECTION METHOD

 R Lullus Lambang G Hidajat and Budi Santoso
- IJCAET 157 DESIGN OF FULL-SCALE FORWARD OSMOSIS (FO) SYSTEMS USING A SIMPLE FO MODULE MODEL

 Jongmin Jeon, Jaehak Jung, Joon Young Choi and Suhan Kim
- IJCAET 158 PALAEOECOLOGICAL ANALYSIS OF SENTOLO FORMATION BASED ON FORAMINIFERA FOSSIL ASSEMBLAGE FROM STRATIGRAPHIC CROSSSECTIONAL MEASUREMENTS IN PENGASIH, KULONPROGO, YOGYAKARTA Anis Kurniasih, Muhammad Idham Fauzan and Reddy Setyawan
- IJCAET 159 EFFECT OF CITRIC ACID IN SLURRY ON FRICTIONAL CHARACTERISTICS OF CMP Hyunseop Lee
- IJCAET 160 ORGANIC SOLAR CELLS APPLICATION OF SOLUTION-PROCESSED BULK-HETEROJUNCTION SMALL MOLECULES BASED ON BENZOTHIADIAZOLE DERIVATIVES

 Nadhila Sylvianti, Youn Whan Kim, Mutia Anissa Marsya and Joo Hyun Kim
- IJCAET 161 STRESS ANALYSIS OF THE VINYL FEEDING MACHINE BY USING FINITE ELEMENTS METHOD

 Jiwook Kim, Chulwoong Jun, Jeonghyun Sohn and Chanjung Kim
- IJCAET 162 STUDY ON THE FLOW ANALYSIS OF 3D INCOMPRESSIBLE FLUID BY USING THE ISPH METHOD

 Minseok Yang, Jiwook Kim, Chulwoong Jun and Jeonghyun Sohn
- IJCAET 163 OPTIMIZATION OF FOAM MAT DRYING OF ROSELLE (HIBISCUS SABDARIFFA L.)
 EXTRACT
 Mohamad Djaeni and Febiani Utari
- IJCAET 164 INTEGRATION OF GREEN QUALITY FUNCTION DEPLOYMENT, MODULARITY AND LIFE CYCLE ASSESSMENT TOWARDS SUSTAINABLE PRODUCT DESIGN Heru Prastawa and Sri Hartini
- IJCAET 165 A FAST MOTION ESTIMATION ALGORITHM USING SELECTIVE PDE METHOD Jongnam Kim

A Review on Sensors for Real-time Monitoring and Control Systems on Machining and Surface Finishing Processes

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Abstract. One of the key components in real-time monitoring and control on machining and surface finishing processes are sensors. The advances of such system have triggered interesting questions on sensor selection that act as the fundamental before starting a project. This paper is made to review and answer the questions surrounding sensor selection. The paper first explains on the type of sensors commonly used in practice for real-time monitoring and control systems. After which, the paper discusses on how often the sensors are used on several machining and surface finishing processes and what are the reasons for the sensor selection. Thereafter, a review on the type features commonly analysed through these sensors is discussed. The paper expects reader would decide better upon selecting sensors and has a better direction in their project. Thus the paper works to guide reader to improve based on what has been completed before.

1 Introduction

The development of manufacturing industry nowadays is pushed to its limit to fulfil the demand of market. The market requires better quality products, more variability, shorter product life cycle, reduced product cost, and globally competitive products [1].

Machining and surface finishing processes develops in the direction of immediate integration with real-time monitoring and control systems to allow users to monitor and control the events happening during machining and surface finishing.

The selection of sensors is one of the fundamental building block for real-time monitoring. This paper will discuss on the sensors used in other real-time monitoring and control projects to better inform reader on suitable sensor application for their project.

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- IJCAET 168 AN EXPERIMENTAL PERFORMANCE TEST APPROACH OF DUAL SOURCE HYBRID SOLAR COLLECTOR UNDER QUASI-DYNAMIC TEST CONDITION Fatkhur Rokhman, Hwiung Choi, Youngbok Kim, Changhyo Son, Jungin Yoon and Kwanghwan Choi
- IJCAET 170 EFFECTS OF CHARACTERISTIC LENGTH VARIATION ON THE PERFORMANCE OF A 70 N-CLASS HYDRAZINE THRUSTER

 Jeong Soo Kim, Seong Hun Bae, Joon Yeol Hong and Dae Seok Bae
- IJCAET 171 BEHAVIOUR OF NATURAL FREQUENCY AND DAMPING ACCORDING TO IMPACT AND CRACK POSITION IN CANTILEVER BEAM Moonchul Yoon, Jongdo Kim and Dohun Chin
- IJCAET 172 DEVELOPMENT OF COLLABORATION IN SUSTAINABLE AGRIBUSINESS CLUSTER Tomy Perdana, Fernianda Rahayu Hermiatin and Tetep Ginanjar
- IJCAET 173 COMBUSTION CHARACTERISTICS OF KEROSENE DROPLETS GENERATED BY ULTRASONIC ATOMIZATION

 Dae Seok Bae, Seong Hun Bae, Joon Yeol Hong and Jeong Soo Kim
- IJCAET 176 RESISTANCE AND STABILITY ANALYSIS FOR CATAMARAN VESSEL WITH SOLAR CELL IN CALM WATER

