MRI for Non-invasive thermometry

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Introduction

Most of the magnetic resonance (MR) parameters that contribute to the signal intensity and phase exhibit temperature dependence. MRI has therefore been long attractive as a tool for non-invasive thermometry during thermal treatment of deep-seated organs. Real-time temperature mapping can ensure the thermal dose delivered is sufficient to cause damage to the target tissue volume only, and can provide feedback to adjust the thermal dose automatically. However, although the concept quickly matured into clinical use, the technique still suffers from problems that were identified early on [1,2], at least in-vivo.

The most extensively explored application of MR-thermometry today is the guidance of thermal therapies [3–26], where a series of temperature maps is acquired in close to real-time, to monitor the tissue being treated and its margins. The aim is less often to sensitize the tissue to radiotherapy or chemotherapy and more often to cause necrosis, typically by delivering but occasionally by abducting heat. Heat-based thermal treatments are separated into hyperthermia (involving temperature rises < 45 °C, over several minutes) or ablation (50-80 °C, over several seconds) depending on the temperature ranges and their time scales.

Approximately 40 medical centres worldwide routinely carry out MR-guided thermal treatments when surgical resection is not an option, or has been shown to be less effective [27]. Thermal energy is delivered via a high power laser source coupled to a fibre, usually inserted into the tissue in a minimally invasive way [14], delivered via a high intensity focused ultrasound (HIFU) system [7] or a hyperthermia unit [12], in a non-invasive way, or with an interstitial US [5], radio-frequency (RF) [28] or microwave probe [29], again minimally invasively. Laser and US sources are preferably used in conjunction with MRI.

The most commonly treated tissue is the liver; however with advances in equipment for delivery of thermal energy [5,7,11,14,28,30–32], accurate temperature monitoring, image reconstruction and automation [3,4,6,8,9,11–13,15–17,23–25,33-111], the possibilities are

expanding. Emerging applications include local drug-delivery [112–114], epilepsy treatment [9], quality control of red blood cells [115], iron mapping [116], diagnosis of multiple sclerosis [117], and brain abnormalities [118,119] and identification of iron-oxide labelled stem cells [120].

Many different commercial systems exist [5,9,12,14,15,33,34,121–123] and Figures 1-4 show examples from clinical practise using state-of-the-art technology. Figure 1 shows images from a minimally invasive MR-guided liver laser interstitial thermal therapy (LITT) carried out at St. Mary's Hospital, London, indicating a) the radiofrequency (RF) coil (8-element HD cardiac) used for MR-guidance, and b) an example case of a lesion exceeding 2 cm diameter which required two ablations.



Figure 1 Liver LITT carried out at St. Mary's Hospital, London, UK: a) patient in the MRsuite, b) axial slice MRI showing a partially ablated lesion (images by kind permission of Prof. W.M.W Gedroyc, St. Mary's Hospital).

Figure 2 shows a system for transurethral prostate ultrasound ablation (TULSA-PRO, Profound Medical). It includes proprietary software for monitoring and temperature feedback control of the heating pattern. It has been used to treat 30 patients in a Phase I study at the University Hospital of Heidelberg (Germany), Western University (Canada) and William Beaumont Hospital (US) [5]. Figure 3 shows a HIFU system recently trialled on ten patients in the University Hospital of Utrecht, Netherlands [7]. It consists of electronically steerable transducers and an integrated RF receiver.

Figure 4 shows the non-invasive hyperthermia system BSD-2000 3D MRI (Pyrexar Medical) used to treat various types of cancer (e.g. rectal, bladder, ovarian, soft tissue sarcoma, cervical and pancreatic). The hyperthermia unit is a phased array of dipoles with filters to minimize RF interference. MR-guidance is performed through the SigmaVision®Advanced

software (Dr. Sennewald Medizintechnik GmbH).

The aim here is to discuss the principles of operation of thermometry based on temperaturesensitive MR-parameters, to comment on the limitations and report on recent progress. Emphasis is placed on the potential of thin-film catheter-based RF coil technology to improve the MR-thermometry and the outcomes of MR-guided thermal treatments in general. We conclude with a general outlook for the field and comment on the possibility for future advances.



Figure 2 MR-guided ultrasound ablation of prostate cancer using the TULSA-PRO tenelement urethral device and a rectal cooling device. The feedback steps involved in the automated MR-guided procedure are illustrated (image by kind permission from Profound Medical Inc.)



Figure 3 a) Breast MR-HIFU system showing the transducer elements surrounding the breast cap and the integrated RF receive coil, b) corresponding MR image indicating the region where focal point can be formed (image by kind permission from [7]).



Figure 4 MRI hyperthermia suite in the Erasmus Medical Centre (Rotterdam, Netherlands) consisting of the control and MRI rooms equipped with the BSD-2000 hyperthermia system (Pyrexar Medical); Illustration of the treatment control through the SigmaVision®Advanced software (Dr. Sennewald Medizintechnik), (image by kind permission from Pyrexar Medical and Dr. Sennewald Medizintechnik).

Temperature-sensitive MR-parameters

MR-thermometry is made possible by the intrinsic sensitivity to absolute temperature T of MR-parameters such as the electron screening constant of the water proton $\sigma(T)$, the proton density $M_0(T)$, the longitudinal relaxation time $T_1(T)$, the transverse relaxation time $T_2(T)$, the diffusion coefficient D(T) and processes such as magnetization transfer.

