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Neeson, Thomas M. and Moody, Allison T. and O'Hanley, J.R. and Diebel, Matthew and Doran, Patrick and Ferris, Michael and Colling, Timothy and McIntyre, Peter (2018) Aging infrastructure creates opportunities for cost-efficient restoration of aquatic ecosystem connectivity. Ecological Applications . ISSN 1051-0761.

DOI

https://doi.org/10.1002/eap.1750

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1	Running head	: Aging	infrastructure and	conservation
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3 Aging infrastructure creates opportunities for cost-efficient restoration of

- 4 aquatic ecosystem connectivity
- 5

7 Doran^e, Michael C. Ferris^f, Timothy Colling^g, Peter B. McIntyre^b

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- ⁹ ^aGeography & Environmental Sustainability, University of Oklahoma, Norman OK
- ¹⁰ ^bCenter for Limnology, University of Wisconsin, Madison WI
- 11 ^cKent Business School, University of Kent, Canterbury, Kent, UK
- ¹² ^dWisconsin Department of Natural Resources, Madison, WI
- 13 ^eThe Nature Conservancy, Lansing, MI
- 14 ^fComputer Sciences, University of Wisconsin, Madison WI
- ^gDepartment of Civil and Environmental Engineering, Michigan Technological University,
- 16 Houghton, MI
- 17
- ¹To whom correspondence should be addressed: Phone: 1-608-338-2235; Email: neeson@ou.edu
- 19 Keywords: Freshwater, conservation, infrastructure, connectivity, prioritization

21 Abstract

22 A hallmark of industrialization is the construction of dams for water management and roads for transportation, leading to fragmentation of aquatic ecosystems. Many nations are striving to 23 address both maintenance backlogs and mitigation of environmental impacts as their 24 25 infrastructure ages. Here, we test whether accounting for road repair needs could offer opportunities to boost conservation efficiency by piggybacking connectivity restoration projects 26 on infrastructure maintenance. Using optimization models to align fish passage restoration sites 27 with likely road repair priorities, we find potential increases in conservation return-on-28 29 investment ranging from 17% to 25%. Importantly, these gains occur without compromising infrastructure or conservation priorities; simply communicating openly about objectives and 30 candidate sites enables greater accomplishment at current funding levels. Society embraces both 31 reliable roads and thriving fisheries, so overcoming this coordination challenge should be 32 33 feasible. Given deferred maintenance crises for many types of infrastructure, there could be 34 widespread opportunities to enhance the cost-effectiveness of conservation investments by coordinating with infrastructure renewal efforts. 35

36

Keywords: Infrastructure, connectivity, fragmentation, conservation, restoration, coordination,collaboration

39 Introduction

40 Roads and dams blanket industrialized landscapes around the world. Such infrastructure has a host of local and long-distance effects on the natural environment, including contributing to 41 extensive fragmentation of terrestrial and freshwater ecosystems (Saunders et al. 1991, 42 43 Trombulak and Frissell 2000, Doyle and Havlick 2009). While infrastructure is essential for the 44 functioning of modern economies, there is growing societal commitment to minimizing and mitigating its environmental impacts. Here, we explore how planned infrastructure maintenance 45 could provide opportunities to increase the cost-effectiveness of conservation investments in 46 restoring the connectivity of aquatic ecosystems. 47 The life cycle of infrastructure offers three stages of opportunities to mitigate 48 49 environmental impacts by adhering to recognized best practices: during site selection and initial planning, design and construction; during routine operations and maintenance; and during 50 decommissioning, when economic and safety concerns typically have primacy (Doyle and 51 52 Havlick 2009). The prevalence of each type of opportunity varies geographically. In developing nations, most infrastructure spending supports new construction, hence conservation 53 opportunities will be associated with designing projects to minimize their impacts (Dulac 2013; 54 Laurance et al. 2014; Mandle et al. 2016). In industrialized nations of North America, Europe 55 56 and Australasia, however, nearly all infrastructure spending supports the maintenance and occasional decommissioning of existing structures (Doyle et al. 2008; Doyle and Havlick 2009). 57 This pattern is likely to hold for the foreseeable future, such that opportunities to align 58 59 conservation and infrastructure objectives will arise largely in the context of addressing 60 maintenance backlogs and strategic decommissioning. For example, more than \$2 trillion of repair costs are anticipated for U.S. infrastructure given its current condition (ASCE 2017), and 61

the US Forest Service has identified almost 300,000 km of roads that may be decommissioned in
the next 40 years (Ihara et al. 2003). The massive, ongoing investments required to sustain
acceptable infrastructure dwarfs budgets for conserving the environment and natural resources
(Lederman and Waches 2016), potentially creating widespread incentives for conservation
groups to collaborate with infrastructure agencies. From the conservation perspective, a
promising strategy is to identify high-return efforts that leverage already-funded infrastructure
maintenance and decommissioning projects (White 2014).

To explore the efficiencies that could be achieved through collaborative approaches, we 69 focus on the conservation challenge of restoring aquatic ecosystem connectivity by enhancing 70 71 the passability of dams and road crossings to riverine animals. River fragmentation is a global 72 problem due to the thousands of large dams that act as absolute barriers in river networks worldwide (Grill et al. 2015). While dams are often a focus of high-profile decommissioning 73 74 efforts, road crossings are many times more numerous (Januchowski-Hartley et al. 2013) and 75 their aggregate contribution to fragmentation is substantial (Jackson 2003; Neeson et al. 2015; McKay et al. 2016). Mitigation of the ecological impacts of road crossings typically occurs by 76 replacing impassable culverts with fish-friendly designs (Cenderelli et al. 2011). Though larger 77 culverts have greater initial costs, their greater diameter reduces failure rates and maintenance 78 79 costs associated with debris removal (Gillespie et al. 2014). As a result, the higher installation 80 costs of larger culverts may be offset over the lifespan of the structure, yielding societal and economic benefits. Thus, transportation agencies are increasingly amenable to up-sizing or 81 82 otherwise adjusting culvert designs to maximize the resilience of road infrastructure to greater peak streamflow arising from the changing climate, and to enhance aquatic organism passage 83 (Schall et al. 2012). As these agencies confront a growing backlog of maintenance demands, they 84

may welcome partnerships that broaden support for climate-appropriate and nature-friendly
designs of transportation infrastructure.