 Teguh Putranto, Wasis Aryawan, Hesty Kurniawati, Aries Sulisetyono, Dony Setyawan and Sri Rejeki Wahyu Pribadi
- IJCAET 178 PATH PLANNING FOR AUTOMATIC GUIDED VEHICLE WITH MULTIPLE TARGETS IN DYNAMIC ENVIRONMENT Chang Kyu Kim, Huy Hung Nguyen, Dae Hwan Kim, Hak Kyeong Kim and Sang Bong Kim
- IJCAET 179 SERVO CONTROLLER DESIGN AND FAULT DETECTION ALGORITHM FOR SPEED CONTROL OF A FISH SORTING CONVEYOR SYSTEM Hwan Yeol Jang, Trong Hai Nguyen, Duy Cuong Tran, Hak Kyeong Kim and Sang Bong Kim
- IJCAET 180 RIVER CONSERVATION USING SECEEL APPROACH (A CASE STUDY ON BANJIR KANAL TIMUR RIVER, SEMARANG CENTRAL JAVA, INDONESIA) Ignatius Sriyana
- IJCAET 181 ESHOTICS (ELECTRONIC SHAKE BOTTLE HEATER INDUCTION ELECTROMAGNETIC SYSTEM): INNOVATIVE PORTABLE WATER HEATER BOTTLES FOR TRAVELERS

 M. Iqbal Sabit, Rahmawati F. Putri, Hasyim Abdulloh, Nuraditya A. Fadhilah and David Arohman
- IJCAET 182 MODELLING AND ANALYSIS THE EFFECT OF UNBALANCED MOMENT DIRECTIONS ON BEHAVIOUR OF EDGE COLUMN-SLAB CONNECTIONS
 I Ketut Sudarsana, I Gede Adi Susila and I Gede Gegiranang Wiryadi
- IJCAET 183 A COMPARISON OF DEGRADATION RATE BONE SCAFFOLD MORPHOLOGY BETWEEN COMPUTER SIMULATION AND EXPERIMENTAL APPROACH Hasan Basri, Akbar Teguh Prakoso and Ardiyansyah Syahrom
- IJCAET 184 A STUDY CHIP FORMATION OF COMMERCIAL STEEL MATERIALS AT LOW SPEED WORKPIECE CYLINDRICAL GRINDING PROCESS
 Wahyu Isti Nugroho, Mudjijanto, Lis Prasetyo, Sri Nugroho and Rusnaldy
- IJCAET 186 OPTIMIZATION OF IRRIGATION WATER USE TO INCREASE THE BENEFIT FROM AGRICULTURAL PRODUCTS
 Edy Anto Soentoro, Erlangga Perwira, Yadi Suryadi and Winskayati
- IJCAET 187 DEPTH CONTROL OF UNDERWATER GLIDER BY USING A REDUCED ORDER OBSERVER
 Hyeonggon Son and Moon Joo

- IJCAET 188 SEDIMENTATION PATTERN IN DELTA OF RESERVOIR Iskahar, Suripin and Isdiyana
- IJCAET 189 MEASUREMENT OF INJURY RATE ON FISH SKIN AND PERFORMANCE COMPARISON BY L*A*B* AND HSV COLOR SPACE BASED APPROACHES

 Minh Thien Tran, Jotje Rantung, Trong Hai Nguyen, Hak Kyeong Kim and Sang Bong Kim
- IJCAET 193 MECHANICAL DESIGN AND MODELING OF A BIPED ROBOT FOR ARGENTINA TANGO
 Doosung Ahn
- IJCAET 195 SULFATE FOR FLUID FLOW THROUGH PIPE SYSTEM IN THE PRESENCE OF MALIC ACID SCALING OF BARIUM Farid Sariman and Athanasius P Bayuseno
- IJCAET 200 DESIGN AND FABRICATION OF A TWIST FIXTURE FOR MEASURING THE TORSIONAL STIFFNESS OF A TATA CAB CHASSIS
 Ojo Kurdi, Mohd Shukri Yob, Awisqarni Haji Ishamuddin, Agus Suprihanto, Susilo Adi Widyanto and Dwi Basuki Wibowo
- IJCAET 201 EFFECT OF VALUE CONGRUENCE, BRAND DISTINCTIVENESS, BRAND SOCIAL, BRAND WARMTH, AND MEMORABLE BRAND EXPERIENCE ON CUSTOMER-BRAND IDENTIFICATION AND CUSTOMER LOYALTY. (CASE STUDY: THE USERS OF ACER LAPTOP)

 Aries Susanty and Aprilia Tresnaningrum
- IJCAET 202 SYNTHESIS OF BARIUM SULFATE IN THE VARIATION OF MIXING SPEED, TEMPERATURE AND ADDITIVE CONCENTRATION
 Waleed Ali, Wahyu Putranto, Stefanus Muryanto and Athanasius Bayuseno
- IJCAET 203 DESIGN OF HYBRID NANOSTRUCTURE FOR ADSORPTION OF VOLATILE ORGANIC COMPOUNDS (VOCS)

 Devi Prashad Ojha and Han Joo Kim
- IJCAET 204 SIMULATION AND ANALYSIS OF THE AEROELASTIC-GALLOPING-BASED PIEZOELECTRIC ENERGY HARVESTER UTILIZING FINITE ELEMENT METHOD AND COMPUTATIONAL FLUID DYNAMIC
 Ismoyo Haryanto, Achmad Widodo, Toni Prahasto, Djoeli Satrijo, Iswan Pradiptya and Hassen Ouakad
- IJCAET 207 EFFECT OF METAKOALINE AND SUPERPLASTICISER ON THE FRESH PROPERTIES OF SELF COMPACTING- CONCRETE.

