# Acoustic Streaming in a Soft Tissue Microenvironment

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# 1 ABSTRACT

2 We demonstrate that sound can push fluid through a tissue-mimicking material. 3 Although acoustic streaming in tissue has been proposed as a mechanism for biomedical 4 ultrasound applications, such as neuromodulation and enhanced drug penetration, no direct observation of streaming in tissue or acoustic phantoms has been observed. We 5 6 developed a material that mimics the porous structure of tissue and used a dye and a video camera to track fluid movement. When applied above an acoustic intensity threshold, a 7 continuous focused ultrasound beam (spatial peak time average intensity: 238 W/cm<sup>2</sup>, 8 9 centre frequency: 5 MHz) was shown to push the dye axially i.e. in the direction of wave 10 propagation and in the radial direction. Dye clearance increased with ultrasound intensity 11 and was modelled using an adapted version of Eckart's acoustic streaming velocity equation. No microstructural changes were observed in the sonicated region when 12 13 assessed using scanning electron microscopy. Our study shows that acoustic streaming 14 can occur in soft porous materials and provides a mechanistic basis for future using 15 streaming for therapeutic or diagnostic purposes.

16 *Keywords*: acoustic streaming; porous materials; drug delivery; focused ultrasound.

### 1 INTRODUCTION

2 Acoustic streaming (Lighthill 1978; Nyborg 1953) - the bulk steady fluid 3 movement generated by the propagation of sound – has been proposed as the mechanism of material displacement for biomedical applications, such as the enhancement of drug 4 5 penetration (Nieminen et al. 2012; Nieminen et al. 2015), promotion of angiogenesis 6 (Young and Dyson 1990), enhancement of tissue repair (Speed 2001), stimulation 7 (Bystritsky et al. 2011; Tyler 2011) and prenatal migration of neurons (Ang et al. 2006). However, a mechanistic link between acoustic streaming and each bioeffect has not yet 8 9 been established. This is in part due to the lack of any direct observation or measurement of acoustic streaming in soft tissues or porous materials, and whether this is even possible 10 11 has yet to be shown.

12 Flow generated in a free fluid by a sound beam has been described in theoretical and experimental work (Eckart 1948; Lighthill 1978; Nyborg 1953; Westervelt 1953). 13 14 When an ultrasonic beam propagates through an unbounded liquid, a transfer of acoustic momentum from the beam to the fluid particles occurs. Fluid viscosity, heat transfer and 15 16 relaxation processes lead to a reduction of the beam's pressure amplitude, and thus its intensity, with increasing distance from the sound source. Therefore, the momentum 17 transferred to the fluid also decreases with increasing depth. Consequentially an energy 18 19 density gradient is established, which in turn causes a net force acting on the fluid. This 20 force, also known as acoustic radiation force (ARF), generates acoustic streaming when applied onto fluid (Lighthill 1978). The applied ARF increases with the sound intensity 21 22 and the material's acoustic absorption property, which is in turn dependent on the sound centre frequency and material's fluid viscosity. It has been shown that focused ultrasound 23 (FUS) can generate streaming velocities up to several cm/s in free fluid close to the 24 geometric focus in the direction of propagation (Starritt et al. 1989). 25

Acoustic streaming has been proposed as a mechanism for many therapeutic 1 2 bioeffects, because it could explain the net movement of a material (e.g., a drug) in a fluid 3 in a single direction (e.g., the direction of wave propagation), which was observed in many studies in post-mortem analyses. This directional bias contrasts with temperature 4 dependent diffusion where molecular movement occurs in all directions. In studies of 5 6 articular cartilage exposed to FUS (Nieminen et al. 2012; Nieminen et al. 2015), a net 7 maximum displacement of an injected drug was observed at the focus in the direction of 8 wave propagation. In other applications, such as neuromodulation (Bystritsky et al. 2011) 9 and bone healing (Romano et al. 2009), although a net unidirectional fluid movement was 10 not observed, such an effect could have led to the resulting biological response. However, even when a net displacement of a fluid is observed after ultrasound exposure, it does not 11 12 rule out other potential mechanisms of fluid movement. For example, ultrasound can nucleate bubbles and drive the bubbles into a dynamic range of behaviours that lead to a 13 14 net displacement of fluid (e.g., primary Bjerknes force) (Apfel 1997; Bjerknes 1906). It 15 has been shown that cavitation can enhance skin permeability for drug delivery (Ogura et al. 2008) and create tunnels in gel phantoms (Caskey et al. 2009). Currently, there is no 16 quantification of acoustic streaming in soft tissue 17 direct observation or microenvironments. 18

We hypothesized that acoustic streaming can be generated within soft porous material microenvironments. This hypothesis was evaluated by developing a suitable soft tissue phantom material and experimental methods that allowed for the direct optical observation of fluid movement through the phantom. Moreover, the resulting acoustic streaming was modelled using an adapted version of Eckart's acoustic streaming velocity equation. Our study shows that acoustic streaming can occur in soft porous materials and provides a mechanistic basis for future studies using streaming for therapeutic or
 diagnostic purposes.