A piggybacking approach for restoring aquatic connectivity might entail a conservation 87 organization paying for a fish-friendly design upgrade at a site where a transportation agency 88 89 was already planning to remove and replace an aging culvert. In this example, the conservation 90 group would bear only a fraction of the cost of the full project, because the infrastructure agency had already budgeted for the base costs of labor and materials for culvert replacement and road 91 resurfacing to fulfill its own mission. Though piggybacking strategies have the potential to offer 92 93 high conservation benefit at little cost, efficient pursuit of this approach at a large scale requires 94 systematic information on the costs and benefits of thousands of potential projects that can be 95 analyzed using sophisticated planning tools. A challenging step in this process is maintaining dialogue and data exchange between conservation organizations and infrastructure agencies so 96 97 that each understands the other's priorities and capacities.

98 Here, we use spatial data on road surface condition in the US state of Michigan to evaluate the potential benefits for conservation practitioners of piggybacking their fish passage 99 100 investments on road maintenance projects. First, we use an optimization model to calculate the return-on-investment (ROI), measured in terms of the river length reconnected per dollar spent, 101 102 that could be achieved by a conservation organization paying the full cost of high-priority culvert replacements. We then use road surface condition data as a proxy for future investment by 103 infrastructure agencies in road maintenance projects, and calculate site-specific reductions in 104 costs to implement fish-friendly culverts when conservation investments take advantage of these 105 106 leveraging opportunities. By comparing the ROIs from the full cost and piggybacking models,

we calculate the savings that would be possible by aligning conservation investments withupcoming infrastructure maintenance.

109

110 Methods

To predict future road maintenance, we obtained road surface condition data for 781,407 road segments (totaling 2.33×10^5 km of road length) for the years 2004 to 2013 from the Michigan Department of Transportation (MDOT). Road surface condition is scored using the Pavement Surface Evaluation and Rating system (PASER), a categorical system in which roads receive scores from 10 (perfect condition) to 1 (very poor). In general, roads ratings \geq 8 require no maintenance, ratings of 5 - 7 would benefit from preventative maintenance, while ratings \leq 4 require structural improvement, resurfacing or complete reconstruction (Fig. 1).

The MDOT PASER data is the most comprehensive spatial information on road 118 conditions for Michigan, yet only a portion of the road network is surveyed in any given year. To 119 estimate the 2013 rating of segments that were last surveyed in an earlier year, we created a state 120 transition model describing road degradation rates (Appendix A). While the state does maintain a 121 PASER data set for the federal aid, paved road network (approximately 1/3 of the entire public 122 123 road mileage), information on the remaining 2/3 of the Michigan public road network is managed by individual counties and municipalities. These data are not fully complete at a state 124 125 level, so we assumed that, on average, these roads would be in similar condition to those in the 126 state database. Thus, we assigned ratings to these crossings by randomly sampling from the distribution of scores in the state PASER database. Repeating the randomized scoring process 30 127

times indicates that our ROI results are robust to that uncertainty; the coefficient of variation inhabitat gains was just 4.62%.

We estimated the costs that a conservation group would pay for a culvert upgrade project 130 under two different cost-sharing strategies (Fig. 1). First, we assumed that any road crossing with 131 132 a PASER score of 4 or lower would be repayed by the road agency in the near future, including paying the full cost to replace culverts using a hydraulic design adequate to handle flows with a 133 50-year recurrence interval (MDOT 2009). Conservation organizations could then elect to pay 134 for the cost difference to upgrade from the hydraulic design to a culvert with state-of-the-art 135 136 features for aquatic organism passage (AOP) to achieve maximal fish passage. For roads with a 137 PASER score of 5 or higher, MDOT is assumed to be unlikely to sponsor any road work in the 138 near future. Thus, conservation organizations would bear the full cost of the culvert replacement, including all excavation and resurfacing costs, if such projects were pursued. Hereafter, we refer 139 140 to this as the "top-up" cost-sharing strategy, in reference to the idea that conservation groups could elect to top-up infrastructure spending on low-condition culverts to ensure full fish 141 passage. 142

Our second cost-sharing strategy is a "discounting" model under which the road agency would be willing to make a partial contribution toward the replacement costs for any culvert, given the benefits of having an upgraded culvert. Specifically, we assumed that the road agency's fractional contribution to total costs would be inversely proportional to the current PASER score: (10 – Score) / 10. The discounting strategy would allow conservation organizations to realize some savings when selecting culverts of high connectivity value even when the overlying pavement is in good condition, but would require greater coordination and

negotiation with the road agency because the final portfolio would reflect conservation prioritiesalone.

