

Numerical Study for a Marine Current Turbine Blade Performance under Varying Angle of Attack

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Abstract

Energy generation from marine currents is a promising technology for sustainable development. The success of using marine current turbines to tap the ocean hydrodynamic energy depends on predicting the hydrodynamic characteristics and performance of such turbines. This paper presents an analysis of the two-dimensional flow using commercial CFD software over a marine current turbine blade. The 2D flow is simulated for HF-SX NACA foil modified from S1210 NACA foil at various angles of attack with Reynolds number of 19×10^4 , which represents the marine current flow. The hydrofoil is designed with considerations for lift and drag coefficients. The flow is simulated by solving the steady-state Navier-Stokes equations coupled with the $k-\omega$ shear stress transport (SST) turbulence model. The aim of this work is to study the effect of the angle of attack on the lift and drag coefficients. The computational domain is composed of non-homogenous structured meshing, with sufficient refinement of the domain near the foil blade in order to capture the boundary layer effects. Hence, all calculations are done at constant flow velocity while varying the angle attack for every model tested. The results have shown that the drag and lift coefficient, C_d and C_l coefficient increases with increasing the value of the angle of attack, ratio C_l/C_d curve related on performance at the peak Γ_0 angle of attack.

1. INTRODUCTION

Electrical energy extraction from marine currents offers the promise of regular and predictable energy [1, 2]. The location and viability of such devices to extract energy from marine currents has been a focus on several investigations [3–5] and a detailed review article [6]. These researches are highlighted several advantages and possible commercial viability for several locations throughout the world, particularly where the mean peak tidal currents are over 2 m/s (4 knots) [7]. The success of using marine current turbines to tap the ocean currents is dependent on predicting their hydrodynamic performance. Methodologies need to be established for studying the physical and operational parameters of the turbines to improve their performance [8, 9].

Performance of the turbines, allowing their design to be investigated and performance evaluated. Much can be transferred from the design ship propellers [10]. There are however a number of fundamental differences in the design and operation of the marine current turbine, which will require further investigation, research, and development. Differences entail changes in Reynolds number, different stall characteristics, and the possible occurrence of cavitation [11].

The rapid development of computational fluid dynamics (CFD) has been driven by the needs for faster and more accurate methods for predicting the flow fields around and over configurations of technical interest. In the past decade, CFD is the method choice in the design of many automotive, industrial components and processes in which fluid or gas flows play a major role. In the fluid dynamics, there are many commercial CFD packages available for modelling flow in or around objects. The computer simulations show features and details that are difficult, expensive or impossible to measure or visualize experimentally. When simulating the flow over foils, swirl flow plays an important role in determining the flow features and in quantifying the foil performance such as lift and drag. Most flows of practical engineering interest are the turbulent and turbulent mixing of the flow usually dominates the behaviour of the fluid. The turbulent nature of the flow plays a crucial part in the determination of many relevant engineering parameters [12- 15].

The simplest turbulence modelling approach rests on the concept of a turbulent viscosity. Such models are widely used for simple shear flows. The one – equation models attempt to improve on the zero-equation models by using an eddy viscosity that no longer depends purely on the local flow conditions but takes into account the flow history, Atkins (2003). Two-equation turbulence models are frequently used. Models like the $k-\epsilon$, Launder (1974), and the $k-\omega$ model, Wilcox (1998), have become industry standard models and are commonly used for most types of engineering problems. By definition, two-equation models include two extra transport equations to

represent the turbulent properties of the flow. This allows a two-equation model to account for history effect like convection and diffusion of turbulent energy. In the field of renewable energy, it is the $k-\epsilon$ model [11] that has found to be quite useful, being able to perform on the most deistic PCs whilst coupling an acceptable level of accuracy with reasonable computation times [16].