 T_1 , T_2 , and M_0 are accessed through the magnitude of the MR signal while the electron screening constant of ¹H is accessed by high resolution spectroscopy or indirectly by monitoring temperature induced phase changes in images acquired with a gradient recalled echo (GRE) sequence. These methods provide a temperature measurement, relative to a baseline with the exception of the proton resonance frequency spectroscopic methods, which can in theory provide an absolute temperature [53,84,119,124,125].

Most of the work has focused on exploiting the thermal dependency of T_1 and σ and MRthermometry methods based on these are clinically accepted and routinely used. The extraction of temperature information through the magnitude signal initially gained popularity faster than proton resonance frequency methods, probably due to its simplicity. However, very soon, it was realized that the technique is not suitable for accurate quantitative measurements. Methods based on D, M_0 and T_2 have been significantly less popular. Here we focus on recent progress, while other excellent reviews can be found in [1,2,95,127].

T_1 , T_2 and proton density

The magnitude of the NMR signal is proportional to the nuclear magnetization M_0 but also depends on the relaxation times T_1 and T_2 in a fashion determined by the parameters of the acquisition method in use (the repetition time *TR*, the echo time *TE*, and the flip angle α). For a spin-echo pulse sequence, the magnitude of the signal *S* for $\alpha = \pi/2$ can be described as:

$$S(TE, TR, T) = M_0(T) \exp\left[-\frac{TE}{T_2(T)}\right] \left(1 - \exp\left[-\frac{TR}{T_1(T)}\right]\right)$$
(1)

The equilibrium of nuclei with spin 1/2 in a thermal bath and a magnetic field B_0 is governed by Boltzmann's distribution which predicts that the equilibrium nuclear magnetization M_0 is:

$$M_0 = \frac{N\gamma^2 h^2 I (I + 1) B_0}{3\mu_0 k_B T}$$
(2)

where N is the number of spins per unit volume, γ is the gyromagnetic ratio, h is Planck's constant, I is the spin quantum number, B_0 is the static magnetic field, k_B is Boltzmann's constant and μ_0 is the permeability of free space. M_0 can be written in terms of the susceptibility χ_0 , as $M_0 = \chi_0(T) B_0$, where χ_0 follows the well-known Curie Law:

$$\chi_o \propto 1/T \tag{3}$$

 M_0 has a small thermal coefficient of -0.3 %/°C between 37 and 80 °C [128]. The temperature dependence of T_1 was first observed by Bloembergen in 1948 [129]. It results from the changes in the dipolar interactions of macromolecules with temperature that follow the temperature–dependent changes in their translational and rotational motion. T_1 is expected to increase with temperature, and its temperature dependence can be described as:

$$T_1 \propto exp\left[-\frac{E_a(T_1)}{k_B T}\right] \tag{4}$$

where $E_a(T_1)$ is the activation energy of the relaxation process. Temperature-dependent transient changes in T_1 can be calculated for a small range of temperatures, relative to a reference value obtained at a baseline temperature T_b , as:

$$T_1\left\{T(t)\right\} = T_1(T_b) + b\left\{T(t) - T_b\right\}$$
(5)

Here *b* is the temperature coefficient dT_1/dT , which must be derived individually for the given subject and tissue-type undergoing thermal treatment.

The usual method of extracting T_1 is to ignore the smaller temperature-dependence of T_2 and acquire an image with a spin-echo or a GRE sequence with a short *TE* and a long *TR* for use as reference, and then follow this by obtaining an image with the same *TE* but a short *TR*. Equations (1) and (2) then imply that the signals from the two images are related by:

$$S / S_{ref} = \left(T / T_{ref}\right) \frac{1 - exp\left[-\frac{TR}{T_1(T)}\right]}{1 - exp\left[-\frac{TR}{T_1(T_{ref})}\right]}$$
(6)

Most often, however, the temperature dependence of T_1 is considered only qualitatively, via measurements of the difference of the signal magnitude in the nth image and that acquired at T_b [3,26]. The signal is expected to decrease with increasing temperature, because T_1 will increase and M_0 will decrease following (3). Considering the signal difference and neglecting the temperature-dependence of other parameters and the dynamic effects can lead to significant errors in-vivo. It has been shown [130] that if $M_0(T)$ is ignored, then dT_1/dT will deviate from the theoretically expected value of 1% /°C, leading to a serious error.

 T_2^* increases approximately linearly as tissue temperature decreases below 0 ^oC [79,131,132]. Consequently, temperature mapping based on T_2^* or the magnitude signal on T_2 -weighted images has been recognised mainly for its potential during cryoablations [79,133]. Tables 1 and 2 summarize the values of the thermal coefficients of T_1 and T_2 respectively that have been measured for various tissues in published calibration experiments.

