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# On geodesic mappings of Riemannian spaces with cyclic Ricci tensor

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#### Abstract

An n-dimensional Riemannian space  $V^n$  is called a Riemannian space with cyclic Ricci tensor [2, 3], if the Ricci tensor  $R_{ij}$  satisfies the following condition

$$R_{ij,k} + R_{jk,i} + R_{ki,j} = 0,$$

where  $R_{ij}$  the Ricci tensor of  $V^n$ , and the symbol "," denotes the covariant derivation with respect to Levi-Civita connection of  $V^n$ .

In this paper we would like to treat some results in the subject of geodesic mappings of Riemannian space with cyclic Ricci tensor.

Let  $V^n=(M^n,g_{ij})$  and  $\overline{V}^n=(M^n,\overline{g}_{ij})$  be two Riemannian spaces on the underlying manifold  $M^n$ . A mapping  $V^n\to \overline{V}^n$  is called geodesic, if it maps an arbitrary geodesic curve of  $\overline{V}^n$ . [4]

At first we investigate the geodesic mappings of a Riemannian space with cyclic Ricci tensor into another Riemannian space with cyclic Ricci tensor.

Finally we show that, the Riemannian - Einstein space with cyclic Ricci tensor admit only trivial geodesic mapping.

Keywords: Riemannian spaces, geodesic mapping.

MSC: 53B40.

### 1. Introduction

Let an n-dimensional  $V^n$  Riemannian space be given with the fundamental tensor  $g_{ij}(x)$ .  $V^n$  has the Riemannian curvature tensor  $R^i_{jkl}$  in the following form:

$$R_{ijk}^{h}(x) = \partial_{j}\Gamma_{ik}^{h}(x) + \Gamma_{ik}^{\alpha}(x)\Gamma_{j\alpha}^{h}(x) - \partial_{k}\Gamma_{ij}^{h}(x) - \Gamma_{ij}^{\alpha}(x)\Gamma_{k\alpha}^{h}(x), \qquad (1.1)$$

where  $\Gamma^{i}_{ik}(x)$  are the coefficients of Levi-Civita connection of  $V^{n}$ .

The Ricci curvature tensor we obtain from the Riemannian curvature tensor using of the following transvection:  $R_{jk\alpha}^{\alpha}(x) = R_{jk}(x)^{1}$ .

**Definition 1.1.** [2, 3] A Riemannian space  $V^n$  is called a Riemannian space with cyclic Ricci tensor, if the Ricci tensor of  $V^n$  satisfies the following equation:

$$R_{ij,k} + R_{jk,i} + R_{ki,j} = 0, (1.2)$$

where the symbol "," means the covariant derivation with respect to Levi-Civita connection of  $V^n$ .

**Definition 1.2.** [4] Let two Riemannian spaces  $V^n$  and  $\overline{V}^n$  be given on the underlying manifold  $M_n$ . The maps:  $\gamma: V^n \to \overline{V}^n$  is called geodesic (projective) mappings, if any geodesic curve of  $V^n$  coincides with a geodesic curve of  $\overline{V}^n$ .

It is wellknown, that the geodesic curve  $x^i(t)$  of  $V^n$  is a result of the second order ordinary differential equations in a canonical parameter t:

$$\frac{d^2x^i}{dt^2} + \Gamma^i_{\alpha\beta}(x)\frac{dx^\alpha}{dt}\frac{dx^\beta}{dt} = 0.$$
 (1.3)

We need in the investigations the next:

**Theorem 1.3.** [4] The maps:  $V^n \to \overline{V}^n$  is geodesic if and only if exits a gradient vector field  $\psi_i(x)$ , which satisfies the following condition:

$$\overline{\Gamma}_{jk}^{i}(x) = \Gamma_{jk}^{i}(x) + \delta_{j}^{i}\psi_{k}(x) + \delta_{k}^{i}\psi_{j}(x), \qquad (1.4)$$

and

**Definition 1.4.** [1] A Riemannian space  $V^n$  is called Einstein space, if exists a  $\rho(x)$  scalar function, which satisfies the equation:

$$R_{ij} = \rho(x)g_{ij}(x). \tag{1.5}$$

 $<sup>^1{\</sup>rm The}$  Roman and Greek indices run over the range 1, ..., n; the Roman indices are free but the Greek indices denote summation.