 Hassan Laminu, Ibrahim Ahmad and Zannah Alhaji Ali
- IJCAET 208 PERFORMANCE ANALYSIS OF SEA WATER SOLAR STILL TO PRODUCE FRESH WATER AND SALT WITH USING FLAT PLATE COLLECTOR Mulyanef Mulyanef, Duskiardi Duskiardi and Rahmat Hidayat
- IJCAET 209 CARDBOARD BASED MULTI-LAYERED HONEYCOMB FOR BUILDING NOISE CONTROL APPLICATIONS

 Abidia Nazaruddin, Iwan Yahya and Ubaidillah Ubaidillah
- IJCAET 210 CYLINDRICAL TUBES SONIC CRYSTAL FEATURING SECONDARY LOCAL MULTIPLE SLITS TYPE DEFECT
 Jabarudin Tito Ardanto, Iwan Yahya and Harjana Harjana
- IJCAET 211 PRELIMINARY LABORATORY INVESTIGATION ON THE SELF-COLLIMATION OF SONIC CRYSTAL WITH HOLLOW TYPE SECONDARY RESONANT SCATTERER Putriana Husnul Khatimah, Iwan Yahya, Harjana Harjana and Ubaidillah Ubaidillah
- IJCAET 212 SUSTAINABLE SOUND DIFFUSER ELEMENT DEVELOPMENT BY USING SLOTTED COUPLED RESONATOR OBTAINED FROM PLASTIC CUP Achmad Ma'Arij Cholati, Iwan Yahya, Harjana Harjana and Ubaidillah Ubaidillah

Measurement of injury rate on fish skin and performance comparison based on L*A*B* and HSV color spaces

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Abstract. This paper analyses and compares the performance of L*A*B* and HSV color spaces and applies them to calculate the injury rate on fish. To do these issues, the following steps are done. An original image is transformed into L*A*B and HSV color spaces. A channel "a" is separated from L*A*B* color space. In channel a, a formula to adjust "channel a value" is proposed to realize the shapes of injury on fish clearly and a new channel a is obtained by adjusting the channel a. The new channel "a" is converted into injury binary image by manual threshold. Otsu's method is applied converted the original channel a image of fish shape into binary image. Finally, by calculating the number of pixels of areas of shape and total injury of fish, the injury rate is calculated. The steps of image processing of HSV color space is similar to L*A*B* color space. The proposed process are tested on fish.

1 Introduction

"Machine vision", as a crucial part of sorting systems, enables automatic and non-destructive selecting of products that satisfy certain requirements. There are many different methodologies for image processing in recent years. Therefore, choosing a right color space in processing algorithms is crucial. Eyarkai et al. described that mangoes were measured during ripening in 24 hours and evaluated using L*A*B* and RGB color coordinates [1]. Using exactly color space is important for controlling of food quality. Ivana et al. measured color of food products by using L*A*B* and RGB color space[2]. In this paper, fruit quality based on L*A*B* color space is more accurate than RGB color space. On the other hand, Hitesh et al. used image processing technique to detect fish disease [3]. This issue is done by using image processing algorithms based on L*A*B* and HSV color spaces. A method to measure injury rate of fish surface based on K-means clustering image segmentation was represented by Sheng el at.[4]. This method calculated injury rate based on S channel of HSV color space. After that, Otsu's threshold was applied to converted S channel into binary image, and calculate injury rate by counting area pixels of injuries and total shape on fish. The results

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- IJCAET 213 ACOUSTICAL PROPERTIES OF PLANAR RESONATOR ARRAY OBTAINED FROM USED CARDBOARD FOR IMPROVING THE PERFORMANCE OF PLAITED BAMBOO PARTITION
 - Ana Ratni Fitrianingrom, Iwan Yahya, Harjana Harjana and Ubaidillah Ubaidillah
- IJCAET 214 ON THE USE OF PEANUT SHELL AS SUSTAINABLE SOUND ABSORBER

 Teguh Prasetiyo, Iwan Yahya and Ubaidillah Ubaidillah affiliation: Sebelas Maret University
- IJCAET 216 THE STUDY OF CREEP PROPERTY FOR CAST AND WROUGHT CONDITIONS OF NI-BASED HAYNES 282 SUPERALLOY Yong Sik Ahn and Young Joo Kim
- IJCAET 219 TEMPERATURE EFFECT OF CELLULOSE FIBER HYBRID POLYURETHANE TO THE MECHANICAL PROPERTIES

 Herald K. Adi, Fauzia H. Ikhwan and Mochamad Chalid
- IJCAET 223 THE CHARACTERISTICS STUDY OF PARKING USER BEHAVIOR TOWARD LOCATION ACCESSIBILITY OF NON-COMMERCIAL ACTIVITIES CENTER (CASE STUDY OFF STREET PARKING AT UPI)

 Juang Akbardin, Supratman Agus and Odih Supratman
- IJCAET 226 INCREASE OF FLEXIBILITY AND CONTACT TIGHTNESS BY DETERMINING GROOVE DIMENSION AT CIRCULAR WALL OF VALVE SEAT Gyeng Ah Kang, Da Som Lee, Dae Min Kang and Jae Seob Kwak
- IJCAET 227 SIMULATION OF OLEOPHOBICITY ON RIBLET SURFACE
 Tae Wan Kim, Won Chan Seo, Jae Seob Kwak and Young Whan Park
- IJCAET 228 REMAINING LIFE ASSESMENT OF SUPERHEATER TUBES IN BOILER OF A COAL POWER PLANT
 Habib Muhajir, Gunawan Dwi Hartadi, Rifky Ismail and Achmad Widodo
- IJCAET 230 DEVELOPMENT OF ACCELERATION TIME HISTORIES FOR SEMARANG, INDONESIA
 Windu Partono, Masyhur Irsyam and Sri Prabandiyani Retno Wardani
- IJCAET 231 FAULT DIAGNOSTIC SYSTEM BEARING CENTRIFUGAL PUMP USING K-MEANS METHOD FOR THERMOGRAPHY IMAGE AND SIGNAL ANALYSIS VIBRATIONS Agung Yudhistira, Achmad Widodo and Gunawan Dwi Haryadi
- IJCAET 232 INDUCTION MOTOR CENTRIFUGAL BLOWER HEALTH DIAGNOSTIC BASED ON COLOR SEGMENTATION OF THERMAL IMAGE AND VIBRATION SIGNAL FEATURE Panut Widodo, Gunawan Haryadi and Achmad Widodo
- IJCAET 233 FUZZY LOGIC-BASED HIGH ENERGY-EFFICIENT CLUSTERING HIERARCHY ROUTING PROTOCOL FOR WIRELESS SENSOR NETWORKS
 Thang Tran Viet, Cuong Tran Duy and Truyen Nguyen The
- IJCAET 234 DESIGN AND CONSTRUCTION OF SPUD HOUSING FOR FLOATING DOCK Hasanudin St and Ardi Nugroho Yulianto
- IJCAET 235 DEVELOPMENT OF GREEN SHIP-RECYCLING YARD IN INDONESIA: CHALLENGES AND OPPORTUNITIES