	[ms/°C]	[%/°C]	Range [°C]	$B_0[T]$
Human breast tissue [55]	8	2	n/a	n/a
Cortical bovine bone [70]	0.67-0.84	n/a	25 - 70	3
Human brain [71]	17.4 (cortex), 3.4 (white matter)	n/a	4-37	3
Human breast tissue [74]*	5.35 (at 25°C) & 9.5 (at 65°C)	n/a	25-65	1.5
Porcine fatty acids CH ₂ /CH ₃ [81]**	10.7/30.3	1.69/3	20-60	11
Cortical bovine bone [134] ***	n/a	0.68-1.07	25-60	3
Bovine muscle [135]	n/a	1.4	10-40	1.5
Porcine liver [136]	n/a	1-2	10 - 50	1.5
Porcine fat [137]	3.9-7.7	n/a	30-70	1.5

Table 1. Temperature coefficient of T_1 for different tissue types.

* Reversible beyond 65°C, Temperature error 2-4 °C, Water suppression applied

** Reversible, No hysteresis

*** Estimation via signal change, Fatty marrow was removed and fat suppression omitted

Table 2. Tempe	rature coefficient	of T_2 for	different	tissue	types.
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	[ms/°C]	Range [°C]	$B_0[T]$
Cortical bovine bone [70]	0.67-0.84	25 - 70	3
Human brain [71]	Negligible	4-37	3
Human breast fat [74]	0.9	25-65	1.5
Porcine fatty acids CH ₂ /CH ₃ [81]	11/22.3	20 -60	11
Porcine fat [138] *	5.17	25-74	1.5
Porcine fat /bovine marrow [139]**	6.1 – 6.4 / 7	25 -70	3

* Temperature accuracy of 0.9 °C, reversible changes during cooling, Relatively slow (16 s) acquisition; without water suppression $dT_2/dT = 3.77 \text{ ms/}^{\circ}\text{C}$

**Irreversible changes beyond 45 °C, Hysteresis;

Without water suppression $dT_2/dT = 4.64 - 5.45 \text{ ms/}^{\circ}\text{C}$

Chemical shift of water proton

As the temperature of aqueous tissue changes, so do the nature and local number of hydrogen bonds. Variations in the hydrogen-bonding network affect the local magnetic field B_{loc} experienced by protons and changes thereof in turn proportionally shift their resonance frequency ω_L according to the Larmor equation:

$$\omega_L(T) = \gamma B_{loc} = \gamma B_0 (1 - \sigma(T))$$
⁽⁷⁾

Here B_{loc} is the local field the nucleus of the hydrogen atoms experience. The temperaturedependent electron screening constant $\sigma(T)$ is an indication of the shielding effect caused by the currents induced in the electron cloud. As temperature rises and the hydrogen bonds are disrupted, the shielding from the main magnetic field B_0 becomes more effective, leading to a decrease in the resonant frequency.

A change in the proton resonance frequency (PRF) therefore reflects temperature-induced changes in the chemistry of the microscopic environment of the H¹ nucleus. The electron screening constant is linearly related to temperature for the temperature range of interest for

thermal ablations (-15 °C to 100 °C) and is independent of tissue type (with the exception of fat, for which $d\sigma_F/dT \approx 0$) [140]. Typically, it follows:

$$\sigma(T) = aT \tag{8}$$

Hindman [141] first demonstrated temperature measurements based on the chemical shift of water. He observed a very small effect for pure water, of the order of -0.0108 ppm/°C. A list of in-vivo and ex-vivo tissue calibration studies is given in [142], indicating only a slight variation across different tissue types (between -0.007 and -0.01 ppm/°C). MR-thermometry based on the water PRF shift was initially investigated using spectroscopic techniques and regained attention in-vivo only after Ishihara et al. [143] proposed a simple method of obtaining temperature information by observing phase differences in the image data acquired with a GRE sequence. PRF MR-thermometry has therefore evolved into two techniques: phase mapping and spectroscopic imaging.

Based on the phase mapping approach, the temperature of water relative to a baseline temperature T_b can be determined using:

$$T - T_b = \frac{\varphi(T) - \varphi(T_b)}{\gamma a B_0 T E}$$
(9)

where $\phi(T)$ is the phase in the *n*th image during the thermal therapy, $\phi(T_b)$ is the phase in the baseline image acquired at the start and *TE* is the echo time of the GRE sequence. Spectroscopic imaging makes use of the temperature insensitivity of the electron screening constant of an internal reference peak such as a lipid or N-acetyl-aspartate (NAA), and could, in theory derive an absolute temperature based on a measurement of the frequency of the water resonance relative to the reference peak.

Based on (7), the PRF for water is $\omega_w(T) = \gamma B_0 \{1 - \sigma_w(T)\}$, while the PRF of the temperature insensitive reference compound is $\omega_R = \gamma B_0(1 - \sigma_R)$. The temperature-dependent chemical shift of water can therefore be determined as:

$$\delta_{W-R}(T) \left[ppm\right] = \left[\left\{\omega_w(T) - \omega_R\right\} / \omega_{RF}\right] x \ 10^6 = \left\{\sigma_R - \sigma_W(T)\right\} x \ 10^6 \tag{10}$$

where $\omega_{RF} \approx \gamma B_0$ is the Larmor frequency. The absolute temperature can then in principle be derived, as $T(t) = (\sigma_{W.R}/a) + c$, where a [ppm/°C] is the temperature coefficient and c [°C] is the temperature at which the chemical shift becomes zero.