For both the top-up and discounting cost-sharing strategies, we estimated the full cost of 152 culvert replacement under a hydraulic design using an updated version of the model in Neeson et 153 154 al. (2015). The model accounts for costs related to stream size, road width, and surface type. We then explored three different methods for estimating the costs of AOP culvert designs. In the first 155 method, AOP cost is treated as a linear function of the cost a hydraulic design, specifically a 156 21% surcharge (hereafter, the "linear" cost model). The 21% surcharge estimate represents the 157 average increase in project costs across studies of completed culvert projects (Levine 2013). In 158 159 the second method, we assumed that the AOP design would entail installing a structure that could pass a bankfull flow (hereafter, "BFW" cost model), and based cost on empirical estimates 160 of replacement components, including culvert structure, fill, road replacement, and labor. Cost 161 162 components were derived from the Michigan Department of Transportation's 2015 schedule of pay items (https://mdotjboss.state.mi.us/BidLetting/BidLettingHome.htm). The width of each 163 structure is equal to the estimated bankfull width of the stream based on a drainage area 164 regression (Wilkerson et al. 2014). Structure types were determined by road type and stream 165 166 bankfull width; interstate, highway, and urban roads use concrete structures, rural roads use metal structures, and all crossings use the lowest cost structure that meets material and size 167 requirements. Because the BFW cost model often entailed switching to a different class of 168 169 structure (e.g., changing from a steel culvert to a concrete arch), AOP costs under the BFW 170 model were on average 221% of hydraulic costs. In the third method, termed a "compromise" 171 model, we used recent MDOT pay items to estimate the cost of maximizing culvert diameter (up to bankfull through-flow) within the same class of structure. On average, AOP costs under the 172

compromise model were estimated as 139% of hydraulic costs. Our exploration of three distinct
cost models (linear, BFW, and compromise) reflects our inability to determine a priori which
culvert design would be adequate for restoring full passability.

176 To quantify the cost savings that might be achieved by a conservation organization that 177 aligns its investments with road maintenance priorities, we used an optimization framework to 178 compare return-on-investment for fish passage projects under the two cost-sharing strategies (top-up, and discounting) and calculated these cost savings for each of the three estimates of 179 AOP project costs (linear, BFW, and compromise AOP cost models). We focused on the 180 181 Saginaw River watershed, the largest watershed in Michigan and one that is fragmented by 4,918 182 road crossings and 153 dams. The average PASER scores for this watershed (5.024) are very 183 close to the average for all of Michigan (5.01; t-test p > 0.05); thus, the proportion of road culvert projects with opportunities for cost-sharing in the Saginaw River basin is broadly 184 185 representative of opportunities across the state.

186 We evaluated ROI for each of two distinct restoration targets: connectivity for streamresident fishes versus connectivity for lake-migrant fishes. To address the first case, we 187 188 developed an optimization model that selects a portfolio of projects to maximize a common 189 index of within-watershed connectivity (dendritic connectivity index, DCI; see Appendix B). To 190 address the second case, we employed the optimization model from Neeson et al. (2015) that selects a portfolio of projects to maximize the total length of stream miles that are accessible to 191 192 fishes migrating from the Great Lakes toward headwater breeding habitats. In general, the 193 second target directs focus to barriers low in a watershed, while the first emphasizes expansion 194 of fully-connected habitat anywhere in the watershed. For both optimization models, we estimated the current passability of each road culvert following Januchowski-Hartley et al. 195

(2014), and assumed that installation of an AOP-design culvert would restore full passability.
For both optimization models, we explored increases in stream connectivity that could be
achieved under budgets ranging from \$5M to \$30M. These budget levels are on par with recent
investments in stream connectivity in the region (Moody et al. 2017).

While our estimates of barrier cost, passability and upstream river length are based on the best available spatial data sets, these estimates have not been validated with on-the-ground surveys. Accordingly, we performed a sensitivity analysis to quantify the degree to which model outputs might depend on uncertainty in the underlying data. Overall, we found that the benefits of cost-sharing were relatively insensitive to variation in estimates of barrier cost, passability, and upstream river length (see Appendix C for details).

206

207 **Results**

State-wide, road surface condition on Federal aid eligible roads in Michigan declined
dramatically from 2004 to 2013 (Fig. 2A), highlighting a growing maintenance backlog. In 2004,
for example, only 10.5% of road segments had a PASER rating of 4 or lower; by 2013, this
number had risen to 36%, meaning that 1 out of 3 road segments was in need of significant
reconstruction work in the coming years. These poor condition road crossings are equally
prevalent from headwaters to river outlets, indicating restoration opportunities throughout river
networks (Fig. 2B).

Aligning priorities for aquatic connectivity restoration with impending infrastructure maintenance can dramatically increase conservation return-on-investment. In the Saginaw River basin, this effect is greatest in the case of restoring connectivity for stream-resident fishes (Fig.

218 3A). An optimal investment of \$30M prioritized without regard to cost-sharing opportunities, for 219 example, would result in a 1321% increase in the DCI score for resident fishes. Investing the same \$30M using a piggybacking approach under the linear AOP cost model, however, would 220 221 result in a 1652% increase (under the top-up cost-sharing strategy) or 1541% increase (under the discounting cost-sharing strategy) in DCI (Fig. 3B). Therefore, ROI can be enhanced by 222 piggybacking by up to 25% (i.e., increased from 1321% gain to 1652% gain) compared to the 223 traditional funding model in which conservation organizations pay the full cost of their priority 224 projects. 225

The ROI gains from piggybacking depend strongly on the method used to estimate costs of culvert materials to ensure aquatic organism passage. The BFW cost model offered only marginal improvements to ROI from piggybacking, in contrast to the linear cost model (Fig. 3B). The compromise cost model offered moderate improvements in cost-efficiency to achieve AOP.

