- 1 How to best threshold and validate stacked species assemblages? Community
- 2 optimisation might hold the answer
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19 ABSTRACT

The popularity of species distribution models (SDMs) and the associated stacked
 species distribution models (S-SDMs), as tools for community ecologists, largely
 increased in recent years. However, while some consensus was reached about the best
 methods to threshold and evaluate individual SDMs, little agreement exists on how to
 best assemble individual SDMs into communities, i.e. how to build and assess S-SDM
 predictions.

2. Here, we used published data of insects and plants collected within the same study 26 region to test (1) if the most established thresholding methods to optimize single 27 species prediction are also the best choice for predicting species assemblage 28 composition, or if community-based thresholding can be a better alternative, and (2) 29 whether the optimal thresholding method depends on taxa, prevalence distribution 30 and/or species richness. Based on a comparison of different evaluation approaches we 31 provide guidelines for a robust community cross-validation framework, to use if 32 33 spatial or temporal independent data are unavailable.

3. Our results showed that the selection of the "optimal" assembly strategy mostly 34 depends on the evaluation approach rather than taxa, prevalence distribution, regional 35 species pool or species richness. If evaluated with independent data or reliable cross-36 validation, community-based thresholding seems superior compared to single species 37 optimisation. However, many published studies did not evaluate community 38 projections with independent data, often leading to overoptimistic community 39 evaluation metrics based on single species optimisation. 40 41 **4.** The fact that most of the reviewed S-SDM studies reported over-fitted community

42 evaluation metrics highlights the importance of developing clear evaluation guidelines

- 43 for community models. Here, we move a first step in this direction, providing a
- 44 framework for cross-validation at the community level.

45 INTRODUCTION

Past and future environmental changes may not only lead to shifts in species distributions 46 (e.g., Parmesan & Yohe 2003; Thuiller et al. 2005; Dullinger et al. 2012), but also to changes 47 48 in species assemblages and interactions (e.g., Van der Putten, Macel & Visser 2010; Nogues-Bravo & Rahbek 2011; Blois et al. 2013; Alexander et al. 2016). Information about 49 communities, here defined as a taxonomic assemblage of distinct populations of species that 50 51 co-occur in a given space at a given time (Begon, Harper & Townsend 1996), is therefore essential to make informed decisions for conservation prioritisation (D'Amen et al. 2011; 52 Guisan et al. 2013; Mateo et al. 2013) and to create biodiversity indices (e.g., Essential 53 54 Biodiversity Variables; Pereira et al. 2013) for policy decisions (Fleishman, Noss & Noon 2006; Granger et al. 2015). 55

Different approaches to model communities are available, using either correlative (e.g., 56 Ferrier & Guisan 2006; Guisan & Rahbek 2011) or mechanistic techniques (e.g., Kearney & 57 58 Porter 2009; Mokany & Ferrier 2011), with some predicting only macro-ecological properties 59 such as species richness (e.g., Currie et al. 2004; Gotelli et al. 2009; Dubuis et al. 2011) and others also predicting community composition (see D'Amen et al. 2017b for a review). In this 60 study, we focused on correlative approaches based on individual species distribution models 61 (SDMs), as they are the most common technique applied to conservation strategies (Guisan et 62 al. 2013), and to predict future patterns of biodiversity in the face of global change (Nogues-63 Bravo & Rahbek 2011; D'Amen et al. 2017b). Niche-based SDMs quantify the relationship 64 between available species occurrences and different environmental factors to analyse and 65 predict distributional patterns (Guisan & Thuiller 2005; Elith & Leathwick 2009; Guisan, 66 67 Thuiller & Zimmermann 2017). By additionally stacking individual SDMs (S-SDMs), one can produce spatiotemporal projections of species richness and composition (Ferrier & Guisan 68 2006; Guisan & Rahbek 2011). 69

While there is a vast and now long-standing literature on advances and limitations of single 70 71 species predictions (e.g., Guisan & Thuiller 2005; Guisan et al. 2006; Maggini et al. 2006; Elith & Leathwick 2009; Meier et al. 2010; Zimmermann et al. 2010; Merow et al. 2014), 72 studies exploring how to improve community predictions based on aggregated information 73 74 from individual SDMs emerged more recently (e.g., Mateo et al. 2012; Benito, Cayuela & Albuquerque 2013; Cord et al. 2014; Mod et al. 2015; but see Ferrier et al. 2002). A 75 76 fundamental difference among the proposed solutions is whether to maintain the information on species composition in the final predictions. For instance, the simple sum of probabilities 77 of individual SDM predictions usually gives better estimates of species richness, but the 78 79 information on species identity is lost (Dubuis et al. 2011; Calabrese et al. 2014). Therefore, predictions of community composition have mainly been achieved so far by thresholding the 80 individual continuous SDM predictions (e.g., probability or suitability index) to obtain binary 81 82 maps (Liu, White & Newell 2013) and then stacking the latter at the assemblage level (e.g., Pottier et al. 2013; D'Amen et al. 2015; D'Amen, Pradervand & Guisan 2015). 83 84 There are several examples in the literature of optimizing thresholding methods for single 85 species predictions (e.g., Liu et al. 2005; Jimenez-Valverde & Lobo 2007; Freeman & Moisen 2008; Liu, White & Newell 2013). These led to a mounting consensus about the most 86 87 appropriate methods, with the majority of SDM studies published nowadays using either an approach maximising the true skills statistics (Max.TSS) or based on the curve in a receiver 88 operating characteristic plot (Opt.ROC, related to AUC) (see Guisan, Thuiller & 89 Zimmermann 2017; Table S1). However, the threshold selection can strongly influence the 90 91 reliability of the predicted richness and composition of S-SDMs assemblages (Pineda & Lobo 92 2009; Benito, Cayuela & Albuquerque 2013). It is thus relevant to explore which thresholding approach provides the best performance in assemblage estimates, and if alternatives exist that 93 can improve the assemblage prediction from individual SDMs. 94

95	Studies focussing on S-SDMs tend to over-predict species richness when based on
96	(thresholded) binary predictions (e.g., Pineda & Lobo 2009; Dubuis et al. 2011; Mateo et al.
97	2012; Pottier et al. 2013; Pouteau et al. 2015), with some exceptions (e.g., D'Amen,
98	Pradervand & Guisan 2015; Distler et al. 2015). Different factors have been proposed to
99	explain this over-prediction: (1) a statistical bias in thresholding site-level occurrence
100	probabilities for each species (Calabrese et al. 2014); (2) the implicit assumption of
101	unsaturated communities not assuming an ecological limit for species numbers in assemblages
102	(environmental carrying capacity; Guisan & Rahbek 2011); (3) the lack of considering
103	different constraints on community composition (i.e., ecological, evolutionary, historical, or
104	biological biodiversity drivers; see Mateo, Mokany & Guisan 2017).
105	The commonly used approach to get binary maps from continuous SDM predictions is to use
106	a species-specific threshold, i.e. each species has a single threshold across all sites ("species
107	threshold", Calabrese et al. 2014). Recently, another community-based approach, called
108	probability ranking rule (PRR), was proposed to predict assemblage composition from
109	individual SDMs (D'Amen et al. 2015). This method does not require a species-specific
110	threshold, therefore preventing over-prediction, but site-by-site ecological constraints (e.g.,
111	macro-ecological models) are applied to assemblages to predict species richness ("site-
112	threshold").
113	Surprisingly, studies aiming to test and improve S-SDM have used very different approaches
114	to evaluate the predicted assemblages (Cord et al. 2014; Hespanhol et al. 2015; Pouteau et al.