Unfortunately (10) is not accurate in practice, because the tissue susceptibility $\chi(T)$ (which is also temperature-dependent) has been ignored. Including the susceptibility, the expression for the water PRF becomes $\omega_w(T) = \gamma B_0 \{1 - \sigma_w(T) + \chi_w(T)\}$ and that of the reference compound now becomes temperature dependent, as $\omega_R(T) = \gamma B_0 \{1 - \sigma_R + \chi_R(T)\}$. The impact of the susceptibility is often neglected although doing so can lead to temperature errors. This is discussed in detail in the following section.

Diffusion coefficient

The temperature-dependence of the diffusion coefficient was first demonstrated by Le Bihan [144] who showed a thermal sensitivity of 2.2 %/°C. The relationship between the diffusion coefficient and temperature can be expressed as:

$$D(T) = exp\left[-\frac{E_a(D)}{k_B T}\right]$$
(11)

Here $E_a(D)$ is the activation energy of the molecular diffusion of water and D is the diffusion coefficient $[mm^2/s]$ which is determined for an applied diffusion weighting b (s/mm²), as $\ln(S/S_0)/b$, where S and S_0 are the voxel signal intensities in diffusion-weighted and reference (b = 0) images respectively. The thermal coefficient for small variations of E_a is then:

$$dD / dT = \frac{DE_a}{k_B T^2}$$
(12)

A relative temperature difference can then be derived from two diffusion-weighted images, where one of them serves as a reference at the baseline temperature, as:

$$\Delta T = \left(\frac{k_B T_b^2}{E}\right) \frac{D - D_b}{D_b}$$
(13)

Limitations and recent progress

MR-thermometry has its limitations whichever of the parameters discussed above is used. The optimum choice typically depends on the particular application, which will determine the required speed of measurement, temperature accuracy and resolution. For thermal therapies, the organ being treated, the type of ablation (cryotherapy, LITT, or HIFU), the magnetic field strength, the hardware used (receiver coils), and the type of sequence all affect the performance with variations expected across different patients in the same type of tissue and treated at the same centre.

Limitations in methods based on the temperature-dependence of T_1 , T_2 and proton density

Magnitude signal changes are caused by the combined effects of the temperature dependence of T_1 , T_2 and M_0 and the dynamic alterations in the physiological response of tissue to heat (which affect all of these parameters) [74]. These effects cannot be easily decoupled. As the temperature starts to change, the body responds by increasing perfusion. Blood has a different density of MR-visible protons, different relaxation times and different susceptibilities as it degrades in an un-predictable way into its by-products [71,116]. The body also responds to stress by oedema which again affects the visible protons and their time constants [130,145].

The level and state of the water in the tissue also varies widely and the situation is even more complex in tissue that contains fat. A changing balance between aqueous and lipid components affects both the proton density and T_1 [81], and this will be a problem even in non-fatty tissue since the disruption of tissue itself may give rise to non-aqueous components. In addition to the observed change being a multicomponent effect, there is a strong dependence on tissue-type as shown in Table 1, a limited linearity range and hysteresis, although reversible T_1 thermal coefficients have also been reported.

Even if the effects of the physiological response of tissue to thermal treatment (protein denaturation, swelling, oedema, and blood degradation) can be modelled, it is unlikely that this would serve any practical purpose, given the complex microenvironment and inhomogeneity of most tumours. These issues render the T_1 method mainly suitable as a qualitative tool in-vivo [3,26], although doubt has been cast over its effectiveness even in this context in a recent study [26]. On the other hand, provided calibration is accurate, the limited linearity of dT_1/dT provides an opportunity to confirm cell death quantitatively [77].

Recently interest has also revived in the use of MR-thermometry for monitoring cryoablations [24,136] and the temperature of adipose tissue [37,55,74,81,137]. When T_1 is used to monitor ablations of fatty tissue such as breast, water must be suppressed [138] or water and fat signals separated [55,77] for improved accuracy. The need to separate the methylene and methyl protons of fatty acids was also highlighted in [81]. When using the temperature coefficient of T_1 of CH₂ only, in tissue with a mixed content, an error of up to 3.3 °C could arise due to the signal containing 18 % CH₃.

The variable flip angle method for T_1 mapping has been shown to produce good results invivo using a hybrid T_1 /PRF thermometry approach [55,137]. However, simultaneously satisfying the need for fast scanning times and precision in both PRF and T_1 measurements is not trivial. In [55], a multi-echo sequence was used to improve the precision of both PRF and T_1 methods by a factor of 3. Hybrid PRF/ T_1 approaches, where T_1 is indirectly measured through the magnitude signal change have also been explored [134].

Methods based on M_0 have been less popular [128], mainly due to the very small thermal coefficient, which implies that a high signal-to-noise ratio (SNR) is required. In addition, long TRs are required to eliminate changes in T_1 , making it altogether less suitable for real-time measurements. Although T_2/T_2^* - based thermometry has not been popular, it has been recognised for its potential during cryoablations [79,133] to confirm necrosis [3,78] and monitor heating of fatty tissue [74,76,80,81,138] (see Table 2).

Limitations in methods based on the chemical shift of water proton

PRF MR-thermometry is generally the method of choice for organs with sufficient water content, because the temperature range of linearity is a good match to the ablation temperature range. In addition, tissue–type independence mitigates the need for calibrations prior to every treatment. Most commonly, it is used in baseline subtraction mode, where a phase image acquired before heating is subtracted from an image during heating.