The two-equation turbulence models are reasonably accurate for fairly simple states of strain but are less accurate for modelling complex strain field arising from the action swirl, body forces such as buoyancy or extreme geometrical complexity. Several alternative models have been proposed, for example, Reynolds, stress transport models, Large Eddy Simulation (LES). And Detached-eddy simulation (DES), Spalart (1997), though these are used infrequently due to the long computational time and the requirement exceptionally powerful computing hardware in order to process the data [17]. In particular, the SST $k-\omega$ model developed by Menter (1994) incorporates the advantages from both the standard $k-\omega$ model and the $k-\epsilon$ model, giving more accurate and reliable predictions for many types of flow, including the flow over a foil [18- 20].

Patel et al. [21] studied and measured numerically and experimentally the drag and lift forces using CFD and validated with wind tunnel experiments. They also presented the analysis of the two dimensional subsonic flow over a NACA 0012 airfoil with various angles of attack at a Reynolds number of $3E6$. It is concluded that at the zero degree of AOA there is no lift force generated, and that obviously amount of lift and drag force and the value of drag coefficient increase but the amount increment in drag force and drag coefficient is quite lower compare to lift force. Also, Nedyalkov and Wosnik [22] investigated performance of bi-directional blades for tidal current turbine. In order to select a favourable hydrofoil, they use simplified 2D for a range of angles of attack for foils with different foil-geometry parameters and the selected hydrofoil is tested in the high speed cavitation tunnel. In addition, Noruzi et al. [23] studied the effect of turbine installation depth with and without extreme gravity waves on hydrokinetic performance of a horizontal marine current axial turbine by Blade Element Momentum Theory and CFD. Their study can provide data choose appropriate installation depth for the turbine to obtain higher power coefficient and avoid undesirable phenomena e.g. fatigue and cavitation. In the other case, Goundar et al. [24] also studied on hydrofoils for marine current turbine. They conclude that maximizing the number of blades to have higher hydrodynamic performance, increasing the camber and thickness of airfoils reduces the suction peak and also improves the performance. Briefly, their designing the hydrofoil having lower suction peak and higher C_L and L/D will improve the rotor performance [25].

In this research, curves for the lift and drag characteristics of the NACA foil were developed. Dependence of the drag coefficient C_d and lift coefficient C_l on the angle of attack were determined using the turbulence model. Turbulent flows are significantly affected by the presence of walls, where the viscosity affected region have large gradients in the solution variables and accurate presentation of the near wall region determines successful prediction of wall bounded turbulent flows. In fluid dynamics, turbulence or turbulent flow is a fluid regime characterized by chaotic, stochastic property changes. This includes low momentum diffusion, high momentum convection and rapid variation of pressure and velocity in space and time.

Nomenclature

A_{ts}	Cross-sectional area of test section (m^2)
C_D	Drag coefficient
C_L	Lift coefficient
C_P	Power coefficient
D	Drag force (N)
g	Gravitational acceleration ($9.81m/s^2$)
M	Pitching moment (Nm)
P	Pressure (Pa)
Re	Reynold Number
α	Angle of attack (degree)

2. MATHEMATICAL & NUMERICAL DETAILS

For all flows, the solver solves conservation equations for mass and momentum. Additional transport equations are also solved when the flow is turbulent. The equation for conservation of mass or continuity equation can be written as follows:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = S_m \quad (1)$$

Equation 1 is the general form of the mass conservation equation and is valid for incompressible flows. The source S_m is mass added to the continuous phase from the dispersed second phase and any user-defined sources. Conservation of momentum in an inertial reference frame is described by equation 2 [12].

$$\frac{\partial}{\partial t} (\rho \vec{u}) + \nabla \cdot (\rho \vec{u} \vec{u}) = -\nabla p + \nabla \cdot (\vec{\tau}) + \rho \vec{g} + \vec{F} \quad (2)$$

where ρ is the static pressure, $\vec{\tau}$ is the stress tensor and $\rho \vec{g}$ and \vec{F} are the gravitational body force and external body forces. \vec{F} Also contains other model-dependent source terms such as porous- media and user defined sources.