115 2015; Thuiller *et al.* 2015; Zurell *et al.* 2016) and this evaluation aspect of the community

116 modelling procedure has not yet received all the attention it deserves. In most studies,

assemblage predictions are not adequately evaluated because the data used for the evaluation

118 were already used for individual model fitting, not allowing anymore a correct cross-

119 validation at the community level. Ideally, the best evaluation method should use spatial or

120	temporal independent data (Elith et al. 2006; Guisan, Thuiller & Zimmermann 2017), but if
121	not available, an appropriate cross-validation approach should at least be set up.
122	Here, we used published high-resolution data of insects (butterflies and grasshoppers) and
123	plants (forests and grasslands sites), collected within the same study region to (1) test if the
124	most established thresholding methods for optimal single species prediction (i.e., Max.TSS
125	and Opt.ROC) are also the best choice for species assemblages, (2) investigate if the optimal
126	thresholding method depends on taxa, prevalence distribution (Allouche, Tsoar & Kadmon
127	2006), and/or species richness and (3) provide guidelines for a correct community cross-
128	validation framework, to be used if spatially- or temporally- independent data are unavailable.

129 MATERIALS AND METHODS

130 Community data and environmental variables

131 *Study area*

The data on all taxa were collected within the same study area located in the western Swiss 132 Alps of the canton Vaud (Fig. 1; 46°10′ to 46°30′ N; 6°50′ to 7°10′ E), covering an area of ca. 133 700 km², with elevation ranging from 375 to 3210 m a.s.l. and forested areas up to 1900 m a.s.l. 134 135 For centuries, agriculture (farming and pasturing) has maintained grasslands among forests and altered the position of the treeline. The highly variable topography and diverse land use of the 136 137 study area, in combination with our high-resolution environmental data (25 x 25 m cell size), provide a huge range of complex species-environment relationships to test our modelling 138 framework. 139

140 Plant data

The forest data were part of a forest inventory of the canton Vaud conducted between 1988 and 2002 (mostly 1990 to 1994) and consisted of 3076 sites. The forest sites were distributed on a 400 m grid all across the forested area of the canton and had a circular area of 314 m² (Fig. 1; for details see Hartmann, Fouvy & Horisberger 2009). In total, 703 plant species were recorded, but only 312 (44%) had enough occurrence data (> 20 occurrences) across the dataset for modelling purposes (see Table 1 for more detailed statistics on the datasets).

The grassland dataset was collected between 2002 and 2009 following an equal randomstratified sampling of non-forested areas in the study area. In total, 911 vegetation sites of 4 m² were sampled (Fig. 1; for more information see Dubuis *et al.* 2011). A total of 905 plant species were recorded but only the 212 most frequent (>20 occurrences) were selected for modelling (Table 1).

152 To predict the distribution of the plant species we used five environmental variables: growing

degree-day (above 0 °C), moisture index over the growing season (difference between
precipitation and potential evapotranspiration), the sum of potential solar radiation over the
year, slope (in degrees), and topographic position (unit-less, indicating the ridges and valleys).
All these variables were at a 25 m resolution and have been shown to be useful predictors for
plant species in mountain environments (see Dubuis *et al.* 2011; D'Amen *et al.* 2015; Scherrer *et al.* 2017 for details on predictors).

159 Insect data

160 Data on butterflies and grasshoppers were respectively collected in 192 and 202 squares of 50

m x 50 m across all the elevational range of the study area (Fig. 1; see Pellissier *et al.* 2012;

162 Pradervand *et al.* 2013, for more information). In total, 131 butterfly and 41 grasshopper

species were observed, but due to model limitations only the most common 67 butterfly and

164 20 grasshopper species (>=20 occurrences) were considered for modelling (Table 1).

For our SDMs we used the same predictors as D'Amen, Pradervand and Guisan (2015): four
bioclimatic variables (solar radiation, summer temperature, annual degree-days and annual
average number of frost days during the growing season), an index of vegetation productivity,
i.e. normalized difference vegetation index (as proxies for trophic resources), and the distance
to forest. These variables were selected as they are not highly correlated (<0.7; Dormann *et al.*2013) and considered ecologically important for insects (e.g., Turner, Gatehouse & Corey

171 1987; Hawkins & Porter 2003).

172 The modelling framework

173 Our modelling framework used three different S-SDM based community modelling pathways

174 ("single species cross-validation", "independent data" and "community cross-validation)

175 representing the most commonly reported practices in the literature (see Fig. 2 and

176 "Evaluating community predictions" section).

177 Single species modelling, thresholding and evaluation

Individual species models were run by generalised linear models (GLM; McCullagh & Nelder 178 1989), generalised additive models (GAM; Hastie & Tibshirani 1990), random forest (RF; 179 180 Breiman 2001) and boosted regression trees (BRT; Elith, Leathwick & Hastie 2008). Models for species with more than 50 occurrences were fitted by simple SDMs using all five selected 181 predictors, followed by a weighted (AUC) ensemble forecast (Marmion et al. 2009). Species 182 183 having only between 20 and 50 occurrence records were fitted by an ensemble bivariate approach optimised for rare or under-sampled species (Lomba et al. 2010; Breiner et al. 184 2015): individual models were calibrated on bivariate combinations of the selected predictors 185 186 with all four modelling techniques, followed by a consensus forecast from all the resulting "small models" weighted by their AUC scores. We used a repeated split-sample procedure 187 (N=25) for model evaluation, followed by a weighted (AUC) ensemble forecast (across 188 techniques and split-sample runs). 189

190 The projected probability outputs of the ensemble models were binarised using two 191 thresholding schemes: (1) species-specific-thresholds (a single threshold calculated for each species) and (2) site-specific-thresholds (differing for each site on the basis of additional 192 community information, i.e. species richness predictions). We selected seven different 193 194 species-specific-thresholding techniques, which can be classified in four major groups: singleindex based, sensitivity and specificity combined, model-building data-only-based, and 195 predicted probability-based (see Table S1; Liu et al. 2005; Nenzen & Araujo 2011 for details 196 on classification). As the thresholding techniques showed minimal within-group variance (see 197 Figure S1 and S2), we decided to only present the results for one thresholding technique per 198 199 group in the main manuscript. The chosen techniques were: Cohen's Kappa maximization approach (Max.Kappa; single-index based), TSS maximization approach (Max.TSS, 200 sensitivity and specificity combined), observed prevalence (Obs. Preval; model-building data-201

only-based approach), and average probability approach (AvgProb; predicted probability-202 203 based approach; for details on techniques see Table S1). In addition, we applied two sitethresholds (community-based approaches) using species richness (SR) predictions in 204 205 combination with a probability ranking rule (PRR). These methods selected a number of species equal to the predicted SR on the basis of decreasing probabilities of presence 206 calculated by the SDMs (D'Amen et al. 2015; D'Amen, Pradervand & Guisan 2015). 207 208 Therefore, the species with the highest probabilities in a site are selected (considered present) 209 in decreasing order until the SR predicted for the site is reached. The SR predictions were derived by either summing the per site probabilities of individual SDMs, obtaining a 210 211 prediction of richness for each site (pS-SDM; Dubuis et al. 2011) or by a macro-ecological model (MEM; see D'Amen, Pradervand & Guisan 2015 for details), directly modelling the 212 213 richness of the sites. As results from the two site-thresholds were concordant, we only show 214 here the former (*pS-SDM+PRR*).

To evaluate the threshold independent performance of our individual species models, the area 215 216 under the curve of a Receiver-Operating Characteristic (ROC) plot (AUC; Fielding & Bell 1997) was calculated based on a repeated split sampling cross-validation (Thuiller, Georges & 217 Engler 2013). Additionally, based on our independent/cross-validation data we calculated five 218 219 threshold dependent metrics for each thresholding technique: the overall accuracy (PCC; i.e. proportion of correctly classified presence and absences; Fielding & Bell 1997), sensitivity 220 (proportion of correctly predicted presences), specificity (proportion of correctly predicted 221 absences), the true skill statistic (i.e. [(sensitivity + specificity) -1]; TSS; Allouche, Tsoar & 222 Kadmon 2006) and Cohen's Kappa (Kappa; i.e., overall accuracy but corrected for chance 223 224 performance; Cohen 1968).