Manufacturing and characterisation of tissue-mimicking materials

3

### 4 MATERIALS AND METHODS

### 5

We created three phantoms - gelatin, polyacrylamide, and a macroporous 6 7 polyacrylamide (MPPa) hydrogel (Plieva et al. 2006). The gelatin phantom was prepared by dissolving 5 g of gelatin powder (Fisher Scientific, Loughborough, UK) in 100 ml of 8 9 water heated to 40 °C. The solution was then allowed to set overnight in a fridge. The polyacrylamide hydrogel was prepared using 5 g of acrylamide monomer, 0.1 g of N,N'-10 11 methylene-bis-acrylamide (BIS), 0.06 g of ammonium persulfate (APS) and 94 µL of N,N,N',N'-tetramethylethylenediamine (TEMED) mixed in a 100 ml solution. The BIS 12 13 crosslinked the monomers while APS and TEMED initiate the polymerization process. The gel was left to set at room temperature for 15 - 20 minutes. Macroporous 14 polyacrylamide (MPPa) was prepared using the freezing before gelation process. The 15 MPPa phantom was prepared using 10 g of Acrylamide monomer, 0.2 g of BIS, 0.12 g of 16 APS, 2 mL of allyl glycidyl ether (AGE) and 200 µL of TEMED mixed in a 200 ml 17 solution. The compounds for the polyacrylamide and MPPa gels were from Sigma-18 Aldrich Company Ltd., Dorset, UK. The solution was then degassed and slowly poured 19 20 into four 50 mL cylindrical containers. The containers were then placed in a freezer at -20 °C; this process allowed the gel to polymerize around the frozen water crystals, i.e., 21 freezing before gelation. The containers including the materials were left in the freezer 22 23 for 16 hours. The containers were then removed from the freezer, washed and kept in an oven at 60 °C for 8 hours. The dry samples were taken out of the containers and measured 24

for their weight and volume. The samples were then swelled in water for a few minutes 1 2 and measured again for their weight and volume. The mass and volume swelling percentages for the MPPa gels were 98  $\pm$  12 % and 95  $\pm$  17 %, respectively. Scanning 3 electron microscopy (SEM) and mercury intrusion porosimetry (MIP) of gelatin, 4 5 polyacrylamide and MPPa were performed using a scanning electron microscope (JSM5610LV Jeol, Peabody, MA, USA) and an automated mercury porosimeter 6 7 (AutoPore IV 9500 Series Micromeritics, Norcross, GA, USA) respectively. SEM 8 evaluates the hydrogel's structure qualitatively and MIP measures the pore size distributions based on the constrictions on mercury flow through the sample. 9

10

# Experimental setup and acoustic measurements

A 5 MHz spherical-segment, single-element transducer (diameter: 33 mm, focal 11 length: 35 mm; SU-108 Sonic Concepts, Bothell, WA, USA) was used to emit focused 12 ultrasound pulses. The full width at half maximum (FWHM) focal diameter and length 13 of the ultrasound beam were 0.45 and 3.2 mm, respectively. Pressure calibrations, focal 14 15 point location, and FWHM beam measurements were performed in a degassed water tank 16 using a 200 µm diameter polyvinylidene fluoride (PVDF) needle hydrophone (Precision Acoustics Ltd, Dorchester, UK) for peak-negative pressures up to 1 MPa. The water was 17 18 degassed using two filters and a membrane contactor (MiniModule, Liqui-Cel, Charlotte, 19 NC, USA) for two hours. The higher pressures and intensities reported for the parameters 20 used were simulated using a HIFU simulation tool based on the geometry of the transducer and setup, attenuation of the MPPa gel and acoustic power transmitted from 21 22 the ultrasound transducer. The tool (a propagation module, which solves the Khokhlov-23 Zabolotskaya-Kuznetsov (KZK) equation) simulated asymmetric nonlinear waves in an attenuating medium (Soneson and Ebbini 2009). 24