 Wasis Akriananta and Ketut Suastika
- IJCAET 237 SHIP PRINCIPAL DIMENSION OPTIMIZATION USING GOLOC METHOD Ilham Alkian, Ledi Anggara, Karnaji, Adi Prasetio, Rizka Zakiyatul
- IJCAET 238 DIGITAL INTEGRATED INSTRUMENT FOR MEASURING BMI AND COMPARING TO THE IDEAL BMI FOR AGE AS A GUIDANCE FOR INDONESIAN MILITARY REQRUITMENT

 Dwi Basuki Wibowo, Mahrizal Rosdiana, Wahyu Caesarendra and Mochammad Ariyanto

- IJCAET 239 DEVELOPMENT OF BACK-CALCULATION MODEL FOR AGGREGATE GRADATION DETERMINATION USING FRACTAL THEORY
 Bagus Hario Setiadji, Supriyono and Djoko Purwanto
- IJCAET 240 DEVELOPMENT OF RISK-BASED STANDARDIZED WBS (WORK BREAKDOWN STRUCTURE) OF HIGH RISE BUILDING FOR QUALITY PLANNING Mirradewi Rianty, Leni Sagita Riantini and Yusuf Latief
- IJCAET 242 PROJECTION MATRIX DESIGN FOR CO-SPARSE ANALYSIS MODEL BASED COMPRESSIVE SENSING Endra Oey, Dadang Gunawan and Dodi Sudiana
- IJCAET 243 THE INFLUENCE OF GUIDE VANE TO THE PERFORMANCE OF CROSS-FLOW WIND TURBINE ON WASTE ENERGY HARVESTING SYSTEM Budi Santoso and Dominicus Danardono Dwi Prija Tjahjana
- IJCAET 244 IMPROVEMENT OF MAGNETORHEOLOGICAL GREASES WITH SUPERPARAMAGNETIC NANOPARTICLES
 Ubaidillah Ubaidillah, Norzilawati Mohamad, Saiful Amri Mazlan and Seung-Bok Choi
- IJCAET 245 DEVELOPING A PROTOTYPE OF EARLY WARNING SYSTEM OF DELAY RISKS FOR PUBLIC PROJECTS (EWASDRIP)

 Jati Utomo Dwi Hatmoko, Hery Priyono, Mochamad Agung Wibowo and Riqi Radian Khasani
- IJCAET 251 ANALYSIS OF ANNUAL CHANGES OF PROJECT COST, CASE STUDY ON BUILDING PROJECT
 Toriq Ghuzdewan and Brigitta Narindri
- IJCAET 252 CRITICAL SUCCESS FACTORS IN DEVELOPING COLLABORATIVE DESIGN BUILD PROJECT TEAM TO IMPROVE PROJECT PERFORMANCE Ibrahim, Afrizal Nursin and Yusuf Latief
- IJCAET 254 ANALYSIS OF PIPING AT CENGKLIK EARTHFILL DAM, BOYOLALI REGENCY, CENTRAL JAVA PROVINCE, INDONESIA
 Najib Najib, Narulita Santi, Indriyani Ardyarini and Suprapto Dwiyanto Joko
- IJCAET 261 THE STUDY ON THE EFFECT OF WORKSTATION DESIGN PARAMETERS TO THE ERGONOMIC PERFORMANCES BY USING VIRTUAL MANUFACTURING TOOL Mohd Iqbal, Iskandar and Mohd Syafiq Mohd Soufi
- IJCAET 262 EFFECT OF POST CURING METHOD ON FLEXURAL STRENGTH OF COMPOSITE FRICTION BRAKE
 Herru Santosa Budiono, Eko Surojo, Nurul Muhayat and Wijang Wisnu Raharjo
- IJCAET 263 ADOMIAN DECOMPOSITION METHOD FOR SOLVING INITIAL VALUE PROBLEMS OF SECOND-ORDER ORDINARY DIFFERENTIAL EQUATIONS
 Sudi Mungkasi and I Made Wicaksana Ekaputra
- IJCAET 266 THE SPATIAL ANALYSIS TO CHOOSE A SUITABLE LOCATION FOR LANDFILL SITE Zaflis Zaim and Febby Asteriani
- IJCAET 267 BEHAVIOR OF GEOPOLYMER CONCRETE CONFINED BY CIRCULAR HOOPS

 Muslikh Muslikh, Nurti K Anggraini, Diwantoro Hardiito and Antonius Antonius
- IJCAET 269 INVESTIGATION ON THE ACOUSTIC PERFORMANCE OF NATURAL FIBERS FOR SOUND ABSORPTION APPLICATION
 Sabri Ahmad, Zahrul Fuadi and Dinni Agustina
- IJCAET 271 POROSITY CONTROL AND MECHANICAL PROPERTIES OF POROUS CERAMIC MATERIAL FROM PLERED REGION Sulistyo Solihin and Rizky Ardiansyah