225 Evaluating community predictions

All the community predictions were built by stacking binary SDMs of individual species (SSDMs; Dubuis *et al.* 2011; Guisan & Rahbek 2011). The three modelling pathways (Fig. 2)
were identical regarding the modelling procedure for single species, thresholding and
community assemblage and only varied in the selection of the data for community calibration
and evaluation.

The "single species cross-validation" (SSCV) approach (Fig. 2) has not fully 231 232 "unused/independent" data for community evaluation (i.e. sites not used for the calibration of any single species). Here, in the process of the cross-validation of all 233 individual SDMs (i.e. across all species), different sites are selected at each resampling 234 235 iteration and for each species, so that all sites are most likely used in at least one splitsampling run and their information incorporated in the final ensemble model. This 236 approach cannot thus be considered based on fully independent data. The SSCV 237 approach has been to date the most common way to model and evaluate communities 238 predictions based on S-SDMs (Fig. 2; e.g., Dubuis et al. 2011; Calabrese et al. 2014; 239 240 D'Amen, Pradervand & Guisan 2015; Distler et al. 2015). As no independent data is set aside for community evaluation, this approach usually gets evaluated with all the 241 sites used for calibration. However, to avoid bias in the results due to different 242 243 numbers of evaluation sites, we evaluated the SSCV approach only on 30% of the available sites (identical to the ID and CCV approach below). 244 The (spatial or temporal) "independent data" (ID) approach (Fig. 2) starts with two 245 _ completely independent datasets. One is used for the calibration of the SDMs (i.e. 246 247 70% of the sites) and the other set is used (only) to evaluate the performance of the 248 community predictions (i.e. 30% of the sites; Fig 2; e.g., Benito, Cayuela & Albuquerque 2013; Pottier et al. 2013; Cord et al. 2014; D'Amen et al. 2015; Zurell et 249 al. 2016). 250

The "community cross-validation" (CCV) approach (Fig. 2) uses a repeated split 251 252 sampling of sites (100 repetitions) dividing the available sites into calibration (70%) and evaluation sets (30%) to perform all the modelling procedure from the single 253 species prediction to the community assembly (Fig. 2). In contrast to the previous ID 254 pathway (above), which only uses one (spatial or temporal) fixed independent 255 evaluation dataset, in the CCV approach all SDMs are fitted at each split-sample 256 257 iteration using the same training and test sets for all species, thus minimizing the risk of bias in the evaluation data (i.e. if the training and test sets differ across species, as 258 in the ID approach). This repeated cross-validation also allows the 259 260 estimation/simulation of confidence intervals for community predictions instead of just a single value per community. To our knowledge, no study used this community 261 cross-validation method so far. 262 To compare the community model performance among thresholding techniques and 263 modelling pathways, we calculated eight different community agreement metrics: 1) the 264 265 deviation of the predicted from the observed species richness (SR.deviation), 2) the proportion of species correctly predicted as present (community sensitivity), 3) the proportion 266

of species correctly predicted as absent (community specificity), 4) community accuracy

268 (PCC; i.e. the percent correctly classified species, present or absent), 5) the community TSS

269 (here measured for a site across all species, rather than for a species across all sites as in

single SDM evaluation; Pottier *et al.* 2013), 6) the community kappa (same as for TSS, for a

site across species; Pottier *et al.* 2013), and 7) the Sørensen similarity (Sørensen 1948).

272 Correlation of single species and community evaluation metrics

For each combination of dataset, modelling pathway and thresholding method (4 x 3 x 9 =

108) we calculated the average evaluation metric for all five single species metrics and all

seven community metrics. We then calculated the Spearman correlation of all possible

combinations of our five single species and seven community evaluation metrics. The

277 resulting correlation matrix tells us if methods (modelling pathways or thresholding methods)

that yield the highest scores in a certain single species metric also yield the highest score in

the corresponding community evaluation metric.

280 **RESULTS**

281 Performance of individual SDMs

282 As expected the evaluation scores of the individual SDMs were similar to earlier studies published with the same data (D'Amen et al. 2015; D'Amen, Pradervand & Guisan 2015; 283 284 Scherrer et al. 2017) and their performance was not affected by the chosen community evaluation approach (Table 1, Table S3). Despite their differences in site SR, prevalence 285 distribution and species pool the average performance of individual SDMs was similar across 286 287 all taxa (Table 1, Table S3). Additionally, the often reported effect of species prevalence on model performance was only marginal in our study, with rare and common species having 288 similar average model performance within a given taxonomic group (Fig. S3). 289

290 Correlation of single species and community evaluation metrics

291 The correlation between the single species and corresponding community metrics was highest

(cor > 0.93; Table 2) for some combinations of metrics based on partial information from the

contingency table comparing predictions to observations (i.e. PCC, specificity and sensitivity)

and considerably lower for the metrics accounting for all dimensions of the contingency table,

such as TSS and Cohen's Kappa (cor = 0.73; Table 2). Correlations between non-

296 corresponding single species and community metrics (i.e. Sørensen and SR deviation) tended

to be even lower, with the exception of Kappa versus Sørensen (Table 2).

298 Species richness and compositional similarity

The deviation in species richness between observed and predicted communities was strongly 299 300 dependent on the chosen thresholding method (Fig. 3). The thresholding approach that uses the average predicted probability (AvgProb) showed the highest amount of over-prediction 301 302 followed by the combined sensitivity and specificity approach (Max.TSS). The other three thresholding methods (Obs. Preval, Max. Kappa and pS-SDM+PRR) performed very similar 303 and showed overall no tendency to over-predict species richness. There were no significant 304 differences between the three modelling pathways for any of the studied taxa (Fig. 3). The 305 absolute number of over-predicted species was strongly related to the average number of 306 species per plot (SR) and therefore differed among the taxa (Fig. 3). However, when corrected 307 308 for the differences in SR the over-prediction did not significantly vary anymore across taxa. The compositional similarity (Sørensen similarity index) varied significantly both among 309 thresholding techniques and modelling pathways (Fig. 4). The compositional similarity was 310 expectedly always much higher with the "single species cross-validation" (SSCV) pathway 311 compared to the "independent data" (ID) or the "community cross-validation" (CCV) 312 313 pathways, which both performed similarly. There was also a strong interaction between modelling pathway and thresholding technique. Using the SSCV pathway, thresholding by 314 Obs. Preval and by Max. Kappa performed better (Fig. 4). However, if independent sites were 315 316 available for the community evaluations (ID and CCV pathways), the community based approaches (pS-SDM+PRR) performed better than the Obs. Preval and Max. Kappa thresholds 317 (Fig. 4). The similarity between predicted and observed communities was higher in the two 318 insect datasets than in the two plant datasets (Fig. 4), which is likely due to the lower number 319 of insect species compared to plant species modelled. Surprisingly, the most established 320 321 thresholding methods for single species SDMs based on sensitivity and specificity (i.e. Max.TSS, Opt.ROC and SenSpec; Fig. 4 and Fig. S1 and S2) never ranked highest, as one or 322

- more of the other thresholding method always ranked above them, both for community
- 324 composition and for species richness.