A dye of 0.025 ml from a 0.1% Bromophenol blue solution was injected into the 1 2 MPPa gel surface over 0.45 seconds using a 1 mL needle-less syringe and a syringe pump 3 (Harvard Apparatus PHD Ultra, Holliston, MA, USA), which was set to the maximum constant flow rate of 3.3 ml/min. The MPPa hydrogel was then immersed in a degassed 4 5 water tank that was previously heated to 37°C. The MPPa surface was placed 35 mm away from the transducer's surface and overlapped with the transducer's focal point. The 6 focal point of a FUS transducer was placed to overlap with the region injected with the 7 8 dye (Fig.1). Axially, it was placed at the distal end of each hydrogel's surface so that the proximal half of the focal volume was in the phantom and the distal half was in the water. 9 A function generator (33500B Series, Agilent technologies, Santa Clara, CA, USA) 10 produced continuous 30 second pulses that were transmitted through a 50 dB power 11 12 amplifier (2100L, E&I Ltd, Rochester, NY, USA) and to the 5 MHz transducer. Three 13 different sets of ultrasound parameters [peak-negative pressure  $(p_n)$ : 2.6, 4.7, and 6.2 MPa, peak-positive pressure  $(p_p)$ : 3.1, 7.3 and 12.0 MPa, spatial peak time average 14 intensity (I<sub>SPTA</sub>): 238, 972 and 2002 W/cm<sup>2</sup>, duration: 30 s] were evaluated in our 15 16 experiments.

Dye clearance was captured with a camera (frame rate: 60 Hz, field of view:
18 1980×1080 pixels, model: Nikon 1 V3, Nikon Inc., USA). The camera was used with a
19 lens (focal length: 10-100mm, zoom ratio: 10:1, model: 1 NIKKOR 10-100mm f/4.0-5.6
20 VR, Nikon Inc., USA) and two magnifying glasses (zoom ratio: 6:1) (Fig.1).

Determination of the samples where the ultrasound beam was accurately placed on the dye-infused hydrogel region was evaluated using a quantitative exclusion criterion. After every sonication, the same hydrogel region was sonicated using a high acoustic intensity that was known to produce dye clearance. Accurate targeting was determined if the dye clearance occurring occurred in an area within 50% of the peak optical intensity. The parametric study was randomized such that 5 samples of MPPa hydrogels were used
 for every ultrasound exposure parameter and the control (no ultrasound). The 5 samples
 were produced from 3 different MPPa batches.

4 Analysis of raw videos

All images and raw video frames were processed and analysed using Matlab. The 5 6 dye clearance was measured by image processing of the captured video data. A spatial disk filter of radius 5 pixels and a moving average filter of 5 frames was used to smooth 7 8 the raw data. The spatial resolution was approximately 10  $\mu$ m/pixel. In order to visualise 9 the dye clearance, we subtracted each image frame after the start of sonication from the 10 first (reference) frame. The dye clearance is the mean average intensity of the pixels in 11 the FWHM of the focal region and was tracked over 1800 frames or 30 s. The dye 12 clearance is denoted in optical intensity units, a dimensionless quantity denoting the intensity value per pixel in a grayscale frame or image. 13

14 Average velocity estimation

The calculation of steady state velocities of the developed flow in the MPPa gel 15 16 were obtained using a model derived from Eckart's solution. To estimate the acoustic 17 streaming velocity induced by an ultrasound beam, the characteristics of both the sound 18 field and the sonicated material was considered. The hydrogel phantom was modelled as a porous material with the dynamic properties of a viscoelastic fluid. In this case, the 19 20 microenvironment of the sample was characterized by its average pore diameter  $\Phi$ , its 21 porosity  $\varepsilon$  and its permeability  $\kappa$ . These parameters were material specific and were 22 estimated using MIP.

We assumed that the ARF generating the acoustic streaming has a component acting in the axial direction and radial force was assumed to be to zero (Kamakura et al. 1995). In addition, only the momentum transferred to the volume occupied by fluid
 caused acoustic streaming and zero impedance mismatch between the fluid and the MPPa
 hydrogel (Prokop et al. 2003). Laminar flow was induced, boundary effects at the pore
 walls were neglected and thermal equilibrium existed (i.e. there was no energy loss due
 to heating).

6 Acoustic streaming is a direct result of an ARF acting on the fluid. The magnitude 7 and direction of the force field generating the flow is in turn dictated by the shape of the ultrasound beam. Therefore, knowing the spatial distribution of the sound field is a 8 9 prerequisite for any subsequent velocity estimation. In this study, we only considered the sound field generated by a focused single-element transducer. Its radiating surface was 10 11 approximated as a segment of a sphere with disk radius a and a geometrical focus at distance d. The ARF acting along the beam axis  $F_z$ , was modelled using the following 12 equation (Kamakura et al. 1995): 13

14 
$$F_z = \frac{\alpha}{(\rho_0 c_0)^2} \frac{P_p^2}{f^2(z)} e^{-2\alpha z}$$
(1)

15 with

16 
$$f(z) = \sqrt{\left(1 - \frac{z}{d}\right)^2 + \frac{z^2}{z_{diff}^2}}, \ z_{diff} = \frac{\pi a^2}{\lambda}$$
 (2)

17 Here,  $\alpha$  is the attenuation coefficient of the liquid phase,  $\rho_0$  is the fluid density, 18  $c_0$  is the speed of sound within the fluid and  $P_p$  is the peak pressure at the focus of the 19 ultrasound beam.  $z_{diff}$  is the characteristic length of diffraction or Rayleigh length.

