1	Improved modelling of the impacts of sea level rise on coastal wetland plant
2	communities

3 Ward, R.D.<sup>a</sup>, Burnside, N.G.<sup>a</sup>, Joyce, C.B.<sup>a</sup>, Sepp, K.<sup>b</sup> and Teasdale, P.A.<sup>a</sup>

4 a Aquatic Research Centre, School of the Environment and Technology, University of Brighton,

5 Cockcroft Building, Moulsecoomb, Brighton, BN2 4GJ, United Kingdom

b Department of Landscape Management, Estonian University of Life Sciences, Fr.R. Kreutzwaldi 1,
51014, Tartu, Estonia

#### 8 Abstract

9 This study presents an enhanced methodology for modelling the impacts of sea level rise on coastal wetlands. The tool integrates dGPS calibrated LiDAR data, isostatic 10 uplift and sediment accretion rates to predict the location and extent of plant 11 communities at three non-contiguous micro-topographical coastal wetlands in Estonia 12 by 2100 in response to global sea level rise. Results showed an increase in surface 13 elevation (related to sediment accretion and isostatic uplift) resulting in a decrease in 14 local sea level in the majority of sites and scenarios in the north of the country although 15 a rise in sea level is predicted in sites with limited allochthonous sediment supply 16 predominantly impacting higher elevation plant communities. Wetlands situated on the 17 west coast are likely to maintain equilibrium with sea level as result of lower 18 sedimentation and isostatic uplift than more northerly sites. This study shows that 19 dGPS calibrated LiDAR data and sediment accretion are essential to maintain model 20 validity in Baltic coastal wetlands due to their low relief and could considerably improve 21 current sea level rise impact models for other regions. 22

#### 23 Keywords

Coastal wetlands; Climate change impacts; Sea level rise modelling tool; LiDAR;
Coastal plant communities

#### 26 Introduction

27 Coastal wetlands are among the most productive ecosystems in the world containing specialist plant species and providing a habitat for a wide diversity of taxa (Allen & 28 Pye, 1998). They also provide important ecosystem services such as coastal 29 protection (Gedan et al., 2011), carbon sequestration (Hopkinson et al., 2012), and 30 nutrient cycling (Barbier et al., 2011). However, coastal wetlands are under threat from 31 sea level rise (SLR) (Nicholls & Cazenave, 2010; Weisse et al., 2014) particularly 32 those located in low lying countries with maritime borders (IPCC, 2013). Current 33 predictions of global sea level rise suggest that SLR will be in the region of 0.26m -34 0.82m by 2100 (IPCC, 2013). 35

In order to make an assessment of the threats to coastal wetlands from sea level rise 36 a variety of models have been developed (Bertrand et al., 2011; Moeslund et al., 2011; 37 Stratonovitch et al., 2012; Bellafiore et al., 2014). Typically, ecological modelling is 38 39 based on knowledge of environmental gradients, which are used as ecological 40 predictors (Burnside & Waite, 2011). Many sea level rise impact models developed for coastal wetlands utilise elevation data as a proxy for hydrology (Moeslund et al., 2011), 41 and the most accurate remotely sensed elevation data available are LiDAR (Gesch, 42 2009). However, LiDAR elevation data have inherent inaccuracies due to the 43 impenetrability of laser pulses through vegetation (Sadro et al., 2007; Ward et al., 44 2013). To overcome these inaccuracies Ward et al. (2013) developed a model that 45 can accurately estimate the current distribution of plant communities in micro-46 topographical coastal wetlands using dGPS calibrated LiDAR data. 47

The recent IPCC (2013) report suggests that climate change will not affect only sea
level and temperature, but is also likely to lead to increased storminess in many areas,

particularly in northern Europe and the Baltic (Rozynski & Pruszak, 2010). Previous 50 studies have shown that in predominantly depositional areas, increased storminess 51 and rising sea levels can facilitate wetland development through sediment deposition 52 (Friedrichs & Perry, 2001; French, 2006; Schuerch et al., 2012; Tsompanglou et al., 53 2012; Ward et al., 2014). A variety of studies have suggested that sediment deposition 54 alone could, in a wide variety of coastal wetlands, keep pace with SLR, thus preventing 55 any large scale wetland loss (Friedrichs & Perry, 2001; French, 2006; Kirwan and 56 Temmerman, 2009; Mudd et al., 2009;). However, many predictive SLR impact models 57 58 (Poulter & Halpin, 2008; Kont et al., 2008; Moeslund et al., 2011) neglect to take into account sediment accretion as a factor even where these data are available. 59

60 This study tested the hypotheses:

1) Does dGPS calibration improve modelling current plant community types in Balticcoastal wetlands?

2) How does the consideration of dGPS LiDAR correction, sediment accretion rates
and the impacts of increased storminess influence plant community distribution by
2100?