## 2. Geodesic mappings of Riemannian spaces with cyclic Ricci tensors

It is easy to get the next equations [4]:

$$\overline{R}_{ij} = R_{ij} + (n-1)\psi_{ij}, \tag{2.1}$$

where  $\psi_{ij} = \psi_{i,j} - \psi_i \psi_j$  and

$$\overline{R}_{ij,k} = \frac{\partial \overline{R}_{ij}}{\partial x^k} - \overline{\Gamma}_{ik}^{\alpha}(x)\overline{R}_{\alpha j} - \overline{\Gamma}_{jk}^{\alpha}(x)\overline{R}_{\alpha i}, \qquad (2.2)$$

where  $\overline{\Gamma}_{ik}^{\alpha}(x)$  are components of Levi-Civita connection if  $\overline{V}^n$ . At now we suppose, that  $\overline{V}^n$  in a Riemannian space with cyclic Ricci tensor, that is

$$\overline{R}_{ij,k} + \overline{R}_{jk,i} + \overline{R}_{ki,j} = 0. (2.3)$$

Using (2.2) we can rewrite (2.3) in the following form:

$$\frac{\partial \overline{R}_{ij}}{\partial x^{k}} - \overline{\Gamma}_{ik}^{\alpha}(x)\overline{R}_{\alpha j} - \overline{\Gamma}_{jk}^{\alpha}(x)\overline{R}_{\alpha i} + 
\frac{\partial \overline{R}_{jk}}{\partial x^{i}} - \overline{\Gamma}_{ji}^{\alpha}(x)\overline{R}_{\alpha k} - \overline{\Gamma}_{ki}^{\alpha}(x)\overline{R}_{\alpha j} + 
\frac{\partial \overline{R}_{ki}}{\partial x^{j}} - \overline{\Gamma}_{kj}^{\alpha}(x)\overline{R}_{\alpha i} - \overline{\Gamma}_{ij}^{\alpha}(x)\overline{R}_{\alpha k} = 0.$$
(2.4)

From (1.4) and (2.1) we can compute:

$$\frac{\partial(R_{ij} + (n-1)\psi_{ij})}{\partial x^k} - (\Gamma_{ik}^{\alpha}(x) + \psi_i(x)\delta_k^{\alpha} + \psi_k(x)\delta_i^{\alpha})(R_{\alpha j} + (n-1)\psi_{\alpha j}) - (\Gamma_{jk}^{\alpha}(x) + \psi_j(x)\delta_k^{\alpha} + \psi_k(x)\delta_j^{\alpha})(R_{\alpha i} + (n-1)\psi_{\alpha i}) + \\
\frac{\partial(R_{jk} + (n-1)\psi_{jk})}{\partial x^i} - (\Gamma_{ji}^{\alpha}(x) + \psi_j(x)\delta_i^{\alpha} + \psi_i(x)\delta_j^{\alpha})(R_{\alpha k} + (n-1)\psi_{\alpha k}) - (\Gamma_{ki}^{\alpha}(x) + \psi_k(x)\delta_i^{\alpha} + \psi_i(x)\delta_k^{\alpha})(R_{\alpha j} + (n-1)\psi_{\alpha j}) + \\
\frac{\partial(R_{ki} + (n-1)\psi_{ki})}{\partial x^j} - (\Gamma_{kj}^{\alpha}(x) + \psi_k(x)\delta_j^{\alpha} + \psi_j(x)\delta_k^{\alpha})(R_{\alpha i} + (n-1)\psi_{\alpha i}) - (\Gamma_{ij}^{\alpha}(x) + \psi_i(x)\delta_j^{\alpha} + \psi_j(x)\delta_i^{\alpha})(R_{\alpha k} + (n-1)\psi_{\alpha k}) = 0.$$

That is

$$\left. \begin{array}{l} \frac{\partial R_{ij}}{\partial x^k} - \Gamma^{\alpha}_{ik}(x) R_{\alpha j} - \Gamma^{\alpha}_{jk}(x) R_{\alpha i} + \\ + \frac{\partial R_{jk}}{\partial x^i} - \Gamma^{\alpha}_{ji}(x) R_{\alpha k} - \Gamma^{\alpha}_{ki}(x) R_{\alpha j} + \\ + \frac{\partial R_{ki}}{\partial x^j} - \Gamma^{\alpha}_{ki}(x) R_{\alpha i} - \Gamma^{\alpha}_{ij}(x) R_{\alpha k} + \end{array} \right\} R_{ij,k} + R_{jk,i} + R_{ki,j}$$

$$+(n-1)\frac{\partial \psi_{ij}}{\partial x^{k}} - (n-1)\Gamma_{ik}^{\alpha}(x)\psi_{\alpha j} - \psi_{i}(x)R_{kj} - (n-1)\psi_{i}(x)\psi_{kj} -$$

$$-\psi_{k}(x)R_{ij} - (n-1)\psi_{k}(x)\psi_{ij} - (n-1)\Gamma_{jk}^{\alpha}(x)\psi_{\alpha i} - \psi_{j}(x)R_{ki} -$$