After defining the force field of the ARF, the steady state velocity of the fully developed flow in a porous medium was approximated using a model derived from Eckart's solution (Eckart 1948) to the acoustic streaming problem. Eckart considered the second-order, incompressible bulk-driven flow generated by an unfocused beam of sound travelling through an infinitely long cylinder of radius  $r_c$  with non-reflecting walls and derived a model for the flow vorticity giving the streaming velocity U as:

4 
$$U = A \begin{cases} \frac{1}{2} \left( 1 - \frac{x^2}{y^2} \right) - \left( 1 - \frac{1}{2} y^2 \right) (1 - x^2) - \log y & 0 \le x \le y \\ - \left( 1 - \frac{1}{2} y^2 \right) (1 - x^2) + \log x & y \le x \le 1 \end{cases}$$
(3)

$$A = \frac{r_b^2}{\mu} \frac{\alpha P_0^2}{2\rho_0 c_0^2} = \frac{r_b^2}{\mu} \frac{\alpha I}{c_0}, \qquad x = \frac{r}{r_c}, \qquad y = \frac{r_b}{r_c}$$
(4)

5

where r<sub>b</sub> is the radius of the sound beam, r is the distance from the centre axis of the
beam, P<sub>0</sub> is the peak sound pressure at the transducer surface, I is the sound intensity, α
is the coefficient of attenuation, µ is the fluid viscosity and c<sub>0</sub> is the speed of sound in the
fluid. A is the ratio of the generated ARF and the viscous damping of the fluid. Evidently,
Eckart's equation coincides with the theoretical prediction in which the acoustic streaming
velocity is proportional to α and inversely proportional to µ.

12 Equation 3 only describes the bulk flow induced when plane waves traverse an 13 attenuating open fluid body (i.e.  $r_c$  > beam diameter). In contrast, this study is interested in the second-order flow generated by a focused ultrasound beam within a porous 14 medium. Therefore, eqn. 3 had to be adapted to the systems geometry and beam shape. 15 16 The following model was proposed to describe the axial streaming velocity generated in 17 a medium with porosity  $\varepsilon$ , permeability  $\kappa$ , and pore diameter  $\Phi$ . Equation 5 corresponds to a volume-averaged Poiseuille flow through a channel filled with a porous medium. 18 Substituting  $P_0$  in eqn. 3 by eqn. 1 incorporated the spatial changes in pressure amplitude 19 20 and characteristic beam width due to focusing. The systems geometry was taken into 21 account by the two factors  $\varepsilon$ , considering for the stationary proportion of the medium not 22 contributing to the streaming velocity, and  $\cos \theta$ . The latter accounts for the reduction in 1 axial fluid velocity due to the internal geometry. Its necessity arises from the assumption 2 that the force is only acting in the axial direction, *i.e.*  $F_r = 0$ . To consider the influence of 3 the channel size on the flow velocity, the inclusion of an additional term,  $\Phi/r_b$  is used. 4 This material specific parameter took the relative size of the pore-channels  $\Phi$  to the beam 5 width  $r_b$  into account. However, this parameter was ad-hoc and its justification needed to 6 be experimentally verified.

7 
$$U_{z,s} = \epsilon \frac{\Phi}{r_b} \frac{\kappa}{\mu} \frac{\alpha P_p^2}{2\rho_0 c_0^2} \frac{1}{f^2(z)} e^{-2\alpha z} \cos(\theta) \quad (5)$$

Equation 5 only described the case where  $\Phi < r_b$ . For  $\Phi > r_b$  eqn. 3 holds. Furthermore, we assumed a one-dimensional flow field of streaming induced within straight non-interacting channels. This contradicted the expectation for the flow pattern in media consisting of interconnected channels such as the MPPa samples. In this case, the channel geometry hindered the fluid to flow along straight lines and a radial velocity component ensued even though radial force was equal to zero. This led to a reduction in axial streaming velocity compared to the case of straight non-interacting channels.

### 15 Statistical analysis

16 Statistical tests were performed to ensure statistical significance of our results. 17 The maximum dye clearance for the different ultrasound exposure levels and control were 18 compared using a one-way analysis of variance (ANOVA) with multiple comparison test. 19 The significance levels adopted were p < 0.05, p < 0.01 and p < 0.001.