3) What do these findings mean for assessing the impacts of sea level rise on coastalwetlands?

Baltic coastal wetlands have been selected for this study as (i) they require greater model accuracy due to the low gradients [typically <1.2m above mean sea level], (ii) they are extensive [extending up to 2 km inland], (iii) they are of ecological importance (EC Habitats Directive, 1992) and (iv) they show micro-topographic variation between the range of wetland plant communities.

#### 73 Materials and Methods

#### 74 Study area

Post glacial isostatic rebound has caused much of the landmass of northern and western Estonia to rise from the sea (Eronen et al., 2001), producing a long shallow coastline. Average isostatic uplift rates of 2.5 mm/yr are found on the west coast with a maximum of 2.8 mm/yr in the far north west (figure 1).

The Baltic Sea along the Estonian coast has almost no regular tide (0.02 m) (Suursaar 79 et al., 2001). However, major fluctuations in sea level do occur due to seasonally 80 changing meteorological conditions facilitating storm surges and variations in 81 barometric pressure, causing an irregular influx of sediment to the coastal wetlands. 82 The highest recorded sea level was during the 2005 storm Gudrun, which caused a 83 84 2.75 m storm surge in Pärnu, Estonia. More typically, water levels do not vary more than between 0.3 m below and 0.4 m above m.s.l. (EMHI, 2012). The generally low 85 relief of Baltic coastal wetlands (between -0.28 m and +1.2 m) means that they can be 86 inundated during periods of elevated sea level. Burnside et al. (2007) identified six 87 main plant communities with indicator species for Estonian coastal wetlands. These 88 89 were: Clubrush Swamp (CS), Reed Swamp (RS), Lower Shore (LS), Upper Shore (US), Tall Grass (TG), and Scrub and developing Woodland (SW). Plant community 90 distribution is characterised by different elevations above m.s.l. related to differing 91 inundation frequencies and durations (Ward et al. 2010) (table 1). 92

Three study sites were selected to model the potential effects of sea level rise on Estonian coastal wetlands in order to represent a range of controlling factors. The Tahu and Kudani wetlands (figure 1) are located in the Silma Nature Reserve in the northwest of Estonia along the south coast of the Baltic Sea. These two sites are

influenced by higher isostatic uplift rates than the third site, Matsalu. Tahu has access 97 to an allochthonous sediment supply and sediment accretion rate data for this site are 98 available. Kudani is cut off from an allochthonous sediment source, and 99 autochthonous soil formation through plant decomposition is considered to be very 100 low in these wetlands (Puurmann & Ratas, 1998). At both Tahu and Kudani, all of the 101 six main plant community types were present. The Matsalu coastal wetland (figure 1) 102 is located in Matsalu National Park and has both lower isostatic uplift and sediment 103 accretion rates than Tahu but greater sediment accretion rates than Kudani. At 104 105 Matsalu, the Clubrush Swamp plant community is not found at the lower elevations due to greater wave energy than at Tahu and Kudani. The Scrub and developing 106 Woodland plant community is also absent from Matsalu due to a different management 107 history to the other sites. 108

# 109 Baseline plant community modelling

110 In order to test hypothesis 1, does DGPS LiDAR calibration improve plant community 111 modelling in Baltic coastal wetlands, and model the potential effects of sea level rise (hypothesis 2), a baseline digital elevation model was required. Ward et al. (2013) 112 developed a methodology to produce an accurate (0.02 m) digital elevation model 113 (DEM) for use in Baltic coastal wetlands using dGPS calibrated LiDAR data. The DEM 114 was derived from medium point density LiDAR data with a footprint of 0.54 m and an 115 average point density of 0.45 points/m<sup>2</sup> collected by the Estonian Land Board in 2009 116 using an ALS50-II laser/detector. dGPS calibration data were collected using a Trimble 117 5700 system (accuracy 0.02 m). Calculations for dGPS calibration of the LiDAR 118 elevation data were conducted in Matlab R2010a using the Ward et al. (2013) 119 methodology. DEM interpolation was conducted based upon raw values for LiDAR 120 121 within ArcGIS 10.1 and using a Delaunay triangulated irregular network (TIN). dGPS

calibration data were added to the last return LiDAR point values. DEMs for each site 122 were categorised using plant community elevation preferences (table 1) (Ward et al., 123 2010) (baseline scenario a). The dGPS calibrated plant community model was used 124 as a baseline for modelling the location of the plant communities by 2100 using 125 modelling parameters explained in the following section. Validation of the baseline 126 plant community models was conducted using a stratified random ground truth survey 127 in July, 2010. At each site 15 points were selected within each predicted plant 128 community yielding ninety 1m<sup>2</sup> quadrats at both Tahu and Kudani and sixty at Matsalu 129 130 (due to the lower number of plant communities) and the presence and abundance of all plant species recorded. Validity of plant community models compared to ground-131 truthed data was assessed using a Fleiss' Kappa coefficient (Landis & Koch, 1972). 132