325 **DISCUSSION**

326 Do the most established thresholds for single species work as well for community327 predictions?

In this paper, we asked if the most established methods for single species thresholding are 328 also the optimal choice for making predictions at the community level and if there is a direct 329 link between the individual species predictions and the corresponding community metrics. 330 Our results confirm the existence of such a link for single-index based metrics such as 331 sensitivity, specificity and accuracy. However, these results should be interpreted with caution 332 333 as maximising sensitivity or specificity can simply be achieved by predicting the species as present or absent (respectively) everywhere. In our study system, most of the modelled 334 species have a low prevalence (i.e. are absent at most sites), thus accuracy (PCC) can often be 335 improved by predicting the species as "absent" nearly everywhere. 336

The two most commonly used community evaluation metrics, Sørensen similarity index and 337 deviation in species richness, were only weakly correlated with most evaluation metrics used 338 for individual species. The most established thresholding methods for individual species 339 predictions (i.e., Max.TSS, Opt.ROC, SenSpec) did show lower performance when applied to 340 community-level predictions. This is likely due to the fact that both TSS and ROC try to find 341 the best trade-off between sensitivity and specificity (Guisan, Thuiller & Zimmermann 2017). 342 As most of the species have a prevalence far below 50% (i.e., are absent in many more sites 343 than present), adding a few more presences might have a big effect on the sensitivity (by 344 increasing the chance of finding the few real presences) but only marginally affects the 345 specificity. By definition, increasing sensitivity also increases TSS, but with the drawback of 346 a slight over-prediction. While this might not matter much on a single species basis, for 347 community-level predictions the over-prediction will accumulate when summing binarised 348 maps across all species, leading to the often observed over-estimation of species richness in S-349

SDMs (e.g., Pineda & Lobo 2009; Dubuis et al. 2011; Mateo et al. 2012; Pottier et al. 2013; 350 351 Pouteau et al. 2015; Zurell et al. 2016). It is important to remark, that in the rare case of an ecosystem mostly comprising of widespread species (i.e., prevalence >50 %) this will turn 352 353 into the opposite as TSS and ROC will optimise absences leading to an underestimation of species richness. The strength of the over/under prediction bias is therefore linked to the 354 355 prevalence distribution of the modelled species assemblages. However, in the vast majority of 356 natural systems, both the site SR and the regional species pool are driven by a large number of 357 rare (low prevalence species) compared to a few widespread species (Preston 1948; Magurran & Henderson 2003). 358

359 The community-based thresholding methods based on the selection of the most probable species (through a probability ranking) up to the predicted site richness (MEM+PRR, pS-360 SDM+PRR) can overcome this problem, because they are able to constrain species predictions 361 based on a different value of species richness in each site (i.e. making them site-specific 362 thresholding methods). Therefore, these methods prevent over-prediction while still allowing 363 364 the analyses of species composition. Our results thus support the conclusion that, when the final goal is to optimize community composition, community-thresholding methods are the 365 best option. Yet, as discussed in the next section, two single-species thresholding methods – 366 367 maximized Kappa and observed prevalence – also showed good results for predicting communities (close to the community-based approaches). However, as community-based 368 thresholds combine the optimisation of species richness prediction and a probability ranking 369 rule (PRR), they would always select the species with the highest predicted probabilities in 370 371 each site (D'Amen, Pradervand & Guisan 2015). This could seem logic and straightforward, 372 but there might be a bias when the species in the community have varying prevalence (D'Amen et al. 2017a). In fact, the maximum predicted probability is depending on the 373 prevalence of the species, thus the common species will tend to always have greater 374

maximum predicted probabilities than rare species and, as a result, will be considered present
an over-proportionate number of time in the final community compositions. This bias will
produce high similarity scores (Sørensen index) in the prediction evaluation, as the most
common species are correctly predicted in most sites. However, the drawback is that the rarest
species will be often omitted in the community predictions, which can be for instance
problematic if the final goal of the modelling exercise has conservation implications.

381 Is there a "best" threshold for community S-SDMs?

We also tested if different methods for binarising community S-SDMs could be superior 382 depending on the taxonomic group, prevalence distribution or species richness. While we 383 observed significant differences between the different groups (i.e. taxa), there is no simple 384 statistical way to assess if these differences are attributable to the biology of the taxa 385 themselves or simply to the differences in site species richness and prevalence distributions. 386 387 Nevertheless, when we standardized the deviation in species richness by the total number of 388 modelled species (regional species pool), no significant difference was any more visible 389 among the different taxonomic groups. The differences in species richness deviation seem therefore a direct cause of the regional species pool. The same also seems correct for the 390 Sørensen similarity index, as datasets with higher species richness and species pool have 391 392 lower similarity scores. This likely results from the fact that the more species need to be predicted correctly, the more difficult it becomes to predict the whole communities. 393

A similar ranking of thresholding methods was overall observed across taxonomic group within a given modelling pathway, while among the pathways there were clear shifts in the ranking of thresholding methods: with no independent community evaluation data (SSCV), the *Obs.Preval* and *Max.Kappa* threshold showed superior results, while the pathways using independent community evaluation data (ID and CCV) indicated the community-based thresholding to be superior (*pS-SDM+PRR*). This observation is in line with published

literature, where studies not using independent community data usually report a good 400 401 performance of single species optimisations methods (e.g. D'Amen, Pradervand & Guisan 2015; Distler et al. 2015; Thuiller et al. 2015), while studies using independent data usually 402 have better results using community constraints (e.g. D'Amen et al. 2015). Yet, it is 403 remarkable to notice that, although previously much criticized in the literature (e.g., 404 McPherson, Jetz & Rogers 2004; Allouche, Tsoar & Kadmon 2006), maximized Kappa 405 406 (together here with the observed prevalence) did indeed perform well as a thresholding method for predicting both single species and communities, being nearly always superior to 407 the sensitivity-specificity thresholding methods supporting earlier findings of Manel, 408 409 Williams and Ormerod (2001).

It is important to notice that the shift in ranking between modelling pathways was likely due
to a lower degree of overfitting and therefore a lower decrease in performance when
predicting to independent data.

413 Summing up: How to evaluate community predictions correctly?

Our results show that the "single species cross-validation" approach (SSCV), the most 414 commonly used in the literature to evaluate community predictions (e.g., Dubuis et al. 2011; 415 Calabrese et al. 2014; Distler et al. 2015), yields overoptimistic and thus not fully realistic 416 417 measures of predictive power. While this approach is usually able to provide satisfying evaluation for single species, as revealed by the cross-validation of individual species runs, it 418 shows a clear degradation of predictions when measured at the level of communities. This 419 occurs likely because "all" sites are used at least once at some stage across all modelling runs 420 of the split-sampling procedure, and thus no observation (or very few in the best cases) 421 remains fully independent (i.e. unused) for the final evaluation at the community level. 422 Additionally, the sets of training sites used at each run differ among the species, making the 423 results not entirely comparable across species. 424

The second approach found in the literature builds on the first one (SSCV; thus including an 425 426 internal cross-validation evaluation), but uses spatially or temporally independent data (ID) for the assessment (thus an external evaluation), thus (unlike SSCV) using the same set of 427 evaluation sites for all species (e.g., Benito, Cayuela & Albuquerque 2013; Pottier et al. 2013; 428 Cord et al. 2014). When such independent data are available, this method provides the best 429 possible evaluation, provided that the evaluation data are representative of the area where the 430 431 models apply. This approach – with both internal and external evaluation - is also the one considered as optimal in James et al. (2013), and recently promoted in the field of SDMs by 432 Guisan, Thuiller and Zimmermann (2017). 433

434 The third approach (CVV), newly presented here, repeats the ID approach a large number of times within a cross-validation procedure at the community-level (no example of this 435 approach known in the literature). By doing this, the risk of bias in the evaluation data, 436 inherent to the selection of a single evaluation data set, is minimized compared to the simple 437 ID approach. Additionally, the repeated cross-validation allows the assessments of uncertainty 438 439 and confidence intervals around the community predictions' performance metrics. However, 440 as this approach selects the same sites for all species, its application is only possible under specific circumstances. First, all the species data need to be collected in the same sites (i.e. 441 442 true 'community data'). Second, as this approach leads to an unequal number of presences/absences between different cross-validation runs for the same species, it can lead to 443 444 models failing for very rare (low sample size) species in some of the cross-validation runs if not enough presence sites are selected in the training set. 445

According to our results and despite the potential limitations we advise the use of the
proposed community cross-validation approach (CCV) to evaluate community models in
future studies. In fact, we clearly showed that the common practice of evaluating the
community predictions on the same dataset used for calibration process (SSCV) leads to

450 overoptimistic estimations of model performance. In the commonest case of unavailability of 451 truly spatial (i.e., different region) or temporal (i.e., different sampling period) independent 452 data, often independent datasets are "created" by randomly splitting the initial dataset in two 453 parts. However, we advocate against this practise and instead promote the community cross-454 validation approach, which minimizes the artefacts of randomly splitting the initial data and 455 allows the estimation of uncertainty associated with the community evaluation metrics.