Differential measurement makes the method sensitive to all non-temperature related effects that alter the local magnetic field between scans. These include a) drift in the static field [146], b) patient motion [16,63,147], c) local or global changes in magnetic susceptibility

(e.g. due to tissue swelling [148], fat [46,161] air [149], movement of interstitial applicators [43] or injection of contrast agent [150]), which can be altered by heating itself [49]. For example, although the screening constant of fat is not temperature-dependent, its susceptibility is, and so is the susceptibility of every other tissue, thus introducing weak tissue-type dependence.

Static magnetic field drifts are mainly problematic in lengthy thermal therapies. To avoid these, standard schemes include subtraction of phase changes in a non-heated region of interest (ROI) [3] or in specific phantoms whose PRF is temperature independent. These can be intrinsic, such as subcutaneous fat/lipids [39,63,98,151] or external, mainly in ex-vivo studies. The intrinsic approach becomes less effective when water and fat components are not homogeneously distributed [41] and when field disturbances are large [96,151].

Fat-referenced phase mapping PRF thermometry offers high spatio-temporal resolution, unlike spectroscopic methods. With spectroscopic PRF, the water protons and the reference moieties in the observation region will in principle be affected by the same susceptibility changes and field drifts at a given time, and therefore these will cancel out. However, large voxels are typically used to obtain sufficient SNR, compromising the spatial resolution and increasing the chances of magnetic field inhomogeneity in the same voxel [96,152].

Intra-voxel temperature gradients will also cause errors due to the temperature-dependence of the susceptibility. High SNR is critical to obtaining accurate results in tissue that contains only a small amount of fat such as liver (where fat is only 3% of water content [151]). Additionally, high SNR could alleviate signal averaging, which will in turn improve the temperature resolution; we will return to this point later.

With phase mapping PRF thermometry, the sensitivity to motion is particularly significant. Motion between scans leads to errors due to misalignment of the images acquired during ablation from the baseline. Similarly, intrascan motion leads to errors due to spatial inhomogeneities and shape-induced body susceptibility changes, for example in, respiration. Although breathing is the main source of motion, the physiological response of tissue to heating can also lead to changes in shape (e.g. swelling, peristalsis, tension). Breath hold is not possible during thermal treatments lasting several minutes. Tracking navigator echoes and synchronization of the image acquisition to the breathing cycle using respiratory belts can be effective in minimizing errors due to mis-registration [26,50,62,68]. However, these measures cannot help with irregular movement. Multi-baseline approaches are even more effective [16]. A number of baseline images are acquired, forming a library and the baseline image that scores the highest correlation factor with the nth image acquired during ablation is then selected from the library for subtraction [60,69].

Further improvements are offered by reference-less methods [126,153], whereby a background phase is derived from the n^{th} image during ablation. This is achieved by fitting a polynomial to the surrounding unheated region and extrapolating to the heated region, thus avoiding subtraction with a separate image [21,154]. This approach is only successful if sufficient SNR is available, and if water-fat interfaces which can lead to inaccurate polynomial fitting are absent. To avoid the latter, fat can be suppressed or water-selective sequences can be used [16,60,69].

Spectroscopic PRF MR-thermometry is inherently reference-less in the sense that the temperature is not derived relative to an initial temperature at t = 0, but instead to an internal reference peak at every time point. In the brain, the proton resonances from a low concentration of brain metabolites (NAA, choline and creatine) are typically used [93,95,118,119,152,155,156]. The methylene lipid resonance in breast [157] or liver and the citrate proton signal in the prostate have also been suggested as internal temperature reference signals [158], although the latter has not been followed up since.

Single-voxel spectroscopy and spectroscopic imaging methods have been employed in-vivo but SNR and scan time become issues [95,157]. As a result, these techniques have not yet proved clinically viable although they perform well in phantom or in-vivo studies [118,134,158]. Accurate calibration in-vivo is also challenging [96,156,157]. High sensitivity is required to detect small internal concentrations of the reference metabolite signals (of the order of 10 mM [95, 158]) and which is still insufficient even when large voxels are used.

Moreover, it is difficult to measure the resonance frequencies of the water and reference peaks accurately enough [99,119,133]. Sufficient attenuation of the water peak is essential to

render the measurement possible without saturating the receive electronics [1,95] and this can lead to errors in accurately estimating the resonance of water. It will also inevitably lead to attenuation of the already weak reference signals resulting in poor measurements [99], especially when the SNR is low. Other issues include the impact of pH and protein content [105,159,160] and the inhomogeneity of fat and water content [96,157].

Although fat can be used to correct for effects that are unrelated to temperature, its presence is a significant problem too. Dynamic changes in the fat content during treatment will lead to temperature errors when the phase mapping approach is used. The chemical shift of fat relative to water is 3.5 ppm. Changes of that order due to changes in the fat content are larger than those induced by the small thermal coefficient of -0.01 ppm/°C [46]. Consequently, effects of this nature will mask the changes of phase due to temperature.

Despite the electron screening constant of fat not being temperature dependent, its susceptibility is [161], again introducing temperature errors even when suppression techniques are employed [41]. Fat suppression should be used for accurate results when the tissue mostly contains water [48]. PRF methods cannot be used to measure the temperature of predominantly fatty tissue such the breast, in which case a hybrid thermometry method is more suitable [55,98]. Finally, thermally induced changes in conductivity will also cause the phase shift to scale inaccurately with TE, especially when temperature measurements are performed over a large volume and over a long time [162].