Selecting fish passage projects based on future road maintenance alters the number, but 230 231 not watershed position, of projects prioritized to enhance connectivity for stream-resident fishes. Most of the 4.918 road crossings in the Saginaw River occur on small 1st and 2nd order streams, 232 while relatively few occur on the Saginaw mainstem $(5^{th} - 7^{th} \text{ order})$ (Fig. 3C). When 233 conservation organizations pay the full cost of culvert replacements (no cost-sharing), the 234 235 optimal investment of \$30 M involves 1,091 road crossings and 42 dams (1,133 projects in total; Fig. 3D). Under a top-up cost-sharing strategy, however, the optimal investment of \$30 M 236 includes many more projects: 1,936 road crossings and 45 dams (1,981 projects in total; Fig. 237 3C). Under a discounting cost model, the optimal investment of \$30 M comprises 1,600 road 238 239 crossings and 45 dams. Under all three selection scenarios, priority projects are disproportionately located on 2nd order reaches (Fig. 3C-3D). 240

241 When optimizing for Great Lakes migratory fishes, the benefits of cost-sharing were 242 smaller than for stream-resident fishes, yet still considerable. With a budget of \$30M, for example, a top-up cost-sharing strategy offered up to 14% gain in ROI for migratory fishes (Fig. 243 244 4A), less than the 25% gain for stream-resident fishes (Fig. 3A). Though project selection for migratory fishes is necessarily more constrained because downstream barriers must be removed 245 first, optimal project portfolios for both stream-resident and migratory fishes contained roughly 246 similar proportions of road crossings and dams (Fig. 4B). Thus, while increasing habitat access 247 for Great Lakes migratory fishes requires the removal of dams low in the watershed, the decrease 248 249 in benefits of cost-sharing for migratory fishes in this watershed was not due to greater spending on dams overall. 250

Although optimal project selection under cost-sharing scenarios generally favors 251 replacement of road crossings that already require urgent maintenance, some projects are so 252 253 beneficial that conservation organizations should consider bearing the full cost. To maximize 254 DCI under a top-up cost model, for example, the optimal investment of \$30M includes 1,323 road crossings in poor condition, but also 613 road crossings in moderate to good condition. 255 256 These 613 projects are high-cost, high-reward projects that merit consideration despite lack of cost-sharing opportunities. Optimal project selection for migratory fishes is similarly diverse. For 257 an investment of \$30M under the top-up model, the best portfolio includes 1,430 road crossings 258 259 in poor condition, 756 full-cost road crossings (moderate to good condition), and 45 dams.

260

261 **Discussion**

262 We find that aligning restoration investments with infrastructure maintenance can increase 263 return-on-investment for conservation purposes by up to 25%. Given the maintenance backlog in Michigan (Fig. 2) and throughout the US (ASCE 2017), there should be abundant opportunities 264 to implement similar strategies in the coming years. Furthermore, piggybacking strategies could 265 be coupled with strategic decommissioning of dams (Doyle et al. 2003; Stanley and Doyle 2003; 266 267 Fitzpatrick and Neeson 2018), thereby leveraging societal responses to the problem of aging infrastructure in ways that enhance access of migratory fishes to river networks that are currently 268 highly fragmented. 269

270 It is striking that opportunities to leverage infrastructure maintenance to boost 271 conservation ROI are much greater for stream-resident fishes than for migratory species in our 272 case study. This is due to differences in the role of the river network structure in constraining project selection. For migratory fishes, little habitat gain is possible without first removing 273 274 expensive dams that occur low in the watershed (Kemp and O'Hanley 2010, McLaughlin et al. 275 2013). As a consequence, Great Lakes migratory fishes fail to benefit from most of the low-cost piggybacking opportunities for culvert replacement because expensive downstream dams remain 276 277 in place, thereby constraining overall ROI. In contrast, for stream-resident fishes, optimal project 278 selection is less constrained by any one barrier, enabling conservation organizations to take advantage of a wider range of piggybacking opportunities throughout the watershed. This 279 280 disparity would be amplified when analyzing multiple watersheds because the terminal dam challenge is ubiquitous, but enlarging the set of potential road crossings that would increase in-281 282 stream connectivity raises the odds of identifying high-return project sites.

Average PASER scores for the Saginaw River watershed are nearly identical to the
Michigan-wide average, suggesting that the conservation efficiencies demonstrated here can be

285 replicated throughout the state. Presumably, the opportunities for conservation piggybacking scale directly with the proportion of road segments that have poor pavement condition, such that 286 transportation agencies are amenable to cost-sharing. Our models also depend on several key 287 assumptions that we could not verify: that roads with and without PASER data are comparable in 288 condition and repair costs, and that road resurfacing in response to a low PASER score is always 289 290 accompanied by culvert replacement (typically, the design life of culverts is longer than that of pavements). In general, roads without PASER data are in worse condition than the Federal aid 291 eligible roads analyzed here (MTAMC 2010); thus, the potential for conservation efficiencies in 292 293 the full road network should be even greater. Furthermore, part of the cost-efficiencies demonstrated here would apply even if cost-sharing was limited to conservation organizations 294 295 paying the entire cost of culvert replacement to match pavement resurfacing by transportation agencies. 296

297 Our analysis also omits other key factors that influence the conservation value of a particular barrier removal: the presence of natural barriers to fish movement, the potential for 298 facilitating invasive species (McLaughlin et al. 2013, Neeson et al. 2016; Milt et al. in press) and 299 300 pathogens (Hurst et al. 2012), or impacts to the social and cultural ecosystem services associated with impoundments (Fox et al. 2016, Magilligan et al. 2017). Furthermore, conservation 301 objectives and priority species vary widely among decision-makers across the region (Allan et al. 302 2013, Pearsall et al. 2013, Neeson et al. in press). While consideration of these factors is 303 essential for evaluating individual barrier removal projects, our sensitivity analysis (Appendix C) 304 305 suggests that the benefits of cost-sharing overall will be robust to changes in the costs and benefits of particular barrier removals. 306