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- 465 Authors' contributions
- DS and AG conceived the ideas; RF and MD analysed the plant and insect data; DS and RGM
 developed the modelling framework; DS led the writing and all authors contributed critically
 to the drafts and gave final approval for publication.

469 Data Accessibility

- 470 A generalised version of the community cross-validation algorithm is available in the ecospat
- 471 R package (Cola *et al.* 2016) on GitHub (ecospat.CCV;
- 472 https://doi.org/10.5281/zenodo.1287805). All species and environmental data are available on
- 473 Dryad: <u>https://doi.org/10.5061/dryad.28d4k</u> (Grassland species and environmental predictors
- 474 for plants; Guisan, Dubuis & Vittoz 2011) and https://doi.org/10.5061/dryad.nf925ps (forest,
- 475 insect species and environmental predictors for insects; Guisan *et al.* 2018).

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677 Figure legends

Figure 1: Map of the study area with the forested sites (dark green triangles, N=3076), the
grassland sites (light green circles and red squares, N=903) and the insect sites (red squares,
butterflies N=192, grasshoppers N=202).

Figure 2: The modelling framework illustrating the three different community modelling
approaches: "single species cross-validation" (SSCV), "independent data" (ID) and
"community cross-validation" (CCV).

Figure 3: Deviation in site specific species richness between observations and predictions for the four different datasets (top to bottom) and the three different modelling pathways (left to right). The boxplots are sorted by the median and the colours indicate the different thresholding techniques used to binarise predictions. The line in the box indicates the median, boxes range from the 25th to the 75th percentile and the whiskers indicate ± 2 standard deviations. Letters above the boxplots indicate significant differences (Wilcoxon rank sum test, p < 0.05).

Figure 4: Sørensen similarity between observations and predictions for the four different datasets (top to bottom) and the three different modelling pathways (left to right). The boxplots are sorted by the median and the colours indicate the different thresholding techniques. The line in the box indicates the median, boxes range from the 25th to the 75th percentile and the whiskers indicate ± 2 standard deviations. Letters above the boxplots indicate significant differences (Wilcoxon rank sum test, p < 0.05). 697 Figure 1

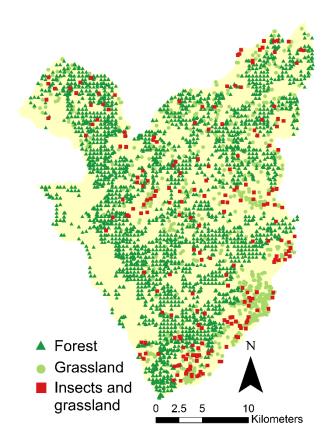
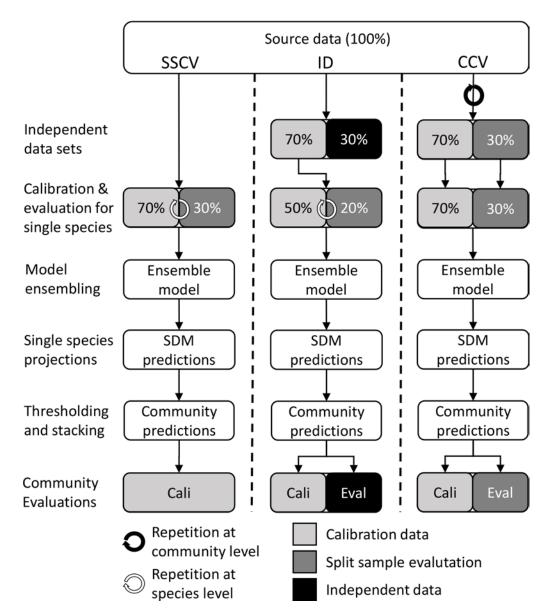


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- 706 "community cross-validation" (CCV).

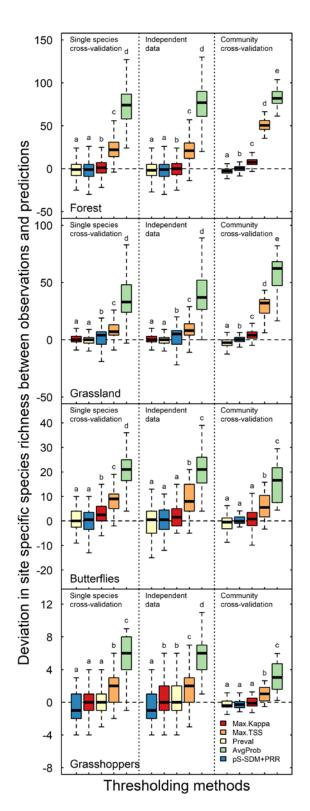


Figure 3: Deviation in site specific species richness between observations and predictions for the four different datasets (top to bottom) and the three different modelling pathways (left to right). The boxplots are sorted by the median and the colours indicate the different thresholding techniques used to binarise predictions. The line in the box indicates the median, boxes range from the 25th to the 75th percentile and the whiskers indicate ± 2 standard deviations. Letters above the boxplots indicate significant differences (Wilcoxon rank sum test, p < 0.05).



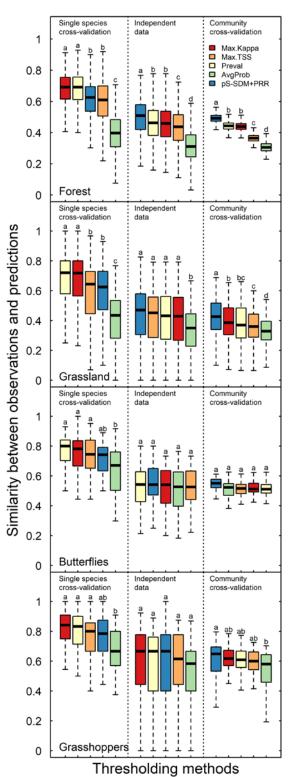


Figure 4: Sørensen similarity between observations and predictions for the four different datasets (top to bottom) and the three different modelling pathways (left to right). The boxplots are sorted by the median and the colours indicate the different thresholding techniques. The line in the box indicates the median, boxes range from the 25th to the 75th percentile and the whiskers indicate \pm 2 standard deviations. Letters above the boxplots indicate significant differences (Wilcoxon rank sum test, p < 0.05). **Table 1:** Basic statistics of the data sets used for the case study and the evaluation metrics (AUC) for the individual species distribution models using the three different community evaluation approaches. SSCV = Single species cross-validation, ID = Independent data, CCV = Community cross-validation

Data set	Number of species modelled (recorded)	Prevalence (mean ± sd)	Species richness (mean ± sd)	AUC SSCV (mean ± sd)	AUC ID (mean ± sd)	AUC CCV (mean ± sd)
Forest	312 (703)	0.044 ± 0.090	29.5 ± 11.8	0.80 ± 0.09	0.80 ± 0.08	0.79 ± 0.09
Grassland	212 (905)	0.098 ± 0.089	23.5 ± 13.8	0.82 ± 0.07	0.83 ± 0.06	0.81 ± 0.06
Butterflies	77 (131)	0.235 ± 0.137	18.1 ± 9.2	0.76 ± 0.10	0.75 ± 0.12	0.76 ± 0.10
Grasshoppers	20 (41)	0.256 ± 0.193	5.1 ± 3.3	0.84 ± 0.07	0.86 ± 0.08	0.84 ± 0.06

Table 2: Pearson Correlation of single species and community evaluation statistics. The asterisks indicate the significance level. Correlations of the single species evaluation metrics and their corresponding community evaluation metric are highlighted in bold.