The commercial software ANSYS FLUENT is used for CFD model discussed in below. Continuity and momentum equations are solved for all types of flow via a finite-volume method. To account for the effects of turbulence, a variety of models are available, ranging in complexity from one-equation models to LES. The turbulence models used in this work belongs to the standard k- ω SST model [12]:

k- ω SST

The transport equations 3 and 4 for the standard k- ω model, developed by Wilcox (1998) are given below,

$$\frac{\partial}{\partial t} (\rho k) + \frac{\partial}{\partial x_i} (\rho k u_i) = \frac{\partial}{\partial x_i} \left(\Gamma_k \frac{\partial k}{\partial x_j} \right) + G_k - Y_k \quad (3)$$

$$\frac{\partial}{\partial t} (\rho \omega) + \frac{\partial}{\partial x_i} (\rho \omega u_i) = \frac{\partial}{\partial x_i} \left(\Gamma_\omega \frac{\partial \omega}{\partial x_j} \right) + G_\omega - Y_\omega \quad (4)$$

where, Γ_k , G_k and Y_k are the diffusivity, generation and dissipation of turbulent kinetic energy and Γ_ω , G_ω and Y_ω diffusivity, generation and dissipation of ω .

The standard k- ω model accounts for Re effects in the inner region of the boundary layer but is highly sensitive to the values of k and ω in the free stream. The SST k- ω model couples the standard k- ω model with a modified version of the k- ϵ model via a blending function. The transport equations for the SST k- ω model were developed by Menter. The expressions for the terms Γ_k , G_k , Y_k , Γ_ω , G_ω and Y_ω are different with different constants and limiters for the turbulent viscosity and production of kinetic energy. The revised model constants are based on experience [12, 25].

There is also an additional cross-diffusion term in the equation for which arises from the modification of the k- ϵ model into equations based on k and by substitution of ϵ with k- ω . This term is given below in equation 5,

$$D_\omega = 2(1 - F_1) \frac{1}{\omega \sigma_{\omega,2}} \frac{\partial k}{\partial x_j} \frac{\partial \omega}{\partial x_j} \quad (5)$$

where F_1 is a blending function and the empirical constant ($\sigma_{\omega,2} = 1.17$).

Through blending both models the SST k- ω model incorporates the advantages from both the standard k- ω model and the k- ϵ model, giving more accurate and reliable predictions for many types of flow, including the flow over a foil [19].

3. NACA Four-Digit Airfoil Profile

In this work, the HF-SX NACA foil is utilized Fig. 1. The NACA X foil series uses the same thickness forms as the 4-digit series, but the mean camber line is defined differently. The final two digits indicate the maximum thickness (t) as percentage of chord. [26]

3.1. Calculation of the airfoil coordinates

Compute the mean camber-line y_c ordinate for each x position, using the following equations. Using geometry of the blade to determine the values of p, m and k_1 :

$$y_c = (k_1/6)(x^3 - 3mx^2 + m^2x(3-m)); \text{ for } x \leq p$$

$$y_c = ((k_1 m^3)/6)(1-x); \text{ for } x > p$$

The final coordinates for the foil upper surface (x_u, y_u) and lower surface (x_L, y_L) are given by:

$$x_u \equiv x - y_t (\sin \theta)$$

$$y_u \equiv y_c + y_t (\cos \theta)$$

$$x_L \equiv x + y_t (\sin \theta)$$

$$y_L \equiv y_c - y_t (\cos \theta)$$

Where $\theta = \arctan(\Delta y_c / \Delta x)$

The chord length is 1 m and domain height is set to approximately 20 chord length. This size should be sufficient to properly resolve the inner parts of the boundary layer.



Fig.1. NACA HFSX foil [27]

3.2. CFD Model

The first step in modelling a problem involves the creation of the geometry and the meshes with a pre-processor. The majority of time spent on CFD project in the industry is usually devoted to successfully generating a mesh for the domain geometry that allows a compromise between desired accurate and solution cost. After the creation of the grid, a solver is able to solve the governing equations of the problem. The basic procedural steps for the solution of the problem are the following. First, the modelling goals have to be defined and the model geometry and grid are created. Then, the solver and the physical models are stepped up in order to compute and monitor the solution. Afterwards, the results are examined and saved and if it is necessary revisions are considered to the numerical or physical model parameters [27,28].