Limitations in methods based on the diffusion coefficient

Since Le Bihan [144] first demonstrated diffusion-based MR-thermometry there has been limited investigation of this parameter [163]. Interest has recently revived for assessment of brain temperature [164-167] or diagnosis of multiple sclerosis [117] and some of the proposed schemes based on D(T) are now clinically used. Problems include anisotropy, long acquisition time, sensitivity to motion and tissue-type dependence. Non-temperature related dynamic effects that may alter the molecular diffusion are also an issue, explaining the lack of popularity for thermal therapies as an application area.

General limitations: SNR and spatio-temporal resolution

The standard deviation of temperature (TSD) is proportional to 1/SNR. High SNR is required for accurate real-time MR-thermometry, precise calibration of small MR-thermal coefficients, and quantification and exclusion of non-temperature related effects (which are very hard to detect and interpret otherwise). It enables faster sequences that minimize motion artefacts and provides sufficient resolution to monitor vital structures near the ablation site, permitting procedures that are currently excluded by existing protocols [27].

High spatial and temporal resolution is a problem common to all in-vivo MR-thermometry techniques where averaging is often not an option. Temporal resolution is particularly important in fast moving organs ablated with HIFU sources, which induce rapid heating. Motion introduces artefacts (e.g. blurring and ghosting) that result in deterioration of the image quality independently of the method used for thermometry.

Interstitial micro-coils have received considerable attention from the MRI and spectroscopy communities due to the local SNR gain they offer compared to surface array coils [168]. However, little attention has been paid to their use in MR-thermometry [28,30,169,170]. This can be attributed partly to incompatibility with non-invasive thermal therapies and partly to the lack of cost-effective, scalable and reproducible receivers. Recently a micro-coil receiver with these characteristics was shown to provide an excellent solution to improved MR-thermometry during minimally invasive LITT ablations and its clinical utility was confirmed on studies at 3T on liver-mimicking gel and ex-vivo porcine liver specimens [169].

The receiver consists of a copper-clad Kapton thin film (25 μ m Kapton® HN, DuPont High Performance Films), patterned to form a two-turn spiral inductor with a pair of integrated capacitors C_T and C_M for tuning and matching. Figure 5 shows the thermal delivery system (a Somatex Laser Applicator) integrated with an MR-imaging device based on the thin-film micro-coil (OD of the modified applicator is 4.8 mm). Figure 6 shows the arrangement used to assess its performance for PRF MR-thermometry based on phase-mapping, and compare it with that of the cardiac array coil used at St. Mary's Hospital [169].



Figure 5 Somatex laser applicator integrated with a micro-coil for operation at 3T.



Figure 6 a) Ablation phantom used for phase mapping PRF MR-thermometry studies and b) arrangement for cardiac coil MR-guided LITT in the 3T scanner at St. Mary's Hospital, London.

A Nd:YAG laser (MY 30, Marting Medizin-Technik, Tuttlingen, Germany) with a wavelength of 1064 nm and 25 W output power was used during ablations. The internal circulation cooling system of the applicator was maintained by a continuous flow of 0.9 % NaCl at a rate of 60 ml/min. The laser light was delivered through a 12 m long fibre with a 400 μ m diameter core and a 20 mm diffuser active tip (Surgical Laser Technology).

Fibre optic sensors based on fluorescence lifetime (Type 790, Luxtron, Santa Clara, CA, USA), with accuracy \pm 0.1 °C, were used to provide references against the MR-inferred temperatures at $d = 5 \text{ mm} (L_1)$ and $d = 10 \text{ mm} (L_2)$ relative to the probe in each monitored slice during the ablation. The two axial slices containing the reference thermometers were monitored (2D GRE thermometry sequence with TR = 7.976 ms, TE = 3.872 ms, $FA = 20^\circ$, temporal resolution = 6 s, voxel size = 0.47 mm x 0.47 mm x 10 mm, FOV = 120 mm x 120 mm, pixel BW = 244.141 Hz/pixel).

Figures 7a and 7b show micro-coil axial baseline thermometry images containing the fluorooptic sensor L_1 at d = 5 mm. Both the micro-coil magnitude and phase images are of good quality, free from artefacts and the fluoro-optic sensor can be clearly seen. Symmetrical patterns of voids near the micro-coil conductors affect the image. Their origin is imperfect decoupling and they occur with all coils and all decoupling schemes, but are generally not noticed because of their short range. Although they can be minimized, they will always be obvious when a local coil is completely immersed in a signal source. The sensitivity is nonuniform and the micro-coil is only able to image a small field-of-view (FOV).



Figure 7 Micro-coil baseline images, showing the sensor L_1 : a) magnitude and b) phase.

Figure 8 is a Bald-Altman plot which indicates the degree of correlation with L_1 in each case, in the 2x2 ROI below the thermometer shown in Figure 7b. The advantage of the micro-coil is obvious. The array coil data are significantly noisier. The thermal coefficient *a* was determined as -0.01 ± 0.009 ppm/°C from the linear fit of micro-coil phase differences plotted against the temperature differences recorded with L_1 . The maximum temperature error is equal to 6 °C for the micro-coil while the corresponding value for the array coil is 20 °C.