	Communit	y metrics					
Single species	Accuracy	Sensitivity	Specificity	KAPPA	TSS	Sørensen similarity	SR deviation
Accuracy	1.00 ***	-0.37 *	0.95 ***	0.70 ***	0.37 *	0.37 *	-0.58 ***
Sensitivity	-0.36 **	0.93 ***	-0.54 ***	0.01 n.s.	0.56 ***	0.18 n.s.	-0.44 ***
Specificity	0.97 ***	-0.53 ***	0.99 ***	0.64 ***	0.20 n.s.	0.31 *	-0.63 ***
KAPPA	0.41 **	0.50 *	0.27 *	0.79 ***	0.72 ***	0.82 ***	-0.3 *
TSS	0.06 n.s.	0.85 ***	-0.14 n.s.	0.35 n.s.	0.79 ***	0.38 **	-0.20 n.s.

The asterisks indicate the significance level (n.s.= not significant, * p<0.05, ** p<0.01, *** p<0.001)

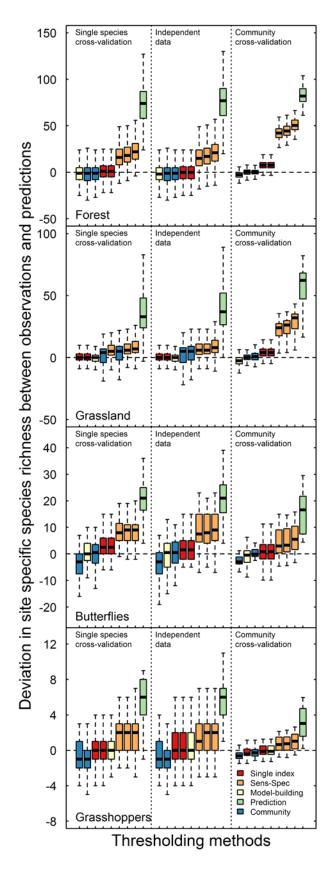


Figure S1: Deviation in site specific species richness between observations and predictions for the four different datasets (top to bottom) and the three different modelling pathways (left to right). The boxplots are sorted by the median and the colours indicate the different thresholding techniques. The line in the box indicates the median, boxes range from the 25th to the 75th percentile and the whiskers indicate ± 2 standard deviations. For details on the method used within each threshold group see Table S1.

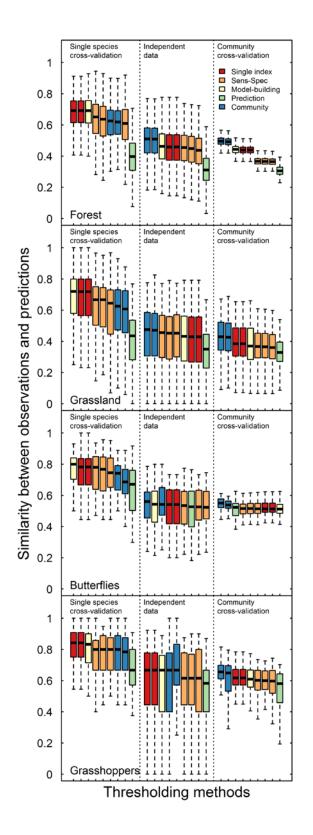


Figure S2: Sørensen similarity between observations and predictions for the four different datasets (top to bottom) and the three different modelling pathways (left to right). The boxplots are sorted by the median and the colours indicate the different thresholding techniques. The line in the box indicates the median, boxes range from the 25th to the 75th percentile and the whiskers indicate \pm 2 standard deviations. For details on the method used within each threshold group see Table S1.

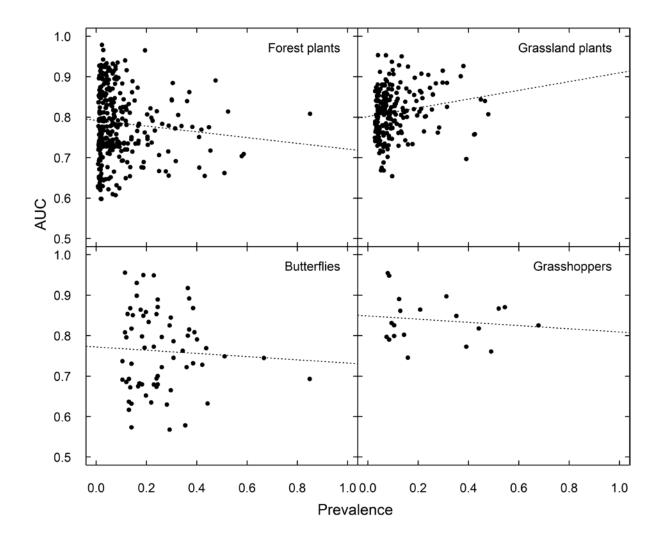


Figure S3: The relationship of the prevalence of a species (i.e., percentage of sites inhabited) to the performance of the SDMs (i.e., as measured by AUC) for the four studied data sets (taxa).

Table S1: Description of the ten thresholding methods based on Liu *et al.* (2005) and Nenzen and Araujo (2011).

Approa	ch	Accronym	Definition	Reference
Single ir	ndex-based approaches			
1.	Kappa maximization approach	Max.Kappa	Kappa statistic is maximized	(Huntley <i>et al.</i> 1995; Guisan, Theurillat & Kienast 1998)
2.	Maximum commission error	MCE05	Allowed a maximum commission error of 5%	(Mateo et al. 2012)
Sensitiv	ity and specificity-combined			
approad	ches			
3.	TSS maximization approach	Max.TSS	TSS statistic is maximized	(Allouche, Tsoar & Kadmon 2006)
4.	Sensitivity-specificity equality approach	SensSpec	Difference of sens-spec is minimized	(Cantor <i>et al.</i> 1999)
5.	ROC plot-based approach	Opt.ROC	ROC statistic is maximized	(Cantor <i>et al.</i> 1999)
Model-l	ouilding data-only-based approach			
6.	Prevalence approach	Preval	Prevalence of the calibration data	(Cramer 2003)
Predicte	ed probability-based approaches			
7.	Average probability approach	AvgProb	Taking the average predicted probability of the model-building data as threshold	(Cramer 2003)
Commu	nity based approaches			
8.	pS-SDM+PRR	pS-SDM+PRR	Probability stacked SDM	(Dubuis <i>et al.</i> 2013)
9.	MEM+PRR	MEM+PRR	Macroecological model for SR	(Guisan & Rahbek 2011)

Metric	Definition
Species richness	
Deviation in species richness	$Dev.SPR = n_{pred} - n_{obs}$
Prediction success	
Sensitivity	$Sens = \frac{TP}{TP + FA}$
Specificity	$Spec = \frac{TA}{TA + FP}$
Community accuracy	$Acc = \frac{TP + TA}{N}$
Community TSS	TSS = Sens + Spec - 1 $Acc - n$
Community Kappa	$K = \frac{Acc - p_e}{1 - p_e}$
Community composition	
Sørensen	$S = \frac{2 * TP}{2 * TP + FP + FA}$
$V_{\text{pred}} = \text{Number of species prediction}$ $V_{\text{obs}} = \text{Number of species observed}$ V = Number of events P = Correctly predicted preseved P = Falsely predicted absenved FA = Falsely predicted absenved FA = Falsely predicted absenved $FA = \frac{(TP + FA)(TP + FP) + (TA + FP)(TA + FP)}{N^2}$	ved nt species nt species species species

Table S2 : Community evaluation metrics used in this study.

2 Table S3 : Evaluation scores of individual SDMs by TSS (A), Kappa (B), PCC (C), Sensitivity (D) and Specificity (E) for the three community

evaluation approaches and four datasets. SSCV = Single species cross-validation, ID = Independent data, CCV = Community cross-validation,
 FO = Forest plants, GL = Grassland plants, BF = Butterflies, GH = Grasshoppers.