CFD model of NACA HFSX is meshed by ANSYS ICEM CFD, as shown in Fig. 2. For converged solution and save calculation time, model is meshed by hexa element. Fine mesh and small element with inflation at location are close to NACA shape. Element size grows at along two axes from NACA shape to boundaries [28]. To get optimal results, the criteria of elements are very important, and number of element of best quality mesh is less than bad mesh. Assessing the quality of good or bad grid will be evaluated by Skewness Ratio, acceptable value is less than 0.54, idea is 0, Aspect Ratios, acceptable value is less than 1.5, idea is 1, the Jacobian Ratio is 1 and Warpangle are 0 deg. If parameters of mesh are close to these criteria, result can be converged [29]. Meshing process depend heavily on the experience of the engineer, especially in using the meshing method and element size.

The model is a closed domain, and all boundaries are open. Except for the inlet boundary, the outlet boundary and wall of NACA shape, inlet is set by a velocity of 3m/s, gauss pressure is zero, and turbulent intensity is 2.8%. Outlet is set by gauss pressure of zero, turbulent intensity is 2.8% and wall is NACA shape.

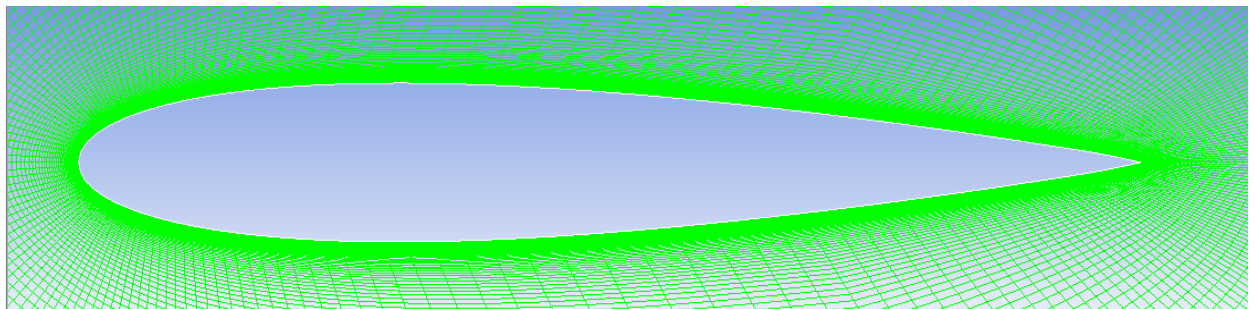


Fig.2. Meshing in ICEM

The mesh is generated with 90400 elements and 91000 nodes see Fig. 3 histogram of mesh quality. All of

elements is quad-elements. The quality of mesh is shown in Fig 3. The quality of mesh can show that the result is acceptable. Maximum of Skewness ratio is 0.36651. This is most important criteria for CFD model. The Reynolds number can be calculated by:

$$Re = \frac{(Inertial\ forces)}{Viscous\ forces} = \frac{(mass)(acceleration)}{(dynamic\ viscosity)\left(\frac{velocity}{distance}\right)} = \frac{\rho v L}{\mu}$$

From Reynolds number, two parameters of turbulent flow can be calculated, turbulent intensity of CFD model is formulated as following [30]:

$$I = 0.16 \times (Re)^{-1/8}$$

where Re is the Reynolds number, I is the turbulent intensity, thus, the value of intensity is 2.489965%

Operation of solving process is set by absolute pressure, reference temperature. Model of NACA HF-SX is simulated in case of depth of 91m from sea water level [31]. So, hydrostatic pressure in this case is absolute pressure, and it is calculated by following formula [32, 33]:

$$P_{absolute} = P_{hydrostatic} + P_{atmospheric} = g \times \rho \times h + 101325(Pa)$$