### 133 Environmental modelling parameters

The baseline model was modified by integrating isostatic uplift rates (Eronen et al. 134 2001), sea level rise data (IPCC 2013) and sediment accretion estimates (Ward et al. 135 136 2014) (figure 2) to predict the location and extent of the plant communities in response to local sea level by 2100 (hypothesis 2). Current IPCC (2013) estimates of global sea 137 level rise are between 0.26 m and 0.82 m by 2100 dependant on scenario. Therefore 138 a mid-range SLR figure of 0.54 m was selected to represent climate driven sea level 139 rise. At the Tahu and Kudani coastal wetlands, isostatic uplift rates were included 140 based on studies by Vallner et al. (1988) and Eronen et al. (2001) (figures 1 and 2). 141 Both the sea level rise and isostatic uplift data were utilised in scenarios b, c, d and e. 142 In scenario b only sea level rise and isostatic uplift were utilised (sediment accretion 143 data not incorporated) to identify changes in plant community location using the dGPS 144 calibrated baseline model. 145

A further parameter incorporated into the model was sediment accretion, [Nolte et al., 146 (2013) terminology]. Past rates of sediment accretion for the Tahu and Matsalu coastal 147 wetlands were based on data derived from <sup>210</sup>Pb radionuclide dating of sediment cores 148 and independently verified using the <sup>137</sup>Cs dating method (Ward et al., 2014). Mean 149 accretion rates for Tahu were 1.9 mm/yr, and for Matsalu 0.9 mm/yr. No accretion 150 rates were used for Kudani (figure 2) as it is largely separated from the sea, and hence 151 lacks a significant allochthonous sediment source and is unlikely to have significant 152 autochthonous organic production. These mean accretion rates were utilised in 153 154 scenarios c and e, although in scenario e the dGPS correction to the LiDAR was not used for comparison. 155

Increased storminess has been linked to greater sediment accretion in predominantly 156 depositional wetlands (Allen, 2000; Kolker et al., 2009; Schuerch et al., 2012). Ward 157 et al. (2014) have shown that increased sedimentation occurs during periods of greater 158 storminess at both the Tahu and Matsalu sites. The IPCC (2013) report states that 159 there is likely to be an increase in the frequency of extreme weather events. In order 160 to take this into account in the model the number of elevated accretion periods 161 recorded in the sedimentary record (Ward et al., 2014) for each site was doubled, as 162 has been suggested by Bender et al. (2010), and a new mean for sedimentation 163 calculated. Scenario d incorporated the increased storminess sediment accretion data 164 to the dGPS calibrated baseline plant community model to predict the location of the 165 plant communities by 2100. 166

The plant community extent outputs using each of these parameters were compared and the results discussed in terms of current models in order to assess the impacts of the individual parameters on model outputs (hypothesis 3).

#### 170 **Results**

# 171 Baseline plant community modelling

The dGPS calibrated LiDAR based plant community models were able to accurately describe the location of the plant communities at Tahu ( $\kappa$  coefficient 0.63, 70.6% correctly identified), Matsalu ( $\kappa$  coefficient 0.89, 91.7% correctly identified) and Kudani ( $\kappa$  coefficient 0.81, 80.0% correctly identified) (table 2) providing a robust static plant community model as a baseline for scenario model development.

At Tahu the model was able to accurately predict the location of the plant community 177 types in only 25% of cases ( $\kappa$  = 0.10), at Matsalu only 14.2% of cases (Kappa 178 coefficient 0.03) and at Kudani 27.8% of cases ( $\kappa = 0.13$ ), a substantial deterioration 179 in model validity. In the majority of cases incorrect identification of the plant 180 181 communities was due to the overestimation of elevation due to interference in LiDAR penetrability through the vegetation canopy. This resulted, in the majority of cases, in 182 the model predicting the adjacent higher elevation plant community e.g. RS in place 183 of CS. 184

#### 185 Plant community model for 2100

#### 186 Tahu 2100

Tahu has the highest sediment accretion and isostatic uplift rates of the studied sites and thus is likely to experience the least impact from SLR. Scenario b predictions (discounting sediment accretion but utilising the calibrated LiDAR) suggest a 9.7% loss of the total wetland area and considerable decrease in the extent of the higher elevation plant communities, namely TG -42.4% and SW -37.7% (table 4). However, scenario c (utilising the sediment accretion data and the dGPS calibration of the

LiDAR) suggests a progradation of the wetland into the Baltic Sea (figure 3c) and a 193 consequent increase in the wetland area of 1.7% by 2100 (table 4). In scenario d 194 assuming an increase in storminess, sediment accretion rates (2.5 mm/yr averaged 195 196 over a 100 year period) are almost as high as isostatic uplift (2.8 mm/yr) (figure 2) suggesting that during storm events sediment accretion is even higher. The model 197 predicts that there will be an increase of 12.6% of the current wetland area (table 4, 198 figure 3d). The model output including sediment accretion estimates but not utilising 199 the calibrated LiDAR (figure 3e, scenario e) predicts progradation of the wetland, with 200 201 an increase of 28.5% of the total wetland area by 2100 (table 2).