20

# 21 **RESULTS**

# 22 A tissue-mimicking material for acoustic streaming

When designing a material to test acoustic streaming, we considered tissue-1 2 mimicking phantoms often used for ultrasound imaging or therapy studies (Culjat et al. 2010). However, although these materials mimicked the acoustic properties well, they did 3 4 not necessarily mimic the fluid microenvironment that would be present in soft tissue. Scanning electron microscopy was used to image the pores that remain following freeze 5 6 drying of the gels, to estimate the gel network and fluid pathways of the hydrated gel. The 7 SEM images showed that while the gelatin and polyacrylamide networks were porous, 8 the pores were not well connected so fluid transport was likely to be hampered by walls 9 of material [Fig. 2(a) and 2(b)]. For gelatin, polyacrylamide and MPPa, MIP showed that the size of interconnecting pores were  $0.22 \pm 0.11 \,\mu\text{m}$ ,  $0.21 \pm 0.14 \,\mu\text{m}$  and  $33 \pm 7.7 \,\mu\text{m}$ , 10 respectively supporting the SEM findings. We deduced that acoustic streaming with 11 12 gelatin and polyacrylamide materials was unlikely to occur unless enough stress was 13 applied to break the walls. In contrast, MPPa had interconnected pores throughout the gel, a feature that more accurately resembled the interstitial space of soft tissue [Fig. 2(c)]. 14 Therefore, we selected MPPa to study acoustic streaming here as it can mimic both the 15 acoustic properties of tissue and the tissue microenvironment. 16

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# Feasibility of acoustic streaming

We tested ultrasound induced acoustic streaming in the MPPa by injecting a dye
into the hydrogel and observing any clearance once ultrasound was applied. FUS was
applied for 30 seconds using a range of acoustic parameters.

To test whether ultrasound applied in a porous material could displace fluid in the MPPa gel, the transducer's focal volume was placed at the phantom-water interface where the dye was inserted, and exposed to either no ultrasound (control) or ultrasound at a high intensity ( $f_c$ : 5 MHz,  $p_n$ : 6.2 MPa,  $p_p$ : 12.0 MPa,  $I_{SPTA}$ : 2002 W/cm<sup>2</sup>, duration: 30 s). To demonstrate the axial motion of the dye, we placed the camera to image the axial-

elevational plane [Fig. 1(Camera View - YZ)]. When ultrasound was applied, the dye was 1 2 instantaneously pushed axially within the MPPa gel surface then out into the water [Fig. 3 3(a-c)]. The presence of dye movement was assessed by calculating difference images by subtracting each frame by an earlier reference frame (start of sonication). To demonstrate 4 the radial motion of the dye, we placed the camera to image the lateral-elevational plane 5 [Fig. 1(Camera View - XY)]. Without the application of ultrasound, no detectable 6 7 changes in contrast was observed [Fig. 4(a-d)]. However, when ultrasound was applied, 8 the dye contrast changed, indicating that the dye was acoustically displaced [Fig. 4(e-h)]. 9 The dye cleared from the focal volume and was pushed radially to other regions of the 10 MPPa hydrogel. The clearance region diameter was approximately 1.5 mm at the time of maximum clearance (t: 30 s) [Fig. 4(h)]. 11

# 12 Assessment of the mechanical structure of the MPPa

To evaluate whether the acoustically-mediated fluid movement was not due to mechanical damage to the tissue (e.g., cavitation, tunnelling), we compared the microstructure of regions exposed to ultrasound ( $f_c$ : 5 MHz,  $p_n$ : 6.2 MPa,  $p_p$ : 12.0 MPa,  $I_{SPTA}$ : 2002 W/cm<sup>2</sup>, duration: 30 s) with regions that were not (Fig. 5a). Based on scanning electron microscopy images of the sonicated region, no difference in the mechanical structure between sonicated (Fig. 5b) and unsonicated regions (Fig. 5c and d) was observed.

20

### Effects of ultrasound parameters on acoustic streaming

Lower ultrasound intensities were tested to determine how clearance depended on the intensity. Three different ultrasound intensities were evaluated ( $f_c$ : 5 MHz,  $p_n$ : 2.6, 4.7, and 6.2 MPa,  $p_p$ : 3.1, 7.3 and 12.0 MPa,  $I_{SPTA}$ : 238, 972 and 2002 W/cm<sup>2</sup>) for 30 s of exposure duration while dye clearance was characterised by a change in optical intensity.