where, g is gravitational acceleration (m/s^2) is density of water (kg/m^3) and h is depth (m); the absolute pressure is 992426.122 (Pa) and reference temperature is 295 K [34]. In order to validate the present simulation, the Re is 19×10^4 ; velocity of water investigated is 3 m/s; the density of the water at given temperature is 998 kg/m^3 ; and the viscosity is 0.00103 kg/ms . This is an assumption close to reality and it is not necessary to resolve the energy equation. A segregated, implicit solver is utilized. Calculations were done for angles of attack ranging from 0° to 15° . The foil profile, boundary conditions and meshes were all created in the pre-processor ICEM. The pre-processor is a program that can employ to produce models in two dimensions, using structured meshes, which can consist of all quadrilateral elements. The resolution of the mesh is greater in regions where greater computational accuracy is needed, such as the region close to the foil. Nodes also increase the required computer memory and computational time. The appropriate number of nodes can be determined by increasing the number of nodes until the mesh is sufficiently fine so that further refinement does not change the results [35].

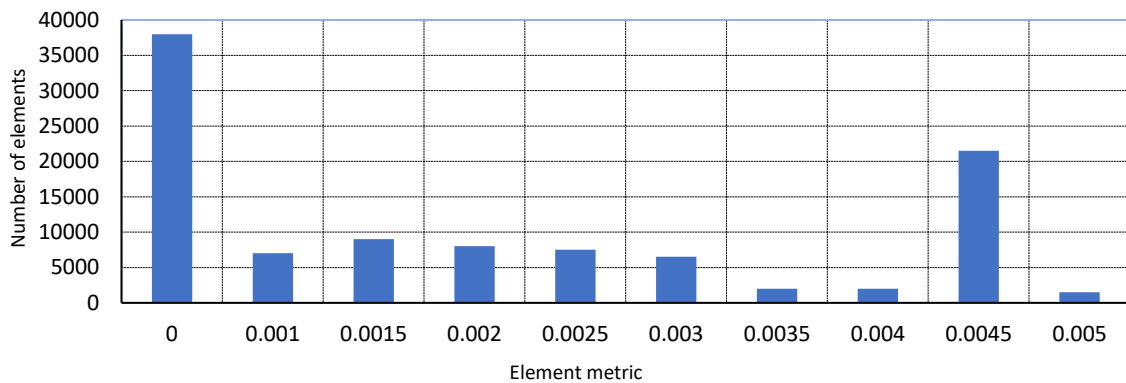


Fig.3. Statistics of elements base on meshing criteria (Histogram)

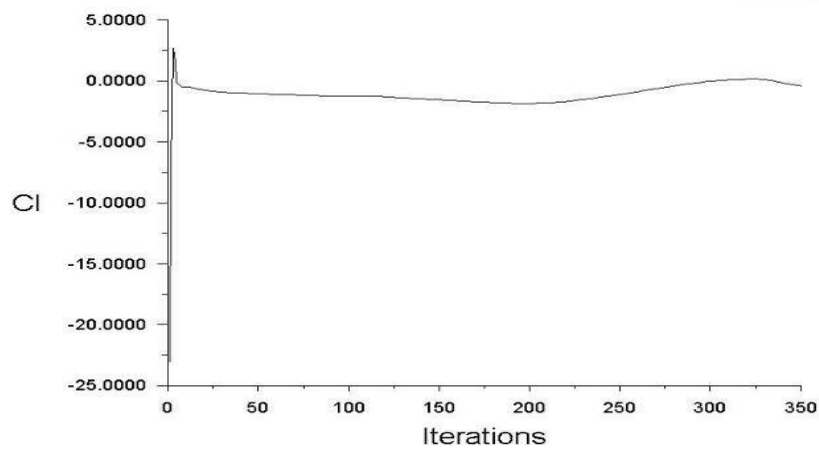
4. RESULTS & DISCUSSION

On a foil, the resultants of the forces are usually resolved into two forces and one moment. The component of net force acting normal to the incoming flow stream is known as lift force and the component of the net force action parallel to the incoming flow stream is known as the drag force. The curves of the lift and the drag coefficient are shown for various angles of attack. Simulations for various angles of attack were done in order to be able to compare the different C_l and C_d coefficients. Accordingly, the model is solved with a range of angle of attack from 0 to 15° . Consequently, Fig. 4 presented the results of convergence graph.