### 202 Matsalu 2100

203 Matsalu is typified by lower uplift and sediment accretion rates than Tahu. In scenario b (dGPS calibration but discounting sediment accretion) there is a small predicted loss 204 of the wetland area (-1.0%, table 4 and figure 4b). In this model output the greatest 205 206 predicted losses occur in the US (-53.0%) and TG (-27.1%) plant communities (table 207 4). In model output c (utilising the dGPS correction and assuming no change in sediment accretion rates), there is a predicted loss of 0.8% of the wetland area by 208 2100 (table 4, figure 4 c). The greatest losses are expected in the higher elevation 209 plant communities US (-29.5%) and TG (-18.9%). In model output d, averaged 210 sediment accretion rates over a 100 year period assuming an increase in storminess 211 are 1.6mm/yr comparable with those of isostatic uplift 2.0mm/yr, suggesting that 212 during storm events sediment accretion exceeds the rates of isostatic uplift as at Tahu 213 (figure 2). In this model output, the model predicts a 0.5% decrease in the total area 214 of wetland by 2100 (table 4, figure 4d). In model output e (taking into account 215 sedimentation but not including the dGPS calibration), there is predicted to be little 216

change in plant community extent and no increase in the total wetland area (table 4,figure 4e).

#### 219 Kudani 2100

The Kudani site along with Tahu has the highest isostatic uplift rates in Estonia and in 220 the modelling an assumption was made that there was no significant sediment 221 accretion (figure 2). Model output b (utilising the dGPS calibration) suggests a 222 decrease of 10.1% in the total extent of the wetland by 2100 (figure 5b, table 4). The 223 lower elevation plant communities, although of limited extent, are expected to increase 224 (CS 150.6%, RS 160.7% and LS 5.8%) at the expense of the higher elevation 225 communities (US -35.9%, TG -26.0% and SW -32.0%) at Kudani by 2100. Model 226 output e not using the dGPS calibration are substantially different, predicting an 227 increase in the total extent of the wetland of 2.1% (figure 5e, table 4). 228

229 Discussion

Hypothesis 1: 'does dGPS calibration improve modelling current plant
 community types in Baltic coastal wetlands?'

The relationship between elevation above mean sea level and plant community type 232 provided a basis for developing predictive plant community models for coastal 233 wetlands (Ward et al., 2010). However, elevation differences between some of the 234 plant communities in these Baltic coastal wetlands were small, with a minimum of 0.04 235 m. Hence it was necessary to obtain highly accurate elevation data that covered a 236 variety of Baltic coastal wetland sites. Due to the small size of some of the plant 237 community patches, as is typical in many mosaic coastal wetlands, it was also 238 necessary to obtain high resolution data for the study areas. The most widely available 239

data that fulfil these conditions are LiDAR elevation. The results of this study have 240 shown that plant communities can be accurately identified using dGPS calibrated 241 LiDAR data. LiDAR data have been successfully used in several studies to develop 242 plant community models over large field areas (Morris et al., 2005; Prisloe et al., 2006; 243 Sadro et al., 2007; Chust et al., 2008; Moeslund et al., 2011). However, none of these 244 studies modelled plant communities at such a fine scale as that developed in this study 245 for micro-topographical coastal wetlands, hence the requirement for the dGPS 246 calibration. 247

This study has shown that in environments with a strong relationship between plant 248 249 community type and small changes in elevation, dGPS calibrated LiDAR is a robust data choice due to its elevation accuracy and the density of the point cloud and a 250 significant improvement on models utilising non-calibrated LiDAR. In this study plant 251 community models run without the dGPS correction provided a substantially inferior 252 outcome (with dGPS calibration  $\kappa$  = 0.63-0.89 and without  $\kappa$  = 0.03-0.13), addressing 253 hypothesis 1 (does dGPS calibration improve modelling current plant community types 254 in Baltic coastal wetlands?). 255

In previous studies in tidal coastal wetlands, with a greater range in relief, calibration 256 and adjustment have not been used and are perhaps not necessary to produce a 257 robust model able to distinguish plant communities based on their elevation range 258 (Morris et al., 2005; Prisloe et al., 2006; Poulter & Halpin, 2008; Moeslund et al., 2011). 259 However, the improvements in the accuracy of the model developed in this study could 260 significantly enhance the accuracy of models developed by using dGPS calibration 261 data for any tidal coastal wetlands with a greater relief. This suggests that dGPS 262 integration would also improve the robustness of correlative plant community models 263 264 in wetlands with greater relief such as tidal salt marshes.