For all three intensities evaluated, average dye clearance increased with time [Fig. 6(a)]. 1 The optical intensity of the clearance at time (t: 30 s) of maximum clearance for ISPTA: 2 238, 972 and 2002 W/cm<sup>2</sup> and the unsonicated control were compared using a one-way 3 ANOVA with multiple comparison test. Only the highest exposure level was statistically 4 significant compared to the control, however the clear trend is dye clearance increasing 5 6 with increasing intensity [Fig. 6(b)]. The clearance rates [Fig. 6(c)] obtained from the dye 7 clearance over time [Fig. 6(b)] were shown to increase as the ultrasound intensity 8 increased. Estimated steady state velocities of the developed flow in the MPPa gel [Fig. 9 6(c)] were obtained using the model described above. The estimated average flow velocity through the MPPa gel was approximately 0.05, 0.25 and 0.65 mm/s for 238, 972 10 and 2002 W/cm<sup>2</sup>, respectively. 11

12

#### 13 **DISCUSSION**

The type of acoustic streaming produced was Eckart streaming (also known as 14 quartz wind), which is the steady fluid flow caused by the bulk absorption of acoustic 15 momentum. The ARF acting on the fluid pushed the fluid through the MPPa gel's 16 17 interconnected network of pores. Higher ultrasound intensities increased the applied ARF (Nyborg 1965), which resulted in higher streaming velocities. From the raw videos, the 18 19 observed streaming direction is both axial (dye leaving the MPPa gel was observed) and 20 radial. Although the ARF is applied axially in the direction of wave propagation, some dye moved radially due to the structure of the gel, where the channels are interconnected 21 22 in all directions. Moreover, the generated streaming is confined to the area around the 23 ultrasound beam, thus demonstrating a localised effect.

We confirmed that the dye clearance was caused by acoustic streaming, by 1 2 excluding the possibility of thermal or mechanical damage to the material. First, the net dye displacement was produced in the axial and radial directions. In contrast, dye 3 movement caused by heat or Fickian diffusion is a slow process (Cussler 2009) and 4 5 would be generated in all directions. Spherical diffusion with a maximum concentration 6 of dye at the centre and decreasing with distance was not observed in our study. The 7 modelled average velocity was proportional with the dye clearance rate as they both 8 increased with increasing ultrasound intensity. We used the clearance to relate acoustic 9 streaming through the gel based on the assumption that a larger clearance area over time implies implied that a fluid of higher speed is moving through the gel. Second, the melting 10 point of our MPPa gel is greater than 200°C, which was well above the temperature rise 11 12 that we could induce with our ultrasound parameters. Third, no detectable changes in the microstructure of the MPPa gel was observed, indicating that cavitation-mediated 13 mechanical damage, such as tunneling, was not responsible for the dye movement. 14 15 Fourth, the mechanical index (MI) of the lowest pressure tested that produced dye clearance – MI of 1.2 – was well below the typical guidelines to avoid bubble nucleation 16 17 (i.e., MI of 4.0) (AIUM 2015; Church et al. 2008; Church et al. 2015). To ensure that no gas bodies were present in our hydrogel, both the phantom and the experimental tanks 18 were degassed. Finally, mechanical damage to the hydrogel was not detected from our 19 20 SEM image analysis.

One of the critical aspects of our experiment was to use an appropriate material for studying acoustic streaming. Current tissue substitutes used for ultrasound imaging (Culjat et al. 2010) have similar acoustic properties of soft tissue, but do not resemble the microstructural characteristics relevant for acoustic streaming. Although these tissue substitutes contain large amounts of fluid, its fluid is confined in pockets. In many materials, such as healthy tissue and tissue scaffolds, fluid is interconnected. For example,
in healthy tissue, interstitial space resides between the blood and lymphatic system and is
interconnected throughout an organ, such as the brain.

4

### 5 CONCLUSIONS

6 The results presented here demonstrate that acoustic streaming could be directly 7 observed in a soft porous material. We have shown that this is achieved by a carefully 8 designed material resembling soft tissue and that traditional soft materials used for 9 ultrasound imaging, such as gelatin and polyacrylamide, may not appropriate for studying 10 acoustic streaming. The fluid velocities produced by acoustic streaming could be 11 controlled by adjusting the ultrasound intensity. Finally, we demonstrated that acoustic 12 streaming could be achieved without mechanical or thermal damage.

13

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10	

# **1 FIGURE LIST**

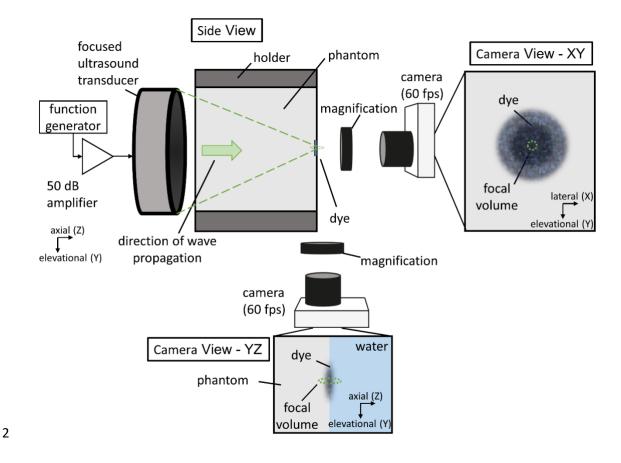


Fig. 1. Experimental setup. An MPPa gel with a localised region of a dye was immersed
in a water tank and sonicated by a 5-MHz focused ultrasound transducer. Ultrasound
pulses pushed the dye, which then cleared over time. Dye displacement was monitored
by a video camera. Camera View – YZ was used to image the axial displacement of the
dye and Camera View – XY was used to image the radial displacement.