$$-(n-1)\psi_{j}(x)\psi_{ki} - \psi_{k}(x)R_{ji} - (n-1)\psi_{k}(x)\psi_{ji} +$$

$$+(n-1)\frac{\partial \psi_{jk}}{\partial x^{i}} - (n-1)\Gamma_{ji}^{\alpha}(x)\psi_{\alpha k} - \psi_{j}(x)R_{ik} - (n-1)\psi_{j}(x)\psi_{ik} -$$

$$-\psi_{i}(x)R_{jk} - (n-1)\psi_{i}(x)\psi_{jk} - (n-1)\Gamma_{ki}^{\alpha}(x)\psi_{\alpha j} - \psi_{k}(x)R_{ij} -$$

$$-(n-1)\psi_{k}(x)\psi_{ij} - \psi_{i}(x)R_{kj} - (n-1)\psi_{i}(x)\psi_{kj} +$$

$$+(n-1)\frac{\partial \psi_{ki}}{\partial x^{j}} - (n-1)\Gamma_{kj}^{\alpha}(x)\psi_{\alpha i} - \psi_{k}(x)R_{ji} - (n-1)\psi_{k}(x)\psi_{ji} -$$

$$-\psi_{j}(x)R_{ki} - (n-1)\psi_{j}(x)\psi_{ki} - (n-1)\Gamma_{ij}^{\alpha}(x)\psi_{\alpha k} - \psi_{i}(x)R_{jk} -$$

$$-(n-1)\psi_{i}(x)\psi_{jk} - \psi_{j}(x)R_{ik} - (n-1)\psi_{j}(x)\psi_{ik} = 0.$$

If we suppose, that  $V^n$  has cyclic Ricci tensor we have:

$$(n-1)\left(\frac{\partial \psi_{ij}}{\partial x^k} - \Gamma^{\alpha}_{ik}(x)\psi_{\alpha j} - \Gamma^{\alpha}_{jk}(x)\psi_{\alpha i}\right) +$$

$$+(n-1)\left(\frac{\partial \psi_{jk}}{\partial x^i} - \Gamma^{\alpha}_{ji}(x)\psi_{\alpha k} - \Gamma^{\alpha}_{ki}(x)\psi_{\alpha j}\right) +$$

$$+(n-1)\left(\frac{\partial \psi_{ki}}{\partial x^j} - \Gamma^{\alpha}_{kj}(x)\psi_{\alpha i} - \Gamma^{\alpha}_{ij}(x)\psi_{\alpha k}\right) +$$

$$-4\psi_i(x)R_{jk} - 4\psi_j(x)R_{ki} - 4\psi_k(x)R_{ij} -$$

$$-(n-1)(4\psi_i(x)\psi_{jk} + 4\psi_j(x)\psi_{ki} + 4\psi_k(x)\psi_{ij}) = 0.$$

That is

$$(n-1)(\psi_{ij,k} + \psi_{jk,i} + \psi_{ki,j}) -$$

$$-4(\psi_i(x)R_{jk} + \psi_j(x)R_{ki} + \psi_k(x)R_{ij}) -$$

$$-4(n-1)(\psi_i(x)\psi_{jk} + \psi_j(x)\psi_{ki} + \psi_k(x)\psi_{ij}) = 0.$$

$$(2.5)$$

**Theorem 2.1.**  $V^n$  and  $\overline{V}^n$  Riemannian spaces with cyclic Ricci tensors have common geodesics, that is  $V^n$  and  $\overline{V}^n$  have a geodesic mapping if and only if exists a  $\psi_i(x)$  gradient vector, which satisfies the condition:

$$(n-1)(\psi_{ij,k} + \psi_{jk,i} + \psi_{ki,j}) -$$

$$-4(\psi_i(x)R_{jk} + \psi_j(x)R_{ki} + \psi_k(x)R_{ij}) -$$

$$-4(n-1)(\psi_i(x)\psi_{jk} + \psi_j(x)\psi_{ki} + \psi_k(x)\psi_{ij}) = 0.$$

## 3. Consequences

A) If  $\psi_{ij} = 0$ , then  $\overline{R}_{ij} = R_{ij}$ , and  $\psi_{i,j} = \psi_i \psi_j$ , so we obtain:

$$\psi_i(x)R_{jk} + \psi_j(x)R_{ki} + \psi_k(x)R_{ij} = 0.$$
(3.1)

B) If the  $V^n$  is a Riemannian space with cyclic Ricci tensor and at the same time is a Einstein space, then we get

$$\rho \psi_i(x) g_{jk} + \rho \psi_j(x) g_{ki} + \rho \psi_k(x) g_{ij} = 0$$

that is

$$n\psi_i(x) + 2\psi_i(x) = 0, (3.2)$$

so

$$(n+2)\psi_i(x) = 0. (3.3)$$

It means

**Theorem 3.1.** A Riemannian-Einstein space  $V^n$  with cyclic Ricci tensor admits into  $\overline{V}^n$  with cyclic Ricci tensor only trivial (affin) geodesic mapping.

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