

University of Nebraska - Lincoln  
**DigitalCommons@University of Nebraska - Lincoln**

---

Faculty Papers and Publications in Animal Science

Animal Science Department

---

2010

# Multi-Robot System Control Architecture (MRSCA) for Agricultural Production

Santosh Pitla

*University of Nebraska-Lincoln*, [spitla2@unl.edu](mailto:spitla2@unl.edu)

Joe D. Luck

*University of Nebraska-Lincoln*, [jluck2@unl.edu](mailto:jluck2@unl.edu)

Scott A. Shearer

*University of Kentucky*, [Scott.A.Shearer@uky.edu](mailto:Scott.A.Shearer@uky.edu)

Follow this and additional works at: <https://digitalcommons.unl.edu/animalscifacpub>

---

Pitla, Santosh; Luck, Joe D.; and Shearer, Scott A., "Multi-Robot System Control Architecture (MRSCA) for Agricultural Production" (2010). *Faculty Papers and Publications in Animal Science*. 927.

<https://digitalcommons.unl.edu/animalscifacpub/927>

This Article is brought to you for free and open access by the Animal Science Department at DigitalCommons@University of Nebraska - Lincoln. It has been accepted for inclusion in Faculty Papers and Publications in Animal Science by an authorized administrator of DigitalCommons@University of Nebraska - Lincoln.

"Multi-Robot System Control Architecture (MRSCA) for Agricultural Production" (MS #1064) has been posted to Conference Presentations and White Papers: Biological Systems Engineering.

<https://digitalcommons.unl.edu/biosysengpres/64>