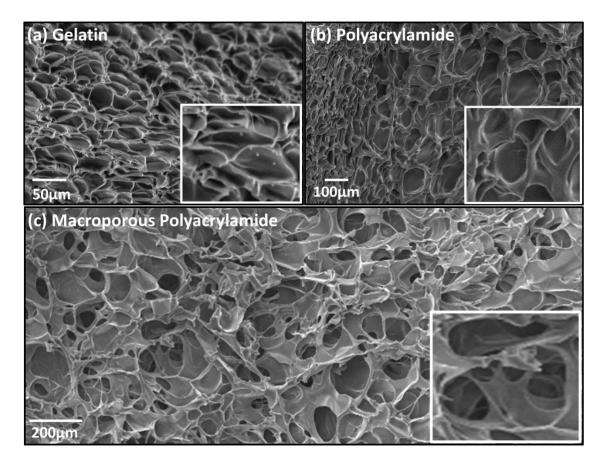


Fig. 2. Scanning electron microscopy images of three soft porous materials: (a) gelatin,
(b) polyacrylamide, and (c) macroporous polyacrylamide (MPPa). Zoomed in sections
show closed pockets or pores for gelatin and polyacrylamide. In contrast, the MPPa had
interconnected pores that provide a path for fluid to travel through.

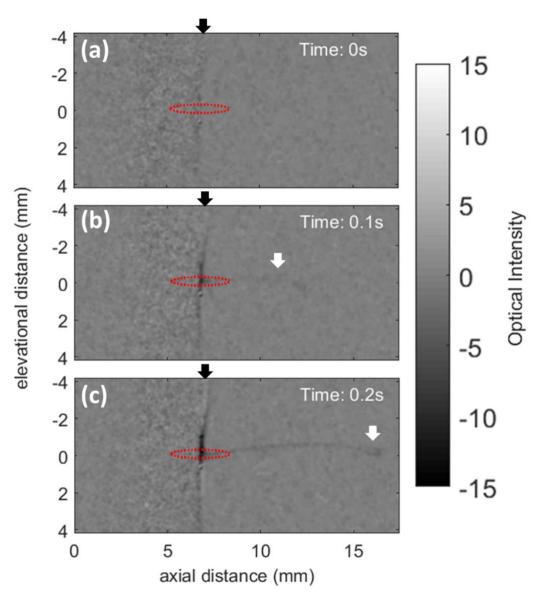
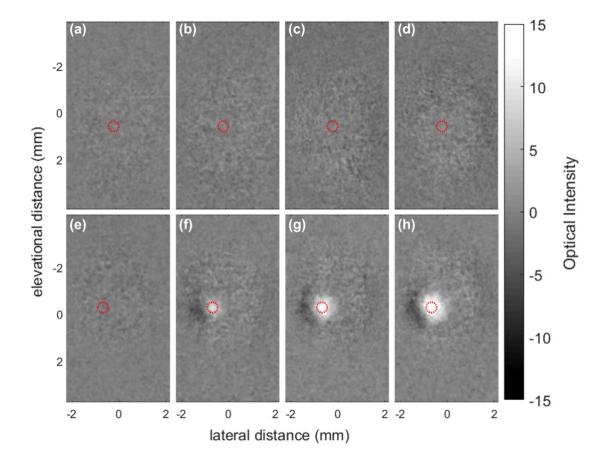




Fig. 3. Demonstration of axial acoustic streaming of dye. Ultrasound travelled axially, 2 which was parallel to the elevational-axial plane captured by the video camera. Images 3 acquired at 0, 0.1, and 0.2 s after the start of the sonication were subtracted from a 4 reference frame. The MPPa hydrogel was exposed to (a-c) ultrasound ( $f_c$ : 5 MHz,  $p_n$ : 6.2 5 MPa,  $p_p$ : 12.0 MPa,  $I_{SPTA}$ : 2002 W/cm<sup>2</sup>, duration: 30 s). The dye was instantaneously 6 pushed axially within the phantom surface then into the water, which appeared as a 7 8 negative change in optical intensity (grey/black). The red dashed circle is the FWHM of the ultrasound focus. Black arrows denote phantom-water interface. White arrows show 9 10 the dye displacement.