# Hypothesis 2: 'how does the consideration of dGPS LiDAR correction, sediment accretion rates and the impacts of increased storminess influence plant community distribution by 2100?'

The predictive plant community models developed in this study, incorporated the main 268 factors predicted to influence the future location and extent of vegetation in coastal 269 wetlands: isostatic uplift, eustatic sea level rise, and sediment accretion (McFadden et 270 al., 2007). Previous studies assessing the effects of sea level rise on coastal wetlands 271 have been limited due partly to the use of inaccurate elevation data, whereas greater 272 accuracy is required for micro-topographical coastal wetlands, and especially the 273 exclusion of sediment accretion data. In the model outputs not utilising dGPS 274 calibrated LiDAR (model output e) to predict plant community distribution by 2100 275 progradation of the wetland is seen (figures 3, 4 and 5) a significant difference to the 276 dGPS calibrated model outputs. 277

278 In many coastal wetlands sediment accretion is a primary driver of wetland 279 development (Webb et al., 2013) and accretion rates are therefore an important factor to be taken into account when modelling the effects of sea level rise on coastal 280 environments (McFadden et al., 2007). This study has utilised historical sediment 281 accretion rates derived from <sup>210</sup>Pb dating (Ward et al., 2014) and extrapolated the 282 results for sea level rise modelling (Craft et al., 2009). The results showed that 283 sediment accretion has a considerable effect on modelling local sea level rise impacts 284 on wetland plant communities, highlighted by the substantial differences in the 285 predicted distribution of the plant communities (figure 3b, c, d, e), particularly at Tahu. 286 Many previous studies of the impacts of sea level rise in coastal wetlands have ignored 287 sediment accretion (Suursaar et al., 2006; Kont et al., 2008, Moeslund et al., 2012). 288 289 Moeslund et al. (2011) justify this exclusion from their dynamic correlative model by

suggesting that accretion rates vary greatly within sites and that the majority of 290 sediment accretion data available are generalised from few samples. However, whilst 291 extrapolation of accretion data from few samples can be problematic due to the spatial 292 variability of sediment deposition the exclusion of these data is likely to provide greater 293 dynamic model prediction errors. Results from this study have shown that sediment 294 accretion rates taking into account increased storminess are of a similar magnitude to 295 isostatic uplift (1.6-2.5 mm/yr compared with 2.0-2.8 mm/yr respectively). Ward et al. 296 (2014) have estimated that during periods of elevated sediment accretion, rates can 297 298 be as high as 5 mm/yr, well in excess of isostatic uplift. In the model outputs assuming an increase in storminess (output d in figures 3, 4 and 5) the impacts of sea level rise 299 are reduced and in the case of Tahu progradation is predicted to take place. This has 300 been predicted to be the case in sheltered coastal wetlands in many areas of the world 301 including the Baltic (Schuerch et al., 2013; Tweel and Turner, 2014; Schindler et al., 302 2014; Ward et al., 2014) suggesting that this is a useful addition to plant community 303 modelling parameters. 304

# Hypothesis 3: 'what do these findings mean for assessing the impacts of sea level rise on coastal wetlands?'

The model developed in this study accurately predicted the location and extent of plant 307 communities in micro-topographic non-tidal Baltic coastal wetlands. The model also 308 309 has potential applications in other appropriate open environments such as floodplains, tidal coastal marshes or for the restoration of wetlands. It does however, have 310 limitations that should be taken into account when interpreting the results. As with any 311 correlative model, there is regional specificity and hence the particular model 312 developed in this study is unlikely to be valid in locations other than Estonia without 313 314 further ground-truthing. The model is also based on the assumption that sea level and sediment accretion will be the only environmental variables that will change due to climate effects by 2100. However, IPCC (2013) climate change scenarios suggest that temperature will also increase and several studies have suggested that this could cause a northward migration of some plant species (Dullinger et al., 2004; Aitken et al., 2008; Hilyer & Silman, 2010), which is likely to affect community composition in coastal wetlands, particularly at the extreme geographical ranges of individual species.