307 Though our analysis focused on the benefits of cost-sharing for conservation outcomes, AOP culvert designs could provide long-term savings to transportation agencies as well. Though 308 AOP culverts have higher upfront cost, their greater diameter enables them to pass water and 309 310 debris associated with larger floods, reducing failure rates and maintenance needs (Gillespie et al. 2014, O'Shaughnessy et al. 2016). Thus, the installation costs may ultimately be fully offset 311 312 over the lifespan of the structure. However, the greater upfront costs of AOP culverts are often prohibitive for transportation agencies in a restricted budget climate (O'Shaughnessy et al. 313 2016). The cost-sharing strategies outlined here offer a rationale for conservation organizations 314 315 to contribute to these upfront costs, providing benefits to both natural resource management 316 (increased ecosystem connectivity) and transportation (greater flood resilience and lower longterm costs) interests. Importantly, these parallel benefits occur without sacrificing infrastructure 317 maintenance priorities or demanding additional conservation funds, thereby representing a true 318 win-win scenario. 319

320 Our work offers a model for large-scale coordination of conservation and infrastructure investments. There is growing recognition of the potential role of such joint efforts, and some 321 322 piggybacking of project costs already occurs opportunistically (White 2014). For example, state transportation agencies are typically required by law to vet construction plans with state wildlife 323 agencies (Public Law 109-59 2005). Thus, key relationships may already be in place, but 324 325 piecemeal, opportunistic collaborations are much less efficient than coordinated portfolios of projects for ecological restoration (Neeson et al. 2015). Knowledge-sharing between 326 327 conservation and infrastructure organizations also may be challenging due to differences in 328 culture, data management protocols, jurisdictional boundaries, and perceived interests. In the case of aquatic connectivity, spatial data on road surface and culvert condition is often managed 329

at the county or municipality level, whereas dam assessments are typically performed by state or
federal agencies. The increasing availability of sophisticated optimization approaches in both
conservation and infrastructure sectors may provide a platform for data integration and strategic
planning to align priorities to mutual benefit (Moody et al. 2017). Indeed, in some states,
legislation already mandates consideration of aquatic organism passage during construction or
repair of road culverts (Levine 2013; Gillespie et al. 2014).

Successful implementation of cost-sharing strategies over the long term (i.e., 10 to 30+ 336 years) will require coordination of multiple rounds of investment by conservation and 337 338 infrastructure groups. In the short term (i.e., within several years), scheduling is less critical. Our 339 analysis focuses on identifying restoration opportunities that may exist in a particular year 340 (2015), but it should be possible to spread conservation investments over several years. For example, investing \$10M per year over three years would yield the same conservation benefits as 341 342 a single lump-sum investment of \$30M. The one caveat is that investments in any one year must be large enough to afford any project within the portfolio; otherwise, annual budgets constrain 343 project selection and it may not be possible to afford certain high-cost, high-reward projects 344 (Neeson et al. 2015). In the Saginaw River this is not likely to be an important constraint, 345 because more than 99% of barrier removal projects cost less than \$500k. Ultimately, successful 346 long-term implementation of the cost-sharing strategies in our paper will require at least annual 347 348 updating of shared databases to identify cases where further deterioration of roads has created new cost-sharing opportunities, or where the completion of construction projects has eliminated 349 350 some cost-sharing opportunities.

A key remaining hurdle involves spatial road and culvert condition data: in many states,
 collection of information on road surface and culvert condition on the local road system is the

prerogative of the county and municipality that owns the road. In many cases the agency may not collect this type of data. Furthermore, in states outside of Michigan, it is uncommon for road and culvert condition data to be collected on both the state and local systems using a uniform rating system. The lack of data and the non-uniformity of data that is collected greatly adds to the complexity of this planning. Furthermore, the differences among the three methods for estimating AOP structure costs and their consequent influence on ROI indicate that more work is needed to better understand the relative costs of various designs.

In the context of expanding rather than repairing infrastructure, habitat conservation plans 360 (HCPs; Lederman and Wachs 2014) offer another example of the benefits of jointly considering 361 362 transportation needs and ecosystem outcomes. HCPs arose as a cost-effective means of 363 complying with Endangered Species Act (ESA) mandates by preemptively seeking input from environmental management agencies. For large infrastructure projects, such dialogue early in the 364 365 planning process may create opportunities for effective action as well as financial leveraging. The funding streams associated with transportation and other infrastructure investments dwarf 366 those earmarked for environmental management (Lederman and Wachs 2016), creating an 367 incentive for genuine engagement by conservation organizations. 368

Infrastructure is integral to modern societies yet also creates pervasive environmental stress in ecosystems worldwide, calling for innovative approaches to maintaining its benefits and mitigating its impacts. Given the looming need for large-scale infrastructure investments in much of the developed world, cost-sharing strategies offer an appealing means for advancing both conservation and transportation interests. Our study highlights the potential benefits from both perspectives, and underscores the opportunities for cost-effective restoration that could arise from increased data-sharing and collaboration during infrastructure project planning.