Figure 8 Bald-Altman plots of temperature errors (the difference between the MR-inferred and the fluoro-optic temperatures) derived from the micro-coil and array coil at L_1 .

Although non-heated ROIs were used to correct for field drifts, slight deviations from the fluoro-optic temperatures remain. This effect could be attributed to changes in susceptibility or electrical conductivity of the gel with temperature [162]. For example, thermal expansion, or changes in the susceptibility of air bubbles in the ablation phantom might have affected the measurements [100]. The importance of correcting for field drifts is highlighted in Figure 9, which compares micro-coil MR-inferred and fluoro-optic temperatures (without correction for field drifts). Errors clearly become significant at temperatures above 40°C.



Figure 9 Micro-coil MR-derived temperatures (without correction for field drift) versus fluoro-optic temperature readings.

The choice of the non-heated ROI plays a significant role on how effective the correction becomes. The ROI must be uniform and of good SNR, otherwise noise is introduced into the measurement. The small FOV and non-uniform sensitivity of the micro-coil makes this challenging since the non-heated ROI will normally lie at a distance where the sensitivity is significantly reduced.

Figures 10a and 10b show SNR maps of the two coils. The SNR of the array coil is almost constant, but only equal to only 23. In contrast, the SNR of the micro-coil is locally high but falls off as $1/r^2$. At 5 mm radius, it is 10 times higher and remains 1.5 times higher up to a 15 mm distance. Figure 10c compares the radial variation of the TSD of the two coils. The TSD is a measure of the noise in the temperature measurement and it is inversely proportional to the SNR:

$$TSD = \frac{0.66}{SNR.\alpha.\gamma.TE.B_o}$$
(14)

The TSD of the micro-coil remains < 0.75 °C up to a radius of 20 mm (and < 3 °C up to 30 mm). Despite its small FOV and non-uniform sensitivity, the micro-coil can provide 10 times less noisy temperature measurements at the margins of small lesions, an impressive result. Even for larger lesions, the TSD will be 1.5 times lower at the margins. The two receivers perform comparably at a radius of 20 mm.



Figure 10 SNR maps of the axial thermometry slice corresponding to L_1 : a) micro-coil, b) array coil, c) radial variation of TSD [°C].

Figure 11 compares the maximum temperature error of the two coils during respiratory-gated MR-thermometry of an unheated liver-mimicking phantom, using a motion simulator to simulate movement due to breathing [169]. The data shows the errors due to local susceptibility variations. The micro-coil has a much smaller deviation from the baseline temperature of 20 °C. This result implies that faster sequences can be used with the micro-coil while still achieving a useful SNR.



Figure 11 Comparison of the mean temperature error due to motion during respiratory-gated PRF MR-thermometry, obtained using the micro-coil and array coil. The baseline temperature is 20 °C.

The following example is based on a MR-guided LITT of ex-vivo porcine liver containing only a small amount of fat. It confirms that the excellent sensitivity of the micro-coil allows accurate calibration of the thermal coefficients. Water/fat separation was used, with a two-point Dixon sequence inserted into to the gradient-echo thermometry sequence (slice thickness = 5 mm, slice spacing = 2.5 mm, TR = 6.068 ms, TE = 2.1 ms, FOV = 200 mm x 160 mm, pixel BW = 1302.11 Hz/pixel, temporal resolution = 10 s), and temperatures were derived through changes of the signal intensity.

Two 80 mm x 120 mm and 20 mm thick liver slices were placed inside a 700 ml container with the probe horizontally in between. Two fluoro-optic sensors L_1 and L_2 were immersed in the same plane between the liver slices, at 90⁰ to the probe and at distances of 5 mm and 10 mm from the probe respectively. Eight axial slices were monitored, two of which contained reference thermometers. The in-phase and out-of-phase images were reconstructed using in-built scanner software (3T GE Signa Excite).

Figures 12a-c show axial micro-coil magnitude baseline thermometry slices: a) in-phase image, b) out-of-phase image and c) fat image. The in-phase and out-of-phase images are very similar confirming the expected small amount of fat present in the liver. Figure 12d is the water-only baseline image indicating the 2x2 ROI next to the reference thermometer L_1 used for calibration. Figure 12e shows the fat content, which was found as a percentage from the ratio between the pixel-by-pixel signal intensity in the in-phase image and the pixel-bypixel signal intensity in the sum of the in-phase and out-of-phase images.

The white regions correspond to pixels with a small amount of fat, which can only be detected due to the high sensitivity of the micro-coil. Figure 12f, shows the fat content at the 4th minute of the ablation; this shows that more pixels now appear to contain a small amount of fat, which could be an indication of the release of lipid components (phospholipids) as tissue denatures.

Figure 13a shows the calibration curves in the out-of-phase, water and in-phase images. The slopes of the fitted curves represent the thermal coefficients (β) which have values equal to - 0.93 %/°C, -1 %/°C and -1.16 %/°C for the out-of-phase, water and in-phase images respectively. The small difference in the values of the thermal coefficients confirms the

presence of only a small amount of fat, and indicates that the micro-coil can differentiate between effects occurring in voxels with a small amount of fat present.