- IJCAET 273 NUMERICAL APPROACHES IN IDEALISING ADDED MASS FOR SHIP VIBRATION ANALYSIS

 Jung Hoon Byeon, Hyun Jin Cho, Seung Jun Baek, Aditya Rio Prabowo, Dong Myung Bae and Jung Min Sohn
- IJCAET 275 SPATIAL STUDIES AND JURIDICAL UTILIZATION VACANT LAND AND ABANDONED LAND CONTROL IN EFFORTS OF REGIONAL AUTHORITY IN THE FIELD OF LAND AND FOOD RESILIENCE CITY SEMARANG Sawitri Subiyanto and Fauzi Janu Amarrohman
- IJCAET 276 INVESTIGATION OF MECHANICAL PROPERTIES OF AL7SI/SIC AND AL7SIMG/SIC COMPOSITES PRODUCED BY SEMI SOLID STIR CASTING TECHNIQUE Sulardjaka Sulardjaka, Sri Nugroho, Suyanto Suyanto and Deni Fajar Fitriyana
- IJCAET 278 MECHANICAL AND MICRO STRUCTURAL CHARACTERIZATION OF ST 37 BUTT JOINTS BY FRICTION STIR WELDING Kasir Kasir and Sulardjaka Sulardjaka
- IJCAET 280 A GREAT ACHIEVEMENT OF CALCULATED AND EXPERIMENTAL RESULTS OF THE CHAR KINETIC RATE IN WOODY MAHOGANY PYROLYSIS Widya Wijayanti and Mega Nur Sasongko
- IJCAET 281 THE PERFORMANCE OF PUMP AS TURBINE WITH MACHINED IMPELLERS Dede Lia Zariatin, Shanti Kumbarasari and Dwi Rahmalina
- IJCAET 284 STUDY OF NATURAL CONVECTION HOLLOW HYBRID FIN HEAT SINKS Severianus Sony G. R Putra, Nico Setiawan Effendi and Kyoung Joon Kim
- IJCAET 285 THE COMPARISON OF BOND STRENGTH BETWEEN NORMAL CONCRETE AND GEOPOLYMER CONCRETE

 Daniel Herdian Primadyas, Ilham Nurhuda, Nuroji and Muslikh
- IJCAET 287 CALCIUM SOAP PRODUCTION FROM PALM FATTY ACID DISTILLATE (PFAD) FOR RUMINANT FEED
 Lienda Aliwarga Handojo, Antonius Indarto, Dian Shofinita, Muhammad Reyhan Saadi, Maulana Gusti Al Hakim, Anggina Meitha, Rakhmawati Nabila and Harry Triharyogi
- IJCAET 290 MODAL ANALYSIS OF REPLICA BOSS HOLE DURING THE DEBURRING PROCESS IN AEROSPACE MANUFACTURING INDUSTRY
 Claudy Andriani, Wahyu Caesarendra, Tegoeh Tjahjowidodo, Bobby K Pappachan and Tomi Wijaya
- IJCAET 293 LIFE-CYCLE ASSESSMENT OF CRUDE PALM OIL PRODUCED AT MILL J, PT XYZ, SUMATERA ISLAND USING ECO-INDICATOR 99

 Pertiwi Andarani, Winardi Dwi Nugraha and Desinta Sawitri Giandadewi
- IJCAET 294 RECOVERY PRACTICE OF UNSORTED SOLID WASTE FROM LANDFILL TOWARDS ECONOMIC BENEFITS: SEMARANG CITY, INDONESIA

 Mochamad Arief Budihardjo, Indah Fajarini Sri Wahyuningrum, Purwono Purwono and Maulia Fatimah
- IJCAET 296 TEA LEAVES DRYING USING AIR DEHUMIDIFICATION PROCESS AND LIQUID DESICCANT REGENERATION ON A CLOSED-CYCLE DEHUMIDIFICATION-HUMIDIFICATION Eflita Yohana, Muhomad Endy Yulianto, Shofwan Bahar, Azza Alifa Muhammad and Novi Laura Indrayani
- IJCAET 298 CFD ANALYSIS ON THE AERODYNAMICS CHARACTERISTICS OF JAKARTA-BANDUNG HIGH SPEED TRAIN

 Tony Suryo Utomo, Hendry Nur Apriyanto and Berkah Fajar

- IJCAET 299 DEVELOPMENT OF INSTITUTIONAL FUNDING MODEL OF DEEP DISCOUNT BOND AND LAND LEASE ON A TOLL ROAD PROJECT Randika Dwirahman, Yusuf Latief and Ayomi Dita Rarasati
- IJCAET 306 PRELIMINARY STUDY OF PRODUCTION OF MAGNESIUM SALT OF FATTY ACID FOR FOOD, NUTRACEUTICAL, AND PHARMACEUTICALS INDUSTRIES FROM PALM FATTY ACID DISTILLATES (PFAD)
 Listianingrum, Reni Yuniarti, Rd. Habib Ripna Muhammad Tamim Al-Aziz, Defri Rizaldy, Muhamad Insanu, Ardiyan Harimawan and Dianika Lestari
- IJCAET 307 MULTI-STAKEHOLDER SWOT ANALYSIS ON INDONESIA HOUSING BACKLOGS Slamet Warsito, Jati Utomo Dwi Hatmoko and Rizal Z. Tamin
- IJCAET 308 DESIGN OF A LOW COST AUTONOMOUS FIXED WING UAV
 Mochammad Ariyanto, Joga D. Setiawan, Teguh Prabowo, Ismoyo Haryanto and M Munadi
- IJCAET 310 THE DETERMINANT FACTOR TO IMPLEMENTATION GREEN SUPPLY CHAIN MANAGEMENT IN CONSTRUCTION INDUSTRY: A LITERATURE REVIEW Mochamad Agung Wibowo, Naniek Utami Handayani, Anita Mustikasari, Asri Nurdiana and Moh Nur Sholeh
- IJCAET 311 COORDINATION AND COLLABORATION FUNCTIONS OF DISASTER MANAGEMENT CENTERS FOR HUMANITARIAN LOGISTICS: A CASE STUDY AT MERAPI ERUPTION