377 Acknowledgements

378 We thank B. Curtis and L. Reed, MDOT Bridge Section, for assistance with cost calculations. Funding was provided by the Upper Midwest and Great Lakes Landscape 379 Conservation Cooperative, The Nature Conservancy's Great Lakes Project, the University of 380 381 Wisconsin, the Great Lakes Fishery Trust, the University of Michigan Water Center, and the Department of Interior Northeast Climate Science Center. The project described in this 382 publication was supported in part by Grant or Cooperative Agreement No. G12AC00001 from 383 the United States Geological Survey. Its contents are solely the responsibility of the authors and 384 do not necessarily represent the views of the Northeast Climate Science Center or the USGS. 385 386 This manuscript is submitted for publication with the understanding that the United States Government is authorized to reproduce and distribute reprints for Governmental purposes. 387

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515 Figure legends

516 Figure 1: Illustration of cost-sharing strategies for road culvert replacements based on road surface condition scores of 8 (top panel), 5 (middle) and 2 (bottom panel). The horizontal red 517 line shows the cost of a hydraulic designed culvert project, which is on average 83% of the cost 518 519 of an Aquatic Organism Passage (AOP) designed culvert project. When no cost-sharing occurs, 520 the conservation group pays the full cost of an AOP designed culvert project regardless of road condition. In the top-up strategy, a transportation agency contributes the full cost of a hydraulic 521 design culvert for roads with a score of 4 or lower; the conservation group pays additional costs 522 523 to upgrade to an AOP design (bottom panel). The conservation group pays the full cost of an 524 AOP design project for roads with a score of 5 or higher. In a discounting strategy, the road 525 agency contribution is inversely proportional to road surface condition, but would never exceed the cost of a hydraulic-design culvert. 526

527

Figure 2: (A) Histogram of PASER scores across Michigan for 2004 (based on 164,506
surveyed road segments) and 2013 (121,624 surveyed road segments). In 2004, 10.5% of
surveyed road segments received a score of 4 or lower; in 2013, that number rose to 36%. (B)
Distribution of road crossings (both bridges and road culverts) across Strahler stream orders for
all road crossings in Michigan, and for those with road surface condition 4 or lower.

533

Figure 3: (A) Return-on-investment curves for three cost-sharing strategies in the resident fish
(DCI) optimization model. (B) The percentage increase in ROI that could be achieved for a
budget of \$30 M for all combinations for two cost-sharing strategies and three AOP culvert cost
models (Linear, Compromise, BFW). (C) The distribution of all road crossings, and selected

projects under each cost-sharing strategy, across Strahler stream order for a budget of \$30 M. (D)
The number of projects in an optimal portfolio with a \$30 M budget for each of the three costsharing strategies. In panels A, C and D, AOP culvert costs are calculated using the Linear cost
model.

542

Figure 4: (A) Percentage increase in return-on-investment resulting from top-up cost-sharing for
the resident fish (DCI) and Great Lakes migratory fish optimization models. (B) The proportion
of optimal project portfolios represented by road culvert (RSX) projects when following a top-up
cost-sharing strategy for the resident fish (DCI) and Great Lakes migratory fish optimization
models.







Figure 3





559 Appendix A: State transition model of road decay over time

560 To estimate the 2013 PASER ratings of road segments that were last surveyed in an earlier year, we created a series of state transition matrices to describe how roads degrade over time. Changes 561 562 in the PASER rating of a road segment over time are due to either further degradation of the road surface (decrease in PASER score) or resurfacing or repair (increase in PASER score). Of the 563 564 781,407 road segments in our data base, 725,728 segments were assessed at least twice during the years 2004 to 2013. We used these longitudinal observations of road surface condition to 565 566 create a series of transition matrices (or Markov matrices) and calculate the expected condition of each road segment in 2013. 567

568 Changes in pavement condition over time generally follow a sigmoid or logistic curve 569 (WDOT 2002). As a result, the expected pavement condition for a road segment last measured 570 before 2013 depends on both the interval of time since it was last assessed, and the pavement 571 condition at that assessment. Accordingly, we created a separate transition matrix for each 572 interval of n years between assessments.

To estimate the PASER ratings of road segments last surveyed in year2013 – n, we first identified all road segments that were assessed at an interval of n years. We then used these longitudinal observations to create a transition matrix P, where the element P_{ij} describes the probability that a road segment with PASER score i would transition to score j after an interval of n years. We then calculated the mean value of each row of this matrix and took this value to be the expected 2013 condition of a road segment that was assessed to have condition i in year2013 – n.

Appendix B: Formulation of a Model to Optimize River Connectivity for Stream-Resident Fish

The model that we propose for optimizing river infrastructure investments for stream-resident fish is based on the Dendritic Connectivity Index (DCI_P) proposed by Cote et al. (2009). DCI_P provides a river network scale measure of habitat connectivity and is evaluated by taking a weighted average of the probability that fish can successfully travel between any two sections of a river. More formally, it is defined as:

$$DCI_{P} = \frac{1}{V^{2}} \sum_{i \in S} \sum_{j \in S} v_{i} v_{j} \varphi_{ij}$$
(A1)

where *S* is the set of stream sections, indexed by *i* and *j*, φ_{ij} denotes the cumulative passability between stream sections *i* and *j*, v_i and v_j specify the size of stream sections *i* and *j* (normally measured in terms of length), and $V = \sum_i v_i$ gives the total size of the river network. Letting B_{ij} , indexed by *k*, represent the set of barriers lying between river sections *i* and *j*, cumulative passability is calculated simply as:

$$\varphi_{ij} = \prod_{k \in B_{ij}} p_k \tag{A2}$$

where p_k denotes the "bidirectional" passability of barrier k, which is taken as the product of barrier k's upstream and downstream passabilities p_k^{up} and p_k^{dwn} (i.e., $p_k = p_k^{up} \times p_k^{dwn}$). Barrier passability represents the fraction of fish (in the range 0 to 1) that are able to successfully negotiate a barrier in the upstream or downstream directions. To formulate an optimization model that maximizes DCI_P for one or more fish species across one or more watersheds, we first introduce the concept of a river "subnetwork." A river subnetwork corresponds to the area upstream of a barrier up to the next set of barriers or the river terminus. Assuming a river network is strictly dendritic (i.e., never diverges in the downstream direction), a subnetwork can be uniquely identified by its most downstream barrier, thereby making a barrier and a subnetwork entirely interchangeable terms. Figure A1 shows an example involving 6 barriers/subnetworks.