Figure 12 Micro-coil magnitude axial thermometry slices (baseline) corresponding to L_1 : a) in-phase image, b) out-of-phase image, c) fat image, d) water image showing the 2x2 pixel ROI next to L_1 , e) % fat content image (baseline) and f) % fat content image (at the 4th minute).

The values are very similar to those quoted in other calibration studies [37,97,171]. Deviations from linearity appear at 60 $^{\circ}$ C and hysteresis is observed during cooling, as others have observed [77]. Figure 13b shows the normalized calibration curves, from the same ROI for the water and fat images. The normalized difference in signal intensity drops with temperature as -1.2 %/ $^{\circ}$ C in the fat images. The linearity of the fat calibration curve breaks down at approximately 50 $^{\circ}$ C, probably due to permanent tissue damage [77].

Figure 14 shows MR-inferred temperatures, based on a) in-phase images with $\beta = -14.2 \text{ °C}^{-1}$, b) out-of-phase images with $\beta = -11.85 \text{ °C}^{-1}$. The laser was operated for 4.8 min, causing a rapid temperature rise to 80 °C. Large deviations from the reference thermometers appear in temperatures derived from the in-phase images compared to those from the out-of-phase images. These observations could indeed indicate some interesting MR-physics as the tissue denatures, which the micro-coil can detect due to its excellent sensitivity.

Figure 15a shows a colour map of the MR-derived temperatures at t = 4 min, based on the out-of-phase images, with $\beta = -11.85$ °C⁻¹. Figure 15b shows a photograph of the corresponding lesion at the end of the ablation, indicating the expected shape and symmetry. Additional opto-thermal characterization of the modified ablation catheter has also been carried out [172], confirming that absorption in the Kapton substrate will not compromise tissue necrosis due to exposure to different temperatures or pose a safety risk due to overheating.



Figure 13 Calibration of the thermal coefficient for micro-coil MR-thermometry based on subtraction of magnitude images: a) out-of-phase, water and in-phase images and b) water and fat images (normalized).



Figure 14 Comparison of temperatures recorded by Luxtron sensors with temperatures derived based on micro-coil MR-thermometry from a) in-phase images with $\beta = -14.2 \text{ °C}^{-1}$, b) out-of-phase images with $\beta = -11.85 \text{ °C}^{-1}$.



Figure 15 a) Colourmap of the temperature distribution at t = 4 min for the slice containing L_1 based on the out-of-phase images, with β = -11.85 °C⁻¹ and b) photograph of lesion at the end of ablation.

Summary and outlook

MR-thermometry is a mature technique, with confirmed clinical utility despite a set of known residual problems. MR-guided thermal ablations are already or will soon be routinely carried out for the treatment of lesions or other pathologies in the brain, breast, prostate, heart, uterus (for uterine fibroids), liver, and other abdominal organs. To a large extent motion-related errors have been dealt with and preventive or corrective schemes are applied in the clinic. Susceptibility correction algorithms keep emerging and more is understood about the errors

caused by fat in tissues (or alternatively how fat can be used to correct for non-temperature related effects).

Significant progress has been made in monitoring tissue that contains fat more accurately by exploiting T_1/T_2 based thermometry, often in combination with PRF-based thermometry. T_1 and T_2 based temperature monitoring during cryoablation or to confirm tissue necrosis also appears promising. However, the proposed techniques have not yet been clinically adopted. Progress has also been made in temperature monitoring of thermal therapies for bone metastases.

Temperature monitoring of the brain has progressively gained clinical acceptance as a diagnostic tool, and spectroscopy- and diffusion-based thermometry have both received attention. In general the possibility of accurate absolute MR-temperature monitoring could prove to be a useful diagnostic tool or a new pathology biomarker. For example, it could help distinguish small variations in temperature due to abnormal tissue metabolism and this possibility is currently being explored.

The potential of spectroscopic approaches to monitor absolute temperature has not yet been fully met, since they are mainly precluded from clinical use due to poor spatio-temporal resolution. A more recent technique [85] based on water saturation shift referencing could be attractive for fatty tissue. It offers high spatio-temporal resolution and provided field inhomogeneities are small it allows for an unbiased assessment of water PRF in the presence of lipid protons, without the need for a priori knowledge of the fat composition and additional data processing steps.

Although the results from this study at high magnetic field strengths (9T and 11 T) are promising, a translation to clinical scanners (1.5T or 3T) may not be as exciting due to lower sensitivity. If this hurdle can be overcome, 3D volumetric temperature mapping with accuracy better than 0.2 °C could be achieved. Another promising approach to absolute thermometry, even in tissue that does not contain temperature-insensitive reference components involves temperature sensitive contrast agents [114]. An important application area is targeted thermally-activated drug delivery which requires accurate temperature monitoring to avoid damage of the surrounding healthy tissue.

A common discussion point is that increased SNR would improve accuracy and spatiotemporal resolution and allow precise calibration. However, researchers use high magnetic field strengths, employ averaging and optimize pulse sequences to increase the SNR. The alternative approach of using internal receivers is being explored by a handful of groups. Disposable internal coils, easily adaptable to existing applicators [169], are suitable for use in minimally invasive thermal therapies and could offer higher SNR, improve calibration accuracy and lead to a better understanding of the impact of biophysical tissue changes on temperature-sensitive MR-parameters.

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