 Naniek Utami Handayani and Anita Mustikasari
- IJCAET 312 DESIGN STUDIES OF INNER AND OUTER ROTOR EMBEDDED PERMANENT MAGNET FOR HYBRID ELECTRIC VEHICLES

 Aravind Cv, Heng Jing Lei, Ramani Kannan and Joga Dharma Setiawan
- IJCAET 313 INFLUENCE OF HULL ENTRANCE ANGLE "PERINTIS 750 DWT", TOWARD SHIP RESISTANCE: CASE STUDY FOR DESIGN DEVELOPMENT "PERINTIS 750 DWT" Parlindungan Manik, Eko Sasmito Hadi and Muhammad Iqbal
- IJCAET 315 METHANE ENRICHMENT OF BIOGAS GENERATED FROM ANAEROBIC DIGESTER VIA CARBON DIOXIDE ADSORPTIONS USING COCONUT SHELL BASED ACTIVATED CARBON
 Cindy Priadi and Ridwan Hakim
- IJCAET 316 COMPONENTS OF INDONESIAN TRADITIONAL MARKET: DESIGN TOOLS FOR REVITALIZATION

 Ferry Hermawan, Himawan Indarto and Ismiyati Ismiyati
- IJCAET 317 ANALYSIS OF GROUNDWATER QUALITY SURROUNDING MUNICIPAL SOLID WASTE LANDFILL: BANYUURIP LANDFILL, MAGELANG, INDONESIA Mochamad Arief Budihardjo, Purwono Purwono and Annisa Selfia Nugraheni
- IJCAET 319 INDONESIAN HIGHWAY CAPACITY GUIDANCE (ICHG) CORRECTION FACTOR BASED ON COMPARISON BETWEEN ANALYTICAL RESULTS WITH EMPIRICAL DATA FOR SIGNALIZED INTERSECTION

 Amelia Kusuma Indriastuti, Eko Yuli Priyono and Yohannes Inigo Wicaksono
- IJCAET 320 DEVELOPMENT OF FORCE FEEDBACK IN STEER-BY-WIRE VEHICLES FOR DRIVING SIMULATOR

 Joga Dharma Setiawan, Masri B. Baharom and Muhammad Ammar Bin Abdul Wali
- IJCAET 324 FLAME STABILITY AND BEHAVIOR INSIDE MESO-SCALE COMBUSTOR WITH DIFFERENT FLAME HOLDER Lilis Yuliati
- IJCAET 325 PREDICTING CONTAMINANT (PB) MIGRATION THROUGH LANDFILL LINER Purwono Purwono, Mochamad Arief Budihardjo and Annisa Selfia Nugraheni

Design studies of inner and outer embedded Permanent Magnet for hybrid electric vehicles

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Abstract. Hybrid vehicles require high torque for propel, hence permanent Magnet machines are highly suiting for the improvement in the torque density. The paper focus on designing built-in interior permanent magnet (IPM) synchronous machine for hybrid electric drive. With the permanent magnet switched from rotor to stator and the characteristics over a wide range of speed operation is studied. The results obtained though performance analysis shows that at 130 rpm high torque with power peaking at around 900 rpm. Both the inner and outer machine are studied using numerical study tool for performance analysis for the application mentioned above. The inner magnet rotor design has provide a better magnetic flux flow due to the larger flux linkage between the permanent magnet and stator pole. Both type of machines are evaluated for torque where the machine with inner magnet provide a higher torque density of 4.94% as compared to the outer magnet machines.

1 Introduction

Unlike internal combustion engine (ICE) vehicles, the mechanical losses are converted into heat and dissipate to surrounding which does not practice the concept of energy efficiency [1-2]. Hybrid vehicles operate based on permanent magnet machine where magnetic flux linkage generated from the overlapping of magnetic field between permanent magnet and electromagnet [3]. The brushless permanent magnet DC machines have advantages over other machines such as simpler to maintain, more durable, and compact, less likely to suffer reduction in torque performance. The issues occurred where the fixed magnetic field in the stator could not increase the torque density due to difficulty in controlling the magnetic flux. [4-5]. A new type of design that includes two rotors one inside the machine and the other outer rotor enable applications in future wherein the operating mode is feasible in either simultaneous or independent operations using control techniques. A comparative design analysis using torque density value as evaluation parameter is presented to suiting to a hybrid electric vehicle.

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- IJCAET 326 ALUMINIUM CORNER JOIN USING FRICTION STIR WELDING Digrot Darmadi and Widia Setiawan
- IJCAET 327 THE OPTIMUM ACCELERATION AS A STRATEGY TO IMPROVE FUEL ECONOMY FOR SMART DRIVING
 Nazaruddin Sinaga, Bambang Yunianto and Tabah Priangkoso
- IJCAET 328 USABILITY EVALUATION OF ANTHROPOMORPHIC PROSTHETIC HAND BASED ON ISO 9241-11 CONCEPT

 Novie Susanto, Wiwik Budiawan and Ahmad Sahal Afhami
- IJCAET 329 ANALYSIS OF EFFECT OF BULBOUS BOW SHAPE TO SHIP RESISTANCE IN CATAMARAN BOAT