5 (A)TSS

Thresholding		SS	CV			I	D			C	CV	
Approach	FO	GL	BF	GH	FO	GL	BF	GH	FO	GL	BF	GH
Max.Kappa	0.2 ± 0.14	0.27 ± 0.2	0.31 ± 0.23	0.42 ± 0.17	0.21 ± 0.17	0.25 ± 0.21	0.3 ± 0.22	0.43 ± 0.26	0.23 ± 0.13	0.28 ± 0.14	0.31 ± 0.18	0.37 ± 0.15
MCE05	0.3 ± 0.17	0.32 ± 0.17	0.27 ± 0.18	0.43 ± 0.16	0.28 ± 0.17	0.34 ± 0.17	0.27 ± 0.23	0.45 ± 0.21	0.25 ± 0.17	0.34 ± 0.12	0.31 ± 0.17	0.42 ± 0.12
Max.TSS	0.35 ± 0.2	0.38 ± 0.14	0.34 ± 0.24	0.47 ± 0.12	0.33 ± 0.22	0.38 ± 0.21	0.34 ± 0.23	0.5 ± 0.26	0.35 ± 0.14	0.39 ± 0.11	0.35 ± 0.18	0.44 ± 0.12
SensSpec	0.32 ± 0.16	0.36 ± 0.14	0.33 ± 0.18	0.51 ± 0.18	0.31 ± 0.2	0.37 ± 0.21	0.34 ± 0.24	0.51 ± 0.26	0.35 ± 0.13	0.38 ± 0.11	0.35 ± 0.18	0.45 ± 0.11
Opt.ROC	0.34 ± 0.21	0.36 ± 0.19	0.33 ± 0.17	0.44 ± 0.26	0.32 ± 0.21	0.37 ± 0.21	0.34 ± 0.23	0.49 ± 0.25	0.35 ± 0.13	0.38 ± 0.11	0.35 ± 0.18	0.44 ± 0.12
Preval	0.18 ± 0.15	0.27 ± 0.15	0.3 ± 0.19	0.41 ± 0.23	0.2 ± 0.16	0.26 ± 0.2	0.31 ± 0.22	0.4 ± 0.23	0.18 ± 0.14	0.23 ± 0.15	0.3 ± 0.17	0.37 ± 0.17
AvgProb	0.43 ± 0.16	0.5 ± 0.12	0.41 ± 0.21	0.55 ± 0.14	0.47 ± 0.16	0.53 ± 0.13	0.38 ± 0.23	0.56 ± 0.15	0.44 ± 0.16	0.49 ± 0.11	0.4 ± 0.18	0.54 ± 0.14
pS-SDM+PRR	0.12 ± 0.19	0.17 ± 0.24	0.28 ± 0.24	0.28 ± 0.22	0.14 ± 0.18	0.2 ± 0.24	0.24 ± 0.24	0.29 ± 0.28	0.14 ± 0.17	0.19 ± 0.21	0.27 ± 0.23	0.27 ± 0.22
MEM+PRR	0.16 ± 0.17	0.2 ± 0.23	0.25 ± 0.24	0.3 ± 0.24	0.14 ± 0.18	0.2 ± 0.24	0.22 ± 0.24	0.32 ± 0.28	0.14 ± 0.17	0.2 ± 0.22	0.25 ± 0.22	0.3 ± 0.22

6

7 (B) KAPPA

Thresholding		SS	CV			I	D			C	CV	
Approach	FO	GL	BF	GH	FO	GL	BF	GH	FO	GL	BF	GH
Max.Kappa	0.2 ± 0.14	0.24 ± 0.18	0.28 ± 0.22	0.35 ± 0.19	0.21 ± 0.15	0.24 ± 0.19	0.29 ± 0.22	0.42 ± 0.25	0.2 ± 0.14	0.24 ± 0.15	0.29 ± 0.18	0.36 ± 0.15
MCE05	0.21 ± 0.13	0.23 ± 0.15	0.24 ± 0.22	0.31 ± 0.16	0.21 ± 0.13	0.28 ± 0.15	0.27 ± 0.22	0.41 ± 0.18	0.11 ± 0.12	0.16 ± 0.14	0.24 ± 0.17	0.32 ± 0.16
Max.TSS	0.19 ± 0.12	0.27 ± 0.17	0.3 ± 0.19	0.4 ± 0.14	0.21 ± 0.14	0.27 ± 0.16	0.3 ± 0.21	0.41 ± 0.23	0.17 ± 0.13	0.22 ± 0.15	0.3 ± 0.17	0.36 ± 0.15
SensSpec	0.21 ± 0.14	0.21 ± 0.17	0.29 ± 0.19	0.41 ± 0.17	0.22 ± 0.14	0.28 ± 0.17	0.3 ± 0.21	0.42 ± 0.23	0.17 ± 0.13	0.23 ± 0.15	0.3 ± 0.17	0.37 ± 0.14
Opt.ROC	0.15 ± 0.15	0.22 ± 0.14	0.32 ± 0.18	0.43 ± 0.17	0.22 ± 0.14	0.27 ± 0.16	0.3 ± 0.21	0.42 ± 0.23	0.17 ± 0.13	0.23 ± 0.15	0.3 ± 0.18	0.37 ± 0.14
Preval	0.2 ± 0.13	0.22 ± 0.18	0.3 ± 0.2	0.34 ± 0.17	0.21 ± 0.15	0.25 ± 0.18	0.3 ± 0.22	0.39 ± 0.22	0.19 ± 0.14	0.23 ± 0.15	0.3 ± 0.17	0.36 ± 0.16
AvgProb	0.17 ± 0.12	0.21 ± 0.14	0.26 ± 0.17	0.38 ± 0.15	0.17 ± 0.13	0.22 ± 0.15	0.26 ± 0.19	0.37 ± 0.18	0.16 ± 0.13	0.22 ± 0.15	0.29 ± 0.16	0.37 ± 0.16
pS-SDM+PRR	0.15 ± 0.16	0.17 ± 0.18	0.26 ± 0.23	0.28 ± 0.25	0.14 ± 0.17	0.18 ± 0.2	0.22 ± 0.23	0.29 ± 0.29	0.14 ± 0.16	0.17 ± 0.19	0.26 ± 0.21	0.28 ± 0.22
MEM+PRR	0.14 ± 0.16	0.17 ± 0.21	0.24 ± 0.22	0.32 ± 0.26	0.14 ± 0.17	0.18 ± 0.2	0.22 ± 0.23	0.34 ± 0.29	0.15 ± 0.16	0.19 ± 0.19	0.25 ± 0.21	0.32 ± 0.22

9 C) Percentage correct classified (PCC)

Thresholding		SS	SCV				ID			C	CV	
Approach	FO	GL	BF	GH	FO	GL	BF	GH	FO	GL	BF	GI
Max.Kappa	0.91 ± 0.09	0.9 ± 0.07	0.78 ± 0.1	0.83 ± 0.08	0.9 ± 0.09	0.89 ± 0.07	0.77 ± 0.09	0.83 ± 0.1	0.88 ± 0.09	0.87 ± 0.06	0.76 ± 0.08	0.82 ±
MCE05	0.85 ± 0.15	0.79 ± 0.07	0.66 ± 0.11	0.82 ± 0.08	0.88 ± 0.07	0.87 ± 0.05	0.77 ± 0.09	0.82 ± 0.08	0.59 ± 0.14	0.68 ± 0.09	0.64 ± 0.1	0.73 ±
Max.TSS	0.85 ± 0.08	0.84 ± 0.07	0.73 ± 0.11	0.83 ± 0.09	0.86 ± 0.1	0.85 ± 0.08	0.73 ± 0.11	0.81 ± 0.09	0.77 ± 0.07	0.79 ± 0.05	0.72 ± 0.08	0.79 ±
SensSpec	0.79 ± 0.1	0.84 ± 0.04	0.73 ± 0.09	0.81 ± 0.08	0.87 ± 0.09	0.86 ± 0.07	0.73 ± 0.1	0.81 ± 0.08	0.79 ± 0.07	0.81 ± 0.05	0.73 ± 0.07	0.8 ± 0
Opt.ROC	0.86 ± 0.08	0.86 ± 0.06	0.72 ± 0.11	0.82 ± 0.05	0.87 ± 0.1	0.86 ± 0.07	0.74 ± 0.1	0.81 ± 0.09	0.79 ± 0.07	0.81 ± 0.05	0.73 ± 0.08	0.8 ± 0
Preval	0.92 ± 0.08	0.91 ± 0.05	0.79 ± 0.08	0.83 ± 0.06	0.9 ± 0.08	0.89 ± 0.06	0.77 ± 0.1	0.83 ± 0.09	0.9 ± 0.08	0.89 ± 0.06	0.77 ± 0.08	0.82 ±
AvgProb	0.71 ± 0.07	0.67 ± 0.08	0.64 ± 0.11	0.74 ± 0.08	0.69 ± 0.08	0.69 ± 0.07	0.64 ± 0.11	0.73 ± 0.08	0.69 ± 0.07	0.69 ± 0.07	0.66 ± 0.09	0.73 ±
pS-SDM+PRR	0.93 ± 0.09	0.88 ± 0.07	0.76 ± 0.08	0.86 ± 0.09	0.91 ± 0.1	0.89 ± 0.08	0.77 ± 0.11	0.83 ± 0.1	0.91 ± 0.1	0.89 ± 0.08	0.78 ± 0.09	0.84 ±
MEM+PRR	0.92 ± 0.1	0.9 ± 0.09	0.8 ± 0.09	0.84 ± 0.09	0.91 ± 0.1	0.89 ± 0.09	0.79 ± 0.1	0.86 ± 0.08	0.91 ± 0.1	0.89 ± 0.08	0.79 ± 0.08	0.86 ±