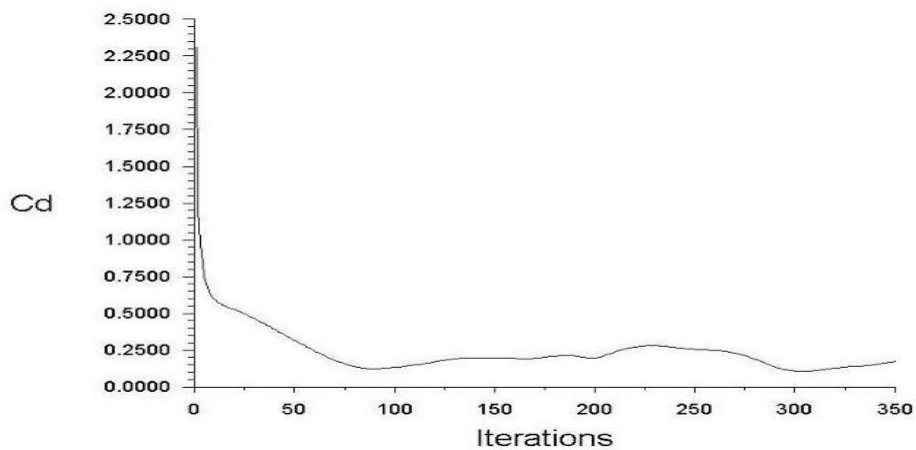
For each simulation, the results are calculated from numerical data and solution converge after 347 iterations, as shown in Fig. 4. Numerical values show that C_l is 1.0530 and C_d is 0.01509 at zero degree angle of attack. For

high quality of mesh, the solution is converged where the value is accepted. From these values, the graph will be plotted, thereafter a holistic view of the dependence of lift coefficient and drag coefficient on the angle of attack can be determined. Hence, it can determine the best angle of attack and design turbine blades to get highest efficiency. Also, from results, also can get contour of pressure, velocity around NACA shape are obtained and the maximum value and minimum value of each variable. Contour of pressure show locations that have maximum pressure; also, it can notice the separation point, transition point, location have turbulent flow, which cause of cavitation phenomenon.

Table 1 illustrates distribution pressure and velocity at four different angles of attack, it can be noticed that, pressure distribution in top and bottom domain (compared to chord) is asymmetry at 0° angle of attack. In this case, it is hard to rotate the blade of the marine turbine due to relative similar pressure distribution between top and bottom domain. In others of angles of attack, pressure distribution in the down domain always has the larger values than the case of 0° angle of attack. In addition, when angle of attack gets up, average of pressure also increase respectively. It is easy to see that when angle of attack is not 0° , the blade of the marine turbine can rotate conveniently thank for different pressure distribution among two domains.



(a)



(b)

Fig.4. Convergence graph of (a) C_l and (b) C_d

From velocity contour, it can be seen when the angle of attack is increased, maximum velocity is increased too. But high velocity is concentrated at spike of NACA shape. It means drop-pressure will be happened, and lead to turbulent flow at back of NACA shape.

From Table. 2, at angle of attack 0° , flow is steady and top pressure and bottom pressure almost is similar. On the

other hand, shape of NACA HF-SX is not symmetric, because pressure in top domain is less than pressure at bottom domain, although other cases at 5° , 10° and 15° , difference between top domain and bottom domain is noticed. The value of pressure at the lower domain is always higher than the value of pressure at higher domain. However, to determine the cases with highest ratio, it is must to get the numerical values at top and bottom surface of NACA shape. All parameters value and results are shown in the Table. 2.