To continue, we let *J* denote the set of barriers within the river network, indexed by *j* and *k*. For each barrier *j*, the immediate downstream barrier is given by d_j , while U_j and F_j represent the set of barriers immediately upstream from *j* and the set of barriers that are directly confluent with *j*, respectively. An illustration of how d_j , U_j , and F_j are determined for a specific barrier is shown in Figure A1.

The set of fish species, guilds or taxa of restoration concern (a.k.a. "targets") is denoted by *T* and indexed by *t*. Associated with each target *t* is a weight $w_t \ge 0$ that specifies the importance of improving connectivity for *t*. With this in place, let v_{jt} specify the net amount of

Figure A1. An example barrier network. For each barrier, the current bidirectional passability pand the amount of river habitat v in the subnetwork immediately above the barrier are provided. The subnetwork specific to barrier 3 is highlighted in light blue. Barriers making up parameters/sets d_j , U_j , and F_j for barrier j = 3 are also provided. Note that barrier M is a dummy barrier located at the river mouth with initial passability 1 to ensure that all habitat within the river network is included in the calculation of the DCI_P metric.



river habitat above barrier *j* (i.e., within subnetwork *j*) for target *t*, let $V_t = \sum_j v_{jt}$ be the total amount of habitat for target *t* within the study area, let $v_j = \sum_t w_t v_{jt}$ be the weighted amount of habitat in subnetwork *j*, and let $V = \sum_t w_t V_t$ be the total weighted amount of habitat within the system. For each target *t*, initial passability of barrier *j* is given by p_{jt}^0 . Given mitigation (i.e., repair or removal) of barrier *j* at a cost of c_j , passability for target *t* increases by an amount p'_{jt} . It is assumed that a budget *b* is available for barrier mitigation.

Finally, we introduce the following decision variables.

625
$$x_j = \begin{cases} 1 & \text{if barrier } j \text{ is mitigated} \\ 0 & \text{otherwise} \end{cases}$$

617

626 z_i = total amount of weighted habitat accessible from subnetwork j

 z_{jt}^{dwn} = amount of accessible habitat for target *t* within and downstream of subnetwork *j*

 z_{jt}^{up} = amount of accessible habitat for target t upstream of barrier j

 y_{jt}^{dwn} = increase in accessible habitat for target t downstream of subnetwork j

 y_{jt}^{up} = increase in accessible habitat for target t upstream of barrier j

631 A mathematical formulation of our model is then given below.

$$\max \frac{1}{V^2} \sum_{j \in J} v_j z_j \tag{A3}$$

s.t.

$$\sum_{j \in J} c_j x_j \le b \tag{A4}$$

$$z_j = \sum_{t \in T} w_t \left(z_{jt}^{dwn} + \sum_{k \in U_j} z_{kt}^{up} \right) \qquad \forall j \in J$$
(A5)

$$z_{jt}^{dwn} = p_{jt}^0 \left(z_{d_jt}^{dwn} + \sum_{k \in F_j} z_{kt}^{up} \right) + v_{jt} + y_{jt}^{dwn} \qquad \forall j \in J, t \in T$$
(A6)

$$y_{jt}^{dwn} \le V_t x_j \qquad \qquad \forall j \in J, t \in T$$
(A7)

$$y_{jt}^{dwn} \le p_{jt}' \left(z_{d_jt}^{dwn} + \sum_{k \in F_j} z_{kt}^{up} \right) \qquad \forall j \in J, t \in T$$
(A8)

$$z_{jt}^{up} = p_{jt}^0 \left(\sum_{k \in U_j} z_{kt}^{up} + v_{jt} \right) + y_{jt}^{up} \qquad \forall j \in J, t \in T$$
(A9)

$$y_{jt}^{up} \le V_t x_j \qquad \qquad \forall j \in J, t \in T \tag{A10}$$

$$y_{jt}^{up} \le p_{jt}' \left(\sum_{k \in U_j} z_{kt}^{up} + v_{jt} \right) \qquad \forall j \in J, t \in T$$
(A11)

The objective (A3) maximizes total habitat availability within the study area. To understand the connection between (A1) and (A3), note that with only one target the amount of habitat accessible from subnetwork *j* is simply equal to $z_j = \sum_{i \in J} v_i \varphi_{ij}$. The objective function (A3) is then obtained through a simple rearrangement of the terms in (A1):

636
$$\frac{1}{V^2} \sum_{j \in J} \sum_{i \in J} v_i v_j \varphi_{ij} = \frac{1}{V^2} \sum_{j \in J} v_j \sum_{i \in J} v_i \varphi_{ij} = \frac{1}{V^2} \sum_{j \in J} v_j z_j$$

To continue, constraint (A4) specifies that the total cost of barrier mitigation cannot exceed the available budget *b*. Equations (A5) determine the total weighted amount of habitat z_j accessible from subnetwork *j*, which is calculated, for any given target *t*, by decomposing accessible habitat into "downstream" (z_{jt}^{dwn}) and "upstream" ($\sum_{k \in U_j} z_{kt}^{up}$) portions.