2 Fig. 4. Feasibility of acoustic streaming in a porous material tested by changes in dye contrast. A video camera imaged the ultrasound region of exposure (Fig. 1). Ultrasound 3 travelled axially, which was perpendicular to the lateral-elevational plane captured by the 4 5 video camera. Images acquired at 0, 10, 20 and 30 s after the start of the sonication were subtracted from a reference frame. The MPPa hydrogel was exposed to (a-d) no 6 7 ultrasound (control) and (e-h) ultrasound (fc: 5 MHz, pn: 6.2 MPa, pp: 12.0 MPa, ISPTA: 8 2002 W/cm<sup>2</sup>, duration: 30 s). With ultrasound, the dye was removed from the hydrogel at 9 the focus, which appeared as a positive change in optical intensity (white). The red dashed 10 circle is the FWHM of the ultrasound focus.

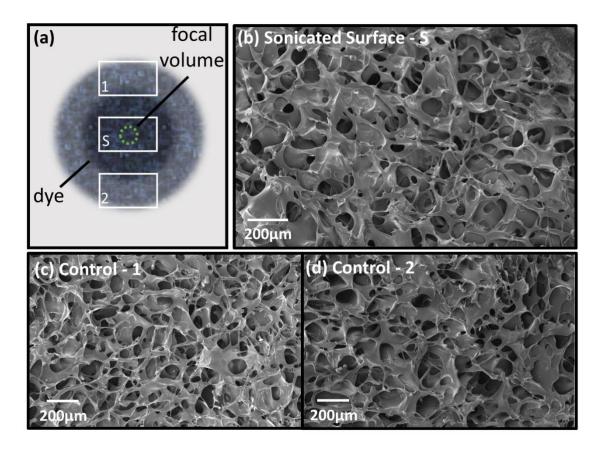
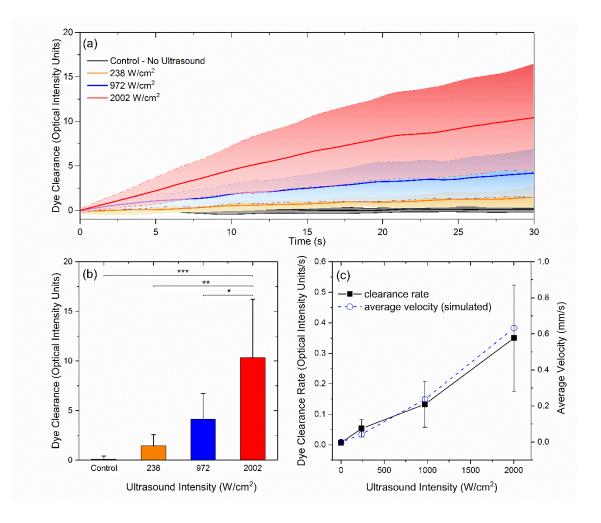




Fig. 5. Assessment of mechanical structure of the MPPa (a, box s; b) at the ultrasound
focus and (a, boxes 1 and 2; c and d) away from the focus using scanning electron
microscopy images of these regions (b-d). Ultrasound was applied at the highest
ultrasound intensity evaluated in our study (*fc*: 5 MHz, *p*<sub>n</sub>: 6.2 MPa, *p*<sub>p</sub>: 12.0 MPa, *I<sub>SPTA</sub>*: 2002
W/cm<sup>2</sup>, duration: 30 s). No qualitative structural differences between the MPPa's
microstructures of the sonicated (b) and control, unsonicated (c-d) regions were observed.



2 Fig. 6. Ultrasound intensity dependent dye clearance, dye clearance rate and estimated average velocities. Ultrasound at 0 (no ultrasound), 238, 972 and 2002 W/cm<sup>2</sup> was applied 3 to the MPPa gel containing a dye. The dye clearance was measured by observing changes 4 5 to the optical intensity of pixels in the focal region (red dashed circle in Fig. 4). (a) The dye clearance over time was observed over 30 s, revealing increased clearance over time. 6 7 Solid lines and shaded areas represent the average clearance and one standard deviation respectively (n = 5). (b) Comparison of maximum dye clearance at 30 s for different 8 9 ultrasound exposure levels and the control. Measurements are presented as mean plus standard deviation. (\* p < 0.05, \*\* p < 0.01, \*\*\* p < 0.001). (c) The clearance rate and the 10 simulated average velocity through the phantom, they both increased with increasing 11

- 1 ultrasound intensity. The measurements of the dye clearance rates for the different
- 2 ultrasound exposure levels are presented mean  $\pm$  standard deviation.