Table 1. Distribution pressure and velocity at four different angles of attack

Angle attack	Pressure Distribution	Velocity Distribution
0		
5		
10		
15		

Table2. Show value C_l , C_d , Max Pressure, Min Pressure, Min Velocity and ratio C_l/C_d

Angle of attack	C_l	C_d	Max Pressure (Pa)	Min Pressure (Pa)	Max Velocity (m/s)	C_l/C_d
0	1.053	0.01509	4440	-2140	3.487	69.78
5	1.5991	0.01868	4339	-7046	4.482	85.6
10	1.9364	0.02938	5177	-14200	4.804	65.9
15	1.958	0.08203	4460	-23970	5.693	23.86

5. VALIDATION OF CFD RESULTS

Fig. 5 shows relationship between C_l and angle of attack. The C_l is directly affected by angle of attack, at angle 0 degree $C_l = 1.053$ which is minimum value, at angle 5 degree $C_l = 1.5991$, at 10 degree is 1.9364 and at 15 degree C_l is 1.958. In general, the lift coefficient increases with the increase of angle of attack. In addition, the lift coefficient is proportional to angle of attack where the trend of curve is reduced when angle of attack increases, which means that the rate of increasing of lift coefficient is decreased when angle of attack increase than the value of 15°.

Based on lift coefficient curve of proposed model and experimental results of NACA HF-SX [35], the trend of two curves in Fig. 5 is relatively similar. Furthermore, the numerical results of C_l and C_d have been agreed with experimental results at different angle of attack. In particular, at 15 degree in two models lift coefficients values are about 2.

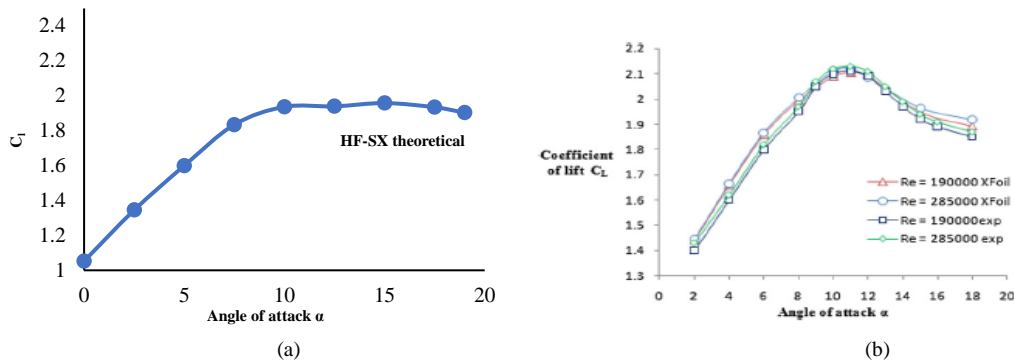


Fig.5. C_l for NACA HF-SX (a) proposed model; (b) experimental [adopted from 35]

Fig. 6 shows relationship between C_d at different angles of attack. At angle 0 degree $C_d = 0.01509$ (i.e. minimum value of C_d); at angle 5 degree $C_d = 0.01868$; at 10 degree is 0.02938 and at 15 degree is 0.08203. The peak of the ratio C_l/C_d is at around 7° angle of attack from Fig. 8 below. Similar to the lift coefficient, the drag coefficient also increases with angle of attack. In spite of this curve is non-linear, it is similar with lift coefficient curve, and it is covariates too, so the drag coefficient is proportional to angle of attack. Also, slope of curve is increased when angle of attack increases, because the speed of increasing of lift coefficient will be increased when angle of attack increases.

Based on drag coefficient curve of proposed model and experimental results of NACA HF-SX [35], the drag coefficients are proportional to angles of attack. The trend of proposed model and experimental results are relatively agreed. Moreover, magnitude of lift coefficient at angle of attack levels also nearly equal; e.g. at 15 degree in two models drag coefficients values are about 0.08.