321 Salt marshes are an obvious environment for the further application of the dynamic plant community model presented in this study. Several authors have related the 322 zonation of marsh communities to elevation above mean sea level and hence tidal 323 range (Cutini et al., 2010; Moffett et al., 2010; Suchrow & Jensen, 2010; Moffett et al., 324 2012). However, tidal ranges vary greatly, so any plant community model would likely 325 be valid only for areas with similar tidal regimes. As correlative plant community 326 327 models have been suggested to be location specific (Franklin, 1995) in localities with different tidal regimes model parameters will need to be adjusted. Furthermore, salt 328 marshes, whilst retaining a similar zonal character typically consisting of a low marsh, 329 middle marsh and a high marsh (Nottage & Robertson, 2005), have a geographically 330 varying species composition requiring the use of different plant community 331 classifications dependent on location (Pennings et al., 2003). Ellenberg (1988), 332 Rodwell (1992) and Isaach et al. (2006) have produced plant community 333 classifications for continental European, UK and South American salt marshes 334 respectively, which would be suitable for use as base model development. With 335 regards to the geomatic stages involved in applying the plant community tool to salt 336 marshes, the conceptual model developed in this study (figure 2) would be applicable 337 for other coastal wetland systems. 338

### 339 Conclusions

Remotely sensed data have been successfully used in many studies to develop plant 340 community models over large field areas. However, previously developed models are 341 unable to work effectively at such a fine scale as that developed in this study. The 342 addition of the dGPS calibration to the model represents an improvement to previous 343 LiDAR based models (Morris et al., 2005; Chust et al., 2008; Moeslund et al., 2011). 344 Without dGPS calibration, this study reported Kappa values of only 0.03-0.13 for Baltic 345 coastal wetlands, compared to Kappa 0.63-0.89, dependant on site, when the 346 calibration was used. Moreover, previous studies investigating the effects of sea level 347 348 rise on coastal wetlands have neglected to include sediment accretion data (Morris et al., 2005; Chust et al., 2008; Moeslund et al., 2011). The results of this study have 349 shown that sediment accretion in some Baltic coastal wetland sites can contribute to 350 greater vertical growth at the littoral edge of the wetland than isostatic uplift, 351 particularly during periods of increased storminess. Thus, dGPS calibrated LiDAR and 352 sediment accretion data are essential to maintain model validity in Baltic coastal 353 wetlands due to their low relief. These data could also considerably improve sea level 354 rise impact models for coastal wetlands in other geographical areas including micro, 355 meso and macro-tidally influenced saltmarshes and wet grasslands. 356

#### 357 Acknowledgements

This research was funded, in part, by the University of Brighton. This research was also supported by the European Social Fund's Doctoral Studies and Internationalisation Programme DoRa, Estonia; and the Estonian Land Board.

We would also like to thank Henri Järv, Tiina Järv, Samuel Bastable, Darren Ward, Taaniel Sepp, Martin Leppik, Kuldar Kuusik, Mae-Liis Sepp, Triin Jaagus and the staff of the Matsalu National Park and the Silma Nature Reserve.

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Figure 1: Study sites in a regional and national context. Isostatic uplift rates are shownin millimetres (rates reproduced from Eronen et al., 2001).

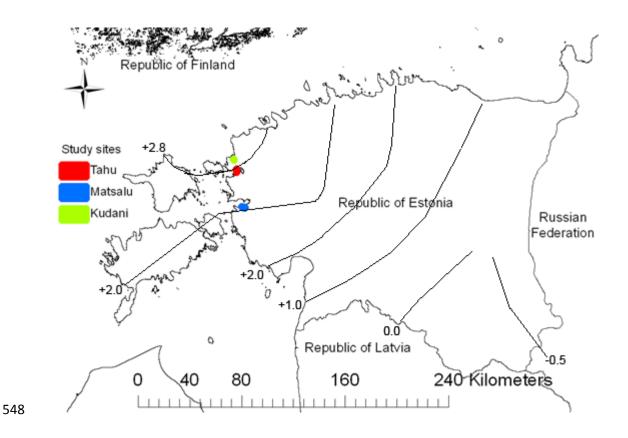


Figure 2: Conceptual model of local sea level rise at Tahu, Kudani and Matsalu study
sites by 2100. Factors decreasing local sea level are denoted with a minus and those
increasing local sea level are denoted with a plus sign.