The amount of accessible habitat within and downstream of subnetwork *j* is determined by equations (A6). Looking at this equation in detail, the initial amount of habitat below subnetwork *j* is given by $p_{jt}^0 \left(z_{djt}^{dwn} + \sum_{k \in F_j} z_{kt}^{up} \right)$, the sum of habitat immediately downstream form *j* (z_{djt}^{dwn}) and the habitat confluent with *j* ($\sum_{k \in F_j} z_{kt}^{up}$), multiplied by the initial passability of *j* (p_{jt}^0). Added to this is $v_{jt} + y_{jt}^{dwn}$, the amount of habitat within subnetwork *j* (v_{jt}) plus any increase in downstream accessible habitat (y_{jt}^{dwn}).

647 The increase in downstream accessible habitat y_{jt}^{dwn} , meanwhile, is determined by inequalities 648 (A7) and (A8). Constraint (A7) specifies that if a barrier has not been mitigated ($x_i = 0$), then there can be no increase in downstream accessible habitat (i.e., $y_{jt}^{dwn} \leq 0$). If mitigation is carried out on barrier *j*, then (A7) is nonbinding and (A8) specifies that y_{jt}^{dwn} is bounded above by the amount of habitat strictly below $j (z_{djt}^{dwn} + \sum_{k \in F_j} z_{kt}^{up})$ multiplied by the change in passability at barrier $j (p'_{jt})$. Constraints (A9)-(A11) serve an analogous function as (A6)-(A8) for determining the amount of accessible habitat upstream of *j*).

It is important to point out that equations (A6) and (A9), as well as inequalities (A8) and (A11), are determined in a recursive manner and form a type of specialized network flow structure. Take (A6), for example. Downstream accessible habitat z_{jt}^{dwn} is determined in part by the amount of habitat downstream from j (z_{djt}^{dwn}) and in part by upstream habitat confluent with j($\sum_{k \in F_j} z_{kt}^{up}$). The term z_{jt}^{dwn} , in turn, feeds into the calculation of downstream habitat for subnetworks upstream from j (i.e., z_{kt}^{dwn} such that $k \in U_j$ via term $z_{dkt}^{dwn} = z_{jt}^{dwn}$).

This is the major novelty of our formulation, which is akin the "probability chain" concept 660 introduced in O'Hanley et al. (2013) and subsequently applied to resident fish passage barrier 661 mitigation in King (2017). The main difference from the approach adopted in King (2017) is that 662 instead of calculating cumulative passability values (i.e., the φ_{ii} terms), we use a network flow 663 structure to calculate downstream and upstream habitat availability (i.e., the z_{jt}^{dwn} and z_{jt}^{up} 664 665 terms). The main advantage and novelty of newly proposed linearization is that it requires 666 substantially fewer auxiliary variables and constraints, thus resulting in significantly reduced run 667 times to solve the model.

668 Our proposed model was coded in OPL, the programming language tied to the IBM ILOG669 CPLEX Optimization Studio platform. OPL is a high-level algebraic modeling language for

- 670 formulating linear optimization problems. The OPL implementation of our model was solved
- 671 using the CPLEX mixed integer linear programming (MILP) solver.

674 Appendix C: Sensitivity Analysis

675 We performed a sensitivity analysis to quantify the degree to which model outputs might depend on uncertainty in the underlying data. For each of the three key parameters that influence 676 optimization model outputs (project costs, barrier passability, and total length of river upstream 677 678 of each barrier to the nearest set of upstream barriers), we performed an independent sensitivity 679 test by randomly increasing or decreasing each value of that parameter in the data set by 10% while holding all other parameters constant. We repeated this process 15 times for each of the 680 three key parameters, generating a total of 45 iterations of our data set. For each of these 45 data 681 sets, we then calculated the percentage increase in connectivity (as measured by DCI) for stream-682 683 resident fish that could be achieved for budgets of \$5 million and \$20 million.

684 Overall, we found that optimization model outputs were relatively insensitive to variation in input parameters (Fig. C1, C2). For a budget of \$5M, for example, the greatest variation in 685 connectivity gains resulted from altering project costs (Fig. C1A); however, even in that case, 686 687 randomly assigning project costs to be $\pm 10\%$ of their estimated value resulted in only $\pm 2.5\%$ in connectivity gains. For a budget of \$5 M, increases in connectivity were less dependent on 688 variability in passability estimates (Fig.C1B) and upstream river length (Fig. C1C). For a budget 689 690 of \$25 M, the greatest variation in connectivity gains resulted from altering estimates of 691 upstream river length (Fig. C2C); in the case, randomly assigning estimates of upstream river length to be \pm 10% of their estimated value resulted in \pm 2.6% in connectivity gains. For a budget 692 of \$20 M, increases in connectivity were less dependent on variability in estimates of project 693 costs (Fig. C2A) and barrier passability (Fig. C2B). 694



695

Figure C1: Variation in the percent increase in connectivity (as measured by DCI) that could be achieved for a budget of \$5 million under three sensitivity tests: A) manipulating estimates of project costs to be \pm 10% of their estimated value, B) manipulating passability estimates to be \pm 10% of their estimated value, and C) manipulating estimates of upstream river length to be \pm 10% of their estimated value.



Figure C2: Variation in the percent increase in connectivity (as measured by DCI) that could be achieved for a budget of \$20 million under three sensitivity tests: A) manipulating estimates of project costs to be \pm 10% of their estimated value, B) manipulating passability estimates to be \pm 10% of their estimated value, and C) manipulating estimates of upstream river length to be \pm 10% of their estimated value.