 Deddy Chrismianto, Kiryanto Kiryanto and Berlian Arswendo
- IJCAET 331 A COMPARATIVE ANALYSIS OF MENTAL WORKLOAD BETWEEN TRAIN AND BUS DRIVERS
 Hartomo Soewardi and Perdana Suteja Putra
- IJCAET 333 STRUCTURAL INVESTIGATION OF SHIP HULL SANDWICH PANEL DUE TO SHIP COLLISION
 Septia Hardy Sujiatanti, Achmad Zubaydi and Agung Budipriyanto
- IJCAET 337 IMPROVING PERFORMANCE MEASUREMENT EFFICIENCY IN PUBLIC SERVICE USING LEAN SIX SIGMA METHODOLOGY
 Purnawan Adi Wicaksono, Heru Prastawa, Nurana Maharani Putri and Ghabyanza Diah Pitaloka
- IJCAET 338 E-TRANSLATOR KAWI TO INDONESIA
 Oka Sudana, Darma Putra, Made Sudarma, Rukmi Sari Hartati and Ryan Pradnya Prastika
- IJCAET 353 LEAVES COMPOSTING PROCESS AND THE INFLUENCE OF RUMEN CONTENT AND BRAN ADDITION

 Mochamad Arief Budihardio, Purwono Purwono, Maulia Fatimah and Endro Sutrisno
- IJCAET 357 STRUCTURAL ANALYSIS FOR IN-SERVICE GAS PIPELINE LOWERING USING NUMERICAL METHOD

 Mochamad Safarudin and Joga Dharma Setiawan
- IJCAET 358 DESIGN AND SIMULATION OF FUZZY LOGIC BASED TEMPERATURE CONTROL FOR A MIXING PROCESS IN THERAPEUTIC POOL M Munadi, Mochammad Ariyanto and Norman Iskandar
- IJCAET 365 HOUSING NORMS AND WILLINGNESS TO MOVE TO LOW-COST RENTAL APARTMENT OF SLUMS DWELLER IN SEMARANG URBAN AREA Asnawi Manaf
- IJCAET 367 EXPERIMENTAL ASSIGNMENT OF BIOMASS GASIFICATION RATE AND TEMPERATURE DISTRIBUTION IN A DUAL CHAMBER CIRCULATING FLUIDIZED BED REACTOR.

 Imam Diunaedi, Sugiyatno, M. Affendi, Haifa Wahyu
- IJCAET 368 DESIGN ENGINEERING AND CHARACTERIZATION OF WATER ELECTROLYSIS-HYDROGEN WITH HIGH PRESSURE SEPARATOR NAFION Imam Djunaedi, Sugiyatno, M. Affendi, Haifa Wahyu
- IJCAET 370 DETERMINING COEFFICIENT OF LATERAL SOIL PRESSURE AT REST FOR FIBROUS PEAT SOIL

 I Gusti Ngurah Nyoman Wismantara and I Gusti Ngurah Putu Dharmayasa

International Symposium on Advanced Mechanical and Power Engineering (ISAMPE 2017) Submission Title

- **ISAMPE 8** HIGH-PERFORMANCE TERNARY SOLAR CELLS Changduk Yang
- ISAMPE 29 COMPARATIVE STUDY ON THE FRACTURE BEHAVIOR OF ALLOY 617 AT ROOM TEMPERATURE AND 950°C UNDER LOW CYCLE FATIGUE
 Youngbok Kim, Yong-Woon Choi, Kyu-II Han, Jung-In Yoon, Kwang-Hwan Choi, Chang-Hyo Son, Nguyen-Van Trong and Sung-Wi Koh
- ISAMPE 30 RESIDUAL VIBRATION AND HEAVING MOTION CONTROL STRATEGY FOR CRANE SYSTEM
 Youngbok Kim, Yong-Woon Choi, Kwang-Hwan Choi, Chang-Hyo Son, Jung-In Yoon and Le-Naght Binh
- ISAMPE 50 COMPARATIVE STUDY ON THE FRACTURE BEHAVIOR OF ALLOY 617 AT ROOM TEMPERATURE AND 950°C UNDER LOW CYCLE FATIGUE
 Park Jeong Hun, Rando Tungga Dewa, Kim Seon Jin, Kim Yeong Sik, Kim Woo Gon and Kim Eung Seon
- ISAMPE 51 LOW-CYCLE FATIGUE BEHAVIOUR OF NICKEL-BASE SUPERALLOY ALLOY 617 AT ELEVATED TEMPERATURES
 Rando Tungga Dewa, Kim Seon Jin, Kim Woo Gon, Kim Eung Seon, I. M. W. Ekaputra and Gunawan Dwi Haryadi
- ISAMPE 79 DESIGN OF MOUNT MODULE OF EMERGENCY ELECTRIC GENERATOR AT BASEMENT FLOOR
 Chan-Jung Kim, Inpil Kang, Jeong-Hyun Sohn and Byung-Tak Kim
- **ISAMPE 84** TRAJECTORY TRACKING AND BACKSTEPPING CONTROL FOR AUTOMATIC GUIDED VEHICLE(AGV)

 Dae Hwan Kim, Sang Bong Kim and Hyuk Yim
- ISAMPE 107 OPTIMAL PASSIVITY DESIGN OF A VIRTUAL COUPLING INCLUDING FIR-TYPE FRACTIONAL DERIVATIVES FOR A HAPTIC INTERFACE Masayuki Kawai, Takuya Yamagishi and Shouta Minami
- **ISAMPE 124** INTEGRAL CYCLE CONTROL OF RECTIFIER/REGULATOR OF WIRELESS CHARGING SYSTEM FOR ELECTRIC VEHICLE
 Joon Heo, Guho Jung, Seong-Jeub Jeon and Dong-Ho Cho
- ISAMPE 129 CENTROID SHIFTING TRACKING METHOD WITH SUPERPIXEL CONFIDENCE MAP Ki-Ryong Kwon
- ISAMPE 135 SURFACE TEXTURE INFLUENCES ON THE RUNNING-IN BEHAVIOR AND FRICTION REDUCTION
 Hou Zhouyong and Tomomi Honda
- ISAMPE 141 POWER ASSIST CONTROL IN STAIRCLIMBING MOTION USING SWINGING-LEG POSITION FOR A POWERED EXOSKELETON WITHOUT BINDING LEGS Shusaku Hayashi, Masayuki Kawai and Yasutake Takahashi
- ISAMPE 148 A STUDY ON BREAK-AWAY BOLT DESIGN FOR A MARINE SAFETY BREAK-AWAY COUPLING BASED ON ELASTIC STRESS ANALYSIS