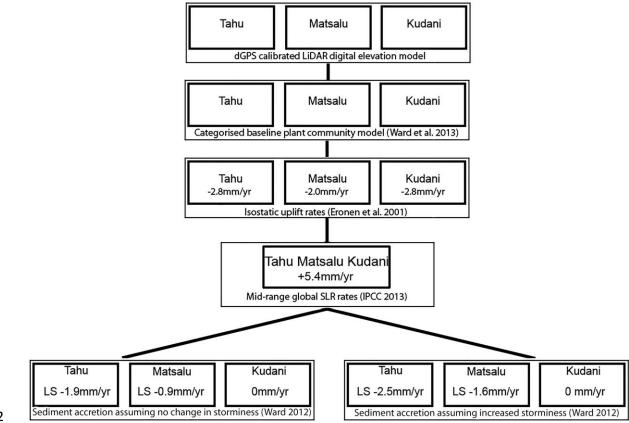
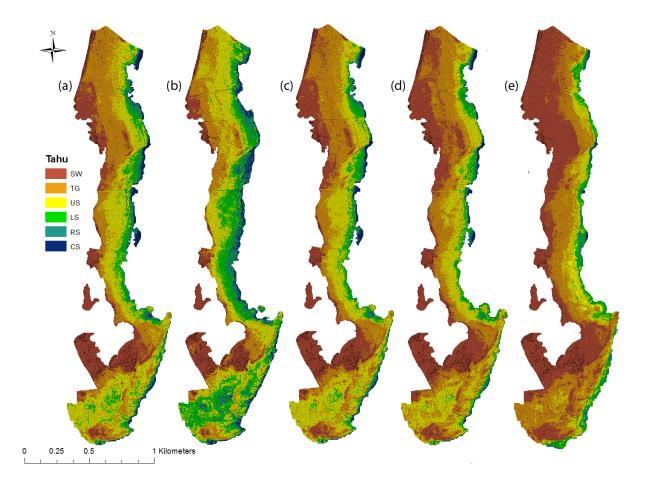
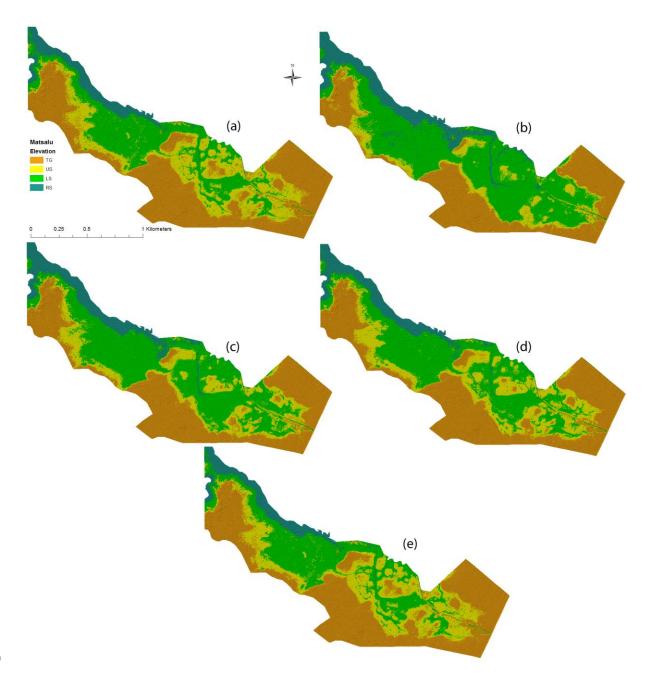


Figure 3: Tahu plant community model output. Plant community location is mapped 553 showing the (a) baseline 2010 locations using the dGPS correction, (b) changes by 554 2100 using the dGPS correction but no sediment data, (c) changes by 2100 using the 555 dGPS correction and assuming no change in sedimentation rates, (d) changes by 556 2100 using the dGPS correction and assuming an increase in sedimentation rates due 557 to greater storm activity, (e) changes by 2100 not using the dGPS correction and 558 assuming no change in sedimentation rates. See table 1 for explanation of plant 559 community codes. 560



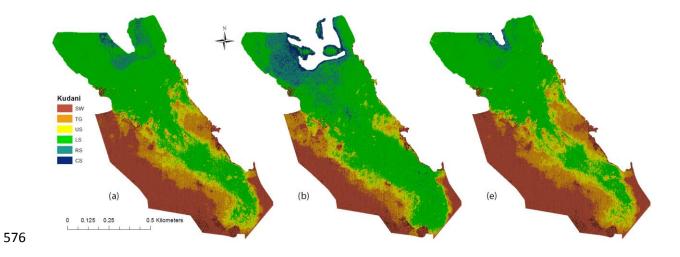
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Figure 4: Matsalu plant community model output. Plant community location is mapped 562 showing the (a) baseline 2010 locations using the dGPS correction, (b) changes by 563 2100 using the dGPS correction but no sediment data, (c) changes by 2100 using the 564 dGPS correction and assuming no change in sedimentation rates, (d) changes by 565 2100 using the dGPS correction and assuming an increase in sedimentation rates due 566 to greater storm activity, (e) changes by 2100 not using the dGPS correction and 567 assuming no change in sedimentation rates. See table 1 for explanation of plant 568 community codes. 569



570

Figure 5: Kudani plant community model output. Plant community location is mapped showing the (a) baseline 2010 locations using the dGPS correction, (b) changes by 2100 using the dGPS correction but no sediment data, (c) changes by 2100 not using the dGPS correction and assuming no change in sedimentation rates. See table 1 for explanation of plant community codes.