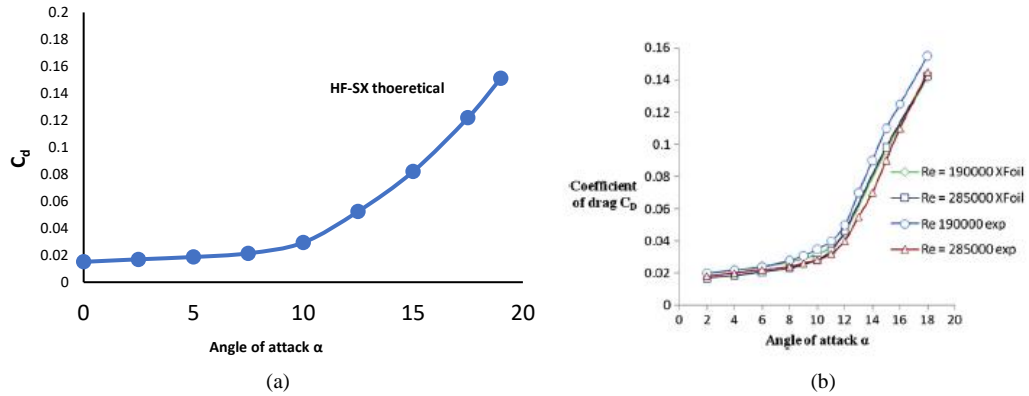


Fig.6. C_d for NACA HF-SX (a) proposed model; (b) experimental [adopted from 35]

Fig. 7 shows the relationship between C_l/C_d and angles of attack, the maximum value at around 7° angle. It can be explained about highest value at angle of attack 7° that, when NACA shape is tilted, both of lift and drag forces are increased. Although velocity contour in Table 1 shows that, at case of 5° angle of attack, water domain after spike of blade begin to reduce the occur drop-pressure, this reduction is increased when the angle of attack is increased. However, the increasing rate of lift coefficient is lower than increasing of drag coefficient; this cause a reduction of C_l/C_d ratio over angles of attack. This is optimal point to determine from this angle of attack, the turbine blade can be designed to get highest efficiency. From N. Goundar, Rafiuddin Ahmed, Lee [35], all airfoil trends of C_l/C_d curves are similar. In this work, the highest ratio of C_l/C_d is occurred at nearly 7° angle.

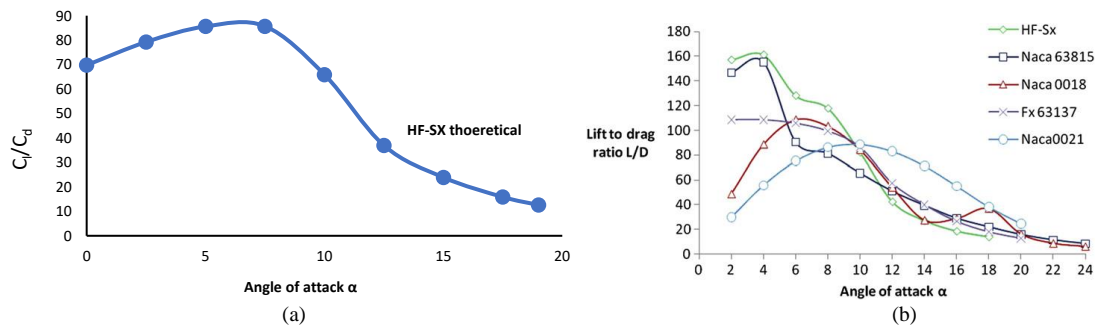


Fig.7. C_l/C_d for NACA HF-SX (a) proposed model; (b) experimental [adopted from 35]

6. CONCLUSION

Based on the results of analysing the flow field around the aerofoil of turbine, the performance of marine turbine is directly affected by the angle of attack. This is clearly shown by the drag and lift coefficients, where C_d and C_l coefficients increases with increasing the angle of attack. Hence, from C_l/C_d curve, the blades performance reaches the peak at around 7° angle of attack.

In conclusion, at the zero degree of angle of attack, there is a relatively small lift force generated, and if it is desired to increase in the amount of lift force and the value of lift coefficient the angle of attack have to be increased. By doing that obviously amount of drag force and value of lift coefficient also increased, but the increment in drag coefficient is slightly lower than lift force. Also, from results of velocity contour, the location of cavitation phenomenon can be located and determined. The pressure contour shows location of the high stress on the material; hence it has to reinforce or may propose other materials. Finally, from all analysed results, the performance of marine turbines is directly affected by angle of attack. In the future, a 3-D study with these data can be coupled with structure analysis method, i.e. finite element analysis, to improve the marine current turbines efficiency.

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