 Baek Gyu Choi, Hee Hak Ahn, Jin Seok Jang, Byung Tak Kim and Inpil Kang
- **ISAMPE 191** NUMERICAL STUDY ON NATURAL COOLING OF STEEL BARS Yeou Myeong Choi, Yoon Hwan Choi, Hyun Wook Kwon and Yeon Won Lee

- ISAMPE 222 EFFECTS OF OVERLAP JOINT WELD GEOMETRY ON TENSILE SHEAR STRENGTH PERFORMANCE FOR ADVANCED HIGH STRENGTH STEEL Myungkoon Son, Seonjin Kim and Chiok Kim
- **ISAMPE 241** PERFORMANCE PREDICTION OF MAGNETORHEOLOGICAL VALVES UNDER VARIOUS TYPE OF FLUID AND FLUX PATHS
 Ubaidillah Ubaidillah, M Hafiz Idris, Saiful Amri Mazlan And Fitrian Imaduddin
- ISAMPE 265 FATIGUE TESTING AND EVALUATION OF FATIGUE STRENGTH UNDER MULTIAXIAL STRESS STATE; WHY DO WE NEED FATIGUE TESTING?

 Takamoto Itoh, Fumio Ogawa and Takahiro Morishita
- **ISAMPE 270** DEVELOPMENT OF TENSION-TORSION MULTIAXIAL CREEP TESTING APPARATUS FOR HEAT RESISTING STEEL Noritake Hiyoshi and Yoshihisa Iriyama
- ISAMPE 272 INFLUENCE OF SURFACE OXIDE FILM ONTO SPRAY COOLING HEAT TRANSFER WHILE BOILING ON STEEL PLATE
 Takahiro Ishizuka and Niro Nagai
- ISAMPE 274 PROPOSAL OF ECO AIR CONDITIONING SYSTEM BY WATER-COOLED HEAT PUMP AND SHALLOW GEOTHERMAL ENERGY EXCHANGE TECHNOLOGY Yuto Suganuma and Niro Nagai
- ISAMPE 277 PROPOSAL OF HORIZONTAL BUBBLE-ACTUATED HEAT PIPE(BACH)
 Ryuta Yamamoto and Niro Nagai
- ISAMPE 286 NUMERICAL STUDY OF THERMAL BEHAVIOR IN PHOSPHOR LAYER OF LIGHT EMITTING DIODE PACKAGES
 Gun Young Do, Dae Seong Woo, Byoung Guk Kim and Kyoung Joon Kim
- **ISAMPE 288** THERMAL ANALYSIS OF HEATER MODULE FOR ANNEALING PROCESS Daeseong Woo, Gunyoung Do, Byoungguk Kim and Kyoungjoon Kim
- ISAMPE 291 NUMERICAL STUDY ON SLOSHING IMPACT REDUCTION DUE TO AIR-TRAPPING MECHANISM
 Hyunjong Kim, Nanjundan Parthasarathy and Yeon-Won Lee
- ISAMPE 360 THE EFFECT OF STONE-WALES DEFECT ON THE STRUCTURAL STABILITY IN SINGLE-WALLED CARBON NANOTUBES
 Tomoya Taniguchi and Lei Xiao-Wen

Fatigue Testing and Evaluation of Fatigue Strength under Multiaxial Stress State; Why do we need fatigue testing?

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Abstract. Types of multiaxial fatigue tests and their experimental results are presented in this paper. There are typical three types in multiaxial fatigue tests: the combining push-pull and reversed torsion loading test using hollow cylinder specimen, the biaxial tension-compression test using cruciform specimen and the inner pressure applied the push-pull loading test using the hollow cylinder specimen. In the combining a push-pull loading and a reversed torsion loading test, failure life under nonproportional loading in which principal directions of stress and strain were changed in a cycle was shortened compared to proportional loading in which those are fixed. Fatigue lives were well-correlated using a nonproportional strain range considering the effect of strain path and material dependence. In the biaxial tension-compression test, the failure life decreased with increase of the principal strain ratio. In the inner pressure applied the push-pull loading test, cyclic deformation behaviour due to complex loading paths of multiaxial fatigue tests with the inner pressure associated with push-pull and rev. torsion acted to reduce the failure lives. Experimental investigation of multiaxial failure life and elucidation of their governing mechanism is essential and it can broaden the applicability of structural components.

1 Introduction

Investigation of fatigue properties is essential for design of structural components. In practical application, structures are subjected to complex multiaxial load. Therefore, the understanding of multiaxial fatigue properties of materials is important. Indeed, failure lives are overestimated when the effect of multiaxiality is neglected. Multiaxial fatigue testing usually has been carried out using a hollow cylinder specimen by applying push-pull loading and a reversed torsion loading and the applicability of multiaxial stress and strain parameters has been discussed [1-5]. However, a principal strain ratio (ϕ) and a principal stress ratio (λ) ranges performable by the testing method are $-1 \le \phi \le -v$ and $-1 \le \lambda \le 0$, where v is the Poisson's ratio. Structural components sometimes undergo fatigue damage at principal strain/stress ratios in excess of the above range under service loading. In

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