12 D) Sensitivity

Thresholding		S	SCV			1	ID		CCV				
Approach	FO	GL	BF	GH	FO	GL	BF	GH	FO	GL	BF	GH	
Max.Kappa	0.31 ± 0.18	0.36 ± 0.24	0.47 ± 0.21	0.51 ± 0.26	0.27 ± 0.21	0.32 ± 0.25	0.46 ± 0.24	0.56 ± 0.26	0.32 ± 0.18	0.37 ± 0.18	0.5 ± 0.2	0.52 ± 0.22	
MCE05	0.45 ± 0.13	0.61 ± 0.11	0.66 ± 0.18	0.73 ± 0.12	0.35 ± 0.17	0.42 ± 0.17	0.42 ± 0.23	0.57 ± 0.19	0.68 ± 0.05	0.67 ± 0.07	0.7 ± 0.09	0.71 ± 0.11	
Max.TSS	0.44 ± 0.28	0.55 ± 0.15	0.62 ± 0.14	0.67 ± 0.15	0.46 ± 0.28	0.52 ± 0.27	0.59 ± 0.22	0.66 ± 0.25	0.57 ± 0.11	0.59 ± 0.11	0.61 ± 0.14	0.63 ± 0.15	
SensSpec	0.55 ± 0.25	0.49 ± 0.15	0.58 ± 0.18	0.65 ± 0.13	0.42 ± 0.26	0.49 ± 0.25	0.58 ± 0.22	0.67 ± 0.25	0.54 ± 0.1	0.55 ± 0.11	0.58 ± 0.14	0.63 ± 0.12	
Opt.ROC	0.44 ± 0.2	0.54 ± 0.14	0.57 ± 0.21	0.67 ± 0.14	0.44 ± 0.26	0.49 ± 0.26	0.58 ± 0.22	0.65 ± 0.24	0.55 ± 0.1	0.56 ± 0.11	0.59 ± 0.14	0.62 ± 0.14	
Preval	0.28 ± 0.17	0.28 ± 0.21	0.46 ± 0.21	0.55 ± 0.25	0.26 ± 0.2	0.32 ± 0.24	0.49 ± 0.22	0.53 ± 0.25	0.24 ± 0.18	0.29 ± 0.18	0.47 ± 0.19	0.5 ± 0.23	
AvgProb	0.76 ± 0.11	0.82 ± 0.1	0.77 ± 0.12	0.83 ± 0.1	0.79 ± 0.11	0.85 ± 0.1	0.78 ± 0.17	0.85 ± 0.13	0.76 ± 0.1	0.81 ± 0.06	0.78 ± 0.1	0.84 ± 0.07	
pS-SDM+PRR	0.21 ± 0.28	0.26 ± 0.32	0.43 ± 0.36	0.42 ± 0.39	0.21 ± 0.28	0.28 ± 0.33	0.44 ± 0.36	0.45 ± 0.4	0.21 ± 0.27	0.26 ± 0.3	0.45 ± 0.33	0.41 ± 0.36	
MEM+PRR	0.21 ± 0.28	0.3 ± 0.31	0.38 ± 0.36	0.41 ± 0.38	0.21 ± 0.29	0.28 ± 0.33	0.38 ± 0.35	0.43 ± 0.38	0.21 ± 0.27	0.28 ± 0.3	0.39 ± 0.32	0.42 ± 0.34	

16 E) Specificity

Thresholding		SS	SCV			1	ID			C	CV	
Approach	FO	GL	BF	GH	FO	GL	BF	GH	FO	GL	BF	GH
Max.Kappa	0.95 ± 0.09	0.91 ± 0.07	0.82 ± 0.12	0.87 ± 0.1	0.94 ± 0.07	0.93 ± 0.07	0.84 ± 0.12	0.88 ± 0.1	0.91 ± 0.09	0.93 ± 0.07	0.81 ± 0.12	0.85 ± 0.1
MCE05	0.87 ± 0.15	0.81 ± 0.04	0.78 ± 0.11	0.79 ± 0.09	0.93 ± 0.03	0.91 ± 0.03	0.86 ± 0.1	0.88 ± 0.08	0.57 ± 0.15	0.91 ± 0.03	0.61 ± 0.13	0.7 ± 0.1
Max.TSS	0.88 ± 0.09	0.79 ± 0.07	0.73 ± 0.1	0.83 ± 0.09	0.87 ± 0.1	0.86 ± 0.09	0.75 ± 0.13	0.84 ± 0.09	0.78 ± 0.08	0.86 ± 0.09	0.74 ± 0.1	0.8 ± 0.08
SensSpec	0.89 ± 0.07	0.82 ± 0.06	0.77 ± 0.1	0.81 ± 0.09	0.89 ± 0.09	0.88 ± 0.07	0.75 ± 0.12	0.84 ± 0.09	0.81 ± 0.07	0.88 ± 0.07	0.76 ± 0.09	0.82 ± 0.07
Opt.ROC	0.84 ± 0.08	0.87 ± 0.08	0.74 ± 0.11	0.82 ± 0.09	0.88 ± 0.09	0.88 ± 0.08	0.76 ± 0.13	0.84 ± 0.09	0.8 ± 0.07	0.88 ± 0.08	0.76 ± 0.09	0.82 ± 0.07
Preval	0.92 ± 0.07	0.95 ± 0.05	0.85 ± 0.13	0.85 ± 0.09	0.94 ± 0.08	0.94 ± 0.06	0.82 ± 0.13	0.87 ± 0.11	0.94 ± 0.08	0.94 ± 0.06	0.84 ± 0.11	0.87 ± 0.09
AvgProb	0.69 ± 0.08	0.68 ± 0.06	0.63 ± 0.12	0.72 ± 0.09	0.68 ± 0.08	0.68 ± 0.07	0.6 ± 0.12	0.71 ± 0.09	0.68 ± 0.08	0.68 ± 0.07	0.62 ± 0.09	0.69 ± 0.08
pS-SDM+PRR	0.92 ± 0.15	0.91 ± 0.12	0.81 ± 0.19	0.86 ± 0.19	0.93 ± 0.15	0.92 ± 0.12	0.8 ± 0.23	0.84 ± 0.21	0.93 ± 0.14	0.92 ± 0.12	0.82 ± 0.19	0.86 ± 0.13
MEM+PRR	0.93 ± 0.14	0.93 ± 0.1	0.85 ± 0.18	0.91 ± 0.15	0.93 ± 0.15	0.92 ± 0.13	0.85 ± 0.2	0.89 ± 0.16	0.93 ± 0.14	0.92 ± 0.13	0.86 ± 0.17	0.88 ± 0.1