577 Table 1: Elevation ranges of the six plant community types above mean sea level used

in the model (BK77 as measured at Kronstadt, in m). Elevation ranges calculated using

a Leica rtk dGPS derived from 2100 records per plant community.

Elevation range (m)
-0.20 to 0.07
0.07 to 0.15
0.15 to 0.27
0.27 to 0.47
0.47 to 0.69
0.69 to 1.2

Table 2: Percentage of quadrats of each plant community type correctly identified at
each site utilising the dGPS calibration. A Fleiss' Kappa coefficient was used to assess
plant community model accuracy at Tahu, Matsalu and Kudani (from Ward et al.,
2013). See table 1 for explanation of plant community codes.

	Observed		<b>F</b> .	( . 1 .				0
		Expected Community					Correctly	
Interpolation	community	CS	RS	LS	US	TG	SW	identified
Tahu	CS	86.7	10					86.7
	RS	13.3	90					90
	LS			80	53.3	26.7		80
	US			20	46.7	20		46.7
	TG					53.3	33.3	53.3
	SW						66.7	66.7
		к coefficient 0.63					Mea	an 70.6

Matsalu	RS	N/A	100.0				N/A	70
	LS	N/A		80.0	6.7		N/A	80
	US	N/A		20.0	86.7		N/A	43.3
	TG	N/A			6.7	100.0	N/A	46.7
		кcoeff	icient 0.8	89			Mea	an 91.7
Kudani	CS	100.0						100.0
	RS		100.0					100.0
	LS			80.0	20.0	13.3		80.0
	US			20.0	60.0	26.7	6.7	60.0
	TG				20.0	60.0	13.3	60.0
	SW						80.0	80.0
		к coefficient 0.81					Mea	an 80.0

Table 3: Percentage of quadrats of each plant community type correctly identified at
each site utilising modelling with no dGPS correction. A Fleiss' Kappa coefficient was
used to assess plant community model accuracy at Tahu, Matsalu and Kudani. See
table 1 for explanation of plant community codes.

	Observed	Expected Community Correctly						
Internelation		66	RS	LS	US	TG	SW	•
Interpolation	community	CS	кэ	LO	03	IG	300	identified
Tahu	CS							0.0
	RS	83.3						0.0
	LS	16.6	100.0		20.0			0.0
	US			93.3	20.0	33.3		20.0
	TG			6.6	60.0	30.0		30.0
	SW					36.6	100.0	100.0
		кcoeff	icient 0.1	0			Mean 25.0	
Matsalu	RS	N/A					N/A	0
	LS	N/A	80.0				N/A	0
	US	N/A	20.0	50.0	10.0		N/A	10
	TG	N/A		50.0	90.0	100.0	N/A	46.7
	к coefficient 0.03				Mean 14.2			
Kudani	CS							0.0
	RS	100.0						0.0
	LS		86.6					0.0
	US		13.3	66.6	26.6			26.6
	TG			26.6	10.0	40.0		40.0
	SW			6.6	73.3	60.0	100.0	100.0
		к coefficient 0.13				Me	an 27.8	

591 Table 4: Predicted changes in the extent of each plant community and total wetland area from 2010 by 2100 at Tahu, Matsalu and Kudani. Model parameters are: a = 592 baseline situation in 2010, b = using dGPS correction but no sediment data, c = using 593 dGPS correction and sediment data assuming no increase in storm activity, d = using 594 dGPS correction and sediment data assuming an increase in storm activity, e = not 595 using dGPS correction but using sediment data assuming no increase in storm activity 596 (except Kudani where no sediment accretion is assumed). See table 1 for explanation 597 of plant community codes. 598

Plant community	a (na)		c (% change)	d (% change)	e (% change)
Tahu		5 /	5 /	5 /	<u></u>
CS	0.6	133.3	14.7	-6.2	-1.1
RS	4.5	137.8	0.5	-2.3	7.0
LS	11.7	112.8	-23.5	-4.6	2.1
US	37.8	-2.1	-7.1	2.0	5.7
TG	35.6	-42.4	4.7	2.0	10.1
SW	26.8	-37.7	17.4	33.2	71.1
Total	117.0	-9.7	1.7	12.6	28.5
Matsalu					
RS	12.5	60.8	28.8	13.6	0.0
LS	48.9	76.9	49.9	24.7	-0.1
US	45.5	-53.0	-29.5	-11.6	-0.3
TG	85.1	-27.1	-18.9	-11.2	0.4
Total	192	-1.0	-0.8	-0.5	0.0
Kudani					
CS	1.4	150.6	-	-	1.1
RS	2.1	160.7	-	-	-1.8
LS	36.0	5.8	-	-	-3.6
US	9.2	-35.9	-	-	10.9
TG	10.0	-26.0	-	-	14.0
SW	20.0	-32.0	-	-	13.5
Total	78.7	-10.1	-	-	2.1